DEPARTMENT OF ELECTRICAL AND ELECTRONICS ENGINEERING GOVERNMENT COLLEGE OF ENGINEERING, SALEM – 636 011.

(An Autonomous Instituion Affiliated to Anna University) Curriculum 2018A

M.E. Power Electronics and Drives - Full Time

			Но	urs/	Week			Maxi	mum l	Marks
Course code Name of the Course		Category	Contact periods	Lecture	Tutorial/ Demo*	Practical	Credit	CA	FE	Total
	SEMESTE	RI								
18PE C 11	Power Semiconductor Devices and Components	Core	3	3	0	0	3	40	60	100
18PE C 12	Analysis of Power Converters	Core	3	3	0	0	3	40	60	100
18PE E 1X	Elective-I	Elect 1	3	3	0	0	3	40	60	100
18PE E 2X	Elective-II	Elect 2	3	3	0	0	3	40	60	100
18PE C 13	Advanced Power Electronics Laboratory-I	Core	4	0	0	4	2	40	60	100
18PE C 14	Advanced Digital Control Laboratory	Core	4	0	0	4	2	40	60	100
18 MLC01	Research Methodology and IPR	MLC	3	3	0	0	3	40	60	100
18ACXX	Audit Course	Audit	2	0	0	0	0	100	0	100
	TOTAL						19			800
	SEMESTE	RII								
18PE C 21	Modelling and Analysis of Electrical Machines	Core	3	3	0	0	3	40	60	100
18PE C 22	Modern Electrical Drives	Core	3	3	0	0	3	40	60	100
18PE E 3X	Elective-III	Elect 3	3	3	0	0	3	40	60	100
18PE E 4X	Elective-IV	Elect 4	3	3	0	0	3	40	60	100
18PE C 23	Advanced Power Electronics Laboratory-II	Core	4	0	0	4	2	40	60	100
18PE C 24	Advanced Electrical Drives Laboratory	Core	4	0	0	4	2	40	60	100
18PE C 25	Mini Project With Seminar		4	0	0	4	2	40	60	100
18ACXX	Audit Course	Audit	2	0	0	0	0	100	0	100
	TOTAL						18			800
	SEMESTE	R III					•	•		
18PE E 5X	Elective - V	Elect 5	3	3	0	0	3	40	60	100
18PE E6 X	Elective - VI	Elect 6	3	3	0	0	3	40	60	100
18PE C 31	Dissertation Phase - I		20	0	0	20	10	80	120	200
	TOTAL						16			400
	SEMESTE	RIV								
18PE C 41	Dissertation Phase - II		32	0	0	32	16	160	240	400

TOTAL 16 4

Total Credits for the programme = 19 + 18 + 16 + 16 = 69

List of Programme Electives:

Course Code	Name of Course
Elective 1	
18PE E 11	Advanced Microcontroller Based System Design
18PE E 12	Applied Mathematics for Electrical Engineering
18PE E 13	System Theory
18PE E 14	Artificial Intelligence and Machine Learning
18PE E 15	Discrete Control System
Elective II	
18PE E 21	Advanced Power Electronic Circuits
18PE E 22	Digital Signal Processing for Power Electronics
18PE E 23	Dynamics of power Converters
18PE E 24	Modulation Control for Power Converters
18PE E 25	Design of Power Converters
Elective III	
18PE E 31	Advanced Power Quality
18PE E 32	Harmonics and Filters for Power Electronic Circuits
18PE E 33	Energy Conservation, Auditing and Management
18PE E 34	Special Electrical Machines and Drives
18PE E 35	Digital Simulation of Power Electronics System
Elective - IV	
18PE E 41	Photo Voltaic System
18PE E 42	Optimization Techniques
18PE E 43	Power System Optimization Techniques
18PE E 44	Wind Energy System
18PE E 45	Power Electronics for Renewable Energy System
Elective -V	
18PE E 51	Smart Grid Technology
18PE E 52	Distributed Generation

18PE E 53	FACTS Controllers
18PE E 54	HVDC Transmission Systems
18PE E 55	SCADA Systems and Applications
Elective -VI	
18PE E 61	Electric Vehicles
18PE E 62	Theory and Design of SMPS
18PE E 63	Energy Storage Technology
18PE E 64	Internet of Things for Electrical Engineers
18PE E 65	Digital Signal Processors for Power Converters

List of Audit Courses:

Course Code	Name of Course
18AC01	English for Research paper writing
18AC02	Disaster Management
18AC03	Sanskrit for Technical Knowledge
18AC04	Value Education
18AC05	Constitution of India
18AC06	Pedagogy Studies
18AC07	Stress Management by Yoga
18AC08	Personality Development through Life Enlightenment Skills

List of Special Electives:

Course Code	Name of Course
18PE SE 1	Pattern Recognition

18PEC11	POWER SEMICONDUCTOR DEVICES AND COMPONENTS	L	Т	Р	С
		3	0	0	3
Course Objectives					
	d the concepts of various power semiconductor devices and their thermal b	ehav	ior		
	agnetic and passive components for specific requirements.	CHav	101.		
Z. 10 designing	ightere and passive components for specific requirements.				
Unit I POWER S	SEMICONDUCTOR SWITCHES		9	+	0
	power device characteristics - Typical power switching waveforms - C				
	arious power semiconductor devices - Power Diode, MOSFET, IGBT, TI		tor, C	STO	-
Gate drive circuits f	or power semiconductor switches - Emerging power semiconductor devices	S.			
II 'A II THEBRA	LANAL VOIC OF DOWER OF MICONELICTOR REVIOES				_
	AL ANALYSIS OF POWER SEMICONDUCTOR DEVICES		9	+	0
	ng and Heat sinks - Thermal modeling of power switching devices - Elec				
	athematical thermal equivalent circuit - Coupling of Electrical and Therm				
Heat sink design - 2 circuits.	Zero voltage Switching and Zero Current switching - Basic concept and mod	del of	SWIT	chin	g
CITCUITS.					
Unit III DESIGI	OF MAGNETIC COMPONENTS		9	+	0
	magnetic material types - Comparison of material types - Ferrite C	hara			,
	n - Ferrite voltage transformer - Ferrite current transformer - Design and req				, –
Hansionnei Desigi	1 - Femile voltage transformer - Femile current transformer - Design and req	ullei	Henri	٠.	
Unit IV DESIGI	I OF INDUCTORS		9	+	0
	ar Inductors and chokes - Design with Hanna curves - Design including	copr	er lo	sse	<u> </u>
	design - Analysis of specific Inductor Design - Inductor design procedure.	0000			_
	<u> </u>				
Unit V DESIGN	OF CAPACITORS		9	+	0
Introduction - Gene	eral properties - Liquid and solid metal oxide dielectric capacitors - Plast	ic filr	n die	elect	ric
capacitors - EMI su	ppression capacitors - Ceramic dielectric capacitors - Mica dielectric capac	itors.			
	Total (L	+T)=	45 F	eric	ds
Course Outcomes					
Upon completion o	this course, the students will be able to:				
CO1 : Rememb	er the overview of power semiconductor switches				
CO2 : Analyze	the thermal requirements of power semiconductor devices				
CO3 : Understa	nd the basic concepts of ZVS and ZCS				
CO4 : Evaluate	the design aspects of various magnetic components according to specific r	equir	reme	nts.	
CO5 : Understa	nd the design concepts of circuit elements				
Text Books:					
1. Rashid M.H.,	Power Electronics: Circuits, Devices and Applications ", Pearson, 3rd Editio				
2. Barry W Willia	ms., Power Electronics: Devices, Drivers, Applications, and Passive compo	onent	ts .		
Reference Books:					
1. Mohan, Net a	. Power Electronics: Converters, Application and Design", Wiley India (P)	Ltd,	New	Del	hi,
2007.					

PO		РО	PO1	PO1								
co	CO Statement	1	2	3	4	5	6	7	8	9	0	1
CO1	Remember the overview of power semiconductor switches	1	3	1	1	1	1	3	1	1	1	1
CO2	Analyze the thermal requirements of power semiconductor devices	1	1	3	3	1	1	3	1	1	2	1
CO3	Understand the basic concepts of ZVS and ZCS	1	1	2	2	2	1	1	1	1	3	1
CO4	Evaluate the design aspects of various magnetic components according to specific requirements.	2	3	2	3	3	1	2	2	1	2	2
CO5	Understand the design concepts of circuit elements	2	2	3	2	3	1	2	3	1	2	2

				_	_
18PEC12	ANALYSIS OF POWER CONVERTERS	L	T	Р	C
		3	0	0	3
Course Objectives	:				
	e electrical circuit concepts behind the different working modes of power Co	nvert	ers	so a	S
	ep understanding of their operation.				
	required skills to derive the criteria for the design of power converters start	ing fro	m t	pasio)
fundamentals 3. To analyze a	nd comprehend the various operating modes of different configurations of po				
converters.	nd comprehend the various operating modes of different configurations of po	Jwei			
CONVENTENS.					
Unit I SINGLE F	PHASE AND THREE PHASE AC TO DC CONVERTERS		9	+	0
Single phase and	three phase ac to dc converters - Half controlled and Fully controlled of	conve	rter	s se	mi
	RLE loads, with and without free-wheeling diodes - Continuous and disco				
	ut general expressions - Dual Converter – performance parameters - effect				
	and overlap- Power factor improvement techniques- Generation of Gat I power balance in converter circuits.	ling S	equ	Jeno	e.
reactive power and	power balance in converter circule.				
Unit II DC TO D	C CONVERTERS		9	+	0
	OC Converters-Buck converter -Boost converter -Buck-Boost converter -				
	eration -Output Voltage ripple - Limitations of Single stage conversion - I				
	ck converters - Forward converters - Push-Pull converters- Full bridge converters	verter	s-C	urre	nt
mode and voltage	mode control - Design of Snubbers.				
Unit III SINGLE	PHASE INVERTERS AND POWER CONDITIONERS		9	_	0
	on of half and full bridge inverters - Performance parameters - Voltage co		_	sina	
	sing various PWM techniques – various harmonic elimination technic			_	
	or inverters- power conditioners-UPS: offline UPS, online UPS.	lucs	- 10) CC	u
	inverters power containoners of o. online of o, online of o.				
Unit IV THREE	PHASE VOLTAGE SOURCE INVERTERS AND MULTI LEV	FI			
CONVE		!	9	+	0
	0 degree conduction mode inverters with star and delta connected loads -	- volta	ne	con	rol
•	erters: single, multi pulse, sinusoidal, space vector modulation techniques		-		
•	ilevel concept - diode clamped - flying capacitor - cascade type multilev				
-	ilevel inverters - application of multilevel inverters .				
 					
Unit V CURR	ENT SOURCE INVERTER	- 1	9	+	0
Operation of six-ste	p thyristor inverter - inverter operation modes - load - commutated inverter	s - Aı	ito		
-	ource inverter (ASCI)- current pulsations -comparison of current source inve				
	erters – PWM techniques for current source inverters.				
	·				
	Total (L-	⊦T)= 4	5 P	erio	ds
Course Outcomes					
Upon completion of	this course, the students will be able to:				
'	rtise in the working modes and operation of Power converters.				
CO2 : Select ar	nd design dc-dc converter topologies for a broad range of power conversion				
	ingle phase and three phase inverters				
0	e and design the inverters for generic loads and machine loads.				
	nowledge on multilevel inverters and modulation techniques				
OOO . Auguile I	and model of malarovor involtors and modelation teorniques				
Text Books:					
Mohan Netal	Power Electronics: Converters, Application and Design", Wiley India (P)	Ltd. N	ew	Dell	ni,
1. 3rd Edition 201	0.			_	
	"Power Electronics", Khanna Publishers, New Delhi, 4th Edition, 2012.				
	Modern Power Electronics and AC Drives, Pearson Education,				
Second Editio	n, 2003.				

Ref	Reference Books:									
1.	Murphy, J.M.D and Turnbull, F.G " Power Electronics Control of AC Motors ", Pergamon Press,									
	Oxford, 1988.									
2.	Rashid M.H., Power Electronics: Circuits, Devices and Applications ", Pearson, 3 rd Edition, 2014.									
3.	P.C. Sen, Modern Power Electronics∥, Wheeler Publishing Co, First Edition, New Delhi, 1998.									
4.	Jai P.Agrawal, Power Electronics Systems∥, Pearson Education, Second Edition, 2002									

PO	CO Statement	PO1	РО	РО	PO4	РО	РО	РО	РО	РО	PO10	PO1
со			2	3		5	6	7	8	9		1
CO1	Get expertise in the working modes and operation of Power converters.	3	3	1	1	1	1	2	3	1	1	1
CO2	Select and design dc-dc converter topologies for a broad range of power conversion applications.	2	2	2	1	2	1	2	3	1	1	2
CO3	Design single phase and three phase inverters	1	2	1	3	2	1	1	1	1	2	1
CO4	Formulate and design the inverters for generic loads and machineloads.	1	1	1	2	1	1	1	1	2	1	1
CO5	Acquire knowledge on multilevel inverters and modulation techniques	1	1	1	1	1	1	1	2	1	1	1

18PEC13	ADVANCED POWER ELECTRONICS LABORATORY-I	L	Т	Р	С					
		0	0	4	2					
Course Objectives:										
To provide an insight on the switching behaviors of power electronic switches										
To make the students familiar with the digital tools used in generation of gate pulses for the power electronic switches										
To make the students capable of implementing analog interfacing as well as control circuits used in a closed-loop control for power electronic system										
To make the students acquire knowledge on mathematical modeling of power electronic circuits and implementing the same using simulation tools										
	To provide and To make the electronic swarf of make the closed-loop of the implementing	Irse Objectives: To provide an insight on the switching behaviors of power electronic switches To make the students familiar with the digital tools used in generation of gate pulses electronic switches To make the students capable of implementing analog interfacing as well as control closed-loop control for power electronic system To make the students acquire knowledge on mathematical modeling of power electronic	Irse Objectives: To provide an insight on the switching behaviors of power electronic switches To make the students familiar with the digital tools used in generation of gate pulses for electronic switches To make the students capable of implementing analog interfacing as well as control circu closed-loop control for power electronic system To make the students acquire knowledge on mathematical modeling of power electronic implementing the same using simulation tools	Irse Objectives: To provide an insight on the switching behaviors of power electronic switches To make the students familiar with the digital tools used in generation of gate pulses for the pelectronic switches To make the students capable of implementing analog interfacing as well as control circuits a closed-loop control for power electronic system To make the students acquire knowledge on mathematical modeling of power electronic circuits and the same using simulation tools	Irse Objectives: To provide an insight on the switching behaviors of power electronic switches To make the students familiar with the digital tools used in generation of gate pulses for the power electronic switches To make the students capable of implementing analog interfacing as well as control circuits used closed-loop control for power electronic system To make the students acquire knowledge on mathematical modeling of power electronic circuits a implementing the same using simulation tools					

LIST OF EXPERIMENTS:

- 1. Study of Power electronics Switches with and without Snubber
 - (i) IGBT (ii) MOSFET
- 2. Modelling of simple PN junction diodes
- 3. Modelling of SCR
- 4. Modelling of MOSFET / IGBT / BJT
- 5. Simulation of 1-phase semi-converter with R-load, RL load, and RLE (Motor) load
- 6. Simulation of 1-phase fully controlled converter with R-load, RL load, and RLE (motor) load at different firing angles.
- 7. Simulation of 1-phase dual converter.
- 8. Simulation of 3-phase semi-converter.
- 9. Simulation of 3-phase fully controlled converter at different firing angles.
- 10. Simulation of 1-phase full bridge inverter.
- 11. Simulation of 3-phase full bridge inverter.
- 12. Simulation of PWM inverter.
- 13. Simulation of 3-phase AC voltage controller.
- 14. Simulation of MOSFET / IGBT based choppers.
- 15. Simulation of DC-DC Buck-Boost converter with RL load.
- 16. Simulation of Series Resonant converter with RL load.
- 17. Numerical solution of ordinary differential, partial and integral equations using MATLAB.
- 18. Full converter fed resistive load
- 19. Full converter fed Resistive-Back Emf (RE) load at different firing angles
- 20. Full Converter fed Resistive-Inductive Load at different firing angles
- 21. Full converter fed DC motor load at different firing angles

		Total (60+0)= 60 Periods
Course	οι	itcomes:
Upon c	omp	pletion of this course, the students will be able to:
CO1	:	Model power electronics converter/Inverter in software
CO2	:	Simulate any power electronic converter/Inverter
CO3	:	Obtain numerical solutions of partial, differential and integral equations
CO4	:	Implement single phase full converter for any type of R and RL load
CO5	:	Implement single phase full converter for dc motors

PQ CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Model power electronics converter/Inverter in software	1	3	1	3	3	1	2	3	1	1	1
CO2	Simulate any power electronic converter/Inverter	1	1	2	1	3	1	2	3	1	1	1
CO3	Obtain numerical solutions of partial, differential and integral equations	1	2	1	3	2	1	1	1	1	1	2
CO4	Implement single phase full converter for any type of R and RL load	1	1	1	3	3	1	2	2	1	2	1
CO5	Implement single phase full converter for dc motors	1	1	1	1	3	1	1	2	2	1	1

	18PEC14	ADVANCED DIGITAL CONTROL LABORATORY	L	Т	Р	С
			0	0	4	2
Cou	ırse Objectives:					
1.	Implementation of DS	SC to various control techniques				
2.	Writing coding for cor	ntrol techniques				

LIST OF EXPERIMENTS:

- 1. Interfacing of LCD with DSC and displaying a message
- 2. Generation of Square Trigger Pulse using DSC
- 3. Measurement of Voltage/Current/Temperature
- 4. Open loop control of Buck/Boost/Buck-Boost Converter using DSC
- 5. Closed loop control of Buck/Boost/Buck-Boost Converter using DSC
- 6. Single phase square wave inverter control in open loop using DSC
- 7. Single phase square wave inverter control in closed loop using DSC
- 8. Single Phase AC-DC Converter in open loop using DSC
- 9. Single Phase AC-DC Converter in closed loop using DSC
- 10. Sine PWM based single phase inverter using DSC
- 11. Single phase AC Voltage controller control using DSC
- 12. Three Phase Inverter control using DSC

Total (60+0)= 60 Periods

Course Outcomes:

Upon completion of this course, the students will be able to:

CO1 : Understand the peripheral requirements for controlling the circuit

CO2 : Understand and implement the configurations of various required peripherals

CO3 : Write coding to implement the devised control technique

CO4 : Understand and implement the measurement principles through digital techniques

CO5 : Develop algorithms for implementation of controls and implement isolation techniques for power control

										1		
	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
PQ												
CO/												
CO1	Understand the											
	peripheral	1	1	1	1	1	1	1	1	1	1	1
	requirements for											
	controlling the circuit											
CO2	Understand and											
	implement the	1	1	1	1	1	1	1	1	1	1	1
	configurations of	'	'	'		'	'	'	'	'	ı	
	various required											
	peripherals											
CO3	Write coding to	1	1	1	1	1	1	1	1	1	1	1
	implement the devised	'	'	'	•	'	'	'	'	'	'	ı
	control technique											
CO4	Understand and											
	implement the	1	1	1	1	1	1	1	1	1	1	1
	measurement	'	'	'	•	'	'	'	'	'	'	ı
	principles through											
	digital techniques											
CO5	Develop algorithms for											
	implementation of											
	controls and	1	1	1	1	1	1	1	1	1	1	1
	implement isolation											
	techniques for power											
	control											

						_
181	MLC	01 RESEARCH METHODOLOGY AND IPR	L	T	Р	C
			3	0	0	3
COU		OBJECTIVES:				
		develop the subject of their research, encourage the formation of a higher level of tra				
1.		ity, critical analysis, rigor, and independence of thought, foster individual judgment				
		lication of research theory and methods, and develop skills required in writing research and disportation	arch	pro	posa	IS,
	repo	orts and dissertation.				
UNIT	. 1	INTRODUCTION TO RESEARCH		9	+	0
		of research problem, Sources of the research problem, Criteria Characteristics of	a doc	od re	_	rch
	_	Errors in selecting a research problem, Scope and objectives of the research problen	_			
inves	tigati	on of solutions for research problem, data collection, analysis, interpretatio	n, N	ece	ssary	/
instru	ımen	tations.				
UNIT		EFFECTIVE LITERATURE STUDIES APPROACHES, ANALYSIS		9	+	0
		g the theoretical framework of the research - Developing operational statements		-		
		r evaluating research approach - Hypotheses: Parametric and non-parametric test	-			_
		ility and validity of findings with literature review and experiments – documentation ethics.	on, P	ıagı	arısn	٦,
nese	aicii	etilics.				
UNIT	. III	EFFECTIVE TECHNICAL WRITING, HOW TO WRITE REPORT, PAPER		9	+	0
		g a Research Proposal, Format of a research proposal, a presentation and assessm	ent h			_
comn			CITE D	y u	TOVIC	, , ,
UNIT	· IV	NATURE OF INTELLECTUAL PROPERTY		9	+	0
Pater	nts, [Designs, Trade and Copyright. The process of Patenting and Development: technol	ogica	l re	sear	ch,
		, patenting, development. International Scenario: International cooperation on Intelle				
Proce	edure	for grants of patents, Patenting under PCT.				
UNIT		PATENT RIGHTS AND IPR		9	+	0
		Patent Rights. Licensing and transfer of technology. Patent information and database		_	•	
		s.New Developments in IPR: Administration of Patent System. New developments	in II	PR;	IPR	of
RIOIO	gicai	Systems, Computer Software etc. Traditional knowledge Case Studies, IPR and IITs.	tal =	45	Dorie	
COLL	DSE	OUTCOMES:	itai =	45	Perio	us
		apletion of this course, the students will be able to:				
<u>СО1</u>		Understand research problem formulation.				
CO2	-	Analyze research-related information				
CO3	·	Follow research ethics				
		Understand that today"s world is controlled by Computer, Information Technology	ı. but	tor	norra	
CO4	:	world will be ruled by ideas, concept, and creativity.	,			
		Understand that IPR protection provides an incentive to inventors for further rese	earch	WC	rk a	nd
CO5	:	investment in R & D, which leads to the creation of new and better products, and in to				
		economic growth and social benefits.		Ū		
	1					
TEXT	ГВО	OKS:				
		rt Melville and Wayne Goddard, Research methodology: an introduction for science				
		gineering students'				
		ne Goddard and Stuart Melville, Research Methodology: An Introduction				
		it Kumar, 2 nd Edition, Research Methodology: A Step by Step Guide for beginners				
		ert, ¯Resisting Intellectual Property∥, Taylor & Francis Ltd, 2007.				
REFE	EREN	NCE BOOKS:				

1.	Mayall, Industrial Design∥, McGraw Hill, 1992.
2.	Niebel, Product Design∥, McGraw Hill, 1974.
3.	Asimov, Introduction to Design, Prentice Hall, 1962.
4.	Robert P. Merges, Peter S. Menell, Mark A. Lemley, Intellectual Property in New Technological Agell,
4.	2016.
5.	T. Ramappa, Intellectual Property Rights Under WTO , S. Chand, 2008

PQ CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Understand research problem formulation.					1	1	1	1	1	2	1
CO2	Analyze research- related information					3	1	1	1	1	1	1
CO3	Follow research ethics					1	1	1	1	3	1	1
CO4	Understand that today"s world is controlled by Computer, Information Technology, but tomorrow world will be ruled by ideas, concept, and creativity.					1	3	1	1	1	1	1
CO5	Understand that IPR protection provides an incentive to inventors for further research work and investment in R & D, which leads to the creation of new and better products, and in turnbrings about, economic growth and social benefits.					1	3	1	1	1	2	2

18	PEC	221 MODELLING AND ANALYSIS OF ELECTRICAL MACHINES	L	T	Р	С
			3	0	0	3
Cour	se (Objectives:				
1.		introduce the basics of DC machines and analyze magnetic circuits				
2.		analyze the steady state and dynamic state operation of Induction machine through machine	athe	mat	cal	
3.		odeling. analyze the various types of machines and model with different transformation technique	IES			
4.		study the phase controlled, frequency controlled and vector controlled of induction mo				
5.		study the special machines and its model				
Unit I		MODELLING OF DC MACHINES	. 9		+	0
		nt circuit and electromagnetic torque - Electromechanical modelling - Field excita				
		eries and compound excitation - commutator action. Effect of armature mmf - Analytica circuit aspects- magnetic circuit aspects- interpoles.	ııun	uan	ienta	115.
Liceti	10 0	medit dopecto. Inagricile direati dopecto. Interporco.				
Unit I	I	DYNAMIC MODELLING OF INDUCTION MACHINES	9		+	0
		nt circuits - steady state performance equations - Dynamic modelling of induction r				
		del of a two phase induction machine, Three phase to two phase transformation - E				
		generalized model in arbitrary reference frames - stator reference, rotor reference,	syn	chro	nou	sly
TOLALII	ıy ı	reference frames model.				
Unit I	II	PHASE CONTROLLED AND FREQUENCY CONTROLLED INDUCTION	9		+	0
Stato	r vo	oltage control: Steady state analysis- approximate analysis- slip power recovery schel	me:	prin	ciple	of
opera	tion	n - steady state analysis: Range of slip - equivalent circuit - performance character	erist	ics ·	- Sta	atic
		s drive. Constant Volts/Hz controls implementation - steady state performance - dyna	mic	sim	ulati	on.
PWM	vol	tages: Generation - machine model - computation of steady state performance.				
Unit I	٧	VECTOR CONTROLLED INDUCTION MOTOR	9		+	0
		of vector control-direct vector control: flux and torque processor-DVC in stator referen				
		ector modulation. Indirect vector control scheme: derivation and implementation. F				
		n: principle of flux weakening operation-flux weakening in stator flux linkages-controlle linkages-controlled schemes.	d sc	hem	es a	ind
10101	iiux	illikages-controlled scriemes.				
Unit \		SPECIAL MACHINES	9	- 4:	+	0
		ent magnet and characteristics - Synchronous machines with PMs: Machine conf distribution - types of PMSM - Variable Reluctance Machines: principle of oper				
		on - Stepping motors: principle of operation- types: Variable reluctance – Hybrid n				
		i - characteristics.		•	. 0. 0	ļuo
•						
		Total (L+	Γ_ <i>/</i>	15 0	Orio	de
Cour	se (Outcomes:	·)=	ЮГ	enc	us
		mpletion of this course, the students will be able to:				
CO1	:	Acquire knowledge about the DC machines and AC machines and their magnetic circ	uits.			
	:	develop mathematical model of AC & DC machines and perform transient analysis on	the	m.		
CO2						
	1:	Understand the different types of reference frame theories and transformation relation	ship	s.		
CO3		,,	,-			
	+	Analyze the steady state and dynamic operation of three phase induction	mot	or	usin	<u>а</u>
CO4	•	transformation theory based mathematical Modelling and Special machines.		'	1	,
COE		Select strategies to control the torque for a given application.				
CO5	1.					
Text						
1. ⊤	$R.\overline{K}$	rishnan,∥Electric motor drives: modelling, analysis, and control∥, prentice hall of India, 2	010			

2. P.S.Bimbra, generalized theory of Electric machines, khanna publishers, 5th Edition, 2007.

Reference Books:

- 1. Charles Kingley, Jr., A.E.Fitzgerald, Stephen D.Umans, "Electric Machinery", Tata McGraw Hill, 6th Edition, 2002.
- 2 Miller, T.J.E., Brushless Permanent Magnet and Reluctance Motor Drives||, Clarendon Press

PO CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO1 0	PO1 1
CO1	Acquire knowledge about the DC machines and AC machines and their magnetic circuits.	2	1	1	1	3	1	3	1	1	1	1
CO2	develop mathematical model of AC & DC machines and perform transient analysis on them.	2	1	3	3	1	1	3	1	1	1	1
CO3	Understand the different types of reference frame theories and transformation relationships.	2	2	2	2	3	1	3	1	1	3	1
CO4	Analyze the steady state and dynamic operation of three phase induction motor using transformation theory based mathematical Modelling and Special machines.	2	3	2	3	3	1	2	2	1	2	1
CO5	Select strategies to control the torque for a given application.	2	2	3	3	3	1	2	1	1	2	2

	18PE	C22	MODERN ELECTRICAL DRIVES	L.	ΓР	С
				3 (0	3
Caur		bjectives:				
1.			d steady state operation and transient dynamics of a motor load system			
2.			analyze the operation of the converter / chopper fed DC drive, both qualitat	ively a	nd	
۷.		intitatively	analyze the operation of the conventer / chopper led Do drive, both qualitat	ively a	iu	
3.	Ťο	analyze ar	nd design the current and speed controllers for a closed loop solid state DC			
4.	То	understand	d the implementation of control algorithms using microcontrollers and phase	locke	d loop.	
Unit			RS FUNDAMENTALS AND MECHANICAL SYSTEMS			0
			nduced emf, speed-torque relations; Speed control - Armature and field			
			rol - Constant torque and constant horse power operations. Introduction			
			drives. Characteristics of mechanical system - dynamic equations, compo rements of drives characteristics -multi-quadrant operation; Drive elements			
			f motor rating.	, types	OI IIIC	ioi
Unit	II	CONVER	TER CONTROL	6	+	0
Princ	iple	of phase of	control - Fundamental relations; Analysis of series and separately excited	DC n	otor v	with
single	e-pha	ase and	three-phase converters - waveforms, performance characteristics. (Continu	ous	and
disco	ntinu	ious arma	ture current operations; Current ripple and its effect on performance;	Opera	ition v	with
freew	/heel	ing diode;	Implementation of braking schemes; Drive employing dual converter.			
Unit	III	INTROD	UCTION TO INDUCTION MOTORS	9	+	0
Stead	dy s	tate perfo	rmance equations - Rotating magnetic field - torque production, Equ	ivalent	circu	it-
	-	•	onstant frequency operation -Variable frequency operation, constant Vo			
		-	ons, variable stator current operation, different braking methods.		•	
Unit	IV	FIELD O	RIENTED CONTROL	9	+	0
Field	orie	nted contro	ol of Induction machines - Theory - DC drive analogy - Direct and Indirect m	ethods	- Flux	X
vecto	r es	timation -	Direct torque control of Induction Machines - Torque expression with s	tator a	nd rot	tor
fluxes	s, DT	C control s	strategy.			
Unit '			ONOUS MOTOR DRIVES	9		0
		•	cal rotor motor - Equivalent circuits - performance equations of operation fr		_	
		-	nd braking, self control - Load commutated Synchronous motor drive	s - Br	ush a	ınd
Brush	nless	excitation				
			Total (L	LT_ 4	Dori	ode
Cour	se C	utcomes:	•	+1)= 4	Perio	ous
Upon	con	npletion of	this course, the students will be able to:			
CO1	:	Understa	nd selection of drives for industries.			
CO2	:	Analyse v	various characteristics of series and separately excited DC motor with			
			d three phase converters.			
CO3			bout different conventional speed control methods for induction motors.			
CO4	:	-	bout direct and indirect methods of field oriented control and direct Torque	Contro	scher	me
005	+	for Induct				
CO5			e the control schemes for synchronous motor drives.			
Text			ower Semiconductor Controlled Drives " DU International New Jersey 109	20		
			ower Semiconductor Controlled Drives ", PH International, New Jersey, 198 ristor D.C Drives ", John Wiley & Sons, New York, 1981.	ອ.		
, ,						
			Modern Power Electronics and AC Drives, Pearson Education Asia 2004.			

