

GOVERNMENT COLLEGE OF ENGINEERING SALEM - 636 011

(An Autonomous Institution Affiliated to Anna University, Chennai)

REGULATIONS 2022 CURRICULUM AND SYLLABUS

(For Candidates admitted from 2022 - 2023 onwards)

DEPARTMENT OF MECHANICAL ENGINEERING (FULL TIME PROGRAMME)

DEPARTMENT OF MECHANICAL ENGINEEERING - VISION & MISSION

A serene and tranquil 'MECH' atmosphere helps the dynamic professionals to kindle their innovative minds. The enduring efforts of faculties have enhanced the students with omnipotent skills, with considerable research work being done in the department.

VISION

The department of mechanical engineering is committed to blossom into a centre of excellence, dedicated and competent engineers by providing global quality interactive technical education to cater the needs of the industries and nation into a technologically, socially and culturally advanced one.

MISSION

- Constantly updating the departmental resources, faculty and other infrastructure by acquiring
 the state of the art equipments and by imparting constant in-service training to the faculty and
 supporting staff.
- Promoting skilled and employable graduates to meet the challenges in emerging fields of engineering.
- To prepare the students for prosperous career in entrepreneurship with leader ship qualities, ethics and human values.
- The department executes life-long learning skills and provides engineering services for sustainable development of the society.

PROGRAMME EDUCATIONAL OBJECTIVES

- **PEO 1**: To provide students with strong fundamental knowledge in mathematics, science and basic engineering to enable them to solve the mechanical engineering related problems.
- **PEO 2**: To develop expertise in core areas like design, analyze and synthesize data and technical concepts with software skills to create novel products and solutions for the real time problems.
- **PEO 3**: Graduates able to exhibit professionalism in their profession with effective communication, ethical attitude, entrepreneurship skills and the knowledge in global economy to meet the social challenges.

• **PEO 4**: To promote the students for continuous learning towards professional growth in contemporary areas of socio-technological issues like energy crisis, environmental pollution, industrial issues and natural disaster.

PROGRAMME OUTCOMES

- **PO1**: Apply the knowledge of mathematics, science and engineering specialization to solve complex engineering problems.
- **PO2**: Graduates will have the ability to identify, formulate, conduct experiment and analyze engineering problems
- **PO3**: Graduates will demonstrate the ability to design and evaluate a mechanical system (or) process with appropriate consideration for the socio environmental conditions.
- **PO4**: Graduates will demonstrate the ability to design and conduct experiments, interpretation of data and synthesis of information to provide valid conclusions.
- **PO5**: Graduates will be familiar with modern engineering software tools and equipments to model and predict the Mechanical engineering problems
- PO6: Demonstrate knowledge to assess societal, health, safety, legal and cultural issues and the
 consequent responsibilities relevant to engineering practice
- PO7: Understand the impact of engineering solution in the environmental context and the need for sustainable development.
- **PO8**: Apply ethical principles and commitment to professional ethics and norms of the practice in the field of Mechanical engineering.
- PO9: Obtain the ability to function individually and also as a team member in multi-disciplinary activities.
- **PO10**: Able to communicate effectively in verbal, written and graphical forms.
- PO11: Recognize the need and ability to engage in independent and life-long learning in the broadest context of technological change.
- **PO12**: Graduates will have the ability to employ effective project management skills and financial principles to develop project plans in multi-disciplinary environments.

PROGRAMME SPECIFIC OUTCOMES

- **PSO 1**: Ability to identify, analyze and solve engineering problems in the domains of Design, Thermal and Manufacturing systems.
- **PSO 2**: Ability to apply their knowledge in principle of design and analysis, in execution of automation in mechanical system / processes.
- **PSO 3**: Ability to involve professionally in industries or as an entrepreneur by applying manufacturing and management practices.

CURRICULUM

B.E – MECHANICAL ENGINEERING (FULL TIME) – R2022 CURRICULUM

	1	SEMESTE	CR I	1			1	ı		
S.	Course	Course Title	Cat	Hou	urs/W	⁷ eek	C	Ma	ax. Ma	arks
No.	Code	Course Title	Cat	L	T	P		CA	FE	Total
1	22MC101	Induction Program	MC	-	-	-	0	-	-	-
		THEOR	Y							
2	22MA101	Matrices, Calculus and Ordinary Differential Equations	BS	3	1	0	4	40	60	100
3	22CY101	Engineering Chemistry	BS	3	1	0	4	40	60	100
4	22EE101	Basic Electrical and Electronics Engineering	ES	3	1	0	4	40	60	100
5	22ME101	Engineering Graphics and Design	ES	1	0	4	3	40	60	100
6	22CS101	Problem Solving and C Programming	ES	3	0	0	3	40	60	100
7	22MC102	Heritage of Tamil / தமிழர்மரபு	HS MC	1	0	0	1	100	-	100
		PRACTIC	AL							
8	22EN102	Professional Skills Laboratory	HS	0	0	2	1.0	60	40	100
9	22PH103	Physics Laboratory	BS	0	0	3	1.5	60	40	100
10	22CY102	Chemistry laboratory	BS	0	0	3	1.5	60	40	100
11	22EE102	Basics Electrical and Electronics Engineering Laboratory	ES	0	0	3	1.5	60	40	100
		TOTAL					24.5			1000
		SEMESTE	R II				•			•
S.	Course			Hot	urs/W	/eek		Ma	ax. Ma	arks
No.	Code	Course Title	Cat	L	T	P	C	CA	FE	Total
		THEOR	Y	1						
1	22EN101	Communicative English (Theory cum Practical)	HS	2	0	2	3	50	50	100
2	22MA201	Partial Differential Equations, Vector Calculus and Complex Variables	BS	3	1	0	4	40	60	100
3	22PH101	Engineering Physics	BS	3	1	0	4	40	60	100
4	22ES101	Engineering Mechanics	ES	3	0	0	3	40	60	100
5	22HS201	Universal Human Values	HS	2	1	0	3	40	60	100
6	22MCIN01	Engineering Sprints	EE	0	0	2	1	100	-	100
7	22MC201	Tamils and Technology / தமிழரும் தொழில்நுட்பமும்	HS MC	1	0	0	1	100	-	100
8	22NC201	NCC Course – I (only for NCC students)*	NC	3	0	0	3*	40	60	100*
	T	PRACTIC	AL	ı	1	1	1	ı	1	_
9	22CS102	Computer Practice and C Programming Laboratory	ES	0	0	3	1.5	60	40	100
10	22ME102	Workshop Manufacturing Practices TOTAL	ES	0	0	4	2.0 22.5	60	40	100 900

^{*}NCC credit course level II is offered for NCC students only. The grades earned by the students will be recorded in the Mark sheet, however the same shall not be considered for the computation of CGPA

		SEMESTE	R III							
S.	Course	G WH	G .	Но	urs/W	eek		Ma	ax. Ma	arks
No.	Code	Course Title	Cat	L	Т	P	С	CA	FE	Total
		THEOR	RY		I.				l .	•
1	22MA305	Fourier Series, Boundary Value Problems and Transforms	BS	3	0	0	3	40	60	100
2	22ME301	Engineering Thermodynamics	PC	3	1	0	4	40	60	100
3	22ME302	Fluid Mechanics and Machinery	PC	3	1	0	4	40	60	100
4	22ME303	Manufacturing Processes	PC	3	0	0	3	40	60	100
5	22MT310	Materials Engineering	ES	3	0	0	3	40	60	100
6	22MCIN02	Innovation Sprints	EE	0	0	2	1	100		100
7	22NC301	NCC Course – II (only for NCC Students)*	NC	3	0	0	3*	40	60	100*
		PRACTIO	CAL		•	•		•		•
8	22ME304	CAD Laboratory	PC	0	0	3	1.5	60	40	100
9	22CE308	Strength of Materials and Fluid Mechanics Laboratory	ES	0	0	3	1.5	60	40	100
		TOTAL					21			800
		SEMESTE	R IV							
S.	Course			Но	urs/W	eek		Ma	ax. Ma	arks
No.	Code	Course Title	Cat	L	Т	P	C	CA	FE	Total
		THEOR	RY		I	I		I		<u> </u>
1	22ME401	Kinematics of Machinery	PC	3	1	0	4	40	60	100
2	22ME402	Thermal Engineering	PC	3	1	0	4	40	60	100
3	22ME403	Metal cutting and Machine Tools	PC	3	0	0	3	40	60	100
4	22ME404	Hydraulics and Pneumatics	PC	3	0	0	3	40	60	100
5	22CE409	Strength of Materials	ES	3	0	0	3	40	60	100
6	22MCIN03	Design Sprints	EE	0	0	2	1	100	-	100
7	22CYMC01	Environmental Science	MC	2	0	1	0	100	-	100
		PRACTIO	CAL							
9	22ME405	Thermal Engineering Laboratory	PC	0	0	3	1.5	60	40	100
10	22ME406	Manufacturing Technology Laboratory	PC	0	0	3	1.5	60	40	100
		TOTAL					21			800

^{*}NCC credit course level II is offered for NCC students only. The grades earned by the students will be recorded in the Mark sheet, however the same shall not be considered for the computation of CGPA

	SEMESTER V												
S.	Course	СТИ-	G-4	Hou	rs/W	eek	C	M	Iax. M	arks			
No.	Code	Course Title	Cat	L	T	P	С	CA	FE	Total			
		THEOR	RY										
1	22ME501	Design of Machine Elements	PC	3	1	0	4	40	60	100			
2	22ME502	Heat and Mass Transfer	PC	3	0	0	3	40	60	100			
3	22ME503	Metrology and Quality Control	PC	3	0	0	3	40	60	100			
4	22ME504	Dynamics of Machinery	PC	3	0	0	3	40	60	100			
5	22ME505	Instrumentation and Control system	PC	3	0	0	3	40	60	100			
6	22MCIN04	Ideation Sprints	EE	0	0	2	1	100	-	100			
7	22MC301	Indian Constitution	MC	2	0	0	0	100	-	100			
		PRACTIO	CAL										
8	22ME506	Dynamics and Metrology Laboratory	PC	0	0	3	1.5	60	40	100			
9	22EN501	Placement and Career Skills Laboratory	HS	0	0	3	1.5	60	40	100			
10	22ME507	Heat Transfer and Refrigeration Laboratory	PC	0	0	3	1.5	60	40	100			
	TOTAL 21.5 900												

SEMESTER VI (REGULAR STREAM)

S.	Course	Course Title	Cat	Hou	rs/W	eek	C	Max. Marks			
No.	Code	Course Title	Cat	L	T	P	C	CA	FE	Total	
		THEOR	Y								
1	22MEPEXX	Professional Elective – I	PE	3	0	0	3	40	60	100	
2	22MEPEXX	Professional Elective – II	PE	3	0	0	3	40	60	100	
3	22MEPEXX	Professional Elective – III	PE	3	0	0	3	40	60	100	
4	22_OEXX	Open Elective –I	OE	3	0	0	3	40	60	100	
5	22 OEXX	Open Elective –II	OE	3	0	0	3	40	60	100	
6	22_OEXX	Open Elective-III	OE	3	0	0	3	40	60	100	
		PRACTIC	AL								
7	22ME601	Mini Project	EE	0	0	6	3	60	40	100	
		TOTAL					21			700	

		SEMESTER VI (PR	OTOSEM	STR	EAM)				
S.	Course	G WH		Ho	urs/V	Veek		N	Iax. M	larks
No.	Code	Course Title	Cat	L	Т	P	С	CA	FE	Total
		THE	ORY							
1	22PSPE01	Computational Hardware	PE	3	0	0	3	100	0	100
2	22PSPE02	Coding for Innovators	PE	3	0	0	3	100	0	100
3	22PSPE03	Industrial Automation	PE	3	0	0	3	100	0	100
4	22PSOE01	Applied Design Thinking	OE	3	0	0	3	100	0	100
5	22PSOE02	Startup Fundamentals	OE	3	0	0	3	100	0	100
6	22PSOE03	Prototype Development	OE	3	0	0	3	100	0	100
		PRAC	TICAL							
7	22PSEE01	Robotics	EE	0	0	6	3	100	0	100
		TOTAL					21			700
		SEMES	TER VII							
S.	Course			Ho	urs/V	Veek		N	Iax. M	larks
No.	Code	Course Title	Cat	L	T	P	C	CA	FE	Total
		THE	ORY		L		ı	I	ı	l
1	22ME701	Mechatronics	PC	3	0	0	3	40	60	100
2	22ME702	Finite Element Analysis	PC	3	0	0	3	40	60	100
3	22HS701	Operations Research	HS	3	0	0	3	40	60	100
4	22MEPEXX	Professional Elective – IV	PE	3	0	0	3	40	60	100
		PRAC	TICAL							
5	22ME703	Mechatronics Laboratory	PC	0	0	3	1.5	60	40	100
6	22ME704	Simulation Laboratory	PC	0	0	3	1.5	60	40	100
7	22ME705	CAM Laboratory	PC	0	0	3	1.5	60	40	100
		TOTAL					16.5			800
		SEMES	TER VIII							
S.	Course	G		Но	urs/V	Veek	_ ~	N	Iax. M	larks
No.	Code	Course Title	Cat	L	T	P	C	CA	FE	Total
		THE	ORY		1		1	1	1	ı
1	22MEPEXX	Professional Elective – V	PE	3	0	0	3	40	60	100
2	22MEPEXX	Professional Elective – VI	PE	3	0	0	3	40	60	100
3	22OEXX	Open Elective –IV	OE	3	0	0	3	40	60	100
		PRAC	TICAL		•		•	•	•	•
4	22ME801	Project Work	EE	0	0	20	10	80	120	200
		TOTAL					19			500
		GRAND TOTAL					167			

PROFESSIONAL ELECTIVE COURSES

Code No.	Course	Hours/Week		eek	С	Max	ximum	Marks			
	PROFESSIONAL ELECTIVES -	I (VI S	EMES	TER)							
		L	T	P	C	CA	FE	Total			
22MEPE11	Automobile Engineering	3	0	0	3	40	60	100			
22MEPE12	Composite Materials	3	0	0	3	40	60	100			
22MEPE13	Computer Integrated Manufacturing	3	0	0	3	40	60	100			
22MEPE14	Design of Transmission system	3	0	0	3	40	60	100			
22MEPE15	Energy Conservation in Industries	3	0	0	3	40	60	100			
22MEPE16	Gas Dynamics & Jet Propulsion	3	0	0	3	40	60	100			
22MEPE17	Renewable Energy System	3	0	0	3	40	60	100			
	PROFESSIONAL ELECTIVES - II (VI SEMESTER)										
22MEPE21	Advanced Strength of Materials	3	0	0	3	40	60	100			
22MEPE22	Energy Efficient Buildings Design	3	0	0	3	40	60	100			
22MEPE23	Engineering System Analysis and Design	3	0	0	3	40	60	100			
22MEPE24	Industrial Engineering and Management	3	0	0	3	40	60	100			
22MEPE25	Internal Combustion Engines	3	0	0	3	40	60	100			
22MEPE26	Machine Drawing	1	0	4	3	40	60	100			
22MEPE27	Power plant Engineering	3	0	0	3	40	60	100			
	PROFESSIONAL ELECTIVES - I	II (VI	SEME	STER)							
22MEPE31	Fuels and Combustion	3	0	0	3	40	60	100			
22MEPE32	Maintenance Engineering	3	0	0	3	40	60	100			
22MEPE33	Non-traditional Machining Process	3	0	0	3	40	60	100			
22MEPE34	Professional Ethics and Human Values	3	0	0	3	40	60	100			
22MEPE35	Rapid Product Development Technologies	3	0	0	3	40	60	100			
22MEPE36	Refrigeration and Air Conditioning	3	0	0	3	40	60	100			
22MEPE37	Solar Energy Technology	3	0	0	3	40	60	100			
	PROFESSIONAL ELECTIVES - I	V (VII	SEME	STER))						
22MEPE41	Advanced Decision Modelling Technique	3	0	0	3	40	60	100			
22MEPE42	Automation in Manufacturing	3	0	0	3	40	60	100			
22MEPE43	Cryogenic Engineering	3	0	0	3	40	60	100			
22MEPE44	Fracture Mechanics and Failure Analysis	3	0	0	3	40	60	100			
22MEPE45	Fundamentals of Tribology	3	0	0	3	40	60	100			
22MEPE46	Metal Forming Processes	3	0	0	3	40	60	100			

22MEPE47	Micro and Nano Machining	3	0	0	3	40	60	100
	PROFESSIONAL ELECTIVES - V	(VIII	SEME	STER)			
22MEPE51	Analysis and Synthesis of Mechanism	3	0	0	3	40	60	100
22MEPE52	Design of Jigs, Fixtures and Press tools	3	0	0	3	40	60	100
22MEPE53	Heat Transfer Problems in Electronics and Instrumentation	3	0	0	3	40	60	100
22MEPE54	Nano Technology	3	0	0	3	40	60	100
22MEPE55	Nuclear Engineering	3	0	0	3	40	60	100
22MEPE56	Thermal Turbo Machines	3	0	0	3	40	60	100
22MEPE57	Total Quality Management	3	0	0	3	40	60	100
	PROFESSIONAL ELECTIVES - V	I (VIII	SEMI	ESTER	.)			
22MEPE61	Design of Production Tooling	3	0	0	3	40	60	100
22MEPE62	Engineering System Modelling and Simulation	3	0	0	3	40	60	100
22MEPE63	Entrepreneurship Development	3	0	0	3	40	60	100
22MEPE64	Industrial Safety	3	0	0	3	40	60	100
22MEPE65	Introduction to Computational Fluid Dynamics	3	0	0	3	40	60	100
22MEPE66	Marine Engineering	3	0	0	3	40	60	100
22MEPE67	Robotics	3	0	0	3	40	60	100

LIST OF OPEN ELECTIVE COURSES

C No	Course	Commen	Cat	Но	ours/W	eek		Maximum Marks				
S.No.	Code	Course	Cat	L	Т	P	С	CA	FE	Total		
		COURSES OFFERED BY THE DEPAR	RTMEN'	T OF N	MATH	EMAT	ICS					
1	22MAOE01	Sampling Theory	OE	3	0	0	3	40	60	100		
2	22MAOE02	Numerical Methods	OE	3	0	0	3	40	60	100		
3	22MAOE03	Probability and Queueing Theory	OE	3	0	0	3	40	60	100		
		COURSES OFFERED BY THE DEPART	MENT C	F CIV	IL EN	GINEI	ERING	r				
4	22CEOE01	Environmental Management	OE	3	0	0	3	40	60	100		
5	22CEOE02	Disaster Mitigation and Management	OE	3	0	0	3	40	60	100		
6	22CEOE03	Repair and Rehabilitation of Building Elements	OE	3	0	0	3	40	60	100		
7	22CEOE04	Mechanics of Deformable bodies	OE	3	0	0	3	40	60	100		
COURSES OFFERED BY THE DEPARTMENT OF COMPUTER SCIENCE AND ENGINEERING												
8	22CSOE01	Object Oriented Programming Concepts	OE	3	0	0	3	40	60	100		
9	22CSOE02	Operating Systems Principles	OE	3	0	0	3	40	60	100		
10	22CSOE03	Computer Communications and Networks	OE	3	0	0	3	40	60	100		
11	22CSOE04	Python Programming	OE	3	0	0	3	40	60	100		
12	22CSOE05	Introduction to Programming in Java	OE	3	0	0	3	40	60	100		
13	22CSOE06	Computer Organization	OE	3	0	0	3	40	60	100		
14	22CSOE07	Data Structures Using C++	OE	3	0	0	3	40	60	100		
15	22CSOE08	Cloud Computing Fundamentals	OE	3	0	0	3	40	60	100		
16	22CSOE09	Artificial Intelligence and ML	OE	3	0	0	3	40	60	100		
CO	URSES OFFER	RED BY THE DEPARTMENT OF ELECT	RONICS	SAND	COMN	MUNIC	CATIO	N ENGI	NEER	ING		
17	22ECOE01	Fundamentals of Electron Devices	OE	3	0	0	3	40	60	100		
18	22ECOE02	Principles of Modern Communication Systems	OE	3	0	0	3	40	60	100		
19	22ECOE03	Microcontrollers and its applications	OE	3	0	0	3	40	60	100		
20	22ECOE04	Computer Networks	OE	3	0	0	3	40	60	100		
21	22ECOE05	Basics of Embedded Systems	OE	3	0	0	3	40	60	100		
22	22ECOE06	Basics of Internet of Things	OE	3	0	0	3	40	60	100		
23	22ECOE07	Basics of AI	OE	3	0	0	3	3 40 60 10				
(COURSES OF	FERED BY THE DEPARTMENT OF ELEC	CTRICA	L ANI	D ELE	CTRO	NICS I	ENGINE	EERIN	G		
24	22EEOE01	Renewable Energy Sources	OE	3	0	0	3	40	60	100		
25	22EEOE02	Industrial Drives	OE	3	0	0	3	40	60	100		
26	22EEOE03	Energy Conservation and Management	OE	3	0	0	3	40	60	100		

27	22EEOE04	Electric Vehicles	OE	3	0	0	3	40	60	100
21					Ŭ		_		00	100
	COU	URSES OFFERED BY THE DEPARTMEN	T OF M	ЕСНА	NICAI	L ENG	INEEL	RING	ı	
28	22MEOE01	Design of Machine Elements and Machining	OE	3	0	0	3	40	60	100
29	22MEOE02	Industrial Engineering	OE	3	0	0	3	40	60	100
30	22MEOE03	Industrial Robotics	OE	3	0	0	3	40	60	100
31	22MEOE04	Power plant Engineering	OE	3	0	0	3	40	60	100
32	22MEOE05	Principles of Management	OE	3	0	0	3	40	60	100
33	22MEOE06	Professional Ethics in Engineering	OE	3	0	0	3	40	60	100
34	22MEOE07	Renewable Sources of Energy	OE	3	0	0	3	40	60	100
35	22MEOE08	Robotic Process Automation	OE	3	0	0	3	40	60	100
36	22MEOE09	Total Quality Management	OE	3	0	0	3	40	60	100
	COUR	SES OFFERED BY THE DEPARTMENT	OF MET	TALLU	RGIC	AL EN	GINE	ERING		
37	22MTOE01	Foundry and Welding Technology	OE	3	0	0	3	40	60	100
38	22MTOE02	Surface Engineering	OE	3	0	0	3	40	60	100
39	22MTOE03	Design and Selection of Materials	OE	3	0	0	3	40	60	100
40	22MTOE04	Nano Science and Technology	OE	3	0	0	3	40	60	100
41	22MTOE05	Materials for Automobile Components	OE	3	0	0	3	40	60	100

B.E – HONOURS PROFESSIONAL ELECTIVE COURSES – VERTICALS

A student can also optionally register for additional courses (18 credits) and become eligible for the award of B.E. / B.Tech. (Honours) or Minor Degree. For B.E. / B. Tech. (Honours). A student shall register for the additional courses (18 credits) from semester V onwards. These courses shall be from the same vertical or a combination of different verticals of the same programme of study only. For minor degree, a student shall register for the additional courses (18 credits) from semester V onwards. All these courses have to be in a particular vertical from any one of the other programmes.

Vertical - I	Vertical - II	Vertical - III
Clean and Green Energy Technologies	Computational Engineering	Product and Process Development
22MEH101 Hydrogen and Fuel Cell Technologies	22MEH201 Numerical methods in Mechanical Engineering	22MEH301 Precision Engineering
22MEH102 Thermal Management of Electric Vehicle Battery Systems	22MEH202 Advanced Fluid Mechanics	22MEH302 Advanced Materials Technology
22MEH103 Electric and Hybrid Vehicle Technology	22MEH203 Fundamentals of Bio-Mechanics	22MEH303 Additive Manufacturing
22MEH104 Alternate Fuels for IC Engines	22MEH204 Introduction to Machine Learning	22MEH304 Non Destructive Testing and Failure Analysis
22MEH105 Advanced Energy Storage Technologies	22MEH205 Design Optimization and Design Theory	22MEH305 Product Life Cycle Management
22MEH106 Solar Power Plants	22MEH206 Advanced Finite Element Methods	22MEH306 Ergonomics in Design
22MEH107 Materials for Solar Devices	22MEH207 Advanced Computational Fluid Dynamics	22MEH307 Surface Engineering
22MEH108 Design of Solar and Wind Systems	22MEH208 Smart Materials and Structures	22MEH308 Industrial Layout Design and Safety
22MEH109 Fire Engineering and Explosion Control	22MEH209 Design of Pressure vessels	22MEH309 Digital Manufacturing and IOT
22MEH110 Energy Management and Environmental Benefits	22MEH210 Mechanical Vibrations	22MEH310 Smart Mobility and Intelligent vehicles

PROFESSIONAL ELECTIVE COURSES – VERTICALS VERTICAL I - CLEAN AND GREEN ENERGY TECHNOLOGIES

S.	Code No.	Course Title	Но	urs/W	eek	C	Maximum Marks			
No.	Code No.	Course Title	L	T	P	C	CA	FE	Total	
1.	22MEH101	Hydrogen and Fuel Cell Technologies	3	0	0	3	40	60	100	
2.	22MEH102	Thermal Management of Electric Vehicle Battery Systems	3	0	0	3	40	60	100	
3.	22MEH103	Electric and Hybrid Vehicle Technology	3	0	0	3	40	60	100	
4.	22MEH104	Alternate Fuels for IC Engines	3	0	0	3	40	60	100	
5.	22MEH105	Advanced Energy Storage Technologies	3	0	0	3	40	60	100	
6.	22MEH106	Solar Power Plants	3	0	0	3	40	60	100	
7.	22MEH107	Materials for Solar Devices	3	0	0	3	40	60	100	
8.	22MEH108	Design of Solar and Wind Systems	3	0	0	3	40	60	100	
9.	22MEH109	Fire Engineering and Explosion Control	3	0	0	3	40	60	100	
10.	22MEH110	Energy Management and Environmental Benefits	3	0	0	3	40	60	100	

<u>VERTICAL II - COMPUTATIONAL ENGINEERING</u>

S.	Codo No	Course Title	Но	urs/W	eek	C	Maximum Marks			
No.	Code No.	Course Title	L	Т	P	C	CA	FE	Total	
1.	22MEH201	Numerical methods in Mechanical Engineering	3	0	0	3	40	60	100	
2.	22MEH202	Advanced Fluid Mechanics	3	0	0	3	40	60	100	
3.	22MEH203	Fundamentals of Bio-Mechanics	3	0	0	3	40	60	100	
4.	22MEH204	Introduction to Machine Learning	3	0	0	3	40	60	100	
5.	22MEH205	Design Optimization and Design Theory	3	0	0	3	40	60	100	
6.	22MEH206	Advanced Finite Element Methods	3	0	0	3	40	60	100	
7.	22MEH207	Advanced Computational Fluid Dynamics	3	0	0	3	40	60	100	
8.	22MEH208	Smart Materials and Structures	3	0	0	3	40	60	100	
9.	22MEH209	Design of Pressure vessels	3	0	0	3	40	60	100	
10.	22MEH210	Mechanical Vibrations	3	0	0	3	40	60	100	

VERTICAL III - PRODUCT AND PROCESS DEVELOPMENT

S.	Code No.	Course Title	Но	urs/W	eek	C	Maximum Marks			
No.	Code No.	Course Title	L	T	P	C	CA	FE	Total	
1.	22MEH301	Precision Engineering	3	0	0	3	40	60	100	
2.	22MEH302	Advanced Materials Technology	3	0	0	3	40	60	100	
3.	22MEH303	Additive Manufacturing		0	0	3	40	60	100	
4.	22MEH304	Non Destructive Testing and Failure Analysis		0	0	3	40	60	100	
5.	22MEH305	Product Life Cycle Management	3	0	0	3	40	60	100	
6.	22MEH306	Ergonomics in Design	3	0	0	3	40	60	100	
7.	22MEH307	Surface Engineering	3	0	0	3	40	60	100	
8.	22MEH308	Industrial Layout Design and Safety	3	0	0	3	40	60	100	
9.	22MEH309	Digital Manufacturing and IOT		0	0	3	40	60	100	
10.	22MEH310	Smart Mobility and Intelligent vehicles	3	0	0	3	40	60	100	

MINOR DEGREE - VERTICALS

For minor degree, a student shall register for the additional courses (18 credits) from semester V onwards. All these courses have to be in a particular vertical from any one of the other programmes.

VERTICAL - I	VERTICAL - II	VERTICAL - III	VERTICAL - IV	VERTICAL - V	VERTICAL - VI
Civil Engineering	Computer Science and Engineering	Electronics and Communication Engineering	Electrical and Electronics Engineering	Mechanical Engineering	Metallurgical Engineering
22CEM01 Construction Materials	22CSM01 Programming in C++	22ECM01 Electron Devices	22EEM01 – Linear and Digital Electronics Circuits	22MEM01 Engineering Thermodynamics	22MTM01 Advanced Physical Metallurgy
22CEM02 Building Construction & Equipment	22CSM02 Advanced Data Structures and Algorithms	22ECM02 Digital Electronics	22EEM02 – Microprocessor and Microcontrollers	22MEM02 Fluid Mechanics and Machinery	22MTM02 Metallurgical Thermodynamics and kinetics
22CEM03 Concrete Technology	22CSM03 Computer Organization and Design	22ECM03 Electronic Circuits	22EEM03 – Control Systems	22MEM03 Manufacturing Processes	22MTM03 Mechanical Behaviour of Materials
22CEM04 Environmental Engineering	22CSM04 Advanced Operating Systems	22ECM04 Signal Processing	22EEM04 – Measurement and Instrumentation	22MEM04 Materials Engineering	22MTM04 Rate Processing in Metallurgy
22CEM05 Basics of Transportation Engineering	22CSM05 Data Communication and Computer Networks	22ECM05 Fundamentals of Microprocessors and Microcontrollers	22EEM05 – Electrical Machines	22MEM05 Kinematics of Machinery	22MTM05 Corrosion and Surface Engineering
22CEM06 Repair and Rehabilitation Structures	22CSM06 Programming Essentials in Python	22ECM06 Analog and Digital Communication	22EEM06 – Electric Drives and Control	22MEM06 Hydraulics and Pneumatics	22MTM06 Characterization of Materials
22CEM07 Green Building Technology	22CSM07 Advanced Database System Concepts	22ECM07 Communication Networks	22EEM07 – Electric Vehicle and Control	22MEM07 Design of Machine Elements	22MTM07 Automotive, Aerospace and Defense Materials
	22CSM08 Virtualization and Cloud Computing	22ECM08 Fundamentals of IoT	22EEM08 – Electrical Energy Conservation and Auditing	22MEM08 Heat and Mass Transfer	
		22ECM09 Wireless Sensors and Networking	22EEM09 – SMPS and UPS	22MEM09 Metrology and Quality Control	
		22ECM10 Fundamentals of Embedded Systems	22EEM10 –Utilization of Electrical Energy	22MEM10 Dynamics of Machinery	

LIST OF MINOR DEGREE - VERTICALS

	Course		~ .	Но	urs/W	eek	lits	Maximum Marks				
S.No.	Code	Course	Cat	L	T	P	Credits	CA	FE	Total		
		CIVIL ENGINE	EERIN	G								
1	22CEM01	Construction Materials	OE	3	0	0	3	40	60	100		
2	22CEM02	Building Construction & Equipment's	OE	3	0	0	3	40	60	100		
3	22CEM03	Concrete Technology	OE	3	0	0	3	40	60	100		
4	22CEM04	Environmental Engineering	OE	3	0	0	3	40	60	100		
5	22CEM05	Basics of Transportation Engineering	OE	3	0	0	3	40	60	100		
6	22CEM06	Repair and Rehabilitation of Structures	OE	3	0	0	3	40	60	100		
7	22CEM07	Green Building Technology	OE	3	0	0	3	40	60	100		
	COMPUTER SCIENCE AND ENGINEERING											
1	22CSM01	Programming in C++	OE	3	0	0	3	40	60	100		
2	22CSM02	Advanced Data Structures and Algorithms	OE	3	0	0	3	40	60	100		
3	22CSM03	Computer Organization and Design	OE	3	0	0	3	40	60	100		
4	22CSM04	Advanced Operating Systems	OE	3	0	0	3	40	60	100		
5	22CSM05	Data Communication and Computer Networks	OE	3	0	0	3	40	60	100		
6	22CSM06	Programming Essentials in Python	OE	3	0	0	3	40	60	100		
7	22CSM07	Advanced Database System Concepts	OE	3	0	0	3	40	60	100		
8	22CSM08	Virtualization and Cloud Computing	OE	3	0	0	3	40	60	100		
		ELECTRONICS AND COMMUN	ICATIO	ON EN	IGINE	EERIN	G		ı			
1	22ECM01	Electron Devices	OE	3	0	0	3	40	60	100		
2	22ECM02	Digital Electronics	OE	3	0	0	3	40	60	100		
3	22ECM03	Electronic Circuits	OE	3	0	0	3	40	60	100		
4	22ECM04	Signal Processing	OE	3	0	0	3	40	60	100		
5	22ECM05	Fundamentals of Microprocessors and Microcontrollers	OE	3	0	0	3	40	60	100		
6	22ECM06	Analog and Digital Communication	OE	3	0	0	3	40	60	100		

7	22ECM07	Communication Networks	OE	3	0	0	3	40	60	100
8	22ECM08	Fundamentals of IoT	OE	3	0	0	3	40	60	100
9	22ECM09	Wireless sensors and networking	OE	3	0	0	3	40	60	100
10	22ECM10	Fundamentals of Embedded systems	OE	3	0	0	3	40	60	100
		ELECTRICAL AND ELECTR	ONICS	ENGI	NEER	RING				
1	22EEM01	Linear and Digital Electronics Circuits	OE	3	0	0	3	40	60	100
2	22EEM02	Microprocessors and Microcontrollers	OE	3	0	0	3	40	60	100
3	22EEM03	Control Systems	OE	3	0	0	3	40	60	100
4	22EEM04	Measurements and Instrumentation	OE	3	0	0	3	40	60	100
5	22EEM05	Electrical Machines	OE	3	0	0	3	40	60	100
6	22EEM06	Electric Drives and Control	OE	3	0	0	3	40	60	100
7	22EEM07	Electric Vehicles and Control	OE	3	0	0	3	40	60	100
8	22EEM08	Electrical Energy Conservation and Auditing	OE	3	0	0	3	40	60	100
9	22EEM09	SMPS and UPS	OE	3	0	0	3	40	60	100
10	22EEM10	Utilization of Electrical Energy	OE	3	0	0	3	40	60	100
		MECHANICAL EN	GINEE	RING						
1	22MEM01	Engineering Thermodynamics	OE	3	0	0	3	40	60	100
2	22MEM02	Fluid Mechanics and Machinery	OE	3	0	0	3	40	60	100
3	22MEM03	Manufacturing Processes	OE	3	0	0	3	40	60	100
4	22MEM04	Materials Engineering	OE	3	0	0	3	40	60	100
5	22MEM05	Kinematics of Machinery	OE	3	0	0	3	40	60	100
6	22MEM06	Hydraulics and Pneumatics	OE	3	0	0	3	40	60	100
7	22MEM07	Design of Machine Elements	OE	3	0	0	3	40	60	100
8	22MEM08	Heat and Mass Transfer	OE	3	0	0	3	40	60	100
9	22MEM09	Metrology and Quality Control	OE	3	0	0	3	40	60	100
10.	22MEM10	Dynamics of Machinery	OE	3	0	0	3	40	60	100
		METALLURGICAL	ENGIN	EEIN	G			_		

1	22MTM01	Advanced Physical Metallurgy	OE	3	0	0	3	40	60	100
2	22MTM02	Thermodynamics and Kinetics in Metallurgy	OE	3	0	0	3	40	60	100
3	22MTM03	Mechanical Behaviour of Materials	OE	3	0	0	3	40	60	100
4	22MTM04	Rate Processes in Metallurgy	OE	3	0	0	3	40	60	100
5	22MTM05	Corrosion and Surface Engineering	OE	3	0	0	3	40	60	100
6	22MTM06	Materials Characterization	OE	3	0	0	3	40	60	100
7	22MTM07	Automotive, Aerospace and Defence Materials	OE	3	0	0	3	40	60	100

COMPARISON WITH AICTE AND ANNA UNIVERSITY CREDITS

S.No	Category	Suggested Breakup of Credits (Total 160) by AICTE	Suggested Breakup of Credits (Total 167) by Anna University	Breakup of credits (Total 167) by GCE	Breakup of GCE credits in Percentage
1	Humanities and Social Sciences including Management courses	12	12	11.5	6.8%
2	Basic Science courses	29	25	22	13.2%
3	Engineering Science courses including workshop, drawing, basics of electrical/mechanical/ computer etc.	27	25 25.5		15.3%
4	Professional core courses	58	56	59	35.3%
5	Professional Elective courses relevant to chosen specialization/branch	9	21	18	10.8%
6	Open subjects – Electives from other technical and /or emerging subjects	9	12	12	7.2%
7	Project work, seminar and internship in industry or elsewhere	16	16	17	10.2%
8	Mandatory Courses [Environmental Sciences, Induction Program, Indian Constitution, Essence of Indian Knowledge Tradition]	(non-credit)	0	2	1.2%
	Total Credit	160	167	167	100%

SUMMARY FOR REGULAR STREAM

Course Component				Credits I	Per Seme	ester			Total
Course component	I	II	III	IV	V	VI	VII	VIII	Credit
Humanities and Social Sciences (HS)/HSMC	2	7			1.5		3		13.5
Engineering Science (ES)	11.5	6.5	4.5	3					25.5
Basic Science (BS)	11	8	3						22
Professional Core (PC)			12.5	17	19		10.5		59
Professional Electives (PE)						9	3	6	18
Open Electives (OE)						9		3	12
Empl. Enhancement Courses (EE)		1	1	1	1	3		10	17
	24.5	22.5	21	21	21.5	21	16.5	19	167

SYLLABUS

PROFESS	SIONAL	CORE C	COURSES

B.E MECHANICAL ENGINEERING - FULL TIME

REGULATION 2022 - SYLLABUS

SEMESTER-I

22MC101 INDUCTION PROGRAM					SEMESTER I			
PRE-REQU	PRE-REQUISITE Category N		IC Cred		edit	0		
	W/NV	I	,	T	P	TH		
	Hours/Wee)	0	0	0		

INDUCTION PROGRAM (MANDATORY) - 3 WEEKS DURATION

LIST OF EXPERIMENTS

- Physical activity.
- Creative Arts.
- Universal Human Values.
- Literary.
- Proficiency Modules.
- Lectures by Eminent People.
- Visits to local Areas.
- Familiarization to Dept./Branch & Innovations.

Total = 21Days

22M	A101	MATRICES, CALCULUS AND ORDINARY DIFFE EQUATIONS	RENTIAL	S	EMES	EMESTER I		
PRE	-REQU	ISITE:	Category	BS	Cre	dit	4	
	1.0th 1		TT /537 1	L	Т	P	TH	
Basic	: 12 th leve	l Matrices, Differential Calculus, Integral Calculus and ODE.	Hours/Week	3	1	0	4	
Cou	rse Obje	ectives:						
1.	To kno	w the use of matrix algebra needed by engineers for practical applica	tions.					
2.	2. To understand effectively both the limit definition and rules of differentiation.							
3.	To fam:	iliarize in solving maxima and minima problems in two variables.						
4.	To obta	in the knowledge of multiple integrations and their related application	ons.					
5.	5. To obtain the knowledge to solve second order differential equations with constant and variable coefficients							
U	nit I	MATRICES		9	3	0	12	
Ur Repre	formation it II esentation	DIFFERENTIAL CALCULUS of functions - Limit of a function - Continuity - Derivatives - Diffe		9	3	0	12	
	it III	FUNCTIONS OF SEVERAL VARIABLES	1	9	3	0	12	
Partia	al derivati	ives – Euler's theorem for homogenous functions – Total Derivative of of Lagrangian multipliers- Taylor's series.				_		
Un	it IV	MULTIPLE INTEGRALS		9	3	0	12	
		rals- Double integrals – Change of order of integration in double i cation to Areas – Evaluation of Triple integrals – Application to volu		e of var	iables	(Carte	sian to	
Uı	Unit V ORDINARY DIFFERENTIAL EQUATIONS 9 3 0 12							
Lege		linear differential equations with constant and variable coefficinear equation - Method of variation of parameters -Simultaneou	s first order linea	ar equa	tions w	vith c	onstant	
			Total ((45L +1	(5T) =	60 P	eriods	

Text	Books:						
1.	Grewal. B.S, "Higher Engineering Mathematics", 43 rd Edition, KhannaPublications, Delhi, 2015.						
2.	Jain R.K. and Iyengar S.R.K., "Advanced Engineering Mathematics", 3rd Edition, Narosa Publications, New Delhi, 2007.						
Reference Books:							
1.	James Stewart, "Essential Calculus", 2 nd Edition Cengage Learning, New Delhi, 2014.						
2.	P. Kandasamy, K. Thilagavathy and K. Gunavathy," Engineering Mathematics (For I year B.E., B. Tech)", 9 th Edition, S. Chand & Co. Ltd. New Delhi, 2010.						
3.	Srimanta pal and Subath.C. Bhumia, "Engineering Mathematics", Oxford university publications, New Delhi, 2015						
4.	Ewinkreyzig, "Advanced Engineering Mathematics", 9th edition, John Wiley & Sons, 2007.						
5.	Siva RamakrishnaDas.P, Ruknmangadachari.E. "Engineering Mathematics", 2 nd edition, Pearson, Chennai & Delhi, , 2013.						

	RSE OUTCOMES: completion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Learn the fundamental knowledge of Matrix theory.	Understand
CO2	Use both the limit definition and rules of differentiation to differentiable functions.	Apply
CO3	Apply differentiation to solve maxima and minima problems.	Apply
CO4	Apply integration to compute multiple integrals, area, volume, integrals in polar coordinates, in addition to a change of order and change of variables.	Apply
CO5	Apply various techniques in solving differential equations.	Apply

COU	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2		2									2		
CO2	3	2		2									2		
CO3	3	2		2									2		
CO4	3	2		2									2		
CO5	3	2		2									2		
Avg	3	2		2									2		
			3/2	/ 1 – in	dicates	strengt	h of cor	relatio	n (3 – H	ligh, 2 –	Medium	, 1 – Lov	v)		

22CY101	ENGINEERING CHEMISTRY			SEME	STER 1	[
PRE-REQ	UISITE:	Category	BS	Cr	edit	4
D . CI	• ,	TT /XX/ 1	L	Т	P	TH
Basic Chen	mstry	Hours/Week	3	1	0	4
Course Ob	jectives:				•	u.
1. Basic P	rinciples of Spectroscopy and their applications.					
2. Knowle	dge of different methods for water analysis and purification & N	Nanomaterial and its	applicat	ion.		
3. Various	adsorption technics and basic knowledge of Phase equilibria.					
4. Principl	es of electrochemistry, electrochemical cells, corrosion, and its	control.				
5. Basis of	polymer preparations and applications and enhancement of the	quantity and quality	of fuels	S.		
Unit I	SPECTROSCOPIC TECHNIQUES		9	3	0	12
instrumentat Flame photo	rt's law (problem) -UV visible spectroscopy: Principle, Chronon (No applications). IR spectroscopy: Principles -instrumentation estimation of sodium by flat strumentation -estimation of nickel by atomic absorption spectroscopy:	ion and applications ame photometer. Ato	of IR in	H ₂ O, ar	nd CO ₂ .	
Unit II	WATER TECHNOLOGY AND NANO TECH	NOLOGY	9	3	0	12
Nano chemis application.	ment – Ion exchange process, zeolite process – desalination of b try – preparations and properties of nanomaterials – nanorods – n	nanowires – nanotub	es – cart	oon nanc	ı	nd the
Unit III	SURFACE CHEMISTRY AND PHASE EQUI	ILIBRIA	9	3	0	12
Freundlich's	Types of adsorption – adsorption of gases on solids – adsorptio adsorption isotherm – Langmuir's adsorption isotherm. attroduction, definition of terms with examples, one component s			•		
	cooling curves – two component systems – lead-silver system –			r - F		
Unit IV	ELECTROCHEMISTRY		9	3	0	12
cell, Cell pot problems. El metal, nature	tential- Oxidation and Reduction Potentials - Electrochemical ser- ential, derivation of Nernst equation for single electrode potential ectrochemical theory of corrosion with respect to iron. Factors of the metal, area effect, over voltage, pH, temperature, and n ies; (i) Differential aeration corrosion- oxygen concentration	l, numerical problem influencing the corr ature of the corrosion	ns on E, osion ra on produ	E_0 , and lete: physict. Type	E _{cell} - nu ical state	merica of th
embrittlemer	at. Corrosion control by i) Cathodic protection- sacrificial an al coatings- galvanizing and tinning.			_	anation-	causti
embrittlemer	tt. Corrosion control by i) Cathodic protection- sacrificial an			_	anation-	causti
embrittlemer coatings-met Unit V Polymers – mechanism -	at. Corrosion control by i) Cathodic protection- sacrificial and coatings- galvanizing and tinning.	tion polymerization	9 - free conate, p	method 3 radical olyureth	anation-ls i) Pro O polymerane, nyl	12 rizatio
embrittlemer coatings-met Unit V Polymers – mechanism – PET – Rubbe Fuels - class and liquid fu	tt. Corrosion control by i) Cathodic protection- sacrificial and coatings- galvanizing and tinning. POLYMERS AND FUELS definition – polymerization – types – addition and condensate plastics, classification – preparation, properties and uses of PV	tion polymerization /C, Teflon, polycarb R – biopolymers – N LCV), and determind catalytic cracking	9 - free conate, p Nylon-2-ation of	3 radical olyureth Nylon-6 calorific	o polymerane, nylor and PH c value o	12 rizatio on-6,6 BV of solid
embrittlemer coatings-met Unit V Polymers – mechanism – PET – Rubbe Fuels - class and liquid fu	POLYMERS AND FUELS definition – polymerization – types – addition and condensal plastics, classification – preparation, properties and uses of PV er-vulcanization of rubber, synthetic rubbers – butyl rubber, SB fication with examples, calorific value-classification (HCV & less using Bomb calorimeter- Petroleum cracking -fluidized be	tion polymerization /C, Teflon, polycarb R – biopolymers – N LCV), and determind catalytic cracking led petrol.	9 - free conate, p Nylon-2-ation of	3 radical olyureth Nylon-6 calorific	opolymerane, nyles and PH	12 rizatio on-6,6 BV of soli
embrittlemer coatings-met Unit V Polymers – mechanism – PET – Rubbe Fuels - class and liquid fu	POLYMERS AND FUELS definition – polymerization – types – addition and condensal plastics, classification – preparation, properties and uses of PV er-vulcanization of rubber, synthetic rubbers – butyl rubber, SB fication with examples, calorific value-classification (HCV & less using Bomb calorimeter- Petroleum cracking -fluidized be revention of knocking. Anti-knocking agent: Leaded and unleaded	tion polymerization /C, Teflon, polycarb R – biopolymers – N LCV), and determind catalytic cracking led petrol.	9 - free conate, p Nylon-2-ation of . Knock	3 radical olyureth Nylon-6 calorific	opolymerane, nyles and PH	12 rizatio on-6,0 BV of soli
embrittlement coatings-met Unit V Polymers — mechanism — PET — Rubber Fuels - class and liquid fueffects and p	POLYMERS AND FUELS definition – polymerization – types – addition and condensal plastics, classification – preparation, properties and uses of PV er-vulcanization of rubber, synthetic rubbers – butyl rubber, SB fication with examples, calorific value-classification (HCV & less using Bomb calorimeter- Petroleum cracking -fluidized be revention of knocking. Anti-knocking agent: Leaded and unleaded	tion polymerization /C, Teflon, polycarb R – biopolymers – N LCV), and determind catalytic cracking led petrol.	9 - free conate, polylon-2-ation of . Knock	radical olyureth Nylon-6 calorificing in ICL+15T)	o polymerane, nyl and PH e value of engine = 60 P	12 rizatio on-6, BV of soli
Unit V Polymers – mechanism – PET – Rubbe Fuels - class and liquid fu effects and p Text Books 1. S. S. Da	POLYMERS AND FUELS definition – polymerization – types – addition and condensate plastics, classification – preparation, properties and uses of PV ervulcanization of rubber, synthetic rubbers – butyl rubber, SB fication with examples, calorific value-classification (HCV & less using Bomb calorimeter- Petroleum cracking -fluidized be revention of knocking. Anti-knocking agent: Leaded and unleaded.	tion polymerization /C, Teflon, polycarb R – biopolymers – N LCV), and determind catalytic cracking led petrol. To S. Chand & Compar	9 - free conate, p Nylon-2- ation of . Knock tal (45)	radical olyureth Nylon-6 calorific ing in ICL+15T)	o polymerane, nyl and PH e value of engine = 60 P	12 rization on -6, BV of solide, its in

Ref	ference Books:
1.	Friedrich Emich, —Engineering Chemistry Scientific International PVT, LTD, New Delhi, 2014.
2.	PrasantaRath, —Engineering Chemistry Cengage Learning India PVT, LTD, Delhi, 2015.
3.	ShikhaAgarwal, — Engineering Chemistry-Fundamentals and Applications Cambridge University Press, Delhi, 2015.
E-F	References:
1	www.onlinecourses.nptel.ac.in/
2	www.ePathshala.nic.in

	RSE OUTCOMES: completion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Recall the basic principles of spectroscopy and their applications	Remember
CO2	Paraphrase the different methods for water analysis & purification and Nanomaterial & its applications	Understand
CO3	Apply the various adsorption technics and basic knowledge of phase equilibria.	Apply
CO4	Integrate the principles of electrochemistry, electrochemical cells, corrosion, and its control	Create
CO5	Assess the basis of polymer preparations & applications and enhancement of the quantity & quality of fuels.	Evaluate

COURSE ARTICULATION MATRIX

COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3		3		0							3	1	1
CO2	3	2		1		2							3	1	1
CO3	3	1		1		0							2	1	1
CO4	2	1		1		2							2	3	2
CO5	3	2		3		2							1	1	1
Avg	2.8	1.8		1.8		2							2.2	1.4	1.2

3/2/1 – indicates strength of correlation (3-High, 2-Medium, 1-Low)

22E	E101	BASIC ELECTRICAL AND ELECTRONICS EN (Common to Civil Engineering, Mechanical Engineering)		\$	Semest	er	II
PRER	REQUIS	ITES	Category	ES Credit		edit	4
				L	T	P	ТН
			Hours/Week	3	1	0	4
Cours	se Learn	ing Objectives					
1	To unde	erstand and analyze basic electric circuits.					
2	To stud	y working principle of electrical machines and transformer.					
3	To stud	y basics of electronic devices and operational amplifier.					
4	To und	erstand the concepts of electrical installations.					
Ur	nit I	DC CIRCUITS		9	3	0	12
circuits		t elements (R, L and C) - Voltage and current sources - Ohmiss of simple electrical circuits with DC excitation using fundar eorems.					
Un	it II	AC CIRCUITS		9	3	0	12
Analys	sis of sing	ingle phase AC circuits - Representation of sinusoidal wavefor le-phase AC circuits consisting of RL, RC, RLC combinations and power factor. Three phase AC circuits, voltage and current	(series and parallel): real	power,	reactive	
Uni	it III	ELECTRICAL MACHINES AND TRANSFO	ORMERS	9	3	0	12
three-p	hase indu	struction, operation, types and applications, Speed control of action motors - Working of single-phase induction motor and it astruction and working, losses and efficiency in transformers, I	s applications – Tra	nsforn	ners: Ide	al and p	
Uni	it IV	BASICS OF ELECTRONICS SYSTEM	M	9	3	0	12
CB, C	C config	asic structure of semiconductors devices- PN junction diode, uration and working principle. Operational Amplifier-princifier, non inverting amplifier, summing amplifier and differentiations.	iple of operation, (
Un	it V	ELECTRICAL INSTALLATIONS		9	3	0	12
_		LT Switchgear: Switch Fuse Unit (SFU), MCB, ELCB, MCCI				_	
	_	tools and components, types of house wiring – Batteries: Prir	nciple characteristic	s-Type	es and it	s applic	cations -
Introdu	iction to	UPS and SMPS.	nn .	1 (457	. 1 500	- CO T	
			1 ota	ı (45 1	<u>+151</u>	= 60 1	Periods

Tex	tt Books:						
1	Muthu Subramaniyam, R., Salivaganan, R., and Muralidharan, K. A., "Basic Electrical and Electronics Engineering", Second Edition, Tata McGraw Hill, 2010.						
2	Kothari, D. P., and Nagrath, I. J., "Basic Electrical Engineering", Tata McGraw Hill, 2010.						
3	Kulshreshtha, D.C., "Basic Electrical Engineering", Tata McGraw Hill, 2009.						
Refe	rence Books:						
1	Bobrow, L. S., "Fundamentals of Electrical Engineering", Oxford University Press, 2011.						
2	Hughes, E., "Electrical and Electronics Technology", Pearson, 2010.						

	Course Outcomes: Upon completion of this course, the students will be able to:						
CO1	Analyze the DC circuits using fundamental laws and theorems.	Analyze					
CO2	Analyze the single and three phase AC circuits.	Analyze					
CO3	Recognize the working principle of electrical machines and transformers.	Understand					
CO4	Recognize the fundamentals and characteristics of diode, BJT and operational amplifier.	Understand					
CO5	Demonstrate the concept of electrical installations.	Apply					

					COUR	SE AI	RTICU	JLATI	ON M	ATRIX	<u> </u>			
COs\ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
CO1	1	1									1	1		
CO 2	1	1									1	1		
CO 3	1										1	1		
CO 4	1										1	1		
CO 5	1										1	1		
Avg	1	1									1	1		

3/2/1 – indicates strength of correlation (3- High, 2-Medium, 1-Low)

ZZIVII	E101	ENGINEERING GRAPHICS AND DES	SIGN		SEME	STER I			
PRE-	REQU	UISITE:	Category	ES	Cre	edit	3		
1. Stu	dents sl	nould know about the basics of drawings.	II/\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	L	T	P	TH		
2. Stud	dents sl	nould be able to construct geometric shapes.	Hours/Week	1	0	4	5		
Cour	se Obj	ectives:							
1.		part knowledge on graphical skills for communications of convide exposure to design.	ncepts, ideas and de	esign of e	engineeri	ng produ	cts and		
2.	To ex	pose them to existing national standards related to technical di	rawings.						
3.	To un	derstand the basics of points, lines, planes and solids.							
4.	To understand the basics of the surface of object.								
5.	To ex	xpose them to isometric and perspective views of simple solids.							
UNI	IT I	PROJECTION OF POINTS, LINES AND PLANE	E SURFACES	3	0	12	15		
		oth reference planes.							
_	ction of	PROJECTION OF SOLIDS simple solids like prisms, pyramids, cylinder and cone when to one reference plane by change of position method.	the axis is perpend	3 licular to	one refe	12 erence pla	15 ane and		
Projec	ction of					l			
Project also in UNIT	etion of nelined FIII oning of solids	simple solids like prisms, pyramids, cylinder and cone when to one reference plane by change of position method.	F SURFACES Inclined to one reference plane- Obtaining	icular to 3 rence platrue shap	one refe	12 perpendic section.	15 cular to		
Project also in UNIT	ction of aclined T III oning of solids opment	simple solids like prisms, pyramids, cylinder and cone when to one reference plane by change of position method. SECTION OF SOLIDS AND DEVELOPMENT Of above solids in a simple vertical position by cutting planes is inclined position with cutting planes parallel to one reference	F SURFACES Inclined to one reference plane- Obtaining wramids cylinders a	icular to 3 rence platrue shap	one refe	12 perpendic section.	15 cular to		
Project also in UNIT	r III oning of solids opment es of so	simple solids like prisms, pyramids, cylinder and cone when to one reference plane by change of position method. SECTION OF SOLIDS AND DEVELOPMENT Of above solids in a simple vertical position by cutting planes is inclined position with cutting planes parallel to one reference of lateral surfaces of simple and truncated solids – Prisms, py	F SURFACES nclined to one refe e plane- Obtaining yramids cylinders a axis.	icular to 3 rence platrue shap	one refe	12 perpendic section.	15 cular to		
Project also in UNIT Section other - Develor surface UNIT Orthogonal Control of the Control of t	r III oning of solids opmentes of so r IV graphic	simple solids like prisms, pyramids, cylinder and cone when to one reference plane by change of position method. SECTION OF SOLIDS AND DEVELOPMENT OF above solids in a simple vertical position by cutting planes is inclined position with cutting planes parallel to one reference of lateral surfaces of simple and truncated solids – Prisms, pyolids with square and cylindrical cutouts, perpendicular to the	F SURFACES Inclined to one reference plane- Obtaining varamids cylinders a axis. IECTION - Visualization prints	3 rence platrue shap nd cones 3 nciples -	one refe	12 perpendicus section. ppment of	15 cular to		
Project also in UNIT Section other - Develor surface UNIT Orthogodimen Princip	r III oning of solids opment es of so r IV graphic sional of	simple solids like prisms, pyramids, cylinder and cone when to one reference plane by change of position method. SECTION OF SOLIDS AND DEVELOPMENT OF above solids in a simple vertical position by cutting planes is inclined position with cutting planes parallel to one reference of lateral surfaces of simple and truncated solids – Prisms, pyralids with square and cylindrical cutouts, perpendicular to the ORTHOGRAPHIC AND ISOMETRIC PROJ	F SURFACES Inclined to one reference plane- Obtaining syramids cylinders a axis. IECTION - Visualization prinews from pictorial visualization.	3 rence platrue shap nd cones 3 nciples - views of	one refe	12 perpendic section. ppment of	15 cular to f lateral 15 f three-		
Project also in UNIT Section other - Develor surface UNIT Orthogodimen Princip cylind	r III oning of solids opment es of so r IV graphic sional of	simple solids like prisms, pyramids, cylinder and cone when to one reference plane by change of position method. SECTION OF SOLIDS AND DEVELOPMENT OF above solids in a simple vertical position by cutting planes is inclined position with cutting planes parallel to one reference of lateral surfaces of simple and truncated solids – Prisms, pyralids with square and cylindrical cutouts, perpendicular to the ORTHOGRAPHIC AND ISOMETRIC PROJECTION Projection - Visualization concepts and Freehand sketching objects - Layout of views - Freehand sketching of multiple views isometric projection – isometric scale - isometric projection	F SURFACES Inclined to one reference plane- Obtaining syramids cylinders a axis. IECTION - Visualization prinews from pictorial visualization.	3 rence platrue shap nd cones 3 nciples - views of	one refe	12 perpendic section. ppment of	15 cular to f lateral 15 f three-		
Project also in UNIT. Section other - Develor surface UNIT. Orthoodimen Principle cylind UNIT.	r III oning of solids opment es of so r IV graphic graphic sional of ples of lers and	simple solids like prisms, pyramids, cylinder and cone when to one reference plane by change of position method. SECTION OF SOLIDS AND DEVELOPMENT OF above solids in a simple vertical position by cutting planes is inclined position with cutting planes parallel to one reference of lateral surfaces of simple and truncated solids – Prisms, pyrolids with square and cylindrical cutouts, perpendicular to the ORTHOGRAPHIC AND ISOMETRIC PROJ. Projection - Visualization concepts and Freehand sketching objects - Layout of views - Freehand sketching of multiple views isometric projection – isometric scale - isometric projection.	F SURFACES Inclined to one reference plane- Obtaining syramids cylinders a axis. IECTION - Visualization printers from pictorial values of simple solitons of simple solitons.	3 rence platrue shap nd cones 3 nciples - views of ids, trund	one refe	12 perpendicus section. ppment of 12 ntation of isms, py	15 cular to f lateral 15 f three- ramids,		

Text	Books:
1.	Bhatt, N.D., Panchal V M and Pramod R. Ingle, "Engineering Drawing", Charotar Publishing House, 53rd Edition, 2014.
2.	Parthasarathy, N. S. and Vela Murali, "Engineering Drawing", Oxford University Press, 2015
Refe	rence Books:
1.	Agrawal, B. and Agrawal C.M., "Engineering Drawing", Tata McGraw, N.Delhi, 2008.
2.	Gopalakrishna, K. R., "Engineering Drawing", Subhas Stores, Bangalore, 2007.
3.	Natarajan, K. V., "A text book of Engineering Graphics", 28th Ed., Dhanalakshmi Publishers, Chennai, 2015.
4.	Shah, M. B., and Rana, B. C., "Engineering Drawing", Pearson, 2 nd Ed., 2009.
5.	Venugopal, K. and Prabhu Raja, V., "Engineering Graphics", New Age, 2008.
E-Re	eferences:

1.	https://nptel.ac.in/courses/112102304
2.	https://home.iitk.ac.in/~anupams/ME251/EDP.pdf
3.	https://static.sdcpublications.com/pdfsample/978-1-58503-610-3-1.pdf

COUF Upon c	Bloom's Taxonomy Mapped	
CO1	Ability to understand the fundamental concepts of projection of points, lines and planes.	Understand
CO2	Ability to project the different views of solids with various positions.	Understand
СОЗ	Ability to section the solids with various positions and develop the lateral surfaces of solids.	Analyze
CO4	Familiarize to convert the isometric projection into orthographic projection of simple solids and vice versa.	Apply
CO5	Visualize and project the perspective sections of simple solids.	Analyze

COU	COURSE ARTICULATION MATRIX														
CO/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1											3	1	
CO2	3	1											3	1	
CO3	3	1											3	1	
CO4	3	1											3	1	
CO5	3	1											3	1	
Avg	3	1											3	1	
			3/2	/ 1 – inc	dicates	strengt	h of cor	relatio	n (3 – H	ligh, 2 –	Medium	, 1 – Lov	w)		

22CS1	01 PROBLEM SOLVING AND C PROGR	RAMMING		SEME	STER I	
PRE-R	REQUISITE	Category	ES	Cro	edit	3
		TT /55/ 1	L	T	P	C
		Hours/Week	3 0		0	3
Course	e Objectives:	·				
1. T	To use general problem-solving techniques to device solutions	to problems				
,	Γο understand the input-output relations of software involved in code.	developing and converting	ng a C pr	ogram t	o an exec	cutable
3. T	To provide complete knowledge about the programming concept	pts of C language.	1		1	
UNIT	SYSTEM SOFTWARE, PROBLEM SOL PROGRAMMING	VING AND C	9	0	0	9
Loader,	vel programming language – Machine level language – role of and Operating System) in developing and executing a C progr	ram				
Variable	ramming: Character set – Case sensitivity – Identifiers – Keyes and their associated information – Formed and unformed ors – Precedence and Associativity – Pre-processor directives (d console input-output st	atements	s – Typ	e conve	
	problem-solving Techniques: Algorithm – Flow-chart – Pse erators and writing their equivalent C programs.	eudocode – Developing s	solution 1	for prob	lems inv	olving
only ope	erators and writing their equivalent C programs. CONTROL STATEMENTS	8	9	0	0	9
UNIT General statement Pseudoc C prograwhile lo Develop	CONTROL STATEMENTS I problem-solving Techniques: Representing Decision making int: for loop, while loop and do-while loop – Branching statement code ramming: Decision Making: if-else statement – switch case state pop – Branching statements: break and continue – Nesting ping solutions for problems involving control statements using the same problems in the sa	g: if-else statement – sw ents: break and continue v tement - Looping stateme	9 vitch-cas with Algo	0 e statem prithm, I	0 nent – L Flow-cha	9 ooping art, and
UNIT General statement Pseudoc C prograwhile lo Develop C program	CONTROL STATEMENTS I problem-solving Techniques: Representing Decision making int: for loop, while loop and do-while loop – Branching statemed code ramming: Decision Making: if-else statement – switch case state pop – Branching statements: break and continue – Nesting ping solutions for problems involving control statements using the same statements.	g: if-else statement – swents: break and continue wetenent - Looping statement - General problem-solving	9 vitch-cas with Algo	0 e statem prithm, I	0 nent – L Flow-cha	9 ooping art, and
UNIT General statement Pseudoc C prograwhile lo Develop	CONTROL STATEMENTS I problem-solving Techniques: Representing Decision making int: for loop, while loop and do-while loop – Branching statemed code ramming: Decision Making: if-else statement – switch case state pop – Branching statements: break and continue – Nesting ping solutions for problems involving control statements using the same statements.	g: if-else statement – swents: break and continue wetenent - Looping statement - General problem-solving	9 vitch-cas with Algo	0 e statem prithm, I	0 nent – L Flow-cha	9 ooping art, and
only ope UNIT General statement Pseudoct C prograwhile lost Develop C progra UNIT One-din Processi Develop	CONTROL STATEMENTS I problem-solving Techniques: Representing Decision making int: for loop, while loop and do-while loop – Branching statemed code ramming: Decision Making: if-else statement – switch case state pop – Branching statements: break and continue – Nesting ping solutions for problems involving control statements using the same statements.	g: if-else statement – swents: break and continue vents: break and con	yitch-cas with Algo ent: for lo g technique general port for s	op, white the poop of the poop	ent – L Flow-cha lle loop a their equ Initializ	9 cooping and do- ivalen 9 cation
only ope UNIT General statement Pseudoct C prograwhile lost Develop C progra UNIT One-din Processi Develop	CONTROL STATEMENTS Problem-solving Techniques: Representing Decision making int: for loop, while loop and do-while loop – Branching statement code Tamming: Decision Making: if-else statement – switch case state pop – Branching statements: break and continue – Nesting ping solutions for problems involving control statements using the same statements. ARRAYS, POINTERS, AND STR mensional and two-dimensional Arrays: Declaration – Initializating – relation between pointers and arrays – Strings – String of ping solutions for problems involving arrays, pointers and stringent C programs.	g: if-else statement – swents: break and continue vents: break and con	yitch-cas with Algo ent: for lo g technique general port for s	op, white the poop of the poop	ent – L Flow-cha lle loop a their equ Initializ	9 oopingart, and do ivalen 9
only ope UNIT General statement Pseudoco C prograwhile loo Develop C prograwhile loo Develop C prograwhile loo Develop C prograwhile loo Develop C processing Develop Equivaled UNIT of the processing Processi	CONTROL STATEMENTS I problem-solving Techniques: Representing Decision making nt: for loop, while loop and do-while loop – Branching statement code camming: Decision Making: if-else statement – switch case state pop – Branching statements: break and continue – Nesting ping solutions for problems involving control statements using the same statements. ARRAYS, POINTERS, AND STR mensional and two-dimensional Arrays: Declaration – Initializating – relation between pointers and arrays – Strings – String of ping solutions for problems involving arrays, pointers and string ent C programs. IV FUNCTIONS In – Library functions and user-defined functions – Function prisms – Recursion – Storage classes – Working with multiple solutions solutions for problems involving functions using General ping solut	g: if-else statement – swents: break and continue vents: break and con	yitch-cas with Algo ent: for lo g technique gents:Decl port for s m-solvin gents:Decl	o e statem orithm, I coop, whi ues and t o aration tring har g Techn o ns – Par	onent – L Flow-cha le loop a their equ Initialize Indling Iniques an orameter p	9 cooping and do- ivalen gation ad their
only ope UNIT General statement Pseudoct C prograwhile loo Develop C prograwhile loo Develop C prograwhile loo Develop C prograwhile loo Develop Equivaled UNIT Function mechanic Develop Develop C prograwhile LONIT Function mechanic Develop Develop C prograwhile LONIT Function mechanic D progra	CONTROL STATEMENTS I problem-solving Techniques: Representing Decision making nt: for loop, while loop and do-while loop – Branching statemed code code comming: Decision Making: if-else statement – switch case state pop – Branching statements: break and continue – Nesting ping solutions for problems involving control statements using the mensional and two-dimensional Arrays: Declaration – Initializating – relation between pointers and arrays – Strings – String oping solutions for problems involving arrays, pointers and string ent C programs. IV FUNCTIONS n – Library functions and user-defined functions – Function places of the ping solutions for problems involving functions using Generals.	g: if-else statement – swents: break and continue vents: break and con	yitch-cas with Algo ent: for lo g technique gents:Decl port for s m-solvin gents:Decl	o e statem orithm, I coop, whi ues and t o aration tring har g Techn o ns – Par	onent – L Flow-cha le loop a their equ Initialize Indling Iniques an orameter p	9 cooping and do- ivalen gation ad their

Text	t Books:
1.	Balagurusamy E, "Programming in ANSI C", Tata McGraw-Hill, 8th Edition, 2022.
2.	Yashvant P. Kanetkar, "Let Us C", BPB Publications, 2016.
Refe	erence Books:
1.	Venugopal, "Mastering C", Second Edition", Tata McGraw-Hill. 2006
2.	R. G. Dromey, "How to solve it by computers", Prentice Hall, 2007
3.	Greg Perry and Dean Miller, "C Programming Absolute Beginner's Guide", Third Edition, Que Publishing, 20123
4.	Brain W.Kernighan and Ritchie Dennis, "The C Programming Language", Second Edition, Pearson, 1988.
E- R	Reference:
1.	https://www.learn-c.org/
2.	https://www.programiz.com/c-programming

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:					
CO1	Explain the concepts of C Programming and roles of system software in programming	Remember & Understand				
CO2	Use general problem-solving techniques to develop solution to problems	Apply				
СОЗ	Apply the concepts of C Programming to develop solutions by writing C programs	Apply & Analyze				

COURSE ARTICULATION MATRIX COs/ PO1 PO2 PO3 **PO4 PO5** PO9 **PO10 PO11 PO12** PSO1 PSO₂ **PO6** PO7 **PO8** PSO3 **POs** CO1 3 2 2 2 2 2 3 2 2 CO₂ 2 2 1 CO3 3 3 2 2 2 2 2 1 1 3 3 2 2 2 Avg 1 $3\,/\,2\,/\,1-indicates$ strength of correlation (3-High,2-Medium,1-Low)

22MC102	தமிழர் மரபு B.E (Common to all Branche	es)		Semest	er I			
முன்நிபந்தனைகள்:	(Category	HSMC	Cre	edit	1		
இலக்கணம் மற்றும் இ	இலக்கியத்தின் அடிப்படைகள்		L	T	P	TH		
		Hours/Week	1	0	0	1		
பாடநெறி நோக்கங்க	ள்: மாணவர்களால்							
1. தமிழ் மொழி மற்	ற்றும் இலக்கியம் பற்றிய அறிவைப் பெற முடியும்.	•						
2. பாரம்பரியம், பா முடியும்	றை ஒவியங்கள் முதல் நவீன ஒவியங்கள் மற்றுட	ம் சிற்பக் கலைகள்	பற்றி தெ	ரிந்து செ	ிகாள்	ា		
3. நாட்டுப்புறக் கஎ	லைகள் மற்றும் வீர விளையாட்டுகள் பற்றி அறிந்	து கொள்ள முடியுப்	Ò					
4. தமிழர்களின் ஒ	ழுக்க நெறிமுறைகளைப் பற்றி தெரிந்து கொண்	டு அதன்படி நடந்த	ு கொள்	ய மிச்ர	ும்.			
h 0 00	<u> </u>	, , ,	களின் ப	ங்களிப்	பு பற்	றியும்		
ு நன்கு அறிந்து கொள்ள முடியும். அலகு I மொழி மற்றும் இலக்கியம் 3 0								
சமண பௌத்த ச சிற்றிலக்கியங்கள	நிருக்குறளில் மேலாண்மைக் கருத்துக்கல மயங்களின் தாக்கம் – பக்தி இலக்கியம் ள் – தமிழில் நவீன இலக்கியத்தின் வஎ ம் பாரதிதாசன் ஆகியோரின் பங்களிப்பு	, ஆழ்வார்கள் ம! ார்ச்சி – தமிழ் இ _! .	ற்றும் ந இலக்கிட	ாய்ன்	_ மார்	கள் –		
அலகு II	மரபு – பாறைஓவியங்கள்முதல்ந வரைசிற்பக்ககை	~	iπ	3	0 0	3		
தயாரிக்கும் கை – நாட்டுப்புறத்	வீன சிற்பங்கள் வரை – ஐம்பொன் வினைப்பொருட்கள்,பொம்மைகள் – தே தெய்வங்கள்- குமரி முனையில் திருவ p, வீணை, யாழ், நாதஸ்வரம் – தமிழர் ங்கு.	ர் செய்யும் கலை ள்ளுவர் சிலை-	– சுடும இசை	ண் சி க் கர	ற்பா நவிக	பகள் ள் –		
அலகு III	நாட்டுப்புறக்கலைகள்மற்றும்வீர	விளையாட்டுக	ां	3	0 0	3		
	காட்டம், வில்லுப்பாட்டு, கணியான்கூத் ாரி, புலியாட்டம், தமிழர்களின்விளையா	_ •	தோல்	பாை	பக்க	த்து,		
அலகு IV	தமிழர்களின் திணைக்கோ	ட்பாடுகள்		3	0 0	3		
அகம் மற்றும் புர தமிழகத்தில் எடு	வரங்களும், விலங்குகளும் – தொல்கா றக்கோட்பாடுகள் – தமிழர்கள் போற்றி தத்தறிவும், கல்வியும் – சங்ககால ற்றுமதி மற்றும் இறக்குமதி – கடல் கடந்	lய அறக்கோட்ட நகரங்களும் <i>த</i>	பாடு <i>– எ</i> புறை	சங்கச முகங்	ாலத் களு	தில் ம் –		
அலகு V	இந்தியதேசியஇயக்கம்மற்றும்இந்தி மிழர்களின்பங்களி		தத் த	3	0 0	3		
தமிழ்ப்பண்பாட்டி	லைப் போரில் தமிழர்களின் பங்கு 4ன் தாக்கம் – சுயமரியாதை இயக்க பங்கு – கல்வெட்டுகள், கையெழுத்துப்ட	கம் – இந்திய	மருத்து		လ်, 8	சித்த		
			ŗ.	Fotal=	15 Pe	riods		

Tex	at Books:
1	தமிழக வரலாறு - மக்களும் பண்பாடும் - கே.கே. பிள்ளை (வெளியீடு: தமிழ்நாடு பாடநூல் மற்றும் கல்வியல் பணிகள் கழகம்)
2	கணினித் தமிழ் - முனைவா் இல.சுந்தரம் (விகடன் பிரசுரம்)
3	கீழ்டி - வைகை நதிக்கரையில் சங்ககால நகர நாகரிகம் (தொல்லியல் துறை வெளியீடு)
4	பொருநை - ஆற்றங்கரை நாகரிகம். (தொல்லியல் துறை வெளியீடு)

பாடநெ	றி முடிவுகள்: இந்தப் படிப்பு முடி <u>ந்தது</u> ம், மாணவர்களால்	Bloom's Taxonomy Mapped		
CO1	இந்திய மொழிகள், இந்திய மொழிக் குடும்பங்கள் பற்றியும் மற்றும் இலக்கியம், இலக்கியதின் வளர்ச்சி, தமிழ் இலக்கிய வளர்ச்சியில் பாரதியார் மற்றும் பாரதிதாசன் ஆகியோரின் பங்களிப்புகளை பற்றியும் அறிந்து கொண்டனர்.	Understanding		
CO2	சிற்பக் கலைகளில் அடங்கியுள்ள பாறை ஒவியங்கள் முதல் நவின ஒவியங்கள் வரை பற்றியும், தமிழர்களின் சமூக, பொருளாதார வாழ்வில் கோவில்களின் பங்கினை பற்றியும் தெரிந்து கொண்டனர்.	Understanding		
CO3	தமிழா்களின் வாழ்வியல் முறைகளோடு ஒன்றிய நாட்டுபுறக் கலைகள் மற்றும் தமிழா்களின் வீர விளையாட்டுகளை பற்றி அறிந்து கொண்டனா்.	Understanding		
CO4	சங்ககாலத்தில் தமிழா்கள் பின்பற்றிய தினைக் கோட்பாடுகள் பற்றி நடந்து கொண்டனர்.	Applying		
CO5	இந்திய தேசிய இயக்கம் மற்றும் இந்திய பண்பாட்டிற்க்குத் தமிழர்களின் பங்கினை பற்றியும் அறிந்து கொண்டனர்.	Understanding		

COURSE ARTICULATION MATRIX															
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1			3			2				1			2		
CO2			3			2				1			2		
CO3			3			2				1			2		
CO4			3			2				1			2		
CO5			3			2				1			2		
Avg			3			2				1			2		

3 / 2 /1 - indicates strength of correlation (3- High, 2- Medium, 1- Low)

22M	IC102	HERITAGE OF TAMILS		S	emeste	er	I	
PREF	REQUIS	ITES	Category	HS MC	Citu		1	
Basic	s of Tam	il Language and Literature		L T				
			Hours/Week	1	0	0	1	
1.	To obta	in the knowledge of Tamil Language and Literature						
2.	To fami	liarize with painting and Sculpture						
3.	To know	w about the folks and martial arts						
4.	To unde	erstand the Thinai concept of Tamils						
5.	To know	w about the contribution of Tamils to Indian National Mo	ovement and Indi	an Cult	ure.			
Uı	nit I	LANGUAGE AND LITERATURE		3	0	0	3	
and In	npact of I	m Literature – Distributive Justice in Sangam Literature - Ma Buddhism & Jainism in Tamil Land - Bakthi Literature Azh Modern literature in Tamil - Contribution of Bharathiyar and	wars and Nayanm Bharathidhasan.	ars - Fo	orms of	minor l	Poetry -	
Un	nit II	HERITAGE - ROCK ART PAINTINGS TO MOI SCULPTURE	DERN ART –	3	0	0	3	
sculptu	ures, Villa	odern sculpture - Bronze icons - Tribes and their handicrafts - ge deities, Thiruvalluvar Statue at Kanyakumari, Making of naswaram - Role of Temples in Social and Economic Life of Ta	nusical instruments	_				
Un	it III	FOLK AND MARTIAL ARTS		3	0	0	3	
	koothu, Ka	aragattam, VilluPattu, KaniyanKoothu, Oyillattam, Leather pu amils.	ippetry, Silambatta	m, Vala	ri, Tige	r dance	- Sports	
Un	it IV	THINAI CONCEPT OF TAMILS		3	0	0	3	
- Educ	ation and	of Tamils & Aham and Puram Concept from Tholkappiyam a Literacy during Sangam Age - Ancient Cities and Ports of San quest of Cholas.	•			-		
Un	nit V	CONTRIBUTION OF TAMILS TO INDIAN N MOVEMENT AND INDIAN CULTUR		3	0	0	3	
	ment - Rol	Tamils to Indian Freedom Struggle - The Cultural Influence of e of Siddha Medicine in Indigenous Systems of Medicine – In		_			_	
					Total	l = 15 F	eriods	

Tex	t Books:
1	Social Life of Tamils (Dr.K.K.Pillay) A joint publication of TNTB & ESC and RMRL – (in print)
2	Social Life of the Tamils - The Classical Period (Dr.S.Singaravelu) (Published by: International Institute of Tamil Studies.
3	Historical Heritage of the Tamils (Dr.S.V.Subatamanian, Dr.K.D. Thirunavukkarasu) (Published by: International Institute of Tamil Studies).
4	The Contributions of the Tamils to Indian Culture (Dr.M.Valarmathi) (Published by: International Institute of Tamil Studies)
5	Keeladi - 'Sangam City Civilization on the banks of river Vaigai' (Jointly Published by: Department of Archaeology & Tamil Nadu Text Book and Educational Services Corporation, Tamil Nadu)
6	Studies in the History of India with Special Reference to Tamil Nadu (Dr.K.K.Pillay) (Published by: The Author)
7	Porunai Civilization (Jointly Published by: Department of Archaeology & Tamil Nadu Text Book and Educational Services Corporation, Tamil Nadu)
8	Journey of Civilization Indus to Vaigai (R.Balakrishnan) (Published by: RMRL)

	SE OUTCOMES:	Bloom's Taxonomy
Upon c	completion of this course, the students will be able to:	Mapped
CO1	Learn the knowledge of Tamil Language and Literature	Understanding
CO2	Familiarize about painting and Sculpture	Understanding
CO3	Acquire the knowledge about folks and Martial arts	Understanding
CO4	Learn the knowledge of Thinai concepts of Tamils	Applying
CO5	Acquire the knowledge about contribution of Tamils to Indian national movement and Indian culture	Understanding

	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1			3			2				1			2		
CO2			3			2				1			2		
CO3			3			2				1			2		
CO4			3			2				1			2		
CO5			3			2				1			2		
Avg			3			2				1			2		

3 / 2 /1 - indicates strength of correlation (3- High, 2- Medium, 1- Low)

22EN102	PROFESSIONAL SKILLS LABORATO	ORY	;	STER 1	[
PRE-REQU	UISITE	Category	HS	Cr	edit	1
Basic langua	age skills listening, speaking, reading and writing	Hours/Week	L 0	T 0	P 2	TH 2
Course Obj	jectives:				ı	
1. To ena	able learners to improve their reading skills					
2. To ma	ke learners show variations while reading					
3. To ass	ist learners to acquire speaking competency in English					
4. To ena	able learners to strengthen their fluency in speaking					
UNIT I	NARRATION		0	0	6	6
C	eading a short story – learning pronunciation, intonation, and sparrating a story without any help of handouts.	plitting of sentences	to form	meanin	gful uni	ts.
UNIT II	PRESENTATION		0	0	6	6
the poem.	eading a poem – learning the skill of reciting, appreciate rhynower-point presentation on a general topic.	ne and music, chang	ge in tone	e as per	the emo	otion of
UNIT III	SHORT SPEECH		0	0	6	6
Reading – Re	ading newspaper article – learning vocabulary and language p	attern of official con	mmunica	ation.	J	
Speaking - O	ral presentation on a topic from basic engineering pertained to	their branch.	1		1	1
UNIT IV	ORGANIZING EVENTS		0	0	6	6
_	eading dialogue scripts – learning expression, tone, stress and corposing welcome address, vote of thanks and organizing even		Ţ .			
UNIT V	DESCRIBING PROCESS		0	0	6	6
Speaking – I	eading technical descriptions of gadgets – learning the different Describing a process – everyday technical activities like takin Il for meetings etc.,	_	sing equ	ipment	for a co	mpany,
			Total	(30P)	= 30 P	eriods
Text Books						
1. Norma 2014.	an Whitby. Business Benchmark – Pre-Intermediate to Intermediate	ediate, Students boo	k, Camb	ridge U	niversity	Press,
Reference I	Books:					
	ng Fluency. Switzerland, MDPI AG, 2021.					
	cobs, Wade. Dare to Read: Improving Your Reading Speed and A. J. Effortless English: Learn to Speak English Like a Native					1.4
3. Hoge,	A. J. Enforcess English: Learn to Speak English Like a Native	e. Office States, Eff	orness E	ngusn L	LC, 201	14.
E-Reference	es:					
	/www.talkenglish.com/					
2. https:/	/www.readingrockets.org/					

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:							
CO1	Read passages fluently with good pronunciation	Remember						
CO2	Develop an expressive style of reading	Create						
CO3	Make effective oral presentations in technical and general contexts	Create						
CO4	Excel at professional oral communication	Evaluate						

	COL	JRSE A	ARTIC	CULAT	TON N	MATR	<u>IX</u>								
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1				1					2	3		1			1
CO2				1					2	3		1			1
CO3				2					2	3		1			1
CO4				2					2	3		1			3
Avg				1.5					2	3		1			1.5
	3 / 2 / 1 – indicates strength of correlation (3 – High, 2 – Medium, 1 – Low)														

22PH103	PHYSICS LABORATORY	SEMESTER I					
PRE-REQ	UISITE	Category	BS	Cro	edit	1.5	
Basic theo	rietical knowledge in Physics	House /Wools	L	T	P	TH	
		Hours/Week	0	0	3	3	

Course Objectives:

- 1. To handle different measuring instruments.
- 2. To understand the basic concepts of interference, diffraction, heat conduction and to measure the important parameters.

LIST OF EXPERIMENTS

- 1. Newton's rings Determination of radius of curvature of a Plano convex lens.
- 2. Carey Foster's bridge Determination of specific resistance of the material.
- 3. Poiseuille's flow Determination of the Coefficient of viscosity of a liquid.
- 4. Spectrometer Grating Normal incidence Determination of Wavelength of Mercury lines.
- 5. Lee's disc Determination of thermal conductivity of a Bad conductor.
- 6. Ultrasonic interferometer Determination of velocity of Ultrasonic Waves in Liquid.
- 7. Non-uniform bending Determination of young's modulus of the wooden bar.
- 8. Determination of Band gap of a given semiconductor.
- 9. Determination of Wavelength of laser using grating and determination of particle size using Laser.
- 10. Determination of Acceptance angle and Numerical Aperture of fiber.

Total (45P) = 45 Periods

Text Books:

- 1. C. S. Robinson, Dr. Ruby Das, 'A Textbook of Engineering Physics Practical', Laxmi Publication Pvt. Ltd., 2016.
- 2. S. Panigrahi, 'Engineering Practical Physics', Cengage Learning India, 2015.

Reference Books:

- 1. M.N. Srinivasan, 'Text Book of Practical Physics', Sultan Chand & Sons, 2013
- 2. Singh Harman, 'B.Sc. Practical Physics', S Chand & Company Ltd, 2022.

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:						
CO1	Handle different measuring instruments and to measure different parameters.	Apply					
CO2	Calculate the important parameters and to arrive at the final result based on the experimental measurements.	Analyze					

COURS	COURSE ARTICULATION MATRIX														
CO/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2		3	3				3	1		2	1	1	1
CO2	3	2		2	1				2	0		1	1	1	1
Avg	3	2		2.5	2				2.5	0.5		1.5	1	1	1
	3/2/1 – indicates strength of correlation (3 – High, 2 – Medium, 1 – Low)														

22CY102	22CY102 CHEMISTRY LABORATORY							
PRE-REQU	ISITE	Category	BS	Cre	dit	1.5		
	Y /X /				P	TH		
		Hours/Week	0	0	3	3		

Course Objectives:

. To gain practical knowledge by applying theoretical principles and performing the following experiments.

LIST OF EXPERIMENTS

- 1. Estimation of hardness of Water by EDTA
- 2. Estimation of Copper in brass by EDTA
- 3. Estimation of Alkalinity in water
- 4. Estimation of Chloride in water sample (Iodimetry)
- 5. Estimation of Iron content in the given salt by using external indicator
- 6. Conductometric titration of Strong Acid and Strong Base
- 7. Conductometric titration of Mixture of acids and Strong base
- 8. Determination of strength of Iron by Potentiometric method
- 9. Estimation of Iron by Spectrophotometry
- 10. Estimation of Copper by Colorimeter
- 11. Determination of molecular weight and degree of Polymerization by Viscometry
- 12. Determination of pKa of the given weak acid by pH meter
- 13. Estimation of the amount of given HCl using pH meter

Total (45P) = 45 Periods

E-References:

1.	www.scuolab.com/en/chemistry/

2. <u>www.onlinelabs.in/chemistry</u>

3. www.virtuallabs.merlot.org/vl chemistry

	RSE OUTCOMES: completion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Summarize the applicability of the practical skill gained in various fields.	Understand
CO2	Calculate the composition of brass quantitatively and the molecular weight of polymers.	Apply
соз	Understand the principle and applications of conductometric and ph titrations, spectrometer, and potentiometric titrations.	Understand

COU	RSE A	RTICU	JLATI	ON M	ATRI	<u>X</u>									
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	1	0	3									2		
CO2	1	2	0	3									2		
CO3	2	2	0	3									2		
Avg	1.3	1.7	0	3									2		
						_	_								

3/2/1 – indicates strength of correlation (3 - High, 2 - Medium, 1 - Low)

22EE102	BASIC ELECTRICAL AND ELECTRONICS EN LABORATORY	GINEERING		SEME	STER I	[
PRE-REQ	UISITE	Category	ES	1.5		
		House/Wools	L	T	P	TH
		Hours/Week	0	3		

Course Objectives:

1. To impart hands on experience in use of measuring instruments, testing in transformers, and house wiring practices

LIST OF EXPERIMENTS

- 1. Verification of Kirchhoff's laws.
- 2. Verification of Superposition theorem.
- 3. Measurement of three-phase power in three-phase circuits.
- 4. Determination losses in single phase Transformer.
- 5. Demonstration of cut-out sections of machines: induction machine (squirrel cage rotor), and single-phase induction motor.
- 6. Speed control of DC shunt motor.
- 7. Study of basic safety precautions, measuring instruments voltmeter, ammeter, multi-meter, and Electrical components.
- 8. VI Characteristics of PN Junction diode.
- 9. Staircase wiring.
- 10. Wiring for fluorescent lamp.

Total (45P) = 45 Periods

	SE OUTCOMES: mpletion of the course, the students will be able to:	Bloom's Taxonomy Mapped						
CO1	Analyse DC and AC circuits.	Analyze						
CO2	CO2 Calculate various losses in transformer.							
CO3	Recognise the parts of single-phase and three phase induction motors.	Understand						
CO4	Demonstrate the characteristics of electron devices.	Understand						
CO5	Practice electrical connections by wires of appropriate ratings.	Apply						

COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	1									1	1			
CO2	1	1									1	1			
CO3	1										1	1			
CO4	1										1	1			
CO5	1										1	1			
Avg	1	1									1	1			

3/2/1 – indicates strength of correlation (3 - High, 2 - Medium, 1 - Low)

22EN	N101	COMMUNICATIVE ENGLIS	SH		SEMESTER II			
PRE	-REQU	ISITE	Category	HS Credit 3				
D'.	1	and the Proceedings of the conditions	II / XX 1-	L	T	P	TH	
Basic	language	e skills listening, speaking, reading and writing	Hours/Week	2	0	2	4	
Cour	rse Obje	ectives:	•					
1.	To deve	elop the communicative skills of learners by engaging the	m in reading, writing a	nd gramn	nar learn	ing acti	vities	
2.	To incu	lcate learners' ability to read texts, summaries, articles an	d user manuals					
3.	To assis	st learners to acquire writing skills for academic, social an	nd professional purpose	s				
4.	To impi	rove learners' vocabulary and grammar to supplement the	ir language use at diffe	rent cont	exts			
UN	ITI	COMPREHENSION		6	0	6	12	
Lister	_	nterview with personal assistant, an interview with a bunensions of products.	usiness consultant, des	cribing c	hanges	in a co	mpany	

Writing – Dialogue writing in a business context.

Grammar - Parts of speech, Tenses, Voices, Common errors in English, Subject-Verb agreement, Noun-Pronoun agreement, Prepositions and Articles.

UNIT II RECOMMENDATION 6 0 6 12

Listening – An interview about a production process, Telephone conversations, Making and changing appointments, Description of how a product is advertised.

Speaking - Personal interview, dress code, body language, required skills, corporate culture and mock interview.

Reading - Reading technical texts from journals, newspapers and technical blogs.

Writing - Writing checklists, Recommendations.

Grammar - Prefix and suffix, Synonyms, Antonyms, Verb forms - Auxiliary verbs, Modal verbs, Phrasal verbs, Pronouns, Adverbs and Adjectives.

UNIT III CONVERSATION 6 0 6 12

Listening - Conversation between two employees, Interview about change in job and corporate gift giving, Creating good teams: a presentation.

Speaking - Role play - examiner and candidate, customer and sales manager, team leader and team member, interviewer and applicant, industrialist and candidate.

Reading - Reading advertisements, gadget reviews, user manuals.

Writing - Providing instruction, Writing E-mails - Attending workshops, Paper submission for seminars and conferences, Arranging and cancelling a meeting.

Grammar - Conditional statements, Redundancies, Collocations and Meanings of individual words.

UNIT IV REPORTING 6 0 6 12

Listening – Working in an international team, Statistical information, Interview with investor relations, Radio interviews.

Speaking – Giving a speech, describing given data, discussing company information, Summarizing an article.

Reading - Reading longer technical texts, cause and effect essays, newspaper articles, company profiles.

Writing - Essay writing on social topics, Technical Report Writing - Status reports on projects, Feasibility reports and event reports on seminars, conferences, meeting.

Grammar - Compound words, Conjunctions, Sentence completion, Negation in statements and questions.

UNIT V INTERPRETATION 6 0 6 12

Listening – An interview with career advisor and recruitment agent, Feedbacks, Meeting extracts.

Speaking – Qualities required for employability, Improving employee productivity, presentation on problem-solving skills, teamwork, creativity and leadership quality.

 $Reading\ -\ Reading\ brochures,\ telephone\ messages,\ and\ social\ media\ messages\ relevant\ to\ technical\ contexts.$

Writing - Letter Writing - Formal Letters and Informal Letters - cover letter with resume, Mind maps, Charts - interpreting statistical data, charts, graphs and tables.

Grammar - One word substitution, Abbreviations and acronyms in technical contexts and technical vocabulary, Idioms.

Total (30L + 30P) = 60 Periods

Refe	erence Books:
1.	Meenakshi Raman and Sangeeta Sharma. Professional English. Oxford University Press, New Delhi, 2019.
2.	Krishna Mohan, MeeraBannerji. Developing Communication Skills. Macmillan India Ltd, Delhi, 1990.
3.	Sanjay Kumar, PushpaLata. English Language and Communication Skills for Engineers. Oxford University Press, 2018.
E-Re	eferences:
1.	https://learnenglish.britishcouncil.org/
2.	https://www.bbc.co.uk/learningenglish

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:							
CO1	Understand							
CO2	Use language effectively at technical and professional contexts	Apply						
соз	Apply the academic and functional writing skills in formal and informal communicative contexts	Apply						
CO4	Interpret pictorial representation of statistical data and charts	Apply						

COU	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1				1					1	3		1			1
CO2				1					1	3		2			2
CO3				2					1	3		1			1
CO4				3					1	3		1			1
Avg				1.75					1	3		1.25			1.25
	1	'	3/2	/ 1 – inc	licates	strengtl	h of cor	relatio	n (3 – H	ligh, 2 –	Medium	, 1 – Lov	v)		1

22MA201	PARTIAL DIFFERENTIAL EQUATIONS, CALCULUS AND COMPLEX VARIA		S	SEMES	STER I	I
PRE-REQ	UISITE:	Category	BS	Cro	edit	4
Basic 12th 1	evel knowledge of Partial Derivatives, Vector algebra and	Hours/Week	L	T	P	TH
Complex Nu	umbers.	Hours/ week	3	1	0	4
Course Ob	ojectives:					
1. To	familiarize with the formation and solutions of first-order parti	al differential equatio	n.			
2. To	familiarize with the solutions of higher-order partial differential	al equations.				
3. To	acquire knowledge of vector differentiation and integration and	d its applications.				
4. To	know about analytic functions with properties, construction of	analytic functions and	d conform	nal trans	sformati	ons.
	obtain the knowledge of Cauchy's integral theorems, calculus of semi-circle.	of residues and compl	ex integr	ation are	ound un	it circl
UNIT I	PARTIAL DIFFERENTIAL EQUATIONS – F	IRST ORDER	9	3	0	12
UNIT II	PARTIAL DIFFERENTIAL EQUATIONS – HI	GHER ORDER	9	3	0	12
complement coordinates,	homogeneous and non-homogeneous linear partial diffe- tary function and particular integral method - Separation of Laplace equation in Cartesian and polar coordinates, one-dir	of variables method:	simple	problem	is in Ca	artesiai
complement	tary function and particular integral method - Separation of Laplace equation in Cartesian and polar coordinates, one-din	of variables method:	simple	problem	is in Ca	artesia
complement coordinates, equation. UNIT III Vector diffe Surface and	tary function and particular integral method - Separation of Laplace equation in Cartesian and polar coordinates, one-din	of variables method: mensional diffusion e	simple equation, 9 - Line in	problem one-din	os in Canensiona 0 n- work	artesian wave
complement coordinates, equation. UNIT III Vector diffe Surface and	VECTOR CALCULUS rentiation- Gradient- Directional derivative - Divergence - Cu Volume integrals - Green's theorem, Gauss divergence and Subes and rectangular parallelepipeds.	of variables method: mensional diffusion e orl, Vector integration Stokes theorem (withou	simple equation, 9 - Line in	problem one-din	os in Canensiona 0 n- work	artesial wav
complement coordinates, equation. UNIT III Vector diffe Surface and involving cu UNIT IV Functions of — Harmonic	VECTOR CALCULUS rentiation- Gradient- Directional derivative - Divergence - Cu Volume integrals - Green's theorem, Gauss divergence and Subes and rectangular parallelepipeds.	of variables method: mensional diffusion e arl, Vector integration stokes theorem (without n equation and sufficient	simple equation, 9 - Line in out proof 9 ent condi	3 tegratio) – Simp	onensiona onensiona	12 done-ication 12 g proof
complement coordinates, equation. UNIT III Vector diffe Surface and involving cu UNIT IV Functions of — Harmonic	VECTOR CALCULUS Perentiation- Gradient- Directional derivative - Divergence - Curl Volume integrals - Green's theorem, Gauss divergence and Subes and rectangular parallelepipeds. COMPLEX DIFFERENTIATION of a complex variable - Analytic functions - Cauchy - Riemann and orthogonal properties of analytic function - Construction of	of variables method: mensional diffusion e arl, Vector integration stokes theorem (without n equation and sufficient	simple equation, 9 - Line in out proof 9 ent condi	3 tegratio) – Simp	onensiona onensiona	12 done-ication 12 g proof

Text	Books:
1.	Grewal. B.S, "Higher Engineering Mathematics", 43 rd Edition, Khanna Publications, Delhi, 2015.
2.	Jain R.K. and Iyengar S.R.K., "Advanced Engineering Mathematics", 3 rd Edition, Narosa Publications, New Delhi, 2007.
Refe	rence Books:
1.	James Stewart, "Essential Calculus", 2 nd Edition Cengage Learning, New Delhi, 2014.
2.	P. Kandasamy, K. Thilagavathy and K. Gunavathy, "Engineering Mathematics (For I year B.E., B. Tech)", 9th Edition, S.Chand & Co. Ltd. New Delhi, 2010.
3.	Srimanta pal and Subath C. Bhumia, "Engineering Mathematics", Oxford University publications, New Delhi, 2015
4.	Ewinkreyzig, "Advanced Engineering Mathematics", 9th Edition, John Wiley & Sons, 2007.

5. Siva Ramakrishna Das. P, Ruknmangadachari.E. "Engineering Mathematics", 2nd Edition, Pearson, Chennai & Delhi, 2013.

	SE OUTCOMES: completion of the course, the students will be able to:	Bloom's Taxonomy Mapped				
CO1	Understand how to solve the given standard partial differential equations.	Understand				
CO2	CO2 Solve higher order partial differential equations.					
CO3	Use Gauss, Stokes and Green's theorems for the verification of line, surface and volume integrals.	Apply				
CO4	Familiar with the concept of Conformal and Bilinear transformations.	Understand				
CO5	Acquire the knowledge of Contour integration over unit circle and semi-circle.	Apply				

COUL	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	1	2									2		
CO2	3	2	1	2									2		
CO3	3	2	1	2									2		
CO4	3	2	1	2									2		
CO5	3	2	1	2									2		
Avg	3	2	1	2									2		
			3/2	/ 1 – inc	dicates	strengtl	of cor	relation	1 (3 – H	ligh, 2 –	Medium	, 1 – Lov	v)		

22PH	2PH101 ENGINEERING PHYSICS					SEMESTER II			
PRE-	-REQUI	SITE:	Category	BS	Cr	edit	4		
Basic	knowled	lge in sound, light and heat.	** /** 1	L	Т	P	TH		
			Hours/Week	3	1	0	4		
Cour	se Obje	ctives:							
1.	To unde	rstand Principles of ultrasonic production, its applications and	acoustics of building	ngs.					
2.	To unde	rstand Principle, working and industrial applications of LASE	R and optical fiber						
3.	To gain	knowledge in mode of transmission of heat by conduction me	chanism with exper	rimental	illustrati	ons			
4.	4. To obtain knowledge in basic concepts of quantum physics and matter waves								
5.	To acqu	ire knowledge in basics of crystal structure, types of crystal, it	s defects and crysta	l growth	techniq	lues			
UN	ITI	ULTRASONICS AND ACOUSTICS	5	9	3	0	12		
applic ACOU	ations - D	enerator –Detection of ultrasonic waves - Properties – According, welding, soldering and cleaning –SONAR – Medical and Education – Reverberation and reverberation – Absorption co-efficient – Basic requirements for the according – Reverberation and reverberation – Absorption co-efficient – Basic requirements for the according to the second seco	applications (Qualitation time –Factors	ative). affecting					
UN	IIT II	LASER AND FIBRE OPTICS		9	3	0	12		
UN: Mode condu Searle	IT III s of Tran activity an	the – Fiber optic communication (Block diagram). THERMAL PHYSICS Is mission of heat - Conduction – Convection – Radiation and its unit –Thermal conduction through compound media in the for good conductors, Lee's disc method for Bad conductors –	n series – Determin	ation of	thermal	conduc	ctivity -		
	IT IV	QUANTUM PHYSICS		9	3	0	12		
		experimental evidence: Davisson and Germer experiment –	Schroedinger's way				l .		
and de		equations – Physical significance of wave function – Particle							
UN	IT V	CRYSTAL PHYSICS		9	3	0	12		
Crysta	al growth	cell – Bravais lattice – Number of atoms per unit cell, atomic techniques: Bridgman, Czochralski techniques. Crystal imperefects – Edge dislocation, Screw dislocation – Planar defects –	rfections - Point de - Grain boundaries,	fects – S Twin bo	chottky oundarie	defect, l	Frenkel		
			10	nai (45)	L+1 51)) = 60 P	erious		
Text	Books:								
1.	Arumı	ıgam M, 'Engineering Physics', Anuradha publishers, 2019.							
2.	Rajeno	lran V. and Marikani A, 'Engineering Physics', PHI Learning	Pvt., India, 2018.						
3.	Palani	samy P.K, 'Engineering Physics', SCITECH Publications, 201	18.						

Arumugam M, 'Engineering Physics', Anuradha publishers, 2019.
 Rajendran V. and Marikani A, 'Engineering Physics', PHI Learning Pvt., India, 2018.
 Palanisamy P.K, 'Engineering Physics', SCITECH Publications, 2018.
 Ragavan V, 'Material science and engineering', Prentice Hall of India Pvt Ltd, NewDelhi, 2004.
 Introduction to crystal growth, Principles and Practice, H.L. Bhat, Taylor and Francis, 2015 edition.
 Reference Books:

 Gaur R.K. and Gupta S.L, 'Engineering Physics', DhanpatRai publishers, 2012.

Arthur Beiser, 'Concepts of Modern Physics', Tata McGraw Hill Publishing Co. Ltd, sixth Edition, 2019.
 Gerdkeiser, 'Optical fiber communications', Tata McGraw Hill Publishing Co. Ltd, 5th Edition, 2017.
 OrazioSvelto. David C. Hanna, 'Principles of Lasers', Springer Science &Business Media, LLC, 2010.

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:					
CO1	Understand the principle, production of ultrasonic wave and acoustics of buildings.	Understand				
CO2	Understand the principle and applications of laser and optical fiber.	Understand				
CO3	Analyze various modes involved in heat transmission	Analyze				
CO4	Gain knowledge in basic concept of quantum physics.	Remember				
CO5	Recognize crystal structure, crystal defects and crystal growth techniques.	Evaluate				

COURS	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	1	1	1	1						2	2	1	
CO2	2	3	1	1	2	1						2	1	1	
CO3	3	2	1	1	0							1	2		
CO4	3	2	1	1	2		1					1	1		
CO5	2	2	1	1	2							1	0	1	1
Avg	2.6	2.2	1	1	1.4	0.4	0.2					1.4	1.2	0.6	0.2
	3/2/1 – indicates strength of correlation (3 – High, 2 – Medium, 1 – Low)														

	101	ENGINEERING MECHANICS			SEMES	STER I	<u>I</u>
PRE-	REQ	UISITE:	Category	ES	Cre	edit	3
1. Eng	gineeri	ng Physics.	TT /XX/ 1	L	Т	P	TH
2. Eng	gineeri	ng Mathematics.	Hours/Week	3	0	0	3
Cour	se Ob	jectives:					
1.		evelop the capacity to predict the effect of force and motion neering.	in the course of carry	ing out	the desig	gn funct	tions o
2.	To an	nalyze the force systems and friction.					
3.	To st	udy the dynamics of particles, impulse and momentum					
UNI	TI	STATICS OF PARTICLES		9	0	0	9
Result a Parti	tant of icle- N	l Concepts and Principles, Systems of Units, Method of Probles, Resolution of a Force into Components, Rectangular Jewton's First Law of Motion, Space and Free-Body Diagrams	Components of a Forces, Forces in Space, Equ	e, Unit V illibrium	Vectors. of a Par	Equilibraticle in	rium o Space
UNI	TII	EQUILIBRIUM OF RIGID BODIE	ES	9	0	0	9
Dimensions - Reactions at Supports and Connections. UNIT III PROPERTIES OF SURFACES AND SOLIDS Centroid of simple figures from first principle, centroid of composite sections; Centre of							
Centro	oid of	simple figures from first principle, centroid of composite sec	ctions; Centre of Gra	-	_		
Centro	oid of ent of in		ctions; Centre of Gra	vity and	l its imp	lication	s; Are
Centro mome of iner	oid of ent of in rtia of	simple figures from first principle, centroid of composite sec nertia- Definition, Moment of inertia of plane sections from fir	ctions; Centre of Gra	vity and	l its imp	lication	s; Are
Centro mome of iner	oid of ent of in rtia of	simple figures from first principle, centroid of composite see nertia- Definition, Moment of inertia of plane sections from fir standard sections and composite sections; Theorems of Pappu	ctions; Centre of Grast principles, Theorem as-Guldinus.	vity and s of mor	l its imp	olications nertia, N	s; Are flomer
Centro mome of iner	oid of ent of in rtia of FIV	simple figures from first principle, centroid of composite seenertia- Definition, Moment of inertia of plane sections from fir standard sections and composite sections; Theorems of Pappu FRICTION	ctions; Centre of Grast principles, Theorem as-Guldinus.	vity and s of mor	l its imp	olications nertia, N	s; Are flomen
Centro mome of iner UNIT The la UNIT Kinem	oid of ent of intia of TIV TW TW nws of TV natics	simple figures from first principle, centroid of composite sections. Moment of inertia of plane sections from fir standard sections and composite sections; Theorems of Pappur FRICTION dry friction. Coefficients of friction, Angles of friction, Wedge	etics- Newton's Secon	yity and s of more	tits impenent of i 0 stance, I 0 f Motion	olications nertia, N o adder fi o r -Equat	s; Are flomen 9 riction 9 tions of
Centro mome of iner UNIT The la UNIT Kinem	oid of ent of intia of TIV TW TW nws of TV natics	simple figures from first principle, centroid of composite sections. Moment of inertia of plane sections from fir standard sections and composite sections; Theorems of Pappur FRICTION dry friction. Coefficients of friction, Angles of friction, Wedge DYNAMICS OF PARTICLES - Rectilinear Motion and Curvilinear Motion of Particles. Kine transic Equilibrium, Energy and Momentum Methods - Work	etics- Newton's Secon	y y y y y y y y y y y y y y y y y y y	o stance, I o f Motion	olications nertia, N o adder fi o r -Equat	s; Are Momen 9 riction 9 tions of ciple of
Centro mome of iner UNIT The la UNIT Kinem Motion Work	oid of ent of in rtia of TIV TW TW TW THAT	simple figures from first principle, centroid of composite sections. Moment of inertia of plane sections from first standard sections and composite sections; Theorems of Pappur FRICTION dry friction. Coefficients of friction, Angles of friction, Wedge DYNAMICS OF PARTICLES - Rectilinear Motion and Curvilinear Motion of Particles. Kine manic Equilibrium, Energy and Momentum Methods - Work energy, Principle of Impulse and Momentum, Impact of elastic	etics- Newton's Secon	y y y y y y y y y y y y y y y y y y y	o stance, I o f Motion	olications nertia, N o Ladder fi o n -Equatele, Prince	s; Are fomer 9 riction 9 tions ociple of
Centrol mome of iner UNIT The la UNIT Kinem Motion Work	poid of ent of intia of TIV TW TW TW The entire of intia of TV TW TRACT TRACT	simple figures from first principle, centroid of composite sections. Moment of inertia of plane sections from fir standard sections and composite sections; Theorems of Pappu FRICTION dry friction. Coefficients of friction, Angles of friction, Wedge DYNAMICS OF PARTICLES - Rectilinear Motion and Curvilinear Motion of Particles. Kine manic Equilibrium, Energy and Momentum Methods - Work nergy, Principle of Impulse and Momentum, Impact of elastic sections.	ctions; Centre of Grast principles, Theorem as-Guldinus. es, Wheel friction. Roletics- Newton's Secon of a Force, Kinetic E bodies.	y y y y y y y y y y y y y y y y y y y	o stance, I o f Motion	olications nertia, N o Ladder fi o n -Equatele, Prince	s; Are Momen 9 riction 9 tions of ciple of
Centro mome of iner UNIT The la UNIT Kinem Motion Work	poid of ent of intia of TIV TW TW TAN TAN TAN TAN TAN TAN	simple figures from first principle, centroid of composite sections. Moment of inertia of plane sections from fir standard sections and composite sections; Theorems of Pappur FRICTION dry friction. Coefficients of friction, Angles of friction, Wedge DYNAMICS OF PARTICLES - Rectilinear Motion and Curvilinear Motion of Particles. Kine manic Equilibrium, Energy and Momentum Methods - Work mergy, Principle of Impulse and Momentum, Impact of elastic sections. Section of Engineering Mechanics, R.K. Bansal, Laxmi Publication of Engineering Mechanics, R.K. Bansal, Laxmi Publication of Engineering Mechanics of Engineerin	ctions; Centre of Grast principles, Theorem as-Guldinus. es, Wheel friction. Roletics- Newton's Second of a Force, Kinetic E bodies.	y y y y y y y y y y y y y y y y y y y	o stance, I o f Motion a Partic	olications nertia, N o Ladder fi o n -Equatele, Prince = 45 P	s; Are fomer g riction g tions of
Centrol mome of iner UNIT The la UNIT Work I	poid of ent of intria of TIV TW TW TW TAN TAN TAN TAN TAN T	simple figures from first principle, centroid of composite sections. Moment of inertia of plane sections from fir standard sections and composite sections; Theorems of Pappur FRICTION dry friction. Coefficients of friction, Angles of friction, Wedge DYNAMICS OF PARTICLES - Rectilinear Motion and Curvilinear Motion of Particles. Kine manic Equilibrium, Energy and Momentum Methods - Work mergy, Principle of Impulse and Momentum, Impact of elastic sections. Section of Engineering Mechanics, R.K. Bansal, Laxmi Publication of Engineering Mechanics, R.K. Bansal, Laxmi Publication of Engineering Mechanics of Engineerin	ctions; Centre of Grast principles, Theorem as-Guldinus. es, Wheel friction. Roletics- Newton's Second of a Force, Kinetic E bodies.	y y y y y y y y y y y y y y y y y y y	o stance, I o f Motion a Partic	olications nertia, N o Ladder fi o n -Equatele, Prince = 45 P	s; Are fomer g riction g tions of
Centrol mome of iner UNIT The la UNIT Kinem Motion Work Text 1	poid of ent of intria of T IV T V matics ons, Dy and Entered Rajas 2013. rence Beer	simple figures from first principle, centroid of composite sections. Moment of inertia of plane sections from fir standard sections and composite sections; Theorems of Pappur FRICTION dry friction. Coefficients of friction, Angles of friction, Wedge DYNAMICS OF PARTICLES - Rectilinear Motion and Curvilinear Motion of Particles. Kine manic Equilibrium, Energy and Momentum Methods - Work nergy, Principle of Impulse and Momentum, Impact of elastic sections. Section of Engineering Mechanics, R.K. Bansal, Laxmi Publicate ekaran S and Sankarasubramanian G., "Fundamentals of Engineering Mechanics of Engineering Mechani	est, Wheel friction. Roletics- Newton's Secon of a Force, Kinetic E bodies. ations, 2010. Deering Mechanics', V	y y y y y y y y y y y y y y y y y y y	o stance, I o f Motion a Particular (45L)	olications nertia, N o Ladder fi o r Equatele, Prince = 45 P	s; Are flomer 9 riction ciple of

3.

4.

5.

E-References:

Engineering Mechanics, D.S. Bedi, Khanna Book Publishing Co. (P) Ltd, 2019.

Palanichamy M.S. and Nagam S., "Engineering Mechanics - Statics & Dynamics", Tata McGraw-Hill, 2001

Hibbeller, R.C., Engineering Mechanics: Statics, and Engineering Mechanics: Dynamics, 13th edition, Prentice Hall, 2013.

1.	https://nptel.ac.in/courses/122104014
2.	https://nptel.ac.in/courses/112106286

	RSE OUTCOMES: ompletion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Apply the various methods to determine the resultant forces and its equilibrium acting on a particle in 2D and 3D	Create
CO2	Apply the concept of reaction forces (non-concurrent coplanar and noncoplanar forces) and moment of various support systems with rigid bodies in 2D and 3D.	Evaluate
CO3	Evaluate area moments of inertia for various sections by applying the concepts of centroids.	Evaluate
CO4	Apply the concepts of frictional forces at the contact surfaces of various engineering systems.	Apply
CO5	Apply the various methods for evaluating dynamic parameters of the particles subjected to concurrent coplanar forces.	Apply

COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	1								1	3	1	
CO2	3	2	2	1								1	3	1	
CO3	3	2	2	1								2	3	2	
CO4	3	1	2	1								1	3	2	
CO5	3	1	2	1								1	3	2	
Avg	3	1.6	2	1								1.2	3	1.6	

 $3\,/\,2\,/\,1-indicates$ strength of correlation $(3-High,\,2-Medium,\,1-Low)$

22H	UNIVERSAL HUMAN VALUES			SEMESTER II					
PRE	-REQU	ISITE:	Category	HS	Cro	edit	3		
			Hours/Week	L	Т	P	TH		
			Hours/ week	2	1	0	3		
Cou	Course Objectives:								
1.		pment of a holistic perspective based on self-exploration aborexistence.	out themselves (hun	nan bein	g), fami	ly, socie	ety and		
2.	Unders	tanding (or developing clarity) of the harmony in the human be	eing, family, society	and nati	ure/exist	ence.			
3.	Strengt	hening of self-reflection.							
4.	. Development of commitment and courage to act.								
UNIT I BASIC CONCEPTS OF HUMAN VALUES			UES	6	3	0	9		

Course Introduction - Need, Basic Guidelines, Content and Process for Value Education. Purpose and motivation for the course, recapitulation from Universal Human Values-I. Self-Exploration—what is it? - Its content and process; 'Natural Acceptance' and Experiential Validation- as the process for self-exploration Continuous Happiness and Prosperity- A look at basic Human Aspirations. Right understanding, Relationship and Physical Facility- the basic requirements for fulfilment of aspirations of every human being with their correct priority. Understanding Happiness and Prosperity correctly- A critical appraisal of the current scenario Method to fulfil the above human aspirations- understanding and living in harmony at various levels.

UNIT II UNDERSTANDING HARMONY IN THE HUMAN BEING 6 3 0 9

Understanding Harmony in the Human Being - Harmony in Myself! Understanding human being as a co-existence of the sentient 'I' and the material 'Body' Understanding the needs of Self ('I') and 'Body' - happiness and physical facility. Understanding the Body as an instrument of 'I' (I being the doer, seer and enjoyer) Understanding the characteristics and activities of 'I' and harmony in 'I' Understanding the harmony of I with the Body: Sanyam and Health; correct appraisal of Physical needs, meaning of Prosperity in detail Programs to ensure Sanyam and Health.

UNIT III	UNDERSTANDING HARMONY IN THE FAMILY AND SOCIETY	6	3	0	9
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Understanding Harmony in the Family and Society- Harmony in Human- Human Relationship Understanding values in human-human relationship; meaning of Justice (nine universal values in relationships) and program for its fulfilment to ensure mutual happiness; Trust and Respect as the foundational values of relationship. Understanding the meaning of Trust; Difference between intention and competence. Understanding the meaning of Respect, Difference between respect and differentiation; the other salient values in relationship. Understanding the harmony in the society (society being an extension of family): Resolution, Prosperity, fearlessness (trust) and co-existence as comprehensive Human Goals. Visualizing a universal harmonious order in society- Undivided Society, Universal Order- from family to world family.

TIMITO IX7	UNDERSTANDING HARMONY IN THE NATURE AND		2	Δ.	0
UNIT IV	EXISTENCE	0	3	U	9

Understanding Harmony in the Nature and Existence - Whole existence as Coexistence. Understanding the harmony in the Nature. Interconnectedness and mutual fulfilment among the four orders of nature- recyclability and self-regulation in nature. Understanding Existence as Co-existence of mutually interacting units in all- pervasive space. Holistic perception of harmony at all levels of existence.

UNIT V	HOLISTIC UNDERSTANDING OF HARMONY	6	3	0	9
		-	_	1 -	-

Implications of the above Holistic Understanding of Harmony on Professional Ethics. Natural acceptance of human values. Definitiveness of Ethical Human Conduct. Basis for Humanistic Education, Humanistic Constitution and Humanistic Universal Order. Competence in professional ethics, Strategy for transition from the present state to Universal Human Order.

Total (30L + 15T) = 45 Periods

Reference Books:

1. Human Values and Professional Ethics by R R Gaur, R Sangal, G P Bagaria, Excel Books, New Delhi, 2010

Refer	rence Books:
1.	JeevanVidya: EkParichaya, A Nagaraj, JeevanVidyaPrakashan, Amarkantak, 1999.
2.	Human Values, A.N. Tripathi, New Age Intl. Publishers, New Delhi, 2004.
3.	The Story of Stuff (Book)
4.	The Story of My Experiments with Truth - by Mohandas Karamchand Gandhi
5.	Small is Beautiful - E. F Schumacher.
6.	Slow is Beautiful - Cecile Andrews
7.	Economy of Permanence - J C Kumarappa
8.	Bharat Mein Angreji Raj - PanditSunderlal
9.	Rediscovering India - by Dharampal
10.	Hind Swaraj or Indian Home Rule - by Mohandas K. Gandhi
11.	India Wins Freedom - Maulana Abdul Kalam Azad
12.	Vivekananda - Romain Rolland (English)
13.	Gandhi - Romain Rolland (English)

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:						
CO1	Become more aware of themselves, and their surroundings (family, society, nature) and become more responsible in life	Evaluate					
CO2	Handle problems with sustainable solutions, while keeping human relationships and human nature in mind	Apply					
соз	Become sensitive to their commitment towards what they have understood (human values, human relationship and human society)	Evaluate					
CO4	Apply what they have learnt to their own self in different day-to-day settings in real life, at least a beginning would be made in this direction.	Apply					

COU	COURSE ARTICULATION MATRIX														
CO/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1			1			1		2		1		3	2		1
CO2			1			3		1		1		3	1		1
CO3			1			2		1		1		3	1		2
CO4			2			1		1		1		3	1		1
Avg			1.25			1.75		1.25		1		3	1.25		1.25
	3 / 2 / 1 – indicates strength of correlation (3 – High, 2 – Medium, 1 – Low)											, 1 – Lov	v)		

	CIN01	ENGINEERING SPRINTS		1	SEMES	STER I	I			
PRE-	-REQU	ISITE:	Category	EE	Cr	edit	1			
			Hanna/Wash	L	Т	P	TH			
			Hours/Week	0	0	2	2			
Cour	se Obje	ectives:								
1.	To strei	ngthen conceptual understanding of fundamental engineering	concepts.							
2.	To spar	k curiosity in students' Minds.								
3.	To focu	s on teaching through a problem-solving approach using Street	eet Fight Engineerin	g princip	les pion	eered.				
4.	To fost	er the growth of functional independence and self-driven lear	ning habits							
5.	To max	imize the interest levels toward learning - as students aspire	to create meaningfu	l changes	s in the v	vorld.				
UN	IT I	STREET FIGHTING ENGINEERIN	IG	0	0	6	6			
UN	IT II	PROGRAMMING PARADIGM		0	0	6	6			
Algor	ithms - N	ramming - Outside box thinking to solve problems - Nee	-				harts &			
Types	of progr	Memory Allocation - Conditions and loops - Creating effect ramming languages& paradigms - Getting started with developments.				_	nming -			
	of progr T III	•				_	nming -			
UNI Key l	IT III Innovation	ramming languages& paradigms - Getting started with develo	opment - Build & te	st an algo	orithm - 1 Oury system	best prace 6 ems - A	nming - etices 6 dapting			
UNI Key l Transo Brains	IT III Innovation	BRAINS OF MACHINES ons in Tesla Electric car - Case study - Brains of Electric systems to Accelerate innovation - Idea Hexagon - Exercise 1	opment - Build & te	st an algo	orithm - 1 Oury system	best prace 6 ems - A	nming - etices 6 dapting			
WNI Key I Transo Brains UNI Basic	IT III Innovation disciplinates of Digital IT IV of Electron	BRAINS OF MACHINES ons in Tesla Electric car - Case study - Brains of Electric systems to Accelerate innovation - Idea Hexagon - Exertal camera	opment - Build & te	o disciplina nnovation	0 ary systems using 0	6 ems - A Idea He	mming - etices 6 dapting xagon -			
WNI Key I Transo Brains UNI Basic to Bui	IT III Innovation disciplinates of Digital IT IV of Electron	BRAINS OF MACHINES ons in Tesla Electric car - Case study - Brains of Electric systems to Accelerate innovation - Idea Hexagon - Exertal camera MACHINES THAT MAKE-UP THE Westernic Passive Components -Need for sensors & Actuators - A	opment - Build & te	o disciplina nnovation	0 ary systems using 0	6 ems - A Idea He	mming - etices 6 dapting xagon -			
UNI Key I Transo Brains UNI Basic to Bui UNI Real-v	IT III Innovation disciplinates of Digital IT IV of Electric III a Basic IT V world as	BRAINS OF MACHINES ons in Tesla Electric car - Case study - Brains of Electric systems to Accelerate innovation - Idea Hexagon - Exertal camera MACHINES THAT MAKE-UP THE Westernic Passive Components -Need for sensors & Actuators - Act Custom Hardware - Bootloader& its purpose	opment - Build & te	o disciplina nnovation o standing	orithm - 1 Oury systems using Ourselectronic	6 ems - A Idea He	nming - etices 6 dapting xagon - 6 s - How			

Text	Text Books:						
1.	SanjoyMahajan - Street Fighting Mathematics						
2.	Donald Knuth - The Art of Computer Programming						
3.	Think like a programmer: An introduction to creative problem solving						
4.	Thinking in Systems: A Primer						
Refe	rence Books:						
1.	Learning to code: How to think like a programmer						
2.	How to find innovative ideas: Ramesh Raskar's note						
3.	Case study: How Tesla changed the auto industry						
4.	Ultimate Guide: How to develop a new electronic hardware product						

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:						
CO1	Apply street fight engineering concepts to solve problems	Apply					
CO2	Construct flowcharts & block diagrams for algorithms	Apply					
CO3	Apply the Idea Hexagon Tool to learn innovation models	Apply					
CO4	Understand basic electronics for building hardware	Apply					
CO5	Examine real-world problems with a system view	Analyze					

COU	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	3							2		2				2
CO2	2			3					2						2
CO3	2	2		3					2		2				2
CO4	2	2		3				1	2		2				2
CO5		3				1	2		2	1	2				2
Avg	2	2.5		2		1	2	1	2	1	2				2
	•	•	3/2	/ 1 – inc	dicates	strengtl	h of cor	relatio	n (3 – H	ligh, 2 –	Medium	, 1 – Lov	v)		

22N	1C201	தமிழரும் தொழில்நுட்பமும்		S	Semeste	er	II			
	10 2 01 பெந்தவை	B.E (Common to all Branches)	Catagory	HS						
			Category	MC	Cre	eart	1			
இலக்	கணம் ம	ற்றும் இலக்கியத்தின் அடிப்படைகள்	TT /537 1	L	T	P	TH			
			Hours/Week	1	0	0	1			
பாட்	ந்றி நோ	க்கங்கள்: மாணவர்களால்								
1.	1. நெசவுத் தொழிலின் நன்மைகள், அதன் பயன்கள், பானைத் தொழில் நுட்பத்தைப் பற்றி நன்கு அறிந்து கொள்ள முடியும்.									
2.	கட்டிடப்	் கட்டுதல் மற்றும் கட்டிடத் தொழிலுள்ள நுட்பங்கள் பற்	றி அறிந்து கொ	ர்ள மு	தயும் .					
3.	உற்பத்த பயன்பா	நி தொழில் நுட்பம், இரும்பு, உலோகம், கனிமம், தொழிற் ரடுகளை வெளிப்படுத்த முடியும்.	சாலைகள் பற்றி	அறிந்த	நு அவற்	ற்றின்				
4.		ண்மை மற்றும் நீர் பாசன முறைகள், தொழில் நுட்பம், ஏர் ளைப் பற்றி தெரிந்து நடைமுறைப் படுத்த முடியும்.	உழுதல் போன்ற) பண்6	டைய க	ால நெ	_ฏ			
5.		றய கால கட்டத்தில் உள்ளவாறு அறிவியல் வளர்ச்சி, க முலிரிவாக்க முடியும்.	ணினித் தமிழ் ப <u>ற</u> ்	றி தெர்	ிந்து ெ	காண்டு)			
அ	w I	நெசவு மற்றும் பானை தொழில்நுட்பம்		3	0	0	3			
	சங்க காலத்தில் நெசவுத் தொழில் - பானை தொழில் நுட்பம் - கருப்பு சிவப்பு பாண்டங்கள்- பாண்டங்களில் கீறல் குறியீடுகள்									
அ 6	ා ල II	வடிவமைப்பு மற்றும் கட்டிடத் தொழில்நுட்	பம்	3	0	0	3			
பற்றி பெரு கட்ட	ய விவர ங்கோயி கமைப்பு	சங்க காலத்தில் கட்டுமான பொருட்களும் நடுகல் ங்கள் - மாமல்லபுரச் சிற்பங்களும், கோவில்களுடி ல்கள் மற்றும் பிற வழிபாட்டுத் தலங்கள்- நா கள் பற்றி அறிதல், மதுரை மீனாட்சி அம்மன் ஆல வீடுகள் - பிரிட்டிஷ் காலத்தில் சென்னையில் இந்ே	ம் - கோவில்கடு யக்கர் காலக் பம் மற்றம் திரு	ளும் - கோ மலை	சோழ யில்கள் நாயக்க	ர் கா ர் - ப கர் ம <u>வ</u>	லத்துப் மாதிரி			
	்கு III	உற்பத்தித் தொழில் நுட்பம்	<u>- </u>	3	0	0	3			
வரல உரு6 - எலு	ாற்றுச் பாக்கம் பம்புத்துவ	ம் கலை - உலோகவியல் - இரும்புத் தொழிற்சா சான்றுகளாக செம்பு மற்றும் தங்க நாணயங்கள் தொழிற்சாலைகள் - கல்மணிகள், கண்ணாடி மணில ன்டுகள் - தொல்லியல் சான்றுகள் - சிலப்பதிகாரத்த	- நாணயங்க கள் - சுடுமண் ப தில் மணிகளின்	ள் அ மணிக வசை	ச்சிடித் ள் - சங் கள்.	தல் - ப்கு மன	மணி னிகள்			
)கு IV	வேளாண்மை மற்றும் நீர்ப்பாசனத் தொழில் ந		3	0	0	3			
கால்! செய	நடைக <u>ஞ</u> ல்பாடுக	குளங்கள், மதகு, - சோழர்காலக் குமுழித் தூம்பின் நக்காக வடிவமைக்கப்பட்ட கிணறுகள் - வேள ள் - கடல்சார் அறிவு - மீன்வளம் - முத்து மற்றும் றிவு - அறிவுசார் சமூகம்.	ாண்மை ம <u>ற்று</u> ப	ம் வே	ளாண்	மை ச	ஈார்ந்த			
அ 6	wகு V	அறிவியல் தமிழ் மற்றும் கணித்தமிழ்		3	0	0	3			
மென்	அறிவியல் தமிழின் வளர்ச்சி - கணித்தமிழ் வளர்ச்சி - தமிழ் நூல்களை மின் பதிப்பு செய்தல் - தமிழ் மென் பொருட்கள் உருவாக்கம் - தமிழ் இணையக் கல்விக்கழகம் - தமிழ் மின் நூலகம் - இணையத்தில் தமிழ் அகராதிகள் - சொற்குவைத் திட்டம்.									
					Total	= 15 P	eriods			

Tex	xt Books:
	தமிழக வரலாறு - மக்களும் பண்பாடும் - கே.கே. பிள்ளை (வெளியீடு: தமிழ்நாடு பாடநூல் மற்றும் கல்வியல் பணிகள் கழகம்)
2	கணினித் தமிழ் - முனைவர் இல.சுந்தரம் (விகடன் பிரசுரம்)
3	கீழடி - வைகை நதிக்கரையில் சங்ககால நகர நாகரிகம் (தொல்லியல் துறை வெளியீடு)
4	பொருநை - ஆற்றங்கரை நாகரிகம். (தொல்லியல் துறை வெளியீடு)

பாட்	ந்றி முடிவுகள்: இந்தப் படிப்பு முடிந்ததும், மாணவர்களால்	Bloom's Taxonomy
		Mapped
CO1	சங்காலத்தில் இருந்த நல்ல தொழில்களையும் கைவிணை கலைகளால் ஏற்படும்	Understanding
	நன்மைகளையும் பற்றி அறிந்து கொண்டனர்.	_
CO2	கட்டிடங்கள் மற்றும் வீட்டுப்பொருட்களை வடிவமைப்பது, சங்காலத்தில் இருந்த	Understanding
	கோவில்களை பற்றி அறிந்து கொண்டனர்	Ç
CO3	உலோகவியல், இரும்பு தொழிற்சாலைகள், தொல்லியல் சான்றுகள், உற்பத்தி	Applying
	தொழல் நுட்பத்தை பற்றி அறிந்து கொண்டனர்.	
CO4	பழங்காலத்தில் வோளண்மை, நீர்பாசனம், மீன் வளம், கால்நடை பராமாிப்பு,	Applying
	அறிவுசார் சமுகம் பற்றி அறிந்து கொண்டனர்.	
CO5	அறிவியல் தமிழன் வளர்ச்சி, கணித்தமிழ் வளர்ச்சி, மென்பொருள் உருவாக்கம்,	Understanding
	இணைய கல்வி கழகம், இணையத்தில் தமிழ் அகராதிகள் பற்றி அறிந்து	
	கொண்டனர்.	

PO1	DO4		_	COURSE ARTICULATION MATRIX											
	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO 10	PO 11	PO 12	PSO 1	PSO 2	PSC 3	
		3			2						1	2			
		3			2						1	2			
		3			2						1	2			
		3			2						1	2			
		3			2						1	2			
		3			2						1	2			
			3 3 3	3 3 3 3	3 3 3 3	3 2 3 2 3 2 3 2	3 2 2 3 3 2 3 2 3 3 2 2 3 3 2 3 3 2 3 3 3 2 3	3 2 2 3 3 2 3 3 2 3 3 2 3 3 2 3 3 3 2 3 3 3 3 2 3	3 2 2 3 3 2 3 3 2 3 3 2 3 3 2 3 3 3 2 3 3 3 3 2 3	3 2 2 3 3 2 3 3 2 3 3 2 3 3 2 3 3 3 2 3 3 3 2 3 3 3 2 3 3 3 3 2 3	3 2 3 2 3 3 2 3 3 2 3 3 2 3 3 2 3 3 3 2 3 3 3 2 3 3 3 2 3 3 3 2 3 3 3 2 3 3 3 3 2 3	3 2 3 2 3 2 3 2 3 2 1 1 3 2 1 1	3 2 3 2 3 2 3 2 1 2 3 2 3 1 2 1 3 2 1 2 2 1 2 1 2 1 2 2	3 2 3 2 3 2 3 2 3 2 3 1 2 1 3 2 1 2	

22M	IC201	TAMILS AND TECHNOLOGY		S	Semester II					
PREI	REQUIS	ITES	Category	HS MC	Cro	edit	1			
Basic	s of Tam	ils Language and Literature		L	T	P	TH			
			Hours/Week	1	0	0	1			
1.	To Obta	in the knowledge of weaving and ceramic technology				1				
2.	To fami	liarize about design and construction technology during	sangam age and	British	period					
3.	To know about the manufacturing technologices									
4.	To obtain	in the knowledge of agriculture and irrigation technolog	y							
5.	To know	w about the development of Scientific Tamil and Tamil	computing							
Uı	nit I	WEAVING AND CERAMIC TECHNOL	OGY	3	0	0	3			
Weavi	ng Industr	ry during Sangam Age – Ceramic technology – Black and Rec	l Ware Potteries (B	RW) –	Graffiti	on Pott	eries.			
Un	nit II	DESIGN AND CONSTRUCTION TECHNO	OLOGY	3	0	0	3			
Hero s Great	stones of S Temples of	Structural construction House & Designs in household matericangum age – Details of Stage Constructions in Silappathikar of Cholas and other worship places - Temples of Nayaka Pekar Mahal - Chetti Nadu Houses, Indo - Saracenic architecture	am - Sculptures an riod - Type study (d Temp (Madura	oles of M ai Meen	Iamalla	puram -			
Un	it III	MANUFACTURING TECHNOLOG	Y	3	0	0	3			
Mintin	ng of Coins	ding - Metallurgical studies - Iron industry - Iron smelting, st s – Beads making-industries Stone beads -Glass beads - Terraco a stone types described in Silappathikaram.								
Un	it IV	AGRICULTURE AND IRRIGATION TECH	NOLOGY	3	0	0	3			
use - A	Agriculture	ds, Sluice, Significance of KumizhiThoompu of Chola Perio e and Agro Processing - Knowledge of Sea - Fisheries – Pearl cific Society.								
Ur	nit V	SCIENTIFIC TAMIL & TAMIL COMPU	TING	3	0	0	3			
		Scientific Tamil - Tamil computing – Digitalization of Tamil y – Tamil Digital Library – Online Tamil Dictionaries – Sorki		nent of	Γamil So	oftware	– Tamil			
					Total	= 15 I	Periods			
Te	xt Books	:								
1	Socia	l Life of Tamils (Dr.K.K.Pillay) A joint publication of TNTB	& ESC and RMRI	_ – (in p	orint)					
2	Socia Studi	l Life of the Tamils - The Classical Period (Dr.S.Singarave es.	elu) (Published by:	Interna	itional I	nstitute	of Tam			
3		rical Heritage of the Tamils (Dr.S.V.Subatamanian, Dr.K.Lute of Tamil Studies).). Thirunavukkaras	su) (Pul	blished	by: Inte	ernationa			
4	Studi	•				stitute of	f Tamil			
5		ndi - 'Sangam City Civilization on the banks of river Vaigai' (chaeology&TamilNadu Text Book and Educational Services C			artment					
6		es in the History of India with Special Reference to Tamil Na								
7		nai Civilization (Jointly Published by: Department of Archaeo ces Corporation, Tamil Nadu)	logy & Tamil Nadı	ı Text E	Book and	d Educa	tional			
8	Journ	ey of Civilization Indus to Vaigai (R.Balakrishnan) (Publishe	d by: RMRL)							

	Course Outcomes: Upon completion of this course, the students will be able to:							
CO1	Obtain the knowledge about weaving and ceramic technology.	Understatnding						
CO2	Familiarize about design and construction technology during sangam age and British period	Understatnding						
CO3	Understanding about the manufacuturing technologies	Applying						
CO4	Acquire the skills in agriculture and irrigation technology	Applying						
CO5	Acquire the knowledge about the development of Scientific Tamils and Tamil computing.	Understatnding						

	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO 10	PO 11	PO 12	PSO 1	PSO 2	PSO 3
CO1			3			2						1	2		
CO2			3			2						1	2		
CO3			3			2						1	2		
CO4			3			2						1	2		
CO5			3			2						1	2		
Avg			3			2						1	2		
	3/2/1 – indicates strength of correlation (3- High, 2- Medium, 1- Low)														

22NC201	NCC COURSE-I (Only for NCC Studen	ts)		Seme	nester II			
PREREQUIS	SITES	Category	NC	Cre	edit	3		
			L	T	P	TH		
		Hours/Week	3	0	0	3		
Course Learn	ning Objectives							
1 To ma	intain the unity and disciplines to the students							
Unit I	NCC GENERAL & NATIONAL INTEGRATIO AWARENESS	N AND	9	0	0	9		
_	es and Org of NCC – Incentives to NCC cadets – Duties of NC ation: Importance and Necessity – Factors affecting National Integration:							
Unit II	PERSONALITY DEVELOPMENT & LEADER DEVELOPMENT	RSHIP	9	9 0 0				
L CI SOHIAHIY I JEV	iolonmont Concula, Salt Assoronace Empoths: Crootisia & Crootisia	Thinking Doci	cion M	akina (Ommii	nication		
Skills - Group I Civil Sense - C Ethics &Honou	velopment Capsule -Self Awareness Empathy, Creative& Creative Discussion - Stress emotions, Change Your Mindset, Inter Persona Career Counselling, SSB Procedures & Interview Skills; Leader r code - Case Studies-Shivaji, APG Abdul Kalam & Deepa Malik, Narayan Murty, PrakashPadukone, Tipu Sultan, Rabindranath Ta	al Relations& Te ship Capsule - 7 MaharanaPrata	am woı Гraits, I	k, Time ndicator	Manag s, Mot	ements, ivation,		
Skills - Group I Civil Sense - C Ethics &Honou	Discussion - Stress emotions, Change Your Mindset, Inter Persona Career Counselling, SSB Procedures & Interview Skills; Leader r code - Case Studies-Shivaji, APG Abdul Kalam & Deepa Malik,	al Relations& Te ship Capsule - MaharanaPrataj agore.	am woı Гraits, I	k, Time ndicator	Manag s, Mot	ements, ivation,		
Skills - Group I Civil Sense - C Ethics &Honou Jhansi Ki Rani, Unit III Disaster Manag Fighting – Initia	Discussion - Stress emotions, Change Your Mindset, Inter Persona Career Counselling, SSB Procedures & Interview Skills; Leader r code - Case Studies-Shivaji, APG Abdul Kalam & Deepa Malik, Narayan Murty, PrakashPadukone, Tipu Sultan, Rabindranath Ta	al Relations& Te ship Capsule - Te MaharanaPrata agore. IYGIENE Role of NCC Ca sasters, Man Ma	eam wor Fraits, I p, Ratar 9 adets – I de Disa	k, Time ndicator Tata, K	Managers, MotairanMa o vice & I ealth &	ements, ivation, jumdar, g		
Skills - Group I Civil Sense - C Ethics &Honou Jhansi Ki Rani, Unit III Disaster Manag Fighting – Initia	Discussion - Stress emotions, Change Your Mindset, Inter Personal Career Counselling, SSB Procedures & Interview Skills; Leader r code - Case Studies-Shivaji, APG Abdul Kalam & Deepa Malik, Narayan Murty, PrakashPadukone, Tipu Sultan, Rabindranath Table DISASTER MANAGEMENT AND HEALTH & Hotement Capsule- SochVichar, Types - Organisation, Capability & Lative Training, Organisation Skills, Do's and Don'ts - Natural Discussions a	al Relations& Teship Capsule - Teship Ca	eam wor Fraits, I p, Ratar 9 adets – I de Disa	k, Time ndicator Tata, K	Managers, MotairanMa o vice & I ealth &	ements, ivation, jumdar, g		
Skills - Group I Civil Sense - C Ethics &Honou Jhansi Ki Rani, Unit III Disaster Manag Fighting – Initis Sanitation – Fir Unit IV Laws of Motion – Stall – Thrust	Discussion - Stress emotions, Change Your Mindset, Inter Personal Career Counselling, SSB Procedures & Interview Skills; Leader r code - Case Studies-Shivaji, APG Abdul Kalam & Deepa Malik, Narayan Murty, PrakashPadukone, Tipu Sultan, Rabindranath Table and DISASTER MANAGEMENT AND HEALTH & Hotement Capsule- SochVichar, Types - Organisation, Capability & Lative Training, Organisation Skills, Do's and Don'ts - Natural Diest aid in Common Medical Emergencies, Treatment & Care of Work PRINCIPLES OF FLIGHT & GENERAL SER KNOWLEDGE 1 - Glossary Terms - Bernoulli's Principle - Aerofoil - Forces act; Armed Forces & IAF Capsule - Modes of Entry in IAF, Civil A	al Relations& Teship Capsule - Teship Ca	eam wor Fraits, I p, Ratar 9 adets – I de Disa action to 9	o Fire Services ters; Ho O O Drag –	Managers, MotificanMagers, MotificanMage	ements, ivation, jumdar, jumdar, jumdar, ises.		
Skills - Group I Civil Sense - C Ethics &Honou Jhansi Ki Rani, Unit III Disaster Manag Fighting – Initis Sanitation – Fir Unit IV Laws of Motion – Stall – Thrust	Discussion - Stress emotions, Change Your Mindset, Inter Personal Career Counselling, SSB Procedures & Interview Skills; Leader r code - Case Studies-Shivaji, APG Abdul Kalam & Deepa Malik, Narayan Murty, PrakashPadukone, Tipu Sultan, Rabindranath Table and DISASTER MANAGEMENT AND HEALTH & Hotement Capsule- SochVichar, Types - Organisation, Capability & Lative Training, Organisation Skills, Do's and Don'ts - Natural Diest aid in Common Medical Emergencies, Treatment & Care of Work PRINCIPLES OF FLIGHT & GENERAL SER KNOWLEDGE 1 - Glossary Terms - Bernoulli's Principle - Aerofoil - Forces act; Armed Forces & IAF Capsule - Modes of Entry in IAF, Civil A	al Relations& Teship Capsule - Teship Ca	eam wor Fraits, I p, Ratar 9 adets – I de Disa action to 9	o Fire Services ters; Ho O O Drag –	Managers, MotificanMagers, MotificanMage	9 Fire ises. 9		
Skills - Group I Civil Sense - C Ethics &Honou Jhansi Ki Rani, Unit III Disaster Manag Fighting - Initia Sanitation - Fir Unit IV Laws of Motion - Stall - Thrust & Acquisitions Unit V Requirements of Engines - Turb	Discussion - Stress emotions, Change Your Mindset, Inter Personal Career Counselling, SSB Procedures & Interview Skills; Leader r code - Case Studies-Shivaji, APG Abdul Kalam & Deepa Malik, Narayan Murty, PrakashPadukone, Tipu Sultan, Rabindranath Ta DISASTER MANAGEMENT AND HEALTH & Hotement Capsule- SochVichar, Types - Organisation, Capability & ative Training, Organisation Skills, Do's and Don'ts - Natural Diest aid in Common Medical Emergencies, Treatment & Care of Work PRINCIPLES OF FLIGHT & GENERAL SER KNOWLEDGE 1 - Glossary Terms - Bernoulli's Principle - Aerofoil - Forces act; Armed Forces & IAF Capsule - Modes of Entry in IAF, Civil A	al Relations& Teship Capsule - Teship Ca	am wor Fraits, I p, Ratar 9 adets – I de Disarction to 9 – Lift & ft Recog	o Fire Services Ho O Drag = gnition = O S = Pisto	Managers, MotificanMagers, MotificanMage	ements, ivation, jumdar, jumdar, jumdar, jumdar, jumdar, sises. 9 & Slats Trends 9		

	completion of this course, the students will be able to:	Bloom's Taxonomy Level
CO1	Acquired knowledge about the history of NCC, its organization, incentives of NCC, duties, different NCC camps	Analyze
CO2	Understand the concept of national integration and its importance	Understand
CO3	Understand the importance disaster management and health and hygiene.	Understand
CO4	Understand the importance principal of Flight and knowledge about armed services.	Understand
CO5	Understand and learn the importance of navigation, Aero engines & Airmanship work.	Understand

22CS102	COMPUTER PRACTICE AND C PROGRA LABORATORY	;	SEMESTER II			
PREREQUIS	Category	ES	Cre	edit	1.5	
			L	Т	P	TH
		Hours/Week	0	0	3	3
Course Learn	ing Ohiectives					

Jourse Learning Objectives

- 1 To provide basic knowledge to work with word processing applications 2 To provide basic knowledge to work with spread sheet applications
 - 3 To promote the programming ability to develop C applications

EXPERIMENTS

A. Word Processing

- 1. Creating and formatting documents.
- 2. Creating Tables and Manipulation
- 3. Using Equation Editor
- 4. Inserting Pictures, Shapes and Charts
- 5. Using Mail merge

B. Spread Sheet

- 6. Creating sheets, using built in function and use-defined formulae
- 7. Creating different types of charts from data

C. Simple C Programming

- 8. Program using different operators.
- 9. Program using Control statements.
- 10. Program using Loops, Array and Strings.
- 11. Program using Functions and pointers.
- 12. Program using Structures and Files.

For programming exercises Algorithm, Flow chart and pseudo code are essential

Total (45P) = 45 Periods

	se Outcomes: completion of this course, the students will be able to:	Bloom's Taxonomy Level				
CO1 Demonstrate the usage of features supported by word processing applications. Apply						
CO2	Demonstrate the usage of features supported by spread sheet applications.	Apply				
CO3	Apply general programming techniques to develop digital solution to problems	Apply				
CO4	Implement solutions develop with general programming techniques in C programming language	Apply				

COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO 10	PO 11	PO 12	PSO 1	PSO 2	PSO 3
CO1										3				1	
CO2	3	3												1	
CO3	3	3	2	2	2	1	1	1			2	3		1	
CO4	3	3	2	2	2	1	1	1			2	3		1	
Avg	3	3	2	2	2	1	1	1		3	2	3		1	
	3/2/1 – indicates strength of correlation (3- High, 2- Medium, 1- Low)														

22ME102	WORKSHOP MANUFACTURING PRA	SEMESTER II				
PREREQUIS	ITES	Category	ES	Cre	Credit	
			L	Т	P	TH
		Hours/Week	0 0		4	4
Course Learn	ing Objectives					

To understand the basics of safety measures taken in the laboratory. 2 To provide exposure to the students with hands-on experience on various basic engineering practices in Civil and Mechanical Engineering. 3 To know about the various fitting joints and lathe operation. 4 To gain knowledge in welding and fitting operation. 5 To understand the fabrication of various models using sheet metals.

LIST OF EXPERIMENTS

- 1. Introduction to Safety measures and First aid.
- Study of Lathe, drilling machine -Welding methods and equipment- Casting process and tools- Sheet metal and fitting tools- Carpentry tools and joints.
- 3. Fitting: V-fitting, square fitting, Curve fitting.
- 4. Lathe: Facing, turning, taper turning and knurling.
- 5. Welding: BUTT, LAP and T- joints.
- 6. Foundry: Greensand preparation- mould making practice.
- Sheet metal: Cone, tray, cylinder.
- 8. Carpentry: CROSS, T and DOVETAIL joints.
- 9. Drilling: simple exercises.

Total (60P) = 60 Periods

Refe	rence Books:
1	Bawa, H.S, "Workshop Practice", Tata McGraw Hill Publishing Company Limited, 2007.
2	Jeyachandran.K, Natarajan.K and Balasubramanian.S, "A Primer on Engineering Practices Laboratory", Anuradha Publications, 2007.
3	Jeyapoovan.T, SaravanaPandian.M, and Pranitha.S, "Engineering Practices Lab Manual", Vikas Publishing House Pvt. Ltd, 2006.
4	Dr. P.Kannan, Mr. T.Satheeskumar & Mr.K.Rajasekar, "Engineering practices laboratory" Mnual first edition 2017.
5	Dr. V. Rameshbabu "Engineering practices laboratory" VRB publication pvt ld.

	Course Outcomes: Upon completion of this course, the students will be able to:					
CO1	Familiarize the working of various equipment and safety measures.	Understand				
CO2	Prepare fitting of metal and wooden pieces using simple fitting and carpentry tools manually.	Apply				
СОЗ	Prepare the mould cavity by using proper moulding tools in foundry section.	Apply				
CO4	Fabrication of components using welding, lathe and drilling machine.	Apply				
CO5	Make the model using sheet metal works.	Apply				

PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
				22	3									
	3		2	1										2
	3		2	1										2
	3		2	1										2
	3		2	1										2
	3		2	1	3									2
	PO1	3 3 3 3	3 3 3 3	3 2 3 2 3 2 3 2	3 2 1 3 2 1 3 2 1 3 2 1 3 2 1	3 2 1 3 2 1 3 2 1 3 2 1 3 2 1	3 2 1 3 2 1 3 2 1 3 2 1 3 2 1	3 2 1 3 2 1 3 2 1 3 2 1 3 2 1	3 2 1 3 2 1 3 2 1 3 2 1 3 2 1	3 2 1 3 2 1 3 2 1 3 2 1 3 2 1	3 2 1 3 2 1 3 2 1 3 2 1 3 2 1	3 2 1 3 2 1 3 2 1 3 2 1 3 2 1	3 2 1 3 2 1 3 2 1 3 2 1 3 2 1 3 2 1	3 2 1 3 2 1 3 2 1 3 2 1 3 2 1 3 2 1

3/2/1 – indicates strength of correlation (3- High, 2- Medium, 1- Low)

22M	IA305	FOURIER SERIES, BOUNDARY VALUES PRO TRANSFORMS	OBLEMS AND	SEMESTER III						
PRE	E-REQU	USITE:	Category	BS	Cro	edit	3			
Basic	e 12 th leve	el knowledge of Taylor series, ODE and integration.	Hours/Week	L 3	T 0	P 0	TH 3			
Cou	rse Obj	ectives:			l .		l .			
1.	To intr	oduce the concept of the Fourier series.								
2.	2. To understand the application of Fourier analysis in solving boundary value problems.									
3.		ain the knowledge of solving second order ODE using Laplace onvolution theorem.	e transform technique	es and inv	verse La	place tra	nsform			
4.	4. To familiarize with Fourier, transform of a function and its sine and cosine transforms.									
5.	To gair	gain the skills to form difference equations and find its solution by using the Z-transform method.								
UN	NIT I	FOURIER SERIES		9	0	0	9			
	hlet's co eval's Ide	nditions – General Fourier series – Odd and even functions - entity.	– Half range sine ser	ries – Ha	lf range	cosine s	series –			
UN	IT II	BOUNDARY VALUE PROBLEMS	S	9	0	0	9			
dime	nsional h	of second-order quasi-linear partial differential equations — leat equation — Steady-state solution of two-dimensional heat artesian coordinates.								
UN	IT III	LAPLACE TRANSFORM		9	0	0	9			
		sform- Conditions for existence – Transform of elementary functions – Inverse Laplace Transform-si								
UN	IT IV	FOURIER TRANSFORM		9	0	0	9			
		Fourier integral theorem – Fourier transforms pair – Sine and Convolution theorem - Parseval's Identity.	Cosine transforms – P	roperties	– Trans	forms of	simple			
UN	NIT V	Z -TRANSFORM AND DIFFERENCE EQUATIONS 9 0 0 9								
		f simple functions and properties – Inverse Z – transform –inidifference equations.	itial and final value tl	neorems-	Convol	ution the	eorem -			
				Tota	ıl (45L)	= 45 P	eriods			

Text Books:								
1.	Veerarajan T, "Engineering Mathematics (For Semester III)", 3 rd Edition, Tata McGraw Hill Education Pvt. Ltd., New Delhi, 2009.							
2.	P. Kandasamy, K. Thilagavathy and K. Gunavathy, "Engineering Mathematics, Volume III", S. Chand & Company ltd., New Delhi, 1996.							
Refe	rence Books:							
1.	Grewal, B.S., "Higher Engineering Mathematics", 43 rd Edition, Khanna Publishers, Delhi, 2014.							
2.	Wylie C. Ray and Barrett Louis, C., "Advanced Engineering Mathematics", 6 th Edition, McGraw-Hill, Inc., New York, 1995.							
3.	Andrews, L.A., and Shivamoggi B.K., "Integral Transforms for Engineers and Applied Mathematics", MacMillan, New York, 1988.							
4.	Narayanan, S., Manicavachagom Pillai, T.K. and Ramaniah, G., "Advanced Mathematics for Engineering Students", Volumes II and III, S. Viswanathan (Printers and Publishers) Pvt. Ltd. Chennai, 2002.							

