GOVERNMENT COLLEGE OF ENGINEERING: : SALEM – 636011

Regulations 2018A

| Course Code | Course Title | Category | Contact | | Hou | rs/week | | Ma | ximum N | Iarks |
|-------------|---|----------|----------|-------|-----|---------|-----|-----|---------|-------|
| | | category | periods | L | Т | Р | С | CA | FE | Total |
| | | FI | RST SEME | STER | | | | | | |
| | | | THEORY | Y | | | | | | |
| 18EN101 | Professional English | HS | 2 | 2 | 0 | 0 | 2 | 40 | 60 | 100 |
| 18MA102 | Matrices, Calculus and Differential Equations | BS | 4 | 3 | 1 | 0 | 4 | 40 | 60 | 100 |
| 18CY101 | Chemistry | BS | 4 | 3 | 1 | 0 | 4 | 40 | 60 | 100 |
| 18CS101 | Fundamentals of Problem Solving and C Programming | ES | 3 | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| | | 1 | PRACTIC | AL | | | | | | |
| 18EN102 | Professional English Laboratory | HS | 2 | 0 | 0 | 2 | 1 | 60 | 40 | 100 |
| 18CS102 | Computer Practice Laboratory | ES | 4 | 0 | 0 | 4 | 2 | 60 | 40 | 100 |
| 18ME102 | Workshop/Manufacturing Practices | ES | 5 | 1 | 0 | 4 | 3 | 60 | 40 | 100 |
| 18MC102 | Induction Programme | MC | | | | | 0 | 100 | - | 100 |
| | Total | | | | | | 19 | | | |
| | | SEC | OND SEM | ESTEI | R | | | | | |
| | | | THEORY | Y | | - | | | | - |
| 18MA204 | Fourier Series and Transforms | BS | 4 | 3 | 1 | 0 | 4 | 40 | 60 | 100 |
| 18PH202 | Physics- Waves & Optics and Quantum Mechanics | BS | 4 | 3 | 1 | 0 | 4 | 40 | 60 | 100 |
| 18ME101 | Engineering Graphics and Design | ES | 5 | 1 | 0 | 4 | 3 | 40 | 60 | 100 |
| 18CM201 | Basic Civil and Mechanical Engineering | ES | 4 | 4 | 0 | 0 | 4 | 40 | 60 | 100 |
| | | | PRACTIC | AL | | • | | · . | | |
| 18PH103 | Physics Laboratory | BS | 3 | 0 | 0 | 3 | 1.5 | 60 | 40 | 100 |
| 18CY102 | Chemistry Laboratory | BS | 3 | 0 | 0 | 3 | 1.5 | 60 | 40 | 100 |
| 18EN103 | Professional Communication Laboratory | HS | 2 | 0 | 0 | 2 | 1 | 60 | 40 | 100 |
| 18CE201 | Basic Civil Engineering Laboratory | ES | 2 | 0 | 0 | 2 | 1 | 60 | 40 | 100 |
| | Total | | | | | | 20 | | | |

B.E. Electrical and Electronics Engineering- Full Time

| | | THI | RD SEM | ESTER | | | | | | |
|----------|---|-----|---------|--------|---|---|-----|-----|----|-----|
| | | | THEOR | Y | | | | | | |
| 18MA302 | Statistics and Numerical Methods | BS | 4 | 3 | 1 | 0 | 4 | 40 | 60 | 100 |
| 18EE301 | Electric Circuit Analysis | PC | 4 | 3 | 1 | 0 | 4 | 40 | 60 | 100 |
| 18EE302 | Electromagnetic Fields | PC | 4 | 3 | 1 | 0 | 4 | 40 | 60 | 100 |
| 18EE303 | DC Machines and Transformers | PC | 3 | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 18EE304 | Electron Devices and Circuits | PC | 4 | 3 | 1 | 0 | 4 | 40 | 60 | 100 |
| | | I | PRACTIC | AL | | | | | | |
| 18EE305 | DC Machines and Transformers Laboratory | PC | 3 | 0 | 0 | 3 | 1.5 | 60 | 40 | 100 |
| 18EE306 | Electron Devices and Circuits Laboratory | PC | 3 | 0 | 0 | 3 | 1.5 | 60 | 40 | 100 |
| 18CYMC01 | Environmental Science | MC | 1 | 0 | 0 | 1 | 0 | 100 | - | 100 |
| | Total | | | | | | 22 | | | |
| | · | FOU | RTH SEN | IESTEI | R | | | | | |
| | | | THEOR | Y | | | | | | |
| 18EE401 | Signals and Systems | PC | 3 | 2 | 1 | 0 | 3 | 40 | 60 | 100 |
| 18EE402 | Synchronous and Induction Machines | PC | 3 | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 18EE403 | Measurements and Instrumentation | PC | 3 | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 18EE404 | Analog and Digital Integrated Circuits | PC | 3 | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 18ME408 | Engineering Mechanics | ES | 3 | 2 | 1 | 0 | 3 | 40 | 60 | 100 |
| | | I | PRACTIC | AL | | | | 1 | | |
| 18EE405 | Synchronous and Induction Machines Laboratory | PC | 3 | 0 | 0 | 3 | 1.5 | 60 | 40 | 100 |
| 18EE406 | Measurements and Instrumentation Laboratory | PC | 3 | 0 | 0 | 3 | 1.5 | 60 | 40 | 100 |
| 18EE407 | Analog and Digital Integrated Circuits Laboratory | PC | 3 | 0 | 0 | 3 | 1.5 | 60 | 40 | 100 |
| 18MC301 | Indian Constitution | MC | 1 | 1 | 0 | 0 | 0 | 100 | - | 100 |
| | | 1 | | | | | | | | |

| | | FI | FTH SEM | IESTEI | R | | | | | | |
|----------|--|-------|-----------|---------|---------|------------|------|-----|-----|----|-----|
| | | | THEO | RY | | - | | | | | |
| 18EE501 | Power Generation, Transmission and Distribution System | PC | 3 | 3 | 0 | 0 | 3 | 40 | 60 | | 100 |
| 18EE502 | Control Systems | PC | 4 | 3 | 1 | 0 | 4 | 40 | 60 | | 100 |
| 18EE503 | Power Electronics | PC | 3 | 3 | 0 | 0 | 3 | 40 | 60 | | 100 |
| 18EE504 | Microprocessor and Microcontroller | | 3 | 3 | 0 | 0 | 3 | 40 | 60 | | 100 |
| 18EEPXX | Program Elective – 1 Pl | | 3 | 3 | 0 | 0 | 3 | 40 | 60 | | 100 |
| 18EE0EXX | Open Elective-1 | OE | 3 | 3 | 0 | 0 | 3 | 40 | 60 | | 100 |
| 18MCIN01 | Ideation Sprits | EEC | 3 | 2 | 2 | 0 | 1 | 100 | | | 100 |
| | | | PRACTI | CAL | | | | | | | |
| 18EE505 | Control SystemLaboratory | PC | 3 | 0 | 0 | 3 | 1.5 | 60 | 40 | | 100 |
| 18EE506 | Power Electronics Laboratory | PC | 3 | 0 | 0 | 3 | 1.5 | 60 | 40 | | 100 |
| 18EE507 | Microprocessor and Microcontroller Laboratory | PC | 3 | 0 | 0 | 3 | 1.5 | 60 | 40 | | 100 |
| | Total | | | | | | 24.5 | | | | |
| | S | EMEST | TER VI (R | legular | Stream) |) | | • | | | |
| | | | THEO | RY | | | | | | | |
| 18EEPXX | Program Elective- 1 | PE | 3 | 3 | 0 | | 0 | 3 | 40 | 60 | 100 |
| 18EEPXX | Program Elective- 2 | PE | 3 | 3 | 0 | | 0 | 3 | 40 | 60 | 100 |
| 18EEPXX | Program Elective- 3 | PE | 3 | 3 | 0 | | 0 | 3 | 40 | 60 | 100 |
| 18EEPXX | Program Elective- 4 | PE | 3 | 3 | 0 | | 0 | 3 | 40 | 60 | 100 |
| 18EEPXX | Program Elective- 5 (Dropped) | PE | 3 | 3 | 0 | | 0 | 3 | 40 | 60 | 100 |
| 18EE0EXX | Open Elective - 2 | OE | 3 | 3 | 0 | | 0 | 3 | 40 | 60 | 100 |
| 18EE0EXX | Open Elective - 3 | OE | 3 | 3 | 0 | | 0 | 3 | 40 | 60 | 100 |
| | Naan Muthalvan | | | | | | | 2 | | | |
| | Total | | | | | | | 21 | | | 1 |
| | SEMI | ESTER | VI (pro | otosen | ı strea | m) | I | | T | | |
| | THEORY | | | | | | | | | | |
| 18MEPS11 | Applied Design Thinking (Open Elective-I) | PE | 3 | 3 | 0 | | 0 | 3 | 100 | - | 100 |
| 18MEPS12 | Startup Fundamentals (Open Elective-II) | PE | 3 | 3 | 0 | | 0 | 3 | 100 | - | 100 |
| 18MEPS13 | Computational Hardware (Professional Elective-I) | PE | 3 | 3 | 0 | | 0 | 3 | 100 | - | 100 |
| 18MEPS14 | Coding for Innovators(Profession Elective-II) | OE | 3 | 3 | 0 | | 0 | 3 | 100 | - | 100 |
| 18MEPS15 | Industrial Design & Rapid Prototyping Techniques (Professional Elective-III) | OE | 3 | 3 | 0 | | 0 | 3 | 100 | - | 100 |
| 18MEPS16 | Industrial Automation/ Data Life Cycle Management (Professional Elective-IV) | | 3 | 3 | 0 | | 0 | 3 | 100 | - | 100 |
| 18MEPS17 | Robotics /ML& MLOps (Professional Elective-V) | EEC | 3 | 3 | 0 | | 0 | 3 | 100 | - | 100 |
| | Total | | | | | T | T | 21 | | | |

| | | SEVE | NTH SEN | | R | | | | | |
|---------|---|---------|------------|---------|-----|----|-----|----|-----|-----|
| | | | THEOR | Y | | | | | | |
| 18EE701 | Power System Protection and SwitchGear | PC | 3 | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 18EE702 | Industrial Management and Economics | HS | 3 | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 18EE601 | Power System Analysis and Stability (6 th Sem Course) | PC | 3 | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 18EE602 | Electrical Drives and Control (6 th Sem Course) | PC | 3 | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 18EE606 | Professional Ethics and Human Values (6 th Sem Course) | HS | 3 | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| | |] | PRACTIC | AL | | | | | | |
| 18EE703 | Power Systems Laboratory | PC | 3 | 0 | 0 | 3 | 1.5 | 60 | 40 | 100 |
| 18EE704 | Electrical Drives and Control Laboratory | PC | 3 | 0 | 0 | 3 | 1.5 | 60 | 40 | 100 |
| 18EN504 | Communication Skills Laboratory | HS | 3 | 3 | 0 | 0 | 1 | 60 | 40 | 100 |
| 18EE604 | Mini Project | EEC | 4 | 0 | 0 | 4 | 2 | 60 | 40 | 100 |
| | Total | | | | | | 21 | | | |
| | | EIG | HTH SEM | ESTEF | ł | | | | | |
| | | | THEOR | Y | | | | | | |
| 18EEPXX | Program Elective –6 | PE | 3 | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| | |] | PRACTIC | AL | | | | | | |
| 18EE801 | Project Work | EEC | 16 | 0 | 0 | 16 | 8 | 80 | 120 | 200 |
| | Total | | | | | | 11 | | | |
| | | Total N | umber of (| Credits | 158 | I | | 1 | | |

B.E. Electrical and Electronics Engineering - Full Time Programme Electives

| S.N | Course | Course Title | Cat. | Hou | irs/wee | k & C | redits | Maxim | um Mark | S | Preferred |
|-----|---------|---|------|-----|---------|-------|--------|-------|---------|-------|-----------|
| 0 | Code | | | L | Т | Р | C | CA | FE | Total | Semester |
| 1 | 18EEP01 | Electrical Machine Design | PE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | V |
| 2 | 18EEP02 | Biology for Electrical Engineers | PE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | V |
| 3 | 18EEP03 | Digital Signal Processing | PE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | V |
| 4 | 18EEP04 | Discrete Control Systems | PE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | V |
| 5 | 18EEP05 | High Voltage Engineering | PE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | VI |
| б | 18EEP06 | HVDC Transmission Systems | PE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | VI |
| 7 | 18EEP07 | EHVAC Transmission Systems | PE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | VI |
| 8 | 18EEP08 | FACTS Controllers | PE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | VI |
| 9 | 18EEP09 | Power Quality | PE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | VI |
| 10 | 18EEP10 | Utilization of Electrical Energy | PE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | VI |
| 11 | 18EEP11 | Electrical Energy Conservation and Auditing | PE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | VI |
| 12 | 18EEP12 | Power System Operation and Control | PE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | VI |
| 13 | 18EEP13 | Distributed Generation and Micro Grid | PE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | VII |
| 14 | 18EEP14 | Wind and Solar Energy Systems | PE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | VII |
| 15 | 18EEP15 | Electrical and Hybrid Vehicles | PE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | VII |
| 16 | 18EEP16 | Soft Computing and Machine Learning | PE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | VII |
| 17 | 18EEP17 | Advanced Electric Drives | PE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | VIII |
| 18 | 18EEP18 | Computational Electromagnetics | PE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | VIII |

| 19 | 18EEP19 | Special Electrical Machines | PE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | VIII |
|----|---------|---|----|---|---|---|---|----|----|-----|------|
| 20 | 18EEP20 | Electrical Wiring Estimation and Costing | PE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | VIII |
| 21 | 18EEP21 | Total Quality Management | PE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | VIII |
| 22 | 18EEP22 | Restructured Power System | PE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | VIII |
| 23 | 18EEP23 | Industrial Electrical Systems | PE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | VIII |
| 24 | 18EEP24 | Smart Grid | PE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | VIII |

Open Electives

| S.N 0 | Course Code | Course Title | Category | Contact Hrs | | ırs/we Credi | eek & ts | | Maximum Marks | | | |
|----------|----------------|---------------------------------------|----------|----------------|---|-----------------|-------------|---|---------------|----|-------|--|
| | | | Cat | Con Hrs | L | Т | Р | С | CA | FE | Total | |
| 1 | 18EEOE1 | Renewable Energy Sources | PE | 3 | 3 | 0 | 0 | 3 | 40 | 60 | 100 | |
| 2 | 18EEOE2 | Smart Grid Technology | PE | 3 | 3 | 0 | 0 | 3 | 40 | 60 | 100 | |
| 3 | 18EEOE3 | Energy Conservation and Management | PE | 3 | 3 | 0 | 0 | 3 | 40 | 60 | 100 | |
| 4 | 18EEOE4 | Electric Vehicles | PE | 3 | 3 | 0 | 0 | 3 | 40 | 60 | 100 | |

| 18EN10 | PROFESSIONAL ENGLISH | L | Т | Ρ | С | | |
|--------------------|--|---------------|----------------|-----------------|----------------|--|--|
| - | | 2 | 0 | 0 | 2 | | |
| Course | Objectives: | | | | | | |
| | - | 00.0 | foor | tone | | | |
| <u>1.</u> 2. | Master basic reading skills such as phonics, word recognition and meaningful division Read fast, decode accurately and remove oral reading errors that affect text meaning | | i sei | literit | ,es. | | |
| 3. | Acquire and develop writing skills for academic, social and professional purposes. | ıy. | | | | | |
| <u> </u> | Gain skills in academic and functional writing tasks. | | | | | | |
| -т. | | | | | | | |
| Writing | | | | | | | |
| 1. \ E | Vord Formation with Prefix and Suffix, Synonyms and Antonyms, Tenses, Parts of Errors in English (Subject –Verb Agreement, Noun-Pronoun Agreement, Prep Conditional statements, Redundancies, Clichés etc), Voices. | ositi | ons, | Ar | ticles | | |
| ć | Email – Training Programme and related details, paper submission for seminars and co an appointment, Arranging and Cancelling a meeting with team members, confere accommodation, Reminder mails, Raising queries with team members, Congratulato arranging for a meeting with a foreign client, personal emails. | ence | det | ails, | hote | | |
| 3. L | Letter Writing – Business and need based communication – Formats of official, perso etters, official leave and request applications (Bonafide certificate, course completion, o permission to arrange industrial visits) complaints, replies to queries from business o dignitaries, accepting and declining invitations, placing orders, cover letter for a jo | conc custo | luct o omer | certif s, in | icate vitin | | |
| 4. | resume. Technical Report Writing – status reports – Work Done in the Project, Feasibility Reports on Off Accommodation, Introduction of New Products, Sales Promotion, Customers Feedback, Starting a N Company, Event Reports- Seminars, Conferences, Meeting, Recommendations and Checklists. | | | | | | |
| | Charts- interpreting pie charts, graphs etc., | | | - | | | |
| | | | | | | | |
| READIN | | | | | | | |
| C | Jnderstanding notices, messages, timetables, adverts, graphs, etc understanding mea of short texts | aning | g and | d pur | pose | | |
| | Gapped sentences – Meanings, collocations and meanings of individual words. | | | | | | |
| 5 | Reading passage with multiple choice questions – reading for gist and reading for spec skimming for general idea of and meaning and contents of the whole text. | | | | | | |
| | Short reading passage; gap-filling – Grammar, especially prepositions, articles, auxiliar /erbs, pronouns, relative pronouns and adverbs. | y ve | erbs, | moc | lal | | |
| | Short reading passages; sentence matching – Scanning – ability to pick out specific info ext. | orma | tion | in a | shor | | |
| METHO | DOLOGY: | | | | | | |
| (| Dbjective Type: | | | | | | |
| | ocabulary of business communication. | | | | | | |
| | Collocations related to technical and business. | | | | | | |
| | Coherence in paragraphs – use of sequence clues. | | | | | | |
| | Conversations and appropriate responses. | | | | | | |
| 5. T | enses with time makers. | | | | | | |
| | /erbal phrases | | | | | | |
| | Description of objects in a sentence or two | | | | | | |
| | Products and likely slogans | | | | | | |
| | one, vocabulary, expressions in formal and informal letters. Email writing- tone, vocabulary, expressions, mail ID., creation, CC, BCC. | | | | | | |
| | Descriptive Writing: | | | | | | |
| | Skimming and scanning to look for specific information. | | | | | | |
| | Spotting Errors. | | | | | | |
| | mail writing in different work place/ profession based contexts with hints. | | | | | | |
| | etter writing in different business based contexts with hints. | | | | | | |
| 5. F | Report writing: feasibility report, progress in project reports, accident reports and event r | еро | rts. | | | | |

- 6. Checklists in business, office and profession based context.
- 7. Recommendations in business, office and profession based context.
- 8. Resume and Cover letter.
- 9. Mind mapping visuals on social and environmental issues essay writing based on the given mind map visual.

| | 0+0)=30 Periods |
|----------|---|
| Course | Outcomes: |
| Upon co | mpletion of this course, the students will be able to |
| CO1 | : Read and summarize the main ideas, key details and inferred meanings from a passage. |
| CO2 | : Internalize the grammar items such as prepositions, articles, tenses, verbs, pronouns, and adverbs adjectives through contexts and apply them to spot errors. |
| CO3 | : Develop the ability to classify, check information and prepare reports. |
| CO4 | : Apply the academic and functional writing skills in new contexts. |
| CO5 | : Interpret pictorial representation of data and statistic. |
| Text Bo | oks: Norman Whitby. Business Benchmark –Pre - Intermediate to Intermediate, Students Book, Cambridge |
| 1. | University Press, 2014. |
| Referen | ce Books: M. Ashraf Rizvi, Effective Technical Communication, McGraw Hill.2017 ,2 nd edition |
| 2 | Farhathullah, T.M. Communication Skills for Technical Students.2002 |
| 3 | Meenakshi Raman and Sangeetha Sharma, Technical Communication: Principles and Practice, Oxford University Press, New Delhi, 2015,3 rd edition. |
| 4 | David F. Beer and David McMurray, Guide to Writing as an Engineer, John Willey. New York, 2019. |
| 5 | Collins Cobuild- Student's Grammar: Self-Study Edition with Answers (Collins Cobuild Grammar) paperback- 6 May 1991. |
| 6 | . Essential English Grammar paperback Raymond Murphy CUP 2015,3rd edition. |
| 7 | Speak Better Write Better English paperback – Nov 2012, Norman Lewis, Goyal Publishers and Distributors. Essential English Grammar Paperback Raymond Murphy CUP 2019. |
| 8 | English Reading Comprehension RPH Editorial Board.2020 |
| 9 | Proficiency in Reading Comprehension Simplifying the 'Passage' for you, 2020 Ajay Singh.6 |
| E-Refere | |
| 1 | https://play.google.com/store/apps/details?id=com.zayaninfotech.english.grammar. |
| 2 | http://www.onestopenglish.com/grammar/ |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | | 1 | | 3 | | 1 | | 1 | 2 | 3 | 1 | 2 |
| CO2 | | 2 | | 2 | | | | 1 | 1 | 3 | 2 | 3 |
| CO3 | | 1 | | 1 | | 1 | | 1 | 2 | 3 | 1 | 2 |
| CO4 | | 1 | | 2 | | 1 | | 1 | | 3 | 1 | 2 |
| CO5 | | 2 | | 3 | | | | 1 | 1 | 3 | 1 | 3 |

| 18MA102 | MATRICES, CALCULUS AND DIFFERENTIAL EQUATIONS | 3 | 1 | Г 0 | C 4 |
|---|--|---|---|--|--|
| Course C | Dbjectives: | | <u> </u> | U | - |
| 1. | To know the use of matrix algebra needed by engineers for practical applications | | | | |
| 2. | To understand effectively the geometrical application of differential calculus and | | calc | iliis | |
| 3. | To familiarize the solutions of ordinary differential equations of higher order. | integrai | calc | uius. | |
| 4. | To obtain the knowledge of solving partial differential equations of higher order. | with con | etan | ł | |
| 4. | coefficients. | | Starr | L | |
| 5. | To acquire the knowledge of vector differentiation and integration and its applica | tions | | | |
| Unit I | MATRICES | | 9 | + | 3 |
| Eigen veo | c, Skew Symmetric and Orthogonal Matrices – Characteristic equation of a Matrix ctors – Properties – Cayley-Hamilton theorem (excluding proof) – Diagonalization of tic form to canonical form by orthogonal transformation. | | | | |
| Unit II | MULTI VARIABLE CALCULUS | | 9 | + | 3 |
| of order of | Minima and Saddle point- – Method of Lagrangian multipliers- Multiple integrals- Dou of integration in double integrals – Change of variables (Cartesian to Polar) – A n of Triple integrals – Application to volumes. | | | | |
| Unit III | ORDINARY DIFFERENTIAL EQUATIONS OF HIGHER ORDER | | 9 | + | 3 |
| Cauchy- I | order linear differential equations with constant and variable coefficients –Cauch _egendre's linear equation - Method of variation of parameters –Simultaneous first tant coefficients | | | | |
| | | | | | |
| Unit III | PARTIAL DIFFERENTIAL EQUATIONS | | 9 | + | 3 |
| | | unctions | - | + olutio | - |
| standard | PARTIAL DIFFERENTIAL EQUATIONS n of partial differential equations by elimination of arbitrary constants and arbitrary for types of first order partial differential equations – Lagrange's linear equation – Linea of second and higher order with constant coefficients. | | – S | | on of |
| Formation standard | n of partial differential equations by elimination of arbitrary constants and arbitrary fu types of first order partial differential equations – Lagrange's linear equation – Linea | | – S | | on of |
| Formatior standard equations Unit V | n of partial differential equations by elimination of arbitrary constants and arbitrary fu types of first order partial differential equations – Lagrange's linear equation – Linea of second and higher order with constant coefficients. | ar partia | – S I diffe | eren [.] | on of tial |
| Formation standard equations Unit V Vector Line integ | n of partial differential equations by elimination of arbitrary constants and arbitrary futures of first order partial differential equations – Lagrange's linear equation – Lineated for second and higher order with constant coefficients. | ar partia Vecto ergence | – S I diffe 9 r ir | eren + | on of tial 3 ration |
| Formation standard equations Unit V Vector Line integ | n of partial differential equations by elimination of arbitrary constants and arbitrary fu types of first order partial differential equations – Lagrange's linear equation – Linea of second and higher order with constant coefficients. VECTOR CALCULUS differentiation- Gradient- Directional derivative - Divergence - Curl , pration- work done – Surface and Volume integrals - Green's theorem , Gauss dive without proof) – Simple applications involving cubes and rectangular parallelopiped | ar partia Vecto ergence | – S I diffe I 9 r ir and | eren + ntegr Stoł | on of tial 3 ration kes |
| Formation standard equations Unit V Vector Line integ theorem (Course C | for partial differential equations by elimination of arbitrary constants and arbitrary for types of first order partial differential equations – Lagrange's linear equation – Linea of second and higher order with constant coefficients. VECTOR CALCULUS differentiation- Gradient- Directional derivative - Divergence - Curl , irration- work done – Surface and Volume integrals - Green's theorem , Gauss diversed without proof) – Simple applications involving cubes and rectangular parallelopiped Tota Dutcomes: | vecto Vecto ergence ls. | – S I diffe I 9 r ir and | eren + ntegr Stoł | on of tial 3 ration- kes |
| Formation standard equations Unit V Vector Line integ theorem (Course C Upon com | n of partial differential equations by elimination of arbitrary constants and arbitrary furtypes of first order partial differential equations – Lagrange's linear equation – Lineated of second and higher order with constant coefficients. VECTOR CALCULUS differentiation- Gradient- Directional derivative - Divergence - Curl , differentiation- Without proof) – Simple applications involving cubes and rectangular parallelopiped Dutcomes: Totage | vecto Vecto ergence ls. | – S I diffe I 9 r ir and | eren + ntegr Stoł | on of tial 3 ration- kes |
| Formation standard equations Unit V Vector Line integ theorem (Course C Upon com CO1 | for partial differential equations by elimination of arbitrary constants and arbitrary for types of first order partial differential equations – Lagrange's linear equation – Linear of second and higher order with constant coefficients. | Vecto Vecto ergence ls. al (45+1 | – S I diffe I 9 r ir and | eren + ntegr Stoł | on of tial 3 ration- kes |
| Formation standard equations Unit V Vector Line integ theorem (Course C Upon com CO1 CO2 | for partial differential equations by elimination of arbitrary constants and arbitrary for types of first order partial differential equations – Lagrange's linear equation – Linea of second and higher order with constant coefficients. VECTOR CALCULUS differentiation- Gradient- Directional derivative - Divergence - Curl , pration- work done – Surface and Volume integrals - Green's theorem , Gauss diversed without proof) – Simple applications involving cubes and rectangular parallelopiped Tota Dutcomes: | Vecto Vecto ergence ls. al (45+1 | – S I diffe I 9 r ir and | eren + ntegr Stoł | on of tial 3 ration kes |
| Formation standard equations Unit V Vector Line integ theorem (Course C Upon com CO1 CO2 | for partial differential equations by elimination of arbitrary constants and arbitrary for types of first order partial differential equations – Lagrange's linear equation – Linear of second and higher order with constant coefficients. | Vecto Vecto ergence ls. al (45+1 | – S I diffe I 9 r ir and | eren + ntegr Stoł | on of tial 3 ration kes |
| Formation standard equations Unit V Vector Line integ theorem (Course C Upon com CO1 CO2 CO3 Text Boo | A of partial differential equations by elimination of arbitrary constants and arbitrary for types of first order partial differential equations – Lagrange's linear equation – Linear of second and higher order with constant coefficients. VECTOR CALCULUS differentiation- Gradient- Directional derivative - Divergence - Curl , iration- work done – Surface and Volume integrals - Green's theorem , Gauss diverses without proof) – Simple applications involving cubes and rectangular parallelopiped Tota Dutcomes: Learn the fundamental knowledge of Matrix theory. Familiar with the concept of the differentiation and integration and its applications : Acquire skills in applications of Vector Calculus. | vecto ergence ls. al (45+1 ons. | - Si I diffi 9 r ir and 5)=6 | eren + htegr Stok | ation cf ation ces |
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| 5 | Sivaramakrishnadas.P, Ruknmangadachari.E. "Engineering Mathematics", Pearson, Chennai & |
|---|---|
| | Delhi, 2 nd edition, 2013 |

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| CO1 | 3 | 2 | 2 | 2 | 1 | 1 | 2 | 1 | 1 | 1 | 1 | 1 |
| CO2 | 3 | 2 | 2 | 2 | 1 | 1 | 2 | 1 | 2 | 1 | 1 | 2 |
| CO3 | 3 | 2 | 2 | 2 | 1 | 1 | 2 | 1 | 1 | 1 | 1 | 2 |

| 18CY101 | CHEMISTRY | L | T | Ρ | С | | | | | | | | |
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| Course Ol | - | | | | | | | | | | | | |
| 1 | Analyze microscopic chemistry in terms of atomic and molecular orbitals. | | | | | | | | | | | | |
| 2 | Rationalize periodic properties of elements and the knowledge of acids and bases. | | | | | | | | | | | | |
| 3 | Analyze the stereo chemical aspects of organic molecules and chemical reactions that are used in the synthesis of organic molecules | | | | | | | | | | | | |
| 4 | Rationalize bulk properties and processes in thermodynamic aspects and its extension in electrochemical processes. | | | | | | | | | | | | |
| 5 | Distinguish the ranges of the electromagnetic spectrum used for exciting different molecular energy levels in various spectroscopic techniques | | | | | | | | | | | | |
| Unit I | MOLECULAR STRUCTURE | | 9 | + | 3 | | | | | | | | |
| | of molecular orbitals of diatomic molecules - energy level diagrams of – H2, He2, N2 | , 02 | 2, CO |) an | | | | | | | | | |
| | r, bond length, bond energy, magnetic behavior and relative stability; | , | , | | | | | | | | | | |
| Aromaticity | /- Huckel rule - concept of aromaticity - aromatic, non-aromatic and anti-arc | mat | ic r | nole | cules- | | | | | | | | |
| | , non-benzenoid and annulenes only; | | | | | | | | | | | | |
| field ligand | d theory – postulates-d-orbital splitting in octahedral and tetrahedral complexes-stro ls-spectrochemical series-high spin and low spin complexes-magnetic properties of zation energy(CFSE) and its calculations for octahedral and tetrahedral complexes | | | | | | | | | | | | |
| | | | - | | | | | | | | | | |
| Unit II | PERIODIC PROPERTIES & ACID-BASE CONCEPTS uclear charge – shielding effect, penetration of orbitals - variations of s, p, d and f | | 9 | + | 3 | | | | | | | | |
| – types- m | bases - Bronsted-Lowry concept - Lewis concept - pH and pKa – problems – HSAE echanism of buffer action- Henderson–Hasselbalch equation- derivation and proble | | | | | | | | | | | | |
| Stereoison chirality, o analysis – Addition | STETEROCHEMISTRY & ORGANIC REACTIONS nerism – geometrical isomerism – cis-trans and E-Z nomenclature – optical isomer ptical activity, enantiomer and diastereomers – absolute configuration - R-S notation Ethane, butane, cyclohexane; reaction – hydrogenation, halogenations - Markovnikov rule – Kharasch ef genation, hydroboration; | า - ต | onfo | orma | tional | | | | | | | | |
| Aliphatic n benzene- | ucleophilic substitution reaction $-SN_1$, SN_2 and SN_i mechanism $-$ electrophilic subs mechanism - nitration, halogenations, sulfonation, alkylation and acylation; neaction $-E_1$, E_2 and E_1CB - mechanism- Saytzeff rule $-$ examples. | titut | on I | eact | ion in | | | | | | | | |
| Unit IV | USE OF FREE ENERGY IN CHEMICAL EQUILIBRIA | | 9 | + | 3 | | | | | | | | |
| Thermodyn thermodyn temperatur Free energ potential a | namic functions- internal energy, enthalpy, entropy and free energy- first an amics - partial molar properties - Gibbs Duhem equation – variation of chemi re and pressure – Third and Zeroth law of thermodynamics – definition only; gy and EMF relation - single electrode potential - electrochemical series and its nd its measurement (Poggendorff method only) - Nernst equation-derivation and p ial and equilibrium constant relation- problems. | cal sigr | pote nifica | entia ance | aw of I with cell | | | | | | | | |
| Unit V | SPECTROSCOPY TECHNIQUES & APPLICATIONS | | 9 | + | 3 | | | | | | | | |
| Beer-lamb transitions IR Spectro Flame pho | ert's law (problem)- UV visible spectroscopy: principle, chromophores, auxochro and instrumentation (no application); scopy: principles-instrumentation and applications of IR in H ₂ O,CO ₂ and NH ₃ ; tometry-principle-instrumentation-estimation of sodium by flame photometer; psorption spectroscopy-principles-instrumentation-estimation of nickel by ato | | ele | ctro | nic | | | | | | | | |

| | Total (45+15)=60 Periods |
|---------|---|
| Course | Dutcomes: |
| Upon co | npletion of this course, the students will be able to |
| CO1 | : Understand in-depth knowledge of atomic and molecular orbitals based chemical aspects. |
| CO2 | : Realize the nature of periodic properties of elements and the knowledge of acids and bases. |
| CO3 | : Grasp the knowledge of 3D structural aspects of organic molecules and chemical reactions that are used in the synthesis of organic molecules. |
| CO4 | : Substantiate the various processes involved in thermodynamic considerations and its |
| 004 | involvement in electrochemical aspects. |
| CO5 | : Aware of spectroscopic techniques in the field of molecular identification of materials. |
| 000 | |
| Text Bo | oks: |
| | P.R. Puri, L.R.Sharma and Madan S. Pathania, "Principle of physical chemistry" 47th Vishal |
| 1. | Publishing Co, Jalandhar-8 |
| 0 | C. N. Banwell and E. M. Mccash, "Fundamentals of Molecular Spectroscopy", Tata McGraw-Hill |
| 2. | Publishing Company Limited, New Delhi, 2009. |
| 3 | Raj. K. Bansal – "A Text Book of Organic Chemistry" Revised 4th Ed.,(2005), New Age |
| | International Publishers Ltd., New Delhi. |
| 4 | P.S. Kalsi – "Stereochemistry conformation and Mechanism", 6th Ed., (2005), New Age |
| 4 | International Publishers Ltd., New Delhi. |
| 5 | J.D. Lee – "A New Concise Inorganic Chemistry", 5th Edn., Oxford University Press, 2011. |
| 6 | Wahid Malik, G.D.Tuli and R.D.Madan, "Selected Topic in Inorganic Chemistry", S.Chand& Co., Ltd (2011). |
| Referen | ce Books: |
| 1 | David.W.Ball, Physical Chemistry, Cengage Learning India Pvt. Ltd., New Delhi, 2009. |
| 2 | G.Aruldhas, Molecular structure and spectroscopy, second edition, PHI learning Pvt. Ltd., New |
| | Delhi, 2008. |
| 3 | Cotton and Wilkinson – "Advanced Inorganic Chemistry", 6th Ed., John Wiley & Sons, New York- |
| | 2004. |
| 4 | James E. Huheey, Ellen A. Keiter and Richard L. Keiter – "Inorganic Chemistry-Principles of |
| | Structure and Reactivity", 4 thEdn., Pearson Education, 11th Impression, 2011. |
| 5 | F.A. Carey and R.J. Sund berg – "Advanced organic chemistry" Vol. I and II– 3rd Ed.,(1984), |
| - | Plenum Publications. |
| 6 | Ernest. Eliel and Samuel H. Wilen – "Stereochemistry of Organic Compounds" – Wiley Student Ed. |
| - | (2006). John Wiley and Sons Pvt. Ltd., Singapore. |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
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| CO1 | 3 | 3 | | | | | | | 2 | | | |
| CO2 | 3 | 3 | | | | | | | 2 | | | |
| CO3 | 3 | 3 | | | | | | | | 2 | | |
| CO4 | 3 | 3 | | | | | | | | | | |
| CO5 | 3 | 3 | | | 2 | | | | | 2 | | |

| 18CS101 | FUNDAMENTALS OF PROBLEM SOLVING AND C PROGRAMMING | L 3 | | P | 3 |
|--|--|--|--|--|--|
| Course O | hiertives | 3 | 0 | 0 | 3 |
| | | | | | |
| 1. | To express problem solving through programming. | | | | |
| 2. | To practice the basic concepts of C programming language. | | _ | | |
| 3. | To provide the basics knowledge about array and strings to solve simple applic | ation | s. | | |
| 4. | To use pointers and functions in the simple applications. | | | | |
| 5. | To review the elementary knowledge of structures and unions. | | • | r | • |
| Unit I | Introduction to Computer and Problem Solving | | 9 | + | 0 |
| code - Fl | ormulation, Problem Solving methods, Need for logical analysis and thinking – Al ow Chart- Need for computer languages, Generation and Classification of (on of a Computer. | | | | |
| Unit II | C Programming Basics and Control Statements | | 9 | + | 0 |
| | er set- Identifies and Keywords- Data Type- Declarations-Expressions-Statemer | nts ar | - | | - |
| Assignmer | Operators – Arithmetic Operators – Unary operators – Relational and Log nt operators – Conditional operators- Managing Input and Output operations- De and Looping statements. | | | | |
| Unit III | Arrays and Strings | | 9 | + | 0 |
| Pre-proces | ssor directives-Storage classes-Arrays – Initialization – Declaration – one dim | ensio | onal | | tw |
| | al arrays. Strings - String operations - String handling functions-Simple | | | | |
| 11 | - Eurotiana and Daintara | | • | | 0 |
| Unit IV | Functions and Pointers | | 9 | + | |
| Function - | Library functions and user-defined functions - Function prototypes and function | defir | - | | 0 Cal |
| | Library functions and user-defined functions – Function prototypes and function Call by reference – Recursion – Pointers - Definition – Initialization – Pointers arith | | nitior | ns – | Cal |
| by value –(and arrays Unit V | Call by reference – Recursion – Pointers - Definition – Initialization – Pointers arith Structures, Unions and File | hmeti | nitior ic – F | ns – Point | Cal ters |
| by value –(and arrays Unit V Introductio | Call by reference – Recursion – Pointers - Definition – Initialization – Pointers arith | hmeti | nitior ic – F 9 ure v | Point | Cal ters 0 n a |
| by value –(and arrays Unit V Introductio structure – operation. | Call by reference – Recursion – Pointers - Definition – Initialization – Pointers arith Structures, Unions and File n – need for structure data type – structure definition – Structure declaration – S - Passing structures to functions – Array of structures – Pointers to structures Total (4 | hmeti Struct Struct | ition ic – F 9 ure v on-b | Point + withi | Cal ters 0 file |
| by value –(and arrays Unit V Introductio structure – operation. Course O | Call by reference – Recursion – Pointers - Definition – Initialization – Pointers arith Structures, Unions and File n – need for structure data type – structure definition – Structure declaration – S - Passing structures to functions – Array of structures – Pointers to structures Total (4 utcomes: | hmeti Struct Struct | ition ic – F 9 ure v on-b | Point + withi | Cal ters 0 file |
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| by value –(and arrays Unit V Introductio structure – operation. Course O Upon com CO1 | Call by reference – Recursion – Pointers - Definition – Initialization – Pointers arith | hmeti Struct Struct | ition ic – F 9 ure v on-b | Point + withi | Cal ters 0 file |
| by value –(and arrays Unit V Introductio structure – operation. Upon com CO1 CO2 | Call by reference – Recursion – Pointers - Definition – Initialization – Pointers arith | hmeti Struct S-Unio | 9 ure on-b | Point Point withi asic Per | Cal ters 0 n a file |
| by value –(and arrays Unit V Introductio structure – operation. Course O Upon com CO1 | Call by reference – Recursion – Pointers - Definition – Initialization – Pointers arith | hmeti Struct S-Unio | 9 ure on-b | Point Point withi asic Per | Cal ters 0 n a file |
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| by value –(and arrays Unit V Introductio structure – operation. Course O Upon com CO1 CO2 CO3 CO4 CO5 Text Book | Call by reference – Recursion – Pointers - Definition – Initialization – Pointers arith Structures, Unions and File n – need for structure data type – structure definition – Structure declaration – S Passing structures to functions – Array of structures – Pointers to structures Total (4 Utcomes: I Formulate and apply logic to solve basic problems. I Write, compile and debug programs in C language. Apply the concepts such as arrays, decision making and looping statements time applications. Solve simple scientific and statistical problems using functions and pointers. Write programs related to structures and unions for simple applications. | Struct S-Unic S-Unic S-Unic S to S | 9 ure v on-b = 45 | real | 0 n a file |
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| PO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 3 | 3 | 3 | 3 | 3 | 2 | 2 | 1 | 1 | 1 | 3 | 3 |
| CO2 | 3 | 3 | 3 | 3 | 3 | 2 | 2 | 1 | 1 | 1 | 3 | 3 |
| CO3 | 3 | 3 | 3 | 3 | 3 | 2 | 2 | 1 | 1 | 1 | 3 | 3 |
| CO4 | 3 | 3 | 3 | 3 | 3 | 2 | 2 | 1 | 1 | 1 | 3 | 3 |
| CO5 | 3 | 3 | 3 | 3 | 3 | 2 | 2 | 1 | 1 | 1 | 3 | 3 |

| 18EN102 | PROFESSIONAL ENGLISH LABORATORY | L | Т | Ρ | С |
|-----------|---|--------|-------|--------|-------|
| | | 0 | 0 | 2 | 1 |
| Course O | ojectives: | | | | |
| 1. | To acquire and develop listening skills for academic, social and professional purpos | es. | | | |
| 2. | To understand short conversations or monologues | | | | |
| 3. | To master basic reading skills such as phonics, word recognition, and fluency | | | | |
| 4. | Acquire and develop pre-intermediate level fluency in oral skills such as discourse | man | age | emei | nt, |
| | grammar and vocabulary, pronunciation and interactive communication for academ | າic, ຄ | SOC | ial ai | าd |
| | professional purposes | | | | |
| 5. | Address an audience and present a topic. | | | | |
| 6. | Express an opinion and justify it | | | | |
| Exercises | | | | | |
| | ogy - Listening | | | | |
| | b Responsibilities | | | | |
| | nversation between two employees on company culture | | | | |
| | nails | | | | |
| | escription of gadgets erview with a leading industrialist | | | | |
| | fice procedures – applying for permission, placing an order for office equipment, | | | | |
| | equiries about orders and deliveries | | | | |
| | nversation between two people on general topics | | | | |
| | lephone Messages | | | | |
| | king and Cancelling appointments | | | | |
| | king for directions | | | | |
| | escheduling a travel plan | | | | |
| | nes : Rude and Polite | | | | |
| | onversation : Statements, Discussions, Debating, Accepting, Negotiating | | | | |
| | onferences ; Announcements about changes in schedules andsessions | | | | |
| | ptivational Speech | | | | |
| | D Talk on Team Work | | | | |
| | escribing charts and data esentation at an office | | | | |
| | ort self-descriptions | | | | |
| | DLOGY: - Speaking | | | | |
| | If-Introduction – Personal information –Name, Home background, study details, area | of ir | nter | est | |
| | bbies, strengths and weaknesses, projects and paper presentations if any, likes and c | | | | od |
| | othes, Special features of home town, Personal role models in life, goals and dreams, | | | | ou, |
| | pirational quote. | | | | |
| | uational Role Play between Examiner and Candidate – Customer and Sales Manage | r, Ho | otel | | |
| Ma | anager and Organiser, Team Leader and Team member, Bank Manager and Candida | ite, I | nte | rviev | ver |
| | d Applicant, Car Driver and Client, Industrialist and Candidate, Receptionist and Appo | | | | eker, |
| | w Employee and Manager, Employee and Employee, P.A. and Manager Schedule for | | | | |
| | king for directions, Seeking help with office equipment, Clarifying an error in the bill, C | | ity (| of | |
| | oducts, Buying a Product, Selling a Product, cancelling and fixing appointments, hote | | | | |
| | commodation, training facilities, dress code, conference facilities, faculty advisors and | 1 stu | der | nt, | |
| Su | Ident and student, college Office personnel and student. | 20) | - 20 | | riodo |
| Course O | Total (0- | -30) | - 31 | | 1005 |
| | bletion of this course, the students will be able to: | | | | |
| CO1 | : Infer, interpret and correlate routine, classroom-related conversation. | | | | |
| CO2 | : Use a range of common vocabulary and context based idioms. | | | | |
| CO3 | : Comprehend native speakers when they speak quickly to one another, although th | e sti | ıde | nt m | iaht |
| 555 | still have trouble. | 5 50 | 100 | | .a |
| CO4 | : Identify the most important words in a story/article. | | | | |
| CO5 | : Summarize the main ideas, key details, and inferred meanings from listening pass | anes | s of | up t | 0 |
| | five minutes. | ~90c | , 01 | SP 0 | - |
| CO6 | : Vocalize words without the aid of pictures | | | | |

| CO7 | : | Make effective self-introductions. |
|------|---|---|
| CO8 | : | Study options, compare and contrasts the options. |
| CO9 | : | Exercise a choice, justify it by giving examples and illustrations. |
| CO10 | : | Construct a situation and to participate in conversations |
| | | |

Text Book:

| 1. | Norman Whitby. Business Benchmark – Pre-Intermediate to Intermediate, Students book, Cambridge |
|----|--|
| | University Press, 2014. |

Reference Books:

| Reference | e Books: |
|-----------|---|
| 1 | Spoken English: A Self-Learning Guide. V.Sasikumar and P V Dhamija |
| 2 | English Conversation Practice: Grant Taylor Paperback 1976ly. Krishna Mohan, N P Singh |
| 3 | Discussions that Work. Penny Ur.CUP, 1981. |
| 4 | Speak Better Write Better English Paperback – November 2012 Norman Lewis, GoyalPublishers and Distributors. |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | | 3 | | 3 | | 1 | | 1 | 2 | 3 | 1 | 2 |
| CO2 | | 2 | | 2 | | | | 1 | 1 | 3 | 2 | 3 |
| CO3 | | 1 | | 1 | | 1 | | 1 | 2 | 3 | 1 | 2 |
| CO4 | | 1 | | 2 | | 1 | | 1 | | 3 | 1 | 2 |
| CO5 | | 2 | | 3 | | | | 1 | 1 | 3 | 1 | 3 |
| CO6 | | 1 | | 1 | | 1 | | 2 | | 3 | 1 | 3 |
| CO7 | | 2 | | 1 | | | | | | 3 | 2 | 3 |
| CO8 | | 2 | | 2 | | 1 | | | 1 | 3 | | 2 |
| CO9 | | 1 | | 1 | | 2 | | 1 | 2 | 3 | | 3 |
| CO10 | | 3 | | 1 | | | | | 3 | 3 | 1 | 3 |

| | 0 0 4 2 |
|---------|--|
| Course | e Objectives: |
| 1. | To provide basic knowledge of creating Word documents and also producing mail merge. |
| 2. | To make use of basic functions, formulas and charts in Spread sheet. |
| 3. | To implement problem solving techniques. |
| 4. | To promote the programming ability to develop applications for real world problems. |
| List of | experiments |
| | Word Processing 1. Document creation, Text manipulation with Scientific notations, Table creation, Table formatting |
| A | and Conversion 2. Letter preparation using Mail merge and Draw flow Charts using tools |
| В | Spread Sheet 3. Chart - Line, XY, Bar and Pie. 4. Formula - formula editor, Sorting and Import and Export features. 5. Spread sheet - inclusion of object, Picture and graphics, protecting the document and sheet. |
| | Simple C Programming 6. Program using Control statements. 7. Program using Looping. |
| | 8. Program using Array. |
| • | 9. Program using String. |
| С | 10. Program using Function. |
| | 11. Program using Structures. |
| | 12. Program using Pointers. |
| | 13. Program using Files. * For programming exercises Flow chart and pseudo code are essential |
| | Total (0+60)=60 Periods |
| | e Outcomes: |
| | ompletion of this course, the students will be able to: |
| CO1 | : Demonstrate the basic mechanics of Word documents and working knowledge of mail merge. |
| CO2 | : Demonstrate the use of basic functions and formulas in Spread sheet. |
| CO3 | : Apply good programming methods for program development. |
| CO4 | : Implement C programs for simple applications. |

| RO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 3 | 3 | 3 | 3 | 3 | 2 | 2 | 1 | 1 | 1 | 3 | 3 |
| CO2 | 3 | 3 | 3 | 3 | 3 | 2 | 2 | 1 | 1 | 1 | 3 | 3 |
| CO3 | 3 | 3 | 3 | 3 | 3 | 2 | 2 | 1 | 1 | 1 | 3 | 3 |
| CO4 | 3 | 3 | 3 | 3 | 3 | 2 | 2 | 1 | 1 | 1 | 3 | 3 |

| 1 8ME10 | 2 WORKSHOP MANUFACTURING PRACTICES | L | Т | P | C |
|----------------|---|--------|-------|-------|---|
| | | 1 | 0 | 4 | 3 |
| Course | objectives: | | | | |
| 1. | To provide an exposure of basic engineering practices to the student | | | | |
| 2. | To provide exposure to the students with hands on experience on various basic en | ngine | ering | 3 | |
| | practices in Civil and Mechanical Engineering | | | | |
| Experin | ents | | | | |
| 1. | Introduction to Safety measures and First aid. | | | | |
| 2. | Study of Lathe -Welding methods and equipment's- Casting process and tools- Sh | neet n | neta | l anc | ł |
| | fitting tools- Carpentry tools and joints. | | | | |
| 3. | Fitting: V-fitting, Square fitting, Curve fitting. | | | | |
| 4. | Lathe: Facing, turning, taper turning and knurling. | | | | |
| 5. | Welding: BUTT, LAP and T- joints. | | | | |
| 6. | Foundry: Green sand preparation- mould making practice. | | | | |
| 7. | Sheet metal: Cone, tray, cylinder. | | | | |
| 8. | Carpentry: CROSS, T and DOVETAIL joints. | | | | |
| 9. | Drilling: simple exercises. | | | | |
| | Total (15 | +60)= | :75 F | Perio | d |
| | | | | | |
| | putcomes: | | | | |
| | npletion of this course, the students will be able to: | | | | |
| CO1 | : Prepare fitting of metal and wooden pieces using simple fitting and carpentry tools | manu | Jally | | |
| CO2 | : Prepare simple lap, butt and tee joints using arc welding equipment. | | | | |
| CO3 | : Prepare green sand moulding. | | | | |
| CO4 | : Prepare sheet metal components. | | | | |
| CO5 | : Prepare simple components using lathe and drilling machine. | | | | |
| Referen | ce books: | | | | |
| 1. | Bawa, H.S, "Work shop Practice", Tata McGraw Hill Publishing Company Limited, 2 | 2007. | | | |
| 2. | Jeyachandran, K, Natarajan, K and Balasubramanian, S, "A Primer on Engineering | Prac | tices | 5 | |
| Ζ. | Laboratory", Anuradha Publications, 2007. | | | | |
| 3. | Jeyapoovan, T, SaravanaPandian, M and Pranitha, S, "Engineering Practices Lab VikasPuplishing House Pvt. Ltd, 2006. | Manu | al", | | |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 2 | 1 | 2 | | | | | | | 1 | | 2 |
| CO2 | 1 | | 2 | | | 2 | | | | | | 2 |
| CO3 | 2 | 1 | 2 | | | 2 | | | | | | 1 |
| CO4 | 1 | | 1 | | | 2 | | | | | | 1 |
| CO5 | 1 | 1 | | | | 1 | | | | | | 1 |

| | FOURIER SERIES AND TRANSFORMS | L 3 | T 1 | P 0 | C 4 |
|---|--|---|--|----------------------------|------------|
| Course Ob | iectives: | U | | v | - |
| 1. | To obtain the knowledge with expansion of a function as a Fourier series. | | | | |
| 2. | To impact analytical skills in the areas of boundary value problems and transform | m toch | niau | 00 | |
| 3. | | | | | |
| 3. | To familiarize with the techniques of Laplace transform for solving second order equations. | amere | entia | I | |
| 4. | To understand the concepts of Fourier transform and its applications | | | | |
| 5. | To obtain the solution of difference equation by Z-transform technique. | | | | |
| Unit I | FOURIER SERIES | | 9 | + | 3 |
| | onditions – General Fourier series – Odd and even functions – Half range sine ser cosine series – Parseval's Identity – Harmonic Analysis. | ries – | | | |
| Unit II | BOUNDARY VALUE PROBLEMS | | 9 | + | 3 |
| equation - | on of second order quasi linear partial differential equations – Solutions of o One dimensional heat equation – Steady state solution of twodimensionalheat uded) – Fourier series solutions in Cartesian coordinates | nedim t equa | ension | onal (Ins | wave |
| Unit III | LAPLACE TRANSFORM | | 9 | + | 3 |
| - | ansform- Conditions for existence – Transform of elementary functions – Basic Pr | opertia | - | | - |
| | es and integrals – Initial and Final value theorems- Transform of periodic Function | | | | |
| | solutions of linear ODE of second order with constant coefficients using Lar | | | | |
| | - statement and application of convolution theorem | | Turic | | lation |
| coninques | | | | | |
| Unit IV | FOURIER TRANSFORM | | 9 | + | 3 |
| Statement | of Fourier integral theorem – Fourier transform pair – Sine and Cosine transfo | | D | | line |
| Statement | | orms - | - Pro | oper | ues - |
| | of simple functions – Convolution theorem - Parseval's Identity | orms - | - Pr(| oper | ues - |
| Transforms | of simple functions – Convolution theorem - Parseval's Identity | orms - | 1 | oper | |
| Transforms Unit V | of simple functions – Convolution theorem - Parseval's Identity Z-TRANSFORM AND DIFFERENCE EQUATIONS | | 9 | • | 3 |
| Transforms Unit V Z-transform | of simple functions – Convolution theorem - Parseval's Identity Z-TRANSFORM AND DIFFERENCE EQUATIONS of simple functions and properties – Inverse Z – transform –initial and find | nal va | 9 lue | + theo | 3 arems |
| Transforms Unit V Z-transform Convolutior | of simple functions – Convolution theorem - Parseval's Identity Z-TRANSFORM AND DIFFERENCE EQUATIONS | nal va | 9 lue | + theo | 3 arems |
| Transforms Unit V Z-transform | of simple functions – Convolution theorem - Parseval's Identity Z-TRANSFORM AND DIFFERENCE EQUATIONS of simple functions and properties – Inverse Z – transform –initial and fin theorem -Formation of difference equations – Solution of difference equations | nal va using | 9 lue Z – | + theo trar | 3 orems |
| Transforms Unit V Z-transform Convolutior | of simple functions – Convolution theorem - Parseval's Identity Z-TRANSFORM AND DIFFERENCE EQUATIONS of simple functions and properties – Inverse Z – transform –initial and find | nal va using | 9 lue Z – | + theo trar | 3 orems |
| Transforms Unit V Z-transform Convolutior technique. | of simple functions – Convolution theorem - Parseval's Identity Z-TRANSFORM AND DIFFERENCE EQUATIONS of simple functions and properties – Inverse Z – transform –initial and fin theorem -Formation of difference equations – Solution of difference equations Total | nal va using | 9 lue Z – | + theo trar | 3 orems |
| Transforms Unit V Z-transform Convolutior technique. Course Ou | of simple functions – Convolution theorem - Parseval's Identity Z-TRANSFORM AND DIFFERENCE EQUATIONS of simple functions and properties – Inverse Z – transform –initial and fin theorem -Formation of difference equations – Solution of difference equations Total tcomes: | nal va using | 9 lue Z – | + theo trar | 3 orems |
| Transforms Unit V Z-transform Convolutior technique. Course Ou Upon comp | of simple functions – Convolution theorem - Parseval's Identity Z-TRANSFORM AND DIFFERENCE EQUATIONS of simple functions and properties – Inverse Z – transform –initial and fin theorem -Formation of difference equations – Solution of difference equations Total tcomes: letion of this course, the students will be able to: | nal va using | 9 lue Z – | + theo trar | 3 orems |
| Transforms Unit V Z-transform Convolutior technique. Course Ou Upon comp CO1 | of simple functions – Convolution theorem - Parseval's Identity Z-TRANSFORM AND DIFFERENCE EQUATIONS of simple functions and properties – Inverse Z – transform –initial and fin theorem -Formation of difference equations – Solution of difference equations Total toomes: letion of this course, the students will be able to: Acquire the knowledge about Fourier series. | nal va using | 9 lue Z – | + theo trar | 3 orems |
| Transforms Unit V Z-transform Convolutior technique. Course Ou Upon comp CO1 CO2 | of simple functions – Convolution theorem - Parseval's Identity Z-TRANSFORM AND DIFFERENCE EQUATIONS of simple functions and properties – Inverse Z – transform –initial and fine theorem -Formation of difference equations – Solution of difference equations Total tcomes: letion of this course, the students will be able to: : Acquire the knowledge about Fourier series. : Learn the techniques of solving boundary value problems | nal va using | 9 lue Z – | + theo trar | 3 orems |
| Transforms Unit V Z-transform Convolutior technique. Course Ou Upon comp CO1 | of simple functions – Convolution theorem - Parseval's Identity Z-TRANSFORM AND DIFFERENCE EQUATIONS of simple functions and properties – Inverse Z – transform –initial and fin theorem -Formation of difference equations – Solution of difference equations Total toomes: letion of this course, the students will be able to: Acquire the knowledge about Fourier series. | nal va using | 9 lue Z – | + theo trar | 3 orems |
| Transforms Unit V Z-transform Convolution technique. Course Ou Upon comp CO1 CO2 | is of simple functions – Convolution theorem - Parseval's Identity Z-TRANSFORM AND DIFFERENCE EQUATIONS in of simple functions and properties – Inverse Z – transform –initial and fine theorem -Formation of difference equations – Solution of difference equations Total toomes: letion of this course, the students will be able to: : Acquire the knowledge about Fourier series. : Learn the techniques of solving boundary value problems : Familiar with the transform techniques. | nal va using | 9 lue Z – | + theo trar | 3 orems |
| Transforms Unit V Z-transform Convolutior technique. Course Ou Upon comp CO1 CO2 CO3 Text Books | of simple functions – Convolution theorem - Parseval's Identity Z-TRANSFORM AND DIFFERENCE EQUATIONS of simple functions and properties – Inverse Z – transform –initial and fin theorem -Formation of difference equations – Solution of difference equations Total tomes: letion of this course, the students will be able to: Acquire the knowledge about Fourier series. Learn the techniques of solving boundary value problems Familiar with the transform techniques. s: | nal va using (45+1 | 9 lue Z 5)= 6 | + theo trar | 3 orems |
| Transforms Unit V Z-transform Convolutior technique. Course Ou Upon comp CO1 CO2 CO3 | of simple functions – Convolution theorem - Parseval's Identity Z-TRANSFORM AND DIFFERENCE EQUATIONS of simple functions and properties – Inverse Z – transform –initial and fin theorem -Formation of difference equations – Solution of difference equations Total tomes: letion of this course, the students will be able to: Acquire the knowledge about Fourier series. Learn the techniques of solving boundary value problems Familiar with the transform techniques. S: Veerarajan T, "Engineering Mathematics (For Semester III)", 3rd Edition, Tata | nal va using (45+1 | 9 lue Z 5)= 6 | + theo trar | 3 orems |
| Transforms Unit V Z-transform Convolutior technique. Course Ou Upon comp CO1 CO2 CO3 Text Books 1. | of simple functions – Convolution theorem - Parseval's Identity Z-TRANSFORM AND DIFFERENCE EQUATIONS of simple functions and properties – Inverse Z – transform –initial and fine theorem -Formation of difference equations – Solution of difference equations Total tcomes: letion of this course, the students will be able to: : Acquire the knowledge about Fourier series. : Learn the techniques of solving boundary value problems : Familiar with the transform techniques. s: Veerarajan T, "Engineering Mathematics (For Semester III)", 3rd Edition, Tata Hill Education Pvt.Ltd., New Delhi, 2009. | nal va using (45+1) | 9 lue Z 5)= 6 | theo trar | 3 orems |
| Transforms Unit V Z-transform Convolutior technique. Course Ou Upon comp CO1 CO2 CO3 Text Books | of simple functions – Convolution theorem - Parseval's Identity Z-TRANSFORM AND DIFFERENCE EQUATIONS of simple functions and properties – Inverse Z – transform –initial and fine theorem -Formation of difference equations – Solution of difference equations Total tecomes: letion of this course, the students will be able to: : Acquire the knowledge about Fourier series. : Learn the techniques of solving boundary value problems : Familiar with the transform techniques. s: Veerarajan T, "Engineering Mathematics (For Semester III)", 3rd Edition, Tata Hill Education Pvt.Ltd., New Delhi, 2009. P.Kandasamy, K.Thilagavathy and K.Gunavathy, "Engineering Mathematics, Veename in the technique is the series is the ser | nal va using (45+1) | 9 lue Z 5)= 6 | theo trar | 3 orems |
| Transforms Unit V Z-transform Convolutior technique. Course Ou Upon comp CO1 CO2 CO3 Text Books 1. | of simple functions – Convolution theorem - Parseval's Identity Z-TRANSFORM AND DIFFERENCE EQUATIONS of simple functions and properties – Inverse Z – transform –initial and fine theorem -Formation of difference equations – Solution of difference equations Total tcomes: letion of this course, the students will be able to: : Acquire the knowledge about Fourier series. : Learn the techniques of solving boundary value problems : Familiar with the transform techniques. s: Veerarajan T, "Engineering Mathematics (For Semester III)", 3rd Edition, Tata Hill Education Pvt.Ltd., New Delhi, 2009. | nal va using (45+1) | 9 lue Z 5)= 6 | theo trar | 3 orems |
| Transforms Unit V Z-transform Convolutior technique. Course Ou Upon comp CO1 CO2 CO3 Text Books 1. 2. | of simple functions – Convolution theorem - Parseval's Identity Z-TRANSFORM AND DIFFERENCE EQUATIONS of simple functions and properties – Inverse Z – transform –initial and fine theorem -Formation of difference equations – Solution of difference equations Total tcomes: letion of this course, the students will be able to: : Acquire the knowledge about Fourier series. : Learn the techniques of solving boundary value problems : Familiar with the transform techniques. s: Veerarajan T, "Engineering Mathematics (For Semester III)", 3rd Edition, Tata Hill Education Pvt.Ltd., New Delhi, 2009. P.Kandasamy, K.Thilagavathy and K.Gunavathy, "Engineering Mathematics, Vo Chand & Company Itd., New Delhi, 1996. | nal va using (45+1) | 9 lue Z 5)= 6 | theo trar | 3 orems |
| Transforms Unit V Z-transform Convolutior technique. Course Ou Upon comp CO1 CO2 CO3 Text Books 1. | of simple functions – Convolution theorem - Parseval's Identity Z-TRANSFORM AND DIFFERENCE EQUATIONS of simple functions and properties – Inverse Z – transform –initial and fine theorem -Formation of difference equations – Solution of difference equations Total tcomes: letion of this course, the students will be able to: : Acquire the knowledge about Fourier series. : Learn the techniques of solving boundary value problems : Familiar with the transform techniques. s: Veerarajan T, "Engineering Mathematics (For Semester III)", 3rd Edition, Tata Hill Education Pvt.Ltd., New Delhi, 2009. P.Kandasamy, K.Thilagavathy and K.Gunavathy, "Engineering Mathematics, Vo Chand & Company Itd., New Delhi, 1996. | nal va using (45+1) McGra | 9 lue Z – 5)= 6 | + theo trar 0 Pe | 3 orems |
| Transforms Unit V Z-transform Convolutior technique. Course Ou Upon comp CO1 CO2 CO3 Text Books 1. 2. Reference | of simple functions – Convolution theorem - Parseval's Identity Z-TRANSFORM AND DIFFERENCE EQUATIONS of simple functions and properties – Inverse Z – transform –initial and fin in theorem -Formation of difference equations – Solution of difference equations Total toomes: letion of this course, the students will be able to: : Acquire the knowledge about Fourier series. : Learn the techniques of solving boundary value problems : Familiar with the transform techniques. S: Veerarajan T, "Engineering Mathematics (For Semester III)", 3rd Edition, Tata Hill Education Pvt.Ltd., New Delhi, 2009. P.Kandasamy, K.Thilagavathy and K.Gunavathy, "Engineering Mathematics, Vor Chand & Company Itd., New Delhi, 1996. Books: Grewal, B.S., "Higher Engineering Mathematics", 43rd Edition, Khanna Publishe Wylie C. Ray and Barrett Louis, C., "Advanced Engineering Mathematics", Sixth | nal va using (45+1) McGra olume | 9 lue Z – 5)= 6 aw III, 3 | + theo trar 0 Pe | 3 orems |
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| Transforms Unit V Z-transform Convolutior technique. Course Ou Upon comp CO1 CO2 CO3 Text Books 1. 2. Reference 1. | of simple functions – Convolution theorem - Parseval's Identity Z-TRANSFORM AND DIFFERENCE EQUATIONS of simple functions and properties – Inverse Z – transform –initial and fine theorem -Formation of difference equations – Solution of difference equations Total Total toomes: letion of this course, the students will be able to: : Acquire the knowledge about Fourier series. : Learn the techniques of solving boundary value problems : Familiar with the transform techniques. S: Veerarajan T, "Engineering Mathematics (For Semester III)", 3rd Edition, Tata Hill Education Pvt.Ltd., New Delhi, 2009. P.Kandasamy, K.Thilagavathy and K.Gunavathy, "Engineering Mathematics, Vo Chand & Company Itd., New Delhi, 1996. Books: Grewal, B.S., "Higher Engineering Mathematics", 43rd Edition, Khanna Publisher Wylie C. Ray and Barrett Louis, C., "Advanced Engineering Mathematics", Sixth McGraw-Hill, Inc., New York, 1995. Srimanta pal and Subath.C.Bhumia, "Engineering Mathematics", Oxford universe | McGra | 9 lue Z – 5)= 6 aw III, 3 | + theo trar 0 Pe | 3 orems |
| Transforms Unit V Z-transform Convolutior technique. Course Ou Upon comp CO1 CO2 CO3 Text Books 1. 2. Reference 1. 2. 3. | of simple functions – Convolution theorem - Parseval's Identity Z-TRANSFORM AND DIFFERENCE EQUATIONS of simple functions and properties – Inverse Z – transform –initial and fin theorem -Formation of difference equations – Solution of difference equations Total toomes: letion of this course, the students will be able to: : Acquire the knowledge about Fourier series. : Learn the techniques of solving boundary value problems : Familiar with the transform techniques. S: Veerarajan T, "Engineering Mathematics (For Semester III)" , 3rd Edition, Tata Hill Education Pvt.Ltd. , New Delhi, 2009. P.Kandasamy, K.Thilagavathy and K.Gunavathy, "Engineering Mathematics, Vo Chand & Company Itd., New Delhi, 1996. Books: Grewal, B.S., "Higher Engineering Mathematics", 43rd Edition, Khanna Publishe Wylie C. Ray and Barrett Louis, C., "Advanced Engineering Mathematics", Sixth McGraw-Hill, Inc., New York, 1995. Srimanta pal and Subath.C.Bhumia, "Engineering Mathematics", Oxford univers publications, New Delhi, 2015 | McGra | 9 lue Z – 5)= 6 | + theo trar 0 Pe | 3 orems |
| Transforms Unit V Z-transform Convolutior technique. Course Ou Upon comp CO1 CO2 CO3 Text Books 1. 2. Reference 1. 2. | of simple functions – Convolution theorem - Parseval's Identity Z-TRANSFORM AND DIFFERENCE EQUATIONS of simple functions and properties – Inverse Z – transform –initial and fine theorem -Formation of difference equations – Solution of difference equations Total Total toomes: letion of this course, the students will be able to: : Acquire the knowledge about Fourier series. : Learn the techniques of solving boundary value problems : Familiar with the transform techniques. S: Veerarajan T, "Engineering Mathematics (For Semester III)", 3rd Edition, Tata Hill Education Pvt.Ltd., New Delhi, 2009. P.Kandasamy, K.Thilagavathy and K.Gunavathy, "Engineering Mathematics, Vo Chand & Company Itd., New Delhi, 1996. Books: Grewal, B.S., "Higher Engineering Mathematics", 43rd Edition, Khanna Publisher Wylie C. Ray and Barrett Louis, C., "Advanced Engineering Mathematics", Sixth McGraw-Hill, Inc., New York, 1995. Srimanta pal and Subath.C.Bhumia, "Engineering Mathematics", Oxford universe | nal va using (45+1! McGra olume ers, De ditic | 9 lue Z – 5)= 6 3 a w lhi,20 on, 0 06 | • • • • • • • • • • | 3 orems |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 3 | 3 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 2 | 1 | 2 |
| CO2 | 3 | 3 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 2 | 1 | 1 |
| CO3 | 3 | 3 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 2 | 1 | 2 |

| 18PH202 | PHYSICS – WAVE & OPTICS AND QUANTUM MECHANICS | L | T | Р | C |
|------------------------|--|------------------|--------|------------------|-----------|
| Course | bjectives: | 3 | 1 | 0 | 4 |
| <u>1.</u> | To make the students to understand Simple harmonic motion and Waves | | | | |
| 2. | To understand the Propagation of light | | | | |
| 3. | To get clear idea of wave optics | | | | |
| 4. | To understand the Principle and working of laser with applications | | | | |
| 5. | To know the basic concepts of quantum Mechanics and Matter Waves | | | | |
| J. | | | | | |
| Unit I | SIMPLE HARMONIC OSCILLATION AND WAVES | | 9 | + | 3 |
| | rmonic motion ; Damped Simple harmonic motion ; Forced vibrations – resonance; \ | | | | |
| | acteristics - velocity of a transverse wave along a stretched string -frequency of a s and overtones - progressive waves & stationary waves – wave equation for progress | | | | |
| Unit II | THE PROPAGATION OF LIGHT AND GEOMETRIC OPTICS | | 9 | + | 3 |
| | Principle - laws of reflection and refraction ; Mirage effect ; Total internal reflection | • Ma | - | | |
| imaging b | y a spherical refracting surface - imaging by a coaxial optical system; Optical Instru d microscope - astronomical telescope. | | | | |
| Unit III | WAVE OPTICS | | 0 | | 2 |
| | Principle; Principle of superposition; Interference of Light – Youngs double slit exp | | 9 | | 3 |
| Fraunhofe | Aperimental arrangement to determine the wavelength of sodium light; Michelse er diffraction from a single slit; Diffraction grating –determination of wavelength of lig plarisation - Polarisation by reflection - Brewsters Law | on Inf ht and | d disp | omete persive | יר; פ |
| Unit IV | LASERS | | 9 | | 3 |
| radiation i | s of Laser beams - monochromacity , coherence , directionality and brightness ; Einstie nteraction and A&B coeffiecients - amplification of light by population inversion - p types of laser - Ruby , Nd-YAG , He-Ne,CO ₂ laser - Energy level diagrams ; Applic engineering and medicine. | umpir | ng me | ethods | s; |
| Unit V | QUANTUM MECHANICS | | 9 | + | 3 |
| Introduction independe | on - matter waves - Debroglie's equation - Davisson-Germer experiment-G.P.Thomso ent and dependent Schroedinger equation; Wave packet; Uncertainity Principle; Sch e in a one dimensional box; Physical Significance of wavefunction. Total (4 | roedi | nger | ent; Ti equat | me ion |
| Course O | utcomes: | 5+15 |)= 00 | Fenc | us |
| | upletion of this course, the students will be able to: | | | | |
| CO1 | : Understand Simple harmonic oscillation and propagation of waves. | | | | |
| CO2 | : Apply matrix method to analyse system of reflecting and refracting surfaces. | | | | |
| CO3 | : Know various experimental techniques in wave optics. | | | | |
| CO4 | : Understand the concept of laser and its applications. | | | | |
| CO5 | : Gain knowledge in the basics of quantum mechanics. | | | | |
| | | | | | |
| Text Boo | ks: AjoyGhatak,'Optics', Tata Mc Graw Hill Publishing Co.Ltd, Fourth Edition,2009 | | | | |
| 1. | |)E | | | |
| 2. 3 | Gupta Kumar Sharma, 'Quantum Mechanics', Jai Prakash Nath & co, 25th Edition, 200 Gaur R.K and Gupta S.L, 'Engineering Physics', Dhanpat Rai Publishers, 2009 | 5C | | | |
| | | | | | |
| Referenc | | | | | |
| 1. | PalanisamyP.K, Engineering Physics', Scitech Publications, 2011 | | | | |
| 2. | Rajendran V and Marikani A, Engineering Physics', PHI learning PVT, India, 2009 | | | | |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 3 | 3 | 1 | 3 | 3 | 2 | | | 1 | | 3 | 2 |
| CO2 | 3 | 2 | 1 | 2 | 3 | 1 | 2 | | 2 | | 3 | 1 |
| CO3 | 2 | 3 | 1 | 3 | 2 | 2 | 1 | | 2 | | 2 | 1 |
| CO4 | 3 | 2 | 1 | 3 | 3 | 1 | 1 | | 2 | | 3 | 1 |
| CO5 | 3 | 3 | 1 | 2 | 3 | 1 | 1 | | 2 | | 3 | 1 |

| | ENGINEERING GRAPHICS AND DESIGN | L 1 | Т 0 | - | C 3 |
|--|---|------------------------|--------|------|--------|
| Course ob | jectives: | | U | - | 5 |
| 1. | To impart knowledge on concepts, ideas and design of engineering products and exposure to CAD Modelling. | to prov | vide a | an | |
| 2. | Standards of Engineering Drawing: Size, layout and folding of drawing sheets, lett drafting instruments | ering - | Use | of | |
| | PROJECTION OF POINTS, LINES AND PLANE SURFACES | | 3 | + | 12 |
| | nciples of orthographic projection- Projection of points, located in all quadrants - Pro | jectior | of st | trai | ghí |
| lines locate | ed in first quadrant – Determination of true lengths and true inclinations – Project d circular lamina inclined to both reference planes. | | | | |
| | PROJECTION OF SOLIDS | | 3 | + | 12 |
| Projection | of simple solids like prisms, pyramids, cylinder and cone when the axis is perp | endicu | lar to | | ne |
| | lane and also inclined to one reference plane by change of position method. | | | _ | |
| | SECTION OF SOLIDS AND DEVELOPMENT OF SURFACES | | 3 | + | 12 |
| Sectioning | of above solids in simple vertical position by cutting planes inclined to one reference lar to other – solids inclined position with cutting planes parallel to one reference | | plan | e a | nd |
| true shape | | | | | |
| | ent of lateral surfaces of simple and truncated solids - Prisms, pyramids cylin | | | one | es |
| Developme | ent of lateral surfaces of solids with square and cylindrical cutouts, perpendicular to | the ax | is. | | |
| UNIT IV | ISOMETRIC PROJECTION | | 3 | + | 12 |
| Principles (| of isometric projectionisometric scale - isometric projections of simple solids, trun | cated i | orism | ıs, | |
| • | cylinders and cones. | | | | |
| | | | | | |
| | PERSPECTIVE PROJECTION | | 3 | + | 12 |
| Perspective | e projection of prisms, pyramids and cylinders by visual ray and vanishing point met | hods. | | | |
| | Total (15- | +45)= € | 60 Pe | erio | ds |
| Note:Study | of drafting software - Auto CAD - Coordinate System (Absolute, relative and polar | •) | | | |
| Creation of | |) | | | |
| | simple figures like polygon, Drawing a plan of residential building, Creation of 3-D I | Vodels | | | |
| | simple figures like polygon, Drawing a plan of residential building, Creation of 3-D I bjects and obtaining 2-D multi view drawing from 3-D model. (Internal Assessmen | Vodels | | | |
| | bjects and obtaining 2-D multi view drawing from 3-D model. (Internal Assessmen | Vodels | | | |
| of simple o Course ou Upon comp | bjects and obtaining 2-D multi view drawing from 3-D model. (Internal Assessmen tcomes: Idetion of this course, the students will be able to: | Vodels | | | |
| of simple o Course ou Upon comp CO1 : | bjects and obtaining 2-D multi view drawing from 3-D model. (Internal Assessment tcomes: bletion of this course, the students will be able to: Understand the conventions and the methods of engineering drawing. | Vodels | | | |
| of simple o Course ou Upon comp CO1 : CO2 : | bjects and obtaining 2-D multi view drawing from 3-D model. (Internal Assessment tcomes: bletion of this course, the students will be able to: Understand the conventions and the methods of engineering drawing. Understand the fundamental concepts of theory of projection. | Vodels | | | |
| of simple oCourse ouUpon compCO1CO2CO3 | bjects and obtaining 2-D multi view drawing from 3-D model. (Internal Assessment tcomes: Deletion of this course, the students will be able to: Understand the conventions and the methods of engineering drawing. Understand the fundamental concepts of theory of projection. Understand the development of different surfaces. | Vodels | | | |
| of simple oCourse ouUpon compCO1CO2CO3CO4 | bjects and obtaining 2-D multi view drawing from 3-D model. (Internal Assessment tcomes: Deletion of this course, the students will be able to: Understand the conventions and the methods of engineering drawing. Understand the fundamental concepts of theory of projection. Understand the development of different surfaces. Develop the relationships between 2D and 3D environments. | Vodels | | | |
| of simple oCourse ouUpon compCO1CO2CO3 | bjects and obtaining 2-D multi view drawing from 3-D model. (Internal Assessment tcomes: Deletion of this course, the students will be able to: Understand the conventions and the methods of engineering drawing. Understand the fundamental concepts of theory of projection. Understand the development of different surfaces. | Vodels | | | |
| of simple o Course ou Upon comp CO1 : CO2 : CO3 : CO4 : | bjects and obtaining 2-D multi view drawing from 3-D model. (Internal Assessment teomes: Deletion of this course, the students will be able to: Understand the conventions and the methods of engineering drawing. Understand the fundamental concepts of theory of projection. Understand the development of different surfaces. Develop the relationships between 2D and 3D environments. Demonstrate computer aided drafting. | Vodels | | | |
| of simple o Course ou Upon comp CO1 : CO2 : CO3 : CO4 : CO5 : Text books 1. | bjects and obtaining 2-D multi view drawing from 3-D model. (Internal Assessment toomes: Deletion of this course, the students will be able to: Understand the conventions and the methods of engineering drawing. Understand the fundamental concepts of theory of projection. Understand the development of different surfaces. Develop the relationships between 2D and 3D environments. Demonstrate computer aided drafting. s: Bhatt N.D, "Engineering Drawing", Charotar publishing House, 2003 | dodels t only) | | | |
| of simple o Course ou Upon comp CO1 : CO2 : CO3 : CO3 : CO4 : CO5 : Text books | bjects and obtaining 2-D multi view drawing from 3-D model. (Internal Assessment toomes: Deletion of this course, the students will be able to: Understand the conventions and the methods of engineering drawing. Understand the fundamental concepts of theory of projection. Understand the development of different surfaces. Develop the relationships between 2D and 3D environments. Demonstrate computer aided drafting. S: | dodels t only) | | | |
| of simple o Course ou Upon comp CO1 : CO2 : CO3 : CO4 : CO5 : Text books 1. | bjects and obtaining 2-D multi view drawing from 3-D model. (Internal Assessment toomes: Deletion of this course, the students will be able to: Understand the conventions and the methods of engineering drawing. Understand the fundamental concepts of theory of projection. Understand the development of different surfaces. Develop the relationships between 2D and 3D environments. Demonstrate computer aided drafting. s: Bhatt N.D, "Engineering Drawing", Charotar publishing House, 2003 | dodels t only) | | | |
| of simple o Course ou Upon comp CO1 : CO2 : CO3 : CO4 : CO5 : Text books 1. | bjects and obtaining 2-D multi view drawing from 3-D model. (Internal Assessment tcomes: Deletion of this course, the students will be able to: Understand the conventions and the methods of engineering drawing. Understand the fundamental concepts of theory of projection. Understand the development of different surfaces. Develop the relationships between 2D and 3D environments. Demonstrate computer aided drafting. S: Bhatt N.D, "Engineering Drawing", Charotar publishing House, 2003 Natarajan, K.V, "A Text book of Engineering Graphics", Dhanalakshmi Publishers, | dodels t only) | | | |
| of simple o Course ou Upon comp CO1 : CO2 : CO3 : CO4 : CO5 : Text books 1. 2. . | bjects and obtaining 2-D multi view drawing from 3-D model. (Internal Assessment tcomes: Deletion of this course, the students will be able to: Understand the conventions and the methods of engineering drawing. Understand the fundamental concepts of theory of projection. Understand the development of different surfaces. Develop the relationships between 2D and 3D environments. Demonstrate computer aided drafting. S: Bhatt N.D, "Engineering Drawing", Charotar publishing House, 2003 Natarajan, K.V, "A Text book of Engineering Graphics", Dhanalakshmi Publishers, | 2006. | | | |
| of simple o Course ou Upon comp CO1 : CO2 : CO3 : CO4 : CO5 : Text books 1. 2. Reference 1. | bjects and obtaining 2-D multi view drawing from 3-D model. (Internal Assessmen tcomes: bletion of this course, the students will be able to: Understand the conventions and the methods of engineering drawing. Understand the fundamental concepts of theory of projection. Understand the development of different surfaces. Develop the relationships between 2D and 3D environments. Demonstrate computer aided drafting. S: Bhatt N.D, "Engineering Drawing", Charotar publishing House, 2003 Natarajan, K.V, "A Text book of Engineering Graphics", Dhanalakshmi Publishers, books: Gopalakrishnana K.R, "Engineering Drawing", Vol. I and II, Subhas Publications, 1 Dhananjay A. Jolhe, "Engineering Drawing with an Introduction to AutoCAD", Tata | 2006. 9999. | | | |
| of simple o Course ou Upon comp CO1 : CO2 : CO3 : CO4 : CO5 : Text books 1. 2. . Reference 1. 2. . | bjects and obtaining 2-D multi view drawing from 3-D model. (Internal Assessmen tcomes: Deletion of this course, the students will be able to: Understand the conventions and the methods of engineering drawing. Understand the fundamental concepts of theory of projection. Understand the development of different surfaces. Develop the relationships between 2D and 3D environments. Demonstrate computer aided drafting. S: Bhatt N.D, "Engineering Drawing", Charotar publishing House, 2003 Natarajan, K.V, "A Text book of Engineering Graphics", Dhanalakshmi Publishers, books: Gopalakrishnana K.R, "Engineering Drawing", Vol. I and II, Subhas Publications, 1 Dhananjay A. Jolhe, "Engineering Drawing with an Introduction to AutoCAD", Tata Publishing Company Limited, 2008. | 2006. 9999. | aw H | | |
| of simple o Course ou Upon comp CO1 : CO2 : CO3 : CO4 : CO5 : Text books 1. 2. Reference 1. | bjects and obtaining 2-D multi view drawing from 3-D model. (Internal Assessmen tcomes: bletion of this course, the students will be able to: Understand the conventions and the methods of engineering drawing. Understand the fundamental concepts of theory of projection. Understand the development of different surfaces. Develop the relationships between 2D and 3D environments. Demonstrate computer aided drafting. S: Bhatt N.D, "Engineering Drawing", Charotar publishing House, 2003 Natarajan, K.V, "A Text book of Engineering Graphics", Dhanalakshmi Publishers, books: Gopalakrishnana K.R, "Engineering Drawing", Vol. I and II, Subhas Publications, 1 Dhananjay A. Jolhe, "Engineering Drawing with an Introduction to AutoCAD", Tata | 2006. 9999. McGr | aw H | | |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 2 | 1 | | | 2 | | | | | 1 | | |
| CO2 | 2 | 1 | | | 2 | | | | | | | |
| CO3 | 3 | 2 | | 2 | 2 | | | | | | | 1 |
| CO4 | 2 | 2 | | 1 | 1 | | | | | 2 | | 1 |
| CO5 | 2 | 2 | | 1 | 1 | | | | | 1 | | 2 |

| 18CM 201 | BASIC CIVIL AND MECHANICAL ENGINEERING | L | Т | Ρ | С |
|-----------------------------|---|-----------------|--------------|-----------------|-----------------|
| | | 4 | 0 | 0 | 4 |
| Course Ob | ectives: | | _ | | |
| 1. | The objective of the course is to impart knowledge on different fields of civil engir various materials used for construction | neerii | ng ai | nd | |
| | | | | | |
| Unit I | CIVIL ENGINEERING MATERIALS AND SURVEYING | | 12 | + | 0 |
| Hooke's lav Civil Engine | : Mechanical properties of materials – Stress – Strain – Types of stresses and str / – stress strain curve of ductile material. ering Materials : Bricks – Stones – Sand - Cement – Concrete – Steel Surveying : C tion – Measurement of Distances | | | | |
| Unit II | BUILDING COMPONENTS AND STRUCTURES | | 12 | + | 0 |
| Foundations Columns – | s : Functions of foundation – Types Superstructure : Brick Masonry – Stone M Lintels – Roofing – Flooring – Plastering.Dams : Types of Dams – cross section uction to Green Building Concept | lasor | iry – | | ams - |
| UNIT III | BOILERS, TURBINES AND PUMPS | | 2 | + | 0 |
| Description boiler only) | ssification of boilers- Working Principle of various types of boilers – Horizontal bo of: Lancashire boiler, Locomotive boiler, Babcock andWilcox boiler, Cochran bo - Boiler Mountings and Accessories. Turbines- Classification- Working Princip bines, Pumps-working principle of reciprocating (single and double acting) and ce | oiler, ole o | simp f Im | ole vo pulse | ertica e anc |
| UNIT IV | INTERNAL COMBUSTION ENGINES | 1 | 2 | + | 0 |
| | , terminologies, classification and components – working principles of petrol and of four stroke and two stroke cycle engines – applications of IC engines. | d die | sel e | engir | ies – |
| UNIT V | REFRIGERATION AND AIR CONDITIONING SYSTEM | 1 | 2 | + | 0 |
| | f refrigeration and air conditioning – terminology; refrigerants – definition, clas vapour compression system and vapour absorption system – window and sp | | | | |
| • • | Total | (60+ | 0)=6 | 0 Pe | eriods |
| Course Ou | | | | | |
| | etion of this course, the students will be able to | | | | |
| CO1 CO2 | Students will acquire the basic knowledge in different fields of civil engineering Materials used in construction. | • | | | |
| CO2 CO3 | : Understand the different parts of the buildings | | | | |
| CO4 | : Gain the knowledge about the working of IC engine, its components and its ap | nlicat | ion | | |
| CO5 | Gain the knowledge about the working of to engine, its components and its ap Gain the knowledge about various types of boilers, turbines and pumps a demonstrate the working of Refrigeration and Air conditioning. | | | able | to |
| Text Books | : | | | | |
| 1. | Shanmugam G and Palanichamy M S, "Basic Civil and Mechanical Engineering" Co., New Delhi, (1996). | ', TM | ΗPι | ıblisł | ning |
| 2. | Ramamrutham. S, "Basic Civil Engineering", Dhanpat Rai Publishing Co. (P) | td (1 | | | |
| 3. | Shanmugam G and Palanisamy M S, "Basic Civil and Mechanical Engineering", T New Delhi, 1996. | МΗр | ubli | shing | g Co, |
| 4. | Ramamrutham.S,"Basic Civil Engineering", DhanpatRai publishing Co.(p) Ltd.199 | 99. | | | |
| | Rooke | | | | |
| Reference | | | | | |
| 1 | SeetharamanS."BasicCivilEngineering", AnuradhaAgencies, (2005). | P . 1 | | | |
| 1 2 | SeetharamanS."BasicCivilEngineering",AnuradhaAgencies,(2005). Venugopal K and Prahu Raja V, "Basic Mechanical Engineering", Anuradha Pub Kumbakonam, (2000). | | | | |
| 1 | SeetharamanS."BasicCivilEngineering",AnuradhaAgencies,(2005). Venugopal K and Prahu Raja V, "Basic Mechanical Engineering", Anuradha Pub | | | urai, | |
| 1 2 | SeetharamanS."BasicCivilEngineering",AnuradhaAgencies,(2005). Venugopal K and Prahu Raja V, "Basic Mechanical Engineering", Anuradha Pub Kumbakonam, (2000). Shantha Kumar S R J., "Basic Mechanical Engineering", Hi-tech Publications, M | | | urai, | |
| 1 2 3 | SeetharamanS."BasicCivilEngineering",AnuradhaAgencies,(2005). Venugopal K and Prahu Raja V, "Basic Mechanical Engineering", Anuradha Pub Kumbakonam, (2000). Shantha Kumar S R J., "Basic Mechanical Engineering", Hi-tech Publications, M (2000). | ayilad | duth | - | 2000. |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | | 2 | | 2 | | | | | | | | |
| CO2 | | | 2 | 2 | | | | | | | | |
| CO3 | | 2 | 2 | 2 | | | | | | | | |
| CO4 | | | | | | | | | | | | |
| CO5 | | | | | | | | | | | | |

| 18PH103 | PHYSICS LABORATORY | L | Т | Ρ | С |
|-----------|---|---------|--------|------|-------|
| | | 0 | 0 | 3 | 1.5 |
| Course Ob | jectives: | | | | |
| 1. | To handle different measuring instruments. | | | | |
| 2. | To understand the basic concepts of interference, diffraction, heat conduction | and | to me | easu | ire |
| | the important parameters | | | | |
| Experimen | ts | | | | |
| 1 | Newton's rings – Determination of radius of curvature of a Plano convex lens. | | | | |
| 2 | Carey Foster's bridge – Determination of specific resistance of the material of | the w | /ire. | | |
| 3 | Poiseuille's flow – Determination of Coefficient of viscosity of a liquid. | | | | |
| 4 | Spectrometer - Grating - Normal incidence - Determination of Wavelength of | Merc | cury I | ines | • |
| 5 | Lee's disc – Determination of thermal conductivity of a Bad conductor. | | | | |
| 6 | Ultrasonic interferometer – Determination of velocity of Ultrasonic Waves in Lic | quid | | | |
| 7 | Non-uniform bending – Determination of young's modulus of the material of the | e Bai | | | |
| 8 | Determination of Band gap of a given semi conductor | | | | |
| 0 | Determination of Wavelength of laser using grating and determination of partic | le siz | e us | ing | |
| 9 | Laser | | | | |
| 10 | Determination of Acceptance angle and Numerical Aperture of fiber. | | | | |
| | Total | (0 . 4) | 5)_44 | 5 00 | riode |
| Course Ou | | (UT4) | 5)-40 | JFe | 1005 |
| | letion of this course, the students will be able to: | | | | |
| CO1 | : Handle different measuring instruments and to measure different parameters. | | | | |
| CO2 | : Calculate the important parameters and to arrive at the final result based on the measurements. | ie ex | perin | nent | al |

| RO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 3 | 3 | | 2 | 3 | 1 | 1 | | 3 | 2 | 3 | 3 |
| CO2 | 3 | 3 | | 2 | 3 | 1 | 1 | | 3 | 2 | 3 | 3 |

| 18CY102 | CHEMISTRY LABORATORY | L | Τ | Ρ | С |
|-----------|---|------|------|-----|------|
| | | 0 | 0 | 3 | 1.5 |
| Course C | bjectives: | | | | |
| 1. | To gain practical knowledge by applying theoretical principles and performing the followinexperiments | | | | |
| Experime | nts | | | | |
| 1 | Estimation of hardness of Water by EDTA | | | | |
| 2 | Estimation of Copper in brass by EDTA | | | | |
| 3 | Estimation of Alkalinity in water | | | | |
| 4 | Estimation of Chloride in water sample (Iodimetry) | | | | |
| 5 | Conductometric titration of Strong Acid and Strong Base | | | | |
| 6 | Conductometric titration of Mixture of acids and Strong base | | | | |
| 7 | Determination of strength of Iron by Potentiometric method | | | | |
| 8 | Estimation of Iron by Spectrophotometry | | | | |
| 9 | Determination of molecular weight and degree of Polymerisation by Viscometry | | | | |
| | Total (0 | +45) | =45 | Per | iods |
| Course C | utcomes: | | | | |
| Upon corr | pletion of this course, the students will be able to: | | | | |
| CO1 : | To know the applicability of the practical skill gained in various fields. | | | | |
| CO2 : | To know the composition of brass quantitatively and the molecular weight of polym | ers. | | | |
| CO3 : | To understand the principle and applications of conductometric titrations, spectron potentiometric titrations | nete | r an | d | |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 3 | 3 | 1 | | | | | | | | | |
| CO2 | 3 | 3 | 1 | | | | | | | | | |
| CO3 | 3 | 3 | 1 | | | | | | | | | |

| | PROFESSIONAL COMMUNICATION LABORATORY L T P C 0 0 2 1 |
|--|---|
| | |
| Course O | - |
| 1. | To improve their reading skills. |
| 2 | To address an audience and present a topic |
| 3 | To acquire speaking competency in English. |
| 4 | To strengthen their fluency in speaking. |
| List of exp | periments |
| | Methodology – Reading |
| | 1) Reading a story aloud with exact pronunciation, with intonation, and with expressing sense. |
| 1 | 2) Reading poems for improving verbal skills, memory, and critical thinking. |
| | 3) Reading newspaper articles for strengthening the vocabulary and writing skills. |
| | 4) Reading homophones with exact pronunciation for expressing different meaning |
| | Methodology – Speaking |
| | 1) Power point presentation – on general topics - for organising and structuring presentation. |
| | 2) Oral presentation -on basic technical ideas related to engineering. |
| 2 | 3) Speaking on a given topic – current affairs, expressing opinion on social issues. |
| | 4) Describing a process – booking Ticket online, survey for starting a new office, sending an e- |
| | mail, etc. |
| | 5) Organising official events –compering, presenting welcome address, proposing vote of thanks. |
| | Total (0+30)=30 Periods |
| Course O | |
| Upon com | pletion of this course, the students will be able to: |
| CO1 | |
| 601 | |
| CUT | Read short passages fluently, avoiding mispronunciation, substitution, omission and |
| | : Read short passages fluently, avoiding mispronunciation, substitution, omission and transposition of word-pairs. |
| CO2 | Read short passages fluently, avoiding mispronunciation, substitution, omission and transposition of word-pairs. Vocalize words without the aid of pictures. |
| CO2 CO3 | Read short passages fluently, avoiding mispronunciation, substitution, omission and transposition of word-pairs. Vocalize words without the aid of pictures. Develop a well-paced, expressive style of reading. |
| CO2 | Read short passages fluently, avoiding mispronunciation, substitution, omission and transposition of word-pairs. Vocalize words without the aid of pictures. |
| CO2 CO3 CO4 CO5 | Read short passages fluently, avoiding mispronunciation, substitution, omission and transposition of word-pairs. Vocalize words without the aid of pictures. Develop a well-paced, expressive style of reading. Make effective oral presentations on technical and general contexts. Describe a process with coherence and cohesion. |
| CO2 CO3 CO4 CO5 Text Book | Read short passages fluently, avoiding mispronunciation, substitution, omission and transposition of word-pairs. Vocalize words without the aid of pictures. Develop a well-paced, expressive style of reading. Make effective oral presentations on technical and general contexts. Describe a process with coherence and cohesion. |
| CO2 CO3 CO4 CO5 | Read short passages fluently, avoiding mispronunciation, substitution, omission and transposition of word-pairs. Vocalize words without the aid of pictures. Develop a well-paced, expressive style of reading. Make effective oral presentations on technical and general contexts. Describe a process with coherence and cohesion. |
| CO2 CO3 CO4 CO5 Text Book 1. | Read short passages fluently, avoiding mispronunciation, substitution, omission and transposition of word-pairs. Vocalize words without the aid of pictures. Develop a well-paced, expressive style of reading. Make effective oral presentations on technical and general contexts. Describe a process with coherence and cohesion. |
| CO2 CO3 CO4 CO5 Text Book 1. Reference | Read short passages fluently, avoiding mispronunciation, substitution, omission and transposition of word-pairs. Vocalize words without the aid of pictures. Develop a well-paced, expressive style of reading. Make effective oral presentations on technical and general contexts. Describe a process with coherence and cohesion. |
| CO2 CO3 CO4 CO5 Text Book 1. Reference | Read short passages fluently, avoiding mispronunciation, substitution, omission and transposition of word-pairs. Vocalize words without the aid of pictures. Develop a well-paced, expressive style of reading. Make effective oral presentations on technical and general contexts. Describe a process with coherence and cohesion. (s: Norman Whitby. Business Benchmark – Pre-Intermediate to Intermediate, Students book, Cambridge University Press, 2014. Books Spoken English: A Self-Learning Guide. V.Sasikumar and P V Dhamija |
| CO2 CO3 CO4 CO5 Text Book 1. Reference 1 2 | Read short passages fluently, avoiding mispronunciation, substitution, omission and transposition of word-pairs. Vocalize words without the aid of pictures. Develop a well-paced, expressive style of reading. Make effective oral presentations on technical and general contexts. Describe a process with coherence and cohesion. s: Norman Whitby. Business Benchmark – Pre-Intermediate to Intermediate, Students book, Cambridge University Press, 2014. Books Spoken English: A Self-Learning Guide. V.Sasikumar and P V Dhamija English Conversation Practice: Grant Taylor Paperback 1976ly. Krishna Mohan, N P Singh |
| CO2 CO3 CO4 CO5 Text Book 1. Reference 1 2 3 | Read short passages fluently, avoiding mispronunciation, substitution, omission and transposition of word-pairs. Vocalize words without the aid of pictures. Develop a well-paced, expressive style of reading. Make effective oral presentations on technical and general contexts. Describe a process with coherence and cohesion. Instrument of the state of the |
| CO2 CO3 CO4 CO5 Text Book 1. Reference 1 2 3 4 | Read short passages fluently, avoiding mispronunciation, substitution, omission and transposition of word-pairs. Vocalize words without the aid of pictures. Develop a well-paced, expressive style of reading. Make effective oral presentations on technical and general contexts. Describe a process with coherence and cohesion. is: Norman Whitby. Business Benchmark – Pre-Intermediate to Intermediate, Students book, Cambridge University Press, 2014. Books Spoken English: A Self-Learning Guide. V.Sasikumar and P V Dhamija English Conversation Practice: Grant Taylor Paperback 1976ly. Krishna Mohan, N P Singh Discussions that Work. Penny Ur.CUP, 1981. Speak Better Write Better English Paperback – November 2012 Norman Lewis, GoyalPublishers and Distributors. |
| CO2 CO3 CO4 CO5 Text Book 1. Reference 1 2 3 | Read short passages fluently, avoiding mispronunciation, substitution, omission and transposition of word-pairs. Vocalize words without the aid of pictures. Develop a well-paced, expressive style of reading. Make effective oral presentations on technical and general contexts. Describe a process with coherence and cohesion. is: Norman Whitby. Business Benchmark – Pre-Intermediate to Intermediate, Students book, Cambridge University Press, 2014. Books Spoken English: A Self-Learning Guide. V.Sasikumar and P V Dhamija English Conversation Practice: Grant Taylor Paperback 1976ly. Krishna Mohan, N P Singh Discussions that Work. Penny Ur.CUP, 1981. Speak Better Write Better English Paperback – November 2012 Norman Lewis, GoyalPublishers and Distributors. |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | | 2 | | | | 1 | | 2 | 2 | 3 | 2 | 2 |
| CO2 | 1 | 1 | | 2 | | | | | 1 | 3 | 1 | 3 |
| CO3 | | 3 | | 2 | | 1 | | | 2 | 3 | | 2 |
| CO4 | | 2 | | 1 | | 1 | | 1 | | 3 | 2 | 3 |
| CO5 | | 2 | | 2 | | | | 1 | 1 | 3 | 1 | 3 |

| 18CE201 | BASIC CIVIL ENGINEERING LABORATORY | L | Т | Ρ | С |
|----------|--|-------|-----|--------|---|
| | | 0 | 0 | 2 | 1 |
| Course O | bjectives: | | | | |
| 1. | To understand the fundamental concept on visual inspection and standard param materials used in the field of civil engineering | eters | abo | ut the | Э |
| 2. | To obtain basic knowledge in testing of the materials widely used for construction | | | | |
| EXPERIM | ENTS | | | | |
| 1 | Cement Tests a) Visual inspection b) Consistency c) Initial and final setting time | | | | |
| 2 | Bricks Test a) Visual examination b) Crushing strength test | | | | |
| 3 | Aggregate Test a) Specific gravity of fine aggregate b) Specific gravity of coarse aggregate | | | | |
| 4 | Concrete – Compression strength Test | | | | |
| 5 | Steel – Tension Test | | | | |
| Course O | Total (0 | +30): | =30 | Perio | d |
| Upon com | pletion of this course, the students will be able to: | | | | |
| CO1 : | Testing the basic materials used in the field of civil engineering | | | | |
| CO2 : | n-depth knowledge about their standard specifications and applications | | | | |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | | 2 | | 2 | | | | | | | | |
| CO2 | | 2 | | 2 | | | | | | | | |

| Course | 2 STATISTICS AND NUMERICAL METHODS | L | Т | Ρ | С |
|---|---|---------------------|----------------------------------|-----------------------------|-------------------------------------|
| Course | | 3 | 1 | 0 | 4 |
| | objectives: | | | • | |
| 1 | To understand the statistical averages and fitting of curves. | | | | |
| 2 | To gain the knowledge of significance test for large and small samples | | | | |
| 3 | To obtain the knowledge about numerical interpolation, differentiation and in | tegr | atior | n | |
| 4 | To acquire knowledge of numerical solution to first order ordinary different | ial e | equa | tion | S |
| | using single step and multi step methods. | | | | |
| 5 | To gain the knowledge of numerical solution to second order partial different by using explicit and implicit methods | ntial | equ | atior | S |
| Unit I | BASIC STATISTICS | | 9 | + | 3 |
| | s of Central tendency: Moments, Skewness and Kurtosis, Curve fitting by the M | /loth | - | | |
| | -Fitting of straight lines, second degree parabolas and curves reducible to line | | | | |
| Unit II | TEST OF HYPOTHESIS | | 9 | + | 3 |
| and diffe | significance: Large Sample tests for Single proportion, difference of proportior prence of means- Small Sample test for single mean, difference of means ent, test for ratio of variances - Chi-square test for goodness of fit and in | and | l cor | relat | ion |
| attributes | | dep | ena | ence | 0 |
| Unit III | INTERPOLATION, NUMERICAL DIFFERENTIATION AND INTEGRATION | 1 | 9 | + | 3 |
| Solution | of Algebraic and Transcendental equations by Newton-Raphson method- Solut | | of sv | /sten | |
| | s by Gauss Elimination and Gauss Seidal iterative methods - Interpolation | | | | |
| | and Backward formulae. Interpolation with unequal intervals: Newton's divided | | | | |
| | e's formulae Numerical Differentiation and Integration: Trapezoidal rule and Sim | ipsc | on's ′ | 1/3 r | ule, |
| Simpsor | 's 3/8 rule. | | | | |
| Unit IV | NUMERICAL SOLUTION FOR ORDINARY DIFFERENTIAL EQUATIONS | | • | r | |
| | | 1 D | 9 | | • |
| | differential equations: Taylor series method- Euler and modified Euler's method of fourth order for solving first and second order differential equations- Milne - corrector methods. | יא -ג | | + | 3 |
| | | e's a | | | ta |
| | NUMERICAL SOLUTION FOR PARTIAL DIFFERENTIAL EQUATION | e's a | | | ta |
| predictor Unit V Partial of equation | | e a | and <i>J</i> 9 nd I | Adar + Pois: | ta n's 3 son |
| predictor Unit V Partial of equation | NUMERICAL SOLUTION FOR PARTIAL DIFFERENTIAL EQUATION differential equations: Finite difference solution of two dimensional Laplace s- Implicit and Explicit methods for one dimensional heat equation (Bender Sch | e a midf | and <i>J</i> 9 nd I and | Adar + Poiss I Cra | ta n's 3 son nk- |
| predicto Unit V Partial o equation Nicholso | NUMERICAL SOLUTION FOR PARTIAL DIFFERENTIAL EQUATION differential equations: Finite difference solution of two dimensional Laplace s- Implicit and Explicit methods for one dimensional heat equation (Bender Schu n methods) - Finite difference explicit method for wave equation. Total (45+ | e a midf | and <i>J</i> 9 nd I and | Adar + Poiss I Cra | ta n's 3 son nk- |
| predicto Unit V Partial o equation Nicholso | NUMERICAL SOLUTION FOR PARTIAL DIFFERENTIAL EQUATION differential equations: Finite difference solution of two dimensional Laplace s- Implicit and Explicit methods for one dimensional heat equation (Bender Schu n methods) - Finite difference explicit method for wave equation. | e a midf | and <i>J</i> 9 nd I and | Adar + Poiss I Cra | ta n's 3 son nk- |
| predicto Unit V Partial c equation Nicholsc Course Upon co | NUMERICAL SOLUTION FOR PARTIAL DIFFERENTIAL EQUATION differential equations: Finite difference solution of two dimensional Laplace s- Implicit and Explicit methods for one dimensional heat equation (Bender Schr n methods) - Finite difference explicit method for wave equation. Total (45+ Outcomes: mpletion of this course, the students will be able to | e a midt 15)= | and <i>J</i> 9 nd I and | Adar + Poiss I Cra | ta n's 3 son nk- |
| Predicto Unit V Partial o equation Nicholso Course Upon co CO1 | NUMERICAL SOLUTION FOR PARTIAL DIFFERENTIAL EQUATION differential equations: Finite difference solution of two dimensional Laplace s- Implicit and Explicit methods for one dimensional heat equation (Bender Schunn methods) - Finite difference explicit method for wave equation. Total (45+ Outcomes: mpletion of this course, the students will be able to : Learn about statistical averages and fitting the curves by Least Square Meth | e a midt 15)= | and <i>J</i> 9 nd I and | Adar + Poiss I Cra | ta n's 3 son nk- |
| Predicto Unit V Partial o equation Nicholso Course Upon co CO1 CO2 | NUMERICAL SOLUTION FOR PARTIAL DIFFERENTIAL EQUATION differential equations: Finite difference solution of two dimensional Laplace s- Implicit and Explicit methods for one dimensional heat equation (Bender Schlunn methods) - Finite difference explicit method for wave equation. Total (45+ Outcomes: mpletion of this course, the students will be able to : Learn about statistical averages and fitting the curves by Least Square Meth : Acquire the techniques of interpolation. | e a midt 15)= | and <i>J</i> 9 nd I and | Adar + Poiss I Cra | ta n's 3 son nk- |
| Predicto Unit V Partial o equation Nicholsco Course Upon co CO1 CO2 CO3 | NUMERICAL SOLUTION FOR PARTIAL DIFFERENTIAL EQUATION differential equations: Finite difference solution of two dimensional Laplace s- Implicit and Explicit methods for one dimensional heat equation (Bender Schlern methods) - Finite difference explicit method for wave equation. Total (45+ Outcomes: mpletion of this course, the students will be able to : Learn about statistical averages and fitting the curves by Least Square Meth : Familiar with the numerical differentiation and integration | e a midt 15)= | and <i>J</i> 9 nd I and | Adar + Poiss I Cra | ta n's 3 son nk- |
| Predicto Unit V Partial o equation Nicholso Course Upon co CO1 CO2 | NUMERICAL SOLUTION FOR PARTIAL DIFFERENTIAL EQUATION differential equations: Finite difference solution of two dimensional Laplace s- Implicit and Explicit methods for one dimensional heat equation (Bender Schlunn methods) - Finite difference explicit method for wave equation. Total (45+ Outcomes: mpletion of this course, the students will be able to : Learn about statistical averages and fitting the curves by Least Square Meth : Acquire the techniques of interpolation. | e a midt 15)= | and 7 9 nd 1 t anc | Adar Poiss I Cra | ta n's son nk- |

| Text Book | is: |
|-----------|---|
| 1. | Veerarajan T, "Probability and Random Process (With Queuing theory)", 4 th Edition, Tata McGraw Hill Education Pvt. Ltd., New Delhi, 2016. |
| 2. | Kandasamy.P, Thilagavathy.K, Gunavathi.K, "Numerical Methods" S.Chand& Co., New Delhi, 2005. |
| 3 | Gupta, S.C. and Kapur, V.K., "Fundamentals of Mathematical Statistics", S.Chand and Sons, New Delhi, 11 th Edition 2014 |
| Reference | Books: |
| 1. | Fruend John, E. and Miller Irwin, "Probability and Statistics for Engineers", 8 th Edition, Prentice Hall India (P) Ltd, 2010. |
| 2 | Gerald, C. F. and Wheatley, P.O., "Applied Numerical Analysis" , Sixth Edition , Pearson Education Asia , New Delhi – 2002 |
| 3 | M.K.Venkataraman, "Numerical Methods", National Publishing Company, 2000 |
| 4 | Jain M.K.Iyengar, K & Jain R.K., "Numerical Methods for Scientific and Engineering Computation", New Age International (P) Ltd, Publishers 2003 |
| 5 | Manish Goyal, "Numerical Methods and Statistical techniques Using "C" ", 1 st Edition, Laxmi Publications (P) Ltd, 2009. |
| E-Referen | ce : |
| 1. | www.onlinecourses.nptel.ac.in |
| 2 | www.class-central.com |
| 3 | www.mooc-list.com |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 3 | 3 | 1 | 2 | 2 | 1 | 1 | 2 | 2 | 1 | 2 | 2 |
| CO2 | 3 | 3 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO3 | 3 | 3 | 1 | 2 | 1 | 1 | 1 | 2 | 2 | 1 | 2 | 2 |
| CO4 | 3 | 3 | 2 | 2 | 1 | 1 | 1 | 2 | 2 | 1 | 1 | 1 |
| CO5 | 3 | 3 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

| 18EE30 ⁻ | 1 | ELECTRIC CIRCUIT ANALYSIS | | T 1 | P 0 | (|
|--|--|--|---|--|--|---------------|
| • | <u>.</u> | | 3 | 1 | U | 4 |
| | - | jectives: | | | | |
| | | pasic circuit concepts, circuit modelling and methods of circuit analysis in time domain a solving simple and multi dimensional circuits including coupled circuits | and f | rec | quen | IC ? |
| Unit I | | BASIC CIRCUITS ANALYSIS | ! | 9 | + | 4 |
| node vol average and capa power fa | tage anc aciti ctor | – Kirchoffs laws – DC and AC Circuits – Resistors in series and parallel circuits –Me e method of analysis for DC and AC Circuits – Sinusoidal voltage and current – instant d effective values – form factor and peak factor (derivations for sine wave) – pure resis ive circuits – RL, RC, RLC series circuits – impedance – phase angle – phasor diagram r – power triangle – apparent power, active and reactive power – parallel circuits (two lance, susceptance and admittance) | ane stive n – j | ous , in pov | s, pe duct ver a | al tiv |
| Unit II | | NETWORK REDUCTION AND NETWORK THEOREMS FOR DC AND AC | | 9 | + | |
| Superpo | sitic | CIRCUITS duction: voltage and current division, source transformation- star and delta t on Theorem - Thevenin's and Norton's Theorem — Maximum power transfer theorem substitution theorem-Millman's theorem. | | | | |
| | | | | | | |
| Series a Selectivi | ty - | RESONANCE AND COUPLED CIRCUITS parallel resonance – frequency response - Effects of varying inductance and – - 'Q' factor – Resonance Frequency – Bandwidth – Half power frequencies. Se – Coefficient of coupling – dot rule – analysis of coupled circuits – coupled circuits | capa If a | nd | mut | ua |
| Series a Selectivi inductan parallel - | ty - ce - | parallel resonance - frequency response - Effects of varying inductance and | capa If ai | icita nd | mut | e ua an |
| Series a Selectivi inductan parallel - Unit IV | ty - ce - - Tu | parallel resonance – frequency response - Effects of varying inductance and – 'Q' factor – Resonance Frequency – Bandwidth – Half power frequencies. Se – Coefficient of coupling – dot rule – analysis of coupled circuits – coupled circuits uned circuits – analysis of Single and double tuned circuits. | capa If ai in s | nd seri | mut es a | e an |
| Selectivi inductan parallel - Unit IV | ty - ce - - Tu | parallel resonance – frequency response - Effects of varying inductance and – 'Q' factor – Resonance Frequency – Bandwidth – Half power frequencies. Se – Coefficient of coupling – dot rule – analysis of coupled circuits – coupled circuits uned circuits – analysis of Single and double tuned circuits. | capa If ai in s | nd seri | mut es a | e an |
| Series a Selectivi inductan parallel - Unit IV Transier Unit V Significa balanced delta cor | ty – ce – Tu – Tu nt re nt re | parallel resonance – frequency response - Effects of varying inductance and – 'Q' factor – Resonance Frequency – Bandwidth – Half power frequencies. Se – Coefficient of coupling – dot rule – analysis of coupled circuits – coupled circuits uned circuits – analysis of Single and double tuned circuits. TRANSIENT RESPONSE ANALYSIS response of RL, RC and RLC Circuits using Laplace transform for DC input and AC single | Lapa If and in s usoid | nd seri 9 Jal 9 | mut es a + inpu + pha tar a | it. |
| Series a Selectivi inductan parallel - Unit IV Transier Unit V Significa balanced delta cor | ty – ce – Tu – Tu nt re nt re | parallel resonance – frequency response - Effects of varying inductance and – 'Q' factor – Resonance Frequency – Bandwidth – Half power frequencies. Se – Coefficient of coupling – dot rule – analysis of coupled circuits – coupled circuits uned circuits – analysis of Single and double tuned circuits. TRANSIENT RESPONSE ANALYSIS esponse of RL, RC and RLC Circuits using Laplace transform for DC input and AC sing THREE PHASE CIRCUITS e of 3 phase circuits – Star, Delta connections – Phase sequence – Balanced load nbalanced voltage sources – analysis of three phase three wire and four wire circuits circuits with balanced and unbalanced loads – phasor diagrams of voltages and current | Lapa If an s in s usoid J-Th s wit | acita nd seri dal dal ree h s | mut es a + inpu + pha tar a ver a | it. |
| Series a Selectivi inductan parallel - Unit IV Transier Unit V Significa balanced delta cor power fa | ty - ce - Tu - Tu nt re nce d/ ui nnec | parallel resonance – frequency response - Effects of varying inductance and – 'Q' factor – Resonance Frequency – Bandwidth – Half power frequencies. Se – Coefficient of coupling – dot rule – analysis of coupled circuits – coupled circuits uned circuits – analysis of Single and double tuned circuits. TRANSIENT RESPONSE ANALYSIS response of RL, RC and RLC Circuits using Laplace transform for DC input and AC sing THREE PHASE CIRCUITS e of 3 phase circuits – Star, Delta connections – Phase sequence – Balanced load nbalanced voltage sources – analysis of three phase three wire and four wire circuits cted with balanced and unbalanced loads – phasor diagrams of voltages and current r measurements in three phase circuits Total (45+15) | Lapa If an s in s usoid J-Th s wit | acita nd seri dal dal ree h s | mut es a + inpu + pha tar a ver a | it. |
| Series a Selectivi inductan parallel - Unit IV Transier Unit V Significa balanced delta cor power fa | ty - ce - - Tu nt re nce d/ un ncctor | parallel resonance – frequency response - Effects of varying inductance and – 'Q' factor – Resonance Frequency – Bandwidth – Half power frequencies. Se – Coefficient of coupling – dot rule – analysis of coupled circuits – coupled circuits uned circuits – analysis of Single and double tuned circuits. TRANSIENT RESPONSE ANALYSIS response of RL, RC and RLC Circuits using Laplace transform for DC input and AC sing THREE PHASE CIRCUITS e of 3 phase circuits – Star, Delta connections – Phase sequence – Balanced load nbalanced voltage sources – analysis of three phase three wire and four wire circuits cted with balanced and unbalanced loads – phasor diagrams of voltages and current r measurements in three phase circuits Total (45+15) | Lapa If an s in s usoid J-Th s wit | acita nd seri dal dal ree h s | mut es a + inpu + pha tar a ver a | it. |
| Series a Selectivi inductan parallel - Unit IV Transier Unit V Significa balanced delta cor power fa delta cor power fa | ty - ce - - Tu nt re nce d/ un ncctor | parallel resonance – frequency response - Effects of varying inductance and – 'Q' factor – Resonance Frequency – Bandwidth – Half power frequencies. Se Coefficient of coupling – dot rule – analysis of coupled circuits – coupled circuits uned circuits – analysis of Single and double tuned circuits. TRANSIENT RESPONSE ANALYSIS response of RL, RC and RLC Circuits using Laplace transform for DC input and AC sing THREE PHASE CIRCUITS e of 3 phase circuits – Star, Delta connections – Phase sequence – Balanced loads nbalanced voltage sources – analysis of three phase three wire and four wire circuits cted with balanced and unbalanced loads – phasor diagrams of voltages and current r measurements in three phase circuits tromes: tetion of this course, the students will be able to Understand the basic concept of circuit elements, circuit laws and network reduction | Lapa capa If an Jusoid J-Th s wit ts –µ | 9 1 1 1 1 1 1 1 1 1 1 1 1 1 | mut es a + inpu + pha tar a ver a | it. |
| Series a Selectivi inductan parallel - Unit IV Transier Unit V Significa balanced delta cor power fa Course | ty - ce - - Tu nt re nce d/ un ncctor | parallel resonance – frequency response - Effects of varying inductance and or 'Q' factor – Resonance Frequency – Bandwidth – Half power frequencies. See – Coefficient of coupling – dot rule – analysis of coupled circuits – coupled circuits uned circuits – analysis of Single and double tuned circuits. TRANSIENT RESPONSE ANALYSIS response of RL, RC and RLC Circuits using Laplace transform for DC input and AC sing THREE PHASE CIRCUITS e of 3 phase circuits – Star, Delta connections – Phase sequence – Balanced load nbalanced voltage sources – analysis of three phase three wire and four wire circuits cted with balanced and unbalanced loads – phasor diagrams of voltages and current r measurements in three phase circuits tcomes: tetion of this course, the students will be able to Understand the basic concept of circuit elements, circuit laws and network reduction Solve the electrical network using mesh, nodal analysis and applying network theore | Lapa capa If an Jusoid J-Th s wit ts –µ | 9 1 1 1 1 1 1 1 1 1 1 1 1 1 | mut es a + inpu + pha tar a ver a | it. |
| Series a Selectivi inductan parallel - Unit IV Transier Unit V Significa balanced delta cor power fa Course | ty - ce - - Tu nt re nce d/ un ncctor | parallel resonance – frequency response - Effects of varying inductance and – 'Q' factor – Resonance Frequency – Bandwidth – Half power frequencies. Se Coefficient of coupling – dot rule – analysis of coupled circuits – coupled circuits uned circuits – analysis of Single and double tuned circuits. TRANSIENT RESPONSE ANALYSIS response of RL, RC and RLC Circuits using Laplace transform for DC input and AC sing THREE PHASE CIRCUITS e of 3 phase circuits – Star, Delta connections – Phase sequence – Balanced loads nbalanced voltage sources – analysis of three phase three wire and four wire circuits cted with balanced and unbalanced loads – phasor diagrams of voltages and current r measurements in three phase circuits tromes: tetion of this course, the students will be able to Understand the basic concept of circuit elements, circuit laws and network reduction | Lapa capa If an Jusoid J-Th s wit ts –µ | 9 1 1 1 1 1 1 1 1 1 1 1 1 1 | mut es a + inpu + pha tar a ver a | it. |
| Series a Selectivi inductan parallel - Unit IV Transier Unit V Significa balanced delta cor power fa delta cor power fa Course Upon co CO1 CO2 CO3 CO3 | ty - ce - - Tu nt re nce d/ un ncctor | parallel resonance – frequency response - Effects of varying inductance and – 'Q' factor – Resonance Frequency – Bandwidth – Half power frequencies. Se Coefficient of coupling – dot rule – analysis of coupled circuits – coupled circuits uned circuits – analysis of Single and double tuned circuits. TRANSIENT RESPONSE ANALYSIS esponse of RL, RC and RLC Circuits using Laplace transform for DC input and AC sing THREE PHASE CIRCUITS e of 3 phase circuits – Star, Delta connections – Phase sequence – Balanced load nbalanced voltage sources – analysis of three phase three wire and four wire circuits cted with balanced and unbalanced loads – phasor diagrams of voltages and current r measurements in three phase circuits total (45+15) toomes: letion of this course, the students will be able to Understand the basic concept of circuit elements, circuit laws and network reduction Solve the electrical network using mesh, nodal analysis and applying network theore Understand the resonance in series and parallel circuits. | Lapa capa If an Jusoid J-Th s wit ts –µ | 9 1 1 1 1 1 1 1 1 1 1 1 1 1 | mut es a + inpu + pha tar a ver a | it. |
| Series a Selectivi inductan parallel - Unit IV Transier Unit V Significa balanced delta cor power fa Course Upon co CO1 CO2 CO3 | ty - ce - - Tu nt re nce d/ un ncctor | parallel resonance – frequency response - Effects of varying inductance and one of the parallel resonance Frequency – Bandwidth – Half power frequencies. See – Coefficient of coupling – dot rule – analysis of coupled circuits – coupled circuits uned circuits – analysis of Single and double tuned circuits. TRANSIENT RESPONSE ANALYSIS sponse of RL, RC and RLC Circuits using Laplace transform for DC input and AC single and voltage sources – analysis of three phase three wire and four wire circuits circuits with balanced and unbalanced loads – phasor diagrams of voltages and curren r measurements in three phase circuits Total (45+15) tcomes: etion of this course, the students will be able to Understand the basic concept of circuit elements, circuit laws and network reduction Solve the electrical network using mesh, nodal analysis and applying network theore | Lapa capa If an Jusoid J-Th s wit ts –µ | 9 1 1 1 1 1 1 1 1 1 1 1 1 1 | mut es a + inpu + pha tar a ver a | it. |

| 1. | William H. Hayt Jr, Jack E. Kemmerly and Steven M. Durbin, "Engineering Circuit Analysis", Seventh Edition, TMH publishers, New Delhi, 2013 |
|---------|--|
| 2. | Sudhakar. A., and Shyammohan. S. Palli, 'Circuits & Networks Analysis and Synthesis', Fourth Edition, Tata McGraw Hill Publishing Co. Ltd., New Delhi, 2015. |
| Referer | nce Books: |
| 1. | A. Chakrabarti, 'Circuit Theory Analysis and Synthesis', Seventh Revised Edition, Dhanpat Rai & Co., New Delhi, 2018 |
| 2 | Dr. M. Arumugam & N. Premkumar, " Electric circuit theory", Khanna Publishers, New Delhi, 1991. |
| 3 | Charles K. Alexander, Mathew N.O. Sadiku, "Fundamentals of Electric Circuits", Second Edition, McGraw Hill, 2013. |
| 4 | Mahmood Nahvi& Joseph Edminister, "Electric Circuits", Schaum's Outline Series, McGraw Hill Publications, Seventh Edition,2018 |
| E-Refer | ence : |
| 1. | NPTEL Courses on Basic Electrical Circuits, IIT Madras |
| | |

| PO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 3 | 3 | 1 | 2 | | | 1 | | | | | |
| CO2 | 2 | 3 | 1 | 2 | | | 1 | | | | | |
| CO3 | 3 | 1 | 2 | | | | 1 | | | | | |
| CO4 | 3 | 1 | 2 | | | | 1 | | | | | |
| CO5 | 1 | 3 | 2 | | 3 | | 1 | | | | | |
| CO6 | 1 | 2 | 1 | 1 | 3 | | 1 | | | | | |

| 18EE302 | ELECTROMAGNETIC FIELDS | L | Т | Ρ | С | | | | |
|---|---|---|---|---|---|--|--|--|--|
| | | 3 | 1 | 0 | 4 | | | | |
| Course Ob | Diectives: | • | - | • | - | | | | |
| 1. | To introduce the basic mathematical concepts related to electromagnetic vector field | s | | | | | | | |
| | To impart knowledge on the concepts of Electrostatic fields, electrical potential, ener | | lens | itv a | nd | | | | |
| 2. | their applications. | | | • | | | | | |
| 3. | To impart knowledge on the concepts of Magneto static fields, magnetic flux density, v and its applications. | | | | | | | | |
| 4. | To impart knowledge on the concepts of Different methods of emf generation and Maxwell's equations. | | | | | | | | |
| 5. | To impart knowledge on the concepts of Electromagnetic waves and characterizing | para | met | ers. | | | | | |
| Unit I | ELECTROSTATICS – I | | 9 | + | 3 | | | | |
| Sources an | nd effects of electromagnetic fields – Coordinate Systems – Vector fields –Gradient, Div | /erg | ence | e, Cu | ırl | | | | |
| | and applications - Coulomb's Law – Electric field intensity – Field due to discrete an | | | | | | | | |
| | Gauss's law and applications. | | | 0.00 | - | | | | |
| Unit II | ELECTROSTATICS – II | | 9 | - | 3 | | | | |
| | | | - | T | - | | | | |
| | tential - Electric field and equipotential plots, Uniform and Non-Uniform field, Utili | | | | | | | | |
| | d in free space, conductors, dielectrics - Dielectric polarization- Dielectric strength - | | | | | | | | |
| | electrics – Boundary conditions, Poisson's and Laplace's equations, Capacitance, E | Ener | gy c | lens | ity, | | | | |
| Application | S. | | | | | | | | |
| Unit III | MAGNETOSTATICS | | 9 | + | 3 | | | | |
| Lorentz for | rce, magnetic field intensity (H) – Biot–Savart's Law - Ampere's Circuit Law – H o | due | to s | traid | uht | | | | |
| | be, magnete hera menerg (m) blet eararte Ean fimpere e encart Ean m | | | | | | | | |
| conductors | circular loop infinite sheet of current Magnetic flux density (B) - B in free space | | | | | | | | |
| | s, circular loop, infinite sheet of current, Magnetic flux density (B) – B in free space | ce, | cond | lucto | r, | | | | |
| magnetic n | naterials – Magnetization, Magnetic field in multiple media – Boundary conditions, sca | ce, alar | cond | lucto | r, | | | | |
| magnetic m | | ce, alar | cond | lucto | r, | | | | |
| magnetic n | naterials – Magnetization, Magnetic field in multiple media – Boundary conditions, sca | ce, alar | cond | lucto | r, | | | | |
| magnetic n potential, F Unit IV | naterials – Magnetization, Magnetic field in multiple media – Boundary conditions, sca Poisson's Equation, Magnetic force, Torque, Inductance, Energy density, Applications | ce, alar | cond and 9 | lucto vect | or, or 3 | | | | |
| magnetic n potential, F Unit IV Magnetic (| naterials – Magnetization, Magnetic field in multiple media – Boundary conditions, sca Poisson's Equation, Magnetic force, Torque, Inductance, Energy density, Applications | ce, alar nt - | cond and 9 Max | lucto vect + | or, or 3 | | | | |
| magnetic n potential, F Unit IV Magnetic (equations (| naterials – Magnetization, Magnetic field in multiple media – Boundary conditions, sca Poisson's Equation, Magnetic force, Torque, Inductance, Energy density, Applications ELECTRODYNAMIC FIELDS Circuits - Faraday's law – Transformer and motional EMF – Displacement currer (differential and integral form) – Relation between field theory and circuit theory – App | ce, alar nt - | cond and 9 Max | lucto vect + | or, or <u>3</u> 's | | | | |
| magnetic n potential, F Unit IV Magnetic (equations (Unit V | Anaterials – Magnetization, Magnetic field in multiple media – Boundary conditions, sca Poisson's Equation, Magnetic force, Torque, Inductance, Energy density, Applications ELECTRODYNAMIC FIELDS Circuits - Faraday's law – Transformer and motional EMF – Displacement currer (differential and integral form) – Relation between field theory and circuit theory – App ELECTROMAGNETIC WAVES | ce, alar nt - olica | ond and 9 Max ation | + well s. + | or, or <u>3</u> 's <u>3</u> | | | | |
| magnetic n potential, F Unit IV Magnetic (equations (Unit V Electromag | Anaterials – Magnetization, Magnetic field in multiple media – Boundary conditions, sca Poisson's Equation, Magnetic force, Torque, Inductance, Energy density, Applications ELECTRODYNAMIC FIELDS Circuits - Faraday's law – Transformer and motional EMF – Displacement currer (differential and integral form) – Relation between field theory and circuit theory – App ELECTROMAGNETIC WAVES gnetic wave generation and equations – Wave parameters; velocity, intrinsic impedance | ce, c alar | 9 Max ation | + wect + well s. + agat | ior 3 is 3 ion | | | | |
| magnetic n potential, F Unit IV Magnetic (equations (Unit V Electromage constant – | Anaterials – Magnetization, Magnetic field in multiple media – Boundary conditions, sca Poisson's Equation, Magnetic force, Torque, Inductance, Energy density, Applications ELECTRODYNAMIC FIELDS Circuits - Faraday's law – Transformer and motional EMF – Displacement currer (differential and integral form) – Relation between field theory and circuit theory – App ELECTROMAGNETIC WAVES gnetic wave generation and equations – Wave parameters; velocity, intrinsic impedance Waves in free space, lossy and lossless dielectrics, conductors- skin depth - Poynting | ce, c alar | 9 Max ation | + wect + well s. + agat | ior 3 is 3 ion | | | | |
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| magnetic m potential, F Unit IV Magnetic (equations (Unit V Electromag constant – wave reflect | Anaterials – Magnetization, Magnetic field in multiple media – Boundary conditions, sca Poisson's Equation, Magnetic force, Torque, Inductance, Energy density, Applications ELECTRODYNAMIC FIELDS Circuits - Faraday's law – Transformer and motional EMF – Displacement currer (differential and integral form) – Relation between field theory and circuit theory – App ELECTROMAGNETIC WAVES gnetic wave generation and equations – Wave parameters; velocity, intrinsic impedance Waves in free space, lossy and lossless dielectrics, conductors- skin depth - Poynting ction and refraction. Total (45+15) | ce, i alar | 9 Max Max ation: 9 Dropa | + well s. + agat - Pla | r, or <u>3</u> 's <u>3</u> ion ine | | | | |
| magnetic m potential, F Unit IV Magnetic C equations (Unit V Electromag constant – wave reflect Course Ou | Anaterials – Magnetization, Magnetic field in multiple media – Boundary conditions, sca Poisson's Equation, Magnetic force, Torque, Inductance, Energy density, Applications ELECTRODYNAMIC FIELDS Circuits - Faraday's law – Transformer and motional EMF – Displacement currer (differential and integral form) – Relation between field theory and circuit theory – App ELECTROMAGNETIC WAVES gnetic wave generation and equations – Wave parameters; velocity, intrinsic impedance Waves in free space, lossy and lossless dielectrics, conductors- skin depth - Poynting cition and refraction. Total (45+15) | ce, i alar | 9 Max Max ation: 9 Dropa | + well s. + agat - Pla | r, or <u>3</u> 's <u>3</u> ion ine | | | | |
| magnetic n potential, F Unit IV Magnetic (equations (Unit V Electromag constant – wave reflect Course Ou Upon comp | Anaterials – Magnetization, Magnetic field in multiple media – Boundary conditions, sca Poisson's Equation, Magnetic force, Torque, Inductance, Energy density, Applications ELECTRODYNAMIC FIELDS Circuits - Faraday's law – Transformer and motional EMF – Displacement currer (differential and integral form) – Relation between field theory and circuit theory – App ELECTROMAGNETIC WAVES gnetic wave generation and equations – Wave parameters; velocity, intrinsic impedance Waves in free space, lossy and lossless dielectrics, conductors- skin depth - Poynting ction and refraction. Total (45+15) Deletion of this course, the students will be able to: | ce, (alar | 9 Max Max ation: 9 Dropa | + well s. + agat - Pla | or, or <u>3</u> 's <u>3</u> ion une | | | | |
| magnetic m potential, F Unit IV Magnetic (equations (Unit V Electromag constant – wave reflect Course Ou | Anaterials – Magnetization, Magnetic field in multiple media – Boundary conditions, sca Poisson's Equation, Magnetic force, Torque, Inductance, Energy density, Applications ELECTRODYNAMIC FIELDS Circuits - Faraday's law – Transformer and motional EMF – Displacement currer (differential and integral form) – Relation between field theory and circuit theory – App ELECTROMAGNETIC WAVES gnetic wave generation and equations – Wave parameters; velocity, intrinsic impedance Waves in free space, lossy and lossless dielectrics, conductors- skin depth - Poynting citon and refraction. Total (45+15) Itemes: Deletion of this course, the students will be able to: : Understand the basic mathematical concepts related to electromagnetic vector field | ce, (alar | 9 Max ation 9 Dropa ctor - | + wwell s. + agat - Pla | r, or <u>3</u> 's <u>3</u> ion ine | | | | |
| magnetic n potential, F Unit IV Magnetic (equations (Unit V Electromag constant – wave reflect Course Ou Upon comp | Anaterials – Magnetization, Magnetic field in multiple media – Boundary conditions, scale oisson's Equation, Magnetic force, Torque, Inductance, Energy density, Applications ELECTRODYNAMIC FIELDS Circuits - Faraday's law – Transformer and motional EMF – Displacement currer (differential and integral form) – Relation between field theory and circuit theory – Applications and equations – Wave parameters; velocity, intrinsic impedance Waves in free space, lossy and lossless dielectrics, conductors- skin depth - Poynting ction and refraction. Total (45+15) Itemes: Oletion of this course, the students will be able to: I Understand the basic mathematical concepts related to electromagnetic vector fiele their applications. | ce, f alar | 9 Max attion 9 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 | + wwell s. + Peric Pittorial Peric | r, or <u>3</u> 's <u>3</u> ion ine ds | | | | |
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| magnetic m potential, F Magnetic C equations (Unit V Electromag constant – wave reflect Course OL Upon comp CO1 CO2 CO3 CO3 | Determinaterials – Magnetization, Magnetic field in multiple media – Boundary conditions, scale coisson's Equation, Magnetic force, Torque, Inductance, Energy density, Applications ELECTRODYNAMIC FIELDS Circuits - Faraday's law – Transformer and motional EMF – Displacement currer (differential and integral form) – Relation between field theory and circuit theory – Apple (ELECTROMAGNETIC WAVES) gnetic wave generation and equations – Wave parameters; velocity, intrinsic impedance Waves in free space, lossy and lossless dielectrics, conductors- skin depth - Poynting cition and refraction. Total (45+15) Itcomes: Oletion of this course, the students will be able to: : Understand the basic concepts about electrostatic fields, electrical potential, energy their applications. Apply knowledge in magneto static fields, magnetic flux density, vector papilications. : Understand the different methods of emf generation and Maxwell's equations | ce, f alar | 9 Max attion: 9 9 Drop: ctor - 60 F | + wwell s. + Peric Pittorial Peric | r, or <u>3</u> 's <u>3</u> ion ine ods | | | | |
| magnetic m potential, F Unit IV Magnetic (equations (Unit V Electromag constant – wave reflect Upon comp CO1 CO2 CO3 | Interials – Magnetization, Magnetic field in multiple media – Boundary conditions, sca Poisson's Equation, Magnetic force, Torque, Inductance, Energy density, Applications Image: Electropynamic Fields Circuits - Faraday's law – Transformer and motional EMF – Displacement currer (differential and integral form) – Relation between field theory and circuit theory – App ELECTROMAGNETIC WAVES gnetic wave generation and equations – Wave parameters; velocity, intrinsic impedance Waves in free space, lossy and lossless dielectrics, conductors- skin depth - Poynting ction and refraction. Total (45+15 Itcomes: Deletion of this course, the students will be able to: : Understand the basic concepts about electrostatic fields, electrical potential, energy : Understand the basic concepts about electrostatic fields, electrical potential, energy : Apply knowledge in magneto static fields, magnetic flux density, vector papelications. | ce, f alar nt - plica ce, f vec 5) = Ids. rgy pote | 9 Max ation 9 oropa ctor - 60 F dens ntial | + well s. + agat - Pla Sity a an | r, or <u>3</u> 's <u>3</u> ion ine ods and d it: | | | | |

| Text Bo | oks: |
|----------|--|
| 1. | Mathew N. O. Sadiku, 'Principles of Electromagnetics', 6th Edition, Oxford University Press Inc. Asian edition, 2015. |
| 2. | William H. Hayt and John A. Buck, 'Engineering Electromagnetics', McGraw Hill Special Indian edition, 2014. |
| 3. | Kraus and Fleish, 'Electromagnetics with Applications', McGraw Hill International Editions, Fifth Edition, 2010. |
| Referen | ce Books: |
| 1. | V.V.Sarwate, 'Electromagnetic fields and waves', First Edition, Newage Publishers, 1993. |
| 2. | J.P.Tewari, 'Engineering Electromagnetics - Theory, Problems and Applications', Second Edition, Khanna Publishers.2013 |
| 3. | Joseph. A.Edminister, 'Schaum's Outline of Electromagnetics, Third Edition (Schaum's Outline Series), McGraw Hill, 2013,4 th edition. |
| 4. | S.P.Ghosh, Lipika Datta, 'Electromagnetic Field Theory', First Edition, McGraw Hill Education(India) Private Limited, 2012. |
| 5. | K A Gangadhar, 'Electromagnetic Field Theory', Khanna Publishers; Eighth Reprint : 2015. |
| E-Refere | ence : |
| 1. | www.onlinecourses.nptel.ac.in |
| 2 | www.class-central.com |
| 3 | www.mooc-list.com |

| RO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 3 | 3 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO2 | 1 | 3 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO3 | 1 | 3 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO4 | 1 | 1 | 3 | 3 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO5 | 1 | 1 | 1 | 3 | 3 | 2 | 2 | 1 | 1 | 1 | 1 | 1 |
| CO6 | 1 | 1 | 3 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 |

| | B DC MACHINES AND TRANSFORMERS L T P C |
|---|---|
| | |
| Course | Objectives: |
| 1. | To understand the concepts of electromechanical energy conversion and to gain the knowledge on single and multiply-excited magnetic systems. |
| 2. | To gain the knowledge on construction and principles of operation of DC machines and transformers. |
| 3. | To analyze the performance characteristics of different types of DC machines and transformers. |
| 4. | To appreciate the applications of DC machines and transformers. |
| 5. | To analyze the performance of DC machines and transformers by conducting various tests. |
| Unit I | ELECTROMECHANICAL ENERGY CONVERSION 9 + 0 |
| Magnetic | circuits – Magnetically induced EMF and force – AC operation of magnetic circuits – Energy in |
| magnetic | c systems – Field energy & mechanical force – Single and Multiply-excited magnetic field systems. |
| Unit II | DC GENERATORS 9 + 0 |
| excitatio | ctional features of DC machine – Principle of operation of DC generator – EMF equation – Types of n – No load and load characteristics of DC generators – Commutation - Armature reaction – Parallel n of DC generators - Applications. |
| Unit III | DC MOTORS |
| | of operation of DC motors - Back EMF – Torque equation – Types of DC motors - Speed – |
| Torque o | haracteristics of DC motors – Starting of DC motors: 3- point starter, 4- point starter – Speed control: htrol, Armature voltage control – Applications. |
| Unit IV | TRANSFORMERS 9 + 0 |
| Principle | of operation – Constructional features of single phase transformers – EMF equation – Transformer on |
| No- load | |
| | and Load – Phasor diagrams Equivalent circuit – Regulation - Auto transformers - Three phase ner connections. |
| | and Load – Phasor diagrams Equivalent circuit – Regulation - Auto transformers - Three phase |
| transform Unit V Losses a | and Load – Phasor diagrams Equivalent circuit – Regulation - Auto transformers - Three phase ner connections. Image: TESTING OF DC MACHINES AND TRANSFORMERS 9 + 0 and efficiency – Condition for maximum efficiency – Testing of DC machines: Swinburne's test and on's test - Testing of transformer: open circuit and short circuit tests, Sumpner's test – All day |
| transform Unit V Losses a Hopkinso | and Load – Phasor diagrams Equivalent circuit – Regulation - Auto transformers - Three phase mer connections. Image: TESTING OF DC MACHINES AND TRANSFORMERS 9 + 0 and efficiency – Condition for maximum efficiency – Testing of DC machines: Swinburne's test and on's test - Testing of transformer: open circuit and short circuit tests, Sumpner's test – All day /. |
| transform Unit V Losses a Hopkinso efficiency | and Load – Phasor diagrams Equivalent circuit – Regulation - Auto transformers - Three phase mer connections. Image: TESTING OF DC MACHINES AND TRANSFORMERS 9 + 0 and efficiency – Condition for maximum efficiency – Testing of DC machines: Swinburne's test and on's test - Testing of transformer: open circuit and short circuit tests, Sumpner's test – All day /. Total (45+0)= 45 Periods |
| transform Unit V Losses a Hopkinsa efficiency | and Load – Phasor diagrams Equivalent circuit – Regulation - Auto transformers - Three phase mer connections. TESTING OF DC MACHINES AND TRANSFORMERS 9 + 0 and efficiency – Condition for maximum efficiency – Testing of DC machines: Swinburne's test and on's test - Testing of transformer: open circuit and short circuit tests, Sumpner's test – All day /. Total (45+0)= 45 Periods Outcomes: |
| transform Unit V Losses a Hopkinse efficiency Course Upon co | and Load – Phasor diagrams Equivalent circuit – Regulation - Auto transformers - Three phase ner connections. TESTING OF DC MACHINES AND TRANSFORMERS 9 + 0 and efficiency – Condition for maximum efficiency – Testing of DC machines: Swinburne's test and on's test - Testing of transformer: open circuit and short circuit tests, Sumpner's test – All day /. Total (45+0)= 45 Periods Outcomes: mpletion of this course, the students will be able to: |
| transform Unit V Losses a Hopkinsa efficiency | and Load – Phasor diagrams Equivalent circuit – Regulation - Auto transformers - Three phase ner connections. TESTING OF DC MACHINES AND TRANSFORMERS 9 + 0 and efficiency – Condition for maximum efficiency – Testing of DC machines: Swinburne's test and on's test - Testing of transformer: open circuit and short circuit tests, Sumpner's test – All day /. Total (45+0)= 45 Periods Outcomes: mpletion of this course, the students will be able to: : Understand the concepts of electromechanical energy conversion principles. |
| transform Unit V Losses a Hopkinsa efficiency Course Upon co CO1 | and Load – Phasor diagrams Equivalent circuit – Regulation - Auto transformers - Three phase ner connections. TESTING OF DC MACHINES AND TRANSFORMERS 9 + 0 and efficiency – Condition for maximum efficiency – Testing of DC machines: Swinburne's test and on's test - Testing of transformer: open circuit and short circuit tests, Sumpner's test – All day /. Total (45+0)= 45 Periods Outcomes: mpletion of this course, the students will be able to: |
| transform Unit V Losses a Hopkinsa efficiency Upon co CO1 CO2 | and Load – Phasor diagrams Equivalent circuit – Regulation - Auto transformers - Three phase ner connections. TESTING OF DC MACHINES AND TRANSFORMERS 9 + 0 and efficiency – Condition for maximum efficiency – Testing of DC machines: Swinburne's test and on's test - Testing of transformer: open circuit and short circuit tests, Sumpner's test – All day /. Total (45+0)= 45 Periods Outcomes: mpletion of this course, the students will be able to: : Understand the concepts of electromechanical energy conversion principles. : Understand the basic concepts of DC machines and transformers. |
| transform Unit V Losses a Hopkinse efficiency Course Upon co CO1 CO2 CO3 | and Load – Phasor diagrams Equivalent circuit – Regulation - Auto transformers - Three phase ner connections. TESTING OF DC MACHINES AND TRANSFORMERS 9 + 0 and efficiency – Condition for maximum efficiency – Testing of DC machines: Swinburne's test and on's test - Testing of transformer: open circuit and short circuit tests, Sumpner's test – All day /. 9 + 0 Total (45+0)= 45 Periods Outcomes: mpletion of this course, the students will be able to: : Understand the concepts of electromechanical energy conversion principles. : Understand the basic concepts of DC machines and transformers. : Evaluate the performance characteristics of DC machines and transformers. |
| transform Unit V Losses a Hopkinse efficiency Course Upon co CO1 CO2 CO3 CO4 | and Load – Phasor diagrams Equivalent circuit – Regulation - Auto transformers - Three phase ner connections. Image: Testing of DC MACHINES AND TRANSFORMERS 9 + 0 and efficiency – Condition for maximum efficiency – Testing of DC machines: Swinburne's test and on's test - Testing of transformer: open circuit and short circuit tests, Sumpner's test – All day /. 9 + 0 Total (45+0)= 45 Periods Outcomes: mpletion of this course, the students will be able to: : Understand the concepts of electromechanical energy conversion principles. : Understand the basic concepts of DC machines and transformers. : Evaluate the performance characteristics of DC machines and transformers. : Conduct various tests on DC machines. : Apply the concepts of transformers for testing. |
| transform Unit V Losses a Hopkinse efficiency Course Upon co CO1 CO2 CO3 CO4 CO5 | and Load – Phasor diagrams Equivalent circuit – Regulation - Auto transformers - Three phase ner connections. ITESTING OF DC MACHINES AND TRANSFORMERS 9 + 0 and efficiency – Condition for maximum efficiency – Testing of DC machines: Swinburne's test and on's test - Testing of transformer: open circuit and short circuit tests, Sumpner's test – All day // Total (45+0)= 45 Periods Outcomes: mpletion of this course, the students will be able to: : Understand the concepts of electromechanical energy conversion principles. : Understand the basic concepts of DC machines and transformers. : Evaluate the performance characteristics of DC machines and transformers. : Conduct various tests on DC machines. : Apply the concepts of transformers for testing. obss: D.P. Kothari, I.J. Nagrath, "Electric Machines", 3rd edition, Tata McGraw-Hill Company Ltd., New Delhi, 2017,5 th edition. |
| transform Unit V Losses a Hopkinse efficiency Course Upon co CO1 CO2 CO3 CO4 CO5 Text Boo | and Load – Phasor diagrams Equivalent circuit – Regulation - Auto transformers - Three phase ner connections. TESTING OF DC MACHINES AND TRANSFORMERS 9 + 0 and efficiency – Condition for maximum efficiency – Testing of DC machines: Swinburne's test and on's test - Testing of transformer: open circuit and short circuit tests, Sumpner's test – All day /. 9 + 0 Total (45+0)= 45 Periods Outcomes: mpletion of this course, the students will be able to: : Understand the concepts of electromechanical energy conversion principles. : Understand the basic concepts of DC machines and transformers. : Evaluate the performance characteristics of DC machines and transformers. : Conduct various tests on DC machines. : Apply the concepts of transformers for testing. bks: D.P. Kothari, I.J. Nagrath, "Electric Machines", 3rd edition, Tata McGraw-Hill Company Ltd., New |
| transform Unit V Losses a Hopkinse efficiency Course Upon co CO1 CO2 CO3 CO4 CO5 Text Boo 1. 2. | and Load – Phasor diagrams Equivalent circuit – Regulation - Auto transformers - Three phase ner connections. TESTING OF DC MACHINES AND TRANSFORMERS 9 + 0 and efficiency – Condition for maximum efficiency – Testing of DC machines: Swinburne's test and on's test - Testing of transformer: open circuit and short circuit tests, Sumpner's test – All day /. 0 + 0 Total (45+0)= 45 Periods Outcomes: mpletion of this course, the students will be able to: Understand the concepts of electromechanical energy conversion principles. Understand the basic concepts of DC machines and transformers. Evaluate the performance characteristics of DC machines and transformers. Conduct various tests on DC machines. Apply the concepts of transformers for testing. D.P. Kothari, I.J. Nagrath, "Electric Machines", 3rd edition, Tata McGraw-Hill Company Ltd., New Delhi, 2017,5 th edition. Dr. P.S. Bimbhra, "Electrical Machinery", Khanna Publishers, Delhi, 2021,2 nd edition. |
| transform Unit V Losses a Hopkinse efficiency Course Upon co CO1 CO2 CO3 CO4 CO5 Text Boo 1. 2. | and Load – Phasor diagrams Equivalent circuit – Regulation - Auto transformers - Three phase ner connections. TESTING OF DC MACHINES AND TRANSFORMERS 9 + 0 and efficiency – Condition for maximum efficiency – Testing of DC machines: Swinburne's test and on's test - Testing of transformer: open circuit and short circuit tests, Sumpner's test – All day /. 9 + 0 Total (45+0)= 45 Periods Outcomes: mpletion of this course, the students will be able to: : Understand the concepts of electromechanical energy conversion principles. : Understand the basic concepts of DC machines and transformers. : Evaluate the performance characteristics of DC machines and transformers. : Conduct various tests on DC machines. : Apply the concepts of transformers for testing. bks: D.P. Kothari, I.J. Nagrath, "Electric Machines", 3rd edition, Tata McGraw-Hill Company Ltd., New Delhi, 2017,5 th edition. Dr. P.S. Bimbhra, "Electrical Machinery", Khanna Publishers, Delhi, 2021,2 nd edition. |

| 3. | Dr. K. Murugesh Kumar, "DC Machines & Transformers", Vikas Publishing House Pvt Ltd., 2nd edition, 2003. |
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| E-Referen | ces: |
| 1. | www.onlinecourses.nptel.ac.in |
| 2. | www.class-central.com |
| 3. | www.mooc-list.com |

| PO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 3 | 2 | 2 | 1 | 1 | 1 | 3 | 1 | 1 | 1 | 1 | 2 |
| CO2 | 3 | 2 | 2 | 2 | 1 | 2 | 3 | 1 | 1 | 2 | 1 | 2 |
| CO3 | 1 | 2 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 3 | 1 | 1 |
| CO4 | 2 | 2 | 2 | 2 | 1 | 1 | 2 | 2 | 1 | 2 | 2 | 2 |
| CO5 | 2 | 2 | 2 | 2 | 1 | 1 | 2 | 3 | 1 | 2 | 2 | 2 |

