DEPARTMENT OF ELECTRICAL AND ELECTRONICS ENGINEERING

GOVERNMENT COLLEGE OF ENGINEERING, SALEM – 636 011.

(An Autonomous Instituion Affiliated to Anna University)

Curriculum 2018 - Autonomous Courses (For Students Admitted from 2018 – 2019)

(101 Students Admitted from 2010 - 2013)

M.E. Power Electronics and Drives – Full Time

			Но	ours/	Week	Ι		Maxi	mum	n Marks	
Course code	Name of the Course	Category	Contact periods	Lecture	Tutorial/ Demo*	Practical	Credit	CA	FE	Total	
	SEMESTE	RI									
18PE C 11	Power Semiconductor Devices and Components	Core	3	3	0	0	3	40	60	100	
18PE C 12	Analysis of Power Converters	Core	3	3	0	0	3	40	60	100	
18PE E 1X	Elective-I	Elect 1	3	3	0	0	3	40	60	100	
18PE E 2X	Elective-II	Elect 2	3	3	0	0	3	40	60	100	
18PE C 13	Advanced Power Electronics Laboratory-I	Core	4	0	0	4	2	40	60	100	
18PE C 14	Advanced Digital Control Laboratory	Core	4	0	0	4	2	40	60	100	
18 MLC01	Research Methodology and IPR	MLC	3	3	0	0	3	40	60	100	
18ACXX	Audit Course	Audit	2	0	0	0	0	100	0	100	
TOTAL							19			800	
	SEMESTE	RII					1	1			
18PE C 21	Modelling and Analysis of Electrical Machines	Core	3	3	0	0	3	40	60	100	
18PE C 22	Modern Electrical Drives	Core	3	3	0	0	3	40	60	100	
18PE E 3X	Elective-III	Elect 3	3	3	0	0	3	40	60	100	
18PE E 4X	Elective-IV	Elect 4	3	3	0	0	3	40	60	100	
18PE C 23	Advanced Power Electronics Laboratory-II	Core	4	0	0	4	2	40	60	100	
18PE C 24	Advanced Electrical Drives Laboratory	Core	4	0	0	4	2	40	60	100	
18PE C 25	Mini Project With Seminar		4	0	0	4	2	40	60	100	
18ACXX	Audit Course	Audit	2	0	0	0	0	100	0	100	
	TOTAL						18			800	
SEMESTER III											
18PE E 5X	Elective – V	Elect 5	3	3	0	0	3	40	60	100	
18PE E6 X	Elective - VI	Elect 6	3	3	0	0	3	40	60	100	
18PE C 31	Dissertation Phase – I		20	0	0	20	10	80	120	200	
	TOTAL						16			400	
	05115055				I						
18PE C 41	SEMESTE		32	0	0	32	16	160	240	400	
1072641	Dissertation Phase – II		J2	U	U	<u></u> کد	01	100	240	400	

TOTAL						16			400
Total Credits for the programme $-10 \pm 18 \pm 16 \pm 16 - 60$									

Total Credits for the programme = 19 + 18 + 16 + 16 = 69

List of Programme Electives:

Course Code	Name of Course
Elective 1	
18PE E 11	Advanced Microcontroller Based System Design
18PE E 12	Applied Mathematics for Electrical Engineering
18PE E 13	System Theory
18PE E 14	Artificial Intelligence and Machine Learning
18PE E 15	Discrete Control System
Elective II	
18PE E 21	Advanced Power Electronic Circuits
18PE E 22	Digital Signal Processing for Power Electronics
18PE E 23	Dynamics of power Converters
18PE E 24	Modulation Control for Power Converters
18PE E 25	Design of Power Converters
Elective III	
18PE E 31	Advanced Power Quality
18PE E 32	Harmonics and Filters for Power Electronic Circuits
18PE E 33	Energy Conservation, Auditing and Management
18PE E 34	Special Electrical Machines and Drives
18PE E 35	Digital Simulation of Power Electronics System
Elective – IV	
18PE E 41	Photo Voltaic System
18PE E 42	Optimization Techniques
18PE E 43	Power System Optimization Techniques
18PE E 44	Wind Energy System
18PE E 45	Power Electronics for Renewable Energy System
Elective –V	
18PE E 51	Smart Grid Technology
18PE E 52	Distributed Generation

18PE E 53	FACTS Controllers
18PE E 54	HVDC Transmission Systems
18PE E 55	SCADA Systems and Applications
Elective –VI	
18PE E 61	Electric Vehicles
18PE E 62	Theory and Design of SMPS
18PE E 63	Energy Storage Technology
18PE E 64	Internet of Things for Electrical Engineers
18PE E 65	Digital Signal Processors for Power Converters

List of Audit Courses:

Course Code	Name of Course
18AC01	English for Research paper writing
18AC02	Disaster Management
18AC03	Sanskrit for Technical Knowledge
18AC04	Value Education
18AC05	Constitution of India
18AC06	Pedagogy Studies
18AC07	Stress Management by Yoga
18AC08	Personality Development through Life Enlightenment Skills

List of Special Electives:

Course Code	Name of Course
18PE SE 1	Pattern Recognition

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Curriculum 2018 - Autonomous Courses

(For Students Admitted from 2018 – 2019)

M.E. Power Electronics and Drives – Part Time

				ours/	Week			Maximum Marks			
Course code	Name of the Course	Category	Contact periods	Lecture	Tutorial/ Demo*	Practical	Credit	CA	Ħ	Total	
	SEMESTE	RI					•				
18PE C 11	Power Semiconductor Devices and Components	Core	3	3	0	0	3	40	60	100	
18PE C 12	Analysis of Power Converters	Core	3	3	0	0	3	40	60	100	
18PE C 13	Advanced Power Electronics Laboratory-I	Core	4	0	0	4	2	40	60	100	
18 MLC01	Research Methodology and IPR	MLC	3	3	0	0	3	40	60	100	
	TOTAL						11			400	
	SEMESTE	RII									
18PE C 21	Modelling and Analysis of Electrical Machines	Core	3	3	0	0	3	40	60	100	
18PE C 22	Modern Electrical Drives	Core	3	3	0	0	3	40	60	100	
18PE C 23	Advanced Power Electronics Laboratory-II	Core	4	0	0	4	2	40	60	100	
18ACX	Audit Course	Audit	2	0	0	0	0	100	0	100	
	TOTAL						8			400	
	SEMESTE	R III Elect									
18PE E 1X	Elective-I	1	3	3	0	0	3	40	60	100	
18PE E 2X	Elective-II	Elect 2	3	3	0	0	3	40	60	100	
18PE C 14	Advanced Digital Control Laboratory	Core	4	0	0	4	2	40	60	100	
18ACX	Audit Course	Audit	2	0	0	0	0	100	0	100	
	TOTAL						8			400	
	SEMESTE		_					-			
18PE E 3X	Elective-III	Elect 3	3	3	0	0	3	40	60	100	
18PE E 4X	Elective-IV	Elect 4	3	3	0	0	3	40	60	100	
18PE C 24	Advanced Electrical Drives Laboratory	Core	4	0	0	4	2	40	60	100	
18PE C 25	Mini Project With Seminar	Core	4	0	0	4	2	40	60	100	
	TOTAL						10			400	
	SEMESTE	RV		-							
18PE E 5X	Elective – V	Elect 5	3	3	0	0	3	40	60	100	
18PE E6 X	Elective - VI	Elect 6	3	3	0	0	3	40	60	100	

18PE C 31 Dissertation Phase – I		Core	20	0	0	20	10	80	120	200
TOTAL							16			400
SEMESTER VI										
18PE C 41	18PEC41 Dissertation Phase – II 32 0 0 32 16 160 240 400						400			
TOTAL 16 400										

Total Credits for the programme = 11 + 8 + 8 + 10+16+16 = 69

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Course Code	Name of Course
Elective 1	
18PE E 11	Advanced Microcontroller Based System Design
18PE E 12	Applied Mathematics for Electrical Engineering
18PE E 13	System Theory
18PE E 14	Artificial Intelligence and Machine Learning
18PE E 15	Discrete Control System
Elective II	
18PE E 21	Advanced Power Electronic Circuits
18PE E 22	Digital Signal Processing for Power Electronics
18PE E 23	Dynamics of power Converters
18PE E 24	Modulation Control for Power Converters
18PE E 25	Design of Power Converters
Elective III	
18PE E 31	Advanced Power Quality
18PE E 32	Harmonics and Filters for Power Electronic Circuits
18PE E 33	Energy Conservation, Auditing and Management
18PE E 34	Special Electrical Machines and Drives
18PE E 35	Digital Simulation of Power Electronics System
Elective – IV	
18PE E 41	Photo Voltaic System
18PE E 42	Optimization Techniques
18PE E 43	Power System Optimization Techniques
18PE E 44	Wind Energy System

18PE E 45	Power Electronics for Renewable Energy System
Elective –V	
18PE E 51	Smart Grid Technology
18PE E 52	Distributed Generation
18PE E 53	FACTS Controllers
18PE E 54	HVDC Transmission Systems
18PE E 55	SCADA Systems and Applications
Elective –VI	
18PE E 61	Electrical Vehicles
18PE E 62	Theory and Design of SMPS
18PE E 63	Energy Storage Technology
18PE E 64	Internet of Things for Electrical Engineers
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18AC04	Value Education
18AC05	Constitution of India
18AC06	Pedagogy Studies
18AC07	Stress Management by Yoga
18AC08	Personality Development through Life Enlightenment Skills

List of Special Electives:

Course Code	Name of Course						
18PE SE 1	Pattern Recognition						

18PE	EC11 POWER SEMICONDUCTOR DEVICES AND COMPONENTS	L	T	P	(
		3	0	0	3
Course O	biectives:				
	inderstand the concepts of various power semiconductor devices and their thermal b	eha	vior		
	lesign magnetic and passive components for specific requirements.	ona	101.		
2. 100					
	OWER SEMICONDUCTOR SWITCHES		9	+	(
Introductio	n – Ideal power device characteristics – Typical power switching waveforms – C	onst	ruct	on a	۹ľ
	stics of various power semiconductor devices - Power Diode, MOSFET, IGBT, T		tor,	GTO)
Gate drive	circuits for power semiconductor switches - Emerging power semiconductor device	s.			
	THERMAL ANALYSIS OF POWER SEMICONDUCTOR DEVICES		9	+	(
	n – Cooling and Heat sinks – Thermal modeling of power switching devices – Elec				
thermal m	odel – Mathematical thermal equivalent circuit – Coupling of Electrical and Therma	l cor	npo	nent	s
Heat sink	design – Zero voltage Switching and Zero Current switching – Basic concept and mo	del	of sv	vitch	in
circuits.					
Unit III	DESIGN OF MAGNETIC COMPONENTS		9	+	(
Introductio	n - Soft magnetic material types - Comparison of material types - Ferrite C	hara	cter	istics	3
Transform	er Design – Ferrite voltage transformer – Ferrite current transformer – Design and re	auire	eme	nts.	
Unit IV	DESIGN OF INDUCTORS		9	+	(
Introductio	n – Linear Inductors and chokes – Design with Hanna curves – Design including	copp	er lo	osse	s
Saturable	Inductor design – Analysis of specific Inductor Design – Inductor design procedure.				
	DESIGN OF CAPACITORS		9	+	(
Introductio	n – General properties – Liquid and solid metal oxide dielectric capacitors – Plast	ic fil	m d	elec	tri
capacitors	- EMI suppression capacitors - Ceramic dielectric capacitors - Mica dielectric capa	citor	s.		
-					
	Total (Li	-T)=	45 F	Peric	bd
Course O	utcomes:				
Upon com	pletion of this course, the students will be able to:				
CO1 :	Remember the overview of power semiconductor switches				
CO2 :	Analyze the thermal requirements of power semiconductor devices				
	Understand the basic concepts of ZVS and ZCS				
	Evaluate the design aspects of various magnetic components according to specific r	equi	rem	ents.	
	Understand the design concepts of circuit elements	1			
Text Book					
	id M.H., "Power Electronics: Circuits, Devices and Applications ", Pearson, 3 rd Editio	n. 20)13.		
	W Williams., "Power Electronics: Devices, Drivers, Applications, and Passive comp				
Reference		0.101			
	an, Net al. "Power Electronics: Converters, Application and Design", Wiley India (P)	Itd	Nev		lh
	r, recall i ower Electronics. Converters, Application and Design, whey india (F)	Liu,	1101	, De	

Mohar 2007. Ί.

PO CO	CO Statement	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	PO 7	PO 8	РО 9	PO1 0	PO1 1
CO1	Remember the overview of power semiconductor switches	1	3	1	1	1	1	3	1	1	1	1
CO2	Analyze the thermal requirements of power semiconductor devices	1	1	3	3	1	1	3	1	1	2	1
CO3	Understand the basic concepts of ZVS and ZCS	1	1	2	2	2	1	1	1	1	3	1
CO4	Evaluate the design aspects of various magnetic components according to specific requirements.	2	3	2	3	3	1	2	2	1	2	2
CO5	Understand the design concepts of circuit elements	2	2	3	2	3	1	2	3	1	2	2

18PEC12

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3

Course Objectives:

- 1. To provide the electrical circuit concepts behind the different working modes of power Converters so as to enable deep understanding of their operation.
- 2. To equip with required skills to derive the criteria for the design of power converters starting from basic fundamentals.
- 3. To analyze and comprehend the various operating modes of different configurations of power converters.

Unit I SINGLE PHASE AND THREE PHASE AC TO DC CONVERTERS

Single phase and three phase ac to dc converters - Half controlled and Fully controlled converters semi converters with RL, RLE loads, with and without free-wheeling diodes - Continuous and discontinuous modes of operation - Output general expressions - Dual Converter – performance parameters - effect of source and load inductances and overlap- Power factor improvement techniques- Generation of Gating Sequence. Reactive power and power balance in converter circuits.

Unit II DC TO DC CONVERTERS

9 + 0

+ 0

0

+ 0

9

9

9

9 + 0

Non-Isolated DC-DC Converters-Buck converter –Boost converter -Buck-Boost converter -Cuk converter-CCM and DCM operation –Output Voltage ripple - Limitations of Single stage conversion - Isolated DC-DC Converters - Flyback converters - Forward converters - Push-Pull converters- Full bridge converters–Current mode and Voltage mode control - Design of Snubbers.

Unit III SINGLE PHASE INVERTERS AND POWER CONDITIONERS

Principle of operation of half and full bridge inverters – Performance parameters – Voltage control of single phase inverters using various PWM techniques – various harmonic elimination techniques – forced commutated thyristor inverters- power conditioners-UPS: offline UPS, online UPS.

Unit IV THREE PHASE VOLTAGE SOURCE INVERTERS AND MULTI LEVEL CONVERTERS

180 degree and 120 degree conduction mode inverters with star and delta connected loads – voltage control of three phase inverters: single, multi pulse, sinusoidal, space vector modulation techniques – Application to drive system- Multilevel concept – diode clamped – flying capacitor – cascade type multilevel inverters - Comparison of multilevel inverters - application of multilevel inverters .

Unit V CURRENT SOURCE INVERTER

Operation of six-step thyristor inverter – inverter operation modes – load – commutated inverters – Auto sequential current source inverter (ASCI)– current pulsations –comparison of current source inverter and voltage source inverters – PWM techniques for current source inverters.

Total (L+T)= 45 Periods

lpon completion of this course, the students will be able to:

CO1	:	Get expertise in the working modes and operation of Power converters.
CO2	:	Select and design dc-dc converter topologies for a broad range of power conversion applications.
CO3	:	Design single phase and three phase inverters
C04	:	Formulate and design the inverters for generic loads and machine loads.
C05	:	Acquire knowledge on multilevel inverters and modulation techniques

Text Books:

Course Outcomes:

1.	Mohan, Net al. "Power Electronics: Converters, Application and Design", Wiley India (P) Ltd, New Delhi, 3 rd Edition 2010.
2.	Bimbhra, P.S, "Power Electronics ", Khanna Publishers, New Delhi, 4 th Edition, 2012.
3.	Bimal K. Bose "Modern Power Electronics and AC Drives", Pearson Education, Second Edition, 2003.

Ref	Reference Books:													
1.	Murphy, J.M.D and Turnbull, F.G " Power Electronics Control of AC Motors ", Pergamon Press,													
	Oxford, 1988.													
2.	Rashid M.H., "Power Electronics: Circuits, Devices and Applications ", Pearson, 3 rd Edition, 2014.													
3.	P.C. Sen, "Modern Power Electronics", Wheeler Publishing Co, First Edition, New Delhi, 1998.													
4.	Jai P.Agrawal, "Power Electronics Systems", Pearson Education, Second Edition, 2002													

PO	CO Statement	PO1	PO 2	PO 3	PO4	PO 5	PO 6	PO 7	PO 8	PO 9	PO10	PO1 1
CO1	Get expertise in the working modes and operation of Power converters.	3	3	1	1	1	1	2	3	1	1	1
CO2	Select and design dc-dc converter topologies for a broad range of power conversion applications.	2	2	2	1	2	1	2	3	1	1	2
CO3	Design single phase and three phase inverters	1	2	1	3	2	1	1	1	1	2	1
CO4	Formulate and design the inverters for generic loads and machineloads.	1	1	1	2	1	1	1	1	2	1	1
CO5	Acquire knowledge on multilevel inverters and modulation techniques	1	1	1	1	1	1	1	2	1	1	1

1	I8PE	EC1	3	ADVANCED POWER ELECTRONICS LABORATORY-I	L	Т	Ρ	С					
					0	0	4	2					
Cou	rse	Obj	jective	es:									
1.	То	prov	vide ar	n insight on the switching behaviors of power electronic switches									
2.	ele	ctro	nic sw										
3.	clo	sed	-loop c	students capable of implementing analog interfacing as well as control control for power electronic system									
4.	implementing the same using simulation tools												
LIST	LIST OF EXPERIMENTS:												
	2. 3. 4. 5. 6. 7. 8. 9. 11. 12. 13. 14. 15. 16. 17. 18. 9. 20.	Moc Sim Sim Sim Sim Sim Sim Sim Sim Sim Full Full	(i) delling delling delling ulatior	Power electronics Switches with and without Snubber IGBT (ii) MOSFET of simple PN junction diodes of SCR of MOSFET / IGBT / BJT of 1-phase semi-converter with R-load, RL load, and RLE (Motor) load of 1-phase fully controlled converter with R-load, RL load, and RL ring angles. of 1-phase dual converter. of 3-phase dual converter. of 3-phase fully controlled converter at different firing angles. of 1-phase fully controlled converter at different firing angles. of 3-phase full bridge inverter. of 3-phase full bridge inverter. of 3-phase full bridge inverter. of 3-phase full bridge inverter. of 3-phase AC voltage controller. of MOSFET / IGBT based choppers. of DC-DC Buck-Boost converter with RL load. of Series Resonant converter with RL load. solution of ordinary differential, partial and integral equations using M/ rter fed resistive load rter fed Resistive-Back Emf (RE) load at different firing angles erter fed Resistive-Inductive Load at different firing angles	E (r		r) lo	ad at					
	Z1.	Full	conve	rter fed DC motor load at different firing angles									
				Total (6	0+0)= 60) Pe	riods					
Cou	rse	Out	tcome			,							
				of this course, the students will be able to:									
Ċ01	1	:	Mode	power electronics converter/Inverter in software									
C02	2	:	Simul	ate any power electronic converter/Inverter									
CO3	3	:	Obtaiı	n numerical solutions of partial, differential and integral equations									
CO4				ment single phase full converter for any type of R and RL load									
COS	5	:	Imple	ment single phase full converter for dc motors									

PQ CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Model power electronics converter/Inverter in software	1	3	1	3	3	1	2	3	1	1	1
CO2	Simulate any power electronic converter/Inverter	1	1	2	1	3	1	2	3	1	1	1
CO3	Obtain numerical solutions of partial, differential and integral equations	1	2	1	3	2	1	1	1	1	1	2
CO4	Implement single phase full converter for any type of R and RL load	1	1	1	3	3	1	2	2	1	2	1
CO5	Implement single phase full converter for dc motors	1	1	1	1	3	1	1	2	2	1	1

	18PEC14	ADVANCED DIGITAL CONTROL LABORATORY	L	Т	Ρ	С
			0	0	4	2
Cοι	Irse Objectives:					
1.	Implementation of DS	C to various control techniques				
2.	Writing coding for con	trol techniques				
LIS	T OF EXPERIMENTS:					
		with DSC and displaying a message				
	2. Generation of Squa	are Trigger Pulse using DSC				
	3. Measurement of V	oltage/Current/Temperature				
	4. Open loop control	of Buck/Boost/Buck-Boost Converter using DSC				
	5. Closed loop contro	l of Buck/Boost/Buck-Boost Converter using DSC				
	6. Single phase squa	re wave inverter control in open loop using DSC				
	7. Single phase squa	re wave inverter control in closed loop using DSC				
	8. Single Phase AC-E	DC Converter in open loop using DSC				

- 9. Single Phase AC-DC Converter in closed loop using DSC
- Sine PWM based single phase inverter using DSC
 Single phase AC Voltage controller control using DSC
- 12. Three Phase Inverter control using DSC

Course Outcomes:

Upon completion of this course, the students will be able to:

CO1	:	Understand the peripheral requirements for controlling the circuit
C02	•••	Understand and implement the configurations of various required peripherals
CO3	:	Write coding to implement the devised control technique
CO4	:	Understand and implement the measurement principles through digital techniques
CO5	:	Develop algorithms for implementation of controls and implement isolation techniques for
		power control

Total (60+0)= 60 Periods

	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
PQ CO												
CO1	Understand the peripheral requirements for controlling the circuit	1	1	1	1	1	1	1	1	1	1	1
CO2	Understand and implement the configurations of various required peripherals	1	1	1	1	1	1	1	1	1	1	1
CO3	Write coding to implement the devised control technique	1	1	1	1	1	1	1	1	1	1	1
CO4	Understand and implement the measurement principles through digital techniques	1	1	1	1	1	1	1	1	1	1	1
CO5	Develop algorithms for implementation of controls and implement isolation techniques for power control	1	1	1	1	1	1	1	1	1	1	1

18	MLC	01 RESEARCH METHODOLOGY AND IPR	L	Τ	Ρ	С
0	Dee	OBJECTIVES:	3	0	0	3
		develop the subject of their research, encourage the formation of a higher level of tr	ainad	intol	oct	
1.	abil app	lity, critical analysis, rigor, and independence of thought, foster individual judgment plication of research theory and methods, and develop skills required in writing res orts and dissertation.	, and	skill	in t	the
	1	INTRODUCTION TO RESEARCH		9	+	0
Mea prob inves	ning Iem, stigat	of research problem, Sources of the research problem, Criteria Characteristics of Errors in selecting a research problem, Scope and objectives of the research problem ion of solutions for research problem, data collection, analysis, interpreta tations.	n. App	od res	seai hes	rch to
UNI	, 11	EFFECTIVE LITERATURE STUDIES APPROACHES, ANALYSIS		9	+	0
the	reliab	or evaluating research approach - Hypotheses: Parametric and non-parametric test ility and validity of findings with literature review and experiments – documenta ethics.	•			•
UNI		EFFECTIVE TECHNICAL WRITING, HOW TO WRITE REPORT, PAPER		9	+	0
	elopir mittee	ng a Research Proposal, Format of a research proposal, a presentation and assessr e	nent l	by a	revi	ew
inno	vatior	Designs, Trade and Copyright. The process of Patenting and Development: technon, patenting, development. International Scenario: International cooperation on Intelector for grants of patents, Patenting under PCT.	-			
UNI	۲V	PATENT RIGHTS AND IPR		9	+	0
		Patent Rights. Licensing and transfer of technology. Patent information and database		-	-	
		s.New Developments in IPR: Administration of Patent System. New developments	s in II	PR; I	PR	of
Biolo	gical	Systems, Computer Software etc. Traditional knowledge Case Studies, IPR and IITs.	4.01	45 D		-1
0	RSE	OUTCOMES:	otal =	45 Pe	erio	as
		npletion of this course, the students will be able to:				
C01		Understand research problem formulation.				
C02	:	Analyze research-related information				
CO3	:	Follow research ethics				
C04	:	Understand that today's world is controlled by Computer, Information Technolog world will be ruled by ideas, concept, and creativity.	iy, bu	it ton	norr	ow
C05	:	Understand that IPR protection provides an incentive to inventors for further resinvestment in R & D, which leads to the creation of new and better products, and in economic growth and social benefits.				
TEX	т во	OKS:				
1.	Stua	rt Melville and Wayne Goddard, "Research methodology: an introduction for science gineering students"				
	W/av	ne Goddard and Stuart Melville, "Research Methodology: An Introduction"				
2.	vvay					
3.	Ran	it Kumar, 2 nd Edition, "Research Methodology: A Step by Step Guide for beginners"				
3. 4.	Ranj Halb					

1.	Mayall, "Industrial Design", McGraw Hill, 1992.
2.	Niebel, "Product Design", McGraw Hill, 1974.
3.	Asimov, "Introduction to Design", Prentice Hall, 1962.
4.	Robert P. Merges, Peter S. Menell, Mark A. Lemley, "Intellectual Property in New Technological Age", 2016.
5.	T. Ramappa, "Intellectual Property Rights Under WTO", S. Chand, 2008

PQ CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Understand research problem formulation.					1	1	1	1	1	2	1
CO2	Analyze research- related information					3	1	1	1	1	1	1
CO3	Follow research ethics					1	1	1	1	3	1	1
CO4	Understand that today's world is controlled by Computer, Information Technology, but tomorrow world will be ruled by ideas, concept, and creativity.					1	3	1	1	1	1	1
CO5	Understand that IPR protection provides an incentive to inventors for further research work and investment in R & D, which leads to the creation of new and better products, and in turnbrings about, economic growth and social benefits.					1	3	1	1	1	2	2

	C21 MODELLING AND ANALYSIS OF ELECTRICAL MACHINES			-
Course	Objectives:	3 0	0	3
	o introduce the basics of DC machines and analyze magnetic circuits			
	o analyze the steady state and dynamic state operation of Induction machine through	mathem	atical	
m	odeling.			
	o analyze the various types of machines and model with different transformation tech			
	b study the phase controlled, frequency controlled and vector controlled of induction b study the special machines and its model	motor		
5. TC				
Unit I	MODELLING OF DC MACHINES	9	+	0
shunt, se	ent circuit and electromagnetic torque - Electromechanical modelling - Field exc eries and compound excitation - commutator action. Effect of armature mmf - Analyti circuit aspects- magnetic circuit aspects- interpoles.			
Unit II	DYNAMIC MODELLING OF INDUCTION MACHINES	9	+	0
	ent circuits - steady state performance equations - Dynamic modelling of induction	-	-	-
	generalized model in arbitrary reference frames - stator reference, rotor reference reference frames model.			1519
Unit III	PHASE CONTROLLED AND FREQUENCY CONTROLLED INDUCTION	9	+	0
	oltage control: Steady state analysis- approximate analysis- slip power recovery scl	heme: pri		
	n - steady state analysis: Range of slip - equivalent circuit - performance chara			
	us drive. Constant Volts/Hz controls implementation - steady state performance - dy	namic sir	nulati	on.
PWM vo	Itages: Generation - machine model - computation of steady state performance .			
Unit IV	VECTOR CONTROLLED INDUCTION MOTOR	9	+	0
Principle space v operatio	VECTOR CONTROLLED INDUCTION MOTOR e of vector control-direct vector control: flux and torque processor-DVC in stator reference vector modulation. Indirect vector control scheme: derivation and implementation. n: principle of flux weakening operation-flux weakening in stator flux linkages-contro k linkages-controlled schemes.	rence frai . Flux we	mes v eaken	vith ing
Principle space v operatio rotor flux	e of vector control-direct vector control: flux and torque processor-DVC in stator reference of vector modulation. Indirect vector control scheme: derivation and implementation. n: principle of flux weakening operation-flux weakening in stator flux linkages-contro (inkages-controlled schemes.	rence frai . Flux we	mes v eaken	vith ing
Principle space v operatio rotor flux Unit V	e of vector control-direct vector control: flux and torque processor-DVC in stator reference ector modulation. Indirect vector control scheme: derivation and implementation. n: principle of flux weakening operation-flux weakening in stator flux linkages-contro (linkages-controlled schemes. SPECIAL MACHINES	rence frai Flux we illed sche	mes v eaken mes a	vith ing and
Principle space v operatio rotor flux Unit V Permane density productio	e of vector control-direct vector control: flux and torque processor-DVC in stator reference of vector modulation. Indirect vector control scheme: derivation and implementation. n: principle of flux weakening operation-flux weakening in stator flux linkages-contro (inkages-controlled schemes.	Iled sche	mes v eaken mes a + on - 1	vith ing and 0 ilux que
Principle space v operatio rotor flux Unit V Permane density productio	of vector control-direct vector control: flux and torque processor-DVC in stator reference ector modulation. Indirect vector control scheme: derivation and implementation. n: principle of flux weakening operation-flux weakening in stator flux linkages-contro c linkages-controlled schemes. SPECIAL MACHINES ent magnet and characteristics - Synchronous machines with PMs: Machine co distribution - types of PMSM - Variable Reluctance Machines: principle of op on - Stepping motors: principle of operation- types: Variable reluctance – Hybrid o - characteristics.	Prence frai Flux we lled sche 9 onfiguratio peration motor -	mes v eaken mes a + on - 1 - torc	vith ing and 0 ilux que
Principle space v operatio rotor flux Unit V Permane density production	of vector control-direct vector control: flux and torque processor-DVC in stator reference ector modulation. Indirect vector control scheme: derivation and implementation. n: principle of flux weakening operation-flux weakening in stator flux linkages-contro c linkages-controlled schemes. SPECIAL MACHINES ent magnet and characteristics - Synchronous machines with PMs: Machine co distribution - types of PMSM - Variable Reluctance Machines: principle of op on - Stepping motors: principle of operation- types: Variable reluctance – Hybrid o - characteristics.	Iled sche	mes v eaken mes a + on - 1 - torc	vith ing and 0 ilux que
Principle space v operatio rotor flux Unit V Permane density production equation	of vector control-direct vector control: flux and torque processor-DVC in stator references of vector modulation. Indirect vector control scheme: derivation and implementation. n: principle of flux weakening operation-flux weakening in stator flux linkages-control clinkages-controlled schemes. SPECIAL MACHINES ent magnet and characteristics - Synchronous machines with PMs: Machine condistribution - types of PMSM - Variable Reluctance Machines: principle of operation - Stepping motors: principle of operation- types: Variable reluctance - Hybrid - characteristics. Total (L Outcomes: mpletion of this course, the students will be able to:	9 onfiguration motor -	mes v eaken mes a + on - 1 - torc	vith ing and 0 ilux que
Principle space v operatio rotor flux Unit V Permane density production equation	of vector control-direct vector control: flux and torque processor-DVC in stator references of vector control scheme: derivation and implementation. n: principle of flux weakening operation-flux weakening in stator flux linkages-control clinkages-controlled schemes.	rence frai . Flux we lled sche 9 onfiguratic peration motor - .+T)= 45 circuits.	mes v eaken mes a - toro - toro - Toro	vith ing and lux que
Principle space v operatio rotor flux Unit V Permane density production equation Course Upon co	of vector control-direct vector control: flux and torque processor-DVC in stator references of vector modulation. Indirect vector control scheme: derivation and implementation. n: principle of flux weakening operation-flux weakening in stator flux linkages-control clinkages-controlled schemes. SPECIAL MACHINES ent magnet and characteristics - Synchronous machines with PMs: Machine condistribution - types of PMSM - Variable Reluctance Machines: principle of operation - Stepping motors: principle of operation- types: Variable reluctance - Hybrid - characteristics. Total (L Outcomes: mpletion of this course, the students will be able to:	rence frai . Flux we lled sche 9 onfiguratic peration motor - .+T)= 45 circuits.	mes v eaken mes a - toro - toro - Toro	vith ing and lux que
Principle space v operatio rotor flux Unit V Permane density productie equation Course Upon co CO1 :	of vector control-direct vector control: flux and torque processor-DVC in stator references of vector control scheme: derivation and implementation. n: principle of flux weakening operation-flux weakening in stator flux linkages-control clinkages-controlled schemes.	rence frai . Flux we lled sche 9 onfiguratic peration motor - .+T)= 45 circuits. s on them	mes v eaken mes a - torc - torc - Torc	vith ing and 0 ilux que
Principle space v operatio rotor flux Unit V Permane density productio equation CO1 : CO2 :	of vector control-direct vector control: flux and torque processor-DVC in stator reference of vector modulation. Indirect vector control scheme: derivation and implementation. n: principle of flux weakening operation-flux weakening in stator flux linkages-controls (linkages-controlled schemes. SPECIAL MACHINES ent magnet and characteristics - Synchronous machines with PMs: Machine condistribution - types of PMSM - Variable Reluctance Machines: principle of operation - Stepping motors: principle of operation- types: Variable reluctance — Hybrid - characteristics. Total (L Outcomes: Methods about the DC machines and AC machines and their magnetic of develop mathematical model of AC & DC machines and perform transient analysis	<pre>rence frai . Flux we illed sche 9 onfiguratio peration 1 motor - .+T)= 45 circuits. s on them tionships.</pre>	mes v eaken mes a + on - 1 - toro - Toro	ods
Principle space v operatio rotor flux Unit V Permane density production equation CO1 : CO2 : CO2 :	A of vector control-direct vector control: flux and torque processor-DVC in stator references of vector control scheme: derivation and implementation. n: principle of flux weakening operation-flux weakening in stator flux linkages-control clinkages-controlled schemes. SPECIAL MACHINES ent magnet and characteristics - Synchronous machines with PMs: Machine condistribution - types of PMSM - Variable Reluctance Machines: principle of operation - Stepping motors: principle of operation- types: Variable reluctance – Hybrid or - characteristics. Total (L Outcomes: Machine students will be able to: Acquire knowledge about the DC machines and AC machines and their magnetic of develop mathematical model of AC & DC machines and perform transient analysis Understand the different types of reference frame theories and transformation rela Analyze the steady state and dynamic operation of three phase induct	<pre>rence frai . Flux we illed sche 9 onfiguratio peration 1 motor - .+T)= 45 circuits. s on them tionships.</pre>	mes v eaken mes a + on - 1 - toro - Toro	vith ing and lux jue jue
Principle space v operatio rotor flux Unit V Permane density production equation CO1 : CO2 : CO2 : CO3 :	of vector control-direct vector control: flux and torque processor-DVC in stator references modulation. Indirect vector control scheme: derivation and implementation. n: principle of flux weakening operation-flux weakening in stator flux linkages-controcted inkages-controlled schemes. SPECIAL MACHINES ent magnet and characteristics - Synchronous machines with PMs: Machine condistribution - types of PMSM - Variable Reluctance Machines: principle of operation - Stepping motors: principle of operation- types: Variable reluctance - Hybrid - characteristics. Total (L Outcomes: mapletion of this course, the students will be able to: Acquire knowledge about the DC machines and AC machines and their magnetic of develop mathematical model of AC & DC machines and perform transient analysis Understand the different types of reference frame theories and transformation rela Analyze the steady state and dynamic operation of three phase induct transformation theory based mathematical Modelling and Special machines. Select strategies to control the torque for a given application.	<pre>rence frai . Flux we illed sche 9 onfiguratio peration 1 motor - .+T)= 45 circuits. s on them tionships.</pre>	mes v eaken mes a + on - 1 - toro - Toro	vith ing and lux jue jue

