



DEPARTMENT OF MECHANICAL ENGINEEERING - VISION & MISSION

A serene and tranquil 'MECH' atmosphere helps the dynamic professionals to kindle their innovative minds. The enduring efforts of faculties have enhanced the students with omnipotent skills, with considerable research work being done in the department.

VISION

The department of mechanical engineering is committed to blossom into a centre of excellence, dedicated and competent engineers by providing global quality interactive technical education to cater the needs of the industries and nation into a technologically, socially and culturally advanced one.

MISSION

- Constantly updating the departmental resources, faculty and other infrastructure by acquiring
 the state of the art equipments and by imparting constant in-service training to the faculty and
 supporting staff.
- Promoting skilled and employable graduates to meet the challenges in emerging fields of engineering.
- To prepare the students for prosperous career in entrepreneurship with leader ship qualities, ethics and human values.
- The department executes life-long learning skills and provides engineering services for sustainable development of the society.

PROGRAMME EDUCATIONAL OBJECTIVES

- **PEO 1**: To provide students with strong fundamental knowledge in mathematics, science and basic engineering to enable them to solve the mechanical engineering related problems.
- **PEO 2**: To develop expertise in core areas like design, analyze and synthesize data and technical concepts with software skills to create novel products and solutions for the real time problems.
- **PEO 3**: Graduates able to exhibit professionalism in their profession with effective communication, ethical attitude, entrepreneurship skills and the knowledge in global economy to meet the social challenges.
- **PEO 4**: To promote the students for continuous learning towards professional growth in contemporary areas of socio-technological issues like energy crisis, environmental pollution, industrial issues and natural disaster.

PROGRAMME OUTCOMES

- **PO1**: Apply the knowledge of mathematics, science and engineering specialization to solve complex engineering problems.
- **PO2**: Graduates will have the ability to identify, formulate, conduct experiment and analyze engineering problems
- **PO3**: Graduates will demonstrate the ability to design and evaluate a mechanical system (or) process with appropriate consideration for the socio environmental conditions.
- **PO4**: Graduates will demonstrate the ability to design and conduct experiments, interpretation of data and synthesis of information to provide valid conclusions.
- PO5: Graduates will be familiar with modern engineering software tools and equipments to model and predict the Mechanical engineering problems
- PO6: Demonstrate knowledge to assess societal, health, safety, legal and cultural issues and the
 consequent responsibilities relevant to engineering practice
- PO7: Understand the impact of engineering solution in the environmental context and the need for sustainable development.
- PO8: Apply ethical principles and commitment to professional ethics and norms of the practice in the field of Mechanical engineering.
- PO9: Obtain the ability to function individually and also as a team member in multi-disciplinary activities.
- **PO10**: Able to communicate effectively in verbal, written and graphical forms.
- PO11: Recognize the need and ability to engage in independent and life-long learning in the broadest context of technological change.
- PO12: Graduates will have the ability to employ effective project management skills and financial
 principles to develop project plans in multi-disciplinary environments.

PROGRAMME SPECIFIC OUTCOMES

- **PSO 1**: Ability to identify, analyze and solve engineering problems in the domains of Design, Thermal and Manufacturing systems.
- **PSO 2**: Ability to apply their knowledge in principle of design and analysis, in execution of automation in mechanical system / processes.
- **PSO 3**: Ability to involve professionally in industries or as an entrepreneur by applying manufacturing and management practices.

GOVERNMENT COLLEGE OF ENGINEERING, SALEM – 636 011. **B.E – MECHANICAL ENGINEERING (FULL TIME) – R2022 CURRICULUM**

		SEMESTE	RI							
S.	Course	C THE	G 4		Hour	s/Wee	k	Ma	ax. Ma	arks
No.	Code	Course Title	Cat	L	T	P	С	CA	FE	Total
1	22MC101	Induction Program	MC	-	-	-	0	-	-	-
	•	THEOR	Y							
2	22MA101	Matrices, Calculus and Ordinary Differential Equation	BS	3	1	0	4	40	60	100
3	22CY101	Engineering Chemistry	BS	3	1	0	4	40	60	100
4	22EE101	Basics Electrical and Electronics Engineering	ES	3	1	0	4	40	60	100
5	22ME101	Engineering Graphics and Design	ES	1	0	4	3	40	60	100
6	22CS101	Problem Solving and C Programming	ES	3	0	0	3	40	60	100
7	22MC102	Heritage of Tamil / தமிழர்மரபு	HS MC	1	0	0	1	100	_	100
		PRACTIC	AL							
8	22EN102	Professional Skills Laboratory	HS	0	0	2	1.0	60	40	100
9	22PH103	Physics Laboratory	BS	0	0	3	1.5	60	40	100
10	22CY102	Chemistry laboratory	BS	0	0	3	1.5	60	40	100
11	22EE102	Basics Electrical and Electronics Engineering Laboratory	ES	0	0	3	1.5	60	40	100
	•	TOTAL					24.5			1000
		SEMESTE	R II	•				•	•	•
S.	Course		~ .	Hours/Week			-	Ma	ax. Ma	arks
No.	Code	Course Title	Cat	L	T	P	C	CA	FE	Total
		THEOR	Y						l	
1	22EN101	Communicative English(Theory cum Practical)	HS	2	0	2	3	50	50	100
2	22MA201	Partial Differential Equation, Vector Calculus and Complex Variables	BS	3	1	0	4	40	60	100
3	22PH101	Engineering Physics	BS	3	1	0	4	40	60	100
4	22ES101	Engineering Mechanics	ES	3	0	0	3	40	60	100
5	22HS201	Universal Human Values	HS	2	1	0	3	40	60	100
6	22MCIN01	Engineering Sprints	EE	0	0	2	1	100	-	100
7	22MC201	Tamils and Technology / தமிழரும் தொழில்நுட்பமும்	HS MC	1	0	0	1	100	-	100
8	22NC201	NCC Course – I (only for NCC students)*	NC	3	0	0	3*	-	-	100*
		PRACTIC	AL		ı	T		I	Π	Π
9	22CS102	Computer Practice and C Programming Laboratory	ES	0	0	3	1.5	60	40	100
10	22ME102	Workshop Manufacturing Practices	ES	0	0	4	2.0	60	40	100
	1	TOTAL T					22 -			000
	•	TOTAL					22.5			900

*NCC credit course level I is offered for NCC students only. The grades earned by the students will be recorded in the

S.	Course	Course Title	Cat		Hours	/Week	K	M	ax. Ma	arks
No.	Code	Course Title	Cat	L	Т	P	С	CA	FE	Total
		THEOR	Ϋ́							
1	22MA305	Fourier Series, Boundary Value Problems and Transforms	BS	3	0	0	3	40	60	100
2	22ME301	Engineering Thermodynamics	PC	3	1	0	4	40	60	100
3	22ME302	Fluid Mechanics and Machinery	PC	3	1	0	4	40	60	100
4	22ME303	Manufacturing Processes	PC	3	0	0	3	40	60	100
5	22MT310	Materials Engineering	ES	3	0	0	3	40	60	100
6	22MCIN02	Innovation Sprints	EE	0	0	2	1	100	-	100
7	22NC301	NCC Course – II (only for NCC Students)*	NC	3	0	0	3*	-	-	100*
		PRACTIO	CAL							
8	22ME304	CAD Laboratory	PC	0	0	3	1.5	60	40	100
9	22CE308	Strength of Materials and Fluid Mechanics Laboratory	ES	0	0	3	1.5	60	40	100
		TOTAL					21			800

SEMESTER IV

S.	Course	СТИ-	C-4		Hours	/Week	<u> </u>	Ma	ax. Ma	arks
No.	Code	Course Title	Cat	L	T	P	C	CA	FE	Total
		THEOR	Y							
1	22ME401	Kinematics of Machinery	PC	3	1	0	4	40	60	100
2	22ME402	Thermal Engineering	PC	3	1	0	4	40	60	100
3	22ME403	Metal cutting and Machine Tools	PC	3	0	0	3	40	60	100
4	22ME404	Hydraulics and Pneumatics	PC	3	0	0	3	40	60	100
5	22CE409	Strength of Materials	ES	3	0	0	3	40	60	100
6	22MCIN03	Design Sprints	EE	0	0	2	1	100	-	100
7	22CYMC01	Environmental Science	MC	2	0	1	0	-	-	-
		PRACTIC	CAL							
9	22ME405	Thermal Engineering Laboratory	PC	0	0	3	1.5	60	40	100
10	22ME406	Manufacturing Technology Laboratory	PC	0	0	3	1.5	60	40	100
		TOTAL					21			800

^{*}NCC credit course level II is offered for NCC students only. The grades earned by the students will be recorded in the Mark sheet, however the same shall not be considered for the computation of CGPA

		SEMESTE	R V							
S.	Course	Course Title	Cat		Hou	rs/W	eek	N	Iax. M	arks
No.	Code	Course Title	Cat	L	T	P	C	CA	FE	Total
		THEOR	Y							
1	22ME501	Design of Machine Elements	PC	3	1	0	4	40	60	100
2	22ME502	Heat and Mass Transfer	PC	3	0	0	3	40	60	100
3	22ME503	Metrology and Quality Control	PC	3	0	0	3	40	60	100
4	22ME504	Dynamics of Machinery	PC	3	0	0	3	40	60	100
5	22ME505	Instrumentation and Control system	PC	3	0	0	3	40	60	100
6	22MCIN04	Ideation Sprints	EE	0	0	2	1	100	-	100
7	22MC301	Indian Constitution	MC	3	0	0	0	100	-	100
		PRACTIC	AL							
8	22ME506	Dynamics and Metrology Laboratory	PC	0	0	3	1.5	60	40	100
9	22EN502	Placement and Career Training Laboratory	HS	0	0	4	1.5	60	40	100
10	22ME507	Heat Transfer and Refrigeration Laboratory	PC	0	0	3	1.5	60	40	100
	_	TOTAL					21.5		_	900

SEMESTER VI (REGULAR STREAM)

S.	Course	C T'41-	Cat		Hou	rs/W	eek	N	Iax. M	larks
No.	Code	Course Title	Cat	L	Т	P	C	CA	FE	Total
		THEORY								
1	22MEPE1X	Professional Elective – I	PE	3	0	0	3	40	60	100
2	22MEPE2X	Professional Elective – II	PE	3	0	0	3	40	60	100
3	22MEPE3X	Professional Elective – III	PE	3	0	0	3	40	60	100
4	22MEOE1X	Open Elective –I	OE	3	0	0	3	40	60	100
5	22MEOE2X	Open Elective –II	OE	3	0	0	3	40	60	100
6	22MEOE3X	Open Elective-III	OE	3	0	0	3	40	60	100
		PRACTICA	L							
7	22ME601	Mini Project	EE	0	0	6	3	60	40	100
		TOTAL					21			700

<u> </u>		SEMESTER VI (PI		l		s/Wee	.lz	n.	Iax. M	[onless
S. No.	Course Code	Course Title	Cat	L	Hour T	P	C	CA	FE	Total
		TH	EORY	L	1	1		CA	FE	Total
1	22PSPE01	Computational Hardware	PE	3	0	0	3	100	0	100
2	22PSPE02	Coding for Innovators	PE	3	0	0	3	100	0	100
3	22PSPE03	Industrial Automation	PE	3	0	0	3	100	0	100
4	22PSOE01	Applied Design Thinking	OE	3	0	0	3	100	0	100
5	22PSOE02	Startup Fundamentals	OE	3	0	0	3	100	0	100
6	22PSOE03	Prototype Development	OE	3	0	0	3	100	0	100
Ü	22150203		CTICAL	3		0		100		100
7	22MEPS17	Robotics	EE	3	0	0	3	100	0	100
,	2211121 517	TOTAL					21	100	Ŭ	700
			STER VII							700
		SENIE	JIEK VII			/3.3.7	1		.	
S. No.	Course Code	Course Title	Cat	L	Hour T	rs/Wee	С	CA	Iax. M FE	Total
		TH	EORY							10001
1	22ME701	Mechatronics	PC	3	0	0	3	40	60	100
2	22ME702	Finite Element Analysis	PC	3	0	0	3	40	60	100
3	22HS701	Operations Research	HS	3	0	0	3	40	60	100
4	22MEPE4X	Professional Elective – IV	PE	3	0	0	3	40	60	100
•			CTICAL			ŭ		.0	00	100
5	22ME703	Mechatronics Laboratory	PC	0	0	3	1.5	60	40	100
6	22ME704	Simulation Laboratory	PC	0	0	3	1.5	60	40	100
7	22ME705	CAM Laboratory	PC	0	0	3	1.5	60	40	100
8	22ME706	Project – I	EE	0	0	8	4	60	40	100
		TOTAL					20.5			800
			TER VIII					<u> </u>		
C	Comman				Hour	s/Wee	·k	V	Iax. M	arks
S. No.	Course Code	Course Title	Cat	L	T	P	C	CA	FE	Total
		TH	EORY			_		011	12	10001
1	22MEPE5X	Professional Elective – V	PE	3	0	0	3	40	60	100
2	22MEPE6X	Professional Elective – VI	PE	3	0	0	3	40	60	100
3	22MEOE4X	Open Elective –IV	OE	3	0	0	3	40	60	100
			CTICAL	<u> </u>	1			<u> </u>	<u> </u>	
4	22ME801	Project –II	EE	0	0	20	10	120	80	200
		TOTAL					19			500
		GRAND TOTAL					167			

SUMMARY FOR REGULAR STREAM

Course Component			(Credits I	Per Seme	ester			Total	
Course component	I	II	III	IV	V	VI	VII	VIII	Credit	
Humanities and Social Sciences (HS)	1	6			1.5		3		11.5	
Engineering Science (ES)	11.5	6.5	4.5	3					25.5	
Basic Science (BS)	11	8	3						22	
Professional Core (PC)			12.5	17	19		10.5		59	
Professional Electives (PE)						9	3	3	18	
Open Electives (OE)						9		3	12	
Empl. Enhancement Courses (EE)		1	1	1	2	3	4	10	19	
Mandatory Course (One Credit) (MC/HSMC)	1	1							2	
	23.5	21.5	21	21	22.5	21	20.5	16	169	

PROFESSIONAL ELECTIVE COURSES

Code No.	Course		Hours	/Week		Maximum Marks			
	PROFESSIONAL ELECTIVES -	I (VI S	EMES	TER)	Ī				
		L	T	P	C	CA	FE	Total	
22MEPE11	Automobile Engineering	3	0	0	3	40	60	100	
22MEPE12	Composite Materials	3	0	0	3	40	60	100	
22MEPE13	Computer Integrated Manufacturing	3	0	0	3	40	60	100	
22MEPE14	Design of Transmission system	3	0	0	3	40	60	100	
22MEPE15	Energy Conservation in Industries	3	0	0	3	40	60	100	
22MEPE16	Gas Dynamics & Jet Propulsion	3	0	0	3	40	60	100	
22MEPE17	Renewable Energy System	3	0	0	3	40	60	100	
	PROFESSIONAL ELECTIVES -	II (VI S	SEMES	STER)					
22MEPE21	Advanced Strength of Materials	3	0	0	3	40	60	100	
22MEPE22	Energy Efficient Buildings Design	3	0	0	3	40	60	100	
22MEPE23	Engineering System Analysis and Design	3	0	0	3	40	60	100	
22MEPE24	Industrial Engineering and Management	3	0	0	3	40	60	100	
22MEPE25	Internal Combustion Engines	3	0	0	3	40	60	100	
22MEPE26	Machine Drawing	2	3	0	3	40	60	100	
22MEPE27	Power plant Engineering	3	0	0	3	40	60	100	
	PROFESSIONAL ELECTIVES - I	II (VI	SEME	STER)	1				
22MEPE31	Fuels and Combustion	3	0	0	3	40	60	100	
22MEPE32	Maintenance Engineering	3	0	0	3	40	60	100	
22MEPE33	Non-traditional Machining Process	3	0	0	3	40	60	100	
22MEPE34	Professional Ethics and Human Values	3	0	0	3	40	60	100	
22MEPE35	Rapid Product Development Technologies	3	0	0	3	40	60	100	
22MEPE36	Refrigeration & Air Conditioning	3	0	0	3	40	60	100	
22MEPE37	Solar Energy Technology	3	0	0	3	40	60	100	
	PROFESSIONAL ELECTIVES - I	V (VII	SEME	STER)				
22MEPE41	Advanced Decision Modelling Technique	3	0	0	3	40	60	100	
22MEPE42	Automation in Manufacturing	3	0	0	3	40	60	100	
22MEPE43	Cryogenic Engineering	3	0	0	3	40	60	100	
22MEPE44	Fracture Mechanics and Failure Analysis	3	0	0	3	40	60	100	
22MEPE45	Fundamentals of Tribology	3	0	0	3	40	60	100	
22MEPE46	Metal Forming Processes	3	0	0	3	40	60	100	
22MEPE47	Micro and Nano Machining	3	0	0	3	40	60	100	

	PROFESSIONAL ELECTIVES - V	(VIII	SEME	STER)			
22MEPE51	Analysis and Synthesis of Mechanism	3	0	0	3	40	60	100
22MEPE52	Design of Jigs, Fixtures and Press tools	3	0	0	3	40	60	100
22MEPE53	Heat Transfer Problems in Electronics and Instrumentation	3	0	0	3	40	60	100
22MEPE54	Nano Technology	3	0	0	3	40	60	100
22MEPE55	Nuclear Engineering	3	0	0	3	40	60	100
22MEPE56	Thermal Turbo Machines	3	0	0	3	40	60	100
22MEPE57	Total Quality Management	3	0	0	3	40	60	100
	PROFESSIONAL ELECTIVES - V	I (VIII	SEMI	ESTER	(1)			
22MEPE61	Design of Production Tooling	3	0	0	3	40	60	100
22MEPE62	Engineering System Modelling and Simulation	3	0	0	3	40	60	100
22MEPE63	Entrepreneurship Development	3	0	0	3	40	60	100
22MEPE64	Industrial Safety	3	0	0	3	40	60	100
22MEPE65	Introduction to Computational Fluid Dynamics	3	0	0	3	40	60	100
22MEPE66	Marine Engineering	3	0	0	3	40	60	100
22MEPE67	Robotics	3	0	0	3	40	60	100

LIST OF OPEN ELECTIVE COURSES

G NI	Course		G .		Hours	/Week		Maxi	mum N	m Marks	
S.No.	Code	Course	Cat	L	Т	P	С	CA	FE	Total	
		COURSES OFFERED BY THE DEPAR	RTMEN	T OF I	MATH	EMAT	ICS				
1	22MAOE01	Sampling Theory	OE	3	0	0	3	40	60	100	
2	22MAOE02	Numerical Methods	OE	3	0	0	3	40	60	100	
3	22MAOE03	Probability and Queuing Theory	OE	3	0	0	3	40	60	100	
	1	COURSES OFFERED BY THE DEPART	MENT C	F CIV	IL EN	GINEI	ERING	i i			
4	22CEOE01	Environmental Management	OE	3	0	0	3	40	60	100	
5	22CEOE02	Disaster Mitigation and Management	OE	3	0	0	3	40	60	100	
6	22CEOE03	Repair and Rehabilitation of Building Elements	OE	3	0	0	3	40	60	100	
7	22CEOE04	Mechanics of Deformable bodies	OE	3	0	0	3	40	60	100	
	COURSES	OFFERED BY THE DEPARTMENT OF O	COMPU'	TER S	CIENC	CE ANI	D ENG	INEER	ING		
8	22CSOE01	Object Oriented Programming Using C++	OE	3	0	0	3	40	60	100	
9	22CSOE02	Operating Systems	OE	3	0	0	3	40	60	100	
10	22CSOE03	Computer Networks	OE	3	0	0	3	40	60	100	
11	22CSOE04	Python Programming	OE	3	0	0	3	40	60	100	
12	22CSOE05	Java Programming	OE	3	0	0	3	40	60	100	
13	22CSOE06	Computer Organization and Architecture	OE	3	0	0	3	40	60	100	
14	22CSOE07	Data Structures Using C++	OE	3	0	0	3	40	60	100	
15	22CSOE08	Neural Networks	OE	3	0	0	3	40	60	100	
16	22CSOE09	Soft Computing	OE	3	0	0	3	40	60	100	
CO	URSES OFFER	RED BY THE DEPARTMENT OF ELECT	RONICS	S AND	COM	MUNIC	CATIO	N ENGI	INEER	ING	
17	22ECOE01	Fundamentals of Electron Devices	OE	3	0	0	3	40	60	100	
18	22ECOE02	Principles of Modern Communication Systems	OE	3	0	0	3	40	60	100	
19	22ECOE03	Microcontrollers and its applications	OE	3	0	0	3	40	60	100	
20	22ECOE04	Computer Networks	OE	3	0	0	3	40	60	100	
21	22ECOE05	Basics of Embedded Systems	OE	3	0	0	3	40	60	100	
22	22ECOE06	Basics of Internet of Things	OE	3	0	0	3	40	60	100	
23	22ECOE07	Artificial Intelligence and Machine Learning	OE	3	0	0	3	40	60	100	
(COURSES OF	FERED BY THE DEPARTMENT OF ELEC	CTRICA	L AN	D ELE	CTRO	NICS I	ENGINE	EERIN	G	
24	22EEOE04	Renewable Energy Sources	OE	3	0	0	3	40	60	100	
25	22EEOE05	Industrial Drives	OE	3	0	0	3	40	60	100	
26	22EEOE06	Energy Conservation and Management	OE	3	0	0	3	40	60	100	
27	22EEOE07	Electric Vehicles	OE	3	0	0	3	40	60	100	

	COURSES OFFERED BY THE DEPARTMENT OF MECHANICAL ENGINEERING									
28	22MEOE01	Design of Machine Elements and Machining	OE	3	0	0	3	40	60	100
29	22MEOE02	Industrial Engineering	OE	3	0	0	3	40	60	100
30	22MEOE03	Industrial Robotics	OE	3	0	0	3	40	60	100
31	22MEOE04	Power plant Engineering	OE	3	0	0	3	40	60	100
32	22MEOE05	Principles of Management	OE	3	0	0	3	40	60	100
33	22MEOE06	Professional Ethics in Engineering	OE	3	0	0	3	40	60	100
34	22MEOE07	Renewable Sources of Energy	OE	3	0	0	3	40	60	100
35	22MEOE08	Robotic Process Automation	OE	3	0	0	3	40	60	100
36	22MEOE09	Total Quality Management	OE	3	0	0	3	40	60	100
	COUR	SES OFFERED BY THE DEPARTMENT	OF MET	FALLU	JRGIC	AL EN	GINE	ERING		
37	22MTOE01	Foundry and Welding Technology	OE	3	0	0	3	40	60	100
38	22MTOE02	Surface Engineering	OE	3	0	0	3	40	60	100
39	22MTOE03	Design and Selection of Materials	OE	3	0	0	3	40	60	100
40	22MTOE04	Nano Science and Technology	OE	3	0	0	3	40	60	100
41	22MTOE05	Materials for Automobile Components	OE	3	0	0	3	40	60	100

B.E – HONOURS PROFESSIONAL ELECTIVE COURSES – VERTICALS

A student can also optionally register for additional courses (18 credits) and become eligible for the award of B.E. / B.Tech. (Honours) or Minor Degree. For B.E. / B. Tech. (Honours). A student shall register for the additional courses (18 credits) from semester V onwards. These courses shall be from the same vertical or a combination of different verticals of the same programme of study only. For minor degree, a student shall register for the additional courses (18 credits) from semester V onwards. All these courses have to be in a particular vertical from any one of the other programmes.

Vertical - I	Vertical - II	Vertical - III
Clean and Green Energy Technologies	Computational Engineering	Product and Process Development
22MEH101 Hydrogen and Fuel Cell Technologies	22MEH201 Numerical methods in Mechanical Engineering	22MEH301 Precision Engineering
22MEH102 Thermal Management of Electric Vehicle Battery Systems	22MEH202 Advanced Fluid Mechanics	22MEH302 Advanced Materials Technology
22MEH103 Electric and Hybrid Vehicle Technology	22MEH203 Fundamentals of Bio-Mechanics	22MEH303 Additive Manufacturing
22MEH104 Alternate Fuels for IC Engines	22MEH204 Introduction to Machine Learning	22MEH304 Non Destructive Testing and Failure Analysis
22MEH105 Advanced Energy Storage Technologies	22MEH205 Design Optimization and Design Theory	22MEH305 Product Life Cycle Management
22MEH106 Solar Power Plants	22MEH206 Advanced Finite Element Methods	22MEH306 Ergonomics in Design
22MEH107 Materials for Solar Devices	22MEH207 Advanced Computational Fluid Dynamics	22MEH307 Surface Engineering
22MEH108 Design of Solar and Wind Systems	22MEH208 Smart Materials and Structures	22MEH308 Industrial Layout Design and Safety
22MEH109 Fire Engineering and Explosion Control	22MEH209 Design of Pressure vessels	22MEH309 Digital Manufacturing and IOT
22MEH110 Energy Management and Environmental Benefits	22MEH210 Mechanical Vibrations	22MEH310 Smart Mobility and Intelligent vehicles

PROFESSIONAL ELECTIVE COURSES – VERTICALS VERTICAL I - CLEAN AND GREEN ENERGY TECHNOLOGIES

S.	Codo No	Course Title		Hours	/Week		Maximum Marks			
No.	Code No.	Course Title	L	T	P	C	CA	FE	Total	
1.	22MEH101	Hydrogen and Fuel Cell Technologies	3	0	0	3	40	60	100	
2.	22MEH102	Thermal Management of Electric Vehicle Battery Systems 3 0 0 3					40	60	100	
3.	22MEH103	Electric and Hybrid Vehicle Technology	3	0	0	3	40	60	100	
4.	22MEH104	Alternate Fuels for IC Engines	3	0	0	3	40	60	100	
5.	22MEH105	Advanced Energy Storage Technologies	3	0	0	3	40	60	100	
6.	22MEH106	Solar Power Plants	3	0	0	3	40	60	100	
7.	22MEH107	Materials for Solar Devices	3	0	0	3	40	60	100	
8.	22MEH108	Design of Solar and Wind Systems	3	0	0	3	40	60	100	
9.	22MEH109	Fire Engineering and Explosion Control	3	0	0	3	40	60	100	
10.	22MEH110	Energy Management and Environmental Benefits	3	0	0	3	40	60	100	

VERTICAL II - COMPUTATIONAL ENGINEERING

S.	Code No.	Course Title		Hours	/Week		Maximum Marks			
No.	Code No.	Course Title	L	T	P	C	CA	FE	Total	
1.	22MEH201	Numerical methods in Mechanical Engineering	3	0	0	3	40	60	100	
2.	22MEH202	Advanced Fluid Mechanics	3	0	0	3	40	60	100	
3.	22MEH203	Fundamentals of Bio-Mechanics	3	0	0	3	40	60	100	
4.	22MEH204	Introduction to Machine Learning	3	0	0	3	40	60	100	
5.	22MEH205	Design Optimization and Design Theory	3	0	0	3	40	60	100	
6.	22MEH206	Advanced Finite Element Methods	3	0	0	3	40	60	100	
7.	22MEH207	Advanced Computational Fluid Dynamics	3	0	0	3	40	60	100	
8.	22MEH208	Smart Materials and Structures	3	0	0	3	40	60	100	
9.	22MEH209	Design of Pressure vessels	3	0	0	3	40	60	100	
10.	22MEH210	Mechanical Vibrations	3	0	0	3	40	60	100	

VERTICAL III - PRODUCT AND PROCESS DEVELOPMENT

S.	Cada Na	Commo Title		Hours	/Week		Maximum Marks			
No.	Code No.	Course Title	L	T	P	С	CA	FE	Total	
1.	22MEH301	Precision Engineering	3	0	0	3	40	60	100	
2.	22MEH302	Advanced Materials Technology	3	0	0	3	40	60	100	
3.	22MEH303	Additive Manufacturing	3	0	0	3	40	60	100	
4.	22MEH304	Non Destructive Testing and Failure Analysis	3	0	0	3	40	60	100	
5.	22MEH305	Product Life Cycle Management	3	0	0	3	40	60	100	
6.	22MEH306	Ergonomics in Design	3	0	0	3	40	60	100	
7.	22MEH307	Surface Engineering	3	0	0	3	40	60	100	
8.	22MEH308	Industrial Layout Design and Safety	3	0	0	3	40	60	100	
9.	22MEH309	Digital Manufacturing and IOT	3	0	0	3	40	60	100	
10.	22MEH310	Smart Mobility and Intelligent vehicles	3	0	0	3	40	60	100	

DEPARTMENT OF MECHANICAL ENGINEERING MINOR DEGREE COURSES - VERTICALS

S.	Code No.	Course Title		Hours	/Week		Maximum Marks			
No.	Code No.	Course Title	L	T	P	C	CA	FE	Total	
1.	22MEM01	Engineering Thermodynamics	3	0	0	3	40	60	100	
2.	22MEM02	Fluid Mechanics and Machinery	3	0	0	3	40	60	100	
3.	22MEM03	Manufacturing Processes	3	0	0	3	40	60	100	
4.	22MEM04	Materials Engineering	3	0	0	3	40	60	100	
5.	22MEM05	Kinematics of Machinery	3	0	0	3	40	60	100	
6.	22MEM06	Hydraulics and Pneumatics	3	0	0	3	40	60	100	
7.	22MEM07	Design of Machine Elements	3	0	0	3	40	60	100	
8.	22MEM08	Heat and Mass Transfer	3	0	0	3	40	60	100	
9.	22MEM09	Metrology and Quality Control	3	0	0	3	40	60	100	
10.	22MEM10	Dynamics of Machinery	3	0	0	3	40	60	100	

B.E MECHANICAL ENGINEERING - FULL TIME

REGULATION 2022 – SYLLABUS

SEMESTER-I

22MC101	SE	SEMESTER I			
PRE-REQU	ISITE Category	MC	Credit		0
	11 /XV1-	L	Т	P	TH
	Hours/Week	0	0	0	0

INDUCTION PROGRAM (MANDATORY) - 3 WEEKS DURATION

LIST OF EXPERIMENTS

- Physical activity.
- Creative Arts.
- Universal Human Values.
- Literary.
- Proficiency Modules.
- Lectures by Eminent People.
- Visits to local Areas.
- Familiarization to Dept./Branch & Innovations.

Total = 21Days

22M	A101	MATRICES, CALCULUS AND ORDINARY DIFFE EQUATION	ERENTIAL	S	EME	STER	RI			
PRE	-REQU	ISITE:	Category	BS	Cre	dit	4			
ъ.	1 2th 1		TT /XX/ 1	L	Т	P	TH			
Basic	12 th leve	l Matrices, Differential Calculus, Integral Calculus and ODE.	Hours/Week	3	1	0	4			
Cour	rse Obje	ctives:								
1.	To know	w the use of matrix algebra needed by engineers for practical applica	ations.							
2.	2. To understand effectively both the limit definition and rules of differentiation.									
3.	To fami	liarize in solving maxima and minima problems in two variables.								
4.	4. To obtain the knowledge of multiple integrations and their related applications.									
5.	5. To obtain the knowledge to solve second order differential equations with constant and variable coefficients									
Uı	nit I	MATRICES		9	3	0	12			
Ur Repre	gonal trar it II esentation	rem (excluding proof) – Diagonalization of Matrices - Reductionsformation. DIFFERENTIAL CALCULUS of functions - Limit of a function - Continuity - Derivatives - Difference of the property of the continuity - Derivatives - Difference of the continuity - Derivatives - Deriv	•	9	3	0	12			
	it III	FUNCTIONS OF SEVERAL VARIABLES	S	9	3	0	12			
		ves – Euler's theorem for homogenous functions – Total Derivativ d of Lagrangian multipliers- Taylor's series.	res -Jacobians – M	axima,	Minim	a and	Saddle			
Un	it IV	MULTIPLE INTEGRALS		9	3	0	12			
		rals- Double integrals – Change of order of integration in double cation to Areas – Evaluation of Triple integrals – Application to volu		e of var	riables	(Carte	sian to			
Ur	nit V	ORDINARY DIFFERENTIAL EQUATION	NS	9	3	0	12			
Leger		linear differential equations with constant and variable coeffic ear equation - Method of variation of parameters -Simultaneou	-	_			-			
			Total ((45L +1	15T) =	60 P	eriods			

Text	Books:
1.	Grewal. B.S, "Higher Engineering Mathematics", 43 rd Edition, KhannaPublications, Delhi, 2015.
2.	Jain R.K. and Iyengar S.R.K., "Advanced Engineering Mathematics", 3rd Edition, Narosa Publications, New Delhi, 2007.
Refe	rence Books:
1.	James Stewart, "Essential Calculus", 2 nd Edition Cengage Learning, New Delhi, 2014.
2.	P. Kandasamy, K. Thilagavathy and K. Gunavathy," Engineering Mathematics (For I year B.E., B. Tech)", 9 th Edition, S. Chand & Co. Ltd. New Delhi, 2010.
3.	Srimanta pal and Subath.C. Bhumia, "Engineering Mathematics", Oxford university publications, New Delhi, 2015
4.	Ewinkreyzig, "Advanced Engineering Mathematics", 9th edition, John Wiley & Sons, 2007.
5.	Siva RamakrishnaDas.P, Ruknmangadachari.E. "Engineering Mathematics", 2 nd edition, Pearson, Chennai & Delhi, , 2013.

	RSE OUTCOMES: completion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Learn the fundamental knowledge of Matrix theory.	Understand
CO2	Use both the limit definition and rules of differentiation to differentiable functions.	Apply
СОЗ	Apply differentiation to solve maxima and minima problems.	Apply
CO4	Apply integration to compute multiple integrals, area, volume, integrals in polar coordinates, in addition to a change of order and change of variables.	Apply
CO5	Apply various techniques in solving differential equations.	Apply

COU	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	0	2	0	0	0	0	0	0	0	0	2	0	0
CO2	3	2	0	2	0	0	0	0	0	0	0	0	2	0	0
CO3	3	2	0	2	0	0	0	0	0	0	0	0	2	0	0
CO4	3	2	0	2	0	0	0	0	0	0	0	0	2	0	0
CO5	3	2	0	2	0	0	0	0	0	0	0	0	2	0	0
Avg	3	2	0	2	0	0	0	0	0	0	0	0	2	0	0
	3/2/1 – indicates strength of correlation (3 – High, 2 – Medium, 1 – Low)														

22CY	Y101	ENGINEERING CHEMISTRY			SEME	STER 1	[
PRE	-REQ	JISITE:	Category	BS	Cre	edit	4
ъ .	OI.	• ,	**	L	Т	P	C
Basic	c Chen	nstry	Hours/Week	3	1	0	4
Cour	se Ob	ectives:		•			
1. I	Basic Pr	rinciples of Spectroscopy and their applications.					
2. 1	Knowle	dge of different methods for water analysis and purification & l	Nanomaterial and its	applicat	ion.		
3. Y	Various	adsorption technics and basic knowledge of Phase equilibria.					
4. I	Principl	es of electrochemistry, electrochemical cells, corrosion, and its	control.				
5. I	Basis of	polymer preparations and applications and enhancement of the	quantity and quality	of fuels	·.		
Un	it I	SPECTROSCOPIC TECHNIQUES		9	3	0	12
instru Flame	mentati e photor	t's law (problem) -UV visible spectroscopy: Principle, Chro on (No applications). IR spectroscopy: Principles -instrumentat metry -principle -instrumentation -estimation of sodium by fla strumentation -estimation of nickel by atomic absorption spectr	tion and applications ame photometer. At	of IR in	H ₂ O, an	nd CO ₂ .	
Uni	it II	WATER TECHNOLOGY AND NANO TECH	NOLOGY	9	3	0	12
and s	sludge)	water – types – expression of hardness – units – estimation of – treatment of boiler feed water – Internal treatment (ph external treatment – Ion exchange process, zeolite process – decoupled to the contract of the contrac	osphate, colloidal,	sodium	alumina	ite and	calgor

Nano chemistry – preparations and properties of nanomaterials – nanorods – nanowires – nanotubes – carbon nano tubes and their application.

Unit III SURFACE CHEMISTRY AND PHASE EQUILIBRIA 9 3 0 12

Adsorption: Types of adsorption – adsorption of gases on solids – adsorption of solute from solutions – adsorption isotherms – Freundlich's adsorption isotherm – Langmuir's adsorption isotherm.

Phase rule: Introduction, definition of terms with examples, one component system -water system - reduced phase rule - thermal analysis and cooling curves - two component systems - lead-silver system - Pattinson process.

Unit IV ELECTROCHEMISTRY 9 3 0 12

Electrode Potential- Oxidation and Reduction Potentials - Electrochemical series - Significance and application - Electrochemical cell, Cell potential, derivation of Nernst equation for single electrode potential, numerical problems on E, E_0 , and E_{cell} - numerical problems. Electrochemical theory of corrosion with respect to iron. Factors influencing the corrosion rate: physical state of the metal, nature of the metal, area effect, over voltage, pH, temperature, and nature of the corrosion product. Types of corrosion: galvanic series; (i) Differential aeration corrosion- oxygen concentration cell, (ii) Stress corrosion-explanation-caustic embrittlement. Corrosion control by i) Cathodic protection- sacrificial anode and impressed current methods i) Protective coatings-metal coatings- galvanizing and tinning.

Unit V POLYMERS AND FUELS 9 3 0 12

Polymers – definition – polymerization – types – addition and condensation polymerization – free radical polymerization mechanism – plastics, classification – preparation, properties and uses of PVC, Teflon, polycarbonate, polyurethane, nylon-6,6, PET – Rubber- vulcanization of rubber, synthetic rubbers – butyl rubber, SBR – biopolymers – Nylon-2-Nylon-6 and PHBV

Fuels - classification with examples, calorific value-classification (HCV & LCV), and determination of calorific value of solid and liquid fuels using Bomb calorimeter- Petroleum cracking -fluidized bed catalytic cracking. Knocking in IC engine, its ill effects and prevention of knocking. Anti-knocking agent: Leaded and unleaded petrol.

Total (45L+15T) = 60 Periods

Tex	xt Books:							
1.	S. S. Dara and S. S. Umare, —A Textbook of Engineering Chemistry S. Chand & Company LTD, New Delhi, 2015							
2.	P. C. Jain and Monika Jain, —Engineering Chemistry Dhanpat Rai Publishing Company (P) LTD, New Delhi, 2015							
3.	S. Vairam, P. Kalyani and Suba Ramesh, —Engineering Chemistry Wiley India PVT, LTD, New Delhi, 2013.							
Ref	Reference Books:							
1.	Friedrich Emich, —Engineering Chemistry Scientific International PVT, LTD, New Delhi, 2014.							
2.	PrasantaRath, —Engineering Chemistry Cengage Learning India PVT, LTD, Delhi, 2015.							
3.	ShikhaAgarwal, — Engineering Chemistry-Fundamentals and Applications Cambridge University Press, Delhi, 2015.							
E-H	E-References:							
1	www.onlinecourses.nptel.ac.in/							
2	www.ePathshala.nic.in							

	RSE OUTCOMES: ompletion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Remember	
CO2	Paraphrase the different methods for water analysis & purification and Nanomaterial & its applications	Understand
CO3	Apply the various adsorption technics and basic knowledge of Phase equilibria	Apply
CO4	Integrate the principles of electrochemistry, electrochemical cells, corrosion, and its control	Create
CO5	Assess the basis of polymer preparations & applications and enhancement of the quantity & quality of fuels.	Evaluate

COU	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	0	3	0	0	0	0	0	0	0	0	3	1	1
CO2	3	2	0	1	0	2	0	0	0	0	0	0	3	1	1
CO3	3	1	0	1	0	0	0	0	0	0	0	0	2	1	1
CO4	2	1	0	1	0	2	0	0	0	0	0	0	2	3	2
CO5	3	2	0	3	0	2	0	0	0	0	0	0	1	1	1
Avg	2.8	1.8	0	1.8	0	1.2	0	0	0	0	0	0	2.2	1.4	1.2
			3/2	/ 1 – inc	dicates	strengt	h of cor	relatio	1 (3 – H	ligh, 2 –]	Medium,	1 – Low	7)		

22EE	101	BASIC ELECTRICAL AND ELECTRONICS EN	NGINEERING		SEMESTER I			
PRE-	REQU	JISITE	Category	ES	Credit		4	
				L	Т	P	С	
			Hours/Week	3	1	0	4	
Cour	se Obj	ectives:		1	I.		l	
1.	Γο unde	erstand and analyze basic electric circuits.						
2.	To stud	y working principle of electrical machines and transformer.						
3.	To stud	y basics of electronic devices and operational amplifier.						
4.	Γο unde	erstand the concepts of electrical installations.						
UNI	I TI	DC CIRCUITS		9	3	0	12	
		lysis of simple electrical circuits with DC excitation using fu theorems.	ndamentai laws – Si	uperpositi	ion theor	em, The	venin's	
	T II uction	AC CIRCUITS to single phase AC circuits - Representation of sinusen-Analysis of single-phase ac circuits consisting of RL, RC,	-				-	
Introd	T II uction entation ve pow		RLC combinations	peak and (series a	RMS nd parall	values, el), real	phasoi power,	
Introduce representation	T II uction entation we pow ctions.	to single phase AC circuits - Representation of sinusen-Analysis of single-phase ac circuits consisting of RL, RC,	RLC combinations its, voltage and cur	peak and (series a	RMS nd parall	values, el), real	phasoi power	
Introduce repressor reactive connective UNITAL DC Muthree-p	T II uction entation we pow ctions. T III Iotor: C phase in	to single phase AC circuits - Representation of sinuscin-Analysis of single-phase ac circuits consisting of RL, RC, er, apparent power, power factor. Three phase AC circuit	RLC combinations its, voltage and cur ORMERS of of DC shunt motor and its applications –	peak and (series and rent relation of the series and rent relation of the series of th	I RMS nd parall tions in 3 truction mers: Ide	values, el), real star and	phason power, d delta	
Introduce repressor reactive connective UNITAL DC Muthree-p	T II uction entation we pow ctions. T III Iotor: C phase in ormer, C	to single phase AC circuits - Representation of sinuscin- Analysis of single-phase ac circuits consisting of RL, RC, er, apparent power, power factor. Three phase AC circuits construction, operation, types and applications, Speed control aduction motors - Working of single-phase induction motor and	RLC combinations its, voltage and cur ORMERS ol of DC shunt motor its applications — ors, Introduction to T	peak and (series and rent relation of the series and rent relation of the series of th	I RMS nd parall tions in 3 truction mers: Ide	values, el), real star and	phason power d delta	
Introduce representation of the connect of the conn	T II uction entation we pow ctions. T III lotor: C phase in ormer, C T IV uction	to single phase AC circuits - Representation of sinuscin- Analysis of single-phase ac circuits consisting of RL, RC, etc., apparent power, power factor. Three phase AC circuits ELECTRICAL MACHINES AND TRANSFORMSTRUCTION, operation, types and applications, Speed control aduction motors - Working of single-phase induction motor and Construction and working, losses and efficiency in transformer	RLC combinations its, voltage and cur ORMERS ol of DC shunt motor and its applications — ors, Introduction to T ode, Zener diode an rinciple of operatio	peak and (series and rent relative peak) or - Constitution Transfort here phase peak and V-I characteristics and very peak and	RMS nd parall tions in 3 truction mers: Ide se transfo	values, el), real star and on and wor eal and pormers o tics- BJT	phasor power, d delta 12 king of ractical	
Introduce representation of the connect of the conn	TII uction entation we pow ctions. TIII Lotor: C phase in ormer, C TIV uction - CC con ing Am	to single phase AC circuits - Representation of sinuscin- Analysis of single-phase ac circuits consisting of RL, RC, etc., apparent power, power factor. Three phase AC circuits ELECTRICAL MACHINES AND TRANSFORMSTRUCTION, operation, types and applications, Speed control aduction motors - Working of single-phase induction motor at Construction and working, losses and efficiency in transforme BASICS ELECTRONICS SYSTEM - Basic structure of semiconductors devices - PN junction die figuration and working principle. Operational Amplifier-principle.	RLC combinations its, voltage and cure of the combinations of the combinations of the combination of the com	peak and (series and rent relative peak) or - Constitution Transfort here phase peak and V-I characteristics and very peak and	RMS nd parall tions in 3 truction mers: Ide se transfo	values, el), real star and on and wor eal and pormers o tics- BJT	phason power d delta 12 king or ractica 12 \(\text{T} - CE	
Introduce reactive connection of the connection	TII uction entation we power ctions. FIII Intornet Commer, Commer, Commer, Commer Commer, Commer C	to single phase AC circuits - Representation of sinuscin- Analysis of single-phase ac circuits consisting of RL, RC, etc., apparent power, power factor. Three phase AC circuits Construction, operation, types and applications, Speed control aduction motors - Working of single-phase induction motor at Construction and working, losses and efficiency in transforme BASICS ELECTRONICS SYSTEM - Basic structure of semiconductors devices - PN junction die figuration and working principle. Operational Amplifier-pupilifier, Non inverting Amplifier, summing amplifier and different construction and different construction and more construction and working principle.	RLC combinations its, voltage and cursons its, voltage and cursons of the composition of	peak and (series and reent relative peak) 9 or - Constitution of the peak and value peak and call the peak and call th	RMS nd parall tions in 3 truction mers: Ide se transfo aracterist cteristics 3 bles – E	values, el), real star and o and wor eal and pormers o tics- BJT a, Applic	phason power, d delta 12 king of ractical 12 T – CE eations-	

Te	Text Books:							
1.	Muthu Subramaniyam, R., Salivaganan, R., and Muralidharan, K. A., "Basic Electrical and Electronics Engineering", Second Edition, Tata McGraw Hill, 2010.							
2.	Kothari, D. P., and Nagrath, I. J., "Basic Electrical Engineering", Tata McGraw Hill, 2010.							
3.	Kulshreshtha, D.C., "Basic Electrical Engineering", Tata McGraw Hill, 2009.							
Re	ference Books:							
1.	Bobrow, L. S., "Fundamentals of Electrical Engineering", Oxford University Press, 2011.							
2.	Hughes, E., "Electrical and Electronics Technology", Pearson, 2010.							

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:						
CO1	Analyze the DC circuits using fundamental laws and theorems.	Analyze					
CO2	Analyze the single and three phase AC circuits.	Analyze					
CO3	Recognize the working principle of electrical machines and transformers.	Understand					
CO4	Recognize the fundamentals and characteristics of diode, BJT and operational amplifier.	Understand					
CO5	Demonstrate the concept of electrical installations.	Apply					

COU	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	1	0	0	0	0	0	0	0	0	1	1	0	0	0
CO2	1	1	0	0	0	0	0	0	0	0	1	1	0	0	0
CO3	1	0	0	0	0	0	0	0	0	0	1	1	0	0	0
CO4	1	0	0	0	0	0	0	0	0	0	1	1	0	0	0
CO5	1	0	0	0	0	0	0	0	0	0	1	1	0	0	0
Avg	1	0.4	0	0	0	0	0	0	0	0	1	1	0	0	0
			3/2	/ 1 – in	dicates	strengt	h of cor	relatio	1 (3 – H	ligh, 2 –	Medium	, 1 – Lov	v)		

22M	E101	ENGINEERING GRAPHICS AND DE	SIGN		SEME	STER I			
PRE	-REQI	JISITE:	Category	ES	Cre	edit	3		
1. Stu	dents sl	nould know about the basics of drawings.	Hours/Week	L	T	P	TH		
2. Stu	dents sl	nould be able to construct geometric shapes.	Hours/ week	1	0	4	5		
Cour	se Ob	ectives:	•						
1.	1. To impart knowledge on graphical skills for communications of concepts, ideas and design of engineering products and to provide exposure to design.								
2.	To ex	pose them to existing national standards related to technical	drawings.						
3.	To un	derstand the basics of points, lines, planes and solids.							
4.	To un	derstand the basics of the surface of object.							
5.	To ex	pose them to isometric and perspective views of simple solid	s.						
UN	IT I	PROJECTION OF POINTS, LINES AND PLAN	E SURFACES	3	0	12	15		
locate	ed in th ar lamin	ciples of orthographic projection- Projection of points, loc e first quadrant – Determination of true lengths and true ha inclined to both reference planes.	_	ection of	f polygo	nal surfa	ace and		
UNI	II II	PROJECTION OF SOLIDS		3	0	12	15		
		simple solids like prisms, pyramids, cylinder and cone wher to one reference plane by change of position method.	n the axis is perpend	dicular to	one refe	erence pla	ane and		
UNI	T III	SECTION OF SOLIDS AND DEVELOPMENT OF	OF SURFACES	3	0	12	15		
other Devel	– solids lopment	above solids in a simple vertical position by cutting planes inclined position with cutting planes parallel to one reference of lateral surfaces of simple and truncated solids — Prismass of solids with square and cylindrical cutouts, perpendicular	ce plane- Obtaining ns, pyramids cylind	true shap	e of the	section.			
UNI	T IV	ORTHOGRAPHIC AND ISOMETRIC PRO	JECTION	3	0	12	15		
dimer Princi	Orthographic Projection - Visualization concepts and Freehand sketching - Visualization principles - Representation of three-dimensional objects - Layout of views - Freehand sketching of multiple views from pictorial views of object. Principles of isometric projection – isometric scale - isometric projections of simple solids, truncated prisms, pyramids, cylinders and cones.								
UN	IT V	PERSPECTIVE PROJECTION		3	0	12	15		
Persp	ective p	rojection of prisms, pyramids and cylinders by visual ray and	d vanishing point m	ethods.					
	Total $(15L+60P) = 75$ Periods								

Text	Books:
1.	Bhatt, N.D., Panchal V M and Pramod R. Ingle, "Engineering Drawing", Charotar Publishing House, 53rd Edition, 2014.
2.	Parthasarathy, N. S. and Vela Murali, "Engineering Drawing", Oxford University Press, 2015
Refe	rence Books:
1.	Agrawal, B. and Agrawal C.M., "Engineering Drawing", Tata McGraw, N.Delhi, 2008.
2.	Gopalakrishna, K. R., "Engineering Drawing", Subhas Stores, Bangalore, 2007.
3.	Natarajan, K. V., "A text book of Engineering Graphics", 28thEd., Dhanalakshmi Publishers, Chennai, 2015.
4.	Shah, M. B., and Rana, B. C., "Engineering Drawing", Pearson, 2 nd Ed., 2009.
5.	Venugopal, K. and Prabhu Raja, V., "Engineering Graphics", New Age,2008.

E-Re	E-References:						
1.	https://nptel.ac.in/courses/112102304						
2.	https://home.iitk.ac.in/~anupams/ME251/EDP.pdf						
3.	https://static.sdcpublications.com/pdfsample/978-1-58503-610-3-1.pdf						

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:						
CO1	Familiarize with the fundamentals and standards of engineering graphics.	Understand					
CO2	Ability to understand the fundamental concepts of projection of points, lines and planes.	Analyze					
CO3	Project the solids and section of solids.	Analyze					
CO4	Familiarize and develop the lateral surfaces of solids	Analyze					
CO5	Visualize and project the orthographic, isometric and perspective sections of simple solids.	Analyze					

COU	COURSE ARTICULATION MATRIX														
CO/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1	0	0	0	0	0	0	0	0	0	0	3	1	0
CO2	3	1	0	0	0	0	0	0	0	0	0	0	3	1	0
CO3	3	1	0	0	0	0	0	0	0	0	0	0	3	1	0
CO4	3	1	0	0	0	0	0	0	0	0	0	0	3	1	0
CO5	3	1	0	0	0	0	0	0	0	0	0	0	3	1	0
Avg	3	1	0	0	0	0	0	0	0	0	0	0	3	1	0
			3 / 2	2 / 1 – iı	ndicates	strengt	h of co	relation	(3 – H	igh, 2 – N	Medium,	1 – Low))		

22CS	101	PROBLEM SOLVING AND C PROGRAM	IMING	SEMESTER I				
PRE-	REQ	UISITE	Category	ES	Cre	edit	3	
			Hours/Week	L	T	P	C	
			Hours/ week	3	0	0	3	
Cour	se Ob	jectives:						
1.	To us	e general problem-solving techniques to device solutions to pro	oblems					
2.		nderstand the input-output relations of software involved in table code.	n developing and c	onvertin	g a C	program	to a	
3.	To pr	ovide complete knowledge about the programming concepts of	f C language.					
UNI	ΤΙ	SYSTEM SOFTWARE, PROBLEM SOLVING PROGRAMMING	G, AND C	9	0	0	9	
-	-	rogramming language – Machine level language – role of syst Operating System) in developing and executing a C program	em software (Editor	, Compi	ler, Asse	embler,	Linker	
Variab	oles ar	ning: Character set – Case sensitivity – Identifiers – Keyword their associated information – Formed and unformed constructions and Associativity – Pre-processor directives (#inches)	sole input-output st	atements	s – Typ	e conve		
	-	blem-solving Techniques: Algorithm – Flow-chart – Pseudocors and writing their equivalent C programs.	ode – Developing s	olution 1	for prob	lems in	volvin	
	1							
UNI'.		CONTROL STATEMENTS blem-solving Techniques: Representing Decision making: if-	else statement – sw	9	0 e statem	0 nent – I	9 oonin	
Generate statem and Ps	al prolent: for seudocommunication and seudoc	blem-solving Techniques: Representing Decision making: if- or loop, while loop and do-while loop – Branching statements	s: break and continu	vitch-cas ue with A	e statem Algorith	nent – L nm, Flow le loop a	Looping v-char and do	
Generate statem and Ps	al problem all pro	blem-solving Techniques: Representing Decision making: if- or loop, while loop and do-while loop – Branching statements ode hing: Decision Making: if-else statement – switch case statement Branching statements: break and continue – Nesting solutions for problems involving control statements using	s: break and continu nt - Looping stateme g General problem	vitch-cas ue with A	e statem Algorith	nent – L nm, Flow le loop a	Looping v-chart and do	
Gener statem and Ps C prog while Develor equiva UNIT One-d Proces	al products for seudoconditions of the control of t	blem-solving Techniques: Representing Decision making: if- or loop, while loop and do-while loop – Branching statements ode ting: Decision Making: if-else statement – switch case statement Branching statements: break and continue – Nesting solutions for problems involving control statements using programs	s: break and continuent - Looping statement GS - Processing - Point ion - C Library supp	vitch-cas ue with -solving -solving -solving ers:Decl	e statem Algorith Doop, whi technic	nent – Lam, Flow ale loop a ques an o	Looping v-chart and do d their	
Gener statem and Ps C prog while Develor equiva UNIT One-d Proces	al product for seudocondition of the control of the	blem-solving Techniques: Representing Decision making: if- or loop, while loop and do-while loop – Branching statements ode ting: Decision Making: if-else statement – switch case statement Branching statements: break and continue – Nesting solutions for problems involving control statements using programs ARRAYS, POINTERS, AND STRING ional and two-dimensional Arrays: Declaration – Initialization – relation between pointers and arrays – Strings – String operations olutions for problems involving arrays, pointers and strings us	s: break and continuent - Looping statement GS - Processing - Point ion - C Library supp	vitch-cas ue with -solving -solving -solving ers:Decl	e statem Algorith Doop, whi technic	nent – Lam, Flow ale loop a ques an o	Looping v-chart and do d thei	
Gener statem and Ps C prog while Developed equivalent UNIT One-depuivalent UNIT Function mechal Developed Developed Equivalent Control of the	al problem: for seudocondinate of the control of th	blem-solving Techniques: Representing Decision making: if- or loop, while loop and do-while loop – Branching statements ode ting: Decision Making: if-else statement – switch case statement Branching statements: break and continue – Nesting solutions for problems involving control statements using programs ARRAYS, POINTERS, AND STRING tional and two-dimensional Arrays: Declaration – Initialization – relation between pointers and arrays – Strings – String operations solutions for problems involving arrays, pointers and strings us programs.	s: break and continuent - Looping statement - Looping statement g General problem SS - Processing - Point ion - C Library supposing General problem types and function of the files	ent: for logarithms of the solving o	e statem Algorith Doop, whit technic technic aration- tring has g Techn ns – Par	nent – Lam, Flow ale loop a ques and transfer of the control of th	cooping v-chart and do d their gration and their grassing	
Gener statem and Ps C prog while Development of the Control of the	al products for seudocondition of the control of th	blem-solving Techniques: Representing Decision making: if- or loop, while loop and do-while loop – Branching statements ode ting: Decision Making: if-else statement – switch case statement Branching statements: break and continue – Nesting solutions for problems involving control statements using programs ARRAYS, POINTERS, AND STRING ional and two-dimensional Arrays: Declaration – Initialization – relation between pointers and arrays – Strings – String operations solutions for problems involving arrays, pointers and strings use programs. FUNCTIONS Library functions and user-defined functions – Function protor – Recursion – Storage classes – Working with multiple source solutions for problems involving functions using General property in the solution of the problems involving functions using General property in the solution of the problems involving functions using General property in the solution of the problems involving functions using General property in the solution of the problems involving functions using General property in the solution of the problems involving functions using General property in the solution of the property in the property in the solution of the property in the prope	s: break and continuent - Looping statement - Looping statement g General problem SS - Processing - Point ion - C Library supposing General problem etypes and function of the files roblem-solving tech	ent: for logarithms of the solving o	e statem Algorith Doop, whit technic technic aration tring har g Techr 0 ns – Par and their	nent – Lam, Flow le loop a ques an o le loop a le loop a ques an o le loop a loop a le	cooping v-chart and do d their station and their spassing alent (
Gener statem and Ps C prog while Development of the Control of the	al problem: for seudocontent: for seudocontent: for seudocontent Content Conte	blem-solving Techniques: Representing Decision making: if- or loop, while loop and do-while loop – Branching statements ode ting: Decision Making: if-else statement – switch case statement Branching statements: break and continue – Nesting solutions for problems involving control statements using programs ARRAYS, POINTERS, AND STRING ional and two-dimensional Arrays: Declaration – Initialization – relation between pointers and arrays – Strings – String operations solutions for problems involving arrays, pointers and strings using programs. FUNCTIONS Library functions and user-defined functions – Function proton – Recursion – Storage classes – Working with multiple source	s: break and continuent - Looping statement - Looping statement g General problem SS - Processing - Point ion - C Library supposing General problem stypes and function of the files roblem-solving technique for the solving te	ent: for logarithms of the solving o	e statem Algorith Doop, whit technic	nent – Lam, Flow ale loop a ques and the loop a ques are a ques a ques are a ques a ques a que a	cooping v-chart and do d their station and their spassing alent (

Text	Books:
1.	Balagurusamy E, "Programming in ANSI C", Tata McGraw-Hill, 8th Edition, 2022.
2.	Yashvant P. Kanetkar, "Let Us C", BPB Publications, 2016.
Refe	rence Books:
1.	Venugopal, "Mastering C", Second Edition", Tata McGraw-Hill. 2006
2.	R. G. Dromey, "How to solve it by computers", Prentice Hall, 2007
3.	Greg Perry and Dean Miller, "C Programming Absolute Beginner's Guide", Third Edition, Que Publishing, 20123
4.	Brain W.Kernighan and Ritchie Dennis, "The C Programming Language", Second Edition, Pearson, 1988.
E-R	eference:
1.	https://www.learn-c.org/
2.	https://www.programiz.com/c-programming

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:						
CO1	Explain the concepts of C Programming and roles of system software in programming	Remember & Understand					
CO2	Use general problem-solving techniques to develop solution to problems	Apply					
СОЗ	Apply the concepts of C Programming to develop solutions by writing C programs	Apply& Analyze					

COU	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	3	0	0	0	0	0	0	0	0	3	1	0	0
CO2	2	1	3	0	2	0	0	0	0	0	0	3	2	0	0
CO3	2	1	3	0	2	0	0	0	0	0	0	3	3	0	0
Avg	2	1	3	0	1.3	0	0	0	0	0	0	3	2	0	0
	3/2/1 – indicates strength of correlation (3 – High, 2 – Medium, 1 – Low)														

22MC102	தமிழர்மரபு		S	r I		
PREREQU ISITES	Category	HSMC	Cr	edit		1
Basics of Tamil	Hours/Week	L	Т	P	•	TH
		1	0	0)	1
அலகு I	மொழி மற்றும் இலக்கியம்	3	0	0)	3
செவ்விலக் சங்கஇலக் தமிழ்க்காப் ஆழ்வார்கள் தமிழில்நவீ	பெத்தில்பகிர்தல்அறம் – திருக்குறளில்மே பியங்கள், தமிழகத்தில்சமணபௌத்தசமயங்கள	சமயச் லாண்ன ரின்தாக ற்றிலக்	சார்ட மைக்க க்கம்- கியா	மற்ற கருத் பக் ங்கச	த் த் தி ள்	ன்மை – அக்கள் – இலக்கியம், –
அலகு II	மரபு – பாறைஓவியங்கள்முதல்நவீன ஓவியங் வரைசிற்பக்கலை	கள்	3	0	0	3
பழங்குடியி தேர்செய்யும குமரிமுனை	னர்மற்றும்தயாரிக்கும்கைவினைப்பொருட்கள்,	நாட் தங்கம்	பொம் டுப்ப , பன	ை புறத் ற,	_ நெ வீ	தய்வங்கள்-
அலகு III	நாட்டுப்புறக்கலைகள்மற்றும்வீரவிளையாட்டு	ிகள்	3	0	0	3
தெருக்கூத்த தோல்பானை	து, கரகாட்டம், வில்லுப்பாட்டு, கணிட வக்கூத்து, சிலம்பாட்டம், வளரி, புலியாட்டம், தமிழ		. –	ளu	_	ட் விலாட்டம், ட்டுகள்.
அலகு IV	தமிழர்களின் திணைக்கோட்பாடுக ள்		3	0	0	3
தொல்காப்ப தமிழர்கள் – சங்ககால	ன்தாவரங்களும், பியம்மற்றும்சங்கஇலக்கியத்தில்அகம்மற்றும்புறச் பாற்றியஅறக்கோட்பாடு – சங்ககாலத்தில்தமிழக நகரங்களும்துறைமுகங்களும் – சங்ககாலத்தில் நாடுகளில்சோழர்களின்வெற்றி.	ந்கோட் த்தில்எ	ழுத்த	தறி	வுப்	•
அலகு V	இந்தியதேசியஇயக்கம்மற்றும்இந்தியபண்பா ற்குத்தமிழர்களின்பங்களிப்பு	тட்டி	3	0	0	3
இந்தியாவி இந்தியமரு	தலைப்போரில்தமிழர்களின்பங்கு எபிறப்பகுதிகளில்தமிழ்ப்பண்பாட்டின்தாக்கம் - த்துவத்தில், சித்தமருத்துவத்தின்பங்கு – கல்வெட்டு கங்களின்அச்சுவரலாறு.					_ இயக்கம் _ துப்படிகள் _
				T	ota	l= 15 Periods

ı	Text Books / Reference Books:			
1	தமிழகவரலாறு – மக்களும்பண்பாடும் – கே. :தமிழ்நாடுபாடநூல்மற்றும்கல்வியியல்பணிகள்கழகம்.	கே.	பிள்ளை	(வெளியீடு
2	கணினித்தமிழ் – முனைவர்இல.சுந்தரம்.(விகடன்பிரசுரம்)			

- 3 கீழடி வைகைநதிக்கரையில்சங்ககாலநகரநாகரிகம்(தொல்லியல்துறைவெளியீடு)
- 4 பொருநை ஆற்றங்கரைநாகரிகம்(தொல்லியல்துறைவெளியீடு)

22MC102			Seme	ester I		
PREREQUISITE	S	Category	BS	Cre	1	
Basics of Tamil			L	Т	P	TH
		Hours/Week	1	0	0	1
Unit I	LANGUAGE AND LITERATURI	E	3	0	0	3
Secular Nature of Sa	es in India - Dravidian Languages - Tamil as a Classic angam Literature - Distributive Justice in Sangam Liter apact of Buddhism & Jainism in Tamil Land - Bakthi L	ature - Manageme	ent Prir	nciples i	n Thirt	ıkural -
minor Poetry - Deve	lopment of Modern literature in Tamil - Contribution of I			•		
minor Poetry - Deve	•	Bharathiyar and Bl		•	0	3
Unit II Hero stone to mode Terracotta sculptures	lopment of Modern literature in Tamil - Contribution of H HERITAGE - ROCK ART PAINTINGS TO M	Bharathiyar and Bl IODERN ART rafts - Art of tem Making of musica	3 apple can be	dhasan. 0 r makin	g N	3 Massive
Unit II Hero stone to mode Terracotta sculptures	HERITAGE - ROCK ART PAINTINGS TO M — SCULPTURE ern sculpture - Bronze icons - Tribes and their handicas, Village deities, Thiruvalluvar Statue at Kanyakumari,	Bharathiyar and Bl IODERN ART rafts - Art of tem Making of musica	3 apple can be	dhasan. 0 r makin	g N	3 Massive
Unit II Hero stone to mode Terracotta sculptures Parai, Veenai, Yazh Unit III	HERITAGE - ROCK ART PAINTINGS TO M — SCULPTURE ern sculpture - Bronze icons - Tribes and their handicus, Village deities, Thiruvalluvar Statue at Kanyakumari, and Nadhaswaram - Role of Temples in Social and Economic FOLK AND MARTIAL ARTS eattam, VilluPattu, KaniyanKoothu, Oyillattam, Leather	Bharathiyar and Bl IODERN ART rafts - Art of tem Making of musica omic Life of Tami	anathic specification of the s	0 makin ments -	g Mridh	3 Massive angam,

Flora and Fauna of Tamils & Aham and Puram Concept from Tholkappiyam and Sangam Literature - Aram Concept of Tamils - Education and Literacy during Sangam Age - Ancient Cities and Ports of Sangam Age - Export and Import during Sangam Age - Overseas Conquest of Cholas.

Unit V CONTRIBUTION OF TAMILS TO INDIAN NATIONAL 3 MOVEMENT AND INDIAN CULTURE	0	0	3
--	---	---	---

Contribution of Tamils to Indian Freedom Struggle - The Cultural Influence of Tamils over the other parts of India - Self-Respect Movement - Role of Siddha Medicine in Indigenous Systems of Medicine - Inscriptions & Manuscripts - Print History of Tamil Books.

Total = 15 Periods

Tex	at Books:
1	Social Life of Tamils (Dr.K.K.Pillay) A joint publication of TNTB & ESC and RMRL – (in print)
2	Social Life of the Tamils - The Classical Period (Dr.S.Singaravelu) (Published by: International Institute of Tamil Studies.
3	Historical Heritage of the Tamils (Dr.S.V.Subatamanian, Dr.K.D. Thirunavukkarasu) (Published by: International Institute of Tamil Studies).
4	The Contributions of the Tamils to Indian Culture (Dr.M.Valarmathi) (Published by: International Institute of Tamil Studies)

5	Keeladi - 'Sangam City Civilization on the banks of river Vaigai' (Jointly Published by: Department of Archaeology & Tamil Nadu Text Book and Educational Services Corporation, Tamil Nadu)
6	Studies in the History of India with Special Reference to Tamil Nadu (Dr.K.K.Pillay) (Published by: The Author)
7	Porunai Civilization (Jointly Published by: Department of Archaeology & Tamil Nadu Text Book and Educational Services Corporation, Tamil Nadu)
8	Journey of Civilization Indus to Vaigai (R.Balakrishnan) (Published by: RMRL)

22EN	102	PROFESSIONAL SKILLS LABORATO	ORY	SEMESTEI			[
PRE-	REQU	TISITE	Category	HS	Cr	edit	1
	_			L	T	P	TH
Basic	langua	age skills listening, speaking, reading and writing	Hours/Week	0	0	2	2
Cours	se Obje	ectives:		l		1	
1.	To enal	ble learners to improve their reading skills					
2.	To mak	te learners show variations while reading					
		st learners to acquire speaking competency in English					
		ble learners to strengthen their fluency in speaking					
UNIT				0	0	6	6
		ading a short story – learning pronunciation, intonation, and s	nlitting of sontonoos	l			
	-	earrating a story without any help of handouts.	pitting of sentences	5 to 101111	IIICaiiiii	grur um	ıs.
UNIT				0	0	6	6
Readin	ισ – Res	ading a poem – learning the skill of reciting, appreciate rhyn	ne and music chang	re in ton	as ner		ntion o
the poe		ading a poem rearming the skin of rectang, appreciate myn	ne and music, chang	c in ton	c as per	the eme	ion o
Speaki	ng – Po	ower-point presentation on a general topic.					
UNIT	III			0	0	6	6
Readin	ıg – Rea	ading newspaper article – learning vocabulary and language p	pattern of official co	mmunica	ation.	1.	
Speaki	ng - Or	al presentation on a topic from basic engineering pertained to	their branch.				
UNIT	IV			0	0	6	6
Readin	ıg – Rea	ading dialogue scripts – learning expression, tone, stress and o	co-operative reading	ŗ.			
Speaki	ng –Pro	oposing welcome address, vote of thanks and organizing even	its.				
UNIT	V			0	0	6	6
Readin	ıg – Rea	ading technical descriptions of gadgets – learning the differen	it parts of devices.	l		1	
-	_	escribing a process – everyday technical activities like takin	ng printouts, purchas	sing equ	ipment	for a co	mpany
bookin	g a hall	for meetings etc.,					
					Total	=30 P	eriod
	Books:						
	Norma 2014.	n Whitby. Business Benchmark – Pre-Intermediate to Intermediate	ediate, Students boo	k, Camb	ridge U	niversity	Press
Refer	ence B	ooks:					
1.	Readin	g Fluency. Switzerland, MDPI AG, 2021.					
		obs, Wade. Dare to Read: Improving Your Reading Speed and					
3.	Hoge,	A. J. Effortless English: Learn to Speak English Like a Native	e. United States, Eff	ortless E	nglish I	LLC, 20	14.
E-Ref	erence	es:					
		www.talkenglish.com/					
-		www.readingrockets.org/					

	RSE OUTCOMES: completion of the course, the students will be able to:	Bloom's Taxonomy Mapped				
CO1	CO1 Read passages fluently with good pronunciation					
CO2	Develop an expressive style of reading	Create				

CO3	Make effective oral presentations in technical and general contexts	Create	l
CO4	Excel at professional oral communication	Evaluate	l

COU	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	0	0	0	1	0	0	0	0	2	3	0	1	0	0	1
CO2	0	0	0	1	0	0	0	0	2	3	0	1	0	0	1
CO3	0	0	0	2	0	0	0	0	2	3	0	1	0	0	1
CO4	0	0	0	2	0	0	0	0	2	3	0	1	0	0	3
Avg	0	0	0	1.5	0	0	0	0	2	3	0	1	0	0	1.5
	3/2/1 – indicates strength of correlation (3 – High, 2 – Medium, 1 – Low)														

22PH103	PHYSICS LABORATORY	SEMESTER I				
PRE-REQ	UISITE	Category	BS	BS Credit		
NIII		TT/\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	L	T	P	TH
NIL		Hours/Week	0	0	3	3

Course Objectives:

- To handle different measuring instruments.
- 2. To understand the basic concepts of interference, diffraction, heat conduction and to measure the important parameters.