4.	R.Krishnan, Electric Motor Drives - Modeling, Analysis and Control, Prentice-Hall of India Pvt. Ltd., New Delhi, 2003.
Ref	erence Books:
1.	Subharamanyam V. "Electric Drives-Concepts and Applications ", TMH Publi., 1994
2.	GobalK.Dubey, Fundamentals of Electrical Drives , Narosal Publishing House, New Delhi,Second Edition ,2009.
3.	W.Leonhard, Control of Electrical Drives, Narosa Publishing House, 1992.
4.	Murphy J.M.D and Turnbull, Thyristor Control of AC Motors , Pergamon Press, Oxford, 1988

PO	CO Statement	PO1	РО	РО	PO4	РО	РО	РО	РО	РО	PO10	PO1
со			2	3		5	6	7	8	9		1
CO1	Understand selection of drives for industries.	1	1	1	1	2	1	2	1	2	1	2
CO2	Analyse various characteristics of series and separately excited DC motor with single and three phase converters.	1	3	3	2	2	1	2	2	1	1	1
CO3	Explain about different conventional speed control methods for induction motors.	1	1	1	2	2	1	1	2	1	1	1
CO4	Explain about direct and indirect methods of field oriented control and direct Torque Control scheme for Induction motor.	1	1	2	2	2	1	2	2	1	1	1
CO5	Formulate the control schemes for synchronous motor drives.	1	2	3	2	3	1	2	2	1	1	1

	18PEC23	ADVANCED POWER ELECTRONICS LABORATORY II	L	Т	Р	С						
			0	0	4	2						
Cou	Course Objectives:											
1.	To provide an ins	sight on the switching behaviours of power electronic switches										
2.	To make the students familiar with the digital tools used in generation of gate pulses for the power electronic switches											
3.		dents capable of implementing analog interfacing as well as control trol for power electronic system	circ	uits	used	l in a						
4.		dents acquire knowledge on mathematical modelling of power elect e same using simulation tools	ronic	circ	cuits	and						

LIST OF EXPERIMENTS:

- Dynamic characteristics of SCR and TRIAC
- Dynamic characteristics of MOSFET, BJT and IGBT
- 3. Single phase ac voltage controller using SCR and TRIAC
- Three phase half and fully controlled bridge converter
- 5. Single phase series inverter6. IGBT based three phase PWM Inverter
- 7. MOSFET based buck boost converter
- 8. DC-DC forward converter
- 9. DC-DC flyback converter
- 10. Single phase dual converter
- 11. DC series resonant converter

			Total (60+0)= 60 Periods
Course	O C	itcomes:	
Upon c	om	pletion of this course, the students will be able to:	
CO1	:	Implement ac voltage controller	
CO2	:	Obtain the performance of any type of converter	
CO3	:	Analyse the performance of single phase and three phase inverter	
CO4	:	Implement DC-DC converter	
CO5	:	Analyse the performance of resonant converter	

PO	CO Statement	PO1	PO	РО	PO4	РО	PO	РО	РО	РО	PO10	PO1
co			2	3		5	6	7	8	9		1
CO1	Implement ac voltage controller	2	1	3	3	3	1	2	3	2	1	2
CO2	Obtain the performance of any type of converter	2	3	3	1	3	1	2	3	1	1	1
CO3	Analyse the performance of single phase and three phase inverter	2	3	1	1	2	1	1	1	1	1	1
CO4	Implement DC-DC converter	1	1	3	3	3	1	2	3	1	1	1
CO5	Analyse the performance of resonant converter	2	3	3	1	3	1	2	3	1	1	1

	18PEC24	ADVANCED ELECTRICAL DRIVES LABORATORY	L	Т	Р	С				
			0	0	4	2				
Cour	se Objectives:									
1.	To analyze the o	operation of DC and AC motor drives								
2.	To study the performance of PMSM, BLDC and SRM drives									
3.	To gain knowled	ge on closed loop control of PMSM, BLDC and SRM drives.								
LIST	OF EXPERIMEN	NTS:								
1	. Four guadran	t chopper fed DC motor drive								

- 2. V/f control of three phase induction motor with voltage source inverter
- 3. DSP based speed control of SRM motor
- 4. DTC control of Induction motor drive
- 5. Self-controlled synchronous motor drive
- 6. Closed loop control of PMSM motor
- Simulation study of four quadrant operation of DC drives using dual converter circuit
- Simulation study of Field oriented control induction motor drive
- Simulation study of CSI fed three phase induction motor drive
- 10. Simulation study of closed loop control of BLDC motor drive

Total (60+0)= 60 Periods **Course Outcomes:** Upon completion of this course, the students will be able to: CO1 Design closed loop control for PMSM and SRM drives. CO2 Analyze the operation of VSI and CSI fed induction motor drives CO3 Select suitable inverter configuration and control for three phase induction motor drives. CO4 Analyze the operation of synchronous motor drives. CO5 Use digital control for special motor drives.

PQ CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Design closed loop control for PMSM and SRM drives.	2		3	2		1		2		1	
CO2	Analyze the operation of VSI and CSI fed induction motor drives	1	3						1			
CO3	Select suitable inverter configuration and control for three phase induction motor drives.	3		1					1			2
CO4	Analyze the operation of synchronous motor drives.	1	3						2			
CO5	Use digital control for special motor drives.	2			3	1			1			

18PEE11 ADVANCED MICROCONTROLLER BASED SYSTEM DESIGN	L	T F	
	3	0 0	3
O command the state of			
Course Objectives:			
To implement digital control for power electronic applications To learn various DSP peripherals for proper implementations to power applications			
To learn various DSP peripherals for proper implementations to power applications			
Unit I INTRODUCTION TO DSPIC 30F DIGITAL SIGNAL CONTROLLER		9 +	- 0
dsPIC 30F CPU Core - Programmers Model - CPU Registers - DSP Engine - Memory Organ		_	
Program - Flash and EEPROM Programming.	iizatioi	ייי	ita
- rogium ridon and EEL recini rogiumining.			
Unit II SYSTEM CONFIGURATION		9 +	0
Oscillator Configuration - Power saving Modes - Various Resets - Device Configuration - Low	Voltag	e De	tect
- I/O Ports			
Unit III CONTROL PERIPHERALS		9 +	
Study, Configuration and control - Interrupt Structure - Timers - Capture and Compare - A	AD Co	nver	er-
Introduction to IDE for dsPIC and Project development with simple C programming.			
		_	
Unit IV MOTOR CONTROL PERIPHERALS		9 +	. 0
Motor Control PWM - Different PWM modes - Dead Time - Output and Polarity Control - PV	NM Fa	ult P	ns -
Quadrature Encoder Interface			
Unit V APPLICATIONS		9 +	. 0
Closed loop Control of Single and three Phase VSI, Sensored and Sensorless BLDC Moto			
Induction Motor Control - Vector Control of AC Induction Motor - Servo Control of a DC-Brus			
Channel Digital Voltmeter with Display	311 14101	.01 1	oui
Total (L	+T)= 4	5 Per	iods
Course Outcomes:			
Upon completion of this course, the students will be able to:			
CO1 : Understand various DSP peripherals			
CO2 : Understand the configurations of peripherals for appropriate power applications			
CO3 : Write C coding for implementing controls using peripherals			
CO4 : Implement interfacing techniques with DSC for control applications CO5 : Understand and implement data acquisition and processing for control application at	n al !:	la m= =	-1
CO5 : Understand and implement data acquisition and processing for control application are control techniques for power electronic applications	па <i>ітр</i> і	emer	π
Reference Books:			
dsPIC30FFamily Reference Manual, Datasheets.			
Creed Huddleston, Intelligent Sensor Design using Microchip dsPIC ", Newnes, 2007.			
Zoran Milivojević, DjordjeŠaponjić, Programming dsPIC (Digital SignalContribution)	ollere)	in	C∥,
3. Zoran Milivojevic, Djordjesaponjic, Programming dsPic (Digital Signalcontin	onora)	111	∪ ∥,
- More Libert State			

PO CO	CO Statement	PO1	PO 2	PO 3	PO4	PO 5	PO 6	PO 7	PO 8	PO 9	PO10	PO1
				3		5	O	/	0	9		ı
CO1	Understand various DSP peripherals	1	1	1	1	1		1	1	1	1	1
CO2	Understand the configurations of peripherals for appropriate power applications	1	1	1	1	1		1	1	1	1	1
CO3	Write C coding for implementing controls using peripherals	1	1	1	1	1		1	1	1	1	1
CO4	Implement interfacing techniques with DSC for control applications	1	1	1	1	1		1	1	1	1	1

CO5	Understand and										
	implement data										
	acquisition and										
	processing for control	1	1	1	1	1	1	1	1	1	1
	application and										
	implement control										
	techniques for power										
	electronic applications										

	18PEE12 APPLIED MATHEMATICS FOR ELECTRICAL ENGINEERI	NG	LT	Р	С
	•		3 0	0	3
Coi	urse Objectives:				
1.	To familiarize the students in the field of variational problems.				
2.	To acquire the techniques in solving simultaneous equations.				
3.	To impart the knowledge in solving differential equations.				
4.	To procure the solutions of linear programming using Graphical and Simplex me	thods			
5.		uiouo.			
	To understand the overall approach of dynamic programming.				
Uni	it I CALCULUS OF VARIATIONS		9		0
	ncept of Variation and its properties - Euler's equation - Functional dependent on file	ct and hig		or.	U
deri	rivatives - Functional dependent on functions of several independent variables- Sor hthods: Ritz and Kantorovich methods.				et .
Uni	it II SOLUTION OF EQUATIONS		9	+	0
	· · · · · · · · · · · · · · · · · · ·	nation Ca			_
	wton Raphson method, Curve fitting (Least square), Direct method: Gaussian Elimid Factorisation methods - Iterative method: Gauss-Jacobi, Gauss - Seidel Methods		เนอร-JC	iuan	
l lm:	it III NUMERICAL SOLUTION OF BOUNDARY VALUE PROBLEMS		10	1.	_
	merical solution of ordinary Differential Equations-Euler' method-Euler's modified n		9	+	0
_	it IV LINEAR PROGRAMMING sic concepts - Graphical and Simplex methods - Transportation problem - Assignn	ent proble	9	+	0
Das	sic concepts - drapnical and omplex methods - transportation problem - Assignin	ient proble	2111		
Uni	it V DYNAMIC PROGRAMMING		9	+	0
Elei	it V DYNAMIC PROGRAMMING ements of the dynamic programming model - optimality principle -Examples of dynamic dels and their solutions.	mic progra			0
Elei	ements of the dynamic programming model - optimality principle -Examples of dyna		amming		
Elei	ements of the dynamic programming model - optimality principle -Examples of dyna	mic progra	amming		
Elei	ements of the dynamic programming model - optimality principle -Examples of dyna odels and their solutions.		amming		
Cou Upo CO	ments of the dynamic programming model - optimality principle -Examples of dynamic dels and their solutions. urse Outcomes: on completion of this course, the students will be able to: 1 Understand the concept of variational problems and its techniques.		amming		
Cou Upo CO	ements of the dynamic programming model - optimality principle -Examples of dynamic dels and their solutions. urse Outcomes: on completion of this course, the students will be able to: 1 : Understand the concept of variational problems and its techniques. 2 : Solve the linear equations		amming		
Cou Upo CO CO	ements of the dynamic programming model - optimality principle -Examples of dynamic dels and their solutions. urse Outcomes: on completion of this course, the students will be able to: 1 : Understand the concept of variational problems and its techniques. 2 : Solve the linear equations 3 : Obtain the numerical solutions of differential equations	Total (L+	amming		
Cou Upo CO CO	ements of the dynamic programming model - optimality principle -Examples of dynamic dels and their solutions. urse Outcomes:	Total (L+	amming		
Cou Upo CO CO CO	ements of the dynamic programming model - optimality principle -Examples of dynamic dels and their solutions. urse Outcomes: on completion of this course, the students will be able to: Understand the concept of variational problems and its techniques.	Total (L+	amming		
Cou Upo CO CO CO	ements of the dynamic programming model - optimality principle -Examples of dynamic dels and their solutions. urse Outcomes: On completion of this course, the students will be able to: On the concept of variational problems and its techniques. On the concept of variational problems and its techniques. On the linear equations Obtain the numerical solutions of differential equations Obtain the numerical solutions of differential equations On the concept of Dynamic Problems and techniques to sext Books:	Total (L+	T)= 45		
Cou Upo CO CO CO Tex 1.	ments of the dynamic programming model - optimality principle -Examples of dynamic dels and their solutions. urse Outcomes: on completion of this course, the students will be able to: 1	Total (L+	T)= 45	Perio	
Cou Upo CO CO CO CO Tex	ments of the dynamic programming model - optimality principle -Examples of dynamic dels and their solutions. urse Outcomes: on completion of this course, the students will be able to: 1	Total (L+	T)= 45 2014. Delhi 2	Perio	ods
Cou Upo CO CO CO Tex 1.	ments of the dynamic programming model - optimality principle -Examples of dynamic dels and their solutions. urse Outcomes: on completion of this course, the students will be able to: 1	Total (L+	T)= 45 2014. Delhi 2	Perio	ods
Cou Upo CO CO CO Tex 1.	ments of the dynamic programming model - optimality principle -Examples of dynamidels and their solutions. urse Outcomes:	Total (L+ ues olve New Delhi td., New , Asia, 7 th ion Edition	T)= 45 2014. Delhi 2 edition.	Perio	ods
Cou Upo CO CO CO Tex 1. 2.	weight and their solutions. weight and the solutions of this course, the students will be able to: weight able to: weight and the concept of variational problems and its techniques. weight and the solutions of differential equations. weight and the solutions of differential equations. weight and the solution and Routing problems using Optimization Techniques. weight and the solution and Routing problems and techniques to solutions. weight and the solution and Routing problems and techniques to solution. Weight and the solution and Routing problems and techniques to solution. Weight and the solution and Routing problems and techniques to solution. Weight and the solution and Routing problems and techniques to solution. Weight and the solution and Routing problems and techniques to solution. Weight and the solution and Routing problems using Optimization Techniques. Weight and the solution and Routing problems using Optimization Techniques. Weight and the solution and Routing problems using Optimization Techniques. Weight and the solution and Routing problems using Optimization Techniques. Weight and the solution and Routing problems using Optimization Techniques. Weight and the solution and Routing problems using Optimization Techniques. Weight and the solution and Routing problems and its techniques. Weight and the solution and Routing problems and its techniques. Weight and the solution and Routing problems and its techniques. Weight and the solution and Routing problems and its techniques. Weight and the solution and Routing problems and its techniques. Weight and the solution and Routing problems and its techniques. Weight and the solution and Routing problems and its techniques. Weight and the solution and Routing problems and its techniques. Weight and the solution and Routing pro	Total (L+ ues olve New Delhi td., New , Asia, 7 th ion Edition	T)= 45 2014. Delhi 2 edition.	Perio	ods

PO CO	CO Statement	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	PO 7	PO 8	PO 9	PO1 0	PO1 1
CO1	Understand the concept of variational problems and its techniques.			3	1	1	1	1	1	1	1	1
CO2	Solve the linear equations			3	1	1	2	2	1	1	1	1
CO3	Obtain the numerical solutions of differential equations			3	1	1	2	1	1	2	1	3
CO4	Solve the Transportation and Routing problems using Optimization Techniques			1	1	1	1	2	1	1	1	1
CO5	Gain the knowledge and concept of Dynamic Problems and techniques to solve			1	1	1	2	1	1	1	1	3

18PEE13	SYSTEM THEORY	-	_	Р	С
IOFELIS	STSTEW THEORY	3	0	0	3
Course Objectives	s:				
	on modelling and representing systems in state variable form				
	on solving linear and non-linear state equations				
	he role of controllability and observability				
	vledge on stability analysis of systems using Lyapunov's theory				
To impart ki estimators	nowledge on modal concepts and design of state and output feedback of	contr	olle	rs a	nd
Unit I STATE V	ARIABLE REPRESENTATION		9	+	0
	cept of State - State equations for Dynamic Systems - Time invariance state model - State Diagrams - Physical System and State Assignment: Line erted pendulum.				
Unit II SOLUTI	ON OF STATE EQUATIONS		9	+	0
	queness of solutions to Continuous-time state equations - Solution of Nonline equations - Evaluation of matrix exponential - System modes - Role of E				
	COLLABILITY AND OBSERVABILITY		9	+	0
time Systems: Tir	Controllability and Observability - Stabilizability and Detectability - Tests me-varying and Time-invariant cases - Output Controllability - Reduci e-variable canonical forms - Jordan canonical form.				
Unit IV STABIL	ITY		9	+	0
Equilibrium Stabilit and the Linear C	ibrium Points - Stability in the sense of Lyapunov - BIBO Stability -Stability of Nonlinear Continuous-Time Autonomous Systems - The Direct Metho Continuous-Time Autonomous Systems - Finding Lyapunov Functions Autonomous Systems - Krasovski and Variable-Gradiant Methods.	od of	fLy	apu	nov
Unit V POLE P	LACEMENT		9		0
	rollable and Observable Companion Forms: SISO and MIMO Systems - The	\ ⊏ff		+	
Feedback on Cont	rollability and Observability - Pole Placement by State Feedback for both Ser and Reduced Order Observers.				
,	Total (L-	T)=	45	Perio	ds
Course Outcomes					
Upon completion o	f this course, the students will be able to:				
	and the concept of state variable representation of systems.				
	ear and non-linear state equations.				
	the concepts of controllability and observability.				
	be better understanding of Stability analysis of nonlinear systems.				
	and the concepts of Pole placement and State feedback.				
Text Books:	Indorn Control System Theory I Now Assistance 2005				
	lodern Control System Theory , New Age International, 2005.	Cc	. n - :	I :	
New Delhi, 20		Con	ıpar	ıy Li	a.,
Reference Books:					
	Modern Control Theory∥, Springer Publishers, 2005.				
2. Ogatta, K., N	fodern Control Engineering∥, Prentice Hall of India, 2002.				

PO CO	CO Statement	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	PO 7	PO 8	PO 9	PO1 0	PO1 1
CO1	Understand the concept of state variable representation of systems.	1	3	1	1	2	1	3	1	1	1	1
CO2	Evaluate linear and non-linear state equations.	1	1	3	3	1	2	3	1	1	2	1
CO3	Analyze the concepts of controllability and observability.	1	1	2	2	2	2	1	1	2	3	1
CO4	Apply Stability concept to nonlinear systems.	2	3	2	3	3	1	2	2	1	2	2
CO5	Understand the concepts of Pole placement and State feedback.	2	2	3	2	3	1	2	3	1	2	2

18PEE14	ARTIFICIAL INTELLIGENCE AND MACHINE LEARNING	L	T	<u>P</u>	
		3	0	0	
Course Objective	s:				
	a strong foundation of fundamental concepts in Artificial Intelligence.				
	he student to apply these techniques in applications which involve percept	ion,	reas	oni	in
and learning	J.	,			
To enable F	roblem-solving through various searching techniques.				
	numerous innate human skills such as automatic programming, case – ba				
	orks, Fuzzy Logic, decision-making, expert systems, natural languahe proc	essir	ng, p	att	е
	and speech recognition, etc. techniques primarily for machine learning, vision, and robotics.				
5. 10 apply 7 ti	teeriniques printarily for macrime rearring, vision, and resource.				
nit I INTROD	UCTION TO AI AND PRODUCTION SYSTEMS		9	+	
troduction to Al	-Problem formulation, Problem Definition -Production systems, Control stra	tegie	es, S	ea	r
	em characteristics, Production system characteristics -Specialized produ				
	nethods - Problem graphs, Matching, Indexing and Heuristic functions -Hill Cli				
	rst, Constraints satisfaction - Related algorithms, Measure of performance a	and a	analy	sis/	3
earch algorithms					
nit II REPRE	SENTATION OF KNOWLEDGE		9	+	Τ
	nowledge representation, Knowledge representation using Predicate logic,		_	ior	<u>_</u>
	s, Resolution, Use of predicate calculus, Knowledge representation using				
tructured repres	entation of knowledge.				
	/LEDGE INFERENCE		_	+	
	entation -Production based system, Frame based system. Inference - Backwa				
	Rule value approach, Fuzzy reasoning - Certainty factors, Bayesian The	eory-	Baye	esia	aı
ietwork-Dempste	r - Shafer theory.				
Init IV DI AN	NING AND MACHINE LEADNING		0		Г
	NING AND MACHINE LEARNING	evnla	9 enati	+	
Basic plan genera	NING AND MACHINE LEARNING tion systems - Strips -Advanced plan generation systems - K strips -Strategic how explanations. Learning- Machine learning, adaptive Learning.	expla	9 anati	+ on:	s
Basic plan genera Why, Why not and	tion systems - Strips -Advanced plan generation systems - K strips -Strategic I how explanations. Learning- Machine learning, adaptive Learning.			+ ons	
asic plan genera Why, Why not and Init V EXPER	tion systems - Strips -Advanced plan generation systems - K strips -Strategic how explanations. Learning- Machine learning, adaptive Learning. T SYSTEMS		9	+	
asic plan genera vhy, Why not and nit V EXPER expert systems -	tion systems - Strips -Advanced plan generation systems - K strips -Strategic how explanations. Learning- Machine learning, adaptive Learning. T SYSTEMS Architecture of expert systems, Roles of expert systems - Knowledge Acc		9	+	
asic plan genera /hy, Why not and nit V EXPER xpert systems -	tion systems - Strips -Advanced plan generation systems - K strips -Strategic how explanations. Learning- Machine learning, adaptive Learning. T SYSTEMS		9	+	
asic plan genera /hy, Why not and nit V EXPER xpert systems -	tion systems - Strips -Advanced plan generation systems - K strips -Strategic how explanations. Learning- Machine learning, adaptive Learning. T SYSTEMS Architecture of expert systems, Roles of expert systems - Knowledge Acc	quisit	9 ion	+ -Me	e
asic plan genera /hy, Why not and nit V EXPER xpert systems - nowledge, Heuris	tion systems - Strips -Advanced plan generation systems - K strips -Strategic how explanations. Learning- Machine learning, adaptive Learning. T SYSTEMS Architecture of expert systems, Roles of expert systems - Knowledge Acceptics. Typical expert systems - MYCIN, DART, XOON, Expert systems shells. Total (L+	quisit	9 ion	+ -Me	e
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Basic plan general Why, Why not and Why, Why not and Direct Systems - Knowledge, Heuris Course Outcome Upon completion Co1 : Provide Co2 : Study to planning learning Co4 : Apply intervention recognication of Ext Books: 1. Stuart Russ Education / Fig. 2. Elaine Rich as series) , The	tion systems - Strips -Advanced plan generation systems - K strips -Strategic how explanations. Learning- Machine learning, adaptive Learning. TSYSTEMS Architecture of expert systems, Roles of expert systems - Knowledge Actics. Typical expert systems - MYCIN, DART, XOON, Expert systems shells. Total (L+s: If this course, the students will be able to: a basic exposition to the goals and methods of Artificial Intelligence. The design of intelligent computational agents. knowledge through learning can be used both for problem solving and the gradient programming of the students and the standard language understanding, computer vision, automatic programming of the students. The problem is a substanding of the students of	quisit T)= 4 for reg and ning, essing tion,	9 Isin Pea	+ -Me pric	e

	Fourth Edition, 2011.
2.	David L. Poole, Alan K. Mackworth, Artificial Intelligence: Foundations of Computational Agents,
	Cambridge University Press, 2010.
3.	Dan W.Patterson, Introduction to Artificial Intelligence and Expert Systems, PHI, 2006.
4.	Nils J. Nilsson, Artificial Intelligence: A new Synthesis, Harcourt Asia Pvt. Ltd., 2000.

PO CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Provide a basic exposition to the goals and methods of Artificial Intelligence.	2	2	2	1	1	1	2	1	1	2	1
CO2	Study the design of intelligent computational agents.	3	1	1	2	2	1	1	1	2	2	1
CO3	Acquire knowledge through learning can be used both for problem solving and for reasoning planning, natural language understanding, computer vision, automatic programming and machine learning.	1	1	1	2	1	1	2	2	2	2	2
CO4	Apply innate human skills such as automatic programming, case — based reasoning, neural networks, Fuzzy Logic, decision-making, expert systems, natural languahe processing, pattern recognition and speech recognition, etc.	1	2	2	3	3	1	1	2	1	1	1
CO5	Enhance their knowledge in their Research works in future.	1	1	1	1	1	2	2	1	2	1	1
CO6	Build new solutions in business in future.	1	1	1	2	1	1	1	2	3	3	3

18PEE15	DISCRETE CONTROL SYSTEM	L	T	Р	С
		3	0	0	3
Course Objectives	::				
	nd the digital signal processing.				
,	design of sampled data control systems in state space.				
To impart kno	owledge on digital control algorithms and stability study.				
					_
Unit I INTRODU		9		+	0
	cy and time response analysis and specifications of continuous time syste				
	uous time compensations - continues time PI, PD, PID controllers, Realize, Lead and Lag-Lead compensation schemes - problems.	ZaliO	11 01	บสร	SIC
compensators. Lag	, Lead and Edg Lead compensation schemes problems.				
Unit II SIGNAL	PROCESSING IN DIGITAL CONTROL	9		+	0
Need for digital co	ontrol - Configuration of basic digital control scheme - Principles of signa	al co	nvei	rsio	n ·
	signals - Time domain and frequency domain models for discrete-time sys f analog signals - Practical aspects of the choice of sampling rate - Discre				
on bilinear transforn					
Unit III MODI	ELING AND ANALYSIS OF SAMPLED DATA CONTROL SYSTEM	9	1	+	O
	n description - Z-transform method of description- Z-transform analysis of		nnle	-	_
	ury's stability test - Routh stability criterion on the r-plane - State variable				
	and companion - Jordan canonical models - Discrete state variable n				
	led continuous time plants, Elementary principles.				
	N OF DIGITAL CONTROL ALGORITHMS	9		+	(
Introduction – z-pla	ane specifications of control system design -Digital lead, lag and lag-lead	പറവ	mpei	nsa	t٥
design using freque	ency response plots - Digital lead lag compensator design using Root locus	plot	:s - z	-pla	n
design using freque synthesis – Digital		plot	:s - z	-pla	n
design using freque	ency response plots - Digital lead lag compensator design using Root locus	plot	:s - z	-pla	ne
design using freque synthesis – Digital Converter.	ency response plots - Digital lead lag compensator design using Root locus	plot	:s - z	-pla	n
design using freque synthesis – Digital Converter. Unit V PRACTIO	ency response plots - Digital lead lag compensator design using Root locus controllers for deadbeat performance – Examples: Digital Controller De	plot esigr	s - z n for	-pla Bu	cł
design using frequesynthesis – Digital Converter. Unit V PRACTION Development and	ency response plots - Digital lead lag compensator design using Root locus controllers for deadbeat performance – Examples: Digital Controller Decay CAL ASPECTS OF DIGITAL CONTROL ALGORITHMS	s plotesign	s - z n for	-pla Bu +	in ck
design using frequesynthesis – Digital Converter. Unit V PRACTION Development and temperature controposition/speed, cor	controllers for deadbeat performance – Examples: Digital Controller Description of digital PID control algorithms – Tunable PID control algorithm - Digital position control system: Control algorithm - Stepping motors and their controls: Torque-speed curves	s plotesign 9 roller reme	s - z n for s - l	-pla Bu + Digi	in ck (ita
design using frequesynthesis – Digital Converter. Unit V PRACTION Development and temperature controposition/speed, cor	ency response plots - Digital lead lag compensator design using Root locus controllers for deadbeat performance – Examples: Digital Controller Description of Digital Controller Description of Digital PID control algorithms – Tunable PID control system: Control algorithm - Digital position control system: Digital measurements.	s plotesign 9 roller reme	s - z n for s - l	-pla Bu + Digi	(lita
design using frequesynthesis – Digital Converter. Unit V PRACTION Development and temperature controposition/speed, cor	controllers for deadbeat performance – Examples: Digital Controller Description of digital PID control algorithms – Tunable PID control algorithm - Digital position control system: Control algorithm - Stepping motors and their controls: Torque-speed curves	9 oller reme	s - z n for s - l ent o	+ Digi	in cl ita o
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design using frequesynthesis – Digital Converter. Unit V PRACTION Development and temperature controposition/speed, constepper motors to make the proper motors to make the p	CAL ASPECTS OF DIGITAL CONTROL ALGORITHMS implementation of digital PID control algorithms – Tunable PID control algorithm - Digital position control system: Digital measurantrol algorithm - Stepping motors and their controls: Torque-speed curves incroprocessors, Design of fuzzy logic controllers, Fuzzy control of water heat this course, the students will be able to:	9 oller reme	s - z n for s - l ent o	+ Digi	in cl ita o
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design using frequesynthesis – Digital Converter. Unit V PRACTION Development and temperature controposition/speed, constepper motors to make the proper motors to make the p	CAL ASPECTS OF DIGITAL CONTROL ALGORITHMS implementation of digital PID control algorithms – Tunable PID control algorithm - Digital position controls: Torque-speed curves, nicroprocessors, Design of fuzzy logic controllers, Fuzzy control of water heat this course, the students will be able to: wedge about digital control scheme. wedge about sampling techniques. the various digital control algorithms. the various types of digital controllers and compensators. wedge about applications of digital control. ital Control and Static Variable Methods", Tata McGraw Hill, New Delhi, 2012 M.Gopal, "Control Systems Engineering", New Age International Publishe	9 oller reme, Inter.	ss - z n for	+ Digif f shing	(data a
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design using frequesynthesis – Digital Converter. Unit V PRACTION Development and temperature controposition/speed, constepper motors to make the proper motors to make the p	CAL ASPECTS OF DIGITAL CONTROL ALGORITHMS implementation of digital PID control algorithms – Tunable PID control algorithm - Digital position controls: Torque-speed curves, nicroprocessors, Design of fuzzy logic controllers, Fuzzy control of water heat this course, the students will be able to: wedge about digital control scheme. wedge about sampling techniques. the various digital control algorithms. the various types of digital controllers and compensators. wedge about applications of digital control. ital Control and Static Variable Methods", Tata McGraw Hill, New Delhi, 2012 M.Gopal, "Control Systems Engineering", New Age International Publishe	9 oller reme, Inter.	ss - z n for	+ Digif f shing	(data a
design using frequesynthesis – Digital Converter. Unit V PRACTION Development and temperature controposition/speed, constepper motors to make the proper motors to make the p	CAL ASPECTS OF DIGITAL CONTROL ALGORITHMS implementation of digital PID control algorithms – Tunable PID control algorithm - Digital position control system: Digital measurable processors, Design of fuzzy logic controllers, Fuzzy control of water heat Total (L+ ithis course, the students will be able to: wedge about digital control scheme. wedge about sampling techniques. the various digital control algorithms. the various dypes of digital controllers and compensators. wedge about applications of digital control. ital Control and Static Variable Methods", Tata McGraw Hill, New Delhi, 2012 M.Gopal, "Control Systems Engineering", New Age International Publishe on. all Control Systems, Oxford University Press, 2nd Edition, 2007.	9 oller remeder. T)= 4	Editi	+ Digitification on. Delification	(itaa co

PO CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Get knowledge about digital control scheme.	1	1	1	1	1	1	1	1	1	2	1
CO2	Get knowledge about sampling techniques.	1	1	1	1	1	1	1	1	1	2	1
CO3	Design the various digital control algorithms.	1	1	2	2	3	1	3	2	1	2	1
CO4	Design the various types of digital controllers and compensators.	1	3	3	3	3	1	3	3	1	2	1
CO5	Get knowledge about applications of digital control.	2	2	3	3	3	1	2	3	1	2	1

18PEE21	ADVANCED POWER ELECTRONIC CIRCUITS	L	Т	Р	С
		3	0	0	3
Course Objective	s:				
1. To provide e	exposure of advanced power electronic converters utilized by the industries ar	nd ut	ilitie	s	
<u>. </u>					
	PULSE CONVERTERS		9	+	0
rectifiers, operation converters, Application					
Unit II PULSE	-WIDTH-MODULATED DC-DC CONVERTERS		9	+	0
	 Half bridge and full-bridge converters , SEPIC Converter; Interleaved be ed topologies, continuous and discontinuous conduction modes of operation, 				
Unit III HIGH F	POWER CONVERTERS		9	+	0
Multi-Level Inverte	rs of Diode Clamped Type and Flying Capacitor Type and suitable modulations of Cascade Type, Series Inverters. Analysis of Series Inverters. Modified S		ate	gies	-
Unit IV BIDIRE	CTIONAL CONVERTERS		9	+	0
Single Phase and	three Phase bidirectional converters in rectifier mode, control of DC volta	ige	- cc	ntro	of
Input Current. Hys	steresis control in Single Phase and three Phase inverter mode - Frequent switching frequency control methods.				
Unit V EMI AN	D FILTERING		9	+	0
EMI Generation a	and Filtering in power converters - Conducted and Radiated Emission	Me	cha	nism	s.
Techniques to rec	luce Emissions. Shielding and Grounding. Power Circuit Layout for minir nd Output. Effect of EMI Filter on converter Control Dynamics				
	Total (L ₁	·T)=	45 I	Perio	ds
Course Outcomes					
	f this course, the students will be able to:				
	e operating modes of new DC-DC voltage regulators				
	ppropriate phase shifting converter for a multi-pulse converter operation				
	an inverter configuration for high power AC applications				
	idirectional converters with optimal component selection				
	hard-switched converters with appropriate control methods				
Reference Books					
	h Power Converters and AC Drives , John Willey & sons, Inc., 2006.				
	ower Electronics: A First Course, John Wiley & Sons, 2012.				
3. B. K Bose M	lodern Power Electronics and AC Drives∥ Pearson Education, 2007.				