2.	P.S.Bimbra,"generalized theory of Electric machines", khanna publishers, 5th Edition, 2007.												
Re	Reference Books:												
1.	Charles Kingley, Jr., A.E.Fitzgerald, Stephen D.Umans, "Electric Machinery", Tata McGraw Hill, 6th Edition, 2002.												
2	Miller, T.J.E., "Brushless Permanent Magnet and Reluctance Motor Drives", Clarendon Press												

PO CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO1 0	PO1 1
CO1	Acquire knowledge about the DC machines and AC machines and their magnetic circuits.	2	1	1	1	3	1	3	1	1	1	1
CO2	develop mathematical model of AC & DC machines and perform transient analysis on them.	2	1	3	3	1	1	3	1	1	1	1
CO3	Understand the different types of reference frame theories and transformation relationships.	2	2	2	2	3	1	3	1	1	3	1
CO4	Analyze the steady state and dynamic operation of three phase induction motor using transformation theory based mathematical Modelling and Special machines.	2	3	2	3	3	1	2	2	1	2	1
CO5	Select strategies to control the torque for a given application.	2	2	3	3	3	1	2	1	1	2	2

	MODERN ELECTRICAL DRIVES	L T 3 0	P 0	(
		5 0	U	<u> </u>
Course Objec				
	rstand steady state operation and transient dynamics of a motor load system			
quantitat		-		
	/ze and design the current and speed controllers for a closed loop solid state DC I			
4. To under	rstand the implementation of control algorithms using microcontrollers and phase	locked	loop	•
Unit I DC M	NOTORS FUNDAMENTALS AND MECHANICAL SYSTEMS	9	+	(
Ward Leonard drives and mod types of load; F	pes, induced emf, speed-torque relations; Speed control - Armature and field I control - Constant torque and constant horse power operations. Introduction dern drives. Characteristics of mechanical system - dynamic equations, compon Requirements of drives characteristics -multi-quadrant operation; Drive elements, tion of motor rating.	to high ents of	spe torq	ee ue
Unit II CON	NVERTER CONTROL	9	-	0
	nase control - Fundamental relations; Analysis of series and separately excited	_	tor w	_
	armature current operations; Current ripple and its effect on performance; (liode; Implementation of braking schemes; Drive employing dual converter.		JI W	
Unit III 🛛 INT	RODUCTION TO INDUCTION MOTORS	9	+	0
Variable voltag	performance equations – Rotating magnetic field – torque production, Equi ge, constant frequency operation –Variable frequency operation, constant Volt			
Drive operating	g regions, variable stator current operation, different braking methods.			
Unit IV FIE	LD ORIENTED CONTROL	9	-	0
	control of Induction machines – Theory – DC drive analogy – Direct and Indirect r	-		-
	ion - Direct torque control of Induction Machines – Torque expression with st			
fluxes, DTC co				10
Unit V SYN	ICHRONOUS MOTOR DRIVES	9	+	0
Wound field a	vlindrical rotor motor – Equivalent circuits – performance equations of operation		volta	ige
vvouna nela Cy		from a	VUILE	and
source - start	ting and braking, self control - Load commutated Synchronous motor drives			
source – start	ting and braking, self control – Load commutated Synchronous motor drives tation.	s - Bru	sh a	
source – start Brushless excit	ting and braking, self control – Load commutated Synchronous motor drives tation. Total (L+1	s - Bru	sh a	
source – start Brushless excit Course Outco	ting and braking, self control – Load commutated Synchronous motor drives tation. Total (L+1	s - Bru	sh a	
source – start Brushless excit Course Outco Upon completio	ting and braking, self control – Load commutated Synchronous motor drives tation. Total (L+1 pmes:	s - Bru	sh a	
source – start Brushless excit Course Outco Upon completie CO1 : Unde CO2 : Anal	ting and braking, self control – Load commutated Synchronous motor drives tation. Total (L+1 omes: ion of this course, the students will be able to:	s - Bru	sh a	
source – start Brushless excit Course Outco Upon completie CO1 : Unde CO2 : Anal sing	ting and braking, self control – Load commutated Synchronous motor drives tation. Total (L+1 Tomes: ion of this course, the students will be able to: lerstand selection of drives for industries. lyse various characteristics of series and separately excited DC motor with le and three phase converters.	s - Bru	sh a	
source – start Brushless excit Course Outco Upon completie CO1 : Unde CO2 : Anal sing CO3 : Expl CO4 : Expl	ting and braking, self control – Load commutated Synchronous motor drives tation. Total (L+1 pmes: ion of this course, the students will be able to: lerstand selection of drives for industries. lyse various characteristics of series and separately excited DC motor with ile and three phase converters. lain about different conventional speed control methods for induction motors. lain about direct and indirect methods of field oriented control and direct Torque C	s - Bru [)= 45 F	sh a	bds
source – start Brushless excit Course Outco Upon completie CO1 : Unde CO2 : Anal sing CO3 : Expl CO4 : Expl for li	ting and braking, self control – Load commutated Synchronous motor drives tation. Total (L+1) Total (L+1) Total selection of drives for industries. Ivse various characteristics of series and separately excited DC motor with le and three phase converters. Iain about different conventional speed control methods for induction motors. Iain about direct and indirect methods of field oriented control and direct Torque C nduction motor.	s - Bru [)= 45 F	sh a	bd
source – start Brushless excit Course Outco Upon completie CO1 : Unde CO2 : Anal singu CO3 : Expl CO4 : Expl for li CO5 : Form	ting and braking, self control – Load commutated Synchronous motor drives tation. Total (L+1 pmes: ion of this course, the students will be able to: lerstand selection of drives for industries. lyse various characteristics of series and separately excited DC motor with ile and three phase converters. lain about different conventional speed control methods for induction motors. lain about direct and indirect methods of field oriented control and direct Torque C	s - Bru [)= 45 F	sh a	bd
source – start Brushless excit Course Outco Upon completie CO1 : Unde CO2 : Anal sing CO3 : Expl CO4 : Expl CO4 : Expl for li CO5 : Form	ting and braking, self control – Load commutated Synchronous motor drives tation. Total (L+1) Total (L+1) Total selection of this course, the students will be able to: Ierstand selection of drives for industries. Iyse various characteristics of series and separately excited DC motor with le and three phase converters. Iain about different conventional speed control methods for induction motors. Iain about direct and indirect methods of field oriented control and direct Torque C nduction motor. mulate the control schemes for synchronous motor drives.	s - Bru	sh a	bd
source – start Brushless excit Course Outco Upon completie CO1 : Unde CO2 : Anal sing CO3 : Expl CO4 : Expl for li CO5 : Form Text Books: 1. Dubey,G.	ting and braking, self control – Load commutated Synchronous motor drives tation. Total (L+1 omes: ion of this course, the students will be able to: lerstand selection of drives for industries. lyse various characteristics of series and separately excited DC motor with ile and three phase converters. lain about different conventional speed control methods for induction motors. lain about direct and indirect methods of field oriented control and direct Torque C nduction motor. mulate the control schemes for synchronous motor drives. K. "Power Semiconductor Controlled Drives ", PH International, New Jersey, 198	s - Bru	sh a	bd
source – start Brushless excit Course Outco Upon completie CO1 : Unde CO2 : Anal sing CO3 : Expl CO4 : Expl for li CO5 : Forn Text Books: 1. Dubey,G. 2. Sen, P.C.	ting and braking, self control – Load commutated Synchronous motor drives tation. Total (L+1) Total (L+1) Total selection of this course, the students will be able to: Ierstand selection of drives for industries. Iyse various characteristics of series and separately excited DC motor with le and three phase converters. Iain about different conventional speed control methods for induction motors. Iain about direct and indirect methods of field oriented control and direct Torque C nduction motor. mulate the control schemes for synchronous motor drives.	s - Bru	sh a	bd

R.Krishnan, "Electric Motor Drives – Modeling, Analysis and Control", Prentice-Hall of India Pvt. Ltd., New Delhi, 2003.

Ref	Reference Books:												
1.	Subharamanyam V. "Electric Drives-Concepts and Applications ", TMH Publi., 1994												
2.	GobalK.Dubey, "Fundamentals of Electrical Drives", Narosal Publishing House, New Delhi,Second Edition ,2009.												
3.	W.Leonhard, "Control of Electrical Drives", Narosa Publishing House, 1992.												
4.	Murphy J.M.D and Turnbull, "Thyristor Control of AC Motors", Pergamon Press, Oxford, 1988												

PO CO	CO Statement	PO1	PO 2	PO 3	PO4	PO 5	PO 6	PO 7	PO 8	PO 9	PO10	PO1 1
CO1	Understand selection of drives for industries.	1	1	1	1	2	1	2	1	2	1	2
CO2	Analyse various characteristics of series and separately excited DC motor with single and three phase converters.	1	3	3	2	2	1	2	2	1	1	1
CO3	Explain about different conventional speed control methods for induction motors.	1	1	1	2	2	1	1	2	1	1	1
CO4	Explain about direct and indirect methods of field oriented control and direct Torque Control scheme for Induction motor.	1	1	2	2	2	1	2	2	1	1	1
CO5	Formulate the control schemes for synchronous motor drives.	1	2	3	2	3	1	2	2	1	1	1

	18	PEC	C23 ADVANCED POWER ELECTRONICS LABORATORY II	L	Т	Ρ	С					
				0	0	4	2					
Cou	rse	Ob	jectives:									
1.	То	pro	vide an insight on the switching behaviours of power electronic switches									
2.	То	ma	ke the students familiar with the digital tools used in generation of gate pulse	s for	the	pow	er					
			nic switches									
3.			ke the students capable of implementing analog interfacing as well as contro	l circ	uits	used	l in a					
			-loop control for power electronic system									
4.	To make the students acquire knowledge on mathematical modelling of power electronic circuits and											
	implementing the same using simulation tools											
LIST		- EX	(PERIMENTS:									
	1.	Dur	namic characteristics of SCR and TRIAC									
			namic characteristics of MOSFET, BJT and IGBT									
			gle phase ac voltage controller using SCR and TRIAC									
			ee phase half and fully controlled bridge converter									
			gle phase series inverter									
			BT based three phase PWM Inverter									
			SFET based buck boost converter									
8	8.	DC-	-DC forward converter									
ļ	9.	DC-	-DC flyback converter									
			gle phase dual converter									
			series resonant converter									
0		0	Total (6	60+0)= 60	0 Pe	riods					
			tcomes:									
		omp.	letion of this course, the students will be able to:									
C01			Implement ac voltage controller									
C02		:	Obtain the performance of any type of converter									
CO3			Analyse the performance of single phase and three phase inverter									
C04		:	Implement DC-DC converter									
C05)		Analyse the performance of resonant converter									

CO5	:	Analyse the performance of resonant converter	

PO CO	CO Statement	PO1	PO 2	PO 3	PO4	PO 5	PO 6	PO 7	PO 8	PO 9	PO10	PO1 1
CO1	Implement ac voltage controller	2	1	3	3	3	1	2	3	2	1	2
CO2	Obtain the performance of any type of converter	2	3	3	1	3	1	2	3	1	1	1
CO3	Analyse the performance of single phase and three phase inverter	2	3	1	1	2	1	1	1	1	1	1
CO4	Implement DC-DC converter	1	1	3	3	3	1	2	3	1	1	1
CO5	Analyse the performance of resonant converter	2	3	3	1	3	1	2	3	1	1	1

	18PEC24	ADVANCED ELECTRICAL DRIVES LABORATORY	L	Τ	Ρ	С
			0	0	4	2
Cou	rse Objectives:					
1.	To analyze the	operation of DC and AC motor drives				
2.	To study the p	erformance of PMSM, BLDC and SRM drives				
3.	To gain knowle	dge on closed loop control of PMSM, BLDC and SRM drives.				
LIST	OF EXPERIME					
	1. Four quadra	nt chopper fed DC motor drive				
2	V/f control o	f three phase induction motor with voltage source inverter				
:	3. DSP based	speed control of SRM motor				
4	 DTC control 	of Induction motor drive				
Ę	5. Self-controlle	ed synchronous motor drive				
(6. Closed loop	control of PMSM motor				
-	7. Simulation s	tudy of four quadrant operation of DC drives using dual converter	circuit			
8	3. Simulation s	tudy of Field oriented control induction motor drive				
9	9. Simulation s	tudy of CSI fed three phase induction motor drive				
	10. Simulation s	tudy of closed loop control of BLDC motor drive				
		Tota	l (60+0)= 6	0 Pe	riod
Cou	rse Outcomes:					
Upo	n completion of	this course, the students will be able to:				
C01	: Design	closed loop control for PMSM and SRM drives.				
C02	: Analvze	the operation of VSI and CSI fed induction motor drives				

Analyze the operation of VSI and CSI fed induction motor drives Select suitable inverter configuration and control for three phase induction motor drives. Analyze the operation of synchronous motor drives. Use digital control for special motor drives.

CO2 CO3 CO4 :

C05

PQ CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Design closed loop control for PMSM and SRM drives.	2		3	2		1		2		1	
CO2	Analyze the operation of VSI and CSI fed induction motor drives	1	3						1			
CO3	Select suitable inverter configuration and control for three phase induction motor drives.	3		1					1			2
CO4	Analyze the operation of synchronous motor drives.	1	3						2			
CO5	Use digital control for special motor drives.	2			3	1			1			

18P	PEE11 ADVAN	CED M	ICRO	CONT	ROLLE	R BAS	SED S	YSTEN	I DESI	GN	LT	P C
											3 0	0 3
	Objectives:	<u></u>			P							
	implement digital control learn various DSP periph						to pow	er app	licatior	าร		
	· ·						•					
	INTRODUCTION TO DS								lomon	. 0	9	+ 0
	F CPU Core – Programm – Flash and EEPROM Pr			PU R	egister	s – DS	PEng	ine – iv	iemory	/ Organ	iization -	- Dala –
Unit II	SYSTEM CONFIGURAT		Indes	- Vario		ote - I	Device	Confic	uratio	n - l o	9 w Voltage	+ 0
- I/O Ports		aving N	noucs	vanc		1013 - 1	50 100	Conne	Juratio		v vonage	Delect
11		AL C										
Unit III Study, Co	CONTROL PERIPHER onfiguration and control		upt St	ructure	e – Tin	ners –	Captu	ire and	d Com	pare -		+ 0
	on to IDE for dsPIC and F									paro	712 00	
Unit IV	MOTOR CONTROL PE			•							9	+ 0
-	ntrol PWM – Different PV		-		Time –	Outpu	t and I	Polarity	Conti	rol – P\	-	
	re Encoder Interface						-					
Unit V	APPLICATIONS										9	+ 0
	pop Control of Single and	d three	Phase	e VSI,	Senso	ored an	nd Ser	sorles	s BLD	C Mot		-
Induction	Motor Control – Vector	Control										
Channel I	Digital Voltmeter with Disp	olay										
									Т	otal (L·	+T)= 45	Periods
Course C	Dutcomes:											
Upon con	npletion of this course, the	e stude	ents wil	l be al	ole to:							
CO1 :	Understand various DSF											
CO2 :	Understand the configur							ver app	olicatio	ons		
CO3 : CO4 :	Write C coding for imple Implement interfacing te							ns				
CO5 :	Understand and implem								applic	ation a	nd imple	ment
Deferrer	control techniques for po	ower el	ectroni	c appl	ications	6						
	e Books: IC30FFamily Reference N	/anual.	Datas	heets								
2. Cree	ed Huddleston, "Intelligen	t Senso	or Desi	gn usi	ng Mic							
3. Zora	an Milivojević, Djordje oElectronika	Saponj	jić, "F	Progra	mming	dsP	IC (E	Digital	Signa	alContr	ollers)	in C",
IVIICI												
PO	CO Statement	PO1	PO	PO	PO4	PO	PO	PO	PO	PO	PO10	PO1
CO			2	3		5	6	7	8	9		1
CO1	Understand various DSP peripherals	1	1	1	1	1		1	1	1	1	1
CO2	Understand the											
	configurations of	1	1	1	1	1		1	1	1	1	1
	peripherals for appropriate power											
	appropriate power applications											
CO3	Write C coding for	1	1	1	1	1		1	1	1	1	1
	implementing controls using peripherals											
CO4	Implement interfacing					4						
	techniques with DSC	1	1	1	1	1		1	1	1	1	1
	for control applications											

CO5	Understand and implement data										
	acquisition and processing for control	1	1	1	1	1	1	1	1	1	1
	application and	1	'	'	'	1	1	1	1		1
	<i>implement</i> control techniques for power										
	electronic applications										

	APPLIED MATHEMATICS FOR ELECTRICAL ENGINEERING	L	T	Ρ	С
Course Objectiv		3	0	0	3
-					
	ze the students in the field of variational problems.				
	the techniques in solving simultaneous equations.				
	he knowledge in solving differential equations.				
	the solutions of linear programming using Graphical and Simplex methods.				
5. To underst	and the overall approach of dynamic programming.				
Unit I CALCU	LUS OF VARIATIONS		9	+	0
Concept of Varia	ion and its properties – Euler's equation – Functional dependent on first and h			der	
	ctional dependent on functions of several independent variables– Some applied Kantorovich methods.	catior	ns –	- Dir	ect
Unit II SOLU	TION OF EQUATIONS	<u> </u>	9	+	0
	method, Curve fitting (Least square), Direct method: Gaussian Elimination,		-		-
	methods – Iterative method: Gauss-Jacobi, Gauss - Seidel Methods.	Joau	133-	-5010	
Unit III NUM	ERICAL SOLUTION OF BOUNDARY VALUE PROBLEMS		9	+	0
	n of ordinary Differential Equations-Euler' method-Euler's modified method –		-	т	v
method and Run	ge – Kutta method for simultaneous equations and 2 nd order equations – Multi	sten	n 3 met	hod	s
Milne's and Adan		Step	met	nou	5 —
				r —	-
	AR PROGRAMMING		9	+	0
Basic concepts –	Graphical and Simplex methods – Transportation problem – Assignment prob	blem			
Unit V DYNA			9	+	0
	lynamic programming model – optimality principle –Examples of dynamic prog		-		0
Elements of the o	lynamic programming model – optimality principle –Examples of dynamic prog solutions.	gramr	min	g	_
Elements of the o	lynamic programming model – optimality principle –Examples of dynamic prog solutions. Total (L+	gramr	min	g	
Elements of the or models and their Course Outcom	lynamic programming model – optimality principle –Examples of dynamic prog solutions. Total (L+	gramr	min	g	
Elements of the c models and their Course Outcom Upon completion CO1 : Unders	lynamic programming model – optimality principle –Examples of dynamic prog solutions. Total (L+ es: of this course, the students will be able to: stand the concept of variational problems and its techniques.	gramr	min	g	
Elements of the c models and their Course Outcom Upon completion CO1 : Unders CO2 : Solve	lynamic programming model – optimality principle –Examples of dynamic prog solutions. Total (L+ es: of this course, the students will be able to: stand the concept of variational problems and its techniques. the linear equations	gramr	min	g	
Elements of the c models and their Course Outcom Upon completion CO1 : Unders CO2 : Solve CO3 : Obtain	lynamic programming model – optimality principle –Examples of dynamic prog solutions. Total (L+ es: of this course, the students will be able to: stand the concept of variational problems and its techniques. the linear equations the numerical solutions of differential equations	gramr	min	g	
Elements of the c models and their Course Outcom Upon completion CO1 : Unders CO2 : Solve CO3 : Obtain CO4 : Solve	lynamic programming model – optimality principle –Examples of dynamic prog solutions. Total (L+ es: of this course, the students will be able to: stand the concept of variational problems and its techniques. the linear equations the numerical solutions of differential equations the numerical solutions of differential equations the Transportation and Routing problems using Optimization Techniques	gramr	min	g	
Elements of the c models and their Course Outcom Upon completion CO1 : Unders CO2 : Solve CO3 : Obtain CO4 : Solve CO5 : Gain th	lynamic programming model – optimality principle –Examples of dynamic prog solutions. Total (L+ es: of this course, the students will be able to: stand the concept of variational problems and its techniques. the linear equations the numerical solutions of differential equations	gramr	min	g	
Elements of the c models and their Course Outcom Upon completion CO1 : Unders CO2 : Solve CO3 : Obtain CO4 : Solve CO5 : Gain th Text Books:	lynamic programming model – optimality principle –Examples of dynamic prog solutions. Total (L+ es: of this course, the students will be able to: stand the concept of variational problems and its techniques. the linear equations the numerical solutions of differential equations the numerical solutions of differential equations the Transportation and Routing problems using Optimization Techniques he knowledge and concept of Dynamic Problems and techniques to solve	gramr • T)= 4	15 F	g	
Elements of the c models and their Course Outcom Upon completion CO1 : Unders CO2 : Solve CO3 : Obtain CO4 : Solve CO5 : Gain th Text Books: 1. Grewal, B.S	lynamic programming model – optimality principle –Examples of dynamic prog solutions. Total (L+ es: of this course, the students will be able to: stand the concept of variational problems and its techniques. the linear equations the numerical solutions of differential equations the numerical solutions of differential equations the Transportation and Routing problems using Optimization Techniques he knowledge and concept of Dynamic Problems and techniques to solve ., Higher Engineering Mathematics, 43 rd edition, Khanna Publishers, New Del	9ramr • T)= 4	14.	g Peric	ods
Elements of the c models and their Course Outcom Upon completion CO1 : Unders CO2 : Solve CO3 : Obtain CO4 : Solve CO5 : Gain th Text Books: 1. Grewal, B.S 2. Gupta, A.S.	lynamic programming model – optimality principle –Examples of dynamic prog solutions. Total (L+ es: of this course, the students will be able to: stand the concept of variational problems and its techniques. the linear equations the numerical solutions of differential equations the numerical solutions of differential equations the Transportation and Routing problems using Optimization Techniques the knowledge and concept of Dynamic Problems and techniques to solve ., Higher Engineering Mathematics, 43 rd edition, Khanna Publishers, New Del , Calculus of Variations with Applications, Prentice Hall of India Pvt. Ltd., New	r T)= 4	14. hi 2	9 Peric	ods
Elements of the c models and their Course Outcom Upon completion CO1 : Unders CO2 : Solve CO3 : Obtain CO4 : Solve CO5 : Gain th Text Books: 1. Grewal, B.S 2. Gupta, A.S. 2. Gerald.C.F	lynamic programming model – optimality principle –Examples of dynamic prog solutions. Total (L+ es: of this course, the students will be able to: stand the concept of variational problems and its techniques. the linear equations the numerical solutions of differential equations the numerical solutions of differential equations the Transportation and Routing problems using Optimization Techniques he knowledge and concept of Dynamic Problems and techniques to solve ., Higher Engineering Mathematics, 43 rd edition, Khanna Publishers, New Del	r T)= 4	14. hi 2	9 Peric	ods
Elements of the c models and their Course Outcom Upon completion CO1 : Unders CO2 : Solve CO3 : Obtain CO4 : Solve CO5 : Gain th Text Books: 1. Grewal, B.S 2. Gupta, A.S. 3. Gerald.C.F Delhi, 2006 4 Taha, H.A.,	In the second se	hi 20 w Del	145 F	g Peric	ods v
Elements of the c models and their Course Outcom Upon completion CO1 : Unders CO2 : Solve CO3 : Obtain CO4 : Solve CO5 : Gain th Text Books: 1. Grewal, B.S 2. Gupta, A.S. 3. Gerald.C.F Delhi, 2006 4. Taha, H.A., Delhi (2014	In the second se	hi 20 w Del n editi	14. 14. 14. 14. 14. 10. 14.	g Peric	ods v

PO CO	CO Statement	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	PO 7	PO 8	PO 9	PO1 0	PO1 1
C01	Understand the concept of variational problems and its techniques.			3	1	1	1	1	1	1	1	1
CO2	Solve the linear equations			3	1	1	2	2	1	1	1	1
CO3	Obtain the numerical solutions of differential equations			3	1	1	2	1	1	2	1	3
CO4	Solve the Transportation and Routing problems using Optimization Techniques			1	1	1	1	2	1	1	1	1
CO5	Gain the knowledge and concept of Dynamic Problems and techniques to solve			1	1	1	2	1	1	1	1	3

18PEE13	SYSTEM THEORY		•	Р	С
		3 ()	0	3
Course Objective					
	on modelling and representing systems in state variable form				
	on solving linear and non-linear state equations				
	the role of controllability and observability				
	vledge on stability analysis of systems using Lyapunov's theory nowledge on modal concepts and design of state and output feedback	aantra	llor		۳d
estimators	nowledge on modal concepts and design of state and output reedback	contro	ner	sa	nu
Colimators					
Unit I STATE V	ARIABLE REPRESENTATION	9)	+	0
	cept of State - State equations for Dynamic Systems - Time invariance	and	ine	arit	/ -
	state model - State Diagrams - Physical System and State Assignment: Lir				
time models – Inve	rted pendulum.				
			_		
	ON OF STATE EQUATIONS	9		+	0
	queness of solutions to Continuous-time state equations - Solution of Nonlin				
Eigenvectors.	e equations - Evaluation of matrix exponential - System modes - Role of E	igenva	liue	s a	na
Eigenvectors.					
Unit III CONTE	ROLLABILITY AND OBSERVABILITY	9		+	0
	Controllability and Observability - Stabilizability and Detectability - Tests	-		nuo	-
	me-varying and Time-invariant cases - Output Controllability - Reduc				
	e-variable canonical forms – Jordan canonical form.	,		,	
Unit IV STABI		9		+	0
	ibrium Points - Stability in the sense of Lyapunov - BIBO Stability -Stability of				
	y of Nonlinear Continuous-Time Autonomous Systems - The Direct Metho				
	Continuous-Time Autonomous Systems - Finding Lyapunov Functions Autonomous Systems - Krasovski and Variable-Gradiant Methods.	s tor i	Nor	nine	ar
Continuous-rime	Rutonomous Systems - Masovski and Vanable-Gradiant Methods.				
Unit V POLE P	LACEMENT	9		+	0
	rollable and Observable Companion Forms: SISO and MIMO Systems - Th	-		Sta	-
	rollability and Observability - Pole Placement by State Feedback for both S				
	er and Reduced Order Observers.				
	Total (L+	-T)= 45	Pe	erio	ds
Course Outcome	S:				
Upon completion c	f this course, the students will be able to:				
CO1 : Underst	and the concept of state variable representation of systems.				
	ear and non-linear state equations.				
	the concepts of controllability and observability.				
	e better understanding of Stability analysis of nonlinear systems.				
	and the concepts of Pole placement and State feedback.				
Text Books:					-
	odern Control System Theory", New Age International, 2005.				
	Digital Control and State Variable Methods", Tata McGraw-Hill Publishing	Comp	any	/ Lt	d.,
New Deini, 20					
Reference Books					
	Modern Control Theory", Springer Publishers, 2005.				
2. Ogatta, K., "N	lodern Control Engineering", Prentice Hall of India, 2002.				

PO CO	CO Statement	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	PO 7	PO 8	PO 9	PO1 0	PO1 1
CO1	Understand the concept of state variable representation of systems.	1	3	1	1	2	1	3	1	1	1	1
CO2	Evaluate linear and non-linear state equations.	1	1	3	3	1	2	3	1	1	2	1
CO3	Analyze the concepts of controllability and observability.	1	1	2	2	2	2	1	1	2	3	1
CO4	Apply Stability concept to nonlinear systems.	2	3	2	3	3	1	2	2	1	2	2
CO5	Understand the concepts of Pole placement and State feedback.	2	2	3	2	3	1	2	3	1	2	2

18PEE14 ARTIFICIAL INTELLIGENCE AND MACHINE LEARNI	NG L T P C 3 0 0 3
Course Objectives:	
1. To provide a strong foundation of fundamental concepts in Artificial Intelligen	ce.
2. To enable the student to apply these techniques in applications which inv	
and learning.	
 To enable Problem-solving through various searching techniques. To simulate numerous innate human skills such as automatic programming 	case based reasoning
neural networks, Fuzzy Logic, decision-making, expert systems, natural la recognition and speech recognition, etc.	
5. To apply AI techniques primarily for machine learning, vision, and robotics.	
Unit I INTRODUCTION TO AI AND PRODUCTION SYSTEMS Introduction to AI-Problem formulation, Problem Definition -Production systems,	9 + 0
strategies. Problem characteristics, Production system characteristics -Speci Problem solving methods - Problem graphs, Matching, Indexing and Heuristic fur first and Breath first, Constraints satisfaction - Related algorithms, Measure of p search algorithms.	alized production system- ctions -Hill Climbing-Depth
Unit II REPRESENTATION OF KNOWLEDGE	9 + 0
Game playing - Knowledge representation, Knowledge representation using Pre predicate calculus, Resolution, Use of predicate calculus, Knowledge representation of knowledge.	
Unit III KNOWLEDGE INFERENCE	9 + 0
Knowledge representation -Production based system, Frame based system. Infe Forward chaining, Rule value approach, Fuzzy reasoning - Certainty factors,	
Network-Dempster - Shafer theory.	
Unit IV PLANNING AND MACHINE LEARNING	9 + 0
Basic plan generation systems - Strips -Advanced plan generation systems – K str Why, Why not and how explanations. Learning- Machine learning, adaptive Learning	os -Strategic explanations -
Unit V EXPERT SYSTEMS	9 + 0
Expert systems - Architecture of expert systems, Roles of expert systems - Kn knowledge, Heuristics. Typical expert systems - MYCIN, DART, XOON, Expert systems	
	Total (L+T)= 45 Periods
Course Outcomes:	
Upon completion of this course, the students will be able to:	
CO1:Provide a basic exposition to the goals and methods of Artificial IntelligentCO2:Study the design of intelligent computational agents.	Ce.
CO3 : Acquire knowledge through learning can be used both for problem planning, natural language understanding, computer vision, automatic learning.	
CO4 : Apply innate human skills such as automatic programming, case - networks, Fuzzy Logic, decision-making, expert systems, natural lar recognition and speech recognition, etc.	
CO5 : Enhance their knowledge in their Research works in future.	
CO6 : Build new solutions in business in future.	
Text Books:	
1. Stuart Russell, Peter Norvig, "Artificial Intelligence: A Modern Approach Education / Prentice Hall of India, 2010.	", Third Edition, Pearson
2. Elaine Rich and Kevin Knight, "Artificial Intelligence", Third Edition, Tata McG	
3. Ethem Alpaydin, "Introduction to Machine Learning (Adaptive Computati series)", The MIT Press; Second edition, 2009.	
 Patrick H. Winston. "Artificial Intelligence", Third edition, Pearson Edition, 200 	б
Reference Books:	
1. Bratko I, "Prolog Programming for Artificial Intelligence", Addison-Wesley	I A CARA D D D D D D D D D D D D D D D D D D

	Fourth Edition, 2011.
2.	David L. Poole, Alan K. Mackworth, "Artificial Intelligence: Foundations of Computational Agents",
	Cambridge University Press, 2010.
3.	Dan W.Patterson, "Introduction to Artificial Intelligence and Expert Systems", PHI, 2006.
1	Nils I Nilsson "Artificial Intelligence: A new Synthesis" Harcourt Asia Pyt I td. 2000

4. Nils J. Nilsson, "Artificial Intelligence: A new Synthesis", Harcourt Asia Pvt. Ltd., 2000.

PO CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Provide a basic exposition to the goals and methods of Artificial Intelligence.	2	2	2	1	1	1	2	1	1	2	1
CO2	Study the design of intelligent computational agents.	3	1	1	2	2	1	1	1	2	2	1
CO3	Acquireknowledgethrough learning can beused both for problemsolving and for reasoningplanning,naturallanguageunderstanding,computervision,automaticprogrammingand machine learning.	1	1	1	2	1	1	2	2	2	2	2
CO4	Apply innate human skills such as automatic programming, case – based reasoning, neural networks, Fuzzy Logic, decision-making, expert systems, natural languahe processing, pattern recognition and speech recognition, etc.	1	2	2	3	3	1	1	2	1	1	1
CO5	Enhance their knowledge in their Research works in future.	1	1	1	1	1	2	2	1	2	1	1
CO6	Build new solutions in business in future.	1	1	1	2	1	1	1	2	3	3	3

	18PEE15	DISCRETE CONTROL SYSTEM		Т	P	С
			3	0	0	3
Cou	Irse Objectives:					
1.	To understand	the digital signal processing.				
2.	To study the d	esion of sampled data control systems in state space.				