LIST OF EXPERIMENTS

- 1. Newton's rings Determination of radius of curvature of a Plano convex lens.
- 2. Carey Foster's bridge Determination of specific resistance of the material.
- Poiseuille's flow Determination of the Coefficient of viscosity of a liquid.
- 4. Spectrometer Grating Normal incidence Determination of Wavelength of Mercury lines.
- 5. Lee's disc Determination of thermal conductivity of a Bad conductor.
- Ultrasonic interferometer Determination of velocity of Ultrasonic Waves in Liquid.
- Non-uniform bending Determination of young's modulus of the wooden bar.
- Determination of Band gap of a given semiconductor.
- Determination of Wavelength of laser using grating and determination of particle size using Laser.
- 10. Determination of Acceptance angle and Numerical Aperture of fiber.

Total (45P) = 45 Periods

Text Books:

- 1. C. S. Robinson, Dr. Ruby Das, 'A Textbook of Engineering Physics Practical', Laxmi Publication Pvt. Ltd., 2016.
- S. Panigrahi, 'Engineering Practical Physics', Cengage Learning India, 2015.

Reference Books:

- 1. M.N. Srinivasan, 'Text Book of Practical Physics', Sultan Chand & Sons, 2013
- 2. Singh Harman, 'B.Sc. Practical Physics', S Chand & Company Ltd, 2022.

	RSE OUTCOMES: completion of the course, the students will be able to:	Bloom's Taxonomy Mapped	
CO1	Handle different measuring instruments and to measure different parameters.	Apply	
CO2	Calculate the important parameters and to arrive at the final result based on the experimental measurements.	Analyze	

COUR	COURSE ARTICULATION MATRIX														
CO/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	0	3	3	0	0	0	3	1	0	2	1	1	1
CO2	3	2	0	2	1	0	0	0	2	0	0	1	1	1	1
Avg	3	2	0	2.5	2	0	0	0	2.5	0.5	0	1.5	1	1	1
			3/2/1	– indic	ates str	enoth o	f correl	ation (3	R _ Hiol	2 – M	edium 1	- Low)	1		

22CY102	SEMESTER I					
PRE-REQU	ISITE	Category	BS	Credit		1.5
		Hours/Week	L	T	P	C
		nours/ week	0	0	3	1.5

Course Objectives:

1. To gain practical knowledge by applying theoretical principles and performing the following experiments.

LIST OF EXPERIMENTS

- 1. Estimation of hardness of Water by EDTA
- 2. Estimation of Copper in brass by EDTA
- 3. Estimation of Alkalinity in water
- 4. Estimation of Chloride in water sample (Iodimetry)
- 5. Estimation of Iron content in the given salt by using external indicator
- 6. Conductometric titration of Strong Acid and Strong Base
- 7. Conductometric titration of Mixture of acids and Strong base
- 8. Determination of strength of Iron by Potentiometric method
- 9. Estimation of Iron by Spectrophotometry
- 10. Estimation of Copper by Colorimeter
- 11. Determination of molecular weight and degree of Polymerization by Viscometry
- 12. Determination of pKa of the given weak acid by pH meter
- 13. Estimation of the amount of given HCl using pH meter

Total = 45 Periods

E-Re	ferences:								
1.	1. <u>www.scuolab.com/en/chemistry/</u>								
2.	2. <u>www.onlinelabs.in/chemistry</u>								
3.	3. www.virtuallabs.merlot.org/vl_chemistry								
	COURSE OUTCOMES: Upon completion of the course, the students will be able to:								
CO1	Summarize the applicability of the practical skill gained in various fields.	Understand							
CO2	Calculate the composition of brass quantitatively and the molecular weight of polymers.	Apply							
соз	Understand the principle and applications of conductometric and ph titrations, spectrometer, and								

<u>COUI</u>	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	1	0	3	0	0	0	0	0	0	0	0	2	0	0
CO2	1	2	0	3	0	0	0	0	0	0	0	0	2	0	0
CO3	2	2	0	3	0	0	0	0	0	0	0	0	2	0	0
Avg	1.3	1.7	0	3	0	0	0	0	0	0	0	0	2	0	0
			2/5) / 1 :			l£	14:	(2 11:	-1- 2 N	/ - J:	1 T)			

 $3 \, / \, 2 \, / \, 1 - indicates \ strength \ of \ correlation \ (3 - High, \, 2 - Medium, \, 1 - Low)$

22EE102	BASIC ELECTRICAL AND ELECTRONICS EN LABORATORY	GINEERING	SEMESTER I				
PRE-REQ	UISITE	Category	ES	Credit		1.5	
		Hours/Week	L	T	P	TH	
			0	0	3	3	

Course Objectives:

1. To impart hands on experience in use of measuring instruments, testing in transformers, and house wiring practices

LIST OF EXPERIMENTS

- 1. Verification of Kirchhoff's laws.
- 2. Verification of Superposition theorem.
- 3. Measurement of three-phase power in three-phase circuits.
- 4. Determination losses in single phase Transformer.
- 5. Demonstration of cut-out sections of machines: induction machine (squirrel cage rotor), and single-phase induction motor.
- 6. Speed control of DC shunt motor.
- 7. Study of basic safety precautions, measuring instruments voltmeter, ammeter, multi-meter, and Electrical components.
- 8. VI Characteristics of PN Junction diode.
- 9. Staircase wiring.
- 10. Wiring for fluorescent lamp.

Total (45 P) = 45 Periods

	SE OUTCOMES: empletion of the course, the students will be able to:	Bloom's Taxonomy Mapped					
CO1	Analyse DC and AC circuits.	Analyze					
CO2	Calculate various losses in transformer.	Analyze					
СОЗ	Recognise the parts of single-phase and three phase induction motors.	Understand					
CO4	Demonstrate the characteristics of electron devices.	Understand					
CO5	Practice electrical connections by wires of appropriate ratings.						

COURSE ARTICULATION MATRIX

COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	1	0	0	0	0	0	0	0	0	1	1	0	0	0
CO2	1	1	0	0	0	0	0	0	0	0	1	1	0	0	0
CO3	1	0	0	0	0	0	0	0	0	0	1	1	0	0	0
CO4	1	0	0	0	0	0	0	0	0	0	1	1	0	0	0
CO5	1	0	0	0	0	0	0	0	0	0	1	1	0	0	0
Avg	1	0.4	0	0	0	0	0	0	0	0	1	1	0	0	0

3/2/1 – indicates strength of correlation (3-High, 2-Medium, 1-Low)

SEMESTER-II

	SEMESTER-I	<u>1</u>				
22EN101	COMMUNICATIVE ENGLIS	SH	Ş	SEMES	STER I	I
PRE-REQU	ISITE	Category	HS	Cr	edit	3
Basic languag	e skills listening, speaking, reading and writing	Hours/Week	L	T	P	TH
Busic lunguag	o same necessing, speaking, reading and writing	Trours,	2	0	2	4
Course Obj	ectives:					
1. To deve	elop the communicative skills of learners by engaging the	m in reading, writing a	nd gramr	nar learr	ning acti	vities
2. To incu	lcate learners' ability to read texts, summaries, articles ar	nd user manuals				
3. To assis	st learners to acquire writing skills for academic, social ar	nd professional purpose	s			
4. To imp	rove learners' vocabulary and grammar to supplement the	eir language use at diffe	rent cont	exts		
UNIT I			6	0	6	12
Describing dia	nterview with personal assistant, an interview with a b mensions of products. If-introduction, name, home background, study details, ar					
relevant to tec	ading for detailed comprehension, specific information, hnical contexts.	Understanding notice	s, messa	ges, tim	etables,	graph
_	logue writing in a business context.	1. C 1	NT.	D		
Grammar - Pa Prepositions a	arts of speech, Tenses, Voices, Common errors in Englis and Articles.	h, Subject-Verb agreer	nent, No	un-Pron	oun agre	eemen
UNIT II			6	0	6	12
Reading - Rea Writing - Writ	rsonal interview, dress code, body language, required skil ding technical texts from journals, newspapers and technical ting checklists, Recommendations. refix and suffix, Synonyms, Antonyms, Verb forms - A	ical blogs.				onouns
Adverbs and A	Adjectives.					12
UNIT III			6	0	6	12
Listening - Co teams: a prese	onversation between two employees, Interview about cl ntation.	nange in job and corpo	orate gift	giving,	Creatin	g goo
	ole play - examiner and candidate, customer and sales mastrialist and candidate.	anager, team leader and	d team m	ember, i	interviev	ver and
•	ding advertisements, gadget reviews, user manuals.		C			
Arranging and	viding instruction, Writing E-mails - Attending workshil cancelling a meeting.			iinars ar	id confe	rences
	onditional statements, Redundancies, Collocations and Mo	eanings of individual w	ords.			
UNIT IV			6	0	6	12
Speaking – Gi Reading - Rea Writing - Essa reports on sen	orking in an international team, Statistical information, In a speech, describing given data, discussing company ding longer technical texts, cause and effect essays, news ay writing on social topics, Technical Report Writing – Spinars, conferences, meeting.	information, Summar paper articles, company Status reports on projec	izing an a y profiles ets, Feasi	article. bility re		
UNIT V	Impound words, conjunctions, bentefice completion, Neg	anon in statements and	6	0	6	12
Listening – As Speaking – Q	 n interview with career advisor and recruitment agent, Fe- ualities required for employability, Improving employee activity and leadership quality.	•	cts.			

36

Reading - Reading brochures, telephone messages, social media messages relevant to technical contexts.

Writing - Letter Writing - Formal Letters and Informal Letters - cover letter with resume, Mind maps, Charts - interpreting statistical data, charts, graphs and tables.

Grammar - One word substitution, Abbreviations and acronyms in technical contexts and technical vocabulary, Idioms.

Total (30L + 30P) = 60 Periods

Refe	Reference Books:							
1.	Meenakshi Raman and Sangeeta Sharma. Professional English. Oxford University Press, New Delhi, 2019.							
2.	Krishna Mohan, MeeraBannerji. Developing Communication Skills. Macmillan India Ltd, Delhi, 1990.							
3.	Sanjay Kumar, PushpaLata. English Language and Communication Skills for Engineers. Oxford University Press, 2018.							
E-R	eferences:							
1.	1. https://learnenglish.britishcouncil.org/							
2.	https://www.bbc.co.uk/learningenglish							

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:						
CO1	Comprehend the main ideas, key details and inferred meanings of technical texts	Understand					
CO2	Use language effectively at technical and professional contexts	Apply					
СОЗ	Apply the academic and functional writing skills in formal and informal communicative contexts	Apply					
CO4	Interpret pictorial representation of statistical data and charts	Apply					

COUL	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	0	0	0	1	0	0	0	0	1	3	0	1	0	0	1
CO2	0	0	0	1	0	0	0	0	1	3	0	2	0	0	2
CO3	0	0	0	2	0	0	0	0	1	3	0	1	0	0	1
CO4	0	0	0	3	0	0	0	0	1	3	0	1	0	0	1
Avg	0	0	0	1.75	0	0	0	0	1	3	0	1.25	0	0	1.25
			3/2/	/ 1 – ind	licates s	strengtl	ı of cor	relatio	n (3 – H	ligh, 2 –	Medium	, 1 – Lov	v)		

22MA	201	PARTIAL DIFFERENTIAL EQUATIONS, CALCULUS AND COMPLEX VARIAI		:	SEMES	STER I	I	
PRE-R	REQU	ISITE:	Category	BS	Cr	edit	4	
Basic 12	2th leve	el knowledge of Partial Derivatives, Vector algebra and		L	Т	P	TH	
Complex			Hours/Week	3	1	0	4	
Course	Obje	ectives:	•	•	•	•	•	
1.	To far	miliarize with the formation and solutions of first-order partia	l differential equatio	n.				
2.	To far	miliarize with the solutions of higher-order partial differential	equations.					
3.	To ac	quire knowledge of vector differentiation and integration and	its applications.					
4.	To kn	now about analytic functions with properties, construction of a	nalytic functions and	d confor	mal trans	sformati	ons.	
5.		otain the knowledge of Cauchy's integral theorems, calculu and semi-circle.	s of residues and co	omplex	integrati	on arou	nd uni	
	ГΙ	PARTIAL DIFFERENTIAL EQUATIONS – FI	RST ORDER	9	3	0	12	
UNIT			1.0			rst orde	r nartia	
Formation		partial differential equations by elimination of arbitrary consuations - Standard types of first order linear and non-linear PE			ons to 11		purnu	
Formation different UNIT Solution complements	tial equ	PARTIAL DIFFERENTIAL EQUATIONS – HICh nomogeneous and non-homogeneous linear partial difference of function and particular integral method - Separation of	DE- Lagrange's linea GHER ORDER ential equations of f variables method:	second simple	3 and h	0 igher-on is in C	12 rder by	
Formatic different UNIT Solution complement coordinates	tial equation in to homentary ates, L	PARTIAL DIFFERENTIAL EQUATIONS – HICh nomogeneous and non-homogeneous linear partial different	DE- Lagrange's linea GHER ORDER ential equations of f variables method:	second simple	3 and h	0 igher-ons in C	12 rder by	
Formation different UNIT Solution complement coordinate equation UNIT Vector of Surface	tial equitial equitial equitial equitial equitial equitial equition is a second equition of the control of the	PARTIAL DIFFERENTIAL EQUATIONS – HICh nomogeneous and non-homogeneous linear partial differency function and particular integral method - Separation of aplace equation in Cartesian and polar coordinates, one-dimensional contents of the coordinates of the coordinates of the cartesian and polar coordinates.	OE- Lagrange's linea GHER ORDER ential equations of f variables method: nensional diffusion e	second simple equation,	3 and h problem one-dir	o igher-on is in Connension. o o	12 rder by artesian al wav	
Formation different UNIT Solution complement coordinate equation UNIT Vector of Surface	tial equital e	PARTIAL DIFFERENTIAL EQUATIONS – HICK nomogeneous and non-homogeneous linear partial differency function and particular integral method - Separation of aplace equation in Cartesian and polar coordinates, one-dimensional coordinates of the separation of the separa	OE- Lagrange's linea GHER ORDER ential equations of f variables method: nensional diffusion e l, Vector integration okes theorem (withough	second simple equation,	3 and h problem one-dir	o igher-on is in Connension. o o	12 rder by artesian al wav	
Formation different UNIT Solution complement coordinate equation UNIT Vector of Surface involvin UNIT Function – Harmon	tial equation to hemontary ates, Len. III different and Very and Cube to the	PARTIAL DIFFERENTIAL EQUATIONS – HICH composed and non-homogeneous linear partial differency function and particular integral method - Separation of aplace equation in Cartesian and polar coordinates, one-dimensional content of the coordinates of the coordinat	OE- Lagrange's linea GHER ORDER ential equations of f variables method: nensional diffusion e l, Vector integration okes theorem (without	second simple equation, 9 - Line ir out proof	and he problem one-directions (e) 3 itions (e)	ouigher-ones in Connension. ouigher-ones in Connension. ouighted ouighted vork ple appl ouighted xcluding	12 rder by artesian al wave 12 done done dication 12	
Formation different UNIT Solution complement coordinate equation UNIT Vector of Surface involvin UNIT Function — Harmon	tial equation to he mentary ates, Len. HIII different and Very cube to the control and the c	PARTIAL DIFFERENTIAL EQUATIONS – HICH composes and non-homogeneous linear partial differency function and particular integral method - Separation of aplace equation in Cartesian and polar coordinates, one-dimensional contest of the compose of the	OE- Lagrange's linea GHER ORDER ential equations of f variables method: nensional diffusion e l, Vector integration okes theorem (without	second simple equation, 9 - Line ir out proof	and he problem one-directions (e) 3 itions (e)	ouigher-ones in Connension. ouigher-ones in Connension. ouighted ouighted vork ple appl ouighted xcluding	12 rder by artesian al wave 12 done ication 12	
Formation different UNIT Solution complement coordinate equation UNIT Vector of Surface involvin UNIT Function - Harmon cz, 1/z, z UNIT Cauchy'	tial equation to have the mentary ates, Land I I I I I I I I I I I I I I I I I I I	PARTIAL DIFFERENTIAL EQUATIONS – HICH composes and non-homogeneous linear partial differency function and particular integral method - Separation of aplace equation in Cartesian and polar coordinates, one-dimensional content of the second s	DE- Lagrange's linea GHER ORDER ential equations of f variables method: nensional diffusion e l, Vector integration okes theorem (without equation and sufficient f analytic functions -	second simple equation, 9 - Line ir out proof 9 - Confor	3 and h problem one-dir 3 ntegratio (a) – Simp itions (e) mal map 3 only) ar	o igher-ones in Connension o n- work ple appl o xcluding ppings:	12 rder by artesian al wav 12 done ication 12 g proof w= z+c	

Text	Text Books:								
1.	Grewal. B.S, "Higher Engineering Mathematics", 43rd Edition, Khanna Publications, Delhi, 2015.								
2.	Jain R.K. and Iyengar S.R.K., "Advanced Engineering Mathematics", 3 rd Edition, Narosa Publications, New Delhi, 2007.								
Refe	Reference Books:								
1.	James Stewart, "Essential Calculus", 2 nd edition Cengage Learning, New Delhi, 2014.								
2.	P. Kandasamy, K. Thilagavathy and K. Gunavathy," Engineering Mathematics (For I year B.E., B. Tech)", 9th Edition, S. Chand & Co. Ltd. New Delhi, 2010.								
3.	Srimanta pal and Subath C. Bhumia, "Engineering Mathematics", Oxford university publications, New Delhi, 2015								
4.	Ewinkreyzig, "Advanced Engineering Mathematics", 9th Edition, John Wiley & Sons, 2007.								

Siva RamakrishnaDas.P, Ruknmangadachari.E. "Engineering Mathematics", 2nd edition Pearson, Chennai & Delhi, 2013.

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:						
CO1	Understand how to solve the given standard partial differential equations.	Understand					
CO2	Solve higher order partial differential equations.	Apply					
CO3	Use Gauss, Stokes and Green's theorems for the verification of line, surface and volume integrals.	Apply					
CO4	Familiar with the concept of Conformal and Bilinear transformations.	Understand					
CO5	Acquire the knowledge of Contour integration over unit circle and semi-circle.	Apply					

COUL	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	1	2	0	0	0	0	0	0	0	0	2	0	0
CO2	3	2	1	2	0	0	0	0	0	0	0	0	2	0	0
CO3	3	2	1	2	0	0	0	0	0	0	0	0	2	0	0
CO4	3	2	1	2	0	0	0	0	0	0	0	0	2	0	0
CO5	3	2	1	2	0	0	0	0	0	0	0	0	2	0	0
Avg	3	2	1	2	0	0	0	0	0	0	0	0	2	0	0
			3 / 2	2 / 1 — iı	ndicates	strengt	h of cor	relation	(3 – Hi	gh, 2 – N	Iedium, 1	l – Low)			

Basic	theoretic	al knowledge in Physics	Hours/Week	L	Т	P	TH
		,		3	1	0	4
Cour	rse Obje	ectives:					
1.	To unde	erstand Principles of ultrasonic production, its applications and	acoustics of building	ngs.			
2.	To unde	erstand Principle, working and industrial applications of LASE	R and optical fiber				
3.	To gain	knowledge in mode of transmission of heat by conduction med	chanism with exper	rimental	illustrati	ons	
4.	To obta	in knowledge in basic concepts of quantum physics and matter	r waves				
5.	To acqu	nire knowledge in basics of crystal structure, types of crystal an	nd its defects and cr	ystal gro	wth tech	niques	1
UN	NIT I	ULTRASONICS AND ACOUSTICS	5	9	3	0	12
pplic COI	cations - I USTICS (generator –Detection of ultrasonic waves - Properties – Aco Drilling, welding, soldering and cleaning –SONAR – Medical a OF BUILDINGS: Introduction – Reverberation and reverbera dies – Absorption co-efficient – Basic requirements for the aco	applications (Qualitation time –Factors	ative).			
UN	II TI	LASER AND FIBRE OPTICS		9	3	0	12
Types FIBE	R OPTIC	Nd–YAG,CO ₂ laser – Industrial and medical applications (Quality S: Principle of optical fiber – Structure and classification of or gle – Fiber optic communication (Block diagram). THERMAL PHYSICS	ŕ	al angle	- Nume	rical apo	erture –
FIBERACCEPTUN Modescondu	R OPTIC ptance and ITT III es of Transactivity and e's method	CS: Principle of optical fiber – Structure and classification of or gle – Fiber optic communication (Block diagram). THERMAL PHYSICS Insmission of heat - Conduction – Convection – Radiation and its unit –Thermal conduction through compound media in an od for good conductors, Lee's disc method for Bad conductions.	optical fiber – Critic	9 tivity –	3 Coeffici	0 ent of toonduction	12 thermal
FIBE Accep UN Mode condu Searle nsula	R OPTIC ptance and ITT III es of Transactivity and e's method attion in but	CS: Principle of optical fiber – Structure and classification of or gle – Fiber optic communication (Block diagram). THERMAL PHYSICS Insmission of heat - Conduction – Convection – Radiation and its unit –Thermal conduction through compound media in od for good conductors, Lee's disc method for Bad conductions.	optical fiber – Critic	9 tivity – nation of nsulatin	3 Coeffici thermal	ent of conduction als – T	12 thermal
FIBERACCEP Whode conductions with a conduction of the conduction	R OPTIC ptance and activity and e's methodation in but of the control of the cont	CS: Principle of optical fiber – Structure and classification of or gle – Fiber optic communication (Block diagram). THERMAL PHYSICS Insmission of heat - Conduction – Convection – Radiation and its unit –Thermal conduction through compound media in an od for good conductors, Lee's disc method for Bad conductions.	pptical fiber – Critical Thermal conductor series – Determinators – Thermal i	tivity – ation of nsulating	3 Coefficithermal g material 3 ion - Tir	o ent of conduction als - T	thermal trivity - Thermal 12
Types FIBE UN Mode condu Searle UN Matte (Qual	R OPTIC ptance and activity are's methodation in but the per waves - dependent	CS: Principle of optical fiber – Structure and classification of or gle – Fiber optic communication (Block diagram). THERMAL PHYSICS Insmission of heat - Conduction – Convection – Radiation and its unit –Thermal conduction through compound media in od for good conductors, Lee's disc method for Bad conductional didings. QUANTUM PHYSICS - experimental evidence: Davisson and Germer experiment –	pptical fiber – Critical Thermal conductor series – Determinators – Thermal i	tivity – ation of nsulating	3 Coefficithermal g material 3 ion - Tir	o ent of conduction als - T	thermal ctivity - Thermal
FIBEI Accep UN Mode condu Searle insula UN Matte and d (Qual UN Lattic	IT III es of Tranuctivity and e's method ation in but of the series of	S: Principle of optical fiber – Structure and classification of or gle – Fiber optic communication (Block diagram). THERMAL PHYSICS Insmission of heat - Conduction – Convection – Radiation and its unit –Thermal conduction through compound media in ord for good conductors, Lee's disc method for Bad conductional didings. QUANTUM PHYSICS - experimental evidence: Davisson and Germer experiment – equations – Physical significance of wave function – Particles	- Thermal conductors - Determinantors - Thermal is Schroedinger's ware in a one-dimension of the conductors - Point detections - Point detections - Grain boundaries,	ye equatonal box 9 on numb fects – S Twin bo	3 Coefficithermal g material 3 ion - Tir – Electr 3 er, and p schottky	o ent of the conduction of the	thermal trivity - Thermal 12 pendent roscope 12 factor-Frenkel
Types FIBE Accep UN Mode condu Searle nsula UN Matte und d Qual UN Crysta	IT III es of Tranuctivity and e's method ation in but of the series of	CS: Principle of optical fiber – Structure and classification of or gle – Fiber optic communication (Block diagram). THERMAL PHYSICS Insmission of heat - Conduction – Convection – Radiation and its unit –Thermal conduction through compound media in od for good conductors, Lee's disc method for Bad conductional diagrams. QUANTUM PHYSICS - experimental evidence: Davisson and Germer experiment – equations – Physical significance of wave function – Particles and CRYSTAL PHYSICS CRYSTAL PHYSICS cell – Bravais lattice – Number of atoms per unit cell, atomical techniques: Bridgman, Czochralski techniques. Crystal imperimentation of the control	- Thermal conductors - Determinantors - Thermal is Schroedinger's ware in a one-dimension of the conductors - Point detections - Point detections - Grain boundaries,	ye equatonal box 9 on numb fects – S Twin bo	3 Coefficithermal g material 3 ion - Tir – Electr 3 er, and p schottky bundaries	o ent of the conduction of the	thermal trivity - Thermal 12 pendent roscope 12 factor-Frenkel
UN Mode Gearle Gearle Matte IN	R OPTIC ptance and activity are e's method ation in but the strength of the st	CS: Principle of optical fiber – Structure and classification of or gle – Fiber optic communication (Block diagram). THERMAL PHYSICS Insmission of heat - Conduction – Convection – Radiation and its unit –Thermal conduction through compound media in od for good conductors, Lee's disc method for Bad conductional diagrams. QUANTUM PHYSICS - experimental evidence: Davisson and Germer experiment – equations – Physical significance of wave function – Particles and CRYSTAL PHYSICS CRYSTAL PHYSICS cell – Bravais lattice – Number of atoms per unit cell, atomical techniques: Bridgman, Czochralski techniques. Crystal imperimentation of the control	- Thermal conductors - Determinantors - Thermal is Schroedinger's ware in a one-dimension of the conductors - Point detections - Point detections - Grain boundaries,	ye equatonal box 9 on numb fects – S Twin bo	3 Coefficithermal g material 3 ion - Tir – Electr 3 er, and p schottky bundaries	o ent of the conduction of the	thermal trivity Thermal 12 pendent roscope 12 factor-Frenke
UN Mode Gearle Gearle Matte IN	R OPTIC ptance and activity and e's method action in but all per waves dependent litative). NIT V Dee — Unit all growth t — Line dependent all growth the dependent all g	THERMAL PHYSICS Insmission of heat - Conduction - Convection - Radiation and its unit -Thermal conduction through compound media in od for good conductors, Lee's disc method for Bad conductions. QUANTUM PHYSICS - experimental evidence: Davisson and Germer experiment - equations - Physical significance of wave function - Particles and techniques: Bridgman, Czochralski techniques. Crystal imperimental effects - Edge dislocation, Screw dislocation - Planar defects -	- Thermal conductors - Determinantors - Thermal is Schroedinger's was e in a one-dimension of the cradius, coordination of the cradius - Point de - Grain boundaries,	ye equatonal box 9 on numb fects – S Twin bo	3 Coefficithermal g material 3 ion - Tir – Electr 3 er, and p schottky bundaries	o ent of the conduction of the	thermal trivity Thermal 12 pendent roscope 12 factor-Frenke
UN Mode condu Matte und d Qual UN Lattic Crysta defect 1.	R OPTIC ptance and IT III es of Transactivity and e's method ation in but IIT IV er waves - dependent ditative). NIT V ere — Unit all growth t — Line d Rajend	THERMAL PHYSICS Institution of the property o	— Thermal conductors — Determinators — Thermal is Schroedinger's ware in a one-dimension of the conditions — Point determinations — Tour Determinations — Point	ye equatonal box 9 on numb fects – S Twin bo	3 Coefficithermal g material 3 ion - Tir – Electr 3 er, and p schottky bundaries	o ent of the conduction of the	thermal trivity - Thermal 12 pendent roscope 12 factor-Frenkel

ENGINEERING PHYSICS

SEMESTER II

Credit

4

BS

Category

22PH101

5.

PRE-REQUISITE:

Introduction to crystal growth, Principles and Practice, H.L. Bhat, Taylor and Francis, 2015 edition.

Reference Books:								
1.	Gaur R.K. and Gupta S.L, 'Engineering Physics', DhanpatRai publishers, 2012.							
2.	Arthur Beiser, 'Concepts of Modern Physics', Tata McGraw Hill Publishing Co. Ltd, sixth Edition, 2019.							
3.	Gerdkeiser, 'Optical fiber communications', Tata McGraw Hill Publishing Co. Ltd, 5th Edition, 2017.							
4.	OrazioSvelto. David C. Hanna, 'Principles of Lasers', Springer Science &Business Media, LLC, 2010.							

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:							
CO1	Understand the principle, production of ultrasonic wave and acoustics of buildings.	Understand						
CO2	Understand the principle and applications of laser and optical fiber.	Understand						
CO3	Analyze various modes involved in heat transmission	Analyze						
CO4	Gain knowledge in basic concept of quantum physics.	Remember						
CO5	Recognize crystal structure, crystal defects and crystal growth techniques.	Evaluate						

COURS	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	1	1	1	1	0	0	0	0	0	2	2	1	0
CO2	2	3	1	1	2	1	0	0	0	0	0	2	1	1	0
CO3	3	2	1	1	0	0	0	0	0	0	0	1	2	0	0
CO4	3	2	1	1	2	0	1	0	0	0	0	1	1	0	0
CO5	2	2	1	1	2	0	0	0	0	0	0	1	0	1	1
Avg	2.6	2.2	1	1	1.4	0.4	0.2	0	0	0	0	1.4	1.2	0.6	0.2
			3/2/1	l – indi	cates s	trength	of cor	relatio	n (3 – F	High, 2 –	Medium	, 1 – Lov	v)		

22ES	5101	ENGINEERING MECHANICS			SEMES	STER I	I
PRE	-REQ	UISITE:	Category	ES	Cro	edit	3
1. En	gineer	ing Physics.	TT /537 1	L	Т	P	ТН
2. En	gineer	ing Mathematics.	Hours/Week	3	0	0	3
Cour	rse Ob	jectives:		J	J	l.	
1.		evelop the capacity to predict the effect of force and motion in leering.	the course of carry	ing out	the desig	gn funct	ions of
2.	To an	nalyze the force systems and friction.					
3.	To st	udy the dynamics of particles, impulse and momentum					
UN	IT I	STATICS OF PARTICLES		9	0	0	9
Prince Theoretic Vector Resol	TII iple of rem, Reports, Modution of	EQUILIBRIUM OF RIGID BODIES Transmissibility, Equivalent Forces, Vector Product of Two Vece ectangular Components of the Moment of a Force, Scalar Product of a Force about an Axis, Couple - Moment of a Coof a Given Force into a Force -Couple system, Further Reductionsions - Reactions at Supports and Connections.	tors, Moment of a loct of Two Vectors, puple, Equivalent (9 Force ab Mixed 7 Couples,	0 out a Po Γriple Pr Additio	oint, Vari	gnon's Three ouples,
UNI	T III	PROPERTIES OF SURFACES AND SOL	IDS	9	0	0	9
mome	ent of	simple figures from first principle, centroid of composite section inertia- Definition, Moment of inertia of plane sections from nertia of standard sections and composite sections; Theorems of	first principles, T	•	_		
UNI	T IV	FRICTION		9	0	0	9
The la	aws of	dry friction. Coefficients of friction, Angles of friction, Wedges,	Wheel friction. Rol	ling resi	stance, I	Ladder fi	riction.
UNI	TV	DYNAMICS OF PARTICLES		9	0	0	9
Motio	ons, Dy	Rectilinear Motion and Curvilinear Motion of Particles. Kinetic rnamic Equilibrium, Energy and Momentum Methods - Work of nergy, Principle of Impulse and Momentum, Impact of elastic boo	a Force, Kinetic E			•	

Text	Books:								
1.	A Textbook of Engineering Mechanics, R.K. Bansal, Laxmi Publications, 2010.								
2.	Rajasekaran S and Sankarasubramanian G., "Fundamentals of Engineering Mechanics", Vikas Publishing House Pvt. Ltd., 2013.								
Refe	Reference Books:								
1.	Beer Ferdinand P, Russel Johnston Jr., David F Mazurek, Philip J Cornwell, SanjeevSanghi, Vector Mechanics for Engineers: Statics and Dynamics, McGraw Higher Education. 11thEdition, 2017.								
2.	Timoshenko S, Young D H, Rao J V and SukumarPati, Engineering Mechanics, 5thEdition, McGraw Hill Higher Education, 2013.								
3.	Hibbeller, R.C., Engineering Mechanics: Statics, and Engineering Mechanics: Dynamics, 13th edition, Prentice Hall, 2013.								

Total = 45 Periods

4.	Palanichamy M.S. and Nagam S., "Engineering Mechanics – Statics & Dynamics", Tata McGraw-Hill, 2001
5.	Engineering Mechanics, D.S. Bedi, Khanna Book Publishing Co. (P) Ltd, 2019.
E-Re	eferences:
1.	https://nptel.ac.in/courses/122104014
2.	https://nptel.ac.in/courses/112106286

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:							
CO1	Apply the various methods to determine the resultant forces and its equilibrium acting on a particle in 2D and 3D	Create						
CO2	Apply the concept of reaction forces (non-concurrent coplanar and noncoplanar forces) and moment of various support systems with rigid bodies in 2D and 3D.	Evaluate						
CO3	Evaluate area moments of inertia for various sections by applying the concepts of centroids.	Evaluate						
CO4	Apply the concepts of frictional forces at the contact surfaces of various engineering systems.	Apply						
CO5	Apply the various methods for evaluating dynamic parameters of the particles subjected to concurrent coplanar forces.	Apply						

COUL	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	1	0	0	0	0	0	0	0	1	3	1	0
CO2	3	2	2	1	0	0	0	0	0	0	0	1	3	1	0
CO3	3	2	2	1	0	0	0	0	0	0	0	2	3	2	0
CO4	3	1	2	1	0	0	0	0	0	0	0	1	3	2	0
CO5	3	1	2	1	0	0	0	0	0	0	0	1	3	2	0
Avg	3	1.6	2	1	0	0	0	0	0	0	0	1.2	3	1.6	0
			3 / 2	2/1-i	ndicates	strengt	h of cor	relation	(3 – Hi	gh, 2 – N	/ledium, 1	l – Low)			

22HS201	UNIVERSAL HUMAN VALUES		SEMESTER II				
PRE-REQU	JISITE:	Category	HS	Cre	Credit		
		TT /537 1	L	Т	P	ТН	
		Hours/Week	2	1	0	3	
Course Obj	ectives:		•				
	opment of a holistic perspective based on self-exploration abovexistence.	out themselves (hun	nan bein	g), fami	ly, soci	ety and	
2. Under	standing (or developing clarity) of the harmony in the human be	eing, family, society	and nati	ure/exist	ence.		
3. Streng	thening of self-reflection.						
4. Devel							
4. Devel	opment of commitment and courage to act.						
UNIT I Course Introcourse, recap Acceptance'	duction - Need, Basic Guidelines, Content and Process for Valutation from Universal Human Values-I. Self-Explorationand Experiential Validation- as the process for self-exploration	what is it? - Its Continuous Happ	content iness and	and prod	ocess; ' crity- A	Natura look a	
UNIT I Course Introccourse, recapt Acceptance' basic Human aspirations of appraisal of the course o	duction - Need, Basic Guidelines, Content and Process for Vabitulation from Universal Human Values-I. Self-Exploration-	what is it? - Its n Continuous Happe Facility- the basic ng Happiness and	Purpose content iness and required	and more and produced Prosper ments for the correction of the corr	tivation ocess; 'erity- A or fulfili	for the Natura look a ment of critica	
UNIT I Course Introccourse, recap Acceptance' basic Human aspirations o	duction - Need, Basic Guidelines, Content and Process for Valitulation from Universal Human Values-I. Self-Explorationand Experiential Validation- as the process for self-exploration Aspirations. Right understanding, Relationship and Physical f every human being with their correct priority. Understanding	what is it? - Its n Continuous Happe Facility- the basic ng Happiness and	Purpose content iness and required	and more and produced Prosper ments for the correction of the corr	tivation ocess; 'erity- A or fulfilictly- A	for the Natura look a ment of critica	
UNIT I Course Introccourse, recap Acceptance' basic Human aspirations o appraisal of t levels. UNIT II Understandin sentient 'I' a Understandin activities of '	duction - Need, Basic Guidelines, Content and Process for Valitulation from Universal Human Values-I. Self-Explorationand Experiential Validation- as the process for self-exploration Aspirations. Right understanding, Relationship and Physical f every human being with their correct priority. Understanding	what is it? - Its an Continuous Happine Facility - the basic and Happiness and Happine	Purpose content iness and requires Prosperit nd living 6 being as appiness tanding	and more and prosper ments for the charments of the charments are also as a co-e and plotted the charments of the charments o	ctivation occess; 'erity- A or fulfillectly- A onony at occurrence of the occurrence	for th Natura look a ment of critica variou 9 e of th facility ics and	
UNIT I Course Introccourse, recap Acceptance' basic Human aspirations o appraisal of t levels. UNIT II Understandin sentient 'I' a Understandin activities of '	duction - Need, Basic Guidelines, Content and Process for Valuation from Universal Human Values-I. Self-Explorationand Experiential Validation- as the process for self-exploration Aspirations. Right understanding, Relationship and Physical fevery human being with their correct priority. Understanding the current scenario Method to fulfil the above human aspiration g Harmony in the Human Being - Harmony in Myself! Understanding the material 'Body' Understanding the needs of Self ('I g the Body as an instrument of 'I' (I being the doer, seer an I' and harmony in 'I' Understanding the harmony of I with the	what is it? - Its an Continuous Happine Facility - the basic and Happiness and Happine	Purpose content iness and requires Prosperit nd living 6 being as appiness tanding	and more and prosper ments for the charments of the charments are also as a co-e and plotted the charments of the charments o	ctivation occess; 'erity- A or fulfillectly- A onony at occurrence of the occurrence	for the Natural look ament of critical various of the facility ics and statement of the sta	

Understanding Harmony in the Family and Society- Harmony in Human- Human Relationship Understanding values in human-human relationship; meaning of Justice (nine universal values in relationships) and program for its fulfilment to ensure mutual happiness; Trust and Respect as the foundational values of relationship. Understanding the meaning of Trust; Difference between intention and competence. Understanding the meaning of Respect, Difference between respect and differentiation; the other salient values in relationship. Understanding the harmony in the society (society being an extension of family): Resolution, Prosperity, fearlessness (trust) and co-existence as comprehensive Human Goals. Visualizing a universal harmonious order in society- Undivided Society, Universal Order- from family to world family.

UNIT IV 6 3 0 9

Understanding Harmony in the Nature and Existence - Whole existence as Coexistence. Understanding the harmony in the Nature. Interconnectedness and mutual fulfilment among the four orders of nature- recyclability and self-regulation in nature. Understanding Existence as Co-existence of mutually interacting units in all- pervasive space. Holistic perception of harmony at all levels of existence.

UNIT V 6 3 0 9

Implications of the above Holistic Understanding of Harmony on Professional Ethics. Natural acceptance of human values. Definitiveness of Ethical Human Conduct. Basis for Humanistic Education, Humanistic Constitution and Humanistic Universal Order. Competence in professional ethics, Strategy for transition from the present state to Universal Human Order.

Total (30L + 15T) = 45 Periods

Refe	rence Books:
1.	Human Values and Professional Ethics by R R Gaur, R Sangal, G P Bagaria, Excel Books, New Delhi, 2010
Refe	rence Books:
1.	JeevanVidya: EkParichaya, A Nagaraj, JeevanVidyaPrakashan, Amarkantak, 1999.
2.	Human Values, A.N. Tripathi, New Age Intl. Publishers, New Delhi, 2004.
3.	The Story of Stuff (Book)
4.	The Story of My Experiments with Truth - by Mohandas Karamchand Gandhi
5.	Small is Beautiful - E. F Schumacher.
6.	Slow is Beautiful - Cecile Andrews
7.	Economy of Permanence - J C Kumarappa
8.	Bharat Mein Angreji Raj - PanditSunderlal
9.	Rediscovering India - by Dharampal
10.	Hind Swaraj or Indian Home Rule - by Mohandas K. Gandhi
11.	India Wins Freedom - Maulana Abdul Kalam Azad
12.	Vivekananda - Romain Rolland (English)
13.	Gandhi - Romain Rolland (English)

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:						
COI	Become more aware of themselves, and their surroundings (family, society, nature) and become more responsible in life	Evaluate					
CO2	Handle problems with sustainable solutions, while keeping human relationships and human nature in mind	Apply					
соз	Become sensitive to their commitment towards what they have understood (human values, human relationship and human society)	Evaluate					
CO4	Apply what they have learnt to their own self in different day-to-day settings in real life, at least a beginning would be made in this direction.	Apply					

COU	COURSE ARTICULATION MATRIX														
CO/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	0	0	1	0	0	1	0	2	0	1	0	3	2	0	1
CO2	0	0	1	0	0	3	0	1	0	1	0	3	1	0	1
CO3	0	0	1	0	0	2	0	1	0	1	0	3	1	0	2
CO4	0	0	2	0	0	1	0	1	0	1	0	3	1	0	1
Avg	0	0	1.25	0	0	1.75	0	1.25	0	1	0	3	1.25	0	1.25
	'	'	3 /	2 / 1 – i	ndicates	strengt	th of co	relation	(3 – H	igh, 2 – N	Medium,	1 – Low)			

22M	CIN01	ENGINEERING SPRINTS			SEMES	STER I	I						
PRE	-REQU	ISITE:	Category	EE	Cro	edit	1						
			Hours/Week	L	Т	P	TH						
			Hours/ week	0	0	2	2						
Cour	se Obje	ectives:											
1.	To stre	strengthen conceptual understanding of fundamental engineering concepts.											
2.	To spar	rk curiosity in students' Minds.											
3.	To focu	s on teaching through a problem-solving approach using Stree	et Fight Engineerin	g princip	oles pion	eered.							
4.	To fost	er the growth of functional independence and self-driven learn	ing habits										
5.	To max	imize the interest levels toward learning - as students aspire to	create meaningfu	l changes	s in the v	vorld.							
UN	IT I	STREET FIGHTING ENGINEERING	G	0	0	6	6						
		ght engineering - How to street fight engineering - Decocutory - Derive actionable inferences - Perform data driven insignate.	-				tterns -						
UN	IT II	PROGRAMMING PARADIGM		0	0	6	6						
Algor	rithms - I	ramming - Outside box thinking to solve problems - Need Memory Allocation - Conditions and loops - Creating effective ramming languages& paradigms - Getting started with develop	e functions - Case	e studies	- Visual	Program	nming -						
UN	IT III	BRAINS OF MACHINES		0	0	6	6						
Trans	disciplin	ons in Tesla Electric car - Case study - Brains of Elect ary systems to Accelerate innovation - Idea Hexagon - Exerc tal camera		-									
UN	IT IV	MACHINES THAT MAKE-UP THE WO	RLD	0	0	6	6						
		ronics Passive Components -Need for sensors & Actuators a Basic Custom Hardware - Bootloader& its purpose	- Analyzing & Uı	nderstand	ling elec	etronic ci	ircuits -						
UN	IT V	ENGINEERING THE REAL WORLI	D	0	0	6	6						
		systems - Introduction to Systems Thinking - Stock and Flow orld of Systems	Diagrams - Syster	n Traps	- Interve	ning in S	ystem -						
					Total	=30 F	Periods						

Text	Books:
1.	SanjoyMahajan - Street Fighting Mathematics
2.	Donald Knuth - The Art of Computer Programming
3.	Think like a programmer: An introduction to creative problem solving
4.	Thinking in Systems: A Primer
Refe	rence Books:
1.	Learning to code: How to think like a programmer
2.	How to find innovative ideas: Ramesh Raskar's note
3.	Case study: How Tesla changed the auto industry
4.	Ultimate Guide: How to develop a new electronic hardware product

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:							
CO1	Apply street fight engineering concepts to solve problems	Apply						
CO2	Construct flowcharts & block diagrams for algorithms	Apply						
СОЗ	Apply the Idea Hexagon Tool to learn innovation models	Apply						
CO4	Understand basic electronics for building hardware	Apply						
CO5	Examine real-world problems with a system view	Analyze						

COU	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	3	0	0	0	0	0	0	2	0	2	0	0	0	2
CO2	2	0	0	3	0	0	0	0	2	0	0	0	0	0	2
CO3	2	2	0	3	0	0	0	0	2	0	2	0	0	0	2
CO4	2	2	0	3	0	0	0	1	2	0	2	0	0	0	2
CO5	0	3	0	0	0	1	2	0	2	1	2	0	0	0	2
Avg	1.6	2	0	1.8	0	0.2	0.4	0.2	2	0.2	1.6	0	0	0	2
			3 / 2	$\frac{1}{2}/1-i$	ndicates	strengt	h of cor	relation	(3 – Hi	gh, 2 – N	ledium,	l – Low)			

22M	22MC201 TAMILS AND TECHNOLOGY		SEMESTER II		II		
PREREQUISITES Category					y HS Credit		1
			TT /XX/ 1	L	T	P	TH
			Hours/Week	1	0	0	1
Course	e Learn	ing Objectives					
1							
2							
3							
4							
5							
Un	it I	WEAVING AND CERAMIC TECHNOL	OGY	3	0	0	3
Weavin	g Industi	ry during Sangam Age – Ceramic technology – Black and Rec	d Ware Potteries (B	RW) –	Graffiti	on Potte	eries.
Uni	t II	DESIGN AND CONSTRUCTION TECHNO	OLOGY	3	0	0	3
Hero sto Great T	ones of Semples	Structural construction House & Designs in household material Sangam age – Details of Stage Constructions in Silappathikar of Cholas and other worship places - Temples of Nayaka Pekar Mahal - Chetti Nadu Houses, Indo - Saracenic architecture	am - Sculptures an riod - Type study	d Temp (Madura	les of Mai Meen	Iamalla	puram -
Unit	t III	MANUFACTURING TECHNOLOG	Y	3	0	0	3
Minting	g of Coi	lding - Metallurgical studies - Iron industry - Iron smelting,st ns — Beads making-industries Stone beads -Glass beads vidences - Gem stone types described in Silappathikaram.					•
Uni	t IV	AGRICULTURE AND IRRIGATION TECH	NOLOGY	3	0	0	3
use - Ag	griculture	ds, Sluice, Significance of KumizhiThoompu of Chola Periode and Agro Processing - Knowledge of Sea - Fisheries – Pearl cific Society.					
Unit V SCIENTIFIC TAMIL & TAMIL COMPUTING		3	0	0	3		
		Scientific Tamil - Tamil computing – Digitalization of Tacademy – Tamil Digital Library – Online Tamil Dictionaries -		elopmer	it of Ta	mil Sof	tware –
					Total	= 15 F	Periods

Tex	at Books:
1	Social Life of Tamils (Dr.K.K.Pillay) A joint publication of TNTB & ESC and RMRL – (in print)
2	Social Life of the Tamils - The Classical Period (Dr.S.Singaravelu) (Published by: International Institute of Tamil Studies.
3	Historical Heritage of the Tamils (Dr.S.V.Subatamanian, Dr.K.D. Thirunavukkarasu) (Published by: International Institute of Tamil Studies).
4	The Contributions of the Tamils to Indian Culture (Dr.M.Valarmathi) (Published by: International Institute of Tamil Studies)

5	Keeladi - 'Sangam City Civilization on the banks of river Vaigai' (Jointly Published by: Department of Archaeology & Tamil Nadu Text Book and Educational Services Corporation, Tamil Nadu)
6	Studies in the History of India with Special Reference to Tamil Nadu (Dr.K.K.Pillay) (Published by: The Author)
7	Porunai Civilization (Jointly Published by: Department of Archaeology & Tamil Nadu Text Book and Educational Services Corporation, Tamil Nadu)
8	Journey of Civilization Indus to Vaigai (R.Balakrishnan) (Published by: RMRL)

PREREQUIS	NCC COURSE-I(Only for NCC Stude	ents)	Semester II				
INDICE	ITES	Category	ry NC Credit				
NIL		_	L	Т	P	TH	
Hours/Week				0	0	3	
Course Learn	ing Objectives		•	•	•	•	
1 To ma	intain the unity and disciplines to the students						
Unit I	NCC GENERAL & NATIONAL INTEGRATI AWARENESS	ION AND	9	0	0	9	
•	es and Org of NCC – Incentives to NCC cadets – Duties of ation: Importance and Necessity – Factors affecting Nationaty.						
Unit II	PERSONALITY DEVELOPMENT & LEAD DEVELOPMENT	ERSHIP	9	0	0	9	
Communication	Skills - Group Discussion - Stress emotions, Change Your			lations	0- Tabe	a rrramle	
Indicators, Mo	nents, Civil Sense - Career Counselling, SSB Procedures & tivation, Ethics & Honour code - Case Studies-Shivaji, APG an Majumdar, Jhansi Ki Rani, Narayan Murty, Prakash Padukon	t Interview Skills; Abdul Kalam & D	; Leade: Deepa M	rship Ca Ialik, M	apsule - Iaharana	Traits,	
Indicators, Mo	tivation, Ethics &Honour code - Case Studies-Shivaji, APG	t Interview Skills; Abdul Kalam & D ne, Tipu Sultan, Ra	; Leade: Deepa M	rship Ca Ialik, M	apsule - Iaharana	Traits,	
Indicators, Mo Ratan Tata, Kira Unit III Disaster Manag Fighting – Initia	tivation, Ethics &Honour code - Case Studies-Shivaji, APG AnMajumdar, Jhansi Ki Rani, Narayan Murty, PrakashPadukon	Abdul Kalam & Dae, Tipu Sultan, Rae HYGIENE & Role of NCC Ca	Leade Deepa M Ibindran 9 adets –	rship Calalik, Math Tage 0 Fire Ser asters; H	apsule - Iaharana ore. 0 vice & l ealth &	Traits, aPratap, 9 Fire	
Indicators, Mo Ratan Tata, Kira Unit III Disaster Manag Fighting – Initia	tivation, Ethics &Honour code - Case Studies-Shivaji, APG AnMajumdar, Jhansi Ki Rani, Narayan Murty, PrakashPadukon DISASTER MANAGEMENT AND HEALTH & ement Capsule- SochVichar, Types - Organisation, Capability ative Training, Organisation Skills, Do's and Don'ts – Natural	Abdul Kalam & Dae, Tipu Sultan, Rae HYGIENE & Role of NCC Carbinsters, Man Ma	Leade Deepa M Ibindran 9 adets –	rship Calalik, Math Tage 0 Fire Ser asters; H	apsule - Iaharana ore. 0 vice & l ealth &	Traits, aPratap, 9 Fire	
Indicators, Mo Ratan Tata, Kira Unit III Disaster Manag Fighting – Initia Sanitation – Fira Unit IV Laws of Motion	tivation, Ethics & Honour code - Case Studies-Shivaji, APG An Majumdar, Jhansi Ki Rani, Narayan Murty, PrakashPadukon DISASTER MANAGEMENT AND HEALTH & ement Capsule- SochVichar, Types - Organisation, Capability tive Training, Organisation Skills, Do's and Don'ts - Natural St aid in Common Medical Emergencies, Treatment & Care of PRINCIPLES OF FLIGHT & GENERAL SE KNOWLEDGE - Glossary Terms - Bernoulli's Principle - Aerofoil - Forces Armed Forces & IAF Capsule - Modes of Entry in IAF, Civil	Abdul Kalam & Dae, Tipu Sultan, Rae HYGIENE & Role of NCC Ca Disasters, Man Ma E Wounds – Introdu ERVICE acting on Aircraft	y Leade Deepa M bindran 9 adets – ade Disa action to 9 – Lift &	rship Callalik, Math Tage O Fire Seresters; Ho Yoga & O & Drag -	apsule - flaharana ore. 0 vice & l ealth & Exerc 0 -Flaps &	Traits, aPratap, 9 Fire ises. 9 & Slats	
Indicators, Mo Ratan Tata, Kira Unit III Disaster Manag Fighting – Initia Sanitation – Fira Unit IV Laws of Motion – Stall – Thrust	tivation, Ethics & Honour code - Case Studies-Shivaji, APG An Majumdar, Jhansi Ki Rani, Narayan Murty, PrakashPadukon DISASTER MANAGEMENT AND HEALTH & ement Capsule- SochVichar, Types - Organisation, Capability tive Training, Organisation Skills, Do's and Don'ts - Natural St aid in Common Medical Emergencies, Treatment & Care of PRINCIPLES OF FLIGHT & GENERAL SE KNOWLEDGE - Glossary Terms - Bernoulli's Principle - Aerofoil - Forces Armed Forces & IAF Capsule - Modes of Entry in IAF, Civil	A Interview Skills; Abdul Kalam & D ne, Tipu Sultan, Ra HYGIENE & Role of NCC Ca Disasters, Man Ma Wounds – Introdu ERVICE acting on Aircraft I Aviation – Aircra	y Leade Deepa M bindran 9 adets – ade Disa action to 9 – Lift &	rship Callalik, Math Tage O Fire Seresters; Ho Yoga & O & Drag -	apsule - flaharana ore. 0 vice & l ealth & Exerc 0 -Flaps &	Traits, aPratap, 9 Fire ises. 9 & Slats	
Indicators, Mo Ratan Tata, Kira Unit III Disaster Manag Fighting – Initia Sanitation – Fira Unit IV Laws of Motion – Stall – Thrust & Acquisitions. Unit V Requirements of Engines – Turb	DISASTER MANAGEMENT AND HEALTH & ement Capsule- SochVichar, Types - Organisation, Capability tive Training, Organisation Skills, Do's and Don'ts – Natural Is st aid in Common Medical Emergencies, Treatment & Care of PRINCIPLES OF FLIGHT & GENERAL SE KNOWLEDGE - Glossary Terms – Bernoulli's Principle – Aerofoil – Forces Armed Forces & IAF Capsule – Modes of Entry in IAF, Civil NAVIGATION, AEROENGINES, AIRCOMP	A Interview Skills; Abdul Kalam & D ne, Tipu Sultan, Ra HYGIENE & Role of NCC Ca Disasters, Man Ma Wounds – Introdu ERVICE acting on Aircraft Aviation – Aircra AIGNS & Theory – Types of ar – Famous Air I	y Leade Deepa M bindran g g adets — ade Disa action to g — Lift & fft Recognition for g g g g g g g g g g g g g g g g g g g	rship Calalik, Math Tage O Fire Serasters; Ho Yoga & O R Drag - gnition -	apsule - Iaharana ore. 0 vice & I ealth & Exerc 0 - Flaps & - Latest	Traits, aPratap, 9 Fire ises. 9 & Slats Trends 9 nes – Jet	

Course Outcomes: Upon completion of this course, the students will be able to:		Bloom's Taxonomy Level
CO1	Acquired knowledge about the history of NCC, its organization, incentives of NCC, duties, different NCC camps	Analyze
CO2	Understand the concept of national integration and its importance	Understand
CO3	Understand the importance disaster management and health and hygiene.	Understand

CO4	Understand the importance principal of Flight and knowledge about armed services.	Understand
CO5	Understand and learn the importance of navigation, Aero engines & Airmanship work.	Understand

22CS	22CS102 COMPUTER PRACTICE AND C PROGRAMMING LABORATORY					SEMESTER II		
PREREQUISITES Category					Cro	edit	1.5	
						P	TH	
	Hours/Week						3	
Course Learning Objectives								
1	1 To provide basic knowledge to work with word processing applications							
2	2 To provide basic knowledge to work with spread sheet applications							
3 To promote the programming ability to develop C applications								
		EXPERIMENTS						

EXPERIMENTS

A. Word Processing

- 1. Creating and formatting documents.
- 2. Creating Tables and Manipulation
- 3. Using Equation Editor
- 4. Inserting Pictures, Shapes and Charts
- 5. Using Mail merge

B. Spread Sheet

- 6. Creating sheets, using built in function and use-defined formulae
- 7. Creating different types of charts from data

C. Simple C Programming

- 8. Program using different operators.
- 9. Program using Control statements.
- 10. Program using Loops, Array and Strings.
- 11. Program using Functions and pointers.
- 12. Program using Structures and Files.

For programming exercises Algorithm, Flow chart and pseudo code are essential

Total (45+15) = 60 **Periods**

	se Outcomes: completion of this course, the students will be able to:	Bloom's Taxonomy Level
CO1	Demonstrate the usage of features supported by word processing applications.	Understand and Apply
CO2	Demonstrate the usage of features supported by spread sheet applications.	Understand and Apply
CO3	Apply general programming techniques to develop digital solution to problems	Understand and Apply
CO4	Implement solutions develop with general programming techniques in C programming language	Understand and Apply

COURSE ARTICULATION MATRIX

0	
	0
0	0
0	0
0	0
0	0
	0

22ME102 WORKSHOP MANUFACTURING PRACTICES SEMESTER I						II	
PREREQUISITES Category						edit	2
				L	T	P	TH
			Hours/Week	0	0	4	4
Course Learning Objectives							
1 7	To understand the	basics of safety measures taken in the laboratory.					
To provide exposure to the students with hands-on experience on various basic engineering practices in Civil and Mechanical Engineering.							
3 7	To know about the	e various fitting joints and lathe operation.					
4 To gain knowledge in welding and fitting operation.							
5 To understand the fabrication of various models using sheet metals.							
,		LIST OF EXPERIMENT	S				

- 1. Introduction to Safety measures and First aid.
- 2. Study of Lathe, drilling machine -Welding methods and equipment- Casting process and tools- Sheet metal and fitting tools- Carpentry tools and joints.
- 3. Fitting: V-fitting, square fitting, Curve fitting.
- 4. Lathe: Facing, turning, taper turning and knurling.
- 5. Welding: BUTT, LAP and T- joints.
- 6. Foundry: Greensand preparation- mould making practice.
- 7. Sheet metal: Cone, tray, cylinder.
- 8. Carpentry: CROSS, T and DOVETAIL joints.
- 9. Drilling: simple exercises.

Total = 30 Periods

Refe	rence Books:
1	Bawa, H.S, "Workshop Practice", Tata McGraw Hill Publishing Company Limited, 2007.
2	Jeyachandran, K, Natarajan, K and Balasubramanian, S, "A Primer on Engineering Practices Laboratory", Anuradha Publications, 2007.
3	Jeyapoovan, T, SaravanaPandian, M and Pranitha, S, "Engineering Practices Lab Manual", Vikas Publishing House Pvt. Ltd, 2006.
4	Dr. P.kannan, Mr. T, Satheeskumar&Mr .K .Rajasekar, "Engineering practices laboratory" manual first edition 2017
5	Dr. V. Rameshbabu "Engineering practices laboratory" VRB publication pvt ld.

	Course Outcomes: Upon completion of this course, the students will be able to:		
CO1	Familiarize the working of various equipment and safety measures.	Understand	
CO2	Prepare fitting of metal and wooden pieces using simple fitting and carpentry tools manually.	Apply	
CO3	Fabrication of components using welding, lathe and drilling machine.	Analyze	
CO4	Make the model using sheet metal works.	Analyze	

COURSE ARTICULATION MATRIX

COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO 10	PO 11	PO 12	PSO 1	PSO 2	PSO 3
CO1	0	0	0	0	0	3	0	0	0	0	0	0	0	0	0
CO2	0	3	0	2	1	0	0	0	0	0	0	0	0	0	2
CO3	0	3	0	2	1	0	0	0	0	0	0	0	0	0	2
CO4	0	3	0	2	1	0	0	0	0	0	0	0	0	0	2
CO5	0	3	0	2	1	0	0	0	0	0	0	0	0	0	2
Avg	0	2.4	0	1.6	0.8	0.6	0	0	0	0	0	0	0	0	1.6
	3/2/1 – indicates strength of correlation (3- High, 2- Medium, 1- Low)														

SEMESTER-III

		<u>SEMESTER III</u>										
22M	A305	FOURIER SERIES, BOUNDARY VALUES PROT TRANSFORMS	BLEMS AND	S	SEMES	TER I	[I					
PRE	-REQU	JISITE:	Category	BS	Cr	edit	3					
	a eth e			L	Т	P	TH					
Basic	c 12 th lev	el knowledge of Taylor series, ODE and integration.	Hours/Week	3	0	0	3					
Cou	rse Obj	ectives:				•						
1.	To intr	oduce the concept of the Fourier series.										
2.	To und	lerstand the application of Fourier analysis in solving boundary	value problems.									
3.		tain the knowledge of solving second order ODE using Larm using convolution theorem.	aplace transform to	echnique	s and in	nverse I	Laplace					
4.	To fam	familiarize with Fourier, transform of a function and its sine and cosine transforms.										
5.	5. To gain the skills to form difference equations and find its solution by using the Z-transform method.											
UN	I TI	FOURIER SERIES		9	0	0	9					
	hlet's co val's Ide	nditions – General Fourier series – Odd and even functions – entity.	Half range sine ser	ies – Ha	lf range	cosine	series –					
UN	II II	BOUNDARY VALUE PROBLEMS		9	0	0	9					
dime	nsional h	of second-order quasi-linear partial differential equations – S neat equation – Steady-state solution of two-dimensional heat e artesian coordinates.										
UN	IT III	LAPLACE TRANSFORM		9	0	0	9					
		sform- Conditions for existence – Transform of elementary funtsform of periodic Functions – Inverse Laplace Transform- sta										
UN	IT IV	FOURIER TRANSFORM		9	0	0	9					
		Fourier integral theorem – Fourier transforms pair – Sine anons – Convolution theorem - Parseval's Identity.	d Cosine transform	s – Prop	perties –	Transfo	orms of					
UN	IT V	Z -TRANSFORM AND DIFFERENCE EQU.	ATIONS	9	0	0	9					
		of simple functions and properties – Inverse Z – transform –initidifference equations.	al and final value th	neorems-	Convol	ution the	eorem -					
					Total	= 45 P	eriods					

Text	Books:
1.	Veerarajan T, "Engineering Mathematics (For Semester III)", 3 rd Edition, Tata McGraw Hill Education Pvt. Ltd., New Delhi, 2009.
2.	P. Kandasamy, K. Thilagavathy and K. Gunavathy, "Engineering Mathematics, Volume III", S. Chand & Company ltd., New Delhi, 1996.
Refe	rence Books:
1.	Grewal, B.S., "Higher Engineering Mathematics", 43 rd Edition, Khanna Publishers, Delhi, 2014.
2.	Wylie C. Ray and Barrett Louis, C., "Advanced Engineering Mathematics", 6 th Edition, McGraw-Hill, Inc., New York, 1995.
3.	Andrews, L.A., and Shivamoggi B.K., "Integral Transforms for Engineers and Applied Mathematics", MacMillan, New York, 1988.
4.	Narayanan, S., Manicavachagom Pillai, T.K. and Ramaniah, G., "Advanced Mathematics for Engineering Students",

	SE OUTCOMES: completion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Acquire knowledge about the Fourier series.	Understand
CO2	Appreciate the physical significance of Fourier series techniques in solving one and two-dimensional heat flow problems and one-dimensional wave equations.	Understand
CO3	Apply the knowledge of the Laplace transforms.	Understand
CO4	Apply the knowledge of Fourier transform in engineering problems.	Apply
CO5	Apply the knowledge of Z-transform in engineering problems.	Apply

COUL	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	0	2	0	0	0	0	0	0	0	0	2	0	0
CO2	3	2	0	2	0	0	0	0	0	0	0	0	2	0	0
CO3	3	2	0	2	0	0	0	0	0	0	0	0	2	0	0
CO4	3	2	0	2	0	0	0	0	0	0	0	0	2	0	0
CO5	3	2	0	2	0	0	0	0	0	0	0	0	2	0	0
Avg	3	2	0	2	0	0	0	0	0	0	0	0	2	0	0
			3/2	/ 1 – inc	licates	strengtl	n of cor	relation	1 (3 – H	igh, 2 –	Medium	, 1 – Low	y)		

22M	E301	ENGINEERING THERMODYNAMIO (Use of standard thermodynamic tables, Mollier diagram		S	EMES	TER I	II.		
PRE	-REQU	ISITE:	Category	PC	Cr	edit	4		
			Hours/Week	L	T	P	TH		
			nours/ week	3	1	0	4		
Cou	rse Obje	ectives:							
1.	To impa	art the knowledge on concepts of zeroth and first law of thermo-	dynamics.						
2.	2. To make the learners to understand the third law of thermodynamics and analyze the various work and heat interactions in closed and open systems.								
3.	3. To teach properties of pure substance.								
4.	To impa	art knowledge on the concepts of steam power cycle.							
5.	To deriv	ve thermodynamic relations for ideal and real gases.		1			1		
Uì	I TIV	BASIC CONCEPT AND FIRST LAW	7	9	3	0	12		
stead UN Heat	y flow pr IT II engine –	of thermodynamics – application to closed and open systems, ocess with reference to various thermal equipment. SECOND LAW AND ENTROPY Refrigerator – Heat Pump, Second law of thermodynamics –	Kelvin's and Claus	9 sius state	3 ements-	0 Equival	12 ence of		
		nts their corollaries. Reversibility and irreversibility. Carnot caropy, principle of increase of entropy, T-s diagram, T-ds equations.	•	not cycl	e. Clau	sius ine	quality,		
UN	IT III	PROPERTIES OF PURE SUBSTANCE	ES	9	3	0	12		
		tion and its thermodynamic properties - p-v, p-T, T-v, T-s, h-s lation of work done and heat transfer in non-flow and flow pro							
UN	IT IV	STEAM POWER CYCLE		9	3	0	12		
Stand	lard Rank	ine cycle, Performance Improvement - Reheat cycle, regeneration	ive cycle and their	combina	tion cyc	les.	•		
UN	IIT V	IDEAL AND REAL GASES AND THERMO D RELATIONS	YNAMIC	9	3	0	12		
Princ	iple of co	deal and real gases, equation of state of ideal and real gases, A presponding states, reduced properties and compressibility chapter, T-ds relations, Clausius Clapeyron equations and Joule Thoms	rt. Exact differenti		-				
			Te	otal (45)	L+15T)= 60 P	eriods		
Text	Books:								
1.	Nag. P.	K, "Engineering Thermodynamics", Tata McGraw-Hill, New I	Delhi, 2017.						

Text	Text Books:								
1.	Nag. P.K, "Engineering Thermodynamics", Tata McGraw-Hill, New Delhi, 2017.								
2.	Sonntag, R.E., Borgnakke, C., and Van Wylen, G.J., Fundamentals of Thermodynamics, 6th ed., John Wiley, 2003.								
3.	Arora C.P, "Thermodynamics", Tata McGraw Hill, New Delhi, 2003.								
4.	Venwylen and Sontag, "Classical Thermodynamics", Wiley Eastern, 1987.								
Refe	Reference Books:								
1.	Cengel, "Thermodynamics- An Engineering Approach", 3rd Edition, Tata McGraw Hill,2015.								

Merala C, Pother, Craig W and Somerton, "Thermodynamics for Engineers", Schaum Outline Series, Tata McGraw-Hill, New Delhi, 2004.