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:		
CO1	Acquire knowledge about the Fourier series.	Understand	
CO2	Appreciate the physical significance of Fourier series techniques in solving one and two-dimensional heat flow problems and one-dimensional wave equations.	Understand	
CO3	Apply the knowledge of the Laplace transforms.	Understand	
CO4	Apply the knowledge of Fourier transform in engineering problems.	Apply	
CO5	Apply the knowledge of Z-transform in engineering problems.	Apply	

COU	RSE A	RTICU	JLATI	ON M	ATRIX	<u> </u>									
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2		2	0								2		
CO2	3	2		2	0								2		
CO3	3	2		2	0								2		
CO4	3	2		2	0								2		
CO5	3	2		2	0								2		
Avg	3	2		2	0								2		
			3/2	/ 1 – inc	dicates	strengtl	h of cor	relation	1 (3 – H	[igh, 2 –]	Medium	, 1 – Lov	v)		

22ME301	ENGINEERING THERMODYNAMICS (Use of standard thermodynamic tables, Mollier diagram are permitted)	S	EMES	TER I	II
PRE-REQU	ISITE: Category	PC	Cr	edit	4
		L	Т	P	TH
	Hours/Week	3	1	0	4
Course Obje	ectives:				
1. To impa	art the knowledge on concepts of zeroth and first law of thermodynamics.				
	e the learners to understand the third law of thermodynamics and analyze the val d and open systems.	rious wo	rk and h	eat inte	raction
3. To teach	n properties of pure substance.				
4. To impa	art knowledge on the concepts of steam power cycle.				
5. To deriv	ve thermodynamic relations for ideal and real gases.				
UNIT I	BASIC CONCEPT AND FIRST LAW	9	3	0	12
with reference UNIT II	bisplacement work, P-V diagram. Zeroth law of thermodynamics – concept of te cs – application to closed and open systems, internal energy, specific heat capacitic to various thermal equipment. SECOND LAW AND ENTROPY	es, enthal	py, stead	dy flow 0	proces
with reference UNIT II Heat engine – these statemen	cs – application to closed and open systems, internal energy, specific heat capacitic to various thermal equipment.	9 usius state	y, stead	dy flow 0 Equival	12 lence of
with reference UNIT II Heat engine – these statemen	cs – application to closed and open systems, internal energy, specific heat capacitic to various thermal equipment. SECOND LAW AND ENTROPY Refrigerator – Heat Pump, Second law of thermodynamics – Kelvin's and Clausts their corollaries. Reversibility and irreversibility. Carnot cycle, reversed Cartesian corollaries.	9 usius state	y, stead	dy flow 0 Equival	12 lence of
with reference UNIT II Heat engine — these statemer Concept of ent UNIT III Steam - forma	cs – application to closed and open systems, internal energy, specific heat capacitic to various thermal equipment. SECOND LAW AND ENTROPY Refrigerator – Heat Pump, Second law of thermodynamics – Kelvin's and Clausts their corollaries. Reversibility and irreversibility. Carnot cycle, reversed Caropy, principle of increase of entropy, T-s diagram, T-ds equations.	9 usius state urnot cycl 9 urface. De	3 ements- e. Claus 3 etermina	o Equival sius ine o ation of	12 lence of quality 12 drynes
with reference UNIT II Heat engine — these statemer Concept of ent UNIT III Steam - forma	cs – application to closed and open systems, internal energy, specific heat capacitic to various thermal equipment. SECOND LAW AND ENTROPY Refrigerator – Heat Pump, Second law of thermodynamics – Kelvin's and Clause their corollaries. Reversibility and irreversibility. Carnot cycle, reversed Carropy, principle of increase of entropy, T-s diagram, T-ds equations. PROPERTIES OF PURE SUBSTANCES tion and its thermodynamic properties - p-v, p-T, T-v, T-s, h-s diagrams. PVT st	9 usius state urnot cycl 9 urface. De	3 ements- e. Claus 3 etermina	o Equival sius ine o ation of	12 lence of quality 12 drynes
with reference UNIT II Heat engine — these statemer Concept of ent UNIT III Steam - forma fraction. Calcu UNIT IV	cs – application to closed and open systems, internal energy, specific heat capacitic to various thermal equipment. SECOND LAW AND ENTROPY Refrigerator – Heat Pump, Second law of thermodynamics – Kelvin's and Clause their corollaries. Reversibility and irreversibility. Carnot cycle, reversed Carropy, principle of increase of entropy, T-s diagram, T-ds equations. PROPERTIES OF PURE SUBSTANCES tion and its thermodynamic properties - p-v, p-T, T-v, T-s, h-s diagrams. PVT statation of work done and heat transfer in non-flow and flow processes using Steam	9 usius state urnot cycl 9 urface. De n Table an	3 ements- e. Claus 3 etermina nd Molli 3	dy flow O Equival sius ine O ation of ier Char	12 dence of quality 12 drynes
with reference UNIT II Heat engine — these statemer Concept of ent UNIT III Steam - forma fraction. Calcu	cs – application to closed and open systems, internal energy, specific heat capacitic to various thermal equipment. SECOND LAW AND ENTROPY Refrigerator – Heat Pump, Second law of thermodynamics – Kelvin's and Clauses their corollaries. Reversibility and irreversibility. Carnot cycle, reversed Carropy, principle of increase of entropy, T-s diagram, T-ds equations. PROPERTIES OF PURE SUBSTANCES tion and its thermodynamic properties - p-v, p-T, T-v, T-s, h-s diagrams. PVT substitution of work done and heat transfer in non-flow and flow processes using Steam STEAM POWER CYCLE	9 usius state urnot cycl 9 urface. De n Table an	3 ements- e. Claus 3 etermina nd Molli 3	dy flow O Equival sius ine O ation of ier Char	12 lence of quality 12 dryneset.
with reference UNIT II Heat engine — these statemer Concept of ent UNIT III Steam - forma fraction. Calcu UNIT IV Standard Rank UNIT V Properties of i Principle of co	cs – application to closed and open systems, internal energy, specific heat capacitic to various thermal equipment. SECOND LAW AND ENTROPY Refrigerator – Heat Pump, Second law of thermodynamics – Kelvin's and Clause their corollaries. Reversibility and irreversibility. Carnot cycle, reversed Caropy, principle of increase of entropy, T-s diagram, T-ds equations. PROPERTIES OF PURE SUBSTANCES tion and its thermodynamic properties - p-v, p-T, T-v, T-s, h-s diagrams. PVT substance of work done and heat transfer in non-flow and flow processes using Steam STEAM POWER CYCLE time cycle, Performance Improvement - Reheat cycle, regenerative cycle and their IDEAL AND REAL GASES AND THERMO DYNAMIC	9 usius state urnot cycl 9 urface. De n Table an 9 combina 9 ander Wa	3 ements- e. Claus 3 etermina d Molli 3 tion cyc 3	O Equivalusius ine O ation of ier Char O les. O ation o	12 dence of quality 12 drynes et. 12
with reference UNIT II Heat engine — these statemer Concept of ent UNIT III Steam - forma fraction. Calcu UNIT IV Standard Rank UNIT V Properties of i Principle of co	SECOND LAW AND ENTROPY Refrigerator – Heat Pump, Second law of thermodynamics – Kelvin's and Clauses their corollaries. Reversibility and irreversibility. Carnot cycle, reversed Caropy, principle of increase of entropy, T-s diagram, T-ds equations. PROPERTIES OF PURE SUBSTANCES tion and its thermodynamic properties - p-v, p-T, T-v, T-s, h-s diagrams. PVT sublation of work done and heat transfer in non-flow and flow processes using Steam STEAM POWER CYCLE time cycle, Performance Improvement - Reheat cycle, regenerative cycle and their IDEAL AND REAL GASES AND THERMO DYNAMIC RELATIONS deal and real gases, equation of state of ideal and real gases, Avogadro's law, Vorresponding states, reduced properties and compressibility chart. Exact differentic, T-ds relations, Clausius Clapeyron equations and Joule Thomson Coefficient.	9 usius state urnot cycl 9 urface. De n Table an 9 combina 9 ander Wa	3 ements- e. Claus 3 etermina d Molli 3 tion cyc 3 nal's equwell rels	O Equivalusius ine O ation of ier Char O less. O ation o ations, S	12 lence of quality 12 drynes t. 12 12 15

Text	Books:
1.	Nag. P.K, "Engineering Thermodynamics", Tata McGraw-Hill, New Delhi, 2017.
2.	Sonntag, R.E., Borgnakke, C., and Van Wylen, G.J., Fundamentals of Thermodynamics, 6th ed., John Wiley, 2003.
3.	Arora C.P, "Thermodynamics", Tata McGraw Hill, New Delhi, 2003.
4.	Venwylen and Sontag, "Classical Thermodynamics", Wiley Eastern, 1987.
Refe	rence Books:
1.	Cengel, "Thermodynamics- An Engineering Approach", 3rd Edition, Tata McGraw Hill, 2015.
2.	Merala C, Pother, Craig W and Somerton, "Thermodynamics for Engineers", Schaum Outline Series, Tata McGraw-Hill, New Delhi, 2004.

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:			
CO1	Understand the concepts of zeroth, first and second law of thermodynamics.	Remember		
CO2	Analyze the various work and heat interactions for different types of processes for closed and open systems	Evaluate		
CO3	Evaluate the different properties of pure substances using steam tables and Mollier chart	Evaluate		
CO4	Analyze the performance of steam power cycle.	Analyze		
CO5	Derive thermodynamic relations for ideal and real gases.	Analyze		

COURSE	APTICIII	ATION	MATRIY
COUNSE	ANTICUL	AIIUN	WIAINIA

COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	2	2			1					1	3	1	1
CO2	3	3	2	2			1					1	3	1	1
CO3	3	3	3	2		1	1					1	3	1	1
CO4	2	3	2	2		1	1					1	3	1	1
CO5	3	3	2	2		1	0					1	3	1	1
Avg	2.8	3	2.2	2		1	1					1	3	1	1

 $3\,/\,2\,/\,1-indicates$ strength of correlation $(3-High,\,2-Medium,\,1-Low)$

22MI	E302	FLUID MECHANICS AND MACHIN	NERY	S	EMES	TER II	I
PRE-	-REQU	ISITE:	Category	PC	Cro	edit	4
1. Eng	gineering	Physics		L	T	P	TH
_	_	Chemistry	Hours/Week	3	1	0	4
		Mathematics				Ů	•
	se Obje						
1.	-	derstand the basic concepts and properties of fluids					
2.		alyze the kinematic and dynamic concepts of fluid flow					
3.		derstand the various incompressible fluid flow through pipes					
4.		ply the principles of fluid mechanics to design and operation					
5.	1	ply the principles of fluid mechanics to design and operation		1		T	I
UN	IT I	INTRODUCTION AND FLUID STA	TICS	9	3	0	12
princip	ple.	r pressure, surface tension, Capillarity and viscosity. Fluid sta		<u> </u>		1	ı
UNI	IT II	FLUID KINEMATICS AND DYNAN	AICS	9	3	0	12
Incom	-	FLOW THROUGH PIPES AND PLA e fluid flow-Laminar flow- Hagen-Poiseuille equation, shea between parallel plates. Turbulent flow – flow through pipe	r stress, pressure grad		_		_
Incom	npressible	e fluid flow-Laminar flow- Hagen-Poiseuille equation, shea	r stress, pressure grad	lient rela	tionship	- flow t	l hrougl
hydrau	ulic grad	ient line, flow through pipes in series and parallel- Moody' oundary layer thickness, momentum thickness, energy thick	's friction factor chart	t. Power	transmis		
UNI	T IV	HYDRAULIC TURBINES		9	3	0	12
perfor	mance c	ines classification-impulse and reaction turbines-Working purves for Pelton, Francis and Kaplan turbines. Comparison ion -draft tubes.	-	_			•
UNI	IT V	HYDRAULIC PUMPS		9	3	0	12
and pr	riming. F	of hydraulic pumps-Centrifugal pumps - working principle, Reciprocating pumps - classification, working principle, incumps. Working principles of gear and vane pumps.		-	-		
			To	otal (451	L+15T)	= 60 P	eriod
Text 1	Books:						
1.		R.K., "A Textbook of Fluid Mechanics and Hydraulic Mach	nines, 9th Ed" Laxmi	Publicat	ion Pvt	Ltd. 201	0.
		R.K., "A Textbook of Fluid Mechanics and Hydraulic Mec					··
2.						,,,,	

Text	Books:
1.	Bansal, R.K., "A Textbook of Fluid Mechanics and Hydraulic Machines, 9th Ed", Laxmi Publication Pvt Ltd, 2010.
2.	Rajput, R.K., "A Textbook of Fluid Mechanics and Hydraulic Mechanics", S.Chand and Company Ltd, 2011.
3.	Subramanya. K., "Fluid Mechanics and Hydraulic Machines", Tata McGraw Hill Publishing Company Ltd, 2011.
Refe	rence Books:
1.	White, "Fluid Mechanics, 8 Ed", McGraw Hill India, 2017.
2.	Munson, Young and Okiishi, "Fundamentals of Fluid Mechanics 8 th Edition", Wiley, 2016.
3.	Yunuscengel, John. M.cimbala, "Fluid Mechanics Fundamentals and Applications", McGraw Hill, 2017.

- 4. Som, S.K, Biswas.G and SumanChakraborty, "Introduction to Fluid Mechanics and Fluid Machines", Tata McGraw Hill India, 2011.
- 5. Dr.P.N.Modi, Dr.S.M.Seth, "Hydraulics and Fluid Mechanics including Hydraulic Machines", Standard book house, 2018.

E-References:

1. NPTEL courses: http://nptel.iitm.ac.in/courses.php - web and video sources on fluid mechanics.

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:	
CO1	Understand the basic concepts and properties of fluids	Remember
CO2	Analyze the kinematic and dynamic concepts of fluid flow	Analyze
CO3	Understand the various incompressible fluid flow through pipes and between parallel plates	Understand
CO4	Apply the principles of fluid mechanics to design and operation of hydraulic turbines	Apply
CO5	Apply the principles of fluid mechanics to design and operation of hydraulic pumps	Apply

COUL	RSE A	RTICU	JLATI	ON M	ATRIX	<u> </u>									
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1	1				2				1		2	2	1
CO2	3	3	1		2								2	2	1
CO3	2	3	2	2	1								2	2	1
CO4	3	3	3	2	1	2	1						2	2	1
CO5	3	3	3	2	1	2	1						2	2	1
Avg	2.8	2.6	2	2	1.25	2	1.3				1		2	2	1
			3/2	/ 1 – inc	dicates	strengtl	h of cor	relation	1 (3 – H	[igh, 2 –]	Medium	, 1 – Lov	v)		

	IE303	MANUFACTURING PROCESSES		S	SEMES	TER I	<u> </u>
PRE	E-REQU	ISITE:	Category	PC	Cre	edit	3
1. Ba	sic scien	ce, Engineering mathematics, Engineering Physics	TT /337 1	L	Т	P	C
2. Er	ngineering	g Materials	Hours/Week	3	0	0	3
Cou	rse Obj	ectives:					
1.	To mak	te the students familiarize with various manufacturing processes	and fabrication tec	chniques	of meta	ls and de	sign of
2.	To dev	elop design concepts of various manufacturing processes.					
3.	Gain kı	nowledge to select appropriate manufacturing processes for various	ous parts.				
4.	To dev	elop an entrepreneur skill among the students.					
5.	To eval	uate and select plastic deformation processes for various parts.					
U	NIT I	CASTING		9	0	0	9
Class arc v	velding, t	of welding processes. Principles of Oxy-acetylene gas welding. ungsten inert gas welding, metal inert gas welding, plasma arc	welding, thermit w			_	_
	IT III	lding, defects in welding, Soldering and Brazing, Adhesive Bon METAL FORMING	ding.	10	0	0	10
proce	esses, Ho	t working and cold working of metals. Forging processes	man alacad and in		a dia fa		
•		t working and cold working of metals, Forging processes – of olling of metals – Types of Rolling mill – Flat strip rolling – steed and wire drawing – Tube drawing – Principles of Extrusion –	shape rolling opera	_			
Princ			shape rolling opera	_			
UN Type typic blow	IT IV es of plast al applicating – Ex	olling of metals— Types of Rolling mill — Flat strip rolling — s d and wire drawing — Tube drawing — Principles of Extrusion —	Types. Ilding of Thermopl – Blow moulding	8 lastics – Rotat	Output Defects Output Defects Output Defects Output Defects	oulding	8 les and – Film
UN Type typic blow typic	IT IV es of plast al applicating – Ex	olling of metals— Types of Rolling mill — Flat strip rolling — set and wire drawing — Tube drawing — Principles of Extrusion — SHAPING OF PLASTICS ics - Characteristics of the forming and shaping processes — Morations of - Injection moulding — Plunger and screw machines trusion - Typical industrial applications — Thermoforming — Pro-	Types. Ilding of Thermopl Blow moulding occessing of Therm	8 lastics – Rotat	Output Defects Output Defects Output Defects Output Defects	oulding	8 les and – Film
UN Type typic blow typic UN Form press	IT IV es of plast al applicated a	olling of metals— Types of Rolling mill — Flat strip rolling — set and wire drawing — Tube drawing — Principles of Extrusion — SHAPING OF PLASTICS ics - Characteristics of the forming and shaping processes — More ations of - Injection moulding — Plunger and screw machines trusion - Typical industrial applications — Thermoforming — Proteions - Compression moulding — Transfer moulding.	TALLURGY ring, Deep drawing	8 lastics – Rotatosets – 9 g, Bendi	O Working ional m Working O ng operatering a	o g princip oulding g princip outling g princip outling a princip outling to the outline outli	8 les and – Film les and 9 ypes of pacting
UN Type typic blow typic UN Form	IT IV es of plast al applicated a	standard of metals— Types of Rolling mill — Flat strip rolling — standard wire drawing — Tube drawing — Principles of Extrusion — SHAPING OF PLASTICS ics - Characteristics of the forming and shaping processes — Modations of - Injection moulding — Plunger and screw machines trusion - Typical industrial applications — Thermoforming — Proteions - Compression moulding — Transfer moulding. SHEET METAL FORMING AND POWDER METAL FORMING AND POWDER METAL Super Plastic forming; Introduction to Powder Metallurgy— Principles of Extrusion — Sheat Super Plastic forming; Introduction to Powder Metallurgy— Principles of Extrusion — Sheat Super Plastic forming; Introduction to Powder Metallurgy— Principles of Extrusion — Sheat Super Plastic forming; Introduction to Powder Metallurgy— Principles of Extrusion — Sheat Super Plastic forming; Introduction to Powder Metallurgy— Principles of Extrusion — Sheat Super Plastic forming; Introduction to Powder Metallurgy— Principles of Extrusion — Sheat Super Plastic forming; Introduction to Powder Metallurgy— Principles of Extrusion — Sheat Super Plastic forming; Introduction to Powder Metallurgy— Principles of Extrusion — Sheat Super Plastic forming; Introduction to Powder Metallurgy— Principles of Extrusion — Sheat Super Plastic forming — Principles of Extrusion — Sheat Super Plastic forming — Sheat Super P	TALLURGY ring, Deep drawing	8 lastics – Rotatosets – 9 g, Bendi	O Working ional m Working O ng operatering a	o princip oulding princip outling a princip	8 les and Film les and ypes of pacting
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Prince UN Typee typic blow typic UN Form press techn	est Books: HajraC 2005.	olling of metals— Types of Rolling mill — Flat strip rolling — set and wire drawing — Tube drawing — Principles of Extrusion — SHAPING OF PLASTICS ics - Characteristics of the forming and shaping processes — Morations of - Injection moulding — Plunger and screw machines trusion - Typical industrial applications — Thermoforming — Proteions - Compression moulding — Transfer moulding. SHEET METAL FORMING AND POWDER METAL Scheet Metal, load estimation of sheet metal processes - Sheat Super Plastic forming; Introduction to Powder Metallurgy— Productions and applications of powder metallurgy.	Types. Ilding of Thermopl Blow moulding occessing of Thermopl TALLURGY ring, Deep drawing incipal steps involving	8 lastics – Rotatosets – 9 g, Bendi ved – sin	O Working ional m Working O mg operantering a	o g princip oulding g princip	8 les and Film les and gypes o pacting eriods

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Jain. R.K., and S.C. Gupta, "Production Technology", 16th Edition, Khanna Publishers, 2001.

 $"H.M.T.\ "Production\ Technology-Handbook",\ Tata\ McGraw-Hill,\ 2000.$

SeropeKalpajian, Steven R.Schmid, "Manufacturing Processes for Engineering Materials", 4/e, Pearson Education, Inc.

Roy. A. Linberg, "Process and Materials of Manufacture", PHI, 2000.
 Mikell P. Groover, Fundamentals of Modern Manufacturing: Materials, Processes, and Systems.

E-References:

https://fdocuments.in/document/production-technology-55844 cac 00 bfc.html?page=40

COURSE OUTCOMES: Upon completion of the course, the students will be able to:					
CO1	Describe the operational features of various casting processes, design of gate, riser and discover various defects in casting.	Understand			
CO2	Explain various metal joining processes and compare them.	Understand			
соз	Summarize several types of metal forming processes and select suitable method for different applications.	Analyze			
CO4	Analyze various manufacturing methods for plastics and their needs in industry.	Analyze			
CO5	Describe various sheet metal forming processes, load estimation calculation and principles of powder metallurgy	Understand			

COURSE ARTICULATION MATRIX															
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	2	1						1			1	2	1
CO2	2	1	2	1		1			1	1			1	2	1
CO3	1	1	1	1						1			1	1	1
CO4	1	1	1		1					1			1	1	1
CO5		1							1	1			1		1
Avg	1.2	1	1.5	1	1	1			1	1			1	1.5	1
3/2/1 – indicates strength of correlation $(3 - High, 2 - Medium, 1 - Low)$															

PRE-REQUI	MATERIALS ENGINEERING		S	EMES	TER II	Ι
	SITE:	Category	ES	Cro	edit	3
1. Engineering	Physics		L	T	P	TH
2.Engineering (H	ours/Week	3	0	0	3
Course Object	etives:				I	
1. To impa	rt concept on reactions, treatment, microstructure and mechanical ure.	behavior of en	gineerin	g mater	ials at di	ifferent
2. To learn	basic principles in metallurgy and materials engineering.					
3. To ident	ity and select suitable engineering materials based on their applicat	ions				
UNIT I	PHASE DIAGRAMS		9	0	0	9
systems – Eutec	es, Phases, solid solution types, compounds, Hume- Rothery rules tic, Eutectoid, Peritectic systems. Lever rule, Equilibrium and non-eying elements – Ferrite and Austenite Stabilizers, TTT and CCT di	equilibrium coo		•	-	•
UNIT II	HEAT TREATMENT		9	0	0	9
hardening. Hea UNIT III Plain carbon ste	5	9	0	0	9	
precipitation ha	rels – Tool steels - maraging steels – HSLA steels. Stainless steels-rdened stainless steels. Types of Cast Irons- Gray cast iron, white c				-	
UNIT IV	Bronze and Cupronickel, Aluminium alloys, Bearing alloys. MECHANICAL PROPERTIES AND TESTIN	IC	9	0	0	9
	operties of engineering materials - Mechanisms of plastic deforms of fracture – Testing of materials - tension, compression and shear	ation, slip and	twinning e and cre	g – Cree	ep, Fatig	ue and
Fracture - Type	ing for hardness (Brinell, Vickers and Rockwell) - Impact test - Izo	od and Charpy.				cos une
Fracture - Type			9	0	0	9
Fracture - Type its effects – test UNIT V Non-Destructive inspection and	ing for hardness (Brinell, Vickers and Rockwell) - Impact test - Izo NON-DESTRUCTIVE TESTING AND SURFA	CE esting, Ultraso – Definition, d	9 onic test	ing, Ma	gnetic p	9
Fracture - Type its effects – test UNIT V Non-Destructive inspection and	NON-DESTRUCTIVE TESTING AND SURFA ENGINEERING e Testing: Basic principles, Testing method - Radiographic T Liquid penetrant inspections. Introduction to surface engineering	CE esting, Ultraso – Definition, d	9 onic testiliffusion ics.	ing, Ma techniq	gnetic p	9 particle
Fracture - Type its effects – test UNIT V Non-Destructive inspection and	NON-DESTRUCTIVE TESTING AND SURFA ENGINEERING e Testing: Basic principles, Testing method - Radiographic T Liquid penetrant inspections. Introduction to surface engineering	CE esting, Ultraso – Definition, d	9 onic testiliffusion ics.	ing, Ma techniq	gnetic pues, dep	9 particle
Fracture - Type its effects – test UNIT V Non-Destructive inspection and methods, high a Text Books:	NON-DESTRUCTIVE TESTING AND SURFA ENGINEERING e Testing: Basic principles, Testing method - Radiographic T Liquid penetrant inspections. Introduction to surface engineering	esting, Ultraso Definition, d ontact mechani	9 onic testiliffusion ics. Tota	ing, Matechniq	gnetic pues, dep	9 particle
Fracture - Type its effects – test UNIT V Non-Destructive inspection and methods, high at the second seco	NON-DESTRUCTIVE TESTING AND SURFA ENGINEERING e Testing: Basic principles, Testing method - Radiographic T Liquid penetrant inspections. Introduction to surface engineering and low energy beam methods, surface engineering charts, elastic c	esting, Ultraso Definition, dontact mechanic	9 onic testiliffusion ics. Tota	ing, Matechniq	gnetic pues, dep	9 particle
Fracture - Type its effects – test UNIT V Non-Destructive inspection and methods, high at a second	NON-DESTRUCTIVE TESTING AND SURFA ENGINEERING e Testing: Basic principles, Testing method - Radiographic T Liquid penetrant inspections. Introduction to surface engineering and low energy beam methods, surface engineering charts, elastic c G. Budinski and Michael K. Buinski, "Engineering Materials", Pro-	esting, Ultraso Definition, d ontact mechani entice Hall of In	9 onic testiliffusion ics. Tota ndia Ltd	ing, Matechniq	gnetic pues, dep	9 particle
Fracture - Type its effects – test UNIT V Non-Destructive inspection and methods, high a second se	NON-DESTRUCTIVE TESTING AND SURFA ENGINEERING e Testing: Basic principles, Testing method - Radiographic T Liquid penetrant inspections. Introduction to surface engineering and low energy beam methods, surface engineering charts, elastic c G. Budinski and Michael K. Buinski, "Engineering Materials", Pron, V, "Materials Science and Engineering", Prentice Hall of India (1997).	esting, Ultraso Definition, dontact mechanic entice Hall of In (P) Ltd., 1999. ew Delhi, 2001	9 onic testiliffusion ics. Tota ndia Ltd	ing, Matechniq	gnetic pues, dep	9 particle

Sydney.H.Avner, "Introduction to Physical Metallurgy" Mc Graw Hill Book Company, 1994.

	RSE OUTCOMES: completion of the course, the students will be able to:	Bloom's Taxonomy Mapped			
CO1	Understand the formation of materials and their classification based on atomic structure.				
CO2	Understand the principles of various heat treatment processes in fabrication industry.	Understand			
соз	Describe properties, applications and types of various ferrous and non-ferrous metals used in fabrication industry	Understand			
CO4	Describe various types of failure and select methods for destructive testing	Understand			
CO5	Select methods for Non-destructive testing	Evaluate			

COUL	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	1	2	2	1	1	1						2	3	1
CO2	1		2	1	1	2	1						2	3	1
CO3		1	1	1	1		1						3	2	1
CO4		2	2	1	1	1	1						2	3	1
CO5		2	2	2	1		1						2	2	1
Avg	1	1.5	1.8	1.4	1.0	1.3	1						2.2	2.6	1.0
			3/2	/ 1 – inc	dicates	strengtl	h of cor	relatio	n (3 – H	(igh, 2 – 1	Medium	, 1 – Low	7)		

22M	CIN02	INNOVATION SPRINTS		S	EMES	TER II	I
PRE	-REQUI	SITE:	Category	EE	Cro	edit	1
			Harry /Wash	L	T	P	TH
			Hours/Week	0	0	2	2
Cour	se Obje	ctives:				•	
1.	To unde	erstand the fundamentals of Design thinking and apply in ideation	ng solutions for rea	al-world	problem	ıs.	
2.	To solve	e challenges through problem curation, problem validation and	customer discover	y proble	ms.		_
UN	I TI	CHALLENGE CURATION		0	6		
		Design Thinking Principles - Design Thinking Values - Design sign challenge.	n Thinking Metho	ds - Cha	allenge i	mpact s	etting -
UN	IT II	CUSTOMER-CENTRIC INNOVATION	N	0	0	6	6
	_	Customer needs - Empathy building techniques - gap analysing ights into Innovation Opportunities	s - adoption barrie	ers - obse	ervation	s and in	sights -
UN	IT III	IDEA GENERATION		0	0	6	6
		ns & gains - crafting value proposition - Ideation - Divergent Theks - Concept of minimum usable prototypes - Generating solution	Ü	nethods-	Rules o	f brainst	orming
UN	IT IV	PROTOTYPING		0	0	6	6
	typing cor	ncepts Palm Pilot Experiment - Fake it before make it - Proto- cototypes	typing - The Law o	of Failure	e - Build	ling a Pr	ototype
UN	IT V	PITCH & PRESENTATION		0	0	6	6
		y telling - the blueprint for story telling - Pitch Script - Pitch Prenication fundamentals	sentations - Best p	ractices t	o creatii	ng a com	pelling
				Tota	l (30P)	= 30 P	eriods

Text	Books:
1.	Tim Brown (2019), "Change by Design: How design thinking transforms organizations and inspires innovation"
2.	Jan Chipchase& Simon Steinhardt (2013), "Hidden in Plain Sight: How to Create extraordinary Products for Tomorrow's Customers", Harper Business 2013
3.	Christian Madsbjerg & Mikkel B. Rasmussen (2014), "The Moment of Clarity", Harvard Business Review Press
4.	IdrisMootee(2013), Design Thinking for Strategic Innovation, Willey
5.	Alexander Osterwalder, Value Proposition Design: How to Create Products and Services Customers Want (Strategyzer) John Wiley & Sons, 2014
Refe	rence Books:
1.	Avoia. Alberto, 2009 The Pretotyping Manifesto -
2.	https://sites.google.com/a/pretotyping.org/www/the-pretotyping-manifesto
3.	Jazz Factory, All about Presentations - http://blog.jazzfactory.in/
4.	Pretotyping Methodology - https://www.pretotyping.org/methodology.html

	RSE OUTCOMES: completion of the course, the students will be able to:	Bloom's Taxonomy Mapped			
CO1	Identify real-world problems	Understand			
CO2	Apply the challenge curation techniques to real-world problems.				
CO3	Analyze the problems and generate solutions to address the challenges	Analyze			
CO4	Build solutions using prototyping tools & techniques	Apply			
CO5	Develop an innovation pitch to effectively communicate the idea to solve the identified problem	Analyze			

COUL	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	0	3	0	0	0	2	1	0	2	0	0	0	0	0	2
CO2	0	3	0	2	0	0	0	0	2	0	0	0	0	0	2
CO3	0	0	3	2	0	0	0	0	2	0	0	0	0	0	2
CO4	2	0	3	0	0	0	0	1	2	0	0	0	0	0	2
CO5	0	0	0	0	0	0	0	0	2	3	0	0	0	0	2
Avg	2	3	2	2	0	2	1	1	2	3	0	0	0	0	2
		3 / 2 / 1 – indicates strength of correlation (3 – High, 2 – Medium, 1 – Low)													

22NC301	NCC COURSE-II (Only for NCC Stude	ents)	S	EMES	TER II	I				
PRE-REQUI	SITE:	Category	NC	Cro	edit	3				
		** /**	L	Т	P	TH				
		Hours/Week	3	0	0	3				
Course Object	ctives:									
1. To main	tain the unity and disciplines to the students									
UNIT I	SOCIAL SERVICE & COMMUNITY DEVEI	LOPMENT	9	0	0	9				
- Civic Respon	service and it's need - Rural Development Program – NGOs Insibilities – Causes & prevention of AIDS/HIV – Counter Ten Organization – Anti Drunken Driving.		-	-		_				
UNIT II	GENERAL AWARENESS & ADVENT	URE	9	9 0 0						
	edge $-$ Logical & Analytical Reasoning - Modes of Entry to A Rock climbing $-$ Cycling and Trekking.	Army, CAPF, Police	e – SSB 1	Procedu	re; Para	Sailing				
UNIT III	AEROENGINES & NAVIGATION	T	9	0	0	9				
engines – Bray	aero engines and its type – Components of aero engines – Fiton Cycle – Turbo prop engines and its types; Requirements of in map – Scales of map – Map reading procedure and its aids	of Navigation - Line			_	-				
UNIT IV	AIRFRAME & METEOROLOGY		9	0	0	9				
	l – Primary and Secondary –Fuselage – Main Plain and Tail Pla METT in Aviation – Atmosphere – Clouds and Precipitation –		ators& R	Rudders -	-Landin	g Gear;				
UNIT V	FLIGHT INSTRUMENTS & AEROMODE	ELLING	9	0	0	9				
-	ator – Altimeter – Artificial Horizon – Radar and Its Type – In sic Materials & Tools – Types of Aero Modelling – Flying/Bu	•		-	•					
			Tota	l (45L)	= 45 P	eriods				

	SE OUTCOMES: mpletion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Acquired knowledge about social and legal responsibilities.	Understand
CO2	Understand the adventure activities and verbal training on defense examinations.	Remember and Understand
CO3	Understand the technical knowledge on aero engines and map reading.	Understand
CO4	Understand the structure and control of an aircraft.	Understand
CO5	Understand and learn the importance of avionic instruments on aircraft control.	Remember and Understand

COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1	0	0	0	0	0	0	0	0	0	0	3	1	1
CO2	3	3	2	3	0	0	0	0	0	0	0	0	3	2	1
CO3	3	2	3	1	0	2	0	0	0	0	0	0	3	2	1
CO4	3	2	2	2	0	0	0	0	0	0	0	0	3	2	1
CO5	3	0	0	0	0	1	0	0	0	0	0	0	3	3	1
Avg	3	2	1.4	2	0	1.5	0	0	0	0	0	0	3	2	1

3/2/1 – indicates strength of correlation (3 - High, 2 - Medium, 1 - Low)

22ME304	CAD LABORATORY		S	SEMESTER III					
PRE-REQU	ISITE:	Category	PC	1.5					
1. Engineering	Drawing	II ourse/XV ook	L	T	P	TH			
2. Machine Di	awing	Hours/Week	0	0	3	3			

Course Objectives:

- 1. Understand the Code of drawing practice as per BIS conventions for mechanical elements using CAD software.
- 2. Practice the methods for sectioning and drawing the joints, couplings, bearings, and keys.
- 3. Prepare assembly drawings, sectional views and bill of materials for selected assemblies.

CAD EXPERIMENTS

The students will be required to carry out the following exercises using software packages (e.g. 3D modeling package / Pro Engineer/ CATIA /I-Deas/ Solid Edge/Solid Works etc.)

- Introduction to advanced modeling software
- Part Modeling of Screw Jack
- Part Modeling of Flange Coupling
- Part Modeling of Plummer Block
- Part Modeling of Knuckle Joint
- Creation of 3D assembly model of universal joint
- Creation of 3D assembly model of connecting rod
- Creation of 3D assembly model of crankshaft
- Creation of 3D assembly model of Lathe Tailstock
- Creation of 3D assembly model of Piston.
- Creation of 3D assembly model of Safety valve.
- Detailing of Lathe Tailstock

Total (45P) = 45 Periods

	SE OUTCOMES: mpletion of the course, the students will be able to:	Bloom's Taxonomy Mapped				
CO1	Describe how CAD technology can be leveraged in the design process and the basic and advanced features available with CAD software					
CO2	Design a part or assembly of parts using Computer-Aided Design software.	Create				
СО3	Design a detailed view of part or assembly of parts using Computer-Aided Design software.	Create				

COUL	COURSE ARTICULATION MATRIX														
CO/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	1	2	3		1				2		2	2	1
CO2	1	1	1	1	3		1				0		2	2	1
CO3	2	2	2	1	2		1				1		2	2	1
Avg	1.6	1.6	1.33	1.33	2.6		1				1		2	2	1

22CE308	STRENGTH OF MATERIALS AND FLUID ME LABORATORY	CHANICS	SEMESTER III				
PRE-REQU	JISITE:	Category	ES	Cr	edit	1.5	
Strength of M		House/Wook	L	Т	P	TH	
Fluid Mechar	nics	Hours/Week	0	0	3	3	

Course Objectives:

- 1. To analyze structural members subjected to tension, compression and bending using the fundamental concepts of stress, strain and elastic behavior of materials.
- 2. To Study about Pump and Turbine.

STRENGTH OF MATERIAL LABORATORY EXERCISES

- 1. Double shear test on mild steel rod
- 2. Tension Test on mild steel rod
- 3. Test of springs (Open coil and closed coil)
- 4. Impact test on a metallic specimen (Izod and Charpy Impact test)
- 5. Hardness tests on metallic specimen (Brinell / Rockwell)
- 6. Bending deflection test on beams

FLUID MECHANICS LABORATORY EXERCISES

- 1. Determination of Friction factor of pipes
- 2. Performance characteristics of Kaplan Turbine
- 3. Determination of the coefficient of discharge of orifice meter
- 4. Determination of the coefficient of discharge of venturi meter
- 5. Conducting experiments and drawing the characteristics curves of centrifugal pump
- 6. Conducting experiments and drawing the characteristics curves of reciprocating pump
- 7. Conducting experiments and drawing the characteristics curves of gear pump

Total (45P) = 45 Periods

	SE OUTCOMES: mpletion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Learn the various techniques of testing methods for materials	Understand
CO2	Perform test and identify the different characteristics of materials.	Evaluate
CO3	Perform experiments on hydraulic machines to draw the performance characteristics.	Evaluate

COUF	COURSE ARTICULATION MATRIX														
CO/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	1	1					1				1	1	3
CO2	1	2	1	1					1				2	1	2
CO3	1	2	2	2					1				2	1	3
Avg	1	2	1.33	1.33					1				1.66	1	2.6
			3/2	/ 1 – inc	dicates	strengtl	of cor	relation	1 (3 – H	igh, 2 – I	Medium,	1 – Low)		

SEMESTER-IV

22ME401	KINEMATICS OF MACHINERY		S	EMES	STER I	V
PRE-RE(QUISITE:	Category	PC	Cr	edit	4
1. Engineeı	ing Graphics.	TT /XX/ 1	L	Т	P	TH
2.Engineer	ng Mechanics	Hours/Week	3	1	0	4
Course O	bjectives:				•	•
1. To u	nderstand the basic components and layout of linkages in the assem	nbly of a system/ ma	achine.			
	inderstand the principles in analyzing the assembly with respect to t in a link of a mechanism.	the displacement, v	elocity,	and acc	eleration	at an
3. To u	nderstand basics of cam profile and its displacement.					
4. To u	nderstand the basic concepts of toothed gearing and kinematics of g	gear trains.				
5. Illus	trate the effects of friction drives in transmission system.					
UNIT I	BASICS OF MECHANISMS		9	3	0	12
inversions some comm	on of mechanisms- Basic kinematic concepts and definitions- Degree of four bar chain and slider-crank chains Limit positions- Mechanism on mechanisms- Quick return mechanism, straight-line generators-	cal advantage - Tra	nsmissio ocker Me	n angle- echanisi	- Descripns.	otion (
UNIT II	KINEMATIC ANALYSIS		9	3	0	12
UNIT II	or motion and path generation. KINEMATICS OF CAM		9	3	0	12
UNIT III	<u> </u>	_	form velo	ocity, pa	arabolic,	simpl
UNIT III Classificati harmonic a	KINEMATICS OF CAM on of cams and followers- Terminology and definitions- Displacer	tour cams circular a	form velo	ocity, pa	arabolic, - pressur	simp
UNIT III Classificati harmonic a	KINEMATICS OF CAM on of cams and followers- Terminology and definitions- Displacer and cycloidal motions- derivatives of follower motions- specified con atting, sizing of cams, graphical and analytical disc cam profile synt	tour cams circular a	form velo	ocity, pa	arabolic, - pressur	simple angi
UNIT III Classificati harmonic a and underc UNIT IV	KINEMATICS OF CAM on of cams and followers- Terminology and definitions- Displacer and cycloidal motions- derivatives of follower motions- specified con atting, sizing of cams, graphical and analytical disc cam profile synt GEARS AND GEAR TRAINS d cycloidal gear profiles, gear parameters, fundamental law of geari	ttour cams circular a thesis for roller and ng and conjugate ac	form velound tange flat face	ocity, pa nt cams Follow 3	arabolic, - pressur ers.	simple ang.
UNIT III Classificati harmonic a and underc UNIT IV Involute an interference	KINEMATICS OF CAM on of cams and followers- Terminology and definitions- Displacer and cycloidal motions- derivatives of follower motions- specified con atting, sizing of cams, graphical and analytical disc cam profile synt GEARS AND GEAR TRAINS d cycloidal gear profiles, gear parameters, fundamental law of geari e/undercutting- helical, bevel, worm, rack & pinion gears, epicyclic	ttour cams circular a thesis for roller and ng and conjugate ac and regular gear tra	form velound tange flat face 9 etion, sputin kinem	ocity, part cams Follow 3 Ir gear chatics.	arabolic, - pressur ers. 0 ontact ra	tio an
UNIT III Classificati harmonic a and underc UNIT IV Involute an interference	KINEMATICS OF CAM on of cams and followers- Terminology and definitions- Displacer and cycloidal motions- derivatives of follower motions- specified con atting, sizing of cams, graphical and analytical disc cam profile synt GEARS AND GEAR TRAINS d cycloidal gear profiles, gear parameters, fundamental law of geari e/undercutting- helical, bevel, worm, rack & pinion gears, epicyclic FRICTION IN MACHINE ELEMENT	ttour cams circular a thesis for roller and ng and conjugate ac and regular gear tra	form velound tange flat face 9 etion, sputin kinem	pocity, part cams Follow Transpart gear chatics.	arabolic, - pressur ers. 0 ontact ra	simple ang
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UNIT III Classificati harmonic a and underc UNIT IV Involute an interference UNIT V Surface con	KINEMATICS OF CAM on of cams and followers- Terminology and definitions- Displacer and cycloidal motions- derivatives of follower motions- specified con atting, sizing of cams, graphical and analytical disc cam profile synt GEARS AND GEAR TRAINS d cycloidal gear profiles, gear parameters, fundamental law of geari e/undercutting- helical, bevel, worm, rack & pinion gears, epicyclic FRICTION IN MACHINE ELEMENT attacts- sliding and rolling friction- friction drives- friction in screw the	thesis for roller and ng and conjugate ac and regular gear tra S hreads – bearings ar	form velound tange flat face 9 etion, sputin kinem	r gear chatics.	ontact ra 0 iction Cl	simple ang
UNIT III Classificati harmonic a and underc UNIT IV Involute an interference UNIT V Surface con	KINEMATICS OF CAM on of cams and followers- Terminology and definitions- Displacer and cycloidal motions- derivatives of follower motions- specified con atting, sizing of cams, graphical and analytical disc cam profile synt GEARS AND GEAR TRAINS d cycloidal gear profiles, gear parameters, fundamental law of geari e/undercutting- helical, bevel, worm, rack & pinion gears, epicyclic FRICTION IN MACHINE ELEMENT attacts- sliding and rolling friction- friction drives- friction in screw the	thesis for roller and ng and conjugate ac and regular gear tra S hreads – bearings ar	form velound tange flat face 9 etion, sputin kinem 9 and lubrica	r gear chatics.	ontact ra 0 iction Cl	simple ang
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UNIT III Classification to the content of the conte	KINEMATICS OF CAM on of cams and followers- Terminology and definitions- Displacer and cycloidal motions- derivatives of follower motions- specified con atting, sizing of cams, graphical and analytical disc cam profile synt GEARS AND GEAR TRAINS d cycloidal gear profiles, gear parameters, fundamental law of geari Audientity of the cycloidal gear, epicyclic FRICTION IN MACHINE ELEMENT attacts- sliding and rolling friction- friction drives- friction in screw the drives- friction in brakes.	ntour cams circular at thesis for roller and ng and conjugate ac and regular gear traces. Shreads – bearings ar Tournay Ltd., New Do	form velound tange flat face 9 etion, sputin kinem 9 ad lubrica otal (451	ocity, pant cams Follow 3 or gear chatics. 3 ortion-fr	ontact ra 0 iction Cl 1 = 60 P	simple ang
UNIT III Classificati harmonic a and underc UNIT IV Involute an interference UNIT V Surface con belt and rop Text Bool 1. Ra 2. Gl	KINEMATICS OF CAM on of cams and followers- Terminology and definitions- Displacer and cycloidal motions- derivatives of follower motions- specified con atting, sizing of cams, graphical and analytical disc cam profile synt GEARS AND GEAR TRAINS d cycloidal gear profiles, gear parameters, fundamental law of gearing elundercutting- helical, bevel, worm, rack & pinion gears, epicyclic FRICTION IN MACHINE ELEMENT attacts- sliding and rolling friction- friction drives- friction in screw the drives- friction in brakes. Extra S.S, "Theory of Machines", Tata McGraw Hill Publishing Controls, A and Mallick, A.K, "Theory of Mechanisms and Machines",	ntour cams circular at thesis for roller and ng and conjugate ac and regular gear traces. Shreads – bearings ar Tournay Ltd., New Do	form velound tange flat face 9 etion, sputin kinem 9 ad lubrica otal (451	ocity, pant cams Follow 3 or gear chatics. 3 ortion-fr	ontact ra 0 iction Cl 1 = 60 P	simple ang
UNIT III Classificati harmonic a and underc UNIT IV Involute an interference UNIT V Surface con belt and rop Text Bool 1. Ra 2. Gl Reference	KINEMATICS OF CAM on of cams and followers- Terminology and definitions- Displacer and cycloidal motions- derivatives of follower motions- specified con atting, sizing of cams, graphical and analytical disc cam profile synt GEARS AND GEAR TRAINS d cycloidal gear profiles, gear parameters, fundamental law of gearing elundercutting- helical, bevel, worm, rack & pinion gears, epicyclic FRICTION IN MACHINE ELEMENT attacts- sliding and rolling friction- friction drives- friction in screw the drives- friction in brakes. Extra S.S, "Theory of Machines", Tata McGraw Hill Publishing Controls, A and Mallick, A.K, "Theory of Mechanisms and Machines",	ng and conjugate ac and regular gear tra S hreads – bearings ar To npany Ltd., New Do East-West Pvt. Ltd	form velound tange flat face 9 etion, sputin kinem 9 ad lubrica otal (451	ocity, pant cams Follow 3 or gear chatics. 3 ortion-fr	ontact ra 0 iction Cl 1 = 60 P	simple ang
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UNIT III Classification harmonic and underce UNIT IV Involute and interference UNIT V Surface control belt and rope Text Bool 1. Ra 2. Gl Reference 1. Th 2. Ra	KINEMATICS OF CAM on of cams and followers- Terminology and definitions- Displacer and cycloidal motions- derivatives of follower motions- specified con atting, sizing of cams, graphical and analytical disc cam profile synt GEARS AND GEAR TRAINS d cycloidal gear profiles, gear parameters, fundamental law of gearite/ cyundercutting- helical, bevel, worm, rack & pinion gears, epicyclic FRICTION IN MACHINE ELEMENT attacts- sliding and rolling friction- friction drives- friction in screw the drives- friction in brakes. Extra S.S, "Theory of Machines", Tata McGraw Hill Publishing Con anosh, A and Mallick, A.K, "Theory of Mechanisms and Machines", Books: omas Bevan, "Theory of Machines", CBS Publishers and Distributed.	thesis for roller and ng and conjugate ac and regular gear tra S hreads – bearings ar To mpany Ltd., New Do East-West Pvt. Ltc ors, 1984. y- Eastern Ltd., New	form velound tange flat face 9 etion, sputin kinem 9 ad lubrica otal (45) elhi, 1998 l., New I	pocity, part cams Follow 3 or gear chatics. 3 ation-fr L+15T) 3. Delhi, 19	ontact ra 0 iction Cl 1 = 60 P	simple ang
UNIT III Classificati harmonic a and underc UNIT IV Involute an interference UNIT V Surface cor belt and rop Text Bool 1. Ra 2. Gl Reference 1. Th 2. Ra 3. Er	KINEMATICS OF CAM on of cams and followers- Terminology and definitions- Displacer and cycloidal motions- derivatives of follower motions- specified con atting, sizing of cams, graphical and analytical disc cam profile synt GEARS AND GEAR TRAINS d cycloidal gear profiles, gear parameters, fundamental law of geari e/undercutting- helical, bevel, worm, rack & pinion gears, epicyclic FRICTION IN MACHINE ELEMENT attacts- sliding and rolling friction- friction drives- friction in screw the attacts- friction in brakes. ASS: attan S.S., "Theory of Machines", Tata McGraw Hill Publishing Con attacts, A and Mallick, A.K, "Theory of Mechanisms and Machines", a Books: comas Bevan, "Theory of Machines", CBS Publishers and Distribute a J.S and Dukkipati R.V, "Mechanism and Machine Theory", Wile	ng and conjugate ac and regular gear tra S hreads – bearings ar To mpany Ltd., New Do East-West Pvt. Ltc ors, 1984. y- Eastern Ltd., New thesis", Vol.I, PHI I	form velound tange flat face 9 etion, sputin kinem 9 ad lubrica otal (451 elhi, 1998 d., New I	pocity, part cams Follow 3 or gear chatics. 3 ation-fr L+15T) 3. Delhi, 19	ontact ra 0 iction Cl 1 = 60 P	simple angle 12 tio and 12 utches

E-References:

5.

1. https://archive.nptel.ac.in/courses/112/104/112104121/

John Hannah and Stephens R C, "Mechanisms of Machines", Viva Low Price Student Edition, New Delhi, 1999.

2.	https://nptel.ac.in/courses/112106270
3.	http://velhightech.com/Documents/ME8492 Kinematics of Machinery.pdf

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:						
CO1	CO1 Demonstrate and understand the concepts of various mechanisms and pairs.						
CO2	Analyze the velocity and acceleration of simple mechanisms.	Analyze					
СОЗ	Construct the cam profile for various motion.	Create					
CO4	Solve problems on gears and gear trains.	Evaluate					
CO5	Evaluate the friction in transmission system	Evaluate					

COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	1									3	1	
CO2	3	2	2	1									3	1	
CO3	3	2	2	1									3	1	
CO4	3	2	2	1									3	1	
CO5	3	2	2	1									3	1	
Avg	3	2	2	1									3	1	

 $3\,/\,2\,/\,1$ – indicates strength of correlation (3 – High, 2 – Medium, 1 – Low)

		THERMAL ENGINEERING					
22M	E402	(Use of standard thermodynamic tables, Mollier diagram, Psy and Refrigerant property tables are permitted in the exc		S	EMES	STER I	V
PRE	-REQU	ISITE:	Category	PC	Cr	edit	4
			Hours/Week	L	T	P	TH
			Hours/ week	3	1	0	4
Cou	rse Obje	ectives:					
1.	To teac	h the construction and working of IC engine and basics on gas po	ower cycles.				
2.	To acqu	uaint the concepts of nozzle, turbine and draw velocity triangle for	or a turbine, calcula	te work o	done and	d efficie	ncy.
3.		erstand the construction and working of all types compressor cating compressor.	and calculate the	work do	ne and	efficien	cy of
4.	To prov	vide knowledge concept of psychrometry and its processes.					
5.	To acqu	uaint knowledge of refrigeration cycles and calculation of COP a	and RE				
UN	UNIT I INTERNAL COMBUSTION ENGINES AND GAS POWER CYCLES				3	0	12
two s	stroke and	of IC engine, IC engine components and functions. Valve timing four stroke engines, Actual and theoretical P-V diagram of two Dual, Brayton cycles, Calculation of mean effective pressure and	and four stroke en	ngines, Pe	_	-	
two s Otto, UN Flow Impu	of steam	of IC engine, IC engine components and functions. Valve timing four stroke engines, Actual and theoretical P-V diagram of two	o and four stroke en air standard efficien by pressure ratio, sup	ngines, Pency. 9 persatura	3 ted flow	0 w. Princi	12
two s Otto, UN Flow Impu turbin	of steam	of IC engine, IC engine components and functions. Valve timing four stroke engines, Actual and theoretical P-V diagram of two dual, Brayton cycles, Calculation of mean effective pressure and STEAM NOZZLES AND TURBINES at through nozzles, shapes of nozzles, effect of friction, critical	o and four stroke en air standard efficien by pressure ratio, sup	ngines, Pency. 9 persatura	3 ted flow	0 w. Princi	12
two s Otto, UN Flow Impu turbin UN Class Isoth	of steam lse and R nes.	of IC engine, IC engine components and functions. Valve timing four stroke engines, Actual and theoretical P-V diagram of two dual, Brayton cycles, Calculation of mean effective pressure and STEAM NOZZLES AND TURBINES at through nozzles, shapes of nozzles, effect of friction, critical Reaction Turbines, Compounding of Impulse Turbines. Velocity	o and four stroke en air standard efficients I pressure ratio, sup y Diagrams, work	ngines, Penncy. 9 persatura done and 9 earance,	3 ted flow d efficient Volume	0 w. Princiency for 0 etric effi	12 simple ciency
two s Otto, UN Flow Impu turbin UN Class Isothe Rotan	of steam lse and R nes.	of IC engine, IC engine components and functions. Valve timing four stroke engines, Actual and theoretical P-V diagram of two dual, Brayton cycles, Calculation of mean effective pressure and STEAM NOZZLES AND TURBINES at through nozzles, shapes of nozzles, effect of friction, critical Reaction Turbines, Compounding of Impulse Turbines. Velocity AIR COMPRESSOR and comparison, working principle, work of compression - wiciency and Isentropic efficiency. Multistage air compressor with	o and four stroke en air standard efficients I pressure ratio, sup y Diagrams, work	ngines, Penncy. 9 persatura done and 9 earance,	3 ted flow d efficient Volume	0 w. Princiency for 0 etric effi	12 iples simp 12 icienc
two s Otto, UN Flow Impu turbin UN Class Isoth Rotar UN Psycl	of steam alse and Rulse an	of IC engine, IC engine components and functions. Valve timing four stroke engines, Actual and theoretical P-V diagram of two dual, Brayton cycles, Calculation of mean effective pressure and STEAM NOZZLES AND TURBINES in through nozzles, shapes of nozzles, effect of friction, critical Reaction Turbines, Compounding of Impulse Turbines. Velocity AIR COMPRESSOR and comparison, working principle, work of compression - wicciency and Isentropic efficiency. Multistage air compressor with reciprocating air compressors. PSYCHROMETRY properties - Property calculations using Psychrometric chart chart - adiabatic saturation, sensible heating and cooling, humidity	o and four stroke en air standard efficient pressure ratio, sup y Diagrams, work with and without cle Intercooling. Work	persatura done and 9 earance, ting prince 9 Psychron	3 ted flow d efficient Volume ciple and	O w. Principle of the processes	12 s using
two s Otto, UN Flow Impu turbin UN Class Isoth Rotar UN Psycl adiab	of steam and Rulse and Rul	of IC engine, IC engine components and functions. Valve timing four stroke engines, Actual and theoretical P-V diagram of two dual, Brayton cycles, Calculation of mean effective pressure and STEAM NOZZLES AND TURBINES in through nozzles, shapes of nozzles, effect of friction, critical Reaction Turbines, Compounding of Impulse Turbines. Velocity AIR COMPRESSOR and comparison, working principle, work of compression - wicciency and Isentropic efficiency. Multistage air compressor with reciprocating air compressors. PSYCHROMETRY properties - Property calculations using Psychrometric chart chart - adiabatic saturation, sensible heating and cooling, humidity	o and four stroke en air standard efficient pressure ratio, sup y Diagrams, work with and without cle Intercooling. Work	persatura done and 9 earance, ting prince 9 Psychron	3 ted flow d efficient Volume ciple and	O w. Principle of the processes	12 s using
two s Otto, UN Flow Impu turbin UN Class Isoth Rotan UN Psycl adiab UN	of steam alse and Rules and Rules. IT III Sification ermal efficiency compresion in the compresion in the company of the com	of IC engine, IC engine components and functions. Valve timing four stroke engines, Actual and theoretical P-V diagram of two dual, Brayton cycles, Calculation of mean effective pressure and STEAM NOZZLES AND TURBINES in through nozzles, shapes of nozzles, effect of friction, critical Reaction Turbines, Compounding of Impulse Turbines. Velocity AIR COMPRESSOR and comparison, working principle, work of compression - wicciency and Isentropic efficiency. Multistage air compressor with reciprocating air compressors. PSYCHROMETRY properties - Property calculations using Psychrometric chart chart - adiabatic saturation, sensible heating and cooling, humiding.	o and four stroke en air standard efficient in air standard efficient in a pressure ratio, sury Diagrams, work with and without cloud intercooling. Work it and expressions. In a control of the control	persatura done and 9 earance, ting prince 19 Psychronication, 6 9 t and subtractions and 19	3 ted flow defficients 3 Volume in the properties of the proper	o v. Principle of the processes tive cool g, perfo	12 iples of simple 12 iciencirison of 12 s using an 12 rmano
two s Otto, UN Flow Impu turbin UN Class Isoth Rotar UN Psycl adiab UN Vapo	of steam alse and Rules and Rules. IT III Sification ermal efficiency compresion in the compresion in the company of the com	of IC engine, IC engine components and functions. Valve timing a four stroke engines, Actual and theoretical P-V diagram of two dual, Brayton cycles, Calculation of mean effective pressure and STEAM NOZZLES AND TURBINES at through nozzles, shapes of nozzles, effect of friction, critical Reaction Turbines, Compounding of Impulse Turbines. Velocity AIR COMPRESSOR and comparison, working principle, work of compression - wicciency and Isentropic efficiency. Multistage air compressor with reciprocating air compressors. PSYCHROMETRY properties - Property calculations using Psychrometric chart chart - adiabatic saturation, sensible heating and cooling, humiding. REFRIGERATION SYSTEMS	o and four stroke en air standard efficient is a pressure ratio, sure y Diagrams, work with and without clear Intercooling. Work it and expressions. In ification, dehumidiff tressures, super heat ween vapour compressions.	persatura done and 9 earance, ting prince 19 Psychronication, 6 9 t and subtractions and 19	3 ted flow defficients 3 Volume iple and sevaporate approach absorption of the cooling description	O v. Principle of the company of the company of the control of the contr	12 liples simp 12 liciencerison 12 s using an litems.

Tex	t Books:
1.	Rajput.R.K, "Thermal Engineering", S. Chand Publishers, 2000.
2.	Rudramoorthy.R, "Thermal Engineering", Tata McGraw Hill, New Delhi, 2003.
3.	Kothandaraman, C.P., Domkundwar.S, and Domkundwar.A.V, "A Course in Thermal Engineering", Dhanpat Rai and Sons, 5 th Edition, 2002.
4.	Sarkar B.K, "Thermal Engineering", Tata McGraw Hill, 1998
Ref	erence Books:
1.	Holman. J.P., "Thermodynamics", McGraw Hill, 1985.
2.	Arora.C.P, "Refrigeration and Air Conditioning", TMH, 1994.

	E OUTCOMES: mpletion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Analyze the performance parameters in IC engines and air standard cycles.	Analyze
CO2	Analyze the performance of steam nozzle and turbines and understand the concepts of compounding.	Analyze
СОЗ	Evaluate the performance parameters of an air compressor.	Evaluate
CO4	Apply the principles of psychrometry for air-conditioning processes.	Apply
CO5	Analyze the vapour compression refrigeration cycle and evaluate COP and refrigerating effect.	Analyze

COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1											3	1	1
CO2	3	3	2	3									3	2	1
CO3	3	2	3	1		2							3	2	1
CO4	3	2	2	2									3	2	1
CO5	3					1							3	3	1
Avg	3	2	2.3	2		1.5							3	2	1

 $3\,/\,2\,/\,1-indicates$ strength of correlation (3-High,2-Medium,1-Low)

22ME	403	METAL CUTTING AND MACHINE TO	OLS	S	SEMES	TER I	V					
PRE-I	REQUI	SITE:	Category	PC	Cr	edit	3					
Introdu	iction to	Materials, force analysis		L	Т	P	TH					
		processes and Engineering physics.	Hours/Week	3	0	0	3					
Cours	e Obje	ctives:		•								
1.	To pro	vide knowledge on basic mechanics of metal cutting.										
2.	Summ	nmarize the constructional and operational features of machine tools for manufacturing various components.										
3.	Explai	Explain the machine tools for hole making grinding and broaching.										
4.	To ana	lyze various unconventional machining processes and their need	ds in industries									
5.	Descri	be the necessity of additive manufacturing techniques and ready	to interpret with in	dustries	requirer	nents						
UNI	IT I	THEORY OF METAL CUTTING		9	0	0	9					
		hip formation, single-point cutting tool, forces in machining, Typhermal aspects, cutting tool materials, tool wear, tool life, surfact					nogonal					
UNI	IT II	AUTOMATS, SHAPING AND PLANING MA	CHINES	9	0	0	9					
-		ret lathes – construction - indexing mechanism - operations - wo blanning machines – types – construction - mechanism – princip		_	-	-						
UNI	TIII	DRILLING, BROACHING AND GRINDING M	IACHINES	9	0	0	9					
tool no	menclat	nes – specifications, types - feed mechanism, operations – drill to ure, broaching operations – grinding – types of grinding mac econditioning of grinding wheels.		-	-							
UNI	T IV	MILLING AND GEAR GENERATING MAG	CHINES	9	0	0	9					
gear ge	eneration	fications – types - cutter nomenclature – types of cutters – milling - gear shaping and gear hobbing – specifications - cutters –coarators – gear finishing methods										
UNI	IT V	ADVANCES IN MACHINING		9	0	0	9					
Machin Additiv Stereo	ning (AJ ve manu	I machining processes - principles, process parameters, MRR, M), Electrochemical Machining (ECM). Electric Discharge M facturing processes - Fundamentals of Additive Manufacturing phy apparatus - STL file - Fused Deposition Modeling- Laminate poling.	fachining (EDM), lag (AM)-Product I	Laser Be Developr	am Mac nent-Ma	chining (iterials f	LBM). for AM					

Total (45L) = 45 Periods

Tex	t Books:									
1.	Kalpakjian and Schmid, "Manufacturing processes for Engineering Materials" (5th Edition) - Pearson India, 2014.									
2.	Rao. P.N "Manufacturing Technology - Metal Cutting and Machine Tools", 3rd Edition, Tata McGraw-Hill, New Delhi, 2013									
Refe	Reference Books:									
1.	HajraChoudhury, "Elements of Workshop Technology", Vol.II., Media Promoters 2014									
2.	"H.M.T. "Production Technology – Handbook", Tata McGraw-Hill, 2000.									
3.	Roy. A. Linberg, "Process and Materials of Manufacture", PHI, 2000.									
4.	Mikell P. Groover, Fundamentals of Modern Manufacturing: Materials, Processes, and Systems.									
5.	Jain. R.K., and S.C. Gupta, "Production Technology", 16th Edition, Khanna Publishers, 2001									

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:						
CO1	Explain the mechanism of material removal processes.	Understand					
CO2	Describe the constructional and operational features of special-purpose lathes, shaper and planner.	Understand					
соз	Gain working exposure to hole-making operations, grinding and broaching machines utilized in industries.	Evaluate					
CO4	Study of special-purpose machine tools, operations and its uses in industries.	Understand					
CO5	Summarize unconventional machining processes and additive manufacturing processes and their applications.	Remember					

COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1		1						1	1		2		1
CO2		1	1	1						1	1	1	1	2	3
CO3		1	1							1	1	1	1	2	2
CO4		1	1							1	1	1	1	2	2
CO5		1			2		2		2	1	1	1	1	2	2
Avg	2	1	1	1	2		2		2	1	1	1	1.2	2	2
1															

 $3\,/\,2\,/\,1-indicates$ strength of correlation $(3-High,\,2-Medium,\,1-Low)$

	E404	HYDRAULICS AND PNEUMATICS		S	SEMES	TER I	V
PRE	E-REQUIS	SITE:	Category	PC	Cro	edit	3
			Hours/Week	L	Т	P	TH
			nours/ week	3	0	0	3
Cou	rse Objec	tives:					
1.	To enable	e the students, understand the basics of hydraulics and pneumati	cs				
2.	Applying	the working principles of hydraulic actuators and control comp	onents.				
3.	Designin	g and develop hydraulic circuits and systems.					
4.	Applying	the working principles of pneumatic power system and its com	ponents.				
5.	Solving p	problems and troubles in fluid power systems.					
U	NIT I	FLUID POWER PRINICIPLES AND HYDRAUI	LIC PUMPS	9	0	0	9
Perfo		ower; Pumping Theory – Pump Classification – Construction election criteria of pumps – Fixed and Variable displacement pu HYDRAULIC ACTUATORS AND CONTROL CO	mps – Problems.	n, Adva	ntages,	Disadva 0	ntages
					Ů		
- Co	ntrol Comp	ators: Cylinders – Types and construction, Application, Hydrauliconents: Direction Control, Flow control and pressure control servoirs, Pressure Switches – Filters – types and selection - Appl	1 valves – Types,	Constru	ction ar	nd Oper	ation -
Uì	NIT III	HYDRAULIC CIRCUITS AND SYSTE	MS	9	0	0	9
		Intensifiers, Industrial hydraulic circuits – Regenerative, Pump	•		p, Press	sure Inte	ensifier
syste		equence, Reciprocation, Synchronization, Fail - Safe, Speed C static transmission, Electro hydraulic circuits – Servo and P systems.					
system	ms, Hydro	static transmission, Electro hydraulic circuits - Servo and P	roportional valves				
hydra UI Propervalve metho	ms, Hydro aulic servo NIT IV erties of air es, Pneumar od – Integ	static transmission, Electro hydraulic circuits – Servo and P systems.	SYSTEMS cator, Muffler, Airgle cylinder and m	9 control	0 valves,	- Mecl O Quick of cuits - C	9 exhaus
by dra UN Proper valve method Introd	ms, Hydro aulic servo NIT IV erties of air es, Pneumar od – Integ	static transmission, Electro hydraulic circuits – Servo and P systems. PNEUMATIC AND ELECTRO PNEUMATIC Str. – Air preparation and distribution – Filters, Regulator, Lubritic actuators, Design of Pneumatic circuit – classification - sin ration of fringe circuits, Electro pneumatic system – Element	SYSTEMS cator, Muffler, Air gle cylinder and m nts – Ladder diagr	9 control	0 valves,	- Mecl O Quick of cuits - C	9 exhaus
Proper valve method Introduced Line Serve hydrate troub Autor	NIT IV erties of air es, Pneumar od – Integ duction to f NIT V o systems, l aulic pneum	PNEUMATIC AND ELECTRO PNEUMATIC Servo and Presystems. PNEUMATIC AND ELECTRO PNEUMATIC Servo and Presystems. PNEUMATIC AND ELECTRO PNEUMATIC Servo and Presystems. PNEUMATIC AND ELECTRO PNEUMATIC Servo and Present Servo and Present Servo and Present Servo and Design of Pneumatic circuit – classification - singular actuators, Design of Pneumatic circuits and pneumatic logic circuits. PESIGN OF FLUID POWER CIRCUITS TROUBLE SHOOTING Hydro mechanical servo systems, Electro hydraulic servo systems and logic circuits, ladder diagrams, PLC applications in fluid Design of Pneumatic circuits for metal working, handling, sydraulic and Pneumatic power packs. Case studies: A simple servo systems.	SYSTEMS cator, Muffler, Air gle cylinder and m nts – Ladder diagr AND ms and proportional power control. Fectamping counter	9 r control nulti cyli ram – ti 9 ul valves, luid pow	valves, nder circumer	Quick of cuits - Courts pro Otto to to tits, failuits Lo	9 exhaus Cascado blems 9 electro ure and ow-cos
Proper valve method Introduced Line Serve hydrate troub Autor	NIT IV erties of air es, Pneumat od – Integ duction to f NIT V o systems, I aulic pneum oleshooting.	PNEUMATIC AND ELECTRO PNEUMATIC Servo and Presystems. PNEUMATIC AND ELECTRO PNEUMATIC Servo and Presystems. PNEUMATIC AND ELECTRO PNEUMATIC Servo and Presystems. PNEUMATIC AND ELECTRO PNEUMATIC Servo and Present Servo and Present Servo and Present Servo and Design of Pneumatic circuit – classification - singular actuators, Design of Pneumatic circuits and pneumatic logic circuits. PESIGN OF FLUID POWER CIRCUITS TROUBLE SHOOTING Hydro mechanical servo systems, Electro hydraulic servo systems and logic circuits, ladder diagrams, PLC applications in fluid Design of Pneumatic circuits for metal working, handling, sydraulic and Pneumatic power packs. Case studies: A simple servo systems.	SYSTEMS cator, Muffler, Air gle cylinder and m nts – Ladder diagr AND ms and proportional power control. Fectamping counter	9 r control nulti cyli ram – ti 9 ll valves, luid pow and time	valves, nder circumer	Quick of cuits - Courts production to nits, failurits Log hydrau	9 exhaus Cascad oblems 9 electro
Proper valve method Introduced Line Serve hydrate troub Autor	NIT IV erties of air es, Pneumat od – Integ duction to f NIT V o systems, I aulic pneum oleshooting.	PNEUMATIC AND ELECTRO PNEUMATIC Servo and Presystems. PNEUMATIC AND ELECTRO PNEUMATIC Servo and Presystems. PNEUMATIC AND ELECTRO PNEUMATIC Servo and Presystems. PNEUMATIC AND ELECTRO PNEUMATIC Servo and Present Servo and Present Servo and Present Servo and Design of Pneumatic circuit – classification - singular actuators, Design of Pneumatic circuits and pneumatic logic circuits. PESIGN OF FLUID POWER CIRCUITS TROUBLE SHOOTING Hydro mechanical servo systems, Electro hydraulic servo systems and logic circuits, ladder diagrams, PLC applications in fluid Design of Pneumatic circuits for metal working, handling, sydraulic and Pneumatic power packs. Case studies: A simple servo systems.	SYSTEMS cator, Muffler, Air gle cylinder and m nts – Ladder diagr AND ms and proportional power control. Fectamping counter	9 r control nulti cyli ram – ti 9 ll valves, luid pow and time	valves, nder circumer	Quick of cuits - Courts production to nits, failurits Log hydrau	9 exhaus Cascad oblems 9 electro
Proper valve method Introduction Autor pneur	NIT IV erties of air es, Pneumat od – Integ duction to f NIT V o systems, I aulic pneum oleshooting.	PNEUMATIC AND ELECTRO PNEUMATIC Servo and Presystems. PNEUMATIC AND ELECTRO PNEUMATIC Servo and Presystems. PNEUMATIC AND ELECTRO PNEUMATIC Servo and Presystems. PNEUMATIC AND ELECTRO PNEUMATIC Servo and Present Servo and Present Servo and Present Servo and Design of Pneumatic circuit – classification - singular actuators, Design of Pneumatic circuits and pneumatic logic circuits. PESIGN OF FLUID POWER CIRCUITS TROUBLE SHOOTING Hydro mechanical servo systems, Electro hydraulic servo systems and logic circuits, ladder diagrams, PLC applications in fluid Design of Pneumatic circuits for metal working, handling, sydraulic and Pneumatic power packs. Case studies: A simple servo systems.	SYSTEMS cator, Muffler, Air gle cylinder and m nts – Ladder diagr AND ms and proportional power control. Fectamping counter	9 r control nulti cyli ram – ti 9 ll valves, luid pow and time	valves, nder circumer	Quick of cuits - Courts production to nits, failurits Log hydrau	9 exhaus Cascad oblems 9 electro
Proper valve method Introduction Autor pneur	ms, Hydro aulic servo NIT IV erties of air es, Pneumat od – Integ duction to f NIT V o systems, l aulic pneum oleshooting. mation – H matics com	PNEUMATIC AND ELECTRO PNEUMATIC Servo and Presystems. PNEUMATIC AND ELECTRO PNEUMATIC Servo and Presystems. PNEUMATIC AND ELECTRO PNEUMATIC Servo and Presystems. PNEUMATIC AND ELECTRO PNEUMATIC Servo and Present Servo and Present Servo and Present Servo and Design of Pneumatic circuit – classification - singular actuators, Design of Pneumatic circuits and pneumatic logic circuits. PESIGN OF FLUID POWER CIRCUITS TROUBLE SHOOTING Hydro mechanical servo systems, Electro hydraulic servo systems and logic circuits, ladder diagrams, PLC applications in fluid Design of Pneumatic circuits for metal working, handling, sydraulic and Pneumatic power packs. Case studies: A simple servo systems.	SYSTEMS cator, Muffler, Air gle cylinder and m nts – Ladder diagr AND ms and proportional power control. Fectamping counter	9 r control nulti cyli ram – ti 9 ll valves, luid pow and time	valves, nder circumer	Quick of cuits - Courts production to nits, failurits Log hydrau	9 exhaus Cascad oblems 9 electro

Ref	erence Books:								
1.	Andrew Parr, "Hydraulic and Pneumatics", Jaico Publications House, 2005.								
2.	Bolton W. "Pneumatic and hydraulic system", Butterworth-Heinemann 1997								
3.	Majumdar S.R., "Pneumatic systems – Principles and maintenance", Tata McGraw Hill, 2010								
4.	Shanmugasundaram. K, "Hydraulic and Pneumatic controls", Chand & Co, 2006								
5.	Srinivasan.R. "Hydraulic and Pneumatic Controls", Vijay Nicole Imprints, 2008.								
E-R	References:								
1.	http://www.fluidpowerjournal.com								
2.	http://14.139.160.15/courses/112102011/2								
3.	https://www.nfpa.com/home.htm								

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:							
CO1	Select the components as per the application	Evaluate						
CO2	Apply the working principles of hydraulic actuators and control components.	Apply						
СОЗ	Design and develop hydraulic circuits and systems.	Create						
CO4	Apply the working principles of pneumatic power system and its components.	Apply						
CO5	Solve problems and troubles in fluid power systems.							

COURSE ARTICULATION MATRIX COs/ PO1 PO2 PO3 PO4 **PO5** PO6 **PO7** PO8 | PO9 | **PO10** PO11 **PO12** PSO1 PSO₂ PSO3 **POs CO1** 2 1 1 1 1 1 CO₂ 2 2 1 1 1 1 CO₃ 3 CO4 1 1 3 2 2 2 1 1 **CO5** 1 2 1 Avg 1.25 1.4 2.2 1.5 2 1.2 1.2 1 1

 $3\,/\,2\,/\,1$ – indicates strength of correlation (3 – High, 2 – Medium, 1 – Low)

22CE409)	STRENGTH OF MATERIALS		S	EMES	TER I	V
PRE-RE	QUI	SITE:	Category	ES	Cr	edit	3
Differentia	ation,	Partial Differential Equations		L	Т	P	TH
Engineerin		_	Hours/Week	3	0	0	3
Course C	Objec	etives:				•	•
		erstand the nature of stresses developed in simple geometries such for various types of simple loads	ch as bars, cantilev	ers, bean	ıs, shaft	s, cylind	ers and
2. To	o calc	ulate the shear force and bending moment of various beams tran	nsverse loading				
3. To	o estir	mate the slope and the deflection of beams and strengths of the	columns				
4. To	o eval	luate the axial and hoop stresses in thin and thick shells for the a	applied internal and	l external	pressu	es.	
5. To	o lear	n about the torsion behavior of shafts and coil springs					
UNIT	Ι	STRESS, STRAIN AND DEFORMATION OF	SOLIDS	9	0	0	9
		ar and shear strains- principal stresses and principal planes- Molen elastic constants-Thermal stresses.	hr's circle. Deform	ation of	simple o	compour	nd bars
UNIT II		TRANSVERSE LOADING ON BEAMS AND ST	RESSES IN				
Beams and supported	d type	BEAMS es of transverse loading on beams- shear force and bending mover-hanging beams, cantilevers. Theory of bending of beams,	noment diagrams T	ribution	and net	ıtral axis	s, shea
Beams and supported stress distr section and	d type and o ribution	es of transverse loading on beams- shear force and bending mover-hanging beams, cantilevers. Theory of bending of beams, on, point and distributed loads. Shear stress distribution of simulated sections.	noment diagrams T bending stress dist nple beams- circul	Types of tribution	beam s and neu	upports, ntral axis	simply
Beams and supported stress distr	d type and o ribution	es of transverse loading on beams- shear force and bending mover-hanging beams, cantilevers. Theory of bending of beams, on, point and distributed loads. Shear stress distribution of sim	noment diagrams T bending stress dist nple beams- circul	Types of tribution	beam s	upports, itral axis	simply
Beams and supported stress distrestion and UNIT I	d type and coribution d characteristic desired and desired theorem.	es of transverse loading on beams- shear force and bending mover-hanging beams, cantilevers. Theory of bending of beams, on, point and distributed loads. Shear stress distribution of simulated sections. DEFLECTION OF BEAMS AND COLUME tia about an axis and polar moment of inertia, deflection of a benefication in beams, Macaulay's method — Area moment method rems. Columns: End Conditions-Equivalent length of a columns	noment diagrams T bending stress distributed beams - circular beams - circular beam using double id - Conjugate beam	Types of tribution ar, rectar 9 ntegration and strain	beam s and neungular, ' 0 n methodin energine	upports, atral axis T' section	simply s, shear on, "T"
Beams and supported stress distresection and UNIT I	d type and o cribution d char III of inerand de theoret columns and de criber columns an	es of transverse loading on beams- shear force and bending mover-hanging beams, cantilevers. Theory of bending of beams, on, point and distributed loads. Shear stress distribution of simulated sections. DEFLECTION OF BEAMS AND COLUME tia about an axis and polar moment of inertia, deflection of a benefication in beams, Macaulay's method — Area moment method rems. Columns: End Conditions-Equivalent length of a columns	noment diagrams To bending stress distributed beams - circulary with the circulary with t	Types of tribution ar, rectar 9 ntegration and strain	beam s and neungular, ' 0 n methodin energine	upports, atral axis T' section	simply s, shear on, "T"
Beams and supported stress distress ction and UNIT I. Moment of slopes a reciprocal formula formula formula and I. Axial and I.	d type and coribution d char III of iner and detection theore or column (V)	es of transverse loading on beams- shear force and bending mover-hanging beams, cantilevers. Theory of bending of beams, on, point and distributed loads. Shear stress distribution of simulated sections. DEFLECTION OF BEAMS AND COLUME tia about an axis and polar moment of inertia, deflection of a beaffection in beams, Macaulay's method — Area moment method rems. Columns: End Conditions-Equivalent length of a columns.	noment diagrams To bending stress distributed beams - circulary with the circulary with t	Types of tribution ar, rectar 9 Integration and strain Slender 9	beam s and neurogular, ' 0 n methodin energeness ra	upports, atral axis T' section 0 od, company — Matio - Ra	simply s, shear on, "T" 9 outation xwell's nkine's
Beams and supported stress distress ction and UNIT I. Moment of slopes a reciprocal formula formula formula and I. Axial and I.	d type and or ribution d charter and described theorem or column (V)	es of transverse loading on beams- shear force and bending mover-hanging beams, cantilevers. Theory of bending of beams, on, point and distributed loads. Shear stress distribution of simulated sections. DEFLECTION OF BEAMS AND COLUNCTION and polar moment of inertia, deflection of a benefication in beams, Macaulay's method – Area moment method rems. Columns: End Conditions-Equivalent length of a column mins. THIN CYLINDERS, SPHERES AND THICK CYLINDERS in cylinders subjected to internal pressure, deformation of the columns and the columns in the cylinders subjected to internal pressure, deformation of the cylinders and the cylinders subjected to internal pressure, deformation of the cylinders and the cylinders subjected to internal pressure, deformation of the cylinders and the cylinders and the cylinders and the cylinders and the cylinders are cylinders and the cylinders and the cylinders are cylinders and the cylinders and the cylinders and the cylinders are cylinders and the cylinders and the cylinders are cylinders and the cylinders and the cylinders are cylinders and cylinders are cylinders and cylinders are cylinders.	noment diagrams To bending stress distributed beams - circulary with the circulary with t	Types of tribution ar, rectar 9 Integration and strain Slender 9	beam s and neurogular, ' 0 n methodin energeness ra	upports, atral axis T' section 0 od, company — Matio - Ra	simply s, shear on, "T" 9 outation xwell's nkine's
Beams and supported stress distress dis	d type and or ribution d char III of iner and de theore or column (V) hoop a jected V	es of transverse loading on beams- shear force and bending mover-hanging beams, cantilevers. Theory of bending of beams, on, point and distributed loads. Shear stress distribution of simulated sections. DEFLECTION OF BEAMS AND COLUNCTION OF BEAM	noment diagrams To bending stress distributed beams - circulary with the conjugate beam using double in the conjugate beam un-Euler's equation with the cylinder and thin cylinder and thin cylinder beam deflection of shaft	Types of cribution ar, rectar 9 Integration and strain Slender 9 Inders, d	beam s and neurogular, ' 0 n methodin energiness ra 0 leformat 0 t both e	upports, atral axis T' section	simply simply s, shear on, "T" 9 putation xwell' nkine' 9 pherical 9 sion of
Beams and supported stress distress dis	d type and or ribution d char III of iner and de theore or column (V) hoop a jected V	es of transverse loading on beams- shear force and bending mover-hanging beams, cantilevers. Theory of bending of beams, on, point and distributed loads. Shear stress distribution of simulated sections. DEFLECTION OF BEAMS AND COLUNTIAL about an axis and polar moment of inertia, deflection of a benefication in beams, Macaulay's method – Area moment method tems. Columns: End Conditions-Equivalent length of a column tems. THIN CYLINDERS, SPHERES AND THICK CY stresses in cylinders subjected to internal pressure, deformation of to internal pressure – Lame's theorem. TORSION AND SPRINGS s and deformation in circular and hollow shafts, stepped shafts,	noment diagrams To bending stress distributed beams - circulary with the conjugate beam using double in the conjugate beam un-Euler's equation with the cylinder and thin cylinder and thin cylinder beam deflection of shaft	Sypes of cribution ar, rectar 9 ntegration and strain Slender 9 linders, described at tion of specific	beam s and neurogular, ' 0 n methodin energiness ra 0 deformation of the both epinings under the prings	upports, atral axis T' section	simply s, shear on, "T" 9 putation xwell' nkine' 9 pherical 9 sion of all load.
Beams and supported stress districted and UNIT I. Moment of slopes a reciprocal formula for UNIT I. Axial and I shells subj. UNIT V. Torsion, st springs-Wareness and support of the suppo	d type and oribution d char (III of iner and de theore or column theore (IV hoops jected V tresses Yahl's	es of transverse loading on beams- shear force and bending mover-hanging beams, cantilevers. Theory of bending of beams, on, point and distributed loads. Shear stress distribution of simulated sections. DEFLECTION OF BEAMS AND COLUNTIAL about an axis and polar moment of inertia, deflection of a benefication in beams, Macaulay's method – Area moment method tems. Columns: End Conditions-Equivalent length of a column tems. THIN CYLINDERS, SPHERES AND THICK CY stresses in cylinders subjected to internal pressure, deformation of to internal pressure – Lame's theorem. TORSION AND SPRINGS s and deformation in circular and hollow shafts, stepped shafts,	noment diagrams To bending stress distributed beams - circulary with the conjugate beam using double in the conjugate beam un-Euler's equation with the cylinder and thin cylinder and thin cylinder beam deflection of shaft	Sypes of cribution ar, rectar 9 ntegration and strain Slender 9 linders, described at tion of specific	beam s and neurogular, ' 0 n methodin energiness ra 0 deformation of the both epinings under the prings	upports, atral axis T' section	simply s, shear on, "T" 9 outation xwell' nkine' 9 oherical sion of all load
Beams and supported stress distress dis	d type and oribution d char (III of iner and de theore or column (IV) hoop spected (V) tresses (ahl's	es of transverse loading on beams- shear force and bending mover-hanging beams, cantilevers. Theory of bending of beams, on, point and distributed loads. Shear stress distribution of simulated sections. DEFLECTION OF BEAMS AND COLUNCIA tia about an axis and polar moment of inertia, deflection of a beneflection in beams, Macaulay's method — Area moment method rems. Columns: End Conditions-Equivalent length of a column sums. THIN CYLINDERS, SPHERES AND THICK CY estresses in cylinders subjected to internal pressure, deformation of to internal pressure — Lame's theorem. TORSION AND SPRINGS s and deformation in circular and hollow shafts, stepped shafts, factor of spring Stresses in helical springs under torsion loads-S	moment diagrams To bending stress distributed beams - circulary with the conjugate beam non-Euler's equation with the cylinder of thick and thin cylinder of the cylinder of t	Sypes of cribution ar, rectar 9 ntegration and strain Slender 9 linders, described at tion of specific	beam s and neurogular, ' 0 n methodin energiness ra 0 deformation of the both epinings under the prings	upports, atral axis T' section	simply s, shear on, "T" 9 putation xwell' nkine' 9 pherical 9 sion of all load.
Beams and supported stress districted and UNIT I. Moment or of slopes a reciprocal formula formula formula shells subject UNIT V. Torsion, strappings-Wall and I. Rajp	d type and or ribution d char (III of iner and de theore or column (IV) hoop jected (V) tresses (ahl's out, R.	es of transverse loading on beams- shear force and bending mover-hanging beams, cantilevers. Theory of bending of beams, on, point and distributed loads. Shear stress distribution of simulated sections. DEFLECTION OF BEAMS AND COLUNTIAL about an axis and polar moment of inertia, deflection of a benefication in beams, Macaulay's method – Area moment method tems. Columns: End Conditions-Equivalent length of a column tems. THIN CYLINDERS, SPHERES AND THICK CY stresses in cylinders subjected to internal pressure, deformation of to internal pressure – Lame's theorem. TORSION AND SPRINGS s and deformation in circular and hollow shafts, stepped shafts,	moment diagrams Tobending stress distributed beams - circulary with the conjugate beam and	Sypes of cribution ar, rectar 9 ntegration and strain Slender 9 linders, described at tion of specific	beam s and neurogular, ' 0 n methodin energiness ra 0 deformation of the both epinings under the prings	upports, atral axis T' section	simply s, shear on, "T 9 outtation xwell' nkine' 9 otherical sion of all load

Text	t Books:
1.	Rajput, R.K, "Strength of Materials", S.Chand and Co, 3rd Edition, 2003.
2.	Bansal, R.K., "Strength of Materials", Laxmi Publications (P) Ltd., 2016.
Refe	erence Books:
1.	Strength of Materials, D.S. Bedi, Khanna Publishing House
2.	Subramanian R., "Strength of Materials", Oxford University Press, Oxford Higher Education Series, 2010.
3.	Mechanics of Materials, Punmia, Jain and Jain, Laxmi Publications
4.	Strength of Materials (Mechanics of Solid), R.S. Khurmi, S.Chand Publications
5.	Strength of Materials, Jindal U.C., Asian Books Pvt. Ltd., New Delhi, 2009

E-References:

1. NPTEL Videos/Tutorials

	COURSE OUTCOMES: Upon completion of the course, the students will be able to: Evaluate the stress strain and strain angular fairnals have							
CO1	Evaluate the stress, strain and strain energy of simple bars	Evaluate						
CO2	Familiarize the load transferring mechanism in beams and stress distribution due to shear force and bending moment	Understand						
СОЗ	Evaluate the slope and the deflection of beams and strengths of the columns	Evaluate						
CO4	Analyze and design thin and thick shells for the applied internal and external pressures.	Analyze						
CO5								

COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	1												
CO2	2	2	1	1									1	2	
CO3	3	2	1	1									2	2	
CO4	3	2	2	2									2		1
CO5	2	2	2	2									2		1
Avg	2.4	1.8	1.4	1.5									1.75	2	1

 $3\,/\,2\,/\,1-indicates$ strength of correlation (3-High,2-Medium,1-Low)

22MCI	IN03	DESIGN SPRINTS		S	SEMESTER IV									
PRE-R	EQUIS	SITE:	Category	EE	Cro	edit	1							
			Hours/Week	L	T	P	TH							
			nours/ week	0	0	2	2							
Course	Objec	tives:												
1.		p key skill areas essential for a product designer from the perspectation with tools and techniques to prototype rapidly.	pective of design, it	s inheren	t comple	exity and	l							
2.	To enal	ble the participants to visualize the experience for a user.												
3.	To learn	n the roles and responsibilities of a designer in creating and sha	aping experiences f	or the us	er.									
4.	The par	participants shall learn through the lenses of system thinking of how existing products work.												
5.	Learn to	ect and apply various practice tools to aid them in rapid prototyping												
UNI	TI	DESIGN FUNDAMENTALS		0	0	6	6							
		Visual Design, History and Modernism, Design Thinking me as of good design, designing a product and a service	thodology, seven e	lements	of desig	n, princi	ples of							
UNI	ГΙΙ	SYSTEM THINKING AND REVERSE ENGIN	NEERING	0	0	6	6							
-		g for Engineering Problem Solving, Understanding Systems, ering Methodology, Identify building blocks/Components - Re	=		-	nplex Sy	ystems,							
UNIT	r III	USER INTERFACE & USER EXPERIE	NCE	0	0	6	6							
		UI/UX, Human-Computer interface, user-centered Design mation Architecture, UI Components, need for UI prototyping,	-	esearch t	echnique	es, UX	Design							
UNIT	ΓIV	MECHANICAL PROTOTYPING		0	0	6	6							
methods	s - Tools	yping - Domains in prototyping - Difference between actual r used in different domains - Introduction - Working with Fusion and engraving - RD Works - Additive manufacturing	_		_	-								
UNI	ΓV	ELECTRONIC & SOFTWARE PROTOTY	YPING	0	0	6	6							
	ment and	Lumped Circuits - Electronic Prototyping - Tinker CAD - Dd version control - GitHub - GitHub Actions - GitBash - Cont			_									
				Toto	1 (30P)	_ 20 D	owi o da							

Text	t Books:								
1.	Thinking in systems - Donella Meadows, 2015								
2.	Rapid Prototyping And Engineering Applications: A Toolbox For Prototype Development - Frank W.Liou, 2007								
3.	Rapid Prototyping Technology: Selection and application - COOPER K. G, 2001								
Refe	Reference Books:								
1.	https://thesystemsthinker.com/wp-content/uploads/2016/03/Introduction-to Systems-Thinking-IMS013Epk.pdf								
2.	https://formlabs.com/blog/ultimate-guide-to-prototyping-tools-for-hardware-and product-design/								
3.	https://docs.kicad-pcb.org/								
4.	https://www.tinkercad.com/learn/circuits								
5.	https://docs.github.com/en/free-pro- team@latest/actions/guides								

	SE OUTCOMES: empletion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Understand the elements and principles of product and service design	Apply
CO2	Apply system thinking concepts in reverse engineering	Apply
СОЗ	Apply user research techniques to meet the UX needs of a customer and design a visual prototype	Apply
CO4	Develop prototyping models using the tools from mechanical prototyping models	Apply
CO5	Develop prototyping models using the tools from electrical and software prototyping methods	Apply

COUR	SE AR	TICUL	<u>ATIO</u>	N MA	TRIX										
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3		1						2						2
CO2	2	3							2						2
CO3	3		1					1	2						2
CO4			3	2	3				2						2
CO5	2		2		1				2						2
Avg	2.5	3	1.7	2	2			1	2						2
	1	1	3/2/	1 – indi	icates st	rength	of corr	elation	(3 – Hi	gh. 2 – N	/ledium.	1 – Low)	1	

22CYN	AC01 ENVIRONMENTAL SCIENCE	SEMESTER IV						
PRE-R	EQUISITE:	Category	MC	Cre	0			
		TT /XX/ 1	L	T	P	TH		
		Hours/Week	2	0	1	3		
Course	Objectives:				•			
1.	To learn the concept of non-conventional energy systems.							
2.	To explore the environmental impact assessment and to learn about	the consequence of d	ifferent t	ypes of 1	ollutant	is.		
3.	To have an ancient wisdom drawn from Vedas.							
4.	To acquire activity-based knowledge to preserve environment.							
5.	To learn about conservation of water and its optimization.							
	ENVIRONMENTAL AWARENESS		30	0	0	30		

Various types of traditional power plant --Advantage and Disadvantage of conventional power. Definition of non-conventional energy sources Plants – Conventional vs. Non-conventional power generation. – Types of non-conventional energy sources - India's current energy resources and their long-term viability – India's Energy requirement and management.

Solar Energy Basics- Solar Thermal Energy- Solar Photovoltaic Energy- Benefits and Drawbacks -Effects on the environment and safety. Wind turbine power and energy- India's wind energy potential- Wind turbine types. Environmental benefits and impacts of offshore wind energy. Air pollution- Sources, effects, control, air quality standards, air pollution act, air pollution measurement. Water Pollution- Sources and its remedy, Soil Pollution- Sources and its remedy, disposal of solid waste. Greenhouse gases – effect, acid rain. Noise pollution reduction. Aspects of pollution from various power plants.

ENVIRONMENTAL ACTIVITIES 0 0 15 15

Group activity on water management – Group discussion on recycle of waste (4R's)- Slogan making contest – Poster making event – Expert lecture on environmental awareness – Imparting knowledge on reduction of electricity usage.

Identification and segregation of biodegradable and non-biodegradable waste – Campus cleaning activity – Plantation of trees in the college campus and local waste lands – Identification of varieties of plants and their usage – Shutting down the fans and ACs of the campus for an hour.

Total (30L + 15P) = 45 Periods

Text B	ooks:
1.	Elements of Environmental science and Engineering, P.Meenakshi, Prentice Hall of India, New Delhi, 2009.
2.	A Textbook of Environmental Chemistry and Pollution Control: (With Energy, Ecology, Ethics and Society), Revised Edition, Dr. S.S. Dara, D.D. Mishra Published by S. Chand & Company Ltd, 20 14.
Refere	nce Books:
1.	Introduction to Environmental Engineering and Science, Gilbert M. Masters; Wendell P. Ela Publisher: Prentice-Hall India, 3rd Edition, 2008.
2.	Environmental Science, Fldren D. Enger, Bredley F.Smith, WCD McGraw Hill 14"Edition 2015.
E-Refe	rence
1	www.onlinecourses.nptel.ac.in/
2	www.ePathshala.nic.in

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:				
CO1	Identify about the major renewable energy systems and will investigate the environmental impact of various energy sources as well as the consequences of various pollutants.	Understand & Analyze			
CO2	Predict the methods to conserve energy and ways to make optimal use of the energy for the future.	Apply			

COU	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1		1	3			3	1	1				1	2		1
CO2		1	3			3	1	1				1	2		1
Avg		1	3			3	1	1				1	2		1
			3/2	/ 1 – in	dicates	strengt	h of cor	relation	n (3 – H	igh, 2 – I	Medium,	1 – Low)		

22M	E405	THERMAL ENGINEERING LABORATO	ORY	SEMESTER IV							
PRE	-REQUI	SITE:	Category	PC	Cro	1.5					
			Hours/Week		T	P	TH				
			Hours/ week	0	0	3	3				
Cour	se Object	ives:									
1.	The com	ponents of IC engine and boiler, mountings and accessories and	procedure of stean	n generat	ion.						
2.	Constructing port and valve timing diagram and determine the flash and fire point of fuel oil.										
3.	3. Analyzing the petrol and diesel engine performance by conducting load test.										

LIST OF EXPERIMENTS

1. Dismantling and assembling of a single cylinder petrol and diesel engine.

Characteristics of heat release in diesel engine and to study the $p-\theta$ diagram.

2. Demonstration of generating steam using boiler.

4.

5.

- 3. Determination of Viscosity, Flash and Fire point.
- 4. Construction of Valve Timing and Port Timing Diagrams.

Analyzing the diesel engine performance by retardation test.

- 5. Performance analysis of a four-stroke Diesel Engine.
- 6. Performance analysis of a four-stroke Petrol Engine.
- 7. Construction of a Heat Balance Test on four-stroke Diesel Engine.
- 8. Morse Test on Multi cylinder Diesel Engine.
- 9. Retardation Test to find Frictional Power of a Diesel Engine.
- 10. Determination of $p-\theta$ diagram and heat release characteristics of an IC engine.

Total (45P) = 45 Periods

	RSE OUTCOMES: completion of the course, the students will be able:	Bloom's Taxonomy Mapped
CO1	To identify the components of IC engine and boiler, mountings and accessories and procedure of steam generation.	Understand
CO2	To construct port and valve timing diagram and determine the flash and fire point of fuel oil.	Create
CO3	To analyze the petrol and diesel engine performance by conducting load test.	Analyze
CO4	To analyze the diesel engine performance by retardation test.	Analyze
CO5	To study the characteristics of heat release in diesel engine and to study the $p-\theta$ diagram.	Remember

COUL	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	1	1	3	1	1						1	1	2
CO2	1	2	1	1	1	2	1						2	1	1
CO3	2	1	3	1	1	2	1						3	1	3
CO4															
CO5															
Avg	2	1.7	1.7	1	1.7	1.7	1						2	1	2
	•	•	3/2	/ 1 – in	dicates	strengt	h of cor	relation	1 (3 – H	igh, 2 – 1	Medium,	1 – Low	·)	•	•

RATORY	SEMESTER IV						
Category	PC Credit						
	L	T	P	TH			
Hours/Week	0	0	3	3			
	Category Hours/Week	Category PC L	Category PC Cro	Category PC Credit L T P			

Course Objectives:

- 1. To study different types of machine tools like lathe, drilling machine, shaper and grinding machine.
- 2. To acquire the necessary skills to operate different machinery.
- 3. To calculate metal removal rate and machining time of metal cutting processes
- 4. To analyze and select an appropriate machining process for different components.
- 5. To study safety measures while machining.

LIST OF EXPERIMENTS

- 1. Eccentric turning
- 2. Multi starts thread cutting
- 3. Drilling and grooving
- 4. Counter boring
- 5. Counter sinking
- 6. Shaping the sides of a cubical blank
- 7. Groove cutting and V-cutting
- 8. Dovetail cutting
- 9. T –slot cutting
- 10. Spur gear cutting in milling machine
- 11. Helical Gear Cutting in milling machine
- 12. Contour milling using vertical milling machine
- 13. Surface Grinding of cubical block
- 14. Cylindrical Grinding of circular shaft

Total (45P) = 45 Periods

	RSE OUTCOMES: completion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Operate machines tools for various assembly and fabrication tasks.	Understand
CO2	Set up machines like lathe shaper, grinding and milling machine for various applications	Create
CO3	Perform machining time calculation in machining jobs.	Analyze
CO4	Evaluate the accuracy & tolerance of components produced	Analyze
CO5	Prepare gears using forming and generating methods of gear manufacturing	Remember

COUR	SE AR	TICU	LATIC	N MA	TRIX										
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2				1		1			1		1		1	
CO2		2			2	2	1	1				2		2	
CO3	3	1		1			2		1	1		1	2	1	3
CO4	3	3			2			2						2	
CO5		1							1	2			3		1
Avg	2.6	1.7		1	1.7	2	1.3	1.5	1	1.3		1.3	2.5	1.5	2
	•	•	3/2/	1 _ ind	icatas s	tranath	of cor	ralation	(3 H	igh 2 – N	Adium	1 _ I ow	,	•	•

22ME501	DESIGN OF MACHINE ELEMENTS		9	SEMES	STER V	V
PREREQUI	SITES	Category	PC	Cr	edit	4
1. Student sho	uld study engineering mechanics.		L	Т	P	TF
	uld study kinematic of machinery.	Hours/Week	3	1	0	4
COURSE O	BJECTIVES					
1. Unders	standing of background in mechanics of materials and design of mac	hine componen	ts.			
2. An unc	derstanding of the origins, nature and applicability of empirical desig	n principles, ba	sed on s	afety co	nsiderat	ions
3. An unc	derstanding the design of shafts, couplings and joints.					
4. Familia	arize the design of energy storing elements and engine components.					
5. An approper perform	preciation of the relationships between component level design and omance	verall machine	system o	design a	nd	
UNIT-I	STEADY STRESSES AND VARIABLE STRESSES IN MEMBERS	MACHINE	9	3	0	12
on mechanical principle stress	the design process – Product development cycle-factors influencing properties - Preferred numbers – Direct, Bending and Torsional stresses for various load combinations, eccentric loading – Design of curvaries of failure – stress concentration – design for variable loading – design for variable loading – Stress concentration – design for variable loading – design for variable – design for variable loading – design for variable	ss – Impact and red beams – cra	shock lone hook	oading -	- Calcula ' frame -	ation o
UNIT-II	DESIGN OF SHAFTS, COUPLINGS AND PIN JO	INTS	9	3	0	12
-	d and hollow shafts based on strength, rigidity and critical speed – I buplings – Design of pin joints like cotter and knuckle joints.	Design of keys	and key	ways -	Design	of rigi
UNIT-III	DESIGN OF THREADED FASTENERS, RIVETEI WELDED JOINTS	O AND	9	3	0	12
	eners - Design of bolted joints including eccentric loading – Design of theory of bonded joints.	f riveted and we	elded joi	nts for j	pressure	vesse
UNIT-IV	DESIGN OF ENERGY STORING ELEMENTS AND COMPONENTS	ENGINE	9	3	0	12
engines and pr	of springs, optimization of helical springs - rubber springs - Flywh unching machines- Connecting Rods and crank shafts. Heat engines astion engines, Design of I.C engine cylinder, piston, connecting rod.	- Brief details	about ex	cternal c		
	DESIGN OF BEARINGS, LEVERS, PRESSURE VESS PIPES	SELS AND	9	3	0	12
UNIT-V						74-
Sliding contac	t and rolling contact bearings - Hydrodynamic journal bearings, Some gn of Levers - Design of pressure vessels and pipes	merfeld Numbe	r - Selec	tion of .	Rolling (Conta
Sliding contac					Rolling () = 60 P	

Text	Books:						
1	Bhandari V.B, "Design of Machine Elements", Tata McGraw Hill Book Co, 2020						
2	Md.Jalaludeen.S, "A text book of Machine Design", Anuradha Publications, 2006						
Refer	Reference Books:						
1	Shigley, J.E. and Mischke, C.R., Mechanical Engineering Design, Fifth Edition, McGraw-Hill International; 1989.						
2	Deutschman, D., Michels, W.J. and Wilson, C.E., Machine Design Theory and Practice, Macmillan, 1992.						
3	Juvinal, R.C., Fundamentals of Machine Component Design, John Wiley, 1994.						
4	PSG Tech, "Design Data Handbook", M/s.DPV Printers, Coimbatore, 2009						

E-R	eferences:
1	https://nptel.ac.in/courses/112105124
2	Design of Machine Elements - V. B. Bhandari - Google Books
3	A Textbook of Machine Design by R.S.Khurmi And J.K.Gupta [tortuka]_1490186411865.pdf DocDroid

	RSE OUTCOMES: mpletion of the course the student will be able to	Bloom's Taxonomy Mapped
CO1	Explain the influence of steady and variable stresses in machine component design.	Understand
CO2	Apply the concepts of design to shafts, keys and couplings.	Apply
CO3	Familiarize the design of temporary and permanent joints	Understand
CO4	Design the various energy storing elements and engine components.	Analyze
CO5	Familiarize the design of various types of bearings and pressure vessels.	Understand

COURS	SE AR	TICU	LATI	ON M	ATRI	X									
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	1	2		1	1				1		3	2	1
CO2	2	2	1	2		1	1				1		3	2	1
CO3	2	2	1	2		1	1				1		3	2	1
CO4	2	2	1	2		1	1				1		3	2	1
CO5	2	2	1	2		1	1				1		3	2	1
Avg	2.0	2.0	1.0	2.0		1.0	1.0				1.0		3.0	2.0	1.0
			3/2/	/1 – inc	licates	streng	th of c	orrelati	on (3 -	High, 2	- Mediun	n, 1- Low	7)		

22ME	502	HEAT AND MASS TRANSFER		;	SEMES	STER '	V	
PRER	EQUI	SITES:	Category	PC	Credit		3	
1. Basic	c laws a	and concepts of thermodynamics.	II/XX/ l-	L	Т	P	ТН	
2. The	concept	of energy transfers and their conversion principles.	Hours/Week	3	0	0	3	
Cours	e Obje	ectives	•			•	•	
1.	Under	standing the science behind conduction heat transfer and its ap	pplications					
2.	Differ	rentiating the concepts of forced and natural convection heat tra	ansfer					
3.	Descri	ibing the laws and concepts of radiation heat transfer						
4.	Under	estanding phase change processes and analyzing heat exchange	rs					
5.	Study	ing the concept of mass transfer process and its modes						
UNI	T-I	CONDUCTION HEAT TRANSFER		9	0	0	9	
UNI'	Γ-II Sovernii	CONVECTION HEAT TRANSFER and equations, boundary layer concept – Forced convection: extended and flow – entrance effects. Free convection – flow over ver	ernal flow – flow ov	9 er plates	0, cylinde	0 ers, sphe	9 eres and	
and sph			orour prace, nonzona			P, °.		
UNIT	T-III	BOILING, CONDENSATION AND HEAT EXC	CHANGERS	9	0	0	9	
_		ool boiling and Flow boiling, Nusselt's theory of condensationes - Overall Heat Transfer Coefficient – Fouling Factors. LM		_	and cond	densatio	n. Heat	
UNIT	Γ -IV	RADIATION HEAT TRANSFER		9	0	0	9	
Radiati	on laws	, Black Body and Gray body Radiation. Shape Factor. Electric	al Analogy. Radiati	on Shiel	ds.			
UNI	Γ-V	MASS TRANSFER		9	0	0	9	
	-	s – Diffusion Mass Transfer – Fick's Law of Diffusion – Ste c Convective Mass Transfer Problems.	ady state Molecular	Diffusi	on - Equ	uimolal	counter	

Text I	Books:						
1	R.C. Sachdeva, "Fundamentals of Engineering Heat & Mass transfer", New Age International Publishers, 2017						
2	Frank P. Incropera and David P. Dewitt, "Fundamentals of Heat and Mass Transfer", John Wiley & Sons, 7th Edition, 2014.						
Refer	Reference Books:						
1	Yunus A. Cengel, "Heat Transfer A Practical Approach" - Tata McGraw Hill, 5 th Edition - 2013						
2	Holman, J.P., "Heat and Mass Transfer", Tata McGraw Hill, 2017						
3	Kothandaraman, C.P., "Fundamentals of Heat and Mass Transfer", New Age International, New Delhi, 2012						
4	Ozisik, M.N., "Heat Transfer", McGraw Hill Book Co., 1994.						

	SE OUTCOMES: appletion of the course the student will be able to	Bloom's Taxonomy Mapped
CO1	Analyze the heat conduction under steady and unsteady conditions in solids.	Analyze
CO2	Describe the fundamentals of natural and forced convective heat transfer processes	Understand
СОЗ	Analyze the performance of heat exchangers by using the method of LMTD and NTU	Analyze
CO4	Evaluate the parameters of radiative heat exchange between surfaces	Evaluate
CO5	Relate the mass transfer concepts for various industrial applications.	Apply

COUR	RSE A	RTIC	ULAT	ION I	MATR	<u>XIX</u>									
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	2		1						3	3	1
CO2	3	3	3	3	2		1						3	3	1
CO3	3	3	3	3	2		1						3	3	1
CO4	3	3	3	3	2		1						3	2	1
CO5	2	2	2	2	1		1						3	1	
Avg	2.8	2.8	2.8	2.8	1.8		1						3	2.4	1
			3/2	2/1 – ir	ıdicate	s stren	gth of o	correlat	tion (3	- High, 2	- Mediur	n, 1- Low	y)		

22M	E503	METROLOGY AND QUALITY CONTROL	1	9	SEMES	STER V	V
PRE	REQUI	ISITES	Category	PC	Cr	edit	3
			II /XX/1-	L	Т	P	TH
			Hours/Week	3	0	0	3
Cou	rse Obje	ectives:					
1.		ning the importance of measurements in engineering and the fact ement uncertainty	tors affecting m	neasurer	nents a	nd to co	ompute
2.	Applyii	ng the applications of linear and angular measuring instruments					
3.	Interpre	etation of various tolerance symbols.					
4.	Applyii	ng the SQC methods in manufacturing					
5.	Applyii	ng the advances in measurements for quality control			ı	Ţ	•
UN	ITI	BASICS OF MEASUREMENT SYSTEM AND DE	VICES	9	0	0	9
mech	anical lo	metrology, accuracy, precision and sensitivity, Abbe's principle. Thr ading – static characteristics of instruments-factors considered in sel and classification - sources of error. Measurement uncertainty					-
UN	IT II	CALIBRATION OF INSTRUMENTS AND QUARMENTS AND QUARMENTS	LITY	9	0	0	9
gauge	es, dial in	measuring instruments - principles of calibration, Calibration of Institution, surface plates, slip gauges, care of gauge blocks. General camparators - mechanical, electrical, optical and pneumatic.		_			
UN	IT III	GEOMETRICAL MEASUREMENT AND MACHINE F	ELEMENTS	9	0	0	9
princ of ma meas	iple, three ajor, min urement.	surement - optical protractors, sine bar, roundness measurement, e basic types of limit gauges, Tomlinson surface meter, computer con or and effective diameters. Gear terminology; spur gear measurem Principle of interferometry, laser interferometer, Machine vision latness, roundness deviations.	trolled CMM. IS nent, checking o	O metri f compo	ic threac osite err	l, measu ors, bas	rement e pitch
UN	IT IV	STATISTICAL QUALITY CONTROL		9	0	0	9
		 terminology and measurements – Optical measuring instrument control charts - Sampling plans. 	ts – Acceptance	e test fo	rmachi	ines. Sta	itistical
	ity Contro				0	0	1
Quali	I IT V	SIX SIGMA		9	U	U	9
Quali UN Six s Contr	IT V igma: de	SIX SIGMA fine measure, analyse, improve and control phases. Analyze phase Scatter chart, Cause and effect diagram, Pareto analysis, interrelation esting, ANOVA, Multi variate analysis.		n Tools	: Histog	gram, B	oxPlot,

Text	Books:									
1.	Gupta.I.C, —A text book of Engineering Metrology, Dhanpat Rai publications, New Delhi, 2018									
2.	Beckwith.T.G,Roy D. Marangoni, John H. Lienhard, - Mechanical Measurements, Prentice Hall, 2006									
Refe	Reference Books:									
1.	Jain.R.K, —Mechanical and Industrial Measurements, Khanna Publishers, Delhi, 1999.									
2.	Holmen.J.P, —Experimental Methods for Engineersl, Tata McGraw Hill Publications Co Limited, 2017.									
3.	Grant, E.L., Statistical Quality Control, Mc Graw-Hill, 2004. 3. Doeblin E.O., Measurement Systems, Mc Graw-Hill, 2004.									
4.	Alan S Morris, —Measurement and Instrumentation Principles , Butterworth, 2006.									

5.	De Feo J A and Barnard W W, —Six Sigma: Break trough and BeyondG, Tata McGraw-Hill, New Delhi, 2005.									
E-References:										
1.	https://nitsri.ac.in/Department/Mechanical%20Engineering/MEC_405_Book_2,_for_Unit_2B.pdf									
2.	https://www.nist.gov/system/files/documents/srm/NIST-SRM-RM-Articlefinal.pdf									
3.	https://www.researchgate.net/publication/319587859_Computer-Aided_Metrology-CAM									

	COURSE OUTCOMES: On completion of the course the student will be able to							
CO1	Explain the importance of measurements in engineering and the factors affecting measurements and to compute measurement uncertainty.							
CO2	Apply the working principle and the applications of linear and angular measuring instruments	Apply						
CO3	Interpret of various tolerance symbols.	Apply						
CO4	Apply the SQC methods in manufacturing.	Apply						
CO5	Apply the advances in measurements for quality control in manufacturing industries.	Apply						

COURS	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1							2	1	2				2	1	
CO2							3	1	2				1	2	
CO3							2	1					2	1	
CO4				3			2		1				1	2	
CO5				2				3	1				2	1	
Avg				2.5			2.2	1.5	1.5				1.6	1.4	
			3/2/	1 – ind	icates	streng	th of co	orrelati	on (3 –	High, 2	- Mediui	n, 1- Lov	v)	•	•

22M	IE504	DYNAMICS OF MACHINERY		5	SEMES	STER Y	V						
PRE	REQUI	SITES	Category	PC	Cre	edit	3						
En ein	i M	(allowing Winnersting of Marking on Stone of Marking)	Hours/Week	L	Т	P	TH						
Engin	eering M	lechanics, Kinematics of Machinery, Strength of Materials	Hours/ week	3	0	0	3						
COU	RSE O	BJECTIVES:											
1.	To impart students with the knowledge about motion, masses and forces in machines and the Principle of Virtual Work												
2.	To facil	o facilitate students to understand the concept of balancing of rotating and reciprocating masses											
3.	To teac	ach concepts of free vibration analyses of one and two degree-of-freedom rigid body systems											
4.	To teach concepts of forced vibrations analyses of rigid body systems and to give awareness to students on the phenomenon of vibration and its effects												
5.	To lear	n about the concept of various types of governors											
UN	ITI	FORCE ANALYSIS		9	0	0	9						
Static	•	BALANCING amic balancing - Balancing of rotating masses - Balancing a sin al balancing in locomotive Engines - Balancing linkages - balancing	• •	9 ine - Ba	0 lancing	0 Multi-c	9 ylinder						
UNI	III TII	FREE VIBRATION		9	0	0	9						
freque Types	ency by one of damp	of vibratory systems – Types – Single degree of freedom systemergy method, Dunkerly's method - Critical speed - Damped from Free vibration with viscous damping, Critically damped systems of two and three rotor systems.	ree vibration of si	ngle de	gree fre	edom sy	stem -						
UNI	IT IV	FORCED VIBRATION		9	0	0	9						
		eriodic Force – Harmonic force – Force caused by unbalance factor – Vibration isolation and transmissibility.	e – Support moti	on - Lo	garithm	ic Decr	ement-						
UN	IT V	GOVERNORS		9	0	0	9						
		ypes - Centrifugal governors - Gravity controlled and spring con on - Controlling Force - other Governor mechanisms.	ntrolled centrifuga	al gover	nors –C	haractei	ristics -						

Text	Books:							
1.	Design of Machinery, Fourth Edition, by R.L. Norton, McGraw Hill, 2007							
2.	Mechanical Vibration, V.P.Singh, Dhanpatrai, Delhi							
Reference Books:								
1.	Ballaney, P.L., "Theory of Machines and Mechanisms", Khanna Publishers, New Delhi, 2002.							
2.	Shigley, J.E. and Uicker, J.J., "Theory of Machines and Mechanisms", TMH ND, 1998.							
3.	Amithabha Ghosh, and Ashok Kumar Malik., "Theory of Mechanisms and Machines", 2nd Ed., Affiliated East and West Press Limited, 1998.							
4.	Prof.Nakara, IIT-Delhi Reference Books							
E-Re	eferences:							

1.	www.university.youth4work.com/IIT Kharagpur Indian-Institute-of-Technology/study/1653-dynamics-of-ebook machinery-	
2	http://nptel.ac.in/courses/112104114/	

	RSE OUTCOMES: upletion of the course the student will be able to	Bloom's Taxonomy Mapped
CO1	Apply basic principles of mechanisms in mechanical system.	Apply
CO2	Familiarize the static and dynamic balancing of rotating and reciprocating masses.	Understand
CO3	Analyze the mechanical systems subjected to free vibration.	Analyze
CO4	Analyze mechanical systems subjected to forced vibration.	Analyze
CO5	Analyze the various types of governors and its speed control mechanism.	Analyze

COURSE A	OURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	3	3	1					1		3	2	1	2
CO2	2	2	3	2	1					1		3	2	1	2
CO3	2	2	3	2						1		3	2	1	2
CO4	2	2	3	2	1					1		3	2	1	2
CO5	1	2	3	2						1		3	2	1	1
Avg	1.8	2.0	3.0	2.2	1					1.0		3.0	2.0	1.0	1.8
	•		3/2/1	– indi	cates s	trengt	h of co	rrelati	on (3 –	High, 2	- Mediu	m, 1- Lo	w)	•	

22ME	2505	INSTRUMENTATION AND CONTROL SYST	EM		SEME	STER V	7
PRER	EQUIS	ITE:	Category	PC	Cro	edit	3
Basics	of measu		Hours/Week	L	0	P	TH
			nours/ week	3	0	0	3
Course	e Objec	tives:					
1.	To mak	e the students aware of the modern sensors and advanced measure	ement systems				
2.	To sele	ct the correct system of instrumentation and sensing as per the ind	lustrial requireme	ents			
3.	To und	erstand statistical signal processing					
4.	To pro	vide adequate knowledge in the time response of systems and stead	dy state error ana	lysis			
5.	To intr	oduce stability analysis and design of compensators			1	1	Γ
UN	IT I	GENERAL CONCEPTS OF MEASUREME	ENT	9	0	0	9
displace		vstems- Sensors and transducers— Classifications of Transducers osition and proximity; velocity, motion, force, fluid pressure, licesors	•				
UNI	IT II	SIGNAL CONDITIONING		9	0	0	9
-		cteristics, wheat's stone bridge- Instrumentation sensor – integrappers, voltage to time conversion, voltage to freq. Conversion con			- samplir	ng, A/D a	and D/A
UNI	TIII	DATA ACQUISITION		9	0	0	9
timers,	DMA, S	acing – Introduction - Elements of data acquisition and control - oftware and hardware installation, Data acquisition interface requi	irements, -Genera	ıl configu	uration-si		
		ta acquisition – Data Logging – Data conversion – Introduction to	ε				
UNI	TIV	ta acquisition – Data Logging – Data conversion – Introduction to TIME RESPONSE ANALYSIS		9	0	0	9
Respon	ise of sy	·	ck control system	n accord	ding to t		
Respon	ise of sy	TIME RESPONSE ANALYSIS stems for different time-based input, Classification of feedback	ck control system	n accord	ding to t		
Respondence Coefficial UNI Frequer	ise of sy ients- gen IT V	TIME RESPONSE ANALYSIS stems for different time-based input, Classification of feedbackeralized steady state errors steady state errors due to impulse, step	ck control system p, ramp and parab	m accordoolic inpu	ding to	ype; stat 0 etween fr	ic error
Respondence Coefficial UNI Frequer	ise of sy ients- gen IT V	TIME RESPONSE ANALYSIS stems for different time-based input, Classification of feedbar heralized steady state errors steady state errors due to impulse, step FREQUENCY DOMAIN ANALYSIS onse-Bode plot -Polar plot -Determination of closed loop response	ck control system p, ramp and parab	m accordolic inpu	ding to tuts. 0 elation bense-Anal	ype; stat 0 etween fr	ic error 9 equency
Respondence Coefficial UNI Frequer	ise of sy ients- gen IT V ncy respondent and time	TIME RESPONSE ANALYSIS stems for different time-based input, Classification of feedbar heralized steady state errors steady state errors due to impulse, step FREQUENCY DOMAIN ANALYSIS onse-Bode plot -Polar plot -Determination of closed loop response	ck control system p, ramp and parab	m accordolic inpu	ding to tuts. 0 elation bense-Anal	o etween fr	ic error 9 equency
Respondence Coefficial UNI Frequer domain Text B	ise of sy ients- gen IT V ncy respondent and time Books:	TIME RESPONSE ANALYSIS stems for different time-based input, Classification of feedbar heralized steady state errors steady state errors due to impulse, step FREQUENCY DOMAIN ANALYSIS onse-Bode plot -Polar plot -Determination of closed loop response	ck control system p, ramp and parab e, open loop responsation on frequen	m accordoolic inpu 9 mse-Corr cy respo To	ding to tuts. 0 elation bense-Anal	o etween fr	ic error 9 equency
Respondence Coefficial UNI Frequer domain Text B 1. J	IT V IT V IT Sooks: John G. V	TIME RESPONSE ANALYSIS stems for different time-based input, Classification of feedbackeralized steady state errors steady state errors due to impulse, step FREQUENCY DOMAIN ANALYSIS onse-Bode plot -Polar plot -Determination of closed loop response edomain specifications - Effect of Lag, lead and lag-lead compen	ck control system p, ramp and parab p, open loop responsation on frequent c', CRC Press. 199	m accordonal accordona	ding to tuts. 0 elation be use-Analotal(45L	0 etween fr lysis 0 = 45 1	ic error 9 equency
Respondence Coefficial	IT V IT V IT Sooks: John G. V	TIME RESPONSE ANALYSIS stems for different time-based input, Classification of feedbackeralized steady state errors steady state errors due to impulse, step FREQUENCY DOMAIN ANALYSIS onse—Bode plot—Polar plot—Determination of closed loop response edomain specifications - Effect of Lag, lead and lag-lead compense to the compense of the compense o	ck control system p, ramp and parab p, open loop responsation on frequent c', CRC Press. 199	m accordonal accordona	ding to tuts. 0 elation be use-Analotal(45L	0 etween fr lysis 0 = 45 1	ic error 9 equency
Respondence Coefficial UNI Frequer domain Text B 1. J 2. M Reference Coefficial Coef	IT V IT V Incy responsion and time Books: John G. V Murthy,	TIME RESPONSE ANALYSIS stems for different time-based input, Classification of feedbackeralized steady state errors steady state errors due to impulse, step FREQUENCY DOMAIN ANALYSIS onse—Bode plot—Polar plot—Determination of closed loop response edomain specifications - Effect of Lag, lead and lag-lead compense to the compense of the compense o	ck control system p, ramp and parate p, open loop responsation on frequen ', CRC Press. 199 all of India Pvt. Li	m accordonal accordona	ding to tuts. 0 elation be use-Analotal(45L	0 etween fr lysis 0 = 45 1	ic error 9 equency
Respondence Coefficial	IT V IT V IT Sooks: John G. V Murthy, Patranab	TIME RESPONSE ANALYSIS stems for different time-based input, Classification of feedbackeralized steady state errors steady state errors due to impulse, step FREQUENCY DOMAIN ANALYSIS onse—Bode plot —Polar plot —Determination of closed loop response edomain specifications - Effect of Lag, lead and lag-lead compense domain specifications - Effect of Lag, lead and lag-lead compense between the compense of the c	ck control system p, ramp and paral e, open loop responsation on frequent c', CRC Press. 199 all of India Pvt. Lu	m accordoolic inpu 9 nse-Corr cy respo To 18. d., New	ding to touts. 0 elation bense-Analotal(45L) Delhi, 20	0 etween fr lysis 0 = 45 1	ic error 9 equency

COURSE OUTCOMES: On completion of the course the student will be able to							
COI	Apply common measurement characteristics and terms to select sensors to meet control and monitoring requirements	Apply					
CO2	Design, build and test sensor interface circuits including amplifiers to process the measured variable into a useful signal in the presence of noise and environmental variations	Create					
СОЗ	Select and design appropriate signal processing to its instrumentation and control and their measurement	Create					
CO4	Understand and apply basic science, theory control theory and apply them to control engineering problems.	Understand					
CO5	Analyse the performance of systems and components through the use of analytical techniques	Analyze					

COURSE	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	1	2	2	3				1			3	1		
CO2													2	1	
CO3	1	2	2	2	2	2	1		2		1	1		2	1
CO4		1	2	3	1		2					2			
CO5		2	3	3	1			1	2	1		3			2
Avg	1	1.5	2.2	2.4	1.7	2	1.5	1	1.0	1.6	1	2.2	1.5	1.5	1.5
			3/2	2/1 – in	dicates	streng	gth of c	orrelat	ion (3 -	- High, 2	- Mediui	m, 1- Lov	v)		

Category		SEMESTER		V	
	EE	Credit 1		1	
r /xx/ 1	L	Т	P	TH	
Iours/Week	0	0	2	2	
	•	•	•	•	
le tools & resou	irces				
ify the challenge/opportunity, derive insights from the customer/user interviews, & build a solution and validate the l feasibility of the solution					
on.					
	0	0	6	6	
oing -Risk of inn oric (FIR)	ovations	- Defini	ing &va	idating	
OVERY	0	0	6	6	
olkit) -Custome y, and incidence ption barriers of	e - Discov	ver & id			
TION	0	0	6	6	
	Proposition	on -Buil	d a com	pelling	
quantify Value	0	0	6	6	
quantify Value l	y- MUP I	Design a	and Tech	nology	
DESIGN	•				
	and Feasibilit	and Feasibility- MUP I	and Feasibility- MUP Design a	and Feasibility- MUP Design and Tech	

proposition - Innovation Brief documentation (Proposal) - Demonstrate a PoC;

Total (30P) = 30 Periods

Tex	Text Books:				
1.	Tim Brown, Change by Design:How design thinking transforms organizations and inspires innovation – HarperCollins e-books, 2009				
2.	Alexander Osterwalder, Value Proposition Design: How to Create Products and Services Customers Want (Strategyzer) - John Wiley & Sons, 2014				
3.	Ulrich Karl and Eppinger Steven D, Product Design and Development - McGraw Hill, 5th edition, 2020				
4.	Blank Steve, Four Steps to Epiphany: Successful strategies for products that win, KS Ranch, 5th edition, 2013				
Reference Books:					
1.	Everything you need about value proposition: https://blog.forgeforward.in/everything-you-need-to-know-about-value-proposition-7247493c940c				
2.	Test your Value Proposition:http://businessmodelalchemist.com/2012/09/test-your-value-proposition-supercharge-lean-startup-and-custdev-principles.html				
3.	Valuation Risk versus Validation Risk in Product Innovations:https://blog.forgeforward.in/valuation-risk-versus-validation-risk-in-product-innovations-49f253ca8624				
4.	User Guide for Product Innovation Rubric:https://blog.forgeforward.in/user-guide-for-product-innovation-rubric-857181b253dd				

5.	Innovation Risk Diagnostic - Product Innovation Rubric:https://blog.forgeforward.in/product-innovation-rubric-adf5ebdfd356
6.	Evaluating Product Innovations - proof, potential, & progress:https://blog.forgeforward.in/evaluating-product-innovations-e8178e58b86e

COURSE OUTCOMES: Upon completion of the course, the students will be able to:		Bloom's Taxonomy Mapped
CO1	Apply a scientific method to understand the inherent risks of product innovation	Apply
CO2	Apply innovation tools & techniques to validate the problem scenario and to assess the market potential of product innovation;	Apply
СОЗ	Design solution concept based on the proposed value by exploring various alternate solutions to achieve value-price fit;	Design
CO4	Demonstrate technical skills by applying technology to build and demonstrate proof of concept for the solution proposed;	Develop
CO5	Develop skills to articulate the solution concept into a proposal for grants.	Develop

22	2MC301	INDIAN CONSTITUTION		S	emest	er	V
PR	EREQUISI	TES	Category	MC	Cr	edit	0
.	-		TT /TT/ 1	L	T	P	ТН
NII	_		Hours/Week	2	0	0	2
Coı	ırse Learni	ng Objectives	1	•		I	
1	To learn th	e Fundamental Rights and Fundamental Duties of the India	an Constitution.				
2	To list the	Union and Territories in our Nation					
3	To know th	ne Finance, Trade and Commerce of our Nation					
4	To present	a systematic analysis of all dimensions of Indian Political	System				
5	To underst	and the power and functions of the Parliament, the Legislat	ture and the Judiciar	y			
	Unit I	FUNDAMENTAL RIGHTS		6	0	0	6
Unio	on and its Te	rritory– Citizenship– Fundamental Rights– Directive Princ	iples of State Policy	-Fundan	nental I	Outies	
	Unit II	UNION & TERRITORIES		6	0	0	6
The	Union-TheS	tates—TheUnionTerritories—ThePanchayats—TheMunicipali	ties				1
Į	Unit III	FINANCE, TRADE & COMMER	CE	6	0	0	6
	-	e Societies—The scheduled and Tribal Areas—Relations betwits—Trade and Commerce within the territory of India.	ween the Union and	the State	es–Fina	nce, Pr	operty,
Į	Unit IV	ELECTIONS		6	0	0	6
Serv	vices under th	te Union, the States-Tribunals-Elections-Special Provision	ns–Relating to certai	n Classe	s	ı	
	Unit V	MISCELLANEOUS AMENDMEN	NTS	6	0	0	6
Lan	guages– Eme	rgency Provisions– Miscellaneous– Amendment of the Co	onstitution.	1		I	1
]	Total=	30 Pe	riods

Tex	xt Books:
1	Subhash C.Kashyap, Our Constitution, National Book Trust, 2017.
2	Durga Das Basu, Introduction to the Constitution of India, Lexis Nexis, 2015.
3	M.V.Pylee, Constitutional History of India, S.Chand publishing, 2010
4	Granville Austin, The Indian Constitution: Cornerstone of a Nation, Oxford UniversityPress,1999.
Refe	erence Books:
1	Indian Constitution And Indian Polity 3 Rd Edition 2021 by Ganesha Subramanian, Pearson.
2	The Indian Constitution Oxford India Short Introductions 2012 Edition by Madhav Khosla , OUP India

	Course Outcomes: Upon completion of this course, the students will be able to:							
CO1	Understanding the Fundamental Rights and Duties	Understand						
CO2	Listing the agreement between the Union and the Territories	Remember						
CO3	Analysing the role of the constitution in a democratic society.	Analyse						
CO4	Explaining the key concepts of the Indian Political System.	Apply						
CO5	Presenting the structure and functions of the Central and State Governments, the Legislature and the Judiciary	Understand						

COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	-	-	1	-	-	3	-	3	2	1	1	2	1	-	1
CO2	-	-	1	-	-	3	-	3	2	1	1	2	1	-	1
СОЗ	-	-	1	-	-	3	-	3	2	1	1	2	1	-	2
CO4	-	-	1	-	-	3	-	3	2	1	1	2	1	-	2
CO5	-	-	1	-	-	3	-	3	2	1	1	2	1	-	-
Avg	-	-	1	-	-	3	-	3	2	1	1	2	1	-	2
	1	ı	2/2/1	indi	ootog gt	nonath	of com	olotion	(2 Uia	h 2 Ma	dium 1	Low)			

3/2/1 – indicates strength of correlation (3- High, 2- Medium, 1- Low)

22ME506	DYNAMICS AND METROLOGY LABORA	TORY	•2	SEMES	STER V	7
PREREQUIS	SITE:	Category	PC	Cro	edit	1.5
		Hours/Week	L	Т	P	ТН
		Hours/ Week	0	0	3	3

Course Objectives:

- To be familiar with different measuring equipment.
 Use of the instruments in industry for quality inspection
- 3. To know the need of accuracy in industry To know about balancing of rotating system
- 4. To be familiar with different measuring equipment.

LIST OF EXPERIMENTS

- 1. Governors- Determination of sensitivity, effort, etc.for Watt, Porter, Proell, Hartnell governors
- 2. Cam- Study of jump phenomenon and drawing profile of the cam.
- 3. Motorized Gyroscope-Verification of laws –Determination of gyroscopic couple.
- 4. Whirling of shaft-Determination of critical speed of shaft with concentrated loads.
- 5. Determination of moment of inertia by oscillation method for connecting rod and flywheel.
- 6. Vibrating system- Spring mass system-Determination of damping co-efficient of single degree of freedom system.
- 7. Determination of transmissibility ratio-vibrating table.
- 8. Determination of torsional frequencies for compound pendulum and fly wheel system with Lumped Moment of inertia.
- 9. Transverse vibration of Beam. Determination of natural frequency and deflection of beam.
- 10. Calibration of Vernier / Micrometer / Dial Gauge
- 11. Checking Dimensions of part using lip gauges
- 12. Measurements of Gear Tooth Dimensions.
- 13. Measurement of Taper Angle using sine bar/tool makers microscope.
- 14. Measurement of thread parameters
- 15. Checking the limits of dimensional tolerances using comparators (Mechanical/Pneumatic/Electrical)

Total (45P) = 45 Periods

	COURSE OUTCOMES: On completion of the course the student will be able to						
CO1	Handle different measurement tools.	Understand					
CO2	Perform measurements with accuracy.	Evaluate					
CO3	Avoid errors in measurement.	Analyze					
CO4	Understand balancing of equipment.	Understand					

COUR	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	3	2	2	3								3	1	2
CO2		2		3	1	1							1	2	3
CO3	3	1				2							2	3	1
CO4	2	3		1	3	1							3	2	1
Avg	2	2.2	2	2	2.3	1.3							2.2	2.0	1.7
	3/2/1 – indicates strength of correlation (3 – High, 2- Medium, 1- Low)														

22	EN501	PLACEMENT AND CAREER SKILLS LABO	ORATORY	S	EMES	STER V	7
PRI	E-REQUIS	ITE:	Category	HS	Cr	edit	1.5
		lge in reading skill and writing skill n listening skill and speaking skill	Hours/Week	L 0	T 0	P 3	TH 3
Cou	rse Object	ives:					
1.	To develo	o the students' confidence and help them to attend interviews s	uccessfully				
2.	To express	s opinions, illustrate with examples and conclude in group disc	ussions				
3.	To acquire	knowledge to write error free letters and prepare reports					
4.	To enhance	e the employability and soft skills of students					
U	I NIT I	WRITING SKILLS		0	0	10	10
Lette	er of invitati	on, Resume and cover letter, Job application, E-mail writing, R	Report writing, progr	ess in pr	oject w	ork	
U	NIT II	SPEAKING SKILLS		0	0	10	10
		s and vote of thanks, Power point presentation, Presenting the ons, understanding group dynamics, Brain-storming the topics	•	Group di	scussio	n, partic	ipating
Ul	NIT III	CAREER SKILLS		0	0	10	10
		nd career skills, Self-introduction, introducing oneself to the te, Dress code, Body language, Attending job interviews	audience, introduc	ing the t	opic, Iı	nterview	skills,
Ul	NIT IV	VERBAL ABILITIES		0	0	10	10
Erro	r Spotting, I	istening Comprehension, reading comprehension, Rearranging	g Jumbled sentences	, Vocabu	lary		
U	NIT V	REASONING ABILITIES			0	5	5
				0	U	5	
	es completio	n, Analogy, Classification, Coding-Decoding, Blood relations,	Seating Arrangeme				
			Seating Arrangeme	ents, Dire	ctional		Logical
reaso		n, Analogy, Classification, Coding-Decoding, Blood relations,	Seating Arrangeme	ents, Dire	ctional	Sense, I	Logical
reaso	erence Boo	n, Analogy, Classification, Coding-Decoding, Blood relations,		ents, Dire	ctional	Sense, I	Logical
reaso	erence Boo	n, Analogy, Classification, Coding-Decoding, Blood relations,	Hyderabad, 2017.	ents, Dire	ctional	Sense, I	Logical
Refe	Campus I John Seel	n, Analogy, Classification, Coding-Decoding, Blood relations, ks: Recruitment Complete Reference, Praxis Groups (5th edition),	Hyderabad, 2017. sity Press, New Delf	Tota	ctional	Sense, I	Logical
Ref e 1. 2.	Campus I John Seel	n, Analogy, Classification, Coding-Decoding, Blood relations, ks: Recruitment Complete Reference, Praxis Groups (5th edition), y, The Oxford Guide to Writing and Speaking, Oxford University	Hyderabad, 2017. sity Press, New Delf	Tota	ctional	Sense, I	Logical
Refe 1. 2. 3.	Campus I John Seel	n, Analogy, Classification, Coding-Decoding, Blood relations, ks: Recruitment Complete Reference, Praxis Groups (5th edition), y, The Oxford Guide to Writing and Speaking, Oxford University	Hyderabad, 2017. sity Press, New Delf	Tota	ctional	Sense, I	Logical
Refe 1. 2. 3.	Campus I John Seel R.S. Agg	n, Analogy, Classification, Coding-Decoding, Blood relations, ks: Recruitment Complete Reference, Praxis Groups (5th edition), y, The Oxford Guide to Writing and Speaking, Oxford University	Hyderabad, 2017. sity Press, New Delf	Tota	ctional	Sense, I	Logical

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:						
CO1	Participate in group discussion and interview confidently	Evaluate					
CO2	Develop adequate soft skills and career skills required for the workplace	Create					
СОЗ	Make effective presentations on given topics	Create					
CO4	Apply their verbal ability and reasoning ability in campus interviews	Apply					

COU	COURSE ARTICULATION MATRIX														
CO/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1				1					2	3		1			1
CO2				2					2	3		1			2
CO3				2					1	3		1			1
CO4				1					2	3		1			2
Avg				1.5					1.75	3.0		1.0			1.5
	3 / 2 / 1 – indicates strength of correlation (3 – High, 2 – Medium, 1 – Low)														

	- 0.					,,			
PRER	EQUISI	ITES:	Category	PC	Cro	edit	1.5		
1.Basic	knowled	ge about the modes of heat transfer	Hours/Week	L	Т	P	ТН		
2.Conce	ept of psy	chrometry and refrigeration and air conditioning systems	Hours, week	0 0 3		3	3		
Course	e Object	tives:							
1.	Applyii	ng the concepts and laws of conduction heat transfer in real equ	aipment						
2.	Practici	ing to estimate the heat transfer coefficient values of various flu	uids.						
3.	Experir	menting and analyzing the heat transfer phenomena in boiling a	and condensation he	at excha	ngers				
4.	Determ	ining the radiation heat transfer parameters for black and grey	surfaces and calibra	ation of t	hermoco	uples			
5.	Studying the performance analysis of the refrigeration and air-conditioning systems and cooling towers.								

HEAT TRANSFER AND REFRIGERATION LABORATORY

LIST OF EXPERIMENTS:

- 1. Thermal conductivity measurement of pipe insulation using lagged pipe apparatus.
- 2. Determination of thermal conductivity of a composite wall, insulating powder.
- 3. Determination of heat transfer coefficient of air under natural convection and forced convection.
- 4. Heat transfer from pin-fin under forced convection heat transfer.
- 5. Determination of heat flux under pool boiling and flow boiling in various regimes.
- 6. Determination of heat transfer coefficient in film-wise and drop-wise condensation.
- 7. Determination of friction factor, heat transfer coefficient of cold/hot fluids and effectiveness oftube-in-tube heat exchanger.
- 8. Determination of Stefan Boltzmann constant.

22ME507

- 9. Determination of emissivity of a grey surface.
- 10. Calibration of thermocouples / RTDs at standard reference temperatures.
- 11. Determination of Coefficient of Performance of a vapor compression refrigeration system
- 12. Determination of Coefficient of Performance of an Air-Conditioning system.
- 13. Determination of effectiveness of a cooling tower.

Total (45P) = 45 Periods

SEMESTER V

	RSE OUTCOMES: npletion of the course the student will be able to	Bloom's Taxonomy Mapped
CO1	Calculate the thermal conductivity of various conducting and non-conducting materials	Evaluate
CO2	Estimate the heat transfer coefficient in free and forced convections for various geometries.	Evaluate
CO3	Evaluate the heat flux and the heat transfer coefficient in various types of heat exchangers	Evaluate
CO4	Obtain the radiation parameters such as emissivity, wave length and surface temperatures	Analyze
CO5	Test the performance of the refrigeration and air-conditioning systems and cooling towers.	Analyze

COURS	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	3		2									3	1	2
CO2	1	2	1	1									2	1	1
CO3	1	3	1										3		2
CO4	1	2	1	1									2		1
CO5	1	2		1									1	1	1
Avg	1	2.4	1	1.2									2.2	1	1.4
			3/2	/1 – in	dicates	strens	gth of c	correlat	ion (3	– High, 2	2- Mediu	m, 1- Lo	w)		

22ME601	MINI PROJECT		SEMESTER VI				
PREREQU	JISITE:	Category	EE	Cre	edit	3	
		Hours/Week	L	Т	P	TH	
		Hours/ Week	0	0	6	6	

Course Objectives:

- 1. Opportunity to design and develop small working models.
- 2. Develop experimental or simulation solutions to small industrial problems.
- 3. Facilitate problem identification, formulation and solution.
- 4. Work collaboratively in small groups.

The students may be grouped into groups of about 2 to 4 members per group and work under a project supervisor. The device / system / component(s) to be designed/ fabricated / investigated / analyzed may be decided in consultation with the supervisor. A project report to be submitted by the group and the fabricated model /investigation / analysis to be reviewed and evaluated continuously by a committee constituted by the head of the department / program coordinator.

FABRICATION PROJECT GUIDELINES

- a. Mechanical Assembly and Dismantling Models
- b. Day-life Usage Project
- c. New Scientific Invention
- d. Implementation of Mechanical Principle

Total (90P) = 90 Periods

	RSE OUTCOMES: npletion of the course the student will be able to	Bloom's Taxonomy Mapped
CO1	Initiate the students to come out with innovative ideas for various applications.	Create
CO2	Create an environment to convert the ideas into design of prototype for useful industrial, agricultural and social applications.	Create
CO3	Familiarize the feasibility study and manage activities to complete task in specified duration.	Understand
CO4	Assign and undertake tasks in a team as per team discussion.	Evaluate
CO5	Do presentation and write technical reports for effective communication within and outside the team.	Create

COURSE A	RTICU	JLATI	ON M	ATRI	<u>X</u>										
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	2	3	3	1	3		2		3	3	3
CO2	3	3	3	3	2	3	3		3		1		3	3	
CO3	2	2	2	2	2	1	1	1	3	1	2	3	3	3	
CO4	3	2	2	1	1	1	2	3	3	3		3	3	3	
CO5					2	2		1	3	3		2	3		3
Avg	2.2	2.0	2.0	1.8	1.8	2.0	1.8	1.2	3.0	1.4	2.0	1.6	3.0	2.4	1.2
			3/2/1 -	- indica	ates st	rength	of cor	relatio	n (3 – 1	High, 2-	Medium	, 1- Low	·)		

PROTOSEM COURSES SYLLABUS

	SPE01	COMPUTATIONAL HARDWAR	E	S	Semester		
PREI	REQUIS	ITES	Category	PE	Cre	edit	3
				L	Т	P	TH
			Hours/Week	3	0	0	3
Cour	se Learn	ing Objectives					
1		n basic concepts of Embedded Systems by familiarizing the furnment boards.	inctionalities of em	bedded	platforn	ns with	
		erstand the core concepts of GPIO Pins, Functionality of perip	herals, Selection of	I/O de	vices, U	Jsage	
2	of Inter	nal functions, and Communication protocols.					
3	To fami	lliarize the current technologies and protocols used in the Interest.	rnet of Things (IoT) and to	learn th	e Cloud	[
Uı	nit I	[9	0	0	9	
	g I/O - Tir	ners, Interrupts - Pulse Width Modulation - Display: 7-segme BASICS OF RASPBERRY PI	nt , LCD , OLED.	9	0	0	9
Raspb	erry Pi: R	aspberry pi Board - Processor - Setup and Configuration - Inc	stalling Python IDI	E using	g Comm	and Te	minal
Genera	al Purpose	I/O Pins - Protocol Pins - GPIO Access - Pulse Width Modul ot - Interfacing pi with camera modules.			-		
Un	it III	SENSORS AND ACTUATORS		9	0	0	9
Soil M	Ioisture Se	ensors and Actuators - Sensors: Introduction, Characteristics: Ansor, LDR - Digital - PIR Sensor, Smoke Sensor, Infrared - Saracteristics and working with relay, DC motors, Servo motors	Sensor, Ultra- Sonic	Sensor	. Actuat		sor,
Un	nit IV	COMMUNICATION PROTOCOLS	3	9	0	0	9
		d: RS232 Standard - UART, SPI, I2C - Comparative study of					
	ss Serial C	protocols Wireless: Standards - Bluetooth, RF - Comparative Communication protocols.	_	_			
wirele	ess Serial C	protocols Wireless: Standards - Bluetooth, RF - Comparative	_	_			
Ur Defini embed I/O pe	nit V	protocols Wireless: Standards - Bluetooth, RF - Comparative Communication protocols.	with IoT protocols e - Creating a serve	9 - MQT er on tar	o T, CoA	o P - Con	9 necting
Ur Defini embed I/O pe	nit V	protocols Wireless: Standards - Bluetooth, RF - Comparative Communication protocols. INTERNET OF THINGS Architecture of IoT, Building blocks of IoT, Programming very board to Web, Basics networking in IoT: creating a web page from the webpage, Embedded Application Development, Creating a web page from the webpage, Embedded Application Development, Creating a web page from the webpage, Embedded Application Development, Creating a web page from the webpage, Embedded Application Development, Creating a web page from the webpage, Embedded Application Development, Creating a web page from the webpage, Embedded Application Development, Creating a web page from the webpage from the	with IoT protocols e - Creating a serve	9 - MQT er on tar	o T, CoA get boar ween di	o P - Con	9 necting trolling nodes
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Ur Defini embed I/O pe Cloud	ition and Added targeteripherals platforms xt Books	INTERNET OF THINGS Architecture of IoT, Building blocks of IoT, Programming valoard to Web, Basics networking in IoT: creating a web page from the webpage, Embedded Application Development, Creating to IoT, Cloud data logging and monitoring, Interfacing with	with IoT protocols e - Creating a serve reating communica web services. ems", 4th Edition, N	9 - MQT er on tartion bet	o T, CoA get boa ween di	O P - Con rd - Con ifferent = 45 F	9 necting trolling nodes
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Refe	Reference Books:								
1	https://juniorfall.files.wordpress.com/2011/11/arduino-cookbook.pdf								
2	https://drive.google.com/file/d/13s0m3lHPEFP2f2aCuVNRWeBZNKXWKTW5/view?ts=6231cab 3								
3	https://ptolemy.berkeley.edu/books/leeseshia/releases/LeeSeshia_DigitalV2_2.pdf 4.								
4	https://www.riverpublishers.com/pdf/ebook/RP9788793519046.pdf								

	Course Outcomes: Upon completion of this course, the students will be able to:							
CO1	Understand and implement the functions & Capabilities of embedded platforms for easy prototyping.	L2: Understanding						
CO2	Identify the type of sensors and actuators for required applications.	L3: Applying						
СОЗ	Develop communication between devices using different protocols.	L3: Applying						
CO4	Develop IoT based systems with wireless network connections and accessing devices over cloud.	L3: Applying						

CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	3	2	3								3	2	2
CO2	3	3	2	2	2								3	2	2
CO3	3	2	3	2	3								3	3	3
CO4	3	2	3	2	3								3	3	3
AVG	3	2.25	2.75	2	2.75								3	2.5	2.5

3/2/1 – indicates strength of correlation (3- High, 2- Medium, 1- Low)

22PS	PE02	CODING FOR INNOVATORS		S	Semeste	er	VI
PRER	EQUIS	ITES	Category	PE	Cre	edit	3
				L	Т	P	TH
			Hours/Week	3	0	0	3
Cours	e Learn	ing Objectives		<u> </u>	<u> </u>		
1	To lear	n and express creativity using coding skills.					
2	To gair	n knowledge of Python programming with hands-on experience	e.				
3	To dem	onstrate a problem solving using OOPs concepts.					
4	To lear	n basics of Linux by familiarizing the concepts of managemen	t and file structure.				
5	To prac	ctise full stack development using cloud platform.					
Un	it I	PROGRAMMING PARADIGMS		9	0	0	9
Algorit Types o	hms - M	amming - Outside box thinking to solve problems - Need for emory Allocation - Conditions and loops - Creating effective mming languages & paradigms - Getting started with developm BASIC OF PROGRAMMING	functions - Case s	tudies -	Visual	Progran	nming -
Algorit Types (Uni Introdu operatio	hms - M of progra it II action to a ons, trav	emory Allocation - Conditions and loops - Creating effective mming languages & paradigms - Getting started with develop	functions - Case s ment - Build & test conditional stateme nctions, conversion	ents, loo	Visual prithm -	Programbest pra 0 nents, Li	nming - ctices 9 ists: list
Algorit Types o Uni Introdu operatio Operati	hms - M of progra it II action to a ons, trav	emory Allocation - Conditions and loops - Creating effective mming languages & paradigms - Getting started with develope BASIC OF PROGRAMMING Python: statements, variables, functions, operators, modules, cersing a list, slicing a list - Text Handling: Strings, string functions	functions - Case s ment - Build & test conditional stateme nctions, conversion	ents, loo	Visual prithm -	Programbest pra 0 nents, Li	nming - ctices 9 ists: list
Algorit Types o Uni Introdu operatio Operati Operati	it II action to actions: File t III S- Why C	BASIC OF PROGRAMMING Python: statements, variables, functions, operators, modules, cersing a list, slicing a list - Text Handling: Strings, string fur topen, close, read, copy, word frequency, creating word histog	functions - Case s ment - Build & test conditional stateme nctions, conversion grams from text file	tudies - t an algo 9 ents, loo n function	Visual prithm - 0 p statem ons, Dic	Program best pra	nming - ctices 9 ists: lists s - File
Uni Introdu operatio Operati OOPS Inheri	it II action to actions: File t III S- Why C	BASIC OF PROGRAMMING Python: statements, variables, functions, operators, modules, cersing a list, slicing a list - Text Handling: Strings, string fur to open, close, read, copy, word frequency, creating word histogroups. OOPS 5 OOPS- verticals- implementation in python - Classes and Objective manipulation of the control of the con	functions - Case s ment - Build & test conditional stateme nctions, conversion grams from text file	tudies - t an algo 9 ents, loo n function	Visual prithm - 0 p statem ons, Dic	Program best pra	nming - ctices 9 ists: lists s - File
Algorit Types of Uni Introdu operatio Operati OOPS Inheri Softwa Based - Sour	hms - M of progra it II action to a ons, trav ions: File t III b- Why C tance, Po t IV are Enginerate Code	BASIC OF PROGRAMMING Python: statements, variables, functions, operators, modules, cersing a list, slicing a list - Text Handling: Strings, string fur open, close, read, copy, word frequency, creating word histogroups. OOPS 5 OOPS- verticals- implementation in python - Classes and Object olymorphism, Abstraction, Encapsulation.	functions - Case s ment - Build & test conditional stateme nctions, conversion grams from text file cts, Methods, Const VERY cork - Why Framev periment from Devo	ents, loon function. 9 ents, loon function. 9 tructors y works -	orithm - orithm	Program best pra 0 ments, Listionarie 0 structors 0 re Testinoloymen	nming - ctices 9 ists: list s - File 9 is, 9 ing(Tool tt(D2D)
Uni Introdu operatio Operati OOPS Inheri Softwa Based - Sour	hms - M of progra it II action to a ons, trav ions: File t III b- Why C tance, Po t IV are Enginerate Code	BASIC OF PROGRAMMING Python: statements, variables, functions, operators, modules, cersing a list, slicing a list - Text Handling: Strings, string functions, copen, close, read, copy, word frequency, creating word histogroup, copen, close, read, copy, word frequency, creating word histogroup, words, and Object of the copen, close, read, copy, words, words, copen, close, read, copy, word frequency, creating word histogroup, copen, close, read, copy, word frequency, creating word histogroup, copen, close, read, copy, word frequency, creating word histogroup, copen, close, read, copy, word frequency, creating word histogroup, copen, close, read, copy, word frequency, creating word histogroup, copen, close, read, copy, word frequency, creating word histogroup, copen, close, read, copy, word frequency, creating word histogroup, copen, close, read, copy, word frequency, creating word histogroup, copen, close, read, copy, word frequency, creating word histogroup, copen, close, read, copy, word frequency, creating word histogroup, copen, close, read, copy, word frequency, creating word histogroup, copen, close, read, copy, word frequency, creating word histogroup, copen, close, read, copy, word frequency, creating word histogroup, copen, close, read, copy, word frequency, creating word histogroup, copen, close, read, copy, word frequency, creating word histogroup, copen, close, read, copy, word frequency, creating word histogroup, copen, close, read, copy, word frequency, creating word histogroup, copen, close, read, copy, word frequency, creating word histogroup, copen, close, read, copy, word frequency, creating word histogroup, copen, close, copy, copy, copy, copen, close, copy, co	functions - Case s ment - Build & test conditional stateme nctions, conversion grams from text file cts, Methods, Const VERY cork - Why Framev periment from Devo	ents, loon functions. 9 ents, loon functions. 9 tructors y works - elopment	orithm - orithm	Program best pra 0 ments, Listionarie 0 structors 0 re Testinoloymen	nming - ctices 9 sists: list s - File 9 s, 10 11 11 11 11 11 11 11 11 11 11 11 11
Uni Introdu Operatio OOPS Inheri Softwa Based - Sour service Uni Introdu - File S	hms - M of progra it II action to a ons, trav ions: File t III b- Why C tance, Po t IV are Engin) - Data S are code e - Herole it V action to b	BASIC OF PROGRAMMING Python: statements, variables, functions, operators, modules, cersing a list, slicing a list - Text Handling: Strings, string fur open, close, read, copy, word frequency, creating word histogroup, close, read, copy, word frequency, creating word histogroup, and the colymorphism, Abstraction, Encapsulation. SOFTWARE DEVELOPMENT TO DELIP neering - Life Cycle (Tools), Agile Methodologies - Framew Structures - Database Management System - A case study to expending and version control - GitHub - GitHub Actions and - Build Packs AWS- Anaconda OPERATING SYSTEMS Linux - Process Management - Process Scheduling - Memory Management - Multithreading - Multicore Programming - Deadlock and control - GitHub - OPERATING SYSTEMS	functions - Case s ment - Build & test conditional stateme nctions, conversion grams from text file cts, Methods, Const VERY ork - Why Framev periment from Deve - GitBash - Contin	ents, loon functions. 9 ents, loon functions. 9 ents, loon functions. 9 ents, loon functions.	Visual prithm - 0 p statem ons, Dic on and Des on to Depart to De	Program best pra 0 ments, Litionarie 0 structors 0 re Testinoloymen n - Plat 0 t - Syste	nming - ctices 9 ists: lists s - File 9 is, 9 ing(Tool at (D2D) form as

Tex	t Books:
1	Zed A. Shaw, "Learn Python 3 the Hard Way", 3rd edition, Addison-Wesley Professional, 2013.
2	Silberschatz Abraham, "Operating System Concepts", 9th edition, John Wiley & Sons Inc (Sea)Pte Ltd, 2016.
3	Paul Barry, "Head-First Python", 2nd edition, O'Reilly Media, Inc, 2016.
4	Anton Spraul, "Think Like a Programmer", 1st edition, No Starch Press, 2012.

E-Re	E-References:								
1	https://www.geeksforgeeks.org/python-programming-language/								
2	https://www.guru99.com/python-tutorials.html								
3	https://www.tutorialspoint.com/python/python_tutorial.pdf								

	se Outcomes: completion of this course, the students will be able to:	Bloom's Taxonomy Level
CO1	Understand the aspects of programming protocols	L2: Understanding
CO2	Develop optimized code for real-world problems	L3: Applying
CO3	Build full-stack development to deployment	L3: Applying
CO4	Demonstrate problem solving and continuous development	L2: Understanding

СО	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO 2	PSO 3
CO1	2	2	2	1	3								2	1	1
CO2	3	3	3	2	3								3	2	2
CO3	3	2	3	1	3								3	2	2
CO4	2	3	2	1	2							3	2	1	1
AV G	2.5	2.5	2.5	1.25	2.75							3	2.5	1.5	1.5

3/2/1 – indicates strength of correlation (3- High, 2- Medium, 1- Low)

22PS	SPE03	INDUSTRIAL AUTOMATION		S	er	VI	
PRER	REQUIS	ITES	Category	PE	Cro	edit	3
				L	T	P	TH
			Hours/Week	3	0	0	3
Cours	se Learn	ing Objectives					
1		conceptual knowledge in Industrial Controllers by scaling or ing with various I/O peripherals.	f on-board devices a	and emb	edded b	oard	
2		LC by working on internal features and also interfacing with and standard communication protocols.	Sensors and actuate	ors alon	g HMI o	concept	using
3	To wor	k with FPGA boards and RT controllers for reprogrammable	embedded application	ons usir	ıg LabV	IEW	
4	Unders	and the concepts and design electronics circuits					
Un	nit I	it I INDUSTRIAL CONTROLLERS - I				0	9
applica	-	Data Logging from sensors - Interfacing Actuators: Relay, INDUSTRIAL CONTROLLERS - I		9	0	0	9
PLC - S Uni	SCADA it III	INDUSTRIAL COMMUNICATION PROT	OCOLS	9	0	0	9
Cloud	data logg	ing. Multi-sensor communication, Data parsing between Emberotocols - Implementation of Industrial Communication protocols	oedded platforms. C				
Uni	it IV	FPGA AND RT CONTROLLER PROGRA	MMING	9	0	0	9
		FPGA - Architecture - Operations in FPGA programming - FPG oduction to RT controllers - Architecture - Programming RT					
Un	it V	INDUSTRIAL CIRCUIT BOARD DES	IGN	9	0	0	9
Design Test po	rules, su	s circuits and to simulate in environment setup - Component pply & communication track rules - Component and footprint	selection - Creatin	g librar	ies- Sch	amatic /	
	documen	on for measurement - PCB Layout,placement rules - Footpri	editor -Understand	_	nerating	package	types ER an
	documen	on for measurement - PCB Layout,placement rules - Footpritation	editor -Understand	_	nerating	package g GERB	types ER an
Tex		on for measurement - PCB Layout,placement rules - Footpritation	editor -Understand	_	nerating	package g GERB	types ER an
Tex	documen	on for measurement - PCB Layout,placement rules - Footpritation	editor -Understand int, 3D models, Bol	_	nerating	package g GERB	types ER an
	kt Books Ed Doe	on for measurement - PCB Layout, placement rules - Footpritation	editor -Understand int, 3D models, Bol	Ms - Ge	nerating	package g GERB	types ER an

Simon Monk, Make Your Own PCBs with EAGLE, McGraw Hill Education, 2014.