3. To impart knowledge on digital control algorithms and stability study.

Unit I INTRODUCTION

Review of frequency and time response analysis and specifications of continuous time systems - need for controllers - continuous time compensations - continues time PI, PD, PID controllers, Realization of basic compensators: Lag, Lead and Lag-Lead compensation schemes - problems.

Unit II SIGNAL PROCESSING IN DIGITAL CONTROL

Need for digital control – Configuration of basic digital control scheme – Principles of signal conversion – Basic discrete-time signals – Time domain and frequency domain models for discrete-time systems - Aliasing – Reconstruction of analog signals – Practical aspects of the choice of sampling rate – Discretization based on bilinear transformation.

Unit III MODELING AND ANALYSIS OF SAMPLED DATA CONTROL SYSTEM

Differential equation description – Z-transform method of description– Z-transform analysis of sampled data control systems –Jury's stability test – Routh stability criterion on the r-plane – State variable concepts: First companion – Second companion – Jordan canonical models – Discrete state variable models – state description of sampled continuous time plants, Elementary principles.

Unit IV DESIGN OF DIGITAL CONTROL ALGORITHMS

Introduction – z-plane specifications of control system design –Digital lead , lag and lag-lead compensator design using frequency response plots - Digital lead lag compensator design using Root locus plots – z-plane synthesis – Digital controllers for deadbeat performance – Examples: Digital Controller Design for Buck Converter.

Unit V PRACTICAL ASPECTS OF DIGITAL CONTROL ALGORITHMS

Development and implementation of digital PID control algorithms – Tunable PID controllers - Digital temperature control system: Control algorithm – Digital position control system: Digital measurement of shaft position/speed, control algorithm – Stepping motors and their controls: Torque-speed curves, Interfacing of stepper motors to microprocessors, Design of fuzzy logic controllers, Fuzzy control of water heater.

Total (L+T)= 45 Periods

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Cou	rse	Outcomes:
Upo	n co	mpletion of this course, the students will be able to:
CO1	:	Get knowledge about digital control scheme.
CO2		Get knowledge about sampling techniques.
CO3		Design the various digital control algorithms.
CO4		Design the various types of digital controllers and compensators.
CO5		Get knowledge about applications of digital control.
Text	Bo	oks:
1.	М.	Gopal, "Digital Control and Static Variable Methods", Tata McGraw Hill, New Delhi, 2012, 4 th Edition.
2.		Nagrath & M.Gopal, "Control Systems Engineering", New Age International Publishers, New Delhi,
Ζ.	20	17,6 th Edition.
Refe	erer	ce Books:
1.	В.(C.Kuo, Digital Control Systems, Oxford University Press,2nd Edition,2007.
2.	K.	Ogata, Modern Control Engineering, Pearson Education, 2002.
3.	Ke	nneth J. Ayala, "The 8051 Microcontroller- Architecture, Programming and Applications", Penram
	Int	ernational, 2nd Edition, 1996.

PO CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Get knowledge about digital control scheme.	1	1	1	1	1	1	1	1	1	2	1
CO2	Get knowledge about sampling techniques.	1	1	1	1	1	1	1	1	1	2	1
CO3	Design the various digital control algorithms.	1	1	2	2	3	1	3	2	1	2	1
CO4	Design the various types of digital controllers and compensators.	1	3	3	3	3	1	3	3	1	2	1
CO5	Get knowledge about applications of digital control.	2	2	3	3	3	1	2	3	1	2	1

3 0 0 3 Course Objectives: 1. To provide exposure of advanced power electronic converters utilized by the industries and utilities Unit I MULTIPULSE CONVERTERS 9 + 0 Concept of multi-pulse converters, Configurations for twelve pulse, eighteen pulse and twenty four pulse converters, Applications 9 + 0 Concept of multi-pulse converters, Applications 9 + 0 Forward converter, Half bridge and full-bridge converters, SEPIC Converter; Interleaved boost converter, transformer-isolated topologies, continuous and discontinuous conduction modes of operation, ripple analysis Unit II HIGH POWER CONVERTERS 9 + 0 Forward converter, Half bridge and Flype and Flying Capacitor Type and suitable modulation strategies - Multi-level Inverters of Diode Clamped Type and Flying Capacitor Type and suitable modulation strategies - Multi-level Inverters of Cascade Type, Series Inverters. Analysis of Series Inverter. 9 + 0 Unit IV BIDIRECTIONAL CONVERTERS 9 + 0 Single Phase and three Phase bidirectional converters in rectifier mode, control of DC voltage - control of Input Current. Hysteresis control in Single Phase and three Phase inverter mode - Frequency control in hysteresis, constant switching frequency control methods. Unit V EMI AND FILTERING<	18PEE21	ADVANCED POWER ELECTRONIC CIRCUITS	L	Т	Ρ	С
1. To provide exposure of advanced power electronic converters utilized by the industries and utilities Unit I MULTIPULSE CONVERTERS 9 + 0 Concept of multi-pulse converters, Configurations for twelve pulse, eighteen pulse and twenty four pulse converters, Applications 9 + 0 Unit I PULSE-WIDTH-MODULATED DC-DC CONVERTERS 9 + 0 Forward converter, Half bridge and full-bridge converters, SEPIC Converter; Interleaved boost converter, transformer-isolated topologies, continuous and discontinuous conduction modes of operation, ripple analysis Unit II HIGH POWER CONVERTERS 9 + 0 Multi-Level Inverters of Diode Clamped Type and Flying Capacitor Type and suitable modulation strategies - Multi-level Inverters of Cascade Type, Series Inverters. Analysis of Series Inverters. Modified Series Inverter. Three Phase Series Inverter 9 + 0 Single Phase and three Phase bidirectional converters in rectifier mode, control of DC voltage - control of Input Current. Hysteresis control in Single Phase and three Phase inverter mode - Frequency control in hysteresis, Constant switching frequency control methods. 9 + 0 Unit V EMI AND FILTERING 9 + 0 Echniques to reduce Emissions. Shielding and Grounding. Power Circuit Layout for minimum EMI. EMI Filtering at Input and Output. Effect of EMI Filter on converter Control Dynamics <th></th> <th></th> <th>3</th> <th>0</th> <th>0</th> <th>3</th>			3	0	0	3
Unit I MULTIPULSE CONVERTERS 9 + 0 Concept of multi-pulse converters, Configurations for twelve pulse, eighteen pulse and twenty four pulse converters, Applications 9 + 0 Unit I PULSE-WIDTH-MODULATED DC-DC CONVERTERS 9 + 0 Forward converter, Half bridge and full-bridge converters , SEPIC Converter; Interleaved boost converter, transformer-isolated topologies, continuous and discontinuous conduction modes of operation, ripple analysis Unit II HIGH POWER CONVERTERS 9 + 0 Multi-Level Inverters of Diode Clamped Type and Flying Capacitor Type and suitable modulation strategies - Multi-level Inverters of Cascade Type, Series Inverters. Analysis of Series Inverters. Modified Series Inverter. Three Phase Series Inverter 9 + 0 Single Phase and three Phase bidirectional converters in rectifier mode, control of DC voltage - control of Input Current. Hysteresis control in Single Phase and three Phase inverter mode - Frequency control in hysteresis, Constant switching frequency control methods. 9 + 0 Unit V EMI AND FILTERING 9 + 0 Echniques to reduce Emissions. Shielding and Grounding. Power Circuit Layout for minimum EMI. EMI Filtering at Input and Output. Effect of EMI Filter on converter Control Dynamics Total (L+T)= 45 Periods Course Outcomes: Upon completion of this course, the students will	Course Objective	s:				
Concept of multi-pulse converters, Configurations for twelve pulse, eighteen pulse and twenty four pulse rectifiers, operation and waveform analysis, phase shifting transformer configurations for multi-pulse converters, Applications Unit II PULSE-WIDTH-MODULATED DC-DC CONVERTERS 9 + 0 Forward converter, Half bridge and full-bridge converters, SEPIC Converter; Interleaved boost converter, transformer-isolated topologies, continuous and discontinuous conduction modes of operation, ripple analysis 9 + 0 Unit II HIGH POWER CONVERTERS 9 + 0 Multi-Level Inverters of Diode Clamped Type and Flying Capacitor Type and suitable modulation strategies - Multi-level inverters of Cascade Type, Series Inverters. Analysis of Series Inverters. Modified Series Inverter. Three Phase Series Inverter 9 + 0 Unit IV BIDIRECTIONAL CONVERTERS 9 + 0 Single Phase and three Phase bidirectional converters in rectifier mode, control of DC voltage - control of Input Current. Hysteresis control in Single Phase and three Phase inverter mode - Frequency control in hysteresis, Constant switching frequency control methods. 9 + 0 Unit V EMI AND FILTERING 9 + 0 EMI Generation and Filtering in power converters - Conducted and Radiated Emission Mechanisms. Techniques to reduce Emissions. Shielding and Grounding. Power Circuit Layout for minimum EMI. EMI Filtering at Input and Output. Ef	1. To provide e	exposure of advanced power electronic converters utilized by the industries ar	nd u	tiliti	es	
Concept of multi-pulse converters, Configurations for twelve pulse, eighteen pulse and twenty four pulse rectifiers, operation and waveform analysis, phase shifting transformer configurations for multi-pulse converters, Applications Unit II PULSE-WIDTH-MODULATED DC-DC CONVERTERS 9 + 0 Forward converter, Half bridge and full-bridge converters, SEPIC Converter; Interleaved boost converter, transformer-isolated topologies, continuous and discontinuous conduction modes of operation, ripple analysis 9 + 0 Unit II HIGH POWER CONVERTERS 9 + 0 Multi-Level Inverters of Diode Clamped Type and Flying Capacitor Type and suitable modulation strategies - Multi-level inverters of Cascade Type, Series Inverters. Analysis of Series Inverters. Modified Series Inverter. Three Phase Series Inverter 9 + 0 Unit IV BIDIRECTIONAL CONVERTERS 9 + 0 Single Phase and three Phase bidirectional converters in rectifier mode, control of DC voltage - control of Input Current. Hysteresis control in Single Phase and three Phase inverter mode - Frequency control in hysteresis, Constant switching frequency control methods. 9 + 0 Unit V EMI AND FILTERING 9 + 0 EMI Generation and Filtering in power converters - Conducted and Radiated Emission Mechanisms. Techniques to reduce Emissions. Shielding and Grounding. Power Circuit Layout for minimum EMI. EMI Filtering at Input and Output. Ef					r	-
rectifiers, operation and waveform analysis, phase shifting transformer configurations for multi-pulse converters, Applications Unit II PULSE-WIDTH-MODULATED DC-DC CONVERTERS 9 + 0 Forward converter, Half bridge and full-bridge converters , SEPIC Converter; Interleaved boost converter, transformer-isolated topologies, continuous and discontinuous conduction modes of operation, ripple analysis 9 + 0 Unit II HIGH POWER CONVERTERS 9 + 0 Multi-Level Inverters of Diode Clamped Type and Flying Capacitor Type and suitable modulation strategies - Multi-level inverters of Cascade Type, Series Inverters. Analysis of Series Inverters. Modified Series Inverter. Three Phase Series Inverter 9 + 0 Single Phase and three Phase bidirectional converters in rectifier mode, control of DC voltage - control of Input Current. Hysteresis control in Single Phase and three Phase inverter mode - Frequency control in hysteresis, Constant switching frequency control methods. 9 + 0 Unit V EMI AND FILTERING 9 + 0 Event and Output. Effect of EMI Filter on converter Control Dynamics Total (L+T)= 45 Periods Course Outcomes: Upon completion of this course, the students will be able to: COC COU : Select appropriate phase shifting converter for a multi-pulse converter operation CO4 :				-	+	ŀ
Forward converter, Half bridge and full-bridge converters , SEPIC Converter; Interleaved boost converter, transformer-isolated topologies, continuous and discontinuous conduction modes of operation, ripple analysis Unit III HIGH POWER CONVERTERS 9 + 0 Multi-Level Inverters of Diode Clamped Type and Flying Capacitor Type and suitable modulation strategies - Multi-level Inverters of Cascade Type, Series Inverters. Analysis of Series Inverters. Modified Series Inverter. Three Phase Series Inverter 9 + 0 Unit IV BIDIRECTIONAL CONVERTERS 9 + 0 Single Phase and three Phase bidirectional converters in rectifier mode, control of DC voltage - control of Input Current. Hysteresis control in Single Phase and three Phase bidirectional converters - Conducted and Radiated Emission Mechanisms. Techniques to reduce Emissions. Shielding and Grounding. Power Circuit Layout for minimum EMI. EMI Filtering at Input and Output. Effect of EMI Filter on converter Control Dynamics 9 + 0 Course Outcomes: Upon completion of this course, the students will be able to: CO1 : Know the operating modes of new DC-DC voltage regulators CO2 : Select appropriate phase shifting converter for a multi-pulse converter operation CO3 : Design an inverter configuration for high power AC applications CO4 : Use of bidirectional converters with appropriate control methods Reference Books: . .	rectifiers, operation	on and waveform analysis, phase shifting transformer configurations f				
transformer-isolated topologies, continuous and discontinuous conduction modes of operation, ripple analysis Unit III HIGH POWER CONVERTERS 9 + 0 Multi-Level Inverters of Diode Clamped Type and Flying Capacitor Type and suitable modulation strategies - Multi-level inverters of Cascade Type, Series Inverters. Analysis of Series Inverters. Modified Series Inverter. 9 + 0 Unit IV BIDIRECTIONAL CONVERTERS 9 + 0 Single Phase and three Phase bidirectional converters in rectifier mode, control of DC voltage - control of Input Current. Hysteresis control in Single Phase and three Phase inverter mode - Frequency control in hysteresis, Constant switching frequency control methods. 9 + 0 Unit V EMI AND FILTERING 9 + 0 EMI Generation and Filtering in power converters - Conducted and Radiated Emission Mechanisms. Techniques to reduce Emissions. Shielding and Grounding. Power Circuit Layout for minimum EMI. EMI Filtering at Input and Output. Effect of EMI Filter on converter Control Dynamics Total (L+T)= 45 Periods CO1 I Know the operating modes of new DC-DC voltage regulators CO2 I CO2 I Select appropriate phase shifting converter for a multi-pulse converter operation CO3 I CO3 I: Design an inverter configuration for high power AC applications CO4 I Use of	Unit II PULSE	-WIDTH-MODULATED DC-DC CONVERTERS		9	+	0
Multi-Level Inverters of Diode Clamped Type and Flying Capacitor Type and suitable modulation strategies - Multi-level Inverters of Cascade Type, Series Inverters. Analysis of Series Inverters. Modified Series Inverter. Three Phase Series Inverter Unit IV BIDIRECTIONAL CONVERTERS 9 + 0 Single Phase and three Phase bidirectional converters in rectifier mode, control of DC voltage - control of Input Current. Hysteresis control in Single Phase and three Phase inverter mode - Frequency control in hysteresis, Constant switching frequency control methods. Unit V EMI AND FILTERING 9 + 0 EMI Generation and Filtering in power converters - Conducted and Radiated Emission Mechanisms. Techniques to reduce Emissions. Shielding and Grounding. Power Circuit Layout for minimum EMI. EMI Filtering at Input and Output. Effect of EMI Filter on converter Control Dynamics Course Outcomes: Upon completion of this course, the students will be able to: COC CO2 Select appropriate phase shifting converter for a multi-pulse converter operation CO3 CO3 Design an inverter configuration for high power AC applications CO4 CO4 Use of bidirectional converters with optimal component selection CO5 CO5 Analyze hard-switched converters and AC Drives", John Willey & sons, Inc., 2006. 2 N. Mohan, Power Electronics: A First Course, John Wiley & Sons, 2012.						
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2. N. Mohan, Power Electronics: A First Course, John Wiley & Sons, 2012.						
3. B. K Bose "Modern Power Electronics and AC Drives" Pearson Education, 2007.						
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PO CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO 9	PO 10	PO 11
CO1	Know the operating modes of new DC- DC voltage regulators	2		1					2			1
CO2	Select appropriate phase shifting converter for a multi- pulse converter operation	1				2	1					
CO3	Design an inverter configuration for high power AC applications		1		2							2
CO4	Use of bidirectional converters with optimal component selection			3	1							2
CO5	Analyze hard- switched converters with appropriate control methods		3						1			

	2 DIGITAL SIGNAL PROCESSING FOR POWER ELECTRONICS	3	0	0	С 3
Course Ob	jectives:				
	derstand the need for filter, its design				
2. To lea	arn selection of sensor and transducers to power applications and choice of conditi	oning			
	ow different sampling techniques in AD converters				
	arn Digital filters and its design				
5. To ur	derstand and learn different parameter measurements				
	NTRODUCTION TO DIGITAL SIGNAL PROCESSING		9	+	0
	ters – Quantization Errors – Sampling – Sample and Hold Circuit – Sampling The g Filter and its Design - Total Harmonic Distortion	orem -	- Ali	asin	g -
Unit II I	NSTRUMENTATION AND CONTROL INTERFACES		9	+	0
	sition – Sensors and Transducers – Electronic Interface – Signal Conditioning (perational Amplifier – Galvanic isolation	Circuits	5 — (Circ	uits
Unit III	ANALOG SIGNAL DISCRETIZATION		9	+	0
	Sequential – Simultaneous – Errors in Sampling – A/D Converters suitable for Pow	er Elec	-	ics	Ŭ
				ſ	r
Unit IV	SIGNAL FILTRATION AND SEPARATION		9	+	0
Implementa	nd Integral Value calculation - Digital Filters – Moving Average Filter - FIR – IIR – tion	Desigi	n of	filte	rs
Unit V	PARAMETER MEASUREMENTS		9	+	0
Power Fact	PARAMETER MEASUREMENTS – Measurement of Voltage and Current – Average – True RMS – Power – Avera or – Reverse Power Flow – Energy – Fundamental Component identification – Component identification		Арр	arer	nt –
Algorithms Power Fact	 Measurement of Voltage and Current – Average – True RMS – Power – Average – Reverse Power Flow – Energy – Fundamental Component identification – Component identification 		App valu	arer atio	nt - n -
Algorithms Power Fact	 Measurement of Voltage and Current – Average – True RMS – Power – Average – Reverse Power Flow – Energy – Fundamental Component identification – Component identification 	THD e	App valu	arer atio	nt –
Algorithms Power Fact Sequence (Course Ou	 Measurement of Voltage and Current – Average – True RMS – Power – Average – Reverse Power Flow – Energy – Fundamental Component identification – Component identification 	THD e	App valu	arer atio	n –
Algorithms Power Fact Sequence (Course Ou	 Measurement of Voltage and Current – Average – True RMS – Power – Average – Reverse Power Flow – Energy – Fundamental Component identification – Component identification Total (total 	THD e	App valu	arer atio	nt –
Algorithms Power Fact Sequence (Course Ou Upon comp CO1 : CO2 :	Measurement of Voltage and Current – Average – True RMS – Power – Averation – Reverse Power Flow – Energy – Fundamental Component identification – Component identification Total (teomes: letion of this course, the students will be able to: Understand errors in quantization and select appropriate anti-aliasing filter Select and Design the suitable circuit for data acquisition	THD e	App valu	arer atio	nt - n -
Algorithms Power Fact Sequence () Course Ou Upon comp CO1 : CO2 : CO3 :	 Measurement of Voltage and Current – Average – True RMS – Power – Average – Reverse Power Flow – Energy – Fundamental Component identification – Component identification Total (total component identification – Component identification Total (total component identification – Component identification – Component identification Total (total component identification – Component identification – Component identification Total (total component identification – Component identification – Component identification Total (total component identification – Component identification Indentification and select appropriate anti-aliasing filter Select and Design the suitable circuit for data acquisition Select the correct AD converter and sampling technique 	THD e	App valu	arer atio	nt - n -
Algorithms Power Fact Sequence C Course Ou Upon comp CO1 : CO2 : CO3 : CO3 :	 Measurement of Voltage and Current – Average – True RMS – Power – Average – Reverse Power Flow – Energy – Fundamental Component identification – Component identification Total (tcomes: Identification and select appropriate anti-aliasing filter Select and Design the suitable circuit for data acquisition Select the correct AD converter and sampling technique Choose and design appropriate software filter 	THD e (L+T)=	App valu 45 P	arer atio	nt - n -
Algorithms Power Fact Sequence () Course Ou Upon comp CO1 : CO2 : CO3 :	 Measurement of Voltage and Current – Average – True RMS – Power – Average – Reverse Power Flow – Energy – Fundamental Component identification – Component identification Total (tcomes: Identification and select appropriate anti-aliasing filter Select and Design the suitable circuit for data acquisition Select the correct AD converter and sampling technique Choose and design appropriate software filter Understand and implement measurement and processing for control application and 	THD e (L+T)=	App valu 45 P	arer atio	nt - n -
Algorithms Power Fact Sequence (Course Ou Upon comp CO1 : CO2 : CO3 : CO3 : CO4 : CO5 :	 Measurement of Voltage and Current – Average – True RMS – Power – Average – Reverse Power Flow – Energy – Fundamental Component identification – Component identification Total (toomponent identification – Component identification Total (total (total (toomes: 	THD e (L+T)=	App valu 45 P	arer atio	nt - n -
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Algorithms Power Fact Sequence (Course Ou Upon comp CO1 : CO2 : CO3 : CO4 : CO5 : Reference 1. Krzysz 2017	 Measurement of Voltage and Current – Average – True RMS – Power – Average – Reverse Power Flow – Energy – Fundamental Component identification – Component identification Total (tcomes: Idetion of this course, the students will be able to: Understand errors in quantization and select appropriate anti-aliasing filter Select and Design the suitable circuit for data acquisition Select the correct AD converter and sampling technique Choose and design appropriate software filter Understand and implement measurement and processing for control application alimplement algorithms for parameter measurement Books: tof Sozański, "Digital Signal Processing in Power Electronics ControlCircuits", 2nd 	THD e (L+T)=/	45 P	arer atio Peric	n –
Algorithms Power Fact Sequence C Course Ou Upon comp CO1 : CO2 : CO3 : CO3 : CO4 : CO5 : Reference 1. Krzysz 2017 2. Opper Hall, E	 Measurement of Voltage and Current – Average – True RMS – Power – Average – Reverse Power Flow – Energy – Fundamental Component identification – Component identification Total (Total (tcomes: Ideition of this course, the students will be able to: Understand errors in quantization and select appropriate anti-aliasing filter Select and Design the suitable circuit for data acquisition Select the correct AD converter and sampling technique Choose and design appropriate software filter Understand and implement measurement and processing for control application and implement algorithms for parameter measurement Books: tof Sozański, "Digital Signal Processing in Power Electronics ControlCircuits", 2 nd heim, A.V., Schafer, R.W. and Buck, J.R., Discrete-Time Signals Processing, 2 nd	THD e (L+T)=/ nd deve Editior	45 P	arer atio	n - ods
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PO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO	PO9	PO1	PO1
со									8		0	1
CO1	Understand errors in quantization and select appropriate anti-aliasing filter	1	1	1	1	2						1
CO2	Select and Design the suitable circuit for data acquisition	1	1	1	1	1			1			1
CO3	Select the correct AD converter and sampling technique	1	1	2	2	1			1			1
CO4	Choose and design appropriate software filter	1	2	1	1	1			1			1
CO5	Understand and implement measurement and processing for control application and develop, implement algorithms for parameter measurement	1	1	1	1	1			1			1

18PEE	23	DYNAMICS OF POWER CONVERTERS	LT	Ρ	(
			3 0	0	
Course Ol	bjective	s:			
1. To p	orovide k	nowledge in dynamic behavior and analyses of the DC-DC converters and t	nree pł	ase	ari
		onverters with source and load interactions.	p.		9.
Unit I 🛛 🛛 🛛	NTROD	JCTION TO DYNAMIC ANALYSIS	9	+	
		eralized Dynamic Representations for Voltage fed and Current fed DC-			
		nteractions- Generalized Dynamic Representations for three-phase voltage-			
		e-phase voltage fed and current-fed inverters-closed loop dynamics- Genera	lized C	asca	de
Control Sc	hemes	Generalized Impedance-Based Stability			
Unit II		IC MODELING AND CONTROL OF VOLTAGE FED DC-DC CONVERTER		<u> </u>	
		ntrol- DOT-controlled converter at open loop with a PWM modulator; Gener		+) Jin
		nic model of Buck-converter -power stages- topological sub circuit structur			
		zed state space model; Peak Current Mode Control principles- Development			
		State Spaces and Transfer Functions		aty i	au
Unit III	DYNA	MIC MODELING AND CONTROL OF CURRENT FED DC-DC CONVERTER	S 9	+	(
Duality Tra	ansform	ation Basics- Duality-Transformed Converters- Voltage-fed and Current-f	ed buc	k, b	00
		nic equivalent circuits of current fed current-output converter and current-fed			
		c model of current fed Buck, Boost Converters; Duty-Ratio Constraints under	r PCM	Con	tro
PCM-contr	rolled cu	rrent-fed buck, boost power-stage converter			
					-
Unit IV		AICS OF THREE PHASE INVERTERS	9	+	
Dynamic N	Nodel of	Voltage-Fed Inverter- Equivalent switching circuit and average model - Li	nearize	d St	ate
Dynamic N Space and	Model of d Open-	Voltage-Fed Inverter- Equivalent switching circuit and average model - Li Loop Dynamics; Dynamic Model of Current-Fed Inverter- Equivalent switc	nearize	d St cuit	ate an
Dynamic N Space and average m	Model of d Open- lodel- Li	Voltage-Fed Inverter- Equivalent switching circuit and average model - Li Loop Dynamics; Dynamic Model of Current-Fed Inverter- Equivalent switc nearized Model and Open-Loop Dynamics Control Design of Grid-Connected	nearize ning ci ed Thre	ed St cuit e-Ph	ate an
Dynamic N Space and average m Inverters- S	Model of d Open- lodel- Li Synchro	Voltage-Fed Inverter- Equivalent switching circuit and average model - Li Loop Dynamics; Dynamic Model of Current-Fed Inverter- Equivalent switc	nearize ning ci ed Thre	ed St cuit e-Ph	ate an
Dynamic N Space and average m	Model of d Open- lodel- Li Synchro	Voltage-Fed Inverter- Equivalent switching circuit and average model - Li Loop Dynamics; Dynamic Model of Current-Fed Inverter- Equivalent switc nearized Model and Open-Loop Dynamics Control Design of Grid-Connected	nearize ning ci ed Thre	ed St cuit e-Ph	ate an
Dynamic N Space and average m Inverters- S of SRF-PL	Model of d Open- nodel- Li Synchro L	Voltage-Fed Inverter- Equivalent switching circuit and average model - Li Loop Dynamics; Dynamic Model of Current-Fed Inverter- Equivalent switc nearized Model and Open-Loop Dynamics Control Design of Grid-Connected	nearize ning ci ed Thre Contro	ed St cuit e-Ph	ate an ias sig
Dynamic M Space and average m Inverters- S of SRF-PL Unit V	Model of d Open- nodel- Li Synchro L DYNAM ASSES	Voltage-Fed Inverter- Equivalent switching circuit and average model - Li Loop Dynamics; Dynamic Model of Current-Fed Inverter- Equivalent switc nearized Model and Open-Loop Dynamics Control Design of Grid-Connecte nous Reference Frame Phase Locked Loop- Linearized Model of SRF-PLL- IC MODELING OF THREE PHASE ACTIVE RECTIFIERS AND STABILITY SMENT	nearize ning ci ed Thre Contro	d St cuit e-Ph I De	ate an ias sig
Dynamic M Space and average m Inverters- S of SRF-PL Unit V	Model of d Open- nodel- Li Synchro L DYNAM ASSES use activ	Voltage-Fed Inverter- Equivalent switching circuit and average model - Li Loop Dynamics; Dynamic Model of Current-Fed Inverter- Equivalent switc nearized Model and Open-Loop Dynamics Control Design of Grid-Connecte nous Reference Frame Phase Locked Loop- Linearized Model of SRF-PLL- IC MODELING OF THREE PHASE ACTIVE RECTIFIERS AND STABILITY SMENT e rectifier -Power stage and Equivalent switch matrix- Equivalent circuit mode	nearize ning ci ed Thre Contro 9 lel- Sta	d St cuit e-Ph I De	ate an ias sig
Dynamic M Space and average m Inverters- S of SRF-PL Unit V	Model of d Open- nodel- Li Synchro L DYNAM ASSES use activ	Voltage-Fed Inverter- Equivalent switching circuit and average model - Li Loop Dynamics; Dynamic Model of Current-Fed Inverter- Equivalent switc nearized Model and Open-Loop Dynamics Control Design of Grid-Connecte nous Reference Frame Phase Locked Loop- Linearized Model of SRF-PLL- IC MODELING OF THREE PHASE ACTIVE RECTIFIERS AND STABILITY SMENT	nearize ning ci ed Thre Contro 9 lel- Sta	d St cuit e-Ph I De	ate an as sig
Dynamic M Space and average m Inverters- S of SRF-PL Unit V	Model of d Open- nodel- Li Synchro L DYNAM ASSES use activ	Voltage-Fed Inverter- Equivalent switching circuit and average model - Li Loop Dynamics; Dynamic Model of Current-Fed Inverter- Equivalent switc nearized Model and Open-Loop Dynamics Control Design of Grid-Connecte nous Reference Frame Phase Locked Loop- Linearized Model of SRF-PLL- IC MODELING OF THREE PHASE ACTIVE RECTIFIERS AND STABILITY SMENT e rectifier -Power stage and Equivalent switch matrix- Equivalent circuit mod active rectifier using transfer matrices- Open-Loop and closed loop control s	nearize hing ci ed Thre Contro 9 el- Sta cheme	ed St cuit e-Ph l De te sp	
Dynamic M Space and average m Inverters- S of SRF-PL Unit V	Model of d Open- nodel- Li Synchro L DYNAM ASSES ise activ ntrol of a	Voltage-Fed Inverter- Equivalent switching circuit and average model - Li Loop Dynamics; Dynamic Model of Current-Fed Inverter- Equivalent switc nearized Model and Open-Loop Dynamics Control Design of Grid-Connecte nous Reference Frame Phase Locked Loop- Linearized Model of SRF-PLL- IC MODELING OF THREE PHASE ACTIVE RECTIFIERS AND STABILITY SMENT e rectifier -Power stage and Equivalent switch matrix- Equivalent circuit mod active rectifier using transfer matrices- Open-Loop and closed loop control s Total (L+	nearize hing ci ed Thre Contro 9 el- Sta cheme	ed St cuit e-Ph l De te sp	
Dynamic N Space and average m Inverters- S of SRF-PL Unit V	Model of d Open- nodel- Li Synchro L DYNAM ASSES ise activ ntrol of a utcome	Voltage-Fed Inverter- Equivalent switching circuit and average model - Li Loop Dynamics; Dynamic Model of Current-Fed Inverter- Equivalent switc nearized Model and Open-Loop Dynamics Control Design of Grid-Connecte nous Reference Frame Phase Locked Loop- Linearized Model of SRF-PLL- IC MODELING OF THREE PHASE ACTIVE RECTIFIERS AND STABILITY SMENT e rectifier -Power stage and Equivalent switch matrix- Equivalent circuit mod active rectifier using transfer matrices- Open-Loop and closed loop control s Total (L+ s:	nearize hing ci ed Thre Contro 9 el- Sta cheme	ed St cuit e-Ph l De te sp	
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\setminus	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO	PO
PQ											10	11
со												
CO1	Know the dynamic representations of power converters	2		3			1	1				
CO2	Make a dynamic model of DC-DC converter	1			2				2			2
CO3	Select appropriate control scheme for DC-DC converter with its dynamic model		2			3			1			2
CO4	Develop state space model for three phase converters			1		1						
CO5	Design a suitable controller for three phase converters	1			2						1	