PO CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO 9	PO 10	PO 11
CO1	Know the operating modes of new DC-DC voltage regulators	2		1					2			1
CO2	Select appropriate phase shifting converter for a multipulse converter operation	1				2	1					
CO3	Design an inverter configuration for high power AC applications		1		2							2
CO4	Use of bidirectional converters with optimal component selection			3	1							2
CO5	Analyze hard- switched converters with appropriate control methods		3						1			

•	18PI	EE22	DIGITAL SIGNAL PROCESSING FOR POWER ELECTRONICS	LT	Р	С
				3 0	0	3
		01.1				
		Objective				
1.			nd the need for filter, its design			
2.			ection of sensor and transducers to power applications and choice of conditioning	<u>ıg</u>		
3.			erent sampling techniques in AD converters			
4.			ital filters and its design			
5.	lo	understa	nd and learn different parameter measurements			
Unit	. 1	INTRO	DUCTION TO DIGITAL SIGNAL PROCESSING	9		0
•			Quantization Errors - Sampling - Sample and Hold Circuit - Sampling Theore		<u> </u>	
			and its Design - Total Harmonic Distortion		lasiii	y -
Unit	· II	INSTRI	JMENTATION AND CONTROL INTERFACES	9	+	0
			- Sensors and Transducers - Electronic Interface - Signal Conditioning Circ			
			nal Amplifier - Galvanic isolation		, II Cu	
Unit	· III	ΔΝΔΙ	OG SIGNAL DISCRETIZATION	9	+	0
			itial - Simultaneous - Errors in Sampling - A/D Converters suitable for Power E			
Jan	ipiiii	g -oequei	tital - Simultaneous - Emois in Sampling - AD Conveners suitable for 1 ower E	_1600011	103	
Unit	: IV	SIGN	AL FILTRATION AND SEPARATION	9	+	0
			egral Value calculation - Digital Filters - Moving Average Filter - FIR - IIR - Desig	an of fil	ers -	
		entation		g c		
Unit	: V	PARA	AMETER MEASUREMENTS	9	+	0
Pow	er F	actor - R	surement of Voltage and Current - Average - True RMS - Power - Average everse Power Flow - Energy - Fundamental Component identification - THD nent identification			
Cou	rea	Outcome	Total (La	-T)=45	Perio	ds
Cou	136	Outcome	5.			
Upo	n co	mpletion o	of this course, the students will be able to:			
CO1			stand errors in quantization and select appropriate anti-aliasing filter			
CO2		Select	and Design the suitable circuit for data acquisition			
CO3	3 :	Select	the correct AD converter and sampling technique			
CO4	1 :	Choos	e and design appropriate software filter			
COS	5 :	Under	stand and implement measurement and processing for control application and c	develop	,	
			nent algorithms for parameter measurement			
Refe	eren	ce Books				
1.	Krz 20		zański, ⁻ Digital Signal Processing in Power Electronics ControlCircuits , 2 nd Ed	ition, Sp	oring	er,
2.			A.V., Schafer, R.W. and Buck, J.R., Discrete-Time Signals Processing, 2 nd Edit bod Cliffs, 1999.	ion, Pre	entice	€
3.	Arr	illage, J., S ns, Inc., H	Smith, B.C., Watson, N.R. and Wood, A.R., Power System Harmonic Analysis,	John W	iley	&
4.			Digital Power System Protection , Prentice Hall India, 2014			
5.	De mo	stro, R., Noving aver	Matakas, L., Komatsu, W. and Ama, N.R.N., Implementation aspects of acage filter applied to PLLs—comparative study , in Brazilian Power Electronicamado, IEEE, pp. 730-736, 2013.			
	, , ,	,, ai	aaao,, pp. 700 700, 2010.			

PO	CO Statement	PO1	PO2	PO3	PO4	PO5	P06	PO7	PO 8	PO9	PO1 0	PO1
co									O			'
CO1	Understand errors in quantization and select appropriate anti-aliasing filter	1	1	1	1	2						1
CO2	Select and Design the suitable circuit for data acquisition	1	1	1	1	1			1			1
CO3	Select the correct AD converter and sampling technique	1	1	2	2	1			1			1
CO4	Choose and design appropriate software filter	1	2	1	1	1			1			1
CO5	Understand and implement measurement and processing for control application and develop, implement algorithms for parameter measurement	1	1	1	1	1			1			1

18	8PEE23	DYNAMICS OF POWER CONVERTERS	L	Т	Р	С
			3	0	0	3
Cou	rse Objec	tives:	I		I	
1.		de knowledge in dynamic behavior and analyses of the DC-DC converters and the converters with source and load interactions.	ree	pha	se g	rid
Unit		ODUCTION TO DYNAMIC ANALYSIS		9	+	0
		Generalized Dynamic Representations for Voltage fed and Current fed DC-D				
		ad Interactions- Generalized Dynamic Representations for three-phase voltage-f				
		hree-phase voltage fed and current-fed inverters-closed loop dynamics- Genera	lized	l Ca	scad	ed
Cont	roi Schen	nes - Generalized Impedance-Based Stability				
Unit		IAMIC MODELING AND CONTROL OF VOLTAGE FED DC-DC CONVERTERS		9	+	0
		e Control- DOT-controlled converter at open loop with a PWM modulator; Gener				
		namic model of Buck-converter -power stages- topological sub circuit structur				
		earized state space model; Peak Current Mode Control principles- Developme	nt of	· Du	ty-Ra	atio
Cons	straints- P	CM State Spaces and Transfer Functions				
Unit	III DY	NAMIC MODELING AND CONTROL OF CURRENT FED DC-DC CONVERTER	S	9	+	0
Dual	ity Transf	ormation Basics- Duality-Transformed Converters- Voltage-fed and Current-fe	d b	uck,	boo	st
conv	erters; Dy	namic equivalent circuits of current fed current-output converter and current-fed	volt	age	outp	ut
		amic model of current fed Buck, Boost Converters; Duty-Ratio Constraints unde	r PC	CM C	ontr	ol-
PCM	l-controlle	d current-fed buck, boost power-stage converter				
Unit	IV DV	NAMICS OF THREE PHASE INVERTERS		9		0
					T	
		el of Voltage-Fed Inverter- Equivalent switching circuit and average model - L pen-Loop Dynamics; Dynamic Model of Current-Fed Inverter- Equivalent switc				
		I- Linearized Model and Open-Loop Dynamics Control Design of Grid-Connect				
		chronous Reference Frame Phase Locked Loop- Linearized Model of SRF-PLL-				
	RF-PLL	chionous reserved i fame i hase bocked boop- bineanzed model of orti-i bb-	COII		بادىر	J''
Unit		IAMIC MODELING OF THREE PHASE ACTIVE RECTIFIERS AND STABILITY SESSMENT	,	9	+	0
Thre	e Phase a	ctive rectifier -Power stage and Equivalent switch matrix- Equivalent circuit mode	el- S	tate	spac	ce
		of active rectifier using transfer matrices- Open-Loop and closed loop control so				
		Total (L-	-T)=	45 I	Perio	ods
Cou	rse Outco	•	-,			
Upor	n complet	on of this course, the students will be able to:				
CO1		w the dynamic representations of power converters				
C02		re a dynamic model of DC-DC converter				
CO3		ect appropriate control scheme for DC-DC converter with its dynamic model				
CO4		elop state space model for three phase converters				
CO5		ign a suitable controller for for three phase converters				
	rence Bo					
1.	Teuvo S Energy A	untio, ¬Power Electronic Converters:Dynamics and Control in Conventional a pplications∥, Wiley-VCH Verlag GmbH & Co. KGaA, Germany, 2018.	ind I	Ren	ewat	ole
2.		untio, Dynamic Profile of Switched-Mode Converter Modeling, Analysis and Cont	rol, \	Wile	y-VC	H
		mbH & Co. KGaA, Germany, 2009.	,			

PO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO 10	PO 11	
co													
CO1	Know the dynamic representations of power converters	2		3			1	1					
CO2	Make a dynamic model of DC-DC converter	1			2				2			2	
CO3	Select appropriate control scheme for DC-DC converter with its dynamic model		2			3			1			2	
CO4	Develop state space model for three phase converters			1		1							
CO5	Design a suitable controller for three phase converters	1			2						1		

18PEE24	MODULATION CONTROL FOR POWER CONVERTERS	LIT	Р	С
	L	3 0	0	3
Course Objectives	»:			
To understar	nd Necessity and Importance of PWM techniques			
	on of PWM controllers			
Unit I INTRO	DUCTION	9	+	0
Introduction to PE of phase VSI.	converters, Modulation of one inverter phase leg, Modulation of single phas	e, VSI an	d 3	
Unit II MODUL	ATION STRATEGIES	9	+	0
Zero space vector p	placement modulation strategies, Losses-Discontinuous modulation, Modula	ation of C	SI.	
	MODULATION	9	+	0
Over modulation of	converters, programme modulation strategies.			
	MENTATION OF MODULATION CONTROLLER	9	+	0
Pulse width modula	tion for multilevel inverters, Implementation of modulation controller			
11 1/ 1/ D)A/A				_
Unit V PWM		9	+	0
continuing develop	oments in modulation as random PWM, PWM for voltage unbalance, Eff	iect of mi	nımu	m
puise width and dea		.+T)= 45 F	Oorio	de
Course Outcomes		.+ i <i>j</i> = 43 i	EIIO	us
	f this course, the students will be able to:			
	ber the basic concepts of power electronic converters.			
	tand and evaluate the modulation strategies.			
	tand the concepts of over modulation of converters.			
	ne concept of pulse width modulation for inverters.			
	e the practices and suggest suitable measures for continuous development	s in modu	ılatio	<u></u>
Reference Books:	o uno praesioco una cuggost cultura moderno no continuodo de verepiment			-
	Holmes, Thomas A. Lipo, Pulse width modulation of Power Converter: Prince	cinles		
	John Wiley & Sons, 03-Oct-2003	Sibios		
2. Bin Vew, Hig	h Power Converter , Wiley Publication			
	imicrczuk, Pulse width modulated dc-dc power converter, Wiley Publicatio	n		
	,			

PO	CO Statement	PO1	PO 2	PO 3	PO4	PO 5	PO 6	PO 7	PO 8	PO 9	PO10	PO1 1
CO1	Remember the basic concepts of power electronic converters.	3	1	1	1	1		1	1	1	1	1
CO2	Understand and evaluate the modulation strategies.	2	1	1	3	1		1	1	1	1	1
CO3	Understand the concepts of over modulation of converters.	2	1	1	3	1		1	1	1	1	1
CO4	Apply the concept of pulse width modulation for inverters.	3	1	1	1	1		1	1	1	1	1
CO5	Evaluate the practices and suggest suitable measures for continuous developments in modulation.	2	1	1	1	1	1	3	1	1	1	1

	DESIGN OF POWER CONVERTERS	L	T	Р	С
		3	0	0	3
Course Objectives					
	ut the design concepts and flow.				
2. To implemen	ts the device and circuit concepts for applications				
H-'(L DEGION	DE LINGONTROL LED DECTIFIEDO	-	•		
	OF UNCONTROLLED RECTIFIERS		9	+	0
	ier topology - Pulse number - Power output - Selection of Diode - Voltag				
	ion of DC Filter - Design and Selection of Inductor and Capacitor	witr	n pra	acti	са
considerations					
Unit II DESIGN	OF CONTROLLED RECTIFIERS		9	+	C
	er topology - Pulse number - Power output - Reactive Power Requirements -	Sale			
	Current Ratings - Selection of DC Filter - Design and Selection of Inductor				
	nce and Sequence control for improved power factor operation.	anu	Сар	acii	UI
- mggcmig ocquei	ice and dequence control for improved power factor operation.				
Unit III DESIGI	N OF SWITCH MODE INVERTERS		9	+	(
	er topology - Power output - Harmonics - Reactive Power Requirements	- 9		ion	
Dowar Davicas - V	oltage and Current Ratings - Selection of output Filter - Design and Selection	on c	of Inc	ion tact	ص
and Canacitor - Dif	ferent control strategy for various requirements.	OII C	, ,,,	iuci	UI
and Capacitor Dir	orone control curatogy for various requirements.				
Unit IV DESIGN	N OF SWITCH MODE DC-DC CONVERTERS		9	+	(
	erter topology - Power output - Performance parameters - Selection of Po	ואא	-	-	
	nt Ratings - Selection of Filter - Design and Selection of Inductor, Capac				
	rol strategies for various requirements.	iloi	anu	iCi	
uansionnois. Com	of strategies for various requirements.				H
					110
			9	+	
Unit V DRIVER	S, PROTECTION OF DEVICES AND CONVERTERS	lam	9	+ nern	(
Unit V DRIVER Driver requirement	S, PROTECTION OF DEVICES AND CONVERTERS s - Design of Drivers - Snubber - Polarized and Non-Polarized - Voltage C		ip-Th	ern	(
Unit V DRIVER Driver requirement	S, PROTECTION OF DEVICES AND CONVERTERS		ip-Th	ern	(
Unit V DRIVER Driver requirement	S, PROTECTION OF DEVICES AND CONVERTERS s - Design of Drivers - Snubber - Polarized and Non-Polarized - Voltage C	tion	ip-Th to E	nern MI	(na
Unit V DRIVER Driver requirement Resistances - Mode	S, PROTECTION OF DEVICES AND CONVERTERS s - Design of Drivers - Snubber - Polarized and Non-Polarized - Voltage Ces of Power dissipation - Heat sinking Design - Current Protection - Introduct Total (L+	tion	ip-Th to E	nern MI	(na
Unit V DRIVER Driver requirement Resistances - Mode	S, PROTECTION OF DEVICES AND CONVERTERS s - Design of Drivers - Snubber - Polarized and Non-Polarized - Voltage C es of Power dissipation - Heat sinking Design - Current Protection - Introduct Total (L+	tion	ip-Th to E	nern MI	(na
Unit V DRIVER Driver requirement Resistances - Mode Course Outcomes Upon completion of	S, PROTECTION OF DEVICES AND CONVERTERS s - Design of Drivers - Snubber - Polarized and Non-Polarized - Voltage Ces of Power dissipation - Heat sinking Design - Current Protection - Introduct Total (L+	tion	ip-Th to E	nern MI	na
Unit V DRIVER Driver requirement Resistances - Mode Course Outcomes Upon completion of CO1 : Understa	S, PROTECTION OF DEVICES AND CONVERTERS s - Design of Drivers - Snubber - Polarized and Non-Polarized - Voltage Ces of Power dissipation - Heat sinking Design - Current Protection - Introduct Total (L+ this course, the students will be able to: and design concepts and flow	tion	ip-Th to E	nern MI	na
Unit V DRIVER Driver requirement Resistances - Mode Course Outcomes Upon completion of CO1 : Understa	S, PROTECTION OF DEVICES AND CONVERTERS s - Design of Drivers - Snubber - Polarized and Non-Polarized - Voltage Ces of Power dissipation - Heat sinking Design - Current Protection - Introduct Total (L+ this course, the students will be able to:	tion	ip-Th to E	nern MI	na
Unit V DRIVER Driver requirement Resistances - Mode Course Outcomes Upon completion of CO1 : Understa CO2 : Select th	S, PROTECTION OF DEVICES AND CONVERTERS s - Design of Drivers - Snubber - Polarized and Non-Polarized - Voltage Ces of Power dissipation - Heat sinking Design - Current Protection - Introduct Total (L+ this course, the students will be able to: and design concepts and flow	tion	ip-Th to E	nern MI	na
Unit V DRIVER Driver requirement Resistances - Mode Course Outcomes Upon completion of CO1 : Understa CO2 : Select th CO3 : Select th	S, PROTECTION OF DEVICES AND CONVERTERS s - Design of Drivers - Snubber - Polarized and Non-Polarized - Voltage Coes of Power dissipation - Heat sinking Design - Current Protection - Introduct Total (L+ this course, the students will be able to: and design concepts and flow e appropriate circuit topology for applications	tion	ip-Th to E	nern MI	(na
Unit V DRIVER Driver requirement Resistances - Mode Course Outcomes Upon completion of CO1 : Understa CO2 : Select th CO3 : Select th CO4 : Select an CO5 : Select th	S, PROTECTION OF DEVICES AND CONVERTERS s - Design of Drivers - Snubber - Polarized and Non-Polarized - Voltage Color of Power dissipation - Heat sinking Design - Current Protection - Introduct Total (L+ this course, the students will be able to: and design concepts and flow be appropriate circuit topology for applications be appropriate power devices and design the appropriate circuit to meet the design metrics be circuit configuration for electrical protection and scheme for thermal protection	T)=	to E	erio	(ma
Unit V DRIVER Driver requirement Resistances - Mode Course Outcomes Upon completion of CO1 : Understa CO2 : Select th CO3 : Select th CO4 : Select an CO5 : Select th	S, PROTECTION OF DEVICES AND CONVERTERS s - Design of Drivers - Snubber - Polarized and Non-Polarized - Voltage Color of Power dissipation - Heat sinking Design - Current Protection - Introduct Total (L+ this course, the students will be able to: and design concepts and flow a appropriate circuit topology for applications a appropriate power devices and design the appropriate circuit to meet the design metrics	T)=	to E	erio	od
Unit V DRIVER Driver requirement Resistances - Mode Course Outcomes Upon completion of CO1 : Understa CO2 : Select th CO3 : Select an CO4 : Select th methodo	S, PROTECTION OF DEVICES AND CONVERTERS s - Design of Drivers - Snubber - Polarized and Non-Polarized - Voltage Ces of Power dissipation - Heat sinking Design - Current Protection - Introduct Total (L+* this course, the students will be able to: and design concepts and flow e appropriate circuit topology for applications e appropriate power devices and design the appropriate circuit to meet the design metrics e circuit configuration for electrical protection and scheme for thermal protection of appropriate circuit for applications.	T)=	to E	erio	od
Unit V DRIVER Driver requirement Resistances - Mode Course Outcomes Upon completion of CO1 : Understa CO2 : Select th CO3 : Select th CO4 : Select th CO5 : Select th methodo Reference Books:	S, PROTECTION OF DEVICES AND CONVERTERS s - Design of Drivers - Snubber - Polarized and Non-Polarized - Voltage Ces of Power dissipation - Heat sinking Design - Current Protection - Introduct Total (L+* this course, the students will be able to: and design concepts and flow e appropriate circuit topology for applications e appropriate power devices and design the appropriate circuit to meet the design metrics e circuit configuration for electrical protection and scheme for thermal protection of appropriate circuit for applications.	T)=	and	eric	od ve
Unit V DRIVER Driver requirement Resistances - Mode Course Outcomes Upon completion of CO1 : Understa CO2 : Select th CO3 : Select th CO4 : Select an CO5 : Select th methodo Reference Books: 1. Muhammad H	S, PROTECTION OF DEVICES AND CONVERTERS s - Design of Drivers - Snubber - Polarized and Non-Polarized - Voltage Ces of Power dissipation - Heat sinking Design - Current Protection - Introduct Total (L+* this course, the students will be able to: and design concepts and flow e appropriate circuit topology for applications e appropriate power devices and design the appropriate circuit to meet the design metrics e circuit configuration for electrical protection and scheme for thermal protection of selection of appropriate circuit for applications.	T)=	and	eric	od ve

PO	CO Statement	PO1	PO 2	PO 3	PO4	PO 5	PO 6	PO 7	PO 8	PO 9	PO10	PO1 1
CO1	Understand design concepts and flow	1	1	1	1	1		1	1	1	1	1
CO2	Select the appropriate circuit topology for applications	1	1	1	1	1		1	1	1	1	1
CO3	Select the appropriate power devices	1	1	1	1	1		1	1	1	1	1
CO4	Select and design the appropriate circuit to meet the design metrics	1	1	1	1	1		1	1	1	1	1
CO5	Select the circuit configuration for electrical protection and scheme for thermal protection and derive methodology for selection of appropriate circuit for applications.	1	1	1	1	1		1	1	1	1	1

18PEE31	ADVANCED POWER QUALITY	L T	Р	C
		3 0	0	3
Course Objectives:				
1. To understand	d the various power quality issues.			
2. To understan	d the concept of power and power factor in single phase and three ph	ase sy	/stem	s
supplying non				
	d the conventional compensation techniques used for power factor corre	ction a	and lo	ac
voltage regula To understand	ition. I the active compensation techniques used for power factor correction and lo	and ha	lancir	
	the active compensation techniques used for load voltage regulation.	Jau ba	iaricii	y.
1 10 0.100.010.				
Unit I INTRODUC	CTION	9	+	(
	cterisation of Electric Power Quality: Transients, short duration and long dur			
	mbalance, waveform distortion, Voltage fluctuations, Power frequency va			
	 power quality problems: poor load power factor, Non linear and unbalance hing in load voltage, Disturbance in supply voltage - Power quality standar 		s, DC	•
onset in loads, rvote	Tillig irriodd voltage, Distarbarice irr suppry voltage - r ower quality staridal	143.		
Jnit II ANALYSI	S OF SINGLE PHASE AND THREE PHASE SYSTEM	9	+	(
	s: single phase sinusoidal voltage source supplying nonlinear loads - sir	ngle pł	nase	าด
	source supplying nonlinear loads,			,
	 three phase sinusoidal balanced system – instantaneous real and reac s-symmetrical components- three phase non-sinusoidal balanced system 			
	s- symmetrical components- three phase non-sinusoidal balanced system three phase system.	III- UIII	Jaiaii	Je
	rom commercial loads: SMPS-fluorescent lighting-ASD, Harmonic sources	from	ndus	tria
	power converter- arcing devices, saturable devices.			
	ENTAL THEORY OF LOAD COMPENSATION	9	+	(
Principle of load con	npensation - some practical aspects of compensator used as voltage regula	ator-		1
Principle of load con Phase balancing a	npensation - some practical aspects of compensator used as voltage regulated power factor correction of unbalanced load- a generalized approximately.	ator- pach f	or lo	
Principle of load con Phase balancing a	npensation - some practical aspects of compensator used as voltage regula	ator- pach f	or lo	ad
Principle of load con Phase balancing a	npensation - some practical aspects of compensator used as voltage regulated power factor correction of unbalanced load- a generalized approximately.	ator- pach f	or lo	ad
Principle of load con Phase balancing a compensation using	npensation - some practical aspects of compensator used as voltage regulated appropriate power factor correction of unbalanced load- a generalized appropriate symmetrical components, generating reference currents using instantaneous	ator- pach f us PQ	or lo	ad y.
Principle of load con Phase balancing a compensation using Unit IV REALISA	npensation - some practical aspects of compensator used as voltage regulated and power factor correction of unbalanced load- a generalized approximately symmetrical components, generating reference currents using instantaneous ATION AND CONTROL OF DSTATCOM	ator- pach f us PQ	or lo	ad y.
Principle of load con Phase balancing a compensation using Unit IV REALISA DSTATCOM structu	npensation - some practical aspects of compensator used as voltage regular and power factor correction of unbalanced load- a generalized approsymmetrical components, generating reference currents using instantaneous ATION AND CONTROL OF DSTATCOM ure- control of DSTATCOM connected to stiff source- DSTATCOM connected t	ator- pach f us PQ	or lo	ad y.
Principle of load con Phase balancing a compensation using Unit IV REALISA DSTATCOM structu	npensation - some practical aspects of compensator used as voltage regulated and power factor correction of unbalanced load- a generalized approximately symmetrical components, generating reference currents using instantaneous ATION AND CONTROL OF DSTATCOM	ator- pach f us PQ	or lo	ad y.
Principle of load con Phase balancing a compensation using Unit IV REALISA DSTATCOM structus supply point-DSTAT	npensation - some practical aspects of compensator used as voltage regular and power factor correction of unbalanced load- a generalized approsymmetrical components, generating reference currents using instantaneous ATION AND CONTROL OF DSTATCOM ure- control of DSTATCOM connected to stiff source- DSTATCOM connected t	ator- pach f us PQ	or lo	ad y.
Principle of load con Phase balancing a compensation using Unit IV REALISA DSTATCOM structu supply point-DSTAT Unit V SERIES C	npensation - some practical aspects of compensator used as voltage regular and power factor correction of unbalanced load- a generalized approxymmetrical components, generating reference currents using instantaneous arrows and approximately components. ATION AND CONTROL OF DSTATCOM are- control of DSTATCOM connected to stiff source- DSTATCOM connected control through phasors-DSTATCOM in Voltage control mode.	pator- pach fus PQ 9 ected	or lo	ad y. (eak
Principle of load con Phase balancing a compensation using Unit IV REALISA DSTATCOM structus supply point-DSTAT Unit V SERIES C Rectifier supported I cower factor and fee	npensation - some practical aspects of compensator used as voltage regular and power factor correction of unbalanced load- a generalized approsymmetrical components, generating reference currents using instantaneous symmetrical components, generating reference currents using instantaneous area control of DSTATCOM connected to stiff source- DSTATCOM connected to stiff source- DSTATCOM connected control through phasors-DSTATCOM in Voltage control mode compensation using DVR approach principle-characteristics for eder resistance- mathematical description to compute DVR voltage - transies	9 ected 9 or diffeent ope	+ to we	addyy.
Principle of load con Phase balancing a compensation using Unit IV REALISA DSTATCOM structus supply point-DSTAT Unit V SERIES C Rectifier supported I cower factor and feel DVR - realization of	Inpensation - some practical aspects of compensator used as voltage regular and power factor correction of unbalanced load- a generalized approxymmetrical components, generating reference currents using instantaneous symmetrical components, generating reference currents using instantaneous and the symmetrical components, generating reference currents using instantaneous and the symmetrical components of DSTATCOM connected to stiff source- DSTATCOM connected components control through phasors-DSTATCOM in Voltage control mode COMPENSATION USING DVR DVR - DC Capacitor supported DVR - Operating principle-characteristics for eder resistance- mathematical description to compute DVR voltage - transite DVR voltage using voltage source inverter- maximum compensation capa	9 ected 9 or diffeent ope	+ to we	ad y.
Principle of load con Phase balancing a compensation using Jnit IV REALISA DSTATCOM structure Supply point-DSTAT Jnit V SERIES C Rectifier supported leading to the cover factor and feel over factor of without real powers.	npensation - some practical aspects of compensator used as voltage regular and power factor correction of unbalanced load- a generalized approsymmetrical components, generating reference currents using instantaneous symmetrical components, generating reference currents using instantaneous are control of DSTATCOM connected to stiff source- DSTATCOM connected control through phasors-DSTATCOM in Voltage control mode COMPENSATION USING DVR DVR - DC Capacitor supported DVR - Operating principle-characteristics for eder resistance- mathematical description to compute DVR voltage - transic DVR voltage using voltage source inverter- maximum compensation capa support from DC-Link.	9 ected 9 or diffeent ope	+ to we	ad y.
Principle of load con Phase balancing a compensation using Jnit IV REALISA DSTATCOM structure Supply point-DSTAT Jnit V SERIES C Rectifier supported leading to the cover factor and feel over factor of without real powers.	Inpensation - some practical aspects of compensator used as voltage regular and power factor correction of unbalanced load- a generalized approxymmetrical components, generating reference currents using instantaneous symmetrical components, generating reference currents using instantaneous and the symmetrical components, generating reference currents using instantaneous and the symmetrical components of DSTATCOM connected to stiff source- DSTATCOM connected components control through phasors-DSTATCOM in Voltage control mode COMPENSATION USING DVR DVR - DC Capacitor supported DVR - Operating principle-characteristics for eder resistance- mathematical description to compute DVR voltage - transite DVR voltage using voltage source inverter- maximum compensation capa	9 ected s. 9 or diffeent ope	+ to we	ad y.
Principle of load con Phase balancing a compensation using Unit IV REALISA DSTATCOM structus supply point-DSTAT Unit V SERIES C Rectifier supported I cower factor and fee DVR - realization of without real power s	npensation - some practical aspects of compensator used as voltage regular and power factor correction of unbalanced load- a generalized approsymmetrical components, generating reference currents using instantaneous symmetrical components, generating reference currents using instantaneous are control of DSTATCOM connected to stiff source- DSTATCOM connected control through phasors-DSTATCOM in Voltage control mode COMPENSATION USING DVR DVR - DC Capacitor supported DVR - Operating principle-characteristics for eder resistance- mathematical description to compute DVR voltage - transic DVR voltage using voltage source inverter- maximum compensation capa support from DC-Link.	9 ected e. 9 or diffeent opecity of	+ to we	ad y. ad ad ad oa
Principle of load con Phase balancing a compensation using Unit IV REALISA DSTATCOM structus upply point-DSTAT Unit V SERIES CRectifier supported I power factor and fee DVR - realization of without real power sunified power quality	npensation - some practical aspects of compensator used as voltage regular and power factor correction of unbalanced load- a generalized approsymmetrical components, generating reference currents using instantaneous symmetrical components, generating reference currents using instantaneous are control of DSTATCOM connected to stiff source- DSTATCOM connected control through phasors-DSTATCOM in Voltage control mode compensation using DVR - DC Capacitor supported DVR - Operating principle-characteristics for each resistance- mathematical description to compute DVR voltage - transic DVR voltage using voltage source inverter- maximum compensation capa support from DC-Link. y conditioner: Configuration - Types, structure and control characteristics.	9 ected e. 9 or diffeent opecity of	+ to we	ad y. ad ad ad oa
Principle of load con Phase balancing a compensation using Unit IV REALISA DSTATCOM structus supply point-DSTAT Unit V SERIES C Rectifier supported I cower factor and fee DVR - realization of without real power s Unified power quality Course Outcomes: Upon completion of	Inpensation - some practical aspects of compensator used as voltage regular and power factor correction of unbalanced load- a generalized approximately symmetrical components, generating reference currents using instantaneous symmetrical components using instantaneous symmetrical of DSTATCOM connected to stiff source- DSTATCOM connected current control through phasors-DSTATCOM in Voltage control mode COMPENSATION USING DVR DVR - DC Capacitor supported DVR - Operating principle-characteristics for each resistance- mathematical description to compute DVR voltage - transite DVR voltage using voltage source inverter- maximum compensation capa support from DC-Link. Ye conditioner: Configuration - Types, structure and control characteristics. Total (45+	9 ected e. 9 or diffeent opecity of	+ to we	ad y. eak oa n c
Principle of load con Phase balancing a compensation using Directly REALISA DSTATCOM structus supply point-DSTAT Directlifier supported lower factor and fee DVR - realization of without real power sunified power quality Dourse Outcomes: Dourse Outcomes: Dourse Outcomes: Understand CO1	Inpensation - some practical aspects of compensator used as voltage regular and power factor correction of unbalanced load- a generalized approximately symmetrical components, generating reference currents using instantaneous symmetrical components using instantaneous symmetrical of DSTATCOM connected to stiff source- DSTATCOM connected components of the component	9 ected bright graph of the sector of the se	+ to we rent I eratio the [ad y. eak oa n c
Principle of load con Phase balancing a compensation using Unit IV REALISADSTATCOM structure supply point-DSTAT Rectifier supported I cower factor and fee DVR - realization of without real power sunified power quality United DVR - United DVR - I cover factor and fee DVR - realization of without real power sunified power quality United DVR - I cover factor and fee DVR - realization of without real power sunified power quality United DVR - I cover factor and fee DVR - realization of without real power sunified power quality Unified DVR - I cover factor and fee DVR - realization of without real power sunified power quality Unified DVR - I cover factor and fee DVR - realization of without real power sunified power quality Unified DVR - realization of without and fee DVR - realization of without re	Inpensation - some practical aspects of compensator used as voltage regular and power factor correction of unbalanced load- a generalized approximately symmetrical components, generating reference currents using instantaneous symmetrical components using voltage control mode and components of the components of	9 ected bright graph of the sector of the se	+ to we rent I eratio the [ad y. eak oa n c
Principle of load con Phase balancing a compensation using Unit IV REALISA DSTATCOM structure supply point-DSTAT Unit V SERIES OF Rectifier supported In power factor and feet DVR - realization of without real power supported In power quality Course Outcomes: Upon completion of CO1 Understand CO2 Analyse the CO3 Understand CO3 Underst	inpensation - some practical aspects of compensator used as voltage regular and power factor correction of unbalanced load- a generalized approsphene symmetrical components, generating reference currents using instantaneous symmetrical components of DSTATCOM connected to stiff source- DSTATCOM connected to stif	9 ected bright graph of the sector of the se	+ to we rent I eratio the [ad y. eak oa n c
Principle of load complete balancing a compensation using Unit IV REALISA DSTATCOM structure balancing balancing a compensation using Unit V SERIES OF Rectifier supported I cower factor and fee bower factor and fee bo	Inpensation - some practical aspects of compensator used as voltage regular and power factor correction of unbalanced load- a generalized approsymmetrical components, generating reference currents using instantaneous symmetrical components of the string principle components of the control of DSTATCOM connected to stiff source- DSTATCOM connected components of the control through phasors-DSTATCOM in Voltage control modes and the various power appoints of the control of the structure of the stru	9 ected bright graph of the sector of the se	+ to we rent I eratio the [ad y. ad ad ad oa
Principle of load completion of without real power quality Course Outcomes: Upon completion of Without real power supply point power supply point power supply supp	Inpensation - some practical aspects of compensator used as voltage regular and power factor correction of unbalanced load- a generalized approsymmetrical components, generating reference currents using instantaneous symmetrical components using instantaneous symmetrical components using voltage control mode components control through phasors-DSTATCOM in Voltage control mode components using voltage by a confidence of components of the components of the control components of the control configuration components of the control configuration and the conventional load components of the conventional load conventional load conventional load conventional load conventional load conventional load convention	9 ected bright graph of the sector of the se	+ to we rent I eratio the [ad y. iali
Principle of load con Phase balancing a compensation using Unit IV REALISA DSTATCOM structus supply point-DSTAT Unit V SERIES CRECTIFIER SUPPORTED IN THE PROPERTY OF THE PR	Inpensation - some practical aspects of compensator used as voltage regular and power factor correction of unbalanced load- a generalized approsymmetrical components, generating reference currents using instantaneous symmetrical components of the string principle components of the control of DSTATCOM connected to stiff source- DSTATCOM connected components of the control through phasors-DSTATCOM in Voltage control modes and the various power appoints of the control of the structure of the stru	9 ected bright graph of the sector of the se	+ to we rent I eratio the [ad y. iali
Principle of load con Phase balancing a compensation using Unit IV REALISA DSTATCOM structus supply point-DSTAT Unit V SERIES OF Rectifier supported I power factor and fee DVR - realization of without real power sunified power quality Course Outcomes: Understant CO2 : Analyse the CO3 : Understant CO4 : Realize of CO5 : Gain know CO6 : Understant CO6 : Unders	Inpensation - some practical aspects of compensator used as voltage regular and power factor correction of unbalanced load- a generalized approsymmetrical components, generating reference currents using instantaneous symmetrical components using instantaneous symmetrical control of DSTATCOM connected to stiff source- DSTATCOM connected to stiff source- DSTATCOM in Voltage control mode compensation voltage control mode description to compute DVR voltage - transite DVR voltage using voltage source inverter- maximum compensation capa support from DC-Link. In this course, the students will be able to: In this course, the students will be able	9 ected 9 or diffeent opecity of	+ to we rent I peration the E	addy.
Principle of load con Phase balancing a compensation using Unit IV REALISA DSTATCOM structus supply point-DSTAT Unit V SERIES CR Rectifier supported I power factor and fee DVR - realization of without real power sunified power quality Course Outcomes: Understant CO2 : Analyse the CO3 : Understant CO4 : Realize of CO5 : Gain know CO6 : Understant Text Books: 1 Arindam Ghos	Inpensation - some practical aspects of compensator used as voltage regular and power factor correction of unbalanced load- a generalized approsymmetrical components, generating reference currents using instantaneous symmetrical components using instantaneous symmetrical components using voltage control mode components control through phasors-DSTATCOM in Voltage control mode components using voltage by a confidence of components of the components of the control components of the control configuration components of the control configuration and the conventional load components of the conventional load conventional load conventional load conventional load conventional load conventional load convention	9 ected 9 or diffeent opecity of	+ to we rent I peration the E	addy.
Principle of load complete balancing a compensation using What IV REALISA DSTATCOM structus supply point-DSTAT Whit V SERIES Components are supported by power factor and fee DVR - realization of without real power sunified power quality Course Outcomes: Upon completion of CO1 : Understan CO2 : Analyse the CO3 : Understan CO4 : Realize of CO5 : Gain know CO6 : Understan CO4 : Realize of CO5 : Gain know CO6 : Understan CO4 : Realize of CO5 : Gain know CO6 : Understan CO5 : Gain know CO6 : Understan CO5 : Gain know CO6 : Understan CO6 :	Inpensation - some practical aspects of compensator used as voltage regular and power factor correction of unbalanced load- a generalized approsymmetrical components, generating reference currents using instantaneous symmetrical components using instantaneous symmetrical components using instantaneous symmetrical control of DSTATCOM connected to stiff source- DSTATCOM connected to stiff source- DSTATCOM in Voltage control mode components and unbalanced instances. **COMPENSATION USING DVR** DVR - DC Capacitor supported DVR - Operating principle-characteristics for each resistance- mathematical description to compute DVR voltage - transite DVR voltage using voltage source inverter- maximum compensation capa support from DC-Link. **Total (45+** Total (45+** Total (45+** Total (45+** Total (45+** Total (45-** Tota	9 ected 9 or diffeent opecity of	+ rent I eration the C	adday.
Principle of load complete balancing a compensation using Unit IV REALISA DSTATCOM structure supply point-DSTAT Unit V SERIES OF Rectifier supported In power factor and feet power quality Course Outcomes: Unified power quality Course Outcomes: Understant CO1 : Understant CO2 : Analyse the CO3 : Understant CO4 : Realize of CO5 : Gain know CO6 : Understant CO6 : Understant CO6 : Understant CO7 : Arindam Ghos Kluwer Acadent CO8 R. C. Dugan, M. McGraw Hill Pu	Inpensation - some practical aspects of compensator used as voltage regular and power factor correction of unbalanced load- a generalized approsymmetrical components, generating reference currents using instantaneous symmetrical components using instantaneous symmetrical components using instantaneous symmetrical description to strip in Voltage control mode components and control through phasors-DSTATCOM in Voltage control mode components and components are provided by the components of the components of the components of the control of the voltage of the control of the control of the conventional load components of the convention of the conventi	9 ected 9 or diffeent opecity of	+ rent I eration the C	ad y. I (a) Date of the control of