Refere	References Books:							
1	Jeffrey Travis, Jim Kring, LabVIEW for Everyone: Graphical Programming Made Easy and Fun,3rd edition, Prentice Hall							
2	Mikell P. Groover, Automation, Production Systems, and Computer-integrated Manufacturing, Fourth edition, Pearson Education, 2016							
3	Michael J. Hamill, Industrial Communications and Control Protocols, PDH centre, 2016							
4	Ema Design Automation, The Hitchhiker's Guide to PCB Design, First edition, Blurb Publishers, December 2021							

	completion of this course, the students will be able to:	Bloom's Taxonomy Level
CO1	Understand the usage of controllers in an industrial environment	L2: Understanding
CO2	Build Real-Time systems for Industrial embedded monitoring and controlling deterministic applications	L3: Applying
CO3	Communicate between devices at different levels using industrial protocols	L3: Applying
CO4	Understand the process involved in PCB design using EDA tools and fabricate it	L2: Understanding

СО	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO 2	PSO3
CO1	3	2	2	1	3								3	2	2
CO2	3	3	3	2	3								3	3	3
CO3	3	2	3	2	3								3	3	3
CO4	3	2	3	2	3								3	3	2
AV G	3	2.25	2.75	1.75	3								3	2.75	2.5

3/2/1 – indicates strength of correlation (3- High, 2- Medium, 1- Low)

22PS	SOE01	APPLIED DESIGN THINKING		S	emeste	er	VI
PREI	REQUIS	ITES	Category	OE	Cre	edit	3
				L	T	P	TH
			Hours/Week	3	0	3	
Cour	se Learn	ning Objectives					
1	The cou	urse enables product innovators and early-stage startup founde	ers to learn the custo	omer de	velopme	ent proc	ess
2		iliarize with the tools & techniques & validate the inherent risks er-commitment & customer-acceptance.	s by linking their pr	ogress t	o custon	ner-mot	ivation,
3	To lear	n the system thinking concepts by reverse engineering techniq	ue.				
Uı	nit I	DESIGN THINKING PRINCIPLES	,	9	0	0	9
&emp	athy –buil	lding techniques, Mitigate validate risk with FIR(Forge Innova	ation Rubric) – Cas	e Studie	es.		
Ur Importand pr	nit II tance of cooblem inc	CUSTOMER-CENTRIC INNOVATIO ustomer-centric innovation – Problem Validation and Custome vidence- Customer Validation. Target user, User persona & user reviews and field visit.	DN or Discovery – Unde	9 erstandir	0		
Ur Importand pr – Cust	nit II tance of cooblem inc	CUSTOMER-CENTRIC INNOVATIOnstoner-centric innovation – Problem Validation and Customeridence- Customer Validation. Target user, User persona & user	or Discovery – Under stories. Activity:	9 erstandir	0	em signi	ficance
Ur Importand pr – Cust Un Conce Design Propos	tance of croblem incomer inte	CUSTOMER-CENTRIC INNOVATION ustomer-centric innovation – Problem Validation and Custome vidence- Customer Validation. Target user, User persona & user rviews and field visit. APPLIED DESIGN THINKING TOOM imum Usable Prototype(MUP) – MUP challenge brief – Design Value Proposition: Design a compelling value propositing.	ON or Discovery – Under stories. Activity: LS gning & Crafting th	9 erstandir Custome	ong proble er develo	em signi opment 0 tion –	ficance process 9
Ur Importand pr – Cust Un Conce Design Propos	nit II tance of cu oblem inc comer inte it III pt of Mining and T	CUSTOMER-CENTRIC INNOVATION ustomer-centric innovation – Problem Validation and Custome vidence- Customer Validation. Target user, User persona & user rviews and field visit. APPLIED DESIGN THINKING TOOM imum Usable Prototype(MUP) – MUP challenge brief – Design Sesting Value Proposition: Design a compelling value proposition.	ON or Discovery – Under stories. Activity: LS gning & Crafting th	9 erstandir Custome	ong proble er develo	em signi opment 0 tion –	ficance process
Ur Importand pr - Cust Un Conce Design Propos Un Solution	nit II tance of cu oblem inc tomer inte it III pt of Mini ning and T sition Des it IV on Exploration to the right p	CUSTOMER-CENTRIC INNOVATION ustomer-centric innovation – Problem Validation and Custome vidence- Customer Validation. Target user, User persona & user rviews and field visit. APPLIED DESIGN THINKING TOOM imum Usable Prototype(MUP) – MUP challenge brief – Design Value Proposition: Design a compelling value propositing.	DN or Discovery – Under stories. Activity: LS gning & Crafting th tion: Process, tools the solution concep	9 erstandir Custome 9 e value and tech	ong proble er develo	em signification of Value	ficance process 9 e 9 earn;
Ur Importand pr – Cust Un Conce Design Propos Un Solution build talterna	nit II tance of cu oblem inc tomer inte it III pt of Mini ning and T sition Des it IV on Exploration to the right p	CUSTOMER-CENTRIC INNOVATION ustomer-centric innovation – Problem Validation and Custome vidence- Customer Validation. Target user, User persona & user reviews and field visit. APPLIED DESIGN THINKING TOOM imum Usable Prototype(MUP) – MUP challenge brief – Design Testing Value Proposition: Design a compelling value proposition. CONCEPT GENERATION ation, Concepts Generation and MUP design – Conceptualize prototype: Assess capability, usability and feasibility. Systematical contents are conceptually and feasibility. Systematical contents are contents are contents are contents are contents are contents.	DN or Discovery – Under stories. Activity: LS gning & Crafting the tion: Process, tools the solution conceptic concept generations.	9 erstandir Custome 9 e value and tech	ong proble er develo	em signification of Value	ficance process 9 e 9 earn;
Ur Importand pr - Cust Un Conce Design Propos Un Solution build t alterna Ur	tance of croblem increment in the state of Minimum and Tasition Destrict IV on Exploration Exploration in the right parties and the right parties and the right parties and the right parties and the right when Thinking in the right parties and the right parties are right parties are right parties are right parties are right parties and the right parties are right part	CUSTOMER-CENTRIC INNOVATION ustomer-centric innovation – Problem Validation and Custome vidence- Customer Validation. Target user, User persona & user reviews and field visit. APPLIED DESIGN THINKING TOOM imum Usable Prototype(MUP) – MUP challenge brief – Design Testing Value Proposition: Design a compelling value proposition. CONCEPT GENERATION ation, Concepts Generation and MUP design – Conceptualize prototype: Assess capability, usability and feasibility. Systematic the solution concepts.	DN or Discovery – Under stories. Activity: LS gning & Crafting the tion: Process, tools the solution conceptic concept generation conception conceptio	e value and technology evalue on; evalue	ong proble er develong proposite hniques one, itera luation to	em signi opment	ficance process 9 e 9 earn; gy

Tex	at Books:
1	Steve Blank, (2013), The four steps to epiphany: Successful strategies for products that win, Wiley.
2	Alexander Osterwalder, Yves Pigneur, Gregory Bernarda, Alan Smith, Trish Papadakos, (2014), Value
3	Proposition Design: How to Create Products and Services Customers Want, Wiley
4	Donella H. Meadows, (2015), "Thinking in Systems -A Primer", Sustainability Institute.
5	Tim Brown, (2012) "Change by Design: How Design Thinking Transforms Organizations and Inspires Innovation", Harper Business.

Refe	rence Books:
1	https://www.ideou.com/pages/design-thinking#process
2	https://blog.forgeforward.in/valuation-risk-versus-validation-risk-in-product-innovations-49f253ca8624
3	https://blog.forgeforward.in/product-innovation-rubric-adf5ebdfd356
4	https://blog.forgeforward.in/evaluating-product-innovations-e8178e58b86e
5	https://blog.forgeforward.in/user-guide-for-product-innovation-rubric-857181b253dd6
6	https://blog.forgeforward.in/startup-failure-is-like-true-lie-7812cdfe9b85

	e Outcomes: completion of this course, the students will be able to:	Bloom's Taxonomy Level
CO1	Define & treat various hypotheses to mitigate the inherent risks in product innovations	L1: Remembering
CO2	Design the solution concept based on the proposed value by exploring various alternate solutions to achieve value-price fit.	L6: Creating
CO3	Develop skills in empathizing, critical thinking, analyzing, storytelling & pitching.	L3: Applying
CO4	Apply system thinking to reverse engineer a product/prototype and understand its internal correlations.	L3: Applying

СО	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO 1	PSO 2	PSO 3
CO1	2	3	2	3	2	1	1	1	1	1	1	1	2	2	3
CO2	2	2	3	2	2	1	1	1	1	1	1	1	3	3	2
CO3	1	2	2	1	1	3	1	1	3	3	1	1	1	1	1
CO4	2	3	3	3	3	2	2	1	2	2	1	1	3	3	3
AVG	1.75	2.5	2.5	2.25	2	1.75	1.25	1	1.75	1.75	1	1	2.25	2.25	2.25

3/2/1 – indicates strength of correlation (3- High, 2- Medium, 1- Low)

PRER	EQUIS	ITES	Category	y OE Credit			
			**	L	Т	P	TH
			Hours/Week	3	0	0	3
Cours	e Learn	ing Objectives					
1	Learn t	he science of to transforming an innovative idea into high-gro	wth enterprises.				
2	To und	erstand the basic concepts of IPR, and develop a patent draft for	or a potential IP				
Un	nit I	ENTREPRENEURIAL MINDSET & MET	ГНОД	9	0	0	9
		Innovation-led, tech-powered entrepreneurship - Understate of the University of the			ttributes	s of an	expert
Un	it II	IDEA TO ENTERPRISE		9	0	0	9
U		nning of Product Concept - Business Model - Business Plannin and Revenue Planning	g - Building Proof	of Prod	uct and	Value T	esting -
Uni	t III	MINIMUM VIABLE BUSINESS		9	0	0	9
		Minimum Viable Business - Disruptive Innovation - Theory obusiness model - Demystifying Scalability - Funding Opportun	•	petitive	advanta	age - Bu	ilding
Uni	it IV	INTELLECTUAL PROPERTY		9	0	0	9
		nd the need for Intellectual Property Rights - IPR Genesis an					
Secret trends Un	t - Geogr s - Patent it V	aphical Indicators - Industrial Designs - Types of Patent – Sa fees PRIOR ART SEARCH AND PATENT DRA	AFTING	eation -	IPR in	INDIA;	Global 9
Secret trends Un Prior A basmat The inv	it V art Search i rice.	raphical Indicators - Industrial Designs - Types of Patent – Sa fees	AFTING ase Study on Apple attributes in patent	9 vsSams	Ouung, Ca	INDIA; 0 se study	9 on visional
Un Prior A basmat The inv specific	it V art Search i rice. vention a cations -	PRIOR ART SEARCH AND PATENT DRA - IP Licensing – IP Commercialization - IP Infringement- Ca s a concept - Keywords formation - Structure of patent - Key Drafting complete specifications - Draft claims - Case studies	AFTING ase Study on Apple attributes in patent	9 vsSams	Ouung, Ca	O see study	9 on visional
Un Prior A basmat The inv specific	it V Art Search i rice. vention a cations - i	PRIOR ART SEARCH AND PATENT DRA - IP Licensing – IP Commercialization - IP Infringement- Ca s a concept - Keywords formation - Structure of patent - Key Drafting complete specifications - Draft claims - Case studies	AFTING se Study on Apple attributes in patent onpatent drafting	9 vsSams	O ung, Ca g -Draft Total	o se study ting prov = 45 P	9 on visional
Un Prior A basmat The inv specific	it V Art Search i rice. vention a cations - Steven I Compar	PRIOR ART SEARCH AND PATENT DRA a - IP Licensing – IP Commercialization - IP Infringement- Ca s a concept - Keywords formation - Structure of patent - Key Drafting complete specifications - Draft claims - Case studies Blank and Bob Dorf, (2012), The Startup Owner's Manual: The	AFTING se Study on Apple attributes in patent onpatent drafting ne Step-by-Step Gu	9 vsSams draftin	O Jung, Ca g -Draft Total Building	o se study ting prov = 45 P	9 on visional
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Prior A basmat The inv specific	it - Geogra - Patent it V Art Search i rice. vention a cations - Cat Books Steven Compar Dr Sara series. Elizabet	PRIOR ART SEARCH AND PATENT DRA 1 - IP Licensing – IP Commercialization - IP Infringement- Cass a concept - Keywords formation - Structure of patent - Key Drafting complete specifications - Draft claims - Case studies Blank and Bob Dorf, (2012), The Startup Owner's Manual: The Thy, K&S Ranch Sarasvathy, (2008), Effectuation: Elements of Entrepreneurists the Verkey, (2005), Law of Patents, Eastern Book Company tha Ganguli, (2017), Intellectual Property Rights: Unleashing the Cass of Patents of Entrepreneurists and Canguli, (2017), Intellectual Property Rights: Unleashing the Cass of Patents of Entrepreneurists and Canguli, (2017), Intellectual Property Rights: Unleashing the Cass of Patents, Eastern Book Company	AFTING ase Study on Apple attributes in patent onpatent drafting the Step-by-Step Gu al Expertise, New I	9 vsSams draftin ide for	O ung, Ca g -Draft Total Buildings s in Entre	o se study ting prov = 45 P	9 on visional Periods t
Prior A basmat The inv specific Tex 1 2 3 4	it V art Search i rice. vention a cations - tat Books Steven I Compar Dr Sara series. Elizabet Prabudo	PRIOR ART SEARCH AND PATENT DRA 1 - IP Licensing – IP Commercialization - IP Infringement- Cases a concept - Keywords formation - Structure of patent - Key Drafting complete specifications - Draft claims - Case studies Blank and Bob Dorf, (2012), The Startup Owner's Manual: The ray, K&S Ranch as Sarasvathy, (2008), Effectuation: Elements of Entrepreneurists the Verkey, (2005), Law of Patents, Eastern Book Company tha Ganguli, (2017), Intellectual Property Rights: Unleashing the company of the Canada and the company of the Ganguli, (2017), Intellectual Property Rights: Unleashing the company of the Canada and the company of the company of the Canada and the company of the Canada and the company of the Canada and the company of the company of the Canada and the company of the Canada and the company of the company of the Canada and the company of the company of the Canada and the company of the company of the Canada and the company of the Canada and the company of the company of the Canada and the company of the	AFTING ase Study on Apple attributes in patent onpatent drafting the Step-by-Step Gu al Expertise, New I	9 vsSams draftin ide for	O ung, Ca g -Draft Total Buildings s in Entre	o se study ting prov = 45 P	9 on visional Periods t
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Prior A basmat The inv specific Tex 1 2 3 4 Refe	at - Geogra - Patent it V Art Search in rice. vention a cations - I at Books Steven I Compar Dr Sara series. Elizabet Prabudo 1st edition and 1st editio	PRIOR ART SEARCH AND PATENT DRA 1 - IP Licensing – IP Commercialization - IP Infringement- Case a concept - Keywords formation - Structure of patent - Key Drafting complete specifications - Draft claims - Case studies Blank and Bob Dorf, (2012), The Startup Owner's Manual: The ray, K&S Ranch as Sarasvathy, (2008), Effectuation: Elements of Entrepreneuricath Verkey, (2005), Law of Patents, Eastern Book Company tha Ganguli, (2017), Intellectual Property Rights: Unleashing ion 100ks: tellectual Property Handbook www.wipo.int/edocs/pubdocs/en/intproperty/489/wipo_pub_489	AFTING see Study on Apple attributes in patent onpatent drafting ne Step-by-Step Gu al Expertise, New I	9 vsSams draftin ide for	O ung, Ca g -Draft Total Buildings s in Entre	o se study ting prov = 45 P	9 on visional Periods t

STARTUP FUNDAMENTALS

VI

Semester

22PSOE02

	Course Outcomes: Upon completion of this course, the students will be able to:				
CO1	Develop an entrepreneurial mindset to identify, assess, shape & act on opportunities.	L3: Applying			
CO2	Demonstrate the potential of an innovative idea to create economic value, as a startup	L2: Understanding			
соз	Understand the scientific process to explore a viable business model	L2: Understanding			
CO4	Demonstrate knowledge on the fundamental concepts of Intellectual Property	L2: Understanding			

СО	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO1 0	PO1 1	PO1 2	PSO 1	PSO 2	PSO 3
CO1	1	2	2	1	1	2	1	2	2	2	3	3	1	1	2
CO2	2	2	3	1	1	1	1	2	2	1	3	2	2	2	2
CO3	1	2	2	2	1	1	1	1	1	1	3	2	1	1	1
CO4	1	1	1	1	1	1	1	3	1	1	1	1	1	1	1
AVG	1.25	1.75	2	1.25	1	1.25	1	2	1.5	1.25	2.5	2	1.25	1.25	1.5

3/2/1 – indicates strength of correlation (3- High, 2- Medium, 1- Low)

	PROTOTYPE DEVELOPMENT		S	emeste	er	VI			
PREREQUI	SITES	Category	OE	Cro	edit	3			
			L	T	P	TH			
		Hours/Week	3	0	0	3			
Course Lead	rning Objectives								
1 Learn	to design a UI/UX design and develop an android application.								
2 Provi	Provide working CAD model for prototype development.								
3 Know	ledge in hardware, 3D Printers and Laser cutters.								
4 Acqu	re basic knowledge in designing electrical circuits and fabrication	n of electronic dev	vices.						
Unit I	UI/UX		9	0	0	9			
	gn - Layout and composition for Web, Mobile and Devices - Typosss flow, wireframes, best practices in the industry -User engagen APP DEVELOPMENT				0	9			
Working with	luction to App Development - Types of Apps - web Developme Databases - Introduction to API - Introduction to Cloud services Embedding ML models to Apps - Deploying application.								
Unit III	INDUSTRIAL DESIGN		9	0	0	9			
to CAD tools	o Industrial Design - Points, lines, and planes - Sketching and con Types of 3D modeling - Basic 3D Modeling Tools - Part creationsioning & Tolerancing								
	MECHANICAL RAPID PROTOTYPIN	G	9	0	0	9			
Unit IV									
Need for proto methods - Too	htyping - Domains in prototyping - Difference between actual manuscript description of the street domains - Mechanical Prototyping: 3DPrint D Works - Additive manufacturing		• •	•	-				
Need for proto methods - Too	ls used in different domains - Mechanical Prototyping: 3DPrint	ting and classifica	• •	•	-				
Need for proto methods - Too engraving - Rl Unit V Electronic P	ls used in different domains - Mechanical Prototyping: 3DPrint D Works - Additive manufacturing	ting and classifica ${f G}$	tion - L	aser Cur	tting and	l			
Need for proto methods - Too engraving - Rl Unit V Electronic P	ls used in different domains - Mechanical Prototyping: 3DPrint D Works - Additive manufacturing ELECTRICAL RAPID PROTOTYPING rototyping: Basics of electronic circuit design - lumped circuits -	ting and classifica ${f G}$	tion - L	o Workin	tting and	9			

Te	xt Books:
1	Peter Fiell, Charlotte Fiell, Industrial Design A-Z, TASCHEN America Llc(2003)
2	Samar Malik, Autodesk Fusion 360 - The Master Guide.
3	Steve Krug, Don't Make Me Think, Revisited: A Common Sense Approach to Web Usability, Pearson,3rd edition (2014)
E -	References:
1	https://www.adobe.com/products/xd/learn/get-started.html
2	https://developer.android.com/guide
3	https://help.autodesk.com/view/fusion360/ENU/courses/
4	https://help.prusa3d.com/en/category/prusaslicer_204

	Course Outcomes: Upon completion of this course, the students will be able to:						
CO1	Create quick UI/UX prototypes for customer needs	L6: Creating					
CO2	Develop web application to test product traction / product feature	L3: Applying					
CO3	Develop 3D models for prototyping various product ideas	L3: Applying					
CO4	Built prototypes using Tools and Techniques in a quick iterative methodology	L3: Applying					

CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	3	2	3				1	1			2	1	1
CO2	3	3	3	2	3				1	1			3	2	2
CO3	3	2	3	2	3				1	1			3	2	2
CO4	3	2	3	2	3				1	1			3	2	2
AVG	2.75	2.25	3	2	3				1	1			2.75	1.75	1.75

3/2/1 – indicates strength of correlation (3- High, 2- Medium, 1- Low)

22PSE	EE01	ROBOTICS		S	emeste	er	VI
PRERE	EQUIS	ITES	Category	EE	Credit		3
				L	Т	P	TH
			Hours/Week	0	0	6	3
Course	Learn	ing Objectives					
1	Learn th	ne fundamentals of ROS					
2	Underst	and the requirements and choose the right sensors and actuator	ors for the application	on deve	lopment	t	
3	Create I	Bot in the virtual environment and simulate it to know the fund	ctionalities of the s	ystem d	evelope	d	
4	Learn th	ne basics of Robotics Vision System					
5	Integrat	e ROS and Computer Vision to build systems for various use	cases				
Unit	t I	INTRODUCTION TO ROBOT KINEMA	TICS	9	0	0	9
Kinema	atics - K	Robotics - Transformations - Forward Kinematics - Kineminematic analysis - Numerical Inverse Kinematic Solutions - A	Analytical Inverse	Kinema	tic Solu	tions	T
Unit	II	SELECTION OF SENSORS AND ACTUA	TORS	9	0	0	9
		ensors & Actuators - Types - Selection criteria - Design conside eed characteristics - Hardware Interface & Assembly	erations: Motor siz	ing - Se	lection	of moto	rs based
Unit	III	INTRODUCTION TO ROBOT OPERATING	SYSTEM	9	0	0	9
	grammi	ROS framework and prerequisites - Understanding communication of the ROS nodes, topics, messages - ROS services - ROS Tool Motion					
Unit	IV	INTRODUCTION TO ROBOTICS VISION S	SYSTEM	9	0	0	9
Gaussia	an, Med	Image Processing - Histograms - Gray scale, Color, Equalizati ian, Bilateral - Thresholding - Simple, Adaptive, Otsu -Gradie umera calibration					
Unit	\mathbf{v}	INTEGRATION OF ROS AND COMPUTER	VISION	9	0	0	9
Introduct real worl		stallation - CV Bridge - Image publisher node - Image subscribeations	oer node - Nodes bu	iildinga	nd launc	ching - H	Buildin

Tex	at Books:
1	Introduction to Robotics: Mechanics and Control by John J Craig, Pearson Publishers.
2	Robot Operating System (ROS) for Absolute Beginners by Lentin Joseph, A press; Publishers (2018).
3	Learning OpenCV by Gary Bradski, Adrian Kaehler, O'Reilly Media, Inc.

Refe	Reference Books:							
1	https://www.intechopen.com/chapters/379							
2	https://www.plantengineering.com/articles/eight-selection-criteria-for-actuation-components/							
3	https://www.controleng.com/articles/tips-on-sensor-selection/							
4	https://www.toptal.com/robotics/introduction-to-robot-operating-system							
5	https://www.thomasnet.com/articles/automation-electronics/machine-vision-systems/							
6	https://automaticaddison.com/working-with-ros-and-opency-in-ros-noetic/							

	Course Outcomes: Upon completion of this course, the students will be able to:					
CO1	Understand kinematics considerations of robot	L2: Understanding				
CO2	Selection of sensors and actuators according to application	L3: Applying				
CO3	Utilize the ROS environment to simulate and communicate between robot	L3: Applying				
CO4	Develop algorithms to extract features and data from image	L3: Applying				
CO5	Utilize the open CV for robotic applications	L3: Applying				

CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	3	1	2								3	3	2
CO2	3	3	2	1	2								3	3	3
CO3	3	2	3	2	3								3	3	3
CO4	3	3	3	2	3								3	3	2
AVG	3	2.5	2.75	1.5	2.5								3	3	2.5

3/2/1 – indicates strength of correlation (3- High, 2- Medium, 1- Low)

22M	E701	MECHATRONICS		S	SEMES	TER V	'II		
PREI	REQU	JISITE:	Category	PC Credit		edit	it 3		
Basics	s of ele	ctronics and electrical engineering		L	Т	P	TH		
Know	ledge i	n instrumentation and sensors	Hours/Week	2	0	0	3		
Basics	s of Hy	draulic and pneumatic systems		3	U	0	3		
COU	RSE (OBJECTIVES:							
1.		part knowledge about the elements and techniques involved in Mederstand the emerging field of automation.	chatronics system	s which	are ver	y much	essentia		
2.	To acc	quire adequate knowledge to model and simulate the physical system	ms.						
3.	To un	derstand issues of implementation of different actuation systems in	a Mechatronics s	ystem,					
4.	To ga	in practical experience in interfacing input and output devices to PL	.Cs						
5.	To ga	in practical experience in applying knowledge in the real word systems.							
UNI	TI	INTRODUCTION TO MECHATRONICS		9	0	0	9		
		Introduction to Mechatronic Systems- Mechatronic Products are s-Measurement systems- Control Systems- sequential controllers.	nd their function	ing- Ac	lvanced	applica	tions i		
UNI	TII	PHYSICAL SYSTEM MODELING		9	0	0	9		
	•	tem Models- zero order-first order- second order-mechanical anical systems, hydro-mechanical systems, pneumatic systems-Basi	•	•			•		
UNIT	ГШ	ACTUATION SYSTEMS		9	0	0	9		
actuat	ors– C	ors - Solenoids - Solid state switches - Stepper motors- Servo motors ontrol systems - PID Controllers - Artificial intelligence in mechanists and fuzzy systems.			•				
UNI	ΓΙ	PROGRAMMING LOGIC CONTROLLER	RS	9	0	0	9		
Mnem		to Programmable Logic Controllers – Basic Structure – Input / C-relays and counters – Shift registers – Master and Jump controls LC.			_		_		
UNI	T V	MECHATRONICS SYSTEMS DESIGN		9	0	0	9		
acquis	sition a	igning of Mechatronics systems – Traditional and Mechatronic desi nd control - Pick and place robot – automatic car park barrier syste tomated manufacturing.	-	-					

Total (45L) = 45 Periods

Text	Text Books:								
1.	Bolton, W, Mechatronics, Pearson Education, 6th Edition, 2015.								
2.	Ganesh S.Hegde, Mechatronics, Jones & Bartlett publishers, 1st Edition, 2010.								
Refe	Reference Books:								
1.	Michael B. Histand and David G. Alciatore, Introduction to Mechatronics and Measurement Systems, McGraw Hill International Editions, 3rd Edition, 2007								
2.	Bradley D. A., Dawson D., Buru N.C. and. Loader A.J, Mechatronics, Chapman and Hall, 1st Edition, 1993.								
3.	Dan Necsulesu, Mechatronics, Pearson Education Asia, 1st Edition, 2002								
4.	Brian Morriss, Automated Manufacturing Systems - Actuators, Controls, Sensors and Robotics, McGraw Hill International Edition, 1995								

5. Devadas Shetty, Richard A.Kolkm, Mechatronics system design, PWS publishing company, 2009

E-References:

1. https://onlinecourses.nptel.ac.in/noc21_me12

	RSE OUTCOMES: empletion of the course the student will be able to	Bloom's Taxonomy Mapped
CO1	Understand the basic elements underlying mechatronics systems and integrate them in the design of mechatronics systems.	Understand
CO2	Develop a simulation model for simple physical systems and illustrate mechatronics design process.	Analyze
СОЗ	Design, interface and understand issues of implementation of different actuation in a mechatronics system for a set of specifications.	Analyze
CO4	Interface electromechanical systems to PLCs.	Apply
CO5	Attain practical experience in applying knowledge gained in the course through a hands-on project.	Understand

COURSE	OURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2		2								1	1		2
CO2	2	2	3	3	1							2	2	2	
CO3			2	2			2		2			2			
CO4		2	3	3	3				3		3	2		2	1
CO5	1	2	2	3	3	2	2	1	3	2	1	3			3
Avg	1.3	2	2.5	2.6	2.3	2	2	1	2.6	2	2	2	1.5	2	2
			3/2	/1 – inc	dicates	streng	gth of c	orrelati	ion (3 –	High, 2	Mediun	n, 1- Low	⁷)		

PRE	EREQU	ISITE:	Category	PC	Cr	3	
		edge in mathematics with differentiation, integration, matrix	TT /537 1	L	T	P	TH
-		d numerical methods. edge in solid mechanics.	Hours/Week	3	0	0	3
COU	URSE (OBJECTIVES:				1	1
1.		ake the students to formulate the physical design problems into Fi olation, application of boundary conditions, assembly of global array					
2.	To ma	ke the students to apply FEM concept for developing FE equations fonts.	or solving 1-D pro	blems w	ith bar,	truss an	d bean
3.		ake the students to apply FEM concept for developing FE equations stress, plane strain and axisymmetric problems.	for solving 2-D pr	roblems	with CS	T eleme	ents fo
4.		uip the students about iso-parametric formulations for quadrilaterical integration.	ral element and a	pply the	e gauss	quadrat	ure fo
5.	To far	niliarize the students, apply FE equations for solving thermal and flu	uid flow problems	5.	1	_	1
UN	ITI	INTRODUCTION		9	0	0	9
Boun	ndary Va	nodels – Boundary, Initial and Eigen Value problems – Weighted Elue Problems – Ritz Technique – Basic concepts of the Finite Elements – ONE DIMENSIONAL EEA			Ī	1	
	IT II	ONE DIMENSIONAL FEA onal Second Order Equations – Discretization – Element types- Li		9	0	0	9
	IT III	TWO DIMENSIONAL FEA or 2D Equations involving Scalar Variable Functions – Variation	al formulation	9 Finite F	0 Element	0 formula	9
Trian	ngular el	ements and Quadrilateral elements- Shape functions and element ma strain and axisymmetric problems – Constitutive matrices and Strain	trices and vectors-	- Equatio	ons of ela	asticity -	- Plane
UNI	IT IV	ISOPARAMETRIC FORMULATION AND NUMI INTEGRATION	ERICAL	9	0	0	9
		dinate systems – Iso-parametric elements – Shape functions for iso	•				
		elements – Numerical integration-Lagrange's interpolation- Higher t - Applying numerical integration: 1, 2 and 3gauge point for 1D and				Quadra	tic and
	TT V	FEA APPLICATION TO HEAT TRANSFER AND MECHANICS		9	0	0	9
for h		neat transfer, 1D heat conduction governing Equations -Functional ap		nductio	ı n- Galer	kin's ap	<u> </u>
	ations of	luction - application to one-dimensional heat transfer problems- 11 Fluid Mechanics – Solid structure interaction - Inviscid and Incom			s proble	ems Gov	erning
	ations of			Potentia	s proble	ems Gov lations-	erning simple
	ations of			Potentia	s proble l Formu	ems Gov lations-	erning simple
Text	ations of lems.	Fluid Mechanics – Solid structure interaction - Inviscid and Incom		Potentia	s proble l Formu	ems Gov lations-	erning simple
Text	t Books	Fluid Mechanics – Solid structure interaction - Inviscid and Incom	pressible Flow –	Potentia Total	s proble l Formu	ems Gov lations- = 45 Po	erning simple
1.	t Books Tirupat Pearson	Fluid Mechanics – Solid structure interaction - Inviscid and Incom thin R. Chandrupatla and Ashok D. Belegundu, "Introduction to Finite	pressible Flow –	Potentia Total	s proble l Formu	ems Gov lations- = 45 Po	erning simple
1. 2.	t Books Tirupat Pearson	Fluid Mechanics – Solid structure interaction - Inviscid and Incom thi R. Chandrupatla and Ashok D. Belegundu, "Introduction to Finite and Education Limited, 2014. P, "Text Book of Finite Element Analysis", PHI Learning Pvt. Ltd.,	pressible Flow –	Potentia Total	s proble l Formu	ems Gov lations- = 45 Po	erning simple
1. 2.	t Books Tirupat Pearson Seshu.l	Fluid Mechanics – Solid structure interaction - Inviscid and Incom thi R. Chandrupatla and Ashok D. Belegundu, "Introduction to Finite and Education Limited, 2014. P, "Text Book of Finite Element Analysis", PHI Learning Pvt. Ltd.,	Pressible Flow – Elements in Engi New Delhi, 2012	Total	s proble l Formu l (45L)	ems Gov lations- = 45 Po	rerning simple

FINITE ELEMENT ANALYSIS

SEMESTER VII

22ME702

2.	Reddy, J.N. "Introduction to the Finite Element Method", 4th Edition, Tata McGrawHill, 2018							
3.	Dhanaraj. R and Prabhakaran Nair. K, "Finite Element Analysis", Oxford Publications, 2015.							
4.	David Hutton, "Fundamentals of Finite Element Analysis", Tata Mc Graw Hill, 2005							
5.	Robert D. Cook, David S. Malkus, Michael E. Plesha, Robert J. Witt, "Concepts and Applications of Finite Element Analysis", 4th Edition, Wiley Student Edition, 2004.							
E-R	deferences:							
1.	https://soaneemrana.com/onewebmedia/TEXT%20BOOKOF%20FINITE%20ELEMENT%20ANALYSIS%20BY%20P. %20SESHU%20.pdf							
2.	https://nptel.ac.in/courses/112104193							
3.	https://www.engr.uvic.ca/~mech410/lectures/FEA_Theory.pdf							

	COURSE OUTCOMES: On completion of the course the student will be able to					
CO1	Formulate the physical design problems into FEA including domain discretization, polynomial interpolation, application of boundary conditions, assembly of global arrays, and solution of the resulting algebraic systems.	Analyze				
CO2	Apply FEM concept for developing FE equations for solving 1-D problems with bar, truss and beam elements.	Apply				
СОЗ	Apply FEM concept for developing FE equations for solving 2-D problems with CST elements for plane stress, plane strain and axisymmetric problems.	Apply				
CO4	Derive iso-parametric formulations for quadrilateral element and apply the gauss quadrature for numerical integration.	Apply				
CO5	Apply the concepts of FEA for solving 1-D heat transfer and fluid flow problems under the given boundary conditions.	Apply				

COURS	E ART	<u>ICUL</u>	ATION	MATI	RIX		COURSE ARTICULATION MATRIX													
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3					
CO1	3	3	2	1	1		!						3	1						
CO2	3	3	2	1	1								3	1						
CO3	3	3	2	1	1								3	1						
CO4	3	3	2	1	1								3	1						
CO5	3	3	2	1	1		,						3	1						
Avg	3.0	3.0	2.0	1.0	1.0								3.0	1.0						
			3/2/1 -	– indica	tes strei	agth of c	correlat	ion (3 –	High, 2	2- Mediu	ım, 1- L	ow)								

22HS	701	OPERATIONS RESEARCH		S	EMES'	TER V	II
PRERE	QUIS	ITE:	Category	PC	Cr	edit	3
1. Know	ledge o	of basic mathematics		L	Т	P	TH
2. Knowl	ledge o	f probability distributions and statistics.	Hours/Week	3	0	0	3
COURS	SE OB	JECTIVES:	1			1	
1. To	o make	the students formulate linear programming problems and solve	them with in the giv	en const	raints fo	r optimi	zation
		the students solve transportation and production problems and into directives for action.	optimize, interpret th	ne result	s obtaine	ed and tr	anslat
3. To	o equip	the students solve replacement and sequencing problems and control into directives for action.	optimize, interpret th	e results	obtaine	ed and tr	anslate
		the students solve gaming theory and network models arising	from a wide range o	f application	ations.		
5. To	o famili	iarize the students about the procedures for queuing theory mo	dels and getting solu	itions us	ing sim	ulation.	
UNIT	I	INTRODUCTION AND LPP		9	0	0	9
UNIT I	II tation r	TRANSPORTATION AND ASSIGNMENT M models - Optimal solution by North West Corner method - Lea	IODELS ast Cost Method - Vo				
optimalit assignme		 MODI method - Assignment problem formulation - Hublems. 	ngarian method - U	Jnbalan	ced and	maxım	1 z at10
UNIT I	II	REPLACEMENT AND SEQUENCING MO	DDELS	9	0	0	9
policy - I	ndividu	items that deteriorate with time: value of money change with all and group replacement - Sequencing problems – Problems vachines, 2 jobs with k machines.	_		-	_	
UNIT I	V	THEORY OF GAMES AND NETWORK MO	ODELS	9	0	0	9
without s networks	saddle p - Netv	Minimax (maximin) – Criterion and optimal strategy – Solution points – 2 X 2 games – dominance principle – m X 2 & 2 X movements of the strategy of the strategy – Solution points – 2 X 2 games – dominance principle – m X 2 & 2 X movements of the strategy – Solution of the strategy – Solutio	n games -graphical n	nethod.	Construc	ction of	proje
CPM and							
CPM and UNIT	V	QUEUING THEORY AND SIMULATION	ON	9	0	0	9

Total (45L) = 45 Periods

Tex	t Books:							
1.	Hira and Gupta, "Introduction to Operations Research", S. Chand and Co, 2011.							
2.	Taha, H.A, "Operations Research", 9th Edition, Pearson Education India, 2014.							
Refe	erence Books:							
1.	S.D.Sharma - Operations Research , Kedarnath, Ramnath 2015							
2.	Hiller &Libermann - Introduction to O.R , Mc Graw Hill 2011							
3.	Sharma J.K, "Operations Research", 6th Edition Macmillan India Ltd, 2007.							
4.	A.M.Natarajan, P.Balasubramani, A.Tamilarasi -Operations Research, Pearson Education.							
5.	R.Pannerselvam - Operations Research ,PHI Publications 2006							
E-R	E-References:							
1.	https://nptel.ac.in/courses/110106062							

2.	https://onlinecourses.nptel.ac.in/noc19_ma29/preview
3.	https://nptel.ac.in/courses/110106059

	RSE OUTCOMES: upletion of the course the student will be able to	Bloom's Taxonomy Mapped
CO1	Formulate and solve linear programming problems for getting optimal solution under given constraints.	Apply
CO2	Solve transportation and production problems and optimize, interpret the results obtained and translate solutions into directives for action.	Analyze
CO3	Solve replacement and sequencing problems and optimize, interpret the results obtained and translate solutions into directives for action.	Analyze
CO4	Solve gaming theory and network models arising from a wide range of applications.	Analyze
CO5	Explain procedures for queuing theory models and getting solutions using simulation.	Understand

COURS	COURSE ARTICULATION MATRIX																	
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3			
CO1	1	2	2										2	2				
CO2		2	2									1	1	2	2			
CO3		2	2	2								1		2				
CO4		2	3			1						1	2	2				
CO5	1	2	2									1		2				
Avg	1	2.0	2.2	2		1						1	1.6	2.0	2			
			3/2/1	– indica	tes strei	ngth of o	3/2/1 – indicates strength of correlation (3 – High, 2- Medium, 1- Low)											

22ME703	MECHATRONICS LABORATO	SEMESTER VII						
PREREQUISIT	Е:	Category	PC	Cre	1.5			
1. Basics of electro	nics and electrical engineering		L	T	P	TH		
2. Knowledge in in3. Basics of Hydra	0	0	3	3				
						<u> </u>		

Course Objectives:

- 1. To provide automation concepts where students could perform experimental study regarding fundamental sequence control by utilising various hydraulic and pneumatic components.
- 2. To provide knowledge to assist the students in the development of "Hands On" skills with an emphasis on actuators and multidisciplinary systems.
- 3. To provide software knowledge to the engineering students to apply hardware and programming basics and absorb Mechatronics concepts.
- 4. To equip students with mechatronics knowledge and also gather knowledge of virtual instrumentation systems for mechanical engineering applications/
- 5. To promote interdisciplinary research and industry driven innovation in the cutting-edge areas of mechatronics.

LIST OF EXPERIMENTS

- 1. Design and testing of fluid power circuits to control
 - (i) velocity (ii) direction and (iii) force of single and double acting cylinders
- 2. Design and testing of cylinder sequences A+B+A-B- and A+B+B-A- of pneumatic circuits.
- 3. Design of Electro pneumatic circuits with logic sequence using Electro pneumatic trainer kits.
- 4. Design of Electro hydraulic circuits with logic sequence using Electro hydraulic trainer kits.
- 5. Simulation of basic Hydraulic, Pneumatic and Electro-hydraulic, Electro-pneumatic circuits using simulation software.
- 6. Design and simulation of Electro pneumatic circuits with PLC programming using simulation software.
- 7. Study the performance of DC motor.
- 8. Experiment on servo controller interfacing for closed loop control.
- 9. Stepper motor interfacing with 8051 Micro controller (i)full step resolution (ii) half step resolution
- 10. Maintain constant pressure of a process in a process station using PID controller in Virtual Instrumentation software.
- 11. Maintain constant temperature of a process in a shell and tube heat exchanger using PID controller in Virtual Instrumentation software.
- 12. Maintain constant flow rate of a process in a process station using PID controller in Virtual Instrumentation software.
- 13. Study the performance of 6- axis robot.

Total (45P) = 45 Periods

	RSE OUTCOMES: mpletion of the course the student will be able to	Bloom's Taxonomy Mapped
CO1	Select various control valves and use them in hydraulic and pneumatic circuit development	Understand
CO2	Get adequate knowledge to simulate the basic electric, hydraulic and pneumatic system using simulation software.	Understand
CO3	Get adequate knowledge about the characteristics of various actuators and methods of tuning of controller in a Mechatronic system.	Understand
CO4	Understand how to interface electromechanical systems to PLCs.	Understand
CO5	Gain practical experience in data acquisition system and develop and evaluate alternate solutions to real world problems.	Understand

COURS	E AR	TICU	LATI	ON N	IATR	<u>IX</u>									
Cos/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	3											1	1	1
CO2			1	2									1	2	2
CO3			1				1	2					2	1	3
CO4				3							2	3	2	1	3
CO5			3						2	1	2		2	2	3
Avg	1	3	1.5	2			1	2	2	1	2	3	1.6	1.4	2.4
	•		3/	/2/1 – i	ndicat	es stre	ngth o	f correl	ation (3 – High	, 2- Med	lium, 1- 1	Low)		

22ME704	SIMULATION LABORATORY		SE	ME	STER	VII
PREREQUIS	SITE:	CATEGORY	PC	Credit		1.5
1. Basic knowl	edge in any modeling software.	Hours/Week	L	T	P	TH
2. Fundamenta	knowledge in FEA.	nours/ week	0	0	3	3
COLIDEE OF	DIECTIVES.					

COURSE OBJECTIVES:

- 1. To make the students analyze the structural components for deflection, stress and reaction forces.
- 2. To make the students analyze the force, stress, deflection in mechanical components.
- 3. To make the students analyze thermal stress and heat transfer in mechanical components.
- 4. To make the students analyze the vibration of mechanical components.
- 5. To make the students analyze the modal, harmonic, transient and spectrum concepts in mechanical components.

LIST OF EXPERIMENTS

Analysis of Mechanical Components – Use of FEA packages, like ANSYS/ NASTRON etc.,

The following exercises includes FEA analysis of

- 1. Force and Stress analysis using link elements in Trusses.
- 2. Force and stress analysis using link elements in axially loaded bars.
- 3. Stress and deflection analysis in beams with different support conditions.
- 4. Stress analysis of flat plates.
- 5. Stress analysis of axis-symmetric components.
- 6. Thermal stress and heat transfer analysis of plates.
- 7. Thermal stress analysis of cylindrical shells.
- 8. Vibration analysis of spring-mass systems.
- 9. Modal analysis of Beams.
- 10. Harmonic, transient and spectrum analysis of simple systems

Total(45P) = 45 Periods

E-REFERENCES:

- 1. https://www.ansys.com/
- 2. https://bmsce.ac.in/Content/ME/MFELAB_manual_Jan2019_Updated_28_1_2019.pdf
- 3. https://confluence.cornell.edu/display/SIMULATION/ANSYS+Learning+Modules

	RSE OUTCOMES: mpletion of the course the student will be able to	Bloom's Taxonomy Mapped
CO1	Analyze the structural components for deflection, stress and reaction forces.	Analyze
CO2	Analyze the force, stress, deflection in mechanical components.	Analyze
CO3	Analyze thermal stress and heat transfer in mechanical components.	Analyze
CO4	Analyze the vibration of mechanical components.	Analyze
CO5	Analyze the modal, harmonic, transient and spectrum concepts in mechanical components.	Analyze

COURSE	ART	ICUL	ATIO	N MA	TRIX										
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2			3			1				1	1		
CO2	2	2			3			1				1	1		
CO3	2	2			3			1				1	2		
CO4	2	2			3			1				1	2		
CO5	2	2			3			1				1	2		
Avg	2.0	2.0			3.0	•		1.0				1.0	1.6		
			3/2	/1 – inc	dicates	strengt	th of co	rrelati	on (3 –	High, 2	- Mediur	n, 1- Lov	v)		

22ME705	CAM LABAROTARY		S	EMES	TER '	VII
PREREQUISITE:		CATEGORY	PC	Cre	edit	1.5
		Hanna/Wash	L	T	P	TH
		Hours/Week	0	0	3	3

COURSE OBJECTIVES:

- 1. To equip the students for implement CNC programs for milling and turning machining operations.
- 2. To create a computer aided manufacturing (CAM) model and generate the machining codes automatically using the CAM system.
- 3. Understand different operations that are to be executed to get a final product which include drilling and reaming operations.
- 4. Understand CNC machining and uses, and applications of CNC program.
- 5. Remember the purpose of other alphabetical commands used in programming operations of a CNC machine.

CAM EXPERIMENTS

Tool path generation, Part programming, G & M codes development for machining operations, Physical interpretation of machining features and tool geometries

Manual part programming

- CNC Turning Centre Facing, Turning, Chamfering, Taper turning, Thread cutting
- CNC Turning Centre Facing, Turning, Chamfering, Taper turning, Grooving, Threading using canned cycles
- CNC Milling Linear and circular Profile, Pocket, Drill, Peck-Drill, Bore, Tap- Using canned cycles.
- Part Program generation and tool path simulation for turning &milling for Fanuc Control System using CAM software.
- Demonstration on CNC Turning & Milling Machines

Total (45P) = 45 Periods

	RSE OUTCOMES: mpletion of the course the student will be able to	Bloom's Taxonomy Mapped
CO1	Understand the features and specifications of CNC machines	Understand
CO2	Develop the process planning sheets and tool layouts.	Apply
CO3	Understand the CAM software and its programming.	Understand
CO4	Use the CAM software and prepare CNC part programs.	Apply
CO5	Execute the part program and machine the component as per the production drawing.	Apply

COURSE	ART	CICUL	ATIO	N MA	TRIX	•									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	2	2	2	1			2		2		2	2	1
CO2	1	1	1	1							3		1	1	1
CO3	1	2	1	2	2	3					3		2	2	1
CO4	1	2	1	1	1	3					3		2	2	1
CO5	1	2	1	1	1	3					3		2	2	1
Avg	1.2	1.6	1.2	1.4	1.5	2.5			2		2.8		1.8	1.8	1.0
			3/2/1	l – indi	icates s	trengtl	h of co	relatio	on (3 –	High, 2-	Mediun	ı, 1- Low	r)		

22ME801	PROJECT WORK	SE	MES	TER '	VIII
PREREQUISITI	E: CATEGOR	Y EE	Cr	edit	10
	Hanna/Wash	L	Т	P	ТН
	Hours/Week	0	0	20	20

COURSE OBJECTIVES:

- 1. The main objective is to give an opportunity to the student to get hands on training in the fabrication of one or more components of a complete working model, which is designed by them.
- 2. It is intended to start the project work early in the seventh semester and carry out both design and fabrication of a mechanical device whose working can be demonstrated. The design is expected to be completed in the seventh semester and the fabrication and demonstration will be carried out in the eighth semester

GUIDELINE FOR REVIEW AND EVALUATION

The students may be grouped into 2 to 4 and work under a project supervisor. The device/system/component(s) to be fabricated may be decided in consultation with the supervisor and if possible, with an industry. A project report to be submitted by the group and the fabricated model, which will be reviewed and evaluated for internal assessment by a committee constituted by the Head of the Department. At the end of the semester examination the project work is evaluated based on oral presentation and the project report jointly by external and internal examiners (Supervisors) constituted by the Head of the Department.

Total (90P) = 90 Periods

	RSE OUTCOMES: mpletion of the course the student will be able to	Bloom's Taxonomy Mapped
CO1	Initiate and motivate the students to come out with innovative ideas for different applications.	Create
CO2	Create an environment to convert the ideas into design of prototype for useful industrial, agricultural and social applications.	Create
CO3	Create an environment to convert the design into manufacturing of prototype for useful industrial, agricultural and social applications.	Create
CO4	Assign and undertake tasks in a team as per team discussion.	Understand
CO5	Do presentation and write technical reports for effective communication within and outside the team.	Understand

COURSE	ART	ICUL	ATIO	N MA	TRIX										
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	2	3	3	1	3		2		3	3	3
CO2	3	3	3	3	2	3	3		3		1		3	3	
CO3	2	2	2	2	2	1	1	1	3	1	2	3	3	3	
CO4	3	2	2	1	1	1	2	3	3	3		3	3	3	
CO5					2	2		1	3	3		2	3		3
Avg	2.75	2.5	2.5	2.2	1.8	2	2.2	1.5	3	2.3	1.6	2.6	3	3	3
			3/2/1	l – indi	icates s	trengtl	h of co	rrelatio	on (3 –	High, 2-	Mediun	1, 1- Low	v)		

PROFESSIONAL ELECTIVE COURSES

<u>PROFESSIONAL ELECTIVES – I</u>

22MEPE11	AUTOMOBILE ENGINEERING		SE	MES	TER	VI
PREREQU	ISITES	CATEGORY	PE	Cro	edit	3
1. Engin	neering Mechanics	II /\ \	L	T	P	TH
2. Ther	modynamics and Thermal Engineering	Hours/Week	3	0	0	3
COURSE C	OBJECTIVES:					
1. To	broaden the understanding of students in the structure of vehicle cha	assis and engines				
2. To	teach students about the importance of alternate fuels and modifying	g the engine suitably				
3. Ana	alyze the working principles and operations details of transmission a	nd suspension syste	ms			
4. Eva	aluate the operational details and design principles of breaking and s	teering systems				
5. To	introduce students to engine auxiliary systems like heating, ventilati	on and air-condition	ing			
UNIT I	AUTOMOBILE VEHICLE STRUCTURE AND PERFO	ORMANCE	9	0	0	9
Operation an	components, subsystems and their positions- Chassis, frame and land performance, Traction force and traction resistance, Power required stance. Introduction to MV Act, Pollution Norms					
gradient resis	stance. Introduction to Mrv Act, Pollution Norms					
UNIT II	POWER TRAIN AND FUEL MANAGEMENT SYSTE		9	0	0	9
UNIT II Reciprocating Electronic Er and Hydroge	POWER TRAIN AND FUEL MANAGEMENT SYSTE g Engine systems, Hybrid systems. Pollutant emissions and their ngine Management systems for SI and CI engines. Liquid and gaseo en.	ir control; Catalytic	c conve Alcoho	erter s	syster G, CN	ms, NG,
UNIT II Reciprocating Electronic Er and Hydroge UNIT III	POWER TRAIN AND FUEL MANAGEMENT SYSTE g Engine systems, Hybrid systems. Pollutant emissions and thei ngine Management systems for SI and CI engines. Liquid and gaseo th. TRANSMISSION AND SUSPENSIONS SYSTEMS	ir control; Catalytic ous alternate fuels	c conve	erter s	syster G, CN	ms, NG,
UNIT II Reciprocating Electronic En and Hydroge UNIT III Transmission fluid fly who continuous v axles types, v bar, shock ab	POWER TRAIN AND FUEL MANAGEMENT SYSTE g Engine systems, Hybrid systems. Pollutant emissions and their ngine Management systems for SI and CI engines. Liquid and gaseo en. TRANSMISSION AND SUSPENSIONS SYSTEMS n system: Clutches - principle, types - single plate clutch, multiplate of eel. Gear boxes, types, constant mesh, synchromesh gear boxes, rariable transmission, propeller shaft, Hotch-Kiss drive, Torque tub wheels and tyres; Suspension system: Objects of suspension system psorber, independent suspension system	clutch, magnetic and epicyclic gear box e drive, universal jo	c converse specification of the conv	erter s l, LPC o ugal c transs	syster G, CN 0 clutch missi tial, r	ns, IG, 9 nes, on, ear ion
UNIT II Reciprocating Electronic Er and Hydroge UNIT III Transmission fluid fly who continuous vaxles types, vaxed in the continuous vaxed in the c	POWER TRAIN AND FUEL MANAGEMENT SYSTE g Engine systems, Hybrid systems. Pollutant emissions and their ngine Management systems for SI and CI engines. Liquid and gased en. TRANSMISSION AND SUSPENSIONS SYSTEMS In system: Clutches - principle, types - single plate clutch, multiplate of eel. Gear boxes, types, constant mesh, synchromesh gear boxes, variable transmission, propeller shaft, Hotch-Kiss drive, Torque tub wheels and tyres; Suspension system: Objects of suspension system	clutch, magnetic and epicyclic gear box e drive, universal jo	converse con	erter s l, LPC o ugal c transs	syster G, CN 0 clutch missi tial, r	ns, IG, 9 nes, on, ear
UNIT II Reciprocating Electronic Er and Hydroge UNIT III Transmission fluid fly who continuous vaxles types, vaxles types, values types, va	POWER TRAIN AND FUEL MANAGEMENT SYSTE g Engine systems, Hybrid systems. Pollutant emissions and their ngine Management systems for SI and CI engines. Liquid and gaseo en. TRANSMISSION AND SUSPENSIONS SYSTEMS n system: Clutches - principle, types - single plate clutch, multiplate of eel. Gear boxes, types, constant mesh, synchromesh gear boxes, rariable transmission, propeller shaft, Hotch-Kiss drive, Torque tub wheels and tyres; Suspension system: Objects of suspension system psorber, independent suspension system	clutch, magnetic and epicyclic gear box e drive, universal jons, rigid axle suspers, stopping distance clock braking system	centrific, auto sint, diffusion sy	o lugal of transiferent extern.	system of the system of the system of the system of the steer of the system of the sys	ms, IG, 9 eas, on, ear ion 9
UNIT II Reciprocating Electronic Er and Hydroge UNIT III Transmission fluid fly who continuous vaxles types, vaxles types, values types, va	POWER TRAIN AND FUEL MANAGEMENT SYSTE g Engine systems, Hybrid systems. Pollutant emissions and theingine Management systems for SI and CI engines. Liquid and gased en. TRANSMISSION AND SUSPENSIONS SYSTEMS In system: Clutches - principle, types - single plate clutch, multiplate of eel. Gear boxes, types, constant mesh, synchromesh gear boxes, rariable transmission, propeller shaft, Hotch-Kiss drive, Torque tub wheels and tyres; Suspension system: Objects of suspension system osorber, independent suspension system BRAKING AND STEERING SYSTEMS ethicles, tyre grip, load transfer, braking distribution between axle Hydraulic, Air brakes, Disc & Drum brakes, Engine brakes antickermann principle, Davis steering gear, steering gear boxes, st	clutch, magnetic and epicyclic gear box e drive, universal jons, rigid axle suspers, stopping distance clock braking system	centrific, auto sint, diffusion sy	o lugal of transiferent extern.	system of the system of the system of the system of the steer of the system of the sys	ms, IG, 9 eas, on, ear ion 9
UNIT II Reciprocating Electronic Er and Hydroge UNIT III Transmission fluid fly who continuous v axles types, v bar, shock ab UNIT IV Forces on ver Mechanical, systems - A geometry-case UNIT V General elect Lighting systems is Electronic Condition in the continuous of the continuous v axles types, v bar, shock ab UNIT IV	POWER TRAIN AND FUEL MANAGEMENT SYSTE g Engine systems, Hybrid systems. Pollutant emissions and theingine Management systems for SI and CI engines. Liquid and gased en. TRANSMISSION AND SUSPENSIONS SYSTEMS a system: Clutches - principle, types - single plate clutch, multiplate of eel. Gear boxes, types, constant mesh, synchromesh gear boxes, rariable transmission, propeller shaft, Hotch-Kiss drive, Torque tub wheels and tyres; Suspension system: Objects of suspension system osorber, independent suspension system BRAKING AND STEERING SYSTEMS ehicles, tyre grip, load transfer, braking distribution between axle Hydraulic, Air brakes, Disc & Drum brakes, Engine brakes antickermann principle, Davis steering gear, steering gear boxes, steer, camber toe-in, toe out etc., wheel alignment and balancing.	clutch, magnetic and epicyclic gear box e drive, universal jons, rigid axle suspersus, stopping distance lock braking system eering linkages, position circuit, Dash box - Air bags - Autoension System (ASS)	centrific, auto sint, diffusion sy ge, Type m. Type wer sto go oard ins motive sto else the control of the cont	o fugal of transiferent externing of trume of tr	o clutch missi tial, r, tors o brake steer o o clutch missi tial, r, tors o o clutch missi tial, r o o o o o o o o o o o o o	ms, NG, 9 es, on, ear ion 9 on, es -

TEXT BOOKS:	
1.	William. H. Crouse, Donald L Anglin, Automotive Mechanics, 10th Edition, McGraw-Hill, 2017
2.	Jack Erjavek, "Automotive Technology – A Systems Approach", Thomson Learning, 3rd Edition, 1999.
REFERENCES:	
1	Bosch Automotive Hand Book, 8th Edition, Bentley Publishers, 2011.
2	Kirpal Singh, Automobile Engineering, Vol.1 &2, Standard Publishers, 2012.
3	N. K. Giri, Automobile Mechanics, 5 th Edition, Khanna Publishers, 2014.

4	Kumar D.S., "Automobile Engineering", S.K.Kataria and Sons, 2nd Edition, 2017.
5	Robert Bosch GmbH, "Automotive Handbook", Robert Bosch, 2004.
E-REFI	ERENCES:
1.	http://www.engineeringstudymaterial.net/tag/automotive-engineering-books
2.	https://www.studynama.com//299-Automobile-engineering-lecture-notes-ebook-pdf
3.	https://onlinecourses.nptel.ac.in/noc21_de02/preview

	SE OUTCOMES: ompletion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Describe the fundamental concepts of automobile engineering	Understand
CO2	Analyze the various types of power train and fuel supply and management systems.	Analyze
CO3	Analyze the various types of automatic transmission and suspension systems for a vehicle.	Analyze
CO4	Discuss various types of braking and steering system.	Understand
CO5	Troubleshoot the electrical and electronics instrumentation system in the automobiles.	Understand

COURSE .	ARTI	CULA	ATIO	N MA	TRIX	<u> </u>									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	2		1				2	2		3	
CO2	3	3	3	3	2		1				2	2		3	
CO3	3	3	3	3	2		1				2	2		3	
CO4	3	3	3	3	2		1				2	2		3	
CO5	3	3	3	3	2		1				2	2		3	
Avg	3	3	3	3	2		1				2	2		3	
	•	1	3/2/1	– indic	eates s	trengtl	h of co	rrelatio	on (3 –	High, 2	- Mediu	m, 1- Lo	w)	•	

22M	EPE12	COMPOSITE MATERIALS		SEMESTER VI				
PRE	REQUI	SITES	PE	Credit		3		
1. Eı	ngineerin	g Physics	House /Wook	L	T	P	ТН	
2. Eı	ngineerin	g Chemistry	Hours/Week	3	0	0	3	
COU	JRSE O	BJECTIVES:						
1.	To provide knowledge on the advantages of use of different types of composites.							
2.	To introduce the advantages of the use of different types of composites, their manufacturing, properties and applications							

3. To make them aware the manufacturing and testing methods of composites

INTRODUCTION TO COMPOSITES

0 0 9

Fundamentals of composites - need for composites - Enhancement of properties - classification of composites - Matrix and their role- Metal matrix composites (MMC), Ceramic matrix composites (CMC), Polymer matrix composites (PMC)-Reinforcement - Particle reinforced composites-Fibre reinforced composites- Rule of mixtures- Applications of various types of composites.

UNIT II METAL MATRIX COMPOSITES

9 0

9

0 9

Metal Matrix, Reinforcements – particles – fibres, Effect of reinforcement - Volume fraction. Various types of Metal Matrix Composites, Characteristics of MMC, Alloy vs. MMC, Advantages and limitations of MMC – Processing of MMC – Powder metallurgy process - diffusion bonding – stir casting – squeeze casting

UNIT III | CERAMIC MATRIX COMPOSITES

0 0

0

9

Engineering ceramic materials – Properties – Advantages – Limitations – Monolithic ceramics - Need for CMCs – Ceramic matrix - Various types of Ceramic Matrix composites- oxide ceramics – Non oxide Ceramics – Aluminium oxide – Silicon nitride – Reinforcements – particles- fibres- whiskers. Sintering - Hot pressing – Cold Isostatic Pressing (CIP) – Hot Isostatic Pressing (HIP).

UNIT IV POLYMER MATRIX COMPOSITES

9 0

0 9

Polymer matrix resins – Thermosetting resins, thermoplastic resins – Reinforcement fibres – Rovings – Woven fabrics – non-woven random mats – Various types of fibres. Methods for producing PMC - Hand layup processes – Spray up processes – Compression moulding – Reinforced reaction injection moulding - Resin transfer moulding – Pultrusion – Filament winding – Injection moulding. Fibre Reinforced Plastics (FRP), Glass fibre Reinforced Plastics (GRP).

UNIT V

UNIT I

TESTING OF COMPOSITES AND INTRODUCTION OF NANO COMPOSITES

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Raw material testing, Property evaluation at laminate level, NDT techniques. Nano particle dispersion in polymer matrix, Polymer- nano clay composites and polymer-carbon nanotubes composites.

Total (45L) = 45Periods

Text Books: 1 R.M. Jones, Mechanics of Composites, 2nd ed., Taylor & Francis, 1999 Mathews F.L. and Rawlings R.D., "Composite materials: Engineering and Science", Chapman and Hall, London, 2. England, 2006 **References:** 1. Chawla K.K., "Compositematerials", Springer – Verlag, 2012... 2. Clyne T.W. and Withers P.J., "Introduction to Metal Matrix Composites", Cambridge University Press, 2003. 3. Strong A.B., "Fundamentals of Composite Manufacturing", SME, 2008... 4 P.M. Ajayan, L. Schadler, P.V. Braun "Nano Composite Science and Technology", Wiley VCH, 2003. C. Seferis, L. Nicolais, (Eds.) The Role of the Polymeric Matrix in the Processing and Structural Properties of Composite Materials, Plenum Press, New York 1983. E-References: NPTEL Courses. 1.

	RSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Identify the various matrices, reinforcements and their combinations in composite materials and select composite materials for suitable applications.	Remember
CO2	Develop suitable Metal Matrix Composites.	Apply
CO3	Identify perfect Ceramic Matrix Composites for high temperature applications.	Remember
CO4	Choose various combinations of fibres and resins and select an appropriate manufacturing technique for composite materials.	Understand
CO5	Predict the appropriate characterization testing methods for different classes of composites and manufacturing process, application polymer nano composites.	Apply

	1	1	1	I	1	I	I		I			1			ı
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	2	1		2		1			1		2	2	1
CO2	2	1	1	1			1				1		2	1	
CO3	2	1	1	1			1				1		2	1	
CO4	2	1	1	1		1	1	1			1		2	1	
CO5	2	2	1	1		1	1	1			1		2	2	1
Avg	2.0	1.4	1.2	1.0		1.3	1	1			1		2.0	1.4	1

	PE13	COMPUTER INTEGRATED MANUFACTURING		SE	MES	TER	VI
PRER	REQUI	ISITES CAT	ΓEGORY	PE	Cre	edit	3
1. Con	nputer A	Aided Design, Process planning	/557 1	L	Т	P	TH
2. Con	nputer A	Aided Manufacturing, integration software	ırs/Week	3	0	0	3
COUI	RSE O	BJECTIVES:		•	•		•
1.	To ga	ain knowledge on how computers are integrated at various levels of planning	ng and manut	facturir	ıg.		
2.	To ap	oply knowledge about Computer Aided Quality control and Process Planning	ng Control.				
3.		nderstand the flexible manufacturing system and to handle the product danfacturing.	ta and vario	us soft	ware ı	ised	for
4.	To de	esign flexible manufacturing cell after carrying out group technology.					
5.	To de	evelop and manage databases for CIM.					
UNI	ΙΤΙ	INTRODUCTION		9	0	0	9
manag UN	IT II	GROUP TECHNOLOGY AND COMPUTER AIDED PROCI	ESS	9	0	0	9
UN: History and M	y of gro ICLAS ng - rol	GROUP TECHNOLOGY AND COMPUTER AIDED PROCE PLANNING oup technology- role of G.T. in CAD/CAM integration - part families - class S and OPITZ coding systems-facility design using G.Tbenefits of G.T. le of process planning in CAD/CAM integration - approaches to compute generative approaches - CAPP and CMPP process planning systems.	ssification an	d codir	ng – During.	CLA Proc	SS ess
UN: History and M planni approa	y of gro ICLAS ng - rol	PLANNING oup technology- role of G.T. in CAD/CAM integration - part families - class S and OPITZ coding systems-facility design using G.Tbenefits of G.T. le of process planning in CAD/CAM integration - approaches to compute.	esification an - cellular ma r aided proce	d codir	ng – During.	CLA Proc	SS ess
UNI History and M planni approa UNI Shop automa	y of group of ICLAS on group of and and of IIII of the and of the	PLANNING oup technology- role of G.T. in CAD/CAM integration - part families - class S and OPITZ coding systems-facility design using G.Tbenefits of G.T. de of process planning in CAD/CAM integration - approaches to compute generative approaches - CAPP and CMPP process planning systems.	ssification an - cellular ma r aided proce	d codir anufacturess plan 9	ng – During. nning	OCLA Proc -vari 0	SS ess ant
UNI History and M planni approa UNI Shop autom system	y of group of ICLAS on group of and and of IIII of the and of the	PLANNING oup technology- role of G.T. in CAD/CAM integration - part families - class S and OPITZ coding systems-facility design using G.Tbenefits of G.T. le of process planning in CAD/CAM integration - approaches to compute generative approaches - CAPP and CMPP process planning systems. SHOP FLOOR CONTROL AND INTRODUCTION OF FMS ontrol-phases -factory data collection system -automatic identification ta collection system. FMS-components of FMS - types -FMS workstation	ssification an - cellular ma r aided proce methods- Ba n -material h	d codir anufacturess plan 9	ng – During. nning	OCLA Proc -vari 0	SS ess ant
UNI History and M planni approa UNI Shop autom system UNI CIM a Archit impler	y of ground y of ground y of ground and are at the ground	PLANNING oup technology- role of G.T. in CAD/CAM integration - part families - class and OPITZ coding systems-facility design using G.Tbenefits of G.T. le of process planning in CAD/CAM integration - approaches to compute generative approaches - CAPP and CMPP process planning systems. SHOP FLOOR CONTROL AND INTRODUCTION OF FMS ontrol-phases -factory data collection system -automatic identification ta collection system. FMS-components of FMS - types -FMS workstation below the computer control systems-application and benefits.	ssification an - cellular ma r aided proce methods- Ba n -material h	d codinunufactivess plan 9 ar codenandlin CIM manage	ng – During. nning o e tech g and Open ement	OCLA Proc -vari O nolog stora O Syst - C	sss ess ant 9 gy- age 9 em IM
UNI History and M planni approa UNI Shop autom system UNI CIM a Archit impler manag	y of ground y of ground y of ground and are at the ground	PLANNING oup technology- role of G.T. in CAD/CAM integration - part families - class S and OPITZ coding systems-facility design using G.Tbenefits of G.T. le of process planning in CAD/CAM integration - approaches to compute generative approaches - CAPP and CMPP process planning systems. SHOP FLOOR CONTROL AND INTRODUCTION OF FMS ontrol-phases -factory data collection system -automatic identification ta collection system. FMS-components of FMS - types -FMS workstation layout -computer control systems-application and benefits. CIM IMPLEMENTATION AND DATA COMMUNICATION mpany strategy - system modeling tools - IDEF models - activity cycle (CIMOSA) - manufacturing enterprise wheel - CIM architecture - Proposition of the process of the communication fundamentals - local area networks - topology - consoftware. Communication fundamentals - local area networks - topology - consoftware.	ssification an - cellular ma r aided proce methods- Ba n -material h	d codinunufactivess plan 9 ar codenandlin CIM manage	ng – During. nning o e tech g and Open ement	OCLA Proc -vari O nolog stora O Syst - C	sss ess ant 9 gy- age 9 em IM

TEX	T BOOKS:
1.	Mikell.P.Groover, "Automation, Production Systems and Computer Integrated Manufacturing", Pearson Education, 2008.
2.	Roger Hanman, "Computer Integrated Manufacturing", Addison –Wesley, 1997
REF	ERENCES:
1.	Ranky and Paul G., "Computer Integrated Manufacturing", Prentice Hall International 1986
2.	David D.Bedworth, Mark R.Hendersan and Phillip M.Wolfe, "Computer Integrated Design and Manufacturing", McGraw Hill Inc, 1998.
3.	Kant Vajpayee S, "Principles of Computer Integrated Manufacturing", Prentice Hall India,2003

4.	Mikell. P.Groover and Emory ZimmersJr, "CAD/CAM", Prentice Hall of India Pvt. Ltd, 1998
5.	Yoremkoren, "Computer Integrated Manufacturing system", McGraw-Hill, 1983.

	URSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Recognize the manufacturing activities interrelated with computers.	Understand
CO2	Understand the concept of group technology and the various approaches of computer aided process planning	Understand
CO3	Explain the phases of shop floor control activities.	Understand
CO4	Apply the system modeling tools in CIM.	Apply
CO5	Explain the applications of database and system protocol.	Understand

COURSE A	ARTIC	CULA	TION	MA	ΓRIX										
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1									1		1	1	1	2	3
CO2									1		1		1	2	2
CO3			1						1		1		1	2	2
CO4		1	1	1	3				3	2	1		1	1	3
CO5			1	3	2				2	2	1	1	1	2	2
Avg		1	1	2	2.5				1.6	2	1.0	1	1.0	1.8	2.4
	•	3/2	2/1 – iı	ndicate	es stre	ngth o	f corre	elation ((3 – Hi	gh, 2- M	ledium,	1- Low)	•	•	

	EPE14	DESIGN OF TRANSMISSION SYSTEM	1	SE	MES	TER	VI
PREF	REQUI	SITES	CATEGORY	PE	Cro	edit	3
1.Stud	ent shou	ald study kinematic of machinery	** /**/	L	Т	P	ТН
2. Stud	dent sho	uld study Design of machine elements.	Horus/Week	3	0	0	3
COU	RSE C	DBJECTIVES:			1		
1.	To ga	in knowledge on the principles and procedures for the design of mo	echanical power tran	smissi	on co	npon	ents.
2.	To ur	derstand the standard procedures available for design of transmissi	on elements.				
3.	To so	lve the problems for the real time applications of the systems					
4.	Desig	ning multi speed gear box for machine tool and automotive application	ations.				
5.	Desig	ning clutch and brake systems for engineering applications.					
UNI	ΙΤΙ	DESIGN OF FLEXIBLE ELEMENTS		9	0	0	9
		capacity for various applications - Design of Flat belts and pullerire ropes and pulleys - Design of Transmission chains and Sprocket		belts	and sl	neave	s –
UNI	T II	SPUR AND HELICAL GEARS		9	0	0	9
Factor	of safe	s - Design of straight tooth spur & helical gears based on speed rety, strength and wear considerations. Force analysis -Tooth stresmal and transverse, Equivalent number of teeth - forces.					
UNIT	ГШ	Module - normal and transverse, Equivalent number of teeth - forces.					
	ht harval	BEVEL AND WORM GEARS		9	0	0	9
of din	nensions	BEVEL AND WORM GEARS gear: Gear materials - Tooth terminology, tooth forces and stresses of straight bevel gears. Worm Gear: Gear materials - Tooth terminology, estimation of dimensions of worm gear pair.		r of tee	eth, es	timat	ion
of din	nensions es, effici	gear: Gear materials - Tooth terminology, tooth forces and stresses of straight bevel gears. Worm Gear: Gear materials - Tooth terminology.		r of tee	eth, es	timat	ion
of dim stresse UNIT Need - diagra	nensions es, effici F IV Design m, kine	gear: Gear materials - Tooth terminology, tooth forces and stresses of straight bevel gears. Worm Gear: Gear materials - Tooth terency, estimation of dimensions of worm gear pair.	ric progression - Star multi speed gear be	r of tee capaci 9 ndard sox for	eth, es ty, fo 0	timat rces a	ion and 9 Ray
of dim stresse UNIT Need - diagra	nensions es, effici Γ IV - Design am, kine ations, V	gear: Gear materials - Tooth terminology, tooth forces and stresses of straight bevel gears. Worm Gear: Gear materials - Tooth terminology, estimation of dimensions of worm gear pair. GEAR BOXES of sliding and constant mesh gear boxes: Speed selection - Geometrematic layout – Determination of number of teeth. Design of	ric progression - Star multi speed gear be	r of tee capaci 9 ndard sox for	eth, es ty, fo 0	timat rces a	ion and 9 Ray
of dim stresses UNIT Need - diagra applica UNIT Design Design	rensions es, effici F IV - Design m, kine eations, V T V n of sing n of brak	gear: Gear materials - Tooth terminology, tooth forces and stresses of straight bevel gears. Worm Gear: Gear materials - Tooth terminology, estimation of dimensions of worm gear pair. GEAR BOXES of sliding and constant mesh gear boxes: Speed selection - Geometermatic layout — Determination of number of teeth. Design of a variable speed gear box, Fluid Couplings, Torque Converters for an	ric progression - Star multi speed gear be atomotive application on clutches and Elect ling shoe brakes and	or of tee capaci 9 ndard sox for ns. 9 romag: Band l	eth, es ty, fo o tep ra mach o netic o orakes	timat rces a 0 tio - Hine t	ion and 9 Ray ool 9

TEXT	TEXT BOOKS:							
1.	Joseph Shigley, Charles Mischke, Richard Budynas and Keith Nisbett "Mechanical Engineering Design", 10th Edition, Tata McGraw-Hill, 2014.							
2.	Sundararajamoorthy T. V and Shanmugam. N, "Machine Design", 9th edition, Anuradha Publications, Chennai, 2003.							
REF	ERENCES:							
1	Bhandari V, "Design of Machine Elements", 15th Reprint, Tata McGraw-Hill Book Co, 2014.							
2	Prabhu. T.J., "Design of Transmission Elements", Mani Offset, Chennai, 2003. Md. Jalaludeen, Machine Design, Volume II, Design of Transmission Systems, 4th edition, Anuradha Publications, 2014.							
3	GitinMaitra,L. Prasad "Handbook of Mechanical Design", 2nd Edition, Tata McGraw-Hill,2001.							
4	C.S.Sharma, KamleshPurohit, "Design of Machine Elements", Prentice Hall of IndiaPvt. Ltd., 2003.							

5	Bernard Hamrock, Steven Schmid, Bo Jacobson, "Fundamentals of Machine Elements", 2 nd Edition, Tata McGraw Hill, 2006.							
E-RF	E-REFERENCES:							
1.	https://archive.nptel.ac.in/courses/112/101/112101304/							
2.	http://www.velhightech.com/Documents/ME8651 Design of Transmission Systems.pdf							
3.	https://civildatas.com/download/design-of-transmission-elements-by-t-j-prabhu							

	RSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Appreciate the functions of various transmission elements and their assemblies.	Understand
CO2	Design different transmission components according to the requirement as per standards using data books.	Analyze
CO3	Apply the appropriate calculation procedures for the various systems designing.	Apply
CO4	Design multi speed gear box for machine tool and automotive applications.	Analyze
CO5	Design clutch and brake systems for engineering applications.	Analyze

COURSE A	OURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	1	2		1	1				1		3	2	1
CO2	2	2	1	2		1	1				1		3	2	1
CO3	2	2	1	2		1	1				1		3	2	1
CO4	2	2	1	2		1	1				1		3	2	1
CO5	2	2	1	2		1	1				1		3	2	1
Avg	2	2	1	2		1	1				1		3	2	1
	•	•	3/2/1	– indi	cates s	treng	th of c	orrelat	ion (3	– High,	2- Medi	um, 1- L	ow)	•	•

22M	EPE15	ENERGY CONVERSION IN INDUSTRIES		SE	MES	ΓER	VI			
PRE	REQUI	SITES C.	ATEGORY	PE	Cre	dit	3			
1.The	ermal Eng	gineering		L	ТН					
2.The	ermal stor	rage system	lours/Week	3 0 0						
CO	URSE O	DBJECTIVES:	<u>"</u>		I	I				
1.	Analyzing the thermodynamic cycles used in power generation									
2.	Evaluat	ing the merits of direct thermal energy conversion systems compared to	conventional te	chniqu	ies					
3.	Analyz	ing the performance of fuel cells								
4.	Selecting the best energy storage mechanism for any given application									
5.	Develo	loping a mechanism for total energy recovery from a system adopting CHCP concept								
U	UNIT I ENERGY CONVERSION CYCLES 9 0 0									
	Coleman, ton cycles	Scuderi, Stirling, Ericsson, Lenoir, Atkinson, Stoddard and Kalina cycs.	cle – Compariso	n with	Rank	ine a	ınd			
Uì	NIT II	DIRECT CONVERSION OF THERMAL TO ELECTRICA	AL ENERGY	9	0	0	9			
		noelectric Converters – Thermoelectric refrigerator – Thermoelectric G converter – Nernst Effect Generator – Thermo Magnetic Converter	enerator – Ther	mionic	conv	erter	s –			
UN	UNIT III DIRECT CONVERSION OF CHEMICAL TO ELECTRICAL ENERGY					0	9			
		ics – working advantages and drawbacks – types – comparative analysiss – performance of fuel cell – applications	is – thermodynai	mics a	nd kir	etics	of			
UNIT IV ENERGY STORAGE SYSTEMS							9			
		bes – working – performance governing parameters – hydrogen energy ell Energy, Electrical Energy, Chemical Energy, Thermal Energy.	– solar cells. Ene	ergy st	orage	devi	ces			
U	NIT V	COMBINED HEAT, COOLING AND POWER PRODUCT	TION (CHCP)	9	0	0	9			
		- types - Configuration and thermodynamic performance of steam turbin- ystems – reciprocating IC engines cogeneration systems – concept of po		ystems	– gas	turb	ine			
			Total (45L)	= 45H	Perio	ds			

TEXT	BOOKS:
1.	Archie.W.Culp, Principles of Energy Conversion, 2 nd Edition, McGraw-Hill Inc., 1991, New York
2.	Kordesch Karl, and Günter R. Simader, Fuel Cell and Their Applications, Wiley 2006
REFE	RENCES:
1	Bent Sorensen, Renewable Energy Conversion, Transmission, and Storage Technology & Engineering, Academic Press, 2007.
2	Charles R. Russell, Elements of Energy Conversion, Permagon Press, 1967
3	Hart A.B. and Womack, G.J., Fuel Cells: Theory and Application, Prentice Hall, 1989
4	Kettari, M.A., Direct Energy Conversion, Addison-Wesley, 1997
5	Yogi Goswami, D. and Frank Kreith, Energy Conversion, Second Edition, Science, 2017.
E-REI	FERENCES:
1.	https://energyeducation.ca/encyclopedia/Energy_conversion_technology
2.	https://ioe.iitm.ac.in/program/energy-systems/
3.	https://www.industrytap.com/industrial-energy-conversion-transfer-efficiencies-trending/39616

	RSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Analyze the thermodynamic cycles used in power generation	Analyze
CO2	Evaluate the merits of direct thermal energy conversion systems compared to conventional techniques	Apply
CO3	Analyze the performance of fuel cells	Analyze
CO4	Select the best energy storage mechanism for any given application	Understand
CO5	Develop a mechanism for total energy recovery from a system adopting CHCP concept	Understand

COURSE A	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	1	1		1						2	1	1
CO2	3	2	2	1	1	1							2	1	1
CO3	3	3	3	1	1	1	1						2	1	1
CO4	2	2	3	1	1	1	1						2	1	1
CO5	2	2	2	2	1	1	1						2	1	1
Avg	2.6	2.2	2.4	1.2	1.0	1	1						2	1	1
	3/2/1 – indicates strength of correlation (3 – High, 2- Medium, 1- Low)														

CATEGORY Hours/Week arameters. — Mach waves and	PE L 3	0 Cro	P 0	3 TH 3		
arameters. — Mach waves and	3	0	0			
arameters. — Mach waves and	9			3		
arameters. – Mach waves and		0	0			
arameters. – Mach waves and		0	0			
– Mach waves and		0	0			
– Mach waves and		0	0			
– Mach waves and		0	0			
– Mach waves and		0	0			
		0	0			
			v	9		
riable area ducts	Mach	cone	– Eff	ect		
	9	0	0	9		
ucts: Flow through c ies – Use of tables a						
	9	0	0	9		
que shocks – Prand	tl Mey	er rel	ation	s –		
UNIT IV JET PROPULSION 9 0						
				sis		
	9	0	0	9		
			study	<i>J</i> –		
(que shocks – Prand	que shocks – Prandtl Mey 9 cy – Operation principle – op engines – Aircraft com	que shocks – Prandtl Meyer rel 9 0 cy – Operation principle – cycle op engines – Aircraft combustor 9 0	que shocks – Prandtl Meyer relations 9 0 0 cy – Operation principle – cycle analy op engines – Aircraft combustors		

TEXT BOOKS:								
1.	John D. Anderson Jr. – 'Modern Compressible Flow with historical perspective' – McGraw Hill Publishing company – International Edition – 1990 – 2nd Edition							
2.	Yahya S. M. – 'Compressible Flow' – Tata McGraw Hill India – 2009							
REFE	REFERENCES:							
1	Balachandran P 'Fundamentals of Compressible Fluid Dynamics' - PHI Learning India Private Ltd 2009							
2	Cohen H., Rogers G. E. and Saravanamuttoo – 'Gas Turbine Theory' – Longman – 1980							
3	Sutton G. P 'Rocket Propulsion Elements' - John Wiley, New York - 1986							
4	Shapiro A. H. – 'Dynamics and Thermodynamics of Compressible Fluid Flow – Vol.I' – John Wiley, New York – 1953							
5	Radhakrishnan E. – 'Gas Dynamics' – Prentice-Hall of India Pvt. Ltd – 2004							

E-RE	EFERENCES:
1.	https://nptel.ac.in/courses

	RSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Describe the compressible fluid flow and isentropic flow through various ducts.	Understand
CO2	Calculate the flow properties of isentropic flow using gas tables and charts.	Analyze
CO3	Differentiate normal and oblique shocks and determine their performance parameters.	Understand
CO4	Explain the theory of jet propulsion and calculate the operating parameters of various jet engines.	Understand
CO5	Illustrate the theory of rocket engines and determine their performance indicators.	Understand

COURSE ARTICULATION MATRIX															
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1			1	1		1	1			1					
CO2	1	1			1			1					1	1	1
CO3															
CO4			1	1											
CO5			1	1		1	1					1			
Avg	1	1	1	1	1	1	1	1		1		1	1	1	1
	•		3/2/1	– indi	cates s	treng	th of c	orrelat	ion (3	– High,	2- Medi	um, 1- L	ow)		

22M	EPE17	RENEWABLE ENERGY SYSTEM		SEMESTER V						
PRE	REQUIS	ITES	CATEGORY	PE	Cre	dit	3			
Basic	idea abou	t solar radiation and other renewable energy that exists.	Hours/Week	L	T	P	TH			
Unde	3	0	0	3						
Cour	Course Objectives:									
1.	To recognize the consciousness of energy conservation in scholars									
2.	To identi	fy the employ of renewable energy sources for electrical power ge	eneration							
3.	To collec	et different energy storage methods								
4.	To detec	t about environmental effects of energy conversion								
Ul	NIT I	SOLAR ENERGY		9	0	0	9			
Then	mal Applic	ermal collectors and storage: Thermal energy, Chemical Energy eations-Solar thermal power plant-Solar Photo voltaic Conversion neating and cooling, Solar distillation, Solar pumping, Solar furnate WIND ENERGY	n-Solar cell-PV appl							
		ind Energy Conversion-Site Selection Considerations-Wind Ener of WECS-Wind Energy Collectors Interconnected System Enviror		em-Ac	lvanta	ges a	ınd			
Ul	III TIV	BIO ENERGY	9	0	0	9				
plant gener	s-Bio gas ration of ga	ersion Technologies- Direct combustion – Thermo-chemical – B from plant wastes-Site selection Problems related to Bio gas plants - Alternative liquid fuels - Advantages and Disadvantages of Bio	ants- factors affectir	ıg bio-	gener	ation rgy.				
Ul	NIT IV	ENERGY FROM THE OCEANS		9	0	0	9			
Com	ponents of	Electric Conversion - Open and Closed cycle; Energy from T Tidal power plants - operation methods of utilization of tidal power Conversion Devices - Hybrid System.								
U	UNIT V GEOTHERMAL ENERGY AND FUEL CELLS									
thern Appl	UNIT V GEOTHERMAL ENERGY AND FUEL CELLS Geothermal sources – hydrothermal geothermal resources, geopressurised resources, hot dry rock resources of Petro thermal systems, Magma resources – Comparison of flashed steam and total flow concept - Advantages and Disadvantages-Applications of Geothermal Energy; Design and principle operation of a Fuel cells, classification of fuel cells, types of fuel cells, Advantages, disadvantages and applications of fuel cells.									

Text	Text Books:						
1.	G.D. Rai, "Non-Conventional Energy Sources", Khanna publishers, 2017						
2.	Suhas P. Sukhatme, "Solar Energy", Tata McGraw Hill Publishing Company Ltd., 2007.						
3.	Sunil S. Rao, B. B. Parulekar, "Energy Technology (Non-Conventional, Renewable And Conventional)", Khanna publishers 2002.						
Ref	References:						
1	Twidell, J.W. & Weir, A., "Renewable Energy Resources", EFN Spon Ltd., UK, 2005.						
2	Tiwari, G.N., "Solar Energy -Fundamentals Design, Modelling and applications", Alpha Science Intl Ltd, 2015.						
3	Khan, B.H., "Non-Conventional Energy Resources", The McGraw Hill Companies, 2009.						
4	Godfrey Boyle, "Renewable Energy", Power for a Sustainable future, Oxford University Press,1996.						
5	Johnson Gavy L, "Wind Energy Systems", Prentice Hall, 1985.						

Total (45L) = 45 Periods

E-References:						
1.	https://www.sciencedirect.com/book/9780128200049/renewable-energy-systems					
2.	https://en.wikipedia.org/wiki/Renewable_energy					
3.	Ellabban, Omar; Abu-Rub, Haitham; Blaabjerg, Frede (2014). "Renewable energy resources: Current status, future prospects and their enabling technology". Renewable and Sustainable Energy Reviews. 39: 748–764 [749]					

	URSE OUTCOMES: n completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Impart knowledge about solar energy harvesting techniques and its storage system	Understand
CO2	Enhance insight into different wind energy methods to generate electricity.	Understand
CO3	Enrich the scholars to inculcate paramount energy conversion technologies and problems related to bio gas plants	Understand
CO4	Reveals the notion of obtaining abundant energy from the oceans	Understand
CO5	Impart knowledge about geothermal energy and fuel cells	Understand

	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	3	2	1		2	2	3	1	1	2	2	1	3
CO2	1	2	3	2	1		2	2	3	1	1	2	2	1	3
CO3		2	3	2	1		2	2	3	1	1	2	2	1	3
CO4	1	2	3	2			2	2	3	1	1	2	2	1	3
CO5	1	2	3	2	1		2	2	3	1	1	2	2	1	3
Avg	1	2.0	3.0	2.0	1		2.0	2.0	3.0	1.0	1.0	2.0	2.0	1.0	3.0
	3/2/1 – indicates strength of correlation (3 – High, 2- Medium, 1- Low)														

PROFESSIONAL ELECTIVES - II

DDE	22MEPE21 ADVANCED STRENGTH OF MATERIALS									
LVC	REQUI	SITES	CATEGORY	PE	Cre	edit	3			
_			** ***	L	Т	P	TH			
Eng	Engineering Mechanics and Strength of Materials Hours/Week									
COU	JRSE O	BJECTIVES:		•	•	•	•			
1.	To prov	wide basic knowledge in mechanics of materials to solve real engineering problems and design engineering								
2.	To dete	termine the mechanical behavior of the body by determining the stresses, strains produced by the application d.								
3.	To lear	n about radial and tangential stresses in thick cylinders and rotating	disks							
4.	To stud	ly about torsion of non-circular sections								
5.	To dete	ermine the stresses in circular and rectangular plates due to various t	ypes of loading and	end co	onditio	ons				
UN	I TI	ELASTICITY		9	0	0	9			
UNI	TII	center for various sections – shear flow. UNIT II UNSYMMETRICAL BENDING					ear			
	mferentia		f a section. Curved	9 flexur	0	0	9			
	entrated l	UNSYMMETRICAL BENDING deflection in beams subjected to unsymmetrical loading – Kern of all and radial stresses – deflection and radial curved beam with repoad and uniform load – chain link and crane hooks.		flexur	al me	embei	9			
conce	entrated l T III	deflection in beams subjected to unsymmetrical loading – Kern o al and radial stresses – deflection and radial curved beam with re-		flexur	al me	embei	9			
UNI Thick tange	T III	deflection in beams subjected to unsymmetrical loading – Kern of and radial stresses – deflection and radial curved beam with reoad and uniform load – chain link and crane hooks. THICK CYLINDERS AND ROTATING DISKS cylinder subjected to internal and external pressures – Shrink fit join sses in solid disc and ring of uniform thickness and varying thickness	strained ends – close ts – Stresses due to	flexursed ring 9 rotation	ral meg subj	ember jected 0	9 rs - 1 to 9 and			
UNI Thick tange	T III k-walled	deflection in beams subjected to unsymmetrical loading – Kern of and radial stresses – deflection and radial curved beam with reoad and uniform load – chain link and crane hooks. THICK CYLINDERS AND ROTATING DISKS cylinder subjected to internal and external pressures – Shrink fit join sses in solid disc and ring of uniform thickness and varying thickness	strained ends – close ts – Stresses due to	flexursed ring 9 rotation	ral meg subj	ember jected 0	9 rs - 1 to 9 and			
UNI Thick tange and cunii Torsi	K-walled ential streetylinders. T IV	deflection in beams subjected to unsymmetrical loading – Kern of and radial stresses – deflection and radial curved beam with reoad and uniform load – chain link and crane hooks. THICK CYLINDERS AND ROTATING DISKS cylinder subjected to internal and external pressures – Shrink fit join asses in solid disc and ring of uniform thickness and varying thickness.	ts – Stresses due to ess – allowable spe	9 rotation ed. – R	al meg subj	ember jected 0 adial ang sha	9 and afts			
UNI Thick tange and c UNI Torsi	k-walled ential streetylinders. T IV ion of receives in hol	deflection in beams subjected to unsymmetrical loading – Kern of and radial stresses – deflection and radial curved beam with repoal and uniform load – chain link and crane hooks. THICK CYLINDERS AND ROTATING DISKS cylinder subjected to internal and external pressures – Shrink fit join asses in solid disc and ring of uniform thickness and varying thickness in solid disc and ring of uniform thickness and varying t	ts – Stresses due to ess – allowable spe	9 rotation ed. – R	al meg subj	ember jected 0 adial ang sha	9 9 and afts 9			
Thick tange and countries tress UNI	k-walled ential streetylinders. T IV ion of receives in hole T V sees in cir	deflection in beams subjected to unsymmetrical loading – Kern of and radial stresses – deflection and radial curved beam with repoal and uniform load – chain link and crane hooks. THICK CYLINDERS AND ROTATING DISKS cylinder subjected to internal and external pressures – Shrink fit join sses in solid disc and ring of uniform thickness and varying thickness in solid disc and ring of uniform thickness and varying thickness tangular cross section – St. Vennant Theory – elastic membrane analogous thin walled tubes.	ts – Stresses due to ess – allowable spe gy – Prandtl's stress conditions – Buckl	flexursed ring 9 rotation ed. – R function 9 function 9	on – T on – T on – T on – T	o adial ang sha o Torsio o	9 grand afts 9 nnal 9 ory			

Text I	Text Books:							
1.	Arthur P.Boresi and Richard J.Schmidt, "Advanced Mechanics of Materials", 6th Edition, John Wiley &Sons-Inc., 2009.							
2.	Arthur P.Boresi and Omar M.Siseborttom- "Advanced Mechanics of Materials", John Wiley International Education, 1985.							
Refer	References:							
1	Robert D.Cook and Wareen.C.Yound, "Advanced Mechanics of Materials", 2nd Edition, Macmilon Publishers Company, 1985							
2	Srinath.L.S, "Advanced Mechanics of Solids", Tata McGraw Hill PublishingCompany Limited, 2003							
3	KrishnaRaju- N and Gururaja-D.R., "Advanced Mechanics of Solids and Structures", Narosa Publishing House, 1997.							

4	U.C.Jindal, "Advanced Topics of Strength of materials", Galgotia Publications, 1st Edition, 1997
E-Refe	erences:
1.	NPTEL Videos/Tutorials

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:					
CO1	Familiarize the concepts of stress and strain at a point as well as the stress-strain relationships for homogenous, isotropic materials.	Understand				
CO2	Evaluate the stresses and strains in axially-loaded members, circular torsion members, and members subject to flexural loadings.	Analyze				
CO3	Evaluate the stresses and strains associated with thick-wall spherical and cylindrical pressure vessels.	Analyze				
CO4	Evaluate the stresses in non-circular sections.	Analyze				
CO5	Evaluate the stresses in circular and rectangular plates due to various types of loading and end conditions.	Analyze				

COURSE ARTICULATION MATRIX COs/POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 PSO₁ PSO₂ PSO3 **CO1** CO₂ **CO3 CO4 CO5** Avg 2.2 2.4 2.2 1.6 0.8 0.2 0.8 0.2 2.8 2.2 1.0 3/2/1 – indicates strength of correlation (3 – High, 2- Medium, 1- Low)

22M	EPE22	ENERGY EFFICIENT BUILDINGS DESIG	GN	SE	MES	TER	l VI
PRE	REQUIS	SITES	CATEGORY	PE	Cro	edit	3
1.Bas	sic knowle	edge about energy efficient technologies		L	Т	P	TH
2.Co	2.Concepts of psychometry and renewable energy technologies Hours/Week						
cot	JRSE OI	BJECTIVES:					
1.	Explain	ing the future building aspects and need for comfort human living.					
2.	Designi	ing an energy efficient landscape system for pleasant living environ	ment.				
3.	Develop	ping novel solutions for storage integration in buildings and will evo	olve passive building	strate	gies.		
4.	Perform	ning building load estimates and applying them real time procedure.					
5.	Explain	ing the importance of renewable energy integration in buildings.					
Ul	NIT I	INTRODUCTION TO ENERGY EFFICIENT BUILDIN	G CONCEPTS	9	0	0	9
build		g design aspects – Effective use of resources and needs of modern sses - Energy conservation building codes. LANDSCAPE AND BUILDING ENVELOPES	living – Building as	sessm 9	ent ar	nd gre	een 9
Ener	rgy efficie	ent landscape design – Micro climates – various methods – Shacrials, Envelope heat loss and heat gain and its evaluation, paints, ins		-Build	ing er	ivelo	pe:
UN	III TIN	HEATING, VENTILATION AND AIR CONDITIONIN	NG	9	0	0	9
evap		ation, Passive cooling and heating: Thermal mass effects – Applicat poling, radiant cooling – Hybrid methods – energy conservation r					
Ul	VI TIV	HEAT TRANSMISSION IN BUILDINGS		9	0	0	9
trans estin carry	sfer due to nation of b ying out t	ficient: air cavity, internal and external surfaces, overall thermal o infiltration, internal heat transfer; solar temperature; decrement fabuilding loads: steady state method, network method, numerical methermal design of buildings and predicting performance. Thermal ethod for seasonal energy consumption.	actor; phase lag. Des hod, correlations; co	sign of mpute	day r pack	lighti tages	ng; for
IIN	Degree day method for seasonal energy consumption. UNIT V BUILDING COOLING AND RENEWABLE ENERGY IN BUILDINGS						

BUILDINGS

Passive cooling concepts, Application of wind, water and earth cooling; shading, paints and cavity walls for cooling; roof radiation traps, Earth air tunnel. Solar sorption cooling and solar vapour compression cooling for buildings – Solar water heating systems in buildings – Small wind turbines, standalone PV, Hybrid systems for residential buildings with economics.

Total (45L) = 45 Periods

TEXT BOOKS:							
1.	Krieder. J., and Rabi. A., Heating and cooling of buildings: design for efficiency, McGraw Hill, 2016.						
2.	Charles. J. Kibert, Sustainable Construction: Green Building Design and Deliver, John Wiley & Sons, 2016.						
REFEI	REFERENCES:						
1	Duffie, A and Beckmann, W. A., Solar Engineering of Thermal Processes, John Wiley, 1991.						
2	Sukhatme, S.P., Solar Energy, Tata McGraw Hill, 1984.						
3	Michael Bauer, Peter Mosle and Michael Schwarz, Green Building - Guidebook for Sustainable Architecture, 2009.						
4	Velraj.R, 'Sensible heat Storage for solar heating and cooling systems' in the book titled "Advances in Solar Heating and Cooling" – Pages 399 - 428 Elsevier Publication, 2016.						
E-REFERENCES:							

1.	https://nptel.ac.in/courses
2.	UrsalaEicker, "Solar Technologies for buildings", Wiley Publications, 2003.3 Guide book for national certification examination for energy managers and energy auditors (downloaded from www.energymanagertraining.com).

	RSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Apply the modern building aspects and the need of indoor air quality for comfort living.	Apply
CO2	Design an energy efficient landscape and evaluate the heat loss or gain through building components.	Analyze
CO3	Develop novel solutions for storage integration in buildings and evolve passive building strategies.	Understand
CO4	Estimate the actual and accurate thermal load for various types of buildings.	Analyze
CO5	Explain the importance of integrating various renewable energy resources in buildings.	Understand

COURSE A	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	1	1		2							2	1	1
CO2			3	2			1						1	1	
CO3			1	1			1								
CO4	1	1	1	1			1	1					1	1	1
CO5						1	1		1	1					
Avg	1.5	1	1.5	1.2		1.5	1	1	1	1			1.3	1	1
			3/2/1 -	– indic	ates s	trengt	h of c	orrelat	ion (3	– High,	2- Medi	ium, 1- I	Low)		

	ENGINEERING SYSTEM ANALYSIS AND DI	ESIGN	SE	MES	TER	VI						
PREREQU	SITES	CATEGORY	PE	Cr	edit	3						
1.Engineering	Mechanics & Product design development		L	Т	P	ТН						
2.Design of N	Iachine Element	Hours/Week	3	0	0	3						
COURSE O	BJECTIVES:		<u>l</u>	1								
1. Analy	te the asymptotic performance of Manual and automated systems.											
2. Ability	to understand the principles of systems documentation.											
3. Demo	onstrate a familiarity with Systems flowcharts and structured charts.											
4. Apply	important Planning considerations for advance development.											
5. Under	stand the basic concepts and implement the Object-orientedanalysis a	and design.										
UNIT I	SYSTEM DEFINITION AND CONCEPTS		9	0	0	9						
to systems Implementati	SYSTEMS ANALYST If of systems analyst, Qualifications and responsibilities, Systems Analystellopment life cycle (SDLC), Various phases of development, Maintenance Systems documentation considerations: Principles and their importance, Enforcing documentation discipline in an organization.	ent: Analysis, Des s of systems document	sign,	Devel	opme	nt,						
UNIT III	SYSTEMS DESIGN AND PROCESS MODELING	guinzution.	9	0	0	9						
Common dia	physical design, Design representation, Systems flowcharts and stramming conventions and guidelines using DFD and ERD diagrams internals: Program and Process design, Designing Distributed Systems	s. Data Modeling a				20						
Designing the		ms	•									
UNIT IV	SYSTEM IMPLEMENTATION AND MAINTENANCE		9	0	0							
UNIT IV Planning con performance,		E eptance Criteria, Sy ntenance activities	9 rstem e	0 valua	tion a	sis, 9 and						
UNIT IV Planning con performance,	SYSTEM IMPLEMENTATION AND MAINTENANCE siderations, Conversion methods, producers and controls, System according and validation, Systems quality Control and assurance, Maintenance, Mainten	E eptance Criteria, Sy ntenance activities	9 rstem e	0 valua	tion a	sis, 9 and						
UNIT IV Planning conperformance, computer sys UNIT V Introduction of	SYSTEM IMPLEMENTATION AND MAINTENANCE siderations, Conversion methods, producers and controls, System according and validation, Systems quality Control and assurance, Mainem and control measures, Disaster recovery and contingency planning	E eptance Criteria, Syntenance activities ng	9 vstem e and iss	0 valua ues. T	tion a Threat	9 and to 9						

TEXT	BOOKS:
1.	Analysis and design of information systems – James A.Senn, McGraw-Hill Education, 2008
2.	System analysis and design –Perry Edwards, McGraw-Hill Companies, 1993
REFE	CRENCES:
1	System Analysis and Design Methods, Whitten, Bentaly and Barlow, Galgotia Publication
2	System Analysis and Design Elias M. Award, Galgotia Publication
3	Modern System Analysis and Design, Jeffrey A. Hofer Joey F. George Joseph S. Valacich Addison Weseley.
E-RE	FERENCES:
1.	https://archive.nptel.ac.in/courses/106/108/106108103/
2.	https://www.tutorialspoint.com/system_analysis_and_design/system_analysis_and_design_overview.htm
3.	https://nios.ac.in/media/documents/vocational/cca/cca1.pdf

	Upon completion of this course, the students will be able to:								
CO1	Understand the requirements of a system.								
CO2	Design system components and environments.	Analyze							
СОЗ	Build general and detailed models that assist programmers in implementing a system.	Apply							
CO4	Design a database for storing data and a user interface for data input and output, as well as controls to protect the system and its data.	Apply							
CO5	Understand the concepts of object modeling and dynamics modeling.	Understand							

COURSE A	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	2	1	2								2	1	
CO2		1	3	2	1								2	3	
CO3	1	2	2	1	1								2	3	
CO4	1	2	3	2	1								1	3	
CO5		2	2	2										2	
Avg	1	1.8	2.4	1.6	1.2								1.7	2.4	
			3/2/1	– indi	cates s	strengt	th of co	rrelati	on (3 – 1	High, 2- 1	Medium,	1- Low)			

22M	EPE24	INDUSTRIAL ENGINEERING AND MANAGE	CMENT	SE	MES	ГER	VI						
PREI	REQUIS	ITES	CATEGORY	PE	Cre	dit	3						
1. Ba	sic know	ledge of mathematics, science, and engineering.		L	Т	P	ТН						
2. Ba	sic know	ledge about management principles.	Hours/Week	3	0	0	3						
COU	RSE OB	JECTIVES:			u.	•							
1.		ip them for applying knowledge of mathematics, science and engitivity of industries.	neering in the direc	ction to	impr	ove	the						
2.	To prov	o provide the knowledge on engineering economic analysis for effective utilization of available facilities.											
3.	To proplannin	vide the knowledge on supply chain management for efficient use g.	e of available resou	rces w	ith ag	greg	ate						
4.	To mak	e the students familiarize the concept of JIT and modern manufactu	ring principles.										
5.	To fam	iliarize the modern concepts and marketing in management for appl	ying them in profess	sional o	organi	zatio	n.						
UN	I TI	FORECASTING AND INVENTORY		9	0	0	9						
Facil	es of layo	FACILITIES PLANNING ning - An overview, Facilities planning and engineering economic outs - Computerized layout planning - Warehouse management, V Role of KAIZEN, TQM, QC and POKA YOKE in facilities planning	alue added manage										
UN	T III	AGGREGATE PLANNING AND SUPPLY CHAIN MA	NAGEMENT	9	0	0	9						
requi	irements	o aggregate planning - Development of master production scheplanning (MRP-I), Manufacturing resources planning (MRP-II), management (SCM) – Supply chain and "Keiretsu".											
UN	IT IV	JIT AND MODERN MANUFACTURING PRINCIPLE	S	9	0	0	9						
(SM) man	ED) - Co ufacturing	Elements of Just in Time (JIT), Pull versus Push method, Kanban s ntinuous improvement - Optimized production technology - Busing concepts – Implementation of Six Sigma concepts - Cellular manufag - Rapid manufacturing.	ess process reengin	eering	(BPR	(), Le	ean						
UN	IT V	MODERN MANAGEMENT CONCEPTS AND MARK	ETING	9	0	0	9						
Man	agement	ures, merits and demerits of: SWOT Analysis; Business Process (SCM) – Marketing: Concept; Functions; Importance; Segmentarise; Competitive Analysis and Advantage – E-marketing.											
			Total (4	45L) =	= 45 F	Perio	ds						

TEXT I	BOOKS:								
1.	Dilworth B. James, "Operations Management Design, Planning and control for Manufacturing and Services", McGraw Hill Inc., New York, 1996.								
2.	Samson Eilon, "Elements of Production Planning and Control", Universal Book Corpn.1984.								
REFER	REFERENCES:								
1	Vollman T.E, "Manufacturing Planning and Control systems", Galgotia Publications, 2002.								
2	Tomkins, J.A and White, J.A, "Facilities Planning", John Wiley and Sons, 1984.								
3	Elwood S. Buffa, and Rakesh K.Sarin, "Modern Production and Operations Management", 8th Edition. John Wiley and Sons, 2000.								
4	Saxena, P.K., Principles of Management: A Modern Approach, Global India Publications, 2009.								

5	M. Govindarajan, Marketing Management, Prentice Hall of India, New Delhi, 2010.										
E-REF	E-REFERENCES:										
1.	https://nptel.ac.in/courses/112107292										
2.	https://cscmp.org/										
3.	https://cdn.websiteeditor.net/25dd89c80efb48d88c2c233155dfc479/files/uploaded/Kotler_keller_marketing_m anagement_14th_edition.pdf										

	E OUTCOMES: ompletion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Apply the knowledge in mathematics, science, and engineering in the direction to improve the productivity of industries.	Apply
CO2	Explain the concepts in engineering economic analysis for effective utilization and management of available facilities.	Understand
СОЗ	Explain the concepts of supply chain management for efficient use of available resources with aggregate planning.	Understand
CO4	Apply the concept of JIT and modern manufacturing principles in professional organization.	Apply
CO5	Identify modern concepts and marketing in management for applying them in professional organization.	Remember

COURSE	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	1	1									2	2	
CO2	1	2	3	1									1	2	1
CO3		2	2		3	1							1	2	3
CO4									3			1			2
CO5						2		2			1	1	2		
Avg	2	2	2	1	3	1.5		2	3		1	1	2	2	2
		3/	2/1 – i	ndicate	es strei	ngth of	corre	lation	(3 – Hi	igh, 2-	Mediun	1, 1- Lov	v)		

22MEPE25	INTERNAL COMBUSTION ENG	GINES	SE	MES	TER	VI
PREREQUIS	TES	CATEGORY	PE	Cre	edit	3
1. Engineering	Thermodynamics		L	Т	P	TH
2. Thermal En	gineering Hours/Week				0	3
COURSE OB.	JECTIVES:	1				
1. To acqu	ire knowledge of basic concepts of IC engine.					
2. To give	a comprehensive insight into the engine fuel supply system.					
3. To make	the students understand the combustion phenomenon of SI a	and CI engines.				
4. To study	engine management and exhaust emission control technique	es.				
5. To impa	rt knowledge on recent trends in IC engines.					
UNIT I	INTRODUCTION OF IC ENGINES		9	0	0	9
	Types of IC engines, Constructional details in IC engine, wo					
engines, Actu Octane and c UNIT II	nal Indicator diagram for four-stroke and two-stroke engines etane rating, Materials for engine components. FUEL SUPPLY SYSTEMS	, General fuel properties,	Ignitio 9	on pro	pertie 0	9
engines, Actu Octane and c UNIT II Fuel supply sy	nal Indicator diagram for four-stroke and two-stroke engines etane rating, Materials for engine components.	quirements - Simple carbi	Ignition 9 uretor,	on pro	pertie 0	9
engines, Actu Octane and c UNIT II Fuel supply sy	nal Indicator diagram for four-stroke and two-stroke engines etane rating, Materials for engine components. FUEL SUPPLY SYSTEMS stems in SI engine - Introduction - Carburetion - Mixture recommendation - Mixture recommendation - Mixture recommendation - Introduction - Carburetion - Mixture recommendation - Introduction -	quirements - Simple carbi	Ignition 9 uretor,	on pro	pertie 0	9
engines, Actu Octane and c UNIT II Fuel supply sy devices, High a UNIT III Combustion pl Factors affecting	ral Indicator diagram for four-stroke and two-stroke engines etane rating, Materials for engine components. FUEL SUPPLY SYSTEMS stems in SI engine - Introduction - Carburetion - Mixture realtitude fuel supply device - CI engine - Injection systems - New York - N	quirements - Simple carb Mechanical and Electronic bustion - Normal and ab	guretor, e. 9	on pro comp	o ensati	9 ion -
engines, Actu Octane and c UNIT II Fuel supply sy devices, High a UNIT III Combustion pl Factors affecting	ral Indicator diagram for four-stroke and two-stroke engines etane rating, Materials for engine components. FUEL SUPPLY SYSTEMS stems in SI engine - Introduction - Carburetion - Mixture realtitude fuel supply device - CI engine - Injection systems - N COMBUSTION IN IC ENGINE nenomenon in SI and CI engines - Ignition - Stages of coming knock - Combustion chambers - Fuel spray behavior - Spra	quirements - Simple carb Mechanical and Electronic bustion - Normal and ab	guretor, e. 9	on pro comp	o ensati	9 ion 9
engines, Actu Octane and c UNIT II Fuel supply sy devices, High a UNIT III Combustion pl Factors affectin - Air motion - UNIT IV Combined igni	ral Indicator diagram for four-stroke and two-stroke engines etane rating, Materials for engine components. FUEL SUPPLY SYSTEMS Stems in SI engine - Introduction - Carburetion - Mixture realtitude fuel supply device - CI engine - Injection systems - N COMBUSTION IN IC ENGINE Tenomenon in SI and CI engines - Ignition - Stages of coming knock - Combustion chambers - Fuel spray behavior - Sprafactors affecting combustion.	quirements - Simple carb Mechanical and Electronic bustion - Normal and above structure, Spray penetra	guretor, c. 9 normal tion, an	on pro	0 ensation of the position of	9 9 n - ion 9
engines, Actu Octane and c UNIT II Fuel supply sy devices, High a UNIT III Combustion pl Factors affectin - Air motion - UNIT IV Combined igni	ral Indicator diagram for four-stroke and two-stroke engines etane rating, Materials for engine components. FUEL SUPPLY SYSTEMS Stems in SI engine - Introduction - Carburetion - Mixture realtitude fuel supply device - CI engine - Injection systems - N COMBUSTION IN IC ENGINE Tenomenon in SI and CI engines - Ignition - Stages of coming knock - Combustion chambers - Fuel spray behavior - Sprafactors affecting combustion. ENGINE MANAGEMENT SYSTEM tion and fuel management systems, Digital control technique	quirements - Simple carb Mechanical and Electronic bustion - Normal and above structure, Spray penetra	guretor, c. 9 normal tion, an	on pro	0 ensation of the position of	9 9 n - ion 9

TEXT	BOOKS:
1.	V. Ganesan, "Internal Combustion Engines", V Edition, Tata McGraw Hill, 2017.
2.	John B. Heywood, "Internal Combustion Engines Fundamentals", McGraw-Hill, 1988.
REFE	RENCES:
1	Thipse.S.S, " internal Combustion Engines & quot; Jaico Publication House., 2010.
2	B.P. Pundir, "IC Engines Combustion & Emission", Narosa Publishing House, 2014.
3	K.K. Ramalingam, "Internal Combustion Engine Fundamentals", SciTech Publications, 2011
4	R.B. Mathur and R.P. Sharma, "Internal Combustion Engines", DhanpatRai & Sons, 2007.
5	Domkundwar.V.M, " A course in internal Combustion Engines & quot; Dhanpat Rai & Domkundwar.V.M, " A course in internal Combustion Engines & quot; Dhanpat Rai & Domkundwar.V.M, " A course in internal Combustion Engines & quot; Dhanpat Rai & Domkundwar.V.M, " Dhanpat Rai & Domkundwar.V.M,
E-REI	TERENCES:
1.	https://www.energy.gov/eere/vehicles/articles/internal-combustion-engine-basics
2.	https://www.energy.gov/sites/prod/files/2014/03/f8/deer11_taub.pdf
3.	https://dieselnet.com/tech/engine_emission-control.php

	E OUTCOMES: mpletion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Understand the concept, construction, and principle of operation of the engine and various engine components.	Understand
CO2	Explain the fuel supply systems of SI and CI engines and understand the various injection systems of CI engine.	Analyze
CO3	Analyze the combustion phenomenon in SI and CI engines.	Analyze
CO4	Understand the Engine management system and exhaust emission control techniques.	Understand
CO5	Understand recent trends in internal combustion engines.	Understand

COURSE A	ARTI	CULA	TION	MAT	TRIX										
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	1									3	2	1
CO2	3	2	2	1									3	2	1
CO3	3	1	2	2	2	2	3						2	3	1
CO4	2	1	2	1	2	2	3						2	3	1
CO5	3	1	1	1	2	2	2						2	3	1
Avg	2.8	1.4	1.8	1.2	2	2	2.6						2.4	2.6	1.0
	•	3/	2/1 - i	ndicate	es strei	ngth of	corre	lation	(3-H)	igh, 2- N	Iedium,	1- Low)			•

22MEPE26	22MEPE26 MACHINE DRAWING					
PREREQUISITES CATEGORY			PE Cree		dit	3
1.Engineering	gineering Drawing		L	T	P	TH
		Hours/Week		0	4	5
COLIDGE OD	TE COLVEC					

COURSE OBJECTIVES:

- 1. Students learn about the conventional representation of materials, machine elements, and sizes of drawing sheets.
- 2. Explain the concept of how to draw section of views, additional views for machine elements and parts like threaded joints, Keys, Cotters and Pin joints.
- 3. Explain the concept of how to draw Section of Views, additional views for machine elements and parts like Gears, Shaft couplings and Bearings
- 4. Students learn about the drawings of assembled views for the part drawings of the following using conventions like Engine parts and machine parts

UNIT I FUNDAMENTALS OF MACHINE DRAWING

3

12 15

Code of practice for Engineering Drawing, BIS specifications – Welding symbols, riveted joints, keys, fasteners – Reference to hand book for the selection of standard components like bolts, nuts, screws, keys etc. - Limits, Fits – Tolerancing of individual dimensions – Specification of Fits – Preparation of production drawings and reading of part and assembly drawings, basic principles of geometric dimensioning & tolerancing.

UNIT II BASIC MACHINE ELEMENTS

0 12 15

The required sectional view of the following machine elements are to be drawn as per the standards. Threaded joints, Riveted joints, Welded joints, Key, Cotter and Pin joints, Shaft coupling, Bearing, Pipe joints, Gears, Surface finish and its representation

UNIT III | ASSEMBLY DRAWING

9

0

45

36

The assembly drawing of the following machine tool parts are to be drawn from the given detailed drawing.

Couplings - Flange, Universal, Oldham's, Muff and gear couplings.

Joints - Knuckle, Gib & cotter, strap, sleeve & cotter joints.

Engine parts – Piston, connecting rod, cross-head (vertical and horizontal), stuffing box, multi-plate clutch.

Miscellaneous machine components – Screw jack, machine vice.

Total (15L + 60P) = 75 Periods

TEXT	BOOKS:
1.	P.S Gill, "Machine Drawing", S K Kataria and sons, 18th edition, 2020 reprint.
2.	N.D.Bhatt, "Machine Drawing". Charotar publications, 49th edition, 2014.
REFER	RENCES:
1	Ajeet Singh, "Machine Drawing (including Auto CAD)", Tata McGraw Hill, 2 nd edition, 2012.
2	G. Pohit, "Machine Drawing with Auto CAD", Pearson Education Asia, 2007.
3	Dhawan, R.K., A Text Book of Machine Drawing, S. Chand & Company, 1996.
4	Ostrowsky, O., Engineering Drawing with CAD Applications, ELBS, 1995.
5	Gopalakrishna K.R., "Machine Drawing", 22th Edition, Subhas Stores Books Corner, Bangalore, 2013.

E-REF	ERENCES:
1.	NPTEL Courses

	TE OUTCOMES: In pletion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Follow the drawing standards, fits and tolerances.	Understand
CO2	Re-create part drawings, sectional views and assembly drawings as per standards.	Analyze
СОЗ	Analyze complex design systems related to mechanical engineering.	Analyze
CO4	Improve skills to adopt modern methods in mechanical engineering as continuous improvement.	Understand
CO5	Understand the impact of engineering solutions in a global, economic, environment and societal context.	Understand

COURSE A	ARTI	CUL	ATIC	N M	ATRI	IX									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	2	1		1	1				1		2	2	1
CO2	2	1	2	1		1	1				1		2	2	1
CO3	2	2	2	2			2				1		2	2	1
CO4	1	1	2	2		1					1		2	2	1
CO5	1	1	1	2		2	2	1			0		1	1	1
Avg	1.6	1.2	1.8	1.6		1.2	1.5	1			1		1.8	1.8	1.0
		3	3/2/1 –	- indic	ates st	trengt	h of c	orrelat	ion (3	– High,	2- Med	ium, 1-	Low)		

22MI	EPE27	POWER PLANT ENGINEERING		SE	MES	TER	VI
PRE	REQUI	SITES	CATEGORY	PE	Cr	edit	3
1.Hav	ving sufficient knowledge on basics of power plant			L	Т	P	TH
2. Ba	2. Basic unit calculation for consumption of power Hours/Week					0	3
COL	IRSE O	BJECTIVES:			•		•
1.	supercl	tanding of thermal power plant operation, different types of high-prarged boilers, fluidized bed combustion systems, Design of chimnes tower operation.					
2.	Locatio	on of hydro power plant and its components to generate power.					
3.	Comple	ete knowledge about diesel and gas power plant.					
4.	Basic k	nowledge of nuclear reaction and types of nuclear power plant.					
5.	Basic k	nowledge of power plant economics and various tariff methods.					
U	NIT I	STEAM POWER PLANT		9	0	0	9
- Pulv	verizer - l mney de	m power plant – boilers - Modern high pressure and supercritical be Dust collector - Ash removal; Stokers - Different types - Pulverized sign - Selection of blowers, Cooling towers - Different types - idised Bed boilers	l fuel burning; Draug	ght - D	iffere	nt typ	pes
UN	II TII	HYDRO ELECTRIC POWER PLANT		9	0	0	9
		lel power plant- classification –working – components – layout Pumped Store Schemes.	of pumped storage	power	plant	- Pl	ant
UN	III TI	DIESEL AND GAS POWER PLANT		9	0	0	9
		sel power plant- Important components – performance analysis – L cycles – components – relative thermal efficiencies of different cyc		olant –	class	ificati	on
UN	IT IV	NUCLEAR, MHD POWER GENERATION		9	0	0	9
		eatment - Nuclear fission, chain reaction - Pressurized water reachereder reactors, Magneto Hydro Dynamic power- open cycle and			s, gas	coo!	led
UN	V TIV	ECONOMICS AND SAFETY		9	0	0	9
and v	ariable lo	d safety - Actual load curves - Fixed and operating costs - Tariff nead operations - Selection of generation type and general equipment onmental impacts - assessment for thermal power plant.					
			Total	(45L)	: 45	Perio	ods

TEX	TT BOOKS:
1.	S. Domkundwar, A.V. Domkundwar, S.C. Arora "A Course in Power Plant Engineering", Dhanpat Rai Publications. 2016.
2.	P.K. Nag, Power Plant Engineering, Tata McGraw Hill, Laxmi Publications Pvt. Ltd New Delhi, 5th Edition, 2014.
REF	TERENCES:
1	R.K. Rajput. A Text of Power Plant Engineering, Laxmi publications, New Delhi 5th Edition, 2016.
2	G.R. Nagpal, Power Plant Engineering, Khanna Publications 1998.
3	Bernhardt G. Askrotzki and William A. Vopat, "Power Station Engineering and Economy", Tata McGraw Hill Publishing Co. Ltd., 1972.
4	Frederick T. Mores, "Power Plant Engineering", Affiliated East-West Press Private Ltd., 1953.
5	Joel Weisman and Roy Eckart, "Modern Power Plant Engineering", Prentice Hall International Inc., 1985.
E-R	EFERENCES:

1.	https://en.wikipedia.org/wiki/Power_plant_engineering
2.	https://onlinecourses.nptel.ac.in/noc21_me86/preview

	RSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Identify elements and their functions of steam power plant.	Understand
CO2	Identify elements and their functions of hydroelectric power plant	Understand
CO3	Identify elements and their functions of diesel and gas power plant.	Understand
CO4	Identify elements and their functions of nuclear power plant.	Understand
CO5	Study the applications of power plants while extend their knowledge to power plant economics and environmental hazards and estimate the cost of electrical energy production.	Understand

COURSE	OURSE ARTICULATION MATRIX														
COs/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	3	2	1		1	1	2		2	2	2	1	2
CO2	1	2	3	2	1		1	1	2		2	2	2	1	2
CO3	1	2	3	2	1		1	1	2		2	2	2	1	2
CO4	1	2	3	2	1		1	1	2		2	2	2	1	2
CO5	2		1	2				2	2	1	1	1	2		
Avg	1.2	2	2.6	2.0	1		1	1.2	2.0	1	1.8	1.8	2.0	1	2
		3	3/2/1 – i	ndicate	es stren	gth of	correla	ation (3	- Hig	h, 2- Me	dium, 1-	Low)	•		

PROFESSIONAL ELECTIVES – III

22M	EPE31	FUELS AND COMBUSTION		SE	MES	TER	VI				
PRE	REQUI	SITES	CATEGORY	PE	Cre	edit	3				
1. B	asic chem	ical reactions between various components		L	Т	P	ТН				
2. Fu	ındamenta	al about various types of fuels and its nature	Hours/Week	3	0	0	3				
COU	JRSE O	BJECTIVES:				1	ı				
1.	To impart the acquaintance about characterize of the different types of fuels.										
2.	To enh	nance the understanding of Classification, Composition & Properties of various fuels									
3.	Unders	anding of thermodynamics and kinetics of combustion.									
4.	Unders	and and analyze the combustion mechanisms of various fuels.									
U	NIT I	CHARACTERIZATION		9	0	0	9				
Form	nula for C	ysis - Moisture Determination - Calorific Value - Gross & Net Ca V Estimation.	lorific Values - Cal	1 1							
Ul	NIT II	SOLID FUELS AND LIQUID FUELS		9	0	0	9				
- Bio Refir	mass - A ning - Pro	rpes - Coal Family - Properties - Calorific Value - ROM, DMMF, Egro Fuels — Manufactured Solid Fuels. Liquid Fuels-Types - Source perties of Liquid Fuels - Calorific Value, Specific Gravity, Flash & Fest - Tar Sand Oil - Liquefaction of Solid Fuels.	es - Petroleum Frac	ctions -	Class	ificat	ion -				
UN	III TII	GASEOUS FUELS		9	0	0	9				
Index	x - Natura	- Composition & Properties - Estimation of Calorific Value – Gas					ho				
Gas -		ll Gas - Dry & Wet Natural Gas- Stripped Natural Gas - Foul & S d natural gas - Compressed natural gas - Methane - Producer Gas -									
	NIT IV										
UN Princ	ciple of co	d natural gas - Compressed natural gas - Methane - Producer Gas - COMBUSTION mbustion - stoichiometry, heat of reaction and formation. Combustiulsating and explosive combustion. Chemical kinetics-NOx and soo	Gasifiers - Water G	as - To 9 ged con	wn G	as. 0 on, sl	y ow				
UN Princ comb Exce	ciple of co	d natural gas - Compressed natural gas - Methane - Producer Gas - COMBUSTION mbustion - stoichiometry, heat of reaction and formation. Combustiulsating and explosive combustion. Chemical kinetics-NOx and soo	Gasifiers - Water G	as - To 9 ged con	wn G	as. 0 on, sl	y ow				
Prince combined Exceller UI Coal Firing	ciple of copustion, poss air calon VIT V Burning g - Spread	d natural gas - Compressed natural gas - Methane - Producer Gas - COMBUSTION mbustion - stoichiometry, heat of reaction and formation. Combustiulsating and explosive combustion. Chemical kinetics-NOx and soo culation.	Gasifiers - Water G on process- submerg t kinetics. Fuel and t g – Fixed Bed & Rec Grate Stokers. Oil	ged comflue gas gycled Burners	onbustics composed of the second of the seco	on, sloositi Cycle	9 ow on, 9 one				
UN Prince comb Exce UI Coal Firin	ciple of copustion, poss air calon VIT V Burning g - Spread	d natural gas - Compressed natural gas - Methane - Producer Gas - COMBUSTION mbustion - stoichiometry, heat of reaction and formation. Combusticulating and explosive combustion. Chemical kinetics-NOx and soo culation. COMBUSTION EQUIPMENT'S Equipment's - Types - Pulverized Coal Firing - Fluidized Bed Firing der Stokers - Vibrating Grate Stokers - Sprinkler Stokers, Traveling	Gasifiers - Water G on process- submerg t kinetics. Fuel and t g – Fixed Bed & Rec Grate Stokers. Oil	ged comflue gas y ged comflue gas geveled l Burners Burner	onbustics composed by a second of the second	on, sloositi Cycle poriz	ow on,				

Tex	t Books:						
1.	Samir Sarkar, Fuels & Combustion, 2nd Edition, Orient Longman, 2009.						
2.	Bhatt, Vora Stoichiometry, 4th Edition, Tata McGraw Hill, 2004.						
Ref	References:						
1	Om Prakash Gupta, Elements of Fuels, Furnaces and Refractories, Khanna publishers, 1999.						
2	Blokh AG, Heat Transfer in Steam Boiler Furnace, Hemisphere Publishing Corpn, 1988.						
3	Sharma SP, Mohan Chander, Fuels & Combustion, Tata McGraw Hill, 1984.						
4	Shaha AK (2003), Combustion Engineering & Fuel Technology, Oxford and IBH Publications, New York.						
5	Kenneth K Kou (2002), Principles of Combustion, Wiley & Sons Publications, New York.						
E-R	eferences:						
1.	https://nptel.ac.in/courses/112106299						

- 2. http://www.sitams.org/assets/pages/hands/material/R18/Engineering%20Chemistry/Fuels%20and%20combustion.pdf
- 3. https://www.researchgate.net/publication/265602602_Fuels_and_Combustion

	URSE OUTCOMES: a completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Understand the various kinds of fuels characteristics.	Understand
CO2	Determine flash and fire points of various fuel blends.	Apply
CO3	Classification, composition, properties and estimation of calorific value of gaseous fuels	Understand
CO4	Understand the thermodynamics behind combustion, flame propagation and choice of combustion systems.	Understand
CO5	Vast knowledge on effective employment of combustion equipment's.	Understand

COURSE A	OURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	3	2	2	1	1		1	2	1	2	1	1	2	1
CO2	1	2	3	1	1	1		1	2	1	2	1	2	2	1
CO3	1	1	2	2	1	1		1	2	1	2	1	2	3	1
CO4	1	3	2	3	1	1		1	2	1	2	1	3	2	1
CO5	1	3	1	2	1	1		1	2	1	2	1	2	1	1
Avg	1.0	2.4	2.0	2.0	1.0	1.0		1.0	2.0	1.0	2.0	1.0	2.0	2.0	1.0
	•	•	3/2/	/1 – in	dicate	s stre	ngth o	f corre	elation	(3 – Hi	gh, 2- N	Iedium,	1- Low)	•	

22MEPE32	MAINTENANCE ENGINEERING		SE	MES	TER	VI
PREREQUI	SITES	CATEGORY	PE	Cre	edit	3
1. Manufactur	ing Technology		L	T	P	TH
2.Environmen	al Science and Engineering	Hours/Week	3	0	0	3
COURSE OI	BJECTIVES:				1	<u> </u>
1.	derstand the principles, functions and practices adapted in industry for ntenance activities.	the successful ma	nagem	ent		
2.	plain the different maintenance categories like preventive maintenance chine elements.	e, condition monito	oring a	nd rep	air	
3. To illu	strate the instruments used for condition monitoring in industry.					
4. To app	ply the repair methods in basic machine elements.					
5. To app	ply the repair methods in material handling equipment.					
UNIT I	INTRODUCTION		9	0	0	9
of maintenan Lubrication.	maintenance - types of maintenance – Breakdown, preventive and proceed planning – Importance and benefits of sound maintenance system Maintenance of Mechanical transmission systems and process plants–	s - Repair cycle -	Repai omics.	r Con	nplex	ity,
UNIT II	RELIABILITY AND AVAILABILITY		9	0	0	9
Productive M	categories – Comparative merits of each category – Preventive main faintenance (TPM). Reliability: Definition, concept of reliability-bas n. Availability and Maintainability concepts- Applications					
UNIT III	CONDITION MONITORING		9	0	0	9
	onitoring – Cost comparison with and without CM – On load testinor CM – Temperature sensitive tapes – Pistol thermometers – wear d					
UNIT IV	REPAIR METHODS FOR BASIC MACHINE ELEMEN	ITS	9	0	0	9
	ods for beds, slide ways, spindles, gears, lead screws and bearings - - Logical fault location methods - Sequential fault location, trouble s		– Fail	ures a	ınd th	neir
UNIT V	REPAIR METHODS FOR MATERIAL HANDLING EQ	QUIPMENT	9	0	0	9
	ods for Material handling equipment – Equipment records – Job Safety Codes and Standards - General Safety considerations in Mater			comp	uters	in
		Total	(45L)	= 45]	Perio	ods

TEXT	TEXT BOOKS:								
1.	Ricky smith and R.keith mobley, "Rules of Thumb for Maintenance and Reliability Engineers", Butterworth-Heinemann, 2011.								
2.	Lindley Higgins, Keith Moley, "Maintenance Engineering Handbook", McGraw-Hill Company, 2002.								
REFE	REFERENCES:								
1	Ahmed E.Haroun, Salih O.Duffuaa, "Handbook of Maintenance Management and Engineering", Springer, 2009.								
2	Mohamed Ben-Daya, Uday Kumar, "Introduction to Maintenance Engineering, Modelling, Optimization and Management", Wiley, 2016.								
3	B.S.Dhillon, "Engineering Systems Reliability, Safety and Maintenance: An integrated Approach", Taylor & Francis; CRC Press, 2017.								
4	David J.Smith, "Reliability, Maintenance and Risk", Butterworth- Heinemann, 2011.								
5	Paul Dempsey, "Troubleshooting and Repair of Diesel Engines, Fourth Edition", McGraw-Hill, 2007.								

E-REFERENCES:

1. NPTEL courses: http://nptel.iitm.ac.in/courses.php - web and video sources on Maintenance Engineering

	URSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Understand the principles, functions and practices adapted in industry for the successful management of maintenance activities.	Understand
CO2	Explain the different maintenance categories like preventive maintenance, condition monitoring and repair of machine elements.	Understand
CO3	Illustrate the instruments used for condition monitoring in industry.	Understand
CO4	Apply the repair methods in basic machine elements.	Understand
CO5	Apply the repair methods in material handling equipment.	Understand

COURSE	OURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	3		2	3	3	2		1	1	1	3	2	3	3
CO2	1	2		2	2	2	1		1		1	3	2	3	3
CO3		3	1	1	2	1			1			2	2	2	2
CO4	3	2	1	2	2								.3	2	1
CO5	3	2		2	2								3	2	1
Avg	2	2.4	1	1.8	2.2	2	1.5		1	1	1	2.6	2.4	2.4	2.0
		•	3/2/1	l – ind	icates	streng	th of c	orrelat	ion (3	– High,	2- Mediu	ım, 1- Lo	ow)	•	•

22MEP	E33	NON-TRADITIONAL MACHINING PROCE	ESSES	SE	MES	TER	VI		
PRERE	EQUI	SITES	CATEGORY	PE	Cre	edit	3		
1.Manuf	facturi	ng Technology		L	Т	P	TH		
2.Engine	eering	Chemistry	Hours/Week	3	0	0	3		
COUR	SE O	BJECTIVES:				1	ı		
1. T	Γo und	erstand the various Non-Traditional machining processes and its ap	plications						
2. T	To decide the appropriate process among various electro chemical processes								
3. T	Γο just	ify the appropriate Thermo - electric process based on the application	on and limitations						
4. T	Γo und	erstand the working principle and applications of Laser machining I	processes						
5. T	Γo und	erstand the working principle and applications of Micro-electro Me	chanical processes						
UNIT	I	INTRODUCTION		9	0	0	9		
- Limitat UNIT		ELECTRO - CHEMICAL PROCESSES		neters -	0	0	9		
UNIT Electro of Chemica	II chemical Grin	ELECTRO - CHEMICAL PROCESSES cal machining: Types - Electro Chemical Machining (ECM) - Electro (ECG) - Electro Chemical Honing (ECH) - Shaped Tube Electro Chemical - Applications - Limitations.		9 ling (E	CD) -	Elec	tro		
UNIT Electro of Chemica	II chemical Grings as para	cal machining: Types - Electro Chemical Machining (ECM) - Elending (ECG) - Electro Chemical Honing (ECH) - Shaped Tube Elec		9 ling (E	CD) -	Elec	tro		
UNIT Electro of Chemica - Process UNIT 1 Thermo - Electro	chemical Grings paran	cal machining: Types - Electro Chemical Machining (ECM) - Electro (ECG) - Electro Chemical Honing (ECH) - Shaped Tube Electro Electro - Applications – Limitations.	trolytic Machining	9 ling (E0-Opera	CD) - nting p	Electrinci 0 EDW	etro ple 9		
UNIT Electro of Chemica - Process UNIT 1 Thermo - Electro	chemical Grings parameters electrical Beau parameters in the control of the contr	cal machining: Types - Electro Chemical Machining (ECM) - Electro (ECG) - Electro Chemical Honing (ECH) - Shaped Tube Electrotes - Applications – Limitations. THERMO - ELECTRICAL PROCESSES ical machining: Types - Electrical Discharge Machining (EDM) - Electrom Machining (EBM) - Ion Beam Machining (IBM) - Plasma Arc Machining (EBM) - Ion Beam Machining (IBM) - Plasma Arc Machining (IBM) - Ion Beam Machining (IBM) - Ion Be	trolytic Machining	9 ling (E0-Opera	CD) - nting p	Electrinci 0 EDW	etro ple 9		
UNIT Electro of Chemica - Process UNIT la Thermo - Electro Process j UNIT la Laser ma	chemical Grin as parameter and the selectric on Beau parameter and the selectric on the sel	cal machining: Types - Electro Chemical Machining (ECM) - Electro (ECM) - Electro (ECM) - Shaped Tube Electro (ECM) - Electro (ECM) - Shaped Tube Electro (ECM) - Limitations. THERMO - ELECTRICAL PROCESSES ical machining: Types - Electrical Discharge Machining (EDM) - Electro (EDM) - Electro (EDM) - Ion Beam Machining (IBM) - Plasma Arc Material - Applications - Limitations.	ectrical Discharge Wachining (PAM) -	9 Sling (Ed-Operation of Control	CD) - ating p tting (ing pr drillin	Electronicion of the second of	rtro ple 9 (C) le -		
UNIT Electro of Chemica - Process UNIT 1 Thermo - Electro Process UNIT 1 Laser marking	chemical Grin is param in the electric on Bea param in the electric on the ele	cal machining: Types - Electro Chemical Machining (ECM) - Electro (ECG) - Electro Chemical Honing (ECH) - Shaped Tube Electro Electro - Applications – Limitations. THERMO - ELECTRICAL PROCESSES ical machining: Types - Electrical Discharge Machining (EDM) - Electro Machining (EBM) - Ion Beam Machining (IBM) - Plasma Arc Materials - Applications - Limitations. LASER MACHINING PROCESSES s processing: Laser types - Processes - Laser Beam Machining (LB)	ectrical Discharge Wachining (PAM) -	9 Sling (Ed-Operation of Control	CD) - ating p tting (ing pr drillin	Electronicion of the second of	graphic of the series of the s		
UNIT Electro of Chemica - Process UNIT I Thermo - Electro Process UNIT I Laser marking Limitatio UNIT Introduc - thin fil	chemical Grin is parameter on Beau parameter in IV attention to the control of t	cal machining: Types - Electro Chemical Machining (ECM) - Electro (ECG) - Electro Chemical Honing (ECH) - Shaped Tube Electro Electro - Applications – Limitations. THERMO - ELECTRICAL PROCESSES ical machining: Types - Electrical Discharge Machining (EDM) - Electro Machining (EBM) - Ion Beam Machining (IBM) - Plasma Arc Materials - Applications - Limitations. LASER MACHINING PROCESSES is processing: Laser types - Processes - Laser Beam Machining (LB) engraving - Laser Micro Machining (LMM)-Laser Engineered	ectrical Discharge Wachining (PAM) - M) - Laser cutting - Net Shaping (LEN	9 ling (Ed-Operation 9 Vire Cut Operation 9 Laser of S) - A 9 nd X-ra	CD) - ating p tting (ing pr drillin applica y lith	Electroninci 0 EDW incip 0 g- La ations 0 ograp	9 9 Ser s - 9		

TEX	TT BOOKS:						
1.	Pandey P.C. and Shan H.S. "Modern Machining processes" Tata McGraw-Hill, New Delhi, 2017.						
2.	Nano Tanigudi, "Nanotechnology", Oxford University Press, New York, 2003.						
3.	Vijay K Jain, "Advanced Machining Processes", Allied Publications Private Limited, 2002.						
REF	REFERENCES:						
1	Carl Sommer, "Non-traditional Machining Handbook", Advance Publishing Inc., 2000.						
2	Groover, M.P. "Fundamentals of Modern Manufacturing Processes - Materials, Processes and Systems", 3rd Edition, John Wiley and Sons Inc., 2007.						
3	Paul De Garmo, J.T.Black, and Ronald.A.Kohser, "Material and Processes in Manufacturing" Prentice Hall of India Pvt.Ltd. New Delhi, 8th Edition, 2001.						
4	Steen, W.M. and Watkins, K. "Laser Materials Processing", Springer London Ltd, 2003.						
5	Hassan Abdel and Gaward El-Hofy, "Advanced Machining Processes", McGraw Hill Publications, 2005.						

E-REFERENCES:

1. NPTEL courses: http://nptel.iitm.ac.in/courses.php - web and video sources on Non-Traditional Machining Processes.

COUR Upon con	Bloom Taxonomy Mapped					
CO1	Understand the various Non-Traditional machining processes and its applications					
CO2	Decide the appropriate process among various electro chemical processes					
СОЗ	Justify the appropriate Thermo electric process based on the application and limitations	Apply				
CO4	Understand the working principle and applications of Laser machining processes					
CO5	Understand the working principle and applications of Micro-electro Mechanical processes Under					

COURSE A	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2		1							1		2	2	1
CO2	3	2			1								2	2	1
CO3	3	2			1								2	2	1
CO4	2	1			1								2	2	1
CO5	2	1			1								2	2	1
Avg	2.6	1.6		0.2	1						1		2.0	2.0	1.0
	3/2/1 – indicates strength of correlation (3 – High, 2- Medium, 1- Low)														

22MEPE34	LUES	SEMESTER VI								
PREREQU	ISITES	CATEGORY	PE	Cro	edit	3				
1. Human R	ghts	** /**/ 1	L	Т	P	TH				
2. Product li	2. Product life Cycle Management Hours/Week									
COURSE O	BJECTIVES:		I		1					
1. Appl	1. Applying the core values toward the ethical behavior of an engineer.									
2. Appl	ying the ethical and moral principles in engineering experimentation.									
3. Appl	ying the ethical and moral principles in engineering for safety.									
4. Appl	ying standard codes of moral conduct toward the ethical behavior of	an engineer.								
	ying ethical and moral principles for engineers as managers, consultar tics concerning weapon development and multinational companies.	its, expert witness. F	Resolvi	ng glo	bal is	sues				
UNIT I	ENGINEERING ETHICS		9	0	0	9				
Kohlberg's to Ideals and V	ngineering Ethics' – Variety of moral issues – Types of inquiry – heory – Gilligan's theory – Consensus and Controversy – Professi rtues – Uses of Ethical Theories.		alism -			nal				
UNIT II	ENGINEERING AS SOCIAL EXPERIMENTATION		9	0	0	9				
	as Experimentation – Engineers as responsible Experimenters – Resea Balanced Outlook on Law – The Challenger Case Study.	earch Ethics Codes	of Ethi	cs – I	ndust	rial				
UNIT III	ENGINEERING FOR SAFETY		9	0	0	9				
	isk – Assessment of Safety and Risk – Risk Benefit Analysis – Reduc Risk - Chernobyl Case Studies and Bhopal.	ring Risk – The Gov	ernme	nt Re	gulato	r's				
UNIT IV	UNIT IV ENGINEER'S RESPONSIBILITIES AND RIGHTS					9				
	and Loyalty – Respect for Authority – Collective Bargaining – C Crime – Professional Rights – Employee Rights – Intellectual Prope					t –				
UNIT V	GLOBAL ISSUES		9	0	0	9				
Developmen	Corporations – Business Ethics - Environmental Ethics – Cont – Weapons Development – Engineers as Managers – Consulting Enter – Honesty – Moral Leadership – Sample Code of Conduct									
		Tota	l(45L)	= 45	Per	iods				

TEXT 1	TEXT BOOKS:						
1.	Mike Martin and Roland Schinzinger, "Ethics in Engineering", McGraw-Hill, New York 2017.						
2.	Govindarajan M, Natarajan S, Senthil Kumar V. S, "Engineering Ethics", Prentice Hall of India, New Delhi, 2004						
REFER	RENCES:						
1	Charles D Fleddermann, "Engineering Ethics", Prentice Hall, New Mexico, 1999.						
2	David Ermann and Michele S Shauf, "Computers, Ethics and Society", Oxford University Press, 2003						
3	Edmund G Seebauer and Robert L Barry, "Fundamentals of Ethics for Scientists and Engineers", Oxford University Press, 2001.						
4	John R Boatright, "Ethics and the Conduct of Business", Pearson Education, 2003.						
5	Prof. (Col) P S Bajaj and Dr. Raj Agrawal, "Business Ethics – An Indian Perspective", Biztantra, New Delhi, 2004.						

E-REFERENCES:							
1.	1. Value Education websites, http://uhv.ac.in, http://www.uptu.ac.in						
2.	IIT Delhi, Modern Technology – the Untold Story						
3.	Gandhi A., Right Here Right Now, Cyclewala Productions						

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:					
CO1	Understand the core values toward the ethical behavior of an engineer.	Understand				
CO2	Apply the ethical and moral principles in engineering experimentation.	Understand				
CO3	Expose the ethical and moral principles in engineering for safety.	Apply				
CO4	Apply standard codes of moral conduct toward the ethical behavior of an engineer	Apply				
CO5	Apply ethical and moral principles for engineers as managers, consultants, expert witness. Resolve global issues of ethics concerning weapon development and multinational companies.	Understand				

COURSE	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1							3	1	3			2	1		
CO2							2	2	3			2	1	2	
CO3							3	2	3			2	1	2	
CO4							3	3	2			2	1	2	
CO5							2	2	3			2	1		
Avg							2.6	2	2.8			2.0	1.0	2	
	3/2/1 – indicates strength of correlation (3 – High, 2- Medium, 1- Low)														

22MI	22MEPE35 RAPID PRODUCT DEVELOPMENT TECHNOLOGIES									
PRE	REQUI	SITES	CATEGORY	PE	Cre	edit	3			
l. Des	sign of M	achine elements and transmission systems, CAD software	Hours/Week	L	T	P	Tl			
2. Ma	3	0	0	3						
COU	RSE OB	JECTIVES:		ı		ı				
1.	To exp	ain the Importance of RPT in Manufacturing.								
2.	To fam	iliarize the students with recent developments in RPT.								
3.	To desc	cribe different methods for Post-processing of AM parts.								
4.	To list	out the challenges in RPT.								
5.	To exp	ain future Directions of AM.								
UN	IT I	INTRODUCTION		9	0	0	9			
UNIT II STEREO LITHOGRAPHY SYSTEMS Stereo lithography systems – Principle – process parameters – process details – machine details- Applications. Selective laser sintering – Principle – process parameters – process details – machine details- Applications-Direct Metal Laser Sintering (DMLS) system – Principle – process parameters – process details – machine details- Applications.						ive				
UNI	T III	FUSED DEPOSITION MODELING		9	0	0	9			
		tion Modelling – Principle – process parameters – process details – maacturing – Principle – process parameters – process details – machine			ns. La	mina	ted			
UNIT IV SOLID GROUND CURING AND CONCEPT MODELERS						0	9			
Solid Ground Curing – Principle – process parameters – process details – machine details- Applications. 3-Dimensional printers – Principle – process parameters – process details – machine details- Applications- and other concept modelers like thermo jet printers- Sander's model maker- JP system 5- Object Quadra system. Laser Engineering Net Shaping (LENS)-Ballistic Particle Manufacturing (BPM) -Principle.										
UN	UNIT V RAPID TOOLING AND SOFTWARES 9 0 0									
filled Rapi	l epoxy to d Tool- I	o rapid tooling – direct and indirect method- Indirect Rapid Tooling oling- Spray metal tooling- etc. Direct Rapid Tooling - Direct AIM- OMILS- ProMetal- Sand casting tooling- Laminate tooling- soft tooling.	Quick cast process	- Copp	er pol	yami	de-			

STL files- Magics- Mimics. Application of Rapid prototyping in medical field.

Total(45L) = 45 Periods

TEXT I	TEXT BOOKS:							
1.	Ian Gibson, David W Rosen, Brent Stucker., "Additive Manufacturing Technologies: Rapid Prototyping to Direct Digital Manufacturing", Springer, 2010.							
2.	Ali K. Kamrani, Emand Abouel Nasr, "Rapid Prototyping: Theory & Practice", Springer, 2006.							
REFER	REFERENCES:							
1	Pham D.T. & Dimov.S. S, "Rapid manufacturing", Springer Verlag, London, 2001.							
2	Paul F Jacobs, "Rapid Prototyping and manufacturing – Fundamentals of Stereo lithographic", Society of Manufacturing Engineering, Dearborn, USA 1992.							
3	Ali K. Kamrani, Emand Abouel Nasr, "Rapid Prototyping: Theory & Practice", Springer, 2006.							
4	Chua Chee Kai, Leong Kah Fai, "Rapid Prototyping: Principles & Applications", World Scientific, 2003.							
5	Terry wohlers, "Wohlers Report 2007", Wohlers Associates, USA 2007.							

	RSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Learn about the hurdles, basic-essentials and key-drivers of innovation in digital manufacturing and its application in Automobile, Aerospace, Bio-medical etc.	Understand
CO2	Recognize the operational features of Stereo Lithography Systems.	Understand
CO3	Explain the concept of Fusion Deposition Modelling.	Understand
CO4	Design for manufacture solid ground curing and concept modelers.	Apply
CO5	Acquire the knowledge of Software for RP and apply RPT in Tooling.	Understand

COURSE A	ARTI	CULA	ATIO	N MA	TRIX	K									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1		1	1	1	1	2					1	1	3	2	1
CO2		2	1	1	1				1		1	1	1	2	2
CO3		2	1	1	1				1		1	1	1	2	2
CO4		2	3	1	1				1		1	1	1	2	2
CO5		1	0	1	3				1		1		3	2	3
Avg		1.6	1.5	1.0	1.4	2			1		1.0	1	1.8	2.0	2.0
	3/2/1 – indicates strength of correlation (3 – High, 2- Medium, 1- Low)														

	EPE36	REFRIGERATION AND AIR CONDITION	ING	SE	MES'	TER	VI				
PREF	REQUI	SITES	CATEGORY	PE	Cre	edit	3				
1. Eng	ineering	Thermodynamics		L	Т	P	TE				
2.Fluid	d Mecha	nics and Machinery	Hours/Week	3	0	0	3				
COU	RSE O	BJECTIVES:		ı		1					
1.	To understand the basic concepts and processes in refrigeration.										
2.	To und	erstand the components of vapour compression refrigerating system	and its effects.								
3.	To und	erstand the other refrigeration systems and their applications.									
4.	To solv	re the problems using psychrometric charts and psychrometric proper	erties.								
5.	To calc	rulate the cooling load for designing air conditioning systems.									
UNI	I TI	INTRODUCTION		9	0	0	9				
UNI	ТП		/Р. М	9	0	0	9				
compr	geration ression c	VAPOUR COMPRESSION REFRIGERATION SYSTE system components: Type of Compressors, Condensers, Experies P-H and T-S diagrams – deviations from theoretical cycle – sevaporator pressure on C.O.P of the system - problems on vapour	M pansion devices, E sub cooling and sup	er heat	ing- e	ffects					
Refrig compr	eration ression c nser and	VAPOUR COMPRESSION REFRIGERATION SYSTE system components: Type of Compressors, Condensers, Expected: P-H and T-S diagrams – deviations from theoretical cycle – statement of the control	M pansion devices, E sub cooling and sup	Evapora er heat	ntors. ing- e	Vap	our				
Refrig compr conder UNIT	geration ression conser and	vapour compression refrigeration system system components: Type of Compressors, Condensers, Expecte: P-H and T-S diagrams – deviations from theoretical cycle – sevaporator pressure on C.O.P of the system - problems on vapour	M pansion devices, E sub cooling and sup compression refriger rigeration, Ejector 1	Evaporation s 9 refriger	ators. ing- e system o ration	Vaperffects	our s of				
Refrig compr conder UNIT	ression conser and FIII ing princhoelectri	vapour compression refrigeration system system components: Type of Compressors, Condensers, Experies P-H and T-S diagrams – deviations from theoretical cycle – stream evaporator pressure on C.O.P of the system - problems on vapour of the refrigeration system – Steam jet refrigered for vapour absorption refrigeration system – Steam jet refrigeration system – Ste	M pansion devices, E sub cooling and sup compression refriger rigeration, Ejector 1	Evaporation s 9 refriger	ators. ing- e system o ration	Vaperffects	our s of				
Refrig compr conder UNIT Worki Therm UNIT	geration ression conser and resolution principle resolution for the resolution resolutio	system components: Type of Compressors, Condensers, Experies P-H and T-S diagrams – deviations from theoretical cycle – sevaporator pressure on C.O.P of the system - problems on vapour of COTHER REFRIGERATION SYSTEMS ciple of vapour absorption refrigeration system – Steam jet refrigeration, Pulse tube refrigeration system, low temperature refrigeration processors.	mansion devices, Esub cooling and sup- compression refriger rigeration, Ejector refrigeration – Cascado	Evapora er heat ration s g refrigere syste g ulb ten	ators. ing- esystem oration ms. oration	Vapore frects in. 0 system	our s of 9 em-				
Refrig compr conder UNIT Worki Therm UNIT	geration ression conser and FIII ing principle principle results of respect to the principle respective results of respective respective results of respective results of respective respective results of respective respective results of respective results of respective respective respective results of respective respec	vapour compression refrigeration system system components: Type of Compressors, Condensers, Expercise P-H and T-S diagrams – deviations from theoretical cycle – servaporator pressure on C.O.P of the system - problems on vapour of the of vapour absorption refrigeration system – Steam jet refrigeration, Pulse tube refrigeration system, low temperature refrigeration air - Gibbs and Dalton's law. Psychrometric property- dry bulk ture, Specific humidity, relative humidity, Degree of saturation, Re	pansion devices, Esub cooling and sup- compression refriger rigeration, Ejector refrigeration – Cascado to temperature, wet be lative humidity, Ent	Evapora er heat ration s g refrigere syste g ulb ten	ators. ing- esystem oration ms. oration	Vapore frects in. 0 system	our s of 9 em-				

TEXT	BOOKS:							
1.	Arora, C.P., "Refrigeration and Air Conditioning", 3rd edition, McGraw Hill, New Delhi, 2017.							
2.	Arora S. C. and Domkundwar, "Refrigeration and Air-Conditioning", Dhanpat Rai and Co. (P) Ltd., 2010.							
REFE	REFERENCES:							
1	Roy J. Dossat, "Principles of Refrigeration", 4th Edition, Pearson Education Asia, 2009.							
2	Stoecker, W.F. and Jones J. W., "Refrigeration and Air Conditioning", McGraw Hill, New Delhi, 1986.							
3	Ballaney P. L, Refrigeration and Air-Conditioning, Khanna Publishers, New Delhi, 2014.							
4	Manohar Prasad, Refrigeration and Air-Conditioning, New Age International, 2011.							
5	ASHRAE Hand book, Fundamentals, 2010.							
E-RE	E-REFERENCES:							
1.	NPTEL courses: http://nptel.iitm.ac.in/courses.php - web and video sources on Refrigeration and Air Conditioning.							

	RSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Understand the basic concepts and processes in refrigeration.	Understand
CO2	Understand the components of vapour compression refrigerating system and its effects.	Understand
CO3	Understand the other refrigeration systems and their applications.	Understand
CO4	Solve the problems using psychrometric charts and psychrometric properties.	Analyze
CO5	Calculate the cooling load for designing air conditioning systems.	Analyze

COURSE	OURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3					1	2						2	2	1
CO2	2	3		2		1	1						2	2	1
CO3	2	3		1							1		2	2	1
CO4	2	1								1			2	2	1
CO5	2	2	1	2	1	2	1				1		2	2	1
Avg	2.2	2.2	1	1.6	1	1.3	1.3			1	1		2.0	2.0	1.0
	3/2/1 – indicates strength of correlation (3 – High, 2- Medium, 1- Low)														

22MI	EPE37	SOLAR ENERGY TECHNOLOGY		SEMESTER VI							
PRE	REQUI	SITES	CATEGORY	PE	Cro	edit	3				
			/	L	Т	P	TH				
			Hours/Week	3	0	0	3				
COU	JRSE O	BJECTIVES:				1	1				
1.	To exp	lain various solar collectors in solar power plants.									
2.	To des	cribe the variety of solar systems used in solar water heating system	ns.								
3.	To des	cribe the solar radiation and its measurements.									
4.	To ana	lyze solar space conditioning systems.									
5.	To des	Γο design PV systems for power plants.									
UN	IT I		9	0	0	9					
		cenario-classification, basic principles and features-comparison and ted tube – concentrated – pool and air collectors- function –suitabil		Solar	collec	tors-	flat				
UN	IT II	SOLAR WATER HEATING SYSTEMS		9	0	0	9				
		ctor storage system - thermosyphon system - open loop, drain of ar water heaters - solar heated pools - solar heated hot tubes and sol			eze sy	stem	ıs -				
UNI	T III	SOLAR RADIATION		9	0	0	9				
		ation – solar constant– solar charts – measurement of diffuse, global pyrgeometer, net pyradiometer-sunshine recorder.	and direct solar radi	ation: ¡	yrhel	iome	ter,				
UNI	T IV	SOLAR SPACE CONDITIONING SYSTEM		9	0	0	9				
		lar heating system with / without storage - heat storage configurations - solar refrigeration and air conditioning.	ns - heat delivery me	thods -	air-ty	pe so	olar				
UN	IT V	7 SOLAR PV CELL 9 0 0 9									
		cell – characteristics-cell arrays-power electric circuits for output ge regulators, construction concepts.	of solar panels –cl	hopper	s –inv	verter	·s –				
			Total	(45L)	= 45]	Perio	ods				

TEXT I	TEXT BOOKS:								
1.	Duffie, J.A., and Beckman, W.A. Solar Energy Thermal Process, John Wiley and Sons, NewYork, 2013.								
2.	Kosuke Kurokawa (Ed.), Energy from the Desert – Feasibility of very large-scale photovoltaic power generation systems, JamesandJames2003.								
REFER	ENCES:								
1	Sukhatme S.P., Solar Energy, TataMcGrawHills P Co., 3 rd Edition, 2008.								
2	C.J.Winter, R.L.Sizmann, L.L.VantHull, SolarPowerPlants, Springer Verlag Berlin and Heidel berg GmbH &Co., 2001.								