| 18EE304 | ELECTRON DEVICES AND CIRCUITS | L 3 | Т 1 | P 0 | 2 4 |
|--|---|------------------------------|----------------------------------|------------|---------------|
| Courso | Objectives: | 3 | 1 | U | 4 |
| 1. | To understand the characteristics of diode. and transistors. | | | | |
| 2. | To understand the characteristics of transistors. | | | | |
| 3. | To design amplifier circuits | | | | |
| 4. | To design the oscillator circuits. | | | | |
| | | | | | |
| Unit I | DIODES | | 9 | + | |
| Junction diode, V | e – Equilibrium conditions – Energy Band Concepts – Zero bias – Forward Bias capacitances – one sided and Non- uniformly doped junctions – Ideal PN junction cu I characteristics of a diode, review of half-wave and full-wave rectifiers, Zener diodes ner diode, clamping and clipping circuits | irrent, F | Ρ-Ν ju | Inct | io |
| Unit II | TRANSISTORS | | 9 | + | 3 |
| Bipolar and CC | unction Transistor-structure, V-I characteristics and Biasing, Input and output charac configurations – Transistor hybrid model - Junction field effect transistor – st ristics and Biasing - MOSFET structure and V-I characteristics- UJT- structure and c | ructure | s of C , JFE | ΞT | CI |
| Unit III | AMPLIFIER CIRCUITS | | 9 | + | 3 |
| | Ill signal model – Analysis of CE, CB, CC amplifiers- Gain and frequency response - | | - | | |
| | odel– Analysis of CS and Source follower – Gain and frequency response- High freq | | | | |
| 0 | | | | , | |
| | | | | | |
| | MULTISTAGE AMPLIFIERS AND DIFFERENTIAL AMPLIFIER | | 9 | + | |
| BIMOS | cascade amplifier, Differential amplifier – Common mode and Difference mode and | | - FET | | с рі |
| BIMOS stages - | cascade amplifier, Differential amplifier – Common mode and Difference mode and Single tuned amplifiers – Gain and frequency response – Neutralization methods, | | - FET | | ; pi |
| BIMOS stages - | cascade amplifier, Differential amplifier – Common mode and Difference mode and | | - FET | | с рі |
| stages – Types (0 | cascade amplifier, Differential amplifier – Common mode and Difference mode and Single tuned amplifiers – Gain and frequency response – Neutralization methods, Qualitative analysis). | | - FET | | g s |
| BIMOS stages – Types (C Unit V | cascade amplifier, Differential amplifier – Common mode and Difference mode and Single tuned amplifiers – Gain and frequency response – Neutralization methods, Qualitative analysis). FEEDBACK AMPLIFIERS AND OSCILLATORS | power | - FET ampli | fiers | pı s |
| BIMOS stages – Types (0 Unit V Advanta | cascade amplifier, Differential amplifier – Common mode and Difference mode and Single tuned amplifiers – Gain and frequency response – Neutralization methods, Qualitative analysis). | power | - FET ampli | fiers | pı s |
| BIMOS stages – Types (0 Unit V Advanta | cascade amplifier, Differential amplifier – Common mode and Difference mode and Single tuned amplifiers – Gain and frequency response – Neutralization methods, Qualitative analysis). FEEDBACK AMPLIFIERS AND OSCILLATORS ges of negative feedback – voltage / current, series, Shunt feedback –positive feedbac ns, phase shift – Wien bridge, Hartley, Colpitts and Crystal oscillators. | power ack – C | - FET ampli 9 onditi | fiers + | τ pι s |
| BIMOS stages – Types (C Unit V Advanta oscillatic | cascade amplifier, Differential amplifier – Common mode and Difference mode and Single tuned amplifiers – Gain and frequency response – Neutralization methods, Qualitative analysis). FEEDBACK AMPLIFIERS AND OSCILLATORS ges of negative feedback – voltage / current, series, Shunt feedback –positive feedback ns, phase shift – Wien bridge, Hartley, Colpitts and Crystal oscillators. Total (45) | power ack – C | - FET ampli 9 onditi | fiers + | τ pι s |
| BIMOS stages – Types (C Unit V Advanta oscillatic | Cascade amplifier, Differential amplifier – Common mode and Difference mode and Single tuned amplifiers – Gain and frequency response – Neutralization methods, Qualitative analysis). FEEDBACK AMPLIFIERS AND OSCILLATORS ges of negative feedback – voltage / current, series, Shunt feedback –positive feedback ns, phase shift – Wien bridge, Hartley, Colpitts and Crystal oscillators. Total (45 Outcomes: | power ack – C | - FET ampli 9 onditi | fiers + | ju s fo |
| BIMOS stages – Types (C Unit V Advanta oscillatic Course Upon co | Cascade amplifier, Differential amplifier – Common mode and Difference mode and Single tuned amplifiers – Gain and frequency response – Neutralization methods, Qualitative analysis). FEEDBACK AMPLIFIERS AND OSCILLATORS ges of negative feedback – voltage / current, series, Shunt feedback –positive feedback ns, phase shift – Wien bridge, Hartley, Colpitts and Crystal oscillators. Total (45 Outcomes: mpletion of this course, the students will be able to: | power ack – C | - FET ampli 9 onditi | fiers + | τ pι s |
| BIMOS stages – Types (C Unit V Advanta oscillatic Course Upon co CO1 | Cascade amplifier, Differential amplifier – Common mode and Difference mode and Single tuned amplifiers – Gain and frequency response – Neutralization methods, Qualitative analysis). FEEDBACK AMPLIFIERS AND OSCILLATORS ges of negative feedback – voltage / current, series, Shunt feedback –positive feedback ns, phase shift – Wien bridge, Hartley, Colpitts and Crystal oscillators. Total (45) Outcomes: mpletion of this course, the students will be able to: : Understand overview of power semiconductor switches. | power ack – C | - FET ampli 9 onditi | fiers + | ju s fo |
| BIMOS stages – Types (C Unit V Advanta oscillatic Upon co CO1 CO2 | Cascade amplifier, Differential amplifier – Common mode and Difference mode and Single tuned amplifiers – Gain and frequency response – Neutralization methods, Qualitative analysis). | power ack – C | - FET ampli 9 onditi | fiers + | τ pι s |
| BIMOS stages – Types (C Unit V Advanta oscillatic Upon co CO1 CO2 CO3 | Cascade amplifier, Differential amplifier – Common mode and Difference mode and Single tuned amplifiers – Gain and frequency response – Neutralization methods, Qualitative analysis). FEEDBACK AMPLIFIERS AND OSCILLATORS Ges of negative feedback – voltage / current, series, Shunt feedback –positive feedback ns, phase shift – Wien bridge, Hartley, Colpitts and Crystal oscillators. Total (45) Outcomes: mpletion of this course, the students will be able to: Understand overview of power semiconductor switches. Analyse the fundamentals and characteristics of BJT and UJT. Analyse the fundamentals and characteristics of FET andMOSFET. | power ack – C | - FET ampli 9 onditi | fiers + | τ pι s |
| BIMOS stages – Types (C Unit V Advanta oscillatic Course Upon co CO1 CO2 CO3 CO4 | cascade amplifier, Differential amplifier – Common mode and Difference mode and Single tuned amplifiers – Gain and frequency response – Neutralization methods, Qualitative analysis). FEEDBACK AMPLIFIERS AND OSCILLATORS ges of negative feedback – voltage / current, series, Shunt feedback –positive feedback ns, phase shift – Wien bridge, Hartley, Colpitts and Crystal oscillators. Total (45) Outcomes: mpletion of this course, the students will be able to: : Understand overview of power semiconductor switches. : Analyse the fundamentals and characteristics of BJT and UJT. : Analyse the fundamentals and characteristics of FET andMOSFET. : Design and analyze the amplifiers | power ack – C | - FET ampli 9 onditi | fiers + | ju s fo |
| BIMOS stages – Types (C Unit V Advanta oscillatic Upon co CO1 CO2 CO3 CO4 CO5 | cascade amplifier, Differential amplifier – Common mode and Difference mode and Single tuned amplifiers – Gain and frequency response – Neutralization methods, Qualitative analysis). FEEDBACK AMPLIFIERS AND OSCILLATORS ges of negative feedback – voltage / current, series, Shunt feedback –positive feedback ns, phase shift – Wien bridge, Hartley, Colpitts and Crystal oscillators. Total (45 Outcomes: mpletion of this course, the students will be able to: : Understand overview of power semiconductor switches. : Analyse the fundamentals and characteristics of BJT and UJT. : Analyse the fundamentals and characteristics of FET andMOSFET. : Design and analyze the amplifiers : Design and analyze the differential amplifiers | power ack – C | - FET ampli 9 onditi | fiers + | τ pι s |
| BIMOS stages – Types (C Unit V Advanta oscillatic Upon co CO1 CO2 CO3 CO4 CO5 | cascade amplifier, Differential amplifier – Common mode and Difference mode and Single tuned amplifiers – Gain and frequency response – Neutralization methods, Qualitative analysis). FEEDBACK AMPLIFIERS AND OSCILLATORS ges of negative feedback – voltage / current, series, Shunt feedback –positive feedback ns, phase shift – Wien bridge, Hartley, Colpitts and Crystal oscillators. Total (45) Outcomes: mpletion of this course, the students will be able to: : Understand overview of power semiconductor switches. : Analyse the fundamentals and characteristics of BJT and UJT. : Analyse the fundamentals and characteristics of FET andMOSFET. : Design and analyze the amplifiers | power ack – C | - FET ampli 9 onditi | fiers + | pi s fo |
| BIMOS stages – Types (C Unit V Advanta oscillatic Upon co CO1 CO2 CO3 CO4 CO5 CO6 | cascade amplifier, Differential amplifier – Common mode and Difference mode and Single tuned amplifiers – Gain and frequency response – Neutralization methods, paualitative analysis). FEEDBACK AMPLIFIERS AND OSCILLATORS ges of negative feedback – voltage / current, series, Shunt feedback –positive feedback ns, phase shift – Wien bridge, Hartley, Colpitts and Crystal oscillators. Total (45 Outcomes: mpletion of this course, the students will be able to: : Understand overview of power semiconductor switches. : Analyse the fundamentals and characteristics of BJT and UJT. : Analyse the fundamentals and characteristics of FET andMOSFET. : Design and analyze the differential amplifiers : Design and analyze the oscillator circuits | power ack – C | - FET ampli 9 onditi | fiers + | pi s fo |
| BIMOS stages – Types (C Unit V Advanta oscillatic Upon co CO1 CO2 CO3 CO4 CO5 CO6 Text Bo | cascade amplifier, Differential amplifier – Common mode and Difference mode and Single tuned amplifiers – Gain and frequency response – Neutralization methods, paulitative analysis). FEEDBACK AMPLIFIERS AND OSCILLATORS ges of negative feedback – voltage / current, series, Shunt feedback –positive feedback ns, phase shift – Wien bridge, Hartley, Colpitts and Crystal oscillators. Total (45 Outcomes: mpletion of this course, the students will be able to: : Understand overview of power semiconductor switches. : Analyse the fundamentals and characteristics of BJT and UJT. : Design and analyze the amplifiers : Design and analyze the oscillator circuits | power ack – C 5+15)= | - FET ampli 9 onditi | fiers + | τ pι s |
| BIMOS stages – Types (C Unit V Advanta oscillatic Upon co CO1 CO2 CO3 CO4 CO5 CO6 Text Bo 1. | Cascade amplifier, Differential amplifier – Common mode and Difference mode and Single tuned amplifiers – Gain and frequency response – Neutralization methods, Qualitative analysis). FEEDBACK AMPLIFIERS AND OSCILLATORS ges of negative feedback – voltage / current, series, Shunt feedback –positive feedback ns, phase shift – Wien bridge, Hartley, Colpitts and Crystal oscillators. Total (45 Outcomes: mpletion of this course, the students will be able to: : Understand overview of power semiconductor switches. : Analyse the fundamentals and characteristics of BJT and UJT. : Analyse the fundamentals and characteristics of FET andMOSFET. : Design and analyze the amplifiers : Design and analyze the oscillator circuits * Outcomes * Design and analyze the oscillator circuits | power ack – C 5+15)= | - FET ampli 9 0nditi | + ion 1 | fo |
| BIMOS stages – Types (C Unit V Advanta oscillatic Upon co CO1 CO2 CO3 CO4 CO5 CO6 Text Bo | Cascade amplifier, Differential amplifier – Common mode and Difference mode and Single tuned amplifiers – Gain and frequency response – Neutralization methods, Qualitative analysis). FEEDBACK AMPLIFIERS AND OSCILLATORS ges of negative feedback – voltage / current, series, Shunt feedback –positive feedback ns, phase shift – Wien bridge, Hartley, Colpitts and Crystal oscillators. Total (45 Outcomes: mpletion of this course, the students will be able to: Understand overview of power semiconductor switches. Analyse the fundamentals and characteristics of BJT and UJT. Design and analyze the amplifiers Design and analyze the differential amplifiers Design and analyze the oscillator circuits Oks: Sedra and smith, "Microelectronic Circuits " Oxford University Press, 2017,7 th edid David A. Bell, "Electronic Devices and Circuits", New Delhi: Oxford University Press, 2017,7 th edid | power ack – C 5+15)= | - FET ampli 9 0nditi | + ion 1 | fo |
| BIMOS stages – Types (C Unit V Advanta oscillatic Upon co CO1 CO2 CO3 CO4 CO5 CO6 Text Bo 1. | Cascade amplifier, Differential amplifier – Common mode and Difference mode and Single tuned amplifiers – Gain and frequency response – Neutralization methods, Qualitative analysis). FEEDBACK AMPLIFIERS AND OSCILLATORS ges of negative feedback – voltage / current, series, Shunt feedback –positive feedback ns, phase shift – Wien bridge, Hartley, Colpitts and Crystal oscillators. Total (45 Outcomes: mpletion of this course, the students will be able to: : Understand overview of power semiconductor switches. : Analyse the fundamentals and characteristics of BJT and UJT. : Analyse the fundamentals and characteristics of FET andMOSFET. : Design and analyze the amplifiers : Design and analyze the oscillator circuits * Outcomes * Design and analyze the oscillator circuits | power ack – C 5+15)= | - FET ampli 9 0nditi | + ion 1 | fo |
| BIMOS stages – Types (C Unit V Advanta oscillatic Upon co CO1 CO2 CO3 CO4 CO5 CO6 Text Bo 1. 2. 3. | Asscade amplifier, Differential amplifier – Common mode and Difference mode and Single tuned amplifiers – Gain and frequency response – Neutralization methods, Qualitative analysis). FEEDBACK AMPLIFIERS AND OSCILLATORS ges of negative feedback – voltage / current, series, Shunt feedback –positive feedback ns, phase shift – Wien bridge, Hartley, Colpitts and Crystal oscillators. Total (45 Outcomes: mpletion of this course, the students will be able to: Understand overview of power semiconductor switches. Analyse the fundamentals and characteristics of BJT and UJT. Analyse the fundamentals and characteristics of FET andMOSFET. Design and analyze the amplifiers Design and analyze the oscillator circuits Oks: Sedra and smith, "Microelectronic Circuits " Oxford University Press, 2017,7th edi David A. Bell, "Electronic Devices and Circuits", New Delhi: Oxford University Pr 2008. Robert L.Boylestad, "Electronic Devices and Circuit theory", 2014,10th edition. | power ack – C 5+15)= | - FET ampli 9 0nditi | + ion 1 | fo |
| BIMOS stages – Types (C Advanta oscillatic Course Upon co CO1 CO2 CO3 CO4 CO5 CO6 Text Bo 1. 2. 3. Referen | Asscade amplifier, Differential amplifier – Common mode and Difference mode and Single tuned amplifiers – Gain and frequency response – Neutralization methods, Qualitative analysis). FEEDBACK AMPLIFIERS AND OSCILLATORS ges of negative feedback – voltage / current, series, Shunt feedback –positive feedbans, phase shift – Wien bridge, Hartley, Colpitts and Crystal oscillators. Total (45 Outcomes: mpletion of this course, the students will be able to: : Understand overview of power semiconductor switches. : Analyse the fundamentals and characteristics of BJT and UJT. : Analyse the fundamentals and characteristics of FET andMOSFET. : Design and analyze the amplifiers : Design and analyze the oscillator circuits obs: Sedra and smith, "Microelectronic Circuits " Oxford University Press, 2017,7th edi David A. Bell, "Electronic Devices and Circuits", New Delhi: Oxford University Press, 2017,7th edition. ce Books: | power ack – C 5+15)= | - FET ampli 9 0nditi | + ion 1 | fo |
| BIMOS stages – Types (C Advanta oscillatic Upon co CO1 CO2 CO3 CO4 CO5 CO6 Text Bo 1. 2. 3. Referen 1. | Asscade amplifier, Differential amplifier – Common mode and Difference mode and Single tuned amplifiers – Gain and frequency response – Neutralization methods, Qualitative analysis). FEEDBACK AMPLIFIERS AND OSCILLATORS ges of negative feedback – voltage / current, series, Shunt feedback –positive feedback ns, phase shift – Wien bridge, Hartley, Colpitts and Crystal oscillators. Total (45 Outcomes: mpletion of this course, the students will be able to: Understand overview of power semiconductor switches. Analyse the fundamentals and characteristics of BJT and UJT. Analyse the fundamentals and characteristics of FET andMOSFET. Design and analyze the amplifiers Design and analyze the differential amplifiers Design and analyze the oscillator circuits Sedra and smith, "Microelectronic Circuits " Oxford University Press, 2017,7 th edi David A. Bell, "Electronic Devices and Circuits", New Delhi: Oxford University Pr 2008. Robert L.Boylestad, "Electronic Devices and Circuit theory", 2014,10 th edition. Ce Books: Rashid, "Micro Electronic Circuits" Thomson publications, 1999. | tion ess, 5 ^{tt} | • FET ampli onditi 60 P | erio | fo |
| BIMOS stages – Types (C Advanta oscillatic Course Upon co CO1 CO2 CO3 CO4 CO5 CO6 Text Bo 1. 2. 3. Referen | Asscade amplifier, Differential amplifier – Common mode and Difference mode and Single tuned amplifiers – Gain and frequency response – Neutralization methods, Qualitative analysis). FEEDBACK AMPLIFIERS AND OSCILLATORS ges of negative feedback – voltage / current, series, Shunt feedback –positive feedbans, phase shift – Wien bridge, Hartley, Colpitts and Crystal oscillators. Total (45 Outcomes: mpletion of this course, the students will be able to: : Understand overview of power semiconductor switches. : Analyse the fundamentals and characteristics of BJT and UJT. : Analyse the fundamentals and characteristics of FET andMOSFET. : Design and analyze the amplifiers : Design and analyze the oscillator circuits obs: Sedra and smith, "Microelectronic Circuits " Oxford University Press, 2017,7th edi David A. Bell, "Electronic Devices and Circuits", New Delhi: Oxford University Press, 2017,7th edition. ce Books: | tion ess, 5 ^t | - FET ampli onditi 60 P | erio | fo |

| E –References | | | | | |
|---------------|--|--|--|--|--|
| 1. | https://electronicsforum.com/resources/electronic-devices-and-circuit-theory | | | | |
| 2. | https://nptel.ac.in/courses/117103063/ | | | | |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 1 | 1 | 1 | 1 | 1 | 1 | 3 | 1 | 1 | 1 | 1 | |
| CO2 | 2 | 3 | 3 | 3 | 2 | 1 | 2 | 1 | 1 | 1 | 1 | |
| CO3 | 3 | 2 | 2 | 3 | 2 | 1 | 2 | 1 | 1 | 1 | 1 | |
| CO4 | 2 | 3 | 2 | 3 | 3 | 1 | 2 | 1 | 1 | 1 | 1 | |
| CO5 | 2 | 2 | 3 | 3 | 3 | 1 | 2 | 1 | 1 | 1 | 1 | |
| CO6 | 2 | 3 | 3 | 3 | 2 | 1 | 2 | 1 | 1 | 1 | 1 | |

| 18EE30 |)5 | DC MACHINES AND TRANSFORMERS LABORATORY | 2 | | | | | | | |
|---------------|-----|---|------|--|--|--|--|--|--|--|
| | | | 1.5 | | | | | | | |
| Course | Ob | ojectives: | | | | | | | | |
| 1. | | To understand the performance characteristics of DC machines and transformers | | | | | | | | |
| 2. | | To gain knowledge on experimental skill of testing different types of DC machines and transforme | ers. | | | | | | | |
| 3. | | Rig up circuits for testing a given machine. | | | | | | | | |
| | | | | | | | | | | |
| Experir | nen | | | | | | | | | |
| 1 | | Open circuit and load characteristics of separately excited DC generator. | | | | | | | | |
| 2 | | Open circuit and load characteristics of DC shunt generator. | | | | | | | | |
| 3 | | Load characteristics of DC long shunt and short shunt compound generator with cumulative a | and | | | | | | | |
| | | differential connections. | | | | | | | | |
| 4 | | Load test on DC shunt motor. | | | | | | | | |
| 5 | | Load test on DC series motor. | | | | | | | | |
| 6 | | Swinburne's test on DC machines. | | | | | | | | |
| 7 | | Speed control of DC shunt motor. | | | | | | | | |
| 8 | | Hopkinson's test on two identical DC machines. | | | | | | | | |
| 9 | | Load test on single-phase transformer. | | | | | | | | |
| 10 | | Equivalent circuit of a single-phase transformer. | | | | | | | | |
| 11 | | Sumpner's test on transformers. | | | | | | | | |
| 12 | | Study of DC motor starters and 3-phase transformer connections. | | | | | | | | |
| | | | | | | | | | | |
| Course | 0 | Itcomes: Total (0+45)= 45 Peri | iods | | | | | | | |
| | | bletion of this course, the students will be able to: | | | | | | | | |
| CO1 | 1.1 | Obtain the performance characteristics of DC generators. | | | | | | | | |
| CO2 | • | Obtain the load characteristics of DC compound generator. | | | | | | | | |
| CO2 CO3 | • | Acquire knowledge on performance characteristics of DC shunt and series motors. | | | | | | | | |
| CO3 CO4 | • | Acquire knowledge on performance characteristics of DC shaft and series motors. | -+ | | | | | | | |
| | • | methods. | | | | | | | | |
| CO5 | : | Acquire knowledge on performance characteristics of transformers using direct and indirect metho | ds. | | | | | | | |
| Refere | nce | Books: | | | | | | | | |
| 1. | | G.P. Chhalotra, 'Experiments in Electrical Engineering', 3 rd Ed., Khanna Publishers, Delhi, 2004. | | | | | | | | |
| 2. | | C.S. Indulkar, 'Laboratory Experiments in Electrical Power', 3 rd Ed., Khanna Publishers, Delhi, 2010. | | | | | | | | |
| 3. | | DC machines and transformers laboratory manual prepared by the department. | | | | | | | | |
| E-Refe | on | | | | | | | | | |
| <u>E-Refe</u> | ene | www.onlinecourses.nptel.ac.in | | | | | | | | |
| 2. | | www.class-central.com | | | | | | | | |
| 3. | | www.mooc-list.com | | | | | | | | |
| 0. | | | | | | | | | | |

| RO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 3 | 3 | 2 | 1 | 1 | 1 | 3 | 1 | 2 | 1 | 1 | 2 |
| CO2 | 3 | 3 | 3 | 3 | 2 | 2 | 3 | 1 | 1 | 2 | 1 | 1 |
| CO3 | 3 | 3 | 3 | 2 | 2 | 1 | 1 | 2 | 1 | 3 | 1 | 1 |
| CO4 | 3 | 3 | 3 | 1 | 1 | 1 | 2 | 2 | 1 | 2 | 2 | 2 |
| CO5 | 2 | 3 | 2 | 3 | 1 | 1 | 1 | 3 | 1 | 2 | 2 | 2 |

18EE306

ELECTRON DEVICES AND CIRCUITS LABORATORY

| L | Т | Ρ | С |
|---|---|---|-----|
| 0 | 0 | 3 | 1.5 |
| | | | |

Course Objectives:

| | To design analog electronic circuits using Diode, BJT and MOSFET |
|----|--|
| 2. | To design amplifiers and oscillators. |

Experiments:

| Ехропппо | |
|----------|--|
| 1 | Static characteristics of semiconductor diode, zener diode and study of simple voltage regulator |
| | circuits. |
| 2 | Single phase half wave and full wave rectifiers with inductive and capacitive filters. |
| 2 3 | Static Characteristics of BJT under CE, CB, CC and determination of hybrid parameters. |
| 4 | Static characteristics of JFET. |
| 5 | Static and Switching Characteristics of MOSFET |
| 6 | Static characteristics of UJT. |
| 7 | Frequency response of CB/CE/CC amplifiers. |
| 8 | Frequency response of CD/CS amplifiers. |
| 9 | Differential amplifiers using FET. |
| 10 | Design of RC Phase shift oscillators. |
| 11 | Design of Wien bridge oscillators. |
| 12 | Design of Hartley/Colpitts oscillators. |
| | Total (0: 45) - 45 Darieda |

Total (0+45)= 45 Periods

| Course Outcomes: | | | | | | |
|---|---|---|--|--|--|--|
| Upon completion of this course, the students will be able to: | | | | | | |
| CO1 | | To design analog electronic circuits using Diode | | | | |
| CO2 | : | To design analog electronic circuits using BJT | | | | |
| CO3 | : | To design analog electronic circuits using MOSFET | | | | |
| CO4 | : | To design analog electronic circuits using FET | | | | |
| CO5 | : | To design oscillator circuits | | | | |
| CO6 | : | To design Wave generating circuits | | | | |
| | | | | | | |

Reference Books:

| 1 | David A. Bell, "Electronic Devices and Circuits", New Delhi: Oxford University Press, 5 th Edition, 2008. |
|----------|---|
| 2 | Jacob Millman, Christos C.Halkias, 'Integrated Electronics - Analog and Digital circuits system', Tata McGraw Hill, 2003. |
| 3 | Robert L.Boylestad, "Electronic Devices and Circuit theory", 2002. |
| E Defera | |

E –References

| 1 | https://electronicsforu.com/resources/electronic-devices-and-circuit-theory |
|---|---|
| 2 | https://nptel.ac.in/courses/117103063/ |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 2 | 3 | 1 | 1 | 1 | 1 | 3 | 1 | 1 | 1 | 1 | |
| CO2 | 2 | 3 | 3 | 3 | 2 | 1 | 3 | 1 | 1 | 1 | 1 | |
| CO3 | 3 | 2 | 2 | 3 | 2 | 1 | 3 | 1 | 1 | 1 | 1 | |
| CO4 | 2 | 3 | 2 | 3 | 3 | 1 | 3 | 1 | 1 | 1 | 1 | |
| CO5 | 2 | 2 | 3 | 3 | 3 | 1 | 3 | 1 | 1 | 1 | 1 | |
| CO6 | 2 | 3 | 3 | 3 | 2 | 1 | 2 | 1 | 1 | 1 | 1 | |

| 18CYMC01 | 1 | ENVIRONMENTAL SCIENCE | L | Т | Ρ | С |
|-----------|------|---|--------------------|---------|--------|-------|
| | | | 0 | 0 | 1 | 0 |
| Course ob | ject | ives: | | | | |
| 1 | | They are part of the environment | | | | |
| 2 | | To have an ancient wisdom drawn from Vedas | | | | |
| 3 | | Activities based knowledge to preserve environment, Conservation of w optimization. | ate | anc | 1 | its |
| Experimen | nts | | | | | |
| | | Environmental Awareness | | 61 | nours | 5 |
| 1 | | Group activity on water management | | | | |
| 2 | | Group discussion on recycle of waste (4R's) | | | | |
| 3 | | Slogan making contest. | | | | |
| 4 | | Poster making event. | | | | |
| 5 | | Expert lecture on environmental awareness. | | | | |
| 6 | | Imparting knowledge on reduction of electricity usage | | | | |
| | | Environmental activities | | 8 | nour | 5 |
| 1 | | Identification and segregation of biodegradable and non biodegradable wa | aste | | | |
| 2 | | Campus cleaning activity | | | | |
| 3 | | Plantation of trees in the college campus and local waste lands. | | | | |
| 4 | | Identification of varieties of plants and their usage | | | | |
| 5 | | Shutting down the fans and ACs of the campus for an hour | | | | |
| 6 | | Field work on growing of kitchen garden for mess. | | <u></u> | | |
| Course Ou | 100 | Total | 14+ | 0)= ^ | 4 Pe | riods |
| | | on of this course, the students will be able to: | | | | |
| CO1 | | Use and save water effectively | | | | |
| CO1 | • | Reuse the waste effectively | | | | |
| CO2 | · | Save electricity for future generation | | | | |
| CO3 | · | Classify biodegradable and non biodegradable waste | | | | |
| CO4 | • | Plant trees in the college campus and local waste lands. | | | | |
| 005 | • | Flant trees in the college campus and local waste lands. | | | | |
| Reference | Boo | oks: | | | | |
| 1 | | D K Asthana "A Text book on Environmental studies", S.Chand Publications | 5, 5 th | Edit | ion, 2 | 2010 |
| 2 | | Rajesh Gopinath," Environmental Science and Engineering", Cengage, 201 | 4 | | | |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | | | | | | 2 | | | | | | |
| CO2 | | | | | | 2 | | | | | | |
| CO3 | | | | | | | 2 | 3 | | | | |
| CO4 | | | | | 1 | | | | | | | |
| CO5 | | | 3 | | | | | | | | | |

| TestEarunt SignALS AND STSTEWS L I P C Course objectives: 1 Understand the concepts of continuous time and discrete time systems. 2 1 0 0 2 Analyze systems in complex frequency domain. 3 3 1 0 6 + 3 3 Understand sampling theorem and its implications. 6 + 3 3 5 6 + 3 3 Signals and systems. Signal properties: periodicity, absolute integrability, deterministic and stochastic character. Some special signals of importance: the unit step, the unit impulse, the sinusoid, the complex exponential. Classification of signals – Continuous time (CT) and Discrete Time (DT) signals. Periodic & Aperiodic Signals, Deterministic & Random signals. Energy & Power signals. System properties: linearity, additivity and homogeneity, shift-invariance, causality and stability of LTI systems. System representation. 6 + 3 NIT II CONTINUOUS AND DISCRETE-TIME LTI SYSTEMS 6 + 3 Fourier series representation of a frequency response and step response, convolution, input-output behavior with aperiodic convergent inputs. 5 + 3 System, the notion of a frequency response and step representation 6 + 3 3 Fourier Fransform, convolution/multiplication and their effect in the frequency domain, magnitude and phase response. <th>4055404</th> <th></th> <th></th> <th>-</th> <th></th> <th></th> | 4055404 | | | - | | |
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| response, Fourier domain duality. The Discrete-Time Fourier Transform (DTFT) and the Discrete Fourier Transform (DFT). Parseval's Theorem. Review of the Laplace Transform for continuous time signals and systems, system functions, poles and zeros of system functions and signals, Laplace domain analysis, solution to differential equations and system behavior. UNIT IV Z-TRANSFORMS Z-transform and its properties, inverse z-transforms; difference equation – Solution by z transform, application to discrete systems - Stability analysis, frequency response – Convolution. UNIT V SAMPLING AND RECONSTRUCTION 6 + 3 The Sampling Theorem and its implications. Spectra of sampled signals. Reconstruction: ideal interpolator, zero-order hold, first-order hold. Aliasing and its effects. Relation between continuous and discrete time systems. Introduction to the applications of signal and system theory: modulation for communication, filtering, feedback control systems. Total (30+15)= 45 Periods Course Outcomes: Upon completion of this course, the students will be able to: <u>CO1</u> : Determine if a given system is linear/causal/stable <u>CO2</u> : Capable of determining the frequency components present in a deterministic signal <u>CO3</u> : Capable of characterizing LTI systems in the time domain and frequency domain <u>CO4</u> : Compute the output of an LTI system in the time and frequency domains <u>CO5</u> : Capable of determining the frequency response of discrete system using Z transform <u>CO6</u> : Understand the concepts and importance of sampling Text Books: <u>1</u> Allan V.Oppenheim, S.Wilsky and S.H.Nawab, —Signals and SystemsII, Pearson, 2015. <u>2</u> J. G. Proakis and D. G. Manolakis, "Digital Signal Processing: Principles, Algorithms, and | | | | | | |
| Transform (DFT). Parseval's Theorem. Review of the Laplace Transform for continuous time signals and systems, system functions, poles and zeros of system functions and signals, Laplace domain analysis, solution to differential equations and system behavior. UNIT IV Z-TRANSFORMS 6 + 3 Z-transform and its properties, inverse z-transforms; difference equation – Solution by z transform, application to discrete systems - Stability analysis, frequency response – Convolution. 6 + 3 UNIT V SAMPLING AND RECONSTRUCTION 6 + 3 The Sampling Theorem and its implications. Spectra of sampled signals. Reconstruction: ideal interpolator, zero-order hold, first-order hold. Aliasing and its effects. Relation between continuous and discrete time systems. Introduction to the applications of signal and system theory: modulation for communication, filtering, feedback control systems. Course Outcomes: Total (30+15)= 45 Periods CO1 : Determine if a given system is linear/causal/stable CO2 : Capable of determining the frequency components present in a deterministic signal CO3 : Capable of characterizing LTI system in the time and frequency domains CO4 : Compute the output of an LTI system in the time and frequency domains CO5 : Capable of determining the frequency response of discrete system using Z transform CO6 <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> | | | | | | |
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| UNIT V SAMPLING AND RECONSTRUCTION 6 + 3 The Sampling Theorem and its implications. Spectra of sampled signals. Reconstruction: ideal interpolator, zero-order hold, first-order hold. Aliasing and its effects. Relation between continuous and discrete time systems. Introduction to the applications of signal and system theory: modulation for communication, filtering, feedback control systems. 6 + 3 Total (30+15)= 45 Periods Course Outcomes: Upon completion of this course, the students will be able to: CO1 : Determine if a given system is linear/causal/stable CO2 : Capable of determining the frequency components present in a deterministic signal CO3 : Capable of characterizing LTI systems in the time and frequency domain CO4 : Compute the output of an LTI system in the time and frequency domains CO5 : Capable of determining the frequency response of discrete system using Z transform CO6 : Understand the concepts and importance of sampling Text Books: 1. Allan V.Oppenheim, S.Wilsky and S.H.Nawab, —Signals and SystemsII, Pearson, 2015. J. G. Proakis and D. G. Manolakis, "Digital Signal Processing: Principles, Algorithms, and | | | orm, | app | licat | on |
| The Sampling Theorem and its implications. Spectra of sampled signals. Reconstruction: ideal interpolator, zero-order hold, first-order hold. Aliasing and its effects. Relation between continuous and discrete time systems. Introduction to the applications of signal and system theory: modulation for communication, filtering, feedback control systems. Total (30+15)= 45 Periods Course Outcomes: Upon completion of this course, the students will be able to: Col : Determine if a given system is linear/causal/stable CO2 : Capable of determining the frequency components present in a deterministic signal CO3 : Capable of characterizing LTI systems in the time domain and frequency domain CO4 : Compute the output of an LTI system in the time and frequency domains CO5 : Capable of determining the frequency response of discrete system using Z transform CO6 : Understand the concepts and importance of sampling Text Books: 1. Allan V.Oppenheim, S.Wilsky and S.H.Nawab, —Signals and SystemsII, Pearson, 2015. 2 J. G. Proakis and D. G. Manolakis, "Digital Signal Processing: Principles, Algorithms, and | to discrete | systems - Stability analysis, frequency response – Convolution. | | | | |
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| J. G. Proakis and D. G. Manolakis, "Digital Signal Processing: Principles, Algorithms, and | | |)15. | | | |
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| 3. | B. P. Lathi, "Linear Systems and Signals", Oxford University Press, 2009. |
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| 4. | A. V. Oppenheim and R. W. Schafer, "Discrete-Time Signal Processing", Prentice Hall, 2009. |
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| Reference | e Books: |
| 1. | H. P. Hsu, "Signals and systems", Schaum's series, McGraw Hill Education, 2010. |
| 2. | S. Haykin and B. V. Veen, "Signals and Systems", John Wiley and Sons, 2007. |
| 3. | M. J. Robert "Fundamentals of Signals and Systems", McGraw Hill Education, 2007. |
| 4. | R.E.Zeimer, W.H.Tranter and R.D.Fannin, —Signals & Systems - Continuous and Discretell, |
| | Pearson, 2007. |
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| E -Referer | nces |
| 1 | https://nptel.ac.in/courses/117104074/ |

| RO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 2 | 3 | 1 | 1 | 1 | 1 | 2 | 1 | 1 | 1 | 1 | |
| CO2 | 2 | 3 | 1 | 1 | 2 | 1 | 2 | 1 | 1 | 1 | 1 | |
| CO3 | 2 | 3 | 2 | 3 | 2 | 1 | 3 | 1 | 1 | 1 | 1 | |
| CO4 | 2 | 3 | 2 | 3 | 3 | 1 | 3 | 1 | 1 | 1 | 1 | |
| CO5 | 2 | 3 | 3 | 3 | 3 | 1 | 3 | 1 | 1 | 1 | 1 | |
| CO6 | 2 | 3 | 3 | 3 | 2 | 1 | 2 | 1 | 1 | 1 | 1 | |

| 18EE40 |)2 | SYNCHRONOUS AND INDUCTION MACHINES | L | Т | Ρ | С |
|---------------|---------|--|------------|----------|-----------|--------------|
| | | | 3 | 0 | 0 | 3 |
| Course | Obj | ectives: | | | | |
| This cou | rse | provides understanding of AC machinery fundamentals, machine parts and helps | s to d | evel | op t | he skills |
| for opera | ating | AC machines, and equips students to analyze the equivalent circuits of Inducti | | | | |
| Machine | s. | | | | | |
| Unit I | | ALTERNATOR | | <u> </u> | | 0 |
| | otion | n, types, practical rating of synchronous generators, winding factors, production | |) EM | + | 0 rmature |
| | | ynchronous reactance, phasor diagram, Methods of pre-determination of | | | | |
| | | s impedance, ampere turn, Potier triangle methods. Two reaction theory–Slip tes | | | | |
| | | xcitation and mechanical input | | | | |
| Unit II | | SYNCHRONOUS MOTOR | | 2 | + | 0 |
| | of or | peration-phasor diagrams, Torque equation - Operation on infinite bus bars, va | | - | | - |
| | | r with excitation. Hunting and its suppression, V and inverted V curves, Sync | | | | |
| method | | | | | | |
| | | | | | | |
| Unit III | | THREE PHASE INDUCTION MACHINES | | - | + | 0 |
| | | nal details, types, production of rotating magnetic field-principle of operation an | | | | |
| | | otors. Need for starting – Types of starters – DOL, Rotor resistance and Auto transferred to the construction operation, and applications. | ansi | onne | er st | arters. |
| General | 01 a | | | | | |
| Unit IV | | ANALYSIS AND TESTING OF THREE PHASE INDUCTION MOTORS | 9 |) | + | 0 |
| Phasor | diac | gram, equivalent circuit, Torque equation-starting and maximum-torque, maxi | mum | -out | put, | |
| | | utput, Torque-slip characteristics, losses and efficiency. Testing-no load and | | | | |
| equivale | nt c | ircuit parameters, circle diagram. | | | | |
| Unit V | | SINGLE PHASE INDUCTION MOTOR | | <u> </u> | | 0 |
| | rtior | nal details of single-phase induction motor – Double field revolving theory and op | | - | + - Eo | - |
| | | ting methods of single-phase induction motors – Capacitor-start capacitor run Ind | | | | |
| | | on motor. | | | | Chado |
| • | | | | | | |
| <u>Cauraa</u> | <u></u> | | (45+ | -0) = | 45 | Period |
| Course | | | | | | |
| Upon co | mpl | etion of this course, the students will be able to: | | | | |
| CO1 | : | Familiarize with construction, working principle, synchronizing techniques an | d pe | rforr | nan | ce of |
| CO2 | | Synchronous Generator. Understand the working principle, torque equation, and excitation control for Syn | chro | | Mo | tor |
| CO3 | • | Operate three phase Induction machine as motor and as a generator. | CIIIOI | ious | | .01. |
| CO4 | : | Analyze the performance of three phase induction motor with testing. | | | | |
| CO5 | : | Know double field revolving theory and starting mechanisms for single-phase inc | luctio | n m | otors | 6 |
| CO6 | : | Use synchronous and induction motors in practical domain with specified ratings | | | | |
| | 1 1 | · · · · · · | | | | |
| Text Bo | oks | | | | | |
| 1. | | D.P. Kothari, I.J. Nagrath, "Electric Machines", 5th edition, Tata McGraw-Hill C Delhi, 2017. | omp | any I | Ltd., | New |
| 2. | | Dr.P.S.Bimbhra, "Electrical Machinery", Khanna Publishers, Delhi, 2021,2 nd edition | on. | | | |
| 0 | | A.E. Fitzgerald, Charles Kingsley, Stephen. D.Umans, 'Electric Machinery', | | McC | Grav | / Hill |
| 3. | | Publishing Company Ltd, 2017,5 th edition. | | | | |
| Poforon | 00 F | Poaks | | | | |
| Referen 1. | cet | зоокs: B.L.Theraja& A.K. Theraja, "Electrical Technology", Vol.II, S.Chand& Company Lt | <u>4 N</u> | |)olh: | 2015 |
| 1. | | D.E. HIGIajaa A.R. HIGIaja, Electrical rectinology, Vol.11, S.Chanua Company El | u., N | UVV L | | , 2010. |

| 2. | Alexander S. Langsdorf, Theory of Alternating-Current Machinery, Tata McGraw Hill Publications, 2009. |
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| E-Referenc | e |
| 1 | www.nptel.ac.in |

| PO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | | 1 | | | | | 2 | | | | | 2 |
| CO2 | | 1 | | | 2 | | | | | | | 1 |
| CO3 | 3 | | | | | | 2 | | | | 1 | |
| CO4 | 2 | | | 3 | | 1 | | | 2 | | | |
| CO5 | | | | | 1 | | | | | 2 | | 2 |
| CO6 | | | 2 | 3 | | | | | | | 2 | |

| 18EE403 | MEASUREMENTS AND INSTRUMENTATION L T P | C 3 |
|---|--|----------------------------------|
| Course Ob | | |
| 1. | To introduce the basic functional elements of instrumentation | |
| 2. | To introduce the fundamentals of electrical and electronic instruments | |
| 3. | To educate on the various magnetic measurement techniques | |
| 4. | | |
| | To be familiarized with the various bridge circuits for measurement of R, L, C | |
| 5. | To introduce various transducers and the data acquisition systems. | |
| Unit I | ANALOG INSTRUMENTS 9 + | 0 |
| Dynamic constructior | f a Generalized Measurement System- Measurement System performance – Static Characteri Characteristics – Classification of Analog instruments – Principle of operation – operating force nal details – types of control systems – types of damping systems. Operation – torque equation errors – extension range of – PMMC – MI – Electrodynamometer – induction type instruments. | es – |
| Unit II | MEASUREMENT OF POWER AND ENERGY 9 + | 0 |
| induction ty of high pow | ent of power in DC circuits, power in AC circuit- single and three phase- electrodynamom pe watt meters – Construction, operation – torque equation for deflection – errors- measuremer using instrument power transformer – measurement of energy for AC circuits- induction type s – construction theory and operation – torque equation – adjustment in energy meter | ents |
| Unit III | MAGNETIC MEASUREMENTS 9 + | 0 |
| testing of testing vary | on of B-H curve –determination of hermistor loop by step by step method and method of reverse bar specimens – Hopkinson permeameters – Illiovici permeameters – alternating current magning with form factor and frequency – wattmeter method of iron loss measurements method. | etic |
| Unit IV | MEASUREMNT OF R, L, C AND POTENTIOMETERS 9 + | |
| inductance potentiomet | uations – Wheatstone bridge – Kelvin double Bridge – Maxwell's inductance bridge – Maxwell capacitance bridge – Hay's bridge – Anderson's bridge – Schering bridge and Wien's bridge. ter – lab type hermist's potentiometer, Duo range potentiometer – precision type potentiomet ometer– Drysdale polar potentiometer- Gall Tinsley co-ordinate type - Campbell – Larsen type. | DC |
| Unit V | MEASUREMENT OF NON-ELECTRICAL QUANTITIES 9 + | 0 |
| Classification Transducer change in A – Tachoger | on of transducers – factor influencing the choice of transducers. Resistive transducers, Indu s – potentiometers. Linear Variable Differential Transformer – RVDT – Capacitive transducers us area of Plates. Photoelectric transducers, Piezoeletrci transducers – Measurement of angular vel nerator – Photoelectric tachometerMeasurement of temperature – hermistor – thermocoup - Measurement of flow – hot wire anemometers – turbine meters – electromagnetic flow meters | ctive using ocity ole – |
| | Total (45+0)= 45 Per | iods |
| Course Ou | tcomes: | |
| | letion of this course, the students will be able to: | |
| CO1 : | Measure current and voltage in AC and DC circuits | |
| CO2 : | : Measure Power and energy AC and DC circuits and magnetic measurements. | |
| CO3 : | : Calculate R,L,C using various bridges | |
| CO4 : | Measure non-electrical quantities | |
| CO5 : | Share knowledge on electrical instruments and measurements. | |
| CO6 : | : Teach the Instrumentation techniques and its applications. | |
| | | |

| Text Books: | |
|-------------|--|
| 1. | A.K. Sawhney, 'A Course in Electrical & Electronics Measurement & Instrumentation', Dhanpat Rai and Co, 2015 |
| 2. | E.O. Doebelin, 'Measurements Systems- Application and Design', Tata McGraw Hill publishing company, 2015. |

Reference Books:

| 1. | D.V.S. Moorthy, 'Transducers and Instrumentation', Prentice Hall of India Pvt. Ltd, 2010. |
|----|--|
| 2. | H.S. Kalsi, 'Electronic Instrumentation', Tata McGraw Hill, 2017,3rd edition. |
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| 2 | https://nptel.ac.in/courses/108106074/ |

| PO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 1 | 2 | | 2 | 1 | | 2 | 1 | 1 | | 1 | 1 |
| CO2 | 1 | 2 | | 2 | 1 | | 2 | 1 | 1 | | 1 | 1 |
| CO3 | 1 | 2 | | 2 | 1 | | 2 | 1 | 1 | | 1 | 1 |
| CO4 | 1 | 2 | | 2 | 1 | | 2 | 1 | 1 | | 1 | 1 |
| CO5 | 2 | 2 | 2 | 3 | 2 | 2 | 1 | 2 | 1 | 3 | 3 | 3 |
| CO6 | 2 | 2 | 2 | 3 | 2 | 2 | 1 | 2 | 1 | 3 | 3 | 3 |

| | ANALOG AND DIGITAL INTEGRATED CIRCUITS | | | Ρ | (|
|---|---|---------------------------------------|--|--------------------------------|-------------|
| | | 3 | 0 | 0 | |
| Course C | bjectives: | | | | |
| 1. | To study the characteristics and applications of Operation Amplifier. | | | | |
| 2. | To gain knowledge about functional diagram and applications of linear lcs | | | | |
| 3. | To simplify the switching functions. | | | | |
| 4. | To design combinational logic circuits. | | | | |
| 5. | To design of sequential logic circuits | | | | |
| | | | | | |
| Unit I | CHARACTERISTICS OF OP-AMP | | 9 | + | (|
| deal OP- | AMP: characteristics-Inverting and non-inverting amplifier- voltage follower - differe | ntial | am | plifie | r |
| | cteristics – AC characteristics. Basic applications: summer- multiplier- divider- di | | | | |
| | instrumentation amplifier – V/I and I/V converters | | | | |
| | | | | | |
| Jnit II | APPLICATIONS OP-AMP AND LINEAR Ics | | 9 | + | (|
| | ns of OP-AMP: comparators – multivibrators – Peak detector- Sample and Hold circ | cuit - | – firs | st an | d |
| | der low pass and high pass active filters. | | | | |
| | I block diagram and Applications of Linear Ics: IC 555 Timer – IC 566 Voltage control | led | osci | llato | • - |
| C 565 Pr | ase-locked loops – IC LM317 voltage regulators. | | | | |
| | | | | | |
| Jnit III | COMBINATIONAL LOGIC CIRCUITS | | 9 | + | |
| Represen | tation of logic functions: SOP and POS forms – Simplification of switching functions: | K-m | nap | meth | າດ |
| Decoder. | | | _ | | |
| | | | | | |
| lin flond | SYNCHRONOUS SEQUENTIAL LOGIC CIRCUITS | | 9 | + | |
| | SR, D, JK and T - Conversion of flip-flops; Classification of sequential circuits: Mo | | and | d Me | а |
| nodels – | SR, D, JK and T – Conversion of flip-flops; Classification of sequential circuits: Mo Analysis and design of synchronous sequential circuits – Design of synchronous coun | | and | d Me | а |
| nodels – | SR, D, JK and T – Conversion of flip-flops; Classification of sequential circuits: Mo Analysis and design of synchronous sequential circuits – Design of synchronous coun | | and | d Me | а |
| models – shift regis | SR, D, JK and T – Conversion of flip-flops; Classification of sequential circuits: Me Analysis and design of synchronous sequential circuits – Design of synchronous coun ter. | | and | d Me | |
| models – shift regis Unit V | SR, D, JK and T – Conversion of flip-flops; Classification of sequential circuits: Mo Analysis and design of synchronous sequential circuits – Design of synchronous coun ter. ASYNCHRONOUS SEQUENTIAL LOGIC CIRCUITS | ters | anc Ui 9 | i Me nivei | a s |
| models – shift regis Unit V fundamer | SR, D, JK and T – Conversion of flip-flops; Classification of sequential circuits: Mo Analysis and design of synchronous sequential circuits – Design of synchronous coun ter. ASYNCHRONOUS SEQUENTIAL LOGIC CIRCUITS tal mode and pulse mode circuits, Analysis procedure of asynchronous circuits with / | ters with | and | d Me niver + using | a |
| nodels – shift regis Jnit V undamer SR latche of asynch | SR, D, JK and T – Conversion of flip-flops; Classification of sequential circuits: Mo Analysis and design of synchronous sequential circuits – Design of synchronous coun ter. ASYNCHRONOUS SEQUENTIAL LOGIC CIRCUITS tal mode and pulse mode circuits , Analysis procedure of asynchronous circuits with / s- primitive state / flow table – Reduction of state and flow table – state assignment – De ronous circuits with /without using of SR latches – Problems in asynchronous sequences. | ters with esigr | and – Ur 9 out on Pro | d Me niver + using | a s |
| nodels – shift regis Jnit V undamer SR latche of asynch | SR, D, JK and T – Conversion of flip-flops; Classification of sequential circuits: Mo Analysis and design of synchronous sequential circuits – Design of synchronous coun ter. ASYNCHRONOUS SEQUENTIAL LOGIC CIRCUITS tal mode and pulse mode circuits , Analysis procedure of asynchronous circuits with / s- primitive state / flow table – Reduction of state and flow table – state assignment – Design of synchronous circuits and the sequence of table and flow table – State assignment – Design of table – State assignment – Design of synchronous circuits with / s- primitive state / flow table – Reduction of state and flow table – state assignment – Design of synchronous circuits (sequence circuits) | ters with esigr | and – Ur 9 out o | d Me niver + using | a s |
| nodels – shift regis Jnit V undamer SR latche of asynch | SR, D, JK and T – Conversion of flip-flops; Classification of sequential circuits: Mo Analysis and design of synchronous sequential circuits – Design of synchronous coun ter. ASYNCHRONOUS SEQUENTIAL LOGIC CIRCUITS Ital mode and pulse mode circuits, Analysis procedure of asynchronous circuits with / s- primitive state / flow table – Reduction of state and flow table – state assignment – De ronous circuits with /without using of SR latches – Problems in asynchronous seq Races – Hazards. | with esigr | and – Ur 9 out o Pro ial o | 4 Me niver using bced | a s u |
| nodels – shift regis Jnit V undamer SR latche of asynch cycles – F | SR, D, JK and T – Conversion of flip-flops; Classification of sequential circuits: Mo Analysis and design of synchronous sequential circuits – Design of synchronous coun ter. ASYNCHRONOUS SEQUENTIAL LOGIC CIRCUITS tal mode and pulse mode circuits, Analysis procedure of asynchronous circuits with / s- primitive state / flow table – Reduction of state and flow table – state assignment – De ronous circuits with /without using of SR latches – Problems in asynchronous seq eaces – Hazards. Total (L+T | with esigr | and – Ur 9 out o Pro ial o | 4 Me niver using bced | a |
| models – shift regis Unit V fundamer SR latche of asynch cycles – F Course C | SR, D, JK and T – Conversion of flip-flops; Classification of sequential circuits: Mo Analysis and design of synchronous sequential circuits – Design of synchronous coun ter. ASYNCHRONOUS SEQUENTIAL LOGIC CIRCUITS Ital mode and pulse mode circuits , Analysis procedure of asynchronous circuits with / s- primitive state / flow table – Reduction of state and flow table – state assignment – De ronous circuits with /without using of SR latches – Problems in asynchronous seq Races – Hazards. Total (L+T putcomes: | with esigr | and – Ur 9 out o Pro ial o | 4 Me niver using bced | a s u |
| models – shift regis Unit V fundamer SR latche of asynch cycles – F Course C At the end | SR, D, JK and T – Conversion of flip-flops; Classification of sequential circuits: Mo Analysis and design of synchronous sequential circuits – Design of synchronous coun ter. ASYNCHRONOUS SEQUENTIAL LOGIC CIRCUITS Ital mode and pulse mode circuits , Analysis procedure of asynchronous circuits with / s- primitive state / flow table – Reduction of state and flow table – state assignment – De ronous circuits with /without using of SR latches – Problems in asynchronous seq Races – Hazards. Total (L+T Putcomes: If of the course the student will be able to | with esigr | and – Ur 9 out o Pro ial o | 4 Me niver using bced | a s u |
| nodels – shift regis Jnit V undamer SR latche of asynch cycles – F Course C At the end CO1 | SR, D, JK and T – Conversion of flip-flops; Classification of sequential circuits: Mo Analysis and design of synchronous sequential circuits – Design of synchronous coun ter. ASYNCHRONOUS SEQUENTIAL LOGIC CIRCUITS tal mode and pulse mode circuits , Analysis procedure of asynchronous circuits with / s- primitive state / flow table – Reduction of state and flow table – state assignment – De ronous circuits with /without using of SR latches – Problems in asynchronous seq Races – Hazards. Total (L+T putcomes: I of the course the student will be able to Explain the OP-AMP characteristics | with esigr | and – Ur 9 out o Pro ial o | 4 Me niver using bced | a s u |
| nodels – shift regis Jnit V undamer SR latche of asynch cycles – F Course C At the end CO1 : CO2 : | SR, D, JK and T – Conversion of flip-flops; Classification of sequential circuits: Me Analysis and design of synchronous sequential circuits – Design of synchronous counter. ASYNCHRONOUS SEQUENTIAL LOGIC CIRCUITS tal mode and pulse mode circuits , Analysis procedure of asynchronous circuits with / s- primitive state / flow table – Reduction of state and flow table – state assignment – De ronous circuits with /without using of SR latches – Problems in asynchronous sequences – Hazards. Total (L+T utcomes: I of the course the student will be able to Explain the OP-AMP characteristics Understand the applications of OP-AMP and other linear lcs. | with esigr | and – Ur 9 out o Pro ial o | 4 Me niver using bced | a s u |
| nodels – shift regis Jnit V undamer SR latche of asynch cycles – F Course C At the end CO1 : CO2 : CO3 : | SR, D, JK and T – Conversion of flip-flops; Classification of sequential circuits: Me Analysis and design of synchronous sequential circuits – Design of synchronous counter. ASYNCHRONOUS SEQUENTIAL LOGIC CIRCUITS tal mode and pulse mode circuits , Analysis procedure of asynchronous circuits with / s- primitive state / flow table – Reduction of state and flow table – state assignment – De ronous circuits with /without using of SR latches – Problems in asynchronous sequences – Hazards. Total (L+T utcomes: I of the course the student will be able to Explain the OP-AMP characteristics Understand the applications of OP-AMP and other linear lcs. Utilize K-map and Tabulation methods to simplify the switching functions | with esigr | and – Ur 9 out o Pro ial o | 4 Me niver using bced | a s u |
| models – shift regis undamer SR latche of asynch cycles – F Course C At the end CO1 : CO2 : CO3 : CO3 : | SR, D, JK and T – Conversion of flip-flops; Classification of sequential circuits: Me Analysis and design of synchronous sequential circuits – Design of synchronous counter. ASYNCHRONOUS SEQUENTIAL LOGIC CIRCUITS tal mode and pulse mode circuits , Analysis procedure of asynchronous circuits with / s- primitive state / flow table – Reduction of state and flow table – state assignment – De ronous circuits with /without using of SR latches – Problems in asynchronous seq Races – Hazards. Total (L+T utcomes: I of the course the student will be able to Explain the OP-AMP characteristics Understand the applications of OP-AMP and other linear lcs. Utilize K-map and Tabulation methods to simplify the switching functions Design and implement of combinational logic circuits | with esigr | and – Ur 9 out o Pro ial o | 4 Me niver using bced | a s u |
| models – shift regis Unit V undamer SR latche of asynch cycles – F Course C Course C At the end CO1 : CO2 : CO3 : CO4 : CO5 : | SR, D, JK and T – Conversion of flip-flops; Classification of sequential circuits: Modeling Analysis and design of synchronous sequential circuits – Design of synchronous counter. ASYNCHRONOUS SEQUENTIAL LOGIC CIRCUITS tal mode and pulse mode circuits , Analysis procedure of asynchronous circuits with / s- primitive state / flow table – Reduction of state and flow table – state assignment – De ronous circuits with /without using of SR latches – Problems in asynchronous sequences – Hazards. Total (L+T Interview of the course the student will be able to Explain the OP-AMP characteristics Understand the applications of OP-AMP and other linear lcs. Utilize K-map and Tabulation methods to simplify the switching functions Design and implement of combinational logic circuits | with esigr | and – Ur 9 out o Pro ial o | 4 Me niver using bced | a |
| nodels – shift regis Jnit V undamer SR latche of asynch cycles – F Course C Course C C Course C C Course C C Course C C C Course C C C Course C C C C C C C C C C C C C C C C C C C | SR, D, JK and T – Conversion of flip-flops; Classification of sequential circuits: Me Analysis and design of synchronous sequential circuits – Design of synchronous counter. ASYNCHRONOUS SEQUENTIAL LOGIC CIRCUITS tal mode and pulse mode circuits , Analysis procedure of asynchronous circuits with / s- primitive state / flow table – Reduction of state and flow table – state assignment – De ronous circuits with /without using of SR latches – Problems in asynchronous seq Races – Hazards. Total (L+T utcomes: I of the course the student will be able to Explain the OP-AMP characteristics Understand the applications of OP-AMP and other linear lcs. Utilize K-map and Tabulation methods to simplify the switching functions Design and implement of combinational logic circuits | with esigr | and – Ur 9 out o Pro ial o | 4 Me niver using bced | a s u |
| models – shift regis unit V fundamer SR latche of asynch cycles – F Course C At the end CO1 : CO2 : CO3 : CO4 : CO5 : | SR, D, JK and T – Conversion of flip-flops; Classification of sequential circuits: Mc Analysis and design of synchronous sequential circuits – Design of synchronous counter. ASYNCHRONOUS SEQUENTIAL LOGIC CIRCUITS Ital mode and pulse mode circuits , Analysis procedure of asynchronous circuits with / s- primitive state / flow table – Reduction of state and flow table – state assignment – De ronous circuits with /without using of SR latches – Problems in asynchronous sequences – Hazards. Total (L+T utcomes: I of the course the student will be able to Explain the OP-AMP characteristics Understand the applications of OP-AMP and other linear lcs. Utilize K-map and Tabulation methods to simplify the switching functions Design and implement of combinational logic circuits Analysis and design of synchronous sequential logic circuits Analysis and design of asynchronous sequential logic circuits | with esigr | and – Ur 9 out o Pro ial o | 4 Me niver using bced | a |
| nodels – shift regis Jnit V undamer SR latche of asynch cycles – F Course C At the end CO1 CO2 CO3 CO4 CO5 CO6 Image: Construction of the second se | SR, D, JK and T – Conversion of flip-flops; Classification of sequential circuits: Me Analysis and design of synchronous sequential circuits – Design of synchronous counter. ASYNCHRONOUS SEQUENTIAL LOGIC CIRCUITS tal mode and pulse mode circuits , Analysis procedure of asynchronous circuits with / s- primitive state / flow table – Reduction of state and flow table – state assignment – De ronous circuits with /without using of SR latches – Problems in asynchronous seq acces – Hazards. Total (L+T tutcomes: I of the course the student will be able to Explain the OP-AMP characteristics Understand the applications of OP-AMP and other linear lcs. Utilize K-map and Tabulation methods to simplify the switching functions Design and implement of combinational logic circuits Analysis and design of synchronous sequential logic circuits Analysis and design of asynchronous sequential logic circuits | ters with esigr uent | anc – Ui 9 00ut i Pro ial c | + usinq bircu | |
| models – shift regis unit V fundamer SR latche of asynch cycles – F Course C At the end CO1 : CO2 : CO3 : CO3 : CO4 : CO5 : CO6 : Text Boo | SR, D, JK and T – Conversion of flip-flops; Classification of sequential circuits: Mc Analysis and design of synchronous sequential circuits – Design of synchronous counter. ASYNCHRONOUS SEQUENTIAL LOGIC CIRCUITS Ital mode and pulse mode circuits , Analysis procedure of asynchronous circuits with / s- primitive state / flow table – Reduction of state and flow table – state assignment – De ronous circuits with /without using of SR latches – Problems in asynchronous seq Races – Hazards. Total (L+T Utilize K-map and Tabulation methods to simplify the switching functions Design and implement of combinational logic circuits Analysis and design of synchronous sequential logic circuits Analysis and design of asynchronous sequential logic circuits | ters with esigr uent ()=4 | anc – Ui 9 out o Pro ial c 5/0 F | + using poced bircu | |

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| Referer | nce Books: |
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| 2 | Jacob Millman, Christos C.Halkias, "Integrated Electronics- Analog and Digital circuits system", Tata McGraw Hill 2003. |
| 3 | R.P.Jain, "Modern Digital Electronics", Third Edition, Tata McGraw–Hill Publishing company limited, New Delhi, 2011. |
| 4. | Thomas L. Floyd, "Digital Fundamentals", Pearson Education, Inc, New Delhi, 2015 |
| 5. | Donald P.Leach and Albert Paul Malvino, "Digital Principles and Applications", Fifth Edition, Tata McGraw Hill Publishing Company Limited, New Delhi, 2012. |
| E-Refer | ence |
| 1 | NPTEL courses on Analog Integrated Circuits, IIT Madras- web: http://nptel.ac.in/courses/108106068/ |
| 2 | NPTEL courses on Analog Circuits, IIT Bombay https://nptel.ac.in/courses/108/101/108101094/ |
| 3 | NPTEL courses on Digital Electronic Circuits, IIT Kharagpur. Web:https://nptel.ac.in/courses/108/105/108105132/ |
| 4 | NPTEL courses on Digital Circuits, IIT Kharagpur. Web: https://nptel.ac.in/courses/108/105/108105113/ |
| 1 | |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 2 | 1 | | | | | | | | | | |
| CO2 | 3 | 2 | 1 | 1 | | | | | | | | |
| CO3 | 3 | 2 | | | 2 | | | | | | | |
| CO4 | 3 | 2 | | | 2 | | | | | | | |
| CO5 | 3 | 2 | | | 2 | | | | | | | |
| CO6 | 3 | 2 | | | 2 | | | | | | | |

| 18ME408 | ENGINEERING MECHANICS | L | Т | Ρ | С |
|-----------------------|--|---------|---|--------|--------------|
| | | 2 | 1 | 0 | 3 |
| Course (| Objectives: | | | | |
| 1. | To develop capacity to predict the effect of force and motion in the course of carryin functions of engineering. | ng ou | it the | des | ign |
| 2. | To analyze the force systems, friction and to study the dynamics of particles, impul momentum. | se ar | nd | | |
| UNIT I | STATICS OF PARTICLES | | 6 | + | 3 |
| forces – product - | on – Units and Dimensions – Laws of Mechanics – Lami's theorem, Parallelogram ar /ectorial representation of forces – Vector operations of forces -additions, subtraction Coplanar Forces – rectangular components – Equilibrium of a particle – Forces in spa in space – Equivalent systems of forces – Principle of transmissibility. | dot | proc | luct, | cross |
| UNIT II | EQUILIBRIUM OF RIGID BODIES | | 6 | + | 3 |
| Couples Scalar co | y diagram – Types of supports and their reactions – requirements of stable equilibriu - Moment of a force about a point and about an axis – Vectorial representation of mom mponents of a moment – Varignon's theorem – Equilibrium of Rigid bodies in two dimer odies in three dimensions – Examples | ents | and | coup | oles – |
| | PROPERTIES OF SURFACES AND SOLIDS | | 6 | + | 3 |
| Area mo | of simple figures from first principle, centroid of composite sections; Centre of Gravity a nent of inertia- Definition, Moment of inertia of plane sections from first principles, The Moment of inertia of standard sections and composite sections. | | | | |
| UNIT IV | FRICTION | | 6 | + | 3 |
| | friction, Limiting friction, Laws of Friction, Static and Dynamic Friction; Motion of Bodie k & differential screw jack. | s, we | dge | fricti | on, |
| UNIT V | KINETICS OF PARTICLES AND RIGID BODIES | | 6 | | 3 |
| Equation equation | s of motion- Rectilinear motion-curvilinear motion- Relative motion- D'Alembert's Princi Conservative forces and principle of conservation of energy-Impulse- momentum- Imp d oblique central impact. Plane motion- Absolute motion- Relative motion- work and en | act- | /ork- Dire | ct ce | rgy ntral |
| | Total (3 |)+15 |) = 4 | 5 Pe | riods |
| Course (| Outcomes: | | <u>, </u> | | |
| Upon cor | pletion of this course, the students will be able to: | | | | |
| CO1 | : Illustrate the vectorial and scalar representation of forces and moments | | | | |
| CO2 | : Analyze the rigid body in equilibrium | | | | |
| CO3 | : Evaluate the properties of surfaces and solids | | | | |
| CO4 | : Determine the friction and the effects by the laws of friction | | | | |
| CO5 | Apply fundamental concepts of kinematics and kinetics of particles to the analysis of problems | of sin | nple, | prac | tical |
| Text Bo | oks: | | | | |
| 1. | A Textbook of Engineering Mechanics, R.K. Bansal, Laxmi Publications, 2015,5t ec | lition. | | | |
| 2. | Engineering Mechanics, R.S. Khurmi, S.Chand Publishing, 2018. | | | | |
| Referer | ce Books: | | | | |
| 1. | Engineering Mechanics, D.S. Bedi, Khanna Book Publishing Co. (P) Ltd. | | | | |
| | Rajasekaran S and Sankarasubramanian G., "Fundamentals of Engineering Mecha | anics | ", Vi | kas | |
| 2. | Publishing House Pvt. Ltd., 2017, 3 rd edition. | | | | |

| 4. | Engineering Mechanics, DP Sharma, Pearson, 2010. |
|------------|---|
| 5. | F. P. Beer and E. R. Johnston, Vector Mechanics for Engineers, Vol I – Statics, Vol II, – |
| 0. | Dynamics, 12 th Ed, Tata McGraw Hill, 2019. |
| | |
| E-Referenc | ce |
| 1 | www.onlinecourses.nptel.ac.in |
| 2 | www.class-central.com |
| 3 | www.mooc-list.com |

| PO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 3 | 2 | 1 | 1 | 1 | | | | | 2 | | |
| CO2 | 2 | 1 | 1 | 0 | 1 | | | | | 2 | | |
| CO3 | 2 | 1 | 1 | 0 | 0 | | | | | | | |
| CO4 | 1 | 1 | 1 | 1 | 0 | | | | | | | |
| CO5 | 2 | 2 | 1 | 1 | 0 | | | | | | | |

| 18EE40 | 5 SYNCHRONOUS AND INDUCTION MACHINES LABORATORY | L | Т | Ρ | С |
|--------|--|----------|--------------|--------|----------|
| | | 0 | 0 | 3 | 1.5 |
| | | | | | |
| Course | Objectives: | | | | |
| 1 | To expose the students to operate of synchronous machines and induction r | notors | and | streng | yth thei |
| I | experimental skill. | | | | |
| xperim | ents: | | | | |
| 1 | Predetermination of Voltage Regulation of three-phase alternator by EMF and | d MMF | me | hods. | |
| 2 | Predetermination of Voltage Regulation of three-phase alternator by ZPF me | | | | |
| 3 | Slip test on three-phase salient pole alternator. | | | | |
| 4 | V and inverted V curves of synchronous motors | | | | |
| 5 | Load test on three-phase induction motor. | | | | |
| 6 | Circle diagram for three phase induction motor with No load and blocked roto | r test o | data. | | |
| 7 | Three Phase Induction Generator action with self-excitation. | | | | |
| 8 | Synchronization of three-phase alternator | | | | |
| 9 | Separation of losses in three phase induction motor. | | | | |
| 10 | Load test on single-phase induction motor. | | | | |
| 11 | Equivalent circuit and pre-determination of performance characteristics of | f singl | e-ph | ase ir | ductio |
| | motor. | - | • | | |
| 12 | Separation of losses in single phase transformer using alternator | | | | |
| | | | | | |
| | | Tota | (0+ 4 | 5)= 45 | 5Perio |
| ourse | Outcomes: | | | | |
| | mpletion of this course, the students will be able to: | | | | |
| CO1 | : Analyze the voltage regulation of a given alternator using different methodolo | <u> </u> | | | |
| CO2 | Analyze the performance of a given synchronous motor under various excita | tion | | | |
| | Conditions | | | | |
| CO3 | : Analyze the characteristics of a induction motor under various load conditions | 6 | | | |
| CO4 | : Analyze the load sharing capability of given alternators | | | | |
| CO5 | : Develop the equivalent circuit and analyze the characteristics of single-phase | induc | tion | motor | |
| CO6 | : Do loss analysis in AC machines. | | | | |

| PO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | | 2 | | | 1 | | 2 | | | | 2 | |
| CO2 | | 2 | | | 2 | | | | | | | 1 |
| CO3 | 3 | | | 2 | | | | | | | 1 | |
| CO4 | 2 | | | | 3 | | 2 | | 2 | | | |
| CO5 | | | | 1 | 1 | | | | | 2 | | 2 |
| CO6 | | 2 | 2 | 3 | | | | | | | 2 | |

| 18EE406 | MEASUREMENTS AND INSTRUMENTATION LABORATORY | L | Τ | Ρ | С |
|-----------|--|--------|-----|-------|---------|
| | | 0 | 0 | 3 | 1.5 |
| Course Ol | ojectives: | | | | |
| 1. | To study the use of Transducer. | | | | |
| 2. | To measure the resistance, capacitance and inductance using bridges. | | | | |
| 3. | To calibrate voltage and current using measuring equipment. | | | | |
| 4. | To calibrate the efficiency of PV modules. | | | | |
| Experime | nts: | | | | |
| 1 | Measurement of displacement using transducers. | | | | |
| 2 | Measurement of pressure using transducers. | | | | |
| 3 | Measurement of inductance by Maxwell's bridge. | | | | |
| 4 | Measurement of inductance by Anderson's bridge | | | | |
| 5 | Measurement of resistance by Wheatstone bridge. | | | | |
| 6 | Measurement of capacitance, Inductance by schering bridge. | | | | |
| 7 | Study of Instrumentation amplifiers. | | | | |
| 8 | A/D converters. | | | | |
| 9 | D/A converters. | | | | |
| 10 | Study of transients. | | | | |
| 11 | Calibration of single phase and three phase energy meter. | | | | |
| 12 | Calibration of AC, DC voltmeter and Ammeter. | | | | |
| 13 | Calibration of current transformer and potential transformer. | | | | |
| 14 | Measurement of three phase power and power factor. | | | | |
| 15 | Calibration and Voltage – Current Measurement of solar light. | | | | |
| 16 | Study of PLC. | | | | |
| 17 | Calibration of series and parallel connection of PV modules. | | | | |
| 18 | Calculation of efficiency for PV system modules, Battery and Inverter. | | | | |
| | | 2Total | 0+4 | 5)= 4 | 5Period |
| Course O | | | | | |
| | pletion of this course, the students will be able to: | | | | |
| CO1 : | Explain analog instruments. | | | | |
| CO2 : | Measure power in AC and DC circuits | | | | |
| CO3 : | Calculate R,L,C using various bridges. | | | | |
| CO4 : | Know about basic of PLC. | | | | |
| CO5 : | Measure the efficiency of PV modules | | | | |
| CO6 : | Calibrate ammeter, voltmeter, energy meter and transformers. | | | | |

| RO CO | PO1 | PO2 | PO3 | PO 4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO 10 | PO 11 | PO 12 |
|----------|-----|-----|-----|---------|-----|-----|-----|-----|-----|----------|----------|----------|
| CO1 | 1 | 2 | | 2 | 1 | | 2 | 1 | 1 | | 1 | 1 |
| CO2 | 1 | 2 | | 2 | 2 | | 2 | 1 | 1 | | 2 | 1 |
| CO3 | 1 | 2 | | 2 | 1 | | 2 | 2 | 1 | | 1 | 1 |
| CO4 | 1 | 2 | | 2 | 1 | | 2 | 1 | 1 | | 1 | 1 |
| CO5 | 1 | 2 | | 2 | 1 | | 2 | 1 | 2 | | 1 | 1 |
| CO6 | 1 | 3 | | 3 | 1 | | 3 | 1 | 1 | | 1 | 1 |

| 18EE407 | ANALOG AND DIGITAL INTEGRATED CIRCUITS LABORA | TORY | L | Т | Ρ | С |
|-------------|--|---------------|-------|----------|---------------------|--------|
| | | | 0 | 0 | 3 | 1.5 |
| Course Obj | jectives: | | | | | |
| 1. | To Expose the characteristics and applications of Linear Ics. | | | | | |
| 2. | To study various digital electronics circuits used in simple system | configurati | on | | | |
| list of Exp | eriments: (Any 10 Experiments) | | | | | |
| <u>1</u> | Verification of IC 741 characteristics: inverting and non-inverting | amplifier _ ' | volta | nde fo | llower | , |
| 2 | Verification of IC 741 Applications circuits: summer, differentiator | | | ige io | 10000 | • |
| 3 | Design of zero crossing detector and Schmitt trigger circuit using | | | | | |
| 4 | Design and testing of first order Low Pass and High Pass Active | | | | | |
| 5 | Design of Wien bridge oscillator and RC phase shift oscillator usi | | 5 | | | |
| 6 | Design of astable and monostable multivibrator circuits using NE, | | | | | |
| 7 | Design of Voltage controlled oscillator using NE/SE 566. | | | | | |
| 8 | Design of Voltage regulator using IC723. | | | | | |
| 9 | Design of +5V, 1A regulated Power supply using IC 7805. | | | | | |
| 10 | Design of variable power supply using IC LM317. | | | | | |
| 11 | Design of dual power supply using LM 320 / LM340. | | | | | |
| 12 | Realize the switching functions using minimum number of NAND | NOR gate | s. | | | |
| 13 | Design of code converter circuits. | , i e i gale | • | | | |
| 14 | Study of different types of Flip-Flops. | | | | | |
| 15 | Design of 3-bit synchronous counters. | | | | | |
| 16 | Implementation of multipliexers and demultiplexers - encoders a | nd decoder: | s | | | |
| 17 | Design of 4-Bit shift registers using flip-flop. | | | | | |
| 18 | Testing of asynchronous counters using flip-flops. | | | | | |
| | | | | _ | - | |
| Course Out | romos: | T | otal | (0+45 | 5)= 45 | Period |
| | letion of this course, the students will be able to: | | | | | |
| CO1 | : Study the characteristics and mathematical applications of op |)-amp | | | | |
| CO2 | : Design and verify waveform generator circuits and filter circuit | | -ami | <u>)</u> | | |
| CO3 | : Design voltage regulator and power supply circuits using Line | | ang | | | |
| CO4 | Realize the switching function using universal gates. | ui 100. | | | | |
| CO4 CO5 | : Realize the various types of combinational logic circuits | | | | | |
| CO6 | : Implement the various types of sequential logic circuits | | | | | |
| 000 | | | | | | |
| Reference | | | | | | |
| 1. | Department Integrated Circuits Laboratory Manual | | | | | |
| 2. | Roy Choudhury. D and Shail. B. Jain, "Linear Integrated Circuits" Edition, 2011. | , New Age | Inter | natio | nal 4 th | |

3 Gayakwad. R.A, "Op-amps & Linear Integrated Circuits", Pearson education, 4th Edition, 2015

| 00/1 0 map | · · · · · · · · · · · · · · · · · · · | | | | | | | | | | | |
|------------|---------------------------------------|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
| CO1 | | | 3 | 3 | 2 | | 1 | | 3 | | | |
| CO2 | | | 3 | 3 | 2 | | 1 | | 3 | | | |
| CO3 | | | 3 | 3 | 2 | | 1 | | 3 | | | |
| CO4 | | | 3 | 3 | 2 | | 1 | | 3 | | | |
| CO5 | | | 3 | 3 | 2 | | 1 | | 3 | | | |
| CO6 | | | 3 | 3 | 2 | | 1 | | 3 | | | |

| 18MC301 | INDIAN CONSTITUTION | L | Т | Ρ | С |
|--|--|--------|-------------------------|-------------------|---------|
| | | 1 | 0 | 0 | 0 |
| Course Ob | jectives: | | | | |
| 1. | Learn the salient features of the Indian Constitution | | | | |
| 2. | List the fundamental rights and fundamental duties | | | | |
| 3. | Present a systematic analysis of all dimensions of the Indian political Systems | | | | |
| 4. | Understand the power functions of Parliament, the legislature and Judiciary. | | | | |
| Unit I | | | 3 | + | 0 |
| | ts Territory – Citizenship – Fundamental Rights – Directive Principles of State Policy | / – Fi | Inda | mer | ta |
| Duties. | | | | | |
| Unit II | | | 3 | + | 0 |
| The Union - | The States – The Union Territories – The Panchayats – the Municipalities | | | | |
| Unit III | | | 3 | + | 0 |
| | Perative Societies – The Scheduled and Tribal Areas – Relations between the Union a | and t | | tate | ' |
| | | | | laie | |
| | | | | | 5 |
| | operty, Contracts and Suits – Trade and Commerce within the territory of India. | | | | |
| | | | 3 | + | |
| Finance, Pr | operty, Contracts and Suits – Trade and Commerce within the territory of India. | | 3 | | |
| Finance, Pr | | | 3 | | 0 |
| Finance, Pr | operty, Contracts and Suits – Trade and Commerce within the territory of India. | | 3 | | C |
| Finance, Pr Unit IV Service und Unit V | operty, Contracts and Suits – Trade and Commerce within the territory of India. | | 3 class | es. | C |
| Finance, Pr Unit IV Service und Unit V | operty, Contracts and Suits – Trade and Commerce within the territory of India. | | 3 class | es. | 0 |
| Finance, Pr Unit IV Service und Unit V Languages | operty, Contracts and Suits – Trade and Commerce within the territory of India. | tain c | 3 class 2 | es. + | (|
| Finance, Pr Unit IV Service und Unit V | operty, Contracts and Suits – Trade and Commerce within the territory of India. | tain c | 3 class 2 | es. + | 0 |
| Finance, Pr Unit IV Service und Unit V Languages Course Our | operty, Contracts and Suits – Trade and Commerce within the territory of India. | tain c | 3 class 2 | es. + | (|
| Finance, Pr Unit IV Service und Unit V Languages Course Our | toperty, Contracts and Suits – Trade and Commerce within the territory of India. der the Union, the States – Tribunals –Elections –Special provisions –Relating to cer - Emergency provisions –Miscellaneous – Amendment of the Constitution. Total (14 tcomes: letion of this course, the students will be able to: | tain c | 3 class 2 | es. + | (|
| Finance, Pr Unit IV Service und Unit V Languages Course Our Upon comp | Trade and Commerce within the territory of India. der the Union, the States – Tribunals –Elections –Special provisions –Relating to cer - Emergency provisions –Miscellaneous – Amendment of the Constitution. Total (14 tcomes: letion of this course, the students will be able to: Understand the emergence and evolution of the Indian Constitution. | tain c | 3 class 2 | es. + | (|
| Finance, Pr Unit IV Service und Unit V Languages Course Our Upon comp CO1 | toperty, Contracts and Suits – Trade and Commerce within the territory of India. der the Union, the States – Tribunals –Elections –Special provisions –Relating to cer - Emergency provisions –Miscellaneous – Amendment of the Constitution. Total (14 tcomes: letion of this course, the students will be able to: | tain c | 3 class 2 | es. + | (|
| Finance, Pr Unit IV Service und Unit V Languages Course Our Upon comp CO1 CO2 | operty, Contracts and Suits – Trade and Commerce within the territory of India. der the Union, the States – Tribunals –Elections –Special provisions –Relating to cer - Emergency provisions –Miscellaneous – Amendment of the Constitution. • Emergency provisions –Miscellaneous – Amendment of the Constitution. • Emergency provisions –Miscellaneous – Amendment of the Constitution. • Emergency provisions –Miscellaneous – Amendment of the Constitution. • Emergency provisions –Miscellaneous – Amendment of the Constitution. • Emergency provisions –Miscellaneous – Amendment of the Constitution. • Understand the students will be able to: • Understand the emergence and evolution of the Indian Constitution. • Explain the key concepts of Indian Political System • Describe the role of Constitution in a democratic society | tain (| 3 Class 2 14 F | es. + Peric | |
| Finance, Pr Unit IV Service und Unit V Languages Course Our Upon comp CO1 CO2 CO3 | operty, Contracts and Suits – Trade and Commerce within the territory of India. der the Union, the States – Tribunals –Elections –Special provisions –Relating to cer - Emergency provisions –Miscellaneous – Amendment of the Constitution. • Emergency provisions –Miscellaneous – Amendment of the Constitution. • Emergency provisions –Miscellaneous – Amendment of the Constitution. • Emergency provisions –Miscellaneous – Amendment of the Constitution. • Emergency provisions –Miscellaneous – Amendment of the Constitution. • Emergency provisions –Miscellaneous – Amendment of the Constitution. • Emergency provisions –Miscellaneous – Amendment of the Constitution. • Understand the emergence and evolution of the Indian Constitution. • Understand the emergence and evolution of the Indian Constitution. • Explain the key concepts of Indian Political System • Describe the role of Constitution in a democratic society • Present the structure and functions of the central and state Governments, the laboration of the central and state Governmentaneous detent of the central and state Governments, the | tain (| 3 Class 2 14 F | es. + Peric | (od |
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| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
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| CO3 | | | | | | | | | 1 | 1 | | 1 |
| CO4 | | | | | | | | | 1 | 1 | | 1 |

| | 01 POWER GENERATION, TRANSMISSION AND DISTRIBUTION SYSTEM | 3 | 0 | 0 | |
|--|--|------------------------------------|---|--|---|
| 0 | Objectioner | 3 | 0 | U | с.) |
| Jourse | Objectives: | | | | |
| 1. | To study the characteristics of load curve, power tariff methods and the various po systems. | | 0 | | Ũ |
| 2. | To become familiar with the different components used in Transmission and Distrit power systems and modeling of these components | outio | on le | vels | of |
| Unit I | POWER GENERATION SYSTEMS | | 9 | + | (|
| load du | e of electric power system: Various levels such as generation, transmission and distrib ration curve - tariff- types of tariff- Power generating Station: layout- selection of site of Th ectric power plant and Nuclear power plants - major power stations in India. | | | | |
| Unit II | TRANSMISSION LINE PARAMETERS | | 9 | – | 0 |
| | sistance- Inductance and capacitance calculations of single phase and 3- phase trans | mic | <u> </u> | Tino | - |
| single a | and proximity effects-Inductive interference between power and communication lines. | | | | |
| Unit III | MODELING AND PERFORMANCE OF TRANSMISSION LINES | | 9 | + | 0 |
| | entation of Lines-Performance of Short line, medium line and long line; equivalent | | | | |
| | ns, transmission efficiency and voltage regulation and ABCD constants-surge-impedanc | e lo | adin | g-pc | wer |
| transmi | ssion capability-Ferranti effect and corona loss. | | | | |
| | | | | | |
| | OVERHEAD LINE INS ULATORS AND CABLES | | 9 | + | 0 |
| Insulato Underg | OVERHEAD LINE INS | nd 3 | ng e - coi | e ca | ncy. bles |
| Underg | OVERHEAD LINE INS ULATORS AND CABLES ors: Types, Potential distribution over a string of suspension insulators- improvement of round cables: Constructional features of LT and HT cables, capacitance of single core ar c stress in a single core cable- grading of cables, thermal resistance of dielectric of a sir | nd 3 | ng e - coi | e ca | ncy. bles |
| Insulato Underg dielectri Unit V Substat Underg | OVERHEAD LINE INS ULATORS AND CABLES ors: Types, Potential distribution over a string of suspension insulators- improvement of round cables: Constructional features of LT and HT cables, capacitance of single core ar | nd 3 ngle grou | ng e - cor core 9 ndee | re ca e cat + d sys | ncy bles ble. 0 |
| Insulato Underg dielectri Unit V Substat Underg | OVERHEAD LINE INS ULATORS AND CABLES ors: Types, Potential distribution over a string of suspension insulators- improvement of round cables: Constructional features of LT and HT cables, capacitance of single core ar c stress in a single core cable- grading of cables, thermal resistance of dielectric of a sir SUBSTATION, GROUNDING SYSTEM AND DISTRIBUTION SYSTEM ion: Classification-bus-bar arrangements in sub stations- Neutral grounding: Effectively ground system –Resonant grounding- Methods of neutral grounding-Distribution system: | nd 3 ngle grou Rac | ng e - cor core 9 ndee lial a | e cat e cat + d sys and r | ncy bles ble. |
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| Insulato Underg dielectri Unit V Substat Underg main dis Course | OVERHEAD LINE INS ULATORS AND CABLES ors: Types, Potential distribution over a string of suspension insulators- improvement of round cables: Constructional features of LT and HT cables, capacitance of single core ar c stress in a single core cable- grading of cables, thermal resistance of dielectric of a sir SUBSTATION, GROUNDING SYSTEM AND DISTRIBUTION SYSTEM ion: Classification-bus-bar arrangements in sub stations- Neutral grounding: Effectively ground system –Resonant grounding- Methods of neutral grounding-Distribution system: stribution systems-Methods of solving AC distributed problems. Total (4 Outcomes: ompletion of this course, the students will be able to: | nd 3 ngle grou Rac 5+0 | ng e - cor cord 9 nded ial a | re ca e cat + d sys and r i5 P | ncy bles ble. 0 sterr ing- erio |
| Insulato Underg dielectri Unit V Substat Underg main dis Course Upon co CO1 | OVERHEAD LINE INS ULATORS AND CABLES ors: Types, Potential distribution over a string of suspension insulators- improvement of round cables: Constructional features of LT and HT cables, capacitance of single core ar c stress in a single core cable- grading of cables, thermal resistance of dielectric of a sir SUBSTATION, GROUNDING SYSTEM AND DISTRIBUTION SYSTEM ion: Classification-bus-bar arrangements in sub stations- Neutral grounding: Effectively g round system –Resonant grounding- Methods of neutral grounding-Distribution system: stribution systems-Methods of solving AC distributed problems. Total (4 Outcomes: ompletion of this course, the students will be able to: Design the layout of various types of power generating systems such as thermal, H diesel and MHD. | nd 3 ngle grou Rac 5+0 | ng e - cor cord 9 nded ial a | re ca e cat + d sys and r i5 P | ncy ble: ble. ble. 0 stem ing- erio |
| Insulato Underg dielectri Unit V Substat Underg main dis Course Upon co CO1 CO2 | OVERHEAD LINE INS ULATORS AND CABLES ors: Types, Potential distribution over a string of suspension insulators- improvement of round cables: Constructional features of LT and HT cables, capacitance of single core ar c stress in a single core cable- grading of cables, thermal resistance of dielectric of a sir SUBSTATION, GROUNDING SYSTEM AND DISTRIBUTION SYSTEM ion: Classification-bus-bar arrangements in sub stations- Neutral grounding: Effectively g round system –Resonant grounding- Methods of neutral grounding-Distribution system: stribution systems-Methods of solving AC distributed problems. Total (4 Outcomes: ompletion of this course, the students will be able to: . Design the layout of various types of power generating systems such as thermal, H diesel and MHD. . Develop expression for computation of fundamental parameters off lines. | nd 3 ngle grou Rac 5+0 | ng e - cor cord 9 nded ial a | re ca e cat + d sys and r i5 P | ncy ble: ble. ble. 0 stem ing- erio |
| Insulato Underg dielectri Underg main dia Course Upon co CO1 CO2 CO3 | OVERHEAD LINE INS ULATORS AND CABLES orrs: Types, Potential distribution over a string of suspension insulators- improvement of round cables: Constructional features of LT and HT cables, capacitance of single core ar c stress in a single core cable- grading of cables, thermal resistance of dielectric of a sir SUBSTATION, GROUNDING SYSTEM AND DISTRIBUTION SYSTEM ion: Classification-bus-bar arrangements in sub stations- Neutral grounding: Effectively ground system –Resonant grounding- Methods of neutral grounding-Distribution system: stribution systems-Methods of solving AC distributed problems. Total (4 Outcomes: ompletion of this course, the students will be able to: . . Design the layout of various types of power generating systems such as thermal, H diesel and MHD. < | nd 3 ngle grou Rac 5+0 | ng e - cor 9 ndee lial a) = 4 | te cal e cal t syse and r | ncy bles ole. 0 stem ing- erio |
| Insulato Underg dielectri Substat Underg main dia Course Upon co CO1 CO2 CO3 CO4 | OVERHEAD LINE INS ULATORS AND CABLES orrs: Types, Potential distribution over a string of suspension insulators- improvement of round cables: Constructional features of LT and HT cables, capacitance of single core ar c stress in a single core cable- grading of cables, thermal resistance of dielectric of a sir SUBSTATION, GROUNDING SYSTEM AND DISTRIBUTION SYSTEM ion: Classification-bus-bar arrangements in sub stations- Neutral grounding: Effectively ground system –Resonant grounding- Methods of neutral grounding-Distribution system: stribution systems-Methods of solving AC distributed problems. Total (4 Outcomes: ompletion of this course, the students will be able to: . Design the layout of various types of power generating systems such as thermal, H diesel and MHD. . Develop expression for computation of fundamental parameters off lines. . Categorize the lines into different classes and develop equivalent circuits. . Analyze the voltage distribution in insulator strings and cables and methods to impro- | nd 3 ngle grou Rac 5+0 | ng e - cor 9 ndee lial a) = 4 | te cal e cal t syse and r | ncy bles ole. 0 stem ing- erio |
| Insulato Underg dielectri Substat Underg main dis Course Upon co CO1 CO2 CO3 CO4 CO5 | OVERHEAD LINE INS ULATORS AND CABLES ors: Types, Potential distribution over a string of suspension insulators- improvement of round cables: Constructional features of LT and HT cables, capacitance of single core ar c stress in a single core cable- grading of cables, thermal resistance of dielectric of a sir SUBSTATION, GROUNDING SYSTEM AND DISTRIBUTION SYSTEM ion: Classification-bus-bar arrangements in sub stations- Neutral grounding: Effectively g round system –Resonant grounding- Methods of neutral grounding-Distribution system: stribution systems-Methods of solving AC distributed problems. Total (4 Outcomes: Design the layout of various types of power generating systems such as thermal, H diesel and MHD. Develop expression for computation of fundamental parameters off lines. Categorize the lines into different classes and develop equivalent circuits. Analyze the voltage distribution in insulator strings and cables and methods to imprint | nd 3 ngle grou Rac 5+0 | ng e - cor 9 ndee lial a) = 4 | te cal e cal t syse and r | ncy bles ole. 0 stem ing- erio |
| Insulato Underg dielectri Substat Underg main dia Course Upon co CO1 CO2 CO3 CO4 | OVERHEAD LINE INS ULATORS AND CABLES orrs: Types, Potential distribution over a string of suspension insulators- improvement of round cables: Constructional features of LT and HT cables, capacitance of single core ar c stress in a single core cable- grading of cables, thermal resistance of dielectric of a sir SUBSTATION, GROUNDING SYSTEM AND DISTRIBUTION SYSTEM ion: Classification-bus-bar arrangements in sub stations- Neutral grounding: Effectively ground system –Resonant grounding- Methods of neutral grounding-Distribution system: stribution systems-Methods of solving AC distributed problems. Total (4 Outcomes: ompletion of this course, the students will be able to: . Design the layout of various types of power generating systems such as thermal, H diesel and MHD. . Develop expression for computation of fundamental parameters off lines. . Categorize the lines into different classes and develop equivalent circuits. . Analyze the voltage distribution in insulator strings and cables and methods to impro- | nd 3 ngle grou Rac 5+0 | ng e - cor 9 ndee lial a) = 4 | te cal e cal t syse and r | ncy bles ole. 0 stem ing- erio |
| Insulato Underg dielectri Unit V Substat Underg main dis Course Upon co CO1 CO2 CO3 CO4 CO5 CO6 | OVERHEAD LINE INS ULATORS AND CABLES rrs: Types, Potential distribution over a string of suspension insulators- improvement of round cables: Constructional features of LT and HT cables, capacitance of single core ar c stress in a single core cable- grading of cables, thermal resistance of dielectric of a sir SUBSTATION, GROUNDING SYSTEM AND DISTRIBUTION SYSTEM ion: Classification-bus-bar arrangements in sub stations- Neutral grounding: Effectively ground system –Resonant grounding- Methods of neutral grounding-Distribution system: stribution systems-Methods of solving AC distributed problems. Total (4 Outcomes: ompletion of this course, the students will be able to: . Design the layout of various types of power generating systems such as thermal, H diesel and MHD. : Develop expression for computation of fundamental parameters off lines. : Categorize the lines into different classes and develop equivalent circuits. : Analyze the voltage distribution in insulator strings and cables and methods to impression for components and grounding techniques. : Grasp the different distribution system | nd 3 ngle grou Rac 5+0 | ng e - con core 9 ndee lial a) = 4 | re cat e cat f + d sys and r is Pe | ncy bles ble. of stem ing- erio |
| Insulato Underg dielectri Substat Underg main dis Course Upon co CO1 CO2 CO3 CO4 CO5 CO6 | OVERHEAD LINE INS ULATORS AND CABLES urs: Types, Potential distribution over a string of suspension insulators- improvement of round cables: Constructional features of LT and HT cables, capacitance of single core ar c stress in a single core cable- grading of cables, thermal resistance of dielectric of a sir SUBSTATION, GROUNDING SYSTEM AND DISTRIBUTION SYSTEM ion: Classification-bus-bar arrangements in sub stations- Neutral grounding: Effectively g round system –Resonant grounding- Methods of neutral grounding-Distribution system: stribution systems-Methods of solving AC distributed problems. Total (4 Outcomes: ompletion of this course, the students will be able to: . Design the layout of various types of power generating systems such as thermal, H diesel and MHD. | nd 3 ngle grou Rac 5+0 | ng e - con core 9 ndee lial a) = 4 | re cat e cat f + d sys and r is Pe | ncy bles bles ble. 0 stem ing- erio ar, e. |
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| Reference | Books: |
|------------|--|
| 1. | Ray, "Electrical Power systems: Concepts, Theory and Practice", PHI Pvt.Ltd., New Delhi,2014,2 nd |
| 1. | edition. |
| 2. | V.K. Mehta, Rohit Mehta, "Principles of Power System", S.Chand& Company Ltd., New Delhi, 2012 |
| 3. | Dr. S.L.UPPAL, 'ELECTRICAL POWER', Khanna publishers, New Delhi, 1987. |
| | |
| E-Referenc | e |
| 1 | www.onlinecourses.nptel.ac.in/noc18_ee41 |
| 2 | www.class-central.com |
| 3 | www.mooc-list.com |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
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| CO1 | 1 | 2 | 1 | 2 | 1 | 2 | 3 | 1 | 1 | 1 | 1 | 2 |
| CO2 | 2 | 3 | 3 | 3 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO3 | 2 | 2 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO4 | 2 | 2 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 2 |
| CO5 | 1 | 1 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO6 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 2 |

| | | CONTROL SYSTEMS | L | TI | 2 | С |
|--|---|--|------------------|------------|------|----|
| | | | 3 | 1 (|) | 4 |
| Course Obj | | | | | 1-1- | |
| <u> </u> | | o understand the methods of representation of systems and getting their transfer fu | | | | • |
| <u> </u> | | o provide adequate knowledge in the time response of systems and steady state e o give basic knowledge in obtaining the open loop and closed loop frequency respo | | | | |
| <u> </u> | | o understand the concept of stability of control system and methods of stability an | | | :115 | • |
| <u>4.</u> 5. | | o study the three ways of designing compensators for a control system. | alysis |) . | | |
| 5. | | | | | | |
| Unit I | S | YSTEMS AND THEIR REPRESENTATION | | 9 - | F | 3 |
| Basic eleme | ents | in control systems – Open and closed loop systems – Mathematical model and E | lectri | cal an | alo | ју |
| | | systems – Transfer function – Synchro – AC and DC servo-motors – Block dia | agran | n redu | icti | on |
| techniques - | – Si | gnal flow graphs. | | | | |
| Unit II | T | ME RESPONSE ANALYSIS | | 9 - | | 3 |
| | | gnals – Time response of first order and second order systems – Steady-state er | roro | - | | - |
| | | es of control systems – Effect of adding poles and zeros to transfer functions – Re | | | | |
| PI, PD and F | | | ,5p01 | | | , |
| Unit III | F | REQUENCY RESPONSE ANALYSIS | 1 | 9 - | L T | 3 |
| | | ween time and frequency response: Second order systems – Polar plots - | - Bo | - | | - |
| | | Gain Margin and Phase Margin – Frequency domain specifications – Constant M | | | | |
| Nichols chai | | | rana | | | |
| | | | | | | |
| Unit IV | S | TABILITY OF CONTROL SYSTEM | | 9 - | F | 3 |
| | | Necessary conditions for stability – Routh-Hurwitz stability criterion – Root locus co | | | | |
| | struc | ction of Root loci - Nyquist stability criterion - Assessment of relative stability | / usir | ng Ny | qui | st |
| criterion. | | | | | | |
| Unit V | | OMPENSATOR DESIGN | | 9 - | | 3 |
| | - | insation – Types of compensators – Electric network realization and frequency cl | araa | - | | |
| | | ators: Lag, lead and lag-lead compensators – Cascade compensation in frequency of | | | 550 | Л |
| | 51100 | | <i>y</i> ao | main | | |
| | | Total (45+ | 15)= | 60 Pe | rio | ls |
| Course Out | cor | les: | | | | |
| Upon compl | etio | n of this course, the students will be able to: | | | | |
| CO1 | <u> </u> | | | | | |
| (.(.)) | | | | | | |
| | + | Derive the transfer function models of any electrical and mechanical systems. | | | | |
| CO2 | : | Develop the time response and steady state error analysis of the control systems | 6. | | | |
| CO2 CO3 | · : : : | Develop the time response and steady state error analysis of the control systems Analyze the frequency response of the systems. | 3. | | | |
| CO2 CO3 CO4 | : | Develop the time response and steady state error analysis of the control systems Analyze the frequency response of the systems. Analyze the stability of closed loop control systems. | 6. | | | |
| CO2 CO3 CO4 CO5 | : | Develop the time response and steady state error analysis of the control systems Analyze the frequency response of the systems. Analyze the stability of closed loop control systems. Construct the root locus plot and analyze system stability. | 5. | | | |
| CO2 CO3 CO4 | : | Develop the time response and steady state error analysis of the control systems Analyze the frequency response of the systems. Analyze the stability of closed loop control systems. | 6. | | | |
| CO2 CO3 CO4 CO5 | : | Develop the time response and steady state error analysis of the control systems Analyze the frequency response of the systems. Analyze the stability of closed loop control systems. Construct the root locus plot and analyze system stability. | 5. | | | |
| CO2 CO3 CO4 CO5 CO6 | : : : | Develop the time response and steady state error analysis of the control systems Analyze the frequency response of the systems. Analyze the stability of closed loop control systems. Construct the root locus plot and analyze system stability. | | 5. | | |
| CO2 CO3 CO4 CO5 CO6 Text Books | : : : A | Develop the time response and steady state error analysis of the control systems Analyze the frequency response of the systems. Analyze the stability of closed loop control systems. Construct the root locus plot and analyze system stability. Design the compensators using conventional techniques. Anand Kumar, "Control Systems", PHI Learning Pvt. Ltd., New Delhi, 2 nd Edition, J. Nagrath& M. Gopal, "Control Systems Engineering", New Age International Pu | , 201 | | əlhi | , |
| CO2 CO3 CO4 CO5 CO6 Text Books 1. | : : : A | Develop the time response and steady state error analysis of the control systems Analyze the frequency response of the systems. Analyze the stability of closed loop control systems. Construct the root locus plot and analyze system stability. Design the compensators using conventional techniques. Anand Kumar, "Control Systems", PHI Learning Pvt. Ltd., New Delhi, 2 nd Edition. | , 201 | | elhi | , |
| CO2 CO3 CO4 CO5 CO6 Text Books 1. | : : : A I 5 ^t | Develop the time response and steady state error analysis of the control systems Analyze the frequency response of the systems. Analyze the stability of closed loop control systems. Construct the root locus plot and analyze system stability. Design the compensators using conventional techniques. Anand Kumar, "Control Systems", PHI Learning Pvt. Ltd., New Delhi, 2 nd Edition, Nagrath& M. Gopal, "Control Systems Engineering", New Age International Pu ^h Edition, 2015. | , 201 | | elhi | , |
| CO2 CO3 CO4 CO5 CO6 Text Books 1. 2. Reference B 1. | : : A I., 5 ^t Boo | Develop the time response and steady state error analysis of the control systems Analyze the frequency response of the systems. Analyze the stability of closed loop control systems. Construct the root locus plot and analyze system stability. Design the compensators using conventional techniques. Anand Kumar, "Control Systems", PHI Learning Pvt. Ltd., New Delhi, 2 nd Edition, Nagrath& M. Gopal, "Control Systems Engineering", New Age International Pu ⁿ Edition, 2015. ks: Ogata, "Modern Control Engineering", Pearson Education, New Delhi, 2010. | , 201: blishe | | elhi | , |
| CO2 CO3 CO4 CO5 CO6 Text Books 1. 2. Reference B | : : A I., 5 ^t Boo | Develop the time response and steady state error analysis of the control systems Analyze the frequency response of the systems. Analyze the stability of closed loop control systems. Construct the root locus plot and analyze system stability. Design the compensators using conventional techniques. Anand Kumar, "Control Systems", PHI Learning Pvt. Ltd., New Delhi, 2 nd Edition, Nagrath& M. Gopal, "Control Systems Engineering", New Age International Pu ^h Edition, 2015. ks: | , 201: blishe | | elhi | , |
| CO2 CO3 CO4 CO5 CO6 Text Books 1. 2. Reference B 1. 2. | : A I 5 ^t Boo | Develop the time response and steady state error analysis of the control systems Analyze the frequency response of the systems. Analyze the stability of closed loop control systems. Construct the root locus plot and analyze system stability. Design the compensators using conventional techniques. Anand Kumar, "Control Systems", PHI Learning Pvt. Ltd., New Delhi, 2 nd Edition, Nagrath& M. Gopal, "Control Systems Engineering", New Age International Pu ⁿ Edition, 2015. ks: Ogata, "Modern Control Engineering", Pearson Education, New Delhi, 2010. | , 201: blishe | | elhi | , |
| CO2 CO3 CO4 CO5 CO6 Text Books 1. 2. Reference B 1. | : A I 5 ^t Boo K M es: | Develop the time response and steady state error analysis of the control systems Analyze the frequency response of the systems. Analyze the stability of closed loop control systems. Construct the root locus plot and analyze system stability. Design the compensators using conventional techniques. Anand Kumar, "Control Systems", PHI Learning Pvt. Ltd., New Delhi, 2 nd Edition, Nagrath& M. Gopal, "Control Systems Engineering", New Age International Pu ⁿ Edition, 2015. ks: Ogata, "Modern Control Engineering", Pearson Education, New Delhi, 2010. | , 201: blishe | | elhi | , |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 3 | 2 | 2 | 1 | 1 | 2 | 1 | 1 | 1 | 1 | 1 | 2 |
| CO2 | 3 | 3 | 2 | 2 | 1 | 2 | 1 | 1 | 1 | 2 | 1 | 2 |
| CO3 | 3 | 3 | 1 | 1 | 2 | 1 | 1 | 1 | 1 | 2 | 1 | 1 |
| CO4 | 3 | 3 | 2 | 1 | 1 | 1 | 2 | 2 | 1 | 2 | 2 | 2 |
| CO5 | 3 | 1 | 2 | 2 | 1 | 1 | 2 | 3 | 1 | 2 | 2 | 2 |
| CO6 | 3 | 1 | 2 | 2 | 1 | 1 | 2 | 3 | 1 | 2 | 2 | 2 |

| 18EE503 | POWER ELECTRONICS | L A | | P | C |
|---|--|---------------------------------|---------------------|--------------------|---------------------------------------|
| | | 3 | 0 | 0 | 3 |
| Course Ol | ojectives: | | | | |
| 1. | To study an overview of power semiconductor devices, principles of control | olled | recti | fiers, | DC-DC |
| Ι. | converters, inverters, AC voltage controller circuits and their analysis. | | | | |
| | | | | | |
| Unit I | POWER SEMICONDUCTOR DEVICES | , | 9 | + | 0 |
| | f power electronics- Structure, Operation, Static and Switching characteristics of | | | | |
| | ower Diode, SCR, MOSFET, IGBT, IGCT — Thyristor ratings and protection, and IGBT, Switching and Conduction losses in a generic power semiconductor de | | | ive c | ircuits to |
| | and IGBT, Switching and Conduction losses in a generic power semiconductor de | evice | 5. | | |
| Unit II | PHASE CONTROLLED RECTIFIERS | | 9 | + | 0 |
| Single pha | ase and three phase fully controlled rectifiers – Power circuit, Operation, W | /avef | form | anal | vsis and |
| | ce parameters - Effect of source and load inductance -Single phase and Three | | | | |
| | n to PWM rectifiers | | | | |
| | - | | | - | |
| Unit III | DC TO DC CONVERTER | | 9 | + | 0 |
| | y chopper with an active switch and diode, concepts of duty ratio and average vol | | | | |
| Power Circ | cuit and steady state analysis of Buck converter, Boost converter, Buck - boos | t cor | nverte | er an | d SEPIC |
| converter- | Design of inductor and capacitors for DC-DC converters. | | | | |
| Unit IV | INVERTERS | 1 | 9 | | • |
| | | 4 a 1 | - | + | 0 |
| | uit of single-phase voltage source inverter, square wave operation of the invert | | | | |
| | modulation modulation index and output valtage. Dower singuit of a three phase | volt | | | |
| | modulation, modulation index and output voltage, Power circuit of a three-phase | | | | |
| operation, | switch states, instantaneous output voltages, three-phase sinusoidal mod | | | | |
| operation, | switch states, instantaneous output voltages, three-phase sinusoidal mod | | | | |
| | switch states, instantaneous output voltages, three-phase sinusoidal mod | | | | |
| operation, modulation Unit V | switch states, instantaneous output voltages, three-phase sinusoidal mod | dulat | ion · | -Spa | ce vecto |
| operation, <u>modulation</u> Unit V Introductio | switch states, instantaneous output voltages, three-phase sinusoidal mod | dulat | ion · | -Spa | ce vect |
| operation, <u>modulation</u> Unit V Introductio | switch states, instantaneous output voltages, three-phase sinusoidal modes of a converter sinu | dulat | 9 9 ∙ Multi | -Spa + istag | ce vect 0 e seque |
| operation, modulation Unit V Introductio control –Aj | switch states, instantaneous output voltages, three-phase sinusoidal mode AC TO AC CONVERTERS n and principle of operation of Single phase and Three phase AC voltage controlled oplications of AC Voltage Controllers–Introduction to Matrix converters. | dulat | 9 9 ∙ Multi | -Spa + istag | ce vect 0 e seque |
| operation, modulation Unit V Introductio control –Aj | switch states, instantaneous output voltages, three-phase sinusoidal mode AC TO AC CONVERTERS n and principle of operation of Single phase and Three phase AC voltage controlled oplications of AC Voltage Controllers–Introduction to Matrix converters. | dulat | 9 9 ∙ Multi | -Spa + istag | ce vect 0 e seque |
| operation, modulation Unit V Introductio control –A Course Ou | switch states, instantaneous output voltages, three-phase sinusoidal mode AC TO AC CONVERTERS n and principle of operation of Single phase and Three phase AC voltage controlled oplications of AC Voltage Controllers–Introduction to Matrix converters. | dulat | 9 9 ∙ Multi | -Spa + istag | ce vecto 0 e seque |
| operation, modulation Unit V Introductio control –A Course Ou | switch states, instantaneous output voltages, three-phase sinusoidal mode AC TO AC CONVERTERS n and principle of operation of Single phase and Three phase AC voltage controlled oplications of AC Voltage Controllers–Introduction to Matrix converters. | dulat | 9 9 Multi | -Spa + istag | ce vect 0 e seque |
| operation, modulation Unit V Introductio control –A Course Ou Upon com | switch states, instantaneous output voltages, three-phase sinusoidal mode AC TO AC CONVERTERS n and principle of operation of Single phase and Three phase AC voltage controlled oplications of AC Voltage Controllers–Introduction to Matrix converters. | dulat | 9 9 Multi | -Spa + istag | ce vecto |
| operation, modulation Unit V Introductio control –A Course Ou Upon com CO1 | switch states, instantaneous output voltages, three-phase sinusoidal mode AC TO AC CONVERTERS n and principle of operation of Single phase and Three phase AC voltage controller oplications of AC Voltage Controllers—Introduction to Matrix converters. Templetion of this course, the students will be able to: : Select the Power Semiconductor Devices based on Characteristics. | dulat | 9 9 Multi | -Spa + istag | ce vecto 0 e sequei |
| operation, modulation Unit V Introductio control –A Course Ou Upon com CO1 CO2 | switch states, instantaneous output voltages, three-phase sinusoidal mode AC TO AC CONVERTERS n and principle of operation of Single phase and Three phase AC voltage controlled oplications of AC Voltage Controllers—Introduction to Matrix converters. Telefonders: pletion of this course, the students will be able to: : Select the Power Semiconductor Devices based on Characteristics. : Evaluate the performance of phase-controlled rectifier. | dulat | 9 9 Multi | -Spa + istag | ce vecto 0 e seque |
| operation, modulation Unit V Introductio control –A Course Ou Upon com CO1 CO2 CO3 | switch states, instantaneous output voltages, three-phase sinusoidal mode AC TO AC CONVERTERS n and principle of operation of Single phase and Three phase AC voltage controlled oplications of AC Voltage Controllers—Introduction to Matrix converters. Templetion of this course, the students will be able to: : Select the Power Semiconductor Devices based on Characteristics. : Evaluate the performance of phase-controlled rectifier. : Design and analyze the DC/DC converter circuits | dulat ers – otal | 9 Multi (45+(| -Spa + istag | ce vect 0 e seque |
| operation, modulation Unit V Introductio control –A Course Ou Upon com CO1 CO2 CO3 CO4 CO5 | switch states, instantaneous output voltages, three-phase sinusoidal mode AC TO AC CONVERTERS n and principle of operation of Single phase and Three phase AC voltage controlled oplications of AC Voltage Controllers—Introduction to Matrix converters. Toutcomes: pletion of this course, the students will be able to: Select the Power Semiconductor Devices based on Characteristics. Evaluate the performance of phase-controlled rectifier. Design and analyze the DC/DC converter circuits Analyze the inverter operation and its control techniques. Know the operation and applications of AC voltage controller and matrix converters. | dulat ers – otal | 9 Multi (45+(| -Spa + istag | ce vecto 0 e seque |
| operation, modulation Unit V Introductio control –A Course Ou Upon com CO1 CO2 CO3 CO3 CO4 | switch states, instantaneous output voltages, three-phase sinusoidal mode AC TO AC CONVERTERS n and principle of operation of Single phase and Three phase AC voltage controlled oplications of AC Voltage Controllers—Introduction to Matrix converters. Toutcomes: pletion of this course, the students will be able to: Select the Power Semiconductor Devices based on Characteristics. Evaluate the performance of phase-controlled rectifier. Design and analyze the DC/DC converter circuits Analyze the inverter operation and its control techniques. Know the operation and applications of AC voltage controller and matrix converters. | dulat ers – otal | 9 Multi (45+(| -Spa + istag | ce vect 0 e seque |
| operation, modulation Unit V Introductio control –A Course Ou Upon com CO1 CO2 CO3 CO4 CO5 Text Book | switch states, instantaneous output voltages, three-phase sinusoidal mode AC TO AC CONVERTERS n and principle of operation of Single phase and Three phase AC voltage controlled oplications of AC Voltage Controllers—Introduction to Matrix converters. Toutcomes: pletion of this course, the students will be able to: Select the Power Semiconductor Devices based on Characteristics. Evaluate the performance of phase-controlled rectifier. Design and analyze the DC/DC converter circuits Analyze the inverter operation and its control techniques. Know the operation and applications of AC voltage controller and matrix converters. | dulat | 9 Multi (45+(| -Spa | ce vect |
| operation, modulation Unit V Introductio control –A Course Ou Upon com CO1 CO2 CO3 CO4 CO5 | switch states, instantaneous output voltages, three-phase sinusoidal models and principle of operation of Single phase and Three phase AC voltage controlled oplications of AC Voltage Controllers—Introduction to Matrix converters. | dulat | 9 Multi (45+(| -Spa | ce vecto 0 e sequer 5 Perioc |
| operation, modulation Unit V Introductio control –A Course Ou Upon com CO1 CO2 CO3 CO4 CO5 Text Book | switch states, instantaneous output voltages, three-phase sinusoidal models and principle of operation of Single phase and Three phase AC voltage controlled oplications of AC Voltage Controllers—Introduction to Matrix converters. | dulat | 9 Multi (45+(| -Spa | ce vecto 0 e sequeo 5 Perioc |
| operation, modulation Unit V Introductio control –A Course Ou Upon com CO1 CO2 CO3 CO4 CO3 CO4 CO5 Text Book | switch states, instantaneous output voltages, three-phase sinusoidal mode AC TO AC CONVERTERS n and principle of operation of Single phase and Three phase AC voltage controlled oplications of AC Voltage Controllers–Introduction to Matrix converters. Technology of this course, the students will be able to: : Select the Power Semiconductor Devices based on Characteristics. : Evaluate the performance of phase-controlled rectifier. : Design and analyze the DC/DC converter circuits : Analyze the inverter operation and its control techniques. : Know the operation and applications of AC voltage controller and matrix converters. M.H.Rashid, 'Power Electronics: Circuits, Devices and Applications', Pearson E New Delhi, 2014. | dulat | 9 Multi (45+(| -Spa | ce vecto 0 e sequeo 5 Perioc |
| operation, modulation Unit V Introductio control –A Course Ou Upon com CO1 CO2 CO3 CO4 CO5 Text Book 1. 2. | switch states, instantaneous output voltages, three-phase sinusoidal model AC TO AC CONVERTERS n and principle of operation of Single phase and Three phase AC voltage controlled oplications of AC Voltage Controllers–Introduction to Matrix converters. Temperature futcomes: obletion of this course, the students will be able to: : Select the Power Semiconductor Devices based on Characteristics. : Evaluate the performance of phase-controlled rectifier. : Design and analyze the DC/DC converter circuits : Analyze the inverter operation and its control techniques. : Know the operation and applications of AC voltage controller and matrix converters: multiple M.H.Rashid, 'Power Electronics: Circuits, Devices and Applications', Pearson E New Delhi, 2014. P.S.Bimbra "Power Electronics" Khanna Publishers, New Delhi 2018. | dulat | 9 Multi (45+(| -Spa | ce vect |
| operation, modulation Unit V Introductio control –A Course Ou Upon com CO1 CO2 CO3 CO4 CO5 Text Book 1. 2. Reference | switch states, instantaneous output voltages, three-phase sinusoidal model AC TO AC CONVERTERS n and principle of operation of Single phase and Three phase AC voltage controlled oplications of AC Voltage Controllers–Introduction to Matrix converters. Television of this course, the students will be able to: : Select the Power Semiconductor Devices based on Characteristics. : Evaluate the performance of phase-controlled rectifier. : Design and analyze the DC/DC converter circuits : Analyze the inverter operation and its control techniques. : Know the operation and applications of AC voltage controller and matrix converter. str M.H.Rashid, 'Power Electronics: Circuits, Devices and Applications', Pearson E New Delhi, 2014. P.S.Bimbra "Power Electronics" Khanna Publishers, New Delhi 2018. | dulat | 9 Multi (45+(| -Spa | ce vecto 0 e sequel 5 Perioc |
| operation, modulation Unit V Introductio control –A Course Ou Upon com CO1 CO2 CO3 CO4 CO5 Text Book 1. 2. | switch states, instantaneous output voltages, three-phase sinusoidal modes and principle of operation of Single phase and Three phase AC voltage controlled oplications of AC Voltage Controllers—Introduction to Matrix converters. Temperature Select the Power Semiconductor Devices based on Characteristics. Evaluate the performance of phase-controlled rectifier. Design and analyze the DC/DC converter circuits Know the operation and applications of AC voltage controller and matrix converters. | dulat | 9 Multi (45+(| -Spa | ce vecto 0 e sequel 5 Perioc |
| operation, modulation Unit V Introductio control –A Course Ou Upon com CO1 CO2 CO3 CO4 CO5 Text Book 1. 2. Reference 1. | switch states, instantaneous output voltages, three-phase sinusoidal modes and principle of operation of Single phase and Three phase AC voltage controlled oplications of AC Voltage Controllers—Introduction to Matrix converters. Temperature Select the Power Semiconductor Devices based on Characteristics. Evaluate the performance of phase-controlled rectifier. Design and analyze the DC/DC converter circuits Know the operation and applications of AC voltage controller and matrix converters. | dulat | 9 Multi (45+(| -Spa | ce vecto 0 e sequel 5 Perioc |
| operation, modulation Unit V Introductio control –A Course Ou Upon com CO1 CO2 CO3 CO4 CO5 Text Book 1. 2. Reference | switch states, instantaneous output voltages, three-phase sinusoidal model AC TO AC CONVERTERS n and principle of operation of Single phase and Three phase AC voltage controlled oplications of AC Voltage Controllers–Introduction to Matrix converters. Temperature opletion of this course, the students will be able to: : Select the Power Semiconductor Devices based on Characteristics. : Evaluate the performance of phase-controlled rectifier. : Design and analyze the DC/DC converter circuits : Analyze the inverter operation and its control techniques. : Know the operation and applications of AC voltage controller and matrix converters strest M.H.Rashid, 'Power Electronics: Circuits, Devices and Applications', Pearson E New Delhi, 2014. P .S.Bimbra "Power Electronics" Khanna Publishers, New Delhi 2018. Books: Ned Mohan, Tore. M. Undel and, William. P. Robbins, 'Power Electronics: Convertional convertions: Convertional convertint convertional convertional convertint conver | dulat ers – otal verte | 9 Multi (45+(| -Spa | ce vect |

| 1 | www.onlinecourses.nptel.ac.in/ |
|---|--------------------------------|
| 2 | www.class-central.com |

| PO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | | | 1 | 3 | | 2 | | | | 1 | | 1 |
| CO2 | 2 | | | 1 | 2 | | | 1 | | | | |
| CO3 | 1 | 2 | | | | | 2 | | | | | |
| CO4 | 1 | 2 | | 3 | | 1 | 2 | | | | | |
| CO5 | | | 1 | | 2 | | | | 2 | | 2 | 2 |

| 18EE504 | MICROPROCESSOR AND MICROCONTROLLER | | т | Р | С |
|-----------------|--|--------|---------|--------|-----------|
| | | L 3 | 0 | Г 0 | 3 |
| Course Ob | instivas | • | | • | • |
| Course Ob | | | | | |
| 1. | A thorough understanding in establishing a digital control system | | | | |
| 2 | Learn different digital communications and their applications | | | | |
| 3 | Get ideas to apply digital controls for different electrical applications | | | | |
| Unit I | 8085 8 BIT MICROPROCESSOR | | 9 | + | 0 |
| Fundament | als of microprocessors – Architecture of 8085 – Groups of Instructions - Address | ing m | nodes | – Ba | sic timin |
| diagram - C | Drganization and addressing of Memory and I/O systems –Interrupt structure – | Stac | k and | sub- | routines |
| Simple 808 | 5 based system design and programming. | | | | |
| Unit II | 8051 8 BIT MICROCONTROLLER | | 9 | + | 0 |
| | als of microcontrollers – Architecture of 8051 – Groups of Instructions - Addressi | na m | - | - | - |
| | systems – I/O Ports – Timers/Counters – Serial Port - Interrupt structure – Simpl | | | | |
| | nblers and Compliers | | 5 | 5 | |
| | | | | | |
| Unit III | INTERFACING WITH 8051 MICROCONTROLLER | | 9 | + | 0 |
| | equirements of interfacing – Interfacing – LED, 7 segment and LCD Displays – | Tacti | le sw | itches | s, Matrix |
| keyboard - | Parallel ADC – DAC – Interfacing of Current, Voltage, RTD and Hall Sensors. | | | | |
| Unit IV | EXTERNAL COMMUNICATION INTERFACE | | 9 | + | 0 |
| | is and Asynchronous Communication. RS232, RS 485, SPI, I2C. Introduction | on a | - | | - |
| | e Blue-tooth and Zig-bee. | | | tonia | ing to |
| | | | | | |
| Unit V | APPLICATIONS OF MICROCONTROLLERS | | 9 | + | 0 |
| Stepper mo | tor interfacing, DC Motor interfacing, Data Acquisition System, Measurement o | f Eleo | ctric F | ower | , Powe |
| factor. Solid | l State Relays | | | | |
| | | | (AE . C | | Deried |
| Course Out | | otai | (45+0 |)= 43 | Period |
| | | | | | |
| | letion of this course, the students will be able to: | | | | |
| CO1 | : Understand any other types of modern microprocessor and microcontroller, | | | | |
| CO2 | : Select appropriate digital system based on applications | | | | |
| CO3 | : Design simple controls using software programs | | | | |
| CO4 | : Design and interface communications between digital systems | | | | |
| CO5 | : Apply the digital concepts to measure and control simple electrical systems | | | | |
| Text Books | S. | | | | |
| | R. S. Gaonkar, ", Microprocessor Architecture: Programming and Applicat ic | ons v | vith t | ne | |
| 1. | 8085", Penram International Publishing, 2013, 6 th edition. | | | | |
| 2. | K. J. Ayala, "8051 Microcontroller", Delmar Cengage Learning, 2004. | | | | |
| <u>^</u> | M. A.Mazidi, J. G. Mazidi and R. D. McKinlay, "The8051Microcontroller a | nd E | mbed | ded | |
| 3. | Systems: Using Assembly and C", Pearson Education, 2007. | | | | |
| | Destre | | | | |
| Reference | Books: R. Kamal, "Embedded System", McGraw Hill Education,2017 | | | | |
| <u>1.</u> 2. | D. V. Hall, "Microprocessors & Interfacing", McGraw Hill Education, 2017 | 75 | | | |
| ۷. | | 55 | | | |
| E-Referenc | e | | | | |
| 1 | www.onlinecourses.nptel.ac.in/ | | | | |
| 2 | www.class-central.com | | | | |
| | | | | | |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 1 | 1 | 1 | 1 | 1 | | 1 | 1 | | 1 | 1 | 1 |
| CO2 | 1 | 1 | 1 | 1 | 1 | | 1 | 1 | | 1 | 1 | 1 |
| CO3 | 1 | 1 | 1 | 1 | 1 | | 1 | 1 | | 1 | 1 | 1 |
| CO4 | 1 | 1 | 1 | 1 | 1 | | 1 | 1 | | 1 | 1 | 1 |
| CO5 | 1 | 1 | 1 | 1 | 1 | | 1 | 1 | | 1 | 1 | 1 |

| | 5 | CONTROL SYSTEMS LABORATORY | L | Т | Ρ | С |
|--|---|--|---------|---|-------|-------|
| | | | 0 | 0 | 3 | 1.5 |
| Course | Obi | ectives: | | | | |
| 1. | | To provide a platform for understanding the basic concepts of linear control theory | and | its a | oilac | ation |
| | | to practical systems. | | | | |
| Experim | nent | | | | | |
| 1 | | Transfer function of separately excited DC generator. | | | | |
| 2 | | Transfer function of self-excited DC generator. | | | | |
| 3 | | Transfer function of armature-controlled DCmotor. | | | | |
| 4 | | Transfer function of field-controlled DC motor. | | | | |
| 5 | | Transfer function of AC servo-motor. | | | | |
| 6 | | Frequency response of Lag, Lead and Lag-lead networks. | | | | |
| 7 | | Study of Synchros. | | | | |
| 8 | | Study of Stepper motor. | | | | |
| 9 | | Ward Leonard method of speed control of DC motor. | | | | |
| 10 | | Study of DC position control system. | | | | |
| 11 | | Study of P, PI and PID controllers (First-order). | | | | |
| | | Total (| 0+45 |)= 4 | 5 Pe | riods |
| | | | • • • • | <u> </u> | | |
| Course | Out | | | , . | | |
| | | | | <u>, .</u> | | |
| | | comes: | | , - | | |
| Upon co | | comes: etion of this course, the students will be able to: | | <u>, </u> | | |
| Upon co CO1 | mpl : | comes: etion of this course, the students will be able to: Design the transfer function of DC and AC machines. | | <u>, -</u> | | |
| Upon co CO1 CO2 | mpl : : | comes: etion of this course, the students will be able to: Design the transfer function of DC and AC machines. Design compensators for control system. | | <u>, -</u> | | |
| Upon co CO1 CO2 CO3 | mpl : | comes: etion of this course, the students will be able to: Design the transfer function of DC and AC machines. Design compensators for control system. Gain knowledge about Synchros. | | | | |
| Upon co CO1 CO2 CO3 CO4 CO5 | mpl : : : : : | comes: etion of this course, the students will be able to: Design the transfer function of DC and AC machines. Design compensators for control system. Gain knowledge about Synchros. Gain knowledge about Stepper motor. Design controllers for control systems. | | | | |
| Upon co CO1 CO2 CO3 CO4 CO5 Referen | mpl : : : : : | comes: etion of this course, the students will be able to: Design the transfer function of DC and AC machines. Design compensators for control system. Gain knowledge about Synchros. Gain knowledge about Stepper motor. Design controllers for control systems. Books: | | | | |
| Upon co CO1 CO2 CO3 CO4 CO5 Referen 1. | mpl : : : : : | comes: etion of this course, the students will be able to: Design the transfer function of DC and AC machines. Design compensators for control system. Gain knowledge about Synchros. Gain knowledge about Stepper motor. Design controllers for control systems. Books: A. Anand Kumar, "Control Systems", PHI Learning Pvt. Ltd., New Delhi, 2 nd Edition | on, 20 |)15. | | |
| Upon co CO1 CO2 CO3 CO4 CO5 Referen | mpl : : : : : | comes: etion of this course, the students will be able to: Design the transfer function of DC and AC machines. Design compensators for control system. Gain knowledge about Synchros. Gain knowledge about Stepper motor. Design controllers for control systems. Books: A. Anand Kumar, "Control Systems", PHI Learning Pvt. Ltd., New Delhi, 2 nd Edition I.J. Nagrath& M. Gopal, "Control Systems Engineering", New Age International Put | on, 20 |)15. | | |
| Upon co CO1 CO2 CO3 CO4 CO5 Referen 1. | mpl : : : : : | comes: etion of this course, the students will be able to: Design the transfer function of DC and AC machines. Design compensators for control system. Gain knowledge about Synchros. Gain knowledge about Stepper motor. Design controllers for control systems. Books: A. Anand Kumar, "Control Systems", PHI Learning Pvt. Ltd., New Delhi, 2 nd Edition | on, 20 |)15. | | |
| Upon co CO1 CO2 CO3 CO4 CO5 Referen 1. 2. 3. | mpl : : : : : : : : : : : : : : : : : : : | comes: etion of this course, the students will be able to: Design the transfer function of DC and AC machines. Design compensators for control system. Gain knowledge about Synchros. Gain knowledge about Stepper motor. Design controllers for control systems. Books: A. Anand Kumar, "Control Systems", PHI Learning Pvt. Ltd., New Delhi, 2 nd Edition I.J. Nagrath& M. Gopal, "Control Systems Engineering", New Age International Put Edition, 2015. K. Ogata, "Modern Control Engineering", Pearson Education, New Delhi, 2010. | on, 20 |)15. | | |
| Upon co CO1 CO2 CO3 CO4 CO5 Referen 1. 2. | mpl : : : : : : : : : : : : : : : : : : : | comes: etion of this course, the students will be able to: Design the transfer function of DC and AC machines. Design compensators for control system. Gain knowledge about Synchros. Gain knowledge about Stepper motor. Design controllers for control systems. Books: A. Anand Kumar, "Control Systems", PHI Learning Pvt. Ltd., New Delhi, 2 nd Edition I.J. Nagrath& M. Gopal, "Control Systems Engineering", New Age International Put Edition, 2015. K. Ogata, "Modern Control Engineering", Pearson Education, New Delhi, 2010. | on, 20 |)15. | | |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 3 | 3 | 2 | 1 | 1 | 1 | 3 | 1 | 2 | 1 | 1 | 2 |
| CO2 | 3 | 3 | 3 | 3 | 2 | 2 | 3 | 1 | 2 | 2 | 1 | 1 |
| CO3 | 3 | 3 | 3 | 2 | 2 | 1 | 1 | 2 | 1 | 3 | 1 | 1 |
| CO4 | 3 | 3 | 3 | 1 | 1 | 1 | 2 | 2 | 1 | 2 | 2 | 2 |
| CO5 | 2 | 3 | 2 | 3 | 1 | 2 | 1 | 3 | 1 | 2 | 2 | 2 |

| 18EE | 506 |
|------|-----|
|------|-----|

POWER ELECTRONICS LABORATORY

| L | Т | Ρ | С |
|---|---|---|-----|
| 0 | 0 | 3 | 1.5 |

| Course O | bjectives: |
|-----------|---|
| 1 | To simulate and analyze the performance of different power electronic converter circuits. |
| Experime | nts: |
| 1 | V-I Characteristics of power diode and SCR |
| 2 | Static and Switching Characteristics of Power MOSFET and IGBT |
| 3 | Single phase AC to DC fully controlled converter |
| 4 | Single phase PWM rectifiers |
| 5 | Buck and Boost Converters |
| 6 | MOSFET based single-phase PWM inverter |
| 7 | IGBT based three-phase PWM inverter |
| 8 | Single phase AC voltage controller |
| 9 | Simulation for Single phase and three phase dual converters |
| 10 | Simulation of Buck – boost converter and SEPIC converter |
| 11 | Simulation of three phase voltage source inverters with sinusoidal modulation |
| 12 | Simulation of Matrix converter |
| | |
| 0 | Total(0+45) = 45 Periods |
| Course O | utcomes: |
| Upon com | pletion of this course, the students will be able to: |
| CO1 | : Analyze the characteristics of MOSFET, SCR and IGBT. |
| CO2 | : Evaluate the performance of DC-DC Converters and inviters. |
| CO3 | : Design and control of inverters with different modulations. |
| CO4 | : Analyze the performance of power converters with simulation studies |
| CO5 | : Demonstrate the operation of power converters |
| Text Bool | is: |
| 1. | M.H.Rashid, 'Power Electronics: Circuits, Devices and Applications', Pearson Education, PHI Third Edition, New Delhi, 2009. |
| 2. | P.S.Bimbra "Power Electronics" Khanna Publishers, New Delhi 2016. |
| Reference | Books: |
| 4 | Ned Mohan, Tore. M. Undel and, William. P. Robbins, 'Power Electronics: Converters, Application |
| 1. | and Design', John Wiley and sons, 2007. |
| <u>^</u> | R. W. Erickson and D. Maksimovic, "Fundamentals of Power Electronics", Springer |
| 2. | Science & Business Media, 2007. |
| 3. | M.D. Singh and K.B. Khanchandani, "Power Electronics," McGraw Hill India, 2013. |
| E-Referen | |
| 1. | www.onlinecourses.nptel.ac.in/ |
| 2. | www.class-central.com |
| 00/20 | /apping |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | | 2 | | 3 | | 2 | | | 1 | | | 1 |
| CO2 | 2 | | 3 | 1 | | | 2 | | | | 1 | |
| CO3 | | 1 | 2 | | 2 | | 2 | | | 2 | | |
| CO4 | 1 | | | 3 | | 1 | | | | | 2 | |
| CO5 | | | | | 2 | | | 1 | 2 | | | 2 |

| 18EE507 | MICROPROCESSOR AND MICROCONTROLLER LABORATORY |
|-----------|---|
| | 0 0 3 1.5 |
| Course Ob | bjectives: |
| 1. | Able to write own programs for different applications |
| 2. | Interface and program for interconnected digital systems |
| | |
| Experimer | nts: |
| 1 | Simple arithmetic operations: addition / subtraction / multiplication / division. |
| 2 | Programming with control instructions: |
| | a. Ascending / Descending order, Maximum / Minimum of numbers |
| | b. Programs using Rotate instructions |
| | c. Hex / ASCII / BCD code conversions. |
| 3 | Interface Experiments: with 8085 |
| 4 | a. A/D Interfacing. & D/A Interfacing. |
| 4 5 | Traffic light controller. I/O Port / Serial communication |
| 6 | Programming Practices with Simulators/Emulators/open source |
| 7 | Keyboard interfacing |
| 8 | LCD interfacing 4bit/8bit mode |
| 9 | Demonstration of basic instructions with 8051 Micro controller execution, including: |
| | a. Conditional jumps, looping |
| | b. Calling subroutines. |
| 10 | Programming I/O Port 8051 |
| | a. Interface with external A/D & D/A |
| | b. Interface with stepper motor |
| 11 | Interrupt programming with external sensors/ devices |
| 12 | Programming for communication using Zigbee protocol. |
| Course Ou | Total (0+45)= 45 Periods |
| | |
| | pletion of this course, the students will be able to: |
| CO1 | : Write coding to implement different types of algorithms |
| CO2 | : Design and implement simple controllers |
| CO3 | : Use simulators and emulators for debugging and verifying codes |
| CO4 | : Write efficient codes using interrupts for time critical applications |
| CO5 | : Interface any application module to microprocessor/microcontroller. |
| Text Book | ·c· |
| | R. S. Gaonkar, ", Microprocessor Architecture: Programming and Applicat ions with the |
| 1. | 8085", Penram International Publishing, 1996 |
| 2. | K. J. Ayala, "8051 Microcontroller", Delmar Cengage Learning,2004. |
| | M. A.Mazidi, J. G. Mazidi and R. D. McKinlay, "The8051Microcontroller and Embedded |
| 3. | Systems: Using Assembly and C", Pearson Education, 2007. |
| | |
| Reference | |
| 1. | R. Kamal, "Embedded System", McGraw Hill Education, 2009 D. V. Hall, "Microprocessors & Interfacing", McGraw Hill Higher Education, 1991 |
| 2. | U. V. Hall, Wildroprocessors & Interfacing, Wilderaw Hill Higher Education, 1991 |
| E-Referen | ces: |
| 1. | www.onlinecourses.nptel.ac.in/ |
| 2. | www.class-central.com |
| | |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 1 | 1 | 1 | 1 | 1 | 0 | 1 | 1 | 1 | 1 | 0 | 1 |
| CO2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO3 | 1 | 1 | 1 | 1 | 1 | 0 | 1 | 1 | 1 | 1 | 0 | 1 |
| CO4 | 1 | 1 | 1 | 1 | 1 | 0 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO5 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

| | POWER SYSTEM ANALYSIS AND STABILITY | LTPC |
|---|--|--|
| | | 3 0 0 3 |
| | | |
| Course Ob | | |
| 1 | To model the power system under steady state operating condition | |
| 2 | To apply efficient numerical methods to solve the power flow problem | |
| 3. | To model and analyze the power systems under abnormal (or) fault conditions | |
| 4. | To model and analyse the transient behaviour of power system when it is subject | cted to a fault. |
| Unit I | POWER SYSTEM OVERVIEW AND MODELLING | 9 + 0 |
| - Three-pha | oonents of modern power system - Per-phase analysis: Generator model - Synchrono ase transformer model - Three-winding transformer model - Line model- per unit quan of per-unit quantities - representation of load impedance - Single line diagram - diagrams. | itities - Changing |
| 11 | | |
| Unit II | POWER FLOW ANALYSIS | 9 + 0 |
| method -D | ication – Bus admittance matrix Formulation: Direct inspection method and Singul evelopment of power flow model - solution of load flow equations: Gauss Seidel r nethod- Fast decoupled method – flowcharts – Comparison of the three power flow s | method - Newtor |
| Unit III | FAULT ANALYSIS - BALANCED FAULT | 9 + 0 |
| Introduction | n – Balanced three phase fault – Short circuit capacity - Algorithm for formation of the | e Bus Impedance |
| matrix- Sys | tematic fault analysis using Bus Impedance matrix -Selection of circuit breakers. | |
| <u> </u> | | |
| Unit IV | FAULT ANALYSIS - UNBALANCED FAULT | 9 + 0 |
| | tals of symmetrical components – Sequence impedances – Construction of seque | |
| | rical faults on power system: Single line-ground fault, line-line fault – Double lin | ne-ground fault- |
| Unbalance | d Fault analysis using bus impedance matrix. | |
| Unit V | STABILITY STUDIES | 9 + 0 |
| Importance | | |
| | of stability studies – Classification of power system stability – Stability limits – Powe | er angle equation |
| | of stability studies – Classification of power system stability – Stability limits – Powe stant- Swing equation of single-machine connected to infinite bus – Solution of S | |
| Inertia con | of stability studies – Classification of power system stability – Stability limits – Power stant- Swing equation of single-machine connected to infinite bus – Solution of So p method-II – Modified Euler's method – Runge-Kutta method – Equal area criterion | wing equation by |
| Inertia con step-by-ste | stant- Swing equation of single-machine connected to infinite bus - Solution of S | wing equation by – Critical clearing |
| Inertia con step-by-ste | stant- Swing equation of single-machine connected to infinite bus – Solution of Sp p method-II – Modified Euler's method – Runge-Kutta method – Equal area criterion ime -Factors affecting transient stability – Techniques for transient stability improve | wing equation by – Critical clearing ment. |
| Inertia con step-by-ste angle and t | stant- Swing equation of single-machine connected to infinite bus – Solution of Sp p method-II – Modified Euler's method – Runge-Kutta method – Equal area criterion ime -Factors affecting transient stability – Techniques for transient stability improve Total (45) | wing equation by – Critical clearing |
| Inertia con step-by-ste | stant- Swing equation of single-machine connected to infinite bus – Solution of Sp p method-II – Modified Euler's method – Runge-Kutta method – Equal area criterion ime -Factors affecting transient stability – Techniques for transient stability improve Total (45) | wing equation by – Critical clearing ment. |
| Inertia con step-by-ste angle and t | stant- Swing equation of single-machine connected to infinite bus – Solution of Sp p method-II – Modified Euler's method – Runge-Kutta method – Equal area criterion ime -Factors affecting transient stability – Techniques for transient stability improve Total (45) | wing equation by – Critical clearing ment. |
| Inertia con step-by-ste angle and t | stant- Swing equation of single-machine connected to infinite bus – Solution of Sp p method-II – Modified Euler's method – Runge-Kutta method – Equal area criterion ime -Factors affecting transient stability – Techniques for transient stability improve Total (45 | wing equation by – Critical clearing ment. |
| Inertia con step-by-ste angle and t Course Ou Upon comp CO1 CO2 | stant- Swing equation of single-machine connected to infinite bus – Solution of Sp p method-II – Modified Euler's method – Runge-Kutta method – Equal area criterion ime -Factors affecting transient stability – Techniques for transient stability improver Total (45 steepense): bletion of this course, the students will be able to: : Develop the single line diagram for the power system. : Perform and analyze load flow computations using bus admittance matrix | wing equation by – Critical clearing ment. |
| Inertia constep-by-ste angle and t Course Ou Upon comp CO1 CO2 CO3 | stant- Swing equation of single-machine connected to infinite bus – Solution of Sight provention and the student's method – Runge-Kutta method – Equal area criterion ime -Factors affecting transient stability – Techniques for transient stability improves Total (45 tecomes: Deletion of this course, the students will be able to: Develop the single line diagram for the power system. Perform and analyze load flow computations using bus admittance matrix Perform and analyze balanced fault using bus impedance matrix | wing equation by – Critical clearing ment. 5+0)= 45 Periods |
| Inertia con step-by-ste angle and t Course Ou Upon comp CO1 CO2 CO3 CO3 CO4 | stant- Swing equation of single-machine connected to infinite bus – Solution of Sp p method-II – Modified Euler's method – Runge-Kutta method – Equal area criterion ime -Factors affecting transient stability – Techniques for transient stability improve Total (45 stcomes: eletion of this course, the students will be able to: : Develop the single line diagram for the power system. : Perform and analyze load flow computations using bus admittance matrix : Perform and analyze balanced fault using bus impedance matrix : Develop computational models for unsymmetrical fault analysis in power system | wing equation by – Critical clearing ment. 5+0)= 45 Periods |
| Inertia constep-by-ste angle and t Course Ou Upon comp CO1 CO2 CO3 | stant- Swing equation of single-machine connected to infinite bus – Solution of Sight provention and the student's method – Runge-Kutta method – Equal area criterion ime -Factors affecting transient stability – Techniques for transient stability improves Total (45 tecomes: Deletion of this course, the students will be able to: Develop the single line diagram for the power system. Perform and analyze load flow computations using bus admittance matrix Perform and analyze balanced fault using bus impedance matrix | wing equation by – Critical clearing ment. 5+0)= 45 Periods |
| Inertia con step-by-ste angle and t Course Ou Upon comp CO1 CO2 CO3 CO4 CO5 | stant- Swing equation of single-machine connected to infinite bus – Solution of Sp p method-II – Modified Euler's method – Runge-Kutta method – Equal area criterion ime -Factors affecting transient stability – Techniques for transient stability improves Total (48 tecomes: Develop the single line diagram for the power system. Perform and analyze load flow computations using bus admittance matrix Perform and analyze balanced fault using bus impedance matrix Develop computational models for unsymmetrical fault analysis in power system Understand the transient stability studies. | wing equation by – Critical clearing ment. 5+0)= 45 Periods |
| Inertia con step-by-ste angle and t Course Ou Upon comp CO1 CO2 CO3 CO4 CO5 Text Book | stant- Swing equation of single-machine connected to infinite bus – Solution of Sp p method-II – Modified Euler's method – Runge-Kutta method – Equal area criterion ime -Factors affecting transient stability – Techniques for transient stability improves Total (45 tecomes: Develop the single line diagram for the power system. Perform and analyze load flow computations using bus admittance matrix Perform and analyze balanced fault using bus impedance matrix Develop computational models for unsymmetrical fault analysis in power system Understand the transient stability studies. s: | wing equation by – Critical clearing ment. 5+0)= 45 Periods ns |
| Inertia constep-by-step-angle and to angle | stant- Swing equation of single-machine connected to infinite bus – Solution of Sp p method-II – Modified Euler's method – Runge-Kutta method – Equal area criterion ime -Factors affecting transient stability – Techniques for transient stability improver Total (45 tcomes: eletion of this course, the students will be able to: : Develop the single line diagram for the power system. : Perform and analyze load flow computations using bus admittance matrix : Perform and analyze balanced fault using bus impedance matrix : Develop computational models for unsymmetrical fault analysis in power system : Understand the transient stability studies. s: Hadi Saadat, "Power System Analysis", Tata McGraw Hill Publishers, New Delhi, | wing equation by – Critical clearing ment. 5+0)= 45 Periods IS 21 st reprint 2010 |
| Inertia con step-by-ste angle and t Course Ou Upon comp CO1 CO2 CO3 CO4 CO5 Text Book | stant- Swing equation of single-machine connected to infinite bus – Solution of Sp p method-II – Modified Euler's method – Runge-Kutta method – Equal area criterion ime -Factors affecting transient stability – Techniques for transient stability improver Total (4 tcomes: eletion of this course, the students will be able to: : Develop the single line diagram for the power system. : Perform and analyze load flow computations using bus admittance matrix : Perform and analyze balanced fault using bus impedance matrix : Develop computational models for unsymmetrical fault analysis in power system : Understand the transient stability studies. s: Hadi Saadat, "Power System Analysis", Tata McGraw Hill Publishers, New Delhi, D.P.Kothari, and I.J.Nagrath, "Modern Power System Analysis", Tata McGra | wing equation by – Critical clearing ment. 5+0)= 45 Periods IS 21 st reprint 2010 |
| Inertia constep-by-ste angle and t Course Ou Upon comp CO1 CO2 CO3 CO4 CO5 Text Book 1. 2. | stant- Swing equation of single-machine connected to infinite bus – Solution of Sip p method-II – Modified Euler's method – Runge-Kutta method – Equal area criterion ime -Factors affecting transient stability – Techniques for transient stability improve Total (4 tcomes: eletion of this course, the students will be able to: Develop the single line diagram for the power system. Perform and analyze load flow computations using bus admittance matrix Perform and analyze balanced fault using bus impedance matrix Develop computational models for unsymmetrical fault analysis in power system Understand the transient stability studies. s: Hadi Saadat, "Power System Analysis", Tata McGraw Hill Publishers, New Delhi, D.P.Kothari, and I.J.Nagrath, "Modern Power System Analysis", Tata McGra Private limited, New Delhi, Fourth Edition, 2011. | wing equation by – Critical clearing ment. 5+0)= 45 Periods IS 21 st reprint 2010 |
| Inertia con step-by-ste angle and t Course Ou Upon comp CO1 CO2 CO3 CO4 CO5 Text Book 1. 2. Reference | stant- Swing equation of single-machine connected to infinite bus – Solution of Sip p method-II – Modified Euler's method – Runge-Kutta method – Equal area criterion ime -Factors affecting transient stability – Techniques for transient stability improve Total (4 tecomes: | wing equation by – Critical clearing ment. 5+0)= 45 Periods 15 15 15 15 15 15 15 15 15 15 |
| Inertia constep-by-ste angle and t Course Ou Upon comp CO1 CO2 CO3 CO4 CO5 Text Book 1. 2. | stant- Swing equation of single-machine connected to infinite bus – Solution of Sip method-II – Modified Euler's method – Runge-Kutta method – Equal area criterion ime -Factors affecting transient stability – Techniques for transient stability improves Total (45 tcomes: Develop the single line diagram for the power system. Perform and analyze load flow computations using bus admittance matrix Perform and analyze balanced fault using bus impedance matrix Perform and analyze balanced fault using bus impedance matrix Develop computational models for unsymmetrical fault analysis in power system Understand the transient stability studies. s: Hadi Saadat, "Power System Analysis", Tata McGraw Hill Publishers, New Delhi, D.P.Kothari, and I.J.Nagrath, "Modern Power System Analysis", Tata McGra Private limited, New Delhi, Fourth Edition, 2011. Books: John J. Grainger and W.D. Stevenson Jr., "Power System Analysis", McGraw Hil | wing equation by – Critical clearing ment. 5+0)= 45 Periods 15 15 15 15 15 15 15 15 15 15 |
| Inertia constep-by-ste angle and t Course Ou Upon comp CO1 CO2 CO3 CO4 CO5 Text Book 1. 2. Reference 1. | stant- Swing equation of single-machine connected to infinite bus – Solution of Sip method-II – Modified Euler's method – Runge-Kutta method – Equal area criterion ime -Factors affecting transient stability – Techniques for transient stability improved Total (45 tecomes: Develop the single line diagram for the power system. Perform and analyze load flow computations using bus admittance matrix Perform and analyze balanced fault using bus impedance matrix Develop computational models for unsymmetrical fault analysis in power system Understand the transient stability studies. Hadi Saadat, "Power System Analysis", Tata McGraw Hill Publishers, New Delhi, D.P.Kothari, and I.J.Nagrath, "Modern Power System Analysis", Tata McGra Private limited, New Delhi, Fourth Edition, 2011. Books: John J. Grainger and W.D. Stevenson Jr., "Power System Analysis", McGraw Hil 2017. | wing equation by – Critical clearing ment. 5+0)= 45 Periods 15 21 st reprint 2010 W Hill Education II Inc., New Delhi, |
| Inertia constep-by-ste angle and t Course Ou Upon comp CO1 CO2 CO3 CO4 CO5 Text Book 1. 2. Reference | stant- Swing equation of single-machine connected to infinite bus – Solution of Sip method-II – Modified Euler's method – Runge-Kutta method – Equal area criterion ime -Factors affecting transient stability – Techniques for transient stability improves Total (45 tcomes: Develop the single line diagram for the power system. Perform and analyze load flow computations using bus admittance matrix Perform and analyze balanced fault using bus impedance matrix Perform and analyze balanced fault using bus impedance matrix Develop computational models for unsymmetrical fault analysis in power system Understand the transient stability studies. s: Hadi Saadat, "Power System Analysis", Tata McGraw Hill Publishers, New Delhi, D.P.Kothari, and I.J.Nagrath, "Modern Power System Analysis", Tata McGra Private limited, New Delhi, Fourth Edition, 2011. Books: John J. Grainger and W.D. Stevenson Jr., "Power System Analysis", McGraw Hil | wing equation by – Critical clearing ment. 5+0)= 45 Periods 15 21 st reprint 2010 W Hill Education II Inc., New Delhi, hi, 2012 |

| E-References | i |
|--------------|---|
| 1. | https://onlinecourses.nptel.ac.in/, for power system analysis course, IIT Kharagpur |
| 2. | NPTEL courses on Power System Generation, Transmission and Distribution, IIT Delhi. |

| PO CO | PO1 | PO2 | PO3 | PO 4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO 10 | PO 11 | PO 12 |
|----------|-----|-----|-----|---------|-----|-----|-----|-----|-----|----------|----------|----------|
| CO1 | 2 | 1 | 3 | 1 | 3 | | 1 | | | | | |
| CO2 | 2 | 2 | 3 | 2 | 3 | | 1 | | | | | |
| CO3 | 2 | 2 | 3 | 2 | 3 | | 1 | | | | | |
| CO4 | 2 | 2 | 3 | 2 | 3 | | 1 | | | | | |
| CO5 | 2 | 2 | 3 | 2 | 3 | | 1 | | | | | |