Re	ference Books:
1.	A. J. Arrillaga, Power System Harmonics, John Wiley & Sons, 2 nd Edition, 2003.
2	G.T.Heydt, Electric Power Quality, McGraw-Hill Professional, 2007.
3	Math H. Bollen, Understanding Power Quality Problems, IEEE Press, 2000

PO CO	CO Statement	PO1	PO 2	PO 3	PO4	PO 5	PO 6	PO 7	PO 8	PO 9	PO1 0	PO1 1
CO1	Understand the various power quality issues.	2	1	3	3	1	1				1	1
CO2	Analyze the single and three-phase circuits under non-sinusoidal and unbalanced load conditions	2	3	2	1	1	1				1	1
CO3	Understand the conventional load compensation theories	2	3	2	3	2	1	1	1		1	1
CO4	Realize of DSTATCOM	2	3	2	2	2	2	1	1		2	1
CO5	Gain knowledge on series compensation using DVR	2	3	2	2	2	2	1	1		2	1
CO6	Understand the operation of UPQC	2	3	2	2	2	2	1	1		2	1

	2 HARMONICS AND FILTERS FOR POWER ELECTRONIC CIRCUITS	L	I	Р	С
		3	0	0	3
Course Obje	ctives				
	o impart knowledge on the fundamentals of harmonics				
	o understand the principle of operation of passive power filter				
	o understand the principle of operation of shunt active power filter				
	o understand the principle of operation of series active power filter				
	o understand the principle of operation of series active power litter				
J. 10	o understand the principle of operation of hybrid active power filter				
Unit I	FUNDAMENTALS OF HARMONICS		9	+	0
harmonics – harmonics: H	ism of harmonic generation – Sources of harmonics: commercial and industria Factors influencing - development of harmonic standards – General harmonic armonic evaluations on the utility system, Harmonic evaluation for end-user facilities lseful tools for harmonic assessment: Fourier series, Fourier Transform, DFT, FFT, H	indic s - Ha	es – armor	App	liec tudy
Unit II	PASSIVE POWER FILTER		9	+	0
	: shunt, series - circuit configuration ,principle of operation - Analysis and design		-	n a	_
	- limitation - mitigation of resonance problem of passive filters with the power supply s),, a,	10
Unit III	SHUNT ACTIVE POWER FILTER	!	9	+	0
	, circuit configuration ,principle of operation and control, Analysis and design, monnate - numerical problems	dellin	ıg sin	nulat	ion
Unit IV	SERIES ACTIVE POWER FILTER		9	+	0
	, circuit configuration ,principle of operation and control, Analysis and design, mod	dellin	a sin	nulat	
		a 0	y Siii	iuiut	ЮП
and performa	nce - numerical problems			- Idiai	IOH
Unit V	HYBRID ACTIVE POWER FILTER		9	+	0
Unit V Classification	·		9	+	0
Unit V Classification	HYBRID ACTIVE POWER FILTER , circuit configuration ,principle of operation and control, Analysis and design, mode	lling,	9 simu	+ latio	0
Unit V Classification and performa	HYBRID ACTIVE POWER FILTER , circuit configuration ,principle of operation and control, Analysis and design, mode nce - numerical problems Total (lling,	9 simu	+ latio	0
Unit V Classification and performa Course Outc	HYBRID ACTIVE POWER FILTER , circuit configuration ,principle of operation and control, Analysis and design, mode nce - numerical problems Total (lling,	9 simu	+ latio	0
Unit V Classification and performa Course Outc At the end of	HYBRID ACTIVE POWER FILTER , circuit configuration ,principle of operation and control, Analysis and design, mode nce - numerical problems Total (omes: the course the student will be able to:	lling,	9 simu	+ latio	0
Unit V Classification and performa Course Outc At the end of CO1 :	HYBRID ACTIVE POWER FILTER , circuit configuration ,principle of operation and control, Analysis and design, mode nce - numerical problems Total (omes: the course the student will be able to: Understand the fundamentals of harmonics	lling,	9 simu	+ latio	0
Unit V Classification and performa Course Outc At the end of CO1 : CO2 :	HYBRID ACTIVE POWER FILTER , circuit configuration ,principle of operation and control, Analysis and design, mode nce - numerical problems Total (omes: the course the student will be able to: Understand the fundamentals of harmonics Analyze and design of passive power filter	lling,	9 simu	+ latio	0
Course Outc At the end of CO2 : CO3 :	HYBRID ACTIVE POWER FILTER , circuit configuration ,principle of operation and control, Analysis and design, mode nce - numerical problems Total (incomparison of passive power filter) Analyze and design of passive power filter Analyze and design of shunt active power filter	lling,	9 simu	+ latio	0
Course Outc At the end of CO2 : CO3 : CO4 :	HYBRID ACTIVE POWER FILTER , circuit configuration ,principle of operation and control, Analysis and design, mode nce - numerical problems Total (incomparison) Total (incomparison) Understand the fundamentals of harmonics Analyze and design of passive power filter Analyze and design of series active power filter Analyze and design of series active power filter	lling,	9 simu	+ latio	0
Course Outc At the end of CO1 : CO2 : CO3 :	HYBRID ACTIVE POWER FILTER , circuit configuration ,principle of operation and control, Analysis and design, mode nce - numerical problems Total (incomparison of passive power filter) Analyze and design of passive power filter Analyze and design of shunt active power filter	lling,	9 simu	+ latio	0
Course Outc At the end of CO2 : CO3 : CO4 :	HYBRID ACTIVE POWER FILTER , circuit configuration ,principle of operation and control, Analysis and design, mode nce - numerical problems Total (incomparison) Total (incomparison) Understand the fundamentals of harmonics Analyze and design of passive power filter Analyze and design of series active power filter Analyze and design of series active power filter	lling,	9 simu	+ latio	0
Unit V Classification and performa Course Outc At the end of CO1 : CO2 : CO3 : CO4 : CO5 : Text Books:	HYBRID ACTIVE POWER FILTER , circuit configuration ,principle of operation and control, Analysis and design, mode nce - numerical problems Total (omes: the course the student will be able to: Understand the fundamentals of harmonics Analyze and design of passive power filter Analyze and design of series active power filter Analyze and design of hybrid active power filter Analyze and design of hybrid active power filter	lling,	9 simu = 45	+ lation	0 ods
Course Outc At the end of CO2 : CO3 : CO4 : CO5 : Text Books:	HYBRID ACTIVE POWER FILTER , circuit configuration ,principle of operation and control, Analysis and design, mode nce - numerical problems Total (incomparison) Total (incomparison) Understand the fundamentals of harmonics Analyze and design of passive power filter Analyze and design of series active power filter Analyze and design of series active power filter	lling,	9 simu = 45	+ lation	ods
Course Outc At the end of CO2 : CO3 : CO4 : CO5 : Text Books: 1. Po Ha	HYBRID ACTIVE POWER FILTER , circuit configuration ,principle of operation and control, Analysis and design, mode nce - numerical problems Total (Independent of the student will be able to: Understand the fundamentals of harmonics Analyze and design of passive power filter Analyze and design of series active power filter Analyze and design of hybrid active power filter	lling,	9 simu = 45	+ lation	ods
Course Outc At the end of CO2 : CO3 : CO4 : CO5 : Text Books: 1. Po Ha 2. Ele Mo	HYBRID ACTIVE POWER FILTER , circuit configuration ,principle of operation and control, Analysis and design, mode nce - numerical problems Total (Incomparison of the student will be able to: Understand the fundamentals of harmonics Analyze and design of passive power filter Analyze and design of shunt active power filter Analyze and design of series active power filter Analyze and design of hybrid active power filter Analyze and design of hybrid active power filter Analyze and design of hybrid active power filter wer quality problems and mitigation techniques Bhim Singh, Ambrish Chandra ddad John Wiley and Sons limited, First Edition 2015 extrical power system quality Roger C. Dugan, Mark F.McGranaghan, Surya Santoso Graw – Hill publications, Second Edition 2009.	lling,	9 simu = 45	+ lation	ods
Course Outc At the end of CO2 : CO3 : CO4 : CO5 : Text Books: 1. Po Ha 2. Ele Mc Reference B	HYBRID ACTIVE POWER FILTER , circuit configuration ,principle of operation and control, Analysis and design, mode nce - numerical problems Total (incompose) Understand the student will be able to: Understand the fundamentals of harmonics Analyze and design of passive power filter Analyze and design of shunt active power filter Analyze and design of series active power filter Analyze and design of hybrid active power filter Analyze and design of hybrid active power filter Analyze and design of hybrid active power filter wer quality problems and mitigation techniques Bhim Singh, Ambrish Chandra ddad John Wiley and Sons limited, First Edition 2015 extrical power system quality Roger C. Dugan, Mark F.McGranaghan, Surya Santoso Graw – Hill publications, Second Edition 2009.	lling, L+T)	9 simu = 45 Kam	+ lation	ods
Course Outc At the end of CO2 : CO3 : CO4 : CO5 : Text Books: 1. Po Ha 2. Ele Mc Reference B	HYBRID ACTIVE POWER FILTER , circuit configuration ,principle of operation and control, Analysis and design, mode nce - numerical problems Total (Incomparison of the student will be able to: Understand the fundamentals of harmonics Analyze and design of passive power filter Analyze and design of shunt active power filter Analyze and design of series active power filter Analyze and design of hybrid active power filter Analyze and design of hybrid active power filter Analyze and design of hybrid active power filter wer quality problems and mitigation techniques Bhim Singh, Ambrish Chandra ddad John Wiley and Sons limited, First Edition 2015 extrical power system quality Roger C. Dugan, Mark F.McGranaghan, Surya Santoso Graw – Hill publications, Second Edition 2009.	lling, L+T)	9 simu = 45 Kam	+ lation	ods

	CO Statement	PO1	РО	РО	PO4	РО	РО	РО	РО	РО	PO1	PO1
PO			2	3		5	6	7	8	9	0	1
co												
CO1	Understand the fundamentals of harmonics	1	1	3	2	3	1	1	1	1	1	1
CO2	Analyze and design of passive power filter	1	3	2	2	1	1	1		1	1	1
CO3	Analyze and design of shunt active power filter	1	3	2	2	1	1	1		1	1	1
CO4	Analyze and design of series active power filter	1	3	2	2	1	1	1		1	1	1
CO5	Analyze and design of hybrid active power filter	1	3	2	2	1	1	1		1	1	1

18PEE33	ENERGY CONSERVATION, AUDITING AND MANAGEMENT	L	Т	Р	С
		3	0	0	(r)
Oarrage Objections					
Course Objectives:					
	dthe energy conservation concepts. ut electrical energy management.				
Z. 10 KIIOW ADOL	и елесинсат енегду тападеттети.				
Unit I ENERGY	SCENARIO		9	+	(
	f India – Present non-renewable energy scenario – Gross domestic	produ	-		
intensity - Current	energy production and pricing – Energy security - Energy strategy f	for the	futi	ıre	.e≀ ai
	ange. Energy Conservation Act-2001 and its features.	.01 1110	·····	a. 0,	u.
,	- g g,				
Unit II ENERG	Y CONSERVATION APPROACHES		9	+	C
	ntroduction - Work, power and energy - Electricity basics - Thermal		gy b	asic	s
	nversions - Energy performance - Matching energy usage to requirement.				
	rtunities in electric motors, Benefits of Power factor improvement and its				
	ous Condenser etc., Energy conservation by industrial drives, electric fur	naces,	ove	ens a	ano
boilers., Lighting tec	chniques – Natural ,CFL, LED lighting sources and fittings.				
Unit III ENERG	Y AUDITING		9		C
	audit methodology: audit preparation, execution and reporting - Fina	ncial a	_	+ veie	,
	- Project financing options - Energy monitoring and targeting -Energy aud				
lighting systems	- 1 Toject illiancing options - Energy monitoring and targeting -Energy add	iit Oi iiii	OlOI.	s an	u
ngriding bysterns					
Unit IV ENERGY	Y MANAGEMENT		9	+	0
Demand side mana	gement (DSM)- DSM planning - DSM techniques - Load management as	s a DS	SM s	trate	eav
	on - tarrif options for DSM - Energy audit - instruments for energy audit				
	ion and utilization systems - economic analysis.	`			
generation, distribut	•				
generation, distribut Unit V ENERGY	EFFICIENT TECHNOLOGIES		9	+	0
generation, distribut Unit V ENERGY Maximum demand of	EFFICIENT TECHNOLOGIES controllers - Automatic power factor controllers - Energy efficient motors	-Soft s	tarte	ers v	vitl
Unit V ENERGY Maximum demand of energy saver - Variation	EFFICIENT TECHNOLOGIES controllers - Automatic power factor controllers - Energy efficient motors able speed drives - Energy efficient transformers - Electronic ballast - Occ	-Soft s	tarte	ers v	vitl
Unit V ENERGY Maximum demand of energy saver - Variation	EFFICIENT TECHNOLOGIES controllers - Automatic power factor controllers - Energy efficient motors	-Soft s	tarte	ers v	vitl
generation, distribut Unit V ENERGY Maximum demand of energy saver - Varia	EFFICIENT TECHNOLOGIES controllers - Automatic power factor controllers - Energy efficient motors - able speed drives - Energy efficient transformers - Electronic ballast - Occiting controls - Energy saving potential of each technology.	-Soft s	tarte y se	ers v enso	vitl rs
generation, distribut Unit V ENERGY Maximum demand of energy saver - Variate Energy efficient light	EFFICIENT TECHNOLOGIES controllers - Automatic power factor controllers - Energy efficient motors able speed drives - Energy efficient transformers - Electronic ballast - Occurring controls - Energy saving potential of each technology. Total (I	-Soft s	tarte y se	ers v enso	vitl rs
Unit V ENERGY Maximum demand of energy saver - Variate Energy efficient light Course Outcomes:	EFFICIENT TECHNOLOGIES controllers - Automatic power factor controllers - Energy efficient motors - able speed drives - Energy efficient transformers - Electronic ballast - Occiting controls - Energy saving potential of each technology. Total (I	-Soft s	tarte y se	ers v enso	vitl rs
Unit V ENERGY Maximum demand of energy saver - Variate Energy efficient light Course Outcomes:	EFFICIENT TECHNOLOGIES controllers - Automatic power factor controllers - Energy efficient motors able speed drives - Energy efficient transformers - Electronic ballast - Occurring controls - Energy saving potential of each technology. Total (I	-Soft s	tarte y se	ers v enso	vitl rs
Unit V ENERGY Maximum demand of energy saver - Variate Energy efficient light Course Outcomes: Upon completion of	EFFICIENT TECHNOLOGIES controllers - Automatic power factor controllers - Energy efficient motors able speed drives - Energy efficient transformers - Electronic ballast - Occiting controls - Energy saving potential of each technology. Total (I	-Soft s	tarte y se	ers v enso	vitl rs
Unit V ENERGY Maximum demand of energy saver - Variate Energy efficient light Course Outcomes: Upon completion of CO1 : Understate	EFFICIENT TECHNOLOGIES controllers - Automatic power factor controllers - Energy efficient motors able speed drives - Energy efficient transformers - Electronic ballast - Occiting controls - Energy saving potential of each technology. Total (In this course, the students will be able to: Indeed the present energy scenario.	-Soft s	tarte y se	ers v enso	vitl rs
Unit V ENERGY Maximum demand of energy saver - Variate Energy efficient light Course Outcomes: Upon completion of CO1 : Understant CO2 : Get fundate ENERGY Maximum demand of energy saver - Variate energy efficient light	EFFICIENT TECHNOLOGIES controllers - Automatic power factor controllers - Energy efficient motors able speed drives - Energy efficient transformers - Electronic ballast - Occiting controls - Energy saving potential of each technology. Total (I this course, the students will be able to: and the present energy scenario. amental knowledge about energy and its various forms.	-Soft s	tarte y se	ers v enso	vitl rs
Unit V ENERGY Maximum demand of energy saver - Variate Energy efficient light Course Outcomes: Upon completion of CO1 : Understate CO2 : Get fundate CO3 : Understate CO3 : Understate	EFFICIENT TECHNOLOGIES controllers - Automatic power factor controllers - Energy efficient motors able speed drives - Energy efficient transformers - Electronic ballast - Occiting controls - Energy saving potential of each technology. Total (I this course, the students will be able to: Ind the present energy scenario. Immental knowledge about energy and its various forms. Ind the process of energy management and energy auditing.	-Soft s	tarte y se	ers v enso	vitl rs
Unit V ENERGY Maximum demand of energy saver - Variate Energy efficient light Course Outcomes: Upon completion of CO1 : Understate CO2 : Get fundate CO3 : Understate CO4 : Understate	EFFICIENT TECHNOLOGIES controllers - Automatic power factor controllers - Energy efficient motors able speed drives - Energy efficient transformers - Electronic ballast - Occiting controls - Energy saving potential of each technology. Total (I this course, the students will be able to: Ind the present energy scenario. Independent energy scenario amental knowledge about energy and its various forms. Ind the process of energy management and energy auditing. Ind the methods improving energy efficiency.	-Soft s	tarte y se	ers v enso	vitl rs
Unit V ENERGY Maximum demand of energy saver - Variate Energy efficient light Course Outcomes: Upon completion of CO1 : Understant CO2 : Get fundate CO3 : Understant CO4 : Understant CO4 : Understant CO4 : Understant	EFFICIENT TECHNOLOGIES controllers - Automatic power factor controllers - Energy efficient motors able speed drives - Energy efficient transformers - Electronic ballast - Occiting controls - Energy saving potential of each technology. Total (I this course, the students will be able to: Ind the present energy scenario. Immental knowledge about energy and its various forms. Ind the process of energy management and energy auditing.	-Soft s	tarte y se	ers v enso	vitl rs
Unit V ENERGY Maximum demand of energy saver - Variate Energy efficient light Course Outcomes: Upon completion of CO1 : Understant CO2 : Get fundate CO3 : Understant CO4 : Understant CO5 : Understant	EFFICIENT TECHNOLOGIES controllers - Automatic power factor controllers - Energy efficient motors able speed drives - Energy efficient transformers - Electronic ballast - Occiting controls - Energy saving potential of each technology. Total (I this course, the students will be able to: Ind the present energy scenario. Immental knowledge about energy and its various forms. Ind the process of energy management and energy auditing. Ind the methods improving energy efficiency. Ind the concepts of energy efficient devices.	-Soft s	tarte y se	ers v enso	vitl rs
Unit V ENERGY Maximum demand of energy saver - Variate Energy efficient light Course Outcomes: Upon completion of CO1 : Understate CO2 : Get fundate CO3 : Understate CO4 : Understate CO5 : U	EFFICIENT TECHNOLOGIES controllers - Automatic power factor controllers - Energy efficient motors able speed drives - Energy efficient transformers - Electronic ballast - Occiting controls - Energy saving potential of each technology. Total (I this course, the students will be able to: Ind the present energy scenario. Independent energy scenario amental knowledge about energy and its various forms. Ind the process of energy management and energy auditing. Ind the methods improving energy efficiency.	-Soft s	tarte y se	ers v enso	vitl rs
Unit V ENERGY Maximum demand of energy saver - Variate Energy efficient light Course Outcomes: Upon completion of CO1 : Understate CO2 : Get fundate CO3 : Understate CO4 : Understate CO5 : U	EFFICIENT TECHNOLOGIES controllers - Automatic power factor controllers - Energy efficient motors able speed drives - Energy efficient transformers - Electronic ballast - Occiting controls - Energy saving potential of each technology. Total (I this course, the students will be able to: Ind the present energy scenario. Immental knowledge about energy and its various forms. Ind the process of energy management and energy auditing. Ind the methods improving energy efficiency. Ind the concepts of energy efficient devices. Energy Audit, Sonal Desai, McGraw Hill, 2015.	-Soft scupanc	45 F	enso	vith
Unit V ENERGY Maximum demand of energy saver - Variate Energy efficient light Course Outcomes: Upon completion of CO1 : Understate CO2 : Get fundate CO3 : Understate CO4 : Understate CO5 : U	EFFICIENT TECHNOLOGIES controllers - Automatic power factor controllers - Energy efficient motors able speed drives - Energy efficient transformers - Electronic ballast - Occiting controls - Energy saving potential of each technology. Total (I this course, the students will be able to: Ind the present energy scenario. Immental knowledge about energy and its various forms. Ind the process of energy management and energy auditing. Ind the methods improving energy efficiency. Ind the concepts of energy efficient devices. Energy Audit, Sonal Desai, McGraw Hill, 2015. Electrical Energy and Conservation, S.C. Tripathy, McGraw Hill, 1980. Ifor National Certification Examination for Energy Manager / Energy Acts (available online).	-Soft scupance	45 F	Perio	vitl rs
Unit V ENERGY Maximum demand of energy saver - Variate Energy efficient light Course Outcomes: Upon completion of CO1 : Understate CO2 : Get fundate CO3 : Understate CO4 : Understate CO5 : U	EFFICIENT TECHNOLOGIES controllers - Automatic power factor controllers - Energy efficient motors able speed drives - Energy efficient transformers - Electronic ballast - Occiting controls - Energy saving potential of each technology. Total (I this course, the students will be able to: Ind the present energy scenario. Immental knowledge about energy and its various forms. Ind the process of energy management and energy auditing. Ind the methods improving energy efficiency. Ind the concepts of energy efficient devices. Energy Audit, Sonal Desai, McGraw Hill, 2015. Energy Audit, Sonal Desai, McGraw Hill, 2015. Idectrical Energy and Conservation, S.C. Tripathy, McGraw Hill, 1980. Ifor National Certification Examination for Energy Manager / Energy Acts (available online). Ifor National Certification Examination for Energy Manager / Energy	-Soft scupance	45 F	Perio	vitl
Unit V ENERGY Maximum demand of energy saver - Variate Energy efficient light Course Outcomes: Upon completion of CO1 : Understate CO2 : Get fundate CO3 : Understate CO4 : Understate CO5 : Un	EFFICIENT TECHNOLOGIES controllers - Automatic power factor controllers - Energy efficient motors able speed drives - Energy efficient transformers - Electronic ballast - Occiting controls - Energy saving potential of each technology. Total (I this course, the students will be able to: Ind the present energy scenario. Ind the process of energy management and energy auditing. Ind the methods improving energy efficiency. Ind the concepts of energy efficient devices. Energy Audit, Sonal Desai, McGraw Hill, 2015. Electrical Energy and Conservation, S.C. Tripathy, McGraw Hill, 1980. Ifor National Certification Examination for Energy Manager / Energy Acts (available online). For National Certification Examination for Energy Manager / Energy ies (available online)	-Soft scupance	45 F	Perio	vitirs
Unit V ENERGY Maximum demand of energy saver - Variate Energy efficient light Course Outcomes: Upon completion of CO1 : Understant CO2 : Get fundate CO3 : Understant CO4 : Understant CO5 : Understant CO6 : Understant CO7 : Understant CO8 : Understant CO9 : Understant CO	EFFICIENT TECHNOLOGIES controllers - Automatic power factor controllers - Energy efficient motors able speed drives - Energy efficient transformers - Electronic ballast - Occiting controls - Energy saving potential of each technology. Total (I this course, the students will be able to: Ind the present energy scenario. Immental knowledge about energy and its various forms. Ind the process of energy management and energy auditing. Ind the methods improving energy efficiency. Ind the concepts of energy efficient devices. Energy Audit, Sonal Desai, McGraw Hill, 2015. Energy Audit, Sonal Desai, McGraw Hill, 2015. Idectrical Energy and Conservation, S.C. Tripathy, McGraw Hill, 1980. Ifor National Certification Examination for Energy Manager / Energy Acts (available online). Ifor National Certification Examination for Energy Manager / Energy	-Soft scupance L+T)=	45 F	Perio	vit

PO CO	CO Statement	PO1	PO 2	PO 3	PO4	PO 5	PO 6	PO 7	PO 8	PO 9	PO10	PO1 1
CO1	Understand the present energy scenario.	1	1	1	1	1	1	3	1	1	1	1
CO2	Get fundamental knowledge about energy and its various forms.	1	1	3	3	1	1	3	1	1	2	1
CO3	Understand the process of energy management and energy auditing.	1	1	2	2	2	1	1	1	1	3	1
CO4	Understand the methods improving energy efficiency.	2	3	2	3	3	1	2	2	1	2	2
CO5	Understand the concepts of energy efficient devices.	2	2	3	3	3	1	2	3	1	2	2

18	PEE34 SPECIAL ELECTRICAL MACHINES AND DRIVES	L	ГР	С
		3 (0	3
Cou	rse Objectives:			
1.	To review the fundamental concepts of permanent magnets and the operation of permanent magnets are the concepts of permanent magnets.	nanent	magr	net
•	brushless DC motors.			
2.	To introduce the concepts of permanent magnet brushless synchronous motors and	Sync	hrono	us
	reluctance motors.			
3.	To develop the control methods and operating principles of switched reluctance motors.			
4.	To introduce the concepts of stepper motors and its applications.			
5.	To understand the basic concepts of other special machines.			
UNI	T I PERMANENT MAGNET BRUSHLESS DC MOTORS	9) <u> </u>	0
_	damentals of permanent magnets - Types - Principle of operation - Magnetic circuit analy			
	que equations - Characteristics and control.	,0.0 _	-ivii u	
	•			
UNI		9		0
	ciple of operation - EMF and Torque equations - Phasor diagram - Power controllers			
	racteristics – Digital controllers – Constructional features, operating principle and ch chronous reluctance motor.	aracte	eristic	S 01
Зуп	sinonous reluctance motor.			
UNI	T III SWITCHED RELUCTANCE MOTORS	9	+	0
Con	structional features - Principle of operation - Torque prediction - Characteristics - Powe	er cont	rollers	; -
Con	trol of SRM drive - Sensorless operation of SRM - Applications.			
UNI		9		0
	structional features -Principle of operation - Types - Torque predictions - Linear and Non-	-linear	analy	sis
- Cr	aracteristics - Drive circuits - Closed loop control - Applications.			
UNI	T V OTHER SPECIAL MACHINES	9) +	0
• • • • •	ciple of operation and characteristics of Hysteresis motor - AC series motors - Linear induc			
	lications.		0.0.	
	Total (L-	⊦T)= 4	Peri	ods
Cou	rse Outcomes:			
_	n completion of this course, the students will be able to:			
CO	1 1			
CO2				
CO	, , ,			
CO				
COS	5 : Understand the necessity of special electrical machines in industry the Books:			
1.	Miller, T.J.E., Brushless Magnet and Reluctance Motor Drives∥, Claredon Press, London,	1989		
2.	Krishnan, R., Switched Reluctance Motor Drives , CRC press, 2001.	1000.		
	Kenjo, T., Stepping Motors and their Microprocessor Controls', Oxford University Pre	ss. Ne	w Del	 lhi.
3.	2000.	,	. 3.	,
Ref	erence Books:			
1.	Kenjo, T & Nagamori, S., Permanent Magnet and Brushless DC Motors', Clarendon I	Press,	Londo	n,
	1988.			
2.	Krishnan, R., Electric Motor Drives , Prentice Hall of India, 2002.			