	SE OUTCOMES: completion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Understand the concepts of zeroth, first and second law of thermodynamics.	Remember
CO2	Analyze the various work and heat interactions for different types of processes for closed and open systems	Evaluate
CO3	Evaluate the different properties of pure substances using steam tables and Mollier chart	Evaluate
CO4	Analyze the performance of steam power cycle.	Analyze
CO5	Derive thermodynamic relations for ideal and real gases.	Analyze

COUI	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	2	2	0	0	1	0	0	0	0	1	3	1	1
CO2	3	3	2	2	0	0	1	0	0	0	0	1	3	1	1
CO3	3	3	3	2	0	1	1	0	0	0	0	1	3	1	1
CO4	2	3	2	2	0	1	1	0	0	0	0	1	3	1	1
CO5	3	3	2	2	0	1	0	0	0	0	0	1	3	1	1
Avg	2.8	3	2.2	2	0	0.6	0.8	0	0	0	0	1	3	1	1
	•		3/2	/ 1 – inc	dicates	strengtl	h of cor	relation	1 (3 – H	ligh, 2 –	Medium	, 1 – Lov	v)		

22ME	302	FLUID MECHANICS AND MACHINE	RY	S	SEMES	TER II	I			
PRE-I	REQU	ISITE:	Category	PC	Cro	edit	4			
1. Engi	ineering	Physics		L	Т	P	TH			
_	_	Chemistry	Hours/Week	3	1	0	4			
		Mathematics			_	Ů	-			
	e Obje									
1.	-	derstand the basic concepts and properties of fluids								
2.		alyze the kinematic and dynamic concepts of fluid flow	11.4	14						
3.										
4. 5.										
				9	3	0	12			
density	Basic concepts and units of measurement of physical quantities- Classification of fluids - Properties of fluids - density, relative density, vapour pressure, surface tension, Capillarity and viscosity. Fluid statics- hydrostatic pressure, buoyancy and Archimedes' principle.									
UNI	T II	FLUID KINEMATICS AND DYNAMIO	CS	9	3	0	12			
streaml applica	line, pat tions.	of fluid flow - system and control volume - Lagrangian and E h line, streak line and timeline. Velocity potential function a Fluid dynamics - Bernoulli's equation and its applications. omogeneity, similarity-laws and models.	and Stream function	on - cont	tinuity e	quation	and its			
UNIT	ΓIII	FLOW THROUGH PIPES AND PLAT	ES	9	3	0	12			
pipes a hydrau layer fl	nd flow lic grad lows - B	e fluid flow-Laminar flow- Hagen-Poiseuille equation, shear st between parallel plates. Turbulent flow – flow through pipes, the ient line, flow through pipes in series and parallel- Moody's foundary layer thickness, momentum thickness, energy thickness	riction factors in turiction factor chart	rbulent : . Power separation	flow - to transmis n.	otal energession-Bo	gy line, oundary			
UNIT		HYDRAULIC TURBINES		9	3	0	12			
perforn	nance ci	ines classification-impulse and reaction turbines-Working prin urves for Pelton, Francis and Kaplan turbines. Comparison bet ion -draft tubes.		•			•			
UNI	UNIT V HYDRAULIC PUMPS 9 3 0 12									
and pri	iming. F	of hydraulic pumps-Centrifugal pumps - working principle, ve Reciprocating pumps - classification, working principle, indica umps. Working principles of gear and vane pumps.		_	_					
			To	tal (451	L+ 15T)	= 60 P	eriods			

Text	Text Books:								
1.	Bansal, R.K., "A Textbook of Fluid Mechanics and Hydraulic Machines, 9th Ed", Laxmi Publication Pvt Ltd, 2010.								
2.	Rajput, R.K., "A Textbook of Fluid Mechanics and Hydraulic Mechanics", S.Chand and Company Ltd, 2011.								
3.	Subramanya. K., "Fluid Mechanics and Hydraulic Machines", Tata McGraw Hill Publishing Company Ltd, 2011.								
Refe	Reference Books:								
1.	White, "Fluid Mechanics, 8 Ed", McGraw Hill India, 2017.								
2.	Munson, Young and Okiishi, "Fundamentals of Fluid Mechanics 8 th Edition", Wiley, 2016.								
3.	Yunuscengel, John. M.cimbala, "Fluid Mechanics Fundamentals and Applications", McGraw Hill, 2017.								

- 4. Som, S.K, Biswas.G and SumanChakraborty, "Introduction to Fluid Mechanics and Fluid Machines", Tata McGraw Hill India, 2011.
- 5. Dr.P.N.Modi, Dr.S.M.Seth, "Hydraulics and Fluid Mechanics including Hydraulic Machines", Standard book house, 2018.

E-References:

1. NPTEL courses: http://nptel.iitm.ac.in/courses.php - web and video sources on fluid mechanics.

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:						
CO1	Understand the basic concepts and properties of fluids	Remember					
CO2	Analyze the kinematic and dynamic concepts of fluid flow	Analyze					
CO3	Understand the various incompressible fluid flow through pipes and between parallel plates	Understand					
CO4	Apply the principles of fluid mechanics to design and operation of hydraulic turbines	Apply					
CO5	Apply the principles of fluid mechanics to design and operation of hydraulic pumps	Apply					

	NOVEMBER A DEPOSIT A PRODUCTION OF THE PRODUCTIO														
COUL	OURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1	1	0	0	0	2	0	0	0	1	0	2	2	1
CO2	3	3	1	0	2	0	0	0	0	0	0	0	2	2	1
CO3	2	3	2	2	1	0	0	0	0	0	0	0	2	2	1
CO4	3	3	3	2	1	2	1	0	0	0	0	0	2	2	1
CO5	3	3	3	2	1	2	1	0	0	0	0	0	2	2	1
Avg	2.8	2.6	2	1.2	1	0.8	0.8	0	0	0	0.2	0	2	2	1
			3/2	/ 1 – inc	dicates	strengtl	h of cor	relatio	1 (3 – H	[igh, 2 –]	Medium	, 1 – Lov	v)		

22M	E303	MANUFACTURING PROCESSES		S	SEMES	TER I	I			
PRE	-REQU	ISITE:	Category	PC	Cr	edit	3			
1. Bas	sic scienc	ce, Engineering mathematics, Engineering Physics	TT /537 1	L	Т	P	С			
2. En	gineering	g Materials	Hours/Week	3	0	0	3			
Cour	rse Obje	ectives:					•			
1.	To mak	te the students familiarize with various manufacturing processes ng.	s and fabrication t	echnique	es of me	tals and	design			
2.	To deve	velop design concepts of various manufacturing processes.								
3.	Gain kr	nowledge to select appropriate manufacturing processes for various	ous parts.							
4.	To deve	elop an entrepreneur skill among the students.								
5.	To eval	uate and select plastic deformation processes for various parts.								
UN	I TI	CASTING		9	0	0	9			
solidi	fication	Manufacturing Process -Sand casting -Patterns – Design of P time calculation - Moulding machines - Core making. Spec estment moulding, pressure die casting, centrifugal casting, casti	ial moulding pro		_		_			
	T/D TT	WELDING		9	0	0	9			
Class		of welding processes. Principles of Oxy-acetylene gas we	-	weldin	g, resis	tance w	elding			
Class subm beam	ification erged are welding	of welding processes. Principles of Oxy-acetylene gas we welding, tungsten inert gas welding, metal inert gas welding, laser beam welding, defects in welding, Soldering and Brazing,	g, plasma arc wel	weldin	g, resis	tance w	elding			
Class subme beam UNI Metal proce	ification erged are welding IT III Illurgical esses, Ho	of welding processes. Principles of Oxy-acetylene gas welding, tungsten inert gas welding, metal inert gas welding, laser beam welding, defects in welding, Soldering and Brazing, METAL FORMING aspects of metal forming, slip, twinning mechanics of plastic of tworking and cold working of metals, Forging processes — op	Adhesive Bondin deformation, load pen, closed and in	weldin ding, the g. 10 estimation appression	g, resis	tance welding, e	relding lectron 10 mation forging			
Class: submi- beam UNI Metal proce opera	ification erged are welding IT III llurgical esses, Hotions. Re	of welding processes. Principles of Oxy-acetylene gas we welding, tungsten inert gas welding, metal inert gas welding, laser beam welding, defects in welding, Soldering and Brazing, METAL FORMING aspects of metal forming, slip, twinning mechanics of plastic of	g, plasma arc weld Adhesive Bondin deformation, load pen, closed and in hape rolling opera	weldin ding, the g. 10 estimation appression	g, resis	tance welding, e	relding lectron 10 mation forging			
Class subme beam UNI Metal proce opera Princi	ification erged are welding IT III llurgical esses, Hotions. Re	of welding processes. Principles of Oxy-acetylene gas we welding, tungsten inert gas welding, metal inert gas welding, laser beam welding, defects in welding, Soldering and Brazing, METAL FORMING aspects of metal forming, slip, twinning mechanics of plastic of tworking and cold working of metals, Forging processes – opolling of metals—Types of Rolling mill – Flat strip rolling—sl	g, plasma arc weld Adhesive Bondin deformation, load pen, closed and in hape rolling opera	weldin ding, the g. 10 estimation appression	g, resis	tance welding, e	relding lectron 10 matior forging			
Class submobeam UNI Metal proce opera Princi UNI Types and ty blowing the submobe and ty blowing the submobe and types are types.	ification erged are welding IT III Illurgical esses, Ho tions. Reciple of ro IT IV s of plast ypical aping – Ext	of welding processes. Principles of Oxy-acetylene gas we welding, tungsten inert gas welding, metal inert gas welding, laser beam welding, defects in welding, Soldering and Brazing, METAL FORMING aspects of metal forming, slip, twinning mechanics of plastic of tworking and cold working of metals, Forging processes – opolling of metals— Types of Rolling mill — Flat strip rolling— slid and wire drawing— Tube drawing— Principles of Extrusion—	g, plasma arc weld Adhesive Bondin deformation, load oen, closed and in hape rolling opera Types.	welding, the g. 10 estimation pression ations — 8 noplastic g — Rota	g, resis ermit we on of but the die for t	tance welding, e	relding lectron 10 matior forging d parts 8 nciples – Film			
Class submode beam UNI Metal proce opera Princi UNI Types and tyblowitypica	ification erged are welding IT III Illurgical esses, Ho tions. Reciple of ro IT IV s of plast ypical aping – Ext	of welding processes. Principles of Oxy-acetylene gas welcome welding, tungsten inert gas welding, metal inert gas welding, laser beam welding, defects in welding, Soldering and Brazing, METAL FORMING aspects of metal forming, slip, twinning mechanics of plastic of tworking and cold working of metals, Forging processes — opolling of metals— Types of Rolling mill — Flat strip rolling — sld and wire drawing — Tube drawing — Principles of Extrusion — SHAPING OF PLASTICS tics - Characteristics of the forming and shaping processes — Melications of - Injection moulding — Plunger and screw machines trusion - Typical industrial applications — Thermoforming — Processes — Melications — Typical industrial applications — Thermoforming — Processes — Melications — Typical industrial applications — Thermoforming — Processes — Melications — Typical industrial applications — Thermoforming — Processes — Melications — Typical industrial applications — Thermoforming — Processes — Melications — Typical industrial applications — Thermoforming — Processes — Melications — Typical industrial applications — Thermoforming — Processes — Melications — Typical industrial applications — Thermoforming — Processes — Melications — Typical industrial applications — Thermoforming — Processes — Melications — Typical industrial applications — Thermoforming — Processes — Melications — Typical industrial applications — Thermoforming — Processes — Melications — Typical industrial applications — Thermoforming — Processes — Melications — Typical industrial applications — Thermoforming — Processes — Melications — Typical industrial applications — Thermoforming — Processes — Melications — Typical industrial applications — Thermoforming — Processes — Melications — Typical industrial applications — Typical industrial app	Adhesive Bondin deformation, load on, closed and in hape rolling opera Types. Moulding of Therm is – Blow moulding of Therm occessing of Therm	welding, the g. 10 estimation pression ations — 8 noplastic g — Rota	g, resis ermit we on of but the die for t	tance welding, e	relding lectron 10 mation forging d parts 8 nciple – Film			
Classisubmi beam UNI Metal proce opera Princi UNI Types and typica UNI Form presse	ification erged are welding IT III Illurgical esses, Ho tions. Reiple of roll IT IV is of plast ypical applical applical applical applical applical applical applical applical applical application in the second in	of welding processes. Principles of Oxy-acetylene gas welcome welding, tungsten inert gas welding, metal inert gas welding, laser beam welding, defects in welding, Soldering and Brazing, METAL FORMING aspects of metal forming, slip, twinning mechanics of plastic of tworking and cold working of metals, Forging processes — opolling of metals— Types of Rolling mill — Flat strip rolling — sld and wire drawing — Tube drawing — Principles of Extrusion — SHAPING OF PLASTICS tics - Characteristics of the forming and shaping processes — Melications of - Injection moulding — Plunger and screw machines trusion - Typical industrial applications — Thermoforming — Protein a compression moulding — Transfer moulding.	deformation, load pen, closed and in hape rolling operatives. Ioulding of Therm is – Blow moulding of Therm is –	welding the g. 10 estimation pression ations — 8 noplastic g — Rota osets — V	g, resistermit we examine we were to be a die for Defects O	tance welding, e	relding lectron 10 mation forging d parts 8 nciple – Film les and			

Text Books:

- 1. HajraChoudhury, "Elements of Workshop Technology", Vol. I and II, Media Promoters and Publishers Pvt., Ltd., Mumbai, 2005.
- 2. NagendraParashar B.S. and Mittal R.K., "Elements of Manufacturing Processes", Prentice-Hall of India Private Limited, 2007.

Reference Books:

SeropeKalpajian, Steven R.Schmid, "Manufacturing Processes for Engineering Materials",4/e, Pearson Education, Inc. 2007.

2.	Jain. R.K., and S.C. Gupta, "Production Technology", 16th Edition, Khanna Publishers, 2001.						
3.	"H.M.T. "Production Technology – Handbook", Tata McGraw-Hill, 2000.						
4.	Roy. A. Linberg, "Process and Materials of Manufacture", PHI, 2000.						
5.	Mikell P. Groover, Fundamentals of Modern Manufacturing: Materials, Processes, and Systems.						
E-Re	E-References:						
1.	https://fdocuments.in/document/production-technology-55844cac00bfc.html?page=40						

COURSE OUTCOMES: Upon completion of the course, the students will be able to:						
COI	Describe the operational features of various casting processes, design of gate, riser and discover various defects in casting.	Understand				
CO2	Explain various metal joining processes and compare them.					
соз	Summarize several types of metal forming processes and select suitable method for different applications.	Analyze				
CO4	Analyze various manufacturing methods for plastics and their needs in industry.	Analyze				
CO5	Describe various sheet metal forming processes, load estimation calculation and principles of powder metallurgy	Understand				

COU	OURSE ARTICULATION MATRIX															
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	
CO1	2	1	2	1	0	0	0	0	0	1	0	0	1	2	1	
CO2	2	1	2	1	0	1	0	0	1	1	0	0	1	2	1	
CO3	1	1	1	1	0	0	0	0	0	1	0	0	1	1	1	
CO4	1	1	1	0	1	0	0	0	0	1	0	0	1	1	1	
CO5	0	1	0	0	0	0	0	0	1	1	0	0	1	0	1	
Avg	1.2	1	1.2	0.6	0.2	0.2	0	0	0.4	1	0	0	1	1.2	1	
	•	•	3/2	/ 1 – inc	dicates	3/2/1 – indicates strength of correlation (3 – High, 2 – Medium, 1 – Low)										

22M	T310	MATERIALS ENGINEERING		S	EMES	TER II	I
PRE	E-REQUI	SITE: C	ategory	ES	Cro	edit	3
1. Er	ngineering l	Physics	/XX/ 1	L	T	P	TH
2.En	gineering C	Chemistry	urs/Week	3	0	0	3
Cou	rse Objec	tives:					
1.	To impartemperat	t concept on reactions, treatment, microstructure and mechanical bure.	ehavior of en	gineerin	g mater	ials at d	ifferent
2.	To learn	basic principles in metallurgy and materials engineering.					
3.	To identi	ty and select suitable engineering materials based on their application	ons				
U	NIT I	PHASE DIAGRAMS		9	0	0	9
syste	ms – Eute	es, Phases, solid solution types, compounds, Hume-Rothery rules; octic, Eutectoid, Peritectic systems. Lever rule, Equilibrium and s of alloying elements – Ferrite and Austenite Stabilizers, TTT and other stabilizers.	non-equilibri	um cool	-	-	-
Ul	II TIN	HEAT TREATMENT		9	0	0	9
UN	NIT III			1			
		FERROUS AND NON-FERROUS METALS els – Tool steels - maraging steels – HSLA steels. Stainless steels n hardened stainless steels. Types of Cast Irons- Gray cast iron, where the stainless steels is the stainless steels.					_
and 1	precipitatio		nite cast iron,	Austeni	tic, mar	tensitic,	duplex
and p Copp UN	precipitatio per alloys – NIT IV	tels – Tool steels - maraging steels – HSLA steels. Stainless steels in hardened stainless steels. Types of Cast Irons- Gray cast iron, where Brass, Bronze and Cupronickel, Aluminium alloys, Bearing alloys. MECHANICAL PROPERTIES AND TESTING	nite cast iron,	Austeni malleab	tic, mar	tensitic, iron, S.C	duplex G. Iron
and p Copp UN Mecl	precipitation per alloys — NIT IV hanical proture - Type	tels – Tool steels - maraging steels – HSLA steels. Stainless steels in hardened stainless steels. Types of Cast Irons- Gray cast iron, where Brass, Bronze and Cupronickel, Aluminium alloys, Bearing alloys.	ion, slip and ar loads - fat	Austeni malleab 9 twinning	tic, mar ble cast:	tensitic, iron, S.C	duplex G. Iron 9 gue and
and part of the control of the contr	precipitation per alloys — NIT IV hanical proture - Type	tels – Tool steels - maraging steels – HSLA steels. Stainless steels in hardened stainless steels. Types of Cast Irons- Gray cast iron, where Brass, Bronze and Cupronickel, Aluminium alloys, Bearing alloys. MECHANICAL PROPERTIES AND TESTING perties of engineering materials - Mechanisms of plastic deformats of fracture – Testing of materials - tension, compression and she	ion, slip and ar loads - fati	Austeni malleab 9 twinning	tic, mar ble cast:	tensitic, iron, S.C	duplex G. Iron. 9 gue and
and p Copp UN Mecl Fract and i Ul Non- inspec	precipitation per alloys — NIT IV hanical proture - Type ts effects — NIT V Destructive ection and	bels – Tool steels - maraging steels – HSLA steels. Stainless steels in hardened stainless steels. Types of Cast Irons- Gray cast iron, where Brass, Bronze and Cupronickel, Aluminium alloys, Bearing alloys. MECHANICAL PROPERTIES AND TESTING perties of engineering materials - Mechanisms of plastic deformats of fracture – Testing of materials - tension, compression and she testing for hardness (Brinell, Vickers and Rockwell) - Impact test - NON-DESTRUCTIVE TESTING AND SURFACE.	ion, slip and ar loads - fatilized and Chartesting, Ultrasor Definition, d	Austeni malleab 9 twinning igue and arpy. 9 onic testiliffusion	tic, mar ble cast a 0 g - Cree creep t	tensitic, iron, S.C	duplex 3. Iron 9 gue and ardness 9 particle
and p Copp UN Mecl Fract and i Ul Non- inspec	precipitation per alloys — NIT IV hanical proture - Type ts effects — NIT V Destructive ection and	rels – Tool steels - maraging steels – HSLA steels. Stainless steels in hardened stainless steels. Types of Cast Irons- Gray cast iron, where Brass, Bronze and Cupronickel, Aluminium alloys, Bearing alloys. MECHANICAL PROPERTIES AND TESTING perties of engineering materials - Mechanisms of plastic deformats of fracture – Testing of materials - tension, compression and she testing for hardness (Brinell, Vickers and Rockwell) - Impact test - NON-DESTRUCTIVE TESTING AND SURFACENGINEERING e Testing: Basic principles, Testing method - Radiographic Testiquid penetrant inspections. Introduction to surface engineering—	ion, slip and ar loads - fatilized and Chartesting, Ultrasor Definition, d	Austeni malleab 9 twinning igue and arpy. 9 onic testiliffusion	tic, mar ole cast: 0 g - Cree creep t	tensitic, iron, S.C	duplex G. Iron 9 gue and ardness 9 particle position
and I Copp UN Mecl Fract and i Ul Non- inspec meth	precipitation per alloys — NIT IV hanical proture - Type ts effects — NIT V Destructive ection and	rels – Tool steels - maraging steels – HSLA steels. Stainless steels in hardened stainless steels. Types of Cast Irons- Gray cast iron, where Brass, Bronze and Cupronickel, Aluminium alloys, Bearing alloys. MECHANICAL PROPERTIES AND TESTING perties of engineering materials - Mechanisms of plastic deformats of fracture – Testing of materials - tension, compression and she testing for hardness (Brinell, Vickers and Rockwell) - Impact test - NON-DESTRUCTIVE TESTING AND SURFACENGINEERING e Testing: Basic principles, Testing method - Radiographic Testiquid penetrant inspections. Introduction to surface engineering—	ion, slip and ar loads - fatilized and Chartesting, Ultrasor Definition, d	Austeni malleab 9 twinning igue and arpy. 9 onic testiliffusion	tic, mar ole cast: 0 g - Cree creep t	tensitic, iron, S.C o ep, Fatigests – harmonic properties of the control of the	duplex G. Iron 9 gue and ardness 9 particle position
and I Copp UN Mecl Fract and i Ul Non- inspec	precipitation per alloys — NIT IV hanical produce - Type ts effects — NIT V Destructive ection and allods, high a set to the set	rels – Tool steels - maraging steels – HSLA steels. Stainless steels in hardened stainless steels. Types of Cast Irons- Gray cast iron, where Brass, Bronze and Cupronickel, Aluminium alloys, Bearing alloys. MECHANICAL PROPERTIES AND TESTING perties of engineering materials - Mechanisms of plastic deformats of fracture – Testing of materials - tension, compression and she testing for hardness (Brinell, Vickers and Rockwell) - Impact test - NON-DESTRUCTIVE TESTING AND SURFACENGINEERING e Testing: Basic principles, Testing method - Radiographic Testiquid penetrant inspections. Introduction to surface engineering—	ion, slip and ar loads - fattized and Cha	Austeni malleab 9 twinning igue and arpy. 9 onic testiliffusion ics.	tic, mar ole cast : ole cast	tensitic, iron, S.C o ep, Fatigests – harmonic properties of the control of the	duplex G. Iron 9 gue and ardness 9 particle position
and I Copp UN Mecl Fractand i Ul Non- inspecementh	precipitation per alloys — NIT IV hanical produce - Type ts effects — NIT V Destructive ection and anods, high a second to the color of the colo	tels – Tool steels - maraging steels – HSLA steels. Stainless steels in hardened stainless steels. Types of Cast Irons- Gray cast iron, where the Brass, Bronze and Cupronickel, Aluminium alloys, Bearing alloys. MECHANICAL PROPERTIES AND TESTING perties of engineering materials - Mechanisms of plastic deformats of fracture – Testing of materials - tension, compression and she testing for hardness (Brinell, Vickers and Rockwell) - Impact test - NON-DESTRUCTIVE TESTING AND SURFACE ENGINEERING Testing: Basic principles, Testing method - Radiographic Testiquid penetrant inspections. Introduction to surface engineering—and low energy beam methods, surface engineering charts, elastic contents.	ion, slip and ar loads - fatt Izod and Cha	Austeni malleab 9 twinning igue and arpy. 9 onic testiliffusion ics.	tic, mar ole cast : ole cast	tensitic, iron, S.C o ep, Fatigests – harmonic properties of the control of the	duplex G. Iron 9 gue and ardness 9 particle position
and p Copp UN Meccl Fractand i Un Non- inspecementh Text 1.	precipitation per alloys — NIT IV hanical proture - Type ts effects — NIT V Destructive ection and allods, high a least tooks: Kenneth Raghava Aswani.I	rels – Tool steels - maraging steels – HSLA steels. Stainless steels in hardened stainless steels. Types of Cast Irons- Gray cast iron, where Brass, Bronze and Cupronickel, Aluminium alloys, Bearing alloys. **MECHANICAL PROPERTIES AND TESTING** **perties of engineering materials - Mechanisms of plastic deformats of fracture – Testing of materials - tension, compression and she testing for hardness (Brinell, Vickers and Rockwell) - Impact test - NON-DESTRUCTIVE TESTING AND SURFACENGINEERING** **e Testing: Basic principles, Testing method - Radiographic Testiquid penetrant inspections. Introduction to surface engineering—and low energy beam methods, surface engineering charts, elastic confidence of the properties of the p	ion, slip and ar loads - fat: Izod and ChacE sting, Ultraso Definition, dentact mechanicative Hall of Italy Ltd., 1999.	Austeni malleab 9 twinning igue and arpy. 9 onic testi diffusion ics.	tic, mar ole cast : ole cast	tensitic, iron, S.C o ep, Fatig ests – ha o ugnetic pues, dep	duplex G. Iron 9 gue and ardness 9 particle position
Mecle Fraction and in the control of	hanical proture - Type ts effects - NIT V Destructive ection and adds, high a Kenneth Raghava Aswani. I Khanna C	pels – Tool steels - maraging steels – HSLA steels. Stainless steels in hardened stainless steels. Types of Cast Irons- Gray cast iron, where the Brass, Bronze and Cupronickel, Aluminium alloys, Bearing alloys. MECHANICAL PROPERTIES AND TESTING perties of engineering materials - Mechanisms of plastic deformats of fracture – Testing of materials - tension, compression and she testing for hardness (Brinell, Vickers and Rockwell) - Impact test - NON-DESTRUCTIVE TESTING AND SURFACENGINEERING Testing: Basic principles, Testing method - Radiographic Testiquid penetrant inspections. Introduction to surface engineering—and low energy beam methods, surface engineering charts, elastic confidence of the properties	ion, slip and ar loads - fat: Izod and ChacE sting, Ultraso Definition, dentact mechanicative Hall of Italy Ltd., 1999.	Austeni malleab 9 twinning igue and arpy. 9 onic testi diffusion ics.	tic, mar ole cast : ole cast	tensitic, iron, S.C o ep, Fatig ests – ha o ugnetic pues, dep	duplex G. Iron 9 gue and ardness 9 particle position
Mecle Fraction and in the control of	hanical proture - Type ts effects - NIT V Destructive ection and adds, high a service the Raghava Aswani. I Khanna Gerence Bo	pels – Tool steels - maraging steels – HSLA steels. Stainless steels in hardened stainless steels. Types of Cast Irons- Gray cast iron, where the Brass, Bronze and Cupronickel, Aluminium alloys, Bearing alloys. MECHANICAL PROPERTIES AND TESTING perties of engineering materials - Mechanisms of plastic deformats of fracture – Testing of materials - tension, compression and she testing for hardness (Brinell, Vickers and Rockwell) - Impact test - NON-DESTRUCTIVE TESTING AND SURFACENGINEERING Testing: Basic principles, Testing method - Radiographic Testiquid penetrant inspections. Introduction to surface engineering—and low energy beam methods, surface engineering charts, elastic confidence of the properties	ion, slip and ar loads - fatt Izod and Charles Esting, Ultraso Definition, dentact mechanism tice Hall of Italy Ltd., 1999. w Delhi, 2001 Rai Sons, 200	Austeni malleab 9 twinning igue and arpy. 9 onic testi diffusion ics.	tic, mar ole cast : ole cast	tensitic, iron, S.C o ep, Fatig ests – ha o ugnetic pues, dep	duplex G. Iron. 9 gue and ardness 9 particle position

Sydney.H.Avner, "Introduction to Physical Metallurgy" Mc Graw Hill Book Company, 1994.

2.

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:							
CO1	Understand the formation of materials and their classification based on atomic structure.	Understand						
CO2	Understand the principles of various heat treatment processes in fabrication industry.	Understand						
СОЗ	Describe properties, applications and types of various ferrous and non-ferrous metals used in fabrication industry	Understand						
CO4	Describe various types of failure and select methods for destructive testing	Understand						
CO5	Select methods for Non-destructive testing	Evaluate						

COUL	COURSE ARTICULATION MATRIX																	
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3			
CO1	1	1	2	2	1	1	1	0	0	0	0	0	2	3	1			
CO2	1	0	2	1	1	2	1	0	0	0	0	0	2	3	1			
CO3	0	1	1	1	1	0	1	0	0	0	0	0	3	2	1			
CO4	0	2	2	1	1	1	1	0	0	0	0	0	2	3	1			
CO5	0	2	2	2	1	0	1	0	0	0	0	0	2	2	1			
Avg	0.4	1.2	1.8	1.4	1.0	0.8	1	0	0	0	0	0	2.2	2.6	1.0			
			3/2	/ 1 – inc	dicates	strengt	h of cor	3/2/1 – indicates strength of correlation (3 – High, 2 – Medium, 1 – Low)										

22M	CIN02	INNOVATION SPRINTS		SEMESTER III					
PRE	-REQUI	SITE:	Category	EE	Cr	edit	1		
			TT /TT/ 1	L	Т	P	TH		
			Hours/Week	0	0	2	2		
Cour	rse Obje	ctives:					1		
1.	To unde	erstand the fundamentals of Design thinking & apply in ideating	solutions for real	-world p	roblems				
2.	To solve	e challenges through problem curation, problem validation and	customer discover	y proble	ms.				
UN	I TIV	CHALLENGE CURATION		3	0	0	3		
		Design Thinking Principles - Design Thinking Values - Design sign challenge.	n Thinking Metho	ds - Cha	allenge i	impact s	etting -		
UN	II TII	CUSTOMER-CENTRIC INNOVATION	N	3	0	0	3		
	U	Customer needs - Empathy building techniques - gap analysis ights into Innovation Opportunities	s - adoption barrie	ers - obs	ervation	s and in	sights -		
UN	IT III	IDEA GENERATION		3	0	0	3		
		ins & gains - crafting value proposition - Ideation - Div Managing risks - Concept of minimum usable prototypes - Ge	0 0		on metl	nods- R	ules of		
UN	IT IV	PROTOTYPING		3	0	0	3		
	• • •	ncepts Palm Pilot Experiment - Fake it before make it - sting the Prototypes	Prototyping - Th	e Law o	of Failu	re - Bui	lding a		
UN	IT V	PITCH & PRESENTATION		3	0	0	3		
		orytelling - the blueprint for storytelling - Pitch Script - Pitch - communication fundamentals	tch Presentations	- Best	practice	s to cre	ating a		
					Total	= 15 P	eriods		

Text	Text Books:							
1.	Tim Brown (2019), "Change by Design: How design thinking transforms organizations and inspires innovation"							
2.	Jan Chipchase& Simon Steinhardt (2013), "Hidden in Plain Sight: How to Create extraordinary Products for Tomorrow's Customers", Harper Business 2013							
3.	Christian Madsbjerg&Mikkel B. Rasmussen (2014), "The Moment of Clarity", Harvard Business Review Press							
4.	IdrisMootee(2013), Design Thinking for Strategic Innovation, Willey							
5.	Alexander Osterwalder, Value Proposition Design: How to Create Products and Services Customers Want (Strategyzer) John Wiley & Sons, 2014							
Refe	rence Books:							
1.	Avoia. Alberto, 2009 The Pretotyping Manifesto -							
2.	https://sites.google.com/a/pretotyping.org/www/the-pretotyping-manifesto							
3.	Jazz Factory, All about Presentations - http://blog.jazzfactory.in/							
4.	Pretotyping Methodology - https://www.pretotyping.org/methodology.html							

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:							
CO1	Identify real-world problems	Understand						
CO2	Apply the challenge curation techniques to real-world problems.							
СОЗ	Analyze the problems and generate solutions to address the challenges	Analyze						
CO4	Build solutions using prototyping tools & techniques	Apply						
CO5	Develop an innovation pitch to effectively communicate the idea to solve the identified problem							

COUL	RSE A	RTICU	<u>JLATI</u>	ON M.	ATRIX	<u> </u>									
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	0	3	0	0	0	2	1	0	2	0	0	0	0	0	2
CO2	0	3	0	2	0	0	0	0	2	0	0	0	0	0	2
CO3	0	0	3	2	0	0	0	0	2	0	0	0	0	0	2
CO4	2	0	3	0	0	0	0	1	2	0	0	0	0	0	2
CO5	0	0	0	0	0	0	0	0	2	3	0	0	0	0	2
Avg	0.4	1.2	1.2	0.8	0	0.4	0.2	0.2	2	0.6	0	0	0	0	2
			3/2	/ 1 – inc	licates s	strengtl	of cor	relation	1 (3 – H	ligh, 2 – 1	Medium	, 1 – Low	7)		

22NC301	NCC COURSE-II (Only for NCC Stude	ents)	S	SEMES	TER I	ΙI
PRE-REQUI	SITE:	Category	NC	Cr	edit	0
			L	Т	P	TH
		Hours/Week	3	0	0	3
Course Object	ctives:			I.		·
1. To main	tain the unity and disciplines to the students					
UNIT I	SOCIAL SERVICE & COMMUNITY DEVEL	LOPMENT	9	0	0	9
Traffic Control	organization – Anti Drunken Driving. CENERAL AWARENESS & ADVENT			ı	I	
UNIT II	GENERAL AWARENESS & ADVENT	URE	9	0	0	9
	edge – Logical & Analytical Reasoning - Modes of Entry to Acock climbing – Cycling and Trekking.	Army, CAPF, Police	e – SSB I	Procedu	re; Para	Sailing
UNIT III	AEROENGINES & NAVIGATION	Ī	9	0	0	9
engines – Bray	aero engines and its type – Components of aero engines – Fiton Cycle – Turbo prop engines and its types; Requirements of in map – Scales of map – Map reading procedure and its aids	of Navigation - Line			-	•
UNIT IV	AIRFRAME & METEOROLOGY		9	0	0	9
	ol – Primary and Secondary –Fuselage – Main Plain and Taice of METT in Aviation – Atmosphere – Clouds and Precipita			rs& Ru	dders –I	anding
UNIT V	FLIGHT INSTRUMENTS & AEROMODE	ELLING	9	0	0	9
-	ator – Altimeter – Artificial Horizon – Radar and Its Type – It asic Materials & Tools – Types of Aero Modelling – Fl	•		-	-	
				Total	= 45 P	eriods

	SE OUTCOMES: mpletion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Acquired knowledge about social and legal responsibilities.	Understand
CO2	Understand the adventure activities and verbal training on defense examinations.	Remember and Understand
CO3	Understand the technical knowledge on aero engines and map reading.	Understand
CO4	Understand the structure and control of an aircraft.	Understand
CO5	Understand and learn the importance of avionic instruments on aircraft control.	Remember and Understand

COUI	RSE A	RTICU	JLATI	ON M	ATRIX	<u> </u>									
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1	0	0	0	0	0	0	0	0	0	0	3	1	1
CO2	3	3	2	3	0	0	0	0	0	0	0	0	3	2	1
CO3	3	2	3	1	0	2	0	0	0	0	0	0	3	2	1
CO4	3	2	2	2	0	0	0	0	0	0	0	0	3	2	1
CO5	3	0	0	0	0	1	0	0	0	0	0	0	3	3	1
Avg	3	1.6	1.4	1.2	0	0.6	0	0	0	0	0	0	3	2	1

3/2/1 – indicates strength of correlation (3 - High, 2 - Medium, 1 - Low)

22ME304	CAD LABORATORY		SEMESTER III					
PRE-REQU	ISITE:	Category	PC	Credit		1.5		
1. Engineering	Drawing	House/Wools	L	T	P	TH		
2. Machine Dr	rawing	Hours/Week	0	0	3	1.5		

Course Objectives:

- 1. Understand the Code of drawing practice as per BIS conventions for mechanical elements using CAD software.
- 2. Practice the methods for sectioning and drawing the joints, couplings, bearings, and keys.
- 3. Prepare assembly drawings, sectional views and bill of materials for selected assemblies.

CAD EXPERIMENTS

The students will be required to carry out the following exercises using software packages (e.g. 3D modeling package / Pro Engineer/ CATIA /I-Deas/ Solid Edge/Solid Works etc.)

- Introduction to advanced modeling software
- Part Modeling of Screw Jack
- Part Modeling of Flange Coupling
- Part Modeling of Plummer Block
- Part Modeling of Knuckle Joint
- Creation of 3D assembly model of universal joint
- Creation of 3D assembly model of connecting rod
- Creation of 3D assembly model of crankshaft
- Creation of 3D assembly model of Lathe Tailstock
- Creation of 3D assembly model of Piston.
- Creation of 3D assembly model of Safety valve.
- Detailing of Lathe Tailstock

CO3

COURSE OUTCOMES:
Upon completion of the course, the students will be able to:

Bloom's Taxonomy Mapped

CO1 Describe how CAD technology can be leveraged in the design process and the basic and advanced features available with CAD software

CO2 Design a part or assembly of parts using Computer-Aided Design software.

Create

Create

Design a detailed view of part or assembly of parts using Computer-Aided Design software.

COU	RSE A	RTICU	JLATI	ON M	ATRI	<u>X</u>									
CO/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	1	2	3	0	1	0	0	0	2	0	2	2	1
CO2	1	1	1	1	3	0	1	0	0	0	0	0	2	2	1
CO3	2	2	2	1	2	0	1	0	0	0	1	0	2	2	1
Avg	1.6	1.6	1.33	1.33	2.6	0	1	0	0	0	1	0	2	2	1
	3 / 2 / 1 – indicates strength of correlation (3 – High, 2 – Medium, 1 – Low)														

22CE308	STRENGTH OF MATERIALS AND FLUID ME LABORATORY	STRENGTH OF MATERIALS AND FLUID MECHANICS LABORATORY SEMESTER III									
PRE-REQU	JISITE:	Category	ES	Credit		1.5					
Strength of I	Materials	Hours/Week	L	Т	P	TH					
Fluid Mecha	nics	Hours/ week	0	0	3	3					

Course Objectives:

- 1. To analyze structural members subjected to tension, compression and bending using the fundamental concepts of stress, strain and elastic behavior of materials.
- 2. To Study about Pump and Turbine.

STRENGTH OF MATERIAL LABORATORY EXERCISES

- 1. Double shear test on mild steel rod
- 2. Tension Test on mild steel rod
- 3. Test of springs (Open coil and closed coil)
- 4. Impact test on a metallic specimen (Izod and Charpy Impact test)
- 5. Hardness tests on metallic specimen (Brinell / Rockwell)
- 6. Bending deflection test on beams

FLUID MECHANICS LABORATORY EXERCISES

- 1. Determination of Friction factor of pipes
- 2. Performance characteristics of Kaplan Turbine
- 3. Determination of the coefficient of discharge of orifice meter
- 4. Determination of the coefficient of discharge of venturi meter
- 5. Conducting experiments and drawing the characteristics curves of centrifugal pump
- 6. Conducting experiments and drawing the characteristics curves of reciprocating pump
- 7. Conducting experiments and drawing the characteristics curves of gear pump

Total = 30 Periods

	SE OUTCOMES: mpletion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Learn the various techniques of testing methods for materials	Understand
CO2	Perform test and identify the different characteristics of materials.	Evaluate
CO3	Perform experiments on hydraulic machines to draw the performance characteristics.	Evaluate

COUR	RSE AI	RTICU	LATIO	ON MA	ATRIX										
CO/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	1	1	0	0	0	0	1	0	0	0	1	1	3
CO2	1	2	1	1	0	0	0	0	1	0	0	0	2	1	2
CO3	1	2	2	2	0	0	0	0	1	0	0	0	2	1	3
Avg	1	2	1.33	1.33	0	0	0	0	1	0	0	0	1.66	1	2.6
	3 / 2 / 1 – indicates strength of correlation (3 – High, 2 – Medium, 1 – Low)														

22ME401	KINEMATICS OF MACHINERY		S	SEMES	TER I	V
PRE-REQ	UISITE:	Category	PC	Cro	edit	4
1. Engineerii	ng Graphics.	TT /55/ 1	L	Т	P	TH
2.Engineerin	g Mechanics	Hours/Week	3	1	0	4
Course Ob	jectives:					•
1. To un	derstand the basic components and layout of linkages in the assem	bly of a system/ ma	chine.			
	derstand the principles in analyzing the assembly with respect to in a link of a mechanism.	the displacement, v	elocity,	and acc	eleration	at any
3. To un	derstand basics of cam profile and its displacement.					
4. To un	derstand the basic concepts of toothed gearing and kinematics of g	gear trains.				
5. Illustr	rate the effects of friction drives in transmission system.					
UNIT I	BASICS OF MECHANISMS		9	3	0	12
	on mechanisms- Quick return mechanism, straight-line generators-	Universal Joint- Ro	1		1	12
UNIT II Displacement velocity and mechanism,	KINEMATIC ANALYSIS at, velocity and acceleration analysis of simple mechanisms - graph acceleration analysis using loop closure equations- kinemat dynamics, Coincident points- Coriolis component of acceleration anthesis for motion and path generation.	nical velocity analysic analysis of sin	9 sis using	3 instanta	0 nneous co	r-cranl
UNIT II Displacement velocity and mechanism,	KINEMATIC ANALYSIS at, velocity and acceleration analysis of simple mechanisms - graph acceleration analysis using loop closure equations- kinemat dynamics, Coincident points- Coriolis component of acceleration	nical velocity analysic analysis of sin	9 sis using	3 instanta	0 nneous co	entres r-cranl
UNIT II Displacement velocity and mechanism, graphical syn UNIT III Classification harmonic an	KINEMATIC ANALYSIS at, velocity and acceleration analysis of simple mechanisms - graph acceleration analysis using loop closure equations- kinemat dynamics, Coincident points- Coriolis component of acceleration anthesis for motion and path generation.	nical velocity analysic analysis of sin . Introduction to lin ment diagrams Unificontour cams circu	9 sis using ple menkage sy 9 form velocation and	instanta chanism nthesis - 3 ocity, patangent	onneous conservations of three F	entres r-crank Position 12 simple pressure
UNIT II Displacement velocity and mechanism, graphical syn UNIT III Classification harmonic an	KINEMATIC ANALYSIS at, velocity and acceleration analysis of simple mechanisms - graph acceleration analysis using loop closure equations- kinemat dynamics, Coincident points- Coriolis component of acceleration anthesis for motion and path generation. KINEMATICS OF CAM n of cams and followers- Terminology and definitions- Displacent d cycloidal motions- derivatives of follower motions- specified	nical velocity analysic analysis of sin . Introduction to lin ment diagrams Unificontour cams circu	9 sis using ple menkage sy 9 form velocation and	instanta chanism nthesis - 3 ocity, patangent	onneous conservations of three F	entres r-crank Position 12 simple pressure
UNIT II Displacement velocity and mechanism, graphical syn UNIT III Classification harmonic an angle and un UNIT IV Involute and	KINEMATIC ANALYSIS at, velocity and acceleration analysis of simple mechanisms - graph acceleration analysis using loop closure equations- kinemat dynamics, Coincident points- Coriolis component of acceleration anthesis for motion and path generation. KINEMATICS OF CAM In of cams and followers- Terminology and definitions- Displacent d cycloidal motions- derivatives of follower motions- specified dercutting, sizing of cams, graphical and analytical disc cam profile	nical velocity analysic analysis of sin . Introduction to line ment diagrams Unificontour cams circule synthesis for rolle aring and conjugate	sis using apple membrage sy 9 Form velocitar and flater and flater and flater action,	instanta chanism nthesis a spur ge.	onneous conservations of the property of the p	entres er-crank Position 12 simple oressures.
UNIT II Displacement velocity and mechanism, graphical syn UNIT III Classification harmonic an angle and un UNIT IV Involute and	KINEMATIC ANALYSIS at, velocity and acceleration analysis of simple mechanisms - graph acceleration analysis using loop closure equations- kinemat dynamics, Coincident points- Coriolis component of acceleration anthesis for motion and path generation. KINEMATICS OF CAM In of cams and followers- Terminology and definitions- Displacent d cycloidal motions- derivatives of follower motions- specified dercutting, sizing of cams, graphical and analytical disc cam profil GEARS AND GEAR TRAINS It cycloidal gear profiles, gear parameters, fundamental law of gear	nical velocity analysic analysis of sin . Introduction to line ment diagrams Unificontour cams circule synthesis for rolle aring and conjugate clic and regular gear	sis using apple membrage sy 9 Form velocitar and flater and flater and flater action,	instanta chanism nthesis a spur ge.	onneous conservations of the property of the p	entres r-cranl Position 12 simple oressures.
UNIT II Displacement velocity and mechanism, graphical syn UNIT III Classification harmonic an angle and un UNIT IV Involute and and interfere UNIT V Surface contributed and contributed and interfere	KINEMATIC ANALYSIS at, velocity and acceleration analysis of simple mechanisms - graph acceleration analysis using loop closure equations- kinemat dynamics, Coincident points- Coriolis component of acceleration anthesis for motion and path generation. KINEMATICS OF CAM In of cams and followers- Terminology and definitions- Displacent d cycloidal motions- derivatives of follower motions- specified dercutting, sizing of cams, graphical and analytical disc cam profil GEARS AND GEAR TRAINS It cycloidal gear profiles, gear parameters, fundamental law of gean nee/undercutting- helical, bevel, worm, rack & pinion gears, epicy	nical velocity analysic analysis of sin . Introduction to line ment diagrams Unificantour cams circule synthesis for rolle aring and conjugate clic and regular gears	sis using apple membrage sy sorm velocitar and flater and flater action, ar train k	instanta chanism nthesis a chanism on thesis a chanism of the chan	onneous conservations of the servations of the s	entres r-cranl Position 12 simple pressures. 12 ct ratio

Text B	Books:
1.	Rattan S.S, "Theory of Machines", Tata McGraw Hill Publishing Company Ltd., New Delhi, 1998.
2.	Ghosh, A and Mallick, A.K, "Theory of Mechanisms and Machines", East-West Pvt. Ltd., New Delhi, 1988.
Dofore	Doolege

· ·	
Refere	ence Books:
1.	Thomas Bevan, "Theory of Machines", CBS Publishers and Distributors, 1984.
2.	Rao J.S and Dukkipati R.V, "Mechanism and Machine Theory", Wiley- Eastern Ltd., New Delhi, 1992.
3.	Erdman AG and Sandor G N, "Mechanism Design, Analysis and Synthesis", Vol.I, PHI Inc., 1997.
4.	Ambekar A.G, "Mechanism and Machine Theory" Prentice Hall of India, New Delhi, 2007.
5.	John Hannah and Stephens R C, "Mechanisms of Machines", Viva Low Price Student Edition, New Delhi, 1999.

E-Refe	E-References:							
1.	https://archive.nptel.ac.in/courses/112/104/112104121/							
2.	https://nptel.ac.in/courses/112106270							
3.	3. http://velhightech.com/Documents/ME8492 Kinematics of Machinery.pdf							

	E OUTCOMES: mpletion of the course, the students will be able to:	Bloom's Taxonomy Mapped					
CO1	Demonstrate and understand the concepts of various mechanisms and pairs.						
CO2	Analyze the velocity and acceleration of simple mechanisms.						
СОЗ	Construct the cam profile for various motion.	Create					
CO4	Solve problems on gears and gear trains.	Evaluate					
CO5	Evaluate the friction in transmission system	Evaluate					

COUF	RSE AI	RTICU	LATIO	ON MA	ATRIX										
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	1	0	0	0	0	0	0	0	0	3	1	0
CO2	3	2	2	1	0	0	0	0	0	0	0	0	3	1	0
CO3	3	2	2	1	0	0	0	0	0	0	0	0	3	1	0
CO4	3	2	2	1	0	0	0	0	0	0	0	0	3	1	0
CO5	3	2	2	1	0	0	0	0	0	0	0	0	3	1	0
Avg	3	2	2	1	0	0	0	0	0	0	0	0	3	1	0
		•	3/2	/ 1 – inc	dicates	strengtl	n of cor	relation	1 (3 – H	igh, 2 – I	Medium,	1 – Low)		

		THERMAL ENGINEERING								
22M	E402	THERMAL ENGINEERING (Use of standard thermodynamic tables, Mollier diagram, Psy and Refrigerant property tables are permitted in the exception of the exceptio		S	SEMES	TER I	V			
PRE	-REQU		Category	PC	Cro	edit	4			
				L	Т	P	TH			
			Hours/Week	3	1	0	4			
Cour	se Obje	ectives:				•	•			
1.	1. To teach the construction and working of IC engine and basics on gas power cycles.									
2.	To acqu	naint the concepts of nozzle, turbine and draw velocity triangle for	or a turbine, calcula	te work	done and	l efficie	ncy.			
3.		erstand the construction and working of all types compressor cating compressor.	and calculate the	work do	ne and	efficiend	cy of a			
4.	To prov	ride knowledge concept of psychrometry and its processes.								
5.	To acqu	naint knowledge of refrigeration cycles and calculation of COP a	nd RE							
UN	IT I	INTERNAL COMBUSTION ENGINES AND GA CYCLES	AS POWER	9	3	0	12			
two s	troke and	of IC engine, IC engine components and functions. Valve timing four stroke engines, Actual and theoretical P-V diagram of two Dual, Brayton cycles, Calculation of mean effective pressure and	and four stroke en	gines, Pe	_	_				
UN	IT II	STEAM NOZZLES AND TURBINES		9	3	0	12			
	lse and F	through nozzles, shapes of nozzles, effect of friction, critical Reaction Turbines, Compounding of Impulse Turbines. Velocity					_			
UNI	IT III	AIR COMPRESSOR		9	3	0	12			
Isothe	ermal eff	and comparison, working principle, work of compression - wiciency and Isentropic efficiency. Multistage air compressor wit pressors with reciprocating air compressors.					-			
UN	IT IV	PSYCHROMETRY		9	3	0	12			
Psych		properties – Property calculations using Psychrometric chart chart – adiabatic saturation, sensible heating and cooling, hummixing.	=	-	_		_			
UN	IT V	REFRIGERATION SYSTEMS		9	3	0	12			
_	_	ression Refrigeration cycle – Effect of suction and delivery pr Working principle of vapour absorption system. Comparison betw	_							
			То	tal (45I	L+ 15T)	$= \overline{60 \text{ P}}$	eriods			
Text	Books:									
1	D : _ 4 1	D. V. "Thomas I. Engineering" C. Chand Dublishous 2000								

Tex	tt Books:						
1.	Rajput, R.K, "Thermal Engineering", S. Chand Publishers, 2000.						
2.	Rudramoorthy, R, "Thermal Engineering", Tata McGraw Hill, New Delhi, 2003.						
3.	Kothandaraman, C.P., Domkundwar,S. and Domkundwar, A.V, "A course in Thermal Engineering", DhanpatRai and Sons, 5th Edition, 2002.						
4.	Sarkar B.K, "Thermal Engineering", Tata McGraw Hill, 1998						
Ref	Reference Books:						
1.	Holman. J.P., "Thermodynamics", McGraw Hill, 1985.						

Arora.C.P, "Refrigeration and Air Conditioning", TMH, 1994.

2.

	E OUTCOMES: mpletion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Analyze the performance parameters in IC engines and air standard cycles.	Analyze
CO2	Analyze the performance of steam nozzle and turbines and understand the concepts of compounding.	Analyze
СОЗ	Evaluate the performance parameters of an air compressor.	Evaluate
CO4	Apply the principles of Psychrometry for air-conditioning processes.	Apply
CO5	Analyze the vapour compression refrigeration cycle and evaluate COP and refrigerating effect.	Analyze

COUL	RSE A	RTICU	LATI	ON MA	ATRIX	<u>.</u>									
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1	0	0	0	0	0	0	0	0	0	0	3	1	1
CO2	3	3	2	3	0	0	0	0	0	0	0	0	3	2	1
CO3	3	2	3	1	0	2	0	0	0	0	0	0	3	2	1
CO4	3	2	2	2	0	0	0	0	0	0	0	0	3	2	1
CO5	3	0	0	0	0	1	0	0	0	0	0	0	3	3	1
Avg	3	1.6	1.4	1.2	0	0.6	0	0	0	0	0	0	3	2	1
			3/2	/ 1 – in	dicates	strengt	h of cor	relation	1 (3 – H	igh, 2 – I	Medium,	1 – Low)		

PRE-			OLS					
	REQUI	SITE:	Category	PC	Credit		3	
Introd	luction to	Materials, force analysis	II/337	L	Т	P	TH	
Heat tr	reatment	processes and Engineering physics.	Hours/Week	3	0	0	3	
Cours	se Objec	ctives:		•			ı	
1.	To pro	vide knowledge on basic mechanics of metal cutting.						
2.	Summa	arize the constructional and operational features of machine tool	ls for manufacturing	g various	compo	nents.		
3.	Explain	n the machine tools for hole making grinding and broaching.						
4.	To ana	lyze various unconventional machining processes and their need	ds in industries					
5.	Descri	be the necessity of additive manufacturing techniques and ready	to interpret with in	dustries	require	ments		
UNIT I THEORY OF METAL CUTTING					0	0	9	
UN Capsta automa	ats – sha	AUTOMATS, SHAPING AND PLANING MA arret lathes – construction - indexing mechanism - operations aping and planning machines – types – construction - mechanism	s - working princip	-	_		-	
operati UNI	T III	DRILLING, BROACHING AND GRINDING M	IACHINES	9	0	0	9	
		l reconditioning of grinding wheels.						
UNI	T IV	MILLING AND GEAR GENERATING MAG	CHINES	9	0	0	9	
Milling – gear	generation	MILLING AND GEAR GENERATING MAC fications – types - cutter nomenclature – types of cutters – mill on - gear shaping and gear hobbing – specifications - cutters – conerators – gear finishing methods	ing processes – ind	exing –	gear for	ming in	millin	
Milling – gear - bevel	g – speci generatio	fications – types - cutter nomenclature – types of cutters – mill on - gear shaping and gear hobbing – specifications - cutters –co	ing processes – ind	exing –	gear for	ming in	millin	
Milling – gear - bevel UN Uncon Machin Additi	g – speci generational gear ger IT V Eventional Ining (AJ) ve manul	fications – types - cutter nomenclature – types of cutters – mill on - gear shaping and gear hobbing – specifications - cutters – concrators – gear finishing methods	ing processes – ind pated tools & insert , process capabilitie Iachining (EDM), I	exing – s- cutting 9 es and to Laser Be Developr	gear for g spur a 0 cooling fram Machanent-Machanert-M	or Abraschining (aterials f	millin gear gear general gener	
Milling – gear – bevel UN Uncon Machin Additiv Stereo sinterin	g – speci generational gear ger IT V Eventional Ining (AJ) ve manul	fications – types - cutter nomenclature – types of cutters – mill on - gear shaping and gear hobbing – specifications - cutters – concrators – gear finishing methods ADVANCES IN MACHINING I machining processes - principles, process parameters, MRR, M), Electrochemical Machining (ECM). Electric Discharge Machining processes - Fundamentals of Additive Manufacturing phy apparatus - STL file - Fused Deposition Modeling- Legisland (ECM).	ing processes – ind pated tools & insert , process capabilitie Iachining (EDM), I	exing – s- cutting 9 es and to Laser Be Developr	gear for g spur a 0 cooling fram Machanent-Machanert-M	o for Abraschining (aterials f	millin gear gear general gener	
Milling – gear – bevel UN Uncon Machin Additiv Stereo sinterin	g – speci generational gear ger IT V Eventional Ining (AJ) Ve manulithogra Ing- 3D P	fications – types - cutter nomenclature – types of cutters – mill on - gear shaping and gear hobbing – specifications - cutters – concrators – gear finishing methods ADVANCES IN MACHINING I machining processes - principles, process parameters, MRR, M), Electrochemical Machining (ECM). Electric Discharge Machining processes - Fundamentals of Additive Manufacturing phy apparatus - STL file - Fused Deposition Modeling- Legisland (ECM).	ing processes – indoated tools & insert process capabilities fachining (EDM), Ing (AM)-Product I aminated Object M	exing – s- cutting 9 es and to Laser Be Developr Manufact	gear for g spur a 0 cooling f am Machanent-Machaning-	or Abraschining (aterials f Selective	millin gear gear gear gear gear gear gear gear	
Milling – gear – bevel UN Uncon Machin Additiv Stereo sinterin Text I 1. F	g – speci generation I gear ger IT V Eventional Ining (AJ) Ive manu Iithogra Ing- 3D P Books: Kalpakjia	fications – types - cutter nomenclature – types of cutters – mill on - gear shaping and gear hobbing – specifications - cutters – concretors – gear finishing methods ADVANCES IN MACHINING I machining processes - principles, process parameters, MRR, M), Electrochemical Machining (ECM). Electric Discharge M facturing processes - Fundamentals of Additive Manufacturing phy apparatus - STL file - Fused Deposition Modeling- Larinter – Tooling.	ing processes – indoated tools & insert process capabilities Iachining (EDM), Ing (AM)-Product I Iaminated Object M	exing — s- cutting 9 es and to Laser Be Developr Manufact	gear for g spur a 0 cooling f sam Machanent-Machaning- Tota	o or Abras chining (aterials f Selective) 1 = 45 P	millimal gear 9 sive Jo LBM for Al	
Milling gear bevel UN Uncon Machin Additiv Stereo sinterin 1. I	g – speci generational l gear ger IT V Eventional ning (AJ) ve manu lithogra ng- 3D P Books: Kalpakjia	fications – types - cutter nomenclature – types of cutters – million - gear shaping and gear hobbing – specifications - cutters – concrators – gear finishing methods ADVANCES IN MACHINING I machining processes - principles, process parameters, MRR, M), Electrochemical Machining (ECM). Electric Discharge M facturing processes - Fundamentals of Additive Manufacturing phy apparatus - STL file - Fused Deposition Modeling- Limiter – Tooling. In and Schmid, "Manufacturing processes for Engineering Mate "Manufacturing Technology - Metal Cutting and Machine To	ing processes – indoated tools & insert process capabilities Iachining (EDM), Ing (AM)-Product I Iaminated Object M	exing — s- cutting 9 es and to Laser Be Developr Manufact	gear for g spur a 0 cooling f sam Machanent-Machaning- Tota	o or Abras chining (aterials f Selective) 1 = 45 P	millir gea	
Milling gear bevel UN Uncon Machin Additiv Stereo sinterin 1. F 2. F Referen	g – speci generation I gear ger IT V eventional ning (AJ) ve manulithograng- 3D P. Books: Kalpakjia Rao. P.N 2013	fications – types - cutter nomenclature – types of cutters – million - gear shaping and gear hobbing – specifications - cutters – concrators – gear finishing methods ADVANCES IN MACHINING I machining processes - principles, process parameters, MRR, M), Electrochemical Machining (ECM). Electric Discharge M facturing processes - Fundamentals of Additive Manufacturing phy apparatus - STL file - Fused Deposition Modeling- Limiter – Tooling. In and Schmid, "Manufacturing processes for Engineering Mate "Manufacturing Technology - Metal Cutting and Machine To	ing processes – indocated tools & insert patents of the process capabilities are supported by the process capabili	exing — s- cutting 9 es and to Laser Be Developr Manufact	gear for g spur a 0 cooling f sam Machanent-Machaning- Tota	o or Abras chining (aterials f Selective) 1 = 45 P	millir gea	

METAL CUTTING AND MACHINE TOOLS

SEMESTER IV

22ME403

Roy. A. Linberg, "Process and Materials of Manufacture", PHI, 2000.

3.

- 4. Mikell P. Groover, Fundamentals of Modern Manufacturing: Materials, Processes, and Systems.
- 5. Jain. R.K., and S.C. Gupta, "Production Technology", 16th Edition, Khanna Publishers, 2001

	RSE OUTCOMES: ompletion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Explain the mechanism of material removal processes.	Understand
CO2	Describe the constructional and operational features of special-purpose lathes, shaper and planner.	Understand
СОЗ	Gain working exposure to hole-making operations, grinding and broaching machines utilized in industries.	Evaluate
CO4	Study of special-purpose machine tools, operations and its uses in industries.	Understand
CO5	Summarize unconventional machining processes and additive manufacturing processes and their applications.	Remember

COUI	RSE Al	RTICU	LATIO	ON MA	ATRIX	· •									
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	0	1	0	0	0	0	0	1	1	0	2	0	1
CO2	0	1	1	1	0	0	0	0	0	1	1	1	1	2	3
CO3	0	1	1	0	0	0	0	0	0	1	1	1	1	2	2
CO4	0	1	1	0	0	0	0	0	0	1	1	1	1	2	2
CO5	0	1	0	0	2	0	2	0	2	1	1	1	1	2	2
Avg	0.4	1	0.6	0.4	0.1	0	0.1	0	0.1	1	1	0.8	1.2	1.6	2
			3/2	/ 1 – inc	dicates	strengt	h of cor	relation	1 (3 – H	igh, 2 – I	Medium,	1 – Low)		

22ME404	HYDRAULICS AND PNEUMATICS	S	S	SEMES	TER I	V
PRE-REQU	SITE:	Category	PC	Cre	edit	3
			L	Т	P	TF
		Hours/Week	3	0	0	3
Course Obje	ctives:			l		
1. To enab	le the students, understand the basics of hydraulics and pneumati	ics				
2. Applyin	g the working principles of hydraulic actuators and control comp	oonents.				
3. Designi	ng and develop hydraulic circuits and systems.					
4. Applyii	g the working principles of pneumatic power system and its com-	nponents.				
5. Solving	problems and troubles in fluid power systems.					
UNIT I	FLUID POWER PRINICIPLES AND HYDRAUI	LIC PUMPS	9	0	0	9
Disadvantages	ydraulic power; Pumping Theory – Pump Classification – Performance, Selection criteria of pumps – Fixed and Variable of	displacement pump	s – Prob	lems.	I	
			_	_	i, Auva	
Disadvantages UNIT II	Performance, Selection criteria of pumps – Fixed and Variable of HYDRAULIC ACTUATORS AND CONTROL CO	displacement pump	9 9	lems.	0	9
UNIT II Hydraulic Act notors - Contr	Performance, Selection criteria of pumps – Fixed and Variable of HYDRAULIC ACTUATORS AND CONTROL COntators: Cylinders – Types and construction, Application, Hydrol Components: Direction Control, Flow control and pressure control and pressur	OMPONENTS raulic cushioning ontrol valves – Typ	9 - Rotary	lems. 0 actuate struction	ors - Hy	9 draul
UNIT II Hydraulic Act notors - Contr	Performance, Selection criteria of pumps – Fixed and Variable of HYDRAULIC ACTUATORS AND CONTROL COntators: Cylinders – Types and construction, Application, Hydraulic Actuators: Cylinders – Types and Construction, Application, Cylinders – Cylinde	OMPONENTS raulic cushioning ontrol valves – Typ	9 - Rotary	lems. 0 actuate struction	ors - Hy	9 draul
UNIT II Hydraulic Act motors - Conti - Accessories;	Performance, Selection criteria of pumps – Fixed and Variable of HYDRAULIC ACTUATORS AND CONTROL COntators: Cylinders – Types and construction, Application, Hydrol Components: Direction Control, Flow control and pressure control and pressur	OMPONENTS raulic cushioning control valves — Typera - Applications —	9 - Rotary	lems. 0 actuate struction	ors - Hy	9 drauli
UNIT II Hydraulic Act motors - Conti - Accessories; Problems. UNIT III	Performance, Selection criteria of pumps – Fixed and Variable of HYDRAULIC ACTUATORS AND CONTROL COntators: Cylinders – Types and construction, Application, Hydrol Components: Direction Control, Flow control and pressure concentration, Pressure Switches – Filters – types and selection HYDRAULIC CIRCUITS AND SYSTEM	DMPONENTS raulic cushioning control valves – Typ - Applications –	9 - Rotary pes, Cons Fluid Po	0 actuate struction ower AN	oprs - Hy and Op NSI Syn	9 rdraul peration abols
UNIT II Hydraulic Act motors - Contr - Accessories; Problems. UNIT III Accumulators, Air-over oil, S	Performance, Selection criteria of pumps – Fixed and Variable of HYDRAULIC ACTUATORS AND CONTROL COntators: Cylinders – Types and construction, Application, Hydrol Components: Direction Control, Flow control and pressure controls, Pressure Switches – Filters – types and selection HYDRAULIC CIRCUITS AND SYSTEM Intensifiers, Industrial hydraulic circuits – Regenerative, Pumpe equence, Reciprocation, Synchronization, Fail - Safe, Speed Controls	DMPONENTS raulic cushioning ontrol valves – Type - Applications – MS Unloading, Doub Control, Deceleration	9 - Rotary pes, Cons Fluid Po 9 - Pum on circuit	o actuate struction ower AN	ors - Hy and Op NSI Syn o sure Integral of hy	gdraul eration bols gensifie
UNIT II Hydraulic Act motors - Contr - Accessories; Problems. UNIT III Accumulators, Air-over oil, S systems, Hydr	Performance, Selection criteria of pumps – Fixed and Variable of HYDRAULIC ACTUATORS AND CONTROL COntators: Cylinders – Types and construction, Application, Hydrol Components: Direction Control, Flow control and pressure concentrations, Pressure Switches – Filters – types and selection HYDRAULIC CIRCUITS AND SYSTEM Intensifiers, Industrial hydraulic circuits – Regenerative, Pump equence, Reciprocation, Synchronization, Fail - Safe, Speed Constatic transmission, Electro hydraulic circuits – Servo and Proceedings of the Procedure	DMPONENTS raulic cushioning ontrol valves – Type - Applications – MS Unloading, Doub Control, Deceleration	9 - Rotary pes, Cons Fluid Po 9 - Pum on circuit	o actuate struction ower AN	ors - Hy and Op NSI Syn o sure Integral of hy	gdraul eration bols gensifie
UNIT II Hydraulic Act motors - Contr - Accessories; Problems. UNIT III Accumulators, Air-over oil, S systems, Hydraulic server	Performance, Selection criteria of pumps – Fixed and Variable of HYDRAULIC ACTUATORS AND CONTROL COntators: Cylinders – Types and construction, Application, Hydrol Components: Direction Control, Flow control and pressure concentration, Pressure Switches – Filters – types and selection HYDRAULIC CIRCUITS AND SYSTEM Intensifiers, Industrial hydraulic circuits – Regenerative, Pump equence, Reciprocation, Synchronization, Fail - Safe, Speed Constatic transmission, Electro hydraulic circuits – Servo and Posystems.	DMPONENTS raulic cushioning ontrol valves – Type - Applications – MS Unloading, Doub Control, Deceleration of the proportional valves	9 - Rotary pes, Cons Fluid Po 9 - Pum on circuit 5 - Appl	o actuate struction ower AN o p. Press its, Sizir ications	oprs - Hy and Op NSI Syn o ure Intense of hy - Mech	9 draul peration bols 9 pensifie draul panica
UNIT II Hydraulic Act motors - Contr - Accessories; Problems. UNIT III Accumulators, Air-over oil, S systems, Hydr hydraulic serve	Performance, Selection criteria of pumps – Fixed and Variable of HYDRAULIC ACTUATORS AND CONTROL COntators: Cylinders – Types and construction, Application, Hydrol Components: Direction Control, Flow control and pressure concentrations, Pressure Switches – Filters – types and selection HYDRAULIC CIRCUITS AND SYSTEM Intensifiers, Industrial hydraulic circuits – Regenerative, Pump equence, Reciprocation, Synchronization, Fail - Safe, Speed Constatic transmission, Electro hydraulic circuits – Servo and Posystems. PNEUMATIC AND ELECTRO PNEUMATIC 1	DMPONENTS raulic cushioning ontrol valves – Type - Applications – MS Unloading, Doub Control, Deceleration of the proportional valves SYSTEMS	9 - Rotary pes, Cons Fluid Po	o actuate struction ower AM o pp, Press its, Sizir ications	opris - Hy and Opris Syn opris - Hy and Opris Syn opris - Mechanis Syn opris - Mechani Syn opris - Mechanis Syn opris - Mechanis Syn opris - Mechani	9 rdraul peration policy gensifies rdraul panica
UNIT II Hydraulic Act motors - Conti - Accessories; Problems. UNIT III Accumulators, Air-over oil, S systems, Hydraulic serve UNIT IV Properties of a	Performance, Selection criteria of pumps – Fixed and Variable of HYDRAULIC ACTUATORS AND CONTROL COntators: Cylinders – Types and construction, Application, Hydrol Components: Direction Control, Flow control and pressure concentrations, Pressure Switches – Filters – types and selection HYDRAULIC CIRCUITS AND SYSTEM Intensifiers, Industrial hydraulic circuits – Regenerative, Pump equence, Reciprocation, Synchronization, Fail - Safe, Speed Constatic transmission, Electro hydraulic circuits – Servo and Posystems. PNEUMATIC AND ELECTRO PNEUMATIC in – Air preparation and distribution – Filters, Regulator, Lubrical Control of the Position of the Posit	DMPONENTS raulic cushioning control valves — Typ - Applications — MS D Unloading, Doub Control, Deceleration Proportional valves SYSTEMS icator, Muffler, Air	9 - Rotary pes, Cons Fluid Po 1 - Pum pon circuit 1 - Appl 9 - Tentrol	o actuato struction ower AN o np, Press its, Sizir ications over the ower actually of the ower actually of the ower actually of the ower actually ower actually of the ower actually of the ower actually ower actually of the ower actually ower actually ower actually of the ower actually of the ower actually ower actually ower actually of the ower actually ower actually of the ower actually of the ower actually ower actually ower actually ower actually of the ower actually ower actually ower actually ower actually ower actually ower actually of the ower actually of the ower actually of the ower actually ower actually ower actually ower actually of the ower actually ower actually ower actually ower actually of the ower actually ower actually ower actually of the ower actually of the ower actually ower actually of the ower actually ower actually of the ower actually ower actually of the ower actually ower actually of the ower actually of the ower actually of the owe	opris - Hy and Opris Syn opris - Hy and Opris Syn opris - Mechanis of hy and Opris	9 draul eratid eratid hbols 9 nsifie draul nanica
UNIT II Hydraulic Act motors - Contr - Accessories; Problems. UNIT III Accumulators, Air-over oil, S systems, Hydr hydraulic serve UNIT IV Properties of a valves, Pneum method — Inter	Performance, Selection criteria of pumps – Fixed and Variable of HYDRAULIC ACTUATORS AND CONTROL COntators: Cylinders – Types and construction, Application, Hydrol Components: Direction Control, Flow control and pressure conference of Reservoirs, Pressure Switches – Filters – types and selection HYDRAULIC CIRCUITS AND SYSTEM Intensifiers, Industrial hydraulic circuits – Regenerative, Pump equence, Reciprocation, Synchronization, Fail - Safe, Speed Constatic transmission, Electro hydraulic circuits – Servo and Posystems. PNEUMATIC AND ELECTRO PNEUMATIC for – Air preparation and distribution – Filters, Regulator, Lubricatic actuators, Design of Pneumatic circuit – classification - singration of fringe circuits, Electro pneumatic system – Elementers	DMPONENTS raulic cushioning control valves – Typ - Applications – MS O Unloading, Doub Control, Deceleration Proportional valves SYSTEMS icator, Muffler, Aingle cylinder and m	9 - Rotary pes, Cons Fluid Po 1 - Pum pon circuit 1 - Appl 9 - r control nulti cyli	o actuate of actuation ower AN o actuation ower AN o ap, Press ats, Sizir ications ower actually of the actual of the actual of the actual ower actual	opris - Hy and Op NSI Syn o Gure Intended of hy - Mech Quick of cuits - C	9 drauli eratica hols 9 ensificadrauli nanica 9 exhau
UNIT II Hydraulic Act motors - Contr - Accessories; Problems. UNIT III Accumulators, Air-over oil, S systems, Hydr hydraulic serve UNIT IV Properties of a valves, Pneum method — Inter	Performance, Selection criteria of pumps – Fixed and Variable of HYDRAULIC ACTUATORS AND CONTROL COntators: Cylinders – Types and construction, Application, Hydrol Components: Direction Control, Flow control and pressure concentrations, Pressure Switches – Filters – types and selection HYDRAULIC CIRCUITS AND SYSTEM Intensifiers, Industrial hydraulic circuits – Regenerative, Pump equence, Reciprocation, Synchronization, Fail - Safe, Speed Constatic transmission, Electro hydraulic circuits – Servo and Posystems. PNEUMATIC AND ELECTRO PNEUMATIC in – Air preparation and distribution – Filters, Regulator, Lubricatic actuators, Design of Pneumatic circuit – classification - sin	DMPONENTS raulic cushioning control valves – Typ - Applications – MS O Unloading, Doub Control, Deceleration Proportional valves SYSTEMS icator, Muffler, Aingle cylinder and m	9 - Rotary pes, Cons Fluid Po 1 - Pum pon circuit 1 - Appl 9 - r control nulti cyli	o actuate of actuation ower AN o actuation ower AN o ap, Press ats, Sizir ications ower actually of the actual of the actual of the actual ower actual	opris - Hy and Op NSI Syn o Gure Intended of hy - Mech Quick of cuits - C	9 drauli eratica hols 9 ensificadrauli nanica 9 exhau
UNIT II Hydraulic Act motors - Contr - Accessories; Problems. UNIT III Accumulators, Air-over oil, S systems, Hydr hydraulic serve UNIT IV Properties of a valves, Pneum method — Inter	Performance, Selection criteria of pumps – Fixed and Variable of HYDRAULIC ACTUATORS AND CONTROL COntators: Cylinders – Types and construction, Application, Hydrol Components: Direction Control, Flow control and pressure conference of Reservoirs, Pressure Switches – Filters – types and selection HYDRAULIC CIRCUITS AND SYSTEM Intensifiers, Industrial hydraulic circuits – Regenerative, Pump equence, Reciprocation, Synchronization, Fail - Safe, Speed Constatic transmission, Electro hydraulic circuits – Servo and Prosystems. PNEUMATIC AND ELECTRO PNEUMATIC in – Air preparation and distribution – Filters, Regulator, Lubricatic actuators, Design of Pneumatic circuit – classification - singuration of fringe circuits, Electro pneumatic system – Element fluidics and pneumatic logic circuits. DESIGN OF FLUID POWER CIRCUITS	DMPONENTS raulic cushioning control valves — Typ - Applications — MS D Unloading, Doub Control, Deceleration Proportional valves SYSTEMS icator, Muffler, Ain agle cylinder and mants — Ladder diagrams	9 - Rotary pes, Cons Fluid Po 1 - Pum pon circuit 1 - Appl 9 - r control nulti cyli	o actuate of actuation ower AN o actuation ower AN o ap, Press ats, Sizir ications ower actually of the actual of the actual of the actual ower actual	opris - Hy and Op NSI Syn o Gure Intended of hy - Mech Quick of cuits - C	9 gradraul geration hols gransified draul nanica gransified carried and carried gransified grans
UNIT II Hydraulic Act motors - Contra Accessories; Problems. UNIT III Accumulators, Air-over oil, S systems, Hydra hydraulic serve UNIT IV Properties of a valves, Pneum method — Inter- introduction to UNIT V	Performance, Selection criteria of pumps – Fixed and Variable of HYDRAULIC ACTUATORS AND CONTROL COntators: Cylinders – Types and construction, Application, Hydrol Components: Direction Control, Flow control and pressure conference of Reservoirs, Pressure Switches – Filters – types and selection HYDRAULIC CIRCUITS AND SYSTEM Intensifiers, Industrial hydraulic circuits – Regenerative, Pump equence, Reciprocation, Synchronization, Fail - Safe, Speed Constatic transmission, Electro hydraulic circuits – Servo and Posystems. PNEUMATIC AND ELECTRO PNEUMATIC in – Air preparation and distribution – Filters, Regulator, Lubricatic actuators, Design of Pneumatic circuit – classification - singration of fringe circuits, Electro pneumatic system – Element fluidics and pneumatic logic circuits.	DMPONENTS raulic cushioning pontrol valves — Type — Applications — MS Deformed the control of t	s – Prob 9 Rotary bes, Cons Fluid Po 9 le - Pum on circuit	o actuate struction ower AN o p. Press its, Sizintications over determined of the control of the	oprs - Hy and Op NSI Syn operation operation operation Quick operation	9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9

pneumatics components.