18	BPEI	E24	М	DULAT	ION	CONT	ROL	. FOR	r pov	VER C	ONV	ERTER	S	L	. T	P	C 3
Cours		bjectives												3	6 0	0	3
		•															
			Necessit			nce of	PWN	M tech	chniqu	es							
2.	Imp	ementation	on of PWM	controlle	ers												
Unit I		INTROD													9		0
	uatio	-	onverters,	Madulati	on of	one in	vorto	ornho		a Ma	dulati	n of oil			-	+	U
phase			Silveners,	wodulati		one in	iverte	er præ	lase le	eg, ivio	uulatio	on or si	ngie pr	ase,	/51 ai	10.5	
Unit II		MODUL	ATION ST	RATEGI	ES										9	+	0
Zero s	pac	e vector p	lacement r	nodulatio	on str	ategies	s, Los	sses-	-Disco	ontinuo	ous m	odulatio	on, Mo	dulatio	on of (CSI.	
Unit II	1	OVER I	IODULAT	ION											9	+	0
Over r	nod		converters		nmeı	modula	ation s	strate	teaies.								-
Unit I																1	
OHIT IN		IMPLEN	ENTATIO	N OF MC	DDUL			ONTR	ROLLE	R					9	+	0
			ENTATIO								lation	control	ler		9	+	0
											lation	control	ler		9	+	0
	widt										lation	control	ler		9	+	0
Pulse Unit V Contin	widt ' iuing	h modula PWM develop	ion for mu ments in r	ltilevel in	verte	ers, Imp	oleme	entatio	tion of	modu				Effect	9	+	0
Pulse Unit V Contin	widt ' iuing	h modula PWM	ion for mu ments in r	ltilevel in	verte	ers, Imp	oleme	entatio	tion of	modu			lance,		9 of m	+ hinim	0
Pulse Unit V Contin pulse	widt v iuing widt	h modula PWM develop h and dea	ion for mu ments in r d time	ltilevel in	verte	ers, Imp	oleme	entatio	tion of	modu					9 of m	+ hinim	0
Pulse Unit V Contin pulse	widt uing widt	h modula PWM develop h and dea utcomes	ion for mu ments in r d time	itilevel in	verte on as	rs, Imp	oleme	entatio PWM,	ion of	modu			lance,		9 of m	+ hinim	0
Pulse Unit V Contin pulse Cours Upon	widt uing widt	h modula PWM g develop h and dea utcomes pletion of	ion for mu ments in r d time this course	tilevel in nodulatic	verte on as	rs, Imp rando s will be	oleme om P\ e able	entatio PWM, le to:	, PWN	modu Λ for ν	voltag		lance,		9 of m	+ hinim	0
Pulse Unit V Contin pulse Cours Upon CO1	widt uing widt	h modula PWM develop n and dea utcomes pletion of <i>Remem</i>	ion for mu ments in r d time this course per the bas	nodulatic	verte on as idents	rs, Imp rando s will be f powe	om P\ e able r elec	entatio PWM, le to: ectroni	, PWN	modu Λ for ν	voltag		lance,		9 of m	+ hinim	0
Pulse Unit V Contin pulse Cours Upon CO1 CO2	widt uing widt	h modula PWM develop n and dea utcomes pletion of <i>Remem</i> Underst	ion for mu ments in r d time this course per the bas and and ev	tilevel in nodulatic e, the stu ic conce aluate th	verte on as dents pts of ne mo	rs, Imp rando s will be f power odulatio	om P\ om P\ e able r elec on stra	entatio PWM, le to: ectroni rategi	, PWN	M for w	voltag		lance,		9 of m	+ hinim	0
Pulse Unit V Contin pulse Upon CO1 CO2 CO3	widt uing widt	h modula PWM develop n and dea utcomes pletion of <i>Remem</i> Underst Underst	ion for mu ments in r d time this course per the bas and and ev and the cor	tilevel in nodulatio e, the stu ic conce aluate th ncepts of	verte on as idents pts on f over	rs, Imp rando s will be f powe odulatio r modul	e able om P\ e able on stra lation	entatio PWM, le to: ctroni rategi n of co	, PWN	modu A for v nverter	voltag		lance,		9 of m	+ hinim	0
Pulse Unit V Contin pulse Upon CO1 CO2 CO3 CO4	widt uing widt	h modula PWM develop n and dea utcomes pletion of Remem Underst Underst Apply th	ion for mu ments in r d time this course ber the bas and and ev and the con e concept of	tilevel in nodulation , the stu ic conce aluate the ncepts of pof pulse	verte on as dents pts on f over width	rs, Imp rando s will be f power odulatio r modul modul	e able er electon stra lation	entatio PWM, le to: ectroni rategio n of co n for in	ion of , PWN nic con gies. conver inverte	M for M	voltag	e unba	lance, Total	(L+T)	9 of m 45	+ ninim	0 1 0 0 0 0 0 0
Pulse Unit V Contin pulse Upon CO1 CO2 CO3 CO3 CO4 CO5	widt	h modula PWM develop n and dea utcomes pletion of <i>Remem</i> <i>Underst</i> <i>Underst</i> <i>Apply th</i> <i>Evaluate</i>	ion for mu ments in r d time this course per the bas and and ev and the cor	tilevel in nodulation , the stu ic conce aluate the ncepts of pof pulse	verte on as dents pts on f over width	rs, Imp rando s will be f power odulatio r modul modul	e able er electon stra lation	entatio PWM, le to: ectroni rategio n of co n for in	ion of , PWN nic con gies. conver inverte	M for M	voltag	e unba	lance, Total	(L+T)	9 of m 45	+ ninim	0 1 0 0 0 0 0 0
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Pulse Unit V Contin pulse Upon CO1 CO2 CO3 CO4 CO5 Reference 1. [widt uing widt com : : : : : : : : : : : : : : : : : : :	h modula PWM develop h and dea utcomes pletion of <i>Remem</i> <i>Underst</i> <i>Underst</i> <i>Underst</i> <i>Apply th</i> <i>Evaluate</i> Books : rahame H	ion for mu ments in r d time this course our the bas and and ev and the cor e concept of the praction	tilevel in nodulatic e, the stu ic conce aluate th ncepts of pof pulse ces and omas A.	verte on as odents opts of ne mo f over width sugge	rs, Imp rando s will be f power odulatio r modul est suit "Pulse	e able r elector lation table	entatio PWM, le to: cctroni rategi n of co n for in e meas	ion of , PWN nic con gies. conver inverte asures	modu A for v nverter rters. ers. for co	voltag s.	e unba	lance, Total	(L+T)	9 of m = 45	+ ninim	0 1 0 0 0 0 0 0
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PO CO	CO Statement	PO1	PO 2	PO 3	PO4	PO 5	PO 6	PO 7	PO 8	PO 9	PO10	PO1 1
CO1	Remember the basic concepts of power electronic converters.	3	1	1	1	1		1	1	1	1	1
CO2	Understand and evaluate the modulation strategies.	2	1	1	3	1		1	1	1	1	1
CO3	Understand the concepts of over modulation of converters.	2	1	1	3	1		1	1	1	1	1
CO4	Apply the concept of pulse width modulation for inverters.	3	1	1	1	1		1	1	1	1	1
CO5	Evaluate the practices and suggest suitable measures for continuous developments in modulation.	2	1	1	1	1	1	3	1	1	1	1

18PEE25

DESIGN OF POWER CONVERTERS

L T P C 3 0 0 3

Course Objectives:

1. To know about the design concepts and flow.

2. To implements the device and circuit concepts for applications

Unit I DESIGN OF UNCONTROLLED RECTIFIERS

Selection of Rectifier topology – Pulse number – Power output - Selection of Diode – Voltage and Current Ratings – Selection of DC Filter – Design and Selection of Inductor and Capacitor with practical considerations

Unit II DESIGN OF CONTROLLED RECTIFIERS

Selection of Rectifier topology - Pulse number – Power output – Reactive Power Requirements - Selection of SCR – Voltage and Current Ratings - Selection of DC Filter – Design and Selection of Inductor and Capacitor – Triggering Sequence and Sequence control for improved power factor operation.

Unit III DESIGN OF SWITCH MODE INVERTERS

Selection of inverter topology – Power output – Harmonics – Reactive Power Requirements - Selection of Power Devices – Voltage and Current Ratings - Selection of output Filter – Design and Selection of Inductor and Capacitor – Different control strategy for various requirements.

Unit IV DESIGN OF SWITCH MODE DC-DC CONVERTERS

Selection of converter topology – Power output – Performance parameters - Selection of Power Devices – Voltage and Current Ratings - Selection of Filter – Design and Selection of Inductor, Capacitor and ferrite transformers. Control strategies for various requirements.

Unit V DRIVERS, PROTECTION OF DEVICES AND CONVERTERS

Driver requirements – Design of Drivers - Snubber – Polarized and Non-Polarized – Voltage Clamp-Thermal Resistances – Modes of Power dissipation – Heat sinking Design – Current Protection – Introduction to EMI

Total (L+T)= 45 Periods

Course Outcomes:

Upon completion of this course, the students will be able to:

C01		:	Understand design concepts and flow
CO2	2	:	Select the appropriate circuit topology for applications
CO3	~	:	Select the appropriate power devices
C04	!	:	Select and design the appropriate circuit to meet the design metrics
CO5		:	Select the circuit configuration for electrical protection and scheme for thermal protection and derive
			methodology for selection of appropriate circuit for applications.
Refe	ere	nc	e Books:
1.	Μ	uh	ammad H. Rashid - Power Electronics Devices, Circuits, and Applications 4 Edition, Pearson 2014.
2.	Ba	arr	y W. Williams - Principles and Elements of Power Electronics – Devices, Drivers, Applications and
	Pa	as	sive Components, ISBN 978-0-9553384-0-3.

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PO	CO Statement	PO1	PO 2	PO 3	PO4	PO 5	PO 6	PO 7	PO 8	PO 9	PO10	PO1 1
CO1	Understand design concepts and flow	1	1	1	1	1		1	1	1	1	1
CO2	Select the appropriate circuit topology for applications	1	1	1	1	1		1	1	1	1	1
CO3	Select the appropriate power devices	1	1	1	1	1		1	1	1	1	1
CO4	Select and design the appropriate circuit to meet the design metrics	1	1	1	1	1		1	1	1	1	1
CO5	Select the circuit configuration for electrical protection and scheme for thermal protection and derive methodology for selection of appropriate circuit for applications.	1	1	1	1	1		1	1	1	1	1

1	8PEE31	ADVANCED POWER QUALITY	LT	r	С
			3 0	0	3
Cours	se Objectives	:			
1.	To understand	d the various power quality issues.			
		nd the concept of power and power factor in single phase and three p	hase :	svste	ms
	supplying nor			-,	
		d the conventional compensation techniques used for power factor corre	ection a	ind la	bad
	voltage regula	ation.			
		d the active compensation techniques used for power factor correction and	load ba	lanci	ng.
5.	To understan	d the active compensation techniques used for load voltage regulation.			
11				1	•
Unit I			9	+	0
		acterisation of Electric Power Quality: Transients, short duration and long d			
		imbalance, waveform distortion, Voltage fluctuations, Power frequency va – power quality problems: poor load power factor, Non linear and unbalar			
		hing in load voltage, Disturbance in supply voltage – Power quality standard		aus,	
011001			.0.		
Unit I		IS OF SINGLE PHASE AND THREE PHASE SYSTEM	9	+	0
		ts: single phase sinusoidal voltage source supplying nonlinear loads - sir	ngle ph	ase i	or
		ource supplying nonlinear loads,			
		: three phase sinusoidal balanced system - instantaneous real and reac			
		ts- symmetrical components- three phase non-sinusoidal balanced system	m- unb	alan	cec
		three phase system.	frame la	بم رام م	
		rom commercial loads: SMPS-fluorescent lighting-ASD, Harmonic sources power converter- arcing devices, saturable devices.	from in	lausi	na
iuaus.	tillee-pliase p				
Unit I		IENTAL THEORY OF LOAD COMPENSATION	9	+	-
					U
			-	<u> </u>	U
Princi	ple of load cor	npensation – some practical aspects of compensator used as voltage regul	ator-		
Princi Phase	ple of load cor balancing a	npensation – some practical aspects of compensator used as voltage regul and power factor correction of unbalanced load- a generalized appr	ator- oach f	or lo	bad
Princi Phase	ple of load cor balancing a	npensation – some practical aspects of compensator used as voltage regul	ator- oach f	or lo	bad
Princi Phase	ple of load cor balancing a	npensation – some practical aspects of compensator used as voltage regul and power factor correction of unbalanced load- a generalized appr	ator- oach f	or lo	bad
Princij Phase compe	ple of load cor balancing a ensation using	npensation – some practical aspects of compensator used as voltage regul and power factor correction of unbalanced load- a generalized appr g symmetrical components, generating reference currents using instantaneo	ator- oach f us PQ f	or lo	pad y.
Princip Phase compe	ple of load cor balancing a ensation using V REALIS	npensation – some practical aspects of compensator used as voltage regul and power factor correction of unbalanced load- a generalized appr symmetrical components, generating reference currents using instantaneo ATION AND CONTROL OF DSTATCOM	ator- roach f us PQ f	or lo heor	oad y. 0
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Ref	Reference Books:									
1.	A. J. Arrillaga, "Power System Harmonics", John Wiley & Sons, 2 nd Edition, 2003.									
2	G.T.Heydt, "Electric Power Quality", McGraw-Hill Professional, 2007.									
3	Math H. Bollen, "Understanding Power Quality Problems", IEEE Press, 2000									

	CO Statement	PO1	PO	PO	PO4	PO	PO	PO	PO	PO	PO1	PO1
	CO Statement	PUT			P04	-						_
ΡQ			2	3		5	6	7	8	9	0	1
со												
CO1	Understand the various power quality issues.	2	1	3	3	1	1				1	1
CO2	Analyze the single and three-phase circuits under non-sinusoidal and unbalanced load conditions	2	3	2	1	1	1				1	1
CO3	Understand the conventional load compensation theories	2	3	2	3	2	1	1	1		1	1
CO4	Realize of DSTATCOM	2	3	2	2	2	2	1	1		2	1
CO5	Gain knowledge on series compensation using DVR	2	3	2	2	2	2	1	1		2	1
CO6	Understand the operation of UPQC	2	3	2	2	2	2	1	1		2	1

18P	PEE32	HARMONICS AND FILTERS FOR POWER ELECTRONIC CIRCUITS	L	Т	Ρ	С
			3	0	0	3
Course (
	Objectives:	knowledge on the fundamentale of hermonice				
<u>1.</u> 2.		knowledge on the fundamentals of harmonics				
		stand the principle of operation of passive power filter				
3.		stand the principle of operation of shunt active power filter				
<u>4.</u> 5.		stand the principle of operation of series active power filter				
5.	To under	stand the principle of operation of hybrid active power filter				
Unit I	FUND	AMENTALS OF HARMONICS		9	+	0
harmonic harmonic procedure	s – Factors s: Harmonio	harmonic generation – Sources of harmonics: commercial and industrial s influencing - development of harmonic standards – General harmonic e evaluations on the utility system, Harmonic evaluation for end-user facilities pols for harmonic assessment: Fourier series, Fourier Transform, DFT, FFT, rm.	indic – Ha	es – armo	App nic st	liec udy
	DAC					•
Unit II		SIVE POWER FILTER , series – circuit configuration ,principle of operation – Analysis and desig		9	+	0
		ion – mitigation of resonance problem of passive filters with the power supply				
Unit III	SHU	INT ACTIVE POWER FILTER		9	+	0
		configuration ,principle of operation and control, Analysis and design, mo		-	mula	-
		umerical problems		0		
Unit IV	SER	IES ACTIVE POWER FILTER		9	+	0
Classifica	ation, circuit	IES ACTIVE POWER FILTER configuration ,principle of operation and control, Analysis and design, mo umerical problems		-	-	-
Classifica and perfo	ation, circuit ormance - n	configuration ,principle of operation and control, Analysis and design, mo umerical problems		-	-	-
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Classifica and perfo Unit V Classifica and perfo Course C	ation, circuit prmance - n HYBI ation, circuit prmance - n Dutcomes:	configuration ,principle of operation and control, Analysis and design, mo umerical problems RID ACTIVE POWER FILTER configuration ,principle of operation and control, Analysis and design, mo umerical problems	odelli	ng si 9 ng, si	mula	tion 0
Classifica and perfo Unit V Classifica and perfo Course C	Ation, circuit prmance - n HYBI Ation, circuit prmance - n Dutcomes: d of the cou	configuration ,principle of operation and control, Analysis and design, mo umerical problems RID ACTIVE POWER FILTER configuration ,principle of operation and control, Analysis and design, mo umerical problems Total (I	odelli	ng si 9 ng, si	mula	tion 0 tion
Classifica and perfo Unit V Classifica and perfo Course C At the en CO1	Ation, circuit prmance - n HYBI Ation, circuit prmance - nu Dutcomes: d of the cou i Unde	configuration ,principle of operation and control, Analysis and design, mo umerical problems RID ACTIVE POWER FILTER configuration ,principle of operation and control, Analysis and design, mo umerical problems Total (I rse the student will be able to:	odelli	ng si 9 ng, si	mula	tion 0
Classifica and perfo Unit V Classifica and perfo Course C At the en	Ation, circuit prmance - n HYBI Ation, circuit prmance - nu Dutcomes: d of the cou i Unde i Analy	configuration ,principle of operation and control, Analysis and design, mo umerical problems RID ACTIVE POWER FILTER configuration ,principle of operation and control, Analysis and design, mo umerical problems Total (I rse the student will be able to: rstand the fundamentals of harmonics	odelli	ng si 9 ng, si	mula	tion 0
Classifica and perfo Unit V Classifica and perfo Course (At the en CO1 CO2 CO3	Ation, circuit prmance - n HYBI Ation, circuit prmance - n Dutcomes: d of the cou : Unde : Analy : Analy	configuration ,principle of operation and control, Analysis and design, mo umerical problems RID ACTIVE POWER FILTER configuration ,principle of operation and control, Analysis and design, mo umerical problems Total (I rse the student will be able to: rstand the fundamentals of harmonics rze and design of passive power filter	odelli	ng si 9 ng, si	mula	tion 0
Classifica and perfo Unit V Classifica and perfo Course (At the en CO1 CO2	Ation, circuit prmance - n HYBI Ation, circuit prmance - n Dutcomes: d of the cou : Unde : Analy : Analy : Analy	configuration ,principle of operation and control, Analysis and design, mo umerical problems RID ACTIVE POWER FILTER configuration ,principle of operation and control, Analysis and design, mo umerical problems Total (I rse the student will be able to: rstand the fundamentals of harmonics rze and design of passive power filter rze and design of shunt active power filter	odelli	ng si 9 ng, si	mula	tion 0
Classifica and perfo Unit V Classifica and perfo Course C At the en CO1 CO2 CO3 CO4 CO5	Ation, circuit prmance - n HYBI Ation, circuit prmance - nu Dutcomes: d of the cou : Unde : Analy : Analy : Analy : Analy	configuration ,principle of operation and control, Analysis and design, mo umerical problems RID ACTIVE POWER FILTER configuration ,principle of operation and control, Analysis and design, mo umerical problems Total (I rse the student will be able to: rstand the fundamentals of harmonics rze and design of passive power filter rze and design of shunt active power filter rze and design of series active power filter	odelli	ng si 9 ng, si	mula	tion 0
Classifica and perfo Unit V Classifica and perfo Course C At the en CO1 CO2 CO3 CO4 CO5	Ation, circuit prmance - n HYBI Ation, circuit prmance - nu Dutcomes: d of the cou : Analy : Analy : Analy : Analy bks: Power qu	configuration ,principle of operation and control, Analysis and design, mo umerical problems RID ACTIVE POWER FILTER configuration ,principle of operation and control, Analysis and design, mo umerical problems Total (I rse the student will be able to: rstand the fundamentals of harmonics rze and design of passive power filter rze and design of shunt active power filter rze and design of series active power filter	odelli odellir L+T):	9 9 = 45	Peri	tior 0 tior
Classifica and perfo Unit V Classifica and perfo Course C At the en CO1 CO2 CO3 CO4 CO5 Text Boc	ation, circuit prmance - n HYBI ation, circuit prmance - nu Dutcomes: d of the cou : Analy : Analy : Analy : Analy : Analy bks: Power qu Haddad" J Electrical p	configuration ,principle of operation and control, Analysis and design, mo umerical problems RID ACTIVE POWER FILTER configuration ,principle of operation and control, Analysis and design, mo umerical problems Total (I rse the student will be able to: rstand the fundamentals of harmonics rze and design of passive power filter rze and design of shunt active power filter rze and design of series active power filter rze and design of hybrid active power filter	odelli odellir L+T):	9 9 = 45	Peri	tior tior
Classifica and perfo Unit V Classifica and perfo Course (At the en CO1 CO2 CO3 CO4 CO5 Text Boo 1. 2.	ation, circuit prmance - n HYBI ation, circuit prmance - nu Dutcomes: d of the cou : Unde : Analy : Analy : Analy : Analy bks: Power qu Haddad" J Electrical p	configuration ,principle of operation and control, Analysis and design, mo umerical problems RID ACTIVE POWER FILTER configuration ,principle of operation and control, Analysis and design, mo umerical problems Total (I rse the student will be able to: rstand the fundamentals of harmonics rze and design of passive power filter rze and design of shunt active power filter rze and design of series active power filter rze and design of hybrid active power rze and hybrid a	odelli odellir L+T):	9 9 = 45	Peri	tior tior
Classifica and perfo Unit V Classifica and perfo Course (At the en CO1 CO2 CO3 CO4 CO5 Text Boo 1. 2.	Ation, circuit prmance - n HYBI Ation, circuit prmance - n Dutcomes: d of the cou : Unde : Analy : Analy : Analy : Analy poks: Power qu Haddad" J Electrical p McGraw – ce Books:	configuration ,principle of operation and control, Analysis and design, mo umerical problems RID ACTIVE POWER FILTER configuration ,principle of operation and control, Analysis and design, mo umerical problems Total (I rse the student will be able to: rstand the fundamentals of harmonics rze and design of passive power filter rze and design of shunt active power filter rze and design of series active power filter rze and design of hybrid active power rze and hybrid a	ra ar	9 9 = 45	Peri	tior tior

	CO Statement	PO1	PO	PO	PO4	PO	PO	PO	PO	PO	PO1	P01
PO CO			2	3		5	6	7	8	9	0	1
CO1	Understand the fundamentals of harmonics	1	1	3	2	3	1	1	1	1	1	1
CO2	Analyze and design of passive power filter	1	3	2	2	1	1	1		1	1	1
CO3	Analyze and design of shunt active power filter	1	3	2	2	1	1	1		1	1	1
CO4	Analyze and design of series active power filter	1	3	2	2	1	1	1		1	1	1
CO5	Analyze and design of hybrid active power filter	1	3	2	2	1	1	1		1	1	1

18	BPEE33	ENERGY CONSERVATION, AUDITING AND MANAGEMENT	LT	P
			3 0	0
Course	e Objective:	s		
		ndthe energy conservation concepts.		
		but electrical energy management.		
Unit I	ENERGY	SCENARIO	9	+
intensit	ty – Curren	of India – Present non-renewable energy scenario – Gross domestic t energy production and pricing – Energy security - Energy strategy t hange. Energy Conservation Act-2001 and its features.		
Unit II	ENERG	SY CONSERVATION APPROACHES	9	+
		Introduction – Work, power and energy – Electricity basics – Thermal	-	
Energy capacit	v saving oppo tor, Synchro	onversions – Energy performance – Matching energy usage to requirement ortunities in electric motors, Benefits of Power factor improvement and its nous Condenser etc., Energy conservation by industrial drives, electric fur chniques – Natural ,CFL, LED lighting sources and fittings.	technique	
Unit III	ENERG	SY AUDITING	9	+
		y audit methodology : audit preparation, execution and reporting – Fir	-	
		 Project financing options - Energy monitoring and targeting –Energy and 		
	systems			
<u> </u>				
Unit IV	/ ENERG	SY MANAGEMENT	9	+
Demar	nd side mana	agement (DSM)– DSM planning – DSM techniques – Load management a	as a DSM :	strated
		tion – tarrif options for DSM - Energy audit – instruments for energy audit		
		ition and utilization systems – economic analysis.	- 57	
0				
Unit V	ENERG	Y EFFICIENT TECHNOLOGIES	9	+
Maxim	um demand	controllers - Automatic power factor controllers - Energy efficient motors	-Soft start	ers wi
		able speed drives - Energy efficient transformers - Electronic ballast - Oco		
		nting controls - Energy saving potential of each technology.	. ,	
	5			
		Total (L+T)= 45 F	Period
Course	e Outcomes			
Upon c	completion o	f this course, the students will be able to:		
C01	-	and the present energy scenario.		
CO2		lamental knowledge about energy and its various forms.		
CO2		and the process of energy management and energy auditing.		
CO4		and the methods improving energy efficiency.		
CO5		and the concepts of energy efficient devices.		
	nce Books:			
		Energy Audit, Sonal Desai, McGraw Hill, 2015.		
		Electrical Energy and Conservation, S.C. Tripathy,McGraw Hill, 1980.	A 11.	<u> </u>
		for National Certification Examination for Energy Manager / Energy ects (available online).	/ Auditors	Book-
4. G	Guide books	for National Certification Examination for Energy Manager / Energy	/ Auditors	Book-
		ties (available online) gement, W.R. Murphy&G. McKay, Butterworths Publications, 1981.		
			06	
6. E	nergy Mana	gement Hand Book, Wayne C Tuner, John Wiley and Sons, 6 th edition, 20	<i>i</i> U0.	

PO CO	CO Statement	PO1	PO 2	PO 3	PO4	PO 5	PO 6	PO 7	PO 8	PO 9	PO10	PO1 1
CO1	Understand the present energy scenario.	1	1	1	1	1	1	3	1	1	1	1
CO2	Get fundamental knowledge about energy and its various forms.	1	1	3	3	1	1	3	1	1	2	1
CO3	Understand the process of energy management and energy auditing.	1	1	2	2	2	1	1	1	1	3	1
CO4	Understand the methods improving energy efficiency.	2	3	2	3	3	1	2	2	1	2	2
CO5	Understand the concepts of energy efficient devices.	2	2	3	3	3	1	2	3	1	2	2

	PEE34 SPECIAL ELECTRICA	L MACHINES AND DRIVES	LT	Ρ	С
	·		3 0	0	3
	urse Objectives:				
1.	To review the fundamental concepts of per	manent magnets and the operation of perr	nanen	mag	Inet
	brushless DC motors.				
2.	To introduce the concepts of permanent r	nagnet brushless synchronous motors and	d Syno	chron	ous
	reluctance motors.				
3.	To develop the control methods and operatin				
4.	To introduce the concepts of stepper motors				
5.	To understand the basic concepts of other sp	ecial machines.			
	T I PERMANENT MAGNET BRUSHLESS	DC MOTORS	9	+	0
	damentals of permanent magnets – Types – P		-		-
	que equations – Characteristics and control.		y 313 —		anu
TOIY					
UNIT	T II PERMANENT MAGNET SYNCHRON	OUS MOTORS	9	+	0
-	ciple of operation – EMF and Torque equation		-	ie-sp	-
char	racteristics – Digital controllers – Construction	onal features, operating principle and ch	aracte	ristics	of
	chronous reluctance motor.	, 1 31 1			
			9	+	0
	structional features - Principle of operation -		er con	trolle	'S -
Cont	trol of SRM drive – Sensorless operation of SR	M – Applications.			
UNIT			9		0
	structional features –Principle of operation – Ty		n-linear	anal	ysis
– Ch	haracteristics – Drive circuits – Closed loop con	trol – Applications.			
					-
UNIT			9	-	0
	ciple of operation and characteristics of Hystere	sis motor – AC series motors – Linear induc	ction m	otor -	_
Appl	lications.				
			T)AE	Dori	<u> </u>
	urse Outcomes:	Total (L+	1)= 45	Perio	Jus
Upor	on completion of this course, the students will be				
Ċ01					
C01 C02	, , ,	nt Magnet Synchronous Motor.			
CO1 CO2 CO3	3 : Analyze and design controllers for specia	nt Magnet Synchronous Motor. al Electrical Machines.			
CO1 CO2 CO3 CO4	 3 : Analyze and design controllers for special 4 : Learn about characteristics and application 	nt Magnet Synchronous Motor. al Electrical Machines. on of stepper motors.			
CO1 CO2 CO3 CO4 CO5	 3 : Analyze and design controllers for special 4 : Learn about characteristics and application 5 : Understand the necessity of special electronic 	nt Magnet Synchronous Motor. al Electrical Machines. on of stepper motors.			
CO1 CO2 CO3 CO4 CO5 Text	 3 : Analyze and design controllers for special 4 : Learn about characteristics and applicati 5 : Understand the necessity of special elect t Books: 	nt Magnet Synchronous Motor. Al Electrical Machines. on of stepper motors. trical machines in industry			
CO1 CO2 CO3 CO4 CO5 Text 1.	3 : Analyze and design controllers for special 4 : Learn about characteristics and application 5 : Understand the necessity of special election t Books: Miller, T.J.E., "Brushless Magnet and Reluctary	nt Magnet Synchronous Motor. al Electrical Machines. on of stepper motors. trical machines in industry nce Motor Drives", Claredon Press, London,	1989.		
CO1 CO2 CO3 CO4 CO5 Text	3 : Analyze and design controllers for special 4 : Learn about characteristics and application 5 : Understand the necessity of special election t Books: Miller, T.J.E., "Brushless Magnet and Reluctar Krishnan, R., "Switched Reluctance Motor Drive	nt Magnet Synchronous Motor. al Electrical Machines. on of stepper motors. trical machines in industry nce Motor Drives", Claredon Press, London, ives", CRC press, 2001.			
CO1 CO2 CO3 CO4 CO5 Text 1. 2.	3 : Analyze and design controllers for special 4 : Learn about characteristics and application 5 : Understand the necessity of special election t Books: Miller, T.J.E., "Brushless Magnet and Reluctant Krishnan, R., "Switched Reluctance Motor Drive Kenjo, T., "Stepping Motors and their Micro	nt Magnet Synchronous Motor. al Electrical Machines. on of stepper motors. trical machines in industry nce Motor Drives", Claredon Press, London, ives", CRC press, 2001.		ew De	elhi
CO1 CO2 CO3 CO4 CO5 Text 1. 2. 3.	 3 : Analyze and design controllers for special 4 : Learn about characteristics and application 5 : Understand the necessity of special election t Books: Miller, T.J.E., "Brushless Magnet and Reluctant Krishnan, R., "Switched Reluctance Motor Drive Kenjo, T., "Stepping Motors and their Micro 2000. 	nt Magnet Synchronous Motor. al Electrical Machines. on of stepper motors. trical machines in industry nce Motor Drives", Claredon Press, London, ives", CRC press, 2001.		ew De	elhi
CO1 CO2 CO3 CO4 CO5 Text 1. 2. 3. Refe	 3 : Analyze and design controllers for special 4 : Learn about characteristics and application 5 : Understand the necessity of special election t Books: Miller, T.J.E., "Brushless Magnet and Reluctand Krishnan, R., "Switched Reluctance Motor Drive Kenjo, T., "Stepping Motors and their Micro 2000. erence Books: 	nt Magnet Synchronous Motor. al Electrical Machines. on of stepper motors. trical machines in industry nce Motor Drives", Claredon Press, London, ives", CRC press, 2001. processor Controls', Oxford University Pre	ess, Ne		
CO1 CO2 CO3 CO4 CO5 Text 1. 2. 3.	 3 : Analyze and design controllers for special 4 : Learn about characteristics and application 5 : Understand the necessity of special election t Books: Miller, T.J.E., "Brushless Magnet and Reluctant Krishnan, R., "Switched Reluctance Motor Drive Kenjo, T., "Stepping Motors and their Micro 2000. 	nt Magnet Synchronous Motor. al Electrical Machines. on of stepper motors. trical machines in industry nce Motor Drives", Claredon Press, London, ives", CRC press, 2001. processor Controls', Oxford University Pre	ess, Ne		

PO CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO1 0	PO1 1
CO1	Gain the knowledge of fundamental concepts of special machines.	1	1	1	1	1	1	3	1	1	1	1
CO2	Develop the phasor diagram of Permanent Magnet Synchronous Motor.	1	2	2	3	1	2	2	1		2	1
CO3	Analyze and design controllers for special Electrical Machines.	1	2	2	2	2	1	1	1	1	3	1
CO4	Learn about characteristics and application of stepper motors.	2	3	2	3	3	1	2	2	1	2	2
CO5	Understand the necessity of special electrical machines in industry	2	2	3	3	3	1	2	3	1	2	2