PO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO1 0	PO1 1
CO1	Gain the knowledge of fundamental concepts of special machines.	1	1	1	1	1	1	3	1	1	1	1
CO2	Develop the phasor diagram of Permanent Magnet Synchronous Motor.	1	2	2	3	1	2	2	1		2	1
CO3	Analyze and design controllers for special Electrical Machines.	1	2	2	2	2	1	1	1	1	3	1
CO4	Learn about characteristics and application of stepper motors.	2	3	2	3	3	1	2	2	1	2	2
CO5	Understand the necessity of special electrical machines in industry	2	2	3	3	3	1	2	3	1	2	2

18PEE	DIGITAL SIMULATION OF POWER ELECTRONICS SYSTEM	L	T	Р	С
		3	0	0	3
Course	Objectives:				
To provi	de knowledge on modeling and simulation of power electronic circuits and systems				
UNIT I	NUMERICAL METHODS IN PASSIVE COMPONENTS		9	+	0
	of numerical methods. Application of numerical methods to solve transients in D.C.	Switche			
	nd R-L-C circuits. Extension to AC circuits.			, .	•
UNIT II	SIMULATION AND MODELLING OF ACTIVE AND PASSIVE COMPONENTS		9	+	0
Modelin	g of diode in simulation. Diode with R, R-L, R-C and R-L-C load with ac supply. Mod	leling o	f SC	R,	<u>. </u>
	GBT and Power Transistors in simulation. Application of numerical methods to R, L		uits v	vith	
power e	ectronic switches. Simulation of gate/base drive circuits, simulation of snubber circu	uits.			
UNIT III	STATE SPACE MODELLING AND SIMULATION OF LINEAR SYSTEMS		9	+	0
	ace modeling and simulation of linear systems. Introduction to electrical machine m	odeling	: ind	uctio	n,
DC, and	synchronous machines, simulation of basic electric drives, stability aspects.				
UNIT IV	SIMULATION OF CONVERTERS AND DC DRIVES		9	+	0
	on of single phase and three phase uncontrolled and controlled (SCR) rectifiers, cor	werters			F
	ated devices- simulation of power factor correction schemes, Simulation of converte				
	imulation of thyristor choppers with voltage, current and load commutation scheme				
	fed dc motor.	s, Silliu	ialio	11 01	
споррсі	ica de motor.				
UNIT V	SIMULATION OF INVERTERS AND AC DRIVES		9	+	0
Simulati	on of single and three phase inverters with thyristors and self-commutated devices,	Space	ecto	r	
	tation, pulse-width modulation methods for voltage control, waveform control. Simu	lation o	f inv	erte	
fed indu	ction motor drives.				
	Total	(L+T)=	45	Peri	ods
Course	Outcomes:				
	mpletion of this course, the students will be able to:				
CO1 :	Understand the concepts of modeling and simulation of power electronics and dri	ves circ	uits.		
CO2 :	Develop algorithm and software models for power electronics and drives application	ons			
CO3 :	Aanalyze the transient and steady performance of the designed models.				
CO4 :	Choose suitable devices or models for appropriate applications				
CO5 :	Identify suitable hardware components for implementation				
	ce Books:				
	nulink Reference Manual , Math works, USA.				
	pert Ericson, Fundamentals of Power Electronics, Chapman & Hall, 1997.				
3. Iss	a Batarseh, _Power Electronic Circuits', John Wiley, 2004Simulink Reference Man	ual , Ma	ath v	ork:	۶,
	· ·				

PO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO 8	PO9	PO1 0	PO1 1
CO1	Understand the concepts of modeling and simulation of power electronics and drives circuits.	3	2	2	2	2	1	2	1	2	1	1
CO2	Develop algorithm and software models for power electronics and drives applications	3	3	3	3	3	3	2	2	2	1	1
CO3	Aanalyze the transient and steady performance of the designed models.	3	3	3	2	2	2	3	3	2	1	1
CO4	Choose suitable devices or models for appropriate applications	3	3	2	3	3	2	2	2	1	2	1
CO5	Identify suitable hardware components for implementation	3	2	2	2	2	1	2	1	2	1	1

		DUATA VALITAIA AVATEM				
·	18PEE41	PHOTO VOLTAIC SYSTEM	L	Т	Р	С
			3	0	0	3
Cou	rse Objective					
1.		the principle of direct solar energy conversion to power using PV technology.				
2.		with the structure, materials and operation of solar cells, PV modules, and arra	ys.			
3. 4.		The concept to design PV systems for various applications.		- ui - 4		
4.	applications	edge on Socio-economic and environmental merits of photovoltaic systems fo	ı a v	anei	y Oi	
Unit		OLTAIC CELL FUNDAMENTALS AND MANUFACTURING		9	+	0
prop	erties, energy	 Principle of direct solar energy conversion into electricity in a solar cell. Ser levels, basic equations. Solar cell, p-n junction, structure. Commercial solar s of single crystalline silicon cells, multi crystalline silicon cells, amorphous sili 	ells	-		m
		dium gallium diselenide cells.				
Unit		DULE PERFORMANCE		9	+	0
	characteristics perature, case	of a PV module, maximum power point, cell efficiency, fill factor, effect of study	irrad	iatio	n aı	nd
Unit	III DESIG	N OF PV SYSTEMS		9	+	0
Des	gn of solar P	V systems and cost estimation. Case study of design of solar PV lantern, solar and other appliances, solar water pumping systems.		_	-	_
Unit	IV CLASS	SIFICATION OF PV SYSTEMS AND COMPONENTS	1	9		0
		ntral Power Station System, Distributed PV System, Stand alone PV system,		9	+	U
		tem, small system for consumer applications, Hybrid solar PV system, Conce		or ca	Jar	
	-					
	•	em components - PV arrays, inverters, batteries, charge controls, net power n	ieter	S. P	V	
ana	y iristaliation, t	pperation, costs, reliability.				
Unit	V PV SYS	TEM APPLICATIONS		9	+	0
		I photovoltaic units, grid-interacting central power stations, standalon				
		supply in remote and rural areas, solar cars, aircraft, space solar power sa	atellit	es.	Soc	io-
ecor	nomic and env	ironmental merits of photovoltaic systems.				
		Total (L+	T)= 4	15 P	erio	ds
Cou	rse Outcome:	5:				
Upo	n completion o	of this course, the students will be able to:				
CO1		nber with the fundamental concepts of Solar Photovoltaic system				
CO2		and the working operation of various components of photovoltaic system				
CO3		e relevant design concepts in any organisation				
CO4		the performance of different PV system.				
CO5	erence Books	te and suggest the economic practices to be carried out for different applicatio	ris.			
1.		n Solanki : Solar photovoltaics: Fundamentals Technology and Applications, S	ecor	nd E	ditio	n,
2.		s of Photovoltaic Modules & Their Applications, by Gopal Nath Tiwari, 9730204, Publisher: Royal Society of Chemistry, 2010				
3.		Systems, 2nd Edition, by James P. Dunlop, ISBN:9780826913081, Publisher: blishers, Inc. 2010	Ame	rica	n	
4.	Jha .A.R, So	olar Cell Technology and Applications∥, CRC Press, 2010.				

PO CO	CO Statement	PO1	PO 2	PO 3	PO4	PO 5	PO 6	PO 7	PO 8	PO 9	PO10	PO1 1
CO1	Remember with the fundamental concepts of Solar Photovoltaic system	1	1	1	1	1	2	3	1	1	1	2
CO2	Understand the working operation of various components of photovoltaic system	1	1	2	2	2	1	1	1	1	3	1
CO3	Apply the relevant design concepts in any organisation	1	1	3	3	1	1	3	1	1	2	1
CO4	Analyze the performance of different PV system.	2	3	2	3	3	1	2	2	1	2	2
CO5	Evaluate and suggest the economic practices to be carried out for different applications.	2	2	3	3	3	3	2	3	2	2	2

1	8PEE42	OPTIMIZATION TECHNIQUES	L	Т	С	
			3	0	0	3
Cour	se Objectives					
1.		 d the need for optimization and different techniques involved and also const 	aints	5.		
2.		ar/Non-linear Programming.				
3.		d the importance of optimization to solve Engineering problems				
4.		etic algorithm for Engineering Optimization				
Unit			9		+	0
Class	epts of optimi sical Ontimizat	zation- Engineering applications - Statement of optimization Problem - ion Techniques: Single and multi variable optimization- Optimization wit				
	ality constrain		09	uun	ty ui	
Unit	II I INEAD	PROGRAMMING	9			0
		g: Standard form-Geometry of LP problems-Theorem of LP - Relation		con	+ /Avit	
		roblems - simplex method and algorithm - Matrix form- two phase method				
		ecomposition- Sensitivity analysis				
Unit	III NONI IN	IEAR PROGRAMMING:	9		_	0
		nethod, conjugates gradient method, Newton's Method, Sequential quadratic		araı	nmir	
		ethod, augmented Lagrange multiplier method	. р. с	9		.9,
11	DVALAR	UO DDOOD AMMINO				
Unit		IIC PROGRAMMING processes, concept of sub-optimization and principle of optimality, Recu	9	- ro	+	0
Unit		C ALGORITHM	9		+	0
Simil	arities and diff	netic Algorithm, working principle, coding of variables, fitness function, erences between GA and traditional methods; Unconstrained and constrain rithm, real coded GA, Advanced GA, global optimization using GA.				
		Total (L-	-T)=	45 F	Perio	ds
Cour	se Outcomes	· · · · · · · · · · · · · · · · · · ·				
Upor	completion of	this course, the students will be able to:				
CO1	: Understa	nd the basics of optimization				
CO2	: Design a	nd formulate Linear Programming optimization problems				
CO3	: Design a	nd formulate unconstraint and constraint optimization problems				
CO4		timization problems to engineering applications				
CO5	: Analyze	the optimization problems using Genetic Algorithm				
Text	Books:					
1		u, S., ¯Engineering Optimization - Theory & Practice∥, New Age Internationa 000.	al (P)	Lin	nited	,
, ,	Kalyanamoy D Pvt. 1995.	Peb, Optimization for Engineering design algorithms and Examples∥, Prentice.	ce H	all c	f Ind	ia
	G.Luenberger 2011.	,- Introduction of Linear and Non-Linear Programming∥, Wesley Publish	ing	Con	npan	у,
Refe	rence Books:					
	Hamdy A. Tah	a, Operations Research - An Introduction , MacMillan Co., Eighth Edition	2010).		
2.	Ronald L Rard				rint,	
	2013					

PO CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Understand the basics of optimization	1	1	1	1	2	3	1	1	1	1	1
CO2	Design and formulate Linear Programming optimization problems	1	1	3	3	2	3	1	2	1	2	1
CO3	Design and formulate unconstraint and constraint optimization problems	1	1	3	3	3	3	3	2	1	2	1
CO4	Apply optimization problems to engineering applications	1	2	3	3	3	3	3	2	1	2	1
CO5	Analyze the optimization problems using Genetic Algorithm	1	2	3	3	3	3	3	3	1	2	1

18	PEE	3 POWER SYSTEM OPTIMIZATION TECHNIQUES	L T P C
			3 0 0 3
		ojectives:	
1.		nderstand the need for optimization and different techniques involved and also const	raints.
2.		now evolutionary computation techniques	
3. 4.		nderstand the importance of particle swarm optimization in power system now advanced and multi objective Optimization	
4.	10 K	now advanced and multi objective Optimization	
Unit		UNDAMENTALS OF OPTIMIZATION	9 + 0
cond	itions	Classification of optimization problems-Unconstrained and Constrained optimization classical Optimization techniques-Linear and non linear programming, Quadratic ger programming	
Unit	II I	EVOLUTIONARY COMPUTATION TECHNIQUES	9 + 0
Evolu Issue	utiona es in	in nature-Fundamentals of Evolutionary algorithms-Working Principles of Gerry Strategy and Evolutionary Programming-Genetic Operators-Selection, Crossove GA implementation- GA based Economic Dispatch solution- GA for unit commit ower flow- GA based state estimation	er and Mutation-
Unit	III	PARTICLE SWARM OPTIMIZATION	9 + 0
Fund (Hybrissue	amer	tal principle-Velocity Updating-Advanced operators-Parameter selection- Hyb GA and PSO, Hybrid of EP and PSO) -Binary, discrete and combinatorial PSO invergence issues- PSO based unit commitment-PSO for reactive power and voltage system reliability and security.	rid approaches -Implementation
Unit	IV	ADVANCED OPTIMIZATION METHODS	9 + 0
		annealing algorithm-Tabu search algorithm-SA and TS for unit commitme	
		n- Bacteria Foraging optimization.	
Unit	V	MULTI OBJECTIVE OPTIMIZATION	9 + 0
Conc	ept c	f pareto optimality-Conventional approaches for multi objective optimization -Mult signment-Sharing function-Economic dispatch using multi objective GA-Multiobjective	
		Total (L-	⊦T)= 45 Periods
Cour	se O	utcomes:	,
Upor	com	pletion of this course, the students will be able to:	
CO1		Understand the basics of optimization	
CO2		To understand the need of optimization in power system	
CO3		Design and formulate power system optimization problems using GA and PSO Understand the basics of advanced optimization techniques.	
CO5		Analyze the optimization problems using multi objective Genetic Algorithm	
-		· · · · · · · · · · · · · · · · · · ·	
Text		S:	
1	Book D.P.ŀ	Kothari and J.S.Dhillon, Power System Optimization, 2nd Edition, PHI learning	private limited,
1.	Book D.P.I 2010	Kothari and J.S.Dhillon, Power System Optimization, 2nd Edition, PHI learning	•
1.	Book D.P.k 2010 Jizho Solim	Kothari and J.S.Dhillon, Power System Optimization, 2nd Edition, PHI learning ang Zhu, Optimization of power system operation, John Wiley and sons Inc publication and Abdel Hady, Abdel Aal Hassan Mantawy, Modern optimization techniques with	n,2009.
1. 2. 3. 4.	Book D.P.k 2010 Jizho Solim Elect	Kothari and J.S.Dhillon, Power System Optimization, 2nd Edition, PHI learning and Zhu, Optimization of power system operation, John Wiley and sons Inc publication and Abdel Hady, Abdel Aal Hassan Mantawy, Modern optimization techniques with the Power Systems, Springer, 2012. Inmoy Deb, Multi objective optimization using Evolutionary Algorithms, John Wiley	n,2009. applications in
1. 2. 3. 4.	D.P.I. 2010 Jizho Solim Elect Kalya 2008	Kothari and J.S.Dhillon, Power System Optimization, 2nd Edition, PHI learning and Zhu, Optimization of power system operation, John Wiley and sons Inc publication analysis and Hady, Abdel Aal Hassan Mantawy, Modern optimization techniques with the Power Systems, Springer, 2012. In Modern Optimization using Evolutionary Algorithms, John World Deb, Multi objective optimization using Evolutionary Algorithms, John World Deb, Multi objective optimization using Evolutionary Algorithms.	n,2009. applications in
1. 2. 3. 4. Refe	Book D.P.k 2010 Jizho Solim Elect Kalya 2008	Kothari and J.S.Dhillon, Power System Optimization , 2nd Edition, PHI learning and Zhu, Optimization of power system operation , John Wiley and sons Inc publication analytic Power Systems , Springer, 2012. Inmoy Deb, Multi objective optimization using Evolutionary Algorithms , John Wiley Books: Books:	applications in liley and Sons,

PO CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Understand the basics of optimization	1	1	1	1	2	3	1	1	1	1	1
CO2	To understand the need of optimization in power system	1	1	2	2	2	3	1	1	1	2	1
CO3	Design and formulate power system optimization problems using GA and PSO	1	1	3	3	3	3	3	3	1	2	1
CO4	Understand the basics of advanced optimization techniques.	1	1	2	2	3	3	2	2	1	2	1
CO5	Analyze the optimization problems using multi objective Genetic Algorithm	1	2	3	3	3	3	2	3	1	2	1

4005544	WIND ENERGY CYCTEM		T	_	_
18PEE44	WIND ENERGY SYSTEM	3	0	0	<u>C</u>
Course Objectives		<u> </u>	•	U	3
Course Objectives					
	derstanding of various aspects related to wind energy systems and technolog	Jy.	•		_
	ergy Fundamentals		9	+	0
facing the wind ind	ram in India and the World: Overview of growth, development, progress a	ana	cnalle	eng	es
	cs, Wind resource assessment, Wind Speeds and scales, Terrain, Roug	hnes	ss W	ind	ı
	Content, Principles of Aerodynamics of wind turbine blade, Class of				
	dary Layers, Turbulence.				,
Unit II Wind Me	easurements, Analysis and Energy Estimates & Aerodynamics Theory		9	_	0
	r wind measurements, Wind data analysis, Wind resource estimation.	Re	-	T Iim	
Turbulence Analys	· · · · · · · · · · · · · · · · · · ·	Ь	12 3		ш,
,	, Blade element theory, Blade design, Rotor performance and dynam	cs,	Balaı	ncir	ng
	Blade), Types of loads; Sources of loads				
Unit III Wind T	urbine Technology & Components of Wind Turbine Generator		9	+	0
	Constant Speed Constant Frequency, Variable speed Variable Frequency,	In V		-	
	, Pitch Control, Gear Coupled Generator type, Direct Generator Drive /PMG				
Sync Generator.					
•	erator Wind Turbine Components and their construction, Direct Rotor Coup	led (Gene	rato	or (
Multipole type)					
Unit IV Modern	Wind Turbine Control & Monitoring System		9	+	0
	stem & Control Algorithms, Protections used & Safety Consideration in Wind	tur		-	_
	with Error codes, SCADA & Databases: Remote Monitoring and Gene				
Operation & Maint	enance for Product Life Cycle, Balancing technique (Rotor & Blade), FACT				
Voltage Ride-Throu	ugh & new trends for new grid codes.				
Unit V Wind Fa	rms & Cost Economics		9	+	0
	e selection of wind farms, power evacuation, and operational problems with	ırid i	-	ice	
	ore wind farms, merits and challenges.	,			
	sessment and R & D costs, Fixed and variable costs, Value of wind ene			сус	le
costing and cash flo	ow of wind power projects, Wind project owners / developers, Wind energy m				
COURSE OUTCOI	Total (L+	1)=	45 P	eric	ds
	of this course, the students will be able to:				
	e concepts of wind energy sources for electricity generation				
	e and analyse the options and estimate the wind energy generation through r	ene	vable		
sources					
	and the concepts and components of wind energy systems.				
CO4 : Underst	and the modern wind turbine control & monitoring system and evaluans	ite i	he c	ont	rol
	e and analyse the wind resource assessment and R & D costs				
Reference Books					
	, "The Generation of Electricity by Wind farms", E & F.N. Spon Ltd, London.(
	y, L. "Wind Energy System " , Prentice Hall Inc . Englewood Cliffs. N.J. (USA	.)			
-	/ind Energy Conversion System" Prentice Hall,(U.K.) Integration of Wind Energy Conversion Systems". Wiley,New York (USA)				
	. A. Mooley, Wind Energy Data for India				
	Energy Resources Survey in India VI				
	thew, Wind Energy : Fundamentals, Resource Analysis and Economics, Sp	rina	er Sc	ien	се
& Business M	edia, March 2006	3			
8. B.H. Khan, N	Ion-Conventional Energy Resources, Tata Mc.Graw Hill Edu Pvt. Ltd.				

PO	CO Statement	PO1	РО	РО	PO4	РО	РО	РО	РО	РО	PO10	PO1
со			2	3		5	6	7	8	9		1
CO1	Apply the concepts of wind energy sources for electricity generation	3	1	1	1	1	1	1	1	1	1	1
CO2	Evaluate and analyse the options and estimate the wind energy generation through renewable sources	1	თ	2	1	2	1	1	1	1	1	1
CO3	Understand the concepts and components of wind energy systems.	2	1	1	3	1	1	1	1	1	1	1
CO4	Understand the modern wind turbine control & monitoring system and evaluate the control algorithms	1	1	1	2	3	1	2	1	1	1	1
CO5	Evaluate and analyse the wind resource assessment and cost economics.	1	1	3	2	1	1	1	1	1	1	1

18PEE45	POWER ELECTRONICS FOR RENEWABLE ENERGY SYSTEM	L	Т	Р	C 3
Course Ohi		3	0	0	3
Course Obj					
	understand the principle of solar and wind energy conversion systems. know inverter structures need for solar and wind energy systems.				
	introduce grid integration methods for solar and wind energy systems.				
Unit I	SOLAR PHOTOVOLTAIC SYSTEM tainable Sun's Energy – Advantages and Conversion Challenge	9		+	0
operation- I-I-V Equation	V Equation and characteristics- Solar PV Modules-Design and Structure, Power curve and rating-Effect of Solar Irradiation and Temperature- Mang-Perturb and Observe algorithm-Incremental conductance algorithms.	e of l	PV r	nodu	ıle-
Unit II	WIND ENERGY CONVERSION SYSTEM	9		+	0
Power Coef	ciple and Components of Wind Energy Conversion System- Power (ricient -Self Excited Induction Generator (SEIG) - Theory of self excitation chronous generator (PMSG) - Autonomous Generation Systems verators.	on –	Per	man	ent
Unit III	FUEL CELL	9		+	0
Intro Proton Exch	duction- Types- Commercial and Manufacturing Issues - Construction ange-Membrane Fuel Cells; Advantages and Disadvantages of Fuel Corcuit; Aspects of Hydrogen as Fuel, Introduction to Bloom energy				
Unit IV	INVERTER STRUCTURES FOR RENEWABLE ENERGY SYSTEM	9		+	0
Neutral Poir Phase solar	eduction- Inverter Structure, control and operation- H5 Inverter - H6 nt Clamped (NPC) Half-Bridge Inverter- H-Bridge Based Boosting In PV Inverters- Two-level back-to-back PWM Inverter- Three-level back neric control structure for a PV inverter	vert	er -	Thr	ee-
Unit V	GRID INTEGRATION OF GREEN ENERGY SYSTEMS	9		+	0
Control sche	eric structure for grid connected PV system- Single stage grid connected erne- Grid Synchronization Techniques for Single-Phase Systems- Grid se-Locked Loop-Control structure of WES- Generator Side Control- WE active and reactive power injection by WES.	Synd	hro	nizat	ion
	Total (45-	-O)=	45 F	Perio	ds
Course Out	·	-,-		J. 10	
	etion of this course, the students will be able to:				
CO1 :	Know solar, fuel cell and wind energy conversion principles.				
CO2 :	Select suitable power inverters for green energy systems.				
CO3 :	Design wind and solar based power plants.				
CO4 :	Design an appropriate system for standalone and grid connected opera	ation			
CO5	Know grid integration challenges with fuel cell, solar and wind energy s	yste	ms.		
Text Books					
	etan Singh Solanki, " Solar Photovoltaics: Fundamentals, Techn olications", PHI Learning Private Limited, New Delhi, 2011.	olog	ies	and	
2. Rei	mus Teodorescu, Grid converters for photovoltaic and wind power syste ey and Sons Ltd Publication, 2011.				
	cha and VG Agilidis, Power Electronic Control In Electrical Systems, Els, Ist Edition, 2006.	sevie	er In	dia F	vt
₁ Fel	ix A. Farret, M. Godoy Simo`es, Integration of Alternative Sources of Energy & Sons, 2006.	ergy	, Joł	nn	

PQ CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Know solar, fuel cell and wind energy conversion principles.		1			1	3			1	2	
CO2	Select suitable power inverters for green energy systems.	2	3								1	
CO3	Design wind and solar based power plants.			2	1			1	2			1
CO4	Design an appropriate system for standalone and grid connected operation.			2				1	2			1
CO5	Know grid integration challenges with fuel cell, solar and wind energy systems.			1	2					1		

	SMART GRID TECHNOLOGY	L	Т	Р	С
		3	0	0	3
Course Obje	ctives:				
	oduce the concepts of Smart Grid, architecture and Functions.				
	illiarize the role of communications technologies in Smart Grid.				
	iliarize control and automation technologies for Smart Grid.				
4. To stud	dy the green energy integration and energy storage systems.				
Unit I	NTRODUCTION TO SMART GRID	9		+	0
	nd Need for Smart Grid, Today's Electric Grid versus Smart Grid, key aspects			ırt G	rid
development	, Smart Grid architecture, Functions of Smart Grid Components, challenges and be	enefi	ts.		
				1	_
	COMMUNICATIONS TECHNOLOGIES	9		+	0
	on infrastructure for the Smart Grid, IEEE 802 architecture and, communication				
	ler IEEE 802, Wireless LANs, ZigBee and 6LoWPAN, ZigBee communication ne				
metering, Po and usage.	wer line communication, Standards for smart metering, Modbus, DNP3, IEC 61850	aata	a st	ructi	ıre
and usage.					
Unit III	CONTROL AND AUTOMATION TECHNOLOGIES	9		+	0
	ing: Benefits, Architecture, Key components and operation, communications are	chite	ctu		or
	ing, Demand-side integration (DSI): Definitions and services provided by DS				
	quipment: architecture, components and functions, Intelligent electronic devices (IE				
	es, Bay controller.	,,		,	
	·				
Unit IV E	NERGY STORAGE SYSTEMS	9		+	0
	I for energy storage in smart grid, Energy storage technologies: operation, featu	rec	ากฝ	USE	
, Flow Datterv					
	, Fuel cell, Superconducting magnetic energy storage systems, Super cap	acito	ors;	pov	wer
converter cor	r, Fuel cell, Superconducting magnetic energy storage systems, Super cap nfigurations for energy storage integration, Energy storage system for solar and wir	acito	ors;	pov	wer
		acito	ors;	pov	wer
converter cor case study.	nfigurations for energy storage integration, Energy storage system for solar and wir	acito	ors;	pov	wer
converter concase study. Unit V GF	nfigurations for energy storage integration, Energy storage system for solar and wir	acitond po	ors; owe	pov r pla	wer nt-
converter concase study. Unit V GF Sustainable	REEN ENERGY INTEGRATION energy options for the smart grid- Solar PV System, Wind Energy and Fuel Cell: 0	acitond po	ors; owe	pov r pla + ion a	wer nt- 0 and
converter concase study. Unit V GF Sustainable of Power elect	REEN ENERGY INTEGRATION energy options for the smart grid- Solar PV System, Wind Energy and Fuel Cell: Coronics technology for grid integration, Penetration and variability issues as	acitond po	ors; owe	pov r pla + ion a	wer nt- 0 and
converter concase study. Unit V GF Sustainable of Power elect	REEN ENERGY INTEGRATION energy options for the smart grid- Solar PV System, Wind Energy and Fuel Cell: 0	acitond po	ors; owe ers	r pla	wer nt- 0 and vith
Unit V GF Sustainable of Power elect sustainable of Course Outc	REEN ENERGY INTEGRATION energy options for the smart grid- Solar PV System, Wind Energy and Fuel Cell: Coronics technology for grid integration, Penetration and variability issues a energy technology, PHEV technology, Impact of PHEV on the Smart Grid. Total (45+6) comes:	acitond po	ors; owe ers	r pla	wer nt- 0 and vith
Unit V GF Sustainable of Power elect sustainable of Course Outc	REEN ENERGY INTEGRATION energy options for the smart grid- Solar PV System, Wind Energy and Fuel Cell: Coronics technology for grid integration, Penetration and variability issues a energy technology, PHEV technology, Impact of PHEV on the Smart Grid. Total (45+6)	acitond po	ors; owe ers	r pla	wer nt- 0 and vith
Course Outc Upon comple CO1 : Ur	REEN ENERGY INTEGRATION energy options for the smart grid- Solar PV System, Wind Energy and Fuel Cell: Coronics technology for grid integration, Penetration and variability issues a energy technology, PHEV technology, Impact of PHEV on the Smart Grid. Total (45+6) comes: tion of this course, the students will be able to: Inderstand the concepts of Smart Grid and its present developments.	acitond po	ors; owe ers	r pla	wer nt- 0 and vith
Course Outo Upon comple CO1 : Ur CO2 : Ge	REEN ENERGY INTEGRATION energy options for the smart grid- Solar PV System, Wind Energy and Fuel Cell: Coronics technology for grid integration, Penetration and variability issues at energy technology, PHEV technology, Impact of PHEV on the Smart Grid. Total (45+6) comes: tion of this course, the students will be able to: inderstand the concepts of Smart Grid and its present developments. et acquainted with the smart resources and other smart devices	acitond po	ors; owe ers	r pla	wer nt- 0 and vith
Course Outc Upon comple CO1 : Ur CO2 : Ge CO3 : Ac	REEN ENERGY INTEGRATION energy options for the smart grid- Solar PV System, Wind Energy and Fuel Cell: Coronics technology for grid integration, Penetration and variability issues at energy technology, PHEV technology, Impact of PHEV on the Smart Grid. Total (45+6) comes: tion of this course, the students will be able to: derstand the concepts of Smart Grid and its present developments. et acquainted with the smart resources and other smart devices quire knowledge of automation and control infrastructure.	acitond po	ors; owe ers	r pla	wer nt- 0 and vith
Course Outc CO1 : Ur CO2 : Ge CO4 : Se	REEN ENERGY INTEGRATION energy options for the smart grid- Solar PV System, Wind Energy and Fuel Cell: Coronics technology for grid integration, Penetration and variability issues at energy technology, PHEV technology, Impact of PHEV on the Smart Grid. Total (45+6) comes: Attion of this course, the students will be able to: Adversard the concepts of Smart Grid and its present developments. Att acquainted with the smart resources and other smart devices quire knowledge of automation and control infrastructure. Allect an energy storage system and its integration with Smart Grids	acitond po	ors; owe ers	r pla	wer nt- 0 and vith
Course Outc CO2 : Ge CO3 : Ac CO4 : Se CO5 : Ide Coase study. Gr	REEN ENERGY INTEGRATION energy options for the smart grid- Solar PV System, Wind Energy and Fuel Cell: Coronics technology for grid integration, Penetration and variability issues at energy technology, PHEV technology, Impact of PHEV on the Smart Grid. Total (45+6) comes: tion of this course, the students will be able to: derstand the concepts of Smart Grid and its present developments. et acquainted with the smart resources and other smart devices quire knowledge of automation and control infrastructure.	acitond po	ors; owe ers	r pla	wer nt- 0 and vith
Course Outo CO2 : Ge CO3 : Ac CO4 : Se CO5 : Ide Text Books:	REEN ENERGY INTEGRATION energy options for the smart grid- Solar PV System, Wind Energy and Fuel Cell: Coronics technology for grid integration, Penetration and variability issues at energy technology, PHEV technology, Impact of PHEV on the Smart Grid. Total (45+6) comes: Attion of this course, the students will be able to: Addressand the concepts of Smart Grid and its present developments. At acquainted with the smart resources and other smart devices Aguire knowledge of automation and control infrastructure. Allect an energy storage system and its integration with Smart Grids Centrify suitable communication networks for smart grid applications	acitond po	ors; owe ers	r pla	wer nt- 0 and vith
Course Outo Upon comple CO1 : Ur CO2 : Ge CO3 : Ac CO4 : Se CO5 : Ide Text Books: 1. James I	REEN ENERGY INTEGRATION Energy options for the smart grid- Solar PV System, Wind Energy and Fuel Cell: Coronics technology for grid integration, Penetration and variability issues at energy technology, PHEV technology, Impact of PHEV on the Smart Grid. Total (45+6) Etion of this course, the students will be able to: Inderstand the concepts of Smart Grid and its present developments. It acquainted with the smart resources and other smart devices Inquire knowledge of automation and control infrastructure. Indeed an energy storage system and its integration with Smart Grids International Energy Storage System and its integration with Smart Grids International Energy Storage System and Its integration with Smart Grids International Energy Storage System and Its Integration States Sta	9 (Converse of Converse of Con	ers iate	poor pla	o o and vith
Course Outo CO3 : G6 CO4 : S6 CO5 : Ide Text Books: Janaka Techno	REEN ENERGY INTEGRATION energy options for the smart grid- Solar PV System, Wind Energy and Fuel Cell: Coronics technology for grid integration, Penetration and variability issues at energy technology, PHEV technology, Impact of PHEV on the Smart Grid. Total (45+6) comes: Attion of this course, the students will be able to: Addressand the concepts of Smart Grid and its present developments. At acquainted with the smart resources and other smart devices Aguire knowledge of automation and control infrastructure. Allect an energy storage system and its integration with Smart Grids Centrify suitable communication networks for smart grid applications	9 Convssoo	ers iate	r pla	o o and vith