| 18EE602 | ELECTRICAL DRIVES AND CONTROL | L | Т | Ρ | С | | | |
|---------------------------|--|---------------|--------------|--------------|------------|--|--|--|
| | | 3 | 0 | 0 | 3 | | | |
| Course Ob | ectives: | | | | | | | |
| 1. | To know about the Analyze the operation of the chopper fed dc drive, both quali quantitatively. | tative | ely a | nd | | | | |
| 2. | To understand the Operation and performance of AC motor drives. | | | | | | | |
| | | | • | | • | | | |
| | DC MOTOR CHARACTERISTICS & CHOPPER FED DC DRIVES | | 9 | + | 0 | | | |
| armature v varying mot | corque-speed characteristics of separately excited dc motor, change in torque-spltage, exampleload torque-speed characteristics, operating point, armature volorspeed. Review of dc chopper and duty ratio control, chopper fed dc motor for speed on of a chopper fed drive, armature current waveform and ripple, calculation of los | tage d cor | con trol, | trol stea | for ady | | | |
| | MULTI-QUADRANT & CLOSED-LOOP CONTROL OF DC DRIVE | | 9 | + | 0 | | | |
| Control strue | our quadrant operation of dc machine; single-quadrant, two-quadrant and four-quacture of DC drive, inner current loop and outer speed loop, dynamic model of dc n nd transfer functions, modeling of chopper as gain with switching delay, plant tr roller specification and design, speed controller specification and design. | notor | – d | yna | mic | | | |
| | INDUCTION MOTOR CHARACTERISTICS | | 9 | + | 0 | | | |
| - | iduction motor equivalent circuit and torque-speed characteristic, variation of torc | ue-s | - | - | rve | | | |
| with (i) appl | ed voltage, (ii) applied frequency and (iii) applied voltage and frequency, typical torquump loads, operating point, constant flux operation, flux weakening operation. | | | | | | | |
| UNIT IV | SCALAR CONTROL OR CONSTANT V/F CONTROL OF INDUCTION MOTOR | 2 | 9 | + | 0 | | | |
| | ree-phase voltage source inverter, generation of three-phase PWM signals, sinusoid | | | | | | | |
| | r theory, conventional space vector modulation; constant V/f control of induction mot analysis based on equivalent circuit, speed drop with loading, slip regulation. | or, si | ead | y-sta | ate | | | |
| UNIT V | CONTROL OF SLIP RING INDUCTION MOTOR | | 9 | + | 0 | | | |
| | or resistance of the induction motor torque-speed curve, operation of slip-ring indu- r resistance, starting torque, power electronic based rotor side control of slip ring mo | otor, | slip | woc | er | | | |
| Course out | Total (45- | ⊦0)= | 45 F | Perio | bds | | | |
| Courseou | comes. | | | | | | | |
| | etion of this course, the students will be able to: | | | | | | | |
| CO1 | : Understand the characteristics of dc motors and induction motors. | | | | | | | |
| CO2 | : Understand the principles of speed-control of dc motors and induction motors. | | | | | | | |
| CO3 | : Understand the power electronic converters used for dc motor and induction mc control. | tor s | peed | Ż | | | | |
| CO4 | : Gain knowledge on the Scalar control or constant V/f control of induction motor | | | | | | | |
| CO5 | : Gain knowledge on chopper fed DC drives. | | | | | | | |
| Text Books | | | | | | | | |
| 1. | G. K. Dubey, "Power Semiconductor Controlled Drives", Prentice Hall, 1989. | | | | | | | |
| 2. | R. Krishnan, "Electric Motor Drives: Modeling, Analysis and Control", Prentice H | all,20 |)15 | | | | | |
| Reference | Books: | | | | | | | |
| 1. | G. K. Dubey, "Fundamentals of Electrical Drives", CRC Press, 2010. | | | | | | | |
| 2. | W. Leonhard, "Control of Electric Drives", Springer Science & Business Media, 2001. | | | | | | | |
| E-reference | | | | | | | | |
| 1 | https://www.iith.ac.in/~ketan/drives.htmL | | | | | | | |
| • | | | | | | | | |

| PO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 3 | 1 | 3 | | | 2 | 1 | 1 | | | 1 | 2 |
| CO2 | 3 | 3 | 1 | 3 | | 1 | 1 | 1 | | | | 1 |
| CO3 | 3 | 3 | 3 | 3 | 3 | 1 | 1 | 1 | | | | 1 |
| CO4 | 1 | 3 | 3 | 2 | 3 | 1 | 1 | 1 | | | | 1 |
| CO5 | 3 | 3 | 3 | 3 | 3 | 1 | 1 | 1 | | | 1 | 1 |

| 18EE603 | PROFESSIONAL ETHICS AND HUMAN VALUES | L | ΤP | С |
|--|--|---|--------------------------------------|------------------------------|
| Course | Dbjectives: | 3 | 0 0 | 3 |
| | To create awareness on Engineering Ethics and providing basic knowledge about e | nginee | ring | |
| 1. | Ethics, Variety of moral issues and Professional Ideals. | • | • | |
| 2. | To provide basic familiarity about Engineers as responsible Experimenters, Codes Industrial Standards. | of Ethic | S, | |
| 3. | To inculcate knowledge and exposure on Safety and Risk, Risk Benefit Analysis. | | | |
| | | | | |
| UNIT I | HUMAN VALUES | | 9 + | 0 |
| Living Pe | 'alues and Ethics – Integrity – Work Ethic – Service Learning – Civic Virtue – Respect acefully – caring – Sharing – Honesty – Courage – Valuing Time – Co-operation – Co – Self-Confidence – Character – Spirituality. | | | |
| | ENGINEERING ETHICS | | 9 + | 0 |
| Senses of Kohlberg | f 'Engineering Ethics' - variety of moral issued - types of inquiry - moral dilemmas - mo 's theory - Gilligan's theory - consensus and controversy – Models of Professional Rol ht action – Self-interest- customs and religion - uses of ethical theories. | oral auto | onomy | |
| | ENGINEERING AS SOCIAL EXPERIMENTATION | | 9 + | 0 |
| | ing as experimentation - engineers as responsible experimenters - codes of ethics - a | balance | - | - |
| | the challenger case study. | ouluito | a out | |
| | | T | • | |
| | SAFETY, RESPONSIBILITIES AND RIGHTS and risk - assessment of safety and risk - risk benefit analysis and reducing risk - the thr | | 9 + | 0 |
| | of interest – occupational crime - professional rights - employee rights - Intellectual Pi | g - conf operty | | |
| (IPR) - di | scrimination. | | Rights | |
| (IPR) - di UNIT V | Scrimination. | operty | Rights | |
| (IPR) - di UNIT V Multination manager Ethics lik | scrimination. | nginee | Rights 9 + 's as code | 0 |
| (IPR) - di UNIT V Multination manager Ethics lik | GLOBAL ISSUES onal corporations - Environmental ethics - computer ethics - weapons development - e s consulting engineers-engineers as expert witnesses and advisors -moral leadership- e ASME,ASCE, IEEE, Institution of Engineers (India), Indian Institute of Materials Man of electronics and telecommunication engineers (IETE),India. | operty nginee sample ageme | Rights 9 + 's as code nt, | 0 |
| (IPR) - di UNIT V Multination manager Ethics lik Institution | GLOBAL ISSUES onal corporations - Environmental ethics - computer ethics - weapons development - e s consulting engineers-engineers as expert witnesses and advisors -moral leadership- e ASME,ASCE, IEEE, Institution of Engineers (India), Indian Institute of Materials Man of electronics and telecommunication engineers (IETE),India. Total (45) | operty nginee sample ageme | Rights 9 + 's as code nt, | 0 |
| (IPR) - di UNIT V Multination manager Ethics lik Institution Course (| Scrimination. GLOBAL ISSUES onal corporations - Environmental ethics - computer ethics - weapons development - e s consulting engineers-engineers as expert witnesses and advisors -moral leadership- e ASME,ASCE, IEEE, Institution of Engineers (India), Indian Institute of Materials Man n of electronics and telecommunication engineers (IETE),India. Total (4 Dutcomes: | operty nginee sample ageme | Rights 9 + 's as code nt, | 0 |
| (IPR) - di UNIT V Multination manager Ethics lik Institution Course (Upon cor | Scrimination. GLOBAL ISSUES onal corporations - Environmental ethics - computer ethics - weapons development - e s consulting engineers-engineers as expert witnesses and advisors -moral leadership- e ASME,ASCE, IEEE, Institution of Engineers (India), Indian Institute of Materials Man n of electronics and telecommunication engineers (IETE),India. Total (4: Dutcomes: n pletion of this course, the students will be able to: | operty nginee sample ageme | Rights 9 + 's as code nt, | 0 |
| (IPR) - di UNIT V Multination Ethics lik Institution Course (Upon cor CO1 CO2 | Scrimination. GLOBAL ISSUES onal corporations - Environmental ethics - computer ethics - weapons development - e s consulting engineers-engineers as expert witnesses and advisors -moral leadership- e ASME,ASCE, IEEE, Institution of Engineers (India), Indian Institute of Materials Man n of electronics and telecommunication engineers (IETE),India. Total (4 Dutcomes: | operty nginee sample ageme | Rights 9 + 's as code nt, | 0 |
| (IPR) - di UNIT V Multination Ethics lik Institution Course (Upon cor CO1 CO2 CO3 | GLOBAL ISSUES onal corporations - Environmental ethics - computer ethics - weapons development - etails of sconsulting engineers-engineers as expert witnesses and advisors -moral leadership-eta ASME, ASCE, IEEE, Institution of Engineers (India), Indian Institute of Materials Manno of electronics and telecommunication engineers (IETE), India. Total (4: Outcomes: inpletion of this course, the students will be able to: : Understand the importance of ethics and values in life and society. : Understood the core values that shape the ethical behavior of an engineer. : Expose awareness on professional ethics and human values. | operty nginee sample ageme | Rights 9 + 's as code nt, | 0 |
| (IPR) - di UNIT V Multinatio manager Ethics lik Institution Course (Upon cor CO1 CO2 CO3 CO4 | Scrimination. GLOBAL ISSUES onal corporations - Environmental ethics - computer ethics - weapons development - e s consulting engineers-engineers as expert witnesses and advisors -moral leadership- e ASME,ASCE, IEEE, Institution of Engineers (India), Indian Institute of Materials Man n of electronics and telecommunication engineers (IETE),India. Total (4! Outcomes: n pletion of this course, the students will be able to: : Understand the importance of ethics and values in life and society. : Understood the core values that shape the ethical behavior of an engineer. : Expose awareness on professional ethics and human values. : Analyse a person based on human value concepts | operty nginee sample ageme | Rights 9 + 's as code nt, | 0 |
| (IPR) - di UNIT V Multination Ethics lik Institution Course O Upon cor CO1 CO2 CO3 | GLOBAL ISSUES onal corporations - Environmental ethics - computer ethics - weapons development - etails of sconsulting engineers-engineers as expert witnesses and advisors -moral leadership-eta ASME, ASCE, IEEE, Institution of Engineers (India), Indian Institute of Materials Manno of electronics and telecommunication engineers (IETE), India. Total (4: Outcomes: inpletion of this course, the students will be able to: : Understand the importance of ethics and values in life and society. : Understood the core values that shape the ethical behavior of an engineer. : Expose awareness on professional ethics and human values. | operty nginee sample ageme | Rights 9 + 's as code nt, | 0 |
| (IPR) - di UNIT V Multination Ethics lik Institution Course (Upon cor CO1 CO2 CO3 CO4 | Scrimination. | nginee sample ageme | Rights 9 + 's as code nt, 45 Per | 0 |
| (IPR) - di UNIT V Multination Ethics lik Institution Course (Upon cor CO1 CO2 CO3 CO4 CO5 | GLOBAL ISSUES onal corporations - Environmental ethics - computer ethics - weapons development - e s consulting engineers-engineers as expert witnesses and advisors -moral leadership- e ASME,ASCE, IEEE, Institution of Engineers (India), Indian Institute of Materials Mann of electronics and telecommunication engineers (IETE),India. Total (44 Dutcomes: npletion of this course, the students will be able to: : Understand the importance of ethics and values in life and society. : Understood the core values that shape the ethical behavior of an engineer. : Expose awareness on professional ethics and human values. : Analyse a person based on human value concepts : Analyse our responsibility and rights to social problems oks: Mike Martin and Roland Schinzinger, "Ethics in Engineering", McGraw-Hill, New Yor | operty nginee sample ageme 5+0) = 4 | Rights 9 + 's as code nt, 45 Per . | 0 of iod |
| (IPR) - di UNIT V Multination manager Ethics lik Institution Course (Upon cor CO1 CO2 CO3 CO3 CO3 CO4 CO5 Text Boo | Scrimination. | operty nginee sample ageme 5+0) = 4 | Rights 9 + 's as code nt, 45 Per . | 0 of iod |
| (IPR) - di UNIT V Multination manager Ethics lik Institution Course (Upon cor CO1 CO2 CO3 CO4 CO5 Text Boo 1. 2. | Scrimination. GLOBAL ISSUES onal corporations - Environmental ethics - computer ethics - weapons development - e s consulting engineers-engineers as expert witnesses and advisors -moral leadership- e ASME,ASCE, IEEE, Institution of Engineers (India), Indian Institute of Materials Man of electronics and telecommunication engineers (IETE),India. Total (44 Dutcomes: mpletion of this course, the students will be able to: : Understand the importance of ethics and values in life and society. : Understood the core values that shape the ethical behavior of an engineer. : Expose awareness on professional ethics and human values. : Analyse a person based on human value concepts : Analyse our responsibility and rights to social problems oks: Mike Martin and Roland Schinzinger, "Ethics in Engineering", McGraw-Hill, New Yor Govindarajan M, Natarajan S, Senthil Kumar V. S, "Engineering Ethics", Prentice H Delhi, 2004. EBooks: | operty nginee sample ageme 5+0) = 4 | Rights 9 + 's as code nt, 45 Per . | of iod |
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| (IPR) - di UNIT V Multination Ethics lik Institution Course (Upon cor CO1 CO2 CO3 CO4 CO5 Text Boo 1. 2. Reference | scrimination. GLOBAL ISSUES onal corporations - Environmental ethics - computer ethics - weapons development - e s consulting engineers-engineers as expert witnesses and advisors -moral leadership-e e ASME,ASCE, IEEE, Institution of Engineers (India), Indian Institute of Materials Mann of electronics and telecommunication engineers (IETE),India. Total (4! Dutcomes: mpletion of this course, the students will be able to: Understand the importance of ethics and values in life and society. Understand the core values that shape the ethical behavior of an engineer. Expose awareness on professional ethics and human values. Analyse a person based on human value concepts Analyse our responsibility and rights to social problems oks: Mike Martin and Roland Schinzinger, "Ethics in Engineering", McGraw-Hill, New Yoi Govindarajan M, Natarajan S, Senthil Kumar V. S, "Engineering Ethics", Prentice H Delhi, 2004. Ce Books: Tripathi A N, "Human values", New Age international Pvt. Ltd., New Delhi, 2002. Charles D. Fleddermann, "Engineering Ethics", Pearson Education / Prentice Hall, I | operty nginee sample ageme 5+0) = - | Rights 9 + 's as code nt, 45 Per | 0 of iod |
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| CO PO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO 10 | PO 11 | PO 12 |
|-------|-----|-----|-----|-----|-----|-----|-----|-----|-----|----------|----------|----------|
| CO1 | | | 2 | | | 3 | | 3 | 2 | | | 3 |
| CO2 | | | 2 | | | 3 | | 3 | 1 | | | 2 |
| CO3 | | | 2 | | | 2 | | 3 | | | | 2 |
| CO4 | | | 2 | | | 3 | | 3 | 1 | 1 | | 2 |
| CO5 | | | 2 | | | 2 | | 2 | | 1 | | 2 |

| 18EN501 | COMMUNICATION SKILLS LABORATORY | L | Т | Ρ |
|--------------------------|--|----------|-------|------|
| | | 0 | 0 | 2 |
| Course Obj | ectives: | | | |
| 1. | Communicate effectively with interviewers | | | |
| 2. | Express opinions, illustrate with examples, elucidate and conclude in group di | scussior | าร | |
| 3 | Write error free letters and prepare reports | | | |
| 4 | Speak fluently and avoid pitfalls in pronunciation and grammatical errors | | | |
| WRITING S | KILLS | (1 | 5 ho | urs) |
| Lett | er seeking permission to go on industrial visit | | | |
| Lett | er of invitation | | | |
| Res | ume and Cover Letter | | | |
| • Rep | ort Writing – Progress in project work | | | |
| SPEAKING | SKILLS | (15 | i hou | urs) |
| | come Address and Vote of Thanks | (| | , |
| | lysing and presenting business articles | | | |
| | ver Point Presentation | | | |
| | up Discussion | | | |
| 2.0 | | | | |
| SOFT SKIL | LS | (1 | 5 ho | urs) |
| Psy | chometric profile | • | | |
| • | -Introduction | | | |
| Inte | rview skills | | | |
| • Con | ducting a board meeting | | | |
| | BILITIES | (1 | 5 ho | urs) |
| • Erro | or Spotting | • | | , |
| | ening Comprehension | | | |
| | Irranging Jumbled sentences | | | |
| | abulary | | | |
| _ab Record | | | | |
| | roup Discussion - Literature survey | | | |
| | roup Discussion - Transcripts | | | |
| | roup Discussion - Assessment forms | | | |
| 4. In | terview Skills – Psychometric profile | | | |
| 5. In | terview Skills - Self-introduction | | | |
| | terview Skills – Resume and Cover Letter | | | |
| | terview Skills - Transcription of interview | | | |
| | terview Skills - Assessment sheet signed by interview panel | | | |
| - | ower Point Presentation | | | |
| | rror spotting worksheet | | | |
| | umbled sentences worksheet | | | |
| | elcome Address | | | |
| | ote of Thanks | | | |
| | etter seeking permission to go on industrial visit | | | |
| | eport Writing – Progress in project work resentation of business articles - Transcription | | | |
| IU. FI | | | | |
| | | (0.20) | 20 5 |)! - |
| | Iotal | (0+30)= | 30 F | eric |

| Course C | Duto | comes: |
|----------|------|--|
| Upon com | nple | tion of this course, the students will be able to: |
| CO1 | : | Write error free letters and prepare reports |
| CO2 | : | Deliver welcome address and vote of thanks |
| CO3 | : | Speak coherently with proper pronunciation and accent |
| CO4 | : | Avoid common Indianisms and grammatical errors |
| CO5 | : | Improve repertoire of passive vocabulary |
| CO6 | : | Answer questions posed by interviewers confidently |
| CO7 | : | Participate in group discussion effectively |
| CO8 | : | Undertake online psychometric and IQ test to understand their strengths and weaknesses |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | | 1 | | | | 2 | | 1 | 3 | 3 | 1 | 2 |
| CO2 | 1 | 3 | | 1 | | | | 1 | 1 | 3 | 1 | 3 |
| CO3 | | 1 | | 3 | | 1 | | 2 | 1 | 3 | 1 | 2 |
| CO4 | | 1 | | 1 | | 2 | | | 1 | 3 | | 3 |
| CO5 | | | | 2 | | | | 1 | | 3 | 2 | 3 |
| CO6 | | 1 | | 1 | | 1 | | 1 | 1 | 3 | 1 | 2 |
| C07 | | | | 1 | | 1 | | 2 | 2 | 3 | 1 | 2 |
| CO8 | 1 | 2 | | 2 | | 1 | | | | 3 | | 2 |

| Course Objectives: 1. To know about the power system protection and switchgear components. 2. To understand the concepts of various protection schemes. 3. To know about numerical protection schemes. Unit I PROTECTIVE RELAYS Functional characteristics of a protective relay – Operating principles of relays Instantaneous and time over current relays - Definite time and inverse time characteri relay – Directional overcurrent relay - Universal torque equation - Performance characteristics - Differential relays - Under frequency and over frequency relays - Translay relays. Unit II CIRCUIT BREAKERS Arc in oil - Arc interruption – Current chopping - Bulk oil and minimum oil circuit breakers - Vacuum circuit breakers - SF6 circuit breakers - Rating of circuit breakers – Autoreclosure. HVDC circuit breakers - Energy consideration in the Commutating principle - Control of di/dt and dv/dt - Surge suppression - Main ci switching. Unit III EQUIPMENT PROTECTION SCHEMES Feeder protection - Distance protection – Alternator protection - Short circuit protect percentage differential relays - Protection against turn to turn faults in stator win protection - Protection of stator windings by overvoltage relays - Protection against st synchronism, loss of excitation, rotor overheating - Protection of transformers - Type | 9 + 0 - Over current relays – stics - Direct over current aracteristics of distance scheme - HRC fuses for 9 + 0 er – Air circuit breakers - Testing of breaking. HVDC system - rcuit breakers for HVDC 9 + 0 oreaking. HVDC system - rcuit breakers for HVDC 9 + 0 ion of stator windings by ding - Field ground fault |
|--|---|
| 1. To know about the power system protection and switchgear components. 2. To understand the concepts of various protection schemes. 3. To know about numerical protection schemes. Unit I PROTECTIVE RELAYS Functional characteristics of a protective relay – Operating principles of relays Instantaneous and time over current relays - Definite time and inverse time characteristic relay – Directional overcurrent relay - Universal torque equation - Performance characteristics - Differential relays - Under frequency and over frequency relays - Translay relays. Unit II CIRCUIT BREAKERS Arc in oil - Arc interruption – Current chopping - Bulk oil and minimum oil circuit break Air blast circuit breakers - Vacuum circuit breakers - SF6 circuit breakers - Rating of circuit breakers – Autoreclosure. HVDC circuit breakers - Energy consideration in the Commutating principle - Control of di/dt and dv/dt - Surge suppression - Main ci switching. Unit III EQUIPMENT PROTECTION SCHEMES Feeder protection - Distance protection – Alternator protection - Short circuit protect percentage differential relays - Protection against turn to turn faults in stator winprotection - Protection of stator windings by overvoltage relays - Protection against st | 9 + 0 - Over current relays – stics - Direct over current aracteristics of distance scheme - HRC fuses for 9 + 0 er – Air circuit breakers - Testing of breaking. HVDC system - rcuit breakers for HVDC 9 + 0 oreaking. HVDC system - rcuit breakers for HVDC 9 + 0 oreaking. HVDC system - rcuit breakers for HVDC 9 + 0 ion of stator windings by ding - Field ground fault |
| 2. To understand the concepts of various protection schemes. 3. To know about numerical protection schemes. Unit I PROTECTIVE RELAYS Functional characteristics of a protective relay – Operating principles of relays Instantaneous and time over current relays - Definite time and inverse time characteri relay – Directional overcurrent relay - Universal torque equation - Performance characteristics - Differential relays - Under frequency and over frequency relays - Translay relays. Unit II CIRCUIT BREAKERS Arc in oil - Arc interruption – Current chopping - Bulk oil and minimum oil circuit breakers - Nature closure. HVDC circuit breakers - SF6 circuit breakers - Rating of circuit breakers – Autoreclosure. HVDC circuit breakers - Energy consideration in the Commutating principle - Control of di/dt and dv/dt - Surge suppression - Main ci switching. Unit III EQUIPMENT PROTECTION SCHEMES Feeder protection - Distance protection – Alternator protection - Short circuit protection percentage differential relays - Protection against turn to turn faults in stator win protection - Protection of stator windings by overvoltage relays - Protection against st | 9 + 0 - Over current relays – stics - Direct over current aracteristics of distance scheme - HRC fuses for 9 + 0 g + 0 xer – Air circuit breakers - Testing of preaking. HVDC system - rcuit breakers for HVDC 9 + 0 oreaking. HVDC system - rcuit breakers for HVDC yeakers for HVDC system - yeakers for HVDC |
| 3. To know about numerical protection schemes. Unit I PROTECTIVE RELAYS Functional characteristics of a protective relay – Operating principles of relays Instantaneous and time over current relays - Definite time and inverse time characteri relay – Directional overcurrent relay - Universal torque equation - Performance characteristics. relays - Differential relays - Under frequency and over frequency relays - Translay relays. Unit II CIRCUIT BREAKERS Arc in oil - Arc interruption – Current chopping - Bulk oil and minimum oil circuit breakers - Nature closure. HVDC circuit breakers - SF6 circuit breakers - Rating of circuit breakers – Autoreclosure. HVDC circuit breakers - Energy consideration in the Commutating principle - Control of di/dt and dv/dt - Surge suppression - Main ci switching. Unit III EQUIPMENT PROTECTION SCHEMES Feeder protection - Distance protection – Alternator protection - Short circuit protect percentage differential relays - Protection against turn to turn faults in stator win protection - Protection of stator windings by overvoltage relays - Protection against st | Over current relays – stics - Direct over current aracteristics of distance scheme - HRC fuses for 9 + 0 er – Air circuit breakers - rcuit breakers - Testing of breaking. HVDC system - rcuit breakers for HVDC 9 + 0 ion of stator windings by ding - Field ground fault |
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| Feeder protection - Distance protection – Alternator protection - Short circuit protect percentage differential relays - Protection against turn to turn faults in stator win protection - Protection of stator windings by overvoltage relays - Protection against st | ion of stator windings by ding - Field ground fault |
| Feeder protection - Distance protection – Alternator protection - Short circuit protect percentage differential relays - Protection against turn to turn faults in stator win protection - Protection of stator windings by overvoltage relays - Protection against st | ion of stator windings by ding - Field ground fault |
| | |
| Unit IV STATIC RELAYS | 9 + 0 |
| Introduction - Advantages of static relays - Basic construction - Phase and amplitudirectional relay - Directional overcurrent relay - Static differential relays and differentiated and | |
| Unit V NUMERICAL PROTECTION | 9 + 0 |
| Introduction – Block diagram – Sampling theorem – Fourier analysis of analogue signatechnique – Digital filtering – Over current protection – Differential protection – Distant | |
| | Total (45+0)= 45 Periods |
| Course Outcomes: | |
| Upon completion of this course, the students will be able to: | |
| CO1 : Understand the concepts and applications of protective relays. | |
| CO2 : Acquire knowledge about different types of circuit breakers | |
| CO3 : Understand the protection schemes of various power components. | |
| CO4 : Understand numerical protection schemes. | |
| CO5 : Design protection scheme for any electrical system | |
| Text Books: | |
| 1. Badri Ram and Vishwakarma, "Power System Protection and Switchg 2017,2 nd edition. | jear", Tata McGraw Hill, |
| 2. Arun Ingole, "Switchgear and Protection", Pearson India, 2018. | |
| Reference Books: | |
| 1. Rao, T. S. M, "Power System Protection Static Relays with Microprocess McGraw-Hill, 2017,2 nd edition. | •• |
| Paithankar, Y. G and Bhide, S. R, "Fundamentals of Power System Pro- 2013. | tection", Prentice Hall, |

| 3. | Uppal, S.L, "Electrical Power", Khanna Publishers, New Delhi, 2019. |
|-------------|---|
| 4. | Ravindranath. B and Chander, N, "Power System Protection and Switchgear", New Age International, 2018, 2 nd edition. |
| E-Reference | ces: |
| 1. | NPTEL Course: Power System Protection - Prof. S.A. Soman, IIT-B. |
| 2. | |
| | NPTEL Course: Power System Protection – organized by IIT-B. |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 2 | 1 | 2 | 2 | 1 | 2 | 3 | 2 | 1 | 2 | 3 | 2 |
| CO2 | 1 | 1 | 3 | 2 | 2 | 1 | 3 | 2 | 2 | 2 | 2 | 2 |
| CO3 | 2 | 2 | 2 | 3 | 1 | 2 | 3 | 3 | 1 | 2 | 3 | 1 |
| CO4 | 2 | 1 | 1 | 2 | 3 | 1 | 3 | 2 | 3 | 2 | 2 | 2 |
| CO5 | 1 | 1 | 2 | 1 | 2 | 2 | 3 | 3 | 2 | 3 | 2 | 1 |

| 18EE70 | INDUSTRIAL MANAGEMENT AND ECONOMICS | L | т | Р | С |
|-----------|---|--------------|-------------|--------|--------|
| | | 3 | 0 | 0 | 3 |
| Course | Dbjectives: | - | | - | |
| 1 | To understand the concept of management, economics and Indian financial system | | | | |
| | | | | | |
| Unit I | MODERN CONCEPT OF MANAGEMENT | | 9 | + | 0 |
| Scientif | management-Functions of management-Planning-Organising- Staffing-Direct | ing | - N | /lotiv | ating- |
| | icating- Co-ordinating- Controlling-Organisational structures- Line, Line and staft hips- Span of control- Delegation- Management by Objectives. | | | Fund | tional |
| Unit II | PERSONNEL MANAGEMENT | | 9 | + | 0 |
| | es and functions of personnel management- Recruitment-Selection and training of work | | | boui | • |
| | Industrial Fatigue- Industrial disputes-Trade Unions- Quality circles. Formation of comp ory-Partnership-Joint stock companies- Public sector- Joint sector and Co-operative sec | | | | |
| Unit III | MARKETING MANAGEMENT | | 9 | + | 0 |
| | Promotion- Channels of distribution- Market research-Advertising. Production Manage | | | | |
| only). | oduction- Inventory control- EOQ-Project planning by PERT/CPM- Construction of Network | NOI | к (D | asic | lueas |
| 0 | | | | | |
| Unit IV | BASICS OF ECONOMICS | | 9 | + | 0 |
| Theory of | f demand and supply- Price mechanism- Factors of production- Land, labour, capital | anc | oro | aniz | ation- |
| | income- Difficulties in estimation- Taxation- Direct and indirect taxes- Progressive and | | | | |
| money- | nflation-Causes and consequences. | | | | |
| | | | - | 1 | |
| Unit V | | | 9 | + | 0 |
| | bank of India: Functions- Commercial banking system-Development financial institut RBI- NABARD- Investment institutions-UTI- Insurance companies- Indian capital mark | | | | |
| | s- Role of the public sector- Privatisation- Multinational corporations and their impa | | | | |
| economy | | | | | nulan |
| | Total 4 | 5 . (| <u>م_</u> ۱ | 5 Dc | riada |
| Course | Dutcomes: | 0+C | J)=4 | эге | nous |
| | | | | | |
| | npletion of this course, the students will be able to : Understand the conceptsof managment | | | | |
| CO2 | : Understand various types of managment. | | | | |
| CO3 | : Understand the Indian economics | | | | |
| CO4 | : Manage an organization efficiently for its upliftment | | | | |
| CO5 | Apply marketing concept to any organization to earn more profit. | | | | |
| Text Bo | oks: | | | | |
| 1. | O P Khanna, "Industrial Management", Dhanpat Rai Publications,4 th edition, 1980. | | | | |
| 2. | Philip Kotler, Kevin Lane Keller, SweeHoon Ang, Chin Tiong Tan, Siew Meng Leong | , "N | /lark | eting | 3 |
| | Management: An Asian Perspective" Pearson Education Limited, 7th Edition, 2017 | | | | |
| 3 | A. N. Agrawal, "Indian Economy", Vikas Publishing House PVT, 4 th edition, 1978. | | | | |
| Referen | ce Books: | | | | |
| 1 | K. K. Ahuja, "Industrial management" Khanna Publishers, 1978. | | | | |
| | | | | | |
| 2 | K.K Dewett, Shyam Lal, "Modern economic theory" S Chand and Company Limited | 1, 2 | 800 | | |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | | | 1 | | | 2 | 1 | | 3 | 2 | 3 | 2 |
| CO2 | | | 1 | | | 2 | 1 | | 3 | 2 | 3 | 2 |
| CO3 | | | | 1 | | 1 | | 2 | | | | 1 |
| CO4 | | | 1 | | | 2 | | 1 | 3 | 2 | 3 | 2 |
| CO5 | | | 1 | | | 2 | | 1 | 3 | 2 | 3 | 2 |

| 18EE703 | POWER SYSTEMS LABORATORY | L | Т | Ρ | С |
|-------------|--|------|------|-------|------|
| | | 0 | 0 | 3 | 1.5 |
| Course Obje | ectives: | | | | |
| 1. | Hands - on and computational experiments related to various power system | m pr | oble | ms. | |
| 2. | Programming of numerical methods for solution of various power syste control problems. | em o | oper | atior | n an |
| xperiments | 3 | | | | |
| 1. | Formation of bus admittance matrix. | | | | |
| 2. | Bus impedance matrix formulation. | | | | |
| 3. | Load flow analysis using Gauss Seidel method. | | | | |
| 4. | Power flow analysis using Newton Raphson method. | | | | |
| 5. | Transient stability analysis: Single machine infinite bus system. | | | | |
| 6. | Transient stability analysis of multi machine power systems. | | | | |
| 7. | Load frequency control of single area and two area power systems. | | | | |
| 8. | Economic dispatch by lambda iteration method. | | | | |
| 9. | Solution to combined economic emission dispatch problems. | | | | |
| 10. | Thermal unit commitment using priority list method. | | | | |

| | | I otal (0+45) = 45 Periods | | | | | | | | |
|------------------|------|---|--|--|--|--|--|--|--|--|
| Course Outcomes: | | | | | | | | | | |
| Upon com | plet | tion of this course, the students will be able to | | | | | | | | |
| CO1 | : | Formulate power system network matrices. | | | | | | | | |
| CO2 | : | Get knowledge about power flow analyses. | | | | | | | | |
| CO3 | : | Analyse power system stability problems. | | | | | | | | |
| CO4 | : | Formulate and solve power system operational problems. | | | | | | | | |
| CO5 | : | Allocate system load to various generators in the system economically | | | | | | | | |
| Deference | | | | | | | | | | |

Reference Books:

| 1. | Hadi Saadat, "Power System Analysis", Tata McGraw Hill, 2010. |
|----|--|
| 2. | Kothari D.P and Dhillon J.S, "Power System Optimization", Prentice Hall of India, New Delhi, 2004. |
| | 2004. |

E-References:

| 1. | NPTEL Course: Power Systems Engineering – Prof. Debapriya Das, IIT-K. |
|----|---|
| 2. | NPTEL Course: Computer Aided Power System Analysis – Prof. Biswarup Das, IIT-R. |
| 3. | www.cdeep.iitb.ac.in. (Electrical Engineering) |

| RO CO | PO1 | PO2 | PO3 | PO 4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO 10 | PO 11 | PO 12 |
|----------|-----|-----|-----|---------|-----|-----|-----|-----|-----|----------|----------|----------|
| CO1 | 1 | 2 | 2 | 1 | 1 | 1 | 2 | 1 | 1 | 1 | 2 | 2 |
| CO2 | 1 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 2 | 2 |
| CO3 | 1 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 2 | 2 | 1 | 2 |
| CO4 | 1 | 2 | 2 | 2 | 1 | 1 | 2 | 1 | 1 | 2 | 2 | 2 |
| CO5 | 1 | 2 | 2 | 2 | 1 | 1 | 2 | 1 | 1 | 2 | 2 | 2 |

| 18EE704 | ELECTRICAL DRIVES AND CONTROL LABORATORY | L | Τ | Ρ | С |
|---------|--|---|---|---|----|
| | | 0 | 0 | 3 | 15 |

| Course C | Dbjectives: |
|----------|---|
| 1. | To impart knowledge on Performance of the fundamental control practices associated with AC and DC machines (starting, reversing, braking, plugging, etc.) using power electronics |
| 2. | To impart industry oriented learning |
| 3. | To evaluate the use of computer-based analysis tools to review the major classes of machines and their physical basis for operation |
| Experime | ents: |
| 1 | Study of thysistor controlled DC Drive using PSPICE / MATLAB / PSIM Software |
| 2 | Study of Chopper fed DC Drive using PSPICE / MATLAB / PSIM Software |
| 3 | Study of AC Single phase motor-speed control using TRIAC. |
| 4 | PWM Inverter fed 3 phase Induction Motor control using PSPICE / MATLAB / PSIM Software |
| 5 | VSI / CSI fed Induction motor Drive analysis using MATLAB/DSPICE/PSIM Software |
| 6 | Study of V/f control operation of 3F induction motor drive using PSPICE / MATLAB / PSIM Software |
| 7 | Study of permanent magnet synchronous motor drive fed by PWM Inverter using Software |
| 8 | Regenerative / Dynamic braking operation for DC Motor - Study using software |
| 9 | Regenerative / Dynamic braking operation of AC motor - Study using software |

Course Outcomes:

Upon completion of this course, the students will be able to:

| CO1 | : | Set up control strategies to synthesize the voltages in dc and ac motor drives |
|-----|---|---|
| CO2 | : | Develop testing and experimental procedures applying basic knowledge in electronics, electrical circuit analysis, electrical machines, microprocessors, and programmable logic controllers |
| CO3 | : | Use standard methods to determine accurate modeling/simulation parameters for various general-purpose electrical machines and power electronics devices required for designing a system and solve drives related problems |
| CO4 | : | Combine the use of computer-based simulation tools relevant to electrical Drives with practical laboratory experimentation. |
| CO5 | : | Design VSI/CSI for induction motor using any simulation software. |

Text Books:

| ShaahinFilizadeh ,"Electric Machines and Drives,", CRC Press,2013. Haitham Abu-Rub, Atif Iqbal, JaroslawGuzinski, "High Performance Control of AC Drives with Matlab/Simulink Models" John Wiley & Sons, Ltd., 2012. | 1. | Seung-Ki Sul, "Control of Electric Machine Drive Systems", John Wiley & Sons, Ltd., 2011. |
|---|----|---|
| | 2. | ShaahinFilizadeh, "Electric Machines and Drives,", CRC Press, 2013. |
| | 3 | Haitham Abu-Rub, Atif Iqbal, JaroslawGuzinski,"High Performance Control of AC Drives with Matlab/Simulink Models"John Wiley & Sons, Ltd., 2012. |

Reference Books:

1 Werner Leonhard ,"Control of Electrical Drives", Springer, 2006.

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 1 | 1 | 2 | 2 | 2 | 1 | 1 | | | | 1 | 1 |
| CO2 | 1 | 2 | 2 | 2 | 2 | 1 | 1 | | | | 1 | 1 |
| CO3 | 1 | 2 | 2 | 2 | 2 | 1 | 1 | | | | 1 | 1 |
| CO4 | | 1 | 2 | 2 | 2 | 1 | 1 | | | | 1 | 1 |
| CO5 | | 1 | 2 | 2 | 2 | 1 | 1 | | | | 1 | 1 |

PROGRAMME ELECTIVES

| 18EEP0 ⁻ | 1 | ELECTRICAL MACHINE DESIGN | L | Т | Ρ | С |
|--|--|---|---|---|--|---|
| | | | 3 | 0 | 0 | 3 |
| Course C | Dbj | ectives: | | | | |
| 1. | | To Study mmf calculation and thermal rating of various types of electrical machines | ; | | | |
| 2. | | To Design armature and field systems for D.C. machines. | | | | |
| 3. | | To Design core, yoke, windings and cooling systems of transformers. | | | | |
| 4. | | To Design stator and rotor of induction machines. | | | | |
| 5. | | To Design stator and rotor of synchronous machines and study their thermal behav | /iour | | | |
| | | | - | _ | 1 | |
| UNIT I | | INTRODUCTION | | 9 ara | + | 0 |
| | | derations – Limitations – Electrical Engineering Materials – Space factor – temperat two dimensions – thermal resistivity of winding – Temperature gradient in conductors | | | | |
| | | nachines – Eddy current losses in conductors – Standard specification | s pia | LEC | 111 31 | 015 |
| rtating | 011 | | | | | |
| UNIT II | | DC MACHINES | 9 | | + | 0 |
| Magnetic | cir | cuit calculations - Net length of Iron -Real & Apparent flux densities - Design of rot | tatin | a m | hachi | nes |
| | | ines output equations – Main dimensions-Selection of number of poles – Armature of | | | | |
| of commu | utat | tor and brushes-Design of slot, air gap, field coils. | | - | | - |
| | | | | | | |
| UNIT III | | TRANSFORMERS | 9 | | + | 0 |
| | | for single and three phase transformers – Window space factor – Overall dimension | | | | |
| | dia ti | cs – Regulation – No load current – Temperature rise of Transformers– Design | ofT | an | k wit | h & |
| | | | | | | |
| without c | ooli | ing tubes – Thermal rating – Methods of cooling of Transformers – Design of chol | | | | |
| without c | ooli | | | | | |
| without c welding T | ooli | ing tubes – Thermal rating – Methods of cooling of Transformers – Design of chol nsformers – Design of CTs &PTs. | kes | | | n of |
| without c welding T UNIT IV | ooli Frar | ing tubes – Thermal rating – Methods of cooling of Transformers – Design of cholosformers – Design of CTs &PTs. | <es -<="" td=""><td>– D</td><td>esigi</td><td>n of</td></es> | – D | esigi | n of |
| without c welding T UNIT IV Output ee | ooli Frar | ing tubes – Thermal rating – Methods of cooling of Transformers – Design of choles nsformers – Design of CTs &PTs. INDUCTION MOTORS ation of Induction motor – Main dimensions –Length of air gap- Rules for selecting | <es -<br="">9 9 rote</es> | - D | esigi | n of 0 of |
| without c welding T UNIT IV Output ee squirrel c | ooli Frar qua | ing tubes – Thermal rating – Methods of cooling of Transformers – Design of cholesformers – Design of CTs &PTs. INDUCTION MOTORS ation of Induction motor – Main dimensions –Length of air gap- Rules for selecting a machines– Design of rotor bars & slots – Design of end rings – Design of wound re | <pre></pre> | - D | esigi + slots erati | n of 0 of |
| without c welding T UNIT IV Output ee squirrel c | ooli Frar qua | ing tubes – Thermal rating – Methods of cooling of Transformers – Design of choles nsformers – Design of CTs &PTs. INDUCTION MOTORS ation of Induction motor – Main dimensions –Length of air gap- Rules for selecting | <pre></pre> | - D | esigi + slots erati | n of 0 of |
| without c welding T UNIT IV Output ea squirrel c character | ooli Frar qua | ing tubes – Thermal rating – Methods of cooling of Transformers – Design of cholosformers – Design of CTs &PTs. INDUCTION MOTORS ation of Induction motor – Main dimensions –Length of air gap- Rules for selecting a machines– Design of rotor bars & slots – Design of end rings – Design of wound r cs –Short circuit current –Dispersion co efficient – relation between D & L for best po | y rote | - D | esign + slots perati ctor. | n of of ng |
| without c welding T UNIT IV Output ed squirrel c character UNIT V | ooli Frar qua age risti | ing tubes – Thermal rating – Methods of cooling of Transformers – Design of cholosformers – Design of CTs &PTs. INDUCTION MOTORS ation of Induction motor – Main dimensions –Length of air gap- Rules for selecting e machines– Design of rotor bars & slots – Design of end rings – Design of wound r cs –Short circuit current –Dispersion co efficient – relation between D & L for best po SYNCHRONOUS MACHINES | es - 9 roto otor- ower | - D or s -Op r fac | esign + slots perati ctor. + | n of of ng |
| without c welding T UNIT IV Output ed squirrel c character UNIT V Runaway | ooli Fran qua age risti v sp | ing tubes – Thermal rating – Methods of cooling of Transformers – Design of cholosformers – Design of CTs &PTs. INDUCTION MOTORS ation of Induction motor – Main dimensions –Length of air gap- Rules for selecting e machines– Design of rotor bars & slots – Design of end rings – Design of wound r cs –Short circuit current –Dispersion co efficient – relation between D & L for best po SYNCHRONOUS MACHINES beed – construction – output equations – choice of loadings – Design of salient p | y rote otor- ower 9 0 9 | - D or s -Op r fac | esign + slots peratictor. + chine | n of of ng 0. |
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| without c welding T UNIT IV Output ed squirrel c character UNIT V Runaway Short circ Design o | ooli Trar qua age risti v sp cuit f ro | ing tubes – Thermal rating – Methods of cooling of Transformers – Design of cholosformers – Design of CTs &PTs. INDUCTION MOTORS ation of Induction motor – Main dimensions –Length of air gap- Rules for selecting ation of Induction motor – Main dimensions –Length of air gap- Rules for selecting ation of Induction motor – Main dimensions –Length of air gap- Rules for selecting ation of Induction motor – Main dimensions –Length of air gap- Rules for selecting ation of Induction motor – Main dimensions –Length of air gap- Rules for selecting ation of Induction motor – Main dimensions –Length of air gap- Rules for selecting ation of Induction motor – Main dimensions –Length of air gap- Rules for selecting ation of Induction motor – Main dimensions – Length of air gap- Rules for selecting ation of Induction motor – Main dimensions –Length of air gap- Rules for selecting ation of Induction motor – Main dimensions –Length of air gap- Rules for selecting ation of Induction motor – Main dimensions –Length of air gap- Rules for selecting ation of Induction motor – Main dimensions – Length of air gap- Rules for selecting ation of Induction motor – Main dimensions – Length of ation of selecting ation of not posign of rotor bars & slots – Design of end rings – Design of salient p ation – Short circuit current –Dispersion co efficient – relation between D & L for best posign ation – Short circuit current –Dispersion – Choice of loadings – Design of salient p ratio – shape of pole face – Armature design – Armature parameters – Estimation of ation – Design of damper winding – Determination of full load field mmf – Design of | es - 9 otor- otor- ower 9 ole i | - D or s -Op r fac mac | esign + slots peratictor. + chine | n of of ng 0 0 es - yth- |
| without c welding T UNIT IV Output ed squirrel c character UNIT V Runaway Short circ Design o | ooli Trar qua age risti v sp cuit f ro | ing tubes – Thermal rating – Methods of cooling of Transformers – Design of cholosformers – Design of CTs &PTs. INDUCTION MOTORS ation of Induction motor – Main dimensions –Length of air gap- Rules for selecting a machines– Design of rotor bars & slots – Design of end rings – Design of wound r cs –Short circuit current –Dispersion co efficient – relation between D & L for best po SYNCHRONOUS MACHINES Deed – construction – output equations – choice of loadings – Design of salient p ratio – shape of pole face – Armature design – Armature parameters – Estimation of | es - 9 otor- otor- ower 9 ole i | - D or s -Op r fac mac | esign + slots peratictor. + chine | n of of ng 0 0 es - yth- |
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| without c welding T UNIT IV Output ed squirrel c character UNIT V Runaway Short circ Design o | oolii Trar qua age ristii c sp cuit f ro ion | ing tubes – Thermal rating – Methods of cooling of Transformers – Design of cholosformers – Design of CTs &PTs. INDUCTION MOTORS ation of Induction motor – Main dimensions –Length of air gap- Rules for selecting e machines– Design of rotor bars & slots – Design of end rings – Design of wound r cs –Short circuit current –Dispersion co efficient – relation between D & L for best por SYNCHRONOUS MACHINES peed – construction – output equations – choice of loadings – Design of salient p ratio – shape of pole face – Armature design – Armature parameters – Estimation of to computer aided design – Program to design main dimensions of Alternators. Total (45+ | 9 9 1 0 1 0 1 | - D or s -Op r fac gap d w | esign + slots berati ctor. + chine b leng | n of of ng g - |
| without c welding T UNIT IV Output ed squirrel c character UNIT V Runaway Short circ Design o Introducti | oolii Trar qua age ristid y sp cuit f ro ion | ing tubes – Thermal rating – Methods of cooling of Transformers – Design of cholosformers – Design of CTs &PTs. INDUCTION MOTORS ation of Induction motor – Main dimensions –Length of air gap- Rules for selecting e machines– Design of rotor bars & slots – Design of end rings – Design of wound r cs –Short circuit current –Dispersion co efficient – relation between D & L for best por SYNCHRONOUS MACHINES peed – construction – output equations – choice of loadings – Design of salient p ratio – shape of pole face – Armature design – Armature parameters – Estimation of to computer aided design – Program to design main dimensions of Alternators. Total (45+ | 9 9 1 0 1 0 1 | - D or s -Op r fac gap d w | esign + slots berati ctor. + chine b leng | n of of ng g - |
| without c welding T UNIT IV Output ed squirrel c character UNIT V Runaway Short circ Design o Introducti | oolii Trar qua age ristid y sp cuit f ro ion | ing tubes – Thermal rating – Methods of cooling of Transformers – Design of cholosformers – Design of CTs &PTs. INDUCTION MOTORS ation of Induction motor – Main dimensions –Length of air gap- Rules for selecting be machines– Design of rotor bars & slots – Design of end rings – Design of wound r cs –Short circuit current –Dispersion co efficient – relation between D & L for best po SYNCHRONOUS MACHINES Deeed – construction – output equations – choice of loadings – Design of salient p ratio – shape of pole face – Armature design – Armature parameters – Estimation of to computer aided design – Program to design main dimensions of Alternators. Total (45+4 comes: | 9 9 1 0 1 0 1 | - D or s -Op r fac gap d w | esign + slots berati ctor. + chine b leng | n of of ng g - |
| without c welding T UNIT IV Output ea squirrel c character UNIT V Runaway Short circ Design o Introducti | oolii Trar qua age ristid y sp cuit f ro ion | ing tubes – Thermal rating – Methods of cooling of Transformers – Design of chole hsformers – Design of CTs &PTs. INDUCTION MOTORS ation of Induction motor – Main dimensions –Length of air gap- Rules for selecting e machines– Design of rotor bars & slots – Design of end rings – Design of wound ro- cs –Short circuit current –Dispersion co efficient – relation between D & L for best por SYNCHRONOUS MACHINES Deed – construction – output equations – choice of loadings – Design of salient p ratio – shape of pole face – Armature design – Armature parameters – Estimation of to computer aided design – Program to design main dimensions of Alternators. Total (45+4) comes: etion of this course, the students will be able to: | <pre>< es -</pre> | - D or s -Op r fac gap d w 45 | esign + slots berati ctor. + chine b leng | n of of ng g – |
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| 2. | Sen.,S.K., 'PrinciplesofElectricalMachineDesignswithComputerProgrammes', OxfordandIBHPublishingCo.Pvt.Ltd.NewDelhi,2014,3 rd edition. | | | | | | | | |
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| Reference | Books: | | | | | | | | |
| 1. | R.K.Agarwal, Principles of Electrical Machine design, S.K. Kataria and Sons, Delhi 2014 5 th edition. | | | | | | | | |
| 2. | V.N. Mittle, 'Design of Electrical Machines', Standard Publications and Distributors, Delhi, 2002. | | | | | | | | |
| E- References 1 http://cusp.umn.edu/machine_design.php | | | | | | | | | |

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| 18EEP02 | BIOLOGY FOR ELECTRICAL ENGINEERS | L | TF | Р С |
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| | Objectives: | _ | | |
| | ose of this course is to provide a basic and easy understanding of modern biology to | | | |
| | disciplinary field. It emphasis on the basic engineering principles of bimedicalequipn | | | |
| | e is expected to encourage the engineering students to think about solving biologica ing tools. These will be gained by the following: | i propi | ems w | lith |
| 1. | An understanding of biological mechanisms of living organisms from the perspect | ive of e | naine | ers |
| 2. | To Understand the principles of Biomedical Equipments. | | Ingine | ci3. |
| 3. | An understanding of the function and regulation of human system and acquire k | nowled | lae ah | out |
| 0. | biological problems that requires engineering expertise to solve them. | 1011100 | ige ab | out |
| 4. | An Understanding of the basics of molecular biology and genetics. | | | |
| 5. | To know about the radiation safety instruments and X Ray examinations. | | | |
| 6. | To evaluate the kinetics and thermodynamics of enzymatic process. | | | |
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| Unit I | BIOMOLECULES AND METABOLISM | | 9 + | - |
| | drates- classification - Glycolysis- definition- flow chart- steps involved in glycolysis- p | | | |
| | off phase- kinds of reactions in glycolysis. Photosynthesis- definition- significanc | | | netic- |
| pigments | types- structure of pigments factors affecting photosynthesis- external and internal f | actors | | |
| Unit II | BASICS OF ENZYMES, MACROMOLECULES AND NUCLEIC ACIDS | | 9 + | 0 |
| Introduct | ion - Enzymes – Proteases and amylases. Proteins- classification- structure of p | orotein | s- prir | nary. |
| | y, tertiary and quaternary structure- properties of proteins- physical and chemical p | | | |
| | s. Types-Structural components of nucleic acids- acid, pentose sugar and nitrogenous | | | |
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| nucleot | ide and its functions - single and double helical structure of DNA-comparison betwee | n Dina | апи п | |
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| types of I Unit III Blood ce thermom – angiogu Unit IV Cells and electric p - nervous micro, ne Unit V Pacemak diathermy of differe Radiatior shock – technique – Positro | RNA -mRNA, tRNA and rRNA and their function. X RAY EXAMINATIONS III counter – Electron microscope – radiation detectors – photo meters and coloreter – audio meters – X-ray tube – X-ray machine – Radiography and fluoroscopy – raphy – applications of X-ray examination. HUMAN PHYSIOLOGY It their structure – Transport of ions through the cell membrane – resting and action potential. Physiology of Human body- Brain, heart, lungs - Cardiovascular system - Reis system. Design of medical instruments components of biomedical instrument system edle, surface electrode - transducers. BIOMEDICAL EQUIPMENTS AND RADIATION SAFETY INSTRUMENTS Kers – Pacemaker batteries – Defibrillators – heart lung machine. Surgical diather y – microwave diathermy – ultrasonic diathermy – therapeutic effect of heat – range are nt diathermy techniques – Ventilators – oxymeters. n safety instrumentation – physiological effects due to 50 Hz current passage – Micro electrical accidents in hospitals – Devices to protect against electrical hazards. es – computer tomography – thermography – ultrasonic imaging system – Magnetic reference in emission tomography – digital subs traction angiography. Total (4 Dutcomes: | rimete image potenti spirato ns – el my – : d area shock Nucle sonan | 9 + rs - c intens 9 + al - bi ry sys ectrod 9 + short v of irrit and m ar ima ce ima | o- tem es – ation aging aging |

| CO4 | : | Explain human physiological systems. |
|-----------------------|------|--|
| CO5 | : | Share knowledge in genetics and molecular biology. |
| CO6 | : | Know about the applications and implementation of medical equipments as it is a challenging |
| | | interdisciplinary process |
| Text Bo | ooks | <u>.</u> |
| 1. | | FJ.L.Jain, Sanjay jain and Nitin jain- "Fundamentals of Biochemistry" - Sixth edition, S.Chand and company Ltd., Ram nagar, 2005. |
| 2. | | Dr.A.V.S.S.Rama Rao-" Text book of Biochemistry"- Text book of Biochemistry- First edition- UBS Publishers' Distributors Pvt. Ltd., 2019 |
| 3. | | U. Satyanarayana – "Biochemistry"-5th edition – Sri Padmavathi Publications Ltd., 2017. |
| 4. | | N. A. Campbell, J. B. Reece, L. Urry, M. L. Cain and S. A. Wasserman, "Biology: A global approach", Pearson Education Ltd, 2014. |
| 5. | | Dr.M.Arumugam, 'Bio-Medical Instrumentation', Anuradha Agencies, 2012. |
| 6. | | Leslie Cromwell, Fred J.Weibell, Erich A.Pfeiffer, 'Bio-Medical Instrumentation andMeasurements', II edition, Pearson Education, 2011 / PHI. |
| Referer | nce | Books: |
| 1. | | Stent, G. S.; and Calender-" Molecular Genetics"- Second edition - R. W.H. Freeman and company, Distributed by Satish Kumar Jain for CBS Publisher |
| 2. | | By Nelson, D. L.; and Cox- "Principles of Biochemistry"- V Edition- M. M.W.H. Freeman and Company |
| 3. | | Conn, E.E; Stumpf, P.K; Bruening, G; Doi, R.H-" Outlines of Biochemistry"- John Wiley and Sons |
| 4. | | Quillin, Allison Scott Freeman, Kim Quillin and Lizabeth Allison, 'Biological Science', Pearson Education India, 2016. |
| 5. | | Reinhard Renneberg, Viola Berkling and Vanya Loroch, 'Biotechnology for Beginner's', Academic Press, 2017. |
| | | |
| 6. | | S Balaji, S Lakshminarayanan, "Conceptual comparison of metabolic pathways with electronic circuits", Journal of Bionics Engineering, Vol 1, Issue 3, pg 175-182, 2004 |
| 6. 7. | | |
| | | circuits", Journal of Bionics Engineering, Vol 1, Issue 3, pg 175-182, 2004 R.S.Khandpur, 'Hand Book of Bio-Medical instrumentation', Tata McGraw Hill Publishing Co |
| 7. | | circuits", Journal of Bionics Engineering, Vol 1, Issue 3, pg 175-182, 2004 R.S.Khandpur, 'Hand Book of Bio-Medical instrumentation', Tata McGraw Hill Publishing Co Ltd.,2012. L.A. Geddes and L.E.Baker, 'Principles of Applied Bio-Medical Instrumentation', John Wiley |
| 7. 8. | | circuits", Journal of Bionics Engineering, Vol 1, Issue 3, pg 175-182, 2004 R.S.Khandpur, 'Hand Book of Bio-Medical instrumentation', Tata McGraw Hill Publishing Co Ltd.,2012. L.A. Geddes and L.E.Baker, 'Principles of Applied Bio-Medical Instrumentation', John Wiley &Sons, 2011. |
| 7. 8. 9. 10. | | circuits", Journal of Bionics Engineering, Vol 1, Issue 3, pg 175-182, 2004 R.S.Khandpur, 'Hand Book of Bio-Medical instrumentation', Tata McGraw Hill Publishing Co Ltd.,2012. L.A. Geddes and L.E.Baker, 'Principles of Applied Bio-Medical Instrumentation', John Wiley &Sons, 2011. C.Rajarao, 'Medical Instrumentation', John Wiley & Sons,2013. C.Rajarao and S.K. Guha, 'Principles of Medical Electronics and Bio-medical Instrumentation', Universities press (India) Ltd, Orient Longman Itd, 2012. |
| 7. 8. 9. | ence | circuits", Journal of Bionics Engineering, Vol 1, Issue 3, pg 175-182, 2004 R.S.Khandpur, 'Hand Book of Bio-Medical instrumentation', Tata McGraw Hill Publishing Co Ltd.,2012. L.A. Geddes and L.E.Baker, 'Principles of Applied Bio-Medical Instrumentation', John Wiley &Sons, 2011. C.Rajarao, 'Medical Instrumentation', John Wiley & Sons,2013. C.Rajarao and S.K. Guha, 'Principles of Medical Electronics and Bio-medical Instrumentation', Universities press (India) Ltd, Orient Longman Itd, 2012. |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 2 | 1 | 1 | 1 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO2 | 3 | 1 | 1 | 3 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO3 | 1 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO4 | 3 | 1 | 1 | 3 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO5 | 2 | 1 | 1 | 2 | 1 | 1 | 2 | 1 | 1 | 1 | 1 | 1 |
| CO6 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

| 18EEP03 | DIGITAL SIGNAL PROCESSING | L | ТР | С |
|---|---|----------------------------------|--|------------------|
| | | 3 | 0 0 | 3 |
| Course Ob | | | | |
| 1. | To classify signals and systems & their mathematical representation. | | | |
| 2. | To analyze the discrete time systems. | | | |
| <u>3.</u> 4 | To study various transformation techniques & their computation. To study about filters and their design for digital implementation. | | | |
| 4 5 | To study about mers and mer design for digital implementation. To study about a programmable digital signal processor & quantization effects. | | | |
| 5 | | | | |
| UNIT I | INTRODUCTION TO SIGNALS AND SYSTEMS | | 9 + | 0 |
| Classificatio | n of systems: Continuous, discrete, linear, causal, stable, dynamic, recursive, | time | variar | ice; |
| | n of signals: continuous and discrete, energy and power; mathematical represent | | of sign | als; |
| spectral der | sity; sampling techniques, quantization, quantization error, Nyquist rate, aliasing e | ffect. | | |
| | | | • | • |
| | DISCRETE TIME SYSTEM ANALYSIS | | 9 + | 0 |
| | and its properties, inverse z-transforms; difference equation – Solution by z transfo stems - Stability analysis, frequency response –Convolution – Discrete TimeFo | | | |
| | and phase representation. | unenn | ansion | 11 |
| magnitude | | | | |
| Unit III | DISCRETE FOURIER TRANSFORM & COMPUTATION | | 9 + | 0 |
| | urier Transform- properties, magnitude and phase representation - Computation of | DFT | usina F | F |
| | DIT &DIF using radix 2 FFT – Butterfly structure. | | | |
| | | | | |
| Unit IV | DESIGN OF DIGITAL FILTERS | | 9 + | 0 |
| | er realization – Parallel & cascade forms. FIR design: Windowing Techniques – Ne | | | |
| | inear phase characteristics. Analog filter design – Butterworth and Chebyshev app | | ations; | II |
| Filters, digit | al design using impulse invariant and bilinear transformation - mWarping, pre warp | ing. | | |
| Unit V | DIGITAL SIGNAL PROCESSORS | | 9 + | 0 |
| | Architecture – Features – Addressing Formats – Functional modes - Introduction | | - | - |
| DSP Proces | | | | Jai |
| 201 11000 | | | | |
| | Total (45- | +0)= 4 | 5 Peri | ods |
| Course Ou | comes: | | | |
| | | | | |
| CO1 | etion of this course, the students will be able to: | | | |
| | Understand the types of systems and signals. | | | |
| CO2 | Understand the types of systems and signals. Solve problems in digital system using Z transform. | | | |
| CO2 2 CO3 2 | Understand the types of systems and signals. Solve problems in digital system using Z transform. Apply Fourier transforms for processing of digital signals. | | | |
| CO2 CO3 CO4 | Understand the types of systems and signals.Solve problems in digital system using Z transform.Apply Fourier transforms for processing of digital signals.Analyze digital systems using Fast Fourier transform. | | | |
| CO2 CO3 CO4 CO5 | Understand the types of systems and signals.Solve problems in digital system using Z transform.Apply Fourier transforms for processing of digital signals.Analyze digital systems using Fast Fourier transform.Design digital filters algorithms in digital signal processor platforms | | | |
| CO2 CO3 CO4 | Understand the types of systems and signals.Solve problems in digital system using Z transform.Apply Fourier transforms for processing of digital signals.Analyze digital systems using Fast Fourier transform. | | | |
| CO2 CO3 CO4 CO5 CO6 | Understand the types of systems and signals.Solve problems in digital system using Z transform.Apply Fourier transforms for processing of digital signals.Analyze digital systems using Fast Fourier transform.Design digital filters algorithms in digital signal processor platformsGain knowledge about DSP processors. | | | |
| CO2 CO3 CO4 CO5 CO6 Text Books | Understand the types of systems and signals. Solve problems in digital system using Z transform. Apply Fourier transforms for processing of digital signals. Analyze digital systems using Fast Fourier transform. Design digital filters algorithms in digital signal processor platforms Gain knowledge about DSP processors. | ms and | 4 | |
| CO2 CO3 CO4 CO5 CO6 | Understand the types of systems and signals. Solve problems in digital system using Z transform. Apply Fourier transforms for processing of digital signals. Analyze digital systems using Fast Fourier transform. Design digital filters algorithms in digital signal processor platforms Gain knowledge about DSP processors. J.G. Proakis and D.G. Manolakis, 'Digital Signal Processing Principles, Algorithr | ms and | 3 | |
| CO2 CO3 CO4 CO5 CO6 Text Books | Understand the types of systems and signals. Solve problems in digital system using Z transform. Apply Fourier transforms for processing of digital signals. Analyze digital systems using Fast Fourier transform. Design digital filters algorithms in digital signal processor platforms Gain knowledge about DSP processors. J.G. Proakis and D.G. Manolakis, 'Digital Signal Processing Principles, Algorithr Applications', Pearson Education, New Delhi, 2007. | | | 3. |
| CO2 CO3 CO4 CO5 CO6 Text Books 1. 2. | Understand the types of systems and signals. Solve problems in digital system using Z transform. Apply Fourier transforms for processing of digital signals. Analyze digital systems using Fast Fourier transform. Design digital filters algorithms in digital signal processor platforms Gain knowledge about DSP processors. J.G. Proakis and D.G. Manolakis, 'Digital Signal Processing Principles, Algorithr Applications', Pearson Education, New Delhi, 2007. S.K. Mitra, 'Digital Signal Processing – A Computer Based Approach', McGraw H | Hill Ed | u, 201 | |
| CO2 CO3 CO4 CO5 CO6 Text Books | Understand the types of systems and signals. Solve problems in digital system using Z transform. Apply Fourier transforms for processing of digital signals. Analyze digital systems using Fast Fourier transform. Design digital filters algorithms in digital signal processor platforms Gain knowledge about DSP processors. J.G. Proakis and D.G. Manolakis, 'Digital Signal Processing Principles, Algorithr Applications', Pearson Education, New Delhi, 2007. | Hill Ed | u, 201 | |
| CO2 CO3 CO4 CO5 CO6 Text Books 1. 2. 3. | Understand the types of systems and signals. Solve problems in digital system using Z transform. Apply Fourier transforms for processing of digital signals. Analyze digital systems using Fast Fourier transform. Design digital filters algorithms in digital signal processor platforms Gain knowledge about DSP processors. J.G. Proakis and D.G. Manolakis, 'Digital Signal Processing Principles, Algorithr Applications', Pearson Education, New Delhi, 2007. S.K. Mitra, 'Digital Signal Processing – A Computer Based Approach', McGraw I Robert Schilling & Sandra L.Harris, "Introduction to Digital Signal Processing Cengage Learning, 2014. | Hill Ed | u, 201 | |
| CO2 CO3 CO4 CO5 CO6 Text Books 1. 2. | Understand the types of systems and signals. Solve problems in digital system using Z transform. Apply Fourier transforms for processing of digital signals. Analyze digital systems using Fast Fourier transform. Design digital filters algorithms in digital signal processor platforms Gain knowledge about DSP processors. J.G. Proakis and D.G. Manolakis, 'Digital Signal Processing Principles, Algorithr Applications', Pearson Education, New Delhi, 2007. S.K. Mitra, 'Digital Signal Processing – A Computer Based Approach', McGraw H Robert Schilling & Sandra L.Harris, "Introduction to Digital Signal Processing Cengage Learning, 2014. | Hill Ed using | u, 201 | |
| CO2 CO3 CO4 CO5 CO6 Text Books 1. 2. 3. Reference 1. | Understand the types of systems and signals. Solve problems in digital system using Z transform. Apply Fourier transforms for processing of digital signals. Analyze digital systems using Fast Fourier transform. Design digital filters algorithms in digital signal processor platforms Gain knowledge about DSP processors. J.G. Proakis and D.G. Manolakis, 'Digital Signal Processing Principles, Algorithr Applications', Pearson Education, New Delhi, 2007. S.K. Mitra, 'Digital Signal Processing – A Computer Based Approach', McGraw I Robert Schilling & Sandra L.Harris, "Introduction to Digital Signal Processing Cengage Learning, 2014. Books: Poorna Chandra S, Sasikala. B ,Digital Signal Processing, Vijay Nicole/TMH,201 | Hill Ed using 3. | u, 2013 9 Matla | ıb", |
| CO2 CO3 CO4 CO5 CO6 Text Books 1. 2. 3. Reference 1. 2. | Understand the types of systems and signals. Solve problems in digital system using Z transform. Apply Fourier transforms for processing of digital signals. Analyze digital systems using Fast Fourier transform. Design digital filters algorithms in digital signal processor platforms Gain knowledge about DSP processors. : J.G. Proakis and D.G. Manolakis, 'Digital Signal Processing Principles, Algorithm Applications', Pearson Education, New Delhi, 2007. S.K. Mitra, 'Digital Signal Processing – A Computer Based Approach', McGraw H Robert Schilling & Sandra L.Harris, "Introduction to Digital Signal Processing Cengage Learning, 2014. Books: Poorna Chandra S, Sasikala. B ,Digital Signal Processing, Vijay Nicole/TMH,201 B.P.Lathi, 'Principles of Signal Processing and Linear Systems', Oxford Universi | Hill Ed using 3. ty Pre | u, 2013 9 Matla ss, 201 | b", 0. |
| CO2 CO3 CO4 CO5 CO6 Text Books 1. 2. 3. Reference 1. | Understand the types of systems and signals. Solve problems in digital system using Z transform. Apply Fourier transforms for processing of digital signals. Analyze digital systems using Fast Fourier transform. Design digital filters algorithms in digital signal processor platforms Gain knowledge about DSP processors. : J.G. Proakis and D.G. Manolakis, 'Digital Signal Processing Principles, Algorithr Applications', Pearson Education, New Delhi, 2007. S.K. Mitra, 'Digital Signal Processing – A Computer Based Approach', McGraw H Robert Schilling & Sandra L.Harris, "Introduction to Digital Signal Processing Cengage Learning, 2014. Books: Poorna Chandra S, Sasikala. B ,Digital Signal Processing, Vijay Nicole/TMH,201 B.P.Lathi, 'Principles of Signal Processing and Linear Systems', Oxford Universi Taan S. EIAli, 'Discrete Systems and Digital Signal Processing with Mat Lab', CR | Hill Ed using 3. ty Pre | u, 2013 g Matla ss, 201 ss, 201 | b", 0. 2. |
| CO2 CO3 CO4 CO5 CO6 Text Books 1. 2. 3. Reference 1. 2. | Understand the types of systems and signals. Solve problems in digital system using Z transform. Apply Fourier transforms for processing of digital signals. Analyze digital systems using Fast Fourier transform. Design digital filters algorithms in digital signal processor platforms Gain knowledge about DSP processors. : J.G. Proakis and D.G. Manolakis, 'Digital Signal Processing Principles, Algorithm Applications', Pearson Education, New Delhi, 2007. S.K. Mitra, 'Digital Signal Processing – A Computer Based Approach', McGraw H Robert Schilling & Sandra L.Harris, "Introduction to Digital Signal Processing Cengage Learning, 2014. Books: Poorna Chandra S, Sasikala. B ,Digital Signal Processing, Vijay Nicole/TMH,201 B.P.Lathi, 'Principles of Signal Processing and Linear Systems', Oxford Universi | Hill Ed using 3. ty Pre | u, 2013 g Matla ss, 201 ss, 201 | b", 0. 2. |

E-References

https://nptel.ac.in/courses/108105055/34 https://books.google.co.in/books/isbn=8131710009 1 2

| RO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 1 | 1 | 1 | 1 | 1 | 1 | 2 | 1 | 1 | 1 | 1 | |
| CO2 | 3 | 3 | 2 | 1 | 2 | 1 | 2 | 1 | 1 | 1 | 1 | |
| CO3 | 3 | 3 | 3 | 3 | 2 | 1 | 3 | 1 | 1 | 1 | 1 | |
| CO4 | 3 | 3 | 3 | 3 | 3 | 1 | 3 | 1 | 1 | 1 | 1 | |
| CO5 | 2 | 3 | 3 | 3 | 3 | 1 | 3 | 1 | 1 | 1 | 1 | |
| CO6 | 1 | 1 | 1 | 3 | 2 | 1 | 3 | 1 | 1 | 1 | 1 | |

| 18EEP04 | DISCRETE CONTROL SYSTEMS | Т | Ρ | С |
|-----------------------------|--|--------|--------------------|-----|
| | 3 | 0 | 0 | 3 |
| Course Ob | | | | |
| 1. | To understand the digital signal processing. | | | |
| 2. | To study the design of sampled data control systems in state space. | | | |
| 3. | To impart knowledge on digital control algorithms and stability study. | | | |
| Unit I | INTRODUCTION | 9 | + | 0 |
| controllers - | equency and time response analysis and specifications of continuous time systems - n continuous time compensations - continues time PI, PD, PID controllers, Realization on prs: Lag, Lead and Lag-Lead compensation schemes - problems. | | | |
| Unit II | SIGNAL PROCESSING IN DIGITAL CONTROL | 9 | + | 0 |
| discrete-tim | gital control – Configuration of basic digital control scheme – Principles of signal conve e signals – Time domain and frequency domain models for discrete-time systems tion of analog signals – Practical aspects of the choice of sampling rate – Discretizati sformation. | s - A | liasin | ng |
| Unit III | MODELING AND ANALYSIS OF SAMPLED DATA CONTROL SYSTEM | 9 | + | 0 |
| data contr concepts: | l equation description – Z-transform method of description– Z-transform analysis of sa ol systems –Jury's stability test – Routh stability criterion on the r-plane – State va First companion – Second companion – Jordan canonical models – Discrete state var Elementary principles. | riable | | |
| Unit IV | DESIGN OF DIGITAL CONTROL ALGORITHMS | | | 0 |
| | – z-plane specifications of control system design –Digital lead , lag and lag-lead comp | 9 | + | 0 |
| using freque | ency response plots - Digital lead lag compensator design using Root locus plots - z- htrollers for deadbeat performance - Examples. | | | |
| Unit V | PRACTICAL ASPECTS OF DIGITAL CONTROL ALGORITHMS | 9 | + | 0 |
| temperature position/spe | nt and implementation of digital PID control algorithms – Tunable PID controlle control system: Control algorithm – Digital position control system: Digital measuren eed, control algorithm – Stepping motors and their controls: Torque-speed curves, Inte cors to microprocessors | nent c | of sha | aft |
| | Total (45+0) | = 45 | Peric | ds |
| Course Out | tcomes: | | | |
| Upon comp | letion of this course, the students will be able to: | | | |
| CO1 : | Get knowledge about digital control scheme. | | | |
| CO2 : | Get knowledge about sampling techniques. | | | |
| CO3 : | Design the various digital control algorithms. | | | |
| CO4 : | Design the various types of digital controllers. | | | |
| CO5 : | Design the various types of digital compensators. | | | |
| CO6 : | Get knowledge about applications of digital control. | | | |
| Text Books | | | | |
| 1. | M.Gopal, "Digital Control and Static Variable Methods", Tata McGraw Hill, New Delh edition. | i, 200 | 03,2 nd | Ł |
| 2. | I.J.Nagrath&M.Gopal, "Control Systems Engineering", New Age International Pub Delhi, 2009,5 th edition. | isher | s, N | эw |
| Reference | Books | | | |
| 1. | B.C.Kuo, Digital Control Systems, Oxford University Press, 2nd Edition, 2007. | | | |
| 2. | K. Ogata, Modern Control Engineering, Pearson Education, 2010 5th edition. | | | |
| ۷. | A cyala, would be control engineering, reason education, 2010 5 educol. | | | |

| 3. | Kenneth J. Ayala, "The 8051 Microcontroller- Architecture, Programming and Applications", Penram International, 2nd Edition, 1996. |
|--------------|--|
| E -Reference | ces |
| 1 | https://nptel.ac.in/courses/108103008/ |
| 2 | https://www.sciencedirect.com/topics/engineering/digital-control-system |

| PO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 1 | 1 | 1 | 1 | 1 | 1 | 2 | 1 | 1 | 1 | 1 | |
| CO2 | 3 | 3 | 2 | 1 | 2 | 1 | 2 | 1 | 1 | 1 | 1 | |
| CO3 | 3 | 3 | 3 | 3 | 2 | 1 | 3 | 1 | 1 | 1 | 1 | |
| CO4 | 3 | 3 | 3 | 3 | 3 | 1 | 3 | 1 | 1 | 1 | 1 | |
| CO5 | 2 | 3 | 3 | 3 | 3 | 1 | 3 | 1 | 1 | 1 | 1 | |
| CO6 | 1 | 1 | 1 | 3 | 2 | 1 | 3 | 1 | 1 | 1 | 1 | |

| | HIGH VOLTAGE ENGINEERING | L | T | Ρ | C |
|--|---|-----------------------|-----------------------------------|--|----------------------------|
| | | 3 | 0 | 0 | 3 |
| Course Ol | biostivos | | | | |
| 1. | To expose the various types of over voltage transients and their effect on power sys | tom | | | |
| 2. | To introduce the concept of insulation co-ordination technique. | lem | | | |
| 3. | To provide an overview of solid, liquid and gaseous dielectrics breakdown mechanis | m | | | |
| <u> </u> | To show how to generate over voltages in the HV testing laboratory | | | | |
| <u>4.</u> 5. | To show how to generate over voltages in the HV testing laboratory | n / | | | |
| <u> </u> | To introduce testing procedure of HV power apparatus. | l y | | | |
| 0. | To introduce testing procedure of HV power apparatus. | | | | |
| Unit I | OVER VOLTAGES IN ELECTRICAL POWER SYSTEMS AND INSULATION CO- ORDINATION | | 9 | + | 0 |
| Causes of | over voltages and its effect on power system - Lightning, switching surges and t | emp | orar | y ov | er |
| voltages - | Bewley lattice diagram-protection against over voltages; Principle of Insulation Coord d Extra high voltage power systems. | | | | |
| Unit II | ELECTRICAL BREAKDOWN IN GASES, LIQUIDS AND SOLIDS DIELECTRICS | | 9 | + | 0 |
| | of Dielectric materials- Gaseous breakdown in uniform and non-uniform fields – con | 002 | - | - | - |
| | breakdown - conduction and breakdown in pure and commercial liquids dielectric | | | | |
| | ns in solid and composite dielectrics- Application of insulating materials in electrical e | | | | , , , , |
| meenamon | | yuip | me | 111.5. | |
| Unit III | GENERATION OF HIGH VOLTAGES AND HIGH CURRENTS | | 9 | + | 0 |
| | n of High DC voltages: Rectifiers, voltage multipliers and Vande Graff generator- Ger | erat | ion | | ah |
| | es: cascaded transformer, resonant transformer and tesla coil- Generation of High im | | | | |
| | | | | | |
| single and | multistage Marx circuits - Generation of switching voltages - Generation of impulse cu | rren | ts. T | ripp | inc |
| | multistage Marx circuits - Generation of switching voltages - Generation of impulse cu of impulse generators. | rren | ts. T | ripp | ing |
| | multistage Marx circuits - Generation of switching voltages - Generation of impulse cu I of impulse generators. | rren | ts. T | ripp | ing |
| | | rren | ts. T 9 | ripp | - |
| and contro | MEASUREMENT OF HIGH VOLTAGES AND HIGH CURRENTS | | 9 | + | 0 |
| and contro Unit IV Measurem | I of impulse generators. MEASUREMENT OF HIGH VOLTAGES AND HIGH CURRENTS Internation of high DC, AC, impulse voltages – Measurement of high currents: Direct, Alternat | | 9 | + | 0 |
| and contro Unit IV Measurem | MEASUREMENT OF HIGH VOLTAGES AND HIGH CURRENTS | | 9 | + | 0 |
| and contro Unit IV Measurem | I of impulse generators. MEASUREMENT OF HIGH VOLTAGES AND HIGH CURRENTS Internation of high DC, AC, impulse voltages – Measurement of high currents: Direct, Alternat | | 9 | + | 0 Ise |
| and contro Unit IV Measurem – digital ter Unit V Overviews method - H | Of impulse generators. MEASUREMENT OF HIGH VOLTAGES AND HIGH CURRENTS ent of high DC, AC, impulse voltages – Measurement of high currents: Direct, Alternat chniques in impulse voltage and current measurements. | ng a | 9 ind I 9 o an | + mpu + d Do | 0 Ise 0 wr |
| and contro Unit IV Measurem – digital ter Unit V Overviews method - H | MEASUREMENT OF HIGH VOLTAGES AND HIGH CURRENTS ent of high DC, AC, impulse voltages – Measurement of high currents: Direct, Alternat chniques in impulse voltage and current measurements. HIGH VOLTAGE TESTING OF ELECTRICAL POWER APPARATUS of International and Indian standards- laboratory test procedure: multi-level method HV Testing of Insulators and Bushings, Isolators and Circuit Breakers, Power trans Power capacitors and Cables. | ng a I, Up form | 9 ind I 9 an ners | + mpu d Dc , Su | 0 Ise 0 wr rge |
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| 2. | C.L. Wadhwa, 'High Voltage Engineering', New Age International (P) Ltd Publishers, Third Edition, 2012 |
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| 3. | Rakosh Das Begamudre, 'Extra High Voltage AC Transmission Engineering', New Age International (P) Ltd Publishers, 4 th Edition, 2011. |
| E-referen | |
| 1 | www.onlinecourses.nptel.ac.in/noc18_ee41 |
| 2 | NPTEL courses on High Voltage Engineering, IIT Kanpur. |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
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| CO4 | 3 | 2 | 3 | | 1 | | | | | | | |
| CO5 | 3 | | 2 | | 1 | | 1 | | | | | |
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| 18EEP06 | HVDC TRANSMISSION SYSTEMS | L | Т | Ρ | С |
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| Course Ol | | | | | |
| 1. | To understand the concept, planning of DC power transmission and comparison wit | h AC | ; | pow | /er |
| | transmission. | | | | |
| 2. | To analyze HVDC converters. | | | | |
| 3. | To study about the HVDC system control. | | | | |
| 4. | To analyze harmonics and design of filters. | | | | |
| 5. | To model and analysis the DC system under steady state. | | | | |
| Unit I | INTRODUCTION | | 9 | + | 0 |
| DC Power | transmission technology - Comparison of AC and DC transmission-Application of DC | C tra | nsm | nissio | on - |
| | n of DC transmission system– Planning for HVDC transmission–Modern trends in HV | | | | |
| DC breake | ers – Operating problems– HVDC transmission based on VSC –Types and applica | tions | s of | MT | ЭС |
| systems. | | | | | |
| Unit II | ANALYSIS OF HVDC CONVERTERS | | 9 | * | 0 |
| | nutated converter-Analysis of Graetz circuit with and without overlap-Pulse numb | or. (| - | | - |
| | configuration–Converter bridge characteristics–Analysis of 12 pulse converters –Analysis | | | | |
| | and firing schemes | arysi | 5 01 | v 00 | , |
| <u>topologico</u> | | | | | |
| Unit III | CONVERTER AND HVDC SYSTEM CONTROL | | 9 | + | 0 |
| - | of DC link control–Converter control characteristics–System control hierarchy– Firin | a an | - | - | - |
| | id extinction angle control-Starting and stopping of DC link-Power control -Higher le | | | | |
| | | velo | | | \mathbf{IS} |
| | | evel | Jon | | 18. |
| | VSC based HVDC link | evel | Jon | | 15 - |
| | | | 9 | + | 0 |
| Control of Unit IV | VSC based HVDC link REACTIVE POWER AND HARMONICS CONTROL | | 9 | + | 0 |
| Control of Unit IV Reactive p | VSC based HVDC link | | 9 | + | 0 |
| Control of Unit IV Reactive p harmonics | VSC based HVDC link REACTIVE POWER AND HARMONICS CONTROL power requirements in steady state—Sources of reactive power—SVC and STATCOM—Design of AC and DC filters —Active filters | | 9 nera | + tion | 0 of |
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| CO2 | 1 | 2 | 3 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO3 | 3 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 2 |
| CO4 | 2 | 2 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO5 | 2 | 3 | 3 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
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| 18EEP07 | EHVAC TRANSMISSION SYSTEMS | L | т | Ρ | С |
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| Course O | bjectives: | | | | |
| 1. | To understand the concept and planning of HVAC power transmission. | | | | |
| 2. | Evaluate EHVAC transmission system with all parameters | | | | |
| 3. | Understand electrostatic effects in EHVAC transmission | | | | |
| 4. | Understand effects of Corona in EHVAC transmission | | | | |
| 5. | Select a suitable voltage controller for an EHVAC transmission system | | | | |
| Unit I | INTRODUCTION | | 9 | + | 0 |
| Necessitv | of EHV AC transmission, advantages and problems, power handling capacity a | and l | ine | loss | es. |
| mechanica | al considerations, resistance of conductors, temperature rise of conductors and properties of bundled conductors – problems. | | | | |
| Unit II | LINE AND GROUND REACTIVE PARAMETERS | | 9 | + | 0 |
| Inductance | of EHV line configurations, line capacitance calculation, sequence inductances and | capa | cita | nces | , |
| line param | eters for modes of propagation, resistance and inductance of ground return. | | | | |
| Unit III | VOLTAGE GRADIENTS OF CONDUCTORS | <u> </u> | 9 | + | 0 |
| | tics, field of sphere gap, field of line changes and properties, charge – potential relation | one f | | | - |
| | s lines, surface voltage gradient on conductors, distribution of voltage gradient on sub | | | | |
| bundle, ef | ect of high electro static field on Humans, animals and plants. | | | | |
| Unit IV | CORONA EFFECTS | | 9 | . . | 0 |
| | | | - | + | - |
| | s and corona loss, corona-loss formulae, charge-voltage (q–V) diagram and corona l g waves due to corona loss, audible noise: generation and characteristics, limits for | | | | |
| noise mea | surement and meters, formulae for audible noise and its use in design, relation betwee phase AN levels example. | | | | |
| Unit V | POWER FREQUENCY VOLTAGE CONTROL | | 9 | + | 0 |
| Power circ | le diagram and its use - voltage control using synchronous condensers - cascade con | nectio | on c | of shu | Int |
| | compensation - sub synchronous resonance in series capacitor - compensated line ting system. | es - s | stati | c VA | R |
| | Total (45+ | ·0) = · | 45 I | Peric | ods |
| Course O | | •/ | | | |
| Upon com | pletion of this course, the students will be able to: | | | | |
| CO1 : | Learn about the trends in EHV AC Transmission and calculate Line inductance and | d cap | acit | ance | s |
| | of bundled conductors. | | | | |
| CO2 : | Calculate voltage gradient of bundled conductors | | | | |
| CO3 : | Understand the effects of corona like Audible noise | | | | |
| CO4 : | Understand the effect of Radio Interference and analyze travelling waves | | | | |
| CO5 : | Calculate electrostatic field of EHV AC lines | | | | |
| CO6 : | Analyze compensated devices for voltage control. | | | | |
| Text Bool | (S: | | | | |
| 1. | R. D. Begamudre, "EHVAC Transmission Engineering" New Age International (Edition, 2014. | P)Ltd | I., T | ⁻ hird | |
| 2. | S. Rao, "HVAC and DC Transmission 7 practice", Khanna Publishers, Delhi, Third E | ditior | n, 19 | 993. | |
| Reference | Books | | | | |
| 1. | Shobhit Gupta and Deepak Gupta," EHV AC/DC Transmission", Engineering Books | s Pub | lish | ers, | |
| | 2014. | | | | |

| E- Referen | ces: |
|------------|---------------------------------------|
| 1 | www.onlinecourses.nptel.ac.in |
| 2 | www.electrical-engineering-portal.com |

| PO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 2 | 2 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 2 |
| CO2 | 2 | 3 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO3 | 2 | 2 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO4 | 2 | 2 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO5 | 2 | 3 | 3 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO6 | 2 | 2 | 3 | 3 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

| 18EEP08 | FACTS CONTROLLERS | L 2 | 1 | P | C 3 |
|--|---|---|---|--|--------------------------|
| | | 3 | 0 | 0 | |
| Course O | bjectives: | | | | |
| 1. | To Introduce the Reactive Power Control Techniques. | | | | |
| 2. | To Educate on Static VAR Compensators and Their Applications | | | | |
| 3. | To Provide Knowledge on Thyristor Controlled Series Capacitors | | | | |
| 4. | To Educate on STATCOM Devices | | | | |
| 5. | To Provide Knowledge on FACTS Controllers | | | | |
| Unit I | INTRODUCTION | | 9 | + | 0 |
| Reactive Compense | Power Control in Electrical Power Transmission Lines -Uncompensated Transmission ation – Basic Concepts of Static Var Compensator (SVC) – Thyristor Controlled S Unified Power Flow Controller (UPFC). | | ne – | | ie |
| Unit II | STATIC VAR COMPENSATOR (SVC) AND APPLICATIONS | | 9 | + | 0 |
| Voltage - | Control by SVC – Advantages of Slope in Dynamic Characteristics – Influence of S Design of SVC Voltage Regulator –Modelling of SVC for Power Flow and Fast Trar ns: Enhancement of Transient Stability – Steady State Power Transfer – Enhance amping. | nsier | t Sta | bility | у- |
| Unit III | THYRISTOR CONTROLLED SERIES CAPACITOR (TCSC) AND APPLICATION | S | 9 | + | C |
| Operation | of The TCSC – Different Modes of Operation – Modelling of TCSC – Variable Rea | | | lode |) - I |
| | for Power Flow and Stability Studies. Applications: Improvement of the System nent of System Damping | | ility | _11111 | τ- |
| Enhancen Unit IV | Nent of System Damping VOLTAGE SOURCE CONVERTER BASED FACTS CONTROLLERS | Stab | 9 | + | 0 |
| Enhancen Unit IV Static Syr Steady St Operation Studies. Unit V Controller | Nent of System Damping VOLTAGE SOURCE CONVERTER BASED FACTS CONTROLLERS Inchronous Compensator (STATCOM) – Principle of Operation – V-I Characteristic ate Power Transfer-Enhancement of Transient Stability – Prevention of Voltage Ins of SSSC and the Control of Power Flow –Modelling of SSSC In Load Flow and Trans CO-ORDINATION OF FACTS CONTROLLERS Interactions – SVC – SVC Interaction – Co-Ordination of Multiple Controllers Using I | Stab s. A stabil | 9 pplica ity. S t Stat | + atior SS(pility + | 0 ns C- / |
| Enhancen Unit IV Static Syr Steady St Operation Studies. Unit V Controller | Nent of System Damping VOLTAGE SOURCE CONVERTER BASED FACTS CONTROLLERS Inchronous Compensator (STATCOM) – Principle of Operation – V-I Characteristic ate Power Transfer-Enhancement of Transient Stability – Prevention of Voltage Ins of SSSC and the Control of Power Flow –Modelling of SSSC In Load Flow and Trans CO-ORDINATION OF FACTS CONTROLLERS | Stab s. A stabil | 9 pplica ity. S t Stat | + atior SS(pility + | 0 ns: C- 7 |
| Enhancen Unit IV Static Syr Steady St Operation Studies. Unit V Controller | Nent of System Damping VOLTAGE SOURCE CONVERTER BASED FACTS CONTROLLERS Inchronous Compensator (STATCOM) – Principle of Operation – V-I Characteristic ate Power Transfer-Enhancement of Transient Stability – Prevention of Voltage Ins of SSSC and the Control of Power Flow –Modelling of SSSC In Load Flow and Trans CO-ORDINATION OF FACTS CONTROLLERS Interactions – SVC – SVC Interaction – Co-Ordination of Multiple Controllers Using I | Stab s. A stabil sien | 9 pplica ity. S t Stat 9 ar Co | + atior SS(pility + ntro | 0 ns C- 1 |
| Enhancen Unit IV Static Syr Steady St Operation Studies. Unit V Controller Technique | VOLTAGE SOURCE CONVERTER BASED FACTS CONTROLLERS Machine the control of the control control control control of the control of the control of the control of the control control of the control of the control of the control of the control control of the c | Stab s. A stabil sien | 9 pplica ity. S t Stat 9 ar Co | + atior SS(pility + ntro | 0 ns C- 1 |
| Enhancen Unit IV Static Syr Steady St Operation Studies. Unit V Controller Technique | VOLTAGE SOURCE CONVERTER BASED FACTS CONTROLLERS Inchronous Compensator (STATCOM) – Principle of Operation – V-I Characteristic ate Power Transfer-Enhancement of Transient Stability – Prevention of Voltage Ins of SSSC and the Control of Power Flow –Modelling of SSSC In Load Flow and Trans CO-ORDINATION OF FACTS CONTROLLERS Interactions – SVC – SVC Interaction – Co-Ordination of Multiple Controllers Using I es – Control Coordination Using Genetic Algorithms. Total (45+ utcomes: | Stab s. A stabil sien | 9 pplica ity. S t Stat 9 ar Co | + atior SS(pility + ntro | 0 ns C- / |
| Enhancen Unit IV Static Syr Steady St Operation Studies. Unit V Controller Technique Course O Upon com | Image: Strain | Stab s. A stabil sien | 9 pplica ity. S t Stat 9 ar Co | + atior SS(pility + ntro | 0 ns: C- 7 |
| Enhancen Unit IV Static Syr Steady St Operation Studies. Unit V Controller Technique Course O Upon com CO1 | Image: Strain | Stat | 9 pplica ity. S t Stat 9 ar Co 45 P | + atior SS(pility + ntro | 0 ns: C- 7 |
| Enhancen Unit IV Static Syr Steady St Operation Studies. Unit V Controller Technique Course O Upon com CO1 : CO2 : | Image: State of System Damping VOLTAGE SOURCE CONVERTER BASED FACTS CONTROLLERS Inchronous Compensator (STATCOM) – Principle of Operation – V-I Characteristic ate Power Transfer-Enhancement of Transient Stability – Prevention of Voltage Ins of SSSC and the Control of Power Flow –Modelling of SSSC In Load Flow and Tran CO-ORDINATION OF FACTS CONTROLLERS Interactions – SVC – SVC Interaction – Co-Ordination of Multiple Controllers Using I es – Control Coordination Using Genetic Algorithms. Total (45+ utcomes: apletion of this course, the students will be able to: Analyze Power System Operation, Stability, Control and Protection. Analyze and develop analytical model of FACTS controller for power system applic | Stat | 9 pplica ity. S t Stat 9 ar Co 45 P | + atior SS(pility + ntro | 0 ns: C- / 0 |
| Enhancen Unit IV Static Syr Steady St Operation Studies. Unit V Controller Technique Course O Upon com CO1 : CO2 : CO3 : | Nent of System Damping VOLTAGE SOURCE CONVERTER BASED FACTS CONTROLLERS Inchronous Compensator (STATCOM) – Principle of Operation – V-I Characteristic ate Power Transfer-Enhancement of Transient Stability – Prevention of Voltage Ins of SSSC and the Control of Power Flow –Modelling of SSSC In Load Flow and Tran CO-ORDINATION OF FACTS CONTROLLERS Interactions – SVC – SVC Interaction – Co-Ordination of Multiple Controllers Using I es – Control Coordination Using Genetic Algorithms. Total (45+ utcomes: appletion of this course, the students will be able to: Analyze Power System Operation, Stability, Control and Protection. Analyze and develop analytical model of FACTS controller for power system applic. Apply knowledge in load compensation techniques. | Stat | 9 pplica ity. S t Stat 9 ar Co 45 P | + atior SS(pility + ntro | 0 ns: C- / 0 |
| Enhancen Unit IV Static Syr Steady St Operation Studies. Unit V Controller Technique CO1 : CO2 : CO3 : CO3 : CO4 : | Voltrage Source Converter Based Facts ControlLers Inchronous Compensator (STATCOM) – Principle of Operation – V-I Characteristic ate Power Transfer-Enhancement of Transient Stability – Prevention of Voltage Ins of SSSC and the Control of Power Flow –Modelling of SSSC In Load Flow and Trans CO-ORDINATION OF FACTS CONTROLLERS Interactions – SVC – SVC Interaction – Co-Ordination of Multiple Controllers Using I es – Control Coordination Using Genetic Algorithms. Total (45+ utcomes: apletion of this course, the students will be able to: Analyze Power System Operation, Stability, Control and Protection. Analyze and develop analytical model of FACTS controller for power system applic. Apply knowledge in load compensation techniques. Analyze the performance of steady state and transients of facts controllers. | Stat | 9 pplica ity. S t Stat 9 ar Co 45 P | + atior SS(pility + ntro | 0 ns: C- 7 |
| Enhancen Unit IV Static Syr Steady St Operation Studies. Unit V Controller Technique Course O Upon com CO1 : CO2 : CO3 : | Nent of System Damping VOLTAGE SOURCE CONVERTER BASED FACTS CONTROLLERS Inchronous Compensator (STATCOM) – Principle of Operation – V-I Characteristic ate Power Transfer-Enhancement of Transient Stability – Prevention of Voltage Ins of SSSC and the Control of Power Flow –Modelling of SSSC In Load Flow and Tran CO-ORDINATION OF FACTS CONTROLLERS Interactions – SVC – SVC Interaction – Co-Ordination of Multiple Controllers Using I es – Control Coordination Using Genetic Algorithms. Total (45+ utcomes: appletion of this course, the students will be able to: Analyze Power System Operation, Stability, Control and Protection. Analyze and develop analytical model of FACTS controller for power system applic. Apply knowledge in load compensation techniques. | Stat | 9 pplica ity. S t Stat 9 ar Co 45 P | + atior SS(pility + ntro | 0 ns C- / |
| Enhancen Unit IV Static Syr Steady St Operation Studies. Unit V Controller Technique CO1 : CO2 : CO3 : CO4 : CO5 : | Internet of System Damping VOLTAGE SOURCE CONVERTER BASED FACTS CONTROLLERS Inchronous Compensator (STATCOM) – Principle of Operation – V-I Characteristic ate Power Transfer-Enhancement of Transient Stability – Prevention of Voltage Ins of SSSC and the Control of Power Flow –Modelling of SSSC In Load Flow and Trans CO-ORDINATION OF FACTS CONTROLLERS Interactions – SVC – SVC Interaction – Co-Ordination of Multiple Controllers Using I es – Control Coordination Using Genetic Algorithms. Total (454 utcomes: apletion of this course, the students will be able to: Analyze Power System Operation, Stability, Control and Protection. Analyze and develop analytical model of FACTS controller for power system applic Apply knowledge in load compensation techniques. Analyze the performance of steady state and transients of facts controllers. Apply knowledge in advanced FACTS controllers. | Stat | 9 pplica ity. S t Stat 9 ar Co 45 P | + atior SS(pility + ntro | 0 ns: C- 7 |
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| Enhancen Unit IV Static Syr Steady St Operation Studies. Unit V Controller Technique CO1 : CO2 : CO3 : CO4 : CO5 : | Inent of System Damping VOLTAGE SOURCE CONVERTER BASED FACTS CONTROLLERS Inchronous Compensator (STATCOM) – Principle of Operation – V-I Characteristic ate Power Transfer-Enhancement of Transient Stability – Prevention of Voltage Ins of SSSC and the Control of Power Flow –Modelling of SSSC In Load Flow and Transient SSSC and the Control of Power Flow –Modelling of SSSC In Load Flow and Transient of SSSC and the Control of Power Flow –Modelling of SSSC In Load Flow and Transient of SSSC and the Control of Power Flow –Modelling of SSSC In Load Flow and Transient of SSSC and the Control of Power Flow –Modelling of SSSC In Load Flow and Transient of SSSC and the Control of Power Flow –Modelling of SSSC In Load Flow and Transient of SSSC and the Control of Power Sustem ControlLERS Interactions – SVC – SVC Interaction – Co-Ordination of Multiple Controllers Using I es – Control Coordination Using Genetic Algorithms. Total (454 trotal (454 utcomes: Interactions - SVC – SVC Interaction – Co-Ordination of Multiple Controllers Using I es – Control Coordination Using Genetic Algorithms. Total (454 Utcomes: Interaction of this course, the students will be able to: Analyze Power System Operation, Stability, Control and Protection. Analyze and develop analytical model of FACTS controller for power system applic Apply knowledge in load compensation techniques. Analyze the performance of steady state and transients of facts controllers. Apply knowledge in advanced FACTS controllers. Ks: R.Mohan Mathur, Rajiv K.Varma, "Thyristor – Based Facts Controllers For Electric | Stat | 9 oplica ity. S t Stat 9 ar Co 45 P | + ation SSC pility + ntro eric | |
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| Referen | ce Books: |
|----------|---|
| 1. | A.T.John, "Flexible A.C. Transmission Systems", Institution of Electrical and Electronic Engineers (IEEE), 2019. |
| 2. | V.K.Sood,"HVDC And FACTS Controllers – Applications of Static Converters in Power System", APRIL 2004, Kluwer Academic Publishers, 2004. |
| 3. | Xiao – Ping Zang, Christian Rehtanz And Bikash Pal, "Flexible AC Transmission System: Modelling and Control" Springer, 2012. |
| E-Refere | nce: |
| 1 | www.onlinecourses.nptel.ac.in |
| 2 | www.class-central.com |
| 3 | www.mooc-list.com |

| PO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
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| CO1 | 1 | 1 | 1 | 2 | 3 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO2 | 1 | 3 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO3 | 3 | 1 | 1 | 3 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO4 | 2 | 1 | 1 | 3 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO5 | 1 | 1 | 1 | 3 | 1 | 1 | 2 | 1 | 1 | 1 | 1 | 1 |

| | POWER QUALITY | L | Γ | Ρ | C |
|--|---|---|---|--|-------------------------------|
| | | 3 (|) | 0 | 3 |
| Course Ol | bjectives: | | | | |
| 1. | Introduce the power quality terms and definitions | | | | |
| 2. | Understand the sources and issues of various power quality problems. | | | | |
| 3. | Gain in-depth knowledge of the mitigation/ suppression techniques of voltages sags | , inte | rrup | otio | ns |
| | and harmonics. | , | | | |
| 4. | Introduce the computer tools for transient's analysis. | | | | |
| 5. | Expose the various methods of power quality monitoring. | | | | |
| Unit I | INTRODUCTION TO POWER QUALITY | 9 | | + | 0 |
| | d definitions of Power quality, General classes of power quality problems: transients- lo | | | | - |
| voltage var | riations- short duration voltage variations, voltage Imbalance, waveform distortion, voltage quency variations-International standard of power quality-CBEMA and ITI curves. | | | | |
| Unit II | VOLTAGE SAGS AND LONG DURATION VOLTAGE VARIATIONS | g |) | + | 0 |
| Sources of | f sags and interruptions, estimating voltage sag performance, fundamental principles | of vo | Itag | qe s | ac |
| | -voltage sag mitigation solution at the End-User level- Evaluating the economics of | | | | |
| | ternatives –Motor Starting sags. | | | | |
| | ation voltage variations: Principles of regulating the voltage – devices for voltage re | | | | |
| | gulator application- capacitor for voltage regulation- End user capacitor applicationF | licker | :: so | our | ces |
| and mitiga | tion techniques. | | | | |
| Unit III | TRANSIENT OVERVOLTAGE | g | | + | 0 |
| | f transientover voltage- Principles of overvoltage Protection- Devices for mitigation of o | | | - | - |
| | acitor-switching transients – Utility system lightning protection - Managing Ferro resona | | | | |
| | | | 0 | | |
| | problems with loads - computer tools for transients analysis: PSCAD and EMTP. | | | | |
| | problems with loads - computer tools for transients analysis: PSCAD and EMTP. | | | | |
| | problems with loads - computer tools for transients analysis: PSCAD and EMTP. | 9 |) | + | 0 |
| Unit IV | · · · · | - | | + vers | - |
| Unit IV Fundamen | HARMONICS | nonic | s١ | | SUS |
| Unit IV Fundamen transients- commercia | HARMONICS htals of Harmonics: Harmonic Distortion, voltage versus current distortion, Harr harmonics phase sequences- triplen harmonics -harmonic indices, harmonic al and industrial loads. Locating harmonic sources - power system response character | nonic sour | s v ces – I | s fr Effe | on |
| Unit IV Fundamen transients- commercia of Harmon | HARMONICS htals of Harmonics: Harmonic Distortion, voltage versus current distortion, Harr harmonics phase sequences- triplen harmonics -harmonic indices, harmonic al and industrial loads. Locating harmonic sources - power system response character ics Distortion –Interharmonics - harmonic distortion evaluations, Principles and devices | nonic sour | s v ces – I | s fr Effe | on |
| Unit IV Fundamen transients- commercia of Harmon | HARMONICS htals of Harmonics: Harmonic Distortion, voltage versus current distortion, Harr harmonics phase sequences- triplen harmonics -harmonic indices, harmonic al and industrial loads. Locating harmonic sources - power system response character | nonic sour | s v ces – I | s fr Effe | om |
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| Unit IV Fundamen transients- commercia of Harmon harmonic o Unit V | HARMONICS htals of Harmonics: Harmonic Distortion, voltage versus current distortion, Harr harmonics phase sequences- triplen harmonics -harmonic indices, harmonic al and industrial loads. Locating harmonic sources - power system response character ics Distortion –Interharmonics - harmonic distortion evaluations, Principles and devices distortion, IEEE and IEC standards on harmonics. POWER QUALITY MONITORING AND DISTRIBUTED GENERATION | nonic sour istics for c | s v ces – I ont | s fr Effe rolli + | om cts ng 0 |
| Unit IV Fundamen transients- commercia of Harmon harmonic c Unit V Monitoring | HARMONICS ntals of Harmonics: Harmonic Distortion, voltage versus current distortion, Harr harmonics phase sequences- triplen harmonics -harmonic indices, harmonic al and industrial loads. Locating harmonic sources - power system response character ics Distortion –Interharmonics - harmonic distortion evaluations, Principles and devices distortion, IEEE and IEC standards on harmonics. POWER QUALITY MONITORING AND DISTRIBUTED GENERATION considerations - power quality measurement equipment: disturbance analyser, | nonic sour istics for c g spec | s v ces – I ont | s fr Effe rolli + | orr orr orts ng 0 |
| Unit IV Fundamen transients- commercia of Harmon harmonic c Unit V Monitoring harmonics | HARMONICS ntals of Harmonics: Harmonic Distortion, voltage versus current distortion, Harr harmonics phase sequences- triplen harmonics -harmonic indices, harmonic al and industrial loads. Locating harmonic sources - power system response character ics Distortion –Interharmonics - harmonic distortion evaluations, Principles and devices distortion, IEEE and IEC standards on harmonics. POWER QUALITY MONITORING AND DISTRIBUTED GENERATION considerations - power quality measurement equipment: disturbance analyser, analysers, flicker meters, applications of Intelligent system for power quality monitor | nonic sour istics for c g spec | s v ces – I ont | s fr Effe rolli + | |
| Unit IV Fundamen transients- commercia of Harmon harmonic c Unit V Monitoring harmonics | HARMONICS ntals of Harmonics: Harmonic Distortion, voltage versus current distortion, Harr harmonics phase sequences- triplen harmonics -harmonic indices, harmonic al and industrial loads. Locating harmonic sources - power system response character ics Distortion –Interharmonics - harmonic distortion evaluations, Principles and devices distortion, IEEE and IEC standards on harmonics. POWER QUALITY MONITORING AND DISTRIBUTED GENERATION considerations - power quality measurement equipment: disturbance analyser, | nonic sour istics for c g spec | s v ces – I ont | s fr Effe rolli + | |
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| Unit IV Fundamen transients- commercia of Harmon harmonic c Unit V Monitoring harmonics Generatior | HARMONICS ntals of Harmonics: Harmonic Distortion, voltage versus current distortion, Harr harmonics phase sequences- triplen harmonics -harmonic indices, harmonic al and industrial loads. Locating harmonic sources - power system response character ics Distortion –Interharmonics - harmonic distortion evaluations, Principles and devices distortion, IEEE and IEC standards on harmonics. POWER QUALITY MONITORING AND DISTRIBUTED GENERATION g considerations - power quality measurement equipment: disturbance analyser, analysers, flicker meters, applications of Intelligent system for power quality monitor n: perspectives - DG technologies - power quality issues by DG - operating conflicts Total (45+0 | nonic sour istics for c for c g spec | s v ces – I ont trur | s fr Effe rolli + n a ribu | |
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| Unit IV Fundamen transients- commercia of Harmon harmonic c Unit V Monitoring harmonics Generatior Course Ou Upon com CO1 : CO2 : CO3 : CO3 : CO3 : CO5 : | HARMONICS ntals of Harmonics: Harmonic Distortion, voltage versus current distortion, Harmonics phase sequences- triplen harmonics -harmonic indices, harmonic al and industrial loads. Locating harmonic sources - power system response characterics Distortion –Interharmonics - harmonic distortion evaluations, Principles and devices distortion, IEEE and IEC standards on harmonics. POWER QUALITY MONITORING AND DISTRIBUTED GENERATION I considerations - power quality measurement equipment: disturbance analyser, analysers, flicker meters, applications of Intelligent system for power quality monitor in: perspectives - DG technologies - power quality issues by DG - operating conflicts I utcomes: pletion of this course, the students will be able to: Understand the definitions and characterization of various power quality issues. Comprehend the sources of sag & long duration voltage variations and its control methods Analyse harmonics problem and apply filters to suppress harmonics in distribution sy Understand the operation and application of power quality measuring equipment. Know PQ issues by Distributed Generation integration with grid. | nonic sour istics for c spec ing D 9 9 9 9 9 9 9 9 1 1 1 1 1 1 1 1 1 1 | s v ces – I ont trur istr | s fr Effe rolli + n a ribu | |
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| Reference | e Books: |
|-----------|---|
| 1. | C. Sankaran ,"Power quality", CRC Press, First Indian Edition, 2019. |
| 2. | G.T.Heydt, "Electric power quality", Stars in a Circle publishers, Second Edition, 1994. |
| 3. | Arindam Ghosh and Gerald Led wich , "Power Quality Enhancement Using Custom Power Devices", Springer-Verlag Publishers, New York Inc., Second Edition.2009. |
| E-Referer | ice: |
| 1 | www.onlinecourses.nptel.ac.in |
| 2 | www.class-central.com |
| 3 | www.mooc-list.com |

| RO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 3 | 1 | | 1 | | | 1 | | | | 1 | |
| CO2 | 3 | 2 | 1 | 1 | | | 1 | | | | 1 | |
| CO3 | 3 | 1 | 1 | 1 | | | 1 | | | | 1 | |
| CO4 | 3 | 1 | 2 | 1 | | 2 | 2 | | | | 1 | |
| CO5 | 3 | 1 | 2 | 1 | | 2 | 2 | | | | 1 | |
| CO6 | 3 | 1 | 2 | 1 | | 1 | 3 | | | | 1 | |

| 18EEP10 | UTILIZATION OF ELECTRICAL ENERGY | L | т | Р | С |
|-------------------------|--|---------|------|-------|------|
| | 1 - | 3 | 0 | 0 | 3 |
| Course O | piectives | | | 1 | |
| 1. | To understand the generation of electrical power by conventional and non-convent | ional | met | hods | 5. |
| 2. | To impart knowledge on principle and design of illumination systems. | | | | |
| 3. | To analyze the performance and different methods of electric heating and electric | veldir | g. | | |
| 4. | To impart knowledge on electric traction systems and their performance. | | 0 | | |
| 5. | To understand electric drives for various industrial applications. | | | | |
| | | | | | |
| Unit I | INTRODUCTION | | 9 | + | 0 |
| Generatio | o of electrical power by conventional & non-conventional methods – a brief review of | tidal | pow | /er, | |
| | r, geothermal power, solar energy, hydro station, steam and nuclearpower plants. | | • | | |
| | s of generation – definitions – load duration curve – number and size ofgenerator un | its – C | Cost | of | |
| electrical e | energy – tariff – need for electrical energy conservation –methods. | | | | |
| | | | | | - |
| Unit II | ILLUMINATION | | 9 | + | 0 |
| | n-nature of radiation – definition – laws of illumination – luminous efficacy-photome | | | | |
| | s – design of illumination systems for residential, commercial, street lightingand spo | | | | |
| | mps -incandescent lamp- mercury vapour -fluorescent lamp-energyefficiency lamp | s – ty | pes | s of | |
| lighting sc | nemes – requirements of good lighting | | | | |
| 11 | | | | | • |
| Unit III | HEATING AND WELDING | | 9 | + | 0 |
| Introductio | n- classification of methods of heating – requirements of a good heating material – (| desig | n of | | |
| | ement – temperature control of resistance furnace – electric arc furnace –induction h | | | _ | |
| | leating – electric welding – resistance welding – electric arcwelding-electrical proper is of electric arc welding. | ties o | rar | C- | |
| application | s of electric arc weiging. | | | | |
| Unit IV | ELECTRIC TRACTION | | 9 | + | 0 |
| | n – requirements of an ideal traction system – supply systems – train movement -me | char | - | | v |
| | ment – traction motors and control –speedcontrol of three phase induction motor- m | | | | |
| | raking – recent trends in electric traction. | landpr | 0 01 | | |
| | | | | | |
| Unit V | DRIVES AND THEIR INDUSTRIAL APPLICATIONS | | 9 | + | 0 |
| Electric dr | ve –advantages of electric drive-individual drive and group drive –factors affecting s | electi | on | of mo | otor |
| | f loads - steady state -transient characteristics -size of motor- load equaliza | | | | |
| | s - modern methods of speed control of D.C drives-dynamic braking using thyristor | | | | |
| braking us | ing thyristors. | | | | |
| | | | | | |
| - | Total (45 | +0)= | 45 I | Perio | ods |
| Course O | utcomes: | | | | |
| Upon com | pletion of this course, the students will be able to: | | | | |
| | | | | | |
| CO1 : | Understand the concept of generation of electrical power from conventional and no | on-co | nve | ntion | al |
| 000 | energy resources. | | | | |
| CO2 : | Understand the economic aspects connected with power system. | | | | |
| 005 | 1. Constructions of the experimental tensional illuminations and shared and a sufficient of the illumination of the experimental second s second second s Second second s Second second seco | om fo | | | |
| CO3 : | Understand the concept behind illumination and design a suitable illumination syst | ennio | r a | | |
| CO3 : | specific application. | | ra | | |
| CO3 : CO4 : | specific application. Design and choose an appropriate heating method for specific application and gain | | or a | | |
| CO4 : | specific application. Design and choose an appropriate heating method for specific application and gain knowledge about electric welding system. | | or a | | |
| CO4 : CO5 : | specific application. Design and choose an appropriate heating method for specific application and gain knowledge about electric welding system. Understand the concepts and recent trends of traction system. | | or a | | |
| | specific application. Design and choose an appropriate heating method for specific application and gain knowledge about electric welding system. Understand the concepts and recent trends of traction system. | | or a | | |
| CO4 : CO5 : CO6 : | specific application. Design and choose an appropriate heating method for specific application and gain knowledge about electric welding system. Understand the concepts and recent trends of traction system. Understand the concepts of electric drives and their characteristics. | | or a | | |
| CO4 : CO5 : | specific application. Design and choose an appropriate heating method for specific application and gain knowledge about electric welding system. Understand the concepts and recent trends of traction system. Understand the concepts of electric drives and their characteristics. | ר | | | |
| CO4 : CO5 : CO6 : | specific application. Design and choose an appropriate heating method for specific application and gain knowledge about electric welding system. Understand the concepts and recent trends of traction system. Understand the concepts of electric drives and their characteristics. | ר | | Age | |

| 2. | Eric Openshaw Taylor, "Utilisation of Electric Energy", English Universities Press Limited, 2009 |
|-----------|---|
| 3. | J.B. Gupta, "Utilization of Electric Power and Electric Traction", S.K.Kataria and Sons, 2013. |
| Reference | e Books: |
| 1. | G.C.Garg, S.K.Gridhar&S.M.Dhir, "A Course in Utilization of Electrical Energy", Khanna Publishers, Delhi, 2003. |
| 2. | H. Partab, "Art and Science of Utilization of Electrical Energy", Dhanpat Rai and Co, New Delhi, 2004. |
| E-Referen | ice |
| 1 | www.onlinecourses.nptel.ac.in |
| 2 | www.class-central.com |
| 3 | www.mooc-list.com |

| PO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 3 | 1 | 1 | 1 | 1 | 2 | 1 | 2 | 2 | 1 | 1 | 1 |
| CO2 | 2 | 3 | 2 | 3 | 1 | 1 | 2 | 1 | 1 | | | 1 |
| CO3 | 3 | 3 | 1 | 3 | 1 | 1 | 2 | 1 | | | | |
| CO4 | 1 | 2 | 2 | 3 | 3 | 1 | 2 | 1 | | | | |
| CO5 | 3 | 1 | 1 | 2 | 1 | 1 | 2 | 1 | | 1 | | 1 |
| CO6 | 1 | 3 | 3 | 3 | 3 | 1 | 2 | 2 | | | | 1 |

| Course Objectives: 1. To get knowledge about basics of energy and energy scenario on India. 2. To understand the energy conservation concepts. 3. To know about energy auditing. Unit I ENERGY SCENARIO Commercial and Non-commercial energy -Primary energy resources - Commercial energy production - Finerergy consumption - Energy needs of growing economy - Long term energy conservation and its importance - Restructuring of the energy supply sector - Energy security - Energy conservation, climate change. Energy Conservation Act-2001 and its features. Unit II ENERGY SOURCES 9 + Electricity tariff - Load management and maximum demand control - Thermal Basics-fuels - Thermal energy contents of fuel, temperature and pressure, heat capacity, sensible and latent heat, evaporation, condensation steam, moist air and humidity & heat transfer, units and conversion. 9 + 1 Unit II ENERGY MANAGEMENT AND AUDIT 9 + 1 9 + 1 Definition - Energy audit - Need and types of energy audit. Energy management (audit) approach understandin energy balance: Facility as an energy system - Matching energy usbstitution - Energy audit instrument Material and energy subalance: Facility as an energy system - Methods for preparing process flow, material and energy system: Electricity billing - Electrical load management and maximum demand control -Power fact improvement and its benefit - Selection and tocas: Types - Losses in induction motors - Motor efficiency | Course Objectives: 1. To get knowledge about basics of energy and energy scenario on India. 2. To understand the energy conservation concepts. 3. To know about energy auditing. Jinit I ENERGY SCENARIO 9 + Commercial and Non-commercial energy -Primary energy resources - Commercial energy pricing - Energy encore regy pricing - Energy security - Energy security - Energy scenario - Energy pricing - Energy encore regy consumption - Energy supply sector - Energy strategy for the future, air pollution, climate change. Energy conservation Act-2001 and its leatures. Jinit II ENERGY SOURCES 9 + Electricity tarif - Load management and maximum demand control - Thermal Basics-fuels - Thermal energy contents of fuel, temperature and pressure, heat capacity, sensible and latent heat, evaporation, condensatio team, moist air and humidity & heat transfer, units and conversion. 9 + Jinit II ENERGY MANAGEMENT AND AUDIT 9 + Setinciencies - Optimizing the input energy requirements, fuel and energy substitution - Energy audit Instrument Adterial and energy balance: Facility as an energy system - Methods for preparing process flow, material and energy balance: Facility as an energy system - Methods for preparing process flow, material and energy balance instrument losses. Electric motors: Types - Losses in induction motors - Motor efficience mores affecting motor performance - Rewinding and motor replacement issues - Energy saving opportunitie with energy selectric motors: Types - Losses in induction motors - Motor efficience actors affecting moto | 18EEP11 | ELECTRICAL ENERGY CONSERVATION AND AUDITING | L | Т | Р | C |
|--|---|---|--|--------------------|---------------|----------------|-----------|
| 1. To get knowledge about basics of energy and energy scenario on India. 2. To understand the energy conservation concepts. 3. To know about energy auditing. Unit I ENERGY SCENARIO 9 + Commercial and Non-commercial energy -Primary energy resources - Commercial energy production - Fineergy consumption - Energy supply sector - Energy security - Energy conservation and its importance - Restructuring of the energy supply sector - Energy strategy for the future, air pollution, climate change. Energe Conservation Act-2001 and its features. Unit II ENERGY SOURCES 9 + Electricity tariff - Load management and maximum demand control - Thermal Basics-fuels - Thermal energe contents of fuel, temperature and pressure, heat capacity, sensible and latent heat, evaporation, condensation steam, moist air and humidity & heat transfer, units and conversion. Unit II ENERGY MANAGEMENT AND AUDIT 9 + Definition - Energy audit - Need and types of energy audit. Energy management (audit) approach understandin energy osits - Bench marking - Energy equirements, fuel and energy substitution - Energy audit instrument Material and energy balance diagrams. 9 + Unit II ENERGY EFFICIENCY 9 + 1 Electrical system: Electricity billing - Electrical load management and maximum demand control -Power factr improvement and its benefit - Selectorion and location of capacitors - Performance assessment of PC capacitor distribution and transformer losses. Electricin transformer - Selectronic | 1. To get knowledge about basics of energy and energy scenario on India. 2. To understand the energy conservation concepts. 3. To know about energy auditing. Jinit I ENERGY SCENARIO 9 + Commercial and Non-commercial energy -Primary energy resources - Commercial energy production - Fin energy conservation and the importance exector reforms - Energy and environment - Energy security - Energy conservation and its importance exector reforms - Energy sources - Energy strategy for the future, air pollution, climate change. Energ Conservation Act-2001 and its features. 9 + Jinit I ENERGY SOURCES 9 + Electricity tariff - Load management and maximum demand control - Thermal Basics-fuels - Thermal energy contents of fuel, temperature and pressure, heat capacity, sensible and latent heat, evaporation, condensatio team, moist air and humidity & heat transfer, units and conversion. 9 + Definition - Energy audit - Need and types of energy audit. Energy management (audit) approach understandir inergy costs - Bench marking - Energy berformance - Matching energy use to requirement - Maximizing syste afficiencies - Optimizing the input energy requirements, fuel and energy substitution - Energy audit instrument energy balance diagrams. 9 +) Jinit IV ENERGY EFFICIENCY 9 +) Linetro - Vainable speed drives - Energy efficient and maximum demand control - Power fact morowement and its benefit - Selectroin and location of capacitors - Performance assessment of PF capacitor isthergy saving porformance - Rewinding and mo | | · | 3 | 0 | 0 | 3 |
| 2. To understand the energy conservation concepts. 3. To know about energy auditing. Unit I ENERGY SCENARIO 9 + Commercial and Non-commercial energy -Primary energy resources - Commercial energy proticing - Energy sector reforms -Energy and environment - Energy security - Energy conservation and its importance - Restructuring of the energy supply sector - Energy strategy for the future, air pollution, climate change. Energ Conservation Act-2001 and its features. 9 + 1 Unit II ENERGY SOURCES 9 + 1 1 2 + 1 | 2. To understand the energy conservation concepts. 3. To know about energy auditing. Janit I ENERGY SCENARIO On know about energy auditing. Janit I ENERGY SCENARIO On know about energy auditing. Janit I ENERGY SCENARIO Janit I ENERGY SCENARIO On the energy scenario - Energy security - Energy conservation and its importance Restructuring of the energy supply sector - Energy strategy for the future, air pollution, climate change. Energ Conservation Act-2001 and its features. Jinit II ENERGY SOURCES Isotrative and management and maximum demand control - Thermal Basics-fuels - Thermal energ Conservation Act-2001 and its features. Jinit II ENERGY MANAGEMENT AND AUDIT Jeleinition - Energy audit - Need and types of energy audit. Energy management (audit) approach understandir anergy balance diagrams. Jinit II ENERGY EFFICIENCY 9 +] Lectricity billing - Electrical load management and maximum demand control -Power fact Biotricity ENERGY EFFICIENCY 9 +] Lectricity billing - Electricinal load management and max | Course Ol | ojectives: | | | | |
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| Electrical system: Electricity billing - Electrical load management and maximum demand control -Power factor improvement and its benefit - Selection and location of capacitors - Performance assessment of PF capacitors distribution and transformer losses. Electric motors: Types - Losses in induction motors - Motor efficiency Factors affecting motor performance - Rewinding and motor replacement issues - Energy saving opportunitie with energy efficient motors. Unit V ENERGY EFFICIENT TECHNOLOGIES 9 + 0 Maximum demand controllers - Automatic power factor controllers - Energy efficient motors - Softstarters with energy saver - Variable speed drives - Energy efficient transformers - Electronic ballast - Occupancy sensors - Energy efficient lighting controls - Energy saving potential of each technology. Total (45+0)= 45 Period Course Outcomes: Upon completion of this course, the students will be able to: CO1 : Understand the present energy scenario. CO2 : Get fundamental knowledge about energy and its various forms. CO3 : Understand the methods improving energy efficiency and energy efficient devices. CO5 : Conduct Energy Audit in industry. Text Books: 1. Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2017. | Electrical system: Electricity billing - Electrical load management and maximum demand control -Power fact Improvement and its benefit - Selection and location of capacitors - Performance assessment of PF capacitor Istribution and transformer losses. Electric motors: Types - Losses in induction motors - Motor efficiency Factors affecting motor performance - Rewinding and motor replacement issues - Energy saving opportunitie With energy efficient motors. Jnit V ENERGY EFFICIENT TECHNOLOGIES 9 Maximum demand controllers - Automatic power factor controllers - Energy efficient motors - Softstarters with energy saver - Variable speed drives - Energy efficient transformers - Electronic ballast - Occupancy sensors Energy efficient lighting controls - Energy saving potential of each technology. Total (45+0)= 45 Period Course Outcomes: Jpon completion of this course, the students will be able to: CO1 : Understand the present energy scenario. CO2 : Get fundamental knowledge about energy and its various forms. CO3 : Understand the process of energy management and energy auditing. CO4 : Understand the methods improving energy efficiency and energy efficient devices. CO5 : | energy cos efficiencies Material ar | ets - Bench marking - Energy performance - Matching energy use to requirement - N s - Optimizing the input energy requirements, fuel and energy substitution - Energy and energy balance: Facility as an energy system - Methods for preparing process f | /laximi audit i | zing nstri | syst umei | er nts |
| Electrical system: Electricity billing - Electrical load management and maximum demand control -Power factor improvement and its benefit - Selection and location of capacitors - Performance assessment of PF capacitors distribution and transformer losses. Electric motors: Types - Losses in induction motors - Motor efficiency Factors affecting motor performance - Rewinding and motor replacement issues - Energy saving opportunitie with energy efficient motors. Unit V ENERGY EFFICIENT TECHNOLOGIES 9 + 0 Maximum demand controllers - Automatic power factor controllers - Energy efficient motors - Softstarters with energy saver - Variable speed drives - Energy efficient transformers - Electronic ballast - Occupancy sensors - Energy efficient lighting controls - Energy saving potential of each technology. Total (45+0)= 45 Period Course Outcomes: Upon completion of this course, the students will be able to: CO1 : Understand the present energy scenario. CO2 : Get fundamental knowledge about energy and its various forms. CO3 : Understand the methods improving energy efficiency and energy efficient devices. CO5 : Conduct Energy Audit in industry. Text Books: 1. Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2017. | Electrical system: Electricity billing - Electrical load management and maximum demand control -Power fact Improvement and its benefit - Selection and location of capacitors - Performance assessment of PF capacitor Istribution and transformer losses. Electric motors: Types - Losses in induction motors - Motor efficiency Factors affecting motor performance - Rewinding and motor replacement issues - Energy saving opportunitie With energy efficient motors. Jnit V ENERGY EFFICIENT TECHNOLOGIES 9 Maximum demand controllers - Automatic power factor controllers - Energy efficient motors - Softstarters with energy saver - Variable speed drives - Energy efficient transformers - Electronic ballast - Occupancy sensors Energy efficient lighting controls - Energy saving potential of each technology. Total (45+0)= 45 Period Course Outcomes: Jpon completion of this course, the students will be able to: CO1 : Understand the present energy scenario. CO2 : Get fundamental knowledge about energy and its various forms. CO3 : Understand the process of energy management and energy auditing. CO4 : Understand the methods improving energy efficiency and energy efficient devices. CO5 : | Unit IV | | | 9 | - | 0 |
| Maximum demand controllers - Automatic power factor controllers - Energy efficient motors -Softstarters with energy saver - Variable speed drives - Energy efficient transformers - Electronic ballast - Occupancy sensors - Energy efficient lighting controls - Energy saving potential of each technology. Total (45+0)= 45 Period Course Outcomes: Upon completion of this course, the students will be able to: CO1 : Understand the present energy scenario. CO2 : Get fundamental knowledge about energy and its various forms. CO3 : Understand the process of energy management and energy auditing. CO4 : Understand the methods improving energy efficiency and energy efficient devices. CO5 : Conduct Energy Audit in industry. Text Books: 1. Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2017. | Maximum demand controllers - Automatic power factor controllers - Energy efficient motors -Softstarters with energy saver - Variable speed drives - Energy efficient transformers - Electronic ballast - Occupancy sensors Energy efficient lighting controls - Energy saving potential of each technology. Total (45+0)= 45 Period Course Outcomes: Joon completion of this course, the students will be able to: CO1 : Understand the present energy scenario. CO2 : Get fundamental knowledge about energy and its various forms. CO3 : Understand the process of energy management and energy auditing. CO4 : Understand the methods improving energy efficiency and energy efficient devices. CO5 : Conduct Energy Audit in industry. Text Books: 1. Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2017. | improveme distribution Factors aff | ent and its benefit - Selection and location of capacitors - Performance assessmen and transformer losses. Electric motors: Types - Losses in induction motors - ecting motor performance - Rewinding and motor replacement issues - Energy sa | t of PF Motor | cap effic | acito cieno | ors ;y |
| Maximum demand controllers - Automatic power factor controllers - Energy efficient motors -Softstarters with energy saver - Variable speed drives - Energy efficient transformers - Electronic ballast - Occupancy sensors - Energy efficient lighting controls - Energy saving potential of each technology. Total (45+0)= 45 Period Course Outcomes: Upon completion of this course, the students will be able to: CO1 : Understand the present energy scenario. CO2 : Get fundamental knowledge about energy and its various forms. CO3 : Understand the process of energy management and energy auditing. CO4 : Understand the methods improving energy efficiency and energy efficient devices. CO5 : Conduct Energy Audit in industry. Text Books: 1. Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2017. | Maximum demand controllers - Automatic power factor controllers - Energy efficient motors -Softstarters with energy saver - Variable speed drives - Energy efficient transformers - Electronic ballast - Occupancy sensors Energy efficient lighting controls - Energy saving potential of each technology. Total (45+0)= 45 Period Course Outcomes: Joon completion of this course, the students will be able to: CO1 : Understand the present energy scenario. CO2 : Get fundamental knowledge about energy and its various forms. CO3 : Understand the process of energy management and energy auditing. CO4 : Understand the methods improving energy efficiency and energy efficient devices. CO5 : Conduct Energy Audit in industry. Text Books: 1. Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2017. | Unit V | ENERGY EFFICIENT TECHNOLOGIES | | 9 | + | 0 |
| Course Outcomes: Upon completion of this course, the students will be able to: CO1 : Understand the present energy scenario. CO2 : Get fundamental knowledge about energy and its various forms. CO3 : Understand the process of energy management and energy auditing. CO4 : Understand the methods improving energy efficiency and energy efficient devices. CO5 : Conduct Energy Audit in industry. Text Books: 1. Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2017. | Course Outcomes: Jpon completion of this course, the students will be able to: CO1 : Understand the present energy scenario. CO2 : Get fundamental knowledge about energy and its various forms. CO3 : Understand the process of energy management and energy auditing. CO4 : Understand the methods improving energy efficiency and energy efficient devices. CO5 : Conduct Energy Audit in industry. Text Books: 1. Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2017. | Maximum energy sav | demand controllers - Automatic power factor controllers - Energy efficient motors - /er - Variable speed drives - Energy efficient transformers - Electronic ballast - Occ | | arter | s wit | h |
| Course Outcomes: Upon completion of this course, the students will be able to: CO1 : Understand the present energy scenario. CO2 : Get fundamental knowledge about energy and its various forms. CO3 : Understand the process of energy management and energy auditing. CO4 : Understand the methods improving energy efficiency and energy efficient devices. CO5 : Conduct Energy Audit in industry. Text Books: 1. Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2017. | Course Outcomes: Jpon completion of this course, the students will be able to: CO1 : Understand the present energy scenario. CO2 : Get fundamental knowledge about energy and its various forms. CO3 : Understand the process of energy management and energy auditing. CO4 : Understand the methods improving energy efficiency and energy efficient devices. CO5 : Conduct Energy Audit in industry. Text Books: 1. Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2017. | | Total (4 | 5+0)= | 45 | Perio | bd |
| CO1 : Understand the present energy scenario. CO2 : Get fundamental knowledge about energy and its various forms. CO3 : Understand the process of energy management and energy auditing. CO4 : Understand the methods improving energy efficiency and energy efficient devices. CO5 : Conduct Energy Audit in industry. Text Books: 1. Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2017. | CO1 : Understand the present energy scenario. CO2 : Get fundamental knowledge about energy and its various forms. CO3 : Understand the process of energy management and energy auditing. CO4 : Understand the methods improving energy efficiency and energy efficient devices. CO5 : Conduct Energy Audit in industry. Fext Books: 1. Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2017. | Course Ou | | <u> </u> | | | |
| CO2 : Get fundamental knowledge about energy and its various forms. CO3 : Understand the process of energy management and energy auditing. CO4 : Understand the methods improving energy efficiency and energy efficient devices. CO5 : Conduct Energy Audit in industry. Text Books: 1. Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2017. | CO2 : Get fundamental knowledge about energy and its various forms. CO3 : Understand the process of energy management and energy auditing. CO4 : Understand the methods improving energy efficiency and energy efficient devices. CO5 : Conduct Energy Audit in industry. Fext Books: 1. Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2017. | Upon com | pletion of this course, the students will be able to: | | | | |
| CO2 : Get fundamental knowledge about energy and its various forms. CO3 : Understand the process of energy management and energy auditing. CO4 : Understand the methods improving energy efficiency and energy efficient devices. CO5 : Conduct Energy Audit in industry. Text Books: 1. Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2017. | CO2 : Get fundamental knowledge about energy and its various forms. CO3 : Understand the process of energy management and energy auditing. CO4 : Understand the methods improving energy efficiency and energy efficient devices. CO5 : Conduct Energy Audit in industry. Fext Books: 1. Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2017. | CO1 : | | | | | |
| CO3 : Understand the process of energy management and energy auditing. CO4 : Understand the methods improving energy efficiency and energy efficient devices. CO5 : Conduct Energy Audit in industry. Text Books: 1. Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2017. | CO3 : Understand the process of energy management and energy auditing. CO4 : Understand the methods improving energy efficiency and energy efficient devices. CO5 : Conduct Energy Audit in industry. Fext Books: 1. Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2017. | CO2 : | | | | | |
| CO5 : Conduct Energy Audit in industry. Text Books: 1. Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2017. | CO5 : Conduct Energy Audit in industry. Fext Books: 1. Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2017. | CO3 : | Understand the process of energy management and energy auditing. | | | | |
| Text Books: 1. Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2017. | Fext Books: 1. Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2017. | CO4 : | Understand the methods improving energy efficiency and energy efficient devices | | | | |
| 1. Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2017. | 1. Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2017. | CO5 : | Conduct Energy Audit in industry. | | | | |
| 1. Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2017. | 1. Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2017. | Text Book | s. | | | | |
| | | | | | | | |
| | | | 1 other book, inclusion of Energy Addit, incore within, 2017 . | | | | |
| | | | Tripathy, S. C. "Utilization of Electrical Energy and Conservation" McGraw Hill 10 | 991 | | | |

| Reference | Books: |
|-----------|--|
| 1. | General Aspects of Energy Management and Energy Audit, Bureau of Energy Efficiency, New Delhi, 2015. |
| 2. | Energy Efficiency in Electrical Utilities, Bureau of Energy Efficiency, New Delhi, 2015. |
| E-Referen | ces: |
| 1. | www.bee-india.nic.in |
| 2. | NPTEL Course: Non-Conventional Energy Resources – Prof. PrathapHaridoss, IIT-M. |
| 3. | NPTEL Course: Energy Management Systems and SCADA, 2015 organised by IIT-M. |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 1 | 2 | 3 | 2 | 2 | 1 | 3 | 2 | 2 | 2 | 2 | 2 |
| CO2 | 1 | 1 | 2 | 2 | 1 | 1 | 3 | 2 | 1 | 1 | 2 | 2 |
| CO3 | 2 | 2 | 2 | 3 | 1 | 1 | 3 | 2 | 2 | 2 | 1 | 2 |
| CO4 | 2 | 1 | 2 | 2 | 1 | 1 | 3 | 2 | 1 | 2 | 2 | 2 |
| CO5 | 2 | 2 | 3 | 1 | 2 | 1 | 3 | 1 | 2 | 1 | 2 | 1 |

| 18EEP12 | POWER SYSTEM OPERATION AND CONTROL | L 7 | P | С |
|--------------|---|------------|--------|------|
| | | 3 (|) 0 | 3 |
| Course Ob | ectives: | | | |
| 1 | To get an overview of system operation and control. | | | |
| 2 | To understand and model power-frequency dynamics and to design power-freque | ency cor | trolle | r. |
| 3 | To understand and model reactive power-voltage interaction and different metho | | | |
| Ū. | maintaining voltage profile against varying system load. | | | 01 |
| 4 | To study the economic operation of power system | | | |
| 5 | To teach about SCADA and its application for real time operation and control of p | ower sv | stems | |
| | | | | |
| Unit I | OVERVIEW OF POWER SYSTEM OPERATION AND CONTROL | 9 | - | 0 |
| | d variation: System load characteristics, load curves -daily, weekly and annual, load | | | |
| | diversity factor - Reserve requirements: Installed, spinning, cold and hot reserv | | | |
| | ration: Load forecasting, unit commitment, load dispatching. Overview of system c | ontrol: C | Soveri | nor |
| control, LFC | C, EDC, AVR, system voltage control, security control. | | | |
| Unit II | REAL POWER - FREQUENCY CONTROL | 9 | + | 0 |
| | als of speed governing mechanism and modeling: Speed-load characteristics | - | | rina |
| | o synchronous machines in parallel; concept of control area, LFC control of a sin | | | |
| Static and | dynamic analysis of uncontrolled and controlled cases; Multi-area systems: T | wo-are | a sys | tem |
| | atic analysis, uncontrolled case, tie-line with frequency bias control; state variable n | iodel- in | tegrat | tion |
| of economic | dispatch control with LFC. | | | |
| 11 | | | | |
| Unit III | REACTIVE POWER-VOLTAGE CONTROL | 9 | | 0 |
| | itation system, modeling, static and dynamic analysis, stability compensation; | | | |
| | of reactive power: Relation between voltage, power and reactive power at a node; r ction of reactive power, Tap-changing transformer, numerical problems - System le | | | |
| | roltage magnitude setting, tap setting of OLTC transformer and MVAR injecti | | | |
| | o maintain acceptable voltage profile and to minimize transmission loss. | | Witten | Ju |
| | · · · · · · · · · · · · · · · · · · · | | | |
| Unit IV | ECONOMIC DISPATCH AND UNIT COMMITMENT | 9 | | 0 |
| | cost curve, co-ordination equations with and without loss, solution by direct method | | | |
| | thod (No derivation of loss coefficients.)- Base point and participation factors- Ed | onomic | dispa | atch |
| | dded to LFC control. | | | |
| | of Unit Commitment problem- Constraints in Unit Commitment: spinning reser | | | |
| | hydro constraints- fuel constraints and other constraints; Unit Commitment so | | | |
| | methods, forward dynamic programming approach, numerical problems only in pr ad average production cost. | iority-lis | st met | noa |
| | | | | |
| Unit V | COMPUTER CONTROL OF POWER SYSTEMSIN | 9 | + | 0 |
| | ns - Energy control centre functions: Monitoring, data acquisition and control, ener | av cont | rol ce | ntre |
| | ADA: system hardware configuration –master station-remote terminal units- and fu | | | |
| | termination- state estimation, security analysis and control - Various operating stat | | | |
| | extremis and restorative; State transition diagram showing various state transit | | | |
| strategies. | | | | |
| | | | | |
| | Total (45 | +0)= 45 | Perio | ods |
| Course Ou | comes: | | | |
| Upon comp | etion of this course, the students will be able to: | | | |
| CO1 : | Understand the overview of power system operation and control. | | | |
| CO2 : | Design power-frequency controller for single and two area system | | | |
| | | | | |

| CO3 : Understand reactive power control methods for maintaining voltage profile against varying systemade. CO4 : Formulate the optimal scheduling problems in power system. CO5 : Get the knowledge about the computer control of power systems. Text Books: 1. Allen J. Wood and Bruce F.Wollenberg, "Power Generation, Operation and Control", Wiley Ir Ltd, New Delhi, Second Edition, Reprint 2016. 2. Olle. I. Elgerd, 'Electric Energy Systems Theory – An Introduction', Tata McGraw Hill Publishing Company Ltd, New Delhi, 34 th reprint 2010. 3. P. Kundur, 'Power System Stability & Control', Tata McGraw Hill Education Pvt. Ltd., New Delhi 10 th reprint 2011. Reference Books: 1. D.P. Kothari and I.J. Nagrath, 'Modern Power System Analysis', Fourth, Tata McGraw I Education Pvt., Limited, New Delhi, 2011. | |
|--|-----|
| CO4 : Formulate the optimal scheduling problems in power system. CO5 : Get the knowledge about the computer control of power systems. Text Books: Image: Comparison of the computer control of power systems. 1. Allen J. Wood and Bruce F.Wollenberg, "Power Generation, Operation and Control", Wiley Ir Ltd, New Delhi, Second Edition, Reprint 2016. 2. Olle. I. Elgerd, 'Electric Energy Systems Theory – An Introduction', Tata McGraw Hill Publishing Company Ltd, New Delhi, 34 th reprint 2010. 3. P. Kundur, 'Power System Stability & Control', Tata McGraw Hill Education Pvt. Ltd., New Det 10 th reprint 2011. Reference Books: 1. D.P. Kothari and I.J. Nagrath, 'Modern Power System Analysis', Fourth, Tata McGraw I | em |
| CO5 : Get the knowledge about the computer control of power systems. Text Books: Allen J. Wood and Bruce F.Wollenberg, "Power Generation, Operation and Control", Wiley Ir Ltd, New Delhi, Second Edition, Reprint 2016. 2. Olle. I. Elgerd, 'Electric Energy Systems Theory – An Introduction', Tata McGraw Hill Publishing Company Ltd, New Delhi, 34 th reprint 2010. 3. P. Kundur, 'Power System Stability & Control', Tata McGraw Hill Education Pvt. Ltd., New De 10 th reprint 2011. Reference Books: 1. D.P. Kothari and I.J. Nagrath, 'Modern Power System Analysis', Fourth, Tata McGraw I | |
| Text Books: 1. Allen J. Wood and Bruce F.Wollenberg, "Power Generation, Operation and Control", Wiley Ir 1. Ltd, New Delhi, Second Edition, Reprint 2016. 2. Olle. I. Elgerd, 'Electric Energy Systems Theory – An Introduction', Tata McGraw Hill Publishing Company Ltd, New Delhi, 34 th reprint 2010. 3. P. Kundur, 'Power System Stability & Control', Tata McGraw Hill Education Pvt. Ltd., New Delhi, 10 th reprint 2011. Reference Books: 1. D.P. Kothari and I.J. Nagrath, 'Modern Power System Analysis', Fourth, Tata McGraw I | |
| 1. Allen J. Wood and Bruce F.Wollenberg, "Power Generation, Operation and Control", Wiley Ir 1. Ltd, New Delhi, Second Edition, Reprint 2016. 2. Olle. I. Elgerd, 'Electric Energy Systems Theory – An Introduction', Tata McGraw Hill Publishing Company Ltd, New Delhi, 34 th reprint 2010. 3. P. Kundur, 'Power System Stability & Control', Tata McGraw Hill Education Pvt. Ltd., New Delhi 10 th reprint 2011. Reference Books: 1. D.P. Kothari and I.J. Nagrath, 'Modern Power System Analysis', Fourth, Tata McGraw Hill | |
| 1. Allen J. Wood and Bruce F.Wollenberg, "Power Generation, Operation and Control", Wiley Ir 1. Ltd, New Delhi, Second Edition, Reprint 2016. 2. Olle. I. Elgerd, 'Electric Energy Systems Theory – An Introduction', Tata McGraw Hill Publishing Company Ltd, New Delhi, 34 th reprint 2010. 3. P. Kundur, 'Power System Stability & Control', Tata McGraw Hill Education Pvt. Ltd., New Delhi 10 th reprint 2011. Reference Books: 1. D.P. Kothari and I.J. Nagrath, 'Modern Power System Analysis', Fourth, Tata McGraw Hill | |
| 1. Ltd, New Delhi, Second Edition, Reprint 2016. 2. Olle. I. Elgerd, 'Electric Energy Systems Theory – An Introduction', Tata McGraw Hill Publishing Company Ltd, New Delhi, 34 th reprint 2010. 3. P. Kundur, 'Power System Stability & Control', Tata McGraw Hill Education Pvt. Ltd., New Delhi, 10 th reprint 2011. Reference Books: 1. D.P. Kothari and I.J. Nagrath, 'Modern Power System Analysis', Fourth, Tata McGraw H | |
| Ltd, New Delhi, Second Edition, Reprint 2016. 2. Olle. I. Elgerd, 'Electric Energy Systems Theory – An Introduction', Tata McGraw Hill Publishing Company Ltd, New Delhi, 34 th reprint 2010. 3. P. Kundur, 'Power System Stability & Control', Tata McGraw Hill Education Pvt. Ltd., New Delhi, 10 th reprint 2011. Reference Books: 1. D.P. Kothari and I.J. Nagrath, 'Modern Power System Analysis', Fourth, Tata McGraw I | lia |
| 2. Publishing Company Ltd, New Delhi, 34 th reprint 2010. 3. P. Kundur, 'Power System Stability & Control', Tata McGraw Hill Education Pvt. Ltd., New Delhi, 10 th reprint 2011. Reference Books: 1. D.P. Kothari and I.J. Nagrath, 'Modern Power System Analysis', Fourth, Tata McGraw Hill | |
| Publishing Company Ltd, New Delhi, 34 th reprint 2010. 3. P. Kundur, 'Power System Stability & Control', Tata McGraw Hill Education Pvt. Ltd., New Delhi, 10 th reprint 2011. Reference Books: 1. D.P. Kothari and I.J. Nagrath, 'Modern Power System Analysis', Fourth, Tata McGraw H | |
| 3. 10 th reprint 2011. Reference Books: 1. D.P. Kothari and I.J. Nagrath, 'Modern Power System Analysis', Fourth, Tata McGraw I | |
| 10" reprint 2011. Reference Books: 1. D.P. Kothari and I.J. Nagrath, 'Modern Power System Analysis', Fourth, Tata McGraw I | hi, |
| 1. D.P. Kothari and I.J. Nagrath, 'Modern Power System Analysis', Fourth, Tata McGraw I | |
| 1. D.P. Kothari and I.J. Nagrath, 'Modern Power System Analysis', Fourth, Tata McGraw I | |
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| Education But Limited New Delbi 2011 | ill |
| | |
| 2. L.L. Grigsby, 'The Electric Power Engineering, Hand Book', CRC Press & IEEE Press, 2012 | |
| | |
| E-Reference | |
| 1 NPTEL courses on Power System Operation and Control, IIT, Bombay. | |
| 2. NPTEL courses on Power System Generation, Transmission And Distribution, IIT Delhi. | |

| PO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | | | | 1 | 1 |
| CO2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | | | | 2 | 2 |
| CO3 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | | | | 1 | 1 |
| CO4 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | | | | 2 | 2 |
| CO5 | 2 | 2 | 2 | 2 | 2 | | | | | | 1 | 1 |

| 18EEP13 | DISTRIBUTED GENERATION AND MICROGRID | L | Т | Ρ | С |
|---|--|--------------------------------|---|--|--|
| | | 3 | 0 | 0 | 3 |
| Course O | - | | | | |
| 1. | To understand the concept of microgrid | | | | |
| 2. | To impart knowledge about distributed generation technologies, their interconnectio | n in | grid | | |
| 3. | To understand relevance of power electronics in DG, | | | | |
| Unit I | INTRODUCTION | | 9 | + | 0 |
| Conventio conventior | nal power generation: advantages and disadvantages, Energy crises, Nor nal energy (NCE) resources: review of Solar PV, Wind Energy systems, Fuel Cell and tidal sources | | - | - | - |
| Unit II | DISTRIBUTED GENERATIONS (DG | | 9 | + | 0 |
| for interco | f distributed generations, topologies, selection of sources, regulatory standards/ frame nnecting Distributed resources to electric power systems: IEEE 1547. DG installation DG implementations. Energy storage elements: Batteries, ultra-capacitors, flywheels. | clas | ses | , sec | urity |
| Unit III | IMPACT OF GRID INTEGRATION | | 9 | + | 0 |
| | ents for grid interconnection, limits on operational parameters,: voltage, frequency, The mal operating conditions, islanding issues. Impact of grid integration with NCE sources of the s | | | | |
| | liability, stability and power quality issues. | | | 51 | |
| | liability, stability and power quality issues. BASICS OF A MICROGRID | | 9 | + | 0 |
| system: re Unit IV Concept a | BASICS OF A MICROGRID and definition of microgrid, microgrid drivers and benefits, review of sources of r and configuration of a microgrid, AC and DC microgrids, Power Electronics interfac | nicro | 9 ogric | + Is, ty | /pica |
| System: re Unit IV Concept a structure a | BASICS OF A MICROGRID and definition of microgrid, microgrid drivers and benefits, review of sources of r and configuration of a microgrid, AC and DC microgrids, Power Electronics interfac | nicro | 9 ogric | + Is, ty | /pica |
| System: re Unit IV Concept a structure a microgrids Unit V Modes of o reactive p techniques | BASICS OF A MICROGRID and definition of microgrid, microgrid drivers and benefits, review of sources of r and configuration of a microgrid, AC and DC microgrids, Power Electronics interfac | micro æs i | 9 ogric n D(9 iicati | + Is, ty C an + on b | /pica d A(0 |
| System: re Unit IV Concept a structure a microgrids Unit V Modes of o reactive p techniques Microgrid o | BASICS OF A MICROGRID and definition of microgrid, microgrid drivers and benefits, review of sources of r and configuration of a microgrid, AC and DC microgrids, Power Electronics interface CONTROL AND OPERATION OF MICROGRID operation and control of microgrid: grid connected and islanded mode, Active and ower control, protection issues, anti-islanding schemes: passive, active and communication infrastructure, Power quality issues in microgrids, register economics, Introduction to smart microgrids. | micro ces i mur ulato | 9 ogric n D(9 icati | + Is, ty C an + on t | /pica d A(0 0 base lards |
| System: re Unit IV Concept a structure a microgrids Unit V Modes of o reactive p techniques Microgrid o Course O | BASICS OF A MICROGRID and definition of microgrid, microgrid drivers and benefits, review of sources of r and configuration of a microgrid, AC and DC microgrids, Power Electronics interface CONTROL AND OPERATION OF MICROGRID operation and control of microgrid: grid connected and islanded mode, Active and ower control, protection issues, anti-islanding schemes: passive, active and comiss, microgrid communication infrastructure, Power quality issues in microgrids, regression s, microgrid communication to smart microgrids. Total (autometers) | micro ces i mur ulato | 9 ogric n D(9 icati | + Is, ty C an + on t | /pica d A(0 0 base lards |
| System: re Unit IV Concept a structure a microgrids Unit V Modes of o reactive p techniques Microgrid o Course O Upon com | BASICS OF A MICROGRID and definition of microgrid, microgrid drivers and benefits, review of sources of r and configuration of a microgrid, AC and DC microgrids, Power Electronics interface CONTROL AND OPERATION OF MICROGRID operation and control of microgrid: grid connected and islanded mode, Active and ower control, protection issues, anti-islanding schemes: passive, active and comiss, microgrid communication infrastructure, Power quality issues in microgrids, regression s, microgrid communication to smart microgrids. Total (Utcomes: pletion of this course, the students will be able to | micro ces i mur ulato | 9 ogric n D(9 icati | + Is, ty C an + on t | /pica d A(0 0 base lards |
| System: re Unit IV Concept a structure a microgrids Unit V Modes of o reactive p techniques Microgrid o Course O Upon com CO1 : | BASICS OF A MICROGRID and definition of microgrid, microgrid drivers and benefits, review of sources of r and configuration of a microgrid, AC and DC microgrids, Power Electronics interface CONTROL AND OPERATION OF MICROGRID operation and control of microgrid: grid connected and islanded mode, Active and ower control, protection issues, anti-islanding schemes: passive, active and comes, microgrid communication infrastructure, Power quality issues in microgrids, regression to smart microgrids. Total (automes: pletion of this course, the students will be able to Explain various distributed generation systems | micro ces i mur ulato | 9 ogric n D(9 icati | + Is, ty C an + on t | /pica d A(0 0 base lards |
| System: re Unit IV Concept a structure a microgrids Unit V Modes of o reactive p techniques Microgrid o Course O Upon com CO1 : CO2 : | BASICS OF A MICROGRID and definition of microgrid, microgrid drivers and benefits, review of sources of r and configuration of a microgrid, AC and DC microgrids, Power Electronics interface CONTROL AND OPERATION OF MICROGRID operation and control of microgrid: grid connected and islanded mode, Active and ower control, protection issues, anti-islanding schemes: passive, active and comes, microgrid communication infrastructure, Power quality issues in microgrids, regrescioned communication to smart microgrids. Total (automes: pletion of this course, the students will be able to Explain various distributed generation systems Understand various developments happening in the field of Grid integration. | micro ces i mur ulato | 9 ogric n D(9 icati | + Is, ty C an + on t | /pica d A(0 0 base lards |
| System: re Unit IV Concept a structure a microgrids Unit V Modes of o reactive p techniques Microgrid o Upon com CO1 : CO2 : CO3 : | BASICS OF A MICROGRID and definition of microgrid, microgrid drivers and benefits, review of sources of r and configuration of a microgrid, AC and DC microgrids, Power Electronics interface CONTROL AND OPERATION OF MICROGRID operation and control of microgrid: grid connected and islanded mode, Active and ower control, protection issues, anti-islanding schemes: passive, active and comiss, microgrid communication infrastructure, Power quality issues in microgrids, regrescionemics, Introduction to smart microgrids. Total (automes: pletion of this course, the students will be able to Explain various distributed generation systems Understand various developments happening in the field of Grid integration. Understand the microgrids and their control schemes. | micro ces i mur ulato | 9 ogric n D(9 icati | + Is, ty C an + on t | /pica d A(0 0 base lards |
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| Referen | e Books: |
|----------|---|
| 1 | John Twidell and Tony Weir, "Renewable Energy Resources" Tyalor and Francis |
| | Publications, 2015, 3 rd edition |
| 2 | DorinNeacsu, "Power Switching Converters: Medium and High Power", CRC |
| | Press, Taylor & Francis, 2006. |
| 3 | AmirnaserYezdani, and Reza Iravani, "Voltage Source Converters in Power Systems: |
| | Modeling, Control and Applications", IEEE John Wiley Publications, 2009 |
| 4 | F. Katiraei, M.R. Iravani, 'Transients of a Micro-Grid System with Multiple Distributed Energy |
| | Resources', International Conference on Power Systems Transients (IPST'05) in Montreal, Canada |
| | on June 19-23, 2005. |
| 5 | Z. Ye, R. Walling, N. Miller, P. Du, K. Nelson, 'Facility Microgrids', General Electric Global Research |
| | Center, Niskayuna, New York, Subcontract report, May 2005 |
| | |
| E-Refere | nce |
| 1 | www.onlinecourses.nptel.ac.in |
| 2 | www.class-central.com |
| 3 | www.mooc-list.com |