3 Course Objectives: To provide knowledge on modeling and simulation of power electronic circuits and systems UNIT I NUMERICAL METHODS IN PASSIVE COMPONENTS Review of numerical methods. Application of numerical methods to solve transients in D.C. Switche L, R-C and R-L-C circuits. Extension to AC circuits. UNIT II SIMULATION AND MODELLING OF ACTIVE AND PASSIVE COMPONENTS Modeling of diode in simulation. Diode with R, R-L, R-C and R-L-C load with ac supply. Modeling of	0 9 ed R,	0 +	
To provide knowledge on modeling and simulation of power electronic circuits and systems UNIT I NUMERICAL METHODS IN PASSIVE COMPONENTS Review of numerical methods. Application of numerical methods to solve transients in D.C. Switche L, R-C and R-L-C circuits. Extension to AC circuits. UNIT II SIMULATION AND MODELLING OF ACTIVE AND PASSIVE COMPONENTS Modeling of diode in simulation. Diode with R, R-L, R-C and R-L-C load with ac supply. Modeling of	-		 R
UNIT I NUMERICAL METHODS IN PASSIVE COMPONENTS Review of numerical methods. Application of numerical methods to solve transients in D.C. Switche L, R-C and R-L-C circuits. Extension to AC circuits. UNIT II SIMULATION AND MODELLING OF ACTIVE AND PASSIVE COMPONENTS Modeling of diode in simulation. Diode with R, R-L, R-C and R-L-C load with ac supply. Modeling of	-		_ _ R
Review of numerical methods. Application of numerical methods to solve transients in D.C. Switche L, R-C and R-L-C circuits. Extension to AC circuits. UNIT II SIMULATION AND MODELLING OF ACTIVE AND PASSIVE COMPONENTS Modeling of diode in simulation. Diode with R, R-L, R-C and R-L-C load with ac supply. Modeling of	-		R
Review of numerical methods. Application of numerical methods to solve transients in D.C. Switche L, R-C and R-L-C circuits. Extension to AC circuits. UNIT II SIMULATION AND MODELLING OF ACTIVE AND PASSIVE COMPONENTS Modeling of diode in simulation. Diode with R, R-L, R-C and R-L-C load with ac supply. Modeling of	-		R
L, R-C and R-L-C circuits. Extension to AC circuits. UNIT II SIMULATION AND MODELLING OF ACTIVE AND PASSIVE COMPONENTS Modeling of diode in simulation. Diode with R, R-L, R-C and R-L-C load with ac supply. Modeling of	ja rt,	, _ ,	• •
Modeling of diode in simulation. Diode with R, R-L, R-C and R-L-C load with ac supply. Modeling of			
Modeling of diode in simulation. Diode with R, R-L, R-C and R-L-C load with ac supply. Modeling of	9	+	Т
	f SCI		_
TRIAC, IGBT and Power Transistors in simulation. Application of numerical methods to R, L, C circu			ı
power electronic switches. Simulation of gate/base drive circuits, simulation of snubber circuits.			
UNIT III STATE SPACE MODELLING AND SIMULATION OF LINEAR SYSTEMS	9	+	Т
State space modeling and simulation of linear systems. Introduction to electrical machine modeling:	: ind	lucti	0
DC, and synchronous machines, simulation of basic electric drives, stability aspects.			
UNIT IV SIMULATION OF CONVERTERS AND DC DRIVES	9	+	
			f
chopper fed dc motor.			' —
UNIT V SIMULATION OF INVERTERS AND AC DRIVES	9	+	
UNIT V SIMULATION OF INVERTERS AND AC DRIVES Simulation of single and three phase inverters with thyristors and self-commutated devices, Space v representation, pulse-width modulation methods for voltage control, waveform control. Simulation o	vecto	tor	
UNIT V SIMULATION OF INVERTERS AND AC DRIVES Simulation of single and three phase inverters with thyristors and self-commutated devices, Space vertex representation, pulse-width modulation methods for voltage control, waveform control. Simulation of red induction motor drives.	vecto of inv	tor /erte	ər
UNIT V SIMULATION OF INVERTERS AND AC DRIVES Simulation of single and three phase inverters with thyristors and self-commutated devices, Space representation, pulse-width modulation methods for voltage control, waveform control. Simulation of fed induction motor drives. Total (L+T)=	vecto of inv	tor /erte	ər
UNIT V SIMULATION OF INVERTERS AND AC DRIVES Simulation of single and three phase inverters with thyristors and self-commutated devices, Space verepresentation, pulse-width modulation methods for voltage control, waveform control. Simulation of induction motor drives. Total (L+T)= Course Outcomes: Upon completion of this course, the students will be able to:	vecto of invo	tor /erte Perio	ər
UNIT V SIMULATION OF INVERTERS AND AC DRIVES Simulation of single and three phase inverters with thyristors and self-commutated devices, Space verepresentation, pulse-width modulation methods for voltage control, waveform control. Simulation of fed induction motor drives. Total (L+T)= Course Outcomes: Upon completion of this course, the students will be able to: CO1 Understand the concepts of modeling and simulation of power electronics and drives circ	vecto of invo	tor /erte Perio	ər
UNIT V SIMULATION OF INVERTERS AND AC DRIVES Simulation of single and three phase inverters with thyristors and self-commutated devices, Space vertex representation, pulse-width modulation methods for voltage control, waveform control. Simulation of ted induction motor drives. Total (L+T)= Course Outcomes: Upon completion of this course, the students will be able to: CO1 Course of modeling and simulation of power electronics and drives circe CO2 Develop algorithm and software models for power electronics and drives applications	vecto of invo	tor /erte Perio	ər
UNIT V SIMULATION OF INVERTERS AND AC DRIVES Simulation of single and three phase inverters with thyristors and self-commutated devices, Space verepresentation, pulse-width modulation methods for voltage control, waveform control. Simulation of fed induction motor drives. Total (L+T)= Course Outcomes: Upon completion of this course, the students will be able to: CO1 Course of modeling and simulation of power electronics and drives circe CO2 Develop algorithm and software models for power electronics and drives applications CO3 CO3 Annalyze the transient and steady performance of the designed models.	vecto of invo	tor /erte Perio	ər
UNIT V SIMULATION OF INVERTERS AND AC DRIVES Simulation of single and three phase inverters with thyristors and self-commutated devices, Space representation, pulse-width modulation methods for voltage control, waveform control. Simulation of ed induction motor drives. Total (L+T)= Course Outcomes: Upon completion of this course, the students will be able to: CO1 : Understand the concepts of modeling and simulation of power electronics and drives circ CO2 : Develop algorithm and software models for power electronics and drives applications CO3 : Aanalyze the transient and steady performance of the designed models. CO4 : Choose suitable devices or models for appropriate applications	vecto of invo	tor /erte Perio	ər
UNIT V SIMULATION OF INVERTERS AND AC DRIVES Simulation of single and three phase inverters with thyristors and self-commutated devices, Space representation, pulse-width modulation methods for voltage control, waveform control. Simulation of fed induction motor drives. Total (L+T)= Course Outcomes: Upon completion of this course, the students will be able to: CO1 : Understand the concepts of modeling and simulation of power electronics and drives circ CO2 : Develop algorithm and software models for power electronics and drives applications CO3 : Analyze the transient and steady performance of the designed models. CO4 : Choose suitable devices or models for appropriate applications CO5 :	vecto of invo	tor /erte Perio	ər
UNIT V SIMULATION OF INVERTERS AND AC DRIVES Simulation of single and three phase inverters with thyristors and self-commutated devices, Space or representation, pulse-width modulation methods for voltage control, waveform control. Simulation of fed induction motor drives. Total (L+T)= Course Outcomes: Upon completion of this course, the students will be able to: CO1 : Understand the concepts of modeling and simulation of power electronics and drives circe CO2 : Develop algorithm and software models for power electronics and drives applications CO4 : Choose suitable devices or models for appropriate applications CO4 : Choose suitable devices or models for appropriate applications CO5 : Identify suitable hardware components for implementation	vecto of invo	tor /erte Perio	ər
UNIT V SIMULATION OF INVERTERS AND AC DRIVES Simulation of single and three phase inverters with thyristors and self-commutated devices, Space or representation, pulse-width modulation methods for voltage control, waveform control. Simulation or fed induction motor drives. Total (L+T)= Course Outcomes: Upon completion of this course, the students will be able to: CO1 : Understand the concepts of modeling and simulation of power electronics and drives circe CO2 : Develop algorithm and software models for power electronics and drives applications CO3 : Aanalyze the transient and steady performance of the designed models. CO4 : Choose suitable devices or models for appropriate applications CO5 : Identify suitable hardware components for implementation Reference Books:	vecto of invo	tor /erte Perio	ər

PO CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO 8	PO9	PO1 0	PO1 1
CO1	Understand the concepts of modeling and simulation of power electronics and drives circuits.	3	2	2	2	2	1	2	1	2	1	1
CO2	Develop algorithm and software models for power electronics and drives applications	3	3	3	3	3	3	2	2	2	1	1
CO3	Aanalyze the transient and steady performance of the designed models.	3	3	3	2	2	2	3	3	2	1	1
CO4	Choose suitable devices or models for appropriate applications	3	3	2	3	3	2	2	2	1	2	1
CO5	Identify suitable hardware components for implementation	3	2	2	2	2	1	2	1	2	1	1

18PEE41	PHOTO VOLTAIC SYSTEM		P 0	(
			0	
Course Objective				
	the principle of direct solar energy conversion to power using PV technology. with the structure, materials and operation of solar cells, PV modules, and array	1		
	The concept to design PV systems for various applications.	5.		
	edge on Socio-economic and environmental merits of photovoltaic systems fo	rav	ariet	y c
Unit I PHOTO	OLTAIC CELL FUNDAMENTALS AND MANUFACTURING	9	+	(
properties, energy Production proces	 Principle of direct solar energy conversion into electricity in a solar cell. Semi levels, basic equations. Solar cell, p-n junction, structure. Commercial solar ce s of single crystalline silicon cells, multi crystalline silicon cells, amorphous silico dium gallium diselenide cells. 	lls -		
Unit II PV MOI	DULE PERFORMANCE	9		(
	of a PV module, maximum power point, cell efficiency, fill factor, effect of ir	-	tion	
emperature, case		auia		
Jnit III DESIG	N OF PV SYSTEMS	9	+	(
•	V systems and cost estimation. Case study of design of solar PV lantern, sta hting and other appliances, solar water pumping systems.	nd a	lone	Ρ
System Theme lig				
Unit IV CLASS				
Classification - Ce nteractive PV Sys photovoltaic. Syste	SIFICATION OF PV SYSTEMS AND COMPONENTS ntral Power Station System, Distributed PV System, Stand alone PV system, G tem, small system for consumer applications, Hybrid solar PV system, Concent em components - PV arrays, inverters, batteries, charge controls, net power me	rator		
Classification - Ce Interactive PV Sys photovoltaic. Syste	ntral Power Station System, Distributed PV System, Stand alone PV system, G tem, small system for consumer applications, Hybrid solar PV system, Concent	rid rator	sola	(r
Classification - Ce Interactive PV Sys photovoltaic. Syste array installation, o	ntral Power Station System, Distributed PV System, Stand alone PV system, G tem, small system for consumer applications, Hybrid solar PV system, Concent em components - PV arrays, inverters, batteries, charge controls, net power me	rid rator	sola	r
Classification - Ce Interactive PV Sys photovoltaic. Syste array installation, o Unit V PV SYS Building-integrated distributed power	ntral Power Station System, Distributed PV System, Stand alone PV system, G tem, small system for consumer applications, Hybrid solar PV system, Concent em components - PV arrays, inverters, batteries, charge controls, net power me operation, costs, reliability.	rid rator ters. 9 devi	sola PV + ces	r fo
Classification - Ce Interactive PV Sys photovoltaic. Syste array installation, o Unit V PV SYS Building-integrated distributed power	ntral Power Station System, Distributed PV System, Stand alone PV system, G tem, small system for consumer applications, Hybrid solar PV system, Concent em components - PV arrays, inverters, batteries, charge controls, net power me operation, costs, reliability. TEM APPLICATIONS d photovoltaic units, grid-interacting central power stations, standalone supply in remote and rural areas, solar cars, aircraft, space solar power sate ironmental merits of photovoltaic systems.	rid rator ters. 9 devi	sola PV + ces . So	r fc
Classification - Ce nteractive PV Sys ohotovoltaic. Syste array installation, o Unit V PV SYS Building-integrated distributed power economic and env	ntral Power Station System, Distributed PV System, Stand alone PV system, G tem, small system for consumer applications, Hybrid solar PV system, Concent em components - PV arrays, inverters, batteries, charge controls, net power me operation, costs, reliability. TEM APPLICATIONS d photovoltaic units, grid-interacting central power stations, standalone supply in remote and rural areas, solar cars, aircraft, space solar power sate ironmental merits of photovoltaic systems. Total (L+T) :	rid rator ters. 9 devi	sola PV + ces . So	r fc
Classification - Ce Interactive PV Sys photovoltaic. Syste array installation, o Unit V PV SYS Building-integrated distributed power economic and env Course Outcome	ntral Power Station System, Distributed PV System, Stand alone PV system, G tem, small system for consumer applications, Hybrid solar PV system, Concent em components - PV arrays, inverters, batteries, charge controls, net power me operation, costs, reliability. TEM APPLICATIONS d photovoltaic units, grid-interacting central power stations, standalone supply in remote and rural areas, solar cars, aircraft, space solar power sate ironmental merits of photovoltaic systems. Total (L+T) :	rid rator ters. 9 devi	sola PV + ces . So	r fc
Classification - Ce Interactive PV Sys photovoltaic. Syste array installation, o Unit V PV SYS Building-integrated distributed power economic and env Course Outcome Upon completion o CO1 : Remen	ntral Power Station System, Distributed PV System, Stand alone PV system, G tem, small system for consumer applications, Hybrid solar PV system, Concent em components - PV arrays, inverters, batteries, charge controls, net power me operation, costs, reliability. TEM APPLICATIONS d photovoltaic units, grid-interacting central power stations, standalone supply in remote and rural areas, solar cars, aircraft, space solar power sate ironmental merits of photovoltaic systems. Total (L+T) : s: of this course, the students will be able to: mber with the fundamental concepts of Solar Photovoltaic system	rid rator ters. 9 devi	sola PV + ces . So	r fc
Classification - Ce Interactive PV Sys photovoltaic. Syste array installation, o Unit V PV SYS Building-integrated distributed power economic and env Course Outcome Upon completion o CO1 : Remen CO2 : Underst	ntral Power Station System, Distributed PV System, Stand alone PV system, G tem, small system for consumer applications, Hybrid solar PV system, Concent em components - PV arrays, inverters, batteries, charge controls, net power me operation, costs, reliability. TEM APPLICATIONS d photovoltaic units, grid-interacting central power stations, standalone supply in remote and rural areas, solar cars, aircraft, space solar power sate ironmental merits of photovoltaic systems. Total (L+T): s: of this course, the students will be able to: nber with the fundamental concepts of Solar Photovoltaic system and the working operation of various components of photovoltaic system	rid rator ters. 9 devi	sola PV + ces . So	r fc
Classification - Ce Interactive PV Sys photovoltaic. Syste array installation, o Unit V PV SYS Building-integrated distributed power economic and env Course Outcome Upon completion o CO1 : Remen CO2 : Underst CO3 : Apply th	ntral Power Station System, Distributed PV System, Stand alone PV system, G tem, small system for consumer applications, Hybrid solar PV system, Concent em components - PV arrays, inverters, batteries, charge controls, net power me operation, costs, reliability. TEM APPLICATIONS d photovoltaic units, grid-interacting central power stations, standalone supply in remote and rural areas, solar cars, aircraft, space solar power sate ironmental merits of photovoltaic systems. Total (L+T) s: of this course, the students will be able to: her with the fundamental concepts of Solar Photovoltaic system and the working operation of various components of photovoltaic system the relevant design concepts in any organisation	rid rator ters. 9 devi	sola PV + ces . So	r fc
Classification - Ce Interactive PV System obotovoltaic. System array installation, of Unit V PV SYS Building-integrated distributed power economic and enver course Outcome Upon completion of CO1 : Rement CO2 : Underst CO3 : Apply th CO4 : Analyze	ntral Power Station System, Distributed PV System, Stand alone PV system, G tem, small system for consumer applications, Hybrid solar PV system, Concent em components - PV arrays, inverters, batteries, charge controls, net power me operation, costs, reliability. TEM APPLICATIONS d photovoltaic units, grid-interacting central power stations, standalone supply in remote and rural areas, solar cars, aircraft, space solar power sate ironmental merits of photovoltaic systems. Total (L+T) s: of this course, the students will be able to: her with the fundamental concepts of Solar Photovoltaic system and the working operation of various components of photovoltaic system te relevant design concepts in any organisation the performance of different PV system.	rid rator ters. 9 devi ellites = 45	sola PV + ces . So	r fc
Classification - Ce Interactive PV Sys obotovoltaic. Syste array installation, o Unit V PV SYS Building-integrated distributed power economic and env Course Outcome Upon completion o CO1 : Remen CO2 : Underst CO3 : Apply th CO4 : Analyze CO5 : Evalua	ntral Power Station System, Distributed PV System, Stand alone PV system, G tem, small system for consumer applications, Hybrid solar PV system, Concent em components - PV arrays, inverters, batteries, charge controls, net power me operation, costs, reliability. TEM APPLICATIONS d photovoltaic units, grid-interacting central power stations, standalone supply in remote and rural areas, solar cars, aircraft, space solar power sate ironmental merits of photovoltaic systems. Total (L+T): s: of this course, the students will be able to: mber with the fundamental concepts of Solar Photovoltaic system and the working operation of various components of photovoltaic system the relevant design concepts in any organisation the performance of different PV system. te and suggest the economic practices to be carried out for different application	rid rator ters. 9 devi ellites = 45	sola PV + ces . So	r fo
Classification - Ce Interactive PV Sys photovoltaic. Syste array installation, o Unit V PV SYS Building-integrated distributed power economic and env Course Outcome Upon completion o CO1 : Remen CO2 : Underst CO3 : Apply th CO4 : Analyze CO5 : Evalua Reference Books	ntral Power Station System, Distributed PV System, Stand alone PV system, G tem, small system for consumer applications, Hybrid solar PV system, Concent em components - PV arrays, inverters, batteries, charge controls, net power me operation, costs, reliability. TEM APPLICATIONS d photovoltaic units, grid-interacting central power stations, standalone supply in remote and rural areas, solar cars, aircraft, space solar power sate ironmental merits of photovoltaic systems. Total (L+T): s: of this course, the students will be able to: mber with the fundamental concepts of Solar Photovoltaic system and the working operation of various components of photovoltaic system the relevant design concepts in any organisation the performance of different PV system. te and suggest the economic practices to be carried out for different application	rid rator ters. 9 devi ellites = 45	sola PV + ces . So Peri	r fo cio
Classification - Ce Interactive PV Sys photovoltaic. Syste array installation, o Unit V PV SYS Building-integrated distributed power economic and env Course Outcome Upon completion o CO1 : Remen CO2 : Undersi CO3 : Apply th CO4 : Analyze CO5 : Evalua Reference Books 1. Chetan Singl PHI, 2012 2. Fundamenta	ntral Power Station System, Distributed PV System, Stand alone PV system, G tem, small system for consumer applications, Hybrid solar PV system, Concent em components - PV arrays, inverters, batteries, charge controls, net power me operation, costs, reliability. TEM APPLICATIONS d photovoltaic units, grid-interacting central power stations, standalone supply in remote and rural areas, solar cars, aircraft, space solar power sate ironmental merits of photovoltaic systems. Total (L+T): s: of this course, the students will be able to: mber with the fundamental concepts of Solar Photovoltaic system and the working operation of various components of photovoltaic system te relevant design concepts in any organisation the performance of different PV system. te and suggest the economic practices to be carried out for different application :	rid rator ters. 9 devi ellites = 45	sola PV + ces . So Peri	r fc cic
Classification - Ce Interactive PV System obotovoltaic. System array installation, or Unit V PV SYS Building-integrated distributed power economic and envert distributed power economic and envert conse Outcome Upon completion of CO1 : Remen CO2 : Underst CO3 : Apply th CO4 : Analyze CO5 : Evaluat Reference Books 1. Chetan Singl PHI, 2012 2. Fundamental ISBN:978184 3. Photovoltaic	ntral Power Station System, Distributed PV System, Stand alone PV system, G tem, small system for consumer applications, Hybrid solar PV system, Concent em components - PV arrays, inverters, batteries, charge controls, net power me operation, costs, reliability. TEM APPLICATIONS d photovoltaic units, grid-interacting central power stations, standalone supply in remote and rural areas, solar cars, aircraft, space solar power sate ironmental merits of photovoltaic systems. Total (L+T): s: of this course, the students will be able to: mber with the fundamental concepts of Solar Photovoltaic system and the working operation of various components of photovoltaic system the performance of different PV system. te and suggest the economic practices to be carried out for different application the poly in photovoltaics: Fundamentals Technology and Applications, Se as of Photovoltaic Modules & Their Applications, by Gopal Nath Tiwari,	rid rator ters. devi ellites = 45 s.	sola PV tes . So Peri	

PO	CO Statement	PO1	PO 2	PO 3	PO4	PO 5	PO 6	PO 7	PO 8	PO 9	PO10	PO1 1
CO1	Remember with the fundamental concepts of Solar Photovoltaic system	1	1	1	1	1	2	3	1	1	1	2
CO2	Understand the working operation of various components of photovoltaic system	1	1	2	2	2	1	1	1	1	3	1
CO3	Apply the relevant design concepts in any organisation	1	1	3	3	1	1	3	1	1	2	1
CO4	Analyze the performance of different PV system.	2	3	2	3	3	1	2	2	1	2	2
CO5	Evaluate and suggest the economic practices to be carried out for different applications.	2	2	3	3	3	3	2	3	2	2	2

1	8PEE42	OPTIMIZATION TECHNIQUES	L	Т	Ρ	С
			3	0	0	3
Cour	oo Ohiootiyo					
Lours	se Objectives To understar	s: In the need for optimization and different techniques involved and also cons	train	ts		
2.		ear/Non-linear Programming.				
3.		d the importance of optimization to solve Engineering problems				
4.	To know gen	etic algorithm for Engineering Optimization				
Unit I	INTRODU	ICTION	9		+	0
		ization- Engineering applications - Statement of optimization Problem ·				
		tion Techniques: Single and multi variable optimization- Optimization wi	th e	qual	ity a	nd
inequ	ality constrain	IS				
Unit I	I LINEAR	PROGRAMMING	9		+	0
		g: Standard form-Geometry of LP problems-Theorem of LP - Relation				
		problems - simplex method and algorithm - Matrix form- two phase method ecomposition- Sensitivity analysis	l- Di	uality	/ - d	ual
Unit I		NEAR PROGRAMMING:	9			0
	-	nethod, conjugates gradient method, Newton's Method, Sequential quadrati	-	oara	+ mmi	
		ethod, augmented Lagrange multiplier method	- p.	9.0		
	-					
Unit I		IIC PROGRAMMING processes, concept of sub-optimization and principle of optimality, Recu	9		+	0
						•
Unit V		C ALGORITHM netic Algorithm, working principle, coding of variables, fitness function,	9	000	+	0
		erences between GA and traditional methods; Unconstrained and constrain				
		rithm, real coded GA, Advanced GA, global optimization using GA.				
		Total (L+	T_	<u> </u>	orio	do
Cour	se Outcomes		1)=	45 F	eno	us
		f this course, the students will be able to:				
C01	· · · · · · · · · · · · · · · · · · ·	and the basics of optimization				
C01		nd formulate Linear Programming optimization problems				
CO3	Ŭ	nd formulate unconstraint and constraint optimization problems				
C03		timization problems to engineering applications				
C05		the optimization problems using Genetic Algorithm				
	Books:	su, S., "Engineering Optimization – Theory & Practice", New Age Internatio	nol		imit	<u></u>
1.	New Delhi, 20	00.				
/	Kalyanamoy [Pvt. 1995.	Deb, "Optimization for Engineering design algorithms and Examples", Prent	ice H	lall (of In	dia
	G.Luenberger 2011.	,- Introduction of Linear and Non-Linear Programming", Wesley Publis	hing	Co	mpa	ny,
Refer	ence Books:					
1.	Hamdy A. Tal	na, — Operations Research - An IntroductionII, MacMillan Co., Eighth Edition				
		din, —Optimisation in Operations Researchll Pearson Education Asia, Firs	t Inc	lian	repr	int,
	2013					

PO CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Understand the basics of optimization	1	1	1	1	2	3	1	1	1	1	1
CO2	Design and formulate Linear Programming optimization problems	1	1	3	3	2	3	1	2	1	2	1
CO3	Design and formulate unconstraint and constraint optimization problems	1	1	3	3	3	3	3	2	1	2	1
CO4	Apply optimization problems to engineering applications	1	2	3	3	3	3	3	2	1	2	1
CO5	Analyze the optimization problems using Genetic Algorithm	1	2	3	3	3	3	3	3	1	2	1

18PEE43	POWER SYSTEM OPTIMIZATION TECHNIQUES	L 1	- P	C 3
		3 1		3
Course Obje	ectives: lerstand the need for optimization and different techniques involved and also con	etrainte		
	· · ·	Siraniis		
	w evolutionary computation techniques			
	lerstand the importance of particle swarm optimization in power system wadvanced and multi objective Optimization			
Definition-Cla conditions-Cl	NDAMENTALS OF OPTIMIZATION assification of optimization problems-Unconstrained and Constrained optimi assical Optimization techniques-Linear and non linear programming, Quadrat r programming			
Unit II EV	OLUTIONARY COMPUTATION TECHNIQUES	9	+	0
Evolutionary Issues in GA	nature-Fundamentals of Evolutionary algorithms-Working Principles of Ge Strategy and Evolutionary Programming-Genetic Operators-Selection, Crossov A implementation- GA based Economic Dispatch solution- GA for unit commi- er flow- GA based state estimation	er and	Mutat	ion-
Unit III P	ARTICLE SWARM OPTIMIZATION	9	+	0
(Hybrid of G issues -Conv	principle-Velocity Updating-Advanced operators-Parameter selection- Hyl A and PSO, Hybrid of EP and PSO) -Binary, discrete and combinatorial PSC rergence issues- PSO based unit commitment-PSO for reactive power and volt stem reliability and security.)-Implei	nenta	tion
Unit IV A	DVANCED OPTIMIZATION METHODS	9	+	0
	nnealing algorithm-Tabu search algorithm-SA and TS for unit commitr Bacteria Foraging optimization.	ment-Ar	t co	lony
	JLTI OBJECTIVE OPTIMIZATION pareto optimality-Conventional approaches for multi objective optimization -Mu	9 Ilti obie	+	0 GA-
Fitness assig	nment-Sharing function-Economic dispatch using multi objective GA-Multiobject	ive PSC).	_
	Total (L	.+T)= 45	Peri	ods
Course Outo	:omes:			
Upon comple	tion of this course, the students will be able to:			
	derstand the basics of optimization			
CO2 : To	understand the need of optimization in power system			
	esign and formulate power system optimization problems using GA and PSO			
	nderstand the basics of advanced optimization techniques. alyze the optimization problems using multi objective Genetic Algorithm			
Text Books:	hari and J.S.Dhillon, "Power System Optimization", 2nd Edition, PHI learning	n nrivet	a limi	ted
^{1.} 2010.				ieu,
	Zhu,"Optimization of power system operation", John Wiley and sons Inc publication			
	Abdel Hady, Abdel Aal Hassan Mantawy, "Modern optimization techniques wit Power Systems", Springer, 2012.	n applie	ation	s in
	noy Deb, "Multi objective optimization using Evolutionary Algorithms", John V	Wiley a	nd So	ons,
Reference B	ooks.			
		otico Ha	ll of li	ndia
Pvt. 199	moy Deb, "Optimization for Engineering design algorithms and Examples", Prer			

PO CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Understand the basics of optimization	1	1	1	1	2	3	1	1	1	1	1
CO2	To understand the need of optimization in power system	1	1	2	2	2	3	1	1	1	2	1
CO3	Design and formulate power system optimization problems using GA and PSO	1	1	3	3	3	3	3	3	1	2	1
CO4	Understand the basics of advanced optimization techniques.	1	1	2	2	3	3	2	2	1	2	1
CO5	Analyze the optimization problems using multi objective Genetic Algorithm	1	2	3	3	3	3	2	3	1	2	1

18PEE44

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WIND ENERGY SYSTEM

L T P C 3 0 0 3

Course	e Objectives:
1. T	o impart understanding of various aspects related to wind energy systems and technology.
Unit I	
Wind E	nergy Program in India and the World: Overview of growth, development, progress and challenges
facing t	he wind industry.
Wind E	Energy Basics, Wind resource assessment, Wind Speeds and scales, Terrain, Roughness, Wind
Mechar	nics, Power Content, Principles of Aerodynamics of wind turbine blade, Class of wind turbines,
Atmosp	oheric Boundary Layers, Turbulence.
Unit II	Wind Measurements, Analysis and Energy Estimates & Aerodynamics Theory 9 + 0
Instrum	nentation for wind measurements, Wind data analysis, Wind resource estimation, Betz's Limit,
Turbule	ence Analysis
Airfoil t	terminology, Blade element theory, Blade design, Rotor performance and dynamics, Balancing
techniq	ue (Rotor & Blade), Types of loads; Sources of loads
Unit III	Wind Turbine Technology & Components of Wind Turbine Generator 9 + 0
	and VAWT, Constant Speed Constant Frequency, Variable speed Variable Frequency, Up Wind, Down
Wind, S	Stall Control, Pitch Control, Gear Coupled Generator type, Direct Generator Drive /PMG/Rotor Excited
Sync G	enerator.
Gear C	coupled Generator Wind Turbine Components and their construction, Direct Rotor Coupled Generator (
Multipol	le type)
Unit IV	6 /
	of Pitch System & Control Algorithms, Protections used & Safety Consideration in Wind turbines, Wind
Turbine	e Monitoring with Error codes, SCADA & Databases: Remote Monitoring and Generation Reports,
Operati	ion & Maintenance for Product Life Cycle, Balancing technique (Rotor & Blade), FACTS control, Low
Voltage	e Ride-Through & new trends for new grid codes.
Unit V	
Typical	layouts, site selection of wind farms, power evacuation, and operational problems with grid interface.
	e and onshore wind farms, merits and challenges.
	esource assessment and R & D costs, Fixed and variable costs, Value of wind energy, Life cycle
costing	and cash flow of wind power projects, Wind project owners / developers, Wind energy market
	Total (L+T)= 45 Periods
	SE OUTCOMES:
	completion of this course, the students will be able to:
	: Apply the concepts of wind energy sources for electricity generation
CO2	: Evaluate and analyse the options and estimate the wind energy generation through renewable
	sources
CO3	: Understand the concepts and components of wind energy systems.
CO4	: Understand the modern wind turbine control & monitoring system and evaluate the control
	algorithms
CO5	: Evaluate and analyse the wind resource assessment and R & D costs
	nce Books
	olding E. W., "The Generation of Electricity by Wind farms", E & F.N. Spon Ltd, London.(U.K).
	ohnson, Gary, L. " Wind Energy System ", Prentice Hall Inc . Englewood Cliffs. N.J. (USA)
	reris, L.L." Wind Energy Conversion System" Prentice Hall,(U.K.)
4. He	eier, S, "Grid Integration of Wind Energy Conversion Systems". Wiley, New York (USA)
4. He 5. Ar	eier, S,"Grid Integration of Wind Energy Conversion Systems". Wiley,New York (USA) nna Mani, D. A. Mooley, "Wind Energy Data for India"
4. He 5. Ar 6. C-	eier, S,"Grid Integration of Wind Energy Conversion Systems". Wiley,New York (USA) nna Mani, D. A. Mooley, "Wind Energy Data for India" -WET Wind Energy Resources Survey in India VI
4. He 5. Ar 6. C- 7. Sa	eier, S,"Grid Integration of Wind Energy Conversion Systems". Wiley,New York (USA) nna Mani, D. A. Mooley, "Wind Energy Data for India" -WET Wind Energy Resources Survey in India VI athyajith Mathew, "Wind Energy : Fundamentals, Resource Analysis and Economics", Springer Science
4. He 5. Ar 6. C- 7. Sa & &	eier, S,"Grid Integration of Wind Energy Conversion Systems". Wiley,New York (USA) nna Mani, D. A. Mooley, "Wind Energy Data for India" -WET Wind Energy Resources Survey in India VI

PO	CO Statement	PO1	PO	PO	PO4	PO	PO	PO	PO	PO	PO10	PO1
со			2	3		5	6	7	8	9		1
CO1	Apply the concepts of wind energy sources for electricity generation	3	1	1	1	1	1	1	1	1	1	1
CO2	Evaluate and analyse the options and estimate the wind energy generation through renewable sources	1	З	2	1	2	1	1	1	1	1	1
CO3	Understand the concepts and components of wind energy systems.	2	1	1	3	1	1	1	1	1	1	1
CO4	Understand the modern wind turbine control & monitoring system and evaluate the control algorithms	1	1	1	2	3	1	2	1	1	1	1
CO5	Evaluate and analyse the wind resource assessment and cost economics.	1	1	3	2	1	1	1	1	1	1	1

18PEE	45	POWER ELECTRONICS FOR RENEWABLE ENERGY SYSTEM	L	Т	Р	С
0	<u>.</u>		3	0	0	3
Course (-					
1. 2.		understand the principle of solar and wind energy conversion systems.				
2. 3.		know inverter structures need for solar and wind energy systems. introduce grid integration methods for solar and wind energy systems.				
0.	10					
Unit I		SOLAR PHOTOVOLTAIC SYSTEM	9		+	0
operation I-V Equa	n- I-V tion,	ainable Sun's Energy – Advantages and Conversion Challenges / Equation and characteristics- Solar PV Modules-Design and Structure Power curve and rating-Effect of Solar Irradiation and Temperature- M g-Perturb and Observe algorithm-Incremental conductance algorithms.	e of l	PV n	nodu	le-
Unit II		WIND ENERGY CONVERSION SYSTEM	9		+	0
Power Co	oeffi sync	iple and Components of Wind Energy Conversion System- Power (cient -Self Excited Induction Generator (SEIG) - Theory of self excitation chronous generator (PMSG) - Autonomous Generation Systems we prators.	n –	Per	man	ent
Unit III		FUEL CELL	9		+	0
Proton E	xcha	duction- Types- Commercial and Manufacturing Issues - Construction ange-Membrane Fuel Cells; Advantages and Disadvantages of Fuel C rcuit; Aspects of Hydrogen as Fuel, Introduction to Bloom energy				
Unit V Control s	Gen Gene Gene	PV Inverters- Two-level back-to-back PWM Inverter- Three-level back eric control structure for a PV inverter GRID INTEGRATION OF GREEN ENERGY SYSTEMS eric structure for grid connected PV system- Single stage grid connect ne- Grid Synchronization Techniques for Single-Phase Systems- Grid S	9 ted I Sync	PV s	+ syste	0 em-
		e-Locked Loop-Control structure of WES- Generator Side Control- WE active and reactive power injection by WES.	SG	iria (Jont	roi-
		Total (45+	0)=	45 F	Peric	ods
Course (Outc		-/			
	nple	tion of this course, the students will be able to:				
CO1	·	Know solar, fuel cell and wind energy conversion principles.				
CO2	:	Select suitable power inverters for green energy systems.				
CO3	:	Design wind and solar based power plants.				
CO4	+ +	Design an appropriate system for standalone and grid connected operation	atior	٦.		
CO5	+	Know grid integration challenges with fuel cell, solar and wind energy s				
Text Boo			, 5.0			
1	Chet	tan Singh Solanki, " Solar Photovoltaics: Fundamentals, Tec ications", PHI Learning Private Limited, New Delhi, 2011.	hnol	ogie	s a	ind
2.	Rem Wile	us Teodorescu, "Grid converters for photovoltaic and wind power sys y and Sons Ltd Publication, 2011.				
3.	E.Ac Ltd,	ha and VG Agilidis," Power Electronic Control In Electrical Systems", El Ist Edition, 2006.				Pvt
		A. Farret, M. Godoy Simo` es, Integration of Alternative Sources of En y & Sons, 2006.	ergy	ν, <mark>J</mark> ο	hn	

PQ CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Know solar, fuel cell and wind energy conversion principles.		1			1	3			1	2	
CO2	Select suitable power inverters for green energy systems.	2	3								1	
CO3	Design wind and solar based power plants.			2	1			1	2			1
CO4	Design an appropriate system for standalone and grid connected operation.			2				1	2			1
CO5	Know grid integration challenges with fuel cell, solar and wind energy systems.			1	2					1		