PQ CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Understand the concepts of Smart Grid and its present developments.			1		1	1	2			3	
CO2	Get acquainted with the smart resources and other smart devices	1							2	1		
CO3	Acquire knowledge of automation and control infrastructure.		1									1
CO4	Select an energy storage system and its integration with Smart Grids	3	1		1							
CO5	Identify suitable communication networks for smart grid applications				1		1				2	

Conventional power generation: advantages and disadvantages, Energy crises, Nonconventionalenergy (NCE) resources: review of Solar PV, Wind Energy systems, Fuel Cells, micro-turbines, biomass, cogenerationand tidal sources. Unit II DISTRIBUTED GENERATION 9 + 0 Concept of Distributed Generations (DGs), topologies, selection of sources, regulatory standards/framework, Standards for interconnecting Distributed resources to electric power systems: IEEE 1547. DG installation classes, security issues in DG implementations. Energy storage elements: Batteries, ultra-capacitors, flywheels. Captive power plants. Unit II DISTRIBUTED GENERATION PLANNING AND EVALUATION 9 + 0 Planning of DGs - Types of DG Planning Methods - Sitting and Sizing of DGs Optimal Placement of DG Sources in Distribution Systems. Technical impacts of DGs - Computer Aided Sizing and Sitting of DGs for Network Loss Minimisation and Voltage Profile Improvement. Economic and Control Aspects of DGs Market facts. DG Evaluation -Basic Cost Analysis - Cost Evaluation and Schedule of Demand - Modelling Uncertain Costs - Sensitivity Studies on Key Factors. Unit IV IMPACT OF GRID INTEGRATION Requirements for grid interconnection, limits on operational parameters: voltage, frequency, THD, response to grid abnormal operating conditions, islanding issues. Impact of grid integration with NCE sources on existing power system: reliability, stability and power quality issues. Unit V DISTRIBUTED POWER GENERATION SYSTEM AND PROTECTION 9 + 0 DPGs. Resilience-relevant demands and control strategies -Tolerance of Frequency and Voltage Deviations , Frequency and Voltage Regulation, Unintentional Islanding Extreme Climate Disaster and Restoration.DPGS Protection - Protection Issues in DPGS - DPGS Protection to Improve Resilience. Total (L+T)=45 Periods Course Outcomes: Upon completion of this course, the students will be able to:							
Course Objectives: 1. To illiustrate the concept of distributed generation. 2. To familiarize with the integration of DG in distribution systems Unit INTRODUCTION	18F	PEE52	DISTRIBUTED GENERATION	L	T	Р	_
1. To illustrate the concept of distributed generation. 2. To familiarize with the integration of DG in distribution systems Unit INTRODUCTION				3	0	0	3
1. To illustrate the concept of distributed generation. 2. To familiarize with the integration of DG in distribution systems Unit INTRODUCTION	Cours	sa Ohiact	ivas:				
Unit INTRODUCTION							
Unit I INTRODUCTION Conventional power generation: advantages and disadvantages, Energy crises, Nonconventionalenergy (NCE) resources: review of Solar PV, Wind Energy systems, Fuel Cells, micro-turbines, biomass, cogenerationand tidal sources. Unit II DISTRIBUTED GENERATION Concept of Distributed Generations (DGs), topologies, selection of sources, regulatory standards/framework, Standards for interconnecting Distributed resources to electric power systems: IEEE 1547. DG installation classes, security issues in DG implementations. Energy storage elements: Batteries, ultra-capacitors, flywheels. Captive power plants. Unit III DISTRIBUTED GENERATION PLANNING AND EVALUATION IP 0 1 0 1 0 1 0 1 0 1 0 0							
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Unit II DISTRIBUTED GENERATION Oncept of Distributed Generations (DGs), topologies, selection of sources, regulatory standards/framework. Standards for interconnecting Distributed resources to electric power systems: IEEE 1547. DG installation classes, security issues in DG implementations. Energy storage elements: Batteries, ultra-capacitors, flywheels. Captive power plants. Unit III DISTRIBUTED GENERATION PLANNING AND EVALUATION Planning of DGs - Types of DG Planning Methods - Sitting and Sizing of DGs Optimal Placement of DG Sources in Distribution Systems. Technical impacts of DGs - Computer Aided Sizing and Sitting of DGs Network Loss Minimisation and Voltage Profile Improvement. Economic and Control Aspects of DGs Market facts. DG Evaluation - Basic Cost Analysis - Cost Evaluation and Schedule of Demand - Modelling Uncertain Costs - Sensitivity Studies on Key Factors. Unit IV IMPACT OF GRID INTEGRATION Requirements for grid interconnection, limits on operational parameters: voltage, frequency, THD, response to grid abnormal operating conditions, islanding issues. Impact of grid integration with NCE sources on existing power system: reliability, stability and power quality issues. Unit V DISTRIBUTED POWER GENERATION SYSTEM AND PROTECTION 9							
Unit II DISTRIBUTED GENERATION Concept of Distributed Generations (DGs), topologies, selection of sources, regulatory standards/framework, Standards/s for interconnecting Distributed resources to electric power systems: IEEE 1547. DG installation classes, security issues in DG implementations. Energy storage elements: Batteries, ultra-capacitors, flywheels. Captive power plants. Unit III DISTRIBUTED GENERATION PLANNING AND EVALUATION 9 + 0 Planning of DGs - Types of DG Planning Methods - Sitting and Sizing of DGs Optimal Placement of DG Sources in Distribution Systems. Technical impacts of DGs - Computer Aided Sizing and Sizing of DGs optimal Placement of DG Sources in Distribution Systems. Technical impacts of DGs - Computer Aided Sizing and Sizing of DGs for Network Loss Minimisation and Voltage Profile Improvement. Economic and Control Aspects of DGs Market facts. DG Evaluation - Basic Cost Analysis - Cost Evaluation and Schedule of Demand - Modelling Uncertain Costs - Sensitivity Studies on Key Factors. Unit IV IMPACT OF GRID INTEGRATION 9 + 0 Physical Profile Improvements for grid interconnection, limits on operational parameters: voltage, frequency, THD, response to grid abnormal operating conditions, islanding issues. Impact of grid integration with NCE sources on existing power system: reliability, stability and power quality issues. Unit V DISTRIBUTED POWER GENERATION SYSTEM AND PROTECTION 9 + 0 Physical Profile Profi				es, l	biom	ass	,
Concept of Distributed Generations (DGs), topologies, selection of sources, regulatory standards/framework, Standards/ for interconnecting Distributed resources to electric power systems: IEEE 1547. DG installation classes, security issues in DG implementations. Energy storage elements: Batteries, ultra-capacitors, flywheels. Captive power plants. Unit III DISTRIBUTED GENERATION PLANNING AND EVALUATION 9 + 0 Planning of DGs – Types of DG Planning Methods - Sitting and Sizing of DGs Optimal Placement of DG Sources in Distribution Systems. Technical impacts of DGs - Computer Aided Sizing and Sitting of DGs for Network Loss Minimisation and Voltage Profile Improvement. Economic and Control Aspects of DGs Market facts. DG Evaluation - Basic Cost Analysis - Cost Evaluation and Schedule of Demand - Modelling Uncertain Costs - Sensitivity Studies on Key Factors. Unit IV IMPACT OF GRID INTEGRATION 9 + 0 Requirements for grid interconnection, limits on operational parameters: voltage, frequency, THD, response to grid abnormal operating conditions, islanding issues. Impact of grid integration with NCE sources on existing power system: reliability, stability and power quality issues. Unit V DISTRIBUTED POWER GENERATION SYSTEM AND PROTECTION 9 + 0 Introduction - Configurations of Typical Distributed Power Generation Systems (DPGS)- Wind DPGs and PV DPGs. Resilience-relevant demands and control strategies - Tolerance of Frequency and Voltage Deviations, Frequency and Voltage Regulation, Unintentional Islanding Extreme Climate Disaster and Restoration.DPGS Protection - Protection Issues in DPGS - DPGS Protection to Improve Resilience. CO2 : Analyse the inspact of DGs in distribution system and challenges in grid integration. Reference Books: 1. Distributed Generation - Planning and Evaluation, H. Lee Willis & Walter G. Scott, CRC Press. 2. Handbook of Distributed Generation Electric Power Technologies, Economics and Environmental Impacts, Ramesh Bansal, Springer 2. Distributed Generation	cogen	erationar	d tidal sources.				
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Standards for interconnecting Distributed resources to electric power systems: IEEE 1547. DG installation classes, security issues in DG implementations. Energy storage elements: Batteries, ultra-capacitors, flywheels. Captive power plants. Unit III				arde	_	T	_
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PO	CO Statement	PO1	РО	РО	PO4	РО	РО	РО	РО	РО	PO10	PO1
со			2	3		5	6	7	8	9		1
CO1	Understand the concept of distributed generation and topologies.	3	1	2	1	1	1	3	1	1	1	1
CO2	Analyse the size and location of distributed generation.	2	3	3	3	2	2	3	2	1	2	2
CO3	Analyse the impact of DGs in distribution system and challenges in grid integration.	2	3	3	2	3	2	2	2	1	3	2
CO4	Understand the distributed power generation protection schemes	3	2	2	1	2	2	2	1	1	1	1
CO5	Analyse the planning and operational issues related to distributed generation.	2	3	3	3	3	3	2	1	1	3	2

18PEE53	FACTS CONTROLLERS	L	Т	Р	С
		3	0	0	3
Carrea Objective	·				
Course Objective					
	e active and reactive power flow control in power system				
	and the need for static shunt and series compensators and develop di	ittere	ent c	onti	roı
3. To understa	or compensation. and the principle of operation of UPFC and IPFC.				
	and the concept of coordination of FACTS controllers.				
4. TO dilucisto	and the concept of coordination of 1 ACTO controllers.				
Unit I FACTS	CONCEPTS		9	+	0
	ow control in power systems-Control of dynamic power imbalances in power	SVS		Pov	
	traints of maximum transmission line loading-Basic types of FACTS control				
	ion line compensation-Uncompensated line-Shunt and series compensation p				
	· · · · · · · · · · · · · · · · · · ·				
Unit II STATIO	SHUNT COMPENSATORS		9	+	0
	ssive VAR compensator-Static shunt compensators: SVC and STATCOM-C			an	ıd
control of TSC, TO	CR and STATCOM-Compensator control-Comparison between SVC and STA	TCC	M.		
	C SERIES COMPENSATOR			+	0
	Phase angle regulators-TCVR and TCPAR operation and control-Application			erie	es
compensation: Go	CSC, TSSC, TCSC and Static synchronous series compensators and their cor	ntrol.			
Unit IV COME	BINED AND SPECIAL PURPOSE FACTS CONTROLLERS	ı	9		0
		ntro		+ IDE	
	ping-Unified Power Flow Controller: Circuit arrangement, operation and co P and Q control-Independent real and reactive power flow control-Application				
	P and Q control-independent real and reactive power flow control-Applica				
Dower Flow Contr		atioi	15- 111	CIII	
Power Flow Conti	oller (IPFC): Basic operation, structure and applications.	auoi	15- 111	CIII	-
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Unit V COORI Controller interact TCSC interaction techniques – Emevaluation of diffe Course Outcome Upon completion CO1 : Remen CO2 : Unders CO3 : Analyz CO4 : Apply to CO5 : Unders Text Books: 1. N.G. Hingora Transmissio 2. K.R. Padiya Publishers, 2 Arindam Ghe Science, 200 Reference Books 1. X.P. Zhang,	DINATION OF FACTS CONTROLLERS Stions - SVC-SVC interaction - SVC-HVDC interaction - SVC -TCSC interaction - SVC-SVC interaction - SVC-HVDC interaction - SVC -TCSC interaction - Coordination of multiple controllers using linear control techniques - Nonerging FACTS Controllers: The STATCOM - The SSSC - The UPFC - rent FACTS controllers. Total (L+ss: Of this course, the students will be able to: Inber knowledge about reactive power flow control in power systems. It and various static series and shunt compensation techniques. In the structure and principle of operation of FACTS devices. In the FACTS devices at suitable location in power system networks. It and the co-ordination of FACTS controllers. In Systems In IEEE Press Book, Standard Publishers and Distributors, Delhi, 20 or, FACTS Controllers in Power Transmission and Distribution New Age 2007. Dosh, Gerard Ledwich, Power Quality Enhancement using Custom Power Dev 22. St. C. Rehtanz, B. Pal, Flexible AC Transmission Systems- Modelling and Controllers and Controllers and Controllers and Controllers and Controllers and Controllers and Controllers.	AC 01. Inte	9 on - T ear c mpai	+ CS ontrativ	o GC-trollwe
Unit V COORI Controller interact TCSC interaction techniques – Emevaluation of diffe Course Outcome Upon completion CO1 : Remen CO2 : Unders CO3 : Analyze CO4 : Apply to CO5 : Unders Text Books: 1. N.G. Hingora Transmissio 2. K.R. Padiya Publishers, 2 Arindam Ghe Science, 200 Reference Books 1. X.P. Zhang, Verlag, Berli	DINATION OF FACTS CONTROLLERS Stions - SVC-SVC interaction - SVC-HVDC interaction - SVC -TCSC interaction - SVC-SVC interaction - SVC-HVDC interaction - SVC -TCSC interaction - Coordination of multiple controllers using linear control techniques - Nonerging FACTS Controllers: The STATCOM - The SSSC - The UPFC - rent FACTS controllers. Total (L+ss: Of this course, the students will be able to: Inber knowledge about reactive power flow control in power systems. It and various static series and shunt compensation techniques. In the structure and principle of operation of FACTS devices. In the FACTS devices at suitable location in power system networks. It and the co-ordination of FACTS controllers. In Systems In IEEE Press Book, Standard Publishers and Distributors, Delhi, 20 or, FACTS Controllers in Power Transmission and Distribution New Age 2007. Dosh, Gerard Ledwich, Power Quality Enhancement using Custom Power Dev 22. St. C. Rehtanz, B. Pal, Flexible AC Transmission Systems- Modelling and Controllers and Controllers and Controllers and Controllers and Controllers and Controllers and Controllers.	AC 01. Interiores	9 on - Tear of mpai	+ CS ontrativ	o GC-trolly we will be a second secon

PO CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Remember knowledge about reactive power flow control in power systems.	2	3	1	1	1	1	3	1	2	1	1
CO2	Understand various static series and shunt compensation techniques.	2	1	3	3	1	1	3	1	1	2	1
CO3	Analyze the structure and principle of operation of FACTS devices.	1	1	2	2	2	3	1	1	1	3	1
CO4	Apply the FACTS devices at suitable location in power system networks.	2	3	2	3	3	1	2	2	1	2	2
CO5	Understand the co- ordination of FACTS controllers.	2	1	3	2	1	1	2	3	1	2	1

18PEE54	HVDC TRANSMISSION SYSTEMS	L	Т	P	
	,	3	0	0	3
				•	•
Course Objective					
	and the concept, planning of DC power transmission and comparison w	ith A	3	po	٧e
transmission To analyze	1. HVDC converters.				
	out the HVDC system control.				
	armonics filters.				
	nowledge on simulation of HVDC systems.				
	,				
	OPMENT OF HVDC TECHNOLOGY	9		+	(
	mparison of AC and DC transmission - Applications of DC transmission			syst	en
	I components - Planning for HVDC transmission - Modern trends in DC trans		ion.		
WIDC systems: F	otential applications, Types - control and protection - study of MTDC System	n.			
Unit II ANALY	SIS OF HVDC CONVERTERS	9		+	(
	Choice of best topology for HVDC – Analysis of six pulse bridge converter				
	ess than 60° - Equivalent circuit model - Abnormal operation: Arcback, Con				
	e - Converter bridge characteristics - Multiple bridge converters.				
<u> </u>	<u> </u>				
	FROL OF HVDC SYSTEMS	9		+	(
Basic principles	of control - Desired features of control - Limitations of manual of	contro	ol -	Con	tro
•	nce - Higher level controllers -Fault development and protection-Functio	ns of	sm	nootr	
system performai reactors	nce - Higher level controllers -Fault development and protection-Functio	ns of	sm	nootr	in
reactors		ns of		nooth	
reactors Unit IV REAC	TIVE POWER CONTROL, HARMONICS AND FILTERS	9			in
Unit IV REAC		9		+	in
Unit IV REAC Reactive Power re Introduction - Ch	TIVE POWER CONTROL, HARMONICS AND FILTERS equirements in steady state - sources of reactive power - static VAR systems aracteristic harmonics - noncharacteristic harmonics - Troubles caused I we distortion or ripple - Means of reducing harmonics - Telephone interfere	9 s. by ha	rmc	+ onics	in (
Unit IV REAC Reactive Power re Introduction - Ch	TIVE POWER CONTROL, HARMONICS AND FILTERS equirements in steady state - sources of reactive power - static VAR systems aracteristic harmonics - noncharacteristic harmonics - Troubles caused I	9 s. by ha	rmc	+ onics	in (
Unit IV REAC Reactive Power reintroduction - Chapter of wave	TIVE POWER CONTROL, HARMONICS AND FILTERS equirements in steady state - sources of reactive power - static VAR systems aracteristic harmonics - noncharacteristic harmonics - Troubles caused I be distortion or ripple - Means of reducing harmonics - Telephone interfere and AC filters - DC side harmonics.	9s. by ha	rmc	+ onics	in
Unit IV REAC Reactive Power re Introduction - Ch Definitions of way minimum cost tun Unit V SIMULA	TIVE POWER CONTROL, HARMONICS AND FILTERS equirements in steady state - sources of reactive power - static VAR systems aracteristic harmonics - noncharacteristic harmonics - Troubles caused le re distortion or ripple - Means of reducing harmonics - Telephone interfere and AC filters - DC side harmonics. ATION OF HVDC SYSTEMS	9 s. by ha ence -	rmc - De	+ onics esign	- o
Unit IV REAC Reactive Power research controduction - Chamber C	TIVE POWER CONTROL, HARMONICS AND FILTERS equirements in steady state - sources of reactive power - static VAR systems aracteristic harmonics - noncharacteristic harmonics - Troubles caused level distortion or ripple - Means of reducing harmonics - Telephone interfered AC filters - DC side harmonics. ATION OF HVDC SYSTEMS DC systems, per unit system, Representation for power flow solution, re	9 s. by ha ence -	rmc - De	+ onics esign + otion	in - c
Unit IV REAC Reactive Power rentroduction - Characteristic Power rentroduction - Char	TIVE POWER CONTROL, HARMONICS AND FILTERS equirements in steady state - sources of reactive power - static VAR systems aracteristic harmonics - noncharacteristic harmonics - Troubles caused I be distortion or ripple - Means of reducing harmonics - Telephone interfere and AC filters - DC side harmonics. ATION OF HVDC SYSTEMS DC systems, per unit system, Representation for power flow solution, recystem simulation: Philosophy and tools - HVDC system simulation - Mo	9 s. by ha ence -	rmc - De	+ onics esign + otion	in - c
Unit IV REAC Reactive Power rentroduction - Characteristic Power rentroduction - Char	TIVE POWER CONTROL, HARMONICS AND FILTERS equirements in steady state - sources of reactive power - static VAR systems aracteristic harmonics - noncharacteristic harmonics - Troubles caused level distortion or ripple - Means of reducing harmonics - Telephone interfered AC filters - DC side harmonics. ATION OF HVDC SYSTEMS DC systems, per unit system, Representation for power flow solution, re	9 s. by ha ence -	rmc - De	+ onics esign + otion	in - c
Pactors Jnit IV REAC Reactive Power reserved Init V SIMULA Modelling of HVI Stability studies. Simulative Stability studies. Simulative Stability Stability Stability Stability Stability Stability Stability Stability Stability Stability Stability Stability Stability Stability Stability Stability Stability Stability Stability Stability Stability	TIVE POWER CONTROL, HARMONICS AND FILTERS equirements in steady state - sources of reactive power - static VAR systems aracteristic harmonics - noncharacteristic harmonics - Troubles caused I be distortion or ripple - Means of reducing harmonics - Telephone interfere and AC filters - DC side harmonics. ATION OF HVDC SYSTEMS DC systems, per unit system, Representation for power flow solution, recystem simulation: Philosophy and tools - HVDC system simulation - Mo	9 s. by ha ence -	rmo	+ onics esign + otion f HV	in - c
Unit IV REAC Reactive Power researched P	TIVE POWER CONTROL, HARMONICS AND FILTERS equirements in steady state - sources of reactive power - static VAR systems aracteristic harmonics - noncharacteristic harmonics - Troubles caused large distortion or ripple - Means of reducing harmonics - Telephone interfered AC filters - DC side harmonics. ATION OF HVDC SYSTEMS OC systems, per unit system, Representation for power flow solution, resystem simulation: Philosophy and tools - HVDC system simulation - Mod I dynamic simulation	9 s. by ha ence -	rmo	+ onics esign + otion f HV	in - c
Unit IV REAC Reactive Power research	TIVE POWER CONTROL, HARMONICS AND FILTERS equirements in steady state - sources of reactive power - static VAR systems aracteristic harmonics - noncharacteristic harmonics - Troubles caused large distortion or ripple - Means of reducing harmonics - Telephone interfered AC filters - DC side harmonics. ATION OF HVDC SYSTEMS OC systems, per unit system, Representation for power flow solution, resystem simulation: Philosophy and tools - HVDC system simulation - Mod I dynamic simulation	9 s. by ha ence -	rmo	+ onics esign + otion f HV	- o
Treactors Unit IV REAC Reactive Power reserved introduction - Characteristic Characteristic Reactive Power reserved introduction - Characteristic Reactive Power reserved introduction - Characteristic Reactive Power	TIVE POWER CONTROL, HARMONICS AND FILTERS equirements in steady state - sources of reactive power - static VAR systems aracteristic harmonics - noncharacteristic harmonics - Troubles caused It are distortion or ripple - Means of reducing harmonics - Telephone interfere and AC filters - DC side harmonics. ATION OF HVDC SYSTEMS OC systems, per unit system, Representation for power flow solution, resystem simulation: Philosophy and tools - HVDC system simulation - Modul dynamic simulation Total (Its.)	9 s. by ha ence -	rmo	+ onics esign + otion f HV	- o
Preactors Unit IV	TIVE POWER CONTROL, HARMONICS AND FILTERS equirements in steady state - sources of reactive power - static VAR systems aracteristic harmonics - noncharacteristic harmonics - Troubles caused level distortion or ripple - Means of reducing harmonics - Telephone interfered AC filters - DC side harmonics. ATION OF HVDC SYSTEMS OC systems, per unit system, Representation for power flow solution, resystem simulation: Philosophy and tools - HVDC system simulation - Mod dynamic simulation Total (is: of this course, the students will be able to: tand the concept of HVDC technology	9 s. by ha ence -	rmo	+ onics esign + otion f HV	- o
Unit IV REAC Reactive Power reserved introduction - Characteristic Power reserved introduction - Characteristic Power reserved in the Introduction - Characteristic Power reserved in the Introduction - Characteristic Power	TIVE POWER CONTROL, HARMONICS AND FILTERS equirements in steady state - sources of reactive power - static VAR systems aracteristic harmonics - noncharacteristic harmonics - Troubles caused larged distortion or ripple - Means of reducing harmonics - Telephone interfered AC filters - DC side harmonics. ATION OF HVDC SYSTEMS OC systems, per unit system, Representation for power flow solution, resystem simulation: Philosophy and tools - HVDC system simulation - Mod dynamic simulation Total (Institute of the students will be able to: Itand the concept of HVDC technology The basic concepts of HVDC and MTDC systems.	9 s. by ha ence -	rmo	+ onics esign + otion f HV	- o
Unit IV REAC Reactive Power re Introduction - Chance Course Outcome Upon completion of CO1 : Unders CO2 : Explain CO3 : Analyze	TIVE POWER CONTROL, HARMONICS AND FILTERS equirements in steady state - sources of reactive power - static VAR systems aracteristic harmonics - noncharacteristic harmonics - Troubles caused level distortion or ripple - Means of reducing harmonics - Telephone interfered AC filters - DC side harmonics. ATION OF HVDC SYSTEMS OC systems, per unit system, Representation for power flow solution, resystem simulation: Philosophy and tools - HVDC system simulation - Mod dynamic simulation Total (is: and the concept of HVDC technology the basic concepts of HVDC and MTDC systems. and control six-pulse and multiple-bridge converters	9 s. by ha ence -	rmo	+ onics esign + otion f HV	- o
Unit IV REAC Reactive Power re ntroduction - Chance Course Outcome Upon completion of CO1 : Unders CO2 : Explain CO3 : Analyze CO4 : Design	TIVE POWER CONTROL, HARMONICS AND FILTERS equirements in steady state - sources of reactive power - static VAR systems eracteristic harmonics - noncharacteristic harmonics - Troubles caused large distortion or ripple - Means of reducing harmonics - Telephone interfered AC filters - DC side harmonics. ATION OF HVDC SYSTEMS OC systems, per unit system, Representation for power flow solution, resystem simulation: Philosophy and tools - HVDC system simulation - Mod dynamic simulation Total (Institute of the students will be able to: tand the concept of HVDC technology the basic concepts of HVDC and MTDC systems. The stand control six-pulse and multiple-bridge converters of harmonics filters.	9 s. by ha ence -	rmo	+ onics esign + otion f HV	- o
Dnit IV REAC Reactive Power rentroduction - Charles Power Power rentroduction	TIVE POWER CONTROL, HARMONICS AND FILTERS equirements in steady state - sources of reactive power - static VAR systems aracteristic harmonics - noncharacteristic harmonics - Troubles caused level distortion or ripple - Means of reducing harmonics - Telephone interfered AC filters - DC side harmonics. ATION OF HVDC SYSTEMS OC systems, per unit system, Representation for power flow solution, resystem simulation: Philosophy and tools - HVDC system simulation - Mod dynamic simulation Total (is: and the concept of HVDC technology the basic concepts of HVDC and MTDC systems. and control six-pulse and multiple-bridge converters	9 s. by ha ence -	rmo	+ onics esign + otion f HV	- o
Preactors Unit IV	TIVE POWER CONTROL, HARMONICS AND FILTERS equirements in steady state - sources of reactive power - static VAR systems eracteristic harmonics - noncharacteristic harmonics - Troubles caused large distortion or ripple - Means of reducing harmonics - Telephone interferenced AC filters - DC side harmonics. ATION OF HVDC SYSTEMS OC systems, per unit system, Representation for power flow solution, resystem simulation: Philosophy and tools - HVDC system simulation - Mod dynamic simulation Total (Institute of the students will be able to: tand the concept of HVDC technology the basic concepts of HVDC and MTDC systems. The stand control six-pulse and multiple-bridge converters of harmonics filters. With the modelling of HVDC systems	9 s. by ha ence -	rmo	+ onics esign + otion f HV	in - c
Unit IV REAC Reactive Power resolution - Charles Power resolution - Charles Power resolutions of wax minimum cost tun Unit V SIMULA Modelling of HVE stability studies. Substantial studies. Substantial studies and substantial studies and substantial studies and substantial studies. Substantial studies and su	TIVE POWER CONTROL, HARMONICS AND FILTERS equirements in steady state - sources of reactive power - static VAR systems aracteristic harmonics - noncharacteristic harmonics - Troubles caused live distortion or ripple - Means of reducing harmonics - Telephone interfered AC filters - DC side harmonics. ATION OF HVDC SYSTEMS DC systems, per unit system, Representation for power flow solution, resystem simulation: Philosophy and tools - HVDC system simulation - Mould dynamic simulation Total (is: of this course, the students will be able to: tand the concept of HVDC technology the basic concepts of HVDC and MTDC systems. a and control six-pulse and multiple-bridge converters of harmonics filters. iith the modelling of HVDC systems imulation tools for HVDC systems	9 s. by had ence -	rmc - De	+ pnics esign + tion f HV	in Co
Unit IV REAC Reactive Power re Introduction - Charles Power Power re I	TIVE POWER CONTROL, HARMONICS AND FILTERS equirements in steady state - sources of reactive power - static VAR systems eracteristic harmonics - noncharacteristic harmonics - Troubles caused large distortion or ripple - Means of reducing harmonics - Telephone interferenced AC filters - DC side harmonics. ATION OF HVDC SYSTEMS OC systems, per unit system, Representation for power flow solution, resystem simulation: Philosophy and tools - HVDC system simulation - Mod dynamic simulation Total (Institute of the students will be able to: tand the concept of HVDC technology the basic concepts of HVDC and MTDC systems. The stand control six-pulse and multiple-bridge converters of harmonics filters. With the modelling of HVDC systems	9 s. by had ence -	rmc - De	+ pnics esign + tion f HV	in control of the con
Unit IV REAC Reactive Power re Introduction - Chance Power re	TIVE POWER CONTROL, HARMONICS AND FILTERS equirements in steady state - sources of reactive power - static VAR systems aracteristic harmonics - noncharacteristic harmonics - Troubles caused I be distortion or ripple - Means of reducing harmonics - Telephone interfere ed AC filters - DC side harmonics. ATION OF HVDC SYSTEMS DC systems, per unit system, Representation for power flow solution, re system simulation: Philosophy and tools - HVDC system simulation - Mo Il dynamic simulation Total (I s: of this course, the students will be able to: tand the concept of HVDC technology the basic concepts of HVDC and MTDC systems. a and control six-pulse and multiple-bridge converters of harmonics filters. ith the modelling of HVDC systems imulation tools for HVDC systems imulation tools for HVDC systems imulation tools for HVDC systems	9 s. by had ence -	rmc - De	+ pnics esign + tion f HV	in Co
Unit IV REAC Reactive Power re Introduction - Chance Power re	TIVE POWER CONTROL, HARMONICS AND FILTERS equirements in steady state - sources of reactive power - static VAR systems aracteristic harmonics - noncharacteristic harmonics - Troubles caused live distortion or ripple - Means of reducing harmonics - Telephone interfered AC filters - DC side harmonics. ATION OF HVDC SYSTEMS DC systems, per unit system, Representation for power flow solution, resystem simulation: Philosophy and tools - HVDC system simulation - Mould dynamic simulation Total (is: of this course, the students will be able to: tand the concept of HVDC technology the basic concepts of HVDC and MTDC systems. a and control six-pulse and multiple-bridge converters of harmonics filters. iith the modelling of HVDC systems imulation tools for HVDC systems	9 s. by had ence -	rmc - De	+ pnics esign + tion f HV	- cod

1.	Colin Adamson and N.G.Hingorani, High Voltage Direct current Power Transmission, Garraway
	Limited, London, First edition, 1960.
2.	Edward Wilson Kimbark, Direct Current Transmission, Vol.I, Wiley Interscience, New York, 1971.
3.	Erich Uhlmann, Power Transmission by Direct Current, B.S. Publications, 2004.
4.	Kamakshaiah, S. & Kamaraju, V, HVDC Transmission , 1st Edition, Tata McGraw Hill, 2011.