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| CO1 | 1 | 2 | 2 | 2 | 2 | 1 | 2 | 1 | | | | 2 |
| CO2 | 1 | 2 | 2 | 2 | 2 | 1 | 2 | 1 | | | | 2 |
| CO3 | 1 | 2 | 2 | 2 | 2 | 1 | 2 | 1 | | | | 2 |
| CO4 | 1 | 2 | 2 | 2 | 2 | 1 | 2 | 1 | | | | 2 |
| CO5 | 1 | 2 | 2 | 2 | 2 | 1 | 2 | 1 | | | | 2 |

| 18EEP14 | |
|------------|---|
| Course (| |
| 1. | Understand the concepts of power generation through Wind and Solar Power |
| 2. | Learn optimal extraction of renewable power and their integration to grid |
| | |
| Unit I | PHYSICS OF WIND POWER9+0 |
| | f wind power, Indian and Global statistics, Wind physics, Betz limit, Tip speed ratio, stall |
| | control, Wind speed statistics-probability distributions, Wind speed and power-cumulative distribution |
| functions | |
| Unit II | WIND GENERATOR TOPOLOGIES 9 + 0 |
| Review | of modern wind turbine technologies, Fixed and Variable speed wind turbines, Induction |
| | ors, Doubly-Fed Induction Generators and their characteristics, Permanent-Magnet Synchronous |
| Generato | ors, Power electronics converters. Generator-Converter configurations, Converter Control. |
| 11 | |
| Unit III | THE SOLAR RESOURCE 9 + 0 |
| | ion, solar radiation spectra, solar geometry, Earth Sun angles, observer Sun angles, solar day stimation of solar energy availability. |
| iongui, Ei | Sumation of Solar Chorgy availability. |
| Unit IV | SOLAR PHOTOVOLTAIC 9 + 0 |
| | gies-Amorphous, monocrystalline, polycrystalline; V-I characteristics of a PV cell, PV |
| | array, Power Electronic Converters for Solar Systems, Maximum Power Point Tracking (MPPT) |
| algorithm | ns.Converter Control. |
| | |
| Unit V | GRID INTEGRATION ISSUES9+0 |
| | v of grid code technical requirements. Fault ride-through for wind farms – real and reactive |
| | egulation, voltage and frequency operating limits, solar PV and wind farm behavior during grid |
| | nces. Power quality issues. Power system interconnection experiences in the world. Hybrid and |
| Isolated C | operations of solar PV and wind systems. |
| | Total (45+0)= 45 Periods |
| Course C | Dutcomes: |
| Upon con | npletion of this course, the students will be able to: |
| CO1 | : Understand the physics behind the wind and solar power generation |
| CO2 | : Implementation of optimal extraction techniques in renewable power generation |
| CO3 | : Apply power electronics to renewable power optimization |
| CO4 | : Understand integration techniques used, power quality issues and their mitigation |
| CO5 | : Device methods to create an approximate energy conversion systems. |
| Text Boo | |
| Text Dou | Mohan, Net al. "Power Electronics: Converters, Application and Design", Wiley India (P) Ltd, New |
| 1. | Delhi, 2008. |
| 2. | Bimbhra, P.S, "Power Electronics ", Khanna Publishers, New Delhi, 4 th Edition, 2018. |
| | |
| Reference | ce Books: |
| 1. | T. Ackermann, "Wind Power in Power Systems", John Wiley and Sons Ltd., 2012, 2 nd edition. |
| 2. | G. M. Masters, "Renewable and Efficient Electric Power Systems", John Wiley and Sons, 2013 |
| 3. | S. P. Sukhatme, "Solar Energy: Principles of Thermal Collection and Storage", McGraw Hill, 2008. |
| 4. | S. F. Sukhatme, Solar Energy. Finiciples of Thermal Collection and Storage, McGraw Fill, 2008. |
| | H. Siegfried and R. Waddington, "Grid integration of wind energy conversion systems" John Wiley |
| | H. Siegfried and R. Waddington, "Grid integration of wind energy conversion systems" John Wiley and Sons Ltd., 2006 |
| 5. | H. Siegfried and R. Waddington, "Grid integration of wind energy conversion systems" John Wiley |
| 5. | H. Siegfried and R. Waddington, "Grid integration of wind energy conversion systems" John Wiley and Sons Ltd., 2006 G. N. Tiwari and M. K. Ghosal, "Renewable Energy Applications", Narosa Publications, 2004. |
| | H. Siegfried and R. Waddington, "Grid integration of wind energy conversion systems" John Wiley and Sons Ltd., 2006 G. N. Tiwari and M. K. Ghosal, "Renewable Energy Applications", Narosa Publications, 2004. J. A. Duffie and W. A. Beckman, "Solar Engineering of Thermal Processes", John Wiley & Sons, |
| 5. | H. Siegfried and R. Waddington, "Grid integration of wind energy conversion systems" John Wiley and Sons Ltd., 2006 G. N. Tiwari and M. K. Ghosal, "Renewable Energy Applications", Narosa Publications, 2004. |

| E-Reference | ce |
|-------------|-------------------------------|
| 1 | www.onlinecourses.nptel.ac.in |
| | www.class-central.com |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 1 | 1 | 1 |
| CO2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 1 | 1 | 1 |
| CO3 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 1 | 1 | 1 |
| CO4 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 1 | 1 | 1 |
| CO5 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

| | 15 ELECTRICAL AND HYBRID VEHICLES | L | Т | Ρ | С |
|--|--|---|--------------------------------|---------------------|--|
| | | 3 | 0 | 0 | 3 |
| | Objectives: | | | | |
| To unde | rstand the operation and need of electrical vehicles, hybrid vehicles with its energy stora | ge te | chno | ologie | es |
| 11 | | | • | 1 | |
| Unit I | ELECTRIC VEHICLES | Ohar | 9 | + | 0 |
| - | rations of Electric Vehicles (EV), Performance of Electric Vehicles: Traction Motor Effort and Transmission Requirement, Vehicle Performance, Energy Consumption | Char | acte | eristic | s, |
| Hactive | Lifert and Transmission Requirement, venicle r enormance, Energy Consumption | | | | |
| Unit II | HYBRID ELECTRIC VEHICLES | | 9 | + | 0 |
| Concept | t of Hybrid Electric Vehicle (HEV) Trains, Architectures of Hybrid Electric Drive Trair | ns, Se | eries | s Hyt | orid |
| Electric | Drive Trains and Parallel Hybrid Electric Drive Trains, Torque-Coupling Parallel Hyb | rid E | ectr | ic Di | rive |
| Trains, S | Speed-Coupling Parallel Hybrid Electric Drive Trains, Torque-Coupling and Speed-Co | ouplin | g P | aralle | əl |
| Hybrid E | ectric Drive Trains | | | | |
| | | | | 1 | |
| Unit III | ELECTRIC PROPULSION SYSTEMS | | 9 | + | 0 |
| | hal block diagram of a typical electric propulsion system, Classification of electric mo | | | | |
| | V applications, Multiquadrant Control of Chopper-Fed DC Motor Drives, Performan | | - | | |
| | of BLDC Machines, Switched Reluctance Motor Drives, SRM Drive Converter, Gen on, Vibration and Acoustic Noise in SRM | eratir | ig n | loae | 01 |
| Operatio | | | | | |
| Unit IV | ENERGY STORAGES | | 9 | + | 0 |
| | Technologies: Lead-Acid Batteries, Nickel-based Batteries, Lithium-Based Batteries – | Liltro | - | | - |
| Dationy | | UIIIA | | | S |
| Feature | - | | - | | |
| | s, Basic Principles and its Performance, Ultracapacitor Technologies- Ultrahigh-Sp | | - | | |
| | - | | - | | |
| | s, Basic Principles and its Performance, Ultracapacitor Technologies- Ultrahigh-Sp | | - | | |
| Operation Unit V Fuel cel | s, Basic Principles and its Performance, Ultracapacitor Technologies- Ultrahigh-Sp on and Power Capacity FUEL CELL VEHICLES I – Characteristics- Types – hydrogen Storage Systems and Fuel cell Electric Vehicle | beed | Flyv 9 | vhee | ls, 0 |
| Operation Unit V Fuel cel | s, Basic Principles and its Performance, Ultracapacitor Technologies- Ultrahigh-Spon and Power Capacity FUEL CELL VEHICLES I – Characteristics- Types – hydrogen Storage Systems and Fuel cell Electric Vehicle trol strategy | eed | Flyv 9 nfig | vhee + uratio | ls, 0 on |
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| Operation Unit V Fuel cel and con | s, Basic Principles and its Performance, Ultracapacitor Technologies- Ultrahigh-Spon and Power Capacity FUEL CELL VEHICLES I – Characteristics- Types – hydrogen Storage Systems and Fuel cell Electric Vehicle trol strategy Total (45 Outcomes: | eed | Flyv 9 nfig | vhee + uratio | ls, 0 on |
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| Operation Unit V Fuel cel and con Course Upon co CO1 CO2 CO3 CO4 CO5 Text Bo 1. Referen | s, Basic Principles and its Performance, Ultracapacitor Technologies- Ultrahigh-Spon and Power Capacity FUEL CELL VEHICLES - Characteristics- Types – hydrogen Storage Systems and Fuel cell Electric Vehicle trol strategy Total (45 Outcomes: mpletion of this course, the students will be able to: Understand the operation of Electrical Vehicles and its energy storage technologie Know Fuel cell, types and characteristics. Operate the vehicle with BLDC and SRM motor drives Design the EV's and HEV's. Choose the energy storage technology for electric vehicle oks: Mehrdad Ehsani, Yimin Gao, Sebastien E. Gay, Ali Emadi, 'Modern Electric, Hydr Fuel Cell Vehicles Fundamentals, Theory, and Design', CRC PRESS, New York 2016 | beed = - co 5+0)= = = = = = = = = = = = = = | 9 nfig 45 lect edi | vhee | ls, 0 on ods |

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| CO2 | | 2 | | 1 | 3 | | 2 | | | | 1 | |
| CO3 | | | | 2 | 2 | | | | | 2 | | |
| CO4 | 1 | | 3 | 3 | | 2 | | | 3 | | 2 | |
| CO5 | | 3 | | | | | 3 | 1 | | | | 2 |

| 18EEP16 | SOFT COMPUTING AND MACHINE LEARNING | L 3 | T | P | <u>C</u> 3 |
|--|--|-----------------|--|--|-----------------------|
| | | 3 | 0 | 0 | 3 |
| Course Ol | - | | | | |
| 1 | To provide adequate knowledge about neural network and fuzzy systems | | | | |
| 2 | To provide adequate knowledge of genetic algorithms and its application to econom | nic d | ispa | tch a | ind |
| 3 | unit commitment problems To expose the students to the concepts of machine learning | | | | |
| 0 | | | | | |
| Unit I | BASIC CIRCUITS ANALYSIS | | 9 | + | 0 |
| | n – Biological neuron – Artificial neuron – Neuron model – Supervised and unsu er – Multi layer feed forward network – Learning algorithm- Back propagation n | | | | |
| Unit II | NETWORK REDUCTION AND NETWORK THEOREMS FOR DC AND AC CIRCUITS | | 9 | + | 0 |
| function – | ets – Fuzzy sets – Fuzzy relations – Fuzzification – Defuzzification – Fuzzy rules – M Knowledge base – Decision-making logic – Introduction to neuro fuzzy system- Adap uzzy logic control: Home heating system – fuzzy PID control, Fuzzy based motor con | otive | | | |
| Unit III | GENETIC ALGORITHMS | | 9 | + | 0 |
| | n-Gradient Search – Non-gradient search – Genetic Algorithms: binary and re | | | | |
| | selection methods, crossover and mutation operators for binary and real coding – c | cons | train | t har | ndlin |
| methods – | applications to economic dispatch and unit commitment problems. | | | | |
| Unit IV | MACHINE LEARNING MODELS | | • | | 0 |
| | | | 9 | + | U |
| Generative | models: Definition and characteristics, probabilistic graphical models, density estima | tion | - | + arnir | - |
| | · · · · · · · · · · · · · · · · · · · | tion | in le | | ng |
| Unit V | MACHINE LEARNING CLASSFIERS | | in le 9 | + | ng 0 |
| Unit V Combining | MACHINE LEARNING CLASSFIERS classifiers: Advantages, boosting, hierarchical classifiers, and issues; Selected spec | | in le 9 | + | ng 0 |
| Unit V Combining | MACHINE LEARNING CLASSFIERS classifiers: Advantages, boosting, hierarchical classifiers, and issues; Selected spec d learning and case studies. | cial t | in le 9 opic: | + s suc | ng 0 :h |
| Unit V Combining as manifol | MACHINE LEARNING CLASSFIERS classifiers: Advantages, boosting, hierarchical classifiers, and issues; Selected spec d learning and case studies. Total (| cial t | in le 9 opic: | + s suc | ng 0 :h |
| Unit V Combining | MACHINE LEARNING CLASSFIERS classifiers: Advantages, boosting, hierarchical classifiers, and issues; Selected spec d learning and case studies. Total (| cial t | in le 9 opic: | + s suc | ng 0 :h |
| Unit V Combining as manifol Course Ou Upon com | MACHINE LEARNING CLASSFIERS classifiers: Advantages, boosting, hierarchical classifiers, and issues; Selected spec d learning and case studies. Total (utcomes: pletion of this course, the students will be able to | cial to 45+0 | in le 9 opic: 0)=4 | + s suc 5 Pe | ng 0 :h |
| Unit V Combining as manifold Course Ou Upon com CO1 : / | MACHINE LEARNING CLASSFIERS classifiers: Advantages, boosting, hierarchical classifiers, and issues; Selected spec d learning and case studies. Total (Itcomes: Deletion of this course, the students will be able to Ability to understand and apply basic science, circuit theory, Electro-magnetic field the | cial to 45+0 | in le 9 opic: 0)=4 | + s suc 5 Pe | ng 0 :h |
| Unit V Combining as manifol Course Ou Upon comp CO1 : / t | MACHINE LEARNING CLASSFIERS classifiers: Advantages, boosting, hierarchical classifiers, and issues; Selected spectod learning and case studies. Total (Itcomes: bletion of this course, the students will be able to Ability to understand and apply basic science, circuit theory, Electro-magnetic field theory and apply them to electrical engineering problems. | cial to 45+0 | in le 9 opic: 0)=4 | + s suc 5 Pe | ng 0 :h |
| Unit V Combining as manifold Course Ou Upon com CO1 : / t CO2 : - | MACHINE LEARNING CLASSFIERS classifiers: Advantages, boosting, hierarchical classifiers, and issues; Selected speceed learning and case studies. Total (Itcomes: Deletion of this course, the students will be able to Ability to understand and apply basic science, circuit theory, Electro-magnetic field theory and apply them to electrical engineering problems. Fo understand and apply computing platform and software for engineering problems. | cial to 45+0 | in le 9 opic: 0)=4 | + s suc 5 Pe | ng 0 :h |
| Unit V Combining as manifold Course Ou Upon com CO1 : / t CO2 : CO3 : | MACHINE LEARNING CLASSFIERS classifiers: Advantages, boosting, hierarchical classifiers, and issues; Selected speceed learning and case studies. Total (utcomes: bletion of this course, the students will be able to Ability to understand and apply basic science, circuit theory, Electro-magnetic field the heory and apply them to electrical engineering problems. To understand and apply computing platform and software for engineering problems. To understand machine learning concepts and apply for engineering problems. | cial to 45+0 | in le 9 opic: 0)=4 | + s suc 5 Pe | ng 0 :h |
| Unit V Combining as manifold Course Ou Upon com CO1 : / t CO2 : CO3 : CO3 : CO4 : S | MACHINE LEARNING CLASSFIERS classifiers: Advantages, boosting, hierarchical classifiers, and issues; Selected speceed learning and case studies. Total (utcomes: bletion of this course, the students will be able to Ability to understand and apply basic science, circuit theory, Electro-magnetic field th heory and apply them to electrical engineering problems. To understand and apply computing platform and software for engineering problems. To understand machine learning concepts and apply for engineering problems. Solve economic dispatch and unit commitment problem using genetic algorithm | cial to 45+0 | in le 9 opic: 0)=4 | + s suc 5 Pe | ng 0 :h |
| Unit V Combining as manifold Course Ou Upon com CO1 : / t CO2 : CO3 : CO3 : CO4 : S | MACHINE LEARNING CLASSFIERS classifiers: Advantages, boosting, hierarchical classifiers, and issues; Selected speceed learning and case studies. Total (utcomes: bletion of this course, the students will be able to Ability to understand and apply basic science, circuit theory, Electro-magnetic field the heory and apply them to electrical engineering problems. To understand and apply computing platform and software for engineering problems. To understand machine learning concepts and apply for engineering problems. | cial to 45+0 | in le 9 opic: 0)=4 | + s suc 5 Pe | ng 0 :h |
| Unit V Combining as manifold Course Ou Upon comp CO1 : / CO2 : CO2 : CO3 : CO4 : CO5 : I | MACHINE LEARNING CLASSFIERS classifiers: Advantages, boosting, hierarchical classifiers, and issues; Selected speceed learning and case studies. Ability to understand and apply basic science, circuit theory, Electro-magnetic field theory and apply them to electrical engineering problems. To understand and apply computing platform and software for engineering problems. To understand machine learning concepts and apply for engineering problems. Solve economic dispatch and unit commitment problem using genetic algorithm Design a fuzzy controller based home heating system | cial to 45+0 | in le 9 opic: 0)=4 | + s suc 5 Pe | ng 0 :h |
| Unit V Combining as manifold Course Ou Upon comp CO1 : / CO2 : CO2 : CO3 : CO3 : CO4 : CO5 : I | MACHINE LEARNING CLASSFIERS classifiers: Advantages, boosting, hierarchical classifiers, and issues; Selected speceed learning and case studies. Ability to understand and apply basic science, circuit theory, Electro-magnetic field the heory and apply them to electrical engineering problems. To understand and apply computing platform and software for engineering problems. To understand machine learning concepts and apply for engineering problems. Solve economic dispatch and unit commitment problem using genetic algorithm Design a fuzzy controller based home heating system s: | eory | 9 opic: 0)=4 | + 5 Pe | ng 0 :h |
| Unit V Combining as manifold Course Ou Upon com CO1 : / CO2 : CO2 : CO3 : CO4 : CO5 : I Text Book 1. Laura | MACHINE LEARNING CLASSFIERS classifiers: Advantages, boosting, hierarchical classifiers, and issues; Selected speceed learning and case studies. Ability to understand and apply basic science, circuit theory, Electro-magnetic field theory and apply them to electrical engineering problems. To understand and apply computing platform and software for engineering problems. To understand machine learning concepts and apply for engineering problems. Solve economic dispatch and unit commitment problem using genetic algorithm Design a fuzzy controller based home heating system | eory | 9 opic: 0)=4 con | + 5 Pe trol | ng 0 :h |
| Unit V Combining as manifold Course Ou Upon com CO1 : / CO2 : CO2 : CO3 : CO3 : CO4 : CO5 : I Text Book 1. Laura 2. S.N.S | MACHINE LEARNING CLASSFIERS classifiers: Advantages, boosting, hierarchical classifiers, and issues; Selected speceed d learning and case studies. Total (Total (Interview of this course, the students will be able to Ability to understand and apply basic science, circuit theory, Electro-magnetic field th heory and apply them to electrical engineering problems. Fo understand and apply computing platform and software for engineering problems. Fo understand machine learning concepts and apply for engineering problems. Solve economic dispatch and unit commitment problem using genetic algorithm Design a fuzzy controller based home heating system s: unceFausett, Englewood cliffs, N.J., 'Fundamentals of Neural Networks', Pearson Edu Site and and S.N.Deepa,' Principles of Soft computing, Wiley India Edition, 2nd | eory | 9 opic: 0)=4 con | + 5 Pe trol | ng 0 :h |
| Unit V Combining as manifold Course Ou Upon comp CO1 : / CO2 : CO2 : CO3 : CO4 : CO5 : I Text Book 1. Laura 2. S.N.S 3 Timo | MACHINE LEARNING CLASSFIERS classifiers: Advantages, boosting, hierarchical classifiers, and issues; Selected speceed learning and case studies. Ability to understand and apply basic science, circuit theory, Electro-magnetic field theory and apply them to electrical engineering problems. Fo understand and apply computing platform and software for engineering problems. Fo understand machine learning concepts and apply for engineering problems. Solve economic dispatch and unit commitment problem using genetic algorithm Design a fuzzy controller based home heating system s: unceFausett, Englewood cliffs, N.J., 'Fundamentals of Neural Networks', Pearson Edu | eory | 9 opic: 0)=4 con | + 5 Pe trol | ng 0 :h |
| Unit V Combining as manifold Course Out Upon comp CO1 : CO2 : CO3 : CO4 : CO5 : I Laura 2. S.N.S 3 Timor 4 S. Mathematical Science | MACHINE LEARNING CLASSFIERS classifiers: Advantages, boosting, hierarchical classifiers, and issues; Selected spectid learning and case studies. Total (Interview of the students will be able to Ability to understand and apply basic science, circuit theory, Electro-magnetic field th heory and apply them to electrical engineering problems. To understand and apply computing platform and software for engineering problems. Fo understand machine learning concepts and apply for engineering problems. Solve economic dispatch and unit commitment problem using genetic algorithm Design a fuzzy controller based home heating system s: nnceFausett, Englewood cliffs, N.J., 'Fundamentals of Neural Networks', Pearson Edu Bivanandam and S.N.Deepa,' Principles of Soft computing, Wiley India Edition, 2nd Edity, J. Ross, 'Fuzzy Logic with Engineering Applications', Tata McGraw Hill, 1997. arsland, 'Machine Learning: An Algorithmic Perspective', Chapman & Hall/CRC, 2009 | eory | 9 opic: 0)=4 con | + 5 Pe trol | ng 0 :h |
| Unit V Combining as manifold Course Out Upon comp CO1 : CO2 : CO3 : CO4 : CO5 : I Laura 2. S.N.S 3 Timor 4 S. Mate | MACHINE LEARNING CLASSFIERS classifiers: Advantages, boosting, hierarchical classifiers, and issues; Selected spection of the second learning and case studies. Total (Interview of the students will be able to Ability to understand and apply basic science, circuit theory, Electro-magnetic field the heory and apply them to electrical engineering problems. To understand and apply computing platform and software for engineering problems. Fo understand machine learning concepts and apply for engineering problems. Solve economic dispatch and unit commitment problem using genetic algorithm Design a fuzzy controller based home heating system s: nnceFausett, Englewood cliffs, N.J., 'Fundamentals of Neural Networks', Pearson Edu Sivanandam and S.N.Deepa,' Principles of Soft computing, Wiley India Edition, 2nd Edity J. Ross, 'Fuzzy Logic with Engineering Applications', Tata McGraw Hill, 1997. ursland, 'Machine Learning: An Algorithmic Perspective', Chapman & Hall/CRC, 2009 Books: | eory | 9 opic: 0)=4 con | + 5 Pe trol | ng 0 :h |
| Unit V Combining as manifold Course Ou Upon comp CO1 : / CO2 : CO2 : CO3 : CO4 : CO5 : I Text Book 1. Laura 2. S.N.S 3 Timot 4 S. Ma Reference 1 Simon | MACHINE LEARNING CLASSFIERS classifiers: Advantages, boosting, hierarchical classifiers, and issues; Selected spected learning and case studies. Total (Total (Interview of the students will be able to Ability to understand and apply basic science, circuit theory, Electro-magnetic field th heory and apply them to electrical engineering problems. To understand and apply computing platform and software for engineering problems. To understand machine learning concepts and apply for engineering problems. Solve economic dispatch and unit commitment problem using genetic algorithm Design a fuzzy controller based home heating system S: anceFausett, Englewood cliffs, N.J., 'Fundamentals of Neural Networks', Pearson Edu Sivanandam and S.N.Deepa,' Principles of Soft computing, Wiley India Edition, 2nd Edi Total (Colspan="2">Books: Haykin, 'Neural Networks', Pearson Education, 2009 ,3rd edition. | eory | 9 opic: 0)=4 con | + 5 Pe trol | ng 0 :h |
| Unit V Combining as manifold Course Ou Upon comp CO1 : / CO2 : CO2 : CO3 : CO4 : CO5 : I Text Book 1. Laura 2. S.N.S 3 Timor 4 S. Ma Reference 1 Simon 2 Hagan | MACHINE LEARNING CLASSFIERS classifiers: Advantages, boosting, hierarchical classifiers, and issues; Selected spected learning and case studies. Total (Interview of the students will be able to Advantages, boosting, hierarchical classifiers, and issues; Selected spected learning and case studies. Total (Interview of the students will be able to Advantages, the students will be able to Advantages, boosting, hierarchical engineering problems. Deletion of this course, the students will be able to Advantages, course, the students will be able to Advantages, provide the students will be able to Advantages, provide the students will be able to Advantages, course, the students will be able to Advantages, provide the students will provide the students and apply computing platform and software for engineering problems. Fo understand machine learning concepts and apply for engineering problems. Solve econo | eory | 9 opic: 0)=4 con | + 5 Pe trol | ng 0 :h |
| Unit V Combining as manifold Course Ou Upon comp CO1 : / CO2 : CO2 : CO3 : CO4 : CO3 : CO4 : CO5 : I Text Book 1. Laura 2. S.N.S 3 Timoi 4 S. Ma Reference 1 Simon 2 Hagar 3 N.P.Pa | MACHINE LEARNING CLASSFIERS classifiers: Advantages, boosting, hierarchical classifiers, and issues; Selected spected learning and case studies. Total (Total (Interview of the students will be able to Ability to understand and apply basic science, circuit theory, Electro-magnetic field th heory and apply them to electrical engineering problems. To understand and apply computing platform and software for engineering problems. To understand machine learning concepts and apply for engineering problems. Solve economic dispatch and unit commitment problem using genetic algorithm Design a fuzzy controller based home heating system S: anceFausett, Englewood cliffs, N.J., 'Fundamentals of Neural Networks', Pearson Edu Sivanandam and S.N.Deepa,' Principles of Soft computing, Wiley India Edition, 2nd Edi Total (Colspan="2">Books: Haykin, 'Neural Networks', Pearson Education, 2009 ,3rd edition. | eory | 9 popic: 0)=4 con | + 5 Suc 5 Pe trol 010 113 | ng 0 Ch riod |

E-References:

1 www.onlinecourses.nptel.ac.in

2 www.class-central.com

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 3 | 2 | 2 | 2 | 2 | 2 | | | | | | 2 |
| CO2 | 1 | 2 | 3 | 3 | 3 | 2 | | | | | | 2 |
| CO3 | 1 | 2 | 2 | 2 | 2 | 2 | | | | | | 2 |
| CO4 | 1 | 2 | 2 | 2 | 2 | 2 | | | | | | 2 |
| CO5 | 1 | 2 | 3 | 3 | 3 | 2 | | | | | | 2 |

| 18EEP17 | ADVANCED ELECTRIC DRIVES | L | Т | Ρ | C |
|---|--|-----------------------------|------|---------|----------|
| | | 3 | 0 | 0 | 3 |
| Course ob | jectives: | | | | |
| 1. | To know about the overview of Electrical drives. | | | | |
| 2. | To know about the Vector control strategies for AC motor drives. | | | | |
| 3. | To understand the concepts of various DSP based control. | | | | |
| | | | _ | | |
| UNIT I | POWER CONVERTERS FOR AC DRIVES | | 9 | + | 0 |
| level invert | ol of inverter, selected harmonic elimination, space vector modulation, current contro er, Different topologies, SVM for 3 level inverter, Diode rectifier with boost chopper, rectifier, current fed inverters with self-commutated devices. Control of CSI, H bridge | PWN | Л со | nver | ter |
| | INDUCTION MOTOR DRIVES | | 9 | + | 0 |
| | ansformations and reference frame theory, modeling of induction machines, volta | ge f | ed i | nver | ter |
| control-v/f | control, vector control, direct torque and flux control(DTC). | | | | |
| | SYNCHRONOUS MOTOR DRIVES | | 9 | | 0 |
| - | f synchronous machines, open loop v/f control, vector control, direct torque control, (| rei f | - | + | U |
| | us motor drives. | 100 | eu | | |
| UNIT IV | PERMANENT MAGNET MOTOR AND SWITCHED RELUCTANCE MOTOR DRIVES | | 9 | + | 0 |
| Modeling (| of synchronous machines, open loop v/f control, vector control, direct torque co | ontro | I, C | SI fe | ed |
| | us motor drives. Various topologies for SRM drives, comparison, Closed loop spe | eed | and | toro | ue |
| control of S | SRM. | | | | |
| | DSP BASED MOTION CONTROL | | 0 | | |
| - | SPs in motion control, various DSPs available, realization of some basic bloc | kc i | 9 | + 9D | 0 for |
| | ation of DSP based motion control. | | | 01 | 101 |
| | | | | | |
| | Total (45- | ⊦0) = | 45 F | Perio | ods |
| Course Ou | itcomes: | | | | |
| Upon com | pletion of this course, the students will be able to: | | | | |
| CO1 : | Explain DSP based motion control. | | | | |
| CO2 : | | | | | |
| | Understand the basics of Permanent magnet motor and Switched reluctance motor | drive | es. | | |
| CO3 : | Learn the concepts of Synchronous motor drives. | drive | es. | | |
| CO3 : CO4 : | Learn the concepts of Synchronous motor drives. Gain knowledge of Induction motor drives. | drive | es. | | |
| CO3 : | Learn the concepts of Synchronous motor drives. | drive | es. | | |
| CO3 : CO4 : CO5 : | Learn the concepts of Synchronous motor drives. Gain knowledge of Induction motor drives. Apply Power converters for AC drives. | drive | es. | | |
| CO3 : CO4 : CO5 : Text Book | Learn the concepts of Synchronous motor drives. Gain knowledge of Induction motor drives. Apply Power converters for AC drives. s: | | | | |
| CO3 : CO4 : CO5 : Text Book 1. | Learn the concepts of Synchronous motor drives. Gain knowledge of Induction motor drives. Apply Power converters for AC drives. s: B. K. Bose, "Modern Power Electronics and AC Drives", Pearson Education, Asia, 2 | 2003 | | | |
| CO3 : CO4 : CO5 : Text Book | Learn the concepts of Synchronous motor drives. Gain knowledge of Induction motor drives. Apply Power converters for AC drives. s: | 2003 | | | |
| CO3 : CO4 : CO5 : Text Book 1. | Learn the concepts of Synchronous motor drives. Gain knowledge of Induction motor drives. Apply Power converters for AC drives. s: B. K. Bose, "Modern Power Electronics and AC Drives", Pearson Education, Asia, 2 P. C. Krause, O. Wasynczuk and S. D. Sudhoff, "Analysis of Electric Machinery and Systems", John Wiley & Sons, 2013. Books: | 2003 d Dri | ve | | |
| CO3 : CO4 : CO5 : Text Book 1. 2. Reference 1. | Learn the concepts of Synchronous motor drives. Gain knowledge of Induction motor drives. Apply Power converters for AC drives. s: B. K. Bose, "Modern Power Electronics and AC Drives", Pearson Education, Asia, 2 P. C. Krause, O. Wasynczuk and S. D. Sudhoff, "Analysis of Electric Machinery and Systems", John Wiley & Sons, 2013. Books: H. A. Taliyat and S. G. Campbell, " DSP based Electromechanical Motion Control", press, 2013. | 2003. d Dri ⁻ | ve | | |
| CO3 : CO4 : CO5 : Text Book 1. 2. Reference | Learn the concepts of Synchronous motor drives. Gain knowledge of Induction motor drives. Apply Power converters for AC drives. s: B. K. Bose, "Modern Power Electronics and AC Drives", Pearson Education, Asia, 2 P. C. Krause, O. Wasynczuk and S. D. Sudhoff, "Analysis of Electric Machinery and Systems", John Wiley & Sons, 2013. Books: H. A. Taliyat and S. G. Campbell, " DSP based Electromechanical Motion Control" | 2003. d Dri ⁻ | ve | | |
| CO3 : CO4 : CO5 : Text Book 1. 2. Reference 1. | Learn the concepts of Synchronous motor drives. Gain knowledge of Induction motor drives. Apply Power converters for AC drives. s: B. K. Bose, "Modern Power Electronics and AC Drives", Pearson Education, Asia, 2 P. C. Krause, O. Wasynczuk and S. D. Sudhoff, "Analysis of Electric Machinery and Systems", John Wiley & Sons, 2013. Books: H. A. Taliyat and S. G. Campbell, " DSP based Electromechanical Motion Control", press, 2013. R. Krishnan, "Permanent Magnet Synchronous and Brushless DC motor Drives", C Press, 2010,1 st edition. | 2003. d Dri ⁻ | ve | | |

| PO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 1 | 1 | 3 | 2 | 2 | 1 | 1 | 1 | | | 1 | 1 |
| CO2 | 3 | 3 | 3 | 3 | 3 | 1 | 1 | 1 | | | 1 | 1 |
| CO3 | 1 | 3 | 3 | 3 | 3 | 1 | 1 | 1 | | | | |
| CO4 | 1 | 3 | 3 | 3 | 3 | 1 | 1 | 1 | | | | 1 |
| CO5 | 3 | 3 | 3 | 3 | 3 | 1 | 1 | 1 | | | 1 | 1 |

| | COMPUTATIONAL ELECTROMAGNETICS | 3 | 0 | Р 0 | C 3 |
|--|--|--|-----------|--------|--------------|
| Course O | ojectives: | | | | |
| 1. | To study the fundamental concepts and analytical methods. | | | | |
| 2. | To give basic knowledge on finite difference methods. | | | | |
| 3. | To understand the concept of variable methods. | | | | |
| 4. | To provide adequate knowledge on moment methods. | | | | |
| 5. | To gain knowledge on finite element method. | | | | |
| Unit I | FUNDAMENTAL CONCEPTS AND ANALYTICAL METHODS | | 9 | + | (|
| Separation | EM theory – Classification of EM problems – Superposition principle – Unique of variables in three coordinate systems – Series expansion – Practical application phere, scattering cross sections. | | | | |
| Unit II | FINITE DIFFERENCE METHODS | | 9 | + | C |
| stability of | Frence schemes – Finite differencing of Parabolic, Hyperbolic and Elliptic PDEs FD solutions – Practical applications: Transmission lines, Yee's finite difference a g for non-rectangular systems – Numerical integration: Euler's rule, Trapezoidal rule | algorit | hm | – Fi | nite |
| Unit III | VARIABLE METHODS | | 9 | + | 0 |
| method – | in linear spaces – Calculus of variations – Construction of functional from PDEs Weighted Residual method – Collocation method: Subdomain method, Galerkir iethod – Eigen value problems. | | | | |
| Unit IV | MOMENT METHODS | | 9 | + | 0 |
| | I equations – Integral equations – Green's functions – Applications: Quasi-static prol ting cylinder, Hallen's IE, Pocklington's IE, Expansion and weighting functions, EM a dy. | | | | |
| Unit V | FINITE ELEMENT METHOD | | 9 | + | 0 |
| | | | 5 | | - |
| mesh gen | f Laplace's equation – Solution of Poisson's equation – Solution of the wave equa eration: Rectangular domains, Arbitrary domains – Bandwidth reduction – Higher ensional elements – Infinite element method – Finite-element time-domain method. | order | | | ati |
| mesh gen Three-dim | eration: Rectangular domains, Arbitrary domains – Bandwidth reduction – Higher ensional elements – Infinite element method – Finite-element time-domain method. Total (4 | order | ele | men | ati :s |
| mesh gen Three-dim Course O | eration: Rectangular domains, Arbitrary domains – Bandwidth reduction – Higher ensional elements – Infinite element method – Finite-element time-domain method Total (4 utcomes: | order | ele | men | ati :s |
| mesh gen Three-dim Course O Upon com | eration: Rectangular domains, Arbitrary domains – Bandwidth reduction – Higher ensional elements – Infinite element method – Finite-element time-domain method Total (4 utcomes: pletion of this course, the students will be able to: | order | ele | men | ati :s |
| mesh gen Three-dim Course O Upon com CO1 : | eration: Rectangular domains, Arbitrary domains – Bandwidth reduction – Higher ensional elements – Infinite element method – Finite-element time-domain method. Total (4 utcomes: pletion of this course, the students will be able to: Understand the fundamental concepts of field theory and analytical methods. | order | ele | men | ati :s - |
| Mesh gen Three-dim Course O Upon com CO1 : CO2 : | eration: Rectangular domains, Arbitrary domains – Bandwidth reduction – Higher ensional elements – Infinite element method – Finite-element time-domain method. Total (4 utcomes: pletion of this course, the students will be able to: Understand the fundamental concepts of field theory and analytical methods. Understand the finite difference methods and applications. | order | ele | men | ati :s - |
| Mesh gen Three-dim Course O Upon com CO1 : CO2 : CO3 : | eration: Rectangular domains, Arbitrary domains – Bandwidth reduction – Higher ensional elements – Infinite element method – Finite-element time-domain method. Total (4 utcomes: pletion of this course, the students will be able to: Understand the fundamental concepts of field theory and analytical methods. Understand the finite difference methods and applications. Analyze the Variable methods of electromagnetics. | order | ele | men | atio :s - |
| mesh gen Three-dim Course O Upon com CO1 : CO2 : CO3 : CO4 : | eration: Rectangular domains, Arbitrary domains – Bandwidth reduction – Higher ensional elements – Infinite element method – Finite-element time-domain method. Total (4 utcomes: pletion of this course, the students will be able to: Understand the fundamental concepts of field theory and analytical methods. Understand the finite difference methods and applications. Analyze the Variable methods of electromagnetics. Analyze the concepts of Moment methods. | order | ele | men | ati :s |
| Mesh gen Three-dimCourse OUpon comCO1CO2CO3 | eration: Rectangular domains, Arbitrary domains – Bandwidth reduction – Higher ensional elements – Infinite element method – Finite-element time-domain method. Total (4 utcomes: pletion of this course, the students will be able to: Understand the fundamental concepts of field theory and analytical methods. Understand the finite difference methods and applications. Analyze the Variable methods of electromagnetics. | order | ele | men | ati :s |
| mesh gen Three-dim Course O Upon com CO1 : CO2 : CO3 : CO4 : | eration: Rectangular domains, Arbitrary domains – Bandwidth reduction – Higher ensional elements – Infinite element method – Finite-element time-domain method Total (4 utcomes: pletion of this course, the students will be able to: Understand the fundamental concepts of field theory and analytical methods. Understand the finite difference methods and applications. Analyze the Variable methods of electromagnetics. Analyze the concepts of Moment methods. Gain knowledge on the concept of finite element method. | order | ele 45 | Perio | ati s |
| Mesh gen Three-dimCourse OUpon comCO1CO2CO3CO4CO5Text Bool1. | eration: Rectangular domains, Arbitrary domains – Bandwidth reduction – Higher ensional elements – Infinite element method – Finite-element time-domain method. Total (4: utcomes: pletion of this course, the students will be able to: Understand the fundamental concepts of field theory and analytical methods. Understand the finite difference methods and applications. Analyze the Variable methods of electromagnetics. Analyze the concepts of Moment methods. Gain knowledge on the concept of finite element method. Matthew N.O. Sadiku, "Computational Electromagnetics with MATLAB", CRC Pre 2018. | order 5+0)= | ele 45 | Perio | ati s |
| mesh gen Three-dim Course O Upon com CO1 : CO2 : CO3 : CO4 : CO5 : Text Bool | eration: Rectangular domains, Arbitrary domains – Bandwidth reduction – Higher ensional elements – Infinite element method – Finite-element time-domain method. Total (4: utcomes: pletion of this course, the students will be able to: Understand the fundamental concepts of field theory and analytical methods. Understand the finite difference methods and applications. Analyze the Variable methods of electromagnetics. Analyze the concepts of Moment methods. Gain knowledge on the concept of finite element method. Matthew N.O. Sadiku, "Computational Electromagnetics with MATLAB", CRC Press | order 5+0)= | ele 45 | Perio | ati s |
| mesh gen Three-dim Course O Upon com CO1 : CO2 : CO3 : CO4 : CO5 : Text Bool 1. | eration: Rectangular domains, Arbitrary domains – Bandwidth reduction – Higher ensional elements – Infinite element method – Finite-element time-domain method Total (4) utcomes: pletion of this course, the students will be able to: Understand the fundamental concepts of field theory and analytical methods. Understand the finite difference methods and applications. Analyze the Variable methods of electromagnetics. Analyze the variable methods of electromagnetics. Analyze the concepts of Moment methods. Gain knowledge on the concept of finite element method. s: Matthew N.O. Sadiku, "Computational Electromagnetics with MATLAB", CRC Pre 2018. Matthew N.O. Sadiku, "Elements of Electromagnetics", CRC Press, 7 th Edition, 20 | order 5+0)= | ele 45 | Perio | ati s |
| mesh gen Three-dim Course O Upon com CO1 : CO2 : CO3 : CO4 : CO5 : Text Book 1. 2. | eration: Rectangular domains, Arbitrary domains – Bandwidth reduction – Higher ensional elements – Infinite element method – Finite-element time-domain method Total (4) utcomes: pletion of this course, the students will be able to: Understand the fundamental concepts of field theory and analytical methods. Understand the finite difference methods and applications. Analyze the Variable methods of electromagnetics. Analyze the variable methods of electromagnetics. Analyze the concepts of Moment methods. Gain knowledge on the concept of finite element method. s: Matthew N.O. Sadiku, "Computational Electromagnetics with MATLAB", CRC Pre 2018. Matthew N.O. Sadiku, "Elements of Electromagnetics", CRC Press, 7 th Edition, 20 | order 5 +0)= ess, 4 ¹ 21. | ele 45 | Perio | atii ss - |
| mesh gen Three-dim Course O Upon com CO1 : CO2 : CO3 : CO4 : CO5 : Text Book 1. 2. Reference | eration: Rectangular domains, Arbitrary domains – Bandwidth reduction – Higher ensional elements – Infinite element method – Finite-element time-domain method. Total (4: utcomes: oletion of this course, the students will be able to: Understand the fundamental concepts of field theory and analytical methods. Understand the finite difference methods and applications. Analyze the Variable methods of electromagnetics. Analyze the concepts of Moment methods. Gain knowledge on the concept of finite element method. S: Matthew N.O. Sadiku, "Computational Electromagnetics with MATLAB", CRC Pre 2018. Matthew N.O. Sadiku, "Elements of Electromagnetics", CRC Press, 7 th Edition, 20 Books: Thomas Rylander, Par Ingelstorm, "Computational Electromagnetics", Springer Pu | order 5 +0)= ess, 4 ¹ 21. | ele 45 | Perio | ati s |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 3 | 2 | 3 | 1 | 1 | 2 | 1 | 1 | 2 | 1 | 1 | 2 |
| CO2 | 3 | 3 | 3 | 2 | 1 | 2 | 1 | 1 | 2 | 2 | 1 | 2 |
| CO3 | 3 | 3 | 1 | 1 | 2 | 1 | 2 | 1 | 1 | 2 | 1 | 1 |
| CO4 | 3 | 3 | 2 | 1 | 1 | 1 | 2 | 2 | 1 | 2 | 2 | 2 |
| CO5 | 3 | 3 | 2 | 2 | 1 | 1 | 2 | 3 | 1 | 2 | 2 | 2 |

| 18EEP | 9 SPECIAL ELECTRICAL MACHINES | | т | D | С |
|----------|---|---------|-------|-------------|-----|
| TOLLF | | 3 | 0 | 0 | 3 |
| Course | Objectives: | | - | - | - |
| | | | | | |
| 1 2 | Learn the fundamental concepts of special electric machines Learn proper selection of special machines based on applications | | | | |
| 2 | | | | | |
| Unit I | SYNCHRONOUS RELUCTANCE MOTORS | | 9 | + | 0 |
| | ctional features – Types – Axial and radial air gap motors – Operating principle – Reluc | tance - | - Ph | asor | |
| diagram | - Characteristics – Vernier motor | | | | |
| Unit II | PERMANENT MAGNET BRUSHLESS D.C. MOTORS | | 9 | - | 0 |
| | of operation – Types – Magnetic circuit analysis – EMF and torque equations – Power of | ontrol | - | - Mo | - |
| | eristics and control. | ontrol | 0.0 | | |
| | | | | | |
| Unit III | PERMANENT MAGNET SYNCHRONOUS MOTORS | | 9 | + | 0 |
| | of operation – EMF and torque equations – Reactance – Phasor diagram – Power contunpere requirements – Torque speed characteristics - Microprocessor based control. | ollers | · Cor | vert | er |
| voit ai | | | | | |
| Unit IV | SWITCHED RELUCTANCE MOTORS | | 9 | + | 0 |
| | ctional features – Principle of operation – Torque prediction – Power controllers – Non- | inear a | inaly | sis - | - |
| Micropro | ocessor based control - Characteristics – Computer control. | | | | |
| Unit V | STEPPING MOTORS | | 9 | | 0 |
| | ctional features – Principle of operation – Variable reluctance motor – Hybrid motor – Sin | nle and | - | + ti sta | |
| | ations – Theory of torque predictions – Linear and non-linear analysis – Characteristics | | | | |
| 0 | | | | | |
| | Total (| 5+0)= | 45 I | Perio | ods |
| Course | Outcomes: | | | | |
| Upon co | mpletion of this course, the students will be able to: | | | | |
| CO1 | : Understand the principles behind the principle of operation of different special mach | ines | | | |
| CO2 | : Apply the electromagnetic concepts in development of EMF and Torque in machine | s | | | |
| CO3 | : Select the control structure in terms of hardware to control the special machines | | | | |
| CO4 | : Select appropriate control techniques for efficient control of special machines | | | | |
| CO5 | Develop strategy and methods to implement suitable application-based projects | | | | |
| 000 | | | | | |
| Text Bo | oks: | | | | |
| 1 | T.J.E. Miller, "Brushless Permanent Magnet and Reluctance Motor Drives", Clarendo | n Pres | s, 0 | xford | ١. |
| | 1989. 2 nd edition | | | | |
| 2. | P.P. Acarnley, "Stepping Motors – A Guide to Motor Theory and Practice", Peter Pere | ngrinu | s, Lo | ndor | ١, |
| | 1982. | | | | |
| 3 | R. Krishnan, "Switched reluctance motor drives", CRC Press, 2017. | | | 004 | |
| 4 | R. Krishnan, "Permanent Magnet Synchronous and Brushless DC Motor Drives", (| KC P | ess | 201 | U |
| E-Refer | ences: | | | | |
| 1 | www.onlinecourses.nptel.ac.in | | | | |
| 2 | www.class-central.com | | | | |
| 3 | www.mooc-list.com | | | | |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 1 | 1 | 1 | 1 | 1 | 0 | 1 | 1 | 0 | 1 | 1 | 1 |
| CO2 | 1 | 1 | 1 | 1 | 1 | 0 | 1 | 1 | 0 | 1 | 1 | 1 |
| CO3 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 1 | 1 | 1 |
| CO4 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 1 | 1 | 1 |
| CO5 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

| 18EEP20 | ELECTRICAL WIRING, ESTIMATION AND COSTING | - T | Ρ | С |
|---|--|--|---|--|
| | | 3 0 | 0 | 3 |
| Course Obj | | | | |
| 1. | Knowledge of I.E rules for different types of electrical installations. | | | |
| 2. | Planning and preparation of different installation projects | | | |
| 3. | Knowledge on the costing and estimates of different installations. | | | |
| 4. | Knowledge on repairs and maintenance of electrical equipment. | | | |
| Unit I | ELECTRICAL WIRING AND INDIAN ELECTRICITY RULES | 9 | + | 0 |
| | ymbols, need of electrical symbols, examples of wiring and schematic diagram, E | | | |
| | in handling the tools, wiring system, sizes of wires, stranded wires, types of wires, wir | | | |
| | , difference between neutral and earth wire, domestic and industrial panel wiring. | | | ols. |
| Indian Elect | tricity rules for wiring, Installation of earth electrode as per I.E rule. Indian Electricity Ac | 1-200 | ა. | |
| Unit II | ESTIMATION AND COSTING OF DOMESTIC AND INDUSTRIAL WIRING | 9 | + | 0 |
| General pri | inciples of estimation - Electrical Schedule of rates, catalogues, Survey and sou | rce s | electi | ion, |
| | estimates Quantity and cost of material required. Purchase system, Purchase enquiry | | | |
| | ate purchase mode, Comparative statement, Purchase orders, Payment of bills. | | | |
| | Industrial wiring : layout, load calculation, cable selection, earthing, selection of switc | hgea | r, ove | erall |
| estimating a | and costing. | | | |
| Unit III | ESTIMATION OF OVERHEAD TRANSMISSION LINES | 9 | . | 0 |
| | | - | + | - |
| | onents of overhead lines, Line supports, Factors governing height of pole, Conductor r r for overhead transmission line, cross arms, pole brackets and clamps, guys and stay | | | |
| | | 3,00 | | ເບເວ |
| contiduratio | n spacing and clearances span lengths overhead line insulators insulator mate | riale | liahtn | |
| | n spacing and clearances, span lengths, overhead line insulators, insulator mate | | | ning |
| arrestors, e | rection of supports, setting of stays, earthing of lines, Guarding of overhead lines, | Clear | | ning |
| arrestors, e | | Clear | | ning |
| arrestors, e conductor fr Unit IV | erection of supports, setting of stays, earthing of lines, Guarding of overhead lines, erection of supports, setting of stays, earthing of lines, erection ground, Spacing between conductors, I.E rules pertaining to LV transmission line | Clear | | ning |
| arrestors, e conductor fr Unit IV | erection of supports, setting of stays, earthing of lines, Guarding of overhead lines, erection of supports, setting of stays, earthing of lines, grown ground, Spacing between conductors, I.E rules pertaining to LV transmission line ESTIMATION OF OVERHEAD AND UNDERGROUND DISTRIBUTIONSYSTEM AND SUBSTATION INSTALLATIONS | Clear s. 9 | ance: | ning s of |
| arrestors, e conductor fr Unit IV | erection of supports, setting of stays, earthing of lines, Guarding of overhead lines, or rom ground, Spacing between conductors, I.E rules pertaining to LV transmission line ESTIMATION OF OVERHEAD AND UNDERGROUND DISTRIBUTIONSYSTEM AND SUBSTATION INSTALLATIONS listribution system and underground distribution system : materials and accessories re | Clear s. 9 equire | ances + ed for | ning s of 0 the |
| arrestors, e conductor fr Unit IV | erection of supports, setting of stays, earthing of lines, Guarding of overhead lines, rom ground, Spacing between conductors, I.E rules pertaining to LV transmission line ESTIMATION OF OVERHEAD AND UNDERGROUND DISTRIBUTIONSYSTEM AND SUBSTATION INSTALLATIONS listribution system and underground distribution system : materials and accessories re istribution system, estimate for 440V/3-phase/ 4 wires or 3 wires overhead distribution | Clear s. 9 equire syste | + d for m, ty | the pes |
| arrestors, e conductor fr Unit IV I Overhead d overhead di of service co | erection of supports, setting of stays, earthing of lines, Guarding of overhead lines, or rom ground, Spacing between conductors, I.E rules pertaining to LV transmission line ESTIMATION OF OVERHEAD AND UNDERGROUND DISTRIBUTIONSYSTEM AND SUBSTATION INSTALLATIONS listribution system and underground distribution system : materials and accessories re | Clear s. 9 equire syste | + d for m, ty | the pes |
| Arrestors, e conductor fr Unit IV I Overhead d overhead di of service co to overhead Classificatio | ESTIMATION OF OVERHEAD AND UNDERGROUND DISTRIBUTIONSYSTEM AND SUBSTATION INSTALLATIONS distribution system and underground distribution system : materials and accessories re- istribution system, estimate for 440V/3-phase/ 4 wires or 3 wires overhead distribution onnections, method of installation of service connection(1-phase and 3-phase), I.E. ru d lines and service connection. on of substation, selection and location of site for substation, main electrical connection | Clear s. 9 equire syste iles p ons, g | + ed for m, ty ertair graph | the pes ical |
| Arrestors, e conductor fr Unit IV I Overhead di of service co to overhead Classificatio symbols for | ESTIMATION OF OVERHEAD AND UNDERGROUND DISTRIBUTIONSYSTEM AND SUBSTATION INSTALLATIONS Instribution system and underground distribution system : materials and accessories re- istribution system, estimate for 440V/3-phase/ 4 wires or 3 wires overhead distribution onnections, method of installation of service connection(1-phase and 3-phase), I.E. ru d lines and service connection. on of substation, selection and location of site for substation, main electrical connection r various types of apparatus and circuit elements on substation, main connection | Clear s. 9 equire syste iles p ons, q diagr | ed for m, ty ertair graph am, k | the peshing |
| Arrestors, e conductor fr Unit IV I Overhead di of service co to overhead Classificatio symbols for | ESTIMATION OF OVERHEAD AND UNDERGROUND DISTRIBUTIONSYSTEM AND SUBSTATION INSTALLATIONS distribution system and underground distribution system : materials and accessories re- istribution system, estimate for 440V/3-phase/ 4 wires or 3 wires overhead distribution onnections, method of installation of service connection(1-phase and 3-phase), I.E. ru d lines and service connection. on of substation, selection and location of site for substation, main electrical connection | Clear s. 9 equire syste iles p ons, q diagr | ed for m, ty ertair graph am, k | the pes ical key |
| Arrestors, e conductor fr Unit IV | ESTIMATION OF OVERHEAD AND UNDERGROUND DISTRIBUTIONSYSTEM AND SUBSTATION INSTALLATIONS Instribution system and underground distribution system : materials and accessories re- istribution system, estimate for 440V/3-phase/ 4 wires or 3 wires overhead distribution onnections, method of installation of service connection(1-phase and 3-phase), I.E. ru d lines and service connection. on of substation, selection and location of site for substation, main electrical connection r various types of apparatus and circuit elements on substation, main connection | Clear s. 9 equire syste iles p ons, q diagr | ed for m, ty ertair graph am, k | the pes ical key |
| arrestors, e conductor fr Unit IV I Overhead di of service co to overhead Classificatio symbols for diagram of supply, subs | erection of supports, setting of stays, earthing of lines, Guarding of overhead lines, from ground, Spacing between conductors, I.E rules pertaining to LV transmission line ESTIMATION OF OVERHEAD AND UNDERGROUND DISTRIBUTIONSYSTEM AND SUBSTATION INSTALLATIONS listribution system and underground distribution system : materials and accessories re- istribution system, estimate for 440V/3-phase/ 4 wires or 3 wires overhead distribution onnections, method of installation of service connection(1-phase and 3-phase), I.E. ru d lines and service connection. on of substation, selection and location of site for substation, main electrical connection r various types of apparatus and circuit elements on substation, main connection typical sub stations, equipment for substation and switchgear installations, substation station earthing. | Clear s. 9 equire syste iles p ons, q diagr | ed for m, ty ertair graph am, k | the pes ical key |
| Arrestors, e conductor fr Unit IV Overhead d overhead di of service co to overhead Classification symbols for diagram of | ESTIMATION OF OVERHEAD AND UNDERGROUND DISTRIBUTIONSYSTEM AND SUBSTATION INSTALLATIONS distribution system and underground distribution system : materials and accessories re- istribution system, estimate for 440V/3-phase/ 4 wires or 3 wires overhead distribution onnections, method of installation of service connection(1-phase and 3-phase), I.E. ru d lines and service connection. on of substation, selection and location of site for substation, main electrical connection r various types of apparatus and circuit elements on substation, main connection typical sub stations, equipment for substation and switchgear installations, substati station earthing. | Clear s. 9 equire syste iles p ons, q diagr | ed for m, ty ertair graph am, k | the pes ical key |
| Arrestors, e conductor fr Unit IV Overhead d overhead di of service co to overhead Classification symbols for diagram of supply, subs Unit V | ESTIMATION OF OVERHEAD AND UNDERGROUND DISTRIBUTIONSYSTEM AND SUBSTATION INSTALLATIONS distribution system and underground distribution system : materials and accessories re- istribution system, estimate for 440V/3-phase/ 4 wires or 3 wires overhead distribution onnections, method of installation of service connection(1-phase and 3-phase), I.E. ru d lines and service connection. on of substation, selection and location of site for substation, main electrical connection typical sub stations, equipment for substation and switchgear installations, substati station earthing. | Clear s. 9 equire syste iles p ons, ç diagr on a | ed for m, ty ertair graph am, H uxiliar | ing s of 0 the pes ning ical key ries 0 |
| Arrestors, e conductor fr Unit IV I Overhead d overhead di of service ca to overhead Classificatio symbols for diagram of supply, subs Unit V D.O.L. starte | ESTIMATION OF OVERHEAD AND UNDERGROUND DISTRIBUTIONSYSTEM AND SUBSTATION INSTALLATIONS distribution system and underground distribution system : materials and accessories re- istribution system, estimate for 440V/3-phase/ 4 wires or 3 wires overhead distribution onnections, method of installation of service connection(1-phase and 3-phase), I.E. ru d lines and service connection. on of substation, selection and location of site for substation, main electrical connection typical sub stations, equipment for substation and switchgear installations, substati station earthing. | Clear s. 9 equire syste lles p ons, q diagr on a 9 on of | ances d for m, ty ertair yraph am, H uxiliar + deta | ing s of 0 the pes ning ical key ries 0 |
| arrestors, e conductor fr Unit IV I Overhead di of service co to overhead Classificatio symbols for diagram of supply, subs Unit V D.O.L. started drawing wor | ESTIMATION OF OVERHEAD AND UNDERGROUND DISTRIBUTIONSYSTEM AND SUBSTATION INSTALLATIONS distribution system and underground distribution system : materials and accessories re- istribution system, estimate for 440V/3-phase/ 4 wires or 3 wires overhead distribution onnections, method of installation of service connection(1-phase and 3-phase), I.E. ru d lines and service connection. on of substation, selection and location of site for substation, main electrical connection typical sub stations, equipment for substation and switchgear installations, substati station earthing. | Clear s. 9 equire syste iles p ons, (diagr on a 9 on of cost | ances d for m, ty ertair graph am, H uxiliar deta requi | ing s of the pes ning ical key ries 0 iled ired |
| arrestors, e conductor fr Unit IV I Overhead di of service co to overhead Classificatio symbols for diagram of supply, subs Unit V D.O.L. starte drawing wor for maintena | ESTIMATION OF OVERHEAD AND UNDERGROUND DISTRIBUTIONSYSTEM AND SUBSTATION INSTALLATIONS Itstribution system and underground distribution system : materials and accessories re- istribution system, estimate for 440V/3-phase/ 4 wires or 3 wires overhead distribution onnections, method of installation of service connection(1-phase and 3-phase), I.E. ru d lines and service connection. on of substation, selection and location of site for substation, main electrical connection typical sub stations, equipment for substation and switchgear installations, substati station earthing. | Clear s. 9 equire syste iles p ons, (diagr on a 9 on of cost | ances d for m, ty ertair graph am, H uxiliar deta requi | the peshing ical ical ical ired |
| arrestors, e conductor fr Unit IV I Overhead di of service co to overhead Classificatio symbols for diagram of supply, subs Unit V D.O.L. starte drawing wor for maintena Preparation | ESTIMATION OF OVERHEAD AND UNDERGROUND DISTRIBUTIONSYSTEM AND SUBSTATION INSTALLATIONS distribution system and underground distribution system : materials and accessories re- istribution system, estimate for 440V/3-phase/ 4 wires or 3 wires overhead distribution onnections, method of installation of service connection(1-phase and 3-phase), I.E. ru d lines and service connection. on of substation, selection and location of site for substation, main electrical connection typical sub stations, equipment for substation and switchgear installations, substati station earthing. | Clear s. 9 equire syste iles p ons, (diagr on a 9 on of cost | ances d for m, ty ertair graph am, H uxiliar deta requi | the pession of the pe |
| arrestors, e conductor fr Unit IV I Overhead di of service co to overhead Classificatio symbols for diagram of supply, subs Unit V D.O.L. starte drawing wor for maintena Preparation | ESTIMATION OF OVERHEAD AND UNDERGROUND DISTRIBUTIONSYSTEM AND SUBSTATION INSTALLATIONS Histribution system and underground distribution system : materials and accessories re- istribution system, estimate for 440V/3-phase/ 4 wires or 3 wires overhead distribution onnections, method of installation of service connection(1-phase and 3-phase), I.E. ru d lines and service connection. In of substation, selection and location of site for substation, main electrical connection typical sub stations, equipment for substation and switchgear installations, substation typical sub stations, equipment for substation and switchgear installations, substation earthing. ESTIMATING AND COSTING OF REPAIRS AND MAINTENANCE OF <u>ELECTRICAL DEVICES AND EQUIPMENT</u> er, small motor, automatic electric iron, table/ceiling fan, ICDP/ICTP Switch, preparation ance work, estimation of repairing cost and overall cost, tools used for repairs &main of cost schedule for repair and maintenance of automatic electric iron, single phase transformer, mixer grinder, D.O.L. Starter. | Clear s. 9 equire syste iles p ons, g diagr on a on of cost tenar | ances d for m, ty ertair graph am, k uxiliar deta requi | ing s of 0 the pes ning ical cey ries 0 illed ired rork |
| arrestors, e conductor fr Unit IV Overhead d overhead di of service co to overhead Classification symbols for diagram of supply, subs Unit V D.O.L. starte drawing wor for maintena Preparation electric fan, | rection of supports, setting of stays, earthing of lines, Guarding of overhead lines, from ground, Spacing between conductors, I.E rules pertaining to LV transmission line ESTIMATION OF OVERHEAD AND UNDERGROUND DISTRIBUTIONSYSTEM AND SUBSTATION INSTALLATIONS listribution system and underground distribution system : materials and accessories re- istribution system, estimate for 440V/3-phase/ 4 wires or 3 wires overhead distribution onnections, method of installation of service connection(1-phase and 3-phase), I.E. rule lines and service connection. on of substation, selection and location of site for substation, main electrical connection typical sub stations, equipment for substation and switchgear installations, substatistation earthing. ESTIMATING AND COSTING OF REPAIRS AND MAINTENANCE OF ELECTRICAL DEVICES AND EQUIPMENT er, small motor, automatic electric iron, table/ceiling fan, ICDP/ICTP Switch, preparation ance work, estimation of repairing cost and overall cost, tools used for repairs &main of cost schedule for repair and maintenance of automatic electric iron, single phase transformer, mixer grinder, D.O.L. Starter. Total (45+0 | Clear s. 9 equire syste iles p ons, g diagr on a on of cost tenar | ances d for m, ty ertair graph am, k uxiliar deta requi | ing s of the pes ning ical cey ries 0 illed ired rork |
| arrestors, e conductor fr Unit IV I Overhead di of service co to overhead Classificatio symbols for diagram of supply, subs Unit V D.O.L. starte drawing wor for maintena Preparation | rection of supports, setting of stays, earthing of lines, Guarding of overhead lines, from ground, Spacing between conductors, I.E rules pertaining to LV transmission line ESTIMATION OF OVERHEAD AND UNDERGROUND DISTRIBUTIONSYSTEM AND SUBSTATION INSTALLATIONS listribution system and underground distribution system : materials and accessories re- istribution system, estimate for 440V/3-phase/ 4 wires or 3 wires overhead distribution onnections, method of installation of service connection(1-phase and 3-phase), I.E. rule lines and service connection. on of substation, selection and location of site for substation, main electrical connection typical sub stations, equipment for substation and switchgear installations, substatistation earthing. ESTIMATING AND COSTING OF REPAIRS AND MAINTENANCE OF ELECTRICAL DEVICES AND EQUIPMENT er, small motor, automatic electric iron, table/ceiling fan, ICDP/ICTP Switch, preparation ance work, estimation of repairing cost and overall cost, tools used for repairs &main of cost schedule for repair and maintenance of automatic electric iron, single phase transformer, mixer grinder, D.O.L. Starter. Total (45+0 | Clear s. 9 equire syste iles p ons, g diagr on a on of cost tenar | ances d for m, ty ertair graph am, k uxiliar deta requi | ing s of the pes ning ical cey ries 0 illed ired rork |
| arrestors, e conductor fr Unit IV Overhead d overhead di of service co to overhead Classification symbols for diagram of supply, subs Unit V D.O.L. starte drawing wor for maintena Preparation electric fan, | rection of supports, setting of stays, earthing of lines, Guarding of overhead lines, from ground, Spacing between conductors, I.E rules pertaining to LV transmission line ESTIMATION OF OVERHEAD AND UNDERGROUND DISTRIBUTIONSYSTEM AND SUBSTATION INSTALLATIONS listribution system and underground distribution system : materials and accessories re- istribution system, estimate for 440V/3-phase/ 4 wires or 3 wires overhead distribution onnections, method of installation of service connection(1-phase and 3-phase), I.E. rule lines and service connection. on of substation, selection and location of site for substation, main electrical connection typical sub stations, equipment for substation and switchgear installations, substatistation earthing. ESTIMATING AND COSTING OF REPAIRS AND MAINTENANCE OF ELECTRICAL DEVICES AND EQUIPMENT er, small motor, automatic electric iron, table/ceiling fan, ICDP/ICTP Switch, preparation ance work, estimation of repairing cost and overall cost, tools used for repairs &main of cost schedule for repair and maintenance of automatic electric iron, single phase transformer, mixer grinder, D.O.L. Starter. Total (45+0 | Clear s. 9 equire syste iles p ons, g diagr on a on of cost tenar | ances d for m, ty ertair graph am, k uxiliar deta requi | ing s of the pes ning ical cey ries 0 illed ired rork |
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| Arrestors, e conductor fr Unit IV Overhead di of service co to overhead Classification symbols for diagram of supply, subs Unit V D.O.L. starte drawing wor for maintena Preparation electric fan, Upon completion | rection of supports, setting of stays, earthing of lines, Guarding of overhead lines, i rom ground, Spacing between conductors, I.E rules pertaining to LV transmission line ESTIMATION OF OVERHEAD AND UNDERGROUND DISTRIBUTIONSYSTEM AND SUBSTATION INSTALLATIONS listribution system and underground distribution system : materials and accessories re- istribution system, estimate for 440V/3-phase/ 4 wires or 3 wires overhead distribution onnections, method of installation of service connection(1-phase and 3-phase), I.E. ru d lines and service connection. on of substation, selection and location of site for substation, main electrical connection typical sub stations, equipment for substation and switchgear installations, substati station earthing. | Clear s. 9 equire syste iles p ons, g diagr on a on of cost tenar | ances d for m, ty ertair graph am, k uxiliar deta requi | ing s of 0 the pes ning ical cey ries 0 illed ired rork |

| CO4 | : | To prepare detail estimate and costing of overhead transmission line, overhead and underground | | | | |
|--|---|--|--|--|--|--|
| | | distribution projects following IE rules. | | | | |
| CO5 | : | To comprehend the estimation of substations. | | | | |
| CO6 | : | To prepare estimates for repairs and maintenance of electrical devices and equipment | | | | |
| Text B | ooks | r. | | | | |
| 4 | | Raina K. B. and Bhattacharya S.K. " Electrical Design, estimating & Costing", New Age | | | | |
| ^{1.} International (p) Limited, New Delhi,2017 2 nd edition. | | | | | | |
| 2. | | Gupta J.B., "Electrical Installation Estimating & Costing", S. K. Kataria& Sons, New Delhi,2015. | | | | |
| 3. | | Uppal S.L. "Electrical Estimating & Costing", New Age International (p) Limited, New Delhi ,2018 | | | | |
| Refere | nce | Books: | | | | |
| 1. | | SurjithSingh, "Electrical Estimating and Costing", Danpat Rai &Co2016. | | | | |
| | | CEA Regulations 2019 | | | | |
| 2. | 3. I.E rules for wiring and supply act manuals. | | | | | |
| | | I.E rules for wiring and supply act manuals. | | | | |
| | erenc | | | | | |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 2 | 1 | 1 | 3 | 1 | 1 | 1 | | | | | 1 |
| CO2 | 3 | 2 | 2 | 2 | 1 | 1 | 1 | | | 1 | | |
| CO3 | 3 | 1 | 1 | 1 | 2 | 2 | 1 | 1 | | | | 1 |
| CO4 | 3 | 3 | 2 | 2 | 2 | 3 | 1 | 1 | 1 | 1 | 1 | |
| CO5 | 3 | 3 | 2 | 2 | 2 | 1 | 1 | | | | | |
| CO6 | 2 | 2 | 3 | 2 | 1 | 3 | 2 | 1 | 1 | 1 | 1 | |

| 18EEF | P 21 | TOTAL QUALITY MANAGEMENT | | T | Ρ | С |
|---------------------------|----------------------|---|----------|------------|----------------|----------|
| | | 3 | | 0 | 0 | 3 |
| ~ | _ | | | | | |
| | | Objectives: | | | | |
| 1. | | To understand the statistical approach for quality control. | | | | |
| 2. | | To Learn about the TQM principle. | | | | |
| 3. | | To introduce the concept of statistical process control | | | | |
| 4. | | To provide awareness on TQM standards | | | | |
| 5. | | To create an awareness about the ISO and QS certification process and its need for the | ie i | ndu | Istrie | s |
| Unit I | | INTRODUCTION | | 9 | + | 0 |
| Definit Costs Conce | tion , Ba epts | of Quality, Dimensions of Quality, Quality Planning, Quality costs - Analysis Techniques asic concepts of Total Quality Management, Historical Review, Principles of TQM, L , Role of Senior Management, Quality Council, Quality Statements, Strategic Planni ny, Barriers to TQM Implementation. | fo ea | r Q der | uality ship | y |
| Unit II | 1 | TQM PRINCIPLES | Т | • | . | _ |
| | | r satisfaction – Customer Perception of Quality, Customer Complaints, Service Quali | | 9 | + | 0 00r |
| Appra Partne | isal ersh | a, Employee Involvement – Motivation, Empowerment, Teams, Recognition and Reward, , Benefits, Continuous Process Improvement – Juran Trilogy, PDSA Cycle, 5S, Kaiz and Partnering, sourcing, Supplier Selection, Supplier Rating, Relationship Ince Measures – Basic Concepts, Strategy, Performance Measure. | zen | i, S | uppl | ier |
| Unit II | 1 | STATISTICAL PROCESS CONTROL (SPC) | Т | 9 | + | 0 |
| and Sa | amp | n tools of quality, Statistical Fundamentals – Measures of central Tendency and Dispersion ole, Normal Curve, Control Charts for variables and attributes, Process capability, Concepten Management tools. | | | | |
| Unit I | v | TQM TOOLS | Т | 9 | + | 0 |
| House | e of | arking – Reasons to Benchmark, Benchmarking Process, Quality Function Deploym Quality, QFD Process, Benefits, Taguchi Quality Loss Function, Total Productive Mainte t, Improvement Needs, FMEA – Stages of FMEA. | | | | |
| Unit V | / | QUALITY SYSTEMS | Т | 9 | + | 0 |
| Need | for | ISO 9000 and Other Quality Systems, ISO 9000:2000 Quality System – Elements, Imple ystem, Documentation, Quality Auditing, QS 9000, ISO 14000 – Concept, Requirements a | me | enta | tion | of |
| | | Total (45+0) |)= 4 | 45 F | Peric | ds |
| Cours | se O | Outcomes: | | | | |
| Upon | com | npletion of this course, the students will be able to: | | | | |
| CO1 | : | Understand the importance of quality, leadership and motivation in TQM | | | | |
| CO2 | : | Understand the problem of customers and continuous process improvement in supplier selection and rating | ра | artn | ersh | ip, |
| CO3 | : | Recall the seven traditional tools, management tools and sigma concepts in TQM | | | | |
| CO4 | : | Identify the TQM tools and know the performance measures, quality control in TQM | | | | |
| CO4 | : | Understand the need for various quality control systems and quality auditing | | | | |
| CO5 | : | Perform the case study on ISO 9000 and 14000. | | | | |
| | | | | | | |
| Text E | 300 | | | | | |
| 1. | | Dale H.Besterfiled, et al., "Total Quality Management", Pearson Education, Inc. 2018 I 0260-6.2018 | SB | 8N 8 | 1-29 | 97- |
| | | 0260-6.2018 | | | | - |

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| | Western (Thomson Learning), 2002 (ISBN 0-324-06680-5). |
| 2. | Feigenbaum.A.V. "Total Quality Management, McGraw Hill, 2004. |
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| | International 1996. |
| 5. | Zeiri. "Total Quality Management for Engineers", Wood Head Publishers, 1991. |
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| 1 | http://textofvideo.nptel.ac.in/video.php?courseId=110104080 |
| 2 | https://nptel.ac.in/courses/110104085/ |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 1 | | 2 | | | 2 | | 3 | 3 | 3 | 3 | 2 |
| CO2 | 1 | | 2 | | | 2 | | 3 | 3 | 3 | 3 | 2 |
| CO3 | 1 | | 1 | | | 1 | | 1 | 1 | 1 | 1 | 1 |
| CO4 | 1 | | 2 | | | 2 | | 2 | 2 | 2 | 2 | 2 |
| CO5 | 1 | | 2 | | | 2 | | 3 | 3 | 3 | 3 | 2 |
| CO6 | 1 | | 1 | | | 1 | | 1 | 1 | 1 | 1 | 1 |

| | RESTRUCTURED POWER SYSTEM | | | Ρ | С |
|--|---|---|---|---|--|
| | | 3 | 0 | 0 | 3 |
| Course Ob | ojectives: | | | | |
| 1 | Know about the implementation of power Systems based on applications | | | | |
| 2 | Learn various safety equipment and their installations | | | | |
| 3 | Get a clear awareness about automation in power Systems | | | | |
| | | | | | |
| Unit I | POWER SYSTEM RESTRUCTURING | | 9 | + | 0 |
| Participant | n –Deregulation - Need for deregulation – Power system restructure models - E s – GENCOS- DISCOS- TO- ISO- PX- SC - trading arrangements - Operational PI ectricity Market Participants - Causes of restructuring- types and effects of restructur | anning | j Ac | tiviti | es |
| Unit II | ELECTRICAL UTILITY | | 9 | + | 0 |
| (PoolCo- b environme - wholesale | tility restructuring Power System Operation in competitive environment –Electricity ilateral- hybrid)- Components of restructured system - Power Sector restructuring a ot - Functions and responsibilities of PX- ISO- RTO and ITP - Electric Utility Market – e electricity market characteristic – Electricity Market types (energy- ancillary service al time) – Market power evaluation and mitigation | and inf Mark | ⁱ luer et M | nce lode | on Is |
| Unit III | EVALUATION OF TRANSMISSION SYSTEM | | 9 | . 1 | 0 |
| Unit IV | mplementation- Curtailment and cancellation of transaction - Availability Based Tari | | | | |
| Introductio Market Pa allocation- | OPTIMUM POWER FLOW (OPF) ANALYSIS IN MARKET ENVIRONMENT n – Approaches to OPF – Application of OPF analysis in Electricity and Power Marker rticipants – Power Flow Tracing – current decomposition axioms- Mathematica usage sharing problem on transmission facilities - Methodology of graph theory - Eco n and transmission issues in the new market environment. | ts with I mod | lel c | of Ic | ss |
| Introductio Market Pa allocation- Mechanisn | n – Approaches to OPF – Application of OPF analysis in Electricity and Power Marker rticipants – Power Flow Tracing – current decomposition axioms- Mathematica usage sharing problem on transmission facilities - Methodology of graph theory - Ec and transmission issues in the new market environment. | ts with I mod conom | Ele lel c ic is | ctric of Ic | sity ss s- |
| Introductio Market Pa allocation- Mechanism Unit V Introductio State Spac Frequency | n – Approaches to OPF – Application of OPF analysis in Electricity and Power Marker rticipants – Power Flow Tracing – current decomposition axioms- Mathematica usage sharing problem on transmission facilities - Methodology of graph theory - Ec | ts with I mod conom ck dia onmei | Eler lel c ic is 9 agran | ctric of Ic sue + m a | sity ss s- 0 nc |
| Introductio Market Pa allocation- Mechanism Unit V Introductio State Spac Frequency | Approaches to OPF – Application of OPF analysis in Electricity and Power Marker rticipants – Power Flow Tracing – current decomposition axioms- Mathematica usage sharing problem on transmission facilities - Methodology of graph theory - Econ and transmission issues in the new market environment. AGC IN RESTRUCTURED POWER SYSTEM Traditional Vs Restructured Scenario –AGC in New market environment - Bloc e representation of a two-area interconnected power system in deregulated envir Control (LFC) dynamics and Bilateral Contacts – Modelling- DISCO Participation Participation Matrix (GPM). | ts with I mod conom ock dia onmer n Matr | Eler lel c ic is 9 agrai nt – rix (l | ctric sue + Ma Loa | sity ss s- 0 nc ad- <i>(I</i>) |
| Introductio Market Pa allocation- Mechanisn Unit V Introductio State Spac Frequency Generatior | n – Approaches to OPF – Application of OPF analysis in Electricity and Power Marker rticipants – Power Flow Tracing – current decomposition axioms- Mathematica usage sharing problem on transmission facilities - Methodology of graph theory - Ec and transmission issues in the new market environment. AGC IN RESTRUCTURED POWER SYSTEM n – Traditional Vs Restructured Scenario –AGC in New market environment - Blo re representation of a two-area interconnected power system in deregulated envir Control (LFC) dynamics and Bilateral Contacts – Modelling- DISCO Participation Participation Matrix (GPM). Total (45 | ts with I mod conom ock dia onmer n Matr | Eler lel c ic is 9 agrai nt – rix (l | ctric sue + Ma Loa | sity s- 0 nd ad |
| Introductio Market Pa allocation- Mechanisn Unit V Introductio State Spac Frequency Generatior Course Ou | n – Approaches to OPF – Application of OPF analysis in Electricity and Power Marker rticipants – Power Flow Tracing – current decomposition axioms- Mathematica usage sharing problem on transmission facilities - Methodology of graph theory - Ec and transmission issues in the new market environment. AGC IN RESTRUCTURED POWER SYSTEM n – Traditional Vs Restructured Scenario –AGC in New market environment - Blo re representation of a two-area interconnected power system in deregulated envir Control (LFC) dynamics and Bilateral Contacts – Modelling- DISCO Participation Participation Matrix (GPM). Total (45 | ts with I mod conom ock dia onmer n Matr | Eler lel c ic is 9 agrai nt – rix (l | ctric sue + Ma Loa | sity s- 0 nd ad |
| Introductio Market Pa allocation- Mechanism Unit V Introductio State Spac Frequency Generation Course Ou Upon comp | n – Approaches to OPF – Application of OPF analysis in Electricity and Power Marker rticipants – Power Flow Tracing – current decomposition axioms- Mathematica usage sharing problem on transmission facilities - Methodology of graph theory - Ec and transmission issues in the new market environment. AGC IN RESTRUCTURED POWER SYSTEM n – Traditional Vs Restructured Scenario –AGC in New market environment - Blo ce representation of a two-area interconnected power system in deregulated envir Control (LFC) dynamics and Bilateral Contacts – Modelling- DISCO Participation Participation Matrix (GPM). Total (45- ntcomes: Deletion of this course, the students will be able to: | ts with I mod conom ock dia onmer n Matr | Eler lel c ic is 9 agrai nt – rix (l | ctric sue + Ma Loa | sity s- 0 no ad |
| Introductio Market Pa allocation- Mechanism Unit V Introductio State Spac Frequency Generatior Course Ou Upon comp CO1 : | n – Approaches to OPF – Application of OPF analysis in Electricity and Power Marker rticipants – Power Flow Tracing – current decomposition axioms- Mathematical usage sharing problem on transmission facilities - Methodology of graph theory - Eco and transmission issues in the new market environment. AGC IN RESTRUCTURED POWER SYSTEM n – Traditional Vs Restructured Scenario –AGC in New market environment - Blo the representation of a two-area interconnected power system in deregulated envir Control (LFC) dynamics and Bilateral Contacts – Modelling- DISCO Participation Participation Matrix (GPM). Total (45 the top of this course, the students will be able to: Select appropriate electrical utility based on applications | ts with I mod conom ock dia onmer n Matr | Eler lel c ic is 9 agrai nt – rix (l | ctric sue + Ma Loa | sity s- 0 nd ad |
| Introductio Market Pa allocation- Mechanism Unit V Introductio State Spac Frequency Generatior Course Ou Upon comp CO1 : CO2 : | n – Approaches to OPF – Application of OPF analysis in Electricity and Power Marker rticipants – Power Flow Tracing – current decomposition axioms- Mathematical usage sharing problem on transmission facilities - Methodology of graph theory - Econ and transmission issues in the new market environment. AGC IN RESTRUCTURED POWER SYSTEM n – Traditional Vs Restructured Scenario –AGC in New market environment - Bloc the representation of a two-area interconnected power system in deregulated envir Control (LFC) dynamics and Bilateral Contacts – Modelling- DISCO Participation Participation Matrix (GPM). Total (45 Intercomes: Deletion of this course, the students will be able to: Select appropriate electrical utility based on applications Design power system according to requirements | ts with I mod conom ock dia onmer n Matr | Eler lel c ic is 9 agrai nt – rix (l | ctric sue + Ma Loa | sity s- 0 nd ad |
| Introductio Market Pa allocation- Mechanism Unit V Introductio State Space Frequency Generation Course Ou Upon comp CO1 : CO2 : CO3 : | n – Approaches to OPF – Application of OPF analysis in Electricity and Power Marker rticipants – Power Flow Tracing – current decomposition axioms- Mathematical usage sharing problem on transmission facilities - Methodology of graph theory - Econ and transmission issues in the new market environment. AGC IN RESTRUCTURED POWER SYSTEM n – Traditional Vs Restructured Scenario –AGC in New market environment - Bloc the representation of a two-area interconnected power system in deregulated envir Control (LFC) dynamics and Bilateral Contacts – Modelling- DISCO Participation Participation Matrix (GPM). Total (45) Intercomes: Deletion of this course, the students will be able to: Select appropriate electrical utility based on applications Design power system according to requirements Design an electrical market model | ts with I mod conom ock dia onmer n Matr | Eler lel c ic is 9 agrai nt – rix (l | ctric sue + Ma Loa | sity s- 0 no ad |
| Introductio Market Pa allocation- Mechanism Unit V Introductio State Space Frequency Generation Course Ou Upon comp CO1 : CO2 : CO3 : CO3 : | n – Approaches to OPF – Application of OPF analysis in Electricity and Power Marker rticipants – Power Flow Tracing – current decomposition axioms- Mathematical usage sharing problem on transmission facilities - Methodology of graph theory - Econ and transmission issues in the new market environment. AGC IN RESTRUCTURED POWER SYSTEM n – Traditional Vs Restructured Scenario –AGC in New market environment - Bloc the representation of a two-area interconnected power system in deregulated envir Control (LFC) dynamics and Bilateral Contacts – Modelling- DISCO Participation Participation Matrix (GPM). Total (45 Intercomes: Deletion of this course, the students will be able to: Select appropriate electrical utility based on applications Design power system according to requirements | ts with I mod conom ock dia onmer n Matr | Eler lel c ic is 9 agrai nt – rix (l | ctric sue + Ma Loa | s- 0 noad |
| Introductio Market Pa allocation- Mechanisn Unit V Introductio State Space Frequency Generation Course Ou Upon comp CO1 : CO2 : CO3 : CO3 : | n – Approaches to OPF – Application of OPF analysis in Electricity and Power Marke rticipants – Power Flow Tracing – current decomposition axioms- Mathematica usage sharing problem on transmission facilities - Methodology of graph theory - Ec and transmission issues in the new market environment. AGC IN RESTRUCTURED POWER SYSTEM n – Traditional Vs Restructured Scenario –AGC in New market environment - Blc re representation of a two-area interconnected power system in deregulated envir Control (LFC) dynamics and Bilateral Contacts – Modelling- DISCO Participation Participation Matrix (GPM). Total (45 tecmes: Deletion of this course, the students will be able to: Select appropriate electrical utility based on applications Design power system according to requirements Design an electrical market model Understand proper selection of automation in power systems Design load frequency control scheme for two area interconnected systems. | ts with I mod conom ock dia onmer n Matr | Eler lel c ic is 9 agrai nt – rix (l | ctric sue + Ma Loa | sity s- 0 no ad |
| Introductio Market Pa allocation- Mechanism Unit V Introductio State Space Frequency Generation Course Ou Upon comp CO1 : CO2 : CO3 : CO4 : CO5 : | n – Approaches to OPF – Application of OPF analysis in Electricity and Power Marke rticipants – Power Flow Tracing – current decomposition axioms- Mathematica usage sharing problem on transmission facilities - Methodology of graph theory - Ec and transmission issues in the new market environment. AGC IN RESTRUCTURED POWER SYSTEM n – Traditional Vs Restructured Scenario –AGC in New market environment - Blo re representation of a two-area interconnected power system in deregulated envir Control (LFC) dynamics and Bilateral Contacts – Modelling- DISCO Participation Participation Matrix (GPM). Total (45 tecomes: Deletion of this course, the students will be able to: Select appropriate electrical utility based on applications Design power system according to requirements Design an electrical market model Understand proper selection of automation in power systems Design load frequency control scheme for two area interconnected systems. s: | ts with I mod conom ock dia onmer n Matr +0)= 4 | Eler lel c ic is 9 agrai nt – rix (l | ctric sue + Ma Loa | sity s- 0 nd ad |
| Introductio Market Pa allocation- Mechanisn Unit V Introductio State Space Frequency Generation Course Ou Upon comp CO1 : CO2 : CO3 : CO3 : | n – Approaches to OPF – Application of OPF analysis in Electricity and Power Marke rticipants – Power Flow Tracing – current decomposition axioms- Mathematica usage sharing problem on transmission facilities - Methodology of graph theory - Ec and transmission issues in the new market environment. AGC IN RESTRUCTURED POWER SYSTEM n – Traditional Vs Restructured Scenario –AGC in New market environment - Blc re representation of a two-area interconnected power system in deregulated envir Control (LFC) dynamics and Bilateral Contacts – Modelling- DISCO Participation Participation Matrix (GPM). Total (45 rtcomes: Deletion of this course, the students will be able to: Select appropriate electrical utility based on applications Design power system according to requirements Design an electrical market model Understand proper selection of automation in power systems Design load frequency control scheme for two area interconnected systems. S: Loi Lei Lai, "Power System Restructuring and deregulation"- John Wiley & Sons,20 Md.Shahidehpour, MuwaffagAlmoush, "Restructured Electric Power System – Oper | ts with I mod conom bock dia onmen n Matu +0)= 4 | 9 agrant | tric of Iccsue + m a Loa DPN | |
| Introductio Market Pa allocation- Mechanism Unit V Introductio State Space Frequency Generation Course Ou Upon comp CO1 : CO2 : CO3 : CO3 : CO4 : CO5 : Text Book 1. | n – Approaches to OPF – Application of OPF analysis in Electricity and Power Marke rticipants – Power Flow Tracing – current decomposition axioms- Mathematica usage sharing problem on transmission facilities - Methodology of graph theory - Ec and transmission issues in the new market environment. AGC IN RESTRUCTURED POWER SYSTEM n – Traditional Vs Restructured Scenario –AGC in New market environment - Blo re representation of a two-area interconnected power system in deregulated envir Control (LFC) dynamics and Bilateral Contacts – Modelling- DISCO Participation Participation Matrix (GPM). Total (45 rtcomes: Deletion of this course, the students will be able to: Select appropriate electrical utility based on applications Design power system according to requirements Design an electrical market model Understand proper selection of automation in power systems Design load frequency control scheme for two area interconnected systems. Select Lai, "Power System Restructuring and deregulation"- John Wiley & Sons,20 | ts with I mod conom bock dia onmer n Matr +0)= 4 | 9 agrant | tric of Iccsue + m a Loa DPN | |

| Reference | |
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| 1 | Xi Fan, Wang, Yonghua Song, Malcolm Irving, "Modern Power System Analysis", Springer, 2008 |
| 2 | Das D, "Electrical Power Systems", New Age International (P) Ltd, New Delh,- 2008. |
| 3 | liic M, Galiana F, Fink L, "Power Systems Restructuring" Norwell MA Kluwer 1998 |
| 4 | Philipson. L, Willis H.Le, "Understanding Electric Utilities and de-regulation", Marcel Dekker Inc |
| | Publishers, New York, 2006 |
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| 1 | www.onlinecourses.nptel.ac.in |
| 2 | www.class-central.com |

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| CO1 | 1 | 1 | 3 | | | | | | | | 1 | 2 |
| CO2 | 1 | 2 | 3 | 2 | 2 | | 2 | | | | | 2 |
| CO3 | 1 | 2 | 3 | 2 | 2 | | 2 | | | | | 2 |
| CO4 | 1 | 2 | 2 | | | | | | | | 1 | 2 |
| CO5 | 1 | 2 | 3 | 2 | 2 | | 2 | | | | | 2 |

| | INDUSTRIAL ELECTRICAL SYSTEMS | . T | P | C |
|---|---|--|---|---|
| | | 8 0 | 0 | 3 |
| Course Ol | bjectives: | | | |
| 1 | Know about the implementation of Electrical Systems based on applications | | | |
| 2 | Learn various safety equipment and their installations | | | |
| 3 | Get a clear awareness about automation in Electrical Systems | | | |
| 11 14 1 | | - | | |
| Unit I | ELECTRICAL SYSTEM COMPONENTS | 9 | + | 0 |
| Tariff struc symbols, s | n wiring components, select ion of cables, wires, switches, distribution box, met cture, protection components- Fuse, MCB, MCCB, ELCB, RCCB inverse current cl ingle line diagram (SLD) of a wiring system, Contactor, Isolator, Relays, MPCB, Electr safety practices | narac | terist | tics, |
| Unit II | RESIDENTIAL AND COMMERCIAL ELECTRICAL SYSTEMS | 9 | + | 0 |
| | residential and commercial wiring systems, general rules and guidelines for insta | - | - | - |
| calculation calculation | and sizing of wire, rating of main switch, distribution board and protection devices, earlies, requirements of commercial installation, deciding lighting scheme and number of lar cial installation, selection and sizing of components. | hing | syste | em |
| Unit III | ILLUMINATION SYSTEMS | 9 | | |
| - | ding various terms regarding light, lumen, intensity, candle power, lamp efficie | - | + | 0 oifio |
| | Incandescent lamps and modern luminaries like CFL, LED and their operation, e ation systems, design of a lighting scheme for a residential and commercial pro- | | | |
| | | | | |
| Unit IV | INDUSTRIAL ELECTRICAL SYSTEM | 9 | + | 0 |
| Unit IV HT conne SLD, Cable calculation | INDUSTRIAL ELECTRICAL SYSTEM ction, industrial substation, Transformer selection, Industrial loads, motors, startir e and Switchgear selection, Lightning Protection, Earthing design, Power factor correct s, type of compensation, Introduction to PCC, MCC panels. Specifications of LT Brow LT panel components. | ng of | – k\ | ors, /AR |
| Unit IV HT conne SLD, Cabl calculation and other I | ction, industrial substation, Transformer selection, Industrial loads, motors, startir e and Switchgear selection, Lightning Protection, Earthing design, Power factor correct is, type of compensation, Introduction to PCC, MCC panels. Specifications of LT Brought LT panel components. | ng of tion eaker | – k\ | ors, /AR CB |
| Unit IV HT conne SLD, Cabl calculation and other I Unit V | ction, industrial substation, Transformer selection, Industrial loads, motors, startir e and Switchgear selection, Lightning Protection, Earthing design, Power factor correct is, type of compensation, Introduction to PCC, MCC panels. Specifications of LT Brow LT panel components. | ng of ction eaker | – k\ s, M | ors, /AR CB |
| Unit IV HT conne SLD, Cabl calculation and other I Unit V Study of b | ction, industrial substation, Transformer selection, Industrial loads, motors, startir e and Switchgear selection, Lightning Protection, Earthing design, Power factor correct is, type of compensation, Introduction to PCC, MCC panels. Specifications of LT Brought LT panel components. | ng of ction eaker | – k\ s, M | ors, /AR CB |
| Unit IV HT conne SLD, Cabl calculation and other I Unit V Study of b | ction, industrial substation, Transformer selection, Industrial loads, motors, startir e and Switchgear selection, Lightning Protection, Earthing design, Power factor corrects, type of compensation, Introduction to PCC, MCC panels. Specifications of LT Bruch panel components. INDUSTRIAL ELECTRICAL SYSTEM AUTOMATION asic PLC, Role of in automation, advantages of process automation, PLC based con inel Metering and Introduction to SCADA system for distribution automation. | ng of ction eaker 9 ntrol s | – k\ s, M + syste | ors, /AR CB 0 m |
| Unit IV HT conne SLD, Cabl calculation and other I Unit V Study of b | ction, industrial substation, Transformer selection, Industrial loads, motors, startir e and Switchgear selection, Lightning Protection, Earthing design, Power factor correct is, type of compensation, Introduction to PCC, MCC panels. Specifications of LT Bro LT panel components. INDUSTRIAL ELECTRICAL SYSTEM AUTOMATION asic PLC, Role of in automation, advantages of process automation, PLC based con inel Metering and Introduction to SCADA system for distribution automation. Total (45+0) | ng of ction eaker 9 ntrol s | – k\ s, M + syste | ors, /AR CB 0 m |
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| Unit IV HT conne SLD, Cable calculation and other I Unit V Study of b design, Pa Course Ou Upon com | ction, industrial substation, Transformer selection, Industrial loads, motors, startir e and Switchgear selection, Lightning Protection, Earthing design, Power factor correct is, type of compensation, Introduction to PCC, MCC panels. Specifications of LT Br LT panel components. INDUSTRIAL ELECTRICAL SYSTEM AUTOMATION asic PLC, Role of in automation, advantages of process automation, PLC based con inel Metering and Introduction to SCADA system for distribution automation. Total (45+0) utcomes: pletion of this course, the students will be able to: | ng of ction eaker 9 ntrol s | – k\ s, M + syste | ors, /AR CB 0 m |
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| E | -Reference | ces: |
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| | 1 | www.onlinecourses.nptel.ac.in |
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| • | | he Recognize current and possible future role of renewable e | | | |
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| Unit I | INTRODUCTION | | 9 | + | 0 |
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| Unit II | SOLAR ENERGY | | 9 | + | 0 |
| Thermal | | Solar Radiation – Flat Plate and Concentrating Collectors Power Generation – Fundamentals of Solar Photo Voltaic on – Solar PV Applications. | | | |
| Unit III | WIND ENERGY | | 9 | | 0 |
| Wind Dat | | pes of Wind Energy Systems – Performance – Site Selection Environmental Aspects. | • | - Detai | |
| Unit IV | BIO – ENERGY | | 9 | + | 0 |
| Biomass | Direct Combustion – Biomass | Gasifiers – Biogas Plants – Digesters – Ethanol Production | – Bi | io Die | esel – |
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| 7. | Chetan Singh Solanki, Solar Photovoltaics, "Fundamentals, Technologies and Applications", PHI Learning Private Limited, New Delhi, 2009. |
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| 3 Course Objectives: 1. To introduce communication technologies, infrastructure and high performance com Smart Grid. Unit 1 INTRODUCTION TO SMART GRID 9 Definitions and Need for Smart Grid, key aspects of Smart Grid development, Smart Grid architecture, of Smart Grid Components, challenges and benefits. 9 Unit II COMMUNICATION TECHNOLOGIES 9 Communication infrastructure for the Smart Grid, IEEE 802 architecture and, communication tect specified under IEEE 802, Wireless LANs, ZigBee and 6LoWPAN, ZigBee communication network for metering. 9 Smart metering: Benefits, Architecture, Key components and operation, communications architecture metering, Intelligent electronic devices (IED), Relay IED, Bay controller. 9 Structure of Energy management systems- Phasor measurement units - Supervisory Con Data Acquisition- Customer information system 9 Unit V ENERGY STORAGE SYSTEMS 9 Need of Energy Storage for the smart grid - Energy storage technologies - Flow battery - FL Superconducting magnetic energy storage systems - Supercapacitors 9 Upon completion of this course, the students will be able to: CO1 1 CO1 2 Get acquainted with the smart resources and devices 2 CO2 3 Get acquainted with the smart resources and devices 2 2 | + Function + Inologi or smain + | 0 000 es rt 0 |
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| Total (45+0) = 4 Course Outcomes: Upon completion of this course, the students will be able to: CO1 : Understand the concepts of Smart Grid and its present developments. CO2 : Get acquainted with the smart resources and devices CO3 : Acquire knowledge of automation and control infrastructure. CO4 : Select an energy storage system and its integration with Smart Grids | el cell | - |
| Course Outcomes: Upon completion of this course, the students will be able to: CO1 : Understand the concepts of Smart Grid and its present developments. CO2 : Get acquainted with the smart resources and devices CO3 : Acquire knowledge of automation and control infrastructure. CO4 : Select an energy storage system and its integration with Smart Grids | | |
| Course Outcomes: Upon completion of this course, the students will be able to: CO1 : Understand the concepts of Smart Grid and its present developments. CO2 : Get acquainted with the smart resources and devices CO3 : Acquire knowledge of automation and control infrastructure. CO4 : Select an energy storage system and its integration with Smart Grids | <u> </u> | |
| Upon completion of this course, the students will be able to: CO1 : Understand the concepts of Smart Grid and its present developments. CO2 : Get acquainted with the smart resources and devices CO3 : Acquire knowledge of automation and control infrastructure. CO4 : Select an energy storage system and its integration with Smart Grids | o Perio | bd |
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| CO2 : Get acquainted with the smart resources and devices CO3 : Acquire knowledge of automation and control infrastructure. CO4 : Select an energy storage system and its integration with Smart Grids | | |
| CO3 : Acquire knowledge of automation and control infrastructure. CO4 : Select an energy storage system and its integration with Smart Grids | | |
| CO4 : Select an energy storage system and its integration with Smart Grids | | |
| | | |
| CO5 [: Identify suitable communication networks for smart grid applications | | |
| | | |
| Taxt Backer | | |
| Text Books: 1. James Momoh "SMART GRID Fundamentals of Design and Analysis", Wiley, 2015. | | |
| Janaka Ekanayake, Nick Jenkins, KithsiriLiyanage, Jianzhong Wu, Akihiko Yoko | | |
| 2. "SmartGrid: Technology and Applications", Wiley, 2012. | | |
| 3. Mini S. Thomas, John D McDonald, 'Power System SCADA and Smart Grids', CRC Pre- | yama, | |
| CO/PO Mapping | | |
| | | |
| | | |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
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| CO1 | | | | 3 | | 2 | 1 | | 1 | | | 1 |
| CO2 | | 2 | 3 | 1 | | | | 1 | | | 1 | |
| CO3 | | | 2 | | 2 | | | | | 2 | | |
| CO4 | 2 | | | | 3 | 1 | 3 | | | | 2 | |
| CO5 | | 3 | | 2 | | | | 1 | 2 | | | 2 |

| 18EEOE | ENERGY CONSERVATION AND MANAGEMENT | L | Т | Ρ | С |
|--|--|-------------------------|------------|-------|-----------|
| Course 0 | bjectives: | 3 | 0 | 0 | 3 |
| 1. | To get knowledge about basics of energy and energy scenario on India. | | | | |
| 2. | To understand the energy conservation concepts. | | | | |
| 3. | To know about electrical energy management. | | | | |
| 11-24 | | | | 1 | |
| Unit I | ENERGY SCENARIO enario of India – Present non-renewable energy scenario – Gross domestic product- | Enor | 9 avi | + | 0 Oitu |
| | energy production and pricing – Energy security - Energy strategy for the future, air p | | | | |
| | nergy Conservation Act-2001 and its features. | Jonat | 011, | CIIII | aic |
| | | | | | - |
| Unit II | BASICS OF ENERGY | | 9 | + | 0 |
| | on – Work, power and energy – Electricity basics – Thermal energy basics – En ns – Energy performance – Matching energy usage to requirement. | hergy | un | its a | ind |
| COnversio | is – Energy performance – Matching energy usage to requirement. | | | | |
| Unit III | ENERGY CONSERVATION APPROACHES | | 9 | + | 0 |
| | ving opportunities in electric motors, Benefits of Power factor improvement and its te | | | | |
| | Synchronous Condenser etc., Energy conservation by industrial drives, Methods an | | | | |
| | onservation in ventilation and air conditioners, compressors pumps, fans and b | | | | |
| | on in electric furnaces, ovens and boilers., lighting techniques - Natural , CFL, LED | lighti | ng | sour | ces |
| and fitting | <u>.</u> | | | | |
| Unit IV | | | 9 | + | 0 |
| | ide management (DSM)– DSM planning – DSM Techniques – Load management as | a DS | - | | - |
| | conservation – tarrif options for DSM - Energy audit – instruments for energy audit – E | | | | |
| | n, distribution and utilization systems – economic analysis. | inerg | y u | uun | 01 |
| | | | | | |
| Unit V | ENERGY EFFICIENT TECHNOLOGIES | | 9 | + | 0 |
| | demand controllers - Automatic power factor controllers - Energy efficient motors - | | | | |
| | ver - Variable speed drives - Energy efficient transformers - Electronic ballast - Occu | panc | y se | enso | rs - |
| Energy er | icient lighting controls - Energy saving potential of each technology. | | | | |
| | Total (45- | +0)= | 45 I | Perie | ods |
| Course C | | , | | | |
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| | | | | | |
| Upon com | pletion of this course, the students will be able to: | | | | |
| Upon com CO1 : | pletion of this course, the students will be able to: Understand the present energy scenario. | | | | |
| CO1 : CO2 : | Understand the present energy scenario. Get fundamental knowledge about energy and its various forms. | | | | |
| CO1 : CO2 : CO3 : | Understand the present energy scenario.Get fundamental knowledge about energy and its various forms.Understand the process of energy management and energy auditing. | | | | |
| CO1 : CO2 : CO3 : CO4 : | Understand the present energy scenario. Get fundamental knowledge about energy and its various forms. Understand the process of energy management and energy auditing. Understand the methods improving energy efficiency and energy efficient devices. | | | | |
| CO1 : CO2 : CO3 : | Understand the present energy scenario.Get fundamental knowledge about energy and its various forms.Understand the process of energy management and energy auditing. | | | | |
| CO1 : CO2 : CO3 : CO4 : CO5 : | Understand the present energy scenario. Get fundamental knowledge about energy and its various forms. Understand the process of energy management and energy auditing. Understand the methods improving energy efficiency and energy efficient devices. Familiarize the role of energy efficient devices in energy conservation | | | | |
| CO1 : CO2 : CO3 : CO4 : CO5 : Text Boo | Understand the present energy scenario. Get fundamental knowledge about energy and its various forms. Understand the process of energy management and energy auditing. Understand the methods improving energy efficiency and energy efficient devices. Familiarize the role of energy efficient devices in energy conservation | | | | |
| CO1 : CO2 : CO3 : CO4 : CO5 : | Understand the present energy scenario. Get fundamental knowledge about energy and its various forms. Understand the process of energy management and energy auditing. Understand the methods improving energy efficiency and energy efficient devices. Familiarize the role of energy efficient devices in energy conservation s: Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2015. | 1. | | | |
| CO1 : CO2 : CO3 : CO4 : CO5 : Text Boo 1. | Understand the present energy scenario. Get fundamental knowledge about energy and its various forms. Understand the process of energy management and energy auditing. Understand the methods improving energy efficiency and energy efficient devices. Familiarize the role of energy efficient devices in energy conservation | 1. | | | |
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| CO1 : CO2 : CO3 : CO4 : CO5 : Text Boo 1. 2. 2. | Understand the present energy scenario. Get fundamental knowledge about energy and its various forms. Understand the process of energy management and energy auditing. Understand the methods improving energy efficiency and energy efficient devices. Familiarize the role of energy efficient devices in energy conservation sc: Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2015. Tripathy, S. C, "Utilization of Electrical Energy and Conservation", McGraw Hill, 199 Books: Guide books for National Certification Examination for Energy Manager / Energy A | | rsB | | 1, |
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| CO1 : CO2 : CO3 : CO4 : CO5 : Text Boo 1. 2. 2. Referenc 1. | Understand the present energy scenario. Get fundamental knowledge about energy and its various forms. Understand the process of energy management and energy auditing. Understand the methods improving energy efficiency and energy efficient devices. Familiarize the role of energy efficient devices in energy conservation sc: Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2015. Tripathy, S. C, "Utilization of Electrical Energy and Conservation", McGraw Hill, 199 Books: Guide books for National Certification Examination for Energy Manager / Energy A General Aspects (available online). Guide books for National Certification Examination for Energy Manager / Energy A | udito udito on, 1 | rsB 982 | ook- | |

| E-Referen | ces: |
|-----------|---|
| 1. | www.bee-india.nic.in |
| 2. | NPTEL Course: Non-Conventional Energy Resources – Prof. PrathapHaridoss, IIT-M. |
| 3. | NPTEL Course: Energy Management Systems and SCADA, 2015 organised by IIT-M. |

| PO CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 1 | 2 | 3 | 2 | 2 | 1 | 3 | 2 | 2 | 2 | 2 | 2 |
| CO2 | 1 | 1 | 2 | 2 | 1 | 1 | 3 | 2 | 1 | 1 | 2 | 2 |
| CO3 | 2 | 2 | 2 | 3 | 1 | 1 | 3 | 2 | 2 | 2 | 1 | 2 |
| CO4 | 2 | 1 | 2 | 2 | 1 | 1 | 3 | 2 | 1 | 2 | 2 | 2 |
| CO5 | 2 | 2 | 3 | 1 | 2 | 1 | 3 | 1 | 2 | 1 | 2 | 1 |

| | 4 ELECTRIC VEHICLES | L | Т | Ρ | C | | | | |
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| | | 3 | 0 | 0 | 3 | | | | |
| | Objectives | | | | | | | | |
| 1. | To understand the components of Electric Vehicle and its global and Indian scenari | 0. | | | | | | | |
| 2. | To understand the types of Electric Vehicle and its architectural design. | | | | | | | | |
| 3. | To analyze the performance of different types of motor and its electrical an | nd n | necl | nanio | cal | | | | |
| | connections. | | | | | | | | |
| 4. | To analyse the energy storage performance and battery management systems. | | | | | | | | |
| 5. | To understand the types of charging stations and its components. | | | | | | | | |
| Unit I | INTRODUCTION TO ELECTRIC VEHICLES | | | | | | | | |
| Compon | ents of Electric Vehicle, Comparison with Internal combustion Engine : Technology, Co | mpa | risc | n wi | th | | | | |
| Internal of | combustion Engine: Benefits and Challenges, EV classification and their electrification I | eve | ls, E | V | | | | | |
| Terminol | ogy, Global and Indian Scenario: Technology Scenario, Market scenario, Policies and R | legu | latio | ons, | | | | | |
| Unit II | ELECTRIC VEHICLE ARCHITECTURE DESIGN | | 9 | + | 0 | | | | |
| | Electric Vehicle and components, Electrical protection and system requirement, Photo | | | | | | | | |
| | / design, Battery Electric vehicle (BEV), Hybrid electric vehicle (HEV) , Plug-in hybrid ve | | • | | | | | | |
| | electric vehicle (FCEV), Electrification Level of EV, Comparison of fuel Vs electric and | sola | ar po | ower | , | | | | |
| | wer operated Electric vehicles. | | | 1 | - | | | | |
| Unit III | ELECTRIC DRIVE AND CONTROLLER | | 9 | + | 0 | | | | |
| | | | | | | | | | |
| | Motors, Selection and sizing of Motor, RPM and Torque calculation of motor, Motor Co | ntro | ller | 5, | | | | | |
| Compon | ent sizing. | ntro | ller | 8, | | | | | |
| Compon Physical | ent sizing. locations, Mechanical connection of motor, Electrical connection of motor. | ntro | | 1 | | | | | |
| Compon Physical Unit IV | ent sizing. locations, Mechanical connection of motor, Electrical connection of motor. ENERGY STORAGE SOLUTIONS AND BATTERY MANAGEMENT SYSTEM | | 9 | + | C | | | | |
| Compon Physical Unit IV Cell Type | ent sizing. locations, Mechanical connection of motor, Electrical connection of motor. ENERGY STORAGE SOLUTIONS AND BATTERY MANAGEMENT SYSTEM es (Lead Acid/Li/NiMH),Battery charging and discharging calculation, Cell Selection and | d siz | 9 2ing | + | 0 | | | | |
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| Compon Physical Unit IV Cell Type Battery la Need of control, N Unit V Type of C line diagu Course 0 Upon con CO1 CO2 CO3 | ent sizing. locations, Mechanical connection of motor, Electrical connection of motor. ENERGY STORAGE SOLUTIONS AND BATTERY MANAGEMENT SYSTEM es (Lead Acid/Li/NiMH),Battery charging and discharging calculation, Cell Selection and ay outing design, Battery Pack Configuration, Battery Pack Construction, Battery selecti BMS, Rule based control and optimization based control, Software-based high level su Mode of power, Behavior of motor, Advance Features. ELECTRIC VEHICLES CHARGING STATION Charging station, Selection and Sizing of charging station, Components of charging statior and of charging station. Total (45+ Dutcomes: mpletion of this course, the students will be able to: Understand the concept of Electric Vehicle technology Understand the types of EV and analyse their characteristics. Analyse the selection and sizing of drive and controller. | d siz on c perv on, | 9 crite /iso 9 Sing | ria. ry + gle | 0 | | | | |
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| 2. | Iqbal Hussain "Electric and Hybrid Vehicles: Design Fundamentals", CRC Press, Taylor &Francis Group, Second Edition (2011). |
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| Reference | Books: |
| 1. | Ali Emadi, Mehrdad Ehsani, John M.Miller ,"Vehicular Electric Power Systems", Ali Emadi, Mehrdad Ehsani, John M.Miller, Special Indian Edition, Marcel dekker, Inc 2010 |
| 2. | Standards. IEC IEC 60068-2 (1,2,14,30),IEC 61683,IEC 60227,IEC 60502 IEC 60947 part I,II, III ,IEC 61215 |
| E-Reference | es: |
| 1 | www.onlinecourses.nptel.ac.in |
| 2 | www.class-central.com |
| 3 | www.mooc-list.com |

| CO PO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 |
|-------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|
| CO1 | 3 | 1 | 1 | 3 | 1 | 1 | 1 | 1 | | | 1 | 1 |
| CO2 | 2 | 3 | 3 | 2 | 1 | 1 | 2 | 1 | 1 | | | 1 |
| CO3 | 1 | 3 | 3 | 3 | 1 | 1 | 2 | 2 | | 1 | 1 | |
| CO4 | 1 | 2 | 2 | 3 | 3 | 1 | 2 | 1 | | 1 | 1 | |
| CO5 | 1 | 1 | 3 | 2 | 3 | 1 | 2 | 2 | | 1 | 1 | 1 |
| CO6 | 1 | 3 | 3 | 3 | 3 | 1 | 2 | 2 | 1 | | 1 | 1 |

PROTOSEM COURSES SYLLABUS

| 18MI | EPS11 | APPLIED DESIGN THINKING | | S | Semeste | er | VI |
|----------|--------------------|---|-----------------------|----------|----------|-----------|----------|
| PRER | EQUIS | ITES | Category | PE | Cre | edit | 3 |
| | | | | L | Т | Р | TH |
| | | | Hours/Week | 3 | 0 | 0 | 3 |
| Cours | e Learn | ing Objectives | | | | - | |
| | | | . 1 .1 . | 1 | 1 | | |
| 1 | | arse enables product innovators and early-stage startup founde | | | - | - | |
| 2 | | liarize with the tools & techniques & validate the inherent risk er-commitment & customer-acceptance. | s by linking their pr | ogress t | o custor | ner-mot | ivation, |
| 3 | To learn | n the system thinking concepts by reverse engineering techniq | lue. | | | | |
| Un | it I | DESIGN THINKING PRINCIPLES | | 9 | 0 | 0 | 9 |
| - | - | an – Centered Design – Understanding the innovation process ding techniques, Mitigate validate risk with FIR(Forge Innova | - | - | - | y, interv | viewing |
| Un | it II | CUSTOMER-CENTRIC INNOVATION | | 9 | 0 | 0 | 9 |
| and pro | blem inc | istomer-centric innovation – Problem Validation and Custome idence- Customer Validation. Target user, User persona & use rviews and field visit. | | | | - | |
| Uni | t III | APPLIED DESIGN THINKING TOOLS | | 9 | 0 | 0 | 9 |
| Design | | imum Usable Prototype(MUP) – MUP challenge brief – Desig Festing Value Proposition: Design a compelling value proposi ign. | | | | | e |
| Uni | t IV | CONCEPT GENERATION | | 9 | 0 | 0 | 9 |
| build th | ne right p | ation, Concepts Generation and MUP design – Conceptualize rototype: Assess capability, usability and feasibility. Systemat the solution concepts. | - | - | | | |
| Un | it V | SYSTEM THINKING & REVERSE ENGINEERIN | NG | 9 | 0 | 0 | 9 |
| - | | ng, Understanding Systems, Examples and Understandi lentify building blocks/Components – Re-Engineering a comp | • • • | vstems, | Revers | e Engi | neering |
| | Total = 45 Periods | | | | | | |
| T | | | | | | | |
| 1 ex | t Books: | | | | | | |
| 1 | Steve Bl | ank, (2013), The four steps to epiphany: Successful strategies | for products that w | vin, Wil | ey. | | |
| 2 | Alexand | er Osterwalder, Yves Pigneur, Gregory Bernarda, Alan Smith | , Trish Papadakos, | (2014), | Value | | |
| 3 | Proposit | ion Design: How to Create Products and Services Customers | Want, Wiley | | | | |

4 Donella H. Meadows, (2015), "Thinking in Systems - A Primer", Sustainability Institute.

5 Tim Brown,(2012) "Change by Design: How Design Thinking Transforms Organizations and Inspires Innovation", Harper Business.

| Refe | Reference Books: | | | | | | | |
|------|---|--|--|--|--|--|--|--|
| 1 | https://www.ideou.com/pages/design-thinking#process | | | | | | | |
| 2 | https://blog.forgeforward.in/valuation-risk-versus-validation-risk-in-product-innovations-49f253c a8624 | | | | | | | |
| 3 | https://blog.forgeforward.in/product-innovation-rubric-adf5ebdfd356 | | | | | | | |
| 4 | https://blog.forgeforward.in/evaluating-product-innovations-e8178e58b86e | | | | | | | |
| 5 | https://blog.forgeforward.in/user-guide-for-product-innovation-rubric-857181b253dd 6 | | | | | | | |
| 6 | https://blog.forgeforward.in/startup-failure-is-like-true-lie-7812cdfe9b85 | | | | | | | |

| | Course Outcomes: Upon completion of this course, the students will be able to: | | | | | | |
|-----|--|--------------|--|--|--|--|--|
| CO1 | CO1 Define & treat various hypotheses to mitigate the inherent risks in product innovations | | | | | | |
| CO2 | Design the solution concept based on the proposed value by exploring various alternate solutions to achieve value-price fit. | L6: Creating | | | | | |
| CO3 | Develop skills in empathizing, critical thinking, analyzing, storytelling & pitching. | L3: Applying | | | | | |
| CO4 | Apply system thinking to reverse engineer a product/prototype and understand its internal correlations. | L3: Applying | | | | | |

| CO | P01 | P02 | P03 | P04 | P05 | P06 | P07 | P08 | P09 | P010 | P011 | P012 | PS01 | PS02 | PS03 |
|-----|------|-----|-----|------|-----|------|------|-----|------|------|------|------|------|------|------|
| C01 | 2 | 3 | 2 | 3 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 2 | 2 | 3 |
| C02 | 2 | 2 | 3 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 3 | 3 | 2 |
| CO3 | 1 | 2 | 2 | 1 | 1 | 3 | 1 | 1 | 3 | 3 | 1 | 1 | 1 | 1 | 1 |
| C04 | 2 | 3 | 3 | 3 | 3 | 2 | 2 | 1 | 2 | 2 | 1 | 1 | 3 | 3 | 3 |
| AVG | 1.75 | 2.5 | 2.5 | 2.25 | 2 | 1.75 | 1.25 | 1 | 1.75 | 1.75 | 1 | 1 | 2.25 | 2.25 | 2.25 |

0: No correlation, 1: Low correlation, 2: Medium correlation, 3: High correlation

| 18MF | EPS12 | STARTUP FUNDAMENTALS | | Semester | | | | | | | |
|---------|------------|---|----------------------|-----------|-----------|----------|----------|--|--|--|--|
| PRER | EQUIS | ITES | Category | | Cre | edit | 3 | | | | |
| | | | | L | T P | | ТН | | | | |
| | | | Hours/Week | 3 | 3 | | | | | | |
| Cours | e Learn | ing Objectives | | | | | | | | | |
| 1 | Learn t | he science of to transforming an innovative idea into high-gro | wth enterprises. | | | | | | | | |
| 2 | To und | erstand the basic concepts of IPR, and develop a patent draft for | or a potential IP | | | | | | | | |
| Un | it I | ENTREPRENEURIAL MINDSET & METHOD | | 9 | 0 | 0 | 9 | | | | |
| | | Innovation-led, tech-powered entrepreneurship - Underst Effectuation principles - Dealing with the unknowns - Case stu | | | ttributes | s of an | expert | | | | |
| Uni | it II | IDEA TO ENTERPRISE | | 9 | 0 | 0 | 9 | | | | |
| - | | nning of Product Concept - Business Model - Business Plannin nd Revenue Planning | g - Building Proof | of Prod | uct and | Value T | esting - | | | | |
| Uni | t III | MINIMUM VIABLE BUSINESS | | 9 | 0 | 0 | 9 | | | | |
| | | Minimum Viable Business - Disruptive Innovation - Theory o ousiness model - Demystifying Scalability - Funding Opportu | - | petitive | advanta | age - Bu | ilding | | | | |
| Uni | t IV | INTELLECTUAL PROPERTY | | 9 | 0 | 0 | 9 | | | | |
| Secret | | nd the need for Intellectual Property Rights - IPR Genesis an aphical Indicators - Industrial Designs - Types of Patent – Sa fees | | | | | | | | | |
| Uni | it V | PRIOR ART SEARCH AND PATENT DRAFTING | r T | 9 | 0 | 0 | 9 | | | | |
| basmati | i rice. Th | n - IP Licensing – IP Commercialization - IP Infringement- (e invention as a concept - Keywords formation - Structure of p fifications - Drafting complete specifications - Draft claims - (| batent - Key attribu | tes in pa | atent dra | | | | | | |
| | | | | | Total | = 45 I | Periods | | | | |
| | Deales | | | | | | | | | | |

| Tey | at Books: |
|-----|--|
| 1 | Steven Blank and Bob Dorf, (2012), The Startup Owner's Manual: The Step-by-Step Guide for Building a Great Company, K&S Ranch |
| 2 | Dr Saras Sarasvathy, (2008), Effectuation: Elements of Entrepreneurial Expertise, New Horizons in Entrepreneurship series. |
| 3 | Elizabeth Verkey, (2005), Law of Patents, Eastern Book Company |
| 4 | Prabuddha Ganguli, (2017), Intellectual Property Rights: Unleashing the Knowledge Economy, McGraw Hill Educatio 1st edition |

| Ref | Reference Books: | | | | | | | |
|-----|--|--|--|--|--|--|--|--|
| 1 | WIPO Intellectual Property Handbook https://www.wipo.int/edocs/pubdocs/en/intproperty/489/wipo_pub_489.pdf | | | | | | | |
| 2 | https://assets.entrepreneur.com/static/20220301113822-Marketing.pdf | | | | | | | |
| 3 | https://www.deluxe.com/blog/startup-fundamentals-guide/ | | | | | | | |
| 4 | https://www.forbes.com/sites/allbusiness/2018/07/15/35-step-guide-entrepreneurs-starting-a-business/?sh=69a6031e184b | | | | | | | |

| | Course Outcomes: Upon completion of this course, the students will be able to: | | | | | | | |
|-----|--|-------------------|--|--|--|--|--|--|
| CO1 | Develop an entrepreneurial mindset to identify, assess, shape & act on opportunities. | L3: Applying | | | | | | |
| CO2 | Demonstrate the potential of an innovative idea to create economic value, as a startup | L2: Understanding | | | | | | |
| CO3 | Understand the scientific process to explore a viable business model | L2: Understanding | | | | | | |
| CO4 | Demonstrate knowledge on the fundamental concepts of Intellectual Property | L2: Understanding | | | | | | |

| CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----|------|------|-----|------|-----|------|-----|-----|-----|------|------|------|------|------|------|
| C01 | 1 | 2 | 2 | 1 | 1 | 2 | 1 | 2 | 2 | 2 | 3 | 3 | 1 | 1 | 2 |
| C02 | 2 | 2 | 3 | 1 | 1 | 1 | 1 | 2 | 2 | 1 | 3 | 2 | 2 | 2 | 2 |
| CO3 | 1 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 3 | 2 | 1 | 1 | 1 |
| C04 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 3 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| AVG | 1.25 | 1.75 | 2 | 1.25 | 1 | 1.25 | 1 | 2 | 1.5 | 1.25 | 2.5 | 2 | 1.25 | 1.25 | 1.5 |

0: No correlation, 1: Low correlation, 2: Medium correlation, 3: High correlation

| 18MI | EPS13 | COMPUTATIONAL HARDWAR | S | Semeste | er | VI | | | | |
|-------------------|---|--|----------------------|----------|----------|---------|---------|--|--|--|
| PRER | REQUIS | ITES | Category | PE | Cre | edit | 3 | | | |
| | | | | L | Т | Р | ТН | | | |
| | | | Hours/Week | 3 | 0 | 0 | 3 | | | |
| Cours | se Learn | ing Objectives | I | | | | | | | |
| 1 | | n basic concepts of Embedded Systems by familiarizing the fu oment boards. | inctionalities of em | bedded | platforn | ns with | | | | |
| 2 | To understand the core concepts of GPIO Pins, Functionality of peripherals, Selection of I/O devices, Usage | | | | | | | | | |
| 2 | - | nal functions, and Communication protocols. | | | | | | | | |
| 3 | To fam service | iliarize the current technologies and protocols used in the Inters. | rnet of Things (IoT |) and to | learn th | e Cloud | l | | | |
| Ur | nit I | BASICS OF EMBEDDED SYSTEM | | 9 | 0 | 0 | 9 | | | |
| schema | atics – To | form: Architecture and working - Factors for Microcontroller ool chain - Setup and Configuration - Input/Output Configuration mers, Interrupts - Pulse Width Modulation - Display: 7-segme | tions and Access - | | | | | | | |
| Un | it II | BASICS OF RASPBERRY PI | | 9 | 0 | 0 | 9 | | | |
| Genera | al Purpose | aspberry pi Board - Processor - Setup and Configuration - In e I/O Pins - Protocol Pins - GPIO Access - Pulse Width Modul Bot - Interfacing pi with camera modules. | | | - | | | | | |
| Uni | it III | SENSORS AND ACTUATORS | | 9 | 0 | 0 | 9 | | | |
| Soil M | oisture S | ensors and Actuators - Sensors: Introduction, Characteristics: ensor, LDR - Digital - PIR Sensor, Smoke Sensor, Infrared - S naracteristics and working with relay, DC motors, Servo motor | Sensor, Ultra- Sonic | c Sensor | . Actuat | | sor, | | | |
| Uni | it IV | COMMUNICATION PROTOCOLS | | 9 | 0 | 0 | 9 | | | |
| Comm | Protocols - Wired: RS232 Standard - UART, SPI, I2C - Comparative study of wired protocols - Implementation of wired Serial Communication protocols Wireless: Standards - Bluetooth, RF - Comparative study of wireless protocols - Implementation of wireless Serial Communication protocols. | | | | | | | | | |
| Un | it V | INTERNET OF THINGS | | 9 | 0 | 0 | 9 | | | |
| embede I/O per | Definition and Architecture of IoT, Building blocks of IoT, Programming with IoT protocols - MQTT, CoAP - Connecting embedded target board to Web, Basics networking in IoT: creating a web page - Creating a server on target board - Controlling I/O peripherals from the webpage, Embedded Application Development, Creating communication between different nodes - Cloud platforms for IoT, Cloud data logging and monitoring, Interfacing with web services. | | | | | | | | | |
| | | | | | Total | = 45 ł | Periods | | | |
| Tex | t Books | : | | | | | | | | |
| 1 | Raj Kan | nal, "Embedded Systems - SoC, IoT, AI and Real-Time Syste | ems", 4th Edition, N | /lcGraw | Hill, 20 | 020. | | | | |
| 2 | Mohit A | rora, "Embedded System Design", 1st Edition, Learning Byte | es Publishing, 2016 | | | | | | | |
| 3 | Elecia V | White, "Making Embedded Systems", 1st Edition, Shroff/ O' F | Reilly, 2012. | | | | | | | |
| 4 | 4 Jack Ganssle, "The Firmware Handbook", 1st Edition, Newnes, 2004. | | | | | | | | | |

| Reference Books: | | | | | | |
|------------------|---|--|--|--|--|--|
| 1 | https://juniorfall.files.wordpress.com/2011/11/arduino-cookbook.pdf | | | | | |
| 2 | https://drive.google.com/file/d/13s0m3lHPEFP2f2aCuVNRWeBZNKXWKTW5/view?ts=6231cab 3 | | | | | |
| 3 | https://ptolemy.berkeley.edu/books/leeseshia/releases/LeeSeshia_DigitalV2_2.pdf 4. | | | | | |
| 4 | https://www.riverpublishers.com/pdf/ebook/RP9788793519046.pdf | | | | | |

| Cours Upon o | Bloom's Taxonomy Level | |
|-----------------|---|-------------------|
| CO1 | Understand and implement the functions & Capabilities of embedded platforms for easy prototyping. | L2: Understanding |
| CO2 | Identify the type of sensors and actuators for required applications. | L3: Applying |
| CO3 | Develop communication between devices using different protocols. | L3: Applying |
| CO4 | Develop IoT based systems with wireless network connections and accessing devices over cloud. | L3: Applying |

| со | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----|-----|------|------|-----|------|-----|-----|-----|-----|------|------|------|------|------|------|
| C01 | 3 | 2 | 3 | 2 | 3 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 3 | 2 | 2 |
| C02 | 3 | 3 | 2 | 2 | 2 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 3 | 2 | 2 |
| CO3 | 3 | 2 | 3 | 2 | 3 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 3 | 3 | 3 |
| C04 | 3 | 2 | 3 | 2 | 3 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 3 | 3 | 3 |
| AVG | 3 | 2.25 | 2.75 | 2 | 2.75 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 3 | 2.5 | 2.5 |

0: No correlation, 1: Low correlation, 2: Medium correlation, 3: High correlation

| 18MEP | PS14 | CODING FOR INNOVATORS | | S | Semeste | er | VI | | | |
|--------------------------|---|--|------------------------|----------|---------------------|---------------------|---------------|--|--|--|
| PRERE | QUIS | ITES | Category | | Credit | | | | | |
| | | | Hours/Week | L | Р | ТН | | | | |
| | 3 | 0 | 0 | 3 | | | | | | |
| Course | Learn | ing Objectives | | I | | | | | | |
| 1 7 | Го learr | and express creativity using coding skills. | | | | | | | | |
| 2 7 | To gain knowledge of Python programming with hands-on experience. | | | | | | | | | |
| 3 Т | Го dem | onstrate a problem solving using OOPs concepts. | | | | | | | | |
| 4 T | Го learr | basics of Linux by familiarizing the concepts of management | at and file structure. | | | | | | | |
| 5 T | Го prac | tise full stack development using cloud platform. | | | | | | | | |
| Unit | Ι | PROGRAMMING PARADIGMS | | 9 | 0 | 0 | 9 | | | |
| operation | ion to H s, trave | BASIC OF PROGRAMMING Python: statements, variables, functions, operators, modules, of ersing a list, slicing a list - Text Handling: Strings, string fu open, close, read, copy, word frequency, creating word histog | nctions, conversion | n functi | | | | | | |
| Unit l | III | OOPS 5 | | 9 | 0 | 0 | 9 | | | |
| | • | OPS- verticals- implementation in python - Classes and Objectly lymorphism, Abstraction, Encapsulation. | cts, Methods, Const | tructors | and De | structors | 5, | | | |
| Unit l | Unit IV SOFTWARE DEVELOPMENT TO DELIVERY | | | | | | 9 | | | |
| Based) - - Source | Data S code 1 | neering - Life Cycle (Tools), Agile Methodologies - Framew tructures - Database Management System - A case study to exp management and version control - GitHub - GitHub Actions | periment from Deve | elopmei | nt to Dep | oloymer | t(D2D) | | | |
| | X 7 | u - Build Packs AWS- Anaconda | | | | | form as | | | |
| Unit | v | | | 9 | 0 | 0 | form as | | | |
| Introducti | ion to L stem Str | u - Build Packs AWS- Anaconda OPERATING SYSTEMS Linux - Process Management - Process Scheduling - Memory M ructure - Multithreading - Multicore Programming - Deadloch | - | age Mar | nagemer | ıt - Syste | 9 em calls | | | |
| Introducti - File Sys | ion to L stem Str | u - Build Packs AWS- Anaconda OPERATING SYSTEMS Linux - Process Management - Process Scheduling - Memory M ructure - Multithreading - Multicore Programming - Deadloch | - | age Mar | nagemer e - Disk | it - Syste Manag | 9 em calls | | | |

| Tex | xt Books: |
|-----|--|
| 1 | Zed A. Shaw, "Learn Python 3 the Hard Way", 3rd edition, Addison-Wesley Professional, 2013. |
| 2 | Silberschatz Abraham, "Operating System Concepts", 9th edition, John Wiley & Sons Inc (Sea) Pte Ltd, 2016. |
| 3 | Paul Barry, "Head-First Python", 2nd edition, O'Reilly Media, Inc, 2016. |
| 4 | Anton Spraul, "Think Like a Programmer", 1st edition, No Starch Press, 2012. |

| E-Re | E-References : | | | | | | | |
|------|--|--|--|--|--|--|--|--|
| 1 | https://www.geeksforgeeks.org/python-programming-language/ | | | | | | | |
| 2 | https://www.guru99.com/python-tutorials.html | | | | | | | |
| 3 | https://www.tutorialspoint.com/python/python_tutorial.pdf | | | | | | | |

| | Course Outcomes: Upon completion of this course, the students will be able to: | | | | | | |
|-----|---|-------------------|--|--|--|--|--|
| CO1 | Understand the aspects of programming protocols | L2: Understanding | | | | | |
| CO2 | Develop optimized code for real-world problems | L3: Applying | | | | | |
| CO3 | Build full-stack development to deployment | L3: Applying | | | | | |
| CO4 | Demonstrate problem solving and continuous development | L2: Understanding | | | | | |

| CO | P01 | P02 | P03 | P04 | P05 | P06 | P07 | P08 | P09 | P010 | P011 | P012 | PS01 | PS02 | PS03 |
|-----|-----|-----|-----|------|------|-----|-----|-----|-----|------|------|------|------|------|------|
| C01 | 2 | 2 | 2 | 1 | 3 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 2 | 1 | 1 |
| C02 | 3 | 3 | 3 | 2 | 3 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 3 | 2 | 2 |
| CO3 | 3 | 2 | 3 | 1 | 3 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 3 | 2 | 2 |
| C04 | 2 | 3 | 2 | 1 | 2 | 0 | 0 | 0 | 0 | 0 | 0 | 3 | 2 | 1 | 1 |
| AVG | 2.5 | 2.5 | 2.5 | 1.25 | 2.75 | 0 | 0 | 0 | 0 | 0 | 0 | 3 | 2.5 | 1.5 | 1.5 |

| PREREQUISITES Category OE Credit 3 Interval Control I T P TH Hours/Week I T P TH Interval Control I< | 18MI | EPS15 | INDUSTRIAL DESIGN AND RAPID PROTO TECHNIQUES | TYPING | S | Semester | | | | | |
|---|---------|-------------|--|----------------------|-----------|----------|----------|---------|--|--|--|
| Hours/Week J <thj< tr=""> Intrit In</thj<> | PRER | REQUIS | ITES | Category | OE | Cr | edit | 3 | | | |
| Solution Solution Solution Solution 1 Learn to design a UI/UX design and develop an android application. - - - 2 Provide working CAD model for prototype development. - < | | | | | L | Т | Р | ТН | | | |
| 1 Learn to design a Ul/UX design and develop an android application. 2 Provide working CAD model for prototype development. 3 Knowledge in hardware, 3D Printers and Laser cutters. 4 Acquire basic knowledge in designing electrical circuits and fabrication of electronic devices. Unit I UI / UX 9 0 0 9 Fundamental concepts in UI & UX - Tools - Fundamentals of design principles - Psychology and Human Factors for User Interface Design - Layout and composition for Web, Mobile and Devices - Typography - Information architecture - Colour theory - Design process flow, wireframes, best practices in the industry -User engagement ethics - Design alternatives Unit II APP DEVELOPMENT 9 0 0 9 SDLC - Introduction to App Development - Types of Apps - web Development - understanding Stack - Frontend - backend - Working with Databases - Introduction to AP1 - Introduction to Cloud services - Cloud environment Setup- Reading and writing data to cloud - Embedding ML models to Apps - Deploying application. 9 0 0 9 Unit III INDUSTRIAL DESIGN 9 0 0 9 0 0 9 Introduction to Industrial Design - Points, lines, and planes - Sketching and concept generation - Sketch to CAD - Introduction to CAD tools - Types of 3D modeling - Basic 3D Modeling Tools - Part creation - Assembly - Product design and rendering basi | | | | Hours/Week | 3 | 0 | 0 | 3 | | | |
| 2 Provide working CAD model for prototype development. 3 Knowledge in hardware, 3D Printers and Laser cutters. 4 Acquire basic knowledge in designing electrical circuits and fabrication of electronic devices. Unit I UI / UX 9 0 0 9 Fundamental concepts in UI & UX - Tools - Fundamentals of design principles - Psychology and Human Factors for User Interface Design - Layout and composition for Web, Mobile and Devices - Typography - Information architecture - Colour theory - Design process flow, wireframes, best practices in the industry -User engagement ethics - Design alternatives Unit II APP DEVELOPMENT 9 0 0 9 SDLC - Introduction to App Development - Types of Apps - web Development - understanding Stack - Frontend - backend - Working with Databases - Introduction to API - Introduction to Cloud services - Cloud environment Setup- Reading and writing data to cloud - Embedding ML models to Apps - Deploying application. 9 0 0 9 Introduction to Industrial Design - Points, lines, and planes - Sketching and concept generation - Sketch to CAD - Introduction to CAD tools - Types of 3D modeling - Basic 3D Modeling Tools - Part creation - Assembly - Product design and rendering basics - Dimensioning & Tolerancing 9 0 0 9 Unit II INDUSTRIAL DESIGN 9 0 0 9 0 0 9 Need | Cours | e Learn | ing Objectives | | | | | | | | |
| 3 Knowledge in hardware, 3D Printers and Laser cutters. 4 Acquire basic knowledge in designing electrical circuits and fabrication of electronic devices. Unit I UI / UX 9 0 0 9 Fundamental concepts in UI & UX - Tools - Fundamentals of design principles - Psychology and Human Factors for User Interface Design - Layout and composition for Web, Mobile and Devices - Typography - Information architecture - Colour theory - Design process flow, wireframes, best practices in the industry -User engagement ethics - Design alternatives Unit II APP DEVELOPMENT 9 0 0 9 SDLC - Introduction to App Development - Types of Apps - web Development - understanding Stack - Frontend - backend - Working with Databases - Introduction to API - Introduction to Cloud services - Cloud environment Setup - Reading and writing data to cloud - Embedding ML models to Apps - Deploying application. 9 0 0 9 Unit II INDUSTRIAL DESIGN 9 0 0 9 Introduction to Industrial Design - Points, lines, and planes - Sketching and concept generation - Sketch to CAD - Introduction to CAD tools - Types of 3D modeling - Basic 3D Modeling Tools - Part creation - Assembly - Product design and rendering basics - Dimensioning & Tolerancing 9 0 0 9 Unit IV MECHANICAL RAPID PROTOTYPING 9 0 0 9 0 0 | 1 | Learn t | o design a UI/UX design and develop an android application. | | | | | | | | |
| 4 Acquire basic knowledge in designing electrical circuits and fabrication of electronic devices. Unit I UI/UX 9 0 0 9 Fundamental concepts in UI & UX - Tools - Fundamentals of design principles - Psychology and Human Factors for User Interface Design - Layout and composition for Web, Mobile and Devices - Typography - Information architecture - Colour theory - Design process flow, wireframes, best practices in the industry -User engagement ethics - Design alternatives Unit II APP DEVELOPMENT 9 0 0 9 SDLC - Introduction to App Development - Types of Apps - web Development - understanding Stack - Frontend - backend - Working with Databases - Introduction to API - Introduction to Cloud services - Cloud environment Setup - Reading and writing data to cloud - Embedding ML models to Apps - Deploying application. 9 0 0 9 Unit III INDUSTRIAL DESIGN 9 0 0 9 Introduction to Industrial Design - Points, lines, and planes - Sketching and concept generation - Sketch to CAD - Introduction to CAD tools - Types of 3D modeling - Basic 3D Modeling Tools - Part creation - Assembly - Product design and rendering basics - Dimensioning & Tolerancing 9 0 0 9 Unit IV MECHANICAL RAPID PROTOTYPING 9 0 0 9 Need for prototyping - Domains in prototyping - Difference between actual manufacturing and prototyping - Rapi | 2 | Provide | e working CAD model for prototype development. | | | | | | | | |
| Unit I UI / UX 9 0 0 9 Fundamental concepts in UI & UX - Tools - Fundamentals of design principles - Psychology and Human Factors for User Interface Design - Layout and composition for Web, Mobile and Devices - Typography - Information architecture - Colour theory - Design process flow, wireframes, best practices in the industry -User engagement ethics - Design alternatives Unit II APP DEVELOPMENT 9 0 0 9 SDLC - Introduction to App Development - Types of Apps - web Development - understanding Stack - Frontend - backend - Working with Databases - Introduction to API - Introduction to Cloud services - Cloud environment Setup- Reading and writing data to cloud - Embedding ML models to Apps - Deploying application. 9 0 0 9 Unit II INDUSTRIAL DESIGN 9 0 0 9 0 0 9 Introduction to Industrial Design - Points, lines, and planes - Sketching and concept generation - Sketch to CAD - Introduction to CAD tools - Types of 3D modeling - Basic 3D Modeling Tools - Part creation - Assembly - Product design and rendering basics - Dimensioning & Tolerancing 9 0 0 9 Need for prototyping - Domains in prototyping - Difference between actual manufacturing and prototyping - Rapid prototyping methods - Tools used in different domains - Mechanical Prototyping: 3DPrinting and classification - Laser Cutting and engraving - RD Works - Additive manufacturing 9 0 0 9 | 3 | Knowle | edge in hardware, 3D Printers and Laser cutters. | | | | | | | | |
| Fundamental concepts in UI & UX - Tools - Fundamentals of design principles - Psychology and Human Factors for User Interface Design - Layout and composition for Web, Mobile and Devices - Typography - Information architecture - Colour theory - Design process flow, wireframes, best practices in the industry -User engagement ethics - Design alternatives Unit II APP DEVELOPMENT 9 0 0 9 SDLC - Introduction to App Development - Types of Apps - web Development - understanding Stack - Frontend - backend - Working with Databases - Introduction to API - Introduction to Cloud services - Cloud environment Setup- Reading and writing data to cloud - Embedding ML models to Apps - Deploying application. 9 0 0 9 Unit II INDUSTRIAL DESIGN 9 0 0 9 Introduction to Industrial Design - Points, lines, and planes - Sketching and concept generation - Sketch to CAD - Introduction to CAD tools - Types of 3D modeling - Basic 3D Modeling Tools - Part creation - Assembly - Product design and rendering basics - Dimensioning & Tolerancing 9 0 0 9 Need for prototyping - Domains in prototyping - Difference between actual manufacturing and prototyping - Rapid prototyping methods - Tools used in different domains - Mechanical Prototyping: 3DPrinting and classification - Laser Cutting and engraving - RD Works - Additive manufacturing 9 0 0 9 Unit IV ELECTRICAL RAPID PROTOTYPING 9 0 | 4 | Acquir | e basic knowledge in designing electrical circuits and fabrication | on of electronic de | vices. | | | | | | |
| Interface Design - Layout and composition for Web, Mobile and Devices - Typography - Information architecture - Colour theory - Design process flow, wireframes, best practices in the industry -User engagement ethics - Design alternatives Unit II APP DEVELOPMENT 9 0 0 9 SDLC - Introduction to App Development - Types of Apps - web Development - understanding Stack - Frontend - backend - Working with Databases - Introduction to API - Introduction to Cloud services - Cloud environment Setup- Reading and writing data to cloud - Embedding ML models to Apps - Deploying application. Unit III INDUSTRIAL DESIGN 9 0 0 9 Introduction to Industrial Design - Points, lines, and planes - Sketching and concept generation - Sketch to CAD - Introduction to CAD tools - Types of 3D modeling - Basic 3D Modeling Tools - Part creation - Assembly - Product design and rendering basics - Dimensioning & Tolerancing Unit IV MECHANICAL RAPID PROTOTYPING 9 0 0 9 Need for prototyping - Domains in prototyping - Difference between actual manufacturing and prototyping - Rapid prototyping methods - Tools used in different domains - Mechanical Prototyping: 3DPrinting and classification - Laser Cutting and engraving - RD Works - Additive manufacturing Unit V ELECTRICAL RAPID PROTOTYPING 9 0 0 9 Electronic Prototyping: Basics of electronic circuit design - lumped circuits - Electronic Prototyping - Working with simulation tool - simple PCB design with EDA Total = 45 Periods | Un | nit I | UI / UX | | 9 | 0 | 0 | 9 | | | |
| SDLC - Introduction to App Development - Types of Apps - web Development - understanding Stack - Frontend - backend - Working with Databases - Introduction to API - Introduction to Cloud services - Cloud environment Setup- Reading and writing data to cloud - Embedding ML models to Apps - Deploying application. Unit III INDUSTRIAL DESIGN 9 0 0 9 Introduction to Industrial Design - Points, lines, and planes - Sketching and concept generation - Sketch to CAD - Introduction to CAD tools - Types of 3D modeling - Basic 3D Modeling Tools - Part creation - Assembly - Product design and rendering basics - Dimensiming & Tolerancing 9 0 0 9 Unit IV MECHANICAL RAPID PROTOTYPING 9 0 0 9 Need for prototyping - Domains in prototyping - Difference between actual manufacturing and prototyping - Rapid prototyping methods - Tools used in different domains - Mechanical Prototyping: 3DPrinting and classification - Laser Cutting and engraving - RD Works - Additive manufacturing 9 0 0 9 Unit V ELECTRICAL RAPID PROTOTYPING 9 0 0 9 Unit V ELECTRICAL RAPID PROTOTYPING 9 0 0 9 Unit V ELECTRICAL RAPID PROTOTYPING 9 0 0 9 Electronic Prototyping: Basics of electronic circuit design - lumped circuits - Electronic Prototyping - Working with simulation tool - s | - Desig | n proces | s flow, wireframes, best practices in the industry -User engage | • • • | gn alteri | natives | 1 | - | | | |
| Introduction to Industrial Design - Points, lines, and planes - Sketching and concept generation - Sketch to CAD - Introduction to CAD tools - Types of 3D modeling - Basic 3D Modeling Tools - Part creation - Assembly - Product design and rendering basics - Dimensioning & Tolerancing Unit IV MECHANICAL RAPID PROTOTYPING 9 0 0 9 Need for prototyping - Domains in prototyping - Difference between actual manufacturing and prototyping - Rapid prototyping methods - Tools used in different domains - Mechanical Prototyping: 3DPrinting and classification - Laser Cutting and engraving - RD Works - Additive manufacturing 9 0 0 9 Unit V ELECTRICAL RAPID PROTOTYPING 9 0 0 9 Electronic Prototyping - Basics of electronic circuit design - lumped circuits - Electronic Prototyping - Working with simulation tool - simple PCB design with EDA 9 0 0 9 Total = 45 Periods | Workir | ng with D | atabases - Introduction to API - Introduction to Cloud services | | | | | | | | |
| to CAD tools - Types of 3D modeling - Basic 3D Modeling Tools - Part creation - Assembly - Product design and rendering basics - Dimensioning & Tolerancing Unit IV MECHANICAL RAPID PROTOTYPING 9 0 0 9 Need for prototyping - Domains in prototyping - Difference between actual manufacturing and prototyping - Rapid prototyping methods - Tools used in different domains - Mechanical Prototyping: 3DPrinting and classification - Laser Cutting and engraving - RD Works - Additive manufacturing 9 0 0 9 Unit V ELECTRICAL RAPID PROTOTYPING 9 0 0 9 Unit V ELECTRICAL RAPID PROTOTYPING 9 0 0 9 Electronic Prototyping: Basics of electronic circuit design - lumped circuits - Electronic Prototyping - Working with simulation tool - simple PCB design with EDA Total = 45 Periods | Uni | t III | INDUSTRIAL DESIGN | | 9 | 0 | 0 | 9 | | | |
| Need for prototyping - Domains in prototyping - Difference between actual manufacturing and prototyping - Rapid prototyping methods - Tools used in different domains - Mechanical Prototyping: 3DPrinting and classification - Laser Cutting and engraving - RD Works - Additive manufacturing Unit V ELECTRICAL RAPID PROTOTYPING 9 0 0 9 Electronic Prototyping: Basics of electronic circuit design - lumped circuits - Electronic Prototyping - Working with simulation tool - simple PCB design with EDA Total = 45 Periods Text Books: Text Books: Electronic Prototyping - Working With State Prototyping - State Prototyping - Working With State Prototyping - State Prototyping - State Prototyping - State Prototyping - Working With State Prototyping - State Prototyping - Working With State Prototyping - State Prototyping - Working With State Prototyping - Working With PCB design With P | to CAL | D tools - T | Гуреs of 3D modeling - Basic 3D Modeling Tools - Part creati | | | | | | | | |
| methods - Tools used in different domains - Mechanical Prototyping: 3DPrinting and classification - Laser Cutting and engraving - RD Works - Additive manufacturing Unit V ELECTRICAL RAPID PROTOTYPING 9 0 0 9 Electronic Prototyping: Basics of electronic circuit design - lumped circuits - Electronic Prototyping - Working with simulation tool - simple PCB design with EDA Total = 45 Periods Text Books: | Uni | it IV | MECHANICAL RAPID PROTOTYPING | | 9 | 0 | 0 | 9 | | | |
| Electronic Prototyping: Basics of electronic circuit design - lumped circuits - Electronic Prototyping - Working with simulation tool - simple PCB design with EDA Total = 45 Periods Text Books: | method | ls - Tools | s used in different domains - Mechanical Prototyping: 3DPrin | | | - | | | | | |
| simulation tool - simple PCB design with EDA Total = 45 Periods Text Books: | Un | it V | ELECTRICAL RAPID PROTOTYPING | | 9 | 0 | 0 | 9 | | | |
| Text Books: | | | | s - Electronic Proto | typing - | Worki | ng with | | | | |
| | | | | | | Tota | l = 45 H | Periods | | | |
| | Теч | t Books | • | | | | | | | | |
| 1 Peter Fiell, Charlotte Fiell, Industrial Design A-Z, TASCHEN America Llc(2003) | | | | | | | | | | | |