Tex	Text Books:								
1.	Manjumdar S.R, "Oil Hydraulics", Tata McGraw-Hill, December 2002.								
2.	Anthony Esposito, "Fluid Power with Applications", Pearson Education 2013.								

Ref	eference Books:						
1.	Andrew Parr, "Hydraulic and Pneumatics", Jaico Publications House, 2005.						
2.	Bolton W. "Pneumatic and hydraulic system", Butterworth-Heinemann 1997						
3.	Majumdar S.R., "Pneumatic systems – Principles and maintenance", Tata McGraw Hill, 2010						
4.	Shanmugasundaram. K, "Hydraulic and Pneumatic controls", Chand & Co, 2006						
5.	Srinivasan.R. "Hydraulic and Pneumatic Controls", Vijay Nicole Imprints, 2008.						
E-R	References:						
1.	http://www.fluidpowerjournal.com						
2.	http://14.139.160.15/courses/112102011/2						
3.	https://www.nfpa.com/home.htm						

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:						
CO1	Select the components as per the application	Evaluate					
CO2	Apply the working principles of hydraulic actuators and control components.	Apply					
CO3	Design and develop hydraulic circuits and systems.	Create					
CO4	Apply the working principles of pneumatic power system and its components.	Apply					
CO5	Solve problems and troubles in fluid power systems.	Evaluate					

COUR	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	1	0	0	0	0	0	0	0	0	0	1	1	1
CO2	0	2	2	1	0	0	0	0	0	0	0	0	1	1	1
CO3	1	2	3	0	0	1	0	0	0	0	0	0	1	2	1
CO4	1	1	3	2	2	0	0	0	0	0	0	0	2	1	1
CO5	1	1	2	0	0	0	0	0	0	0	0	0	1	1	1
Avg	1	1.4	2.2	0.6	0.4	0.2	0	0	0	0	0	0	1.2	1.2	1
			3/2	/ 1 – inc	dicates s	strengtl	ı of cor	relatior	(3 – H	igh, 2 – I	Medium,	1 – Low	·)		

22CE	409	STRENGTH OF MATERIALS		5	SEMES	STER I	V
PRE-	REQUI	SITE:	Category	ES	Cr	edit	3
Differ	entiation	, Partial Differential Equations		L	T	P	TH
	eering Me	•	Hours/Week	3	0	0	3
Cours	se Objec	etives:			1		
1.		erstand the nature of stresses developed in simple geometries neres for various types of simple loads	such as bars, canti	ilevers, t	beams, s	hafts, cy	linde
2.	To calc	ulate the shear force and bending moment of various beams tra	nsverse loading				
3.	To esti	mate the slope and the deflection of beams and strengths of the	columns				
4.	To eval	luate the axial and hoop stresses in thin and thick shells for the	applied internal and	l externa	l pressui	res.	
5.	To lear	n about the torsion behavior of shafts and coil springs					
UN	IT I	STRESS, STRAIN AND DEFORMATION OF	F SOLIDS	9	0	0	9
Beams suppor	ted and o	TRANSVERSE LOADING ON BEAMS AND ST BEAMS es of transverse loading on beams- shear force and bending no over-hanging beams, cantilevers. Theory of bending of beams, con, point and distributed loads. Shear stress distribution of simple sections.	noment diagrams T	tribution	and net	ıtral axis	s, she
	T III	DEFLECTION OF BEAMS AND COLUM	MNS	9	0	0	9
Momes of slop recipro	nt of iner	tia about an axis and polar moment of inertia, deflection of a beflection in beams, Macaulay's method – Area moment methorems. Columns: End Conditions-Equivalent length of a columns	eam using double i d - Conjugate beam	ntegration	on metho ain energ	od, comp gy – Ma	utatio xwell
UNI	T IV	THIN CYLINDERS, SPHERES AND THICK C	YLINDERS	9	0	0	9
	_	subjected to internal pressure, deform subjected to internal pressure – Lame's theorem.	ation of thick and	thin cy	linders,	deforma	tion i
UN	IT V	TORSION AND SPRINGS		9	0	0	9
		s and deformation in circular and hollow shafts, stepped shafts factor of spring Stresses in helical springs under torsion loads-5					

Text	t Books:						
1.	Rajput, R.K, "Strength of Materials", S.Chand and Co, 3rd Edition, 2003.						
2.	Bansal, R.K., "Strength of Materials", Laxmi Publications (P) Ltd., 2016.						
Refe	Reference Books:						
1.	Strength of Materials, D.S. Bedi, Khanna Publishing House						
2.	Subramanian R., "Strength of Materials", Oxford University Press, Oxford Higher Education Series, 2010.						
3.	Mechanics of Materials, Punmia, Jain and Jain, Laxmi Publications						
4.	Strength of Materials (Mechanics of Solid), R.S. Khurmi, S.Chand Publications						

5. Strength of Materials, Jindal U.C., Asian Books Pvt. Ltd., New Delhi, 2009

E-References:

1. NPTEL Videos/Tutorials

	RSE OUTCOMES: completion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Evaluate the stress, strain and strain energy of simple bars	Evaluate
CO2	Familiarize the load transferring mechanism in beams and stress distribution due to shearing force and bending moment	Understand
СОЗ	Evaluate the slope and the deflection of beams and strengths of the columns	Evaluate
CO4	Analyze and design thin and thick shells for the applied internal and external pressures.	Analyze
CO5	Analyze the torsion behavior of shafts and coil springs	Analyze

COUI	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	1	0	0	0	0	0	0	0	0	0	0	0	0
CO2	2	2	1	1	0	0	0	0	0	0	0	0	1	2	0
CO3	3	2	1	1	0	0	0	0	0	0	0	0	2	2	0
CO4	3	2	2	2	0	0	0	0	0	0	0	0	2	0	1
CO5	2	2	2	2	0	0	0	0	0	0	0	0	2	0	1
Avg	2.4	1.8	1.4	1.2	0	0	0	0	0	0	0	0	1.4	0.8	0.4
	1	1	3/2	/ 1 – in	dicates	strengt	h of cor	relation	1 (3 – H	igh, 2 –]	Medium,	1 – Low	· ')	1	

22MCIN03		DESIGN SPRINTS		SEMESTER IV				
PRE-	REQUI	SITE:	Category	EE	Cr	edit	1	
				L	T	P	TH	
			Hours/Week	0	0	2	2	
Cours	se Objec	tives:	1		I		<u>.I</u>	
1.		p key skill areas essential for a product designer from the positions them with tools & techniques to prototype rapidly.	erspective of design, it	s inheren	t compl	exity and	1	
2.	To enal	ple the participants to visualize the experience for a user.						
3.	To lear	n the roles & responsibilities of a designer in creating and s	haping experiences for	the user				
4.	The par	rticipants shall learn through the lenses of system thinking of	of how existing produc	ts work.				
5.	Learn t	o select & apply various practice tools to aid them in rapid	prototyping					
UN	ITI	DESIGN FUNDAMENTALS		0	0	6	6	
		Visual Design, History and Modernism, Design Thinking	methodology, seven e	elements	of desig	gn, princ	iples o	
		es of good design, designing a product and a service			ı	T		
UN	IT II	SYSTEM THINKING AND REVERSE ENG	GINEERING	0	0	6	6	
-		g for Engineering Problem Solving, Understanding Systemering Methodology, Identify building blocks/Components -	_		_	mplex S	ystems	
UNI	T III	USER INTERFACE & USER EXPER	IENCE	0	0	6	6	
		UI/UX, Human-Computer interface, user-centered Designation Architecture, UI Components, need for UI prototype	•	esearch t	echniqu	es, UX	Design	
UNI	IT IV	MECHANICAL PROTOTYPIN	G	0	0	6	6	
method	ds - Too	yping - Domains in prototyping - Difference between actu ls used in different domains - Introduction - Working Laser Cutting and engraving - RD Works - Additive manufa	with Fusion 360 - 31		-		• •	
UN	IT V	ELECTRONIC & SOFTWARE PROTO	TYPING	0	0	6	6	
	ement an	Lumped Circuits - Electronic Prototyping - Tinker CAD d version control - GitHub - GitHub Actions - GitBash - C						
					Total	= 30 P	eriod	
Text I	Books:							
1.	Thinking	in systems - Donella Meadows, 2015						
-+								

Text	Cext Books:							
1.	Thinking in systems - Donella Meadows, 2015							
2.	Rapid Prototyping And Engineering Applications: A Toolbox For Prototype Development - Frank W.Liou, 2007							
3.	Rapid Prototyping Technology: Selection and application - COOPER K. G, 2001							
Refe	Reference Books:							
1.	https://thesystemsthinker.com/wp-content/uploads/2016/03/Introduction-to Systems-Thinking-IMS013Epk.pdf							
2.	https://formlabs.com/blog/ultimate-guide-to-prototyping-tools-for-hardware-and product-design/							
3.	https://docs.kicad-pcb.org/							
4.	https://www.tinkercad.com/learn/circuits							
5.	https://docs.github.com/en/free-pro- team@latest/actions/guides							

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:							
CO1	Understand the elements and principles of product and service design	Apply						
CO2	Apply system thinking concepts in reverse engineering	Apply						
СОЗ	Apply user research techniques to meet the UX needs of a customer and design a visual prototype	Apply						
CO4	Develop prototyping models using the tools from mechanical prototyping models	Apply						
CO5	Develop prototyping models using the tools from electrical and software prototyping methods	Apply						

COURS	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	0	1	0	0	0	0	0	2	0	0	0	0	0	2
CO2	2	3	0	0	0	0	0	0	2	0	0	0	0	0	2
CO3	3	0	1	0	0	0	0	1	2	0	0	0	0	0	2
CO4	0	0	3	2	3	0	0	0	2	0	0	0	0	0	2
CO5	2	0	2	0	1	0	0	0	2	0	0	0	0	0	2
Avg	2	0.6	1.4	0.4	0.8	0	0	0	2	0	0	0	0	0	2
			3/2/	1 – indi	icates st	rength	of corr	elation	(3 – Hi	gh, 2 – N	Iedium,	1 – Low)		

22CY	MC01	ENVIRONMENTAL SCIENCE		SEMESTER IV								
PRE-	REQUI	SITE:	Category	MC	Cro	0						
			II / XX 1 -	L	T	P	C					
			Hours/Week	2	0	1	3					
Course	Course Objectives:											
1.	To lear	n the concept of non-conventional energy systems.										
2.	To expl	lore the environmental impact assessment and to learn about th	e consequence of di	ifferent ty	ypes of p	ollutant	s.					
3.	To have	e an ancient wisdom drawn from Vedas.										
4.	4. To acquire activity-based knowledge to preserve environment.											
5.	5. To learn about conservation of water and its optimization.											
	•	ENVIRONMENTAL AWARENESS		30	0	0	30					

ENVIRONMENTAL AWARENESS

Various types of traditional power Plant --Advantage and Disadvantage of conventional Power Definition of non-conventional energy sources Plants - Conventional vs. Non-conventional power generation. - types of non-conventional energy sources -India's current energy resources and their long-term viability - India's Energy requirement and management

Solar Energy Basics- Solar Thermal Energy- Solar Photovoltaic Energy- Benefits and Drawbacks -Effects on the environment and safety. Wind turbine power and energy- India's wind energy potential- Wind turbine types. Environmental benefits and impacts of offshore wind energy. Air pollution- Sources, effects, control, air quality standards, air pollution act, air pollution measurement. Water Pollution-Sources and its remedy, Soil Pollution-Sources and its remedy, disposal of solid waste. Greenhouse gases – effect, acid rain. Noise pollution reduction. Aspects of pollution from various power plants.

15 **ENVIRONMENTAL ACTIVITIES** 0 0 15

Group activity on water management - Group discussion on recycle of waste (4R's)- Slogan making contest - Poster making event – Expert lecture on environmental awareness – Imparting knowledge on reduction of electricity usage.

Identification and segregation of biodegradable and non-biodegradable waste - Campus cleaning activity - Plantation of trees in the college campus and local waste lands - Identification of varieties of plants and their usage - Shutting down the fans and ACs of the campus for an hour.

Total (30L + 15P) = 45 Periods

Text B	ooks:						
1.	Elements of Environmental science and Engineering, P.Meenakshi, Prentice Hall of India, New Delhi, 2009.						
2.	A Textbook of Environmental Chemistry and Pollution Control: (With Energy, Ecology, Ethics and Society), Revised Edition, Dr. S.S. Dara, D.D. Mishra Published by S. Chand & Company Ltd, 20 14.						
Refere	Reference Books:						
1.	Introduction to Environmental Engineering and Science, Gilbert M. Masters; Wendell P. Ela Publisher: Prentice-Hall India, 3rd Edition, 2008.						
2.	Environmental Science, Fldren D. Enger, Bredley F.Smith, WCD McGraw Hill 14"Edition 2015.						
E-Refe	erence						
1	www.onlinecourses.nptel.ac.in/						
2	www.ePathshala.nic.in						

	SE OUTCOMES: mpletion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Identify about the major renewable energy systems and will investigate the environmental impact of various energy sources as well as the consequences of various pollutants.	Understand & Analyze
CO2	Predict the methods to conserve energy and ways to make optimal use of the energy for the future.	Apply

COUL	RSE AI	RTICU	LATI	ON MA	ATRIX	· :									
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	0	1	3	0	0	3	1	1	0	0	0	1	2	0	1
CO2	0	1	3	0	0	3	1	1	0	0	0	1	2	0	1
Avg	0	1	3	0	0	3	1	1	0	0	0	1	2	0	1
			3/2	/ 1 – in	dicates	strengt	h of cor	relation	1 (3 – H	igh, 2 – 1	Medium,	1 – Low)		

22ME	E405 THERMAL ENGINEERING I	LABORATORY	SEMESTER IV					
PRE-	REQUISITE:	Category	PC	Cre	1.5			
		II/IV1-	L	T	P	TH		
		Hours/Week	0	0	3	3		
Course	se Objectives:							
1.	The components of IC engine and boiler, mountings and accessories and procedure of steam generation.							
2.	 Constructing port and valve timing diagram and determine the flash and fire point of fuel oil. 							

3. Analyzing the petrol and diesel engine performance by conducting load test.

4. Analyzing the diesel engine performance by retardation test.

5. Characteristics of heat release in diesel engine and to study the p- θ diagram.

LIST OF EXPERIMENTS

- 1. Dismantling and assembling of a single cylinder petrol and diesel engine.
- 2. Demonstration of generating steam using boiler.
- 3. Determination of Viscosity, Flash and Fire point.
- 4. Construction of Valve Timing and Port Timing Diagrams.
- 5. Performance analysis of a four-stroke Diesel Engine.
- 6. Performance analysis of a four-stroke Petrol Engine.
- 7. Construction of a Heat Balance Test on four-stroke Diesel Engine.
- 8. Morse Test on Multi cylinder Diesel Engine.
- 9. Retardation Test to find Frictional Power of a Diesel Engine.
- 10. Determination of p- θ diagram and heat release characteristics of an IC engine.

	RSE OUTCOMES: ompletion of the course, the students will be able:	Bloom's Taxonomy Mapped
CO1	To identify the components of IC engine and boiler, mountings and accessories and procedure of steam generation.	Understand
CO2	To construct port and valve timing diagram and determine the flash and fire point of fuel oil.	Create
CO3	To analyze the petrol and diesel engine performance by conducting load test.	Analyze
CO4	To analyze the diesel engine performance by retardation test.	Analyze
CO5	To study the characteristics of heat release in diesel engine and to study the p - θ diagram.	Remember

COUI	RSE Al	RTICU	LATI	ON MA	ATRIX	·									
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	1	1	3	1	1	0	0	0	0	0	1	1	2
CO2	1	2	1	1	1	2	1	0	0	0	0	0	2	1	1
CO3	2	1	3	1	1	2	1	0	0	0	0	0	3	1	3
CO4	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
CO5	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
Avg	1.2	1	1	0.6	1	1	0.6	0	0	0	0	0	1.2	0.6	1.2
	1	1	3/2	/ 1 – inc	dicates	strengtl	h of cor	relation	1 (3 – H	igh, 2 – I	Medium,	1 – Low	· ')	ı	

22ME406	MANUFACTURING TECHNOLOGY LABOR	SEMESTER IV					
PRE-REQU	UISITE:	Category	PC	Cro	edit	1.5	
1. Constructi	onal and operational features of conventional machine tools		L	T	P	TH	
2. Theory of materials.	metal cutting and machinability of various engineering	Hours/Week	0	0	3	3	

Course Objectives:

- To study different types of machine tools like lathe, drilling machine, shaper and grinding machine.
- 2. To acquire the necessary skills to operate different machinery.
- 3. To calculate metal removal rate and machining time of metal cutting processes
- 4. To analyze and select an appropriate machining process for different components.
- 5. To study safety measures while machining.

LIST OF EXPERIMENTS

- Eccentric turning
- Multi starts thread cutting
- 3. Drilling and grooving
- 4. Counter boring
- 5. Counter sinking
- 6. Shaping the sides of a cubical blank
- 7. Groove cutting and V-cutting
- 8. Dovetail cutting
- T -slot cutting 9.
- 10. Spur gear cutting in milling machine
- 11. Helical Gear Cutting in milling machine
- 12. Contour milling using vertical milling machine
- 13. Surface Grinding of cubical block
- 14. Cylindrical Grinding of circular shaft

	RSE OUTCOMES: completion of the course, the students will be able to:	Bloom's Taxonomy Mapped				
CO1	Operate machines tools for various assembly and fabrication tasks.	Understand				
CO2	Set up machines like lathe shaper, grinding and milling machine for various applications					
CO3	Perform machining time calculation in machining jobs.	Analyze				
CO4	Evaluate the accuracy & tolerance of components produced	Analyze				
CO5	Prepare gears using forming and generating methods of gear manufacturing	Remember				

COUR	COURSE ARTICULATION MATRIX														
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	0	0	0	1	0	1	0	0	1	0	1	0	1	0
CO2	0	2	0	0	2	2	1	1	0	0	0	2	0	2	0
CO3	3	1	0	1	0	0	2	0	1	1	0	1	2	1	3
CO4	3	3	0	0	2	0	0	2	0	0	0	0	0	2	0
CO5	0	1	0	0	0	0	0	0	1	2	0	0	3	0	1
Avg	1.6	1.4	0	0.2	1	0.4	0.8	0.6	0.4	0.8	0	0.8	1	1.2	0.8
		•	3/2/	′ 1 – ind	licates s	trength	of cor	relation	(3 – H	igh, 2 – N	Aedium.	1 – Low)		

		<u> </u>						
22M	E501	SEMI	ESTER	XV				
PRE	REQUI	SITES	Category	PC	Cr	edit	4	
1. Stu	dent sho	uld study engineering mechanics.	Harrya/Wash	L	T	P	TH	
2. Stu	dent sho	uld study kinematic of machinery.	Hours/Week	3	1	0	4	
COU	RSE O	BJECTIVES					•	
1.	Unders	standing of background in mechanics of materials and design of ma	chine componen	ts.				
2. An understanding of the origins, nature and applicability of empirical design principles, based on safety considerations								
3.	An unc	derstanding the design of shafts, couplings and joints.						
4.	Familia	arize the design of energy storing elements and engine components.	•					
5.	An app	preciation of the relationships between component level design and mance	overall machine	system	design a	nd		
UN	NIT-I	STEADY STRESSES AND VARIABLE STRESSES IN MEMBERS	MACHINE	9	3	0	12	
on me princi Factor relation	ple stress r of safe ons.	to the design process – Product development cycle- factors influenced properties - Preferred numbers – Direct, Bending and Torsional streams for various load combinations, eccentric loading – Design of the ty -theories of failure – stress concentration – design for variable process.	ess – Impact and f curved beams le loading – Soo	shock leterane derberg,	oading - hook a Goodm	- Calculand 'C':	ation o frame Gerbe	
on me princi Factor relation	ple stress r of safe ons .	properties - Preferred numbers— Direct, Bending and Torsional stresses for various load combinations, eccentric loading — Design of ety -theories of failure — stress concentration — design for variable DESIGN OF SHAFTS, COUPLINGS AND PIN JO	ess – Impact and f curved beams le loading – Soc	shock leterated shock leterate	hook a Goodm	- Calculard 'C' :	frame Gerber	
on me princi Factor relation UN	echanical ple stress r of safe ons . IT-II	properties - Preferred numbers—Direct, Bending and Torsional stresses for various load combinations, eccentric loading — Design of the ty -theories of failure — stress concentration — design for variable	ess – Impact and f curved beams le loading – Soc	shock leterated shock leterate	hook a Goodm	- Calculard 'C' :	ation of frame Gerbe	
on me princi Factor relation UN Design and fl	echanical ple stress r of safe ons . IT-II	properties - Preferred numbers— Direct, Bending and Torsional streams of various load combinations, eccentric loading — Design of the ty -theories of failure — stress concentration — design for variable design of SHAFTS, COUPLINGS AND PIN Jet design and hollow shafts based on strength, rigidity and critical speed —	ess – Impact and f curved beams le loading – Socion OINTS Design of keys	shock leterated shock leterate	hook a Goodm	- Calculard 'C' :	ation of frame Gerbe	
on me princi Factor relation UN Design and fl UNI Threa	echanical ple stress of safe ons. IT-II on of solid exible control of safe on series of solid decided faste of safe on series of safe on series of safe on series of safe on series of safe of safe on series of	properties - Preferred numbers— Direct, Bending and Torsional streams of various load combinations, eccentric loading — Design of the ty -theories of failure — stress concentration — design for variable design of SHAFTS, COUPLINGS AND PIN Jet and hollow shafts based on strength, rigidity and critical speed — puplings — Design of pin joints like cotter and knuckle joints. DESIGN OF THREADED FASTENERS, RIVETE	ess – Impact and f curved beams le loading – Socion OINTS Design of keys ED AND	shock leterated be shock leterated be shock leterated be shock leterated by shock leterated be shock leterated be shock leterated by shock leterat	oading - hook a Goodm 3 ways -	- Calculand 'C' and and and o Design	ation of frame Gerbe 12 of rigidal	
on me princi Factor relation UN Design and fl UNI Threa vessel	echanical ple stress of safe ons. IT-II on of solid exible control of safe on series of solid decided faste of safe on series of safe on series of safe on series of safe on series of safe of safe on series of	properties - Preferred numbers— Direct, Bending and Torsional streams of various load combinations, eccentric loading — Design of the ty -theories of failure — stress concentration — design for variable design and hollow shafts based on strength, rigidity and critical speed—puplings — Design of pin joints like cotter and knuckle joints. DESIGN OF THREADED FASTENERS, RIVETE WELDED JOINTS eners - Design of bolted joints including eccentric loading — Design of bolted joints — Design of bolted — Design of bolted joints — Design of bolted — Design of bol	ess – Impact and f curved beams le loading – Soc OINTS Design of keys ED AND esign of riveted a	shock leterated be shock leterated be shock leterated be shock leterated by shock leterated be shock leterated be shock leterated by shock leterat	oading - hook a Goodm 3 ways -	- Calculand 'C' and and and o Design	ation of frame Gerbe 12 of riginal 12 oressur	
on me princi Factor relation UN Design and fl UNI Threat vessel UNI Vario engine	echanical iple stress r of safe ons. IT-II In of solid exible co IT-III Ided faste ls and str IT-IV us types es and pu	properties - Preferred numbers— Direct, Bending and Torsional streams for various load combinations, eccentric loading — Design of the ety -theories of failure — stress concentration — design for variable design and hollow shafts based on strength, rigidity and critical speed — puplings — Design of pin joints like cotter and knuckle joints. DESIGN OF THREADED FASTENERS, RIVETE WELDED JOINTS eners - Design of bolted joints including eccentric loading — Desuctures- theory of bonded joints. DESIGN OF ENERGY STORING ELEMENTS AND	ess – Impact and f curved beams le loading – Soc OINTS Design of keys ED AND Sign of riveted a DENGINE Theels considering	shock leterated a shock letera	anding - hook a Goodm 3 ways - ded join 3 es in rin kternal c	O Design O o o o o o o o o o o o o	ation of frame Gerbe 12 of riginal 12 or essure 12 or service 12 or serv	
on me princi Factor relation UN. Design and flund Threat vessel UNI Various engine intern	echanical iple stress r of safe ons. IT-II In of solid exible co IT-III Ided faste ls and str IT-IV us types es and pu	properties - Preferred numbers— Direct, Bending and Torsional stresses for various load combinations, eccentric loading — Design of the ety -theories of failure — stress concentration — design for variable and hollow shafts based on strength, rigidity and critical speed—buplings — Design of pin joints like cotter and knuckle joints. DESIGN OF THREADED FASTENERS, RIVETE WELDED JOINTS eners - Design of bolted joints including eccentric loading — Desuctures - theory of bonded joints. DESIGN OF ENERGY STORING ELEMENTS AND COMPONENTS of springs, optimization of helical springs - rubber springs - Flywunching machines - Connecting Rods and crank shafts. Heat engine	ess – Impact and f curved beams le loading – Socion OINTS Design of keys ED AND Sign of riveted a property of the second of t	shock leterated a shock letera	anding - hook a Goodm 3 ways - ded join 3 es in rin kternal c	O Design O o o o o o o o o o o o o	12 of rigi 12 rms fc ion an	
on me princi Factor relation UN Design and flund Threat vessel UNI Vario engine intern UN Slidin	echanical ple stress of safe ons. IT-II on of solid exible construction of solid exibition of sol	properties - Preferred numbers— Direct, Bending and Torsional streams of various load combinations, eccentric loading — Design of the ety -theories of failure — stress concentration — design for variable and hollow shafts based on strength, rigidity and critical speed—puplings — Design of pin joints like cotter and knuckle joints. DESIGN OF THREADED FASTENERS, RIVETE WELDED JOINTS The eners - Design of bolted joints including eccentric loading — Design of bonded joints. DESIGN OF ENERGY STORING ELEMENTS AND COMPONENTS of springs, optimization of helical springs - rubber springs - Flywards and crank shafts. Heat engine austion engines, Design of I.C engine cylinder, piston, connecting roce. DESIGN OF BEARINGS, LEVERS, PRESSURE VES	ess – Impact and f curved beams le loading – Soc OINTS Design of keys ED AND Sign of riveted a property of the self considering essentials described by the self of the sel	shock leterance of crane derberg, 9 and key 9 and welf 9 g stresse about example of the stresse abou	ading - hook a Goodm 3 ways - 3 ded join sternal cel.	Calculated of Criman and Criman a	12 oressur 12 rms for ion and	

Text	Text Books:							
1	Bhandari V.B, "Design of Machine Elements", Tata McGraw Hill Book Co, 2020							
2	Md.Jalaludeen.S, "A text book of Machine Design", Anuradha Publications, 2006							
Refer	rence Books:							
1	Shigley, J.E. and Mischke, C.R., Mechanical Engineering Design, Fifth Edition, McGraw-Hill International; 1989.							
2	Deutschman, D., Michels, W.J. and Wilson, C.E., Machine Design Theory and Practice, Macmillan, 1992.							

3	Juvinal, R.C., Fundamentals of Machine Component Design, John Wiley, 1994.							
4	PSG Tech, "Design Data Handbook", M/s.DPV Printers, Coimbatore, 2009							
E-R	eferences:							
1	https://nptel.ac.in/courses/112105124							
2	Design of Machine Elements - V. B. Bhandari - Google Books							
3	A Textbook of Machine Design by R.S.Khurmi And J.K.Gupta [tortuka]_1490186411865.pdf DocDroid							

	RSE OUTCOMES: impletion of the course the student will be able to	Bloom's Taxonomy Mapped
CO1	Explain the influence of steady and variable stresses in machine component design.	Understand
CO2	Apply the concepts of design to shafts, keys and couplings.	Apply
CO3	Familiarize the design of temporary and permanent joints	Understand
CO4	Design the various energy storing elements and engine components.	Analyze
CO5	Familiarize the design of various types of bearings and pressure vessels.	Understand

COURS	SE AR	TICU	LATI	ON M	ATRI	X									
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	1	2	0	1	1	0	0	0	1	0	3	2	1
CO2	2	2	1	2	0	1	1	0	0	0	1	0	3	2	1
CO3	2	2	1	2	0	1	1	0	0	0	1	0	3	2	1
CO4	2	2	1	2	0	1	1	0	0	0	1	0	3	2	1
CO5	2	2	1	2	0	1	1	0	0	0	1	0	3	2	1
Avg	2.0	2.0	1.0	2.0	0.0	1.0	1.0	0.0	0.0	0.0	1.0	0.0	3.0	2.0	1.0
			3/2	2/1 – in	dicates	s stren	gth of	correlat	tion (3	– high, 2	- mediui	n, 1- low)		

22ME	2502	HEAT AND MASS TRANSFER		5	SEMES	STER Y	V	
PRER	REQUI	SITES:	Category	PC	Cr	edit	3	
1.The la	laws and	l basic concepts of thermodynamics		L	Т	P	TH	
		of energy transfers and their conversion principles	Hours/Week	3	0	0	3	
Cours	se Obje	ectives	1		I	1		
1.	Under	rstanding the science behind conduction heat transfer and its a	applications					
2.	Differ	rentiating the concepts of forced and natural convection heat to	ransfer					
3.	Descr	ibing the laws and concepts of radiation heat transfer						
4.	Under	rstanding phase change processes and analyzing heat exchang	gers					
5.	Study	ing the concept of mass transfer process and its modes						
UNI	T-I	CONDUCTION HEAT TRANSFE	R	9	0	0	9	
Differe Conduc	ential E ction —	rential equation – Cartesian (derivation of General Differentiation) and Spherical Coordinates– One Dimensional Seplane and Composite Systems – Conduction with Internal Heaters – Unsteady Heat Conduction – Lumped Analysis – Separate Specification – Separate Specification – Separate Specification – Conduction – Separate Specification – Separate	Steady State Heat-Co eat Generation., Critic	oncepts cal thick	drical (derivation of General Accepts of electrical analogal thickness of insulation. Inite Solids –Use of Heisler 9 0 0 Plates, cylinders, spheres arizontal plate, inclined plate.			
Differe Conduc Extend charts.	ential E ction — ded Sur T-II	quation) and Spherical Coordinates— One Dimensional Splane and Composite Systems – Conduction with Internal Herfaces – Unsteady Heat Conduction – Lumped Analysis – Sconvection HEAT TRANSFER	Steady State Heat-Coeat Generation., Critic Semi Infinite and Inf	oncepts cal thicks finite So	of electroness of i lids –U	trical a insulation see of H	nalogy, n. eisler's	
Extende charts. UNIT	ential E ction — ded Sur T-II evation e	quation) and Spherical Coordinates— One Dimensional Splane and Composite Systems — Conduction with Internal Heraces — Unsteady Heat Conduction — Lumped Analysis — Sequations, boundary layer concept — Forced convection: external flow — entrance effects. Free convection —flow of	Steady State Heat-Co eat Generation., Critic Semi Infinite and Inf R	oncepts cal thicks finite So	of electroness of ilids –U o cylinde	trical a insulation se of H	nalogy, n. eisler's 9 res and	
Extende charts. UNIT	ential E ction — ded Sur T-II rvation e of tubes. ers and s	quation) and Spherical Coordinates— One Dimensional Splane and Composite Systems — Conduction with Internal Heraces — Unsteady Heat Conduction — Lumped Analysis — Sequations, boundary layer concept — Forced convection: external flow — entrance effects. Free convection —flow of	Steady State Heat-Coeat Generation., Critic Semi Infinite and Inf R ernal flow – flow ove over vertical plate, h	oncepts cal thicks finite So	of electroness of ilids –U o cylinde	trical a insulation se of H	nalogy, n. eisler's 9 res and	
Differe Conductor Extende charts. UNIT Conservation bank of cylinder UNIT Regime	ential Ection— ded Sur T-II Evation e of tubes ers and s T-III Evation of tubes ers and s	quation) and Spherical Coordinates— One Dimensional Splane and Composite Systems — Conduction with Internal Herfaces — Unsteady Heat Conduction — Lumped Analysis — Sequations, boundary layer concept — Forced convection: extending expheres.	Steady State Heat-Coeat Generation., Critic Semi Infinite and Inf R ernal flow – flow over vertical plate, heat-CHANGERS ition- correlations in be	oncepts cal thicks finite So 9 or plates, acrizonta 9 poiling a	of electroness of i lids –U o cylinde l plate,	etrical a insulation of the second House of Hous	nalogy, n. eisler's 9 res and l plate,	
Differe Conductor Extende charts. UNIT Conservation bank of cylinder UNIT Regime	T-II rvation cof tubes ers and s T-III respectively.	quation) and Spherical Coordinates— One Dimensional Splane and Composite Systems — Conduction with Internal Heraces — Unsteady Heat Conduction — Lumped Analysis — Sequations, boundary layer concept — Forced convection: external flow — entrance effects. Free convection—flow of spheres. BOILING, CONDENSATION AND HEAT EX pool boiling and Flow boiling, Nusselt's theory of condensations.	Steady State Heat-Coeat Generation., Critic Semi Infinite and Information Info	oncepts cal thicks finite So 9 or plates, acrizonta 9 poiling a	of electroness of i lids –U o cylinde l plate,	etrical a insulation of the second House of Hous	nalogy, n. eisler's 9 res and l plate,	
Differe Conductor Extende charts. UNIT Conservant bank or cylinde UNIT Regime Exchant UNIT	T-II rvation cof tubes. ers and s T-III runting results of tubes. ers and s T-III results of Ponger Typer T-IV	quation) and Spherical Coordinates— One Dimensional Splane and Composite Systems — Conduction with Internal Heraces — Unsteady Heat Conduction — Lumped Analysis — Sequations, boundary layer concept — Forced convection: extended in the spheres. **BOILING, CONDENSATION AND HEAT EX BOILING, CONDENSATION AND HEAT EX BOILING and Flow boiling, Nusselt's theory of condensations — Overall Heat Transfer Coefficient — Fouling Factors. LM	Steady State Heat-Coeat Generation., Critic Semi Infinite and Information of the Example of the Semi Infinite and Information of the Echangers ECHANGERS Information of the Echangers of the of t	oncepts cal thicks finite So 9 or plates, acrizonta 9 ooiling a ds. 9	of electroness of i lids –U organisation of the content of the co	trical a insulation for the second House of Hous	nalogy, n. eisler's 9 res and d plate, 9 n. Heat	
Differe Conductor Extende charts. UNIT Conservant bank or cylinde UNIT Regime Exchant UNIT	T-II rvation e of tubes. ers and s F-III F-III res of Ponger Type T-IV ion laws	quation) and Spherical Coordinates— One Dimensional Splane and Composite Systems — Conduction with Internal Herfaces — Unsteady Heat Conduction — Lumped Analysis — Sequations, boundary layer concept — Forced convection: extended and the spheres. **BOILING, CONDENSATION AND HEAT EXTENDED BOILING, CONDENSATION AND HEAT EXTENDED BOILING, Nusselt's theory of condensations — Overall Heat Transfer Coefficient — Fouling Factors. LM **RADIATION HEAT TRANSFER**	Steady State Heat-Coeat Generation., Critic Semi Infinite and Information of the Example of the Semi Infinite and Information of the Echangers ECHANGERS Information of the Echangers of the of t	oncepts cal thicks finite So 9 or plates, acrizonta 9 ooiling a ds. 9	of electroness of i lids –U organisation of the content of the co	trical a insulation for the second House of Hous	nalogy, n. eisler's 9 res and d plate, 9 n. Heat	
Differe Conduct Extend charts. UNIT Conservant bank of cylinder UNIT Regime Exchant UNIT Radiation UNIT Radiation UNIT Radiation UNIT Basic Conduction Co	T-II rvation of tubes ers and s T-III reaction T-III rvation of tubes ers and s T-III reaction T-III Concept Concept	quation) and Spherical Coordinates— One Dimensional Splane and Composite Systems — Conduction with Internal Herfaces — Unsteady Heat Conduction — Lumped Analysis — Sequations, boundary layer concept — Forced convection: extended in the spheres. CONVECTION HEAT TRANSFER Convection — Flow of Spheres. BOILING, CONDENSATION AND HEAT EXTENDED in the spheres in the spheres of the spheres. RADIATION HEAT TRANSFER Spirit And Spaces — Overall Heat Transfer Coefficient — Fouling Factors. LM RADIATION HEAT TRANSFER Spirit And Spaces — Spheres — Sph	Steady State Heat-Coeat Generation., Critic Semi Infinite and Information of the Example of the	oncepts cal thicks finite So y y y y y y y y y y y y y y y y y y	of electroness of i lids –U o cylinde l plate, o nd cond o ds.	trical a insulation from the second Hersel of	nalogy, n. eisler's 9 res and l plate, 9 n. Heat	

Text I	Books:
1	R.C. Sachdeva, "Fundamentals of Engineering Heat & Mass transfer", New Age International Publishers, 2017
2	Frank P. Incropera and David P. Dewitt, "Fundamentals of Heat and Mass Transfer", John Wiley & Sons, 7th Edition, 2014.
Refere	ence Books:
1	Yunus A. Cengel, "Heat Transfer A Practical Approach" – Tata McGraw Hill, 5 th Edition - 2013
2	Holman, J.P., "Heat and Mass Transfer", Tata McGraw Hill, 2017
3	Kothandaraman, C.P., "Fundamentals of Heat and Mass Transfer", New Age International, New Delhi, 2012
4	Ozisik, M.N., "Heat Transfer", McGraw Hill Book Co., 1994.

	RSE OUTCOMES: npletion of the course the student will be able to	Bloom's Taxonomy Mapped
CO1	Analyze the mechanism of heat conduction under steady and transient conditions.	Apply
CO2	Develop solutions to problems involving convective heat transfer	Create
СОЗ	Design a heat exchanger for any specific application	Understand
CO4	Adopt the concept of radiation heat transfer in real time systems	Understand
CO5	Develop solutions to problems involving combined heat and mass transfer	Apply

COUR	RSE Al	RTIC	ULAT	ION N	MATR	IX									
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	2	0	1	0	0	0	0	0	3	3	1
CO2	3	3	3	3	2	0	1	0	0	0	0	0	3	3	1
CO3	3	3	3	3	2	0	1	0	0	0	0	0	3	3	1
CO4	3	3	3	3	2	0	1	0	0	0	0	0	3	2	1
CO5	2	2	2	2	1	0	1	0	0	0	0	0	3	1	0
Avg	2.8	2.8	2.8	2.8	1.8	0	1	0	0	0	0	0	3	2.4	0.8
			3.	/2/1 – i	ndicate	es strei	ngth of	correla	tion (3	– high, 2	2- mediur	n, 1- low))		

PREREQUISITES Category PC Rategory	22M	E503	METROLOGY AND QUALITY CONTRO	L	5	SEMES	STER V	V
Course Objectives:	PRE	REQUI	SITES	Category	PC	Cre	edit	3
Course Objectives: 1. Explaining the importance of measurements in engineering and the factors affecting measurements and to compute measurement uncertainty 2. Applying the applications of linear and angular measuring instruments 3. Interpretation of various tolerance symbols. 4. Applying the SQC methods in manufacturing 5. Applying the advances in measurements for quality control UNIT I BASICS OF MEASUREMENT SYSTEM AND DEVICES 9 0 0 9 Definition of metrology, accuracy, precision and sensitivity, Abbe's principle. Three stages of generalize-dimeasurements-weight in the control of metrology, accuracy, precision and sensitivity, Abbe's principle. Three stages of generalize-dimeasurements-mechanical loading-static characteristics of instruments - commonly used terms, error analysis and classification - sources of error. Measurement uncertainty UNIT II CALIBRATION OF INSTRUMENTS AND QUALITY STANDARDS Calibration of measuring instruments - principles of calibration, Calibration of Instruments - Vernier caliper, Micrometer, feeler gauges, dial indicator, surface plates, slip gauges, care of gauge blocks. General cares and rules in measurement, ISO 9000 quality standards. Comparators - mechanical, electrical, optical and pneumatic. UNIT III GEOMETRICAL MEASUREMENT AND MACHINE ELEMENTS 9 0 0 9 Angular measurement - optical protractors, sine bar, roundness measurement, limit gauge, design of plug gauge, Taylor's principle, three basic types of limit gauges, Tomlinson surface meter, computer controlled CMM. ISO metric thread, measurement of major, minor and effective diameters. Gear terminology; spur gear measurement, checking of composite errors, base pitch measurement. Principle of interferometry, laser interferometer, Machine vision, Fundamental of GD and T. Inspection of straightness, flatness, roundness deviations. UNIT IV STATISTICAL QUALITY CONTROL 9 0 0 9 Surfacefinish-terminologyandmeasurements-Opticalmeasuring instruments-AcceptancetestformachinesStatistical/Quality Control-Control charts-Sampling				II /\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	L	Т	P	TH
1. Explaining the importance of measurements in engineering and the factors affecting measurements and to compute measurement uncertainty 2. Applying the applications of linear and angular measuring instruments 3. Interpretation of various tolerance symbols. 4. Applying the SQC methods in manufacturing 5. Applying the sQC methods in manufacturing 6. Applying the advances in measurements for quality control 1. UNIT I BASICS OF MEASUREMENT SYSTEM AND DEVICES 9 0 0 9 1. Definition of metrology, accuracy, precision and sensitivity, Abbe's principle. Three stages of generalizedmeasurementsystem-mechanicalloading-staticcharacteristicsofinstruments-factorsconsideredinselection of instruments - commonly used terms, error analysis and classification - sources of error. Measurement uncertainty 1. UNIT II CALIBRATION OF INSTRUMENTS AND QUALITY STANDARDS 2. Calibration of measuring instruments - principles of calibration, Calibration of Instruments - Vernier caliper, Micrometer, feeler gauges, dial indicator, surface plates, slip gauges, care of gauge blocks. General cares and rules in measurement, ISO 9000 quality standards. Comparators - mechanical, electrical, optical and pneumatic. 1. UNIT III GEOMETRICAL MEASUREMENT AND MACHINE ELEMENTS 9 0 0 9 3. Angular measurement - optical protractors, sine bar, roundness measurement, limit gauge, design of plug gauge, Taylor 's principle, three basic types of limit gauges, Tomlinson surface meter, computer controlled CMM. ISO metric thread, measurement of major, minor and effective diameters. Gear terminology; spur gear measurement, checking of composite errors, base pitch measurement. Principle of interferometry, laser interferometer, Machine vision, Fundamental of GD and T. Inspection of straightness, flatness, roundness deviations. 1. UNIT IV STATISTICAL QUALITY CONTROL 9 0 0 9 2. Surfacefinish-terminologyandmeasurements-Opticalmeasuringinstruments-AcceptancetestformachinesStatisticalQuality Control-Control charts-Sampling plans 1. UNIT V STATISTICAL QUALITY CON				Hours/ week	3	0	0	3
measurement uncertainty 2. Applying the applications of linear and angular measuring instruments 3. Interpretation of various tolerance symbols. 4. Applying the SQC methods in manufacturing 5. Applying the advances in measurements for quality control UNIT I BASICS OF MEASUREMENT SYSTEM AND DEVICES 9 0 0 9 Definition of metrology, accuracy, precision and sensitivity, Abbe's principle. Three stages of generalizedmeasurementsystem-mechanicalloading-staticcharacteristicsofinstruments-factorsconsideredinselection of instruments - commonly used terms, error analysis and classification - sources of error. Measurement uncertainty UNIT II CALIBRATION OF INSTRUMENTS AND QUALITY STANDARDS 9 0 0 9 Calibration of measuring instruments - principles of calibration, Calibration of Instruments - Vernier caliper, Micrometer, feeler gauges, dial indicator, surface plates, slip gauges, care of gauge blocks. General cares and rules in measurement, ISO 9000 quality standards. Comparators - mechanical, electrical, optical and pneumatic. UNIT III GEOMETRICAL MEASUREMENT AND MACHINE ELEMENTS 9 0 0 9 Angular measurement - optical protractors, sine bar, roundness measurement, limit gauge, design of plug gauge, Taylor 's principle, three basic types of limit gauges, Tomlinson surface meter, computer controlled CMM. ISO metric thread, measurement of major, minor and effective diameters. Gear terminology; spur gear measurement, checking of composite errors, base pitch measurement. Principle of interferometry, laser interferometer, Machine vision, Fundamental of GD and T. Inspection of straightness, flatness, roundness deviations. UNIT IV STATISTICAL QUALITY CONTROL 9 0 0 9 Sixsigma: UNIT V SIX SIGMA 9 0 0 9 Sixsigma: Sixsigma: VNIT V SIX SIGMA 9 0 0 9 Sixsigma: Sixsigma: Nova, Multi variate analysis, Hypothesis Testing, ANOVA, Multi variate analysis.	Cou	rse Obje	ectives:					
3. Interpretation of various tolerance symbols. 4. Applying the SQC methods in manufacturing 5. Applying the advances in measurements for quality control UNIT I BASICS OF MEASUREMENT SYSTEM AND DEVICES 9 0 0 9 Definition of metrology, accuracy, precision and sensitivity, Abbe's principle. Three stages of generalized measurementsystem-mechanical loading-static characteristics of instruments-factors considered inselection of instruments - commonly used terms, error analysis and classification - sources of error. Measurement uncertainty UNIT II CALIBRATION OF INSTRUMENTS AND QUALITY 9 0 0 0 9 Calibration of measuring instruments - principles of calibration, Calibration of Instruments - Vernier caliper, Micrometer, feeler gauges, dial indicator, surface plates, slip gauges, care of gauge blocks. General cares and rules in measurement, ISO 9000 quality standards. Comparators - mechanical, electrical, optical and pneumatic. UNIT III GEOMETRICAL MEASUREMENT AND MACHINE ELEMENTS 9 0 0 9 Angular measurement - optical protractors, sine bar, roundness measurement, limit gauge, design of plug gauge, Taylor 's principle, three basic types of limit gauges, Tomlinson surface meter, computer controlled CMM. ISO metric thread, measurement of major, minor and effective diameters. Gear terminology; spur gear measurement, checking of composite errors, base pitch measurement. Principle of interferometry, laser interferometer, Machine vision, Fundamental of GD and T. Inspection of straightness, flatness, roundness deviations. UNIT IV STATISTICAL QUALITY CONTROL 9 0 0 9 Surfacefinish-terminologyandmeasurements-Opticalmeasuringinstruments-AcceptancetestformachinesStatisticalQuality Control-Control charts-Sampling plans UNIT V SIX SIGMA 9 0 0 9 Sixsigma:definemeasure,analyse,improveandcontrolphases.Analyzephasetools:CommonTools:Histogram,BoxPlot,Controlchart,Scatterchart,Causeandeffectdiagram,Paretoanalysis,interrelationsdiagram. Special Tools: Regression Analysis, Hypothesis Testing, ANOVA, Multi variate analysis.	1.			actors affecting n	neasurer	ments a	nd to co	ompute
4. Applying the SQC methods in manufacturing 5. Applying the advances in measurements for quality control UNIT I BASICS OF MEASUREMENT SYSTEM AND DEVICES 9 0 0 9 Definition of metrology, accuracy, precision and sensitivity, Abbe's principle. Three stages of generalized measurementsystem-mechanicalloading-staticcharacteristicsofinstruments-factors considered inselection of instruments - commonly used terms, error analysis and classification - sources of error. Measurement uncertainty UNIT II CALIBRATION OF INSTRUMENTS AND QUALITY 9 0 0 9 Calibration of measuring instruments - principles of calibration, Calibration of Instruments - Vernier caliper, Micrometer, feeler gauges, dial indicator, surface plates, slip gauges, care of gauge blocks. General cares and rules in measurement, ISO 9000 quality standards. Comparators - mechanical, electrical, optical and pneumatic. UNIT III GEOMETRICAL MEASUREMENT AND MACHINE ELEMENTS 9 0 0 9 Angular measurement - optical protractors, sine bar, roundness measurement, limit gauge, design of plug gauge, Taylor's principle, three basic types of limit gauges, Tomlinson surface meter, computer controlled CMM. ISO metric thread, measurement of major, minor and effective diameters. Gear terminology; spur gear measurement, checking of composite errors, base pitch measurement. Principle of interferometry, laser interferometer, Machine vision, Fundamental of GD and T. Inspection of straightness, flatness, roundness deviations. UNIT IV STATISTICAL QUALITY CONTROL 9 0 0 9 Surfacefinish-terminologyandmeasurements-Opticalmeasuringinstruments-AcceptancetestformachinesStatisticalQuality Control-Control charts-Sampling plans UNIT V SIX SIGMA 9 0 0 9 Sixsigma:definemeasure,analyse,improveandcontrolphases.Analyzephasetools:CommonTools:Histogram,BoxPlot,Controlchart,Scatterchart,Causeandeffectdiagram,Paretoanalysis,interrelationsdiagram. Special Tools: Regression Analysis, Hypothesis Testing, ANOVA, Multi variate analysis.	2.	Applyii	ng the applications of linear and angular measuring instruments					
UNIT I BASICS OF MEASUREMENT SYSTEM AND DEVICES 9 0 0 9 Definition of metrology, accuracy, precision and sensitivity, Abbe's principle. Three stages of generalizedmeasurementsystem-mechanicalloading-staticcharacteristicsofinstruments-factorsconsideredinselection of instruments - commonly used terms, error analysis and classification - sources of error. Measurement uncertainty UNIT II CALIBRATION OF INSTRUMENTS AND QUALITY 9 0 0 9 Calibration of measuring instruments - principles of calibration, Calibration of Instruments - Vernier caliper, Micrometer, feeler gauges, dial indicator, surface plates, slip gauges, care of gauge blocks. General cares and rules in measurement, ISO 9000 quality standards. Comparators - mechanical, electrical, optical and pneumatic. UNIT III GEOMETRICAL MEASUREMENT AND MACHINE ELEMENTS 9 0 0 9 Angular measurement - optical protractors, sine bar, roundness measurement, limit gauge, design of plug gauge, Taylor 's principle, three basic types of limit gauges, Tomlinson surface meter, computer controlled CMM. ISO metric thread, measurement of major, minor and effective diameters. Gear terminology; spur gear measurement, checking of composite errors, base pitch measurement. Principle of interferometry, laser interferometer, Machine vision, Fundamental of GD and T. Inspection of straightness, flatness, roundness deviations. UNIT IV STATISTICAL QUALITY CONTROL 9 0 0 9 Surfacefinish-terminologyandmeasurements-Opticalmeasuringinstruments-AcceptancetestformachinesStatisticalQuality Control-Control charts-Sampling plans UNIT V SIX SIGMA 9 0 0 9 Sixsigma:definemeasure, analyse, improveandcontrolphases. Analyzephasetools: CommonTools: Histogram, BoxPlot, Controlchart, Scatterchart, Causeandelfectdiagram, Paretoanalysis, interrelationsdiagram. Special Tools: Regression Analysis, Hypothesis Testing, ANOVA, Multi variate analysis.	3.	Interpre	etation of various tolerance symbols.					
UNIT I BASICS OF MEASUREMENT SYSTEM AND DEVICES 9 0 0 9 Definition of metrology, accuracy, precision and sensitivity, Abbe's principle. Three stages of generalizedmeasurementsystem-mechanicalloading-staticcharacteristicsofinstruments-factorsconsideredinselection of instruments - commonly used terms, error analysis and classification - sources of error. Measurement uncertainty UNIT II CALIBRATION OF INSTRUMENTS AND QUALITY STANDARDS Calibration of measuring instruments - principles of calibration, Calibration of Instruments - Vernier caliper, Micrometer, feeler gauges, dial indicator, surface plates, slip gauges, care of gauge blocks. General cares and rules in measurement, ISO 9000 quality standards. Comparators - mechanical, electrical, optical and pneumatic. UNIT III GEOMETRICAL MEASUREMENT AND MACHINE ELEMENTS 9 0 0 9 Angular measurement - optical protractors, sine bar, roundness measurement, limit gauge, design of plug gauge, Taylor 's principle, three basic types of limit gauges, Tomlinson surface meter, computer controlled CMM. ISO metric thread, measurement of major, minor and effective diameters, Gear terminology; spur gear measurement, checking of composite errors, base pitch measurement. Principle of interferometry, laser interferometer, Machine vision, Fundamental of GD and T. Inspection of straightness, flatness, roundness deviations. UNIT IV STATISTICAL QUALITY CONTROL 9 0 0 9 Surfacefinish-terminologyandmeasurements-Opticalmeasuringinstruments-AcceptancetestformachinesStatisticalQuality Control-Control charts-Sampling plans UNIT V SIX SIGMA 9 0 0 9 Sixsigma:definemeasure, analyse, improveandcontrolphases. Analyzephasetools: CommonTools: Histogram, BoxPlot, Controlchart, UScatterchart, Causeandeffectdiagram, Paretoanalysis, interrelationsdiagram. Special Tools: Regression Analysis, Hypothesis Testing, ANOVA, Multi variate analysis.	4.	Applyii	ng the SQC methods in manufacturing					
Definition of metrology, accuracy, precision and sensitivity, Abbe's principle. Three stages of generalizedmeasurementsystem- mechanicalloading-staticcharacteristicsofinstruments-factorsconsideredinselection of instruments - commonly used terms, error analysis and classification - sources of error. Measurement uncertainty UNIT II CALIBRATION OF INSTRUMENTS AND QUALITY STANDARDS Calibration of measuring instruments - principles of calibration, Calibration of Instruments - Vernier caliper, Micrometer, feeler gauges, dial indicator, surface plates, slip gauges, care of gauge blocks. General cares and rules in measurement, ISO 9000 quality standards. Comparators - mechanical, electrical, optical and pneumatic. UNIT III GEOMETRICAL MEASUREMENT AND MACHINE ELEMENTS Angular measurement - optical protractors, sine bar, roundness measurement, limit gauge, design of plug gauge, Taylor 's principle, three basic types of limit gauges, Tomlinson surface meter, computer controlled CMM. ISO metric thread, measurement of major, minor and effective diameters. Gear terminology; spur gear measurement, checking of composite errors, base pitch measurement. Principle of interferometry, laser interferometer, Machine vision, Fundamental of GD and T. Inspection of straightness, flatness, roundness deviations. UNIT IV STATISTICAL QUALITY CONTROL 9 0 9 0 9 SURfacefinish-terminologyandmeasurements-Opticalmeasuringinstruments-AcceptancetestformachinesStatisticalQuality Control-Control charts-Sampling plans UNIT V SIX SIGMA 9 0 9 0 9 Sixsigma:definemeasure,analyse,improveandcontrolphases.Analyzephasetools:CommonTools:Histogram,BoxPlot,Controlchar t,Scatterchart,Causeandeffectdiagram,Paretoanalysis,interrelationsdiagram. Special Tools: Regression Analysis, Hypothesis Testing, ANOVA, Multi variate analysis.	5.	Applyii	ng the advances in measurements for quality control					
mechanicalloading-staticcharacteristicsofinstruments-factorsconsideredinselection of instruments - commonly used terms, error analysis and classification - sources of error. Measurement uncertainty CALIBRATION OF INSTRUMENTS AND QUALITY STANDARDS	UN	ITI	BASICS OF MEASUREMENT SYSTEM AND D	EVICES	9	0	0	9
Calibration of measuring instruments - principles of calibration, Calibration of Instruments - Vernier caliper, Micrometer, feeler gauges, dial indicator, surface plates, slip gauges, care of gauge blocks. General cares and rules in measurement, ISO 9000 quality standards. Comparators - mechanical, electrical, optical and pneumatic. UNIT III GEOMETRICAL MEASUREMENT AND MACHINE ELEMENTS 9 0 0 9 Angular measurement - optical protractors, sine bar, roundness measurement, limit gauge, design of plug gauge, Taylor 's principle, three basic types of limit gauges, Tomlinson surface meter, computer controlled CMM. ISO metric thread, measurement of major, minor and effective diameters. Gear terminology; spur gear measurement, checking of composite errors, base pitch measurement. Principle of interferometry, laser interferometer, Machine vision, Fundamental of GD and T. Inspection of straightness, flatness, roundness deviations. UNIT IV STATISTICAL QUALITY CONTROL 9 0 0 9 Surfacefinish-terminologyandmeasurements-Opticalmeasuringinstruments-AcceptancetestformachinesStatisticalQuality Control-Control charts-Sampling plans UNIT V SIX SIGMA 9 0 0 9 Sixsigma:definemeasure,analyse,improveandcontrolphases.Analyzephasetools:CommonTools:Histogram,BoxPlot,Controlchar t,Scatterchart,Causeandeffectdiagram,Paretoanalysis,interrelationsdiagram. Special Tools: Regression Analysis, Hypothesis Testing, ANOVA, Multi variate analysis.	mech	anicalloa	ding-staticcharacteristicsofinstruments-factorsconsideredinselection					-
gauges, dial indicator, surface plates, slip gauges, care of gauge blocks. General cares and rules in measurement, ISO 9000 quality standards. Comparators - mechanical, electrical, optical and pneumatic. UNIT III GEOMETRICAL MEASUREMENT AND MACHINE ELEMENTS 9 0 0 9 Angular measurement - optical protractors, sine bar, roundness measurement, limit gauge, design of plug gauge, Taylor 's principle, three basic types of limit gauges, Tomlinson surface meter, computer controlled CMM. ISO metric thread, measurement of major, minor and effective diameters. Gear terminology; spur gear measurement, checking of composite errors, base pitch measurement. Principle of interferometry, laser interferometer, Machine vision, Fundamental of GD and T. Inspection of straightness, flatness, roundness deviations. UNIT IV STATISTICAL QUALITY CONTROL 9 0 0 9 Surfacefinish-terminologyandmeasurements-Opticalmeasuringinstruments-AcceptancetestformachinesStatisticalQuality Control-Control charts-Sampling plans UNIT V SIX SIGMA 9 0 0 9 Sixsigma:definemeasure,analyse,improveandcontrolphases.Analyzephasetools:CommonTools:Histogram,BoxPlot,Controlchart,Scatterchart,Causeandeffectdiagram,Paretoanalysis,interrelationsdiagram. Special Tools: Regression Analysis, Hypothesis Testing, ANOVA, Multi variate analysis.	UN	IT II		ALITY	9	0	0	9
Angular measurement - optical protractors, sine bar, roundness measurement, limit gauge, design of plug gauge, Taylor 's principle, three basic types of limit gauges, Tomlinson surface meter, computer controlled CMM. ISO metric thread, measurement of major, minor and effective diameters. Gear terminology; spur gear measurement, checking of composite errors, base pitch measurement. Principle of interferometry, laser interferometer, Machine vision, Fundamental of GD and T. Inspection of straightness, flatness, roundness deviations. UNIT IV STATISTICAL QUALITY CONTROL 9 0 9 Verifacefinish-terminologyandmeasurements-Opticalmeasuringinstruments-AcceptancetestformachinesStatisticalQuality Control-Control charts-Sampling plans UNIT V SIX SIGMA 9 0 9 Sixsigma:definemeasure,analyse,improveandcontrolphases.Analyzephasetools:CommonTools:Histogram,BoxPlot,Controlchart,Scatterchart,Causeandeffectdiagram,Paretoanalysis,interrelationsdiagram. Special Tools: Regression Analysis, Hypothesis Testing, ANOVA, Multi variate analysis.	gauge	es, dial i	ndicator, surface plates, slip gauges, care of gauge blocks. Gene		_			
principle, three basic types of limit gauges, Tomlinson surface meter, computer controlled CMM. ISO metric thread, measurement of major, minor and effective diameters. Gear terminology; spur gear measurement, checking of composite errors, base pitch measurement. Principle of interferometry, laser interferometer, Machine vision, Fundamental of GD and T. Inspection of straightness, flatness, roundness deviations. UNIT IV STATISTICAL QUALITY CONTROL 9 0 0 9 Surfacefinish-terminologyandmeasurements-Opticalmeasuringinstruments-AcceptancetestformachinesStatisticalQuality Control-Control charts-Sampling plans UNIT V SIX SIGMA 9 0 0 9 Sixsigma:definemeasure,analyse,improveandcontrolphases.Analyzephasetools:CommonTools:Histogram,BoxPlot,Controlchar t,Scatterchart,Causeandeffectdiagram,Paretoanalysis,interrelationsdiagram. Special Tools: Regression Analysis, Hypothesis Testing, ANOVA, Multi variate analysis.	UN	IT III	GEOMETRICAL MEASUREMENT AND MACHINE	ELEMENTS	9	0	0	9
Surfacefinish-terminologyandmeasurements-Opticalmeasuringinstruments-AcceptancetestformachinesStatisticalQuality Control-Control charts-Sampling plans UNIT V SIX SIGMA 9 0 0 9 Sixsigma:definemeasure,analyse,improveandcontrolphases.Analyzephasetools:CommonTools:Histogram,BoxPlot,Controlchar t,Scatterchart,Causeandeffectdiagram,Paretoanalysis,interrelationsdiagram. Special Tools: Regression Analysis, Hypothesis Testing, ANOVA, Multi variate analysis.	princi measi base	iple, thre urement pitch m	ee basic types of limit gauges, Tomlinson surface meter, co of major, minor and effective diameters. Gear terminology; spur g easurement. Principle of interferometry, laser interferometer,	emputer controlled gear measurement,	d CMM, checking	I. ISO	metric mposite	thread, errors,
Control-Control charts-Sampling plans UNIT V SIX SIGMA 9 0 0 9 Sixsigma:definemeasure,analyse,improveandcontrolphases.Analyzephasetools:CommonTools:Histogram,BoxPlot,Controlchar t,Scatterchart,Causeandeffectdiagram,Paretoanalysis,interrelationsdiagram. Special Tools: Regression Analysis, Hypothesis Testing, ANOVA, Multi variate analysis.	UN	IT IV	STATISTICAL QUALITY CONTROL		9	0	0	9
Sixsigma:definemeasure,analyse,improveandcontrolphases.Analyzephasetools:CommonTools:Histogram,BoxPlot,Controlchar t,Scatterchart,Causeandeffectdiagram,Paretoanalysis,interrelationsdiagram. Special Tools: Regression Analysis, Hypothesis Testing, ANOVA, Multi variate analysis.			· · ·	eptancetestformac	hinesSta	ntistical	Quality	
t,Scatterchart,Causeandeffectdiagram,Paretoanalysis,interrelationsdiagram. Special Tools: Regression Analysis, Hypothesis Testing, ANOVA, Multi variate analysis.	UN	TT V	SIX SIGMA		9	0	0	9
Total = 45 Periods	t,Sc	atterchar	$t, Cause and effect diagram, Pareto analysis, interrelations diagram. \ Space{-0.05cm} Space{-$		_			
						Total	= 45 P	eriods

Text	Books:
1.	Gupta.I.C, —A text book of Engineering Metrology, Dhanpat Rai publications, New Delhi, 2018
2.	Beckwith.T.G,Roy D. Marangoni, John H. Lienhard, - Mechanical Measurements, Prentice Hall, 2006
Refe	rence Books:
1.	Jain.R.K, —Mechanical and Industrial Measurementsl, Khanna Publishers, Delhi, 1999.
2.	Holmen.J.P, —Experimental Methods for Engineersl, Tata McGraw Hill Publications Co Limited, 2017.
3.	Grant, E.L., Statistical Quality Control, Mc Graw-Hill, 2004. 3. Doeblin E.O., Measurement Systems, Mc Graw-Hill, 2004.