	CO Statement	PO1	РО	РО	PO4	РО	РО	РО	РО	РО	PO1	PO1
PO			2	3		5	6	7	8	9	0	1
co												
CO1	Understand the concept of HVDC technology	3	1	2	3	2	1				2	1
CO2	Explain the basic concepts of HVDC and MTDC systems.	3	2	3	3	1	1	1	1	1	2	1
CO3	Analyze and control six- pulse and multiple-bridge converters	3	2	3	1	1					1	
CO4	Design of harmonics filters	2	2	3	3	2	1	1	1	1	2	1
CO5	Work with the modelling of HVDC systems	2	3	2	2	1	1	2	1	1	1	1
CO6	Apply simulation tools for HVDC system	1	2	2	3	3	1	2	1	1	2	2

	18D	EE55	SCADA SYSTEMS AND APPLICATIONS		TIP	
	101	LLJJ	SCADA STOTEMO AND ALL EICATIONS	3	0 0	3
Cou	rse (Objectives:				
1.	To	understand	about the SCADA system components and SCADA communication proto	cols.		
2.	To	provide kn	owledge about SCADA applications in power system.			
Unit	1	INTRODUC	CTION TO SCADA		9 +	. 0
			A, SCADA definitions, SCADA Functional requirements and Compo	nents	-	
			, SCADA architecture, General features, SCADA Applications, Benefits.			
Unit	ıı .	SCADA S	YSTEM COMPONENTS		9 +	0
			Unit (RTU), Interface units, Human- Machine Interface Units (HI	ЛI), [-	55
Mon	itors	/Data Logge	er Systems, Intelligent Electronic Devices (IED), Communication Network			
SCA	DA (Control syst	ems and Control panels.			
Unit	III	SCADA	COMMUNICATION		9 +	0
			ation requirements, Communication protocols: Past, Present and Future			
			ations Protocol, Comparison of various communication protocols, IE			
			itecture, Communication media like Fiber optic, PLCC etc. Interface pnsions, synchronization with NCC, DCC.	rovisio	ons ar	na
00111		iodiion oxio	notione, synonicine and in war 1100, 500.			
Unit			RING AND CONTROL		9 +	0
			itoring the event and alarm system, trends and reports, Blocking list, Ever nction: Station control, bay control, breaker control and disconnector cont		ırbanc	е
			ng Systems (WAMS), Phasor Measurement Unit (PMU), A generic PM		he alc	bal
			Hierarchy for phasor measurement systems - Functional requirements, PI			
Unit	\ <u>'</u>	CCADA A	PPLICATIONS		9 +	
			neration, Transmission and Distribution sector, Substation SCADA sy		-	
			specification, System selection such as Substation configuration,			
			cubicle concepts, gateway interoperability list, signal naming concept. Sys	stem I	nstalla	tion,
		and Commis	ssioning. CADA Design for 66/11KV and 132/66/11KV or 132/66 KV any utility Sul	netatio	n and	IEC
			A Implementation issues in utility Substations.	JStatio	ii aiiu	ILC
			Tatal /I	· T\	4E Dan	ا مام
Cou	rse (Outcomes:	Total (L	+1)=4	to Per	ioas
			this course, the students will be able to:			
					• •	
CO1	:	Describe application	the basic tasks of Supervisory Control Systems (SCADA) as well as.	as the	əir typ	oicai
CO2	: :		nowledge about SCADA architecture, various advantages and disadva	ntage	s of e	ach
		system.				
CO3			e about single unified standard architecture IEC 61850. about SCADA system components: remote terminal units, PLCs, intel	ligant	oloctra	onic
004	` ·		about SCADA system components. Temote terminal units, FECs, intell HMI systems.	igeni	GIGGLI	JIIIC
CO5	5 :		d understand about SCADA applications in transmission and distribution	sector,	indust	ries
Refe	eren	ce Books:				
1.	SC	ADA-Super	visory Control and Data Acquisition, Stuart A. Boyer, Instrument Soc	iety o	f Ame	rica
		olications,US				
2.			ern SCADA Protocols: DNP3, 60870.5 and Related Systems, Gordo nes Publications, Oxford, UK.	n Cla	rke&D	eon
3.	Cyl	persecurity f	or SCADA Systems, William T. Shaw,PennWell Books.			
4.			DA for Industry, David Bailey&Edwin Wright, Newnes.			_
5.			Phasor Measurements and Their Applications, A.G. Phadke&J.S. Thorp, S			hoo!
6.	Wie	ebe,PennWe				
7.			Distributed Control Systems, Dieter K. Hammer, Lonnie R. Welch&Die	ter K.	Hamr	ner,
	1101	ra Science i	Publishers, USA.			

PO	CO Statement	PO1	PO 2	PO 3	PO4	PO 5	PO 6	PO 7	PO 8	PO 9	PO10	PO1 1
co												
CO1	Describe the basic tasks of Supervisory Control Systems (SCADA) as well as their typical applications.	1	1	1	1	1	1	3	1	1	1	1
CO2	Acquire knowledge about SCADA architecture, various advantages and disadvantages of each system.	1	1	3	3	1	1	3	1	1	2	1
CO3	Knowledge about single unified standard architecture IEC 61850.	1	1	2	2	2	1	1	1	1	3	1
CO4	To learn about SCADA system components: remote terminal units, PLCs, intelligent electronic devices, HMI systems.	2	3	2	3	3	1	2	2	1	2	2
CO5	Learn and understand about SCADA applications in transmission and distribution sector, industries etc.	2	2	3	3	3	1	2	3	1	2	2

18PEE61	ELECTRICAL VEHICLES	L	Т	Р	С
		3	0	0	3
		·			
Course Objectives:					
	the concept of electrical vehicles and its operations				
	the need for energy storage in hybrid vehicles				
	wledge about various possible energy storage technologies that can be				
Used in electric	c vehicles				
			_		_
Unit I INTRODU	 		9	+	. 0
•	V), Hybrid Electric Vehicles (HEV), Engine ratings, Comparisons of EV	with	ini	erna	al
combustion Engine v	ehicles, Fundamentals of vehicle mechanics.				
Unit II ARCHITE	THE		9	_	0
	and HEV's – Plug-n Hybrid Electric Vehicles (PHEV) - Power train co	mno	•	+	_
	· · · · · · · · · · · · · · · · · · ·	про	пеп	is a	nu
sizing, Gears, Clutcr	nes, Transmission and Brakes.				
Unit III DRIVES			9	_	0
= -	ed four quadrant operations of DC drives – Inverter based V/f Operation	· /m		na c	_
	n motor drive system - Induction motor and permanent motor based	vec	tor	con	troi
operation – Switched	d reluctance motor (SRM) drives.				
Unit IV BATTERIE			0		^
			9	+	0
Battery Basics, Differ	ent types, Battery Parameters, Battery modeling, Traction Batteries				
Unit V FUEL CEL	<u> </u>		9	+	0
	stics- Types - hydrogen Storage Systems and Fuel cell EV - Ultra capacito	ors			
r der den Gridiaeteri	one Types Tryanogen eterage cycleme and the context of the capacit	010			
	Total (L+	·T)= 4	45 F	eric	ods
Course Outcomes:	·	·T)= 4	45 F	eric	ods
Upon completion of the	his course, the students will be able to:	·T)= 4	45 F	Perio	ods
Upon completion of the CO1 : Remember	his course, the students will be able to: ber the fundamentals of electric vehicle and its mechanics	·T)= 4	45 F	Perio	ods
Upon completion of tl CO1 : Rememble CO2 : Understa	his course, the students will be able to: ber the fundamentals of electric vehicle and its mechanics and the architecture of electric and hybrid electric vehicle.		45 F	Perio	ods
Upon completion of the CO1 : Remember CO2 : Understate CO3 : Analyse	his course, the students will be able to: ber the fundamentals of electric vehicle and its mechanics and the architecture of electric and hybrid electric vehicle. the four quandrant operation of DC drive, induction motor drive and SRM o		45 F	Perio	ods
Upon completion of the CO1 : Remember CO2 : Understate CO3 : Analyse CO4 : Apply an	his course, the students will be able to: ber the fundamentals of electric vehicle and its mechanics and the architecture of electric and hybrid electric vehicle. the four quandrant operation of DC drive, induction motor drive and SRM of analyse the basic battery concepts and modeling.		45 F	Perio	ods
Upon completion of the CO1 : Remember CO2 : Understate CO3 : Analyse CO4 : Apply and CO5 : Understate CO5 :	his course, the students will be able to: ber the fundamentals of electric vehicle and its mechanics and the architecture of electric and hybrid electric vehicle. the four quandrant operation of DC drive, induction motor drive and SRM o		45 F	Perio	ods
Upon completion of the CO1 : Remember CO2 : Understate CO3 : Analyse CO4 : Apply are CO5 : Understate Reference Books:	his course, the students will be able to: ber the fundamentals of electric vehicle and its mechanics and the architecture of electric and hybrid electric vehicle. the four quandrant operation of DC drive, induction motor drive and SRM of analyse the basic battery concepts and modeling. and the concepts of fuel cell	drive.		Perio	ods
Upon completion of the CO1 : Remember CO2 : Understate CO3 : Analyse CO4 : Apply are CO5 : Understate CO5 : Understate CO5 : Understate CO5 : Understate CO5 : Electric and Hyman CO5 : Electric and Hyman CO5 : Understate CO5 : Electric and Hyman CO5 : Understate	his course, the students will be able to: ber the fundamentals of electric vehicle and its mechanics and the architecture of electric and hybrid electric vehicle. the four quandrant operation of DC drive, induction motor drive and SRM of analyse the basic battery concepts and modeling. and the concepts of fuel cell ybrid Vehicles: Design Fundamentals , qbal Hussain, CRC Press, Taylor &	drive.		Perio	ods
Upon completion of the CO1 : Remember CO2 : Understate CO3 : Analyse CO4 : Apply and CO5 : Understate CO5 :	his course, the students will be able to: ber the fundamentals of electric vehicle and its mechanics and the architecture of electric and hybrid electric vehicle. the four quandrant operation of DC drive, induction motor drive and SRM of analyse the basic battery concepts and modeling. and the concepts of fuel cell ybrid Vehicles: Design Fundamentals , qbal Hussain, CRC Press, Taylor & Edition (2011).	drive.	cis		
Upon completion of the CO1 : Remember CO2 : Understate CO3 : Analyse CO4 : Apply and CO5 : Understate CO5 :	his course, the students will be able to: ber the fundamentals of electric vehicle and its mechanics and the architecture of electric and hybrid electric vehicle. the four quandrant operation of DC drive, induction motor drive and SRM of analyse the basic battery concepts and modeling. and the concepts of fuel cell ybrid Vehicles: Design Fundamentals , Iqbal Hussain, CRC Press, Taylor & Edition (2011). tric Power Systems , Ali Emadi, Mehrdad Ehsani, John M.Miller, Special In	drive.	cis		

PO	CO Statement	PO1	PO 2	PO 3	PO4	PO 5	PO 6	PO 7	PO 8	PO 9	PO10	PO1 1
CO1	Remember the fundamentals of electric vehicle and its mechanics	3	1	2	1	1		1	1		1	1
CO2	Understand the architecture of electric and hybrid electric vehicle.	1	1	3	2	2		2			2	
CO3	Analyse the four quandrant operation of DC drive, induction motor drive and SRM drive.	1	1	2	3	2		1	1	1	3	
CO4	Apply and analyse the basic battery concepts and modeling.	2	3	3	1	1		1	2		1	2
CO5	Understand the concepts of fuel cell	2	1	1	1	2		1	3		1	1

18PEE62	THEORY AND DESIGN OF SMPS	L	Т	Р	С
		3	0	0	3
Course Objectives					
Course Objectives: 1. To know operation	on and design procedure.				
	lesign control techniques				
,	ed magnetics for converters				
9 1	components and scheme protection circuits				
	· '				
Unit I DESIGN OF N	ION-ISOLATED DC-DC CONVERTERS		9	+	0
Topologies, General De Charge Pumps	esign Method, Design of Buck Converter, Boost Conve	rter, Buck	/Boos	t Cor	nverter,
	ISOLATED DC-DC CONVERTERS		9	+	0
· ·	onverter, Forward Converter, Push-Pull Converter, H	alf Bridge	and	Full	Bridge
Converters					
Unit III CONTROL	CIRCUITS		9	+	0
	, Error Amplifier and its compensation, Voltage mo	nde Contr			_
	Mode Control, Voltage feed-back circuit, IC Control M				
Module, TL494, SG152		oddio, Ty	Jioai i	* *	Control
,					
Unit IV DESIGN OF	MAGNETIC ELEMENTS		9	+	0
Magnetic Concepts, I	nductor design, Transformer Design for Fly-back,	Forward	and	Pus	h-Pull
converters					
Unit V SELECTION	OF PERIPHERAL COMPONENTS		9	+	0
	itors, EMI Filter, Input and Output rectifier, Voltage	cupproced	_		•
Power Switches, Prote		suppresso	JIS, C	/ριο-α	oupiei,
		Total ((L+T):	= 45	Periods
Course Outcomes:					
Upon completion of this	s course, the students will be able to:				
CO1 : Implement d	esign concepts and analyze the converters				
	propriate control strategy and implement				
	propriate power devices				
	nagnetic components based on requirements				
	emponents to meet the complete realization of converte	er and Cho	ose t	he co	rrect
	nd filter elements				
Reference Books:					
	- Power Sources and Supplies World Class Designs, I	Newnes 2	007		
	wer Supply Cook Book 2 nd , Newnes 2001				
	Electronics Essentilas and Applications - Wiley 2009	_			
	optimal Design of Switching Power Supply - Wiley 2015				
	wer Electronics Converters and Regulators, 3 rd Edition	n - Spring	er		
Online Resources	D				NIDTE:
1. Umanand and	Ramanarayanan - Switched Mode Powe	er Con	ersio/	n,	NPTEL
nttps://nptei.ac.in/s	syllabus/108108036/				

PQ CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Implement design concepts and analyze the converters	1	1	1	1	1						1
CO2	Select the appropriate control strategy and implement	1	1	2	2	1			1			1
CO3	Select the appropriate power devices	1	2	1	1	1			1			1
CO4	Design the magnetic components based on requirements	1	2	2	2	1			2			1
CO5	Select the components to meet the complete realization of converter and Choose the correct protection and filter elements	1	2	2	1	1			1		2	1

19	8PEE63	ENERGY STORAGE TECHNOLOGY	1	Т	Р	С
	OI LLOS	ENERGY GTORAGE TEGINGEGGT	3	0	0	3
	Objectives:					
l o explo	ore the fundame	ntals, technologies and applications of energy storage				
Unit I		9	+	0		
		ons in Energy Demand- Variations in Energy Supply- Ir				
		Congestion - Demand for Portable Energy-Demand and	scal	e rec	luirer	nents
nvironi	mental and sust	ainability issues.				
Jnit II	TECHNICAL	METHODS OF STORAGE		9	+	0
ntroduc		nd Energy Transformations, Potential energy (pumped h	ydro,	com	press	ed air
		(mechanical flywheels)- Thermal energy without phase ch				
		rmal energy with phase change (ice, molten salts, stea				
		asoline, coal, oil)- Electrochemical energy (batteries, fu				
	(capacitors), Ele Systems.	ectromagnetic energy (superconducting magnets)- Different	ent I	ypes	of E	nergy
Siorage	Systems.					
Unit III	PERFORMA	NCE FACTORS OF ENERGY STORAGE SYSTEMS		9	+	0
		nd efficiency- Discharge rate and efficiency- Dispatch al				
		exibility, durability - Cycle lifetime, mass and safety - Ri				
		als, recycling and recovery- Environmental consideration	and	recyc	ling	Merit
and den	nerits of differei	nt types of Storage.				
Jnit IV	APPI ICATIO	ON CONSIDERATION		9	+	0
		chnologies- Technology options- Performance factors and	l met	_		_
		gy Recovery - Battery Storage System: Introduction with				
		of Battery Operation, Power storage calculations, Reversit				
		gement systems, System Performance, Areas of Application				
		olar energy storage, Green house heating, Power plant app				
heating '	for process indu	stries, energy storage in automotive applications in hybrid a	and e	lectric	veh	icles.
Unit V	HYDROGEN	FUEL CELLS AND FLOW BATTERIES		9	+	0
		d Generation Techniques, Storage of Hydrogen, Energ	ıv de			-
		power calculations – Operation and Design methods - H				
		ontinuous power needs, options - Level 1: (Hybrid Powe				
		Combinations: need, operation and Merits; Level 2: (Hybr				
Bacitor	+ Fuel Cel	I or Flow Battery operation-Applications: Storage	for	Hyb	rid	Electri
Vehicles	s,Regenerative I	Power, capturing methods.				
		To	otal (l	_+T)=	45 F	Period
Course	Outcomes:					
	amplation of this					
Upon co	impletion of this	course, the students will be able to:				
•	<u>'</u>	course, the students will be able to:	age.			
Upon cc CO1 : CO2 :	Recollect the		rage.			
CO1 :	Recollect the Learn the bas	course, the students will be able to: historical perspective and technical methods of energy stor	rage.			
CO1 :: CO2 :: CO3 :: CO4 ::	Recollect the Learn the bas Understand the	course, the students will be able to: historical perspective and technical methods of energy storaics of different storage methods. he concepts of energy conversion technology e performance factors of energy storage systems	rage.			
CO1 : CO2 : CO3 : CO4 : CO5 :	Recollect the Learn the bas Understand the Determine the	course, the students will be able to: historical perspective and technical methods of energy storsics of different storage methods. he concepts of energy conversion technology	rage.			
CO1 : CO2 : CO3 : CO4 : CO5 : Referen	Recollect the Learn the bas Understand the Determine the Identify the ap	course, the students will be able to: historical perspective and technical methods of energy storsics of different storage methods. he concepts of energy conversion technology e performance factors of energy storage systems oplications of various energy storage systems				
CO1 :: CO2 :: CO3 :: CO4 :: CO5 :: Referen	Recollect the Learn the bas Understand the Determine the Identify the apace Books:	course, the students will be able to: historical perspective and technical methods of energy storaics of different storage methods. he concepts of energy conversion technology e performance factors of energy storage systems		catior	os",	Wiley,
CO1 : CO2 : CO3 : CO4 : CO5 : Referen 1. De 20	Recollect the Learn the bas Understand the Determine the Identify the ap Idea Books: ItlefStolten, "Hyding."	course, the students will be able to: historical perspective and technical methods of energy storsics of different storage methods. he concepts of energy conversion technology e performance factors of energy storage systems oplications of various energy storage systems	Applio			
CO1 : CO2 : CO3 : CO4 : CO5 : Referen 1.	Recollect the Learn the base Understand the Determine the Identify the approximate Books: stlefStolten, "Hydinology Zhang, Lei ergy Storage and	course, the students will be able to: historical perspective and technical methods of energy storages of different storage methods. he concepts of energy conversion technology experiormance factors of energy storage systems oplications of various energy storage systems rogen and Fuel Cells: Fundamentals, Technologies and Allahang, Hansan Liu, Andy Sun, Ru-Shi Liu, "Electrochemed Conversion", John Wiley and Sons, 2012.	Applio			
CO1 : CO2 : CO3 : CO4 : CO5 : Referen 1. De 20 2. Jiu En 3. Fra	Recollect the Learn the base Understand the Determine the Identify the approach of the state of	course, the students will be able to: historical perspective and technical methods of energy storages of different storage methods. he concepts of energy conversion technology experiormance factors of energy storage systems oplications of various energy storage systems rogen and Fuel Cells: Fundamentals, Technologies and All Zhang, Hansan Liu, Andy Sun, Ru-Shi Liu, "Electrochem and Conversion", John Wiley and Sons, 2012. had ElzbietaFrackowiak, "Super capacitors", Wiley, 2013.	Applio	Techi		
CO1 : CO2 : CO3 : CO4 : CO5 : Referen 1.	Recollect the Learn the bas Understand the Determine the Identify the ap Ident	course, the students will be able to: historical perspective and technical methods of energy storages of different storage methods. he concepts of energy conversion technology experiormance factors of energy storage systems oplications of various energy storage systems rogen and Fuel Cells: Fundamentals, Technologies and Allahang, Hansan Liu, Andy Sun, Ru-Shi Liu, "Electrochemed Conversion", John Wiley and Sons, 2012.	Applio	Techi		

PQ CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	PO11
CO1	Recollect the historical perspective and technical methods of energy storage.	3	2	2	2	2	2	1	2	1	3	2
CO2	Learn the basics of different storage methods.	3	2	2	2	2	2	1	2	1	2	1
CO3	Understand the concepts of energy conversion technology	3	3	3	3	2	2	1	2	1	2	1
CO4	Determine the performance factors of energy storage systems	3	3	3	3	2	2	1	2	1	2	1
CO5	Identify the applications of various energy storage systems	3	3	3	3	2	2	1	2	1	2	1

18PEE64 INTERNET OF THINGS FOR ELECTRICAL ENGINEERS L T P C
Course Objectives:
To illustrate the concept of Internet of Things (IoT).
 To findstrate the concept of internet of Things (101). To familiarize with implementations of IoT for electrical engineering applications.
2. To familiarize with implementations of for for electrical engineering applications.
Unit I INTRODUCTION 9 + 0
Internet of Things - Physical Design- Logical Design- IoT Enabling Technologies - IoT Levels & Deploymen Templates - Domain Specific IoTs - IoT and M2M - IoT System Management with NETCONF-YANG- IoT Platforms Design Methodology.
Unit II ARCHITECTURE 9 + 0
M2M high-level ETSI architecture - IETF architecture for IoT - OGC architecture - IoT referencemodel - Domain model - information model - functional model - communication model - IoT reference architecture
Unit III IOT PROTOCOLS 9 + 0
Protocol Standardization for IoT - Efforts - M2M and WSN Protocols - SCADA and RFIDProtocols - Unified Data Standards - Protocols - IEEE 802.15.4 - BACNet Protocol - Modbus-Zigbee Architecture - Network layer - 6LowPAN - CoAP - Security
Unit IV BUILDING IOT 9 + 0
Building IOT with RASPERRY PI- IoT Systems - Logical Design using Python - IoT Physical Devices & Endpoints - IoT Device -Building blocks -Raspberry Pi -Board - Linux on Raspberry Pi - Raspberry Pi Interfaces -Programming Raspberry Pi with Python - Other IoT Platforms - Arduino.
Unit V APPLICATIONS 9 + 0
Real world design constraints - Applications - Asset management, Industrial automation, smartgrid Commercial building automation, Smart cities - participatory sensing - Data Analytics for IoT- Software & Management Tools for IoT Cloud Storage Models & Communication APIs - Cloud for IoT - Amazon Web Services for IoT.
Total (L+T)= 45 Periods
Course Outcomes:
Upon completion of this course, the students will be able to:
CO1 : Analyze various protocols for IoT.
CO2 : Develop web services to access/control IoT devices.
CO3 : Design a portable IoT using Rasperry Pi.
CO4 : Deploy an IoT application and connect to the cloud.
CO5 : Analyze applications of IoT in real time scenario.
References:
1. The Internet of Things – Enabling Technologies, Platforms, and Use Cases, Pethuru Raj & Anupama C. Raman, CRCPress.
2. Internet of Things – A hands-on approach, ArshdeepBahga&Vijay Madisetti, Universities Press.
3. From Machine-to-Machine to the Internet of Things - Introduction to a New Age of Intelligence, Jan Holler, VlasiosTsiatsis, Catherine Mulligan, Stamatis, Karnouskos, Stefan Aves & David Boyle, Elsevier.
4. The Internet of Things – Key applications and Protocols, Olivier Hersent, David Boswarthick& Omar Elloumi, Wiley.
5. The Internet of Things in the Cloud: A Middleware Perspective, Honbo Zhou, CRC Press.
6. Integration of Distributed Generation in the Volt/VAR Management System for Active Distribution Networks, Barr, Johanna &RitwikMajumder, IEEE Transactions on Smart Grid, Vol. 6, No. 2, pp. 576-586, 2015.
7. Review of Internet of Things (IoT) in Electric Power and Energy Systems, GuneetBedi, Ganesh Kumar Venayagamoorthy, Rajendra Singh, Richard Brooks &Kuang-Ching Wang, IEEE Internet of Things Journal, DOI 10.1109/JIOT.2018.2802704.