2 Samar Malik, Autodesk Fusion 360 - The Master Guide.
 3 Steve Krug, Don't Make Me Think, Revisited: A Common Sense Approach to Web Usability, Pearson, 3rd edition (2014)

| E - R | E - References: | | | | | | | |
|-------|--|--|--|--|--|--|--|--|
| 1 | https://www.adobe.com/products/xd/learn/get-started.html | | | | | | | |
| 2 | https://developer.android.com/guide | | | | | | | |
| 3 | https://help.autodesk.com/view/fusion360/ENU/courses/ | | | | | | | |
| 4 | https://help.prusa3d.com/en/category/prusaslicer_204 | | | | | | | |

| | Course Outcomes: Upon completion of this course, the students will be able to: | | | | | | |
|-----|---|--------------|--|--|--|--|--|
| CO1 | Create quick UI/UX prototypes for customer needs | L6: Creating | | | | | |
| CO2 | Develop web application to test product traction / product feature | L3: Applying | | | | | |
| CO3 | Develop 3D models for prototyping various product ideas | L3: Applying | | | | | |
| CO4 | Built prototypes using Tools and Techniques in a quick iterative methodology | L3: Applying | | | | | |

| СО | P01 | P02 | P03 | P04 | P05 | P06 | P07 | P08 | P09 | P010 | P011 | P012 | PS01 | PS02 | PSO3 |
|-----|------|------|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| C01 | 2 | 2 | 3 | 2 | 3 | 0 | 0 | 0 | 1 | 1 | 0 | 0 | 2 | 1 | 1 |
| C02 | 3 | 3 | 3 | 2 | 3 | 0 | 0 | 0 | 1 | 1 | 0 | 0 | 3 | 2 | 2 |
| CO3 | 3 | 2 | 3 | 2 | 3 | 0 | 0 | 0 | 1 | 1 | 0 | 0 | 3 | 2 | 2 |
| C04 | 3 | 2 | 3 | 2 | 3 | 0 | 0 | 0 | 1 | 1 | 0 | 0 | 3 | 2 | 2 |
| AVG | 2.75 | 2.25 | 3 | 2 | 3 | 0 | 0 | 0 | 1 | 1 | 0 | 0 | 2.75 | 1.75 | 1.75 |

| INDUSTRIAL AUTOMATION 18MEPS16 DATA LIFE CYCLE MANAGEMENT | S | emeste | er | VI | | | | | | |
|---|----------|-----------|-----------|---------|--|--|--|--|--|--|
| PREREQUISITES Category | OE | Cre | edit | 3 | | | | | | |
| | L | ТН | | | | | | | | |
| Hours/Week | 3 | 0 | 0 | 3 | | | | | | |
| Course Learning Objectives | | | | | | | | | | |
| 1 Acquire conceptual knowledge in Industrial Controllers by scaling of on-board devices and embedded board interfacing with various I/O peripherals. | | | | | | | | | | |
| 2 Learn PLC by working on internal features and also interfacing with Sensors and actuate SCADA and standard communication protocols. | rs along | g HMI c | concept | using | | | | | | |
| 3 To work with FPGA boards and RT controllers for reprogrammable embedded application | ons usin | g LabV | IEW | | | | | | | |
| 4 Understand the concepts and design electronics circuits | | | | | | | | | | |
| Unit I INDUSTRIAL CONTROLLERS - I | 9 | 0 | 0 | 9 | | | | | | |
| devices - Module SOM - Interfacing with Input and Output devices - Interfacing protocol based Acquiring and Data Logging from sensors - Interfacing Actuators: Relay, DC Motor, Servo applications. | Motor | - Creat | ting star | ndalone | | | | | | |
| Unit II INDUSTRIAL CONTROLLERS - II | 9 | 0 | 0 | 9 | | | | | | |
| Industrial Controllers - II - PLC - Introduction - Mode of Operation - IEC 61131 Programming lang & sequence control - Instruction set - Scan Time - Timers - Counters - Interfacing with Input/Ou Sensors - Interfacing with Actuators - Interfacing with Human Machine Interface - Commission PLC - SCADA. | itput de | vices - I | nterfaci | ng with | | | | | | |
| Unit III INDUSTRIAL COMMUNICATION PROTOCOLS | 9 | 0 | 0 | 9 | | | | | | |
| Serial Communication Protocols - I2C, SPI - Serial Field bus protocols CAN, PROFIBUS - Eth Cloud data logging. Multi-sensor communication, Data parsing between Embedded platforms. C communication protocols - Implementation of Industrial Communication protocols. | | | | | | | | | | |
| Unit IV FPGA AND RT CONTROLLER PROGRAMMING | 9 | 0 | 0 | 9 | | | | | | |
| Introduction to FPGA - Architecture - Operations in FPGA programming - FPGA Pro- implementation in myRIO - Introduction to RT controllers - Architecture - Programming RT Co- applications. | - | - | | | | | | | | |
| Unit V INDUSTRIAL CIRCUIT BOARD DESIGN | 9 | 0 | 0 | 9 | | | | | | |
| Designing basics circuits and to simulate in environment setup - Component selection - Creating Design rules, supply & communication track rules - Component and footprint editor - Understand - Test point creation for measurement - PCB Layout, placement rules - Footprint, 3D models, Bol | | | | | | | | | | |
| output documentation. | Ms - Ge | - | | e types | | | | | | |

| Tex | t Books: |
|--------|--|
| 1 | Ed Doering, NI myRIO Project Essential Guide, National Instruments, 2016. |
| 2 | Willian Bolton, Programmable Logic Controllers, 6th edition, Newnes Publications, 2015 |
| 3 | Richard Zurawski, Industrial Communication Technology Handbook, Second edition, CRC Press, 2014 |
| 4 | Simon Monk, Make Your Own PCBs with EAGLE, McGraw Hill Education, 2014. |
| Refere | ences Books: |
| 1 | Jeffrey Travis, Jim Kring, LabVIEW for Everyone: Graphical Programming Made Easy and Fun, 3rd edition, Prentice Hall |
| 2 | Mikell P. Groover, Automation, Production Systems, and Computer-integrated Manufacturing, Fourth edition, Pearson Education, 2016 |
| 3 | Michael J. Hamill, Industrial Communications and Control Protocols, PDH centre, 2016 |
| 4 | Ema Design Automation, The Hitchhiker's Guide to PCB Design, First edition, Blurb Publishers, December 2021 |

| | se Outcomes: completion of this course, the students will be able to: | Bloom's Taxonomy Level | | | |
|-----|---|---------------------------|--|--|--|
| CO1 | Understand the usage of controllers in an industrial environment | L2: Understanding | | | |
| CO2 | Build Real-Time systems for Industrial embedded monitoring and controlling deterministic applications | L3: Applying | | | |
| CO3 | Communicate between devices at different levels using industrial protocols | L3: Applying | | | |
| CO4 | Understand the process involved in PCB design using EDA tools and fabricate it | L2: Understanding | | | |

| СО | P01 | P02 | P03 | P04 | P05 | P06 | P07 | P08 | P09 | P010 | P011 | P012 | PS01 | PS02 | PS03 |
|-----|-----|------|------|------|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| C01 | 3 | 2 | 2 | 1 | 3 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 3 | 2 | 2 |
| C02 | 3 | 3 | 3 | 2 | 3 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 3 | 3 | 3 |
| CO3 | 3 | 2 | 3 | 2 | 3 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 3 | 3 | 3 |
| C04 | 3 | 2 | 3 | 2 | 3 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 3 | 3 | 2 |
| AVG | 3 | 2.25 | 2.75 | 1.75 | 3 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 3 | 2.75 | 2.5 |

| 18M | EPS17 | ROBOTICS/ML&MLOps | | S | Semester | | | | | |
|-------|---|--|-----------------------|----------|----------|-----------|----------|--|--|--|
| PRER | REQUIS | ITES | Category | EE | Cre | edit | 3 | | | |
| | | | | L | Т | Р | ТН | | | |
| | | | Hours/Week | 3 | 0 | 0 | 3 | | | |
| Cours | se Learn | ing Objectives | | | | | | | | |
| 1 | Learn t | he fundamentals of ROS | | | | | | | | |
| 2 | 2 Understand the requirements and choose the right sensors and actuators for the application development | | | | | | | | | |
| 3 | Create | Bot in the virtual environment and simulate it to know the fun | ctionalities of the s | ystem d | evelope | d | | | | |
| 4 | 4 Learn the basics of Robotics Vision System | | | | | | | | | |
| 5 | Integra | te ROS and Computer Vision to build systems for various use | cases | | | | | | | |
| Ur | nit I | INTRODUCTION TO ROBOT KINEMATICS | | 9 | 0 | 0 | 9 | | | |
| | | Robotics - Transformations - Forward Kinematics - Kinematic analysis - Numerical Inverse Kinematic Solutions - | | | | | Inverse | | | |
| Un | it II | SELECTION OF SENSORS AND ACTUATORS | | 9 | 0 | 0 | 9 | | | |
| | | ensors & Actuators - Types - Selection criteria - Design consid peed characteristics - Hardware Interface & Assembly | lerations: Motor siz | ing - Se | lection | of motor | rs based | | | |
| Uni | it III | INTRODUCTION TO ROBOT OPERATING SYS | TEM | 9 | 0 | 0 | 9 | | | |
| ROS p | | ROS framework and prerequisites - Understanding communic ing - ROS nodes, topics, messages - ROS services - ROS Too Motion | | | | | | | | |
| Uni | it IV | INTRODUCTION TO ROBOTICS VISION SYST | EM | 9 | 0 | 0 | 9 | | | |
| Gauss | Image basics - Image Processing - Histograms - Gray scale, Color, Equalization - Smoothing and blurring/filtering - Averaging, Gaussian, Median, Bilateral - Thresholding - Simple, Adaptive, Otsu - Gradients and Edge detection - Laplacian, Sobel, Canny - Contours - Camera calibration | | | | | | | | | |
| Un | it V | INTEGRATION OF ROS AND COMPUTER VISI | ON | 9 | 0 | 0 | 9 | | | |
| | iction - Ir orld appli | sstallation - CV Bridge - Image publisher node - Image subscrib cations | oer node - Nodes bu | ilding a | nd laund | ching - E | Building | | | |
| | Total = 45 Periods | | | | | | | | | |

| Tex | xt Books: |
|-----|---|
| 1 | Introduction to Robotics: Mechanics and Control by John J Craig, Pearson Publishers. |
| 2 | Robot Operating System (ROS) for Absolute Beginners by Lentin Joseph, A press; Publishers (2018). |
| 3 | Learning OpenCV by Gary Bradski, Adrian Kaehler, O'Reilly Media, Inc. |

| Refe | erence Books: |
|------|--|
| 1 | https://www.intechopen.com/chapters/379 |
| 2 | https://www.plantengineering.com/articles/eight-selection-criteria-for-actuation-components/ |
| 3 | https://www.controleng.com/articles/tips-on-sensor-selection/ |
| 4 | https://www.toptal.com/robotics/introduction-to-robot-operating-system |
| 5 | https://www.thomasnet.com/articles/automation-electronics/machine-vision-systems/ |
| 6 | https://automaticaddison.com/working-with-ros-and-opencv-in-ros-noetic/ |

| | se Outcomes: completion of this course, the students will be able to: | Bloom's Taxonomy Level |
|-----|--|---------------------------|
| CO1 | Understand kinematics considerations of robot | L2: Understanding |
| CO2 | Selection of sensors and actuators according to application | L3: Applying |
| CO3 | Utilize the ROS environment to simulate and communicate between robot | L3: Applying |
| CO4 | Develop algorithms to extract features and data from image | L3: Applying |
| CO5 | Utilize the open CV for robotic applications | L3: Applying |

| CO | P01 | P02 | P03 | P04 | P05 | P06 | P07 | P08 | P09 | P010 | P011 | P012 | PS01 | PS02 | PS03 |
|-----|-----|-----|------|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| C01 | 3 | 2 | 3 | 1 | 2 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 3 | 3 | 2 |
| C02 | 3 | 3 | 2 | 1 | 2 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 3 | 3 | 3 |
| CO3 | 3 | 2 | 3 | 2 | 3 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 3 | 3 | 3 |
| C04 | 3 | 3 | 3 | 2 | 3 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 3 | 3 | 2 |
| AVG | 3 | 2.5 | 2.75 | 1.5 | 2.5 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 3 | 3 | 2.5 |

PROGRAMME ELECTIVE COURSEVERTICALS FOR HONOURS / MINOR DEGREE

VERTICAL I : POWER ENGINEERING

| 18E | EHO1 | 01 SUBSTATION ENGINEERING AND AU | TOMATION | SEME | STE | R | |
|------------|----------|---|---------------------------|------------|--------|--------|---------|
| PRE | REQU | JISTIES | CATEGORY | PEC | Cre | edit | 3 |
| Dowe | r evetar | n protection, Electrical Measurements, Power system | Hours/Week | L | Т | Р | TH |
| TOWC | i syster | n protection, Electrical Measurements, i ower system | Hours/ week | 3 | 0 | 0 | 3 |
| Cour | se Ob | jectives: | | | | | |
| 1. | | derstand the importance of the substation design | | | | | |
| 2. | | tline the different factor for effecting substation design | | | | | |
| 3. | | assify the bus configurations | | | | | |
| 4. | | ow the design criteria for substation grounding | | | | | |
| 5. | To un | derstand the importance of substation automation | | | | | |
| UNI | ГІ | INTRODUCTION | | 9 | 0 | 0 | 9 |
| | | Need Determination, Budgeting, Financing, Traditional and | innovative Substation I | Design, Si | te Se | lectio | n and |
| | | Design, Construction and Commissioning Process | | 0 | | | |
| UNI | ГΠ | HIGH VOLTAGE SWITCHING EQUIPMENT | | 9 | 0 | 0 | 9 |
| | | ditions, Disconnect switches, Load Break switches, high speed | grounding switches, poy | 1 | • | - | |
| | t break | | 8, F | , | | | , |
| UNI | гш | TYPES OF SUBSTATIONS & BUS/SWITCHING C | ONFIGURATIONS | 9 | 0 | 0 | 9 |
| | | n substation, distribution substation, collector substation, swi | | insulated | subs | | is, air |
| | | ostations, bus configurations: single bus, double bus, double | | | | | |
| | | bus, break-and-a-half, Comparison of configurations. | | | | | U |
| | | | | | | | |
| UNI | | DESIGN OF SUBSTATION GROUNDING AND PR | | 9 | 0 | 0 | 9 |
| | | substation grounding system, accidental ground circuit, Des | | | | | |
| | | rid resistance, grid current, use of the design equations, select | | | | | |
| | | as. Lightning stroke protection-lightning parameters, empirica | al design methods. Subs | tation fir | e prot | ection | n-Fire |
| nazar | us, me | protection measures, fire protection selection criterion. | | | | | |
| UNI | гν | SUBSTATION AUTOMATION AND COMMUNIC. | ATIONS | 9 | 0 | 0 | 9 |
| | | , components of substation automation system, automation | | - | - | - | |
| | | data acquisition (SCADA) historical perspective, SCADA f | | | | | |
| | | s, components of SCADA system, SCADA communication pro | | | | | |
| proto | col, sec | urity for substation communications, security methods, security | assessment. | | | | |
| | | | | | | | |
| | | | Total | (45L+0 | T)= 4 | 5 Pe | riods |
| Text | Books | 5: | | | | | |
| 1. | Joh | n D. McDonald, Electrical Power Substation Engineering, CR | C Press, 3 rd Edition, 20 | 17 | | | |
| Refe | rence | Books: | | | | | |
| 1. | | S. Dahiya, VinayAttri," Sub-Station Engineering Design & lications, 1 st Edition, 2013. | Computer Application | s"SK | Kata | ria a | nd son |
| 2. | | Satnam, P. V. Gupta, "Substation Design and Equipment" D | hananat Rai Publications | 1 st Edit | tion ? | 013 | |
| 3. | | an Gonen, "Electric Power Distribution Engineering "CRC pre- | | , 1 5t Lan | | | |
| | ferenc | | ,, 201 ··· | | | | |
| 1 | | os://www.transgrid.com.au/what-we-do/our-network/connection | 25 | | | | |
| 2 | | s://www.transgrid.com.au/what-we-do/our-network/connection s://new.abb.com/substations | 15 | | | | |
| 4 | Intp | 5.// IIC w. a00. COIII/ Substations | | | | | |

| 3 | https://ieeexplore.ieee.org/document/178016 |
|---|--|
| 4 | https://www.sciencedirect.com/topics/engineering/substations |

| Course O | outo | comes: | Bloom's Taxonomy |
|----------|------|---|-------------------|
| Upon com | plet | ion of this course, the students will be able to: | Mapped |
| CO1 | : | Understand the commissioning of substation | L2: Understanding |
| CO2 | : | Know working principles of substation switching equipment | L2: Understanding |
| CO3 | : | Identify the different types of bus configurations | L1: Remembering |
| CO4 | : | Design substation grounding and protection | L6: Creating |
| CO5 | : | Analyse the substation communication (SCADA) | L4: Analysing |

| COs/ POs | РО 1 | PO 2 | PO 3 | PO 4 | PO 5 | PO 6 | PO 7 | PO 8 | PO 9 | PO 10 | PO 11 | PO 12 | PS O1 | PS O2 | PS O3 |
|-------------|---------|---------|---------|----------------|---------|---------|---------|---------|---------|----------|----------|----------|----------|----------|----------|
| CO1 | 2 | 2 | 3 | 1 | 1 | | 1 | 1 | | | 1 | | 2 | 2 | 1 |
| CO2 | 1 | 2 | 1 | 1 | 1 | | | | | | | | 1 | 1 | 2 |
| CO3 | 1 | 3 | 2 | 2 | 2 | | 1 | 1 | | | | 1 | 1 | 2 | 1 |
| CO4 | 2 | 2 | 3 | 2 | 3 | 2 | | | | | | 1 | 2 | 2 | 1 |
| CO5 | 1 | 2 | 1 | 1 | 3 | 1 | 1 | 1 | | | 1 | 1 | 2 | 2 | 1 |
| Avg | 1.4 | 2.2 | 2 | 1.4 | 2 | 1.5 | 1 | 1 | 0 | 0 | 1 | 1 | 1.6 | 1.8 | 1.2 |

| 18EEHO102 | EMS AND SCADA | SEME | STER | | |
|--|--|---|--|---------------------------------|---|
| PREREQUISI | TES CATEGORY | PEC | | edit | 3 |
| Power System | Hours/Week | | T | P | TH |
| | | 3 | 0 | 0 | 3 |
| Course Objecti | | | | | |
| | knowledge on energy management system. | | | | |
| | and network analysis function of EMS. ne function and control of SCADA. | | | | |
| | the concept of SCADA hardware and software. | | | | |
| | e concept of power system automation using SCADA. | | | | |
| | ΙΕΡΟΥ ΜΑΝΑ Ο ΕΜΕΝΈ ΑνζΈΓΕΜ | 9 | 0 | 0 | 9 |
| | NERGY MANAGEMENT SYSTEM o EMS, Objectives, Evolution of EMS, Evolution (| | ADA, | | nctio |
| | o EMS, Objectives, Evolution of EMS, Evolution of EMS, Evolution of EMS, EMS Architecture, Practical EMS, Working of EMS, | | System | | curity |
| | atic Security Assessment, Operating states of Power System. | | | | Onlin |
| / | trol Function, Protection Function, Operating States of Power System | Real 1 | mic | 01 (| J |
| -pp.ice.com - Com | | | | | |
| UNIT II NI | ETWORK ANALYSIS FUNCTION OF EMS | 9 | 0 | 0 | 9 |
| | on, Extended Real Time Function, State Estimation: Introduction, Conventional | | | | ır |
| | conomic Dispatch and Optimal Power Flow: Introduction, Economic Dispatch, | Generatio | n Mode | el, | |
| Economic Dispate | h Problem, Optimal Power Flow problem Formulation. | | | | |
| | | | 0 | 0 | 0 |
| | CADA | 9 | 0 | 0 | 9 |
| | A SCADA Evolution of SCADA Banafits of S | | Fund | otion | |
| | | CADA, | | ction Moni | |
| SCADA, SCAI | DA in Process control, SCADA Application, Usage of SCADA | , Real-7 | | ction Moni | |
| SCADA, SCAI | | , Real-7 | | | |
| SCADA, SCAI and Control using | DA in Process control, SCADA Application, Usage of SCADA SCADA, Data Acquisition, Data Communication, Data Presentation, and Control | , Real-7 | Гime | Moni | torin |
| SCADA, SCAI and Control using UNIT IV S(| DA in Process control, SCADA Application, Usage of SCADA SCADA, Data Acquisition, Data Communication, Data Presentation, and Controcada CADA HARDWARE AND SOFTWARE | A, Real-7 ol. 9 | Гіте 0 | Moni | 9 |
| SCADA, SCAI and Control using UNIT IV SC ntroduction, | DA in Process control, SCADA Application, Usage of SCADA SCADA, Data Acquisition, Data Communication, Data Presentation, and Control CADA HARDWARE AND SOFTWARE SCADA hardware Functions, Remote | A, Real-7 ol. 9 Termin | Fime 0 nal | Moni | torin 9 Unit |
| SCADA, SCAI and Control using UNIT IV SC Introduction, SCADA RTU, | DA in Process control, SCADA Application, Usage of SCADA SCADA, Data Acquisition, Data Communication, Data Presentation, and Contro CADA HARDWARE AND SOFTWARE SCADA hardware Functions, Remote Basic Functions, RTU Standards, Difference Between RTU | a, Real-7 ol. 9 Termin and PL | Fime 0 nal C, F | Moni 0 eature | torin 9 Unit |
| SCADA, SCAI and Control using UNIT IV SC ntroduction, SCADA RTU, SCADA. SCA | DA in Process control, SCADA Application, Usage of SCADA SCADA, Data Acquisition, Data Communication, Data Presentation, and Contro CADA HARDWARE AND SOFTWARE SCADA hardware Functions, Remote Basic Functions, RTU Standards, Difference Between RTU | a, Real-7 ol. 9 Termin and PL | Fime 0 nal | Moni 0 eature | torin 9 Unit |
| CADA, SCAI nd Control using JNIT IV SC ntroduction, CADA RTU, CADA. SCA Geatures of DNP3 | DA in Process control, SCADA Application, Usage of SCADA SCADA, Data Acquisition, Data Communication, Data Presentation, and Contro CADA HARDWARE AND SOFTWARE SCADA hardware Functions, Remote Basic Functions, RTU Standards, Difference Between RTU DA Software and Protocols: Introduction to ISO Model, I , IEC60870 PROTOCOL, HDLC, Modbus Protocol. | A, Real-7 ol. 9 Termin and PL DNP3 M | Fime 0 nal C, F Iodel, | Moni 0 eature Imp | torin 9 Unit s oorta |
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| Course O |) uto | comes: | Bloom's Taxonomy |
|----------|--------------|---|-------------------|
| Upon com | plet | ion of this course, the students will be able to: | Mapped |
| CO1 | : | Explore the objectives of EMS. | L2: Understanding |
| CO2 | : | Understand the real time function of EMS. | L1: Remembering |
| CO3 | : | Explain the real time monitoring and control of SCADA. | L4: Analyzing |
| CO4 | : | Analyze the hardware and software functions of SCADA. | L4: Analyzing |
| CO5 | : | Outline the power system automation and protection using SCADA. | L2: Understanding |

| COUR | SE AR | TICUI | LATIO | ON MA | TRIX | | | | | | | | | | |
|-------------|---------|---------|---------|----------|---------|----------|----------|---------|---------|----------|----------|----------|----------|----------|----------|
| COs/ POs | PO 1 | PO 2 | PO 3 | PO 4 | PO 5 | PO 6 | PO 7 | PO 8 | PO 9 | PO 10 | PO 11 | PO 12 | PS O1 | PS O2 | PS O3 |
| CO1 | 3 | 1 | | | | | | 1 | | | | | 2 | | 3 |
| CO2 | 3 | | 2 | | | 2 | | | | | | | 2 | | 3 |
| CO3 | 3 | | 2 | | | | | | | | | | 2 | | 3 |
| CO4 | 3 | | 2 | | | | | | | | | | 2 | | 3 |
| CO5 | 3 | | 2 | | | | | | | | | | 2 | | 3 |
| Avg | 3 | 1 | 2 | 0 | 0 | 2 | 0 | 1 | 0 | 0 | 0 | 0 | 2 | 0 | 3 |
| | • | • | 3/2/1-i | ndicates | strengt | h of cor | relation | (3- Hig | h, 2-Me | dium, 1 | - Low) | | | | |

| 18EEHO103 | POWER SYSTEM STATE ESTIMATION AND CONTROL | D SECURITY | SEMI | ESTE | R | |
|---|--|--|--|---|---|---|
| PREREQUIS | | CATEGORY | PEC | Cre | dit | 3 |
| | on, Transmission and Distribution System; Power System | Hours \Week | L | Т | Р | TH |
| Analysis and Sta | bility | Hoursweek | 3 | 0 | 0 | 3 |
| Course Object | tives: | | | | | |
| | e fundamental knowledge on power system state estimation. | | | | | |
| | arise on network observability analysis. onceptual aspects in power system state estimation and s s. | trategies to enhance | e the sec | cure po | ower s | system |
| UNIT I | INTRODUCTION | | | 9 | 0 (|) 9 |
| Concepts of relia | - Energy management system- SCADA system- Energy co ability, security and stability - State transitions and control st DEMS, Power line carrier communication. | | | | | |
| UNIT II | POWER SYSTEM STATE ESTIMATION | | | 9 | 0 (|) 9 |
| | nation: Active and reactive power bus measurements – Line f | flow measurements - | Line cur | - | · · | |
| - Bus voltage n | neasurements - Measurement model and assumptions - We | eighted least square | state est | imatio | n algo | |
| Maximum likelih | hood estimation - Decoupled formulation of WLS state estim | nation- Fast decouple | ed state es | stimati | on. | |
| | | | | | | |
| UNIT III | NETWORK ORSERVARIEITV ANALVSIS | | | 0 | 0 (| |
| | NETWORK OBSERVABILITY ANALYSIS estimation: Algorithm - Computational aspects – Measure Variance of measurement residuals- Detection, identification | | | | varia | |
| Tracking state e measurements - measurements- V phasor measurem | estimation: Algorithm - Computational aspects – Measure Variance of measurement residuals- Detection, identification Virtual measurements- External system equivalencing- Netw | n and suppression of | bad meas | y and sureme | varia ents - l | nce of Pseudo |
| Tracking state e measurements - measurements- V phasor measurem UNIT IV | estimation: Algorithm - Computational aspects – Measure Variance of measurement residuals- Detection, identification Virtual measurements- External system equivalencing- Netw nent units. DISTRIBUTION SYSTEM STATE ESTIMATION | n and suppression of vork observability - (| bad meas Observab | y and sureme ility a | varia ents - l nalysis | nce of Pseudo s using 9 |
| Tracking state e measurements - measurements- V phasor measurem UNIT IV Distribution syst | estimation: Algorithm - Computational aspects – Measure Variance of measurement residuals- Detection, identification Virtual measurements- External system equivalencing- Netw nent units. DISTRIBUTION SYSTEM STATE ESTIMATION rem state estimation- State of the art methods – Comparison | n and suppression of york observability - (<u>N</u> of different DSSE a | bad meas Observab | y and sureme ility a | varia ents - l nalysis | nce of Pseudo s using |
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| Tracking state e measurements - We phasor measurements - We UNIT IV Distribution syst measurement syst UNIT V Contingency ana | estimation: Algorithm - Computational aspects – Measure Variance of measurement residuals- Detection, identification Virtual measurements- External system equivalencing- Netw nent units. DISTRIBUTION SYSTEM STATE ESTIMATION tem state estimation- State of the art methods – Comparison stem and DSSE design- Pseudo measurements- System archi SECURITY ASSESSMENT AND ENHANCEMEN alysis: Linearized AC and DC models of power systems for | n and suppression of york observability - (N of different DSSE a tecture. NT r security assessmen | bad meas Observab Igorithms nt - Line | y and sureme ility and 9 S- Dev 9 outage | varia ents - l nalysis 0 (elopm 0 (e distri | nce of Pseudo susing () 9 ents in () 9 bution |
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| Course (| Dute | comes: | Bloom's Taxonomy |
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| Upon com | plet | ion of this course, the students will be able to: | Mapped |
| CO1 | : | Understand the conceptual aspects in power system state estimation. | L2: Understanding |
| CO2 | : | Demonstrate various state estimation methods. | L3: Applying |
| CO3 | : | Acquire proficiency to perform observability analysis. | L4: Analysing |
| CO4 | : | Demonstrate the distribution state estimation. | L3: Applying |
| CO5 | : | Realize the security assessment and enhancement strategies. | L3: Applying |

| COURS | SE AR | FICUL | ATION | N MAT | RIX | | | | | | | | | | |
|-------------|--|-------|-------|-------|-----|-----|-----|-----|-----|------|------|------|----------|----------|----------|
| COs\ POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO 1 | PSO 2 | PSO 3 |
| CO 1 | 1 | 3 | 3 | 1 | 1 | | 1 | | | | 1 | 2 | 1 | 3 | 1 |
| CO 2 | 1 | 2 | 3 | 2 | 2 | | 2 | | | | 1 | 2 | 1 | 3 | 1 |
| CO 3 | 1 | 2 | 3 | 2 | 2 | | 2 | | | | 1 | 2 | 1 | 2 | 1 |
| CO 4 | 1 | 2 | 2 | 1 | 1 | | 1 | | | | 1 | 2 | 1 | 2 | 1 |
| CO 5 | 1 | 2 | 3 | 2 | 2 | | 2 | | | | 1 | 2 | 1 | 1 | 1 |
| Avg | 1 | 2.2 | 2.8 | 1.6 | 1.6 | 0 | 1.6 | 0 | 0 | 0 | 1 | 2 | 1 | 2.2 | 1 |
| | 3/2/1 – indicates strength of correlation (3- High, 2-Medium, 1-Low) | | | | | | | | | | | | | | |

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|--|---|---|---|--|--|---|---|
| Analysis and Stability Hours/Week 3 0 0 3 Course Objectives: 1 To acquire fundamental knowledge on power system instrumentation. 2 To familiarise on automations in electric power distribution systems. 3 10 < | | | CATEGORY | PEC | Cre | edit | |
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| Course C |)uto | comes: | Bloom's Taxonomy |
|----------|------|---|-------------------|
| Upon com | plet | ion of this course, the students will be able to: | Mapped |
| CO1 | | Understand the conceptual aspects in power system measurements and | L2: Understanding |
| 001 | • | signal transmission techniques. | E2. Onderstanding |
| CO2 | : | Demonstrate various communication technologies for data transmission. | L3: Applying |
| CO3 | : | Acquire proficiency to distribution system instrumentation. | L3: Applying |
| CO4 | : | Demonstrate the automation in power distribution system. | L3: Applying |
| CO5 | : | Conceptualize the smart tools for automation. | L3: Applying |

| COUR | COURSE ARTICULATION MATRIX | | | | | | | | | | | | | | |
|-------------|--|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|----------|----------|----------|
| CO\/ POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO 1 | PSO 2 | PSO 3 |
| CO 1 | 1 | 3 | 3 | 1 | 1 | | 1 | | | | 1 | 2 | 1 | 3 | 1 |
| CO 2 | 1 | 2 | 3 | 2 | 2 | | 2 | | | | 1 | 2 | 1 | 3 | 1 |
| CO 3 | 1 | 2 | 3 | 2 | 2 | | 2 | | | | 1 | 2 | 1 | 2 | 1 |
| CO 4 | 1 | 2 | 2 | 1 | 1 | | 1 | | | | 1 | 2 | 1 | 2 | 1 |
| CO 5 | 1 | 2 | 3 | 2 | 2 | | 2 | | | | 1 | 2 | 1 | 1 | 1 |
| Avg | 1 | 2.2 | 2.8 | 1.6 | 1.6 | 0 | 1.6 | 0 | 0 | 0 | 1 | 2 | 1 | 2.2 | 1 |
| | 3/2/1 – indicates strength of correlation (3- High, 2-Medium, 1-Low) | | | | | | | | | | | | | | |

| 18EEHO105 | POWER PLANT ENGINEERING | r I | SEME | STEI | ł | |
|-----------------------------|--|---|-------------|----------|--------|--------|
| PREREQUISTI | ES | CATEGORY | PEC | Cre | dit | 3 |
| Power Systems | | Hours/Week | L | Т | P | TH |
| Tower bystems | | Hours, week | 3 | 0 | 0 | 3 |
| Course Objectiv | /es: | | | | | |
| The objective of th | is course is to familiarize with operation of various power | plants | | | | |
| | | | - | | | |
| UNIT I | THERMAL POWER PLANT | | 9 | 0 | 0 | 9 |
| | layout- main components- boiler- economizer- air prehe | | | | | |
| | wers- FD and ID fans- Coal handling plant-water treatmen | | | Types | s of b | oilers |
| and theirs characte | ristics- Steam turbines- and their characteristics- governing | g system for therma | stations | | | |
| UNIT II | HYDRO POWER PLANT | | 9 | 0 | 0 | 9 |
| | ations- Selection of site- layout- classification of hydro pla | ants- general arrang | | - | • | |
| | ning system for hydel plant- types of turbines-pumped stor | | | - P | | |
| | 1 | | | | | |
| UNIT III | NUCLEAR POWER PLANT | | 9 | 0 | 0 | 9 |
| | ants - Principles of nuclear energy -Working of Nuclear | | | | | |
| | Reactor (PWR), CANada Deuterium- Uranium reactor (| | | | and L | iquid |
| Metal Cooled Read | ctors - location - advantages and disadvantages of nuclear p | ower plants - React | tor control | l | | |
| | | | | | | |
| UNIT IV | POWER FROM RENEWABLE ENERGY | | 9 | 0 | 0 | 9 |
| | ction and working of Solar Thermal, Solar Photo Voltaic (S | SPV), Wind, Tidal. | Geo Ther | mal. | - | - |
| Fuel Cell power sy | | <i>SI ()</i> , <i>() () () () () () () ()</i> | 000 110 | | 51080 | |
| k | | | | | | |
| UNIT V | POWER PLANT ECONOMICS AND ENVI | RONMENTAL | 9 | 0 | 0 | 9 |
| | HAZARDS | | - | Ŭ | - | - |
| | ver generation -Capital & Operating Cost of different po | | | | | |
| | arison of site selection criteria, relative merits & deme | | | | | |
| | ding Waste Disposal Options for Coal and Nuclear Powe | er Plants- safety me | asures for | r Nuc | lear F | ower |
| plants. | | | | | | |
| | | Т | otal (45L | -4 | 5 Pei | rinds |
| | | | | <u> </u> | | Tous |
| Text Books: | | | | | | |
| 1. Nag. P.K., Po | ower Plant Engineering, 2nd ed., Tata McGraw-Hill, 2002 | | | | | |
| | r, S., Power Plant Engineering, Dhanpat Rai & Sons, 1988 | | | | | |
| | M., "Power plant Technology", McGraw-Hill Book Co, 20 | 002 | | | | |
| Reference Book | s: | | | | | |
| 1. Deshpande.M | I.V, "Elements of Electrical Power station Design", Pitman | , New Delhi,Tata M | IcGraw H | ill, 20 | 08. | |
| | Bhatnagar and Chakrabarti, "A text book on Power Systems | 8 | | | | |
| ² . Engineering" | , Dhanpat Rai and Sons, New Delhi, 1997. | | | | | |

| Course Out | comes: | Bloom's Taxonomy |
|-------------------|--|------------------|
| Upon complet | tion of this course, the students will be able to: | Mapped |
| CO1 | : Recall the construction and principle of working for different power plants. | L1: Remembering |

| CO2 | : | Identify the site requirements and component requirements. | L2: Understanding |
|-----|---|---|-------------------|
| CO3 | : | Analyze the concept governors and their control of power plant. | L4: Analysing |
| CO4 | : | Assess the power plant and its suitability for the environment. | L3: Applying |
| CO5 | : | Interpret the economics involved in design of power plant. | L2: Understanding |

| COUR | SE AR | TICU | LATIO | ON MA | TRIX | | | | | | | | | | |
|-------------|---|---------|---------|----------|----------|----------|-----------|----------|---------|----------|----------|----------|----------|----------|----------|
| COs/ POs | PO 1 | PO 2 | PO 3 | PO 4 | PO 5 | PO 6 | PO 7 | PO 8 | PO 9 | PO 10 | PO 11 | PO 12 | PS O1 | PS O2 | PS O3 |
| CO1 | 3 | | | | | | | | | | | | | | |
| CO2 | CO2 1 2 2 2 2 1 1 2 1 1 | | | | | | | | | | | | | | |
| CO3 | CO3 1 3 2 2 2 1 1 2 1 1 | | | | | | | | | | | | | | 1 |
| CO4 | 1 | 1 | 3 | 3 | 2 | 2 | 1 | | 1 | 1 | | 1 | 2 | 2 | 1 |
| CO5 | CO5 1 1 3 2 2 2 1 1 1 1 1 2 2 1 | | | | | | | | | | | | | | 1 |
| Avg | Avg 1.4 2 2.4 2.2 2 1.4 1 1 1 1 1 2 1.4 1 | | | | | | | | | | | | | | 1 |
| | | | 3/2/1-1 | indicate | s streng | th of co | rrelation | n (3- Hi | gh, 2-M | ledium, | 1- Low |) | | | |

| 18EEHO106 | COMPUTER RELAYING AND WIDE MEASUREMENT SYSTEMS | AREA | SEME | STE | R | | | | | | | | |
|---|---|----------------------|------------|---------|-----------------|------------------|--|--|--|--|--|--|--|
| PREREQUISTI | ES | CATEGORY | PEC | Cre | edit | 3 | | | | | | | |
| Power System Prot | action | Hours/Week | L | Т | P | TH | | | | | | | |
| Fower System Flot | ection | Hours/ week | 3 | 0 | 0 | 3 | | | | | | | |
| Course Objectiv | es: | | | | | | | | | | | | |
| | erent techniques of digital relaying - their constructions, we ction to Wide Area Measurement System and network prot | | pplication | s and | limit | ations | | | | | | | |
| | ction to while Area Measurement System and network pro- | ection. | | | | | | | | | | | |
| UNIT I | INTRODUCTION TO COMPUTER RELAYING | G | 9 | 0 | 0 | 9 | | | | | | | |
| | hitecture - analog-to-digital converters - anti-aliasing filter | | | • | • | | | | | | | | |
| | | 1 | | 1 | J | 0 | | | | | | | |
| UNIT II | RELAYING PRACTICES | | 9 | 0 | 0 | 9 | | | | | | | |
| | otection systems, function of protection system, protection distance relays, pilot relaying, transformer protection, rea | | | | | | | | | | | | |
| UNIT III | MATHEMATICAL BASIS FOR PROTECTIVE RELAYING 9 0 0 9 | | | | | | | | | | | | |
| Fourier series, Wal | sh functions, Fourier transforms, probability and random p | rocess, Kalman filte | ering | | | | | | | | | | |
| | | | - | | | | | | | | | | |
| UNIT IV | SYSTEM RELAYING AND CONTROL | | 9 | 0 | 0 | 9 | | | | | | | |
| | ent Unit - Measurement of frequency and phase – samp nt to state estimation – Monitoring- Control applications | oling clock synchro | nization - | – Apj | plicat | ion of | | | | | | | |
| phasor measuremen | it to state estimation – Monitoring- Control applications | | | | | | | | | | | | |
| UNIT V | WIDE AREA MEASUREMENT SYSTEMS | | 9 | 0 | 0 | 9 | | | | | | | |
| Wide Area Measur security – Monitori | ement Systems (WAMS) architecture – WAMS based pro- ing approach of apparaent impedances towards relay chara- packup zones – Intelligent load shedding – Intelligent isla | cteristics – WAMS | based out | t-of st | labili ep re | ty and laying | | | | | | | |
| | | Te | otal (45L | L) = 4 | 5 Pe | riods | | | | | | | |
| | | | | | | | | | | | | | |
| Text Books: | | | | | | | | | | | | | |
| 1. | Arun G. Phadke, James S. Thorp, Computer Rela Edition,2009. | ying for Power S | Systems, | Wile | ey, S | econd | | | | | | | |
| 2. | Allan Thomas Johns, S.K. Salman, Digital Protection Engineering and Technology, Second Edition, 1995. | on for Power Sys | tems, Th | e Ins | stituti | on of | | | | | | | |
| Reference Books | 5: | | | | | | | | | | | | |
| 1. | A.G. Phadke, J.S. Thorp, Synchronized Phasor Measuren | nents and Their App | olications | , Spri | nger | | | | | | | | |
| 2. | Walter A. Elmore, 'Protective Relaying: Theory and App | lications, CRC Pres | s | | | | | | | | | | |

| Course Out | | | Bloom's Taxonomy |
|--------------|------|---|-------------------|
| Upon complet | tion | of this course, the students will be able to: | Mapped |
| CO1 | : | Understand on protection system schemes, its co-ordination and settings for any general power network. | L2: Understanding |
| CO2 | : | Identify the digital relaying, its fundamentals, attributes and implementation. | L2: Understanding |
| CO3 | : | Analyze the concept synchro-phasor based power system relaying | L4: Analysing |
| CO4 | : | Assess the algorithms and its importance | L3: Applying |
| CO5 | : | Recall the power system monitoring using wide area measurement system | L1: Remembering |

| COUR | SE AR | TICU | LATIO | ON MA | TRIX | | | | | | | | | | |
|---|---|---------|---------|----------|----------|----------|-----------|----------|---------|----------|----------|----------|----------|----------|----------|
| COs/ POs | PO 1 | PO 2 | PO 3 | PO 4 | РО 5 | PO 6 | PO 7 | PO 8 | PO 9 | PO 10 | PO 11 | PO 12 | PS O1 | PS O2 | PS O3 |
| CO1 | 3 | 3 | 2 | 2 | 2 | 1 | 1 | | | | | 1 | 3 | 1 | 1 |
| CO2 | CO2 1 3 2 2 2 1 1 1 2 1 1 | | | | | | | | | | | | | | |
| CO3 | 1 | 3 | 3 | 3 | 3 | 1 | 1 | | | | | 1 | 3 | 2 | 1 |
| CO4 | 3 | 3 | 3 | 3 | 3 | 2 | 1 | | | | | 1 | 3 | 2 | 1 |
| CO5 1 1 3 2 2 2 1 | | | | | | | | | | | | | | 1 | |
| Avg | 1.8 | 2.6 | 2.6 | 2.4 | 2.4 | 1.4 | 1 | 0 | 0 | 0 | 0 | 1 | 2.4 | 1.6 | 1 |
| | | | 3/2/1- | indicate | s streng | th of co | rrelation | n (3- Hi | gh, 2-M | ledium, | 1- Low |) | | | |

| | POWER SYSTEM PLANNING | GAND RELIABILITY | SEME | STE | R | | |
|--|---|---|--|--|--|---|--|
| PREREQUIS | TIES | CATEGORY | PEC | Cr | edit | 3 | |
| Power System | S | | L | Т | Р | TH | |
| | | Horus/Week | 3 | 0 | 0 | 3 | |
| Course Obje | ctives: | | | | | | |
| 1. Understa | and the concepts of power system planning | | | | | | |
| | power system reliability | | | | | | |
| 3. Understa | and generation, transmission and distribution plan | ning and reliability | | | | | |
| UNIT I | INTRODUCTION | | 9 | 0 | 0 | 9 | |
| | bjectives & Factors affecting to System Planning | , Short Term Planning, Medium 7 | | - | - | | |
| | ive Power Planning. | , | | U/ | 0 | | |
| | RELIABILITY | | 9 | 0 | 0 | 9 | |
| UNIT II Paliability Fail | RELIABILITY ure, Concepts of Probability, Evaluation Techniqu | les (i) Markov Process (ii) Decurs | - | • | - | - | |
| | equency and Duration of Long & Short Interruption | | | | Stocila | istic | |
| | | | | | | | |
| | ENERATION PLANNING AND RELIAB urces, Integrated Resource Planning, Genera | | 9 | 0 | 0 | 9 | |
| | biggtives of Transmission Dianning Natwork Dec | RELIABILITY | 9 oint India | | to roc | 9 | |
| for Composite | bjectives of Transmission Planning, Network Rec System Reliability. | | - | es, Da | ata rec | | |
| * | System Reliability. | configuration, System and Load P | oint Indico | | | quire | |
| UNIT V | System Reliability. DISTRIBUTION PLANNING AND R | configuration, System and Load P ELIABILITY | oint Indico | 0 | 0 | quire | |
| UNIT V Radial Networ | System Reliability. | ELIABILITY iques, Interruption Indices, Effect | oint Indico 9 cts of Lat | 0 eral 1 | 0 Distrib | quire 9 putio | |
| UNIT V Radial Networ Protection, Eff Indices, Paralle | System Reliability. DISTRIBUTION PLANNING AND R cs, Network Reconfiguration, Evaluation Techn | configuration, System and Load P ELIABILITY iques, Interruption Indices, Effectree, Effects of Transferring Load | oint Indico 9 cts of Lat ls, Distrib | 0 eral I oution | 0 Distrib Relia | quire | |
| UNIT V Radial Networ Protection, Eff Indices, Paralle | DISTRIBUTION PLANNING AND R ks, Network Reconfiguration, Evaluation Techn ects of Disconnects, Effects of Protection Failure | configuration, System and Load P ELIABILITY iques, Interruption Indices, Effectree, Effects of Transferring Load | oint Indico 9 cts of Lat ls, Distrib | 0 eral I oution | 0 Distrib Relia | quire quire 9 Dutio abilit | |
| UNIT V Radial Networ Protection, Eff Indices, Paralle | DISTRIBUTION PLANNING AND R ks, Network Reconfiguration, Evaluation Techn ects of Disconnects, Effects of Protection Failure | ELIABILITY ELIABILITY iques, Interruption Indices, Effective ire, Effects of Transferring Load led Maintenance, Temporary and | oint Indico 9 cts of Lat ls, Distrib | 0 eral I bution Failu | 0 Distrit Relia re, Bi | quire quire 9 outio abilit ceake | |
| UNIT V Radial Networ Protection, Eff Indices, Paralle Failure. | DISTRIBUTION PLANNING AND R ks, Network Reconfiguration, Evaluation Techn ects of Disconnects, Effects of Protection Failure | ELIABILITY ELIABILITY iques, Interruption Indices, Effective ire, Effects of Transferring Load led Maintenance, Temporary and | 9 cts of Lat ls, Distrib Transient | 0 eral I bution Failu | 0 Distrit Relia re, Bi | quire quire 9 outio abilit ceake | |
| UNIT V Radial Networ Protection, Eff Indices, Paralle Failure. Text Books: | DISTRIBUTION PLANNING AND R ks, Network Reconfiguration, Evaluation Techn ects of Disconnects, Effects of Protection Failu l & Meshed Networks, Bus Bar Failure, Schedul | ELIABILITY iques, Interruption Indices, Effective, Effects of Transferring Load ed Maintenance, Temporary and | 9 cts of Lat ls, Distrib Transient | 0 eral I bution Failu | 0 Distrit Relia re, Bi | quire quire 9 outio abilit ceake | |
| UNIT V Radial Networ Protection, Eff Indices, Paralle Failure. Text Books: 1. R.L. S | DISTRIBUTION PLANNING AND R ks, Network Reconfiguration, Evaluation Techn ects of Disconnects, Effects of Protection Failure | ELIABILITY iques, Interruption Indices, Effective, Effects of Transferring Load led Maintenance, Temporary and To | 9 y ts of Lat ls, Distrib Transient tal (45L+ | 0 eral I bution Failu | 0 Distrit Relia re, Bi | quire quire 9 outio abilit ceake | |
| UNIT V Radial Networ Protection, Eff Indices, Paralle Failure. Text Books: 1. R.L. S 2. Roy B | DISTRIBUTION PLANNING AND R ks, Network Reconfiguration, Evaluation Techn ects of Disconnects, Effects of Protection Failure 1 & Meshed Networks, Bus Bar Failure, Schedul ullivan "Power System Planning", Tata McGraw H | ELIABILITY iques, Interruption Indices, Effective re, Effects of Transferring Load led Maintenance, Temporary and To <u>Hill Publishing Company Ltd.</u> | 9 y ts of Lat ls, Distrib Transient tal (45L+ | 0 eral I bution Failu | 0 Distrit Relia re, Bi | quire quire 9 outio abilit ceake | |
| UNIT V Radial Networ Protection, Eff Indices, Paralle Failure. Text Books: 1. R.L. S 2. Roy B 3. T. W. | DISTRIBUTION PLANNING AND R ks, Network Reconfiguration, Evaluation Techn ects of Disconnects, Effects of Protection Failur 1 & Meshed Networks, Bus Bar Failure, Schedul ullivan "Power System Planning", Tata McGraw H illinton & Ronald N. Allan "Reliability Evaluation Berrie "Electricity Economics & Planning", Peter | ELIABILITY iques, Interruption Indices, Effective re, Effects of Transferring Load led Maintenance, Temporary and To <u>Hill Publishing Company Ltd.</u> | 9 y ts of Lat ls, Distrib Transient tal (45L+ | 0 eral I bution Failu | 0 Distrit Relia re, Bi | quire quire 9 outio abilit ceake | |
| UNIT V Radial Networ Protection, Eff Indices, Paralle Failure. Text Books: 1. R.L. S 2. Roy B 3. T. W. Reference Bo | DISTRIBUTION PLANNING AND R ks, Network Reconfiguration, Evaluation Techn ects of Disconnects, Effects of Protection Failur 1 & Meshed Networks, Bus Bar Failure, Schedul ullivan "Power System Planning", Tata McGraw H illinton & Ronald N. Allan "Reliability Evaluation Berrie "Electricity Economics & Planning", Peter oks: owdhury, Don Koval, "Power Distribution System | ELIABILITY iques, Interruption Indices, Effect re, Effects of Transferring Load ed Maintenance, Temporary and To Hill Publishing Company Ltd. of Power System", Springer Publ Peregrinus Ltd., London. | 9 ets of Lat ls, Distrib Transient otal (45L+ | 0 eral 1 bution Failu 0T)= | 0 Distrib Relia re, Br 45 Pe | 9 putio abiliti reakc | |
| UNIT V Radial Networ Protection, Eff Indices, Paralle Failure. Text Books: 1. R.L. S 2. Roy B 3. T. W. Reference Bo 1. Ali Ch IEEE | DISTRIBUTION PLANNING AND R ks, Network Reconfiguration, Evaluation Techn ects of Disconnects, Effects of Protection Failure 1 & Meshed Networks, Bus Bar Failure, Schedul ullivan "Power System Planning", Tata McGraw H illinton & Ronald N. Allan "Reliability Evaluation Berrie "Electricity Economics & Planning", Peter oks: | ELIABILITY iques, Interruption Indices, Effect re, Effects of Transferring Load led Maintenance, Temporary and To Hill Publishing Company Ltd. of Power System'', Springer Publ Peregrinus Ltd., London. | 9 ets of Lat ls, Distrib Transient otal (45L+ | 0 eral 1 bution Failu 0T)= | 0 Distrib Relia re, Br 45 Pe | guire 9 putio abiliti reakc | |
| UNIT V Radial Networ Protection, Eff Indices, Paralle Failure. Text Books: 1. R.L. S 2. Roy B 3. T. W. Reference Bo 1. Ali Ch IEEE 1 2. Roy B | DISTRIBUTION PLANNING AND R ks, Network Reconfiguration, Evaluation Techn ects of Disconnects, Effects of Protection Failure l & Meshed Networks, Bus Bar Failure, Schedul ullivan "Power System Planning", Tata McGraw H illinton & Ronald N. Allan "Reliability Evaluation Berrie "Electricity Economics & Planning", Peter owdhury, Don Koval, "Power Distribution System Press, 2009. | ELIABILITY iques, Interruption Indices, Effect re, Effects of Transferring Load led Maintenance, Temporary and To Hill Publishing Company Ltd. of Power System'', Springer Publ Peregrinus Ltd., London. | 9 ets of Lat ls, Distrib Transient otal (45L+ | 0 eral 1 bution Failu 0T)= | 0 Distrib Relia re, Br 45 Pe | 9 outio abilit reakce | |
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| Course | Out | comes: | Bloom's Taxonomy |
|---------|-----|---|-------------------|
| Upon co | mpl | etion of this course, the students will be able to: | Mapped |
| CO1 | : | To understand the power system planning | L2: Understanding |
| CO2 | : | To determine the reliability of power system | L1: Applying |

| CO3 | : | to understand the generation planning and reliability of power system | L1: Remembering |
|-----|---|---|-------------------|
| CO4 | : | to understand the transmission planning and reliability of power system | L2: Understanding |
| CO5 | : | to understand the distribution planning and reliability of power system | L1: Remembering |

| COURS | SE ART | TICUL | ATION | MATE | RIX | | | | | | | | | | |
|-------------|--------|-------|--------|----------|----------|----------|-----------|----------|---------|----------|----------|----------|----------|----------|----------|
| COs/ POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO1 0 | PO1 1 | PO1 2 | PSO 1 | PSO 2 | PSO 3 |
| CO1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | | | 1 | | 1 | 1 | 1 |
| CO2 | 1 | 3 | 3 | 3 | 2 | 1 | 2 | 1 | 1 | | 1 | | 1 | 1 | 1 |
| CO3 | 1 | 2 | 2 | 3 | 2 | 1 | 2 | 1 | 1 | | 1 | | 1 | 1 | 1 |
| CO4 | 1 | 3 | 2 | 3 | 2 | 1 | 2 | 1 | 1 | | 1 | | 1 | 1 | 1 |
| CO5 | 1 | 2 | 3 | 3 | 2 | 1 | 2 | 1 | 1 | | 1 | | 1 | 1 | 1 |
| Avg | 1 | 2.2 | 2.2 | 2.6 | 1.8 | 1 | 1.8 | 1 | 1 | 0 | 1 | 0 | 1 | 1 | 1 |
| | | | 3/2/1- | indicate | s streng | th of co | rrelation | n (3- Hi | gh, 2-M | ledium, | 1- Low |) | | | |

| 18EEHO108 | ADVANCED POWER SYSTEM | PROTECTION | SEME | ESTER | | |
|--|--|--|--|---|--|---------------------------------|
| PREREQUISTI | ES | CATEGORY | PEC | Cr | edit | 3 |
| Power systems p | | Hours/Week | L | Т | Р | TH |
| | | Hours/ week | 3 | 0 | 0 | 3 |
| Course Objectiv | es: | | | | | |
| | the concepts of advances in power system protect | ion | | | | |
| | ital protection of power system equipments | | | | | |
| 3. Design of pr | rotection relays | | | | | |
| UNIT I | NUMERICAL PROTECTION | | 9 | 0 | 0 | 9 |
| Introduction - Blo | ck diagram of numerical relay - Sampling theorem | orem - Correlation with a | a reference | ce wave | - Least | Error |
| Squared (LES) tech | nique - Digital filtering and numerical over- Curr | rent protection. | | | | |
| UNIT II | DIGITAL PROTECTION OF TRANSM | ISSION LINE | 9 | 0 | 0 | 9 |
| | ection scheme of transmission line – Distance rela | | | - | _ | - |
| based upon fundam | ental signal - Hardware design - Software design | - Digital protection of EH | | | | |
| upon traveling wav | e phenomenon - New relaying scheme using amp | litude comparison. | | | | |
| UNIT III DIG | ITAL PROTECTION OF SYNCHRONO | US GENERATOR & | | | | |
| | ANSFORMER | | 9 | 0 | 0 | 9 |
| | lts in synchronous generator - Protection sche | | | | | |
| Synchronous Gene Transformer. | erator - Faults in a Transformer - Schemes u | sed for Transformer Pro | tection - | Digital | Protecti | on of |
| Transformer. | | | | | | |
| UNIT IV | DISTANCE AND OVERCURRENT RE | LAY SETTING AND | 9 | 0 | 0 | 9 |
| Directional instant | CO-ORDINATION aneous IDMT over current relay - Directional relation | multi-Zone distance relay | - Distan | ice relav | setting | - Co- |
| | nce relays - Co-ordination of over current relay | | | | | 00 |
| orumation or ulsta | nee relays - co-ordination of over current relay | s - Computer graphics u | ispiay - i | vian-mac | mile mi | erface |
| | ited operation of national power system - Applica | | | vian-ma | | erface |
| subsystem - Integra | ted operation of national power system - Applica | tion of computer graphics. | | | | erface |
| | tted operation of national power system - Applica PC APPLICATIONS FOR DESIGNING | tion of computer graphics. | | | | erface |
| subsystem - Integra UNIT V | ted operation of national power system - Applica | tion of computer graphics. PROTECTIVE | 9 | 0 | 0 | 9 |
| subsystem - Integra UNIT V Types of faults – A Transformation to | PC APPLICATIONS FOR DESIGNING RELAYING SCHEME Assumptions - Development of algorithm for SC component quantities - SC studies of multiphas | tion of computer graphics. PROTECTIVE studies - PC based integ | 9 grated sof | 0 Tware fo | 0 or SC stu | 9 dies - |
| subsystem - Integra UNIT V Types of faults - 4 | PC APPLICATIONS FOR DESIGNING RELAYING SCHEME Assumptions - Development of algorithm for SC component quantities - SC studies of multiphas | tion of computer graphics. PROTECTIVE studies - PC based integ | 9 grated sof | 0 Tware fo | 0 or SC stu | 9 dies - |
| subsystem - Integra UNIT V Types of faults – A Transformation to | PC APPLICATIONS FOR DESIGNING RELAYING SCHEME Assumptions - Development of algorithm for SC component quantities - SC studies of multiphas | tion of computer graphics. PROTECTIVE studies - PC based integ | 9 grated sof peed pro | 0 Tware fo | 0 r SC stu elays for | 9 Idies - r high |
| subsystem - Integra UNIT V Types of faults - A Transformation to | PC APPLICATIONS FOR DESIGNING RELAYING SCHEME Assumptions - Development of algorithm for SC component quantities - SC studies of multiphas | tion of computer graphics. PROTECTIVE studies - PC based integ | 9 grated sof peed pro | 0 Tware fo tective r | 0 r SC stu elays for | 9 Idies - r high |
| subsystem - Integra UNIT V Types of faults - A Transformation to | PC APPLICATIONS FOR DESIGNING RELAYING SCHEME Assumptions - Development of algorithm for SC component quantities - SC studies of multiphas | tion of computer graphics. PROTECTIVE studies - PC based integ | 9 grated sof peed pro | 0 Tware fo tective r | 0 r SC stu elays for | 9 Idies - r high |
| subsystem - Integra UNIT V Types of faults – A Transformation to voltage long transm Text Books: | Application of national power system - Application of national power system - Application of App | tion of computer graphics. PROTECTIVE 2 studies - PC based integ se systems - Ultra high s | 9 grated sof peed pro | 0 tective r (45L+01 | 0 or SC stue elays for C)= 45 Pe | 9 Idies - r high |
| subsystem - Integra UNIT V Types of faults - A Transformation to voltage long transm Text Books: 1. L. P. Singi Internation | Application of national power system - Application of national power system - Application of a provide the system - Application - Applicatio | tion of computer graphics. PROTECTIVE C studies - PC based integraphics se systems - Ultra high s Electromechanical to Micro | 9 grated sof peed pro Total (| 0 itware fo tective r (45L+01 | 0 or SC stue elays for C)= 45 Pe | 9 Idies - r high |
| subsystem - Integra UNIT V Types of faults - A Transformation to voltage long transm Text Books: 1. L. P. Singlinternation 2. S. R. Bhid | h, "Digital Protection - Protective Relaying from I hal Ltd., New Delhi, Second Edition, 2006 e, "Digital Power System Protection", Prentice H | tion of computer graphics. PROTECTIVE Studies - PC based integ se systems - Ultra high s Electromechanical to Micr all of India Pvt. Ltd., New | 9 grated soft peed pro Total (roprocessor | 0 ftware fo tective r (45L+01 or", New 014 | 0 or SC stu elays for ()= 45 Pe Age | 9 dies - r high eriods |
| subsystem - Integra UNIT V Types of faults - A Transformation to voltage long transm Text Books: 1. L. P. Singl Internation 2. S. R. Bhid Paithankan | Application of national power system - Application of national power system - Application of a provide the system - Application - Applicatio | tion of computer graphics. PROTECTIVE Studies - PC based integ se systems - Ultra high s Electromechanical to Micr all of India Pvt. Ltd., New | 9 grated soft peed pro Total (roprocessor | 0 ftware fo tective r (45L+01 or", New 014 | 0 or SC stu elays for ()= 45 Pe Age | 9 dies - r high eriods |
| subsystem - Integra UNIT V Types of faults – A Transformation to voltage long transn Text Books: 1. L. P. Singl Internation 2. S. R. Bhid Paithankan | Application of national power system - Application of national power system - Application of an application of a system - Application of a system of a | tion of computer graphics. PROTECTIVE Studies - PC based integ se systems - Ultra high s Electromechanical to Micr all of India Pvt. Ltd., New | 9 grated soft peed pro Total (roprocessor | 0 ftware fo tective r (45L+01 or", New 014 | 0 or SC stu elays for ()= 45 Pe Age | 9 dies - r high eriods |
| subsystem - Integra UNIT V Types of faults - A Transformation to voltage long transm Text Books: 1. L. P. Singl Internation 2. S. R. Bhid 3. Paithankan second edi Reference Books | Application of national power system - Application of national power system - Application of an application of a system - Application of a system of a | tion of computer graphics. PROTECTIVE Studies - PC based integrates se systems - Ultra high s Electromechanical to Micra all of India Pvt. Ltd., New Protection", Prentice Hall | 9 grated soft peed pro Total (roprocessor | 0 ftware fo tective r (45L+01 or", New 014 | 0 or SC stu elays for ()= 45 Pe Age | 9 dies - r high eriods |
| subsystem - Integra UNIT V Types of faults - A Transformation to voltage long transm Text Books: 1. L. P. Singl Internation 2. S. R. Bhid 3. Paithankan second edi Reference Books 1. Paithankan | Application of national power system - Application of national power system - Application of an application of a system - Application of a system of a system of a system for some of a system for some of a system of a syste | tion of computer graphics. PROTECTIVE Studies - PC based integ se systems - Ultra high s Electromechanical to Micr all of India Pvt. Ltd., New rotection", Prentice Hall Dekker, New York, 1998 | 9 grated sof peed pro Total (Total (Delhi, 2(of India | 0 ftware fo tective r (45L+01 or", New 014 | 0 or SC stu elays for ()= 45 Pe Age | 9 dies - r high eriods |
| subsystem - Integra UNIT V Types of faults – A Transformation to voltage long transmotion to voltage long transmotion Text Books: 1. L. P. Single Internation 2. S. R. Bhid 3. Paithankar second edit Reference Books: 1. Paithankar second edit | Application of national power system - Application of national power system - Application of an application of a system - Application of a system of a system for second power of a system for second power of a system of a s | tion of computer graphics. PROTECTIVE Studies - PC based integ se systems - Ultra high s Electromechanical to Micr all of India Pvt. Ltd., New rotection", Prentice Hall Dekker, New York, 1998 | 9 grated sof peed pro Total (Total (Delhi, 2(of India | 0 ftware fo tective r (45L+01 or", New 014 | 0 or SC stu elays for ()= 45 Pe Age | 9 dies - r high eriods |

| | Course Outcomes: Upon completion of this course, the students will be able to: | | | | | | |
|--|--|---|---------------|--|--|--|--|
| | Mapped | | | | | | |
| CO1 : To understand the numeric protection L2: Understandi | | | | | | | |
| CO2 | : | To design the digital protection of transmission line | L1: Applying | | | | |
| CO3 | : | To design the digital protection of synchronous generator | L4: Analysing | | | | |
| CO4 | | | | | | | |
| CO5 | | | | | | | |

| COs/ POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO1 0 | PO1 1 | PO1 2 | PSO 1 | PSO 2 | PSO 3 |
|-------------|-----|-----|-----|-----|-----|-----|-----|-----|-----|----------|----------|----------|----------|----------|----------|
| CO1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | | | 1 | | 1 | 1 | 1 |
| CO2 | 1 | 3 | 3 | 2 | 2 | 1 | 2 | 1 | 1 | | 1 | | 1 | 1 | 1 |
| CO3 | 1 | 2 | 2 | 2 | 2 | 1 | 2 | 1 | 1 | | 1 | | 1 | 1 | 1 |
| CO4 | 1 | 3 | 2 | 2 | 2 | 1 | 2 | 1 | 1 | | 1 | | 1 | 1 | 1 |
| CO5 | 1 | 2 | 3 | 2 | 2 | 1 | 2 | 1 | 1 | | 1 | | 1 | 1 | 1 |
| Avg | 1 | 2.2 | 2.2 | 1.8 | 1.8 | 1 | 1.8 | 1 | 1 | 0 | 1 | 0 | 1 | 1 | 1 |

| 18EEHO109 | HIGH VOLTAGE INSULATION SY | <u>'STEMS</u> | SEMES | STER | | |
|------------------------|--|------------------------|--|--------------------|---------|-------|
| PREREQUISTI | ES | CATEGORY | PEC | Cre | edit | C |
| High voltage Engin | neering, Measurements and Instrumentation | Hound | L | Т | Р | TI |
| | | Hours\Week | 3 | 0 | 0 | 3 |
| Course Objectiv | es: | | | | | |
| | he various types of insulating materials used for power sy | stem equipment | | | | |
| | e the concept of insulation design. | | | | | |
| | an overview of insulation defects in power system equipn | nent | | | | |
| 4. To understa | nd insulation condition monitoring techniques. | | | | | |
| UNIT I | INSULATING MATERIALS | | 9 | 0 | 0 | 9 |
| | al insulating materials, characterization of insulation of | condition models of | - | | - | - |
| practical insulating | materials, electrical breakdown and operating stresses, d | evelopment of insulati | ion applica | tions | | |
| UNIT II | ELECTRICAL INSULATION DESIGN CONC | CEPTS | 9 | 0 | 0 | 9 |
| | tion design requirements - electrical stress distribution in | | tem – elect | tric stre | ess co | ntro |
| Principles of stress | control, Stress distribution in multiple dielectrics, Stress | calculation. | | | | |
| | | | 0 | | | |
| | ULATION DEFECTS IN HV POWER SYSTEM | | 9 | 0 | 0 | 9 |
| | V bushings - HV power capacitors - HV surge arresters | – HV circuit breakers | , HV Cabl | es - G | as Ins | ulate |
| system – HV Trans | sformers - HV instrument transformers. | | | | | |
| UNIT IV | BASIC METHODS FOR INSULATION ASSE | SSMENT | 9 | 0 | 0 | 9 |
| Generation and me | asurement of test high voltages - Non-destructive electric | cal measurements: Ins | ulation Rea | sistanc | e, die | lectr |
| dissipation factor, | partial discharges, dielectric response – Physical and cher | nical diagnostic metho | ods. | | | |
| | ON THE INCLUSATION CONDITION MONIT | | | | | |
| UNIT V | ONLINE INSULATION CONDITION MONIT TECHNIQUES | ORING | 9 | 0 | 0 | 9 |
| Main problem with | Offline condition monitoring - Noise-mitigation technic | ues - Non-electrical c | nline cond | lition r | nonite | ring |
| | ctric PD location methods for transformers - Electrical or | | | | nonnu | ning |
| Olimie deoustie/ele | Serie 1 D Tocutori metriodis for transformers - Dicetteur of | | ,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,, | | | |
| | | Tot | tal (45L+ | \mathbf{OT})= 4 | 45 Pe | riod |
| | | | ` | , | | |
| Text Books: | | | | | | |
| | es and Q. Su, "Condition Assessment of High Voltage Ins | sulation in Power Syst | em Equipn | nent", | IET p | owe |
| and Energ | y Series Publisher, London, United Kingdom, 2008. | | | | | |
| Reference Book | 5: | | | | | |
| | nd and Hermann Kärner (1985). High-Voltage Insulation | | | | | |
| 2. Ravindra Publishers | Arora & Wolfgang Mosch, "High Voltage and Electrical | Insulation Engineering | g", John W | 'iley& | Sons | |
| | W.S. Zaengl, and J.Kuffel, 'High Voltage Engineering Fu | indamentals' Newness | s Publisher | s. Sec | ond | |
| | lsevier, New Delhi, 2005. | | | , | 5114 | |
| | | | | | | |
| 0 0 1 | | | • • | | 1.5 | |
| Course Outcom | P65. | I Blo | oom's Tax | onomy | ⊭ เ∨เลา | med |

| Course | Ou | tcomes: | Bloom's Taxonomy Mapped |
|----------|------|--|--------------------------------|
| Upon con | nple | etion of this course, the students will be able to: | |
| CO1 | : | Know the various insulating materials. | L2: Understanding |
| CO2 | : | Understand the concepts of insulation design for power system equipment. | L2: Understanding |
| CO3 | : | Analyze insulation defects in high voltage power system equipment | L4: Analyzing |
| CO4 | : | Recite the basic methods for insulation assessment | L1: Remembering |
| CO5 | : | Apply online insulation condition monitoring techniques | L3: Applying |

| COUR | SE AR | RTICU | LATIO | ON MA | ATRIX | | | | | | | | | | |
|-------------|---------|---------|---------|----------|------------|---------|-----------|-----------|----------|----------|----------|----------|----------|----------|----------|
| COs/ POs | PO 1 | PO 2 | PO 3 | PO 4 | РО 5 | PO 6 | PO 7 | PO 8 | PO 9 | PO 10 | РО 11 | PO 12 | PS O1 | PS O2 | PS O3 |
| CO1 | 2 | | | 1 | | | 1 | | | | | | 1 | 1 | |
| CO2 | 2 | 1 | 3 | 1 | 1 | | 1 | | | | | | 3 | 2 | |
| CO3 | 2 | | | 3 | 2 | 1 | 1 | | | | | | 1 | 3 | |
| CO4 | 2 | 1 | 1 | 3 | | 1 | | | | | | 1 | 2 | 3 | 1 |
| CO5 | 2 | 1 | 1 | 3 | 2 | | 1 | | | | | 1 | 2 | 3 | 1 |
| Avg | 2 | 1 | 1.6 | 2.2 | 1.6 | 1 | 1 | 0 | 0 | 0 | 0 | 1 | 1.8 | 2.4 | 1 |
| | | | 3/2/ | 1-indica | ites strei | ngth of | correlati | ion (3- 1 | High, 2- | Mediur | n, 1- Lo | ow) | | | |

| PREREQ | | ACTION ENGINEERING | | SEMI | 1 | | - |
|--|---|--|--|--|--|---|--|
| | UISITES | | CATEGORY | PEC | Cre | 1 | 3 |
| Power Elec | tronics, Electrical Machines | | Hours/Week | L | T | P | TH |
| | | | | 3 | 0 | 0 | 3 |
| | bjectives: | | •• • • | 1 1 | | | |
| | earn the fundamentals of electric gn, construction and operation | traction, power substation, distr | ribution system and o | overhead | contac | et syst | em |
| | | ver supply systems and role of ba | attery banks and main | ntenance | | | |
| | earn the traction motor drives an | | | | | | |
| | earn about traction power supply | and protection | | | | | |
| 5. 101 | earn about railway signalling | | | | | | |
| UNIT I | INTRODUCTION TO E | LECTRIC TRACTION | | 9 | 0 | 0 | 9 |
| Requireme | nts of Ideal Traction Systems, th | e Indian Scenario of Electric tra | action, Present day S | tate of an | t Elec | tric tr | actio |
| | | es of Electric Traction over othe | | | | | |
| | | e Traction, DC systems, Single | | | | | |
| | ks in Traction, types and mainte | phase with special reference to | locomotives, EMUs | and Met | ro sto | ck, R | ole o |
| Dattery Dat | ks in Traction, types and manie | nance. | | | | | |
| UNIT II | TRACTION MECHANI | CS | | 9 | 0 | 0 | 9 |
| Requireme | | e Indian Scenario of Electric tra | action, Present day S | tate of a | t Elec | tric tr | action |
| | | es of Electric Traction over othe | | | | | |
| | | e Traction, DC systems, Single | | | | | |
| | | phase with special reference to | locomotives, EMUs | and Met | ro sto | ck, R | ole o |
| Battery dai | ks in Traction, types and mainte | nance. | | | | | |
| UNIT III | TRACTION MOTOR A | | | 9 | 0 | 0 | 9 |
| duties, spe of design a Drive Rati based Con | d control methods, Braking me nd construction features for imp ngs, Important Features of Trac verter Controlled Drives, DC Trac ction control of DC locomotive | ction duties, Available motor c thods, special Emphasis and tec roved power to weight ratio, Por etion Drives, conventional DC a raction using Chopper Controlle s and EMU's, Traction control s | chniques of regenera wer Factor and Harn and AC Traction dri ed Drives, AC Tract system of AC locomo | tive brak nonics, T ves, Sen ion empl otives, Co | ing, O ractive nicond oying ontrol | ptimi Effo uctor/ Poly- gear, | zation rt and IGBT -phas |
| | nduction motors, Power & am oduction to Maglev Technology | p; Auxiliary circuit equipment (| | | | ir ma | |
| motors, int | oduction to Maglev Technology | | | 0 | 0 | | uctio |
| motors, int UNIT IV | oduction to Maglev Technology POWER SUPPLY AND | PROTECTION | aquinment at tractio | 9 a substati | 0 | 0 | uction 9 |
| motors, int UNIT IV Traction su sizing of n lines, surge posts, Boo Train light Design req insulator, | POWER SUPPLY AND bstation, spacing and location ajor equipment like transformer protection, maximum demand a ter transformers, Return Condu ng and Air-conditioning. uirement of catenary wire, cont | PROTECTION of Traction substations, Major et and Switchgear, Types of prote and load sharing between substat ctor, 2X25KV AC system, cont act wire, Dropper, Height, span of current collection (overhead | ection provided for tions, sectionalizing trolling/monitoring, in length, Automatic | n substati Transforn parallelir Railway weight te | ion, se ner an ig post SCAD ensioni | 0 election and the over the and the over the o | 9 9 on and orhead feede stems |
| motors, int UNIT IV Traction su sizing of n lines, surge posts, Boo Train light Design req insulator, overhead c | POWER SUPPLY AND bstation, spacing and location ajor equipment like transformer protection, maximum demand a ter transformers, Return Condu ng and Air-conditioning. uirement of catenary wire, cont worlap, Different techniques of cossing of power lines, Protectio | PROTECTION of Traction substations, Major et and Switchgear, Types of prote and load sharing between substat ctor, 2X25KV AC system, cont act wire, Dropper, Height, span of current collection (overhead n | ection provided for tions, sectionalizing trolling/monitoring, in length, Automatic | n substat: Transforr parallelir Railway weight te systems) | ion, se ner an ig post SCAD ensioni | 0 election ad over t and t PA system ing, se | 9 on and orhead feede stems ection |
| motors, int UNIT IV Traction su sizing of n lines, surge posts, Boo Train light Design req insulator, overhead c UNIT V | oduction to Maglev Technology POWER SUPPLY AND bstation, spacing and location ajor equipment like transformers protection, maximum demand a ter transformers, Return Conduing and Air-conditioning. uirement of catenary wire, controverlap, Different techniques of cossing of power lines, Protection RAILWAY SIGNALING | PROTECTION of Traction substations, Major et and Switchgear, Types of prote and load sharing between substat ctor, 2X25KV AC system, cont act wire, Dropper, Height, span of current collection (overhead n | ection provided for tions, sectionalizing trolling/monitoring, a length, Automatic and underground | n substat: Transforn parallelir Railway weight te systems). | ion, se ner an ng post SCAD ension , neut | 0 election ad over t and t DA system ing, se ral se 0 | 9 on and erhead feede stems ection ection 9 |
| motors, int UNIT IV Traction su sizing of n lines, surge posts, Boo Train light Design req insulator, overhead c UNIT V Block Sect | oduction to Maglev Technology POWER SUPPLY AND bstation, spacing and location ajor equipment like transformer ajor equipment like transformer protection, maximum demand a ter transformers, Return Condu ng and Air-conditioning. uirement of catenary wire, cont voerlap, Different techniques or cossing of power lines, Protection RAILWAY SIGNALING on Concept, AC/DC Track Circle | PROTECTION of Traction substations, Major et and Switchgear, Types of prote and load sharing between substat ctor, 2X25KV AC system, cont act wire, Dropper, Height, span of current collection (overhead n | ection provided for tions, sectionalizing trolling/monitoring, in a length, Automatic and underground n speed and signalin | n substat: Transforn parallelir Railway weight te systems) 9 g, Solid s | ion, se ner an ag post SCAD ensioni , neut 0 | 0 election d over t and t oA system ing, se ral se 0 nterlo | 9 on and or head feede stems ection ection 9 cking |
| motors, int UNIT IV Traction su sizing of n lines, surge posts, Boo Train light Design req insulator, overhead c UNIT V Block Sect Automatic | oduction to Maglev Technology POWER SUPPLY AND bstation, spacing and location ajor equipment like transformer protection, maximum demand a ter transformers, Return Conduing and Air-conditioning. uirement of catenary wire, controverlap, Different techniques or cossing of power lines, Protectio RAILWAY SIGNALING on Concept, AC/DC Track Circ Warning Systems, CAB signali | PROTECTION of Traction substations, Major et and Switchgear, Types of prote and load sharing between substat ctor, 2X25KV AC system, cont act wire, Dropper, Height, span of current collection (overhead n | ection provided for tions, sectionalizing trolling/monitoring, a length, Automatic and underground n speed and signalin ermissible limit of E | n substat: Transforn parallelir Railway weight ta systems) 9 g, Solid s MI and H | ion, se ner an ag post SCAD ensioni , neut 0 | 0 election d over t and t oA system ing, se ral se 0 nterlo | 9 on and or head feede stems ection ection 9 cking |
| motors, int UNIT IV Traction su sizing of n lines, surge posts, Boo Train light Design req insulator, overhead c UNIT V Block Sect Automatic | oduction to Maglev Technology POWER SUPPLY AND bstation, spacing and location ajor equipment like transformer protection, maximum demand a ter transformers, Return Conduing and Air-conditioning. uirement of catenary wire, controverlap, Different techniques or cossing of power lines, Protectio RAILWAY SIGNALING on Concept, AC/DC Track Circ Warning Systems, CAB signali | PROTECTION of Traction substations, Major et and Switchgear, Types of prote and load sharing between substat ctor, 2X25KV AC system, cont act wire, Dropper, Height, span of current collection (overhead n | ection provided for tions, sectionalizing trolling/monitoring, i a length, Automatic and underground n speed and signalin ermissible limit of E 1g, Electrostatic indu | n substat: Transforn parallelir Railway weight ta systems) 9 g, Solid s MI and H | ion, se mer an ng post SCAD ensionit neut neut 0 State In EMC, | 0 election and to A system ing, series ral series nterloop Permi | 9 n and crhead feede stems ection ction 9 cking |
| motors, int UNIT IV Traction su sizing of n lines, surge posts, Boo Train light Design req insulator, overhead c UNIT V Block Sect Automatic capacitivel | POWER SUPPLY AND bstation, spacing and location ajor equipment like transformer protection, maximum demand a ter transformers, Return Conduing and Air-conditioning. uirement of catenary wire, controverlap, Different techniques or cossing of power lines, Protectio RAILWAY SIGNALING on Concept, AC/DC Track Circ Warning Systems, CAB signalize | PROTECTION of Traction substations, Major et and Switchgear, Types of prote and load sharing between substat ctor, 2X25KV AC system, cont act wire, Dropper, Height, span of current collection (overhead n | ection provided for tions, sectionalizing trolling/monitoring, i a length, Automatic and underground n speed and signalin ermissible limit of E 1g, Electrostatic indu | n substat: Transforr parallelir Railway weight te systems) g, Solid s MI and F ction. | ion, se mer an ng post SCAD ensionit neut neut 0 State In EMC, | 0 election and to A system ing, series ral series nterloop Permi | 9 n an arrhead feede ectio cctior 9 cking ssibl |
| motors, int UNIT IV Traction su sizing of n lines, surge posts, Boo Train light Design req insulator, overhead c UNIT V Block Sect Automatic capacitivel Reference | POWER SUPPLY AND bstation, spacing and location ajor equipment like transformer protection, maximum demand a ter transformers, Return Condu ng and Air-conditioning. uirement of catenary wire, cont werlap, Different techniques of ossing of power lines, Protectio RAILWAY SIGNALING on Concept, AC/DC Track Circ Warning Systems, CAB signality -coupled current, Coupling between Books: | PROTECTION of Traction substations, Major et and Switchgear, Types of prote and load sharing between substat ctor, 2X25KV AC system, cont act wire, Dropper, Height, span of current collection (overhead n | ection provided for tions, sectionalizing trolling/monitoring, a length, Automatic and underground n speed and signalin ermissible limit of E ng, Electrostatic indu Total | substat: Transform parallelin Railway weight te systems) 9 g, Solid s MI and H ction. (45L+0 | 0 0 0 $\mathbf{T} = 4$ | 0 election and to A system ing, series ral series nterloop Permi | 9 n an feede stem: ectio cctior g cking ssibl |

| 2. | Douglas W. Hinde, M. Hinde, "Electric Traction Systems and Equipment", Elsevier Science & Technology, 1968 |
|----|---|
| 3. | Samuel Sheldon, Erich Hausmann, "Electric Traction and Transmission Engineering", Van Nostrand, 1911 |
| 4. | Frederick William Carter, "Railway Electric Traction", E. Arnold & Company, 1922 |
| 5. | Edward Parris Burch, "Electric traction for railway trains; a book for students, electrical and mechanical engineers, |
| 5. | superintendents of motive power and others", New York, McGraw-Hill Book Company |
| 6. | Edward Trevert, "Electric Railway Engineering", Lynn, Mass. : Bubier Pub. Co. |
| 7 | Burch Edward Parris, "Electric Traction for Railway Trains; a Book for Students, Electrical and Mechanical |
| 7. | Engineers, Superintendents of Motive Power and Others", Arkose Press, ISBN: 9781345582376, 9781345582376 |

| Course O | outo | comes: | Bloom's Taxonomy | | | |
|----------|--|---|-------------------|--|--|--|
| Upon com | plet | ion of this course, the students will be able to: | Mapped | | | |
| CO1 | CO1 : To understand the basics of traction and supply systems. | | | | | |
| CO2 | : | To understand the traction mechanics and ideal choice of supply systems. | L4: Analyzing | | | |
| CO3 | : | To describe the concepts of traction motors and applying the solid state drive control. | L3: Applying | | | |
| CO4 | : | To design the protection system for the traction power supply system | L5: Evaluating | | | |
| CO5 | : | To understand the concepts of railway signaling | L2: Understanding | | | |

| COUR | SE AR | TICU | LATIO | ON MA | TRIX | | | 1 | | • | | 1 | 1 | 1 | 1 |
|-------------|---|---------|---------|---------|---------|---------|---------|---------|---------|----------|----------|----------|----------|----------|----------|
| COs/ POs | PO 1 | РО 2 | РО 3 | PO 4 | РО 5 | PO 6 | РО 7 | PO 8 | PO 9 | PO 10 | РО 11 | PO 12 | PS O1 | PS O2 | PS O3 |
| CO1 | 3 | 2 | 3 | 2 | 2 | 3 | 2 | 1 | | | | 1 | 3 | 2 | 3 |
| CO2 | 3 | 2 | 3 | 2 | 2 | 3 | 2 | 1 | | | | 1 | 3 | 2 | 3 |
| CO3 | 3 | 2 | 3 | 2 | 2 | 3 | 2 | 1 | | | | 1 | 3 | 2 | 3 |
| CO4 | 3 | 2 | 3 | 2 | 2 | 3 | 2 | 2 | 1 | 1 | 2 | 1 | 3 | 2 | 3 |
| CO5 | 3 | 2 | 3 | 2 | 2 | 3 | 2 | 3 | 1 | 1 | 2 | 1 | 3 | 3 | 3 |
| Avg | 3 | 2 | 3 | 2 | 2 | 3 | 2 | 1.6 | 1 | 1 | 2 | 1 | 3 | 2.2 | 3 |
| | 3/2/1-indicates strength of correlation (3- High, 2-Medium, 1- Low) | | | | | | | | | | | | | | |

PROGRAMME ELECTIVE COURSE VERTICALS FOR HONOURS / MINOR DEGREE

VERTICAL II : POWER CONVERTERS AND DRIVES

| 18EEHO201 ANALYSIS OF ELECTRICAL MAC | HINES | SEMES | TER | | |
|---|-----------------------|--------------|------------------|------------|--------------|
| PREREQUISITES | CATEGORY | PEC | Cre | edit | 3 |
| | Hours/Week | L | Т | Р | TH |
| DC Machines, Synchronous and Induction Machines | 110urs/ week | 2 | 0 | 2 | 4 |
| Course Objectives: | | | | | |
| 1. To model & simulate all types of DC machines | | | | | |
| 2. To develop reference frame equations for various elements like R, L and | | | | | |
| To model an induction (three phase and 'n' phase) and synchronous mac To drive reference frame equations for induction and synchronous maching | | | | | |
| 5. To study the need and working of multiphase induction and synchronous | | | | | |
| | | | | I . | |
| UNIT I MODELING OF BRUSHED-DC ELECTRIC MACHINE | | 6 | 0 | 6 | 12 |
| Fundamentals of Operation – Introduction – Governing equations and mode Compound – State model derivation – Construction of Model of a DC M | | | | | |
| Compound. | | quantonis | ,, | | is und |
| | | | | | 10 |
| UNIT IIREFERENCE FRAME THEORYHistorical background – phase transformation and commutator transformation | transformation of | 6 | 0 | 6 | 12 arv to |
| arbitrary reference frame . | | variables | 10III S | tation | ary to |
| | | | | | |
| UNIT III INDUCTION MACHINES | | 6 | 0 | 6 | 12 |
| Three phase induction machine - equivalent circuit – free acceleration character | | | | | |
| variables and arbitrary reference frame variables – Simulation under no loa arbitrary reference variable form. | | ms- macm | le val | lable | ioriii, |
| | | | | | |
| UNIT IV SYNCHRONOUS MACHINES | | 6 | 0 | 6 | 12 |
| Three phase synchronous machine - voltage and torque equations in machin (Park's equations). | ne variables and rote | or reference | e fram | ne var | iables |
| (Park s equations). | | | | | |
| UNIT V MULTIPHASE (MORE THAN THREE-PHASE) MACHI | NES CONCEPTS | 6 | 0 | 6 | 12 |
| Preliminary Remarks - Necessity of Multiphase Machines - Evolution of M | | | | | |
| Machines - Working Principle - Multiphase Induction Machine, Multiphase machine. Applications of Multiphase Machines | Synchronous Mach | ine -Mode | ling o | of 'n' | phase |
| inacinite. Appleations of Multipliase Machines | | | | | |
| LAB COMPONENT | | | | | |
| 1 Madeling of DC marking | | | | | |
| Modeling of DC machines. Simulation under no-load and loaded conditions for a PMDC motor | | | | | |
| 3 Simulation of smooth starting for DC motor. | | | | | |
| 4 Simulation under no-load and load conditions of a three phase induction | machine in machine | e variable f | orm a | nd art | oitrary |
| reference variable form | | | | | 1 |
| 5 Simulation under no-load and load conditions of a three phase synch arbitrary reference variable form. | ronous machine in | machine v | ariabl | e forr | n and |
| | | | | | |
| | Total (30 |)L+0T+30 | $\mathbf{P} = 0$ | 60 Pe | riods |
| | | | | | |
| Test Books: | | | | | |

| 1. | Stephen D. Umans, "Fitzgerald & Kingsley's Electric Machinery", Tata McGraw Hill, 7th Edition, 2020. |
|--------|--|
| 2. | Bogdan M. Wilamowski, J. David Irwin, The Industrial Electronics Handbook, Second Edition, Power Electronics and Motor Drives, CRC Press, 2011, 1st Edition. |
| 3. | Paul C. Krause, Oleg Wasynczuk, Scott D. Sudhoff, Steven D. Pekarek, "Analysis of Electric Machinery and Drive Systems", 3rd Edition, Wiley-IEEE Press, 2013 |
| 4. | Chee Mun Ong, Dynamic Simulation of Electric Machinery using MATLAB, Prentice Hall, 1997, 1st Edition |
| 5. | Atif Iqbal,Shaikh Moinoddin, Bhimireddy Prathap Reddy, Electrical Machine Fundamentals with Numerical Simulation using MATLAB/SIMULINK, Wiley,2021,1st Edition |
| Refere | ence Books |
| 1. | R. Krishnan, Electric Motor & Drives: Modeling, Analysis and Control, Pearson Education, 1st Imprint, 2015, 1st Edition. |
| 2. | R.Ramanujam, Modeling and Analysis of Electrical Machines, I.k.International Publishing House Pvt.Ltd,2018. |

| Course O | | | Bloom's Taxonomy | | |
|----------|-------|---|-------------------|--|--|
| Upon com | pleti | on of this course, the students will be able to: | Mapped | | |
| CO1 | : | Find the modeling for a brushed DC-Motor (Shunt, Series, Compound and separately excised motor) and to simulate DC motors using state models | L1: Remembering | | |
| CO2 | : | Apply reference frame theory for, resistive and reactive elements (three phase) | L2: Understanding | | |
| CO3 | : | Compute the equivalent circuit and torque of three phase induction motor and synchronous motor in machine variable arbitrary reference frame variable | L5: Evaluating | | |
| CO4 | : | Demonstrate the working of multiphase induction and synchronous machine. | L3: Applying | | |
| CO5 | : | Compute the model of three phase and multiphase induction and synchronous machine. | L6: Creating | | |

| COs/ Pos | PO 1 | PO 2 | PO 3 | PO 4 | PO 5 | PO 6 | PO 7 | PO 8 | PO 9 | PO 10 | PO 11 | PSO1 | PSO2 | PSO3 |
|-------------|---------|----------------|---------|---------|---------|---------|---------|---------|---------|----------|----------|------|------|------|
| CO1 | 3 | 3 | 3 | 3 | 3 | | 2 | 1 | | 3 | | 3 | 3 | 3 |
| CO2 | 3 | 3 | 3 | 3 | 3 | | 2 | 1 | | 3 | | 3 | 3 | 3 |
| CO3 | 3 | 3 | 3 | 3 | 3 | | 2 | 1 | | 3 | | 3 | 3 | 3 |
| CO4 | 3 | | | | 3 | | 2 | 1 | | 3 | | 3 | 3 | 3 |
| CO5 | 3 | | | | 3 | | 2 | 1 | | 3 | | 3 | 3 | 3 |
| Avg | 3 | 3 | 3 | 3 | 3 | 0 | 2 | 1 | 0 | 3 | 0 | 3 | 3 | 3 |

| 18E | EHO20 | 2 MULTILEVEL POWER CONV | ERTERS | SEME | STEF | 2 | |
|-----------------|---------------------|---|--------------------------|-------------------|----------|--------|--------|
| PREI | REQUI | STIES | CATEGORY | PEC | Cre | | 3 |
| Power | electror | ics | Hours/Week | | T | P | TH |
| | | | | 3 | 0 | 0 | 3 |
| Cour | se Obje | ctives: | | | | | |
| ι. | | oduce the fundamentals of multilevel voltage source inver | ters and multilevel cur | rent source | inverte | rs wi | th its |
| | modula | tion control | | | | | |
| | | | | | | | |
| UNIT | ГΙ | DIODE-CLAMPED MULTILEVEL INVERTER | S | 9 | 0 | 0 | 9 |
| Dwell Discor | Time Ca ntinuous | nverter - Converter Configuration and Switching State, Sp alculation and Switching Sequence Design, Neutral-Point V Space Vector Modulation, SVM Based on Two-Level -Level Diode-Clamped Inverters | Voltage Control 164 | | | | |
| UNIT | II 7 | MULTILEVEL VOLTAGE SOURCE INVERTE | RS | 9 | 0 | 0 | 9 |
| | | NPC/H-Bridge Inverter, Inverter Topology and Modular | | ms and Ha | rmonic | - | |
| Multil | evel Fly | ing-Capacitor Inverters, Inverter Configuration, Modulation | n Schemes | | | | |
| | | | | | | 0 | |
| UNIT | | CASCADED MULTILEVEL INVERTERS rter, Bipolar Pulse-Width Modulation and Unipolar Pulse | | 9 | 0 | 0 | 9 |
| | | MODULAR MULTILEVEL INVERTER | | 9 | 0 | 0 | 9 |
| | | lular Multilevel Inverter- Power circuit, operation and app ular Multilevel Inverter | lications, DC voltage b | alance contr | ol, Car | rier I | Sased |
| | 101 11104 | | | | | | |
| UNIT | | PWM TECHNIQUES | | 9 | 0 | 0 | 9 |
| | | Iodulation, Selective Harmonic Elimination, Space Vec | tor Modulation-Switch | ing States, | Space | Vec | ctors, |
| Dwell | Time Ca | alculation, Switching Sequence, Harmonic Content | | | | | |
| | | | Το | tal (45L+0 | T) = 44 | 5 Pe | riod |
| | | | | (1021) | | | |
| Text] | Books: | | | | | | |
| 1. | Bin W | u, Mehdi Narimani, 'High-Power Converters and AC Driv | res, 2nd Edition, Wiley- | IEEE Press, | 2017 | | |
| Refer | ence B | ooks: | | | | | |
| 1. | | ohan, T. M. Undeland, et al., Power Electronics—Converte as, New York, 2003 | rs, Applications and De | sign, 3rd ed | ition, J | ohn V | Wiley |
| E-Ref | ference | | | | | | |
| 1 | https:/ | //archive.nptel.ac.in/courses/108/102/108102157/ | | | | | |
| | | . | | | | | |
| 7 | 04 | | | DL. 1 | | т. | |
| | e Outco | | | Bloom's Monnod | | Taxo | nom |

| Course O | uto | comes: | Bloom's Taxonomy | | |
|----------|-------|--|-------------------|--|--|
| Upon com | pleti | Mapped | | | |
| CO1 | : | Understand the configurations for multilevel voltage source inverters. | L1: Remembering | | |
| CO2 | : | Describe the working principle of multilevel current source inverters | L2: Understanding | | |
| CO3 | : | Draw the topology structure of different types of multilevel inverters | L3: Applying | | |
| CO4 | : | Understand the principle of space vector modulation for multilevel inverters | L1: Remembering | | |
| CO5 | : | Select an appropriate modulation scheme for multilevel inverters | L4: Analyzing | | |

| COUR | COURSE ARTICULATION MATRIX | | | | | | | | | | | | | | |
|-------------|---|---------|---------|---------|---------|---------|----------------|---------|---------|----------|----------|----------|----------|----------|----------|
| COs/ POs | PO 1 | PO 2 | PO 3 | PO 4 | PO 5 | PO 6 | PO 7 | PO 8 | PO 9 | PO 10 | PO 11 | PO 12 | PS O1 | PS O2 | PS O3 |
| CO1 | 2 | 2 | 2 | 2 | | | | 1 | 2 | 2 | | 2 | 2 | 2 | 2 |
| CO2 | 1 | 3 | | | 2 | | | | 2 | 2 | | 1 | 1 | 3 | |
| CO3 | 1 | 1 | | 1 | 1 | 1 | 2 | | | | | | 1 | 1 | |
| CO4 | 1 | 1 | | 1 | 1 | | 2 | 2 | 1 | | 2 | 2 | 1 | 1 | |
| CO5 | 2 | 2 | 3 | 1 | 2 | 2 | 1 | | | 1 | 3 | | 2 | 2 | 3 |
| Avg | 1.4 | 1.8 | 2.5 | 1.25 | 1.5 | 1.5 | 1.67 | 1.5 | 1.67 | 1.67 | 2.5 | 1.67 | 1.4 | 1.8 | 2.5 |
| | 3/2/1-indicates strength of correlation (3- High, 2-Medium, 1- Low) | | | | | | | | | | | | | | |

| PREREQUISITES Power Electronics Course Objectives: | | UPS | | | | STEF | 2 |
|---|---|---|--|--|---------------|------------------|----------------|
| | | | CATEGORY | PEC | | edit | 3 |
| | | | Hours/Week | L | T | P | TE |
| Course Objectives: | | | | 3 | 0 | 0 | 3 |
| 0 | | | | | | | |
| | lge about modern power electronic cor | | applications in po- | wer utility | | | |
| 2. To impart knowled | lge about Resonant converters and UP | S. | | | | | |
| UNIT I DC-DC O | CONVERTERS | | | 9 | 0 | 0 | 9 |
| | Non-isolated DC-DC converters: Cu | | | | | | |
| | nodeling Concept of volt-second an | nd charge balance | – High gain inpu | t-parallel o | output | -serie | s DC |
| DC converter. | | | | | | | |
| UNIT II SWITCH | IED MODE POWER CONVER | TERS | | 9 | 0 | 0 | 9 |
| Isolated DC-DC converte | ers: Analysis and state space modellin | ng of fly back, Fo | | Luo, Hal | f brid | ge an | d ful |
| bridge converters- control | circuits and PWM techniques - Bidir | ectional DC-DC o | converters. | | | | |
| UNIT III RESONA | ANT CONVERTERS | | | 9 | 0 | 0 | 9 |
| | n- basic concepts- Resonant switch- I | oad Resonant co | nverters- ZVS C | | - | - | - |
| | ro Voltage Switching- Series and para | | | | nuge | topon | 05100 |
| | | | C | | | | |
| | CONVERTERS | | | 9 | 0 | 0 | 9 |
| | concept – Types of multilevel inverte | | | | | | |
| | Applications – Switching device current | nts – DC link cap | acitor voltage bala | ancing – F | eature | es of N | MLI |
| Comparisons of MLI. | | | | | | | |
| - | CONDITIONERS, UPS, AND F | TILTERS | | | | | |
| UNIT V POWER | , , | | | 9 | 0 | 0 | 9 |
| | disturbances- Power conditioners -U | PS: offline UPS, | Online UPS, App | | ~ | ~ | |
| Introduction- Power line filters, Series-parallel reso | onant filters, filter without series capac | PS: offline UPS, vitors, filter for PV | VM VSI, current f | lications - | - Filte | ers: V | oltag |
| Introduction- Power line filters, Series-parallel reso | | PS: offline UPS, vitors, filter for PV | VM VSI, current f | lications - | - Filte | ers: V | oltag |
| Introduction- Power line filters, Series-parallel reso | onant filters, filter without series capac | PS: offline UPS, vitors, filter for PV | VM VSI, current f ors. | lications – ilter, DC f | - Filte | ers: Vo – Des | oltag ign c |
| Introduction- Power line filters, Series-parallel reso | onant filters, filter without series capac | PS: offline UPS, vitors, filter for PV | VM VSI, current f ors. | lications - | - Filte | ers: Vo – Des | oltag ign c |
| Introduction- Power line filters, Series-parallel reso inductor and transformer | onant filters, filter without series capac | PS: offline UPS, vitors, filter for PV | VM VSI, current f ors. | lications – ilter, DC f | - Filte | ers: Vo – Des | oltag ign c |
| Introduction- Power line filters, Series-parallel reso inductor and transformer Text Books: | onant filters, filter without series capac for power electronic applications – Sel | PS: offline UPS, itors, filter for PV lection of capacito | VM VSI, current f ors. Tota | lications - ilter, DC f l (45L+0 | - Filte | ers: Vo – Des | oltag ign c |
| Introduction- Power line filters, Series-parallel reso inductor and transformer Text Books: 1. Simon Ang, Alej | onant filters, filter without series capac for power electronic applications – Sel andro Oliva," Power-Switching Conve | PS: offline UPS, sitors, filter for PV lection of capacito erters", Third Edit | VM VSI, current f ors. Tota | lications - ilter, DC f l (45L+0 | - Filte | ers: Vo – Des | oltag ign c |
| Introduction- Power line filters, Series-parallel reso inductor and transformer Text Books: 1. Simon Ang, Alej 2. M.H. Rashid – P | onant filters, filter without series capac for power electronic applications – Sel | PS: offline UPS, sitors, filter for PV lection of capacito erters", Third Edit | VM VSI, current f ors. Tota | lications - ilter, DC f l (45L+0 | - Filte | ers: Vo – Des | oltag ign c |
| Introduction- Power line filters, Series-parallel reso inductor and transformer Text Books: 1. Simon Ang, Alej 2. M.H. Rashid – P Reference Books: | onant filters, filter without series capac for power electronic applications – Sel andro Oliva," Power-Switching Conve ower Electronics handbook, Elsevier P | PS: offline UPS, bitors, filter for PV lection of capacito erters", Third Edit Publication, 2001. | VM VSI, current f ors. Tota tion, CRC Press, 2 | lications - ilter, DC f 1 (45L+0 010. | T)= 4 | - Des | riod |
| Introduction- Power line filters, Series-parallel reso inductor and transformer Text Books: 1. Simon Ang, Ale 2. M.H. Rashid – P Reference Books: 1. Ned Mohan, To | onant filters, filter without series capac for power electronic applications – Sel andro Oliva," Power-Switching Conve ower Electronics handbook, Elsevier F | PS: offline UPS, bitors, filter for PV lection of capacito erters", Third Edit Publication, 2001. | VM VSI, current f ors. Tota tion, CRC Press, 2 | lications - ilter, DC f 1 (45L+0 010. | T)= 4 | - Des | riod |
| Introduction- Power line filters, Series-parallel reso inductor and transformer Text Books: 1. Simon Ang, Ale 2. M.H. Rashid – P Reference Books: 1. Ned Mohan, To Edition, John Wi | onant filters, filter without series capac for power electronic applications – Sel andro Oliva," Power-Switching Conve ower Electronics handbook, Elsevier F re.M.Undeland, William.P.Robbins, " ley and Sons, 2006. | PS: offline UPS, bitors, filter for PV lection of capacito erters", Third Edit Publication, 2001. | VM VSI, current f ors. Tota tion, CRC Press, 2 ss Converters, Ap | lications – liter, DC f l (45L+0 010. | T)= 4 | - Des | riod |
| Introduction- Power line filters, Series-parallel reso inductor and transformer Text Books: 1. Simon Ang, Alej 2. M.H. Rashid – P Reference Books: 1. Ned Mohan, To Edition, John Wi 2. M.H. Rashid, "P | onant filters, filter without series capac for power electronic applications – Sel andro Oliva," Power-Switching Conve ower Electronics handbook, Elsevier F | PS: offline UPS, bitors, filter for PV lection of capacito erters", Third Edit Publication, 2001. | VM VSI, current f ors. Tota tion, CRC Press, 2 ss Converters, Ap | lications – liter, DC f l (45L+0 010. | T)= 4 | - Des | riod |
| Introduction- Power line filters, Series-parallel reso inductor and transformer Text Books: 1. Simon Ang, Alej 2. M.H. Rashid – P Reference Books: 1. Ned Mohan, To Edition, John Wi 2. M.H. Rashid, "P E-References: | andro Oliva," Power-Switching Conve ower Electronics handbook, Elsevier F re.M.Undeland, William.P.Robbins, " ley and Sons, 2006. ower Electronics circuits, devices and | PS: offline UPS, bitors, filter for PV lection of capacito erters", Third Edit Publication, 2001. | VM VSI, current f ors. Tota tion, CRC Press, 2 ss Converters, Ap | lications – liter, DC f l (45L+0 010. | T)= 4 | - Des | riod |
| Introduction- Power line filters, Series-parallel reso inductor and transformer Text Books: 1. Simon Ang, Ale 2. M.H. Rashid – P Reference Books: 1. Ned Mohan, To Edition, John Wi 2. M.H. Rashid, "P E-References: 1. NPTEL Course: | onant filters, filter without series capac for power electronic applications – Sel andro Oliva," Power-Switching Conve ower Electronics handbook, Elsevier F re.M.Undeland, William.P.Robbins, " ley and Sons, 2006. | PS: offline UPS, bitors, filter for PV lection of capacito erters", Third Edit Publication, 2001. | VM VSI, current f ors. Tota tion, CRC Press, 2 ss Converters, Ap | lications – liter, DC f l (45L+0 010. | T)= 4 | - Des | riod |

| Course O |)uto | Bloom's Taxonomy | |
|----------|--------|--|-------------------|
| Upon com | Mapped | | |
| CO1 | : | Analyze the state space model for DC – DC converters. | L4: Analyzing |
| CO2 | : | Acquire knowledge on switched mode power converters. | L2: Understanding |
| CO3 | : | Outline the PWM techniques for DC-AC converters. | L1: Remembering |
| CO4 | : | Discuss about modern power electronic converters and its applications in electric power utility. | L2: Understanding |

| _ | | | | |
|---|-----|---|-------------------------------|-------------------|
| | CO5 | : | Identify the filters and UPS. | L2: Understanding |
| | | | | |

| COUR | COURSE ARTICULATION MATRIX | | | | | | | | | | | | | | |
|---|----------------------------|---------|---------|---------|---------|---------|---------|---------|---------|----------|----------|----------|----------|----------|----------|
| COs/ POs | PO 1 | PO 2 | PO 3 | PO 4 | PO 5 | PO 6 | РО 7 | PO 8 | PO 9 | PO 10 | PO 11 | PO 12 | PS O1 | PS O2 | PS O3 |
| CO1 | 2 | 1 | 2 | 2 | | | 3 | 2 | | 2 | | 2 | 2 | 2 | 1 |
| CO2 | 1 | 1 | 3 | 2 | | | 3 | 2 | | 2 | | 2 | 3 | 3 | 2 |
| CO3 | 2 | 2 | 2 | 3 | | | 3 | 3 | | 2 | | 1 | 2 | 2 | 1 |
| CO4 | 2 | 1 | 1 | 2 | | | 3 | 2 | | 2 | | 2 | 2 | 3 | 2 |
| CO5 | 1 | 1 | 2 | 1 | | | 3 | 3 | | 3 | | 1 | 2 | 2 | 1 |
| Avg | 1.6 | 1.2 | 2 | 2 | 0 | 0 | 3 | 2.4 | 0 | 2.2 | 0 | 1.6 | 2.2 | 2.4 | 1.4 |
| 3/2/1-indicates strength of correlation (3- High, 2-Medium, 1- Low) | | | | | | | | | | | | | | | |

| - | EEHO204 MODELING AND CONTROL OF POW | CATEGORY | SEME | | | - |
|--|---|--|--|---|----------------------|---------------------|
| PF | REREQUISITES | PEC | | | 3 | |
| Po | wer Electronics and Control Systems | Hours/Week | L 3 | Т 0 | <u>Р</u> 0 | TH 3 |
| Co | ourse Objectives: | | | | 0 | |
| 1. | To learn the basics of control system simulation. | | | | | |
| 2. | To do symbolic calculation and study the principles of sliding r | node control and the way of | annly sm | c for h | nick | |
| | converter. | | appij on | | | |
| 3. | To learn the concept of power factor correction. | | | | | |
| 4. | To design simulate smc for buck converter and power factor co | rrection circuit with control | ler. | | | |
| TIN | NIT I SIMULATION BASICS IN CONTROL SYST | FMS | 9 | 0 | 0 | 9 |
| | ansfer Function-How to build transfer function, identify Poles, zer | | - | - | - | |
| | Multiplication Factors, Constant, Single and Double Integr | | | | | |
| | nctions, Single Pole and Single Zero Functions, RHP Pole | | | | | |
| | nsfer function from state space model. | | | 1 | | |
| F T N | | | 0 | | 0 | • |
| | NIT II SYMBOLIC CALCULATIONS | | 9 | 0 | 0 | 9 |
| | mbolic Variables - Symbolic Vector Variables, Commands for Ha | | | | | |
| | Polynomial Factorization and Roots of Polynomials, Sy atrices - Other Symbolic Matrix Operations. | moone matrix Algebra - | Operation | is with | i Syn | |
| VIC | arrees - Oner Symbolic Marix Operations. | | | | | |
| UN | NIT III SLIDING MODE CONTROL BASICS | | 9 | 0 | 0 | 9 |
| | roduction- Introduction to Sliding-Mode Control- Basics of S | Sliding-Mode Theory- Ap | olication | of Slie | ding- | Mod |
| Co | ntrol to DC-DC Converters-Principle-Sliding mode control of b | uck converter. | - | | - | |
| | | | | | | |
| | NIT IV POWER FACTOR CORRECTION CIRCUIT | | 9 | 0 | 0 | 9 |
| | roduction, Operating Principle of Single-Phase PFCs, Control | | | | | |
| Av | verage-Current-Control Loop, Designing the Outer Voltage-Con- | ntrol Loop, Example of Sin | gle-Phase | e PFC S | Syste | ms. |
| | | | 0 | 0 | 0 | 9 |
| TIN | NIT V - I CONTROLI FR DESIGN FOR PEC CIRCLE | ГС | U U | | | |
| | NIT V CONTROLLER DESIGN FOR PFC CIRCUT wer factor correction circuit using other SMPS topologies: (| | 9 - PFC c | | empl | |
| Po | wer factor correction circuit using other SMPS topologies: O dgeless topologies. | | | | empl | loym |
| Po | wer factor correction circuit using other SMPS topologies: C | Cuk and SEPIC converter | - PFC c | ircuits | - | • |
| Po | wer factor correction circuit using other SMPS topologies: C | Cuk and SEPIC converter | | ircuits | - | • |
| Po bri | wer factor correction circuit using other SMPS topologies: C | Cuk and SEPIC converter | - PFC c | ircuits | - | - |
| Po bri Te | wer factor correction circuit using other SMPS topologies: C dgeless topologies. ext Books: Feedback Control problems using MATLAB and the Control | Cuk and SEPIC converter Total | - PFC c | $(\Gamma) = 4$ | 5 Pe | rioc |
| Pov brid Te | ext Books: Feedback Control problems using MATLAB and the Control 2000, 1 st Edition, Cengage Learning. | Cuk and SEPIC converter Total | - PFC c | $(\Gamma) = 4$ | 5 Pe | riod |
| Po bri Te | wer factor correction circuit using other SMPS topologies: dgeless topologies. ext Books: Feedback Control problems using MATLAB and the Control 2000, 1 st Edition, Cengage Learning. . Ned Mohan,"Power Electronics: A First Course", Johnwiley, | Cuk and SEPIC converter Total | - PFC c (45L+0' | $(\Gamma) = 4$ | 5 Pe Joe (| riod |
| Pov brid Te | wer factor correction circuit using other SMPS topologies: dgeless topologies. ext Books: Feedback Control problems using MATLAB and the Control 2000, 1st Edition, Cengage Learning. Ned Mohan,"Power Electronics: A First Course", Johnwiley, Marian K. Kazimierczuk and AgasthyaAyachit,"Laboratory | Cuk and SEPIC converter Total | - PFC c (45L+0' | $(\Gamma) = 4$ | 5 Pe Joe (| riod |
| Pov brid Te 1. 2. | wer factor correction circuit using other SMPS topologies: dgeless topologies. ext Books: Feedback Control problems using MATLAB and the Control 2000, 1 st Edition, Cengage Learning. Ned Mohan,"Power Electronics: A First Course", Johnwiley, Marian K. Kazimierczuk and AgasthyaAyachit,"Laboratory Converters", Wiley 2016, 1 st Edition. | Cuk and SEPIC converter Total I system tool box By Dear 2013, 1 st Edition. Manual for Pulse-Width | - PFC c (45L+0' Frederic Modulate | Γ) = 4 k and . d DC- | 5 Pe Joe (| riod |
| Pov brid Te 1. 2. 3. 4. | wer factor correction circuit using other SMPS topologies: dgeless topologies. ext Books: Feedback Control problems using MATLAB and the Control 2000, 1st Edition, Cengage Learning. Ned Mohan,"Power Electronics: A First Course", Johnwiley, Marian K. Kazimierczuk and AgasthyaAyachit,"Laboratory Converters", Wiley 2016, 1st Edition. | Cuk and SEPIC converter Total I system tool box By Dear 2013, 1 st Edition. Manual for Pulse-Width | - PFC c (45L+0' Frederic Modulate | Γ) = 4 k and . d DC- | 5 Pe Joe (| riod |
| Poy brid Te 1. 2. 3. 4. Re | wer factor correction circuit using other SMPS topologies: C dgeless topologies. ext Books: Feedback Control problems using MATLAB and the Control 2000, 1 st Edition, Cengage Learning. Ned Mohan,"Power Electronics: A First Course", Johnwiley, Marian K. Kazimierczuk and AgasthyaAyachit,"Laboratory Converters", Wiley 2016, 1 st Edition. Power Electronics handbook, Industrial Electronics series, S.I Eference Books: Sliding mode control for Switching Power Converters:, | Cuk and SEPIC converter Total of system tool box By Dear 2013, 1 st Edition. Manual for Pulse-Width K.Varenina, CRC press, 200 | - PFC c (45L+0' Frederic Modulate | T) = 4 k and . d DC- | Joe (| riod Chow |
| Pov brid Te 1. 2. 3. 4. Re 1. | wer factor correction circuit using other SMPS topologies: C dgeless topologies. ext Books: Feedback Control problems using MATLAB and the Control 2000, 1st Edition, Cengage Learning. Ned Mohan, "Power Electronics: A First Course", Johnwiley, Marian K. Kazimierczuk and AgasthyaAyachit, "Laboratory Converters", Wiley 2016, 1st Edition. Power Electronics handbook, Industrial Electronics series, S.I efference Books: Sliding mode control for Switching Power Converters:, Yuk Ming Lai Chi-Kong Tse, 1st Edition, CRC Press. | Cuk and SEPIC converter Total of system tool box By Dear 2013, 1 st Edition. Manual for Pulse-Width K.Varenina, CRC press, 200 Techniques and Impleme | - PFC c (45L+0' Frederic Modulate 2, 1 st Edi | T) = 4 k and . d DC- | Joe (| riod Chov |
| Pov brid Te 1. 2. 3. 4. Re | wer factor correction circuit using other SMPS topologies: C dgeless topologies. ext Books: Feedback Control problems using MATLAB and the Control 2000, 1st Edition, Cengage Learning. Ned Mohan, "Power Electronics: A First Course", Johnwiley, Marian K. Kazimierczuk and AgasthyaAyachit, "Laboratory Converters", Wiley 2016, 1st Edition. Power Electronics handbook, Industrial Electronics series, S.I efference Books: Sliding mode control for Switching Power Converters:, Yuk Ming Lai Chi-Kong Tse, 1st Edition, CRC Press. Andre Kislovski, "Dynamic Analysis of Switching-Mode DC | Cuk and SEPIC converter Total I system tool box By Dear 2013, 1 st Edition. Manual for Pulse-Width K.Varenina, CRC press, 200 Techniques and Impleme /DC Converters", Springer | - PFC c (45L+0' Frederic Modulate 2, 1 st Edi | T) = 4 k and . d DC- | Joe (| rioc Chow |

| Course C |)uto | comes: | Bloom's Taxonomy |
|----------|------|---|-------------------|
| Upon com | plet | ion of this course, the students will be able to: | Mapped |
| CO1 | : | To calculate transfer function for constant, differential, integral, First order and Second order factors. | L2: Understanding |
| CO2 | : | To illustrate the effect of poles and zero's in the 's' plane. | L1: Remembering |
| CO3 | : | To select Symbolic equations for solving problems related with Matrices, Polynomial and vectors. | L5: Evaluating |
| CO4 | : | To compute the control expression for DC – DC buck converter using sliding mode control theory | L3: Applying |
| CO5 | : | To determine the controller expression for power factor correction circuits and to simulate sliding mode control of buck converter and power factor correction circuit. | L5: Evaluating |

| COUR | SE AR | RTICU | LATIO | ON MA | ATRIX | | | | | | | | | | |
|-------------|---------|---------|---------|----------|------------|---------|----------|-----------|---------|----------|----------|----------|----------|----------|----------|
| COs/ POs | PO 1 | PO 2 | PO 3 | PO 4 | РО 5 | PO 6 | PO 7 | PO 8 | PO 9 | PO 10 | PO 11 | PO 12 | PS O1 | PS O2 | PS O3 |
| CO1 | 3 | 3 | 3 | 3 | 3 | | | 1 | | 2 | | 3 | 3 | 3 | 3 |
| CO2 | 3 | 3 | 3 | 3 | 3 | | | 1 | | 2 | | 3 | 3 | 3 | 3 |
| CO3 | 3 | 3 | 3 | 3 | 3 | | | 1 | | 2 | | 3 | 3 | 3 | 3 |
| CO4 | 3 | 3 | 3 | 3 | 3 | | | 1 | | 2 | | 3 | 3 | 3 | 3 |
| CO5 | 3 | 3 | 3 | 3 | 3 | | | 1 | | 2 | | 3 | 3 | 3 | 3 |
| Avg | 3 | 3 | 3 | 3 | 3 | 0 | 0 | 1 | 0 | 2 | 0 | 3 | 3 | 3 | 3 |
| | | - | 3/2/ | 1-indica | ites strei | ngth of | correlat | ion (3-] | High, 2 | Mediur | n, 1- Lo | w) | · | · | · |

| 18EE | HO205 | DIGITA | | | POWER ELE | CTRON | ICS | SEN | IES' | ГER | | |
|--------|-----------------------|---------------------------------------|----------------------|-----------|--|------------|--------------|--------------|----------|--------|---------|--------|
| PRE | REQUIST | IES | | | | CATE | GORY | PEC | 2 | Cre | edit | 3 |
| | - | Power Electron | nics | | | | 1887 1 | L | | Т | Р | С |
| | | | | | | Hour | s∖Week | 3 | | 0 | 0 | 3 |
| Cour | se Objecti | ves: | | | | • | | | | | | • |
| 1. | To underst | and the concepts | of discrete time sy | stems. | | | | | | | | |
| 2. | | systems in z don | | | | | | | | | | |
| 3. | To design t | he digital control | lers | | | | | | | | | |
| UNIT | די | INTRODUC | TION | | | | | | 9 | 0 | 0 | 9 |
| | | | | ital cor | trol-Importance | of digital | control-S | | - | v | - | |
| | | | | | ansform-MATLA | - | | | | - | | |
| - | | • | - | | stems-Sampling the | - | ies. Treque | ney rea | spon | | 1150101 | e time |
| systen | | , or nequency rea | sponse of discrete | time sys | stenns Sumpring un | | | | | | | |
| UNIT | T II | Z-PLANE | ANALYSIS | OF | DISCRETE-T | IME | CONTR | OL | • | | | |
| | | SYSTEMS | | | | | | - | 9 | 0 | 0 | 9 |
| Impul | se sampling | | alse transfer functi | ion - Rea | alization of digital | controlle | ers- Mappir | ig betw | veen | s-plar | ne and | |
| zplane | e - Stability | nalysis of closed | loop systems in z | -plane_ | Transient and stead | dy state a | nalyses. | - | | - | | |
| | | | | | | | | | | | 1 | 1 |
| UNII | | | PPROACH TC |) DISC | RETE-TIME C | ONTRO |)L | | 9 | 0 | 0 | 9 |
| ~ | | STEMS | | • | | | | | - | | - | - |
| | | | | | l systems - Soluti | | | nd dis | crete | time | state | space |
| equati | ons -Puise t | ansier function n | natrix - Discretiza | tion of c | ontinuous time sta | ite space | equations. | | | | | |
| UNIT | ' IV | DIGITAL | ONTROLLER | DESI | GN METHODS | | | | 9 | 0 | 0 | 9 |
| | | | | | trollers by using b | | ansformati | | - | - | | - |
| | | | | | · Deadbeat contro | | | | | | | |
| | | | | | zation of Digital co | | | | | | | |
| | | | | | | | | | | | 1 | 1 |
| UNI | T V | | | S IN P | OWER ELECT | RONIC | S | | 9 | 0 | 0 | 9 |
| | ~ " | APPLICAT | | ~ | ~ | | | | - | · | - | |
| | | | | | er Control Applica | | | | | | | |
| | | | | | r instantaneous ov ample Code for P | | | i, inter | rupts | , Dise | crete I | P1 and |
| TIDU | Juanons, Ai | | a i ib implemente | | | www.gene | ation. | | | | | |
| | | | | | | |] | Fotal (| 45L- | -0T)= | = 45 P | eriods |
| | | | | | | | | | | , | | |
| Text | Books: | | | | | | | | | | | |
| 1 | M. Gopa | , "Digital Contro | l and State Variab | le Meth | ods", McGraw Hil | ll Educati | ion, 4th | | | | | |
| 1. | Edition, 2 | | | | | | | | | | | |
| 2. | | | | | Education, India, | | | | | | | |
| 3. | | | | | ity Press; 2ndEdit | | | . ~ | | | | |
| 4. | | strom & Tore Hag nent and Control, | | ollers: 1 | Theory, Design and | l Tuning' | ' Internatio | nal So | cıety | for | | |
| Refer | ence Book | s: | | | | | | | | | | |
| 1. | G.F.Fran Wesley, 2 | | ell and M.Workm | an, Dig | ital Control of Dyr | namic Sys | stems, 3rd o | ed., Ad | ldiso | n | | |
| | | | Gary B. Lamont | Digital | control systems: T | Theory h | ardware so | oftware | <u>,</u> | | | |
| 2. | | Hill Book Compa | | , 2151ul | control systems. I | . neory, n | | , i t v ui t | , | | | |
| 3. | | | | Systems | ", McGraw Hill Ed | lucation, | 2007. | | | | | |

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https://nptel.ac.in/courses/108103008

| | Course Outcomes: Upon completion of this course, the students will be able to: | | | | | | |
|-----|--|--|-------------------|--|--|--|--|
| CO1 | : | To understand the digital control system | L2: Understanding | | | | |
| CO2 | : | Capable of determining the stability in z domain | L1: Applying | | | | |
| CO3 | : | To understand the state space analysis | L1: Remembering | | | | |
| CO4 | : | To design the various types of digital controllers | L3: Analysing | | | | |
| CO5 | : | To check the digital controllers in power electronics design | L5: Evaluating | | | | |

| COs/ POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO1 0 | PO1 1 | PO1 2 | PSO 1 | PSO 2 | PSO 3 |
|-------------|-----|-----|-----|-----|-----|-----|-----|-----|-----|----------|----------|----------|----------|----------|----------|
| CO1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | | | 1 | | 1 | 1 | 1 |
| CO2 | 1 | 3 | 3 | 3 | 2 | 1 | 2 | 1 | 1 | | 1 | | 1 | 1 | 1 |
| CO3 | 1 | 2 | 2 | 3 | 2 | 1 | 2 | 1 | 1 | | 1 | | 1 | 1 | 1 |
| CO4 | 1 | 3 | 2 | 3 | 2 | 1 | 2 | 1 | 1 | | 1 | | 1 | 1 | 1 |
| CO5 | 1 | 2 | 3 | 3 | 2 | 1 | 2 | 1 | 1 | | 1 | | 1 | 1 | 1 |
| Avg | 1 | 2.2 | 2.2 | 2.6 | 1.8 | 1 | 1.8 | 1 | 1 | 0 | 1 | 0 | 1 | 1 | 1 |

| 18EEHO2 0 | | PWM CONVERTERS AND A | | SEME | | | 1 |
|---|--|---|---|--|---|---|---|
| PREREQU | JISIT | 'ES | CATEGORY | PEC | | edit | 3 |
| Power Electr | onics. | | PEC | L 3 | T 0 | P 0 | <u>TH</u> 3 |
| Course Ob | iectiv | 765. | | 5 | U | U | 5 |
| | • | a strong foundation of fundamental concepts in ba | sic operation of PWM convert | are like sol | lid sta | to driv | VAS |
| and po | ower o | quality. | - | | nu sta | | ves |
| | | he student to apply these techniques in application | s including basic circuit operat | ion | | | |
| and de | 0 | inderstand the steady-state and dynamic analysis of | f DWM convertors application | | | | |
| 5. 10 em | able u | inderstand the steady-state and dynamic analysis of | n r www.converters.applications | 5 | | | |
| UNIT I | IN | TRODUCTION | | 9 | 0 | 0 | 9 |
| | | Overview of applications of voltage source conve | | | | | |
| | | overters, operation of each type, design of commut ncy control, current source inverter and pulse wid | | age and cu | rrent v | wavef | orms |
| voltage and I | lieque | ney control, current source inverter and pulse wid | in modulated inverter. | | | | |
| UNIT II | PV | VM TECHNIQUES | | 9 | 0 | 0 | 9 |
| | | lation techniques for bridge converters Bus clam | | | | | |
| | | DC Converters: Classification of choppers, operative transforms. | ating principle and control circu | uits for each | ch typ | e. An | alysi |
| of voltage all | | | | | | | |
| UNIT III | PE | RFORMANCE ANALYSIS OF LINE CU | RRENT RIPPLE | 9 | 0 | 0 | 9 |
| Analysis of | line | | | | togo | and a | nnlia |
| | gral of | current ripple: Synchronously revolving refere f voltage error; evaluation of line current ripple; h | ybrid PWM for reduced line cu | rrent ripple | e. An | alysis | of d |
| link current | gral of t: Rela | | ybrid PWM for reduced line cu | rrent ripple | e. An | alysis | of d |
| link current over a carrier UNIT IV | gral of t: Rela r cycle PE | f voltage error; evaluation of line current ripple; hy ition between line-side currents and dc link current e; rms current rating of dc capacitors. RFORMANCE ANALYSIS OF TORQUE | ybrid PWM for reduced line cu nt; dc link current and inverter RIPPLE AND LOSS | rrent ripple state; rms 9 | e. Ana dc cu 0 | alysis rrent | of d rippl |
| link current over a carrier UNIT IV Analysis of t | gral of t: Rela r cycle PE torque | f voltage error; evaluation of line current ripple; h ation between line-side currents and dc link current e; rms current rating of dc capacitors. RFORMANCE ANALYSIS OF TORQUE e ripple: Evaluation of harmonic torques and rms | ybrid PWM for reduced line cu nt; dc link current and inverter RIPPLE AND LOSS torque ripple, hybrid PWM for | rrent ripple state; rms 9 reduced to | e. An dc cu 0 orque | alysis rrent 0 ripple | of d rippl |
| link current over a carrier UNIT IV Analysis of t Analysis for | gral of t: Rela <u>r cycle</u> PE torque r inve | f voltage error; evaluation of line current ripple; h ation between line-side currents and dc link current e; rms current rating of dc capacitors. RFORMANCE ANALYSIS OF TORQUE e ripple: Evaluation of harmonic torques and rms erter's loss: Simplifying assumptions in evaluat | ybrid PWM for reduced line cu nt; dc link current and inverter RIPPLE AND LOSS torque ripple, hybrid PWM for ion of inverter loss, dependen | rrent ripple state; rms 9 reduced to ce of inve | e. An dc cu 0 orque | alysis rrent 0 ripple | of d rippl |
| link current over a carrier UNIT IV Analysis of t Analysis for | gral of t: Rela <u>r cycle</u> PE torque r inve | f voltage error; evaluation of line current ripple; h ation between line-side currents and dc link current e; rms current rating of dc capacitors. RFORMANCE ANALYSIS OF TORQUE e ripple: Evaluation of harmonic torques and rms | ybrid PWM for reduced line cu nt; dc link current and inverter RIPPLE AND LOSS torque ripple, hybrid PWM for ion of inverter loss, dependen | rrent ripple state; rms 9 reduced to ce of inve | e. An dc cu 0 orque | alysis rrent 0 ripple | of d rippl |
| link current over a carrier UNIT IV Analysis of t Analysis for power factor, UNIT V | gral of t: Rela r cycle PE torque r inve r, influ | f voltage error; evaluation of line current ripple; hy ition between line-side currents and dc link current e; rms current rating of dc capacitors. RFORMANCE ANALYSIS OF TORQUE e ripple: Evaluation of harmonic torques and rms erter's loss: Simplifying assumptions in evaluat ence of PWM techniques on switching loss, desig | ybrid PWM for reduced line cu nt; dc link current and inverter RIPPLE AND LOSS torque ripple, hybrid PWM for ion of inverter loss, dependen n of PWM for low inverter loss D APPLICATIONS | rrent ripple state; rms reduced to ce of inve s. 9 | e. Ana dc cu 0 orque erter 1 0 | alysis rrent 0 ripple oss o 0 0 | of d rippl 9 e n lin 9 |
| link current over a carrier UNIT IV Analysis of t Analysis for power factor, UNIT V PWM for m based PWM | gral of t: Rela r cycle PE torque r inve r, influ PV nultile | f voltage error; evaluation of line current ripple; hy attion between line-side currents and dc link current e; rms current rating of dc capacitors. RFORMANCE ANALYSIS OF TORQUE ripple: Evaluation of harmonic torques and rms rter's loss : Simplifying assumptions in evaluat ence of PWM techniques on switching loss, desig | ybrid PWM for reduced line cu nt; dc link current and inverter RIPPLE AND LOSS torque ripple, hybrid PWM for ion of inverter loss, dependen n of PWM for low inverter loss D APPLICATIONS o multilevel inverters, voltage | rrent ripple state; rms reduced to ce of inve s. 9 space vect | e. Ana dc cu orque erter 1 0 tors, s | alysis rrent 0 ripple oss o 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 | of d rippl 9 e n lin 9 vecto |
| ink current over a carrier UNIT IV Analysis of t Analysis for oower factor, UNIT V PWM for m pased PWM | gral of t: Rela r cycle PE torque r inve r, influ PV nultile | f voltage error; evaluation of line current ripple; hy ation between line-side currents and dc link current e; rms current rating of dc capacitors. RFORMANCE ANALYSIS OF TORQUE e ripple: Evaluation of harmonic torques and rms erter's loss: Simplifying assumptions in evaluat ence of PWM techniques on switching loss, desig WM FOR MULTILEVEL INVERTER ANI vel inverter -Extensions of sine-triangle PWM to lysis of line current ripple and torque ripple | ybrid PWM for reduced line cu nt; dc link current and inverter RIPPLE AND LOSS torque ripple, hybrid PWM for ion of inverter loss, dependen n of PWM for low inverter loss D APPLICATIONS o multilevel inverters, voltage . Applications Active power | rrent ripple state; rms reduced to ce of inve s. 9 space vect | e. Ana dc cu orque erter 1 0 tors, s Reac | alysis rrent 0 ripple oss o 0 0 pace tive | of d rippl 9 e n lin 9 vecto |
| link current over a carrier UNIT IV Analysis of t Analysis for power factor, UNIT V PWM for m based PWM | gral of : Rela r cycle PE torque r inve r, influ PV nultile I, ana n, Con | f voltage error; evaluation of line current ripple; hy ation between line-side currents and dc link current e; rms current rating of dc capacitors. RFORMANCE ANALYSIS OF TORQUE e ripple: Evaluation of harmonic torques and rms erter's loss: Simplifying assumptions in evaluat ence of PWM techniques on switching loss, desig WM FOR MULTILEVEL INVERTER ANI vel inverter -Extensions of sine-triangle PWM to lysis of line current ripple and torque ripple | ybrid PWM for reduced line cu nt; dc link current and inverter RIPPLE AND LOSS torque ripple, hybrid PWM for ion of inverter loss, dependen n of PWM for low inverter loss D APPLICATIONS o multilevel inverters, voltage . Applications Active power | rrent ripple state; rms 9 reduced to ce of inve s. 9 space vect filtering, | e. Ana dc cu orque erter 1 0 tors, s Reac | alysis rrent 0 ripple oss o 0 0 pace tive | of d rippl 9 e n lin 9 vecto |
| link current over a carrier UNIT IV Analysis of t Analysis for power factor, UNIT V PWM for m based PWM compensation Test Books | gral of t: Rela r cycle PE torque r inve r influ PV nultile I, ana n, Cor | f voltage error; evaluation of line current ripple; hy tition between line-side currents and dc link current e; rms current rating of dc capacitors. RFORMANCE ANALYSIS OF TORQUE e ripple: Evaluation of harmonic torques and rms erter's loss: Simplifying assumptions in evaluat ence of PWM techniques on switching loss, desig WM FOR MULTILEVEL INVERTER ANI vel inverter -Extensions of sine-triangle PWM to lysis of line current ripple and torque ripple enstant Volt Per hertz drives, PWM Rectifier etc. | ybrid PWM for reduced line cu nt; dc link current and inverter RIPPLE AND LOSS torque ripple, hybrid PWM for ion of inverter loss, dependen n of PWM for low inverter loss D APPLICATIONS o multilevel inverters, voltage . Applications Active power Tota | rrent ripple state; rms 9 reduced to ce of inve s. 9 space vect filtering, 1 (45L+0 | e. Ana dc cu orque erter 1 0 tors, s Reac T)= 4 | alysis rrent 0 ripple oss 0 0 0 pace tive 15 Pe | of d rippl 9 e n lin 9 vecto powe |
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| link current over a carrier UNIT IV Analysis of t Analysis for power factor, UNIT V PWM for m based PWM compensation Test Books 1. D. C Sons 2. Bin | gral of r cycle r cycle r cycle r orque r inve r | f voltage error; evaluation of line current ripple; hy tition between line-side currents and dc link current e; rms current rating of dc capacitors. RFORMANCE ANALYSIS OF TORQUE e ripple: Evaluation of harmonic torques and rms erter's loss: Simplifying assumptions in evaluat ence of PWM techniques on switching loss, desig WM FOR MULTILEVEL INVERTER ANI vel inverter -Extensions of sine-triangle PWM to lysis of line current ripple and torque ripple enstant Volt Per hertz drives, PWM Rectifier etc. mes, T. A. Lipo, 'Pulse Width Modulation For Po 03. 'High Power Converters and AC Drives'', John W an, Undeland and Robbins, "Power Electronics: C | ybrid PWM for reduced line cu nt; dc link current and inverter RIPPLE AND LOSS torque ripple, hybrid PWM for ion of inverter loss, dependen n of PWM for low inverter loss D APPLICATIONS o multilevel inverters, voltage . Applications Active power Tota ower Converters: Principles and illey & sons, Inc., 2006. | rrent ripple state; rms 9 reduced to ce of inve s. 9 space vect filtering, 1 (45L+0 | e. Ana dc cu orque erter 1 0 tors, s Reac T)= 4 | alysis rrent 0 ripple oss o 0 pace tive 15 Pe | of d rippl 9 e n lin 9 vecto powe riod |
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| link current over a carrier UNIT IV Analysis of t Analysis for power factor, UNIT V PWM for m based PWM compensation Test Books 1. D. C Sons 2. Bin 3. Ned 3. Ned Sons Reference E | gral of r cycle pE torque r inve , influ PV nultile (, ana n, Cor G. Hol s., 200 Wu, ' I Moh s. Books eli Ci iverter | f voltage error; evaluation of line current ripple; hy tition between line-side currents and dc link current e; rms current rating of dc capacitors. RFORMANCE ANALYSIS OF TORQUE e ripple: Evaluation of harmonic torques and rms erter's loss: Simplifying assumptions in evaluat ence of PWM techniques on switching loss, desig WM FOR MULTILEVEL INVERTER ANI vel inverter -Extensions of sine-triangle PWM to lysis of line current ripple and torque ripple nstant Volt Per hertz drives, PWM Rectifier etc. mes, T. A. Lipo, 'Pulse Width Modulation For Po 03. 'High Power Converters and AC Drives'', John W an, Undeland and Robbins, "Power Electronics: C | ybrid PWM for reduced line cu nt; dc link current and inverter RIPPLE AND LOSS torque ripple, hybrid PWM for ion of inverter loss, dependen n of PWM for low inverter loss D APPLICATIONS o multilevel inverters, voltage . Applications Active power Tota wer Converters: Principles and illey & sons, Inc., 2006. Tonverters, Applications and De Da Silva "Advanced Power E | rrent ripple state; rms 9 reduced to ce of inve s. 9 space vect filtering, l (45L+0 Practice', esign'', Joh | e. Ana dc cu orque erter 1 0 tors, s Reac (T)= 4 | alysis rrent 0 ripple oss o 0 pace tive filey a | of d rippl 9 en lin 9 vecto powe riod |

| 1 | NPTEL Lecture series by Prof. G. Narayanan, Department of Electrical Engineering, IISC Bangalore on the web- |
|----|--|
| 1. | course . http://www.digimat.in/nptel/courses/video/108108035/ |

| Course O | outo | comes: | Bloom's Taxonomy |
|----------|------|---|-------------------|
| Upon com | plet | ion of this course, the students will be able to: | Mapped |
| CO1 | : | Explain the need of PWM | L1: Remembering |
| CO2 | : | Compare the PWM techniques on different aspects | L2: Understanding |
| CO3 | : | Analyze parameter current ripple for different PWM approaches. | L5: Analyzing |
| CO4 | : | Analyze parameters like losses, torque ripple for different PWM approaches. | L4: Analyzing |
| CO5 | : | Develop suitable Pulse Width Modulation method for power converter used | L3: Applying |
| | | for different applications | 11 2 0 |

| COUR | SE AR | RTICU | LATIO | ON MA | TRIX | | | | | | | | | |
|-------------|---------|---------|---------|----------------|---------|---------|---------|---------|---------|----------|----------|----------|----------|------|
| COs/ Pos | PO 1 | PO 2 | PO 3 | PO 4 | PO 5 | PO 6 | PO 7 | PO 8 | PO 9 | PO 10 | PO 11 | PS O1 | PS O2 | PSO3 |
| CO1 | 2 | 2 | 2 | 1 | 1 | | | 1 | 1 | 2 | 1 | 2 | 1 | 2 |
| CO2 | 3 | 1 | 1 | 2 | 2 | | | 1 | 2 | 2 | 1 | 1 | 1 | 1 |
| CO3 | 1 | 1 | 1 | 2 | 1 | | | 2 | 2 | 2 | 2 | 2 | 1 | 2 |
| CO4 | 1 | 2 | 2 | 3 | 3 | | | 2 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO5 | 1 | 1 | 1 | 1 | 1 | | | 1 | 2 | 1 | 1 | 2 | 1 | 2 |
| Avg | 1.6 | 1.4 | 1.4 | 1.8 | 1.6 | 0 | 0 | 1.4 | 1.6 | 1.6 | 1.2 | 1.6 | 1 | 1.6 |

| 18EEHC | 207 | GRID CONVERTERS FOR RENEWABLE APPLICATIONS | ENERGY | SEN | AEST | TER | | |
|-------------|-----------------|--|-------------------------|---------|-----------|---------------|----------|--------|
| PREREC | UIST | | CATEGORY | PF | EC | Cre | dit | 3 |
| Power elec | tronics | 2 | Hours\Week | Ι | | Т | P | TH |
| r ower elec | uomes | 5 | 110u15\week | 3 | 3 | 0 | 0 | 3 |
| Course C | - | | | | | | | |
| 1. To : | introdu | ice the inverter structures and grid integration methods for so | blar and wind energy | systen | ns. | | | |
| UNIT I | P | HOTOVOLTAIC INVERTER STRUCTURES | | | 9 | 0 | 0 | 9 |
| | | peration modes and Solar PV integration with H5 Inverter, | HERIC Inverter. RE | FU In | | - | - | |
| | | Half-Bridge Inverter, Conergy NPC Inverter, Three-Phase PV | | | | , | | |
| UNIT II | | RID SYNCHRONIZATION IN SINGLE ONVERTERS | -PHASE POW | /ER | 9 | 0 | 0 | 9 |
| Grid Sync | | ation Techniques for Single-Phase Systems, Grid Synch | hronization Using t | he Fo | urier | Anal | ysis, | Grid |
| • | | Using a Phase-Locked Loop, PLLs Based on In-Quadratur | 0 | , PLL | Base | d on t | he H | ilbert |
| Transform | , PLL | Based on the Inverse Park Transform, PLLs Based on Adapt | tive Filtering | | | | | |
| UNIT III | G | RID CONVERTER STRUCTURES FOR WIND T | URBINE SYSTEN | AS | 9 | 0 | 0 | 9 |
| | | ystem Power Configurations, Grid Power Converter Topolo | | | | | | |
| | | Converter), Multicell (Interleaved or Cascaded), Wind Turbin | e System Control: Ge | enerat | or-Sid | e Con | trol, | Wind |
| Turbine Sy | stem | Control Grid Control | | | | | | |
| UNIT IV | | RID SYNCHRONIZATION IN THREE-PHASE PO ONVERTERS | OWER | | 9 | 0 | 0 | 9 |
| Reference | Frame Double | ference Frame PLL under Unbalanced and Distorted Gri- e PLL (DDSRF-PLL): Double Synchronous Reference Fra e Second-Order Generalized Integrator FLL (DSOGI-FLL), he DDSRF | ame, Decoupling Ne | twork | and | Analy | vsis o | f the |
| | | | | | 0 | 0 | 0 | |
| UNIT V | | RID CONVERTER CONTROL FOR WIND TURE Control and Direct Power Control: Synchronous Frame VO | | ontrol | 9 Sun/ | 0 | 0 | 9 |
| | | I-Loop Control, Stationary Frame VOC: PQ Open-Loop Co | | | | | | |
| Control, V | irtual-1 | Flux-Based Control, Direct Power Control, Stand-alone, M | licro-grid, Droop Co | ntrol a | and G | rid Su | appor | ting: |
| | ected/S | Stand-Alone Operation without Load Sharing, Micro-Gri | id Operation with (| Contro | lled S | Storag | ge, D | roop |
| Control | | | | | | | | |
| | | | Tota | al (45 | L+07 | Г) = 4 | 5 Pei | riods |
| | | | | | | | | |
| Text Boo | | | | | | | | |
| | | Feodorescu, Marco Liserre, Pedro Rodríguez, 'Grid Conver EEE Press, 2017 | ters for Photovoltaic | and V | Wind | Power | r Sys | tems, |
| Referenc | e Bool | ks: | | | | | | |
| | | Singh Solanki, " Solar Photovoltaics: Fundamentals, Techno New Delhi, 2011. | ologies and Application | ions", | PHI I | earni | ng Pi | rivate |
| E-Refere | nce | | | | | | | |
| 1 ht | tps://oi | nlinecourses.nptel.ac.in/noc22_ee71 | | | | | | |
| • | | · - | | | | | | |

| Course C | | | Bloom's Taxonomy |
|----------|------|--|------------------|
| Upon com | plet | ion of this course, the students will be able to: | Mapped |
| C01 | : | Understand the configurations for inverter structures for solar photovoltaic system | L1: Remembering |
| CO2 | : | Use grid synchronization technique for single phase converters | L3: Applying |
| CO3 | : | Draw the topology structure of three phase converter for wind energy conversion system | L3: Applying |
| CO4 | : | Understand the principle of grid converter control for wind energy conversion system | L1-Remembering |
| CO5 | : | Select an grid synchronization scheme for three phase converters | L4-Analyzing |

| COUR | SE AR | | LAIIC | JN MA | ΙΚΙΧ | | | | | | | | | | |
|-------------|---------|---------|---------|----------|---------|----------|----------|---------|---------|----------|----------|----------|----------|----------|----------|
| COs/ POs | PO 1 | РО 2 | PO 3 | PO 4 | РО 5 | PO 6 | PO 7 | PO 8 | PO 9 | PO 10 | РО 11 | PO 12 | PS O1 | PS O2 | PS O3 |
| CO1 | 2 | 2 | 3 | 2 | 2 | | | 1 | | 2 | | 2 | 2 | 1 | 3 |
| CO2 | 1 | 3 | | 2 | 2 | | | | | 2 | | 1 | 1 | 2 | |
| CO3 | 1 | 1 | 2 | | | 1 | 2 | | 1 | | | | 1 | 1 | 2 |
| CO4 | 1 | 1 | 1 | | | | 2 | 2 | 1 | | 2 | 2 | 1 | 1 | 1 |
| CO5 | 1 | 2 | 1 | 1 | 1 | 2 | 1 | | | 1 | 3 | | 2 | 2 | 1 |
| Avg | 1.2 | 1.8 | 1.75 | 1.67 | 1.67 | 1.5 | 1.67 | 1.5 | 1 | 1.67 | 2.5 | 1.67 | 1.4 | 1.4 | 1.75 |
| | | 1 | 3/2/1-i | ndicates | strengt | h of cor | relation | (3- Hig | h, 2-Me | edium, 1 | - Low) | | | | |

| PREREQUISIT | SOURCES | EWABLE ENERGY | SEMI | ESTE | R | |
|---|---|--|--|--|---------------------------------|--|
| | ES | CATEGORY | PEC | Cre | dit | 3 |
| | | Hours/Week | L | T | P | TH |
| | | | 3 | 0 | 0 | 3 |
| Course Objecti | | | | | | |
| | electric power Generation, Transmission and Distri | ibution | | | | |
| 2. To study Pov | er System Operation and Control | | | | | |
| UNIT I INT | RODUCTION | | 9 | 0 | 0 | 9 |
| | ity ideal features, Supply guarantee, power qual penetration into the grid, Boundaries of the act | | | | | |
| UNIT II DY | NAMIC ENERGY CONVERSION TECHN | NOLOGIES | 9 | 0 | 0 | 9 |
| Introduction, type | s of conventional and nonconventional dynamic | generation technologies | | ple of | f ope | |
| and analysis of re | ciprocating engines, gas and micro turbines, hydro a | nd wind based generation | technolo | ogies | | |
| UNIT III STA | TIC ENERGY CONVERSION TECHNO | LOGIES | 9 | 0 | 0 | 9 |
| Linear and nonlin | NTROL ISSUES AND CHALLENGES ar controllers, predictive controllers and adaptive c Techniques, Control of Diesel, PV, wind and fuel c illities. | | | | | |
| | | CONVERSION | I | | | |
| | EGRATION OF ENERGY CHNOLOGIES | CONVERSION | 9 | 0 | 0 | 9 |
| | mportance, sizing, Optimized integrated system ol, Grid connected Photovoltaic systems –classif ty and protection issues, load sharing, operation cations. IEEE & IEC Codes and standards for re | ications, operation, meri n & control of hybrid | its & de energy grations | emerits syste | s; Isla ms, | |
| Operations, stabil Photovoltaic appl | | Total | (45L+0 | \mathbf{T}) = 4 | 45 Pe | eriod |
| Operations, stabil Photovoltaic appl Text Books: | and Efficient Electric Power Systems. G. Masters 11 | | | | | |
| Operations, stabil Photovoltaic appl Text Books: 1. Renewable Edition | and Efficient Electric Power Systems, G. Masters, I | EEE-John Wiley and Son | s Ltd. Pu | ıblishe | rs, 20 | 013,2ª |
| Operations, stabil Photovoltaic appl Text Books: 1. Renewable Edition 2. Microgrids | and Active Distribution Networks, S.Chowdh | EEE-John Wiley and Son | s Ltd. Pu | ıblishe | rs, 20 | 013,2 ⁿ |
| Operations, stabil Photovoltaic appl Text Books: 1. Renewable Edition 2. Microgrids Electronics 3 Integration | • • • • | EEE-John Wiley and Son ury, S. P. Chowdhury | s Ltd. Pu | ıblishe sley, | rs, 20 IET | 013,2" Powe |
| Operations, stabil Photovoltaic appl Text Books: 1. Renewable Edition 2. Microgrids Electronics 3. Integration | and Active Distribution Networks, S.Chowdh Series, 2012. and Control of Renewable Energy in Electric Powe Viley publishing company, 2010, 2 nd Edition. | EEE-John Wiley and Son ury, S. P. Chowdhury | s Ltd. Pu | ıblishe sley, | rs, 20 IET | 013,2 ⁿ Powe |
| Operations, stabil Photovoltaic appl Text Books: 1. Renewable Edition 2. Microgrids Electronics 3. Integration Dai, John V Reference Book | and Active Distribution Networks, S.Chowdh Series, 2012. and Control of Renewable Energy in Electric Powe Viley publishing company, 2010, 2 nd Edition. | EEE-John Wiley and Son ury, S. P. Chowdhury er System, Ali Keyhani N | s Ltd. Pu , P.Cros Mohamm | iblishe isley, nad Ma | rs, 20 IET arwal | 113,2 ⁿ Power |
| Operations, stabil Photovoltaic appl Text Books: 1. Renewable Edition 2. Microgrids Electronics 3. Integration Dai, John V Reference Book 1. Solar Photo Edition. 2. Solar PV | and Active Distribution Networks, S.Chowdh Series, 2012. and Control of Renewable Energy in Electric Power Viley publishing company, 2010, 2 nd Edition. | EEE-John Wiley and Son ury, S. P. Chowdhury er System, Ali Keyhani M s, Chetan Singh Solanki, | s Ltd. Pu , P.Cros Mohamm PHI Pul | iblishe ssley, nad Ma blisher | rs, 20 IET arwal s, 20 | 113,2 ⁿ Powe i, Mir 19, 3 ^r |

| 4. | Power Conversion and Control of Wind Energy Systems, Bin Wu, Yongqiang Lang, NavidZargari, IEEE- John Wiley and Sons Ltd. Publishers,2011,1 st Edition. |
|----|--|
| 5. | Report on "Large Scale Grid Integration of Renewable Energy Sources - Way Forward" Central Electricity Authority, GoI, 2013. |

| Course O | outo | comes: | Bloom's Taxonomy |
|----------|-------------------|---|------------------|
| Upon com | Mapped | | |
| CO1 | L2: Understanding | | |
| CO2 | : | Model and simulate renewable energy sources. | L5: Evaluating |
| CO3 | : | Apply various MPPT techniques for wind and solar energy generation | L3: Applying |
| CO4 | : | Analyze and simulate control strategies for grid connected and off-grid systems | L4: Analyzing |
| CO5 | : | Develop converters to comply with grid standards to obtain grid integration | L6: Creating |

| COs/ POs | PO 1 | РО 2 | PO 3 | РО 4 | РО 5 | PO 6 | РО 7 | PO 8 | PO 9 | PO 10 | PO 11 | PO 12 | PS O1 | PS O2 | PS O3 |
|-------------|---------|---------|---------|---------|---------|---------|---------|---------|---------|----------|----------|----------|----------|----------|----------|
| CO1 | 2 | 2 | 2 | 2 | 3 | 3 | 1 | 1 | 2 | 1 | 2 | 3 | 3 | 3 | 3 |
| CO2 | 3 | 2 | 3 | 3 | 3 | 3 | 1 | 1 | 2 | 1 | 2 | 1 | 3 | 3 | 3 |
| CO3 | 3 | 2 | 3 | 3 | 3 | 3 | 1 | 1 | 1 | 2 | 1 | 1 | 3 | 3 | 3 |
| CO4 | 3 | 2 | 3 | 3 | 3 | 3 | 1 | 2 | 2 | 2 | 1 | 1 | 3 | 3 | 3 |
| CO5 | 3 | 2 | 3 | 3 | 3 | 3 | 1 | 2 | 2 | 2 | 2 | 1 | 3 | 3 | 3 |
| Avg | 2.8 | 2 | 2.8 | 2.8 | 3 | 3 | 1 | 1.4 | 1.8 | 1.6 | 1.6 | 1.4 | 3 | 3 | 3 |

| 18EE J | HO209 | | | Μ | IODERN | ELECT | RICAL DRI | VES | SEME | ESTE | R | |
|--|---|---|--|---|---|---|--|--|---|----------------------|------------------------|-----------------------------|
| PRER | REQUIS | ITES | | | | | | CATEGORY | PEC | Cı | edit | 3 |
| Electri | cal Drives | s and o | ontrol. | | | | | Hours\Week | L 3 | T | P | TH |
| G | | | | | | | | | 3 | 0 | 0 | 3 |
| | se Object | | | | | | | | | | | |
| | | | | | lectrical dr | | | | | | | |
| | | | | | | for DC mot based contro | | | | | | |
| 5. | To unders | stanu | | epts of var | | | | | | | | |
| UNIT | 'I D | DC M | OTOR | DRIVES | S: | | | | 9 | 0 | 0 | 9 |
| Modeli | ing of DC | c moto | rs, State | space mo | deling, blo | ck diagram | & Transfer fun | ction, Single phase, th | nree phase | es full | y cont | trolled |
| | | | | | | | | pop control of separat | ely excite | d dc | motor | drive. |
| Supply | harmonic | cs and | ripple ii | n motor cu | irrent chop | per controll | ed DC motor d | rives. | | | | |
| UNIT | TI II | NDU | CTION | ΜΟΤΟ | R DRIVE | FS | | | 9 | 0 | 0 | 9 |
| | | | | | | | eling of induc | tion machines, voltag | - | | | |
| | | | | | flux contro | | ching of induc | tion machines, voitag | | verter | cont | 101-1/1 |
| TINITT | | N/NIC | ΠΡΟΝ | | | DIVES | | | 0 | 0 | Δ | 0 |
| UNIT | | | | | OTOR DI | | | irect torque control, C | 9 | 0 | 0 | 9 |
| drives. | | ICHIOI | ous mac | miles, op | EII IOOD V/I | | ctor control, a | fiect torque control, C | SI Ieu sy | /ncm (| mous | motor |
| | | | | | | | | | | | | |
| | | | | | - | | | TED DELLICTAN | CE | | | |
| UNIT | P | | IANEN DR DR | T MAG | - | | | HED RELUCTAN | CE 9 | 0 | 0 | 9 |
| UNIT Modeli | IV P Ming of syn | MOT hchror | OR DR | T MAG IVES hines, ope | NET MC en loop v/f | DTOR AN f control, ve | ND SWITCI | irect torque control, C | CSI fed sy | | | - |
| UNIT Modeli | IV P Ming of syn | MOT hchror | OR DR | T MAG IVES hines, ope | NET MC en loop v/f | DTOR AN f control, ve | ND SWITCI | | CSI fed sy | | | - |
| UNIT Modeli drives. | TIV P M ing of syn Various t | AOT nchror topolo | OR DR ous mac gies for | T MAG IVES hines, ope SRM drive | en loop v/f | DTOR AN f control, ve ison, Closed | ND SWITCI | irect torque control, C | CSI fed sy | | | - |
| UNIT Modeli drives. UNIT | IV P Ming of syn Various te | AOT nchror topolo DSP E | OR DR ous mac gies for a | T MAG IVES hines, op SRM drive | NET MC en loop v/f es, compar | DTOR AN f control, ve ison, Closed | ND SWITCI ector control, d d loop speed an | irect torque control, C d torque control of SF | SI fed sy M. | /nchro | onous | motor 9 |
| UNIT Modeli drives. UNIT Use of | IV P Ming of syn Various te | AOT hchror topolo DSP E motio | OR DR ous mac gies for a | T MAG IVES hines, op SRM drive | NET MC en loop v/f es, compar | DTOR AN f control, ve ison, Closed | ND SWITCI ector control, d d loop speed an | irect torque control, C | SI fed sy M. | /nchro | onous | motor 9 |
| UNIT Modeli drives. UNIT Use of | IV P N ing of syn Various to V D S DSPs in 1 | AOT hchror topolo DSP E motio | OR DR ous mac gies for a | T MAG IVES hines, op SRM drive | NET MC en loop v/f es, compar | DTOR AN f control, ve ison, Closed | ND SWITCI ector control, d d loop speed an | irect torque control, C d torque control of SF basic blocks in DSP f | SI fed sy M. | nchro 0 nentat | onous 0 tion of | motor 9 5 DSP |
| UNIT Modeli drives. UNIT Use of | IV P N ing of syn Various to V D S DSPs in 1 | AOT hchror topolo DSP E motio | OR DR ous mac gies for a | T MAG IVES hines, op SRM drive | NET MC en loop v/f es, compar | DTOR AN f control, ve ison, Closed | ND SWITCI ector control, d d loop speed an | irect torque control, C d torque control of SF basic blocks in DSP f | CSI fed sy RM. 9 for implen | nchro 0 nentat | onous 0 tion of | motor 9 5 DSP |
| UNIT Modeli drives. UNIT Use of | P P ing of syn Various t Various t D DSPs in r motion con | AOT hchror topolo DSP E motio | OR DR ous mac gies for a | T MAG IVES hines, op SRM drive | NET MC en loop v/f es, compar | DTOR AN f control, ve ison, Closed | ND SWITCI ector control, d d loop speed an | irect torque control, C d torque control of SF basic blocks in DSP f | CSI fed sy RM. 9 for implen | nchro 0 nentat | onous 0 tion of | motor 9 5 DSP |
| UNIT Modeli drives. UNIT Use of based r | IV P Ming of syn Various to Various to DSPs in 1 motion con Books: | AOT achror topolo DSP E motio ntrol. | OR DR ous mac gies for s ASED n contro | T MAG IVES hines, op SRM drive MOTIO I, various | NET MC en loop v/f es, compar N CONT DSPs avai | DTOR AN f control, ve ison, Closed 'ROL lable, realiz | ND SWITCI ector control, d d loop speed an eation of some | irect torque control, C d torque control of SF basic blocks in DSP f | CSI fed sy RM. 9 for implen | nchro 0 nentat | onous 0 tion of | motor 9 5 DSP |
| UNIT Modeli drives. UNIT Use of based r Text B | IV P ing of syn N Various tr D DSPs in r D DSPs in r D Books: B. K. B | AOT Anchror topolo DSP F motio ntrol. Gose, " rause, | OR DR ous mac gies for 3 ASED n contro | T MAG IVES hines, op SRM drive MOTIO I, various | NET MC en loop v/f es, compar N CONT DSPs avai | DTOR AN f control, ve ison, Closed ROL lable, realiz | ND SWITCI ector control, d d loop speed an extion of some es", Pearson Ec | irect torque control, C d torque control of SF basic blocks in DSP f Tota | CSI fed sy RM. or implen | nentat | 0 iion of | motor 9 DSP eriods |
| UNIT Modeli drives. UNIT Use of based r Text B 1. 2. | IV P ing of syn Various t V D DSPs in 1 motion con Books: B. K. Be P. C. Ku | AIOT anchror topolo DSP E motio ontrol. Bose, " rause, 013. | OR DR ous mac gies for 3 ASED n contro | T MAG IVES hines, op SRM drive MOTIO I, various | NET MC en loop v/f es, compar N CONT DSPs avai | DTOR AN f control, ve ison, Closed ROL lable, realiz | ND SWITCI ector control, d d loop speed an extion of some es", Pearson Ec | irect torque control, C d torque control of SF basic blocks in DSP f Tota lucation, Asia, 2003. | CSI fed sy RM. or implen | nentat | 0 iion of | motor 9 DSP eriods |
| UNIT Modeli drives. UNIT Use of based r Text B 1. 2. | P P ing of syn N Various t V V D DSPs in r motion con Books: B. K. Bo B. K. Bo P. C. Kn Sons, 20 Sons, 20 | AIOT anchror topolo DSP E motio ontrol. Bose, " rause, 013. Ss: 'aliyat | OR DR ous mac gies for ASED n contro | T MAG IVES hines, op SRM drive MOTIO I, various | ENET MC en loop v/f es, compar N CONT DSPs avai | DTOR AN f control, ve ison, Closed ROL lable, realiz | ND SWITCI ector control, d d loop speed an ation of some es", Pearson Ec alysis of Electri | irect torque control, C d torque control of SF basic blocks in DSP f Tota lucation, Asia, 2003. | CSI fed sy RM. 9 for implem 1 (45L+0 7e System | nentat | 0 iion of | motor 9 DSP eriods |
| UNIT Modeli drives. UNIT Use of based r Text B 1. 2. Refere | P P ing of syn Various t Various t D DSPs in r D DSPs in r D DOSPs in r D Books: B. K. Ba B. K. Ba P. C. Kr Sons, 20 Ence Book H. A. Ta press, 20 | AIOT hchror topolo DSP E motio ontrol. Gose, " rause, 013. cs: Caliyat 2003 hnan, | OR DR ous mac gies for 3 ASED n contro Modern O. Was and S. C | T MAG IVES hines, ope SRM drive MOTIO I, various | en loop v/f es, compar N CONT DSPs avai ectronics ar id S. D. Sud | DTOR AN f control, ve ison, Closed (ROL lable, realiz nd AC Drive dhoff, "Ana pased Electr | ND SWITCI ector control, d 100p speed and d loop speed and 1000 speed and eation of some 1000 speed and </td <td>irect torque control, C d torque control of SF basic blocks in DSP f Tota lucation, Asia, 2003. c Machinery and Driv</td> <td>CSI fed sy RM. 9 for implem 1 (45L+0 7e System</td> <td>nentat</td> <td>0 iion of</td> <td>motor 9 DSP eriods</td> | irect torque control, C d torque control of SF basic blocks in DSP f Tota lucation, Asia, 2003. c Machinery and Driv | CSI fed sy RM. 9 for implem 1 (45L+0 7e System | nentat | 0 iion of | motor 9 DSP eriods |

| Course Ou Upon com | | mes: on of this course, the students will be able to: | Bloom's Taxonomy Mapped |
|-----------------------|---|---|----------------------------|
| CO1 | : | Apply Power converters for DC drives. | L1: Remembering |
| CO2 | : | Understand the basics of Permanent magnet motor and Switched reluctance motor drives. | L2: Understanding |
| CO3 | : | Learn the concepts of Synchronous motor drives. | L5: Evaluating |

| CO4 | : | Gain knowledge of Induction motor drives. | L4: Analyzing |
|-----|-----|---|---------------|
| CO5 | ••• | Explain DSP based motion control. | L3: Applying |

| COUR | SE AR | TICU | LATIC | ON MA | TRIX | | | | | | | | | | |
|-------------|---------|---------|---------|----------|-----------|----------|----------|---------|---------|----------|----------|----------|----------|----------|----------|
| COs/ POs | PO 1 | PO 2 | РО 3 | РО 4 | РО 5 | PO 6 | PO 7 | PO 8 | PO 9 | PO 10 | PO 11 | PO 12 | PS O1 | PS O2 | PS O3 |
| CO1 | 1 | 1 | 3 | 2 | 2 | 1 | 1 | 1 | | | 1 | 1 | 1 | 1 | 1 |
| CO2 | 3 | 3 | 3 | 3 | 3 | 1 | 1 | 1 | | | 1 | 1 | 3 | 3 | 3 |
| CO3 | 1 | 3 | 3 | 3 | 3 | 1 | 1 | 1 | | | | | 1 | 3 | 1 |
| CO4 | 1 | 3 | 3 | 3 | 3 | 1 | 1 | 1 | | | | 1 | 1 | 3 | 1 |
| CO5 | 3 | 3 | 3 | 3 | 3 | 1 | 1 | 1 | | | 1 | 1 | 3 | 3 | 3 |
| Avg | 1.8 | 2.6 | 3 | 2.8 | 2.8 | 1 | 1 | 1 | 0 | 0 | 1 | 1 | 1.8 | 2.6 | 1.8 |
| | | | 3/2/1-i | ndicates | s strengt | h of cor | relation | (3- Hig | h, 2-Me | edium, 1 | - Low) | | | | |