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:							
CO1	Explain various solar collectors in solar power plants.	Understand						
CO2	Describe the variety of solar systems used in solar water heating systems.	Understand						
CO3	Describe the solar radiation and its measurements.	Understand						
CO4	Analyze solar space conditioning systems.	Apply						
CO5	Design PV systems for power plants.	Apply						

COURSE	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1				2	1						2	1	2
CO2	3	2	1	2		1					1		2	2	2
CO3	3	2		2	3	2					1		2	2	1
CO4	3	3	1	2	2	2					1		3	2	2
CO5	3	2	3	2	3	2					1		2	3	2
Avg	3	2	1.6	2	2.6	1.8	1				1		2.2	2	1.8
	3/2/1 – indicates strength of correlation (3 – High, 2- Medium, 1- Low)														

<u>PROFESSIONAL ELECTIVES – IV</u>

22MI	EPE41	ADVANCED DECISION MODELING TECHN	IQUES	SE	MES	TER	VII
PRE	REQUI	SITES	CATEGORY	PE	Cre	edit	3
1.		ts are expected to have a background knowledge in probability.		L	Т	P	TH
2. Calcu 3.	ılus, and	ts are expected to have a basic understanding in the concepts of Algebra. cnowledge in python programming.	Hours/Week	3	0	0	3
COU	RSE OB	JECTIVES:		•			
1.		ip student, explain the fundamentals of machine learning, need forms, linear algebra concepts and application areas of deep learning to		d ense	mble	learn	ing
2.		ke the student explain the concepts of Convolutional Neural Ne entation of different CNN models using Python.	twork (CNN) archi	tecture	, trair	ing a	and
3.		ke the student explain the concepts of Recurrent Neural Netventation of different CNN models using Python.	vork (RNN) archit	ecture,	train	ing a	and
4.		iliarize the need, methods and concepts for ensemble learning and le learning approaches.	d apply with Pytho	n impl	ement	ation	of
5.		ntify alternate deep learning models for the listed use cases, identifices between standard deep learning models.	y a suitable algorith	hm by a	apprel	nend	the
UN	I TI	INTRODUCTION		9	0	0	9
		 rationale- concept of Eigenvalues and Eigenvectors- fundamenmentals – real world examples- implementation aspects of deep lea 		rning-	histor	y-neu	ıral
UN	IT II	CONVOLUTIONAL NEURAL NETWORKS		9	0	0	9
Conv	olutional	e process of convolution, convolutional layer, pooling layer, fully Neural Network (CNN) - architecture and training of different CoogLeNet - Implement the CNN models using Python.					
UNI	III TII	RECURRENT NEURAL NETWORKS		9	0	0	9
		ls - Evolution of LSTM from RNN -Working of LSTM concerning goupled gates, Gated Recurrent Network -Implement RNN using Py		TM suc	ch as p	eeph	ole
UNI	IT IV	ENSEMBLE LEARNING		9	0	0	9
		mble learning -methods involved in ensemble learning - bagging rithms to a real-world problem - Python implementation of ensemb			AdaB	oost a	and
UN	IT V	CASE STUDIES		9	0	0	9
class stand	ification/j lard deep	p learning models for the listed use cases like plant species identified prediction, loan eligibility prediction and resume parsing - identify a learning models and advanced deep learning models - selection l for the application under consideration.	a suitable algorithm	-differe	ences	betwo	een
			Total(45L) =	= 45]	Perio	ds

TEXT	TEXT BOOKS:								
1.	1. S. Sumathi, Suresh Rajappa, L. Ashok Kumar, And Surekha Paneerselvam, "Advanced Decision Sciences Based on Deep Learning and Ensemble Learning algorithms", Nova Science Publishers, Inc, 2021.								
2.	Singhal, Vanika, Shikha Singh, and Angshul Majumdar, "How to train your deep neural network with dictionary learning". ArXiv preprint arXiv: 1612.07454 (2016).								
REFER	RENCES:								
1	Srivastava, Pranjal. Essentials of deep learning: introduction to long short-term memory. (2017).								
2	Sumathi, Sai, and Surekha Paneerselvam. Computational intelligence paradigms: Theory & applications using MATLAB. CRC Press, 2010.								

3	Goodfellow and Bengio, "Deep Learning", MIT press.
4	Christopher Bishop, "Pattern Recognition and Machine Learning", Springer Science+Business Media, LLC, 2006.
5	Francois Cholle, "Deep Learning with Python" Manning publications.
E-REF	ERENCES:
1	Study-Material-BTech-IT-VIII-sem-Subject-Deep-Learning-deep_learning_Btech_IT_VIII-sem.pdf (ccsuniversity.ac.in)
2	ResNet, AlexNet, VGGNet, Inception: Understanding various architectures of Convolutional Networks – CV-Tricks.com.
3	Convolutional Neural Networks and their components for computer vision – Machine Curve.
4	Dive into Deep Learning — Dive into Deep Learning 0.16.4 documentation (d21.ai).

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:					
CO1	Learn the fundamentals of machine learning, need for deep learning and ensemble learning algorithms, linear algebra concepts and application areas of deep learning models.	Understand				
CO2	Understand the concepts of Convolutional Neural Network (CNN) architecture, training and implementation of different CNN models using Python.	Understand				
СОЗ	Study the concepts of Recurrent Neural Network (RNN) architecture, training and implementation of different CNN models using Python.	Remember				
CO4	Capture the need, methods and concepts for ensemble learning and apply with Python implementation of ensemble learning approaches.	Analyze				
CO5	Identify alternate deep learning models for the listed use cases, identify a suitable algorithm by apprehend the differences between standard deep learning models.	Apply				

COURSE ARTICULATION MATRIX															
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	2	3	2					1	1		1	1	
CO2	3	2		3	2					1	1		1	1	
CO3	3	2		3	2					1	1		1	1	
CO4	3	2		3	2					1	1		1	1	
CO5	3	2	2	3	1					1	1		1	1	
Avg	3.0	2.2	2	3.0	1.8					1.0	1.0		1.0	1.0	
	3/2/1 – indicates strength of correlation (3 – High, 2- Medium, 1- Low)														

	AUTOMATION IN MANUFACTURING		SE	MES	TER	VII		
PREREQUI	REREQUISITES CATEGORY							
1.77 1.1 '	L	Т	P	ТН				
1.Knowledge i	ours/Week	3	0	0	3			
COURSE O	BJECTIVES:							
1. To get	the knowledge of various elements of manufacturing automation.							
2. To stud	dy various techniques of automatic material handling in a manufacturing	organization.						
3. To ide:	ntify suitable automation hardware for the given application.							
	corporate application of electronics and computer engineering in mediacturing automation.	chanical engine	ering f	or en	hanc	ing		
5. To dev	relop CNC programs to manufacture industrial components.							
UNIT I	INTRODUCTION TO AUTOMATION		9	0	0	9		
UNIT II	DETROIT-TYPE AUTOMATION		9	0	0	9		
Automated F. Automation f General Term	low lines, Methods of Work part Transport, Transfer Mechanism, Bufffor Machining Operations, Design and Fabrication Considerations. Aninology and Analysis, Analysis of Transfer Lines Without Storage, Pa	nalysis of Auto	ntrol Formated	unction Flow	ons, a	and es:		
Automated F Automation f General Term Lines with Ste	low lines, Methods of Work part Transport, Transfer Mechanism, Bufffor Machining Operations, Design and Fabrication Considerations. An almology and Analysis, Analysis of Transfer Lines Without Storage, Paperage Buffers, Computer Simulation of Automated Flow Lines.	nalysis of Auto	ntrol F omated on, Au	unction Flow tomate	ons, a v Lin ed Fl	and nes: ow		
Automated F Automation of General Term Lines with Sto UNIT III Industrial Co Control, Com	low lines, Methods of Work part Transport, Transfer Mechanism, Bufffor Machining Operations, Design and Fabrication Considerations. An innology and Analysis, Analysis of Transfer Lines Without Storage, Paperage Buffers, Computer Simulation of Automated Flow Lines. CONTROL TECHNOLOGIES IN AUTOMATION Introl Systems, Process Industries Verses Discrete-Manufacturing Induputer Process Control and its Forms. Computer Based Industrial Control ding Blocks of Automation System: LAN, Analog & Digital I/O Module	nalysis of Automatical Automatical Automatical Stries, Continu	ntrol Formated on, Autority 9 ous Ver Autority Autority Autority 100 pt	unctic Flov tomate 0 erses matic	ons, av Lined Fl O Discr	and les: ow 9		
Automated F. Automation of General Term Lines with Ste UNIT III Industrial Co Control, Com Control, Build	low lines, Methods of Work part Transport, Transfer Mechanism, Bufffor Machining Operations, Design and Fabrication Considerations. An innology and Analysis, Analysis of Transfer Lines Without Storage, Paperage Buffers, Computer Simulation of Automated Flow Lines. CONTROL TECHNOLOGIES IN AUTOMATION Introl Systems, Process Industries Verses Discrete-Manufacturing Induputer Process Control and its Forms. Computer Based Industrial Control ding Blocks of Automation System: LAN, Analog & Digital I/O Module	nalysis of Automatical Automatical Automatical Stries, Continu	ntrol Formated on, Autority 9 ous Ver Autority Autority Autority 100 pt	unctic Flov tomate 0 erses matic	ons, av Lined Fl O Discr	and les: ow 9		
Automated F. Automation of General Term Lines with Ste UNIT III Industrial Co Control, Com Control, Build machine inter UNIT IV NC componer Steps in NC in and tooling of	low lines, Methods of Work part Transport, Transfer Mechanism, Buffer Machining Operations, Design and Fabrication Considerations. An Aninology and Analysis, Analysis of Transfer Lines Without Storage, Paperage Buffers, Computer Simulation of Automated Flow Lines. CONTROL TECHNOLOGIES IN AUTOMATION Introl Systems, Process Industries Verses Discrete-Manufacturing Induputer Process Control and its Forms. Computer Based Industrial Control ding Blocks of Automation System: LAN, Analog & Digital I/O Module face	nalysis of Automatical Automatical Automatical Stries, Continual: Introduction & es, SCADA Systopen and close eatures of CNC	ntrol Formated on, Autority 9 ous Vel Autoritem and 100p ce system	ounction Flow tomate out of RT out on trol on, com	ons, av Lined Fl O Discr Proc U. ma o systempone	9 em,		
Automated F. Automation of General Term Lines with Ste UNIT III Industrial Co Control, Com Control, Build machine inter UNIT IV NC componer Steps in NC in and tooling of	low lines, Methods of Work part Transport, Transfer Mechanism, Buffer Machining Operations, Design and Fabrication Considerations. An aninology and Analysis, Analysis of Transfer Lines Without Storage, Patorage Buffers, Computer Simulation of Automated Flow Lines. CONTROL TECHNOLOGIES IN AUTOMATION Introl Systems, Process Industries Verses Discrete-Manufacturing Induputer Process Control and its Forms. Computer Based Industrial Control ding Blocks of Automation System: LAN, Analog & Digital I/O Module face NUMERICAL CONTROL MACHINES Ints, NC coordinate systems, Point to point, line and contouring systems, manufacturing, Role of NC/CNC technology in modern manufacturing, Fee for machining centre and CNC turning centre, Automatic tool changer, Fee	nalysis of Automatical Automatical Automatical Stries, Continual: Introduction & es, SCADA Systopen and close eatures of CNC	ntrol Formated on, Autority 9 ous Vel Autoritem and 100p ce system	ounction Flow tomate out of RT out on trol on, com	ons, av Lined Fl O Discr Proc U. ma o systempone	9 9 ete ess an-		
Automated F. Automation of General Term Lines with Stormation of General Term Lines with Stormation of Control, Common Control, Build machine intermated UNIT IV NC componer Steps in NC in and tooling of scale, Feature UNIT V Part programs	low lines, Methods of Work part Transport, Transfer Mechanism, Buffer Machining Operations, Design and Fabrication Considerations. An aninology and Analysis, Analysis of Transfer Lines Without Storage, Patorage Buffers, Computer Simulation of Automated Flow Lines. CONTROL TECHNOLOGIES IN AUTOMATION Introl Systems, Process Industries Verses Discrete-Manufacturing Induputer Process Control and its Forms. Computer Based Industrial Control ding Blocks of Automation System: LAN, Analog & Digital I/O Module face NUMERICAL CONTROL MACHINES Ints, NC coordinate systems, Point to point, line and contouring systems, manufacturing, Role of NC/CNC technology in modern manufacturing, Formachining centre and CNC turning centre, Automatic tool changer, Feets of DNC and adaptive control systems.	nalysis of Automatical Automatical Automatical Automatical Stries, Continual: Introduction & Ses, SCADA System open and close eatures of CNC edback devices:	ntrol Formated on, Autority 9 ous Ver Autority 9 loop cressystem Encode 9	o erses matic ad RT o entrol ers ar	O Discr Proc U. ma	9 em, nts ear		

TEXT I	BOOKS:
1.	M.P.Grover, Automation, Production Systems and Computer Integrated Manufacturing, Pearson Education. 2016.
2.	Computer Numerical Control (CNC) Machines Paperback – 1, P. Radhakrishnan, New Central Book Agency; 1st edition, 2013
REFER	RENCES:
1	Steve F Krar, "Computer Numerical Control Simplified", Industrial Press, 2001.
2	Tien-Chien Chang, Richard A. Wysk and Hsu-Pin Wang - Computer Aided Manufacturing, Pearson 2009
3	Frank Lamb - Industrial Automation, Mc Graw Hill,2013

E-REFERENCES:								
1.	Steve F Krar, "Computer Numerical Control Simplified ", Industrial Press, 2001.							
2.	Tien-Chien Chang, Richard A. Wysk and Hsu-Pin Wang - Computer Aided Manufacturing, Pearson 2009							

	URSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Understand the effect of manufacturing automation strategies	Understand
CO2	Apply knowledge of industrial automation by transfer lines and automated assembly lines.	Apply
СОЗ	Understand the electronic control systems in metal machining and other manufacturing processes.	Understand
CO4	Identify different CNC components, systems and controls CNC machines	Apply
CO5	Write CNC programming to solve complex machining process	Understand

COURSE A	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	1	2	1	1	2	2	1			1	1	1	2	2
CO2	1	2	2	1	1	2	1		2		1	1	1	2	2
CO3	1	2	2	2	2	2	1		2		1	1	1	2	2
CO4			1	1	3	2	2	1		2	1	1	1	2	2
CO5				1	3	2	2	1		2	1	1	1	2	2
Avg	1	1.6	1.7	1.2	2.0	2.0	1.6	1	2	2	1.0	1.0	1.0	2.0	2.0
			3/2/1 -	- indic	ates st	rengtl	n of co	rrelatio	on (3 –	High, 2	- Mediu	m, 1- Lo	ow)		

	EPE43	CRYOGENIC ENGINEERING		SE	MES	TER	VI
PRE	REQUI	ISITES CATEGO	ORY	PE	Cr	edit	3
1.Engineering Thermodynamics 2.Refrigeration and air conditioning Hours/Week						P	TH
						0	3
COUI	RSE OB	BJECTIVES:	•		•	•	•
1.	To pro	vide the knowledge of evolution of low temperature science.					
2.	To pro	vide knowledge on the properties of materials at low temperature.					
3.	To fam lines.	niliarize with various gas liquefaction systems and to provide design aspects of cry	yogenic	storag	ge and	trans	fer
4.	To lear	rn information concerning low temperature processes and techniques.					
5.	To be f	familiar with the applications of low temperature technology.		1			
UN	IT I	PROPERTIES OF CRYOGENIC FLUIDS & MATE PROPERTIES AT LOW TEMPERATURE	ERIAL	9	0	0	9
streng Speci	gth, Fatig ific heat -	materials at Cryogenic Temperature – Mechanical Properties – Yield Strength, gue Strength, Ductility and Hardness -Thermal Properties – Thermal expansion, - Electrical and Magnetic Properties- Superconductivity, BCS theory, HT and LT of superconductivity.	, Therm	al Co	nduct	vity	and
	IT II	BASICS OF GAS LIQUEFACTION AND REFRIGERAL SYSTEMS	ATION	9	0	0	9
				_	Ů		
		rigeration-Methods of Production of low Temperatures- Critical Components of I Compressors and Expanders (only description with figure).	Liquefac	ction s		ns – F	leat
Exch Joule	angers, C Thomso	I rigeration-Methods of Production of low Temperatures- Critical Components of I	_		ysten		
Exch Joule Layo	angers, C Thomso	rigeration-Methods of Production of low Temperatures- Critical Components of I Compressors and Expanders (only description with figure). on expansion of a real gas, Isentropic expansion, Comparison of J-T Expansion	n and Is		ysten		
UNI Gas I such Ne an Basic	angers, C Thomso ut and W IT III Liquefact as Ideal to des of Cryco	rigeration-Methods of Production of low Temperatures- Critical Components of I Compressors and Expanders (only description with figure). on expansion of a real gas, Isentropic expansion, Comparison of J-T Expansion or Vorking of Liquid Helium and Nitrogen. VARIOUS GAS LIQUEFACTION AND REFRIGERATION SYSTEM.	TEMS on of Yie em. Liquimon systrigerate	9 ld for uefaction stems.	ystem or Ex or Varion on sy Cryo	0 us cyc	9 eles for rs -
UNI Gas I such Ne ar Basic Pulse	angers, C Thomso ut and W IT III Liquefact as Ideal to des of Cryco	rigeration-Methods of Production of low Temperatures- Critical Components of I Compressors and Expanders (only description with figure). on expansion of a real gas, Isentropic expansion, Comparison of J-T Expansion of Liquid Helium and Nitrogen. VARIOUS GAS LIQUEFACTION AND REFRIGERATION SYSTAND CRYOCOOLERS tion Parameters – Calculation of Liquid Yield, Work requirement and Optimization thermodynamic system, Linde Hampson Cycle, Precooled Linde Hampson system of the Precooled Claude System, Liquefaction systems for He – Collins and Singuicoolers-Ideal Stirling Cycle- Stirling Cryocooler, Philips Refrigerator, Solvey Re	TEMS on of Yie em. Liquimon systrigerate	9 ld for uefaction stems.	ystem or Ex or Varion on sy Cryo	0 us cyc	9 eles for rs -
UNI Gas I such Ne ar Basic Pulse UNI Cryog	angers, Control and War and War and War and War and War and Hydron and Hydron and Hydron and Hydron are of Cryon are Tube Cruthal and Hydron and Hydron and Hydron are of Cryon are the Cruthal and Hydron and Hydron are are and Hydron and Hydro	rigeration-Methods of Production of low Temperatures- Critical Components of I Compressors and Expanders (only description with figure). on expansion of a real gas, Isentropic expansion, Comparison of J-T Expansion of Liquid Helium and Nitrogen. VARIOUS GAS LIQUEFACTION AND REFRIGERATION SYSTAND CRYOCOOLERS tion Parameters – Calculation of Liquid Yield, Work requirement and Optimization thermodynamic system, Linde Hampson Cycle, Precooled Linde Hampson system of Precooled Claude System, Liquefaction systems for He – Collins and Sin Occoolers-Ideal Stirling Cycle- Stirling Cryocooler, Philips Refrigerator, Solvey Regryocooler, Vuilleumier Refrigerator, Dilution Refrigerator and Magnetic Refrigerator	rems. The	9 ermal	ystem o various fon sy Cryo M Cry o insula	ous cyclestem coole vocool	9 cles for rs - ller,
UNI Gas I such Ne an Basic Pulse UNI Cryos their Mate	angers, Control and War and War and War and War and War and Hydron and Hydron and Hydron and Hydron are of Cryon are Tube Cruthal and Hydron and Hydron and Hydron are of Cryon are the Cruthal and Hydron and Hydron are are and Hydron and Hydro	rigeration-Methods of Production of low Temperatures- Critical Components of I Compressors and Expanders (only description with figure). on expansion of a real gas, Isentropic expansion, Comparison of J-T Expansion or Various of Liquid Helium and Nitrogen. VARIOUS GAS LIQUEFACTION AND REFRIGERATION SYSTAND CRYOCOOLERS tion Parameters – Calculation of Liquid Yield, Work requirement and Optimization thermodynamic system, Linde Hampson Cycle, Precooled Linde Hampson system of Precooled Claude System, Liquefaction systems for He – Collins and Sin Decoolers-Ideal Stirling Cycle- Stirling Cryocooler, Philips Refrigerator, Solvey Refrigerator, Vuilleumier Refrigerator, Dilution Refrigerator and Magnetic Refriger CRYOGENIC FLUID STORAGE AND TRANSFER SYSTEMS orage vessels - Dewar Vessel and Vapour Shielded Vessel, Transportation system ance at cryogenic temperatures - Types of Insulation – Expanded Foam, Gas I	rems. The	9 ermal	ystem o various fon sy Cryo M Cry o insula	ous cyclestem coole vocool	9 cles for rs - ller,
UNI Gas I such Ne an Basic Pulse UNI Cryos their Mate	angers, C Thomso ut and W THI Liquefact as Ideal t and Hydro es of Cryc Tube Cr TIV genic Sto performa rials, Vac	rigeration-Methods of Production of low Temperatures- Critical Components of I Compressors and Expanders (only description with figure). on expansion of a real gas, Isentropic expansion, Comparison of J-T Expansion or Vorking of Liquid Helium and Nitrogen. VARIOUS GAS LIQUEFACTION AND REFRIGERATION SYSTAND CRYOCOOLERS tion Parameters – Calculation of Liquid Yield, Work requirement and Optimization thermodynamic system, Linde Hampson Cycle, Precooled Linde Hampson system or Precooled Claude System, Liquefaction systems for He – Collins and Sin Occoolers-Ideal Stirling Cycle- Stirling Cryocooler, Philips Refrigerator, Solvey Refryocooler, Vuilleumier Refrigerator, Dilution Refrigerator and Magnetic Refriger CRYOGENIC FLUID STORAGE AND TRANSFER SYSTEMS Orage vessels - Dewar Vessel and Vapour Shielded Vessel, Transportation system ance at cryogenic temperatures - Types of Insulation – Expanded Foam, Gas I cuum, Evacuated Powder and Multi-Layer Insulation.	rEMS on of Yie em. Liqu mon sys efrigerate rator. ems. The	9 ermal sowder	ystem o various of Cryo M Cryo insulars and	0 us cyc stem coole cocoo 0 Fibr	9 Peles for rs - ler, 9 and ous

TEXT I	TEXT BOOKS:							
1.	J. H. Boll Jr, Cryogenic Engineering							
2.	R. B. Scott, Cryogenic Engineering, Van Nostrand Co., 1959							
REFER	RENCES:							
1	Klaus D. Timmerhaus and Thomas M.Flynn, "Cryogenic Process Engineering", Plenum Press, New York, 1989.							
2	Randal F.Barron, "Cryogenic systems", McGraw Hill, 1986.							
E-REFI	E-REFERENCES:							

	. 1	. ,	1 1	
Ι.	nptel.ac.in /	courses /	down	loads

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:					
CO1	Understand the properties of both cryogenic fluids and material properties for better design process in cryogenic applications.	Understand				
CO2	Apply the knowledge of low temperature production methods.	Understand				
CO3	Analyze the performance parameters of various gas liquefaction systems.	Analyze				
CO4	Understand the various cryogenic fluid storage for transportation systems and transfer lines.	Understand				
CO5	Understand different instrumentation in cryogenics.	Understand				

COURSE ARTICULATION MATRIX

COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	3	1									2	1	
CO2	2	2	2	1									3	1	
CO3	2	2	3	1									3	1	
CO4	2	2	2	1									1	1	
CO5	2	1	1	1									1	1	
Avg	2.0	1.8	2.2	1.0									2.0	1.0	

3/2/1 – indicates strength of correlation (3 – High, 2- Medium, 1- Low)

22MEPE44	FRACTURE MECHANICS AND FAILURE AN	ALYSIS	SEN	1EST	ER	VII	
PREREQU	ISITES	CATEGORY	PE	Cre	edit	3	
1. Student sh	ould study Strength of material.	TT /557 1	L	Т	P	TH	
2. Student sh	ould study Materials Engineering.	Hours/Week	3	0	0	3	
COURSE	OBJECTIVES:		•				
1. Ident	fy and explain the types of fractures of engineered materials and their	characteristic featu	ires.				
	rstand the differences in the classification of fracture mechanics and laized to determine conditions under which engineering materials vie.						
3. Unde	rstand and explain the mechanisms of fracture; and learn how to carry	out engineering fa	ilure aı	nalysis	S.		
4. To le	arn the microstructural aspects that lead to fracture.						
5. Appl	advanced mathematical theories to characterize and predict fracture						
UNIT I	UNIT I BASIC CONCEPTS IN FRACTURE MECHANICS						
	y of stress and strain, elastic deformation, plastic and elasto-plastic le fracture, Probabilistic aspects of fracture mechanics – Microstruct		e fract	ure: C	riffit	h's	
UNIT II	MECHANICS OF FRACTURE- STATIC LOADING		9	0	0	9	
– J integral a	 Analytical solutions yielding near a crack front – Irwin's approximand its relation to crack opening displacement. Strain energy release aghness of different materials: size effect & control 						
UNIT III	FAILURE ANALYSIS OF FATIGUE FRACTURE		9	0	0	9	
calculations	sources of failures- Deficiency in design, Empirical Relation deserver a given load amplitude – effects of changing the load spectrum – I latigue failures, some case studies in analysis of fatigue failures.						
UNIT IV	FAILURE ANALYSIS OF CREEP RUPTURE		9	0	0	9	
creep, Mech	levated temperature: Time dependent mechanical behavior, stress ruanism of creep deformation and Creep deformation maps, Prediction case studies in analysis of creep failures.						
UNIT V	FAILURE ANALYSIS OF CORROSION AND WEAR		9	0	0	9	
types of cor	ear, analyzing wear failure, corrosion failures- factors influencing corosion, stress corrosion cracking, sources, characteristic of stress corrosion cracking, various types hydrogen damage failures.						

TEXT I	TEXT BOOKS:							
1.	Hertz berg R W, "Deformation and fracture mechanics of Engineering Materials" Second Edition John Wiley's sons inc, New York 1983.							
2.	Knott. J.F, "Fundamentals of Fracture Mechanics" Butterworth London, 1973.							
REFER	REFERENCES:							
1	Evalds H L and RJH Warnhil," Fracture Mechanics", Edward Arnold Ltd, Baltimore, 1984.							

1	Evalds H L and RJH Warnhil," Fracture Mechanics", Edward Arnold Ltd, Baltimore, 1984.
2	Campbell J E, Underwood J H, and Gerberich W., "Applications of Fracture Mechanics for the selection of Materials", American Society for Metals, Metals Park Ohio, 1982.
3	Fracture Mechanics Metals Handbook, ninth edition, vol. 8 437-491, American Society of Metals Metal Park Ohio, 1985.
4	Kare Hellan, "Introduction of Fracture Mechanics", McGraw-Hill Book Company, 1985.
5	Prashant Kumar, "Elements of Fracture Mechanics", Wheeler Publishing, 1999.

E-REFE	E-REFERENCES:								
1	https://www.fracturemechanics.org/								
2	https://archive.nptel.ac.in/courses/112/107/112107241/								
3	http://vucoe.drbriansullivan.com/wp-content/uploads/Fundamentals-of-Fracture-Mechanics.pdf								

	URSE OUTCOMES: n completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Familiarize the structure design to prevent failure from the internal defect.	Create
CO2	Illustrate the design structure to prevent fatigue and creep – in static loading.	Create
CO3	Solve the problems related to deformation and related theories for fatigue fracture.	Evaluate
CO4	Formulate the empirical relations for creep fracture.	Apply
CO5	Analyse the failures in corrosion and wear.	Analyse

COURSE A	OURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	1	1		2	1						3	1	1
CO2	2	2	1	1		2	1						3	1	1
CO3	2	2	1	1		2	1						3	1	1
CO4	2	2	1	1		2	1						3	1	1
CO5	2	2	1	1		2	1						3	1	1
Avg	2	2	1	1		2	1						3	1	1
	3/2/1 – indicates strength of correlation (3 – High, 2- Medium, 1- Low)														

22M	EPE45	FUNDAMENTALS OF TRIBOLOGY		SE	MES	TER	VII
PRE	REQUI	SITES	CATEGORY	PE	Cro	edit	3
1.Eng	ineering	Mechanics		L	Т	P	TH
			Hours/Week	3	0	0	3
COU	RSE O	BJECTIVES:			ı	1	
1.	To prov	vide broad understanding of the interdisciplinary subject 'tribology'	and its technologica	al signi	ifican	ce.	
2.	To lear	n about consequences of wear, wear mechanisms, wear theories and	analysis of wear pr	oblem	s.		
3.	To stud	y about properties of lubricants, testing methods and types of lubric	ants.				
4.	To acqu	uire the knowledge about the stress, co-efficient of friction and visco	ous flow in journal b	earing	gs.		
5.	To lear	n about the nature of engineering surfaces, their topography and bea	rings material.				
UN	IT I	SURFACES AND FRICTION		9	0	0	9
Types	sive and	WEAR T – Simple theory of Sliding Wear Mechanism of sliding wear of a Abrasive wear situations – Corrosive wear – Surface Fatigue wear situations – Wear Measurements.					
	T III	LUBRICANTS AND LUBRICATION TYPES		9	0	0	9
		perties of Lubricants — Testing methods — Hydrodynamic Lubricationication — Solid Lubrication — Hydrostatic Lubrication.	on – Elasto- hydro	dynam	ic lub	ricati	on-
UNI	T IV	FILM LUBRICATION THEORY		9	0	0	9
film l	Lubricati	imple shear – Viscous flow between very close parallel plates – Sheaton – High speed unloaded journal bearings – Loaded journal bearingicient of friction – The Sommer field diagram.					
UNI	IT V	SURFACE ENGINEERING AND MATERIALS FOR BI	EARINGS	9	0	0	9
Platin	ng and an	rications – Transformation Hardening, surface fusion – Thermo clodizing – Fusion Processes – Vapour Phase processes – Materials to bearings – Materials for marginally lubricated and dry bearings.					
			Total	(45L)	: 45]	Perio	ods

TEXT BOOKS:

1. A. Harnoy. "Bearing Design in Machinery "Marcel Dekker Inc, New York, 2003.

2. B.C. Majumdar; A.H. Wheeler "Introduction to Tribology of Bearings"

REFERENCES:

M. M. Khonsari & E. R. Booser, "Applied Tribology", John Willey &Sons, New York, 2001

E. P. Bowden and Tabor.D. "Friction and Lubrication", Heinemann Educational Books Ltd., 1974.

A. Cameron, "Basic Lubrication theory", Longman, U.K.., 1981.

M. J. Neale (Editor), "Tribology Handbook", Newnes. Butterworth-Heinemann, U.K., 1995.

E-REFERENCES:

1. NPTEL Videos/Tutorials

	Upon completion of this course, the students will be able to:					
CO1	Familiarize the surface phenomena related to relative motion, the nature of friction, and mechanisms of wear.	Remember				
CO2	Analyze the various wear mechanism and fatigue wear of the engineering components.	Analyze				
CO3	Familiarize the lubricants testing methods and types of lubrication.	Remember				
CO4	Analyze the stress, co-efficient of friction and viscous flow in journal bearings.	Analyze				
CO5	Analyze the surface engineering and materials for bearings.	Analyze				

COURSE A	OURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	3	3	1	1	2						1	2	1
CO2		1	2	2	1	1	1						1	1	1
CO3	1	2	2	2	1	1							2	1	1
CO4		1	2	2	1								2	1	1
CO5		2	2	2									1	2	1
Avg	1	1.6	2.2	2.2	1	1	1.5						1.4	1.4	1.0
	3/2/1 – indicates strength of correlation (3 – High, 2- Medium, 1- Low)														

22ME	PE46	METAL FORMING PROCESS	ES	SE	MES	TER	l VII
PRE	REQUI	SITES	CATEGORY	PE	Credit		3
1.Ma	nufactur	ing processes		L	Т	P	TH
2.Str	ength of	materials	Hours/Week	3	0	0	3
COUL	RSE OF	BJECTIVES:		ı	ı		<u> </u>
1.	To fan formin	niliarize the students about principle, procedure and applica	tions of bulk metmal for	ming a	and sh	neet 1	netal
2.	To illu	strate capabilities and applications of metal forming processes	S.				
3.	To ana	lyze effect of parameters influencing metal forming processes	S.				
4.	Outline	e tooling and equipment required for important metal forming	processes.				
5.	Exami	ne effects of friction, lubrication and causes of common defec	ts in metal forming.				
UN	IT I	FUNDAMENTALS OF METAL FORMING		9	0	0	9
Rolli		ROLLING OF METALS sses, forces and geometrical relationship in rolling, simplified and rolling, problems and defects in rolling, torque and power controlling.		9 ng vari	0 ables,	theo:	9 ries
UNI	T III	FORGING		9	0	0	9
defec vario	cts, and p us press	of forging processes, forging of plate, forging of circular d owder metallurgy forging. Problems on flow stress, true strain tools and dies like piercing dies, blanking dies, compound ing and drawing dies.	n and forging load. Press to	ool des	ign: D	Design	ı of
UNI	T IV	EXTRUSION		9	0	0	9
seam	less pipe	Hot Extrusion, Analysis of Extrusion process, defects in s. Problems on extrusion load. Drawing: Drawing of tubes, rossis of wire, deep drawing and tube drawing. Problems on drawing.	ds, and wires: Wire drawing				
UN	IT V	SHEET METAL FORMING		9	0	0	9
criter proce	ria, defec ess heat t	nods, Bending, stretch forming, spinning and Advanced techn t in formed parts. Advanced Metal forming processes: HERF, reatment, and computer applications in metal forming. Problemmum considering shear.	Electromagnetic forming,	residu	al stre	esses,	in-

Total (45L) = 45 Periods

TEXT BOOKS:							
1.	Surender Kumar, Technology of Metal Forming Processes, Prentice - Hall, Inc., 2008						
2.	Nagpal G.R. Metal forming processes, Khanna publishers, New Delhi, 2004						
REFERENCES:							
1	Serope Kalpakjian, Steven R Schmid, Manufacturing Process for Engineering Materials, 4th Edition, Pearson Education, 2003.						
2	Rao, P.N. Manufacturing Technology, TMH Ltd., 2003						
3	Edward M.Mielink, Metal working Science Engineering", McGraw Hill, Inc, 2000.						
4	Metal Handbook Vol.14, Forming and Forging, Metal Park, Ohio, USA, 1990						

	OUTCOMES: upletion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Understand fundamentals of metal forming and stress curves.	Understand
CO2	State the principles of rolling and stresses developed under rolling loads.	Evaluate
CO3	Brief various forging techniques and defects in forging.	Understand
CO4	Analyze Extrusion and drawing processes and associated stresses developed.	Understand
CO5	Know various process parameters and applied loads in sheet metal working.	Analyze

COURSE ARTICULATION MATRIX

COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1		1							1	1			1		2
CO2	1	2		2						1			1	1	2
CO3		1	2			2				1			1	1	2
CO4	1	1		1						1			1	1	2
CO5	1	3		1	1		2					1	1	1	2
Avg	1	1.6	2	1.3	1	2	2	•	1	1		1	1.0	1	2.0

3/2/1 – indicates strength of correlation (3 – High, 2- Medium, 1- Low)

22MEP	PE47	MICRO AND NANO MACHINING		SEN	AES T	ER	VII
PRERI	EQUI	SITES	CATEGORY	PE	Cro	edit	3
135 0			** /**/ 1	L	Т	P	TH
1.Manut	acturir	g process	Hours/Week	3	0	0	3
COURS	E OB	JECTIVES:					
1. T	Γο give	awareness of different techniques used in micro and nano machini	ng/manufacturing.				
2. T	Γο give	in-depth idea of the conventional techniques used in micro machin	ning/manufacturing.				
3. T	Γο intro	duce Non-conventional micro-nano manufacturing and finishing a	pproaches.				
		roduce Micro and Nanofabrication Techniques and other page manufacturing.	processing routes i	n Mi	cro a	ind I	Nano
UNIT	I	INTRODUCTION		9	0	0	9
UNIT	II	CONVENTIONAL PROCESSES: MICRO-TURNING, DRILLING AND MICRO-MILLING		9	0	0	9
		Micro-turning, Micro-drilling, Micro-milling, Product quality in microsesses Introduction, Micro and nanogrinding, Nanogrinding tools	cromachining Micro	-grind	ling ar	nd Ul	tra-
UNIT	III	NON-CONVENTIONAL PROCESSES: LASER MICRO	OMACHINING	9	0	0	9
		fundamentals of lasers, Laser microfabrication, Laser nanofabrication omachining, Destructive evaluation technologies, Non-destructive			ce, Da	amage	e in
UNIT	IV	MICRO AND NANO FINISHING PROCESSES, MICR	O JOINING	9	0	0	9
	olishing	-finishing, Magnetic abrasive Finishing, Magnetorheological Finish, John Beam finishing. Micro Joining - Challenges, Micro Resistations.					
UNIT	V	APPLICATIONS OF NANO AND MICROMACHININ	G IN INDUSTRY	9	0	0	9
Typical	machi	ning methods, Applications in optical manufacturing, Semiconduct	or and electronics re	lated a	applica	ations	· · ·
			Total	(45L	= 45	Per	iods

TEXT 1	BOOKS:
1.	J. Paulo Davim, Mark J. JacksonNano and Micromachining, John Wiley & Sons, 2013 2 Mark.
2.	J. Jackson, Micro and Nano-manufacturing, Springer, 2006.
REFER	ENCES:
1	Mark. J. Jackson, Micro-fabrication and Nano-manufacturing - Pulsed water drop micromachining CRC Press 2006.
2	NitaigourPremchandMahalik, Micro-manufacturing and Nanotechnology, 2006
3	V.K.Jain, Micro-manufacturing Processes, CRC Press, 2012
4	Yi Qin, Micro-manufacturing Engineering and Technology, William Andrew, 2015
5	Kapil Gupta, Micro and Precision Manufacturing, Springer, 2017

	SE OUTCOMES: mpletion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Understand the various techniques in micro and nano manufacturing.	Understand
CO2	To know about the conventional techniques used in micro manufacturing.	Understand
CO3	To know about the non-conventional techniques used in micro manufacturing.	Understand
CO4	To know about the finishing and joining process used in micro manufacturing.	Understand
CO5	Find the applications of all the areas in industries.	Apply

COURSE	ARTI	CUL	ATIO	N MA	ATRI	X									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1		1						1	1		2		1
CO2		1	1	1						1	1	1	1	2	3
CO3			1	1						1	1	1	1	1	1
CO4	1	2	1	1						1	1	1	1	1	1
CO5	1	1		1						2	2	1	2	2	2
Avg	1.3	1.6	1	1						1.2	1.2	1	1.4	1.5	1.6
	•	•	3/2/1	– ind	icates	streng	th of co	orrelati	ion (3 -	- High, 2	- Mediur	n, 1- Low)		

$\underline{\textbf{PROFESSIONAL ELECTIVES} - \textbf{V}}$

PREREQU	USITES (CATEGORY				
l.Kinematics		CATEGORI	PE	Cre	edit	3
	of Machinery		L	Т	P	TH
2. Dynamics	of Machinery.	Hours/Week	3	0	0	3
COURSE C	OBJECTIVES:					
1. To stu	dy of kinematics of various mechanisms and kinematic synthesis of lin	kages.				
2. To stu	dy of various graphical constructions of acceleration analysis.					
3. To stu	dy static and dynamic force analysis of linkages.					
4. To stu	dy kinematic analysis and kinematic synthesis of spatial mechanisms.					
5. To stu	dy about the spatial mechanisms and robotics.					
UNIT I	INTRODUCTION		9	0	0	9
Methods: Tw Precision pos	er and Dimensional Synthesis - Function Generation - Path Generation or Position, Three Position and Four Position synthesis of four bar Nations Over lay Method. Analytical Methods: Blotch's Synthesis - Fognate linkages - The Roberts - Chebyshev theorem.	Mechanism, Slide	r crank	Mec	hanis	sm,
UNIT III	PATH CURVATURE THEORY		9	0	0	9
	oving centrodes Hartmann's Construction - Inflection Points, The Inflection axis and Bobiller's theorem - Conjugate points and infall's Point.					
UNIT IV	DYNAMICS OF MECHANISMS		9	0	0	9
	nalysis - Inertia force analysis - Combined static and inertia force Ana ment balancing of linkages	lysis - Shaking fo	orce - I	ntrodu	iction	ı to
UNIT V	SPATIAL MECHANISMS AND ROBOTICS		9	0	0	9
		atic analysis of	enatial	mech	anisr	<u> </u>

TEXT I	BOOKS:
1.	Amitabha Ghosh and Asok Kumar Mallik, "Theory of Mechanism and Machines", EWLP, Delhi, 1999.
2.	Kenneth J, Waldron, Gary L. Kinzel, "Kinematics, Dynamics and Design of Machinery", John Wiley-sons, 2016.
REFER	RENCES:
1	Uicker, J.J., Pennock, G. R. and Shigley, J.E., "Theory of Machines and Mechanisms", Oxford University Press, 2017.
2	Sandor G.N., and Erdman A.G., "Advanced Mechanism Design Analysis and Synthesis", Prentice Hall, 1984.
3	Robert L.Norton., "Design of Machinery", Tata McGraw Hill, 2012
4	Sandor G.N., Erdman, A. G, "Advanced mechanism design", Prentice Hall Inc, 1984

	URSE OUTCOMES: n completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Analysis the kinematics of mechanisms.	Evaluate
CO2	Synthesis the kinematics of linkages.	Evaluate
CO3	Acquire knowledge about the theory of path curvature.	Understand
CO4	Learned the dynamics of mechanisms.	Evaluate
CO5	Design the robotics arms and manipulators.	Apply

COURSI	E ARTI	CULA	TION	I MAT	TRIX										
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	2	2			1	1			1		2	2	1
CO2	2	2	2	2			1	1			1		2	2	1
CO3	1	1	1	1									1	1	
CO4	2	2	2	2			1	1			1		2	2	1
CO5	2	2	2	2			1	1			1		2	2	1
Avg	1.8	1.8	1.8	1.8			1	1			1		1.8	1.8	1
			3/2/1 –	indica	tes stre	ength o	f corre	lation ((3 – Hi	gh, 2- M	edium, 1	- Low)			

22Ml	EPE52	DESIGN OF JIGS, FIXTURES AND PRESS	TOOLS	SEM	IEST	ER '	VII
PRE	REQUI	ISITES	CATEGORY	PE	Cre	edit	3
				L	Т	P	TE
			Hours/Week	3	0	0	3
COU	URSE O	BJECTIVES:		<u> </u>			
1.	To und	erstand the functions and design principles of Jigs and fixtures.					
2.	To kno	w the importance of work piece location and its design.					
3.	To kno	w the importance of work piece clamping and its design.					
4.	To kno	w about the importance of jigs bushings and drill jig.					
5.	To kno	w about the design of fixtures.					
UN	I TIV	BASICS OF JIGS AND FIXTURES		9	0	0	9
Elem	nents of J	Jigs and Fixtures- Difference between Jigs and Fixtures- Advantag ligs and Fixtures- Fool Proofing. Materials used in Jigs and Fixt ential features of Jigs and Fixtures- General Design Principles- De-	ures- Degrees of Fre	s- Econ edom-	12 de	grees	ost- of
Elem	nents of J	Jigs and Fixtures- Difference between Jigs and Fixtures- Advantag ligs and Fixtures- Fool Proofing. Materials used in Jigs and Fixt	cures- Degrees of Fre sign steps- Common of	s- Econ edom-	12 de	grees	ost- of
UN Prince speciaction hinger operations	nents of J lom. Esse WIT II ciples of l ial adjusta n 'V' loc ed clamp- ated clam	Jigs and Fixtures- Difference between Jigs and Fixtures- Advantag ligs and Fixtures- Fool Proofing. Materials used in Jigs and Fixt ential features of Jigs and Fixtures- General Design Principles- Des	CVICES location points- adjus locator- Cam operate clamping- types of claining arrangement- quicking arrangem	s- Econ edom- lefects g table lo d 'V' lo imping- ek actio	12 degin Jigs 0 ccating ocator lever	grees designed point Que clan np. Ca	ost- of gn. 9 ats- ick ap- am
Prince speciaction hinger operar flat w	nents of J lom. Esse WIT II ciples of l ial adjusta n 'V' loc ed clamp- ated clam	Jigs and Fixtures- Difference between Jigs and Fixtures- Advantage figs and Fixtures- Fool Proofing. Materials used in Jigs and Fixtures and Fixtures- General Design Principles- Description of Jigs and Fixtures- General Design Principles- Description of Control of	CVICES location points- adjus locator- Cam operate clamping- types of claining arrangement- quicking arrangem	s- Econ edom- lefects g table lo d 'V' lo imping- ek actio	12 degin Jigs 0 ccating ocator lever	grees designed point Que clan np. Ca	ost- of gn. 9 ats- ick ap- am
Prince speciaction hinger operaflat w	nents of Jalom. Essent III III Types of Jalom in 'V' located clampated clam	Jigs and Fixtures- Difference between Jigs and Fixtures- Advantage figs and Fixtures- Fool Proofing. Materials used in Jigs and Fixturestantial features of Jigs and Fixtures- General Design Principles- Design Principles of Control of Six-point location of a three-legged object. Principles of Control of Design Principles of Design Principles of Design Principles of Design Principles of Design	CVICES location points- adjus locator- Cam operate clamping- types of claing arrangement- quick amps- Washers- 'C' was a sign steps.	s- Econ edom- lefects: 9 table lod 'V' loamping- ek actio	12 degin Jigs 0 ccating ocator lever n clann Spher	grees designed g poin Que clan np. Ca ical a	ost- of gn. 9 uts- ick np- am and
Prince specia action hinge opera flat w	nents of Jalom. Essent III III Types of Jalom in 'V' located clampated clam	Jigs and Fixtures- Difference between Jigs and Fixtures- Advantage figs and Fixtures- Fool Proofing. Materials used in Jigs and Fixturestantial features of Jigs and Fixtures- General Design Principles- Description of Jigs and Fixtures- General Design Principles- Description of Catalogue of	CVICES location points- adjus locator- Cam operate clamping- types of claing arrangement- quick amps- Washers- 'C' was a sign steps.	s- Econ edom- lefects: 9 table lod 'V' loamping- ek actio	12 degin Jigs 0 ccating ocator lever n clann Spher	grees designed g poin Que clan np. Ca ical a	ost- of gn. 9 uts- ick np- am and
UN Prince specia action hinger operated with Jigs, Jigs- UN Jigs B screw drill	ents of John Essential Adjustant Victorial Adjustant Victoria Adjustant Victorial Adju	Jigs and Fixtures- Difference between Jigs and Fixtures- Advantage figs and Fixtures- Fool Proofing. Materials used in Jigs and Fixtures and Fixtures- General Design Principles- Desential features of Jigs and Fixtures- General Design Principles- Desocation- types of locators- pins and studs- V block- cup and cone able stops- location from finished holes in the work. Diamond pin cator - Six-point location of a three-legged object. Principles of contwo-way clamp - swinging clamp- wedge clamp- eccentric clamp appropriate turn screw. Toggle clamp- Pneumatic and hydraulic class folerance, Tolerance Analysis and problems. DESIGN OF JIGS Tigs - Post, turnover, Channel, Latch, Box, Pot, Angular post jigs and Development of Jigs and Fixtures for the given component.	CVICES location points- adjus locator- Cam operate lamping- types of claing arrangement- quick amps- Washers- 'C' was a locator and Pneuring- slip renewable burill Jigs: Open drill jigs:	s- Econ edom- lefects 9 table lod 'V' lo umping- ck actio vasher- 9 matic J 9 ushing- g plate	12 de in Jigs 0 cating ocator lever n clan Spher 0 liner t drill ji	grees designed of the control of the	9 ing g g g g g g g g g g g g

Introduction - principles of fixture design- element of fixtures. Design consideration of locators and clamps for fixturestypes of fixtures. Design of turning fixtures- Boring fixtures- Planning Fixtures - milling fixtures, Method of locating milling fixtures with respect to cutter position - Assembly and Inspection Fixtures - Special Purpose Fixtures. Grinding fixtures- surface grinding and cylindrical grinding fixtures. Broaching fixtures- internal and external broaching fixtureswelding fixtures. Modular Fixturing systems - Design and Development of Fixtures for given components.

Total (45L) = 45 Periods

TEXT I	BOOKS:							
1.	Design of Jigs, Fixtures and Press tools, C.Elanchezhian, T.Sunderselvan, B.Vijayaramnath, Eswar Press, 2005.							
2.	Nagpal, G R, Tool Engineering & Design, 2000, Khanna Publishers.							
REFER	REFERENCES:							
1	Joshi, P H, Jigs & Fixtures, 2010, 3rd Edition, McGraw Hill.							
2	Jig and fixture design- 5th edition by Hoffman.							
3	Venkataraman, K, Design of Jigs, Fixtures & Press Tools, 2015, Wiley & Sons.							
4	Mehta, N K, Metal Cutting and Design of Cutting Tools, Jigs & Fixtures, 2015, McGraw Hill Publisher.							

	URSE OUTCOMES: n completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Understand the basics of jigs and fixtures and its designing principles.	Understand
CO2	Identify and design the various locating and clamping devices.	Evaluate
CO3	Design the jigs for various components.	Create
CO4	Identify and design the jig bushes and drill jigs.	Evaluate
CO5	Design the fixtures for various components.	Create

COURSE A	OURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	2	1	1		2	1	1		1		2	2	1
CO2	1	2	2	1	1		1	1	1		1		2	2	1
CO3	1	2	2	2	2		1	1	1		1		2	2	1
CO4	1	2	1	1	3		2	1	1		1		2	2	1
CO5	1	2	1	1	3		2	1	1		1		2	2	1
Avg	1	2	1.6	1.2	2.0		1.6	1	1		1		2	2	1
		3	/2/1 –	indica	ites st	rengtl	of co	rrelati	on (3 -	- High, 2	2- Medi	um, 1- L	ow)		

22MI	EPE53	HEAT TRANSFER PROBLEMS IN ELECTRONICS AND INSTRUMENTATION	SEN	IEST	ER '	VIII					
PRE	REQUI	SITES CATEGORY	PE	Cre	edit	3					
1.Fu	ndamenta	al knowledge in various modes of heat transfer	L	Т	P	TH					
2.Ba	sic conce	pts of electronics and instrumentation Hours/Week	3	0	0	3					
COU	RSE O	BJECTIVES:	-		•						
1.	Unders	tanding the basic principles of heat transfer in electronic systems.									
2.	2. Learning to solve conduction heat transfer problems in electronic equipment.										
3.	Studyir	ng about the convection heat transfer phenomena in electronic applications.									
4.	Acquir	ing the knowledge in the radiation heat transfer in electronic instruments.									
5.	Unders	tanding the principles of thermal design of electronic equipment.									
UN	9	0	0	9							
		tronic and instrumentations, basics of thermodynamics and heat transfer, Components of gement in electronic devices - Packaging Trends. Electronic packaging and interconne				ns,					
UN	II TI	CONDUCTION HEAT TRANSFER IN ELECTRONIC EQUIPMENT	9	0	0	9					
Cond Cond	uction ir uction—' Surface F	ductivity, Thermal Resistances, Conductivity in Solids, Conductivity in Fluids, Conduction Simple Geometries, Conduction through a Plane Wall, Conduction through Cy Transient, Lumped Capacitance Method, Conduction in Extended Surfaces. Fin Efficier Efficiency, Thermal Contact Resistance in Electronic Equipment, Discrete Heat S	linders cy, Fin	and Optin	Sphei nizati	res. on,					
UNI	T III	CONVECTION HEAT TRANSFER IN ELECTRONIC EQUIPMENT	9	0	0	9					
Coeff	icient. L	eat Transfer in Electronic Equipment. Natural Convection in Electronic Devices, Ciquid Cooling Systems, Coolant Selection, Pressure Drop and Pump Requirements. aft Cooling, Selection of Fans and Blowers.									
UNI	TIV	RADIATION HEAT TRANSFER IN ELECTRONIC EQUIPMENT	9	0	0	9					
Emitt	ance Fac	agnetic Spectrum, Radiation Equations, Stefan-Boltzmann Law, Surface Charactor, Emittance from Extended Surface, Absorptance, Reflectance, Specular Reflectance. Combined Modes of Heat Transfer for Electronic Equipment, Radiation and Convect	e, Heat	Trans	sfer w						
UN	IT V	THERMAL ANALYSIS OF ELECTRONIC EQUIPMENT	9	0	0	9					
Stiffr Heat	ess on W Sinks, H	nermal Failure of Electronic Components. Analysis of Thermal Stresses and Strain, Edvire Stresses, Vibration Fatigue in Lead Wires and Solder Joints. Electronics Cooling Heat Pipes, Heat Pipes in Electronics Cooling, Thermoelectric Cooling, Immersion High Density Electronics.	Method	ds in I	ndust	try.					
		Tota	l (45L)	= 45	Per	iods					

TEX	XT BOOKS:						
1.	Heat transfer Dr. A.S. Padalkar, NiraliPrakashan, Pune 2012						
2.	Heat & mass transfer, D.S. Kumar, S.K. Kataria& Sons, 2010						
REI	REFERENCES:						
1	Heat transfer B.L. Singhal, Techmax, publication, Pune 2010						
2	Heat & mass transfer, Mills and Ganesan, Pearson Publication, New Delhi 2010						
E-R	EFERENCES:						
1	https://nptel.ac.in/courses						

	RSE OUTCOMES: n completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Apply the concepts of heat transfer laws and principles in electronic systems.	Apply
CO2	Solve conduction heat transfer problems in various electronic instruments.	Evaluate
CO3	Analyze the real time convection heat transfer problems of electronic equipment.	Analyze
CO4	Solve the problems of combined effect of heat transfer form electronic equipment.	Apply
CO5	Determine the thermal stresses and strains in various real time electronic systems.	Evaluate

COURSE A	ARTI	CULA	ATIO	N MA	ATRE	X									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	1		1			2					1	1	1
CO2	3	2						1					2	1	1
CO3	3	3			1			2					3	3	2
CO4	3	2			2			1					3	1	1
CO5			1	1		1	1					1			
Avg	2.2	2.25	1	1	1.3	1	1	1.5				1	2.2	1.5	1.2
	•	•	3/2/1	– indi	cates s	trengt	h of c	orrelat	ion (3	– High,	2- Medi	ium, 1- L	ow)		•

22M	EPE54	NANO TECHNOLOGY		SEN	IEST	ER	VII
PREI	REQUI	SITES	CATEGORY	PE	Cre	edit	3
			** /**/ 1	L	T	P	TF
			Hours/Week	3	0	0	3
cot	IRSE O	BJECTIVES:					
1.	To mot	ivate the students to understand the evolution of nanomaterials in th	e scientific era.				
2.	To mal	te them to understand different processing methods.					
3.	To mal	te them to understand properties of nanomaterials for the future eng	ineering applications	S			
UN	IT I	INTRODUCTION		9	0	0	9
Botto		rithesis-Top-down Approach: Co-Precipitation, Ultrasonication, Menous phase deposition, MCCVD, Sputtering, Evaporation, Melocule					
		onthesis-Top-down Approach: Co-Precipitation, Ultrasonication, Mepour phase deposition, MOCVD, Sputtering, Evaporation, Molecula					
Meta	1 Organi	c MBE (MOMBE).		1			
UNI	T III	NANOMATERIALS		9	0	0	9
and N struct	Multi wal ture-prop	Carbon - Buckminster fullerene- graphene and carbon nanotube, Solicarbon nanotubes (MWCNT)- methods of synthesis(arc-growth, labority Relationships applications- Nanometal oxides-ZnO, TiO ₂ ,MgO oclays- functionalization and applications-Quantum wires, Quantum	ser ablation, CVD ro, ZrO ₂ , NiO, nanoalu	outes, l mina,	Plasm CaO,	a CV AgTi	D), O ₂ ,
UNI	T IV	CHARACTERIZATION TECHNIQUES		9	0	0	9
inclu		ion technique, Scanning Electron Microscopy - environmental technich-resolution imaging, Surface Analysis techniques- AFM, SPM					

Nano InfoTech: Information storage- Nano computer, molecular switch, super chip, nanocrystal, Nanobiotechnology: nanoprobes in medical diagnostics and biotechnology, Nano medicines, Targeted drug delivery, Bioimaging - Micro Electro Mechanical Systems (MEMS), Nano Electro Mechanical Systems (NEMS)- Nano sensors, nano crystalline silver for bacterial inhibition, Nanoparticles for sun barrier products - In Photostat, printing, solar cell, battery.

Total (45L) = 45 Periods

9

0

0

9

TEX	T BOOKS:								
1.	Carl C. Koch (ed.), "Nanostructured Materials", Processing, Properties and Potential Applications, Noyes Publications, Norwich, New York, U.S.A.								
2.	A.S. Edelstein and R.C. Cammearata, eds., "Nanomaterials: Synthesis, Properties and Applications", Institute of Physics Publishing, Bristol and Philadelphia, 1996.								
3.	A Textbook of Nanoscience and Nanotechnology – T.Pradeep, Tata McGraw Hill edition.								
REF	REFERENCES:								
1	G Timp, "Nanotechnology", AIP press/Springer, 1999.								
2	Akhlesh Lakhtakia, "The Hand Book of Nano Technology, Nanometer Structure, Theory, Modeling and Simulations". Prentice-Hall of India (P) Ltd, New Delhi, 2007.								
3	Mark Ratner and Daniel Ratner, "Nano Technology", Pearson Education, New Delhi, 2003.								
4	Charles P. Poole Jr., Frank J. Ownes, 'Introduction to Nanotechnology", Wiley Interscience, 2003								

UNIT V

APPLICATIONS

	RSE OUTCOMES: a completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Will familiarize about the science of nanomaterials	Remember
CO2	Will demonstrate the preparation of nanomaterials	Understand
CO3	Use of difficult characterization techniques to study the fundamental properties.	Apply
CO4	To know the various industrial applications using nanomaterials.	Understand
CO5	Will familiarize about the science of nanomaterials	Remember

COURSE A	OURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	2	1		2		1			1		2	2	1
CO2	2	1	1	1			1				1		2	1	
CO3	2	1	1	1			1				1		2	1	
CO4	2	1	1	1		1	1	1			1		2	1	
CO5	2	2	1	1		1	1	1			1		2	2	1
Avg	2.0	1.4	1.2	1.0		1.3	1	1			1		2.0	1.4	1
			3/2/1	– indi	cates s	treng	th of c	orrelat	ion (3	– High,	2- Medi	um, 1- L	ow)		

PREREQUI					LI	VIII						
	SITES	CATEGORY	PE	cre	dit	3						
			L	Т	P	TH						
		Hours/Week	3	0	0	3						
COURSE O	BJECTIVES:			I		<u> </u>						
1. To tead	th the fundamental physics about nuclear processes and a heat transfer	er technique from n	uclear	energy	у.							
2. To intr	o introduce the nuclear fuels, its properties and extraction techniques of nuclear fuels.											
3. To tead	th the characteristics of spent fuel and reprocessing techniques.											
4. To tead	th the design, construction and heat transfer in nuclear reactor.											
5. To tead	th the safety aspects used in nuclear reactor and disposal of nuclear v	vaste.										
UNIT I		9	0	0	9							
Mechanism o	f Nuclear Fission - Nuclides - Radioactivity – Decay Chains - Neutro	on Reactions - The	Fission	Proce	ess							
UNIT II	REACTOR MATERIALS		9	0	0	9						
	s of Nuclear Fuels - Uranium - Production and Purification of Uraniu conium, Thorium - Beryllium.	ım - Conversion to	UF4 an	d UF	5 - Ot	her						
UNIT III	REPROCESSING		9	0	0	9						
Nuclear Fuel Equipment.	Cycles - Spent Fuel Characteristics - Role of Solvent Extraction	n in Reprocessing	- Solve	ent Ex	tract	ion						
UNIT IV	NUCLEAR REACTOR		9	0	0	9						
	ors: types of fast breeding reactors-design and construction of fast bretors-reactor shielding. Fusion reactors.	reeding reactors-hea	at trans	fer tec	chniq	ues						
UNIT V	SAFETY AND DISPOSAL		9	0	0	9						
	sposal: Nuclear plant safety-safety systems-changes and consequence f waste and its disposal-radiation hazards and their prevention-weap		ria for	safety	-nucl	ear						

TEXT I	BOOKS:									
1.	Thomas J.Cannoly, "Fundamentals of nuclear Engineering" John Wiley 1978.									
2.	lasstone, S and Sesonske, A, "Nuclear Reactor Engineering", 3rd Edition, Von Nostrand, 1981.									
3.	amarsh, J.R., "Introduction to Nuclear Reactor Theory", Wesley, 1966.									
REFER	REFERENCES:									
1	Winterton, R.H.S., "Thermal Design of Nuclear Reactors", Pergamon Press, 1981.									
2	Jelly N A, "Nuclear Engineering", Cambridge University Press, 2005.									
3	Duderstadt, J.J and Hamiition, L.J, "Nuclear Reactor Analysis", John Wiley, 1976.									
4	Walter, A.E and Reynolds, A.B, "Fast Breeder Reactor", Pergamon Press, 1981.									
E-REFE	RENCES:									
1	http://nptel.ac.in/courses/112101007/									

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:								
CO1	Understand the fundamental knowledge about nuclear reactions.	Understand							
CO2	Understand the various nuclear fuels and its properties.	Understand							
CO3	Explain the nuclear fuel cycles and spent fuel characteristics.a	Analyze							
CO4	Understand the design and heat transfer in nuclear reactor.	Understand							
CO5	Explain the safe disposal of nuclear wastes.	Apply							

COURSE A	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	2	1	1	1	1						1	1	1
CO2	1	1	2	1	2	1	2						2	3	3
CO3	1	1	1	1	1	1	1						1	2	1
CO4	3	1	1	1	1	2	1						3	1	1
CO5	1	1	2	1	1	1	1						1	3	1
Avg	1.4	1.2	1.6	1.0	1.2	1.2	1.2						1.6	2.0	1.4
	•	3.	/2/1 –	indica	tes str	ength	of cor	relatio	n (3 –	High, 2-	Mediun	n, 1- Lov	w)		

	THERMAL TURBO MACHINES		SEM	IEST	ER	VIII
PREREQUI	SITES	CATEGORY	PE	Cre	edit	3
			L	Т	P	ТН
		Hours/Week	3	0	0	3
COURSE O	BJECTIVES:				1	ı
1. To und compor	erstand the various systems, principles, operations and application nents.	s of different types	of turl	oo ma	chine	ery
UNIT I	INTRODUCTION TO TURBO MACHINES		9	0	0	9
compressionto – Static ef	triangles Thermal Turbo machines – Classification – General energen and expansion process – Velocity triangles – Work – T-S and H-S ficiencies. Dimensional analysis – Non dimensional parameters of s, applications and limitations.	diagram, Total – to	o – Tot	al and	l Tota	al –
UNIT II	CENTRIFUGAL FANS AND COMPRESSOR		9	0	0	9
impeller blade measures. Cer	lection and classifications —Types of blading design-velocity triangles —Design parameter- Volute and Diffusers — Efficiencies and Los atrifugal Compressors: - Constructional details — Stage velocity trianglency — Degree of reaction — Slip factor — H-S diagram — Efficiencies	ses – Fan noises – G gles — Stage work	Causes – Stag	and in a pres	emed	lial
impeller blade measures. Cer	es —Design parameter- Volute and Diffusers — Efficiencies and Los atrifugal Compressors: - Constructional details — Stage velocity trians	ses – Fan noises – G gles — Stage work	Causes – Stag	and in a pres	emed	lial
impeller blade measures. Cer – Stage efficie UNIT III Definition and Cascade tunne Compressors:	es –Design parameter- Volute and Diffusers – Efficiencies and Los attrifugal Compressors: - Constructional details – Stage velocity triangency – Degree of reaction – Slip factor – H-S diagram – Efficiencies AXIAL FANS AND COMPRESSOR I classifications – Stage parameters – Types of fan stages-performatel - Blade Geometry-Cascade Variables-Energy transfer and loss definition and classifications – Constructional details – Stage velocity agram – Stage efficiencies and losses- Degree of reaction – Radional Construction – Radional C	ses – Fan noises – Gagles — Stage work s – Performance characteristics. in terms of lift and sy triangles – Stage w	Causes — Stag racteris 9 Cascad drag vork —	e pressitics. 0 de of - Axi	o blade ial Fl	g g s – ow ure
impeller blade measures. Cer – Stage efficie UNIT III Definition and Cascade tunne Compressors: rise – H-S di	es –Design parameter- Volute and Diffusers – Efficiencies and Los attrifugal Compressors: - Constructional details – Stage velocity triangency – Degree of reaction – Slip factor – H-S diagram – Efficiencies AXIAL FANS AND COMPRESSOR I classifications – Stage parameters – Types of fan stages-performatel - Blade Geometry-Cascade Variables-Energy transfer and loss definition and classifications – Constructional details – Stage velocity agram – Stage efficiencies and losses- Degree of reaction – Radional Construction – Radional C	ses – Fan noises – Gagles — Stage work s – Performance characteristics. in terms of lift and sy triangles – Stage w	Causes — Stag racteris 9 Cascad drag vork —	e pressitics. 0 de of - Axi	o blade ial Fl	g g s – ow ure
impeller blade measures. Cer – Stage efficient with the stage of the s	es –Design parameter- Volute and Diffusers – Efficiencies and Los attrifugal Compressors: - Constructional details – Stage velocity trians ency – Degree of reaction – Slip factor – H-S diagram – Efficiencies AXIAL FANS AND COMPRESSOR I classifications – Stage parameters – Types of fan stages-performatel - Blade Geometry-Cascade Variables-Energy transfer and loss definition and classifications – Constructional details – Stage velocities agram – Stage efficiencies and losses- Degree of reaction – Radicharacteristics.	ses – Fan noises – or agles — Stage work s – Performance characteristics. In terms of lift and ty triangles – Stage white Equilibrium-Surfage pressure rise – 1	Causes Stag racteris 9 Cascad drag work rging a	and the pression of the pressi	o blade ial Fl press calling	g - g - g
impeller blade measures. Cer – Stage efficient with the stage of the s	es –Design parameter- Volute and Diffusers – Efficiencies and Los attrifugal Compressors: - Constructional details – Stage velocity triangency – Degree of reaction – Slip factor – H-S diagram – Efficiencies AXIAL FANS AND COMPRESSOR I classifications – Stage parameters – Types of fan stages-performatel - Blade Geometry-Cascade Variables-Energy transfer and loss definition and classifications – Constructional details – Stage velocity agram – Stage efficiencies and losses- Degree of reaction – Radicharacteristics. AXIAL FLOW TURBINES details –90° IFR turbine- Stage work – Stage Velocity triangles – Stage ve	ses – Fan noises – or agles — Stage work s – Performance characteristics. In terms of lift and ty triangles – Stage white Equilibrium-Surfage pressure rise – 1	Causes Stag racteris 9 Cascad drag work rging a	and the pression of the pressi	o blade ial Fl press calling	g - g - g

Total (45L) = 45Periods

TEXT I	BOOKS:
1.	Yahya, S.M., "Turbines, Compressors and Fans", Tata McGraw Hill Publishing Company, 1996.
2.	Dixon S.L, "Fluid Mechanics, Thermodynamics of Turbo Machines", 2nd Edition, Pergamon press, 1990.
3.	Kadambi V and Manohar Prasad, "An Introduction to Energy Conversion - Vol. III Turbo Machines", Wiley Eastern India Ltd, 1977.
REFER	RENCES:
1	Bruneck, Fans, Pergamom Press, 1973.
2	Earl Logan, Jr., Hand book of Turbomachinery, Marcel Dekker Inc., 1992.
3	Shepherd, D.H., Principles of Turbomachinery, Macmillan, 1969.
4	Stepanpff, A.J., Blowers and Pumps, John Wiley and Sons Inc. 1965.
5	Ganesan, V., Gas Turbines, Tata McGraw Hill Pub. Co., 1999.
6	Rangwala A S, "Structural Dynamics of Turbo-Machines", New Age International, 2005.
7	Astashev VK, Babitsky VI and Kolovsky MZ, "Dynamics and Control of Machines", Springer Pub, 2000

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:							
CO1	Understand the basic concept of compressors, turbines, fans and blowers.	Understand						
CO2	Analyze the velocity triangles of centrifugal fans and compressors.	Analyze						
CO3	Analyze the construction details and performance of axial fans and compressor.	Analyze						
CO4	Analyze the design variations of axial flow turbines.	Analyze						
CO5	Understand the construction features and performance analysis of radial flow turbine and wind turbine.	Understand						

COURSE A	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	1	1	3	1	1						1	2	2
CO2	1	3	1	1	2	1	1						1	1	3
CO3	2	1	3	1	1	2	1						1	1	2
CO4	2	1	1	1	3	1	1						1	1	2
CO5	2	1	1	3	1	2	1						2	3	1
Avg	1.6	1.6	1.4	1.4	2.0	1.4	1.0						1.2	1.6	2.0
		3/2/	′1 – in	dicate	stren	gth of	corre	lation (3 – Hi	gh, 2- M	ledium,	1- Low)			

22M	EPE57	TOTAL QUALITY MANAGEMENT		SEN	IEST	SEMESTER '							
PRE	REQUI	SITES	CATEGORY	PE	Cre	edit	3						
			Hanna/Wash	L	Т	P	ТН						
			Hours/Week	3	3								
COU	RSE O	BJECTIVES:											
1.		the need for quality, its evolution, basic concepts, contribution of enefits of TQM.	quality gurus, TQM	frame	work,	Barri	ers						
2.	Explain	n the TQM Principles for application.											
3.	Define	Define the basics of Six Sigma and apply Traditional tools, New tools, Benchmarking and FMEA.											
4.	Describ BPR.	be Taguchi's Quality Loss Function, Performance Measures and app	ly Techniques like (QFD, T	PM, C	OQ a	and						
5.	Illustra	te and apply QMS and EMS in any organization.											
UNI	ΤΙ	INTRODUCTION		9	0	0	9						
Empl proce	omer sati	TQM PRINCIPLES asfaction - Customer perception of quality, Customer complaints colvement - Motivation, Empowerment, Teams, Recognition and revolvement - Juran Trilogy, PDSA Cycle, 5S, Kaizen - Supplier Pag, Relationship development - Performance measures, Basic concepts	vard, Performance a artnership, Sourcing	ppraisa	l - Co	ntinu	ous						
UNI	T III	STATISTICAL PROCESS CONTROL (SPC)		9	0	0	9						
Norm		ls of quality, Statistical fundamentals – Measures of central tendence - Control charts for variables and attributes, Process capabilitiosls.											
UNI	T IV	TQM TOOLS		9	0	0	9						
qualit	ty, Bene	g – Reasons to benchmark, Benchmarking process, Quality functio fits - Taguchi quality loss function - Total productive maintenances of FMEA.											
UNI	T V	QUALITY MANAGEMENT SYSTEMS		9	0	0	9						
	for ISO	9000 and other quality systems, benefits of ISO registration, ISO) 9001·2008 quality	syster	n – E	leme	nts,						
		on of quality system, Documentation, Quality auditing, AS 9100,TS											

TEXT I	BOOKS:								
1.	Dale H.Besterfiled, Carol B.Michna, Glen H. Bester field, Mary B. Sacre, Hemant Urdhwareshe and Rashmi Urdhwareshe, "Total Quality Management", Pearson Education Asia, Revised Third Edition, Indian Reprint, Sixth Impression, 2013.								
2.	Feigenbaum.A.V. "Total Quality Management", McGraw Hill, 1991.								
REFER	REFERENCES:								
1	Joel.E. Ross, "Total Quality Management – Text and Cases", Routledge. 2017.								
2	Kiran.D.R, "Total Quality Management: Key concepts and case studies, Butterworth – Heinemann Ltd, 2016.								
3	Oakland, J.S. "TQM – Text with Cases", Butterworth – Heinemann Ltd., Oxford, Third Edition, 2003.								
4	Suganthi,L and Anand Samuel, "Total Quality Management", Prentice Hall (India) Pvt. Ltd., 2006								
5	Narayana V and Sreenivasan, N.S, "Quality Management – Concepts and Tasks", New Age International,								

	1996.										
E-REFERENCES:											
1	https://www.oreilly.com/library/view/total-quality-management/9780815330486/xhtml/Reference1.xhtml										
2	https://www.sanfoundry.com/best-reference-books-total-quality-management/										
3	https://www.routledge.com/Total-Quality-Management-TQM-Principles-Methods-and-Applications/Luthra-Garg-Agarwal-Mangla/p/book/9780367512835										

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:						
CO1	Ability to apply TQM concepts in a selected enterprise.	Apply					
CO2	Ability to apply TQM principles in a selected enterprise.	Apply					
CO3	Ability to understand Six Sigma and apply Traditional tools, new tools, Benchmarking and FMEA.	Understand					
CO4	Ability to understand Taguchi's Quality Loss Function, Performance Measures and apply QFD, TPM, COQ and BPR.	Understand					
CO5	Ability to apply QMS and EMS in any organization.	Apply					

COURSE ARTICULATION MATRIX

COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	3			2		1		2			2	1	2	1
CO2	1	2							2			2			
CO3	1	2	2		1			1				2	1		1
CO4	1	2			2	3		2		3		2	2	2	1
CO5	1	2	2		2	2	1	2	2	3		2	2	2	1
Avg	1	2.2	2		1.7	2.5	1	1.7	2	3		2	1.5	2	1

3/2/1 – indicates strength of correlation (3 – High, 2- Medium, 1- Low)

PROFESSIONAL ELECTIVES – VI

OBJECTIVES: ribe tool design methods and punch and die manufacte et material for cutting tools and gages; classify various ribe the principles of clamping, drill jigs and compute gen fixtures for milling, boring, lathe, grinding, welding ain the principles of dies and moulds design. DESIGN OF CUTTING TOOLS als, design of single point cutting tool, form tool, drill, METAL CUTTING	cutting tools and gages and identify raided jig design. g; identify fixtures and cutting tools	for NC 9 utter.	T 0				
ribe tool design methods and punch and die manufacte et material for cutting tools and gages; classify various ribe the principles of clamping, drill jigs and compute gan fixtures for milling, boring, lathe, grinding, welding ain the principles of dies and moulds design. DESIGN OF CUTTING TOOLS als, design of single point cutting tool, form tool, drill,	uring techniques. cutting tools and gages and identify r aided jig design. g; identify fixtures and cutting tools	y their refor NC	nomer C macl	nclatu	are.		
ribe tool design methods and punch and die manufacte et material for cutting tools and gages; classify various ribe the principles of clamping, drill jigs and compute gan fixtures for milling, boring, lathe, grinding, welding ain the principles of dies and moulds design. DESIGN OF CUTTING TOOLS als, design of single point cutting tool, form tool, drill,	uring techniques. cutting tools and gages and identify r aided jig design. g; identify fixtures and cutting tools	y their refor NC	nomer C macl	nclatu	re.		
ribe tool design methods and punch and die manufacte et material for cutting tools and gages; classify various ribe the principles of clamping, drill jigs and compute gan fixtures for milling, boring, lathe, grinding, welding ain the principles of dies and moulds design. DESIGN OF CUTTING TOOLS als, design of single point cutting tool, form tool, drill,	cutting tools and gages and identify raided jig design. g; identify fixtures and cutting tools	for NC 9 utter.	C macl	hine t	ools.		
et material for cutting tools and gages; classify various ribe the principles of clamping, drill jigs and compute gan fixtures for milling, boring, lathe, grinding, welding ain the principles of dies and moulds design. DESIGN OF CUTTING TOOLS als, design of single point cutting tool, form tool, drill,	cutting tools and gages and identify raided jig design. g; identify fixtures and cutting tools	for NC 9 utter.	C macl	hine t	ools.		
ribe the principles of clamping, drill jigs and compute gn fixtures for milling, boring, lathe, grinding, welding ain the principles of dies and moulds design. DESIGN OF CUTTING TOOLS als, design of single point cutting tool, form tool, drill,	r aided jig design. g; identify fixtures and cutting tools	for NC 9 utter.	C macl	hine t	ools.		
gn fixtures for milling, boring, lathe, grinding, welding ain the principles of dies and moulds design. DESIGN OF CUTTING TOOLS als, design of single point cutting tool, form tool, drill,	g; identify fixtures and cutting tools	9 utter.			ı		
DESIGN OF CUTTING TOOLS als, design of single point cutting tool, form tool, drill,		9 utter.			ı		
DESIGN OF CUTTING TOOLS als, design of single point cutting tool, form tool, drill,	reamer, broach and plain milling co	utter.	0	0	9		
als, design of single point cutting tool, form tool, drill,	reamer, broach and plain milling co	utter.	0	0	9		
	reamer, broach and plain milling co		ı				
METAL CUTTING							
1		9	0	0	9		
netal cutting – design of tool holders for single point – economics of machining.	tools – Boring bars – selection of	tools	for m	achin	ing		
UNIT III DESIGN OF FIXTURES					9		
ork holding devices – principles of location and clamsign and sketching of milling fixtures for simple compdesign of gauges.							
UNIT IV DESIGN OF DRILL JIGS							
gs – types of jigs: Plate, Leaf, Turn over and Box Jigs	– design and sketching of drill jigs f	for mac	chinin	g sim	ple		
UNIT V PRESS TOOLS							
and Compound dies – die design for simple compone	ents. Drawing dies – blank develop	ment –	estin	nation	n of		
	DESIGN OF DRILL JIGS gs – types of jigs: Plate, Leaf, Turn over and Box Jigs PRESS TOOLS es – die cutting operations – centre of pressure – scrap and Compound dies – die design for simple compone e – blank holders and blank holding pressure – design	DESIGN OF DRILL JIGS gs – types of jigs: Plate, Leaf, Turn over and Box Jigs – design and sketching of drill jigs: PRESS TOOLS es – die cutting operations – centre of pressure – scrap strip lay out for blanking – press to and Compound dies – die design for simple components. Drawing dies – blank develop	DESIGN OF DRILL JIGS gs – types of jigs: Plate, Leaf, Turn over and Box Jigs – design and sketching of drill jigs for mace. PRESS TOOLS gs – die cutting operations – centre of pressure – scrap strip lay out for blanking – press tonnage and Compound dies – die design for simple components. Drawing dies – blank development – te – blank holders and blank holding pressure – design and sketching of drawing dies for simple and Combination tools.	DESIGN OF DRILL JIGS gs – types of jigs: Plate, Leaf, Turn over and Box Jigs – design and sketching of drill jigs for machining PRESS TOOLS gs – die cutting operations – centre of pressure – scrap strip lay out for blanking – press tonnage calculand Compound dies – die design for simple components. Drawing dies – blank development – estimate – blank holders and blank holding pressure – design and sketching of drawing dies for simple components.	DESIGN OF DRILL JIGS gs – types of jigs: Plate, Leaf, Turn over and Box Jigs – design and sketching of drill jigs for machining sime. PRESS TOOLS gs – die cutting operations – centre of pressure – scrap strip lay out for blanking – press tonnage calculation and Compound dies – die design for simple components. Drawing dies – blank development – estimation are – blank holders and blank holding pressure – design and sketching of drawing dies for simple components.		

TEXT	TEXT BOOKS:				
1.	Cyril Donaldson, Lecain and Goold: Tool Design – Tata McGraw Hill publications.				
2.	A Bhattacharyya: Metal Cutting – Theory and Practice – Central Book Agency Kolkata.				
REFER	REFERENCES:				
1	ASTME: Fundamentals of Tool Design – Prentice Hall.				
2	F W Wilson: Hand Book of Fixture Design - McGraw Hill publications.				
3	Edward G Hoffman, "Jigs and Fixture Design", Thomson – Delmar Learning, Singapore 2004.				
4	Joshi P H, "Jigs and Fixtures", Tata McGraw Hill Publishing Company Limited, New Delhi 2004.				
E-REF	E-REFERENCES:				
1.	https://lecturenotes.in/subject/150/production-design-and-production-tooling-PDPT				

COURS Upon c	Bloom Taxonomy Mapped		
CO1	Identify the various cutting tools for different machining processes.	Evaluate	
CO2	Select suitable tools for metal machining.	Apply	
СОЗ	Identify suitable fixtures for various components.	Apply	
CO4	Ability to design jigs for machining components.	Create	
CO5	Design jigs, fixtures for press tools.	Create	

COURSE ARTICULATION MATRIX															
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1											1	1	
CO2		1											1	1	
CO3		1	2										1	1	
CO4	1	2	3										1	2	
CO5	1	1	1	3											
Avg	1.3	1.2	2	3									1	1	
	1	1	3/2/1	– indi	cates s	trengt	th of co	rrelati	ion (3 –	High, 2	Mediur	n, 1- Lov	v)		

22MEPE62	SEM	VIII						
PREREQU	PE Cre		edit	3				
			L	Т	P	ТН		
	Hours/Week	3	0	0	3			
COURSE	OBJECTIVES:					.1		
1. Outli	1. Outline the fundamentals of system simulation							
2. Ident	2. Identify the different types of techniques to generate Random numbers							
3. Outli	ne random number and variate generation.							
4. The a	4. The ability to analyze a system and to make use of the information to improve the performance							
5. Outli	ne the fundamentals of system simulation							
UNIT I	INTRODUCTION		9	0	0	9		
UNIT II	Types of system study. UNIT II MATHEMATICAL AND STATISTICAL MODELS 9 0 0							
Probability of	oncepts, Queuing Models, Methods for generating random variables	and Validation of ra	ndom	numb	ers.			
UNIT III	UNIT III DESIGN OF SIMULATION EXPERIMENTS					9		
	mulation, data collection and reduction, time flow mechanism, k n size, experimental design consideration, output analysis and interpr		flow o	chart,	start	ing		
UNIT IV SIMULATION LANGUAGES				0	0	9		
Input modeling: data collection, identifying the distribution with data, parameter estimation, goodness of fit test, fitting a non-stationary Poisson process, selecting input models without data, multivariate and time series input models. Verification and validation of simulation models, model building, verification and validation, verification of simulation models, calibration and validation of models.								
UNIT V	T V CASE STUDIES							
Development of simulation models using simulation language studied for systems like queuing systems, Production systems, Inventory systems, maintenance and replacement systems and Investment analysis.								
		Total	(45T)	– 451	Pario	vqe		

TEXT	TEXT BOOKS:				
1.	Geoffrey Gordon, "System Simulation", 2nd Edition, Prentice Hall, India, 2002.				
2.	Narsingh Deo, "System Simulation with Digital Computer, "Prentice Hall, India, 2001.				
REFE	RENCES:				
1	Jerry Banks and John S.Carson, Barry L. Nelson, David M.Nicol, "Discrete Event System Simulation", 3rd Edition, Prentice Hall, India, 2002.				
2	Thomas J. Schriber, Simulation using GPSS, John Wiley, 1991.				
3	Shannon, R.E. Systems simulation, The art and science, Prentice Hall, 1975.				
4	Averill M. Law and W. David Kelton, "Simulation modeling and analysis", McGraw·HiII, Inc, 1991.				
E-REF	E-REFERENCES:				
1.	https://www.cs.nmt.edu/~jholten/ModelingAndSimulation/lectures.html				
2.	https://lecturenotes.in/subject/383/simulation-and-modelling-sm				
3.	https://backbencher.club/system-modelling-and-simulation/				

	COUTCOMES: colletion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Modeling any given system with rationality.	Create
CO2	Predicting the behavior through fine grained analysis.	Create
CO3	Simulate the life cycle analysis, and drives over issues like model verification and validation.	Evaluate
CO4	Design simulation models for various case studies like inventory, traffic flow networks, etc.,	Design
CO5	Practice on simulation tools and impart knowledge on building simulation systems.	Apply

COURSE A	OURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	1	1									1	1	
CO2	1	2	1										1	1	
CO3	2	1	1	1									1	1	
CO4	2	2	1											1	
CO5	1	1	1		3								1	2	
Avg	1.6	1.4	1	1	3								1	1.2	
	•	•	3/2/1	– indi	cates s	trengt	h of co	rrelati	on (3 – I	High, 2- N	Medium,	1- Low)			

22M	EPE63	ENTREPRENEURSHIP DEVELOPMEN	Т	SEN	1EST	ER	VIII
PRE	REQUI	SITES	CATEGORY	PE	Cro	edit	3
1.Bas	ic knowl	edge in business strategies and ideas	TT /XX/ I -	L	T	P	TH
2.Cur	rent and	existing business growth status in our country	Hours/Week	3	0	0	3
COUI	RSE OB	JECTIVES:					
1.	Unders	tanding the business management and fundamental concepts of Ent	repreneurship				
2.	Learnir	ng about business idea generation and converting the idea into a bus	iness model.				
3.	Unders	tanding the role of government and the machinery that renders supp	port in terms of polic	ies, as	sistan	ces et	tc.
4.	Discuss	sing various information about the process, procedure and rules and	regulations for setting	ng up	new p	rojec	ts.
5.		ing knowledge and information about the sources of help, incentive ag up new projects	s and subsidies avail	able fr	om go	overn	ment
UN	IT I		9	0	0	9	
UN Defin		SMALL ENTERPRISES AND OWNERSHIP STRUCTURE are careful tracteristics-objectives-opportunities and problems of small-scale	industries-Role of				
		relopment. Project identification and selection-project formulat rnership structures-proprietorship-company-cooperative-selection of				g of	an
UNI	T III	FINANCING AND ACCOUNTING		9	0	0	9
entre small	preneurs enterpr	inance to entrepreneurs –commercial banks and other financi - taxation benefits to small scale industry- Government policy for ises- need-meaning-objectives. Accounting process-journal-ledgincomplete records.	small scale enterpri	ises. A	ccou	nting	for
UNI	T IV	ENTREPRENEURSHIP MANAGEMENT		9	0	0	9
admi	nistration	of management process - meaning - characteristics scope-function. Working capital management, Inventory management, production and human resource management					
UN	IT V	ENTREPRENEURSHIP DEVELOPMENT		9	0	0	9
		gies in small business- sickness in small business-small enterpr d procedure for small enterprises-Electronic commerce and small en			ness -	- exp	ort
			Total (4	15L) =	= 45]	Perio	ods

TEXT I	BOOKS:						
1.	S.S.Khanka "Entrepreneurial Development", S.Chand and Co. Ltd, 1999.						
2.	Essentials of Entrepreneurship and Small Business management (5/ed.): Thomas W. Zimmerer, and Norman M.Scarborough. PHI						
REFE	REFERENCES:						
1	EDII, "Faulty and External Experts – A Hand Book for New Entrepreneurs Publishers. Entrepreneurship Development", Institute of India, Ahmadabad, 1986.						
2	Athore B. S and Saini J. S, "A Handbook of Entrepreneurship", Aapga Publications, 2004.						
3	Rabindra N. Kanungo, "Entrepreneurship and Innovation", Sage Publications, New Delhi, 1998.						
4	Gupta CB and Srinivasan P, "Entrepreneurship Development" Sultan Chand & Sons, New Delhi, 2005						
5	Hisrich. R. D and Peters M. P, "Entrepreneurship", 5th Edition, Tata McGraw Hill, 2002						

E-REFERENCES:

1. https://nptel.ac.in/courses

	E OUTCOMES: mpletion of this course, the students will be able to:	Bloom Taxonomy Mapped			
CO1	Describe the types of entrepreneurships and their development and growth.				
CO2	Identify and select an appropriate project formation for any type of small enterprise.	Apply			
СОЗ	Recognize various financial institutions and adapt the existing government policies for the growth of small-scale enterprises.	Remember			
CO4	Illustrate various fields of entrepreneurship management and their functions.	Understand			
CO5	Elaborate the steps of development processes for the small-scale industries.	Understand			

COURSE A	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1			1	1		1	1						1	1	1
CO2		3							1		1	1	1	1	1
CO3									1		3		1	1	2
CO4			1				1								2
CO5						1	1			1			1	1	1
Avg		3	1	1		1	1		1	1	2	1	1	1	1.4
	•		3/2/1 -	- indic	ates s	trengt	h of c	orrelat	ion (3	– High,	2- Med	ium, 1-	Low)		

22M	EPE64	INDUSTRIAL SAFETY		SEM	EST	ER V	/III
PRE	REQUI	SITES	CATEGORY	PE	Cre	edit	3
1.Ind	ustrial E	ngineering	**	L	Т	P	ТН
2.Po	wer Plant	Engineering	Hours/Week	3	0	0	3
COU	RSE OI	BJECTIVES:				1	
1.	To und	erstand the safety norms and inspection procedures to create risk fro	ee working environr	nent.			
2.	To app	ly adequate machine guarding to eliminate the hazards from flying	chips and sparks and	d movii	ng par	ts.	
3.		ly the safety concepts in welding, gas cutting, storage and handling or working.	of gas cylinders, met	tal forn	ning p	roces	ses
4.	To pred of meta	lict, identify and evaluate, hazardous conditions and practices safety als.	rules in in cold work	king an	d hot	work	ing
5.		ploy the safety rules in inspection and testing processes and take process' aspects in engineering industry.	eventive measures i	in healt	h and	welf	are
UNI	ΤΙ		9	0	0	9	
UNI	T II nine Guar	PRINCIPLES OF MACHINE GUARDING ding, guarding of hazards, Machine Guarding types and its applica Manual and Mechanical material handling, Safety in use of elec					
	nition, Po	licy for ZMS - guarding of hazards - point of operation protective					
UNI	T III	SAFETY IN WELDING AND GAS CUTTING		9	0	0	9
prote distri	ctive equ bution ar	s welding and oxygen cutting, resistance welding, arc welding ipment-safety precautions in brazing, soldering and metalizing - I and handling of industrial gases- colour coding - flashback arrestor - I as cylinders.	Explosive welding-	safety	in gei	nerati	on,
UNI	T IV	SAFETY IN COLD FORMING AND HOT WORKING	OF METALS	9	0	0	9
or fo	ot-operat	Power presses-point of operation safe guarding-auxiliary mechanism ed presses, power press electric controls. Hot working: Safety in rolling mills - hot bending of pipes, hazards and control measures. ns.	forging, hot rolling	mill c	perati	ion, s	afe
UNI	TV	SAFETY IN FINISHING, INSPECTION AND TESTING	3	9	0	0	9
dyna radio	mic balar graphy, p	treatment operations: Electro plating, paint shops, sand and shotb neing, hydrotesting, valves, boiler drums and headers, pressure vess personal monitoring devices, radiation hazards, Indian Boilers Reg dustry-pollution control in engineering industry.	els, air leak test, ste	eam tes	ting, s	safety	in in

Total (45L) = 45 Periods

TEXT B	OOKS:								
1.	Andrew Furness, Martin Muckett, "Introduction to Fire Safety Management", Butterworth-Heinemann, 2007.								
2.	C.Rayasfahl, David W.Rieske, "Industrial Safety and Health Management", Pearson, 2009.								
3.	Philip Hagan "Accident Prevention Manual for Business and Industry", National Safety Council, Chicago, 13th edition 2009.								
REFE	REFERENCES:								
1	Peter Warren, "Handbook of Hazardous Chemicals Properties", Butterworth-Heinemann, 1997.								

2	Louis Theodore, Ryan Dupont, "Environmental Health and Hazard Risk Assessment: Principles and Calculations", CRC Press, 2012.								
3	John V.Grimaldi and Rollin H.Simonds, "Safety Management", Richard D Irwin, 1994.								
4	Krishnan N.V. "Safety Management in Industry" Jaico Publishing House, Bombay, 1997.								
5	Charles D.Reese, "Industrial Safety and Health for People- Oriented Services". CRC Press, 2009.								
E-REF	E-REFERENCES:								
1.	NPTEL courses: http://nptel.iitm.ac.in/courses.php - web and video sources on Industrial Safety.								

	RSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Understand the safety norms and inspection procedures to create risk free working environment.	Understand
CO2	Apply adequate machine guarding to eliminate the hazards from flying chips and sparks and moving parts.	Apply
CO3	Apply the safety concepts in welding, gas cutting, storage and handling of gas cylinders, metal forming processes for safe working.	Apply
CO4	Predict, identify and evaluate, hazardous conditions and practices safety rules in in cold working and hot working of metals.	Evaluate
CO5	Employ the safety rules in inspection and testing processes and take preventive measures in health and welfare of workers' aspects in engineering industry.	Evaluate

COURSE A	ARTI	CULA	TIO	N MA	TRIX	<u> </u>									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	0			2	3			1				2	2	1
CO2	3	1	1			2	2	1					2	2	1
CO3	2		1		2	2	2						2	2	1
CO4	2	1	1			2							2	2	1
CO5	2	1			2	2	2		1				2	2	1
Avg	2	1	1		2	2.2	2	1	1				2	2	1
		1	3/2/1	– indi	cates s	streng	th of c	orrelat	ion (3	– High,	2- Medi	um, 1- L	ow)		

22MI	EPE65	INTRODUCTION TO COMPUTATIONAL FLUID	DYNAMICS	SEM	EST	ER V	/III
PRE	REQUI	SITES	CATEGORY	PE	Cro	edit	3
1. Fun	damental	knowledge in partial differential equations.	Hours/Week	L	T	P	TH
2. Cor	cepts of	laws of motion and fluid mechanics.	Hours/ week	3	0	0	3
COU	IRSE O	BJECTIVES:					
1.		tanding the major theories, approaches, and methodologies and praynamics.	ogramming techniqu	ies in	comp	ıtatio	nal
2.	Studyii	ng various fluid flow governing equations from the conservation law	vs of motion and flui	id mec	hanic	S.	
3.		ying rigorous and comprehensive treatment of numerical methods in ering applications.	n fluid flow and heat	transf	er pro	blems	in
4.		strating the computational methods, algorithms and applied be imate solution.	oundary conditions	that w	ill af	fect	the
5.	Buildir	ng up the skills in the actual implementation of CFD methods and co	odes to investigate th	ne resu	lts.		
UNI	ΤI	NAMICS	9	0	0	9	
	•	Philosophy of computational fluid dynamics, CFD as a design and Numerical Methods Programming fundamentals, simple coding technique.				CFD	in
UNIT II GOVERNING EQUATIONS OF FLUID FLOW AND HEAT TRANSFER							9
diver	gence of	quations of Fluid Dynamics: Models of the flow, The substantivelocity, The continuity equation, The momentum equation, The ebw, Euler equations for in viscid flow, Physical boundary conditions	nergy equation, Nav				
UNI	T III	PARTIAL DIFFERENTIAL EQUATIONS AND ITS N BEHAVIOUR	UMERICAL	9	0	0	9
captu	ring, Tingification	f the governing equations suited for CFD, Conservation form of me marching and space marching problems. Mathematical Beh- of quasi-linear partial differential equations, Methods of determiniar arabolic and Elliptic equations	avior of Partial Dif	ferenti	al Eq	uatio	ns:
UNI	T IV	DISCRETIZATION AND NUMERICAL METHODS	OF PDEs	9	0	0	9
and p Trans Stabi Grid	oolynomi sformatic lity analy	of Discretization: Introduction to finite differences, Finite differences als, Explicit and implicit approaches, uniform and unequally spaces. General transformation of the equations, Metrics and Jacobians. The sis, von Neumann Stability analysis, Error analysis, Modified equation: Algebraic Grid Generation, Elliptic Grid Generation, Hyperboom.	ced grid points. Grid Stability Analysis: I ons, Artificial dissip	ds With Discrett ation a	h App e Pert nd dis	ropri urbat persi	ate ion on;
UNI	UMERICS TO	9	0	0	9		
meth	ods – Las	cial Differential Equations: Finite difference formulations, Explicit sonen and Crank-Nicolson; Finite Volume Method for Structured a Nodal point Approaches, Numerical Solution of Quasi 1D Flow equ	nd Unstructured Grid	ds: Ad	vantaş	ges, C	Cell
			Tota	al (451	L) = 4	5 Pe	riod
TEX	T BOO	KS					
1	An	derson, J.D. (Jr), "Computational Fluid Dynamics", McGraw-Hill l	Book Company, 1st 1	Edition	ı. 199	5.	_

TEXT I	BOOKS
1.	Anderson, J.D. (Jr), "Computational Fluid Dynamics", McGraw-Hill Book Company, 1st Edition, 1995.
2.	Hoffman, K.A., and Chiang, S.T., "Computational Fluid Dynamics", Vol. I, II and III, Engineering Education System, Kansas, USA, 2000.
REFER	ENCES:

1	Anderson, D.A., Tannehill, J.C., and Pletcher, R.H., "Computational Fluid Mechanics and Heat Transfer", McGraw Hill Book Company, 2002.
2	Chung, T.J., "Computational Fluid Dynamics", Cambridge University Press, 2003
3	Muralidhar K and Sundararajan, "Computational Fluid Flow & Heat Transfer", 2009.
E-REF	ERENCES:
1.	https://nptel.ac.in/courses/112105045

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:					
CO1	Summarize the basics of computational fluid dynamics and its applications in various industries as a tool for fluid analysis	Remember				
CO2	Select an appropriate finite difference approach for numerical formulations based on fluid mechanics and/or heat transfer concepts to get the approximate solutions.	Apply				
CO3	Develop the governing equations for computational fluid dynamics CFD analysis by setting appropriate boundary conditions.	Create				
CO4	Identify different CFD techniques available for relevant partial differential equations to get analytical solutions for fluid flow.	Understand				
CO5	Analyze the numerical solution of fluid flow problems using discretization methods addressing accuracy, stability and convergence aspects to minimize the errors.	Analyze				

COURSE A	ARTIO	CULA	TION	MAT	RIX										
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO:
CO1	1			1			1								
CO2			1				1								
CO3	1	1	1			1	1	1							
CO4	2	2			1			1					2	2	1
CO5	2	1						2					2	2	1
Avg	1.5	1.7	1	1	1	1	1	1.7					2	2	1
		3/2/	1 – ind	icates	strength	of cor	relatio	n (3 –	High, 2	2- Mediu	ım, 1- L	ow)			•

22MI	EPE66	MARINE ENGINEERING		SEM	EST	ER V	/III	
PRE	REQUI	SITES	CATEGORY	PE	Cro	edit	3	
1. Int	ernal Co	mbustion Engines		L	Т	P	ТН	
2.Flu	id Mecha	nics and Machinery	Hours/Week	3 0 0				
COU	JRSE O	BJECTIVES:		ı	I			
1.	To und	lerstand the basic principles of Marine Engineering						
2.	To und	lerstand the naval architects and the fields related to the maritime indus	stry					
3.	To ana	lyze the vibrations in various equipment used in marine engineering						
4.	To und	lerstand various electrical systems and environmental control and safet	y in marine engi	neering				
5.	To und	lerstand the nuclear applications in marine engineering						
UN	IT I	INTRODUCTION		9	0	0	9	
		of marine Engineering - Ship system formulations-main propulsion system for studies, Arrangement of machinery-piping diagrams and auxiliary		and m	ain pr	opuls	ion	
UN	IT II	ENGINES AND PROPULSION		9	0	0	9	
		s of internal combustion engines - marine uses for such engines. Ma ers. Main propulsion systems-steam engines, steam turbines, gas turbin					and	
UNI	III TIII	VIBRATIONS ANALYSIS		9	0	0	9	
exch	angers, d	fting and shafting system vibration analysis - Pumps, blowers, cor istilling plants. Hull machinery design considerations and machinery ostatic power transmission equipment and systems.						
UNI	IT IV	POWER DISTRIBUTION		9	0	0	9	
Elect	ronics na	rating plants- switchboards and panels-lighting and power distribution avigation and radio communication-automation systems- safety consideraste treatment.						
UN	IT V	NUCLEAR APPLICATION		9	0	0	9	
		of pressurized-water nuclear steam supply systems for use in s- Nuclear fuels, reactor coolants, reactor control, shielding, safety, hea				des	ign	
							riod	

TEXT B	OOKS:
1.	Grover T K, "Marine Engineering", Anmol Publications Pvt Ltd, 2008.
2.	Harrington and Roy, L, "Marine Engineering", The Society of Naval Architects and Marine Engineers, 1991.
3.	D.A.Taylor, "Introduction to Marine Engineering", Butterworth Heinmann, 1996.
REFEI	RENCES:
1	Cameron, I.R., "Nuclear Fission Reactors", Plenum Press, 1998.
2	Henke and Russell, W., "Introduction to Fluid Power Circuits and Systems", Addison-Wesley, 1970.
3	John W.Gaythwaite, "Design of Marine Facilities: Engineering for Port and Harbour Structures", American Society of Civil Engineers, 2016.
4	Doug Woodyard, "Pounder's Marine Diesel Engines and Gas Turbines", Elsevier Ltd, 2009.
5	Kuwahara, Takuya, "New Technologies for Emission Control in Marine Diesel Engines", Elsevier Science & Technology, 2019.
E-REF	ERENCES:
1.	NPTEL courses: http://nptel.iitm.ac.in/courses.php - web and video sources on Marine Engineering.

	SE OUTCOMES: ompletion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Understand the basic principles of marine engineering.	Understand
CO2	Understand the naval architects and the fields related to the maritime industry.	Understand
CO3	Analyze the vibrations in various equipment used in marine engineering.	Analyze
CO4	Understand various electrical systems and environmental control and safety in marine engineering.	Understand
CO5	Understand the nuclear applications in marine engineering.	Understand

COURSE A	ARTI	CULA	TIO	N MA	TRIX	ζ									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1	1	1									2	2	1
CO2	2	1	1	1	1								2	2	1
CO3	2	2	3	1	1								2	2	1
CO4	2		3			3	2			2		1	2	2	1
CO5	1	1	2	1		3	2			1			2	2	1
Avg	2.0	1.25	2.0	1	1	3	2			1.5		1	2.0	2.0	1.0
			3/2	/1 – in	dicate	s stre	ngth o	f corre	lation	(3 – Hig	h, 2- Me	dium, 1	· Low)		

PRE	EPE67	ROBOTICS		SEM	1EST	ER	VIII
	REQUI	SITES CA	TEGORY	PE	Cre	edit	3
			Hours/Week		Т	P	TH
		H	ours/ Week	3	0	0	3
COU	JRSE O	BJECTIVES:			•		
1.	To exp	olore concepts of Robot technologies that is playing vital role in manufact	ure.				
2.	Descri	be various Robot technology applications.					
3.	Develo	op an understanding of Robot Kinematics and dynamics.					
4.	Explai	n and summarize Robot end effectors and Sensors.					
5.	Explor	e conceptual understanding of robot programming.					
UNI	ΤΙ	FUNDAMENTALS OF ROBOT		9	0	0	9
end e	ffectors -	aulic, pneumatic, mechanical, and electrical - servo motors - stepper motors - types: tools - grippers - mechanical grippers - pneumatic and hydraulic grippers.					
UNI	T III	SENSORS AND MACHINE VISION		9	0	0	9
	citive, ul lvers, op	of sensors – principles, types and applications of following types of sensor				posit	
(reso	n -runcu	trasonic and optical) – range (Triangulation, structured light approactical encoders, pneumatic) – force – torque – touch sensors (binary, analogous - image processing and analysis.		roducti	on to	шасп	
(resol	T IV	tical encoders, pneumatic) – force – torque – touch sensors (binary, analogous)		roducti 9	on to	0	
vision UNI Forw homo progr	T IV rard kine ogeneous ramming	tical encoders, pneumatic) – force – torque – touch sensors (binary, analogous - image processing and analysis.	og sensor) - int of freedom (9 in 2 d ing lan	0 imens	0 sional es - V	9) – AL
(resolvision VINI' Forw homo	T IV rard kine ogeneous ramming oalletizin	rical encoders, pneumatic) – force – torque – touch sensors (binary, analogous - image processing and analysis. ROBOT KINEMATICS AND ROBOT PROGRAMMING rematics and reverse kinematics of manipulators - two, three degrees transformation matrix - simple problems - lead through programming, ro—motion commands - sensor commands - end effecter commands - simple problems - lead through programming, ro—motion commands - sensor commands - end effecter commands - simple problems - lead through programming, ro—motion commands - sensor commands - end effecter commands - simple problems - lead through programming, ro—motion commands - sensor commands - end effecter commands - simple problems - lead through programming, ro—motion commands - sensor commands - end effecter commands - simple problems - lead through programming - motion commands - simple problems - lead through programming - motion commands - simple problems - lead through programming - motion commands - simple problems - lead through programming - motion commands - simple problems - lead through programming - motion commands - simple problems - lead through programming - motion commands - simple problems - lead through programming - motion commands - simple problems - lead through programming - motion commands - simple problems - lead through programming - motion commands - simple problems - lead through programming - motion commands - simple problems - lead through programming - motion commands - simple problems - lead through programming - motion commands - simple problems - lead through programming - motion commands - simple problems - lead through programming - motion commands - simple problems - lead through programming - motion commands - simple problems - lead through - motion commands - simple problems - lead through - motion commands - simple problems - lead through - motion commands - simple problems - lead through - motion commands - simple problems - lead through - motion - mo	of freedom (bot programs fo	9 in 2 d ing lan	0 imens	0 sional es - V	9) – AL

TEXT B	OOKS:						
1.	M.P.Groover, "Industrial Robotics – Technology, Programming and Applications", McGraw-Hill, 2001						
2.	Fu.K.S. Gonzalz.R.C., and Lee C.S.G., "Robotics Control, Sensing, Vision and Intelligence", Mc Graw Hill Book Co.,1987						
REFER	REFERENCES:						
1	Richard D.Klafter, Thomas A.Chmielewski and Micheal Negin, "Robotic engineering –An Integrated Approach", Prentice Hall Inc, Englewoods Cliffs, NJ, USA, 2005.						
2	Janakiraman.P.A. "Robotics and Image Processing", Tata McGraw-Hill, 1995.						
3	Yoram Koren, "Robotics for Engineers", McGraw-Hill Book Co., 1992.						
4	A.K.Gupta and S.K.Arora, "Industrial Automation and Robotics", Laxmi Publications Pvt ltd, 2007.						
E-REFI	E-REFERENCES:						

1	NPTEL	Vidage	Tutoriole
1.	NPIEL	v ideos/	Tutoriais

COURSE OUTCOMES: Upon completion of this course, the students will be able to:			
CO1	Describe the basic concepts, parts of robots and types of robots.	Understand	
CO2	Know the potential applications of robots in industries as part of automation tool.	Understand	
СОЗ	Familiar with the various drive systems for robot, sensors and their applications in robots, programming of robots.	Remember	
CO4	Discuss about the various applications of robots, justification, implementation and safety of robot.	Analyze	
CO5	Select an appropriate robot for a particular application with economically.	Apply	

COURSE A	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	2	1	2		1				2		2	2	1
CO2	2	1	1	1		1	2	1			1		2	2	1
CO3	1	1	1	1		1	1	1			1		2	2	1
CO4	1	1	1	2	2	2	1				2		1	1	1
CO5	1	1	1	1	2	1	1				1		2	2	1
Avg	1.4	1	1.2	1.2	2	1.25	1.2	1			1.4		1.8	1.8	1
3/2/1 – indicates strength of correlation (3 – High, 2- Medium, 1- Low)															

OPEN ELECTIVE COURSES

PREREQUISTIES Basic 12 th level knowledge of Probability, Statistics, Matrices, ODE and PDE. Basic 12 th level knowledge of Probability, Statistics, Matrices, ODE and PDE. Course Objectives: 1. To gain the knowledge of tests of significance for large and small samples. 2. To find the numerical solution of linear, non-linear equations and to obtain the knowledge about fitting method of least squares. 3. To obtain the knowledge about numerical interpolation, differentiation and integration. 4. To acquire the knowledge about numerical solutions to first order ordinary differential equations using multi-step methods. 5. To gain the knowledge about numerical solutions to second order partial differential equations by using implicit methods. UNIT I SAMPLING THEORY 9 Test of significance: Large Sample tests for Single proportion, difference of proportions, single mean and difference of proportions, single mean and difference of proportions.	g singl		_
Course Objectives: 1. To gain the knowledge of tests of significance for large and small samples. 2. To find the numerical solution of linear, non-linear equations and to obtain the knowledge about fitting method of least squares. 3. To obtain the knowledge about numerical interpolation, differentiation and integration. 4. To acquire the knowledge about numerical solutions to first order ordinary differential equations using multi-step methods. 5. To gain the knowledge about numerical solutions to second order partial differential equations by u implicit methods. UNIT I SAMPLING THEORY 9	g of cur	rves b	y the
1. To gain the knowledge of tests of significance for large and small samples. 2. To find the numerical solution of linear, non-linear equations and to obtain the knowledge about fitting method of least squares. 3. To obtain the knowledge about numerical interpolation, differentiation and integration. 4. To acquire the knowledge about numerical solutions to first order ordinary differential equations using multi-step methods. 5. To gain the knowledge about numerical solutions to second order partial differential equations by unimplicit methods. 9. UNIT I SAMPLING THEORY	g singl		_
 To find the numerical solution of linear, non-linear equations and to obtain the knowledge about fitting method of least squares. To obtain the knowledge about numerical interpolation, differentiation and integration. To acquire the knowledge about numerical solutions to first order ordinary differential equations using multi-step methods. To gain the knowledge about numerical solutions to second order partial differential equations by u implicit methods. UNIT I SAMPLING THEORY 	g singl		_
method of least squares. 3. To obtain the knowledge about numerical interpolation, differentiation and integration. 4. To acquire the knowledge about numerical solutions to first order ordinary differential equations using multi-step methods. 5. To gain the knowledge about numerical solutions to second order partial differential equations by u implicit methods. 9. UNIT I SAMPLING THEORY	g singl		_
 To acquire the knowledge about numerical solutions to first order ordinary differential equations using multi-step methods. To gain the knowledge about numerical solutions to second order partial differential equations by unimplicit methods. UNIT I SAMPLING THEORY 		le step	1
multi-step methods. 5. To gain the knowledge about numerical solutions to second order partial differential equations by u implicit methods. UNIT I SAMPLING THEORY 9		le step	1
implicit methods. UNIT I SAMPLING THEORY 9	sing e		and
		xplici	t and
Tast of significance: Large Sample tasts for Single proportion, difference of proportions, single man and difference of proportions, single man and difference of proportions.	0	0	9
Small Sample test for single mean, difference of means, test for ratio of variances - Chi-square test for good independence of attributes.	odness	of fi	
UNIT II SOLUTION OF EQUATIONS Solutions of nonlinear equations by Newton Raphson Method-Solutions of linear system of equations by Ga	0	0	9
Gauss Jacobi and Gauss Seidel methods, Curve fitting by the Method of Least Squares – Fitting of straight line parabolas.			
UNIT III INTERPOLATION, NUMERICAL DIFFERENTIATION AND 9	0	0	9
Interpolation using Newton's Forward and Backward formula- Interpolation with unequal intervals: N difference and Lagrange's formula -Numerical Differentiation and Integration: Trapezoidal rule, Simpson's 3/8 rule.			
UNIT IV NUMERICAL SOLUTION FOR ORDINARY DIFFERENTIAL 9	0	0	9
Ordinary differential equations: Taylor series method- Euler and modified Euler's method- Runge-Kutta method for solving first order differential- Milne's and Adam's predictor - corrector methods.	od of fo	ourth	order
UNIT V NUMERICAL SOLUTION FOR PARTIAL DIFFERENTIAL 9	0	0	9
Partial differential equations: Finite difference solution of two-dimensional Laplace and Poisson equation Explicit methods for one dimensional heat equation (Bender Schmidt and Crank-Nicholson methods) - Finite dimethod for wave equation.			
Total (45 L + 01	(T) = 4	5 Per	iods
Toyt Dooks			
Text Books:			
1. Veerarajan T, "Probability and Random Process (With Queuing theory)", 4 th Edition, Tata McGrav Pvt. Ltd., New Delhi, 2016.	v Hill	Educ	ation
2. Kandasamy.P, Thilagavathy.K, Gunavathi.K, "Numerical Methods", S. Chand & Co., New Delhi, 20)05.		
3. Gupta, S.C. and Kapoor, V.K., "Fundamentals of Mathematical Statistics", S. Chand and Sons, New 11th Edition, 2014.	Delhi	,	

1.	Freund John, E. and Miller Irwin, "Probability and Statistics for Engineers", 8 th Edition, Prentice Hall India (P) Ltd, 2010.
2.	Gerald, C. F. and Wheatley, P.O., "Applied Numerical Analysis", Sixth Edition, Pearson Education Asia, New Delhi, 2002.
3.	M.K. Venkataraman, "Numerical Methods in Science and Engineering", 5 th Edition, National Publishing Company, 2000.
4.	Jain M.K, Iyengar K & Jain R.K., "Numerical Methods for Scientific and Engineering Computation", New Age International (P) Ltd, Publishers, 2003.
5.	Manish Goyal, "Numerical Methods and Statistical techniques Using 'C", 1st Edition, Laxmi Publications (P) Ltd, 2009.

		utcomes:	Bloom's Taxonomy
Upon c	omp	pletion of this course, the students will be able to:	Mapped
CO1	:	Learn about the concept of sampling theory and testing of hypotheses.	L2: Understanding
CO2		Find the numerical solution of equations and fitting the curves by Least Square	L2: Understanding
CO2	:	Method.	
CO3		Appreciate the numerical techniques of interpolation in various intervals and apply	L3: Applying
COS	•	the numerical techniques of differentiation and integration for engineering problems.	
CO4	:	Solve the initial value problems for ordinary differential equations.	L3: Applying
COS		Find the numerical solution of the partial differential equation by using the Finite	I 2. Undonstanding
CO5		difference method.	L2: Understanding

COUI	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2		2									2		
CO2	3	2		2									2		
CO3	3	2		2									2		
CO4	3	2		2									2		
CO5	3	2		2									2		
Avg	3	2	-	2	-	-	-	-	-	-	-	-	2	-	-
	3/2/1-indicates strength of correlation (3- High, 2-Medium, 1- Low)														

22M	AOE02	NUMERICAL METHODS					
	REQUIST		CATEGORY	L	T	P	C
	12 th level ki and PDE.	nowledge of solution of equations, differentiation, integration,	BS	3	0	0	3
Cour	se Objecti	ves:		1			
1.	To familiar	ize the numerical solution of the linear system of equations.					
2.	To understa	and the concept of interpolation and approximation.					
3.	To obtain t	he knowledge about numerical differentiation, integration.					
4.	To familian methods	rize the students on solving first order ordinary differential e	quations using singl	e step	and	multi	-step
5.	To enable t	hem to solve boundary value problems associated with engineer	ring applications usin	g nur	nerica	l metl	ods.
	ons of nonli	LUTION OF EQUATIONS near equations by Newton Raphson Method-Solutions of linear ass Jacobi and Gauss Seidel Methods.	system of equations l	9 by Ga	uss E	0 limina	9 ation,
TINITT	TI INT	EDDOLATION AND ADDROVIMATION		0	Ι.	Ι.	10
UNIT Interp		ERPOLATION AND APPROXIMATION Equal Intervals-Newton's Forward and Backward interpolat	ions- Unequal interv	als-N	0 ewtor	0 n's div	9 vided
		and Lagrangian Polynomials.	1				
TINIT	TIT NITI	MEDICAT DIEEEDENTIATION AND INTECDATIO	NNT	Δ	Δ	Δ	Δ.
UNIT Newto		MERICAL DIFFERENTIATION AND INTEGRATION and Backward Differences to compute derivatives-Trapezoid		9 3 rule	0 Sim	0 pson'	9 s 3/8
		ree-point Gaussian quadrature formulas.				1	
UNIT		TIAL VALUE PROBLEMS FOR ORDINARY I	DIFFERENTIAL	9	0	0	9
		ODE – Single step method: Taylor series method-Euler and m litistep method: Milne's and Adam's predictor and corrector me		l-Fou	rth or	der Ru	inge-
UNIT		UNDARY VALUE PROBLEMS IN ORDINARY FERENTIAL EQUATIONS	AND PARTIAL	9	0	0	9
	on by expli	olution of second order ordinary differential equations-Finite di cit and implicit methods-One dimensional wave equation a					
			Total (45 L	+ 0 T	() = 4	5 Per	riods
Text 1	Books:						
1.	2006.	n. T and Ramachandran, "Numerical methods with Programs in				New I	Delhi,
	Kandacar				2005		
2.	Kandasai	ny.P, Thilagavathy.K, Gunavathi.K, "Numerical Methods", S. C	Chand & Co., New Do	elhi, 2	2005.		
	ence Book	s:					
Refer	Gerald, C 2002.	s: . F. and Wheatley, P.O.," Applied Numerical Analysis", Sixth Ed	dition, Pearson Educa	ıtion 1	Asia, N		
Refer	Gerald, C 2002. M.K. Ver 2000.	s: F. and Wheatley, P.O.," Applied Numerical Analysis", Sixth Edukataraman, "Numerical Methods in Science and Engineering",	dition, Pearson Educa 5 th Edition, National	tion 2	Asia, N	Com	oany,
Refer	Gerald, C 2002. M.K. Ver 2000. Jain M.K Internation	s: . F. and Wheatley, P.O.," Applied Numerical Analysis", Sixth Ed	dition, Pearson Educa 5th Edition, National and Engineering Cor	ution 2 Publi	Asia, Nashing	Comp	pany,

		oletion of this course, the students will be able to:	Bloom's Taxonomy Mapped			
CO1	:	L2: Understanding				
CO2	:	Acquired the techniques of interpolation and approximations.	L2: Understanding			
CO3	:	Familiarize with numerical differentiation and integration.	L2: Understanding			
CO4	:	Solve the initial value problems for ordinary differential equations.	L3: Applying			
CO5	:	Acquire the techniques of solving Boundary value problems.	L2: Understanding			

COUL	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2		2									2		
CO2	3	2		2									2		
CO3	3	2		2									2		
CO4	3	2		2									2		
CO5	3	2		2									2		
Avg	3	2	-	2	-	-	-	-	-	-	-	-	2	-	-
	3/2/1-indicates strength of correlation (3- High, 2-Medium, 1- Low)														

	MAOE03			PROB A	ABILITY A	ND QUEU	ING THE	ORY				
PRE	REQUIS'	TIES						CATEGORY	L	T	P	С
Basic	2 12 th level	knowledge	of Prob	ability and	Statistics.			BS	3	0	0	3
Cou	rse Objec	tives:										
1.						onal random of fe phenomen		d to introduce s	ome stand	dard d	istribu	tions
2.	To under	stand the o	concept o	f two-dim	ensional rand	lom variables	, Correlation	and linear regre	ssion.			
3.		de necessa cation eng			in random p	rocesses for a	applications	such as random	signals,	linear	systen	ns in
4.	To under	stand the o	concept o	f queueing	g models and	apply in engi	neering.					
5.				nce of adv engineering		ing models a	nd develop	probabilistic mo	dels whic	h can	be us	ed in
UNI		ANDOM							9	0	0	9
	rete and co				- Moments	- Moment	generating 1	functions – Bin	omial, P	oisson	, Unit	orm,
UNI	T II T	WO - DI	MENSI	ONAL R	ANDOM V	ARIABLES	$\overline{\mathbf{S}}$		9	0	0	9
	ndom varial		mar and	Conditiona	r distribution.	s – Covarianc	c – Correlat	ion and linear re	gression	– IIan	18101111	ation
		ANDOM							9	0	0	9
Class		Stationar			ov process -	Poisson prod	cess – Discr	rete parameter l		_	_	
Class Koln	rification – rigorov equ	Stationar nations . UEUEIN	y proces G MOI	s – Marko DELS				-	Markov c	hain -	- Chap	oman 9
Class Kolm UNI Mark	rification – rigorov equ	Stationar nations . UEUEIN es – Birth	y proces G MOI	s – Marko DELS				rete parameter l	Markov c	hain -	- Chap	oman 9
Class Kolm UNI Mark finite	rification – nogorov equence T IV Quence covian queue waiting roce	Stationar nations . UEUEIN es — Birth oms.	G MOI and dear	S – Marko DELS th processor	es – Single ar	nd multiple se		-	Markov c	hain –	Oueues	9 with
Class Kolm UNI Mark finite UNI Finite	TIV QUE to vian queue waiting room of the course more than the course more than the course was a course more than the course more than	Stationar nations . UEUEIN es — Birth oms. DVANCI dels - M/O	G MOI and dear	DELS th processor	es – Single ar	nd multiple se	erver queuein	-	Markov c	0	Oueues 0	9 with
Class Kolm UNI Mark finite UNI Finite	TIV QUE to waiting room	Stationar nations . UEUEIN es — Birth oms. DVANCI dels - M/O	G MOI and dear	DELS th processor	es – Single ar	nd multiple se	erver queuein	ng models – Litt	Markov c	0	Oueues 0	9 with
UNI Mark finite UNI Finite	TIV QUE to vian queue waiting room of the course more than the course more than the course was a course more than the course more than	Stationar nations . UEUEIN es — Birth oms. DVANCI dels - M/O	G MOI and dear	DELS th processor	es – Single ar	nd multiple se	erver queuein	ng models – Litt	Markov c 9 e's form 9 ase – Seri	hain - 0 ula - Q 0 es que	Oueues Oueues	9 with
Class Koln UNI Mark finite UNI Finite Jacks	TIV QUE to vian queue waiting room of the course more than the course more than the course was a course more than the course more than	Stationar nations . UEUEIN es — Birth oms. DVANCI dels - M/O	G MOI and dear	DELS th processor	es – Single ar	nd multiple se	erver queuein	ng models – Litt	Markov c 9 e's form 9 ase – Seri	hain - 0 ula - Q 0 es que	Oueues Oueues	9 with
Class Koln UNI Mark finite UNI Finite Jacks	T V QUE to vian queue waiting room on network to Books:	Stationar nations . UEUEIN es – Birth oms. DVANCI dels - M/C.s.	G MOI and dear	DELS h processo EUEING e – Pollacz	es – Single ar MODELS ek Khinchin	nd multiple se	erver queueii	ng models – Litt	Aarkov c 9 e's form 9 ase – Seri	hain - $\begin{array}{ c c } \hline 0 \\ \hline 0 \\ \hline 0 \\ \end{array}$ es que	Oueues Oueues Francisco	9 with 9 Open
UNI Mark finite UNI Finite Jacks	T V QUE to vian queue waiting room network Books: Gross, Edition	Stationar nations . UEUEIN es — Birth oms. DVANCI dels - M/C ss. D., Shortl , 2014.	G MOI and dear ED QUI 6/1 queue	DELS h processo EUEING e – Pollacz	MODELS Tek Khinchin J.M and Har	formula - M/l	D/1 and M/E	ng models – Litt	Aarkov c 9 e's formu 9 ase – Seri	hain - $\begin{array}{ c c } \hline 0 \\ \hline 0 \\ \hline 0 \\ \hline 0 \\ \text{es que} \end{array}$ Viley,	Oueues Oueues Studen	9 with 9 Open
UNI Mark finite UNI Finite Jacks Text 1.	T V QUE to vian queue waiting room network Books: Gross, Edition	Stationar nations . UEUEIN es — Birth oms. DVANCI dels - M/C s. D., Shortl , 2014. C., "Funda	G MOI and dear ED QUI 6/1 queue	DELS h processo EUEING e – Pollacz	MODELS Tek Khinchin J.M and Har	formula - M/l	D/1 and M/E	ng models – Litt Total (4 of Queueing T	Aarkov c 9 e's formu 9 ase – Seri	hain - $\begin{array}{ c c } \hline 0 \\ \hline 0 \\ \hline 0 \\ \hline 0 \\ \text{es que} \end{array}$ Viley,	Oueues Oueues Studen	9 with 9 Open
UNI Finite Jacks Text 1. 2. Refe	T IV QUE to vian queue waiting root on networks a Books: Gross, Edition Ibe, O.0 Hwei H Tata M	Stationar nations . UEUEIN es — Birth oms. DVANCI dels - M/C s.s. D., Shortl , 2014. C., "Funda oks: Isu, "Scha cGraw Hill	G MOI and dear ED QUI G/1 queue	DELS h processo e Pollacz hompson, of Applied	MODELS Lek Khinchin J.M and Har I Probability heory and Prhi, 2004.	formula - M/l	D/1 and M/E undamentals Processes", I	Total (4 Total (4 Total (4) Total (4)	Aarkov c 9 e's form 9 use – Seri 5 L + 0' neory", V an Reprin	hain - hain - 0 ula - Q o es que Γ) = 4	Oueues Oueues Studen	y with 9 Open iods
UNI Mark finite UNI Finite Jacks Text 1. 2.	T IV QI tovian queue waiting roc T V AI e source motors on network Books: Gross, Edition Ibe, O.6 Frence Book Tata M Taha, F Trivedi	D., Shortl, 2014. C., "Funda CGraw Hill.A., "Ope, K.S., "	G MOI and dear ED QUI 6/1 queue	DELS h processo EUEING e – Pollacz nompson, of Applied ttline of T , New Del desearch",	MODELS The Single are MODELS The Khinchin J.M and Hare Heropean Are Probability The Heory and Prob	formula - M/I	D/1 and M/E undamentals Processes", 1 obability, Ra	ng models – Litt Total (4 of Queueing T Elsevier, 1st Ind	Aarkov c 9 e's formu 9 ase – Seri 5 L + 0' an Reprii	hain - hain - 0 ula - Q es que Γ) = 4 Viley, adom 1	Oueues Oueues Studen 7.	y with 9 9 Open iiods

		putcomes: pletion of this course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	:	Understand the fundamental knowledge of the standard distributions which can describe real life phenomenon.	L2: Understanding
CO2	:	Understand the concepts of two-dimensional random variables, Correlation and linear regression.	L2: Understanding
CO3	:	Apply the concept of random processes in engineering disciplines.	L3: Applying
CO4	:	Acquire skills in analysing queueing models.	L2: Understanding
CO5	:	Understand and characterize phenomenon which evolve with respect to time in a probabilistic manner.	L2: Understanding

COUL	RSE A	RTICU	ULATI	ION M	IATRI	X									
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2		2									2		
CO2	3	2		2									2		
CO3	3	2		2									2		
CO4	3	2		2									2		
CO5	3	2		2									2		
Avg	3	2	-	2	-	-	-	-	-	-	-	-	2	-	-
	3/2/1-indicates strength of correlation (3- High, 2-Medium, 1- Low)														

22C	EOE01	ENVIRONMENTAL MANAGEMI	ENT	S	emeste	er	VI
PRI	EREQUISI	TES	Category	OE		edit	3
NIL	,		Hours/Week	3	T 0	P 0	TH 3
Cou	rse Learnii	ng Objectives					
1	societic life		•	portanc	e associ	iated w	ith our
2		ne variable categories of pollutants and their controlling me		100.1	1000	1	1 .
3		an understanding of systems approach to Environmental ement plan using gis tools	Management as per	r 150 i	.4000 a	na to ev	aiuate
4		skills for environmental performance in terms of legal	compliance, pollution	on prev	ention	and co	ntinual
5	To impart s system.	skills for managing the usage of our natural resources with		•		ı	
	Unit I	ENVIRONMENTAL RESOURC	ES	9	0	0	9
dams pract resou	s-benefits an tices, land use urces- Timbe	esources-Mineral use and exploitation; fossil fuels. Renewed problems; Soil and Land resources- Structure, formate, degradation and desertification; Fisheries- Inland and mater, Medicinal plants, fuel-wood, deforestation, forest maters; Sustainable use	ation, erosion, conse arine fisheries, aquacu	ervation ulture, o	of soi	l, agric	ultural Forest
ı	U nit II	ENVIRONMENTAL POLLUTION	ON	9	0	0	9
of po	ollution and c	ution and pollutants; types of pollution-Air, Water ,Soil, Nontrol measures; Liquid and Solid waste management, nuclear power plants					
τ	Jnit III	ENVIRONMENTAL MANAGEMENT	SYSTEM	9	0	0	9
Envi cycle		Anagement Systems; ISO14000 series; Environmental a lent; Human health risk assessment. Management plans us			act Ass	essmen	t; Life
Ţ	J nit IV	ENVIRONMENTAL LAW AND PO	DLICY	9	0	0	9
amei	ndments; The	aw and Policy – Objectives; Polluter pays principle, Prece e Environment (Protection) Act (EPA) 1986; National C s of International Law and International treaties.					
1	U nit V	ENERGY-ENVIRONMENT AND SUST DEVELOPMENT	AINABLE	9	0	0	9
Ener	gy-Environn	onment: Energy sources – overview of resources and reservent nexus Sustainable Development: Definition and cols; Hurdles to sustainability; Environment and economics.	oncepts of sustainabl				
					Total:	= 45 P	eriods
Te	xt Books:						
1	"Natural R	esources Conservation & Management", K.K.SINGH -M	D PUBLICATIONS	PVT L	ΓD		
2	"Environm	nental Pollution " by N.MANIVASAKAM,2021					
3		/14004: Environmental management systems – Requirem rdisation, 2004.	ents and Guidelines	– Intern	ational	Organi	sation
4		tal Concepts in Environmental Studies by Dr.D.D Mishra					
	erence Bool						
1		2002, "Guidelines for quality and/or Environmental New Delhi, 2002.	Management System	auditing	g, Bure	au of I	ndian
2	·	op "Pollution Prevention: Fundamentals and Practice", Mo	cGraw -Hill Internati	ional, B	oston,2	000.	

- Environmental Management Systems: An Implementation Guide for Small and Medium-Sized Organizations, Second Edition, NSF International, Ann Arbor, Michigan, January 2001
- Christopher Sheldon and Mark Yoxon, "Installing Environmental management Systems –a step by step guide" Earthscan Publications Ltd, London, 1999.

	se Outcomes: completion of this course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Understand the importance of variable natural resources	Understand
CO2	Understand the necessity of environmental management that will be caused by projects or industries.	Understand
CO3	Develop, Implement, maintain and Audit Environmental Management systems for Organizations.	Understand /Evaluate
CO4	Gain the Knowledge about the legal requirements of Environmental management and auditing	Remembering
CO5	Understand eco-friendly business in order to achieve sustainable development	Understand

COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	-	1	2	-	-	3	1	1	1	-	1	3	3	-	2
CO2	-	1	3	-	-	3	1	1	1	-	1	3	3	-	2
СОЗ	1	1	1	2	2	3	1	-	2	2	3	2	3	-	3
CO4	-	1	1	-	-	3	1	1	2	2	1	2	1	-	2
CO5	1	1	3	2	1	3	3	-	2	-	3	3	3	-	2
Avg	1	1	2	2	0.6	3	1.4	0.6	1.6	2	1.8	2.6	2.6	-	2.2
	3/2/1 – indicates strength of correlation (3- High, 2- Medium, 1- Low)														

	DISASTER MITIGATION AND MANA	TION AND MANAGEMENT Semester							
PREREQUISI	TES	Category	OE	Cr	edit	3			
NIL		Hours/Week	L	Т	P	ТН			
			3	0	0	3			
Course Learni	ng Objectives	l							
1 To prov	vide students an exposure to disasters, their significance an	id types							
	are that students begin to understand the relationship between		asters, di	saster p	reventi	on and			
3 To gair	a preliminary understanding of approaches of Disaster Ri	sk Reduction (DRR))						
	ance the institutional processes in the country	``							
5 To eval	uate the various case studies in disaster management								
Unit I	INTRODUCTION TO DISASTE	RS	9	0	0	9			
pandemics, complex emergencies, Climate change- Dos and Don'ts during various types of Disasters. Unit II									
nonstructural m	Phases, Culture of safety, prevention, mitigation and peasures, Roles and responsibilities of-community, Pa	nnchayat Raj Inst	itutions/U	Jrban	Local	Bodies			
nonstructural mo(PRIs/ULBs), Sta	easures, Roles and responsibilities of- community, Pattes, Centre, and other stake-holders- Institutional Processe ment Authority(SDMA)— Early Warning System — Adviso	nnchayat Raj Inst s and Framework at ries from Appropria	itutions/U State and	Jrban d Centra	Local	Bodies			
nonstructural mo(PRIs/ULBs), Sta	easures, Roles and responsibilities of-community, Pattes, Centre, and other stake-holders-Institutional Processe	nnchayat Raj Inst s and Framework at ries from Appropria	itutions/U State and	Jrban d Centra	Local	Bodies			
nonstructural me (PRIs/ULBs), Sta Disaster Manage Unit III Factors affecting in Land-use etc	easures, Roles and responsibilities of- community, Pates, Centre, and other stake-holders- Institutional Processe ment Authority(SDMA)— Early Warning System — Adviso INTER-RELATIONSHIP BETWEEN DISA	anchayat Raj Inst s and Framework at ries from Appropria STERS AND	state and te Agence 9 dams, en	Jrban I Centra ies. 0	Local in Level	Bodies - State 9 hanges			
nonstructural me (PRIs/ULBs), Sta Disaster Manage Unit III Factors affecting in Land-use etc	easures, Roles and responsibilities of- community, Pates, Centre, and other stake-holders- Institutional Processe ment Authority(SDMA)— Early Warning System — Adviso INTER-RELATIONSHIP BETWEEN DISA DEVELOPMENT Vulnerabilities, differential impacts, impact of Development Climate Change Adaptation- IPCC Scenario and Scenarios	anchayat Raj Inst s and Framework at ries from Appropria STERS AND ent projects such as s in the context of In	state and te Agence 9 dams, en	Jrban I Centra ies. 0	Local in Level	Bodies - State 9 hanges			
nonstructural me (PRIs/ULBs), Sta Disaster Manage Unit III Factors affecting in Land-use etcknowledge, approunit IV Hazard and Vulr Management, Insother related potential potential potential potential meaning and po	easures, Roles and responsibilities of- community, Pattes, Centre, and other stake-holders- Institutional Processe ment Authority(SDMA)— Early Warning System — Adviso INTER-RELATIONSHIP BETWEEN DISA DEVELOPMENT Vulnerabilities, differential impacts, impact of Development Climate Change Adaptation- IPCC Scenario and Scenarios opriate technology and local resources.	anchayat Raj Instala and Framework at sea and Framework at tries from Appropria and STERS AND STERS AND ent projects such as a in the context of In I INDIA : Water, Food, Saniaredness, Disaster Management of Information	state and te Agence 9 dams, endia – Rel 9 tation, SI fanagem Techno	Jrban	Onents, cloof indig	9 hanges genous Waste olicy –			
nonstructural me (PRIs/ULBs), Sta Disaster Manage Unit III Factors affecting in Land-use etcknowledge, appround IV Hazard and Vulr Management, Insother related por Preparedness, Riemann (PRIs/ULB).	easures, Roles and responsibilities of- community, Parties, Centre, and other stake-holders- Institutional Processes ment Authority(SDMA)— Early Warning System — Adviso INTER-RELATIONSHIP BETWEEN DISA DEVELOPMENT Vulnerabilities, differential impacts, impact of Development Climate Change Adaptation- IPCC Scenario and Scenarios operiate technology and local resources. DISASTER RISK MANAGEMENT IN the stitutional arrangements (Mitigation, Response and Preparticles, plans, programmes and legislation — Role of Grinder Components of Disaster Relief Stitutional arrangements (Mitigation, Response and Preparticles, plans, programmes and legislation — Role of Grinder Components of Disaster Relief Stitutional Arrangements (Mitigation, Response and Preparticles, plans, programmes and legislation — Role of Grinder Components of Disaster Relief Stitutional Arrangements (Mitigation, Response and Preparticles, plans, programmes and legislation — Role of Grinder Components (Mitigation) — Role of	s and Framework at ries from Appropria STERS AND ent projects such as in the context of In I INDIA : Water, Food, Saniaredness, Disaster Manda Information — Disaster Damage	state and te Agence 9 dams, endia – Rel 9 tation, Sl fanagem Techno Assessm	Jrban	Onents, cloof indigenous of the late of th	9 hanges genous Waste blicy – ents in			
nonstructural me (PRIs/ULBs), Sta Disaster Manage Unit III Factors affecting in Land-use etcknowledge, appro Unit IV Hazard and Vulr Management, Insother related po	easures, Roles and responsibilities of- community, Partes, Centre, and other stake-holders- Institutional Processes ment Authority(SDMA)— Early Warning System — Adviso INTER-RELATIONSHIP BETWEEN DISA DEVELOPMENT Vulnerabilities, differential impacts, impact of Development Climate Change Adaptation- IPCC Scenario and Scenarios operiate technology and local resources. DISASTER RISK MANAGEMENT IN DISASTER RISK MANAGEMENT IN Stitutional arrangements (Mitigation, Response and Preparticles, plans, programmes and legislation — Role of Gisk Assessment, Response and Recovery Phases of Disaster Relief Stitutional Response Response and Recovery Phases of Disaster Relief Stitutional Response Re	ent projects such as in the context of In I INDIA Water, Food, Saniaredness, Disaster M IS and Information — Disaster Damage NS AND CASE	state and te Agence 9 dams, endia – Rel 9 tation, SI fanagem Techno	Jrban	Onents, cloof indig	9 hanges genous Waste olicy -			
nonstructural me (PRIs/ULBs), Sta Disaster Manage Unit III Factors affecting in Land-use etcknowledge, appround IV Hazard and Vulr Management, Insother related porparedness, Ristructure V Landslide Hazard Drought Assessn Studies; Forest 1	easures, Roles and responsibilities of- community, Parties, Centre, and other stake-holders- Institutional Processes ment Authority(SDMA)— Early Warning System — Adviso INTER-RELATIONSHIP BETWEEN DISA DEVELOPMENT Vulnerabilities, differential impacts, impact of Development Climate Change Adaptation- IPCC Scenario and Scenarios oppriate technology and local resources. DISASTER RISK MANAGEMENT IN DISASTER RISK MANAGEMENT IN Stitutional arrangements (Mitigation, Response and Preparticular programmes and legislation — Role of Grak Assessment, Response and Recovery Phases of Disaster DISASTER MANAGEMENT: APPLICATION	ent projects such as in the context of In I INDIA Water, Food, Saniaredness, Disaster M IS and Information — Disaster Damage NS AND CASE ment of Buildings an ment, Floods: Fluvi	g dams, endia – Rel g tation, SI fanagem Techno Assessm g d Infrastr al and Pl	onelter, lent. onelter, lent Actlogy Chent. ucture:	O Case S Clooding	9 hanges genous Waste olicy - ents in			

Te	ext Books:
1	Singhal J.P. "Disaster Management", Laxmi Publications, 2010. ISBN-10: 9380386427 ISBN-13:978-9380386423
2	Tushar Bhattacharya, "Disaster Science and Management", McGraw Hill India Education Pvt.Ltd., 2012. ISBN-10: 1259007367, ISBN-13: 978-1259007361]
Ref	erence Books:
1	Govt. of India: Disaster Management Act, Government of India, New Delhi, 2005
2	Government of India, National Disaster Management Policy, 2009.

	se Outcomes: completion of this course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Differentiate the types of disasters, causes and their impact on environment and society	Analyze
CO2	Assess vulnerability and various methods of risk reduction measures as well as mitigation	Understand
СОЗ	Draw the hazard and vulnerability profile of India, Scenarios in the Indian context, Disaster damage assessment and management.	Create
CO4	Use the GIS softwares for disaster risk management in india	Evaluate
CO5	Gain knowledge on various case studies of disaster management	Evaluate

COs/	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
POs		102	103	104	103	100	107	100	10)	1010	1011	1012	1301	1302	1503
CO1	2	1	1	1	1	2	1		1	1	1	1	1		1
CO2	1	1	1	2	1	1	1		1	1	2	1	1		1
CO3	2	1	2	2	1	-	1		2	1	2	1	1		1
CO4	1	1	2	1	3	3	2	1	3	2	3	2	2	2	3
CO5	1	2	2	2	2	2	2	1	2	2	2	2	2		2
Avg	1.4	1.2	1.6	1.6	1.6	1.6	1.4	1	1.8	1.4	2	1.4	1.4	2	1.6
	ı	I	3/2/1 -	- indica	ites str	ength o	f corre	lation (3- High	ı, 2- Me	dium, 1	Low)	ı	I	

22CE	EOE03	ELEMENTS	BUILDING	Semester						
PRE	REQUISI	TES	Category	OE	Cr	edit	3			
Cons	truction n	naterials and Technology & Concrete	Hours/Week	L	Т	P	TH			
Tech	nology			3	0	0	3			
Cour	rse Learni	ng Objectives		•						
1	To get the	knowledge on causes of deterioration of structure								
2	To know about the assessment of distressed structures									
3	To get the	knowledge on maintenance of building systems								
4	To know	about the repairing of structures								
5	To gain k	nowledge about the techniques involved in the demolition	n procedure							
U	Jnit I	ATEGIES	9	0	0	9				
	-	pair and rehabilitation, Facts of Maintenance, importan- dure for evaluating a damaged structure, causes of deterior		arious a	spects	of insp	ection,			
U	nit II	MAINTENANCE OF ELECTRICITY ANI WATER PUMP SYSTEMS	D DOMESTIC	9	0	0	9			
supply Gener	y during pov	hting devices and usual household appliances, electric sup wer failure, importance of earth leakage circuit breaker (E tions of water pumps, centrifugal pumps, jet pumps and intenance of the sump.	ELCB), Maintenance of	of electri	c syster	n in bui	ldings.			
Uı	nit III	MATERIALS AND TECHNIQUES FO	R REPAIR	9	0	0	9			
concre	ete sulphur ed concrete	pair: Special concretes and mortar concrete chemicals c infiltrated concrete Ferro cement Fibre reinforced concre dry pack vacuum concrete asphalt sheeting Techniques fo	ete Rust eliminators a	nd polyn	ners coa	ating for	r rebar			
Uı	nit IV	9	0	0	9					
-		eams and columns damaged by steel corrosion, repair or racks in concrete structures, repair of rain water, groundware.	• •		pair of	efflore	scence			
U	nit V	DEMOLITION TECHNIQUE	ES	9	0	0	9			
Engin	eered demo	lition techniques for dilapidated structures- case studies								
					Total:	= 45 Pe	eriods			

Te	ext Books:								
1	Varghese P.C., Maintenance Repair Rehabilitation and Minor Works of Buildings, PHI Learning								
1	pvt.ltd.,NewDelhi,2014								
Ref	erence Books:								
1	Santhakumar A.R, Training Course notes on Damage Assessment and Repair in Low cost housing, "RHDC.NBO" Anna								
1	University, July 1992.								
2	Shetty, M.S., Concrete Technology-Theory and Practice, S. Chand and company, NewDelhi,1992								
2	RaikarR.N., Learning from failures- deficiencies in design, construction and services- R &D centre (SDCPL), raikar								
3	bhavan, Bombay,1987								
4	Palaniyappan, N., Estate management, Anna Institute of Management, Chennai, 1992.								
5	Lakshmipathy, M. et al., Lecture notes of workshop on Repairs and Rehabilitation of structures, 29-30thoctober 1999.								

	se Outcomes: completion of this course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Carry out the damage assessment and Rapid Visual inspection of a building showing signs of deterioration and thus should be able to detect the possible cause /source of deterioration	Analyse
CO2	Know how to Maintain and repair the building systems like electricity, plumbing etc.	Remember
СОЗ	Know how of the Concrete repair industry equipped with variety of repair materials and techniques	Remember
CO4	Know the various repair works in building systems.	Remember
CO5	Demonstrate the dismantling and demolishing structures	Apply

COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	-	-	-	-	1	1	1	1	1	1	2	1	1	-	1
CO2	-	-	-	-	2	1	1	1	1	1	2	1	1	-	1
CO3	-	-	-	-	2	1	1	1	1	1	1	1	2	-	1
CO4	-	-	-	-	2	1	1	1	1	-	-	-	1	-	1
CO5	-	-	-	-	1	2	1	2	2	2	1	1	1	-	1
Avg	-	-	-	-	1.6	1.2	1	1.2	1.2	1.25	1.5	1	1.2	-	1
	3/2/1 – indicates strength of correlation (3- High, 2- Medium, 1- Low)														

22CI	EOE04	MECHANICS OF DEFORMABI	LE BODIES	S	er	VI		
PRE	REQUISI	TES	Category	OE	Cr	edit	3	
Mecl	hanics of S	Solids and Strength of Materials	Hours/Week	L	T	P	TH	
				3	0	0	3	
Cou	rse Learni	ng Objectives						
1	To learn t	he fundamental concepts of stress, strain and their relas.	ations based on linear elas	sticity wit	h appli	cations	to bars	
2	_	he bending of various types of beams under static load and find the Maximum moment/shear and their loca	_				ngrams	
3	Understar	nd the basic concept of theory of flexure and torsion,	springs and strain energy					
4		the principles of mechanics applied to different maxills through application of these principles to basic e		tions and	l to dev	elop pi	oblem	
5	To learn to parametri	the principles of mechanical behavior of engineering c studies.	materials, various tests u	nder dyn	amics o	conditio	ns and	
Ţ	U nit I	SIMPLE STRESSES, BEHAVIOUR O SECTIONS, THERMAL STR		9	0	0	9	
		erties of solids –Hooke's law, principle of superpons – determination of stress, strain, deformation –Tel		sections	–Elasti	ic cons	iants –	
U	J nit II	BENDING AND SHEA	R	9	0	0	9	
		shear force and bending moment. Theory of simple beams of different cross sections	e bending - Analysis of	stress-lo	ad carr	ying ca	pacity	
U	nit III	TORSION AND SPRIN	GS	9	0	0	9	
		l ar shaft – Hollow and solid circular section, torsion shafts springs-Stiffness and deflection of helical sprin		 -Twist ar	l nd torsi	l onal sti	ffness-	
U	nit IV	MECHANICAL BEHAVIOUR OF MAT STATIC LOADS	TERIALS UNDER	9	0	0	9	
		l tress – strain diagram, Elastic and plastic regions – T empression and Torsion tests – stress concentration –l		ties in ter	l nsion –	fracture	under	
τ	J nit V	MECHANICAL BEHAVIOUR OF MA DYNAMIC LOADS	TERIALS UNDER	9	0	0	9	
stress	concentrati	 and Fatigue fracture – Fatigue tests – Empirical relation Factors – Cumulative Damage – Endurance limit ct tests – Elevated temperature – Creep tests – Isochr	t –Impact – notched – Ba	ır Impact	tests, C	Charpy	Impac	
						= 45 Pc		

Te	ext Books:
1	James M.Gere, Mechanics of Materials, Brooke/Cole Thomson Learning, 5 Ed., 2001.
2	Dr.R.Vaithiyanathan, Dr. P. Perumal &Lingeswari", Mechanics of Solids and StructuresVolume-I" Scitech publications, India(Pvt) Chennai-17.
3	Srinath L.S; - Strength of materials – Macmillan India Limited – New Delhi,2017
Ref	Ference Books:
1	Popov.E.P., "Engineering Mechanics of solids", Prentice- Hall of India, New Delhi
2	Beer F.P and Johnston R, "Mechanics of Materials", McGraw- Hill book Co, Third Edition
3	Timoshenko S.P., "Elements of Strength of Materials", Tata McGraw- Hill, New Delhi
4	Nash W.A., "Theory and Problems in Strength of Materials", Schuam outline Series, McGraw- Hill Book Co., New York.
5	Rajput. R.K., "Strength of Materials", S. Chand & Co, Delhi, Third Edition, 2003.

	Course Outcomes: Upon completion of this course, the students will be able to:	
CO1	CO1 To acquire basic knowledge of stress strain and deformation of structures of varying cross sections of bars.	
CO2	To draw Shear Force and Bending Moment Diagram for transverse loading under various types of loadings and beams.	Analyse
CO3	To solve problems of Torsional shear stress for shaft and stiffness and deflection of springs	Apply
CO4	Describe the mechanical behaviour of engineering materials subjected to various types of stresses	Understand
CO5	Understand the concept of mechanical behaviour under dynamic loading of various tests to find the stresses induced in the materials.	Understand

COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	1	-	2	-	-	1	-	-	-	-	1	-	-	-
CO2	1	1	-	-	-	-	-	-	-	-	-	1	-	-	-
CO3	1	1	-	1	-	-	-	-	-	-	-	1	-	-	-
CO4	1	1	-	1	-	-	-	-	-	-	1	1	-	-	-
CO5	1	1	-	1	-	-	-	-	-	-	1	1	-	-	-
Avg	1	1	-	1.25	-	-	1	-	-	-	1	1	-	-	-

22CSO	E01	OBJECT ORIENTED PROGRAMMING USING	CONCEPTS					
PRERE	EQUIS	SITES	CATEGORY	OE	Cred	it	3	}
Problem	n Solvi	ng and C Programming	Hours/Week	L	T	P	1	Ή
			Hours/ week	3	0	0		3
Cours	e Obje	ectives:		•	·			
1.	To und	lerstand object oriented programming concept						
2.	То арр	oly object oriented concept for problem solving						
3.	To des	ign solutions to the real world problems using object oriented	concept.					
UNIT	I	INTRODUCTION			9	0	0	9
progran	nming,	ented programming paradigm - Object oriented programmin benefits of OOP, application of OOP - C++ fundamentals expressions - Control structures - Functions.		-				
UNI	II II	CLASSES AND OBJECTS	S		9	0	0	9
		objects - friend functions- constructors and destructors- Opesing member function and friend function - Type conversions.	erator overloading	– binary	and u	nary	ope	rator
UNIT	III	INHERITANCE AND VIRTUAL FUR	NCTIONS		9	0	0	9
		defining derived classes, types, virtual base classes, abstract dects, this pointer, pointer to derived classes - Virtual functions		in deriv	ed class	ses -	Poir	iters-
UNIT	ΓIV	TEMPLATES AND EXCEPTION HA	ANDLING		9	0	0	9
templat	es with	\cos – class template, class templates with multiple parameters - α multiple parameters, member function templates - Exception α exception .			-			
UNI	TV	CONSOLE I/O AND FILE HANI	DLING		9	0	0	9
		Classes – unformatted I/O operations, formatted console I/O ning and closing a file, detecting end of file, files modes, sequ	ential file operation		m file o	pera	tions	S.

Text 1	Text Books:						
1. E. Balagurusamy "Object Oriented Programming with C++", Eighth Edition, Tata McGraw-Hill, 2020.							
Refer	ence Books:						
1.	Herbert Schildt, "The Complete Reference C++", Fifth Edition, Tata McGraw Hill, 2015.						
2. Bjarne Stroustrup, "The C++ programming language", Fourth Edition Addison Wesley, 2013.							
3.	K.R. Venugopal, Rajkumar Buyya, T.Ravishankar, Mastering in C++, Second Edition, Tata McGraw Hill, 2013.						

Course	Course Outcomes:			
Upon co	Upon completion of this course, the students will be able to:			
CO1	Familiarize the object oriented programming concepts, Generic Programming and handling	Understand		
	exceptions.			
CO2	Build Object Oriented Programming concepts for problem solving.	Apply		
CO3	Develop solutions to real world problems using Object Oriented Concepts.	Apply		

22CSOE02		OPERATING SYSTEMS PRINCIPLES				
PREREQU	UISITES	CATEGORY	OE	Cr	edit	3
NIL			L	T	P	TH
		Hours/Week	3	0	0	3
Course O	bjectives:					
1. To	understand the	structure and functions of Operating systems				
		process concepts and scheduling algorithms				
3. To	understand the	concept of process synchronization and deadlocks				
4. To	learn various m	emory management schemes				
5. To	illustrate variou	s file systems and disk management strategies				
UNIT I	INTRO	DUCTION AND OPERATING SYSTEM STRUCTURES	9	0	0	9
systems, H	and held System	sktop Systems, Multiprocessor Systems, Distributed Systems, Clusterens; Operating Systems Structures - System Components, Operating System	-			
System Fit	grams, System	Design and Implementation.				
UNIT II		PROCESS MANAGEMENT	9	0	0	9
UNIT II Processes-I	Process Conce	<u> </u>	Process	es, I	nterP	roces
UNIT II Processes-I	Process Conceptation; Threads-Algorithms.	PROCESS MANAGEMENT pts, Process Scheduling, Operation on Processes, Co-Operating	Process	es, I	nterP	roces
Processes-l Communic Scheduling UNIT III Process Sy Deadlocks-	Process Concelation; Threads-Algorithms. PI nchronization-Deadlock Cha	PROCESS MANAGEMENT pts, Process Scheduling, Operation on Processes, Co-Operating Multithreading Models, Threading Issues; CPU Scheduling-Basic Conce	Processipts, Sch	es, Ineduli	nterP ng Cı 0	roces riteria 9 nitors
Processes-l Communic Scheduling UNIT III Process Sy Deadlocks-	Process Conceptation; Threads-Algorithms. PI nchronization-Deadlock Charles Detection, Reco	PROCESS MANAGEMENT pts, Process Scheduling, Operation on Processes, Co-Operating Multithreading Models, Threading Issues; CPU Scheduling-Basic Concessional Rocess Synchronization and Deadlocks The Critical Section Problem, Semaphores, Classical Problem of Synaracterization, Methods for handling Deadlocks, Deadlock Prevention	Processipts, Sch	es, Ineduli	nterP ng Cı 0	roces riteria 9 nitors
Processes-Icommunic Scheduling UNIT III Process Sy Deadlocks-,Deadlock UNIT IV	Process Conceptation; Threads-Algorithms. PI nchronization-Deadlock Charlestection, Recomplete ME anagement-Ba	PROCESS MANAGEMENT pts, Process Scheduling, Operation on Processes, Co-Operating Multithreading Models, Threading Issues; CPU Scheduling-Basic Conce ROCESS SYNCHRONIZATION AND DEADLOCKS The Critical Section Problem, Semaphores, Classical Problem of Synaracterization, Methods for handling Deadlocks, Deadlock Prevention very from Deadlock.	Processing school of the processing school of	es, Ineduli 0 cation llock	nterPng Co	roces riteria 9 nitors dance
Processes-Icommunic Scheduling UNIT III Process Sy Deadlocks-,Deadlock UNIT IV	Process Conceptation; Threads-Algorithms. PI nchronization-Deadlock Chapetection, Recomplete ME anagement- Battual Memory -	PROCESS MANAGEMENT pts, Process Scheduling, Operation on Processes, Co-Operating Multithreading Models, Threading Issues; CPU Scheduling-Basic Conce ROCESS SYNCHRONIZATION AND DEADLOCKS The Critical Section Problem, Semaphores, Classical Problem of Synaracterization, Methods for handling Deadlocks, Deadlock Prevention very from Deadlock. EMORY MANAGEMENT AND VIRTUAL MEMORY ckground, Swapping, Contiguous Memory Allocation, Paging, Segmenta	Processing school of the processing school of	es, Ineduli 0 cation llock	nterPng Co	roces riteria 9 nitors dance
Processes-Icommunic Scheduling UNIT III Process Sy Deadlocks-,Deadlock UNIT IV Memory Maging; Vin UNIT V File Syster Implement	Process Conceptation; Threads-Algorithms. PI nchronization-Deadlock Characteristics Detection, Recomplete ME anagement-Batual Memory - In Interface - Fation - File Sys	PROCESS MANAGEMENT pts, Process Scheduling, Operation on Processes, Co-Operating Multithreading Models, Threading Issues; CPU Scheduling-Basic Conce ROCESS SYNCHRONIZATION AND DEADLOCKS The Critical Section Problem, Semaphores, Classical Problem of Synaracterization, Methods for handling Deadlocks, Deadlock Prevention very from Deadlock. EMORY MANAGEMENT AND VIRTUAL MEMORY ckground, Swapping, Contiguous Memory Allocation, Paging, Segmenta Demand paging, Page Replacement, Thrashing.	Processing the process of the proces	es, Ineduli 0 cation cation con; Inods,	nterPing Cr 0 Avoid 0 ntation	pointors dance

Text	Books:
1.	Abraham Silberschatz, P.B.Galvin, G.Gagne —Operating System Concepts 6th edition, John Wiley & Sons,
	2003.
Refe	rence Books:
1.	Andrew S. Tanenbaum, —Modern Operating Systems, PHI, 2nd edition, 2001
2.	D.M.Dhamdhere, "Systems Programming and Operating Systems", 2nd edition, Tata McGraw Hill
	Company, 1999.
3.	Maurice J. Bach, —The Design of the Unix Operating System, 1st edition, PHI, 2004.