PO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO1 0	PO1 1
CO1	Analyze various protocols for IoT	1	1	1	1	1	1	3	1	1	1	1
CO2	Develop web services to access/control loT devices.	1	1	3	3	1	1	3	1	1	2	1
CO3	Design a portable IoT using Rasperry Pi.	1	1	2	2	2	1	1	1	1	3	1
CO4	Deploy an IoT application and connect to the cloud.	2	3	2	3	3	1	2	2	1	2	2
CO5	Analyze applications of IoT in real time scenario.	2	2	3	3	3	1	2	3	1	2	2

1	8PE	E65 DIGITAL SIGNAL PROCESSORS FOR POWER CONVERTERS	L	Т	Р	С
		·	3	0	0	3
Cou	rse	Objectives:				
1.		o understand the basic concepts of discrete time signals, digital signal processors, proceplications.	ırar	nmin	g an	d
Unit	ı	INTRODUCTION to TMS 320C54X PROCESSOR	1	9	+	0
		r digital signal processor - Basic architecture of DSP's - Architecture of TMS 320C5		_	cesso	
		ing modes- Assembly instructions- Pipelining- Interrupts- Clock generator- Timer ports- Host-port interface (HPI)	- ;	Seria	l po	rts-
Unit	II	TMS 320C67X PROCESSOR		9	+	0
		ture of TMS 320C67X processor- CPU data paths and control. Addressing modes. operation.	Ins	truct	ion s	et.
Unit	Ш	PERIPHERALS AND INTERFACE		9	+	0
		ng with serial I/O- A/D, D/A converters- Parallel interfacing- Interfacing with RAM- EEP		-		_
		nerationDSP tools: Assembler- Debugger- C compiler- Linker -loader.				
Unit	IV	ADVANCES IN DSP PROCESSORS		9		0
		chitecture - Multiprocessor DSPs, SHARC, SIMB, MIMD Architectures and Analog Dev			Ps -	
		tion to FPGA - FPGA based DSP system - Architecture of TMS 320F28335				
Unit	V	MOTOR CONTROL APPLICATION	1	9	+	0
		sed Implementation of DC-DC Buck-Boost Converters - DSP-Based Control of Mat		-	erte	_
		sed Switched reluctance motor control- DSP based brushless DC motor control, DSP	bas	ed c	ontro	l of
Pern	nan	ent Magnet Synchronous Motor Total (45	+0)	= 45	Perio	ods
Cou	rse	Outcomes:				
Upo	n cc	mpletion of this course, the students will be able to:				
CO1	:	Understand the basic concepts of digital signal processor.				
CO2	:	Program the digital signal processor.				
CO3	;	Analyze interfacing of peripherals with DSP.				
CO4	! :	Understand the advancements in DSP processors				
CO5	; ;	Programming of DSP for motor control.				
T						
Text		oks: /enkataramani et al. Digital Signal processor -Architecture, Programming and Appl	ica	tions	I TM	1H
1.	Ne	w Delhi 2010, second edition.				
2.		Srinivasan & Avtar Singh, "Digital Signal Processing, Implementations croprocessors with Examples from TMS320C54X", Brooks/Cole, 2004.		using	g E	SP
3.	Ha 200	mid A Joliyet and Steven G Campell, ${}^-$ DSP Based Electromechanical Motion Conti 03.	ol	CRC	Pres	SS
4.	Us	er guides Texas Instrumentation, Analog Devices, Motorola.				
5.		n M.Kuo & Woon-Seng S.Gan, Digital Signal Processors: Architectures, Im _i d Applications, Printice Hall, 2004	olei	nent	ation	S,

PO CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Understand the basic concepts of digital signal processor.	1	1	1	1	1	1	1	1	1	2	1
CO2	Program the digital signal processor.	1	1	1	1	1	1	3	3	1	2	1
CO3	Analyze interfacing of peripherals with DSP.	1	1	2	2	2	1	2	1	1	2	1
CO4	Understand the advancements in DSP processors	1	1	2	2	3	1	2	3	1	2	1
CO5	Programming of DSP for motor control.	2	3	3	3	3	1	3	3	1	2	1

Course Objectives: To understand the importance of writing skills in a Research paper. To Learn how to write different sections in a research paper and skills of writing a good research paper Unit I		18AC01	ENGLISH FOR RESEARCH PAPER WRITING	L	T	Р	С
To understand the importance of writing skills in a Research paper. To Learn how to write different sections in a research paper and skills of writing a good research paper Unit I				2	0	0	0
Unit I 4	Cou	rse Objectiv	es:				
Unit II	To u	inderstand th	ne importance of writing skills in a Research paper. To Learn how to write diffe	erent	t sec	ction	ıs
Unit II	in a	research pap	per and skills of writing a good research paper				
Unit II	Unit	:1		4		+	0
English in research papers – Basic word order – Collocation – Concord – Breaking up of long sentences – Ambiguity and Redundancy Unit III	Rese	earch paper a	and its importance – Structure of a research paper – Planning and Preparation				
Unit III	Unit	: II		4		+	0
Key factors that determine the style of a paper – Journal's background – Passive form – Right tense – Cohesion and Coherence. Unit IV	_	•	· · ·	ente	nce	s –	
Unit IV	Unit	: III		4		+	0
Unit IV	Key	factors that o	determine the style of a paper – Journal's background – Passive form – Right t	ense	<u> </u>		
Highlighting you findings – Hedging and Criticizing – Paraphrasing and Plagiarism. Unit V	Coh	esion and Co	herence.				
Highlighting you findings – Hedging and Criticizing – Paraphrasing and Plagiarism. Unit V	Unit	· IV		4		+	0
Unit V			findings — Hedging and Criticizing — Paranhrasing and Plagiarism			•	
Key skills in writing Title – Abstract – Introduction – Review of Literature – Methods – Discussion and Conclusion – useful phrases – Ensuring quality of the paper. Total (L+T) = 20 periods Course Outcomes: 1. Upon completion of the course, the students will be able to: 1. Understand and appreciate the process of writing a good research paper 2. Apply their gained knowledge in writing a research paper 3. Analyse and assess the quality of their research paper Suggested reading 1 Goldbort R (2006) "Writing for Science," Yale University press 2 Day R (2006) "How to Write and Publish a Scientific Paper," Cambridge University Press 3 Highman N (1998), "Handbook of Writing for the Mathematical Sciences," SIAM. Highman's book. Adrian Wallwork, "English for Writing Research Papers," Springer New York Dorecht Heidelberg	6		Through the criticizing in a phrobing and magnificant.				
Conclusion – useful phrases – Ensuring quality of the paper. Total (L+T) = 20 periods Course Outcomes: 1. Upon completion of the course, the students will be able to: Understand and appreciate the process of writing a good research paper 2. Apply their gained knowledge in writing a research paper 3. Analyse and assess the quality of their research paper Suggested reading 1 Goldbort R (2006) "Writing for Science," Yale University press 2 Day R (2006) "How to Write and Publish a Scientific Paper," Cambridge University Press 3 Highman N (1998), "Handbook of Writing for the Mathematical Sciences," SIAM. Highman's book. Adrian Wallwork, "English for Writing Research Papers," Springer New York Dorecht Heidelberg	Unit	: V		4		+	0
Total (L+T) = 20 periods Course Outcomes: Upon completion of the course, the students will be able to: Understand and appreciate the process of writing a good research paper Apply their gained knowledge in writing a research paper Analyse and assess the quality of their research paper Suggested reading Goldbort R (2006) "Writing for Science," Yale University press Day R (2006) "How to Write and Publish a Scientific Paper," Cambridge University Press Highman N (1998), "Handbook of Writing for the Mathematical Sciences," SIAM. Highman's book. Adrian Wallwork, "English for Writing Research Papers," Springer New York Dorecht Heidelberg	Key	skills in writir	ng Title – Abstract – Introduction – Review of Literature – Methods – Discussio	n ar	nd		ı
Course Outcomes: Upon completion of the course, the students will be able to: Understand and appreciate the process of writing a good research paper Apply their gained knowledge in writing a research paper Analyse and assess the quality of their research paper Suggested reading Goldbort R (2006) "Writing for Science," Yale University press Day R (2006) "How to Write and Publish a Scientific Paper," Cambridge University Press Highman N (1998), "Handbook of Writing for the Mathematical Sciences," SIAM. Highman's book. Adrian Wallwork, "English for Writing Research Papers," Springer New York Dorecht Heidelberg	Con	clusion – use	ful phrases – Ensuring quality of the paper.				
 Upon completion of the course, the students will be able to: Understand and appreciate the process of writing a good research paper Apply their gained knowledge in writing a research paper Analyse and assess the quality of their research paper Goldbort R (2006) "Writing for Science," Yale University press Day R (2006) "How to Write and Publish a Scientific Paper," Cambridge University Press Highman N (1998), "Handbook of Writing for the Mathematical Sciences," SIAM. Highman's book. Adrian Wallwork, "English for Writing Research Papers," Springer New York Dorecht Heidelberg 			Total (L+	T) =	20	perio	ods
 Understand and appreciate the process of writing a good research paper Apply their gained knowledge in writing a research paper Analyse and assess the quality of their research paper Suggested reading Goldbort R (2006) "Writing for Science," Yale University press Day R (2006) "How to Write and Publish a Scientific Paper," Cambridge University Press Highman N (1998), "Handbook of Writing for the Mathematical Sciences," SIAM. Highman's book. Adrian Wallwork, "English for Writing Research Papers," Springer New York Dorecht Heidelberg 	Cou						
3. Analyse and assess the quality of their research paper Suggested reading 1 Goldbort R (2006) "Writing for Science," Yale University press 2 Day R (2006) "How to Write and Publish a Scientific Paper," Cambridge University Press 3 Highman N (1998), "Handbook of Writing for the Mathematical Sciences," SIAM. Highman's book. Adrian Wallwork, "English for Writing Research Papers," Springer New York Dorecht Heidelberg	1.						
Suggested reading 1 Goldbort R (2006) "Writing for Science," Yale University press 2 Day R (2006) "How to Write and Publish a Scientific Paper," Cambridge University Press 3 Highman N (1998), "Handbook of Writing for the Mathematical Sciences," SIAM. Highman's book. Adrian Wallwork, "English for Writing Research Papers," Springer New York Dorecht Heidelberg	2.	Apply their (gained knowledge in writing a research paper				
Goldbort R (2006) "Writing for Science," Yale University press Day R (2006) "How to Write and Publish a Scientific Paper," Cambridge University Press Highman N (1998), "Handbook of Writing for the Mathematical Sciences," SIAM. Highman's book. Adrian Wallwork, "English for Writing Research Papers," Springer New York Dorecht Heidelberg	3.	Analyse and	d assess the quality of their research paper				
Day R (2006) "How to Write and Publish a Scientific Paper," Cambridge University Press Highman N (1998), "Handbook of Writing for the Mathematical Sciences," SIAM. Highman's book. Adrian Wallwork, "English for Writing Research Papers," Springer New York Dorecht Heidelberg	Sug	gested read	ing				
Highman N (1998), "Handbook of Writing for the Mathematical Sciences," SIAM. Highman's book. Adrian Wallwork, "English for Writing Research Papers," Springer New York Dorecht Heidelberg	1	Goldbort R	(2006) "Writing for Science," Yale University press				
Adrian Wallwork, "English for Writing Research Papers," Springer New York Dorecht Heidelberg	2						
	3						
	4			eide	lber	g	

PO CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Understand and appreciate the process of					1	1	1	1	1	1	1

	writing a good research paper									
CO2	Apply their gained knowledge in writing a research paper			1	1	1	1	1	1	1
CO3	Analyse and assess the quality of their research paper			1	1	1	1	1	1	1

18	BAC0	DISASTER MANAGEMENT	L 1	ΓР	С
Course	Ob	la attiva a .	2 (0 0	0
		jectives:			
		critical understanding of key concepts in disaster risk reduction and humanitarian i		-	-
		e from multiple perspectives. Develop an understanding of standards of humanit			
-		al relevance in specific types of disasters and conflict situations and evaluate the		_	
		s of disaster management approaches. Planning and programming in different	ent c	ountr	ies,
-		their home country or the countries they work in. NTRODUCTION - Disaster Prone Areas In India	1		
Unit I			4	+	0
		CTION			
		Definition, Factors And Significance; Difference Between Hazard And Disaster;			
		Disasters: Difference, Nature, Types And Magnitude. Disaster Prone Areas In Inc		-	
		ones; Areas Prone To Floods And Droughts, Landslides And Avalanches; Areas Prone		ycloni	С
And	Coast	al Hazards With Special Reference To Tsunami; Post Disaster Diseases And Epidemic	S		
Unit I	I F	REPERCUSSIONS OF DISASTERS AND HAZARDS	4	+	0
Econ	omic	Damage, Loss Of Human And Animal Life, Destruction Of Ecosystem. Natur	al Di	sastei	rs:
		es, Volcanisms, Cyclones, Tsunamis, Floods, Droughts And Famines, Landslides And			
	•	e disaster: Nuclear Reactor Meltdown, Industrial Accidents, Oil Slicks And Spills, C			
		nd Epidemics, War And Conflicts.			
Unit I	II	DISASTER PREPAREDNESS AND MANAGEMENT	4	+	0
-		ess: Monitoring Of Phenomena Triggering A Disaster Or Hazard; Evaluation Of Risk:			
		e Sensing, Data From Meteorological And Other Agencies, Media Reports: Govern	ment	al An	d
Com	munit	y Preparedness.			
Unit I	V	RISK ASSESSMENT	4	+	0
Disas	ster R	sk: Concept And Elements, Disaster Risk Reduction, Global And National Disaster R	sk Sit	uatior	า.
		s Of Risk Assessment, Global Co-Operation In Risk Assessment And Warnii			
		on In Risk Assessment. Strategies for Survival.	•	·	
Unit \		DISASTER MITIGATION	4	+	0
	•	Concept And Strategies Of Disaster Mitigation, Emerging Trends In Mitigation. Structural Mitigation, Programs Of Disaster Mitigation In India.	tural		
	,	Total (L+	T)= 20) Peri	ods
		tcomes			
	mple	tion of the course, the students will be able to			
CO1	:	Learn to demonstrate a critical understanding of key concepts in disaster risk reduction humanitarian response.	tion a	nd	
CO2	:	Critically evaluate disaster risk reduction and humanitarian response policy and promultiple perspectives	ictice .	from	
CO3	.	multiple perspectives	.11		
003	:	Develop an understanding of standards of humanitarian response and practice specific types of disasters and conflict situations	ii reie	vance	? IN
CO4	:	Critically understand the strengths and weaknesses of disaster management appro	aches		
			· <u> </u>	_	
Refer			-(N.I	D	
'-	book (hith, Singh AK, Disaster Management in India: Perspectives, issues and strategies Company.		•	
	Sahni New [, PardeepEt.Al. (Eds.),∥ Disaster Mitigation Experiences And Reflections∥, Prentice H Delhi.	tall O	India	3,
<u> </u>					

	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
PØ												
CO /												

004	1 _	1								
CO1	Learn to			1	1	1	1	1	1	1
	demonstrate a									
	critical									
	understanding of									
	key concepts in									
	disaster risk									
	reduction and									
	humanitarian									
	response.									
CO2	Critically			1	1	1	1	1	1	1
	evaluate disaster									
	risk reduction									
	and									
	humanitarian									
	response policy									
	and practice									
	from multiple									
	perspectives									
CO3	Develop an			1	1	1	1	1	1	1
	understanding of			-						-
	standards of									
	humanitarian									
	response and									
	practical									
	relevance in									
	specific types of									
	disasters and									
	conflict									
	situations									
`CO4	Critically			1	1	1	1	1	1	1
	understand the			'	'	'	'	'	'	•
	strengths and									
	weaknesses of									
	disaster									
	management									
	approaches									

1	I8AC()3	SANSKRIT FOR TECHNICAL KNOWLEDGE	L	T	Р	С
				2	0	0	0
Cou	rse O	bjectiv	es:				
To g	et a w	orking	knowledge in illustrious Sanskrit, the scientific language in the world. Learnir	ıg of	San	skrit	to
impr	ove b	rain fui	nctioning. Learning of Sanskrit to develop the logic in mathematics, science &	ι oth	ier s	ubje	cts
enha	ancing	the m	emory power. The engineering scholars equipped with Sanskrit will be able	to e	xplo	re th	ie
_		vledge	from ancient literature.				
Unit	1			8		+	0
Alp	habet	s in San	skrit-Past/Present/Future Tense-Simple Sentences				
Unit				8		+	0
Ord	er-Int	roducti	ion of roots-Technical information about Sanskrit Literature				
Unit				8		+	0
Tec	hnical	conce	ots of Engineering-Electrical, Mechanical, Architecture, Mathematics				
			Total (L+	<u></u>	24 5	Oorio	, do
Cou	rsa O	utcome	•	1 <i>)</i> =	<u> 24 F</u>	enc	us
			of the course, the students will be able to				
CO1			erstanding basic Sanskrit language				
CO2	:	Ancie	ent Sanskrit literature about science & technology can be understood				
CO3	:	Being	g a logical language will help to develop logic in students				
Sug	geste	d Read	ling:				
1.	Abhy	aspust	akam" – Dr. Vishwas, Samskrita-Bharti Publication, New Delhi				
2.	"Tea	ch You	rself Sanskrit" PrathamaDeeksha-VempatiKutumbshastri, Rashtriya Sanskri	: Sai	nsth	anaı	n,
	ivew	Deini P	Publication				
3.	India	"s Glor	ious Scientific Tradition" Suresh Soni, Ocean books (P) Ltd., New Delhi				

PO CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Understanding basic Sanskrit language					1	1	1	1	1	1	1
CO2	Ancient Sanskrit literature about science & technology can be understood					1	1	1	1	1	1	1
CO3	Being a logical language will help to develop logic in students					1	1	1	1	1	1	1

18	BAC0	VALUE EDUCATION	L	T	Р	С
			2	0	0	0
Cours	se Ob	jectives:				
To un	derst	and the importance of value education and self-development. To imbibe good val	ues i	n st	uder	nts
	so kn	ow about the importance of character.				
Unit I			4		+	0
Value	es an	d self-development – Social values and individual attitudes - Work ethics, Ind	ian '	/isid	on o	F
		Moral and non-moral valuation - Standards and principles - Value judgements.				
Unit II			6		+	0
		e of cultivation of values - Sense of duty-Devotion - Self-reliance – Confidence – Co				ļ
– Tru	thful	ness – Cleanliness – Honesty – Humanity -Power of faith - National Unity – Patrioti	sm -	Lov	e fo	<u>-</u>
natur	re – D	iscipline				
11	. 1				1	
Unit II			6		+	0
Perso	onalit	y and Behavior Development - Soul and Scientific attitude — Positive — Thinking -	Inte	gri	ty an	d
discip	oline-	Punctuality - Love and Kindness - Avoid fault Thinking - Free from anger - Digr	nity (of I	abor	-
Unive	ersal	brotherhood and religious tolerance - True friendship-Happiness Vs suffering - lo	ve fo	or t	ruth	_
		elfdestructive habits-Association and Cooperation - Doing best for saving nature				
711101	010	Chaestractive habits 7,550ctation and cooperation. Boiling sest for saving hatare				
Unit I\	V		6		+	0
Chara	acter	and Competence - Holy books vs Blind faith - Self-management and Good health	-Sc	end	e of	ļ
reinc	arnat	ion-Equality – Nonviolence – Humility - Role of Women - All religions and same me	ssag	e -	Mino	ı
		- Self-control – Honesty - Studying effectively				
		Total (L-	⊦T)=	22	Perio	ods
		tcomes				
	mpie	tion of the course, the students will be able to				
CO1	•	Knowledge of self-development				
CO2	:	Critically evaluate disaster risk reduction and humanitarian response policy and pr	actic	e fr	om	
000		multiple perspectives				
CO3	:	Learn the importance of Human values				
CO4	:	Developing the overall personality				
Sugge	astad	Reading:				
		aborty, S.K. "Values and Ethics for organizations Theory and practice", Oxford Unive	arcit	, Dr	۵۵۲	
		belhi,1998.	:1 51L	/ 11	css,	
	4CAA F	7CHH,±330.				

PO CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Knowledge of self-development					1	1	1	1	1	1	1
CO2	Critically evaluate disaster risk reduction and humanitarian response policy and practice from multiple					1	1	1	1	1	1	1

	perspectives									
CO3	Learn the importance of Human values			1	1	1	1	1	1	1
CO4	Developing the overall personality			1	1	1	1	1	1	1

18AC05	CONSTITUTION OF INDIA	L	T	Р	<u>C</u>
		2	0	0	0
Course Objectiv	res:				
-	premises informing the twin themes of liberty and freedom from a civil right	s pe	rsp	ecti	ve.
	growth of Indian opinion regarding modern Indian intellectuals" constituti				
	ivil and economic rights as well as the emergence of nationhood in the early y				
	address the role of socialism in India after the commencement of the Bolshevik				
	act on the initial drafting of the Indian Constitution.				
<u> </u>					
Unit I HISTOR	Y OF MAKING OF THE INDIAN CONSTITUTION		4	+	0
History, Drafting	Committee, (Composition & Working)				
1					
Unit II PHILO	SOPHY OF THE INDIAN CONSTITUTION		4	+	0
Preamble, Salien	t Features				
1164111 05:	TOURS OF CONSTITUTIONAL BIGUTS & BUTTER	- 1	. 1	1	_
	OURS OF CONSTITUTIONAL RIGHTS & DUTIES		4	+	0
_	thts, right to equality, right to freedom, right against exploitation, right to				
	and educational rights, right to constitutional remedies, directive principles o	t sta	te p	olio	γ,
fundamental dut	les				
Unit IV ORGA	ANS OF GOVERNANCE		4	. 1	^
			•	+	0
	position, qualifications and disqualifications, powers and functions, executively of positions and functions are distributed as a finding position of the posi				
-	il of ministers, judiciary, appointment and transfer of judges, qualifications,	po	wer	s ar	ıa
functions					
Unit V LOCAL	ADMINISTRATION		4	+	0
	tration head: role and importance, municipalities: introduction, mayor and r				_
	CEO of municipal corporation. Panchayati raj: introduction, PRI: zilapanch				
•	r roles, CEO zilapanchayat: position and role. Block level: organizational hierarc				
	llage level: role of elected and appointed officials, importance of grass root den				
<u> </u>		1001	<i>,</i>		
Unit VI ELECT	ON COMMISSION		4	+	0
	sion: role and functioning. Chief election commissioner and election commiss	sione	ers.	Sta	te
	sion: role and functioning. Institute and bodies for the welfare of SC/ST/OBC an				
	Total (L+1				ds
Course Outcom		•			
Upon completion	of this course, the students will be able to:				
· · · · · · · · · · · · · · · · · · ·		41		: <i>l</i>	
	s the growth of the demand for civil rights in India for the bulk of Indians before	tne	arr	ıvaı	ΟŢ
+ +	i in Indian politics				
	s the intellectual origins of the framework of argument that informed the conce	ptud	IIZa	tion	
	al reforms leading to revolution in India	[CCI	.7	1 -	
	s the circumstances surrounding the foundation of the Congress Socialist Party				
the le	adorable of laurabarial Nobre and the acceptual failure of the acceptual of the	ect	PIPI	LIO	15
46	adership of Jawaharlal Nehru and the eventual failure of the proposal of di		Cici		
	h adult suffrage in the Indian Constitution				
CO4 : Discus	th adult suffrage in the Indian Constitution s the passage of the Hindu Code Bill of 1956.				
CO4 : Discus Suggested Read	th adult suffrage in the Indian Constitution s the passage of the Hindu Code Bill of 1956. Hing:				
CO4 : Discus Suggested Read 1. The Constit	th adult suffrage in the Indian Constitution s the passage of the Hindu Code Bill of 1956. ding: ution of India, 1950 (Bare Act), Government Publication				
CO4 : Discus Suggested Read 1. The Constit 2. Dr. S. N. Bu	th adult suffrage in the Indian Constitution s the passage of the Hindu Code Bill of 1956. Hing: ution of India, 1950 (Bare Act), Government Publication si, Dr. B. R. Ambedkar framing of Indian Constitution, 1st Edition, 2015.				
CO4 : Discus Suggested Read The Constit Dr. S. N. Bu M. P. Jain, I	th adult suffrage in the Indian Constitution s the passage of the Hindu Code Bill of 1956. ding: ution of India, 1950 (Bare Act), Government Publication				

PQ CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	PO11
CO1	Discuss the growth of the demand for civil rights in India for the bulk of Indians before the arrival of Gandhi in Indian politics					1	1	1	1	1	1	1
CO2	Discuss the intellectual origins of the framework of argument that informed the conceptualization of social reforms leading to revolution in India					1	1	1	1	1	1	1
CO3	Discuss the circumstances surrounding the foundation of the Congress Socialist Party [CSP] under the leadership of Jawaharlal Nehru and the eventual failure of the proposal of direct elections through adult suffrage in the Indian Constitution					1	1	1	1	1	1	1
CO4	Discuss the passage of the Hindu Code Bill of 1956.					1	1	1	1	1	1	1

-	10 A	C06	PEDAGOGY STUDIES	1	_	D	С
	IOA	C06	PEDAGOGT STODIES	2	0	0	0
Cou	rse	Objectives	S:				
			evidence on the review topic to inform programme design and policy making			rtak	en
by th	ie D	FID, other	agencies and researchers. Identify critical evidence gaps to guide the develo	pme	ent.		
Unit				-	4		^
		d rational	e, Policy background, Conceptual framework and terminology, Theories	of I	•	+	0
			er, Policy background, Conceptual framework and terminology, Theories er education, Conceptual framework, Research questions, Overview of me				٦d
Sear			er education, conceptual framework, Research questions, Overview of the	tilot	JUIU	gy a	iu
ocu.		В					
Unit	II				2	+	0
Ther	nati	c overview	r: Pedagogical practices are being used by teachers in formal and informa	clas	sro	oms	in
deve	lopi	ing countri	es, Curriculum, Teacher education.				
		1			_		
Unit					4	+	0
			effectiveness of pedagogical practices, Methodology for the in depth		_	•	•
			luded studies, How can teacher education (curriculum and practicum)				
		_	dance materials best support effective pedagogy? Theory of change. Strer dence for effective pedagogical practices, Pedagogic theory and pedagogic	_			
		•	s and beliefs and Pedagogic strategies.	aı a	opro	aciit	25,
Teac	HEL	s attitude	s and beliefs and redagogic strategies.				
Unit	IV				4	+	0
Prof	essio	onal devel	opment: alignment with classroom practices and follow-up support, Peer su	рро	rt, S	uppo	ort
			acher and the community, Curriculum and assessment, Barriers to lea				
reso	urce	es and larg	e class sizes.				
					_		
Unit					2	+	0
		• .	I future directions, Research design, Contexts, pedagogy, teacher educati	on, (curri	culu	m
anu	asse	issment, a	ssemination and research impact				
			Total (L-	-T)=	16 F	Perio	ds
Cou	rse	Outcomes		,			
Upoi	n co	mpletion o	f this course, the students will be able to:				
CO1	-		edagogical practices are being used by teachers in formal and informal	clas	sroc	oms	in
000	+-	· ·	ng countries?				
CO2	:		the evidence on the effectiveness of these pedagogical practices, in what cor	iditio	ons,	and	
<u> </u>	١.		at population of learners?		, .	. ,	
CO3	:		teacher education (curriculum and practicum) and the school curriculum	and	gui	dan	ce
Sug	706	ted Readir	s best support effective pedagogy?				
1.			lman F (2001) Classroom interaction in Kenyan primary schools, Compare, 3	1 (2)	. 24	5-26	1
			004) Curricular reform in schools: The importance of evaluation, Journal of 0				
2.	_	-): 361-379.	Juiii	cuiui		
			K (2003) Teacher training in Ghana - does it count? Multi-site teacher educa	tion	rese	arcl	<u> </u>
3.			TER) country report 1. London: DFID		, 030	-u1 Cl	•
	•	•	K, Lussier K, Pryor J, Westbrook J (2013) Improving teaching and learning of	f has	ic m	aths	
4.	-		n Africa: Does teacher preparation count? International Journal Educational				
		(3): 272–2			J. JP		,
			(2001) Culture and pedagogy: International comparisons in primary education	on. C)xfo	rd ar	nd
5.		ston: Black		- · · · · ·	0		

PO CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	What pedagogical practices are being used by teachers in formal and informal classrooms in developing countries?					1	1	1	1	1	1	1
CO2	What is the evidence on the effectiveness of these pedagogical practices, in what conditions, and with what population of learners?					1	1	1	1	1	1	1
CO3	How can teacher education (curriculum and practicum) and the school curriculum and guidance materials best support effective pedagogy?					1	1	1	1	1	1	1

18AC07	STRESS MANAGEMENT BY YOGA	L	Т	Р	С
		2	0	0	0
Course Objective	s:				
To achieve overall	health of body and mind, To overcome stress				
Unit I			8	+	0
Definitions of Eigh	t parts of yoga				
Unit II			8	+	0
Yam and Niyam. D	o`s and Don"t"s in life. 1.Ahinsa, satya, astheya, bramhacharya and aparigra	aha 2	2.Sha	auch	a,
santosh, tapa, swa	dhyay, ishwarpranidhan				
Unit III			8	+	0
Asan and Pranaya	m 1. Various yog poses and their benefits for mind & body 2. Regularizatio	n of	bre	athir	ng
techniques and its	effects-Types of pranayama				
			•		
	Total (L+	T)=	24 P	erio	ds

Cou	rse	Outcomes:
Upo	n co	empletion of this course, the students will be able to:
CO1	٠.	Develop healthy mind in a healthy body thus improving social health also
CO2	· .	Improve efficiency
Sug	ges	ted Reading:
	Yo	gic Asanas for Group Tarining-Part-I": Janardan Swami Yogabhyasi Mandal, Nagpur "Rajayoga or
1.	со	nquering the Internal Nature" by Swami Vivekananda, Advaita Ashrama (Publication Department),
	Ko	kata

PO CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Develop healthy mind in a healthy body thus improving social health also					1	1	1	1	1	1	1
CO2	Improve efficiency					1	1	1	1	1	1	1

18AC08	PERSONALI	ITY DEV	ELOPN	VENT:	THROU	GH LIF	E ENLI	GHTEN	IMENT	SKILL	.S	L	Т	Р	С
												2	0	0	0
Course Object	ives:														
	ieve the highest	goal ha	ppily,	To bed	ome a	persor	with	stable	mind,	pleasi	ng p	oerso	nali	ty a	nd
	To awaken wisdo	-				•				•	٠.			·	
Unit I													8	+	0
Neetisatakam-	Holistic developm	nent of _l	persor	nality											
Verses- 19,20,2	21,22 (wisdom)														
Verses- 29,31,3	2 (pride & herois	sm)													
Verses- 26,28,6	3,65 (virtue)														
Verses- 52,53,5	9 (dont"s)														
Verses- 71,73,7	5,78 (do"s)														
Unit II													8	+	0
	y to day work an	d duties	S.												
ShrimadBhagw															
Chapter 2-Vers															
•	es 13, 21, 27, 35,														
•	es 5,13,17,23, 35	, ,													
Chapter 18-Ve	ses 45, 46, 48.														
Unit III													8	+	0
Statements of I	oasic knowledge.											Į.		l	
Shrimad Bhagv	_														
Chapter2-Verse															
•	rses 13, 14, 15, 1	6.17. 18	3												
Personality of I		-,,													
Shrimad Bhagv															
Chapter2-Verse															
Chapter 3-Vers	•														
Chapter 4-Vers															
Chapter18 – V															
										Total	I (L+	+T)=	24 F	Perio	ds
Course Outco	nes:														
Upon completion	on of this course,	the stud	dents ı	vill be	able to.										
CO1 : Stud	y of Shrimad-Bha	agwad-0	Geeta	will he	elp the	studer	nt in de	evelopi	ng his	perso	nali	ity ar	nd a	chie	ve
	nighest goal in life	_			•				•	•		•			
CO2 : The	person who has s	tudied (Geeta	will led	ad the r	ation	and mo	ankind	to pea	ice and	d pr	ospei	rity		
CO3 : Stud	y of Neetishataka	am will l	help in	devel	oping v	ersatile	e perso	nality	of stud	lents.					
Suggested Re			•				•								
	hagavad Gita" by	/ Swami	Swarı	ıpanaı	ndaAdv	aita As	hram	(Public	ation [Depart	me	nt), K	olka	ata.	
₂ Bhartriha	ri"s Three Satakaı			•				•							N
Delhi.															
		BQ /	5 0		·		F.				-	0.10	-		7
PO CO	Statement	PO1	PO	PO	PO4	PO	PO	PO	PO	PO	P	O10	P	01	

PO	CO Statement	PO1	PO 2	PO 3	PO4	PO 5	PO 6	PO 7	PO 8	PO 9	PO10	PO1 1
CO1	Study of Shrimad- Bhagwad-Geeta will help the student in					1	1	1	1	1	1	1

	developing his personality and achieve the highest goal in life									
CO2	The person who has studied Geeta will lead the nation and mankind to peace and prosperity			1	1	1	1	1	1	1
CO3	Study of Neetishatakam will help in developing versatile personality of students.			1	1	1	1	1	1	1

18PE	SE1	PATTERN RECOGNITION	L	Т	Р	С
			3	0	0	3
Course	Ohiooti					
Course		ves: stand pattern and unsupervised classification.				
		n feature extraction and selection.				
		stand structural pattern recognition.				
0. 1.	3 4114010	nana di adalah patam 1000gi itani				
Unit I	PATTI	ERN CLASSIFIER		9	+	0
Maximu Problem	m likelih s with	ttern recognition - Discriminant functions - Supervised learning - Parametric nood estimation - Bayesian parameter estimation - Perceptron algorithm - LMS Bayes approach - Pattern classification by distance functions - Minimum dis	SE a	lgori	thm	-
classifie	er.					
Unit II	UNSU	JPERVISED CLASSIFICATION		9	+	0
		unsupervised learning and classification – Clustering concept – C-mea	ns a		-	-
	nical clu	stering procedures - Graph theoretic approach to pattern clustering - Valid				
Unit III	STR	UCTURAL PATTERN RECOGNITION		9	_	0
		mal grammars - String generation as pattern description - Recognition of synta	ctic		rinti	
		nastic grammars and applications - Graph based structural representation.	Clic		при	
Unit IV	FEA	TURE EXTRACTION AND SELECTION		9	+	0
		ation - Karhunen - Loeve transformation - Feature selection through functions e selection.	app	roxir	nati	on
Unit V	REC	ENT ADVANCES		9	+	0
Unsuper	rvised le	k structures for Pattern Recognition - Neural network based Pattern earning in neural Pattern Recognition - Self-organizing networks - Fuzzy logic - ern classification using Genetic Algorithms				
		Total /I .	Τ\	4E D	_ =: _	
Course	Outcon	Total (La	· I)=	45 P	eric	as
		n of this course, the students will be able to:				
CO1 :	Tosc	lve pattern and unsupervised classification problems.				
CO2 :	То ре	erform feature extraction and selection.				
CO3 :	To ex	recute structural pattern recognition.				
Text Bo						
I. So	ns Inc.,	chalkoff, Pattern Recognition Statistical, Structural and Neural Approaches, Joh New York, 1992.		•	<u></u>	
		onzales, Pattern Recognition Principles, Wesley Publication Company, London,	197	4		
Referen			70			
		, and Har P.E., Pattern Classification and Scene Analysis, Wiley, New York, 197		orle i	1001)
2. Mo		dier and Eric Smith P., Pattern Recognition Engineering, John Wiley & Sons, No	W Y	υιΚ,	1993)
		v.geeksforgeeks.org/pattern-recognition-introduction/				
1144	JJ.,, VV VV V	ngosnororgosnororg pattorn rocognition introduction				

\ PO	CO Statement	PO1	PO	РО	PO4	PO	PO	PO	РО	РО	PO10	PO1
			2	3		5	6	7	8	9		1
co /												
CO1	To solve pattern					2	1	1	2	1	2	1
	and unsupervised											
	classification											
	problems.											

CO2	To perform feature extraction and selection.			1	1	2	1	1	2	1
CO3	To execute structural pattern recognition.			1	1	1	2	1	3	3