4.	Alan S Morris, —Measurement and Instrumentation Principles, Butterworth, 2006.
5.	De Feo J A and Barnard W W, —Six Sigma: Break trough and BeyondG, Tata McGraw-Hill, New Delhi, 2005.
E-Re	eferences:
1.	https://nitsri.ac.in/Department/Mechanical%20Engineering/MEC_405_Book_2,_for_Unit_2B.pdf
2.	https://www.nist.gov/system/files/documents/srm/NIST-SRM-RM-Articlefinal.pdf
3.	https://www.researchgate.net/publication/319587859_Computer-Aided_Metrology-CAM

	RSE OUTCOMES: upletion of the course the student will be able to	Bloom's Taxonomy Mapped
CO1	Explain the importance of measurements in engineering and the factors affecting measurements and to compute measurement uncertainty	Understand
CO2	Apply the working principle and the applications of linear and angular measuring instruments	Apply
CO3	Interpret of various tolerance symbols.	Apply
CO4	Apply the SQC methods in manufacturing.	Apply
CO5	Apply the advances in measurements for quality control in manufacturing industries.	Apply

COURS	E AR	TICU	LATI	ON M	<u>IATRI</u>	<u>IX</u>									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	0	0	0	0	0	0	2	1	2	0	0	0	2	1	0
CO2	0	0	0	0	0	0	3	1	2	0	0	0	1	2	0
CO3	0	0	0	0	0	0	2	1	0	0	0	0	2	1	0
CO4	0	0	0	3	0	0	2	0	1	0	0	0	1	2	0
CO5	0	0	0	2	0	0	0	3	1	0	0	0	2	1	0
Avg	0.0	0.0	0.0	1.0	0.0	0.0	1.8	1.2	1.2	0.0	0.0	0.0	1.6	1.4	0.0
			3/2	/1 – in	dicates	stren	gth of c	correlat	ion (3	– high, 2	- mediur	n, 1- low)		

22M	IE504	DYNAMICS OF MACHINERY			SEME	STER '	V
PRE	REQUI	SITES	Category	PC	Cr	edit	3
				L	Т	P	TH
Engin	neering M	lechanics, Kinematics of Machinery, Strength of Materials	Hours/Week	3	0	0	3
COU	RSE OI	BJECTIVES:	1			•	
1.	To impa	art students with the knowledge about motion, masses and force	s in machines and t	he Princ	iple of	Virtual V	Work
2.	To facil	litate students to understand the concept of balancing of rotating	and reciprocating i	nasses			
3.	To teacl	h concepts of free vibration analyses of one and two degree-of-f	Freedom rigid body	systems			
4.		ch concepts of forced vibrations analyses of rigid body systemen of vibration and its effects	tems and to give	awarene	ess to s	tudents	on th
5.	To learn	n about the concept of various types of governors					
UN	ITI	FORCE ANALYSIS		9	0	0	9
Static Princi fluctu requir	iple – Ine lation of e	nalysis, Free body diagrams, Conditions of two, three and four ertia force analysis in reciprocating engines – Crank shaft torce energy of reciprocating engine mechanisms, Coefficient of fluctures.	que. Flywheels – T	Turning and spee	momen ed, Weig	t diagra	ms an
Static Princi fluctu requir UN	iple – Inelation of each	ertia force analysis in reciprocating engines - Crank shaft torce	que. Flywheels – Tetuation of energy a	Turning and spee	momen ed, Weig	t diagra	ms an ywhee
Static Princi fluctu requir UN Static Engin	iple – Inelation of each	ertia force analysis in reciprocating engines – Crank shaft torce energy of reciprocating engine mechanisms, Coefficient of fluctures and the state of the state	que. Flywheels – Tetuation of energy a	Turning and spee	momen ed, Weig	t diagra	ms an ywhee
Static Princi fluctu requir UN Static Engin UNI Basic freque Types Natura	iple – Inelation of ered. IT II and dynates - Partiti IT III features ency by east of damperal frequent	BALANCING amic balancing - Balancing of rotating masses - Balancing a stal balancing in locomotive Engines - Balancing linkages - balancing of vibratory systems - Types - Single degree of freedom systems greening method, Dunkerly's method - Critical speed - Damped bing - Free vibration with viscous damping, Critically damped syncy of two and three rotor systems.	que. Flywheels – Tetuation of energy a single cylinder Enginering machines stem – Transverse free vibration of si	y vibratic ingle de syste	momen ed, Weiş of the lancing of the gree freem. Tors	diagrament	ywhee 9 ylinde 9 Natura ystem
Static Princi fluctu requir UN Static Engin UNI Basic freque Types Natura	iple – Inelation of eation of eat. IT II and dynates - Partition IT III features ency by eas of damp	BALANCING amic balancing - Balancing of rotating masses - Balancing a stal balancing in locomotive Engines - Balancing linkages - balancing of vibratory systems - Types - Single degree of freedom systems yenergy method, Dunkerly's method - Critical speed - Damped bing - Free vibration with viscous damping, Critically damped systems - Types - Single degree of freedom systems - Types	que. Flywheels – Tetuation of energy a single cylinder Enginering machines stem – Transverse free vibration of si	y vibratic ingle de	momen ad, Weight of the desired of t	t diagrament diagrament diagrams of the diagram of the d	9 ylinde
Static Princi fluctu requir UN Static Engin UNI Basic freque Types Natura UNI Respo	iple – Inelation of electron o	BALANCING amic balancing - Balancing of rotating masses - Balancing a stal balancing in locomotive Engines - Balancing linkages - balancing of vibratory systems - Types - Single degree of freedom systems greening method, Dunkerly's method - Critical speed - Damped bing - Free vibration with viscous damping, Critically damped syncy of two and three rotor systems.	que. Flywheels – Tetuation of energy a ingle cylinder Engineing machines stem – Transverse free vibration of signification of significant properties.	y vibratic ingle de syste	on of begree frem. Tors	t diagrament diagrament diagrams – Multi-communication of the communication of the communicat	ywheen yylinde 9 Naturaystem
Static Princi fluctu requir UN Static Engin UNI Basic freque Types Natura UNI Respo	iple – Inelation of electron o	BALANCING amic balancing - Balancing of rotating masses - Balancing a stal balancing in locomotive Engines - Balancing linkages - balancing in locomotive Engines - Balancing linkages - balancing with reference of freedom systems - Types - Single degree of freedom systems - Free vibration with viscous damping, Critically damped syncy of two and three rotor systems. FORCED VIBRATION Deriodic Force - Harmonic force - Force caused by unbalance energy of reciprocating engines - Crank shaft torce energy of fluorest control of the control of th	que. Flywheels – Tetuation of energy a ingle cylinder Engineing machines stem – Transverse free vibration of signification of significant properties.	y vibratic ingle de syste	on of begree frem. Tors	t diagrament diagrament diagrams – Multi-communication of the communication of the communicat	ywheen yylinde 9 Naturaystem ystem 9
Static Princi fluctu requir UN Static Engin UNI Basic freque Types Natura UNI Respo Magn UN Gover	iple – Inelation of electron o	BALANCING amic balancing - Balancing of rotating masses - Balancing a stal balancing in locomotive Engines - Balancing linkages - balancing of vibratory systems - Types - Single degree of freedom systems yearery method, Dunkerly's method - Critical speed - Damped bing - Free vibration with viscous damping, Critically damped syncy of two and three rotor systems. FORCED VIBRATION Deriodic Force - Harmonic force - Force caused by unbalance factor - Vibration isolation and transmissibility.	que. Flywheels – Tetuation of energy a ingle cylinder Engineing machines stem – Transverse free vibration of si ystem, Under damp	y vibration of the desired system 9 on - Lo 9	on of begree freem. Tors	t diagrament diagramen	ywhee 9 ylinde 9 Natura ystem ystems 9

Text	Books:
1.	Design of Machinery, Fourth Edition, by R.L. Norton, McGraw Hill, 2007
2.	Mechanical Vibration, V.P.Singh, Dhanpatrai, Delhi
Refe	rence Books:
1.	Ballaney, P.L., "Theory of Machines and Mechanisms", Khanna Publishers, New Delhi, 2002.
2.	Shigley, J.E. and Uicker, J.J., "Theory of Machines and Mechanisms", TMH ND, 1998.
3.	Amithabha Ghosh, and Ashok Kumar Malik., "Theory of Mechanisms and Machines", 2nd Ed., Affiliated East and West Press Limited, 1998.
4.	Prof.Nakara, IIT-Delhi Reference Books
E-Re	eferences:

1	1.	www.university.youth4work.com/IIT Kharagpur Indian-Institute-of-Technology/study/1653-dynamics-of-ebook machinery-	
2	2.	http://nptel.ac.in/courses/112104114/	

	On completion of the course the student will be able to					
CO1	Apply basic principles of mechanisms in mechanical system	Apply				
CO2	Familiarize the static and dynamic analysis of simple mechanisms	Understand				
CO3	Analyze the mechanical systems subjected to free vibration	Analyze				
CO4	Analyze mechanical systems subjected to forced vibration	Analyze				
CO5	Analyze the various types of governors and its speed control mechanism	Analyze				

OURSE A	RTIC	ULA	ΓΙΟΝ	MAT	RIX										
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	3	3	1	0	0	0	0	1	0	3	2	1	2
CO2	2	2	3	2	1	0	0	0	0	1	0	3	2	1	2
CO3	2	2	3	2	0	0	0	0	0	1	0	3	2	1	2
CO4	2	2	3	2	1	0	0	0	0	1	0	3	2	1	2
CO5	1	2	3	2	0	0	0	0	0	1	0	3	2	1	1
Avg	1.8	2.0	3.0	2.2	1.2	0.0	0.0	0.0	0.0	1.0	0.0	3.0	2.0	1.0	1.8
	•		3/2/1	– ind	icates	streng	th of c	orrelat	ion (3	– high, 2	- mediu	m, 1- lov	v)	•	•

22MF	E 505	INSTRUMENTATION AND CONTROL SYSTEM	M		SEMES	STER V	,
PRER	REQUIS	SITE:	Category	PC	Cre	edit	3
Basics	of measu		ours/Week	L	0	P	TH
		H	ours/ week	3	0	0	3
Cours	se Objec	ctives:					
1.	To mal	ke the students aware of the modern sensors and advanced measurem	nent systems				
2.	To sele	ect the correct system of instrumentation and sensing as per the industrial	strial requireme	ents			
3.	To und	erstand statistical signal processing					
4.	To pro	vide adequate knowledge in the time response of systems and steady	state error ana	llysis			
5.	To intr	oduce stability analysis and design of compensators					
UN	IT I	GENERAL CONCEPTS OF MEASUREMEN	Т	9	0	0	9
displac		ystems- Sensors and transducers- Classifications of Transducers -Sosition and proximity; velocity, motion, force, fluid pressure, liquinsors	•				
UN	IT II	SIGNAL CONDITIONING		9	0	0	9
Amplit	fier chara	acteristics, wheat's stone bridge- Instrumentation sensor – integration	on and differe	ntiation -	samplin	ng, A/D a	and D/A
conver		ppers, voltage to time conversion, voltage to freq. Conversion concep			r		
		<u> </u>			0	0	9
UNI Real-ti timers,	rsion, cho IT III me interf DMA,	ppers, voltage to time conversion, voltage to freq. Conversion conce	ept and method verview of I/O nirements, -Ge	s. 9 process, neral cor	0 Digital I	0 I/O, coun	ters and
UNI Real-ti timers, and mu	rsion, cho IT III me interf DMA,	DATA ACQUISITION Facing – Introduction - Elements of data acquisition and control - Ox Software and hardware installation, Data acquisition interface requ	ept and method verview of I/O nirements, -Ge	s. 9 process, neral cor	0 Digital I	0 I/O, coun	ters and
UNI Real-ti timers, and mu UNI Respon	me interface DMA, Sultichann	DATA ACQUISITION Facing – Introduction - Elements of data acquisition and control - Ox Software and hardware installation, Data acquisition interface requel data acquisition – Data Logging – Data conversion – Introduction	verview of I/O nirements, -Ge to Digital Tran	process, neral cornsmission 9 m accord	O Digital Infiguration system. O ding to t	0 (O, coun on-single	ters and channel
UNI Real-ti timers, and mu UNI Respor	me interface DMA, Sultichann	DATA ACQUISITION Facing – Introduction - Elements of data acquisition and control - Over Software and hardware installation, Data acquisition interface required data acquisition – Data Logging – Data conversion – Introduction – TIME RESPONSE ANALYSIS Systems for different time-based input, Classification of feedback	verview of I/O nirements, -Ge to Digital Tran	process, neral cornsmission 9 m accord	O Digital Infiguration system. O ding to t	0 (O, coun on-single	ters and channel
UNI Real-ti timers, and mu UNI Respor coeffic UN	me interface DMA, Sultichanner IT IV mse of systems- ge IT V ency response of systems	DATA ACQUISITION Facing – Introduction - Elements of data acquisition and control - Oversion concepts of data acquisition and control - Oversion elements acquisition interface required data acquisition – Data Logging – Data conversion – Introduction — TIME RESPONSE ANALYSIS Systems for different time-based input, Classification of feedback meralized steady state errors steady state errors due to impulse, step, in the conversion of the con	verview of I/O nirements, -Ge to Digital Tran control system ramp and paral	process, neral cornsmission maccore bolic input poop respect	O Digital Infiguration a system. O ding to tats. O Donse-Corr	0 I/O, count on-single 0 Type; state 0 Trelation	ters and channel 9 ic error 9 between
UNI Real-ti timers, and mu UNI Respor coeffic UN	me interface DMA, Sultichanner IT IV mse of systems- ge IT V ency response of systems	DATA ACQUISITION Facing – Introduction - Elements of data acquisition and control - Oversion concepts of data acquisition and control - Oversion elements acquisition - Data Logging – Data conversion – Introduction - TIME RESPONSE ANALYSIS For different time-based input, Classification of feedback and state errors steady state errors due to impulse, step, and the state of the st	verview of I/O nirements, -Ge to Digital Tran control system ramp and paral	process, neral cornsmission maccore bolic input poop respect	O Digital Infiguration a system. O ding to tats. O Donse-Correct responses	0 I/O, count on-single 0 Type; state 0 Trelation	ters and channel 9 ic error 9 between lysis
Real-ti timers, and mu UNI Respor coeffic UNI Freque frequer	me interface DMA, Sultichanne IT IV nse of systems- ge IT V ency response of systems	DATA ACQUISITION Facing – Introduction - Elements of data acquisition and control - Oversion concepts of data acquisition and control - Oversion elements acquisition - Data Logging – Data conversion – Introduction - TIME RESPONSE ANALYSIS For different time-based input, Classification of feedback and state errors steady state errors due to impulse, step, and the state of the st	verview of I/O nirements, -Ge to Digital Tran control system ramp and paral	process, neral cornsmission maccore bolic input poop respect	O Digital Infiguration a system. O ding to tats. O Donse-Correct responses	0 I/O, count on-single 0 Type; state 0 Trelation onse-Ana	ters and channel 9 ic error 9 between lysis
UNI Real-ti timers, and mu UNI Respor coeffic UN Freque frequer	me interface DMA, Sultichanner IT IV mse of systems- get IT V ency responcy doma Books:	DATA ACQUISITION Facing – Introduction - Elements of data acquisition and control - Oversion concepts of data acquisition and control - Oversion elements acquisition - Data Logging – Data conversion – Introduction - TIME RESPONSE ANALYSIS For different time-based input, Classification of feedback and state errors steady state errors due to impulse, step, and the state of the st	verview of I/O nirements, -Ge to Digital Tran control systemand paral conse, open locompensation of	process, neral cornsmission maccord bolic input poop respon frequent	O Digital Infiguration a system. O ding to tats. O Donse-Correct responses	0 I/O, count on-single 0 Type; state 0 Trelation onse-Ana	ters and channel 9 ic error 9 between lysis
Real-ti timers, and mu UNI Respor coeffic UN Freque frequer Text I 1.	me interface DMA, Sultichanner IT IV Inse of sycients- ge IT V Incy responcy doma Books: John G.	DATA ACQUISITION Facing – Introduction - Elements of data acquisition and control - Oversoftware and hardware installation, Data acquisition interface required data acquisition – Data Logging – Data conversion – Introduction – TIME RESPONSE ANALYSIS Systems for different time-based input, Classification of feedback neralized steady state errors steady state errors due to impulse, step, response—Bode plot –Polar plot –Determination of closed loop response and time domain specifications-Effect of Lag, lead and lag-lead control of the contro	verview of I/O nirements, -Ge to Digital Tran control system ramp and paral conse, open lo compensation of	process, neral cornsmission maccord bolic input pop respon frequent	O Digital Infiguration a system. O ding to tats. O Donse-Corner responses	0 I/O, coun on-single 0 Type; stat 0 Trelation onse-Ana onse-Ana onse-Ana	ters and channel 9 ic error 9 between lysis
Real-ti timers, and mu UNI Respor coeffic UN Freque frequer Text I 1. 2.	me interface DMA, Sultichanner IT IV Inse of sycients- ge IT V Incy responcy doma Books: John G.	DATA ACQUISITION Facing – Introduction - Elements of data acquisition and control - Ox Software and hardware installation, Data acquisition interface requel data acquisition – Data Logging – Data conversion – Introduction TIME RESPONSE ANALYSIS Vistems for different time-based input, Classification of feedback neralized steady state errors steady state errors due to impulse, step, response—Bode plot –Polar plot –Determination of closed loop response and time domain specifications-Effect of Lag, lead and lag-lead companies. Webster, "Measurement, Instrumentation, and Sensors Handbook", C.D.V.S., Transducers and Instrumentation, 2 nd Edition, Prentice Hall of the control of the contro	verview of I/O nirements, -Ge to Digital Tran control system ramp and paral conse, open lo compensation of	process, neral cornsmission maccord bolic input pop respon frequent	O Digital Infiguration a system. O ding to tats. O Donse-Corner responses	0 I/O, coun on-single 0 Type; stat 0 Trelation onse-Ana onse-Ana onse-Ana	ters and channel 9 ic error 9 between lysis
Real-ti timers, and mu UNI Respon coeffic UN Freque frequer Text I 1. 2. Refere	me interface DMA, Sultichanner IT IV mes of systems o	DATA ACQUISITION Facing – Introduction - Elements of data acquisition and control - Ox Software and hardware installation, Data acquisition interface requel data acquisition – Data Logging – Data conversion – Introduction TIME RESPONSE ANALYSIS Vistems for different time-based input, Classification of feedback neralized steady state errors steady state errors due to impulse, step, response—Bode plot –Polar plot –Determination of closed loop response and time domain specifications-Effect of Lag, lead and lag-lead companies. Webster, "Measurement, Instrumentation, and Sensors Handbook", C.D.V.S., Transducers and Instrumentation, 2 nd Edition, Prentice Hall of the control of the contro	verview of I/O nirements, -Ge to Digital Tran control system ramp and paral conse, open lo compensation of	process, neral cornsmission maccord bolic input pop respon frequent	O Digital Infiguration a system. O ding to tats. O Donse-Corner responses	0 I/O, coun on-single 0 Type; stat 0 Trelation onse-Ana onse-Ana onse-Ana	ters and channel 9 ic error 9 between lysis
Real-ti timers, and mu UNI Respon coeffic UN Freque frequer 1. 2. Reference 1.	me interface DMA, Sultichann IT IV mese of systems of	DATA ACQUISITION Facing – Introduction - Elements of data acquisition and control - Ox Software and hardware installation, Data acquisition interface requeled data acquisition – Data Logging – Data conversion – Introduction — TIME RESPONSE ANALYSIS Systems for different time-based input, Classification of feedback neralized steady state errors steady state errors due to impulse, step, respectively. TREQUENCY DOMAIN ANALYSIS Sonse—Bode plot —Polar plot —Determination of closed loop respection and time domain specifications-Effect of Lag, lead and lag-lead composes. Webster, "Measurement, Instrumentation, and Sensors Handbook", C. D.V.S., Transducers and Instrumentation, 2 nd Edition, Prentice Hall cooks:	verview of I/O nirements, -Ge to Digital Tran control system ramp and paral conse, open locompensation of CRC Press. 199 of India Pvt. L	process, neral cornsmission maccord bolic input poop respon frequent 98. td., New	Digital Infiguration a system. Oling to tats. Omse-Corner respondency respon	0 I/O, coun on-single 0 Type; stat 0 Trelation onse-Ana onse-Ana onse-Ana	ters and channel 9 ic error 9 between lysis

	COURSE OUTCOMES: On completion of the course the student will be able to					
CO1	Apply common measurement characteristics and terms to select sensors to meet control and monitoring requirements	Apply				
CO2	Design, build and test sensor interface circuits including amplifiers to process the measured variable into a useful signal in the presence of noise and environmental variations	Create				
соз	Select and design appropriate signal processing to its instrumentation and control and their measurement	Create				
CO4	Understand and apply basic science, theory control theory and apply them to control engineering problems.	Understand				
CO5	Analyse the performance of systems and components through the use of analytical techniques	Analyze				

COURSE	ART	ICUL	ATIO	N MA	TRIX										
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	1	2	2	3	0	0	0	1	0	0	3	1	0	0
CO2	0	0	2	2	0	0	0	0	0	0	0	0	2	1	0
CO3	1	2	2	2	2	2	1	0	2	0	1	1	0	2	1
CO4	0	1	2	3	1	0	2	0	0	0	0	2	0	0	0
CO5	0	2	3	3	1	0	0	1	2	1	0	3	0	0	2
Avg	0.4	1.2	2.2	2.4	1.4	0.4	0.6	0.2	1.0	0.2	0.2	1.8	0.6	0.6	0.6
			3/2	2/1 — iı	ndicate	s stren	gth of	correla	tion (3	– high, 2	2- mediu	m, 1- low	·)		

	IDEATION SPRINTS			SEMES	STER V	V
PRE-REQU	ISITE:	Category	EE	Cro	edit	1
		Hours/Week	L	Т	P	TH
		0	0	2	2	
Course Obje	ctives:	-				
1. To offer	a systematic and structured process to hack a solution using	available tools & resou	rces			
	ify the challenge/opportunity, derive insights from the custor I feasibility of the solution	mer/user interviews, &	build a so	olution a	nd valid	late the
3. To build	the PoC for proposed solution & pitch to user/customer for	validation.				
UNIT I	INNOVATION 101		0	0	6	6
Tools and ted	PROBLEM VALIDATION & CUSTOMER chiques of the managed innovation process (iTOOLS		0	0	6	6
	ric design thinking and validate the problem scenario, its ht buyer beneficiary/Customer - rigorous Gap analysis of the	s significance, severity	, and in	cidence	- Disco	over &
	ric design thinking and validate the problem scenario, its	s significance, severity e existing solution - Ad	, and in	cidence	- Disco	over &
identify the rig	ric design thinking and validate the problem scenario, its ht buyer beneficiary/Customer - rigorous Gap analysis of the DESIGNING & CRAFTING VALUE PRODUCTION OF STREET OF STREE	s significance, severity e existing solution - Ad OPOSITION	option ba	cidence rriers of 0	- Disco	over & ations.
UNIT III Understand Cu	ric design thinking and validate the problem scenario, its ht buyer beneficiary/Customer - rigorous Gap analysis of the DESIGNING & CRAFTING VALUE PRODUCTION OF STREET OF STREE	s significance, severity e existing solution - Ad POSITION Tine & quantify Value I	option ba	cidence rriers of 0	- Disco	over & ations.
UNIT III Understand Cuvalue propositi UNIT IV Solution: Con	ric design thinking and validate the problem scenario, its ht buyer beneficiary/Customer - rigorous Gap analysis of the DESIGNING & CRAFTING VALUE PROstomer Jobs, Pains & gains - Design Product/Service - Defon. MUP SOLUTION CONCEPT EXPLORATION	s significance, severity existing solution - Ad DPOSITION Tine & quantify Value ION & DESIGN Tility, Usability, and	option ba	oridence of the control of the contr	- Disco the solution of the so	over & ations. 6 pelling
UNIT III Understand Cuvalue propositi UNIT IV Solution: Con	DESIGNING & CRAFTING VALUE PRODUCTION CONCEPT EXPLORATION MUP SOLUTION CONCEPT EXPLORATION Cept Generation, Concept Assessment, Solution, Capab	S significance, severity existing solution - Ad DPOSITION Tine & quantify Value IN TON & DESIGN Tility, Usability, and Intion	option ba	oridence of the control of the contr	- Disco the solution of the so	6 pellin
UNIT IV Solution: Con Technology Bl UNIT V Proof-of-Conc	DESIGNING & CRAFTING VALUE PRODUCTION CONCEPT EXPLORATION CEPT Generation, Concept Assessment, Solution, Capabook Diagrams- Bill of Materials Generation - BoM Optimiza	s significance, severity existing solution - AdopPOSITION Tine & quantify Value In the AdopPOSITION Tine & Quantif	option bar option optio	oridence curriers of the control of	- Disco the solution of the so	over & ations. 6 pelling 6 gn and

Tex	t Books:
1.	Tim Brown, Change by Design:How design thinking transforms organizations and inspires innovation – HarperCollins e-books, 2009
2.	Alexander Osterwalder, Value Proposition Design: How to Create Products and Services Customers Want (Strategyzer) - John Wiley & Sons, 2014
3.	Ulrich Karl and Eppinger Steven D, Product Design and Development - McGraw Hill, 5th edition, 2020
4.	Blank Steve, Four Steps to Epiphany: Successful strategies for products that win, KS Ranch, 5th edition, 2013
Ref	erence Books:
1.	Everything you need about value proposition: https://blog.forgeforward.in/everything-you-need-to-know-about-value-proposition-7247493c940c
2.	Test your Value Proposition:http://businessmodelalchemist.com/2012/09/test-your-value-proposition-supercharge-lean-startup-and-custdev-principles.html
3.	Valuation Risk versus Validation Risk in Product Innovations:https://blog.forgeforward.in/valuation-risk-versus-validation-risk-in-product-innovations-49f253ca8624
4.	User Guide for Product Innovation Rubric:https://blog.forgeforward.in/user-guide-for-product-innovation-rubric-

	857181b253dd				
5.	Innovation Risk Diagnostic - Product Innovation Rubric:https://blog.forgeforward.in/product-innadf5ebdfd356	ovation-rubric-			
6.	Evaluating Product Innovations - proof, potential, & progress:https://blog.forgeforward.in/evaluating-produce8178e58b86e	ct-innovations-			
	URSE OUTCOMES: completion of the course, the students will be able to:	Bloom's Taxonomy Mapped			
COI	Apply a scientific method to understand the inherent risks of product innovation	Apply			
CO2	Apply innovation tools & techniques to validate the problem scenario and to assess the market potential of product innovation;	Apply			
CO3 Design solution concept based on the proposed value by exploring various alternate solutions to achieve value-price fit;					
	Demonstrate technical skills by applying technology to build and demonstrate proof of concept for the solution proposed; Development				

Develop

Develop skills to articulate the solution concept into a proposal for grants.

CO5

22MC301	INDIAN CONSTITUTION			SEME	STER V	V
PREREQUI	SITE:	Category	MC	Cr	edit	0
		Hours/Week	L	0	TH	
		Hours/ week	3	0	0	3
COURSE O	BJECTIVES:					
1. Learn	the salient features of the Indian Constitution.					
2. To stu	dy the List the Fundamental Rights and Fundamental Duties.					
3. To stu	dy the Present a systematic analysis of all dimensions of Indian	Political System.				
4. To stu	dy the Understand the power and functions of the Parliament, t	he Legislature and	the Judi	ciary.		
UNIT I			9	0	0	9
Union and its	Territory – Citizenship–Fundamental Rights–Directive Principl	es of State Policy-	-Fundam	ental Du	ties	
UNIT II			9	0	0	9
The Union-Th	e States-The Union Territories-The Panchayats-The Municipa	alities	l			
UNIT III			9	0	0	9
	ive Societies—The scheduled and Tribal Areas—Relations bet Suits—Trade and Commerce within the territory of India	ween the Union a	and the S	States–Fi	inance, l	Property,
UNIT IV			9	0	0	9
Services under	the Union, the States – Tribunals – Elections– Special Provision	ons –Relating to ce	ertain Cla	isses	•	•
UNIT V			9	0	0	9
Languages-En	nergency Provisions – Miscellaneous–Amendment of the Const	titution	1			
				Tota	al = 45	Periods

Refere	Reference Books:							
1.	. Subhash C. Kashyap, Our Constitution, National Book Trust, 2017							
2.	Durga Das Basu, Introduction to the Constitution of India, Lexis Nexis, 2015							
3.	Granville Austin, The Indian Constitution: Cornerstone of a Nation, Oxford University Press, 1999.							
4.	M.V. Pylee, Constitutional History of India, S.Chand publishing, 2010							

	COURSE OUTCOMES: On completion of the course the student will be able to						
CO1	Understand the emergence and evolution of the Indian Constitution	Understand					
CO2	Explain the key concepts of Indian Political System	Understand					
CO3	Describe the role of constitution in a democratic society.	Understand					
CO4	Present the structure and functions of the Central and State Governments, the Legislature and the Judiciary	Apply					

22ME506	DYNAMICS AND METROLOGY LABORA	DYNAMICS AND METROLOGY LABORATORY										
PREREQUIS	REQUISITE: Category PC C											
		Hours/Week	L	Т	P	ТН						
		Hours/ Week	0	0	3	3						

Course Objectives:

- 1. To be familiar with different measuring equipment.
- 2. Use of the instruments in industry for quality inspection
- 3. To know the need of accuracy in industry To know about balancing of rotating system
- 4. To be familiar with different measuring equipment.

LIST OF EXPERIMENTS

- 1. Governors- Determination of sensitivity, effort, etc.for Watt, Porter, Proell, Hartnell governors
- 2. Cam- Study of jump phenomenon and drawing profile of the cam.
- 3. Motorized Gyroscope-Verification of laws –Determination of gyroscopic couple.
- 4. Whirling of shaft-Determination of critical speed of shaft with concentrated loads.
- 5. Determination of moment of inertia by oscillation method for connecting rod and flywheel.
- 6. Vibrating system- Spring mass system-Determination of damping co-efficient of single degree of freedom system.
- 7. Determination of transmissibility ratio-vibrating table.
- 8. Determination of torsional frequencies for compound pendulum and fly wheel system with Lumped Moment of inertia.
- 9. Transverse vibration of Beam. Determination of natural frequency and deflection of beam.
- 10. Calibration of Vernier / Micrometer / Dial Gauge
- 11. Checking Dimensions of part using lip gauges
- 12. Measurements of Gear Tooth Dimensions.
- 13. Measurement of Taper Angle using sine bar/tool makers microscope.
- 14. Measurement of thread parameters
- 15. Checking the limits of dimensional tolerances using comparators (Mechanical/Pneumatic/Electrical)

	RSE OUTCOMES: completion of the course the student will be able to	Bloom's Taxonomy Mapped
CO1	Handle different measurement tools	Understand
CO2	Perform measurements with accuracy.	Evaluate
CO3	Avoid errors in measurement	Analyze
CO4	Understand balancing of equipment	Understand

COUR	SE AR'	TICUL	ATION	MAT	RIX										
COs/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	3	2	2	3	0	0	0	0	0	0	0	3	1	2
CO2	0	2	0	3	1	1	0	0	0	0	0	0	1	2	3
CO3	3	1	0	0	0	2	0	0	0	0	0	0	2	3	1
CO4	2	3	0	1	3	1	0	0	0	0	0	0	3	2	1
Avg	1.5	2	0.5	1.2	1.7	1	0.0	0.0	0.0	0.0	0.0	0.0	2.2	2.0	1.7
			3/2	/1 – indi	icates st	rength o	of correl	ation (3	– high,	2- medi	um, 1- le	ow)			

	EN502	PLACEMENT AND CAREER TRAINING LAI	BORATORY	S	SEMES	STER Y	V					
PRF	E-REQUIS	SITE:	Category	HS	 							
1. B	asic knowle	dge in reading skill and writing skill	TT /XX/1-	L	T	P	TH					
2. Ba	asic ability i	n listening skill and speaking skill	Hours/Week	0	0	4	4					
Cou	rse Object	tives:										
1.	To develo	p the students' confidence and help them to attend interviews	successfully									
2.	To express	s opinions, illustrate with examples and conclude in group disc	cussions									
3.	To acquire	e knowledge to write error free letters and prepare reports										
4.	To enhance	ee the employability and soft skills of students										
U	NIT I	WRITING SKILLS		0	0	10	10					
Lette	er of invitati	on, Resume and cover letter, Job application, E-mail writing, I	Report writing, progr	ess in pr	oject w	ork						
U	NIT II	SPEAKING SKILLS		0	0	10	10					
Emp		CAREER SKILLS nd career skills, Self-introduction, introducing oneself to the tte, Dress code, Body language, Attending job interviews	e audience, introduc	ing the t	opic, I	10 nterview	10 skills					
	· io ouique	HE. DIESS COUE. DOUY MIRHARE. AHEHUHIR IOD HHELVIEWS										
UI	NIT IV	VERBAL ABILITIES		0	0	10	10					
		, , , ,	g Jumbled sentences			10	10					
Erro		VERBAL ABILITIES	g Jumbled sentences			10	10					
Error U Serie	r Spotting, I	VERBAL ABILITIES Listening Comprehension, reading comprehension, Rearranging		, Vocabu	o octional	5 Sense, l	5 Logica					
Error U. Serie reaso	r Spotting, I NIT V es completion oning	VERBAL ABILITIES Listening Comprehension, reading comprehension, Rearranging REASONING ABILITIES In, Analogy, Classification, Coding-Decoding, Blood relations		, Vocabu	o octional	5	5 Logica					
Erroi U. Serie reaso	NIT V es completion oning erence Boo	VERBAL ABILITIES Listening Comprehension, reading comprehension, Rearranging REASONING ABILITIES Inn, Analogy, Classification, Coding-Decoding, Blood relations Oks:	, Seating Arrangeme	, Vocabu	o octional	5 Sense, l	5 Logica					
Error U Serie reaso	NIT V es completion oning erence Boo Campus I	VERBAL ABILITIES Listening Comprehension, reading comprehension, Rearranging REASONING ABILITIES In, Analogy, Classification, Coding-Decoding, Blood relations Oks: Recruitment Complete Reference, Praxis Groups (5th edition),	, Seating Arrangeme	, Vocabu 0 ents, Dire	o octional	5 Sense, l	5 Logica					
Error U. Serie reaso Refe	r Spotting, I NIT V es completion oning erence Boo Campus I John Seel	VERBAL ABILITIES Listening Comprehension, reading comprehension, Rearranging REASONING ABILITIES Inn, Analogy, Classification, Coding-Decoding, Blood relations Oks:	Hyderabad, 2017.	vocabu o ents, Dire ni, 2004.	0 ectional	5 Sense, l	5 Logica					
Error U Serie reaso Refe 1. 2. 3.	r Spotting, I NIT V es completion oning erence Boo Campus I John Seel R.S. Agg	VERBAL ABILITIES Listening Comprehension, reading comprehension, Rearranging REASONING ABILITIES In, Analogy, Classification, Coding-Decoding, Blood relations Oks: Recruitment Complete Reference, Praxis Groups (5th edition), ly, The Oxford Guide to Writing and Speaking, Oxford Universarwal. A Modern Approach to Verbal & Non-Verbal Reasoning	Hyderabad, 2017.	vocabu o ents, Dire ni, 2004.	0 ectional	5 Sense, l	5 Logica					
Error U Serie reaso Refe 1. 2. 3.	r Spotting, I NIT V es completion oning crence Boo Campus I John Seel R.S. Agg	VERBAL ABILITIES Listening Comprehension, reading comprehension, Rearranging REASONING ABILITIES In, Analogy, Classification, Coding-Decoding, Blood relations Oks: Recruitment Complete Reference, Praxis Groups (5th edition), ly, The Oxford Guide to Writing and Speaking, Oxford Universarwal. A Modern Approach to Verbal & Non-Verbal Reasoning	Hyderabad, 2017.	vocabu o ents, Dire ni, 2004.	0 ectional	5 Sense, l	5 Logica					

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:						
CO1	Participate in group discussion and interview confidently	Evaluate					
CO2	Develop adequate soft skills and career skills required for the workplace	Create					
СОЗ	Make effective presentations on given topics	Create					
CO4	Apply their verbal ability and reasoning ability in campus interviews	Apply					

COURSE ARTICULATION MATRIX CO/ PO11 PO1 PO2 PO3 **PO4 PO5** PO6 **PO7 PO8** PO9 **PO10 PO12** PSO1 PSO2 PSO3 **POs** CO1 CO₂ **CO3 CO4** 1.75 1.5 3.0 1.0 1.5 Avg

3/2/1 – indicates strength of correlation (3 – High, 2 – Medium, 1 – Low)

22ME5	507	HEAT TRANSFER AND REFRIGERATION LA	LABORATORY SEMESTER V									
PRERI	EQUIS	ITES:	Category	PC	Credit		1.5					
1.Basic	knowled	ge about the modes of heat transfer	Hours/Week	L	L T		С					
2.Conce	ept of psy	ychrometry and refrigeration and air conditioning systems	Tiours/ week	0	0	3	1.5					
Course	e Objec	tives:										
1.	Applyi	ng the concepts and laws of conduction heat transfer in real e	quipment									

Applying the concepts and laws of conduction heat transfer in real equipment
 Practicing to estimate the heat transfer coefficient values of various fluids.
 Experimenting and analyzing the heat transfer phenomena in boiling and condensation heat exchangers
 Determining the radiation heat transfer parameters for black and grey surfaces and calibration of thermocouples
 Studying the performance analysis of the refrigeration and air-conditioning systems and cooling towers.

LIST OF EXPERIMENTS:

- 1. Thermal conductivity measurement of pipe insulation using lagged pipe apparatus.
- 2. Determination of thermal conductivity of a composite wall, insulating powder.
- 3. Determination of heat transfer coefficient of air under natural convection and forced convection.
- 4. Heat transfer from pin-fin under forced convection heat transfer.
- 5. Determination of heat flux under pool boiling and flow boiling in various regimes.
- 6. Determination of heat transfer coefficient in film-wise and drop-wise condensation.
- 7. Determination of friction factor, heat transfer coefficient of cold/hot fluids and effectiveness oftube-in-tube heat exchanger.
- 8. Determination of Stefan Boltzmann constant.
- 9. Determination of emissivity of a grey surface.
- 10. Calibration of thermocouples / RTDs at standard reference temperatures.
- 11. Determination of Coefficient of Performance of a vapor compression refrigeration system
- 12. Determination of Coefficient of Performance of an Air-Conditioning system.
- 13. Determination of effectiveness of a cooling tower.

Total = 45 Periods

	RSE OUTCOMES: upletion of the course the student will be able to	Bloom's Taxonomy Mapped
CO1	Calculate the thermal conductivity of various conducting and non-conducting materials	Evaluate
CO2	Estimate the heat transfer coefficient in free and forced convections for various geometries.	Evaluate
CO3	Evaluate the heat flux and the heat transfer coefficient in various types of heat exchangers	Evaluate
CO4	Obtain the radiation parameters such as emissivity, wave length and surface temperatures	Analyze
CO5	Test the performance of the refrigeration and air-conditioning systems and cooling towers.	Analyze

COURS	E AR	TICU	LATI	ON M	IATR	<u>IX</u>									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	3	0	2	0	0	0	0	0	0	0	0	3	1	2
CO2	1	2	1	1	0	0	0	0	0	0	0	0	2	1	1
CO3	1	3	1	0	0	0	0	0	0	0	0	0	3	0	2
CO4	1	2	1	1	0	0	0	0	0	0	0	0	2	0	1
CO5	1	2	0	1	0	0	0	0	0	0	0	0	1	1	1
Avg	1	2.4	0.6	1	0	0	0	0	0	0	0	0	2.2	0.6	1.4
		·	2/)/1 :-	dianta	a atmon	ath of	aammala	tion (2	hiah) madin	m 1 lov)		

3/2/1 – indicates strength of correlation (3 – high, 2- medium, 1- low)

22ME 601	MINI PROJECT	SEMESTER VI					
PREREQU	USITE:	Category	EE	Cre	edit	3	
		Hours/Week	L	T	P	TH	
		Hours/ Week	0	0	6	6	

Course Objectives:

- 1. Opportunity to design and develop small working models.
- 2. Develop experimental or simulation solutions to small industrial problems.
- 3. Facilitate problem identification, formulation and solution.
- 4. Work collaboratively in small groups.

The students may be grouped into groups of about 2 to 4 members per group and work under a project supervisor. The device / system / component(s) to be designed/ fabricated / investigated / analyzed may be decided in consultation with the supervisor. A project report to be submitted by the group and the fabricated model /investigation / analysis to be reviewed and evaluated continuously by a committee constituted by the head of the department / program coordinator.

FABRICATION PROJECT GUIDELINES

- a. Mechanical Assembly and Dismantling Models
- b. Day-life Usage Project
- c. New Scientific Invention
- d. Implementation of Mechanical Principle

Total = 90 Periods

COURSE OUTCOMES: On completion of the course the student will be able to							
CO1	Initiate the students to come out with innovative ideas for various applications.	Create					
CO2	Create an environment to convert the ideas into design of prototype for useful industrial, agricultural and social applications.	Create					
CO3	Familiarize the feasibility study and manage activities to complete task in specified duration.	Understand					
CO4	Assign and undertake tasks in a team as per team discussion.	Evaluate					
CO5	Do presentation and write technical reports for effective communication within and outside the team.	Create					

COURSE A	OURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	2	3	3	1	3	0	2	0	3	3	3
CO2	3	3	3	3	2	3	3	0	3	0	1	0	3	3	0
CO3	2	2	2	2	2	1	1	1	3	1	2	3	3	3	0
CO4	3	2	2	1	1	1	2	3	3	3	0	3	3	3	0
CO5	0	0	0	0	2	2	0	1	3	3	0	2	3	0	3
Avg	2.2	2.0	2.0	1.8	1.8	2.0	1.8	1.2	3.0	1.4	2.0	1.6	3.0	2.4	1.2
			3/2/1	– indic	cates si	trengtl	h of co	rrelatio	on (3 –	high, 2-	medium	, 1- low)	1		

SEMESTER - VII

22ME70	MECHATRONICS	SEMESTER VII								
PRERE(UISITE:	Category	PC	Cr	Credit					
Basics of e	ectronics and electrical engineering		L	Т	P	TH				
_	in instrumentation and sensors	3	0	0	3					
Basics of I	ydraulic and pneumatic systems		3	U	U	3				
COURSI	OBJECTIVES:									
	mpart knowledge about the elements and techniques involved in Mederstand the emerging field of automation.	chatronics system	s which	are ver	y much e	essential				
2. To a	2. To acquire adequate knowledge to model and simulate the physical systems.									
3. To 1	nderstand issues of implementation of different actuation systems in	a Mechatronics s	ystem,							
4. To §	ain practical experience in interfacing input and output devices to PI	LCs								
5. To §	ain practical experience in applying knowledge in the real word syst	ems.								
UNIT I	INTRODUCTION TO MECHATRONICS	S	9	0	0	9				
	Introduction to Mechatronic Systems- Mechatronic Products at cs -Measurement systems- Control Systems- sequential controllers.	nd their function	ning- Ad	lvanced	applica	tions in				
UNIT II	PHYSICAL SYSTEM MODELING	9	0	0	9					
	vstem Models- zero order-first order- second order-mechanical nanical systems, hydro-mechanical systems, pneumatic systems-Basi	•	-			systems,				
UNIT III	ACTUATION SYSTEMS	9	0	0	9					
Piezo actu	otors - Solenoids - Solid state switches - Stepper motors- Servo motors- Control systems - PID Controllers - Artificial intelligence in a networks and fuzzy systems.									
UNIT IV	PROGRAMMING LOGIC CONTROLLER	9	0	0	9					
	n to Programmable Logic Controllers – Basic Structure – Input / Controllers – Basic Structure – Input / Controllers – Shift registers – Master and Jump controls PLC.			_		_				
UNIT V	MECHATRONICS SYSTEMS DESIGN	9	0	0	9					
Data acqu	esigning of Mechatronics systems – Traditional and Mechatronic sition and control - Pick and place robot – automatic car park c control in automated manufacturing.									
				Tota	l = 45 I	Periods				

Text	Text Books:						
1.	Bolton, W, Mechatronics, Pearson Education, 6th Edition, 2015.						
2.	2. Ganesh S.Hegde, Mechatronics, Jones & Bartlett publishers, 1st Edition, 2010.						
Refe	Reference Books:						
1.	1. Michael B. Histand and David G. Alciatore, Introduction to Mechatronics and Measurement Systems, McGraw Hi International Editions, 3rd Edition, 2007						
2.	Bradley D. A., Dawson D., Buru N.C. and Loader A.J, Mechatronics, Chapman and Hall, 1st Edition, 1993.						

3.	Dan Necsulesu, Mechatronics, Pearson Education Asia, 1st Edition, 2002				
4.	Brian Morriss, Automated Manufacturing Systems - Actuators, Controls, Sensors and Robotics, McGraw Hill International Edition, 1995				
5.	Devadas Shetty, Richard A.Kolkm, Mechatronics system design, PWS publishing company, 2009				
E-Re	E-References:				
1.	https://onlinecourses.nptel.ac.in/noc21_me12				

COU On co	Bloom's Taxonomy Mapped	
CO1	Understand the basic elements underlying mechatronics systems and integrate them in the design of mechatronics systems.	Understand
CO2	Develop a simulation model for simple physical systems and illustrate mechatronics design process.	Analyze
СОЗ	Design, interface and understand issues of implementation of different actuation in a mechatronics system for a set of specifications.	Analyze
CO4	Interface electromechanical systems to PLCs.	Apply
CO5	Attain practical experience in applying knowledge gained in the course through a hands-on project.	Understand

COURSE	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	0	2	0	0	0	0	0	0	0	1	1	0	2
CO2	2	2	3	3	1	0	0	0	0	0	0	2	2	2	0
CO3	0	0	2	2	0	0	2	0	2	0	0	2	0	0	0
CO4	0	2	3	3	3	0	0	0	3	0	3	2	0	2	1
CO5	1	2	2	3	3	2	2	1	3	2	1	3	0	0	3
Avg	2.0	1.6	2.0	2.6	1.4	0.4	0.8	0.2	1.6	0.4	0.8	2.0	0.6	0.8	1.2
	3/2/1 – indicates strength of correlation (3 – high, 2- medium, 1- low)														

22ME70	2 FINITE ELEMENT ANALYSIS		S	EMEST	TER V	II				
PREREQU	REQUISITE: Category PC									
	ledge in mathematics with differentiation, integration, matrix	L	Т	P	TH					
operations as Basic knowl	3	0	0	3						
	edge in solid mechanics. OBJECTIVES:									
	ake the students to formulate the physical design problems into Facilition, application of boundary conditions, assembly of global ms.									
	ke the students to apply FEM concept for developing FE equations for solving 1-D problems with bar, truss and elements.									
	ake the students to apply FEM concept for developing FE equation ane stress, plane strain and axisymmetric problems.	ns for solving 2-D) problei	ns with	CST ele	ement				
	quip the students about iso-parametric formulations for quadrilate rical integration.	ral element and a	pply the	gauss	quadratu	ire fo				
5. To fa	miliarize the students, apply FE equations for solving thermal and fl	uid flow problems	.	T		_				
UNIT I	INTRODUCTION		9	0	0	9				
Shape functi	ional Second Order Equations – Discretization – Element types- Lions and Stiffness matrices and force vectors-Assembly of Matrice ermal stresses.	_								
UNIT III	TWO DIMENSIONAL FEA		9	0	0	9				
Triangular e	er 2D Equations involving Scalar Variable Functions – Variatio lements and Quadrilateral elements- Shape functions and element plane strain and axisymmetric problems – Constitutive matrices and ulations. ISOPARAMETRIC FORMULATION AND NUM	matrices and vec d Strain displacem	etors- Equent matr	uations	of elast	icity -				
UNIT IV	INTEGRATION	ERICAL	9	0	0	9				
 Serendipit 	rdinate systems – Iso-parametric elements – Shape functions for iso y elements – Numerical integration-Lagrange's interpolation- High ement - Applying numerical integration: 1, 2 and 3 gauge point for 1	her order one dim	ensional	elemen	ıts - Qu					
UNIT V	FEA APPLICATION TO HEAT TRANSFER ANI MECHANICS	FLUID	9	0	0	9				
approach for	heat transfer, 1D heat conduction governing Equations -Function heat conduction - application to one-dimensional heat transfer properties of Fluid Mechanics — Solid structure interaction - is simple problems.	roblems- 1D heat	transfer	in thin	fins pro	blem				
				Total	= 45 Pe	eriod				
				Total	= 45 Pe	eriod				
	S:			Total	= 45 Pe	eriod				

Tex	Text Books:						
1.	Tirupathi R. Chandrupatla and Ashok D. Belegundu, "Introduction to Finite Elements in Engineering", International Edition, Pearson Education Limited, 2014.						
2.	Seshu.P, "Text Book of Finite Element Analysis", PHI Learning Pvt. Ltd., New Delhi, 2012						

Ref	Reference Books:							
1.	Rao, S.S., "The Finite Element Method in Engineering", 6th Edition, Butterworth-Heinemann, 2018							
2.	Reddy, J.N. "Introduction to the Finite Element Method", 4th Edition, Tata McGrawHill, 2018							
3.	Dhanaraj. R and Prabhakaran Nair. K, "Finite Element Analysis", Oxford Publications, 2015.							
4.	David Hutton, "Fundamentals of Finite Element Analysis", Tata Mc Graw Hill, 2005							
5.	Robert D. Cook, David S. Malkus, Michael E. Plesha, Robert J. Witt, "Concepts and Applications of Finite Element Analysis", 4th Edition, Wiley Student Edition, 2004.							
E-F	References:							
1.	https://soaneemrana.com/onewebmedia/TEXT%20BOOKOF%20FINITE%20ELEMENT%20ANALYSIS%20BY%20P. %20SESHU%20.pdf							
2.	https://nptel.ac.in/courses/112104193							
3.	https://www.engr.uvic.ca/~mech410/lectures/FEA_Theory.pdf							

	RSE OUTCOMES: unpletion of the course the student will be able to	Bloom's Taxonomy Mapped
CO1	Formulate the physical design problems into FEA including domain discretization, polynomial interpolation, application of boundary conditions, assembly of global arrays, and solution of the resulting algebraic systems.	Analyze
CO2	Apply FEM concept for developing FE equations for solving 1-D problems with bar, truss and beam elements.	Apply
СОЗ	Apply FEM concept for developing FE equations for solving 2-D problems with CST elements for plane stress, plane strain and axisymmetric problems.	Apply
CO4	Derive iso-parametric formulations for quadrilateral element and apply the gauss quadrature for numerical integration.	Apply
CO5	Apply the concepts of FEA for solving 1-D heat transfer and fluid flow problems under the given boundary conditions.	Apply

COURS	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	2	1	1	0	0	0	0	0	0	0	3	1	0
CO2	3	3	2	1	1	0	0	0	0	0	0	0	3	1	0
CO3	3	3	2	1	1	0	0	0	0	0	0	0	3	1	0
CO4	3	3	2	1	1	0	0	0	0	0	0	0	3	1	0
CO5	3	3	2	1	1	0	0	0	0	0	0	0	3	1	0
Avg	3.0	3.0	2.0	1.0	1.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	3.0	1.0	0.0
			3/2/1	– indica	ates stre	ngth of	correla	tion (3 –	high, 2	- mediu	m, 1- lo	w)			

22ME703	MECHATRONICS LABORATO	SEMESTER VII						
PREREQUISIT	Е:	Category	PC	Credit		1.5		
1. Basics of electro	nics and electrical engineering		L	T	P	TH		
2. Knowledge in in	2. Knowledge in instrumentation and sensors Hours/Week							
3. Basics of Hydra	alic and pneumatic systems		U	U	3	3		
Course Objectiv	es:					,		

- 1. To provide automation concepts where students could perform experimental study regarding fundamental sequence control by utilising various hydraulic and pneumatic components.
- 2. To provide knowledge to assist the students in the development of "handson" skills with an emphasis on actuators and multidisciplinary systems.
- 3. To provide software knowledge to the engineering students to apply hardware and programming basics and absorb Mechatronics concepts.
- 4. To equip students with mechatronics knowledge and also gather knowledge of virtual instrumentation systems for mechanical engineering applications/
- 5. To promote interdisciplinary research and industry driven innovation in the cutting-edge areas of mechatronics.

LIST OF EXPERIMENTS

- 1. Design and testing of fluid power circuits to control
 - (i) velocity (ii) direction and (iii) force of single and double acting cylinders
- 2. Design and testing of cylinder sequences A+B+A-B- and A+B+B-A- of pneumatic circuits.
- 3. Design of Electro pneumatic circuits with logic sequence using Electro pneumatic trainer kits.
- 4. Design of Electro hydraulic circuits with logic sequence using Electro hydraulic trainer kits.
- 5. Simulation of basic Hydraulic, Pneumatic and Electro-hydraulic, Electro-pneumatic circuits using simulation software.
- 6. Design and simulation of Electro pneumatic circuits with PLC programming using simulation software.
- 7. Study the performance of DC motor.
- 8. Experiment on servo controller interfacing for closed loop control.
- 9. Stepper motor interfacing with 8051 Micro controller (i)full step resolution (ii) half step resolution
- 10. Maintain constant pressure of a process in a process station using PID controller in Virtual Instrumentation
- 11. Maintain constant temperature of a process in a shell and tube heat exchanger using PID controller in Virtual Instrumentation software.
- 12. Maintain constant flow rate of a process in a process station using PID controller in Virtual Instrumentation software.
- 13. Study the performance of 6- axis robot.

Total = 45 Periods

	RSE OUTCOMES: mpletion of the course the student will be able to	Bloom's Taxonomy Mapped
CO1	Select various control valves and use them in hydraulic and pneumatic circuit development	Understand
CO2	Get adequate knowledge to simulate the basic electric, hydraulic and pneumatic system using simulation software.	Understand
CO3	Get adequate knowledge about the characteristics of various actuators and methods of tuning of controller in a Mechatronic system.	Understand
CO4	Understand how to interface electromechanical systems to PLCs.	Understand
CO5	Gain practical experience in data acquisition system and develop and evaluate alternate solutions to real world problems.	Understand

	RSE OUTCOMES: mpletion of the course the student will be able to	Bloom's Taxonomy Mapped
CO1	Select various control valves and use them in hydraulic and pneumatic circuit development	Understand
CO2	Get adequate knowledge to simulate the basic electric, hydraulic and pneumatic system using simulation software.	Understand
CO3	Get adequate knowledge about the characteristics of various actuators and methods of tuning of controller in a Mechatronic system.	Understand
CO4	Understand how to interface electromechanical systems to PLCs.	Understand
CO5	Gain practical experience in data acquisition system and develop and evaluate alternate solutions to real world problems.	Understand

Cos/ POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	3	0	0	0	0	0	0	0	0	0	0	1	1	1
CO2	0	0	1	2	0	0	0	0	0	0	0	0	1	2	2
CO3	0	0	1	0	0	0	1	2	0	0	0	0	2	1	3
CO4	0	0	0	3	0	0	0	0	0	0	2	3	2	1	3
CO5	0	0	3	0	0	0	0	0	2	1	2	0	2	2	3
Avg	0.2	0.6	1	1	0	0	0.2	0.4	0.4	0.2	0.8	0.6	1.6	1.4	2.4

22M	E704	SIMULATION LABORATORY		SEMESTER VII				
PRER	REQUIS	SITE:	CATEGORY	PC	PC Credit			
	ic knowl	Hours/Week	L	T	P	TH		
2. Fund	damenta	nours/ week	0	0	3	3		
COURSE OBJECTIVES:								
1.	To make the students analyze the structural components for deflection, stress and reaction forces.							
2	To mole	the students analyze the force stress deflection in mechanical con	nnononta	<u> </u>		<u> </u>	<u> </u>	

- 2. To make the students analyze the force, stress, deflection in mechanical components.
- 3. To make the students analyze thermal stress and heat transfer in mechanical components.
- 4. To make the students analyze the vibration of mechanical components.
- 5. To make the students analyze the modal, harmonic, transient and spectrum concepts in mechanical components.

LIST OF EXPERIMENTS

Analysis of Mechanical Components – Use of FEA packages, like ANSYS/ NASTRON etc., Excesses shell include FEA analysis of

- 1. Force and Stress analysis using link elements in Trusses.
- 2. Force and stress analysis using link elements in axially loaded bars.
- 3. Stress and deflection analysis in beams with different support conditions.
- 4. Stress analysis of flat plates.
- 5. Stress analysis of axis–symmetric components.
- 6. Thermal stress and heat transfer analysis of plates.
- 7. Thermal stress analysis of cylindrical shells.
- 8. Vibration analysis of spring-mass systems.
- 9. Modal analysis of Beams.
- 10. Harmonic, transient and spectrum analysis of simple systems

E-REFERENCES:

https://www.ansys.com/
 https://bmsce.ac.in/Content/ME/MFELAB_manual_Jan2019_Updated_28_1_2019.pdf
 https://confluence.cornell.edu/display/SIMULATION/ANSYS+Learning+Modules

COU	RSE OUTCOMES:							
On co	On completion of the course the student will be able to							
CO1	Analyze the structural components for deflection, stress and reaction forces.	Analyze						
CO2	Analyze the force, stress, deflection in mechanical components.	Analyze						
CO3	Analyze thermal stress and heat transfer in mechanical components.	Analyze						
CO4	Analyze the vibration of mechanical components.	Analyze						
CO5	Analyze the modal, harmonic, transient and spectrum concepts in mechanical components.	Analyze						

COURSE	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	0	0	3	0	0	1	0	0	0	1	1	0	0
CO2	2	2	0	0	3	0	0	1	0	0	0	1	1	0	0
CO3	2	2	0	0	3	0	0	1	0	0	0	1	2	0	0
CO4	2	2	0	0	3	0	0	1	0	0	0	1	2	0	0
CO5	2	2	0	0	3	0	0	1	0	0	0	1	2	0	0
Avg	2.0	2.0	0.0	0.0	3.0	0.0	0.0	1.0	0.0	0.0	0.0	1.0	1.6	0.0	0.0
3/2/1 - i	indicat	es stren	gth of	correlat	ion (3 -	- high.	2- med	ium. 1-	low)						

22ME705	CAM LABAROTARY		SEMESTER VII					
PREREQUISITE:		CATEGORY	PC	Cre	edit	1.5		
						TH		
	Hours/V		0	0	3	3		

COURSE OBJECTIVES:

- 1. To equip the students for implement CNC programs for milling and turning machining operations.
- 2. To create a computer aided manufacturing (CAM) model and generate the machining codes automatically using the CAM system.
- 3. Understand different operations that are to be executed to get a final product which include drilling and reaming operations.
- 4. Understand CNC machining and uses, and applications of CNC program.
- 5. Remember the purpose of other alphabetical commands used in programming operations of a CNC machine.

CAM EXPERIMENTS

Tool path generation, Part programming, G & M codes development for machining operations, Physical interpretation of machining features and tool geometries

Manual part programming

- CNC Turning Centre Facing, Turning, Chamfering, Taper turning, Thread cutting
- CNC Turning Centre Facing, Turning, Chamfering, Taper turning, Grooving, Threading using canned cycles
- CNC Milling Linear and circular Profile, Pocket, Drill, Peck-Drill, Bore, Tap- Using canned cycles.
- Part Program generation and tool path simulation for turning &milling for Fanuc Control System using CAM software.
- Demonstration on CNC Turning & Milling Machines

	RSE OUTCOMES: mpletion of the course the student will be able to	Bloom's Taxonomy Mapped
CO1	Understand the features and specifications of CNC machines	Understand
CO2	Develop the process planning sheets and tool layouts.	Apply
CO3	Understand the CAM software and its programming.	Understand
CO4	Use the CAM software and prepare CNC part programs.	Apply
CO5	Execute the part program and machine the component as per the production drawing.	Apply

COURSE	ART	ICUL	ATIO	N MA	TRIX										
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	2	2	2	1	0	0	2	0	2	0	2	2	1
CO2	1	1	1	1	0	0	0	0	0	0	3	0	1	1	1
CO3	1	2	1	2	2	3	0	0	0	0	3	0	2	2	1
CO4	1	2	1	1	1	3	0	0	0	0	3	0	2	2	1
CO5	1	2	1	1	1	3	0	0	0	0	3	0	2	2	1
Avg	1.2	1.6	1.2	1.4	1.2	2.0	0.0	0.0	0.4	0.0	2.8	0.0	1.8	1.8	1.0
3/2/1 -	indicat	es strer	gth of	correla	tion (3	– high,	2- med	lium, 1	low)			•			•

22ME706	PROJECT – I	PROJECT – I					
PREREQUISIT	E: CATEGOR	Y	EE	Cr	edit	4	
	House/Wool	-	L	T	P	TH	
	Hours/Weel		0	0	8	8	

COURSE OBJECTIVES:

1.

CO5

Avg

2.2

2.0

2.0

- 1. The main objective is to give an opportunity to the student to get hands on training in the fabrication of one or more components of a complete working model, which is designed by them.
- 2. It is intended to start the project work early in the seventh semester and carry out both design and fabrication of a mechanical device whose working can be demonstrated. The design is expected to be completed in the seventh semester and the fabrication and demonstration will be carried out in the eighth semester

GUIDELINE FOR REVIEW AND EVALUATION

COURSE ARTICULATION MATRIX

The students may be grouped into 2 to 4 and work under a project supervisor. The device/system/component(s) to be fabricated may be decided in consultation with the supervisor and if possible, with an industry. A project report to be submitted by the group and the fabricated model, which will be reviewed and evaluated for internal assessment by a committee constituted by the Head of the Department. At the end of the semester examination the project work is evaluated based on oral presentation and the project report jointly by external and internal examiners (Supervisors) constituted by the Head of the Department

Total (75P) = 75 Periods

	RSE OUTCOMES: mpletion of the course the student will be able to	Bloom's Taxonomy Mapped
CO1	Initiate and motivate the students to come out with innovative ideas for different applications.	Create
CO2	Create an environment to convert the ideas into design of prototype for useful industrial, agricultural and social applications.	Create
CO3	Create an environment to convert the design into manufacturing of prototype for useful industrial, agricultural and social applications.	Create
CO4	Assign and undertake tasks in a team as per team discussion.	Understand
CO5	Do presentation and write technical reports for effective communication within and outside the team.	Understand

PO1 PO₂ PO3 **PO4 PO5 PO6 PO7 PO8 PO9** PO10 PO11 **PO12** PSO₁ PSO₂ PSO₃ COs/POs CO₁ CO₂ **CO3 CO4**

1.2

3.0

1.4

1.0

1.6

3.0

2.4

1.2

3/2/1 – indicates strength of correlation (3 – high, 2- medium, 1- low)

1.8

2.0

1.8

1.8

SEMESTER-VIII

22ME801	22ME801 PROJECT – II						
PREREQUISITI	E: CATEGORY	EE	Cr	edit	10		
	¥¥/¥¥I	L	Т	P	TH		
	Hours/Week	0	0	20	10		

COURSE OBJECTIVES:

- 1. The main objective is to give an opportunity to the student to get hands on training in the fabrication of one or more components of a complete working model, which is designed by them.
- 2. It is intended to start the project work early in the seventh semester and carry out both design and fabrication of a mechanical device whose working can be demonstrated. The design is expected to be completed in the seventh semester and the fabrication and demonstration will be carried out in the eighth semester

GUIDELINE FOR REVIEW AND EVALUATION

The students may be grouped into 2 to 4 and work under a project supervisor. The device/system/component(s) to be fabricated may be decided in consultation with the supervisor and if possible, with an industry. A project report to be submitted by the group and the fabricated model, which will be reviewed and evaluated for internal assessment by a committee constituted by the Head of the Department. At the end of the semester examination the project work is evaluated based on oral presentation and the project report jointly by external and internal examiners (Supervisors) constituted by the Head of the Department.