COURS	SE OUTCOMES:	Bloom's
		Taxonomy
Upon co	empletion of the course, the students will be able to:	Mapped
CO1	Interpret the components and functionalities of the operating system	Understand
CO2	Apply various services and concepts of operating system to real time applications	Apply
CO3	Analyze the issues related to operating system and provide suitable solutions.	Analyze

22CSOE03		COMPUTER COMMUNICATIO NETWORKS	NS AND					
PREREQUI	SITES	1	CATEGORY	OE	Cr	edit	3	
NIL			Hours/Week	L	L T P			
			Hours, Week	3	0	0	3	
Course Obj	ectives:		1	1				
1. To stud	ly the concept	s of data communications and functions of differen	at ISO/OSI reference	architec	ture			
	·	ror detection and correction methods and also the ty						
3. To stud	ly the concept	s of subnetting and routing mechanisms						
4. To und	erstand the di	fferent types of protocols and congestion control						
		ion protocols and network security				1		
UNIT I	DAT	A COMMUNICATIONS AND PHYSICAL	LAYER	9	0	0	9	
Data Commu	nication: Netv	vorks- Physical Structures (Types of Connections,	Physical Topology)	Catego	ries o	f Net	works	
		ss: Internetwork; Protocols and Standards; Network		_				
		nission media-Guided Media, Unguided Media.		10001, 1	2 m y 0 2 1	, 111 (1		
UNIT II		DATA LINK LAYER		9	0	0	9	
(VRC, LRC,	CRC, Checksomatic Repeat	rs, Redundancy, Detection versus Correction; Bl um, Hamming Code);Data link Control- Flow Cor Request, Stop-and-wait ARQ, Sliding Window Al	ntrol (Stop- and-Wait	, Slidin	g Wii	ndow),Erro	
UNIT III		NETWORK LAYER		9	0	0	9	
•		acket Switching-Network Layer Performance-III -Routing Algorithm-Distance Vector Routing, Lin		address	ing-	Subn	etting	
UNIT IV		TRANSPORT LAYER		9	0	0	9	
Duties of the	Transport lay	er-User Datagram Protocol-Transmission Control	Protocol- Congestion	n Contr	ol and	l Qua	ılity o	
		stion Control, Quality of Service, Techniques to im	•				•	
UNIT V		APPLICATION LAYER		9	0	0	9	
Domain Nam	e System - Do	main Name Space, DNS in the Internet; Electronic	: Mail-FTP- HTTP- V	Vorld W	/ide V	Veb.		
						- D	• •	
			Tota	al (45 I	ر) = 4	5 Pei	rioas	

Text	Text Book:						
1.	Behrouz A. Ferouzan, "Data Communications and Networking", 4th Edition, Tata McGraw-Hill, 2007.						
Refer	rence Books:						
1.	Andrew S. Tanenbaum, "Computer networks "PHI, 4th edition 2008						
2.	William Stallings," Data and computer communications", 10th edition, PHI, 2012						
3.	Douglas E. comer," Internetworking with TCP/IP-Volume-I", 6 th edition,PHI, 2008						

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:		
CO1	Understand the fundamental concepts of networking and working principles of various communication protocols.	Understand	
CO2	Apply the various functionalities of OSI layers in real time applications	Apply	
CO3	Analyze the various network issues in different layers and provide suitable solutions.	Analyze	

22CSOE04	PYTHON PROGRAMMING					
PREREQUIS	SITES	Category	OE	Cre	edit	3
NIL		Hours/Week	L	T	P	ТН
		Hours/ week	3	0	0	3
Course Leari	ning Objectives					1
1 To Le	earn the basic concepts of python programming.					
2 To wi	rite simple programs using python programming concepts.					
3 To bu	ild simple real world applications using python.					
UNIT I	INTRODUCTION		9	0	0	9
Introduction -	Features- The Basics - Numbers, Sequence: Strings, Lists, Tup	les Manning and s	set types	Variah	oles- On	erators
	Precedence of operators – Comments - Input and output				_	
•	cit type conversion.		8			8
UNIT II	CONDITIONS, CONTROL STRUCTURES A	ND FILES	9	0	0	9
	,				_	
	and loops-if statement-else statement – elif-Conditional Exps; Files and Input/ Output.	ressions-while sta	tement-	for state	ement –	break
UNIT III	PYTHON EXCEPTIONS, MODULES AND PA	ACKAGES	9	0	0	9
Errors and Exc	ceptions – Introduction-Detecting and handling Exceptions- Rais	sing Exceptions – A	Assertion	ns-Stanc	lard Exc	eption
- Modules: us	er defined modules, random and o s modules - Packages.					
UNIT IV	FUNCTIONS		9	0	0	9
Functions-Ca	lling functions-Creating functions-Passing Functions-Formal.	Arouments-Variah	le lengt	h aroun	nents- V	/ariahl
	sion- Map, Filter, Reduce and List Comprehensions-Iterators -	•	_	ar argan	ilents	uruor
		DECLE AD	ı		П	1
UNIT V	OBJECT ORIENTED PROGRAMMING AND EXPRESSION	REGULAR	9	0	0	9
	Classes- Class Attributes – Instances-Instances attributes-Bui	lding and Method	Invocat	ion-Stat	ic meth	ods an
Class Methods	s – Inheritance-Operator overloading-Regular Expression.					
			Tota	l (45 L) =45 F	 Period
Text Books:						
	J.Chun-"Core Python Programming" –Prentice Hall, Third Edi	tion, 2012.				
Reference Bo						
1. Swaroo	p C N, "A Byte of Python", ebshelf Inc., 1st Edition, 2013					
	tical Introduction to python programming", Brian Heinold, Mou	ıntSt.Mary's Univ	ersity,20)12		
3. Learnin	g to Program with Python," Richard L. Halterman"., Southern	Adventist Universi	ty			

COURSE Upon con	Bloom's Taxonomy Mapped	
CO1	To understand the basic concepts of python programming.	Understand
CO2	To design simple programs using python programming concepts.	Apply
CO3	To apply python programming concepts in the real world application.	Analyze

	INTRODUTION TO PROGRAMMING IN	N JAVA					
PREREQUI	SITES	CATEGORY	OE	Cred	lit	3	3
C Programm	ing	** ***	L	T	P		TH
		Hours/Week	3	0	0		3
Course Obje				Į.		·	
	niliarize and apply the Object Oriented concepts and java feature	ires					
	te the standalone applications and applet applications ld simple chart application and Database Connectivity						
UNIT I	INTRODUCTION TO JAVA	1		9	0	0	9
	ava language - java program structure, java tokens, java state mand line arguments; constants, variables and data types - C looping.						
UNIT II	JAVA FEATURES			9	0	0	9
Classes, object handling.	ts methods – arrays, Strings and Vectors– Interfaces – Pack	ages - Multithread	ded prog	rammi	ng- l	Exce	ptio
nananng.							
UNIT III	APPLET			9	0	0	9
UNIT III Applet programe the applet ,pas	APPLET mming- build applet code, applet life cycle, creating executable sing parameters to Applet; Graphics programming – graphics			e, appl	et tag	g, run	nin
UNIT III Applet programe the applet ,pas	nming- build applet code, applet life cycle, creating executable			e, appl	et tag	g, run	
UNIT III Applet programe the applet ,past polygons UNIT IV Event handlin	nming- build applet code, applet life cycle, creating executable sing parameters to Applet; Graphics programming – graphics	class, lines, rectang	gles, circ	e, appl les, elli	et tag ipses	g, rur , arcs	nnin s an
UNIT III Applet programe the applet ,past polygons UNIT IV Event handlin	nming- build applet code, applet life cycle, creating executable sing parameters to Applet; Graphics programming – graphics of the AWT CONTROLS g – event handling Mechanisms, delegation event model, expressions and the state of the control of th	class, lines, rectang	gles, circ	e, appl les, elli	et tag ipses	g, rur , arcs	nnin s an

Text	Books:
1.	E. Balaguruswamy, "Programming with java", Sixth, TMH 2019 (Unit- I-III)
2.	Patrick Naughton , Herbert Schildt, "The Complete Reference Java 2" , Twelfth edition Tata McGraw Hills , 2021 (Unit IV - V)
Refer	rence Books:
1.	Cay S. Horstmann, Gary Cornell "Core Java 2" Eighth Edition, Pearson Education, 2008
2.	Graham Hamilton, Rick Cattell, Maydene Fisher,"JDBC Database access with java".1997
3.	PaulDeitel and Harvey Deitel, "Java How to Program", Eleventh Edition, Pearson Prentice Hall 2017.

COURSE Upon com	Bloom's Taxonomy Mapped	
CO1	Familiarize the Object Oriented concepts and java features	Understand
CO2	Build the simple standalone applications and web applications	Create
CO3	Create	

220	CSOE06	COMPUTER ORGANIZATION		SEM	EST	ER	VI
PRER	REQUIS	ITES	CATEGORY	OE	Cre	dit	3
Digita	1 Princip	les and System Design		L	P	ТН	
			Hours/Week	3	0	0	3
Cou	rse Obje	ctives:					
1.	To und	erstand the basic structure and operations of digital computer arms.	nd to learn the working	g of dif	ferent	arith	ımetic
2.		se different types of processor control and the concept of pipelining cache memory and virtual memory	g and to familiarize hier	rarchica	l men	ory s	ystem
3.	To expo	se the different ways of communicating with I/O devices and stand	ard I/O interfaces				
Ul	NIT I	INTRODUCTION		9	0	0	9
		ts ,Basic Operational Concepts, Bus Structure ,Memory Locations a Sequencing, Addressing modes.	and Addresses, Memory	Operation	ons, I	ıstruc	tion
Uľ	II TIN	ARITHMETIC UNIT		9	0	0	9
		Subtraction of Signed Numbers, Design of Fast Adders, Multiplica Integer Division, Floating point number operations.	tion of Positive Number	rs, Boot	hAlgo	rithn	ı, Fast
UNI	III TII	PROCESSOR UNIT AND PIPELINI	NG	9	0	0	9
		Concepts, Execution of Instruction, Multi Bus Organization, Hardw pelining, Data Hazards, Instruction Hazards, Data path & Control O		gramme	d con	trol, I	3asic
UN	UNIT IV MEMORY SYSTEMS				0	0	9
	-	ts, Semiconductor RAM, ROM, Cache memory, Improving equirements, Secondary Storage Device.	Cache Performance, V	irtual n	nemo	y, Mo	emory
UN	IT V	INPUT AND OUTPUT ORGANIZAT	ION	9	0	0	9
	ssing I/C	devices, Programmed I/O, Interrupts, Direct Memory Access,	Interface circuits, Stand	dard I/0	OInter	faces	(PCI,
	, ,.		Tota	ıl (45 L)= 4 5	Per	iods

Text	Books:
1.	Carl Hamacher V., Zvonko G. Vranesic, Safwat G. Zaky, "Computer organization", Tata McGraw Hill, 5th Edition, 2008.
Refe	rence Books:
1.	Patterson and Hennessey, "Computer Organization and Design". The Hardware/Software interface, Harcourt Asia Morgan Kaufmann, 3rd Edition, 2007
2.	Hayes, "Computer Architecture and Organization", 3rd edition, Tata McGraw Hill, 2006
3.	Heuring V.P., Jordan H.F., "Computer System Design and Architecture ", 6th edition ,Addison Wesley,2008

COUR Upon c	Bloom's Taxonomy	
		Mapped
CO1	Understand the working principles of computer components	Understand
CO2	Design the arithmetic and processing units	Create
CO3	Analyze the various computer components	Analyze

22CSOE07	DATA STRUCTURES USING C+	SEMEST			MESTER VI		
PREREQUIS	ITES	Category OE		Cre	edit	3	
C Program	ming		L	T	P	TH	
		Hours/Week	3	3 0	3 0	0	3
Course Learn	ing Objectives						
1 To co	mprehend the fundamentals of object oriend programming, par	rticularly in C++					
2 To de	sign linear and non linear data structure using object programn	ning concepts					
3 To ap	ply various sorting and searching alogorithims.						
UNIT I	DATA ABSTRACTION & OVERLOAD	DING	9	0	0	9	
	rs – Container Classes and Integrators – Overloading: Fun						
UNIT II Base Classes Public, Protect to Base – Clas	INHERITANCE AND POLYMORPHI and Derived Classes – Protected Members – Casting Class ped and Private Inheritance – Constructors and Destructors in des Object Conversion – Virtual functions – this Pointer – Abstructors Binding.	SM pointers and Memberived Classes – Im	9 per Fund	0 ctions – Derived -	0 Overri	9 Iding -	
UNIT II Base Classes Public, Protect to Base – Clas	and Derived Classes – Protected Members – Casting Class ped and Private Inheritance – Constructors and Destructors in descriptions – Virtual functions – this Pointer – Abstructors	SM pointers and Memberived Classes – Im	9 per Fund	0 ctions – Derived -	0 Overri	9 Iding - Objec Virtua	
UNIT II Base Classes Public, Protect to Base – Clas Destructors – I UNIT III Abstract Data	INHERITANCE AND POLYMORPHI and Derived Classes – Protected Members – Casting Class ped and Private Inheritance – Constructors and Destructors in des Object Conversion – Virtual functions – this Pointer – Abstructors Binding.	SM pointers and Memberived Classes – Imract Base Classes a	9 Der Fund pplicit D nd Cond	0 ctions – Derived - crete Cla	Overri - Class asses –	9 dding - Objec Virtua	
UNIT II Base Classes Public, Protect to Base – Clas Destructors – I UNIT III Abstract Data	INHERITANCE AND POLYMORPHI and Derived Classes – Protected Members – Casting Class ped and Private Inheritance – Constructors and Destructors in des Object Conversion – Virtual functions – this Pointer – Abstructions – Binding. LINEAR DATA STRUCTURES Types (ADTs) – List ADT – array-based implementation –	pointers and Memberived Classes – Imract Base Classes a linked list implementic expressions.	9 Der Fund pplicit D nd Cond	0 ctions – Derived - crete Cla	Overri - Class asses –	9 dding - Objec Virtua 9 ed lists	
UNIT II Base Classes Public, Protect to Base – Clas Destructors – I UNIT III Abstract Data –Polynomial M UNIT IV Trees – Binar Operations of	INHERITANCE AND POLYMORPHI and Derived Classes – Protected Members – Casting Class ped and Private Inheritance – Constructors and Destructors in des Object Conversion – Virtual functions – this Pointer – Abstructions – Binding. LINEAR DATA STRUCTURES Types (ADTs) – List ADT – array-based implementation – Manipulation – Stack ADT – Queue ADT – Evaluating arithmentation – Stack ADT – Queue ADT – Evaluating arithmentation – Stack ADT – Queue ADT – Evaluating arithmentation – Stack ADT – Queue ADT – Evaluating arithmentation – Stack ADT – Queue ADT – Evaluating arithmentation – Stack ADT – Queue ADT – Evaluating arithmentation – Stack ADT – Queue ADT – Evaluating arithmentation – Stack ADT – Queue ADT – Evaluating arithmentation – Stack ADT – Queue ADT – Evaluating arithmentation – Stack ADT – Queue ADT – Evaluating arithmentation – Stack ADT – Queue ADT – Evaluating arithmentation – Stack ADT – Queue ADT – Evaluating arithmentation – Stack ADT – Queue ADT – Evaluating arithmentation – Stack ADT – Queue ADT – Evaluating arithmentation – Stack ADT – Queue ADT – Evaluating ADT – E	pointers and Memberived Classes – Imract Base Classes a linked list implementic expressions.	9 Der Fund Policit Der Grand Cond 9 Dentation 9 Dentation	0 ctions - Derived - Crete Cla 0 n -Singi	Overri-Class asses - Uy Linke	9 Iding - Object Virtual 9 ed lists Heaps	
UNIT II Base Classes Public, Protect to Base – Clas Destructors – I UNIT III Abstract Data –Polynomial M UNIT IV Trees – Binar Operations of	INHERITANCE AND POLYMORPHI and Derived Classes – Protected Members – Casting Class ped and Private Inheritance – Constructors and Destructors in des Object Conversion – Virtual functions – this Pointer – Abstructions – this Pointer – Abstructions – this Pointer – Abstruction – Manipulation – List ADT – array-based implementation – Manipulation – Stack ADT – Queue ADT – Evaluating arithme NON-LINEAR DATA STRUCTURE Ty Trees – Binary tree representation and traversals – Application – Binary Heap – Max Heap – Min Heap – Grap	pointers and Memberived Classes – Imract Base Classes a linked list implementic expressions.	9 Der Fund Policit Der Grand Cond 9 Dentation 9 Dentation	0 ctions - Derived - Crete Cla 0 n -Singi	Overri-Class asses - Uy Linke	9 Iding - Object Virtua 9 ed lists Heaps	
UNIT II Base Classes Public, Protect to Base – Clas Destructors – I UNIT III Abstract Data –Polynomial M UNIT IV Trees – Binar Operations of Representation UNIT V	INHERITANCE AND POLYMORPHI and Derived Classes – Protected Members – Casting Class ped and Private Inheritance – Constructors and Destructors in des Object Conversion – Virtual functions – this Pointer – Abstructions – Binding. LINEAR DATA STRUCTURES Types (ADTs) – List ADT – array-based implementation – Manipulation – Stack ADT – Queue ADT – Evaluating arithmethory Trees – Binary tree representation and traversals – Applied Heaps – Binary Heap – Max Heap – Min Heap – Graph of Graphs – Breadth-first search – Depth-first search.	pointers and Memberived Classes – Imract Base Classes a linked list implementic expressions.	9 per Fund Cond 9 pentation 9 sinary S ntations	0 ctions – Derived - Crete Cla 0 n –Single 0 earch T – Gra	Overri - Class asses - O ly Linke	9 dding - Objec Virtua 9 ded lists Heaps ersals	

Tex	t Books:
1	Deitel and Deitel, "C++, How To Program", Tenth Edition, Pearson Education, 2017.
2	Mark Allen Weiss, "Data Structures and Algorithm Analysis in C++", Fourth Edition, Addison Wesley, Copyright 2014.
Refer	rence Books:
1	Bhushan Trivedi, "Programming with ANSI C++, A Step-By-Step approach", Oxford University Press,2010.
2	Goodrich, Michael T., Roberto Tamassia, David Mount, "Data Structures and Algorithms in C++", 7thEdition, Wiley. 2004.
3	Thomas H. Cormen, Charles E. Leiserson, Ronald L. Rivest and Clifford Stein, "Introduction to Algorithms", Second Edition, Mc Graw Hill, 2002.
4	Bjarne Stroustrup, "The C++ programming language", Fourth Edition Addison Wesley, 2013.
5	Ellis Horowitz, Sartaj Sahni and Dinesh Mehta, "Fundamentals of Data Structures in C++", Galgotia Publications, 2007.

	Course Outcomes: Upon completion of this course, the students will be able to:					
CO1	Understand the concepts of Object oriented programming	Understand				
CO2	Design linear and non-linear data structure using object oriented programming concepts	Apply				
CO3	Apply various sorting and searching Alogarithms.	Analyze				

PREREQ	TITCT											
	U151 .	TES:				CATE	GORY	OE	Credit			3
Computer	Netw	orks				11	/XX7 1	T	L T P			TH
						Hours	/Week	3 0 0				3
Course O	bjecti	ves:							•		<u> </u>	
1. To	o introd	luce the b	proad perc	ceptive of	Parallel Con	mputing, Distrib	outed Compu	iting and C	oud Co	mpu	ting.	
2. To	unde	stand the	concept	of Virtua	lization, Clo	oud Architecture	and Storage					
3. To	unde	stand the	Cloud Pl	atforms i	n Industry a	nd Software En	vironments.					
4. To	unde	stand the	concept	of Cloud	Security and	d Applications.						
UNIT I					INTRODU	JCTION			9	0	0	9
computing.	of Para	llel and l	Distribute	d Compu	ting: Paralle	zation - Web 2.			•		•	
UNIT II		nologies	ioi uisuio	V	IRTUALI	IZATION			9	0	0	9
Level Virtu Virtualizati					_	irtualization —A	Application I	Level Virtu	alizatio	n - (Other	types o
UNIT III			CLOU	JD ARC	HITECTU	URE AND ST	ORAGE		9	0	0	9
					Types of clo	ouds: Public clo	uds – Private	clouds – H	ybrid cl	louds	– Co	mmunit
clouds ;Arc Cloud Stor					intages of cl	loud storage –	Cloud Storag	ge Provider	: Amaz	on S	imple	Storag
Service (S3		CLC	DIID INI	HISTRI	IAL PLAT	FORMS ANI) SOFTW	ARE.				
UNIT IV		CEC	OD II (I		ENVIRON		5 501 T W	III	9	0	0	9
Cloud Platf	orms i	n Industr	y: Amazo	n Web Se	ervice - Goo	gle App Engine	- Microsoft	Azure; Clo	ud Soft	ware	Envi	ronment
-Hadoop –N	Map R	educe -Eu	ıcalyptus	– Open N	Vebula;							
UNIT V			CLO	UD SEC	CURITY A	ND APPLICA	ATIONS		9	0	0	9
•				•	_	oftware as a Se				geme	ent –	Securit
actionnon oc	-Sec	urity Arc	hitecture l	Design -V		nine Security – I	dentity Acce	ess Manage				
-		1	TT 4	1	1	in the cloud- Ge	~	. 11'. T	т.			

Text 1	Books:
1.	Rajkumar Buyya, Christian Vecchiola, S.TamaraiSelvi, 'Mastering Cloud Computing-Foundations
	and Applications Programming", TMGH,2013.
2.	Rittinghouse, John W., and James F. Ransome – Cloud Computing: Implementation, Management
	and Security. CRC Press, 2017.
Refer	rence Books:
1.	Kai Hwang.GeoffreyC.Fox.JackJ.Dongarra, "Distributed and Cloud Computing, From Parallel Processing
	to The Internet of Things", 2012 Elsevier
2.	Barrie Sosinsky, "Cloud Computing Bible", Wiley Publisher, 2011

	RSE OUTCOMES: completion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Explain the main concepts and architecture of Parallel computing, Distributed Computing and Cloud Computing.	Understand
CO2	Analyze the concept of Virtualization, Cloud Architecture and Storage.	Analyze
CO3	Analyze the Cloud Platforms in Industry and Software Environments.	Analyze
CO4	Identify the security issues in scientific and real time applications.	Apply

22CSOE09 ARTIFICIAL INTELLIGENCE AND			ND MACHINE						
			LEARNING						
PRER	EQUI	SIT	TES:	CATEGORY	OE	Cr	edit		3
					OE	Cr	ean		3
				Hours/Week	L	T]	P	TH
					3	0	0)	3
Course	e Obje	ectiv	ves:						
1.			he various characteristics of Intelligent agen	ts, different search stra	ategies a	and repre	esent	kno	wledge in
2.			and the need for machine learning for various	problem solving					
3.	To stu	dy tl	he various supervised, semi-supervised and un	supervised learning alg	orithms	in machi	ne le	arnir	ıg
UNI	ΓΙ		INTRODUCTIO	ON		9	0	0	9
			nition – Future of Artificial Intelligence – Cha g Approach to Typical AI problems.	racteristics of Intelligen	t Agents	s–Typica	1 Inte	llige	nt Agents
UNI	ГП		PROBLEM SOLVING I	METHODS		9	0	0	9
Problen	n solvi	ing]	Methods – Search Strategies- Uninformed -	- Informed – Heuristic	cs – Lo	cal Sear	ch A	lgori	thms and
-			lems - Searching with Partial Observations -			ns – Con	straiı	nt Pr	opagation
- Backt	racking	g Se	arch – Game Playing – Optimal Decisions in O	Games – Alpha – Beta l	Pruning.				
UNIT	'III		KNOWLEDGE REPRES	ENTATION		9	0	0	9
Ontolog	gical E	ngin	cate Logic – Forward Chaining-Backward leering-Categories and Objects – Events – Moning with Default Information.						
UNIT	'IV		LEARNING PROB	LEMS		9	0	0	9
Perspec	tives a	nd I	ssues – Concept Learning – Version Spaces and	nd Candidate Elimination	ons – Inc	luctive b	ias –	Deci	ision Tree
learning	g – Rep	orese	entation – Algorithm – Heuristic Space Search						
UNIT	T V NEURAL NETWORKS AND GENETIC ALGORITHMS 9 0 0 9								
			Representation – Problems – Perceptrons – I					_	
		pics	- Genetic Algorithms - Hypothesis Space Se	earch – Genetic Program	mming -	- Models	of E	Evalu	ation and
Learnin	ıg.				=	D . T	\		D
]	rotal (4	5 L)=	=45	Periods

Text	Books:
1.	S. Russell and P. Norvig, "Artificial Intelligence: A Modern Approach", Prentice Hall, Third Edition, 2009
2.	I. Bratko, —Prolog: Programming for Artificial Intelligence, Fourth edition, Addison-Wesley Educational Publishers Inc., 2011
3.	Tom M. Mitchell, —Machine Learning, McGraw-Hill Education (India) Private Limited, 2013.
Refer	rence Books:
1.	M. Tim Jones, —Artificial Intelligence: A Systems Approach(Computer Science) , Jones and Bartlett Publishers, Inc.; First Edition, 2008
2.	Nils J. Nilsson, —The Quest for Artificial Intelligencel, Cambridge University Press, 2009
3.	William F. Clocksin and Christopher S. Mellish, Programming in Prolog: Using the ISO Standard, Fifth Edition, Springer, 2003

E-Re	ferences:
1.	https://builtin.com/artificial-intelligence
2.	https://science.howstuffworks.com/robot6.htm
3.	https://onlinecourses.nptel.ac.in/noc18_cs40/preview, (Prof. Sudeshna Sarkar,IIT KHARAGPUR)
4.	Shai Shalev-Shwartz, Shai Ben-David, Understanding Machine Learning From Theory to Algorithms, Cambridge University Press, 2014
5.	Machine Learning. Tom Mitchell. First Edition, McGraw- Hill, 1997

	RSE OUTCOMES: completion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Use appropriate search algorithms for any AI problem	Apply
CO2	Represent a problem using first order and predicate logic	Understand
CO3	Differentiate between supervised, unsupervised, semi-supervised machine learning approaches	Analyze
CO4	Discuss the decision tree algorithm and identity and overcome the problem of over fitting	Apply

22EC	COE01	FUNDAMENTALS OF ELECTRON DEVI	CES	OPEN ELECTIV					
PRER	EQUISI	ΓES	CATEGORY	OE	Cree	dit	3		
			** ***	L	T	P	TH		
			Hours/Week	3	0	0	3		
Course	e Object	ives:							
1.	To und circuits	erstand the fundamentals of electron devices and apply the k	knowledge of thes	e devic	es in e	elect	ronic		
2.		gn and analyse single stage and multistage amplifier circuits	·						
3.	To und	erstand and classify different kinds of power and feedback a	mplifiers.						
Unit I	SE	MICONDUCTOR DIODE		9	0	0	9		
		de, Current equations, Energy Band diagram, Diffusion and o							
		tics, Transition and Diffusion Capacitances, Switching Ch	aracteristics, Brea	akdown	in Pl	V Ju	nction		
Diodes									
Unit 1	II BI	POLAR JUNCTION TRANSISTORS		9	0	0	9		
		erations-Early effect-Current equations — Input and Output	characteristics of	CE, CI	3, CC	– Hy	brid -		
p mode	el – h-par	ameter model, Multi Emitter Transistor.							
Unit 1	III FIE	LD EFFECT TRANSISTORS		9	0	0	9		
JFET		n and Transfer characteristics,-Current equations-Pinch off	voltage and its si	gnifica	nce- N	1OS	FET-		
Chara		- Threshold voltage, D-MOSFET, E-MOSFET- Characteri							
IFET	IV CDI	ECIAL CEMICONDUCTOD DEVICES		Δ.	Ι Λ	Λ	9		
	Unit IV SPECIAL SEMICONDUCTOR DEVICES 9 0 0								
Metal-Semiconductor Junction- MESFET, FINFET, PINFET, CNTFET, DUAL GATE MOSFET, Schottky barrier diode-Zener diode-Varactor diode –Tunnel diode, LASER diode.									
		·		T	1	, ,			
	Unit V POWER DEVICES AND DISPLAY DEVICES 9 0 0 9								
		e, Triac, Power BJT- Power MOSFET- DMOS-VMOS, LED), LCD, Photo trai	nsistor,	Opto	Coup	oler,		
Solar c	ell, CCD		ran-	otal (45	T)	15	wio J.		
	Total $(45L) = 45$ periods								

Text	Books:					
1.	Millman and Halkias, "Electronic Devices and Circuits", 4th Edition, McGraw Hill, 2015.					
2.	2. Salivahanan. S, Suresh Kumar. N, Vallavaraj.A, "Electronic Devices and circuits", Fourth Edition, Tata McGraw- Hill. 2016.					
Refe	erence Books:					
1.	Robert L. Boylestad and Louis Nashelsky, "Electronic Devices and Circuit Theory" Pearson Prentice Hall, 11th Edition, 2014.					
2.	Bhattacharya and Sharma, "Solid State Electronic Devices", 2nd Edition, Oxford University Press, 2014.					
3.	R.S.Sedha, "A Textbook of Electronic Devices and Circuits", 2nd Edition, S.Chand Publications, 2008.					
4.	David A. Bell, "Electronic Devices and Circuits", 5th Edition, Oxford University Press, 2008.					

E-Refe	E-References:				
1.	https://archive.nptel.ac.in/courses/108/108/108108122/				
2.	https://www.youtube.com/watch?v=qqQ8wO-lNmI				
3.	https://slideplayer.com/slide/12438044/				

Course Or Upon com	utcomes: pletion of this course, the students will be able to	Bloom's Taxonomy Mapped
CO1	Analyze the characteristics of semiconductor diodes.	Understanding
CO2	Describe the problems of Transistor circuits using model	Analysing
CO3	Analyze the knowledge of various types of FET.	Analysing
CO4	Gain a knowledge on special semiconductor devices	Understanding
CO5	Understand the knowledge on Power and Display devices.	Understanding

	COURSE ARTICULATION MATRIX														
COs/POs	PO	PO	РО	PO4	PO	РО	РО	PO	PO	PO	РО	PO	PSO	PSO	PSO
	1	2	3		5	6	7	8	9	10	11	12	1	2	3
CO1	2	3	1	-	-	-	-	-	-	-	-	-	1	-	-
CO2	2	3	1	2	-	-	-	-	-	-	-	-	2	-	-
CO3	2	3	1	3	-	-	-	-	-	-	-	-	3	-	-
CO4	1	2	1	-	-	-	1	-	-	-	1	3	3	-	1
CO5	1	3	1	1	1	-	1	-	-	-	2	3	3	1	2
Avg	1.6	2.8	1	2	2	-	2	-	-	-	1.5	3	2.4	1	1.5
	3/2/1 - indicates strength of correlation (3-High,2- Medium,1- Low)														

22E	COE02	PRINCIPLES OF MODERN COMMUNICATION	SYSTEMS	OPE	N EL	ECT	IVE
PRE	REQUI	SITES	CATEGORY	OE	Cre	dit	3
			Hours/Week	L	T	P	TH
			Hours/ Week	3	0	0	3
Cou	rse Obje	ectives:					
1.	To hav	e the knowledge of the basic concepts of AM, FM and PM.					
2.	To gair	n knowledge about different pulse modulation and digital modul	ation techniques.				
3.	To gair	n knowledge about technical information on satellite communica	ation and wireless	commu	nicatio	on	
Unit	I	FUNDAMENTALS OF ANALOG COMMUNICATION		9	0	0	9
and Com	FM - 1	odulation: Modulator and demodulator with waveforms - Phase FM transmitters and receivers (Block diagram approach of ion System (AM – FM – PM). BASICS OF DIGITAL COMMUNICATION AND PULSE	only) - Compariso	on of	variou	ıs Aı	nalog
Unit	II	MODULATION	-	9	0	0	9
Pulse	e Code	ude Modulation (PAM) – Pulse Width Modulation (PWM) – Pomodulation - Pulse Position modulation: Generation and defion System (PAM – PWM – PCM - PPM).					
Unit	III	DIGITAL MODULATION TECHNIQUES		9	0	0	9
		nift Keying (ASK) – Frequency Shift Keying (FSK) - Minimum K) – QPSK –M- ary PSK- Comparison of various Digital Com					
Unit	IV	SATELLITE COMMUNICATION		9	0	0	9
Satel	History of Satellites- Kepler's laws - Satellite Orbits-Geo synchrous Satellites - Satellite Classification - Footprints - Satellite system link models: Uplink model and down link model - Multiple Access Techniques: TDMA - FDMA-CDMA-SDMA - Comparison of Multiple Access Schemes - various satellite services.						
Unit	V	CELLULAR MOBILE COMMUNICATION		9	0	0	9
	Cellular concept - Frequency reuse-Channel Assignment Strategy - Hand off mechanism - Basic propagation models: Reflection - diffraction and scattering - Bluetooth-WLAN-Global System for Mobile Communications (GSM) –GPRS.						
	Total (45L)= 45 Periods						

Text	Books:
1.	Rappaport T.S, "Wireless Communications: Principles and Practice", 2nd Edition, Pearson Education, 2007
2.	Simon Haykin, "Communication Systems", 4th Edition, John Wiley & Sons, 2010
Refe	rence Books:
1.	Dennis Roddy, John Coolen, "Electronic Communications", Prentice Hall of India, 4th Edition.,2016
2.	H.Taub, D L Schilling and G Saha, "Principles of Communication", 3rd Edition, Pearson Education, 2007.
3.	B. P.Lathi, "Modern Analog and Digital Communication Systems", 3 rd Edition, Oxford University Press, 2007.
4.	AnokhSingh, "Principles of Communication Engineering", S.CHAND Publication, 2002

E-References:									
1.	http://www.nptelvideos.in/2012/11/communication-engineering.html								
2.	https://www.tutorialspoint.com/analog_communication/analog_communication_introduction.htm								
3.	https://ocw.mit.edu/courses/electrical-engineering-and-computer-science/6-973-communication-system-								
	design-spring-2006/lecture-notes/								

	se Outcomes: completion of this course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Understand the need for modulation and how analog modulation takes place	Understanding
CO2	Understand the features of digital communication and pulse modulation.	Understanding
CO3	Analyse various digital modulation schemes.	Analysing
CO4	Have the knowledge about satellite communication.	Remembering
CO5	Have the basics of wireless and mobile communication.	Remembering

				С	OURSI	E ART	TICUL	ATIO	N MA	TRIX					
COs/POs	PO 1	PO 2	PO 3	PO4	PO 5	PO 6	PO 7	PO 8	PO 9	PO 10	PO 11	PO 12	PSO 1	PSO 2	PSO 3
		_					,			10		12	-	_	
CO1	2	2	1	2	1	-	-	-	-	-	-	-	3	2	2
CO2	2	2	1	1	1	-	-	-	-	-	-	-	2	1	2
CO3	1	3	2	2	1	-	-	-	-	-	-	-	3	1	2
CO4	2	2	1	1	1	-	-	-	-	-	-	-	3	2	2
CO5	1	2	2	1	1	-	-	-	-	-	-	-	3	2	2
Avg	1.6	2.2	1.4	1.4	1	-	-	-	-	-	-	-	2.8	1.6	2
	•	3/2	2/1 - iı	ndicates	streng	th of c	correla	tion (3	8-High	,2- Med	ium,1-	Low)			

22ECO	E03	MICROCONTROLLERS AND ITS APPLIC	CATIONS	OPE	N EL	ECT	IVE						
PREREQ	UISITES		CATEGORY	OE	Cre	edit	3						
			** /** *	L	T	P	TH						
			Hours/Week	3	0	0	3						
Course O	bjectives					1	<u>I</u>						
1.	To lear	n microcontroller basics and get exposure to 8051 archit	ectures										
2.	To emb	To embed and program with 8051 microcontrollers											
3.	To intro	To introduce the advanced features in microcontrollers and its applications											
Unit I	INTR	ODUCTION TO 8051 MICROCONTROLLER		9	0	0	9						
architectur	es. Selec	e concepts of microprocessors, microcontrollers, RIstion of microcontrollers, variants of MCS-51 fam 151 architecture - Registers in 8051 - Pin description - 805	nily and their feat	ures.	Appli	catio	ns of						
Unit II	ASSE	MBLY LANGUAGE PROGRAMMING		9	0	0	9						
		e language, assembly language, middle-level and high- sification, syntax and function of instructions, example)51 Ad	dressi	ing n	nodes.						
Unit III	I/O P	ORT AND INTERRUPTS PROGRAMMING		9	0	0	9						
buzzer, pu	ısh-buttoı	ss. Byte size I/O, bit addressability and configuring I/O switch, relay, example programs with assembly. Poypes, IE and IP registers, enabling, disabling and priority	olling & interrupt	method	s, ex	ecuti	ng an						
Unit IV	PIC I	MICROCONTROLLERS		9	0	0	9						
		of PIC microcontrollers – PIC microcontroller familie ion word-Inside a PIC microcontroller.	s-12-bit instruction	word-1	4-bit	instr	uction						
Unit V	APPI	ICATIONS		9	0	0	9						
		segment display, LCD module, ADC 0804, wave form trol, Stepper motor, appropriate program.	generation using	DAC 0	808, 1	DC n	notor-						
			T	otal (45	(L)=	45 Pe	eriods						

Text	Books:							
1.	A.Mazidi , J.C. Mazidi&R.D.McKinlay," The 8051 Microcontroller & Embedded systems using assembly and C" (2ndEdition)							
2.	Lucio Di Jasio et.al., "PIC Microcontrollers: Know It All", Elsevier Science,2007							
Refe	rence Books:							
1.	Microcontrollers & applications, Ramani Kalpathi, & Ganesh Raja							
2.	Embedded C - Michael .J.Pont - Pearson Education -2002							
3.	I. Scott MacKenzie, Raphael CW. Phan "The 8051 Microcontroller", Pearson/Prentice Hall Publishers, 2008.							
4.	M. Mahalakshmi, "8051 Microcontroller Architecture, Programming and Application", Laxmi Publications , 2008.							
E-R	eferences:							
1.	https://nptel.ac.in/courses/108105102							
2.	https://www.youtube.com/playlist?list=PLm_MSClsnwm9hEIDpFfDnOEu-6kVnF4ug							
3.	3. http://www.satishkashyap.com/2012/02/video-lectures-on-microprocessors-and.html							

	Outcomes: completion of this course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Understand the basics of microcontroller and 8051 architectures.	Understanding
CO2	Develop programs for control applications using assembly language	Applying
CO3	Illustrate the use of interrupts service routines	Applying
CO4	Understand the PIC microcontroller architecture.	Understanding
CO5	Design microcontroller based simple real-world applications	Applying

				С	OURSI	E ART	TCUL	ATIO	N MA	TRIX					
COs/POs	PO	PO	PO	PO4	PO	PO	PO	PO	PO	PO	PO	PO	PSO	PSO	PSO
	1	2	3		5	6	7	8	9	10	11	12	1	2	3
CO1	1	2	-	2	-	2	-	-	-	-	-	-	3	-	2
CO2	1	2	-	-	-	2	-	-	-	-	-	-	-	-	1
CO3	2	2	-	3	-	1	-	-	-	-	-	-	2	-	3
CO4	1	3	-	2	-	2	-	-	-	-	-	-	2	-	1
CO5	2	3	-	1	-	2	-	-	-	-	-	-	2	-	2
Avg	1.4	2.4	-	2	-	1.8	-	-	-	-	-	1	2.25	-	1.8
		3/2	2/1 - iı	ndicates	streng	th of c	orrela	tion (3	-High	,2- Med	ium,1-	Low)			

22	ECOE04	COMPUTER NETWOR	RKS	OPEN ELECTIVE								
PRE	EREQUISI	TES	CATEGORY	OE	Cre	dit	3					
			TT /XX7 1	L	T	P	TH					
			Hours/Week	3	0	0	3					
Cou	rse Object	ives:	1									
1.	To introd	ace the basic concept in modern data communication	and computer networking.									
2.	To introd	ace the students the functions of different layers and	in - depth knowledge of data l	ink laye	r.							
3.	To make	students to get familiarized with different protocols a	and network layer components	i.								
4.	To introd	ace the basic functions of transport layer and congest	tion in networks.									
5.	To understand the concepts of various network Applications and Data security.											
Unit	t I	9	0	0	9							
		networks – Topologies – The OSI reference model - I Layer: Transmission Media – Guided media & ungu	•		del –	layeı	s and					
Unit	t II	DATA LINK LAYER		9	0	0	9					
		ntrol Functions: - Framing, Flow control, Error cor Random access, Controlled access, Channelization -										
		ternetworking, Interconnection issues, Interconnecti										
	eways.											
Unit	t III	NETWORK LAYER		9	0	0	9					
		uit switching, packet switching, message switching. Ig Algorithms - Unicast routing protocol: Distance V			P, RA	RP,	VPN.					
Unit	t IV	TRANSPORT LAYER		9	0	0	9					
		ices, Elements of Transport protocols, Connection ontrol Protocol (TCP) – Congestion Control and Qua				•)P) –					
Unit	t V	APPLICATION LAYER		9	0	0	9					
		Space (DNS) – Electronic mail (SMTP, MIME, PO ET, Network management protocol: SNMP.	P3, IMAP4) - Application pro	otocols:	WW	W, H	TTP,					
			T	otal (45	L)= 4	5 Pe	riods					

Text I	Books:
1.	Behrouz A. Foruzan, "Data communication and Networking", TMH, 4th edition, 2014.
2.	James. F. Kurouse& W. Ross, "Computer Networking: A Top down Approach Featuring", Pearson, 2020.
Refere	ence Books:
1.	LarryL.Peterson&PeterS.Davie,"ComputerNetworks",HarcourtAsiaPvt.Ltd.,SecondEdition.
2.	AndrewS.Tanenbaum, "ComputerNetworks", PHI, FourthEdition, 2003.
3.	An Engineering Approach to Computer Networks-S. Keshav, 2nd Edition, Pearson Education
4.	AjitPal, "DataCommunicationandComputerNetworks", PHI, 2014.
E-Ref	erences:
1.	https://nptel.ac.in/courses/106105183
2.	https://www.mbit.edu.in/wp-content/uploads/2020/05/Computer-Networks-5th-Edition.pdf
3.	https://www.tutorialspoint.com/data_communication_computer_network/index.htm

		Dutcomes: Appletion of this course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	:	Explain the basic concept in modern data communication and different level of layers in the protocol	Understanding
CO2	:	Analyse the functions and services of data link layer	Analysing
CO3	:	Categorize the functions and services of network layer	Understanding
CO4	:	Examine the basic functions of transport layer and congestion in networks	Understanding
CO5	:	Analyse the concepts of various network applications and data security	Analysing

				С	OURSI	E ART	TCUL	ATIO	N MA	TRIX					
COs/POs	PO	PO	PO	PO4	PO	PO	PO	PO	PO	PO	PO	PO	PSO	PSO	PSO
	1	2	3		5	6	7	8	9	10	11	12	1	2	3
CO1	2	1	1	-	1	-	-	-	-	-	-	-	2	-	1
CO2	2	1	2	-	1	-	-	-	-	-	-	-	2	1	1
CO3	2	1	1	-	-	-	-	-	-	-	-	-	3	1	2
CO4	3	2	1	-	2	-	-	-	-	-	-	-	2	-	2
CO5	2	1	1	-	1	-	-	-	-	-	-	-	1	1	1
Avg	2.2	1.2	1.2	-	1.25	-	-	-	-	-	-	-	2	1	1.4
		3/2	2/1 - iı	ndicates	streng	th of c	orrela	tion (3	8-High	,2- Med	ium,1-	- Low)			

22ECOE05	BASICS OF EMBEDDE	D SYSTEMS	OPE	N EL	ECT	IVE							
	1	CATEGORY	OE	Credit		3							
PREREQUISI	ΓES	TT // // /	L	T	P	TH							
		Hours/Week	3	0	0	3							
Course Object	ves:			•	•								
1. To im	art knowledge on embedded system architectur	e and embedded development Str	ategies										
	erstand the bus Communication in processors a	nd peripheral interfacing											
	3. To understand basics of Real Time Operating System												
Unit I	Unit I BASICS OF EMBEDDED SYSTEMS												
	Fundamental Components of Embedded Syste												
	anguages - Recent Trends in Embedded Systems		tems - E	mbed	ded D	esign							
· · · · · · · · · · · · · · · · · · ·	ection Process - Hardware Software Partitioning					_							
Unit II	MEMORY MANAGEMENT AND INTERR	UPTS	9	0	0	9							
	Procedure - Types of Memory - Memory Mana												
	ypes of Interrupts - Interrupt Latency - Interrupt	t Priority – Programmable Interru	pt Cont	coller	s - Int	errupt							
Service Routine					Τ.	Τ.							
	COMMUNICATION INTERFACES		9	0	0	9							
	s - Serial Interfaces - RS232/UART - RS422/RS	S485 - I2C Interface - SPI Interfa	ce - USI	3 - C	AN - 1	IRDA							
	E 802.11 – Bluetooth				Ι.	Τ							
	REAL TIME OPERATING SYSTEMS		9	0	0	9							
	cepts - Task Management - Task Scheduling -												
	ent Driven Scheduling - Resource Sharing - Prio		y Ceilin	g Pro	cocol	- Inter							
	eation - Mutex - Semaphores - Message Queues	- Timers - Commercial RTOS.			Τ.	Τ.							
	VALIDATION AND DEBUGGING		9	0	0	9							
	Machines - Validation Types and Methods - H												
	gers and Debug Kernels - ROM Emulator - Lo				- InC	ircuit							
Emulator CASI	STUDY: RFID Systems - GPS Navigation Sys	•			45.5								
1			Total (45L)= 45 Periods										

Text Bo	ooks:
1	Sriram VIyer and Pankaj Gupta, —Embedded Real-time Systems Programmingl, Tata McGraw-Hill
1.	Publishing Company Limited, New Delhi, 2006.
2.	Arnold S Berger, —Embedded Systems Design - An Introduction to Processes, Tools and Techniques,
۷.	Elsevier, New Delhi, 2011.
Referei	nce Books:
1.	Prasad K V K K, —Embedded/Real-Time Systems: Concepts, Design and Programming – The Ultimate
	Reference, Himal Impressions, New Delhi, 2003
2.	Heath, "Embedded Systems Design", Newnes an Imprint of Elsevier, Massachusetts, 2003.
3.	Tammy Noergaard, "Embedded Systems Architecturel, Newnes an Imprint of Elsevier,
	Massachusetts, 2006.
4.	Raj Kamal, 'Embedded System-Architecture, Programming, Design', McGraw Hill, 2013
E-Refe	rences:
1.	https://lecturenotes.in/subject/225/embedded-system-es
2.	https://nptel.ac.in/courses/108102045/19
3.	https://www.coursera.org/learn/introduction-embedded-systems.

Course O Upon com	utcomes: pletion of this course, the students will be able to	Bloom's Taxonomy Mapped
CO1	Outline the concepts of embedded systems	Remembering
CO2	Understand the concept of memory management system and interrupts.	Understanding
CO3	Know the importance of interfaces.	Understanding
CO4	Understand real time operating system concepts.	Understanding
CO5	To realize the applications of validation and debugging.	Applying

				С	OURSI	E ART	TCUL	ATIO	N MA	TRIX					
COs/POs	PO	PO	PO	PO4	PO	PO	PO	PO	PO	PO	PO	PO	PSO	PSO	PSO
	1	2	3		5	6	7	8	9	10	11	12	1	2	3
CO1	3	3	1	3	3	3	2	-	-	-	3	3	3	-	2
CO2	3	3	2	3	3	3	2	-	-	-	3	3	3	-	2
CO3	3	3	3	3	3	3	2	-	-	-	3	3	3	-	2
CO4	3	3	2	3	3	3	2	ı	-	-	2	3	3	-	2
CO5	3	3	2	3	3	3	2	-	-	-	3	3	3	-	2
Avg	3	3	2	3	3	3	2	ı	-	-	2.8	3	3	-	2
		3/2	2/1 - ir	ndicates	streng	th of c	orrela	tion (3	8-High	,2- Med	ium,1-	Low)			

22ECOE06	BASICS OF INTERNET OF THINGS	OPI	EN I	ELEC	CTI	VE
PREREQUISITE	CATEGORY	OE	(Credi	t	3
	Hours/Week	L	7.	Т	P	ТН
		3	(0	0	3
Course Objectives	:					
1. To understa	nd the vision of M2M to IOT.					
	inderstanding of IOT market perspective.					
	cnowledge on Io T Technology Fundamentals and applications					
	all system using Raspberry Pi.					,
	O IOT – THE VISION		9	0	0	9
	n M2M to Io T- M2M towards Io T: M2M Communication - The global co	ontext - A	A use	e case	e exa	mple
 Differing Charac 						
TI 1/ TT BEAR OF	O IOT A MADIZET DEDCDECTIVE					•
	O IOT – A MARKET PERSPECTIVE		9	0	0	9
Introduction - Som	e Definitions - M2M Value Chains - Io T Value Chains - An emerging in	ndustrial	stru	cture	for	Io T-
Introduction - Som International drive	e Definitions - M2M Value Chains – Io T Value Chains - An emerging in global value chain and global information monopolies - M2M to Io T-An	ndustrial n Archite	l stru	cture	for	Io T-iew –
Introduction - Som International drive Building an archit	e Definitions - M2M Value Chains - Io T Value Chains - An emerging in	ndustrial n Archite	l stru	cture	for	Io T-iew –
Introduction - Som International driver Building an archit considerations.	e Definitions - M2M Value Chains – Io T Value Chains - An emerging in global value chain and global information monopolies - M2M to Io T-An ecture - Main design principles and needed capabilities - An Io T architecture	ndustrial n Archite tecture (l stru ectur outlii	cture ral O	for vervi	Io T- iew – dards
Introduction - Som International driver Building an archit considerations. Unit III IOT TE	e Definitions - M2M Value Chains – Io T Value Chains - An emerging in a global value chain and global information monopolies - M2M to Io T-An exture - Main design principles and needed capabilities - An Io T archi CHNOLOGY FUNDAMENTALS	ndustrial n Archite tecture (stru ectur outlii	cture ral Or ne -	for vervi Stan	Io T- iew – dards
Introduction - Som International drive Building an archit considerations. Unit III IOT TE Io T Enabling techn	e Definitions - M2M Value Chains - Io T Value Chains - An emerging in a global value chain and global information monopolies - M2M to Io T-An ecture - Main design principles and needed capabilities - An Io T architecture - Io T levels and deployment templates - Devices and gateways - Devices	ndustrial n Archite tecture (stru ectur outlii	cture ral Or ne -	for vervi Stan	Io T- iew – dards
Introduction - Som International drive: Building an archit considerations. Unit III IOT TE Io T Enabling techn processes in Io T -	e Definitions - M2M Value Chains — Io T Value Chains - An emerging in a global value chain and global information monopolies - M2M to Io T-An ecture - Main design principles and needed capabilities - An Io T archively CHNOLOGY FUNDAMENTALS and ologies — Io T levels and deployment templates - Devices and gateways - Deverything as a Service (XaaS) - M2M and Io T Analytics.	ndustrial n Archite tecture (stru ectur outlin 9	cture ral O ne - 0 nent -	for vervi Stan 0	Io T- iew – dards 9 siness
Introduction - Som International driver Building an archit considerations. Unit III IOT THE IOT Enabling techn processes in IoT - Unit IV BUILD	e Definitions - M2M Value Chains – Io T Value Chains - An emerging in a global value chain and global information monopolies - M2M to Io T-An ecture - Main design principles and needed capabilities - An Io T archive CHNOLOGY FUNDAMENTALS alologies – Io T levels and deployment templates - Devices and gateways - Deverything as a Service (XaaS) - M2M and Io T Analytics.	ndustrial n Archite tecture of gata mana	stru ectur outlin 9 agen	octure ral Orne - 0 nent -	for vervi Stan 0 Bus	Io T- iew – dards 9 siness
Introduction - Som International drive Building an archit considerations. Unit III IOT TE IO T Enabling techn processes in Io T - Unit IV BUILD IO T Systems-Log	e Definitions - M2M Value Chains – Io T Value Chains - An emerging in a global value chain and global information monopolies - M2M to Io T-An ecture - Main design principles and needed capabilities - An Io T archive CHNOLOGY FUNDAMENTALS cologies – Io T levels and deployment templates - Devices and gateways - Deverything as a Service (XaaS) - M2M and Io T Analytics. ING IOT WITH HARDWARE PLATFORMS cal Design using Python –Io T Physical Devices and End Points- Io T	ndustrial n Archite tecture of pata mana	stru ectur outlin g agen - Ra	octure ral Orne - 0 nent -	for vervi Stan 0 Bus	Io T- iew – dards 9 siness
Introduction - Som International drive: Building an archit considerations. Unit III IOT TE Io T Enabling techn processes in Io T - Unit IV BUILD Io T Systems-Log Interfaces - Progra	e Definitions - M2M Value Chains – Io T Value Chains - An emerging in a global value chain and global information monopolies - M2M to Io T-An ecture - Main design principles and needed capabilities - An Io T archive CHNOLOGY FUNDAMENTALS Tologies – Io T levels and deployment templates - Devices and gateways - Deverything as a Service (XaaS) - M2M and Io T Analytics. TORIOT WITH HARDWARE PLATFORMS Tologies – Io T Physical Devices and End Points- Io T mming – Other Io T devices – Io T Reference Model - Real World Design	ndustrial n Archite tecture of pata mana general of Device Constrain	stru ectur outlin g agen - Ra ints.	octure ral Orne - 0 nent - 0 aspber	for vervi	Io T- iew – dards 9 siness 9
Introduction - Som International drive: Building an archit considerations. Unit III IOT TE Io T Enabling techn processes in Io T - Unit IV BUILD Io T Systems-Log Interfaces - Progra Unit V IOT US	e Definitions - M2M Value Chains – Io T Value Chains - An emerging in a global value chain and global information monopolies - M2M to Io T-An ecture - Main design principles and needed capabilities - An Io T archive CHNOLOGY FUNDAMENTALS cologies – Io T levels and deployment templates - Devices and gateways - Deverything as a Service (XaaS) - M2M and Io T Analytics. ING IOT WITH HARDWARE PLATFORMS cal Design using Python –Io T Physical Devices and End Points- Io T mming – Other Io T devices – Io T Reference Model - Real World Design E CASES AND APPLICATIONS	ndustrial n Archite tecture of pata mana Device Constrai	stru ectur outlin agen - Ra ints.	octure ral Orne - 0 nent - 0 aspber	for vervi	Io T- iew – dards 9 siness
Introduction - Som International driver Building an archit considerations. Unit III IOT TE IO T Enabling techn processes in Io T - Unit IV BUILD IO T Systems-Log Interfaces - Progra Unit V IOT US Home automation-	e Definitions - M2M Value Chains - Io T Value Chains - An emerging in a global value chain and global information monopolies - M2M to Io T-An ecture - Main design principles and needed capabilities - An Io T archive CHNOLOGY FUNDAMENTALS cologies - Io T levels and deployment templates - Devices and gateways - Deverything as a Service (XaaS) - M2M and Io T Analytics. ING IOT WITH HARDWARE PLATFORMS cal Design using Python -Io T Physical Devices and End Points- Io T mming - Other Io T devices - Io T Reference Model - Real World Design E CASES AND APPLICATIONS Automatic lighting-Home intrusion detection- Cities-Smart parking - Environment of the color of the	ndustrial n Archite tecture of gata mana Device Constrai	struecturoutlinagen 9 - Raints. 9 - Value - Water	octure ral Orne - 0 nent - 0 aspber 0 eather	for vervi	Io T- iew – dards 9 siness 9 1 -
Introduction - Som International drive Building an archit considerations. Unit III IOT TE IO T Enabling techn processes in Io T - Unit IV BUILD IO T Systems-Log Interfaces - Progra Unit V IOT US Home automation- monitoring system	e Definitions - M2M Value Chains - Io T Value Chains - An emerging in a global value chain and global information monopolies - M2M to Io T-An ecture - Main design principles and needed capabilities - An Io T archive CHNOLOGY FUNDAMENTALS Tologies - Io T levels and deployment templates - Devices and gateways - Deverything as a Service (XaaS) - M2M and Io T Analytics. TOT WITH HARDWARE PLATFORMS TOT WITH HARDWARE PLAT	ndustrial n Archite tecture of pata mana Device Constrai	struecturoutlin g agen - Ra ints. y t - Womme	one - one - one - one - one - one	for vervistan O Bus O rry F O Bus O Bus	Io T- iew – dards 9 siness 9 Pi -
Introduction - Som International drive: Building an archit considerations. Unit III IOT TE Io T Enabling techn processes in Io T - Unit IV BUILD Io T Systems-Log Interfaces - Progra Unit V IOT US Home automation- monitoring system Automation - Intro	e Definitions - M2M Value Chains - Io T Value Chains - An emerging in a global value chain and global information monopolies - M2M to Io T-An ecture - Main design principles and needed capabilities - An Io T archive CHNOLOGY FUNDAMENTALS cologies - Io T levels and deployment templates - Devices and gateways - Deverything as a Service (XaaS) - M2M and Io T Analytics. ING IOT WITH HARDWARE PLATFORMS cal Design using Python -Io T Physical Devices and End Points- Io T mming - Other Io T devices - Io T Reference Model - Real World Design E CASES AND APPLICATIONS Automatic lighting-Home intrusion detection- Cities-Smart parking - Environment of the color of the	ndustrial n Archite tecture of pata mana Device Constrai	struecturoutlin g agen - Ra ints. y t - Womme	one - one - one - one - one - one	for vervistan O Bus O rry F O Bus O Bus	Io T- iew – dards 9 siness 9 Pi -

Text	Books:
	Jan Holler, VlasiosTsiatsis, Catherine Mulligan, Stefan Avesand, StamatisKarnouskos, David Boyle, "From
1.	Machine-to-Machine to the Internet of Things: Introduction to a New Age of Intelligence", 1st Edition, Academic
	Press, 2014.
2.	Arshdeep Bahga, Vijay Madisetti, "Internet of Things-A hands-on approach", Universities Press, 2015
Refer	rence Books:
1.	Olivier Hersent, davidBoswarthick, Omar Elloumi, 'The Internet of Things Applications to the smart grid
	building automation', John Wiley & Sons, 2012
2.	Francis daCosta, "Rethinking the Internet of Things: A Scalable Approach to Connecting Everything", 1st Edition,
	Apress Publications, 2013
3.	HakimaChaouchi, 'The Internet of Things Connecting Objects', John Wiley & Sons, 2010.
4.	FabriceTheoleyr, Ai-Chun Pang, 'Internet of Things and M2M Communications', River Publishers, 2013.
E-Re	ferences:
1.	https://nptel.ac.in/courses/106105166
2.	https://onlineitguru.com/IoT-online-training.html
3.	https://onlinecourses.nptel.ac.in/noc22_cs53/preview

		Outcomes: upper on this course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	:	Understand the vision of IoT from a global context.	Understanding
CO2	:	Determine the Market perspective of IoT.	Remembering
CO3	:	Understand the IoT technology fundamentals.	Understanding
CO4	:	Build small system using Raspberry Pi.	Applying
CO5	:	Analyse applications of IoT and case studies	Analysing

				С	OURSI	E ART	TCUL	ATIO	N MA	TRIX					
COs/POs	PO	PO	PO	PO4	PO	PO	РО	PO	PO	PO	PO	PO	PSO	PSO	PSO
	1	2	3		5	6	7	8	9	10	11	12	1	2	3
CO1	-	1	-	-	2	-	-	-	-	-	-	-	-	-	-
CO2	2	2	2	2	2	-	-	-	-	-	-	1	1	-	-
CO3	2	2	2	2	2	-	-	-	-	-	-	1	1	-	-
CO4	2	2	2	2	2	-	-	-	-	-	2	2	2	-	-
CO5	2	2	2	2	2	-	-	-	-	-	2	-	2	-	2
Avg	2	1.8	2	2	2	-	-	-	-	-	2	1.3	1.5	-	2
		3/2	2/1 - iı	ndicates	streng	th of c	correla	tion (3	8-High	,2- Med	ium,1-	Low)	•		

22F	ECOE07	BASICS OF ARTIFICIAL INTELLIGENCE	E	OPE	N E	LEC	CTI	VE
PRE	REQU	ISITES	CATEGORY	OE	C	redi	it	3
			Hours/Week	L	r	Г	P	T H
				3	()	0	3
	rse Obj							
1.		about uninformed and Heuristic search techniques.						
2.		arn techniques for reasoning under uncertainty						
3.		ace Machine Learning and supervised learning algorithms						
4.		about ensemble and unsupervised learning algorithms.						
5.		the basics of deep learning using neural networks. PROBLEM SOLVING						
Unit		9	0	0	9			
		to AI - AI applications - problem solving agents - search algor						
		arch strategies - local search and optimization problems -adve	rsarial search –	constrai	ng	satis	sfact	ion
prob	lems(CS	SP).						
Unit		PROBABILISTIC REASONING			9	0	0	9
		r uncertainty - Bayesian inference - naïve bayes models. Probab	ilistic reasoning -	- Bayes	ian	netv	vork	:s –
exac		ce in BN – approximate inference in BN – causal networks.						
Unit	-	SUPERVISED LEARNING			9	0	0	9
Intro	duction	to machine learning - Linear Regression Models: Least squares, sin	gle & multiple var	riables,	Bay	esia	n lin	ear
		radient descent, Linear Classification Models: Discriminant function						
		ression, Probabilistic generative model - Naive Bayes, Maximu	um margin classi	ifier –	Sup	port	vec	ctor
		cision Tree.						
Unit		ENSEMBLE TECHNIQUES AND UNSUPERVISED LEARNI			9	0	0	9
Com		nultiple learners: Model combination schemes, Voting, Ensemble I	earning - bagging	g, boosti	ing,	stac	king	5,
	mervice	d learning: K-means, Instance Based Learning: KNN						
Unsu	_	NEURAL NETWORKS					^	
Unsu Unit	V				9	0	0	9
Unsu Unit Perce	eptron -	Multilayer perceptron, activation functions, network training – gr		timizati	on -	- stc	ocha	stic
Unsu Unit Perce gradi	eptron -	Multilayer perceptron, activation functions, network training – greent, error backpropagation, from shallow networks to deep network		timizati	on -	- stc	ocha	stic
Unsu Unit Perce gradi	eptron -	Multilayer perceptron, activation functions, network training – gr	orks –Unit saturat	timizati	on -	- stc	ocha nish	stic

Text	Books:								
1	Stuart Russell and Peter Norvig, "Artificial Intelligence - A Modern Approach", Fourth Edition, Pearson								
1.	Education, 2021								
2.	Christopher M. Bishop, "Pattern Recognition and Machine Learning", Springer, 2006								
Refe	rence Books:								
1.	Ethem Alpaydin, "Introduction to Machine Learning", MIT Press, Fourth Edition, 2020.								
2.	Kevin Night, Elaine Rich, and Nair B., "Artificial Intelligence", McGraw Hill, 2008								
3.	Patrick H. Winston, "Artificial Intelligence", Third Edition, Pearson Education, 2006								
4.	Tom Mitchell, "Machine Learning", McGraw Hill, 3rd Edition, 1997.								
E-R	eferences:								
1.	https://machinelearningmastery.com/								
2.	https://ai.google/education/								
3.	https://in.coursera.org/learn/machine-learning								

Course	Outcomes:	
Upon con	mpletion of this course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Use appropriate search algorithms for problem solving	Understanding
CO2	Apply reasoning under uncertainty	Applying
CO3	Build supervised learning models	Applying
CO4	Build ensembling and unsupervised models	Applying
CO5	Build deep learning neural network models	Applying

				С	OURSI	E ART	TCUL	ATIO	N MA	TRIX					
COs/POs	PO	PO	PO	PO4	PO	PO	PO	PO	PO	PO	PO	PO	PSO	PSO	PSO
	1	2	3		5	6	7	8	9	10	11	12	1	2	3
CO1	2	1	2	1	1	-	-	-	-	-	1	1	2	2	2
CO2	2	1	2	1	1	-	-	-	-	-	1	1	2	2	2
CO3	2	2	3	2	1	-	-	-	-	-	3	2	2	2	2
CO4	2	2	2	1	1	-	-	-	-	-	3	2	2	2	2
CO5	2	2	3	2	1	-	-	-	-	-	3	2	2	2	2
Avg	2	1.6	2.4	1.4	1	-	-	-	-	-	2.2	1.6	2	2	2
		3/2	2/1 - ir	ndicates	streng	th of c	orrela	tion (3	8-High	,2- Med	ium,1-	Low)	•	•	

22EEOE01	RENEWABLE ENERGY SOURCES		SEM	EST	ER	VI / VII
PREREQUI	SITES	CATEGORY	OE	Cro	edit	3
Basic Electri	cal and Electronics Engineering	Hours/Week	L 3	T 0	P 0	TH 3
Course Obje	ectives:					
1. To in	part knowledge on the different renewable energy sources and te	chnologies.				
UNIT I	INTRODUCTION		9	0	0	9
Energy System		ts / Applications –	Econoi	nics o	of Ren	T
UNIT II	SOLAR ENERGY		9	0	0	9
Applications -	on – Measurements of Solar Radiation – Flat Plate and Concert-Solar Thermal Power Generation – Fundamentals of Solar Photheration – Solar PV Applications.					
UNIT III	WIND ENERGY		9	0	0	9
	d Energy Estimation – Types of Wind Energy Systems – Perforator – Safety and Environmental Aspects.	rmance – Site Sel	ection -	– Det	ails o	f Wind
UNIT IV	BIO – ENERGY		9	0	0	9
Biomass Dire	ct Combustion – Biomass Gasifiers – Biogas Plants – Digest	ters – Ethanol Pro	oductio	n – 1	Bio D	Diesel –
Cogeneration	- Biomass Applications.					
UNIT V	OTHER RENEWABLE ENERGY SOURCES		9	0	0	9
	 Wave Energy – Open and Closed Ocean Thermal Energy C nergy – Hydrogen and Storage – Fuel Cell Systems – Hybrid Sys 		Cycle	$s - \overline{S}$	mall	Hydro-
]		Total (45L+0	T) =	45 P	eriods

Text Books:								
1.	Rai. G.D., "Non-Conventional Energy Sources", Khanna Publishers, New Delhi, 2011.							
2.	Twidell, J.W. & Weir, A., "Renewable Energy Sources", EFN Spon Ltd., UK, 2006.							
3.	Godfrey Boyle, "Renewable Energy, Power for A Sustainable Future", Oxford University Press, U.K., 1996.							
Reference B	Reference Books:							
1.	Chetan Singh Solanki, Solar Photovoltaics, "Fundamentals, Technologies and Applications", PHI Learning Private Limited, New Delhi, 2009.							
2.	Tiwari. G.N., Solar Energy – "Fundamentals Design, Modelling & Applications", Narosa Publishing House, New Delhi, 2002.							
3.	Freris. L.L., "Wind Energy Conversion Systems", Prentice Hall, UK, 1990.							
4.	Johnson Gary, L. "Wind Energy Systems", Prentice Hall, New York, 1985							
5.	David M. Mousdale – "Introduction to Biofuels", CRC Press, Taylor & Francis Group, USA 2010							

Course Oute Upon complet		Bloom's Taxonomy Mapped				
CO1	:	Recall the available renewable Energy Sources	L1: Remembering			
CO2	:	Illustrate the types of generators.	L4: Analysing			
CO3	:	Apply different types of mechanism for energy conversion.	L3: Applying			
CO4	:	Analyze the benefits and challenges in harnessing renewable Energy.	L4: Analysing			
CO5	:	L2: Understanding				

COUR	COURSE ARTICULATION MATRIX														
COs/ POs	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	PO 7	PO 8	PO 9	PO 10	PO 11	PO 12	PS O1	PS O2	PS O3
CO1	2	1	1	1	2	1	1	1	1	1	1	1	1	1	1
CO2	3	1	1	3	1	1	1	1	1	1	1	1	2	1	1
CO3	1	2	2	1	1	1	1	1	1	1	1	1	2	1	1
CO4	3	1	1	3	2	1	1	1	1	1	1	1	2	1	1
CO5	2	1	1	2	1	1	2	1	1	1	1	1	2	1	1
Avg	2.2	1.2	1.2	2	1.4	1	1.2	1	1	1	1	1	1.7	1.2	1
			3/2/1-i	ndicate	s streng	th of co	rrelatio	n (3- Hi	gh, 2-M	ledium,	1- Low)			

22EEOE02	INDUSTRIAL DRIVES		SEM	EST	ER	VI / VII
PREREQUIS	ITES	CATEGORY	OE	Cro	edit	3
Power Electronic	cs, and Electrical Machines	Hours/Week	L 3	T 0	P 0	TH 3
Course Objec	tives:					
1. To understa	and the basic components of electric drive system,					
2. To analyze	the operation and performance of the chopper fed DCdrive,					
3. To understa	and the operation and performance of AC motor drives					
4. To understa	and the advanced techniques in the control of industrial drive	es.				
Unit I BA	SICS OF ELECTRIC DRIVE		9	0	0	9
	ntroduction and advantages, types and choice of electric driv	ve, components of ele	ectric dr	ive s	ystem	, motor
•	fication continuous, short time and intermittent duty, spee	d-torque characteris	tics of	DC a	nd In	duction
motor drive.						
	DRIVES		9	0	0	9
Review of dc ch	opper and duty ratio control, chopper fed dc motor for speed		peratio	n of a	a chop	per fed
Review of dc ch			peratio	n of a	a chop	per fed
Review of dc ch	opper and duty ratio control, chopper fed dc motor for speed		peratio	n of a	a chop	per fed
Review of dc che drive, armature of starting,	opper and duty ratio control, chopper fed dc motor for speed current waveform and ripple, calculation of losses in dc motor	or and chopper, effic	operationiency of	on of a	a chop lrive,	per fed smooth
Review of dc chedrive, armature of starting, Review of motor	opper and duty ratio control, chopper fed dc motor for speed courrent waveform and ripple, calculation of losses in dc motor oring and generating modes operation of a separately excite	or and chopper, efficed dc machine, four	operationiency of	on of a f dc d	a chop lrive,	per fed smooth
Review of dc che drive, armature of starting, Review of motor machine; single-	opper and duty ratio control, chopper fed dc motor for speed ocurrent waveform and ripple, calculation of losses in dc motor oring and generating modes operation of a separately excited equadrant, two-quadrant and four-quadrant choppers; steady-	or and chopper, efficed dc machine, four	operationiency of	on of a f dc d	a chop lrive,	per fed smooth
Review of dc chedrive, armature of starting, Review of motor	opper and duty ratio control, chopper fed dc motor for speed ocurrent waveform and ripple, calculation of losses in dc motor oring and generating modes operation of a separately excited equadrant, two-quadrant and four-quadrant choppers; steady-rative braking	or and chopper, efficed dc machine, four	operationiency of	on of a f dc d nt ope	a chop lrive,	per fed smooth
Review of dc chedrive, armature of starting, Review of motor machine; singledc drive, regenerated Unit III AC	opper and duty ratio control, chopper fed dc motor for speed ocurrent waveform and ripple, calculation of losses in dc motor oring and generating modes operation of a separately excite quadrant, two-quadrant and four-quadrant choppers; steady-rative braking DRIVES	or and chopper, efficed dc machine, four- estate operation of m	operationiency of quadranulti-qua	on of a f dc d d nt open drant	a chop lrive, seration t chop	per fed smooth n of dc per fed
Review of dc chedrive, armature of starting, Review of motor machine; singledc drive, regenerated Unit III AC Review of induced to the control of the contro	current waveform and ripple, calculation of losses in dc motor for speed of current waveform and ripple, calculation of losses in dc motor or and generating modes operation of a separately excited equadrant, two-quadrant and four-quadrant choppers; steady-rative braking DRIVES Stion motor equivalent circuit and torque-speed characteristics.	or and chopper, efficed dc machine, four state operation of me, variation of torque	operation iency of quadranulti-qua	on of a f dc d d d d d d d d d d d d d d d d d	a chop lrive, seration t chop 0	per fed smooth of dc per fed 9
Review of dc chedrive, armature of starting, Review of motor machine; singlede drive, regener Unit III AC Review of inductive to the control of the control	opper and duty ratio control, chopper fed dc motor for speed of current waveform and ripple, calculation of losses in dc motor oring and generating modes operation of a separately excited equadrant, two-quadrant and four-quadrant choppers; steadynative braking DRIVES Stion motor equivalent circuit and torque-speed characteristic frequency and applied voltage and frequency, typical torque-	or and chopper, efficed dc machine, four state operation of me, variation of torque	operation iency of quadranulti-qua	on of a f dc d d d d d d d d d d d d d d d d d	a chop lrive, seration t chop 0	per fed smooth of dc per fed 9
Review of dc chedrive, armature of starting, Review of motor machine; singledc drive, regenerated the control of the control o	current waveform and ripple, calculation of losses in dc motor for speed of current waveform and ripple, calculation of losses in dc motor or and generating modes operation of a separately excited equadrant, two-quadrant and four-quadrant choppers; steady-rative braking DRIVES Stion motor equivalent circuit and torque-speed characteristics.	or and chopper, efficed dc machine, four state operation of me, variation of torque	operation iency of quadranulti-qua	on of a f dc d d d d d d d d d d d d d d d d d	a chop lrive, seration t chop 0	per fed smooth of dc per fed 9
Review of dc chedrive, armature of starting, Review of motor machine; singledc drive, regenerated the control of the control o	opper and duty ratio control, chopper fed dc motor for speed of current waveform and ripple, calculation of losses in dc motor oring and generating modes operation of a separately excited equadrant, two-quadrant and four-quadrant choppers; steadynative braking DRIVES Stion motor equivalent circuit and torque-speed characteristic frequency and applied voltage and frequency, typical torque-lux operation, flux weakening operation. NTROL OF DC AND AC DRIVES	ed dc machine, four estate operation of m e, variation of torque espeed curves of fan a	pperation iency of quadranulti-quadranulti	on of a f de d d d d d d d d d d d d d d d d d	a chop drive, seration t chop with ds, op	per fed smooth n of dc per fed 9 applied erating
Review of dc chedrive, armature of starting, Review of motor machine; single-dc drive, regenerated drive, re	opper and duty ratio control, chopper fed dc motor for speed ocurrent waveform and ripple, calculation of losses in dc motor oring and generating modes operation of a separately excited equadrant, two-quadrant and four-quadrant choppers; steadynative braking DRIVES Stion motor equivalent circuit and torque-speed characteristic frequency and applied voltage and frequency, typical torque-lux operation, flux weakening operation. NTROL OF DC AND AC DRIVES et of DC drive, inner current loop and outer speed loop, dynare	or and chopper, efficed dc machine, four estate operation of mes, variation of torque espeed curves of fan a mic model of dc motor.	pperation iency of quadranulti-qualulti	on of a f dc d d d d d d d d d d d d d d d d d	a chop lrive, seration t chop o with ads, op	per fed smooth n of dc per fed 9 applied erating 9 ons and
Review of dc chedrive, armature of starting, Review of motor machine; single-dc drive, regenerated drive, re	opper and duty ratio control, chopper fed dc motor for speed of current waveform and ripple, calculation of losses in dc motor ring and generating modes operation of a separately excited equadrant, two-quadrant and four-quadrant choppers; steadynative braking DRIVES Setion motor equivalent circuit and torque-speed characteristic frequency and applied voltage and frequency, typical torque-lux operation, flux weakening operation. NTROL OF DC AND AC DRIVES To of DC drive, inner current loop and outer speed loop, dynamics, modeling of chopper as gain with switching delay, plant to	ed dc machine, four estate operation of mestate operation of messpeed curves of fan a mic model of dc motoransfer function, for	pperation iency of quadranulti-qualulti	on of a f dc d d d d d d d d d d d d d d d d d	a chop lrive, seration t chop o with ads, op	per fed smooth n of dc per fed 9 applied erating 9 ons and
Review of dc chedrive, armature of starting, Review of motor machine; single-dc drive, regenerated drive, re	current waveform and ripple, calculation of losses in dc motor of a separately excited equadrant, two-quadrant and four-quadrant choppers; steadynative braking DRIVES Etion motor equivalent circuit and torque-speed characteristic frequency and applied voltage and frequency, typical torque-lux operation, flux weakening operation. NTROL OF DC AND AC DRIVES et of DC drive, inner current loop and outer speed loop, dynamics, modeling of chopper as gain with switching delay, plant to ication and design, speed controller specification and design.	ed dc machine, four- estate operation of m e, variation of torque espeed curves of fan a mic model of dc motoransfer function, for	pperation iency of quadranulti-qualulti	on of a f dc d d d d d d d d d d d d d d d d d	eration t chop with ds, op quaticesign,	per fed smooth of dc per fed 9 applied perating 9 ons and current
Review of dc chedrive, armature of starting, Review of motor machine; singlede drive, regeneration Unit III AC Review of induction voltage, applied point, constant for the controller specific Generation of the drive, armature of the controller specific drive, armature of the contr	opper and duty ratio control, chopper fed dc motor for speed of current waveform and ripple, calculation of losses in dc motor ring and generating modes operation of a separately excited equadrant, two-quadrant and four-quadrant choppers; steadynative braking DRIVES Setion motor equivalent circuit and torque-speed characteristic frequency and applied voltage and frequency, typical torque-lux operation, flux weakening operation. NTROL OF DC AND AC DRIVES To of DC drive, inner current loop and outer speed loop, dynamics, modeling of chopper as gain with switching delay, plant to	ed dc machine, four state operation of mestate operation of mestate operation of torque speed curves of fan a mic model of dc moteransfer function, for theory, conventional	pperation iency of quadranulti-qualulti	on of a f dc d d d d d d d d d d d d d d d d d	eration techop with ds, op equation of the control of the contro	per fed smooth of dc per fed 9 applied perating 9 ons and current ulation;
Review of dc chedrive, armature of starting, Review of motor machine; singlede drive, regeneration of the constant V/f control of the constant V/f control of the drive, armature of the constant V/f control of the drive, armature of the constant V/f control of the drive, armature of the constant V/f control of the drive, armature of the drive,	current waveform and ripple, calculation of losses in dc motor of a separately excited and generating modes operation of a separately excited equadrant, two-quadrant and four-quadrant choppers; steadynative braking DRIVES Intimiting and applied voltage and frequency, typical torque-lux operation, flux weakening operation. NTROL OF DC AND AC DRIVES The of DC drive, inner current loop and outer speed loop, dynamics, modeling of chopper as gain with switching delay, plant to dication and design, speed controller specification and design, ree-phase PWM signals, sinusoidal modulation, space vector	ed dc machine, four estate operation of mestate operation of mestate operation of torque espeed curves of fan a mic model of dc motoransfer function, for theory, conventional motor with externa	pperation iency of quadranulti-qualulti	on of a f dc d d d d d d d d d d d d d d d d d	eration techop with ds, op equation of the control of the contro	per fed smooth of dc per fed 9 applied perating 9 ons and current ulation;
Review of dc chedrive, armature of starting, Review of motor machine; singlede drive, regeneration of the constant of the constant of the constant v/f coelectronic based of the control of the constant of th	current waveform and ripple, calculation of losses in dc motor or speed of current waveform and ripple, calculation of losses in dc motor or speed of current waveform and ripple, calculation of losses in dc motor or speed of current waveform and specific and four-quadrant choppers; steady-rative braking DRIVES Section motor equivalent circuit and torque-speed characteristic frequency and applied voltage and frequency, typical torque-lux operation, flux weakening operation. NTROL OF DC AND AC DRIVES For of DC drive, inner current loop and outer speed loop, dynamics, modeling of chopper as gain with switching delay, plant to fication and design, speed controller specification and design, ree-phase PWM signals, sinusoidal modulation, space vector introl of induction motor. Operation of slip-ring induction	ed dc machine, four estate operation of mestate operation of mestate operation of torque espeed curves of fan a mic model of dc motoransfer function, for theory, conventional motor with externa	pperation iency of quadranulti-qualulti	on of a f dc d d d d d d d d d d d d d d d d d	eration techop with ds, op equation of the control of the contro	per fed smooth of dc per fed 9 applied perating 9 ons and current ulation;
Review of dc chedrive, armature of starting, Review of motor machine; singlede drive, regeneration of the constant V/f coelectronic based drive, regeneration of the constant V/f coelectronic based drive, regeneration of the constant V/f coelectronic based drive, armatic drive	opper and duty ratio control, chopper fed dc motor for speed of current waveform and ripple, calculation of losses in dc motor oring and generating modes operation of a separately excited equadrant, two-quadrant and four-quadrant choppers; steadynative braking DRIVES Stion motor equivalent circuit and torque-speed characteristic frequency and applied voltage and frequency, typical torque-lux operation, flux weakening operation. NTROL OF DC AND AC DRIVES The of DC drive, inner current loop and outer speed loop, dynamics, modeling of chopper as gain with switching delay, plant the dication and design, speed controller specification and design, ree-phase PWM signals, sinusoidal modulation, space vector introl of induction motor. Operation of slip-ring induction rotor side control of slip ring motor, slip power recovery schevance.	or and chopper, efficed dc machine, four estate operation of mestate operation of torque espeed curves of fan a mic model of dc motoransfer function, for theory, conventional motor with external emes.	pperation iency of quadranulti-qualulti	on of a f de d d d d d d d d d d d d d d d d d	eration t chop with das, op equation esign, r modutance,	per fed smooth of of dc per fed per fe
Review of dc chedrive, armature of starting, Review of motor machine; single-dc drive, regeneration of the constant V/f coelectronic based drive, regeneration of the constant V/f coelectronic based Unit V AD	current waveform and ripple, calculation of losses in dc motor or speed of current waveform and ripple, calculation of losses in dc motor or speed of current waveform and ripple, calculation of losses in dc motor or speed generating modes operation of a separately excited equadrant, two-quadrant and four-quadrant choppers; steady-rative braking DRIVES Section motor equivalent circuit and torque-speed characteristic frequency and applied voltage and frequency, typical torque-lux operation, flux weakening operation. NTROL OF DC AND AC DRIVES The of DC drive, inner current loop and outer speed loop, dynamics, modeling of chopper as gain with switching delay, plant the fication and design, speed controller specification and design ree-phase PWM signals, sinusoidal modulation, space vector introl of induction motor. Operation of slip-ring induction rotor side control of slip ring motor, slip power recovery schi	ed dc machine, four estate operation of mestate operation of mestate operation of torque espeed curves of fan a mic model of dc motoransfer function, for theory, conventional motor with external emes.	pperation iency of quadranulti-qualulti	on of a f de d d d d d d d d d d d d d d d d d	a chop lrive, seration t chop with ds, op equation exists, or constance, r modutance, cropro	per fed smooth of of dc per fed per fe

Text	Books:
1.	G. K. Dubey, "Fundamentals of Electrical Drives", CRC Press, 2002.
2.	Subrahmanyam, Vedam "Electrical Drives Concepts and Applications", Mc-Graw Hill Publishing, New Delhi, 2016
3.	S.K.Pillai, "A first course on Electric Drives", Wiley Eastern Ltd., New Delhi, 2016
Refe	rence Books:
1.	G. K. Dubey, "Power Semiconductor Controlled Drives", Prentice Hall, 1989.
2.	W. Leonhard, "Control of Electric Drives", Springer Science & Business Media, 2001.
3.	Jai P.Agrawal, "Power Electronics Systems - Theory and Design", Pearson Education, Inc., New Delhi, 2016

Course	Out	comes:	
Upon co	omplet	ion of this course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	:	Identify the electric drive for the required speed-torque characteristics	L1: Remembering
CO2	:	Understand the functioning of DC drive using converters	L2: Understanding
CO3	:	Understand the functioning of AC drive using converters	L2: Understanding
CO4	:	Analyse the various control schemes for AC and DC drive	L4: Analyzing
CO5	:	To use microcontroller based system for motor control	L6: Creating
COLID	OTC A		

COURSE ARTICULATION MATRIX

COs/ POs	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	PO 7	PO 8	PO 9	PO 10	PO 11	PO 12	PSO 1	PSO 2	PSO 3
CO1	1	1	1	2	1							1	1	2	
CO2	2	2	2	3	2		1					1	1	2	
CO3	2	2	2	3	2		1					1	2	3	
CO4	2	3	3	3	3	1	2	2				3	2	3	2
CO5	1	2	2	3	3		2					3	1	2	2
Avg	1.6	2	2	2.8	2.2	1	1.5	2	•	-	•	1.8	1.4	2.4	2
	•		3/2	2/1-indi	cates str	ength o	f correl	ation (3	- High,	2-Medi	um, 1- I	Low)			

PREREQUISITES Basic Electrical and Electronics Engineering or Principles of Electrical Engineering or Basic Electrical Engineering for Metallurgy Course Objectives: 1. To understand basics of energy. 2. To familiarize the energy scenario in India. 3. To understand the energy conservation approaches.	CATEGORY Hours/Week	OE L 3	Cre T 0	dit P 0	3 C 3
Engineering or Basic Electrical Engineering for Metallurgy Course Objectives: 1. To understand basics of energy. 2. To familiarize the energy scenario in India. 3. To understand the energy conservation approaches.	Hours/Week				
Engineering or Basic Electrical Engineering for Metallurgy Course Objectives: 1. To understand basics of energy. 2. To familiarize the energy scenario in India. 3. To understand the energy conservation approaches.	Hours/Week	3	0	0	3
 To understand basics of energy. To familiarize the energy scenario in India. To understand the energy conservation approaches. 					
 To familiarize the energy scenario in India. To understand the energy conservation approaches. 					
3. To understand the energy conservation approaches.					
62					
4 m - 1 - 1 - 1					•
4. To get knowledge on energy management approaches.					
5. To update the knowledge in energy efficient technologies.					
UNIT I ENERGY SCENARIO		9	0	0	9
UNIT II BASICS OF ENERGY Introduction – Work, power and energy – Electricity basics – Thermal ener performance – Matching energy usage to requirement.	gy basics – Energy u	9 nits and c	onversi	ions –	Energy
UNIT III ENERGY CONSERVATION APPROACHES		9	0	0	9
Energy saving opportunities in electric motors, Benefits of Power factor Synchronous Condenser etc., Energy conservation by industrial drives, Noventilation and air conditioners, compressors pumps, fans and blowers. En boilers., lighting techniques – Natural, CFL, LED lighting sources and fit	Methods and technique tergy conservation in	ies of ene	ergy co	nserva	ation in
UNIT IV ENERGY MANAGEMENT		9	0	0	9
Demand side management (DSM)— DSM planning — DSM Techniques - conservation — tariff options for DSM - Energy audit — instruments for ener and utilization systems — economic analysis.					
UNIT V ENERGY EFFICIENT TECHNOLOGIES		9	0	0	9
Maximum demand controllers - Automatic power factor controllers - Ener - Variable speed drives - Energy efficient transformers - Electronic ballas controls - Energy saving potential of each technology.					
	Tota	al (45 L-	+0 T)=	45 P	eriods

Text	Text Books:								
1.	Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 2015.								
2.	Tripathy, S. C, "Utilization of Electrical Energy and Conservation", McGraw Hill, 1991.								
Refe	Reference Books:								
1.	Guide books for National Certification Examination for Energy Manager / Energy AuditorsBook-1, General Aspects (available online).								
2.	Guide books for National Certification Examination for Energy Manager / Energy AuditorsBook-3, Electrical Utilities (available online)								
3.	Murphy. W.R and McKay. G, "Energy Management", Butterworths Publications, London, 1982.								
4.	Wayne C Tuner, "Energy Management Hand Book", John Wiley and Sons, 1982.								

Course O	ut	comes:	Bloom's Taxonomy
Upon comp	plet	ion of this course, the students will be able to:	Mapped
CO1	:	Identify the present energy scenario.	L2: Understanding
CO2	:	Recognize the various form of energy.	L2: Understanding
CO3	:	Interpret the process of energy conservation.	L3: Applying
CO4	:	Categorize the methods improving energy management.	L4: Analysing
CO5	:	Examine the role of energy efficient devices in energy conservation	L4: Analysing

COUR	SE AR	TICUI	LATIO	N MA	TRIX										
CO/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO 10	PO 11	PO 12	PSO 1	PSO 2	PSO 3
CO 1	1	2	3	2	2		3				2	2	2	2	1
CO 2	1	2	2	2	2		3				3	3	2	2	1
CO 3	2	2	2	3	2		3				2	3	1	3	1
CO 4	2	3	2	2	3		3				3	3	3	3	1
CO 5	2	2	3	1	2		3				2	1	3	2	1
Avg	1.6	2.2	2.4	2	2.2	-	3	-	-		2.4	2.4	2.2	2.4	1
			3/	2/1 - i	ndicates	strengtl	n of corr	elation	(3- High	, 2-Med	dium, 1-I	Low)			

22EF	EOE04	ELECTRIC VEHICLES		SEM	EST	ER	VI / VII					
PRE	REQUI	SITES	CATEGORY	OE	Cro	edit	3					
-			** /** 1	L	Т	P	TH					
Electi	rical Mad	chines	Hours/Week	3	0	0	3					
Cour	rse Obj	ectives:										
1.	To lear	n the components of Electric Vehicle, configurations and its architec	tural design									
2.	To stud	ly the energy storage options for Electric vehicle.										
UNI	ГΙ	ELECTRIC VEHICLES		9	0	0	9					
Confi	guration	s of Electric Vehicles (EV), Performance of Electric Vehicles: Traction	on Motor Characteri	stics, Tı	activ	e Effo	ort and					
Trans	mission	Requirement and Vehicle Performance, Tractive Effort in Normal D	riving, Energy Cons	sumptio	n							
UNI	ΓII	HYBRID ELECTRIC VEHICLES		9	0	0	9					
		ybrid Electric Drive Trains, Classification of hybrid electric vehicle										
		Hybrid Electric Drive Trains, Parallel Hybrid Electric Drive Train										
		Speed-Coupling Parallel Hybrid Electric Drive Trains, Torque-Co	upling and Speed-C	Coupling	g Para	allel I	Iybrid					
	ric Drive			T								
UNI		PLUG-IN HYBRID ELECTRIC VEHICLES (PHEV)		9	0	0	9					
		d Benefits Of PHEV, Components of PHEV, Operating Principles			, Plu	g-In I	Hybrid					
		hitecture, Compound PHEV Architecture, Control Strategy of PHEV	, Charging of PHE									
UNI		FUEL CELL ELECTRIC VEHICLE		9	0	0	9					
		nciples of Fuel Cells, Fuel Cell System Characteristics, Fuel Cell Tec		n Storag	ge, Co	onfigu	ıration					
		hybrid Electric Vehicle, Control Strategy of Fuel cell Electric Vehicl	e	T								
UNI	-	ENERGY STORAGE SYSTEM		9	0	0	9					
		tery Systems for Automotive Applications, Battery Technologies										
		mer (Li-P) Battery, Lithium-Ion (Li-Ion) Battery, Ultracapacito	ors: Features, opera	ation a	nd p	erforn	nance,					
Hybri	dization	of Energy Storages										
			Total (45L+0T)= 45 Periods									

Text l	Books:
1.	Iqbal Hussain, "Electric and Hybrid Vehicles: Design Fundamentals", CRC Press, Taylor & Francis Group, Second Edition ,2011.
2.	Mehrdad Ehsani, Yimin Gao, Sebastien E. Gay, AliEmadi,, "Modern Electric, Hybrid Electric, and Fuel Cell Vehicles" CRC Press, 2016
Refer	ence Books:
1.	Ali Emadi, Mehrdad Ehsani, John M.Miller , "Vehicular Electric Power Systems", Ali Emadi, Mehrdad Ehsani, John M.Miller, Special Indian Edition, Marcel dekker, Inc 2010
E-Ref	erence e
1	https://archive.nptel.ac.in/courses/108/106/108106170/

Course	Ou	tcomes:	Bloom's Taxonomy
Upon co	mpl	etion of this course, the students will be able to:	Level
CO1	:	L1: Remembering	
CO2	:	Draw the configuration of different types of Electric Vehicle	L4: Analyzing
CO3	:	Describe the selection and sizing of Fuel cell for hybrid electric vehicle.	L2: Understanding
CO4	:	Select control strategy and control for Plug In Hybrid Electric vehicle	L4: Analyzing
CO5	:	Use the battery management system for electric vehicle	L3: Applying

COUR	SE AR	FICUL	ATIO	N MA	TRIX										
COs/ POs	PO1	PO 2	PO 3	PO 4	PO 5	PO 6	PO 7	PO 8	PO 9	PO 10	PO 11	PO 12	PS O1	PS O2	PS O3
CO1	1		1	3	1	2	1		1	2	1	1	1	2	1
CO2	1	2	3	1		1	2	1	1		1	2	1	2	
CO3	1	1			2		3	2	1	2	1		1	1	1
CO4	3	1	2	1	2	1	1				3	2	1	2	1
CO5	1	2	1	2	1	2		1	2	1		1	1	2	1
Avg	1.4	1.5	1.75	1.75	1.50	1.5	1.75	1.33	1.25	1.67	1.5	1.5	1	1.8	1
	•		3/2/1-in	dicates	strength	of con	relation	(3- Hig	h, 2-Me	dium, 1	- Low)		-		•

22M	IEOE01	DESIGN OF MACHINE ELEMENTS AND N	MACHINING	SI	EME VI/V		R
			CATEGORY	OE	Cre	dit	3
			II / XV 1-	L	T	P	TH
			Hours/Week	3	0	0	3
CO	URSE OF	BJECTIVES			<u>.</u>		
1	To famil	iarize the various steps involved in the design process.					
2	To under	estand the basic concepts of machining techniques.					
3	To know	the factors influencing the processes and their applications.					
4	Applying	g the principles of milling and gear cutting machines.					
5	To gain t	he knowledge of cutting tool materials and surface finishing	process.				
UN	I TI	STRESSES IN MACHINE ELEMENTS		9	0	0	9
		ole machine members- axial, bending, torsional, bearing stress, Theories of failure, factor of safety, stress concentration		s; cor	nbine	d stre	esses,
UN	II TII	DESIGN OF SHAFTS AND WELDED JOINTS		9	0	0	9
		ft members subjected to simple and combined stresses - Wel ats subjected to various load -Design of Riveted joints	lded joints- Types of we	lding	symbo	ols, d	esign
UN	III TII	DESIGN OF MACHINE ELEMENTS		9	0	0	9
		gn of helical springs- stresses and deflection - design proceduntact bearings, hydro- dynamic and hydro static bearings- Life					
UN	NIT IV	METAL CUTTING		9	0	0	9
chi	p formation	tal cutting: Introduction, mechanics of metal cutting, orthogon, heat generation, cutting fluids, cutting tool life, recent ded machining)					
UN	NIT V	MACHINE TOOLS AND SURFACE FINISHING	PROCESSES	9	0	0	9
pla	nning, mill	chine tools: Cutting tool materials, cutting tool nomenclature ing, drilling and boring machines, working principle, operat roduction to Grinding honing, lapping processes and machine	tions, work holding devi	ces. S	urface	fini	
			Tota	l(45L	$\overline{a} = 4$	5Per	riods

REF	ERENCE BOOKS:
1	Rao P N, "Manufacturing Technology" Tata McGraw-Hill Publishing Company Ltd, New Delhi, 2006
2	HMT, "Production Technology" Tata McGraw-Hill Co., New Delhi, 1998
3	Milton C Shaw, "Metal Cutting Principles", Clarendon Press, Oxford, 1999.
4	James Brown, "Advanced Machining Technology Handbook", McGraw- Hill Book Company, New York, 1988.
5	Robert L Mott, "Machine Elements in Mechanical Design", Macmillan Publishing Co., London. UK, 1992.
6	Shighley and Mische, "Mechanical Engineering Design" McGraw Hill, 1992.
7	Rao. P.N "Manufacturing Technology," Metal Cutting and Machine Tools, Tata McGraw-Hill, New Delhi, 2003.
E-R	EFERENCES:
1.	https://nptel.ac.in/courses/112105124
2.	Design of Machine Elements - V. B. Bhandari - Google Books
3.	"A Textbook of Machine Design" by R.S.Khurmi and J.K.Gupta

	RSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Analyze the stresses induced in a machine element.	Analyze
CO2	Familiarize the design concept of joints under various loading.	Remember
CO3	Familiarize the design of various types of bearings and Spring.	Remember
CO4	Identify the process parameters associated with various machining processes.	Apply
CO5	Familiarize the cutting tools materials and surface finishing processes.	Remember

COURSE	ARTI	CUL	ATIO	N MA	TRIX	K								
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PSO1	PSO2	PSO3
CO1	2	2	1	2		1	1				1		3	2
CO2	2	2	1	2		1	1				1		3	2
CO3	2	2	1	2		1	1				1		3	2
CO4	2	2	1	2		1	1				1		3	2
CO5	2	2	1	2		1	1				1		3	2
Avg	2	2	1	2		1	1				1		3	2
	•	3/2	2/1 – in	dicate	s strer	ngth of	corre	lation (3 – Hi	gh, 2- M	edium, 1	- Low)	1	

	COE02	INDUSTRIAL ENGINEERING	;	S	EME VI/		R	
			CATEGORY	OE	Cr	edit		3
				L	Т	P	Т	Ή
			Hours/Week	3	0	0		3
COU	RSE O	BJECTIVES					I	
1	Assur	me technical and managerial roles in the industries.						
2	Apply	y engineering principles to the working environment.						
3	Use q	quality tools to foresee and solve issues in the industrial signal.	tuations.					
4	Work	collaboratively.						
5	To kr	now the importance of EBQ.						
UNIT	ΓI	FORECASTING			9	0	0	9
	rrelation	ving Average (ARIMA) models – Fitting Regression Models – Problem solving. FACILITIES PLANNING AND WORK STUDY		of Forecas	t Erroi	rs, Coe	effic 0	ien 9
Comp	uterised	ing Site Location Decisions - Principles and Types of Layout Techniques - Design of Group Technology Layout	out – Line Balancir	ng - Line I	Balanc	ing M	letho	ods-
Comp Object Econo Motio	outerised tives of omy - Te on Time S	Layout Techniques - Design of Group Technology Layout Work Study -Method Study Procedure, Recording Techniques of Work measurement - Time Study - Synthesis System (PMTS) - Work Sampling Techniques.	out – Line Balancir hniques - Motion	ng - Line I Study - Pi	Balanc rincipl ing - F	ing Mes of	Ietho Mo ermi	ods- tion ined
Comp Object Econd Motio	outerised tives of omy - Te on Time S	Layout Techniques - Design of Group Technology Layout Work Study -Method Study Procedure, Recording Techniques of Work measurement - Time Study - Synthesis System (PMTS) - Work Sampling Techniques. LEAN MANUFACTURING	out – Line Balancir hniques - Motion Method - Analytic	ng - Line I Study - Pr al Estimat	Balanc rincipl ing - F	ing Mes of Predeto	Mo ermi	ods- tior nec
Comp Object Econd Motio UNIT Eleme Synch Concu Proces Resou	tives of only - Teen Time S TIII ents of only - Teen S pronous of o	Layout Techniques - Design of Group Technology Layout Work Study -Method Study Procedure, Recording Techniques of Work measurement - Time Study - Synthesis System (PMTS) - Work Sampling Techniques.	out – Line Balancir hniques - Motion of Method - Analytic System- Optimize Minute Exchange Ianufacturing – Ra ent, Supply chain	ng - Line I Study - Pra al Estimat d Production of Die (SI pid Manuf and "Keir	Balancerincipling - F 9 ionTec MED) Facturicetsu"	es of Predeto o chnolo 5S co ng - Ent	Mo ermi O ogy once Busin	ods- tion ined 9 and ept - ness rises
Comp Object Econo Motio UNII Eleme Synch Concu Proces Resou	tives of omy - Te on Time Sents of or III ents of or III ent	Layout Techniques - Design of Group Technology Layout Work Study -Method Study Procedure, Recording Techniques of Work measurement - Time Study - Synthesis System (PMTS) - Work Sampling Techniques. LEAN MANUFACTURING Just In Time (JIT) - Pull and Push System, Kanban Synthesis Manufacturing – Implementation of Six Sigma - Single Ingineering - Cellular Manufacturing – Enablersof Agile Magineering (BPR) - Basics of Supply Chain Managemenning (ERP) - Role of KAIZEN, Quality Circles and Position of Six Sigma - Single Managemenning (ERP) - Role of KAIZEN, Quality Circles and Position of Six Sigma - Single Managemenning (ERP) - Role of KAIZEN, Quality Circles and Position of Six Sigma - Single Managemenning (ERP) - Role of KAIZEN, Quality Circles and Position of Six Sigma - Single Managemenning (ERP) - Role of KAIZEN, Quality Circles and Position of Six Sigma - Single Managemenning (ERP) - Role of KAIZEN, Quality Circles and Position of Six Sigma - Single Managemenning (ERP) - Role of KAIZEN, Quality Circles and Position of Six Sigma - Single Managemenning (ERP) - Role of KAIZEN, Quality Circles and Position of Six Sigma - Single Managemenning (ERP) - Role of KAIZEN, Quality Circles and Position of Six Sigma - Single Managemenning (ERP) - Role of KAIZEN, Quality Circles and Position of Six Sigma - Single Managemenning (ERP) - Role of KAIZEN, Quality Circles and Position of Six Sigma - Single Managemenning (ERP) - Role of KAIZEN, Quality Circles and Position of Six Sigma - Single Managemenning (ERP) - Role of KAIZEN, Quality Circles and Position of Six Sigma - Single Managemenning (ERP) - Role of KAIZEN, Quality Circles and Position of Six Sigma - Single Managemenning (ERP) - Role of KAIZEN, Quality Circles and Position of Six Sigma - Single Managemenning (ERP) - Role of KAIZEN, Quality Circles and Position of Six Sigma - Single Managemenning (ERP) - Role of KAIZEN, Quality Circles and Position of Six Sigma - Single Managemenning (ERP) - Role of KAIZEN, Quality Circles and Position of Six Sigma - Single Managemenning	out – Line Balancir hniques - Motion of Method - Analytic System- Optimize Minute Exchange Ianufacturing – Ra ent, Supply chain	ng - Line I Study - Pra al Estimat d Production of Die (SI pid Manuf and "Keir	Balancerincipling - F 9 ionTec MED) Facturicetsu"	es of Predeto o chnolo 5S co ng - Ent	Mo ermi O ogy once Busin	9 and pt ness ever
Comp Object Econol Motio UNIT Eleme Synch Concu Proces Resou wastes UNIT Object Strate Requir	tives of only - Te on Time of Time of the only on Time of the only	Layout Techniques - Design of Group Technology Layout Work Study -Method Study Procedure, Recording Techniques of Work measurement - Time Study - Synthesis System (PMTS) - Work Sampling Techniques. LEAN MANUFACTURING Just In Time (JIT) - Pull and Push System, Kanban Manufacturing – Implementation of Six Sigma - Single Ingineering - Cellular Manufacturing – Enablersof Agile Magineering (BPR) - Basics of Supply Chain Managementing (ERP) - Role of KAIZEN, Quality Circles and Pont Manufacturing.	System- Optimized Minute Exchange Manufacturing – Ra ent, Supply chain a DKA YOKE in Mo (CRP) Process - T ling - Procedure for	g - Line I Study - Pral Estimat d Production of Die (SI pid Manuf and "Keir odern Man	Balance rincipling - F 9 ionTec MED) Facturi etsu" uufactu 9 Capaci	o ty Plate PS - Months of the	O O O O O O O O O O O O O O O O O O O	9 and ept - nessever 9
Comp Object Econo Motio UNIT Eleme Synch Concu Proces Resou wastes UNIT Object Strate Requi	tives of on Time of TIII ents of or on Time	Layout Techniques - Design of Group Technology Layou Work Study -Method Study Procedure, Recording Techniques of Work measurement - Time Study - Synthesis System (PMTS) - Work Sampling Techniques. LEAN MANUFACTURING Just In Time (JIT) - Pull and Push System, Kanban Smanufacturing – Implementation of Six Sigma - Single Ingineering- Cellular Manufacturing – Enablersof Agile Magineering (BPR) - Basics of Supply Chain Managemenning (ERP) - Role of KAIZEN, Quality Circles and Pont Manufacturing. AGGREGATE PRODUCTION PLANNING Aggregate Planning - Capacity Requirement Planning Aggregate Capacity Planning - Master Production Schedul Planning (MRP-I), Issues in MRP, Designing and Manufacturing and Manufacturing and Manufacturing (MRP-I), Issues in MRP, Designing and Manufacturing and Manufacturing (MRP-I), Issues in MRP, Designing and Manufacturing (MRP-I)	System- Optimized Minute Exchange Manufacturing – Ra ent, Supply chain a DKA YOKE in Mo (CRP) Process - T ling - Procedure for	g - Line I Study - Pral Estimat d Production of Die (SI pid Manuf and "Keir odern Man	Balance rincipling - F 9 ionTec MED) Facturi etsu" uufactu 9 Capaci	o ty Plate PS - Months of the	O O O O O O O O O O O O O O O O O O O	9 and opt hess ever

REFERENCE BOOKS:

1 R.Panneerselvam, "Production & Operations Management", 3rd Edition, PHI LearningPrivate Limited, New Delhi, 2012

2 Elwood S.Buffa, and Rakesh K.Sarin, "Modern Production/Operation Management", 8th Edition, John Wiley & Sons, 2000

3 Dilworth B.James, "Operations Management Design, Planning and Control for Manufacturing and Services", Mcgraw Hill Inc., New York, 1992

4	Vollman T.E, "Manufacturing Planning and Control Systems", Galgotia Publications, 2002.								
E-REI	E-REFERENCES:								
1.	https://www.newtondesk.com/industrial-engineering-study-notes-hand-written								
2.	https://en.wikipedia.org/wiki/Lean_manufacturing								
3.	https://www.planettogether.com/blog/types-of-scheduling-in-production-planning-and-control								

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:						
CO1	Apply the knowledge of engineering and sciences to improve the productivity of industries.						
CO2	Design a system to meet the desired needs within realistic constraints.	Create					
CO3	Function in multidisciplinary teams.	Apply					
CO4	Use the techniques, skills, and modern engineering tools in manufacturing practice.	Understand					
CO5	Perform as an effective industrial engineer integrating high and low levels of management	Create					

COURSE A	ARTI	CULA	TION	MAT	RIX									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PSO1	PSO2	PSO3
CO1	3			2	2									3
CO2			3											2
CO3						3	2		3	2	3	2	3	
CO4	3	3		2	3	3						2		3
CO5						3	2	3					3	
Avg	3	3	3	2	2.5	3	2	3	3	2	3	2	3	2.6
		3/2	2/1 — in	dicates	streng	th of c	orrelat	tion (3	– High, 2	2- Mediu	m, 1- Lo	ow)		

	COE03	INDUSTRIAL ROBOTICS		SEM	ESTI	ER V	I/V	II
			CATEGORY	OE	Cre	dit	3	}
				L	Т	P	T	H
			Hours/Week	3	0	0	3	}
COUR	RSE OB	JECTIVES	1				ı	
1	To explo	ore concepts of robot technologies that is playing vital r	ole in manufacture.					
2	Describe	e various robot technology applications.						
3	Develop	an understanding of robot Kinematics and dynamics.						
4	Explain	and summarize robot end effectors and Sensors.						
5	Explore	conceptual understanding of Robot programming.						
UNIT	Ί	INTRODUCTION			9	0	0	9
- end e	effectors	lic, pneumatic, mechanical and electrical - servo motor – types: tools - grippers - mechanical grippers - pneums, multiple grippers.						
UNIT	III	SENSORS AND MACHINE VISION			9	0	0	9
	ements o					U	U	
effect, o	ers, opti	f sensors – principles, types and applications of follow e, ultrasonic and optical) – range (Triangulation, structucal encoders, pneumatic) – force – torque – touch senfunctions - image processing and analysis.	red light approach, lase	r range) – spe	active ed, po	, Ha	n
effect, o	ers, option	e, ultrasonic and optical) – range (Triangulation, structucal encoders, pneumatic) – force – torque – touch set	red light approach, lase nsors (binary, analog	r range) – spe	active ed, po	, Ha	on to
effect, of (resolve machin UNIT Forwar homogo VAL p	rers, optione vision IV rd kinemeteneous to brogramn	e, ultrasonic and optical) – range (Triangulation, structucal encoders, pneumatic) – force – torque – touch ser-functions - image processing and analysis.	red light approach, lase nsors (binary, analog anal	er range sensor) om (in orogran	- Intr	uctive ed, pooduct 0 ension	e, Habition ion of the mall ages	on to 9
effect, of (resolve machin UNIT Forwar homogo VAL p	rers, option in a vision of IV ord kinem teneous to brogramming and p	e, ultrasonic and optical) – range (Triangulation, structucal encoders, pneumatic) – force – torque – touch serfunctions - image processing and analysis. ROBOT KINEMATICS AND ROBOT PROGRATICS and reverse kinematics of manipulators - two, transformation matrix - simple problems - lead throughing –motion commands - sensor commands - end effective.	RAMMING three degrees of freeder programming, robot pecter commands - simple	or range sensor) om (in orogran ole prog	9 2 dim	uctive ed, pooduct 0 ension	e, Habition ion of the mall ages	on to 9
effect, of (resolver machine) UNIT Forwar homogy VAL punloadi UNIT Robot of unloadi	rers, optione vision IV rd kinemeteneous to brogramming and procell designing - auto	e, ultrasonic and optical) – range (Triangulation, structucal encoders, pneumatic) – force – torque – touch ser-functions - image processing and analysis. ROBOT KINEMATICS AND ROBOT PROGRATICS and reverse kinematics of manipulators - two, transformation matrix - simple problems - lead throughing –motion commands - sensor commands - end effectable tizing operations.	RAMMING three degrees of freeder programming, robot pecter commands - simple DROBOT ECONOLOGICAL PROBOT ECONOLOGICA PROBOT ECONOLOG	om (in brogram ble program ble program ble program bright program ble program bright program ble progr	9 2 dimensing grams i	oduct od	, Habitic Action (1997) And the control of the cont	9 - - g,

REFE	REFERENCE BOOKS:							
1	Mikell. P. Groover, 'Industrial Robotics Technology', Programming and Applications, McGraw Hill Co, 1995.							
2	Fu.K.S. Gonzalz.R.C., and Lee C.S.G., "Robotics Control, Sensing, Vision and Intelligence", McGraw Hill Book Co., 1987.							
3	Richard D.Klafter, Thomas A.Chmielewski and MichealNegin, "Robotic engineering –An Integrated Approach", Prentice Hall Inc, Englewoods Cliffs, NJ, USA, 2005.							
4	Janakiraman.P.A. "Robotics and Image Processing", Tata McGraw-Hill, 1995.							
5	YoramKoren, "Robotics for Engineers", McGraw-Hill Book Co., 1992.							
6	A.K.Gupta and S.K.Arora, "Industrial Automation and Robotics", Laxmi Publications Pvt ltd, 2007.							
7	Fu. K. S., Gonzalez. R. C. & Lee C.S.G., 'Robotics control, sensing, vision and intelligence', McGraw Hill Book co, 1987.							
8	Craig, J. J. 'Introduction to Robotics mechanics and control', Addison-Wesley, 1999							

COURSE OUTCOMES: Upon completion of this course, the students will be able to:					
CO1	Understand the basic concepts, parts of robots and types of robots.	Understand			
CO2	Understand the potential applications of robots in industries as part of automation tool.	Understand			
соз	Familiar with the various drive systems for robot, sensors and their applications in robots, programming of robots.	Remember			
CO4	Discuss about the various applications of robots, justification, implementation and safety of robot	Analyze			
CO5	Select an appropriate robot for a particular application.	Apply			

COURSE A	COURSE ARTICULATION MATRIX													
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PSO1	PSO2	PSO3
CO1	3	2	1			1							1	1
CO2			1		1	1							1	1
CO3		1	0										1	1
CO4			1			3								1
CO5		2											1	2
Avg	3	1.7	1		1	1.7							1	1.2
	3/2/1 – indicates strength of correlation (3 – High, 2- Medium, 1- Low)													

	OE04	POWER PLANT ENGINEERING		SE	MES VI/V		R
PRER	EQUI	SITES	CATEGORY	OE	Cre	edit	3
1.	Havin	g sufficient knowledge on basics of power plant	TT /XX/ 1	L	T	P	TH
2.	Basic	unit calculation for consumption of power	Hours/Week	3	0	3	
COUF	RSE O	BJECTIVES:		•		•	
1.	Unders	tanding of thermal power plant operations and its components.					
2.	Locatio	on of hydro power plant and its components to generate power.					
3.	Comple	ete knowledge about diesel and gas power plant.					
4.	Basic k	nowledge of nuclear reaction and types of nuclear power plant.					
5.	Basic k	nowledge of power plant economics and various tariff methods.					
UNI	ΤI	STEAM POWER PLANT		9	0	0	9
		Dust collector - Ash removal; Stokers - Different types - Pulverisign - Selection of blowers, Cooling towers - Different types		ght - Di	fferen	it typ	es
- Chim Circula	nney de ated Flu	sign - Selection of blowers, Cooling towers - Different types idised Bed boilers	zed fuel burning; Draug	ght - Di	fferen	it typ	es
- Chim Circula UNI Layout	nney de ated Flu IT II t of hyd	sign - Selection of blowers, Cooling towers - Different types	zed fuel burning; Drau - Waste heat recovery	ght - Di , Fluidi 9	fferen sed B	nt typ sed an	es nd 9
- Chim Circula UNI Layout equipn	nney de ated Flu IT II t of hyd	sign - Selection of blowers, Cooling towers - Different types idised Bed boilers HYDRO ELECTRIC POWER PLANT del power plant- classification –working – components – layor	zed fuel burning; Drau - Waste heat recovery	ght - Di , Fluidi 9	fferen sed B	nt typ sed an	es nd 9
- Chim Circula UNI Layout equipn UNI Layout	iney de ated Flu IT II It of hydrent for T III It of Dies	sign - Selection of blowers, Cooling towers - Different types idised Bed boilers HYDRO ELECTRIC POWER PLANT del power plant- classification –working – components – layor Pumped Store Schemes.	zed fuel burning; Drauge Waste heat recovery at of pumped storage Layout of gas power p	ght - Di , Fluidi 9 power	fferensed B 0 plant	ont type ed an one of type ed	es nd 9 nt 9
- Chim Circula UNI Layour equipm UNI Layour of gas	iney de ated Flu IT II It of hydrent for T III It of Dies	sign - Selection of blowers, Cooling towers - Different types idised Bed boilers HYDRO ELECTRIC POWER PLANT del power plant- classification –working – components – layor Pumped Store Schemes. DIESEL AND GAS POWER PLANT sel power plant- Important components – performance analysis –	zed fuel burning; Drauge Waste heat recovery at of pumped storage Layout of gas power p	ght - Di , Fluidi 9 power	fferensed B 0 plant	ont type ed an one of type ed	es and 9 ant 9
- Chim Circula UNI Layour equipm UNI Layour of gas UNI Element	T III To Diest turbine T IV	sign - Selection of blowers, Cooling towers - Different types idised Bed boilers HYDRO ELECTRIC POWER PLANT del power plant- classification –working – components – layor Pumped Store Schemes. DIESEL AND GAS POWER PLANT sel power plant- Important components – performance analysis – cycles – components – relative thermal efficiencies of different	eactors, boiling water	ght - Di , Fluidi 9 power 9 plant - c	o plant o classif	ont typed and one of the one of t	9 nnt 9
- Chim Circula UNI Layout equipm UNI Layout of gas UNI Elementer	T III To Diest turbine T IV	sign - Selection of blowers, Cooling towers - Different types idised Bed boilers HYDRO ELECTRIC POWER PLANT del power plant- classification –working – components – layor Pumped Store Schemes. DIESEL AND GAS POWER PLANT sel power plant- Important components – performance analysis – cycles – components – relative thermal efficiencies of different NUCLEAR, MHD POWER GENERATION eatment - nuclear fission, chain reaction - Pressurized water re-	eactors, boiling water	ght - Di , Fluidi 9 power 9 plant - c	o plant o classif	ont typed and one of the one of t	9 nnt 9

Total(45L) = 45 Periods

TEXT	BOOKS:					
1.	S. Domkundwar, A.V. Domkundwar, S.C. Arora.A Course in Power Plant Engineering, Dhanpat Rai Publications. 2013					
2.	P.K. Nag, Power Plant Engineering, Tata McGraw Hill, Laxmi Publications Pvt.Ltd New Delhi, 5th Edition, 2014.					
REFER	ENCES:					
1	R.K. Rajput. A Text of Power Plant Engineering, Laxmi publications, New Delhi 5th Edition, 2016.					
2	G.R. Nagpal, Power Plant Engineering, Khanna Publications 1998.					
3	Bernhardt G. Askrotzki and William A. Vopat, "Power Station Engineering and Economy", Tata McGraw Hill Publishing Co. Ltd., 1972.					
4	Frederick T. Mores, "Power Plant Engineering", Affiliated East-West Press Private Ltd., 1953.					
5	Joel Weisman and Roy Eckart, "Modern Power Plant Engineering", Prentice Hall International Inc., 1985.					
E-REF	E-REFERENCES:					
1.	https://en.wikipedia.org/wiki/Power_plant_engineering					

2	https://onlinecourses.n	4 - 1 : / 2 1	
,	i niing//onlinecolirges n	niei ac in/noc7 i	mexn/preview

COURSE OUTCOMES: Upon completion of this course, the students will be able to:					
CO1	Ample knowledge on thermal power plant operation and its merits and demerits.	Analyze			
CO2	Potential Power of water to convert into useful energy by hydropower.	Remember			
CO3	Augment with diesel and gas power plant operation and its components.	Understand			
CO4	Able to cope with recent developments on nuclear power plant.	Understand			
CO5	Understanding of various economics to construct power plant and to measure the consumption of power by different tariff.	Understand			

COURSE	COURSE ARTICULATION MATRIX																
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3		
CO1	1	2	3	2	1		1	1	2		2	2	2	1	2		
CO2	1	2	3	2	1		1	1	2		2	2	2	1	2		
CO3	1	2	3	2	1		1	1	2		2	2	2	1	2		
CO4	1	2	3	2	1		1	1	2		2	2	2	1	2		
CO5	2		1	2				2	2	1	1	1	2				
Avg	1.2	2	2.6	2.0	1		1	1.2	2.0	1	1.8	1.8	2.0	1	2		
			3/2/1 -	indicat	es stre	ngth o	f corre	3/2/1 – indicates strength of correlation (3 – High, 2- Medium, 1- Low)									

22MEOE05	PRINCIPLES OF MANAGEMEN	NT		ME: VI/V	STEI III	R
		CATEGORY	OE	Cr	edit	3
		** /**/	L	T	P	TI
		Hours/Week	3	0	0	3
COURSE O	BJECTIVES					
1. To und	erstand the management basic features of management.					
2. Princip	les usages in all walks of life and industrial growth.					
3. Able to control	have a clear understanding of the managerial functions like ling.	e planning, organizing	, staffin	g, lea	ding	and
4. To gain	n some basic knowledge in international aspect of manageme	ent.				
UNITI	MANAGEMENT - AN INTRODUCTION AND O	VERVIEW	9	0	0	9
functions and	FUNCTIONS OF MANAGEMENT agers. Functions approach to management, Management for role, responsibility of managers – towards subordinates, ditors, shareholders, competitors etc.					
UNIT III	MANAGERIAL PLANNING AND DECISION M	IAKING	9	0	0	9
of planning, importance of	lamentals, objectives. Management by objectives – Changes policies and objectives, procedures – methods, rules, progedecision making, types of decisions, decision making process king conditions – Operation Research (OR), Definition, successions	grammes and scheduless – decision theory – q	e, projec uantitat	ets, b	udget chniq	ts – jues
UNIT IV	ORGANIZATION		9	0	0	9
typology,co-operative,	Basic concepts – organization as a structure – as a process – mportance of organization – business /industrial organization public enterprise line (military), line and staff, function zation – need, bases of departmentation – career planning an	ntion – sole trading, al, matrix committee	partners	hip c	compa	any,
UNIT V	STAFFING, CONTROLLING AND COMMUNIC	CATION	9	0	0	9
sources of rec importance pr – definition –	arpose of staffing – man power planning, aims and objective ruitment, process of recruitment, training methods – performances – barriers to communications. How to remove obstacl Characteristics of control – types of control – requirements ing, control techniques.	nance appraisal methodes of effective commu	ds – con nication	nmun 1 – cc	icatio ntrol	on – ling

Total (45L) = 45Periods

REF	REFERENCE BOOKS:						
1	Herald knootz and Heinz weihrich, Essentials of Management I, McGraw-Hill Publishing Company, Singapore International Edition, 2007						
2	Joseph L, Massie, Essentials of Management. Prentice Hall of IndiaPvt., Ltd (Pearson) Fourth Edition, 2003.						
3	Stephen A. Robbins & David A. Decenzo & Mary Coulter, "Fundamentals of Management" 7 th Edition, Pearson Education, 2011.						
4	Robert Kreitner & Mamata Mohapatra, "Management", Biztantra, 2008.						
5	Harold Koontz & Heinz Weihrich "Essentials of management" Tata McGraw Hill, 1998.						
6	Tripathy PC & Reddy PN, "Principles of Management", Tata McGraw Hill, 1999.						
7	R.S.N. Pillai & S. Kala "Principles and Practice of Management", S Chand & company, 2014.						

E-REFERENCES:						
1.	https://nptel.ac.in/courses/110105146					
2.	https://nptel.ac.in/courses/122106031					

COU	Bloom Taxonomy Mapped	
CO1	Understand the basic concept of management.	Understand
CO2	Familiarize the contribution sand functions, types of business organization.	Understand
CO3	List the various types of leadership and evaluate the motivation the ories and techniques.	Evaluate
CO4	Select forecasting models for future demands and to make decision in the management processes.	Evaluate

COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PSO1	PSO2	PSO3
CO1							1	3	1		2	2	1	1
CO2							1	1	2		3	2	1	1
CO3								1	2		1	1	1	1
CO4							2	1	2		2	1	1	1
Avg							1.3	1.5	1.75		2	1.5	1	1
		3/2	2/1 – i	ndicat	es stre	ngth o	f corr	elation	(3 – H	igh, 2- N	Iedium,	1- Low)		

22MI	PROFESSIONAL ETHICS IN ENGINEERING				SEMESTER VI/VIII					
			CATEGORY	OE	Cre	dit	3			
			Horus/Week	L	T	P	TH			
			Horus/ week	3	0	0	3			
COU	JRSE O	BJECTIVES								
1		tte awareness on Engineering Ethics and providing basic knowssues and Professional Ideals.	wledge about enginee	ring Eth	ics, V	ariety	of of			
2	To pro	provide basic familiarity about Engineers as responsible Experimenters, Codes of Ethics, Industrial ndards.								
3	To incu	rulcate knowledge and exposure on safety and risk, risk benefit analysis.								
UNI	UNIT I HUMAN VALUES						9			
	idence –	caring – Sharing – Honesty – Courage – Valuing Time – Co- Character – Spirituality. ENGINEERING ETHICS	-operation – Commit	ment – I	Empati 0	hy –	Self-			
Kohl	berg's the	ngineering Ethics' - variety of moral issued - types of inqueory - Gilligan's theory - consensus and controversy – Modenterest- customs and religion - uses of ethical theories.								
UNI	IT III ENGINEERING AS SOCIAL EXPERIMENTATION				0	0	9			
		s experimentation - engineers as responsible experimenters - case study.	codes of ethics - a ba	lanced o	utlool	c on 1	law –			
UNI	UNIT IV SAFETY, RESPONSIBILITIES AND RIGHTS						9			
Cher of ir	nobyl cas	sk - assessment of safety and risk - risk benefit analysis are studies. Collegiality and loyalty - respect for authority - col occupational crime - professional rights - employee right.	lective bargaining - c	onfident	iality	- con	flicts			
UNI	T V	GLOBAL ISSUES		9	0	0	9			
const ASC	ılting eng E, IEEE,	corporations - Environmental ethics - computer ethics - we gineers-engineers as expert witnesses and advisors -moral le Institution of Engineers (India), Indian Institute of Materials cation Engineers (IETE),India.	adership-sample cod	e of Eth	ics lik	e AS	SME,			

Total(45L) = 45Periods

REFERENCE BOOKS:						
1	Mike Martin and Roland Schinzinger, "Ethics in Engineering", McGraw-Hill, New York 2005.					
2	Govindarajan M, Natarajan S, Senthil Kumar V. S, "Engineering Ethics", Prentice Hall of India, New Delhi, 2004.					
3	Tripathi A N, "Human values", New Age international Pvt. Ltd., New Delhi, 2002.					
4	Charles D. Fleddermann, "Engineering Ethics", Pearson Education / Prentice Hall, New Jersey, 2004.					
5	Charles E Harris, Michael S. Protchard and Michael J Rabins, "Engineering Ethics – Concepts and Cases", Wadsworth Thompson Learning, United States, 2000.					
6	John R Boatright, "Ethics and the Conduct of Business", Pearson Education, New Delhi, 2003.					
7	R S Naagarazan, "A Textbook on Professional Ethics and Human Values" New age international (p) limited, publishers, New Delhi – 110002, 2006.					

	URSE OUTCOMES: n completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Understand the importance of ethics and values in life and society.	Understand
CO2	Understood the core values that shape the ethical behavior of an engineer.	Understand
СОЗ	Exposed awareness on professional ethics and human values.	Remember

COURSI	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1						2	1	3	2		1				1
CO2						1	1	3	1		1				1
CO3						2	1	3	1		1				1
Avg						1.66	1	3	1.33		1				1
	•	3/2	2/1 – inc	dicates	stren	gth of c	correla	tion (3	– High,	2- Med	lium, 1	- Low)			•

22Ml	EOE07	RENEWABLE SOURCES OF ENER	GY		MES VI/V		R
	REQUI		CATEGORY	OE	Cre	dit	3
		oout solar radiation and other renewable energy that exists. ng about various chemical reactions occur in the energy		L	Т	P	TH
	version p		Horus/Week	3	0	1	4
COU	JRSE O	BJECTIVES			I.	ı	
1.							
2.	To idea	ntify the employ of renewable energy sources for electrical po-	wer generation				
3.	To coll	ect different energy storage methods					
4.	To dete	ect about environmental effects of energy conversion					
UNI	ΤI	SOLAR RADIATION AND ITS MEASUREMENT	S	9	0	0	9
		nergy sources, Global and Indian energy scenario. Sola and Instruments – Data and estimation.	r Energy: Introduction	n – 3	Solar	Radi	ation
UNI	T II	SOLAR ENERGY COLLECTORS, SOLAR ENERGAND APPLICATIONS OF SOLAR ENERGY	GY STORAGE	9	0	0	9
Fund Then	amentals mal energ	d Concentrating Collectors —Solar direct Thermal Applicat of Solar Photo Voltaic Conversion — Solar Cells — Solar PV gy, Chemical Energy and Electromagnetic energy storage; S and cooling, Solar distillation, Solar pumping, Solar furnace,	Power Generation – olar PV Applications:	Solar 1	Energy	Sto	rage:
UNI	T III T	BIOMASS AND ITS CONVERSION TECHNOLOG	GIES	9	0	0	9
types	; Wet Pr	version Techniques: Direct combustion (incineration); Thern occess- Classification of biogas plant- types of Anaerobic di, Gasnesh biogas plant and Ferro-cement digester biogas plant	gestion (Khadi and V	llage			
UNI	T IV	WIND, GEOTHERMAL AND TIDAL ENERGY		9	0	0	9
geoth Com	nermal re parison o	le of wind energy conversion, types of wind energy conversions, geopressurised resources, hot dry rock resources of flashed steam and total flow concept. Basic principle of tide hods of utilization of tidal power.	petrothermal systems	, Mag	ma re	sour	ces –
UNI	T V	CHEMICAL ENERGY, HYDROGEN ENERGY AN HYDRO DYNAMIC	ND MAGNETO	9	0	0	9
		inciple operation of a Fuel cells, classification of fuel cells, ty ns of fuel cells. Basic principle of Magneto Hydro Dynamic –					tages

REFE	CRENCE BOOKS:					
1	G.D. Rai, "Non-Conventional Energy Sources", Khanna Publishers, New Delhi, 2014.					
2	Suhas P. Sukhatme, "Solar Energy", Tata McGraw Hill Publishing Company Ltd., 2007.					
3	Khan, B.H., "Non-Conventional Energy Resources", The McGraw Hill Companies, 2009.					
4	Twidell, J.W. & Weir, A., "Renewable Energy Resources", EFN Spon Ltd., UK, 2005.					
5	Solanki: Renewable Energy Technologies: Practical Guide for Beginners, PHI Learning Pvt.Ltd., 2008					
6	D. Mukherjee: Fundamentals of Renewable Energy Systems, New Age International publishers, 2007.					
7	Gilbert M. Masters: Renewable and Efficient Electric Power Systems, John Wiley & Sons, 2004.					
E-R	E-REFERENCES:					
1.	https://en.wikipedia.org/wiki/Renewable_energy					

Total (45L) = 45Periods

2. Ellabban, Omar; Abu-Rub, Haitham; Blaabjerg, Frede (2014). "Renewable energy resources: Current status, future prospects and their enabling technology". Renewable and Sustainable Energy Reviews. 39: 748–764 [749]

	URSE OUTCOMES: n completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Understand the principles of solar radiation and its measuring devices	Understand
CO2	Comprehend the ideology of solar energy collectors, solar photovoltaic power generationsolar energy storage and applications of solar energy	Analyze
CO3	Acquire awareness about biomass sources of energy technologies	Understand
CO4	Design various renewable energy gadgets such as wind and tidal plant	Create
CO5	Learn about extracting energy from chemical methods	Understand

COURSE	COURSE ARTICULATION MATRIX													
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PSO1	PSO2	PSO3
CO1	1	2	3	2	1		2	2	3	1	1	2	2	1
CO2	1	2	3	2	1		2	2	3	1	1	2	2	1
CO3		2	3	2	1		2	2	3	1	1	2	2	1
CO4	1	2	3	2			2	2	3	1	1	2	2	1
CO5	1	2	3	2	1		2	2	3	1	1	2	2	1
Avg	1	2	3	2	1		2	2	3	1	1	2	2	1
		3	/2/1 –	indica	tes stre	ength o	of corr	elation (3	8 – High	ı, 2- Med	lium, 1- L	ow)		

2MI	EOE08	ROBOTIC PROCESS AUTOMATI	ON		MES		₹
Pre-r	equisite	:	CATEGORY	OE	Cre	edit	3
				L	T	P	TH
Ba	sics in ki	nematics and dynamics	Hours/Week	3	0	0	3
COU	U RSEO	BJECTIVES	•	•		•	
1.	To stu	dy the various parts of robots and fields of robotics.					
2.	To stu	dy the various kinematics and inverse kinematics of robots.					
3.	To stu	dy the Euler, Lagrangian formulation of Robot dynamics.					
4.	To stu	dy the trajectory planning for robot.					
5.	To stu	dy the control of robots for some specific applications					
UNI	ΙΤΙ	BASIC CONCEPTS		9	0	0	9
	nov``s law	POWER SOURCES AND SENSORS		9	0	0	9
– pat		eumatic and electric drives – determination of HP of motor an ination – micro machines in robotics – machine vision – rangasors					
UNI	III TI	MANIPULATORS, ACTUATORS AND GRIPPER	RS	9	0	0	9
		of manipulators – manipulator dynamics and force control – effectors – U various types of grippers – design consideration		atic man	ipulat	or co	ntrol
UNI	T IV	KINEMATICS AND PATH PLANNING		9	0	0	9
		verse kinematics problem – multiple solution jacobian work languages	envelop – Hill Climb	oing Tec	hniqu	es – :	robot
UNI	T V	CASE STUDIES		9	0	0	9
	iple robo	ts – machine interface – robots in manufacturing and non- mabot.	anufacturing application	ons – rol	oot cel	ll des	ign –
			Total	(45L)	= 45	Peri	ods

REF	ERENCE BOOKS:
1	Mikell P. Weiss G.M., Nagel R.N., Odraj N.G., "Industrial Robotics", Mc Graw-Hill Singapore, 1996.
2	Ghosh, Control in Robotics and Automation: Sensor Based Integration, Allied Publishers, Chennai, 1998.
3	Deb. S.R., "Robotics Technology and flexible Automation", John Wiley, USA 1992.
4	Klafter R.D., Chimielewski T.A., Negin M., "Robotic Engineering – An integrated approach", Prentice Hall of India, New Delhi, 1994.
5	Barry Leatham – Jones, "Elements of industrial Robotics" PITMAN Publishing, 1987.
6	Mikell P.Groover, Mitchell Weiss, Roger N.Nagel Nicholas G.Odrey, "Industrial Robotics Technology, Programming and Applications", McGraw Hill Book Company 1986.
7	Fu K.S. Gonzaleaz R.C. and Lee C.S.G., "Robotics Control Sensing, Vision and Intelligence" McGraw Hill International Editions, 1987.

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:							
CO1	Explain the basic concepts of working of robot.	Understand						
CO2	Analyze the function of sensors in the robot.	Analyze						
CO3	Analyze the working of manipulates, actuators and grippers.	Analyze						
CO4	Write program to use a robot for a typical application.	Create						
CO5	Use robots in different applications.	Apply						

COURSE	COURSE ARTICULATION MATRIX													
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PSO1	PSO2	PSO3
CO1	1	1	2		2					1		2	2	2
CO2	1	3	2	1	1							2	1	3
CO3		2	2	1	1							2	1	3
CO4		1	1	2	3			1	3	2	1	2		
CO5		1	2	2	2	1	2	2	3	2	1	2		
Avg	1	1.6	1.8	1.5	2	1	2	1.5	3	1.7	1	2	1.3	2.7
	•	3/	/2/1 – i	ndicat	es stre	ength o	of corr	elation	(3-H)	igh, 2- N	ledium, 1	1- Low)	•	•

22Ml	EOE09		STEI 'III				
			CATEGORY	OE	Cr	edit	3
				L	Т	P	TH
			Hours/Week	3	0	0	3
cot	JRSE O	BJECTIVES			I		I
1.		the need for quality, its evolution, basic concepts, contribut enefits of TQM.	ion of quality gurus, T	QM fram	iewor	k, Ba	rriers
2.	Explain	n the TQM Principles for application.					
3.	Define	the basics of six sigma and apply traditional tools, new too	ols, Benchmarking and	FMEA.			
4.	Describ and BP	be Taguchi's Quality Loss Function, Performance measure PR.	es and apply technique	s like QI	FD, T	PM,	COQ
5.	Illustra	ate and apply QMS and EMS in any organization.					
UNI	ΤI	INTRODUCTION		9	0	0	9
Basic mana	concept gement	Quality - Dimensions of Quality - Quality planning - Quality of total quality management (TQM) - Historical review - I - Quality council, Quality statements - Strategic plann	Principles of TQM – Le	eadership	- Rol	le of s	enior
Basic mana	concept gement	s of total quality management (TQM) - Historical review - I - Quality council, Quality statements - Strategic plann	Principles of TQM – Le	eadership	- Rol	le of s	enior
Basic mana imple UNI Custo	c concept agement ementation T II	s of total quality management (TQM) - Historical review - From the control of total quality management (TQM) - Historical review - From total quality council, Quality statements - Strategic plann on TQM PRINCIPLES Instruction - Customer perception of quality, Customer control of total quality, Customer control of total quality and total quality in the control of total quality and	Principles of TQM – Leing- Deming philosophi	eadership ohy - Ba 9 ty, Custo	- Rol	le of s s to 0	enior TQM 9 ntion,
Basic mana imple UNI Custo Emple Conti	c concept agement ementation T II omer sati loyee invinuous pr	s of total quality management (TQM) - Historical review - From the review - Quality council, Quality statements - Strategic plann on TQM PRINCIPLES isfaction - Customer perception of quality, Customer convolvement - Motivation, Empowerment, Teams, Recognocess improvement - Juran Trilogy, PDSA Cycle, 5S, Ka	Principles of TQM – Leing- Deming philosophi	eadership bhy - Ba g ty, Custo Performan rship, Soo	- Rol	le of s s to O Reterapprai	enior TQM 9 ntion, sal -
Basic mana imple UNI Custo Empl Conti selec	c concept agement ementation T II omer sati loyee invinuous pr	s of total quality management (TQM) - Historical review - I - Quality council, Quality statements - Strategic plann on TQM PRINCIPLES isfaction - Customer perception of quality, Customer convolvement - Motivation, Empowerment, Teams, Recog	Principles of TQM – Leing- Deming philosophi	eadership bhy - Ba g ty, Custo Performan rship, Soo	- Rol	le of s s to O Reterapprai	enior TQM 9 ntion, sal -
Basic mana imple UNI Custo Emplo Contiselect UNI The s	c concept gement ementation T II Dimer satistic groups in the second proper in the second p	s of total quality management (TQM) - Historical review - IIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIII	Principles of TQM – Leing- Deming philosophing- Deming philosophing ph	9 ty, Custo Performar rship, Soo Strategy 9 n, Popular	- Rollarriers 0 omerace a urcing 0 tion a	le of s s to O Reterappraig, Sup O nd sar	9 ntion, sal - pplier 9 mple,
Basic mana imple UNI Custo Emplo Contiselect UNI The s	T II Difference of the concepts of the concep	s of total quality management (TQM) - Historical review - IIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIII	Principles of TQM – Leing- Deming philosophing- Deming philosophing ph	9 ty, Custo Performar rship, Soo Strategy 9 n, Popular	- Rollarriers 0 omerace a urcing 0 tion a	le of s s to O Reterappraig, Sup O nd sar	9 ntion, sal - pplier 9 mple,
Basic mana imple UNI Custo Emplo Contiselect UNI The s Norm Mana UNI Benc quali	c concept gement ementation T II Dimer satistic loyee invition, Supper	s of total quality management (TQM) - Historical review - I - Quality council, Quality statements - Strategic plann on TQM PRINCIPLES isfaction - Customer perception of quality, Customer convolvement - Motivation, Empowerment, Teams, Recogrecess improvement - Juran Trilogy, PDSA Cycle, 5S, Karpplier rating, Relationship development - Performance measurements of quality, Statistical fundamentals - Measures of central tear - Control charts for variables and attributes, Process cartools.	Principles of TQM – Leing- Deming philosophing- Deming philosophing- Deming philosophing philoso	eadership bhy - Ba ty, Custo Performar rship, Son Strategy 9 n, Populat F six sigr 9 QFD) pro	Omernice a urcing tion a ma, N	le of sist to Reterappraise, Sup O nd sasses Services O Hou	9 ntion, sal - pplier 9 mple, Seven 9
Basic mana imple UNI Custo Emplo Contiselect UNI The s Norm Mana UNI Benc quali	c concept gement ementation T II omer satistic loyee invitation, Support on the curve agement of the curve ageme	s of total quality management (TQM) - Historical review - I - Quality council, Quality statements - Strategic plann on TQM PRINCIPLES isfaction - Customer perception of quality, Customer convolvement - Motivation, Empowerment, Teams, Recogrecess improvement - Juran Trilogy, PDSA Cycle, 5S, Karpplier rating, Relationship development - Performance measures of quality, Statistical fundamentals - Measures of central tear - Control charts for variables and attributes, Process cartools. TQM TOOLS g - Reasons to benchmark, Benchmarking process, Quality fits - Taguchi quality loss function - Total productive main	Principles of TQM – Leing- Deming philosophing- Deming philosophing- Deming philosophing philoso	eadership bhy - Ba ty, Custo Performar rship, Son Strategy 9 n, Populat F six sigr 9 QFD) pro	Omernice a urcing tion a ma, N	le of sist to Reterappraise, Sup O nd sasses Services O Hou	9 ntion, sal - pplier 9 mple, Seven 9 use of
Basic mana imple UNI Custo Emple Contiselect UNI The s Norm Mana UNI Benc qualiff FME UNI Need	c concept gement ementation T II omer satistic loyee invitation, Support III even tooleral curve agement of T IV hmarking ty, Benef A – Stage T V for ISO	s of total quality management (TQM) - Historical review - I - Quality council, Quality statements - Strategic plann on TQM PRINCIPLES isfaction - Customer perception of quality, Customer convolvement - Motivation, Empowerment, Teams, Recogrocess improvement - Juran Trilogy, PDSA Cycle, 5S, Kapplier rating, Relationship development - Performance measurables of quality, Statistical fundamentals - Measures of central tear - Control charts for variables and attributes, Process carools. TQM TOOLS g - Reasons to benchmark, Benchmarking process, Quality fits - Taguchi quality loss function - Total productive maines of FMEA.	Principles of TQM – Leing- Deming philosophing- Deming philosophing- Deming philosophing- Deming philosophing- Deming philosophing- Partner sures, Basic concepts, Strendency and dispersionapability - Concept of function deployment (Ontenance (TPM) conception, ISO 9001:2008 quality - Leinger Partner (TPM) conception (eadership bhy - Ba ty, Custo Performar rship, Son Strategy 9 n, Popular r six sigr 9 QFD) pro pt, Impro 9 ality syst	Omer nce a urcing on a na, No ocess overner o	le of sist to	enior TQM 9 ntion, sal - pplier 9 mple, Seven 9 use of eeds -

REF	ERENCE BOOKS:
1	Dale H.Besterfiled, Carol B.Michna, Glen H. Bester field, Mary B. Sacre, Hemant Urdhwareshe and Rashmi Urdhwareshe, "Total Quality Management", Pearson Education Asia, Revised Third Edition, Indian Reprint, Sixth Impression, 2013.
2	Feigenbaum.A.V. "Total Quality Management", McGraw Hill, 1991.
3	Joel.E. Ross, "Total Quality Management – Text and Cases", Routledge. 2017.
4	Kiran.D.R, "Total Quality Management: Key concepts and case studies, Butterworth – Heinemann Ltd, 2016.
5	Oakland, J.S. "TQM – Text with Cases", Butterworth – Heinemann Ltd., Oxford, Third Edition, 2003.
6	Suganthi.L and Anand Samuel, "Total Quality Management", Prentice Hall (India) Pvt. Ltd., 2006

7	Narayana V and Sreenivasan, N.S, "Quality Management – Concepts and Tasks", New Age International, 1996.
E-RI	EFERENCES:
1.	https://www.oreilly.com/library/view/total-quality-management/9780815330486/xhtml/Reference1.xhtml
2.	https://www.sanfoundry.com/best-reference-books-total-quality-management/
3.	https://www.routledge.com/Total-Quality-Management-TQM-Principles-Methods-and-Applications/Luthra-Garg-Agarwal-Mangla/p/book/9780367512835

COURSE OUTCOMES: Upon completion of this course, the students will be able to:						
CO1	Ability to apply TQM concepts in a selected enterprise.	Apply				
CO2	Ability to apply TQM principles in a selected enterprise.	Apply				
соз	Ability to understand Six Sigma and apply Traditional tools, new tools, Benchmarking and FMEA.	Understand				
CO4	Ability to understand Taguchi's Quality Loss Function, Performance Measures and apply QFD, TPM, COQ and BPR.	Understand				
CO5	Ability to apply QMS and EMS in any organization.	Apply				

COURSE	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PSO1	PSO2	PSO3	
CO1	1	3			2		1		2			2	1	2	
CO2	1	2							2			2			
CO3	1	2	2		1			1				2	1		
CO4	1	2			2	3		2		3		2	2	2	
CO5	1	2	2		2	2	1	2	2	3		2	2	2	
Avg	1	2.2	2		1.75	2.5	1	1.7	2	3		2	1.5	2	
		3/	/2/1 – i	ndicat	es stre	ngth o	of corr	elation	(3 – H	igh, 2- M	ledium, 1	1- Low)			

	22MTO	E01	FOUNDRY AND WELDING T	ECHNOLOGY						
DD	EDEAL	TOTT	EQ.	Category	OE	Credit		3		
	EREQU		ES: Fechnology	Hours/Week	L	Т	P	TH		
IVI	muractu	ing i	recimology	Hours/ week	3	0	0	3		
Co	urse Obj	jectiv	es:							
1.	materia	ls.	basic concepts of metal casting technologies			•				
2. To know the concepts of different materials joining technology and emphasis on underlying science and engineering principle of every processes.										
UNIT I MOULDING MATERIALS AND PATTERNS 9 0 0										
Introduction to foundry operations, patterns - functions, types, allowances, selection of pattern materials, colourcodes, core boxes, moulding practice, ingredients of moulding sand and core sand, Testing of Moulding sands. Sand preparation, Sand reclamation in foundries.										
U	NIT II	MOU	ULDING AND CASTING TECHNIQ	UES	9	0	0	9		
car	bon- di-o	xide j	green sand moulding, dry sand moulding, dry sand moulding, die can casting, die can casting, Thixo casting, Thi	sting, centrifugal cas						
			LTING PRACTICE		9	0	0	9		
			and special precautions for steels, alloy ium alloys, Cleaning and repair of casting					copper		
U.	NIT IV	WEI	LDING AND OTHER JOINING PRO	CESSES	9	0	0	9		
we	lding, ga	s tung	welding processes- oxy-acetylene we sten arc and gas metal arc welding, el ting processes							
U	UNIT V SPECIAL WELDING PROCESSES 9 0 0									
arc	nciple, ed andlaser lding.	quipm beam	ent, process variables, merits, limitation n welding processes. Friction, friction st	ns and applications of ir welding, ultrasonic	Elect explo	ron be	eam, and di	plasma ffusion		
				To	tal (4	5+0) =	= 45]	Hours		

m 4	D. 1
1.	Books: Heine R W., Loper, C.R.Rosenthal, P.C., "Principles of Metal Casting", Tata-McGraw Hill PublishingCo Ltd, New Delhi, 2008.
2.	Srinivasan N K.,"Foundry Engineering", Khanna Tech Publications, New Delhi, 2005.
3.	Parmar, R.S., -Welding Processes and Technology , 2nd edn. Khanna Publishers, New Delhi, 2001
4.	Srinivasan N K ,"Welding Technology", Khanna Publications, Delhi, 2000
Refer	rence Books:
1.	Beeley P R., "Foundry Technology", Butterworths, London, 1982.
2.	Howard B. Cary, "Modern Welding Technology", Prentice Hall, New Jersey, USA, 1998.

		utcomes: appletion of this course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	:	Discuss the alloying element effect on the steels and mention the precaution to be taken in mouldingand melting of steels.	L2: Understanding
CO2	:	Distinguish different moulding and casting techniques.	L3:Applying
CO3	:	Apply the melting procedure for the various alloys like steels, stainless steels, discuss the slag-metal reactions	L3:Applying
CO4	:	Illustrate the conventional welding processes and allied joining processes.	L2: Understanding
CO5	:	Compare the various special welding processes.	L3:Applying

COURS	COURSE ARTICULATION MATRIX															
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	2	1	1										2			
CO2	1	1		1	1								1			1
CO3	2	1	1				1						2			
CO4	1	1	1	1	1	1							1			1
CO5	2	1		1	1								1			
Avg.	1.6	1.0	1.0	1.0	1.0	1.0	1.0						1.4			1.0
						3/2/1-ir	dicates	strengt	h of co	relation	(3- High	, 2-Medi	um, 1- Lo	ow)		

22MTC	DE02	ADVANCED SURFACE ENG	INEERING							
PREREQU			Category	OE	Credit		3			
Manufactu	ring To	echnology	Carregory		Т	P	TH			
	J		Hours/Week	L	_					
				3	0	0	3			
Course Obj	jectives	s:								
1. Analyze	e the va	rious concepts of surface engineering and	d comprehend the o	lesign o	lifficu	lties				
UNIT I	TRIB	OLOGY AND PLATING PROCESSE	S	9	0	0	9			
trotting wear electrode po plating adhe	ar, roles osition, esion, e	pology, Wear: Types of wear - adhesive, so of friction and lubrication and wear to plating of nickel, chromium, tin and coppelectroless plating, electrochemical convehard anodizing.	esting. Plating Proper, pulsed plating,	cesses: hydrog	Funda en eml	menta brittler	ls of nent,			
UNIT II HARD FACING PROCESSES 9 0 0 9										
		GMAW, FCAW, SAW, PAW, Oxy-Acety	ylene Welding, Fur	rnace fu	ising,	Therm	-			
spray, Flam	espray	processes - HVOF, Detonation gun and J	let kote processes,	Hard fa	cing c	onsum	ables.			
		IAL DIFFUSION PROCESSES		9	0	0	9			
Principle of diffusion properties as	ocesses	sion processes - Boriding, Aluminising - Characteristics of diffused layer - mic ications.	g, Siliconising, Claro structure and m	hromisi icro ha	ng - rdness	Selecti evalua	ion of ation -			
UNIT IV	THIN	FILM COATINGS		9	0	0	9			
vapour depo	sition	eposition processes - Thermal evaporation - reactive sputtering - TiC, TiN, Alu es and applications.								
	PROC	PECIAL	9	0	0	9				
created by	laser a th,therr	dening, glazing, Laser beam hardening and Electron beam. Surface cements, Vinal / chemical. Ceramic coatings, centri	Vear tiles, Electro fugal cast wear co	spark patings,	depo Wear	sition, sleeve	fused es and			
				Total (L+T) :	= 45 H	ours			

Text	Books:
1.	Chattopadhyay R., Surface Wear: Analysis, Treatment, Prevention, ASM International, USA, 2001
2.	Kenneth G. Budinski, Surface Engineering for Wear Resistance, Prentice Hall, Englewood Cliff, 1990.
Refer	rence Books:
1.	ASM Metals Handbook, Vol 5: Surface Engineering, ASM International, Ohio, 1994.
2.	Ernest Rabinowicz, Friction and Wear of Materials, 2nd ed., John Wiley & Sons, NY, 1995.
3.	Davis J.R., Surface Engineering for Corrosion and Wear resistance, ASM International, 2001.