PROGRAMME ELECTIVE COURSE VERTICALS FOR HONOURS / MINOR DEGREE

VERTICAL III: ELECTRIC VEHICLE TECHNOLOGY

| 18F | EHO | 301 ELECTRIC VEHICLE ARCHITEC | TURE | SEM | IES | TER | 2 | |
|--------|----------|--|-------------------------|---------|-------|----------------|--------|--------|
| | | ISTIES | CATEGORY | PEC | | Cre | | 3 |
| | | | | L | | T | P | TH |
| Electr | ic Driv | es, Energy management, Electric Vehicles | Hours/Week | 3 | | 0 | 0 | 3 |
| | | jectives: | | | | - | | |
| 1. | To pr | ovide knowledge about electric vehicle architecture and power trai | n components. | | | | | |
| 2. | - | ow the concepts of dynamics of electrical vehicles | Ĩ | | | | | |
| 3. | To im | part knowledge on vehicle control for standard drive cycles of hyb | rid electrical vehicles | s (HEV | s) | | | |
| 4. | To un | derstand the concept of energy storage systems | | | | | | |
| 5. | To pr | ovide knowledge about different energy sources and energy manag | ement in HEVs. | | | | | |
| | | | | | | | | |
| UNI | ſI | HYBRID ELECTRIC VEHICLE ARCHITECTUR TRAIN COMPONENTS | RE AND POWI | ER 9 | | 0 | 0 | 9 |
| Histor | ry of ev | volution of Electric Vehicles - Comparison of Electric Vehicles w | ith Internal Combust | ion Eng | gines | s - A | rchite | ecture |
| of Ele | ectric V | Vehicles (EV) and Hybrid Electric Vehicles (HEV) - Plug-in H | | | | | | |
| comp | onents | and sizing, Gears, Clutches, Transmission and Brakes. | | | | | | |
| | | | | | | | | |
| UNI | | MECHANICS OF HYBRID ELECTRIC VEHICLES | | 9 | | 0 | 0 | 9 |
| | | s of vehicle mechanics - tractive force, power and energy require and power rating and battery capacity. | rements for standard | drive | сус | cles o | of HE | V's - |
| motor | lorque | and power rating and battery capacity. | | | | | | |
| UNI | ГШ | CONTROL OF DC AND AC MOTOR DRIVES | | 9 | | 0 | 0 | 9 |
| | | of for constant torque, constant HP operation of all electric m | otors - DC/DC cho | | | - | - | |
| | | DC motor drives, inverter based V/f Operation (motoring and bra | | | | | | |
| opera | tion of | Induction motor and PMSM, Brushless DC motor drives, Switcher | l reluctance motor (S | RM) di | rives | 5 | | |
| | | | | | | | | |
| UNI | | ENERGY STORAGE SYSTEMS | | 9 | | 0 | 0 | 9 |
| | | ciple of operation, types, models, estimation of parameters, batter | | | | | | |
| Fly w | - | acity for standard drive cycles, Vehicle to Grid operation of EV's. | Alternate sources: F | uer cer | is, c | Jura | capac | mors, |
| 1 Iy w | neers. | | | | | | | |
| UNI | ГΥ | HEV CONTROL STRATEGY AND ENERGY MANA | GEMENT | 9 | | 0 | 0 | 9 |
| | | isory control - Selection of modes - power spilt mode - parallel 1 | | | | gener | ation | |
| | | el mode - energy management of HEV's. | 6 | | | | | |
| | | | | | | | | |
| | | | Total | (45L- | +0T | ')= 4 : | 5 Pe | riods |
| | | | | | | | | |
| Text | Books | | | | | | | |
| 1. | Iqba | al Husain, 'Electric and Hybrid Electric Vehicles', CRC Press, 201 | 1. | | | | | |
| 2. | Wei | Liu, 'Hybrid Electric Vehicle System Modeling and Control', Sec | ond Edition, WILEY | , 2017. | | | | |
| Refe | | Books: | · | | | | | |
| 1. | Jam | es Larminie and John Lowry, 'Electric Vehicle Technology Explai | ned', Second Edition | , 2012. | | | | |
| | | darzi, Gordon A., Hayes, John G, Electric power train: energy syst | | | | | | |
| 2. | driv | es for hybrid, electric & fuel cell vehicles, Wiley 2018 | - | | | | | |
| 3. | Del | Doncker, Rik, Pulle, Duco W.J., Veltman, Andre, Advanced Electr | ical Drives, First Edi | tion, C | RC | | | |
| 5. | Pres | s, Taylor and Francis Group, 2011. | | | | | | |

| 4. | Mehradad Eshani, Yimin Gao, Ali Emadi, Modern Electric, Hybrid Electric, and Fuel Cell Vehicles, Fundamentals, Theory and Design, Second Edition, CRC Press, Taylor and Francis Group, 2010. | | | | | | | | |
|-------|---|--|--|--|--|--|--|--|--|
| | RiK De Doncker, Advanced Electric Drives – Analysis , Modeling ,Control, Springer publications | | | | | | | | |
| E-Ref | erence | | | | | | | | |
| 1 | https://nptel.ac.in/courses/108/106/108106170/ | | | | | | | | |
| 2 | https://nptel.ac.in/courses/108/106/1081061/0/ https://nptel.ac.in/courses/108/102/108102121/ | | | | | | | | |

| Course O |)utc | comes: | Bloom's Taxonomy |
|----------|-------|---|-------------------|
| Upon com | pleti | Mapped | |
| CO1 | : | L1: Remembering | |
| CO2 | : | Acquired the concepts of dynamics of electrical vehicles | L2: Understanding |
| CO3 | : | Apply the vehicle control for standard drive cycles of hybrid electrical vehicles (HEVs). | L3: Applying |
| CO4 | : | Ability to design and select energy storage systems. | L6: Creating |
| CO5 | : | Evaluate different energy sources and energy management in HEVs. | L5: Evaluating |

| COUR | SE AR | TICU | LATIO | ON MA | TRIX | | | | | | | | | | |
|-------------|---------|---------|---------|----------|----------|----------|----------|----------|---------|----------|----------|----------|----------|----------|----------|
| COs/ POs | PO 1 | PO 2 | PO 3 | PO 4 | PO 5 | PO 6 | PO 7 | PO 8 | PO 9 | PO 10 | PO 11 | PO 12 | PS O1 | PS O2 | PS O3 |
| CO1 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 2 | 1 | 1 |
| CO2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 2 | 1 | 1 |
| CO3 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 2 | 1 | 1 |
| CO4 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 2 | 1 | 1 |
| CO5 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 2 | 1 | 1 |
| Avg | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 2 | 1 | 1 |
| | | | 3/2/1-i | indicate | s streng | th of co | rrelatio | n (3- Hi | gh, 2-M | ledium, | 1- Low |) | | | |

| | DESIGN OF MOTORS AND POWER ELECTRIC VEHI | | SEME | STEI | R | |
|---|--|--|---|----------------------|----------|-----------|
| PREREQUIST | | CATEGORY | PEC | Cre | edit | 3 |
| | | Hours/Week | L | Т | Р | T |
| Power Electronic | s, Special Electrical Machines | Hours/ week | 3 | 0 | 0 | 3 |
| Course Object | ives: | | | | | |
| 1. To study t | he characteristics of motors used Electric Vehicle | | | | | |
| | tand the design of dc drives used in Electric Vehicl | e | | | | |
| | e the ac drives used in Electric Vehicle | | | | | |
| 4. To unders | tand the role of converters used in Electric Vehicle | | | | | |
| | | | 9 | 0 | 0 | 0 |
| | V MOTORS CHARACTERISTICS | 1 | - | 0 | | 9 |
| | in, Tractive effort in normal driving, Comparison of tor, Torque speed characteristics, DC Motor dynam | | Four quad | rant o | perati | on |
| UNIT II DI | ESIGN OF DC DRIVES | | 9 | 0 | 0 | 9 |
| | variable speed chopper fed DC drives, Four quad | rant variable sneed chonner fed | - | Ŷ | ÷ | |
| | erter, Dual converter fed DC Drive, current loop | | | | | |
| | lers and firing circuits. | ···· | , , , | | | |
| | ~ | | | | | |
| UNIT III IN | VERTER FED AC DRIVES | | 9 | 0 | 0 | 9 |
| Analysis of diffe | rent AC motor with single phase and three phase in | nverters Operations in different | modes and | l conf | igura | tion |
| | ERMANENT MAGNET AC MOTORS ANI modelling, torque equations, BLDC control met | | 9 | 0 | 0 | 9 |
| | modeling, torque equations, blbc control met | hods machine sizing current | voltage a | nd sn | eed | imi |
| | nt power speed range, current control methods- Ap | | | | | imi |
| | | | | | s. | |
| UNIT V PV Sinusoidal PWM | VM AND INVERTER I, Injection of third order harmonics, Space Ve | plication of hall current sensor i | n PM AC | motor 0 | •s. 0 | 9 |
| UNIT V PV Sinusoidal PWM | VM AND INVERTER I, Injection of third order harmonics, Space Ve | plication of hall current sensor i | n PM AC | motor 0 | •s. 0 | 9 |
| UNIT V PV Sinusoidal PWM | VM AND INVERTER I, Injection of third order harmonics, Space Ve | plication of hall current sensor i | n PM AC | motor 0 sation | s. 0 Enc | 9 ode |
| UNIT V PV Sinusoidal PWM Resolvers, R/D C | VM AND INVERTER I, Injection of third order harmonics, Space Ve | plication of hall current sensor i | n PM AC | motor 0 sation | s. 0 Enc | ode |
| UNIT V PV Sinusoidal PWM Resolvers, R/D C Text Books: | VM AND INVERTER I, Injection of third order harmonics, Space Ve Converters. | plication of hall current sensor is ctor Modulation, Dead time & Tota | n PM AC | motor 0 sation | s. 0 Enc | 9 ode |
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| UNIT V PV Sinusoidal PWM Resolvers, R/D C Text Books: 1. B.K. Bo Reference Boo 1. H. Buys Holland | VM AND INVERTER I, Injection of third order harmonics, Space Ve converters. se, "Power Electronics and Motor Drives", Elsevie ks: e and I.J. Robert, "Electrical machines and convert | plication of hall current sensor is ctor Modulation, Dead time & Tota r 2015. ers: Modeling and simulation", I | n PM AC 9 c compen 1 (45L+0 North | motor 0 sation | s. 0 Enc | 9 ode |
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| Course O | uto | comes: | Bloom's Taxonomy |
|-----------|-------|--|-------------------|
| Upon comp | oleti | ion of this course, the students will be able to: | Mapped |
| CO1 | ••• | Describe the characteristics of the motors use in EV. | L1: Remembering |
| CO2 | ••• | Analyze dynamics of DC motor and different controllers used in their control | L4: Analysing |
| CO3 | ••• | Explain the speed control and PWM techniques used in the control of ac motor | L2: Understanding |
| CO4 | ••• | Analyze the operation and control of permanent magnet ac motors. | L4: Analyzing |
| CO5 | ••• | Analyze sensors used for control of 3-phase ac motors. | L4: Analysing |

| COs/ POs | PO 1 | РО 2 | PO 3 | PO 4 | РО 5 | PO 6 | РО 7 | PO 8 | PO 9 | PO 10 | PO 11 | PO 12 | PS O1 | PS O2 | PS O3 |
|-------------|---------|---------|---------|---------|---------|---------|---------|---------|---------|----------|----------|----------|----------|----------|----------|
| CO1 | 2 | 2 | 3 | 1 | 1 | | 1 | 1 | | | 1 | | 2 | 2 | 1 |
| CO2 | 2 | 2 | 1 | 1 | 1 | | | | | | | | 1 | 1 | 2 |
| CO3 | 1 | 2 | 3 | 2 | 2 | | 1 | 1 | | | | 1 | 1 | 2 | 1 |
| CO4 | 2 | 2 | 3 | 2 | 3 | 2 | | | | | | 1 | 3 | 2 | 1 |
| CO5 | 1 | 3 | 2 | 1 | 3 | 1 | 1 | 1 | | | 1 | 1 | 3 | 2 | 1 |
| Avg | 1.6 | 2.2 | 2.4 | 1.4 | 2 | 1.5 | 1 | 1 | 0 | 0 | 1 | 1 | 2 | 1.8 | 1.2 |

| PREREQUISITES | LECTRIC VEHICLE DESIGN, MEC | HANICS AN | DCONIKOL | SE | MES | STEF | ζ. |
|--|---|--|--|--|--|--|---|
| | | | CATEGORY | L | Т | P | С |
| | | | | | | | |
| Power Electronics and | Electrical Machines | | PEC | 3 | 0 | 0 | 3 |
| Course Objectives: | | | | | • | • | |
| 1. To learn the ba | sics of EV and vehicle mechanics | | | | | | |
| | <i>V</i> architecture and to study the energy storage | system concer | ots | | | | |
| | I for batteries and to know the different types | | | thods | | | |
| | ntrol preliminaries for DC-DC converters. | | | | | | |
| I | • | | | | | | |
| UNIT I INTEF | NAL COMBUSTION ENGINES | | | 9 | 0 | 0 | 9 |
| | and BSFC, Vehicle Fuel Economy, Emiss | ion Control S | Systems Treatme | | • | - | |
| | n of Internal Combustion Engine and Electric | | | | | | |
| all-electric vehicles. | n of merina Compusion Engine and Decar | e veniere, reev | iew of light , met | arum | , una | neu , | , aa |
| | | | | | | | |
| UNIT II ELEC | TRIC VEHICLES AND VEHICLE ME | CHANICS | | 9 | 0 | 0 | 9 |
| | V), Hybrid Electric Vehicles (HEV), E | | - Comparisons | - | ÷ | | |
| | hicles- Fundamentals of vehicle mechanics. | ingine ratings | Comparisons | | | iui ii | nem |
| | | | | | | | |
| UNIT III BATT | ERY MODELING, TYPES AND CHAI | PCINC | | 9 | 0 | 0 | 9 |
| | and Hybrid Vehicles - Battery Basics | | | | - | - | - |
| | ery - Nickel-Metal-Hydride (Ni MH) Batte | | | | | | |
| | | 1 1 D | | | | D | |
| Battery, Sodium-Sul | ohur Battery, Sodium-Metal-Chloride, Re | search and D | | | anced | Bat | terie |
| | ohur Battery, Sodium-Metal-Chloride, Re ectric Circuit Models. Battery Pack Manager | | evelopment for | | anced | Bat | terie |
| | | | evelopment for | | anced | Bat | terie |
| Battery Modelling, El | | | evelopment for | | anced | Bat | terie |
| Battery Modelling, El | ectric Circuit Models. Battery Pack Manager | ment, Battery (| evelopment for Charging. | Adva 9 | 0 | 0 | 9 |
| Battery Modelling, El UNIT IV CONT Control Design Prelin | ectric Circuit Models. Battery Pack Manager ROL PRELIMINARIES | ment, Battery (- Bode plot and | evelopment for Charging. alysis for First orc | Adva 9 der an | 0 Id se | 0 cond | 9 ord |
| Battery Modelling, El UNIT IV CONT Control Design Prelin systems - Stability | ROL PRELIMINARIES inaries - Introduction - Transfer Functions – Transient Performance- Power transfer f | ment, Battery (- Bode plot and | evelopment for Charging. alysis for First orc | Adva 9 der an | 0 Id se | 0 cond | 9 ord |
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| Course O | outo | comes: | Bloom's Taxonomy |
|----------|------|---|-------------------|
| Upon com | plet | ion of this course, the students will be able to: | Mapped |
| CO1 | : | To describe the concepts related with EV, HEV and to compare the same | L2: Understanding |
| | | with internal combustion engine vehicles | |
| CO2 | : | To find gain margin & phase margin for various types of transfer functions of | L5: Evaluating |
| | | boost converter | |
| CO3 | : | To demonstrate the Control of A.C Machines | L3: Applying |
| CO4 | : | To explain the concepts related with batteries and parameters of battery | L4: Analyzing |
| CO5 | : | To module the battery and to study the research and development for batteries | L6: Creating |

| COUR | SE AR | RTICU | LATIO | ON MA | TRIX | | I | I | I | I | I | I | I | I | I |
|-------------|---------|---------|---------|----------|------------|---------|----------|-----------|----------|----------|----------|----------|----------|----------|----------|
| COs/ POs | РО 1 | РО 2 | РО 3 | PO 4 | РО 5 | PO 6 | РО 7 | PO 8 | PO 9 | PO 10 | PO 11 | PO 12 | PS O1 | PS O2 | PS O3 |
| CO1 | 3 | | | | | | | | 1 | 2 | | 2 | 3 | | 3 |
| CO2 | 3 | | | | | | | | 1 | 2 | | 2 | 3 | | 3 |
| CO3 | 3 | | | | | | 3 | | 1 | 2 | | 2 | 3 | | 3 |
| CO4 | 3 | | | | | | 3 | | 1 | 2 | | 2 | 3 | | 3 |
| CO5 | 3 | | | | | | 3 | | 1 | 2 | | 2 | 3 | 2 | 3 |
| Avg | 3 | 0 | 0 | 0 | 0 | 0 | 3 | 0 | 1 | 2 | 0 | 2 | 3 | 2 | 3 |
| | | | 3/2/ | 1-indica | ites strei | ngth of | correlat | ion (3-] | High, 2- | Mediur | n, 1- Lo | ow) | | | |

| 18EF | ЕНО304 | DESIGN OF ELECTRIC VEHICLE CHARGING | G SYSTEM | SEM | EST | ER | |
|--------|------------|---|-----------------------|-----------|--------|--------|--------|
| PRE | REQUI | STIES | CATEGORY | L | Т | Р | С |
| Electr | ic vehicle | 2 | PEC | 3 | 0 | 0 | 3 |
| Cour | se Obje | ctives: | | | | | |
| 1. | To intro | duce the fundamentals of charging architectures, converter topolo | gies and control sche | mes fo | r elec | tric v | ehicle |
| | chargin | g system | | | | | |
| | | | | | | | |
| UNI | ГІ | CHARGING ARCHITECTURES FOR ELECTRIC V | EHICLES | 9 | 0 | 0 | 9 |
| | | of EV charging architectures, Onboard Chargers, Level 1: Dedi | | | | | |
| | | verter (Semi-fast Charging), Off-Board Chargers, Level 3: Dedicat Bus Architecture, Common DC Bus Architecture | ted Off-Board DC Cl | nargers | (Fast | Char | ging), |
| Com | IIOII AC I | dus Architecture, Common DC Bus Architecture | | | | | |
| UNI | ГП | CONVERTER TOPOLOGIES FOR CHARGING STA | ATION | 9 | 0 | 0 | 9 |
| | | er, Multipulse Rectifier with DC Active Power Filter, Non-isolate | | | | | |
| | | ZVS Full-Bridge Converter, Grid-connected cascaded H-bridge co | | cted Mo | odular | Mult | ilevel |
| Conve | erter base | d integrated charger for split integrated battery pack, Neutral-Point | Clamped Converter | | | | |
| UNI | гш | CONTROL SCHEMES AND CHARGING STANDAR | RDS | 9 | 0 | 0 | 9 |
| Contr | ol Schem | es for Charging Converters, Single-Phase AC-DC Converter Cont | rol, Three-Phase AC | -DC C | onver | | ntrol, |
| | · | d control (VOC) and direct power control (DPC), Electric Vehicle | e / Plug in Hybrid El | lectric ` | Vehic | le cha | rging |
| Stand | ards | | | | | | |
| | | BATTERY TECHNOLOGIES FOR TRANSPORTAT | ION | | | | |
| UNI | ΓIV | APPLICATIONS | | 9 | 0 | 0 | 9 |
| | | m (Ni-Cd) Battery, Nickel-Metal Hydride (Ni-MH), Lithium-Ion | (Li-Ion), Flow Batte | eries, B | attery | Cha | rging |
| Metho | ods, Batte | ry management system | | | | | |
| UNI | гv | LATEST DEVELOPMENTS IN EV CHARGING | | 9 | 0 | 0 | 9 |
| | | rging, Vehicle-to-Grid (V2G) and Vehicle-to-Home (V2H), | EV charging saf | ety co | - | - | |
| consid | lerations, | Grid-Tied Residential charging Systems, Grid-Tied Public ch | | | | | |
| protoc | cols, Cha | ging cable standards | | | | | |
| | | | Total (4 | 15T ⊥0' | T) - 4 | 5 Po | riode |
| | | | 10tal (- | IJLTU | 1)- ٩ | 510 | lious |
| Text | Books: | | | | | | |
| | | n Sachan, P. Sanjeevikumar, Sanchari Deb, Smart Charging Solution | one for Unbrid and F | loctric | Vahio | los V | Vilov |
| 1. | | ner Publishing LLC, 2022 | | lecule | venic | 105, V | viicy- |
| | | . | | | | | |
| Refe | rence Bo | ooks: | | | | | |
| 1. | Mary | Murphy " Electric and Hybrid Vehicles: Principles, Design and 7 | Technology ", Larser | n and H | Keller | Educ | ation, |
| 1. | 2019 | | | | | | |
| E-Re | ference | | | | | | |
| 1 | | /archive.nptel.ac.in/courses/108/103/108103009/ | | | | | |
| 1 | intpo./ | arom (0.11. 0.11. 0001000) 100/ 100/ 100/ 000000 | | | | | |

| Course O | outo | comes: | Bloom's Taxonomy |
|----------|-------|---|------------------|
| Upon com | pleti | ion of this course, the students will be able to: | Mapped |
| CO1 | : | Understand the configurations for chargers for electric vehicle | L1: Remembering |

| CO2 | : | Select a converter topology for electric vehicle charging station | L3: Applying |
|-----|---|---|-------------------|
| CO3 | : | Use an appropriate control scheme for charging converter | L3: Applying |
| CO4 | : | Understand the principle of batteries used for EV charging station | L1: Remembering |
| CO5 | : | Explain the latest developments in Electric vehicle charging technologies | L2: Understanding |

| COUR | SE AF | RTICU | LATIO | ON MA | TRIX | | | | | | | | | | |
|-------------|---------|---------|---------|----------------|----------|----------|-----------|-----------|---------|----------|----------|----------|----------|----------|----------|
| COs/ POs | PO 1 | PO 2 | PO 3 | PO 4 | PO 5 | PO 6 | PO 7 | PO 8 | PO 9 | PO 10 | PO 11 | PO 12 | PS O1 | PS O2 | PS O3 |
| CO1 | 1 | 1 | 2 | 2 | | 2 | | 1 | | 2 | | 2 | 2 | 2 | 2 |
| CO2 | 2 | 1 | | | 1 | | | | | 2 | | 1 | 1 | 3 | |
| CO3 | 2 | 1 | 1 | 2 | 1 | 1 | 2 | | 1 | | | | 1 | 1 | 1 |
| CO4 | 1 | 1 | | 1 | | 2 | 2 | 2 | 1 | | 2 | 2 | 1 | 1 | |
| CO5 | 2 | 2 | 3 | 1 | | 3 | 1 | | | 1 | 3 | | 2 | 2 | 3 |
| Avg | 1.6 | 1.2 | 2 | 1.5 | 1 | 2 | 1.67 | 1.5 | 1 | 1.67 | 2.5 | 1.67 | 1.4 | 1.8 | 2 |
| | • | | 3/2/1-i | ndicates | s streng | th of co | rrelation | i (3- Hig | gh, 2-M | edium, | l-Low) | | | | |

| | CHO305 TESTING OF ELECTRIC VEHIC | | | | STEI | |
|---|--|---|---|--|--------------------------------|----------------------------|
| | REQUISITES | CATEGORY | | Τ | Р | С |
| Electi | rical Machines and Power Electronics | PEC | 3 | 0 | 0 | 3 |
| Cour | rse Objectives: | | | | | |
| l. | To know various standardization procedures | | | | | |
| 2. | To learn the testing procedures for EV & HEV components | | | | | |
| i. | To know the functional safety and EMC | | | | | |
| <u>.</u> | To realize the effect of EMC in EVs | | | | | |
| • | To study the effect of EMI in motor drives and in DC-DC converter | r system | | | | |
| JNIT | ΓΙ EV STANDARDIZATION | | 9 | 0 | 0 | 9 |
| | luction - Current status of standardization of electric vehicle | es, electric Vehicles | | - | - | |
| | ardization Bodies Active in the Field – Standardization activities in d | | | | | |
| | ical Commission - Standardization of Vehicle Components. | Ĩ | | | | |
| | | | | 1 | | |
| JNIT | TESTING OF ELECTRIC MOTORS AND CONTR | | 9 | 0 | 0 | 9 |
| | ELECTRIC AND HYBRID ELECTRIC VEHICLES | | | • | Ĩ | - |
| | Procedure Using M-G Set, electric motor, controller, application of T Test - Motor Test and Controller Test (Controller Only) Tes | | | | | |
| | mometer, Test Strategy, Test Procedure, Discussion on Test Procedure | | | | | |
| ynai | moniecer, rest strategy, rest riocedure, Discussion on rest riocedure | . Test Hocedure Using | AC D | ynann | omen | |
| INIT | Γ III FUNDAMENTALS OF FUNCTIONAL SAFETY AN | ND EMC | 9 | 0 | 0 | 9 |
| | ional safety life cycle - Fault tree analysis - Hazard and risk a | | devel | opme | nt - P | roce |
| nodel | ls - Development assessments - Configuration management - Reli | ability - Reliability | block | dia | grams | s a1 |
| | dancy - Functional safety and EMC - Functional safety as | | | | | |
| | omous vehicles. | na quanty Standards | 1 un | etion | ui sui | oty |
| | | | | | | |
| JNIT | <u>IV</u> EMC IN ELECTRIC VEHICLES | | 9 | 0 | 0 | 9 |
| | luction - EMC Problems of EVs, EMC Problems of Motor D | | | | | |
| | m, EMC Problems of Wireless Charging System, EMC Problem of | Vehicle Controller, EM | C Pro | blems | s of E | Batte |
| Aanag | gement System, Vehicle EMC Requirements. | | | | | |
| JNIT | Γ V EMI IN MOTOR DRIVE AND DC-DC CONVERTE | | | | | |
| | view -EMI Mechanism of Motor Drive System, Conducted Emissio | CR SVSTEM | 0 | 0 | 0 | 0 |
| | | | 9 Syste | 0 em I | 0 GBT | 9 EN |
| | | on Test of Motor Drive | e Syste | em, I | GBT | EN |
| ource | e, EMI Coupling Path, EMI Modelling of Motor Drive System Conducted Emission High-Frequency, Equivalent Circuit of DC-D | on Test of Motor Driven. EMI in DC-DC Co | e Syste | em, I er, E | GBT MI S | EN |
| ource | e, EMI Coupling Path, EMI Modelling of Motor Drive System | on Test of Motor Drivon. EMI in DC-DC Co C Converter System, EN | e Syste onverte AI Cou | em, I er, E ipling | GBT MI S g Path | EN |
| ource | e, EMI Coupling Path, EMI Modelling of Motor Drive System | on Test of Motor Driven. EMI in DC-DC Co | e Syste onverte AI Cou | em, I er, E ipling | GBT MI S g Path | EN |
| ource The C | e, EMI Coupling Path, EMI Modelling of Motor Drive System Conducted Emission High-Frequency, Equivalent Circuit of DC-De | on Test of Motor Drivon. EMI in DC-DC Co C Converter System, EN | e Syste onverte AI Cou | em, I er, E ipling | GBT MI S g Path | EN |
| ource The C | e, EMI Coupling Path, EMI Modelling of Motor Drive System | on Test of Motor Drivon. EMI in DC-DC Co C Converter System, EN | e Syste onverte AI Cou | em, I er, E ipling | GBT MI S g Path | EN |
| ourco The C | e, EMI Coupling Path, EMI Modelling of Motor Drive System Conducted Emission High-Frequency, Equivalent Circuit of DC-De | on Test of Motor Drivon. EMI in DC-DC Co C Converter System, EM Total (4: | e Syste onverte MI Cou | em, I er, E upling Γ) = c | GBT MI S g Path | EN Jourd |
| Che C Che C Refer 1. 2. | e, EMI Coupling Path, EMI Modelling of Motor Drive System Conducted Emission High-Frequency, Equivalent Circuit of DC-De rence Books: Handbook of Automotive Power Electronics and Motor Drive Edition. Electromagnetic Compatibility of Electric Vehicle, Li Zhai, Springer | on Test of Motor Drivon. EMI in DC-DC Co C Converter System, EN Total (4 es, Ali Emadi, Taylon 2021, 1 st Edition. | e Syste onverte MI Cou | em, I er, E upling Γ) = c | GBT MI S g Path | EN Jourd |
| Che C Che C Refer 1. 2. | e, EMI Coupling Path, EMI Modelling of Motor Drive System Conducted Emission High-Frequency, Equivalent Circuit of DC-De rence Books: Handbook of Automotive Power Electronics and Motor Drive Edition. Electromagnetic Compatibility of Electric Vehicle, Li Zhai, Springer EMC and Functional Safety of Automotive Electronics, Kai Borgeest | on Test of Motor Driven. EMI in DC-DC Co <u>C Converter System, El</u> Total (4 es, Ali Emadi, Taylor <u>2021, 1st Edition.</u> t, IET 2018, 1 st Edition. | E Systo onverte MI Cou 5L+07 | Γ = Γ Γ = Γ Γ = Γ | GBT MI S g Path 45 Pe | erio |
| ource The C Refer 1. 2. 3. | e, EMI Coupling Path, EMI Modelling of Motor Drive System Conducted Emission High-Frequency, Equivalent Circuit of DC-De rence Books: Handbook of Automotive Power Electronics and Motor Drive Edition. Electromagnetic Compatibility of Electric Vehicle, Li Zhai, Springer EMC and Functional Safety of Automotive Electronics, Kai Borgeest EMI/EMC Computational Modeling Handbook, Druce Archam bea | on Test of Motor Driven. EMI in DC-DC Co <u>C Converter System, El</u> Total (4 es, Ali Emadi, Taylor <u>2021, 1st Edition.</u> t, IET 2018, 1 st Edition. | E Systo onverte MI Cou 5L+07 | Γ = Γ Γ = Γ Γ = Γ | GBT MI S g Path 45 Pe | erio |
| Source Che C Refer 1. 2. 3. 4. 4. | e, EMI Coupling Path, EMI Modelling of Motor Drive System Conducted Emission High-Frequency, Equivalent Circuit of DC-De rence Books: Handbook of Automotive Power Electronics and Motor Drive Edition. Electromagnetic Compatibility of Electric Vehicle, Li Zhai, Springer EMC and Functional Safety of Automotive Electronics, Kai Borgeest EMI/EMC Computational Modeling Handbook, Druce Archam bea 2012, 2 nd Edition. | on Test of Motor Driven. EMI in DC-DC Co <u>C Converter System, El</u> Total (4 es, Ali Emadi, Taylor <u>2021, 1st Edition.</u> t, IET 2018, 1 st Edition. | E Systo onverte MI Cou 5L+07 | Γ = Γ Γ = Γ Γ = Γ | GBT MI S g Path 45 Pe | erio |
| Source Che C Refer 1. 2. 3. 4. 5. | e, EMI Coupling Path, EMI Modelling of Motor Drive System Conducted Emission High-Frequency, Equivalent Circuit of DC-De rence Books: Handbook of Automotive Power Electronics and Motor Drive Edition. Electromagnetic Compatibility of Electric Vehicle, Li Zhai, Springer EMC and Functional Safety of Automotive Electronics, Kai Borgeest EMI/EMC Computational Modeling Handbook, Druce Archam bea | on Test of Motor Drivon. EMI in DC-DC Co <u>C Converter System, EN</u> Total (4 es, Ali Emadi, Taylon <u>2021, 1st Edition.</u> t, IET 2018, 1 st Edition. ult, colin branch, Oma | e Systo onverte <u>AI Cou</u> 5 L+0 7 | em, I er, E $_1pling$ $\Gamma) = c$ Franc | GBT MI S g Path 45 Pe | EN Jourd |
| ource The C Refer 1. 2. 3. 4. 5. | e, EMI Coupling Path, EMI Modelling of Motor Drive System Conducted Emission High-Frequency, Equivalent Circuit of DC-De rence Books: Handbook of Automotive Power Electronics and Motor Drive Edition. Electromagnetic Compatibility of Electric Vehicle, Li Zhai, Springer EMC and Functional Safety of Automotive Electronics, Kai Borgeest EMI/EMC Computational Modeling Handbook, Druce Archam bea 2012, 2 nd Edition. Automotive EMC, Mark Steffika, Springer 2013, 1 st Edition. | on Test of Motor Drivon. EMI in DC-DC Co <u>C Converter System, EN</u> Total (4 es, Ali Emadi, Taylon <u>2021, 1st Edition.</u> t, IET 2018, 1 st Edition. ult, colin branch, Oma | s System SL+07 & I MI Cou | em, I er, E $_1pling$ $\Gamma) = c$ Franc | GBT MI S g Path 45 Pe | EN Jource erioo |
| ourcci he C Refer 1. 2. 3. 4. 5. | e, EMI Coupling Path, EMI Modelling of Motor Drive System Conducted Emission High-Frequency, Equivalent Circuit of DC-De rence Books: Handbook of Automotive Power Electronics and Motor Drive Edition. Electromagnetic Compatibility of Electric Vehicle, Li Zhai, Springer EMC and Functional Safety of Automotive Electronics, Kai Borgeest EMI/EMC Computational Modeling Handbook, Druce Archam bea 2012, 2 nd Edition. Automotive EMC, Mark Steffika, Springer 2013, 1 st Edition. Electric Vehicle Systems Architecture and Standardization Needs, | on Test of Motor Drivon. EMI in DC-DC Co <u>C Converter System, EN</u> Total (4 es, Ali Emadi, Taylon <u>2021, 1st Edition.</u> t, IET 2018, 1 st Edition. ult, colin branch, Oma | s System SL+07 & I MI Cou | em, I er, E $_1pling$ $\Gamma) = c$ Franc | GBT MI S g Path 45 Pe | EN Jourd |
| Source Che C Refer 1. 2. 3. 4. 5. 6. 6. | e, EMI Coupling Path, EMI Modelling of Motor Drive System Conducted Emission High-Frequency, Equivalent Circuit of DC-De rence Books: Handbook of Automotive Power Electronics and Motor Drive Edition. Electromagnetic Compatibility of Electric Vehicle, Li Zhai, Springer EMC and Functional Safety of Automotive Electronics, Kai Borgeest EMI/EMC Computational Modeling Handbook, Druce Archam bea 2012, 2 nd Edition. Automotive EMC, Mark Steffika, Springer 2013, 1 st Edition. Electric Vehicle Systems Architecture and Standardization Needs, | on Test of Motor Drivon. EMI in DC-DC Co C Converter System, EN Total (4 es, Ali Emadi, Taylor 2021, 1 st Edition. t, IET 2018, 1 st Edition. tult, colin branch, Oma Reports of the PPP Eu | s System SL+07 & I MI Cou | $\mathbf{\Gamma} = \mathbf{r}, \mathbf{E}$ $\mathbf{r}, \mathbf{E}, \mathbf{r}$ $\mathbf{r} = \mathbf{r}$ $\mathbf{r} = \mathbf{r}$ \mathbf{r} \mathbf{r} \mathbf{r} \mathbf{r} \mathbf{r} | GBT MI S g Path 45 Pe | EN ourc erioo 05, |

Course Outcomes:Bloom'sTaxonomyUpon completion of this course, the students will be able to:Mapped

| CO1 | : | To describe the status and other details of standardization of EVs | L1: Remembering |
|-----|---|--|-------------------|
| CO2 | : | To illustrate the testing protocols for EVs and HEV components | L2: Understanding |
| CO3 | : | To analyze the safety cycle and need for functions safety for EV | L4: Analyzing |
| CO4 | : | To analyze the problems related with EMC for EV components. | L4: Analyzing |
| CO5 | : | To evaluate the EMI in motor drive and DC-DC converter system. | L5: Evaluating |

| COUR | SE AF | RTICU | LATIO | ON MA | ATRIX | | | | | | | | | | |
|-------------|---------|----------------|---------|----------|-----------|----------|----------------|----------|---------|----------|----------|----------|----------|----------|----------|
| COs/ POs | PO 1 | PO 2 | PO 3 | PO 4 | PO 5 | PO 6 | PO 7 | PO 8 | PO 9 | PO 10 | PO 11 | PO 12 | PS O1 | PS O2 | PSO 3 |
| CO1 | 3 | 1 | 1 | | | | 2 | | | | | | 3 | | 2 |
| CO2 | 3 | 1 | 1 | | | | 1 | | | | | | 3 | | 2 |
| CO3 | 3 | 1 | 1 | | | | 2 | | | | | | 3 | | 2 |
| CO4 | 3 | 1 | 1 | | | | 1 | | | | | | 3 | | 2 |
| CO5 | 3 | 1 | 1 | | | | 2 | | | | | | 3 | | 3 |
| Avg | 3 | 1 | 1 | 0 | 0 | 0 | 1.6 | 0 | 0 | 0 | 0 | 0 | 3 | 0 | 2.2 |
| | 1 | | 3/2 | /1-indic | ates stre | ength of | f correla | tion (3- | High, 2 | 2-Mediu | m, 1- L | ow) | 1 | | 1 |

| 18EE | HO3 | 06 INTELLIGENT CONTROL OF ELECTRIC VEH | ICLES | SE | MES | STEF | K |
|---|--|--|---|--|---|---|---|
| PREF | REQU | JISITES | CATEGORY | L | Τ | Р | С |
| Power | Electr | ronics and Electric Vehicle | PEC | 3 | 0 | 0 | 3 |
| Cour | se Ob | jectives: | | | | | |
| 1. | Тос | design and drive the mathematical model of a BLDC motor and its charac | acteristics | | | | |
| 2. | | learn the different control schemes for BLDC motor | | | | | |
| 3. | To s | study the basics of fuzzy logic | | | | | |
| 4. | | study the FPGA & VHDL basics | | | | | |
| 5. | | implement fuzzy logic control of BLDC motor in real time | | | | | |
| UNIT | T I | MATHEMATICAL MODEL AND CHARACTERISTICS OF THE BLDC MOTOR | ANALYSIS | 9 | 0 | 0 | 9 |
| Structu | ure and | d Drive Modes - Basic Structure, General Design Method, Drive Mod | les. Mathematica | al Mo | del, | Diffe | rentia |
| | | ransfer Functions, State-Space Equations. Characteristics Analysis, St | tarting Charact | eristi | cs, S | teady | -Stat |
| Operat | tion, I | Dynamic Characteristics, Load Matching Commutation Transients | | | | | |
| UNIT | П | SPEED CONTROL FOR ELECTRIC DRIVES | | 9 | 0 | 0 | 9 |
| | | -PID Control Principle, Anti windup Controller, Intelligent Controller | r. Vector Contr | - | - | - | |
| | c motor | | | | | | |
| | | | | | | | |
| | III 7 | FUZZY LOGIC | | 9 | 0 | 0 | 9 |
| | | | | - | | | |
| Memb cuts - measu propos | • meth res of sitions, | functions: features, fuzzification, methods of membership value nods - fuzzy arithmetic and fuzzy measures: fuzzy arithmetic - e fuzziness -fuzzy integrals - fuzzy rule base and approximate reasoning , formation of rules decomposition of rules, aggregation of fu- stems, overview of fuzzy expert system-fuzzy decision making | extension princip g : truth value | fuzzit ple - f es an | fication fuzzy fuz tal | meas bles, | ures fuzz |
| Memb cuts - measu propos inferer | meth res of sitions, nce sy | functions: features, fuzzification, methods of membership value nods - fuzzy arithmetic and fuzzy measures: fuzzy arithmetic - e fuzziness -fuzzy integrals - fuzzy rule base and approximate reasoning , formation of rules decomposition of rules, aggregation of fu- stems, overview of fuzzy expert system-fuzzy decision making | extension princip g : truth value | fuzzii ple - 1 es an izzy | ficatio fuzzy id tal reaso | meas bles, bning | fuzz fuzz |
| Memb cuts - measu propos inferen | meth mes of sitions, nce sy | functions: features, fuzzification, methods of membership value nods - fuzzy arithmetic and fuzzy measures: fuzzy arithmetic - e fuzziness -fuzzy integrals - fuzzy rule base and approximate reasoning , formation of rules decomposition of rules, aggregation of fu- stems, overview of fuzzy expert system-fuzzy decision making FPGA AND VHDL BASICS | extension princip g : truth value uzzy rules, fu | fuzzil ple - f es an uzzy 9 | fication fuzzy id tal reaso | measoles, oning | fuzz fuzz fuzz |
| Memb cuts - measu propos inferer UNIT Introdu Sparta | meth res of sitions, nce sy F IV uction uction n 7. | functions: features, fuzzification, methods of membership value nods - fuzzy arithmetic and fuzzy measures: fuzzy arithmetic - e fuzziness -fuzzy integrals - fuzzy rule base and approximate reasoning , formation of rules decomposition of rules, aggregation of fu- stems, overview of fuzzy expert system-fuzzy decision making | extension princip g : truth value fuzzy rules, fu cessors- Sparta | fuzzit ple - t es an izzy 9 in 3, | ficatio fuzzy id tal reaso 0 Spar | measoles, oning 0 tan (| fuzz fuzz fuzz |
| Memb cuts - measu propos inferer UNIT UNIT Introdu Sparta sorting | meth res of sitions, nce sy FIV uction n 7. g, PWN | functions: features, fuzzification, methods of membership value and solve fuzzy arithmetic and fuzzy measures: fuzzy arithmetic - e fuzziness -fuzzy integrals - fuzzy rule base and approximate reasoning, formation of rules decomposition of rules, aggregation of frestems, overview of fuzzy expert system-fuzzy decision making FPGA AND VHDL BASICS FPGA Architecture-Advantages-Review of FPGA family prodivide VHDL Basics- Fundamentals-Instruction set-data type-conditional M generation, Speed detection | extension princip g : truth value fuzzy rules, fu cessors- Sparta | fuzzif ple - 1 es an izzy 9 in 3, grams | ficatio fuzzy id tal reaso 0 Spar s like | meas bles, oning 0 tan (arith | fuzz fuzz fuzz 9 5 and metic |
| Memb cuts - measu propos inferer UNIT Introdu Sparta sorting UNIT | meth res of sitions, nce sy CIV uction uction n 7. g, PWN | functions: features, fuzzification, methods of membership value and fuzzy arithmetic and fuzzy measures: fuzzy arithmetic - end fuzziness -fuzzy integrals - fuzzy rule base and approximate reasoning, formation of rules decomposition of rules, aggregation of fuzzy expert system-fuzzy decision making FPGA AND VHDL BASICS – FPGA Architecture-Advantages-Review of FPGA family prodiverses. VHDL Basics- Fundamentals-Instruction set-data type-conditional Migeneration, Speed detection REAL TIME IMPLEMENTATION | extension princip g : truth value fuzzy rules, fu cessors- Sparta statements- pro | fuzzit ple - t es an izzy 9 in 3, grams 9 | ficatio fuzzy ad tal reaso 0 Spar s like 0 | meas bles, oning 0 tan (arith | sures fuzz fuzz fuzz 9 ó an metio |
| Memb cuts - measu propos inferer UNIT Introdu Sparta sorting UNIT Inverte | T IV meth res of sitions, nce sy T IV uction m 7. g, PWN T V er desig | functions: features, fuzzification, methods of membership value and solve and fuzzy arithmetic and fuzzy measures: fuzzy arithmetic - end fuzziness -fuzzy integrals - fuzzy rule base and approximate reasoning, formation of rules decomposition of rules, aggregation of fuzzy expert system-fuzzy decision making FPGA AND VHDL BASICS – FPGA Architecture-Advantages-Review of FPGA family prodiverses. Fundamentals-Instruction set-data type-conditional digeneration, Speed detection REAL TIME IMPLEMENTATION gn, identifying rotor position via hall effect sensors, open loop and fuzz | extension princip g : truth value fuzzy rules, fu cessors- Sparta statements- pro | fuzzit ple - t es an izzy 9 in 3, grams 9 | ficatio fuzzy ad tal reaso 0 Spar s like 0 | meas bles, oning 0 tan (arith | sures fuzz fuzz fuzz 9 ó an metio |
| Memb cuts - measu propos inferer UNIT Introdu Sparta sorting UNIT Inverte | meth res of sitions, nce sy CIV uction uction n 7. g, PWN | functions: features, fuzzification, methods of membership value and solve and fuzzy arithmetic and fuzzy measures: fuzzy arithmetic - end fuzziness -fuzzy integrals - fuzzy rule base and approximate reasoning, formation of rules decomposition of rules, aggregation of fuzzy expert system-fuzzy decision making FPGA AND VHDL BASICS – FPGA Architecture-Advantages-Review of FPGA family prodiverses. Fundamentals-Instruction set-data type-conditional digeneration, Speed detection REAL TIME IMPLEMENTATION gn, identifying rotor position via hall effect sensors, open loop and fuzz | extension princip g : truth value fuzzy rules, fu cessors- Sparta statements- pro zy logic control | fuzzif ple - 1 es an izzy 9 in 3, grams 9 of 48 | ficatio fuzzy id tal reaso 0 Spar s like 0 S V B | meas bles, bning 0 tan (arith 0 LDC | sures fuzz -fuzz 9 ó an metic 9 moto |
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| CO2 | : | To demonstrate the PID control, anti-windup controller, Intelligent Controller and Vector Control. Control applied to BLDC motor. | L5: Evaluating |
| CO3 | : | To illustrate the basics of fuzzy logic system | L1: Remembering |
| CO4 | : | To describe the basics of VHDL & FPGA applied to control of EVs. | L2: Understanding |
| CO5 | : | To design and implement of fuzzy logic control scheme for BLDC motor using FPGA in real time | L6: Creating |

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| 4. | Electric and Hybrid Vehicles Design Fundamentals, Iqbal Husain, Second Edition, CRC Press, Taylor and Francis Group, 2011. |
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| 5. | Sandeep Dhameja, 'Electric Vehicle Battery Systems', Newnes, 2002. |
| 6. | Chris Mi, M. Abul Masrur, David Wenzhong Gao, 'Hybrid Electric Vehicles: Principles and Applications with Practical Perspectives', Wiley, 2011. |
| E-Refe | erence |
| 1 | https://nptel.ac.in/courses/108/106/108106170/ |
| 2 | https://nptel.ac.in/courses/108/102/108102121/ |

| Course O | outo | comes: | Bloom's Taxonomy |
|----------|------|--|-------------------|
| Upon com | plet | Mapped | |
| CO1 | : | Plan the selection of electrical machines for hybrid and electric vehicles. | L3: Applying |
| CO2 | : | Analyze the drive-train topologies and advanced propulsion techniques | L4: Analyzing |
| CO3 | : | Understand the concepts of electric vehicles, hybrid electric vehicles and their impact on environment | L2: Understanding |
| CO4 | : | Evaluate modelling and simulation of EV | L5: Evaluating |
| CO5 | : | Demonstrate the power system of various vehicular system. | L6: Creating |

| COUR | SE AR | RTICU | LATIO | ON MA | ATRIX | | | | | | | | | | |
|-------------|---------|---------|---------|----------|----------|----------|-----------|----------|---------|----------|----------|----------|----------|----------|----------|
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| CO1 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO3 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO4 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| CO5 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
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| | • | • | 3/2/1- | indicate | s streng | th of co | rrelation | n (3- Hi | gh, 2-M | ledium, | 1- Low |) | • | • | <u>.</u> |

| 18EEHO308 | BATTERY MANAGEMENT SYSTEM | | SE | MES | STEF | 2 |
|---|---|--|---|---|---|-------------------------------------|
| PREREQUIS' | TIES | CATEGORY | L | Т | P | С |
| Basics of Electri | cal Engineering, Electric Circuit theory, Chemistry and Physics | PEC | 3 | 0 | 0 | 3 |
| Course Objec | tives: | | | | | |
| | ifferent techniques of digital relaying - their constructions, workir | | cation | is and | limit | tation |
| along with intro | duction to Wide Area Measurement System and network protection | on. | | | | |
| UNIT I | INTRODUCTION | | 9 | 0 | 0 | 9 |
| | Battery Management System(BMS), Cells & Batteries, Nominal | | | | | |
| | nnected in series, Cells connected in parallel, Electrochemical a | | ls, R | echar | geabl | e cel |
| Charging and Di | scharging Process, Overcharge and Undercharge, Modes of Charg | ging | | | | |
| UNIT II | BATTERY-MANAGEMENT-SYSTEM REQUIREM | IENTS. | 9 | 0 | 0 | 9 |
| | BMS functionality, Battery pack topology, BMS Functionality, | | Temr | beratu | re Se | ensing |
| | , BMS Functionality, High-voltage contactor control, Isolation | | | | | |
| | Interface, Range estimation, State-of charge estimation. | <i>, , , ,</i> | | , | | |
| | DATTEDX CTATE OF CHADGE AND CTATE | | 1 | 1 | 1 | <u> </u> |
| UNIT III | BATTERY STATE OF CHARGE AND STATE ESTIMATION | OF HEALIH | 9 | 0 | 0 | 9 |
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| Course Out | omes: | Bloom's Taxonomy |
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| Upon complet | on of this course, the students will be able to: | Mapped |
| CO1 | : Recall the role of battery management system | L1: Remembering |

| CO2 | : | Identify the requirements of Battery Management System w.r.t application | L2: Understanding |
|-----|---|--|-------------------|
| CO3 | : | Analyze the concept associated with battery charging / discharging process | L4: Analysing |
| CO4 | : | Assess the various parameters of battery and battery pack | L3: Applying |
| CO5 | : | Design the battery pack model. | L4: Analysing |

| COUR | SE AR | RTICU | LATIO | ON MA | TRIX | | | | | | | | | | |
|-------------|---------|---------|---------|----------|----------|----------|-----------|----------|---------|----------|----------|----------|----------|----------|----------|
| COs/ POs | PO 1 | PO 2 | PO 3 | PO 4 | PO 5 | PO 6 | PO 7 | PO 8 | PO 9 | PO 10 | PO 11 | PO 12 | PS O1 | PS O2 | PS O3 |
| CO1 | 2 | 2 | 2 | 2 | 2 | 2 | 1 | | | | | 1 | 2 | 2 | 1 |
| CO2 | 1 | 2 | 2 | 2 | 2 | 2 | 1 | | | | | 1 | 2 | 2 | 1 |
| CO3 | 2 | 3 | 3 | 3 | 3 | 2 | 1 | | | | | 1 | 3 | 2 | 1 |
| CO4 | 3 | 3 | 3 | 3 | 3 | 2 | 1 | | | | | 1 | 3 | 2 | 1 |
| CO5 | 2 | 2 | 3 | 3 | 3 | 3 | 1 | | | | | 1 | 3 | 2 | 1 |
| Avg | 2 | 2.4 | 2.6 | 2.6 | 2.6 | 2.2 | 1 | 0 | 0 | 0 | 0 | 1 | 2.4 | 1.9 | 1 |
| | 1 | 1 | 3/2/1-i | indicate | s streng | th of co | rrelation | n (3- Hi | gh, 2-M | ledium, | 1- Low |) | 1 | 1 | L |

| 18EEHO | 309 ADVANCED ELECTRICAL DRIVES FOR ELECT | RIC VEHICLE | SEM | IEST | ER | |
|---------------|--|--------------------------------|--------|------------|--------|----------|
| PREREQ | | CATEGORY | L | Т | P | С |
| Solid state | drives | PEC | 3 | 0 | 0 | 3 |
| Course O | bjectives: | | | | | |
| 1. To i | ntroduce the electrical machines with control module for electric vehic | ele propulsion. | | | | |
| | | | | | | |
| UNIT I | PERMANENT MAGNET BRUSHLESS MOTOR DRIV | 'ES | 9 | 0 | 0 | 9 |
| | ess Machines : Structure and Principle of PM Brushless Machines, Inv | | | | | |
| for Brushle | ss AC Operation, PM Brushless Motor Control, Application of PM Br | ushless Motor Drives | in Ele | ctric v | ehicle | 2 |
| UNIT II | SWITCHED RELUCTANCE MOTOR DRIVES | | 9 | 0 | 0 | 9 |
| | nfigurations, Switched Reluctance Machine: Structure and Principle | e of operation, Swite | | - | - | |
| Converter | Topologies, Soft-Switching Switched Reluctance Motor Converter | [•] Topologies, Switc | hed R | lelucta | | |
| | orque-Ripple Minimization Control, Switched Reluctance Motor | Drives for Electric | Vehic | le, | Appli | cation |
| Examples of | of Switched Reluctance Motor Drives in Electric Vehicles | | | | | |
| UNIT III | MAGNETLESS MOTOR DRIVES | | 9 | 0 | 0 | 9 |
| | us Reluctance Motor Drives, Doubly-Salient DC Motor Drives, Fl | ux-Switching DC M | otor I | Drive, | - | |
| | Motor Drives, Design Criteria of Advanced Magnetless Motor Drive | | | oles of | Adv | anced |
| Magnetless | Motor Drives for EVs, Potential Applications of Advanced Magnetles | ss Motor Drives in EV | s | | | |
| UNIT IV | VERNIER PERMANENT MAGNET MOTOR DRIVES | 1 | 9 | 0 | 0 | 9 |
| | nfigurations and Vernier Permanent Magnet Machines, Structure a | | ier Pe | erman | - | |
| | Inverters for Vernier Permanent Magnet Motors, Vernier Permanent | | | | | |
| | I Motor Drives for EVs, Outer-Rotor Vernier PM Motor Drive, Outer ntial Applications of Vernier PM Motor Drives in EVs | r-Rotor Flux-Controll | able V | ernier | · PM 1 | Motor |
| Dive, role | initial Applications of Vermer FW Word Drives in EVS | | | | | |
| UNIT V | DOUBLE-ROTOR ELECTRIC VARIABLE | TRANSMISSION | 9 | 0 | 0 | 9 |
| | SYSTEMS | | | Ŭ | Ŭ | |
| | tor Machines, Double-Rotor Electric Variable Transmission System (tor EVT Systems, PM DR EVT System, SR DR EVT System, Axial | | | | | |
| | Systems in HEVs | I-MUX DK EVI Syste | m, ro | tentia | Арр | lication |
| | • | | | | | |
| | | Total (4 | 5L+0 | T)= | l5 Pe | riods |
| | | | | | | |
| Text Boo | | | | | | |
| 1. K. | T. Chau, 'Electric Vehicle Machines and Drives: Design, Analysis and | d Application, Wiley- | IEEE | Press, | 2015 | 5 |
| Reference | e Books: | | | | | |
| | | | | | | |
| | ary Murphy " Electric and Hybrid Vehicles: Principles, Design and | Technology ", Larsen | and 1 | Keller | Educ | ation, |
| 20 | 19 | | | | | |
| E-Refere | nce | | | | | |
| | tps://archive.nptel.ac.in/courses/108/103/108103009/ | | | | | |
| I III | ps.//arom/o.np/01.ao.nn/courses/100/105/100105007/ | | | | | |

| Course O | outo | Bloom's Taxonomy | |
|----------|------|---|-----------------|
| Upon com | plet | ion of this course, the students will be able to: | Mapped |
| CO1 | : | Explain the use for Permanent magnet Brushless motor drive for electric vehicle | L1: Remembering |

| CO2 | : | Select converter topology for Switched Reluctance Motor used for electric vehicle | L3: Applying |
|-----|---|---|-------------------|
| CO3 | : | Describe the operation of Magnetless Motor Drives in Electric Vehicles | L2: Understanding |
| CO4 | : | Understand the principle of Vernier Permanent Magnet Machines | L1: Remembering |
| CO5 | : | Select a suitable electric drive for electric vehicle | L4: Analyzing |

| COUR | SE AR | TICU | LATIO | ON MA | TRIX | | | | | | | | | | |
|-------------|---------|---------|---------|----------|----------|-----------|----------------|-----------|---------|----------|----------|----------|----------|----------|----------|
| COs/ POs | PO 1 | PO 2 | PO 3 | PO 4 | РО 5 | PO 6 | PO 7 | PO 8 | PO 9 | PO 10 | PO 11 | PO 12 | PS O1 | PS O2 | PS O3 |
| CO1 | 3 | 2 | 2 | 3 | | 3 | | 1 | | 2 | | 2 | 2 | 1 | 2 |
| CO2 | | 3 | | | 1 | | | | | 2 | | 1 | 1 | 2 | |
| CO3 | 2 | 1 | | 2 | 1 | | 1 | | 1 | | | | 1 | 1 | 1 |
| CO4 | 1 | 1 | | 1 | | 2 | 1 | 2 | 1 | | 2 | 2 | 1 | 1 | 1 |
| CO5 | 1 | 2 | 3 | 1 | | 3 | | | | 1 | 3 | 1 | 2 | 2 | 1 |
| Avg | 1.75 | 1.8 | 2.5 | 1.75 | 1 | 2.67 | 1 | 1.5 | 1 | 1.67 | 2.5 | 1.5 | 1.4 | 1.4 | 1.25 |
| | | 1 | 3/2/1-i | indicate | s streng | th of con | rrelation | n (3- Hig | gh, 2-M | edium, | l-Low) | | 1 | 1 | L |

| 18EEHO3 | | | SEM | 1 | EK | |
|---|---|--|--|---|--|--|
| PREREQU | | CATEGORY | L | Т | Р | С |
| Electrical E | Engineering | PEC | 3 | 0 | 0 | 3 |
| Course Ot | bjectives: | | | | | |
| 1. To u | nderstand the various types of energy storage technologies. | | | | | |
| | nalyze thermal storage system. | | | | | |
| | nalyze different battery storage technologies. | | | | | |
| | nodel the Lithium-ion batteries. | | | | | |
| 5. To st | udy the various applications of energy storage systems. | | | | | |
| UNIT I | INTRODUCTION | | 9 | 0 | 0 | 9 |
| | f energy storage – Types of energy storage – Comparison of energ age technology in power system, application outlook and challer | | | | | |
| UNIT II | THERMAL STORAGE SYSTEM | | 9 | 0 | 0 | 9 |
| Pressurized | rage – Types – Modeling of thermal storage units – Simple water ar water storage system – Modeling of phase change storage system – sing porous medium approach – Use of TRNSYS. | | | age u | nits – | |
| UNIT III | ELECTRICAL ENERGY STORAGE | | 9 | 0 | 0 | 9 |
| manomatic | | | | | | |
| | al modeling of Lead Acid batteries – Flow batteries. LITHIUM-ION BATTERY MODELING charge and discharge temperature characteristics of Lithium-ion ba Modeling and Optimization of Air Cooling Heat Dissipation of Lith | | | 0 ing | 0 | 9 |
| Analysis on Modeling - 1 | LITHIUM-ION BATTERY MODELING charge and discharge temperature characteristics of Lithium-ion ba Modeling and Optimization of Air Cooling Heat Dissipation of Lith | ium-ion Battery Pack | al coupl | Ŷ | 0 | |
| Analysis on Modeling - UNIT V Flywheel, S | LITHIUM-ION BATTERY MODELING charge and discharge temperature characteristics of Lithium-ion ba | ium-ion Battery Pack | al coupli | ing 0 | 0 | 9 |
| Analysis on Modeling - UNIT V Flywheel, S | LITHIUM-ION BATTERY MODELING charge and discharge temperature characteristics of Lithium-ion ba Modeling and Optimization of Air Cooling Heat Dissipation of Lith ALTERNATE ENERGY STORAGE TECHNOLOGII Supercapacitors, Principles and methods – Applications, Compre | ium-ion Battery Pack E S essed air energy stor | al coupli s. 9 age, Con | ing 0 ncept | 0 of H | 9 ybric |
| Analysis on Modeling - UNIT V Flywheel, S | LITHIUM-ION BATTERY MODELING charge and discharge temperature characteristics of Lithium-ion ba Modeling and Optimization of Air Cooling Heat Dissipation of Lith ALTERNATE ENERGY STORAGE TECHNOLOGII Supercapacitors, Principles and methods – Applications, Compre | ium-ion Battery Pack E S essed air energy stor | al coupli | ing 0 ncept | 0 of H | 9 ybrid |
| Analysis on Modeling - 1 UNIT V Flywheel, S storage – Ap | LITHIUM-ION BATTERY MODELING charge and discharge temperature characteristics of Lithium-ion ba Modeling and Optimization of Air Cooling Heat Dissipation of Lith ALTERNATE ENERGY STORAGE TECHNOLOGII Supercapacitors, Principles and methods – Applications, Compre pplications, Pumped hydro storage – Applications. | ium-ion Battery Pack E S essed air energy stor | al coupli s. 9 age, Con | ing 0 ncept | 0 of H | 9 ybrid |
| Analysis on Modeling - 1 UNIT V Flywheel, S storage – Ap Text Book | LITHIUM-ION BATTERY MODELING charge and discharge temperature characteristics of Lithium-ion ba Modeling and Optimization of Air Cooling Heat Dissipation of Lith ALTERNATE ENERGY STORAGE TECHNOLOGII Supercapacitors, Principles and methods – Applications, Compre pplications, Pumped hydro storage – Applications. | ium-ion Battery Pack ES essed air energy stor Total (| al coupli s. age, Con (45L+0) | 0 ncept Γ)= 4 | 0 of H | 9 ybrio |
| Analysis on Modeling - 1 UNIT V Flywheel, S storage – Ap Text Book 1. Ibra Joh 2. Ru- and | LITHIUM-ION BATTERY MODELING charge and discharge temperature characteristics of Lithium-ion ba Modeling and Optimization of Air Cooling Heat Dissipation of Lith ALTERNATE ENERGY STORAGE TECHNOLOGII Supercapacitors, Principles and methods – Applications, Compre pplications, Pumped hydro storage – Applications. Stress: ahim Dincer and Mark A. Rosen, 'Thermal Energy m Wiley & Sons, 3rd Edition, 2021. -shi Liu, Lei Zhang and Xueliang sun, 'Electrocher t conversion', Wiley publications, 2 nd Volume set, 2012. | ium-ion Battery Pack ES essed air energy stor Total (7 Storage System nical technologies | al couplines. 9 age, Con 45L+0 s and for o | 0 ncept Γ)= 4 App energy | 0 of H 5 Per | ybrid iod |
| Analysis on Modeling - 1 UNIT V Flywheel, S storage – Ap Text Book 1. Ibra Joh 2. Ru- and | LITHIUM-ION BATTERY MODELING charge and discharge temperature characteristics of Lithium-ion ba Modeling and Optimization of Air Cooling Heat Dissipation of Lith ALTERNATE ENERGY STORAGE TECHNOLOGII Supercapacitors, Principles and methods – Applications, Compre pplications, Pumped hydro storage – Applications. st: ahim Dincer and Mark A. Rosen, 'Thermal Energy m Wiley & Sons, 3rd Edition, 2021. -shi Liu, Lei Zhang and Xueliang sun, 'Electrocher | ium-ion Battery Pack ES essed air energy stor Total (7 Storage System nical technologies | al couplines. 9 age, Con 45L+0 s and for o | 0 ncept Γ)= 4 App energy | 0 of H 5 Per | ybrid iod |
| Analysis on Modeling - 1 UNIT V Flywheel, S storage – Ap Text Book 1. Ibra Joh 2. Ru- and 3. Jun | LITHIUM-ION BATTERY MODELING charge and discharge temperature characteristics of Lithium-ion ba Modeling and Optimization of Air Cooling Heat Dissipation of Lith ALTERNATE ENERGY STORAGE TECHNOLOGII Supercapacitors, Principles and methods – Applications, Compre pplications, Pumped hydro storage – Applications. st: ahim Dincer and Mark A. Rosen, 'Thermal Energy m Wiley & Sons, 3rd Edition, 2021. -shi Liu, Lei Zhang and Xueliang sun, 'Electrocher conversion', Wiley publications, 2 nd Volume set, 2012. aqiu Li, "Modeling and simulation of Lithium-ion power battery the | ium-ion Battery Pack ES essed air energy stor Total (7 Storage System nical technologies | al couplines. 9 age, Con 45L+0 s and for o | 0 ncept Γ)= 4 App energy | 0 of H 5 Per | ybrid iod |
| Analysis on Modeling - 1 UNIT V Flywheel, S storage – Ap Text Book 1. Ibra Joh 2. Ru- and 3. Jun Reference 1. Lur | LITHIUM-ION BATTERY MODELING charge and discharge temperature characteristics of Lithium-ion ba Modeling and Optimization of Air Cooling Heat Dissipation of Lith ALTERNATE ENERGY STORAGE TECHNOLOGII Supercapacitors, Principles and methods – Applications, Compre pplications, Pumped hydro storage – Applications. Supercapacitors, Principles and methods – Applications, Compre pplications, Pumped hydro storage – Applications. Supercapacitors, Principles and methods – Applications, Compre pplications, Pumped hydro storage – Applications. Supercapacitors, Principles and methods – Applications, Compre pplications, Pumped hydro storage – Applications. Supercapacitors, Principles and Mark A. Rosen, 'Thermal Energy in Wiley & Sons, 3rd Edition, 2021. shi Liu, Lei Zhang and Xueliang sun, 'Electrocher I conversion', Wiley publications, 2 nd Volume set, 2012. aqiu Li, "Modeling and simulation of Lithium-ion power battery there Books: nardini.V.J, 'Heat Transfer in Cold Climates', Jeter Superceapacity in the set in th | ium-ion Battery Pack ES essed air energy stor Total (7 Storage System nical technologies | al couplines. | 0 ncept Γ)= 4 App energy 2020. | 0 of H 5 Per | ybrid iodi |
| Analysis on Modeling - 1 UNIT V Flywheel, S storage – Ap Text Book 1. Ibra Joh 2. Ru- and 3. Jun Reference 1. Lur Edi 2. Sch | LITHIUM-ION BATTERY MODELING charge and discharge temperature characteristics of Lithium-ion ba Modeling and Optimization of Air Cooling Heat Dissipation of Lith ALTERNATE ENERGY STORAGE TECHNOLOGIH Supercapacitors, Principles and methods – Applications, Compre pplications, Pumped hydro storage – Applications. String ahim Dincer and Mark A. Rosen, 'Thermal Energy m Wiley & Sons, 3rd Edition, 2021. -shi Liu, Lei Zhang and Xueliang sun, 'Electrocher d conversion', Wiley publications, 2 nd Volume set, 2012. aqiu Li, "Modeling and simulation of Lithium-ion power battery the Books: nardini.V.J, 'Heat Transfer in Cold Climates', Je | ium-ion Battery Pack ES essed air energy stor Total (7 Storage System nical technologies rmal management", S | al couplines. | 0 ncept Γ)= 4 App energy 2020. | 0 of H 5 Per | 9 ybrid iod ons' prag |
| Analysis on Modeling - 1 UNIT V Flywheel, S storage – Ap Text Book 1. Ibra Joh 2. Ru- and 3. Jun Reference 1. Lur Edi 2. Sch Hen | LITHIUM-ION BATTERY MODELING charge and discharge temperature characteristics of Lithium-ion ba Modeling and Optimization of Air Cooling Heat Dissipation of Lith ALTERNATE ENERGY STORAGE TECHNOLOGII Supercapacitors, Principles and methods – Applications, Compreplications, Pumped hydro storage – Applications. Supercapacitors, Principles and methods – Applications, Compreplications, Pumped hydro storage – Applications. Supercapacitors, Principles and Mark A. Rosen, 'Thermal Energy m Wiley & Sons, 3rd Edition, 2021. -shi Liu, Lei Zhang and Xueliang sun, 'Electrocherd conversion', Wiley publications, 2 nd Volume set, 2012. aqiu Li, "Modeling and simulation of Lithium-ion power battery thered the simulation of Lithium-ion power battery thered the simulation of Lithium-ion power battery thered the simulation of Lithium-ion power battery the simulation of Lithium-ion power battery the set in the simulation of Lithium-ion power battery the set in the simulation of Lithium-ion power battery the set in the se | ium-ion Battery Pack ES essed air energy stor Total (7 Storage System mical technologies rmal management", S ohn Wiley and | al couplines. | 0 ncept Γ)= 4 App energy 2020. | 0 of H 5 Per plicati 7 sto 981, | 9 ybrid iod ons' prag |
| Analysis on Modeling - 1 UNIT V Flywheel, S storage – Ap Text Book 1. Ibra Joh 2. Ru- and 3. Jun Reference 1. Lur Edi 2. Sch Hen terent 1. Pro | LITHIUM-ION BATTERY MODELING charge and discharge temperature characteristics of Lithium-ion ba Modeling and Optimization of Air Cooling Heat Dissipation of Lith ALTERNATE ENERGY STORAGE TECHNOLOGII Supercapacitors, Principles and methods – Applications, Compreplications, Pumped hydro storage – Applications. Supercapacitors, Principles and methods – Applications, Compreplications, Pumped hydro storage – Applications. Supercapacitors, Principles and Mark A. Rosen, 'Thermal Energy m Wiley & Sons, 3rd Edition, 2021. -shi Liu, Lei Zhang and Xueliang sun, 'Electrocherd conversion', Wiley publications, 2 nd Volume set, 2012. aqiu Li, "Modeling and simulation of Lithium-ion power battery thered the simulation of Lithium-ion power battery thered the simulation of Lithium-ion power battery thered the simulation of Lithium-ion power battery the simulation of Lithium-ion power battery the set in the simulation of Lithium-ion power battery the set in the simulation of Lithium-ion power battery the set in the se | ium-ion Battery Pack ES essed air energy stor Total (7 Storage System nical technologies rmal management", S ohn Wiley and Energy Storage | al couplines. | 0 ncept Γ)= 4 App energy 2020. | 0 of H 5 Per plicati 7 sto 981, | 9 ybrid iod ons' prag |

| Course C |)uto | Bloom's Taxonomy | |
|----------|------|--|-------------------|
| Upon com | plet | ion of this course, the students will be able to: | Mapped |
| CO1 | : | Understand different types of storage technologies. | L2: Understanding |
| CO2 | : | Model a thermal battery energy storage system | L1: Remembering |
| CO3 | : | Analyze the modeling of Lithium-ion batteries. | L4: Analyzing |
| CO4 | : | Analyze the appropriate storage technologies for different applications. | L3: Applying |
| CO5 | : | Explore the alternate energy storage technologies. | L2: Understanding |

| COUR | COURSE ARTICULATION MATRIX | | | | | | | | | | | | | | |
|-------------|----------------------------|-----|----------|---------|----------|----------|-----------|----------|----------|----------|----------|----------|----------|----------|----------|
| COs/ POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO 10 | PO 11 | PO 12 | PS O1 | PS O2 | PS O3 |
| CO1 | 3 | 1 | | | | | | | | | | | 2 | | 3 |
| CO2 | 3 | | 2 | | | | | | | | | | 2 | | 3 |
| CO3 | 3 | | 2 | | | | | | | | | | 2 | | 3 |
| CO4 | 3 | | 2 | | | | | | | | | | 2 | | 3 |
| CO5 | | 3 | | | | 2 | | 1 | | | | | 2 | | 3 |
| Avg | 3 | 2 | 2 | 0 | 0 | 2 | 0 | 1 | 0 | 0 | 0 | 0 | 2 | 0 | 3 |
| | • | • | 3/2/1-in | dicates | strength | of corre | elation (| 3- High, | , 2-Medi | um, 1- l | Low) | | | | |

GOVERNMENT COLLEGE OF ENGINEERING, SALEM

REGULATION 2018 A - VERTICALS FOR MINOR DEGREE

| VERTICAL - I | VERTICAL - II | VERTICAL - III | VERTICAL - IV | VERTICAL - V | VERTICAL - VI |
|--|--|--|---|--|---|
| Civil Engineering | Computer Science and Engineering | Electronics and Communication Engineering | Electrical and Electronics Engineering | Mechanical Engineering | Metallurgical Engineering |
| 18CEM01 Construction Materials | 18CSM01 Programming in C++ | 18ECM01 Electron Devices | 18EEM01 – Network Analysis and Synthesis | 18MEM01 Engineering Thermodynamics | 18MTM01 Advanced Physical Metallurgy |
| 18CEM02 Building Construction & Equipment | 18CSM02 Advanced Data Structures and Algorithms | 18ECM02 Digital Electronics | 18EEM02 – Signals and Systems 18MEM02 Fluid Mechan and Machinery | | 18MTM02 Metallurgical Thermodynamics and kinetics |
| 18CEM03 Concrete Technology | 18CSM03 Computer Organization and Design | 18ECM03 Electronic Circuits (EC-I & EC- II, LIC) | 18EEM03 – Linear and Digital Electronics Circuits | 18MEM03 Manufacturing Processes | 18MTM03 Mechanical Behaviour of Materials |
| 18CEM04 Environmental Engineering | 18CSM04 Advanced Operating Systems | 18ECM04 Signal Processing | 18EEM04 – Microprocessor and Microcontrollers | 18MEM04 Materials Engineering | 18MTM04 Rate Processing in Metallurgy |
| 18CEM05 Basics of Transportation Engineering | 18CSM05 Data Communication and Computer Networks | 18ECM05 Microprocessors and Microcontrollers | 18EEM05 – Control Systems | 18MEM05 Kinematics of Machinery | 18MTM05 Corrosion and Surface Engineering |
| 18CEM06 Repair and Rehabilitation Structures | 18CSM06 Programming Essentials in Python | 18ECM06 Analog and Digital Communication | 18EEM06 – Measurement and Instrumentation | 18MEM06 Hydraulics and Pneumatics | 18MTM06 Characterization of Materials |
| 18CEM07 Green Building Technology | 18CSM07 Advanced Database System Concepts | 18ECM07 Communication Networks (CN) | 18EEM07 – Electrical Machines | 18MEM07 Design of Machine Elements | 18MTM07 Automotive, Aerospace and Defense Materials |
| | 18CSM08 Virtualization and Cloud Computing | 18ECM08 Fundamentals of IoT | 18EEM08 – Electric Drives and Control | 18MEM08 Heat and Mass Transfer | |
| | | 18ECM09 Wireless Sensors and Networking (WSN) | 18EEM09 – Electric Vehicle and Control | 18MEM09 Metrology and Quality Control | |
| | | 18ECM10 Basics of Embedded Systems | 18EEM10 –Electric Energy Conservation and Auditing | 18MEM10 Dynamics of Machinery | |

LIST OF MINOR DEGREE - VERTICALS

| | Course | | ~ . | Ho | ours/W | /eek | lits | Maxi | imum I | Marks |
|-------|---------|---|-------|-------|--------|-------|---------|------|--------|-------|
| S.No. | Code | Course | Cat | L | Т | Р | Credits | CA | FE | Total |
| | | CIVIL ENGIN | EERIN | G | | | | | | |
| 1 | 18CEM01 | Construction Materials | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 2 | 18CEM02 | Building Construction & Equipment's | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 3 | 18CEM03 | Concrete Technology | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 4 | 18CEM04 | Environmental Engineering | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 5 | 18CEM05 | Basics of Transportation Engineering | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 6 | 18CEM06 | Repair and Rehabilitation of Structures | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 7 | 18CEM07 | Green Building Technology | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| | | COMPUTER SCIENCE A | ND EN | GINE | ERIN | G | | | | |
| 1 | 18CSM01 | Programming in C++ | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 2 | 18CSM02 | Advanced Data Structures and Algorithms | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 3 | 18CSM03 | Computer Organization and Design | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 4 | 18CSM04 | Advanced Operating Systems | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 5 | 18CSM05 | Data Communication and Computer Networks | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 6 | 18CSM06 | Programming Essentials in Python | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 7 | 18CSM07 | Advanced Database System Concepts | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 8 | 18CSM08 | Virtualization and Cloud Computing | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| | | ELECTRONICS AND COMMUN | ICATI | ON EN | IGINI | EERIN | IG | | | · |
| 1 | 18ECM01 | Electron Devices | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 2 | 18ECM02 | Digital Electronics | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 3 | 18ECM03 | Electronic Circuits | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 4 | 18ECM04 | Signal Processing | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 5 | 18ECM05 | Microprocessors and Microcontrollers | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |

| 6 | 18ECM06 | Analog and Digital Communication | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
|----|---------|---|-------|------|------|------|---|----|----|-----|
| 7 | 18ECM07 | Communication Networks | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 8 | 18ECM08 | Fundamentals of IoT | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 9 | 18ECM09 | Wireless sensors and networking | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 10 | 18ECM10 | Basics of Embedded systems | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| | | ELECTRICAL AND ELECTR | ONICS | ENGI | NEEF | RING | | | | |
| 1 | 18EEM01 | Linear and Digital Electronics Circuits | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 2 | 18EEM02 | Microprocessors and Microcontrollers | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 3 | 18EEM03 | Control Systems | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 4 | 18EEM04 | Measurements and Instrumentation | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 5 | 18EEM05 | Electrical Machines | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 6 | 18EEM06 | Electric Drives and Control | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 7 | 18EEM07 | Electric Vehicles and Control | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 8 | 18EEM08 | Electrical Energy Conservation and Auditing | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 9 | 18EEM09 | SMPS and UPS | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 10 | 18EEM10 | Utilization of Electrical Energy | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| | | MECHANICAL EN | GINEE | RING | | L | | | | |
| 1 | 18MEM01 | Engineering Thermodynamics | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 2 | 18MEM02 | Fluid Mechanics and Machinery | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 3 | 18MEM03 | Manufacturing Processes | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 4 | 18MEM04 | Materials Engineering | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 5 | 18MEM05 | Kinematics of Machinery | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 6 | 18MEM06 | Hydraulics and Pneumatics | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 7 | 18MEM07 | Design of Machine Elements | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 8 | 18MEM08 | Heat and Mass Transfer | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |
| 9 | 18MEM09 | Metrology and Quality Control | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 |

| 10. | 18MEM10 | Dynamics of Machinery | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | | | |
|-----|--------------------------|--|----|---|---|---|---|----|----|-----|--|--|--|
| | METALLURGICAL ENGINEEING | | | | | | | | | | | | |
| 1 | 18MTM101 | Advanced Physical Metallurgy | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | | | |
| 2 | 18MTM102 | Thermodynamics and Kinetics in Metallurgy | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | | | |
| 3 | 18MTM103 | Mechanical Behaviour of Materials | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | | | |
| 4 | 18MTM104 | Rate Processes in Metallurgy | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | | | |
| 5 | 18MTM105 | Corrosion and Surface Engineering | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | | | |
| 6 | 18MTM106 | Materials Characterization | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | | | |
| 7 | 18MTM107 | Automotive, Aerospace and Defence Materials | OE | 3 | 0 | 0 | 3 | 40 | 60 | 100 | | | |

B.E. – CIVIL ENGINEERING - MINOR DEGREE

| 18CEM01 | | CONSTRUCTION MATERIALS | | Semester | | | | |
|---|---|--|------------|----------|---|---|----|--|
| PREREQUISITES Category | | | OE | Credit | | 3 | | |
| NIL | | | Hours/Week | L | Т | Р | ТН | |
| | | | 3 | 0 | 0 | 3 | | |
| Course Learning Objectives | | | | | | | | |
| 1 | 1 To study the characteristics and Properties of Stones and Brick | | | | | | | |
| 2 | To impart | impart knowledge on Cement, Aggregate and Mortar | | | | | | |
| 3 | To understand the behaviour of concrete and seasoning timber | | | | | | | |
| 4 | 4 To study the Parts and types of flooring and roofing | | | | | | | |
| 5 | 5 To study carpentry, arches, lintels and finishing works. | | | | | | | |
| Unit I | | STONES, BRICKS | | 9 | 0 | 0 | 9 | |
| Building Stone –classification of rocks-characteristics of good building stone – deterioration and preservation of stone work – tests on stones - Bricks- manufacture of clay bricks -classification - tests on bricks- bricks for special use- refractory bricks. | | | | | | | | |
| Unit II | | CEMENT, AGGREGATES, MORTAR | | 9 | 0 | 0 | 9 | |
| Cement- composition- manufacturing process-wet and dry processes. Aggregates –coarse and fine aggregates- characteristics and function. Mortar- properties- uses- types of mortars- selection of mortars for various Civil Engineering construction. | | | | | | | | |
| Unit III | | CONCRETE, TIMBER AND OTHER MATERIALS | | 9 | 0 | 0 | 9 | |
| Concrete- ingredients - principles of hardened concrete- Special concrete- types. | | | | | | с | | |
| Timber- characteristics- seasoning-preservation- Panels of laminates. Glass- properties- uses. Steel- Uses - market forms. Aluminum and other metallic materials for construction. | | | | | | | | |
| Paints, Varnishes and Distempers-types-properties. | | | | | | | | |
| Unit IV | | FLOORING AND ROOFING | | 9 | 0 | 0 | 9 | |
| Components of floor- selection of flooring materials- suitability of floors for various applications. damp proof course, causes of dampness- effect of dampness - requirements of good stairs - classification of stairs -Roofs - types of roofs- requirements - pitched roof - lean to roof-gable roof-hip roof-flat roof-RCC roof. | | | | | | | | |
| Unit V | | CARPENTARY, ARCHES, LINTELS AND FINISHING WORKS | | 9 | 0 | 0 | 9 | |
| Location of doors and windows - size of doors - types of doors - fixture and fastenings for doors and windows - arches - classification - stability of an arch - lintels - classification of lintels - steel lintel. scaffolding - component parts - shoring - methods of plastering - defects in plastering - pointing - objectives- methods of pointing | | | | | | | | |
| Total= 45 Periods | | | | | | | | |

| Te | ext Books: |
|-----|--|
| 1 | B.C. Punmia, Building Construction, Laxmi Publications; Eleventh edition -2021 |
| 2 | S.C.Rangwala, Building Construction, CharotarPublishing House Pvt. Ltd, 34th Edition - 2022 |
| 3 | P. Purushothama Raj., Building Construction Materials and Techniques, Pearson Education India, First Edition - 2017 |
| Ref | erence Books: |
| 1 | Shetty M.S., Concrete Technology (Theory and Practice), S.Chand& Company Ltd., 2021. |
| 2 | Rangwala S.C., Engineering Materials (Material Science) revised and enlarged by Rangwala K.S. and Rangwala P.S., Charotar Publishing House, 2010. |

| | Course Outcomes: Upon completion of this course, the students will be able to: | | | | | | | | |
|-----|---|------------|--|--|--|--|--|--|--|
| CO1 | Identify and characterize and properties of Stone and brick | Remember | | | | | | | |
| CO2 | Understand the manufacturing process of cement and functions of mortar | Understand | | | | | | | |
| CO3 | Identify the age of timber and preservation methods of timber | Remember | | | | | | | |
| CO4 | Differentiate the types of roofing and flooring | Understand | | | | | | | |
| CO5 | Understand the miscellaneous works such as carpentry, lintels, Arch, etc. | Understand | | | | | | | |

| COs/ POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-------------|-----|-----|-------|----------|----------|---------|---------|----------|---------|----------|----------|------|------|------|------|
| C01 | 1 | - | - | - | - | - | 1 | - | - | - | - | - | - | - | - |
| CO2 | - | 2 | - | - | - | 2 | 3 | - | - | - | - | - | - | - | - |
| CO3 | 1 | - | - | - | 1 | - | - | - | - | - | - | - | - | - | - |
| CO4 | 1 | - | 2 | - | 2 | 3 | 2 | - | - | - | - | - | - | - | - |
| CO5 | 1 | - | - | - | 3 | - | 2 | - | - | - | - | - | - | - | - |
| Avg | 1 | 2 | 2 | - | 2 | 3 | 2 | - | - | - | - | - | - | - | - |
| | • | • | 3/2/1 | – indica | ates str | ength o | f corre | lation (| 3- High | n, 2- Me | dium, 1- | Low) | | | |

| 18C | EM02 | PMENT | S | emesto | er | | |
|-------|----------------------|---|----------------------|-----------|----------|----------|---------|
| PRF | EREQUISI | TES | Category | OE | Cr | edit | 3 |
| NIL | , | | Hours/Week | L | Т | Р | ТН |
| | | | | 3 | 0 | 0 | 3 |
| Cou | rse Learni | ng Objectives | | | | 1 | |
| 1 | Able to ga | in basic knowledge in construction methods. | | | | | |
| 2 | Able to ga | in basic knowledge in equipment. | | | | | |
| 3 | Able to ga | in basic knowledge in machineries. | | | | | |
| 4 | Able to ga | in basic knowledge in fire safety principles. | | | | | |
| 5 | Able to ga | in basic knowledge in green technology. | | | | | |
| | | CLASSIFICATION OF BUILDINGS, FOUND | ATIONS AND | 9 | 0 | 0 | 9 |
| 1 | Unit I | TYPES OF MASONRY | | , | U | U | , |
| level | ,Classificatio | n for foundation as per N.B.C, Types of foundation on of stone masonry DOORS, WINDOWS, LINTELS, SCAFFOL | | T | - | | |
| τ | U nit II | STAIRCASES | | 9 | 0 | 0 | 9 |
| | | ows – parts of door and window – Types of Door and w – Functions, Scaffolding – Purpose and types –Location of | | | l, swin | ging ty | pe and |
| τ | Init III | ROOFS, FLOORINGS, PROTECTIVE AND E FINISHES | DECORATIVE | 9 | 0 | 0 | 9 |
| | | Roof Slabs – Types of Roofing Systems – Methods of Terr Plastering (Interior and Exterior) – Pointing for Walls ar | U | | | | · |
| | ning with di cation. | fferent Color Shades available in the Markets – Painting | g – Types of Painti | ing for | Interior | and E | xterior |
| τ | J nit IV | CONSTRUCTION EQUIPMENT | S | 9 | 0 | 0 | 9 |
| | - | ipment for earthwork excavation, drilling, blasting, tuni ial handling and erection of structures | nelling, erection an | d dewa | tering | and pu | mping, |
| | U nit V | GREEN BUILDING TECHNOLO | GY | 9 | 0 | 0 | 9 |
| | - | reen technology – types and importance; zero waste and r co green buildings, green engineering. | oncept, green materi | als – gre | en con | crete (p | ourpose |
| | | | | | Total | = 45 Po | eriods |

| Te | xt Books: | | | | | | | | | |
|-----|---|--|--|--|--|--|--|--|--|--|
| 1 | Building Construction by S.C.Rangawala | | | | | | | | | |
| 2 | Construction Technology by Sarkar Oxford University Press | | | | | | | | | |
| 3 | Building Material & Construction by S.P. Arora& S. P. Bindra | | | | | | | | | |
| Ref | erence Books: | | | | | | | | | |
| 1 | Hopkinson And Kay J.D., The Lighting of Building, Faber and Faber, London. | | | | | | | | | |
| 2 | Koerner, R.M, Construction & Geotechnical Methods in Foundations Engineering, McGraw Hill, 1984 | | | | | | | | | |
| 3 | Varna M., Construction Equipment and Its Planning & Applications, Metropolitan Books Co, 1979 | | | | | | | | | |

| | se Outcomes: completion of this course, the students will be able to: | Bloom's Taxonomy Mapped |
|-----|--|-------------------------------|
| CO1 | Organize the construction technique to be followed in brick and stone masonry, concreting, flooring, roofing and plastering etc. | Create |
| CO2 | Select safe practices in building construction activities | Evaluate |
| CO3 | Clarify the different types of roofs, floor and productive materials of buildings | understand |
| CO4 | Select the relevant equipment for building construction | Evaluate |
| CO5 | Apply the Principles of green building technology. | Apply |

| COs/ POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-------------|--|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| CO1 | - | - | - | - | 3 | 2 | 2 | 2 | 1 | 1 | - | - | - | - | 1 |
| CO2 | - | - | - | - | 3 | 2 | 2 | 2 | 2 | 2 | - | - | - | - | 1 |
| CO3 | - | - | - | - | 2 | 3 | 2 | 2 | 2 | 1 | - | - | - | - | 1 |
| CO4 | - | - | - | - | 2 | 2 | 3 | 1 | 1 | 2 | - | - | - | - | 1 |
| CO5 | - | - | - | - | 2 | 3 | 2 | 2 | 2 | 2 | - | - | - | - | 1 |
| Avg | - | - | - | - | 2.4 | 2.4 | 2.2 | 1.8 | 1.6 | 1.6 | - | - | - | - | 1 |
| | 3/2/1 – indicates strength of correlation (3- High, 2- Medium, 1- Low) | | | | | | | | | | | | | | |

| 18C | EM03 | CONCRETE TECHNOLOG | Y | S | emest | er | | | |
|-------|------------------|---|-------------------------|-------------|------------|----------|----------------|--|--|
| PRF | EREQUISI | TES | Category | OE | Cr | edit | 3 | | |
| NIL | 1 | | | L | Т | Р | TH | | |
| | | | Hours/Week | 3 | 0 | 0 | 3 | | |
| Cou | rse Learni | ng Objectives | I | | 1 | | 1 | | |
| 1 | To unders | tand the properties of ingredients of concrete. | | | | | | | |
| 2 | To study t | he behavior of concrete at its fresh and hardened state. | | | | | | | |
| 3 | To study a | bout the concrete design mix. | | | | | | | |
| 4 | To know a | about the procedures in concrete at different stage. | | | | | | | |
| 5 | To unders | tand special concrete and their uses. | | | | | | | |
| 1 | Unit I | | 9 | 0 | 0 | 9 | | | |
| Conc | crete materia | ls, Cement: Field and laboratory tests on cement, Types o | f cement and their use | s, differer | it tests f | for aggr | egates. | | |
| Meth | nods for man | ufacturing of cement- Wet and dry process. Hydration o | f cement, Bogue's co | mpound. | | | | | |
| τ | U nit II | ADMIXTURES | | 9 | 0 | 0 | 9 | | |
| Acce | elerating adu | nixtures, Retarding admixtures, water reducing admix | xtures, Air entraining | g admixtı | ures, co | oloring | agent, | | |
| Plast | icizers. Batc | hing, Mixing, Transportation, placing of concrete, curing | g of Concrete | | | | | | |
| τ | J nit III | MIX DESIGN | MIX DESIGN | | | | | | |
| Facto | ors influenci | ng mix proportion, Mix design by ACI method and I.S. | code method, Design | of high st | rength o | concrete | <u>.</u> 2. | | |
| τ | J nit IV | BEHAVIOUR OF CONCRE | ТЕ | 9 | 0 | 0 | 9 | | |
| Strer | igth of conc | rete, Shrinkage and temperature effects, creep of concre | ete, permeability of co | oncrete, d | urabilit | ty of co | ncrete, | | |
| Corr | osion, Cause | s and effects, remedial measures, Thermal properties of | concrete, Micro crack | ting of co | ncrete. | | | | |
| I | U nit V | SPECIAL CONCRETE | | 9 | 0 | 0 | 9 | | |
| Ligh | t-weight con | ncrete, Fibre reinforced concrete, Polymer modified c | oncrete, Ferro cemer | nt, Mass | concret | te, Rea | dy-mix | | |
| conc | rete, Self-co | mpacting concrete, Quality control, Sampling and testing | g, Acceptance criteria | | | | | | |
| | | | | | Total | = 45 P | eriods | | |

| Те | ext Books: |
|----|--|
| 1 | Neville A.M Properties of Concrete, Pearson publication, 2012. |
| 2 | Shetty M.S Concrete technology, S.Chand and Company Ltd, New Delhi 2022. |
| 3 | Santha Kumar A.R Concrete Technology, Oxford university Press, NewDelhi, 2022. |
| 4 | Mehta K.P Concrete Technology, Chand & Co, NewDelhi, 2006. |
| 5 | Robert RatayForensic Structural Engineering Handbook, McGraw Hill LLC, 2009 |

| Ref | erence Books: | | | | | | | | | | | |
|-----|--|--|--|--|--|--|--|--|--|--|--|--|
| 1 | Indian Standard Recommended Guide lines for Concrete Mix Design, IS:10262 – 2019, Bureau of Indian Standards, NewDelhi. | | | | | | | | | | | |
| 2 | Indian Standard Specification for Coarse and Fine Aggregates from Natural Sources for Concrete IS:383-1970 R2011, Bureau of Indian Standards, NewDelhi. | | | | | | | | | | | |
| 3 | Gambhir.M.L,Concrete Technology, Volume I & II, Tata McGraw-HillBookCompany,Third print, 2003 | | | | | | | | | | | |
| 4 | Krishna Raju N. Design of Concrete Mixes, CBS publishers. NewDelhi, 2002. | | | | | | | | | | | |
| 5 | Stephen E. Petty,Forensic Engineering: Damage Assessments for Residential and Commercial Structures,CRCpress,Taylor& Francis,2013. | | | | | | | | | | | |

| | se Outcomes: completion of this course, the students will be able to: | Bloom's Taxonomy Mapped |
|-----|--|-------------------------------|
| CO1 | To identify suitable materials to be used in the cement concrete by conducting various tests as per BIS code. | Evaluate |
| CO2 | To know about the specific applications and uses of admixtures. | Understand |
| CO3 | Design the concrete mix using ACI and BIS code methods. | Create |
| CO4 | Determine the properties of fresh and hardened of concrete. | Evaluate |
| CO5 | Design special concretes and to Ensure quality control while testing/ sampling and acceptance criteria for pre and post construction work. | Apply |

| COs/ POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-------------|-----|-----|-------|----------|----------|---------|----------|----------|---------|-----------|----------|------|------|------|------|
| CO1 | - | - | - | - | 3 | - | 1 | 1 | 1 | 2 | 1 | 1 | 1 | - | 1 |
| CO2 | - | - | - | - | 3 | - | 3 | - | 1 | 1 | - | - | 2 | - | 1 |
| CO3 | - | - | - | - | 3 | - | 3 | - | - | 1 | - | - | 1 | - | 1 |
| CO4 | - | - | - | - | 3 | 2 | 1 | - | - | - | - | - | - | - | 1 |
| CO5 | - | - | - | - | 3 | 3 | 3 | 1 | 1 | 3 | 1 | | 3 | - | 1 |
| Avg | - | - | - | - | 3 | 2.5 | 2.2 | 1 | 1 | 1.75 | 1 | 1 | 1.75 | - | 1 |
| | • | • | 3/2/1 | – indica | ates str | ength o | of corre | lation (| 3- High | n, 2- Meo | lium, 1- | Low) | | | |

| 18CEM04ENVIRONMENTAL ENGINEERINGS | | | | | | | | | |
|-----------------------------------|---|---|-------------------------|-----------|-----------|----------|----------|--|--|
| PR | EREQUISI | TES | Category | OE | Cr | edit | 3 | | |
| NII | ⊿ | | Hours/Week | L | Т | P | TH | | |
| | | 3 | 0 | 0 | 3 | | | | |
| Сог | Course Learning Objectives | | | | | | | | |
| 1 | To evaluate distribution | the sources of water and analyse its characteristics and pr network | ocesses in water trea | itment, e | xpress t | he anal | ysis of | | |
| 2 | To design s disposal | ewer system, basic design of the biological treatment proc | esses, gain knowled | ge on slu | dge tre | atment | and its | | |
| 3 | To predict t | he sources, effects, dispersion of air pollutants air quality | management and its | control r | neasure | s | | | |
| 4 | | the characteristics and sources of municipal solid wast olid wastes and its recovery, disposal methods | es, its collection me | ethods, c | off-site | process | sing of | | |
| 5 | To assess th | ne sources, effects and control measures of noise pollution | | | | | | | |
| | Unit I | WATER TREATMENT | | 9 | 0 | 0 | 9 | | |
| Wat | er Quality an | d its Treatment: Basics of water quality standards - Phy | vsical, chemical and | biologic | al para | meters; | Water | | |
| qual | lity index; Un | it processes and operations; Water requirement; Water dis | tribution system; Dr | inking w | ater tre | atment. | | | |
| | Unit II | WASTEWATER TREATMEN | Г | 9 | 0 | 0 | 9 | | |
| Sew | verage system | design, quantity and quality of domestic wastewater, prin | mary and secondary | treatmen | nt. Efflu | ent dis | charge | | |
| stan | dards; Sludge | e disposal; Reuse of treated sewage for different applicatio | ns. | | | | | | |
| I | Unit III | AIR POLLUTION | | 9 | 0 | 0 | 9 | | |
| Air | Pollution: Ty | pes of pollutants, their sources and impacts, air pollution c | ontrol, air quality sta | andards, | Air qua | lity Ind | ex and | | |
| limi | ts. | | | | | | | | |
| 1 | Unit IV | SOLID WASTE MANAGEMEN | Τ | 9 | 0 | 0 | 9 | | |
| Mur | nicipal Solid V | Wastes: Characteristics, generation, collection and transpor | tation of solid wastes | s, engine | ered sys | stems fo | or solid | | |
| wast | waste management (reuse/ recycle, energy recovery, treatment and disposal). | | | | | | | | |
| Unit VNOISE POLLUTION90 | | | | | | 0 | 9 | | |
| Nois | se pollution: S | Sources; Health effects; Standards; Measurement and cont | rol methods | 1 | | 1 | 1 | | |
| | Total= 45 Periods | | | | | | | | |

| Те | Text Books: | | | | | |
|----|--|--|--|--|--|--|
| 1 | Garg, S.K. Water supply Engineering, Khanna Publishers, New Delhi, 2010. | | | | | |
| 2 | Garg, S.K. Sewage water disposal and Air pollution, Khanna Publishers, New Delhi, 2010. | | | | | |
| 3 | George Tchobanoglous et.al., Integrated Solid Waste Management, McGraw-Hill, Publishers, 1993. | | | | | |
| 4 | Rao, C.S., Environmental Pollution Control Engineering, Wiley Eastern Ltd., New Delhi, 1996. | | | | | |

| Ref | ference Books: |
|-----|--|
| | Manual on Water Supply and Treatment, CPHEEO, Ministry of Urban Development, Government of India, New Delhi, |
| 1 | 2013. |
| 2 | Peavy S.W., Rowe D.R. and Tchobanoglous G. Environmental Engineering, McGraw Hill, NewDelhi, 1985. |
| | Metcalf and Eddy, M.C., Wastewater Engineering – Treatment & Reuse, TataMcGraw-Hill Publications, New |
| 3 | Delhi,2003. |

| | Course Outcomes: Upon completion of this course, the students will be able to: | | | |
|-----|--|------------|--|--|
| CO1 | Identify the sources of water supply, analyze the characteristics of water with its standards and various unit operations and processes in water treatment, express the analysis of distribution network | Remember | | |
| CO2 | Expertise design sewer system, basic design of the biological treatment processes, gain knowledge on sludge treatment and disposal and justify the methods for disposal of sewage | Analyze | | |
| CO3 | Predict the sources, effects, dispersion of air pollutants air quality management and its control measures | Apply | | |
| CO4 | Aware about the characteristics, types and sources of municipal solid wastes, Learn the collection methods, Know about off-site processing of municipal solid wastes and its recovery, disposal methods | Remember | | |
| CO5 | Understand the sources, effects and control methods of noise pollution | Understand | | |

| COs/ POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-------------|--|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| C01 | 2 | 1 | 3 | 2 | 1 | 3 | 2 | 1 | 1 | 2 | 1 | 1 | 3 | - | 2 |
| CO2 | 2 | 1 | 3 | 1 | 1 | 3 | 1 | - | 1 | 2 | 2 | 1 | 3 | - | 2 |
| CO3 | 2 | 1 | 3 | 1 | 1 | 3 | 1 | - | 1 | 2 | 2 | 1 | 3 | - | 2 |
| CO4 | 2 | 1 | 3 | 1 | 1 | 3 | 1 | - | - | 2 | 2 | 1 | 3 | - | 2 |
| CO5 | 2 | - | 3 | - | - | 3 | - | - | - | 2 | 1 | 1 | 3 | - | 2 |
| Avg | 2 | 1 | 3 | 1.3 | 1 | 3 | 1.3 | 1 | 1 | 2 | 1.6 | 1 | 3 | - | 2 |
| | 3/2/1 – indicates strength of correlation (3- High, 2- Medium, 1- Low) | | | | | | | | | | | | | | |

| 18CEM05 BASICS OF TRANSPORTATION ENGINEERING S | | | | | | | | | |
|--|---|--|-----------------------|-----------|----------|----------|---------|--|--|
| PRE | REQUISI | TES | Category | OE | Cre | edit | 3 | | |
| NIL | | | | L | Т | Р | TH | | |
| | | | Hours/Week | 3 | 0 | 0 | 3 | | |
| Cour | se Learni | ng Objectives | | | | | | | |
| 1 | The objec | tive of the course is to educate the students on various co | mponents of highway | y enginee | ering. | | | | |
| 2 | To educat | e the geometric design concepts of highway engineering | | | | | | | |
| 3 | To develo | p skills on construction and maintenance of highway. | | | | | | | |
| 4 | Ability to | plan various civil engineering aspects of railways and ed | ucate various compo | nents of | railway | s | | | |
| 5 | The cours | e enables the students to develop skill on evaluation and | maintenance of railw | ay track. | | | | | |
| U | J nit I | CROSS SECTIONAL ELEMENTS OF H | IIGHWAYS | 9 | 0 | 0 | 9 | | |
| Sight | Distance (S | of Way, Carriage Way, Camber, Kerbs, Shoulders and Foo SSD), Overtaking Sight Distance (OSD), Sight Distance t Distance - Cross Sections of Different Class of Roads - | at Intersections, Int | . 0 | | | | | |
| U | nit II | GEOMETRIC DESIGN OF HIGH | WAYS | 9 | 0 | 0 | 9 | | |
| | ing, Excepti | ments – Superelevation, Widening of Pavements on H onal and Minimum Gradients, Summit and Valley Curve | | | - | | - | | |
| U | nit III | CONSTRUCTION AND MAINTENANCE (| OF HIGHWAY | 9 | 0 | 0 | 9 | | |
| | | Flexible and Rigid Pavements – Defects in Flexible and of Pavements. | Rigid Pavements -Hi | ghway D | Drainage | e – Eva | luation | | |
| U | nit IV | RAILWAY PLANNING AND DES | SIGN | 9 | 0 | 0 | 9 | | |
| Gauge Geom | Permanent Way, its Components and Functions of Each Component: Rails - Types of Rails, Rail Fastenings, Concept of Gauges, Coning of Wheels, Creeps Sleepers - Functions, Materials, Density. Ballasts - Functions, Materials, Ballast less Tracks Geometric Design of Railway Tracks Gradients and Grade Compensation, Super-Elevation, Widening of Gauges in Curves, Transition Curves, Horizontal and Vertical Curves. | | | | | | | | |
| T | nit V | RAILWAY TRACK CONSTRUCTION MAIN | TENANCE AND | 0 | 0 | 0 | 9 | | |
| Unit V OPERATION 9 0 0 | | | | | | | 9 | | |
| | | ngs – Turnouts, Track circuiting, Signaling, Interlocking ower, Track Resistance, Level Crossings. | , Lay Outs of Railwa | y Station | is and Y | Yards, F | Rolling | | |
| | Total= 45 Periods | | | | | | | | |

| Te | ext Books: |
|----|--|
| 1 | Khanna K., Justo C.E.G., Highway Engineering Revised 10th Edition Khanna Publishers, Roorkee, 2014 |
| 2 | Kadiyalil. R, Engineering Traffic and Transport Planning, Khanna Publishers, New Delhi, 2019. |
| 3 | Chandola S.P. Transportation Engineering-2019 |

| Ref | ference Books: |
|-----|--|
| 1 | Sharma S.K., Principles Practice and Design of Highway Engineering, S. Chand & Co Ltd. New Delhi, 2006 |
| 2 | Guidelines Of Ministry of Road Transport and Highways, Government of India. |
| 3 | Agarwal M.M., Indian Railway Track, 14th Edition, Prabha and Co., New Delhi, 2002. |
| 4 | Saxena S.C. Highway & Traffic Engineering, 2014. |

| | Course Outcomes: Upon completion of this course, the students will be able to: | | | | | | |
|-----|--|------------|--|--|--|--|--|
| CO1 | Classify roads as per Indian Road Congress and describe the principles of highway alignment | Understand | | | | | |
| CO2 | Determine the highway geometric elements | Analyse | | | | | |
| CO3 | Differentiate between types of pavements, their construction and design principles | | | | | | |
| CO4 | Explain the functions of components of Railways | Understand | | | | | |
| CO5 | Carry out the various methods for track alignment & procedure for construction of railway & maintenance of track | Apply | | | | | |

| COs/ POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-------------|--|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|------|
| CO1 | - | - | - | - | 2 | 2 | 3 | 1 | 2 | - | - | - | 1 | - | - |
| CO2 | 2 | 3 | 2 | 2 | - | - | - | - | - | - | - | - | - | - | - |
| CO3 | - | - | - | - | 2 | 2 | 3 | 1 | 3 | - | - | - | 1 | - | - |
| CO4 | - | - | - | - | 2 | 2 | 3 | 1 | 2 | - | - | - | - | - | - |
| CO5 | - | - | - | - | 2 | 2 | 3 | 1 | 2 | - | - | - | 1 | - | - |
| Avg | 2 | 3 | 2 | 2 | 2 | 2 | 3 | 1 | 2.25 | - | - | - | 1 | - | - |
| | 3/2/1 – indicates strength of correlation (3- High, 2- Medium, 1- Low) | | | | | | | | | | | | | | |

| 18CI | EM06 | REPAIR AND REHABILITATION OF | STRUCTURES | S | emest | er | | | | |
|---|--|---|---------------------------|-----------|----------|-----------|----------|--|--|--|
| PRE | REQUISI | TES | Category | OE | Cr | edit | 3 | | | |
| NIL | | Hours/Week | L | Т | Р | TH | | | | |
| | 3 0 0 | | | | | | | | | |
| Cour | se Learni | ng Objectives | | 1 | | | 1 | | | |
| 1 | Study the | various types and properties of repair materials | | | | | | | | |
| 2 | Learn var | ious distress and damages to concrete structures | | | | | | | | |
| 3 | Understar | d the importance of maintenance of structures | | | | | | | | |
| 4 | Assess the | e damage to structures using various tests | | | | | | | | |
| 5 | Learn var | ious repair techniques of damaged structures, corroded | structures | | | | | | | |
| τ | J nit I | MAINTENANCE AND REPAIR ST | RATEGIES | 9 | 0 | 0 | 9 | | | |
| Maint | enance, rep | pair and rehabilitation, Facts of Maintenance, import | ance of Maintenance v | arious a | spects | of insp | ection, | | | |
| assess | sment proce | dure for evaluating a damaged structure, causes of dete | rioration. | | | | | | | |
| U | nit II | SERVICEABILITY AND DURABILITY | OF CONCRETE | 9 | 0 | 0 | 9 | | | |
| Quali | ty assuranc | e for concrete construction, concrete properties- stren | ngth, permeability, the | mal pro | perties | and cra | icking- | | | |
| effect | s due to cl | imate, temperature, chemical, corrosion- Design and | l construction errors-et | fects of | cover | thickne | ss and | | | |
| crack | ing. | | | | | | | | | |
| U | nit III | MATERIALS AND TECHNIQUES F | OR REPAIR | 9 | 0 | 0 | 9 | | | |
| Speci | al concretes | and mortar, concrete chemical, special elements for a | ccelerated strength gai | n, expan | sive cei | nent, p | olymer | | | |
| concr | ete, Sulphu | infiltrated concrete, ferro cement, fibre reinforced con- | crete, rust eliminators a | nd polym | ers coa | ting for | rebars | | | |
| during | g repair, foa | med concrete, mortar and dry pack, vacuum concrete, g | unite and shotcrete, epo | oxy injec | tion, m | ortar rej | pair for | | | |
| | - | nd underpinning. Methods of corrosion protection, co | rrosion inhibitors, corre | osion res | istant s | teels, co | oatings | | | |
| and ca | athodic prot | | | T | | 1 | T | | | |
| Unit IVREPAIRS, REHABILITATION AND RETROFITTING OF STRUCTURES9 | | | | | | 0 | 9 | | | |
| Streng | gthening of | Structural elements, deflection, cracking, chemical dist | ruption, weathering cor | rosion, w | ear, fir | e, leaka | ge and | | | |
| | e exposure. | | | - | | | | | | |
| | nit V | DEMOLITION TECHNIQ | | 9 | 0 | 0 | 9 | | | |
| | Demolition methods by machines, explosives, Advanced techniques-Demolition sequences, dismantling techniques, safety | | | | | | | | | |
| preca | precautions in dismantling and demolition, Engineered demolition techniques for dilapidated structures- case studies Total= 45 Periods | | | | | | | | | |
| | | | | | 1 otal | = 45 P | eriods | | | |

| Te | Text Books: | | | | | | | |
|----|---|--|--|--|--|--|--|--|
| 1 | Shetty, M.S, Concrete Technology- Theory and Practice, S. Chand and company, New Delhi,2019 | | | | | | | |
| 2 | Repair and protection of concrete structures by Noel P. Mailvaganam, CRC Press, 1991. | | | | | | | |
| 3 | CPWD: Handbook on Repair & Rehabilitation of R.C.C. Buildings, CPWD, Govt. of India, 2002, updated reprint 2011 | | | | | | | |

| Ref | erence Books: |
|-----|--|
| 1 | Santhakumar A.R, Training Course notes on Damage Assessment and Repair in Low-cost housing, "RHDC.NBO" Anna University, July 1992. |
| 2 | Raikar R.N.,Learning from failures- deficiencies in design, construction and services – R&D Centre (SDCPL), Raikar bhavan, Bombay,1987 |
| 3 | Palaniyappan, N., Estate management, Anna Institute of Management, Chennai, 1992. |
| 4 | Lakshmipathy, M. etal., Lecture notes of workshop on Repairs and Rehabilitation of structures, 29-30 th October 1999. |
| 5 | https://nptel.ac.in/courses/114106035/38 |

| | Course Outcomes: Upon completion of this course, the students will be able to: | | | | | | |
|-----|--|------------|--|--|--|--|--|
| CO1 | Demonstrate the condition of structures | Understand | | | | | |
| CO2 | Inspect and evaluate the damaged structure | Analyze | | | | | |
| CO3 | Implement the repairing techniques of a structure | Analyze | | | | | |
| CO4 | Identify and Use different materials for repairing works | Apply | | | | | |
| CO5 | Demonstrate the dismantling and demolishing structures | Apply | | | | | |

| COs/ POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-------------|--|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| C01 | 1 | - | 2 | 2 | 2 | 2 | 3 | 2 | - | - | - | 1 | 2 | - | - |
| CO2 | 1 | - | 2 | 2 | 2 | 2 | 3 | 2 | - | - | - | 1 | 2 | - | - |
| CO3 | 1 | - | 2 | 2 | 2 | 2 | 3 | 2 | - | - | - | 1 | 2 | - | - |
| CO4 | 1 | - | 2 | 2 | 2 | 2 | 3 | 2 | - | - | - | 1 | 2 | - | - |
| CO5 | 1 | - | 2 | 2 | 2 | 2 | 3 | 2 | - | - | - | 1 | 2 | - | - |
| Avg | 1 | - | 2 | 2 | 2 | 2 | 3 | 2 | - | - | - | 1 | 2 | - | - |
| | 3/2/1 – indicates strength of correlation (3- High, 2- Medium, 1- Low) | | | | | | | | | | | | | | |

| 18CE | EM07 | GREEN BUILDING TECHNOLO | GY | Semester | | | | | |
|--|--|---|-----------------------|----------|----------|----------|---------|--|--|
| PRE | REQUISI | TES | Category | OE | Cre | edit | 3 | | |
| NIL | | | | L | Т | Р | ТН | | |
| INIL | | | Hours/Week | 3 | 0 | 0 | 3 | | |
| Course Learning Objectives | | | | | | | | | |
| 1 To Know various aspects of green buildings | | | | | | | | | |
| 2 | To Learn | the principles of planning and orientation of buildings. | | | | | | | |
| 3 | To Relate | the construction of green building with prevailing energy | conservation policy a | ind regu | lations. | | | | |
| 4 | To Know | and identify different green building construction material | s. | | | | | | |
| 5 | To Learn | different rating systems and their criteria | | | | | | | |
| U | J nit I | INTRODUCTION TO GREEN BUI | LDING | 9 | 0 | 0 | 9 | | |
| | | cessity, Definition & concept of Green Building, Issues a | - | | - | - | | | |
| | | en Building, Components/ features of Green Building, or Air Quality. | Energy Efficiency, | water | efficiei | ncy, M | aterial | | |
| | nit II | SITE SELECTION AND PLANNI | NG | 9 | 0 | 0 | 9 | | |
| Site se | election Sit | e selection strategies, Landscaping, building form, orienta | | ne and | | - | - | | |
| | | techniques, roofs, walls, fenestration and shaded finishes, I | - | - | | | | | |
| | | nwater harvesting methods for roof & non-roof, reducir | ng landscape water o | lemand | by pro | per irri | gation | | |
| systen | ns, recycle a | and reuse systems, Waste Management. | | | | - | | | |
| Uı | nit III | ENERGY AND ENERGY CONSERV | VATION | 9 | 0 | 0 | 9 | | |
| Introd | uction, Env | vironmental impact of building constructions, present scen | nario, Need of energ | y conse | rvation | , Conce | epts of | | |
| emboo | died energy | , | | | | | | | |
| - | - | y and life cycle energy, Methods to reduce operational energy | | - | | - | - | | |
| _ | | naterials, wind and solar energy harvesting, energy meterin | ng and monitoring, co | _ | f net ze | ro buile | | | |
| Uı | nit IV | BUILDING MATERIALS | | 9 | 0 | 0 | 9 | | |
| | - | naterials and products- Bamboo, Rice husk ash concrete, | | - | | | | | |
| | | use of materials with recycled content such as blended cer | - | | • | | | | |
| | tiles, materials from agro and industrial waste, reuse of waste material-Plastic, rubber, Newspaper wood, Nontoxic paint, green roofing. | | | | | | | | |
| | Unit VRATING SYSTEM900 | | | | | | 9 | | |
| Introd | Introduction to Leadership in Energy and Environmental Design (LEED) criteria, Indian Green Building council (IGBC) Gree | | | | | | Green | | |
| - | rating, Green Rating for Integrated Habitat Assessment. (GRIHA) criteria, National Productivity council (NPC) Ministry of | | | | | | • | | |
| New a | New and Renewable Energy (MNRE) Bureau of Energy efficiency (BEE) -BER (Building Energy Rating) – Certificates. | | | | | | | | |
| | | | | | Total= | = 45 Pe | eriods | | |
| | | | | | | | | | |

| Te | ext Books: |
|----|---|
| | Kibert, C.J., Sustainable construction: Green Building design and Delivery, John Wiley Hobouken, NewJersey, 3 rd |
| | Edition, 2012. |
| | Chauhan, D S Sreevasthava, S K., Non-conventional Energy Resources, New Age International Publishers, NewDelhi, |
| 2 | 4 th Edition, 2021 |

| Ref | ference Books: |
|-----|--|
| 1 | O.P. Gupta, Energy Technology, Khanna Publishing House, NewDelhi |
| 2 | Jagadeesh, K S, Reddy Venkatta Rama &Nanjunda Rao, K S., Alternative Building Materials and Technologies, New Age International Publishers, Delhi. |
| 3 | Sam Kubba., Handbook of Green Building Design and Construction, Butterworth- Heinemann. |
| 4 | Means R S, Green Building - Project Planning and Cost Estimating, John Wiley &Sons |
| 5 | Sharma K V, Venkataseshaiah P., Energy Management and Conservation, IK International. |

| | Course Outcomes: Upon completion of this course, the students will be able to: | | | | | | |
|-----|--|------------|--|--|--|--|--|
| CO1 | Understand the concepts of Green Building | Understand | | | | | |
| CO2 | Discuss the Planning of Green Building. | Understand | | | | | |
| CO3 | Explain the concept of Energy and Energy Conservation. | Understand | | | | | |
| CO4 | Select appropriate green building material and technique. | Understand | | | | | |
| CO5 | Summarize the Green Building Functions in various organizations. | Understand | | | | | |

| COs/ POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-------------|--|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| CO1 | - | - | - | 1 | - | 2 | 3 | - | - | - | 2 | 1 | 2 | - | - |
| CO2 | 1 | 1 | 1 | 2 | 1 | - | - | - | - | - | - | - | 2 | - | - |
| CO3 | - | 1 | 3 | - | 2 | - | - | - | - | - | - | - | 2 | - | - |
| CO4 | - | 1 | 2 | - | 3 | - | - | - | - | - | 2 | - | 2 | - | - |
| CO5 | 1 | 1 | 2 | 3 | 2 | - | - | - | - | - | 2 | - | 2 | - | - |
| Avg | 1 | 1 | 2 | 2 | 2 | 2 | 3 | - | - | - | 2 | 1 | 2 | - | - |
| | 3/2/1 – indicates strength of correlation (3- High, 2- Medium, 1- Low) | | | | | | | | | | | | | | |

B.E. – COMPUTER SCIENCE ENGINEERING - MINOR DEGREE

| 1805 | 18CSM01 PROGRAMMING IN C++ | | | | | | | | | |
|---|---|--|--------------------------------|---------|---------|----------|----------|--|--|--|
| PRER | EQUIS | ITES | Category | OE | Cre | edit | 3 | | | |
| | | | Hours/Week | L | TH | | | | | |
| | | 3 | 0 | 0 | 3 | | | | | |
| Cours | e Learn | ing Objectives | | | | | | | | |
| 1 | To und | erstand and develop the object oriented programming concepts | s. | | | | | | | |
| 2 | To fam | iliarize and design the template functions and classes | | | | | | | | |
| 3 | To diss | eminate and apply exception handling mechanisms. | | | | | | | | |
| 4 | To lear | n and exploit stream classes. | | | | | | | | |
| Un | it I | INTRODUCTION | | 9 | 0 | 0 | 9 | | | |
| program | nming, t | ted programming paradigm - Object oriented programming penefits of OOP, application of OOP - C++ fundamentals xpressions - Control structures - Functions. | • • • | | - | | | | | |
| Un | it II | INHERITANCE AND VIRTUAL FUNCT | TIONS | 9 | 0 | 0 | 9 | | | |
| | | jects - friend functions- constructors and destructors- Open ng member function and friend function - Type conversions. | erator overloading | – bina | ry and | unary o | operator | | | |
| Uni | t III | INHERITANCE AND VIRTUAL FUNCT | ERITANCE AND VIRTUAL FUNCTIONS | | | | | | | |
| | | fining derived classes, types, virtual base classes, abstract clas cts, this pointer, pointer to derived classes - Virtual functions. | sses, constructor in | derived | classes | - Pointe | ers- | | | |
| Uni | t IV | TEMPLATES AND EXCEPTION HAND | LING | 9 | 0 | 0 | 9 | | | |
| Generic Classes – class template, class templates with multiple parameters - Generic Functions - function templates, function templates with multiple parameters, member function templates - Exception handling – basics, exception handling mechanism, rethrowing an exception – Exception handling options – understanding terminate() and unexpected() – the uncaught_exception() function – bad_exception(). | | | | | | | | | | |
| Un | Unit VCONSOLE I/O AND FILE HANDLING900 | | | | | | | | | |
| | C++ Stream Classes – unformatted I/O operations, formatted console I/O operations, manipulators - Files-classes for file operation, opening and closing a file, detecting end of file, files modes, sequential file operations, random file operations. | | | | | | | | | |
| | Total (45 L) =45 Periods | | | | | | | | | |

| Text | Text Books: | | | | | | | |
|-------|--|--|--|--|--|--|--|--|
| 1 | E. Balagurusamy "Object – Oriented Programming with C++" Sixth Edition Tata McGraw-Hill | | | | | | | |
| Refer | Reference Books: | | | | | | | |
| 1 | Herbert Schildt, "The Complete Reference C++", Fifth Edition, Tata McGraw Hill | | | | | | | |
| 2 | Bjarne Stroustrup, "The C++ programming language", Fourth Edition Addison Wesley | | | | | | | |
| 3 | K.R.Venugopal, Rajkumar Buyya, T.Ravishankar, Mastering in C++, Second Edition, Tata McGraw Hill | | | | | | | |

| | Course Outcomes: Upon completion of this course, the students will be able to: | | | | | | | |
|-----|---|------------|--|--|--|--|--|--|
| CO1 | Build the object oriented programming concepts. | Apply | | | | | | |
| CO2 | Familiarize and build the template functions and classes | Understand | | | | | | |
| CO3 | Disseminate and apply exception handling mechanisms. | Apply | | | | | | |
| CO4 | Depict and exploit steam classes. | Understand | | | | | | |

| 180 | CSM02 | ADVANCED DATA STRUCTURES AND AL | GORITHMS | | | | |
|-------|---------------------------|--|---------------------|----------|-----------|-----------|----------|
| PRE | REQUIS | ITES | Category | OE | Cr | edit | 3 |
| | | | | L | Т | Р | ТН |
| | | | Hours/Week | 3 | 0 | 0 | 3 |
| Cou | rse Learn | ing Objectives | | | | | |
| 1 | To und | erstand the concepts of ADTs | | | | | |
| 2 | To Lea | rn linear data structures – lists, stacks, and queues | | | | | |
| 3 | To have | e knowledge about non-linear data structures like trees and gra | aphs | | | | |
| 4 | To und | erstand concepts about searching and sorting and hashing tech | iniques | | | | |
| U | Init I | LINEAR DATA STRUCTURES – LIS | ST | 9 | 0 | 0 | 9 |
| Circu | larly Linke | ypes (ADTs) – List ADT - Array based Implementation - Lined Lists - Doubly-Linked Lists - Applications of Lists – Polye, Traversal). | - | | | | |
| U | nit II | LINEAR DATA STRUCTURES –STACKS AN | D QUEUES | 9 | 0 | 0 | 9 |
| | - | verations - Applications of Stacks - Evaluating Arithmetic Exp Operations - Circular Queue - DeQueue - Applications of Que | | n of inf | ix to po | stfix Exp | pression |
| U | nit III | NON LINEAR DATA STRUCTURES – T | REES | 9 | 0 | 0 | 9 |
| Threa | ded Binar | ee traversals – Binary Tree ADT – Expression Trees – Applica y Trees- AVL Trees – B-Tree – Heaps - Operations of Heaps plications of Heap. | | - | | | |
| U | nit IV | NON LINEAR DATA STRUCTURES – GI | RAPHS | 9 | 0 | 0 | 9 |
| Appli | | presentation of Graphs –Types of Graphs - Graph Traversals - Graph Structures: Shortest Path Problem: Dijkstra's Algorithm ithms | | - | - | | |
| U | nit V | SEARCHING, SORTING AND HASHING TE | CHNIQUES | 9 | 0 | 0 | 9 |
| | · Merge So | ar Search - Binary Search - Sorting Algorithms - Insertion Sort ort - Radix Sort - Hashing: Hash Functions – Separate Chain | | | | | - |
| | | | | Tota | al (45 L | L) =45 I | Periods |
| | (D 1 | | | | | | |
| | ext Books | | Deener Education | - 2012 | | | |
| | | n Weiss, "Data Structures and Algorithm Analysis in C", 4/E | Pearson Education | n, 2013. | | | |
| | erence B | | | | | | |
| | Seymour I Pvt. Ltd., 2 | Lipschutz, "Data Structures With C ",(Schaum's Outline Ser 2015 | ries) Published by | Tata N | IcGraw | -Hill Ed | ucation |
| 2 | Ellis Horo | witz, Sartaj Sahni, Dinesh Mehta, "Fundamentals of Data Stru | ctures In C", Secor | nd Editi | on, Silio | con Pres | s, 2008. |
| 5 | | Gilberg & Behrouz A.Forouzan, "Data Structures: A Pseudo c Publishers,2005. | code Approach With | h C", So | econd E | dition, (| Cengage |
| 4 | Classic Da | ta Structures", Second Edition by Debasis Samanta, PHI Lear | ning, 2009. | | | | |

| Cours Upon | Bloom's Taxonomy Level | |
|---------------|--|---------|
| CO1 | Implement various abstract data types to solve real time problems by using Linear Data Structures | Apply |
| CO2 | Apply the different Non-Linear Data Structures to solve problems | Apply |
| CO3 | Analyze and implement graph data structures to solve various computing problems. | Analyze |
| CO4 | Critically analyze the various sorting and searching algorithms | Analyze |

| 18CSM03 | COMPUTER ORGANIZATION AND D | ESIGN | | | | |
|------------------------------|--|---------------------|-----------|----------|-----------|----------|
| PREREQUIS | ITES | Category | OE Credit | | 3 | |
| | | | L | L T P | | ТН |
| | | Hours/Week | 3 | 0 | 0 | 3 |
| Course Learn | ing Objectives | | | | 1 | 1 |
| 1 To und | erstand the basic structure and operations of digital computer | | | | | |
| 2 To lear | n the working of different arithmetic operations | | | | | |
| 3 To und | erstand the different types of control and the concept of pipelin | ing | | | | |
| 4 To stud | y the hierarchical memory system including cache memory and | d virtual memory | | | | |
| 5 To und | erstand the different ways of communication with I/O devices a | and standard I/O ir | nterface | 8 | | |
| UNIT I | INTRODUCTION | | 9 | 0 | 0 | 9 |
| | ,Basic Operational Concepts, Bus Structure ,Memory Locatior Sequencing, Addressing modes. | ns and Addresses, I | Memory | Operati | ons, Ins | truction |
| UNIT II | ARITHMETIC UNIT | | 9 | 0 | 0 | 9 |
| | btraction of Signed Numbers, Design of Fast Adders, Multiplic Integer Division, Floating point number operations. | ation of Positive N | lumbers | , Booth | Algorith | nm, Fast |
| UNIT III | PROCESSOR UNIT AND PIPELININ | IG | 9 | 0 | 0 | 9 |
| | oncepts, Execution of Instruction, Multi Bus Organization, Har of pipelining, Data Hazards, Instruction Hazards, Data path & | | - | ogramm | ed cont | rol, |
| UNIT IV | MEMORY SYSTEMS | | 9 | 0 | 0 | 9 |
| - | Semiconductor RAM, ROM, Cache memory, Improving Cac quirements, Secondary Storage Device. | he Performance, V | /irtual r | nemory | ,Memor | У |
| UNIT V | INPUT AND OUTPUT ORGANIZATI | ON | 9 | 0 | 0 | 9 |
| Accessing I/O of SCSI, USB). | levices, Programmed I/O, Interrupts, Direct Memory Access, | Interface circuits, | Standa | rd I/O 1 | Interface | es (PCI, |
| | | | Tota | l (45 L |) =45 I | Periods |

| Text | t Books: |
|-------|---|
| 1 | Carl Hamacher V., Zvonko G. Vranesic, Safwat G. Zaky, " Computer organization ", Tata McGraw Hill, 5th Edition, 200 |
| Refer | rence Books: |
| 1 | Patterson and Hennessey, "Computer Organization and Design ". The Hardware/Software interface, Harcourt Asia Morgan Kaufmann, 3rd Edition, 2007 |
| 2 | Hayes, "Computer Architecture and Organization ", 3rd edition, Tata McGraw Hill, 2006 |
| 3 | Heuring V.P., Jordan H.F., " Computer System Design and Architecture ", 6th edition ,Addison Wesley,2008 |

| Course Outcomes: Upon completion of this course, the students will be able to: | | Bloom's Taxonomy Level |
|--|---|------------------------------|
| CO1 | Understand the working principles of computer componets | Understand |
| CO2 | Design the arithmetic and processing units | Create |
| CO3 | Analyze the various computer components | Analyze |

\

| 18CS | SM04 | ADVANCED OPERATING SYSTE | MS | Semester | | | |
|---|--|--|---|---|---|---|--|
| PRER | EQUIS | ITES | Category | OE | Cre | edit | 3 |
| | | | | L | Т | Р | ТН |
| | | | Hours/Week | 3 | 0 | 0 | 3 |
| Cours | e Learn | ing Objectives | | | l | | |
| 1 | To un | derstand the structure and functions of Operating systems | | | | | |
| 2 | To un | derstand the process concepts and scheduling algorithms | | | | | |
| 3 | To un | derstand the concept of process synchronization and deadlock | S | | | | |
| 4 | To lea | rn various memory management schemes | | | | | |
| 5 | To illu | istrate various file systems and disk management strategies | | | | | |
| UNIT | ГΙ | INTRODUCTION AND OPERATING SYSTEM S | STRUCTURES | 9 | 0 | 0 | 9 |
| Hand h | held Syste | tems, Desktop Systems, Multiprocessor Systems, Distributed ems; Operating Systems Structures - System Components, C m Design and Implementation. | | - | | | - |
| UNIT | ΓII | PROCESS MANAGEMENT | | 9 | 0 | 0 | 9 |
| Commu Schedu | unication lling Algo | | Scheduling-Basic | Concept | ts, Sche | duling (| Criteria, |
| UNIT | ΓIII | PROCESS SYNCHRONIZATION AND DEA | DLOCKS | 9 | 0 | 0 | 0 |
| | | | | | | U | 9 |
| Synchr | onization | onization- The Critical Section Problem, Synchronization , Monitors; Deadlocks- Deadlock Characterization, Method lance ,Deadlock Detection, Recovery from Deadlock. | | - | | al Prot | olem of |
| Synchr | onization ck Avoid | onization- The Critical Section Problem, Synchronization Monitors; Deadlocks- Deadlock Characterization, Method | s for handling Dea | - | | al Prot | olem of |
| Synchro Deadlo UNIT Memor | onization ck Avoid F IV ry Manag | onization- The Critical Section Problem, Synchronization , Monitors; Deadlocks- Deadlock Characterization, Method lance ,Deadlock Detection, Recovery from Deadlock. | s for handling Dea | adlocks 9 | , Deadlo | cal Protock Prev | olem of vention, |
| Synchro Deadlo UNIT Memor | onization ck Avoid Γ IV ry Manag ; Virtual 1 | onization- The Critical Section Problem, Synchronization , Monitors; Deadlocks- Deadlock Characterization, Method lance ,Deadlock Detection, Recovery from Deadlock. MEMORY MANAGEMENT AND VIRTUAL gement- Background, Swapping, Contiguous Memory Alloc | s for handling Dea MEMORY ation, Paging, Seg | adlocks 9 | , Deadlo | cal Protock Prev | olem of vention, |
| Synchro Deadlo UNIT Memor paging; UNIT File Sy Implem | onization ck Avoid F IV ry Manag ; Virtual 1 F V ystem Int nentation- ement; M | onization- The Critical Section Problem, Synchronization , Monitors; Deadlocks- Deadlock Characterization, Method lance ,Deadlock Detection, Recovery from Deadlock. MEMORY MANAGEMENT AND VIRTUAL gement- Background, Swapping, Contiguous Memory Alloc Memory - Demand paging, Page Replacement, Thrashing. | s for handling Dea MEMORY ation, Paging, Seg RUCTURE rure, File Sharing, nplementation, All | 9 mentati 9 File P ocation | , Deadlo 0 on, Seg 0 rotectio Metho | al Prob ock Pre 0 mentation 0 n; File ds, Free | olem of vention, 9 on with 9 System e Space |
| Synchro Deadlo UNIT Memor paging; UNIT File Sy Implem Manage | onization ck Avoid F IV ry Manag ; Virtual 1 F V ystem Int nentation- ement; M | onization- The Critical Section Problem, Synchronization Monitors; Deadlocks- Deadlock Characterization, Method lance ,Deadlock Detection, Recovery from Deadlock. MEMORY MANAGEMENT AND VIRTUAL gement- Background, Swapping, Contiguous Memory Alloc Memory - Demand paging, Page Replacement, Thrashing. FILE SYSTEM AND MASS-STORAGE STF terface - File Concepts, Access methods, Directory Struct - File System Structure and Implementation, Directory In | s for handling Dea MEMORY ation, Paging, Seg RUCTURE rure, File Sharing, nplementation, All | 9 mentati 9 File P ocation D Struc | , Deadlo 0 on, Seg 0 rotectio Metho ture; Ca | al Prob ock Prev 0 mentation n; File ds, Free use study | olem of vention, 9 on with 9 System e Space |
| Synchro Deadlo UNIT Memor paging; UNIT File Sy Implem Manage | onization ck Avoid F IV ry Manag ; Virtual 1 F V ystem Int nentation- ement; M | onization- The Critical Section Problem, Synchronization Monitors; Deadlocks- Deadlock Characterization, Method lance ,Deadlock Detection, Recovery from Deadlock. MEMORY MANAGEMENT AND VIRTUAL gement- Background, Swapping, Contiguous Memory Alloc Memory - Demand paging, Page Replacement, Thrashing. FILE SYSTEM AND MASS-STORAGE STF terface - File Concepts, Access methods, Directory Struct - File System Structure and Implementation, Directory In | s for handling Dea MEMORY ation, Paging, Seg RUCTURE rure, File Sharing, nplementation, All | 9 mentati 9 File P ocation D Struc | , Deadlo 0 on, Seg 0 rotectio Metho ture; Ca | al Prob ock Prev 0 mentation n; File ds, Free use study | 9 on with 9 System e Space v: Linux |
| Synchro Deadlo UNIT Memor paging; UNIT File Sy Implem Manago system. | onization ck Avoid F IV ry Manag ; Virtual 1 F V ystem Int nentation- ement; M | onization- The Critical Section Problem, Synchronization , Monitors; Deadlocks- Deadlock Characterization, Method lance ,Deadlock Detection, Recovery from Deadlock. MEMORY MANAGEMENT AND VIRTUAL gement- Background, Swapping, Contiguous Memory Alloc Memory - Demand paging, Page Replacement, Thrashing. FILE SYSTEM AND MASS-STORAGE STF terface - File Concepts, Access methods, Directory Struct - File System Structure and Implementation, Directory In Iass-Storage Structure - Disk Structure, Disk scheduling, Disk | s for handling Dea MEMORY ation, Paging, Seg RUCTURE rure, File Sharing, nplementation, All | 9 mentati 9 File P ocation D Struc | , Deadlo 0 on, Seg 0 rotectio Metho ture; Ca | al Prob ock Prev 0 mentation n; File ds, Free use study | 9 on with 9 System e Space v: Linux |
| Synchro Deadlo UNIT Memor paging; UNIT File Sy Implem Manago system. | onization ck Avoid F IV y Manag ; Virtual 1 F V ystem Int nentation- ement; M t Books | onization- The Critical Section Problem, Synchronization , Monitors; Deadlocks- Deadlock Characterization, Method lance ,Deadlock Detection, Recovery from Deadlock. MEMORY MANAGEMENT AND VIRTUAL gement- Background, Swapping, Contiguous Memory Alloc Memory - Demand paging, Page Replacement, Thrashing. FILE SYSTEM AND MASS-STORAGE STF terface - File Concepts, Access methods, Directory Struct - File System Structure and Implementation, Directory In Iass-Storage Structure - Disk Structure, Disk scheduling, Disk | s for handling Des MEMORY ation, Paging, Seg RUCTURE rure, File Sharing, nplementation, All Management, RAI | 9 mentati 9 File P ocation D Struc Tota | , Deadlo 0 on, Seg 0 rotectio Metho ture; Ca 1 (45 L | al Prob ock Prev 0 mentation n; File ds, Free se study) =45 I | olem of vention, 9 on with 9 System e Space 7: Linux Periods |
| Synchro Deadlo UNIT Memor paging; UNIT File Sy Implem Manage system. | onization ck Avoid F IV y Manag ; Virtual 1 F V ystem Int nentation- ement; M t Books | onization- The Critical Section Problem, Synchronization , Monitors; Deadlocks- Deadlock Characterization, Method lance ,Deadlock Detection, Recovery from Deadlock. MEMORY MANAGEMENT AND VIRTUAL gement- Background, Swapping, Contiguous Memory Alloc Memory - Demand paging, Page Replacement, Thrashing. FILE SYSTEM AND MASS-STORAGE STR terface - File Concepts, Access methods, Directory Struct - File System Structure and Implementation, Directory Im lass-Storage Structure - Disk Structure, Disk scheduling, Disk : ham Silberschatz, P.B.Galvin, G.Gagne —Operating System C | s for handling Des MEMORY ation, Paging, Seg RUCTURE rure, File Sharing, nplementation, All Management, RAI | 9 mentati 9 File P ocation D Struc Tota | , Deadlo 0 on, Seg 0 rotectio Metho ture; Ca 1 (45 L | al Prob ock Prev 0 mentation n; File ds, Free se study) =45 I | olem of vention, 9 on with 9 System e Space 7: Linux Periods |