Total (90P) = 90 Periods

	RSE OUTCOMES: mpletion of the course the student will be able to	Bloom's Taxonomy Mapped
CO1	Initiate and motivate the students to come out with innovative ideas for different applications.	Create
CO2	Create an environment to convert the ideas into design of prototype for useful industrial, agricultural and social applications.	Create
CO3	Create an environment to convert the design into manufacturing of prototype for useful industrial, agricultural and social applications.	Create
CO4	Assign and undertake tasks in a team as per team discussion.	Understand
CO5	Do presentation and write technical reports for effective communication within and outside the team.	Understand

COURSE	OURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	2	3	3	1	3	0	2	0	3	3	3
CO2	3	3	3	3	2	3	3	0	3	0	1	0	3	3	0
CO3	2	2	2	2	2	1	1	1	3	1	2	3	3	3	0
CO4	3	2	2	1	1	1	2	3	3	3	0	3	3	3	0
CO5	0	0	0	0	2	2	0	1	3	3	0	2	3	0	3
Avg	2.2	2.0	2.0	1.8	1.8	2.0	1.8	1.2	3.0	1.4	1.0	1.6	3.0	2.4	1.2
3/2/1 - i	indicat	es strer	gth of	correla	tion (3	– high,	2- med	lium, 1	low)						

PROFESSIONAL ELECTIVES – I

2. Thermodynamics and Thermal Engineering 1. To broaden the understanding of students in the structure of vehicle chassis and engines 2. To teach students about the importance of alternate fuels and modifying the engine suitably 3. Analyze the working principles and operations details of transmission and suspension systems 4. Evaluate the operational details and design principles of breaking and steering systems 5. To introduce students to engine auxiliary systems like heating, ventilation and air-conditioning UNIT I AUTOMOBILE VEHICLE STRUCTURE AND PERFORMANCE 9 0 Automotive components, subsystems and their positions- Chassis, frame and body, front, rear and four-wheel of Operation and performance, Traction force and traction resistance, Power required for automobile - Rolling, a gradient resistance. Introduction to MV Act, Pollution Norms UNIT II POWERTRAIN AND FUEL MANAGEMENT SYSTEMS 9 0 Reciprocating Engine systems, Hybrid systems. Pollutant emissions and their control; Catalytic converter sy Electronic Engine Management systems for SI and CI engines. Liquid and gaseous alternate fuels - Alcohol, LPG, and Hydrogen. UNIT III TRANSMISSION AND SUSPENSIONS SYSTEMS 9 0 Transmission system: Clutches - principle, types - single plate clutch, multiplate clutch, magnetic and centre clutches, fluid fly wheel. Gear boxes, types, constant mesh, synchromesh gear boxes, epicyclic gear box transmission, continuous variable transmission, propeller shaft, Hotch-Kiss drive, Torque tube drive, universal differential, rear axles types, wheels and tyres; Suspension system: Objects of suspension systems, rigid axle suspensystem, torsion bar, shock absorber, independent suspension system	ER '	rer	ER	R	V
2. Thermodynamics and Thermal Engineering COURSE OBJECTIVES: 1. To broaden the understanding of students in the structure of vehicle chassis and engines 2. To teach students about the importance of alternate fuels and modifying the engine suitably 3. Analyze the working principles and operations details of transmission and suspension systems 4. Evaluate the operational details and design principles of breaking and steering systems 5. To introduce students to engine auxiliary systems like heating, ventilation and air-conditioning UNIT I AUTOMOBILE VEHICLE STRUCTURE AND PERFORMANCE 9 0 Automotive components, subsystems and their positions- Chassis, frame and body, front, rear and four-wheed operation and performance, Traction force and traction resistance, Power required for automobile - Rolling, a gradient resistance. Introduction to MV Act, Pollution Norms UNIT II POWERTRAIN AND FUEL MANAGEMENT SYSTEMS 9 0 Reciprocating Engine systems, Hybrid systems. Pollutant emissions and their control; Catalytic converter sy Electronic Engine Management systems for SI and CI engines. Liquid and gaseous alternate fuels - Alcohol, LPG, and Hydrogen. UNIT III TRANSMISSION AND SUSPENSIONS SYSTEMS 9 0 Fransmission system: Clutches - principle, types - single plate clutch, multiplate clutch, magnetic and central clutches, fluid fly wheel. Gear boxes, types, constant mesh, synchromesh gear boxes, epicyclic gear box transmission, continuous variable transmission, propeller shaft, Hotch-Kiss drive, Torque tube drive, universal differential, rear axles types, wheels and tyres; Suspension system: Objects of suspension systems, rigid axle suspe system, torsion bar, shock absorber, independent suspension system UNIT IV BRAKING AND STEERING SYSTEMS 9 0 Forces on vehicles, tyre grip, load transfer, braking distribution between axles, stopping distance, Types of br Mechanical, Hydraulic, Air brakes, Disc & Drum brakes, Engine brakes anti-lock braking system. Types of st systems - Ackermann principle, Davis steering gear, stee	it	dit	lit	t	3
2. Thermodynamics and Thermal Engineering COURSE OBJECTIVES: 1. To broaden the understanding of students in the structure of vehicle chassis and engines 2. To teach students about the importance of alternate fuels and modifying the engine suitably 3. Analyze the working principles and operations details of transmission and suspension systems 4. Evaluate the operational details and design principles of breaking and steering systems 5. To introduce students to engine auxiliary systems like heating, ventilation and air-conditioning UNIT I AUTOMOBILE VEHICLE STRUCTURE AND PERFORMANCE 9 0 1 Automotive components, subsystems and their positions- Chassis, frame and body, front, rear and four-wheel operation and performance, Traction force and traction resistance, Power required for automobile - Rolling, a gradient resistance. Introduction to MV Act, Pollution Norms UNIT II POWERTRAIN AND FUEL MANAGEMENT SYSTEMS 9 0 Reciprocating Engine systems, Hybrid systems, Pollutant emissions and their control; Catalytic converter sy Electronic Engine Management systems for SI and CI engines. Liquid and gaseous alternate fuels - Alcohol, LPG, and Hydrogen. UNIT III TRANSMISSION AND SUSPENSIONS SYSTEMS 9 0 Transmission system: Clutches - principle, types - single plate clutch, multiplate clutch, magnetic and centre clutches, fluid fly wheel. Gear boxes, types, constant mesh, synchromesh gear boxes, epicyclic gear box transmission, continuous variable transmission, propeller shaft, Hotch-Kiss drive, Torque tube drive, universal differential, rear axles types, wheels and tyres; Suspension system: Objects of suspension systems. UNIT IV BRAKING AND STEERING SYSTEMS 9 0 Forces on vehicles, tyre grip, load transfer, braking distribution between axles, stopping distance, Types of st systems - Ackermann principle, Davis steering gear; boxes, steering linkages, power steering, geometry-caster, camber toe-in, toe out etc., wheel Alignment and balancing. UNIT V ELECTRICAL AND ELECTRONICS SYSTEMS 9 0 General electrical cir	P	P	P	•	Tl
1. To broaden the understanding of students in the structure of vehicle chassis and engines 2. To teach students about the importance of alternate fuels and modifying the engine suitably 3. Analyze the working principles and operations details of transmission and suspension systems 4. Evaluate the operational details and design principles of breaking and steering systems 5. To introduce students to engine auxiliary systems like heating, ventilation and air-conditioning UNIT I AUTOMOBILE VEHICLE STRUCTURE AND PERFORMANCE 9 0 Automotive components, subsystems and their positions- Chassis, frame and body, front, rear and four-wheel Operation and performance, Traction force and traction resistance, Power required for automobile - Rolling, a gradient resistance. Introduction to MV Act, Pollution Norms UNIT II POWERTRAIN AND FUEL MANAGEMENT SYSTEMS 9 0 Reciprocating Engine systems, Hybrid systems. Pollutant emissions and their control; Catalytic converter sy Electronic Engine Management systems for SI and CI engines. Liquid and gaseous alternate fuels - Alcohol, LPG, and Hydrogen. UNIT III TRANSMISSION AND SUSPENSIONS SYSTEMS 9 0 Transmission system: Clutches - principle, types - single plate clutch, multiplate clutch, magnetic and central clutches, fluid fly wheel. Gear boxes, types, constant mesh, synchromesh gear boxes, epicyclic gear box transmission, continuous variable transmission, propeller shaft, Hotch-Kiss drive, Torque tube drive, universal differential, rear axles types, wheels and tyres; Suspension system: Objects of suspension systems, rigid axle suspesystem, torsion bar, shock absorber, independent suspension system: Objects of suspension systems, rigid axle suspesystem, torsion bar, shock absorber, independent suspension system: UNIT IV BRAKING AND STEERING SYSTEMS 9 0 Forces on vehicles, tyre grip, load transfer, braking distribution between axles, stopping distance, Types of br Mechanical, Hydraulic, Air brakes, Disc & Drum brakes, Engine brakes anti-lock braking system. Types of Systems	0	0	0)	3
2. To teach students about the importance of alternate fuels and modifying the engine suitably 3. Analyze the working principles and operations details of transmission and suspension systems 4. Evaluate the operational details and design principles of breaking and steering systems 5. To introduce students to engine auxiliary systems like heating, ventilation and air-conditioning UNIT I AUTOMOBILE VEHICLE STRUCTURE AND PERFORMANCE 9 0 Automotive components, subsystems and their positions- Chassis, frame and body, front, rear and four-wheel of Operation and performance, Traction force and traction resistance, Power required for automobile - Rolling, a gradient resistance. Introduction to MV Act, Pollution Norms UNIT II POWERTRAIN AND FUEL MANAGEMENT SYSTEMS 9 0 Reciprocating Engine systems, Hybrid systems. Pollutant emissions and their control; Catalytic converter sy Electronic Engine Management systems for SI and CI engines. Liquid and gaseous alternate fuels - Alcohol, LPG, and Hydrogen. UNIT III TRANSMISSION AND SUSPENSIONS SYSTEMS 9 0 Transmission system: Clutches - principle, types - single plate clutch, multiplate clutch, magnetic and central clutches, fluid fly wheel. Gear boxes, types, constant mesh, synchromesh gear boxes, epicyclic gear box transmission, continuous variable transmission, propeller shaft, Hotch-Kiss drive, Torque tube drive, universal differential, rear axles types, wheels and tyres; Suspension system: Objects of suspension systems, rigid axle suspesystem, torsion bar, shock absorber, independent suspension system UNIT IV BRAKING AND STEERING SYSTEMS 9 0 Forces on vehicles, tyre grip, load transfer, braking distribution between axles, stopping distance, Types of st systems - Ackermann principle, Davis steering gear boxes, Engine brakes anti-lock braking system. Types of st systems - Ackermann principle, Davis steering gear steering gear boxes, steering linkages, power steering, geometry-caster, camber toe-in, toe out etc., wheel Alignment and balancing. UNIT V ELECTRICAL AND ELE					
3. Analyze the working principles and operations details of transmission and suspension systems 4. Evaluate the operational details and design principles of breaking and steering systems 5. To introduce students to engine auxiliary systems like heating, ventilation and air-conditioning UNIT I AUTOMOBILE VEHICLE STRUCTURE AND PERFORMANCE 9 0 0 Automotive components, subsystems and their positions- Chassis, frame and body, front, rear and four-wheel of Operation and performance, Traction force and traction resistance, Power required for automobile - Rolling, a gradient resistance. Introduction to MV Act, Pollution Norms UNIT II POWERTRAIN AND FUEL MANAGEMENT SYSTEMS 9 0 Reciprocating Engine systems, Hybrid systems. Pollutant emissions and their control; Catalytic converter sy Electronic Engine Management systems for SI and CI engines. Liquid and gaseous alternate fuels - Alcohol, LPG, and Hydrogen. UNIT III TRANSMISSION AND SUSPENSIONS SYSTEMS 9 0 Transmission system: Clutches - principle, types - single plate clutch, multiplate clutch, magnetic and centre clutches, fluid fly wheel. Gear boxes, types, constant mesh, synchromesh gear boxes, epicyclic gear box transmission, continuous variable transmission, propeller shaft, Hotch-Kiss drive, Torque tube drive, universal differential, rear axles types, wheels and tyres; Suspension system: Objects of suspension systems, rigid axle suspensystem, torsion bar, shock absorber, independent suspension system UNIT IV BRAKING AND STEERING SYSTEMS 9 0 Forces on vehicles, tyre grip, load transfer, braking distribution between axles, stopping distance, Types of st systems - Ackermann principle, Davis steering gear steering gear boxes, steering linkages, power steering, geometry-caster, camber toe-in, toe out etc., wheel Alignment and balancing. UNIT V ELECTRICAL AND ELECTRONICS SYSTEMS 9 0 General electrical circuits. Battery, Starting motor, DC generator, Alternator, Ignition circuit, Dash instrumentation, Lighting system. Passenger comfort - Safety and security -					
4. Evaluate the operational details and design principles of breaking and steering systems 5. To introduce students to engine auxiliary systems like heating, ventilation and air-conditioning UNIT I AUTOMOBILE VEHICLE STRUCTURE AND PERFORMANCE 9 0 Automotive components, subsystems and their positions- Chassis, frame and body, front, rear and four-wheel of Operation and performance, Traction force and traction resistance, Power required for automobile - Rolling, a gradient resistance. Introduction to MV Act, Pollution Norms UNIT II POWERTRAIN AND FUEL MANAGEMENT SYSTEMS 9 0 Reciprocating Engine systems, Hybrid systems. Pollutant emissions and their control; Catalytic converter sy Electronic Engine Management systems for SI and CI engines. Liquid and gaseous alternate fuels - Alcohol, LPG, and Hydrogen. UNIT III TRANSMISSION AND SUSPENSIONS SYSTEMS 9 0 Transmission system: Clutches - principle, types - single plate clutch, multiplate clutch, magnetic and centre clutches, fluid fly wheel. Gear boxes, types, constant mesh, synchromesh gear boxes, epicyclic gear box transmission, continuous variable transmission, propeller shaft, Hotch-Kiss drive, Torque tube drive, universal differential, rear axles types, wheels and tyres; Suspension system: Objects of suspension systems, rigid axle suspesystem, torsion bar, shock absorber, independent suspension system: Objects of suspension systems, rigid axle suspesystem, torsion bar, shock absorber, independent suspension system: UNIT IV BRAKING AND STEERING SYSTEMS 9 0 Forces on vehicles, tyre grip, load transfer, braking distribution between axles, stopping distance, Types of st systems - Ackermann principle, Davis steering gear, steering gear boxes, steering linkages, power steering, geometry-caster, camber toe-in, toe out etc., wheel Alignment and balancing. UNIT V ELECTRICAL AND ELECTRONICS SYSTEMS 9 0 General electrical circuits. Battery, Starting motor, DC generator, Alternator, Ignition circuit, Dash instrumentation, Lighting system. Passenger comfort - Safet					
UNIT I AUTOMOBILE VEHICLE STRUCTURE AND PERFORMANCE 9 0 0 Automotive components, subsystems and their positions- Chassis, frame and body, front, rear and four-wheel operation and performance, Traction force and traction resistance, Power required for automobile - Rolling, a gradient resistance. Introduction to MV Act, Pollution Norms UNIT II POWERTRAIN AND FUEL MANAGEMENT SYSTEMS 9 0 Reciprocating Engine systems, Hybrid systems. Pollutant emissions and their control; Catalytic converter sy Electronic Engine Management systems for SI and CI engines. Liquid and gaseous alternate fuels - Alcohol, LPG, and Hydrogen. UNIT III TRANSMISSION AND SUSPENSIONS SYSTEMS 9 0 Transmission system: Clutches - principle, types - single plate clutch, multiplate clutch, magnetic and centre clutches, fluid fly wheel. Gear boxes, types, constant mesh, synchromesh gear boxes, epicyclic gear box transmission, continuous variable transmission, propeller shaft, Hotch-Kiss drive, Torque tube drive, universal differential, rear axles types, wheels and tyres; Suspension system: Objects of suspension systems, rigid axle suspensystem, torsion bar, shock absorber, independent suspension system: UNIT IV BRAKING AND STEERING SYSTEMS 9 0 Forces on vehicles, tyre grip, load transfer, braking distribution between axles, stopping distance, Types of st systems - Ackermann principle, Davis steering gear, steering gear boxes, steering linkages, power steering, geometry-caster, camber toe-in, toe out etc., wheel Alignment and balancing. UNIT V ELECTRICAL AND ELECTRONICS SYSTEMS 9 0 General electrical circuits. Battery, Starting motor, DC generator, Alternator, Ignition circuit, Dash instrumentation, Lighting system. Passenger comfort - Safety and security - HVAC - Seat belts - Air bags - Autor Electronic S Take Distribution (EBD) - Electronic Stability Program (ESP) Traction Control System (TCS) - Celectronic Brake Distribution (EBD) - Electronic Stability Program (ESP) Traction Control System (TCS)					
Automotive components, subsystems and their positions- Chassis, frame and body, front, rear and four-wheel operation and performance, Traction force and traction resistance, Power required for automobile - Rolling, a gradient resistance. Introduction to MV Act, Pollution Norms UNIT II POWERTRAIN AND FUEL MANAGEMENT SYSTEMS Pelectronic Engine Systems, Hybrid systems. Pollutant emissions and their control; Catalytic converter sy Electronic Engine Management systems for SI and CI engines. Liquid and gaseous alternate fuels - Alcohol, LPG, and Hydrogen. UNIT III TRANSMISSION AND SUSPENSIONS SYSTEMS Pollutant mesh, synchromesh gear boxes, epicyclic gear box transmission system: Clutches - principle, types - single plate clutch, multiplate clutch, magnetic and centerlutches, fluid fly wheel. Gear boxes, types, constant mesh, synchromesh gear boxes, epicyclic gear box transmission, continuous variable transmission, propeller shaft, Hotch-Kiss drive, Torque tube drive, universal differential, rear axles types, wheels and tyres; Suspension system: Objects of suspension systems, rigid axle suspesystem, torsion bar, shock absorber, independent suspension system: UNIT IV BRAKING AND STEERING SYSTEMS Porces on vehicles, tyre grip, load transfer, braking distribution between axles, stopping distance, Types of st systems - Ackermann principle, Davis steering gear, steering gear boxes, steering linkages, power steering, geometry-caster, camber toe-in, toe out etc., wheel Alignment and balancing. UNIT V ELECTRICAL AND ELECTRONICS SYSTEMS Porces on vehicles, tyre grip, load transfer, braking distribution between axles, stopping distance, Types of st systems - Ackermann principle, Davis steering gear, steering gear boxes, steering linkages, power steering, geometry-caster, camber toe-in, toe out etc., wheel Alignment and balancing. UNIT V ELECTRICAL AND ELECTRONICS SYSTEMS Porces on vehicles, tyre grip, load transfer, braking distribution to travely between toe-in, toe out etc., wheel Alignment and balancing. UNIT V EL					
Automotive components, subsystems and their positions- Chassis, frame and body, front, rear and four-wheel of Operation and performance, Traction force and traction resistance, Power required for automobile - Rolling, a gradient resistance. Introduction to MV Act, Pollution Norms UNIT II POWERTRAIN AND FUEL MANAGEMENT SYSTEMS 9 0					
Operation and performance, Traction force and traction resistance, Power required for automobile - Rolling, a gradient resistance. Introduction to MV Act, Pollution Norms UNIT II POWERTRAIN AND FUEL MANAGEMENT SYSTEMS 9 0 Reciprocating Engine systems, Hybrid systems. Pollutant emissions and their control; Catalytic converter sy Electronic Engine Management systems for SI and CI engines. Liquid and gaseous alternate fuels - Alcohol, LPG, and Hydrogen. UNIT III TRANSMISSION AND SUSPENSIONS SYSTEMS 9 0 Transmission system: Clutches - principle, types - single plate clutch, multiplate clutch, magnetic and centre clutches, fluid fly wheel. Gear boxes, types, constant mesh, synchromesh gear boxes, epicyclic gear box transmission, continuous variable transmission, propeller shaft, Hotch-Kiss drive, Torque tube drive, universal differential, rear axles types, wheels and tyres; Suspension system: Objects of suspension systems, rigid axle suspension bar, shock absorber, independent suspension system UNIT IV BRAKING AND STEERING SYSTEMS 9 0 Forces on vehicles, tyre grip, load transfer, braking distribution between axles, stopping distance, Types of brakenincal, Hydraulic, Air brakes, Disc & Drum brakes, Engine brakes anti-lock braking system. Types of st systems - Ackermann principle, Davis steering gear, steering gear boxes, steering linkages, power steering, geometry-caster, camber toe-in, toe out etc., wheel Alignment and balancing. UNIT V ELECTRICAL AND ELECTRONICS SYSTEMS 9 0 General electrical circuits. Battery, Starting motor, DC generator, Alternator, Ignition circuit, Dash instrumentation, Lighting system. Passenger comfort - Safety and security - HVAC - Seat belts - Air bags - Autor Electronics - Electronic Control Unit (ECU) - Variable Valve Timing (VVT) - Active Suspension System (AELECTRONICE STATEMS) - Calcuttonic Stability Program (ESP) Traction Control System (TCS) - Calcuttonic Control Syst)	0	0		9
Reciprocating Engine systems, Hybrid systems. Pollutant emissions and their control; Catalytic converter sy Electronic Engine Management systems for SI and CI engines. Liquid and gaseous alternate fuels - Alcohol, LPG, and Hydrogen. UNIT III TRANSMISSION AND SUSPENSIONS SYSTEMS 9 0 Transmission system: Clutches - principle, types - single plate clutch, multiplate clutch, magnetic and centre clutches, fluid fly wheel. Gear boxes, types, constant mesh, synchromesh gear boxes, epicyclic gear box transmission, continuous variable transmission, propeller shaft, Hotch-Kiss drive, Torque tube drive, universal differential, rear axles types, wheels and tyres; Suspension system: Objects of suspension systems, rigid axle suspension bar, shock absorber, independent suspension system UNIT IV BRAKING AND STEERING SYSTEMS 9 0 Forces on vehicles, tyre grip, load transfer, braking distribution between axles, stopping distance, Types of brakenancial, Hydraulic, Air brakes, Disc & Drum brakes, Engine brakes anti-lock braking system. Types of st systems - Ackermann principle, Davis steering gear, steering gear boxes, steering linkages, power steering, geometry-caster, camber toe-in, toe out etc., wheel Alignment and balancing. UNIT V ELECTRICAL AND ELECTRONICS SYSTEMS 9 0 General electrical circuits. Battery, Starting motor, DC generator, Alternator, Ignition circuit, Dash instrumentation, Lighting system. Passenger comfort - Safety and security - HVAC - Seat belts - Air bags - Autor Electronics - Electronic Control Unit (ECU) - Variable Valve Timing (VVT) - Active Suspension System (FCS) - General electronic Brake Distribution (EBD) - Electronic Stability Program (ESP) Traction Control System (TCS) - General Control					
Electronic Engine Management systems for SI and CI engines. Liquid and gaseous alternate fuels - Alcohol, LPG, and Hydrogen. UNIT III TRANSMISSION AND SUSPENSIONS SYSTEMS 9 0 Transmission system: Clutches - principle, types - single plate clutch, multiplate clutch, magnetic and centre clutches, fluid fly wheel. Gear boxes, types, constant mesh, synchromesh gear boxes, epicyclic gear boxes transmission, continuous variable transmission, propeller shaft, Hotch-Kiss drive, Torque tube drive, universal differential, rear axles types, wheels and tyres; Suspension system: Objects of suspension systems, rigid axle suspension bar, shock absorber, independent suspension system UNIT IV BRAKING AND STEERING SYSTEMS 9 0 Forces on vehicles, tyre grip, load transfer, braking distribution between axles, stopping distance, Types of st systems - Ackermann principle, Davis steering gear, steering gear boxes, steering linkages, power steering, geometry-caster, camber toe-in, toe out etc., wheel Alignment and balancing. UNIT V ELECTRICAL AND ELECTRONICS SYSTEMS 9 0 General electrical circuits. Battery, Starting motor, DC generator, Alternator, Ignition circuit, Dash instrumentation, Lighting system. Passenger comfort - Safety and security - HVAC - Seat belts - Air bags - Autor Electronics - Electronic Control Unit (ECU) - Variable Valve Timing (VVT) - Active Suspension System (TCS) - Gelectronic Brake Distribution (EBD) - Electronic Stability Program (ESP) Traction Control System (TCS) - Gelectronic Brake Distribution (EBD) - Electronic Stability Program (ESP) Traction Control System (TCS)	0	0	0	1	9
Transmission system: Clutches - principle, types - single plate clutch, multiplate clutch, magnetic and centre clutches, fluid fly wheel. Gear boxes, types, constant mesh, synchromesh gear boxes, epicyclic gear box transmission, continuous variable transmission, propeller shaft, Hotch-Kiss drive, Torque tube drive, universal differential, rear axles types, wheels and tyres; Suspension system: Objects of suspension systems, rigid axle suspension bar, shock absorber, independent suspension system UNIT IV BRAKING AND STEERING SYSTEMS Porces on vehicles, tyre grip, load transfer, braking distribution between axles, stopping distance, Types of brakenanical, Hydraulic, Air brakes, Disc & Drum brakes, Engine brakes anti-lock braking system. Types of st systems - Ackermann principle, Davis steering gear, steering gear boxes, steering linkages, power steering, geometry-caster, camber toe-in, toe out etc., wheel Alignment and balancing. UNIT V ELECTRICAL AND ELECTRONICS SYSTEMS Pollowing System: Passenger comfort - Safety and security - HVAC - Seat belts - Air bags - Autor Electronics - Electronic Control Unit (ECU) - Variable Valve Timing (VVT) - Active Suspension System (A Electronic Brake Distribution (EBD) - Electronic Stability Program (ESP) Traction Control System (TCS) - Control Control Control System (TCS) - Control Control System (TCS) - Control Control Control Control System (TCS) - Control					
clutches, fluid fly wheel. Gear boxes, types, constant mesh, synchromesh gear boxes, epicyclic gear box transmission, continuous variable transmission, propeller shaft, Hotch-Kiss drive, Torque tube drive, universal differential, rear axles types, wheels and tyres; Suspension system: Objects of suspension systems, rigid axle suspension bar, shock absorber, independent suspension system UNIT IV BRAKING AND STEERING SYSTEMS 9 0 Forces on vehicles, tyre grip, load transfer, braking distribution between axles, stopping distance, Types of braken and types of the systems - Ackermann principle, Davis steering gear, steering gear boxes, steering linkages, power steering, geometry-caster, camber toe-in, toe out etc., wheel Alignment and balancing. UNIT V ELECTRICAL AND ELECTRONICS SYSTEMS 9 0 General electrical circuits. Battery, Starting motor, DC generator, Alternator, Ignition circuit, Dash instrumentation, Lighting system. Passenger comfort - Safety and security - HVAC - Seat belts - Air bags - Autor Electronics - Electronic Control Unit (ECU) - Variable Valve Timing (VVT) - Active Suspension System (A Electronic Brake Distribution (EBD) - Electronic Stability Program (ESP) Traction Control System (TCS) - October 10 (TCS) - Oct	0	0	0	ı	9
Forces on vehicles, tyre grip, load transfer, braking distribution between axles, stopping distance, Types of br Mechanical, Hydraulic, Air brakes, Disc & Drum brakes, Engine brakes anti-lock braking system. Types of st systems - Ackermann principle, Davis steering gear, steering gear boxes, steering linkages, power steering, geometry-caster, camber toe-in, toe out etc., wheel Alignment and balancing. UNIT V ELECTRICAL AND ELECTRONICS SYSTEMS 9 0 General electrical circuits. Battery, Starting motor, DC generator, Alternator, Ignition circuit, Dash instrumentation, Lighting system. Passenger comfort - Safety and security - HVAC - Seat belts - Air bags - Autor Electronics - Electronic Control Unit (ECU) - Variable Valve Timing (VVT) - Active Suspension System (ACC) - Control Brake Distribution (EBD) - Electronic Stability Program (ESP) Traction Control System (TCS) - Control System	aut join	x, a	k, ai 1 joi	au joir	ito nt,
Mechanical, Hydraulic, Air brakes, Disc & Drum brakes, Engine brakes anti-lock braking system. Types of st systems - Ackermann principle, Davis steering gear, steering gear boxes, steering linkages, power steering, geometry-caster, camber toe-in, toe out etc., wheel Alignment and balancing. UNIT V ELECTRICAL AND ELECTRONICS SYSTEMS 9 0 General electrical circuits. Battery, Starting motor, DC generator, Alternator, Ignition circuit, Dash instrumentation, Lighting system. Passenger comfort - Safety and security - HVAC - Seat belts - Air bags - Autor Electronics - Electronic Control Unit (ECU) - Variable Valve Timing (VVT) - Active Suspension System (AC) Electronic Brake Distribution (EBD) - Electronic Stability Program (ESP) Traction Control System (TCS) - Control Syste	0	0	0		9
General electrical circuits. Battery, Starting motor, DC generator, Alternator, Ignition circuit, Dash instrumentation, Lighting system. Passenger comfort - Safety and security - HVAC - Seat belts - Air bags - Autor Electronics - Electronic Control Unit (ECU) - Variable Valve Timing (VVT) - Active Suspension System (A Electronic Brake Distribution (EBD) - Electronic Stability Program (ESP) Traction Control System (TCS) - Control System (TCS) - Control System (TCS) - Control System (TCS)	eerin	steer	teer	erii	ng
instrumentation, Lighting system. Passenger comfort - Safety and security - HVAC - Seat belts - Air bags - Autor Electronics - Electronic Control Unit (ECU) - Variable Valve Timing (VVT) - Active Suspension System (A Electronic Brake Distribution (EBD) - Electronic Stability Program (ESP) Traction Control System (TCS) - (Control System (TCS))	0	0	0	0	9
	notiv SS)	mot ASS	mot ASS	otiv SS)	ive) -
Total (45L) = 45Pe	riod	eric	erio	ioi	ds

TEXT I	BOOKS:							
1.	William. H. Crouse, Donald L Anglin, Automotive Mechanics, 10th Edition, McGraw-Hill, 2017							
2.	ack Erjavek, "Automotive Technology – A Systems Approach", Thomson Learning, 3rd Edition, 1999.							
REFER	ENCES:							
1	Bosch Automotive Hand Book, 8th Edition, Bentley Publishers, 2011.							
2	Kirpal Singh, Automobile Engineering, Vol.1 &2, Standard Publishers, 2012.							

3	N. K. Giri, Automobile Mechanics, 5 th Edition, Khanna Publishers, 2014.						
4	Kumar D.S., "Automobile Engineering", S.K.Kataria and Sons, 2nd Edition, 2017.						
5	Robert Bosch GmbH, "Automotive Handbook", Robert Bosch, 2004.						
E-REFE	C-REFERENCES:						
1.	http://www.engineeringstudymaterial.net/tag/automotive-engineering-books						
2.	https://www.studynama.com//299-Automobile-engineering-lecture-notes-ebook-pdf						
3.	https://onlinecourses.nptel.ac.in/noc21_de02/preview						

	E OUTCOMES: upletion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Describe the fundamental concepts of automobile engineering	Understand
CO2	Analyze the various types of power train and fuel supply and management systems.	Analyze
СОЗ	Analyze the various types of automatic transmission and steering systems for a vehicle.	Analyze
CO4	Discuss various types of braking and suspension system.	Understand
CO5	Troubleshoot the electrical and electronics instrumentation system in the automobiles.	Understand

COURSE .	ARTI	CULA	ATIO	N MA	TRIX	<u> </u>									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	2	0	1	0	0	0	2	2	0	3	0
CO2	3	3	3	3	2	0	1	0	0	0	2	2	0	3	0
CO3	3	3	3	3	2	0	1	0	0	0	2	2	0	3	0
CO4	3	3	3	3	2	0	1	0	0	0	2	2	0	3	0
CO5	3	3	3	3	2	0	1	0	0	0	2	2	0	3	0
Avg	3	3	3	3	2	0	1	0	0	0	2	2	0	3	0
	•	•	3/2/1	– indi	cates	streng	th of co	orrelati	on (3 -	high, 2	- mediu	m, 1- low	7)	•	

22MEPE12	COMPOSITE MATERIALS		SE	MES	TEF	ł VI
PREREQU	ISITES	CATEGORY	PE	Cro	edit	C
1. Engineerii	ng Physics	**	L	Т	P	TI
2. Engineerin	ng Chemistry	Hours/Week	3	0	0	3
COURSE C	DBJECTIVES:		u .	II.		
1. To pro	vide knowledge on the advantages of use of different types of compo	osites.				
2. To intapplica	roduce the advantages of the use of different types of compositions	ites, their manufac	cturing	, prop	pertie	s ar
3. To ma	ke them aware the manufacturing and testing methods of composites					
UNIT I	INTRODUCTION TO COMPOSITES		9	0	0	9
types of comp	nt – Particle reinforced composites-Fibre reinforced composites-Reposites. METAL MATRIX COMPOSITES	ne of mixtures- Ap	plication 9	ons of	0	ous 9
Matrix Comp	, Reinforcements – particles – fibres, Effect of reinforcement - V posites, Characteristics of MMC, Alloy vs. MMC, Advantages and der metallurgy process - diffusion bonding – stir casting – squeeze c CERAMIC MATRIX COMPOSITES	nd limitations of M				
Ceramic mat oxide – Silice	ceramic materials – Properties – Advantages – Limitations – Morix - Various types of Ceramic Matrix composites- oxide ceramic on nitride – Reinforcements – particles- fibres- whiskers. Sintering sostatic Pressing (HIP).	s - Non oxide Cer	amics	– Alı	umini	ium
UNIT IV	POLYMER MATRIX COMPOSITES		9	0	0	9
non-woven raprocesses – 0	rix resins – Thermosetting resins, thermoplastic resins – Reinforcen andom mats – Various types of fibres. Methods for producing PN Compression moulding – Reinforced reaction injection moulding - ding – Injection moulding. Fibre Reinforced Plastics (FRP), Glass fi	IC - Hand layup p Resin transfer mou	rocesso	es – S – Pult	Spray	up
UNIT V	TESTING OF COMPOSITES AND INTRODUCTION COMPOSITES	OF NANO	9	0	0	9
	testing, Property evaluation at laminate level, NDT techniques. Nar o clay composites and polymer-carbon nanotubes composites.	no particle dispersio	n in po	olyme	r mat	rix,
		Total	(45L)	= 45]	Perio	ods
Text Books:						
1. R.M.	Jones, Mechanics of Composites, 2nd ed., Taylor & Francis, 1999					
2. Math	news F.L. and Rawlings R.D., "Composite materials: Engineering an	d Science", Chapma	an and	Hall,	Lond	on,

Text I	Books:
1.	R.M. Jones, Mechanics of Composites, 2nd ed., Taylor & Francis, 1999
2.	Mathews F.L. and Rawlings R.D., "Composite materials: Engineering and Science", Chapman and Hall, London, England, 2006
Refere	ences:
1.	Chawla K.K., "Compositematerials", Springer –Verlag, 2012
2.	Clyne T.W. and Withers P.J., "Introduction to Metal Matrix Composites", Cambridge University Press, 2003.
3.	Strong A.B., "Fundamentals of Composite Manufacturing", SME, 2008
4	P.M. Ajayan, L. Schadler, P.V. Braun "Nano Composite Science and Technology", Wiley VCH, 2003.
5	C. Seferis, L. Nicolais, (Eds.) The Role of the Polymeric Matrix in the Processing and Structural Properties of Composite Materials, Plenum Press, New York 1983.

E-References:

1. NPTEL Courses.

	OUTCOMES: pletion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Identify the various matrices, reinforcements and their combinations in composite materials and select composite materials for suitable applications.	Remember
CO2	Develop suitable Metal Matrix Composites.	Apply
CO3	Identify perfect Ceramic Matrix Composites for high temperature applications.	Remember
CO4	Choose various combinations of fibres and resins and select an appropriate manufacturing technique for composite materials.	Understand
CO5	Predict the appropriate characterization testing methods for different classes of composites and manufacturing process, application polymer nano composites.	Apply

COURSE A	RTIC	CULA	TION	MAT	ΓRIX										
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	2	1	0	2	0	1	0	0	1	0	2	2	1
CO2	2	1	1	1	0	0	1	0	0	0	1	0	2	1	0
CO3	2	1	1	1	0	0	1	0	0	0	1	0	2	1	0
CO4	2	1	1	1	0	1	1	1	0	0	1	0	2	1	0
CO5	2	2	1	1	0	1	1	1	0	0	1	0	2	2	1
Avg	2.0	1.4	1.2	1.0	0.0	0.8	0.8	0.6	0.0	0.0	5.0	0.0	2.0	1.4	0.4
	•		3/2/	1 – ind	licates	strengt	h of co	orrelatio	n (3 –	high, 2-1	medium,	1- low)			

	E13	COMPUTER INTEGRATED MANUFACTURIN	IG	SE	MES	TER	VI
PRERE	QUI	SITES C.	ATEGORY	PE	Cro	edit	3
1. Compu	uter A	ided Design, Process planning		L	Т	P	TF
2. Compu	uter A	ided Manufacturing, integration software	lours/Week	3	0	0	3
COURS	SE O	BJECTIVES:				•	•
1. To	gain	knowledge on how computers are integrated at various levels of planni	ng and manufac	turing.			
2. To	appl	y knowledge about Computer Aided Quality control and Process Planni	ing Control.				
		erstand the flexible manufacturing system and to handle the product acturing	data and variou	ıs softv	vare ı	ised i	for
4. To	o desig	gn flexible manufacturing cell after carrying out group technology					
5. To	o deve	elop and manage databases for CIM					
UNIT	Ι	INTRODUCTION		9	0	0	9
UNIT	TT	GROUP TECHNOLOGY AND COMPUTER AIDED PRO	M ILICO				
	of gro	PLANNING up technology- role of G.T. in CAD/CAM integration - part families - c	classification and				SS
and MIC planning	of gro	PLANNING	classification and T cellular ma	d codir nufacti	ng – During.	CLA Proc	SS ess
and MIC planning	of gro CLASS : - role n and s	PLANNING up technology- role of G.T. in CAD/CAM integration - part families - of S and OPITZ coding systems-facility design using G.Tbenefits of G. e of process planning in CAD/CAM integration - approaches to comp	classification and T cellular ma uter aided proce	d codir nufacti	ng – During.	CLA Proc	a.SS ess ant
and MIC planning approach UNIT Shop floautomate	of groot coded date	PLANNING up technology- role of G.T. in CAD/CAM integration - part families - of S and OPITZ coding systems-facility design using G.Tbenefits of G. e of process planning in CAD/CAM integration - approaches to compagenerative approaches - CAPP and CMPP process planning systems.	classification and T cellular mauter aided process MS on methods- Ba	d codir nufacti ess plai 9	ng – During. nning	OCLA Proc -vari 0	ass ess ant
and MIC planning approach UNIT Shop floautomate	of groced dat	PLANNING up technology- role of G.T. in CAD/CAM integration - part families - of and OPITZ coding systems-facility design using G.Tbenefits of G. e of process planning in CAD/CAM integration - approaches to compregenerative approaches - CAPP and CMPP process planning systems. SHOP FLOOR CONTROL AND INTRODUCTION OF FM ontrol-phases -factory data collection system -automatic identification at collection system. FMS-components of FMS - types -FMS worksta	classification and T cellular mauter aided process MS on methods- Battion -material h	d codir nufacti ess plai 9	ng – During. nning	OCLA Proc -vari 0	SS ess ant
and MIC planning approach UNIT Shop flo automate systems- UNIT CIM and Architect impleme	of groot CLASS TII oor coed dat FMS IV d conture	PLANNING up technology- role of G.T. in CAD/CAM integration - part families - c and OPITZ coding systems-facility design using G.Tbenefits of G. e of process planning in CAD/CAM integration - approaches to compagenerative approaches - CAPP and CMPP process planning systems. SHOP FLOOR CONTROL AND INTRODUCTION OF FN ontrol-phases -factory data collection system -automatic identification and collection system. FMS-components of FMS - types -FMS workstate layout -computer control systems-application and benefits.	classification and T cellular mauter aided process MS on methods- Battion -material had be considered by the constant of	d codir nufacti ess plan g ar code nandlin GIM man	ng – During. nning	OCLA Proc -vari 0 anolog stora 0 Systent-C	9 gy-age 9 em
and MIC planning approach UNIT Shop flo automate systems- UNIT CIM and Architectimpleme	of groot Canada and a second data and a second d	PLANNING up technology- role of G.T. in CAD/CAM integration - part families - of and OPITZ coding systems-facility design using G.Tbenefits of G. e of process planning in CAD/CAM integration - approaches to compregenerative approaches - CAPP and CMPP process planning systems. SHOP FLOOR CONTROL AND INTRODUCTION OF FNONTROL-phases -factory data collection system -automatic identification at a collection system. FMS-components of FMS - types -FMS workstate layout -computer control systems-application and benefits. CIM IMPLEMENTATION AND DATA COMMUNICATION of the computer control system is a collection system of the computer control systems of the computer co	classification and T cellular mauter aided process MS on methods- Battion -material had be considered by the constant of	d codir nufacti ess plan g ar code nandlin GIM man	ng – During. nning	OCLA Proc -vari 0 anolog stora 0 Systent-C	sss ess ant gy- age gy- age IM s -
and MIC planning approach UNIT Shop floautomate systems- UNIT CIM and Architectimpleme network UNIT Open systems- TOP). I	of groot Can and	planning up technology- role of G.T. in CAD/CAM integration - part families - cs and OPITZ coding systems-facility design using G.Tbenefits of G. e of process planning in CAD/CAM integration - approaches to compagenerative approaches - CAPP and CMPP process planning systems. SHOP FLOOR CONTROL AND INTRODUCTION OF FN ontrol-phases -factory data collection system -automatic identification accollection system. FMS-components of FMS - types -FMS workstate layout -computer control systems-application and benefits. CIM IMPLEMENTATION AND DATA COMMUNICATION of the company strategy - system modeling tools -IDEF models - activity cycle (CIMOSA) - manufacturing enterprise wheel-CIM architecture on software. Communication fundamentals- local area networks -togement and installations.	classification and T cellular manuter aided process MS on methods- Battion -material had be	d codir nufactivess plan 9 ar code andlin CIM a man imple 9 ffice pri mode	o o o o o o o o o o o o o o o o o o o	OCLA Proc -vari 0 Syst ent-C ation 0 I (M	sSS ess ant 9 gy-age 9 AP

TEXT	T BOOKS:
1.	Mikell.P.Groover, "Automation, Production Systems and Computer Integrated Manufacturing", Pearson Education, 2008.
2.	Roger Hanman, "Computer Integrated Manufacturing", Addison –Wesley, 1997
REFI	ERENCES:
1.	Ranky and Paul G., "Computer Integrated Manufacturing", Prentice Hall International 1986
2.	David D.Bedworth, Mark R.Hendersan and Phillip M.Wolfe, "Computer Integrated Design and Manufacturing", McGraw Hill Inc, 1998.

3.	Kant Vajpayee S, "Principles of Computer Integrated Manufacturing", Prentice Hall India,2003
4.	Mikell. P.Groover and Emory ZimmersJr, "CAD/CAM", Prentice Hall of India Pvt. Ltd, 1998
5.	Yoremkoren, "Computer Integrated Manufacturing system", McGraw-Hill, 1983.

	OUTCOMES: pletion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Recognize the manufacturing activities interrelated with computers.	Understand
CO2	Understand the concept of group technology and the various approaches of computer aided process planning	Understand
СОЗ	Explain the phases of shop floor control activities.	Understand
CO4	Apply the system modeling tools in CIM.	Apply
CO5	Explain the applications of database and system protocol	Understand

COURSE A	RTIC	CULA	TION	MA	ΓRIX										
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	0	0	0	0	0	0	0	0	1	0	1	1	1	2	3
CO2	0	0	0	0	0	0	0	0	1	0	1	0	1	2	2
CO3	0	0	1	0	0	0	0	0	1	0	1	0	1	2	2
CO4	0	1	1	1	3	0	0	0	3	2	1	0	1	1	3
CO5	0	0	1	3	2	0	0	0	2	2	1	1	1	2	2
Avg	0.0	0.2	0.6	0.8	1.0	0.0	0.0	0.0	1.6	0.8	1.0	0.4	1.0	1.8	2.4
	•	•	3/2/1 -	- indica	ates str	ength	of corr	elation	(3 – hi	gh, 2- me	dium, 1-	low)	•		•

22MF	EPE14	DESIGN OF TRANSMISSION SYSTEM	A	SE	MES	TER	VI
PREF	REQUI	ISITES	CATEGORY	PE	Cre	edit	3
1.Stud	lent shou	uld study kinematic of machinery	***	L	Т	P	TH
2. Stud	dent sho	ould study Design of machine elements.	Horus/Week	3	0	0	3
COU	IRSE C	OBJECTIVES:			1		ı
1.	To ga	ain knowledge on the principles and procedures for the design of m	echanical power tran	smissi	on cor	npon	ents.
2.	To ur	nderstand the standard procedures available for design of transmissi	on elements.				
3.	To so	olve the problems for the real time applications of the systems					
4.	Desig	gning multi speed gear box for machine tool and automotive applica	ations.				
5.	Desig	gning clutch and brake systems for engineering applications.					
UNI	ΤΙ	DESIGN OF FLEXIBLE ELEMENTS		9	0	0	9
		capacity for various applications - Design of Flat belts and pulle vire ropes and pulleys – Design of Transmission chains and Sprock		belts	and sl	neave	s –
Select	IOII OI W	The representation of the residue of					
UNIT		SPUR AND HELICAL GEARS		9	0	0	9
UNIT	Γ II material r of safe		ratios, number of tee	eth, Fat	igue s	streng	gth,
UNIT	Γ II material r of safe le - norr	SPUR AND HELICAL GEARS s - Design of straight tooth spur & helical gears based on speed a ety, strength and wear considerations. Force analysis -Tooth stress	ratios, number of tee	eth, Fat	igue s	streng	gth,
UNIT Gear 1 Factor Modul UNIT Straigl	material r of safe le - norr r III ht bevel nensions	SPUR AND HELICAL GEARS Is - Design of straight tooth spur & helical gears based on speed a ety, strength and wear considerations. Force analysis -Tooth stress mal and transverse, Equivalent number of teeth - forces.	ratios, number of tee ses - Dynamic effe s, equivalent numbe	eth, Fat cts - H	tigue s lelical 0 eth, es	streng gear 0	gth, s –
Gear in Factor Moduli UNIT Straigh	material r of safe le - norr III ht bevel nensions es, effici	SPUR AND HELICAL GEARS Is - Design of straight tooth spur & helical gears based on speed a ety, strength and wear considerations. Force analysis -Tooth stressmal and transverse, Equivalent number of teeth - forces. BEVEL AND WORM GEARS I gear: Gear materials - Tooth terminology, tooth forces and stresses of straight bevel gears. Worm Gear: Gear materials - Tooth terminology.	ratios, number of tee ses - Dynamic effe s, equivalent numbe	eth, Fat cts - H	tigue s lelical 0 eth, es	streng gear 0	gth, s –
UNIT Gear in Factor Moduli UNIT Straigh of dim stresse UNIT Need Ray d	material r of safe le - norr III ht bevel nensions es, effici IV - Design liagram,	SPUR AND HELICAL GEARS Is - Design of straight tooth spur & helical gears based on speed a lety, strength and wear considerations. Force analysis -Tooth stressmal and transverse, Equivalent number of teeth - forces. BEVEL AND WORM GEARS I gear: Gear materials - Tooth terminology, tooth forces and stresses of straight bevel gears. Worm Gear: Gear materials - Tooth terminology, estimation of dimensions of worm gear pair.	ratios, number of teeses - Dynamic effects, equivalent number minology, Thermal metric progression - f multi speed gear between the second sec	eth, Father Fath	o leth, esty, for our steel	o timat rees a	9 ion and 9
UNIT Gear in Factor Moduli UNIT Straigh of dim stresse UNIT Need Ray d	material r of safe le - norr III ht bevel nensions es, effici IV - Design liagram, eations, V	SPUR AND HELICAL GEARS Is - Design of straight tooth spur & helical gears based on speed a ety, strength and wear considerations. Force analysis -Tooth stressmal and transverse, Equivalent number of teeth - forces. BEVEL AND WORM GEARS I gear: Gear materials - Tooth terminology, tooth forces and stresses of straight bevel gears. Worm Gear: Gear materials - Tooth terminology, estimation of dimensions of worm gear pair. GEAR BOXES In of sliding and constant mesh gear boxes: Speed selection - Georgian with the side of teeth. Design of the side of the side of teeth.	ratios, number of teeses - Dynamic effects, equivalent number minology, Thermal metric progression - f multi speed gear between the second sec	eth, Father Fath	o leth, esty, for our steel	o timat rees a	9 ion and 9
UNIT Gear in Factor Moduli UNIT Straigh of dim stresse UNIT Need Ray dapplic UNIT Design Design	material r of safe le - norr III ht bevel nensions es, effici IV - Design liagram, eations, V IV n of sing n of bra	SPUR AND HELICAL GEARS Is - Design of straight tooth spur & helical gears based on speed of the ety, strength and wear considerations. Force analysis -Tooth stress and and transverse, Equivalent number of teeth - forces. BEVEL AND WORM GEARS I gear: Gear materials - Tooth terminology, tooth forces and stresses of straight bevel gears. Worm Gear: Gear materials - Tooth terminology, estimation of dimensions of worm gear pair. GEAR BOXES In of sliding and constant mesh gear boxes: Speed selection - Georgian with the speed gear box, Fluid Couplings, Torque Converters for an analysis - Tooth terminology tooth forces and stresses and stresses are straight bevel gears.	ratios, number of teeses - Dynamic effectses - Dynamic effects, equivalent number minology, Thermal metric progression - f multi speed gear but to a clutches and Elect expanding shoe brak	eth, Fatets - H 9 r of tee capaci Standa ox for ns. 9 romagnes and	o eth, es ty, for o ard ste mach	0 timat cress a 0 p ratiiine t	9 9 9 9 9 9 9 9

1.	Joseph Shigley, Charles Mischke, Richard Budynas and Keith Nisbett "Mechanical Engineering Design", 10th Edition, Tata McGraw-Hill, 2014.
2.	Sundararajamoorthy T. V and Shanmugam. N, "Machine Design", 9th edition, Anuradha Publications, Chennai, 2003.
REFE	ERENCES:
1	Bhandari V, "Design of Machine Elements", 15th Reprint, Tata McGraw-Hill Book Co, 2014.
2	Prabhu. T.J., "Design of Transmission Elements", Mani Offset, Chennai, 2003. Md. Jalaludeen, Machine Design, Volume II, Design of Transmission Systems, 4th edition, Anuradha Publications, 2014.
3	GitinMaitra,L. Prasad "Handbook of Mechanical Design", 2nd Edition, Tata McGraw-Hill,2001.
4	C.S.Sharma, KamleshPurohit, "Design of Machine Elements", Prentice Hall of IndiaPvt. Ltd., 2003.

TEXT BOOKS:

5	Bernard Hamrock, Steven Schmid, Bo Jacobson, "Fundamentals of Machine Elements",2nd Edition, Tata McGraw Hill, 2006.
E-REF	ERENCES:
1.	https://archive.nptel.ac.in/courses/112/101/112101304/
2.	http://www.velhightech.com/Documents/ME8651 Design of Transmission Systems.pdf
3.	https://civildatas.com/download/design-of-transmission-elements-by-t-j-prabhu

	E OUTCOMES: upletion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Appreciate the functions of various transmission elements and their assemblies	Understand
CO2	Design different transmission components according to the requirement as per standards using data books.	Analyze
СОЗ	Apply the appropriate calculation procedures for the various systems designing	Apply
CO4	Design multi speed gear box for machine tool and automotive applications.	Analyze
CO5	Design clutch and brake systems for engineering applications.	Analyze

COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
			100			100	107				1011				1500
CO1	2	2	1	2	0	1	1	0	0	0	1	0	3	2	1
CO2	2	2	1	2	0	1	1	0	0	0	1	0	3	2	1
CO3	2	2	1	2	0	1	1	0	0	0	1	0	3	2	1
CO4	2	2	1	2	0	1	1	0	0	0	1	0	3	2	1
CO5	2	2	1	2	0	1	1	0	0	0	1	0	3	2	1
Avg	2	2	1	2	0	1	1	0	0	0	1	0	3	2	1

22MEPE15	ENERGY CONVERSION IN INDUSTRIE	ES	SE	MES	TER	VI			
PREREQU	SITES	CATEGORY	PE	Cre	edit	3			
1.Thermal En	gineering	II / XV I-	L	T	P	TH			
2.Thermal sto	rage system	Hours/Week	3	0	0	3			
COURSE (DBJECTIVES:								
1. Analyz	Analyzing the thermodynamic cycles used in power generation								
2. Evalua	2. Evaluating the merits of direct thermal energy conversion systems compared to conventional techniques								
3. Analyz	ing the performance of fuel cells								
4. Selecti	4. Selecting the best energy storage mechanism for any given application								
5. Develo	5. Developing a mechanism for total energy recovery from a system adopting CHCP concept								
UNIT I ENERGY CONVERSION CYCLES 9 0									
Bell Coleman Brayton cycle	, Scuderi, Stirling, Ericsson, Lenoir, Atkinson, Stoddard and Kalinass.	a cycle – Compariso	on with	Rank	kine a	and			
UNIT II	DIRECT CONVERSION OF THERMAL TO ELECTRI	CAL ENERGY	9	0	0	9			
	noelectric Converters – Thermoelectric refrigerator – Thermoelectr converter – Nernst Effect Generator – Thermo Magnetic Converter	ic Generator – Ther	mionio	conv	erter	s –			
UNIT III	DIRECT CONVERSION OF CHEMICAL TO ELECTR	ICAL ENERGY	9	0	0	9			
	sics – working advantages and drawbacks – types – comparative an ess – performance of fuel cell – applications	alysis – thermodyna	mics a	nd kir	netics	of			
UNIT IV	ENERGY STORAGE SYSTEMS		9	0	0	9			
	pes – working – performance governing parameters – hydrogen ene al Energy, Electrical Energy, Chemical Energy, Thermal Energy.	rgy – solar cells. En	ergy st	orage	devi	ces			
UNIT V	COMBINED HEAT, COOLING AND POWER PRODUC	CTION (CHCP)	9	0	0	9			
	- types - Configuration and thermodynamic performance of steareration systems – reciprocating IC engines cogeneration systems – compared to the compared to th			ystem	ıs – ş	gas			
	Total (45L) = 45Periods								

TEXT I	BOOKS:						
1.	Archie.W.Culp, Principles of Energy Conversion, 2 nd Edition, McGraw-Hill Inc., 1991, New York						
2.	Kordesch Karl, and Günter R. Simader, Fuel Cell and Their Applications, Wiley 2006						
REFER	REFERENCES:						
1	Bent Sorensen, Renewable Energy Conversion, Transmission, and Storage Technology & Engineering, Academic Press, 2007.						
2	Charles R. Russell, Elements of Energy Conversion, Permagon Press, 1967						
3	Hart A.B. and Womack, G.J., Fuel Cells: Theory and Application, Prentice Hall, 1989						
4	Kettari, M.A., Direct Energy Conversion, Addison-Wesley, 1997						
5	Yogi Goswami, D. and Frank Kreith, Energy Conversion, Second Edition, Science, 2017.						
E-REFE	RENCES:						
1.	https://energyeducation.ca/encyclopedia/Energy_conversion_technology						
2.	https://ioe.iitm.ac.in/program/energy-systems/						
3.	https://www.industrytap.com/industrial-energy-conversion-transfer-efficiencies-trending/39616						

	E OUTCOMES: npletion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Analyze the thermodynamic cycles used in power generation	Analyze
CO2	Evaluate the merits of direct thermal energy conversion systems compared to conventional techniques	Apply
СОЗ	Analyze the performance of fuel cells	Analyze
CO4	Select the best energy storage mechanism for any given application	Understand
CO5	Develop a mechanism for total energy recovery from a system adopting CHCP concept	Understand

COURSE A	OURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	1	1	0	1	0	0	0	0	0	2	1	1
CO2	3	2	2	1	1	1	0	0	0	0	0	0	2	1	1
CO3	3	3	3	1	1	1	1	0	0	0	0	0	2	1	1
CO4	2	2	3	1	1	1	1	0	0	0	0	0	2	1	1
CO5	2	2	2	2	1	1	1	0	0	0	0	0	2	1	1
Avg	2.6	2.2	2.4	1.2	1.0	0.8	0.8	0.0	0.0	0.0	0.0	0.0	2	1	1
			3/2/1	l – ind	icates	streng	gth of	correla	tion (3	– high,	2- medi	um, 1- lo	ow)		

22MEPE	16	GAS DYNAMICS AND JET PROPULSION	ON	SE	MES	TER	VI
PREREC	QUI	SITES	CATEGORY	PE	Cr	edit	C
1.Basic kr	owl	edge in laws and principles of thermodynamics		L	Т	P	ТН
2.Fundan	enta	al concepts about turbo machines and compressible flow	Hours/Week	3	0	0	3
COURS	E O	BJECTIVES:	1	I	1	1	
1. Stu	Studying the basic concepts of compressible fluid flow and isentropic flow						
2. Lea	ırnin	g about the flow through ducts and various flow parameters					
3. Dis	cuss	ing various flow parameters of normal and oblique shocks					
4. Un	ders	tanding the concept of jet propulsion and its performance analysis					
5. Stu	dyin	g about space propulsion concept and evaluating its performance p	arameters				
UNIT	[BASIC CONCEPTS OF FLUID FLOW		9	0	0	9
		omentum equations of compressible fluid flows – Stagnation state per on compressibility. Isentropic flows: Isentropic flow through va		Mach	cone	– Eff	ect
UNIT	II	ISENTROPIC FLOW		9	0	0	9
with heat	tran	users, compressors and turbines – Use of Gas tables. Flow through sfer (Rayleigh flow) and Friction (Fanno flow) – Variation of flows dynamics.					
UNIT	II	NORMAL AND OBLIQUE SHOCKS		9	0	0	9
		uations – Variation of flow parameters across the normal and oblesupersonic flow, Use of table and charts – Applications	ique shocks – Prand	ltl Mey	er re	lation	s –
UNIT	V	JET PROPULSION		9	0	0	9
	ind	propulsion – Thrust equation – Thrust power and propulsive e use of stagnation state performance of ram jet, turbojet, turbo					
UNIT V SPACE PROPULSION 9							
		et engines – Propellants – Ignition and combustion – Theory of reminal and characteristic velocity – Applications – Space flights	ocket propulsion – l	Perforn	nance	stud	y –
			TOTAL (45	L) = 4	5PE	RIO	DS

TEX	T BOOKS:
1.	John D. Anderson Jr. – 'Modern Compressible Flow with historical perspective' – McGraw Hill Publishing company – International Edition – 1990 – 2nd Edition
2.	Yahya S. M. – 'Compressible Flow' – Tata McGraw Hill India – 2009
REFI	ERENCES:
1	Balachandran P 'Fundamentals of Compressible Fluid Dynamics' - PHI Learning India Private Ltd 2009
2	Cohen H., Rogers G. E. and Saravanamuttoo – 'Gas Turbine Theory' – Longman – 1980
3	Sutton G. P 'Rocket Propulsion Elements' - John Wiley, New York - 1986
4	Shapiro A. H. – 'Dynamics and Thermodynamics of Compressible Fluid Flow – Vol.I' – John Wiley, New York – 1953
5	Radhakrishnan E. – 'Gas Dynamics' – Prentice-Hall of India Pvt. Ltd – 2004
E-REI	FERENCES:
1.	https://nptel.ac.in/courses

	E OUTCOMES: upletion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Describe the compressible fluid flow and isentropic flow through various ducts	Understand
CO2	Calculate the flow properties of isentropic flow using gas tables and charts	Analyze
CO3	Differentiate normal and oblique shocks and determine their performance parameters	Understand
CO4	Explain the theory of jet propulsion and calculate the operating parameters of various jet engines	Understand
CO5	Illustrate the theory of rocket engines and determine their performance indicators	Understand

COURSE A	ARTIO	CULA	ATIO	N MA	TRIX										
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	0	0	1	1	0	1	1	0	0	1	0	0	0	0	0
CO2	1	1	0	0	1	0	0	1	0	0	0	0	1	1	1
CO3	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
CO4	0	0	1	1	0	0	0	0	0	0	0	0	0	0	0
CO5	0	0	1	1	0	1	1	0	0	0	0	1	0	0	0
Avg	0.2	0.2	0.6	0.6	0.2	0.4	0.4	0.2	0.0	0.2	0.0	0.2	0.2	0.2	0.2
	Avg 0.2 0.6 0.6 0.2 0.4 0.4 0.2 0.0 0.2 0.0 0.2 0														

22M	EPE17	RENEWABLE ENERGY SYSTEM		SE	MES	TER	VI			
PRE	REQUIS	ITES	CATEGORY	PE	Cro	edit	ТН			
Basic	idea abou	t solar radiation and other renewable energy that exists.	TT /557 1	L	T	P	С			
Unde	rstanding a	bout various chemical reactions occur in the process	Hours/Week	3	0	0	3			
Cou	rse Objec	tives:			•	•				
1.	To recognize the consciousness of energy conservation in scholars									
2.	To identi	fy the employ of renewable energy sources for electrical power ge	eneration							
3.	To collec	t different energy storage methods								
4.	To detect	about environmental effects of energy conversion								
U	NIT I	SOLAR ENERGY		9	0	0	9			
Ther	mal Applic	ermal collectors and storage: Thermal energy, Chemical Energy rations-Solar thermal power plant-Solar Photo voltaic Conversion neating and cooling, Solar distillation, Solar pumping, Solar furnation wind Energy	n-Solar cell-PV appl							
		ind Energy Conversion-Site Selection Considerations-Wind Ener of WECS-Wind Energy Collectors Interconnected System Environ		em-Ao	lvanta	iges a	ınd			
Ul	NIT III	BIO ENERGY		9	0	0	9			
plant	s-Bio gas	ersion Technologies- Direct combustion – Thermo-chemical – Efrom plant wastes-Site selection Problems related to Bio gas plass - Alternative liquid fuels -Advantages and Disadvantages of Bio	ants- factors affecting	ıg bio-	gener	ation				
UI	NIT IV	ENERGY FROM THE OCEANS		9	0	0	9			
Com	ponents o	Electric Conversion- Open and Closed cycle; Energy from Tidal power plants- operation methods of utilization of vave-Energy Conversion Devices-Hybrid System.								
U	NIT V	GEOTHERMAL ENERGY AND FUEL CELLS		9	0	0	9			
thern Disac	nal system dvantages-	arces – hydrothermal geothermal resources, geopressurised resources, Magma resources – Comparison of flashed steam and Applications of Geothermal Energy; Design and principle operatuel cells, Advantages, disadvantages and applications of fuel cells	total flow concept tion of a Fuel cells, or	- Ad	vanta	ges a	and			

Text	t Books:						
1.	G.D. Rai, "Non-Conventional Energy Sources", Khanna publishers, 2017						
2.	Suhas P. Sukhatme, "Solar Energy", Tata McGraw Hill Publishing Company Ltd., 2007.						
3.	Sunil S. Rao, B. B. Parulekar, "Energy Technology (Non-Conventional, Renewable And Conventional)", Khanna publishers 2002.						
Refe	References:						
1	Twidell, J.W. & Weir, A., "Renewable Energy Resources", EFN Spon Ltd., UK, 2005.						
2	Tiwari, G.N., "Solar Energy -Fundamentals Design, Modelling and applications", Alpha Science Intl Ltd, 2015.						
3	Khan, B.H., "Non-Conventional Energy Resources", The McGraw Hill Companies, 2009.						
4	Godfrey Boyle, "Renewable Energy", Power for a Sustainable future, Oxford University Press,1996.						
5	Johnson Gavy L, "Wind Energy Systems", Prentice Hall, 1985.						

E-Re	E-References:							
1.	https://www.sciencedirect.com/book/9780128200049/renewable-energy-systems							
2.	https://en.wikipedia.org/wiki/Renewable_energy							
3.	Ellabban, Omar; Abu-Rub, Haitham; Blaabjerg, Frede (2014). "Renewable energy resources: Current status, future prospects and their enabling technology". Renewable and Sustainable Energy Reviews. 39: 748–764 [749]							

	E OUTCOMES: npletion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Impart knowledge about solar energy harvesting techniques and its storage system	Understand
CO2	Enhance insight into different wind energy methods to generate electricity.	Understand
СОЗ	Enrich the scholars to inculcate paramount energy conversion technologies and problems related to bio gas plants	Understand
CO4	Reveals the notion of obtaining abundant energy from the oceans	Understand
CO5	Impart knowledge about geothermal energy and fuel cells	Understand

COURSE A	DURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	3	2	1	0	2	2	3	1	1	2	2	1	3
CO2	1	2	3	2	1	0	2	2	3	1	1	2	2	1	3
CO3	0	2	3	2	1	0	2	2	3	1	1	2	2	1	3
CO4	1	2	3	2	0	0	2	2	3	1	1	2	2	1	3
CO5	1	2	3	2	1	0	2	2	3	1	1	2	2	1	3
Avg	0.8	2.0	3.0	2.0	0.8	0.0	2.0	2.0	3.0	1.0	1.0	2.0	2.0	1.0	3.0
	1	1	3/2/	/1 – inc	licates	stren	gth of	correla	tion (3	– high,	2- medi	ım, 1- lo	w)	I	

PROFESSIONAL ELECTIVES - II

22MEPE21	ADVANCED STRENGTH OF MATERIA	LS	SE	MES	TER	VI							
PREREQU	ISITES	CATEGORY	PE	Cre	edit	3							
			L	Т	P	TH							
Engineering	Mechanics and Strength of Materials	Hours/Week	3	0	0	3							
COURSE (DBJECTIVES:		•										
1. To pro	ovide basic knowledge in mechanics of materials to solve real engines	neering problems and	d desig	n eng	ineer	ing							
2. To det of load	• • •	ine the mechanical behavior of the body by determining the stresses, strains produced by the application											
3. To lea	rn about radial and tangential stresses in thick cylinders and rotating	disks											
4. To stu	dy about torsion of non-circular sections												
5. To det	ermine the stresses in circular and rectangular plates due to various	types of loading and	end co	nditio	ons								
3. 10 det	UNIT I ELASTICITY 9 0 0												
UNIT I Stress – Straequation of e	nin relation and General equation of elasticity in cartesian-polar equilibrium – compact ability –boundary conditions- representation	s of three dimension	rdinate al stres	s- dif	feren	ion							
UNIT I Stress – Stra equation of e –generalized	I lin relation and General equation of elasticity in cartesian-pola	s of three dimension	rdinate al stres	s- dif	feren	tial ion							
UNIT I Stress – Stra equation of e –generalized	nin relation and General equation of elasticity in cartesian-polar equilibrium – compact ability –boundary conditions- representation Hooke's law – St.Vennant's principle – Plane strain- plane stress	s of three dimension	rdinate al stres	s- dif	feren	tial ion							
UNIT I Stress – Stra equation of e –generalized Location of s UNIT II Stresses and circumferent	nin relation and General equation of elasticity in cartesian-polary equilibrium – compact ability –boundary conditions- representation Hooke's law – St. Vennant's principle – Plane strain- plane stress hear center for various sections – shear flow.	s of three dimensions – Airy's stress fun	rdinate al stres ction.	s- diffs of a Shear	ferent tensi	tial ion re-							
UNIT I Stress – Stra equation of e –generalized Location of s UNIT II Stresses and circumferent	nin relation and General equation of elasticity in cartesian-polar equilibrium – compact ability –boundary conditions- representation. Hooke's law – St.Vennant's principle – Plane strain- plane stress hear center for various sections – shear flow. UNSYMMETRICAL BENDING deflection in beams subjected to unsymmetrical loading – Kern et al and radial stresses – deflection and radial curved beam with re	s of three dimensions – Airy's stress fun	rdinate al stres ction.	s- diffs of a Shear	ferent tensi	tial ion re-							
UNIT I Stress - Straequation of e-generalized Location of s UNIT II Stresses and circumferent concentrated UNIT III Thick-walled	ain relation and General equation of elasticity in cartesian-polar equilibrium – compact ability –boundary conditions- representation Hooke's law – St. Vennant's principle – Plane strain- plane stress hear center for various sections – shear flow. UNSYMMETRICAL BENDING deflection in beams subjected to unsymmetrical loading – Kern et al and radial stresses – deflection and radial curved beam with reload and uniform load – chain link and crane hooks. THICK CYLINDERS AND ROTATING DISKS I cylinder subjected to internal and external pressures – Shrink fit all stresses in solid disc and ring of uniform thickness and varying	s of three dimensions — Airy's stress fun of a section. Curved — strained ends — clos	rdinate al stres ction. 9 flexure sed ring to rota	s- difference of a second of a	ferent tensic Cent	tial ion re- 9 rs - to 9							
UNIT I Stress – Straequation of e-generalized Location of s UNIT II Stresses and circumferent concentrated UNIT III Thick-walled and tangentia	ain relation and General equation of elasticity in cartesian-polar equilibrium – compact ability –boundary conditions- representation Hooke's law – St. Vennant's principle – Plane strain- plane stress hear center for various sections – shear flow. UNSYMMETRICAL BENDING deflection in beams subjected to unsymmetrical loading – Kern et al and radial stresses – deflection and radial curved beam with reload and uniform load – chain link and crane hooks. THICK CYLINDERS AND ROTATING DISKS I cylinder subjected to internal and external pressures – Shrink fit all stresses in solid disc and ring of uniform thickness and varying	s of three dimensions — Airy's stress fun of a section. Curved — strained ends — clos	rdinate al stres ction. 9 flexure sed ring to rota	s- difference of a second of a	ferent tensic Cent	tial ion re- 9 rs - to 9							
UNIT I Stress – Straequation of e-generalized Location of s UNIT II Stresses and circumferent concentrated UNIT III Thick-walled and tangentia shafts and cy UNIT IV Torsion of r	tin relation and General equation of elasticity in cartesian-polar equilibrium – compact ability –boundary conditions- representation Hooke's law – St. Vennant's principle – Plane strain- plane stress hear center for various sections – shear flow. UNSYMMETRICAL BENDING deflection in beams subjected to unsymmetrical loading – Kern dial and radial stresses – deflection and radial curved beam with reload and uniform load – chain link and crane hooks. THICK CYLINDERS AND ROTATING DISKS cylinder subjected to internal and external pressures – Shrink fit all stresses in solid disc and ring of uniform thickness and varying linders.	of three dimensions – Airy's stress funds – Airy's stress funds – Curved – Strained ends – Closs – Stresses due thickness – allowab	rdinate al stres ction. 9 flexure sed ring to rotale speed	s- difference of the second of	ferent tensis Cent 0 ember ected 0 - Rac Rotati	9 Itial g Jial g Jial g Jial g Jial							
UNIT I Stress – Straequation of e-generalized Location of s UNIT II Stresses and circumferent concentrated UNIT III Thick-walled and tangentia shafts and cy UNIT IV Torsion of r	tin relation and General equation of elasticity in cartesian-polar equilibrium – compact ability –boundary conditions- representation Hooke's law – St. Vennant's principle – Plane strain- plane stress hear center for various sections – shear flow. UNSYMMETRICAL BENDING deflection in beams subjected to unsymmetrical loading – Kern dial and radial stresses – deflection and radial curved beam with reload and uniform load – chain link and crane hooks. THICK CYLINDERS AND ROTATING DISKS cylinder subjected to internal and external pressures – Shrink fit all stresses in solid disc and ring of uniform thickness and varying linders. TORSION OF NON-CIRCULAR SECTIONS ectangular cross section – St. Vennant Theory – elastic membrane	of three dimensions – Airy's stress funds – Airy's stress funds – Curved – Strained ends – Closs – Stresses due thickness – allowab	rdinate al stres ction. 9 flexure sed ring to rotale speed	s- difference of the second of	ferent tensis Cent 0 ember ected 0 - Rac Rotati	9 lial ing							

Text l	Books:
1.	Arthur P.Boresi and Richard J.Schmidt, "Advanced Mechanics of Materials", 6th Edition, John Wiley &Sons-Inc., 2009.
2.	Arthur P.Boresi and Omar M.Siseborttom- "Advanced Mechanics of Materials", John Wiley International Education, 1985.
Refer	ences:
1	Robert D.Cook and Wareen.C.Yound, "Advanced Mechanics of Materials", 2nd Edition, Macmilon Publishers Company, 1985
2	Srinath.L.S, "Advanced Mechanics of Solids", Tata McGraw Hill PublishingCompany Limited, 2003

3	KrishnaRaju- N and Gururaja-D.R., "Advanced Mechanics of Solids and Structures", Narosa Publishing House, 1997.								
4	U.C.Jindal, "Advanced Topics of Strength of materials", Galgotia Publications, 1st Edition, 1997								
E-Refe	erences:								
1.	NPTEL Videos/Tutorials								

	URSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Familiarize the concepts of stress and strain at a point as well as the stress-strain relationships for homogenous, isotropic materials.	Understand
CO2	Evaluate the stresses and strains in axially-loaded members, circular torsion members, and members subject to flexural loadings.	Analyze
СОЗ	Evaluate the stresses and strains associated with thick-wall spherical and cylindrical pressure vessels.	Analyze
CO4	Evaluate the stresses in non-circular sections	Analyze
CO5	Evaluate the stresses in circular and rectangular plates due to various types of loading and end conditions	Analyze

COURSE A	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	1	1	0	0	0	1	0	0	0	0	3	2	1
CO2	2	3	3	1	0	0	0	0	0	0	0	0	3	2	1
CO3	2	3	3	2	0	0	0	1	0	0	0	0	2	3	1
CO4	2	2	2	2	2	0	1	1	0	0	1	0	3	2	1
CO5	2	2	2	2	2	0	0	1	0	0	0	0	3	2	1
Avg	2.2	2.4	2.2	1.6	0.8	0.0	0.2	0.8	0.0	0.0	0.2	0.0	2.8	2.2	1.0
3/2/1 – indi	cates st	trength	of cor	relatio	n (3 –	high, 2	- medi	um, 1-	low)						

22MEPE22	ENERGY EFFICIENT BUILDINGS DESIG	GN	SE	MES	TER	VI
PREREQUIS	ITES	CATEGORY	PE	Cre	edit	3
1.Basic knowl	edge about energy efficient technologies		L	Т	P	TI
2.Concepts of	psychometry and renewable energy technologies	Hours/Week	3	0	0	3
COURSE OB	JECTIVES:				1	
1. Explair	ing the future building aspects and need for comfort human living.					
2. Design	ng an energy efficient landscape system for pleasant living environ	ment.				
3. Develop	ing novel solutions for storage integration in buildings and will evol	ve passive building	strateg	ies.		
4. Perform	ning building load estimates and applying them real time procedure.					
5. Explair	ing the importance of renewable energy integration in buildings.					
UNIT I	INTRODUCTION TO ENERGY EFFICIENT BUILDIN	IG CONCEPTS	9	0	0	9
Future building building proce	versus energy efficient buildings – Historical perspective – Water g design aspects – Effective use of resources and needs of modern esses - Energy conservation building codes.		ssessm	ent an		
UNIT II	LANDSCAPE AND BUILDING ENVELOPES		9	0	0	9
	ent landscape design – Micro climates – various methods – Shac rials, Envelope heat loss and heat gain and its evaluation, paints, ins					pe:
UNIT III	HEATING, VENTILATION AND AIR CONDITIONIN	NG	9	0	0	9
	lation, Passive cooling and heating: Thermal mass effects – Aporative cooling, radiant cooling – Hybrid methods – energy cobuildings.					
UNIT IV	HEAT TRANSMISSION IN BUILDINGS		9	0	0	9
transfer due to estimation of for carrying o	ficient: air cavity, internal and external surfaces, overall thermal o infiltration, internal heat transfer; solar temperature; decrement fabuilding loads: steady state method, network method, numerical nut thermal design of buildings and predicting performance. Thermaethod for seasonal energy consumption.	actor; phase lag. De nethod, correlations;	sign of	day luter p	lighti acka	ng; ges
UNIT V	BUILDING COOLING AND RENEWABLE ENERGY BUILDINGS	IN	9	0	0	9
	g concepts, Application of wind, water and earth cooling; shading,					

Passive cooling concepts, Application of wind, water and earth cooling; shading, paints and cavity walls for cooling; roof radiation traps, Earth air tunnel. Solar sorption cooling and solar vapour compression cooling for buildings – Solar water heating systems in buildings – Small wind turbines, standalone PV, Hybrid systems for residential buildings with economics.