	Course Outcomes: Upon completion of this course, the students will be able to: Discuss the influence of the tribological characteristics						
CO1	:	Discuss the influence of the tribological characteristics.	L2: Understanding				
CO2	:	Discuss the various hard facing processes.	L3:Applying				
CO3	:	Demonstrate the surface properties with diffusion of foreign atoms into the outer surface of thematerial such as boriding, aluminizing, etc.	L2: Understanding				
CO4	:	Demonstrate the various vapour deposition processes of different materials on the surface of native materials using the Chemical, Physical and Thermal vapour deposition processes.	L2: Understanding				
CO5	:	Describe the Modern processes and high energy processes like electron beam hardening, laser beamhardening.	L3:Applying				

COURS	COURSE ARTICULATION MATRIX															
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	1	1		1	1								1	1		1
CO2	2	1			1	1						1	1			1
CO3	1	1		1	1		1					1	2			1
CO4	2	1	1		1									2		1
CO5	1			1	1								1			1
Avg.	1.4	1.0	1.0	1.0	1.0	1.0	1.0					1.0	1.3	1.5		1.0
					,	3/2/1-in	dicates	strengt	h of cor	relation	(3- High	, 2-Medi	um, 1- Lo	ow)		

22MTOE 0	DESIGN AND SELECTION OF MA	TERIALS				
PREREQU	ISITES:	Category	OE	Cı	edit	3
Manufactu	ring Technology	Hours/Week	L	Т	P	TH
		nours/ week	3	0	0	3
Course Ob	ectives:					
1. To kno	w different types of materials and properties and to selec	t better materials for	orDiff	erent	applic	ations.
UNIT I	DESIGN PROCESS		9	0	0	9
	Design, Evolution of Engineering Materials, Design paterial data, Interaction between Function, Material, Sh		lesign	, Desi	gn flo	w chart-
UNIT II	MATERIAL PROPERTIES		9	0	0	9
nodulus-den	ngineering materials and properties, Material propertie ity, Strength-density, Young's modulus-Strength, wea relative cost and others.					
UNIT III	MATERIAL SELECTION		9	0	0	9
aided selec	election, selection strategy: material attributes, attributes, structural index; Case studies: table legs, flywheairframes, ship structures, automobile structures.		•			•
UNIT IV	PROCESSES AND PROCESS SELECTION		9	0	0	9
	es: shaping, joining and finishing, Process selection, ran ase studies: fan, pressure vessel, optical table, economi		st, con	nputei	basec	l process
	A STATE OFFICE A CONTROL AND A					

UNIT V	MULTIPLE CONSTRAINTS AND OBJECTIVES	9	0	0	9								
	election under multiple constraints, conflicting objectives, penalty-functions, exchange constants, Case studies												
connecting i	ods for high performance engines, windings of high field magnets.												
	7	otal	(L+T) = 45	Hours								
Toyt Rook													

Text l	Text Books:											
1.	Michael F. Ashby, Materials Selection in Mechanical Design, third edition, Butterworth- Heinemann, 2005											
2.	J. Charles, F.A.A. Crane, J. A.G. Furness, Selection and Use of Engineering Materials, third edition, Butterworth-Heinemann, 2006											
Refer	ence Books:											
1.	ASM Metals Handbook, Vol.20: Materials Selection and Design, ASM International,1997											
2.	Myer Kutz, Handbook of Materials Selection, John Wiley & Sons, Inc., New York, 2002											

		utcomes: appletion of this course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	:	Explain the design process and design flow chart tools for the materials selection criterion.	L2: Understanding
CO2	:	Apply the materials for corrosion and wear resistance processes.	L3:Applying
CO3	:	Apply the materials for auto and aero industry.	L3:Applying
CO4	:	Classify the process selection criterion for high temperature materials.	L2: Understanding
CO5	:	Suggest the process selection criterion for high performance materials	L3:Applying

COURS	COURSE ARTICULATION MATRIX															
CO/P	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO1	PO1	PO1	PSO	PSO	PSO	PSO
O	1	2	3	4	5	6	7	8	9	0	1	2	1	2	3	4
CO1	1	1		1	1								1		1	
CO2	2	1	1			1	1							2		
CO3	1	1		1	1								1	1		
CO4	2	1	1		1									2		
CO5	1	1		1	1											1
Avg.	1.4	1.0	1.0	1.0	1.0	1.0	1.0						1.0	1.7	1.0	1.0
					3/	/2/1-inc	licates	strengt	th of co	rrelatio	n (3- Hi	gh, 2-M	edium, 1	- Low)		

22MTOE04	NANOSCIENCE AND TECH	INOLOGY					
PREREQUISITES:		Category	OE	Cr	edit	3	
Engineering material	and metallurgy	Hours/Week	L	Т	P	T H	
			3	0	0	3	
Course Objectives:							
1. To study about na	nomaterials and its application						
UNIT I INTROD	OUCTION		9	0	0	9	
dots (QDs), effect of sanomaterials.	ng carbon nanotubes (CNT), graphene, meta ize on thermal, mechanical and electrical pro-		· -			F	
	ESIS OF NANOMATERIALS		9	0	0	9	
		1 37 1 1 1		*11*		,	
Plastic Deformation, B	materials: Top-down approaches-lithograp sottom-up approaches-chemical vapour dep D), and Sol-gel method, Synthesis and pu ene.	osition, physical vapo	our de	posit	ion, a	ıtomi	
Plastic Deformation, B layer deposition (ALI	Sottom-up approaches-chemical vapour depolity, and Sol-gel method, Synthesis and pulene.	osition, physical vapo	our de	posit	ion, a	ıtomi	
Plastic Deformation, Blayer deposition (ALI graphite (EG) orgraph UNIT III NANOCO Fabrication of nanoco	cottom-up approaches-chemical vapour dep D), and Sol-gel method, Synthesis and putene. OMPOSITES Emposites: Fabrication of Clay-rubber, Clay-rubbe	osition, physical vaporification of CNT, s	our de synthes 9 olyme	positsis o	ion, and free free free free free free free fre	ande 9 lyme	
Plastic Deformation, Blayer deposition (ALI graphite (EG) orgraph UNIT III NANOCO Fabrication of nanocomagnetic particle-pol Consolidation of nanocomagnet	cottom-up approaches-chemical vapour dep D), and Sol-gel method, Synthesis and putene. OMPOSITES Emposites: Fabrication of Clay-rubber, Clay-rubbe	osition, physical vaporification of CNT, solution of CNT, solution of CNT-phe composites and	our de synthes 9 olyme	positsis o	ion, and free free free free free free free fre	ande 9	
Plastic Deformation, Blayer deposition (ALI graphite (EG) orgraph UNIT III NANOCO Fabrication of nanocomagnetic particle-pol Consolidation of nanocomagnetic particle-pol Consolidation of Namicroscope (SEM),	Sottom-up approaches-chemical vapour dep D), and Sol-gel method, Synthesis and purene. OMPOSITES Omposites: Fabrication of Clay-rubber, Clay-rubbe	osition, physical vaporification of CNT, solution of CNT, solution of CNT-phe composites and solution amic Light Scattering of UV-Visible spectres.	9 olymenanoo	positions of the position of the positions of the positio	o G-poloosites o electricannii	ymers etc	
Plastic Deformation, Blayer deposition (ALI graphite (EG) orgraph UNIT III NANOCO Fabrication of nanocomagnetic particle-pol Consolidation of nanocomagnetic particle-pol Consolidation of nanocomagnetic particle-pol Consolidation of Namicroscope (SEM), probe microscopy- A Nanoindentation.	Sottom-up approaches-chemical vapour depolo, and Sol-gel method, Synthesis and putene. OMPOSITES OMPOSITE	osition, physical vaporification of CNT, solution of CNT, solution of CNT-phe composites and solution amic Light Scattering of UV-Visible spectres.	9 olymenanoo	positions of the position of the positions of the positio	o G-poloosites o electricannii	9 yme s etc	

Total (L+T) = 45 Hours

Text 1	Books:									
1.	B.S. Murty, P. Shankar, Baldev Raj, B BRath, James Murday, Textbook of Nanoscience and Nanotechnology, University Press (I) Pvt. Ltd., 2013.									
2.	Bharat Bhushan (Ed), Springer Handbook of Nanotechnology, Springer-Verlag Berlin Heidelberg, 2004									
Reference Books:										
1.	Charles P Poole and Frank J Owens, –Introduction to Nanotechnology , John Wiley and Sons, New York, 2003.									
2.	Michael Wilson, KamaliKannagara and Geoff Smith, —Nanotechnology: Basic Science and Emerging Technologyl, Chapman and Hall, New York, 2002.									
3.	Pradeep T, -Nano: The Essentials , Tata McGraw Hill, New Delhi, 2007.									

		utcomes: utcomes: utcomes:	Bloom's Taxonomy Mapped
CO1	:	Define and differentiate engineering materials on the basis of structure and properties for engineering applications.	L2: Understanding
CO2	:	Explain the various applications of nanomaterials.	L3:Applying
CO3	:	Discuss the fabrications of composites and nano composites.	L2: Understanding
CO4	:	Describe the charactrization of nanomaterials using SEM & TEM.	L4: Analyzing
CO5	:	Apply the applications of nanomaterials.	L3:Applying

COURS	COURSE ARTICULATION MATRIX															
CO/P	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO1	PO1	PO1	PSO	PSO	PSO	PSO
О	1	2	3	4	5	6	7	8	9	0	1	2	1	2	3	4
CO1	1	2		1	1								1			1
CO2	2	2		1	1		1						1			1
CO3	3	2	1		1									1	1	
CO4	1	1		1	1	1							1	2		
CO5	1	1		1	1									1		
Avg.	1.6	1.6	1.0	1.0	1.0	1.0	1.0						1.0	1.3	1.0	1.0
					3	3/2/1-in	dicates	strengt	th of co	rrelation	(3- High	h, 2-Med	lium, 1- l	Low)		

								1
22M	TOE0	5	MATERIALS FOR AUTOMOTIVE	COMPONENTS				
PRE	REQU	ISI'	TES:	Category	OE	Cı	edit	3
Engi	ineerin	g m	aterial and metallurgy	Hours/Week	L	Т	P	T H
					3	0	0	3
Cou	rse Ob	jecti	ives:					
1.			an overview of material properties, use of material selection	terials selection char	t and			
2.	To im	part	knowledge about the basis of materials selection	1				
3.	To giv	ve in	sight about the factors that influence materials so	election for engines ar	nd trans	missi	on sys	stem
4.			the knowledge required for the selection of restructures	materials for				
5.	To rea	nder	the basis of material selection for electronics de	vices in the automobil	e.			
UN	I TI	EN	GINEERING MATERIALS AND THEIR PR	ROPERTIES	9	0	0	9
Disp desig	laying	mate eria	neering materials - the evolution of engineering rerial properties using materials selection charts, less and the environment. Selection of materials for	Forces for change in r	naterial	s sele	ction	and
UN	II TII	BA	SIS OF MATERIAL SELECTION		9	0	0	9
- typ Mate proce	es of derials person ess sele	esig roce ctio	gy, Attribute limits and Material indices, structura in, design requirements, Function, Material attribusing and design processes and their influence in, Process selection diagrams, Process cost, En ity, Recyclability, Environmental consideration.	outes, Shape and Man e on design, Process ergy consumption for	ufacturi attribut r produc	ing pr es, Sy	ocess ystem	es - atic
	i		TERIALS FOR ENGINES AND TRANSMIS		9	0	0	9
			on for IC engines: Piston, piston rings, cylinder box, Gears, Splines, Clutches.	, Engine block, Conne	ecting r	od, C	rank s	shaft,
UN	IT IV	MA	TERIALS FOR AUTOMOTIVE STRUCTU	RES	9	0	0	9
			ion for bearings, leaf springs, chasis& frames, E brake shoes, Disc, wheels, differentials, dampin					
UN	IT V		ECTRONIC MATERIALS FOR AUTOMOTPLICATIONS	ΓIVE	9	0	0	9
			ectronic devices meant for engine control, ABS ate control, anti-collision, Anti-fog, Head lamps.		on, Sens	sors, '	Temp	erature
					Total (L	_+ T) =	= 45 I	Hours
					· <u> </u>			

Text	Books:
1.	Charles J A and Crane. F A. A., -Selection and Use of Engineering Materials , 3rd Edition, Butterworths, London UK, 1996.
2.	Jason Rowe, —Advanced Materials in Automotive Engineering®, Wood Head Publishing, 2012.
Refer	rence Books:
1.	Ahmed E, —Advanced composite materials for Automotive applications, Wiley, 2013
2.	Don H Wright, Testing Automotive Materials and Components, SAE 1993.

Geoff Davis, — Materials for Automobile bodies||, Butter Worth Heinemann, 2012
 Hiroshi Yamagata, -The Science and Technology of Materials in Automotive Engines||, Elsvier, 2005
 Mstislav A M, Valentin N A, Gleb V M, —Automotive materials: a handbook for the mechanical engineer||, NTIS, 1972.

		utcomes: appletion of this course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	:	Identify the criteria and forces that cause the changes in materials selection.	L3:Applying
CO2	:	Investigate the influence of structural index, manufacturing process, design and Functional requirements on selection strategies.	L4:Analysing
CO3	:	Recognize the temperature regime, nature of load and property requirements of materials for engines and transmission system.	L4:Analysing
CO4	:	Analyse the various stresses acting on the structural members of automobile under Dynamic loading and select suitable material.	L4:Analysing
CO5	:	Prepare the apt material for electronic devices used in automobiles	L3:Applying

COURS	COURSE ARTICULATION MATRIX															
CO/P	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO1	PO1	PO1	PSO	PSO	PSO	PSO
О	1	2	3	4	5	6	7	8	9	0	1	2	1	2	3	4
CO1	1	1		1	1									2		1
CO2	3	2		1		1								2	1	
CO3	2	3	1		1								1			1
CO4	2	1		1	1								2			
CO5	1	1			1		1							1		
Avg.	1.8	1.6	1.0	1.0	1.0	1.0	1.0						1.5	1.7	1.0	1.0
					,	3/2/1-ir	dicates	streng	th of co	rrelation	(3- High	ı, 2-Med	ium, 1- L	ow)		

ELECTIVES FOR HONOURS

PROFESSIONAL ELECTIVE COURSES – VERTICALS

VERTICAL 1 – CLEAN AND GREEN ENERGY TECHNOLOGY

22M	IEH101	HYDROGEN AND FUEL CELL TEC	CHNOLOGIES										
			CATEGORY	PE	Cr	edit	3						
			TT /XX/ 1	L	T	P	TH						
			Hours/Week	3	0	0	3						
COU	RSE OBJI	ECTIVES	·										
1	To study i	n detail on the hydrogen production methodologies, pos	ssible applications and vario	us stora	age op	otions							
2	To unders	nderstand the working principle of a typical fuel cell and its types. To elaboration its thermodynamics and cs.											
3	To study t	To study the cost effectiveness and eco-friendliness of Fuel Cells.											
UNI	IT I		9	0	0	9							
wate		ification – biological hydrogen production – photo dissertion – biological hydrogen production – photo dissertion – photo – p	sociation – direct thermal or	r cataly	tic sp	litting 0	g of 9						
	lrogen storag	ge options – compressed gas – liquid hydrogen – Hydri ydrogen.	ide – chemical Storage – co	mpariso	ons, s	afety	and						
UNI	T III	FUEL CELLS		9	0	0	9						
		ble – working – thermodynamics and kinetics of fuel centery Vs fuel cell.	ll process – performance eva	luation	of fu	el cel	l –						
UNI	IT IV	FUEL CELL-TYPES		9	0	0	9						
Тур	es of fuel ce	lls–AFC, PAFC, SOFC, MCFC, DMFC, PEMFC – Rel	ative merit sand demerits.										
UNI	T V	APPLICATION OF FUEL CELL AND ECO	ONOMICS	9	0	0	9						
Fue		for domestic power systems, large scale power g	eneration Auto mobile S	pace, I	Econo	mic	1						
	ronmental an	alysison usage of Hydrogen and Fuel cell, Future trend					and						

REF	TERENCE BOOKS:
1	Viswanathan B. and Aulice Scibioh.M, Fuel Cells – Principles and Applications, Universities Press, 2006
2	RebeccaL.and Busby, Hydrogen and Fuel Cells: A Comprehensive Guide, Penn Well Corporation, Oklahoma, 2005
3	Bent Sorensen (Sorensen), Hydrogen and Fuel Cells: Emerging Technologies and Applications, Elsevier, UK2005
4	Kordesch K.and G.Simader, Fuel Cell and their Applications, Wiley-Vch, Germany 1996
5	Hart A.B.and G.J.Womack, Fuel Cells: Theory and Application, Prentice Hall, New York Ltd., London 1989
6	Jeremy Rifkin, The Hydrogen Economy, Penguin Group, USA 2002
7	Barclay F.J., Fuel Cells, Engines and Hydrogen, Wiley, 2009

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:						
CO1	Describe and analyze the techniques of Hydrogen generation.	Analyze					
CO2	Describe and classify various options for Hydrogen storage.	Analyze					
CO3	Explain the principal operations of fuel cell, its thermodynamics and kinetics process.	Understand					
CO4	Comprehend the different types of fuel cells compare their merits and demerits.	Understand					
CO5	Identify the potential application of a fuel cells for domestic, automotive, space craft power generations and evaluate the techno-economics of a fuel cells.	Analyze					

COURSE	OURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2			1									1	1
CO2	3	2			1									1	1
CO3	3	2	1	1	1		1							1	1
CO4	3	3	1	2	1	1	1							1	1
CO5	3	2	1	1	2	2	1						1	1	1
Avg	3	2.2	1	1.3	1.2	1.5	1						1	1	1
			3/2/1 -	- indic	ates st	rength	of cor	relatio	n (3 –	High, 2-	Medium	, 1- Low	<u>')</u>		•

2 To re 3 To in exper 4 To ca 5 To ob UNIT I Introduction Batteries, Li	ecogniz envestigatimenta	ermal management of electric vehicle battery systems. e the applications of PCM in thermal management. ate the thermal behaviors in electric vehicle battery systems through si	PE L 3	T 0	P 0	Т	3 TH 3				
1 To k 2 To re 3 To in exper 4 To ca 5 To ob UNIT I Introduction Batteries, Li	ecogniz ecogniz envestigatimenta	TIVES ermal management of electric vehicle battery systems. e the applications of PCM in thermal management. ate the thermal behaviors in electric vehicle battery systems through side.	3	0		Т					
1 To k 2 To re 3 To in exper 4 To ca 5 To ob UNIT I Introduction Batteries, Li	ecogniz ecogniz envestigatimenta	TIVES ermal management of electric vehicle battery systems. e the applications of PCM in thermal management. ate the thermal behaviors in electric vehicle battery systems through side.	<u> </u>		0		3				
1 To k 2 To re 3 To in exper 4 To ca 5 To ob UNIT I Introduction Batteries, Li	ecogniz ecogniz envestigatimenta	ermal management of electric vehicle battery systems. e the applications of PCM in thermal management. ate the thermal behaviors in electric vehicle battery systems through side.	mulatio								
2 To re 3 To in exper 4 To ca 5 To ob UNIT I Introduction Batteries, Li	ecogniz nvestiga rimenta alculate	e the applications of PCM in thermal management. ate the thermal behaviors in electric vehicle battery systems through side.	mulatio								
3 To in expert 4 To ca 5 To ob UNIT I Introduction Batteries, Li	nvestigarimenta	ate the thermal behaviors in electric vehicle battery systems through si	mulatio								
4 To ca 5 To ob UNIT I Introduction Batteries, Li	rimenta alculate	l.	mulation								
5 To ob UNIT I Introduction Batteries, Li		the energy and exergy analyses of battery TMSs.		on an	d						
UNIT I Introduction Batteries, Li	btain so										
Introduction Batteries, Li		lutions for case studies on Thermal Management Solutions of Electric batt	teries.								
Batteries, Li	UNIT I INTRODUCTION										
UNIT II		Ion Batteries, Battery Environmental Impact, Battery Management Systemermal Management. PHASE CHANGE MATERIALS FOR THERMAL MANAGEMENT SYSTEMS		9	0	0	9				
		d Types of PCMs, Organic PCMs, Inorganic PCMs, Measurement of The neements, Environmental Impact of Phase Change Materials, Applications			ties of	PC	Ms				
UNIT III		SIMULATION AND EXPERIMENTAL INVESTIGATION BATTERY TMS	N OF	9	0	0	9				
	el exper	evelopment for cell and sub modules, Cell and module level experimenta imentation set up and procedure, Illustrative, Simulation and Experimenta									
UNIT IV		ENERGY AND EXERGY ANALYSES OF BATTERY TMS		9	0	0	9				
		Modeling of Major TMS Components, Energy and Exergy Analyses, Illanagement Systems	lustrativ	ve Ex	ample	: Li	quid				
UNIT V	UNIT V CASE STUDIES ON THERMAL MANAGEMENT SOLUTIONS OF ELECTRIC BATTERIES										
Battery.	_	rimental and Theoretical Investigation of Temperature Distributions in									
Case Study2 Discharge C		nal Management Solutions for Electric Vehicle Lithium-Ion Batteries bas	sed on '	Vehic	le Cha	arge	and				

REFE	RENCE BOOKS:
1	Ibrahim Dinçer, Halil S.Hamut, Nader Javani, Thermal Management of Electric Vehicle Battery Systems, 2017
2	Halil S.Hamut, Nader Javani, Ibrahim Dinçer, Thermal Management of ElectricVehicle Battery Systems, Wiley, 2016
3	Weixiang Shen, Rui Xiong, Advanced Battery Management Technologies for Electric Vehicles, John Wiley and sons, First edition 2019.
4	Chitra A., Sanjeevi kumar Padmanaban, Jens BoHolm - Nielsen, Artificial Intelligent Techniques for Electric and Hybrid Electric Vehicles, John Wiley and sons, First edition 2020.

Bruno Scrosati, Jurgen Garche, Werner Tillmetz, Advances in Battery Technologies for Electric Vehicles, Wood head Publishing, 2015

5

	RSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Describe and analyse the techniques of thermal management of electric vehicle battery systems	Analyze
CO2	Describe and classify various applications of PCM in thermal management	Understand
соз	Investigate the thermal behaviour sin electric vehicle battery systems through simulation and experimental.	Analyze
CO4	Calculate the energy and exergy analyses of battery TMSS	Analyze
CO5	Identify the solutions for case studies on thermal management solutions of electric batteries.	Analyze

COURSE A	OURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2			2		1						1		
CO2	3	2	1		1		1				1		2		
CO3	3	2	2	3	1		1				1		2		
CO4	3	2	1	2	1	1					1		2		
CO5	3	3			1	2	1	1	1	1	1		2		
Avg	2.8	2.2	1.3	2.5	1.2	1.5	1	1	1	1	1		1.8		
		,	3/2/1 -	– indi	cates s	treng	th of c	orrela	tion (3 -	- High, 2	- Mediur	n, 1- Low	·)		

	EH103	ELECTRIC AND HYBRID VEHICLE TECHNOLOGY CATEG		PE	Cre	dit	3	,			
		e.ii20		L	T	P	-	H			
		Hours/We	eek	3	0	0	3				
COUR	SE OBJE	ECTIVES									
1	To intro	duce the concept of hybrid and electric drive trains.									
2	To elabo	orate on the types and utilization of hybrid and electric drive trains.									
3	То ехро	se on different types of AC and DC drives for electric vehicles.									
4	To understand and utilize different types of energy storage systems.										
5	To intro	duce concept of energy management strategies and drive sizing.									
UNIT	I	INTRODUCTION			9	0	0	9			
		e performance, vehicle power source characterization, transmission chara-		ics, H	listory	of l	ıybr	id			
and el	ectric vehic	cles, social and environmental importance of hybrid and electric vehicles.			1						
and ele		cles, social and environmental importance of hybrid and electric vehicles. HYBRID ELECTRIC DRIVE TRAINS			9	0	0	9			
UNIT Basic efficie	concept or	<u> </u>	s, pow		ow co	ontro	l, fu	ıel			
UNIT Basic efficie	concept or ency analystous electric	HYBRID ELECTRIC DRIVE TRAINS f hybrid traction, introduction to various hybrid drive-train topologies is in hybrid drive-train topologies. Electric Drive-trains: Basic concept of	s, pow		ow co	ontro	l, fu	iel on			
UNIT Basic efficie to vari UNIT	concept of analysious electric	HYBRID ELECTRIC DRIVE TRAINS f hybrid traction, introduction to various hybrid drive-train topologies is in hybrid drive-train topologies. Electric Drive-trains: Basic concept of c drive-train topologies, power flow control in electric drive-train.	s, pow electric	rol – D	ow coion, in	ontrod ntrod	l, fuuctio	iel on ges,			
UNIT Basic efficie to vari UNIT	concept or ney analystous electric CIII uction to electron Motor	HYBRID ELECTRIC DRIVE TRAINS f hybrid traction, introduction to various hybrid drive-train topologies is in hybrid drive-train topologies. Electric Drive-trains: Basic concept of c drive-train topologies, power flow control in electric drive-train. CONTROL OF AC & DC DRIVES dectric components used in hybrid and electric vehicles, Configuration and	s, pow electric	rol – D	ow coion, in	ontrod ntrod	l, fuuctio	es,			
UNIT Basic efficie to vari UNIT Introduct UNIT Introduct UNIT Introduct International Internation	concept of analysious electric TIII uction to electric TIV uction to I dization of	HYBRID ELECTRIC DRIVE TRAINS f hybrid traction, introduction to various hybrid drive-train topologies is in hybrid drive-train topologies. Electric Drive-trains: Basic concept of a drive-train topologies, power flow control in electric drive-train. CONTROL OF AC & DC DRIVES lectric components used in hybrid and electric vehicles, Configuration and drives, Permanent Magnet Motor drive, and Switch Reluctance Motor drives, Permanent Magnet Motor drive, and Switch Reluctance Motor drives, Torage Requirements in Hybrid and Electric Vehicles, Energy different energy storage devices, Sizing the drive system: Matching that ton Engine (ICE), Sizing the propulsion motor, sizing the power electror	s, powelectric	rol – Drive sy	ow coion, in 9 OC Moystem 9 and its naching	ontrod otor of efficients and the arms are are are arms.	o o o o o o o o o o o o o	on ges, cy gis, he			
UNIT Basic efficie to vari UNIT Introduct UNIT Introduct UNIT Introduct Introduct Introduct Introduct Introduct Introduct Introduct Introduct Introduct International Inte	concept of ancy analystous electric construction to electric construction to electric construction to ladization of all Combustors storage te	HYBRID ELECTRIC DRIVE TRAINS f hybrid traction, introduction to various hybrid drive-train topologies is in hybrid drive-train topologies. Electric Drive-trains: Basic concept of a drive-train topologies, power flow control in electric drive-train. CONTROL OF AC & DC DRIVES lectric components used in hybrid and electric vehicles, Configuration and drives, Permanent Magnet Motor drive, and Switch Reluctance Motor drives, Permanent Magnet Motor drive, and Switch Reluctance Motor drives, Torage Requirements in Hybrid and Electric Vehicles, Energy different energy storage devices, Sizing the drive system: Matching that ton Engine (ICE), Sizing the propulsion motor, sizing the power electror	s, powelectric	rol – Drive sy	ow coion, in 9 OC Moystem 9 and its naching	ontrod otor of efficients and the arms are are are arms.	o o o o o o o o o o o o o	es, ey is, he			

REFE	ERENCE BOOKS:
1	Iqbal Hussein, Electric and Hybrid Vehicles: Design Fundamentals, CRC press, 2003.
2	James Larminie, john lowry, Electric Vehicle Technology Explained, Wiley, 2003.
3	Mehrdad Ehsani, Yimi Gao, Sebastian E. Gay, AliEmadi, Modern Electric, Hybrid Electric and fuel cell vehicles: Fundamentals, theory and design, CRC press, 2004.
4	Randd.A.J, Woods, R & dell rm Batteries for electric vehicles, john wiley & Sons,1998.

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:							
CO1	Characterize and configure hybrid drive trains requirement for a vehicle.	Understand						
CO2	Design and apply appropriate hybrid and electric drive trains in a vehicle.	Create						
CO3	Design and install suitable AC and DC drives for electric vehicles.	Create						
CO4	Arrive at a suitable energy storage system for a hybrid/electric vehicle.	Understand						
CO5	Apply energy management strategies to ensure better economy and efficiency.	Apply						

COURSE	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2		1	1	1								1
CO2	3	2	2		1	1		1	1						2
CO3	3	1	3	1	2	1	1	2		1					2
CO4	2	3	1	1	1	1	1	1		1	2			1	1
CO5	3	2			1	1	1			2	1	2		1	1
Avg	2.8	2	2	1	1.2	1	1	1.3	1	1.3	1.5	2		1	1.4
			3/2/1 -	- indica	ates str	ength o	of corr	elation	(3 – Hi	igh, 2- N	Iedium	, 1- Low	r)		

22ME	H104	ALTERNATE FUELS FOR IC ENG	INES									
			CATEGORY	PE	Cr	edit	3					
			**	L	T	P	TH					
			Hours/Week	3	0	0	3					
COUR	RSE OBJE	CTIVES										
1	To expose	e potential alternate fuels and their characteristics.										
2	To use appropriate synthetic fuels and fuel additives for better combustion characteristics.											
3	To utilize alcohol fuels effectively for low emissions.											
4	To elaborate on the utilization of Bio-Diesel and its types as a suitable fuel in CI engines.											
5	To utilize	different gaseous fuels and predict their performance and co	ombustion characteris	stics.								
UNIT	T I INTRODUCTION											
		, suitability, properties, merits and demerits of potential ed Petroleum Gas, Natural Gas, Biogas, Fuel standards—AST		Alcoh	ols, I	Bio-D	iesel,					
UNIT	· II	SPECIAL AND SYNTHETIC FUELS			9	0 () 9					
effect		fuels, Merits and demerits, Dual, Bi-fuel and Pilot inject definance and emission characteristics of engines, Ethers-as										
UNIT	III	ALCOHOL FUELS			9	0 () 9					
		es, Production methods and usage in engines. Performance, cel limitation in alcohols.	combustion and emis	sion C	harac	eterist	ics in					
UNIT	IV	BIO-DIESEL FUELS			9	0 () 9					
	ting, Transe	their important properties. Fuel properties characterization. It esterification and emulsification – Performance, combustion										
UNIT	· V	GASEOUS FUELS			9	0 () 9					
		ss, LPG, Hydrogen–Properties, problems, storage and safety on in Gaseous fuels.	spects. Methods of	utiliza	tion i	in eng	gines.					
			Tota	l (45I	ر ا ا ا	45 Pe	eriod					

REF	ERENCE BOOKS:								
1	Keith Owen and trevoreoley, Automotive Fuels Handbook, SAE publications, 1990.								
2	Pundir B.P, I.C.Engines Combustion and Emission, 2010, Narosa publishing house.								
3	PundirB.P, Engine Combustion and Emission, 2011, Narosa publishing house, Keith.								
4	Richard l.Bechtold, Automotive Fuels guide book, SAE publications, 1997.								

	URSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Analyze potential alternate fuels and their characteristics.	Analyze
CO2	Use appropriate synthetic fuels and fuel additives for better combustion characteristics.	Understand
СОЗ	Describe the properties of alcohol fuel and estimate the performance of alcohol fuels and its emissions.	Understand
CO4	Explain the properties and combustion and emission characteristics of bio-diesel.	Understand
CO5	Explain different gaseous fuels and predict their performance and combustion characteristics.	Understand

COURSE A	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3		1	1	1								3	2
CO2	3	2	1	1		1					1			2	2
CO3	2	3	2	1	1		1			1				2	2
CO4	2	1	1	1	1	1	1		1		2				2
CO5	1					2				2	1				
Avg	2.2	2.25	1.3	1	1	1.25	1		1	1.5	1.3			2.3	2
		3/	/2/1 – i	ndicat	es stre	ength o	of corr	elation	(3 – H	igh, 2- M	ledium,	1- Low)			

TEGORY											
	PE	Cre	dit	3							
/887	L	Т	P	TH	I						
rs/Week	3	3 0 0									
		u .									
applications.											
the various modelling techniques of energy storage systems using TRNSYS.											
the students to get understand the concepts of Hydrogen and Biogas storage.											
de the insights on flywheel and compressed energy storage systems.											
UNIT I INTRODUCTION											
orage technolo	ogies –	Appli	catio	ns.							
		9	0	0	9						
d rock bed sto packed bed sto			n– pr	essur	ized						
		9	0	0	9						
g and dischar											
el – Cadmium,		9	0	0	9						
el – Cadmium,	l Stora	age, B	Biogas	stor	age-						
el – Cadmium, ides, chemica ations.		_	0	0	9						
ides, chemica		9			_						
id	tions.		ES 9	ES 9 0	ES 9 0 0						

REF	ERENCE BOOKS:
1	Ibrahim Dincer and Mark A.Rosen, Thermal Energy Storage Systems and Applications, John Wiley & Sons 2002
2	James Larminie and Andrew Dicks, Fuel cell systems Explained, Wiley publications, 2003
3	LuisaF. Cabeza, Advances in Thermal Energy Storage Systems: Methods and Applications, Elsevier Wood head Publishing, 2015.
4	Robert Huggins, Energy Storage: Fundamentals, Materials and Applications, 2 nd edition, Springer, 2015.
5	Ru-shiliu, Leizhang, Xueliangsun, Electro-chemical technologies for energy storage and conversion, Wiley publications, 2012.

	OURSE OUTCOMES: Upon completion of this course, the students will be able to:							
CO1	Identify the energy storage technologies for suitable applications	Analyze						
CO2	Analyze the energy storage systems	Analyze						
<i>CO3</i>	Recognize the concept sand types of batteries	Understand						
CO4	Diagnose the principle of operations of Hydrogen and Bio gas storage	Understand						
CO5	Analyze the concepts of fly wheel and compressed energy storage systems	Analyze						

COURSE ARTICULATION MATRIX															
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2			1	1		1						3	1
CO2	2	3	1	1	1		1		1						
CO3	3	2		1			1	1			1			3	
CO4	3	1	2	1	1	2	1			2				1	1
CO5	2	3	1	1					1						1
Avg	2.6	2.2	1.3	1	1	1.5	1	1	1	2	1			2.3	1
Avg	2.6			indics	l tes sti			l relatio	n (3 –	_	Medium	n 1. Lov	w)	2.3	1

22MEH106	SOLAR POWER PLANT	S											
		CATEGORY	PE	Cro	edit		3						
		Hours/Week	L	T	P	Т	Ή						
		Hours, Week	3	0	0		3						
COURSE OI	JECTIVES				•								
1 To e	plain concept of various power cycles involved in the	solar power plants.											
2 To le	arn and study the solar adiation and various solar power	er plants.											
3 To o	tline the variety of solar systems used to collect solar	energy.											
4 To le	To learn electrical performance of PV power plants.												
5 To s	To summarize basic economics of solar power plants.												
UNIT I	INTRODUCTION			9	0	0	9						
Power Plant S	cenario - Classification, Basic Principles and Features	– Comparison and select	tion crit	eria									
UNIT II	SOLAR POWER CYCLES			9	0	0	9						
Vapour cycle	- Organic cycles - Combined Cycles - Binary Cycles	- Stirling Cycle - Bray	ton Cyc	le – F	Ericsso	n Cy	cle						
UNIT III	SOLAR THERMAL POWER PLANTS			9	0	0	9						
	eiver, Energy Transfer Power cycles - Tower, Trougeys – Hybrid Systems	th and Dish Systems- C	oncentr	ating	Dish	Syst	ems						
UNIT IV	SOLAR PV POWER PLANTS			9	0	0	9						
	PV Power Programmes – Photovoltaic Power System Stand-Alone Systems - Grid-Connected Systems – El		– Energ	gy Sto	orage	– Po	wer						
UNIT V	ECONOMICS OF POWER PLANTS			9	0	0	9						
	king power tariff –Simple methods to calculate the p lysis for the selection of alternative decisions and the f			- Pa	yback	Peri	od -						
		T	otal(4	5L) =	45Pc	erio	ds						

REF	ERENCE BOOKS:
1	Duffie, J.A., and Beckman, W.A. Solar Energy Thermal Process, John Wiley and Sons, NewYork, 2006.
2	Kosuke Kurokawa (Ed.), Energy from the Desert –Feasibility of very large-scale photo-voltaic power generation systems, James and James 2003.
3	Sukhatme S.P., SolarEnergy, Tata McGraw Hills Pvt Co., 3 rd Edition, 2008.
4	C.J.Winter, R.L.Sizmann, L.L.Vant-Hull, Solar Power Plants, Springer-Verlag Berlin and Heidel berg GmbH & Co.K, 2001.

	URSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Describe the concept of various power cycles involved in the solar power plants were learnt.	Understand
CO2	Analyze different cycle for solar power generation.	Analyze
<i>CO3</i>	Describe the construction and working of component solar thermal power plant.	Understand
CO4	Explain PV system and its integration.	Understand
CO5	Fix power tariff and analyze economical aspects of power plant.	Analyze

COURSE	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1	1		1	2	1							2	2
CO2	3	2	1	1	2		1							2	2
CO3	2	1			1		1							1	
CO4	3	2	1	2				1						1	1
CO5	1	2			2									1	
Avg	2.4	1.6	1	1.5	1.5	2	1	1						1.4	2
		3	/2/1 – i	indicat	es stren	gth of o	correla	tion (3	– Higl	h, 2- Me	dium, 1-	Low)	-		

22ME	H107	MATERIALS FOR SOLAR DEVI	CES					
			CATEGORY	PE	Cre	dit	3	
			/	L	T	P	Tl	H
			Hours/Week	3	0	0	3	}
COUR	SE OBJ	ECTIVES	1		I		ı	
1	To cor	nprehend the materials that has been implicated in various	forms of solar energy	source	es and	its s	tora	ges
2	To edu	icate the structure-property relationship and appreciate eno	vel developments in t	he mat	erials.			
3	To exp	plain the concept and the diverse materials used for solar de	evices.					
4	To exp	plicate in depth knowledge of about solar cells, thermal ene	ergy storage and electr	rical en	ergy s	storaș	ges.	
5	To gat	her idea of system balance and analysis with reference to it	ts cost.					
UNIT	ľ	MATERIALS FOR SOLAR COLLECTORS			9	0	0	9
Absort	ber Coat	rials for Low, Medium and High Temperature Applicatio ings, Insulations, Use of Plastics – Reliability and Dur- Low-Cost Solar Collectors.						
UNIT	`II	MATERIALS FOR SOLAR CELLS			9	0	0	9
impuri		acture – Fundamental Principles of Energy Bands–Types of ergy levels—Structure of Silicon solar cell – Fabrication ells						
UNIT	III	NOVEL AND THIN FILM SOLAR CELLS			9	0	0	9
		uride, Galium-Arsenic, GaInP/GaAs/Ge-Thin Film, Single andem Junction Solar Cells – Conversion Efficiency of Sol				ials-	Mu	lti
UNIT	IV	ENERGY STORAGE MATERIALS			9	0	0	9
	rgeable l	ge Concepts - Materials for Sensible and Latent Heat Eng Batteries – Types, Operating range, Comparison and s						
UNIT	· V	MATERIALS AND COST ANALYSIS			9	0	0	9

REFERENCE BOOKS:

1 Ibrahim Dincer and Marc A Rosan, Thermal Energy Storage: Systems and Applications, JohnWiley, 2003.

2 Sukhatme and Nayak, Solar Energy: Principles of Thermal Collection & Storage, Tata McGraw Hill, 2008.

3 Nelson.J, The Physics of Solar Cells, Imperial College Press, 2003.

4 Jef Poortmans and Vladimir Arkhipov, Thin Film Solar Cells, John Wiley and Sons, 2008.

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:					
CO1	CO1 Describe the fundamental principles of materials best suited for making solar collectors, their reliability, characteristics and possibility of using plastics.					
CO2	Explore the materials for solar cells, principles, doping and fabrication and optimizations of solar cells.	Analyze				
СОЗ	Explore the novel materials for the fabrication of solar cell, their efficiency and organic solar cells.	Analyze				

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Thomas Markvart, Solar Electricity, John Wiley and Sons, 2007.

CO4	Explain the concept and the diverse materials used for solar energy devices for diverse applications.	Understand
CO5	Describe the requirements of system balance and analysis with reference to its cost.	Understand

COURSE	AR	ricu	LAT	ION	MAT	RIX									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	1					1					1	1	1
CO2	3	2	1				1						1	1	2
CO3	2	3			1								2	2	2
CO4	2	1			2	1			1				1	1	1
CO5	3	2		1			1					1	1	1	2
Avg	2.6	2	1	1	1.5	1	1	1	1			1	1.2	1.2	1.6
	•		3/2/1 -	- indi	cates	streng	th of	correla	tion (3	– High,	2- Mediu	ım, 1- Lo	w)		

22M	EH108	DESIGN OF SOLAR AND WIND SYSTEM	IS					
		(CATEGORY	PE	Cre	dit	3	
			/XX/ X	L T		ГР		I
		He	ours/Week	3	0	0	3	
OUI	RSE OBJ	ECTIVES						
1	To lear	rn and study the radiation principles with respective solar energy e	estimation.					
2	To und	lerstand PV technology principles and techniques of various solar	cells / materials	s for e	nergy	con	versi	ion
3	To und	derstand the fundamentals of wind energy and its conversion syste	em.					
4	To und	derstand the aerodynamics and types of loads, generators in wind t	turbines.					
5	To lear	rn and study the radiation principles with respective solar energy e	estimation.					
UN	ITI	SOLAR RADIATION AND COLLECTORS			9	0	0	9
Sun a	angles–Rac	diation-extra-terrestrial characteristics -estimation on horizontal a	and tilted surface	es - fla	at plat	e col	lect	or
thern parar	nal analys neters - co	sis —evacuated tubular collectors-concentrator collectors—cla: pmpound parabolic concentrators - parabolic trough concentrators	ssification-desig				nan	ce
thern parar UN Princ	nal analys meters - co WIT II	sis -evacuated tubular collectors-concentrator collectors-clas-	ssification-desig -Heliostats. ng systems— Th	gn ar	nd pe	erfori 0	nan 0	се 9
UN Prince syste	nal analys meters - co WIT II	sis —evacuated tubular collectors-concentrator collectors—classimpound parabolic concentrators - parabolic trough concentrators SOLAR THERMAL TECHNOLOGIES orking, types, design and operation of-Solar heating and coolin	ssification-desig -Heliostats. ng systems— Th	gn ar	nd pe	erfori 0	nan 0	ge
UN Prince syste UN Solar – PV	nal analys meters - co IIT II ciple of wo ms - Solar IIT III cells - p-n system de	sis —evacuated tubular collectors-concentrator collectors—classimpound parabolic concentrators - parabolic trough concentrators SOLAR THERMAL TECHNOLOGIES orking, types, design and operation of-Solar heating and cooling to Desalination — Solar cooker: domestic, community — Solar Pond	-Heliostats. ng systems— Th I – Solar drying. ction - solar cell storage autonom	ermal	9 Ener desig	o gy st	o coraș	9 ge
Princ syste UN Solar – PV - cen	nal analys meters - co IIT II ciple of wo ms - Solar IIT III cells - p-n system de	sis —evacuated tubular collectors-concentrator collectors—classimpound parabolic concentrators - parabolic trough concentrators SOLAR THERMAL TECHNOLOGIES orking, types, design and operation of-Solar heating and cooling pesalination — Solar cooker: domestic, community — Solar Pond SOLAR PV SYSTEM DESIGN n junction- Solar cell array system analysis and performance predicted processing — design — design process and optimization — detailed array design — sections are supported by the section of	ng systems— The language of th	ermal array ny - vo	9 Ener desig	o gy st	o coraș	ge 9 ots
UN Prince syste UN Solar - PV - cen UN Wince turbin	nal analyse meters - co ITT II ciple of woms - Solar ITT III cells - p-n system de tralized an ITT IV I Energy Enes, Atmos	sis —evacuated tubular collectors-concentrator collectors—classis —evacuated tubular collectors-concentrators of parabolic trough concentrators. SOLAR THERMAL TECHNOLOGIES orking, types, design and operation of-Solar heating and cooling Desalination — Solar cooker: domestic, community — Solar Pond SOLAR PV SYSTEM DESIGN n junction- Solar cell array system analysis and performance predicted processing — design process and optimization — detailed array design — sid decentralized SPV systems — hybrid and grid connected systems.	ng systems— The language of th	ermal array ny - vo	9 Ener 9 designification of the content of the cont	o gy st o o o o o o o o o o o o o o o o o o	oraș oraș	9 9 ots on 9 nd
thern parar UN Prince syste UN Solar PV - cen UN Wince turbin	nal analyse meters - co ITT II ciple of woms - Solar ITT III cells - p-n system de tralized an ITT IV I Energy Enes, Atmos	sis —evacuated tubular collectors-concentrator collectors—classic propound parabolic concentrators - parabolic trough concentrators SOLAR THERMAL TECHNOLOGIES orking, types, design and operation of-Solar heating and cooling pesalination — Solar cooker: domestic, community — Solar Pond SOLAR PV SYSTEM DESIGN in junction- Solar cell array system analysis and performance predicted process and optimization — detailed array design — sed decentralized SPV systems — hybrid and grid connected systems. WIND ENERGY FUNDAMENTALS AND WIND MESASICS, Wind Speed sand scales, Terrain, Roughness, Wind Mechaspheric Boundary Layers, Instrumentation for wind measurements,	ng systems— The language of th	ermal array ny - vo	9 Ener 9 designification of the content of the cont	o gy st o o o o o o o o o o o o o o o o o o	oraș oraș	9 ots on 9 nd

Air foil terminology, Blade element theory, Blade design, Rotor performance and dynamics, Balancing technique (Rotor & Blade), Types of loads, Sources of loads - Vertical Axis, Horizontal Axis, Constant Speed, Constant Frequency, Variable speed, Variable Frequency, Stall Control, Pitch Control, Gear Coupled Generator type, Direct generator drive systems.

Total (45L) = 45 Periods

REF	ERENCE BOOKS:
1	Sukhatme S.P., Nayak.J.P, 'Solar Energy –Principle of Thermal Storage and collection", Tata McGraw Hill, 2008.
2	Solar Energy International, "Photovoltaic – Design and Installation Manual" –New Society Publishers, 2006.
3	DuffieA.and Beckann W.A., "Solar Engineering of Thermal Processes, JohnWiley, 1991.
4	John D S orensen and Jens N S orensen, "Wind Energy Systems", Wood head Publishing

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:				
CO1	Classify and describe solar radiation and collectors.	Understand			
CO2	Describe the principle and design the solar heating, cooling and other solar applications.	Understand			
CO3	Explain the principle, working, design optimization of PV system for different applications.	Understand			
CO4	Describe the basics and measurements of wind energy.	Understand			
CO5	Explain the aerodynamic constructional details of wind turbine.	Understand			

COURSE A	ARTI	CUL	ATIC	N M	ATR	IX									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	1										3	1	
CO2	3	1	2	1									3	2	
CO3	3	2	2		1					1			3	2	2
CO4	3	2		1		1							3	2	
CO5	3	2			1	1							3	2	
Avg	3	1.8	1	1	1	1				1			3	1.8	2
	•		3/2/1	– indi	cates	streng	gth of	correla	tion (3	– High,	2- Mediu	m, 1- Lov	v)		

22MF	EH109	FIRE ENGINEERING AND EXPLOSION C	CONTROL					
			CATEGORY	PE	Cre	dit	3	}
			II arrag/Wash	L	Т	P	Т	Ή
			Hours/Week	3	0	0	3	3
COUI	RSE OB	JECTIVES		1	ı	l.		
1	To und	erstand and learn the fundamentals of fire, explosion and the	eory of combustion					
2	To kno	w various classes of fires and types of fire extinguishers.						
3	To und	erstand and learn various fire protection systems, component	ts and their workin	g.				
4	To und	erstand the various fire-resistant materials and to design fire	protection of build	ling.				
5	To und	erstand the principles of explosion protection systems.						
UNIT	`I	FIRE AND EXPLOSIONS			9	0	0	9
classes	s of fires-	ion—fire triangle — principles of fire extinguishing — active ar — A,B,C,D,E —types of fire extinguishers— fire stoppers—hydrors—escape from fire rescue operations—fire drills—notice—fire	drant pipes – hoses					
UNIT	III	FIRE PROTECTION SYSTEM COMPONENTS			9	0	0	9
the abo	ove instal	lrants – stand pipes – special fire suppression systems like cllations, reliability, maintenance, evaluation and standards – system, foam system – smoke venting – fire fighting system	alarm and detection					
UNIT	IV	BUILDING FIRE SAFETY			9	0	0	9
structu	ıral integ	ire safe building design, Fire load, fire resistant material and rity – concept of egress design– with calculations- fire certisnookers.						
UNIT	V	EXPLOSION PROTECTING SYSTEMS			9	0	0	9
Flame	Arrestors	xplosion- detonation and blast waves- explosion paramete, isolation, suppression, venting, explosion relief of large erstem based on carbon-di-oxide (CO ₂) and halons - hazards i	nclosure - explosio	n ven	ting -	inert	gase	es,

Total (45L) = 45 Periods

REFE	RENCE BOOKS:
1	Gupta, R.S., "Hand Book of Fire Technology" Orient Longman, Bombay 1977.
2	"Accident Prevention manual for industrial operations" N.S.C., Chicago, 1982.
3	DinkoTuhtar, "Fire and explosion protection".
4	Davis Daniel etal, "Hand Book of fire technology".
5	"Fire fighters hazardous materials reference book" Fire Prevention in Factories", An Nostrand ReinHold, New York, 1991.

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:					
CO1	Describe the fundamentals of fire, explosion and theory of combustion.	Understand				
CO2	Classify the fire, class of fire and equipment for fire extinguishing.	Understand				
CO3	Explain various industrial fire protection systems components and their working.	Understand				
CO4	Design the building with fire protection and concepts of their design.	Create				
CO5	Describe the explosion protection system for various application.	Understand				

COURSE ARTICULATION MATRIX															
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2		1		1							2		
CO2	3	2				1	2						2		
CO3	3	2		1	2	1	2						2		
CO4	2	1	3	2		1	2				1		2		
CO5	3	2		1	2	2	1				1		2		
Avg	2.8	1.8	3	1.25	2	1.2	1.75				1		2		
		•	3/2/1	– indi	icates	streng	gth of	correla	tion (3	– High,	2- Mediu	m, 1- Lov	v)	•	

22ME	H110	ENERGY MANAGEMENT AND ENVIRO BENEFITS	ONMENTAL					
			CATEGORY	PE	Cred	lit		3
				L	Т	P	TI	Η
			Hours/Week	3	0	0		3
COUR	SE OBJE	ECTIVES		•	•			
1	To creat	e awareness on the energy scenario of india with respect to	world.					
2	To learn	the methodology adopted for an energy audit.						
3	To appre	eciate the concepts adopted in project management.						
4	To study	the different techniques adopted for financial appraisal of	a project.					
5	To comp	prehend the impact of energy on environment.						
UNIT	· I	ENERGY SCENARIO			9	0	0	9
energy	demand, tance, Ener	nergy scenario – India and World (energy sources, genera per capita energy consumption) – energy pricing—energy Conservation Act 2001. ENERGY MANAGEMENT						
Energy substit	y audit-nee cution–billi	d-types- methodology- barriers-analysis on energy costing parameters in TANGEDCO-demand side manage argeting- CUSUM energy labeling.			ıg- fu	el and	l ene	rgy
UNIT	· III	PROJECT MANAGEMENT			9	0	0	9
Defini	tion and S	ents of Project Management- Project Management Life Cope, Technical Design, Financing, Contracting, Implemormance Monitoring.						
UNIT	CIV	FINANCIAL MANAGEMENT			9	0	0	9
		uisal for energy conservation projects - Financial analysis to present value, Internal rate of return - Cashflows, Risk and						
UNIT	V	ENERGY AND ENVIRONMENT			9	0	0	9
Conce (COP)	rns– Unite , Emission	ct and the carbon cycle - current evidence and future effect d Nations Frame work Convention on Climate Change (UN is trading (ET), Joint Implementation (JI), Clean Develop- ainable development.	FCC), Kyoto Protoc	ol, Co	nferei	ice of	f Part	ties

REFE	REFERENCE BOOKS:								
1	Energy Manager Training Manual (4 Volumes) available at http://www.em- ea.org/gbook1.asp, a website administered by Bureau of Energy Efficiency (BEE), a statutory body under Ministry of Power, Government of India.2004.								
2	L.C.Witte, P.S.Schmidt, D.R.Brown, "Industrial Energy Management and Utilisation" Hemisphere Publ, Washington, 1988.								
3	W.C.turner, "Energy Management Handbook" Wiley, New York, 1982.								
4	W.R.Murphy and G.McKay "Energy Management" Butterworths, London1987.								
5	Eastop.T.D & Croft D.R, Energy Efficiency for Engineers and Technologists, Logman Scientific & Technical, ISBN-0-582-03184, 1990.								

COUR Upon o	Bloom Taxonomy Mapped				
CO1	Recognize the importance of energy conservation and suggest measures for improving percapita energy consumption.				
CO2	Analyses the energy sharing and cost sharing pattern of fuels used in industries.				
CO3	Apply Gantt Chart, CPM and PERT in energy conservation projects.	Apply			
CO4	Evaluate the techno-economics of a project adopting discounting and non-discounting cashflow techniques.	Evaluate			
CO5	5 Assess the sources of additional revenue generation for energy conservation projects adopting. Evaluate				

COURSE A	OURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	1	1		1				1	1			2	2
CO2	3	2				1						2		2	
CO3	3	1	1	1		1								2	3
CO4	3	2					1					1			2
CO5	2	1			1	2	1								
Avg	2.8	1.6	1	1	1	1.25	1		1	1	1	1.5		2	2.3
	ı		3/2/1 -	– indic	cates s	treng	th of c	orrelat	tion (3 -	- High, 2	- Mediur	n, 1- Low	<i>y</i>)	•	•

VERTICAL 2 - COMPUTATIONAL ENGINEERING

22MEH201	NUMERICAL METHODS IN MECHANICAL ENG	GINEERING				
PREREQUISI	TES	CATEGORY	PE	Cr	edit	3
			L	Т	P	ТН
		Hours/Week	3	0	0	3
COURSE OB	ECTIVES:			<u> </u>	<u> </u>	
	mpletion of this course, the students will understand and systemati ifferential equations governing the physics of mechanical engineer		on tech	nniqu	es for	the
2. Numeric would o	al Methods use computers to solve problems by step-wise, repeate therwise be tedious or unsolvable by hand-calculations.	ed and iterative solu	ition m	ethoo	ls, wh	ich
3. This cou	rse is designed to give an overview of numerical methods of interes	st to scientists and r	nechan	ical e	ngine	ers.
UNIT I	ERRORS		9	0	0	9
UNIT II	LINEAR ALGEBRAIC EQUATION		9	0	0	9
UNIT II Linear Algebra			compo	sition	meth	od,
	abolic regression - Interpolation–Interpolating polynomial, Lagran					
UNIT III	NUMERICAL DIFFERENTIATION AND INTEGRAT	ΓΙΟΝ	9	0	0	9
Integration of	erentiation and Integration - Newton-Cote's Integration of equati Equation: Gauss Quadrature methods Numerical differentiationula, Central difference Formula, Backward difference Formula, nula.	on: For Equally sp	aced I	Data:	Forw	ard
difference Form				_	0	
	ORDINARY DIFFERENTIAL EQUATION		9	0	U	9
UNIT IV Ordinary Diffe	ential Equation - Taylor's series method, Picard's Method, Euler's per Problem- Finite Difference Method - Eigen value problem: Eigen		utta 4 th	Orde	r metl	hod
UNIT IV Ordinary Diffe	rential Equation - Taylor's series method, Picard's Method, Euler's		utta 4 th	Orde	r metl	hod

	10tal (45L) = 45 1 C110tas
TEXT BOOKS:	

1.	B. S. Grewal and J. S. Grewal, "Numerical methods in Engineering and Science," 6 th Edition, Khanna publishers, New Delhi, 2004.						
2.	D. G. Luenberger, "Linear and Nonlinear Programming," Springer, 3rd Edition, 2008.						
REFE	ERENCES:						
1.	K. E. Atkinson, "An Introduction to Numerical Analysis," Wiley, 2nd Edition, 1989.						
2.	S. D. Conte and C. de Boor, Elementary Numerical Analysis, Third Edition, Tata McGraw-Hill Education, 2005.						
3.	F.B. Hildebrand, Introduction to Numerical Analysis, Second (Revised) Edition, Courier Dover Publications, 1987.						
4.	E. Kreyszig, Advanced Engineering Mathematics, Tenth Ed., John Wiley and Sons, 2010						
5.	R. L. Burden and J. D. Faires, Numerical Analysis, 9th Edition (second Indian Reprint 2012), Brooks/Cole, 2011.						

6.	L.N. Trefethen, David Bau III, Numerical Linear Algebra, SIAM, 1997.
7.	A.Quarteroni, R. Sacco, and F. Saleri. Numerical Mathematics, Springer-Verlag, New York, 2000.

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:					
CO1	Apply various methods to find roots of equations.					
CO2	Implement different methods to solve simultaneous equations and apply the methods of Regression and interpolation.					
CO3	Implement various numerical methods for differentiation and Integration.	Apply				
CO4	Apply various methods to solve engineering problems with Ordinary differential equations.					
CO5	Solve Partial differential equations involved in Engineering Problems.					

COURSE A	OURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	1	2	1								2	1	
CO2	3	3	1	2	1								2	1	
CO3	3	3	1	2	1								2	1	
CO4	3	3	1	2	1								2	1	
CO5	3	3	1	2	1								2	1	
Avg	3	3	1	2	1								2	1	
			3/2/1 -	- indic	ates st	rengt	h of co	rrelati	on (3 -	- High,	2- Medi	um, 1- L	ow)		•

22MEH202	ADVANCED FLUID MECHANICS							
	CAT	EGORY	PE	Cr	edit	3		
		/TT/ 1	L	Т	P	ТН		
	Hou	Hours/Week	3	0	0	3		
COURSE OF	JECTIVES:			1	1	.1		
Enhanced under	estanding of fluid mechanics, including the equations of motion in differen	itial form and	d turbu	lence				
UNIT I	INTRODUCTION		9	0	0	9		
deformation of	agrangian description of fluid motion, Lines of flow visualization an fluid elements, Linear and volumetric deformation; Perspectives fron gral form stream function and velocity potential.							
UNIT II	VISCOUS FLUID FLOW		9	0	0	9		
Reynolds Transcontrol volume	for invpiscid flow, Bernoulli's equation, Examples of bernoulli's equation port Theorem Mass and Linear Momentum Conservation, Reynolds transport theorem angular momentum conservation, Introduc Navier equation, Navier Stokes equation.	sport theore	n arbi	trarily	mov	ing		
UNIT III	NIT III FLUID DYNAMICS 9 0 0 9							
Lubrication The	eory, Thin Film Dynamics, Stokes flow past a sphere.							
UNIT IV	TURBULENCE		9	0	0	9		
Layer Theory, S	Turbulence, Statistical Treatment of Turbulence and Near - Wall Velocity I Similarity Solution of Boundary Layer Equation, Momentum Integral Mel and Boundary Layer Separation, Potential Flow.							

Stagnation properties, Compressible flows - Variable area - Normal shock - Converging Nozzle- Converging Diverging Nozzle - Compressible Flow with Friction.

COMPRESSIBLE FLOWS

UNIT V

Total (45L) = 45 Periods

0

9

0

TEXT I	TEXT BOOKS:					
1.	Rouse, H. (1957), "Advanced Fluid Mechanics", John Wiley & Sons, N York.					
2.	Mohanty A.K. (1994), "Fluid Mechanics", Prentice Hall of India, N Delhi.					
REFE	RENCES:					
1.	Wand D.J., and Harleman D.R. (1964) "Fluid Dynamics", Addison Wesley.					
2.	Schlichting, H.: (1976) "Boundary Layer theory", International Text – Butterworth.					
3.	Lamb, H.R. (1945) "Hydrodynamics", Rover Publications.					
4.	White, F.M. (1980) "Viscous Fluid Flow", McGraw Hill Pub. Co, N York.					
5.	Yalin, M.S. (1971), "Theory of Hydraulic Models", McMillan Co.,.					

	SE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Explain the fundamental concepts of fluid flow.	Understand
CO2	Apply the Bernoulli equation to solve problems related to viscous fluid flow.	Apply
CO3	Device the concepts of fluid dynamics in various geometry.	Create
CO4	Depict the turbulence of fluid flow.	Analyze
CO5	Interpret the knowledge for compressible flows in various geometrical configuration.	Evaluate

COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	2	3								1	2	2	
CO2	3	3	2	3								1	2	2	
CO3	3	3	2	3	3							1	2	2	
CO4	3	3	2	3								1	2	2	
CO5	3	3	2	3	3							1	2	2	
Avg	3	3	2	3	3							1	2	2	

22MF	EH203	FUNDAMENTALS OF BIO-MECHANI	CS				
PRE	REQUISIT	TES	CATEGORY	PE	Cre	edit	3
D	1 1.1		II / XV I-	L	T	P	TH
Basic	knowledge	of physics and biology which includes kinetics and kinematics.	Hours/Week	3	0	0	3
COU	RSE OBJ	ECTIVES:			•		
1.	Explain the	e principles of mechanics.					
2.	Discuss the	e mechanics of physiological systems.					
3.	Explain the	e mechanics of joints.					
4.	Illustrate tl	he mathematical models used in the analysis of biomechanical s	ystems				
UNI	ΤΙ	INTRODUCTION TO MECHANICS		9	0	0	9
coup - Linaccel	le, Resultant near motion eration, Kin	calars and vectors, Statics – Force types, Resolution and comp force determination, parallel forces in space, equilibrium of cop , Newton's laws of motion, Impulse and Momentum, Work ematics – Link segment models, Force transducers, Force plates tions of Non-viscous fluid, Newtonian Viscous fluid and Hooke	lanar forces, Dynam and Energy. Kine Introduction to Cor	ics - B tics –	asic p Velo	rinci _l city	ples and
UNI	T II	BIO-FLUID MECHANICS		9	0	0	9

Intrinsic fluid properties – Density, Viscosity, Compressibility and Surface Tension, Viscometers – Capillary, Coaxial cylinder and cone and plate, Rheological properties of blood, Pressure-flow relationship for Non-Newtonian Fluids, Fluid mechanics in straight tube – Steady Laminar flow, Turbulent flow, Flow development, Viscous and Turbulent Sheer Stress, Effect of pulsatility, Boundary Layer Separation, Structure of blood vessels, Material properties and modeling of Blood vessels, Heart – Cardiac muscle characterization, Native heart valves – Mechanical properties and valve dynamics, Prosthetic heart valve fluid dynamics.

UNIT III BIO-SOLID MECHANICS 9 0 0 9

Constitutive equation of viscoelasticity – Maxwell & Voight models, anisotropy, Hard Tissues – Structure, blood circulation, elasticity and strength, viscoelastic properties, functional adaptation, Soft Tissues – Structure, functions, material properties and modeling of Soft Tissues – Cartilage, Tendons and Ligaments Skeletal Muscle – Muscle action, Hill's models, mathematical modeling, Bone fracture mechanics, Implants for bone fracture

UNIT IV BIO-MECHANICS OF JOINTS 9 0 0 9

Skeletal joints, forces and stresses in human joints, Analysis of rigid bodies in equilibrium, Free body diagrams, Structure of joints, Types of joints, Biomechanical analysis of elbow, shoulder, spinal column, hip, knee and ankle, Lubrication of synovial joints, Gait analysis, Motion analysis using video.

UNIT V MODELING AND ERGONOMICS 9 0 0 9

Introduction to Finite Element Analysis, finite element analysis of lumbar spine; Ergonomics – Musculoskeletal disorders, Ergonomic principles contributing to good workplace design, Design of a Computer work station, Whole body vibrations, Hand transmitted vibrations.

TEXT B	OOKS:
1.	Y.C. Fung, "Bio-Mechanics- Mechanical Properties of Tissues", Springer-Verlag, 1998.
2.	Subrata Pal, "Textbook of Biomechanics", Viva Books Private Limited, 2009.
REFE	RENCES:
1.	Krishna B. Chandran, Ajit P. Yoganathan and Stanley E. Rittgers, "Biofluid Mechanics: The Human Circulation", Taylor and Francis, 2007.
2.	Sheraz S. Malik and Shahbaz S. Malik, "Orthopaedic Biomechanics Made Easy", Cambridge University Press, 2015.
3.	Jay D. Humphrey, Sherry De Lange, "An Introduction to Biomechanics: Solids and Fluids, Analysis and Design", Springer Science Business Media, 2004.

4.	Shrawan Kumar, "Biomechanics in Ergonomics", Second Edition, CRC Press 2007.
5.	Neil J. Mansfeild, "Human Response to Vibration", CRC Press, 2005.
6.	Carl J. Payton, "Biomechanical Evaluation of movement in sports and Exercise", 2008
7.	NPTEL: Mechanical Engineering - NOC:Biomechanics of Joints and Orthopaedic Implants

COURSE OUTCOMES: Upon completion of this course, the students will be able to:		Bloom Taxonomy Mapped
CO1	Understand the fundamentals of mechanics and its application in human system.	Understand
CO2	Understand the principles of bio-fluid dynamics and its application in human system.	Understand
CO3	Understand the fundamentals of bio-solid mechanics.	Understand
CO4	Analyze the biomechanics of different human joints and also the forces at a skeletal joint for various static and dynamic human activities.	Analyze
CO5	Give Examples of computational mathematical modelling applied in Bio-mechanics.	Analyze

COURSE A	ARTI(CULA	ATIO	N MA	TRIX	X.									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	2	2							1		2	2	
CO2	2	2	2	2							1		2	2	
CO3	2	2	2	2							1		2	2	
CO4	2	2	2	2							1		2	2	

3/2/1 – indicates strength of correlation (3 – High, 2- Medium, 1- Low)

CO5

Avg

22MI	EH204	INTRODUCTION TO MACHINE LEARN	ING				
PRE	REQUISI	ΓΕS	CATEGORY	PE	Cre	dit	3
		g is a mathematical discipline, and students will benefit from a		L	T	P	TF
	background rience is ess	d in probability, linear algebra and calculus, programming, and cential.	Hours/Week	3	0	0	3
COU	RSE OBJI	ECTIVES:		•			
1.	Understar	nd a wide variety of learning algorithms.					
2.	Understar	nd how to evaluate models generated from data.					
3.	Apply the	algorithms to a real problem.					
4.	Optimize	the models learned and report on the expected accuracy that can	be achieved by a	pplying	the m	odels	
UNI	ΤΙ	INTRODUCTION		9	0	0	9
		asic definition-types of learning-designing a learning system-pe e and inductive bias- evaluation-cross-validation.	rspective and issu	es in m	achine	e lear	ning-
UNI	T II	CONCEPT LEARNING AND THE GENERAL-TO ORDERING	-SPECIFIC	9	0	0	9
		concept task, concept learning as search-find S: finding a maximal elimination algorithm-remarks on version spaces and candidate				ion s _l	paces
UNI	T III	DECISION TREE LEARNING		9	0	0	9
	rithm-hypot	cision tree representation-appropriate problems for decision tree hesis space search in decision tree learning-inductive bias inductive bias					
UNI	T IV	ARTIFICIAL NEURAL NETWORKS		9	0	0	9
netw	orks and th	arral network representation-appropriate problems for neural rule back propagation algorithm-remarks on the back propagation anced topics in artificial neural networks.					
UNI	T V	LEARNING SYSTEM		9	0	0	9
Proba K ne	ability and l arest neight	LEARNING SYSTEM Bayes learning, bayes optimal classifier, gibbs algorithm, Naïve bour learning - locally weighted regression, Computational learn Dimension -Ensemble learning, analytical learning-learning with	ning theory-PAC l	nstance- learning	based mode	learr	n

complexity-VC Dimension -Ensemble learning, analytical learning-learning with perfect domain theories: prolog –EBG.

REFER	RENCES:
1.	Machine Learning. Tom Mitchell. First Edition, McGraw- Hill, 1997.
2.	Introduction to Machine Learning Edition 2, by Ethem Alpaydin
3.	T. Hastie, R. Tibshirani, and J. Friedman. The Elements of Statistical Learning. Springer 2011. (Available for download on the authors' web-page: http://statweb.stanford.edu/~tibs/ElemStat Learn/)
4.	Kevin P. Murphy. Machine Learning: A Probabilistic Perspective, MIT Press 2012. (Electronic copy available through the Bodleian library.)
5.	Christopher M. Bishop. Pattern Recognition and Machine Learning, Springer 2007.
6.	S. Haykin. Neural networks and learning machines. Pearson 2008.

	SE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Have a good understanding of the fundamental issues and challenges of machine learning: data, model selection, model complexity, etc.	Understand
CO2	Have an understanding of the strengths and weaknesses of many popular machine learning approaches.	Understand
СОЗ	Appreciate the underlying mathematical relationships within and across Machine Learning algorithms and the paradigms of supervised and un-supervised learning.	Understand
CO4	Be able to design and implement Artificial Neural Networks algorithms in a range of real-world applications.	Create
CO5	Be able to design and implement various machine learning algorithms in a range of real-world applications.	Create

COURSE A	ARTI	CUL	ATIO	N M	ATRI	X									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2		1	3							1	2	2	
CO2	2	2		1	3		3					1	2	2	
CO3	2	2		1	3							1	2	2	
CO4	2	2		1	3		3					1	2	2	
CO5	2	2		1	3		3					1	2	2	
Avg	2	2		1	3		3					1	2	2	
	•		3/2/1 -	- indic	ates s	trengt	h of co	rrelati	on (3 –	High, 2	- Mediu	m, 1- Lo	w)		

22MEH205	DESIGN OPTIMIZATION AND DESIGN THEORY				
	CATEGO	RY PE	Cr	edit	3
	** (33)	, L	Т	P	TH
	Hours/We	3	0	0	3
COURSE OBJ	IECTIVES:				
	ojective of this course is for students to gain knowledge to translate practical encal optimization problems that can be solved using numerical methods for optim		esign	proble	ems
UNIT I	INTRODUCTION	9	0	0	9
optimization tec	function, design constraints, and classification of optimization problems.	onigic and	iiiui	11 V at 16	ioic
UNIT II		9	0	0	9
The technique	DESIGN OPTIMIZATION TECHNIQUE of unconstrained minimization. The Golden section, Random, Pattern, and O		Ů	Ů	
The technique	DESIGN OPTIMIZATION TECHNIQUE		Ů	Ů	
The technique Interpolation M UNIT III Direct methods	DESIGN OPTIMIZATION TECHNIQUE of unconstrained minimization. The Golden section, Random, Pattern, and Gethods, and equality and inequality constraints.	Gradient Se	earch 0	Metho	ods,
The technique Interpolation M UNIT III Direct methods	DESIGN OPTIMIZATION TECHNIQUE of unconstrained minimization. The Golden section, Random, Pattern, and Gethods, and equality and inequality constraints. PROGRAMMING and indirect methods using penalty function, Lagrange multipliers, Geometric	Gradient Se	earch 0	Metho	ods,
The technique Interpolation M UNIT III Direct methods programming, C UNIT IV Engineering ap	DESIGN OPTIMIZATION TECHNIQUE of unconstrained minimization. The Golden section, Random, Pattern, and Gethods, and equality and inequality constraints. PROGRAMMING and indirect methods using penalty function, Lagrange multipliers, Geometric Genetic algorithms	Gradient Se 9 c programn 9	earch Oning, s	Methodological O	ods, 9 astic
The technique Interpolation M UNIT III Direct methods programming, C UNIT IV Engineering ap	DESIGN OPTIMIZATION TECHNIQUE of unconstrained minimization. The Golden section, Random, Pattern, and Gethods, and equality and inequality constraints. PROGRAMMING and indirect methods using penalty function, Lagrange multipliers, Geometric Genetic algorithms ENGINEERING APPLICATION plications, structural-design application axial and transverse loaded members for	Gradient Se 9 c programn 9	earch Oning, s	Methodological O	ods, 9 astic
The technique Interpolation M UNIT III Direct methods programming, O UNIT IV Engineering apweight. Design UNIT V	DESIGN OPTIMIZATION TECHNIQUE of unconstrained minimization. The Golden section, Random, Pattern, and Gethods, and equality and inequality constraints. PROGRAMMING and indirect methods using penalty function, Lagrange multipliers, Geometric algorithms ENGINEERING APPLICATION plications, structural-design application axial and transverse loaded members for of shafts and torsion members, Design optimization of springs.	Gradient Se 9 c programn 9 minimum	earch o ning, s o cost, n	Methodological Method	ods, 9 astic

TEXT B	OOKS:
1.	S. S. Rao, Engineering Optimization: Theory and Practice, 4th edition, John Wiley & Sons, 2009. ISBN: 0470183527.
2.	Kalyanmoy Deb, "Optimization for Engineering Design", Prentice Hall of India, New Delhi, 2005
REFE	RENCES:
1.	R.C. Johnson, "Optimum Design of Mechanical Elements", Willey, New York, 1980
2.	Kalyanmoy Deb, "Evolutionary multi-objective optimization, Willey, New York.
3.	S. S. Stricker, "Optimising performance of energy systems" Battelle Press, New York, 1985.
4.	J. S. Arora, "Introduction to Optimum Design", McGraw Hill, New York, 1989.
5.	L.C.W. Dixon, "Non-Linear Optimisation - Theory and Algorithms", Birkhauser, Boston, 1980.
6.	R.J. Duffin, E.L. Peterson and C.Zener "Geometric Programming-Theory and Applications", Willey, New York, 1967.
7.	G.B.Dantzig "Linear Programming and Extensions Princeton University Press", Princeton, N. J., 1963
8.	R. Bellman "Dynamic Programming-Princeton" University Press, Princeton, N.J. 1957.

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:						
CO1	Demonstrate an understanding of how design optimization fits into the overall engineering design process.	Create					
CO2	Formulate practical engineering design problems as well-posed optimization problems.	Create					
CO3	Determine the advantages and disadvantages of applying different optimization techniques for a specific problem.	Analyze					
CO4	Model and analyze multi-objective and multi-disciplinary optimization problems.	Analyze					

COURSE	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	3	3	1							2	2	2	
CO2	2	2	3	3	1							2	2	2	
CO3	2	2	2	3	1							2	2	2	
CO4	2	2	2	3	1							2	2	2	
Avg	2	2	2.5	3	1							2	2	2	

22MEH 2	206	ADVANCED FINITE ELEMENT METHO	DS				
			CATEGORY	PE	Credit		3
			TT /XX/ 1	L	Т	P	ТН
			Hours/Week	3	0	0	3
COURS	E OBJ	ECTIVES:			•		
1. To	o devel	op a thorough understanding of the advanced finite element analys	is techniques.				
2. A	n abilit	y to effectively use the tools of the analysis for solving practical pr	oblems arising in e	enginee	ring d	esigr	1.
3. To	o under	stand and solve the Finite Element 1-D structural and 2-D structura	al problems.				
4. To	o devel	op and understand the dynamic problems in structures					
5. To	o gain t	he knowledge of FEM for heat transfer analysis and flow analysis					
UNIT I		INTRODUCTION		9	0	0	9
Classifica	ation o	f problems – Dimensionality, time dependence, Boundary va	lue problems, Ini	tial va	lue p	roble	ms,

Classification of problems – Dimensionality, time dependence, Boundary value problems, Initial value problems, Linear/Non-linearetc., Historical Perspective of FEM and applicability to mechanical engineering design problems. Differential equation as the starting point for FEM, steps in finite element method, discretization, types of elements used, Shape functions, Linear Elements, Local and Global coordinates, Coordinate transformation and Gauss-Legendre scheme of numerical integration, Nodal degrees of freedom. Compatibility conditions, Assembly and boundary considerations.

UNIT II ONE DIMENSIONAL PROBLEMS

Structural problems with one dimensional geometry. Formulation of stiffness matrix, consistent and lumped load vectors. Boundary conditions and their incorporation: Elimination method, Penalty Method. Introduction to higher order elements and their advantages and disadvantages. Formulation for Truss elements, Case studies with emphasis on boundary conditions and introduction to contact problems. Beams and Frames: Review of bending of beams, higher order continuity (C0 and C1 Continuity), interpolation for beam elements and formulation of FE characteristics, Plane and space frames and examples problems involving hand calculations. Algorithmic approach for developing computer codes involving 1-D elements.

UNIT III TWO DIMENSIONAL PROBLEMS

Interpolation in two dimensions, natural coordinates, Isoparametric representation, Concept of Jacobian. Finite element formulation for plane stress plane strain and axi-symmetric problems; Triangular and Quadrilateral elements, higher order elements, sub parametric, Isoparametric and super parametric elements. General considerations in finite element analysis of two-dimension problems. Introduction plate bending elements and shell elements.

UNIT IV DYNAMIC ANALYSIS

FE formulation in dynamic problems in structures using Lagragian Method, Consistent and lumped mass models, Formulation of dynamic equations of motion and introduction to the solution procedures. Modelling of structural damping and formulation of damping matrices, Model analysis, Mode superposition methods and reduction techniques.

UNIT V FEM IN HEAT TRANSFER AND FLUID MECHANICS

Finite element solution for one dimensional heat conduction with convective boundaries. Formulation of element characteristics and simple numerical problems. Formulation for 2-D and 3-D heat conduction problems with convective boundaries. Introduction to thermo-elastic contact problems. Finite element applications in potential flows; Formulation based on potential function and stream function. Design case studies.

Total (45L) = 45 Periods

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REFER	REFERENCES:											
1.	K. J. Bathe, Finite Element Procedures, Prentice-Hall of India Private Limited, New Delhi, 1996											
2.	J. C. Simo and T. J. R. Hughes, Computational Inelasticity, Springer-Verlag New York, Inc., New York, 1998											
3.	Cook and Robert Davis etal, "Concepts and Applications of Finite Element Analysis", 4th Edition, John Wiley and Sons, 2001.											
4.	Segerlind L.J, "Applied Finite Element Analysis", 2nd Edition, John Wiley, 1984.											
5.	O. C. Zienkiewicz and R. L. Taylor, Finite Element Method: Volume 2 Solid Mechanics, Fifth Edition,											

Butterworth-Heinemann, Oxford.	
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	COURSE OUTCOMES: Upon completion of this course, the students will be able to:						
CO1	Understand the concept of the finite element method for solving design problems.	Understand					
CO2	Formulate and solve manually problems in 1-D structural systems involving bars, trusses, beams and frames.	Apply					
CO3	Develop 2-D FE formulations involving triangular, quadrilateral elements, and higher-order elements	Create					
CO4	Apply the knowledge of FEM for stress analysis, model analysis, heat transfer analysis and flow analysis	Evaluate					
CO5	Apply the knowledge of FEM for heat transfer analysis and flow analysis	Apply					

COURSE	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1	3	1				1	1				1	2	
CO2	3	1	3	3	3			1	1						3
CO3	3	1	3	3	2			1	1						
CO4	3	2	3	3	2		2	2	1				1	2	
CO5	3	1	1	1	1				1				1	1	
Avg	3.0	1.2	2.6	2.2	1.6		0.4	1.25	1.0				0.6	1.7	3
	1	1	3/2/1	– indi	cates	streng	th of	correla	tion (3	– High	, 2- Med	lium, 1- I	Low)	1	

22MEH207	207 ADVANCED COMPUTATIONAL FLUID DYNAMICS										
PREREQUISIT	ES	CATEGORY	PE	Credit		3					
Knowledge of un	dergraduate heat transfer and fluid mechanics, basic	Harrya/Wash	L	Т	P	TH					
computational flu	iid dynamics	Hours/Week	3	3 0 0 3							

COURSE OBJECTIVES:

1.

The primary objective of the course is to teach fundamentals of computational method for solving non-linear partial differential equations (PDE) primarily in complex geometry. The emphasis of the course is to teach CFD techniques for solving incompressible and compressible N-S equation in primitive variables, grid generation in complex geometry, transformation of N-S equation in curvilinear coordinate system and introduction to turbulence modelling.

UNIT I INTRODUCTION

Brief introduction of boundary layer flow, incompressible and compressible flows, finite difference and finite volume method, example of parabolic and hyperbolic systems and time discretization technique, explicit and implicit methods, upwind and central difference schemes, stability, dissipation and dispersion errors

UNIT II SOLUTION OF SIMULTANEOUS EQUATIONS

Point iterative/block iterative methods, Gauss-Seidel iteration (concept of central coefficient and residue, SOR), CGS, Bi-CGSTAB and GMRES (m) matrix solvers, different acceleration techniques.

UNIT III INCOMPRESSIBLE FLOW

Higher order upwind schemes: second order convective schemes, QUICK. Solution of NS equations: Solution of incompressible N-S equation (Explicit time stepping, Semi-explicit time stepping). SMAC method for staggered grid: Predictor - Corrector step, discretization of N-S and continuity equations, Pressure correction Poisson's equation, boundary conditions (no-slip, moving wall, slip boundary and inflow conditions), outflow (zero gradient/Orlanski) boundary conditions for unsteady flows, algorithm for the SMAC method, stability considerations for SMAC method.

UNIT IV FDE IN COMPLEX GEOMETRIES

Transformation of governing equation in ξ η – plane, transformation of Laplace equation, introduction to geometrical parameters and the accuracy of the solution, basic facts about transformation, grid transformation on complex geometries. N-S equations in transformed plane, matrices and Jacobians

UNIT V COMPRESSIBLE FLOW

N-S and energy equations, properties of Euler equation, linearization. Solution of Euler equation: Explicit and implicit treatment such as Lax-Wendroff, MacCormark, Beam and Warming schemes, Upwind schemes for Euler equation: Steger and Warming, Van Leer's flux splitting, Roe's approximate Riemann solver, TVD schemes. Solution of N-S equations: MacCormack, Jameson algorithm in finite volume formulation and transformed coordinate system.

Total (45L) = 45 Periods

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TEXT	BOOKS:
1.	Computational Fluid Flow and Heat Transfer, Second Edition by K. Muralidhar, T. Sundararajan (Narosa), 2011.
2.	Computational Fluid Dynamics by Chung T. J., Cambridge University Press, 2003.
3.	Computational Fluid Dynamics by Tapan K. Sengupta, University Press, 2005.
4.	Numerical Computation of Internal and External Flows by Hirch C., Elesvier 2007.
REFEI	RENCES:
1.	K. J. Bathe, Finite Element Procedures, Prentice-Hall of India Private Limited, New Delhi, 1996
2.	J. C. Simo and T. J. R. Hughes, Computational Inelasticity, Springer-Verlag New York, Inc., New York, 1998
3.	Cook and Robert Davis et.al, "Concepts and Applications of Finite Element Analysis", 4th Edition, John Wiley and Sons, 2001.
4.	Segerlind L.J, "Applied Finite Element Analysis", 2nd Edition, John Wiley, 1984.
5.	O. C. Zienkiewicz and R. L. Taylor, Finite Element Method: Volume 2 Solid Mechanics, Fifth Edition, Butterworth-Heinemann, Oxford,

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:						
CO1	Understand and be able to numerically solve the incompressible and compressible flows.	Understand					
CO2	Solve computational problems related to iterative methods.	Evaluate					
CO3	Solve the problems related to incompressible fluid flow.	Evaluate					
CO4	Interpret the knowledge, capability of analyzing and solving FDE in complex geometries problem.	Apply					
CO5	Solve the problems related to compressible fluid flow.	Evaluate					

COURSE A	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	1	1	2								2	2	
CO2	2	2	1	3	2								2	2	
CO3	2	2	1	3	2								2	2	
CO4	2	2	1	1	2								2	2	
CO5	2	2	1	3	2								2	2	
Avg	2	2	1	2.2	2								2	2	
			3/2/1 -	– indic	ates s	trengt	h of c	orrelat	ion (3	– High,	2- Medi	ium, 1- I	Low)		

22MF	EH208	SMART MATERIALS AND STRUCTURES					
		CATE	GORY	PE	Cr	edit	3
			/XX/ 1	L	Т	P	TF
		Hours	s/Week	3	0	0	3
COU	JRSE OBJ	ECTIVES:			•		
1.		e of smart materials and structures is essential designing mechanical sysns, the course aims at training students in smart materials and structures approximately ap					ing
UNI	TI	SMART STRUCTURES		9	0	0	9
Smart strain induce Actua	Structures. l relation. Hy ed strain Rat	tructures, Potential Feasibility of Smart Structures, Key Elements of Sm Piezoelectric materials, Properties, piezoelectric Constitutive Relations, De steresis, Creep and Strain Rate effects, Inchworm Linear Motor. Beam Me e effects, Inchworm Linear Motor Beam Modeling with induced strain A extension, Pure Bending harmonic excitation, Bernoulli-Euler beam Mo	poling and lodeling: B ctuation-sin	Coers eam I ngle A	ive Fi Model Actuat	eld, fi ling v	ield vith lual
UNI	TII	SHAPE MEMORY ALLOY		9	0	0	9
Wires and pr	, Vibration Coperties, Flu	nomenology, Shape Memory Effect, Phase Transformation, Tanaka's Constrol through SMA, Multiplexing. Applications of SMA and Problems. End Composition and behavior, The Bingham Plastic and Related Models, In Clutches, Dampers and Others.	ER and MR	Fluids	: Med	chanis	sms

UNIT III VIBRATION ABSORBERS

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Series and Parallel Damped Vibrations (Overview), Active Vibration Absorbers, Fiber Optics, Physical Phenomena, Characteristics, Sensors, Fiber Optics in Crack Detection, applications. Control of Structures: Modeling, Control Strategies and Limitations, Active Structures in Practice.

UNIT IV MEMS

Mechanical Properties of MEMS Materials, Scaling of Mechanical Systems, Fundamentals of Theory, The Intrinsic Characteristics of MEMS, Miniaturization, Microelectronics Integration.

UNIT V SENSORS AND ACTUATORS

Sensors and Actuators, Conductivity of Semiconductors, Crystal Planes and Orientation, (Stress and Strain Relations, Flexural Beam Bending Analysis Under Simple Loading Conditions), Polymers in MEMS, Optical MEMS Applications.

TEXT I	BOOKS:
1.	Smart Materials and Structures - M. V. Gandhi and B. So Thompson, Chapman and Hall, London; New York, 1992 (ISBN: 0412370107).
2.	Smart Structures and Materials - B. Culshaw, Artech House, Boston, 1996 (ISBN: 0890066817). 3. Smart Structures: Analysis and Design - A. V. Srinivasan, Cambridge University Press, Cambridge; New York, 2001 (ISBN: 0521650267).
REFER	RENCES:
1.	Electro ceramics: Materials, Properties and Applications - A. J. Moulson and J. M. Herbert. John Wiley & Sons, ISBN: 0471497429
2.	Piezoelectric Sensories: Force, Strain, Pressure, Acceleration and Acoustic Emission Sensors. Materials and Amplifiers, Springer, Berlin; New York, 2002 (ISBN: 3540422595).
3.	Piezoelectric Actuators and Transonic Motors - K. Uchino, Kluwer Academic Publishers, Boston, 1997 (ISBN: 0792398114).
4.	Handbook of Giant Magneto strictive Materials - G. Engdahl, Academic Press, San Diego, Calif.; London, 2000 (ISBN: 012238640X).
5.	Shape Memory Materials - K. Otsuka and C. M. Wayman, Cambridge University Press, Cambridge; New York, 199~ (ISBN: 052144487X).

	RSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Understand the behavior and applicability of various smart materials.	Understand
CO2	Design simple models for smart structures and materials.	Create
СОЗ	Perform simulations of smart structures and materials application.	Analyse
CO4	Conduct experiments to verify the predictions.	Analyze

COURSE	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	1	1	2								2	2	
CO2	2	2	1	1	2								2	2	
CO3	2	2	1	1	2								2	2	
CO4	2	2	1	1	2								2	2	
Avg	2	2	1	1	2								2	2	
	3/2/1 – indicates strength of correlation (3 – High, 2- Medium, 1- Low)														

	EH209	DESIGN OF PRESSURE VESSELS					
PRE	EREQUIS	ITES	CATEGORY	PE	Cr	edit	3
			Hours/Week	L	Т	P	TH
			nours/ week	3	0	0	3
COI	URSE OB	JECTIVES:					
1.	To study	about the various types of stresses act in the pressure vessels.					
2.	To desig	n components of pressure vessel using codes and standards.					
3.							
4.	To study	about design considerations of pressure vessels.					
5	To study	about the design of pipes related to design of pressure vessels.					
UNI	IT I	9	0	0	9		
comp		astic instability, Brittle rupture and creep. Theory of reinforced openi sis, wind and seismic load consideration in the design of pressure ve DESIGN OF VESSELS USING CODES		9	0	0	9
Supp		ASME codes for pressure vessel design, Pressure vessel and related co ort vertical vessels, Stress concentration at a variable thickness transes.					
UNI	IT III	SUPPORTS FOR VERTICAL AND HORIZONTAL VI	ESSELS	9	0	0	9
	£1	SUPPORTS FOR VERTICAL AND HORIZONTAL VI			U	U	1 -
Desig	gn or base p	plate and support lugs. Types of anchor bolt, its material and allowab					rs.
	IT IV	I					ors.
UNI Buck cyline stiffe tempe	IT IV cling pheno ders or tuberers, and erature, irra	olate and support lugs. Types of anchor bolt, its material and allowab	le stresses. Designal pressure, Col Cylinders, Desi Fatigue, shock, ight weight pres	n of sa 9 lapse of control of the high of the sure vector of the same of the	ddle s 0 f thic ircumpressu	o www. o k-wal feren ure, h	9 lled atial nigh
UNI Buck cylin stiffe temp resist	IT IV cling pheno ders or tuberers, and erature, irra	OTHER DESIGN CONSIDERATIONS menon, Elastic Buckling of circular ring and cylinders under externes under external pressure, Effect of supports on Elastic Buckling of buckling under combined External pressure and Axial loading. adiation, corrosion, and other hostile environments; High strength, I	le stresses. Designal pressure, Col Cylinders, Desi Fatigue, shock, ight weight pres	n of sa 9 lapse of control of the high of the sure vector of the same of the	ddle s 0 f thic ircumpressu	o www. o k-wal feren ure, h	9 lled itial nigh
UNI Buck cyline stiffe temperesist UNI Flow syste	IT IV cling pheno ders or tube eners, and erature, irra tant to exten IT V v diagram, I em as per B	OTHER DESIGN CONSIDERATIONS menon, Elastic Buckling of circular ring and cylinders under externes under external pressure, Effect of supports on Elastic Buckling of buckling under combined External pressure and Axial loading. Indiation, corrosion, and other hostile environments; High strength, and high pressures found in undersea exploration, offshore drilling, and the pressure of the pressure	le stresses. Designal pressure, Col Cylinders, Desi Fatigue, shock, light weight presund mineral minim	an of sa 9 lapse of chigh plants we have been sure verified. 9 tor; Details of the same should be same shou	ddle s 0 f thic ircumpressuessels, 0	ok-wal feren ire, h Vess	9 lled tial night sels
UNI Buck cyline stiffe temperesist UNI Flow syste	IT IV cling pheno ders or tube eners, and erature, irra tant to exten IT V v diagram, I em as per B	OTHER DESIGN CONSIDERATIONS menon, Elastic Buckling of circular ring and cylinders under externes under external pressure, Effect of supports on Elastic Buckling of buckling under combined External pressure and Axial loading. In adiation, corrosion, and other hostile environments; High strength, I mal high pressures found in undersea exploration, offshore drilling, a pripring layout and piping stress analysis; Flexibility factor and stress if 31.1 piping code. Piping components - bends, tees, bellows and valve	le stresses. Designal pressure, Colf Cylinders, Desi Fatigue, shock, light weight presund mineral minimum.	an of sa 9 lapse of chigh plants we have been sure verified. 9 tor; Details of the same should be same shou	ddle s 0 of thic ircumpressuessels, 0 esign oports	ok-walaferen vess	9 Illed titial high ssels

TEXT	BOOKS:									
1.	Dennis Moss "Pressure Vessel Design Manual"									
2.	Henry H Bednar, "Pressure vessel Design Hand book", CBS publishers and distributors.									
REFER	RENCES:									
1.	Harvey J F, "Pressure vessel design", CBS, publication.									
2.	Brownell L. E & Young. E. D, "Process equipment design", Wiley Eastern Ltd., India.									
3.	Stanley M Wales, "Chemical Process Equipment, Selection and Design", Butterworths,									
4.	Series in Chemical Engineering, 1988. 6. J. Phillip Ellenberger "Pressure Vessels: ASME Code Simplified".									

5.	"ASME Pressure Vessel and Boiler Code", Section VIII Div. 1, 2, and 3.
6.	"American standard code for pressure piping", B 31.1.
7.	Smith P, "Fundamentals of Piping Design", Elsevier.

	SE OUTCOMES: ompletion of this course, the students will be able to:	Bloom Taxonomy Mapped								
CO1	Determine stresses in pressure vessels.									
CO2	Design pressure vessels using ASME codes.									
CO3	Design support members of pressure vessels.	Create								
CO4	Apply other design considerations for pressure vessels.									
CO5	Design of pressurized fluid piping.									

COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	2	2									3	3	
CO2	2	3	3	3									3	3	
CO3	2	3	3	3									3	3	
CO4	3	1	1	1									3	3	
CO5	2	3	3	3									3	3	
Avg	2	2.4	2.4	2.4									3	3	

)						I	ME	ECE	HAN	NI(C	A]	L	, VI	BI	R/	ΑT	ΓIC	ON	NS												
PREREQUISITES CATEGORY													7	PE	C	redi	t	3														
Have /Wash												L	Т	I	>	TI																
											Hours/Week									3	0	()	3								
0	BJ	ECTIVES:	;																			ı							1	ı		
o'	uno	derstand the l	Fun	ndaı	mer	ntal	ls of	f Vil	bratio	ion	n a	anc	ıd i	its p	orac	cti	ical	l ap	ppl	lica	tio	ıs.										
2. To understand the characteristics of free and forced vibration.																																
3. To understand the Single and Multi DOF of vibration system.																																
4. To understand the working principle and operations of various vibration measuring instruments																																
5 To understand about the vibration analysis methods.																																
		FUNDAM	EN	NT.	ΊΑL	LS (OF	VI	BRA	ΑT	ΤI	Ю	ON	\S														9	0	0		9
no	n-p	of vibration — periodic, harm vibration and	nor	nic,	, no																											
		FREE VII	BR	RAT	ΓIC	ON	OF	SI	NG	LI	E	D	ЭE	EGF	RE	E	O	F	FI	RE	EL	ON	I S	SYS	STE	MS	5	9	0	0		9
ial	eq	single DOF viquations by nd, over dampe	iew	vton	ı, ei	nerg	gy,]	lagr	rangi	gian	n a	an	nd	Ray	yle	ig	h's	s n	net	thoo	d. V	/isco	us	da	mp	ed sy	yste	m –	unde	r da	mp	ed,
		FORCED SYSTEMS		VII	BR	RAT	(OI	N	OF	F	S	SI	IN	IGI	LE	,	D	E(GF	RE	E	OF	1	FF	EF	DO	М	9	0	0		9
	D	SYSTEMS OF system –	Ar ela	naly	ysis c da	s of amp	line	ear a	and t	tor	orsi on	sioi is	ona sol	al sy	yste on	em	ns for	sub	bje e tr	ecte rans	d to	ha ssibi	r	rmo lity	rmonic lity –	rmonic for lity – mot	rmonic force e	rmonic force excit lity – motion tran	rmonic force excitation lity – motion transmis	rmonic force excitation and lity – motion transmissibili	rmonic force excitation and harmonic	rmonic force excitation and harmonity – motion transmissibility, typi

motion excitation (excluding elastic damper) – vibration isolation – force transmissibility – motion transmissibility, typical isolators & mounts – Rotor dynamics, critical speed of single rotor, undamped and damped.

UNIT IV VIBRATION OF MULTI DEGREE OF FREEDOM SYSTEMS

0 0 9

Free undamped Multi Degree of Freedom vibration system – Influence Coefficients and stiffness coefficients- Flexibility Matrix and Stiffness Matrix - Eigen values and Eigen vectors for linear system and torsional two degree of freedom; Holzer method for linear and torsional unbalanced system; Two rotors, three rotors and geared system; Dunkerley's and Rayleigh's method for transverse vibratory system.

UNIT V VIBRATION MEASURING INSTRUMENTS AND VIBRATION 9 0 9

Vibration Analysis Overview - Experimental Methods in Vibration Analysis. -Vibration Measuring Instruments - Selection of Sensors- Accelerometer Mountings. -Vibration Exciters-Mechanical, Hydraulic, Electromagnetic and Electrodynamics - Frequency Measuring Instruments-. System Identification from Frequency Response -Testing for resonance and mode shapes.

TEXT BO	OOKS:
1.	Mechanical Vibration by V.P.Singh
2.	Singiresu S. Rao, "Mechanical Vibrations", Pearson Education Incorporated, 2017.

REFERE	ENCES:
1.	Benson H. Tongue, "Principles of Vibrations", Oxford University, 2007.
2.	Grover. G.K., edited by Nigam. S. P., "Mechanical Vibrations", Nem Chand and Bros., 2014.
3.	David A. Bies and Colin H. Hansen, "Engineering Noise Control – Theory and Practice", Spon Press, 2009.
4.	Julian Happian-Smith – "An Introduction to Modern Vehicle Design", Butterworth-Heinemann, 2001.

5.	William T. Thomson, "Theory of Vibration with Applications", Taylor and Francis, 2003.
6.	Balakumar Balachandran and Edward B. Magrab, "Fundamentals of Vibrations", 1st Editon, Cengage Learning, 2009
7.	Grover. G.T., "Mechanical Vibrations", Nem Chand and Bros., 2009
8.	NPTEL :: Mechanical Engineering - NOC:Introduction to Mechanical Vibration

	SE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Explain basics of sound, noise and vibration; as well as their control strategies.	Evaluate
CO2	Derive equations of motion for undamped one-dimensional vibrations, and solve problems of damped free vibrations.	Create
CO3	Analyse and solve problems of forced vibrations involving frequency response curves, phase angle plots, vibration isolation and transmissibility.	Analyze
CO4	Analyse and solve problems involving vibrations of systems having more than one degree of freedom.	Analyze
CO5	Recall and explain concepts involving vibrations measuring instruments.	Create

COURSE A	RTI	CULA	TIO	N MA	TRIX										
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	2	1									2	2	
CO2	3	3	2	2									2	2	
CO3	3	3	2	2									2	2	
CO4	3	3	2	2									2	2	
CO5	1	1	2	2									2	2	
Avg	2.2	2.4	2	1.8									2	2	
	•	3/2	2/1 – i	ndica	tes sti	rengtl	of co	orrelat	ion (3	– High	, 2- Me	dium, 1	- Low)	•	

VERTICALS -3 PRODUCT AND PROCESS DEVELOPMENT

22M	EH301	PRECISION ENGINEERING					
PREI	REQUIS	ITES CA	TEGORY	PE	Cr	edit	3
			/ T T	L	Т	P	TH
		H	ours/Week	3	0	0	3
COU	RSE OB	JECTIVES:		l		ı	
1.	Explain t	the need and progress of precision engineering.					
2.	To know	about the principle and working of different methods of precision made	hining.				
3.	To under	estand about design requirements of precision machine tools.					
4.	To know	about the mechanical and thermal errors in measurement.					
5.	To under	estand about laser devices, machine vision, SEM and 3D surface topogrammers and surface topogrammers.	aphy.				
Ul	NIT I	INTRODUCTION		9	0	0	9
		Precision Engineering, Need for precision manufacturing, Four classes on, High-precision, Ultra-precision Processes and Nanotechnology	s of achievable	machi	ning	accur	acy –
UN	NIT II	PRECISION MACHINING AND UNCONVENTIONAL MICROMACHING TECHNIQUES		9	0	0	9
grindi Photo	ng, Ultra- chemical r	cro and Nano machining, Conventional micro machining techniques - precision diamond turning, SPDT Single point diamond turning. Machining, Electro chemical micromachining, Laser beam micromachinam micromachining, etc	licro electrical	discha	arge i	nachi	ning.
UN	IT III	MACHINE DESIGN FOR PRECISION MANUFACTURI	NG	9	0	0	9
Linear	r Motor dı	recision machine design -Ultra-Precision machine elements: Guide wa rive – Spindle drive. Bearings: Principle – Construction and application rings – Aerostatic Bearings – Magnetic Bearings.					
UN	IT IV	MECHANICAL AND THERMAL ERRORS		9	0	0	9
Stuctu		- Principle of measurement – Errors die to machine elements – Beari liance – Vibration – Thermal Effects – Environmental control of prec					
UN	NIT V	MEASUREMENT AND CHARACTERISATION		9	0	0	9
metro Need,	logy – Fri Measure	 Laser tracking systems – Laser scanners – White light Interference 3 nge projection method. Measurement of typical nanofeatures, Surface ment – Chromatic confocal Microscopy, Interferometry, Non-optica copes, Scanning probe microscopes, Parameters for characterizing 3D 	metrology - 31 al Scanning M	O surfa	ice to	pogra	phy -

TEXT 1	BOOKS:
1.	Jain, V.K., Introduction to micromachining, Narosa publishers, 2018
2.	Venktesh V.C., Sudin Izman, Precision Engineering, Tata Mc.Graw Hill Publishing Company, New Delhi 2007.
REFER	RENCES:
1.	David Dornfeld, Dae-Eun Lee, Precision Manufacturing, Springer, 2008
2.	Kevin Harding, "Handbook of Optical Dimensional Metrology, Series: Series in Optics and optoelectronics", Taylor & Francis, 2013
3.	Murty, R.L., Precision Engineering in Manufacturing, New Age publishers, 2005.
4.	Jain V.K, "Micro-manufacturing Prrocesses", 1st Edition, CRC press, Taylor and Francis group, 2012.

	SE OUTCOMES: ompletion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Impart knowledge progress of precision engineering.	Understand
CO2	Identify principle and working of different methods of precision machining.	Apply
CO3	Choose the basic design requirements for the construction of precision machine tools.	Apply
CO4	Identify various errors affecting the accuracy of precision manufacturing.	Apply
CO5	Define the uses of laser devices and machine vision, apply the knowledge on surface metrology.	Apply

COURSE	ARTI	CUL	ATIO	N M	ATRI	X									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2		1			1					2	1	2	2
CO2	1	3	1	1			1					2		1	1
CO3	3	3	1	1	2		1					3		1	3
CO4	3	2	1	2	2		1					3	2	1	3
CO5	2	3		3	1		1					3		1	2
Avg	2.2	2.6	1	1.6	1.7		1.0					2.6	1.5	1.2	2.2
	•	3/2	2/1 – i	ndica	tes sti	rengtl	of co	orrelat	ion (3	– High	, 2- Me	dium, 1	- Low)		

22MEH302	ADVANCED MATERIALS TECHNOLOGY					
PREREQUI	SITES CATEGO	RY	PE	Cre	dit	3
		,	L	Т	P	TH
	Hours/W	еек	3	0	0	3
COURSE OF	BJECTIVES:					
1. To under	rstand the causes of crack and failure in metals.					
2. To know	different types of surface coatings in metals.					
3. To know	v about different composite materials.					
4. To under	rstand the properties of modern alloys					
5. To know	about the advanced aerospace alloys					
UNIT I	REVIEW OF MECHANICAL BEHAVIOUR OF MATERIALS		9	0	0	9
fractures- dar	nation in poly phase alloys – Strengthening mechanism –Griffith's theory of failur nping property of materials- fracture toughness –initiation and propagation Hydrogen embrittlement of metals					
fractures- dar mechanism –l UNIT II Mechanical st implantation-	nping property of materials- fracture toughness –initiation and propagation Hydrogen embrittlement of metals SURFACE MODIFICATION OF MATERIALS urface treatment and coating –Case hardening and hard facing –thermal sprayin diffusion coating –electroplating and electroforming –conversion coating –Cera	of fatig	gue cra 9 oour de	0 epositi	- Cro 0 ion -	eep 9 Ion
fractures- dar mechanism –l UNIT II Mechanical st implantation-	nping property of materials- fracture toughness –initiation and propagation Hydrogen embrittlement of metals SURFACE MODIFICATION OF MATERIALS urface treatment and coating –Case hardening and hard facing –thermal sprayin	of fatig	gue cra 9 oour de	0 epositi	- Cro 0 ion -	9 Ion
fractures- dar mechanism -l UNIT II Mechanical st implantation- Diamond coat UNIT III Iron Carbon Spherodizing; media; Surfac steel and their of aluminum a	nping property of materials- fracture toughness –initiation and propagation Hydrogen embrittlement of metals SURFACE MODIFICATION OF MATERIALS urface treatment and coating –Case hardening and hard facing –thermal sprayin diffusion coating –electroplating and electroforming –conversion coating –Ceraing – Advanced surface modification of steels	of fatig	9 poour dend organge, Streenchantical Tree on of h	o eposition co ess rets; Queatmeneat tr	O lion — oating O elievinenchient; Teeatme	9 Ion g – 9 ng; ing ool ent
fractures- dar mechanism -l UNIT II Mechanical st implantation- Diamond coat UNIT III Iron Carbon Spherodizing; media; Surfac steel and their of aluminum a	Inping property of materials- fracture toughness –initiation and propagation Hydrogen embrittlement of metals SURFACE MODIFICATION OF MATERIALS Inface treatment and coating –Case hardening and hard facing –thermal sprayin diffusion coating –electroplating and electroforming –conversion coating –Ceraing – Advanced surface modification of steels ADVANCED HEAT TREATMENT OF MATERIALS phase diagram; TTT diagram; different microstructures; transformations; A Normalizing; Hardening; Tempering; Austemepring; Martempering; Quenching e hardening; Harden ability; Sub-zero treatment; Thermo-mechanical treatment; theat treatment; cast Iron and their heat treatment. Aluminum and its alloys; Classilloys; Heat treatment of Magnesium and its alloys; Heat treatment of Titanium and Its alloys; Heat trea	of fatig	9 poour dend organge, Streenchantical Tree on of h	o eposition co ess rets; Queatmeneat tr	O lion — oating O elievinenchient; Teeatme	9 Jong; ing ool ent
fractures- dar mechanism -l UNIT II Mechanical strimplantation- Diamond coat UNIT III Iron Carbon Spherodizing; media; Surfact steel and their of aluminum a of Copper and UNIT IV Super alloys refractories, S	Inping property of materials- fracture toughness –initiation and propagation Hydrogen embrittlement of metals SURFACE MODIFICATION OF MATERIALS Inface treatment and coating –Case hardening and hard facing –thermal sprayin diffusion coating –electroplating and electroforming –conversion coating –Ceraing – Advanced surface modification of steels ADVANCED HEAT TREATMENT OF MATERIALS phase diagram; TTT diagram; different microstructures; transformations; A Normalizing; Hardening; Tempering; Austemepring; Martempering; Quenching e hardening; Harden ability; Sub-zero treatment; Thermo-mechanical treatment; theat treatment; cast Iron and their heat treatment. Aluminum and its alloys; Classilloys; Heat treatment of Magnesium and its alloys; Heat treatment of Titanium and its alloys; Heat treatment of Nickel and its alloys, Energy Economy in heat treatment.	of fatig	9 g, Streenchantical Tree on of helloys; H	eposition of the control of the cont	O elievinenchi reatmoreatmo o alum	9 Ion g - 9 ng; ing ool ent ent 9 ina

Ti and Ni based alloys for gas turbine applications –Maraging (Low carbon and high Nickel) and cryogenic steels – Advanced materials and their treatment for automobile applications – Materials for aerospace (Al6061, Al7075), Marine (AH36, DH36, and EH36) and nuclear systems

TEXT B	OOKS:
1.	Dowling, "Mechanical Behaviour of Materials, Engineering Method of Determination, Fracture", Mcgraw Hill,1999
2.	Dieter, 'Engineering Design, A materials And Processing Approach'', Third Edition, Mcgraw Hill, 1999
REFERI	ENCES:
1.	P.Rama Rao,"Advances In Materials And Their Applications", Willey Eastern Ltd., 1993.
2.	Serope Kalpakjian, "Manufacturing Engineering And Technology' Third Edition, Addison Wisley Publishing Co., 1995.
3.	Kennith G .Budinski, "Surface Engineering For Wear Resistance", Prentice Hall, 1998.
4.	Dieter, ''Mechanical Metallurgy' 'Mcgraw Hill, 1989
5.	D.R.Gabe, 'Principles Of Metal Surface Treatment And Protection', Pergamon Press1978.

	SE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Impart the knowledge of crack and failure of metals.	Understand
CO2	Identify the different types of surface coatings to improve the property of material.	Understand
CO3	Impart the knowledge of advanced heat treatment method for various materials.	Understand
CO4	Define the properties of modern materials and alloys	Remember
CO5	Provide information of advanced aerospace alloys.	Remember

COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2		1			1					2	1	2	2
CO2	1	3	1	1			1					2		1	1
CO3	3	3	1	1	2		1					3		1	3
CO4	3	2	1	2	2		1					3	2	1	3
CO5	2	3		3	1		1					3		1	2
Avg	2.2	2.6	1	1.6	1.7		1.0					2.6	1.5	1.2	2.2

22N	IEH303	ADDITIVE MANUFACTURING					
PRE	REQUISI	TES	CATEGORY	PE	Cr	edit	3
1. M	anufacturin	g technology, Drafting software		L	Т	P	TH
2. Eı	ngineering l	Materials	Hours/Week	3	0	0	3
COU	RSE OBJ	ECTIVES:		1	1	1	
1.	To introd	duce the development of Additive Manufacturing (AM), various b	usiness opportunitie	es and a	pplic	ation	s
2.		liarize various software tools, processes and techniques to creatent / prototyping requirements, using AM.	te physical objects	that sa	tisfy	prod	uct
3.	To be acc	quainted with vat polymerization and material extrusion processes	S.				
4.	To be far	miliar with powder bed fusion and direct energy deposition.					
5.	To gain k	knowledge on applications of binder jetting, material jetting and la	minated object man	ufactur	ing pı	roces	ses
T T							
Over Rapic Printi Prope	d Manufact ing- Bio Pr erty.	INTRODUCTION ed - Development of Additive Manufacturing (AM) Technology uring - Additive Manufacturing. AM Process Chain- Classificat inting- Food Printing- Printing Electronics. Business Opportunit	tion – Benefits. Apies and Future Dire	plications	ons: E - Inte	Buildi	ng ıal
Over Rapid	view – Nee d Manufact	ed - Development of Additive Manufacturing (AM) Technology uring – Additive Manufacturing. AM Process Chain- Classificat	tion – Benefits. Ap	g - Rap plication	id To	oling Buildi	g – ng
Over Rapio Printi Prope Ul	view – Need Manufact ing- Bio Preerty.	ed - Development of Additive Manufacturing (AM) Technology uring – Additive Manufacturing. AM Process Chain- Classificating Food Printing- Printing Electronics. Business Opportunit	tion – Benefits. Apies and Future Dire	g - Rap plications	id Toons: B - Inte	ooling Buildi Ellectu	ng nal
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Over-Rapid Printi Prope Un Conc DFAl Gene Studi Un Photo Digita	view – Need Manufacting- Bio Pretty. NIT II epts and Ole M for Part (cration - Modes. NIT III p polymeriz al Light Present description of the polymeriz al Light Present description of the present descriptio	ed - Development of Additive Manufacturing (AM) Technology uring – Additive Manufacturing. AM Process Chain- Classificatining- Food Printing- Printing Electronics. Business Opportunit DESIGN FOR ADDITIVE MANUFACTURING (DFA bjectives- AM Unique Capabilities: Part Consolidation- Topology Quality Improvement. Data Processing - CAD Model Preparation odel Slicing - Tool Path Generation- Customized Design and Fabruary	tion – Benefits. Apies and Future Director AM) y Optimization Light-Part Orientation arrication for Medical USION Advantages Limita	g - Rapplications g - Rapplications g - Rapplications g - Rapplications	id Toons: B - Inte 0 nt Stroort Stroo	ooling Buildi Bu	g – nng anal 9 9 e – nire asse 9
Over-Rapid Printi Prope UN Conc DFAI Gene Studi UN Photo Digita Depo	view – Need Manufacting- Bio Pretty. NIT II epts and Ole M for Part (cration - Modes. NIT III p polymeriz al Light Present description of the polymeriz al Light Present description of the present descriptio	ed - Development of Additive Manufacturing (AM) Technology uring – Additive Manufacturing. AM Process Chain- Classificatining- Food Printing- Printing Electronics. Business Opportunit DESIGN FOR ADDITIVE MANUFACTURING (DFA bjectives- AM Unique Capabilities: Part Consolidation- Topology Quality Improvement. Data Processing - CAD Model Preparation odel Slicing - Tool Path Generation- Customized Design and Fabruation: Stereo lithography Apparatus (SLA) - Materials - Process rocessing (DLP) - Materials - Process - Advantages - Applica	tion – Benefits. Apies and Future Director AM) y Optimization Light-Part Orientation arrication for Medical USION Advantages Limitations. Extrusion Ba	g - Rapplications g - Rapplications g - Rapplications g - Rapplications	id Toons: B - Inte 0 nt Stroort Stroo	ooling Buildi Bu	g – nng anal 9 9 e – nire asse 9
Over-Rapid Printi Prope UN Conc DFAI Gene Studi UN Photo Digita Depo UN Powd Mater	view – Need Manufacting- Bio Pretty. NIT II epts and Olemon - Modes. NIT III o polymerizal Light Presition Mode NIT IV der Bed Fusirials and A	ed - Development of Additive Manufacturing (AM) Technology uring – Additive Manufacturing. AM Process Chain- Classificatining- Food Printing- Printing Electronics. Business Opportunit DESIGN FOR ADDITIVE MANUFACTURING (DFA bjectives- AM Unique Capabilities: Part Consolidation- Topology Quality Improvement. Data Processing - CAD Model Preparation odel Slicing - Tool Path Generation- Customized Design and Fabruation: Stereo lithography Apparatus (SLA) - Materials - Process-rocessing (DLP) - Materials - Process - Advantages - Applicateling (FDM) - Process-Materials - Applications and Limitations.	tion – Benefits. Apies and Future Director AM) y Optimization Light-Part Orientation arrication for Medical USION Advantages Limitations. Extrusion Battons. Extrusion Battons. Extrusion Battons.	g - Rapplications g - Rapplicat	id Toons: B - Inte Ont Stroort Sociation Ont Stroort Sociation Ont Stroort Sociation	Oucture tructures - Cations : Fus	g - ng nal 9 e - nre use 9 nas. ed 9
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Binder Jetting: Three -Dimensional Printing - Materials - Process - Benefits and Limitations. Material Jetting: Multi-jet Modeling- Materials - Process - Benefits. Sheet Lamination Process: Laminated Object Manufacturing (LOM) - Basic Principle- Mechanism: Gluing or Adhesive Bonding - Thermal Bonding - Materials - Application and Limitation.

TEX	T BOOKS:
1.	Andreas Gebhardt and Jan-Steffen Hötter "Additive Manufacturing: 3D Printing for Prototyping and Manufacturing", Hanser publications, United States, 2015, ISBN: 978-1-56990-582-1.
2.	Ian Gibson, David W. Rosen and Brent Stucker "Additive Manufacturing Technologies: Rapid Prototyping to Direct Digital Manufacturing", 2nd edition, Springer., United States, 2015, ISBN13: 978-1493921126.
REF	FERENCES:
1.	Amit Bandyopadhyay and Susmita Bose, "Additive Manufacturing", 1st Edition, CRC Press., United States, 2015, ISBN-13: 978-1482223590.
2.	Andreas Gebhardt, "Understanding Additive Manufacturing: Rapid Prototyping, Rapid Manufacturing", Hanser Gardner Publication, Cincinnati., Ohio, 2011, ISBN: 9783446425521.
3.	Kamrani A.K. and Nasr E.A., "Rapid Prototyping: Theory and practice", Springer., United States, 2006, ISBN:

	978-1-4614-9842-1.
4.	Liou, L.W. and Liou, F.W., "Rapid Prototyping and Engineering applications: A tool box for prototype development", CRC Press., United States, 2011, ISBN: 9780849334092.
5.	Milan Brandt, "Laser Additive Manufacturing: Materials, Design, Technologies, and Applications", Woodhead Publishing., United Kingdom, 2016, ISBN: 9780081004333.

	SE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Recognize the development of AM technology and how AM technology propagated into various businesses and developing opportunities.	Remember
CO2	Acquire knowledge on process of transforming a concept into the final product in AM technology.	Understand
CO3	Elaborate the vat polymerization and material extrusion processes and its applications.	Apply
CO4	Acquire knowledge on process and applications of powder bed fusion and direct energy deposition.	Apply
CO5	Evaluate the advantages, limitations, applications of binder jetting, material jetting and laminated object manufacturing processes.	Evaluate

COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2						1	2		1		2	1	1	1
CO2	2	1	1	1	1		2	1		1		2	1	2	1
CO3	2	1					1			1		2	1	1	1
CO4	2	1					1			1		2	1	1	1
CO5	2	1					1			1		2	1	1	1
Avg	2.0	1	1	1	1		1.2	1.5		1		2.0	1.0	1.2	1.0

22MF	EH304	NON DESTRUCTIVE TESTING AND FAILURE	ANALYSIS				
PRER	EQUISI	TES	CATEGORY	PE	Cr	edit	3
			** ***	L	Т	P	TH
			Hours/Week	3	0	0	3
COUR	SE OBJ	ECTIVES:		•	•	•	
		op the fundamental knowledge about non-destructive and destr manufacturing and production engineering components.	uctive analysis, in	order	to coi	ntrol	the
UN	IT I	INTRODUCTION AND SURFACE NDT		9	0	0	9
applica	ations and	testing—Comparison with destructive testing, importance, scope at limitations. Liquid penetrant Inspection - Principles, propert enetic particle inspection - Principles, advantage and limitations.					
UNI	TII	RADIOGRAPHY AND ACOUSTIC EMISSION		9	0	0	9
		asic principle, electromagnetic radiation sources, radiographic imagafety. Acoustic emission testing- procedures and its importance.	ging, inspection tech	nniques	s, appl	licatio	ons,
UNI	T III	EDDY CURRENT AND ULTRASONIC TESTING		9	0	0	9
		sting – principle, application, limitation; Ultrasonic testing – basicods, flaw characterization techniques, immersion testing, advantage		nd bear	n, trai	nsduc	ers,
UNI	T IV	LEAK TESTING AND THERMOGRAPHY		9	0	0	9
		olography and Thermography – principles, procedures and applicant methods; Defects in casting, forging, rolling and welding.	ntions; Comparison	and se	lection	n of l	Von
UNI	T V	FAILURE ANALYSIS METHODOLOGY		9	0	0	9
		methodology, tools and techniques of failure analysis, failure analysis; types of failure and techniques for failure analy		proced	ural s	steps	for
			Total ((45L)	= 45	Peri	ods
TEXT	ВООК	S:					
1.	Balde	v Raj, "Practical Non-Destructive Testing", Narosa Publishing Ho	ouse, 1997.				
		<i>y, e y</i>	,				-

TEXT I	BOOKS:
1.	Baldev Raj, "Practical Non-Destructive Testing", Narosa Publishing House, 1997.
2.	J. Prasad and C. G. K. Nair, Non-Destructive Test and Evaluation of Materials, Tata McGraw-Hill Education, 2nd edition (2011).
3.	Peter J Shull, "Nondestructive Evaluation- Theory, Techniques and Applications" Marcel Dekker, Inc, USA 2002, ISBN: 0-8247-8872-9.
REFE	RENCES:
1	George E Dieter, "Mechanical Metallurgy", McGraw Hill Book Company
2	B.Hull and V.John. "Non-Destructive Testing", McMillan
3	A.K Das, "Metallurgy of failure analysis", TMH, 1992

	SE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Understand the concept of destructive and Non-destructive testing methods.	Understand
CO2	Explain the working principle and application of die penetrant test and magnetic particle inspection.	Remember
СОЗ	Understand the working principle of eddy current inspection, Ultrasonic testing and applications.	Understand
CO4	Apply radiographic techniques for testing and acoustic emission testing.	Apply
CO5	Define tools and techniques of failure analysis, procedural steps for investigation of failure.	Remember

COURSE A	ARTI	CUL	ATIC	N M	ATR	IX									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	1	1									2	2	
CO2	2	2	1	3									2	2	
CO3	2	2	1	3	1								2	2	
CO4	2	2	1	3	1								2	2	
CO5	2	2	1	3	3								2	2	
Avg	1.8	2	1	2.6	1.7								2	2	
	•	3/2/	/1 – ir	dicat	es str	enoth	of co	rrelat	tion (3 – Higl	h. 2- M	edium.	1- Low)		

22M	IEH305	PRODUCT LIFE CYCLE MANAGEMEN	IT				
PREI	REQUIS	TES	CATEGORY	PE	Cr	edit	3
			Hours/Week	L	T	P	Tl
			nours/ week	3	0	0	3
COU	RSE OBJ	ECTIVES:					
1.	To study	about the history, concepts and terminology in PLM.					
2.	To learn	the functions and features of PLM/PDM.					
3.	To devel	op different modules offered in commercial PLM/PDM tools.					
4.	To demo	nstrate PLM/PDM approaches for industrial applications.					
5.	To use P	LM/PDM with legacy data bases, Coax & ERP systems.					
Ul	NIT I	HISTORY, CONCEPTS AND TERMINOLOGY OF P	LM	9	0	0	9
Data		C), Product Lifecycle Management (PLM). PLM/PDM Infrastrucent, Heterogeneous data sources and applications PLM/PDM FUNCTIONS AND FEATURES	cture – Network ai	nd Cor	mmun	o icatio	ons,
data t UN Case	IT III studies ba	roduct Classification and Programme Management. Utility Function at translation, image services, system administration and application and app	ion integration RE chill, ENOVIA, Ar	9 ras PL	0 M, SA	0 AP PI	9 .M,
		gile PLM and Autodesk VaultArchitecture of PLM software- sele and name to be removed	ection criterion of so	oftwar	e for p	artic	ılar
UN	IT IV	ROLE OF PLM IN INDUSTRIES		9	0	0	9
PLM imple	strategy, ementation	PLM selection and implementation (like auto, aero, electronic) - PLM feasibility study, change management for PLM, financial , ten step approach to PLM, benefits of PLM for-business, organis rocess compliance and process automation	justification of PL	M, ba	rriers	to P	LM
UN	NIT V	BASICS ON CUSTOMISATION/INTEGRATION OF SOFTWARE	PDM/PLM	9	0	0	9
PLM	Customiza	ation, use of EAI technology (Middleware), Integration with legacy	data base, CAD, S	SLM aı	nd ER	P.	
			Total (45L)	= 45	Perio	ods
TEX	т воок	S:					
1.		act Lifecycle Management for a Global Market, Springer; 2014 e 516330	edition (29 Septem	ber 20	16),IS	SBN-	10 :
2.	Produ	ct Life Cycles and Product Management, Praeger Publishers Inc (2	7 March 1989)ISB	N-10	: 0899	93031	96
REF1	ERENCE	S:					
1.	Antti Editio	Saaksvuori and AnselmiImmonen, "Product Lifecycle Manage on)	ement", Springer I	Publish	ner, 2	008 ([3rd
2.		Crnkovic, Ulf Asklund and Annita Persson Dahlqvist, "Imple		grating	Prod	uct I)ata

Springer Publisher, 2007

Publisher, 2011 (2nd Edition).

3.

4.

Management and Software Configuration Management", Artech House Publishers, 2003.

J ohn Stark, "Global Product: Strategy, Product Lifecycle Management and the Billion Customer Question",

John Stark, "Product Lifecycle Management: 21st Century Paradigm for Product Realisation", Springer

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:							
CO1	Summarize the history, concepts and terminology of PLM	Remember						
CO2	Develop the functions and features of PLM/PDM	Create						
CO3	Discuss different modules offered in commercial PLM/PDM tools.	Evaluate						
CO4	Interpret the implement PLM/PDM approaches for industrial applications.	Analyze						
CO5	Integrate PLM/PDM with legacy data bases, CAD & ERP systems	Analyze						

COURSE A	ARTI	CULA	ATIO1	N MA	TRI	X									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	1									2	2	1	1	
CO2	1	1									2	2	1	1	
CO3	1	1			1						2	2	1	1	
CO4	1	1			2				2		2	2	1	1	
CO5	1	1			3				2		2	2	1	1	
Avg	1	1			2				2		2	2	1	1	
	1	3/2	2/1 – i	ndica	tes sti	rengtl	of co	rrelat	ion (3	– High	, 2- Me	dium, 1	- Low)		1

	IEH306	ERGONOMICS IN DESIGN					
PRE	REQUIS	ITES CATEGOI	RY	PE	Cr	edit	3
			,	L	Т	P	TH
		Horus/We	ek	3	0	0	3
COU	RSE OBJ	JECTIVES:					•
1.		ely recognize and evaluate hazards (ergonomic in nature) Accurately recogmic in nature) which are likely to cause occupational illnesses or injuries.	iize	and e	valua	te haz	zards
2.	To introd	duce students about the essentials of Static and dynamic anthropometry and Posts	re an	ıd job ı	relatio	on	
3.	Apply th	ne knowledge, skills, and abilities obtained in through subject into an industrial bar	sed p	robler	n.		
U	NIT I	INTRODUCING ERGONOMICS AND DISCIPLINE APPROACH ERGONOMICS/ HUMAN FACTORS	;	9	0	0	9
Obje	ective, Mut	Human aid to lifestyle, Journey, Fitting task to man their contractual structure, tual task comfort: two way dialogue, communication model, Ergonomics/ humork physiology) and stress					
Ul	NIT II	HUMAN PHYSICAL DIMENSION CONCERN AND POSTURE A MOVEMENT	ND	9	0	0	9
		Stand Posture- erect, Anthropometry landmark: Sitting postures, Anthropometry	try: :	squatti	ing ai	nd cro	mic oss-
body	y- structure	s, Anthropometric measuring techniques, Statistical treatment of data and perce and function, Posture and job relation, Posture and body supportive devices, Charlorizontal work surface, Movement, Work Counter.	ntile	calcul	ation	s Hun	oss- nan
body	y- structure	s, Anthropometric measuring techniques, Statistical treatment of data and perce and function, Posture and job relation, Posture and body supportive devices, Cha	ntile	calcul	ation	s Hun	oss- nan
UN Com	y-structure k surface, H NIT III nmunication perception,	s, Anthropometric measuring techniques, Statistical treatment of data and perce and function, Posture and job relation, Posture and body supportive devices, Charlerizontal work surface, Movement, Work Counter. BEHAVIOUR AND PERCEPTION AND VISUAL ISSUES,	ntile ir cha	calcul aracter 9 Cormat	ation istics 0	o Hum	oss-nan ical 9
UN Com and disp	y-structure k surface, H NIT III nmunication perception,	s, Anthropometric measuring techniques, Statistical treatment of data and perce and function, Posture and job relation, Posture and body supportive devices, Charlorizontal work surface, Movement, Work Counter. BEHAVIOUR AND PERCEPTION AND VISUAL ISSUES, ENVIRONMENTS FACTORS In and cognitive issues, Psycho-social behaviour aspects, behaviour and stereotyp, Cognitive aspects and mental workload, Human error and risk perception; Visual Processing P	ntile ir cha	calcul aracter 9 Cormat	ation istics 0	o Hum	oss-nan ical 9
UN Com and disp UN Ergo Som disco	NIT III munication perception, lays, Enviro NIT IV onomics desire checklists omforts and	s, Anthropometric measuring techniques, Statistical treatment of data and perce and function, Posture and job relation, Posture and body supportive devices, Charlorizontal work surface, Movement, Work Counter. BEHAVIOUR AND PERCEPTION AND VISUAL ISSUES, ENVIRONMENTS FACTORS In and cognitive issues, Psycho-social behaviour aspects, behaviour and stereotype, Cognitive aspects and mental workload, Human error and risk perception; Visonmental factors influencing human performance. ERGONOMIC DESIGN PROCESS, PERFORMANCE SUPPORT	ntile ir cha	9 Format performation of the performation of the performation of the performance of the p	ation istics 0 ion prominence nominence	o verting of the control of the cont	9 ing ual
UN Comand disp UN Ergo Som disco Hun	NIT III munication perception, lays, Enviro NIT IV onomics desire checklists omforts and	s, Anthropometric measuring techniques, Statistical treatment of data and perce and function, Posture and job relation, Posture and body supportive devices, Charlorizontal work surface, Movement, Work Counter. BEHAVIOUR AND PERCEPTION AND VISUAL ISSUES, ENVIRONMENTS FACTORS and cognitive issues, Psycho-social behaviour aspects, behaviour and stereotyp, Cognitive aspects and mental workload, Human error and risk perception; Visonmental factors influencing human performance. ERGONOMIC DESIGN PROCESS, PERFORMANCE SUPPORT AND DESIGN INTERVENTION sign methodology, Ergonomics criteria/check while designing, Design process invise for task easiness. Occupational safety and stress at workplace in view to reduce the dunsafe acts, Workstation design, Furniture support, Vertical arm reach and design	ntile rcha	9 Format performation of the performation of the performation of the performance of the p	ation istics 0 ion prominence nominence	o verting of the control of the cont	9 ing ual
UN Com and disp UN Ergo Som disco Hunn UI Offfin According Desired to the control of the control	y- structure k surface, F NIT III munication perception, lays, Environ NIT IV conomics des the checklists comforts and manising des NIT V ce Furniture essories Re agn Consider	s, Anthropometric measuring techniques, Statistical treatment of data and perce and function, Posture and job relation, Posture and body supportive devices, Charlorizontal work surface, Movement, Work Counter. BEHAVIOUR AND PERCEPTION AND VISUAL ISSUES, ENVIRONMENTS FACTORS n and cognitive issues, Psycho-social behaviour aspects, behaviour and stereotyp, Cognitive aspects and mental workload, Human error and risk perception; Vionmental factors influencing human performance. ERGONOMIC DESIGN PROCESS, PERFORMANCE SUPPORT AND DESIGN INTERVENTION sign methodology, Ergonomics criteria/check while designing, Design process invest for task easiness. Occupational safety and stress at workplace in view to reduce the dunsafe acts, Workstation design, Furniture support, Vertical arm reach and desisting: Design and human compatibility, comfort and adaptability aspects. OFFICE FURNITURE GUIDELINES FOR FIT AND FUNCTION DESIGN ERGONOMICS IN INDIA AND UNIVERSAL DESIGN	ntile e, Infile	g ergo ential plicati	o o o o o o o o o o o o o o o o o o o	o cs che e, erro ossibil o und Fi Jniver	9 ing ual 9 eck, ors, ity,

TEXT	TEXT BOOKS:									
1.	Bridger, RS: Introduction to Ergonomics, 2nd Edition, Taylor &Francis, 2003.									
2.	Dul, J. and Weerdmeester, B. Ergonomics for beginners, a quick reference guide, Taylor & Francis, 1993.									
REFEI	RENCES:									
1.	Green, W.S. and Jordan, P.W, Human Factors in Product Design, Taylor & rancis, 1999.									
2.	D. Chakrabarti, Indian Anthropometric Dimensions for ergonomic design practice, National Institute of Design, Ahmedabad, 1997									

G Salvendy (edit)	Handbook of Human	Factors and ergonomics.	John Wiley &	Sons Inc 1998
i O. Sarvenuv (cuit)	. Handbook of Human	raciois and cigonomics.	JUILL WILLY O	k 50118, 1110., 1990.

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:					
CO1	Learn about the basics of human aid to lifestyle, physiology and stress.	Understand				
CO2	Learn about the anthropometry: body growth and somatotypes, further about vertical work surface, horizontal work surface can also be obtained.	Remember				
СОЗ	Study about the communication and cognitive issues, it promotes about environmental factors influencing human performance.	Understand				
CO4	Learn about the ergonomics design methodology and gives fathom notion on occupational safety and stress at workplace.	Apply				
CO5	Study about office furniture guidelines for fit and function and universal design considerations.	Apply				

COURSE A	OURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1					3	2	2				2	1	2	1
CO2	1					3	2	2				2	1	2	1
CO3	1					3	2	2				2	1	2	1
CO4	1					3	2	2				2	1	2	1
CO5	1					3	2	2				2	1	2	1
Avg	1					3	2	2				2	1	2	1
	3/2/1 – indicates strength of correlation (3 – High, 2- Medium, 1- Low)														

3.

22M	EH307	SURFACE ENGINEERING					
PREI	REQUISI	TES	CATEGORY	PE	Cro	edit	3
			Hanna/Wash	L	Т	P	ТН
			Hours/Week	3	0	0	3
COUI	RSE OBJ	ECTIVES:					
1.	To teach	students fundamental about surface properties in engineering app	lications and wear n	nodes.			
2.	To introd	duce students about the essentials of electroplating and other platin	g processes.				
3.	To teach	about the thin film for wear application, coating specifications.					
4.	To teach	about the special surfacing processes.					
5.	To teach	about the hard facing processes and applications.					
UN	I TI	BASICS OF SURFACE ENGINEERING		9	0	0	9
mode	s; Categor	urfaces and wear surface properties in engineering applications, Curies of wear, Low stress, High stress and Gougingoabrasion, Cg wear, Adhesive wear, Seizure, Galling, Oxidative wear, Spalling	avitation, Slurry er	osion,			
UN	II II	PLATING PROCESSES		9	0	0	9
		f electroplating, Electro deposition from plating baths, Electroless, Other plating processes, Applicability of plating for wear resistar		ıg, Sel	ective	plati	ng,
UN	IT III	THIN FILM COATINGS		9	0	0	9
Theri	nal evapor	ation, PVD and CVD, Sputter coating, Ion plating, Thin film for v	vear application, Co	ating s	pecifi	catio	ns.
UN	IT IV	SPECIAL SURFACING PROCESSES		9	0	0	9

sleeves, Wear plates.

UNIT V HARD FACING PROCESSES AND APPLICATIONS 9 0 0 9

Rebuilding and surface cements, Wear tiles, Electrospark deposition coatings, Fused carbide cloth ceramic coatings, Wear

Shielded metal arc welding, Gas tungsten arc welding, Gas metal arc welding, Flux coaxed are welding, Submerged arc welding, Plasma arc welding, oxyacetylene welding, Furnace fusing, Thermal spray processes and their applications, Hardfacing transformation, Fusion alloys, Non-fusion materials. Hardfacing in new designs, Hardfacing for repairs, Hardfacing with fusion processes, Non-fusion deposits, Weldability considerations, Finishing considerations.

TEXT	TEXT BOOKS:								
1.	Budinski, K.G., Surface Engineering for Wear Resistance, Prentice Hall (1988).								
2.	Mathews, A., Advanced Surface Coatings: A Hand book of Surface Engineering, Spinger (1991)								
REFE	REFERENCES:								
1.	Hocking, M.G., Metallic and Ceramic Coatings, John Wiley (1989)								
2.	Strafford, K.N., Datta, P.K., and Gray, J.S., Surface Engineering Practice, Processes, Fundamentals and Applications in Corrosion and Wear, Ellis Harwood (1990).								

COUR Upon o	Bloom Taxonomy Mapped	
CO1	Learn about the basics and current status of surface engineering and wear modes.	Understand
CO2	Learn about the fundamentals of electroplating and other plating processes.	Understand
CO3	Study about the thermal evaporation and wear application, coating specifications.	Remember
CO4	Learn about the rebuilding and surface cements, wear sleeves, and wear plates.	Understand
CO5	Study about shielded metal arc welding, gas tungsten arc welding and non-fusion deposits, weldability considerations, finishing considerations.	Understand

COURSE	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	1	2		1								2	1	
CO2	1	1	2		1								2	1	
CO3	1	1	2		1								2	1	
CO4	1	1	2		1								2	1	
CO5	1	1	2		1								2	1	
Avg	1	1	2		1								2	1	
	3/2/1 – indicates strength of correlation (3 – High, 2- Medium, 1- Low)														

22M	IEH308	INDUSTRIAL LAYOUT DESIGN AND SA	FETY				
PRE	REQUIS	ITES	CATEGORY	PE	Cro	edit	3
1. 2.	Knowled	lge in basic manufacturing systems. lge in operations research	Hours/Week	L	T	P	ТН
3.		lge in safety regulations.		3	0	0	3
COL	JRSE OB	JECTIVES:					
1.	To get th	e basics of process layout and product layout.					
2.	To explo	re the layout planning by computer applications following differen	nt algorithms.				
3.	To imbib	e knowledge on safety management functions and its techniques.					
4.	To introd	uce knowledge on accident reporting and investigation procedure					
5.	To assim	ilate knowledge on workplace hazards and its control.					
Uì	I TIN	INTRODUCTION		9	0	0	9
speci		s, Layout design procedures, Overview of the plant layout. Proce inplementation and follow up, comparison of product and process COMPUTERIZED LAYOUT PLANNING		et laye	out: S	electi 0	ion, 9
		lant layout – ALDEP, CORELAP, CRAFT, Group Layout, Fixed and bound method, Evaluation of layout.	d position layout - (Quadra	tic ass	ignm	ient
UN	IT III	SAFETY REGULATIONS		9	0	0	9
Occu of ma	rrence, Re	y. Safety and productivity. Definitions: Accident, Injury, Unsportable accidents. Theories of accident causation. Safety organic supervisors, workmen, unions, government and voluntary agencies, Overview of factories act 1948 – ISO-45001.	zation- objectives, ty	pes, fi	unctio	ns, R	Role
UN	IT IV	SAFETY HARAZDS IN MACHINES		9	0	0	9
		ing, Guarding of hazards, Machine Guarding types and its applicated and Mechanical material handling-Safety in use of electricity		ding aı	nd Ga	s cutt	ing
UN	NIT V	CHEMICAL AND FIRE HAZARDS		9	0	0	9
hazaı	ds- control	- Types of Chemical Hazards-Occupational diseases caused by measures Fire triangle- Types of fire - first aid fire fighting equipation and Risk Analysis, case studies					

Total (45L) = 45Periods

TEXT B	OOKS:
1.	James M Moore-Plant Layout Design, Mac Millan Co.1962 LCCCN61-5204.
2.	Krishnan N.V. "Safety Management in Industry" Jaico Publishing House, Bombay, 1997
REFERI	ENCES:
1.	James Apple, "Plant Layout & Material Handling", The Ronalt Press Co., New Delhi, 1998.
2.	Pannerselvam. R, "Production and Operations Management", PHI, 2017
3.	Sunderesh Heragu-Facilities Design, PWS Publishing Company, ISBN-0-534-95183.
4.	Heinrich H.W. "Industrial Accident Prevention" McGraw-Hill Company, New York, 1980.
5.	Blake R.B., "Industrial Safety" Prentice Hall, Inc., New Jersey, 1973
6.	John Ridley, "Safety at Work", Butterworth & Co., London, 1983.

	RSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Able to get the basics of layout design procedure and selection of appropriate layout for industries.	Create
CO2	The students will be able to plan and design plant and production layouts through basic strategies and with computer application	Create
CO3	Apply principles of safety management, its functions and technique in any organization.	Apply
CO4	Apply machine guarding principles in industrial applications.	Apply
CO5	Realize chemical hazards, toxicity, fire and explosion in the work place and involve to take various control measures to prevent hazards	Understand

COURSE A	RTI	CULA	TIO	N MA	TRI	K									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	1	2	3	2	1	1	2	2	2	2	3	2	2
CO2		1	2	3		1		1	2		2		1	2	1
CO3		2	2	1	3	1	1	1	1		1	2	2	3	2
CO4		2	1	1	2			1	1	1	2		2	1	1
CO5	1	2	2	1	2			1	1	1	2	1	3	2	1
Avg	1	1.8	1.6	1.6	2.5	1.3	1	1.0	1.4	1.3	1.8	1.0	1.7	2	1.4
		3/2/	1 – in	dicat	es str	ength	of co	rrelati	on (3	– High,	, 2- Med	lium, 1	- Low)		

	DIGITAL MANUFACTURING AND IOT				
PREREQUI	SITES CATEGOR	Y PE	0 0 g: Product liture of Digit 0 0 ering Vaultin 1 Mock up an enges in Digit	3	
	Harris AV as	L	Т	P	TH
	Hours/Wee	3	0	0	3
COURSE OF	JECTIVES:		•		
1. To stu	ly the various aspects of digital manufacturing.				
2. To inci	lcate the importance of DM in product lifecycle management and supply chain ma	nagement.			
3. To form	nulate of smart manufacturing systems in the digital work environment.				
4. To inte	rpret IOT to support the digital manufacturing.				
5. To elab	orate the significance of digital twin.	9 0 0 Manufacturing: Product ing – The Future of Digorous Product Product of Digorous Product Pro			
UNIT I	INTRODUCTION	9	0	0	9
and Product r Prototype dev	Product Development, Mapping Requirements to specifications - Part Numberin		erina '	143	
UNIT III	euse – Engineering Change Management, Bill of Material and Process Consistence lopment – Virtual testing and collateral. Overview of Digital Supply Chain – Scope Digital Transformation - Future Practices in SCM		l Moc	k up	and
UNII III	elopment – Virtual testing and collateral. Overview of Digital Supply Chain – Scope	and Chall	l Moc enges	k up in Dig	and
Smart Factory	elopment – Virtual testing and collateral. Overview of Digital Supply Chain – Scope Digital Transformation - Future Practices in SCM	and Chall	l Mocenges	k up in Dig	and rital
Smart Factory	elopment – Virtual testing and collateral. Overview of Digital Supply Chain – Scope Digital Transformation - Future Practices in SCM SMART FACTORY - Levels of Smart Factories – Benefits – Technologies used in Smart Factory – S	and Chall	1 Modenges	k up in Dig 0 IoT- I	and rital
Smart Factory Principles of a UNIT IV Introduction - services – Int	elopment – Virtual testing and collateral. Overview of Digital Supply Chain – Scope Digital Transformation - Future Practices in SCM SMART FACTORY - Levels of Smart Factories – Benefits – Technologies used in Smart Factory – Smart Factory – Creating a Smart Factory – Smart Factories and Cyber security	9 mart Facto 9 Connectiv	Output Design of the second of	ek up in Dig	and gital 9 Key 9 and
Smart Factory Principles of a UNIT IV Introduction - services – Int	elopment – Virtual testing and collateral. Overview of Digital Supply Chain – Scope Digital Transformation - Future Practices in SCM SMART FACTORY - Levels of Smart Factories – Benefits – Technologies used in Smart Factory – Sasmart Factory – Creating a Smart Factory – Smart Factories and Cyber security INDUSTRY 4.0 - Industry 4.0 – Internet of Things – Industrial Internet of Things – Framework: Celligent networks of manufacturing – Cloud computing – Data analytics – Cyber ph	9 mart Facto 9 Connectiv	Output Design of the second of	ek up in Dig	and gital 9 Key 9 and
Smart Factory Principles of a UNIT IV Introduction - services – Int to Machine co UNIT V Basic Concep	elopment – Virtual testing and collateral. Overview of Digital Supply Chain – Scope Digital Transformation - Future Practices in SCM SMART FACTORY - Levels of Smart Factories – Benefits – Technologies used in Smart Factory – Smart Factory – Creating a Smart Factory – Smart Factories and Cyber security INDUSTRY 4.0 - Industry 4.0 – Internet of Things – Industrial Internet of Things – Framework: Calligent networks of manufacturing – Cloud computing – Data analytics – Cyber phenomenication – Case Studies.	9 mart Facto 9 Connectivysical sys 9 dow- Bui	Outy devices -	ek up in Dig 0 IoT- I vices -Mach	9 Xey 9 and dinne

TEXT	BOOKS:
1.	Zude Zhou, Shane (Shengquan) Xie and Dejun Chen, Fundamentals of Digital Manufacturing Science, Springer-Verlag London Limited, 2012.
2.	Alasdair Gilchrist, "Industry 4.0: The Industrial Internet of Things", A press, 2016.
REFER	RENCES:
1.	Lihui Wang and Andrew YehChing Nee, Collaborative Design and Planning for Digital Manufacturing, Springer-Verlag London Limited, 2009.
2.	Andrew Yeh Chris Nee, Fei Tao, and Meng Zhang, "Digital Twin Driven Smart Manufacturing", Elsevier Science., United States, 2019.
3.	Alp Ustundag and Emre Cevikcan, "Industry 4.0: Managing The Digital Transformation", Springer Series in Advanced Manufacturing., Switzerland, 2017
4.	Ronald R. Yager and Jordan Pascual Espada, "New Advances in the Internet of Things", Springer., Switzerland, 2018.
5.	Ronald R. Yager and Jordan Pascual Espada, "New Advances in the Internet of Things", Springer., Switzerland, 2018

	RSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Impart knowledge to use various elements in the digital manufacturing.	Understand
CO2	Differentiate the concepts involved in digital product development life cycle process and supply chain management in digital environment.	Analyze
CO3	Select the proper procedure of validating practical work through digital validation in Factories.	Apply
CO4	Implementation the concepts of iot and its role in digital manufacturing.	Apply
CO5	Analyse and optimize various practical manufacturing process through digital twin.	Analyze

COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	1					2				2	2	2	2	2
CO2	1	1					2				2	2	2	2	2
CO3	1	1					2				2	2	2	2	2
CO4	1	1					2				2	2	2	2	2
CO5	1	1					2				2	2	2	2	2
Avg	1	1					2				2	2	2	2	2

22MI	EH310	SMART MOBILITY AND INTELLIGENT VEHIC	LES				
PREI	REQUI	SITES C.	ATEGORY	PE	Cro	edit	3
		н	ours/Week	L	Т	P	TI
				3	0	0	3
OUI	RSE OF	BJECTIVES:					
1.	To intr	roduce students to the various technologies and systems used to impletes.	ment smart mob	oility a	and in	itellig	ent
2.		rn Basics of Radar Technology and Systems, Ultrasonic Sonar Systems and other sensors for automobile vision system.	is, LIDAR Sens	sor Te	chnol	ogy a	and
3.	To lear	n Basic Control System Theory applied to Autonomous Automobiles.					
4.		duce overall impact of automating like various driving functions, connation that assist with a task.	ecting the autor	nobile	to so	urces	of
5.		ow the automobile to make autonomous intelligent decisions concerning ally impact the safety of the occupants through connected car and autonomous intelligent decisions.				icle t	hat
UN	IT I	INTRODUCTION TO AUTOMATED, CONNECTED ANI INTELLIGENT VEHICLES)	9	0	0	9
Powe	ertrain E	Automotive Electronics, Electronics Overview, History & Evolution, lectronics, Introduction to Automated, Connected, and Intelligent Vand Intelligent Vehicles					
UNI	IT II	SENSOR TECHNOLOGY FOR SMART MOBILITY		9	0	0	9
Гесһі		dar Technology and Systems, Ultrasonic Sonar Systems, Lidar Sensor Night Vision Technology, Other Sensors, Use of Sensor Data Fusion, Interns					
UNI	T III	CONNECTED AUTONOMOUS VEHICLE		9	0	0	9
Theo		System Theory applied to Automobiles, Overview of the Operation of I utonomous Vehicles, Role of Surroundings Sensing Systems and Autono y.					
UNI	T IV	VEHICLE WIRELESS TECHNOLOGY AND NETWORKI	NG	9	0	0	9
Syste Comp	m Conc puter Ne	em Block Diagram and Overview of Components, Transmission System epts— Demodulation/Decoding, Wireless Networking and Application tworking – the Internet of Things, Wireless Networking Fundamentals, I Vehicle Networks	s to Vehicle A	utono	my, B	Basics	of
UNI	IT V	CONNECTED CAR AND AUTONOMOUS VEHICLE TE	CHNOLOGY	9	0	0	Ģ
Vehic	cle-to-Ro	Fundamentals, Navigation and Other Applications, Vehicle-to-Vehicle and Vehicle-to-Infrastructure Applications, Autonomous Vehicle Roadblock Issues, Technical Issues, Security Issues.					
			Total ((45L)	= 45]	Perio	ods
EXT	Г ВОО	KS:					
1.	"In Boa	telligent Transportation Systems and Connected and Automated Vehiclard	es", 2016, Tran	sporta	tion F	Resea	rch
2.	Rad	dovan Miucic, "Connected Vehicles: Intelligent Transportation Systems'	', 2019, Springe	r			
EFI	ERENC	TES:					
1.	Toi	m Denton, "Automobile Electrical and Electronic systems, Roultedge", T	aylor & Francis	Grou	p, 5th	Editi	on,

2018.

	SE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Recognize the concept of cyber-physical control systems and their application to collision avoidance and autonomous vehicles.	Understand
CO2	Select the concept of remote sensing and the types of sensor technology needed to implement remote sensing.	Understand
CO3	Familiar with the concept of fully autonomous vehicles.	Understand
CO4	Apply the basic concepts of wireless communications and wireless data networks.	Apply
CO5	Analyse the concept of the connected vehicle and its role in automated vehicles.	Analyse

COURSE	ART	ICUL	ATIC)N M	ATR	IX									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	2		2	1					1	2	2	2	
CO2	2	2	2		2	1					1	2	2	2	
CO3	2	2	2		2	1					1	2	2	2	
CO4	2	2	2		2	1					1	2	2	2	
CO5	2	2	2		2	1					1	2	2	2	
Avg	2	2	2		2	1					1	2	2	2	
		3/2/	1 – in	dicat	es str	ength	of co	rrelati	on (3 -	- High,	2- Medi	um, 1-	Low)		

ELECTIVES FOR MINOR

22CEM01	CONSTRUCTION MATERIALS		S	emest	er	
PREREQUI	 SITES (Category	OE	Cr	edit	3
NIL		Hours/Week	L	Т	P	TH
		mours/ week	3	0	0	3
Course Lear	rning Objectives		,		J	l
1 To stud	dy the characteristics and Properties of Stones and Brick					
2 To imp	part knowledge on Cement, Aggregate and Mortar					
3 To und	derstand the behaviour of concrete and seasoning timber					
4 To stud	dy the Parts and types of flooring and roofing					
5 To stud	dy carpentry, arches, lintels and finishing works.					
Unit I	STONES, BRICKS		9	0	0	9
work – tests o	e –classification of rocks-characteristics of good building stone n stones - Bricks- manufacture of clay bricks -classification - tests of		-			
bricks.						
characteristics	CEMENT, AGGREGATES, MORTAR position- manufacturing process-wet and dry processes. Aggrand function. Mortar- properties- uses- types of mortars- selection	gregates –coars				
Unit II Cement- comparacteristics construction.	position- manufacturing process-wet and dry processes. Again and function. Mortar- properties- uses- types of mortars- selection	gregates —coars n of mortars for v	se and various (fine a	ggregat	es- ng
Unit II Cement- come characteristics construction. Unit III	position- manufacturing process-wet and dry processes. Age and function. Mortar- properties- uses- types of mortars- selection CONCRETE, TIMBER AND OTHER MATER	gregates –coars n of mortars for v	se and	fine a	ggregat	es-
Unit II Cement- complete construction. Unit III Concrete- ingr	position- manufacturing process-wet and dry processes. Again and function. Mortar- properties- uses- types of mortars- selection CONCRETE, TIMBER AND OTHER MATER redients - principles of hardened concrete- Special concrete- types.	gregates —coars n of mortars for v	se and various (fine a Civil E	ggregat ngineeri 0	es- ng
Unit II Cement- complete construction. Unit III Concrete- ingr	redients - principles of hardened concrete- Special concrete- types. Classical concrete- seasoning-preservation- Panels of laminates. Glass- p	gregates —coars n of mortars for v	se and various (fine a Civil E	ggregat ngineeri 0	es- ng
Unit II Cement- comparate construction. Unit III Concrete- ingraph construction construction and construc	concrete- types of hardened concrete- Special concrete- types acteristics- seasoning-preservation- Panels of laminates. Glass- pd other metallic materials for construction.	gregates —coars n of mortars for v	se and various (fine a Civil E	ggregat ngineeri 0	es- ng
Unit II Cement- comparate construction. Unit III Concrete- ingramment characteristics	redients - principles of hardened concrete- Special concrete- types. Classical concrete- seasoning-preservation- Panels of laminates. Glass- p	gregates —coars n of mortars for v	se and various (fine a Civil E	ggregat ngineeri 0	es- ng
Unit II Cement- components of dampness-	concrete- types. CONCRETE, TIMBER AND OTHER MATER redients - principles of hardened concrete- Special concrete- types. acteristics- seasoning-preservation- Panels of laminates. Glass- pd other metallic materials for construction. these and Distempers-types-properties.	rious application	9 Steel- U	fine a Civil En	ggregatingineeri	es- ng 9 forms
Unit II Cement- complete construction. Unit III Concrete- ingrammer characteristics construction. Unit III Concrete- ingrammer characteristics construction. Unit IV Components confidences confide	CONCRETE, TIMBER AND OTHER MATER redients - principles of hardened concrete- Special concrete- types. acteristics- seasoning-preservation- Panels of laminates. Glass- pd other metallic materials for construction. hes and Distempers-types-properties. FLOORING AND ROOFING of floor- selection of flooring materials- suitability of floors for varieffect of dampness - requirements of good stairs - classification of	RIALS . properties- uses. rious application f stairs -Roofs - t	9 Steel- U	fine a Civil En	ggregatingineeri	es- ng 9 form
Unit II Cement- components of dampness-pitched roof declassification of declassification.	CONCRETE, TIMBER AND OTHER MATER redients - principles of hardened concrete- Special concrete- types. acteristics- seasoning-preservation- Panels of laminates. Glass- pd other metallic materials for construction. hes and Distempers-types-properties. FLOORING AND ROOFING of floor- selection of flooring materials- suitability of floors for varieffect of dampness - requirements of good stairs - classification of lean to roof-gable roof-hip roof-flat roof-RCC roof. CARPENTARY, ARCHES, LINTELS AND FIN	RIALS . properties- uses. rious application f stairs -Roofs - t IISHING fastenings for detel. scaffolding -	9 Steel- U 9 oors and	fine a Civil En	ggregatingineeri	9 forms 9 cause ments

T	ext Books:
1	B.C. Punmia, Building Construction, Laxmi Publications; Eleventh edition -2021
2	S.C.Rangwala, Building Construction, Charotar Publishing House Pvt. Ltd, 34th Edition - 2022
3	P. Purushothama Raj., Building Construction Materials and Techniques, Pearson Education India, First Edition - 2017

Ref	Reference Books:						
1	Shetty M.S., Concrete Technology (Theory and Practice), S.Chand& Company Ltd.,2021.						
2	Rangwala S.C., Engineering Materials (Material Science) revised and enlarged by Rangwala K.S. and Rangwala P.S.,						
2	Charotar Publishing House, 2010.						

	se Outcomes: completion of this course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Identify and characterize and properties of Stone and brick	Remember
CO2	Understand the manufacturing process of cement and functions of mortar	Understand
CO3	Identify the age of timber and preservation methods of timber	Remember
CO4	Differentiate the types of roofing and flooring	Understand
CO5	Understand the miscellaneous works such as carpentry, lintels, Arch, etc.	Understand

COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	-	-	-	-	-	1	-	-	-	-	-	-	-	•
CO2	-	2	-	-	-	2	3	-	-	-	-	-	-	-	-
CO3	1	-	-	-	1	-	-	-	-	-	-	-	-	-	-
CO4	1	-	2	-	2	3	2	-	-	-	-	-	-	-	-
CO5	1	-	-	-	3	-	2	-	-	-	-	-	-	-	-
Avg	1	2	2	-	2	3	2	-	-	-	-	-	-	-	-
			2/2/1	india	. t o a a t m	onath o	f commo	lation (2 II:~l	. 2 Ma		I 0***)	ı		

3/2/1 – indicates strength of correlation (3- High, 2- Medium, 1- Low)

1 Ab 2 Ab 3 Ab 4 Ab	Learning of the control of the contr		Category Hours/Week	OE L 3	Cr T 0	edit P 0	3 TH 3
1 Ab 2 Ab 3 Ab 4 Ab	ole to ga	in basic knowledge in construction methods.	Hours/Week				
1 Ab 2 Ab 3 Ab 4 Ab	ole to ga	in basic knowledge in construction methods.		3	0	0	3
1 Ab 2 Ab 3 Ab 4 Ab	ole to ga	in basic knowledge in construction methods.					
2 Ab3 Ab4 Ab	ole to gar ole to gar						
3 Ab	ole to ga	in basic knowledge in equipment.					
4 Ab	ole to ga						
		in basic knowledge in machineries.					
5 Ab	10 to 00	in basic knowledge in fire safety principles.					
	ne to ga	in basic knowledge in green technology.					
TT •4	_	CLASSIFICATION OF BUILDINGS, FOUND	ATIONS AND	9	0	0	9
Unit	: 1	TYPES OF MASONRY					
Site inve	estigation	of a building -Their functions. Classification of buildings and for foundation as per N.B.C, Types of foundation of stone masonry	•		_		seme
		DOORS, WINDOWS, LINTELS, SCAFFOL		0		0	
Unit 1	II	STAIRCASES	9	0	0	9	
		ws – parts of door and window – Types of Door and w – Functions, Scaffolding – Purpose and types –Location of			d, swin	ging ty	pe an
		ROOFS, FLOORINGS, PROTECTIVE AND D	DECORATIVE	9	0	0	9
Unit I	111	FINISHES			U	U	
		Roof Slabs – Types of Roofing Systems – Methods of Tern Plastering (Interior and Exterior) – Pointing for Walls an	_			_	
• •		ferent Color Shades available in the Markets – Painting	•			•	
application		referre color shades available in the Markets Tament	5 Types of Tunic	ing 101		una 2	Atorio
Unit I	IV	CONSTRUCTION EQUIPMENT	S	9	0	0	9
	-	ipment for earthwork excavation, drilling, blasting, tunnial handling and erection of structures	nelling, erection an	nd dewa	tering	and pui	mping
Unit		GREEN BUILDING TECHNOLOG	GY	9	0	0	9
		een technology – types and importance; zero waste and r cogreen buildings, green engineering.	oncept, green materi	ials – gre	een con	crete (p	urpos
					Total	= 45 Pc	eriod

Te	ext Books:
1	Building Construction by S.C.Rangawala
2	Construction Technology by Sarkar Oxford University Press
3	Building Material & Construction by S.P. Arora& S. P. Bindra

Ref	Reference Books:						
1	Hopkinson And Kay J.D., The Lighting of Building, Faber and Faber, London.						
2	Koerner, R.M, Construction & Geotechnical Methods in Foundations Engineering, McGraw Hill, 1984						
3	Varna M., Construction Equipment and Its Planning & Applications, Metropolitan Books Co, 1979						

	se Outcomes: completion of this course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Organize the construction technique to be followed in brick and stone masonry, concreting, flooring, roofing and plastering etc.	Create
CO2	Select safe practices in building construction activities	Evaluate
CO3	Clarify the different types of roofs, floor and productive materials of buildings	understand
CO4	Select the relevant equipment for building construction	Evaluate
CO5	Apply the Principles of green building technology.	Apply

COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	-	-	-	-	3	2	2	2	1	1	-	-	-	-	1
CO2	-	-	-	-	3	2	2	2	2	2	-	-	-	-	1
CO3	-	-	-	-	2	3	2	2	2	1	-	-	-	-	1
CO4	-	-	-	-	2	2	3	1	1	2	-	-	-	-	1
CO5	-	-	-	-	2	3	2	2	2	2	-	-	-	-	1
Avg	-	-	-	-	2.4	2.4	2.2	1.8	1.6	1.6	-	-	-	-	1

3/2/1 – indicates strength of correlation (3- High, 2- Medium, 1- Low)

22CEM03		CONCRETE TECHNOLOG	S								
PRI	EREQUISI	TES	Category	OE	Cr	edit	3				
NIL	,		Hours/Week	L	T	P	TH				
			Hours/ week	3	0	0	3				
Cou	rse Learni	ng Objectives	,	•		•	•				
1	To unders	derstand the properties of ingredients of concrete.									
2	To study t	the behavior of concrete at its fresh and hardened state.									
3	To study a	about the concrete design mix.									
4	To know a	about the procedures in concrete at different stage.									
5	To unders	tand special concrete and their uses.									
	Unit I	INTRODUCTION		9	0	0	9				
Acce	•	ADMIXTURES mixtures, Retarding admixtures, water reducing admixtures, Mixing, Transportation, placing of concrete, curin		9 g admixt	0 ures, co	0 oloring	g agent,				
Acce	elerating adı	mixtures, Retarding admixtures, water reducing admi									
Acce Plast	elerating addicizers. Batc	mixtures, Retarding admixtures, water reducing admitting, Mixing, Transportation, placing of concrete, curing	g of Concrete	g admixt	ures, co	oloring	agent,				
Acce Plast U	elerating addicizers. Batc	mixtures, Retarding admixtures, water reducing admirbling, Mixing, Transportation, placing of concrete, curin	eg of Concrete	g admixt	ures, co	oloring	agent,				
Acce Plast U Facto	elerating addicizers. Batco Unit III Ors influence Unit IV Ingth of conc	mixtures, Retarding admixtures, water reducing admixtures, Mixing, Transportation, placing of concrete, curin MIX DESIGN ng mix proportion, Mix design by ACI method and I.S.	code method, Design of TE ete, permeability of co	g admixto	o rength o	oloring Oconcrete	agent.				
Acce Plast U Facto U Strer Corr	elerating addicizers. Batco Unit III Ors influence Unit IV Ingth of conc	mixtures, Retarding admixtures, water reducing admixtures, Mixing, Transportation, placing of concrete, curin MIX DESIGN mg mix proportion, Mix design by ACI method and I.S. BEHAVIOUR OF CONCRE rete, Shrinkage and temperature effects, creep of concre	code method, Design of TE ete, permeability of co	g admixto	o rength o	oloring Oconcrete	agent.				
Accee Plast U Facto U Strer Corr	Unit IV Ingth of concosion, Cause Unit V T-weight contraction	mixtures, Retarding admixtures, water reducing admixtures, Mixing, Transportation, placing of concrete, curin MIX DESIGN mg mix proportion, Mix design by ACI method and I.S. BEHAVIOUR OF CONCRE rete, Shrinkage and temperature effects, creep of concretes and effects, remedial measures, Thermal properties of	code method, Design of TE ete, permeability of concrete, Micro crack	9 of high strong of coording of coordinate c	o verength	o concrete o o o o o o o o o o o o o o o o o o	agent, 9 e. 9 norrete,				

Te	Text Books:					
1	Neville A.M Properties of Concrete, Pearson publication, 2012.					
2	Shetty M.S Concrete technology, S.Chand and Company Ltd, New Delhi 2022.					
3	Santha Kumar A.R Concrete Technology, Oxford university Press, NewDelhi, 2022.					
4	Mehta K.P Concrete Technology, Chand & Co, NewDelhi, 2006.					
5	Robert RatayForensic Structural Engineering Handbook, McGraw Hill LLC, 2009					

Ref	ference Books:
1	Indian Standard Recommended Guide lines for Concrete Mix Design, IS:10262 – 2019, Bureau of Indian Standards, NewDelhi.
2	Indian Standard Specification for Coarse and Fine Aggregates from Natural Sources for Concrete IS:383-1970 R2011, Bureau of Indian Standards, NewDelhi.
3	Gambhir.M.L,Concrete Technology, Volume I & II, Tata McGraw-HillBookCompany,Third print, 2003
4	Krishna Raju N. Design of Concrete Mixes, CBS publishers. NewDelhi, 2002.
5	Stephen E. Petty,Forensic Engineering: Damage Assessments for Residential and Commercial Structures,CRCpress,Taylor& Francis,2013.