 1
 Andrew S. Tanenbaum, —Modern Operating Systems, PHI , 2nd edition, 2001

 2
 D.M.Dhamdhere, "Systems Programming and Operating Systems ", 2nd edition, Tata McGraw Hill Company, 1999.

3 Maurice J. Bach, —The Design of the Unix Operating System, 1st edition, PHI, 2004.

| Cours Upon | Bloom's Taxonomy Level | |
|---------------|---|---------|
| CO1 | Identify the components and their functionalities in the operating system | Apply |
| CO2 | Apply various CPU scheduling algorithms to solve problems | Apply |
| CO3 | Analyze the needs and applications of process synchronization and deadlocks | Analyze |
| CO4 | Apply the concepts of memory management including virtual memory and page replacement to the issues that occur in real time applications | Apply |
| CO5 | Solve issues related to file system implementation and disk management | Apply |

| 1805 | 18CSM05 DATA COMMUNICATION AND COMPUTER NETWORKS Semester | | er | | | | |
|-------------------|--|---|--------------------|----------|----------|------------------|----------|
| PRER | REQUIS | ITES | Category | OE | Cr | edit | 3 |
| | | | | L | Т | Р | ТН |
| | | | Hours/Week | 3 | 0 | 0 | 3 |
| Cours | e Learn | ing Objectives | | | | | |
| 1 | To stud | y the concepts of data communications and functions of differ | ent ISO/OSI refere | ence arc | hitectur | e | |
| 2 | To unde | erstand the error detection and correction methods and also the | e types of LAN | | | | |
| 3 | To stud | y the concepts of subnetting and routing mechanisms | | | | | |
| 4 | To unde | erstand the different types of protocols and congestion control | | | | | |
| 5 | To stud | y the application protocols and network security | | | | | |
| UNI | ГΙ | DATA COMMUNICATIONS AND PHYSICA | AL LAYER | 9 | 0 | 0 | 9 |
| Interc | onnection | ication; Networks- Physical Structures (Types of Connection n of Networks: Internetwork; Protocols and Standards; Networks: sing; Transmission media-Guided Media, Unguided Media. | • • | | - | | |
| UNIT | ΓII | DATA LINK LAYER | | 9 | 0 | 0 | 9 |
| Correct Window | tion (VR w),Error | pes of errors, Redundancy, Detection versus Correction, Modu C,LRC,CRC, Checksum, Hamming Code);Data link Co Control (Automatic Repeat Request, Stop-and-wait ARQ, Slid Bus, Token Ring, FDDI. | ntrol- Flow Cont | rol (St | op- and | l-Wait, | Sliding |
| UNI | ГШ | NETWORK LAYER | | 9 | 0 | 0 | 9 |
| | • | r services-Packet Switching-Network Layer Performance-IPvaters-Routing Algorithm-Distance Vector Routing, Link State | | ddressir | ıg- Subi | netting-l | Bridges- |
| UNI | ГІ | TRANSPORT LAYER | | 9 | 0 | 0 | 9 |
| | | ransport layer-User Datagram Protocol-Transmission Contr tion, Congestion Control, Quality of Service, Techniques to in | | | | and Qu | ality of |
| UNI | ΓV | PRESENTATION LAYER AND APPLICATION I | LAYER | 9 | 0 | 0 | 9 |
| Doma | ain Name | System - Domain Name Space, DNS in the Internet; Electron | ic Mail-FTP- HTT | P- Wor | ld Wide | Web. | 1 |
| | | | | Tota | al (45 L | .) = 45 I | Periods |
| Tev | t Books | • | | | | | |
| | | | | | | | |
| 1 | Behrouz | z A.Ferouzan, "Data Communications and Networking", 4th E | dition, Tata McGra | w-Hill, | 2007. | | |
| Refe | rence B | ooks: | | | | | |
| 1 | Andrey | v S. Tanenbaum, "Computer networks "PHI, 4 th edition 2008 | | | | | |

| 2 | William Stallings," Data and computer communications", 10th edition, PHI, 2012 |
|---|--|

3 Douglas E. comer," Internetworking with TCP/IP-Volume-I", 6th edition,PHI, 2008

| | Course Outcomes: Upon completion of this course, the students will be able to: | | |
|-----|--|------------|--|
| CO1 | Classify the fundamentals of data communications and functions of layered architecture | Understand | |
| CO2 | Apply the error detection and correction methods and also identify the different network technologies | Apply | |
| CO3 | Analyze the requirements for a given organizational structure and select the most appropriate networking architecture and routing technologies | Analyze | |
| CO4 | Illustrate the transport layer principles and reliable data transfer using protocols | Apply | |
| CO5 | Analyze the application layer protocols and also the use of network security | Analyze | |

| 18CSM06 | 06 PROGRAMMING ESSENTIALS IN PYTHON | | S | emest | er | | |
|-----------------|--|---------------------|----------|----------|-----------|----------|----|
| PREREQUIS | ITES | Category | OE | Cr | edit | 3 | |
| | | | L | L | Т | Р | ТН |
| | | Hours/Week | 3 | 0 | 0 | 3 | |
| Course Learn | ing Objectives | | | | | | |
| 1 To lear | n Python data structures, conditional and control structures and | d files | | | | | |
| 2 To stud | y Python Modules, packages, Functions and Exceptions. | | | | | | |
| 3 To des | cribe Object oriented programming features and Regular Expre | essions. | | | | | |
| 4 To lear | n about Web programming, GUI Programming and Database | programming | | | | | |
| UNIT I | INTRODUCTION | | 9 | 0 | 0 | 9 | |
| | s - The Basics-Python Objects-Numbers-Sequences-Mapping a lif-Conditional Expressions-while statement-for statement-bre | | itionals | and loc | ps-if sta | itement- | |
| UNIT II | FUNCTIONS, MODULES AND PACKA | GES | 9 | 0 | 0 | 9 | |
| | ng functions-Creating functions-Passing Functions-Formal n, Modules-Packages. | Arguments-Variab | ole leng | gth arg | uments- | variable | |
| UNIT III | FILES AND EXCEPTIONS | | 9 | 0 | 0 | 9 | |
| | Output –Errors and Exceptions-Introduction-Detecting and herrions-Standard Exceptions. | andling Exceptions | -Conte | t Mana | gement- | Raising | |
| UNIT IV | OBJECT ORIENTED PROGRAMMING AND EXPRESSIONS | REGULAR | 9 | 0 | 0 | 9 | |
| | ed Programming Introduction-Classes-class Attributes-Insta | | | | e | | |
| Invocation-Stat | c methods and class Methods-Inheritance-Operator overloadir | ig - Regular Expres | sions-N | etwork | Program | nmıng – | |
| UNIT V | ADVANCED TOPICS | | 9 | 0 | 0 | 9 | |
| | | | , | v | Ŭ | , | |
| GUI Programm | ing- Web Programming-Database Programming | | | | | | |
| | | | Tota | al (45 L |) =45 I | Periods | |

| Tex | Text Books: | | | | | |
|------|--|--|--|--|--|--|
| 1 | 1 Wesley J.Chun-"Core Python Programming" –Prentice Hall, Second Edition, 2006. | | | | | |
| Refe | Reference Books: | | | | | |
| 1 | Swaroop C N, "A Byte of Python ", ebshelf Inc., 1st Edition, 2013 | | | | | |
| 2 | "A Practical Introduction to python programming", Brian Heinold, Mount St. Mary's University, 2012 | | | | | |
| 3 | Learning to Program with Python," Richard L. Halterman"., Southern Adventist University | | | | | |

| | Course Outcomes: Upon completion of this course, the students will be able to: | | |
|-----|--|--------|--|
| CO1 | Develop programs using control structures and files. | Create | |
| CO2 | Create own Python Modules, packages, functions and Exceptions. | Create | |
| CO3 | Illustrate Object oriented Programming features and Regular Expressions. | Apply | |
| CO4 | Create own Web programs, GUI and database programs. | Create | |

| 22CS | SM07 | ADVANCED DATABASE SYSTEM CO | NCEPTS | Semeste | | | |
|-----------------|-----------|--|-------------------|-----------|----------|----------|---------|
| PRER | EQUIS | ITES | Category | OE Credit | | | 3 |
| | | L | Т | Р | ТН | | |
| | | 3 | 0 | 0 | 3 | | |
| Cours | e Learn | ing Objectives | | • | | | |
| 1 | To unde | erstand the fundamentals of data models, SQL queries and rela | ational databases | | | | |
| 2 | To mak | e a study of database design using ER Diagram and normalize | 2 | | | | |
| 3 | To impa | art knowledge in transaction processing. | | | | | |
| 4 | To mak | e the students to understand the file operations and indexing | | | | | |
| 5 | To fami | liarize the students with advanced databases | | | | | |
| UNI | ΓI | RELATIONAL DATABASES | | 9 | 0 | 0 | 9 |
| – Relat SQL. | ional Mo | pase System – Views of data – Data Models – Database System del – Keys – Relational Algebra – SQL fundamentals – Adv | | | | | |
| ÛNI | ΓII | DATABASE DESIGN | | 9 | 0 | 0 | 9 |
| | | hip model – E-R Diagrams – Enhanced-ER Model – ER-to- position – First, Second, Third Normal Forms, Dependency H | | | | | |
| valued | Depender | ncies and Fourth Normal Form - Join Dependencies and Fifth | | | | | |
| UNI | ſ III | TRANSACTION | | 9 | 0 | 0 | 9 |
| Protoco | ols – Two | cepts – ACID Properties – Schedules – Serializability – Concu o Phase Locking – Deadlock – Transaction Recovery – Sav d Recovery. | | | | | |
| UNI | | IMPLEMENTATION TECHNIQUE | S | 9 | 0 | 0 | 9 |
| B tree | Index Fil | ganization – Organization of Records in Files – Indexing and es – Static Hashing – Dynamic Hashing – Query Processing ery optimization using Heuristics and Cost Estimation. | | | | | |
| UNI | ΓV | ADVANCED TOPICS | | 9 | 0 | 0 | 9 |
| Object- | Relationa | bases: Architecture, Data Storage, Transaction Processing – O al features, ODMG Object Model, ODL, OQL – XML Da y – Data Warehousing and Data Mining - information Retriev | tabases: XML Hie | erarchic | al Mod | el, DTD | , XML |
| | | | | Tota | al (45 L | .) =45 I | Periods |
| | | | | | | - | |

| Text | t Books: |
|-------|--|
| 1 | Abraham Silberschatz, Henry F.Korth and S.Sundarshan "Database System Concepts", Sixth Edition, Tata McGraw Hi 2011. |
| Refer | rence Books: |
| 1 | Ramez Elamassri and Shankant B-Navathe, "Fundamentals of Database Systems", Sixth Edition, Pearson Education, 2011. |
| 2 | C.J. Date, "An Introduction to Database Systems", Eighth Edition, Pearson Education Delhi, 2008. |
| 3 | Raghu Ramakrishnan, —Database Management Systems, Fourth Edition, McGraw-Hill CollegePublications, 2015. |
| 4 | G.K.Gupta,"Database Management Systems", Tata McGraw Hill, 2011. |
| E-Ref | erences: |
| 1. | Lecture Series on Database Management System by Dr.S.Srinath, IIIT Bangalore, nptl |

| Cours Upon | Bloom's Taxonomy Level | |
|---------------|--|------------|
| CO1 | Understand the basic concepts of the database and data models. | Understand |
| CO2 | Design a database using ER diagrams and map ER into Relations and normalize the relations. | Create |
| CO3 | Develop a simple database for applications | Create |

| 18CS | SM08 | VIRTUALIZATION AND CLOUD COM | S | | | | |
|--------------------|-------------------------|--|-------------------|----------|-----------|-----------|------------|
| PRER | EQUIS | ITES | Category | OE | DE Credit | | 3 |
| | | | | L | Т | Р | ТН |
| | | | Hours/Week | 3 | 0 | 0 | 3 |
| Cours | e Learn | ing Objectives | | | | | |
| 1 | | roduce the broad perceptive of Parallel Computing, Distributed | l Computing and C | Cloud C | omputii | ng. | |
| 2 | To un | derstand the concept of Virtualization | | | _ | - | |
| 3 | To ide | entify the approaches of SLA and programming model in Cloud | d | | | | |
| 4 | To un | derstand the Cloud Platforms in Industry and Software Environ | nments. | | | | |
| 5 | To lea | rn to design the trusted Cloud Computing system | | | | | |
| UNI | ΓI | INTRODUCTION | | 9 | 0 | 0 | 9 |
| Compu | ting; Vis | rallel and Distributed Computing – Elements of Parallel and Dis ion of Cloud, Defining a Cloud, characteristics and benefits; G f Clouds, Open Challenges. | | | | | |
| UNI | TII | VIRTUALIZATION | | 9 | 0 | 0 | 9 |
| Virtual Full Vi | ization a rtualizati | | ogy examples-Xen | : Para v | virtualiz | ation, V | Mware: |
| UNI | 1 111 | SLA MANAGEMENT IN CLOUD COMPUT PROGRAMMING MODEL | 9 | 0 | 0 | 9 | |
| | | roaches to SLA Management, Types of SLA, Life Cycle of S chnologies for Data Intensive Computing, MapReduce Program | | ment ir | Cloud | ; Data Iı | ntensive |
| UNI | ΓIV | CLOUD INDUSTRIAL PLATFORMS AND SO ENVIRONMENTS | 9 | 0 | 0 | 9 | |
| | | s in Industry - Amazon Web Service, Google App Engin neka Cloud Application Platform-Aneka Framework Overview | | | | ts –Euc | alyptus, |
| UNI | ΓV | CLOUD SECURITY AND APPLICATION | ONS | 9 | 0 | 0 | 9 |
| Securit | y Risk, C | to the Idea of Data Security, The Current State of Data Sec Cloud Computing and Identity; The Cloud, Digital Identity, and entific Applications. | | | | | |
| | | | | Tota | al (45L |) = 45 I | Periods |
| | | | | | | | |
| Tex 1 | t Books Raikum | : ar Buyya, Christian Vecchiola, S.Tamarai Selvi, 'Mastering | Cloud Computing | z-Found | lations | and An | olications |
| 1 | | ming", TMGH,2013.(Unit- I,II & IV) | companie | | | · · · PI | |

| - | RajKumar Buyya, James Broberg, Andrezei M.Goscinski, "Cloud Computing: Principles and paradigms",2011(Unit-III & V) |
|-------|--|
| Refer | rence Books: |
| 1 | Kai Hwang.GeoffreyC.Fox.JackJ.Dongarra, "Distributed and Cloud Computing ,From Parallel Processing to The Internet of Things", 2012 Elsevier |
| 2 | Barrie Sosinsky, "Cloud Computing Bible", Wiley Publisher, 2011 |

| Cours Upon | Bloom's Taxonomy Level | |
|----------------------|--|------------|
| CO1 | Explain the main concepts and architecture of Parallel computing, Distributed Computing and Cloud Computing. | Understand |
| CO2 | Analyze the concept of Virtualization | Analyze |
| CO3 | Identify the approaches of SLA and programming model in Cloud | Apply |
| CO4 | Analyze the Cloud Platforms in Industry and Software Environments. | Analyze |
| CO5 | Identify the security issues in scientific and real time applications. | Apply |

B.E. - ELECTRONICS AND COMMUNICATION ENGINEERING - MINOR DEGREE

| 18ECM01 | | ELECTRON DEVICES | | | | | | | | | | |
|-----------|---|--|-----------------------|------------|---------|----------|-------|-----|--|--|--|--|
| PREREQ | UISITES | | CATEGORY | OE | Cre | Credit 3 | | | | | | |
| | | | Hours/Week | L | Т | P | Т | H | | | | |
| | 3 0 | | | | | | | | | | | |
| Course Ol | ojectives: | | 1 | I | -1 | | 1 | | | | | |
| 1. To int | roduce con | ponents such as diodes, BJTs and FETs, their charac | cteristics and applic | cations | | | | | | | | |
| 2. To une | 2. To understand, analyse and design of simple diode and transistor circuits. | | | | | | | | | | | |
| 3. To kno | ow the swit | ching characteristics of components and the conce | pt of rectifiers and | power suj | pplies | | | | | | | |
| Unit I | EXTRIN | SIC SEMICONDUCTOR AND PN JUCTIONS | | | 9 | 0 | 0 | 9 | | | | |
| | | ductor and their energy band structures- Law of electr | • | | | | | | | | | |
| | | n and hole densities in extrinsic semiconductors-Mo nation- Hall effect and its applications. Band structur | • | | | | | | | | | |
| | • • | f diode equation-temperature dependence of diode c | v | | - | | | | | | | |
| Unit II | SWITC | HING CHARACTERISTICS OF PN JUNTION A | AND SPECIAL D | IODES | 9 | 0 | 0 | 9 | | | | |
| | | tion and diffusion capacitance- varactor diode-ch | e | • | | | | • | | | | |
| | | e- mechanism of avalanche and Zener breakdown-ter eling effect in thin barriers - tunnel diode-photo diod | • • | | akdow | n vol | tag | es- | | | | |
| | | | | Jues. | | | | | | | | |
| Unit III | BIPOLA | R JUNCTION TRANSISTORS | | | 9 | 0 | 0 | 9 | | | | |
| | | and NPN transistors- BJT current components-emi | | | | | | | | | | |
| e | | lulation CB, CE and CC characteristics- breakdown o translator. | characteristics- ED | ers-Moll | model | - trai | 1515 | tor | | | | |
| Unit IV | FIELD I | EFFECT TRANSISTORS | | | 9 | 0 | 0 | 9 | | | | |
| | | racteristics of JFET-relation between pinch off volta letion types. CMOS circuits. MOS capacitance, BIC | - | | ion. M | OSF | ETS | S - | | | | |
| Unit V | RECTIFIERS AND POWER SUPPLIES | | | | | | | | | | | |
| | | and bridge rectifiers with resistive load. Analysis for | •• | 0 | | | | | | | | |
| | - | e multipliers Zener diode regulator. Electronically r temperature coefficient. | egulated d.c power | r supplies | . Line | regul | latio | on, | | | | |
| | | | | Total (4 | 15L)= 4 | 45 Po | erio | ds | | | | |
| | | | | | | | | | | | | |
| Text Book | s: | | | | | | | | | | | |

| 1. | JaconMillman& Christos C. Halkias, "Electronic Devices and Circuits" | Tata McGraw-Hill, 1991. |
|----|--|-------------------------|
| | | |

| Robert L. Boylestad and Louis Nashelsky, "Electronic Devices and Circuit Theory 8 th edition.", PHI, 2002 | | | | | | |
|--|--|--|--|--|--|--|
| erence Books: | | | | | | |
| Donald A. Neaman. "Semiconductor Physics and Devices" 3rd Ed., Tata McGraw-Hill 2002 | | | | | | |
| S. Salivahanan, N. Suresh kumar and A. Vallavaraj, Electronic Devices and Circuits, TMH, 1998. | | | | | | |
| Ben, G. Streetman and Sanjay Banerjee, Solid State Electronic Devices, Pearson Education 2000 | | | | | | |
| Floyd, "Electronic Devices", Sixth edition, Pearson Education, 2003. | | | | | | |
| eferences: | | | | | | |
| https://archive.nptel.ac.in/courses/108/108/108108122/ | | | | | | |
| https://www.youtube.com/watch?v=qqQ8wO-lNmI | | | | | | |
| https://slideplayer.com/slide/12438044/ | | | | | | |
| | | | | | | |

| Course | Course Outcomes: | | | | | |
|---|---|---------------|--|--|--|--|
| Upon completion of this course, the students will be able to: | | | | | | |
| CO1 | Interpret various applications of diode. | Applying | | | | |
| CO2 | Classify various configurations and biasing technique of BJT | Applying | | | | |
| CO3 | Apply the knowledge of using special devices for various applications | Understanding | | | | |
| CO4 | Discuss operation, biasing and applications of JFET. | Analysing | | | | |
| CO5 | Design power supplies and rectifiers | Applying | | | | |

| COURSE ARTICULATION MATRIX | | | | | | | | | | | | | | | |
|---|----|----|----|----|----|----|----|----|----|----|----|----|------|------|------|
| COs/POs | PO | РО | PO | РО | РО | РО | РО | РО | РО | PO | РО | PO | PSO1 | PSO2 | PSO3 |
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | | | |
| CO1 | 2 | 2 | 1 | - | - | - | I | I | I | - | - | - | 1 | - | - |
| CO2 | 2 | 2 | 1 | I | I | I | I | I | I | - | I | - | 2 | - | - |
| CO3 | 2 | 2 | 1 | - | - | - | - | - | - | - | - | - | 3 | - | - |
| CO4 | 2 | 2 | 1 | - | - | - | - | - | - | - | - | - | 2 | 2 | 1 |
| CO5 | 2 | 2 | 1 | - | - | - | - | - | - | - | - | - | 3 | 2 | 2 |
| Avg | 2 | 2 | 1 | - | - | - | - | - | - | - | - | - | 2.2 | 2 | 1.5 |
| 3/2/1 - indicates strength of correlation (3-High,2- Medium,1- Low) | | | | | | | | | | | | | | | |

| 18E0 | BECM02 DIGITAL ELECTRONICS | | | | | | | | | | |
|--|--|---|---------------------|------------|----------|----------|--------|--|--|--|--|
| PRE | REQU | JISITES | CATEGORY | OE | Crec | lit | 3 | | | | |
| | | | Hours/Week | L | Т | Р | ТН | | | | |
| | | | Hours/ Week | 3 | 0 | 0 | 3 | | | | |
| Cour | | | • | | | | | | | | |
| 1 | 1 To introduce basic postulates of boolean algebra and show the correlation between expressions | | | | | | | | | | |
| 2 | To In | troduce the methods for Simplifying Boolean expressions | | | | | | | | | |
| 3 | To O | utline the formal procedures for the analysis and design of co | ombinational circu | uits and s | equenti | ial circ | uits | | | | |
| 4 | To in | troduce the Concept of Memories and programmable logic d | evices | | | | | | | | |
| 5 | To ill | ustrate the concept of synchronous and Asynchronous seque | ntial circuits | | | | | | | | |
| Unit | I | NUMBER SYSTEMS AND LOGIC GATES | | | 9 | 0 0 | 9 | | | | |
| - Bo Simp | Number Systems - signed Binary numbers - Binary Arithmetic - Binary codes -conversion from one code to another - Boolean Algebra and Minimization Techniques - Canonical forms – Conversion between canonical forms – Simplifications of Boolean expressions using Karnaugh map - LOGIC GATES - Implementations of Logic Functions using gates. | | | | | | | | | | |
| Unit | Π | COMBINATIONAL CIRCUITS | | | 9 | 0 0 | 9 | | | | |
| | - | cedure – Adders/Subtractor – Serial adder/ Subtractor - Paralle xer - encoder / decoder – code converters. | el adder/ Subtracto | or-BCD a | adder- l | Multip | lexer/ | | | | |
| Unit | III | SEQUENTIAL CIRCUITS | | | 9 | 0 0 | 9 | | | | |
| and M | Mealy | cedure - Flip flops: SR, JK, T, D and JKMS – Triggering of – Counters: Asynchronous / Ripple counters – Synchronous Iniversal shift register. | | | | | | | | | |
| Unit | IV | ASYNCHRONOUS SEQUENTIAL CIRCUITS | | | 9 | 0 0 | 9 | | | | |
| Design of fundamental mode circuits – primitive state / flow table – Minimization of primitive state table –state assignment. Problems in Asynchronous Circuits: Cycles – Races – Hazards. Design of Hazard Free Circuits: Static, Dynamic Hazards elimination | | | | | | | | | | | |
| Unit V PLD AND MEMORY DEVICES | | | | | | | 9 | | | | |
| Classification of memories –RAM organization –ROM organization. Programmable Logic Devices: Programmable Logic Array (PLA) - Programmable Array Logic (PAL). Implementation of combinational logic using MUX, ROM, PAL and PLA. | | | | | | | | | | | |
| | | | | Total (| 45 L) = | = 45 Pe | eriods | | | | |
| | | | | | | | | | | | |
| Tex | t Bool | xs: | | | | | | | | | |
| 1 | | M. Morris Mano, Digital Design, 4.ed., Pearson Education (| Singapore) Pvt. L | td., New | Delhi, | 2008 | | | | | |

| 2 | R.P.Jain, Modern Digital Electronics, 4 th edition, TMH, 2010. | | | | | | |
|------------------|---|--|--|--|--|--|--|
| Reference Books: | | | | | | | |
| 1 | S. Salivahanan and S. Arivazhagan, Digital Circuits and Design, 2 nd ed., Vikas Publishing House Pvt. Ltd, New Delhi, 2004 | | | | | | |
| 2 | Charles H.Roth. "Fundamentals of Logic Design", Thomson Publication Company, 2003. | | | | | | |
| 3 | Donald P.Leach and Albert Paul Malvino, Digital Principles and Applications, 5 ed., Tata McGraw Hill Publishing Company Limited, New Delhi, 2003. | | | | | | |
| 4 | John F.Wakerly, Digital Design: Principles and practices, PHI, 2006 | | | | | | |
| E-Refe | E-Reference: | | | | | | |
| 1 | http://nptel.ac.in/noc/individual_course.php?id=noc15-ec01 | | | | | | |

| 2 | https://nptel.ac.in/courses/117105080/6 |
|---|--|
| 3 | https://nptel.ac.in/courses/117105080/12 |

| Course Outcomes: Upon completion of this course, the students will be able to: | | | | | | | |
|---|---|---------------|--|--|--|--|--|
| CO1 | Minimize Boolean expressions and implement using logic gates | Applying | | | | | |
| CO2 | Design and analyse combinational logic circuits. | Analysing | | | | | |
| CO3 | Design and analyse synchronous and asynchronous sequential logic circuits | Analysing | | | | | |
| CO4 | Understand the concepts of memories and PLDs | Understanding | | | | | |
| CO5 | Implement circuits using memory and PLDs. | Applying | | | | | |

| | COURSE ARTICULATION MATRIX | | | | | | | | | | | | | | |
|---------|---|-----|-----|-----|-----|----|-----|-----|----|----|----|----|-----|-----|-----|
| COs/POs | PO | PO | PO | PO4 | РО | PO | PO | PO | PO | РО | PO | РО | PSO | PSO | PSO |
| | 1 | 2 | 3 | | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 1 | 2 | 3 |
| CO1 | 3 | 2 | 2 | 2 | 3 | 2 | 3 | 2 | - | - | - | - | 2 | 1 | - |
| CO2 | 3 | 3 | 2 | 2 | 3 | 3 | 2 | 1 | 1 | - | - | - | 3 | 2 | - |
| CO3 | 2 | 2 | 3 | 3 | 2 | 1 | 2 | 1 | 1 | - | - | - | 2 | 2 | - |
| CO4 | 2 | 1 | 2 | 1 | 2 | 2 | 3 | 1 | - | - | - | - | 2 | 1 | - |
| CO5 | 2 | 1 | 2 | 1 | 3 | 2 | 1 | 2 | - | - | - | I | 3 | 2 | - |
| Avg | 2.4 | 1.8 | 2.2 | 1.8 | 2.6 | 2 | 2.2 | 1.4 | 1 | - | - | I | 2.4 | 1.6 | - |
| | 3/2/1 - indicates strength of correlation (3-High,2- Medium,1- Low) | | | | | | | | | | | | | | |

| 18EC | M03 | ELECTRONIC CIRCUITS | | | | | | |
|---|---|--|--|--|--|--|--|--|
| PREF | REQU | ISITES | CATEGORY | OE | | Crec | lit | 3 |
| Floot | ron De | viene | Hours/Week | L | | Т | Р | ТН |
| Elecu | ron De | vices | nours/ week | 3 | | 0 | 0 | 3 |
| Cours | se Obj | ectives | I | | | | | |
| 1 | To pe | erform analysis on Small signal amplifiers and large sign | nal amplifiers. | | | | | |
| 2 | To gi | ve a comprehensive exposure to all types of discrete am | plifiers and oscillators | 5. | | | | |
| 3 | To ur | nderstand the various linear and non-linear applications | of op-amp | | | | | |
| Uni | it I | MIDBAND ANALYSIS OF SMALL SIGNAL AN | IPLIFIERS | | 9 | 0 | 0 | 9 |
| bias c Mid-b Miller imped emitte | ircuit a band ar r's the lance u er coup | for biasing - Fixed bias circuit - Load line and quiescent as a constant current circuit. CE, CB and CC amplifiers halysis of various types of single stage amplifiers to of orem. Darlington connection using similar and Comp using Darlington connection and bootstrapping. CS, CG and the differential amplifier circuit. Differential gain - CMF | s. Method of drawing btain gain - input imp plementary transistors and CD (FET) amplifie | small-s edance Meth ers. Mu | ignal and ods c ltistag | equi outpo of inc ge am | valer ut im reasi plific | nt circuit. pedance. ng input ers-Basic |
| Uni | t II | LARGE SIGNAL AMPLIFIERS | | | 9 | 0 | 0 | 9 |
| circuit Calcuit their r and trapower | t of FE lation or relation ansform routpu | acy & High frequency analysis of amplifiers -Hybrid – pi ETs. Gain-bandwidth product of FETs. General express of overall upper and lower cut off frequencies of multist a to cut off frequencies. Classification of amplifiers (Class mer-coupled power amplifiers. Class B complementary- it, efficiency and power dissipation. Crossover distortion ing capacity of transistors with and without heat sink. H | sion for frequency resp tage amplifiers. Ampl ss A, B, AB, C&D), Ef symmetry, push-pull p n and methods of elim | ponse o ifier ris ficiency ower a | of mu se tim y of cl mplif | ltista e and lass A iers. (| ge ar l sag A, RC Calcu | nplifiers. time and coupled lation of |
| power | manui | ing capacity of transistors with and without heat sink. If | | | | | | |
| Unit | t III | OSCILLATORS | | | 9 | 0 | 0 | 9 |
| Feed stabi Osci | lback A lization llator - | | usen Criterion - Mecha e connection of RC at lysis of LC Oscillator | nd LC s: Colp | or star filter | rt of c s - R Hart | oscill C ph | ation and ase shift |
| Feed stabi Osci | back A lization llator - er and | OSCILLATORS Amplifier: Block diagram - Gain with feedback - Barkhau n of amplitude - Analysis of Oscillator using Cascade Wien bridge Oscillator and Twin-T Oscillators - Ana | usen Criterion - Mecha e connection of RC as lysis of LC Oscillator Electrical equivalent of | nd LC s: Colp | or star filter | rt of c s - R Hart | oscill C ph | ation and ase shift - Clapp - |
| Feed stabi Osci Mille Unit Analy of Cla Bistab | lback A lization llator - er and t t IV vsis of s uss C tu ble Mu | OSCILLATORS Amplifier: Block diagram - Gain with feedback - Barkhau n of amplitude - Analysis of Oscillator using Cascade - Wien bridge Oscillator and Twin-T Oscillators - Ana Pierce oscillators - Frequency range of RC Oscillators - | usen Criterion - Mecha e connection of RC at lysis of LC Oscillator Electrical equivalent of S C tuned amplifiers and Astable Multi vibrator | nd LC s: Colp circuit of d their a – Mon | or star filter itts – of Cry 9 applic o stat | t of c s - R Hart ystal. 0 cation | bscill C ph tley - 0 ns - E | ation and ase shift - Clapp - 9 fficiency <i>i</i> brator – |
| Feed stabi Osci Mille Unit Analy of Cla | lback A lization llator - er and t t IV sis of s uss C tu ble Mu g. | OSCILLATORS Amplifier: Block diagram - Gain with feedback - Barkhau n of amplitude - Analysis of Oscillator using Cascade Wien bridge Oscillator and Twin-T Oscillators - Ana Pierce oscillators - Frequency range of RC Oscillators - TUNED AMPLIFIERS AND MULTIVIBRATOR single tuned and synchronously tuned amplifiers - Class uned Amplifier- Collector coupled and Emitter coupled | usen Criterion - Mecha e connection of RC at lysis of LC Oscillator Electrical equivalent of RS C tuned amplifiers and Astable Multi vibrator Astable Blocking Osci | nd LC s: Colp circuit of d their a – Mon | or star filter itts – of Cry 9 applic o stat | t of c s - R Hart ystal. 0 cation | bscill C ph tley - 0 ns - E | ation and ase shift - Clapp - 9 fficiency <i>i</i> brator – |
| Feed stabi Osci Mille Unit Analy of Cla Bistab timing Uni Basic desigr Differ | lback A lization llator - er and t t IV rsis of s uss C tu ble Mu g. t V structu n - DC rentiato | OSCILLATORS Amplifier: Block diagram - Gain with feedback - Barkhau n of amplitude - Analysis of Oscillator using Cascade - Wien bridge Oscillator and Twin-T Oscillators - Ana Pierce oscillators - Frequency range of RC Oscillators - TUNED AMPLIFIERS AND MULTIVIBRATOR single tuned and synchronously tuned amplifiers - Class uned Amplifier- Collector coupled and Emitter coupled a lti vibrator - Triggering methods – Mono stable and A | usen Criterion - Mecha e connection of RC at lysis of LC Oscillator Electrical equivalent of RS C tuned amplifiers and Astable Multi vibrator Astable Blocking Osci ICATIONS ntial gain - Common I verting and non-invert rigger and its applicati | nd LC s: Colp circuit of d their - Mon illators Mode g ing am ons - A prator. | or star filter: itts – of Cry 9 applic o star using 9 ain, 0 plifie Active | t of c s - R Hart ystal. 0 catior ble M g Em 0 CMR ers - l e filte | oscilla C ph tley - 0 as - E ulti v itter 0 R - 0 Integ | ation and ase shift - Clapp - 9 fficiency vibrator – and base 9 OP-AMP rator and |
| Feed stabi Osci Mille Unit Analy of Cla Bistab timing Uni Basic desigr Differ high p | lback A lization llator - er and t t IV sis of s ass C tu ble Mu g. t V structu n - DC rentiato bass, ba | OSCILLATORS Amplifier: Block diagram - Gain with feedback - Barkhau n of amplitude - Analysis of Oscillator using Cascade Wien bridge Oscillator and Twin-T Oscillators - Ana Pierce oscillators - Frequency range of RC Oscillators - TUNED AMPLIFIERS AND MULTIVIBRATOR single tuned and synchronously tuned amplifiers - Class aned Amplifier- Collector coupled and Emitter coupled a lti vibrator - Triggering methods – Mono stable and A OPERATIONAL AMPLIFIERS AND ITS APPLI are and principle of operation - Calculation of different and AC characteristics of OP-AMP. Applications: Invo or - Summing amplifier - Precision rectifier - Schmitt tr and pass and band stop filters - Sine wave oscillators - Calculation - Calcula | usen Criterion - Mecha e connection of RC at lysis of LC Oscillator Electrical equivalent of RS C tuned amplifiers and Astable Multi vibrator Astable Blocking Osci ICATIONS ntial gain - Common I verting and non-invert rigger and its applicati | nd LC s: Colp circuit of d their - Mon illators Mode g ing am ons - A prator. | or star filter: itts – of Cry 9 applic o star using 9 ain, 0 plifie Active | t of c s - R Hart ystal. 0 catior ble M g Em 0 CMR ers - l e filte | oscilla C ph tley - 0 as - E ulti v itter 0 R - 0 Integ | ation and ase shift - Clapp - 9 fficiency ribrator – and base 9 OP-AMP rator and ow pass, |
| Feed stabi Osci Mille Unit Analy of Cla Bistab timing Uni Basic desigr Differ high p | lback A lization llator - er and i t IV siss C tu ble Mu g. t V structu n - DC rentiato bass, ba | OSCILLATORS Amplifier: Block diagram - Gain with feedback - Barkhau n of amplitude - Analysis of Oscillator using Cascade Wien bridge Oscillator and Twin-T Oscillators - Ana Pierce oscillators - Frequency range of RC Oscillators - TUNED AMPLIFIERS AND MULTIVIBRATOR single tuned and synchronously tuned amplifiers - Class uned Amplifier- Collector coupled and Emitter coupled A lti vibrator - Triggering methods – Mono stable and A OPERATIONAL AMPLIFIERS AND ITS APPLI ure and principle of operation - Calculation of different and AC characteristics of OP-AMP. Applications: Invor - Summing amplifier - Precision rectifier - Schmitt tr and pass and band stop filters - Sine wave oscillators – C ooks: | usen Criterion - Mecha e connection of RC an lysis of LC Oscillator Electrical equivalent of RS C tuned amplifiers and Astable Multi vibrator Astable Blocking Osci ICATIONS ntial gain - Common I verting and non-invert rigger and its applicati Comparator – Multi vil | nd LC s: Colp circuit of d their i – Mon illators Mode g ing am ions - A prator. To | or star filter: itts – of Cry 9 applic o stat using 9 gain, 0 plifie Active tal (4 | t of c s - R Hart ystal. 0 catior ole M g Em 0 CMR ers - 1 e filte 5 L) | oscilla C ph deley - 0 as - E ulti v itter 0 R - 0 Integ ers: L = 45 | ation and ase shift - Clapp - 9 fficiency vibrator – and base 9 OP-AMP rator and ow pass, 5 Periods |
| Feed stabi Osci Mille Unit Analy of Cla Bistab timing Uni Basic desigr Differ high p | lback A lization llator - er and i t IV sis of s uss C tu ble Mu g. t V structu n - DC rentiato bass, ba | OSCILLATORS Amplifier: Block diagram - Gain with feedback - Barkhau n of amplitude - Analysis of Oscillator using Cascade Wien bridge Oscillator and Twin-T Oscillators - Ana Pierce oscillators - Frequency range of RC Oscillators - TUNED AMPLIFIERS AND MULTIVIBRATOR single tuned and synchronously tuned amplifiers - Class uned Amplifier- Collector coupled and Emitter coupled a lti vibrator - Triggering methods – Mono stable and A OPERATIONAL AMPLIFIERS AND ITS APPLI ure and principle of operation - Calculation of different and AC characteristics of OP-AMP. Applications: Invor - Summing amplifier - Precision rectifier - Schmitt tr and pass and band stop filters - Sine wave oscillators – G ooks: B.Visvesvara Rao, K.Raja Rajeswari, P.Chalam Raju Circuits-II', Pearson Education,2012 | usen Criterion - Mecha e connection of RC at lysis of LC Oscillator Electrical equivalent of RS C tuned amplifiers and Astable Multi vibrator Astable Blocking Osci ICATIONS ntial gain - Common I verting and non-invert rigger and its applicati Comparator – Multi vil | nd LC s: Colp circuit of d their - Mon illators Mode g ing am ons - Drator. To Rama | or star filter: itts – of Cry 9 applic o star using 9 gain, 0 plifie Active tal (4 | t of c s - R Hart ystal. 0 catior ble M g Em 0 CMR ers - 1 e filte 5 L) | oscilla C philey - itley - 0 as - E ulti v itter 0 Integ ers: L = 45 | ation and ase shift - Clapp - 9 fficiency vibrator – and base 9 OP-AMP rator and ow pass, 5 Periods |
| Feed stabi Osci Mille Unit Analy of Cla Bistab timing Uni Basic desigr Differ high p | lback A lization llator - er and t t V sis of s ass C tu ble Mu g. t V structu n - DC rentiato bass, ba | OSCILLATORS Amplifier: Block diagram - Gain with feedback - Barkhau n of amplitude - Analysis of Oscillator using Cascade Wien bridge Oscillator and Twin-T Oscillators - Ana Pierce oscillators - Frequency range of RC Oscillators - TUNED AMPLIFIERS AND MULTIVIBRATOR single tuned and synchronously tuned amplifiers - Class med Amplifier- Collector coupled and Emitter coupled a liti vibrator - Triggering methods – Mono stable and A OPERATIONAL AMPLIFIERS AND ITS APPLI ure and principle of operation - Calculation of different and pass and band stop filters - Sine wave oscillators - Constitute moks: B.Visvesvara Rao, K.Raja Rajeswari, P.Chalam Raju Circuits-II", Pearson Education,2012 D.Roy Choudhry, Shail Jain, "Linear Integrated Circuits | usen Criterion - Mecha e connection of RC at lysis of LC Oscillator Electrical equivalent of RS C tuned amplifiers and Astable Multi vibrator Astable Blocking Osci ICATIONS ntial gain - Common I verting and non-invert rigger and its applicati Comparator – Multi vil | nd LC s: Colp circuit of d their - Mon illators Mode g ing am ons - Drator. To Rama | or star filter: itts – of Cry 9 applic o star using 9 gain, 0 plifie Active tal (4 | t of c s - R Hart ystal. 0 catior ble M g Em 0 CMR ers - 1 e filte 5 L) | oscilla C philey - itley - 0 as - E ulti v itter 0 Integ ers: L = 45 | ation and ase shift - Clapp - 9 fficiency vibrator – and base 9 OP-AMP rator and ow pass, 5 Periods |
| Feed stabi Osci Mille Unit Analy of Cla Bistab timing Uni Basic desigr Differ high p | lback A lization llator - er and t t IV sis of s ass C two ble Mu g. t V structur n - DC rentiato bass, ba | OSCILLATORS Amplifier: Block diagram - Gain with feedback - Barkhau n of amplitude - Analysis of Oscillator using Cascade Wien bridge Oscillator and Twin-T Oscillators - Ana Pierce oscillators - Frequency range of RC Oscillators - TUNED AMPLIFIERS AND MULTIVIBRATOR single tuned and synchronously tuned amplifiers - Class uned Amplifier- Collector coupled and Emitter coupled a lti vibrator - Triggering methods – Mono stable and A OPERATIONAL AMPLIFIERS AND ITS APPLI ure and principle of operation - Calculation of different and AC characteristics of OP-AMP. Applications: Invor - Summing amplifier - Precision rectifier - Schmitt tr and pass and band stop filters - Sine wave oscillators – G ooks: B.Visvesvara Rao, K.Raja Rajeswari, P.Chalam Raju Circuits-II', Pearson Education,2012 | usen Criterion - Mecha e connection of RC an lysis of LC Oscillator Electrical equivalent of RS C tuned amplifiers and Astable Multi vibrator Astable Blocking Osci ICATIONS ntial gain - Common I verting and non-invert rigger and its applicati Comparator – Multi vil Pantulu, K.Bhaskara s", New Age Internatio | nd LC s: Colp circuit of d their - - Mon illators Mode g ing am ions - A <u>orator.</u> To Rama | or star filter: itts – of Cry 9 applic o star using 9 gain, 0 plifie Active tal (4 | t of c s - R Hart ystal. 0 catior ble M g Em 0 CMR ers - 1 e filte 5 L) hy, " | $\frac{0}{0}$ $\frac{0}{0}$ $\frac{0}{0}$ $\mathbf{R} - 0$ $\mathbf{R} - 0$ $\mathbf{R} - 1$ 0 $\mathbf{R} - 1$ | ation and ase shift - Clapp - 9 fficiency ribrator – and base 9 OP-AMP rator and ow pass, 5 Periods |

1 Millma , 2011.

| 2 | Sedera& Smith, "Micro Electronic Circuits", 4 th Edition, Oxford University Press, Chennai. |
|------|---|
| 3 | Michael Jacob, 'Applications and Design with Analog Integrated Circuits', Prentice Hall of India, 1996. |
| 4 | K.R.Botkar, 'Integrated Circuits', 10th edition, Khanna Publishers, 2010. |
| e-Re | ference: |
| 1 | http://nptel.ac.in/courses/117105080/40 |
| 2 | http://nptel.ac.in/courses/117108038/1 |
| 3 | https://freevideolectures.com/course/2915/linear-integrated-circuits |

| | se Outcomes: completion of this course, the students will be able to: | Bloom's Taxonomy Mapped |
|-----|--|----------------------------|
| CO1 | To analyze small signal amplifiers and Large signal Amplifiers. | Applying |
| CO2 | Analyze the frequency response characteristics of amplifiers | Applying |
| CO3 | Develop insight of on oscillator design. | Applying |
| CO4 | Construct and analyse tuned amplifiers and multivibrators. | Applying |
| CO5 | Develop competence in linear and nonlinear Op amp circuit analysis. | Applying |

| | COURSE ARTICULATION MATRIX | | | | | | | | | | | | | | |
|--------|----------------------------|----|--------|--------|---------|-------|--------|---------|--------|-----------|----------------|--------|-----|-----|-----|
| COs/PO | PO | PO | PO | PO | PO | PO | PO | PO | PO | PO | PO | PO | PSO | PSO | PSO |
| S | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 1 | 2 | 3 |
| CO1 | 2 | 2 | 1 | 2 | - | - | - | - | 1 | - | - | - | 1 | 2 | 1 |
| CO2 | 3 | 2 | 1 | 2 | - | - | - | - | - | - | - | - | 1 | 2 | 1 |
| CO3 | 3 | 2 | 1 | 2 | - | - | - | - | - | - | - | - | 1 | 2 | 1 |
| CO4 | 3 | 2 | 1 | 2 | - | - | - | - | - | - | - | - | 1 | 2 | 1 |
| CO5 | 1 | 2 | 1 | 2 | - | - | - | - | - | - | - | - | 1 | 2 | 1 |
| Avg | 2.4 | 2 | 1 | 2 | - | - | - | - | - | - | - | - | 1 | 2 | 1 |
| | | 3/ | /2/1 - | indica | tes str | ength | of cor | relatio | n (3-H | ligh,2- N | <i>l</i> edium | ,1- Lo | w) | | |

| DEDEC | | | | | | | |
|------------------|-----------|--|-------------------------|------------|----------------|--------|------|
| . NEKE(| QUISI | ΓΕS | CATEGORY | OE | Cre | dit | 3 |
| | | | Hours/Week | L | Т | P | T |
| | | | | 3 | 0 | 0 | |
| Course C | bjecti | ves: | | | 1 | | |
| I. To u | ndersta | nd and perform Fourier and Laplace analysis on signal | s and systems respec | ctively. | | | |
| 2. To ar | alyse | the Discrete Fourier Transform, Fast Fourier Transform | n algorithms. | | | | |
| 3. To de | esign a | nd realize IIR, FIR filters. | | | | | |
| Unit I | INT | TRODUCTION TO SIGNALS AND SYSTEMS | | | 9 | 0 | 0 |
| | | f Signals: Even and Odd Signal - Energy and power sig | • | | | | |
| - | | Continuous and Discrete amplitude signal System pusality – Stability - Realizability Linear Time-Invar | | | | | |
| | | volution – Correlation - System representation through | | - | - | | |
| U nit II | AN | ALYSIS OF SIGNAL AND SYSTEMS | | | 9 | 0 | 0 |
| | | | | | | | |
| | | Fourier Transform, Fourier Series, Relating the Laplac | te Transform to Four | rier Tran | sform, 1 | Freq | uen |
| esponse | of con | tinuous time systems. Introduction to z- Transform. | | | | | |
| U nit III | DIS | CRETE FOURIER TRANSFORM | | | 9 | 0 | 0 |
| ntroduct | on to | DFT - Properties of DFT - Circular convolution - | FFT algorithms – F | Radix-2 I | FFT alg | orith | nms |
| | | Time and Decimation in Frequency algorithms. | | | | ,01101 | |
| T | INIT | ENTRE IMPLITOE DEGRANGE EN TER DEGLAN | | | | | 0 |
| U nit IV | INF | FINITE IMPULSE RESPONSE FILTER DESIGN | | | 9 | 0 | 0 |
| Character | istics of | of Analog Butterworth filter - Chebyshev filter - Low p | bass filter, High pass | filter, Ba | and pass | s filt | er a |
| 3and stop | o filter | - Transformation of analog filters in to equivalent digi | tal filters using bilin | ear trans | formati | on m | leth |
| Realizat | ion str | ucture for IIR filters-Direct form - Cascade form - Para | allel form. | | | | |
| U nit V | FIN | IITE IMPULSE RESPONSE FILTER DESIGN | | | 9 | 0 | 0 |
| Blackmar | nn Win | esponse of FIR filter - FIR design using window m dows - Park-McClellan's method - Realization structur cture - Comparison of FIR and IIR filters. | • | | • | | - |
| | | | | Total (4 | 45L)= 4 | 5 Pe | erio |
| | | | | | | | |

| Text | Books: |
|------|---|
| 1. | A.Anand Kumar, "Signals and Systems", 3rd Edition, PHI, 2013. |
| 2. | John G Proakis and Manolakis, "Digital Signal Processing Principles, Algorithms and Applications", 4th Edition, Pearson Education, 2009. |

| Refe | erence Books: |
|------|---|
| 1. | Alan V Oppenheim, Alan S Willsky and S Hamid Nawab, "Signals and Systems", 2nd edition, PHI Learning Private Limited, New Delhi, 2010. |
| 2. | B.P. Lathi, "Principles of Signal Processing and Linear Systems", Oxford University Press, 2009. |
| 3. | Emmanuel C. Ifeacher, Barry W. Jervis, "Digital Signal Processing: A Practical Approach", 2nd Edition, Pearson Education, 2004. |
| 4. | S.K. Mitra, "Digital Signal Processing, A Computer Based approach", 4th Edition, McGraw-Hill, 2010. |
| E-R | eferences: |
| 1. | http://nptel.ac.in/courses/117104074/ |
| 2. | https://www.coursera.org/learn/dsp |
| 3. | https://ocw.mit.edu/resources/res-6-008-digital-signal-processing-spring-2011/ |

| Course | e Outcomes: | Bloom's | | | |
|--------|--|-----------|--|--|--|
| Upon | Upon completion of this course, the students will be able to: | | | | |
| | | Mapped | | | |
| CO1 | Analyse and understands different types of signals. | Analysing | | | |
| CO2 | Represent continuous signals and systems in time and frequency domain using different transforms. | Analysing | | | |
| CO3 | Analyse the need for Discrete Fourier Transform, Fast Fourier Transform algorithms in digital signals & systems. | Analysing | | | |
| CO4 | Design and realize IIR filters. | Applying | | | |
| CO5 | Design and realize FIR filters. | Applying | | | |

| COURSE ARTICULATION MATRIX | | | | | | | | | | | | | | | |
|----------------------------|-----|-----|---------|--------|----------|--------|--------|---------|---------|-----------|--------|---------|------|------|------|
| COs/POs | PO | PO | PO | РО | PO | РО | РО | РО | PO | PO | PO | PO | PSO1 | PSO2 | PSO3 |
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | | | |
| CO1 | 3 | 2 | 3 | 3 | 3 | - | - | - | - | - | - | - | 2 | 2 | 2 |
| CO2 | 3 | 2 | 2 | 3 | 3 | 2 | - | - | - | - | - | - | 2 | 2 | 2 |
| CO3 | 3 | 2 | 2 | 2 | 1 | - | 1 | I | I | - | - | - | 1 | 1 | 1 |
| CO4 | 3 | 2 | 2 | 2 | 1 | - | 1 | I | I | - | - | - | 1 | 1 | 1 |
| CO5 | 1 | 1 | 1 | 1 | 1 | I | - | - | - | - | - | - | 2 | 2 | 1 |
| Avg | 2.6 | 1.8 | 2 | 2.2 | 1.8 | 2 | 1 | | | | | | 1.6 | 1.6 | 1.4 |
| | | | 3/2/1 - | indica | ates str | rength | of con | relatio | on (3-F | ligh,2- N | Mediun | n,1- Lo | ow) | | |

| 18ECM05 | MICROPROCESSORS AND MICRO | CONTROLLERS | | | | |
|------------------------------|--|------------------------------|------------|---------|----------|---------|
| PREREQUI | ISITES | CATEGORY | OE | Cre | dit | 3 |
| | | Hours/Week | L | Т | Р | ТН |
| | | Hours/ week | rs/Week 3 | | | |
| Course Obje | ectives: | | | | 1 1 | |
| 1. T | o familiarise with 8086 and 8051 architectures. | | | | | |
| 2. T | o interface 8086 microprocessor and 8051 microcor | ntrollers with peripherals b | y program | ming. | | |
| 3. T | o gain basic knowledge of PIC microcontrollers. | | | | | |
| | | | | | | |
| | 086 MICROPROCESSOR ARCHITECTURE | | | 9 | 0 | 9 |
| | Microcomputer systems-8086 Architecture – Pin As | • | itecture – | Addres | sing r | nodes |
| | formats- Directives and Operators-Assembly process | | | | <u> </u> | |
| | PROGRAMMING AND INTERFACING OF 808 | | | 9 | 0 | 9 |
| 8251 USART | Г. 051 ARCHITECTURE | | | 9 | 0 | 9 |
| 8051 architec — Addressin | cture - Registers in 8051 - Pin description - 8051 pa | arallel I/O ports - memory | organizati | on - In | struct | ion se |
| Unit IV P | ROGRAMMING AND INTERFACING OF 805 | 1 | | 9 | 0 | 9 |
| - | nguage programming.8051Timers - Serial Port Progr ADC, DAC and Sensor Interfacing - Motor Control | | amming - I | LCD ar | nd Ke | yboard |
| | TC MICROCONTROLLERS | | | | | |
| Unit V P | IC MICROCONTROLLERS | | | 9 | 0 | 9 |
| | teristics of PIC microcontrollers – PIC microcontrol struction set and timers in PIC | oller families-Memory-Pro | ogram Mei | nory – | RAN | /I Data |
| - | | | Total | (L+T) : | = 45 p | period |
| | | | | . , | 1 | |
| | | | | | | |

| Text B | ooks: | | | | | | | | |
|--|--|--|--|--|--|--|--|--|--|
| 1. | Yu-Cheng Liu, Glenn A. Gibson," Microcomputer Systems, The 8086/8088 Family", Pearson, 2e, 2019. | | | | | | | | |
| 2. | Muhammad Ali Mazidi, Janice GillispieMazidi, RolinD.McKinlay, "The 8051 Microcontroller and Embedded | | | | | | | | |
| ۷. | Systems using Assembly and C", 2e, 2022. | | | | | | | | |
| Referen | nce Books: | | | | | | | | |
| 1 | Mohamed Ali Mazidi, Janice GillispieMazidi, RolinMcKinlay, "The 8051 Microcontroller and Embedded | | | | | | | | |
| 1. Systems: Using Assembly and C", 2nd Edition, Pearson education, 2011. | | | | | | | | | |
| 2. | Martin Bates,"PIC Microcontrollers-An Introduction to Microelectronics", 3e, Elsevier, 2011. | | | | | | | | |
| 3. | Mathur Sunil,"Microprocessor 8086: Architecture, Programming and Interfacing" PHI Learning Pvt. Ltd. 2011. | | | | | | | | |
| 4. | Salvador PinillosGimenez," 8051 Microcontrollers Fundamental Concepts, Hardware, Software and | | | | | | | | |
| 4. | Applications in Electronics", Springer 2019. | | | | | | | | |
| E-Refe | erences: | | | | | | | | |
| 1. | Ashraf Almadhoun,"A Detailed Look Into PIC Microcontroller and Its Architecture", Amazon 2020. | | | | | | | | |
| 2. | https://nptel.ac.in/courses/108105102 | | | | | | | | |
| 3. | http://www.satishkashyap.com/2012/02/video-lectures-on-microprocessors-and.html | | | | | | | | |
| | | | | | | | | | |

| Cour | rse Outcomes: | Bloom's Taxonomy |
|------------|--|------------------|
| Upor | n completion of this course, the students will be able to: | Mapped |
| CO1 | Describe and analyse the architecture of 8086 microprocessor and 8051 architectures. | Remembering |
| CO2 | Develop assembly language programs and Interface peripherals with 8086. | Applying |
| CO3 | Develop assembly language programs and Interface peripherals with 8051. | Applying |
| CO4 | Determine application specific circuit for real-time applications. | Understanding |
| CO5 | Associate appropriate PIC microcontroller for a given application. | Understanding |

| | COURSE ARTICULATION MATRIX | | | | | | | | | | | | | | |
|---------|----------------------------|----|----|----|----|----|----|----|----|----|----|----|-----|-----|------|
| COs/POs | PO | PO | PO | PO | PO | PO | PO | PO | PO | PO | PO | PO | PSO | PSO | PSO3 |
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 1 | 2 | |
| CO1 | 2 | 2 | - | - | - | - | - | - | - | - | 2 | - | 1 | - | - |
| CO2 | 2 | 2 | 2 | 2 | - | - | - | - | - | - | - | - | 2 | 2 | - |
| CO3 | 2 | 2 | 2 | 2 | - | - | - | - | - | - | - | - | 2 | 2 | - |
| CO4 | 2 | 2 | 2 | 2 | - | - | - | - | - | - | - | - | 2 | 2 | 2 |
| CO5 | 2 | 2 | - | 2 | - | - | - | - | - | - | - | - | 2 | 2 | - |
| Avg | 2 | 2 | 2 | 2 | - | - | - | - | - | - | 2 | - | 1.8 | 2 | 2 |

| 18ECN | A06 | ANALOG AND DIGITAL COMMUNICA | TION | | | | | | | | |
|--------------------|---|--|-------------------|------------|---------|--------|---------|--|--|--|--|
| PRER | EQUISITE | S | CATEGORY | OE | Credit | | 3 | | | | |
| | | | Hours/Week | L | Т | Р | TH | | | | |
| | | | | 3 | 0 | 0 | 3 | | | | |
| Course Objectives: | | | | | | | | | | | |
| 1. | Understan | analog and digital communication techniques. | | | | | | | | | |
| 2. | Learn data | and pulse communication techniques. | | | | | | | | | |
| 3. | Be familia | ized with source and Error control coding. | | | | | | | | | |
| Unit I | | DRMATION THEORY | | | | 9 0 | | | | | |
| | • | nation and entropy - Source coding theorem - Shanno | Ū. | Huffman | coding | s - Di | iscrete | | | | |
| | • | els – Mutual information – Channel capacity – Channel | coding theorem. | | | | | | | | |
| Unit I | - | ALOG COMMUNICATION | | | - | 9 0 | | | | | |
| | | oise – External Noise- Internal Noise- Noise Calculation | | | | • | | | | | |
| | • 1 | es - Need for Modulation. Theory of Amplitude Mod | | | | | | | | | |
| | • | ory of Frequency and Phase Modulation - Comparisor | n of various Anal | og Comm | unicat | ion S | ystem | | | | |
| (AM – | FM – PM). | | | | | | | | | | |
| Unit I | | GITAL COMMUNICATION | | | 9 | | 09 | | | | |
| - | | eying (ASK) – Frequency Shift Keying (FSK) Minimu | | , | | | | | | | |
| | | QPSK – 8 PSK – 16 PSK – Quadrature Amplitude M | | | | - | AM – | | | | |
| Bandw | idth Efficie | ncy- Comparison of various Digital Communication Sy | vstem (ASK – FSI | K – PSK – | QAM |). | | | | | |
| Unit I | | LSE COMMUNICATION AND MULTIPLE ACC | | | 1 | | 09 | | | | |
| Pulse C | Communicat | ion: Pulse Amplitude Modulation (PAM) – Pulse Time | Modulation (PTN | M) – Pulse | code | Modu | ilation | | | | |
| (PCM) | (PCM) - Comparison of various Pulse Communication System (PAM - PTM - PCM). Multiple access techniques: | | | | | | | | | | |
| - | FDMA, CDMA, TDMA, SDMA. | | | | | | | | | | |
| Unit V | | ROR CONTROL CODING | | | 1 | _ | 09 | | | | |
| Linear | block code | s - Cyclic codes - Convolution codes - Maximum lik | kelihood decodin | g of conv | olution | nal co | odes – | | | | |
| Sequer | ntial decodir | g of convolutional codes – Trellis codes – Applications | S. | | | | | | | | |
| | | | | Total (| 45L)= | 45 P | eriods | | | | |

| Text | Books: |
|-------|---|
| 1. | Simon Haykin, "Communication Systems", 4th Edition, John Wiley & Sons, 2014. |
| 2. | J.G.Proakis, M.Salehi, -Fundamentals of Communication Systems, Pearson Education 2014. |
| Refer | rence Books: |
| 1. | B.P.Lathi, —Modern Digital and Analog Communication Systems ^{II} , 4th Edition, Oxford University Press, 2013. |
| 2. | D.Roody, J.Coolen, —Electronic Communications, 4th edition PHI 2015. |
| 3. | B.Sklar, —Digital Communications Fundamentals and Applications, 5th Edition Pearson Education 2017 |
| 4. | H P Hsu, Schaum Outline Series - —Analog and Digital Communications TMH, 5th edition 2006 |
| E-Re | ferences: |
| 1. | https://onlinecourses.nptel.ac.in/noc21_ee74/preview |
| 2. | https://nptel.ac.in/courses/117101051 |
| 3. | https://www.digimat.in/nptel/courses/video/117105143/L51.html |
| | |

| | | Dutcomes: mpletion of this course, the students will be able to: | Bloom's Taxonomy Mapped |
|----|---|---|----------------------------|
| CO | : | Apply the concepts of Random Process to the design of Communication | Applying |
| CO | : | Apply analog and digital communication techniques. | Applying |
| CO | : | Understand the use of data and pulse communication techniques. | Understanding |
| CO | : | Analyze Source and Error control coding. | Analysing |
| CO | : | Design AM communication systems and Angle modulated communication | Applying |

| | COURSE ARTICULATION MATRIX | | | | | | | | | | | | | | |
|------|---|-----|-----|-----|-----|-----|-----|-----|-----|----|----|-----|-----|-----|-----|
| COs/ | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO | PO | PO1 | PSO | PSO | PSO |
| POs | | | | | | | | | | 10 | 11 | 2 | 1 | 2 | 3 |
| CO1 | 2 | 3 | 2 | 1 | 1 | - | - | - | - | - | - | - | 3 | - | - |
| CO2 | 3 | 2 | 2 | 1 | 1 | - | - | - | - | - | - | - | 3 | 2 | 1 |
| CO3 | 2 | 2 | 2 | 3 | 1 | - | - | - | - | - | - | - | 3 | 2 | - |
| CO4 | 1 | 1 | 2 | 1 | 2 | - | - | - | - | - | - | - | 2 | 3 | - |
| CO5 | 1 | 1 | 2 | 2 | 2 | - | - | - | - | - | - | - | 2 | 3 | 1 |
| Avg | 1.8 | 1.8 | 2 | 1.6 | 1.4 | - | - | - | - | - | - | - | 2.6 | 2.5 | 1 |
| | 3/2/1 - indicates strength of correlation (3-High,2- Medium,1- Low) | | | | | | | | | | | | | | |

| Hours/Week | | | | | | | | | |
|--|-----------|--|--|--|--|--|--|--|--|
| Hours/Week | | | | | | | | | |
| | P TH | | | | | | | | |
| | 0 3 | | | | | | | | |
| Course Objectives: | | | | | | | | | |
| 1. Understand the division of network functionalities into layers. | | | | | | | | | |
| 2. Be familiar with the components required to build different types of networks | | | | | | | | | |
| 3. Be exposed to the required functionality at each layer | | | | | | | | | |
| 4. Learn the flow control and congestion control algorithms | | | | | | | | | |
| Unit I FUNDAMENTALS & LINK LAYER 9 | 0 0 9 | | | | | | | | |
| Overview of Data Communications- Networks – Building Network and its types– Overview of Internet - Layering - OSI Mode – Physical Layer – Overview of Data and Signals - introduction to Data Link Layer - L Addressing- Error Detection and Correction | | | | | | | | | |
| Unit II MEDIA ACCESS & INTERNETWORKING 9 | 0 0 9 | | | | | | | | |
| Overview of Data link Control and Media access control - Ethernet (802.3) - Wireless LANs – Available Pro Bluetooth – Bluetooth Low Energy – WiFi – 6LowPAN–Zigbee - Network layer services – Packet Switching Address – Network layer protocols (IP, ICMP, Mobile IP) | | | | | | | | | |
| Unit IIIROUTING9 | 0 0 9 | | | | | | | | |
| Routing - Unicast Routing – Algorithms – Protocols – Multicast Routing and its basics – Overview of Intrador interdomain protocols – Overview of IPv6 Addressing – Transition from IPv4 to IPv6 | main and | | | | | | | | |
| Unit IVTRANSPORT LAYER9 | 0 0 9 | | | | | | | | |
| Introduction to Transport layer –Protocols- User Datagram Protocols (UDP) and Transmission Control Protocols (TCP) –Services – Features – TCP Connection – State Transition Diagram – Flow, Error and Congestion Control - Congestion avoidance (DECbit, RED) – QoS – Application requirements | | | | | | | | | |
| Unit V APPLICATION LAYER 9 | 0 0 9 | | | | | | | | |
| Application Layer Paradigms – Client Server Programming – World Wide Web and HTTP - DNS- Electronic Mail (SMTP, POP3, IMAP, MIME) – Introduction to Peer to Peer Networks – Need forCryptography and Network Security – Firewalls. | | | | | | | | | |
| Total (45L)= 45 | 5 Periods | | | | | | | | |

Text Books: 1.

Behrouz A Forouzan, Data Communications and Networking, 4th Edition, 2020

| | C | James F. Kurose, Keith W. Ross, Computer Networking - A Top-Down Approach Featuring the Internet, |
|---|----|---|
| 4 | ۷. | Seventh Edition, Pearson Education, 2016. |

| Refe | Reference Books: | | | | | | | |
|------|--|--|--|--|--|--|--|--|
| 1. | Nader. F. Mir," Computer and Communication Networks", Pearson Prentice Hall Publishers, 2nd Edition, 2014. | | | | | | | |
| 2. | Alberto Leon-Garcia, IndraWidjajaCommunication Networks 2nd Edition McGraw-Hill Education, 2003 | | | | | | | |
| 3. | Ying-Dar Lin, Ren-Hung Hwang, Fred Baker, "Computer Networks: An Open Source Approach", McGraw Hill | | | | | | | |
| | Publisher, 2011. | | | | | | | |
| 4. | Larry L. Peterson, Bruce S. Davie, "Computer Networks: A Systems Approach", Fifth Edition, Morgan | | | | | | | |
| | Kaufmann Publishers, 2011. | | | | | | | |
| E-Re | ferences: | | | | | | | |
| 1. | https://onlinecourses.nptel.ac.in/noc22_ee61/preview | | | | | | | |
| 2. | https://www.ee.iitb.ac.in/~sarva/courses/EE706/2012/EE706LecNotes.pdf | | | | | | | |
| 3. | http://www.cs.kent.edu/~farrell/net01/lectures/ | | | | | | | |
| | | | | | | | | |

| | Course Outcomes: Upon completion of this course, the students will be able to: | | | | | | |
|-----|--|---------------|--|--|--|--|--|
| CO1 | Explain the basic concept in modern data communication and different level of layers in the protocol | Understanding | | | | | |
| CO2 | Analyse the functions and services of data link layer | Analysing | | | | | |
| CO3 | Categorize the functions and services of network layer | Understanding | | | | | |
| CO4 | Examine the basic functions of transport layer and congestion in networks | Understanding | | | | | |
| CO5 | Analyse the concepts of various network applications and data security | Analysing | | | | | |

| | | | | | COL | JRSE . | ARTI | CULA | TION | MATR | IX | | | | |
|---------|---|-----|-----|----|------|--------|------|------|------|------|----|----|------|------|------|
| COs/POs | РО | PO | РО | PO | PO5 | PO | РО | PO | PO | PO | РО | PO | PSO1 | PSO2 | PSO3 |
| | 1 | 2 | 3 | 4 | | 6 | 7 | 8 | 9 | 10 | 11 | 12 | | | |
| CO1 | 2 | 1 | 1 | - | 1 | - | - | - | - | - | - | - | 2 | - | 1 |
| CO2 | 2 | 1 | 2 | - | 1 | - | - | - | - | - | - | - | 2 | 1 | 1 |
| CO3 | 2 | 1 | 1 | - | - | - | - | - | - | - | - | - | 3 | 1 | 2 |
| CO4 | 3 | 2 | 1 | - | 2 | - | - | - | - | - | - | - | 2 | - | 2 |
| CO5 | 2 | 1 | 1 | - | 1 | - | - | - | - | - | - | - | 1 | 1 | 1 |
| Avg | 2.2 | 1.2 | 1.2 | - | 1.25 | - | - | - | - | - | - | - | 2 | 1 | 1.4 |
| | 3/2/1 - indicates strength of correlation (3-High,2- Medium,1- Low) | | | | | | | | | | | | | | |

| 18E | CM08 | | | | | | | | | |
|------|---|--|---------------------|----------|---------|-------|--------|--------|--|--|
| PRI | EREQUIS | ITES | CATEGORY | OE | C | redit | | 3 | | |
| | | | Hours/Week | L | | Т | Р | TH | | |
| | | | Hours/ week | 3 | | 0 | 0 | 3 | | |
| Cou | Course Objectives | | | | | | | | | |
| 1 | To under | stand Smart Objects and IoT Architectures | | | | | | | | |
| 2 | To learn | about various IOT-related protocols | | | | | | | | |
| 3 | To build | simple IoT Systems using Arduino and Raspberry I | Pi | | | | | | | |
| 4 | To under | stand data analytics and cloud in the context of IoT | | | | | | | | |
| 5 | To develo | op IoT infrastructure for popular applications | | | | | | | | |
| Ī | Unit I | FUNDAMENTALS OF IOT | | | 9 | 0 | 0 | 9 | | |
| | | nternet of Things - Enabling Technologies - Io | | | | | | | | |
| | | Alternative IoT models – Simplified IoT Architectu | | | | | | | | |
| | Cloud in I art Objects | oT – Functional blocks of an IoT ecosystem – Sen | sors, Actuators, Sr | nart Ot | ojects | and (| Conn | ecting | | |
| | Jnit II | IoT PROTOCOLS | | | 9 | 0 | 0 | 9 | | |
| IoT | Access T | echnologies: Physical and MAC layers, topology | y and Security of | IEEE | 802.1 | 5.4, | 802. | 15.4g, | | |
| 802 | .15.4e, 190 | 1.2a, 802.11ah and LoRaWAN – Network Layer: I | P versions, Constra | ained N | lodes a | and C | Const | rained | | |
| | | ptimizing IP for IoT: From 6LoWPAN to 6Lo, Ro | | | | - | | | | |
| | MQTT | ansport Methods: Supervisory Control and Data Ac | equisition – Applic | ation L | ayer F | roto | cols: | COAP | | |
| | nit III | DESIGN AND DEVELOPMENT | | | 9 | 0 | 0 | 9 | | |
| | | odology - Embedded computing logic - Microcont | roller, System on | Chips - | - IoT | syste | m bu | ilding | | |
| | • | ino - Board details, IDE programming - Raspberry | • | - | | • | | • | | |
| Pro | ogramming | Ţ. | | | | | - | | | |
| U | nit IV | DATA ANALYTICS AND SUPPORTING SE | ERVICES | | 9 | 0 | 0 | 9 | | |
| | | Unstructured Data and Data in Motion Vs Data in | | | | • | | - | | |
| | | Iadoop Ecosystem – Apache Kafka, Apache Spa | | | | | | | | |
| | • | ively Cloud for IoT, Python Web Application Fra vith NETCONF-YANG | amework – Djang | 0 - AV | NS 10 | r 101 | - 3 | ystem | | |
| | Jnit V | CASE STUDIES/INDUSTRIAL APPLICATI | ONS | | 9 | 0 | 0 | 9 | | |
| Cisc | co IoT syst | em - IBM Watson IoT platform – Manufacturing - | Converged Plantw | vide Etl | hernet | Mod | lel (C | (PwE) | | |
| - Po | ower Utilit | y Industry - Grid Blocks Reference Model - Sma | rt and Connected | | | | | | | |
| Sma | Smart Lighting, Smart Parking Architecture and Smart Traffic Control Total (45 L) = 45 Periods | | | | | | | | | |
| | | | | Tota | 1 (45] | L) = | 45 P | eriods | | |
| | | | | | | | | | | |

| Text | Text Books: | | | | | | | | |
|------|--|--|--|--|--|--|--|--|--|
| 1 | David Hanes, Gonzalo Salgueiro, Patrick Grossetete, Rob Barton and Jerome Henry, —IoT Fundamentals: Networking Technologies, Protocols and Use Cases for Internet of Things, Cisco Press, 2017 | | | | | | | | |
| 2 | ArshdeepBahga, Vijay Madisetti, —Internet of Things – A hands-on approachl, Universities Press, 2015 | | | | | | | | |
| Refe | erence Books: | | | | | | | | |
| 1 | Olivier Hersent, David Boswarthick, Omar Elloumi, —The Internet of Things – Key applications and Protocols, Wiley, 2012 (for Unit 2). | | | | | | | | |

| 1 | https://online.stanford.edu/courses/xee100-introduction-internet-things https://www.udemy.com/topic/internet-of-things/ |
|------|--|
| E-Re | ferences: |
| 4 | Michael Margolis, Arduino Cookbook, Recipes to Begin, Expand, and Enhance Your Projects, 2nd Edition, O'Reilly Media, 2011. |
| 3 | Dieter Uckelmann, Mark Harrison, Michahelles, Florian (Eds), —Architecting the Internet of Thingsl, Springer, 2011. |
| 2 | Jan Ho ⁻ Iler, VlasiosTsiatsis, Catherine Mulligan, Stamatis, Karnouskos, Stefan Avesand. David Boyle, "From Machine-to-Machine to the Internet of Things - Introduction to a New Age of Intelligence", Elsevier, 2014. |

| | Course Outcomes: Upon completion of this course, the students will be able to: | | | | | | |
|-----|---|---------------|--|--|--|--|--|
| CO1 | Explain the concept of IoT. | Understanding | | | | | |
| CO2 | Analyze various protocols for IoT. | Applying | | | | | |
| CO3 | Design a PoC of an IoT system using Rasperry Pi/Arduino | Applying | | | | | |
| CO4 | Apply data analytics and use cloud offerings related to IoT. | Applying | | | | | |
| CO5 | Analyze applications of IoT in real time scenario | Analysing | | | | | |

| | COURSE ARTICULATION MATRIX | | | | | | | | | | | | | | |
|--------|---|-----|-----|-----|----|----|----|----|----|----|-----|----|-----|-----|-----|
| COs/PO | РО | РО | РО | PO | РО | PO | РО | РО | РО | PO | РО | РО | PSO | PSO | PSO |
| s | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 1 | 2 | 3 |
| CO1 | 2 | 1 | 2 | 1 | 1 | - | - | - | - | - | 1 | - | 2 | 2 | 2 |
| CO2 | 2 | 1 | 2 | 1 | 1 | - | - | - | - | - | 1 | - | 2 | 2 | 2 |
| CO3 | 2 | 2 | 3 | 2 | 1 | - | - | - | - | - | 2 | - | 2 | 2 | 2 |
| CO4 | 2 | 2 | 2 | 1 | 1 | - | - | - | - | - | 1 | - | 2 | 2 | 2 |
| CO5 | 2 | 2 | 3 | 2 | 1 | - | - | - | - | - | 2 | - | 2 | 2 | 2 |
| Avg | 2 | 1.6 | 2.4 | 1.4 | 1 | - | - | - | - | - | 1.4 | - | 2 | 2 | 2 |
| | 3/2/1 - indicates strength of correlation (3-High,2- Medium,1- Low) | | | | | | | | | | | | | | |

| 18E0 | CM09 | WIRELESS SENSORS AND NETWORK | XING | | | | | | | |
|--|-------|---|--------------------|-------------|--------|-------|--------|--|--|--|
| PRER | EQUIS | ITE: | CATEGORY | OE | Cre | dit | 3 | | | |
| | | | Hours/Week | L | Т | Р | ТН | | | |
| | | | Hours/ Week | 3 | 0 | 0 | 3 | | | |
| Course | | 49.000 | | | | | | | | |
| Course | Ŭ | | | | | | | | | |
| 1. | Learn | fundamental of Ad hoc network and architecture | | | | | | | | |
| 2. | Under | stand the MAC and routing protocols. | | | | | | | | |
| 3. | | | | | | | | | | |
| Unit I ROUTING PROTOCOLS 9 0 9 | | | | | | | | | | |
| | | d hoc Wireless Networks, Issues in Ad hoc wireless networks | • | | | | | | | |
| | • | Ad hoc wireless Internet, Issues in Designing a Routing of Routing Protocols, Table Driven Routing Protocols – Des | | | | | | | | |
| | | Routing protocols – Ad hoc On–Demand Distance Vector Rou | • | Distance | | | D V), | | | |
| Unit II | [| ARCHITECTURES OF WSN | | | 9 | 0 | 0 9 | | | |
| | • • | ion examples, Types of applications, Challenges for Wireless | | 0 | | • | | | | |
| | | or Networks, Single-Node Architecture: Hardware Components and execution environments | ents, Energy Cons | umption of | Sens | or N | odes, | | | |
| - | | itecture: Sensor Network Scenarios, Optimization goals and | figures of merit T | Design prin | cinles | of V | WSN | | | |
| | | ces of WSNs, gateway concepts. | inguies of ment, L | esign prin | cipies | 01 | vor, | | | |
| Unit II | I | MAC PROTOCOLS AND ROUTING PROTOCOLS | | | 9 | 0 | 0 9 | | | |
| Ũ | - | ssion: Predictive techniques – PCM – DPCM - DM - Transfor | e e | | | | | | | |
| | | rds - Study of EZW. Video compression: Video signal repre coding – The MPEG-1 Video Standard - The MPEG-2 Video | | | | | | | | |
| H.263. | based | Journg The Will 10-1 Video Standard - The Will 10-2 Vide | o Standard: 11.202 | - 110-1 K | cconn | nene | ation | | | |
| Unit I | V | QUALITY OF SERVICE AND ADVANCED APPLICA | ATION SUPPORT | I | 9 | 0 | 0 9 | | | |
| - • | | vice: Coverage and deployment, Reliable data transport, Singl | | | • | • | | | | |
| control specific | | te control - Advanced application support: Advanced in-ne | etwork processing, | Security a | nd Ap | plica | ation- | | | |
| ^ | | | | | - | | | | | |
| Unit V | | SENSOR NETWORK PLATFORMS AND TOOLS | | | 9 | 0 | 0 9 | | | |
| | | Hardware – Berkeley Motes, Programming Challenges, Nor | • | | • | | | | | |
| | | Node-level Simulators – NS2 and its extension to sensor lual nodes – State centric programming. | networks, COOJA | ., 1058IM | , Pro | gram | ming | | | |
| | | | | Total (45 | L) = 4 | 45 Pe | riods | | | |
| | | | | | | | | | | |

| Text | Books: |
|------|---|
| 1. | C. Siva Ram Murthy, and B. S. Manoj, "AdHoc Wireless networks ", Pearson Education – 2008 |
| 2. | Holger Karl and Andreas Willig, "Protocols And Architectures for Wireless Sensor Networks", John Wiley, 2007. |
| Refe | rence Books: |
| 1. | Feng Zhao and LeonidesGuibas, "Wireless sensor networks ", Elsevier publication - 2004. |
| 2. | Charles E. Perkins, —Ad Hoc Networking ^{II} , Addison Wesley, 2000. |
| 3. | William Stallings, "Wireless Communications and Networks ", Pearson Education – 2004 |
| 4. | I.F. Akyildiz, W. Su, Sankarasubramaniam, E. Cayirci, "Wireless sensor networks: a survey", Computer Networks, Elsevier, 2002, 394 - 422. |
| E-R | eferences: |
| 1. | https://nptel.ac.in/courses/106105183 |
| 2. | https://nptel.ac.in/courses/106105183 |
| 3. | https://archive.nptel.ac.in/courses/106/105/106105160/ |

| Course C Upon con | Bloom's Taxonomy Mapped | | | | | | |
|----------------------|---|---------------|--|--|--|--|--|
| CO1 | CO1 Know the basics of Ad hoc networks and Wireless Sensor Networks | | | | | | |
| CO2 | Have a knowledge on architecture of Wireless Sensor Networks | Applying | | | | | |
| CO3 | Apply the knowledge to identify MAC and routing protocols | Applying | | | | | |
| CO4 | Understand the transport layer and security issues possible in Ad hoc and sensor networks | Understanding | | | | | |
| CO5 | Be familiar with the OS used in Wireless Sensor Networks and build basic modules | Remembering | | | | | |

| | | | | | С | OURS | SE AR | TICU | LATI | ON M | ATRIX | | | | |
|---------|---|---------|---------|---------|---------|---------|---------|---------|---------|----------|----------|----------|----------|------|------|
| COs/POs | PO 1 | PO 2 | PO 3 | PO 4 | PO 5 | PO 6 | PO 7 | PO 8 | PO 9 | PO 10 | PO 11 | PO 12 | PSO 1 | PSO2 | PSO3 |
| CO1 | 3 | 3 | 1 | 3 | 3 | 3 | 2 | - | - | - | 3 | 3 | 3 | - | 2 |
| CO2 | 3 | 3 | 2 | 3 | 3 | 3 | 2 | - | - | - | 3 | 3 | 3 | - | 2 |
| CO3 | 3 | 3 | 3 | 3 | 3 | 3 | 2 | - | - | - | 3 | 3 | 3 | - | 2 |
| CO4 | 3 | 3 | 2 | 3 | 3 | 3 | 2 | - | - | - | 2 | 3 | 3 | - | 2 |
| CO5 | 3 | 3 | 2 | 3 | 3 | 3 | 2 | - | - | - | 3 | 3 | 3 | - | 2 |
| Avg | 3 | 3 | 2 | 3 | 3 | 3 | 2 | - | - | - | 2.8 | 3 | 3 | - | 2 |
| | 3/2/1 - indicates strength of correlation (3-High,2- Medium,1- Low) | | | | | | | | | | | | | | |

| 18E0 | CM10 | | | BASICS O | F EMBEDDED SYST | EMS | | | | | |
|---|--|--------------|-------------|--------------------------------|--|----------------------|-------|------------|------|-----|-------|
| PRE | REQU | JISITES | | | | CATEGORY | 0 | E | Cred | it | 3 |
| Mior | oproce | essors and I | Mmicroco | ntrollors | | Hours/Week | L | л - | Г | Р | TH |
| WIICI | oproce | | Minicioco | nuoners | | Hours/ Week | 3 | ; (| 0 | 0 | 3 |
| Cou | Course Objectives | | | | | | | | | | |
| 1 | 1 To impart knowledge on embedded system architecture and embedded development Strategies | | | | | | | | | | |
| 2 | | | | | processors and periphera | al interfacing | | | | | |
| 3 | To u | nderstand b | basics of F | Real Time Operat | ting System | | | | | - | |
| UNI | ΤI | BASICS | OF EMB | EDDED SYSTI | EMS | | | 9 | 0 | 0 | 9 |
| Prog | Introduction - Fundamental Components of Embedded Systems - Challenges for Embedded Systems - Examples - Programming Languages - Recent Trends in Embedded Systems - Architecture of Embedded Systems - Embedded Design Life Cycle - Selection Process - Hardware Software Partitioning - Development Environment. | | | | | | | | | | |
| UNIT II MEMORY MANAGEMENT AND INTERRUPTS | | | | | | | | | | 0 | 9 |
| Vs I | nterrup | | s of Intern | | Memory Management N Latency - Interrupt Pri | | | | | | |
| UNI | T III | COMMU | UNICATI | ON INTERFAC | CES | | | 9 | 0 | 0 | 9 |
| | 0 | | | faces - RS232/U – Bluetooth | ART - RS422/RS485 - | I2C Interface - SPI | Inter | rface - | USB | – C | CAN - |
| UNI | T IV | REAL T | IME OPE | ERATING SYST | ΓEMS | | | 9 | 0 | 0 | 9 |
| Sche | duling | - Event D | riven Sch | eduling - Resour | t Scheduling - Classifica ree Sharing - Priority Inl es - Message Queues - T | heritance Protocol - | Prior | rity Cei | | | |
| UNI | UNIT V VALIDATION AND DEBUGGING | | | | | | | | | 0 | 9 |
| Host and Target Machines - Validation Types and Methods - Host Testing - Host-Based Testing Setup - Target Testing - Remote Debuggers and Debug Kernels - ROM Emulator - Logical Analyzer – Background Debug Mode - InCircuit Emulator CASE STUDY: RFID Systems - GPS Navigation System – Development of Protocol Converter. Total (45 L) = 45 Periods | | | | | | | | | | | |
| | D 1 | | | | | | | | | | |

| Text] | Books: | | | | | | | |
|--------|--|--|--|--|--|--|--|--|
| 1 | Sriram V Iyer and Pankaj Gupta, —Embedded Real-time Systems Programming ^I , Tata McGraw-Hill Publishing Company Limited, New Delhi, 2006. | | | | | | | |
| 2 | Arnold S Berger, —Embedded Systems Design - An Introduction to Processes, Tools and Techniques, Elsevier, New Delhi, 2011. | | | | | | | |
| Refer | ence Books: | | | | | | | |
| 1 | Prasad K V K K, —Embedded/Real-Time Systems: Concepts, Design and Programming – The Ultimate Reference, Himal Impressions, New Delhi, 2003 | | | | | | | |
| 2 | Heath, "Embedded Systems Design", Newnes an Imprint of Elsevier, Massachusetts, 2003. | | | | | | | |
| 3 | Tammy Noergaard, "Embedded Systems Architecture", Newnes an Imprint of Elsevier, Massachusetts, 2006. | | | | | | | |
| 4 | Raj Kamal, 'Embedded System-Architecture, Programming, Design', McGraw Hill, 2013 | | | | | | | |
| E-Ref | E-References: | | | | | | | |
| 1 | https://lecturenotes.in/subject/225/embedded-system-es | | | | | | | |
| 2 | https://nptel.ac.in/courses/108102045/19 | | | | | | | |

.

| | Course Outcomes: Upon completion of this course, the students will be able to | | | | | | |
|-----|--|---------------|--|--|--|--|--|
| CO1 | Outline the concepts of embedded systems | Understanding | | | | | |
| CO2 | Understand the concept of memory management system and interrupts. | Understanding | | | | | |
| CO3 | Know the importance of interfaces. | Understanding | | | | | |
| CO4 | Understand real time operating system concepts. | Understanding | | | | | |
| CO5 | To realize the applications of validation and debugging. | Applying | | | | | |

| | COURSE ARTICULATION MATRIX | | | | | | | | | | | | | | |
|---------|----------------------------|---------|---------|---------|---------|---------|---------|---------|---------|----------|----------|----------|-------|------|------|
| COs/POs | PO 1 | PO 2 | PO 3 | PO 4 | PO 5 | PO 6 | PO 7 | PO 8 | PO 9 | PO 10 | PO 11 | PO 12 | PSO 1 | PSO2 | PSO3 |
| CO1 | 3 | 3 | 1 | 3 | - | - | - | - | - | - | 3 | 3 | 3 | - | 2 |
| CO2 | 3 | 3 | 2 | 3 | - | - | - | - | - | - | 3 | 3 | 3 | - | 2 |
| CO3 | 3 | 3 | 3 | 3 | - | - | - | - | - | - | 3 | 3 | 3 | - | 2 |
| CO4 | 3 | 3 | 2 | 3 | - | - | - | - | - | - | 2 | 3 | 3 | - | 2 |
| CO5 | 3 | 3 | 2 | 3 | - | - | - | - | - | - | 3 | 3 | 3 | - | 2 |
| Avg | 3 | 3 | 2 | 3 | - | - | - | - | - | - | 2.8 | 3 | 3 | - | 2 |
| | | 3/ | 2/1 - i | ndicat | es stre | ength o | of corr | elatior | n (3-H | igh,2- N | Medium | n,1- Lo | w) | | |

B.E. - ELECTRICAL AND ELECTRONICS ENGINEERING - MINOR DEGREE

| 181 | EEM01 | LINEAR AND DIGITAL ELECTRONICS CI | IRCUITS | SEM | IESTI | ER | | | | | | |
|-------------|---|--|------------------------|-------------|----------|----------|--------|--|--|--|--|--|
| PR | EREQ | UISITES | CATEGORY | PE | Cre | edit | 3 | | | | | |
| F1 - | atura D | | Harry/Wash | L | Т | Р | TH | | | | | |
| Ele | ctron D | evices and Circuits | Hours/Week | 3 | 0 | 0 | 3 | | | | | |
| Co | urse O | bjectives: | | | | | | | | | | |
| 1. | To im | part knowledge on the characteristics& applications of Operation A | Amplifier, functiona | l diagram | and a | oplicat | ions | | | | | |
| | of line | | | | | | | | | | | |
| 2. | | | | | | | | | | | | |
| 3. | 3. To design the combinational logic circuits and sequential logic circuits | | | | | | | | | | | |
| Un | it I | OPERATIONAL AMPLIFIERS | | 9 | 0 | 0 | 9 | | | | | |
| Ope | erationa | amplifiers - Equivalent circuit, voltage transfer curve - Open loop | Op-amp configurati | ons-Volt | age ser | ries, V | oltage | | | | | |
| | | ack amplifiers configurations, closed loop differential amplifiers f | - | - | | | | | | | | |
| | - | et voltage, minimizing output offset voltage due to input bias curre | | | | | - | | | | | |
| | - | ers, CMRR - Open loop and closed loop frequency response of op | o-amps, circuit stabi | lity, slew | rate ar | nd its e | ffects | | | | | |
| in a | Γ. | | _ | | | | | | | | | |
| | it II | APPLICATION OF OPERATIONAL AMPLIFIER AN | | 9 | 0 | 0 | 9 | | | | | |
| | | amplifiers- Summing, Scaling and Averaging amplifiers-Instrume | - | - | | | | | | | | |
| | - | and grounded loads - Current to voltage converter - Integrator, Diff | - | - | | | - | | | | | |
| | | Schmitt trigger with voltage limiter- Precision Rectifier Circuits- equency response characteristics of major active filters, first and his | | - | | | | | | | | |
| filte | | quency response characteristics of major active inters, inst and my | glief ofder fow pass | | pass m | ters, ar | i pass | | | | | |
| | | block diagram and Applications of Linear ICs: IC 555 Timer -IC 5 | 566 Voltage control | led oscill: | ator- IC | 7 565 F | hase- | | | | | |
| | | vs - IC LM317 voltage regulators. | oo voluge control | ieu oseini | | 20001 | nuse | | | | | |
| | it III | COMBINATIONAL LOGIC CIRCUITS | | 9 | 0 | 0 | 9 | | | | | |
| Rep | oresenta | tion of logic functions: SOP and POS forms - Simplification | of switching func | tions: K- | maps | metho | d and | | | | | |
| - | | luskey (Tabulation) method. | C | | 1 | | | | | | | |
| Des | sign:Ad | lers -Subtractors- 2 bit Magnitude Comparator-Multiplexer- Demu | ultiplexer- Encoder | - Priority | Encod | er - De | coder | | | | | |
| - C | ode Co | overters. Implementation of combinational logic circuits using mul | tiplexers and Decod | ler. | | | | | | | | |
| Un | it IV | SYNCHRONOUS SEQUENTIAL LOGIC CIRCUITS | | 9 | 0 | 0 | 9 | | | | | |
| Flip | p-flops: | SR, D, JK and T- Conversion of flip-flops; Classification of sequen | tial circuits: Moore a | and Mealy | y mode | ls - An | alysis | | | | | |
| and | l design | of synchronous sequential circuits - Design of synchronous counter | ers- Universal shift 1 | egister. | | | | | | | | |
| Un | it V | ASYNCHRONOUS SEQUENTIAL LOGIC CIRCUITS | 5 | 9 | 0 | 0 | 9 | | | | | |
| Fur | ndament | al mode and pulse mode circuits, Analysis procedure of asynchro | nous circuits with / | without u | sing of | SR la | tches- | | | | | |
| - | | ate / flow table - Reduction of state and flow table - state assignm | • | • | nchro | 10us ci | rcuits | | | | | |
| wit | h /witho | ut using of SR latches-Problems in asynchronous sequential circui | | | | | | | | | | |
| | | | Tota | al (45L+0 | = (T0 | 45 Pe | riods | | | | | |
| | | | | | | | | | | | | |

| Text | Books: |
|------|---|
| 1. | Ramakant A Gayakward, "Op-Amps and Linear Integrated Circuits", Fourth Edition, Pearson Education, 2003. |
| 2. | Donald.E.Neaman, "Electronic Circuit, Analysis and Design", Tata McGraw Hill Publishing Company Limited, Second |
| ۷. | Edition, 2002. |
| 3. | D.Roy Chowdhury and Shail B. Jain, "Linear Integrated Circuits", Fourth Edition, New Age International (P) Ltd |
| | Publishers, 2014. |
| 4. | M. Morris Mano, "Digital Design", Third Edition, Prentice Hall of India Pvt. Ltd., New Delhi, 2003 / Pearson |
| 4. | Education (Singapore) Pvt. Ltd., New Delhi, 2010. |
| 5. | S. Salivahanan and S. Arivazhagan, "Digital Circuits and Design", Third Edition, Vikas Publishing House Pvt. Ltd, |
| 5. | New Delhi, 201 |
| Refe | rence Books: |

| 1. | Jacob Millman, Christos C.Halkias, "Integrated Electronics - Analog and Digital circuits system", Tata McGraw Hill 2003. |
|----|---|
| 2. | R.P.Jain, "Modern Digital Electronics", Third Edition, Tata McGraw-Hill Publishing company limited, New Delhi, 2011. |
| 3. | Thomas L. Floyd, "Digital Fundamentals", Pearson Education, Inc, New Delhi, 2015 |
| 4. | Donald P.Leach and Albert Paul Malvino, "Digital Principles and Applications", Fifth Edition, Tata McGraw Hill Publishing Company Limited, New Delhi, 2012. |

| Cours | e O | utcomes: | Bloom's Taxonomy | | | |
|--------|-----|---|-------------------|--|--|--|
| Upon c | omp | Mapped | | | | |
| CO1 | : | Understand the Op-amp characteristics | L2: Understanding | | | |
| CO2 | : | Understand the applications of Op-amp and other linear ICs. L2: Understanding | | | | |
| CO3 | : | Apply K-map and Tadulation methods to simplify the switching functions | L3: Applying | | | |
| CO4 | : | Design and implement of combinational logic circuits | L6: Creating | | | |
| CO5 | : | Analyse and design of synchronous & asynchronous sequential logic circuits | L4: Analyzing | | | |

| COUR | COURSE ARTICULATION MATRIX | | | | | | | | | | | | | | |
|------------|---|-----|-----|------|-----|-----|------------|-----|-----|----------|----------|----------|----------|----------|----------|
| CO/ POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO 10 | PO 11 | PO 12 | PSO 1 | PSO 2 | PSO 3 |
| CO1 | 2 | 1 | | | | | | | | | | | 2 | | |
| CO2 | 3 | 2 | 1 | 1 | | | | | | | | | 3 | | |
| CO3 | 3 | 2 | | 2 | 2 | | | | | | | | 3 | 3 | |
| CO4 | 3 | 2 | 3 | 1 | 2 | | | | | | | 2 | 3 | 3 | 1 |
| CO5 | 3 | 2 | 3 | 1 | 2 | | | | | | | 2 | 3 | 3 | 1 |
| Avg. | 2.8 | 1.8 | 2.3 | 1.25 | 2 | - | - | - | - | - | - | 2 | 2.8 | 3 | 1 |
| | 3/2/1-indicates strength of correlation (3- High, 2-Medium, 1- Low) | | | | | | | | | | | | | | |

| 18EEM02 | MICROPROCESSOR AND MICROCONTR | ROLLER | SE | SEMESTER | | | | |
|---------------|--|----------------------|------------|----------|----------|----------|--|--|
| PREREQU | ISTIES | CATEGORY | PE | C | redit | 3 | | |
| C Program | ming | | L | Т | Р | TH | | |
| U | | Hours/Week | 3 | 0 | 0 | 3 | | |
| Course Ob | jectives: | | | | | | | |
| 1. To stu | idy the architecture of μP8085 and μC 8051. | | | | | | | |
| 2. To stu | dy the Interrupt structure of 8085 and 8051. | | | | | | | |
| 3. To do | simple applications development with programming 8085 and 8 | 8051. | | | | | | |
| UNIT I | 8085 8 BIT MICROPROCESSOR | | 9 | 0 | 0 | 9 | | |
| Fundamental | s of microprocessors – Architecture of 8085 – Groups of Instruc | tions - Addressing r | nodes – I | Basic t | iming d | iagram | | |
| – Organizati | on and addressing of Memory and I/O systems -Interrupt structu | ure – Stack and sub- | routines | - Sim | ple 808 | 5 based | | |
| system desig | n and programming. | | | | | | | |
| UNIT II | 8051 8 BIT MICROCONTROLLER | | 9 | 0 | 0 | 9 | | |
| Fundamental | s of microcontrollers - Architecture of 8051 - Groups of Ins | tructions - Address | ing mod | es – C | rganiza | tion of | | |
| Memory sys | tems - I/O Ports - Timers/Counters - Serial Port - Interrupt | structure – Simple | program | ming o | concept | s using | | |
| Assemblers a | and Compliers. | | | | | | | |
| UNIT III | INTERFACING WITH 8051 MICROCONTROLLEI | R | 9 | 0 | 0 | 9 | | |
| Need and rec | uirements of interfacing – Interfacing – LED, 7 segment and LC | D Displays – Tactil | e switche | es, Mat | rix keyl | ooard – | | |
| Parallel ADC | C - DAC - Interfacing of Current, Voltage, RTD and Hall Sensor | rs. | | | | | | |
| UNIT IV | EXTERNAL COMMUNICATION INTERFACE | | 9 | 0 | 0 | 9 | | |
| Synchronous | and Asynchronous Communication. RS232, RS 485, SPI, I2C. I | ntroduction and inte | rfacing to | o proto | cols lik | e Blue- | | |
| tooth and Zig | g-bee. | | | | | | | |
| UNIT V | APPLICATIONS OF MICROCONTROLLERS | | 9 | 0 | 0 | 9 | | |
| Simple progr | ramming exercises- key board and display interface -Control of s | servo motor stepper | motor co | ontrol- | Applica | ation to | | |
| automation s | ystems. | | | | | | | |
| | | To | tal (45I | (+0T) | - 45 P | eriods | | |

| Text H | Books: | | | | | | |
|--------|--|--|--|--|--|--|--|
| 1. | R.S. Gaonkar, 'Microprocessor Architecture Programming and Application', with 8085, Wiley Eastern Ltd., New Delhi, 2013. | | | | | | |
| | | | | | | | |
| 2. | K. J. Ayala, "8051 Microcontroller", Delmar Cengage Learning, 2004. | | | | | | |
| 3. | Muhammad Ali Mazidi & Janice Gilli Mazidi, R.D.Kinely 'The 8051 Micro Controller and Embedded Systems', PHI | | | | | | |
| 5. | Pearson Education, 5th Indian reprint, 2003. | | | | | | |
| Refere | Reference Books: | | | | | | |
| 1. | R. Kamal, "Embedded System", McGraw Hill Education, 2009. | | | | | | |
| 2. | D. V. Hall, "Microprocessors & Interfacing", McGraw Hill Higher Education, 1991. | | | | | | |
| E-Ref | erences; | | | | | | |
| 1. | www.onlinecourses.nptel.ac.in/noc18_ee41 | | | | | | |
| 2. | www.class-central.com | | | | | | |
| 3. | www.mooc-list.com | | | | | | |

| Cours | e O | utcomes: | Bloom's Taxonomy | | | |
|--------|------|---|-------------------|--|--|--|
| Upon c | comp | pletion of this course, the students will be able to: | Mapped | | | |
| CO1 | : | Understand basics of microprocessor and microcontroller | L2: Understanding | | | |
| CO2 | : | Understand the architecture of Microprocessor and Microcontroller | L1: Remembering | | | |
| CO3 | : | Apply the digital concepts to measure and control simple electrical systems | L3: Applying | | | |
| CO4 | : | Design and interface communications between digital systems | L2: Understanding | | | |
| CO5 | : | Design a microcontroller based electrical control system. | L5: Evaluating | | | |

| COUR | COURSE ARTICULATION MATRIX | | | | | | | | | | | | | | |
|-------------|---|---------|---------|----------------|---------|---------|---------|---------|---------|----------|----------|----------|----------|----------|----------|
| COs/ POs | PO 1 | PO 2 | PO 3 | PO 4 | PO 5 | PO 6 | PO 7 | PO 8 | PO 9 | PO 10 | PO 11 | PO 12 | PS O1 | PS O2 | PS O3 |
| CO1 | 2 | 1 | 1 | 1 | | | | | | | | 1 | 1 | 1 | |
| CO2 | 2 | 1 | 1 | 1 | | | | | | | | 1 | 1 | 1 | |
| CO3 | 2 | 3 | 2 | 3 | 2 | | | | | | | 1 | 1 | 1 | 2 |
| CO4 | 2 | 3 | 3 | 3 | 2 | | | | | | | 2 | 2 | 2 | 2 |
| CO5 | 2 | 3 | 3 | 3 | 2 | | | | | | | 2 | 2 | 2 | 2 |
| Avg. | 2 | 2.2 | 2 | 2.2 | 2 | - | - | - | - | - | - | 1.4 | 1.4 | 1.4 | 2 |
| | 3/2/1-indicates strength of correlation (3- High, 2-Medium, 1- Low) | | | | | | | | | | | | | | |

| 18 | EEM03 | CONTROL SYSTEMS | | SEI | MEST | ER | | | | | | |
|---|---|---|------------------------|----------|-----------|-----------|-----------|--|--|--|--|--|
| PR | EREQUI | ISTIES | CATEGORY | PE | Cre | edit | 3 | | | | | |
| Flee | ctrical Ma | chines and Electric circuit analysis | Hours/Week | L | Т | Р | TH | | | | | |
| LIC | | ennies and Electric circuit analysis | Hours/ Week | 1 | 1 | 0 | 3 | | | | | |
| Co | urse Obje | ectives: | | | | | | | | | | |
| 1. | To under | stand the methods of representation of physical systems and | getting their transfer | functi | on moo | lels. | | | | | | |
| 2. | 2. To provide adequate knowledge in the time response of systems and steady state error analysis. | | | | | | | | | | | |
| 3. | - | pasic knowledge in obtaining the open loop and closed loop f | 1 , 1 | - | ms. | | | | | | | |
| 4. | | stand the concept of stability of control system and methods | of stability analysis. | | | | | | | | | |
| 5. | To study | the designing compensators for a feedback control system. | | | | | | | | | | |
| UN | UNIT IMODELLING OF LINEAR TIME INVARIANT SYSTEMS69 | | | | | | | | | | | |
| Bas | ic element | s in control systems – Open and closed loop systems – Feedba | ck control system ch | naracter | ristics - | Mathe | ematical | | | | | |
| mod | del and Ele | ectrical analogy of mechanical systems - Transfer function | Representation- Sy | nchro · | – AC a | and DO | C servo- | | | | | |
| mot | tors – Bloc | k diagram reduction techniques – Signal flow graphs. | | | | | | | | | | |
| UN | IT II | TIME RESPONSE ANALYSIS | | 6 | 3 | 0 | 9 | | | | | |
| Star | ndard test | signals - Time response of first order and second order syst | ems -time domain | specific | cations | - Stea | dy-state | | | | | |
| erro | ors and erro | or constants - Type and order of control systems - Effect o | f adding poles and z | zeros to | o transf | fer fun | ctions – | | | | | |
| Res | ponse with | P, PI, PD and PID controllers. | | | | | | | | | | |
| UN | IT III | FREQUENCY RESPONSE ANALYSIS | | 6 | 3 | 0 | 9 | | | | | |
| Cor | relation be | tween time and frequency response: Second order systems - | Frequency domain | specific | cations | - Pola | r plots – | | | | | |
| Boo | le plots – C | Computation of Gain Margin and Phase Margin — Constant I | M and N-circles – N | ichols | chart. | | | | | | | |
| UN | IT IV | STABILITY OF CONTROL SYSTEM | | 6 | 3 | 0 | 9 | | | | | |
| BIE | BO stability | v – Necessary conditions for stability – Routh-Hurwitz stabilit | y criterion – Root lo | cus co | ncepts | – Rule | s for the | | | | | |
| con | struction o | f Root loci - Nyquist stability criterion - Assessment of relat | ive stability using N | lyquist | criterio | on. | | | | | | |
| UNIT VCOMPENSATOR AND CONTROLLER DESIGN6309 | | | | | | | | | | | | |
| Nee | ed for com | pensation - Types of compensators - Electric network rea | alization and freque | ncy ch | aracter | istics of | of basic | | | | | |
| con | pensators | Lag, lead and lag-lead compensators - Design of compensation | tors using root locu | s and H | Bode pl | ot tech | iniques- | | | | | |
| PID | o controller | : Design using reaction curve and Ziegler - Nichols techniqu | ıe. | | | | | | | | | |
| | Total (30L+15T) = 45 Periods | | | | | | | | | | | |

| Tex | xt Books: |
|-----|--|
| 1. | A. Anand Kumar, "Control Systems", PHI Learning Pvt. Ltd., New Delhi, 2 nd Edition, 2017. |
| 2. | I.J. Nagrath, and M. Gopal, "Control Systems Engineering", New Age International Publishers, Delhi, 7th Edition, 2021. |
| Ref | ference Books: |
| 1. | K. Ogata, "Modern Control Engineering", Pearson Education, New Delhi, 5th Edition, 2021. |
| 2. | M. Gopal, "Control Systems: Principles and Design", TMH, New Delhi, 4th Edition, 2018. |
| E-F | Reference |
| 1. | https://nptel.ac.in/courses/107106081 |
| 2. | https://nptel.ac.in/courses/108106098 |

| Course Ou | itco | mes: | Bloom's Taxonomy | | |
|-----------|---|---|-------------------|--|--|
| Upon com | plet | ion of this course, the students will be able to: | Mapped | | |
| CO1 | | Develop the transfer function models of any electrical and electro-mechanical | L2: Understanding | | |
| COI | · | systems. | | | |
| CO2 | CO2 : Obtain the time responses of the systems and construct root locus plot. | | | | |
| CO3 | : | Analyze the frequency response of the system | L3: Applying | | |
| CO4 | : | Analyze the absolute / relative stability of a control system. | L4: Analyzing | | |
| CO5 | L3: Applying | | | | |

| COUR | SE AR | TICU | LATIO | ON MA | ATRIX | | | | | | | | | | |
|-------------|---------|---------|---------|----------|----------|----------|-----------|----------|---------|----------|----------|----------|----------|----------|----------|
| COs/ POs | PO 1 | PO 2 | PO 3 | PO 4 | PO 5 | PO 6 | PO 7 | PO 8 | PO 9 | PO 10 | PO 11 | PO 12 | PS O1 | PS O2 | PS O3 |
| CO1 | 3 | 3 | 2 | 2 | 2 | | | | | | | 1 | 3 | 2 | 1 |
| CO2 | 3 | 3 | 3 | 2 | 2 | | | | | | | 1 | 3 | 2 | 1 |
| CO3 | 3 | 3 | 3 | 2 | 2 | | | | | | | 1 | 3 | 2 | 1 |
| CO4 | 3 | 3 | 3 | 2 | 2 | | | | | | | 1 | 3 | 2 | 1 |
| CO5 | 3 | 3 | 3 | 2 | 2 | | | | | | | 1 | 3 | 2 | 1 |
| Avg | 3 | 3 | 2.8 | 2 | 2 | - | - | - | - | - | - | 1 | 3 | 2 | 1 |
| | • | | 3/2/1- | indicate | s streng | th of co | rrelation | n (3- Hi | gh, 2-M | ledium, | 1- Low |) | • | • | · |

| 18E | EM04 | MEASUREMENTS AND INSTRUMENTA | ATION | SEN | 1ESTI | ER | | | | | |
|-----------------------------------|--------------------|---|------------------------|-------------|-----------------|----------|----------|--|--|--|--|
| PRE | REQU | ISTIES | CATEGORY | PE | Cre | edit | 3 | | | | |
| Flootr | ria Circu | it Analysis | Hours/Week | L | Т | Р | TH | | | | |
| Elecu | ic Circu | | Hours/ week | 3 | 0 | 0 | 3 | | | | |
| Cour | se Obj | ectives: | | | | | | | | | |
| 1. | To edu | cate the fundamental concepts and characteristics of measureme | ent System | | | | | | | | |
| 2. | To intr quantit | oduce the fundamentals of electrical and electronic instruments ies | for measurement of | Electric | al and I | Non-el | ectrical | | | | |
| 3. | To fam | iliarize Oscilloscope and the bridge circuits for electrical param | neters measurement | | | | | | | | |
| UNI | ГΙ | INTRODUCTION | | 9 | 0 | 0 | 9 | | | | |
| Eleme | ents of a | generalized measurement system - Static and dynamic character | eristics - Errors in m | neasurem | ent. Me | easurei | nent of | | | | |
| voltag | ge and cu | irrent - permanent magnet moving coil and moving iron type m | eters | | - | | | | | | |
| UNI | ΓII | MEASUREMENT OF POWER, ENERGY AND FR | REQUENCY | 9 | 0 | 0 | 9 | | | | |
| | | of power - single and three phase- electrodynamometer type | | | - | | - | | | | |
| equati | ion for d | eflection - errors. Measurement of energy-Single phase induction | ion type energy mete | ers, Instru | iment t | ransfo | rmers – | | | | |
| | | otential transformers, Power factor meters- Single phase electro | dynamometer type p | power fac | tor me | ter, fre | quency | | | | |
| | | al resonance type frequency meter | | | | | | | | | |
| UNI | | DC AND AC BRIDGES | | 9 | 0 | 0 | 9 | | | | |
| | | ions - Wheatstone bridge - Kelvin double Bridge -Maxwell's | s inductance capacit | ance brid | ge – H | lay's b | ridge – | | | | |
| Ander | rson's bi | idge – Schering bridge and De Sauty's bridge | | | | 1 | | | | | |
| UNI | ГIV | POTENTIOMETERS, OSCILLOSCOPES AND DIO | GITAL | 9 | 0 | 0 | 9 | | | | |
| UNI | | INSTRUMENTS | | , | U | v | , | | | | |
| DC Po | otentiom | eter- Crompton's Potentiometer, AC potentiometer- Drysdale p | polar potentiometer- | Gall Tin | sley co | -ordina | ite type | | | | |
| poten | tiometer | , Cathode Ray Oscilloscope and Digital storage Oscilloscope-O | Construction, operat | tion and a | Applica | ations, | Digital | | | | |
| multi-meters, Digital voltmeters. | | | | | | | | | | | |
| UNI | ΓV | MEASUREMENT OF NON-ELECTRICAL QUANT | FITIES | 9 | 0 | 0 | 9 | | | | |
| | | of transducers -Position transducers, Piezo-electric transduce | rs and Hall effect tr | ansduce | s. Me | asuren | nent of | | | | |
| pressu | ure, temp | perature and displacement- Introduction to Smart Sensors | | | | | | | | | |
| | | | То | tal (45L | -+ 0 T)= | = 45 P | eriods | | | | |

| Text H | Books: |
|--------|--|
| 1. | A.K. Sawhney, 'A Course in Electrical & Electronics Measurement & Instrumentation', Dhanpat Rai and Co, 2015 |
| 2. | E.O. Doebelin, 'Measurements Systems- Application and Design', Tata McGraw Hill publishing company, 2015. |
| Refere | ence Books: |
| 1. | D.V.S. Moorthy, 'Transducers and Instrumentation', Prentice Hall of India Pvt. Ltd, 2010. |
| 2. | H.S. Kalsi, 'Electronic Instrumentation', Tata McGraw Hill, 2015. |
| 3. | Martin Reissland, ' Electrical Measurements', New Age International(P) Ltd., Delhi, 2011. |
| E-Ref | erence: |
| 1 | https://archive.nptel.ac.in/courses/108/105/108105153/ |

| Course (| Duto | comes: | Bloom's Taxonomy |
|----------|------|---|-------------------|
| Upon com | plet | ion of this course, the students will be able to: | Mapped |
| CO1 | : | Recall the fundamentals of measurement system in electrical engineering. | L1: Remembering |
| CO2 | : | Describe the working principle of different measuring instruments | L2: Understanding |
| CO3 | : | Choose appropriate instrument for measuring the electrical parameters | L3: Applying |
| CO4 | : | Employ the digital instruments in real time measurements. | L3: Applying |
| CO5 | : | Select an appropriate transducer for measurement of non-electrical quantities | L4: Analysing |

| COUR | SE AR | FICUL | ATIO | N MA' | TRIX | | | | | | | | | | |
|-------------|---------|---------|----------|---------|----------|----------|----------|---------|---------|----------|----------|----------|----------|----------|----------|
| COs/ POs | PO 1 | PO 2 | PO 3 | PO 4 | PO 5 | PO 6 | PO 7 | PO 8 | PO 9 | PO 10 | PO 11 | PO 12 | PS O1 | PS O2 | PS O3 |
| CO1 | 2 | 2 | 2 | 3 | | | | 1 | | 2 | | 2 | 2 | 1 | 1 |
| CO2 | 1 | 3 | | | 3 | | | | | 2 | | 1 | 2 | 1 | |
| CO3 | 1 | 1 | | 2 | 1 | 1 | 2 | | 1 | | | | 1 | 2 | 1 |
| CO4 | 1 | 1 | | 1 | 1 | | 2 | 2 | 1 | | 2 | 2 | 1 | 3 | 1 |
| CO5 | 2 | 2 | 3 | 1 | 2 | 2 | 1 | | | 1 | 3 | | 1 | 2 | |
| Avg | 1.4 | 1.8 | 2.5 | 1.75 | 1.75 | 1.5 | 1.67 | 1.5 | 1 | 1.67 | 2.5 | 1.67 | 1.4 | 1.8 | 1 |
| | | • | 3/2/1-ir | dicates | strength | n of cor | relation | (3- Hig | h, 2-Me | edium, 1 | - Low) | • | | | • |

| 18E | EMO | 5 ELECTRICAL MACHINES | | SEME | ESTEF | ł | |
|--------|---------|--|----------------------------|--------------|------------|----------|----------|
| PRE | REQ | UISTIES | CATEGORY | PE | Cre | edit | 3 |
| | | | H | L | Т | P | TH |
| | | | Hours/Week | 3 | 0 | 0 | 3 |
| Cour | rse O | bjectives: | | | | | |
| 1. | To ii | mpart knowledge on construction, working and performance of D | C generators and me | otors. | | | |
| 2. | To d | eliberate the construction, working and performance of single pha | ase and three phase | ransform | ers. | | |
| 3. | To ii | mpart knowledge on construction, working and performance of sy | ynchronous generato | rs and mo | otors. | | |
| 4. | Toir | npart knowledge on construction, principle of operation and perfor | rmance of single and | three-pha | ase indu | uction 1 | notors. |
| UNI | ΤI | DC GENERATORS | | 9 | 0 | 0 | 9 |
| | - | operation, constructional details, types - EMF equation, armatu | | - | | - | - |
| - | | ns, compensating winding, commutation, methods of improving | | - | - | | |
| | | ics of different types of DC Generators. Parallel operation of DC | Generators, applicat | 1 | 1 | 1 | |
| UNI | | DC MOTORS | | 9 | 0 | 0 | 9 |
| | - | operation, significance of back emf, torque equation and power de | | | | | |
| | | compound type motors, starting methods, speed control methods efficiency. Testing of DC Machines: Brake test, Swinburne's test | | • | | | |
| | | - applications of DC motors. | , mopkinson's test, r | Cetaruatio | m test, | Separa | |
| | T III | TRANSFORMER | | 9 | 0 | 0 | 9 |
| | | se transformer: Construction and principle of operation, work | ting of practical tra | | | | |
| - | - | ulation, losses and efficiency- testing : polarity test, open circuit | • • | | - | | |
| - | | parallel operation, applications. | | , | | , | 2 |
| Auto | transf | former: Construction and working, saving of copper - application | ns, Three phase tra | nsformer | : const | ructior | , types |
| of con | nnectio | ons and their comparative features. | | | | | |
| UNI | T IV | SYNCHRONOUS GENERATOR AND MOTOR | | 9 | 0 | 0 | 9 |
| Syncl | hrono | us Generator: Constructional and working details – Types of r | otors – EMF equation | on – Phas | sor diag | grams o | of non- |
| salien | nt pole | synchronous generator connected to infinite bus - Synchronizin | g and parallel opera | tion – Sy | nchron | izing t | orque - |
| Volta | ige reg | ulation – EMF, MMF and ZPF method – steady state power angle | e characteristics – T | wo reacti | on theo | ory – sl | ip test. |
| | | | | X 7 1 | T , | 1 3 7 | |
| - | | us Motor: Principle of operation – Torque equation – Operation | | | | | |
| | - | t and power developed equations – Starting methods – Current loc wer Developed -Hunting – natural frequency of oscillations – dar | - | - | | | on and |
| UNI | - | THREE PHASE AND SINGLE PHASE INDUCTION | | | | 0 | 9 |
| | | THREE THASE AND SINGLE THASE INDOCTION se induction motor: Constructional details – Types of rotors – Pr | | Fauival | Ŷ | - | - |
| | - | eristics - Condition for maximum torque – Losses and efficiency – | | - | | | - |
| - | | Separation of losses – Starters: DOL, Autotransformer and Star | | | | | |
| - | | quency control and pole changing $-V/f$ control $-$ Slip power reco | - | | | | |
| | | | 5 | | | | |
| Singl | e phas | se induction motor: Constructional details – Double field revolve | ing theory and opera | tion – Eq | uivaler | nt circu | it – No |
| load a | and blo | ocked rotor test - Performance analysis - Starting methods of sing | le-phase induction m | otors – sp | olit pha | se, Cap | acitor- |
| start, | capaci | itor start and capacitor run Induction motor. | | | | | |
| | | | To | otal (45L | 2+0T)= | = 45 P | eriods |
| | | | | | | | |
| Text | Book | XS: | | | | | |
| 1. | I. | J. Nagrath and D. P. Kothari, "Electric Machines", McGraw Hill | Education, 5th Editi | on, 2017 | | | |
| 2. | | S. Bimbhra, "Electric Machinery", Khanna Publishers, 2nd Editi | | | | | |
| | | L.Theraja and A.K.Theraja," A text book of Electrical Technolo | | Chand & | Compa | any Ltd | ., New |
| 3. | | elhi, 23 rd Edition, 2009. | | | - | | |

 Reference Books:

 1.
 B.R.Gupta, 'Fundamental of Electric Machines' New age International Publishers,3rd Edition, Reprint 2015.

| 2. | Murugesh Kumar, 'Electric Machines', Vikas Publishing House Pvt. Ltd, First edition, 2010. |
|----|---|
| 3. | A.E. Fitzgerald, Charles Kingsley, Stephen. D. Umans, 'Electric Machinery', Mc Graw Hill publishing Company Ltd, 6th Education, 2017. |
| 4. | Stephen J. Chapman, 'Electric Machinery Fundamentals'4th edition, McGraw Hill Education Pvt. Ltd, 4th Edition 2017. |

| Course (| Dute | comes: | Bloom's Taxonomy |
|----------|------|---|-------------------|
| Upon com | plet | ion of this course, the students will be able to: | Mapped |
| CO1 | : | Explain the construction and working principle of DC machines, and Interpret various characteristics of DC machines. | L2: Understanding |
| CO2 | : | Compute various performance parameters of the machine, by conducting suitable tests. | L5: Evaluating |
| CO3 | : | Describe the working principle of transformer, auto transformer, three phase transformer connection, and determine the efficiency and regulation. | L3: Applying |
| CO4 | : | Understand the construction and working principle of Synchronous Machines. | L3: Applying |
| CO5 | | Understand the construction and working principle, speed control of three phase and single phase induction motor. | L5: Evaluating |

| COs/ POs | PO 1 | PO 2 | PO 3 | РО 4 | PO 5 | PO 6 | PO 7 | PO 8 | PO 9 | PO 10 | PO 11 | PO 12 | PS O1 | PS O2 | PS O3 |
|-------------|---------|---------|---------|---------|---------|---------|---------|---------|---------|----------|----------|----------|----------|----------|----------|
| CO1 | 3 | 3 | 1 | 1 | 1 | | | 1 | | | | 1 | 3 | 2 | 1 |
| CO2 | 3 | 3 | 1 | 1 | 1 | | | 1 | | | | 1 | 3 | 2 | 1 |
| CO3 | 3 | 3 | 1 | 1 | 1 | | | 1 | | | | 1 | 3 | 2 | 1 |
| CO4 | 3 | 3 | 1 | 1 | 1 | | | 1 | | | | 1 | 3 | 2 | 1 |
| CO5 | 3 | 3 | 1 | 1 | 1 | | | 1 | | | | 1 | 3 | 2 | 1 |
| Avg. | 3 | 3 | 1 | 1 | 1 | - | - | 1 | - | - | - | 1 | 3 | 2 | 1 |

| C Machines and Transformers, Synchronous and Induction Machines, and over Electronics L T P T Owner Electronics 3 0 0 2 Course Objectives: | 18EEM06 | ELECTRICAL DRIVES AND CONTI | ROL | SEN | MEST | ER | |
|---|---------------|--|---------------------------------|-------------|---------|-----------|----------|
| Hours/Week 3 0 0 2 Course Objectives: | PREREQU | ISTIES | CATEGORY | PE | C | redit | 3 |
| Source Objectives: 3 0 0 3 1. To know about the operation analyse of chopper fed DC drive, both qualitatively and quantitatively. 2. To understand the operation and performance of AC motor drives. INIT I DC MOTOR CHARACTERISTICS & CHOPPER FED DC DRIVES 9 0 0 9 leview of torque-speed characteristics, operating point, armature voltage control for varying motor speed. Review of hopper and duty ratio control, chopper fed d motor for speed control, steady state operation of a chopper fed drive, armatur urrent waveform and ripple, calculation of losses in dc motor and chopper. 9 0 0 9 Veriew of Four quadrant operation of de machine; single-quadrant, two-quadrant and four-quadrant choppers; Control structu f DC drive, inner current loop and outer speed loop, dynamic model of de motor – dynamic equations and transfer function iodeling of chopper as gain with switching delay, plant transfer function, current controller specification and design. 9 0 0 9 INIT II INDUCTION MOTOR CHARACTERISTICS 9 0 0 9 0 0 9 veriew of induction motor equivalent circuit and torque-speed characteristic, variation of torque-speed curve with (i) applied oltage, (ii) applied voltage and frequency. Review of three-phase voltage source inverter, generati f three-phase PWM signals, constant V/f control of induction motor 9 0 0 9 | DC Machine | s and Transformers, Synchronous and Induction Machines, and | TT / TT / | L | Т | Р | TH |
| 1. To know about the operation analyse of chopper fed DC drive, both qualitatively and quantitatively. 2. To understand the operation and performance of AC motor drives. INIT I DC MOTOR CHARACTERISTICS & CHOPPER FED DC DRIVES 9 0 0 9 deview of torque-speed characteristics of separately excited dc motor, change in torque-speed curve with armature voltage control for varying motor speed. Review of hopper and duty ratio control, chopper fed dc motor for speed control, steady state operation of a chopper fed drive, armature rurent waveform and ripple, calculation of losses in dc motor and chopper. INIT II MULTI-QUADRANT & CLOSED-LOOP CONTROL OF DC DRIVE 9 0 0 9 teview of Four quadrant operation of dc machine; single-quadrant, two-quadrant and four-quadrant choppers; Control structur f DC drive, inner current loop and outer speed loop, dynamic model of dc motor – dynamic equations and transfer function todeling of chopper as gain with switching delay, plant transfer function, current controller specification and design. INIT II INDUCTION MOTOR CHARACTERISTICS 9 0 0 9 NIT II INDUCTION MOTOR CHARACTERISTICS 9 0 0 9 teview of induction motor equivalent circuit and torque-speed characteristic, variation of torque-speed curve with (i) appliol oltage, (ii) applied frequency and (iii) applied voltage and frequency. Review of three-phase voltage source inverter, generati f three-phase PWM signals, constant V/f control of induction motor VIT V CONTROL OF SLIP RING INDUCTION MOTOR REVES. 9 0 0 9 9 RM construction - Principle of operation - SRM drive design factors-Torque controlled SRM- Block diagram of Instantaneou or orque control | Power Electr | onics | Hours/ week | 3 | 0 | 0 | 3 |
| 2. To understand the operation and performance of AC motor drives. INIT I DC MOTOR CHARACTERISTICS & CHOPPER FED DC DRIVES 9 0 0 9 teview of torque-speed characteristics of separately excited dc motor, change in torque-speed curve with armature voltage control for varying motor speed. Review of hopper and duty ratio control, chopper fed dc motor for speed control, steady state operation of a chopper fed drive, armatu urrent waveform and ripple, calculation of losses in dc motor and chopper. INIT II MULTI-QUADRANT & CLOSED-LOOP CONTROL OF DC DRIVE 9 0 0 9 leview of Four quadrant operation of dc machine; single-quadrant, two-quadrant and four-quadrant choppers; Control structt f DC drive, inner current loop and outer speed loop, dynamic model of dc motor – dynamic equations and transfer function odeling of chopper as gain with switching delay, plant transfer function, current controller specification and design. INIT II INDUCTION MOTOR CHARACTERISTICS 9 0 0 9 leview of induction motor equivalent circuit and torque-speed curve with (i) applioltage, (ii) applied voltage and frequency. Review of three-phase voltage source inverter, generati f three-phase PVM signals, constant V/f control of induction motor 9 0 0 9 INIT IV CONTROL OF SLIP RING INDUCTION MOTOR 9 0 0 9 INIT IV CONTROL OF SRM AND BLDC MOTOR DRIVES. 9 | Course Ob | jectives: | | | | | • |
| INIT I DC MOTOR CHARACTERISTICS & CHOPPER FED DC DRIVES 9 0 0 9 teview of torque-speed characteristics of separately excited dc motor, change in torque-speed curve with armature voltag xample load torque-speed characteristics, operating point, armature voltage control for varying motor speed. Review of hopper and duty ratio control, chopper fed dc motor for speed control, steady state operation of a chopper fed drive, armature urrent waveform and ripple, calculation of losses in dc motor and chopper. 9 0 0 9 INIT II MULTI-QUADRANT & CLOSED-LOOP CONTROL OF DC DRIVE 9 0 0 9 teview of Four quadrant operation of dc machine; single-quadrant, two-quadrant and four-quadrant choppers; Control struction odeling of chopper as gain with switching delay, plant transfer function, current controller specification and design. 9 0 0 9 INIT II INDUCTION MOTOR CHARACTERISTICS 9 0 0 9 teview of induction motor equivalent circuit and torque-speed claracteristic, variation of torque-speed curve with (i) appliol applied frequency and (iii) applied voltage and frequency. Review of three-phase voltage source inverter, generati function motor 9 0 0 9 0 0 9 0 0 9 0 0 9 0 0 9 0 0 9 0 0 | 1. To kn | ow about the operation analyse of chopper fed DC drive, both qu | alitatively and quar | ntitativel | у. | | |
| Leview of torque-speed characteristics of separately excited dc motor, change in torque-speed curve with armature voltag xample load torque-speed characteristics, operating point, armature voltage control for varying motor speed. Review of hopper and duty ratio control, chopper fed dc motor for speed control, steady state operation of a chopper fed drive, armature transfer and ripple, calculation of losses in dc motor and chopper. INIT II MULTI-QUADRANT & CLOSED-LOOP CONTROL OF DC DRIVE 9 0 0 9 teview of Four quadrant operation of dc machine; single-quadrant, two-quadrant and four-quadrant choppers; Control struction f DC drive, inner current loop and outer speed loop, dynamic model of dc motor – dynamic equations and transfer function oncoleing of chopper as gain with switching delay, plant transfer function, current controller specification and design. INIT III INDUCTION MOTOR CHARACTERISTICS 9 0 0 9 teview of induction motor equivalent circuit and torque-speed curve, Review of three-phase voltage source inverter, generatif three-phase PWM signals, constant V/f control of induction motor 9 0 0 9 INIT IV CONTROL OF SLIP RING INDUCTION MOTOR 9 0 0 9 INIT IV CONTROL OF SLIP RING INDUCTION MOTOR 9 0 0 9 NIT IV CONTROL OF SLIP RING INDUCTION MOTOR 9 0 0 9 0 0 9 | 2. To un | derstand the operation and performance of AC motor drives. | | | - | | |
| xample load torque-speed characteristics, operating point, armature voltage control for varying motor speed. Review of hopper and duty ratio control, chopper fed dc motor for speed control, steady state operation of a chopper fed drive, armaturent waveform and ripple, calculation of losses in dc motor and chopper. INIT II MULTI-QUADRANT & CLOSED-LOOP CONTROL OF DC DRIVE 9 0 0 9 teview of Four quadrant operation of dc machine; single-quadrant, two-quadrant and four-quadrant choppers; Control structure f DC drive, inner current loop and outer speed loop, dynamic model of dc motor – dynamic equations and transfer function is oncelling of chopper as gain with switching delay, plant transfer function, current controller specification and design. INIT III INDUCTION MOTOR CHARACTERISTICS 9 0 0 9 teview of induction motor equivalent circuit and torque-speed characteristic, variation of torque-speed curve with (i) appliol oltage, (ii) applied frequency and (iii) applied voltage and frequency. Review of three-phase voltage source inverter, generati f three-phase PWM signals, constant V/f control of induction motor 9 0 0 9 INIT IV CONTROL OF SLIP RING INDUCTION MOTOR 9 0 0 9 INIT V CONTROL OF SLIP RING INDUCTION MOTOR 9 0 0 9 Review of or or resistance of the induction motor torque-speed curve, operation of slip-ring induction motor with external rocesistance, starting torque, power electronic based rotor side control of slip ring | UNIT I | DC MOTOR CHARACTERISTICS & CHOPPER FE | D DC DRIVES | 9 | 0 | 0 | 9 |
| xample load torque-speed characteristics, operating point, armature voltage control for varying motor speed. Review of hopper and duty ratio control, chopper fed dc motor for speed control, steady state operation of a chopper fed drive, armaturent waveform and ripple, calculation of losses in dc motor and chopper. INIT II MULTI-QUADRANT & CLOSED-LOOP CONTROL OF DC DRIVE 9 0 0 9 teview of Four quadrant operation of dc machine; single-quadrant, two-quadrant and four-quadrant choppers; Control structure f DC drive, inner current loop and outer speed loop, dynamic model of dc motor – dynamic equations and transfer function is oncelling of chopper as gain with switching delay, plant transfer function, current controller specification and design. INIT III INDUCTION MOTOR CHARACTERISTICS 9 0 0 9 teview of induction motor equivalent circuit and torque-speed characteristic, variation of torque-speed curve with (i) appliol oltage, (ii) applied frequency and (iii) applied voltage and frequency. Review of three-phase voltage source inverter, generati f three-phase PWM signals, constant V/f control of induction motor 9 0 0 9 INIT IV CONTROL OF SLIP RING INDUCTION MOTOR 9 0 0 9 INIT V CONTROL OF SLIP RING INDUCTION MOTOR 9 0 0 9 Review of or or resistance of the induction motor torque-speed curve, operation of slip-ring induction motor with external rocesistance, starting torque, power electronic based rotor side control of slip ring | Review of to | orque-speed characteristics of separately excited dc motor, chan | ge in torque-speed | curve w | ith arn | nature | voltage |
| hopper and duty ratio control, chopper fed dc motor for speed control, steady state operation of a chopper fed drive, armatu urrent waveform and ripple, calculation of losses in dc motor and chopper. INIT II MULTI-QUADRANT & CLOSED-LOOP CONTROL OF DC DRIVE 9 0 0 9 deview of Four quadrant operation of dc machine; single-quadrant, two-quadrant and four-quadrant choppers; Control structur f DC drive, inner current loop and outer speed loop, dynamic model of dc motor – dynamic equations and transfer function odeling of chopper as gain with switching delay, plant transfer function, current controller specification and design. INIT III INDUCTION MOTOR CHARACTERISTICS 9 0 0 9 teview of induction motor equivalent circuit and torque-speed characteristic, variation of torque-speed curve with (i) applie oltage, (ii) applied frequency and (iii) applied voltage and frequency. Review of three-phase voltage source inverter, generation f three-phase PWM signals, constant V/f control of induction motor INIT IV CONTROL OF SLIP RING INDUCTION MOTOR 9 0 0 9 mpact of rotor resistance of the induction motor torque-speed curve, operation of slip-ring induction motor with external ro sistance, starting torque, power electronic based rotor side control of slip ring motor, slip power recovery. INIT V CONTROL OF SRM AND BLDC MOTOR DRIVES. 9 0 0 9 RM construction - Principle of operation - SRM drive design factors-Torque controlled SRM- Block diagram of Instantaneou corque control using current controllers and flux controllers. Construction and Principle of operation of BLDC Machine ensing and logic switching scheme,-Sinusoidal and trapezoidal type of Brushless dc motors – Block diagram of curre ontrolled Brushless dc motor drive | | | 0 1 1 | | | | 0 |
| urrent waveform and ripple, calculation of losses in dc motor and chopper. INIT II MULTI-QUADRANT & CLOSED-LOOP CONTROL OF DC DRIVE 9 0 0 9 teview of Four quadrant operation of dc machine; single-quadrant, two-quadrant and four-quadrant choppers; Control structure f DC drive, inner current loop and outer speed loop, dynamic model of dc motor – dynamic equations and transfer function modeling of chopper as gain with switching delay, plant transfer function, current controller specification and design, speontroller specification and design. INIT III INDUCTION MOTOR CHARACTERISTICS 9 0 0 9 teview of induction motor equivalent circuit and torque-speed characteristic, variation of torque-speed curve with (i) appliol oltage, (ii) applied frequency and (iii) applied voltage and frequency. Review of three-phase voltage source inverter, generati f three-phase PWM signals, constant V/f control of induction motor 9 0 0 9 INIT IV CONTROL OF SLIP RING INDUCTION MOTOR 9 0 0 9 INIT V CONTROL OF SRM AND BLDC MOTOR DRIVES. 9 0 0 9 RM construction - Principle of operation - SRM drive design factors-Torque controlled SRM- Block diagram of Instantaneous 'orque control using current controllers and flux controllers. Construction and Principle of operation of BLDC Machine ensing and logic switching scheme,-Sinusoidal and trapezoidal type of Brushless dc motors – Block diagram of curree ontrolled Brushless dc motor d | - | | • | - | - | | |
| INIT II MULTI-QUADRANT & CLOSED-LOOP CONTROL OF DC DRIVE 9 0 0 9 teview of Four quadrant operation of dc machine; single-quadrant, two-quadrant and four-quadrant choppers; Control structing for the provided of | | • • • • • • | , | | | , | |
| teview of Four quadrant operation of dc machine; single-quadrant, two-quadrant and four-quadrant choppers; Control structul f DC drive, inner current loop and outer speed loop, dynamic model of dc motor – dynamic equations and transfer function modeling of chopper as gain with switching delay, plant transfer function, current controller specification and design. INIT III INDUCTION MOTOR CHARACTERISTICS 9 0 0 9 teview of induction motor equivalent circuit and torque-speed characteristic, variation of torque-speed curve with (i) applie oltage, (ii) applied frequency and (iii) applied voltage and frequency. Review of three-phase voltage source inverter, generati f three-phase PWM signals, constant V/f control of induction motor 9 0 0 9 INIT IV CONTROL OF SLIP RING INDUCTION MOTOR 9 0 0 9 INIT V CONTROL OF SLIP RING INDUCTION MOTOR 9 0 0 9 INIT V CONTROL OF SLIP RING INDUCTION MOTOR 9 0 0 9 INIT V CONTROL OF SRM AND BLDC MOTOR DRIVES. 9 0 0 9 INIT V CONTROL OF SRM AND BLDC MOTOR DRIVES. 9 0 0 9 RM construction - Principle of operation - SRM drive design factors-Torque controlled SRM- Block diagram of Instantaneou forque control using current controllers and flux controllers. Construction and Principle of operation of | | | OF DC DRIVE | 9 | 0 | 0 | 9 |
| f DC drive, inner current loop and outer speed loop, dynamic model of dc motor – dynamic equations and transfer function odeling of chopper as gain with switching delay, plant transfer function, current controller specification and design, spectration of chopper as gain with switching delay, plant transfer function, current controller specification and design. INIT III INDUCTION MOTOR CHARACTERISTICS 9 0 0 9 Induction motor equivalent circuit and torque-speed characteristic, variation of torque-speed curve with (i) applie oltage, (ii) applied frequency and (iii) applied voltage and frequency. Review of three-phase voltage source inverter, generating three-phase PWM signals, constant V/f control of induction motor 9 0 0 9 INIT IV CONTROL OF SLIP RING INDUCTION MOTOR 9 0 0 9 INIT V CONTROL OF SLIP RING INDUCTION MOTOR 9 0 0 9 INIT V CONTROL OF SRM AND BLDC MOTOR DRIVES. 9 0 0 9 RM construction - Principle of operation - SRM drive design factors-Torque controlled SRM- Block diagram of Instantaneous orque control using current controllers and flux controllers. Construction and Principle of operation of BLDC Machine ensing and logic switching scheme,-Sinusoidal and trapezoidal type of Brushless dc motors – Block diagram of curre ontrolled Brushless dc motor drive | | | | - | | - | - |
| nodeling of chopper as gain with switching delay, plant transfer function, current controller specification and design, specification and design. JNIT III INDUCTION MOTOR CHARACTERISTICS 9 0 0 9 teview of induction motor equivalent circuit and torque-speed characteristic, variation of torque-speed curve with (i) applie oltage, (ii) applied frequency and (iii) applied voltage and frequency. Review of three-phase voltage source inverter, generatient for three-phase PWM signals, constant V/f control of induction motor 9 0 0 9 INIT IV CONTROL OF SLIP RING INDUCTION MOTOR 9 0 0 9 mpact of rotor resistance of the induction motor torque-speed curve, operation of slip ring induction motor with external rotesistance, starting torque, power electronic based rotor side control of slip ring motor, slip power recovery. JNIT V CONTROL OF SRM AND BLDC MOTOR DRIVES. 9 0 0 9 INT V CONTROL OF SRM AND BLDC MOTOR DRIVES. 9 0 0 9 RM construction - Principle of operation - SRM drive design factors-Torque controlled SRM- Block diagram of Instantaneou Corque control using current controllers and flux controllers. Construction and Principle of operation of BLDC Machine ensing and logic switching scheme,-Sinusoidal and trapezoidal type of Brushless dc motors – Block diagram of curre ontrolled Brushless dc motor drive | | | - | | | | |
| ontroller specification and design. JNTT III INDUCTION MOTOR CHARACTERISTICS 9 0 0 9 teview of induction motor equivalent circuit and torque-speed characteristic, variation of torque-speed curve with (i) applie oltage, (ii) applied frequency and (iii) applied voltage and frequency. Review of three-phase voltage source inverter, generatif f three-phase PWM signals, constant V/f control of induction motor 9 0 0 9 INIT IV CONTROL OF SLIP RING INDUCTION MOTOR 9 0 0 9 INIT V CONTROL OF SLIP RING INDUCTION MOTOR 9 0 0 9 mpact of rotor resistance of the induction motor torque-speed curve, operation of slip-ring induction motor with external rocesistance, starting torque, power electronic based rotor side control of slip ring motor, slip power recovery. JNIT V CONTROL OF SRM AND BLDC MOTOR DRIVES. 9 0 0 9 RM construction - Principle of operation - SRM drive design factors-Torque controlled SRM- Block diagram of Instantaneou Corque control using current controllers and flux controllers. Construction and Principle of operation of BLDC Machine ensing and logic switching scheme,-Sinusoidal and trapezoidal type of Brushless dc motors – Block diagram of curre ontrolled Brushless dc motor drive Total (45L+0T)= 45 Period | | | • 1 | | | | |
| INIT III INDUCTION MOTOR CHARACTERISTICS 9 0 0 9 Leview of induction motor equivalent circuit and torque-speed characteristic, variation of torque-speed curve with (i) applie oltage, (ii) applied frequency and (iii) applied voltage and frequency. Review of three-phase voltage source inverter, generating f three-phase PWM signals, constant V/f control of induction motor 9 0 0 9 INIT IV CONTROL OF SLIP RING INDUCTION MOTOR 9 0 0 9 Impact of rotor resistance of the induction motor torque-speed curve, operation of slip-ring induction motor with external rosesistance, starting torque, power electronic based rotor side control of slip ring motor, slip power recovery. Impact Of Operation - SRM AND BLDC MOTOR DRIVES. 9 0 0 9 RM construction - Principle of operation - SRM drive design factors-Torque controlled SRM- Block diagram of Instantaneor or orque control using current controllers and flux controllers. Construction and Principle of operation of BLDC Machine ensing and logic switching scheme,-Sinusoidal and trapezoidal type of Brushless dc motors – Block diagram of curre ontrolled Brushless dc motor drive Total (45L+0T)= 45 Periodet Control of control using current controllers and flux controllers. Construction and Principle of operation of BLDC Machine ensing and logic switching scheme,-Sinusoidal and trapezoidal type of Brushles | - | | unent controller s _f | cemean | | uesign | i, speci |
| teview of induction motor equivalent circuit and torque-speed characteristic, variation of torque-speed curve with (i) applied oltage, (ii) applied frequency and (iii) applied voltage and frequency. Review of three-phase voltage source inverter, generating f three-phase PWM signals, constant V/f control of induction motor JNIT IV CONTROL OF SLIP RING INDUCTION MOTOR 9 0 0 9 mpact of rotor resistance of the induction motor torque-speed curve, operation of slip-ring induction motor with external rotesistance, starting torque, power electronic based rotor side control of slip ring motor, slip power recovery. JNIT V CONTROL OF SRM AND BLDC MOTOR DRIVES. 9 0 0 9 RM construction - Principle of operation - SRM drive design factors-Torque controlled SRM- Block diagram of Instantaneous forque control using current controllers and flux controllers. Construction and Principle of operation of BLDC Machine ensing and logic switching scheme,-Sinusoidal and trapezoidal type of Brushless dc motors – Block diagram of curre ontrolled Brushless dc motor drive Total (45L+0T)= 45 Period | | | | 0 | 0 | Δ | 0 |
| oltage, (ii) applied frequency and (iii) applied voltage and frequency. Review of three-phase voltage source inverter, generating f three-phase PWM signals, constant V/f control of induction motor INIT IV CONTROL OF SLIP RING INDUCTION MOTOR 9 0 0 9 Impact of rotor resistance of the induction motor torque-speed curve, operation of slip-ring induction motor with external rotesistance, starting torque, power electronic based rotor side control of slip ring motor, slip power recovery. 9 0 0 9 INIT V CONTROL OF SRM AND BLDC MOTOR DRIVES. 9 0 0 9 RM construction - Principle of operation - SRM drive design factors-Torque controlled SRM- Block diagram of Instantaneous orque control using current controllers and flux controllers. Construction and Principle of operation of BLDC Machine ensing and logic switching scheme,-Sinusoidal and trapezoidal type of Brushless dc motors – Block diagram of curre ontrolled Brushless dc motor drive Total (45L+0T)= 45 Period | | | variation of tanga | - | | | - |
| f three-phase PWM signals, constant V/f control of induction motor INIT IV CONTROL OF SLIP RING INDUCTION MOTOR 9 0 0 9 mpact of rotor resistance of the induction motor torque-speed curve, operation of slip-ring induction motor with external rotesistance, starting torque, power electronic based rotor side control of slip ring motor, slip power recovery. 9 0 0 9 INIT V CONTROL OF SRM AND BLDC MOTOR DRIVES. 9 0 0 9 RM construction - Principle of operation - SRM drive design factors-Torque controlled SRM- Block diagram of Instantaneous or orque control using current controllers and flux controllers. Construction and Principle of operation of BLDC Machine ensing and logic switching scheme,-Sinusoidal and trapezoidal type of Brushless dc motors – Block diagram of curre ontrolled Brushless dc motor drive Total (45L+0T)= 45 Period | | | - | - | | | |
| INIT IV CONTROL OF SLIP RING INDUCTION MOTOR 9 0 0 9 mpact of rotor resistance of the induction motor torque-speed curve, operation of slip-ring induction motor with external rotesistance, starting torque, power electronic based rotor side control of slip ring motor, slip power recovery. 9 0 0 9 INIT V CONTROL OF SRM AND BLDC MOTOR DRIVES. 9 0 0 9 INIT V CONTROL OF SRM AND BLDC MOTOR DRIVES. 9 0 0 9 RM construction - Principle of operation - SRM drive design factors-Torque controlled SRM- Block diagram of Instantaneous orque control using current controllers and flux controllers. Construction and Principle of operation of BLDC Machine ensing and logic switching scheme,-Sinusoidal and trapezoidal type of Brushless dc motors – Block diagram of curre ontrolled Brushless dc motor drive Total (45L+0T)= 45 Periode Controlled State (45L+0T) | • | | of three-phase volta | age sourc | e inve | rter, gei | ieratio |
| mpact of rotor resistance of the induction motor torque-speed curve, operation of slip-ring induction motor with external rotesistance, starting torque, power electronic based rotor side control of slip ring motor, slip power recovery. JNIT V CONTROL OF SRM AND BLDC MOTOR DRIVES. 9 0 0 9 RM construction - Principle of operation - SRM drive design factors-Torque controlled SRM- Block diagram of Instantaneous 'orque control using current controllers and flux controllers. Construction and Principle of operation of BLDC Machine ensing and logic switching scheme,-Sinusoidal and trapezoidal type of Brushless dc motors – Block diagram of curre ontrolled Brushless dc motor drive Total (45L+0T)= 45 Period | | | | | 0 | 0 | |
| esistance, starting torque, power electronic based rotor side control of slip ring motor, slip power recovery JNIT V CONTROL OF SRM AND BLDC MOTOR DRIVES. 9 0 0 9 RM construction - Principle of operation - SRM drive design factors-Torque controlled SRM- Block diagram of Instantaneous orque control using current controllers and flux controllers. Construction and Principle of operation of BLDC Machine ensing and logic switching scheme,-Sinusoidal and trapezoidal type of Brushless dc motors – Block diagram of curre ontrolledd Brushless dc motor drive Total (45L+0T)= 45 Perio | | | | - | - | - | - |
| JNIT V CONTROL OF SRM AND BLDC MOTOR DRIVES. 9 0 0 9 RM construction - Principle of operation - SRM drive design factors-Torque controlled SRM- Block diagram of Instantaneor Orque control using current controllers and flux controllers. Construction and Principle of operation of BLDC Machine ensing and logic switching scheme,-Sinusoidal and trapezoidal type of Brushless dc motors – Block diagram of curre ontrolled Brushless dc motor drive Total (45L+0T)= 45 Perior | - | • • • | | | | 1 extern | al roto |
| RM construction - Principle of operation - SRM drive design factors-Torque controlled SRM- Block diagram of Instantaneous orque control using current controllers and flux controllers. Construction and Principle of operation of BLDC Machine ensing and logic switching scheme,-Sinusoidal and trapezoidal type of Brushless dc motors – Block diagram of curre ontrolledd Brushless dc motor drive Total (45L+0T)= 45 Perio | | | ng motor, slip powe | r recover | у | - | 1 |
| Yorque control using current controllers and flux controllers. Construction and Principle of operation of BLDC Machine ensing and logic switching scheme,-Sinusoidal and trapezoidal type of Brushless dc motors – Block diagram of curre ontrolledd Brushless dc motor drive Total (45L+0T)= 45 Perio | UNIT V | CONTROL OF SRM AND BLDC MOTOR DRIVES. | | 9 | 0 | 0 | 9 |
| ensing and logic switching scheme,-Sinusoidal and trapezoidal type of Brushless dc motors – Block diagram of curre ontrolledd Brushless dc motor drive Total (45L+0T)= 45 Perio | SRM constru | ction - Principle of operation - SRM drive design factors-Torque | controlled SRM-B | lock diag | ram of | Instant | aneous |
| ontrolledd Brushless dc motor drive Total (45L+0T)= 45 Perio | Torque contr | rol using current controllers and flux controllers. Construction | and Principle of op | peration of | of BLI | DC Ma | chine |
| Total (45L+0T)= 45 Perio | Sensing and | logic switching scheme,-Sinusoidal and trapezoidal type of B | rushless dc motors | - Block | diagr | am of | curren |
| | controlledd I | Brushless dc motor drive | | | | | |
| Text Books: | | | Te | otal (451 | L+0T) | = 45 P | Period |
| Text Books: | | | | | | | |
| Yext Books: | | | | | | | |
| | Text Books | | | | | | |

| 1. | G. K. Dubey, "Power Semiconductor Controlled Drives", Prentice Hall, 1989. |
|--------|--|
| 2. | R. Krishnan, "Electric Motor Drives: Modeling, Analysis and Control", Prentice Hall,2010 |
| 3. | Bose B K, "Modern Power Electronics and AC Drives", Pearson Education New Delhi, 2010. |
| Refere | nce Books: |
| 1. | G. K. Dubey, "Fundamentals of Electrical Drives", CRC Press, 2012. |
| 2. | W. Leonhard, "Control of Electric Drives", Springer Science & Business Media, 2001. |
| E-Refe | erence |
| 1 | https://www.iith.ac.in/~ketan/drives.htmL |

| Course (|)uto | comes: | Bloom's Taxonomy |
|----------|------|--|-------------------|
| Upon com | plet | ion of this course, the students will be able to: | Mapped |
| CO1 | : | Understand the characteristics of dc motors and induction motors. | L2: Understanding |
| CO2 | : | Summarize the operation of chopper fed DC drives. | L4: Analyzing |
| CO3 | : | Understand the principles of speed-control of dc motors and induction motors. | L2: Understanding |
| CO4 | : | Identify suitable power electronic converters used for dc motor and induction motor speed control. | L3: Applying |

| COUR | SE AR | TICUI | LATIO | N MA | TRIX | | | | | | | | | | |
|-------------|---------|---------|----------|----------|---------|----------|----------|---------|---------|----------|----------|----------|----------|----------|----------|
| COs/ POs | PO 1 | PO 2 | PO 3 | PO 4 | РО 5 | PO 6 | PO 7 | PO 8 | PO 9 | PO 10 | PO 11 | PO 12 | PS O1 | PS O2 | PS 03 |
| CO1 | 3 | 1 | 3 | | | 1 | 1 | | | | | 1 | 3 | 2 | |
| CO2 | 3 | 3 | 1 | 3 | | 1 | 1 | | | | | 1 | 3 | 2 | |
| CO3 | 3 | 3 | 3 | 3 | 1 | 1 | 1 | | | | | 1 | 3 | 2 | |
| CO4 | 1 | 3 | 3 | 2 | 1 | 1 | 1 | | | | | 1 | 3 | 2 | |
| CO5 | 3 | 3 | 3 | 3 | 1 | 1 | 1 | | | | | 1 | 3 | 2 | |
| Avg. | 2.6 | 2.6 | 2.6 | 2.75 | 1 | 1 | 1 | - | - | - | - | 1 | 3 | 2 | - |
| | | | 3/2/1-ii | ndicates | strengt | h of cor | relation | (3- Hig | h, 2-Me | dium, 1 | - Low) | 1 | 1 | 1 | J |