18P	PEE(51	SMART GRID TECHNOLOGY	L	I	Ρ	С
				3	0	0	3
Cours		-	tives:				
1.			duce the concepts of Smart Grid, architecture and Functions.				
2.			arize the role of communications technologies in Smart Grid.				
3.			arize control and automation technologies for Smart Grid.				
4.	10	study	the green energy integration and energy storage systems.				
Unit I		IN	TRODUCTION TO SMART GRID	Ş)	+	0
Defini	ition	s an	d Need for Smart Grid, Today's Electric Grid versus Smart Grid, key asp	ects of	Sm	nart (Grio
devel	opm	nent,	Smart Grid architecture, Functions of Smart Grid Components, challenges ar	nd bene	fits.		
Unit I			OMMUNICATIONS TECHNOLOGIES	ç	<u>,</u>	+	0
			n infrastructure for the Smart Grid, IEEE 802 architecture and, communi	-			
			r IEEE 802, Wireless LANs, ZigBee and 6LoWPAN, ZigBee communication				
	-		er line communication, Standards for smart metering, Modbus, DNP3, IEC 6	1850 da	ata	struc	ture
and u	sag	e.					
Unit I			ONTROL AND AUTOMATION TECHNOLOGIES	g	<u> </u>	.	0
					·	+	
			g: Benefits, Architecture, Key components and operation, communicatio				
smart	m	eterin	g, Demand-side integration (DSI): Definitions and services provided b	ov DSI.	Sι	ubsta	tior
			uinment: architecture, components and functions Intelligent electronic device		ν D	alav	
			uipment: architecture, components and functions, Intelligent electronic device	es (IED)), R	elay	IFL
			upment: architecture, components and functions, Intelligent electronic device s, Bay controller.	es (IED)), R	elay	IEL
		· type	s, Bay controller.	es (IED)), R	elay	IEL
	ther	· type		es (IED)		elay	
and o	ther V	type	s, Bay controller. ERGY STORAGE SYSTEMS)	+	0
and o Unit I	ther V	type	s, Bay controller. ERGY STORAGE SYSTEMS for energy storage in smart grid, Energy storage technologies: operation, f	features) an	+ d us	0 Эо
and o Unit I Flow	ther V N bat	type EN	s, Bay controller. ERGY STORAGE SYSTEMS for energy storage in smart grid, Energy storage technologies: operation, f Fuel cell, Superconducting magnetic energy storage systems, Super	features capaci) an tors	+ d use ; po	l C e o we
and o Unit I Flow conve	ther V N bat	EN EN Leed tery, conf	s, Bay controller. ERGY STORAGE SYSTEMS for energy storage in smart grid, Energy storage technologies: operation, f	features capaci) an tors	+ d use ; po	l C e o we
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CO1	Understand the concepts of Smart Grid and its present developments.			1		1	1	2			3	
CO2	Get acquainted with the smart resources and other smart devices	1							2	1		
CO3	Acquire knowledge of automation and control infrastructure.		1									1
CO4	Select an energy storage system and its integration with Smart Grids	3	1		1							
CO5	Identify suitable communication networks for smart grid applications				1		1				2	

		52 DISTRIBUTED GENERATION	L	1	r	С
			3	0	0	3
C ~ 1	reo (Dbjectives:				
1.		illustrate the concept of distributed generation.				
2.		familiarize with the integration of DG in distribution systems				
Unit	: I	INTRODUCTION		9	+	0
		onal power generation: advantages and disadvantages, Energy crises, Noncor				
		esources: review of Solar PV, Wind Energy systems, Fuel Cells, micro-tur	bine	s, bi	oma	ss,
cog	enera	tionand tidal sources.				
11				0		•
Unit		DISTRIBUTED GENERATION of Distributed Generations (DGs), topologies, selection of sources, regulatory stand	lord	9 /fron	+	0
		s for interconnecting Distributed resources to electric power systems: IEEE 1547				
		security issues in DG implementations. Energy storage elements: Batteries,				
		. Captive power plants.	untre	i cap	aone	13,
Unit		DISTRIBUTED GENERATION PLANNING AND EVALUATION		9	+	0
		of DGs - Types of DG Planning Methods - Sitting and Sizing of DGs Optimal P				
		in Distribution Systems. Technical impacts of DGs - Computer Aided Sizing and S				
		Loss Minimisation and Voltage Profile Improvement. Economic and Control Aspect				
		Evaluation -Basic Cost Analysis – Cost Evaluation and Schedule of Demand – Mo	dellii	ng Ur	ncert	ain
Cos	ts – S	Sensitivity Studies on Key Factors.				
Uni	· IV	IMPACT OF GRID INTEGRATION		9		0
-		nents for grid interconnection, limits on operational parameters: voltage, frequency, T	п.	-		
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		rmal operating conditions, islanding issues. Impact of grid integration with NCE sou		s on	exist	ing
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CO2	Analyse the size and location of distributed generation.	2	3	3	3	2	2	3	2	1	2	2
CO3	Analyse the impact of DGs in distribution system and challenges in grid integration.	2	3	3	2	3	2	2	2	1	3	2
CO4	Understand the distributed power generation protection schemes	3	2	2	1	2	2	2	1	1	1	1
CO5	Analyse the planning and operational issues related to distributed generation.	2	3	3	3	3	3	2	1	1	3	2

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Basic principle of P an Power Flow Controller (Unit V COORDINAT Controller interactions TCSC interaction - Coo techniques – Emerging	d Q control-Independent real and reactive power flow control-Applica IPFC): Basic operation, structure and applications. ION OF FACTS CONTROLLERS SVC-SVC interaction - SVC-HVDC interaction - SVC -TCSC intera	ations-	Interl	ine
Power Flow Controller (Unit V COORDINAT Controller interactions TCSC interaction - Coordinates TCSC interaction - Emerging Emerging	PFC): Basic operation, structure and applications. ION OF FACTS CONTROLLERS SVC-SVC interaction - SVC-HVDC interaction - SVC -TCSC intera	9 action -	+	
Unit V COORDINAT Controller interactions TCSC interaction - Coo techniques – Emerging	ION OF FACTS CONTROLLERS • SVC-SVC interaction - SVC-HVDC interaction - SVC -TCSC intera	action -	+ • TCS	
Controller interactions TCSC interaction - Coo techniques – Emerging	SVC-SVC interaction - SVC-HVDC interaction - SVC -TCSC intera	action -	+ • TCS	-
	FACTS Controllers: The STATCOM - The SSSC - The UPFC	n-lineai - Com	r con parat	trol
Course Outeensee	Total (L+1	T)= 45	Peric	ds
Course Outcomes:				
Upon completion of this	course, the students will be able to:			
CO1 : Remember k	nowledge about reactive power flow control in power systems.			
	arious static series and shunt compensation techniques.			
	tructure and principle of operation of FACTS devices.			
	CTS devices at suitable location in power system networks.			
	he co-ordination of FACTS controllers.			
Text Books:				
	Gyugyi, "Understanding FACTS: Concepts and Technology of Flexible A ems", IEEE Press Book, Standard Publishers and Distributors, Delhi, 20			
, K.R. Padiyar, "FA	CTS Controllers in Power Transmission and Distribution", New Age		natio	nal
N	erard Ledwich, "Power Quality Enhancement using Custom Power Dev	vices", S	Spring	ger
Science, 2002.				
Reference Books:	htanz R Dal "Elevible AC Transmission Systems Modelling and Car	ntrol"	Sprin	<u></u>
Verlag, Berlin, 200				yer
2. R. Mohan Mathur Systems", IEEE pr	, Rajiv K Verma, "Thyrisor-Based FACTS Controllers for Electrical	l Trans	smiss	

PO CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Remember knowledge about reactive power flow control in power systems.	2	3	1	1	1	1	3	1	2	1	1
CO2	Understand various static series and shunt compensation techniques.	2	1	3	3	1	1	3	1	1	2	1
CO3	Analyze the structure and principle of operation of FACTS devices.	1	1	2	2	2	3	1	1	1	3	1
CO4	Apply the FACTS devices at suitable location in power system networks.	2	3	2	3	3	1	2	2	1	2	2
CO5	Understand the co- ordination of FACTS controllers.	2	1	3	2	1	1	2	3	1	2	1

18	BPE	E54	HVDC TRANSMISSION SYSTEMS	L	Т	Ρ	C
				3	0	0	3
Cour	se C	Objective	S:				
1.			nd the concept, planning of DC power transmission and comparison with	AC		ро	wer
	trar	nsmissior	l.			•	
2.	То	analyze ł	HVDC converters.				
3.	То	study abo	but the HVDC system control.				
4.	То	design ha	armonics filters.				
5.	То	impart kr	owledge on simulation of HVDC systems.				
							1
Unit I			PMENT OF HVDC TECHNOLOGY	9	_	+	0
config	jura	tions and	nparison of AC and DC transmission – Applications of DC transmission – components – Planning for HVDC transmission – Modern trends in DC trans otential applications, Types – control and protection – study of MTDC System	smis			tem
11	. 1			•			•
Unit I			SIS OF HVDC CONVERTERS	9		+	0
and w	/ith (overlap le	hoice of best topology for HVDC – Analysis of six pulse bridge converter vess than 60° - Equivalent circuit model - Abnormal operation: Arcback, Comr e - Converter bridge characteristics - Multiple bridge converters.				
110:41		CONT	ROL OF HVDC SYSTEMS	0			•
Unit I			of control – Desired features of control – Limitations of manual c	9	<u></u>	+	
			ierarchy of different levels of HVDC system controls – Converter firing cor				
			bypassing – Starting, stopping and power flow reversal – Controls for enha				
	m p		ce – Higher level controllers -Fault development and protection-Function				
Unit I	v	REACT	IVE POWER CONTROL. HARMONICS AND FILTERS	9		+	0
Introd Defini	tive ucti tion	Power re on – Cha s of wave	TIVE POWER CONTROL, HARMONICS AND FILTERS quirements in steady state – sources of reactive power – static VAR systems aracteristic harmonics – noncharacteristic harmonics – Troubles caused b distortion or ripple – Means of reducing harmonics – Telephone interferen- ed AC filters – DC side harmonics.	by h			
React Introd Defini minim	tive luction tion	Power re on – Cha s of wave cost tune	quirements in steady state – sources of reactive power – static VAR systems aracteristic harmonics – noncharacteristic harmonics – Troubles caused b e distortion or ripple – Means of reducing harmonics – Telephone interferen ed AC filters – DC side harmonics.	s. by h nce -		onic	s – n of
React Introd Defini minim	tive luction num	Power re on – Cha s of wave cost tune	quirements in steady state – sources of reactive power – static VAR systems aracteristic harmonics – noncharacteristic harmonics – Troubles caused b e distortion or ripple – Means of reducing harmonics – Telephone interferen ed AC filters – DC side harmonics.	s. by h nce -	- De	onic esigi +	:s – n of 0
React Introd Defini minim Unit Mode stabili	tive luction num /	Power re on – Cha s of wave cost tune SIMULA g of HVD studies.Sy	quirements in steady state – sources of reactive power – static VAR systems aracteristic harmonics – noncharacteristic harmonics – Troubles caused b e distortion or ripple – Means of reducing harmonics – Telephone interferen ed AC filters – DC side harmonics.	s. by h nce - 9 prese	- De	onic esigi + tion	s – n of 0 for
React Introd Defini minim Unit Mode stabili	tive luction num /	Power re on – Cha s of wave cost tune SIMULA g of HVD studies.Sy	quirements in steady state – sources of reactive power – static VAR systems aracteristic harmonics – noncharacteristic harmonics – Troubles caused b e distortion or ripple – Means of reducing harmonics – Telephone interferent ed AC filters – DC side harmonics. TION OF HVDC SYSTEMS C systems, per unit system, Representation for power flow solution, representation: Philosophy and tools – HVDC system simulation – Mod dynamic simulation	s. by hance - 9 prese ellin	- De enta g of	onic esigi tion HV	n of 0 for /DC
React Introd Defini minim Unit Mode stabili system	tive tion tion tum lling ty s ms f	Power re on – Cha s of wave cost tune SIMULA g of HVD studies.Sy for digital	quirements in steady state – sources of reactive power – static VAR systems aracteristic harmonics – noncharacteristic harmonics – Troubles caused b e distortion or ripple – Means of reducing harmonics – Telephone interferent ed AC filters – DC side harmonics. TION OF HVDC SYSTEMS C systems, per unit system, Representation for power flow solution, representation: Philosophy and tools – HVDC system simulation – Mod dynamic simulation Total (L-	s. by hance - 9 prese ellin	- De enta g of	onic esigi tion HV	n of 0 for /DC
React Introd Defini minim Unit V Mode stabili system Cour	tive luction num / Iling ity s ms f	Power re on – Cha s of wave cost tune SIMULA of HVD tudies.Sy for digital	quirements in steady state – sources of reactive power – static VAR systems aracteristic harmonics – noncharacteristic harmonics – Troubles caused b e distortion or ripple – Means of reducing harmonics – Telephone interferent ed AC filters – DC side harmonics. TION OF HVDC SYSTEMS C systems, per unit system, Representation for power flow solution, representation: Philosophy and tools – HVDC system simulation – Mod dynamic simulation Total (L-	s. by hance - 9 prese ellin	- De enta g of	onic esigi tion HV	n of 0 for /DC
React Introd Defini minim Unit V Mode stabili system Cour	tive luction num / Iling ity s ms f	Power re on – Cha s of wave cost tune SIMULA of HVD studies.Sy for digital Dutcomes npletion c	quirements in steady state – sources of reactive power – static VAR systems aracteristic harmonics – noncharacteristic harmonics – Troubles caused b e distortion or ripple – Means of reducing harmonics – Telephone interferent ed AC filters – DC side harmonics. TION OF HVDC SYSTEMS C systems, per unit system, Representation for power flow solution, represent simulation: Philosophy and tools – HVDC system simulation – Mod dynamic simulation Total (L- s:	s. by hance - 9 prese ellin	- De enta g of	onic esigi tion HV	n of 0 for /DC
React Introd Defini minim Unit Mode stabili system Cour Upon	tive luction num / Iling ity s ms f	Power re on – Cha s of wave cost tune SIMULA of HVD tudies.Sy for digital Dutcomes npletion c	quirements in steady state – sources of reactive power – static VAR systems aracteristic harmonics – noncharacteristic harmonics – Troubles caused to a distortion or ripple – Means of reducing harmonics – Telephone interferent ad AC filters – DC side harmonics. TION OF HVDC SYSTEMS C systems, per unit system, Representation for power flow solution, represent simulation: Philosophy and tools – HVDC system simulation – Mod dynamic simulation Total (L- s: f this course, the students will be able to:	s. by hance - 9 prese ellin	- De enta g of	onic esigi tion HV	n of 0 for /DC
React Introd Defini minim Unit Mode stabili syste Cours Upon CO1	tive luction num / Iling ity s ms f	Power re on – Cha s of wave cost tune SIMULA of HVD studies.Sy for digital Dutcomes npletion c <i>Underst</i> <i>Explain</i>	quirements in steady state – sources of reactive power – static VAR systems aracteristic harmonics – noncharacteristic harmonics – Troubles caused be distortion or ripple – Means of reducing harmonics – Telephone interferent ed AC filters – DC side harmonics. TION OF HVDC SYSTEMS C systems, per unit system, Representation for power flow solution, represent simulation: Philosophy and tools – HVDC system simulation – Mod dynamic simulation Total (L- s: f this course, the students will be able to: and the concept of HVDC technology	s. by hance - 9 prese ellin	- De enta g of	onic esigi tion HV	n of 0 for /DC
React Introd Defini minim Unit V Mode stabili system Cour Upon CO1 CO2	tive luction num / Iling ity s ms f	Power re on – Cha s of wave cost tune SIMULA of HVD studies.Sy for digital Dutcomes npletion c <i>Underst</i> <i>Explain</i> <i>Analyze</i>	quirements in steady state – sources of reactive power – static VAR systems aracteristic harmonics – noncharacteristic harmonics – Troubles caused be distortion or ripple – Means of reducing harmonics – Telephone interferent ed AC filters – DC side harmonics. TION OF HVDC SYSTEMS C systems, per unit system, Representation for power flow solution, represent simulation: Philosophy and tools – HVDC system simulation – Mod dynamic simulation Total (L- s: f this course, the students will be able to: and the concept of HVDC technology the basic concepts of HVDC and MTDC systems.	s. by hance - 9 prese ellin	- De enta g of	onic esigi tion HV	n of 0 for /DC
React Introd Defini minim Unit V Mode stabili system Cour Upon CO1 CO2 CO3	tive luction num / Iling ity s ms f	Power re on – Cha s of wave cost tune SIMULA of HVD studies.Sy for digital Dutcomes npletion c <i>Understa</i> <i>Explain</i> <i>Analyze</i> <i>Design</i> of	quirements in steady state – sources of reactive power – static VAR systems aracteristic harmonics – noncharacteristic harmonics – Troubles caused be distortion or ripple – Means of reducing harmonics – Telephone interferent ed AC filters – DC side harmonics. TION OF HVDC SYSTEMS C systems, per unit system, Representation for power flow solution, represent simulation: Philosophy and tools – HVDC system simulation – Mod dynamic simulation Total (L- S: If this course, the students will be able to: and the concept of HVDC technology the basic concepts of HVDC and MTDC systems. and control six-pulse and multiple-bridge converters	s. by hance - 9 prese ellin	- De enta g of	onic esigi tion HV	n of 0 for /DC
React Introd Defini minim Unit V Mode stabili system Cours Upon CO1 CO2 CO3 CO4	tive luction num / Iling ity s ms f	Power re on – Cha s of wave cost tune SIMULA studies.Sy for digital Dutcomes Dutcomes Explain Analyze Design o Work wi	quirements in steady state – sources of reactive power – static VAR systems aracteristic harmonics – noncharacteristic harmonics – Troubles caused be distortion or ripple – Means of reducing harmonics – Telephone interferent ed AC filters – DC side harmonics. TION OF HVDC SYSTEMS C systems, per unit system, Representation for power flow solution, represent simulation: Philosophy and tools – HVDC system simulation – Mod dynamic simulation Total (L- s: If this course, the students will be able to: and the concept of HVDC technology the basic concepts of HVDC and MTDC systems. and control six-pulse and multiple-bridge converters of harmonics filters.	s. by hance - 9 prese ellin	- De enta g of	onic esigi tion HV	n of 0 for /DC
Reac Introd Defini minim Mode stabili system Cours Upon CO1 CO2 CO3 CO4 CO5 CO6	tive luctive tition num / / Illing ty s ms f se C con : : : : : : : : : : : : : : : :	Power re on – Cha s of wave cost tune SIMULA of HVD studies.Sy for digital Dutcomes npletion c <i>Underst</i> <i>Explain</i> <i>Analyze</i> <i>Design o</i> <i>Work wi</i>	quirements in steady state – sources of reactive power – static VAR systems aracteristic harmonics – noncharacteristic harmonics – Troubles caused be distortion or ripple – Means of reducing harmonics – Telephone interferent ed AC filters – DC side harmonics. TION OF HVDC SYSTEMS C systems, per unit system, Representation for power flow solution, represent simulation: Philosophy and tools – HVDC system simulation – Mod dynamic simulation Total (L- s: If this course, the students will be able to: and the concept of HVDC technology the basic concepts of HVDC and MTDC systems. and control six-pulse and multiple-bridge converters of harmonics filters. th the modelling of HVDC systems	s. by hance - 9 prese ellin	- De enta g of	onic esigi tion HV	n of 0 for /DC
Reac Introd Defini minim Mode stabili system Cours Upon CO1 CO2 CO3 CO4 CO5 CO6 Text	tive luctive tion num / / Illing ty s ms f se C con : : : : : : : : : : : : : : : : : : :	Power re on – Cha s of wave cost tune SIMULA of HVD studies.Sy for digital Dutcomes npletion of Underst Explain Analyze Design of Work wi Apply si	quirements in steady state – sources of reactive power – static VAR systems aracteristic harmonics – noncharacteristic harmonics – Troubles caused b a distortion or ripple – Means of reducing harmonics – Telephone interferent ad AC filters – DC side harmonics. TION OF HVDC SYSTEMS C systems, per unit system, Representation for power flow solution, represent simulation: Philosophy and tools – HVDC system simulation – Mod dynamic simulation Total (L- 5: If this course, the students will be able to: and the concept of HVDC technology the basic concepts of HVDC and MTDC systems. and control six-pulse and multiple-bridge converters of harmonics filters. th the modelling of HVDC systems mulation tools for HVDC system	3. by h nce - 9 prese ellin •T)=	- Deenta g of 45F	onic esign tion HV	is – n of for /DC
Reac Introd Defini minim Unit V Mode stabili syste Syste Upon CO1 CO2 CO3 CO4 CO5 CO6 Text	tive luctive tion hum / Illing ty s ms f se C con : : : : : : : : : : : : : : : : : : :	Power re on – Cha s of wave cost tune SIMULA of HVD studies.Sy for digital Dutcomes npletion c <i>Understi</i> <i>Explain</i> <i>Analyze</i> <i>Design o</i> <i>Work wi</i> <i>Apply si</i> iyar, K.R	quirements in steady state – sources of reactive power – static VAR systems aracteristic harmonics – noncharacteristic harmonics – Troubles caused be distortion or ripple – Means of reducing harmonics – Telephone interferent ed AC filters – DC side harmonics. TION OF HVDC SYSTEMS C systems, per unit system, Representation for power flow solution, represent simulation: Philosophy and tools – HVDC system simulation – Mod dynamic simulation Total (L- s: If this course, the students will be able to: and the concept of HVDC technology the basic concepts of HVDC and MTDC systems. and control six-pulse and multiple-bridge converters of harmonics filters. th the modelling of HVDC systems	3. by h nce - 9 prese ellin •T)=	- Deenta g of 45F	onic esign tion HV	is – n of for /DC
Reac Introd Defini minim Unit V Mode stabili syste Syste Upon CO1 CO2 CO3 CO4 CO5 CO6 Text	tive luction hum / Illing ty s ms f se C con : : : : : : : : : : : : : : : : : : :	Power re on – Cha s of wave cost tune SIMULA of HVD studies.Sy for digital Dutcomes npletion of <i>Understa</i> <i>Explain</i> <i>Analyze</i> <i>Design of</i> <i>Work wi</i> <i>Apply si</i> iyar, K.R 0.	quirements in steady state – sources of reactive power – static VAR systems aracteristic harmonics – noncharacteristic harmonics – Troubles caused b a distortion or ripple – Means of reducing harmonics – Telephone interferent ad AC filters – DC side harmonics. TION OF HVDC SYSTEMS C systems, per unit system, Representation for power flow solution, represent simulation: Philosophy and tools – HVDC system simulation – Mod dynamic simulation Total (L- 5: If this course, the students will be able to: and the concept of HVDC technology the basic concepts of HVDC and MTDC systems. and control six-pulse and multiple-bridge converters of harmonics filters. th the modelling of HVDC systems mulation tools for HVDC system	3. by h nce - 9 prese ellin •T)=	- Deenta g of 45F	onic esign tion HV	is – n of for /DC

Colin Adamson and N.G.Hingorani, "High Voltage Direct current Power Transmission", Garraway 1. Limited, London, First edition, 1960.

- Edward Wilson Kimbark, "Direct Current Transmission", Vol.I, Wiley Interscience, New York, 1971. 2.
- 3.

Erich Uhlmann, "Power Transmission by Direct Current", B.S. Publications, 2004. Kamakshaiah, S. & Kamaraju, V, "HVDC Transmission", 1st Edition, Tata McGraw Hill, 2011. 4.

	CO Statement	PO1	PO	PO	PO4	PO	PO	PO	PO	PO	PO1	PO1
PO			2	3		5	6	7	8	9	0	1
со												
CO1	Understand the concept of HVDC technology	3	1	2	3	2	1				2	1
CO2	Explain the basic concepts of HVDC and MTDC systems.	3	2	3	3	1	1	1	1	1	2	1
CO3	Analyze and control six- pulse and multiple-bridge converters	3	2	3	1	1					1	
CO4	Design of harmonics filters	2	2	3	3	2	1	1	1	1	2	1
CO5	Work with the modelling of HVDC systems	2	3	2	2	1	1	2	1	1	1	1
CO6	Apply simulation tools for HVDC system	1	2	2	3	3	1	2	1	1	2	2

Corr	186	PEE55	SCADA SYSTEMS AND APPLICATIONS	LT	Ρ	С
C ~ · ·				3 0	0	3
500		Objectives				
1.			d about the SCADA system components and SCADA communication protoc	cols.		
2.	10	o provide kn	nowledge about SCADA applications in power system.			
Unit	t I	INTRODU	CTION TO SCADA	9	+	0
-	-		DA, SCADA definitions, SCADA Functional requirements and Compo	nents,	SCA	DĂ
Hier	arch	ical concep	t, SCADA architecture, General features, SCADA Applications, Benefits.			
Unit	• 11	SCADA	SYSTEM COMPONENTS	9	+	0
			Unit (RTU), Interface units, Human- Machine Interface Units (HM		-	-
			er Systems, Intelligent Electronic Devices (IED), Communication Network,			
SCA	ADA (Control sys	tems and Control panels.			
Unit		SCADA	COMMUNICATION	9	· .	0
			ation requirements, Communication protocols: Past, Present and Future,	•	+	-
			cations Protocol, Comparison of various communication protocols, IE			
com	mun	ication arc	hitecture, Communication media like Fiber optic, PLCC etc. Interface			
com	mun	ication exte	ensions, synchronization with NCC, DCC.			
11	. 117	MONITO	DRING AND CONTROL	9		•
Unit			pritoring the event and alarm system, trends and reports, Blocking list, Eve	-	+ urbar	0
			unction: Station control, bay control, breaker control and disconnector control		uibai	100
			ing Systems (WAMS), Phasor Measurement Unit (PMU), A generic PM		e glo	bal
posi	tioni	ng system -	- Hierarchy for phasor measurement systems – Functional requirements, PN	/U plac	emer	nt.
					_	-
Unit			APPLICATIONS	9	+	0
			neration, Transmission and Distribution sector, Substation SCADA system specification, System selection such as Substation configuration,			
			cubicle concepts, gateway interoperability list, signal naming concept. Syst			
		and Commi				,
		TUDIES				
618	50 ba		CADA Design for 66/11KV and 132/66/11KV or 132/66 KV any utility Subs	station a	and I	EC
				station a	and I	EC
			CADA Design for 66/11KV and 132/66/11KV or 132/66 KV any utility Subs DA Implementation issues in utility Substations.			
Сои	Irse		CADA Design for 66/11KV and 132/66/11KV or 132/66 KV any utility Subs DA Implementation issues in utility Substations. Total (L+			
		ased SCAD	CADA Design for 66/11KV and 132/66/11KV or 132/66 KV any utility Subs DA Implementation issues in utility Substations. Total (L+ :			
Upo	on co	ased SCAD Outcomes: mpletion of	CADA Design for 66/11KV and 132/66/11KV or 132/66 KV any utility Subs DA Implementation issues in utility Substations. Total (L+ : this course, the students will be able to:	T)= 45	Perio	ods
	on co	Outcomes: mpletion of Describe	CADA Design for 66/11KV and 132/66/11KV or 132/66 KV any utility Subs DA Implementation issues in utility Substations. Total (L+ : : : : : : : : : : : : :	T)= 45	Perio	ods
Upo CO	on co 1 :	Outcomes: mpletion of Describe applicatio	CADA Design for 66/11KV and 132/66/11KV or 132/66 KV any utility Subs DA Implementation issues in utility Substations. Total (L+ : : : : : : : : : : : : :	T)= 45 as their	Perio	ods ical
Upo CO CO2	on co 1 : 2 :	Describe application Acquire H system.	CADA Design for 66/11KV and 132/66/11KV or 132/66 KV any utility Subs DA Implementation issues in utility Substations. Total (L+ : : : : : : : : : : : : : : : : : : :	T)= 45 as their	Perio	ods ical
Upo CO CO2 CO3	on co. 1 : 2 : 3 :	Ased SCAD Outcomes: mpletion of Describe applicatio Acquire H system. Knowledg	CADA Design for 66/11KV and 132/66/11KV or 132/66 KV any utility Subs DA Implementation issues in utility Substations. Total (L+ : : : : : : : : : : : : : : : : : : :	T)= 45 as their ntages	Perio	ods ical ach
Upo CO CO2	on co. 1 : 2 : 3 :	ased SCAD Outcomes: mpletion of Describe applicatio Acquire I system. Knowledg To learn	CADA Design for 66/11KV and 132/66/11KV or 132/66 KV any utility Subs DA Implementation issues in utility Substations. Total (L+ : : : : : : : : : : : : : : : : : : :	T)= 45 as their ntages	Perio	ods ical ach
Upc CO ² CO2 CO2	on co. 1 : 2 : 3 : 4 :	ased SCAD Outcomes: mpletion of Describe applicatio Acquire H system. Knowledg To learn devices, H	CADA Design for 66/11KV and 132/66/11KV or 132/66 KV any utility Subs DA Implementation issues in utility Substations. Total (L+ : : : : : : : : : : : : : : : : : : :	T)= 45 as their ntages igent er	Perio	ical ach
Upc CO ² CO2 CO2	on co. 1 : 2 : 3 : 4 :	ased SCAD Outcomes: mpletion of Describe applicatio Acquire H system. Knowledg To learn devices, H	CADA Design for 66/11KV and 132/66/11KV or 132/66 KV any utility Subs DA Implementation issues in utility Substations. Total (L+ : : : : : : : : : : : : : : : : : : :	T)= 45 as their ntages igent er	Perio	ical ach
Upo <u> CO</u> <u> CO</u> <u> CO</u> <u> CO</u>	on co. 1 : 2 : 3 : 4 : 5 :	Outcomes: mpletion of Describe applicatio Acquire H system. Knowledg To learn devices, H Learn and	CADA Design for 66/11KV and 132/66/11KV or 132/66 KV any utility Subs DA Implementation issues in utility Substations. Total (L+ : : : : : : : : : : : : : : : : : : :	T)= 45 as their ntages igent er	Perio	ical ach
Upo <u> CO</u> <u> CO</u> <u> CO</u> <u> CO</u>	on co. 1 : 2 : 3 : 4 : 5 : erene SC.	Ased SCAD Outcomes: mpletion of Describe applicatio Acquire H system. Knowledg To learn devices, H Learn and etc. CE Books: ADA-Super	CADA Design for 66/11KV and 132/66/11KV or 132/66 KV any utility Subs DA Implementation issues in utility Substations. Total (L+ : : : : : : : : : : : : : : : : : : :	T)= 45 as their ntages igent er sector,in	Perio	ical ical nic
Upc CO2 CO2 CO2 CO2 CO2 Refe 1.	on co. 1 : 2 : 3 : 4 : 5 : erene SC. Pul	Ased SCAD Outcomes: mpletion of Describe application Acquire H system. Knowledg To learn devices, H Learn and etc. Ce Books: ADA-Super blications, U	CADA Design for 66/11KV and 132/66/11KV or 132/66 KV any utility Subs DA Implementation issues in utility Substations. Total (L+ : : : : : : : : : : : : : : : : : : :	T)= 45 as their ntages igent er ector, in ety of ,	Perio of ea lectro dustr	ical ach nic ries
Upo CO2 CO2 CO2 CO2 Refe	on co. 1 : 2 : 3 : 4 : 5 : erenc SC. Pul Pra	Ased SCAD Outcomes: mpletion of Describe application Acquire H system. Knowledg To learn devices, H Learn and etc. CE Books: ADA-Super blications, U actical Mod	CADA Design for 66/11KV and 132/66/11KV or 132/66 KV any utility Subs DA Implementation issues in utility Substations. Total (L+ : : : this course, the students will be able to: the basic tasks of Supervisory Control Systems (SCADA) as well a ons. knowledge about SCADA architecture, various advantages and disadvar ge about single unified standard architecture IEC 61850. about SCADA system components: remote terminal units, PLCs, intelli HMI systems. d understand about SCADA applications in transmission and distribution s rvisory Control and Data Acquisition, Stuart A. Boyer, Instrument Socie ISA. item SCADA Protocols: DNP3, 60870.5 and Related Systems, Gordor	T)= 45 as their ntages igent er ector, in ety of ,	Perio of ea lectro dustr	ical ach nic ries
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Upc CO ² CO ² CO ² CO ² CO ² 7 CO ² CO ² 2. 3.	n co. 1 : 2 : 3 : 4 : 5 : 901 901 Pra Rej Cyl	Assed SCAD Outcomes: mpletion of Describe application Acquire H system. Knowledg To learn devices, H Learn and etc. CE Books: ADA-Super blications, U actical Mod ynders, New bersecurity	CADA Design for 66/11KV and 132/66/11KV or 132/66 KV any utility Subs A Implementation issues in utility Substations. Total (L+ : : : : : : : : : : : : :	T)= 45 as their ntages igent er ector, in ety of ,	Perio of ea lectro dustr	ods ical ach nic ries
Upc CO ² CO	n co. 1 : 2 : 3 : 4 : 5 : eren SC. Pul Pra Rey Cyl Pra	Assed SCAD Outcomes: mpletion of Describe application Acquire H system. Knowledg To learn devices, H Learn and etc. CE Books: ADA-Super blications, U actical Mod ynders, New bersecurity actical SCAI	CADA Design for 66/11KV and 132/66/11KV or 132/66 KV any utility Subs DA Implementation issues in utility Substations. Total (L+ : : : this course, the students will be able to: : the basic tasks of Supervisory Control Systems (SCADA) as well a ons. knowledge about SCADA architecture, various advantages and disadvar ge about single unified standard architecture IEC 61850. about SCADA system components: remote terminal units, PLCs, intelli HMI systems. d understand about SCADA applications in transmission and distribution s rvisory Control and Data Acquisition, Stuart A. Boyer, Instrument Socie ISA. lern SCADA Protocols: DNP3, 60870.5 and Related Systems, Gordor wnes Publications, Oxford, UK.	T)= 45 as their ntages igent er ector,in ety of , n Clark	Perio of ea lectro dustr	ical ach nic ries
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PO CO	CO Statement	PO1	PO 2	PO 3	PO4	PO 5	PO 6	PO 7	PO 8	PO 9	PO10	PO1 1
CO1	Describe the basic tasks of Supervisory Control Systems (SCADA) as well as their typical applications.	1	1	1	1	1	1	3	1	1	1	1
CO2	Acquire knowledge about SCADA architecture, various advantages and disadvantages of each system.	1	1	З	3	1	1	3	1	1	2	1
CO3	Knowledge about single unified standard architecture IEC 61850.	1	1	2	2	2	1	1	1	1	3	1
CO4	To learn about SCADA system components: remote terminal units, PLCs, intelligent electronic devices, HMI systems.	2	3	2	3	3	1	2	2	1	2	2
CO5	Learn and understand about SCADA applications in transmission and distribution sector, industries etc.	2	2	3	3	3	1	2	3	1	2	2