	Course Outcomes: Upon completion of this course, the students will be able to:				
CO1	To identify suitable materials to be used in the cement concrete by conducting various tests as per BIS code.	Evaluate			
CO2	To know about the specific applications and uses of admixtures.	Understand			
CO3	Design the concrete mix using ACI and BIS code methods.	Create			
CO4	Determine the properties of fresh and hardened of concrete.	Evaluate			
CO5	Design special concretes and to Ensure quality control while testing/ sampling and acceptance criteria for pre and post construction work.	Apply			

COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	-	-		-	3	-	1	1	1	2	1	1	1	-	1
CO2	-	-		-	3	-	3	-	1	1	-	-	2	-	1
CO3	•	•	•	•	3	•	3	•	-	1	1	-	1	•	1
CO4	•	•	1	•	3	2	1	•	-	-	-	-	-	-	1
CO5	•	•	•	•	3	3	3	1	1	3	1		3	•	1
Avg	•	•	•	ı	3	2.5	2.2	1	1	1.75	1	1	1.75	-	1

3/2/1-indicates strength of correlation (3- High, 2- Medium, 1- Low)

220	CEM04	ENVIRONMENTAL ENGINE	S	Semester										
PR	EREQUISI	TES	Category	OE	Cre	3								
NII			Hours/Week	L	Т	P	TH							
			Hours/ Week	3	0	0	3							
Coi	urse Learni	ng Objectives	,	1										
1	To evaluate distribution	the sources of water and analyse its characteristics an network	d processes in water trea	atment, e	xpress t	he anal	ysis o							
2	To design sewer system, basic design of the biological treatment processes, gain knowledge on sludge treatment and its disposal													
3	To predict	he sources, effects, dispersion of air pollutants air qua	lity management and its	control 1	neasure	es								
4		To identify the characteristics and sources of municipal solid wastes, its collection methods, off-site processing of municipal solid wastes and its recovery, disposal methods												
5	To assess th	ne sources, effects and control measures of noise pollu			T	T	ı							
	Unit I	WATER TREATMENT		9	0	0	9							
Sew		WASTEWATER TREATME design, quantity and quality of domestic wastewater, e disposal; Reuse of treated sewage for different applic	primary and secondary	9 treatmen	0 nt. Efflu	0 nent disc	9 charg							
1	Unit III	AIR POLLUTION		9	0	0	9							
	Pollution: Ty	pes of pollutants, their sources and impacts, air polluti	on control, air quality st	andards,	l Air qua	lity Ind	ex and							
111111														
	Unit IV	SOLID WASTE MANAGEM	ENT	9	0	0	9							
Muı	nicipal Solid	SOLID WASTE MANAGEM Wastes: Characteristics, generation, collection and trans nt (reuse/ recycle, energy recovery, treatment and disp	sportation of solid waste											
Mui was	nicipal Solid	Wastes: Characteristics, generation, collection and trans	sportation of solid waste											
Mui was	nicipal Solid V te manageme Unit V	Wastes: Characteristics, generation, collection and trans nt (reuse/ recycle, energy recovery, treatment and disp	sportation of solid waste osal).	s, engine	ered sys	stems fo	r solic							

Te	Text Books:									
1	Garg, S.K. Water supply Engineering, Khanna Publishers, New Delhi, 2010.									
2	Garg, S.K. Sewage water disposal and Air pollution, Khanna Publishers, New Delhi, 2010.									
3	George Tchobanoglous et.al., Integrated Solid Waste Management, McGraw-Hill, Publishers, 1993.									
4	Rao, C.S., Environmental Pollution Control Engineering, Wiley Eastern Ltd., New Delhi, 1996.									

Ref	Reference Books:									
1	Manual on Water Supply and Treatment, CPHEEO, Ministry of Urban Development, Government of India, New Delhi,									
2	2013. Peavy S.W., Rowe D.R. and Tchobanoglous G. Environmental Engineering, McGraw Hill, NewDelhi, 1985.									
3	Metcalf and Eddy,M.C., Wastewater Engineering – Treatment &Reuse,TataMcGraw-Hill Publications, New Delhi,2003.									

	se Outcomes: completion of this course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Identify the sources of water supply, analyze the characteristics of water with its standards and various unit operations and processes in water treatment, express the analysis of distribution network	Remember
CO2	Expertise design sewer system, basic design of the biological treatment processes, gain knowledge on sludge treatment and disposal and justify the methods for disposal of sewage	Analyze
CO3	Predict the sources, effects, dispersion of air pollutants air quality management and its control measures	Apply
CO4	Aware about the characteristics, types and sources of municipal solid wastes, Learn the collection methods, Know about off-site processing of municipal solid wastes and its recovery, disposal methods	Remember
CO5	Understand the sources, effects and control methods of noise pollution	Understand

COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	3	2	1	3	2	1	1	2	1	1	3	-	2
CO2	2	1	3	1	1	3	1	-	1	2	2	1	3	-	2
CO3	2	1	3	1	1	3	1	-	1	2	2	1	3	-	2
CO4	2	1	3	1	1	3	1	-	-	2	2	1	3	-	2
CO5	2	-	3	-	-	3	-	-	-	2	1	1	3	-	2
Avg	2	1	3	1.3	1	3	1.3	1	1	2	1.6	1	3	-	2
	1	1	3/2/1	indice	otoc ctr	anath o	f corro	lation (3. High	2- Me	dium 1	I ow)			

3/2/1 – indicates strength of correlation (3- High, 2- Medium, 1- Low)

22C	EM05	BASICS OF TRANSPORTATION ENGINEER	S	Semester								
PRE	EREQUISI	TES Cate	gory	OE	Cr	edit	3					
NIL	ı	Hour	rs/Week	L	T	P	TH					
				3	0	0	3					
Cou	rse Learni	ng Objectives										
1	The object	ctive of the course is to educate the students on various component	s of highway	enginee	ering.							
2	To educat	te the geometric design concepts of highway engineering										
3	To develo	op skills on construction and maintenance of highway.										
4	Ability to	ty to plan various civil engineering aspects of railways and educate various components of railways										
5	The cours	se enables the students to develop skill on evaluation and maintena	nce of railw	ay track.								
	Unit I	9	0	0	9							
	U nit II	GEOMETRIC DESIGN OF HIGHWAYS		9	0	0	9					
		GEOMETRIC DESIGN OF HIGHWAYS nments – Superelevation, Widening of Pavements on Horizonta	1 Curves V									
	ting, Except	ional and Minimum Gradients, Summit and Valley Curves -Geom			_							
τ	J nit III	CONSTRUCTION AND MAINTENANCE OF HIG	HWAY	9	0	0	9					
		Flexible and Rigid Pavements – Defects in Flexible and Rigid Pa of Pavements.	vements -Hi	ghway D	rainage	e – Eva	luatio					
τ	Jnit IV	RAILWAY PLANNING AND DESIGN		9	0	0	9					
Perm	nanent Way,	its Components and Functions of Each Component: Rails - Ty	pes of Rails	, Rail Fa	l stening	gs, Cond	cept o					
Geor	metric Desig	of Wheels, Creeps Sleepers - Functions, Materials, Density. Ballast										
1	U nit V	n of Railway Tracks Gradients and Grade Compensation, Supers, Horizontal and Vertical Curves.					Jurves					
		•	NCE AND	9	0	0	9					
		s, Horizontal and Vertical Curves. RAILWAY TRACK CONSTRUCTION MAINTENA					9					
		RAILWAY TRACK CONSTRUCTION MAINTENAL OPERATION ings – Turnouts, Track circuiting, Signaling, Interlocking, Lay Ou			ns and		9 Rolling					
		RAILWAY TRACK CONSTRUCTION MAINTENAL OPERATION ings – Turnouts, Track circuiting, Signaling, Interlocking, Lay Ou			ns and	Yards, I	9 Rolling					
Stocl		RAILWAY TRACK CONSTRUCTION MAINTENAL OPERATION ings – Turnouts, Track circuiting, Signaling, Interlocking, Lay Ou			ns and	Yards, I	9 Rolling					

Te	Text Books:							
1	Khanna K., Justo C.E.G., Highway Engineering Revised 10th Edition Khanna Publishers, Roorkee, 2014							
2	Kadiyalil. R, Engineering Traffic and Transport Planning, Khanna Publishers, New Delhi, 2019.							
3	Chandola S.P. Transportation Engineering-2019							

Ref	Reference Books:									
1	Sharma S.K., Principles Practice and Design of Highway Engineering, S. Chand & Co Ltd. New Delhi, 2006									
2	Guidelines Of Ministry of Road Transport and Highways, Government of India.									
3	Agarwal M.M., Indian Railway Track, 14th Edition, Prabha and Co., New Delhi, 2002.									
4	Saxena S.C. Highway & Traffic Engineering, 2014.									

Cour	se Outcomes:	Bloom's Taxonomy					
Upon	Upon completion of this course, the students will be able to:						
CO1	Classify roads as per Indian Road Congress and describe the principles of highway alignment	Understand					
CO2	Determine the highway geometric elements	Analyse					
CO3	Differentiate between types of pavements, their construction and design principles	Analyse					
CO4	Explain the functions of components of Railways	Understand					
CO5	Carry out the various methods for track alignment & procedure for construction of railway & maintenance of track	Apply					

COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	-	-	-	-	2	2	3	1	2	-	-	-	1	-	-
CO2	2	3	2	2	-	-	-	-	-	-	-	-	-	-	-
CO3	-	-	-	-	2	2	3	1	3	-	-	-	1	-	-
CO4	-	-	-	-	2	2	3	1	2	-	-	-	-	-	-
CO5	-	-	-	-	2	2	3	1	2	-	-	-	1	-	-
Avg	2	3	2	2	2	2	3	1	2.25	-	-	-	1	-	-
	•	•		•					•	•	•	•		•	•

22CF	ЕМ06	REPAIR AND REHABILITATION OF STI	AND REHABILITATION OF STRUCTURES						
PRE	REQUISI	TES	Category	OE Cre			3		
NIL			Hours/Week	L T P			TH		
		3 0 0							
Cour	se Learni	ng Objectives							
1	Study the	various types and properties of repair materials							
2	Learn var	ious distress and damages to concrete structures							
3	Understa	nd the importance of maintenance of structures							
4	Assess the	e damage to structures using various tests							
5	Learn var	ious repair techniques of damaged structures, corroded stru	ictures						
J	Jnit I	MAINTENANCE AND REPAIR STRA	TEGIES	9	0	0	9		
Maint	enance, rep	pair and rehabilitation, Facts of Maintenance, importance	e of Maintenance v	arious a	spects (of insp	ection,		
assess	ment proce	dure for evaluating a damaged structure, causes of deterior	ation.						
U	nit II	SERVICEABILITY AND DURABILITY OF	CONCRETE	9	0	0	9		
Quali	ty assuranc	e for concrete construction, concrete properties- strength	, permeability, ther	mal prop	perties	and cra	cking-		
effect	s due to c	imate, temperature, chemical, corrosion- Design and co	nstruction errors-ef	ffects of	cover	thickne	ss and		
cracki	ing.			_		Ī	_		
Uı	nit III	MATERIALS AND TECHNIQUES FOR	R REPAIR	9	0	0	9		
Specia	al concretes	and mortar, concrete chemical, special elements for acce	lerated strength gain	n, expans	sive cen	nent, po	olymer		
concr	ete, Sulphu	infiltrated concrete, ferro cement, fibre reinforced concrete	e, rust eliminators ar	nd polym	ers coat	ing for	rebars		
during	g repair, foa	med concrete, mortar and dry pack, vacuum concrete, gunit	te and shotcrete, epo	oxy inject	tion, mo	rtar rep	air for		
cracks	s, shoring a	nd underpinning. Methods of corrosion protection, corros	ion inhibitors, corre	osion resi	stant st	eels, co	atings		
and ca	athodic prot								
TI	nit IV	REPAIRS, REHABILITATION AND RETRO	OFITTING OF	9	0	0	9		
U I	IIIt I V		Ů	Ů					
Streng	gthening of	Structural elements, deflection, cracking, chemical disrupt	ion, weathering cor	rosion, w	ear, fire	, leaka	ge and		
marin	e exposure.								
U	Unit V DEMOLITION TECHNIQUES 9 0 0 9								
Demo	olition meth	ods by machines, explosives, Advanced techniques-Demo	olition sequences, o	lismantlii	ng tech	niques,	safety		
precai	utions in dis	mantling and demolition, Engineered demolition technique	es for dilapidated st	ructures-	case stu	ıdies			
					Total=	= 45 Pc	eriods		

Te	ext Books:
1	Shetty, M.S, Concrete Technology- Theory and Practice, S. Chand and company, New Delhi,2019
2	Repair and protection of concrete structures by Noel P. Mailvaganam, CRC Press,1991.
3	CPWD: Handbook on Repair & Rehabilitation of R.C.C. Buildings, CPWD, Govt. of India, 2002, updated reprint 2011

Ref	Perence Books:
1	Santhakumar A.R, Training Course notes on Damage Assessment and Repair in Low-cost housing, "RHDC.NBO" Anna University, July 1992.
2	Raikar R.N.,Learning from failures- deficiencies in design, construction and services – R&D Centre (SDCPL), Raikar bhavan, Bombay,1987
3	Palaniyappan, N., Estate management, Anna Institute of Management, Chennai, 1992.
4	Lakshmipathy, M. etal., Lecture notes of workshop on Repairs and Rehabilitation of structures, 29-30 th October 1999.
5	https://nptel.ac.in/courses/114106035/38

	Course Outcomes: Upon completion of this course, the students will be able to:					
CO1	Demonstrate the condition of structures					
CO2	Inspect and evaluate the damaged structure					
CO3	Implement the repairing techniques of a structure					
CO4	Identify and Use different materials for repairing works	Apply				
CO5	Demonstrate the dismantling and demolishing structures					

COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	-	2	2	2	2	3	2	-	-	-	1	2	-	-
CO2	1	-	2	2	2	2	3	2	-	-	-	1	2	-	-
CO3	1	-	2	2	2	2	3	2	-	-	-	1	2	-	-
CO4	1	-	2	2	2	2	3	2	-	-	-	1	2	-	-
CO5	1	-	2	2	2	2	3	2	-	-	-	1	2	-	-
Avg	1	-	2	2	2	2	3	2	-	-	-	1	2	-	•
			2/2/1	india	stog atm	onath o	faanna	lation (2 II;~l	. 2 Ma	d: 1	I 0)			

3/2/1 – indicates strength of correlation (3- High, 2- Medium, 1- Low)

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22CEM0	07	GREEN BUILDING TECHNOLOG	ING TECHNOLOGY Semest							
PRERE(QUISI	TES	Category	OE	OE Cre		3			
				L	Т	P	TH			
NIL		Hours/Week	3	0	0	3				
Course I	Learni	ng Objectives					I			
1 To	Know	various aspects of green buildings								
2 To	Learn	the principles of planning and orientation of buildings.								
3 То	Relate	the construction of green building with prevailing energy	conservation policy	and regu	lations					
4 To	Know	and identify different green building construction material	S.							
5 To	Learn	different rating systems and their criteria								
Unit	Ι	INTRODUCTION TO GREEN BUI	LDING	9	0	0	9			
	0. 0.0.	en Building, Components/ features of Green Building,	zneigj zmeienej	,		110), 1				
Efficiency ————	y, Indoo	r Air Quality.		T -			1 -			
Unit I	II tion, Sit	SITE SELECTION AND PLANNI e selection strategies, Landscaping, building form, orienta	tion, building envel	_			nateri			
Unit I	II tion, Sit ruction on, Rai	SITE SELECTION AND PLANNI	tion, building envel Environmental desig	ope and a	fenestra trategie	ation, m	nateri uildin			
Unit I	tion, Sitruction con, Rairecycle	SITE SELECTION AND PLANNI e selection strategies, Landscaping, building form, orienta techniques, roofs, walls, fenestration and shaded finishes, I nwater harvesting methods for roof & non-roof, reducin	tion, building envel Environmental desig ng landscape water	ope and a	fenestra trategie	ation, m	nateri uildir igatio			
Unit I Site select and construction systems, re Unit I	II tion, Sit ruction on, Rai recycle a	SITE SELECTION AND PLANNII e selection strategies, Landscaping, building form, orienta techniques, roofs, walls, fenestration and shaded finishes, I nwater harvesting methods for roof & non-roof, reducin and reuse systems, Waste Management.	tion, building envel Environmental designg landscape water	ope and agn (ED) s demand	fenestra trategie by pro	ation, mes for beoper irr	nateri uildin igatio			
Unit I Site select and construction systems, re Unit I	tion, Sitteruction, Con, Rairecycle a	SITE SELECTION AND PLANNI e selection strategies, Landscaping, building form, oriental techniques, roofs, walls, fenestration and shaded finishes, I nwater harvesting methods for roof & non-roof, reducing and reuse systems, Waste Management. ENERGY AND ENERGY CONSERVATION TO THE PROPERTY CONSERVATION TO	tion, building envel Environmental designg landscape water	ope and agn (ED) s demand	fenestra trategie by pro	ation, mes for beoper irr	uildir igatio			
Unit I Site select and construction systems, re Unit I Introduction	tion, Sitt ruction on, Rai recycle a	SITE SELECTION AND PLANNI e selection strategies, Landscaping, building form, oriental techniques, roofs, walls, fenestration and shaded finishes, I nwater harvesting methods for roof & non-roof, reducing and reuse systems, Waste Management. ENERGY AND ENERGY CONSERVATION TO THE PROPERTY CONSERVATION TO	tion, building envel Environmental designg landscape water VATION nario, Need of ener	ope and some (ED) some demand	fenestrategic by pro	ation, mes for be open irr	nateri uildin igatio			
Unit I Site select and construction systems, re Unit I Introduction embodied operationa	tion, Sittruction, Rair recycle at the conference on the conferenc	SITE SELECTION AND PLANNI e selection strategies, Landscaping, building form, oriental techniques, roofs, walls, fenestration and shaded finishes, I nwater harvesting methods for roof & non-roof, reducin and reuse systems, Waste Management. ENERGY AND ENERGY CONSERV vironmental impact of building constructions, present scen y and life cycle energy, Methods to reduce operational energy materials, wind and solar energy harvesting, energy meterin	tion, building envel Environmental designg landscape water VATION nario, Need of ener gy, Energy efficient	ope and a gn (ED) s demand	fenestrategic by pro	on, Conc	nateriuildinigatio			
Unit I Site select and construction systems, re Unit I Introduction embodied operationa	tion, Sitt ruction on, Rai recycle a recycle a recycle a recycle a renergy all energy (ODP) r	SITE SELECTION AND PLANNIS e selection strategies, Landscaping, building form, oriental techniques, roofs, walls, fenestration and shaded finishes, I nwater harvesting methods for roof & non-roof, reducing and reuse systems, Waste Management. ENERGY AND ENERGY CONSERVATION CO	tion, building envel Environmental designg landscape water VATION nario, Need of ener gy, Energy efficient	ope and a gn (ED) s demand	fenestrategic by pro	on, Conc	nateri naidin igation getts pletin dings			
Unit I Site select and construction systems, re Unit I Introduction embodied operationa potential (Unit I	tion, Sitt ruction on, Rai recycle a recycle and energy all energy (ODP) r	SITE SELECTION AND PLANNI e selection strategies, Landscaping, building form, oriental techniques, roofs, walls, fenestration and shaded finishes, I nwater harvesting methods for roof & non-roof, reducin and reuse systems, Waste Management. ENERGY AND ENERGY CONSERV vironmental impact of building constructions, present scen y and life cycle energy, Methods to reduce operational energy materials, wind and solar energy harvesting, energy meterin	tion, building envel Environmental designg landscape water VATION nario, Need of ener gy, Energy efficient and monitoring, contact and monitoring and monito	ope and a gn (ED) s demand 9 gy conservations building, concept of 9	fenestrategic by pro O ervation zero of net zero	one de ero buil	gation of the second of the se			
Unit I Site select and construction construction systems, re Unit I Introduction embodied operational potential (Unit I Green bui concrete for	tion, Sittruction on, Rairecycle at the conference of the conferen	SITE SELECTION AND PLANNII e selection strategies, Landscaping, building form, oriental techniques, roofs, walls, fenestration and shaded finishes, I nwater harvesting methods for roof & non-roof, reducin and reuse systems, Waste Management. ENERGY AND ENERGY CONSERY rironmental impact of building constructions, present scen y and life cycle energy, Methods to reduce operational energy materials, wind and solar energy harvesting, energy meterin BUILDING MATERIALS materials and products- Bamboo, Rice husk ash concrete, use of materials with recycled content such as blended cen	tion, building envel Environmental design landscape water VATION nario, Need of ener gy, Energy efficient and monitoring, of plastic bricks, Bagments, pozzolana ce	ope and a gn (ED) s demand 9 gy conservation of the servation of the serv	fenestra trategia by pro ervation zero or f net ze o yash by	one de ero buil oricks, v	pletindings			
Unit I Site select and construction systems, re Unit I Introduction embodied operational potential (Unit I Green bui concrete fettiles, mate	tion, Sittruction on, Rairecycle at the conference of the conferen	SITE SELECTION AND PLANNIS e selection strategies, Landscaping, building form, oriental techniques, roofs, walls, fenestration and shaded finishes, I nwater harvesting methods for roof & non-roof, reducing and reuse systems, Waste Management. ENERGY AND ENERGY CONSERVATION OF THE PROPERTY OF THE PRO	tion, building envel Environmental design landscape water VATION nario, Need of ener gy, Energy efficient and monitoring, of plastic bricks, Bagments, pozzolana ce	ope and a gn (ED) s demand 9 gy conservation of the servation of the serv	fenestra trategia by pro ervation zero or f net ze o yash b	one de ero buil oricks, v	pletindings			
Unit I Site select and construction systems, re Unit I Introduction embodied operational potential (Unit I Green built concrete for tiles, mate roofing.	tion, Site ruction from the control on the control	SITE SELECTION AND PLANNIE e selection strategies, Landscaping, building form, oriental techniques, roofs, walls, fenestration and shaded finishes, I nwater harvesting methods for roof & non-roof, reducing and reuse systems, Waste Management. ENERGY AND ENERGY CONSERVATION OF THE PROPERTY OF THE PRO	tion, building envel Environmental design landscape water VATION nario, Need of ener gy, Energy efficient and monitoring, of plastic bricks, Bagments, pozzolana ce	ope and a gn (ED) s demand 9 gy conservation of the servation of the serv	fenestrategic by pro O ervation zero of net zero O icle bo yash b Nontox	one de ero buil oricks, v	pletingsulaterifications			
Unit I Site select and construction systems, re Unit I Introduction embodied operational potential (Unit I Green bui concrete fettiles, mate roofing. Unit I	tion, Sitt ruction on, Rai recycle a recycle a renergy all energy (ODP) r r r r r r r r r r r r r r r r r r r	SITE SELECTION AND PLANNII e selection strategies, Landscaping, building form, oriental techniques, roofs, walls, fenestration and shaded finishes, I nwater harvesting methods for roof & non-roof, reducin and reuse systems, Waste Management. ENERGY AND ENERGY CONSERY Frommental impact of building constructions, present scen y and life cycle energy, Methods to reduce operational energy materials, wind and solar energy harvesting, energy meterin BUILDING MATERIALS materials and products- Bamboo, Rice husk ash concrete, use of materials with recycled content such as blended center to magro and industrial waste, reuse of waste material-Plastic RATING SYSTEM	tion, building envel Environmental design landscape water VATION nario, Need of ener gy, Energy efficient and monitoring, complete plastic bricks, Bagments, pozzolana cec, rubber, Newspape	ope and a gn (ED) s demand 9 egy conservations of the servation of the se	fenestrategic by pro orvation zero or f net zero over ticle bowyash by Nontox	one de ero buil o pard, Ingricks, vice paint	pletingsulate itrific			
Unit I Site select and construction systems, re Unit I Introduction embodied operational potential (Unit I Green bui concrete fi tiles, mate roofing. Unit I Introduction	tion, Sitt ruction on, Rain on, Rain on, Environment of the control of the contro	SITE SELECTION AND PLANNIE e selection strategies, Landscaping, building form, oriental techniques, roofs, walls, fenestration and shaded finishes, I nwater harvesting methods for roof & non-roof, reducing and reuse systems, Waste Management. ENERGY AND ENERGY CONSERVATION OF THE PROPERTY OF THE PRO	tion, building envel Environmental design landscape water VATION nario, Need of ener gy, Energy efficient and monitoring, of plastic bricks, Bagments, pozzolana cec, rubber, Newspape eria, Indian Green B	gy consession ope and some and	fenestrategic by pro O ervation zero or f net zero Nontox O ouncil	ation, mes for be open irrollogon, Concorded on the conco	nateriuildinigation of the sulation of the sul			
Unit I Site select and construction systems, re Unit I Introduction embodied operational potential (Unit I Green built concrete for tiles, mate roofing. Unit I Introduction Introduction rating, Green	tion, Sit ruction from, Rai recycle a recycle	SITE SELECTION AND PLANNIS e selection strategies, Landscaping, building form, oriental techniques, roofs, walls, fenestration and shaded finishes, I nwater harvesting methods for roof & non-roof, reducing and reuse systems, Waste Management. ENERGY AND ENERGY CONSERVATION FOR THE PROPERTY OF THE PLANNISH OF THE PL	tion, building envel Environmental design landscape water VATION nario, Need of ener gy, Energy efficient and monitoring, of plastic bricks, Bagments, pozzolana cec, rubber, Newspape eria, Indian Green B National Productivi	ope and a gn (ED) s demand 9 gy conservation of the properties of	fenestrategie by pro orvation zero or f net ze or icle bor yash br Nontox or ouncil iil (NPO) g) – Ce	ation, mes for be open irror on the concept of the	pleti ding: Grestry es.			

Te	ext Books:
	Kibert, C.J., Sustainable construction: Green Building design and Delivery, John Wiley Hobouken, NewJersey, 3rd
1	Edition, 2012.
2	Chauhan, D S Sreevasthava, S K., Non-conventional Energy Resources, New Age International Publishers, NewDelhi,
2	4 th Edition, 2021

Ref	Ference Books:
1	O.P. Gupta, Energy Technology, Khanna Publishing House, NewDelhi
2	Jagadeesh, K S, Reddy Venkatta Rama &Nanjunda Rao, K S., Alternative Building Materials and Technologies, New Age International Publishers, Delhi.
3	Sam Kubba., Handbook of Green Building Design and Construction, Butterworth- Heinemann.
4	Means R S, Green Building - Project Planning and Cost Estimating, John Wiley &Sons
5	Sharma K V, Venkataseshaiah P., Energy Management and Conservation, IK International.

	Course Outcomes: Upon completion of this course, the students will be able to:					
CO1	Understand the concepts of Green Building					
CO2	Discuss the Planning of Green Building.					
CO3	Explain the concept of Energy and Energy Conservation.					
CO4	Select appropriate green building material and technique.					
CO5	Summarize the Green Building Functions in various organizations.					

COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	-	-	-	1	-	2	3	-	-	-	2	1	2	-	-
CO2	1	1	1	2	1	-	-	-	-	-	-	-	2	-	-
CO3	-	1	3	-	2	•	-	•	•	•	1	-	2	-	-
CO4	-	1	2	-	3	•	-	•	ı	ı	2	-	2	-	-
CO5	1	1	2	3	2	•	-	ı	1		2	-	2	-	-
Avg	1	1	2	2	2	2	3	•	ı	•	2	1	2	-	-

3/2/1 – indicates strength of correlation (3- High, 2- Medium, 1- Low)

22CS	SM01	PROGRAMMING IN C++					
PREREQUIS		ITES	Category	OE	DE Credit		3
				L	Т	P	TH
			Hours/Week	3	0	0	3
Cours	e Learn	ing Objectives					
1	To und	erstand and develop the object oriented programming concepts					
2	To fam	iliarize and design the template functions and classes					
3	To diss	eminate and apply exception handling mechanisms.					
4	To lear	and exploit stream classes.					
Un	it I	INTRODUCTION		9	0	0	9
Uni	it II s and ob	INHERITANCE AND VIRTUAL FUNCTI giects - friend functions- constructors and destructors- Open ag member function and friend function - Type conversions.		9 – bina	0 ry and	0 unary o	9 operator
	t III	INHERITANCE AND VIRTUAL FUNCTI	IONS	9	0	0	9
		fining derived classes, types, virtual base classes, abstract classes, this pointer, pointer to derived classes - Virtual functions.	ses, constructor in	derived	classes	- Pointe	ers-
Uni	it IV	TEMPLATES AND EXCEPTION HANDI	LING	9	0	0	9
templat rethrow	tes with r ving an e	- class template, class templates with multiple parameters - Grantiple parameters, member function templates - Exception has exception - Exception handling options - understanding termination() function - bad_exception().	andling – basics, e	xception	n handli		
Un	it V	CONSOLE I/O AND FILE HANDLING		9	0	0	9
		asses – unformatted I/O operations, formatted console I/O ng and closing a file, detecting end of file, files modes, sequen	-				
				Tota	l (45 L	$=45\overline{1}$	Periods

Text	Text Books:						
1	E. Balagurusamy "Object -Oriented Programming with C++" Sixth Edition Tata McGraw-Hill						
Refer	Reference Books:						
1	Herbert Schildt, "The Complete Reference C++", Fifth Edition, Tata McGraw Hill						
2	Bjarne Stroustrup, "The C++ programming language", Fourth Edition Addison Wesley						
3	K.R.Venugopal, Rajkumar Buyya, T.Ravishankar, Mastering in C++, Second Edition, Tata McGraw Hill						

	se Outcomes: completion of this course, the students will be able to:	Bloom's Taxonomy Level
CO1	Build the object oriented programming concepts.	Apply
CO2	Familiarize and build the template functions and classes	Understand
CO3	Disseminate and apply exception handling mechanisms.	Apply
CO4	Depict and exploit steam classes.	Understand

22CS	SM02	ADVANCED DATA STRUCTURES AND ALG	GORITHMS				
PRER	EQUIS	ITES	Category	OE	Cre	edit	3
				L	Т	P	TH
			Hours/Week	3	0	0	3
Course	e Learn	ing Objectives					
1	To unde	To understand the concepts of ADTs					
2	To Lear	rn linear data structures – lists, stacks, and queues					
3	To have	knowledge about non-linear data structures like trees and grap	hs				
4	To unde	erstand concepts about searching and sorting and hashing techni	iques				
Uni	it I	LINEAR DATA STRUCTURES – LIST	Γ	9	0	0	9
	DT - Op	erations - Applications of Stacks - Evaluating Arithmetic Expre Operations - Circular Queue - DeQueue - Applications of Queue	ession - Conversio	9 n of infi	0 ix to pos	tfix Exp	9 pression
Unit	t III	NON LINEAR DATA STRUCTURES – TR	REES	9	0	0	9
	ed Binary	e traversals – Binary Tree ADT – Expression Trees – Application Trees – AVL Trees – B-Tree – Heaps - Operations of Heaps - I		-			
Min He		lications of Heap.					
Min Hea	t IV	lications of Heap. NON LINEAR DATA STRUCTURES – GRA	APHS	9	0	0	9
Unit Definition Applica	on – Rep	NON LINEAR DATA STRUCTURES – GRADIT Presentation of Graphs – Types of Graphs - Graph Traversals - Boraph Structures: Shortest Path Problem: Dijkstra's Algorithm -	Breadth First Searc	ch - Dep	oth First	Search	-
Unit Definition	on – Rep ation of C l's Algor	NON LINEAR DATA STRUCTURES – GRADIT Presentation of Graphs – Types of Graphs - Graph Traversals - Boraph Structures: Shortest Path Problem: Dijkstra's Algorithm -	Breadth First Searc Minimum Spann	ch - Dep	oth First	Search	-
Unit Definition Applica Kruskal Uni Searchin	on – Repation of Cal's Algor It V Ing: Linea	NON LINEAR DATA STRUCTURES – GRA bresentation of Graphs –Types of Graphs - Graph Traversals - Braph Structures: Shortest Path Problem: Dijkstra's Algorithm - ithms	Breadth First Search Minimum Spann HNIQUES Selection Sort - S	ch - Der ing Tre	oth First es: Prim 0 rt - Bubl	Search 's Algor	- rithm - 9 - Quicl

T	Text Books:					
1	Mark Allen Weiss, "Data Structures and Algorithm Analysis in C", 4/E Pearson Education, 2013.					
Re	Reference Books:					
1	Seymour Lipschutz, "Data Structures With C ",(Schaum`s Outline Series) Published by Tata McGraw-Hill Education Pvt. Ltd., 2015					
2	Ellis Horowitz, Sartaj Sahni, Dinesh Mehta, "Fundamentals of Data Structures In C", Second Edition, Silicon Press, 2008.					
3	Richard F.Gilberg & Behrouz A.Forouzan, "Data Structures: A Pseudo code Approach With C", Second Edition, Cengage Learning Publishers, 2005.					
4	Classic Data Structures", Second Edition by Debasis Samanta, PHI Learning, 2009.					

	Course Outcomes: Upon completion of this course, the students will be able to:	
CO1	Implement various abstract data types to solve real time problems by using Linear Data Structures	Apply
CO2	Apply the different Non-Linear Data Structures to solve problems	Apply
CO3	Analyze and implement graph data structures to solve various computing problems.	Analyze
CO4	Critically analyze the various sorting and searching algorithms	Analyze

22CSM03	COMPUTER ORGANIZATION AND DI	ESIGN				
PREREQUIS	ITES	Category	OE	Cre	edit	3
			L T	P	TH	
		Hours/Week	3	0	0	3
Course Learn	ing Objectives				<u> </u>	
1 To und	erstand the basic structure and operations of digital computer					
2 To lear	n the working of different arithmetic operations					
3 To und	erstand the different types of control and the concept of pipelini	ing				
4 To stud	y the hierarchical memory system including cache memory and	l virtual memory				
5 To und	erstand the different ways of communication with I/O devices a	and standard I/O in	nterfaces	S		
UNIT I	INTRODUCTION		9	0	0	9
	ARITHMETIC UNIT btraction of Signed Numbers, Design of Fast Adders, Multiplicating Point number operations.	ation of Positive N	9 Jumbers	0 s, Booth	0 Algorit	9 hm, Fa
UNIT III	PROCESSOR UNIT AND PIPELININ	G	9	0	0	9
	oncepts, Execution of Instruction, Multi Bus Organization, Hard of pipelining, Data Hazards, Instruction Hazards, Data path & 0		-	ogramm	ned cont	rol,
	MEMORY SYSTEMS	Control Considera	9	0	0	9
UNIT IV	WIEWOKT STSTEMS					
Basic Concepts	Semiconductor RAM, ROM, Cache memory, Improving Cacl quirements, Secondary Storage Device.	he Performance, V	/irtual r	nemory	,Memor	ry
Basic Concepts	Semiconductor RAM, ROM, Cache memory, Improving Cacl		irtual r	nemory	,Memor	9
Basic Concepts, Management re-	Semiconductor RAM, ROM, Cache memory, Improving Cacl quirements, Secondary Storage Device.	ON	9	0	0	9

Tex	t Books:				
1	Carl Hamacher V., Zvonko G. Vranesic, Safwat G. Zaky, "Computer organization", Tata McGraw Hill,5th Edition, 200				
Refe	Reference Books:				
1	Patterson and Hennessey, "Computer Organization and Design". The Hardware/Software interface, Harcourt Asia Morgan Kaufmann, 3rd Edition, 2007				
2	Hayes, "Computer Architecture and Organization", 3rd edition, Tata McGraw Hill, 2006				
3	Heuring V.P., Jordan H.F., "Computer System Design and Architecture ", 6th edition ,Addison Wesley,2008				

	se Outcomes: completion of this course, the students will be able to:	Bloom's Taxonomy Level
CO1	Understand the working principles of computer componets	Understand
CO2	Design the arithmetic and processing units	Create
CO3	Analyze the various computer components	Analyze

Course 1	QUISITES		2	Semeste	er	
		Category	OE	Cre	edit	3
		YY /XY/ 1	L	T	P	TH
		Hours/Week	3	0	0	3
1	Learning Objectives					
1	To understand the structure and functions of Operat	ing systems				
2	To understand the process concepts and scheduling	o understand the process concepts and scheduling algorithms				
3	To understand the concept of process synchronizat	ion and deadlocks				
4	To learn various memory management schemes					
5	To illustrate various file systems and disk managem	ent strategies				
UNIT I	INTRODUCTION AND OPERATIN	G SYSTEM STRUCTURES	9	0	0	9
Communi	-Process Concepts, Process Scheduling, Ope ecation; Threads- Multithreading Models, Threading g Algorithms.		_			
UNIT I		ON AND DEADLOCKS	9	0	0	9
	Synchronization- The Critical Section Problem, ization, Monitors; Deadlocks- Deadlock Character	rization, Methods for handling Dea				olem
Synchron	Avoidance ,Deadlock Detection, Recovery from De	eadlock.				ventio
Synchron			9	0	0	ventio 9
Synchron Deadlock UNIT I Memory		D VIRTUAL MEMORY S Memory Allocation, Paging, Seg				9
Synchron Deadlock UNIT I Memory	MEMORY MANAGEMENT AN Management- Background, Swapping, Contiguous irtual Memory - Demand paging, Page Replacement	D VIRTUAL MEMORY s Memory Allocation, Paging, Segut, Thrashing.				9
Synchroni Deadlock UNIT I Memory paging; V UNIT V File Syste Implement	MEMORY MANAGEMENT AN Management- Background, Swapping, Contiguous irtual Memory - Demand paging, Page Replacement	ID VIRTUAL MEMORY S Memory Allocation, Paging, Segut, Thrashing. FORAGE STRUCTURE Directory Structure, File Sharing, on, Directory Implementation, Allo	mentati 9 File Pocation	on, Seg 0 rotectio Metho	mentation 0 n; File ds, Free	9 on wi

Tex	t Books:
1	Abraham Silberschatz, P.B.Galvin, G.Gagne —Operating System Concepts 6th edition, John Wiley & Sons, 2003.
Refe	rence Books:
1	Andrew S. Tanenbaum, —Modern Operating Systems, PHI, 2nd edition, 2001
2	D.M.Dhamdhere, "Systems Programming and Operating Systems", 2nd edition, Tata McGraw Hill Company, 1999.
3	Maurice J. Bach, —The Design of the Unix Operating System, 1st edition, PHI, 2004.

	Course Outcomes: Upon completion of this course, the students will be able to:	
CO1	Identify the components and their functionalities in the operating system	Apply
CO2	Apply various CPU scheduling algorithms to solve problems	Apply
CO3	Analyze the needs and applications of process synchronization and deadlocks	Analyze
CO4	Apply the concepts of memory management including virtual memory and page replacement to the issues that occur in real time applications	Apply
CO5	Solve issues related to file system implementation and disk management	Apply

	DATA COMMUNICATION AND COMP NETWORKS	PUTER	S	Semeste	er	
PREREQUI		Category	OE	Cre	edit	3
			L	T	P	TH
		Hours/Week	3	0	0	3
Course Lear	ning Objectives					
1 To stu	dy the concepts of data communications and functions of differe	nt ISO/OSI refere	nce arcl	hitecture	e	
2 To un	derstand the error detection and correction methods and also the	types of LAN				
3 To stu	dy the concepts of subnetting and routing mechanisms					
4 To un	derstand the different types of protocols and congestion control					
5 To stu	dy the application protocols and network security					
UNIT I	DATA COMMUNICATIONS AND PHYSICAL	L LAYER	9	0	0	9
UNIT II	DATA LINK LAYER		9	0	0	9
Correction (V	ypes of errors, Redundancy, Detection versus Correction, Modula		ck Codi	ng-Erro	r Detec	tion one
	RC,LRC,CRC, Checksum, Hamming Code);Data link Control (Automatic Repeat Request, Stop-and-wait ARQ, Sliding Bus, Token Ring, FDDI.		rol (Sto	op- and	l-Wait,	Sliding
	Control (Automatic Repeat Request, Stop-and-wait ARQ, Slidin		rol (Sto	op- and	l-Wait,	Sliding
Ethernet, Toke UNIT III Network Lay	Control (Automatic Repeat Request, Stop-and-wait ARQ, Slidin n Bus, Token Ring, FDDI.	addresses-IPv6 ac	rol (Sto HDLC	op- and; Local A	l-Wait, Area Ne	Sliding etworks
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UNIT III Network Lay Gateways- Re UNIT IV Duties of the	Control (Automatic Repeat Request, Stop-and-wait ARQ, Sliding Bus, Token Ring, FDDI. NETWORK LAYER er services-Packet Switching-Network Layer Performance-IPv4 butters-Routing Algorithm-Distance Vector Routing, Link State Formance Proceedings (1988).	addresses-IPv6 acRouting.	y ddressin	op- and; Local A O g- Subr O Control	l-Wait, Area Ne	Sliding Stworks- 9 Bridges-
UNIT III Network Lay Gateways- Re UNIT IV Duties of the	Control (Automatic Repeat Request, Stop-and-wait ARQ, Sliding Bus, Token Ring, FDDI. NETWORK LAYER er services-Packet Switching-Network Layer Performance-IPv4 outers-Routing Algorithm-Distance Vector Routing, Link State F TRANSPORT LAYER Transport layer-User Datagram Protocol-Transmission Control	addresses-IPv6 ac Routing. 1 Protocol- Conge	y ddressin	op- and; Local A O g- Subr O Control	l-Wait, Area Ne	Sliding Stworks-
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UNIT III Network Lay Gateways- Re UNIT IV Duties of the Service-Conge	Recontrol (Automatic Repeat Request, Stop-and-wait ARQ, Sliding Bus, Token Ring, FDDI. NETWORK LAYER Per services-Packet Switching-Network Layer Performance-IPv4 outers-Routing Algorithm-Distance Vector Routing, Link State For TRANSPORT LAYER Transport layer-User Datagram Protocol-Transmission Controstion, Congestion Control, Quality of Service, Techniques to improve the presentation of the presentat	addresses-IPv6 ac Routing. 1 Protocol- Conge prove QoS, Integra	9 estion Cated Ser	op- and; Local A O g- Subn O Control vices.	l-Wait, Area Ne 0 netting-l and Qu 0 Web.	Sliding etworks 9 Bridges 9 ality of
UNIT III Network Lay Gateways- Ro UNIT IV Duties of the Service-Conge	Recontrol (Automatic Repeat Request, Stop-and-wait ARQ, Sliding Bus, Token Ring, FDDI. **NETWORK LAYER** **Preservices-Packet Switching-Network Layer Performance-IPv4 outers-Routing Algorithm-Distance Vector Routing, Link State For TRANSPORT LAYER **Transport layer-User Datagram Protocol-Transmission Controlstion, Congestion Control, Quality of Service, Techniques to impresent the state of	addresses-IPv6 ac Routing. 1 Protocol- Conge prove QoS, Integra	9 estion Cated Ser	op- and; Local A Control vices. O d Wide	l-Wait, Area Ne 0 netting-l and Qu 0 Web.	Sliding etworks by Sliding stworks by Sliding stwor

	se Outcomes: completion of this course, the students will be able to:	Bloom's Taxonomy Level
CO1	Classify the fundamentals of data communications and functions of layered architecture	Understand
CO2	Apply the error detection and correction methods and also identify the different network technologies	Apply
CO3	Analyze the requirements for a given organizational structure and select the most appropriate networking architecture and routing technologies	Analyze
CO4	Illustrate the transport layer principles and reliable data transfer using protocols	Apply
CO5	Analyze the application layer protocols and also the use of network security	Analyze

22CS	SM06	PROGRAMMING ESSENTIALS IN PY	THON	Semester			
PRER	EQUIS	ITES	Category	OE Credit			3
				L T P			ТН
			Hours/Week	3	0	0	3
Course	e Learn	ing Objectives					
1	To lear	n Python data structures, conditional and control structures and	d files				
2	To stud	y Python Modules, packages, Functions and Exceptions.					
3	To desc	ribe Object oriented programming features and Regular Expre	essions.				
4	To lear	n about Web programming, GUI Programming and Database p	orogramming				
UNIT	Π	INTRODUCTION		9	0	0	9
		s - The Basics-Python Objects-Numbers-Sequences-Mapping a lif-Conditional Expressions-while statement-for statement-bre		litionals	and loo	ps-if sta	itement-
UNI	TII	FUNCTIONS, MODULES AND PACKA	GES	9	0	0	9
		ng functions-Creating functions-Passing Functions-Formal n, Modules-Packages.	Arguments-Variat	ole leng	gth argi	ıments-	variable
UNIT	ı III	FILES AND EXCEPTIONS		9	0	0	9
		Output –Errors and Exceptions-Introduction-Detecting and haertions-Standard Exceptions.	andling Exceptions	-Contex	t Mana	gement-	Raising
UNIT	ΓΙ	OBJECT ORIENTED PROGRAMMING AND EXPRESSIONS	REGULAR	9	0	0	9
		d Programming Introduction-Classes-class Attributes-Insta				-	
		c methods and class Methods-Inheritance-Operator overloadin rogramming	ig - Regular Expres	sions-IN	etwork	Progran	nmıng –
UNIT		ADVANCED TOPICS		9	0	0	9
GUI Pro	ogrammi	ng- Web Programming-Database Programming					
				Tota	ıl (45 L) =45 I	Periods
					•	-	
Text	t Books	:					
1	Wesley	J.Chun-"Core Python Programming" –Prentice Hall, Second F	Edition, 2006.				
Refer	rence B	ooks:					
1	Swaroo	op C N, "A Byte of Python ", ebshelf Inc., 1st Edition, 2013					
2	"A Pra	ctical Introduction to python programming", Brian Heinold,M	ount St.Mary's Un	iversity	,2012		

Cours	Bloom's Taxonomy Level	
CO1	Develop programs using control structures and files.	Create
CO2	Create own Python Modules, packages, functions and Exceptions.	Create
CO3	Illustrate Object oriented Programming features and Regular Expressions.	Apply
CO4	Create own Web programs, GUI and database programs.	Create

Learning to Program with Python," Richard L. Halterman"., Southern Adventist University

22CS	SM07	ADVANCED DATABASE SYSTEM COM	NCEPTS	S			
PRER	EQUIS	ITES	Category	OE Credit			3
			** /** 1	L T P			TH 3
			Hours/Week	3			
Course	e Learn	ing Objectives					L
1	To unde	erstand the fundamentals of data models ,SQL queries and rela	ational databases				
2	To mak	e a study of database design using ER Diagram and normalize	;				
3	To impa	art knowledge in transaction processing.					
4	To mak	e the students to understand the file operations and indexing					
5	To fami	iliarize the students with advanced databases					
UNIT	ΓI	RELATIONAL DATABASES		9	0	0	9
Non-los	Relations ss Decom Depende	DATABASE DESIGN hip model – E-R Diagrams – Enhanced-ER Model – ER-to-Inposition – First, Second, Third Normal Forms, Dependency Fincies and Fourth Normal Form – Join Dependencies and Fifth TRANSACTION	Preservation – Boyo				
Protoco	ols – Two	cepts – ACID Properties – Schedules – Serializability – Concu o Phase Locking – Deadlock – Transaction Recovery – Sav d Recovery.					
UNIT	ΓIV	IMPLEMENTATION TECHNIQUE	S	9	0	0	9
B tree loperation	Index Fil ons – Qu	ganization – Organization of Records in Files – Indexing and les – Static Hashing – Dynamic Hashing – Query Processing ery optimization using Heuristics and Cost Estimation.		rithms 1	for SEL	ECT an	d JOIN
UNIT	Γ \mathbf{V}	ADVANCED TOPICS		9	0	0	9
Object- Schema	Relationa , XQuer	bases: Architecture, Data Storage, Transaction Processing – Olal features, ODMG Object Model, ODL, OQL – XML Day – Data Warehousing and Data Mining - information Retrievativel Models, Queries in IR systems.	tabases: XML Hie				
				Tota	1 (45 L) =45 I	Periods

Tex	at Books:
1	Abraham Silberschatz, Henry F.Korth and S.Sundarshan "Database System Concepts", Sixth Edition, Tata McGraw Hi 2011.
Refe	erence Books:
1	Ramez Elamassri and Shankant B-Navathe, "Fundamentals of Database Systems", Sixth Edition, Pearson Education, 2011.
2	C.J. Date, "An Introduction to Database Systems", Eighth Edition, Pearson Education Delhi, 2008.
3	Raghu Ramakrishnan, —Database Management Systems, Fourth Edition, McGraw-Hill CollegePublications, 2015.
4	G.K.Gupta,"Database Management Systems", Tata McGraw Hill, 2011.

E-Ref	ferences:
1.	Lecture Series on Database Management System by Dr.S.Srinath, IIIT Bangalore, nptl

	Course Outcomes: Upon completion of this course, the students will be able to:	
CO1	Understand the basic concepts of the database and data models.	Understand
CO2	Design a database using ER diagrams and map ER into Relations and normalize the relations.	Create
CO3	Develop a simple database for applications	Create

	SM08	VIRTUALIZATION AND CLOUD COME	PUTING	S	Semeste	er	
PRER	EQUIS	ITES	Category	OE	Cro	edit	3
				L T P 3 0 0		P	TH
			Hours/Week			0	3
Course	e Learn	ing Objectives					
1	To int	roduce the broad perceptive of Parallel Computing, Distributed	Computing and C	Cloud C	omputin	ıg.	
2	To uno	derstand the concept of Virtualization					
3	To ide	ntify the approaches of SLA and programming model in Cloud	1				
4	To uno	derstand the Cloud Platforms in Industry and Software Environ	ments.				
5	To lea	rn to design the trusted Cloud Computing system					
UNIT	ГΙ	INTRODUCTION		9	0	0	9
Compu	ting; Vis	allel and Distributed Computing – Elements of Parallel and Dist ion of Cloud, Defining a Cloud, characteristics and benefits; C Clouds, Open Challenges.					
UNI	II II	VIRTUALIZATION		9	0	0	9
UNIT		nd Cloud computing, Pros and cons of Virtualization, Technoloon.	ogy examples-Xen	ı: Para v	/irtualiza	ation, V	Mware:
	ГШ	SLA MANAGEMENT IN CLOUD COMPUTI PROGRAMMING MODEL	ING AND	9	0	0	9
Traditio	Γ III onal App	SLA MANAGEMENT IN CLOUD COMPUTI	ING AND LA, SLA Manage	9	0	0	9
Traditio	onal App	SLA MANAGEMENT IN CLOUD COMPUTI PROGRAMMING MODEL roaches to SLA Management, Types of SLA, Life Cycle of S.	ING AND LA, SLA Manage nming Model.	9	0	0	9
Tradition Computer UNIT	Onal Apporting - Teo	SLA MANAGEMENT IN CLOUD COMPUTE PROGRAMMING MODEL roaches to SLA Management, Types of SLA, Life Cycle of St. Chnologies for Data Intensive Computing, MapReduce Program CLOUD INDUSTRIAL PLATFORMS AND SO	ING AND LA, SLA Manage nming Model. DFTWARE e; Cloud Softwar	9 ment in	0 Cloud;	O Data In	9 ntensive
Tradition Computer UNIT	onal App ating - Teo F IV Platform bebula; An	SLA MANAGEMENT IN CLOUD COMPUTE PROGRAMMING MODEL roaches to SLA Management, Types of SLA, Life Cycle of Schnologies for Data Intensive Computing, MapReduce Program CLOUD INDUSTRIAL PLATFORMS AND SO ENVIRONMENTS s in Industry - Amazon Web Service, Google App Engine	LA, SLA Manage nming Model. DFTWARE e; Cloud Software, Anatomy of Ane	9 ment in	0 Cloud;	O Data In	9 ntensive
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Tradition Compute UNITE Cloud OpenNote UNITE An Intra Security	Onal Appointing - Teo Γ IV Platform ebula; An r V roduction y Risk, C	SLA MANAGEMENT IN CLOUD COMPUTI PROGRAMMING MODEL roaches to SLA Management, Types of SLA, Life Cycle of St. Chnologies for Data Intensive Computing, MapReduce Program CLOUD INDUSTRIAL PLATFORMS AND SO ENVIRONMENTS s in Industry - Amazon Web Service, Google App Engine neka Cloud Application Platform-Aneka Framework Overview CLOUD SECURITY AND APPLICATION To the Idea of Data Security, The Current State of Data Security and Identity, Id	ING AND LA, SLA Manage nming Model. DFTWARE e; Cloud Software, Anatomy of Ane DNS curity in the Cloud	9 ment in 9 e Envirka Con 9	O Cloud; O Compevel Sec	O Data In O O O O O O O O O O O O O O O O O O	9 alyptus, 9 al Data Pros and
Cloud OpenNo UNIT An Intr Security Cons; C	Onal Apporting - Tector Γ IV Platform (ebula; An Γ V) roduction y Risk, C Cloud Sci	SLA MANAGEMENT IN CLOUD COMPUTING PROGRAMMING MODEL roaches to SLA Management, Types of SLA, Life Cycle of Stannologies for Data Intensive Computing, MapReduce Program CLOUD INDUSTRIAL PLATFORMS AND SOME ENVIRONMENTS in Industry - Amazon Web Service, Google App Engine neka Cloud Application Platform-Aneka Framework Overview CLOUD SECURITY AND APPLICATION to the Idea of Data Security, The Current State of Data Security and Identity; The Cloud, Digital Identity, and entific Applications.	ING AND LA, SLA Manage nming Model. DFTWARE e; Cloud Software, Anatomy of Ane DNS curity in the Cloud	9 ment in 9 e Envirka Con 9	O Cloud; O Compevel Sec	O Data In O O O O O O O O O O O O O O O O O O	9 alyptus, 9 al Data Pros and
Tradition Compute UNIT	TIII onal App ting - Tec ΓIV Platform febula; An ΓV roduction y Risk, C Cloud Sci t Books: Rajkuma	SLA MANAGEMENT IN CLOUD COMPUTING PROGRAMMING MODEL roaches to SLA Management, Types of SLA, Life Cycle of Stannologies for Data Intensive Computing, MapReduce Program CLOUD INDUSTRIAL PLATFORMS AND SOME ENVIRONMENTS in Industry - Amazon Web Service, Google App Engine neka Cloud Application Platform-Aneka Framework Overview CLOUD SECURITY AND APPLICATION to the Idea of Data Security, The Current State of Data Security and Identity; The Cloud, Digital Identity, and entific Applications.	ING AND LA, SLA Manage nming Model. DFTWARE e; Cloud Softwar , Anatomy of Ane DNS curity in the Cloud Data Security, Co	9 re Envirka Con 9 d, Cloucontent L	o Cloud; o Cloud; o Competationer. o Compevel Second (45L)	Data In O as –Euc o o curity, F	9 alyptus, 9 alyptus and Data Pros and

102	t Dooks.				
1	Rajkumar Buyya, Christian Vecchiola, S.Tamarai Selvi, 'Mastering Cloud Computing-Foundations and Applications Programming", TMGH,2013.(Unit- I,II & IV)				
2	RajKumar Buyya, James Broberg, Andrezei M.Goscinski, "Cloud Computing: Principles and paradigms",2011(Unit-III & V)				
Reference Books:					
1	Kai Hwang.GeoffreyC.Fox.JackJ.Dongarra, "Distributed and Cloud Computing, From Parallel Processing to The Internet of Things", 2012 Elsevier				
2	Barrie Sosinsky, "Cloud Computing Bible", Wiley Publisher, 2011				

Cours	Bloom's Taxonomy Level	
CO1	Explain the main concepts and architecture of Parallel computing, Distributed Computing and Cloud Computing.	Understand
CO2	Analyze the concept of Virtualization	Analyze
CO3	Identify the approaches of SLA and programming model in Cloud	Apply
CO4	Analyze the Cloud Platforms in Industry and Software Environments.	Analyze
CO5	Identify the security issues in scientific and real time applications.	Apply

PREREQUISITES CATEGORY OE Crutter Hours/Week L T P 3 0 0 Course Objectives: 1. To introduce components such as diodes, BJTs and FETs, their characteristics and applications 2. To understand, analyse and design of simple diode and transistor circuits. 3. To know the switching characteristics of components and the concept of rectifiers and power supplies Unit I EXTRINSIC SEMICONDUCTOR AND PN JUCTIONS 9 0 N and P type semiconductor and their energy band structures. Law of electrical neutrality-calculation of location of level and free electron and hole densities in extrinsic semiconductors-Mobility, drift current and conductivity-diff current-continuity equation- Hall effect and its applications. Band structure of PN junction – current component in junction- derivation of diode equation-temperature dependence of diode characteristics and equivalent models. Unit II SWITCHING CHARACTERISTICS OF PN JUNTION AND SPECIAL DIODES 9 0 Calculation of transition and diffusion capacitance- varactor diode-charge control description of diode-switcharacteristics of diode- mechanism of avalanche and Zener breakdown-temperature dependence of breakdown volbackward diode-tunneling effect in thin barriers - tunnel diode-photo diode-light emitting diodes. Unit II BIPOLAR JUNCTION TRANSISTORS 9 0 Construction of PNP and NPN transistors- BJT current components-emitter to collector and base to collector cagains-base width modulation CB, CE and CC characteristics- breakdown characteristics- Ebers-Moll model - transwitching times- Photo translator. Unit IV FIELD EFFECT TRANSISTORS 9 0	
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Unit II SWITCHING CHARACTERISTICS OF PN JUNTION AND SPECIAL DIODES OF Calculation of transition and diffusion capacitance- varactor diode-charge control description of diode-switch characteristics of diode- mechanism of avalanche and Zener breakdown-temperature dependence of breakdown volbackward diode-tunneling effect in thin barriers - tunnel diode-photo diode-light emitting diodes. Unit III BIPOLAR JUNCTION TRANSISTORS 9 0 Construction of PNP and NPN transistors- BJT current components-emitter to collector and base to collector capains-base width modulation CB, CE and CC characteristics- breakdown characteristics- Ebers-Moll model - transwitching times- Photo translator. Unit IV FIELD EFFECT TRANSISTORS 9 0	
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characteristics of diode- mechanism of avalanche and Zener breakdown-temperature dependence of breakdown volbackward diode-tunneling effect in thin barriers - tunnel diode-photo diode-light emitting diodes. Unit III BIPOLAR JUNCTION TRANSISTORS 9 0 Construction of PNP and NPN transistors- BJT current components-emitter to collector and base to collector agains-base width modulation CB, CE and CC characteristics- breakdown characteristics- Ebers-Moll model - transwitching times- Photo translator. Unit IV FIELD EFFECT TRANSISTORS 9 0	ching
Unit III BIPOLAR JUNCTION TRANSISTORS Construction of PNP and NPN transistors- BJT current components-emitter to collector and base to collector control gains-base width modulation CB, CE and CC characteristics- breakdown characteristics- Ebers-Moll model - transwitching times- Photo translator. Unit IV FIELD EFFECT TRANSISTORS 9 0	
Construction of PNP and NPN transistors- BJT current components-emitter to collector and base to collector control gains-base width modulation CB, CE and CC characteristics- breakdown characteristics- Ebers-Moll model - translation times- Photo translator. Unit IV FIELD EFFECT TRANSISTORS 9 0	
gains-base width modulation CB, CE and CC characteristics- breakdown characteristics- Ebers-Moll model - transwitching times- Photo translator. Unit IV FIELD EFFECT TRANSISTORS 9 0	0 9
gains-base width modulation CB, CE and CC characteristics- breakdown characteristics- Ebers-Moll model - transwitching times- Photo translator. Unit IV FIELD EFFECT TRANSISTORS 9 0	irrent
Unit IV FIELD EFFECT TRANSISTORS 9 0	
C / / 11 / / C CEPER 1/ 1/ 1/ C 1/ 11/ 11/ 2/ 2/COPE	0 9
Construction and characteristics of JFET-relation between pinch off voltage and drain current derivation. MOSF	ETS -
enhancement and depletion types. CMOS circuits. MOS capacitance, BICMOS, SOI CMOS.	
Unit V RECTIFIERS AND POWER SUPPLIES 9 0	0 9
Half-wave, full-wave and bridge rectifiers with resistive load. Analysis for Vdc and ripple voltage with C, CL, L-	and
C-L-C filters. Voltage multipliers Zener diode regulator. Electronically regulated d.c power supplies. Line regulated	ition,
output resistance and temperature coefficient.	
Total (45L)= 45 Pc	riods

Text	Books:
1.	JaconMillman& Christos C. Halkias, "Electronic Devices and Circuits" Tata McGraw-Hill, 1991.
2.	Robert L. Boylestad and Louis Nashelsky, "Electronic Devices and Circuit Theory 8th edition.", PHI, 2002
Refe	rence Books:
1.	Donald A. Neaman. "Semiconductor Physics and Devices" 3rd Ed., Tata McGraw-Hill 2002
2.	S. Salivahanan, N. Suresh kumar and A. Vallavaraj, Electronic Devices and Circuits, TMH, 1998.
3.	Ben, G. Streetman and Sanjay Banerjee, Solid State Electronic Devices, Pearson Education 2000
4.	Floyd, "Electronic Devices", Sixth edition, Pearson Education, 2003.
E-Re	ferences:
1.	https://archive.nptel.ac.in/courses/108/108/108108122/
2.	https://www.youtube.com/watch?v=qqQ8wO-lNmI
3.	https://slideplayer.com/slide/12438044/

Course	Bloom's					
Upon	Upon completion of this course, the students will be able to:					
		Mapped				
CO1	Interpret various applications of diode.	Applying				
CO2	Classify various configurations and biasing technique of BJT	Applying				
CO3	Apply the knowledge of using special devices for various applications	Understanding				
CO4	Discuss operation, biasing and applications of JFET.	Analysing				
CO5	Design power supplies and rectifiers	Applying				

					COL	JRSE .	ARTI	CULA	TION	MATR	X				
COs/POs	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	PSO1	PSO2	PSO3
	1	2	3	4	5	6	7	8	9	10	11	12			
CO1	2	2	1	ı	-	-	-	-	ı	ı	ı	-	1	-	ı
CO2	2	2	1	-	-	-	-	-	-	-	-	-	2	-	-
CO3	2	2	1	-	-	-	-	-	-	-	-	-	3	-	-
CO4	2	2	1	1	-	-	-	-	1	1	1	-	2	2	1
CO5	2	2	1	-	-	-	-	-	-	-	-	-	3	2	2
Avg	2	2	1	-	-	-	-	-	-	-	-	-	2.2	2	1.5
		3	3/2/1 -	indica	ates sti	ength	of cor	relatio	on (3-F	ligh,2- N	Mediun	1,1- Lo	ow)		

	CM02	DIGITAL ELECTRONICS					
PRE	REQU	JISITES	CATEGORY	OE	Cre	dit	3
				L	T	P	TH
			Hours/Week	3	0	0	3
Cou	rse Ob	jectives		<u> </u>	II.		
1	To in	troduce basic postulates of boolean algebra and show the cor	relation between	expression	ons		
2	To In	troduce the methods for Simplifying Boolean expressions					
3	To O	utline the formal procedures for the analysis and design of co	ombinational circ	uits and s	equent	ial cir	cuits
4	To in	troduce the Concept of Memories and programmable logic de	evices				
5	To ill	ustrate the concept of synchronous and Asynchronous sequen	ntial circuits				
Unit	I	NUMBER SYSTEMS AND LOGIC GATES			9	0	0 9
Nıın	nber Sv	ystems - signed Binary numbers - Binary Arithmetic - Binary	codes -conversi	on from o	ne coo	le to a	nothe
	gn proc	cedure – Adders/Subtractor – Serial adder/ Subtractor - Paralle exer - encoder / decoder – code converters.	el adder/ Subtracto	or- BCD	9 adder-		0 9 plexe
Desi	gn proc ultiple		el adder/ Subtract	or- BCD		Multi	
Designment	gn procultiples III gn Procu	cedure – Adders/Subtractor – Serial adder/ Subtractor - Paralle xer - encoder / decoder – code converters.	Flip-flop - Reali	zation of	adder- 9 flip flo	Multi	plexe 0 Moor
Designment	gn procultiples III gn Proc Mealy - ters- U	cedure – Adders/Subtractor – Serial adder/ Subtractor - Paralle exer - encoder / decoder – code converters. SEQUENTIAL CIRCUITS cedure - Flip flops: SR, JK, T, D and JKMS – Triggering of – Counters: Asynchronous / Ripple counters – Synchronous	Flip-flop - Reali	zation of	adder- 9 flip flo	Multi ops – egiste	plexe 0 Moor
Designment	gn procultiples III gn Proc Mealy - ters- U IV gn of f nment. nmic H	cedure – Adders/Subtractor – Serial adder/ Subtractor - Parallel exer - encoder / decoder – code converters. SEQUENTIAL CIRCUITS cedure - Flip flops: SR, JK, T, D and JKMS – Triggering of – Counters: Asynchronous / Ripple counters – Synchronous / niversal shift register. ASYNCHRONOUS SEQUENTIAL CIRCUITS fundamental mode circuits – primitive state / flow table – Problems in Asynchronous Circuits: Cycles – Races – Haz fazards elimination	Flip-flop - Reali counters – Modu Minimization of	zation of alo n cou	g flip floater. R	Multipops – egiste	plexe Moor r: shi -stat
Designed Interest Designed Int	gn procultiples III gn Proc Mealy - ters- U IV gn of f nment. nmic H	cedure – Adders/Subtractor – Serial adder/ Subtractor - Paralle exer - encoder / decoder – code converters. SEQUENTIAL CIRCUITS cedure - Flip flops: SR, JK, T, D and JKMS – Triggering of – Counters: Asynchronous / Ripple counters – Synchronous / niversal shift register. ASYNCHRONOUS SEQUENTIAL CIRCUITS fundamental mode circuits – primitive state / flow table – Problems in Asynchronous Circuits: Cycles – Races – Haz	Flip-flop - Reali counters – Modu Minimization of	zation of alo n cou	g flip floater. R	Multipops – egiste table cuits:	plexe Moor r: shi -stat
Designed Interest Designed Int	gn procultiples III gn Proc Mealy - ters- U IV gn of f nment. amic H V 1	cedure – Adders/Subtractor – Serial adder/ Subtractor - Parallel exer - encoder / decoder – code converters. SEQUENTIAL CIRCUITS cedure - Flip flops: SR, JK, T, D and JKMS – Triggering of – Counters: Asynchronous / Ripple counters – Synchronous / niversal shift register. ASYNCHRONOUS SEQUENTIAL CIRCUITS fundamental mode circuits – primitive state / flow table – Problems in Asynchronous Circuits: Cycles – Races – Haz fazards elimination PLD AND MEMORY DEVICES on of memories –RAM organization –ROM organization. Programmable Array Logic (PAL). Implementation	Flip-flop - Reali counters – Modu Minimization of ards. Design of I	zation of ilo n cou primitiv Hazard F	flip floater. R g e state ree Cir	Multipops – egiste table cuits:	plexe Moor r: shi static mable

Text Bo	ooks:					
1	M. Morris Mano, Digital Design, 4.ed., Pearson Education (Singapore) Pvt. Ltd., New Delhi, 2008					
2	R.P.Jain, Modern Digital Electronics, 4 th edition, TMH, 2010.					
Referen	nce Books:					
1	S. Salivahanan and S. Arivazhagan, Digital Circuits and Design, 2 nd ed., Vikas Publishing House Pvt. Ltd, New Delhi, 2004					
2	Charles H.Roth. "Fundamentals of Logic Design", Thomson Publication Company, 2003.					
3	Donald P.Leach and Albert Paul Malvino, Digital Principles and Applications, 5 ed., Tata McGraw Hill Publishing Company Limited, New Delhi, 2003.					
4	John F.Wakerly, Digital Design: Principles and practices, PHI, 2006					
E-Reference:						
1	http://nptel.ac.in/noc/individual_course.php?id=noc15-ec01					
2	https://nptel.ac.in/courses/117105080/6					

3	https://nptel.ac.in/courses/117105080/12
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	Outcomes: upletion of this course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Minimize Boolean expressions and implement using logic gates	Applying
CO2	Design and analyse combinational logic circuits.	Analysing
CO3	Design and analyse synchronous and asynchronous sequential logic circuits	Analysing
CO4	Understand the concepts of memories and PLDs	Understanding
CO5	Implement circuits using memory and PLDs.	Applying

				C	OURSI	E ART	TCUL	ATIO	N MA	TRIX					
COs/POs	PO	PO	PO	PO4	PO	PO	PO	PO	PO	PO	PO	PO	PSO	PSO	PSO
	1	2	3		5	6	7	8	9	10	11	12	1	2	3
CO1	3	2	2	2	3	2	3	2	-	-	-	-	2	1	-
CO2	3	3	2	2	3	3	2	1	1	-	-	-	3	2	-
CO3	2	2	3	3	2	1	2	1	1	-	-	-	2	2	-
CO4	2	1	2	1	2	2	3	1	-	1	-	ı	2	1	-
CO5	2	1	2	1	3	2	1	2	-	-	-	1	3	2	-
Avg	2.4	1.8	2.2	1.8	2.6	2	2.2	1.4	1	1	-	1	2.4	1.6	-
		3/2	/1 - ir	ndicates	streng	th of c	orrela	tion (3	8-High	,2- Med	ium,1-	Low)	·		

PREI	CM03	ELECTRONIC CIRCUITS					
	REQU.	ISITES	CATEGORY	OE	Cre	dit	3
Floor	non Do		II orreg/XV o ole	L	T	P	TH
Liecu	ron De	vices	Hours/Week	3	0	0	3
Cour	se Obj	ectives		<u>I</u>		1	
1	То ре	erform analysis on Small signal amplifiers and large sign	al amplifiers.				
2	To gi	ve a comprehensive exposure to all types of discrete amp	olifiers and oscillators	.			
3	To ur	derstand the various linear and non-linear applications of	of op-amp				
Uni	it I	MIDBAND ANALYSIS OF SMALL SIGNAL AM	PLIFIERS	9	0	0	9
emitte Uni	er coup it II	sing Darlington connection and bootstrapping. CS, CG a led differential amplifier circuit. Differential gain - CMR LARGE SIGNAL AMPLIFIERS cy & High frequency analysis of amplifiers -Hybrid – pi e	R. Use of constant cur	rrent circ	uit to im	nprove 0	e CMRR 9
Calcu their r and tr power power	llation or relation or ansformer outpur on the control of the cont	Trs. Gain-bandwidth product of FETs. General expression of overall upper and lower cut off frequencies of multistate to cut off frequencies. Classification of amplifiers (Classification of amplifiers) (Classification) of the complementary-st, efficiency and power dissipation. Crossover distortion in grapacity of transistors with and without heat sink. He	age amplifiers. Ampl s A, B, AB, C&D), Eff ymmetry, push-pull p and methods of elim	ifier rise ficiency o ower am inating it	time an of class plifiers. . Calcul	d sag A, RC Calcu ation	time and coupled lation of of actua
Unit		OSCILLATORS			9 0	Ŭ	9
Feed	ilizatio	Amplifier: Block diagram - Gain with feedback - Barkhau n of amplitude - Analysis of Oscillator using Cascade	connection of RC ar	nd LC fil			
stabi Osci Mille	er and	Wien bridge Oscillator and Twin-T Oscillators - Analy Pierce oscillators - Frequency range of RC Oscillators - I	Electrical equivalent o	circuit of	s – Ha Crystal	rtley -	ase shif - Clapp
stabi Osci Mille	er and	· ·	Electrical equivalent o	circuit of	s – Ha Crystal	rtley -	ase shif - Clapp
stabi Osci Millo Unit Analy of Cla	er and t IV ysis of s ass C tu ble Mu	Pierce oscillators - Frequency range of RC Oscillators - In TUNED AMPLIFIERS AND MULTIVIBRATORS and the single tuned and synchronously tuned amplifiers - Class and Amplifier - Collector coupled and Emitter coupled Alti vibrator - Triggering methods – Mono stable and A	Electrical equivalent of S C tuned amplifiers and astable Multi vibrator astable Blocking Osci	d their ap	cs — Har Crystal 9 0 plication stable N	rtley - 0 ns - E Multi v	ease shift clapp of the shift o
stabi Osci Millo Unit Analy of Cla Bistab	er and to the total tota	Pierce oscillators - Frequency range of RC Oscillators - I TUNED AMPLIFIERS AND MULTIVIBRATORS single tuned and synchronously tuned amplifiers - Class Caned Amplifier- Collector coupled and Emitter coupled Amplifier-	Electrical equivalent of S C tuned amplifiers and astable Multi vibrator astable Blocking Osci	d their ap Mono Illators us	cs — Har Crystal 9 0 plication stable N	ns - E	ease shift clapp of the shift o
stabi Osci Millo Unit Analy of Cla Bistab timing Uni Basic design Differ	er and t IV ysis of s ass C tu ble Mu g. tit V structu n - DC rentiato	Pierce oscillators - Frequency range of RC Oscillators - In TUNED AMPLIFIERS AND MULTIVIBRATORS and the single tuned and synchronously tuned amplifiers - Class and Amplifier - Collector coupled and Emitter coupled Alti vibrator - Triggering methods – Mono stable and A	Electrical equivalent of S C tuned amplifiers and astable Multi vibrator stable Blocking Osci CATIONS Tial gain - Common Merting and non-inverting and its applications	d their ap — Mono Illators us Mode gai ing ampl ons - Ac	Crystal Crystal O O O O O O O O O O O O O O O O O O O	ns - E Multi v nitter 0 RR - 0 Integ	9 fficiency and base 9 OP-AMI rator and assertion and base 19

Text Books:

1 B.Visvesvara Rao, K.Raja Rajeswari, P.Chalam Raju Pantulu, K.Bhaskara Rama Murthy, "Electronic Circuits-II", Pearson Education,2012

2 D.Roy Choudhry, Shail Jain, "Linear Integrated Circuits", New Age International Pvt. Ltd., 2011.

Reference Books:

1 Millman J. and Taub H., "Pulse Digital and Switching waveform", 3rd Edition, McGraw-Hill International , 2011.

2 Sedera& Smith, "Micro Electronic Circuits", 4 th Edition, Oxford University Press, Chennai.

3	Michael Jacob, 'Applications and Design with Analog Integrated Circuits', Prentice Hall of India, 1996.
4	K.R.Botkar, 'Integrated Circuits', 10th edition, Khanna Publishers, 2010.
e-Ref	ference:
1	http://nptel.ac.in/courses/117105080/40
2	http://nptel.ac.in/courses/117108038/1
3	https://freevideolectures.com/course/2915/linear-integrated-circuits

Cour	se Outcomes:	Bloom's Taxonomy
Upon	completion of this course, the students will be able to:	Mapped
CO1	To analyze small signal amplifiers and Large signal Amplifiers.	Applying
CO2	Analyze the frequency response characteristics of amplifiers	Applying
CO3	Develop insight of on oscillator design.	Applying
CO4	Construct and analyse tuned amplifiers and multivibrators.	Applying
CO5	Develop competence in linear and nonlinear Op amp circuit analysis.	Applying

	COURSE ARTICULATION MATRIX														
COs/PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	PSO	PSO	PSO
S	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	2	2	1	2	-	-	-	-	1	1	-	-	1	2	1
CO2	3	2	1	2	-	-	-	-	-	ı	ı	-	1	2	1
CO3	3	2	1	2	-	-	-	-	1	1	-	-	1	2	1
CO4	3	2	1	2	-	-	-	-	-	ı	1	-	1	2	1
CO5	1	2	1	2	-	-	-	-	1	ı	1	-	1	2	1
Avg	2.4	2	1	2	-	-	-	-	-	ı	-	-	1	2	1
	3/2/1 - indicates strength of correlation (3-High,2- Medium,1- Low)														

22ECM04	SIGNAL PROCESSING					
PREREQUISI	ΓES	CATEGORY	OE	Cree	dit	3
		Hanna/Wash	L	Т	P	TH
		Hours/Week	3	0	0	3
G 01: 4:			3	0	0	

Course Objectives:

- 1. To understand and perform Fourier and Laplace analysis on signals and systems respectively.
- 2. To analyse the Discrete Fourier Transform, Fast Fourier Transform algorithms.
- 3. To design and realize IIR, FIR filters.

Unit I INTRODUCTION TO SIGNALS AND SYSTEMS

9 0 0 9

Classification of Signals: Even and Odd Signal - Energy and power signals - Continuous time (CT) and Discrete time (DT) signals - Continuous and Discrete amplitude signal -. System properties and representation: linearity - Tme-invariance - Causality - Stability - Realizability. - Linear Time-Invariant (LTI) systems: Impulse response and step response - Convolution - Correlation - System representation through differential equations and difference equations.

Unit II ANALYSIS OF SIGNAL AND SYSTEMS

9 0 0 9

Introduction to Fourier Transform, Fourier Series, Relating the Laplace Transform to Fourier Transform, Frequency response of continuous time systems. Introduction to z- Transform.

Unit III DISCRETE FOURIER TRANSFORM

9 0 0 9

Introduction to DFT – Properties of DFT - Circular convolution - FFT algorithms – Radix-2 FFT algorithms – Decimation in Time and Decimation in Frequency algorithms.

Unit IV INFINITE IMPULSE RESPONSE FILTER DESIGN

9 0 0 9

Characteristics of Analog Butterworth filter - Chebyshev filter - Low pass filter, High pass filter, Band pass filter and Band stop filter - Transformation of analog filters in to equivalent digital filters using bilinear transformation method - Realization structure for IIR filters-Direct form - Cascade form - Parallel form.

Unit V FINITE IMPULSE RESPONSE FILTER DESIGN

9 0 0 9

Linear phase response of FIR filter - FIR design using window method: Rectangular, Hamming, Hanning and Blackmann Windows - Park-McClellan's method - Realization structures for FIR filters - Linear phase structures and Direct form structure - Comparison of FIR and IIR filters.

Total (45L)= 45 Periods

Text Books:

- 1. A.Anand Kumar, "Signals and Systems", 3rd Edition, PHI, 2013.
- 2. John G Proakis and Manolakis, "Digital Signal Processing Principles, Algorithms and Applications", 4th Edition, Pearson Education, 2009.

Reference Books:

- 1. Alan V Oppenheim, Alan S Willsky and S Hamid Nawab, "Signals and Systems", 2nd edition, PHI Learning Private Limited, New Delhi, 2010.
- 2. B.P. Lathi, "Principles of Signal Processing and Linear Systems", Oxford University Press, 2009.
- 3. Emmanuel C. Ifeacher, Barry W. Jervis, "Digital Signal Processing: A Practical Approach", 2nd Edition, Pearson Education, 2004.
- 4. S.K. Mitra, "Digital Signal Processing, A Computer Based approach", 4th Edition, McGraw-Hill, 2010.

E-References:

- 1. http://nptel.ac.in/courses/117104074/
- 2. https://www.coursera.org/learn/dsp
- 3. https://ocw.mit.edu/resources/res-6-008-digital-signal-processing-spring-2011/

	e Outcomes: completion of this course, the students will be able to:	Bloom's Taxonomy
Сроп	completion of this course, the students will be able to.	Mapped
CO1	Analyse and understands different types of signals.	Analysing
CO2	Represent continuous signals and systems in time and frequency domain using different transforms.	Analysing
CO3	Analyse the need for Discrete Fourier Transform, Fast Fourier Transform algorithms in digital signals & systems.	Analysing
CO4	Design and realize IIR filters.	Applying
CO5	Design and realize FIR filters.	Applying

COURSE ARTICULATION MATRIX															
COs/POs	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	РО	PSO1	PSO2	PSO3
	1	2	3	4	5	6	7	8	9	10	11	12			
CO1	3	2	3	3	3	-	-	-	-	-	-	-	2	2	2
CO2	3	2	2	3	3	2	-	-	-	-	-	-	2	2	2
CO3	3	2	2	2	1	-	1	-	-	-	-	-	1	1	1
CO4	3	2	2	2	1	-	1	-	-	1	-	-	1	1	1
CO5	1	1	1	1	1	-	-	-	-	-	-	-	2	2	1
Avg	2.6	1.8	2	2.2	1.8	2	1						1.6	1.6	1.4
	3/2/1 - indicates strength of correlation (3-High,2- Medium,1- Low)														

22ECM05	5 FUNDAMENTALS OF MICROPRO	CESSORS AND MICRO	CONTRO	LLER	S	
PREREQ	UISITES	CATEGORY	OE	Cred	lit	3
			L	T	P	TH
		Hours/Week	3	0	0	3
Course Ol	ojectives:		l		1	
1.	To familiarise with 8086 and 8051 architectures.					
2.	To interface 8086 microprocessor and 8051 microco	ontrollers with peripherals b	y program	ming.		
3.	To gain basic knowledge of PIC microcontrollers.	• •	<u> </u>			
	<u> </u>					
Unit I	8086 MICROPROCESSOR ARCHITECTURE			9	0	9
Overview	of Microcomputer systems-8086 Architecture – Pin A	Assignments – Internal Arch	itecture –	Addres	sing r	nodes-
Instruction	Formats- Directives and Operators-Assembly process	SS.			Ū	
Unit II	PROGRAMMING AND INTERFACING OF 80	86		9	0	9
Fundamen	tal I/O considerations- Programmed I/O- Interrupt I/O	- Basic 8086 Configurations	s- Minimuı	n Mode	e-Max	ximum
Mode-Syst 8251 USA	rem Bus timing- I/O Interfaces-Peripheral Interfacin RT.	g using 8255 PPI - 8279 F	Keyboard/I	Display	conti	roller -
Unit III	8051 ARCHITECTURE			9	0	9
8051 archi — Address	tecture - Registers in 8051 - Pin description - 8051 psing modes	parallel I/O ports - memory	organizati	on - In	struct	ion set
Unit IV	PROGRAMMING AND INTERFACING OF 80	51		9	0	9
	language programming.8051Timers - Serial Port Prog s - ADC, DAC and Sensor Interfacing - Motor Contro		amming - l	LCD an	d Ke	yboard
Unit V	PIC MICROCONTROLLERS			9	0	9
	acteristics of PIC microcontrollers – PIC microcont Instruction set and timers in PIC	roller families-Memory-Pro	ogram Mei	nory –	RAN	1 Data
			Total	$\overline{(L+T)}$ =	= 45 p	periods

Text B	Books:							
1.	Yu-Cheng Liu, Glenn A. Gibson," Microcomputer Systems, The 8086/8088 Family", Pearson, 2e, 2019.							
2.	Muhammad Ali Mazidi, Janice GillispieMazidi, RolinD.McKinlay, "The 8051 Microcontroller and Embedded							
۷.	Systems using Assembly and C", 2e, 2022.							
Refere	ence Books:							
1.	Mohamed Ali Mazidi, Janice GillispieMazidi, RolinMcKinlay, "The 8051 Microcontroller and Embedded							
1.	Systems: Using Assembly and C", 2nd Edition, Pearson education, 2011.							
2.	Martin Bates,"PIC Microcontrollers-An Introduction to Microelectronics", 3e, Elsevier, 2011.							
3.	Mathur Sunil,"Microprocessor 8086: Architecture, Programming and Interfacing" PHI Learning Pvt. Ltd. 2011.							
4.	Salvador PinillosGimenez," 8051 Microcontrollers Fundamental Concepts, Hardware, Software and							
4.	Applications in Electronics", Springer 2019.							
E-Refe	erences:							
1.	Ashraf Almadhoun,"A Detailed Look Into PIC Microcontroller and Its Architecture", Amazon 2020.							
2.	https://nptel.ac.in/courses/108105102							
3.	http://www.satishkashyap.com/2012/02/video-lectures-on-microprocessors-and.html							

Cour	rse Outcomes:	Bloom's Taxonomy
Upor	completion of this course, the students will be able to:	Mapped
CO1	Describe and analyse the architecture of 8086 microprocessor and 8051	Remembering
	architectures.	
CO2	Develop assembly language programs and Interface peripherals with 8086.	Applying
CO3	Develop assembly language programs and Interface peripherals with 8051.	Applying
CO4	Determine application specific circuit for real-time applications.	Understanding
CO5	Associate appropriate PIC microcontroller for a given application.	Understanding

	COURSE ARTICULATION MATRIX														
COs/POs	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	PSO	PSO	PSO3
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	
CO1	2	2	-	-	-	-	-	-	-	-	2	-	1	-	-
CO2	2	2	2	2	-	-	-	-	-	ı	-	-	2	2	-
CO3	2	2	2	2	-	-	-	-	-	ı	-	-	2	2	1
CO4	2	2	2	2	-	-	-	-	-	ı	-	-	2	2	2
CO5	2	2	-	2	-	-	-	-	-	ı	-	-	2	2	1
Avg	2	2	2	2	-	-	-	-	-	-	2	-	1.8	2	2

22ECN	106	ANALOG AND DIGITAL COMMUNICA	TION				
PRERI	EQUIS	ITES	CATEGORY	OE	Cre	dit	3
			Hours/Week	L	Т	P	TH
			nours/ week	3	0	0	3
Course	Objec	tives:					
1.	Under	stand analog and digital communication techniques.					
2.	Learn	data and pulse communication techniques.					
3.	Be fan	niliarized with source and Error control coding.					
Unit I	I	NFORMATION THEORY				9 0	0 9
		formation and entropy — Source coding theorem — Shannon nannels — Mutual information — Channel capacity — Channel		Huffman	coding	g – D	iscret
Unit II		ANALOG COMMUNICATION			٩	9 0	0 9
		of Noise - External Noise- Internal Noise- Noise Calculation					
		Types – Need for Modulation. Theory of Amplitude Modu					
	ques – ' FM – P	Theory of Frequency and Phase Modulation – Comparison M).	of various Anal	og Comn	nunıcat	10n S	Systen
Unit II	I	DIGITAL COMMUNICATION			9	9 0	0 9
		ft Keying (ASK) – Frequency Shift Keying (FSK) Minimum					
		 X – QPSK – 8 PSK – 16 PSK – Quadrature Amplitude Miciency – Comparison of various Digital Communication Systems 					AM ·
Danuw	iulii Ell	iciency– Comparison of various Digital Communication Sys	ACH (ACA) IIIJIS	- LOK -	- QAM	١)٠	
Unit IV	V	PULSE COMMUNICATION AND MULTIPLE ACC	ESS TECHNIQU	ES	9	9 0	0 9
		nication: Pulse Amplitude Modulation (PAM) – Pulse Time parison of various Pulse Communication System (PAM –	,	,			

Unit	V	ERR	OR (CON	TRO	L COI	DING						9	0	0	9
· ·	- 1 1		~	-1.		~		•		 • •	 4.	_	 -			

Linear block codes - Cyclic codes - Convolution codes - Maximum likelihood decoding of convolutional codes - Sequential decoding of convolutional codes - Trellis codes - Applications.

Total (45L)= 45 Periods

Text	Books:
1.	Simon Haykin, "Communication Systems", 4th Edition, John Wiley & Sons, 2014.
2.	J.G.Proakis, M.Salehi, —Fundamentals of Communication Systems, Pearson Education 2014.
Refe	erence Books:
1.	B.P.Lathi, —Modern Digital and Analog Communication Systems, 4th Edition, Oxford University Press, 2013.
2.	D.Roody, J.Coolen, —Electronic Communications, 4th edition PHI 2015.
3.	B.Sklar, —Digital Communications Fundamentals and ApplicationsII, 5th Edition Pearson Education 2017
4.	H P Hsu, Schaum Outline Series - —Analog and Digital Communications TMH, 5th edition 2006
E-Re	eferences:
1.	https://onlinecourses.nptel.ac.in/noc21_ee74/preview
2.	https://nptel.ac.in/courses/117101051
3.	https://www.digimat.in/nptel/courses/video/117105143/L51.html

FDMA, CDMA, TDMA, SDMA.

		Outcomes: mpletion of this course, the students will be able to:	Bloom's Taxonomy Mapped
CO	:	Apply the concepts of Random Process to the design of Communication	Applying
CO	:	Apply analog and digital communication techniques.	Applying
CO	:	Understand the use of data and pulse communication techniques.	Understanding
CO	:	Analyze Source and Error control coding.	Analysing
CO	:	Design AM communication systems and Angle modulated communication	Applying

	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO 10	PO 11	PO1 2	PSO 1	PSO 2	PSO 3
CO1	2	3	2	1	1	-	-	-	-	-	-	-	3	-	-
CO2	3	2	2	1	1	-	-	-	-	-	-	-	3	2	1
CO3	2	2	2	3	1	-	-	-	-	-	-	-	3	2	-
CO4	1	1	2	1	2	-	-	-	-	-	-	-	2	3	-
CO5	1	1	2	2	2	-	-	-	-	-	-	-	2	3	1
Avg	1.8	1.8	2	1.6	1.4	-	-	-	-	-	-	-	2.6	2.5	1
		•	3/2/	/1 - indi	icates st	rength o	of corre	lation (3	3-High,2	2- Medi	um,1- L	ow)	•	•	

22ECM07	COMMUNICATION NETWORKS							
PREREQUISI	TES	CATEGORY	OE	3				
			L	Т	P	TH		
		Hours/Week	3	0	0	3		
Course Object	ives:							
1. Understand	the division of network functionalities into layers.							
	with the components required to build different types of ne	tworks						
	to the required functionality at each layer							
4. Learn the f	low control and congestion control algorithms							
Unit I FU	NDAMENTALS & LINK LAYER			9	0	0 9		
Overview of Data Communications- Networks - Building Network and its types- Overview of Internet - Protocol								
Layering - OSI Mode - Physical Layer - Overview of Data and Signals - introduction to Data Link Layer - Link layer								
	or Detection and Correction					1		
	EDIA ACCESS & INTERNETWORKING			9		0 9		
	ata link Control and Media access control - Ethernet (802.3	*						
	netooth Low Energy – WiFi – 6LowPAN–Zigbee - Networ	k layer services –	Packet S	witchi	ng –	IPV4		
	ork layer protocols (IP, ICMP, Mobile IP)							
	OUTING			9		0 9		
	ast Routing – Algorithms – Protocols – Multicast Routing at		erview of	Intrad	oma	in and		
	tocols – Overview of IPv6 Addressing – Transition from IP	Pv4 to IPv6						
	ANSPORT LAYER			9		0 9		
	Transport layer –Protocols- User Datagram Protocols (UDP							
	tures – TCP Connection – State Transition Diagram – Flow	, Error and Conges	stion Con	trol - (Cong	estion		
	Cbit, RED) – QoS – Application requirements							
	PLICATION LAYER			9		0 9		
	yer Paradigms – Client Server Programming – World Wic							
	IMAP, MIME) – Introduction to Peer to Peer Networks – N	Need forCryptograp	ohy and I	Vetwor	k Se	curity		
– Firewalls.								
			Total (4	45L)=	45 P	eriods		

Text	Books:
1.	Behrouz A Forouzan, Data Communications and Networking, 4th Edition, 2020
2	James F. Kurose, Keith W. Ross, Computer Networking - A Top-Down Approach Featuring the Internet,
2.	Seventh Edition, Pearson Education, 2016.
Refe	rence Books:
1.	Nader. F. Mir, "Computer and Communication Networks", Pearson Prentice Hall Publishers, 2nd Edition, 2014.
2.	Alberto Leon-Garcia, IndraWidjajaCommunication Networks 2nd Edition McGraw-Hill Education, 2003
3.	Ying-Dar Lin, Ren-Hung Hwang, Fred Baker, "Computer Networks: An Open Source Approach", McGraw Hill
	Publisher, 2011.
4.	Larry L. Peterson, Bruce S. Davie, "Computer Networks: A Systems Approach", Fifth Edition, Morgan
	Kaufmann Publishers, 2011.
E-Re	eferences:
1.	https://onlinecourses.nptel.ac.in/noc22_ee61/preview
2.	https://www.ee.iitb.ac.in/~sarva/courses/EE706/2012/EE706LecNotes.pdf
3.	http://www.cs.kent.edu/~farrell/net01/lectures/

	completion of this course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Explain the basic concept in modern data communication and different level of layers in the protocol	Understanding
CO2	Analyse the functions and services of data link layer	Analysing
CO3	Categorize the functions and services of network layer	Understanding
CO4	Examine the basic functions of transport layer and congestion in networks	Understanding
CO5	Analyse the concepts of various network applications and data security	Analysing

	COURSE ARTICULATION MATRIX														
COs/POs	PO	PO	PO	PO	PO5	PO	PO	PO	PO	PO	РО	PO	PSO1	PSO2	PSO3
	1	2	3	4		6	7	8	9	10	11	12			
CO1	2	1	1	-	1	-	1	-	1	-	ı	-	2	-	1
CO2	2	1	2	-	1	-	1	-	1	-	ı	-	2	1	1
CO3	2	1	1	-	-	-	1	-	-	-	1	-	3	1	2
CO4	3	2	1	-	2	-	1	-	1	-	ı	-	2	-	2
CO5	2	1	1	-	1	-	-	-	-	1	1	-	1	1	1
Avg	2.2	1.2	1.2	-	1.25	-	-	-	-	-	ı	-	2	1	1.4
	3/2/1 - indicates strength of correlation (3-High,2- Medium,1- Low)														

Cour	REQUIS	ITES	CATEGORY	OE	Cr	edit		3
				OE		Credit		
			Hours/Week	L	7	Γ	P	TH
			Hours/ week	3	()	0	3
1	rse Objec	tives	-1		<u> </u>	I		
	To under	stand Smart Objects and IoT Architectures						
2	To learn	about various IOT-related protocols						
3	To build	simple IoT Systems using Arduino and Raspberry	Pi					
4	To under	stand data analytics and cloud in the context of Io	Γ					
5	To develo	op IoT infrastructure for popular applications						
U	nit I	FUNDAMENTALS OF IOT		9)	0	0	9
IoT A 802.1 Netw Appl	15.4e, 190 vorks – O	IoT PROTOCOLS echnologies: Physical and MAC layers, topologol.2a, 802.11ah and LoRaWAN – Network Layer: ptimizing IP for IoT: From 6LoWPAN to 6Lo, Reansport Methods: Supervisory Control and Data A	IP versions, Constra Couting over Low P	IEEE 8 ained No ower an	des and Los	nd C sy N	Consti Vetwo	raine orks
	nit III	DESIGN AND DEVELOPMENT			9	0	0	9
bloc	_	odology - Embedded computing logic - Microcornino - Board details, IDE programming - Raspberg.	•	•		•		
Ur	nit IV	DATA ANALYTICS AND SUPPORTING S	ERVICES		9	0	0	9
Datal Anal	bases – I ytics – X	Unstructured Data and Data in Motion Vs Data is Hadoop Ecosystem – Apache Kafka, Apache Spively Cloud for IoT, Python Web Application Fwith NETCONF-YANG	ark – Edge Stream	ning Ana	alytics	s and	d Ne	twor
	nit V	CASE STUDIES/INDUSTRIAL APPLICAT	TIONS		9	0	0	9
Uı		em - IBM Watson IoT platform – Manufacturing	Converged Planty		4 1	N / L	a1 (C	'DT

Text Books:

David Hanes, Gonzalo Salgueiro, Patrick Grossetete, Rob Barton and Jerome Henry, —IoT Fundamentals: Networking Technologies, Protocols and Use Cases for Internet of Things, Cisco Press, 2017

2 ArshdeepBahga, Vijay Madisetti, —Internet of Things – A hands-on approachl, Universities Press, 2015

Reference Books:

Olivier Hersent, David Boswarthick, Omar Elloumi, —The Internet of Things – Key applications and Protocols, Wiley, 2012 (for Unit 2).

Jan Ho" ller, VlasiosTsiatsis, Catherine Mulligan, Stamatis, Karnouskos, Stefan Avesand. David Boyle,
"From Machine-to-Machine to the Internet of Things - Introduction to a New Age of Intelligence",
Elsevier, 2014.

3	Dieter Uckelmann, Mark Harrison, Michahelles, Florian (Eds), —Architecting the Internet of Thingsl, Springer, 2011.							
4	Michael Margolis, Arduino Cookbook, Recipes to Begin, Expand, and Enhance Your Projects, 2nd Edition, O'Reilly Media, 2011.							
E-Re	E-References:							
1	https://online.stanford.edu/courses/xee100-introduction-internet-things							
2	https://www.udemy.com/topic/internet-of-things/							
3	https://www.netacad.com/courses/iot							

Course	Outcomes:	Bloom's
Upon co	ompletion of this course, the students will be able to:	Taxonomy Mapped
CO1	Explain the concept of IoT.	Understanding
CO2	Analyze various protocols for IoT.	Applying
CO3	Design a PoC of an IoT system using Rasperry Pi/Arduino	Applying
CO4	Apply data analytics and use cloud offerings related to IoT.	Applying
CO5	Analyze applications of IoT in real time scenario	Analysing

	COURSE ARTICULATION MATRIX														
COs/PO	PO	PO	PO	PO	PO	PO	PO	PO	РО	PO	PO	PO	PSO	PSO	PSO
S	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	2	1	2	1	1	1	1	ı	-	ı	1	-	2	2	2
CO2	2	1	2	1	1	1	1	ı	-	ı	1	-	2	2	2
CO3	2	2	3	2	1	1	1	ı	-	ı	2	-	2	2	2
CO4	2	2	2	1	1	1	1	ı	-	ı	1	-	2	2	2
CO5	2	2	3	2	1	1	1	ı	-	ı	2	-	2	2	2
Avg	2	1.6	2.4	1.4	1	-	-	-	-	ı	1.4	-	2	2	2
		3/	/2/1 -	indica	tes str	ength	of cor	relatio	n (3-H	igh,2- N	l edium	,1- Lo	w)		

22ECM09	WIRELESS SENSORS AND NETWORK	ING					
PREREQUISIT	TE:	CATEGORY	OE	Cre	Credit		
		TT /XX71-	L	Т	P	ТН	
		Hours/Week	3	0	3		
Course Objecti	ves:						
	indamental of Ad hoc network and architecture						
	and the MAC and routing protocols.						
	in-depth knowledge on QoS, security and sensor network p	latforms					
	OUTING PROTOCOLS			9	0 (0 9	
Elements of Ad	hoc Wireless Networks, Issues in Ad hoc wireless networks,	Example commercial	cial applic	ations	of A	d hoc	
	hoc wireless Internet, Issues in Designing a Routing						
	of Routing Protocols, Table Driven Routing Protocols – Dest						
On-Demand Ro	uting protocols -Ad hoc On-Demand Distance Vector Rout	ing (AODV).					
Unit II A	RCHITECTURES OF WSN			9	0 (0 9	
WSN application	n examples, Types of applications, Challenges for Wireless	Sensor Networks,	Enabling [Гесhn	ologie	es for	
Wireless Sensor	Networks, Single-Node Architecture: Hardware Compone	ents, Energy Const	umption o	f Sens	or N	odes,	
	ns and execution environments						
	ecture: Sensor Network Scenarios, Optimization goals and	figures of merit, D	esign prii	nciples	of V	VSN,	
	es of WSNs, gateway concepts.			1		1	
	MAC PROTOCOLS AND ROUTING PROTOCOLS			9		0 9	
	ion: Predictive techniques – PCM – DPCM - DM - Transform						
	s - Study of EZW. Video compression: Video signal repres						
	ding – The MPEG-1 Video Standard - The MPEG-2 Video	Standard: H.262	- ITU-T R	Recom	mend	lation	
H.263.		TVOLUCIUM ON THE				<u> </u>	
	QUALITY OF SERVICE AND ADVANCED APPLICA			9		0 9	
	ce: Coverage and deployment, Reliable data transport, Single						
	control - Advanced application support: Advanced in-net	work processing,	Security a	ind Ap	plica	atıon-	
specific support.						0 0	
	ENSOR NETWORK PLATFORMS AND TOOLS	1 1 0	1	9		$0 \mid 9$	
	ardware – Berkeley Motes, Programming Challenges, Nod						
	Node-level Simulators – NS2 and its extension to sensor	networks, COOJA	, TOSSIN	ı, Pro	gram	mıng	
beyond individu	al nodes – State centric programming.		TD 4 1 / 4	~T \	4.5 D	• 1	
			Total (4:) = 4	45 Pe	eriods	

Text Books:									
1.	C. Siva Ram Murthy, and B. S. Manoj, "AdHoc Wireless networks", Pearson Education – 2008								
2.	Holger Karl and Andreas Willig, "Protocols And Architectures for Wireless Sensor Networks", John Wiley,								
2.	2007.								
Refer	Reference Books:								
1.	Feng Zhao and LeonidesGuibas, "Wireless sensor networks", Elsevier publication - 2004.								
2.	Charles E. Perkins, —Ad Hoc Networking, Addison Wesley, 2000.								
3.	William Stallings, "Wireless Communications and Networks", Pearson Education – 2004								
4.	I.F. Akyildiz, W. Su, Sankarasubramaniam, E. Cayirci, "Wireless sensor networks: a survey", Computer								
	Networks, Elsevier, 2002, 394 - 422.								
E-Re	ferences:								
1.	https://nptel.ac.in/courses/106105183								
2.	https://nptel.ac.in/courses/106105183								
3.	https://archive.nptel.ac.in/courses/106/105/106105160/								

	Course Outcomes: Upon completion of this course, the students will be able to						
CO1	Know the basics of Ad hoc networks and Wireless Sensor Networks	Understanding					
CO2	Have a knowledge on architecture of Wireless Sensor Networks	Applying					
CO3	Apply the knowledge to identify MAC and routing protocols	Applying					
CO4	Understand the transport layer and security issues possible in Ad hoc and sensor networks	Understanding					
CO5	Be familiar with the OS used in Wireless Sensor Networks and build basic modules	Remembering					

	COURSE ARTICULATION MATRIX														
COs/POs	PO	РО	PO	PO	PO	РО	РО	РО	PO	PO	РО	PO	PSO	PSO2	PSO3
COS/FOS	1	2	3	4	5	6	7	8	9	10	11	12	1	1302	1303
CO1	3	3	1	3	3	3	2	-	-	-	3	3	3	-	2
CO2	3	3	2	3	3	3	2	-	-	-	3	3	3	-	2
CO3	3	3	3	3	3	3	2	-	-	-	3	3	3	-	2
CO4	3	3	2	3	3	3	2	-	-	-	2	3	3	-	2
CO5	3	3	2	3	3	3	2	-	-	-	3	3	3	-	2
Avg	3	3	2	3	3	3	2	-	-	-	2.8	3	3	_	2
			3/2/	1 - ind	licates	stren	gth of	correl	ation	(3-Higl	h,2- Me	edium,	l-Low)		·

22E	CM10		FUNDAMENTALS OF EMBEDI	DED SYSTEMS					
PRE	REQU	JISITES		CATEGORY	OE	(Credi	t	3
M			(miles controllers	Hours/Week	L	7	r	P	TH
MICI	oproce	essors and n	Mmicrocontrollers	Hours/ week	3	()	0	3
Cou	rse Ob	jectives							
1	To in	npart know	ledge on embedded system architecture and embed	lded development S	Strategie	es			
2	To u	nderstand tl	ne bus Communication in processors and periphera	l interfacing					
3	To u	nderstand b	asics of Real Time Operating System				•		
UNI	ΤI	BASICS	OF EMBEDDED SYSTEMS			9	0	0	9
	gn Life	e Cycle - Se	ges - Recent Trends in Embedded Systems - Arc election Process - Hardware Software Partitioning - Y MANAGEMENT AND INTERRUPTS				s - E	mbe	gadec
Men	norv A	_		lethods - DMA – M	emory		Ŭ	Ŭ	
Vs I	nterrup	ccess Proce	dure - Types of Memory - Memory Management Monday of Interrupts - Interrupt Latency - Interrupt Prior			Interf	acing	g - Po	olling
Vs I Inter	nterrup	ccess Proce ots - Types ervice Rout	dure - Types of Memory - Memory Management Monday of Interrupts - Interrupt Latency - Interrupt Prior			Interf	acing	g - Po	olling
Vs I Inter	nterrupt Se T III facing	ccess Proce ots - Types ervice Rout COMMU Buses - Se	dure - Types of Memory - Memory Management M of Interrupts - Interrupt Latency - Interrupt Pricines	ority – Programma	ble Into	Interferrup	facing t Cor	g - Pontroll	olling ers -
Vs I Inter	nterrupt Se T III facing A - Eth	ccess Proce ots - Types ervice Rout COMMU Buses - Se ernet - IEE	dure - Types of Memory - Memory Management Months of Interrupts - Interrupt Latency - Interrupt Pricines UNICATION INTERFACES Erial Interfaces - RS232/UART - RS422/RS485 - 1	ority – Programma	ble Into	Interferrup	facing t Cor	g - Pontroll	olling ers -
Vs I Inter UNI Inter IRD. UNI Real Sche	rupt Se T III facing A - Eth T IV -Time duling	ccess Proce ots - Types ervice Rout COMMU Buses - Se ernet - IEE REAL TI Concepts Event Dr	dure - Types of Memory - Memory Management Months of Interrupts - Interrupt Latency - Interrupt Pricines INICATION INTERFACES Berial Interfaces - RS232/UART - RS422/RS485 - EE 802.11 - Bluetooth	I2C Interface - SPI	Interfa	Interferrup	facing t Cor O USB O Cloo	g - Pontroll 0 - C. 0	olling ers - 9 AN -
Vs I Inter UNI Inter IRD. UNI Real Sche	nterrupt Set III facing A - Eth IIV - Time duling Task (ccess Proce ots - Types ervice Rout COMMU Buses - Se ernet - IEE REAL TI Concepts Event Dr Communica	dure - Types of Memory - Memory Management Months of Interrupts - Interrupt Latency - Interrupt Pricines INICATION INTERFACES Brial Interfaces - RS232/UART - RS422/RS485 - EE 802.11 - Bluetooth IME OPERATING SYSTEMS Task Management - Task Scheduling - Classificativen Scheduling - Resource Sharing - Priority Inhology	I2C Interface - SPI	Interfa	Interferrup	facing t Cor O USB O Cloo	g - Pontroll 0 - C. 0	olling ers - 9 AN -
Vs I Inter UNI Inter IRD. UNI Real Sche Inter UNI Host - Rei	rupt Se T III facing A - Eth T IV -Time duling Task 0 T V and T mote I	ccess Proce ots - Types ervice Rout COMMU Buses - Se ernet - IEE REAL TI Concepts Event Dr Communica VALIDA arget Mach Debuggers a	dure - Types of Memory - Memory Management Months of Interrupts - Interrupt Latency - Interrupt Pricines INICATION INTERFACES Brial Interfaces - RS232/UART - RS422/RS485 - EE 802.11 - Bluetooth IME OPERATING SYSTEMS Task Management - Task Scheduling - Classificativen Scheduling - Resource Sharing - Priority Inhemion - Mutex - Semaphores - Message Queues - Ti	tion of Scheduling aeritance Protocol - mers - Commercial ag - Host-Based Tesalyzer – Backgrour	Algoriting Send Debu	Interferrupt 9 ace - 9 hms - y Cei . 9 tup -	acing t Cor USB Clook ling l Targe ode -	g - Potentroll 0 - C. 0 Protect 0	9 AN 9 river ocol 9

Text	Books:
1	Sriram V Iyer and Pankaj Gupta, —Embedded Real-time Systems Programmingl, Tata McGraw-Hill Publishing Company Limited, New Delhi, 2006.
2	Arnold S Berger, —Embedded Systems Design - An Introduction to Processes, Tools and Techniques, Elsevier, New Delhi, 2011.
Refe	rence Books:
1	Prasad K V K K, —Embedded/Real-Time Systems: Concepts, Design and Programming – The Ultimate Reference, Himal Impressions, New Delhi, 2003
2	Heath, "Embedded Systems Design", Newnes an Imprint of Elsevier, Massachusetts, 2003.
3	Tammy Noergaard, "Embedded Systems Architecture", Newnes an Imprint of Elsevier, Massachusetts, 2006.
4	Raj Kamal, 'Embedded System-Architecture, Programming, Design', McGraw Hill, 2013
E-Re	ferences:
1	https://lecturenotes.in/subject/225/embedded-system-es
2	https://nptel.ac.in/courses/108102045/19
3	https://www.coursera.org/learn/introduction-embedded-systems.

	Outcomes: npletion of this course, the students will be able to	Bloom's Taxonomy Mapped
CO1	Outline the concepts of embedded systems	Understanding
CO2	Understand the concept of memory management system and interrupts.	Understanding
CO3	Know the importance of interfaces.	Understanding
CO4	Understand real time operating system concepts.	Understanding
CO5	To realize the applications of validation and debugging.	Applying

	COURSE ARTICULATION MATRIX														
COs/POs	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	PO 7	PO 8	PO 9	PO 10	PO 11	PO 12	PSO 1	PSO2	PSO3
CO1	3	3	1	3	-	-	-	-	-	-	3	3	3	-	2
CO2	3	3	2	3	-	-	-	-	-	-	3	3	3	-	2
CO3	3	3	3	3	-	ı	-	-	ı	-	3	3	3	-	2
CO4	3	3	2	3	-	-	-	-	-	-	2	3	3	-	2
CO5	3	3	2	3	-	-	-	-	-	-	3	3	3	-	2
Avg	3	3	2	3	-	-	-	-	-	-	2.8	3	3	-	2
		3/	2/1 - i	indicat	es stre	ength o	of corr	elatior	1 (3-H	igh,2- N	Medium	1,1- Lov	w)		

22EEM01	LINEAR AND DIGITAL ELECTRONIC	CS CIRCUITS	SEN	IEST	ER	
PREREQU	ISITES	CATEGORY	PE	Cre	edit	3
Flactron Dov	rices and Circuits	Hours/Week	L	T	P	TH
Electron Dev	ices and Circuits	Hours/ Week	3	0	0	3
Course Ob	jectives:					
1. To impa of linear	ort knowledge on the characteristics& applications of Operators.	ration Amplifier, functiona	l diagran	n and a	pplicat	ions
	olify the switching functions					
-	gn the combinational logic circuits and sequential logic circ	cuits				
Unit I (OPERATIONAL AMPLIFIERS		9	0	0	9
	amplifiers - Equivalent circuit, voltage transfer curve - Oper	n loon On-amn configurati	ons –Vol		ries V	oltag
n application				Tate at		
Unit II A	APPLICATION OF OPERATIONAL AMPLIFIE	ER AND LINEAR ICS	9	0	0	9
Detector - So Filters - Freq	nd grounded loads - Current to voltage converter - Integrate chmitt trigger with voltage limiter- Precision Rectifier Cir uency response characteristics of major active filters, first	rcuits-Peak Detector-Sam	ple and I	Hold cir	rcuit, A	Activ
Detector - So Filters - Freq filters. Functional bl	chmitt trigger with voltage limiter- Precision Rectifier Cir	rcuits-Peak Detector-Sam and higher order low pass	ple and I and high	Hold cir pass fil	rcuit, A ters, al	Active Il pass
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New Delhi, 201

S. Salivahanan and S. Arivazhagan, "Digital Circuits and Design", Third Edition, Vikas Publishing House Pvt. Ltd,

Refe	rence Books:
1.	Jacob Millman, Christos C.Halkias, "Integrated Electronics - Analog and Digital circuits system", Tata McGraw Hill 2003.
2.	R.P.Jain, "Modern Digital Electronics", Third Edition, Tata McGraw-Hill Publishing company limited, New Delhi, 2011.
3.	Thomas L. Floyd, "Digital Fundamentals", Pearson Education, Inc, New Delhi, 2015
4.	Donald P.Leach and Albert Paul Malvino, "Digital Principles and Applications", Fifth Edition, Tata McGraw Hill Publishing Company Limited, New Delhi, 2012.

Cours	e O	utcomes:	Bloom's Taxonomy
Upon c	omp	pletion of this course, the students will be able to:	Mapped
CO1	:	Understand the Op-amp characteristics	L2: Understanding
CO2	:	Understand the applications of Op-amp and other linear ICs.	L2: Understanding
CO3	:	Apply K-map and Tadulation methods to simplify the switching functions	L3: Applying
CO4	:	Design and implement of combinational logic circuits	L6: Creating
CO5	:	Analyse and design of synchronous & asynchronous sequential logic circuits	L4: Analyzing

COUR	COURSE ARTICULATION MATRIX														
CO/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO 10	PO 11	PO 12	PSO 1	PSO 2	PSO 3
CO1	2	1											2		
CO2	3	2	1	1									3		
CO3	3	2		2	2								3	3	
CO4	3	2	3	1	2							2	3	3	1
CO5	3	2	3	1	2							2	3	3	1
Avg.	2.8	1.8	2.3	1.25	2	-	-	-	-	-	-	2	2.8	3	1
	3/2/1-indicates strength of correlation (3- High, 2-Medium, 1- Low)														

	EM02	MICROPROCESSOR AND MICR	OCONTROLLER	SEI	MEST	ΓER	
PRE	REQUI	ISTIES	CATEGORY	PE	C	redit	3
CH	Programn	ming	Hours/Week	L	T	P	TH
<u> </u>	01.1			3	0	0	3
	rse Obje						
1. 2.		dy the architecture of μP8085 and μC 8051. dy the Interrupt structure of 8085 and 8051.					
3.		simple applications development with programming	8085 and 8051.				
	1						
UNI	TI 8	8085 8 BIT MICROPROCESSOR		9	0	0	9
		s of microprocessors – Architecture of 8085 – Group	_			_	-
		n and addressing of Memory and I/O systems -Inter	rupt structure – Stack and sub-	-routines	- Sim	ple 8085	based
syste	m design	and programming.					
UNI	тп	8051 8 BIT MICROCONTROLLER		9	0	0	9
		s of microcontrollers – Architecture of 8051 – Gro	una of Instructions Address	-			
		ems – I/O Ports – Timers/Counters – Serial Port	-	_		_	
		nd Compliers.	merrupt structure – Simple	programi	innig (s using
TINIT	T III	INTERFACING WITH 8051 MICROCONT	DOLLED	9	0	0	9
		uirements of interfacing – Interfacing – LED, 7 segm		_			-
	-	– DAC – Interfacing of Current, Voltage, RTD and		e switche	s, mai	ilix keyt	oaru -
ı araı	ICI / IDC	Drie interfacing of Current, Voltage, KTD and	rian bensors.				
UNI	T IV 1			9	0	0	9
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Cours	e O	outcomes:	Bloom's Taxonomy
Upon c	omp	pletion of this course, the students will be able to:	Mapped
CO1	:	Understand basics of microprocessor and microcontroller	L2: Understanding
CO2	:	Understand the architecture of Microprocessor and Microcontroller	L1: Remembering
CO3	:	Apply the digital concepts to measure and control simple electrical systems	L3: Applying
CO4	:	Design and interface communications between digital systems	L2: Understanding
CO5	:	Design a microcontroller based electrical control system.	L5: Evaluating

COUR	SE AR	RTICU	LATIO	ON MA	ATRIX										
COs/ POs	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	PO 7	PO 8	PO 9	PO 10	PO 11	PO 12	PS O1	PS O2	PS O3
CO1	2	1	1	1								1	1	1	
CO2	2	1	1	1								1	1	1	
CO3	2	3	2	3	2							1	1	1	2
CO4	2	3	3	3	2							2	2	2	2
CO5	2	3	3	3	2							2	2	2	2
Avg.	2	2.2	2	2.2	2	-	-	-	-	-	-	1.4	1.4	1.4	2
	•		3/2/1-	indicate	s streng	gth of co	orrelatio	n (3- H	igh, 2-N		, 1- Lov	v)	l-		

22EEM03	CONTROL SYSTE	MS		SEN	MEST	ER	
PREREQUI	STIES	CATEGO	RY	PE	Cr	edit	3
E14.21 Ma	chines and Electric singuit analysis	Hanna/XV		L	T	P	TH
Electrical IVIa	chines and Electric circuit analysis	Hours/W	еек	1	1	0	3
Course Obj	ectives:						
. To under	stand the methods of representation of physical sys	stems and getting their tr	ansfer	function	on mod	dels.	
	de adequate knowledge in the time response of sys						
B. To give 1	pasic knowledge in obtaining the open loop and clo	osed loop frequency resp	onse of	syster	ms.		
I. To under	stand the concept of stability of control system and	d methods of stability an	alysis.				
5. To study	the designing compensators for a feedback control	l system.					
UNIT I	MODELLING OF LINEAR TIME INVA	RIANT SYSTEMS		6	9	0	9
Basic element	s in control systems – Open and closed loop system	s – Feedback control sys	tem cha	aracter	istics -	Mathe	ematic
nodel and Ele	ectrical analogy of mechanical systems - Transfer	r function Representatio	n– Syn	nchro -	- AC a	and DO	c serve
notors – Bloc	k diagram reduction techniques – Signal flow grap	hs.					
UNIT II	TIME RESPONSE ANALYSIS			6	3	0	9
	signals - Time response of first order and second	•					•
	or constants – Type and order of control systems	 Effect of adding poles 	and ze	eros to	transi	fer fun	ctions
Response with	P, PI, PD and PID controllers.						
				ı		Ι.,	
JNIT III						1 41	9
	FREQUENCY RESPONSE ANALYSIS			6	3	0	
Correlation be	tween time and frequency response: Second order			pecific	ations		r plots
Correlation be				pecific	ations		r plots
Correlation be Bode plots – C	tween time and frequency response: Second order Computation of Gain Margin and Phase Margin —			pecific chols o	cations chart.	- Pola	
Correlation be Bode plots – C	tween time and frequency response: Second order Computation of Gain Margin and Phase Margin — STABILITY OF CONTROL SYSTEM	Constant M and N-circle	es – Nic	pecific chols of	cations chart.	- Pola	9
Correlation be Bode plots – C UNIT IV BIBO stability	tween time and frequency response: Second order Computation of Gain Margin and Phase Margin — STABILITY OF CONTROL SYSTEM 7 – Necessary conditions for stability – Routh-Hurw	Constant M and N-circle	es – Nie	pecific chols c	cations chart.	- Pola 0 - Rule	9
Correlation be Bode plots – C UNIT IV BIBO stability	tween time and frequency response: Second order Computation of Gain Margin and Phase Margin — STABILITY OF CONTROL SYSTEM	Constant M and N-circle	es – Nie	pecific chols c	cations chart.	- Pola 0 - Rule	9
Correlation be Bode plots – C UNIT IV BIBO stability construction of	stween time and frequency response: Second order Computation of Gain Margin and Phase Margin — STABILITY OF CONTROL SYSTEM - Necessary conditions for stability – Routh-Hurv f Root loci – Nyquist stability criterion – Assessment	Constant M and N-circle vitz stability criterion – Fent of relative stability u	es – Nie	pecific chols c	eations chart. 3 ncepts criterio	- Pola 0 - Rule on.	9 s for th
Correlation be Bode plots – C UNIT IV BIBO stability construction of	tween time and frequency response: Second order Computation of Gain Margin and Phase Margin — STABILITY OF CONTROL SYSTEM - Necessary conditions for stability – Routh-Hurv f Root loci – Nyquist stability criterion – Assessment COMPENSATOR AND CONTROLLER	Constant M and N-circle vitz stability criterion – Fent of relative stability u DESIGN	es – Nices – N	pecific chols c	actions chart. 3 ncepts criterio	- Pola 0 - Rule on.	9 s for th
Correlation be Bode plots – CUNIT IV BIBO stability construction of CUNIT V	stween time and frequency response: Second order Computation of Gain Margin and Phase Margin — STABILITY OF CONTROL SYSTEM - Necessary conditions for stability – Routh-Hurv f Root loci – Nyquist stability criterion – Assessment COMPENSATOR AND CONTROLLER pensation – Types of compensators – Electric necessary conditions.	vitz stability criterion – Fent of relative stability u DESIGN etwork realization and	coot locksing Ny	pecific chols c	3 ncepts criterio	- Pola 0 - Rule on. 0 ristics	9 s for the
Correlation be Bode plots – C UNIT IV BIBO stability construction of UNIT V Need for compensators	stween time and frequency response: Second order Computation of Gain Margin and Phase Margin — STABILITY OF CONTROL SYSTEM V – Necessary conditions for stability – Routh-Hurver from the Frederick of the Stability criterion – Assessment COMPENSATOR AND CONTROLLER Supensation – Types of compensators – Electric margin from the Electric from the Electri	Constant M and N-circle vitz stability criterion – Fent of relative stability u DESIGN etwork realization and to compensators using roce	coot locksing Ny	pecific chols c	3 ncepts criterio	- Pola 0 - Rule on. 0 ristics	9 s for the
Correlation be Bode plots – C UNIT IV BIBO stability construction of UNIT V Need for compensators	stween time and frequency response: Second order Computation of Gain Margin and Phase Margin — STABILITY OF CONTROL SYSTEM - Necessary conditions for stability – Routh-Hurv f Root loci – Nyquist stability criterion – Assessment COMPENSATOR AND CONTROLLER pensation – Types of compensators – Electric necessary conditions.	Constant M and N-circle vitz stability criterion – Fent of relative stability u DESIGN etwork realization and to compensators using roce	coot locksing Ny	pecific chols c	3 ncepts criterio	- Pola 0 - Rule on. 0 ristics	9 s for the
Correlation be Bode plots – C UNIT IV BIBO stability construction of UNIT V Need for compensators	stween time and frequency response: Second order Computation of Gain Margin and Phase Margin — STABILITY OF CONTROL SYSTEM V – Necessary conditions for stability – Routh-Hurver from the Frederick of the Stability criterion – Assessment COMPENSATOR AND CONTROLLER Supensation – Types of compensators – Electric margin from the Electric from the Electri	Constant M and N-circle vitz stability criterion – Fent of relative stability u DESIGN etwork realization and to compensators using rocals technique.	coot loc sing Ny	6 cus corryquist 6 acy character and B	actions chart. 3 ncepts criterio 3 aracter 3ode pl	- Pola 0 - Rule on. 0 ristics olot tech	9 s for the
Correlation be Bode plots – C UNIT IV BIBO stability construction of UNIT V Need for compensators	stween time and frequency response: Second order Computation of Gain Margin and Phase Margin — STABILITY OF CONTROL SYSTEM V – Necessary conditions for stability – Routh-Hurver from the Frederick of the Stability criterion – Assessment COMPENSATOR AND CONTROLLER Supensation – Types of compensators – Electric margin from the Electric from the Electri	Constant M and N-circle vitz stability criterion – Fent of relative stability u DESIGN etwork realization and to compensators using rocals technique.	coot locksing Ny	6 cus corryquist 6 acy character and B	actions chart. 3 ncepts criterio 3 aracter 3ode pl	- Pola 0 - Rule on. 0 ristics olot tech	9 s for the
Correlation be Bode plots – C UNIT IV BIBO stability construction of UNIT V Need for compensators PID controller	stween time and frequency response: Second order Computation of Gain Margin and Phase Margin — STABILITY OF CONTROL SYSTEM V – Necessary conditions for stability – Routh-Hurver from the Frederick of the Stability criterion – Assessment COMPENSATOR AND CONTROLLER Supensation – Types of compensators – Electric margin from the Electric from the Electri	Constant M and N-circle vitz stability criterion – Fent of relative stability u DESIGN etwork realization and to compensators using rocals technique.	coot loc sing Ny	6 cus corryquist 6 acy character and B	actions chart. 3 ncepts criterio 3 aracter 3ode pl	- Pola 0 - Rule on. 0 ristics olot tech	9 s for the
Correlation be Bode plots – C UNIT IV BIBO stability construction of UNIT V Need for components	stween time and frequency response: Second order Computation of Gain Margin and Phase Margin — STABILITY OF CONTROL SYSTEM V – Necessary conditions for stability – Routh-Hurver from the Frederick of the Stability criterion – Assessment COMPENSATOR AND CONTROLLER Supensation – Types of compensators – Electric margin from the Electric from the Electri	Constant M and N-circle vitz stability criterion – Fent of relative stability u DESIGN etwork realization and to compensators using rocals technique.	coot loc sing Ny	6 cus corryquist 6 acy character and B	actions chart. 3 ncepts criterio 3 aracter 3ode pl	- Pola 0 - Rule on. 0 ristics olot tech	9 s for the
Correlation be Bode plots – Correlation be Bode plots – Country IV BIBO stability construction of Country IV Need for compensators PID controller Fext Books: 1. A. Anance	stween time and frequency response: Second order Computation of Gain Margin and Phase Margin — STABILITY OF CONTROL SYSTEM - Necessary conditions for stability — Routh-Hurver for the foliation of the foliatio	vitz stability criterion – Fent of relative stability u DESIGN etwork realization and to compensators using root ls technique.	Root locksing Ny Crequent t locus Fotal (pecific chols construction of the construction	actions chart. 3 ncepts criterio 3 aracter Bode pl	- Pola O - Rule on. O ristics old tech	9 s for the
Correlation be Bode plots – C UNIT IV BIBO stability construction of UNIT V Need for compensators PID controller Fext Books: 1. A. Anana	stween time and frequency response: Second order Computation of Gain Margin and Phase Margin — STABILITY OF CONTROL SYSTEM V—Necessary conditions for stability — Routh-Hurver for the foliation of the foliatio	vitz stability criterion – Fent of relative stability u DESIGN etwork realization and to compensators using root ls technique.	Root locksing Ny Crequent t locus Fotal (pecific chols construction of the construction	actions chart. 3 ncepts criterio 3 aracter Bode pl	- Pola O - Rule on. O ristics old tech	9 s for the graph of base nanique
Correlation be Bode plots – C UNIT IV BIBO stability construction of UNIT V Need for compensators PID controller Fext Books: 1. A. Anana	stween time and frequency response: Second order Computation of Gain Margin and Phase Margin — STABILITY OF CONTROL SYSTEM - Necessary conditions for stability — Routh-Hurver for the foliation of the foliatio	vitz stability criterion – Fent of relative stability u DESIGN etwork realization and to compensators using root ls technique.	Root locksing Ny Crequent t locus Fotal (pecific chols construction of the construction	actions chart. 3 ncepts criterio 3 aracter Bode pl	- Pola O - Rule on. O ristics old tech	9 s for the
UNIT IV BIBO stability construction of UNIT V Need for compensators PID controller Fext Books: 1. A. Anance	stween time and frequency response: Second order Computation of Gain Margin and Phase Margin — STABILITY OF CONTROL SYSTEM - Necessary conditions for stability — Routh-Hurver for the foliation of the foliatio	vitz stability criterion – Fent of relative stability u DESIGN etwork realization and to compensators using root ls technique.	Root locksing Ny Crequent t locus Fotal (pecific chols construction of the construction	actions chart. 3 ncepts criterio 3 aracter Bode pl	- Pola O - Rule on. O ristics old tech	9 s for the graph of base nanique
Correlation be Bode plots – Correlation be Bode plots – Correlation of Control of Control of Compensators: PID controller Fext Books: 1. A. Ananco 2. I.J. Nagron 2021.	tween time and frequency response: Second order Computation of Gain Margin and Phase Margin — STABILITY OF CONTROL SYSTEM Y—Necessary conditions for stability — Routh-Hurver of Root loci — Nyquist stability criterion — Assessment of the Compensation — Types of compensators — Electric in Elag, lead and lag-lead compensators — Design of the Electric in the Electri	vitz stability criterion – Fent of relative stability u DESIGN etwork realization and to compensators using root ls technique.	Root locksing Ny Crequent t locus Fotal (pecific chols construction of the construction	actions chart. 3 ncepts criterio 3 aracter Bode pl	- Pola O - Rule on. O ristics old tech	9 s for the graph of base nanique
UNIT IV BIBO stability construction of UNIT V Need for compensators PID controller 1. A. Ananc 2. I.J. Nagr 2021.	stween time and frequency response: Second order Computation of Gain Margin and Phase Margin — STABILITY OF CONTROL SYSTEM - Necessary conditions for stability — Routh-Hurver from the Indian formula of the Indian formu	vitz stability criterion – Fent of relative stability under the property of th	Root locksing Ny Frequent locus Fotal (6 cus cor yquist of and B (30L+	actions chart. 3 ncepts criterio 3 aracter Bode pl	- Pola O - Rule on. O ristics old tech	9 s for the graph of base nanique
Correlation be Bode plots – Correlation be Bode plots – Country IV BIBO stability construction of Country Version for compensators: PID controller PID controller I.J. Nagra 2021. Reference B 1. K. Ogata	tween time and frequency response: Second order Computation of Gain Margin and Phase Margin — STABILITY OF CONTROL SYSTEM Note Necessary conditions for stability — Routh-Hurver of Root loci — Nyquist stability criterion — Assessment of the Compensation — Types of compensators — Electric in Lag, lead and lag-lead compensators — Design of the Compensation — Types of compensators — Design of the Compensation — Design of the Compensation — Second Compensators — Design of the Compensation — Second Compensators — Design of the Compensation — Nicholago — Second Compensators — Design of the Compensation — Nicholago —	vitz stability criterion – Fent of relative stability u DESIGN etwork realization and from the stability u compensators using root ls technique.	Root locksing Ny Grequent locus Fotal (Don, 201 nal Pub on, 202	6 cus corryquist of and B (30L+	actions chart. 3 ncepts criterio 3 aracter Bode pl	- Pola O - Rule on. O ristics old tech	9 s for the graph of base nanique
Correlation be Bode plots – Correlation be Bode plots – Correlation of Control of Contro	tween time and frequency response: Second order Computation of Gain Margin and Phase Margin — STABILITY OF CONTROL SYSTEM - Necessary conditions for stability — Routh-Hurver from the Properties of Computation — Assessment of Computation — Assessment of Computation — Types of compensators — Electric in Elag, lead and lag-lead compensators — Design of the Electric in Elag, lead and lag-lead compensators — Design of the Electric in Elag, lead and Electric in	vitz stability criterion – Fent of relative stability u DESIGN etwork realization and from the stability u compensators using root ls technique.	Root locksing Ny Grequent locus Fotal (Don, 201 nal Pub on, 202	6 cus corryquist of and B (30L+	actions chart. 3 ncepts criterio 3 aracter Bode pl	- Pola O - Rule on. O ristics old tech	9 s for the second of the seco
Correlation be Bode plots – Correlation be Bode plots – Correlation of Control of Control of Control of Compensators: Pid controller Fext Books: 1. A. Ananco 2. I.J. Nagrous 2. 2021. Reference B 1. K. Ogata 2. M. Gopa E-Reference	stween time and frequency response: Second order Computation of Gain Margin and Phase Margin — STABILITY OF CONTROL SYSTEM - Necessary conditions for stability — Routh-Hurver for the Root loci — Nyquist stability criterion — Assessment of Compensation — Types of compensators — Electric network Lag, lead and lag-lead compensators — Design of the Electric network is a Lag, lead and lag-lead compensators — Design of the Electric network is a Lag, lead and lag-lead compensators — Design of the Electric network is a Lag, lead and lag-lead compensators — Design of the Electric network is a Lag, lead and lag-lead compensators — Design of the Electric network is a Lag, lead and lag-lead compensators — Design of the Electric network is a Lag, lead and lag-lead compensators — Design of the Electric network is a Lag, lead and lag-lead compensators — Design of the Electric network is a Lag, lead and lag-lead compensators — Design of the Electric network is a Lag, lead and lag-lead compensators — Design of the Electric network is a Lag, lead and lag-lead compensators — Design of the Electric network is a Lag, lead and lag-lead compensators — Design of the Electric network is a Lag, lead and lag-lead compensators — Design of the Electric network is a Lag, lead and lag-lead compensators — Design of the Electric network is a Lag, lead and lag-lead compensators — Design of the Electric network is a Lag, lead and lag-lead compensators — Design of the Electric network is a Lag, lead and lag-lead compensators — Design of the Electric network is a Lag, lead and lag-lead compensators — Design of the Electric network is a Lag, lead and lag-lead compensators — Design of the Electric network is a Lag, lead and lag-lead compensators — Design of the Electric network is a Lag, lead and lag-lead compensators — Design of the Electric network is a Lag, lead and lag-lead compensators — Design of the Electric network is a Lag, lead and lag-lead compensators — Design of the Electric network is a Lag, lead and lag-lead compensators — Design of	vitz stability criterion – Fent of relative stability u DESIGN etwork realization and from the stability u compensators using root ls technique.	Root locksing Ny Grequent locus Fotal (Don, 201 nal Pub on, 202	6 cus corryquist of and B (30L+	actions chart. 3 ncepts criterio 3 aracter Bode pl	- Pola O - Rule on. O ristics old tech	9 s for the second of the seco
UNIT IV BIBO stability construction of UNIT V Need for compensators PID controller 1. A. Anana 2. I.J. Nagr 2021. Reference B 1. K. Ogata 2. M. Gopa E-Reference 1. https://ng	tween time and frequency response: Second order Computation of Gain Margin and Phase Margin — STABILITY OF CONTROL SYSTEM - Necessary conditions for stability — Routh-Hurver from the Properties of Computation — Assessment of Computation — Assessment of Computation — Types of compensators — Electric in Elag, lead and lag-lead compensators — Design of the Electric in Elag, lead and lag-lead compensators — Design of the Electric in Elag, lead and Electric in	vitz stability criterion – Fent of relative stability u DESIGN etwork realization and from the stability u compensators using root ls technique.	Root locksing Ny Grequent locus Fotal (Don, 201 nal Pub on, 202	6 cus corryquist of and B (30L+	actions chart. 3 ncepts criterio 3 aracter Bode pl	- Pola O - Rule on. O ristics old tech	9 s for the graph of base nanique

Course Ou	ıtco	mes:	Bloom's Taxonomy
Upon com	Mapped		
CO1		Develop the transfer function models of any electrical and electro-mechanical	L2: Understanding
COI	•	systems.	
CO2	:	Obtain the time responses of the systems and construct root locus plot.	L3: Applying
CO3	:	Analyze the frequency response of the system	L3: Applying
CO4	:	Analyze the absolute / relative stability of a control system.	L4: Analyzing
CO5	:	Design the compensators and PID controller of a feedback control system.	L3: Applying

COUR	SE AR	RTICU	LATI(ON MA	TRIX										
COs/ POs	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	PO 7	PO 8	PO 9	PO 10	PO 11	PO 12	PS O1	PS O2	PS 03
CO1	3	3	2	2	2							1	3	2	1
CO2	3	3	3	2	2							1	3	2	1
CO3	3	3	3	2	2							1	3	2	1
CO4	3	3	3	2	2							1	3	2	1
CO5	3	3	3	2	2							1	3	2	1
Avg	3	3	2.8	2	2	-	-	-	-	-	-	1	3	2	1
			3/2/1-	indicate	s streng	th of co	rrelatio	n (3- Hi	gh, 2-M	ledium,	1- Low)		•	

22EI	EM04	MEASUREMENTS AND INSTRUM	IENTATION	SE	MEST	ΓER	
PRE	REQU	ISTIES	CATEGORY	PE	C	redit	3
Electr	ic Circı	uit Analysis	Hours/Week	L	T	P	TH
		•	Trouis, Week	3	0	0	3
Cour		ectives:					
1.	To edu	acate the fundamental concepts and characteristics of mea	asurement System				
2.		roduce the fundamentals of electrical and electronic instr	uments for measurement of	f Electric	al and	Non-el	ectrical
	quanti						
3.	To fan	niliarize Oscilloscope and the bridge circuits for electrica	l parameters measurement				
UNIT		INTRODUCTION		9	0	0	9
		a generalized measurement system - Static and dynamic		neasuren	nent. N	Aeasure:	ment of
voltag	e and c	urrent - permanent magnet moving coil and moving iron	type meters				
UNIT	T II	MEASUREMENT OF POWER, ENERGY AN	ND FREOUENCY	9	0	0	9
		of power - single and three phase- electrodynamomet		nstruction	ı, ope	ration –	torque
-		deflection – errors. Measurement of energy-Single phase	• • • • • • • • • • • • • • • • • • • •				
		Potential transformers, Power factor meters- Single phase	electrodynamometer type	power fa	ctor m	eter, fre	quency
meter-	-Electri	cal resonance type frequency meter					
UNIT	r III	DC AND AC BRIDGES		9	0	0	9
		tions - Wheatstone bridge – Kelvin double Bridge –Ma	xwell's inductance canacit				
		ridge – Schering bridge and De Sauty's bridge	Awen's inductance capacit	unice of the	450	Truy 5 c	riage
				1	1		1
UNIT	ΓIV	POTENTIOMETERS, OSCILLOSCOPES AN	D DIGITAL	9	0	0	9
DC Pa	otention	INSTRUMENTS neter- Crompton's Potentiometer, AC potentiometer- Dry	vedala polar potentiometer	Gall Tir	slev c	o ordin	ote type
		r, Cathode Ray Oscilloscope and Digital storage Oscillo			•		
_		Digital voltmeters.	,		rr	,	<i>6</i> ····
UNIT		MEASUREMENT OF NON-ELECTRICAL Q		9	0	0	9
		of transducers –Position transducers, Piezo-electric tra		ransduce	rs. M	leasuren	nent of
pressu	ire, tem	perature and displacement– Introduction to Smart Sensor	rs .				
			To	otal (451	L+0T)= 45 P	eriods
				(,	
Text	Books	:					
1.	A.K.	Sawhney, 'A Course in Electrical & Electronics Measur	rement & Instrumentation'.	Dhanpa	ıt Rai	and Co,	2015
2.		Doebelin, 'Measurements Systems- Application and Des					
	1	Books:	sign , rata wediaw rim p	uonsiing	comp	any, 20	13.
1.		S. Moorthy, 'Transducers and Instrumentation', Prentice	Hall of India Dut 1 td 201	10			
2.	_	Kalsi, 'Electronic Instrumentation', Tata McGraw Hill, 2		10.			
3.		tin Reissland, 'Electrical Measurements', New Age Inter		11.			
	ferenc		(, ·····, = ·····, = ·				
1		:://archive.nptel.ac.in/courses/108/105/108105153/					
	пира	atem (e.iiptenae.iii) courses/100/100/100/100103133/					

Course O	Course Outcomes:						
Upon com	Mapped						
CO1	:	Recall the fundamentals of measurement system in electrical engineering.	L1: Remembering				
CO2	:	Describe the working principle of different measuring instruments	L2: Understanding				
CO3	:	Choose appropriate instrument for measuring the electrical parameters	L3: Applying				
CO4	:	Employ the digital instruments in real time measurements.	L3: Applying				
CO5	:	Select an appropriate transducer for measurement of non-electrical quantities	L4: Analysing				

COUR	SE AR	TICUI	ATIO	N MA	TRIX										
COs/ POs	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	PO 7	PO 8	PO 9	PO 10	PO 11	PO 12	PS O1	PS O2	PS O3
CO1	2	2	2	3				1		2		2	2	1	1
CO2	1	3			3					2		1	2	1	
CO3	1	1		2	1	1	2		1				1	2	1
CO4	1	1		1	1		2	2	1		2	2	1	3	1
CO5	2	2	3	1	2	2	1			1	3		1	2	
Avg	1.4	1.8	2.5	1.75	1.75	1.5	1.67	1.5	1	1.67	2.5	1.67	1.4	1.8	1
		•	3/2/1-ir	dicates	strengtl	of cor	relation	(3- Hig	h, 2-Me	dium, 1	- Low)				

22EEM05	ELECTRICAL MACHINES	SEME				
PREREQUI	STIES	CATEGORY	PE	Cre	edit	3
		Hours/Week	L	T	P	TH
		Hours/ week	3	0	0	3
C Obia						

Course Objectives:

- 1. To impart knowledge on construction, working and performance of DC generators and motors.
- 2. To deliberate the construction, working and performance of single phase and three phase transformers.
- 3. To impart knowledge on construction, working and performance of synchronous generators and motors.
- 4. To impart knowledge on construction, principle of operation and performance of single and three-phase induction motors.

UNIT I DC GENERATORS

9 0 0 9

Principle of operation, constructional details, types - EMF equation, armature reaction, demagnetizing and cross magnetizing Ampere turns, compensating winding, commutation, methods of improving commutation, interpoles, Open circuit and load characteristics of different types of DC Generators. Parallel operation of DC Generators, applications of DC Generators.

UNIT II DC MOTORS

0

0 9

Principle of operation, significance of back emf, torque equation and power developed by armature, load characteristics of shunt, series and compound type motors, starting methods, speed control methods - losses and efficiency calculation, condition for maximum efficiency. Testing of DC Machines: Brake test, Swinburne's test, Hopkinson's test, Retardation test, Separation of core losses - applications of DC motors.

UNIT III | TRANSFORMER

9 0 0 9

Single phase transformer: Construction and principle of operation, working of practical transformer - equivalent circuit, voltage regulation, losses and efficiency- testing: polarity test, open circuit and short circuit tests, back-to back test, all day efficiency, parallel operation, applications.

Autotransformer: Construction and working, saving of copper - applications, **Three phase transformer**: construction, types of connections and their comparative features.

UNIT IV | SYNCHRONOUS GENERATOR AND MOTOR

0 0

Synchronous Generator: Constructional and working details – Types of rotors – EMF equation – Phasor diagrams of non-salient pole synchronous generator connected to infinite bus - Synchronizing and parallel operation – Synchronizing torque - Voltage regulation – EMF, MMF and ZPF method – steady state power angle characteristics – Two reaction theory – slip test.

Synchronous Motor: Principle of operation – Torque equation – Operation on infinite bus bars - V and Inverted V curves – Power input and power developed equations – Starting methods – Current loci for constant power input, constant excitation and constant power Developed -Hunting – natural frequency of oscillations – damper windings- synchronous condenser.

UNIT V THREE PHASE AND SINGLE PHASE INDUCTION MOTOR

0

 $\label{thm:construction} \textbf{Three phase induction motor:} \ Constructional \ details - Types \ of \ rotors -- Principle \ of \ operation -- Equivalent \ circuit -- Torque-Slip \ characteristics -- Condition for maximum torque -- Losses \ and \ efficiency -- load \ test -- No \ load \ and \ blocked \ rotor \ tests -- Circle \ diagram -- Separation \ of \ losses -- Starters: \ DOL, \ Autotransformer \ and \ Star \ delta \ starters -- Speed \ control \ methods: \ Voltage \ control, Frequency \ control \ and \ pole \ changing -- V/f \ control -- Slip \ power \ recovery \ Scheme.$

Single phase induction motor: Constructional details – Double field revolving theory and operation – Equivalent circuit – No load and blocked rotor test – Performance analysis – Starting methods of single-phase induction motors – split phase, Capacitor-start, capacitor start and capacitor run Induction motor.

Total (45L+0T)=45 Periods

Text Books:

1. I. J. Nagrath and D. P. Kothari, "Electric Machines", McGraw Hill Education, 5th Edition, 2017.

2.	P. S. Bimbhra, "Electric Machinery", Khanna Publishers, 2nd Edition, 2021.
3.	B.L.Theraja and A.K.Theraja," A text book of Electrical Technology - Volume-II", S.Chand & Company Ltd., New Delhi, 23 rd Edition, 2009.
Refere	ence Books:
1.	B.R.Gupta, 'Fundamental of Electric Machines' New age International Publishers,3 rd Edition, Reprint 2015.
2.	Murugesh Kumar, 'Electric Machines', Vikas Publishing House Pvt. Ltd, First edition, 2010.
3.	A.E. Fitzgerald, Charles Kingsley, Stephen. D. Umans, 'Electric Machinery', Mc Graw Hill publishing Company Ltd, 6th Education, 2017.
4.	Stephen J. Chapman, 'Electric Machinery Fundamentals'4th edition, McGraw Hill Education Pvt. Ltd, 4th Edition 2017.