| 18E | EM07 | ELECTRIC VEHICLES AND CONTRO | L | SEM | ESTI | ER | | | |
|---|---|--|-----------------------|----------|--------------|--------|---------|--|--|
| PRE | REQU | ISTIES | CATEGORY | PE | Cre | dit | 3 | | |
| El a ata | | | Houng/Wools | L | Т | Р | TH | | |
| Electr | | les and control | Hours/ week | 3 | 0 | 0 | 3 | | |
| Cour | se Obj | ectives: | | | | | | | |
| 1. | To pro | vide knowledge on electric vehicle architecture and its configuration | IS | | | | | | |
| 2. | To imp | part knowledge on vehicle control, use of energy storage systems and | l energy management | in Ele | ctric V | /ehicl | e | | |
| Electrical drives and control Hours/Week L T P TI Electrical drives and control Image: Strate Strat | | | | | 9 | | | | |
| Confi | Configurations of Electric Vehicles (EV), Performance of Electric Vehicles, Tractive Effort in Normal Driving and Energy Consumption, Hybrid Electric Vehicles (HEV): Classification, Series Hybrid Electric Drive Trains, Parallel Hybrid Electric | | | | | | | | |
| Consu | umption, | , Hybrid Electric Vehicles (HEV): Classification, Series Hybrid El | ectric Drive Trains, | Paralle | l Hyb | rid El | ectric | | |
| Drive | Trains | | | | | | | | |
| TINIT | гп | PLUG-IN HYBRID ELECTRICVEHICLES (PHEV) A | ND FUEL CELL | 0 | 0 | • | 0 | | |
| UNI | 1 11 | ELECTRIC VEHICLES | | 9 | U | U | 9 | | |
| Funct | ions and | Benefits of PHEV, Components of PHEVs, Operating Principles of | f Plug-in Hybrid Veh | icle, Co | ontrol | Strate | egy of | | |
| PHEV | /, Fuel C | Cell: Operation and Types, Fuel Cell Electric Vehicle: Configuration | and Control Strategy | 7 | | | | | |
| UNI | ГШ | ELECTRIC PROPULSION SYSTEMS | | 9 | 0 | 0 | 9 | | |
| Typic | al electr | ic propulsion system, Classification of electric motor drives for EV a | and HEV, Multiquadr | ant Co | ntrol o | of Cho | pper- | | |
| Fed D | C Moto | r Drives, Vector Control of Induction Motor drives, Permanent Mag | netic Brush-Less DC | Motor | Drive | s, Sw | itched | | |
| Reluc | tance M | | | | | | | | |
| UNI | ΓIV | ENERGY STORAGE SYSTEM | | 9 | 0 | 0 | 9 | | |
| Status | s of Bat | tery Systems for Automotive Applications, Battery Technologies | s: Nickel–Metal Hyd | lride (l | Ni-M | H) Ba | attery, | | |
| Lithiu | m–Poly | mer (Li-P) Battery, Lithium-Ion (Li-Ion) Battery, Ultracapacit | ors: Features, opera | ation a | nd pe | erforn | nance, | | |
| Ultrah | nigh-Spe | ed Flywheels, Hybridization of Energy Storages | | | | | | | |
| UNI | ΓV | ENERGY MANAGEMENT SYSTEM | | 9 | 0 | 0 | 9 | | |
| Energ | y Mana | gement System(EMS) in Electric Vehicle, Rule-based control strat | egy: Deterministic ru | le-base | ed cor | ntrol, | Fuzzy | | |
| logic- | based c | control, and Neural network-based control. Optimization based | control strategy: I | Dynami | c Pro | ogram | ming, | | |
| | | | e Hybrid Energy Stor | age Sys | stem- | based | EMS, | | |
| Fully- | active ty | ype Hybrid Energy Storage System-based EMS | | | | | | | |
| | | | Total (4 | 45L+0 | T)= 4 | 15 Pe | riods | | |

| Text E | Books: |
|--------|--|
| 1. | Iqbal Hussain, "Electric and Hybrid Vehicles: Design Fundamentals", CRC Press, Taylor & Francis Group, Second |
| 1. | Edition ,2011. |
| 2. | Mehrdad Ehsani, Yimin Gao, Sebastien E. Gay, AliEmadi,, "Modern Electric, Hybrid Electric, and Fuel Cell Vehicles" |
| 2. | CRC Press, 2016 |
| Refere | ence Books: |
| 1 | Ali Emadi, Mehrdad Ehsani, John M.Miller, "Vehicular Electric Power Systems", Ali Emadi, Mehrdad Ehsani, John |
| 1. | M.Miller, Special Indian Edition, Marcel dekker, Inc 2010 |
| E-Ref | erence: |
| 1 | https://archive.nptel.ac.in/courses/108/106/108106170/ |

| Course | e Oi | itcomes: | Bloom's Taxonomy | | | | | |
|---------|------|--|------------------|--|--|--|--|--|
| Upon co | omp | letion of this course, the students will be able to: | Mapped | | | | | |
| CO1 | : | Recall the fundamentals of electric vehicle and its mechanics | L1: Remembering | | | | | |
| CO2 | : | Explain the architecture of different forms of hybrid electric vehicles. L2: Understanding | | | | | | |
| CO3 | : | Illustrate the four-quadrant operation of DC drive, induction motor drive and SRM drive for Electric Vehicles. | L4: Analyzing | | | | | |
| CO4 | : | Select an appropriate energy storage system for Electric vehicle | L4: Analyzing | | | | | |
| CO5 | : | Use the suitable energy management control strategy for hybrid electric vehicle L3: Applying | | | | | | |

| COUR | SE AR | TICUI | LATIO | N MA' | TRIX | | | | | | | | | | |
|-------------|---------|---------|----------|----------|----------|----------|----------|---------|---------|----------|----------|----------|----------|----------|----------|
| COs/ POs | PO 1 | PO 2 | PO 3 | PO 4 | PO 5 | PO 6 | PO 7 | PO 8 | PO 9 | PO 10 | PO 11 | PO 12 | PS O1 | PS O2 | PS 03 |
| CO1 | 1 | | 1 | 3 | 1 | | 1 | | | | | 1 | 1 | 2 | 1 |
| CO2 | 1 | 2 | 3 | 1 | | | 2 | | | | | 2 | 1 | 2 | |
| CO3 | 1 | 1 | | | 2 | | 3 | | | | | | 1 | 1 | 1 |
| CO4 | 3 | 1 | 2 | 1 | 2 | | 1 | | | | | 2 | 1 | 2 | 1 |
| CO5 | 1 | 2 | 1 | 2 | 1 | | | | | | | 1 | 1 | 2 | 1 |
| Avg | 1.4 | 1.5 | 1.75 | 1.75 | 1.5 | - | 1.75 | - | - | - | - | 1.5 | 1 | 1.8 | 1 |
| | | • | 3/2/1-ir | ndicates | strengtl | n of cor | relation | (3- Hig | h, 2-Me | dium, 1 | - Low) | | | • | |

| 18EEM08 | ELECTRICAL ENERGY CONSERVATION AN | D AUDITING | SEN | 1ESTI | | |
|------------------|--|------------------------|-------------|----------|----------|---------|
| PREREQUI | SITES | CATEGORY | PE | Cre | edit | 3 |
| D G | | TT (TT) | L | Т | Р | TH |
| Power Gener | ation, Transmission and Distribution System | Hours/Week | 3 | 0 | 0 | 3 |
| Course Obje | ectives: | | | | | |
| 1. To get k | knowledge about basics of energy and energy scenario of India. | | | | | |
| | liarise the energy conservation methods. | | | | | |
| 3. To acqu | ire knowledge on energy auditing, energy efficiency and mode | ern energy efficient o | levices. | | | |
| UNIT I | ENERGY SCENARIO | | 9 | 0 | 0 | 9 |
| Commercial a | nd non-commercial energy -Primary energy resources - C | Commercial energy | producti | on - F | 'inal e | nergy |
| consumption - | Energy needs of growing economy - Long term energy scen | ario - Energy pricin | ig - Energ | gy sect | or refo | rms - |
| Energy and en | vironment - Energy security - Energy conservation and its import | rtance - Restructurin | g of the e | nergy s | upply s | sector |
| - Energy strate | gy for the future, air pollution, climate change. Energy Conser | vation Act-2001 and | l its featu | res. | | |
| UNIT II | BASICS OF ENERGY | | 9 | 0 | 0 | 9 |
| Electricity tari | ff - Load management and maximum demand control - Therma | al Basics-fuels - The | rmal ener | gy cont | ents of | f fuel, |
| temperature an | d pressure, heat capacity, sensible and latent heat, evaporation | , condensation, stear | m, moist | air and | humid | lity & |
| heat transfer, u | inits and conversion. | | | | | |
| UNIT III | ENERGY MANAGEMENT AND AUDIT | | 9 | 0 | 0 | 9 |
| Definition - Er | nergy audit – Need and types of energy audit. Energy managem | nent (audit) approach | understa | nding | energy | costs |
| - Bench marki | ng - Energy performance - Matching energy use to requiremen | t - Maximizing syste | em efficie | encies - | Optin | nizing |
| the input energ | gy requirements, fuel and energy substitution - Energy audit in | struments. Material | and energ | gy bala | nce: Fa | acility |
| as an energy sy | stem - Methods for preparing process flow, material and energy | gy balance diagrams | • | | | |
| UNIT IV | ENERGY EFFICIENCY | | 9 | 0 | 0 | 9 |
| Electrical syste | em: Electricity billing - Electrical load management and maxim | num demand control | -Power f | actor in | nprove | ement |
| and its benefit | - Selection and location of capacitors - Performance assessme | nt of PF capacitors, | distributi | on and | transfo | ormer |
| losses. Electri | c motors: Types - Losses in induction motors - Motor effic | eiency - Factors affe | ecting me | otor pe | rforma | nce - |
| Rewinding and | 1 motor replacement issues - Energy saving opportunities with | energy efficient mot | ors. | | | |
| UNIT V | | 9 | 0 | 0 | 9 | |
| Maximum den | nand controllers - Automatic power factor controllers - Energy | efficient motors -So | oft starter | s with e | energy | saver |
| | ed drives - Energy efficient transformers - Electronic ballast | - Occupancy sensor | s - Energ | v effic | ient lic | hting |
| - Variable spe | | | 6 | , on the | ionic ng | |
| - | gy saving potential of each technology. | i i i j | | y enne | ient ng | ,B |

| Text | Books: | | | | | | | | | |
|------|--|--|--|--|--|--|--|--|--|--|
| 1. | Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2015. | | | | | | | | | |
| 2, | Tripathy, S. C, "Utilization of Electrical Energy and Conservation", McGraw Hill, 1991. | | | | | | | | | |
| 3. | Hossam A Gabbar, "Energy Conservation in Infrastructure Systems", Wiley-IEEE Press, New Jersey, 2018 | | | | | | | | | |
| Refe | erence Books: | | | | | | | | | |
| 1. | General Aspects of Energy Management and Energy Audit, Bureau of Energy Efficiency, New Delhi, 2015. | | | | | | | | | |
| 2, | 2, Energy Efficiency in Electrical Utilities, Bureau of Energy Efficiency, New Delhi, 2015. | | | | | | | | | |

| Course | e Outcomes: | Bloom's Taxonomy |
|---------|--|-------------------|
| Upon co | ompletion of this course, the students will be able to: | Mapped |
| CO1 | Identify the present energy scenario and future energy strategy. | L1: Understanding |
| CO2 | Recognize the various forms of energy. | L1: Understanding |
| CO3 | Interpret energy management methods and energy auditing. | L3: Applying |
| CO4 | Familiar in energy efficiency of electrical systems. | L4: Analysing |
| CO5 | Familiar with the advanced energy efficient technologies. | L4: Analysing |

| COUR | SE AR | TICU | LATIO | ON MA | TRIX | | | | | | | | | | |
|-------------|---------|---------|---------|----------------|------------|---------|----------|-----------|----------|----------|----------|----------|----------|----------|----------|
| COs/ POs | PO 1 | PO 2 | PO 3 | PO 4 | PO 5 | PO 6 | PO 7 | PO 8 | PO 9 | PO 10 | PO 11 | PO 12 | PS O1 | PS O2 | PS O3 |
| CO1 | 1 | 2 | 3 | 2 | 2 | | 3 | | | | | 1 | 2 | 2 | 1 |
| CO2 | 1 | 2 | 2 | 2 | 2 | | 3 | | | | | 1 | 2 | 2 | 1 |
| CO3 | 2 | 2 | 2 | 3 | 2 | | 3 | | | | | 1 | 1 | 3 | 1 |
| CO4 | 2 | 3 | 2 | 2 | 3 | | 3 | | | | | 1 | 3 | 3 | 1 |
| CO5 | 2 | 2 | 3 | 1 | 2 | | 3 | | | | | 1 | 3 | 2 | 1 |
| Avg | 1.6 | 2.2 | 2.4 | 2 | 2.2 | - | 3 | - | - | - | - | 1 | 2.2 | 2.4 | 1 |
| | | | 3/2/ | 1-indica | ites strei | ngth of | correlat | ion (3- 1 | High, 2- | Mediur | n, 1- Lo | w) | | | |

| 18E | EM09 | SMPS AND UPS | | SEN | MEST | ER | |
|------------|-----------|---|-------------------------|-------------|----------------|-----------|---------|
| PREF | REQUI | SITES | CATEGORY | PE | C | redit | 3 |
| D | | | | L | Т | P | TH |
| Power | Electro | nics | Hours/Week | 3 | 0 | 0 | 3 |
| Cours | se Obje | ectives: | | · | | - | • |
| 1. | To imp | art knowledge about modern power electronic converters and | their applications in | power uti | lity. | | |
| 2. | To imp | art knowledge about Resonant converters and UPS. | | | | | |
| UNIT | I | DC-DC CONVERTERS | | 9 | 0 | 0 | 9 |
| Introdu | uction to | o SMPS - Non-isolated DC-DC converters: Cuk, SEPIC t | topologies, Z-source | converter | r – Ze | ta conv | erter - |
| Analys | sis and s | state space modeling Concept of volt-second and charge ba | alance – High gain in | put-paral | lel out | put-seri | es DC- |
| DC con | nverter. | | | | | | |
| UNIT | II | SWITCHED MODE POWER CONVERTERS | | 9 | 0 | 0 | 9 |
| Isolate | d DC-D | C converters: Analysis and state space modelling of fly back, | Forward, Push pull, L | uo, Half t | oridge | and full | bridge |
| conver | rters- co | ntrol circuits and PWM techniques - Bidirectional DC-DC co | onverters. | | | | |
| UNIT | III | RESONANT CONVERTERS | | 9 | 0 | 0 | 9 |
| Introdu | uction- | classification- basic concepts- Resonant switch- Load Reson | ant converters- ZVS, | Clampeo | l volta | ge topo | logies- |
| DC lin | ık invert | ers with Zero Voltage Switching- Series and parallel Resonan | nt inverters- Voltage o | control. | | | |
| UNIT | IV | DC-AC CONVERTERS | | 9 | 0 | 0 | 9 |
| Introdu | uction – | Multilevel concept - Types of multilevel inverters - Diode- | clamped MLI – Flyin | g capacit | ors M | LI – Ca | scaded |
| MLI – | Cascad | ed MLI - Applications - Switching device currents - DC lin | nk capacitor voltage b | alancing | – Feat | ures of | MLI – |
| Compa | arisons o | of MLI. | | | | | |
| UNIT | V | POWER CONDITIONERS, UPS, AND FILTERS | | 9 | 0 | 0 | 9 |
| Introdu | uction- | Power line disturbances- Power conditioners -UPS: offline | UPS, Online UPS, A | pplication | ns – F | ilters: V | oltage |
| filters, | Series- | parallel resonant filters, filter without series capacitors, filter | for PWM VSI, curren | t filter, D | C filte | ers – De | sign of |
| inducto | or and ti | ransformer for power electronic applications - Selection of ca | apacitors. | | | | |
| | | | To | otal (45L | -+ 0 T) | = 45 Pe | eriods |

| Text I | Books: | | | | | | | | | |
|------------------|---|--|--|--|--|--|--|--|--|--|
| 1. | Simon Ang, Alejandro Oliva," Power-Switching Converters", Third Edition, CRC Press, 2010. | | | | | | | | | |
| 2. | M.H. Rashid – Power Electronics handbook, Elsevier Publication, 2001. | | | | | | | | | |
| Reference Books: | | | | | | | | | | |
| 1. | Ned Mohan, Tore.M.Undeland, William.P.Robbins, "Power Electronics Converters, Applications and Design", 3rd | | | | | | | | | |
| 1. | Edition, John Wiley and Sons, 2006. | | | | | | | | | |
| 2. | M.H. Rashid, "Power Electronics circuits, devices and applications", 3 rd Edition, PHI, New Delhi, 2007. | | | | | | | | | |
| E-Ref | erences: | | | | | | | | | |
| 1. | NPTEL Course: Power Electronics, IIT-B. | | | | | | | | | |
| 2. | www.cdeep.iitb.ac.in. (Electrical Engineering) | | | | | | | | | |

| Course (|)uto | comes: | Bloom's Taxonomy | | |
|----------|------|--|-------------------|--|--|
| Upon com | plet | Mapped | | | |
| CO1 | : | Analyze the state space model for DC – DC converters. | L4: Analyzing | | |
| CO2 | : | Acquire knowledge on switched mode power converters. | L2: Understanding | | |
| CO3 | : | Outline the PWM techniques for DC-AC converters. | L1: Remembering | | |
| CO4 | : | Discuss about modern power electronic converters and its applications in electric power utility. | L2: Understanding | | |
| CO5 | : | Identify the filters and UPS. | L2: Understanding | | |

| COUR | COURSE ARTICULATION MATRIX | | | | | | | | | | | | | | |
|-------------|----------------------------|---------|---------|----------|---------|----------|----------|---------|----------|----------|----------|----------|----------|----------|----------|
| COs/ POs | PO 1 | PO 2 | PO 3 | PO 4 | PO 5 | PO 6 | PO 7 | PO 8 | PO 9 | PO 10 | PO 11 | PO 12 | PS O1 | PS O2 | PS 03 |
| CO1 | 2 | 1 | 2 | 2 | | | 1 | | | | | 2 | 2 | 2 | 1 |
| CO2 | 1 | 1 | 3 | 2 | | | 1 | | | | | 2 | 3 | 3 | 2 |
| CO3 | 2 | 2 | 2 | 3 | | | 1 | | | | | 1 | 2 | 2 | 1 |
| CO4 | 2 | 1 | 1 | 2 | | | 1 | | | | | 2 | 2 | 3 | 2 |
| CO5 | 1 | 1 | 2 | 1 | | | 1 | | | | | 1 | 2 | 2 | 1 |
| Avg. | 1.6 | 1.2 | 2 | 2 | - | - | 1 | - | - | - | - | 1.6 | 2.2 | 2.4 | 1.4 |
| | | ł | 3/2/1-i | ndicates | strengt | h of cor | relation | (3- Hig | sh, 2-Me | edium, 1 | - Low) | ł | ł | ł | |

| 18F | EEM10 | UTILIZATION OF ELECTRICAL EN | ZATION OF ELECTRICAL ENERGY | | | | | | | |
|---------|---|---|-----------------------------|------------|---------------------------|----------|---------|--|--|--|
| PRE | REQUI | SITES | CATEGORY | PE | Cre | edit | 3 | | | |
| El a at | ani a al Mara | him a Darman Cristern and Darman Electronian | Hours/Week | L | Т | Р | TH | | | |
| Elect | | hines, Power System, and Power Electronics | nours/ week | 3 | 0 | 0 | 3 | | | |
| Cour | rse Obje | ctives: | | | | | | | | |
| 1. | To unde | rstand the economics of power generation, tariff and energy co | onservation methods | 5. | | | | | | |
| 2. | 2. To impart knowledge on principle and design of illumination systems. | | | | | | | | | |
| 3. | To anal | yze the performance and different methods of electric heating a | and electric welding | | | | | | | |
| 4. | - | rt knowledge on electric traction systems and their performance | ce. | | | | | | | |
| 5. | | rstand electric drives for various industrial applications. | | | | | - | | | |
| UNI | ГΙ | INTRODUCTION | | 9 | 0 | 0 | 9 | | | |
| Econo | omics of g | generation – definitions – load duration curve – number and size | ze of generator units | s – Cost o | of elect | rical er | nergy – | | | |
| tariff | — availa | bility based Tariff- (ABT) - Battery Energy storage system (| (BESS)- Frequency | based en | ergy n | neasure | ement - | | | |
| need | for electri | cal energy conservation - methods Introduction to energy au | dit | | | | | | | |
| UNI | ГΠ | ILLUMINATION | | 9 | 0 | 0 | 9 | | | |
| Introd | luction-na | ature of radiation - definition - laws of illumination - lumino | ous efficacy-photom | etry – lig | ghting o | calcula | tions – | | | |
| - | | nination systems for residential, commercial, street lighting a | | • • | - | | | | | |
| lamp- | - mercury | vapour fluorescent lamp-energy efficiency lamps types of l | lighting schemes – r | equireme | nts of g | good li | ghting | | | |
| UNI | ГII | HEATING AND WELDING | | 9 | 0 | 0 | 9 | | | |
| | | lassification of methods of heating - requirements of a good | - | - | | - | | | | |
| tempe | erature co | ntrol of resistance furnace - electric arc furnace -induction | heating - dielectric | heating | elect | ric wel | lding – | | | |
| | | ing - electric arc welding-electrical properties of arc-application | ons of electric arc w | elding. | | | | | | |
| UNI | ΓIV | ELECTRIC TRACTION | | 9 | 0 | 0 | 9 | | | |
| | | requirements of an ideal traction system - supply systems - t | | | | | | | | |
| tractio | on motors | and control -speed control of three phase induction motor- | multiple unit contro | l – braki | ng – re | cent tre | ends in | | | |
| electr | ic traction | 1. | | | | | | | | |
| UNI | ΓV | DRIVES AND THEIR INDUSTRIAL APPLICATIO | NS | 9 | 0 | 0 | 9 | | | |
| Electu | ric drive - | -advantages of electric drive-individual drive and group drive | e -factors affecting | selection | of mo | tor – ty | pes of | | | |
| | • | state -transient characteristics -size of motor- load equalization | | | - moder | rn metł | nods of | | | |
| speed | control c | f D.C drives-dynamic braking using thyristors-regenerative br | | | | | | | | |
| | | | То | tal (45L | -+ 0 T)= | = 45 P | eriods | | | |
| | | | | | | | | | | |

| ooks: |
|--|
| C.L. Wadhwa, "Generation, Distribution and Utilization of Electrical Energy", New Age International Pvt.Ltd, 2003. |
| Eric Openshaw Taylor, "Utilisation of Electric Energy", English Universities Press Limited, 1937 |
| J.B. Gupta, "Utilization of Electric Power and Electric Traction", S.K.Kataria and Sons, 2002. |
| nce Books: |
| G.C.Garg, S.K.Gridhar&S.M.Dhir, "A Course in Utilization of Electrical Energy", Khanna Publishers, Delhi, 2003. |
| H. Partab, "Art and Science of Utilization of Electrical Energy", Dhanpat Rai and Co, New Delhi, 2004. |
| erences: |
| www.onlinecourses.nptel.ac.in |
| www.class-central.com |
| www.mooc-list.com |
| |

| Course C |)uto | comes: | Bloom's Taxonomy | | | |
|----------|------|--|------------------|--|--|--|
| Upon com | plet | ion of this course, the students will be able to: | Mapped | | | |
| CO1 | : | L2: Understanding | | | | |
| CO2 | : | Interpret the concept behind illumination and design a suitable illumination system for a specific application. | L3: Applying | | | |
| CO3 | : | Design and choose an appropriate heating method for specific application and gain knowledge about electric welding system. | L4: Analyzing | | | |
| CO4 | : | Explain the concepts and recent trends of traction system. | L4: Analyzing | | | |
| CO5 | : | L2: Understanding | | | | |

| COUR | COURSE ARTICULATION MATRIX | | | | | | | | | | | | | | |
|-------------|----------------------------|---------|---------|----------|---------|----------|----------|---------|---------|----------|----------|----------|----------|----------|----------|
| COs/ POs | PO 1 | PO 2 | PO 3 | РО 4 | PO 5 | PO 6 | PO 7 | PO 8 | PO 9 | PO 10 | PO 11 | PO 12 | PS O1 | PS O2 | PS O3 |
| CO1 | 3 | 1 | 1 | 1 | 1 | 2 | 1 | 2 | 2 | 1 | 1 | 1 | 2 | 2 | 3 |
| CO2 | 2 | 3 | 2 | 3 | 1 | 1 | 2 | 1 | 1 | | | 1 | 3 | 3 | 2 |
| CO3 | 3 | 3 | 1 | 3 | 1 | 1 | 2 | 1 | | | | | 2 | 2 | 3 |
| CO4 | 1 | 2 | 2 | 3 | 3 | 1 | 2 | 1 | | | | | 2 | 3 | 2 |
| CO5 | 3 | 1 | 1 | 2 | 1 | 1 | 2 | 1 | | 1 | | 1 | 2 | 2 | 3 |
| CO6 | 1 | 3 | 3 | 3 | 3 | 1 | 2 | 2 | | | | 1 | 3 | 3 | 2 |
| Avg | 2.17 | 2.17 | 1.67 | 2.5 | 1.67 | 1.17 | 1.83 | 1.33 | 1.5 | 1 | 1 | 1 | 2.33 | 2.5 | 2.5 |
| | | | 3/2/1-i | ndicates | strengt | h of cor | relation | (3- Hig | h, 2-Me | dium, 1 | - Low) | | | | • |

MECHANICAL ENCINEEDING MINOD DECDEE DE

| 101/15 | 3.601 | ENGINEERING THERMODYNAMICS | | | | | | | | | | | | |
|-----------|--|--|-------------------|-------------------|-----------|-----------|---------|--|--|--|--|--|--|--|
| 18ME | M01 | (Use of standard thermodynamic tables, Mollier diagram are p | | | | | | | | | | | | |
| PRE-I | REQUI | SITE: C. | ATEGORY | PE | Cr | edit | 3 | | | | | | | |
| | | | | L | Т | P | ТН | | | | | | | |
| | | H | lours/Week | 3 | 0 | 0 | 3 | | | | | | | |
| Cours | e Objec | tives: | | L | I | | | | | | | | | |
| 1. | To imp | part the knowledge on concepts of zeroth and first law of thermodyn | amics. | | | | | | | | | | | |
| 2. | | ke the learners to understand the third law of thermodynamics ar tions in closed and open systems. | nd analyze the | variou | 18 W | ork an | d heat | | | | | | | |
| 3. | To teach properties of pure substance. | | | | | | | | | | | | | |
| 4. | To impart knowledge on the concepts of steam power cycle. | | | | | | | | | | | | | |
| 5. | 5. To derive thermodynamic relations for ideal and real gases. | | | | | | | | | | | | | |
| UNIT | I | BASIC CONCEPT AND FIRST LAW | | | 9 | 0 0 | 9 | | | | | | | |
| | s thermal | aw of thermodynamics – application to closed and open systems, s equipment. SECOND LAW AND ENTROPY | steady flow pro | ocesses | with 9 | refere | | | | | | | | |
| | | | | | | | | | | | | | | |
| of thes | se staten | tefrigerator – Heat Pump, Second law of thermodynamics – Kelvin' tents their corollaries. Reversibility and irreversibility. Carnot c cept of entropy, principle of increase of entropy, T-s diagram, T-ds e | ycle, reversed | Carnot | | - | | | | | | | | |
| UNIT | III | PROPERTIES OF PURE SUBSTANCES | | | 9 | 0 0 | 9 | | | | | | | |
| | | on and its thermodynamic properties - p-v, p-T, T-v, T-s, h-s diag . Calculation of work done and heat transfer in non-flow and flow p | | | | | | | | | | | | |
| UNIT | IV | STEAM POWER CYCLE | | | 9 | 0 0 | 9 | | | | | | | |
| | Rankine nation cy | cycle, T-s & h-s diagrams - Performance Improvement - Rehe cles. | at cycle, reger | nerative | e cyc | cle and | l their | | | | | | | |
| UNIT | V | IDEAL AND REAL GASES AND THERMO DYNAMIC | C RELATION | NS | 9 | 0 0 | 9 | | | | | | | |
| states, l | Principle | eal and real gases, equation of state of ideal and real gases, Avog of corresponding states, reduced properties and compressibility char uations, Tds, relations, Clausius Clapeyron equations and Joule The | t. Exact differen | ntials, N ent. | laxw | vell rela | ations, | | | | | | | |
| | | | To | tal (45 | L)= | 45 Pe | riods | | | | | | | |

| Text B | Books: |
|--------|---|
| 1. | Nag. P.K, "Engineering Thermodynamics", Tata McGraw-Hill, New Delhi, 2017. |
| 2. | Sonntag, R.E., Borgnakke, C., and Van Wylen, G.J., Fundamentals of Thermodynamics, 6th ed., John Wiley, 2003. |
| 3. | Arora C.P, "Thermodynamics", Tata McGraw Hill, New Delhi, 2003. |
| 4. | Venwylen and Sontag, "Classical Thermodynamics", Wiley Eastern, 1987. |

| R | lefere | ence Books: |
|---|--------|--|
| | 1. | Cengel, "Thermodynamics- An Engineering Approach", 3rd Edition, Tata McGraw Hill, 2015. |
| | 2. | Merala C, Pother, Craig W and Somerton, "Thermodynamics for Engineers", Schaum Outline Series, Tata McGrawHill, New Delhi, 2004. |

| | RSE OUTCOMES: completion of this course, the students will be able to: | Bloom Taxonomy Mapped |
|------------|--|-----------------------------|
| C01 | Understand the concepts of zeroth, first and second law of thermodynamics. | Remember |
| <i>CO2</i> | Analyze the various work and heat interactions for different types of processes for closed and open systems | Evaluate |
| СОЗ | Evaluate the different properties of pure substances using steam tables and Mollier chart | Evaluate |
| <i>CO4</i> | Analyze the performance of steam power cycle. | Analyze |
| <i>CO5</i> | Derive thermodynamic relations for ideal and real gases. | Analyze |

| COURSE | ART | ICUL | ATIO | ON M | ATR | IX | | | | | | | | | |
|---------|-----|------|---------|-------|--------|-------|-------|---------|-------|---------|----------|----------|------|------|------|
| COs/POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
| CO1 | 3 | 3 | 2 | 2 | | | 1 | | | | | 1 | 3 | 1 | 1 |
| CO2 | 3 | 3 | 2 | 2 | | | 1 | | | | | 1 | 3 | 1 | 1 |
| CO3 | 3 | 3 | 3 | 2 | | 1 | 1 | | | | | 1 | 3 | 1 | 1 |
| CO4 | 2 | 3 | 2 | 2 | | 1 | 1 | | | | | 1 | 3 | 1 | 1 |
| CO5 | 3 | 3 | 2 | 2 | | 1 | | | | | | 1 | 3 | 1 | 1 |
| Avg | 2.8 | 3 | 2.2 | 2 | | 1 | 1 | | | | | 1 | 3 | 1 | 1 |
| | • | 3/2/ | '1 – in | dicat | es str | ength | of co | rrelati | on (3 | – High, | , 2- Meo | lium, 1- | Low) | | • |

| 1 | PRE-REQUISITE: CATEGORY | | | | | | 3 | | | | | | |
|--|---|---|----|---------|-----|------|-------|--|--|--|--|--|--|
| 1.Engineering Physics L | | | | | | Р | ТН | | | | | | |
| 2.Engineering Chemistry Hours/Week 3 | | | | | | | 3 | | | | | | |
| | 3.Engineering Mathematics | | | | | | | | | | | | |
| Course (| Object | tives: | | | | | | | | | | | |
| 1. To understand the basic concepts and properties of fluids. | | | | | | | | | | | | | |
| 2. To analyze the kinematic and dynamic concepts of fluid flow. | | | | | | | | | | | | | |
| 3. To understand the various incompressible fluid flow through pipes and between parallel plates. | | | | | | | | | | | | | |
| 4. Т | To apply the principles of fluid mechanics to design and operation of hydraulic turbines. | | | | | | | | | | | | |
| 5. T | 5. To apply the principles of fluid mechanics to design and operation of hydraulic pumps. | | | | | | | | | | | | |
| UNIT I | | INTRODUCTION AND FLUID STATICS | | | 9 | 0 | 0 9 | | | | | | |
| Basic concepts and units of measurement of physical quantities- Classification of fluids - Properties of fluids – density, relative density, vapour pressure, surface tension, Capillarity and viscosity. Fluid statics- hydrostatic pressure, buoyancy and Archimedes' principle. | | | | | | | | | | | | | |
| UNIT II | | FLUID KINEMATICS AND DYNAMICS | | | 9 | 0 | 0 9 | | | | | | |
| Classification of fluid flow - system and control volume - Lagrangian and Eulerian description for fluid flow - flow patterns- streamline, pathline, streakline and timeline. Velocity potential function and Stream function - continuity equation and its applications. Fluid dynamics - Bernoulli's equation and its applications. Dimensional analysis – Buckingham's theorem, dimensional homogeneity, similarity-laws and models. | | | | | | | | | | | | | |
| UNIT II | Ι | FLOW THROUGH PIPES AND PLATES | | | 9 | 0 | 0 9 | | | | | | |
| Incompressible fluid flow-Laminar flow- Hagen-Poiseuille equation, shear stress, pressure gradient relationship - flow through pipes and flow between parallel plates. Turbulent flow – flow through pipes, friction factors in turbulent flow - total energy line, hydraulic gradient line, flow through pipes in series and parallel- Moody's friction factor chart. Power transmission-Boundary layer flows - Boundary layer thickness, momentum thickness, energy thickness-boundary layer separation. | | | | | | | | | | | | | |
| UNIT IV | V | HYDRAULIC TURBINES | | | 9 | 0 | 0 9 | | | | | | |
| curves for | r Pelto | es classification-impulse and reaction turbines-Working Prin- n, Francis and Kaplan turbines (Only descriptive) - Compar- egree of reaction -draft tubes. | - | - | - | | | | | | | | |
| UNIT V | | HYDRAULIC PUMPS | | | 9 | 0 | 0 9 | | | | | | |
| Classification of hydraulic pumps- Centrifugal pumps - working principle, specific speed, performance curves and priming(Only descriptive) - Reciprocating pumps - classification, working principle, indicator diagram, air vessels and performance curves. Cavitation in pumps (Only descriptive) - Working principles of gear and vane pumps. | | | | | | | | | | | | | |
| | | | Το | tal (45 | L)= | 45 P | eriod | | | | | | |
| | | | | | | | | | | | | | |

| Text Books: | | | | | | | | | |
|-------------|--|--|--|--|--|--|--|--|--|
| 1. | Bansal, R.K., "A Textbook of Fluid Mechanics and Hydraulic Machines, 9th Ed", Laxmi Publication Pvt Ltd, 2010. | | | | | | | | |
| 2. | Rajput, R.K., "A Textbook of Fluid Mechanics and Hydraulic Mechanics", S.Chand and Company Ltd, 2011. | | | | | | | | |
| 3. | Subramanya. K., "Fluid Mechanics and Hydraulic Machines", Tata McGraw Hill Publishing Company Ltd, 2011. | | | | | | | | |

| Reference Books: | | | | | | | | | | |
|------------------|--|--|--|--|--|--|--|--|--|--|
| 1. | White, "Fluid Mechanics, 8 Ed", McGraw Hill India, 2017. | | | | | | | | | |
| 2. | Munson, Young and Okiishi, "Fundamentals of Fluid Mechanics 8 th Edition", Wiley, 2016. | | | | | | | | | |
| 3. | Yunuscengel, John. M.cimbala, "Fluid Mechanics Fundamentals and Applications", McGraw Hill, 2017. | | | | | | | | | |
| 4. | Som, S.K, Biswas.G and SumanChakraborty, "Introduction to Fluid Mechanics and Fluid Machines", Tata McGraw Hill India, 2011. | | | | | | | | | |
| 5. | Dr.P.N.Modi, Dr.S.M.Seth, "Hydraulics and Fluid Mechanics including Hydraulic Machines", Standard book house, 2018. | | | | | | | | | |
| E-Refe | E-References: | | | | | | | | | |
| 1. | NPTEL courses: http://nptel.iitm.ac.in/courses.php - web and video sources on fluid mechanics. | | | | | | | | | |

| COURSE OUTCOMES: Upon completion of the course, the students will be able to: | | | | | | |
|--|---|------------|--|--|--|--|
| C01 | Understand the basic concepts and properties of fluids. | Remember | | | | |
| <i>CO2</i> | Analyze the kinematic and dynamic concepts of fluid flow. | | | | | |
| СОЗ | Understand the various incompressible fluid flow through pipes and between parallel plates. | Understand | | | | |
| <i>CO4</i> | Apply the principles of fluid mechanics to design and operation of hydraulic turbines. | Apply | | | | |
| <i>CO5</i> | Apply the principles of fluid mechanics to design and operation of hydraulic pumps. | Apply | | | | |

| COURSE ARTICULATION MATRIX | | | | | | | | | | | | | | | |
|---|-----|-----|-----|-----|------|-----|-----|------------|-----|------|------|------|------|------|------|
| COs/POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
| CO1 | 3 | 1 | 1 | | | | 2 | | | | 1 | | 2 | 2 | 1 |
| CO2 | 3 | 3 | 1 | | 2 | | | | | | | | 2 | 2 | 1 |
| CO3 | 2 | 3 | 2 | 2 | 1 | | | | | | | | 2 | 2 | 1 |
| CO4 | 3 | 3 | 3 | 2 | 1 | 2 | 1 | | | | | | 2 | 2 | 1 |
| CO5 | 3 | 3 | 3 | 2 | 1 | 2 | 1 | | | | | | 2 | 2 | 1 |
| Avg | 2.8 | 2.6 | 2 | 2 | 1.25 | 2 | 1.3 | | | | 1 | | 2 | 2 | 1 |
| 3/2/1 – indicates strength of correlation (3 – High, 2- Medium, 1- Low) | | | | | | | | | | | | | | | |

| | EM03 | MANUFACTURING PROCESSE | S | | | | |
|---|---|--|--|---|---|--|---|
| PRE | -REQUI | SITE: | CATEGORY | PE | Cre | edit | 3 |
| 1. | | science, Engineering mathematics, Engineering Physics | TT (TT) | L | Т | Р | TH |
| 2. | Engine | eering Materials | Hours/Week | 3 | 0 | 0 | 3 |
| Cour | rse Objec | tives: | | | | | |
| 1. | | e the students familiarize with various manufacturing proces f casting. | sses and fabrication t | echniqu | ies of | f met | als and |
| 2. | To deve | lop design concepts of various manufacturing processes. | | | | | |
| 3. | Gain kn | owledge to select appropriate manufacturing processes for var | rious parts. | | | | |
| 4. | To deve | lop an entrepreneur skill among the students. | | | | | |
| 5. | To evalu | ate and select plastic deformation processes for various parts | • | | | | |
| UNI | ГΙ | CASTING | | | 9 | 0 | 09 |
| mould | ding, inves | me calculation - Moulding machines - Core making. Specia stment moulding, pressure die casting, centrifugal casting, cas | • • | s – CO | 1 | ulding | - |
| UNI | ГП | WELDING | | | 9 | 0 | 09 |
| | welding, l | welding, tungsten inert gas welding, metal inert gas welding, aser beam welding, defects in welding, Soldering and Brazing | | | | 0. | |
| | lurgical as | METAL FORMING | | | 10 | 0 | 0 10 |
| operat | sses, Hot v tions. Roll | METAL FORMING spects of metal forming, slip, twinning mechanics of plastic de working and cold working of metals, Forging processes – ope ling of metals– Types of Rolling mill – Flat strip rolling – sha and wire drawing – Tube drawing – Principles of Extrusion – | n, closed and impress ape rolling operations | ion die | bulk forgi | defor ng – | rmatior forging |
| operat Princi | sses, Hot v tions. Roll iple of rod | been been been been been been been been | n, closed and impress ape rolling operations | ion die | bulk forgi | defor ng – | rmatior forging |
| operat Princi UNIT Types and ty Film | sses, Hot v tions. Roll iple of rod Γ IV s of plastic ypical app blowing - | pects of metal forming, slip, twinning mechanics of plastic de working and cold working of metals, Forging processes – ope ling of metals– Types of Rolling mill – Flat strip rolling – sha and wire drawing – Tube drawing – Principles of Extrusion – | en, closed and impress ape rolling operations - Types. ulding of Thermoplas nes – Blow moulding ning – Processing of | ion die – Defe tics – W – Rota | bulk forgi cts in 8 Vorkin tional | defor ng – rolle 0 ng pri mou | rmatior forging d parts 0 8 inciples ilding - |
| operat Princi UNIT Types and ty Film | sses, Hot v tions. Roll iple of rod F IV s of plastic ypical app blowing - iples and ty | pects of metal forming, slip, twinning mechanics of plastic de working and cold working of metals, Forging processes – ope ling of metals– Types of Rolling mill – Flat strip rolling – sha and wire drawing – Tube drawing – Principles of Extrusion – SHAPING OF PLASTICS s - Characteristics of the forming and shaping processes – Mo lications of - Injection moulding – Plunger and screw machir - Extrusion - Typical industrial applications – Thermoform | en, closed and impress ape rolling operations - Types. ulding of Thermoplas nes – Blow moulding ning – Processing of ling. | ion die – Defe tics – W – Rota | bulk forgi cts in 8 Vorkin tional | defor ng – rolle 0 ng pri mou | rmatior forging d parts 0 8 inciples ilding - |
| operat Princi UNIT Types and ty Film princi UNIT Forma of pre | sses, Hot v tions. Roll iple of rod Γ IV s of plastic ypical appi blowing - iples and t Γ V ability of S esses used | s - Characteristics of the forming and shaping processes – Molications of - Injection moulding – Plunger and screw maching results of the forming and shaping processes – Molications of - Injection moulding – Plunger and screw maching – Extrusion - Typical industrial applications – Thermoform solutions – Compression moulding – Thermoform moulding – Transfer Matei – T | en, closed and impress ape rolling operations - Types. ulding of Thermoplast hes – Blow moulding hing – Processing of ling. FALLURGY ring, Deep drawing, B gy– Principal steps i | ion die – Defe tics – W – Rota Therm ending | bulk forgi cts in 8 Vorkin tional nosets 9 opera | defor ng – rolle 0 ng pri mou – W 0 ations | ormation forging d parts 0 8 inciples ilding - vorking 0 9 s- types |
| operat Princi UNIT Types and ty Film princi UNIT Forma of pre | sses, Hot v tions. Roll iple of rod Γ IV s of plastic ypical appi blowing - iples and t Γ V ability of S esses used | pects of metal forming, slip, twinning mechanics of plastic de working and cold working of metals, Forging processes – ope ling of metals– Types of Rolling mill – Flat strip rolling – sha and wire drawing – Tube drawing – Principles of Extrusion – SHAPING OF PLASTICS s - Characteristics of the forming and shaping processes – Mo lications of - Injection moulding – Plunger and screw machin - Extrusion - Typical industrial applications – Thermoforn ypical applications - Compression moulding – Transfer mould SHEET METAL FORMING AND POWDER MET Sheet Metal, load estimation of sheet metal processes - Shear I, Super Plastic forming; Introduction to Powder Metallurg | en, closed and impress ape rolling operations - Types. ulding of Thermoplast hes – Blow moulding hing – Processing of ling. FALLURGY ring, Deep drawing, B gy– Principal steps in netallurgy. | ion die – Defe tics – W – Rota Therm ending | bulk forgi cts in 8 /orkin tional nosets 9 opera d – s | defor ng – rolle 0 mg pri mou – W 0 ations interi | mation forging d parts 0 8 inciple ilding Vorking 0 9 s- type ng and |
| operat Princi UNIT Types and ty Film princi UNIT Forma of pre | sses, Hot v tions. Roll iple of rod Γ IV s of plastic ypical appi blowing - iples and t Γ V ability of S esses used | pects of metal forming, slip, twinning mechanics of plastic de working and cold working of metals, Forging processes – ope ling of metals– Types of Rolling mill – Flat strip rolling – sha and wire drawing – Tube drawing – Principles of Extrusion – SHAPING OF PLASTICS s - Characteristics of the forming and shaping processes – Mo lications of - Injection moulding – Plunger and screw machin - Extrusion - Typical industrial applications – Thermoforn ypical applications - Compression moulding – Transfer mould SHEET METAL FORMING AND POWDER MET Sheet Metal, load estimation of sheet metal processes - Shear I, Super Plastic forming; Introduction to Powder Metallurg | en, closed and impress ape rolling operations - Types. ulding of Thermoplast hes – Blow moulding hing – Processing of ling. FALLURGY ring, Deep drawing, B gy– Principal steps in netallurgy. | ion die – Defe tics – W – Rota Therm ending nvolved | bulk forgi cts in 8 /orkin tional nosets 9 opera d – s | defor ng – rolle 0 mg pri mou – W 0 ations interi | mation forging d parts 0 8 inciple ilding Vorking 0 9 s- type ng and |
| operat Princi UNI Types and ty Film princi ONI Forma of pre compa | sses, Hot v tions. Roll iple of rod Γ IV s of plastic ypical appi blowing - iples and t Γ V ability of S esses used | pects of metal forming, slip, twinning mechanics of plastic de working and cold working of metals, Forging processes – ope ling of metals– Types of Rolling mill – Flat strip rolling – sha and wire drawing – Tube drawing – Principles of Extrusion – SHAPING OF PLASTICS s - Characteristics of the forming and shaping processes – Mo lications of - Injection moulding – Plunger and screw machin - Extrusion - Typical industrial applications – Thermoforn ypical applications - Compression moulding – Transfer mould SHEET METAL FORMING AND POWDER MET Sheet Metal, load estimation of sheet metal processes - Shear I, Super Plastic forming; Introduction to Powder Metallurg | en, closed and impress ape rolling operations - Types. ulding of Thermoplast hes – Blow moulding hing – Processing of ling. FALLURGY ring, Deep drawing, B gy– Principal steps in netallurgy. | ion die – Defe tics – W – Rota Therm ending nvolved | bulk forgi cts in 8 /orkin tional nosets 9 opera d – s | defor ng – rolle 0 mg pri mou – W 0 ations interi | mation forging d parts 0 8 inciple ilding Vorking 0 9 s- type ng and |

2. NagendraParashar B.S. and Mittal R.K., "Elements of Manufacturing Processes", Prentice-Hall of India Private Limited, 2007.

Reference Books:

| 1. | Serope Kalpajian, Steven R.Schmid, "Manufacturing Processes for Engineering Materials", 4/e, Pearson Education, Inc. 2007. |
|--------|--|
| 2. | Jain. R.K., and S.C. Gupta, "Production Technology", 16th Edition, Khanna Publishers, 2001. |
| 3. | "H.M.T. "Production Technology – Handbook", Tata McGraw-Hill, 2000. |
| 4. | Roy. A. Linberg, "Process and Materials of Manufacture", PHI, 2000. |
| 5. | Mikell P. Groover, Fundamentals of Modern Manufacturing: Materials, Processes, and Systems. |
| E-Refe | erences: |
| 1. | https://fdocuments.in/document/production-technology-55844cac00bfc.html?page=40 |
| | |

| COURSE OUTCOMES: Upon completion of the course, the students will be able to: | | | | | | | |
|--|--|------------|--|--|--|--|--|
| C01 | <i>O1</i> Describe the operational features of various casting processes, design gate and riser and discover various defects in casting. | | | | | | |
| <i>CO2</i> | <i>CO2</i> Explain various metal joining processes and compare them. | | | | | | |
| СОЗ | Summarize several types of metal forming processes and select suitable method for different applications. | Analyze | | | | | |
| <i>CO4</i> | Analyze various manufacturing methods for plastics and their needs in industry. | Analyze | | | | | |
| <i>CO5</i> | Describe various sheet metal forming processes, load estimation calculation and principles of powder metallurgy | Understand | | | | | |

| COs/POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|---------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| CO1 | 2 | 1 | 2 | 1 | | | | | | 1 | | | 1 | 2 | 1 |
| CO2 | 2 | 1 | 2 | 1 | | 1 | | | 1 | 1 | | | 1 | 2 | 1 |
| CO3 | 1 | 1 | 1 | 1 | | | | | | 1 | | | 1 | 1 | 1 |
| CO4 | 1 | 1 | 1 | | 1 | | | | | 1 | | | 1 | 1 | 1 |
| CO5 | | 1 | | | | | | | 1 | 1 | | | 1 | | 1 |
| Avg | 1.5 | 1 | 1.5 | 1 | 1 | 1 | | | 1 | 1 | | | 1 | 1.5 | 1 |

| 18ME | M04 | | | | | | |
|----------------------|--|---|--|---------------------|------------------|------------------|-----------------|
| PRE-F | REQU | SITE: | CATEGORY | PE | Cre | dit | 3 |
| 1. | | eering Physics | | L | Т | Р | ТН |
| 2. | Engin | Hours/Week | 3 | 0 | 0 | 3 | |
| Course | e Obje | ctives: | | | | | 1 |
| 1. | | part concept on reactions, treatment, microstructure and mechanical be rature. | havior of engineer | ing ma | terials | at dif | ferent |
| 2. | To lea | rn basic principles in metallurgy and materials engineering. | | | | | |
| 3. | To ide | entity and select suitable engineering materials based on their application | ons. | | | | |
| UNIT | I | PHASE DIAGRAMS | | 9 | 0 | 0 | 9 |
| systems diagram | s – Eut 1 - effec | es, Phases, solid solution types, compounds, Hume- Rothery rules; Gi ectic, Eutectoid, Peritectic systems. Lever rule, Equilibrium and no ts of alloying elements – Ferrite and Austenite Stabilizers, TTT and Co | on-equilibrium coo | oling, I | Fe-C E | lquilit | brium |
| UNIT | II | HEAT TREATMENT | | 9 | 0 | 0 | 9 |
| Isotherr test – A | nal trar Austemp | all annealing, stress relief, recrystallisation and spheroidizing –norma sformation diagrams – cooling curves superimposed on I.T. diagram ering, martempering – case hardening, carburising, nitriding, cyanidi t treatment of non-ferrous alloys - precipitation hardening. Heat treatment | CCR - Hardenabi ng, carbo-nitriding | lity, Jo g – Fla | miny e me and | end qu I Indu | uench action |
| UNIT | III | FERROUS AND NON FERROUS METALS | | 9 | 0 | 0 | 9 |
| precipit | ation h | eels – Tool steels - maraging steels – HSLA steels .Stainless steels- ferr ardened stainless steels. Types of Cast Irons- Gray cast iron, white cast Bronze and Cupronickel, Aluminium alloys, Bearing alloys. | | | | - | |
| UNIT | IV | MECHANICAL PROPERTIES AND TESTING | | 9 | 0 | 0 | 9 |
| Fracture | e - Type | operties of engineering materials - Mechanisms of plastic deformation as of fracture – Testing of materials - tension, compression and shear lo ting for hardness (Brinell, Vickers and Rockwell) - Impact test - Izod a | ads - fatigue and c | - | - | - | |
| UNIT | V | NON DESTRUCTIVE TESTING AND SURFACE ENGIN | IEERING | 9 | 0 | 0 | 9 |
| Inspecti | ion and | ve Testing: Basic principles - Testing method - Radiographic testi Liquid Penetrant Inspections. Introduction to surface engineering - D and low energy beam methods, surface engineering charts, elastic conta | Definition, diffusio | - | - | | |
| | | | Tot | al (45) | L) = 4 | 5 Pe | riods |
| | | | | | | | |
| Text B | ooks: | | | | | | |
| 1. | Ke | nneth G. Budinski and Michael K. Buinski, "Engineering Materials", P | rentice Hall of Ind | lia Ltd, | 2002. | | |
| 2. | Ra | ghavan, V, "Materials Science and Engineering", Prentice Hall of India | a (P) Ltd., 1999. | | | | |
| 3. | 3. Aswani.K.G, "A Text Book of Material Science", S.Chand and Co. Ltd., New Delhi, 2001. | | | | | | |

4. Khanna O.P., "A Text Book of Materials Science and Metallurgy", DhanpatRai Sons, 2004. **Reference Books:**

| Keleren | te Dooks. |
|---------|--|
| 1. | William. D.Callsber, "Material Science and Engineering", John Wiley and Sons, 1997. |
| 2. | Sydney.H.Avner, "Introduction to Physical Metallurgy" Mc Graw Hill Book Company, 1994. |

| | COURSE OUTCOMES: Upon completion of the course, the students will be able to: | | | | | | | |
|------------|--|------------|--|--|--|--|--|--|
| C01 | <i>I</i> Understand the formation of materials and their classification based on atomic structure. | | | | | | | |
| <i>CO2</i> | <i>O2</i> Understand the principles of various heat treatment processes in fabrication industry. | | | | | | | |
| СОЗ | Describe properties, applications and types of various ferrous and non-ferrous metals used in fabrication industry | Understand | | | | | | |
| <i>CO4</i> | Describe various types of failure and select methods for destructive testing | Understand | | | | | | |
| <i>C05</i> | Select methods for non destructive testing | Evaluate | | | | | | |

| COURSE A | ARTI | CULA | ATIO | N MA | TRIX | K | | | | | | | | | |
|----------|------|------|---------|-------|--------|-------|-------|---------|-------|---------|--------|---------|------|------|------|
| COs/POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
| CO1 | 1 | 1 | 2 | 2 | 1 | 1 | 1 | | | | | | 2 | 3 | 1 |
| CO2 | 1 | | 2 | 1 | 1 | 2 | 1 | | | | | | 2 | 3 | 1 |
| CO3 | | 1 | 1 | 1 | 1 | | 1 | | | | | | 3 | 2 | 1 |
| CO4 | | 2 | 2 | 1 | 1 | 1 | 1 | | | | | | 2 | 3 | 1 |
| CO5 | | 2 | 2 | 2 | 1 | | 1 | | | | | | 2 | 2 | 1 |
| Avg | 1 | 1.5 | 1.8 | 1.4 | 1.0 | 1.3 | 1 | | | | | | 2.2 | 2.6 | 1.0 |
| | | 3/2/ | /1 – in | dicat | es str | ength | of co | rrelati | on (3 | – High, | 2- Mee | lium, 1 | Low) | 1 | • |

| 18ME | M05 | KINEMATICS OF MACHINERY | | | | | | |
|--------------------|---|---|----------------------|----------|--------|-------|-----|------|
| PRE-F | REQUIS | SITE: | CATEGORY | PE | Cr | edit | | 3 |
| 1. Engi | neering g | raphics. 2.Engineering Mechanics | Hours/Week | L | Т | Р | r | ΓН |
| | | | Hours/ week | 3 | 0 | 0 | | 3 |
| Course Objectives: | | | | | | | | |
| 1. | To und | erstand the basic components and layout of linkages in the assem | bly of a system/ ma | chine. | | | | |
| 2. | | erstand the principles in analyzing the assembly with respect to t point in a link of a mechanism. | he displacement, ve | elocity, | and | accel | era | tion |
| 3. | To und | erstand basics of cam profile and its displacement. | | | | | | |
| 4. | To und | erstand the basic concepts of toothed gearing and kinematics of g | ear trains. | | | | | |
| 5. | Illustra | te the effects of friction drives in transmission system. | | | | | | |
| UNIT | I | BASICS OF MECHANISMS | | | 9 | 0 | 0 | 9 |
| Kinema | tic inver | f mechanisms- Basic kinematic concepts and definitions- Degressions of four bar chain and slider-crank chains Limit positions- Mome common mechanisms- Quick return mechanism, straight-lin | lechanical advantag | | | | | |
| UNIT | II | KINEMATIC ANALYSIS | | | 9 | 0 | 0 | 9 |
| centres | - kinema | elocity and acceleration analysis of simple mechanisms, graph tic analysis of simple mechanisms- slider-crank mechanism dynam ntroduction to linkage synthesis three Position graphical synthesis | nics Coincident poi | nts- Co | orioli | s com | | |
| UNIT | III | KINEMATICS OF CAM | | | 9 | 0 | 0 | 9 |
| simple | harmonic | cams and followers- Terminology and definitions- Displaceme and cycloidal motions- derivatives of follower motions- specifie and undercutting, sizing of cams, graphical method for cam profile | ed contour cams cire | | | | | |
| UNIT | IV | GEARS AND GEAR TRAINS | | | 9 | 0 | 0 | 9 |
| | • | cloidal gear profiles, gear parameters, fundamental law of gearir rence / undercutting- helical, bevel, worm, rack & pinion gears, e | | | - | - | | |
| UNIT | V | FRICTION IN MACHINE ELEMENTS | | | 9 | 0 | 0 | 9 |
| | Surface contacts- sliding and rolling friction- friction drives- friction in screw threads – bearings and lubrication- friction Clutches- belt and rope drives. | | | | | | | tion |
| | | | | | | | | |
| | | | Tota | al (451 | L) = | 45 P | eri | ods |
| | | | | | | | | |
| Text B | ooks: | | | | | | | |
| 1. | Rattan | S.S, "Theory of Machines", Tata McGraw Hill Publishing Compa | any Ltd., New Delh | i, 1998 | | | | |

| 2. | Ghosh, A and Mallick, A.K, "Theory of Mechanisms and Machines", East-West Pvt. Ltd., New Delhi, 1988. |
|--------|---|
| Refere | ence Books: |
| 1. | Thomas Bevan, "Theory of Machines", CBS Publishers and Distributors, 1984. |
| 2. | Rao J.S and Dukkipati R.V, "Mechanism and Machine Theory", Wiley-Eastern Ltd., New Delhi, 1992. |

| 3. | Erdman AG and Sandor G N, "Mechanism Design, Analysis and Synthesis", Vol.I, PHI Inc., 1997. | | | | | | | | | |
|--------|--|--|--|--|--|--|--|--|--|--|
| 4. | mbekar A.G, "Mechanism and Machine Theory" Prentice Hall of India, New Delhi, 2007. | | | | | | | | | |
| 5. | John Hannah and Stephens R C, "Mechanisms of Machines", Viva Low Price Student Edition, New Delhi, 1999. | | | | | | | | | |
| E-Refe | erences: | | | | | | | | | |
| 1. | https://archive.nptel.ac.in/courses/112/104/112104121/ | | | | | | | | | |
| 2. | https://nptel.ac.in/courses/112106270 | | | | | | | | | |
| 3. | http://velhightech.com/Documents/ME8492 Kinematics of Machinery.pdf | | | | | | | | | |

| | COURSE OUTCOMES: Upon completion of the course, the students will be able to: | | | | | | | |
|------------|---|----------|--|--|--|--|--|--|
| C01 | CO1 Demonstrate and understand the concepts of various mechanisms and pairs. | | | | | | | |
| <i>CO2</i> | <i>CO2</i> Analyze the velocity and acceleration of simple mechanisms. | | | | | | | |
| СО3 | Construct the cam profile for various motion. | Create | | | | | | |
| <i>CO4</i> | Solve problems on gears and gear trains. | Evaluate | | | | | | |
| <i>C05</i> | Evaluate the friction in transmission system | Evaluate | | | | | | |

| COURSE A | ARTIO | CULA | TION | N MA | TRIX | X | | | | | | | | | |
|----------|-------|------|---------|--------|--------|-------|-------|------------|-------|---------|--------|----------|------|------|------|
| COs/POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
| CO1 | 3 | 2 | 2 | 1 | | | | | | | | | 3 | 1 | |
| CO2 | 3 | 2 | 2 | 1 | | | | | | | | | 3 | 1 | |
| CO3 | 3 | 2 | 2 | 1 | | | | | | | | | 3 | 1 | |
| CO4 | 3 | 2 | 2 | 1 | | | | | | | | | 3 | 1 | |
| CO5 | 3 | 2 | 2 | 1 | | | | | | | | | 3 | 1 | |
| Avg | 3 | 2 | 2 | 1 | | | | | | | | | 3 | 1 | |
| | | 3/2/ | /1 – ir | ndicat | es str | ength | of co | rrelati | on (3 | – High, | 2- Med | lium, 1- | Low) | | |

| PRE-REQUISITE: CATEGORY PE Credit 3 Iburs/Week L T P TH Hours/Week L T P TH Iburs/Week Applying the working principles of hydraulics and pneumatics 3 3 0 0 3 Course Designing and develop hydraulic circuits and systems. 5 Solving problems and troubles in fluid power system and its components. 5 9 0 < | 18MEM06 HYDRAULICS AND PNEUMATICS | | | | | | | | | | | |
|--|--|--|---|--|---------------------|-------------------|-----------------|----------------------|---|--|--|--|
| Hours/Week i <th colsp<="" th=""><th>PRE-</th><th>REQUIS</th><th>SITE:</th><th>CATEGORY</th><th>PE</th><th>Cre</th><th>edit</th><th>3</th></th> | <th>PRE-</th> <th>REQUIS</th> <th>SITE:</th> <th>CATEGORY</th> <th>PE</th> <th>Cre</th> <th>edit</th> <th>3</th> | PRE- | REQUIS | SITE: | CATEGORY | PE | Cre | edit | 3 | | | |
| 3 0 0 3 Course Objectives: 1. To enable the students understand the basics of hydraulic and pneumatics . 2. Applying the working principles of hydraulic actuators and control components. . 3. Designing and develop hydraulic circuits and systems. . 4. Applying the working principles of pneumatic power system and its components. . 5. Solving problems and troubles in fluid power systems. 9 0 0 9 UNTT I FLUID POWER PRINICIPLES AND HYDRAULIC PUMIPS 9 0 0 9 Introduction to Fluid power - Advantages and Applications – Fluid power systems – Work, Power and Torque - Problems, Sources of Hydraulic power; Pumping Theory – Pump Classification – Construction, Working, Design, Advantages, Disadvantages, Performance, Selection criteria of pumps – Fixed and Variable displacement pumps – Problems. UNIT II HYDRAULIC ACTUATORS AND CONTROL COMPONENTS 9 0 0 9 UNIT II HYDRAULIC CIRCUITS AND SYSTEMS 9 0 0 9 0 0 9 UNIT II HYDRAULIC CIRCUITS AND SYSTEMS 9 0 0 9 0 0 9 0 0 | | | | TT /XX / 1 - | L | Т | Р | ТН | | | | |
| 1. To enable the students understand the basics of hydraulics and pneumatics 2. Applying the working principles of hydraulic actuators and control components. 3. Designing and develop hydraulic circuits and systems. 4. Applying the working principles of pneumatic power system and its components. 5. Solving problems and troubles in fluid power systems. UNT I FLUD POWER PRINCIPLES AND HYDRAULIC PUMPS 9 0 0 9 Introduction to Fluid power - Advantages and Applications - Fluid power systems - Types of fluids - Properties of fluids and selection - Basics of Hydraulic power; Pumping Theory - Pump Classification - Construction, Working, Design, Advantages, Disadvantages, Performance, Selection criteria of pumps - Fixed and Variable displacement pumps - Problems. UNIT II HYDRAULIC ACTUATORS AND CONTROL COMPONENTS 9 0 0 9 Hydraulic Actuators: Cylinders - Types and construction, Application, Hydraulic cushioning - Rotary actuators - Hydraulic motors - Control Components : Direction Control, Flow control and pressure control valves - Types, Construction and Operation - Accessories; Reservoirs, Pressure Switches - Filters - types and selection - Applications - Fluid Power ANSI Symbols - Problems. UNIT II HYDRAULIC CIRCUITS AND SYSTEMS 9 0 0 9 Accumulators, Intensifiers, Industrial hydraulic circuits - Regenerative, Pump Unloading, Double - Pump, Pressure Intensifier, Air osvern J, Sequ | | | | Hours/ week | 3 | 0 | 0 | 3 | | | | |
| 2. Applying the working principles of hydraulic actuators and control components. 3. Designing and develop hydraulic circuits and systems. 4. Applying the working principles of pneumatic power system and its components. 5. Solving problems and troubles in fluid power systems. UNIT I FLUID POWER PRINICIPLES AND HYDRAULIC PUMPS 9 0 0 9 Introduction to Fluid power - Advantages and Applications - Fluid power systems - Types of fluids - Properties of Huds and selection - Basics of Hydraulic power; Pumping Theory - Pump Classification - Construction, Working, Design, Advantages, Disadvantages, Performance, Selection criteria of pumps - Fixed and Variable displacement pumps - Problems. UNIT II HYDRAULIC ACTUATORS AND CONTROL COMPONENTS 9 0 0 9 Hydraulic Actuators: Cylinders - Types and construction, Application, Hydraulic cushioning - Rotary actuators - Hydraulic motors - Control Components : Direction Control, Flow control and pressure control valves - Types, Construction and Operation - Accessories; Reservoirs, Pressure Switches - Filters - types and selection - Applications - Fluid Power ANSI Symbols - Problems. UNIT II HYDRAULIC CIRCUITS AND SYSTEMS 9 0 0 9 4 0 9 0 0 9 0 0 9 0 0 9 0 0 9 0 <t< td=""><td>Cour</td><td>se Objec</td><td>tives:</td><th></th><td>1</td><td></td><td></td><td></td></t<> | Cour | se Objec | tives: | | 1 | | | | | | | |
| 3. Designing and develop hydraulic circuits and systems. 4. Applying the working principles of pneumatic power system and its components. 5. Solving problems and troubles in fluid power systems. UNIT I FLUID POWER PRINICIPLES AND HYDRAULIC PUMPS 9 0 0 9 Introduction to Fluid power – Advantages and Applications – Fluid power systems – Types of fluids - Properties of fluids and selection – Basics of Hydraulics – Pascal's Law – Principles of flow - Friction loss – Work, Power and Torque - Problems, Sources of Hydraulic power; Pumping Theory – Pump Classification – Construction, Working, Design, Advantages, Disadvantages, Performance, Selection criteria of pumps – Fixed and Variable displacement pumps – Problems. UNIT II HYDRAULIC ACTUATORS AND CONTROL COMPONENTS 9 0 0 9 UNIT III HYDRAULIC CACTUATORS AND CONTROL COMPONENTS 9 0 0 9 UNIT III HYDRAULIC CIRCUITS AND SYSTEMS 9 0 0 9 Notors - Control Components : Direction Control, Flow control and pressure control valves – Types, Construction and Operation – Accessories; Reservoirs, Pressure Switches – Filters – types and selection - Applications – Fluid Power ANSI Symbols – Problems. 9 0 0 9 UNIT III HYDRAULIC CIRCUITS AND SYSTEMS 9 0 0 9 0 < | 1. | To enabl | e the students understand the basics of hydraulics and pneumatic | CS | | | | | | | | |
| 4. Applying the working principles of pneumatic power system and its components. 5. Solving problems and troubles in fluid power systems. UNIT I FLUID POWER PRINICIPLES AND HYDRAULIC PUMPS 9 0 0 9 Introduction to Fluid power – Advantages and Applications – Fluid power systems – Types of fluids - Properties of Indust and selection – Basics of Hydraulic – Pascal's Law – Principles of flow - Friction loss – Work, Power and Torque – Problems, Sources of Hydraulic power; Pumping Theory – Pump Classification – Construction, Working, Design, Advantages, Disadvantages, Performance, Selection criteria of pumps – Fixed and Variable displacement – pumps – Problems. UNIT II HYDRAULIC ACTUATORS AND CONTROL COMPONENTS 9 0 0 9 Hydraulic Actuators: Cylinders – Types and construction, Application, Hydraulic cushioning – Rotary actuators - Hydraulic motors - Control Components : Direction Control, Flow control and pressure control valves – Types, Construction and Operation – Accessories; Reservoirs, Pressure Switches – Filters – types and selection - Applications – Fluid Power ANSI Symbols – Problems. UNIT III HYDRAULIC CIRCUITS AND SYSTEMS 9 0 0 9 Accumulators, Intensifiers, Industrial hydraulic circuits – Regenerative, Pump Unloading, Double - Pump, Pressure Mechanical, hydraulic servo systems. 9 0 0 9 Properties of air – Air preparation and distribution – Filters, Regulator, Lubricator, Muffler, Air control Valves, Quic | 2. | Applying | g the working principles of hydraulic actuators and control comp | oonents. | | | | | | | | |
| 5. Solving problems and troubles in fluid power systems. UNIT 1 FLUID POWER PRINICIPLES AND HYDRAULIC PUMPS 9 0 0 9 Introduction to Fluid power – Advantages and Applications – Fluid power systems – Types of fluids - Properties of fluids and selection – Basics of Hydraulics – Pascal's Law – Principles of flow - Friction loss – Work, Power and Torque - Problems, Sources of Hydraulic power; Pumping Theory – Pump Classification – Construction, Working, Design, Advantages, Disadvantages, Performance, Selection criteria of pumps – Fixed and Variable displacement pumps – Problems. UNIT II HYDRAULIC ACTUATORS AND CONTROL COMPONENTS 9 0 0 9 Hydraulic Actuators: Cylinders – Types and construction, Application, Hydraulic cushioning – Rotary actuators - Hydraulin ontors - Control Components : Direction Control, Flow control and pressure control valves – Types, Construction and Operation – Accessories; Reservoirs, Pressure Switches – Filters – types and selection - Applications – Fluid Power ANSI Symbols – Problems. UNIT III HYDRAULIC CIRCUITS AND SYSTEMS 9 0 0 9 Accumulators, Intensifiers, Industrial hydraulic circuits – Regenerative, Pump Unloading, Double - Pump, Pressure Intensifier, Air-over oil, Sequence, Reciprocation, Synchronization, Fail - Safe, Speed Control, Deceleration circuits, Sizing of hydraulic servo systems. 9 0 0 9 0 0 9 UNIT III HYDRAULIC CIRCUITS AND SYSTEMS 9 | 3. | 3. Designing and develop hydraulic circuits and systems. | | | | | | | | | | |
| UNIT 1 FLUID POWER PRINCIPLES AND HYDRAULIC PUMPS 9 0 0 9 Introduction to Fluid power – Advantages and Applications – Fluid power systems – Types of fluids - Properties of fluids and selection – Basics of Hydraulics – Pascal's Law – Principles of flow - Friction loss – Work, Power and Torque - Problems, Sources of Hydraulic power; Pumping Theory – Pump Classification – Construction, Working, Design, Advantages, Disadvantages, Performance, Selection criteria of pumps – Fixed and Variable displacement pumps – Problems. UNIT II HYDRAULIC ACTUATORS AND CONTROL COMPONENTS 9 0 0 9 Hydraulic Actuators: Cylinders – Types and construction, Application, Hydraulic cushioning – Rotary actuators - Hydraulic motors - Control Components : Direction Control, Flow control and pressure control valves – Types, Construction and Operation – Accessories; Reservoirs, Pressure Switches – Filters – types and selection - Applications – Fluid Power ANSI Symbols – Problems. UNIT III HYDRAULIC CIRCUITS AND SYSTEMS 9 0 0 9 Accumulators, Intensifiers, Industrial hydraulic circuits – Regenerative, Pump Unloading, Double - Pump, Pressure Intensifier, Air-over oil, Sequence, Reciprocation, Synchronization, Fail - Safe, Speed Control, Deceleration circuits, Sizing of hydraulic servo systems. 9 0 0 9 0 0 9 UNIT III HYDRAULIC CIRCUITS AND SYSTEMS 9 0 0 9 0 0 9 | 4. | 4. Applying the working principles of pneumatic power system and its components. | | | | | | | | | | |
| Introduction to Fluid power – Advantages and Applications – Fluid power systems – Types of fluids - Properties of fluids and selection – Basies of Hydraulics – Pascal's Law – Principles of flow - Friction loss – Work, Power and Torque – Problems, Sources of Hydraulic power; Pumping Theory – Pump Classification – Construction, Working, Design, Advantages, Disadvantages, Performance, Selection criteria of pumps – Fixed and Variable displacement pumps – Problems. UNIT II HYDRAULIC ACTUATORS AND CONTROL COMPONENTS 9 0 0 9 Hydraulic Actuators: Cylinders – Types and construction, Application, Hydraulic cushioning – Rotary actuators - Hydra-lic motors - Control Components : Direction Control, Flow control and pressure control valves – Types, Construction – and Operation – Accessories; Reservoirs, Pressure Switches – Filters – types and selection - Applications – Fluid Power ANSI Symbols – Problems. UNIT III HYDRAULIC CIRCUITS AND SYSTEMS 9 0 0 9 Accumulators, Intensifiers, Industrial hydraulic circuits – Regenerative, Pump Unloading, Double - Pump, Pressure Intensifier, Air-over oil, Sequence, Reciprocation, Synchronization, Fail - Safe, Speed Control, Deceleration circuits, Sizing of hydraulic systems. 9 0 0 9 UNIT IV PNEUMATIC AND ELECTRO PNEUMATIC SYSTEMS 9 0 0 9 Properties of air – Air preparation and distribution – Filters, Regulator, Lubricator, Muffler, Air control Valves, Quick Exhaust Valves, Pneumatic actuators, Design of Pneumatic Circuit - Classification - single cylinder and multi cylinder circu | 5. | Solving | problems and troubles in fluid power systems. | | | | | | | | | |
| and selection – Basics of Hydraulics – Pascal's Law – Principles of flow - Friction loss – Work, Power and Torque - Problems, Sources of Hydraulic power; Pumping Theory – Pump Classification – Construction, Working, Design, Advantages, Disadvantages, Performance, Selection criteria of pumps – Fixed and Variable displacement – pumps – Problems. UNIT II HYDRAULIC ACTUATORS AND CONTROL COMPONENTS 9 0 0 9 Hydraulic Actuators: Cylinders – Types and construction, Application, Hydraulic cushioning – Rotary actuators - Hydraulic motors - Control Components : Direction Control, Flow control and pressure control valves – Types, Construction and Operation – Accessories; Reservoirs, Pressure Switches – Filters – types and selection - Applications – Fluid Power ANSI Symbols – Problems. UNIT III HYDRAULIC CIRCUITS AND SYSTEMS 9 0 0 9 Accumulators, Intensifiers, Industrial hydraulic circuits – Regenerative, Pump Unloading, Double - Pump, Pressure Intensifier, Air-over oil, Sequence, Reciprocation, Synchronization, Fail - Safe, Speed Control, Deceleration circuits, Sizing of hydraulic systems, Hydrostatic transmission, Electro hydraulic circuits – Servo and Proportional valves – Applications - Mechanical, hydraulic servo systems. UNIT IV PNEUMATIC AND ELECTRO PNEUMATIC SYSTEMS 9 0 0 9 Properties of air – Air preparation and distribution – Filters, Regulator, Lubricator, Muffler, Air control Valves, Quick Exhaust Valves, Pneumatic actuators, Design of Pneumatic circuit – classification - single cylinder and multi cylinder circuits roblems, Introduction to fluidics and pneumatic logic circuits. UNIT V DESIGN OF FLUID POWER CIRCUITS AND TROUBLESHOOTING 9 0 0 9 Servo systems, Hydro mechanical servo systems, electro hydraulic servo systems and proportional Valves, Introduction to electro hydraulic pneumatic logic circuits, Ledder diagrams, PLC applications in fluid power control. Fluid power circuits, failure and troubleshooting. Design of Pneumatic circuits for metal working, handling, clamping counter and tin | UNIT | ΓI | FLUID POWER PRINICIPLES AND HYDRAULIC | PUMPS | | 9 | 0 | 09 | | | | |
| Hydraulic Actuators: Cylinders – Types and construction, Application, Hydraulic cushioning – Rotary actuators - Hydraulic motors - Control Components : Direction Control, Flow control and pressure control valves – Types, Construction and Operation – Accessories; Reservoirs, Pressure Switches – Filters – types and selection - Applications – Fluid Power ANSI Symbols – Problems. UNIT III HYDRAULIC CIRCUITS AND SYSTEMS 9 0 0 9 Accumulators, Intensifiers, Industrial hydraulic circuits – Regenerative, Pump Unloading, Double - Pump, Pressure Intensifier, Air-over oil, Sequence, Reciprocation, Synchronization, Fail - Safe, Speed Control, Deceleration circuits, Sizing of hydraulic systems, Hydrostatic transmission, Electro hydraulic circuits – Servo and Proportional valves – Applications - Mechanical, hydraulic servo systems. 9 0 0 9 UNIT IV PNEUMATIC AND ELECTRO PNEUMATIC SYSTEMS 9 0 0 9 Properties of air – Air preparation and distribution – Filters, Regulator, Lubricator, Muffler, Air control Valves, Quick Exhaust Valves, Pneumatic actuators, Design of Pneumatic circuit – classification - single cylinder and multi cylinder circuits problems, Introduction to fluidies and pneumatic logic circuits. 9 0 0 9 Servo systems, Hydro mechanical servo systems, electro hydraulic servo systems and proportional Valves, Introduction to electro hydraulic one control. Fluid power circuits, failure and troubleshooting. Design of Pneumatic circuits for metal working, handling, clamping counter and timer circuits Low cost Automation – Hydraulic and Pneumatic power packs. C | Advantages, Disadvantages, Performance, Selection criteria of pumps - Fixed and Variable displacement pu | | | | | | | | | | | |
| motors - Control Components : Direction Control, Flow control and pressure control valves – Types, Construction and Operation – Accessories; Reservoirs, Pressure Switches – Filters – types and selection - Applications – Fluid Power ANSI Symbols – Problems.UNIT IIIHYDRAULIC CIRCUITS AND SYSTEMS9009Accumulators, Intensifiers, Industrial hydraulic circuits – Regenerative, Pump Unloading, Double - Pump, Pressure Intensifier, Air-over oil, Sequence, Reciprocation, Synchronization, Fail - Safe, Speed Control, Deceleration circuits, Sizing of hydraulic systems, Hydrostatic transmission, Electro hydraulic circuits – Servo and Proportional valves – Applications - Mechanical, hydraulic servo systems.9009Properties of air – Air preparation and distribution – Filters, Regulator, Lubricator, Muffler, Air control Valves, Quick Exhaust Valves, Pneumatic actuators, Design of Pneumatic circuit – classification - single cylinder and multi cylinder circuits problems, Introduction to fluidics and pneumatic logic circuits.9009Servo systems, Hydro mechanical servo systems, electro hydraulic servo systems and proportional Valves, Introduction to electro hydraulic pneumatic logic circuits, Ided r diagram, PLC applications in fluid power control. Fluid power circuits, failure and troubleshooting. Design of Pneumatic circuits for metal working, handling, clamping counter and timer circuits - Low cost Automation – Hydraulic and Pneumatic power packs. Case studies: A simple sequence, synchronize circuits using hydraulic and pneumatic power packs. Case studies: A simple sequence, synchronize circuits - Low cost Automation – Hydraulic and Pneumatic power packs. Case studies: A simple sequence, synchronize circuits - using hydraulic and pneumatic components. </td <td>UNIT</td> <td>T II</td> <td>HYDRAULIC ACTUATORS AND CONTROL COM</td> <th>IPONENTS</th> <td></td> <td>9</td> <td>0</td> <td>09</td> | UNIT | T II | HYDRAULIC ACTUATORS AND CONTROL COM | IPONENTS | | 9 | 0 | 09 | | | | |
| Accumulators, Intensifiers, Industrial hydraulic circuits – Regenerative, Pump Unloading, Double - Pump, Pressure Intensifier, Air-over oil, Sequence, Reciprocation, Synchronization, Fail - Safe, Speed Control, Deceleration circuits, Sizing of hydraulic systems, Hydrostatic transmission, Electro hydraulic circuits – Servo and Proportional valves – Applications - Mechanical, hydraulic servo systems. UNIT IV PNEUMATIC AND ELECTRO PNEUMATIC SYSTEMS 9 0 0 9 Properties of air – Air preparation and distribution – Filters, Regulator, Lubricator, Muffler, Air control Valves, Quick Exhaust Valves, Pneumatic actuators, Design of Pneumatic circuit – classification - single cylinder and multi cylinder circuits - Cascade method – Integration of fringe circuits, Electro Pneumatic System – Elements – Ladder diagram – timer circuits problems, Introduction to fluidics and pneumatic logic circuits. 9 0 0 9 Servo systems, Hydro mechanical servo systems, electro hydraulic servo systems and proportional Valves, Introduction to electro hydraulic pneumatic logic circuits, Iadder diagrams, PLC applications in fluid power control. Fluid power circuits, failure and troubleshooting. Design of Pneumatic power packs. Case studies: A simple sequence, synchronize circuits using hydraulic and pneumatic power packs. Case studies: A simple sequence, synchronize circuits using hydraulic and pneumatic power packs. Case studies: A simple sequence, synchronize circuits | motor Opera Symbo | s - Contro tion – Acc ols – Prob | l Components : Direction Control, Flow control and pressure essories; Reservoirs, Pressure Switches – Filters – types and se lems. | control valves – ' | Types, | Cons luid I | tructi Power | on and ANSI | | | | |
| Intensifier, Air-over oil, Sequence, Reciprocation, Synchronization, Fail - Safe, Speed Control, Deceleration circuits, Sizing of hydraulic systems, Hydrostatic transmission, Electro hydraulic circuits – Servo and Proportional valves – Applications - Mechanical, hydraulic servo systems. 9 0 0 9 UNIT IV PNEUMATIC AND ELECTRO PNEUMATIC SYSTEMS 9 0 0 9 Properties of air – Air preparation and distribution – Filters, Regulator, Lubricator, Muffler, Air control Valves, Quick Exhaust Valves, Pneumatic actuators, Design of Pneumatic circuit – classification - single cylinder and multi cylinder circuits - Cascade method – Integration of fringe circuits, Electro Pneumatic System – Elements – Ladder diagram – timer circuits problems, Introduction to fluidics and pneumatic logic circuits. 9 0 0 9 Servo systems, Hydro mechanical servo systems, electro hydraulic servo systems and proportional Valves, Introduction to electro hydraulic pneumatic logic circuits, ladder diagrams, PLC applications in fluid power control. Fluid power circuits, failure and troubleshooting. Design of Pneumatic circuits for metal working, handling, clamping counter and timer circuits. – Low cost Automation – Hydraulic and Pneumatic power packs. Case studies: A simple sequence, synchronize circuits using hydraulic and pneumatics components. | UNIT | T III | HYDRAULIC CIRCUITS AND SYSTEMS | | | 9 | 0 | 09 | | | | |
| Properties of air – Air preparation and distribution – Filters, Regulator, Lubricator, Muffler, Air control Valves, Quick Exhaust Valves, Pneumatic actuators, Design of Pneumatic circuit – classification - single cylinder and multi cylinder circuits - Cascade method – Integration of fringe circuits, Electro Pneumatic System – Elements – Ladder diagram – timer circuits problems, Introduction to fluidics and pneumatic logic circuits. UNIT V DESIGN OF FLUID POWER CIRCUITS AND TROUBLESHOOTING 9 0 0 9 Servo systems, Hydro mechanical servo systems, electro hydraulic servo systems and proportional Valves, Introduction to electro hydraulic pneumatic logic circuits, ladder diagrams, PLC applications in fluid power control. Fluid power circuits. 9 0 0 9 Low cost Automation – Hydraulic and Pneumatic power packs. Case studies: A simple sequence, synchronize circuits using hydraulic and pneumatics components. Case studies: A simple sequence, synchronize circuits | Intens of hyd | ifier, Air-o Iraulic sys | over oil, Sequence, Reciprocation, Synchronization, Fail - Safe, ems, Hydrostatic transmission, Electro hydraulic circuits – Ser | Speed Control, Dec | celeration | on cir | cuits, | Sizing | | | | |
| Exhaust Valves, Pneumatic actuators, Design of Pneumatic circuit – classification - single cylinder and multi cylinder circuits - Cascade method – Integration of fringe circuits, Electro Pneumatic System – Elements – Ladder diagram – timer circuits problems, Introduction to fluidics and pneumatic logic circuits. UNIT V DESIGN OF FLUID POWER CIRCUITS AND TROUBLESHOOTING 9 0 0 9 Servo systems, Hydro mechanical servo systems, electro hydraulic servo systems and proportional Valves, Introduction to electro hydraulic pneumatic logic circuits, ladder diagrams, PLC applications in fluid power control. Fluid power circuits, failure and troubleshooting. Design of Pneumatic circuits for metal working, handling, clamping counter and timer circuits. – Low cost Automation – Hydraulic and Pneumatic power packs. Case studies: A simple sequence, synchronize circuits using hydraulic and pneumatics components. | UNIT | T IV | PNEUMATIC AND ELECTRO PNEUMATIC SYST | EMS | | 9 | 0 | 09 | | | | |
| Servo systems, Hydro mechanical servo systems, electro hydraulic servo systems and proportional Valves, Introduction to electro hydraulic pneumatic logic circuits, ladder diagrams, PLC applications in fluid power control. Fluid power circuits, failure and troubleshooting. Design of Pneumatic circuits for metal working, handling, clamping counter and timer circuits. – Low cost Automation – Hydraulic and Pneumatic power packs. Case studies: A simple sequence, synchronize circuits using hydraulic and pneumatics components. | Exhau - Casc | st Valves, ade metho | Pneumatic actuators, Design of Pneumatic circuit – classification d – Integration of fringe circuits, Electro Pneumatic System – | n - single cylinder a | nd mul | ti cyli | nder | circuits | | | | |
| electro hydraulic pneumatic logic circuits, ladder diagrams, PLC applications in fluid power control. Fluid power circuits, failure and troubleshooting. Design of Pneumatic circuits for metal working, handling, clamping counter and timer circuits. – Low cost Automation – Hydraulic and Pneumatic power packs. Case studies: A simple sequence, synchronize circuits using hydraulic and pneumatics components. | UNIT | UNIT V DESIGN OF FLUID POWER CIRCUITS AND TROUBLESHOOTING | | | | | | | | | | |
| Total (45L) = 45 Periods | electro failure – Low | o hydrauli e and troub v cost Aut | e pneumatic logic circuits, ladder diagrams, PLC applications in leshooting. Design of Pneumatic circuits for metal working, har omation – Hydraulic and Pneumatic power packs. Case studie | n fluid power contr ndling, clamping co | ol. Flu ounter a | id por and tim | wer c mer c | ircuits, ircuits. | | | | |
| Total (45L) = 45 Periods | | | | | | | | | | | | |
| | | | | Tot | al (45) | L) = | 45 P | eriods | | | | |

| Text I | Books: |
|--------|---|
| 1. | Manjumdar S.R, "Oil Hydraulics", Tata McGraw-Hill, December 2002. |

| 2. | Anthony Esposito, "Fluid Power with Applications", Pearson Education 2013. |
|--------|---|
| Refere | ence Books: |
| 1. | Andrew Parr, "Hydraulic and Pneumatics", Jaico Publications House, 2005. |
| 2. | Bolton W. "Pneumatic and hydraulic system", Butterworth-Heinemann 1997 |
| 3. | Majumdar S.R., "Pneumatic systems – Principles and maintenance", Tata McGraw Hill, 2010 |
| 4. | Shanmugasundaram.K, "Hydraulic and Pneumatic controls", Chand & Co, 2006 |
| 5. | Srinivasan.R. "Hydraulic and Pneumatic Controls", Vijay Nicole Imprints, 2008. |
| E-Refe | erences: |
| 1. | http://www.fluidpowerjournal.com |
| 2. | http://14.139.160.15/courses/112102011/2 |
| 3. | https://www.nfpa.com/home.htm |

| | COURSE OUTCOMES: Upon completion of the course, the students will be able to: | | | | | | | |
|------------|--|----------|--|--|--|--|--|--|
| C01 | Select the components as per the application | Evaluate | | | | | | |
| <i>CO2</i> | Apply the working principles of hydraulic actuators and control components. | Apply | | | | | | |
| СО3 | Design and develop hydraulic circuits and systems. | Create | | | | | | |
| <i>CO4</i> | Apply the working principles of pneumatic power system and its components. | Apply | | | | | | |
| <i>C05</i> | Solve problems and troubles in fluid power systems. | Evaluate | | | | | | |

| COURSE A | ARTI | CULA | TIO | N MA | TRIX | K | | | | | | | | | |
|----------|------|------|---------|--------|--------|-------|-------|---------|-------|---------|--------|----------|------|------|------|
| COs/POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
| CO1 | 2 | 1 | 1 | | | | | | | | | | 1 | 1 | 1 |
| CO2 | | 2 | 2 | 1 | | | | | | | | | 1 | 1 | 1 |
| CO3 | 1 | 2 | 3 | | | 1 | | | | | | | 1 | 2 | 1 |
| CO4 | 1 | 1 | 3 | 2 | 2 | | | | | | | | 2 | 1 | 1 |
| CO5 | 1 | 1 | 2 | | | | | | | | | | 1 | 1 | 1 |
| Avg | 1.25 | 1.4 | 2.2 | 1.5 | 2 | 1 | | | | | | | 1.2 | 1.2 | 1 |
| | • | 3/2/ | /1 – ir | ndicat | es str | ength | of co | rrelati | on (3 | – High, | 2- Mec | lium, 1- | Low) | | |

| 18M | EM07 | DESIGN OF MACHINE ELEMEN | TS | | | | | | |
|----------------|--|--|---|------------|--------|--------|---------|--|--|
| PRE | REQUIS | SITE: | CATEGORY | PE | Cre | edit | 3 | | |
| 1. | | should study engineering mechanics. | Houng/Wools | L | Т | Р | ТН | | |
| 2. | Studen | should study kinematic of machinery. | Hours/Week | 3 | 0 | 0 | 3 | | |
| Cour | se Objec | tives: | | | | | | | |
| 1. | Understa | nding of background in mechanics of materials and design of | of machine componen | nts. | | | | | |
| 2. | An unde consider | erstanding of the origins, nature and applicability of eations | empirical design pri | inciples, | based | l on | safety | | |
| 3. | An unde | rstanding the design of shafts and couplings. | | | | | | | |
| 4. | Familiar | ze the design of energy storing elements and engine compo | nents. | | | | | | |
| 5. | 5. An appreciation of the relationships between component level design and overall machine system design and performance | | | | | | | | |
| UNI | CHINE | 9 | 0 | 0 9 | | | | | |
| based Calcu | on mecha lation of p | he design process – Product development cycle- factors inf nical properties - Preferred numbers– Direct, Bending and rinciple stresses for various load combinations, eccentric le ion – design for variable loading – Soderberg, Goodman and | Torsional stress – Ir oading – Factor of s | npact and | l shoc | ck loa | ading – | | |
| UNI | ГП | DESIGN OF SHAFTS AND COUPLINGS | | | 9 | 0 | 09 | | |
| - | | and hollow shafts based on strength, rigidity and critical spe e couplings. | eed – Design of keys | and key | ways | - De | sign of | | |
| UNI | ГШ | DESIGN OF THREADED FASTENERS, RIV JOINTS | YETED AND WI | ELDED | 9 | 0 | 0 9 | | |
| | | ers - Design of bolted joints including eccentric loading – E etures- theory of bonded joints. | Design of riveted and | welded j | oints | for p | ressure | | |
| UNI | UNIT IV DESIGN OF ENERGY STORING ELEMENTS AND ENGINE COMPONENTS | | | | | | | | |
| | • • | Springs, optimization of helical springs - rubber springs - F punching machines- Connecting rods and crank shafts. | Flywheels considering | g stresses | in rir | ns ar | id arms | | |
| UNI | ΓV | DESIGN OF BEARINGS | | | 9 | 0 | 09 | | |
| | g contact a ct bearings | and rolling contact bearings - Hydrodynamic journal bearin s. | gs, Sommerfeld Nun | nber - Se | lectio | n of I | Rolling | | |
| | | | Т | otal (45 | L) = | 45 P | eriods | | |

| Text E | Books: | | | | | | | | | |
|--------|---|--|--|--|--|--|--|--|--|--|
| 1. | Bhandari V.B, "Design of Machine Elements", Tata McGraw Hill Book Co, 2020 | | | | | | | | | |
| 2. | Md.Jalaludeen.S, "A text book of Machine Design", Anuradha Publications, 2006 | | | | | | | | | |
| Refere | Reference Books: | | | | | | | | | |
| 1. | Shigley, J.E. and Mischke, C.R., Mechanical Engineering Design, Fifth Edition, McGraw-Hill International; 1989. | | | | | | | | | |
| 2. | Deutschman, D., Michels, W.J. and Wilson, C.E., Machine Design Theory and Practice, Macmillan, 1992. | | | | | | | | | |

| 3. | Juvinal, R.C., Fundamentals of Machine Component Design, John Wiley, 1994. | | | | | | | |
|--------|---|--|--|--|--|--|--|--|
| 4. | PSG Tech, "Design Data Handbook", M/s.DPV Printers, Coimbatore, 2009 | | | | | | | |
| E-Refe | erences: | | | | | | | |
| 1. | https://nptel.ac.in/courses/112105124 | | | | | | | |
| 2. | Design of Machine Elements - V. B. Bhandari - Google Books | | | | | | | |
| 3. | A Textbook of Machine Design by R.S.Khurmi And J.K.Gupta [tortuka] 1490186411865.pdf DocDroid | | | | | | | |

| | RSE OUTCOMES: ompletion of the course the student will be able to | Bloom's Taxonomy Mapped |
|------------|---|-------------------------------|
| C01 | Understand the influence of steady and variable stresses in machine component design. | Understand |
| <i>CO2</i> | Apply the concepts of design to shafts, keys and couplings. | Apply |
| СОЗ | Familiarize the design of temporary and permanent joints. | Understand |
| <i>CO4</i> | Design the various energy storing elements and engine components. | Analyse |
| <i>C05</i> | Familiarize the design of various types of bearings. | Understand |

| COs/POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|---------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| CO1 | 2 | 2 | 1 | 2 | | 1 | 1 | | | | 1 | | 3 | 2 | 1 |
| CO2 | 2 | 2 | 1 | 2 | | 1 | 1 | | | | 1 | | 3 | 2 | 1 |
| CO3 | 2 | 2 | 1 | 2 | | 1 | 1 | | | | 1 | | 3 | 2 | 1 |
| CO4 | 2 | 2 | 1 | 2 | | 1 | 1 | | | | 1 | | 3 | 2 | 1 |
| CO5 | 2 | 2 | 1 | 2 | | 1 | 1 | | | | 1 | | 3 | 2 | 1 |
| Avg | 2.0 | 2.0 | 1.0 | 2.0 | | 1.0 | 1.0 | | | | 1.0 | | 3.0 | 2.0 | 1.0 |

| 2. The concCOURSE1. | and l | pasic concepts of thermodynamics | CATEGORY | PE | Cre | edit | 3 | | | |
|-----------------------|--|--|--------------------|----------|---------|---------|------------|--|--|--|
| 2. The concCOURSE1.Un | cept o | | | | | | - - | | | |
| COURSE | • | f an anna fan an 14 air an ann air air 1 a | TT /TT/ | L | Т | Р | ТН | | | |
| 1. Un | OB | f energy transfers and their conversion principles | Hours/Week | 3 | 0 | 0 | 3 | | | |
| | | JECTIVES | | 11 | | | | | | |
| | nderst | anding the science behind conduction heat transfer and its applica | tions. | | | | | | | |
| 2. Di | Differentiating the concepts of forced and natural convection heat transfer. | | | | | | | | | |
| 3. De | escrib | ing the laws and concepts of radiation heat transfer. | | | | | | | | |
| 4. Un | Understanding phase change processes and analyzing heat exchangers. | | | | | | | | | |
| 5. Stu | udyin | g the concept of mass transfer process and its modes. | | | | | | | | |
| UNIT-I | 9 | 0 | 0 | 9 | | | | | | |
| charts. | I | ces – Unsteady Heat Conduction – Lumped Analysis – Semi Inf CONVECTION HEAT TRANSFER | | 9 | 0 | 0 | 9 | | | |
| | | uations, boundary layer concept – Forced convection: external fles. Internal flow – entrance effects. | ow – flow over pl | ates, cy | linde | ers, sp | heres | | | |
| | | -flow over vertical plate, horizontal plate, inclined plate, cylinder | s and spheres. | | | | | | | |
| UNIT-II | Π | BOILING, CONDENSATION AND HEAT EXCHANG | FERS | 9 | 0 | 0 | 9 | | | |
| | | boiling and Flow boiling, Nusselt's theory of condensation- corr - Overall Heat Transfer Co-efficient – Fouling Factors. LMTD a | | and con | dens | ation. | Heat | | | |
| UNIT-I | IT-IV RADIATION HEAT TRANSFER | | | | | 0 | 9 | | | |
| Radiation la | aws - | Black Body and Gray body Radiation - Shape Factor - Electrical | Analogy -Radiatio | n Shield | nields. | | | | | |
| UNIT-V | V | MASS TRANSFER | | 9 | 0 | 0 | 9 | | | |
| | | - Diffusion Mass Transfer – Fick's Law of Diffusion – Steady state Convective Mass Transfer Problems. | e Molecular Diffus | ion - Eq | uimo | olal co | unter | | | |
| | | | Tot | al(45L) |) = 4 | 5 Pe | riods | | | |

| ТЕХТ | BOOKS: | | | | | | | |
|------|---|--|--|--|--|--|--|--|
| 1 | R.C. Sachdeva, "Fundamentals of Engineering Heat & Mass transfer", New Age International Publishers, 2017 | | | | | | | |
| 2 | Frank P. Incropera and David P. Dewitt, "Fundamentals of Heat and Mass Transfer", John Wiley & Sons, 7th Edition, 2014. | | | | | | | |
| REFE | REFERENCE BOOKS: | | | | | | | |
| 1 | Yunus A. Cengel, "Heat Transfer A Practical Approach" – Tata McGraw Hill, 5 th Edition - 2013 | | | | | | | |
| 2 | Holman, J.P., "Heat and Mass Transfer", Tata McGraw Hill, 2017 | | | | | | | |
| 3 | Kothandaraman, C.P., "Fundamentals of Heat and Mass Transfer", New Age International, New Delhi, 2012 | | | | | | | |
| 4 | Ozisik, M.N., "Heat Transfer", McGraw Hill Book Co., 1994. | | | | | | | |

| | RSE OUTCOMES: mpletion of the course the student will be able to: | Bloom's Taxonomy Mapped |
|------------|---|-------------------------------|
| C01 | Analyze the mechanism of heat conduction under steady and transient conditions. | Apply |
| <i>CO2</i> | Develop solutions to problems involving convective heat transfer. | Create |
| СОЗ | Design a heat exchanger for any specific application. | Understand |
| <i>CO4</i> | Adopt the concept of radiation heat transfer in real time systems. | Understand |
| <i>C05</i> | Develop solutions to problems involving combined heat and mass transfer. | Apply |

| COs/POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|---------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| CO1 | 3 | 3 | 3 | 3 | 2 | | 1 | | | | | | 3 | 3 | 1 |
| CO2 | 3 | 3 | 3 | 3 | 2 | | 1 | | | | | | 3 | 3 | 1 |
| CO3 | 3 | 3 | 3 | 3 | 2 | | 1 | | | | | | 3 | 3 | 1 |
| CO4 | 3 | 3 | 3 | 3 | 2 | | 1 | | | | | | 3 | 2 | 1 |
| CO5 | 2 | 2 | 2 | 2 | 1 | | 1 | | | | | | 3 | 1 | |
| Avg | 2.8 | 2.8 | 2.8 | 2.8 | 1.8 | | 1 | | | | | | 3 | 2.4 | 1 |

| 18MEM09 | METROLOGY AND QUALITY CONTR | OL | | | | | |
|--|--|-------------------------------------|------------------|--------------|----------------|-------------|---------------|
| PREREQUIS | SITES | CATEGORY | PE | Cr | edit | | 3 |
| | | | L | Т | Р | , | ГН |
| | | Horus/Week | 3 | 0 | 0 | | 3 |
| COURSE OF | SJECTIVES | | | 1 | 1 | | |
| 1. | Explaining the importance of measurements in engineering and compute measurement uncertainty | the factors affecting | g measu | irem | ents a | and | to |
| 2. | Applying the applications of linear and angular measuring instr | uments | | | | | |
| 3. | Interpretation of various tolerance symbols. | | | | | | |
| 4. | Applying the SQC methods in manufacturing. | | | | | | |
| 5. | Applying the advances in measurements for quality control. | | | | | | |
| | | | | | | | |
| UNIT-I | BASICS OF MEASUREMENT SYSTEM AND DEVIC | CES | | 9 | 0 | 0 | 9 |
| | nical loading – static characteristics of instruments – factors consid or analysis and classification - sources of error. Measurement unce CALIBRATION OF INSTRUMENTS AND QUALITY | rtainty. | nstrum | ents | - con | 0 | only 9 |
| feeler gauges, d | I neasuring instruments - principles of calibration, Calibration of I lial indicator, surface plates, slip gauges, care of gauge blocks. Ge indards. Comparators- mechanical, electrical, optical and pneumat | eneral cares and rule | | | | | |
| UNIT-III | GEOMETRICAL MEASUREMENT AND MACHINE | E ELEMENTS | | 9 | 0 | 0 | 9 |
| principle, three measurement o errors, base pito | rement - optical protractors, sine bar, roundness measurement, li basic types of limit gauges, Tomlinson surface meter, compu f major, minor and effective diameters. Gear terminology; spur ch measurement. Principle of interferometry, laser interferometer raightness, flatness, roundness deviations. | ter controlled CM gear measurement, | M. ISO checki |) me ng o | etric f cor | thre npo | ead, osite |
| UNIT-IV | STATISTICAL QUALITY CONTROL | | | 9 | 0 | 0 | 9 |
| | terminology and measurements – Optical measuring instruments Control charts - Sampling plans. | Acceptance test f | for mac | hine | s. Sta | atist | ical |
| UNIT-V | SIX SIGMA | | | 9 | 0 | 0 | 9 |
| Control chart, S | ne measure, analyse, improve and control phases. Analyze phase t Scatter chart, Cause and effect diagram, Pareto analysis, interrel thesis Testing, ANOVA Multi variate analysis. | | | | | | |
| | | Tot | al(45L | .) = (| 45 P | eri | ods |

| TEXT | TEXT BOOKS: | | | | | | | | |
|------|---|--|--|--|--|--|--|--|--|
| 1 | Gupta.I.C, —A text book of Engineering Metrology, Dhanpat Rai publications, New Delhi, 2018 | | | | | | | | |
| 2 | Beckwith.T.G, Roy D. Marangoni, John H. Lienhard, - Mechanical Measurements, Prentice Hall, 2006 | | | | | | | | |
| REFE | REFERENCE BOOKS: | | | | | | | | |
| 1 | Jain.R.K, —Mechanical and Industrial Measurements, Khanna Publishers, Delhi, 1999. | | | | | | | | |
| 2 | Holmen.J.P, —Experimental Methods for Engineersl, Tata McGraw Hill Publications Co Limited, 2017. | | | | | | | | |

| 3 | Grant, E.L., Statistical Quality Control, Mc Graw-Hill, 2004. 3. Doeblin E.O., Measurement Systems, Mc Graw-Hill, 2004. | | | | | | | |
|-------|---|--|--|--|--|--|--|--|
| 4 | Alan S Morris,Measurement and Instrumentation Principles, Butterworth, 2006. | | | | | | | |
| 5 | De Feo J A and Barnard W W, —Six Sigma: Break trough and BeyondG, Tata McGraw-Hill, New Delhi, 2005. | | | | | | | |
| E-REF | E-REFERENCES: | | | | | | | |
| 1 | https://nitsri.ac.in/Department/Mechanical%20Engineering/MEC_405_Book_2,_for_Unit_2B.pdf | | | | | | | |
| 2 | https://www.nist.gov/system/files/documents/srm/NIST-SRM-RM-Articlefinal.pdf | | | | | | | |
| 3 | https://www.researchgate.net/publication/319587859_Computer-Aided_Metrology-CAM | | | | | | | |

| | RSE OUTCOMES: mpletion of the course the student will be able to: | Bloom's Taxonomy Mapped |
|------------|--|-------------------------------|
| C01 | Explain the importance of measurements in engineering and the factors affecting measurements and to compute measurement uncertainty. | Understand |
| <i>CO2</i> | Apply the working principle and the applications of linear and angular measuring instruments. | Apply |
| СОЗ | Interpret of various tolerance symbols. | Apply |
| <i>CO4</i> | Apply the SQC methods in manufacturing. | Apply |
| <i>C05</i> | Apply the advances in measurements for quality control in manufacturing industries. | Apply |

| COs/POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|---------|-----|-----|-----|-----|-----|-----|------|------------|-----|------|------|------|------|------|------|
| CO1 | | | | | | | 2 | 1 | 2 | | | | 2 | 1 | |
| CO2 | | | | | | | 3 | 1 | 2 | | | | 1 | 2 | |
| CO3 | | | | | | | 2 | 1 | | | | | 2 | 1 | |
| CO4 | | | | 3 | | | 2 | | 1 | | | | 1 | 2 | |
| CO5 | | | | 2 | | | | 3 | 1 | | | | 2 | 1 | |
| Avg | 1 | | | 2.5 | | | 2.25 | 1.5 | 1.5 | | | | 1.6 | 1.4 | |

| 18 | MEMI | 10 | DYNAMICS OF MACHINERY | | | | | |
|------------|----------------------|---------|--|----------------------|------------|-------------|--------|----------|
| PR | EREQU | UISI | res | CATEGORY | PE | Cre | edit | 3 |
| En | | M1 | wing Wingson of Mashington Strength of Materials | Hound Wools | L | Т | Р | ТН |
| Eng | ineering | Mecr | nanics, Kinematics of Machinery, Strength of Materials | Hours\Week | 3 | 0 | 0 | 3 |
| CC | URSE | OBJ | ECTIVES: | | | | | |
| 1. | To imp | art sti | udents with the knowledge about motion, masses and forces in | machines and the F | Principl | e of V | irtual | Work. |
| 2. | To faci | litate | the students, to understand the concept of balancing of rotating | g and reciprocating | masse | s. | | |
| 3. | To teac | ch con | cepts of free vibration analyses of one and two degree-of-free | dom rigid body sys | tems | | | |
| 4. | | | ncepts of forced vibrations analyses of rigid body systems a of vibration and its effects. | and to give awar | eness to | o stuc | lents | on the |
| 5. | To lear | n abo | ut the concept of various types of governors. | | - | | | |
| U | NIT I | FO | RCE ANALYSIS | | 9 | 0 | 0 | 9 |
| Spe | | ght of | s and Fluctuation of Energy of reciprocating engine mechanis Flywheel Required. LANCING | ns, Coefficient of I | Fluctuat 9 | ion of 0 | Ener | gy and 9 |
| | | | c balancing - Balancing of rotating masses - Balancing a single balancing in locomotive Engines - Balancing linkages - balanc | | Balanc | ing M | ulti-c | ylinder |
| - | | | EE VIBRATION | 0 | 9 | 0 | 0 | 9 |
| Fre Sys | quency b tem -Typ | by En | Vibratory Systems – Types – Single Degree of Freedom System ergy Method, Dunkerly's Method - Critical Speed - Damped Damping – Free Vibration with Viscous Damping, Critically s: Natural Frequency of Two and Three Rotor Systems. | Free Vibration of | Single | Deg | ee Fr | eedom |
| UN | IT IV | FO | RCED VIBRATION | | 9 | 0 | 0 | 9 |
| | • | | odic Force – Harmonic Force – Force caused by Unbalance – ctor – Vibration Isolation and Transmissibility. | Support Motion - | Logari | thmic | Decr | ement- |
| U | V TIN | GC | OVERNORS | | 9 | 0 | 0 | 9 |
| | | | s - Centrifugal governors - Gravity controlled and spring contro a - Controlling Force - other governor mechanisms. | olled centrifugal go | overnor | s – Cł | aract | eristics |
| | | | | То | tal (45 | L) = | 45 P | eriods |
| | | _ | | | _ | _ | _ | |

| TE | XT BOOKS: |
|----|--|
| 1. | Design of Machinery, Fourth Edition, by R.L. Norton, McGraw Hill, 2007 |
| 2. | Mechanical Vibration, V.P.Singh, Dhanpatrai, Delhi |
| RE | FERENCE BOOKS: |
| 1. | Ballaney, P.L., "Theory of Machines and Mechanisms", Khanna Publishers, New Delhi, 2002. |
| 2. | Shigley, J.E. and Uicker, J.J., "Theory of Machines and Mechanisms", TMH ND, 1998. |
| 3. | Amithabha Ghosh, and Ashok Kumar Malik., "Theory of Mechanisms and Machines", 2nd Ed., Affiliated East and West Press Limited, 1998. |
| 4. | Prof.Nakara, IIT-Delhi Reference Books |
| | · |

| E-R | E-REFERENCES: | | | | | | | |
|-----|---|--|--|--|--|--|--|--|
| 1. | www.university.youth4work.com/IIT_Kharagpur_Indian-Institute-of-Technology/study/1653-dynamics-of- Machinery-ebook | | | | | | | |
| 2. | http://nptel.ac.in/courses/112104114/ | | | | | | | |
| | · | | | | | | | |

| | RSE OUTCOMES: | Bloom's Taxonomy Mapped |
|------------|---|-------------------------------|
| C01 | Apply basic principles of mechanisms in mechanical system. | Apply |
| <i>CO2</i> | Familiarize the static and dynamic analysis of simple mechanisms. | Understand |
| СО3 | Analyze the mechanical systems subjected to free vibration. | Analyze |
| <i>CO4</i> | Analyze mechanical systems subjected to forced vibration. | Analyze |
| C05 | Analyze the various types of governors and its speed control mechanism. | Analyze |

| COs/POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|---------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| CO1 | 2 | 2 | 3 | 3 | 1 | | | | | 1 | | 3 | 2 | 1 | 2 |
| CO2 | 2 | 2 | 3 | 2 | 1 | | | | | 1 | | 3 | 2 | 1 | 2 |
| CO3 | 2 | 2 | 3 | 2 | | | | | | 1 | | 3 | 2 | 1 | 2 |
| CO4 | 2 | 2 | 3 | 2 | 1 | | | | | 1 | | 3 | 2 | 1 | 2 |
| CO5 | 1 | 2 | 3 | 2 | | | | | | 1 | | 3 | 2 | 1 | 1 |
| Avg | 1.8 | 2.0 | 3.0 | 2.2 | 1 | | | | | 1.0 | | 3.0 | 2.0 | 1.0 | 1.8 |

MINOR DEGREE: METALLURGICAL ENGINEEING

| 18N | ATM01 | ADVANCED PHYSICAL METALL | URGY | S | emeste | r | | | | |
|--|-------------------------|--|----------------------|----------|-----------|----------|---------|--|--|--|
| PREF | REQUISIT | ES | Category | OE | Cre | dit | 3 | | | |
| Б. | • 1 | | | L | Т | Р | ТН | | | |
| Engin | eering phy | /SICS | Hours/Week | 3 | 0 | 0 | 3 | | | |
| Course Learning Objectives | | | | | | | | | | |
| 1 To impart knowledge on the crystal structure, diffusion, phase diagrams for various engineering materials. | | | | | | | | | | |
| τ | J nit I | CRYSTAL STRUCTURES | | 9 | 0 | 0 | 9 | | | |
| Revie | w of atomic | c bonds, Lattice, unit cell, crystal systems and Bravai | s lattices; Princip | al crys | tal struc | ctures - | - BCC, | | | |
| | | ts characteristics; Miller indices for crystallographic | | • | | | | | | |
| Volun | ne, planar a | and linear atomic density; Polymorphism and allotro | py; CsCl, NaCl, | Diamo | ond stru | ctures; | single | | | |
| crysta | l and polyc | rystalline and amorphous materials; isotropy and aniso | otropy; Simple pr | oblems | s in the | above t | opics | | | |
| U | nit II | 9 | 0 | 0 | 9 | | | | | |
| Types | of point de | efects, effect of temperature on vacancy concentratio | n, interstitial site | s-octał | edral a | nd tetra | ahedral | | | |
| sites; | Line defect | s - dislocations - Edge, screw and mixed dislocation | ns, Burger's vecto | r, slip | and twi | nning; | Planar | | | |
| defect | as – grain ł | boundaries, tilt boundaries, small angle grain bound | laries; ASTM gra | ain size | e numb | er, gra | in size | | | |
| detern | ninations; V | olume defects; Simple problems in the above topics. | | | | | | | | |
| U | nit III | ATOMIC DIFFUSION IN SOLIDS AND SOLII OF METAL | DIFICATION | 9 | 0 | 0 | 9 | | | |
| Diffus | sion mecha | nisms, steady state diffusion and non-steady state | diffusion-Fick's | first 1 | aw and | secon | d law; | | | |
| Kirker | ndall effect | and Darken's equation; Factors affecting diffusion; I | Industrial applicat | ions o | f diffusi | on pro | cesses; | | | |
| Simpl | e problems | in the above topics; Basic principles of solidification | on of metals and | alloys; | Growt | h of cr | ystals– | | | |
| Planar | r growth, o | lendritic growth, Solidification time, dendrite size | ; Cooling curves | s; Cas | t or In | got str | ucture, | | | |
| Solidi | fication de | fects - Control of casting structure; Directional so | lidification – sin | gle cry | ystal gr | owth; | Simple | | | |
| proble | ems in the a | bove topics. | | | | | | | | |
| | nit IV | PHASE DIAGRAMS | | 9 | 0 | 0 | 9 | | | |
| Phase | s, solid sol | ution types, compounds, Hume- Rothery rules; Gibb | o's phase rule; Ph | ase di | agram d | letermi | nation; | | | |
| - | - | ous alloy systems - composition and amount of phases | - | | | - | | | | |
| | - | um cooling- Coring and its effects, homogenization | • | • | | - | | | | |
| | - | , development of microstructure; Eutectoid, Peritectic | | | | diagran | ns with | | | |
| interm | nediate phas | ses and compounds; Ternary phase diagrams. Simple j | problems in the al | pove to | pics. | | | | | |
| U | Init V | IRON-CARBON PHASE DIAGRAM | | 9 | 0 | 0 | 9 | | | |
| | Ū. | am, Phases in Fe-C system, Invariant reactions, Micro | | • | | - | | | | |
| | - | nases, Effect of Alloying elements on Fe-C system, T | • • • | - | | | | | | |
| | | els and different types of Cast iron; IS Specification f | for Steels and Cas | t Irons | , Simpl | e probl | ems in | | | |
| above | topics. | | | | | | | | | |
| | Total (45+0) = 45 Hours | | | | | | | | | |

| Tex | t Books: |
|------|---|
| 1 | Donald R. Askeland,"The Science and Engineering of Materials", Thomson Learning, India Edition, 2007. |
| 2 | William D.Callister, "Materials Science and Engineering – An Introduction", 4th edition, JohnWiley & Sons, New York, USA, 1997. |
| Refe | rence Books: |
| 1 | Avner S H."An Introduction to Physical Metallurgy", McGraw Hill Book Co, New York, USA, 1997. |
| 2 | Donald R Askeland," Essentials of Material Science and Engineering ", Thomson Learning, India Edition, 2007 |
| 3 | Raghavan V., "Physical Metallurgy – Principles and Practice", Prentice Hall of India Ltd., New Delhi, 199. |
| 4 | William F.Smith, "Foundations of Materials Science and Engineering", Second Edition, McGraw-Hill Inc, New York, 1993. |

| | | utcomes: npletion of this course, the students will be able to: | Bloom's Taxonomy Mapped | | |
|-----|----|---|-------------------------------|--|--|
| CO1 | •• | Describe the basic crystal structure, orientation and their influence on macroscopic properties. | L2: Understanding | | |
| CO2 | : | Discuss the role of imperfections in strengthening the materials. | L2: Understanding | | |
| CO3 | : | Diagonise the diffusion mechanism in solidification of materials under different conditions. | L4:Analysing | | |
| CO4 | : | Apply the concept of phase diagrams in equilibrium transformation of materials phases. | L3:Applying | | |
| CO5 | : | Construct the Fe-Fe ₃ C phase diagram and discuss various properties of steel and cast iron. | L3:Applying | | |

| COURS | E ART | ICULA | TION | MATR | <u>XIX</u> | | | | | | | | | | | |
|-------|-------|-------|------|------|------------|----------|------------|---------|----------|----------|-----------|--------|-----------|------|------|------|
| CO/PO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 | PSO4 |
| CO1 | 1 | 1 | | 1 | 1 | | | | | | | | 1 | | 1 | |
| CO2 | 1 | 1 | | | | 1 | 1 | | | | | | 1 | | | 1 |
| CO3 | 1 | 1 | 1 | 1 | | 1 | | | | | | | 1 | 1 | | |
| CO4 | 1 | 1 | | 1 | 1 | | | | | | | | 1 | | | |
| CO5 | 1 | 1 | | 1 | | | | | | | | | 1 | | | 1 |
| Avg. | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | | | | | | 1.0 | 1.0 | 1.0 | 1.0 |
| | | | | | | 3/2/1-in | dicates | strengt | h of cor | relation | (3- High, | 2-Medi | um, 1- Lo | ow) | | |

| 18MTM02 | THERMODYNAMICS AND KINETICS IN | METALLURGY | S | emest | er | |
|---------------------------------------|---|-----------------------|---------|--------|---------------|----------|
| PREREQUISIT | ES | Category | OE | Cr | edit | 3 |
| D · · · 1 | | | L | Т | Р | ТН |
| Engineering ph | ysics and Engineering chemistry | Hours/Week | 3 | 0 | 0 | 3 |
| Course Learnin | g Objectives | | | | | |
| 1 | the basic principles and concepts of thermodynamics | in the field of Meta | llurgy | and m | aterials | s; and |
| to learn a | bout equations and their applications. | | r | 1 | r | |
| Unit I | L ENERGY | 9 | 0 | 0 | 9 | |
| processes, Thern and work, Interna | stem and surrounding, Classification of systems, nodynamic equilibrium, Reversible and Irreversible p al energy, Heat capacity of materials, Cp-Cv relations, noff's law, Maximum flame temperature. | processes. First law | of the | rmody | ynamic | s: Heat |
| Unit II | 9 | 0 | 0 | 9 | | |
| statement of first | ermodynamics: Carnot cycle, Entropy - Statistical inte and second laws, Thermodynamic functions - Maxwel of thermodynamics : Definition, concept and applicati | ll's relations, Gibbs | • | | | |
| Unit III | THERMODYNAMIC POTENTIALS AND PHA EQUILIBRIA | SE | 9 | 0 | 0 | 9 |
| rule. Le Chateli Thermodynamic | potentials: Fugacity, Activity and Equilibrium consta er's principle, Vant Hoff's equation. Equilibria in p s of surfaces, interfaces and defects, P-G-T diagram tudy of alloy systems. | ohase diagrams: Ph | nase ru | le, Pl | hase st | ability, |
| Unit IV | THERMODYNAMICS OF SOLUTIONS | | 9 | 0 | 0 | 9 |
| solutions, Activi | quation, Partial and integral molar quantities, chemica ty coefficient, Henry's law, Alternative standard state ar solutions, Applications of Gibbs - Duhem equation. | s, Sievert's law, Mi | | | | - |
| Unit V | THERMODYNAMICS OF REACTIONS AND I | KINETICS | 9 | 0 | 0 | 9 |
| quantities using | process: Cells, Interconversion of free energy and electroversible cells, Solid electrolytic cells. Kinetics: First tion energy, Determination of order of the reaction. | | | | | |
| | | | Total | (45+(|) = 45 | Hours |

| Tex | t Books: |
|------|--|
| 1 | Upadhyaya G S andDube R K., "Problems in Metallurgical Thermodynamics & Kinetics", Pergamon, 1977. |
| 2 | Ahindra Ghosh, Text book of Materials & MetallurgicalThermodynamics, Prentice Hall India, 2002 |
| 3 | . David R Gaskell, "Introduction to the Thermodynamics of Materials", Fifth Edition, Taylor & Francis, 2008 |
| Refe | rence Books: |
| 1 | David V Ragone, "Thermodynamics of Materials - Volume-1", John Wiley & Sons, Inc. 1995. |
| 2 | Dr S.K Dutta,Prof A.B.Lele – Metallurgical thermodynamics kinetics and numericals,S.Chand& co Ltd.,New Delhi 2011 |
| 3 | Darken LS and Gurry R W,"Physical Chemistry of Metals", CBS publications and distributors, 2002. |
| 4 | Parker R H, "An introduction to chemical metallurgy", Pergamon press, New York, second edition, 1978. |
| 5 | Kapoor M.L., "Chemical and Metallurgical Thermodynamics Vol. I and II", Nem Chand, 1st Ed., 1981 |

| | Course Outcomes: Upon completion of this course, the students will be able to: | | | | | | | |
|-----|---|--|-------------------|--|--|--|--|--|
| CO1 | : | Discuss the fundamental concepts of thermodynamics and internal energy | L2: Understanding | | | | | |
| CO2 | : | State the thermodynamics entropy and auxiliary functions. | L2: Understanding | | | | | |
| CO3 | : | Identify the basic laws, chemical potential and phase equilibria. | L4:Analysing | | | | | |
| CO4 | : | Describe the thermodynamics of the solution and various important equations. | L2: Understanding | | | | | |
| CO5 | : | Apply to solve problems related to electrochemical processes and kinetics. | L3:Applying | | | | | |

| COURS | E ART | ICULA | TION | MATR | <u>XIX</u> | | | | | | | | | | | |
|-------|------------|-------|------|------|------------|----------|------------|---------|------------|----------|-----------|--------|-----------|------|------|------|
| CO/PO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 | PSO4 |
| CO1 | 1 | 1 | | 1 | 1 | | | | | | | | 1 | 1 | | |
| CO2 | 1 | 1 | 1 | | | | | | | | | | 1 | | 1 | |
| CO3 | 1 | 1 | | 1 | 1 | | | | | | | | 1 | | | |
| CO4 | 1 | | | 1 | 1 | | | | | | | | 1 | | 1 | 1 |
| CO5 | 1 | 1 | | | | 1 | 1 | | | | | | 1 | | 1 | |
| Avg. | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | | | | | | 1.0 | 1.0 | 1.0 | 1.0 |
| | | | | | | 3/2/1-in | dicates | strengt | h of coi | relation | (3- High, | 2-Medi | um, 1- Lo | ow) | | |

| 18M7 | ГМ03 | MECHANICAL BEHAVIOUR OF MAT | FERIALS | S | Semeste | er | | | | | |
|---|--------------------------------------|---|-----------------------------------|------------------|---------------------------------|-----------------|---------------------|--|--|--|--|
| PRERI | EQUISIT | TES | | OE | Cre | edit | 3 | | | | |
| Encino | | | | L | Т | Р | ТН | | | | |
| Engine | ering ph | ysics | Hours/Week | 3 | 0 | 0 | 3 | | | | |
| Course | e Learnir | ng Objectives | I | | | | | | | | |
| 1 | To know | the fundamental concepts of deformation behaviour f | for structural engin | neering | applica | ations. | | | | | |
| Un | it I | DISLOCATIONS AND PLASTIC DEFORMATIC | ON | 9 | 0 | 0 | 9 | | | | |
| Strength of perfect crystal and need for dislocations; Characteristics of dislocations – Edge dislocation, Screw dislocation, Burger's vector, mixed dislocation, dislocation loops; Movement of dislocation – Pierls stress, Cross slip, Climb; Dislocations in FCC, HCP and BCC lattice; Stress fields and energies of dislocations, forces on and between dislocations; Dislocation density; Intersections of dislocations – Jogs and kinks; Dislocation multiplication; Dislocation pile-ups; Deformation by slip and twinning; Critical resolved shear stress; Deformation bands and kink bands. | | | | | | | | | | | |
| Uni | Unit IISTRENGTHENING MECHANISMS9009 | | | | | | | | | | |
| Strain hardening; Grain boundary strengthening; Solid solution strengthening - yield-point phenomenon, strain ageing; Precipitation hardening - Conditions for precipitation hardening, Ageing, Formation of precipitates, coarsening of precipitates, Mechanism of strengthening; Dispersion strengthening; Fiber strengthening; Martensite strengthening - examples for above strengthening mechanisms from ferrous and non-ferrous systems, Bauschinger effect; Preferred orientation; Sever plastic deformation. | | | | | | | | | | | |
| Uni | t III | FRACTURE AND FRACTURE MECHANICS | | 9 | 0 | 0 | 9 | | | | |
| factors cohesiv introdue | affecting ve strengt ction, mo | re – ductile and brittle fracture, Ductile to Brittle Tra g DBTT, determination of DBTT, Hydrogen embritt th of metals, Griffith's theory of brittle fracture, Or des of fracture, stress intensity factor, strain energy rele- ction to COD, J integral. | lement and other rowan's modifica | embri tion. H | ttlemen ⁷ racture | t, Theo mech | oretical anics - | | | | |
| Uni | t IV | FATIGUE BEHAVIOUR AND TESTS | | 9 | 0 | 0 | 9 | | | | |
| fatigue, | , cumulat | cycles, S-N curves, effect of mean stress, factors affect ive damage, HCF / LCF, thermo-mechanical fatigue, on, fatigue testing machines. | | | - | - | • • | | | | |
| Uni | Unit VCREEP BEHAVIOUR AND TESTS9009 | | | | | | | | | | |
| factors | affecting | ges in creep curve and explanation, structural changes of creep, high temperature alloys, stress rupture testing, Deformation Mechanism Maps | e . | | | | • | | | | |
| | | | | Tota | al (45+0 |) = 45 | Hours | | | | |
| | | | | | | | | | | | |

| Tex | t Books: |
|------|---|
| 1 | George. E. Dieter, "Mechanical Metallurgy", 3rd Edition, McGraw-Hill Publications, New York, SI Edition, 2004 |
| 2 | Marc Andr'e Meyers, Krishan Kumar Chawla, "Mechanical Behavior of Materials", Cambridge University Press, UK, 2009. |
| Refe | rence Books: |
| 1 | Reed Hill, R.E., "Physical Metallurgy Principles", Affiliated East West Press, New Delhi, 1992. |
| 2 | Davis.H.E. Troxell G.E., Hauck.G.E.W. "The Testing of Engineering Materials", McGraw-Hill, 1982. |
| 3 | Wulff et al Vol. III "Mechanical Behavior of Materials", John Wiley and Sons, New York, USA, 1983. |
| 4 | Honeycombe R.W.K., "Plastic Deformation of Materials", Edward Arnold Publishers, 1984 |

| | | utcomes: npletion of this course, the students will be able to: | Bloom's Taxonomy Mapped |
|-----|---|--|-------------------------------|
| CO1 | : | Discuss the mechanical behaviour of materials. | L2: Understanding |
| CO2 | : | Discuss the strengthening mechanisms of materials. | L2: Understanding |
| CO3 | : | List the various types of fractures and their mechanisms, fracture mechanics and various theories describing fracture mechanics. | L2: Understanding |
| CO4 | : | Discuss the fatigue behaviour and the mechanism of fatigue, SN curve and fatigue testing machines. | L2: Understanding |
| CO5 | : | Describe the creep behaviour and mechanism, factors affecting creep and creep testing machines. | L2: Understanding |

| COURS | E ART | ICULA | TION | MATR | <u>XIX</u> | | | | | | | | | | | |
|-------|---|-------|------|------|------------|-----|------------|-----|-----|------|------|------|------|------|------|------|
| CO/PO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 | PSO4 |
| CO1 | 1 | 1 | | 1 | 1 | | | | | | | | 1 | 1 | | |
| CO2 | 1 | 1 | | 1 | 1 | | | | | | | | 1 | 1 | | |
| CO3 | 1 | 1 | 1 | | 1 | | | | | | | | | | 1 | 1 |
| CO4 | 1 | 1 | | | | 1 | 1 | | | | | | | | 1 | 1 |
| CO5 | 1 | 1 | | 1 | 1 | | | | | | | | 1 | 1 | | |
| Avg. | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | | | | | | 1.0 | 1.0 | 1.0 | 1.0 |
| | 3/2/1-indicates strength of correlation (3- High, 2-Medium, 1- Low) | | | | | | | | | | | | | | | |

| 18M | TM04 | RATE PROCESSES IN METALLUI | RGY | S | Semeste | er | | | | |
|--|---|---|--------------------|----------|-----------|----------|---------|--|--|--|
| PRER | EQUISIT | TES | | OE | Cre | edit | 3 | | | |
| | | | | L | Т | Р | TH | | | |
| Engin | eering ph | ysics | Hours/Week | 3 | 0 | 0 | 3 | | | |
| | | | | 5 | U | U | 5 | | | |
| Cours | e Learnir | ng Objectives | | | | | | | | |
| 1 To learn the basic principles and concepts of kinetics in the domain of metallurgy and materials; to learn about equations and their applications; And to appreciate that metallurgical kinetics as a Knowledge base with abundant applications. | | | | | | | | | | |
| U | nit I | INTRODUCTION 9 0 0 | | | | | | | | |
| Introdu | uction: Re | ole of kinetics, heterogeneous and homogeneous ki | netics, Role of | heat a | ind ma | ss tran | sfer in | | | |
| | | netics, rate expression, Effect of Temperature and c | | | | | | | | |
| - | | rhenius Equation), Effect of concentration (order of a | reaction), signifi | cance | and det | ermina | tion of | | | |
| activat | ion energ | у. | | | n | [| | | | |
| Un | nit II | KINETICS OF SOLID-FLUID REACTION | | 9 | 0 | 0 | 9 | | | |
| Kinetic | cs of solid | -fluid reaction: kinetic steps, rate controlling step, defini | tion of various re | sistanc | es in se | ries, sh | inking | | | |
| core m | odel, chei | nical reaction as rate controlling step, Product layer dif | fusion as rate co | ntrollir | ng step, | Mass t | ransfer | | | |
| - | | fluid film as rate controlling step, heat transfer as the r | - | - | | | - | | | |
| - | | and significance of heat and mass transfer coeffic | ient, Theoretical | mode | els for | mass t | ransfer | | | |
| coeffic | eients, Cor | relations for heat and mass transfer coefficients | | | 1 | | | | | |
| | it III | LIQUID-SOLID PHASE TRANSFORMATION | | 9 | 0 | 0 | 9 | | | |
| - | | lidification in metals and alloys: thermodynamics inv | | • | | | cation, | | | |
| Homog | geneous a | nd heterogeneous nucleation, Mechanisms of growth. F | Rapid Solidificati | on Pro | cessing | | | | | |
| Un | it IV | SOLID STATE PHASE TRANSFORMATIONS | | 9 | 0 | 0 | 9 | | | |
| Nuclea | ation and | growth Kinetics, homogeneous and heterogeneous tra | ansformation, Pr | ecipita | tion: C | oherend | ey, age | | | |
| harden | ing, partio | cle Coarsening. Ostwald ripening, Order-disorder trans | formation, spino | dal dec | compos | ition, n | nassive | | | |
| transfo | rmations | | | | r | 1 | | | | |
| Un | Unit VSOLID STATE PHASE TRANSFORMATIONS IN STEEL900 | | | | | | | | | |
| Recons | structive a | and displacive transformations; Pearlitic transformation | on: mechanism a | and kir | netics: . | Johnson | n-Mehl | | | |
| - | - | ology of pearlite; Bainitic transformation: mechanism a | - | | | | | | | |
| | | lartensitic transformation: Mechanism- diffusionless d | isplacive nature; | morph | ology c | of high | carbon | | | |
| and lov | w carbon | martensite. | | | | | | | | |
| | Total (45+0) = 45 Hours | | | | | | | | | |
| | | | | | | | | | | |
| | | | | | | | | | | |

| Tex | Text Books: | | | | | | |
|-----|---|--|--|--|--|--|--|
| 1. | Ahindra Ghosh and Sudipto Ghosh, A Text book of Metallurgical Kinetics, PHI learning Pvt. Ltd., New | | | | | | |
| | Delhi, 2014 | | | | | | |
| 2. | H.S. Ray, Kinetics of Metallurgical Reactions, International Science publisher, 1993. | | | | | | |
| 3. | F. Habashi, Kinetics of Metallurgical Processes, Metallurgy Extractive Québec, 1999. | | | | | | |
| 4. | Upadhyaya G S and Dube R K., "Problems in Metallurgical Thermodynamics & Kinetics", Pergamon, | | | | | | |
| | 1977. | | | | | | |
| Ref | erence Books: | | | | | | |

| 1. | Phase transformations in metals and alloys- D.A. Potter and K.E. Easterling, CRC Press, |
|----|---|
| | 1992. 2. Transformations in Metals, P.G. Shewmon, Mc-Graw Hill, 1969. |
| 2. | Introduction to Physical Metallurgy – S. N. Avner, Tata McGraw Hill, 1997. |
| 3. | Physical Metallurgy Principles, R. E. Reed-Hill and R. Abbaschian, 3rd ed, PWS-Kent |
| | Publishing, 1992. |
| 4. | Modern Physical Metallurgy, R. E. Smallman, Butterworths, 1963 |

| 00000 | • • | utcomes: npletion of this course, the students will be able to: | Bloom's Taxonomy Mapped |
|-------|-----|---|-------------------------------|
| CO1 | : | Discuss the thermodynamic aspects of phase changes. | L2: Understanding |
| CO2 | : | Discuss the fundamentals of solid –fluid reactions. | L2: Understanding |
| CO3 | : | Explain the eutectic and peritectic solidifications and rapid solidification processes. | L2: Understanding |
| CO4 | : | Describe the fundamentals of solidification. | L1: Remembering |
| CO5 | : | Apply the solid state phase transformations in steel. | L3:Applying |

| COURS | E ART | ICULA | TION | MATR | IX | | | | | | | | | | | |
|-------|---|-------|------|------|-----|-----|-----|-----|------------|------|------|------|------|------|------|------|
| CO/PO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 | PSO4 |
| CO1 | 1 | 1 | | 1 | 1 | | | | | | | | 1 | | | 1 |
| CO2 | 1 | 1 | | | 1 | 1 | | | | | | | | | 1 | 1 |
| CO3 | 1 | 1 | | 1 | 1 | | | | | | | | 1 | 1 | | |
| CO4 | 1 | 1 | | 1 | 1 | | | | | | | | | 1 | | 1 |
| CO5 | 1 | | 1 | | | 1 | 1 | | | | | | | | 1 | 1 |
| Avg. | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | | | | | | 1.0 | 1.0 | 1.0 | 1.0 |
| | 3/2/1-indicates strength of correlation (3- High, 2-Medium, 1- Low) | | | | | | | | | | | | | | | |

| 18MTM05 | CORROSION AND SURFACE ENGIN | EERING | S | er | | | | | | |
|---------------------------------|---|---------------------|---------|----------|---------|--------|--|--|--|--|
| PREREQUISI | TES | | OE | Cre | edit | 3 | | | | |
| En sin sonin a sh | | | L | Т | Р | TH | | | | |
| Engineering ch | lemistry | Hours/Week | 3 | 0 | 0 | 3 | | | | |
| Course Learni | ng Objectives | | | | | | | | | |
| 1 To und | erstand the corrosion and surface engineering, with it | ts application in e | enginee | ring fie | eld. | | | | | |
| Unit I | MECHANISMS AND TYPES OF CORROSION | J | 9 | 0 | 0 | 9 | | | | |
| – Galvanic co Cavitations, C | Principles of direct and Electro chemical Corrosion, Hydrogen evolution and Oxygen absorption mechanisms – Galvanic corrosion, Galvanic series-specific types of corrosion such as uniform, Pitting, Intergranular, Cavitations, Crevice Fretting, Erosion and Stress Corrosion, corrosion fatigue, hydrogen damage –Factors influencing corrosion | | | | | | | | | |
| Unit II | TESTING AND PREVENTION OF CORROSIO | ON | 9 | 0 | 0 | 9 | | | | |
| | aced Cracking Test, Sulphide Stress Corrosion Crack on –Modifications of corrosive environment –Inhibito CORROSION OF INDUSTRIAL COMPONEN | ors – Cathodic Pro | | | | | | | | |
| | CORROSION OF INDUSTRIAL COMPONEN | 15 | 9 | U | U | 9 | | | | |
| | fossil fuel power plants, Automotive industry, Ch action operations and refining, Corrosion of pipelines | • | • | | | ion in | | | | |
| Unit IV | SURFACE ENGINEERING FOR WEAR AND RESISTANCE | CORROSION | 9 | 0 | 0 | 9 | | | | |
| | ings –Electro and Electroless Plating –Hot dip coatin Conversion coating –Selection of coating for wear a | | | | g, Flam | e and | | | | |
| Unit V | THIN LAYER ENGINEERING PROCESSES900 | | | | | | | | | |
| deposition, Th | Laser and Electron Beam hardening –Effect of process variables such as power and scan speed - Physical vapor deposition, Thermal evaporation, Arc vaporization, Sputtering, Ion plating - Chemical vapor deposition – Coating of tools, TiC, TiN, Al ₂ O ₃ and Diamond coating-Properties and applications of thin coatings. | | | | | | | | | |
| | | | Tota | l (45+0 |) = 45 | Hours | | | | |
| | | | | | | | | | | |
| Reference Boo | | | | | | | | | | |

| Re | Reference Books: | | | | | | | |
|----|--|--|--|--|--|--|--|--|
| 1. | Fontana. G., Corrosion Engineering, McGraw Hill, 1985. | | | | | | | |
| 2. | Kenneth G. Budinski, Surface Engineering for Wear Resistance, Prenticehall, 1992. | | | | | | | |
| 3. | ASM Metals Hand Book – Vol. 5, Surface Engineering, 1996. | | | | | | | |
| 4. | Denny A Jones, "Principles and prevention of corrosion", 2 nd edition, Prentice Hall, New Jersey, 1995. | | | | | | | |
| 5. | ASM International, Surface Engineering for Corrosion and Wear Resistance,2005. | | | | | | | |
| 6. | Schweitzer. P.A., Corrosion Engineering Hand Book, 3rd Edition, Marcel Decker, 1996. | | | | | | | |

| Cours Upon | | Bloom's Taxonomy Mapped | |
|---------------|---|---|-------------------|
| CO1 | : | Name the different types of corrosion and their mechanism. | L2: Understanding |
| CO2 | : | Estimate corrosion resistance by different tests. | L4:Analysing |
| CO3 | : | Explain the corrosion behavior of different metals in different industries. | L2: Understanding |
| CO4 | : | Classify the different forms of processing techniques of surface engineering materials. | L1: Remembering |
| CO5 | : | Select the type of deposition and spraying technique. | L3:Applying |

| <u>COURS</u> | E ART | ICULA | TION | MATR | <u>RIX</u> | | | | | | | | | | | |
|--------------|-------|-------|------|------|------------|----------|---------|---------|------------|----------|----------|----------|-----------|------|------|------|
| CO/PO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 | PSO4 |
| CO1 | 1 | 1 | | 1 | 1 | | | | | | | | 1 | 1 | | |
| CO2 | 1 | 1 | | 1 | | 1 | | | | | | | 1 | 1 | | |
| CO3 | 1 | 1 | 1 | 1 | | | 1 | | | | | | | | 1 | 1 |
| CO4 | 1 | 1 | | 1 | 1 | | | | | | | | | | 1 | 1 |
| CO5 | 1 | 1 | | 1 | 1 | | | | | | | | 1 | 1 | | |
| Avg. | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | | | | | | 1.0 | 1.0 | 1.0 | 1.0 |
| | | | | | | 3/2/1-in | dicates | strengt | h of coi | relation | (3- High | , 2-Medi | um, 1- Lo | ow) | | |

| 18N | ATM06 | MATERIALS CHARACTERIZAT | ΓΙΟΝ | S | | | | | |
|---|--|---|---|-------------------|----------------------|-------------------|------------------|--|--|
| PRE | REQUISI | TES | | OE | Cre | edit | 3 | | |
| Engi | nooming n | | | L | Т | Р | ТН | | |
| Engi | neering pl | nysics | Hours/Week | 3 | 0 | 0 | 3 | | |
| Cour | se Learni | ng Objectives | | | | | | | |
| 1 | - | ire knowledge on various characterizations, chemica ents using its analysis tools. | l and thermal ana | lysis o | f metal | llurgica | ıl | | |
| τ | Jnit I | OPTICAL MICROSCOPY | | 9 | 0 | 0 | 9 | | |
| const depth techn | Metallographic specimen preparation. Macro-examination -applications. Metallurgical microscope - principle, construction and working, , Optic properties - magnification, numerical aperture, resolving power, depth of focus, depth of field, different light sources, lens aberrations and their remedial measures, Various illumination techniques-bright field , dark field, phase-contrast, polarized light illuminations, interference microscopy, high temperature microscopy; Quantitative metallography – Image analysis. | | | | | | | | |
| | nit II | X-RAY DIFFRACTION | 515. | 9 | 0 | 0 | 9 | | |
| Characteristic X-ray spectrum, Bragg's Law, Diffraction methods - Laue method, rotating crystal method ar powder method. Diffraction intensity – structure factor calculation. X-ray diffractometer -general features, filte and counters. Applications of X-ray diffraction in materials characterisation – Determination of crystallite siz crystal structure, precise lattice parameter, measurement of stress. | | | | | | | | | |
| | nit III | ELECTRON MICROSCOPY | | 9 | 0 | 0 | 9 | | |
| Diffra prepa applie | action effe tration tech cations, E | - specimen interactions. Construction and operation cts and image formation, various imaging modes, selechniques. Scanning electron microscopy – principle lectron probe microanalyser (EPMA)- principle, in uction to HRTEM, FESEM, EBSD. | ected area diffract , equipment, var | ion, ap ious o | plication peratin | ons, spe g mod | ecimen es and | | |
| U | nit IV | SPECTROSCOPIC TECHNIQUES | | 9 | 0 | 0 | 9 | | |
| spect emiss | roscopy, X sion spect | copy – EDS and WDS. Principle, instrumentation, w X-ray photoelectron spectroscopy and Secondary ion r roscopy, Atomic Absorption spectroscopy and X-r orking and applications. UV-Vis, FTIR and Raman s | mass spectroscop ray fluorescence | y/ion | microp | probe. (| Optical | | |
| U | nit V | THERMAL ANALYSIS AND CHARACTERIZATION TECHNIQUES | ADVANCED | 9 | 0 | 0 | 9 | | |
| gravi micro | Thermal Analysis: Principles of differential thermal analysis, differential scanning calorimetry and thermo- graviometric analysis – Instrumentation and applications. Advanced characterization techniques: Scanning probe microscopy - STM and AFM - principle, instrumentation and applications. Field ion microscopy including atom probe - principles, instrumentation and applications. Total (45+0) = 45 Hours | | | | | | | | |
| | | | | | | | | | |
| Text | Books: | | | | | | | | |
| 1. | Cullity, B 1978 | .D., Elements of X Ray Diffraction, Addison-Wesley | Publishing Com | ipany I | inc, Phi | ilippine | es, | | |
| 2. | Brandon, England, | D. and W.D. Kaplan, Microstructural Characterizatio 2013. | on of Materials, J | ohn W | iley & | Sons L | .td, | | |

| 3. | Leng, Y., Materials Characterization: Introduction to Microscopic and Spectroscopic Methods, John |
|----|---|
| | Wiley & Sons (Asia) Pte Ltd, Singapore, 2008 |

| Re | Reference Books: | | | | | | | |
|----|---|--|--|--|--|--|--|--|
| 1. | ASM Handbook, Volume 10, Materials Characterization, ASM international, USA, 1986. | | | | | | | |
| 2. | Vander Voort, G.F., Metallography: Principle and practice, ASM International, 1999. | | | | | | | |
| 3. | Phillips V A, Modern Metallographic Techniques and their Applications, Wiley Eastern, 1971. | | | | | | | |
| 4. | Angelo, P. C., Materials Characterization, Reed Elsevier India Pvt Ltd, Haryana, 2013. | | | | | | | |

| Cours Upon | | Bloom's Taxonomy Mapped | |
|---------------|---|---|-------------------|
| CO1 | : | Discuss the principles of metallurgical microscope, optical properties and various illumination techniques. | L2: Understanding |
| CO2 | : | Analyze the various diffraction methods, X-ray diffractometer and determination of crystal parameter. | L4:Analysing |
| CO3 | : | Discuss the principles of TEM, SEM, EPMA. | L2: Understanding |
| CO4 | : | Explain various spectroscopic techniques, | L2: Understanding |
| CO5 | : | Discuss the chemical and thermal analysis using advanced methods. | L2: Understanding |

| COURSE ARTICULATION MATRIX | | | | | | | | | | | | | | | | |
|----------------------------|------------|-----|-----|-----|-----|----------|---------|---------|------------|----------|----------|----------|-----------|------|------|------|
| CO/PO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 | PSO4 |
| CO1 | 1 | `1 | | 1 | 1 | | | | | | | | 1 | | 1 | |
| CO2 | 1 | 1 | 1 | 1 | | 1 | | | | | | | 1 | | | 1 |
| CO3 | 1 | | 1 | | | 1 | 1 | | | | | 1 | 1 | | | 1 |
| CO4 | 1 | 1 | | 1 | 1 | | | | | | | 1 | 1 | | | 1 |
| CO5 | 1 | 1 | | 1 | 1 | | | | | | | | 1 | | 1 | |
| Avg. | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | | | | | 1.0 | 1.0 | | 1.0 | 1.0 |
| | | | | | | 3/2/1-in | dicates | strengt | h of coi | relation | (3- High | , 2-Medi | um, 1- Lo | ow) | | |

| 18M | ITM07 | AUTOMOTIVE, AEROSPACE AND DEFENC | CE MATERIAL | S | emeste | er | |
|---------|--|--|----------------------|---------|-----------|----------|----------|
| PRER | REQUISI | TES | | OE | Cre | edit | 3 |
| Engin | oo ning n k | vicios | | L | Т | Р | TH |
| Engin | eering ph | lysics | Hours/Week | 3 | 0 | 0 | 3 |
| Cours | se Learni | ng Objectives | | | | | |
| 1 | | rstand the properties and applications various materia | ls suitable for au | tomobi | le, airc | raft and | 1 |
| | defnce in | ndustries and its components. | | | | | |
| U | Unit I MATERIALS FOR ENGINES AND TRANSMISSION SYSTEMS | | | | | 0 | 9 |
| Materi | ials select | ion for IC engines: Piston, piston rings, cylinder, Eng | gine block, Conne | ecting | rod, Cra | ank sha | aft, Fly |
| wheels | s, Gear bo | x, Gears, Splines, Clutches. | | | | | |
| Ur | nit II | MATERIALS FOR AUTOMOTIVE STRUCTU | RES | 9 | 0 | 0 | 9 |
| Materi | ials select | per, shock absor | bers, v | vind sc | reens, | panels, | |
| brake | shoes, Dis | sc, wheels, differentials, damping and antifriction flui | ids, Tyres and tuł | bes. Ma | aterials | for ele | ctronic |
| device | es meant f | or engine control, ABS, Steering, Suspension, Sensor | s, anti-collision, A | Anti-fo | g, Hea | d lamp | s. |
| Un | it III | AEROSPACE METALS AND ALLOYS | | 9 | 0 | 0 | 9 |
| Types | of corros | sion - Effect of corrosion on mechanical propertie | s – Stress corro | sion c | racking | – Co | rrosion |
| resista | nce mater | ials used for space vehicles. Heat treatment of carbon | steels – aluminiu | m alloy | /s, mag | nesium | alloys |
| | | oys - Effect of alloying treatment, heat resistance a | - | | | - | - |
| powde | er metallu | rgy- application of materials in Thermal protection sy | stems of Aerospa | ice veh | icles – | super a | alloys |
| Un | it IV | CERAMICS AND COMPOSITES | | 9 | 0 | 0 | 9 |
| Introd | uction – p | hysical metallurgy – modern ceramic materials – cerm | et - cutting tools - | – glass | cerami | c –proc | luction |
| of sen | ni-fabricat | ed forms - Plastics and rubber - Carbon/Carbon co | mposites, Fabrica | ation p | rocesse | s invol | lved in |
| metal | matrix co | mposites - shape memory alloys - applications in aero | ospace vehicle de | sign. | | | |
| Uı | nit V | NUCLEAR WASTE AND RADIATION PROTE IRRADIATION EFEFCTS | CCTION, | 9 | 0 | 0 | 9 |
| Introd | uction-un | it of nuclear radiation-Types of waste –disposal –ICR | P recommendation | ons-rad | liation | | |
| hazard | ls and pre | vention –radiation dose units - Irradiation Examination | on of Fuels, Irradi | ation b | oehavio | ur of n | netallic |
| uraniu | m – irradi | iation growth, thermal cycling, swelling, adjusted ura | nium, blistering i | n uran | ium roo | ds. Irra | diation |
| | | ic oxide and mixed oxide fuels, definition and units of | burn up, main ca | uses o | f fuel el | lement | failure |
| in pow | ver reactor | rs and remedies to avoid failures. | | | | | |
| | | | | Tota | l (45+0 |) = 45 | Hours |
| | | | | | | | |

| Re | ference Books: |
|----|---|
| 1. | ASM Handbook, "Selection of Materials Vol. 1 and 2", ASM Metals Park, Ohio. USA, 1991. |
| 2. | Materials Science and Engineering, Willium D. Callister, Jr. John Wiley & Sons publications Or Callister's Materials Science and Engineering Adapted By R. Balasubramaniam, Wiley India, Edition -2010. |
| 3. | Material Science and Engineering, V. Raghavan, Prentice Hall of India, 4th Edition. |
| 4. | Engineering Metallurgy Applied Physical Metallurgy, R. A. Higgins, 6th Edition |

| 5. | Gladius Lewis, "Selection of Engineering Materials", Prentice Hall Inc. New Jersey USA, 1995. |
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| 6. | Charles J A and Crane. F A. A., "Selection and Use of Engineering Materials", 3rd Edition, Butterworths, London UK, 1996 |
| 7. | ASM Handbook. "Materials Selection and Design", Vol. 20- ASM Metals Park Ohio.USA, 1997 |
| 8. | Cantor," Automotive Engineering: Lightweight, Functional, and Novel Materials", Taylor & Francis Group, London, 2006 |

| | Course Outcomes: Upon completion of this course, the students will be able to: | | | | | |
|-----|--|--|-------------------|--|--|--|
| CO1 | CO1 : Describe the materials selection criteria for engine and transmission systems. | | | | | |
| CO2 | : | Analyze the different materials used for automotive structures and Different electronic materials for automotive applications. | L4:Analysing | | | |
| CO3 | : | Explain various topics such as elements of aerospace materials and mechanical behaviour of materials, | L2: Understanding | | | |
| CO4 | : | Compare the ceramics and composites of aerospace materials | L4:Analysing | | | |
| CO5 | : | Examine the fuels for nuclear materials. | L3:Applying | | | |

| PO2 1 1 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 | PSO4 |
|---------|---------------|---|---|-----|-----|-----|-----|------|------|------|------|------|---|------|
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| 1 | | 1 | 1 | | | | | | | | 1 | | | 1 |
| 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | | | | | | 1.0 | 1.0 | 1.0 | 1.0 |
| | 1 1 1.0 | 1 1 1 1 1.0 1.0 | 1 1 1 1 1 1 1 1 1.0 1.0 | | | | | | | | | | 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1.0 1.0 1.0 1.0 3/2/1-indicates strength of correlation (3- High, 2-Medium, 1- Low) | |