18	BPEE61	ELECTRICAL VEHICLES	L	т	Ρ	С
			3	0	0	3
Course	e Objectives:					
1.	To understand	the concept of electrical vehicles and its operations				
		the need for energy storage in hybrid vehicles				
		wledge about various possible energy storage technologies that can be				
l	Jsed in electri	c vehicles				
					r	
Unit I				9	+	0
	,	V), Hybrid Electric Vehicles (HEV), Engine ratings, Comparisons of E	EV w	vith	inter	nal
combu	stion Engine v	ehicles, Fundamentals of vehicle mechanics.				
Unit II	ARCHITE	CTURE		9	+	0
		and HEV's – Plug-n Hybrid Electric Vehicles (PHEV) - Power train of	omp	-	-	-
		es, Transmission and Brakes.				
oizirig,						
					1	_
Unit III				9	+	0
	chopper bas	ed four quadrant operations of DC drives - Inverter based V/f Operatio	n (m	οιοι	ing a	
Unit IV				9	+	0
Battery	/ Basics, Diffe	ent types, Battery Parameters, Battery modeling, Traction Batteries				
Unit V	FUEL CEI	L	[9	+	0
Fuel ce		istics- Types – hydrogen Storage Systems and Fuel cell EV – Ultra capac	itors	-	1	-
	• •	Total (L-	⊦T)= ⁄	45 F	Perio	bds
	e Outcomes:	Providence de la completa de la comp				
		his course, the students will be able to: ber the fundamentals of electric vehicle and its mechanics				
<u>CO1</u>						
CO2		and the architecture of electric and hybrid electric vehicle.	drive			
<u>CO3</u>		the four quandrant operation of DC drive, induction motor drive and SRM	anve	<i>;.</i>		
CO4		ad analyse the basic battery concepts and modeling.				
CO5		and the concepts of fuel cell				
	ence Books:	wid Vakielee, Deelen Fundementele" Iskel Usersie ODO Deves Terley () Г			
G	roup, Second	/brid Vehicles: Design Fundamentals",Iqbal Hussain, CRC Press, Taylor & Edition (2011).				
2. "\	/ehicular Elec	tric Power Systems", Ali Emadi, Mehrdad Ehsani, John M.Miller, Specia	l Ind	ian	Editi	on
	larcel dekker,					
						-

PO CO	CO Statement	PO1	PO 2	PO 3	PO4	PO 5	PO 6	PO 7	PO 8	PO 9	PO10	PO1 1
CO1	Remember the fundamentals of electric vehicle and its mechanics	3	1	2	1	1		1	1		1	1
CO2	Understand the architecture of electric and hybrid electric vehicle.	1	1	3	2	2		2			2	
CO3	Analyse the four quandrant operation of DC drive, induction motor drive and SRM drive.	1	1	2	3	2		1	1	1	3	
CO4	Apply and analyse the basic battery concepts and modeling.	2	3	3	1	1		1	2		1	2
CO5	Understand the concepts of fuel cell	2	1	1	1	2		1	3		1	1

18	PEE62		Theory A	AND	DESIG	N OF 3	SMPS			L	Т	Ρ	С
										3	0	0	3
	Objectives:												
	know operatio												
	analyze and d												
	design require												
4. To	select proper	component	s and sche	eme p	protectio	on circ	uits						
													1
	DESIGN OF N										9	+	0
	es, General De	esign Metho	od, Design	of Bu	uck Cor	verter	r, Boos	st Conv	verter,	Buck	k/Boos	st Co	nverte
Charge P	umps												
											-	-	-
Unit II	DESIGN OF			-		-					9	+	0
	f Fly-back Co	nverter, Fo	orward Co	nvert	er, Pus	sh-Pull	Conv	/erter,	Half I	Bridge	e and	Full	Bridg
Converte	rs												
												-	
Unit III	CONTROL			:4 -		a a t' a c	<u> </u>			0	9	+	
	ontrol Circuits,												
	Compensated		rol, voltage	e tee	а-раск	circuit	, IC Co	ontrol IN	lodule	e, ryp	Dical F	200 IVI	Contr
wodule,	FL494, SG152	4											
11											•	r –	•
Unit IV	DESIGN OF			NIS							9	+	0
Magnetic			· · · · · · · · · · · · · · · · · · ·	(.			<u> </u>						
•	• •	nauctor a	esign, Tra	nsfor	rmer D	esign	for	Fly-bac	:k, Fo	orwar	d an	d Pu	ush-Pu
•	• •	nauctor a	esign, Tra	Insfor	rmer D	esign	for	Fly-bac	k, Fo	orwar	d an	d Pu	ush-Pi
converter	S					0	for	Fly-bac	∶k, Fo	orwar	1	d Pu	
converter Unit V	SELECTION	OF PERIP	HERAL CO	OMP	ONENT	-s		-			9	+	0
converter Unit V Fixed Re	s SELECTION sistor, Capaci	OF PERIP itors, EMI	HERAL CO	OMP	ONENT	-s		-			9	+	0
converter Unit V Fixed Re	SELECTION	OF PERIP itors, EMI	HERAL CO	OMP	ONENT	-s		-			9	+	0
converter Unit V Fixed Re	s SELECTION sistor, Capaci	OF PERIP itors, EMI	HERAL CO	OMP	ONENT	-s		-	supp	presso	9 ors, C	+ Opto-o	0 Couple
converter Unit V Fixed Re Power Sv	s SELECTION sistor, Capaci vitches, Protec	OF PERIP itors, EMI	HERAL CO	OMP	ONENT	-s		-	supp	presso	9 ors, C	+ Opto-o	0
Converter Unit V Fixed Re Power Sv Course C	SELECTION sistor, Capaci vitches, Protec Dutcomes:	OF PERIP itors, EMI ction eleme	HERAL CO Filter, Inpu nts	OMP It and	ONENT d Outpu	S ut rect		-	supp	presso	9 ors, C	+ Opto-o	0 Couple
Converter Unit V Fixed Re Power Sv Course C	s SELECTION sistor, Capaci vitches, Protec	OF PERIP itors, EMI ction eleme	HERAL CO Filter, Inpu nts	OMP It and	ONENT d Outpu	S ut rect		-	supp	presso	9 ors, C	+ Opto-o	0 Couple
Converter Unit V Fixed Re Power Sv Course C Upon cor	SELECTION sistor, Capaci vitches, Protec Dutcomes: npletion of this	OF PERIP itors, EMI ction eleme	HERAL Co Filter, Inpu nts e students	OMP It and will t	ONENT d Outpu	TS ut rect to:	ifier, \	-	supp	presso	9 ors, C	+ Opto-o	0 Couple
Converter Unit V Fixed Re Power Sv Course C Upon cor CO1 :	SELECTION sistor, Capaci vitches, Protec Dutcomes: npletion of this Implement de	OF PERIP itors, EMI ction eleme s course, th esign conce	HERAL Co Filter, Inpunts e students	OMP It and will k	ONENT d Outpu be able e the co	to:	ifier, \	-	supp	presso	9 ors, C	+ Opto-o	0 Couple
Converter Unit V Fixed Re Power Sv Course C Upon cor CO1 : CO2 :	SELECTION sistor, Capaci vitches, Protec Dutcomes: npletion of this Implement de Select the ap	OF PERIP itors, EMI ction eleme course, th esign conce	HERAL CO Filter, Inpunts e students epts and ar ontrol strat	OMP it and will <i>k</i> nalyze tegy a	ONENT d Outpu be able e the co	to:	ifier, \	-	supp	presso	9 ors, C	+ Opto-o	0 Couple
Converter Unit V Fixed Re Power Sv Course C Upon cor CO1 : CO2 : CO3 :	SELECTION sistor, Capaci vitches, Protec Dutcomes: npletion of this Implement de Select the ap Select the ap	OF PERIP tors, EMI ction eleme course, th esign conce propriate c propriate p	HERAL Co Filter, Inpunts e students epts and an ontrol strat	OMP It and will the malyze tegy a ces	ONENT d Outpu be able e the co	to:	ifier, \ ers ht	-	supp	presso	9 ors, C	+ Opto-o	0 Couple
Converter Unit V Fixed Re Power Sv Course C Upon cor CO1 : CO2 : CO3 : CO3 :	SELECTION sistor, Capaci vitches, Protect Dutcomes: npletion of this Implement de Select the ap Select the ap Design the m	OF PERIP tors, EMI ction eleme course, th esign conce propriate p pagnetic co	HERAL Co Filter, Inpunts e students epts and ar ontrol strat ower device mponents	OMP It and will the malyze tegy a ces based	ONENT d Outpu be able e the co and imp d on rec	to: ponverte	ifier, \ ers nt	/oltage	supp T	oresso	9 ors, C L+T)=	+)pto-c	0 Couple
Converter Unit V Fixed Re Power Sv Course C Upon cor CO1 : CO2 : CO3 : CO3 :	SELECTION sistor, Capaci vitches, Protect Dutcomes: Impletion of this Implement de Select the ap Select the ap Design the m Select the co	OF PERIP itors, EMI ction eleme s course, th esign conce propriate co propriate p nagnetic co mponents	HERAL Co Filter, Inpunts e students epts and ar ontrol strat ower device mponents in to meet the	OMP It and will the malyze tegy a ces based	ONENT d Outpu be able e the co and imp d on rec	to: ponverte	ifier, \ ers nt	/oltage	supp T	oresso	9 ors, C L+T)=	+)pto-c	0 Couple
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Converter Unit V Fixed Re Power Sv Course C Upon cor CO1 : CO2 : CO3 : CO3 : CO4 : CO5 : Reference	SELECTION sistor, Capaci vitches, Protect Dutcomes: npletion of this Implement de Select the ap Select the ap Design the m Select the co protection an ce Books:	OF PERIP itors, EMI ction eleme s course, th esign conce propriate c propriate p magnetic con imponents d filter elem	HERAL Co Filter, Inpunts e students epts and an ontrol strat ower device mponents in to meet the nents	OMP It and will b halyze tegy a ces based a com	ONENT d Outpu be able e the co and imp d on rea	to: ponverte quirem ealizat	ifier, \ ers nt nents ion of	/oltage	supp To	oresso otal (9 ors, C L+T)=	+)pto-c	0 Couple
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Converter Unit V Fixed Re Power Sv Course C Upon cor CO1 : CO2 : CO3 : CO4 : CO5 : Reference 1. Mar 2. Mar	SELECTION sistor, Capaci vitches, Protect Dutcomes: npletion of this Implement de Select the ap Select the ap Design the m Select the co protection an se Books: ty Brown et. al ty Brown – Po	OF PERIP itors, EMI ction eleme s course, th esign conce propriate p pagnetic co mponents of filter elem - Power Si wer Supply	HERAL CO Filter, Inpunts e students e students opts and ar ontrol strat ower device mponents in to meet the nents ources and Cook Boo	OMP It and will the halyze based bas	ONENT d Outpu d Outpu d on red and imp d on red aplete re plies W , Newn	to: ponverte lemen quirem forld C es 200	ifier, \ ers nt ion of ilass D	/oltage conver	ter an	oresso otal (9 ors, C L+T)=	+)pto-c	0 Couple
Converter Fixed Re Power Sv Course C Upon cor CO1 : CO2 : CO3 : CO3 : CO4 : CO5 : Reference 1. Mar 2. Mar 3. Uma	SELECTION sistor, Capaci vitches, Protect Dutcomes: Implement de Select the ap Select the ap Design the m Select the co protection an ce Books: ty Brown et. al ty Brown – Por anand – Powe	OF PERIP itors, EMI ction eleme s course, th esign conce propriate p magnetic con mponents d filter elem - Power Si wer Supply r Electronic	HERAL CO Filter, Inpunts e students e students epts and ar ontrol strate ower device mponents in to meet the nents ources and Cook Boo s Essentila	omp at and will the halyze based based based based based based based based based based based based based based based based based based	ONENT d Outpu d Outpu d on rea and imp d on rea plies W , Newne d Applia	to: ponverte lemen corld C es 200 cations	ifier, \ ers nents ion of lass D 1 s – Wi	/oltage conver Designs	ter an	oresso otal (9 ors, C L+T)=	+)pto-c	0 Couple
Converter Unit V Fixed Re Power Sv Course C Upon cor CO1 : CO2 : CO3 : CO3 : CO3 : CO3 : CO3 : CO4 : CO5 : Reference 1. Mar 2. Mar 3. Uma 4. Zha	SELECTION sistor, Capacitivitches, Protectivitches, Protectivitches, Protectivitches, Protectivitches, Protectivitches, Protection and Select the appletion of this Select the appletion of the select the appletion and select the comprotection and selects the comprotection and select the comprotection and select the comprotection and select the comprotection and selects the comprotection and selects and selects and select the comprotection and selects and sele	OF PERIP itors, EMI ction eleme s course, th esign conce propriate p propriate p in gnotic co mponents d filter elem - Power Supply r Electronic optimal Des	HERAL Co Filter, Inpunts e students e students epts and ar ower device monents for meet the nents ources and Cook Boo s Essentila ign of Swit	omp it and will k halyze based b	ONENT d Outpu d Outpu d outpu e the co and imp d on rec and imp d on rec plies W , Newne d Applic g Power	to: ponverte lemen guirem corld C es 200 cations	ifier, \ ers nents ion of ilass D 01 s – Wi oly – W	/oltage conver Designs ley 200 /iley 200	ter and , New 99	oresso otal (nd Cho	9 ors, C L+T)=	+)pto-c	0 Couple
Converter Unit V Fixed Re Power Sv Course C Upon cor CO1 : CO2 : CO3 : CO3 : CO3 : CO3 : CO4 : CO5 : Reference 1. Mar 2. Mar 3. Uma 4. Zha 5. Brar	SELECTION sistor, Capacitivitches, Protectivitches, Protectivitches, Protectivitches, Protectivitches, Protectivitches, Protection of this Implement definition of this Implement definition of the select the appleter of the protection and select the comprotection and select the	OF PERIP itors, EMI ction eleme s course, th esign conce propriate p propriate p in gnotic co mponents d filter elem - Power Supply r Electronic optimal Des	HERAL Co Filter, Inpunts e students e students epts and ar ower device monents for meet the nents ources and Cook Boo s Essentila ign of Swit	omp it and will k halyze based b	ONENT d Outpu d Outpu d outpu e the co and imp d on rec and imp d on rec plies W , Newne d Applic g Power	to: ponverte lemen guirem corld C es 200 cations	ifier, \ ers nents ion of ilass D 01 s – Wi oly – W	/oltage conver Designs ley 200 /iley 200	ter and , New 99	oresso otal (nd Cho	9 ors, C L+T)=	+)pto-c	0 Couple
Converter Unit V Fixed Re Power Sv Course C Upon cor CO1 : CO2 : CO3 : CO3 : CO4 : CO5 : Reference 1. Mar 2. Mar 3. Uma 4. Zha 5. Brar Online R	SELECTION sistor, Capacitivitches, Protectivitches, Protectivitches, Protectivitches, Protectivitches, Protectivitches, Protection and Select the appletion of this Select the appletion of the select the appletion and select the comprotection and selects the comprotection and select the comprotection and select the comprotection and select the comprotection and selects the comprotection and selects and selects and select the comprotection and selects and sele	OF PERIP itors, EMI ction eleme s course, th esign conce propriate p propriate p in gnotic co mponents d filter elem - Power Supply r Electronic optimal Des	HERAL Co Filter, Inpunts e students e students opts and ar ontrol strat ower device mponents for to meet the nents ources and Cook Boo s Essentila ign of Swit	omp it and will k halyze based b	ONENT d Outpu d Outpu d outpu e the co and imp d on rec and imp d on rec plies W , Newne d Applic g Power	to: ponverted lemen quirem corld C es 200 cations Supp Regula	ifier, \ ers nents ion of ilass D 01 s – Wi oly – W	/oltage conver Designs ley 200 /iley 200	ter and , New 99 15 on – S	oresso otal (od Cho mes 2	9 ors, C L+T)=	+)pto-(= 45 F	0 Couple

PQ CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Implement design concepts and analyze the converters	1	1	1	1	1						1
CO2	Select the appropriate control strategy and implement	1	1	2	2	1			1			1
CO3	Select the appropriate power devices	1	2	1	1	1			1			1
CO4	Design the magnetic components based on requirements	1	2	2	2	1			2			1
CO5	Select the components to meet the complete realization of converter and Choose the correct protection and filter elements	1	2	2	1	1			1		2	1

				-		^
10	8PEE63	ENERGY STORAGE TECHNOLOGY	 3	Т 0	P 0	C 3
			5	U	U	5
Course	Objectives:					
		ntals, technologies and applications of energy storage				
1						
Unit I	CHANGES	STORICAL PERSPECTIVE, INTRODUCTION AND		9	+	0
Supply-	Transmission (ons in Energy Demand- Variations in Energy Supply- Congestion - Demand for Portable Energy-Demand an ainability issues.				
Unit II		METHODS OF STORAGE		9	+	0
Introduct springs)- and acti (hydroge energy	tion: Energy ar - Kinetic energy ive (water)-The en, methane, g	d Energy Transformations, Potential energy (pumped (mechanical flywheels)- Thermal energy without phase rmal energy with phase change (ice, molten salts, ste asoline, coal, oil)- Electrochemical energy (batteries, f ectromagnetic energy (superconducting magnets)- Diff	change eam)- fuel ce	com e pass Chem ells)-	press sive (nical Elect	ed ai adobe energ rostati
	capture rate ar	NCE FACTORS OF ENERGY STORAGE SYSTEMS ad efficiency- Discharge rate and efficiency- Dispatch				
toxicity-	Ease of materi	exibility, durability – Cycle lifetime, mass and safety – als, recycling and recovery- Environmental consideration t types of Storage.				
Unit IV						
		ON CONSIDERATION	nd met	9	+ =fficia	0
Compari Energy 3 and Lithi patterns Waste h	ing Storage Teo Systems- Energ ium- Chemistry , Battery Manag neat recovery, S	DN CONSIDERATION chnologies- Technology options- Performance factors ar gy Recovery - Battery Storage System: Introduction w of Battery Operation, Power storage calculations, Revers gement systems, System Performance, Areas of Applica olar energy storage, Green house heating, Power plant a stries, energy storage in automotive applications in hybri	ith foc tible re ation of applica	rics- us on actior Ener tions,	Lea is, Ch gy S Dryi	ency o ad Aci nargin torage ng an
Compari Energy 3 and Lithi patterns Waste h	ing Storage Teo Systems- Energ ium- Chemistry , Battery Manag leat recovery, S for process indu	chnologies- Technology options- Performance factors ar gy Recovery - Battery Storage System: Introduction w of Battery Operation, Power storage calculations, Revers gement systems, System Performance, Areas of Applica olar energy storage, Green house heating, Power plant	ith foc tible re ation of applica	rics- us on actior Ener tions,	Lea is, Ch gy S Dryi	ency o ad Aci nargin torage ng an
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PQ CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Recollect the historical perspective and technical methods of energy storage.	3	2	2	2	2	2	1	2	1	3	2
CO2	Learn the basics of different storage methods.	3	2	2	2	2	2	1	2	1	2	1
CO3	Understand the concepts of energy conversion technology	3	3	3	3	2	2	1	2	1	2	1
CO4	Determine the performance factors of energy storage systems	3	3	3	3	2	2	1	2	1	2	1
CO5	Identify the applications of various energy storage systems	3	3	3	3	2	2	1	2	1	2	1

18PEE64 INTERNET OF THINGS FOR ELECTRICAL ENGINEERS	L	Т	Ρ	С
	3	0	0	3
Course Objectives:				
1. To illustrate the concept of Internet of Things (IoT).				
2. To familiarize with implementations of IoT for electrical engineering applications.				
Unit I INTRODUCTION		9	+	0
Internet of Things - Physical Design- Logical Design- IoT Enabling Technologies - IoT Leve	els &	Depl	oym	ent
Templates - Domain Specific IoTs - IoT and M2M - IoT System Management withNETC	ONF-	YAN	IG-	lоТ
Platforms Design Methodology.				
		9	_	0
M2M high-level ETSI architecture - IETF architecture for IoT - OGC architecture - IoT r	efere	-	node	-
Domain model - information model - functional model - communication model – IoT reference				
· · · · · · · · · · · · · · · · · · ·				
Unit III IOT PROTOCOLS		9	+	0
Protocol Standardization for IoT – Efforts – M2M and WSN Protocols – SCADA and RFIDPr				
Data Standards – Protocols – IEEE 802.15.4 – BACNet Protocol – Modbus–Zigbee Archite layer – 6LowPAN - CoAP - Security	cture	e – r	letw	ork
layer – 6LowPAN - COAP - Security				
Unit IV BUILDING IOT		9	+	0
Building IOT with RASPERRY PI- IoT Systems - Logical Design using Python - IoT Phy	/sical	-	vices	-
Endpoints - IoT Device -Building blocks -Raspberry Pi -Board - Linux on Raspberry Pi				
Interfaces -Programming Raspberry Pi with Python - Other IoT Platforms - Arduino.			-	
			-	_
Unit V APPLICATIONS		9	+	0
Real world design constraints - Applications - Asset management, Industrial automa				
Commercial building automation, Smart cities - participatory sensing - Data Analytics for Management Tools for IoT Cloud Storage Models & Communication APIs – Cloud for IoT				
Services for IoT.	- Л	Παζ		CD
Total (L	+T)=	45 F	Perio	ds
Course Outcomes:				
Upon completion of this course, the students will be able to:				
CO1 : Analyze various protocols for IoT.				
CO2 : Develop web services to access/control IoT devices.				
CO3 : Design a portable IoT using Rasperry Pi.				
CO4 : Deploy an IoT application and connect to the cloud.				
CO5 : Analyze applications of IoT in real time scenario.				
References:		-		
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Raman, CRCPress.	Droc			
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3. Holler, VlasiosTsiatsis, Catherine Mulligan, Stamatis, Karnouskos, Stefan Aves & David				
4. The Internet of Things – Key applications and Protocols, Olivier Hersent, David Bos				
Elloumi, Wiley.				
5. The Internet of Things in the Cloud: A Middleware Perspective, Honbo Zhou, CRC Press				
6. Integration of Distributed Generation in the Volt/VAR Management System for Ad				
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Venayagamoorthy, Rajendra Singh, Richard Brooks &Kuang-Ching Wang, IEEE In				
Journal, DOI 10.1109/JIOT.2018.2802704.		. 01		.93

PO CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO1 0	PO1 1
CO1	Analyze various protocols for loT	1	1	1	1	1	1	3	1	1	1	1
CO2	Developwebservicestoaccess/controlIoTdevices.	1	1	3	3	1	1	3	1	1	2	1
CO3	Design a portable IoT using Rasperry Pi.	1	1	2	2	2	1	1	1	1	3	1
CO4	Deploy an IoT application and connect to the cloud.	2	3	2	3	3	1	2	2	1	2	2
CO5	Analyze applications of loT in real time scenario.	2	2	3	3	3	1	2	3	1	2	2

1	8PE	E65 DIGITAL SIGNAL PROCESSORS FOR POWER CONVERTERS	3 0	0	2
Cou	rse	Objectives:	3 0	U	3
1.	То	understand the basic concepts of discrete time signals, digital signal processors, proplications.	gramr	ning	and
Unit		INTRODUCTION to TMS 320C54X PROCESSOR	9	+	0
Addr	essi	digital signal processor - Basic architecture of DSP's – Architecture of TMS 320C5- ng modes- Assembly instructions- Pipelining- Interrupts- Clock generator- Timer- ports- Host-port interface (HPI)			
Unit	11	TMS 320C67X PROCESSOR	9	+	0
Arch	itect	ure of TMS 320C67X processor- CPU data paths and control. Addressing modes. operation.	Instruc	tion	set.
Unit		PERIPHERALS AND INTERFACE	9	-	0
Inter	facir	ng with serial I/O- A/D, D/A converters- Parallel interfacing- Interfacing with RAM- EE nerationDSP tools: Assembler- Debugger- C compiler- Linker -loader.		1s - V	-
Unit	IV	ADVANCES IN DSP PROCESSORS	9	+	0
		chitecture – Multiprocessor DSPs, SHARC, SIMB, MIMD Architectures and Analog Dev ion to FPGA – FPGA based DSP system – Architecture of TMS 320F28335	vices D	SPs	_
intro	auct				
Unit DSP	V -Bas	MOTOR CONTROL APPLICATION Seed Implementation of DC-DC Buck-Boost Converters - DSP-Based Control of Matr			rs -
Unit DSP DSP Pern	V -Bas bas nane	MOTOR CONTROL APPLICATION Seed Implementation of DC-DC Buck-Boost Converters - DSP-Based Control of Matr ed Switched reluctance motor control- DSP based brushless DC motor control, DSP beent Magnet Synchronous Motor Total (45-	ix Con ased o	ontro	ol of
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Unit DSP DSP Pern Cou Upol	V -Bas bas nane rse (n col	MOTOR CONTROL APPLICATION sed Implementation of DC-DC Buck-Boost Converters - DSP-Based Control of Matr ed Switched reluctance motor control- DSP based brushless DC motor control, DSP b ent Magnet Synchronous Motor Total (45+ Dutcomes: mpletion of this course, the students will be able to: Understand the basic concepts of digital signal processor.	ix Con ased o	ontro	rs - ol of
Unit DSP DSP Pern Cou Upol CO1	V Bas bas nane rse (n col 2 : 3 :	MOTOR CONTROL APPLICATION Seed Implementation of DC-DC Buck-Boost Converters - DSP-Based Control of Matr ed Switched reluctance motor control- DSP based brushless DC motor control, DSP b ent Magnet Synchronous Motor Total (454 Outcomes: mpletion of this course, the students will be able to: Understand the basic concepts of digital signal processor. Program the digital signal processor.	ix Con ased o	ontro	rs - ol of
Unit DSP DSP Pern Cou Upol CO1 CO2 CO3	V -Bas bas nane rse (n col : : : : : : : : : : :	MOTOR CONTROL APPLICATION sed Implementation of DC-DC Buck-Boost Converters - DSP-Based Control of Matr ed Switched reluctance motor control- DSP based brushless DC motor control, DSP beent Magnet Synchronous Motor Total (45- Outcomes: mpletion of this course, the students will be able to: Understand the basic concepts of digital signal processor. Program the digital signal processor. Analyze interfacing of peripherals with DSP.	ix Con ased o	ontro	rs - ol of
Unit DSP DSP Pern Cou CO1 CO2 CO3 CO4	V bas nane rse (n con 2 : 3 : 4 : 5 :	MOTOR CONTROL APPLICATION seed Implementation of DC-DC Buck-Boost Converters - DSP-Based Control of Matreed Switched reluctance motor control- DSP based brushless DC motor control, DSP bent Magnet Synchronous Motor Total (45- Outcomes: mpletion of this course, the students will be able to: Understand the basic concepts of digital signal processor. Program the digital signal processor. Analyze interfacing of peripherals with DSP. Understand the advancements in DSP processors Programming of DSP for motor control.	ix Con ased o	ontro	rs - ol of
Unit DSP DSP Pern Cou Upol CO1 CO2 CO3 CO4 CO5	V -Bass bass bass n col : : : : : : : : : : : : :	MOTOR CONTROL APPLICATION seed Implementation of DC-DC Buck-Boost Converters - DSP-Based Control of Matreed Switched reluctance motor control- DSP based brushless DC motor control, DSP bent Magnet Synchronous Motor Total (45- Outcomes: mpletion of this course, the students will be able to: Understand the basic concepts of digital signal processor. Program the digital signal processor. Analyze interfacing of peripherals with DSP. Understand the advancements in DSP processors Programming of DSP for motor control.	•0)= 45	Peri	ods
Unit DSP DSP Perm Cou Upol CO1 CO2 CO3 CO4 CO5 CO4 CO5	V -Bas bas nane rse (n col 	MOTOR CONTROL APPLICATION sed Implementation of DC-DC Buck-Boost Converters - DSP-Based Control of Matr ed Switched reluctance motor control- DSP based brushless DC motor control, DSP b ent Magnet Synchronous Motor Total (45- Dutcomes: mpletion of this course, the students will be able to: Understand the basic concepts of digital signal processor. Program the digital signal processor. Analyze interfacing of peripherals with DSP. Understand the advancements in DSP processors Programming of DSP for motor control. bks: enkataramani et al. "Digital Signal processor –Architecture, Programming and Appli	•0)= 45	s", TI	ods
Unit DSP Perm Cou Upol CO1 CO2 CO3 CO4 CO5 Text 1.	V -Bass bass nane rse (n col 	MOTOR CONTROL APPLICATION sed Implementation of DC-DC Buck-Boost Converters - DSP-Based Control of Matr ed Switched reluctance motor control- DSP based brushless DC motor control, DSP b ent Magnet Synchronous Motor Total (45- Outcomes: mpletion of this course, the students will be able to: Understand the basic concepts of digital signal processor. Program the digital signal processor. Program the digital signal processor. Analyze interfacing of peripherals with DSP. Understand the advancements in DSP processors Programming of DSP for motor control. DKs: enkataramani et al. "Digital Signal processor –Architecture, Programming and Appli w Delhi 2010, second edition. trinivasan & Avtar Singh, 'Digital Signal Processing, Implementations roprocessors with Examples from TMS320C54X", Brooks/Cole, 2004. mid A Joliyet and Steven G Campell, "DSP Based Electromechanical Motion Control	cations	s", Ti	
Unit DSP Pern Cou Upol CO1 CO2 CO3 CO4 CO5 Text 1. 2.	V -Bas bas bas n col rse (n col 	MOTOR CONTROL APPLICATION sed Implementation of DC-DC Buck-Boost Converters - DSP-Based Control of Matr ed Switched reluctance motor control- DSP based brushless DC motor control, DSP b ent Magnet Synchronous Motor Total (45- Outcomes: mpletion of this course, the students will be able to: Understand the basic concepts of digital signal processor. Program the digital signal processor. Program the digital signal processor. Analyze interfacing of peripherals with DSP. Understand the advancements in DSP processors Programming of DSP for motor control. DKs: enkataramani et al. "Digital Signal processor –Architecture, Programming and Appli w Delhi 2010, second edition. trinivasan & Avtar Singh, 'Digital Signal Processing, Implementations roprocessors with Examples from TMS320C54X", Brooks/Cole, 2004. mid A Joliyet and Steven G Campell, "DSP Based Electromechanical Motion Control	cations	s", Ti	

PQ CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Understand the basic concepts of digital signal processor.	1	1	1	1	1	1	1	1	1	2	1
CO2	Program the digital signal processor.	1	1	1	1	1	1	3	3	1	2	1
CO3	Analyze interfacing of peripherals with DSP.	1	1	2	2	2	1	2	1	1	2	1
CO4	Understand the advancements in DSP processors	1	1	2	2	3	1	2	3	1	2	1
CO5	Programming of DSP for motor control.	2	3	3	3	3	1	3	3	1	2	1

	18AC01	ENGLISH FOR RESEARCH PAPER WRITING	L 1	P	С
Co	urse Objectiv	es:	2 0	0	0
		ie importance of writing skills in a Research paper. To Learn how to write dif	ferent	sectio	ns
in a	a research pap	er and skills of writing a good research paper			
Un	it l		4	+	0
Res	search paper a	ind its importance – Structure of a research paper – Planning and Preparatio	n		
Un			4	+	0
	nglish in resea mbiguity and f	rch papers – Basic word order – Collocation – Concord – Breaking up of lor Redundancy	ig sente	ences	-
Un	it III		4	+	0
Кеу		determine the style of a paper – Journal's background – Passive form – Right	tense ·	_	_
CO		nerence.			
Un	it IV		4	+	0
Hi	ghlighting you	findings – Hedging and Criticizing – Paraphrasing and Plagiarism.		1	
Un	it V			1	
			4	+	0
Key	y skills in writi	ng Title – Abstract – Introduction – Review of Literature – Methods – Discuss ful phrases – Ensuring quality of the paper.			0
Key	y skills in writi		ion and	k	
Key Cor	y skills in writi nclusion – use urse Outcom	ful phrases – Ensuring quality of the paper. Total (L+ es:	ion and	k	
Key Cor	y skills in writi nclusion – use urse Outcom Upon com	ful phrases – Ensuring quality of the paper. Total (L+	ion and	k	
Key Cor	y skills in writi nclusion – use urse Outcom Upon com Understand	ful phrases – Ensuring quality of the paper. Total (L+ es: pletion of the course, the students will be able to:	ion and	k	
Key Cor Co 1.	y skills in writi nclusion – use urse Outcom Upon com Understand Apply their	ful phrases – Ensuring quality of the paper. Total (L+ es: pletion of the course, the students will be able to: I and appreciate the process of writing a good research paper	ion and	k	
Key Cor 1. 2. 3.	y skills in writi nclusion – use urse Outcom Upon com Understand Apply their	ful phrases – Ensuring quality of the paper. Total (L+ es: Deletion of the course, the students will be able to: I and appreciate the process of writing a good research paper gained knowledge in writing a research paper d assess the quality of their research paper	ion and	k	
Key Cor 1. 2. 3.	y skills in writi nclusion – use urse Outcom <i>Upon com</i> <i>Understand</i> <i>Apply their</i> <i>Analyse an</i> ggested read	ful phrases – Ensuring quality of the paper. Total (L+ es: Deletion of the course, the students will be able to: I and appreciate the process of writing a good research paper gained knowledge in writing a research paper d assess the quality of their research paper	ion and	k	
Key Cor 1. 2. 3. Su	y skills in writi nclusion – use urse Outcom <i>Upon com</i> <i>Understand</i> <i>Apply their</i> <i>Analyse and</i> ggested read Goldbort R	ful phrases – Ensuring quality of the paper. Total (L+ es: Deletion of the course, the students will be able to: and appreciate the process of writing a good research paper gained knowledge in writing a research paper d assess the quality of their research paper ing	-T) = 20	k	
Key Cor 1. 2. 3. Su g	y skills in writi nclusion – use urse Outcom <i>Upon com</i> <i>Understand</i> <i>Apply their</i> <i>Analyse an</i> ggested read Goldbort R Day R (200	ful phrases – Ensuring quality of the paper. Total (L+ es: Deletion of the course, the students will be able to: and appreciate the process of writing a good research paper gained knowledge in writing a research paper d assess the quality of their research paper ing (2006) "Writing for Science," Yale University press	- T) = 20) perio	ods