Course O	uto	comes:	Bloom's Taxonomy		
Upon comp	Upon completion of this course, the students will be able to:				
CO1	:	Explain the construction and working principle of DC machines, and Interpret various characteristics of DC machines.	L2: Understanding		
CO2	:	Compute various performance parameters of the machine, by conducting suitable tests.	L5: Evaluating		
CO3	:	Describe the working principle of transformer, auto transformer, three phase transformer connection, and determine the efficiency and regulation.	L3: Applying		
CO4	:	Understand the construction and working principle of Synchronous Machines.	L3: Applying		
CO5	:	Understand the construction and working principle, speed control of three phase and single phase induction motor.	L5: Evaluating		

COs/ POs	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	PO 7	PO 8	PO 9	PO 10	PO 11	PO 12	PS O1	PS O2	PS 03
CO1	3	3	1	1	1			1				1	3	2	1
CO2	3	3	1	1	1			1				1	3	2	1
CO3	3	3	1	1	1			1				1	3	2	1
CO4	3	3	1	1	1			1				1	3	2	1
CO5	3	3	1	1	1			1				1	3	2	1
Avg.	3	3	1	1	1	-	-	1	-	-	-	1	3	2	1

	6 ELECTRICAL DRIVES AND CONTI	ROL	SEN	MEST	ER	
PREREQ	DUISTIES	CATEGORY	PE	Cr	edit	3
DC Machin	nes and Transformers, Synchronous and Induction Machines, and	TT / XX/ 1 -	L	T	P	TH
Power Elec	etronics	Hours/Week	3	0	0	3
Course O	Objectives:					
1. To 1	know about the operation analyse of chopper fed DC drive, both qu	ialitatively and quai	ntitatively	7.		
2. To u	understand the operation and performance of AC motor drives.					
UNIT I	DC MOTOR CHARACTERISTICS & CHOPPER FE	D DC DRIVES	9	0	0	9
	torque-speed characteristics of separately excited dc motor, chan			-	-	
	pad torque-speed characteristics, operating point, armature voltage					_
-	d duty ratio control, chopper fed dc motor for speed control, stead	•	_	-		
	veform and ripple, calculation of losses in dc motor and chopper.		11			
UNIT II	MULTI-QUADRANT & CLOSED-LOOP CONTROL	OF DC DRIVE	9	0	0	9
	Four quadrant operation of dc machine; single-quadrant, two-quadrant	-				
	e, inner current loop and outer speed loop, dynamic model of dc n	•				
_	of chopper as gain with switching delay, plant transfer function, of	current controller sp	ecification	on and	design	, speed
controller s	specification and design.					
	The state of the s				1 0	
UNIT III			9	0	0	9
	induction motor equivalent circuit and torque-speed characteristic) applied frequency and (iii) applied voltage and frequency. Review	-	-			
		of three-phase voita	age sourc	e inver	ter, ger	ieratioi
	ase PWM signals, constant V/f control of induction motor	of three-phase volu	age sourc	e inver	ter, ger	leration
of three-ph	ase PWM signals, constant V/f control of induction motor	of three-phase void	ge sourc	e inver	0	9
of three-ph	ase PWM signals, constant V/f control of induction motor	•	9	0	0	9
of three-ph UNIT IV Impact of r	control of slip RING INDUCTION MOTOR	on of slip-ring induc	9 etion mote	0 or with	0	9
UNIT IV Impact of resistance,	CONTROL OF SLIP RING INDUCTION MOTOR rotor resistance of the induction motor torque-speed curve, operation starting torque, power electronic based rotor side control of slip ring.	on of slip-ring induc	9 tion motor recover	or with	0 extern	9 al rotor
UNIT IV Impact of r resistance, UNIT V	CONTROL OF SLIP RING INDUCTION MOTOR rotor resistance of the induction motor torque-speed curve, operation starting torque, power electronic based rotor side control of slip ring. CONTROL OF SRM AND BLDC MOTOR DRIVES.	on of slip-ring inducing motor, slip powe	9 etion motor recover	0 or with y	0 extern	9 al rotor
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UNIT IV Impact of r resistance, UNIT V SRM const Torque con	CONTROL OF SLIP RING INDUCTION MOTOR rotor resistance of the induction motor torque-speed curve, operation starting torque, power electronic based rotor side control of slip ring. CONTROL OF SRM AND BLDC MOTOR DRIVES. Bruction - Principle of operation - SRM drive design factors-Torque on trol using current controllers and flux controllers. Construction	on of slip-ring inducing motor, slip power	9 ction motor recover 9 ock diagration of	or with	0 extern	9 al roto: 9 aneous chine -
UNIT IV Impact of r resistance, UNIT V SRM const Torque con Sensing an	CONTROL OF SLIP RING INDUCTION MOTOR rotor resistance of the induction motor torque-speed curve, operation starting torque, power electronic based rotor side control of slip ring. CONTROL OF SRM AND BLDC MOTOR DRIVES. Truction - Principle of operation - SRM drive design factors-Torque of the induction and logic switching scheme,-Sinusoidal and trapezoidal type of B	on of slip-ring inducing motor, slip power	9 ction motor recover 9 ock diagration of	or with	0 extern	9 al roto 9 aneous chine -
UNIT IV Impact of r resistance, UNIT V SRM const Torque con Sensing an	CONTROL OF SLIP RING INDUCTION MOTOR rotor resistance of the induction motor torque-speed curve, operation starting torque, power electronic based rotor side control of slip ring. CONTROL OF SRM AND BLDC MOTOR DRIVES. Bruction - Principle of operation - SRM drive design factors-Torque on trol using current controllers and flux controllers. Construction	on of slip-ring inducing motor, slip power	9 ction motor recover 9 ock diagration of	or with	0 extern	9 al roto: 9 aneous chine -
UNIT IV Impact of r resistance, UNIT V SRM const Torque con Sensing an	CONTROL OF SLIP RING INDUCTION MOTOR rotor resistance of the induction motor torque-speed curve, operation starting torque, power electronic based rotor side control of slip ring. CONTROL OF SRM AND BLDC MOTOR DRIVES. Truction - Principle of operation - SRM drive design factors-Torque of the induction and logic switching scheme,-Sinusoidal and trapezoidal type of B	on of slip-ring inducing motor, slip power controlled SRM-Bl and Principle of oprushless dc motors	9 ction motor recover 9 ock diagration of	or with y Oram of BLD diagra	0 extern 0 Instant: C Mac	9 al roto: 9 aneous chine - current
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https://www.iith.ac.in/~ketan/drives.htmL

Course C	Bloom's Taxonomy				
Upon com	Mapped				
CO1	:	Understand the characteristics of dc motors and induction motors.	L2: Understanding		
CO2	CO2 : Summarize the operation of chopper fed DC drives.				
CO3	:	Understand the principles of speed-control of dc motors and induction motors.	L2: Understanding		
CO4	:	Identify suitable power electronic converters used for dc motor and induction motor speed control.	L3: Applying		
CO5	:	Analyze the SRM and BLDC motor drive control	L4: Analyzing		

COUR	COURSE ARTICULATION MATRIX														
COs/ POs	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	PO 7	PO 8	PO 9	PO 10	PO 11	PO 12	PS O1	PS O2	PS O3
CO1	3	1	3			1	1					1	3	2	
CO2	3	3	1	3		1	1					1	3	2	
CO3	3	3	3	3	1	1	1					1	3	2	
CO4	1	3	3	2	1	1	1					1	3	2	
CO5	3	3	3	3	1	1	1					1	3	2	
Avg.	2.6	2.6	2.6	2.75	1	1	1	-	-	-	-	1	3	2	-
			3/2/1-i	ndicates	strengt	h of cor	relation	(3- High	h, 2-Me	dium, 1	- Low)				

22EE	M07	ELECTRIC VEHICLES AND CONTROL	L	SEM	EST	ER	
PRER	REQUI	CATEGORY	PE	Cre	edit	3	
Electri	cal driv	es and control	Hours/Week	L	T	P	TH
Licetii	cai diiv	es and control	Hours/ Week	3	0	0	3
Cours	se Obje	ectives:					
1.	To pro	vide knowledge on electric vehicle architecture and its configurations	5				
2.	To imp	art knowledge on vehicle control, use of energy storage systems and	energy management	in Ele	ctric \	Vehic	le
T 13 17	- 1	DI ECODICI VIETVO EC					
UNIT		ELECTRIC VEHICLES	with Eccardin Name	9	0	0	9
_	mption,	s of Electric Vehicles (EV), Performance of Electric Vehicles, Tra Hybrid Electric Vehicles (HEV): Classification, Series Hybrid Ele			_		
UNIT	П	PLUG-IN HYBRID ELECTRICVEHICLES (PHEV) AD ELECTRIC VEHICLES	ND FUEL CELL	9	0	0	9
		Benefits of PHEV, Components of PHEVs, Operating Principles of dell: Operation and Types, Fuel Cell Electric Vehicle: Configuration	•		ontrol	Strat	egy of
UNIT	III	ELECTRIC PROPULSION SYSTEMS		9	0	0	9
		ic propulsion system, Classification of electric motor drives for EV at	nd HEV, Multiquadr	ant Co	ntrol (of Cho	
Fed DO	C Moto	Drives, Vector Control of Induction Motor drives, Permanent Magn	etic Brush-Less DC	Motor	Drive	s, Sw	itched
Relucta	ance M	otor Drives for Electric Vehicles					
UNIT	TX7	ENERGY STORAGE SYSTEM		9	0	0	9
		tery Systems for Automotive Applications, Battery Technologies	Niekal Matal Hyd		_	_	_
Lithiur	n-Poly	mer (Li–P) Battery, Lithium-Ion (Li-Ion) Battery, Ultracapacito ed Flywheels, Hybridization of Energy Storages	•				•
UNIT	V	ENERGY MANAGEMENT SYSTEM		9	0	0	9
Energy	Mana	gement System(EMS) in Electric Vehicle, Rule-based control strate	egy: Deterministic ru	le-bas	ed co	ntrol,	Fuzzy
Metahe	euristic	ontrol, and Neural network-based control. Optimization based optimization methods and Model predictive control, Semi-active type Pybrid Energy Storage System-based EMS	0.	•		_	•
			Total (4	15L+0	T)= 4	45 Pe	riods
To4 1	Dooless						
1 ext I	Books:	Hussain, "Electric and Hybrid Vehicles: Design Fundamentals", C	RC Press Taylor &	Franc	is Gr	uin S	econd
1.	Editio	on ,2011.	•				
2.	CRC	dad Ehsani, Yimin Gao, Sebastien E. Gay, AliEmadi,, "Modern Elect Press, 2016	tric, Hybrid Electric,	and Fu	ıel Ce	ll Vel	icles"
Refer	ence B						
1.		madi, Mehrdad Ehsani, John M.Miller ,"Vehicular Electric Power S	Systems", Ali Emadi	, Mehi	dad E	hsani	, John
F-Dof	erence	iller, Special Indian Edition, Marcel dekker, Inc 2010					
1		//archive.nptel.ac.in/courses/108/106/108106170/					
	mps.	// atom - o.mpon.ac.mi/ coarsos/ 100/ 100/ 100100170/					

Course	Bloom's Taxonomy		
Upon co	Mapped		
CO1	:	Recall the fundamentals of electric vehicle and its mechanics	L1: Remembering
CO2	:	Explain the architecture of different forms of hybrid electric vehicles.	L2: Understanding

CO3	:	Illustrate the four-quadrant operation of DC drive, induction motor drive and SRM drive for Electric Vehicles.	L4: Analyzing
CO4	:	Select an appropriate energy storage system for Electric vehicle	L4: Analyzing
CO5	:	Use the suitable energy management control strategy for hybrid electric vehicle	L3: Applying

COURSE ARTICULATION MATRIX															
COs/ POs	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	PO 7	PO 8	PO 9	PO 10	PO 11	PO 12	PS O1	PS O2	PS O3
CO1	1		1	3	1		1					1	1	2	1
CO2	1	2	3	1			2					2	1	2	
CO3	1	1			2		3						1	1	1
CO4	3	1	2	1	2		1					2	1	2	1
CO5	1	2	1	2	1							1	1	2	1
Avg	1.4	1.5	1.75	1.75	1.5	-	1.75	-	-	-	-	1.5	1	1.8	1
	1	•	3/2/1-ir	dicates	strengtl	n of cor	relation	(3- Hig	h, 2-Me	dium, 1	- Low)	1	ı	•	I

22EEN	MO8 ELECTRICAL ENERGY CONSERVATION A	AND AUDITING	SEN	MESTI	ER	
PRER	EQUISITES	CATEGORY	PE	Cre	edit	3
D	Constitution Transmission of Distribution Contract	Hours/Week	L	T	P	TH
Power	Generation, Transmission and Distribution System	3	0	0	3	
Course	e Objectives:					
1. T	To get knowledge about basics of energy and energy scenario of Inc	dia.				
	To familiarise the energy conservation methods.					
3. T	To acquire knowledge on energy auditing, energy efficiency and me	odern energy efficient of	levices.			
Į.						
UNIT I	I ENERGY SCENARIO		9	0	0	9
Comme	rcial and non-commercial energy -Primary energy resources -	- Commercial energy	product	ion - F	inal e	nerg
consum	ption - Energy needs of growing economy - Long term energy so	cenario - Energy pricir	ig - Ener	gy sect	or refe	orms
Energy a	and environment - Energy security - Energy conservation and its im	portance - Restructurin	g of the e	energy s	supply	secto
- Energy	y strategy for the future, air pollution, climate change. Energy Con-	servation Act-2001 and	l its featu	ıres.		
UNIT I	II BASICS OF ENERGY		9	0	0	9
Electric	ity tariff - Load management and maximum demand control - Ther	mal Basics-fuels - The	rmal ene	rgy con	tents o	f fuel
tempera	ature and pressure, heat capacity, sensible and latent heat, evaporation	ion, condensation, steam	m, moist	air and	humic	lity &
heat trai	nsfer, units and conversion.					
UNIT 1	III ENERGY MANAGEMENT AND AUDIT		9	0	0	9
Definition	on - Energy audit – Need and types of energy audit. Energy manag	rement (audit) approach	underst	anding	energy	cost
	marking - Energy performance - Matching energy use to requiren			_		
		nent - Iviaximizing syste	em effici	encies -	- Optin	nizin
					_	
_	nt energy requirements, fuel and energy substitution - Energy audit	instruments. Material	and ener		_	
_		instruments. Material	and ener		_	
as an en	nt energy requirements, fuel and energy substitution - Energy audit nergy system - Methods for preparing process flow, material and en	instruments. Material	and ener		_	acility
as an en	nt energy requirements, fuel and energy substitution - Energy audit energy system - Methods for preparing process flow, material and energy system - Methods for preparing process flow, material and energy ENERGY EFFICIENCY	t instruments. Material nergy balance diagrams	and ener	gy bala	nce: Fa	acility 9
as an en UNIT	nt energy requirements, fuel and energy substitution - Energy audit energy system - Methods for preparing process flow, material and energy system: ENERGY EFFICIENCY al system: Electricity billing - Electrical load management and	t instruments. Material nergy balance diagrams	and ener . 9 -Power	gy bala 0 factor in	0	9 emen
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UNIT Delectrication and its belosses. Delectrication and its belosses and its belosses. Delectrication and its belosses and its bel	IV ENERGY EFFICIENCY al system: Electricity billing - Electrical load management and management - Selection and location of capacitors - Performance assess: Electric motors: Types - Losses in induction motors - Motor eding and motor replacement issues - Energy saving opportunities with the speed drives - Energy efficient transformers - Electronic ballats - Energy saving potential of each technology. ENERGY EFFICIENT TECHNOLOGIES Lim demand controllers - Automatic power factor controllers - Energies speed drives - Energy efficient transformers - Electronic ballats - Energy saving potential of each technology. ENORS: Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 20 Tripathy, S. C, "Utilization of Electrical Energy and Conservations and Energy and Conservations and Energy and Conservations and Energy and Conservations are substituted in the Energy and Conservations and Energy and Conservations are substituted in the Energy and Conservations and Energy and Conservations are substituted in the Energy Substituted	ximum demand control ment of PF capacitors, fficiency - Factors affi ith energy efficient motors –So ast - Occupancy sensor Total 15. ation", McGraw Hill,	-Power distribut ecting materials - Energy (45 L+)	gy bala 0 factor in ion and otor pe 0 rs with or gy effice 0 T) =	omprovement of transfer formation of the light of the lig	9 emen corme save
UNIT Delectrical and its belosses. Delectrical and its belosses and its belosses. Delectrical and its belosses and its belosses and its belosses and its belosses and its belosses. Delectrical and its belosses and its belo	IV ENERGY EFFICIENCY al system: Electricity billing - Electrical load management and management - Selectric motors: Types - Losses in induction motors - Motor eding and motor replacement issues - Energy saving opportunities with the speed drives - Energy efficient transformers - Electronic ballates - Energy saving potential of each technology. ENERGY EFFICIENT TECHNOLOGIES and demand controllers - Automatic power factor controllers - Energies peed drives - Energy efficient transformers - Electronic ballates - Energy saving potential of each technology.	ximum demand control ment of PF capacitors, fficiency - Factors affi ith energy efficient motors –So ast - Occupancy sensor Total 15. ation", McGraw Hill,	-Power distribut ecting materials - Energy (45 L+)	gy bala 0 factor in ion and otor pe 0 rs with or gy effice 0 T) =	omprovement of transfer formation of the light of the lig	9 emen corme save
UNIT Electrical and its belosses. Rewind: UNIT Maximular Variable controls Text B 1. S 2, T 3. H	IV ENERGY EFFICIENCY al system: Electricity billing - Electrical load management and management - Selection and location of capacitors - Performance assess: Electric motors: Types - Losses in induction motors - Motor eding and motor replacement issues - Energy saving opportunities with the speed drives - Energy efficient transformers - Electronic ballats - Energy saving potential of each technology. ENERGY EFFICIENT TECHNOLOGIES Lim demand controllers - Automatic power factor controllers - Energies speed drives - Energy efficient transformers - Electronic ballats - Energy saving potential of each technology. ENORS: Sonal Desai, "Handbook of Energy Audit", McGraw Hill, 20 Tripathy, S. C, "Utilization of Electrical Energy and Conservations and Energy and Conservations and Energy and Conservations and Energy and Conservations are substituted in the Energy and Conservations and Energy and Conservations are substituted in the Energy and Conservations and Energy and Conservations are substituted in the Energy Substituted	ximum demand control ment of PF capacitors, fficiency - Factors affi ith energy efficient motors –So ast - Occupancy sensor Total 15. ation", McGraw Hill,	-Power distribut ecting materials - Energy (45 L+)	gy bala 0 factor in ion and otor pe 0 rs with or gy effice 0 T) =	omprovement of transfer formation of the light of the lig	9 emeriormee save
UNIT DELECTRICATE AND ASSESSED TO SERVING TO	IV ENERGY EFFICIENCY al system: Electricity billing - Electrical load management and management: - Selection and location of capacitors - Performance assess: Electric motors: Types - Losses in induction motors - Motor et ing and motor replacement issues - Energy saving opportunities with the speed drives - Energy efficient transformers - Electronic ballats - Energy saving potential of each technology. ENERGY EFFICIENT TECHNOLOGIES Immediately demand controllers - Automatic power factor controllers - Energy efficient transformers - Electronic ballats - Energy saving potential of each technology. Fooks: Goods: G	ximum demand control ment of PF capacitors, fficiency - Factors affeith energy efficient motors gy efficient motors –So ast - Occupancy sensor Total 15. ation", McGraw Hill ystems", Wiley-IEEE	-Power distribut ecting materials - Energy (45 L+) 1991. Press, 1	gy bala 0 factor in ion and ottor per otto per	omprover transfer formation of the series of	9 emen ormer ance saver ghting 2018

1. 2,

Energy Efficiency in Electrical Utilities, Bureau of Energy Efficiency, New Delhi, 2015.

Course	e Outcomes:	Bloom's Taxonomy
Upon c	ompletion of this course, the students will be able to:	Mapped
CO1	Identify the present energy scenario and future energy strategy.	L1: Understanding
CO2	Recognize the various forms of energy.	L1: Understanding
CO3	Interpret energy management methods and energy auditing.	L3: Applying
CO4	Familiar in energy efficiency of electrical systems.	L4: Analysing
CO5	Familiar with the advanced energy efficient technologies.	L4: Analysing

COUR	COURSE ARTICULATION MATRIX														
COs/ POs	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	PO 7	PO 8	PO 9	PO 10	PO 11	PO 12	PS O1	PS O2	PS 03
CO1	1	2	3	2	2		3					1	2	2	1
CO2	1	2	2	2	2		3					1	2	2	1
CO3	2	2	2	3	2		3					1	1	3	1
CO4	2	3	2	2	3		3					1	3	3	1
CO5	2	2	3	1	2		3					1	3	2	1
Avg	1.6	2.2	2.4	2	2.2	-	3	-	-	-	-	1	2.2	2.4	1
			3/2/	1-indica	ites strei	ngth of	correlat	ion (3- l	High, 2-	Mediur	n, 1- Lo	w)			

	SMPS AND UPS		SE	MEST	ER	
PREREQU	JISITES	CATEGORY	PE	Cr	edit	3
Power Electr	ronics	Hours/Week	L	T	P	TH
rowei Elecu	onies	Hours/ week	3	0	0	3
Course Ob	jectives:					
1. To im	part knowledge about modern power electronic converters an	d their applications in 1	power uti	lity.		
2. To im	part knowledge about Resonant converters and UPS.					
UNIT I	DC-DC CONVERTERS		0	Ι Δ		0
	to SMPS – Non-isolated DC-DC converters: Cuk, SEPIC	topologies 7 source	9 converte	0 r 70	to conv	9 verter
	state space modeling — Concept of volt-second and charge					
UNIT II	SWITCHED MODE POWER CONVERTERS		9	0	0	9
Isolated DC-	DC converters: Analysis and state space modelling of fly back	Forward, Push pull, L	uo, Half l	oridge a	and full	bridge
converters- c	control circuits and PWM techniques - Bidirectional DC-DC of	converters.				
	I			T .	1 -	
UNIT III	RESONANT CONVERTERS		9	0	0	9
	- classification- basic concepts- Resonant switch- Load Resonant s		-	d volta	ge topo	logies-
DC link inve	erters with Zero Voltage Switching- Series and parallel Resona	int inverters- voitage o	control.			
UNIT IV	DC-AC CONVERTERS		9	0	0	9
Introduction	 Multilevel concept – Types of multilevel inverters – Diode 	-clamped MLI – Flyin	g capacit	tors Ml	LI – Ca	scaded
	aded MLI – Applications – Switching device currents – DC 1	-				
						WILI -
Comparisons	s of MLI.					WILI -
-					<u> </u>	
UNIT V	POWER CONDITIONERS, UPS, AND FILTERS	LIPS Online LIPS A	9	0	0	9
UNIT V Introduction-	POWER CONDITIONERS, UPS, AND FILTERS - Power line disturbances- Power conditioners –UPS: offline		9 pplicatio	0 ns - Fi	ilters: V	9 Voltage
UNIT V Introduction-filters, Series	POWER CONDITIONERS, UPS, AND FILTERS	for PWM VSI, curren	9 pplicatio	0 ns - Fi	ilters: V	9 Voltage
UNIT V Introduction-filters, Series	POWER CONDITIONERS, UPS, AND FILTERS - Power line disturbances- Power conditioners –UPS: offline s-parallel resonant filters, filter without series capacitors, filter	for PWM VSI, curren apacitors.	9 pplicatio t filter, D	0 ns – Fi	ilters: V rs – De	9 Voltage sign of
UNIT V Introduction-filters, Series	POWER CONDITIONERS, UPS, AND FILTERS - Power line disturbances- Power conditioners –UPS: offline s-parallel resonant filters, filter without series capacitors, filter	for PWM VSI, curren apacitors.	9 pplicatio	0 ns – Fi	ilters: V rs – De	9 Voltage sign of
UNIT V Introduction- filters, Series	POWER CONDITIONERS, UPS, AND FILTERS - Power line disturbances- Power conditioners –UPS: offline s-parallel resonant filters, filter without series capacitors, filter	for PWM VSI, curren apacitors.	9 pplicatio t filter, D	0 ns – Fi	ilters: V rs – De	9 Voltage sign of
UNIT V Introduction-filters, Series	POWER CONDITIONERS, UPS, AND FILTERS - Power line disturbances- Power conditioners –UPS: offline s-parallel resonant filters, filter without series capacitors, filter transformer for power electronic applications – Selection of of the series of the serie	for PWM VSI, curren apacitors.	9 pplicatio t filter, D	0 ns – Fi	ilters: V rs – De	9 Voltage sign of
UNIT V Introduction- filters, Series inductor and	POWER CONDITIONERS, UPS, AND FILTERS - Power line disturbances- Power conditioners –UPS: offline s-parallel resonant filters, filter without series capacitors, filter transformer for power electronic applications – Selection of of the series of the serie	for PWM VSI, current papacitors.	9 pplicatio t filter, E	0 ns – Fi	ilters: V rs – De	9 Voltage sign of
UNIT V Introduction- filters, Series inductor and Text Books 1. Sim	POWER CONDITIONERS, UPS, AND FILTERS - Power line disturbances- Power conditioners –UPS: offline s-parallel resonant filters, filter without series capacitors, filter transformer for power electronic applications – Selection of officers.	for PWM VSI, current apacitors. To ard Edition, CRC Press	9 pplicatio t filter, E	0 ns – Fi	ilters: V rs – De	9 Voltage sign of
UNIT V Introduction- filters, Series inductor and Text Books 1. Sim	POWER CONDITIONERS, UPS, AND FILTERS - Power line disturbances- Power conditioners –UPS: offline s-parallel resonant filters, filter without series capacitors, filter transformer for power electronic applications – Selection of control of the series capacitors, filter transformer for power electronic applications – Selection of control of the series capacitors, filter without series capacitors, filter transformer for power electronic applications – Selection of control of the series capacitors, filter without series capacitors, filter transformer for power electronic applications – Selection of control of the series capacitors, filter without series capacitors, filter transformer for power electronic applications – Selection of control of the series capacitors, filter without series capacitors, filter transformer for power electronic applications – Selection of control of the series capacitors, filter without series capacitors, filter transformer for power electronic applications – Selection of control of the series capacitors, filter transformer for power electronic applications – Selection of control of the series capacitors o	for PWM VSI, current apacitors. To ard Edition, CRC Press	9 pplicatio t filter, E	0 ns – Fi	ilters: V rs – De	9 Voltage sign of
UNIT V Introduction- filters, Series inductor and Text Books 1. Sim 2. M.H. Reference	POWER CONDITIONERS, UPS, AND FILTERS - Power line disturbances- Power conditioners –UPS: offline s-parallel resonant filters, filter without series capacitors, filter transformer for power electronic applications – Selection of control of the series capacitors, filter transformer for power electronic applications – Selection of control of the series capacitors, filter without series capacitors, filter transformer for power electronic applications – Selection of control of the series capacitors, filter without series capacitors, filter transformer for power electronic applications – Selection of control of the series capacitors, filter without series capacitors, filter transformer for power electronic applications – Selection of control of the series capacitors, filter without series capacitors, filter transformer for power electronic applications – Selection of control of the series capacitors, filter without series capacitors, filter transformer for power electronic applications – Selection of control of the series capacitors, filter transformer for power electronic applications – Selection of control of the series capacitors o	To ress, 2001.	pplicatio t filter, E	0 ns – Fi oC filte -+0T):	ilters: Vers – De	9 Voltage sign of
UNIT V Introduction- filters, Series inductor and Text Books 1. Sim 2. M.F. Reference	POWER CONDITIONERS, UPS, AND FILTERS - Power line disturbances- Power conditioners –UPS: offline s-parallel resonant filters, filter without series capacitors, filter transformer for power electronic applications – Selection of convergence of the series capacitors of th	To ress, 2001.	pplicatio t filter, E	0 ns – Fi oC filte -+0T):	ilters: Vers – De	9 Voltage sign of
UNIT V Introduction- filters, Series inductor and Text Books 1. Sim 2. M.H. Reference I 1. Ned Edit	POWER CONDITIONERS, UPS, AND FILTERS - Power line disturbances- Power conditioners –UPS: offline s-parallel resonant filters, filter without series capacitors, filter transformer for power electronic applications – Selection of of S: on Ang, Alejandro Oliva," Power-Switching Converters", The I. Rashid – Power Electronics handbook, Elsevier Publication Books: Mohan, Tore.M.Undeland, William.P.Robbins, "Power Electronics in the content of the content	To To Edition, CRC Press , 2001.	pplication t filter, Detail (451), 2010.	0 ns - Fi oC filte +0T):	ilters: Vers – De	9 Voltage sign of
UNIT V Introduction- filters, Series inductor and Text Books 1. Sim 2. M.H. Reference I 1. Ned Edit 2. M.H.	POWER CONDITIONERS, UPS, AND FILTERS Power line disturbances- Power conditioners –UPS: offline s-parallel resonant filters, filter without series capacitors, filter transformer for power electronic applications – Selection of of the series capacitors of the series capacitors of the series capacitors, filter transformer for power electronic applications – Selection of the series of the serie	To To Edition, CRC Press , 2001.	pplication t filter, Detail (451), 2010.	0 ns - Fi oC filte +0T):	ilters: Vers – De	9 Voltage sign of
Text Books 1. Sim 2. M.H Reference 1. Ned E-Reference	POWER CONDITIONERS, UPS, AND FILTERS Power line disturbances- Power conditioners –UPS: offline s-parallel resonant filters, filter without series capacitors, filter transformer for power electronic applications – Selection of of the series capacitors of the series capacitors of the series capacitors, filter transformer for power electronic applications – Selection of the series of the serie	To To Edition, CRC Press , 2001.	pplication t filter, Detail (451), 2010.	0 ns - Fi oC filte +0T):	ilters: Vers – De	9 Voltage sign of

Course (Outo	Bloom's Taxonomy	
Upon completion of this course, the students will be able to:		Mapped	
CO1	:	Analyze the state space model for DC – DC converters.	L4: Analyzing
CO2	:	Acquire knowledge on switched mode power converters.	L2: Understanding
CO3	:	Outline the PWM techniques for DC-AC converters.	L1: Remembering
CO4	Discuss about modern power electronic converters and its applications in		L2: Understanding
CO5	:	Identify the filters and UPS.	L2: Understanding

COUR	COURSE ARTICULATION MATRIX														
COs/ POs	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	PO 7	PO 8	PO 9	PO 10	PO 11	PO 12	PS O1	PS O2	PS O3
CO1	2	1	2	2			1					2	2	2	1
CO2	1	1	3	2			1					2	3	3	2
СОЗ	2	2	2	3			1					1	2	2	1
CO4	2	1	1	2			1					2	2	3	2
CO5	1	1	2	1			1					1	2	2	1
Avg.	1.6	1.2	2	2	-	-	1	-	-	-	-	1.6	2.2	2.4	1.4

3/2/1-indicates strength of correlation (3- High, 2-Medium, 1- Low)

22E	EEM10	UTILIZATION OF ELECTRICAL EN	NERGY	SEM	ESTE	R	
PREI	REQUIS	PE	Cr	edit	3		
Ela ata		sings Danier Contains and Danier Electronics	House/Wools	L	Т	P	TH
Electr	ricai Macr	nines, Power System, and Power Electronics	Hours/Week	3	0	0	3
Cour	se Objec	etives:			•	•	•
1.		estand the economics of power generation, tariff and energy of	conservation method	S.			
2.		rt knowledge on principle and design of illumination systems					
3.		ze the performance and different methods of electric heating		Ţ.			
4.	To impar	rt knowledge on electric traction systems and their performar	nce.				
5.	To under	stand electric drives for various industrial applications.					
UNIT	ГΙΙ	NTRODUCTION		9	0	0	9
Econo	omics of g	eneration – definitions – load duration curve – number and s	size of generator unit	s – Cost	of elec	trical e	nergy –
tariff -	— availab	pility based Tariff- (ABT) - Battery Energy storage system	(BESS)- Frequency	based e	nergy 1	measure	ement -
need f	for electric	cal energy conservation - methods Introduction to energy a	udit				
				1			1
UNIT		ILLUMINATION		9	0	0	9
		ture of radiation - definition - laws of illumination - lumin		-			
_		ination systems for residential, commercial, street lighting		• •			
lamp-	mercury v	vapour –fluorescent lamp-energy efficiency lamps – types of	flighting schemes –	requirem	ents of	good li	ghting
				Τ.	Ι.	Τ.	Ι.
	I'			9	0	0	9
UNIT		HEATING AND WELDING				_	•
Introd	luction- cl	assification of methods of heating - requirements of a good	•	- design		_	
Introdu	luction- cl rature cor	assification of methods of heating – requirements of a good atrol of resistance furnace – electric arc furnace –induction	heating – dielectric	- design c heating		_	
Introdu	luction- cl rature cor	assification of methods of heating - requirements of a good	heating – dielectric	- design c heating		_	
Introde temper resista	uction- cl rature cor nnce weldi	assification of methods of heating – requirements of a good atrol of resistance furnace – electric arc furnace –induction ang – electric arc welding-electrical properties of arc-application	heating – dielectric	design heating velding.	– elec	tric we	lding –
Introdu temper resista	uction- clerature corance weldi	assification of methods of heating – requirements of a good trol of resistance furnace – electric arc furnace – induction ng – electric arc welding-electrical properties of arc-applicate ELECTRIC TRACTION	heating – dielectric tions of electric arc v	design heating velding.	- elec	tric we	lding –
Introductemper resista UNIT	rature connuce weldi	assification of methods of heating – requirements of a good atrol of resistance furnace – electric arc furnace – induction and – electric arc welding-electrical properties of arc-applicate ELECTRIC TRACTION requirements of an ideal traction system – supply systems –	heating – dielectric tions of electric arc v train movement -me	- design c heating welding.	- elec	0 n move	lding –
Introduction Introduction	rature cor nnce weldi FIV I	assification of methods of heating – requirements of a good atrol of resistance furnace – electric arc furnace – induction and – electric arc welding-electrical properties of arc-applicate ELECTRIC TRACTION requirements of an ideal traction system – supply systems – and control –speed control of three phase induction motor-	heating – dielectric tions of electric arc v train movement -me	- design c heating welding.	- elec	0 n move	lding –
Introduction Introduction	rature connuce weldi	assification of methods of heating – requirements of a good atrol of resistance furnace – electric arc furnace – induction and – electric arc welding-electrical properties of arc-applicate ELECTRIC TRACTION requirements of an ideal traction system – supply systems – and control –speed control of three phase induction motor-	heating – dielectric tions of electric arc v train movement -me	- design c heating welding.	- elec	0 n move	lding –
Introduction Introduction	rature cor ance weldi Γ IV I luction – r on motors ic traction.	assification of methods of heating – requirements of a good atrol of resistance furnace – electric arc furnace – induction and – electric arc welding-electrical properties of arc-applicate ELECTRIC TRACTION requirements of an ideal traction system – supply systems – and control –speed control of three phase induction motor-	train movement -me	- design c heating welding.	- elec	0 n move	lding –
UNITI	F V I	assification of methods of heating – requirements of a good atrol of resistance furnace – electric arc furnace – induction ang – electric arc welding-electrical properties of arc-applicate ELECTRIC TRACTION requirements of an ideal traction system – supply systems – and control –speed control of three phase induction motor-	train movement -me multiple unit contro	design heating velding. 9 echanism ol – brak	- elec	0 n move ecent tr	9 ement – ends in
UNITI Introdutractio electric UNITI Electric	FIV I I uction - r on motors ic traction.	assification of methods of heating – requirements of a good atrol of resistance furnace – electric arc furnace – induction ang – electric arc welding-electrical properties of arc-applicate ELECTRIC TRACTION requirements of an ideal traction system – supply systems – and control –speed control of three phase induction motor-	train movement -me multiple unit contro	e heating velding. 9 echanism ol – brak 9 selection	of training – re	0 n move eccent tr	9 ement – ends in 9 ypes of
UNITI Introdutaction electric	F V I I I I I I I I I I I I I I I I I I	assification of methods of heating – requirements of a good atrol of resistance furnace – electric arc furnace – induction and – electric arc welding-electrical properties of arc-applicate ELECTRIC TRACTION requirements of an ideal traction system – supply systems – and control –speed control of three phase induction motor- DRIVES AND THEIR INDUSTRIAL APPLICATION advantages of electric drive-individual drive and group drives.	train movement -me multiple unit control one of the control of the	- design c heating welding. 9 echanism ol – brak 9 selection lications	of training – re	0 n move eccent tr	9 ement – ends in 9 ypes of
UNITI Introdutaction electric	F V I I I I I I I I I I I I I I I I I I	assification of methods of heating – requirements of a good atrol of resistance furnace – electric arc furnace –induction and – electric arc welding-electrical properties of arc-applicate ELECTRIC TRACTION requirements of an ideal traction system – supply systems – and control –speed control of three phase induction motors. DRIVES AND THEIR INDUSTRIAL APPLICATION advantages of electric drive-individual drive and group drive tate –transient characteristics –size of motor– load equalizate	train movement -me multiple unit control one of the control of the	- design c heating welding. 9 echanism ol – brak 9 selection lications	of training – re	0 n move eccent tr	9 ement – ends in 9 ypes of
UNITI Introdutaction electric	F V I I I I I I I I I I I I I I I I I I	assification of methods of heating – requirements of a good atrol of resistance furnace – electric arc furnace –induction and – electric arc welding-electrical properties of arc-applicate ELECTRIC TRACTION requirements of an ideal traction system – supply systems – and control –speed control of three phase induction motors. DRIVES AND THEIR INDUSTRIAL APPLICATION advantages of electric drive-individual drive and group drive tate –transient characteristics –size of motor– load equalizate	train movement -me multiple unit control ONS ve —factors affecting tion — industrial apple traking using thyristors	- design c heating welding. 9 echanism ol – brak 9 selection lications	of training – reconstruction of model	0 n move eccent tr	9 ment – ends in 9 ypes of hods of
UNITI Introdutractio electric UNITI Electric loads - speed	FIV I I I I I I I I I I I I I I I I I I	assification of methods of heating – requirements of a good atrol of resistance furnace – electric arc furnace –induction and – electric arc welding-electrical properties of arc-applicate ELECTRIC TRACTION requirements of an ideal traction system – supply systems – and control –speed control of three phase induction motors. DRIVES AND THEIR INDUSTRIAL APPLICATION advantages of electric drive-individual drive and group drive tate –transient characteristics –size of motor– load equalizate	train movement -me multiple unit control ONS ve —factors affecting tion — industrial apple traking using thyristors	- design c heating velding. 9 cchanism ol – brak 9 selection lications ors.	of training – reconstruction of model	0 n move eccent tr	9 ment – ends in 9 ypes of hods of
UNIT Introdutractio electric UNIT Electric loads - speed	FIV I I uction - r on motors ic traction. FV I I control of the c	assification of methods of heating – requirements of a good atrol of resistance furnace – electric arc furnace –induction and – electric arc welding-electrical properties of arc-applicate ELECTRIC TRACTION requirements of an ideal traction system – supply systems – and control –speed control of three phase induction motorical advantages of electric drive-individual drive and group drive tate –transient characteristics –size of motor– load equalizate D.C drives-dynamic braking using thyristors-regenerative between the system – supply systems – and control –speed control of three phase induction motorical equalization of the system – supply systems – and control –speed control of three phase induction motorical equalization of the system – supply systems – and control –speed control of three phase induction motorical equalization of the system – supply systems – and control –speed control of three phase induction motorical equalization of three phase induction induct	train movement -me multiple unit control ONS The effectors affecting tion – industrial application are using thyrister.	e heating velding. 9 echanism ol – brak 9 selection lications ors.	of training – round of mode	0 n move eccent tr 0 otor - ty	9 ment – ends in 9 ypes of hods of
UNITI Introdutractio electric UNITI Electric loads - speed Text 1	F V I I I I I I I I I I I I I I I I I I	assification of methods of heating – requirements of a good atrol of resistance furnace – electric arc furnace –induction and – electric arc welding-electrical properties of arc-applicate ELECTRIC TRACTION requirements of an ideal traction system – supply systems – and control –speed control of three phase induction motoradvantages of electric drive-individual drive and group drive attate –transient characteristics –size of motor– load equalizate for D.C drives-dynamic braking using thyristors-regenerative before the phase induction of Electrical forms of Ele	train movement -me multiple unit control ONS /e —factors affecting tion — industrial appl oraking using thyristo Tell I Energy", New Age	9 selections ors. Internation	on of training – reconstruction of training –	0 n move eccent tr 0 otor - ty	9 ment – ends in 9 ypes of hods of
UNITI Introdutractio electric UNITI Electric loads - speed Text 1 1.	FIV I I I I I I I I I I I I I I I I I I	assification of methods of heating – requirements of a good atrol of resistance furnace – electric arc furnace –induction and – electric arc welding-electrical properties of arc-applicate ELECTRIC TRACTION requirements of an ideal traction system – supply systems – and control –speed control of three phase induction motoradvantages of electric drive-individual drive and group drivatate –transient characteristics –size of motor– load equalizate D.C drives-dynamic braking using thyristors-regenerative by adhwa, "Generation, Distribution and Utilization of Electrica penshaw Taylor, "Utilisation of Electric Energy", English University of the size of	train movement -me multiple unit control ONS re –factors affecting tion – industrial apple traking using thyriste I Energy", New Age niversities Press Lim	e heating velding. 9 echanism ol – brak 9 selection lications ors. Otal (45) Internation of the property o	on of training – respectively. On of model L+OT)	0 n move eccent tr 0 otor - ty	9 ment – ends in 9 ypes of hods of
UNITI Introdutractio electric UNITI Electric loads - speed Text 1 2. 3.	FV Incomplete traction.	assification of methods of heating – requirements of a good atrol of resistance furnace – electric arc furnace –inductioning – electric arc welding-electrical properties of arc-applicated ELECTRIC TRACTION requirements of an ideal traction system – supply systems – and control –speed control of three phase induction motoradvantages of electric drive-individual drive and group drive attace –transient characteristics –size of motor– load equalizate for D.C drives-dynamic braking using thyristors-regenerative by the state –transient characteristics –size of motor– load equalizate for D.C drives-dynamic braking using thyristors-regenerative by the state –transient characteristics –size of motor– load equalizate for D.C drives-dynamic braking using thyristors-regenerative by the state –transient characteristics –size of motor– load equalizate for D.C drives-dynamic braking using thyristors-regenerative by the state –transient characteristics –size of motor– load equalizate for D.C drives-dynamic braking using thyristors-regenerative by the state –transient characteristics –size of motor– load equalizate for D.C drives-dynamic braking using thyristors-regenerative by the state –transient characteristics –size of motor– load equalizate for D.C drives-dynamic braking using thyristors-regenerative by the state –transient characteristics –size of motor– load equalizate for D.C drives-dynamic braking using thyristors-regenerative by the state –transient characteristics –size of motor– load equalizate for D.C drives-dynamic braking using thyristors-regenerative by the state –transient characteristics –size of motor– load equalizate for D.C drives-dynamic braking using thyristors-regenerative by the state –transient characteristics –size of motor– load equalizate for D.C drives-dynamic braking using thyristors-regenerative by the state –transient characteristics –size of motor– load equalizate –transient characteristics –size of motor– load equalizate –transient characteristics –size of motor– load equalizate –transient –t	train movement -me multiple unit control ONS re –factors affecting tion – industrial apple traking using thyriste I Energy", New Age niversities Press Lim	e heating velding. 9 echanism ol – brak 9 selection lications ors. Otal (45) Internation of the property o	on of training – respectively. On of model L+OT)	0 n move eccent tr 0 otor - ty	9 ment – ends in 9 ypes of hods of
UNITI Introdutractio electric UNITI Electric loads - speed Text 1 2. 3. Refer	FIV I I I I I I I I I I I I I I I I I I	assification of methods of heating – requirements of a good atrol of resistance furnace – electric arc furnace – induction and – electric arc welding-electrical properties of arc-applicated ELECTRIC TRACTION requirements of an ideal traction system – supply systems – and control –speed control of three phase induction motoradvantages of electric drive-individual drive and group drivatate –transient characteristics –size of motor– load equalizate for D.C drives-dynamic braking using thyristors-regenerative by a fadhwa, "Generation, Distribution and Utilization of Electrical censhaw Taylor, "Utilisation of Electric Energy", English Unipta, "Utilization of Electric Power and Electric Traction", Sooks:	train movement -me multiple unit control ONS ve —factors affecting tion — industrial appl traking using thyristor and the state of th	9 echanism ol – brak 9 selection lications ors. Internation ited, 193 2002.	onal Pv	on move eccent tr	ypes of hods of deriods
UNITI Introdutractio electric UNITI Electric loads - speed Text 1. 2. 3. Refer 1.	FIV I I uction - rance welding a rance welling	assification of methods of heating — requirements of a good atrol of resistance furnace — electric arc furnace —induction and — electric arc welding-electrical properties of arc-applicate ELECTRIC TRACTION requirements of an ideal traction system — supply systems — and control —speed control of three phase induction motorand advantages of electric drive-individual drive and group drivatate —transient characteristics —size of motor—load equalizate —transient —	train movement -me multiple unit control ONS Te —factors affecting tion — industrial apploraking using thyriste I Energy", New Age niversities Press Lim K. Kataria and Sons, etrical Energy", Khar	9 echanism of brak 9 selection lications ors. Internation ited, 193 and 2002.	on of model L+0T) shers, I	on move eccent tr	ypes of hods of deriods
UNITI Introdutractio electric UNITI Electric loads - speed Text 1 2. 3. Refer 1. 2.	F V I I I I I I I I I I I I I I I I I I	assification of methods of heating — requirements of a good atrol of resistance furnace — electric arc furnace —induction ing — electric arc welding-electrical properties of arc-applicated. ELECTRIC TRACTION requirements of an ideal traction system — supply systems — and control —speed control of three phase induction motoradvantages of electric drive-individual drive and group drivatate —transient characteristics —size of motor—load equalizate —transient characteristics —size of motor—load equalizate —D.C drives-dynamic braking using thyristors-regenerative by the properties of	train movement -me multiple unit control ONS Te —factors affecting tion — industrial apploraking using thyriste I Energy", New Age niversities Press Lim K. Kataria and Sons, etrical Energy", Khar	9 echanism of brak 9 selection lications ors. Internation ited, 193 and 2002.	on of model L+0T) shers, I	on move eccent tr	ypes of hods of deriods
UNITI Introdutractio electric UNITI Electric loads - speed Text 1 2. 3. Refer 1. 2. E-Ref	FIV I I uction - r on motors ic traction. FV I I ic drive - steady s control of I J.B. Gu Frence Books: G.C.G. H. Part	assification of methods of heating — requirements of a good atrol of resistance furnace — electric arc furnace —induction and — electric arc welding-electrical properties of arc-applicated. ELECTRIC TRACTION requirements of an ideal traction system — supply systems — and control —speed control of three phase induction motoral advantages of electric drive-individual drive and group drivatate —transient characteristics —size of motor—load equalizate —transient —t	train movement -me multiple unit control ONS Te —factors affecting tion — industrial apploraking using thyriste I Energy", New Age niversities Press Lim K. Kataria and Sons, etrical Energy", Khar	9 echanism of brak 9 selection lications ors. Internation ited, 193 and 2002.	on of model L+0T) shers, I	on move eccent tr	ypes of hods of deriods
UNITI Introduction electric UNITI Electric loads - speed Text 1 2. 3. Refer 1. 2. E-Refer 1.	F V I I I I I I I I I I I I I I I I I I	assification of methods of heating — requirements of a good atrol of resistance furnace — electric arc furnace —induction ing — electric arc welding-electrical properties of arc-applicated. ELECTRIC TRACTION requirements of an ideal traction system — supply systems — and control —speed control of three phase induction motoral advantages of electric drive-individual drive and group drivatate —transient characteristics —size of motor—load equalizate —transient characteristics —size of motor—load equalizate —f.D.C drives-dynamic braking using thyristors-regenerative by the properties of Electric Power and Electric Traction", Source, "Utilization of Electric Power and Electric Traction", Source, "Utilization of Electric Power in Utilization of Electrical Energy", Drives — arg, S.K.Gridhar&S.M.Dhir, "A Course in Utilization of Electrical Energy", Drives — and Electrical Energy", Dr	train movement -me multiple unit control ONS Te —factors affecting tion — industrial apploraking using thyriste I Energy", New Age niversities Press Lim K. Kataria and Sons, etrical Energy", Khar	9 echanism of brak 9 selection lications ors. Internation ited, 193 and 2002.	on of model L+0T) shers, I	on move eccent tr	ypes of hods of deriods
UNITI Introdutractio electric UNITI Electric loads - speed Text 1 2. 3. Refer 1. 2. E-Ref	FIV Interest of the control of the c	assification of methods of heating — requirements of a good atrol of resistance furnace — electric arc furnace —induction and — electric arc welding-electrical properties of arc-applicated. ELECTRIC TRACTION requirements of an ideal traction system — supply systems — and control —speed control of three phase induction motoral advantages of electric drive-individual drive and group drivatate —transient characteristics —size of motor—load equalizate —transient —t	train movement -me multiple unit control ONS Te —factors affecting tion — industrial apploraking using thyriste I Energy", New Age niversities Press Lim K. Kataria and Sons, etrical Energy", Khar	9 echanism of brak 9 selection lications ors. Internation ited, 193 and 2002.	on of model L+0T) shers, I	on move eccent tr	ypes of hods of deriods

Course O	uto	comes:	Bloom's Taxonomy
Upon com	Upon completion of this course, the students will be able to:		Mapped
CO1 : Understand the economics of power generation, tariff and energy conservation methods.		L2: Understanding	
CO2	:	Interpret the concept behind illumination and design a suitable illumination system for a specific application.	L3: Applying
CO3	Design and choose an appropriate heating method for specific application and		L4: Analyzing
CO4	:	Explain the concepts and recent trends of traction system.	L4: Analyzing
CO5	:	Discuss the concepts of electric drives and their characteristics.	L2: Understanding

COUR	COURSE ARTICULATION MATRIX														
COs/ POs	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	PO 7	PO 8	PO 9	PO 10	PO 11	PO 12	PS O1	PS O2	PS O3
CO1	3	1	1	1	1	2	1	2	2	1	1	1	2	2	3
CO2	2	3	2	3	1	1	2	1	1			1	3	3	2
CO3	3	3	1	3	1	1	2	1					2	2	3
CO4	1	2	2	3	3	1	2	1					2	3	2
CO5	3	1	1	2	1	1	2	1		1		1	2	2	3
CO6	1	3	3	3	3	1	2	2				1	3	3	2
Avg	2.17	2.17	1.67	2.5	1.67	1.17	1.83	1.33	1.5	1	1	1	2.33	2.5	2.5
	3/2/1-indicates strength of correlation (3- High, 2-Medium, 1- Low)														

22ME	EM01	ENGINEERING THERMODYNAMICS (Use of standard thermodynamic tables, Mollier diagram as						
PRE-	REQUI	SITE:	CATEGORY	PE	Cr	edit		3
			TT //X7 1	L	T	P	7	ГН
			Hours/Week	3	0	0		3
Cours	se Obje	etives:		•				
1.	To im	part the knowledge on concepts of zeroth and first law of thermod	ynamics.					
2.		ke the learners to understand the third law of thermodynamics tions in closed and open systems.	and analyze the	variou	is wo	ork an	d l	neat
3.	To tea	ch properties of pure substance.						
4.	To im	part knowledge on the concepts of steam power cycle.						
5.	To der	ive thermodynamic relations for ideal and real gases.						
UNIT	ľ	BASIC CONCEPT AND FIRST LAW			9	0 0)	9
Thermoand he	uum, ma odynami eat. First	odynamics in Engineering and Science - Applications of Therroroscopic approach, thermodynamic systems, Property, state, c equilibrium, Displacement work, P-V diagram. Zeroth law of thermodynamics – application to closed and open system equipment.	path and process hermodynamics -	es, qua - conce	si-sta pt of	atic p	roc era	ess, ture
UNIT	· II	SECOND LAW AND ENTROPY			9	0 ()	9
UNII						E	ale	
Heat en	se staten	Refrigerator – Heat Pump, Second law of thermodynamics – Kelvnents their corollaries. Reversibility and irreversibility. Carnot cept of entropy, principle of increase of entropy, T-s diagram, T-c	cycle, reversed	Carnot				
Heat en	se staten llity, Con	nents their corollaries. Reversibility and irreversibility. Carnot	cycle, reversed	Carnot		ele. Cl	laus	
Heat er of thes inequal UNIT	se statemality, Con TIII formates fraction	nents their corollaries. Reversibility and irreversibility. Carnot cept of entropy, principle of increase of entropy, T-s diagram, T-c	c cycle, reversed ds equations, Entre liagrams. PVT so	Carnot opy.	9 Dete	o o rmina	laus () (tion	9 n of

 $Basic\ Rankine\ cycle,\ T-s\ \&\ h-s\ diagrams\ -\ Performance\ Improvement\ -\ Reheat\ cycle,\ regenerative\ cycle\ and\ their\ combination\ cycles.$

UNIT V | IDEAL AND REAL GASES AND THERMO DYNAMIC RELATIONS | 9 | 0 | 0 | 9

Properties of ideal and real gases, equation of state of ideal and real gases, Avogadro's law, Vander Waal's equation of states, Principle of corresponding states, reduced properties and compressibility chart. Exact differentials, Maxwell relations, Specific heat equations, Tds, relations, Clausius Clapeyron equations and Joule Thomson Coefficient.

Total (45L)= 45 Periods

Text B	Text Books:							
1.	Nag. P.K, "Engineering Thermodynamics", Tata McGraw-Hill, New Delhi, 2017.							
2.	Sonntag, R.E., Borgnakke, C., and Van Wylen, G.J., Fundamentals of Thermodynamics, 6th ed., John Wiley, 2003.							
3.	Arora C.P, "Thermodynamics", Tata McGraw Hill, New Delhi, 2003.							
4.	Venwylen and Sontag, "Classical Thermodynamics", Wiley Eastern, 1987.							

Refere	nce Books:
1.	Cengel, "Thermodynamics- An Engineering Approach", 3rd Edition, Tata McGraw Hill, 2015.

Merala C, Pother, Craig W and Somerton, "Thermodynamics for Engineers", Schaum Outline Series, Tata McGrawHill, New Delhi, 2004.

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:				
CO1	Understand the concepts of zeroth, first and second law of thermodynamics.				
CO2	Analyze the various work and heat interactions for different types of processes for closed and open systems				
CO3	Evaluate the different properties of pure substances using steam tables and Mollier chart	Evaluate			
CO4	Analyze the performance of steam power cycle.	Analyze			
CO5	Derive thermodynamic relations for ideal and real gases.	Analyze			

COURSE	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	2	2			1					1	3	1	1
CO2	3	3	2	2			1					1	3	1	1
CO3	3	3	3	2		1	1					1	3	1	1
CO4	2	3	2	2		1	1					1	3	1	1
CO5	3	3	2	2		1						1	3	1	1
Avg	2.8	3	2.2	2		1	1					1	3	1	1
	3/2/1 – indicates strength of correlation (3 – High, 2- Medium, 1- Low)														

22ME	M02									
PRE-F	PRE-REQUISITE: CATEGORY PE							3		
1.Engin	eering P	hysics		L	T	P]	ГН		
	•	hemistry	Hours/Week	3	0	0		3		
3.Engin	eering N	f athematics								
Course	e Objec	tives:								
1.	To und	erstand the basic concepts and properties of fluids.								
2.	To ana	lyze the kinematic and dynamic concepts of fluid flow.								
3.	To und	erstand the various incompressible fluid flow through pipes a	nd between parallel p	lates.						
4.	To app	ly the principles of fluid mechanics to design and operation of	f hydraulic turbines.							
5.	5. To apply the principles of fluid mechanics to design and operation of hydraulic pumps.									
UNIT	UNIT I INTRODUCTION AND FLUID STATICS							9		
Basic c	fluid	ls – d	lens	sity,						

Basic concepts and units of measurement of physical quantities- Classification of fluids - Properties of fluids - density, relative density, vapour pressure, surface tension, Capillarity and viscosity. Fluid statics- hydrostatic pressure, buoyancy and Archimedes' principle.

UNIT II FLUID KINEMATICS AND DYNAMICS

9 0 0 9

Classification of fluid flow - system and control volume - Lagrangian and Eulerian description for fluid flow - flow patterns-streamline, pathline, streakline and timeline. Velocity potential function and Stream function - continuity equation and its applications. Fluid dynamics - Bernoulli's equation and its applications. Dimensional analysis - Buckingham's theorem, dimensional homogeneity, similarity-laws and models.

UNIT III FLOW THROUGH PIPES AND PLATES

0 0 9

9

Incompressible fluid flow-Laminar flow- Hagen-Poiseuille equation, shear stress, pressure gradient relationship - flow through pipes and flow between parallel plates. Turbulent flow - flow through pipes, friction factors in turbulent flow - total energy line, hydraulic gradient line, flow through pipes in series and parallel- Moody's friction factor chart. Power transmission-Boundary layer flows - Boundary layer thickness, momentum thickness, energy thickness-boundary layer separation.

UNIT IV HYDRAULIC TURBINES

0 0 9

Hydraulic turbines classification-impulse and reaction turbines-Working Principle, work done-efficiency and performance curves for Pelton, Francis and Kaplan turbines (Only descriptive) - Comparison between impulse and reaction turbine-specific speed degree of reaction -draft tubes.

UNIT V HYDRAULIC PUMPS

9 0 0 9

Classification of hydraulic pumps- Centrifugal pumps - working principle, specific speed, performance curves and priming(Only descriptive) - Reciprocating pumps - classification, working principle, indicator diagram, air vessels and performance curves. Cavitation in pumps (Only descriptive) - Working principles of gear and vane pumps.

Total (45L)= 45 Periods

Text B	ooks:
1.	Bansal, R.K., "A Textbook of Fluid Mechanics and Hydraulic Machines, 9th Ed", Laxmi Publication Pvt Ltd, 2010.
2.	Rajput, R.K., "A Textbook of Fluid Mechanics and Hydraulic Mechanics", S.Chand and Company Ltd, 2011.
3.	Subramanya. K., "Fluid Mechanics and Hydraulic Machines", Tata McGraw Hill Publishing Company Ltd, 2011.
Refere	nce Books:
1.	White, "Fluid Mechanics, 8 Ed", McGraw Hill India, 2017.
2.	Munson, Young and Okiishi, "Fundamentals of Fluid Mechanics 8 th Edition", Wiley, 2016.
3.	Yunuscengel, John. M.cimbala, "Fluid Mechanics Fundamentals and Applications", McGraw Hill, 2017.
4.	Som, S.K, Biswas.G and SumanChakraborty, "Introduction to Fluid Mechanics and Fluid Machines", Tata McGraw Hill India, 2011.

5. Dr.P.N.Modi, Dr.S.M.Seth, "Hydraulics and Fluid Mechanics including Hydraulic Machines", Standard book house, 2018.

E-References:

1. NPTEL courses: http://nptel.iitm.ac.in/courses.php - web and video sources on fluid mechanics.

	SE OUTCOMES: ompletion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Understand the basic concepts and properties of fluids.	Remember
CO2	Analyze the kinematic and dynamic concepts of fluid flow.	Analyze
СОЗ	Understand the various incompressible fluid flow through pipes and between parallel plates.	Understand
CO4	Apply the principles of fluid mechanics to design and operation of hydraulic turbines.	Apply
CO5	Apply the principles of fluid mechanics to design and operation of hydraulic pumps.	Apply

COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1	1				2				1		2	2	1
CO2	3	3	1		2								2	2	1
CO3	2	3	2	2	1								2	2	1
CO4	3	3	3	2	1	2	1						2	2	1
CO5	3	3	3	2	1	2	1						2	2	1
Avg	2.8	2.6	2	2	1.25	2	1.3				1		2	2	1

22MI	EM03	MANUFACTURING PROCESSES						
PRE-	REQUI	SITE:	The matics, Engineering Physics Hours/Week L 3 with various manufacturing processes and fabrication techniques manufacturing processes. te manufacturing processes for various parts.	PE	Cre	edit		3
1. 2.		cience, Engineering mathematics, Engineering Physics ering Materials	Hours/Week	L	Т	P	۲.	ГН
	8		riours, vicen	3	0	0		3
Cour	se Objec	tives:						
1.		e the students familiarize with various manufacturing processes f casting.	and fabrication to	echniqu	ies of	meta	als	and
2.	To devel	op design concepts of various manufacturing processes.						
3.	Gain kno	owledge to select appropriate manufacturing processes for variou	s parts.					
4.	To devel	op an entrepreneur skill among the students.						
5.	To evalu	ate and select plastic deformation processes for various parts.						
UNIT	ΓI	CASTING			9	0	0	9

Concepts of Manufacturing Process -Sand casting -Patterns – Design of Pattern, mould and cores- gating and risering design, solidification time calculation - Moulding machines - Core making. Special moulding processes – CO2 moulding; shell moulding, investment moulding, pressure die casting, centrifugal casting, casting defects.

UNIT II | WELDING | 9 | 0 | 0 | 9

Classification of welding processes. Principles of Oxy-acetylene gas welding. Metal arc welding, resistance welding, submerged arc welding, tungsten inert gas welding, metal inert gas welding, plasma arc welding, thermit welding, electron beam welding, laser beam welding, defects in welding, Soldering and Brazing, Adhesive Bonding.

UNIT III METAL FORMING 10 0 10

Metallurgical aspects of metal forming, slip, twinning mechanics of plastic deformation, load estimation of bulk deformation processes, Hot working and cold working of metals, Forging processes – open, closed and impression die forging – forging operations. Rolling of metals – Types of Rolling mill – Flat strip rolling – shape rolling operations – Defects in rolled parts. Principle of rod and wire drawing – Tube drawing – Principles of Extrusion – Types.

UNIT IV SHAPING OF PLASTICS

Types of plastics - Characteristics of the forming and shaping processes - Moulding of Thermoplastics - Working principles and typical applications of - Injection moulding - Plunger and screw machines - Blow moulding - Rotational moulding - Film blowing - Extrusion - Typical industrial applications - Thermoforming - Processing of Thermosets - Working principles and typical applications - Compression moulding - Transfer moulding.

UNIT V SHEET METAL FORMING AND POWDER METALLURGY 9 0 0 9

Formability of Sheet Metal, load estimation of sheet metal processes - Shearing, Deep drawing, Bending operations- types of presses used, Super Plastic forming; Introduction to Powder Metallurgy- Principal steps involved - sintering and compacting techniques, Advantages, limitations and applications of powder metallurgy.

Total (45L) = 45 Periods

0 8

Text B	ooks:
1.	HajraChoudhury, "Elements of Workshop Technology", Vol. I and II, Media Promoters and Publishers Pvt., Ltd., Mumbai, 2005.
2.	NagendraParashar B.S. and Mittal R.K., "Elements of Manufacturing Processes", Prentice-Hall of India Private Limited, 2007.
Refere	ence Books:
1.	Serope Kalpajian, Steven R.Schmid, "Manufacturing Processes for Engineering Materials", 4/e, Pearson Education, Inc. 2007.
2.	Jain. R.K., and S.C. Gupta, "Production Technology", 16th Edition, Khanna Publishers, 2001.
3.	"H.M.T. "Production Technology – Handbook", Tata McGraw-Hill, 2000.
4.	Roy. A. Linberg, "Process and Materials of Manufacture", PHI, 2000.

Mikell P. Groover, Fundamentals of Modern Manufacturing: Materials, Processes, and Systems.
 E-References:

 https://fdocuments.in/document/production-technology-55844cac00bfc.html?page=40

	SE OUTCOMES: ompletion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Describe the operational features of various casting processes, design gate and riser and discover various defects in casting.	Understand
CO2	Explain various metal joining processes and compare them.	Understand
СОЗ	Summarize several types of metal forming processes and select suitable method for different applications.	Analyze
CO4	Analyze various manufacturing methods for plastics and their needs in industry.	Analyze
CO5	Describe various sheet metal forming processes, load estimation calculation and principles of powder metallurgy	Understand

COURSE A	ARTI	CULA	TIO	N MA	TRIX	K									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	2	1						1			1	2	1
CO2	2	1	2	1		1			1	1			1	2	1
CO3	1	1	1	1						1			1	1	1
CO4	1	1	1		1					1			1	1	1
CO5		1							1	1			1		1
Avg	1.5	1	1.5	1	1	1			1	1			1	1.5	1
	•	3/2/		dicat	es str	ength	of co	rrelati	on (3	– High,	2- Med	lium, 1	- Low)		

22ME	M04	MATERIALS ENGINEERING					
PRE-I	REQUI	SITE:	CATEGORY PE Credit	3			
1.		eering Physics	T (XX)	L	T	P	TH
2.	Engine	eering Chemistry	lours/Week	3	0	0	3
Cours	se Objec	ctives:					
1.	To im	•	vior of engineer	ing ma	terials	at dif	ferent
2.	To lea	rn basic principles in metallurgy and materials engineering.					
3.	To ide	ntity and select suitable engineering materials based on their application	s.				
UNIT	I	PHASE DIAGRAMS		9	0	0	9
system: diagran	s – Eute n - effec	ectic, Eutectoid, Peritectic systems. Lever rule, Equilibrium and non- ts of alloying elements – Ferrite and Austenite Stabilizers, TTT and CCT	equilibrium coo	oling, l	Fe-C E	quilit	brium
UNIT	II	HEAT TREATMENT		9	0	0	9
Isother test – A	mal tran Austemp	sformation diagrams – cooling curves superimposed on I.T. diagram C ering, martempering – case hardening, carburising, nitriding, cyaniding	CR - Hardenabi g, carbo-nitriding	lity, Jo g – Fla	miny e me and	nd qu Indu	uench action
UNIT	III	FERROUS AND NON FERROUS METALS		9	0	0	9
precipi	tation ha						
UNIT	IV	MECHANICAL PROPERTIES AND TESTING		9	0	0	9
Fractur	e - Type		s - fatigue and c				
UNIT	V	NON DESTRUCTIVE TESTING AND SURFACE ENGINE	ture and mechanical behavior of engineering materials at different engineering. Dased on their applications. 9				
Inspect	tion and	re Testing: Basic principles - Testing method - Radiographic testing Liquid Penetrant Inspections. Introduction to surface engineering - Deand low energy beam methods, surface engineering charts, elastic contact	finition, diffusio				

Text Bo	oks:
1.	Kenneth G. Budinski and Michael K. Buinski, "Engineering Materials", Prentice Hall of India Ltd, 2002.
2.	Raghavan, V, "Materials Science and Engineering", Prentice Hall of India (P) Ltd., 1999.
3.	Aswani.K.G, "A Text Book of Material Science", S.Chand and Co. Ltd., New Delhi, 2001.
4.	Khanna O.P., "A Text Book of Materials Science and Metallurgy", DhanpatRai Sons, 2004.
Referen	ce Books:
1.	William. D.Callsber, "Material Science and Engineering", John Wiley and Sons, 1997.
2.	Sydney.H.Avner, "Introduction to Physical Metallurgy" Mc Graw Hill Book Company, 1994.

Total (45L) = 45 Periods

	SE OUTCOMES: ompletion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Understand the formation of materials and their classification based on atomic structure.	Understand
CO2	Understand the principles of various heat treatment processes in fabrication industry.	Understand
СОЗ	Describe properties, applications and types of various ferrous and non-ferrous metals used in fabrication industry	Understand
CO4	Describe various types of failure and select methods for destructive testing	Understand
CO5	Select methods for non destructive testing	Evaluate

COURSE A	ARTI	CULA	TIO	N MA	TRI	K									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	1	2	2	1	1	1						2	3	1
CO2	1		2	1	1	2	1						2	3	1
CO3		1	1	1	1		1						3	2	1
CO4		2	2	1	1	1	1						2	3	1
CO5		2	2	2	1		1						2	2	1
Avg	1	1.5	1.8	1.4	1.0	1.3	1						2.2	2.6	1.0
	•	3/2/	/1 – in	dicat	es str	ength	of co	rrelati	on (3	– High,	, 2- Med	lium, 1	Low)		•

	M05	KINEMATICS OF MACHINERY					
PRE-	REQUIS	SITE:	CATEGORY	PE	Cr	edit	3
1. Engi	ineering g	raphics. 2.Engineering Mechanics	Hours/Week	L	T	P	TF
			Hours/ week	3	0	0	3
Cours	se Objec	tives:					
1.	To und	erstand the basic components and layout of linkages in the assemb	oly of a system/ ma	chine.			
2.		erstand the principles in analyzing the assembly with respect to to point in a link of a mechanism.	he displacement, vo	elocity,	and	accele	ratio
3.	To und	erstand basics of cam profile and its displacement.					
4.	To und	erstand the basic concepts of toothed gearing and kinematics of g	ear trains.				
5.	Illustra	te the effects of friction drives in transmission system.					
UNIT	I		9	0	9		
Kinem	atic inver	f mechanisms- Basic kinematic concepts and definitions- Degrations of four bar chain and slider-crank chains Limit positions- Mome common mechanisms- Quick return mechanism, straight-lin	Iechanical advantag				
UNIT	II	KINEMATIC ANALYSIS			9	0	9
centres	- kinema	elocity and acceleration analysis of simple mechanisms, graphitic analysis of simple mechanisms-slider-crank mechanism dynan antroduction to linkage synthesis three Position graphical synthesis	nics Coincident poi	ints- Co	riolis	s comp	
UNIT	III	KINEMATICS OF CAM			9	0	9
simple	harmonic	cams and followers- Terminology and definitions- Displacement and cycloidal motions- derivatives of follower motions- specified undercutting, sizing of cams, graphical method for cam profile	ed contour cams cir				
OINII		GEARS AND GEAR TRAINS			9	0) 9
Involut					pur g	gear c	9 ontac
Involut	nd interfe	GEARS AND GEAR TRAINS cloidal gear profiles, gear parameters, fundamental law of gearing			pur g	gear co	9 ontac
Involut ratio ar UNIT	v contacts	GEARS AND GEAR TRAINS cloidal gear profiles, gear parameters, fundamental law of gearing tence / undercutting- helical, bevel, worm, rack & pinion gears, expression of the control of th	picyclic and regula	r gear t	pur grain l	gear cokinem	ontacatics.
Involut ratio ar UNIT	v contacts	GEARS AND GEAR TRAINS cloidal gear profiles, gear parameters, fundamental law of gearing tence / undercutting- helical, bevel, worm, rack & pinion gears, established the statement of the state	picyclic and regula hreads – bearings	r gear t	pur grain l	gear cokinema 0 (ontacatics 9 Ontacatics 1 9 Priction
Involut ratio ar UNIT Surface Clutche	v contacts	GEARS AND GEAR TRAINS cloidal gear profiles, gear parameters, fundamental law of gearing tence / undercutting- helical, bevel, worm, rack & pinion gears, established the statement of the state	picyclic and regula hreads – bearings	r gear t	pur grain l	gear cokinema 0 (ontacatics 9 Ontacatics 1 9 Priction

Text E	Books:							
1.	Rattan S.S, "Theory of Machines", Tata McGraw Hill Publishing Company Ltd., New Delhi, 1998.							
2.	Ghosh, A and Mallick, A.K, "Theory of Mechanisms and Machines", East-West Pvt. Ltd., New Delhi, 1988.							
Refere	ence Books:							
1.	Thomas Bevan, "Theory of Machines", CBS Publishers and Distributors, 1984.							
2.	Rao J.S and Dukkipati R.V, "Mechanism and Machine Theory", Wiley-Eastern Ltd., New Delhi, 1992.							
3.	Erdman AG and Sandor G N, "Mechanism Design, Analysis and Synthesis", Vol.I, PHI Inc., 1997.							
4.	Ambekar A.G, "Mechanism and Machine Theory" Prentice Hall of India, New Delhi, 2007.							
5.	John Hannah and Stephens R C, "Mechanisms of Machines", Viva Low Price Student Edition, New Delhi, 1999.							
E-Ref	E-References:							
1.	https://archive.nptel.ac.in/courses/112/104/112104121/							

2.	https://nptel.ac.in/courses/112106270
3.	http://velhightech.com/Documents/ME8492 Kinematics of Machinery.pdf

	SE OUTCOMES: Ompletion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Demonstrate and understand the concepts of various mechanisms and pairs.	Apply
CO2	Analyze the velocity and acceleration of simple mechanisms.	Analyze
CO3	Construct the cam profile for various motion.	Create
CO4	Solve problems on gears and gear trains.	Evaluate
CO5	Evaluate the friction in transmission system	Evaluate

COURSE A	OURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	1									3	1	
CO2	3	2	2	1									3	1	
CO3	3	2	2	1									3	1	
CO4	3	2	2	1									3	1	
CO5	3	2	2	1									3	1	
Avg	3	2	2	1									3	1	
	3/2/1 – indicates strength of correlation (3 – High, 2- Medium, 1- Low)														

22M	EM06	HYDRAULICS AND PNEUMATICS					
PRE	-REQUIS	SITE: CATEGORY	PE	Cro	edit		3
		Hours/Week	L	Т	P]	ГΗ
		Hours/ week	3	0	0		3
Cour	rse Objec	tives:					
1.	To enab	le the students understand the basics of hydraulics and pneumatics					
2.	Applyin	g the working principles of hydraulic actuators and control components.					
3.	Designin	ng and develop hydraulic circuits and systems.					
4.	Applyin	g the working principles of pneumatic power system and its components.					
5.	Solving	problems and troubles in fluid power systems.					
UNI	ΓI	FLUID POWER PRINICIPLES AND HYDRAULIC PUMPS		9	0	0	9
Advai Proble	ntages, D ems.	ces of Hydraulic power; Pumping Theory – Pump Classification – Construction of Pumps – Fixed and Variable		emen	ıt pı	ımp	
UNI'	T II	TIVED ATTLE A CONTACODE AND CONTROL COMPONENTS		Α.	0	0	
Hydra motor Opera Symb	aulic Actua rs - Contro ation – Acc ools – Prob		Types,	Cons luid l	s - Hy tructi Powe	dra ion r A	uli an NS
Hydra motor Opera Symb UNI Accur	aulic Actuars - Contro ation – Accools – Prob FIII mulators, sifier, Air-o	ators: Cylinders – Types and construction, Application, Hydraulic cushioning – Rot Components: Direction Control, Flow control and pressure control valves – Scessories; Reservoirs, Pressure Switches – Filters – types and selection - Application	Types, ons – F ouble celerati	uators Cons Fluid I 9 - Pun on cir	onp, Fecuits	odra	uli an NS
Hydramotor Opera Symb UNIT Accur Intens of hyd	aulic Actuars - Contro ation – Accools – Prob F III mulators, sifier, Air-edraulic sys	ators: Cylinders – Types and construction, Application, Hydraulic cushioning – Rote Components: Direction Control, Flow control and pressure control valves – Coessories; Reservoirs, Pressure Switches – Filters – types and selection - Application blems. HYDRAULIC CIRCUITS AND SYSTEMS Intensifiers, Industrial hydraulic circuits – Regenerative, Pump Unloading, Dover oil, Sequence, Reciprocation, Synchronization, Fail - Safe, Speed Control, Dectems, Hydrostatic transmission, Electro hydraulic circuits – Servo and Proportional draulic servo systems.	Types, ons – F ouble celerati	uators Cons Tuid I 9 - Pun on cir s – A	onp, Pocuits	or A	uli an NS sur zin
Hydramotor Opera Symb UNI Accur Intens of hyd Mech UNI Prope Exhau	aulic Actuars - Control ation - Accools - Prob FIII mulators, sifier, Air-odraulic systanical, hyo FIV erties of airust Valves, cade methol	ators: Cylinders – Types and construction, Application, Hydraulic cushioning – Rote Components: Direction Control, Flow control and pressure control valves – Sessories; Reservoirs, Pressure Switches – Filters – types and selection - Application of the HYDRAULIC CIRCUITS AND SYSTEMS Intensifiers, Industrial hydraulic circuits – Regenerative, Pump Unloading, Dover oil, Sequence, Reciprocation, Synchronization, Fail - Safe, Speed Control, Decitems, Hydrostatic transmission, Electro hydraulic circuits – Servo and Proportiona	Types, ons – F	y Pun on cir s – A g rol Va ti cyli	onp, Focuits. police on one of the content of the	or A Press, Sizatio	uli an NS
Hydra motor Opera Symb UNIT Accur Intens of hyd Mech UNIT Prope Exhau - Caso proble	aulic Actuars - Control ation - Actual rs - Control ation - Actual r III mulators, sifier, Air-edraulic system anical, hyde rties of air ust Valves, cade method ems, Introd	Ators: Cylinders – Types and construction, Application, Hydraulic cushioning – Rotal Components: Direction Control, Flow control and pressure control valves – Coessories; Reservoirs, Pressure Switches – Filters – types and selection - Application blems. HYDRAULIC CIRCUITS AND SYSTEMS Intensifiers, Industrial hydraulic circuits – Regenerative, Pump Unloading, Dover oil, Sequence, Reciprocation, Synchronization, Fail - Safe, Speed Control, Dectems, Hydrostatic transmission, Electro hydraulic circuits – Servo and Proportional draulic servo systems. PNEUMATIC AND ELECTRO PNEUMATIC SYSTEMS T – Air preparation and distribution – Filters, Regulator, Lubricator, Muffler, Air Pneumatic actuators, Design of Pneumatic circuit – classification - single cylinder and – Integration of fringe circuits, Electro Pneumatic System – Elements – Ladder	Types, ons – F	y Pun on cir s – A g rol Va ti cyli	onp, Focuits. police on one of the content of the	or A Press, Sizatio	ulii an NS
Hydramotor Opera Symb UNI Accur Intens of hyd Mech Prope Exhau Case proble UNI Servo electr failure Lov	rs - Controlation - According - Problem - According - Problem - Pr	Ators: Cylinders – Types and construction, Application, Hydraulic cushioning – Rotal Components: Direction Control, Flow control and pressure control valves – Coessories; Reservoirs, Pressure Switches – Filters – types and selection - Application blems. HYDRAULIC CIRCUITS AND SYSTEMS Intensifiers, Industrial hydraulic circuits – Regenerative, Pump Unloading, Dover oil, Sequence, Reciprocation, Synchronization, Fail - Safe, Speed Control, Dectems, Hydrostatic transmission, Electro hydraulic circuits – Servo and Proportional draulic servo systems. PNEUMATIC AND ELECTRO PNEUMATIC SYSTEMS r – Air preparation and distribution – Filters, Regulator, Lubricator, Muffler, Air Pneumatic actuators, Design of Pneumatic circuit – classification - single cylinder and – Integration of fringe circuits, Electro Pneumatic System – Elements – Ladder duction to fluidics and pneumatic logic circuits.	Types, ons – F ouble celeration of multiple diagrams NG I Valve col. Flucture a	y Pun on cir s - A g rol Va ti cyli m - t g es, Int id por	o np, F cuits. pplic o normalizer o roduction o r	ordra ion r A ordra o	ulii an NS
Hydramotor Opera Symb UNI Accur Intens of hydramotor Mech Prope Exhau - Case proble UNI Servo electr failure - Lov	rs - Controlation - According - Problem - According - Problem - Pr	ators: Cylinders – Types and construction, Application, Hydraulic cushioning – Rot of Components: Direction Control, Flow control and pressure control valves – Teessories; Reservoirs, Pressure Switches – Filters – types and selection - Application blems. HYDRAULIC CIRCUITS AND SYSTEMS Intensifiers, Industrial hydraulic circuits – Regenerative, Pump Unloading, Decover oil, Sequence, Reciprocation, Synchronization, Fail - Safe, Speed Control, Decover oil, Sequence, Reciprocation, Synchronization, Fail - Safe, Speed Control, Decover oil, Sequence, Reciprocation, Synchronization, Fail - Safe, Speed Control, Decover oil, Sequence, Reciprocation, Synchronization, Fail - Safe, Speed Control, Decover oil, Sequence, Reciprocation, Electro hydraulic circuits – Servo and Proportional draulic servo systems. PNEUMATIC AND ELECTRO PNEUMATIC SYSTEMS T – Air preparation and distribution – Filters, Regulator, Lubricator, Muffler, Air Pneumatic actuators, Design of Pneumatic circuit – classification - single cylinder and Luction to fluidics and pneumatic logic circuits. DESIGN OF FLUID POWER CIRCUITS AND TROUBLESHOOTION Hydro mechanical servo systems, electro hydraulic servo systems and proportional content of the present of the	ouble celeration of multiple of the control of the celeration of t	9 Pun on cir s – A 9 rol Vati cyli m – t 9 ss, Int id po and tin nchro	s - Hy rowe O np, F cuits pplic O roduc wer c nnize	ordra ion r A ordra ion ordra	uli an NS
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Text B	Text Books:							
1.	Manjumdar S.R, "Oil Hydraulics", Tata McGraw-Hill, December 2002.							
2.	Anthony Esposito, "Fluid Power with Applications", Pearson Education 2013.							
Refere	ence Books:							
1.	Andrew Parr, "Hydraulic and Pneumatics", Jaico Publications House, 2005.							
2.	Bolton W. "Pneumatic and hydraulic system", Butterworth-Heinemann 1997							

3.	Majumdar S.R., "Pneumatic systems – Principles and maintenance", Tata McGraw Hill, 2010
4.	Shanmugasundaram.K, "Hydraulic and Pneumatic controls", Chand & Co, 2006
5.	Srinivasan.R. "Hydraulic and Pneumatic Controls", Vijay Nicole Imprints, 2008.
E-Refe	erences:
1.	http://www.fluidpowerjournal.com
2.	http://14.139.160.15/courses/112102011/2
3.	https://www.nfpa.com/home.htm

	SE OUTCOMES: ompletion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Select the components as per the application	Evaluate
CO2	Apply the working principles of hydraulic actuators and control components.	Apply
CO3	Design and develop hydraulic circuits and systems.	Create
CO4	Apply the working principles of pneumatic power system and its components.	Apply
CO5	Solve problems and troubles in fluid power systems.	Evaluate

COURSE A	OURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	1										1	1	1
CO2		2	2	1									1	1	1
CO3	1	2	3			1							1	2	1
CO4	1	1	3	2	2								2	1	1
CO5	1	1	2										1	1	1
Avg	1.25	1.4	2.2	1.5	2	1							1.2	1.2	1
		3/2	/1 – ir	dicat	es str	ength	of co	rrelati	on (3	– High,	2- Med	lium, 1-	Low)		

22M	EM07	DESIGN OF MACHINE ELEMEN	TS				
PRE	-REQUIS	SITE:	CATEGORY	PE	Cre	edit	3
1.		t should study engineering mechanics.		L	T	P	TH
2.	Studen	t should study kinematic of machinery.	Hours/Week	3	0	3	
Cou	rse Objec	tives:					
1.	Understa	anding of background in mechanics of materials and design of	of machine compone	nts.			
2.	An under	erstanding of the origins, nature and applicability of eations	empirical design pr	inciples,	based	l on	safet
3.	An unde	rstanding the design of shafts and couplings.					
4.	Familiar	ize the design of energy storing elements and engine compo	nents.				
5.	An appr performa	reciation of the relationships between component level deance	esign and overall m	achine sy	stem	desi	gn and
		STEADY STRESSES AND VARIABLE STR	PECCEC IN MA	CHINE		•	
based	duction to t	MEMBERS the design process – Product development cycle- factors infunical properties - Preferred numbers– Direct, Bending and	luencing machine de Torsional stress – In	esign, sele	d shoo	k loa	ding -
Introd based Calcu stress	duction to to duction to to duction duction of particular concentration of particular duction	MEMBERS the design process – Product development cycle- factors infinical properties - Preferred numbers– Direct, Bending and principle stresses for various load combinations, eccentric letion – design for variable loading – Soderberg, Goodman and	luencing machine de Torsional stress – Inoading – Factor of s	esign, sele	ction d show eories	of mack load	aterial ding
Introduced based Calcustress	duction to to duction to to duction to to duction of particles concentrated.	MEMBERS the design process – Product development cycle- factors infinical properties - Preferred numbers– Direct, Bending and principle stresses for various load combinations, eccentric lition – design for variable loading – Soderberg, Goodman an DESIGN OF SHAFTS AND COUPLINGS	luencing machine de Torsional stress – It oading – Factor of s d Gerber relations .	esign, sele mpact and eafety -the	ction d show	of mack load of fa	aterial ding ilure
Introd based Calcu stress UNI'	duction to to duction to to do not mechalation of posterior T II	MEMBERS the design process – Product development cycle- factors infinical properties - Preferred numbers– Direct, Bending and principle stresses for various load combinations, eccentric letion – design for variable loading – Soderberg, Goodman and	luencing machine de Torsional stress – It oading – Factor of s d Gerber relations .	esign, sele mpact and eafety -the	ction d show	of mack load of fa	nterial ding ilure
Introduction Introduction Calcustress UNI' Desig	duction to to duction to to do not mechalation of posterior T II	MEMBERS the design process – Product development cycle- factors infinical properties - Preferred numbers– Direct, Bending and principle stresses for various load combinations, eccentric lition – design for variable loading – Soderberg, Goodman an DESIGN OF SHAFTS AND COUPLINGS and hollow shafts based on strength, rigidity and critical specific process.	Tuencing machine de Torsional stress – In loading – Factor of s d Gerber relations.	esign, sele mpact and safety -the	ction d shoceories	of mack load of fa	oterial ding ilure
Introo based Calcustress UNI' Designigid UNI'	duction to to a duction to to a duction of possible concentrate. T II gn of solid and flexible T III	the design process – Product development cycle- factors infinical properties - Preferred numbers – Direct, Bending and principle stresses for various load combinations, eccentric letion – design for variable loading – Soderberg, Goodman and DESIGN OF SHAFTS AND COUPLINGS and hollow shafts based on strength, rigidity and critical spee couplings. DESIGN OF THREADED FASTENERS, RIV	Tuencing machine de Torsional stress – In loading – Factor of s ad Gerber relations .	esign, selempact and safety -the sand key	ction d show eories 9 ways	of mack load of fa	o 9 sign o
Introo based Calcustress UNI' Designigid UNI'	duction to to to to to mechanilation of proceedings concentrated and flexible T III anded fastenels and structure and structure to the total concentration of the total concentration	the design process – Product development cycle- factors infinical properties - Preferred numbers – Direct, Bending and principle stresses for various load combinations, eccentric letton – design for variable loading – Soderberg, Goodman an DESIGN OF SHAFTS AND COUPLINGS and hollow shafts based on strength, rigidity and critical spee couplings. DESIGN OF THREADED FASTENERS, RIV JOINTS ers - Design of bolted joints including eccentric loading – I	Thuencing machine de Torsional stress – In loading – Factor of stand Gerber relations. The deciding – Factor of stand Gerber relations. The deciding – Factor of standard stress – In loading – Factor of standard stress – In loading – In l	esign, selempact and safety -the sand key	ction d shoceories 9 ways	of mack load of fa	o 9 sign o
Introo based Calcustress UNI' Designigid UNI' Threatvesse UNI'	duction to to a duction to to a duction of possible concentrate of the	the design process – Product development cycle- factors infinical properties - Preferred numbers – Direct, Bending and principle stresses for various load combinations, eccentric letton – design for variable loading – Soderberg, Goodman an DESIGN OF SHAFTS AND COUPLINGS and hollow shafts based on strength, rigidity and critical spee couplings. DESIGN OF THREADED FASTENERS, RIV JOINTS ers - Design of bolted joints including eccentric loading – Dectures - theory of bonded joints. DESIGN OF ENERGY STORING ELEM	Thuencing machine de Torsional stress – In loading – Factor of stand Gerber relations. The eed – Design of keys of the control of the contro	esign, selempact and safety -the safety -t	ction d shoceories 9 ways 9 oints	of mack load of fa	o 9 cessur o 9
Introo based Calcustress UNI' Designigid UNI' Threatvesse UNI'	duction to the duction of process of the duction of process of the duction of process of the duction of the duc	the design process – Product development cycle- factors infinical properties - Preferred numbers – Direct, Bending and principle stresses for various load combinations, eccentric letton – design for variable loading – Soderberg, Goodman an DESIGN OF SHAFTS AND COUPLINGS and hollow shafts based on strength, rigidity and critical speciouplings. DESIGN OF THREADED FASTENERS, RIV JOINTS ers - Design of bolted joints including eccentric loading – Ectures - theory of bonded joints. DESIGN OF ENERGY STORING ELEM COMPONENTS f springs, optimization of helical springs - rubber springs - F	Thuencing machine de Torsional stress – In loading – Factor of stand Gerber relations. The eed – Design of keys of the control of the contro	esign, selempact and safety -the safety -t	ction d shoceories 9 ways 9 oints	of mack load of fa	o 9 cessur o 9
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Text 1	Text Books:							
1.	Bhandari V.B, "Design of Machine Elements", Tata McGraw Hill Book Co, 2020							
2.	Md.Jalaludeen.S, "A text book of Machine Design", Anuradha Publications, 2006							
Refer	rence Books:							
1.	Shigley, J.E. and Mischke, C.R., Mechanical Engineering Design, Fifth Edition, McGraw-Hill International; 1989.							
2.	Deutschman, D., Michels, W.J. and Wilson, C.E., Machine Design Theory and Practice, Macmillan, 1992.							
3.	Juvinal, R.C., Fundamentals of Machine Component Design, John Wiley, 1994.							
4.	PSG Tech, "Design Data Handbook", M/s.DPV Printers, Coimbatore, 2009							
E-Ref	E-References:							
1.	https://nptel.ac.in/courses/112105124							

Design of Machine Elements - V. B. Bhandari - Google Books

3. A Textbook of Machine Design by R.S.Khurmi And J.K.Gupta [tortuka]_1490186411865.pdf | DocDroid

	RSE OUTCOMES: ompletion of the course the student will be able to	Bloom's Taxonomy Mapped
CO1	Understand the influence of steady and variable stresses in machine component design.	Understand
CO2	Apply the concepts of design to shafts, keys and couplings.	Apply
CO3	Familiarize the design of temporary and permanent joints.	Understand
CO4	Design the various energy storing elements and engine components.	Analyse
CO5	Familiarize the design of various types of bearings.	Understand

COURSE .	ARTI	CUL	ATIO	N MA	ATRI	X									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	1	2		1	1				1		3	2	1
CO2	2	2	1	2		1	1				1		3	2	1
CO3	2	2	1	2		1	1				1		3	2	1
CO4	2	2	1	2		1	1				1		3	2	1
CO5	2	2	1	2		1	1				1		3	2	1
Avg	2.0	2.0	1.0	2.0		1.0	1.0				1.0		3.0	2.0	1.0
		3/2/	/1 – in	dicat	es str	ength	of cor	relatio	on (3	- High,	2- Med	ium, 1-	Low)		

PRER	M08	HEAT AND MASS TRANSFER						
	EQUIS	SITES CA	ATEGORY	PE	Cr	edit	3	
1.The la	aws and	basic concepts of thermodynamics	/TTT 1	L	T	P	TH	
		of energy transfers and their conversion principles	ours/Week	3	0	0	3	
COUR	RSE OB	SJECTIVES						
1.	Understanding the science behind conduction heat transfer and its applications.							
2.	Differe	ntiating the concepts of forced and natural convection heat transfer.						
3.	Describ	oing the laws and concepts of radiation heat transfer.						
4.	Unders	tanding phase change processes and analyzing heat exchangers.						
5.	Studyir	ng the concept of mass transfer process and its modes.						
UNI	I-T	CONDUCTION HEAT TRANSFER		9) (0	9	
UNI'	T-II	Extended Surfaces – Unsteady Heat Conduction – Lumped Analysis – Semi Infinite and Infinite Solic charts.						
OIII								
and ban	ık of tub	CONVECTION HEAT TRANSFER quations, boundary layer concept – Forced convection: external flow es. Internal flow – entrance effects.	– flow over pl	Ģ) (0	9	
and ban Free con	nk of tubenvection	CONVECTION HEAT TRANSFER quations, boundary layer concept – Forced convection: external flow es. Internal flow – entrance effects. —flow over vertical plate, horizontal plate, inclined plate, cylinders and	– flow over pl	Ģ) (0 0 ers, sp	9 phere	
and ban Free con UNIT	nk of tubenvection F-III es of Poo	CONVECTION HEAT TRANSFER quations, boundary layer concept – Forced convection: external flow es. Internal flow – entrance effects.	flow over pld spheres.asons in boiling	lates, cy	ylind	0 0 ers, sp	ohere 9	
and ban Free con UNIT	nvection r-III es of Pooger type:	CONVECTION HEAT TRANSFER quations, boundary layer concept – Forced convection: external flow es. Internal flow – entrance effects. —flow over vertical plate, horizontal plate, inclined plate, cylinders and BOILING, CONDENSATION AND HEAT EXCHANGER bl boiling and Flow boiling, Nusselt's theory of condensation- correlations.	flow over pld spheres.asons in boiling	lates, cy	ylind ylind	o o o o o o o o o o o o o o o o o o o	9 ohere	
and ban Free con UNIT Regime Exchan	r-III s of Pooger type: Γ-IV	CONVECTION HEAT TRANSFER quations, boundary layer concept – Forced convection: external flow es. Internal flow – entrance effects. —flow over vertical plate, horizontal plate, inclined plate, cylinders and BOILING, CONDENSATION AND HEAT EXCHANGER of boiling and Flow boiling, Nusselt's theory of condensation- correlatives - Overall Heat Transfer Co-efficient – Fouling Factors. LMTD and N	– flow over pld spheres. Solutions in boiling TU methods.	glates, cy	ylind	o o o o o o o o o o o o o o o o o o o	9 ohere	
and ban Free con UNIT Regime Exchan	r-III es of Pooger type: r-IV on laws	CONVECTION HEAT TRANSFER quations, boundary layer concept – Forced convection: external flow es. Internal flow – entrance effects. a –flow over vertical plate, horizontal plate, inclined plate, cylinders and BOILING, CONDENSATION AND HEAT EXCHANGER of boiling and Flow boiling, Nusselt's theory of condensation- correlatives – Overall Heat Transfer Co-efficient – Fouling Factors. LMTD and N RADIATION HEAT TRANSFER	– flow over pld spheres. Solutions in boiling TU methods.	glates, cy	ylindens (ds.	0 0 ers, sp 0 0 sation 0 0	gohere 9 . Hea	

TEXT	BOOKS:					
1	1 R.C. Sachdeva, "Fundamentals of Engineering Heat & Mass transfer", New Age International Publishers, 2017					
2	Frank P. Incropera and David P. Dewitt, "Fundamentals of Heat and Mass Transfer", John Wiley & Sons, 7th Edition, 2014.					
REFE	CRENCE BOOKS:					
1	Yunus A. Cengel, "Heat Transfer A Practical Approach" – Tata McGraw Hill, 5 th Edition - 2013					
2	Holman, J.P., "Heat and Mass Transfer", Tata McGraw Hill, 2017					
3	Kothandaraman, C.P., "Fundamentals of Heat and Mass Transfer", New Age International, New Delhi, 2012					
4	Ozisik, M.N., "Heat Transfer", McGraw Hill Book Co., 1994.					

	RSE OUTCOMES: mpletion of the course the student will be able to:	Bloom's Taxonomy Mapped
CO1	Analyze the mechanism of heat conduction under steady and transient conditions.	Apply
CO2	Develop solutions to problems involving convective heat transfer.	Create
CO3	Design a heat exchanger for any specific application.	Understand
CO4	Adopt the concept of radiation heat transfer in real time systems.	Understand
CO5	Develop solutions to problems involving combined heat and mass transfer.	Apply

COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	2		1						3	3	1
CO2	3	3	3	3	2		1						3	3	1
CO3	3	3	3	3	2		1						3	3	1
CO4	3	3	3	3	2		1						3	2	1
CO5	2	2	2	2	1		1						3	1	
Avg	2.8	2.8	2.8	2.8	1.8		1						3	2.4	1

DDEDEATIO	METROLOGY AND QUALITY CONTRO	L					
PREREQUISITES CATEGORY PE				Cr	edit	3	3
		Horus/Week	L	T	P	1	ГН
		Horus/ Week		0	0		3
COURSE O	BJECTIVES			•	•		
1.	Explaining the importance of measurements in engineering and the compute measurement uncertainty	ne factors affecting	g meası	ırem	ents	and t	to
2.	Applying the applications of linear and angular measuring instru	ments					
3.	Interpretation of various tolerance symbols.						
4.	Applying the SQC methods in manufacturing.						
5.	Applying the advances in measurements for quality control.						
		T G			0		
UNIT-I	BASICS OF MEASUREMENT SYSTEM AND DEVIC	ES		9	0	0	9
UNIT-II							
	CALIBRATION OF INSTRUMENTS AND QUALITY	STANDARDS		9	0	0	9
Calibration of	measuring instruments - principles of calibration, Calibration of Indial indicator, surface plates, slip gauges, care of gauge blocks. Gen	nstruments - Vern		per, l	Micr	ome	ter
Calibration of feeler gauges,	measuring instruments - principles of calibration, Calibration of In	astruments - Vern eral cares and rule		per, l	Micr	ome	ter
Calibration of feeler gauges,	measuring instruments - principles of calibration, Calibration of Indial indicator, surface plates, slip gauges, care of gauge blocks. Gen	nstruments - Vern neral cares and rule		per, l	Micr	ome	ter
Calibration of feeler gauges, 9000 quality st UNIT-III Angular measurement of the errors, base pin	measuring instruments - principles of calibration, Calibration of Indial indicator, surface plates, slip gauges, care of gauge blocks. Gen andards. Comparators- mechanical, electrical, optical and pneumatic	nstruments - Vern neral cares and rules. ELEMENTS nit gauge, design of the controlled CM ear measurement,	of plug	per, leasure 9 gauge of meding of	Microreme 0 ge, Tetric f con	omernt, Is	ter SC 9 or's
Calibration of feeler gauges, 9000 quality st UNIT-III Angular measurement of the errors, base pin	measuring instruments - principles of calibration, Calibration of Indial indicator, surface plates, slip gauges, care of gauge blocks. Genandards. Comparators- mechanical, electrical, optical and pneumatical geometrical protractors, sine bar, roundness measurement, lime basic types of limit gauges, Tomlinson surface meter, computed major, minor and effective diameters. Gear terminology; spur getch measurement. Principle of interferometry, laser interferometer,	nstruments - Vern neral cares and rules. ELEMENTS nit gauge, design of the controlled CM ear measurement,	of plug	per, leasure 9 gauge of meding of	Microreme 0 ge, Tetric f con	omernt, Is	ter SC 9 or's ad site
Calibration of feeler gauges, 9000 quality st UNIT-III Angular measurement of errors, base pit Inspection of s UNIT-IV Surface finish	measuring instruments - principles of calibration, Calibration of Indial indicator, surface plates, slip gauges, care of gauge blocks. Genandards. Comparators- mechanical, electrical, optical and pneumatical generations. GEOMETRICAL MEASUREMENT AND MACHINE arement - optical protractors, sine bar, roundness measurement, lime basic types of limit gauges, Tomlinson surface meter, computed major, minor and effective diameters. Gear terminology; spur getch measurement. Principle of interferometry, laser interferometer, traightness, flatness, roundness deviations.	extruments - Vern leral cares and rule. ELEMENTS nit gauge, design ler controlled CM ear measurement, Machine vision, I	of plug	per, leasure g gauge Come ing onenta	Microreme 0 ge, Tetric f con l of 0	omeont, IS Olivination of the control of the contr	ter SC 9 or's ad site
Calibration of feeler gauges, 9000 quality st UNIT-III Angular measurement of errors, base pit Inspection of s UNIT-IV Surface finish	measuring instruments - principles of calibration, Calibration of Indial indicator, surface plates, slip gauges, care of gauge blocks. Genandards. Comparators- mechanical, electrical, optical and pneumatical generations. GEOMETRICAL MEASUREMENT AND MACHINE The present - optical protractors, sine bar, roundness measurement, lime to basic types of limit gauges, Tomlinson surface meter, compute of major, minor and effective diameters. Gear terminology; spur getch measurement. Principle of interferometry, laser interferometer, traightness, flatness, roundness deviations. STATISTICAL QUALITY CONTROL — terminology and measurements — Optical measuring instruments —	extruments - Vern leral cares and rule. ELEMENTS nit gauge, design ler controlled CM ear measurement, Machine vision, I	of plug	per, leasure g gauge Come ing onenta	Microreme 0 ge, Tetric f con l of 0	omeont, IS Olivination of the control of the contr	9 or's ead site
Calibration of feeler gauges, 9000 quality st UNIT-III Angular measurement of errors, base pit Inspection of s UNIT-IV Surface finish Quality Control UNIT-V Six sigma: Def Control chart,	measuring instruments - principles of calibration, Calibration of Indial indicator, surface plates, slip gauges, care of gauge blocks. Genandards. Comparators- mechanical, electrical, optical and pneumatical optical protractors, sine bar, roundness measurement, lime basic types of limit gauges, Tomlinson surface meter, computed major, minor and effective diameters. Gear terminology; spur getch measurement. Principle of interferometry, laser interferometer, traightness, flatness, roundness deviations. STATISTICAL QUALITY CONTROL — terminology and measurements — Optical measuring instruments—of - Control charts - Sampling plans.	eral cares and rule. ELEMENTS nit gauge, design er controlled CM ear measurement, Machine vision, I Acceptance test	of plug M. ISO checki rundan for mac	per, deasured a second of the	Microreme O ge, T con l of C O m, Bo	O Saylo thre mpos GD& O natisti	gor's addsite

TEXT	TEXT BOOKS:								
1	1 Gupta.I.C, —A text book of Engineering Metrology, Dhanpat Rai publications, New Delhi, 2018								
2	2 Beckwith.T.G, Roy D. Marangoni, John H. Lienhard, - Mechanical Measurements, Prentice Hall, 2006								
REFE	REFERENCE BOOKS:								
1	Jain.R.K, —Mechanical and Industrial Measurements, Khanna Publishers, Delhi, 1999.								
2	Holmen.J.P, —Experimental Methods for Engineersl, Tata McGraw Hill Publications Co Limited, 2017.								
3	Grant, E.L., Statistical Quality Control, Mc Graw-Hill, 2004. 3. Doeblin E.O., Measurement Systems, Mc Graw-Hill, 2004.								

4	Alan S Morris, —Measurement and Instrumentation Principles, Butterworth, 2006.						
5	De Feo J A and Barnard W W, —Six Sigma: Break trough and BeyondG, Tata McGraw-Hill, New Delhi, 2005.						
E-REF	ERENCES:						
1	https://nitsri.ac.in/Department/Mechanical%20Engineering/MEC_405_Book_2,_for_Unit_2B.pdf						
2	https://www.nist.gov/system/files/documents/srm/NIST-SRM-RM-Articlefinal.pdf						
3	https://www.researchgate.net/publication/319587859_Computer-Aided_Metrology-CAM						

	RSE OUTCOMES: mpletion of the course the student will be able to:	Bloom's Taxonomy Mapped
CO1	Explain the importance of measurements in engineering and the factors affecting measurements and to compute measurement uncertainty.	Understand
CO2	Apply the working principle and the applications of linear and angular measuring instruments.	Apply
CO3	Interpret of various tolerance symbols.	Apply
CO4	Apply the SQC methods in manufacturing.	Apply
CO5	Apply the advances in measurements for quality control in manufacturing industries.	Apply

COURSE	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1							2	1	2				2	1	
CO2							3	1	2				1	2	
CO3							2	1					2	1	
CO4				3			2		1				1	2	
CO5				2				3	1				2	1	
Avg				2.5			2.25	1.5	1.5				1.6	1.4	
		3/2/	/1 – in	dicate	es str	ength	of cor	rrelati	on (3	– High,	2- Med	lium, 1-	Low)		1

22	2MEM	DYNAMICS OF MACHINERY						
PR	REREQ	UISITES	CATEGORY	PE	Cre	dit	3	
				L	ТР		TH	
Eng	gineering	g Mechanics, Kinematics of Machinery, Strength of Materials	Hours\Week	3	0	0	3	
CO	OURSE	OBJECTIVES:			<u> </u>			
1.	To impart students with the knowledge about motion, masses and forces in machines and the Principle of Virtual Wor							
2.	To fac	cilitate the students, to understand the concept of balancing of rota	ting and reciprocating	masses	S.			
3.	To tea	ch concepts of free vibration analyses of one and two degree-of-fr	reedom rigid body sys	tems				
4.		ach concepts of forced vibrations analyses of rigid body systemenon of vibration and its effects.	ns and to give aware	eness to	o stud	ents	on th	
	T. 1	1						
5.	10 lea	rn about the concept of various types of governors.						
Ul Stat D'A Mo	NIT I atic Force Alembert oment Dia	FORCE ANALYSIS e Analysis, Free Body Diagrams, Conditions of Two, Three a t's Principle – Inertia Force Analysis in Reciprocating Engines agrams and Fluctuation of Energy of reciprocating engine mechan	- Crank Shaft Torqu	ue. Fly	wheel	s – T	es an	
Stat D'A Mo Spe	NIT I atic Force Alembert benent Dia eed, Wei	FORCE ANALYSIS e Analysis, Free Body Diagrams, Conditions of Two, Three att's Principle – Inertia Force Analysis in Reciprocating Engines agrams and Fluctuation of Energy of reciprocating engine mechanght of Flywheel Required.	- Crank Shaft Torqu	bers. In the second sec	nertia wheel ion of	Force s – T Energ	es an urnir gy an	
Stat D'A Mo Spe UN	ntic Force Alembert oment Dieed, Weig NIT II	FORCE ANALYSIS e Analysis, Free Body Diagrams, Conditions of Two, Three a t's Principle – Inertia Force Analysis in Reciprocating Engines agrams and Fluctuation of Energy of reciprocating engine mechan	Crank Shaft Torquisms, Coefficient of F gle cylinder Engine -	bers. In the second sec	nertia wheel ion of	Force S - T Energy	es an urnin gy an	
Stat D'A Mo Spe UN Stat Eng	ntic Force Alembert oment Dieed, Weig NIT II	FORCE ANALYSIS e Analysis, Free Body Diagrams, Conditions of Two, Three att's Principle – Inertia Force Analysis in Reciprocating Engines agrams and Fluctuation of Energy of reciprocating engine mechanght of Flywheel Required. BALANCING lynamic balancing - Balancing of rotating masses - Balancing a sin	Crank Shaft Torquisms, Coefficient of F gle cylinder Engine -	bers. In the second sec	nertia wheel ion of	Force S - T Energy	urnin gy an	
Stat D'A Mo Spe UN Stat Eng UN Bas Free Sys	INIT I Intic Force Alembert Diment Die Leed, Weig NIT II Intic and d Intic	FORCE ANALYSIS e Analysis, Free Body Diagrams, Conditions of Two, Three at t's Principle – Inertia Force Analysis in Reciprocating Engines agrams and Fluctuation of Energy of reciprocating engine mechanght of Flywheel Required. BALANCING lynamic balancing - Balancing of rotating masses - Balancing a singertial balancing in locomotive Engines - Balancing linkages - - balancing linka	- Crank Shaft Torquisms, Coefficient of Facilities, Coefficient of Faciliti	bers. In ue. Fly Fluctuat 9 Balanci 9 ration of Single	nertia wheel ion of 0 ing M 0 f Bear Degr	Forces — T Energy Oulti-cy Oms — Nee Free Free	es an urningy an gy linde	
State D' A Moo Spee UN State Eng UN Bass Free Sys	INIT I Intic Force Alembert Diment Die Leed, Weig NIT II Intic and d Intic	FORCE ANALYSIS e Analysis, Free Body Diagrams, Conditions of Two, Three as it's Principle – Inertia Force Analysis in Reciprocating Engines agrams and Fluctuation of Energy of reciprocating engine mechanght of Flywheel Required. BALANCING Iynamic balancing - Balancing of rotating masses - Balancing a sineratial balancing in locomotive Engines - Balancing linkages - balancing of Vibratory Systems – Types – Single Degree of Freedom Systems of Vibratory Systems – Types – Single Degree of Freedom Systems – Types – Single Degree of Freedom Systems of Damping – Free Vibration with Viscous Damping, Critical Speed - Damping of Damping – Free Vibration with Viscous Damping, Critical Speed - Critical Speed - Damping of Damping – Free Vibration with Viscous Damping, Critical Speed - Critical Speed - Damping of Damping – Free Vibration with Viscous Damping, Critical Speed - Damping - Free Vibration with Viscous Damping, Critical Speed - Damping - Free Vibration with Viscous Damping, Critical Speed - Damping - Free Vibration with Viscous Damping, Critical Speed - Damping - Free Vibration with Viscous Damping - Free Vibration - Free Vibra	- Crank Shaft Torquisms, Coefficient of Facilities, Coefficient of Faciliti	bers. In ue. Fly Fluctuat 9 Balanci 9 ration of Single	nertia wheel ion of 0 ing M 0 f Bear Degr	Forces — T Energy Oulti-cy Oms — Nee Free Free	es an urningy an gy linde	
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Total (45L) = 45 Periods

TE	XT BOOKS:
1.	Design of Machinery, Fourth Edition, by R.L. Norton, McGraw Hill, 2007
2.	Mechanical Vibration, V.P.Singh, Dhanpatrai, Delhi
RE	FERENCE BOOKS:
1.	Ballaney, P.L., "Theory of Machines and Mechanisms", Khanna Publishers, New Delhi, 2002.
2.	Shigley, J.E. and Uicker, J.J., "Theory of Machines and Mechanisms", TMH ND, 1998.
3.	Amithabha Ghosh, and Ashok Kumar Malik., "Theory of Mechanisms and Machines", 2nd Ed., Affiliated East and West Press Limited, 1998.
4.	Prof.Nakara, IIT-Delhi Reference Books
E-R	REFERENCES:
1.	www.university.youth4work.com/IIT_Kharagpur_Indian-Institute-of-Technology/study/1653-dynamics-of-Machinery-ebook

2. http://nptel.ac.in/courses/112104114/

	RSE OUTCOMES: mpletion of the course the student will be able to	Bloom's Taxonomy Mapped
CO1	Apply basic principles of mechanisms in mechanical system.	Apply
CO2	Familiarize the static and dynamic analysis of simple mechanisms.	Understand
CO3	Analyze the mechanical systems subjected to free vibration.	Analyze
CO4	Analyze mechanical systems subjected to forced vibration.	Analyze
CO5	Analyze the various types of governors and its speed control mechanism.	Analyze

COURSE A	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	3	3	1					1		3	2	1	2
CO2	2	2	3	2	1					1		3	2	1	2
CO3	2	2	3	2						1		3	2	1	2
CO4	2	2	3	2	1					1		3	2	1	2
CO5	1	2	3	2						1		3	2	1	1
Avg	1.8	2.0	3.0	2.2	1					1.0		3.0	2.0	1.0	1.8
	•	3/2	2/1 – iı	ndicat	tes str	ength	of co	rrelati	on (3 -	- High,	2- Medi	ium, 1-	Low)	•	

22MTM01	ADVANCED PHYSICAL METALL	URGY	S	emeste	r							
PREREQUISI	ΓES	Category	OE	Cre	edit	3						
Engineering pl	weiec		L	T	P	TH						
Engineering pi	iysics	Hours/Week	3	3								
Course Learnin	ng Objectives		<u> </u>			<u> </u>						
1 To impa	rt knowledge on the crystal structure, diffusion, phase	diagrams for vario	ous eng	ineerin	g matei	rials.						
Unit I	CRYSTAL STRUCTURES		9	0	0	9						
	• •	-	-									
Review of atomic bonds, Lattice, unit cell, crystal systems and Bravais lattices; Principal crystal structures – BCC, FCC, HCP and its characteristics; Miller indices for crystallographic planes and directions, interplanar spacing;												

crystal and polycrystalline and amorphous materials; isotropy and anisotropy; Simple problems in the above topics

Unit II CRYSTALLINE IMPERFECTIONS

Types of point defects, effect of temperature on vacancy concentration, interstitial sites-octahedral and tetrahedral sites; Line defects - dislocations - Edge, screw and mixed dislocations, Burger's vector, slip and twinning; Planar defects - grain boundaries, tilt boundaries, small angle grain boundaries; ASTM grain size number, grain size determinations; Volume defects; Simple problems in the above topics.

Unit III ATOMIC DIFFUSION IN SOLIDS AND SOLIDIFICATION 0 OF METAL

Diffusion mechanisms, steady state diffusion and non-steady state diffusion-Fick's first law and second law; Kirkendall effect and Darken's equation; Factors affecting diffusion; Industrial applications of diffusion processes; Simple problems in the above topics; Basic principles of solidification of metals and alloys; Growth of crystals-Planar growth, dendritic growth, Solidification time, dendrite size; Cooling curves; Cast or Ingot structure, Solidification defects - Control of casting structure; Directional solidification - single crystal growth; Simple problems in the above topics.

Unit IV PHASE DIAGRAMS 0 0 9

Phases, solid solution types, compounds, Hume-Rothery rules; Gibb's phase rule; Phase diagram determination; Binary isomorphous alloy systems – composition and amount of phases, development of microstructure – equilibrium and non-equilibrium cooling- Coring and its effects, homogenization; Binary eutectic system - composition and amount of phases, development of microstructure; Eutectoid, Peritectic and monotectic reaction, Phase diagrams with intermediate phases and compounds; Ternary phase diagrams. Simple problems in the above topics.

Unit V IRON-CARBON PHASE DIAGRAM 0 0

Iron-carbon diagram, Phases in Fe-C system, Invariant reactions, Microstructure of slowly cooled steels, composition and amount of phases, Effect of Alloying elements on Fe-C system, Type, structure, properties and applications of Plain Carbon Steels and different types of Cast iron; IS Specification for Steels and Cast Irons, Simple problems in above topics.

Total (45+0) = 45 Hours

Text Books: Donald R. Askeland,"The Science and Engineering of Materials", Thomson Learning, India Edition, 2007. 1 William D.Callister, "Materials Science and Engineering – An Introduction", 4th edition, JohnWiley & Sons, New York, USA, 1997. **Reference Books:**

1	Avner S H."An Introduction to Physical Metallurgy", McGraw Hill Book Co, New York, USA, 1997.
2	Donald R Askeland," Essentials of Material Science and Engineering ", Thomson Learning, India Edition, 2007
3	Raghavan V., "Physical Metallurgy – Principles and Practice", Prentice Hall of India Ltd., New Delhi, 199.
	William F.Smith, "Foundations of Materials Science and Engineering", Second Edition, McGraw-Hill Inc, New York, 1993.

	-	utcomes: npletion of this course, the students will be able to:	Bloom's Taxonomy Mapped
CO1		Describe the basic crystal structure, orientation and their influence on macroscopic properties.	L2: Understanding
CO2	:	Discuss the role of imperfections in strengthening the materials.	L2: Understanding
CO3	:	Diagonise the diffusion mechanism in solidification of materials under different conditions.	L4:Analysing
CO4	:	Apply the concept of phase diagrams in equilibrium transformation of materials phases.	L3:Applying
CO5	:	Construct the Fe-Fe ₃ C phase diagram and discuss various properties of steel and cast iron.	L3:Applying

COURS	E ART	ICULA	TION	MATR	<u>IX</u>											
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	1	1		1	1								1		1	
CO2	1	1				1	1						1			1
CO3	1	1	1	1		1							1	1		
CO4	1	1		1	1								1			
CO5	1	1		1									1			1
Avg.	1.0	1.0	1.0	1.0	1.0	1.0	1.0						1.0	1.0	1.0	1.0
						3/2/1-ir	dicates	strengt	h of cor	relation ((3- High,	2-Mediu	ım, 1- Lo	w)		

Category Hours/Week	OE L 3	Т	edit P	3 TH						
Hours/Week		T								
Hours/Week	3	T P 0 0	2							
	I	<u>l</u>								
he field of Metal	lurgy a	nd ma	terials	; and						
NERGY	9									
N tl	NERGY h and state pr	TERGY 9 h and state propertie	TERGY 9 0 h and state properties, The	TERGY 9 0 0 h and state properties, Thermody esses. First law of thermodynamics						

and work, Internal energy, Heat capacity of materials, Cp-Cv relations, Nernst Equation, Enthalpy, Thermochemistry Hess's law, Kirchoff's law, Maximum flame temperature.

ENTROPY AND AUXILARY FUNCTIONS 9 **Unit II** 0

Second law of thermodynamics: Carnot cycle, Entropy - Statistical interpretation of entropy, Free energy, Combined statement of first and second laws, Thermodynamic functions - Maxwell's relations, Gibbs Helmholtz equation. Third and Zeroth laws of thermodynamics: Definition, concept and applications

THERMODYNAMIC POTENTIALS AND PHASE **Unit III** 0 0 9 **EQUILIBRIA**

Thermodynamic potentials: Fugacity, Activity and Equilibrium constant. Clausius - Clayperon equation, Troutons rule. Le Chatelier's principle, Vant Hoff's equation. Equilibria in phase diagrams: Phase rule, Phase stability, Thermodynamics of surfaces, interfaces and defects, P-G-T diagrams, Application of free energy - composition diagrams to the study of alloy systems.

THERMODYNAMICS OF SOLUTIONS **Unit IV** 0

Gibbs - Duhem equation, Partial and integral molar quantities, chemical potential, Ideal solutions - Raoult's law, Real solutions, Activity coefficient, Henry's law, Alternative standard states, Sievert's law, Mixing functions and excess functions, Regular solutions, Applications of Gibbs - Duhem equation.

Unit V THERMODYNAMICS OF REACTIONS AND KINETICS 0 0 9

Electro chemical process: Cells, Interconversion of free energy and electrical work, Determination of thermodynamic quantities using reversible cells, Solid electrolytic cells. Kinetics: First, Second and third order reactions, Arrhenius equation - activation energy, Determination of order of the reaction.

Tex	xt Books:
1	Upadhyaya G S and Dube R K., "Problems in Metallurgical Thermodynamics & Kinetics", Pergamon, 1977.
2	Ahindra Ghosh, Text book of Materials & MetallurgicalThermodynamics, Prentice Hall India, 2002
3	. David R Gaskell, "Introduction to the Thermodynamics of Materials", Fifth Edition, Taylor & Francis, 2008

Ref	erence Books:
1	David V Ragone, "Thermodynamics of Materials - Volume-1", John Wiley & Sons, Inc. 1995.
2	Dr S.K Dutta,Prof A.B.Lele – Metallurgical thermodynamics kinetics and numericals,S.Chand& co Ltd.,New Delhi 2011

3	Darken LS and Gurry R W,"Physical Chemistry of Metals", CBS publications and distributors, 2002.
4	Parker R H, "An introduction to chemical metallurgy", Pergamon press, New York, second edition, 1978.
5	Kapoor M.L., "Chemical and Metallurgical Thermodynamics Vol. I and II", Nem Chand, 1st Ed., 1981

		utcomes: appletion of this course, the students will be able to:	Bloom's Taxonomy Mapped
CO1		Discuss the fundamental concepts of thermodynamics and internal energy	L2: Understanding
CO2	:	State the thermodynamics entropy and auxiliary functions.	L2: Understanding
CO3	:	Identify the basic laws, chemical potential and phase equilibria.	L4:Analysing
CO4	:	Describe the thermodynamics of the solution and various important equations.	L2: Understanding
CO5		Apply to solve problems related to electrochemical processes and kinetics.	L3:Applying

COURS	COURSE ARTICULATION MATRIX															
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	1	1		1	1								1	1		
CO2	1	1	1										1		1	
CO3	1	1		1	1								1			
CO4	1			1	1								1		1	1
CO5	1	1				1	1						1		1	
Avg.	1.0	1.0	1.0	1.0	1.0	1.0	1.0						1.0	1.0	1.0	1.0
						3/2/1-ir	dicates	strengt	h of cor	relation ((3- High,	2-Mediu	ım, 1- Lo	w)		

22M	TM03	MECHANICAL BEHAVIOUR OF MAT	TERIALS	S	Semeste	r	
PREF	REQUISI	ΓES		OE	Cre	edit	3
Fngin	neering pl	nyciec	Hours/Week	L	Т	P	ТН
Engin	ieering pi	3	0	0	3		
Cours	se Learni	ng Objectives			I		
1	To knov	v the fundamental concepts of deformation behaviour for	or structural engin	eering	applica	tions.	
U	nit I	DISLOCATIONS AND PLASTIC DEFORMATION	ON	9	0	0	9
Streng	gth of per	fect crystal and need for dislocations; Characteristics	s of dislocations	– Edg	e dislo	cation.	Screw
_		ger's vector, mixed dislocation, dislocation loops; Move		_	•		
		ions in FCC, HCP and BCC lattice; Stress fields and er					_
		islocation density; Intersections of dislocations – J	-				
		-ups; Deformation by slip and twinning; Critical resolv	•				-
	and kink		ou sirour suress, 2	0101111			
U	nit II	STRENGTHENING MECHANISMS		9	0	0	9
Strain	hardenin	g; Grain boundary strengthening; Solid solution stre	ngthening - yield	l-point	pheno	menon	, strain
		g; Grain boundary strengthening; Solid solution stre tation hardening - Conditions for precipitation hard		•	•		
ageing	g; Precipi	• • •	dening, Ageing,	Forma	ation of	f preci	pitates,
ageing coarse	g; Precipi ening of p	tation hardening - Conditions for precipitation hard	dening, Ageing, rengthening; Fibe	Forma er stren	ation of	f precing; Ma	pitates, rtensite
ageing coarse streng	g; Precipi ening of pathening -	tation hardening - Conditions for precipitation hard recipitates, Mechanism of strengthening; Dispersion st	dening, Ageing, rengthening; Fibe	Forma er stren	ation of	f precing; Ma	pitates, rtensite
ageing coarse streng effects	g; Precipi ening of pathening -	tation hardening - Conditions for precipitation hard recipitates, Mechanism of strengthening; Dispersion st examples for above strengthening mechanisms from fe	dening, Ageing, rengthening; Fibe	Forma er stren	ation of	f precing; Ma	pitates, rtensite
ageing coarse streng effect;	g; Precipi ening of p thening - ; Preferred nit III	tation hardening - Conditions for precipitation hardening recipitates, Mechanism of strengthening; Dispersion st examples for above strengthening mechanisms from fell orientation; Sever plastic deformation.	dening, Ageing, rengthening; Fiberrous and non-fer	Forma er strer crous s	nation of one of the original original of the original	f precing; MaBausc	pitates, rtensite hinger
ageing coarse streng effect: Ur Types	g; Precipi ening of pa thening - ; Preferred it III	tation hardening - Conditions for precipitation hardening in the recipitates, Mechanism of strengthening; Dispersion streamples for above strengthening mechanisms from feature and provided in the recipitation. FRACTURE AND FRACTURE MECHANICS	dening, Ageing, rengthening; Fibe errous and non-fer	Forma er strer crous s	otion of other or oth	f precing; Ma Bausc Metall	pitates, rtensite hinger 9
ageing coarse streng effect: Ur Types factor	g; Precipi ening of pa thening - ; Preferred nit III s of fractures affecting	tation hardening - Conditions for precipitation hardening recipitates, Mechanism of strengthening; Dispersion st examples for above strengthening mechanisms from fell orientation; Sever plastic deformation. FRACTURE AND FRACTURE MECHANICS re – ductile and brittle fracture, Ductile to Brittle Tra	dening, Ageing, rengthening; Fibe errous and non-fermansition Temperatement and other	Forma er strer rrous s 9 ture (I embri	ontion of the property of the	f precing; Ma Bausc 0 Metall tt, The	pitates, rtensite chinger 9 lurgical oretical
ageing coarse streng effect: Ur Types factor cohesi	g; Precipi ening of pa thening - ; Preferred it III s of fractures affecting ive streng	tation hardening - Conditions for precipitation hardening in the recipitates, Mechanism of strengthening; Dispersion strengthening mechanisms from fell orientation; Sever plastic deformation. FRACTURE AND FRACTURE MECHANICS re – ductile and brittle fracture, Ductile to Brittle Trage DBTT, determination of DBTT, Hydrogen embrittle	dening, Ageing, rengthening; Fibe errous and non-fermansition Temperatement and other rowan's modifica	Forma er strer trous s 9 ture (I embrition. I	ontion of the original origina	f precing; Ma Bausc 0 Metallat, Theorem	pitates, rtensite hinger 9 lurgical oretical anics -
ageing coarse streng effect: Ur Types factor cohesi introd	g; Precipi ening of parthening - ; Preferred nit III s of fractures affecting ive streng fuction, m	tation hardening - Conditions for precipitation hardening in the recipitates, Mechanism of strengthening; Dispersion strengthening mechanisms from fell orientation; Sever plastic deformation. FRACTURE AND FRACTURE MECHANICS are – ductile and brittle fracture, Ductile to Brittle Tracting DBTT, determination of DBTT, Hydrogen embrittle the of metals, Griffith's theory of brittle fracture, On	dening, Ageing, rengthening; Fibe errous and non-fermansition Temperatement and other rowan's modifica	Forma er strer trous s 9 ture (I embrition. I	ontion of the original origina	f precing; Ma Bausc 0 Metallat, Theorem	pitates, rtensite hinger 9 lurgical oretical anics -
ageing coarse streng effect: Ur Types factor cohest introd determ	g; Precipi ening of parthening - ; Preferred nit III s of fractures affecting ive streng fuction, m	tation hardening - Conditions for precipitation hardening between the conditions and strengthening; Dispersion strengthening mechanisms from for above strengthening mechanisms from for a condition; Sever plastic deformation. FRACTURE AND FRACTURE MECHANICS The ductile and brittle fracture, Ductile to Brittle Traction of DBTT, Hydrogen embrittle that of metals, Griffith's theory of brittle fracture, On anodes of fracture, stress intensity factor, strain encodes	dening, Ageing, rengthening; Fibe errous and non-fermansition Temperatement and other rowan's modifica	Forma er strer trous s 9 ture (I embrition. I	ontion of the original origina	f precing; Ma Bausc 0 Metallat, Theorem	pitates, rtensite hinger 9 lurgical oretical anics -
ageing coarse streng effect: Ut Types factor cohesi introd determ Ut	g; Precipi ening of precipi gthening - gthening - g; Preferred nit III s of fractures affecting ive streng duction, manination of nit IV	tation hardening - Conditions for precipitation hardening in the recipitates, Mechanism of strengthening; Dispersion strengthening mechanisms from fell orientation; Sever plastic deformation. FRACTURE AND FRACTURE MECHANICS re – ductile and brittle fracture, Ductile to Brittle Traction of DBTT, Hydrogen embrittle that of metals, Griffith's theory of brittle fracture, Oriendes of fracture, stress intensity factor, strain energy for KIC, introduction to COD, J integral.	dening, Ageing, rengthening; Fibe errous and non-fermansition Temperatement and other towan's modificatergy release rate	Forma er strer trous s 9 ture (I embrition. I e, frace	ontion of agthenia ystems, on the original of	f precing; Ma Bausc 0 Metall tt, Thee e mech ughnes	pitates, rtensite shinger 9 lurgical oretical sanics - ss and
ageing coarse streng effect: Ur Types factor cohest introd determ Ur Fatigu	g; Precipi ening of parthening - ; Preferred nit III s of fractures affecting ive streng fuction, maintaion of nit IV ne: Stress of	tation hardening - Conditions for precipitation hardening in the recipitates, Mechanism of strengthening; Dispersion strengthening mechanisms from featorientation; Sever plastic deformation. FRACTURE AND FRACTURE MECHANICS The results of determination of DBTT, Hydrogen embrittle that of metals, Griffith's theory of brittle fracture, Ornodes of fracture, stress intensity factor, strain end for KIC, introduction to COD, J integral. FATIGUE BEHAVIOUR AND TESTS	dening, Ageing, rengthening; Fibe errous and non-ference and in Temperatement and other rowan's modificatergy release rate and fatigue, structums	Forma er strer trous s 9 ture (I embrition. I e., frace	ontion of anythening stems, on the state of	f precing; Ma Bausco Metall at, Thee mechangements O ccompa	pitates, rtensite shinger 9 lurgical coretical sanics - ss and 9 anying
ageing coarse streng effect: Un Types factor cohest introd determ Un Fatigut	g; Precipi ening of pr ethening - ; Preferred nit III s of fractu es affecting ive streng duction, m mination o nit IV ne: Stress of e, cumulat	tation hardening - Conditions for precipitation hardening recipitates, Mechanism of strengthening; Dispersion streamples for above strengthening mechanisms from fell orientation; Sever plastic deformation. FRACTURE AND FRACTURE MECHANICS re – ductile and brittle fracture, Ductile to Brittle Trage DBTT, determination of DBTT, Hydrogen embrittle the of metals, Griffith's theory of brittle fracture, Ondoes of fracture, stress intensity factor, strain end for KIC, introduction to COD, J integral. FATIGUE BEHAVIOUR AND TESTS cycles, S-N curves, effect of mean stress, factors affecting the content of	dening, Ageing, rengthening; Fibe errous and non-ference and in Temperatement and other rowan's modificatergy release rate and fatigue, structums	Forma er strer trous s 9 ture (I embrition. I e., frace	ontion of anythening stems, on the state of	f precing; Ma Bausco Metall at, Thee mechangements O ccompa	pitates, rtensite chinger 9 lurgical coretical canics - as and 9 anying
ageing coarse streng effect: Ur Types factor cohesi introd determ Ur Fatigu fatigu crack	g; Precipi ening of pr ethening - ; Preferred nit III s of fractu es affecting ive streng duction, m mination o nit IV ne: Stress of e, cumulat	tation hardening - Conditions for precipitation hardening recipitates, Mechanism of strengthening; Dispersion strengthening mechanisms from fell orientation; Sever plastic deformation. FRACTURE AND FRACTURE MECHANICS Tree—ductile and brittle fracture, Ductile to Brittle Trage DBTT, determination of DBTT, Hydrogen embrittle, the of metals, Griffith's theory of brittle fracture, Ondoes of fracture, stress intensity factor, strain ender for KIC, introduction to COD, J integral. FATIGUE BEHAVIOUR AND TESTS Trycles, S-N curves, effect of mean stress, factors affective damage, HCF / LCF, thermo-mechanical fatigue, a	dening, Ageing, rengthening; Fibe errous and non-ference and in Temperatement and other rowan's modificatergy release rate and fatigue, structums	Forma er strer trous s 9 ture (I embrition. I e., frace	ontion of anythening stems, on the state of	f precing; Ma Bausco Metall at, Thee mechangements O ccompa	pitates, rtensite chinger 9 lurgical coretical canics - as and 9 anying
ageing coarse streng effect: Ur Types factor cohest introd determ Ur Fatigu fatigu crack Ur	g; Precipi ening of posthening - ; Preferred nit III s of fractu s affecting ive streng fuction, m mination of nit IV ne: Stress of e, cumulat propagation init V	tation hardening - Conditions for precipitation hardening recipitates, Mechanism of strengthening; Dispersion strengthening mechanisms from fell orientation; Sever plastic deformation. FRACTURE AND FRACTURE MECHANICS Tree — ductile and brittle fracture, Ductile to Brittle Traction of DBTT, Hydrogen embrittle that of metals, Griffith's theory of brittle fracture, Ondoes of fracture, stress intensity factor, strain end for KIC, introduction to COD, J integral. FATIGUE BEHAVIOUR AND TESTS Eycles, S-N curves, effect of mean stress, factors affective damage, HCF / LCF, thermo-mechanical fatigue, a con, fatigue testing machines.	dening, Ageing, rengthening; Fibe errous and non-ference and in the rowan's modificate ergy release rate and fatigue, structupplication of fract	Forma er strer trous s 9 ture (I embrition. I e., frace 9 aral character materials	ontion or agthering stems, or a structure to the control of the co	f precing; Ma Bausco Metall at, There mechangements Occompass to fat	pitates, rtensite shinger 9 lurgical coretical sanics - ss and sanying igue
ageing coarse streng effect: Ur Types factor cohesi introd determ Ur Fatigu fatigu crack Ur Creep	g; Precipi ening of posthening - ; Preferred nit III s of fractures affecting ive streng duction, menination of nit IV ue: Stress of e, cumulate propagation nit V of curve, se	tation hardening - Conditions for precipitation hardening recipitates, Mechanism of strengthening; Dispersion streamples for above strengthening mechanisms from fell orientation; Sever plastic deformation. FRACTURE AND FRACTURE MECHANICS re – ductile and brittle fracture, Ductile to Brittle Trage DBTT, determination of DBTT, Hydrogen embrittle the of metals, Griffith's theory of brittle fracture, Ondoes of fracture, stress intensity factor, strain end for KIC, introduction to COD, J integral. FATIGUE BEHAVIOUR AND TESTS cycles, S-N curves, effect of mean stress, factors affecting the damage, HCF / LCF, thermo-mechanical fatigue, a con, fatigue testing machines. CREEP BEHAVIOUR AND TESTS	dening, Ageing, rengthening; Fibe errous and non-ferencement and other rowan's modificatergy release rate and fatigue, structupplication of fractions during changes during of	Forma er strer trous s 9 ture (I embrition. I e, frace 9 ural chaure months are personnel e, frace	ontion or negthening stems, on the state of	f precing; Ma Bausc O Metall tt, There mechalled to the secomposition of the second of the s	pitates, rtensite shinger 9 lurgical coretical canics - cs and signer 9 anying igue 9 nisms,

T	ext Books:
1	George. E. Dieter, "Mechanical Metallurgy", 3rd Edition, McGraw-Hill Publications, New York, SI Edition, 2004
2	Marc Andr'e Meyers, Krishan Kumar Chawla, "Mechanical Behavior of Materials", Cambridge University Press, UK, 2009.

Total (45+0) = 45 **Hours**

parametetric methods of extrapolation. Deformation Mechanism Maps

Refe	rence Books:
1	Reed Hill, R.E., "Physical Metallurgy Principles", Affiliated East West Press, New Delhi, 1992.
2	Davis.H.E. Troxell G.E., Hauck.G.E.W. "The Testing of Engineering Materials", McGraw-Hill, 1982.
3	Wulff et al Vol. III "Mechanical Behavior of Materials", John Wiley and Sons, New York, USA, 1983.
4	Honeycombe R.W.K., "Plastic Deformation of Materials", Edward Arnold Publishers, 1984

	Course Outcomes: Upon completion of this course, the students will be able to:					
CO1	:	Discuss the mechanical behaviour of materials.	L2: Understanding			
CO2	:	Discuss the strengthening mechanisms of materials.	L2: Understanding			
CO3	:	List the various types of fractures and their mechanisms, fracture mechanics and various theories describing fracture mechanics.	L2: Understanding			
CO4	:	Discuss the fatigue behaviour and the mechanism of fatigue, SN curve and fatigue testing machines.	L2: Understanding			
CO5	:	Describe the creep behaviour and mechanism, factors affecting creep and creep testing machines.	L2: Understanding			

COURS	E ART	ICULA	TION	MATR	<u>IX</u>											
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	1	1		1	1								1	1		
CO2	1	1		1	1								1	1		
CO3	1	1	1		1										1	1
CO4	1	1				1	1								1	1
CO5	1	1		1	1								1	1		
Avg.	1.0	1.0	1.0	1.0	1.0	1.0	1.0						1.0	1.0	1.0	1.0
						3/2/1-ir	dicates	strengt	h of cor	relation ((3- High,	2-Mediu	ım, 1- Lo	w)		

22M	TM04	RATE PROCESSES IN METALLU	S	r			
PRER	REQUISIT	TES		OE	Cre	edit	3
Engin	neering ph	vicies		L	T	P	TH
Engin	icering ph	ysics	Hours/Week	3	0	0	3
Cours	se Learnii	ng Objectives					
1	To learn	the basic principles and concepts of kinetics in the do	main of metallur	gy and	materia	ls; to le	earn

To learn the basic principles and concepts of kinetics in the domain of metallurgy and materials; to learn about equations and their applications; And to appreciate that metallurgical kinetics as a Knowledge base with abundant applications.

Unit I INTRODUCTION 9 0 0 9

Introduction: Role of kinetics, heterogeneous and homogeneous kinetics, Role of heat and mass transfer in metallurgical kinetics, rate expression, Effect of Temperature and concentration on reaction kinetics: effect of temperature (Arrhenius Equation), Effect of concentration (order of a reaction), significance and determination of activation energy.

Unit II KINETICS OF SOLID-FLUID REACTION 9 0 0 9

Kinetics of solid-fluid reaction: kinetic steps, rate controlling step, definition of various resistances in series, shrinking core model, chemical reaction as rate controlling step, Product layer diffusion as rate controlling step, Mass transfer through external fluid film as rate controlling step, heat transfer as the rate controlling step, Concentration boundary layer, definition and significance of heat and mass transfer coefficient, Theoretical models for mass transfer coefficients, Correlations for heat and mass transfer coefficients

Unit III LIQUID-SOLID PHASE TRANSFORMATION 9 0 0 9

Principles of Solidification in metals and alloys: thermodynamics involved, eutectic and peritectic Solidification, Homogeneous and heterogeneous nucleation, Mechanisms of growth. Rapid Solidification Processing.

Unit IV | SOLID STATE PHASE TRANSFORMATIONS | 9 | 0 | 9

Nucleation and growth Kinetics, homogeneous and heterogeneous transformation, Precipitation: Coherency, age hardening, particle Coarsening. Ostwald ripening, Order-disorder transformation, spinodal decomposition, massive transformations

Unit V SOLID STATE PHASE TRANSFORMATIONS IN STEEL 9 0 0 9

Reconstructive and displacive transformations; Pearlitic transformation: mechanism and kinetics: Johnson-Mehl equation, morphology of pearlite; Bainitic transformation: mechanism and kinetics; morphology of upper bainite and lower bainite; Martensitic transformation: Mechanism- diffusionless displacive nature; morphology of high carbon and low carbon martensite.

Tex	xt Books:
1.	Ahindra Ghosh and Sudipto Ghosh, A Text book of Metallurgical Kinetics, PHI learning Pvt. Ltd., New
	Delhi, 2014
2.	H.S. Ray, Kinetics of Metallurgical Reactions, International Science publisher, 1993.
3.	F. Habashi, Kinetics of Metallurgical Processes, Metallurgy Extractive Québec, 1999.
4.	Upadhyaya G S and Dube R K., "Problems in Metallurgical Thermodynamics & Kinetics", Pergamon,
	1977.

Ref	Reference Books:				
1.	Phase transformations in metals and alloys- D.A. Potter and K.E. Easterling, CRC Press,				
	1992. 2. Transformations in Metals, P.G. Shewmon, Mc-Graw Hill, 1969.				
2.	Introduction to Physical Metallurgy – S. N. Avner, Tata McGraw Hill, 1997.				
3.	Physical Metallurgy Principles, R. E. Reed-Hill and R. Abbaschian, 3rd ed, PWS-Kent				
	Publishing, 1992.				
4.	Modern Physical Metallurgy, R. E. Smallman, Butterworths, 1963				

		utcomes: npletion of this course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	:	Discuss the thermodynamic aspects of phase changes.	L2: Understanding
CO2	:	Discuss the fundamentals of solid –fluid reactions.	L2: Understanding
CO3	:	Explain the eutectic and peritectic solidifications and rapid solidification processes.	L2: Understanding
CO4	:	Describe the fundamentals of solidification.	L1: Remembering
CO5	:	Apply the solid state phase transformations in steel.	L3:Applying

COURS	E ART	ICULA	TION	MATR	<u>IX</u>											
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	1	1		1	1								1			1
CO2	1	1			1	1									1	1
CO3	1	1		1	1								1	1		
CO4	1	1		1	1									1		1
CO5	1		1			1	1								1	1
Avg.	1.0	1.0	1.0	1.0	1.0	1.0	1.0						1.0	1.0	1.0	1.0
						3/2/1-ir	dicates	strengt	h of cor	relation ((3- High,	2-Mediu	ım, 1- Lo	w)		

22MTM05	CORROSION AND SURFACE ENGIN	EERING	S	emeste	er	
PREREQUIS	TES		OE	Cre	edit	3
Engineering c	ng chemistry Hours/Wee		L	T	P	TH
Engineering c	Hours/Weel				0	3
Course Learn	ing Objectives					
1 To un	derstand the corrosion and surface engineering, with it	s application in e	nginee	ring fie	ld.	
Unit I	MECHANISMS AND TYPES OF CORROSION	I	9	0	0	9
Cavitations, Cinfluencing co	orrosion, Galvanic series-specific types of corrosion Crevice Fretting, Erosion and Stress Corrosion, correspondent	osion fatigue, hy		damaş	ge –Fa	ctors
	ting techniques and procedures- Corrosion Testing	ASTM Standard				
Corrosion tes Hydrogen Ind	1	ASTM Standard king Test- Prever ors – Cathodic Pro	s, Pitti ntion o	ng Cor	rosion osion-E	Test. Design
Corrosion tes Hydrogen Ind against corros processes. Unit III Corrosion in	ting techniques and procedures- Corrosion Testing luced Cracking Test, Sulphide Stress Corrosion Crackion – Modifications of corrosive environment – Inhibito	ASTM Standard king Test- Preventors – Cathodic Pro	s, Pittintion of otection 9 indus	ng Correst Correst On —Spece	rosion-Erial surf	Test Design facing
Corrosion tes Hydrogen Ind against corros processes. Unit III Corrosion in	ting techniques and procedures- Corrosion Testing luced Cracking Test, Sulphide Stress Corrosion Crackion – Modifications of corrosive environment – Inhibito CORROSION OF INDUSTRIAL COMPONENT fossil fuel power plants, Automotive industry, Che	ASTM Standard king Test- Preverors – Cathodic Pro	s, Pittintion of otection 9 indus	ng Correst Correst On —Spece	rosion-Erial surf	Test Design facing 9 on in
Corrosion tes Hydrogen Inc against corros processes. Unit III Corrosion in petroleum proc Unit IV	ting techniques and procedures- Corrosion Testing luced Cracking Test, Sulphide Stress Corrosion Crackion – Modifications of corrosive environment – Inhibito CORROSION OF INDUSTRIAL COMPONENT fossil fuel power plants, Automotive industry, Cheluction operations and refining, Corrosion of pipelines SURFACE ENGINEERING FOR WEAR AND OR STREET CORROSION TESTING FOR TESTING FOR WEAR AND OR STREET CORROSION TESTING FOR TESTING	ASTM Standard king Test- Preverors – Cathodic Proof. TS Emical processing s- wear of industr. CORROSION g –Hard facing-M	s, Pittintion of otection 9 g industrial com 9	ng Correspondent of Correspondent of the Correspond	rrosion osion-E cial surf o corrosio ts.	Test Design facing 9 on in 9
Corrosion tes Hydrogen Inc against corros processes. Unit III Corrosion in petroleum proc Unit IV	ting techniques and procedures- Corrosion Testing luced Cracking Test, Sulphide Stress Corrosion Crackion – Modifications of corrosive environment – Inhibito CORROSION OF INDUSTRIAL COMPONENT fossil fuel power plants, Automotive industry, Chelluction operations and refining, Corrosion of pipelines SURFACE ENGINEERING FOR WEAR AND RESISTANCE tings – Electro and Electroless Plating – Hot dip coating	ASTM Standard king Test- Preverors – Cathodic Proof. TS Emical processing s- wear of industr. CORROSION g –Hard facing-M	s, Pittintion of otection 9 g industrial com 9	ng Correspondent of Correspondent of the Correspond	rrosion osion-E cial surf o corrosio ts.	Test Design facing 9 on in

Re	ference Books:
1.	Fontana. G., Corrosion Engineering, McGraw Hill, 1985.
2.	Kenneth G. Budinski, Surface Engineering for Wear Resistance, Prenticehall, 1992.
3.	ASM Metals Hand Book –Vol. 5, Surface Engineering,1996.
4.	Denny A Jones, "Principles and prevention of corrosion", 2 nd edition, Prentice Hall, New Jersey,1995.
5.	ASM International, Surface Engineering for Corrosion and Wear Resistance,2005.
6.	Schweitzer. P.A., Corrosion Engineering Hand Book, 3rd Edition, Marcel Decker, 1996.

Course	-	Bloom's Taxonomy Mapped	
CO1	:	Name the different types of corrosion and their mechanism.	L2: Understanding
CO2	:	Estimate corrosion resistance by different tests.	L4:Analysing
CO3	:	Explain the corrosion behavior of different metals in different industries.	L2: Understanding
CO4	:	Classify the different forms of processing techniques of surface engineering materials.	L1: Remembering
CO5	:	Select the type of deposition and spraying technique.	L3:Applying

COURS	COURSE ARTICULATION MATRIX															
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	1	1		1	1								1	1		
CO2	1	1		1		1							1	1		
CO3	1	1	1	1			1								1	1
CO4	1	1		1	1										1	1
CO5	1	1		1	1								1	1		
Avg.	1.0	1.0	1.0	1.0	1.0	1.0	1.0						1.0	1.0	1.0	1.0
						3/2/1-ir	dicates	strengt	h of cor	relation	(3- High,	2-Mediu	ım, 1- Lo	w)		

22M	ITM06	MATERIALS CHARACTERIZATI	ION	S	Semeste	er			
PRE	REQUISI	TTES		OE	Cre	edit	3		
T	•	h		L T P					
Engu	neering p	nysics	Hours/Week	3	0	0	3		
Cour	se Learni	ing Objectives		1					
1	To acqu	uire knowledge on various characterizations, chemical a	and thermal ana	lysis o	f metall	urgical	l		
	compor	nents using its analysis tools.							
U	J nit I	OPTICAL MICROSCOPY		9	0	0	9		
depth	of field,	d working,, Optic properties - magnification, numerical different light sources, lens aberrations and their ght field, phase-contrast, polarized light	r remedial meas	sures, '	Various	_			
	_			sis					
micro U Chara	oscopy, high	gh temperature microscopy; Quantitative metallography X-RAY DIFFRACTION X-ray spectrum, Bragg's Law, Diffraction methods -	ny – Image analy Laue method, r	9 otating					
U Chara powd and	oscopy, his acteristic der method counters.	gh temperature microscopy; Quantitative metallography X-RAY DIFFRACTION X-ray spectrum, Bragg's Law, Diffraction methods - I. Diffraction intensity – structure factor calculation. X-Applications of X-ray diffraction in materials characteristics.	Laue method, ray diffractome	9 rotating eter -ge	crysta neral fe	l meth	od ar		
U Chara powd and o	oscopy, his acteristic der method counters.	gh temperature microscopy; Quantitative metallography X-RAY DIFFRACTION X-ray spectrum, Bragg's Law, Diffraction methods - Id. Diffraction intensity – structure factor calculation. X-	Laue method, ray diffractome	9 rotating eter -ge	crysta neral fe	l meth	od ar		
Chara powd and c crysta	oscopy, his oscopy	gh temperature microscopy; Quantitative metallography X-RAY DIFFRACTION X-ray spectrum, Bragg's Law, Diffraction methods - I. Diffraction intensity – structure factor calculation. X-Applications of X-ray diffraction in materials characteristic crystal structure, precise lattice parameter, measurements.	Laue method, radiation – ent of stress.	9 rotating eter -ge Deter	crysta eneral fe rminati	l meth eatures on of	od an, filte		
Chara powd and crysta U1 Electro	oscopy, his oscopy	X-RAY DIFFRACTION X-ray spectrum, Bragg's Law, Diffraction methods - I. Diffraction intensity – structure factor calculation. X-Applications of X-ray diffraction in materials characteristic structure, precise lattice parameter, measurement ELECTRON MICROSCOPY - specimen interactions. Construction and operation exts and image formation, various imaging modes, select	Laue method, r L-ray diffractome aracterisation — ent of stress. n of Transmissi cted area diffract	9 rotating eter -ge Deter 9 on Eletion, ap	crysta eneral fermination	1 meth eatures on of 0 Microscons, spo	od ar, filte 9 copy		
Chara powd and corysta Un Electro Diffra prepare	oscopy, higher method counters. allite size, mit III ron beam action effectively.	X-RAY DIFFRACTION X-ray spectrum, Bragg's Law, Diffraction methods - I. Diffraction intensity – structure factor calculation. X-Applications of X-ray diffraction in materials characteristic structure, precise lattice parameter, measurement ELECTRON MICROSCOPY - specimen interactions. Construction and operation ects and image formation, various imaging modes, selectioniques. Scanning electron microscopy – principle, extractions.	Laue method, ray diffractome aracterisation—ent of stress. n of Transmissicted area diffract equipment, var	9 rotating eter -ge Deter 9 on Election, apious opious opi	crysta eneral formination octron I	1 metheatures on of 0 Microsoons, spog model	od and, filter		
U Chara powd and corysta U Electro Diffra applica applica	oscopy, his operation teccations, Establishment of the counters.	X-RAY DIFFRACTION X-ray spectrum, Bragg's Law, Diffraction methods - Id. Diffraction intensity – structure factor calculation. X-Applications of X-ray diffraction in materials characteristal structure, precise lattice parameter, measurement ELECTRON MICROSCOPY - specimen interactions. Construction and operation exts and image formation, various imaging modes, selection probe microanalyser (EPMA)- principle, institution in the properties of the properties o	Laue method, ray diffractome aracterisation—ent of stress. n of Transmissicted area diffract equipment, var	9 rotating eter -ge Deter 9 on Election, apious opious opi	crysta eneral formination octron I	1 metheatures on of 0 Microsoons, spog model	od ar, filte 9 copy		
Chara powd and corysta Un Electro Diffra applic quant	oscopy, his operation tecceptors, Entity of the counters. The counters of the	X-RAY DIFFRACTION X-ray spectrum, Bragg's Law, Diffraction methods - I. Diffraction intensity – structure factor calculation. X-Applications of X-ray diffraction in materials characteristic structure, precise lattice parameter, measurement ELECTRON MICROSCOPY - specimen interactions. Construction and operation exts and image formation, various imaging modes, selection probe microanalyser (EPMA)- principle, installysis. Introduction to HRTEM, FESEM, EBSD.	Laue method, ray diffractome aracterisation—ent of stress. n of Transmissicted area diffract equipment, var	9 rotating eter -ge Deter 9 on Ele tion, ap ious op ualitati	g crysta eneral formination operating ive and	1 meth eatures on of 0 Microsoons, special model	od ar, filte 9 copy ecimes ar		
Chara powd and corysta Un Electro prepa applica quant	oscopy, higher method counters. allite size, mit III ron beam action effectations, Editative and mit IV	X-RAY DIFFRACTION X-ray spectrum, Bragg's Law, Diffraction methods - I. Diffraction intensity – structure factor calculation. X-Applications of X-ray diffraction in materials characteristic structure, precise lattice parameter, measurement ELECTRON MICROSCOPY - specimen interactions. Construction and operation exts and image formation, various imaging modes, selection image. Scanning electron microscopy – principle, installysis. Introduction to HRTEM, FESEM, EBSD. SPECTROSCOPIC TECHNIQUES	Laue method, ray diffractome aracterisation—ent of stress. n of Transmissicated area diffract equipment, var strumentation, q	9 rotating eter -ge Deter 9 on Election, apious opualitation	crysta eneral formination operating ive and	1 meth eatures on of 0 Microsoons, spoons, spoons model	od ar, filte 9 copy ecimes ar		
Chara powd and corysta Ui Electro Diffra applic quant Ui X-ray	oscopy, his operation tectors, Estitative and interest of the counters.	X-RAY DIFFRACTION X-ray spectrum, Bragg's Law, Diffraction methods - I. Diffraction intensity – structure factor calculation. X-Applications of X-ray diffraction in materials characteristic precise lattice parameter, measurement ELECTRON MICROSCOPY - specimen interactions. Construction and operation exts and image formation, various imaging modes, selection probe microanalyser (EPMA)- principle, instalysis. Introduction to HRTEM, FESEM, EBSD. SPECTROSCOPIC TECHNIQUES copy – EDS and WDS. Principle, instrumentation, we	Laue method, ray diffractome aracterisation—ent of stress. n of Transmissicated area diffract equipment, variety strumentation, querorking and appleators.	9 rotating eter -ge Deter 9 on Eletion, apious opualitation	g crysta g c	1 meth eatures on of 0 Microsons, spong model 0 uger E	od an, filte 9 copy ecimes ar		
Chara powd and ocrysta Un Electro prepa applic quant Un X-ray spectro	oscopy, higher method counters. allite size, mit III ron beam action effectations, Editative and mit IV y spectroscopy, 2	X-RAY DIFFRACTION X-ray spectrum, Bragg's Law, Diffraction methods - I. Diffraction intensity – structure factor calculation. X-Applications of X-ray diffraction in materials characteristic structure, precise lattice parameter, measurement ELECTRON MICROSCOPY - specimen interactions. Construction and operation exts and image formation, various imaging modes, selection image. Scanning electron microscopy – principle, installysis. Introduction to HRTEM, FESEM, EBSD. SPECTROSCOPIC TECHNIQUES	Laue method, referring diffractome aracterisation—ent of stress. In of Transmissicated area diffract equipment, varietrumentation, quantity orking and applicass spectroscop	9 rotating eter -ge Deter 9 on Election, apious of qualitation y / ion	crysta neral formination o cetron I oplication perating ive and o as of A microp	1 meth eatures on of 0 Microsons, spog model 0 uger E	od an, filte 9 copy ecimes ar		
Chara powd and corysta Un Electro Diffra prepa applic quant Un X-ray spectro	oscopy, his operation tectors, Estitative and not rescopy, a spectrose, a spectrose, a spectrose of the spec	X-RAY DIFFRACTION X-ray spectrum, Bragg's Law, Diffraction methods - I. Diffraction intensity – structure factor calculation. X-Applications of X-ray diffraction in materials characteristic structure, precise lattice parameter, measurement ELECTRON MICROSCOPY - specimen interactions. Construction and operation exts and image formation, various imaging modes, selection probe microanalyser (EPMA)- principle, installysis. Introduction to HRTEM, FESEM, EBSD. SPECTROSCOPIC TECHNIQUES copy – EDS and WDS. Principle, instrumentation, workstray photoelectron spectroscopy and Secondary ion methods - I.	Laue method, ray diffractome aracterisation—ent of stress. In of Transmissicated area diffract equipment, varietrumentation, quasis spectroscopyray fluorescence	9 rotating eter -ge Deter 9 on Ele tion, ap ious of ualitati 9 lication y / ion e spec	crysta neral formination o cetron I oplication perating ive and o as of A microp	1 meth eatures on of 0 Microsons, spog model 0 uger E	od ar, filte 9 copy ecimes ar		

Thermal Analysis: Principles of differential thermal analysis, differential scanning calorimetry and thermograviometric analysis – Instrumentation and applications. Advanced characterization techniques: Scanning probe microscopy - STM and AFM - principle, instrumentation and applications. Field ion microscopy including atom probe - principles, instrumentation and applications.

Tex	Text Books:										
1.	Cullity, B.D., Elements of X Ray Diffraction, Addison-Wesley Publishing Company Inc, Philippines,										
	1978										
2.	Brandon, D. and W.D. Kaplan, Microstructural Characterization of Materials, John Wiley & Sons Ltd,										

	England, 2013.								
3.	Leng, Y., Materials Characterization: Introduction to Microscopic and Spectroscopic Methods, John								
	Wiley & Sons (Asia) Pte Ltd, Singapore, 2008								
Ref	Reference Books:								
1.	ASM Handbook, Volume 10, Materials Characterization, ASM international, USA, 1986.								
2.	Vander Voort, G.F., Metallography: Principle and practice, ASM International, 1999.								
3.	Phillips V A, Modern Metallographic Techniques and their Applications, Wiley Eastern, 1971.								
4.	Angelo, P. C., Materials Characterization, Reed Elsevier India Pvt Ltd, Haryana, 2013.								

		utcomes: npletion of this course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	:	Discuss the principles of metallurgical microscope, optical properties and various illumination techniques.	L2: Understanding
CO2	:	Analyze the various diffraction methods, X-ray diffractometer and determination of crystal parameter.	L4:Analysing
CO3	:	Discuss the principles of TEM, SEM, EPMA.	L2: Understanding
CO4	:	Explain various spectroscopic techniques,	L2: Understanding
CO5	:	Discuss the chemical and thermal analysis using advanced methods.	L2: Understanding

COURS	COURSE ARTICULATION MATRIX															
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	1	`1		1	1								1		1	
CO2	1	1	1	1		1							1			1
CO3	1		1			1	1					1	1			1
CO4	1	1		1	1							1	1			1
CO5	1	1		1	1								1		1	
Avg.	1.0	1.0	1.0	1.0	1.0	1.0	1.0					1.0	1.0		1.0	1.0
						3/2/1-ir	dicates	strengt	h of cor	relation ((3- High,	2-Mediu	ım, 1- Lo	w)		

22M'	TM07	AUTOMOTIVE, AEROSPACE AND DEFENC	EE MATERIAL	S	Semester				
PRER	REQUISI	ΓES		OE	Cre	edit	3		
				L	ТР		TH		
Engin	neering pl	nysics	Hours/Week	3	0	0	3		
Cours	se Learni	ng Objectives							
1		rstand the properties and applications various material ndustries and its components.	ls suitable for aut	omobi	le, aircr	aft and			
U	nit I	MATERIALS FOR ENGINES AND TRANSMIS SYSTEMS	SION	9	0	0	9		
		ion for IC engines: Piston, piston rings, cylinder, Engines, Gears, Splines, Clutches.	ine block, Conne	cting r	od, Cra	nk shaf	t, Fly		
Uı	nit II	MATERIALS FOR AUTOMOTIVE STRUCTU	RES	9	0	0	9		
	es meant f	sc, wheels, differentials, damping and antifriction flui for engine control, ABS, Steering, Suspension, Senso	•				ctroni		
	nit III	AEROSPACE METALS AND ALLOYS		9	0	0	9		
resista	ance mater tanium al	sion – Effect of corrosion on mechanical properties rials used for space vehicles. Heat treatment of carbon loys – Effect of alloying treatment, heat resistance a rgy- application of materials in Thermal protection sy	steels – aluminiu lloys – tool and	m alloy die ste	ys, mag els, ma	nesium gnetic	alloy		
		-6,	•						
powde alloys		CERAMICS AND COMPOSITES		9	0	0	9		
powde alloys Un Introd	nit IV luction –		cermet - cutting	9 g tools es, Fab	s – glas rication	ss cera	mic –		

Introduction-unit of nuclear radiation-Types of waste –disposal –ICRP recommendations-radiation

hazards and prevention -radiation dose units - Irradiation Examination of Fuels, Irradiation behaviour of metallic uranium – irradiation growth, thermal cycling, swelling, adjusted uranium, blistering in uranium rods. Irradiation effects in ceramic oxide and mixed oxide fuels, definition and units of burn up, main causes of fuel element failure in power reactors and remedies to avoid failures.

Total (45+0) = 45 Hours

Reference Books:

- ASM Handbook, "Selection of Materials Vol. 1 and 2", ASM Metals Park, Ohio. USA, 1991.
- Materials Science and Engineering, Willium D. Callister, Jr. John Wiley & Sons publications Or Callister's Materials Science and Engineering Adapted By R. Balasubramaniam, Wiley India, Edition -2010.

3.	Material Science and Engineering, V. Raghavan, Prentice Hall of India, 4th Edition.
4.	Engineering Metallurgy Applied Physical Metallurgy, R. A. Higgins, 6th Edition
5.	Gladius Lewis, "Selection of Engineering Materials", Prentice Hall Inc. New Jersey USA, 1995.
6.	Charles J A and Crane. F A. A., "Selection and Use of Engineering Materials", 3rd Edition, Butterworths, London UK, 1996
7.	ASM Handbook. "Materials Selection and Design", Vol. 20- ASM Metals Park Ohio.USA, 1997
8.	Cantor," Automotive Engineering: Lightweight, Functional, and Novel Materials", Taylor & Francis Group, London, 2006

Cours Upon	-	Bloom's Taxonomy Mapped	
CO1	:	Describe the materials selection criteria for engine and transmission systems.	L2: Understanding
CO2	:	Analyze the different materials used for automotive structures and Different electronic materials for automotive applications.	L4:Analysing
CO3	:	Explain various topics such as elements of aerospace materials and mechanical behaviour of materials,	L2: Understanding
CO4	:	Compare the ceramics and composites of aerospace materials	L4:Analysing
CO5	:	Examine the fuels for nuclear materials.	L3:Applying

COURS	COURSE ARTICULATION MATRIX															
СО/РО	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	1	1		1	1								1	1		
CO2	1	1	1			1							1	1		
CO3	1			1	1								1		1	
CO4	1	1	1				1						1			1
CO5	1	1		1	1								1			1
Avg.	1.0	1.0	1.0	1.0	1.0	1.0	1.0						1.0	1.0	1.0	1.0
						3/2/1-in	dicates	strengt	h of cor	relation	(3- High,	2-Mediu	ım, 1- Lo	w)		