PQ CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Understand and appreciate the process of					1	1	1	1	1	1	1

	writing a good research paper									
CO2	Apply their gained knowledge in writing a research paper			1	1	1	1	1	1	1
CO3	Analyse and assess the quality of their research paper			1	1	1	1	1	1	1

	BAC0	2 DISASTER MANAGEMENT	2	0 0	0
Cours	se Ob	ojectives:	2		0
To hav and p and p	ve a o ractio ractio	critical understanding of key concepts in disaster risk reduction and humanita ce from multiple perspectives. Develop an understanding of standards of hur cal relevance in specific types of disasters and conflict situations and evaluat	nanitarian e the stre	respo ngths	onse and
		es of disaster management approaches. Planning and programming in y their home country or the countries they work in.	different	count	ries
Unit I		INTRODUCTION - Disaster Prone Areas In India	4	+	0
Disas Manı Seisn	ster: made nic Z	ICTION Definition, Factors And Significance; Difference Between Hazard And Disate Disasters: Difference, Nature, Types And Magnitude. Disaster Prone Areas I cones; Areas Prone To Floods And Droughts, Landslides And Avalanches; Areas tal Hazards With Special Reference To Tsunami; Post Disaster Diseases And Epic	n India : S Prone To	tudy (Df
Unit I	I F	REPERCUSSIONS OF DISASTERS AND HAZARDS	4	+	0
Earth Man-	nquak -mad	Damage, Loss Of Human And Animal Life, Destruction Of Ecosystem. I kes, Volcanisms, Cyclones, Tsunamis, Floods, Droughts And Famines, Landslide e disaster: Nuclear Reactor Meltdown, Industrial Accidents, Oil Slicks And Sp nd Epidemics, War And Conflicts.	s And Ava	anche	s,
Com	munit	ty Preparedness.	Bovernmer		iù
Unit I Disas Tech	V ster R nique	ty Preparedness. RISK ASSESSMENT Risk: Concept And Elements, Disaster Risk Reduction, Global And National Disas es Of Risk Assessment, Global Co-Operation In Risk Assessment And V ion In Risk Assessment, Strategies for Survival	4 ster Risk Si	+ tuatio	(n.
Unit l' Disas Tech Partie	V ster R nique cipati	RISK ASSESSMENT Risk: Concept And Elements, Disaster Risk Reduction, Global And National Disas es Of Risk Assessment, Global Co-Operation In Risk Assessment And V ion In Risk Assessment. Strategies for Survival.	4 ster Risk Si Varning, 1	+ tuatio People	n. 2's
Unit I Disas Tech Partic Unit V Mear	V ster R nique cipati / [RISK ASSESSMENT Risk: Concept And Elements, Disaster Risk Reduction, Global And National Disaster Ses Of Risk Assessment, Global Co-Operation In Risk Assessment And Wition In Risk Assessment. Strategies for Survival. DISASTER MITIGATION Concept And Strategies Of Disaster Mitigation, Emerging Trends In Mitigation of And Non-Structural Mitigation, Programs Of Disaster Mitigation In India.	4 Ster Risk Si Varning, 4 . Structura	+ tuatio People + I	(n. _'s (
Unit I Disas Tech Partio Unit V Mean Mitig	V ster R nique cipati / I ning, gation se Ou	RISK ASSESSMENT Risk: Concept And Elements, Disaster Risk Reduction, Global And National Disaster Risk: Concept And Elements, Global Co-Operation In Risk Assessment And V ion In Risk Assessment. Strategies for Survival. DISASTER MITIGATION Concept And Strategies Of Disaster Mitigation, Emerging Trends In Mitigation in And Non-Structural Mitigation, Programs Of Disaster Mitigation In India. Tota Jtcomes	4 ster Risk Si Varning, 1 4	+ tuatio People + I	(n. _'s (
Unit I Disas Tech Partio Unit V Mear Mitig Cours On co	V ster R nique cipati / I ning, gation se Ou	RISK ASSESSMENT Risk: Concept And Elements, Disaster Risk Reduction, Global And National Disaster Risk: Concept And Elements, Global Co-Operation In Risk Assessment And Wition In Risk Assessment. Strategies for Survival. DISASTER MITIGATION Concept And Strategies Of Disaster Mitigation, Emerging Trends In Mitigation on And Non-Structural Mitigation, Programs Of Disaster Mitigation In India. Tota Utcomes etion of the course, the students will be able to Learn to demonstrate a critical understanding of key concepts in disaster risk	4 Ster Risk Si Varning, 4 . Structura	+ tuatio People + I 0 Peri	(n. _'s (
Unit I Disas Tech Partio Unit V Mear Mitig Cours On cc CO1	V ster R nique cipati / I ning, gation se Ou	RISK ASSESSMENT Risk: Concept And Elements, Disaster Risk Reduction, Global And National Disasters of Risk Assessment, Global Co-Operation In Risk Assessment And Vision In Risk Assessment. Strategies for Survival. DISASTER MITIGATION Concept And Strategies Of Disaster Mitigation, Emerging Trends In Mitigation on And Non-Structural Mitigation, Programs Of Disaster Mitigation In India. Tota utcomes etion of the course, the students will be able to Learn to demonstrate a critical understanding of key concepts in disaster risk humanitarian response. Critically evaluate disaster risk reduction and humanitarian response policy and	4 Ster Risk Si Varning, 4 . Structura II (L+T)= 2 reduction	+ tuatio People + I 0 Peri and	(n. :'s (od
Unit I Disas Tech Partic Unit V Mear Mitig On co CO1	V ster R nique cipati / I ning, gation se Ou omple :	RISK ASSESSMENT Risk: Concept And Elements, Disaster Risk Reduction, Global And National Disastes of Risk Assessment, Global Co-Operation In Risk Assessment And V ion In Risk Assessment. Strategies for Survival. DISASTER MITIGATION Concept And Strategies Of Disaster Mitigation, Emerging Trends In Mitigation in And Non-Structural Mitigation, Programs Of Disaster Mitigation In India. Tota Interpretent of the course, the students will be able to Learn to demonstrate a critical understanding of key concepts in disaster risk humanitarian response. Critically evaluate disaster risk reduction and humanitarian response policy and multiple perspectives Develop an understanding of standards of humanitarian response and pr	4 ster Risk Si Varning, 4 . Structura Il (L+T)= 2 reduction nd practice	+ tuatio People + I 0 Peri and	(n. :'s (od
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Unit I Disas Tech Partic Unit V Mear Mitig Cours On cc CO1 CO2 CO3 CO3 CO4	V iter R nique cipati / [ning, gation se Ou omple : : ence R. Nis pook	RISK ASSESSMENT Risk: Concept And Elements, Disaster Risk Reduction, Global And National Disas es Of Risk Assessment, Global Co-Operation In Risk Assessment And V ion In Risk Assessment. Strategies for Survival. DISASTER MITIGATION Concept And Strategies Of Disaster Mitigation, Emerging Trends In Mitigation. And Non-Structural Mitigation, Programs Of Disaster Mitigation In India. Tota Utcomes etion of the course, the students will be able to Learn to demonstrate a critical understanding of key concepts in disaster risk humanitarian response. Critically evaluate disaster risk reduction and humanitarian response policy an multiple perspectives Develop an understanding of standards of humanitarian response and pr specific types of disasters and conflict situations Critically understand the strengths and weaknesses of disaster management	4 ster Risk Si Varning, 4 . Structura I (L+T)= 2 reduction nd practice ractical rel approache	+ tuatio People + I 0 Peri and e from evanc s	od e /

	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
PQ												
CO	\mathbf{i}											

l a sum ta					1	1	4	1	1	1	1
										1	I
humanitarian											
response.											
					1	1	1	1	1	1	1
risk reduction											
and											
humanitarian											
response policy											
and practice											
from multiple											
perspectives											
Develop an					1	1	1	1	1	1	1
understanding of											
standards of											
humanitarian											
response and											
practical											
relevance in											
specific types of											
disasters and											
conflict											
situations											
Critically					1	1	1	1	1	1	1
understand the											
strengths and											
weaknesses of											
disaster											
management											
approaches											
	Critically evaluate disaster risk reduction and humanitarian response policy and practice from multiple perspectives Develop an understanding of standards of humanitarian response and practical relevance in specific types of disasters and conflict situations Critically understand the strengths and weaknesses of disaster management	demonstrate a critical understanding of key concepts in disaster risk reduction and humanitarian response.Critically evaluate disaster risk reduction and humanitarian response policy and practice from multiple perspectivesDevelop an understanding of standards response and practical relevance in specific types of disasters and conflict situationsCritically understand the strengths and weaknesses of disaster management	demonstrate a critical understanding of key concepts in disaster risk reduction and humanitarian response.ICritically evaluate disaster risk reduction and humanitarian response policy and practice from multiple perspectivesIDevelop an understanding of standards practical relevance isIDevelop standards practical relevanceICritically understanding of standards practical relevanceISponse and understanding of standards practical relevanceISponse and practical relevanceIconflict situationsICritically understand the strengths and weaknesses of disaster managementI	demonstrate a critical understanding of key concepts in disaster risk reduction and humanitarian response.ICritically evaluate disaster risk reduction and humanitarian response policy and practice from multiple perspectivesIDevelop standards response and nunderstanding of standards response criticallyIDevelop standards response and practical practical relevance in specific types of disasters situationsICritically understand the strengths and weaknesses of disaster managementIII <td< td=""><td>demonstrate a criticalIIIunderstanding of key concepts in disaster riskIIdisaster riskIIIreduction and humanitarianIIIresponse.IIICriticallyIIIevaluate disaster risk reductionIIIand humanitarianIIIresponse policy and practiceIIIperspectivesIIIDevelop standardsIIIpractical relevanceIIIpractical relevanceIIIpractical relevanceIIIpractical relevanceIIIpractical relevanceIIIpractical relevanceIIIpractical relevanceIIIpractical relevanceIIIpractical relevanceIIIpractical relevanceIIIpractical relevanceIIIpractical relevanceIIIpractical relevanceIIIpractical relevanceIIIprodical relevanceIIIprodical relevanceIIIprodical relevanceIIIprodical relevanceII<td>demonstrate a </td><td>demonstrate a critical understanding of key concepts in disaster risk reduction and humanitarian response.11Critically evaluate disaster risk reduction and humanitarian response policy and practice from multiple perspectives11Develop an understanding of standards response11Develop standards of humanitarian11critically evaluate disaster risk reduction and humanitarian11response policy and practice from multiple perspectives11Develop an understanding of standards of humanitarian11critically understanding of standards of humanitarian11criticall relevance in specific types of disasters situations11Critically understand the strengths and weaknesses of disaster management11</td><td>demonstrate a critical understanding of key concepts in disaster risk reduction and humanitarian response.111Critically evaluate disaster risk reduction and humanitarian response policy and practice from multiple perspectives111Develop an understanding of standards of humanitarian response111Develop and practical response111Develop standards of humanitarian response and practical111Develop standards response and practical response and practical111Develop standards response and practical111Develop standards response and practical111Tritically understand the situations111Critically understand the strengths and weaknesses of disaster management111</td><td>demonstrate a critical understanding of key concepts in disaster risk reduction and humanitarian response.1111Critically evaluate disaster risk reduction and humanitarian response policy and practice from multiple perspectives1111Develop standards of humanitarian response11111Image: transform multiple perspectives11111Develop and understanding of standards fit111111Image: transform multiple perspectives111111Develop and understanding of standards fit111111Image: transform multiple perspectives111111Image: transform multiple perspectives<!--</td--><td>demonstrate a critical understanding of key concepts in disaster risk reduction and humanitarian response.IIIIICritically evaluate disaster risk reduction and humanitarian response policy and practice from multiple perspectivesII</td><td>demonstrate a critical understanding of key concepts in disaster risk reduction and humanitarian response. Critically evaluate disaster risk reduction and humanitarian response policy and practice from multiple perspectives Develop an understanding of standards of humanitarian response and practical response and practical response and practical response and practical response and practical response and practical response and practical response and practical response and practical relevance in specific types of disasters and conflict situations Critically understand the strengths and weaknesses of disaster management</td></td></td></td<>	demonstrate a criticalIIIunderstanding of key concepts in disaster riskIIdisaster riskIIIreduction and humanitarianIIIresponse.IIICriticallyIIIevaluate disaster risk reductionIIIand humanitarianIIIresponse policy and practiceIIIperspectivesIIIDevelop standardsIIIpractical relevanceIIIpractical relevanceIIIpractical relevanceIIIpractical relevanceIIIpractical relevanceIIIpractical relevanceIIIpractical relevanceIIIpractical relevanceIIIpractical relevanceIIIpractical relevanceIIIpractical relevanceIIIpractical relevanceIIIpractical relevanceIIIpractical relevanceIIIprodical relevanceIIIprodical relevanceIIIprodical relevanceIIIprodical relevanceII <td>demonstrate a </td> <td>demonstrate a critical understanding of key concepts in disaster risk reduction and humanitarian response.11Critically evaluate disaster risk reduction and humanitarian response policy and practice from multiple perspectives11Develop an understanding of standards response11Develop standards of humanitarian11critically evaluate disaster risk reduction and humanitarian11response policy and practice from multiple perspectives11Develop an understanding of standards of humanitarian11critically understanding of standards of humanitarian11criticall relevance in specific types of disasters situations11Critically understand the strengths and weaknesses of disaster management11</td> <td>demonstrate a critical understanding of key concepts in disaster risk reduction and humanitarian response.111Critically evaluate disaster risk reduction and humanitarian response policy and practice from multiple perspectives111Develop an understanding of standards of humanitarian response111Develop and practical response111Develop standards of humanitarian response and practical111Develop standards response and practical response and practical111Develop standards response and practical111Develop standards response and practical111Tritically understand the situations111Critically understand the strengths and weaknesses of disaster management111</td> <td>demonstrate a critical understanding of key concepts in disaster risk reduction and humanitarian response.1111Critically evaluate disaster risk reduction and humanitarian response policy and practice from multiple perspectives1111Develop standards of humanitarian response11111Image: transform multiple perspectives11111Develop and understanding of standards fit111111Image: transform multiple perspectives111111Develop and understanding of standards fit111111Image: transform multiple perspectives111111Image: transform multiple perspectives<!--</td--><td>demonstrate a critical understanding of key concepts in disaster risk reduction and humanitarian response.IIIIICritically evaluate disaster risk reduction and humanitarian response policy and practice from multiple perspectivesII</td><td>demonstrate a critical understanding of key concepts in disaster risk reduction and humanitarian response. 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Critically evaluate disaster risk reduction and humanitarian response policy and practice from multiple perspectives Develop an understanding of standards of humanitarian response and practical response and practical response and practical response and practical response and practical response and practical response and practical response and practical response and practical relevance in specific types of disasters and conflict situations Critically understand the strengths and weaknesses of disaster management

18	AC03	SANSKRIT FOR TECHNICAL KNOWLEDGE	L	Τ	Ρ	С
			2	0	0	0
Cours	e Objectiv	/es:				
•		knowledge in illustrious Sanskrit, the scientific language in the world. Learni	•			
•		nctioning. Learning of Sanskrit to develop the logic in mathematics, science				
	-	nemory power. The engineering scholars equipped with Sanskrit will be able	e to	expl	ore	the
	nowledge	from ancient literature.				
Unit I			8		+	0
Alpha	bets in Sa	nskrit-Past/Present/Future Tense-Simple Sentences				
	-					
Unit II			8		+	0
Order	r-Introduct	ion of roots-Technical information about Sanskrit Literature				
1114.10					1	^
Unit II			8		+	0
Techr	nical conce	pts of Engineering-Electrical, Mechanical, Architecture, Mathematics				
		Total (L	⊦T)=	24 F	Perio	ods
Cours	e Outcom					
	mpletion	of the course, the students will be able to				
CO1	: Und	erstanding basic Sanskrit language				
CO2	: Anci	ent Sanskrit literature about science & technology can be understood				
CO3	: Bein	g a logical language will help to develop logic in students				
-						
	ested Rea					
		akam" – Dr.Vishwas, Samskrita-Bharti Publication, New Delhi				
"		urself Sanskrit" PrathamaDeeksha-VempatiKutumbshastri, Rashtriya Sansk	rit S	anst	hana	am
~						
~	lew Delhi I	Publication				
2. N		Publication rious Scientific Tradition" Suresh Soni, Ocean books (P) Ltd., New Delhi				

PQ CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Understanding basic Sanskrit language					1	1	1	1	1	1	1
CO2	Ancient Sanskrit literature about science & technology can be understood					1	1	1	1	1	1	1
CO3	Being a logical language will help to develop logic in students					1	1	1	1	1	1	1

-				-		
1	8AC0	VALUE EDUCATION	L 2	0	P 0	C 0
Cour	rse Ob	jectives:	2	U	U	U
		and the importance of value education and self-development. To imbibe good val ow about the importance of character.	ues	in s	tude	nts
Unit			4		+	0
		d self-development – Social values and individual attitudes - Work ethics, Inc Moral and non-moral valuation - Standards and principles - Value judgements.	ian	visi	on c	of
Unit	11		6		+	0
		ness – Cleanliness – Honesty – Humanity -Power of faith - National Unity – Patriot iscipline	sm	- Lo	ve to	or
Unit			6		+	0
Unit Cha rein	IV racter carnat	elfdestructive habits-Association and Cooperation - Doing best for saving nature and Competence – Holy books vs Blind faith - Self-management and Good healt ion-Equality – Nonviolence – Humility - Role of Women - All religions and same me		Scier		
you		- Self-control – Honesty - Studying effectively				
Cour		Total (L+	1)=	221	eric	as
		tion of the course, the students will be able to				
C01		Knowledge of self-development				
CO2	:	Critically evaluate disaster risk reduction and humanitarian response policy and pr multiple perspectives	acti	ce f	rom	
CO3	:	Learn the importance of Human values				
CO4	:	Developing the overall personality				
Sug	Chakr	Reading: aborty, S.K. "Values and Ethics for organizations Theory and practice", Oxford Univ Delhi,1998.	ersi	ty Pi	ess,	

PØ CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Knowledge of self- development					1	1	1	1	1	1	1
CO2	Critically evaluate disaster risk reduction and humanitarian response policy and practice from multiple					1	1	1	1	1	1	1

	perspectives									
CO3	Learn the importance of Human values			1	1	1	1	1	1	1
CO4	Developing the overall personality			1	1	1	1	1	1	1

18AC05 CONSTIT	UTION OF INDIA	ΤP	С
	2	0 0	0
Course Objectives			
Course Objectives: Understand the premises informing the twin theme	s of liberty and freedom from a civil rights no	renoc	tivo
		•	
To address the growth of Indian opinion regardin	-		
entitlement to civil and economic rights as well as the			
nationalism. To address the role of socialism in India		olutio	n in
1917 and its impact on the initial drafting of the India	an constitution.		
Unit I HISTORY OF MAKING OF THE INDIAN CONS	TITUTION	4 +	0
History, Drafting Committee, (Composition & Worki		<u> </u>	
Unit II PHILOSOPHY OF THE INDIAN CONSTITUTIO)N 2	4 +	0
Preamble, Salient Features			
Unit III CONTOURS OF CONSTITUTIONAL RIGHTS		4 +	0
Fundamental rights, right to equality, right to free			
religion, cultural and educational rights, right to cor	stitutional remedies, directive principles of sta	ite po	licy,
fundamental duties			
Unit IV ORGANS OF GOVERNANCE		4 +	0
Parliament, composition, qualifications and disqua			
governor, council of ministers, judiciary, appointm	ent and transfer of judges, qualifications, po	wers	and
functions			
		4	•
		-	0
Districts administration head: role and importance,			
representative, CEO of municipal corporation. Pa			
officials and their roles, CEO zilapanchayat: position departments), village level: role of elected and appoint	- ·	-	rent
departments), vinage level. Tole of elected and appo	filed officials, importance of grass root democr	acy	
Unit VI ELECTION COMMISSION	2	4 +	0
Election Commission: role and functioning. Chief el	ection commissioner and election commission	ers. S	tate
election commission: role and functioning. Institute			
<u></u>	Total (L+T)= 24		
Course Outcomes:			
Upon completion of this course, the students will be a	able to:		
		arriv	~l of
Gandhi in Indian politics	rights in India for the bulk of Indians before the	urriv	ui oj
	ework of argument that informed the conceptud	alizati	<u></u>
of social reforms leading to revolution in Ir		JIIZUU	υn
		ייי נססי	ndor
······································	e foundation of the Congress Socialist Party [C. the eventual failure of the proposal of direct	-	
through adult suffrage in the Indian Consti		eiect	10115
CO4 : Discuss the passage of the Hindu Code Bill			
Suggested Reading:	0] 1330.		
1. The Constitution of India, 1950 (Bare Act), Gove	Proment Publication		
 Dr. S. N. Busi, Dr. B. R. Ambedkar framing of Inc. 			
3. M. P. Jain, Indian Constitution Law, 7th Edn., Le			
 M. P. Jain, Indian Constitution Law, 7th Edit, Le D.D. Basu, Introduction to the Constitution of Ir 			
	IUIU, LENIS INENIS, 2013.		

PQ CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Discuss the growth of the demand for civil rights in India for the bulk of Indians before the arrival of Gandhi in Indian politics					1	1	1	1	1	1	1
CO2	Discuss the intellectual origins of the framework of argument that informed the conceptualization of social reforms leading to revolution in India					1	1	1	1	1	1	1
CO3	Discuss the circumstances surrounding the foundation of the Congress Socialist Party [CSP] under the leadership of Jawaharlal Nehru and the eventual failure of the proposal of direct elections through adult suffrage in the Indian Constitution					1	1	1	1	1	1	1
CO4	Discuss the passage of the Hindu Code Bill of 1956.					1	1	1	1	1	1	1

1	8AC06	PEDAGOGY STUDIES	L	Т	Ρ	С
			2	0	0	0
Cour	an Ohiantiy					
	se Objectiv	es: g evidence on the review topic to inform programme design and policy mal	/ing i	indo	rtak	on
		r agencies and researchers. Identify critical evidence gaps to guide the deve	-		ιιακ	511
by th		r agencies and researchers. Identity entited evidence gaps to guide the deve	opin	cm.		
Unit I	I [4	+	0
Aims	and ration	ale, Policy background, Conceptual framework and terminology, Theor	ies o	f le	arnir	ıg,
Curric	culum, Teac	her education, Conceptual framework, Research questions, Overview of m	etho	dolo	gy a	nd
Searc	ching					
11			<u> </u>	•		_
Unit I		wy Dedagogical practices are being used by teachers in formal and informa		2	+	0 in
		w: Pedagogical practices are being used by teachers in formal and informative ries, Curriculum, Teacher education.		5510	oms	m
uevei						
Unit I				4	+	0
Evide	nce on the	e effectiveness of pedagogical practices, Methodology for the in depth	stag	ge:	qual	ity
asses	sment of ir	cluded studies, How can teacher education (curriculum and practicum)	and	the	schc	, ool
curric	culum and g	uidance materials best support effective pedagogy? Theory of change. Stre	ngth a	and	natu	re
of the	e body of e	vidence for effective pedagogical practices, Pedagogic theory and pedagogi	cal a	pprc	ache	es,
Teach	ners" attitud	es and beliefs and Pedagogic strategies.				
	N/					_
Unit I				4	+	0
		elopment: alignment with classroom practices and follow-up support, Peer s				
		teacher and the community, Curriculum and assessment, Barriers to le ge class sizes.	:arm	ig:	Innit	ea
16300		ge class sizes.				
Unit V	V			2	+	0
Resea	arch gaps a	nd future directions, Research design, Contexts, pedagogy, teacher education	tion,	curr	iculu	m
and a	issessment,	dissemination and research impact				
Cour	se Outcom	Total (L-	-T)= 1	16 P	erio	st
Upon	completion	of this course, the students will be able to:				
C01	: What	pedagogical practices are being used by teachers in formal and informa	l clas	ssro	oms	in
	develo	ping countries?				
C02	: What i	s the evidence on the effectiveness of these pedagogical practices, in what co	onditi	ons,	and	
	with w	hat population of learners?				
CO3	: How c	an teacher education (curriculum and practicum) and the school curriculur	n and	d gu	idan	се
	materi	als best support effective pedagogy?				
	ested Read					
		rdman F (2001) Classroom interaction in Kenyan primary schools, Compare,				1
	-	2004) Curricular reform in schools: The importance of evaluation, Journal of	Curri	iculu	Im	
	Studies 36	3): 361-379.				
3	Akyeampon	g K (2003) Teacher training in Ghana - does it count? Multi-site teacher educ	ation	res	earc	h
3.	Akyeampon project (ML	STER) country report 1. London: DFID				h
3.	Akyeampon project (MU Akyeampon	STER) country report 1. London: DFID g K, Lussier K, Pryor J, Westbrook J (2013) Improving teaching and learning o	f basi	ic m	aths	
3. ⁴	Akyeampon project (ML Akyeampon and reading	STER) country report 1. London: DFID g K, Lussier K, Pryor J, Westbrook J (2013) Improving teaching and learning o in Africa: Does teacher preparation count? International Journal Educationa	f basi	ic m	aths	
3. 4 4.	Akyeampon project (ML Akyeampon and reading 33 (3): 272-	STER) country report 1. London: DFID g K, Lussier K, Pryor J, Westbrook J (2013) Improving teaching and learning o in Africa: Does teacher preparation count? International Journal Educationa 282.	f basi l Dev	ic m elop	aths mer	ıt,
3. 4 4. 5	Akyeampon project (ML Akyeampon and reading 33 (3): 272-	STER) country report 1. London: DFID g K, Lussier K, Pryor J, Westbrook J (2013) Improving teaching and learning o in Africa: Does teacher preparation count? International Journal Educationa 282. J (2001) Culture and pedagogy: International comparisons in primary educat	f basi l Dev	ic m elop	aths mer	ıt,

PQ CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	What pedagogical practices are being used by teachers in formal and informal classrooms in developing countries?					1	1	1	1	1	1	1
CO2	What is the evidence on the effectiveness of these pedagogical practices, in what conditions, and with what population of learners?					1	1	1	1	1	1	1
CO3	How can teacher education (curriculum and practicum) and the school curriculum and guidance materials best support effective pedagogy?					1	1	1	1	1	1	1

18AC07	STRESS MANAGEMENT BY YOGA	L	Т	Ρ	С
		2	0	0	0
Course Objective	PS:				
To achieve overall	health of body and mind, To overcome stress				
Unit I			8	+	0
Definitions of Eigh	t parts of yoga				
Unit II			8	+	0
-	Do`s and Don"t"s in life. 1.Ahinsa, satya, astheya, bramhacharya and aparigr adhyay, ishwarpranidhan	aha	2.Sł	nauc	ha,
Unit III			8	+	0
	m 1. Various yog poses and their benefits for mind & body 2. Regularizations of pranayama	on o	fbre	eath	ing
	Total (L+	T)= 2	24 P	eric	ods

Cou	Irs	e (Dutcomes:
Upo	n e	coi	npletion of this course, the students will be able to:
CO	1	:	Develop healthy mind in a healthy body thus improving social health also
C02	2	:	Improve efficiency
Sug	ge	est	ed Reading:
1.	С	on	ic Asanas for Group Tarining-Part-I" :Janardan Swami Yogabhyasi Mandal, Nagpur "Rajayoga or quering the Internal Nature" by Swami Vivekananda, Advaita Ashrama (Publication Department), kata

PQ CO	CO Statement	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	Develop healthy mind in a healthy body thus improving social health also					1	1	1	1	1	1	1
CO2	Improve efficiency					1	1	1	1	1	1	1

18AC08	PERSONALITY DEVELOPMENT THROUGH LIFE ENLIGHTENMENT SKILLS	L	T	Ρ	C
		2	0	0	0
Course Objective	95:				
To learn to achiev	e the highest goal happily, To become a person with stable mind, pleasing p	bers	onal	lity a	nc
determination, To	awaken wisdom in students.				
Unit I			8	+	0
Neetisatakam-Hol	istic development of personality				
Verses- 19,20,21,2	22 (wisdom)				
Verses- 29,31,32 (pride & heroism)				
Verses- 26,28,63,6	55 (virtue)				
Verses- 52,53,59 (dont"s)				
Verses- 71,73,75,7	78 (do"s)				
Unit II			8	+	0
Approach to day t	o day work and duties.				
ShrimadBhagwad	Geeta:				
Chapter 2-Verses	41, 47,48,				
Chapter 3-Verses	13, 21, 27, 35,				
Chapter 6-Verses	5,13,17,23, 35,				
Chapter 18-Verses	s 45, 46, 48.				
Unit III			8	+	0
Statements of bas	-				
Shrimad Bhagwad	Geeta:				
Chapter2-Verses 5	66, 62, 68				
Chapter 12 -Verse	s 13, 14, 15, 16,17, 18				
Personality of Role	e model.				
Shrimad Bhagwad	Geeta:				
Chapter2-Verses 1	.7,				
Chapter 3-Verses	36,37,42				
Chapter 4-Verses	18, 38,39				
Chapter18 – Vers	es 37,38,63				
	Total (L+	T)= 2	24 F	Peric	ds
Course Outcome	S:				
Upon completion of	of this course, the students will be able to:				
CO1 : Study o	f Shrimad-Bhagwad-Geeta will help the student in developing his personali	'ty a	nd o	achi	eve
	nest goal in life				
	son who has studied Geeta will lead the nation and mankind to peace and pro	ospe	eritv		
	f Neetishatakam will help in developing versatile personality of students.		,		
Suggested Readi					
	gavad Gita" by Swami SwarupanandaAdvaita Ashram (Publication Departme	nt).	Kolk	ata	
Rhartrihari"s	Three Satakam (Niti-sringar-vairagya) by P.Gopinath, Rashtriya Sanskrit Sans				
2. Bilartinian s	The Could and the singer variagy by roopinally hashing satisfit satis	JUID	nan	1, INC	. v v

PO	CO Statement	PO1	PO	PO	PO4	PO	PO	PO	PO	PO	PO10	PO1
			2	3		5	6	7	8	9		1
CO												
CO1	Study of Shrimad-					1	1	1	1	1	1	1
	Bhagwad-Geeta will											
	help the student in											

	developing his personality and achieve the highest goal in life									
CO2	The person who has studied Geeta will lead the nation and mankind to peace and prosperity			1	1	1	1	1	1	1
CO3	Study of Neetishatakam will help in developing versatile personality of students.			1	1	1	1	1	1	1

18PESE1	PATTERN RECOGNITION	L T 3 0	P 0	C 3
		3 0	U	
Course Objectiv				
	and pattern and unsupervised classification.			
	feature extraction and selection.			
3. To underst	and structural pattern recognition.			
Unit I PATTE	RN CLASSIFIER	9	+	0
Maximum likeliho	ern recognition – Discriminant functions – Supervised learning – Parametric od estimation – Bayesian parameter estimation – Perceptron algorithm – LMS ayes approach – Pattern classification by distance functions – Minimum dis	SE algo	orithn	า -
Unit II UNSU	PERVISED CLASSIFICATION	9	+	0
	nsupervised learning and classification – Clustering concept – C-means tering procedures – Graph theoretic approach to pattern clustering – Validit			
Unit III STRU	CTURAL PATTERN RECOGNITION	9	+	0
Elements of form	al grammars – String generation as pattern description – Recognition of syntac nastic grammars and applications – Graph based structural representation.	-	cript	-
Unit IV FEAT	URE EXTRACTION AND SELECTION	9	+	0
Entropy minimiza	tion – Karhunen – Loeve transformation – Feature selection through functions	-	-	_
 Binary feature s 	selection.			
	NT ADVANCES	9	+	0
Neural network Unsupervised lea	structures for Pattern Recognition – Neural network based Pattern Irning in neural Pattern Recognition – Self-organizing networks – Fuzzy logic – Ern classification using Genetic Algorithms	associa	ators	-
	Total (L+T	-)= 45 F	Perio	ds
Course Outcom		<u>)- 40 i</u>	0110	
Upon completion	of this course, the students will be able to:			
	ve pattern and unsupervised classification problems.			
	form feature extraction and selection. cute structural pattern recognition.			
Text Books:				
Robert LSc	halkoff, Pattern Recognition Statistical, Structural and Neural Approaches, Joh	n Wilev	ጲ	
	lew York, 1992.	i wiicy	ũ	
	nzales, Pattern Recognition Principles, Wesley Publication Company, London,	1974		
Reference Book				
1. Duda R.O.,	and Har P.E., Pattern Classification and Scene Analysis, Wiley, New York, 197	'3.		
2. Morton Nad	ier and Eric Smith P., Pattern Recognition Engineering, John Wiley & Sons, Ne	w York	, 199	3
E References:				
1. https://www	geeksforgeeks.org/pattern-recognition-introduction/			_

PO	CO Statement	PO1	PO	PO	PO4	PO	PO	PO	PO	PO	PO10	PO1
со			2	3		5	6	7	8	9		1
CO1	To solve pattern and unsupervised classification problems.					2	1	1	2	1	2	1

CO2	To perform extraction selection.	feature and			1	1	2	1	1	2	1
CO3	To structural recognition.	execute pattern			1	1	1	2	1	3	3