TEXT B	OOKS:
1.	Krieder. J., and Rabi. A., Heating and cooling of buildings: design for efficiency, McGraw Hill, 2016.
2.	Charles. J. Kibert, Sustainable Construction: Green Building Design and Deliver, John Wiley & Sons, 2016.
REFERI	ENCES:
1	Duffie, A and Beckmann, W. A., Solar Engineering of Thermal Processes, John Wiley, 1991.
2	Sukhatme, S.P., Solar Energy, Tata McGraw Hill, 1984.
3	Michael Bauer, Peter Mosle and Michael Schwarz, Green Building - Guidebook for Sustainable Architecture, 2009.
4	Velraj.R, 'Sensible heat Storage for solar heating and cooling systems' in the book titled "Advances in Solar

	Heating and Cooling" – Pages 399 - 428 Elsevier Publication, 2016.									
E-REF	E-REFERENCES:									
1.	https://nptel.ac.in/courses									
2.	UrsalaEicker, "Solar Technologies for buildings", Wiley Publications, 2003.3 Guide book for national certification examination for energy managers and energy auditors (downloaded from www.energymanagertraining.com).									

	SE OUTCOMES: ompletion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Apply the modern building aspects and the need of indoor air quality for comfort living.	Apply
CO2	Design an energy efficient landscape and evaluate the heat loss or gain through building components.	Analyze
CO3	Develop novel solutions for storage integration in buildings and evolve passive building strategies.	Understand
CO4	Estimate the actual and accurate thermal load for various types of buildings.	Analyze
CO5	Explain the importance of integrating various renewable energy resources in buildings.	Understand

COURSE A	OURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	1	1	0	2	0	0	0	0	0	0	2	1	1
CO2	0	0	3	2	0	0	1	0	0	0	0	0	1	1	0
CO3	0	0	1	1	0	0	1	0	0	0	0	0	0	0	0
CO4	1	1	1	1	0	0	1	1	0	0	0	0	1	1	1
CO5	0	0	0	0	0	1	1	0	1	1	0	0	0	0	0
Avg	0.6	0.4	1.2	1.0	0.0	0.6	0.8	0.2	0.2	0.2	0.0	0.0	0.8	0.6	0.4
	•		3/2	2/1 - i	ndicate	s stren	gth of	correlat	ion (3	high, 2	- mediun	n, 1- low)	•	

	EPE23	ENGINEERING SYSTEM ANALYSIS AND DE	CSIGN	SE	MES	TER	VI
PRE	CATEGORY	PE	Cre	edit	3		
1.Engineering Mechanics & Product design development							TF
2.De	2.Design of Machine Element Hours/Week						3
COU	RSE OB	JECTIVES:				ı	l
1.	Analyzo	e the asymptotic performance of Manual and automated systems.					
2.	Ability	to understand the principles of systems documentation.					
3.	Demon	strate a familiarity with Systems flowcharts and structured charts.					
4.	Apply i	mportant Planning considerations for advance development.					
5.	Underst	tand the basic concepts and implement the Object-orientedanalysis an	nd design.				
UN	I TIV	SYSTEM DEFINITION AND CONCEPTS		9	0	0	9
	NIT II	ributed systems, Basic principles of successful systems SYSTEMS ANALYST		9	0	0	9
to s	ystems d ementatio	of systems analyst, Qualifications and responsibilities, Systems Analevelopment life cycle (SDLC), Various phases of development, Maintenance Systems documentation considerations: Principles and their importance, Enforcing documentation discipline in an organization.	nt: Analysis, Des	sign, l	Devel	opme	nt,
to s Impl docu	ystems d ementatio	levelopment life cycle (SDLC), Various phases of developme on, Maintenance Systems documentation considerations: Principles	nt: Analysis, Des	sign, l	Devel	opme	nt,
to si Implidocu UN Logi Com	ystems dementation mentation NIT III cal and I mon diag	evelopment life cycle (SDLC), Various phases of developme on, Maintenance Systems documentation considerations: Principles in and their importance, Enforcing documentation discipline in an organization	nt: Analysis, Desort of systems docurrent anization. Tructured charts, I. Data Modeling a	sign, linentati 9 Data flo	Develon, T 0 ow di	opme ypes 0 agran	ont, of 9
to s Impl docu UN Logi Com Desi	ystems dementation mentation NIT III cal and I mon diag	development life cycle (SDLC), Various phases of development, Maintenance Systems documentation considerations: Principles and their importance, Enforcing documentation discipline in an organisation of the systems design and PROCESS MODELING on the state of the systems of the systems and state of the systems are systems. Systems flowcharts and state of the systems are systems and state of the systems are systems and systems are systems and systems are systems and systems are systems and systems are systems.	nt: Analysis, Desortion of systems documentation. Tructured charts, I. Data Modeling ans	sign, linentati 9 Data flo	Develon, T 0 ow di	opme ypes 0 agran	ont, of 9
to symmetric Implication of the symmetric Imp	ystems dementation mentation with the cal and properties with the calculation of the calculation with the calculation wit	levelopment life cycle (SDLC), Various phases of development, Maintenance Systems documentation considerations: Principles and their importance, Enforcing documentation discipline in an organisation of the systems design and Process MODELING on the systems of t	nt: Analysis, Desort of systems documentation. Tructured charts, I. Data Modeling ans Cocceptance Criteria ce, Maintenance a	9 Data flond system, System	Oeveloon, T Owding O	opme ypes 0 agran nalys 0 aluati	nt, of 9 ns, sis, 9 on
Logi Com Desi UN Plant and Thre	ystems dementation mentation with the cal and properties with the calculation of the calculation with the calculation wit	evelopment life cycle (SDLC), Various phases of development, Maintenance Systems documentation considerations: Principles and their importance, Enforcing documentation discipline in an organisation of their importance, Enforcing documentation discipline in an organisation of their importance, Enforcing documentation discipline in an organisation of their importance, Enforcing documentation discipline in an organisation of their importance, Systems flowcharts and stramming conventions and guidelines using DFD and ERD diagrams internals: Program and Process design, Designing Distributed System System Implementations, Conversion methods, producers and controls, System and ce, Testing and validation, Systems quality Control and assurance.	nt: Analysis, Desort of systems documentation. Tructured charts, I. Data Modeling ans Cocceptance Criteria ce, Maintenance a	9 Data flond system, System	Oeveloon, T Owding O	opme ypes 0 agran nalys 0 aluati	nt, of 9 ns, sis, 9 on

TEXT I	BOOKS:					
1.	Analysis and design of information systems – James A.Senn, McGraw-Hill Education, 2008					
2.	System analysis and design –Perry Edwards, McGraw-Hill Companies, 1993					
REFER	ENCES:					
1	System Analysis and Design Methods, Whitten, Bentaly and Barlow, Galgotia Publication					
2	System Analysis and Design Elias M. Award, Galgotia Publication					
3	Modern System Analysis and Design, Jeffrey A. Hofer Joey F. George Joseph S. Valacich Addison Weseley.					
E-REF	ERENCES:					
1.	https://archive.nptel.ac.in/courses/106/108/106108103/					
2.	https://www.tutorialspoint.com/system_analysis_and_design/system_analysis_and_design_overview.htm					
3.	https://nios.ac.in/media/documents/vocational/cca/cca1.pdf					

COURS Upon co	Bloom Taxonomy Mapped	
CO1	Understand the requirements of a system	Understand
CO2	Design system components and environments.	Analyze
CO3	Build general and detailed models that assist programmers in implementing a system.	Apply
CO4	Design a database for storing data and a user interface for data input and output, as well as controls to protect the system and its data.	Apply
CO5	Understand the concepts of object modeling and dynamics modeling.	Understand

COURSE A	ARTI(CULA	TION	MA	ΓRIX										
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	2	1	2	0	0	0	0	0	0	0	2	1	0
CO2	0	1	3	2	1	0	0	0	0	0	0	0	2	3	0
CO3	1	2	2	1	1	0	0	0	0	0	0	0	2	3	0
CO4	1	2	3	2	1	0	0	0	0	0	0	0	1	3	0
CO5	0	2	2	2	0	0	0	0	0	0	0	0	0	2	0
Avg	0.6	1.8	2.4	1.6	1.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	1.4	2.4	0.0
	•	•	3/2	2/1 – iı	ndicate	s stren	gth of	correlat	ion (3	high, 2	- mediur	n, 1- low)		

22MEPE24 INDUSTRIAL ENGINEERING AND MANAGEMENT							R VI
PREF	REQUIS	ITES	CATEGORY	PE	Cro	edit	3
1. Basi	. Basic knowledge of mathematics, science, and engineering.						TH
2. Basi	Hours/Week Basic knowledge about management principles.					0	3
COU	RSE OB	JECTIVES:					•
1.		ip them for applying knowledge of mathematics, science and engivity of industries.	ineering in the direc	tion to	impı	rove	the
2.	To prov	ride the knowledge on engineering economic analysis for effective	utilization of availab	le faci	lities.		
3.	To proplannin	vide the knowledge on supply chain management for efficient g.	use of available res	ources	with	agg	regate
4.	To mak	e the students familiarize the concept of JIT and modern manufactu	ring principles.				
5.	To fam	iliarize the modern concepts and marketing in management for app	lying them in profess	sional o	organi	izatio	n
U	NIT I	FORECASTING AND INVENTORY		9	0	0	9
disco	ounts - AI	of forecast errors. Inventory models - Classification of invento BC and other classification methods - Applications FACILITIES PLANNING	ry systems – EOQ	model 9	s and	0	9
Facil	lities plan	FACILITIES PLANNING ning - An overview, Facilities planning and engineering economic outs - Computerized layout planning - Warehouse management,		es locat	ion p	roble	ems –
		Role of KAIZEN, TQM, QC and POKA YOKE in facilities planni					
UN	III TII	AGGREGATE PLANNING AND SUPPLY CHAIN MA	NAGEMENT	9	0	0	9
requi	irements	o aggregate planning - Development of master production so planning (MRP-I), Manufacturing resources planning (MRP-II), management (SCM) – Supply chain and "Keiretsu".					
UN	UNIT IV JIT AND MODERN MANUFACTURING PRINCIPLES						
(SM) manu	ED) - Co ufacturing	Elements of Just in Time (JIT), Pull versus Push method, Kanbar entinuous improvement - Optimized production technology - Busy concepts - Implementation of Six Sigma concepts - Cellular returning - Rapid manufacturing.	siness process reeng	ineerir	ng (B)	PR),	Lean
UN	UNIT V MODERN MANAGEMENT CONCEPTS AND MARKETING 9 0 0						
Man	agement	ures, merits and demerits of: SWOT Analysis; Business Proces (SCM) – Marketing: Concept; Functions; Importance; Segmentise: Competitive Analysis and Advantage – E-marketing.					

Small Enterprise; Competitive Analysis and Advantage – E-marketing.

TEXT B	OOKS:							
1.	Dilworth B. James, "Operations Management Design, Planning and control for Manufacturing and Services", McGraw Hill Inc., New York, 1996.							
2.	Samson Eilon, "Elements of Production Planning and Control", Universal Book Corpn.1984.							
REFERI	ENCES:							
1	Vollman T.E, "Manufacturing Planning and Control systems", Galgotia Publications, 2002.							
2	Tomkins, J.A and White, J.A, "Facilities Planning", John Wiley and Sons, 1984.							
3	Elwood S. Buffa, and Rakesh K.Sarin, "Modern Production and Operations Management", 8th Edition. John Wiley and Sons, 2000.							

4	Saxena, P.K., Principles of Management: A Modern Approach, Global India Publications, 2009.								
5	M. Govindarajan, Marketing Management, Prentice Hall of India, New Delhi, 2010.								
E-REF	EFERENCES:								
1.	https://nptel.ac.in/courses/112107292								
2.	https://cscmp.org/								
3.	https://cdn.websiteeditor.net/25dd89c80efb48d88c2c233155dfc479/files/uploaded/Kotler_keller_marketing_management_14th_edition.pdf								

	E OUTCOMES: ompletion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Apply the knowledge in mathematics, science, and engineering in the direction to improve the productivity of industries.	Apply
CO2	Explain the concepts in engineering economic analysis for effective utilization and management of available facilities.	Understand
СОЗ	Explain the concepts of supply chain management for efficient use of available resources with aggregate planning.	Understand
CO4	Apply the concept of JIT and modern manufacturing principles in professional organization.	Apply
CO5	Identify modern concepts and marketing in management for applying them in professional organization	Remember

COURSE A	ARTI	CULA	TIOI	N MA	TRIX	(
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	1	1	0	0	0	0	0	0	0	0	2	2	0
CO2	1	2	3	1	0	0	0	0	0	0	0	0	1	2	1
CO3	0	2	2	0	3	1	0	0	0	0	0	0	1	2	3
CO4	0	0	0	0	0	0	0	0	3	0	0	1	0	0	2
CO5	0	0	0	0	0	2	0	2	0	0	1	1	2	0	0
Avg	0.8	1.2	1.2	0.4	0.6	0.6	0	0.4	0.6	0.0	0.2	0.4	1.2	1.2	1.2
	3/2/1 – indicates strength of correlation (3 – high, 2- medium, 1- low)														

22MEPE25 INTERNAL COMBUSTION ENGINES							R VI
PRER	EQUIS	SITES	CATEGORY	PE	Cre	edit	3
1. Er	L	Т	P	ТН			
2. T	2. Thermal Engineering Hours/Week						3
COUI	RSE OF	BJECTIVES:			ı	1	
1.	To acq	uire knowledge of basic concepts of IC engine.					
2.	To give	e a comprehensive insight into the engine fuel supply system.					
3.	To mak	te the students understand the combustion phenomenon of SI and Cl	engines.				
4.	To stud	ly engine management and exhaust emission control techniques.					
5.	To imp	art knowledge on recent trends in IC engines.					
Uľ	ITI	INTRODUCTION OF IC ENGINES		9	0	0	9
engir	ies, Actu	Types of IC engines, Constructional details in IC engine, working tal Indicator diagram for four-stroke and two-stroke engines, Geretane rating, Materials for engine components.					
UN	II TI	FUEL SUPPLY SYSTEMS		9	0	0	9
		ystems in SI engine - Introduction - Carburetion - Mixture require altitude fuel supply device - CI engine - Injection systems - Mecha			r, con	npens	ation
UN	IT III	COMBUSTION IN IC ENGINE		9	0	0	9
Facto	rs affect	ohenomenon in SI and CI engines - Ignition - Stages of combusting knock - Combustion chambers - Fuel spray behavior - Spray str Factors affecting combustion.					
UN	IT IV	ENGINE MANAGEMENT SYSTEM		9	0	0	9
		nition and fuel management systems, Digital control techniques, Corith engine management - Exhaust emission control techniques in SI		trol sys	stems,	Arti	ficial
UN	IIT V	RECENT TRENDS IN IC ENGINE		9	0	0	9
		es – construction and working, CRDI injection system, GDI Tratio engines, variable valve timing technology, Fuel cell, Hybrid ele		urboch	arger	, Var	iable

TEXT 1	BOOKS:
1.	V. Ganesan, "Internal Combustion Engines", V Edition, Tata McGraw Hill, 2017.
2.	John B. Heywood, "Internal Combustion Engines Fundamentals", McGraw-Hill, 1988.
REFER	RENCES:
1	Thipse.S.S, " internal Combustion Engines & quot; Jaico Publication House., 2010.
2	B.P. Pundir, "IC Engines Combustion & Emission", Narosa Publishing House, 2014.
3	K.K. Ramalingam, "Internal Combustion Engine Fundamentals", SciTech Publications, 2011
4	R.B. Mathur and R.P. Sharma, "Internal Combustion Engines", DhanpatRai & Sons, 2007.
5	Domkundwar.V.M, " A course in internal Combustion Engines & quot; Dhanpat Rai & Domkundwar.V.M, " A course in internal Combustion Engines & quot; Dhanpat Rai & Domkundwar.V.M, " A course in internal Combustion Engines & quot; Dhanpat Rai & Domkundwar.V.M, " Dhanpat Rai & Domkundwar.V.M,
E-REI	FERENCES:
1.	https://www.energy.gov/eere/vehicles/articles/internal-combustion-engine-basics
2.	https://www.energy.gov/sites/prod/files/2014/03/f8/deer11_taub.pdf
3.	https://dieselnet.com/tech/engine_emission-control.php

COURSE Upon con	Bloom Taxonomy Mapped	
CO1	Understand the concept, construction, and principle of operation of the engine and various engine Components.	Understand
CO2	Explain the fuel supply systems of SI and CI engines and understand the various injection systems of CI engine.	Analyze
CO3	Analyze the combustion phenomenon in SI and CI engines.	Analyze
CO4	Understand the Engine management system and exhaust emission control techniques.	Understand
CO5	Understand recent trends in internal combustion engines.	Understand

COURSE A	ARTIC	CULA	TION	N MA	TRIX										
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	1	0	0	0	0	0	0	0	0	3	2	1
CO2	3	2	2	1	0	0	0	0	0	0	0	0	3	2	1
CO3	3	1	2	2	2	2	3	0	0	0	0	0	2	3	1
CO4	2	1	2	1	2	2	3	0	0	0	0	0	2	3	1
CO5	3	1	1	1	2	2	2	0	0	0	0	0	2	3	1
Avg	2.8	1.4	1.8	1.2	1.2	1.2	1.6	0.0	0.0	0.0	0.0	0.0	2.4	2.6	1.0
	3/2/1 – indicates strength of correlation (3 – high, 2- medium, 1- low)														

22MI	EPE26		SEN	ΓER	VI		
PRER	EQUIS	SITES	CATEGORY	PE	Cre	edit	3
1.Engineering Drawing					Т	P	ТН
	Hours/Week					0	3
COUF	RSE OF	BJECTIVES:			ı		
1.	Studen sheets.	its learn about the conventional representation of materials, machin	e elements, and	sizes	of dr	awin	g
2.		n the concept of how to draw section of views, additional views for ed joints, Keys, Cotters and Pin joints.	r machine eleme	ents an	d par	ts lik	æ
3.		n the concept of how to draw Section of Views, additional views for Shaft couplings and Bearings	r machine elem	ents an	d par	ts lik	ie.
4.		its learn about the drawings of assembled views for the part drawings agine parts and machine parts	of the following	using	conve	ntion	IS
UN	UNIT I FUNDAMENTALS OF MACHINE DRAWING					0	1 5

Code of practice for Engineering Drawing, BIS specifications – Welding symbols, riveted joints, keys, fasteners – Reference to hand book for the selection of standard components like bolts, nuts, screws, keys etc. - Limits, Fits – Tolerancing of individual dimensions – Specification of Fits – Preparation of production drawings and reading of part and assembly drawings, basic principles of geometric dimensioning & tolerancing.

UNIT II BASIC MACHINE ELEMENTS 6 9 0 15

The required sectional view of the following machine elements are to be drawn as per the standards. Threaded joints, Riveted joints, Welded joints, Key, Cotter and Pin joints, Shaft coupling, Bearing, Pipe joints, Gears, Surface finish and its representation

UNIT III ASSEMBLY DRAWING 18 0 27 45

The assembly drawing of the following machine tool parts is to be drawn from the given detailed drawing.

lings – Flange, Universal, Oldham's, Muff and gear couplings.

- Knuckle, Gib & cotter, strap, sleeve & cotter joints.

e parts - Piston, connecting rod, cross-head (vertical and horizontal), stuffing box, multi-plate clutch.

llaneous machine components – Screw jack, machine vice.

Total (30L + 45P) = 75 Periods

TEXT	EXT BOOKS:						
1.	P.S Gill, "Machine Drawing", S K Kataria and sons, 18th edition, 2020 reprint.						
2.	N.D.Bhatt, "Machine Drawing". Charotar publications, 49th edition, 2014						
REFER	RENCES:						
1	Ajeet Singh, "Machine Drawing (including Auto CAD)", Tata McGraw Hill, 2 nd edition, 2012						
2	G. Pohit, "Machine Drawing with Auto CAD", Pearson Education Asia, 2007						
3	Dhawan, R.K., A Text Book of Machine Drawing, S. Chand & Company, 1996.						
4	Ostrowsky, O., Engineering Drawing with CAD Applications, ELBS, 1995.						
5	Gopalakrishna K.R., "Machine Drawing", 22th Edition, Subhas Stores Books Corner, Bangalore, 2013						
E-REF	E-REFERENCES:						
1.	NPTEL Courses						

	SE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Follow the drawing standards, fits and tolerances	Understand
CO2	Re-create part drawings, sectional views and assembly drawings as per standards	Analyze
CO3	Analyze complex design systems related to mechanical engineering.	Analyze
CO4	Improve skills to adopt modern methods in mechanical engineering as continuous improvement.	Understand
CO5	Understand the impact of engineering solutions in a global, economic, environment and societal context.	Understand

COURSE A	ARTIO	CULA	TIOI	N MA	TRIX										
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	2	1	0	1	1	0	0	0	1	0	2	2	1
CO2	2	1	2	1	0	1	1	0	0	0	1	0	2	2	1
CO3	2	2	2	2	0	0	2	0	0	0	1	0	2	2	1
CO4	1	1	2	2	0	1	0	0	0	0	1	0	2	2	1
CO5	1	1	1	2	0	2	2	1	0	0	0	0	1	1	1
Avg	1.6	1.2	1.8	1.6	0.0	1.0	1.2	0.2	0.0	0.0	0.8	0.0	1.8	1.8	1.0
	3/2/1 – indicates strength of correlation (3 – high, 2- medium, 1- low)														

22ME	EPE27	POWER PLANT ENGINEERING		SE	MES	TER	VI	
PRE	REQUI	SITES	CATEGORY	PE	Cre	edit	3	
1.Havi	ng suffic	ent knowledge on basics of power plant		L	Т	P	TE	
2. Basi	2. Basic unit calculation for consumption of power Hours/Week							
COU	JRSE O	BJECTIVES:				ı		
1.	and su	tanding of thermal power plant operation, different types of high- percharged boilers, fluidized bed combustion systems, Design edge of cooling tower operation.						
2.	Locatio	on of hydro power plant and its components to generate power.						
3.	Comple	ete knowledge about diesel and gas power plant.						
4.	Basic k	nowledge of nuclear reaction and types of nuclear power plant.						
5.	Basic k	nowledge of power plant economics and various tariff methods.						
UN	ITI	STEAM POWER PLANT		9	0	0	9	
coal types	- Pulveriz s - Chimn	am power plant – boilers - Modern high pressure and supercritica zer - Dust collector - Ash removal; Stokers - Different types - Pulv ey design - Selection of blowers, Cooling towers - Different types idised Bed boilers	erized fuel burning;	Draug	ht - I	Differ	ent	
UN	NIT II	HYDRO ELECTRIC POWER PLANT		9	0	0	9	
		del power plant- classification –working – components – layout Pumped Store Schemes.	of pumped storage	power	plant	- Pla	ant	
UN	III TII	DIESEL AND GAS POWER PLANT		9	0	0	9	
		sel power plant- Important components – performance analysis – Lacycles – components – relative thermal efficiencies of different cyc		plant –	class	ificati	on	
UN	NIT IV	NUCLEAR, MHD POWER GENERATION		9	0	0	9	
		eatment - Nuclear fission, chain reaction - Pressurized water reac breeder reactors, Magneto Hydro Dynamic power- open cycle and			s, gas	cool	ed	
Uľ	NIT V	9	0	0	9			
and '	variable l	d safety - Actual load curves - Fixed and operating costs - Tariff n oad operations - Selection of generation type and general equipment of Environmental impacts - assessment for thermal power plant.	nethods for electrica ment. Introduction	l energ to safe	y - Pe ety as	eak lo	ad in	

TEXT I	TEXT BOOKS:							
1.	S. Domkundwar, A.V. Domkundwar, S.C. Arora A Course in Power Plant Engineering, Dhanpat Rai Publications. 2016.							
2.	P.K. Nag, Power Plant Engineering, Tata McGraw Hill, Laxmi Publications Pvt. Ltd New Delhi, 5th Edition, 2014.							
REFER	ENCES:							
1	R.K. Rajput. A Text of Power Plant Engineering, Laxmi publications, New Delhi 5th Edition, 2016.							
2	G.R. Nagpal, Power Plant Engineering, Khanna Publications 1998.							
3	Bernhardt G. Askrotzki and William A. Vopat, "Power Station Engineering and Economy", Tata McGraw Hill Publishing Co. Ltd., 1972.							
4	Frederick T. Mores, "Power Plant Engineering", Affiliated East-West Press Private Ltd., 1953.							
5	Joel Weisman and Roy Eckart, "Modern Power Plant Engineering", Prentice Hall International Inc., 1985.							

E-REFERENCES:						
1.	https://en.wikipedia.org/wiki/Power_plant_engineering					
2.	https://onlinecourses.nptel.ac.in/noc21_me86/preview					

COU Upon	Bloom Taxonomy Mapped	
CO1	Identify elements and their functions of steam power plant.	Understand
CO2	Identify elements and their functions of hydroelectric power plant	Understand
CO3	Identify elements and their functions of diesel and gas power plant.	Understand
CO4	Identify elements and their functions of nuclear power plant.	Understand
CO5	Study the applications of power plants while extend their knowledge to power plant economics and environmental hazards and estimate the cost of electrical energy production.	Understand

COURSE ARTICULATION MATRIX PO PO PO PO PO PO PO PO7 PO8 COs/POs PO10 PO11 PSO₁ PSO₂ PSO3 **PO12** CO₁ **CO2** CO₃ **CO4 CO5** 1.2 1.6 2.6 2.0 0.8 0.0 0.8 1.2 2.0 0.2 1.8 1.8 2.0 0.8 Avg 1.6

PROFESSIONAL ELECTIVES – III

22MI	EPE31	FUELS AND COMBUSTION		SE	MES	TER	VI
PRE	REQUI	ISITES	CATEGORY	PE	Cre	edit	3
l. Basi	ic chemi	cal reactions between various components	/	L	Т	P	ТН
2. Fund	damental	about various types of fuels and its nature	Hours/Week	3	0	0	3
COU	RSE O	BJECTIVES:			1		
1.	To imp	part the acquaintance about characterize of the different types of fue	ls.				
2.	To enh	ance the understanding of Classification, Composition & Propertie	s of various fuels				
3.	Unders	standing of thermodynamics and kinetics of combustion.					
4.	Unders	stand and analyze the combustion mechanisms of various fuels.					
UN	IT I	CHARACTERIZATION		9	0	0	9
Ultima	ate Anal	quid and gaseous fuels-characteristics. Determination of Properties lysis - Moisture Determination - Calorific Value - Gross & Net Calorific Value - Gross &		•			
				1			
UN	IT II	SOLID FUELS & LIQUID FUELS		9	0	0	9
UN Solid Fuels Classi	IT II Fuels-Ty - Biom ification		Types - Sources - cific Gravity, Flash	Dry. R Petrole	enew um F	able l	Solid ons -
Solid Fuels Classi Numb	Fuels-Ty - Biom ification per, Cetan	SOLID FUELS & LIQUID FUELS ypes - Coal Family - Properties - Calorific Value - ROM, DMN hass - Agro Fuels - Manufactured Solid Fuels. Liquid Fuels Refining - Properties of Liquid Fuels - Calorific Value, Spe	Types - Sources - cific Gravity, Flash	Dry. R Petrole	enew um F	able l	Solid ons -
Solid Fuels Classi Numb UNI Classi Index	Fuels-Ty - Biom ification per, Cetan IT III ification - Natura	SOLID FUELS & LIQUID FUELS ypes - Coal Family - Properties - Calorific Value - ROM, DMN hass - Agro Fuels - Manufactured Solid Fuels. Liquid Fuels Refining - Properties of Liquid Fuels - Calorific Value, Spe ne Number etc., - Alcohols - Tar Sand Oil - Liquefaction of Solid	Types - Sources - Cific Gravity, Flash Fuels. Calorimeter. Rich & Sweet Natural Gas -	Dry. R Petrole & Fire 9 & Lean Liquef	enew um F e Poin 0 Gas -	able fraction of the control of the	Solidons - ctane 9
Solid Fuels Classi Numb UNI Classi Index Gas -	Fuels-Ty- Biom ification oer, Cetan IT III ification Natura Liquefie	ypes - Coal Family - Properties - Calorific Value - ROM, DMN hass - Agro Fuels - Manufactured Solid Fuels. Liquid Fuels Refining - Properties of Liquid Fuels - Calorific Value, Spene Number etc., - Alcohols - Tar Sand Oil - Liquefaction of Solid In GASEOUS FUELS - Composition & Properties - Estimation of Calorific Value - Gas al Gas - Dry & Wet Natural Gas - Stripped Natural Gas - Foul & St	Types - Sources - Cific Gravity, Flash Fuels. Calorimeter. Rich & Sweet Natural Gas -	Dry. R Petrole & Fire 9 & Lean Liquef	enew um F e Poin 0 Gas -	able fraction of the control of the	Solidons - ctane 9
Solid Fuels Classi Numb UNI Classi Index Gas - UNI Princi slow	Fuels-Ty - Biom ification per, Cetan IT III ification - Natura Liquefie IT IV iple of co	solid Fuels & Liquid Fuels ypes - Coal Family - Properties - Calorific Value - ROM, DMN hass - Agro Fuels - Manufactured Solid Fuels. Liquid Fuels Refining - Properties of Liquid Fuels - Calorific Value, Spe ne Number etc., - Alcohols - Tar Sand Oil - Liquefaction of Solid I GASEOUS FUELS - Composition & Properties - Estimation of Calorific Value - Gas al Gas - Dry & Wet Natural Gas - Stripped Natural Gas - Foul & Sed natural gas - Compressed natural gas - Methane - Producer Gas	Types - Sources - cific Gravity, Flash Fuels. Calorimeter. Rich & Sweet Natural Gas - Gasifiers - Water G pustion process- sub	Dry. R Petrole & Fire 9 & Lean Liquef as - To 9	enew um F e Poin Gas - ied Pe wn G	able abraction, October 1981 Work etrole as. Output	Solid ons - ctane 9 obe um 9 on,
Solid Fuels Classi Numb UNI Classi Index Gas - UNI Princi slow compo	Fuels-Ty Biom ification per, Cetan IT III ification - Natura Liquefie IT IV iple of co- combust osition, I	ypes - Coal Family - Properties - Calorific Value - ROM, DMN hass - Agro Fuels - Manufactured Solid Fuels. Liquid Fuels Refining - Properties of Liquid Fuels - Calorific Value, Spene Number etc., - Alcohols - Tar Sand Oil - Liquefaction of Solid In GASEOUS FUELS - Composition & Properties - Estimation of Calorific Value - Gas al Gas - Dry & Wet Natural Gas - Stripped Natural Gas - Foul & St	Types - Sources - cific Gravity, Flash Fuels. Calorimeter. Rich & Sweet Natural Gas - Gasifiers - Water G pustion process- sub	Dry. R Petrole & Fire 9 & Lean Liquef as - To 9	enew um F e Poin Gas - ied Pe wn G	able abraction, October 1981 Work etrole as. Output	Solid ons - ctane 9 obe um 9 on,
Solid Fuels Classi Numb UNI Classi Index Gas - UNI Princi slow compo UNI Coal I	Fuels-Ty - Biom ification per, Cetan IT III ification - Natura Liquefie IT IV iple of cocombust osition, I IT V Burning one Firing rizing Bi	ypes - Coal Family - Properties - Calorific Value - ROM, DMN ass - Agro Fuels - Manufactured Solid Fuels. Liquid Fuels Refining - Properties of Liquid Fuels - Calorific Value, Spe ne Number etc., - Alcohols - Tar Sand Oil - Liquefaction of Solid I GASEOUS FUELS - Composition & Properties - Estimation of Calorific Value - Gas al Gas - Dry & Wet Natural Gas- Stripped Natural Gas - Foul & Ed natural gas - Compressed natural gas - Methane - Producer Gas - COMBUSTION ombustion - stoichiometry, heat of reaction and formation. Combin, pulsating and explosive combustion. Chemical kinetics-Notexcess air calculation.	Types - Sources - Cific Gravity, Flash Fuels. Calorimeter. Rich & Sweet Natural Gas - Gasifiers - Water G Dustion process- sub Ox and soot kinetics Firing - Fixed Bec S, Traveling Grate S	Dry. R Petrole & Fire 9 & Lean Liquef as - To 9 mergee Fuel 9 I & Re tokers.	Gas- ied Pe wn Ga d com and ecycle Oil E	on the state of th	Solidons - ctane 9 on, gas 9 d - crs -

Text B	Text Books:								
1.	Samir Sarkar, Fuels & Combustion, 2nd Edition, Orient Longman, 2009.								
2.	Bhatt, Vora Stoichiometry, 4th Edition, Tata McGraw Hill, 2004.								
Refere	References:								
1	Om Prakash Gupta, Elements of Fuels, Furnaces and Refractories, Khanna publishers, 1999.								
2	Blokh AG, Heat Transfer in Steam Boiler Furnace, Hemisphere Publishing Corpn, 1988.								
3	Sharma SP, Mohan Chander, Fuels & Combustion, Tata McGraw Hill, 1984.								
4	Shaha AK (2003), Combustion Engineering & Fuel Technology, Oxford and IBH Publications, New York.								
5	Kenneth K Kou (2002), Principles of Combustion, Wiley & Sons Publications, New York.								

E-Refere	ences:
1.	https://nptel.ac.in/courses/112106299
2.	http://www.sitams.org/assets/pages/hands/material/R18/Engineering%20Chemistry/Fuels%20and%20combustion .pdf
3.	https://www.researchgate.net/publication/265602602_Fuels_and_Combustion_CHAPTER _4_FUELS_AND_COMBUSTION_41_Introduction_42_Requirements_of_a_Good_Fuel

COU	Bloom Taxonomy Mapped	
CO1	Understand the various kinds of fuels characteristics.	Understand
CO2	Determine flash and fire points of various fuel blends.	Apply
СОЗ	Classification, composition, properties and estimation of calorific value of gaseous fuels	Understand
CO4	Understand the thermodynamics behind combustion, flame propagation and choice of combustion systems.	Understand
CO5	Vast knowledge on effective employment of combustion equipment's	Understand

COURSE A	OURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	3	2	2	1	1	0	1	2	1	2	1	1	2	1
CO2	1	2	3	1	1	1	0	1	2	1	2	1	2	2	1
CO3	1	1	2	2	1	1	0	1	2	1	2	1	2	3	1
CO4	1	3	2	3	1	1	0	1	2	1	2	1	3	2	1
CO5	1	3	1	2	1	1	0	1	2	1	2	1	2	1	1
Avg	1.0	2.4	2.0	2.0	1.0	1.0	0.0	1.0	2.0	1.0	2.0	1.0	2.0	2.0	1.0
	3/2/1 – indicates strength of correlation (3 – high, 2- medium, 1- low)														

22M	EPE32	MAINTENANCE ENGINEERING		SE	MES	TER	l VI
PREI	REQUIS	ITES	CATEGORY	PE	Cre	edit	3
1. Mar	nufacturin	g Technology		L	Т	P	ТН
2.Envi	ronmenta	1 Science and Engineering	Hours/Week	3	0	0	3
COU	RSE OB	JECTIVES:		I	1	1	
1.		derstand the principles, functions and practices adapted in indinance activities	ustry for the succe	essful	mana	geme	nt of
2.	-	plain the different maintenance categories like preventive maintenance elements	nance, condition mo	onitori	ng an	d rep	air o
3.	To illus	strate the instruments used for condition monitoring in industry					
4.	To app	ly the repair methods in basic machine elements					
5.	То арр	ly the repair methods in material handling equipment					
UN	IT I	INTRODUCTION		9	0	0	9
of m	aintenanc	maintenance - types of maintenance – Breakdown, preventive and be planning – Importance and benefits of sound maintenance system faintenance of Mechanical transmission systems and process plants	ms – Repair cycle -	Repai	r Cor		
UN	IT II	RELIABILITY AND AVAILABILITY		9	0	0	9
Prod	uctive Ma	categories – Comparative merits of each category – Preventive ma aintenance (TPM). Reliability: Definition, concept of reliability-ba . Availability and Maintainability concepts- Applications					
UN	IT III	CONDITION MONITORING		9	0	0	9
instr		onitoring – Cost comparison with and without CM – On load test or CM – Temperature sensitive tapes – Pistol thermometers – wear					
UN	IT IV	NTS	9	0	0	9	
		ds for beds, slide ways, spindles, gears, lead screws and bearings - Logical fault location methods - Sequential fault location, trouble		– Fail	ures a	and th	neir
UN	IT V	REPAIR METHODS FOR MATERIAL HANDLING E	QUIPMENT	9	0	0	9
		ds for Material handling equipment – Equipment records – Jos Safety Codes and Standards - General Safety considerations in Mate			comp	outers	in
			Total	(45L)	= 45	Perio	ods

TEXT	TEXT BOOKS:							
1.	Ricky smith and R.keith mobley, "Rules of Thumb for Maintenance and Reliability Engineers", Butterworth-Heinemann, 2011.							
2.	Lindley Higgins, Keith Moley, "Maintenance Engineering Handbook", McGraw-Hill Company, 2002.							
REFE	ERENCES:							
1	Ahmed E.Haroun, Salih O.Duffuaa, "Handbook of Maintenance Management and Engineering", Springer, 2009.							
2	Mohamed Ben-Daya, Uday Kumar, "Introduction to Maintenance Engineering, Modelling, Optimization and Management", Wiley, 2016.							
3	B.S.Dhillon, "Engineering Systems Reliability, Safety and Maintenance : An integrated Approach", Taylor & Francis; CRC Press,2017.							
4	David J.Smith, "Reliability, Maintenance and Risk", Butterworth- Heinemann, 2011.							
5	Paul Dempsey, "Troubleshooting and Repair of Diesel Engines, Fourth Edition", McGraw-Hill ,2007.							

1. NPTEL courses: http://nptel.iitm.ac.in/courses.php - web and video sources on Maintenance Engineering

	URSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Understand the principles, functions and practices adapted in industry for the successful management of maintenance activities	Understand
CO2	Explain the different maintenance categories like preventive maintenance, condition monitoring and repair of machine elements	Understand
CO3	Illustrate the instruments used for condition monitoring in industry	Understand
CO4	Apply the repair methods in basic machine elements	Understand
CO5	Apply the repair methods in material handling equipment	Understand

COURSE A	RTI(CULA	TION	MA'	ΓRIX										
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	3	0	2	3	3	2	0	1	1	1	3	2	3	3
CO2	1	2	0	2	2	2	1	0	1	0	1	3	2	3	3
CO3	0	3	1	1	2	1	0	0	1	0	0	2	2	2	2
CO4	3	2	1	2	2	0	0	0	0	0	0	0	.3	2	1
CO5	3	2	0	2	2	0	0	0	0	0	0	0	3	2	1
Avg	1.6	2.4	0.4	1.8	2.2	1.2	0.6	0.0	0.6	0.2	0.4	1.6	2.4	2.4	2.0

22MEPE33 NON-TRADITIONAL MACHINING PROCESS	SEMESTER V				
PREREQUISITES C	ATEGORY	PE	Cre	edit	3
1.Manufacturing Technology		L	Т	P	ТН
2.Engineering Chemistry	Iours/Week	3	0	0	3
COURSE OBJECTIVES:			I		ı
To understand the various Non-Traditional machining processes and its applicates	ions				
2. To decide the appropriate process among various electro chemical processes					
3. To justify the appropriate Thermo - electric process based on the application and	d limitations				
4. To understand the working principle and applications of Laser machining proce	sses				
5. To understand the working principle and applications of Micro-electro Mechani	cal processes				
UNIT I INTRODUCTION		9	0	0	9
UNIT II ELECTRO - CHEMICAL PROCESSES Electro chemical machining: Types - Electro Chemical Machining (ECM) - Electro Chemical Grinding (ECG) - Electro Chemical Honing (ECH) - Shaped Tube Electro Process parameters - Applications – Limitations.					
UNIT III THERMO - ELECTRICAL PROCESSES		9	0	0	9
Thermo electrical machining: Types - Electrical Discharge Machining (EDM) - Electr Electron Beam Machining (EBM) - Ion Beam Machining (IBM) - Plasma Arc Mac Process parameters - Applications - Limitations.					
UNIT IV LASER MACHINING PROCESSES	9	0	0	9	
Laser materials processing: Laser types - Processes - Laser Beam Machining (LBM) marking and engraving - Laser Micro Machining (LMM)-Laser Engineered No Limitations.					
UNIT V MICRO ELECTRO - MECHANICAL PROCESSES		9	0	0	9
Introduction to silicon processing - Wafer cleaning - Oxidation - Photolithography - thin film deposition - sputtering - chemical vapour deposition - electro plating - E etching, anisotropic etching, dry etching.					
	Tota	ıl(45L	-4	5 Pe	riods

TEXT E	BOOKS:
1.	Pandey P.C. and Shan H.S. "Modern Machining processes" Tata McGraw-Hill, New Delhi, 2017.
2.	Nano Tanigudi, "Nanotechnology", Oxford University Press, New York, 2003.
3.	Vijay K Jain, "Advanced Machining Processes", Allied Publications Private Limited, 2002.
REFER	ENCES:
1	Carl Sommer, "Non-traditional Machining Handbook", Advance Publishing Inc., 2000.
2	Groover, M.P. "Fundamentals of Modern Manufacturing Processes - Materials, Processes and Systems", 3rd Edition, John Wiley and Sons Inc., 2007.
3	Paul De Garmo, J.T.Black, and Ronald.A.Kohser, "Material and Processes in Manufacturing" Prentice Hall of India Pvt.Ltd., New Delhi, 8th Edition, 2001.
4	Steen, W.M. and Watkins, K. "Laser Materials Processing", Springer London Ltd, 2003.
5	Hassan Abdel and Gaward El-Hofy, "Advanced Machining Processes", McGraw Hill Publications, 2005.

1. NPTEL courses: http://nptel.iitm.ac.in/courses.php - web and video sources on Non-Traditional Machining Processes.

COU Upon	Bloom Taxonomy Mapped	
CO1	Understand the various Non-Traditional machining processes and its applications	Understand
CO2	Decide the appropriate process among various electro chemical processes	Understand
CO3	Justify the appropriate Thermo electric process based on the application and limitations	Apply
CO4	Understand the working principle and applications of Laser machining processes	Understand
CO5	Understand the working principle and applications of Micro-electro Mechanical processes	Understand

COURSE ARTICULATION MATRIX

COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	0	1	0	0	0	0	0	0	1	0	2	2	1
CO2	3	2	0	0	1	0	0	0	0	0	0	0	2	2	1
CO3	3	2	0	0	1	0	0	0	0	0	0	0	2	2	1
CO4	2	1	0	0	1	0	0	0	0	0	0	0	2	2	1
CO5	2	1	0	0	1	0	0	0	0	0	0	0	2	2	1
Avg	2.6	1.6	0.0.	0.2	0.8	0.0	0.0	0.0	0.0	0.0	0.2	0.0	2.0	2.0	1.0
		1 1.6			0.8										1.0

	PE34	PROFESSIONAL ETHICS AND HUMAN VALUES	SE	MES	TER	VI				
PRE	REQUI	ISITES CATEGORY	PE	Cre	edit	3				
l.Hum	an Right	s	L	Т	P	TH				
2. Prod	luct life (Cycle Management Hours/Week	3	0	0	3				
COUI	RSE OF	BJECTIVES:	l.	1						
1.	Applyin	g the core values toward the ethical behavior of an engineer.								
2.	Applyin	g the ethical and moral principles in engineering experimentation.								
3.	Applyin	g the ethical and moral principles in engineering for safety.								
4.	Applyin	g standard codes of moral conduct toward the ethical behavior of an engineer.								
	5. Applying ethical and moral principles for engineers as managers, consultants, expert witness. Resolving global issue of ethics concerning weapon development and multinational companies.									
UNI	TI	ENGINEERING ETHICS	9	0	0	9				
	s and Vii	ngineering Ethics' – Variety of moral issues – Types of inquiry – Moral dilemmas neory – Gilligan's theory – Consensus and Controversy – Professions and Profession tues – Uses of Ethical Theories. ENGINEERING AS SOCIAL EXPERIMENTATION								
UNI Engin	s and Vir T II neering a	neory – Gilligan's theory – Consensus and Controversy – Professions and Profession rtues – Uses of Ethical Theories.	nalism -	- Prot 0	fessio 0	nal 9				
UNI Engin	s and Vir T II neering a	neory – Gilligan's theory – Consensus and Controversy – Professions and Profession rtues – Uses of Ethical Theories. ENGINEERING AS SOCIAL EXPERIMENTATION as Experimentation – Engineers as responsible Experimenters – Research Ethics Codes	nalism -	- Prot 0	fessio 0	nal 9				
UNI Engin Stand UNI Safet	s and Vin T II neering a dards - A T III y and R	neory – Gilligan's theory – Consensus and Controversy – Professions and Profession rtues – Uses of Ethical Theories. ENGINEERING AS SOCIAL EXPERIMENTATION as Experimentation – Engineers as responsible Experimenters – Research Ethics Codes Balanced Outlook on Law – The Challenger Case Study.	9 of Ethi	- Proi	0 ndust	9 rial				
UNI Engin Stand UNI Safet Regu	s and Vin T II neering a dards - A T III y and R	neory – Gilligan's theory – Consensus and Controversy – Professions and Profession rtues – Uses of Ethical Theories. ENGINEERING AS SOCIAL EXPERIMENTATION as Experimentation – Engineers as responsible Experimenters – Research Ethics Codes Balanced Outlook on Law – The Challenger Case Study. ENGINEERING FOR SAFETY Risk – Assessment of Safety and Risk – Risk Benefit Analysis – Reducing Risk	9 of Ethi	- Proi	0 ndust	9 rial				
UNI Engin Stand UNI Safet Regu UNI Colle	s and Vin T II neering a dards - A T III ty and R tlator's A T IV egiality a	neory – Gilligan's theory – Consensus and Controversy – Professions and Profession rules – Uses of Ethical Theories. ENGINEERING AS SOCIAL EXPERIMENTATION as Experimentation – Engineers as responsible Experimenters – Research Ethics Codes Balanced Outlook on Law – The Challenger Case Study. ENGINEERING FOR SAFETY Risk – Assessment of Safety and Risk – Risk Benefit Analysis – Reducing Risk approach to Risk - Chernobyl Case Studies and Bhopal.	9 s of Ethi 9 Conflicts	0 cs - Ii 0 cs - Ii 0 cs - Ii 1 of Ii	0 ndust 0 rernm 0	9 rial 9 ent				
UNI Engin Stand UNI Safet Regu UNI Colle	s and Vin T II neering a dards - A T III ry and R dator's A T IV regiality a regiality a	rtues – Uses of Ethical Theories. ENGINEERING AS SOCIAL EXPERIMENTATION as Experimentation – Engineers as responsible Experimenters – Research Ethics Codes Balanced Outlook on Law – The Challenger Case Study. ENGINEERING FOR SAFETY Risk – Assessment of Safety and Risk – Risk Benefit Analysis – Reducing Risk approach to Risk - Chernobyl Case Studies and Bhopal. ENGINEER'S RESPONSIBILITIES AND RIGHTS and Loyalty – Respect for Authority – Collective Bargaining – Confidentiality – Confidenti	9 s of Ethi 9 Conflicts	0 cs - Ii 0 cs - Ii 0 cs - Ii 1 of Ii	0 ndust 0 rernm 0	9 rial 9 ent				
UNI Safet Regu UNI Colle Occu UNI Multi Deve	T II neering a dards - A T III y and R dator's A T IV egiality a upational T V inational elopment	Record — Gilligan's theory — Consensus and Controversy — Professions and Profession retues — Uses of Ethical Theories. ENGINEERING AS SOCIAL EXPERIMENTATION As Experimentation — Engineers as responsible Experimenters — Research Ethics Codes Balanced Outlook on Law — The Challenger Case Study. ENGINEERING FOR SAFETY Risk — Assessment of Safety and Risk — Risk Benefit Analysis — Reducing Risk approach to Risk - Chernobyl Case Studies and Bhopal. ENGINEER'S RESPONSIBILITIES AND RIGHTS and Loyalty — Respect for Authority — Collective Bargaining — Confidentiality — Crime — Professional Rights — Employee Rights — Intellectual Property Rights (IPR) —	9 s of Ethi 9 Conflicts Discrim 9 cole in	O CS - In O CS -	0 ndust 0 erennm 0 nteres 0 nolog	9 9 ent 9 ical				

TEXT	BOOKS:
1.	Mike Martin and Roland Schinzinger, "Ethics in Engineering", McGraw-Hill, New York 2017.
2.	Govindarajan M, Natarajan S, Senthil Kumar V. S, "Engineering Ethics", Prentice Hall of India, New Delhi, 2004
REFE	RENCES:
1	Charles D Fleddermann, "Engineering Ethics", Prentice Hall, New Mexico, 1999.
2	David Ermann and Michele S Shauf, "Computers, Ethics and Society", Oxford University Press, 2003
3	Edmund G Seebauer and Robert L Barry, "Fundamentals of Ethics for Scientists and Engineers", Oxford University Press, 2001.
4	John R Boatright, "Ethics and the Conduct of Business", Pearson Education, 2003.
5	Prof. (Col) P S Bajaj and Dr. Raj Agrawal, "Business Ethics – An Indian Perspective", Biztantra, New Delhi, 2004.
E-REF	ERENCES:
1.	Value Education websites, http://uhv.ac.in, http://www.uptu.ac.in
2.	IIT Delhi, Modern Technology – the Untold Story

3. Gandhi A., Right Here Right Now, Cyclewala Productions

	RSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped	
CO1	Understand the core values toward the ethical behavior of an engineer.	Understand	
CO2	Apply the ethical and moral principles in engineering experimentation	Understand	
CO3	Expose the ethical and moral principles in engineering for safety.	Apply	
CO4	Apply standard codes of moral conduct toward the ethical behavior of an engineer	Apply	
CO5	Apply ethical and moral principles for engineers as managers, consultants, expert witness. Resolve global issues of ethics concerning weapon development and multinational companies.	Understand	

COURSE A	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	0	0	0	0	0	0	3	1	3	0	0	2	1	0	0
CO2	0	0	0	0	0	0	2	2	3	0	0	2	1	2	0
CO3	0	0	0	0	0	0	3	2	3	0	0	2	1	2	0
CO4	0	0	0	0	0	0	3	3	2	0	0	2	1	2	0
CO5	0	0	0	0	0	0	2	2	3	0	0	2	1	0	0
Avg	0.0	0.0	0.0	0.0	0.0	0.0	2.6	2	2.8	0.0	0.0	2.0	1.0	1.2	0.0
3/2/1 – indica	ates str	ength	of corr	elation	n (3 – 1	nigh, 2	- medi	um, 1-	low)						•

22MEPE35	RAPID PRODUCT DEVELOPMENT TECHNOLOGI	ES	SE	MES	TER	l VI					
PREREQUI	SITES CA	TEGORY	PE	Cre	edit	3					
1. Design of M	achine elements and transmission systems, CAD software	/337 1	L	T	P	TH					
2. Material scie	ence, Tool Design, Engineering physics	ours/Week	3	0	0	3					
COURSE OF	JECTIVES:			•							
1. To expla	in the Importance of RPT in Manufacturing										
2. To famil	2. To familiarize the students with recent developments in RPT										
3. To descr	ibe different methods for Post-processing of AM parts										
4. To list o	ut the challenges in RPT										
5. To explain future Directions of AM											
UNIT I		9	0	0	9						
design – proto systems	otype – tooling -History of RP systems- Survey of applications- Growth of STEREO LITHOGRAPHY SYSTEMS	RP industry-	classi:	ficatio	on of 0	RP 9					
Stereo lithogr laser sintering	aphy systems – Principle – process parameters – process details – maching – Principle – process parameters – process details – machine details-ILS) system – Principle – process parameters – process details – machine details – ma	Applications	plicati -Direc	ons. S	Select	ive					
UNIT III	FUSED DEPOSITION MODELING		9	0	0	9					
	sition Modelling – Principle – process parameters – process details - pject Manufacturing – Principle – process parameters – process details – m					ons.					
UNIT IV	SOLID GROUND CURING AND CONCEPT MODELERS		9	0	0	9					
printers –	Curing – Principle – process parameters – process details – machine details – process parameters – process details – machine details – Applicated printers – Sander's model maker – JP system 5 – Object Quadra system stic Particle Manufacturing (BPM) -Principle.	ions- and oth	er con	cept r	nodel	lers					
UNIT V	RAPID TOOLING AND SOFTWARES		9	0	0	9					
Introduction t	o rapid tooling – direct and indirect method- Indirect Rapid Tooling - Sil	licone rubber	tooling	g- Alı	ımini	um					

Introduction to rapid tooling – direct and indirect method- Indirect Rapid Tooling - Silicone rubber tooling- Aluminium filled epoxy tooling- Spray metal tooling- etc. Direct Rapid Tooling - Direct AIM- Quick cast process- Copper polyamide- Rapid Tool- DMILS- ProMetal- Sand casting tooling- Laminate tooling- soft tooling vs hard tooling. Software for RP – STL files- Magics- Mimics. Application of Rapid prototyping in medical field.

Total(45L) = 45 Periods

TEXT	BOOKS:
1.	Ian Gibson, David W Rosen, Brent Stucker., "Additive Manufacturing Technologies: Rapid Prototyping to Direct Digital Manufacturing", Springer, 2010
2.	Ali K. Kamrani, Emand Abouel Nasr, "Rapid Prototyping: Theory & Practice", Springer, 2006. 4. D.T. Ph
REFE	RENCES:
1	Pham D.T. & Dimov.S. S, "Rapid manufacturing", Springer Verlag, London, 2001.
2	Paul F Jacobs, "Rapid Prototyping and manufacturing – Fundamentals of Stereo lithographic", Society of Manufacturing Engineering, Dearborn, USA 1992.
3	Ali K. Kamrani, Emand Abouel Nasr, "Rapid Prototyping: Theory & Practice", Springer, 2006.
4	Chua Chee Kai, Leong Kah Fai, "Rapid Prototyping: Principles & Applications", World Scientific, 2003.
5	Terry wohlers, "Wohlers Report 2007", Wohlers Associates, USA 2007.

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:							
CO1	Learn about the hurdles, basic-essentials and key-drivers of innovation in digital manufacturing and its application in Automobile, Aerospace, Bio-medical etc.	Understand						
CO2	Recognize the operational features of Stereo Lithography Systems.	Understand						
CO3	Explain the concept of Fusion Deposition Modelling.	Understand						
CO4	Design for manufacture solid ground curing and concept modelers	Apply						
CO5	Acquire the knowledge of Software for RP and apply RPT in Tooling.	Understand						

COURSE A	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	0	1	1	1	1	2	0	0	0	0	1	1	3	2	1
CO2	0	2	1	1	1	0	0	0	1	0	1	1	1	2	2
CO3	0	2	1	1	1	0	0	0	1	0	1	1	1	2	2
CO4	0	2	3	1	1	0	0	0	1	0	1	1	1	2	2
CO5	0	1	0	1	3	0	0	0	1	0	1	0	3	2	3

3/2/1 – indicates strength of correlation (3 – high, 2- medium, 1- low)

0.8

0.0

1.0

0.8

1.8

0

Avg

0.0

1.6

1.2

1.0

1.4

0.4

0

2.0

2.0

	REFRIGERATION & AIR CONDITIONIN	IG	SE	MES	TER	VI				
PREREQUIS	ITES	CATEGORY	PE	Credit		3				
1.Engineering	Thermodynamics	** /** 1	L	Т	P	TH				
2.Fluid Mechar	ics and Machinery	Hours/Week	3	0	0	3				
COURSE OF	JECTIVES:					1				
1. To unde	estand the basic concepts and processes in refrigeration									
2. To unde	2. To understand the components of vapour compression refrigerating system and its effects									
3. To unde	3. To understand the other refrigeration systems and their applications									
4. To solve	4. To solve the problems using psychrometric charts and psychrometric properties									
5. To calcu	late the cooling load for designing air conditioning systems									
UNIT I	INTRODUCTION		9	0	0	9				
compression	system components: Type of Compressors, Condensers, Expecte: P-H and T-S diagrams – deviations from theoretical cycle – s	ansion devices, E ub cooling and sup	er heat	ing- e	ffects					
UNIT III	other refrigeration Systems - problems on vapour cother refrigeration systems	compression rerriger	9	0	0	9				
	ciple of vapour absorption refrigeration system — Steam jet refr c refrigeration, Pulse tube refrigeration system, low temperature refrigeration.				syste	em-				
*********			^							
UNIT IV			9	0	0	9				
Properties of dew point to	moist air - Gibbs and Dalton's law. Psychrometric property- dry bemperature, Specific humidity, relative humidity, Degree of sar chart; Psychometric processes, mixing of air streams.		et bull	tem _j	perati	ure,				
Properties of dew point to	mperature, Specific humidity, relative humidity, Degree of sai	turation, Relative	et bull	tem _j	perati	ure,				
Properties of dew point to Psychometric UNIT V Air condition appliances, Ir principles. Air	mperature, Specific humidity, relative humidity, Degree of sar chart; Psychometric processes, mixing of air streams.	TION agh structure, Solar resh air load, huma	et bulk humid 9 radiat	tempity, E	peratu Enthal 0 Electri	ure, lpy. 9 ical AQ				

TEXT I	BOOKS:							
1.	Arora, C.P., "Refrigeration and Air Conditioning", 3rd edition, McGraw Hill, New Delhi, 2017.							
2.	Arora S. C. and Domkundwar, "Refrigeration and Air-Conditioning", Dhanpat Rai and Co. (P) Ltd., 2010.							
REFER	ENCES:							
1	Roy J. Dossat, "Principles of Refrigeration", 4th Edition, Pearson Education Asia, 2009.							
2	Stoecker, W.F. and Jones J. W., "Refrigeration and Air Conditioning", McGraw Hill, New Delhi, 1986.							
3	Ballaney P. L, Refrigeration and Air-Conditioning, Khanna Publishers, New Delhi, 2014.							
4	Manohar Prasad, Refrigeration and Air-Conditioning, New Age International, 2011.							
5	ASHRAE Hand book, Fundamentals, 2010.							
E-REFI	ERENCES:							
1.	NPTEL courses: http://nptel.iitm.ac.in/courses.php - web and video sources on Refrigeration and Air Conditioning.							

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:							
CO1	Understand the basic concepts and processes in refrigeration	Understand						
CO2	Understand the components of vapour compression refrigerating system and its effects	Understand						
CO3	Understand the other refrigeration systems and their applications	Understand						
CO4	Solve the problems using psychrometric charts and psychrometric properties	Analyze						
CO5	Calculate the cooling load for designing air conditioning systems	Analyze						

COURSE A	ARTI	CULA	TIO	N MA	TRIX	<u> </u>									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	0	0	0	0	1	2	0	0	0	0	0	2	2	1
CO2	2	3	0	2	0	1	1	0	0	0	0	0	2	2	1
CO3	2	3	0	1	0	0	0	0	0	0	1	0	2	2	1
CO4	2	1	0	0	0	0	0	0	0	1	0	0	2	2	1
CO5	2	2	1	2	1	2	1	0	0	0	1	0	2	2	1
Avg	2.2	1.8	0.2	1.0	0.2	0.8	0.8	0.0.	0.0	0.2	0.4	0.0	2.0	2.0	1.0
	•		3/2	1/1 - in	dicate	s stren	gth of	correlat	tion (3	– high, 2	2- mediu	m, 1- lov	v)		•

CATEGORY Hours/Week	PE L 3	T 0	P 0	3 C 3
election criteria.	3 Solar o	0 collec	0	9
election criteria.	9 Solar o	0 collec	0	9
	Solar	collec	Ů	
	Solar	collec	Ů	Ĺ
	Solar	collec	Ů	Ĺ
	Solar	collec	Ů	Ĺ
	Solar	collec	Ů	
	Solar	collec	Ů	Ĺ
	Solar	collec	Ů	
			tors- i	flat
	q	_		
		0	0	9
vn, drain back, position algorithr		eze s	ystem	.s -
	9	0	0	9
, global and dir	rect so	olar r	adiatio	on:
	9	0	0	9
ns - heat deliver	y meth	nods -	air-ty	ype
	9	0	0	
of solar panels	s-chop _l	pers-i	nverte	ers-
,	ons - heat deliver	ons - heat delivery meth	9 0 ons - heat delivery methods -	ons - heat delivery methods - air-ty

TEXT	TEXT BOOKS:							
1.	Duffie, J.A., and Beckman, W.A. Solar Energy Thermal Process, John Wiley and Sons, NewYork, 2013.							
2.	Kosuke Kurokawa (Ed.), Energy from the Desert – Feasibility of very large-scale photovoltaic power generation systems, JamesandJames2003.							
REFER	REFERENCES:							
1	Sukhatme S.P., Solar Energy, TataMcGrawHills P Co., 3 rd Edition, 2008.							
2	C.J.Winter, R.L.Sizmann, L.L.VantHull, SolarPowerPlants, Springer Verlag Berlinand HeidelbergGmbH &Co., 2001.							

COURS	COURSE OUTCOMES:								
Upon con	Mapped								
CO1	Explain various solar collectors in solar power plants.	Understand							
CO2	Describe the variety of solar systems used in solar water heating systems.	Understand							
CO3	Describe the solar radiation and its measurements.	Understand							
CO4	Analyze solar space conditioning systems.	Apply							
CO5	Design PV systems for power plants	Apply							

COURSE ARTICULATION MATRIX

COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1	0	0	0	2	1	0	0	0	0	0	2	1	2
CO2	3	2	1	2	0	1	0	0	0	0	1	0	2	2	2
CO3	3	2	0	2	3	2	0	0	0	0	1	0	2	2	1
CO4	3	3	1	2	2	2	0	0	0	0	1	0	3	2	2
CO5	3	2	3	2	3	2	0	0	0	0	1	0	2	3	2
Avg	3	2	1	1.6	1.6	1.8	0.2	0	0	0	0.8	0	2.2	2	1.8

PROFESSIONAL ELECTIVES – IV

22MEPE	1	ADVANCED DECISION MODELING TECHN	IQUES	SEMESTE			l VI
PREREC	QUI	SITES	CATEGORY	PE	Cr	edit	3
1.Students	are e	expected to have a background knowledge in probability.		L	Т	P	TH
2.Students and Algebr		expected to have a basic understanding in the concepts of Calculus,	Hours/Week	3	0	0	3
3.Basic kno	wle	dge in python programming.		1	ı	1	.1
COURSE	OE	BJECTIVES:					
		p student, explain the fundamentals of machine learning, need forms, linear algebra concepts and application areas of deep learning machine in the students.		d ense	mble	learn	ing
		e the student explain the concepts of Convolutional Neural Net entation of different CNN models using Python.	work (CNN) archi	tecture	, trair	ning a	and
		e the student explain the concepts of Recurrent Neural Networtation of different CNN models using Python.	ork (RNN) archit	ecture,	train	ing a	and
		liarize the need, methods and concepts for ensemble learning and e learning approaches.	l apply with Pytho	n impl	emen	tation	of
		rify alternate deep learning models for the listed use cases, identify ess between standard deep learning models.	a suitable algorith	nm by	appre	hend	the
UNIT I		INTRODUCTION		9	0	0	9
		g – rationale- concept of Eigenvalues and Eigenvectors- fundamen amentals – real world examples- implementation aspects of deep lea		rning-	histor	y-nei	ural
UNIT I	[CONVOLUTIONAL NEURAL NETWORKS		9	0	0	9
Convolut	ona	ne process of convolution, convolutional layer, pooling layer, fully layeral Network (CNN) - architecture and training of different CongleNet - Implement the CNN models using Python.					
UNIT II	I	RECURRENT NEURAL NETWORKS		9	0	0	9
		Ns - Evolution of LSTM from RNN -Working of LSTM concernections, coupled gates, Gated Recurrent Network -Implement RNN		ts of L	STM	such	ıas
UNIT I	7	ENSEMBLE LEARNING		9	0	0	9
		emble learning -methods involved in ensemble learning - bagging or or or things to a real-world problem - Python implementation of ensemb			AdaB	oost	and
UNIT V	7	CASE STUDIES		9	0	0	9
classificat between	ion/ stand	p learning models for the listed use cases like plant species identify prediction, loan eligibility prediction and resume parsing - ided dard deep learning models and advanced deep learning models - ning model for the application under consideration.	ntify a suitable al	gorithn	n -dif	feren	ices
							riod

TEXT	BOOKS:						
1.	S. Sumathi, Suresh Rajappa, L. Ashok Kumar, And Surekha Paneerselvam, "Advanced Decision Sciences Based on Deep Learning and Ensemble Learning algorithms", Nova Science Publishers, Inc, 2021.						
2.	Singhal, Vanika, Shikha Singh, and Angshul Majumdar, "How to train your deep neural network with dictionary learning". arXiv preprint arXiv:1612.07454 (2016).						
REFEI	REFERENCES:						
1	Srivastava, Pranjal. Essentials of deep learning: introduction to long short-term memory. last updated on Dec 10						

	(2017).					
2	Sumathi, Sai, and Surekha Paneerselvam. Computational intelligence paradigms: theory & applications using MATLAB. CRC Press, 2010.					
3	Goodfellow and Bengio, "Deep Learning", MIT press.					
4	Christopher Bishop, "Pattern Recognition and Machine Learning", Springer Science+Business Media, LLC, 2006.					
5	Francois Cholle, "Deep Learning with Python" Manning publications.					
E-REFE	E-REFERENCES:					
1	Study-Material-BTech-IT-VIII-sem-Subject-Deep-Learning-deep_learning_Btech_IT_VIII-sem.pdf (ccsuniversity.ac.in)					
2	ResNet, AlexNet, VGGNet, Inception: Understanding various architectures of Convolutional Networks – CV-Tricks.com.					
3	Convolutional Neural Networks and their components for computer vision – MachineCurve.					
4	Dive into Deep Learning — Dive into Deep Learning 0.16.4 documentation (d2l.ai).					

	RSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Learn the fundamentals of machine learning, need for deep learning and ensemble learning algorithms, linear algebra concepts and application areas of deep learning models.	Understand
CO2	Understand the concepts of Convolutional Neural Network (CNN) architecture, training and implementation of different CNN models using Python.	Understand
CO3	Studythe concepts of Recurrent Neural Network (RNN) architecture, training and implementation of different CNN models using Python.	Remember
CO4	Capture the need, methods and concepts for ensemble learning and apply with Python implementation of ensemble learning approaches.	Analyze
CO5	Identify alternate deep learning models for the listed use cases, identify a suitable algorithm by apprehend the differences between standard deep learning models.	Apply

COURSE A	ARTIC	CULA	TIO	N MA	TRIX	(
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	2	3	2	0	0	0	0	1	1	0	1	1	0
CO2	3	2	0	3	2	0	0	0	0	1	1	0	1	1	0
CO3	3	2	0	3	2	0	0	0	0	1	1	0	1	1	0
CO4	3	2	0	3	2	0	0	0	0	1	1	0	1	1	0
CO5	3	2	2	3	1	0	0	0	0	1	1	0	1	1	0
Avg	3.0	2.2	0.8	3.0	1.8	0.0	0.0	0.0	0.0	1.0	1.0	0.0	1.0	1.0	0.0
3/2/1 – indica	ates str	ength (of corr	elatior	n (3 – ł	nigh, 2	- medi	um, 1-	low)						

	42 AUTOMATION IN MANUFACTURING		SE	MES	TER	VI	
PREREQ	UISITES CAT	ГEGORY	PE	Cre	edit	3	
1.17 1.1		/XX7 1	L	T	P	TH	
1.Knowledg	e in manufacturing technology Hou	urs/Week	3	0	0	3	
COURS	E OBJECTIVES:			•			
1. To g	et the knowledge of various elements of manufacturing automation						
2. To s	udy various techniques of automatic material handling in a manufacturing org	anization					
3. To io	lentify suitable automation hardware for the given application						
	ncorporate application of electronics and computer engineering in mechanifacturing automation	nical engine	ering f	for er	hanc	ing	
5. To d	evelop CNC programs to manufacture industrial components.						
UNIT I	INTRODUCTION TO AUTOMATION		9	0	0	9	
Automatic General T	d Flow lines, Methods of Work part Transport, Transfer Mechanism, Buffer on for Machining Operations, Design and Fabrication Considerations. Analerminology and Analysis, Analysis of Transfer Lines Without Storage, Part	alysis of Auto	omated	Flov	v Lin	ies:	
Automate Automatic General T	d Flow lines, Methods of Work part Transport, Transfer Mechanism, Buffer on for Machining Operations, Design and Fabrication Considerations. Analerminology and Analysis, Analysis of Transfer Lines Without Storage, Part Storage Buffers, Computer Simulation of Automated Flow Lines.	alysis of Auto	ntrol Formated	function Flow	ons, a	and nes:	
Automate Automatic General T Lines with UNIT II Industrial Control, C	d Flow lines, Methods of Work part Transport, Transfer Mechanism, Buffer on for Machining Operations, Design and Fabrication Considerations. Analysis and Analysis, Analysis of Transfer Lines Without Storage, Part Storage Buffers, Computer Simulation of Automated Flow Lines. CONTROL TECHNOLOGIES IN AUTOMATION Control Systems, Process Industries Verses Discrete-Manufacturing Indust Computer Process Control and its Forms. Computer Based Industrial Control: Stuilding Blocks of Automation System: LAN, Analog & Digital I/O Modules,	ries, Continu	ntrol Formated on, Autority 9 ous Ve	Function Flow tomate to the following to	ons, av Lined Fl O Discr	and nes: ow	
Automate Automatic General T Lines with UNIT II Industrial Control, C Control, F	d Flow lines, Methods of Work part Transport, Transfer Mechanism, Buffer on for Machining Operations, Design and Fabrication Considerations. Analysis of Transfer Lines Without Storage, Part Storage Buffers, Computer Simulation of Automated Flow Lines. CONTROL TECHNOLOGIES IN AUTOMATION Control Systems, Process Industries Verses Discrete-Manufacturing Indust Computer Process Control and its Forms. Computer Based Industrial Control: Building Blocks of Automation System: LAN, Analog & Digital I/O Modules, Interface	ries, Continu	ntrol Formated on, Autority 9 ous Ve	Function Flow tomate to the following to	ons, av Lined Fl O Discr	and nes: ow	
Automate Automatic General T Lines with UNIT II Industrial Control, C Control, E machine i UNIT IV	d Flow lines, Methods of Work part Transport, Transfer Mechanism, Buffer on for Machining Operations, Design and Fabrication Considerations. Analysis and Analysis, Analysis of Transfer Lines Without Storage, Part a Storage Buffers, Computer Simulation of Automated Flow Lines. CONTROL TECHNOLOGIES IN AUTOMATION Control Systems, Process Industries Verses Discrete-Manufacturing Indust Computer Process Control and its Forms. Computer Based Industrial Control: Building Blocks of Automation System: LAN, Analog & Digital I/O Modules, Interface	ries, Continu Introduction & SCADA Sys	9 ous Ve Auto Auto gloop cess of 6	function of the following terms of the follow	ons, av Lined Fl O Discr Proc U. ma o syste syste	generated and seed of the seed	
Automate Automatic General T Lines with UNIT II Industrial Control, C Control, E machine i UNIT IV	d Flow lines, Methods of Work part Transport, Transfer Mechanism, Buffer on for Machining Operations, Design and Fabrication Considerations. Analysis and Analysis, Analysis of Transfer Lines Without Storage, Part Storage Buffers, Computer Simulation of Automated Flow Lines. I CONTROL TECHNOLOGIES IN AUTOMATION Control Systems, Process Industries Verses Discrete-Manufacturing Industrial Computer Process Control and its Forms. Computer Based Industrial Control: Fauilding Blocks of Automation System: LAN, Analog & Digital I/O Modules, Interface NUMERICAL CONTROL MACHINES Onents, NC coordinate systems, Point to point, line and contouring systems, of NC manufacturing, Role of NC/CNC technology in modern manufacturits and tooling of machining centre and CNC turning centre, Automatic and linear scale, Features of DNC and adaptive control systems.	ries, Continu Introduction & SCADA Sys	9 ous Ve Auto Auto gloop cess of 6	function of the following terms of the follow	ons, av Lined Fl O Discr Proc U. ma o syste syste	9 9 ete te eess an- 9 em, em, ees:	
Automate Automatic General T Lines with UNIT II Industrial Control, C Control, E machine i UNIT IV NC comp Steps in componer Encoders UNIT V Part programments of the Control of the Cont	d Flow lines, Methods of Work part Transport, Transfer Mechanism, Buffer on for Machining Operations, Design and Fabrication Considerations. Analysis and Analysis, Analysis of Transfer Lines Without Storage, Part Storage Buffers, Computer Simulation of Automated Flow Lines. I CONTROL TECHNOLOGIES IN AUTOMATION Control Systems, Process Industries Verses Discrete-Manufacturing Industrial Computer Process Control and its Forms. Computer Based Industrial Control: Fauilding Blocks of Automation System: LAN, Analog & Digital I/O Modules, Interface NUMERICAL CONTROL MACHINES Onents, NC coordinate systems, Point to point, line and contouring systems, of NC manufacturing, Role of NC/CNC technology in modern manufacturits and tooling of machining centre and CNC turning centre, Automatic and linear scale, Features of DNC and adaptive control systems.	ries, Continu Introduction & SCADA Sys	9 ous Ve Auto Auto 9 loop cres of G Feedl	ontrol CNC back	ons, a v Linder Floor V Linder Floor V Linder Floor Procedu. many of the system of the	9 em, ees:	

TEXT	BOOKS:						
1.	M.P.Grover, Automation, Production Systems and Computer Integrated Manufacturing, Pearson Education. 2016.						
2.	Computer Numerical Control (CNC) Machines Paperback – 1, P. Radhakrishnan, New Central Book Agency; 1st edition, 2013						
REFE	RENCES:						
1	Steve F Krar, "Computer Numerical Control Simplified ", Industrial Press, 2001.						
2	Tien-Chien Chang, Richard A. Wysk and Hsu-Pin Wang - Computer Aided Manufacturing, Pearson 2009						

3	Frank Lamb - Industrial Automation, Mc Graw Hill,2013									
E-REFERENCES:										
1.	Steve F Krar, "Computer Numerical Control Simplified ", Industrial Press, 2001.									
2.	Tien-Chien Chang, Richard A. Wysk and Hsu-Pin Wang - Computer Aided Manufacturing, Pearson 2009									

	VRSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Understand the effect of manufacturing automation strategies	Understand
CO2	Apply knowledge of industrial automation by transfer lines and automated assembly lines.	Apply
CO3	Understand the electronic control systems in metal machining and other manufacturing processes.	Understand
CO4	Identify different CNC components, systems and controls CNC machines	Apply
CO5	Write CNC programming to solve complex machining process	Understand

COURSE A	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	1	2	1	1	2	2	1	0	0	1	1	1	2	2
CO2	1	2	2	1	1	2	1	0	2	0	1	1	1	2	2
CO3	1	2	2	2	2	2	1	0	2	0	1	1	1	2	2
CO4	0	0	1	1	3	2	2	1	0	2	1	1	1	2	2
CO5	0	0	0	1	3	2	2	1	0	2	1	1	1	2	2
Avg	0.6	1.0	1.4	1.2	2.0	2.0	1.6	0.6	0.8	0.8	1.0	1.0	1.0	2.0	2.0
			3/2	/1 – in	dicate	s stren	gth of	correlat	tion (3	– high, 2	2- mediu	m, 1- lov	v)		

	EPE43	CRYOGENIC ENGINEERING		SE	MES	TER	VI
PREI	REQUI	SITES CATI	EGORY	PE	Cre	edit	3
1.Eng	ineering	Thermodynamics	/337 1-	L	Т	P	ТН
2.Refr	rigeration	n and air conditioning	rs/Week	3	0	0	3
COU	RSE O	BJECTIVES:			•		
1.	To prov	ride the knowledge of evolution of low temperature science					
2.	To prov	ride knowledge on the properties of materials at low temperature					
3.	To fam lines	iliarize with various gas liquefaction systems and to provide design aspects	of cryoger	nic stor	age a	nd tra	ansfe
4.	To lear	n information concerning low temperature processes and techniques					
5.	To be fa	amiliar with the applications of low temperature technology					
UN	NIT I	PROPERTIES OF CRYOGENIC FLUIDS & MATERIAL PRO AT LOW TEMPERATURE	PERTIES	9	0	0	9
- Ph Prop stren Spec	ase diag perties of agth, Fat cific hea		ngth, Ultim	ate Str	ength nducti	, Imp	act and
UN	IT II	BASICS OF GAS LIQUEFACTION AND REFRIGERATION S	SYSTEMS	9	0	0	9
Heat Joule	t Exchan	gers, Compressors and Expanders (only description with figure). on expansion of a real gas, Isentropic expansion, Comparison of J-T Expan		•	•		
UN	ecific heat - Electrical and Magnetic Properties- Superconductivity, BCS theory, HT and LT Superconducting terials, Applications of superconductivity. NIT II BASICS OF GAS LIQUEFACTION AND REFRIGERATION SYSTEMS 9 0 0 sics of Refrigeration-Methods of Production of low Temperatures- Critical Components of Liquefaction systems at Exchangers, Compressors and Expanders (only description with figure). the Thomson expansion of a real gas, Isentropic expansion, Comparison of J-T Expansion and Isentropic Expansion yout and Working of Liquid Helium and Nitrogen. VARIOUS GAS LIQUEFACTION AND REFRIGERATION SYSTEMS 9 0 0 Stiquefaction Parameters - Calculation of Liquid Yield, Work requirement and Optimization of Yield for various						9
cycle syste	es such em for N ocoolers	ction Parameters – Calculation of Liquid Yield, Work requirement and Opas Ideal thermodynamic system, Linde Hampson Cycle, Precooled Linde We and Hydrogen - Precooled Claude System, Liquefaction systems for He-Basics of Cryocoolers-Ideal Stirling Cycle- Stirling Cryocooler, Philips Rooler, Pulse Tube Cryocooler, Vuilleumier Refrigerator, Dilution Refrigerator	Hampson s e – Collins efrigerator,	system. and Si Solvey	Liqu mon Refr	iefact syster igera	ion ms.
		CDV/CCDVIC DI LUD CECD A CE AND ED ANGDED CVCEDIA					9
G-M	IT IV	CRYOGENIC FLUID STORAGE AND TRANSFER SYSTEMS		9	0	0	
G-M UN Cryc	ogenic Si perforn	torage vessels - Dewar Vessel and Vapour Shielded Vessel, Transportation shance at cryogenic temperatures - Types of Insulation – Expanded Foam, Cacuum, Evacuated Powder and Multi-Layer Insulation.	systems. Th	ermal	insula	tion	and
G-M UN Cryo their Mate	ogenic Si perforn	torage vessels - Dewar Vessel and Vapour Shielded Vessel, Transportation shance at cryogenic temperatures - Types of Insulation - Expanded Foam, O	systems. Th	ermal	insula	tion	and
G-M UN Cryc their Mate	ogenic So perforn erials, Va	torage vessels - Dewar Vessel and Vapour Shielded Vessel, Transportation shance at cryogenic temperatures - Types of Insulation – Expanded Foam, Cacuum, Evacuated Powder and Multi-Layer Insulation.	systems. Th Gas Filled I	ermal Powder	insula s and	tion a	and ous

TEXT B	TEXT BOOKS:										
1.	J. H. Boll Jr, Cryogenic Engineering										
2.	. B. Scott, Cryogenic Engineering, Van Nostrand Co., 1959										
REFERI	ENCES:										
1	Klaus D. Timmerhaus and Thomas M.Flynn, "Cryogenic Process Engineering", Plenum Press, New York, 1989.										
2	Randal F.Barron, "Cryogenic systems", McGraw Hill, 1986.										

1. nptel.ac.in / courses / downloads

	RSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Understand the properties of both cryogenic fluids and material properties for better design process in cryogenic applications.	Understand
CO2	Apply the knowledge of low temperature production methods	Understand
CO3	Analyze the performance parameters of various gas liquefaction systems	Analyze
CO4	Understand the various cryogenic fluid storage for transportation systems and transfer lines	Understand
CO5	Understand different instrumentation in cryogenics	Understand

COURSE A	OURSE ARTICULATION MATRIX														
COs/POs	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	PO 7	PO8	PO 9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	3	1	0	0	0	0	0	0	0	0	2	1	0
CO2	2	2	2	1	0	0	0	0	0	0	0	0	3	1	0
CO3	2	2	3	1	0	0	0	0	0	0	0	0	3	1	0
CO4	2	2	2	1	0	0	0	0	0	0	0	0	1	1	0
CO5	2	1	1	1	0	0	0	0	0	0	0	0	1	1	0
Avg	2.0	1.8	2.2	1.0	0.0	0.0	0.0	0.0	0.0.	0.0	0.0	0.0	2.0	1.0	0.0
3/2/1 – indic	cates st	rength	of cor	relatio	n (3 –	high, 2	- medi	um, 1-	low)						

22MI	EPE44	FRACTURE MECHANICS AND FAILURE AN	IALYSIS	SEM	EST	ER V	/I
PRE	REQU	ISITES	CATEGORY	PE	Cr	edit	3
l. Stu	dent shou	ld study Strength of material.	/	L	Т	P	TH
2. Stu	dent shou	ld study Materials Engineering.	Hours/Week	3	0	0	3
COL	URSE O	BJECTIVES:		I	1		
1.	Identif	y and explain the types of fractures of engineered materials and the	ir characteristic feat	ures.			
2.		stand the differences in the classification of fracture mechanics and ized to determine conditions under which engineering materials e.					
3.	Under	stand and explain the mechanisms of fracture; and learn how to carr	y out engineering fa	ailure aı	nalysi	s.	
4.	To Lea	arn the microstructural aspects that lead to fracture.					
5.	Apply	advanced mathematical theories to characterize and predict fracture	<u>.</u>		•		
Ul	I TIV	BASIC CONCEPTS IN FRACTURE MECHANICS		9	0	0	9
theo	ory, Duct	y of stress and strain, elastic deformation, plastic and elasto-plastic life fracture, Probabilistic aspects of fracture mechanics – Microstructure, Probabilistic aspects – Microstructure mechanics – M			1	I	
	IIT II	MECHANICS OF FRACTURE- STATIC LOADING		9	0	0	9
mod	del – J i	s – Analytical solutions yielding near a crack front – Irwin's apprentegral and its relation to crack opening displacement. Strain en f fracture Toughness of different materials: size effect & control					
UN	IT III	FAILURE ANALYSIS OF FATIGUE FRACTURE		9	0	0	9
calc	ulations	sources of failures- Deficiency in design, Empirical Relation de for a given load amplitude – effects of changing the load specallysis of fatigue failures, some case studies in analysis of fatigue fai	trum - Effects of				
UN	IT IV	FAILURE ANALYSIS OF CREEP RUPTURE		9	0	0	9
cree	p, Mech	levated temperature: Time dependent mechanical behavior, stress anism of creep deformation and Creep deformation maps, Prediction case studies in analysis of creep failures.					
UN	NIT V	FAILURE ANALYSIS OF CORROSION AND WEAR		9	0	0	9
type	es of corr	ar, analyzing wear failure, corrosion failures- factors influencing cosion, stress corrosion cracking, sources, characteristic of stress coron cracking, various types hydrogen damage failures.					
_			Total	(45L)	= 45	Perio	ods

TEXT I	BOOKS:								
1.	Hertz berg R W, "Deformation and fracture mechanics of Engineering Materials" Second Edition John Wiley's sons inc, New York 1983.								
2.	Knott. J.F, "Fundamentals of Fracture Mechanics" Butterworth London, 1973.								
REFERENCES:									
1	Evalds H L and RJH Warnhil," Fracture Mechanics", Edward Arnold Ltd, Baltimore,1984.								
2	Campbell J E, Underwood J H, and Gerberich W., "Applications of Fracture Mechanics for the selection of Materials", American Society for Metals, Metals Park Ohio, 1982.								
3	Fracture Mechanics Metals Handbook, ninth edition, vol. 8 437-491, American Society of Metals Metal Park Ohio, 1985.								
4	Kare Hellan, "Introduction of Fracture Mechanics", McGraw-Hill Book Company, 1985.								

5	Prashant Kumar, "Elements of Fracture Mechanics", Wheeler Publishing, 1999.
E-REFE	RENCES:
1	https://www.fracturemechanics.org/
2	https://archive.nptel.ac.in/courses/112/107/112107241/
3	http://vucoe.drbriansullivan.com/wp-content/uploads/Fundamentals-of-Fracture-Mechanics.pdf

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:							
CO1	Familiarize the structure design to prevent failure from the internal defect.	Create						
CO2	Illustrate the design structure to prevent fatigue and creep.	Create						
CO3	Solve the problems related to deformation and related theories.	Evaluate						
CO4	Formulate the empirical relations for fatigue fracture.	Apply						
CO5	Analyse the failures in corrosion and wear.	Analyse						

COURSE A	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	1	1	0	2	1	0	0	0	0	0	3	1	1
CO2	2	2	1	1	0	2	1	0	0	0	0	0	3	1	1
CO3	2	2	1	1	0	2	1	0	0	0	0	0	3	1	1
CO4	2	2	1	1	0	2	1	0	0	0	0	0	3	1	1
CO5	2	2	1	1	0	2	1	0	0	0	0	0	3	1	1
Avg	2	2	1	1	0	2	1	0	0	0	0	0	3	1	1
			3/2/1	– indi	cates s	trengtl	of co	rrelatio	n (3 – 1	high, 2- 1	medium,	1- low)			

22MEPE 4	2MEPE45 FUNDAMENTALS OF TRIBOLOGY					R VI
PRERE(PE	Cre	edit	3		
l.Engineeri	g Mechanics		L	Т	P	TH
		Hours/Week	3	0	0	3
COURSE	OBJECTIVES:					
1. Тор	ovide broad based understanding of the interdisciplinary subject 'tribo	ology' and its techno	logical	signif	icano	e.
2. To le	arn about consequences of wear, wear mechanisms, wear theories and	l analysis of wear pro	blems.			
3. To st	dy about properties of lubricants, testing methods and types of lubric	eants.				
4. To a	quire the knowledge about the stress, Co-efficient of friction and visc	ous flow in journal b	earings	.		
5. To le	arn about the nature of engineering surfaces, their topography and bea	arings material.				
UNIT I	SURFACES AND FRICTION		9	0	0	9
	WEAR vear – Simple theory of Sliding Wear Mechanism of sliding wear or and Abrasive wear situations – Corrosive wear – Surface Fatigue w					
	eramics and Polymers – Wear Measurements.	ear situations – Briti	le Flac	iure -	- wez	u –
UNIT II	LUBRICANTS AND LUBRICATION TYPES		9	0	0	9
	properties of Lubricants – Testing methods – Hydrodynamic Lubrication – Solid Lubrication- Hydrostatic Lubrication.	ation – Elasto- hydro	dynam	ic lub	ricati	on-
UNIT IV	FILM LUBRICATION THEORY		9	0	0	9
for film L	in simple shear – Viscous flow between very close parallel plates – brication – High speed unloaded journal bearings – Loaded journal bo-efficient of friction – The Sommer field diagram.					
	SURFACE ENGINEERING AND MATERIALS FOR I	REARINGS	9	0	0	9
UNIT V		DEFINITION OF				ш_

2002(102)/10201104

TEXT B	OOKS:						
1.	A. Harnoy. "Bearing Design in Machinery "Marcel Dekker Inc, New York, 2003.						
2.	B.C. Majumdar ; A.H.Wheeler "Introduction to Tribology of Bearings"						
REFERI	ENCES:						
1	M. M. Khonsari & E. R. Booser, "Applied Tribology", John Willey &Sons, New York, 2001						
2	E. P. Bowden and Tabor.D., "Friction and Lubrication", Heinemann Educational Books Ltd., 1974.						
3	A. Cameron, "Basic Lubrication theory", Longman, U.K, 1981.						
4	M. J. Neale (Editor), "Tribology Handbook", Newnes. Butterworth-Heinemann, U.K., 1995.						
E-REF	E-REFERENCES:						
1.	NPTEL Videos/Tutorials						

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:						
CO1	Familiarize the surface phenomena related to relative motion, the nature of friction, and mechanisms of wear.	Remember					
CO2	Analyze the various wear mechanism and fatigue wear of the engineering components	Analyze					
СОЗ	Familiarize the lubricants testing methods and types of lubrication	Remember					
CO4	Analyze the stress, co-efficient of friction and viscous flow in journal bearings	Analyze					
CO5	Analyze the surface engineering and materials for bearings	Analyze					

COURSE A	RTI(CULA	TION	MA	ΓRIX										
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	3	3	1	1	2	0	0	0	0	0	1	2	1
CO2	0	1	2	2	1	1	1	0	0	0	0	0	1	1	1
CO3	1	2	2	2	1	1	0	0	0	0	0	0	2	1	1
CO4	0	1	2	2	1	0	0	0	0	0	0	0	2	1	1
CO5	0	2	2	2	0	0	0	0	0	0	0	0	1	2	1
Avg	0.4	1.6	2.2	2.2	0.8	0.6	0.6	0.0	0.0	0.0	0.0	0.0	1.4	1.4	1.0
	•	•	3/2	2/1 - i	ndicate	s stren	gth of	correlat	ion (3	high, 2	- mediun	n, 1- low)	•	

22MI	EPE46	PE46 METAL FORMING PROCESSES							
PRE	REQUI	SITES	CATEGORY	EGORY PE Credit					
1.Man	ufacturin	g processes		L T P					
2.Stre	ngth of n	naterials	PE	3 0 0					
COU	RSE OE	BJECTIVES:				1			
1.	To fami Forming	liarize the students about principle, procedure and applications	of Bulk Metal For	ming a	nd Sl	heet	Meta		
2.	To Illust	rate capabilities and applications of metal forming processes.							
3.	To analy	ze effect of parameters influencing metal forming processes.							
4.	Outline t	tooling and equipment required for important metal forming process	ses.						
5.	Examine	effects of friction & lubrication and causes of common defects in I	netal forming.						
UN	ITI	FUNDAMENTALS OF METAL FORMING		9	0	0	9		
Defo		of forming processes, mechanisms of metal forming: slab met energy method and finite element method temperature of metal works.							
UN	IT II	ROLLING OF METALS		9	0	0	9		
		esses, forces and geometrical relationship in rolling, simplified and hot rolling, problems and defects in rolling, torque and power			ing v	ariab	les,		
UN	IT III	FORGING		9	0	0	9		
defe of va	cts, and parious pre	of forging processes, forging of plate, forging of circular discs, cowder metallurgy forging. problems on flow stress, true strain and ess tools and dies like piercing dies, blanking dies, compound dies ling and drawing dies.	forging load. Press	tool d	esign:	Des	ign		
UN	IT IV	EXTRUSION		9	0	0	9		
sean	iless pipe	Hot Extrusion, Analysis of Extrusion process, defects in extruses. Problems on extrusion load. Drawing: Drawing of tubes, rocess, analysis of wire, deep drawing and tube drawing. Problems on the control of the contro	ls, and wires: Wire						
UN	IT V	SHEET METAL FORMING		9	0	0	9		
Forn	ning meth	nods Bending stretch forming spinning and Advanced techniques	of Sheet Metal For	mino	Formi	no li	mit		

Forming methods, Bending, stretch forming, spinning and Advanced techniques of Sheet Metal Forming, Forming limit criteria, defect in formed parts. Advanced Metal forming processes: HERF, Electromagnetic forming, residual stresses, in-process heat treatment, and computer applications in metal forming. problems on Blanking force, Blank diagram in Cup Diagram, Maximum considering shear.

Total(45L) = 45 Periods

TEXT	BOOKS:						
1.	Surender Kumar, Technology of Metal Forming Processes, Prentice - Hall, Inc., 2008						
2.	Nagpal G.R. Metal forming processes, Khanna publishers, New Delhi, 2004						
REFEI	RENCES:						
1	Serope Kalpakjian, Steven R Schmid, Manufacturing Process for Engineering Materials, 4th Edition, Pearson Education, 2003.						
2	Rao, P.N. Manufacturing Technology, TMH Ltd., 2003						
3	Edward M.Mielink, Metal working Science Engineering", McGraw Hill, Inc, 2000.						
4	Metal Handbook Vol.14, Forming and Forging, Metal Park, Ohio, USA, 1990						

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:						
CO1	Understand fundamentals of metal forming and stress curves.	Understand					
CO2	Know various process parameters and applied loads in sheet metal working.	Evaluate					
СОЗ	Brief various forging techniques and defects in forging.	Understand					
CO4	State the principles of rolling and stresses developed under rolling loads.	Understand					
CO5	Analyze Extrusion and drawing processes and associated stresses developed.	Analyze					

COURSE	ARTICU	LATION	MATRIX

COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	0	1	0	0	0	0	0	0	1	1	0	0	1	0	2
CO2	1	2	0	2	0	0	0	0	0	1	0	0	1	1	2
CO3	0	1	2	0	0	2	0	0	0	1	0	0	1	1	2
CO4	1	1	0	1	0	0	0	0	0	1	0	0	1	1	2
CO5	1	3	0	1	1	0	2	0	0	0	0	1	1	1	2
Avg	0.6	1.6	0.4	0.8	0.2	0.4	0.4	0.0	0.2	0.8	0.0	0.2	1.0	0.8	2.0

22MEPE47	MICRO AND NANO MACHINING		SE	MES	ГER	VI
PREREQUIS	ITES	CATEGORY	PE	Cre	edit	3
			L	Т	P	ТН
1.Manufacturin	g process	Hours/Week	3	0	0	3
COURSE OF	JECTIVES:			ı	1	
1. To give	awareness of different techniques used in micro and nano machining	/manufacturing.				
2. To give	in-depth idea of the conventional techniques used in micro machinin	g/manufacturing.				
3. To introd	duce Non-conventional micro-nano manufacturing and finishing app	roaches.				
	uce Micro and Nanofabrication Techniques and other prog/manufacturing.	cessing routes in	Mic	ero a	nd l	Nano
UNIT I	INTRODUCTION		9	0	0	9
UNIT II	ls in Micromachining - Diamond technology, Diamond micromachin CONVENTIONAL PROCESSES: MICRO-TURNING, M DRILLING AND MICRO-MILLING		9	0	0	9
	Micro-turning, Micro-drilling, Micro-milling, Product quality in microssesses Introduction, Micro and nanogrinding, Nanogrinding tools	cromachining Micro	-grind	ing ar	nd Ul	tra-
UNIT III	NON-CONVENTIONAL PROCESSES: LASER MICRO	MACHINING	9	0	0	9
	Fundamentals of lasers, Laser microfabrication, Laser nanofabrication romachining Destructive evaluation technologies, Non-destructive e			ice Da	ımage	e in
UNIT IV	MICRO AND NANO FINISHING PROCESSES, MICRO) JOINING	9	0	0	9
Need for Nan Float Polishin TIG, Applicat	o finishing, Magnetic abrasive Finishing, Magnetorheological Finish g, Ion Beam finishing. Micro Joining - Challenges, Micro Resistations.	n, Elastic Emission nce welding, Ultras	Finish onic w	ing, N eldin	Magne g, Mi	etic cro
UNIT V	APPLICATIONS OF NANO AND MICROMACHINING	G IN INDUSTRY	9	0	0	9
	APPLICATIONS OF NANO AND MICROMACHINING ining methods, Applications in optical manufacturing, Semiconductor					

TEXT B	OOKS:
1.	J. Paulo Davim, Mark J. JacksonNano and Micromachining, John Wiley & Sons, 2013 2 Mark.
2.	J. Jackson, Micro and Nano-manufacturing, Springer, 2006.
REFERI	ENCES:
1	Mark. J. Jackson, Micro-fabrication and Nano-manufacturing - Pulsed water drop micromachining CRC Press 2006.
2	NitaigourPremchandMahalik, Micro-manufacturing and Nanotechnology, 2006
3	V.K.Jain, Micro-manufacturing Processes, CRC Press, 2012
4	Yi Qin, Micro-manufacturing Engineering and Technology, William Andrew, 2015
5	Kapil Gupta, Micro and Precision Manufacturing, Springer, 2017

	RSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Identify different areas of micro and nano machining	Evaluate
CO2	Find the applications of all the areas in industries.	Evaluate

COURSE A	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	0	1	0	0	0	0	0	1	1	0	2	0	1
CO2	0	1	1	1	0	0	0	0	0	1	1	1	1	2	3
Avg	1	1	0.5	1	0		0	0	0	1	1	0.5	1.5	1	1.5
3/2/1 – indica	ates str	ength	of corr	elation	n (3 – 1	nigh, 2	- medi	um, 1-	low)	•		· ·		- 1	•

$\underline{\textbf{PROFESSIONAL ELECTIVES} - \textbf{V}}$

	ANALYSIS AND SYNTHESIS OF MECHA	NISMS	SEM	EST	ER '	VIII
PREREQUIS	SITES	CATEGORY	PE	Cre	edit	3
.Kinematics of	f Machinery		L	Т	P	TH
2. Dynamics of	Machinery.	PE	3	0	0	3
COURSE O	BJECTIVES:		1	I		
1. To Study	y of kinematics of various mechanisms and kinematic synthesis of	linkages.				
2. To Study	y of various graphical constructions of acceleration analysis.					
3. To Study	y Static and dynamic force analysis of linkages.					
4. To Study	y Kinematic analysis and kinematic synthesis of spatial mechanism	18				
5. To Study	y about the spatial mechanisms and robotics					
UNIT I		9	0	0	9	
	LKINEMATIC SYNTHESIS OF LINKAGES		g	0	n	Q
	r and Dimensional Synthesis - Function Generation - Path Gener to Position, Three Position and Four Position synthesis of four by					ical
Type, Number Methods: Two Precision pos	er and Dimensional Synthesis - Function Generation - Path Gener to Position, Three Position and Four Position synthesis of four bacterials of the Position Synthesis of Synthesis (Part In Proceedings of the Position Synthesis (Part In Proceedings of the Part In Pro	oar Mechanism, Slide	neration er crank	n G	raphi	ical sm,
Type, Number Methods: Two Precision pos	er and Dimensional Synthesis - Function Generation - Path Gener o Position, Three Position and Four Position synthesis of four b	oar Mechanism, Slide	neration er crank	n G	raphi	ical sm, rve
Type, Number Methods: Two Precision post Synthesis - Column UNIT III Fixed and more	er and Dimensional Synthesis - Function Generation - Path Generation Position, Three Position and Four Position synthesis of four bitions Over lay Method. Analytical Methods: Blotch's Synthesis ognate linkages - The Roberts - Chebyshev theorem. PATH CURVATURE THEORY Description of the collination axis and Bobiller's theorem - Conjugate points and Bobiller's theo	oar Mechanism, Slide - Freudestien's Met he Inflection Circle	eneration er crank hod - C	n G Mec Coupl Output	raphichaniser cu 0 - Sav	ical sm, rve
Type, Number Methods: Two Precision post Synthesis - Column UNIT III Fixed and moderation - Tile	er and Dimensional Synthesis - Function Generation - Path Generation Position, Three Position and Four Position synthesis of four bitions Over lay Method. Analytical Methods: Blotch's Synthesis ognate linkages - The Roberts - Chebyshev theorem. PATH CURVATURE THEORY Description of the collination axis and Bobiller's theorem - Conjugate points and Bobiller's theo	oar Mechanism, Slide - Freudestien's Met he Inflection Circle	eneration er crank hod - C	n G Mec Coupl Output	raphichaniser cu 0 - Sav	sm, rve 9 ary
Type, Number Methods: Two Precision post Synthesis - Color UNIT III Fixed and mode Equation - True Curvature - Barrell UNIT IV Static force and Total Color of the Color of	er and Dimensional Synthesis - Function Generation - Path Generation Position, Three Position and Four Position synthesis of four bestitions Over lay Method. Analytical Methods: Blotch's Synthesis organte linkages - The Roberts - Chebyshev theorem. PATH CURVATURE THEORY Eving centrodes Hartmann's Construction - Inflection Points, The collination axis and Bobiller's theorem - Conjugate points and all's Point.	he Inflection Circle d inverse motion - 7	er crank hod - (n G	oraphichaniser cu O Savation	ary ary
Type, Number Methods: Two Precision post Synthesis - Color UNIT III Fixed and mode Equation - True Curvature - Barrell UNIT IV Static force and Total Color of the Color of	er and Dimensional Synthesis - Function Generation - Path Generation Position, Three Position and Four Position synthesis of four bestitions Over lay Method. Analytical Methods: Blotch's Synthesis orgnate linkages - The Roberts - Chebyshev theorem. PATH CURVATURE THEORY Eving centrodes Hartmann's Construction - Inflection Points, The collination axis and Bobiller's theorem - Conjugate points and all's Point. DYNAMICS OF MECHANISMS malysis - Inertia force analysis - Combined static and inertia force	he Inflection Circle d inverse motion - 7	er crank hod - (n G	oraphichaniser cu O Savation	ical sm, rve 9 ary ary
Type, Number Methods: Two Precision post Synthesis - Color UNIT III Fixed and moderate and mode	er and Dimensional Synthesis - Function Generation - Path Generation Position, Three Position and Four Position synthesis of four batterions Over lay Method. Analytical Methods: Blotch's Synthesis ognate linkages - The Roberts - Chebyshev theorem. PATH CURVATURE THEORY Eving centrodes Hartmann's Construction - Inflection Points, The collination axis and Bobiller's theorem - Conjugate points and all's Point. DYNAMICS OF MECHANISMS Inalysis - Inertia force analysis - Combined static and inertia force ment balancing of linkages	he Inflection Circle d inverse motion - The Analysis - Shaking for analysis of analysis of spatial manalysis of sp	9 - The E The Cul 9 spatial gles - In	on Go Mec Coupl Outer pic St Outer of the mechantrodu	raphirhanise of the control of the c	gary ary grant to grant to

TEXT	BOOKS:						
1.	Amitabha Ghosh and Asok Kumar Mallik, "Theory of Mechanism and Machines", EWLP, Delhi,1999.						
2.	nneth J, Waldron, Gary L. Kinzel, "Kinematics, Dynamics and Design of Machinery", John Wiley-sons, 2016.						
REFE	RENCES:						
1	Uicker, J.J., Pennock, G. R. and Shigley, J.E., "Theory of Machines and Mechanisms", Oxford University Press, 2017.						
2	Sandor G.N., and Erdman A.G., "Advanced Mechanism Design Analysis and Synthesis", Prentice Hall, 1984.						

3	Robert L.Norton., "Design of Machinery", Tata McGraw Hill, 2012
4	Sandor G.N., Erdman, A. G, "Advanced mechanism design", Prentice Hall Inc, 1984
5	Suh C.H., Radcliff C.W, "Kinematics and mechanisms design", John Wiley &Sons., 1978.

	IRSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped			
CO1	Analysis the kinematics of mechanisms	Evaluate			
CO2	Synthesis the kinematics of linkages	Evaluate			
CO3	Acquire knowledge about the theory of path curvature	Understand			
CO4	Learned the dynamics of mechanisms	Evaluate			
CO5	Design the robotics arms and manipulators	Apply			

COURSE A	OURSE ARTICULATION MATRIX														
COs/P Os	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	2	2	0	0	1	1	0	0	1	0	2	2	1
CO2	2	2	2	2	0	0	1	1	0	0	1	0	2	2	1
CO3	1	1	1	1	0	0	0	0	0	0	0	0	1	1	0
CO4	2	2	2	2	0	0	1	1	0	0	1	0	2	2	1
CO5	2	2	2	2	0	0	1	1	0	0	1	0	2	2	1
Avg	1.8	1.8	1.8	1.8	0	0	0.8	0.8	0	0	0.8	0	1.8	1.8	0.8

22ME	EPE52	DESIGN OF JIGS, FIXTURES AND PRESS TOOLS		SEM	IEST	ER	VII
PRE	REQUI	SITES CATEGO	RY	PE	Cro	edit	3
				L	Т	P	TF
		Hours/W	eek	3	0	0	3
COU	JRSE O	BJECTIVES:					1
1.	To und	erstand the functions and design principles of Jigs and fixtures					
2.	To kno	w the importance of work piece location and its design					
3.	To kno	w the importance of work piece clamping and its design					
4.	To kno	w about the importance of jigs bushings and drill jig					
5.	To kno	w about the design of fixtures					
UN	ITI	BASICS OF JIGS AND FIXTURES		9	0	0	9
point locate clamp quick	cs- specia or – Qu ping- lev c action c	location- types of locators- pins and studs- V block- cup and cone location and adjustable stops- location from finished holes in the work. Diamond pin lick action 'V' locator - Six-point location of a three-legged object. Principer clamp- hinged clamp- two-way clamp - swinging clamp- wedge clamp- eccenter. Clamp. Cam operated clamp- quarter turn screw. Toggle clamp- Pneumatic and h	ocator- les of o tric clar	Cam clamp mping	opera ing- 1 arran	ated ' types geme	v,
		pherical and flat washers. Tolerance. Tolerance Analysis and problems				, asiic	
OI		pherical and flat washers. Tolerance, Tolerance Analysis and problems. DESIGN OF JIGS		9	0	0	
Jigs,			ulic and	_	Ů	0	ers-
Jigs, Index	xing Jigs	DESIGN OF JIGS f Jigs – Post, turnover, Channel, Latch, Box, Pot, Angular post jigs –Hydra	ulic and	_	Ů	0	9 s -
Jigs, Index UNI Jig E bushi jig- p	IT IV Bushing: ing- screen blate drill	DESIGN OF JIGS f Jigs – Post, turnover, Channel, Latch, Box, Pot, Angular post jigs –Hydra –Design and Development of Jigs and Fixtures for the given component.	renew gs: Ope	d Pne 9 able to drill	umati 0 oushir jig pl	o de Jigo o de J	9 s - 9 ner rill
Jigs, Index UN Jig E bushi jig- p	IT IV Bushing: ing- screplate drill post jig- i	DESIGN OF JIGS f Jigs – Post, turnover, Channel, Latch, Box, Pot, Angular post jigs –Hydra –Design and Development of Jigs and Fixtures for the given component. JIG BUSHINGS AND DRILL JIGS Materials for jig bushing - press fit bushing- Fixed renewable bushing- slip w bushing- miscellaneous type of drill bushings- bushing specifications. Drill Jig jig- template drill jig- channel drill jig- turn over drill jig- angle plate drill jig- cl	renew gs: Ope	d Pne 9 able to drill	umati 0 oushir jig p	o de Jigo o de J	9 s -

TEXT I	BOOKS:						
1.	Design of Jigs, Fixtures and Press tools, C.Elanchezhian, T.Sunderselvan, B.Vijayaramnath, Eswar Press, 2005.						
2.	gpal, G R, Tool Engineering & Design, 2000, Khanna Publishers.						
REFER	ENCES:						
1	Joshi, P H, Jigs & Fixtures, 2010, 3rd Edition, McGraw Hill.						
2	Jig and fixture design- 5th edition by Hoffman						
3	Venkataraman, K, Design of Jigs, Fixtures & Press Tools, 2015, Wiley & Sons						

Total (45L) = 45 Periods

4	Mehta, N K, Metal Cutting and Design of Cutting Tools, Jigs & Fixtures, 2015, McGraw
5	Design Data, PSG Tech, Coimbatore, 2003.

	RSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Understand the basics of jigs and fixtures and its designing principles	Understand
CO2	Identify and design the various locating and clamping devices	Evaluate
CO3	Design the jigs for various components.	Create
CO4	Identify and design the jig bushes and drill jigs.	Evaluate
CO5	Design the fixtures for various components.	Create

COURSE A	ARTI	CULA	ATIO	N MA	TRIX	K									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	2	1	1	0	2	1	1	0	1	0	2	2	1
CO2	1	2	2	1	1	0	1	1	1	0	1	0	2	2	1
CO3	1	2	2	2	2	0	1	1	1	0	1	0	2	2	1
CO4	1	2	1	1	3	0	2	1	1	0	1	0	2	2	1
CO5	1	2	1	1	3	0	2	1	1	0	1	0	2	2	1
Avg	1	2	1.4	1.2	2.0	0	1.6	1	1	0	1	0	2	2	1
3/2/1 – indic	ates st	rength	of cor	relatio	n (3 –	high, 2	2- med	ium, 1-	low)	I	I			ı	ı

22IVII	EPE53	HEAT TRANSFER PROBLEMS IN ELECTRON INSTRUMENTATION	ICS AND	SEM	1EST	ER	VIII	
PRER	EQUIS	ITES	CATEGORY	PE	Cre	edit	3	
.Funda	amental	knowledge in various modes of heat transfer	** /**/ 1	L	Т	P	TH	
2.Basic	c concep	ts of electronics and instrumentation	Hours/Week	3	0	0	3	
COU	RSE O	BJECTIVES: The main learning objective of this course is to pre	pare the students fo	r:	•	•	•	
1.	Unders	tanding the basic principles of heat transfer in electronic systems						
2.	Learnii	ng to solve conduction heat transfer problems in electronic equipme	nt					
3.	Studyii	ng about the convection heat transfer phenomena in electronic applications	cations					
4.	Acquir	ing the knowledge in the radiation heat transfer in electronic instrur	nents					
5.	Unders	tanding the principles of thermal design of electronic equipment						
UN	UNIT I INTRODUCTION TO ELECTRONICS SYSTEMS AND HEAT TRANSFER							
Syste		ectronic and instrumentations, basics of thermodynamics and hermal management in electronic devices - Packaging Trends. Ele						
UNI	T II	CONDUCTION HEAT TRANSFER IN ELECTRONIC EQUIPMENT		9	0	0	9	
Cond Optin	uction—	n Simple Geometries, Conduction through a Plane Wall, Conduction Transient, Lumped Capacitance Method, Conduction in Ext Fin Surface Efficiency, Thermal Contact Resistance in Electronic ading.	ended Surfaces. I	Fin Ef	ficien	ıcy,	Fin	
UNI	T III	CONVECTION HEAT TRANSFER IN ELECTRONIC EQUIPMENT		9	0	0	9	
Coeff	icient. L	eat Transfer in Electronic Equipment. Natural Convection in Ele iquid Cooling Systems, Coolant Selection, Pressure Drop and Pu aft Cooling, Selection of Fans and Blowers.						
	T IV					0	9	
UNI		RADIATION HEAT TRANSFER IN ELECTRONIC F	QUIPMENT	9	0			
UNI The Emitt	Electron ance Fac	ragnetic Spectrum, Radiation Equations, Stefan-Boltzmann Latter, Emittance from Extended Surface, Absorptance, Reflectance, S. Combined Modes of Heat Transfer for Electronic Equipment, Rad	w, Surface Charac	teristic e, Heat	s, Er Trans	sfer w		
UNI The Emitt Phase	Electron ance Fac	agnetic Spectrum, Radiation Equations, Stefan-Boltzmann Lattor, Emittance from Extended Surface, Absorptance, Reflectance, S	w, Surface Charac pecular Reflectance iation and Convecti	teristic e, Heat	s, Er Trans	sfer w		
UNI The Emitt Phase UNI Analy Stiffn Heat	Electron ance Face Change TT V vsis of Ti ess on V Sinks, 1	nagnetic Spectrum, Radiation Equations, Stefan-Boltzmann Lattor, Emittance from Extended Surface, Absorptance, Reflectance, Stefan-Boltzmann Lattor, Emittance from Extended Surface, Absorptance, Reflectance, Stefan-Boltzmann Lattor, Equipment, Radiation Stefan-Boltzmann Lattor, Equipment, Radiation Equipment, Radiation Equipment, Radiation Equipment, Radiation Equations, Stefan-Boltzmann Lattor, Education Education Equations, Stefan-Boltzmann Lattor, Education E	w, Surface Charac pecular Reflectance iation and Convecti ENT esses and Strain, Effectronics Cooling	teristice, Heat on in F 9 fect of Method	es, Er Trans Paralle 0 PCB	sfer well. 0 Bend Indus	yith 9 ing try.	
UNI The Emitt Phase UNI Analy Stiffn Heat	Electron ance Face Change TT V vsis of Ti ess on V Sinks, 1	ragnetic Spectrum, Radiation Equations, Stefan-Boltzmann Lartor, Emittance from Extended Surface, Absorptance, Reflectance, S. Combined Modes of Heat Transfer for Electronic Equipment, Radiation THERMAL ANALYSIS OF ELECTRONIC EQUIPMENT Properties of Electronic Components. Analysis of Thermal Strevire Stresses, Vibration Fatigue in Lead Wires and Solder Joints. Electronics, Heat Pipes in Electronics Cooling, Thermoelectric	w, Surface Charac pecular Reflectance iation and Convecti ENT esses and Strain, Eff lectronics Cooling Cooling, Immersion	teristice, Heat on in F 9 fect of Method	es, Er Trans Paralle 0 PCB ds in loling,	sfer well. 0 Bend Indus Cool	9 ing try.	
UNI The Emitt Phase UNI Analy Stiffn Heat Techn	Electron ance Face Change TT V vsis of Ti ess on V Sinks, 1	tor, Emittance from Extended Surface, Absorptance, Reflectance, S. Combined Modes of Heat Transfer for Electronic Equipment, Rad THERMAL ANALYSIS OF ELECTRONIC EQUIPM nermal Failure of Electronic Components. Analysis of Thermal Strevire Stresses, Vibration Fatigue in Lead Wires and Solder Joints. Eleat Pipes, Heat Pipes in Electronics Cooling, Thermoelectric r High Density Electronics.	w, Surface Charac pecular Reflectance iation and Convecti ENT esses and Strain, Eff lectronics Cooling Cooling, Immersion	teristice, Heat on in F	es, Er Trans Paralle 0 PCB ds in loling,	sfer well. 0 Bend Indus Cool	9 ing try.	

TEXT B	TEXT BOOKS:									
1.	Heat transfer Dr. A.S. Padalkar, NiraliPrakashan, Pune 2012									
2.	Heat & mass transfer, D.S. Kumar, S.K. Kataria& Sons, 2010									
REFER	ENCES:									
1	Heat transfer B.L. Singhal, Techmax, publication, Pune 2010									
2	Heat & mass transfer, Mills and Ganesan, Pearson Publication, New Delhi 2010									

1 https://nptel.ac.in/courses

COUI	Bloom Taxonomy Mapped	
CO1	Apply the concepts of heat transfer laws and principles in electronic systems	Apply
CO2	Solve conduction heat transfer problems in various electronic instruments	Evaluate
CO3	Analyze the real time convection heat transfer problems of electronic equipment	Analyze
CO4	Solve the problems of combined effect of heat transfer form electronic equipment	Apply
CO5	Determine the thermal stresses and strains in various real time electronic systems	Evaluate

COURSE ARTICULAT	TON I	MATRIX
------------------	-------	--------

COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	1	0	1	0	0	2	0	0	0	0	1	1	1
CO2	3	2	0	0	0	0	0	1	0	0	0	0	2	1	1
CO3	3	3	0	0	1	0	0	2	0	0	0	0	3	3	2
CO4	3	2	0	0	2	0	0	1	0	0	0	0	3	1	1
CO5	0	0	1	1	0	1	1	0	0	0	0	1	0	0	0
Avg	2.2	1.8	0.4	0.2	0.8	0.2	0.2	1.2	0	0	0	0.2	1.8	1.2	1
1															

22ME	PE54	SEMESTER VI					
PRERE	EQUIS	SITES	CATEGORY	PE	Cre	edit	3
			** ***	L	Т	P	TH
			Hours/Week	3	0	0	3
COUF	•	•	•				
1.	To mot	tivate the students to understand the evolution of nanomaterials in th	e scientific era.				
2.	To mak	ke them to understand different processing methods.					
3.	To mak	ke them to understand properties of nanomaterials for the future engineers	ineering application	ıs			
UNI	ΙΤ	INTRODUCTION		9	0	0	9
nanosti	ructure	tience and Technology- Implications for Physics, Chemistry, Biol d materials- nano particles- quantum dots, nanowires-ultra-thinfilr effect on properties: Mechanical, Electronic, Optical, Magnetic and	nsmultilayered mat	erials.			
UNIT	ΓII	GENERAL METHODS OF PREPARATION		9	0	0	9
	bly, Var	onthesis-Top-down Approach: Co-Precipitation, Ultrasonication, Mepour phase deposition, MOCVD, Sputtering, Evaporation, Molecular					
UNIT	Ш	NANOMATERIALS		9	0	0	9
and M CVD), AgTiO	Iulti wa , structu) ₂ , Ferri	f Carbon - Buckminster fullerene- graphene and carbon nanotube, Sall carbon nanotubes (MWCNT)- methods of synthesis(arc-grownere-property Relationships applications- Nanometal oxides-ZnO, Tigites, Nanoclays- functionalization and applications-Quantum wire ons	th, laser ablation, O ₂ ,MgO, ZrO ₂ , NiC	CVD r	outes, alumi	, Plas na, C	ma aO,
and M CVD), AgTiO	Iulti wa , structu O ₂ , Ferri plicatio	all carbon nanotubes (MWCNT)- methods of synthesis(arc-grown are-property Relationships applications- Nanometal oxides-ZnO, Tienites, Nanoclays- functionalization and applications-Quantum wire ons	th, laser ablation, O ₂ ,MgO, ZrO ₂ , NiC	CVD r	outes, alumi	, Plas na, C	ma aO,
and M CVD), AgTiO and app UNIT X-ray Micros	Iulti wa structu O ₂ , Ferri plicatio I IV diffrac scopy ir	all carbon nanotubes (MWCNT)- methods of synthesis(arc-growner-property Relationships applications- Nanometal oxides-ZnO, Tietes, Nanoclays- functionalization and applications-Quantum wire ons CHARACTERIZATION TECHNIQUES ction technique, Scanning Electron Microscopy - environmental negligible resolution imaging, Surface Analysis techniques- Al	th, laser ablation, O ₂ ,MgO, ZrO ₂ , NiCos, Quantum dots-producted techniques, Transcription	CVD root nanoa reparati 9 ansmis	outes, alumi on, p	Plas na, Ca roper	ma aO, ties 9
and M CVD), AgTiO and app UNIT X-ray Micros	fulti wa , structu O ₂ , Ferri plicatio T IV diffrac scopy in	all carbon nanotubes (MWCNT)- methods of synthesis(arc-growner-property Relationships applications- Nanometal oxides-ZnO, Tietes, Nanoclays- functionalization and applications-Quantum wire ons CHARACTERIZATION TECHNIQUES ction technique, Scanning Electron Microscopy - environmental negligible resolution imaging, Surface Analysis techniques- Al	th, laser ablation, O ₂ ,MgO, ZrO ₂ , NiCos, Quantum dots-producted techniques, Transcription	CVD root nanoa reparati 9 ansmis	outes, alumi on, p	Plas na, Ca roper	ma aO, ties 9
and M CVD), AgTiO and app UNIT X-ray Micros Nano i UNIT	Iulti wa structu 0 ₂ , Ferri pplicatio r IV diffrac scopy ir indentat r V InfoTec robes in	all carbon nanotubes (MWCNT)- methods of synthesis(arc-grownere-property Relationships applications- Nanometal oxides-ZnO, Tities, Nanoclays- functionalization and applications-Quantum wire ons CHARACTERIZATION TECHNIQUES etion technique, Scanning Electron Microscopy - environment ncluding high-resolution imaging, Surface Analysis techniques- Altion.	th, laser ablation, O ₂ ,MgO, ZrO ₂ , NiCos, Quantum dots-process,	9 Nanob Bioima ano cry	outes, aluminon, p on, p sion ESCA onioteclaging ystalli	Plas na, Croper O Elect A, SIN O hnolo - Mi ne sil	ma aO, ties 9 ron dS- gy: cro ver
and M CVD), AgTiO and app UNIT X-ray Micros Nano i UNIT Nano l nanopr Electro for bac	fulti wa structu 0 ₂ , Ferri plicatio TIV diffrac scopy ir indentat TV InfoTec robes in o Mecha eterial ir	all carbon nanotubes (MWCNT)- methods of synthesis(arc-grownere-property Relationships applications- Nanometal oxides-ZnO, Tientes, Nanoclays- functionalization and applications-Quantum wire ons CHARACTERIZATION TECHNIQUES Ction technique, Scanning Electron Microscopy - environment including high-resolution imaging, Surface Analysis techniques- Altion. APPLICATIONS Ch: Information storage- Nano computer, molecular switch, superint medical diagnostics and biotechnology, Nano medicines, Target anical Systems (MEMS), Nano Electro Mechanical Systems (NEM inhibition, Nanoparticles for sun barrier products - In Photostat, printing and the products in Photostat, printing and the printing and the printing and the printin	th, laser ablation, O ₂ ,MgO, ZrO ₂ , NiCos, Quantum dots-process,	9 ansmiss NOM, P Nanob Bioima ano cry	outes, aluminon, p on, p sion ESCA onioteclaging ystalli	Plas na, Croper O Elect A, SIN O hnolo - Mi ne sil	ma aO, ties 9 ron IS- gy: cro
and M CVD), AgTiO and app UNIT X-ray Micros Nano i UNIT Nano l nanopr Electro for bac	Iulti wa structu D2, Ferriplicatio T IV diffractscopy ir indentat T V InfoTecrobes impo Mechaeterial ir	all carbon nanotubes (MWCNT)- methods of synthesis(arc-grownere-property Relationships applications- Nanometal oxides-ZnO, Tivites, Nanoclays- functionalization and applications-Quantum wire ons CHARACTERIZATION TECHNIQUES Ction technique, Scanning Electron Microscopy - environment necluding high-resolution imaging, Surface Analysis techniques- Altion. APPLICATIONS Ch: Information storage- Nano computer, molecular switch, supern medical diagnostics and biotechnology, Nano medicines, Target anical Systems (MEMS), Nano Electro Mechanical Systems (NEM nhibition, Nanoparticles for sun barrier products - In Photostat, prince and supern medical diagnostics and biotechnology of the products - In Photostat, prince and supern medical diagnostics and biotechnology of the products - In Photostat, prince and supern medical diagnostics and biotechnology of the products - In Photostat, prince and supern medical diagnostics and biotechnology of the products - In Photostat, prince and supern medical diagnostics and biotechnology of the products - In Photostat, prince and supern medical diagnostics and biotechnology of the products - In Photostat, prince and supern medical diagnostics and biotechnology of the products - In Photostat, prince and supern medical diagnostics and biotechnology of the products - In Photostat, prince and supern medical diagnostics and biotechnology of the products - In Photostat, prince and supern medical diagnostics and biotechnology of the products - In Photostat, prince and supern medical diagnostics and biotechnology of the products - In Photostat, prince and supern medical diagnostics and biotechnology of the products - In Photostat, prince and supern medical diagnostics and biotechnology of the prince and supern medical diagnostics and biotechnology of the prince and supern medical diagnostics and biotechnology of the prince and supern medical diagnostics and supern med	th, laser ablation, O ₂ ,MgO, ZrO ₂ , NiCos, Quantum dots-process,	Popular of the control of the contro	outes, aluminon, p on, p sion ESCA obioteclaging ystalli L) = 4	Plas na, Caroper O Electa, SIN O hnolo - Mine sil	ma ao, ties 9 ron MS- gy: cro ver
and M CVD), AgTiO and app UNIT X-ray Micros Nano i UNIT Nano l nanopr Electro for bac	Iulti wa structu 0 ₂ , Ferri pplicatio IV diffrac scopy ir indentat IV UnfoTec robes in o Mecha eterial ir	all carbon nanotubes (MWCNT)- methods of synthesis(arc-grownere-property Relationships applications- Nanometal oxides-ZnO, Tientes, Nanoclays- functionalization and applications-Quantum wire ons CHARACTERIZATION TECHNIQUES Ction technique, Scanning Electron Microscopy - environment including high-resolution imaging, Surface Analysis techniques- Altion. APPLICATIONS Ch: Information storage- Nano computer, molecular switch, superint medical diagnostics and biotechnology, Nano medicines, Target anical Systems (MEMS), Nano Electro Mechanical Systems (NEM inhibition, Nanoparticles for sun barrier products - In Photostat, printing and the products in Photostat, printing and the printing and the printing and the printin	th, laser ablation, O ₂ ,MgO, ZrO ₂ , NiCos, Quantum dots-process,	Popular of the control of the contro	outes, aluminon, p on, p sion ESCA obioteclaging ystalli L) = 4	Plas na, Caroper O Electa, SIN O hnolo - Mine sil	ma aO, ties 9 ron MS- gy: cro ver
and M CVD), AgTiO and app UNIT X-ray Micros Nano i UNIT Nano l nanopr Electro for bac	Iulti wa structu 102, Ferri plicatio 1 IV 1 diffract scopy ir indentat 1 V InfoTecrobes in the characterial ir BOOK Car Pub A.S	all carbon nanotubes (MWCNT)- methods of synthesis(arc-grownere-property Relationships applications- Nanometal oxides-ZnO, Tivites, Nanoclays- functionalization and applications-Quantum wire ons CHARACTERIZATION TECHNIQUES Ction technique, Scanning Electron Microscopy - environment including high-resolution imaging, Surface Analysis techniques- Altion. APPLICATIONS Ch: Information storage- Nano computer, molecular switch, superint medical diagnostics and biotechnology, Nano medicines, Target anical Systems (MEMS), Nano Electro Mechanical Systems (NEM inhibition, Nanoparticles for sun barrier products - In Photostat, print C. Koch (ed.), "Nanostructured Materials", Processing, Property of the computer of t	th, laser ablation, O ₂ ,MgO, ZrO ₂ , NiCos, Quantum dots-protein tal techniques, Tr. FM, SPM, STM, Since the chip, nanocrystal, ted drug delivery, S)- Nano sensors, noting, solar cell, batter tries and Potential	Popular of the control of the contro	outes, aluminon, p on, p sion ESCA oniotechaging ystalli ations	Plas na, Cr roper	ma aO, tiles 9 ron 1S- gy: cro ver rioc
and M CVD), AgTiO and app UNIT X-ray Micros Nano i UNIT Nano l nanopr Electro for bac TEXT l 1.	Iulti wa structu 102, Ferri plicatio 1 IV 1 diffract scopy ir indentat 1 V InfoTecrobes in the characterial ir BOOK Car Pub A.S	all carbon nanotubes (MWCNT)- methods of synthesis(arc-grownere-property Relationships applications- Nanometal oxides-ZnO, Tightes, Nanoclays- functionalization and applications-Quantum wire one. CHARACTERIZATION TECHNIQUES Cition technique, Scanning Electron Microscopy - environmental number of the compact of the com	th, laser ablation, O ₂ ,MgO, ZrO ₂ , NiCos, Quantum dots-protein tal techniques, Tr. FM, SPM, STM, Since the chip, nanocrystal, ted drug delivery, S)- Nano sensors, noting, solar cell, batter tries and Potential	Popular of the control of the contro	outes, aluminon, p on, p sion ESCA oniotechaging ystalli ations	Plas na, Cr roper	ma aO, ties 9 ron 1S- gy: cro ver
and M CVD), AgTiO and apply UNIT X-ray Micros Nano i UNIT Nano lananopr Electro for bace	Iulti wa structu 102, Ferri plicatio 1 IV 1 diffract scopy ir indentatt 1 V InfoTecrobes ir o Mecha cterial ir 1 BOOK Car Pub A.S. of I	all carbon nanotubes (MWCNT)- methods of synthesis(arc-grownere-property Relationships applications- Nanometal oxides-ZnO, Tightes, Nanoclays- functionalization and applications-Quantum wire one. CHARACTERIZATION TECHNIQUES Cition technique, Scanning Electron Microscopy - environmental number of the compact of the com	th, laser ablation, O ₂ ,MgO, ZrO ₂ , NiCos, Quantum dots-process,	Population of the control of the con	outes, aluminon, p on, p sion ESCA oniotechaging ystalli ations	Plas na, Cr roper	ma aO, tiles 9 ron 1S- gy: cro ver rioc

Charles P. Poole Jr., Frank J. Ownes, 'Introduction to Nanotechnology", Wiley Interscience, 2003

Mark Ratner and Daniel Ratner, "Nano Technology", Pearson Education, New Delhi, 2003.

Simulations". Prentice-Hall of India (P) Ltd, New Delhi, 2007.

3

45

Akhlesh Lakhtakia, "The Hand Book of Nano Technology, Nanometer Structure, Theory, Modeling and

COUL	Bloom Taxonomy Mapped	
CO1	Will familiarize about the science of nanomaterials	Remember
CO2	Will demonstrate the preparation of nanomaterials	Understand
CO3	Use of difficult characterization techniques to study the fundamental properties.	Apply
CO4	To know the various industrial applications using nanomaterials.	Understand
CO5	Will familiarize about the science of nanomaterials	Remember

COURSE A	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	2	1	0	2	0	1	0	0	1	0	2	2	1
CO2	2	1	1	1	0	0	1	0	0	0	1	0	2	1	0
CO3	2	1	1	1	0	0	1	0	0	0	1	0	2	1	0
CO4	2	1	1	1	0	1	1	1	0	0	1	0	2	1	0
CO5	2	2	1	1	0	1	1	1	0	0	1	0	2	2	1
Avg	2.0	1.4	1.2	1.0	0.0	0.8	0.8	0.6	0.0	0.0	5.0	0.0	2.0	1.4	0.4
3/2/1 – indic	ates st	rength	of cor	relatio	n (3 –	high, 2	2- med	ium, 1-	low)						•

22MEPE55	NUCLEAR ENGINEERING		SEN	IEST	ER	VIII		
PREREQUI	SITES	CATEGORY	Y PE credit					
			L	Т	P	TH		
		Hours/Week	3	0	0	3		
COURSE O	OBJECTIVES:		I					
1. To tea	ch the fundamental physics about nuclear processes and a heat transf	er technique from n	uclear	energ	y			
2. To intr	oduce the nuclear fuels, its properties and extraction techniques of n	uclear fuels.						
3. To tea	ch the characteristics of spent fuel and reprocessing techniques.							
4. To tea	ch the design, construction and heat transfer in nuclear reactor.							
5. To tea	ch the safety aspects used in nuclear reactor and disposal of nuclear v	waste.						
UNIT I	NUCLEAR REACTIONS		9	0	0	9		
Mechanism o	of Nuclear Fission - Nuclides - Radioactivity - Decay Chains - Neutr	on Reactions - The	Fission	Proc	ess			
UNIT II	REACTOR MATERIALS		9	0	0	9		
	cs of Nuclear Fuels - Uranium - Production and Purification of Unike Zirconium, Thorium - Beryllium.	ranium - Conversion	n to U	F4 an	d UF	6 -		
UNIT III	REPROCESSING		9	0	0	9		
Nuclear Fuel Equipment.	Cycles - Spent Fuel Characteristics - Role of Solvent Extraction	n in Reprocessing	- Solve	ent Ez	ktract	ion		
UNIT IV	NUCLEAR REACTOR		9	0	0	9		
	tors: types of fast breeding reactors-design and construction of fast bactors-reactor shielding. Fusion reactors.	reeding reactors-hea	at trans	fer tec	chniq	ues		
UNIT V	SAFETY AND DISPOSAL		9	0	0	9		
	sposal: Nuclear plant safety-safety systems-changes and consequence of waste and its disposal-radiation hazards and their prevention-weap		ria for	safety	-nucl	ear		
		Total	(45L)	= 451	Perio	ds		

TEXT I	EXT BOOKS:								
1.	Thomas J.Cannoly, "Fundamentals of nuclear Engineering" John Wiley 1978.								
2.	Glasstone, S and Sesonske, A, "Nuclear Reactor Engineering", 3rd Edition, Von Nostrand, 1981.								
3.	Lamarsh, J.R., "Introduction to Nuclear Reactor Theory", Wesley, 1966.								
REFER	ENCES:								
1	Winterton, R.H.S., "Thermal Design of Nuclear Reactors", Pergamon Press, 1981.								
2	Jelly N A, "Nuclear Engineering", Cambridge University Press, 2005.								
3	Duderstadt, J.J and Hamiition, L.J, "Nuclear Reactor Analysis", John Wiley, 1976.								
4	Walter, A.E and Reynolds, A.B, "Fast Breeder Reactor", Pergamon Press, 1981.								
E-REFE	RENCES:								
1	http://nptel.ac.in/courses/112101007/								

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:						
CO1	Understand the fundamental knowledge about nuclear reactions	Understand					
CO2	Understand the various nuclear fuels and its properties.	Understand					
CO3	Explain the nuclear fuel cycles and spent fuel characteristics.	Analyze					
CO4	Understand the design and heat transfer in nuclear reactor	Understand					
CO5	Explain the safe disposal of nuclear wastes.	Apply					

COURSE A	ARTI	CULA	TIO	N MA	TRIX	<u> </u>									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	2	1	1	1	1	0	0	0	0	0	1	1	1
CO2	1	1	2	1	2	1	2	0	0	0	0	0	2	3	3
CO3	1	1	1	1	1	1	1	0	0	0	0	0	1	2	1
CO4	3	1	1	1	1	2	1	0	0	0	0	0	3	1	1
CO5	1	1	2	1	1	1	1	0	0	0	0	0	1	3	1
Avg	1.6	1.2	1.6	1.0	1.2	1.6	1.6	0.0	0.0	0.0	0.0	0.0	1.6	2.0	1.4
	•		3/2	2/1 – iı	ndicate	s stren	gth of	correla	tion (3	- high,	2- mediu	ım, 1- lo	w)		

22MEPE56	THERMAL TURBO MACHINES		SEM	IEST	ER	VII	
PREREQU	ISITES	CATEGORY					
			L	Т	P	TI	
		Hours/Week	3	0	0	3	
COURSE C	OBJECTIVES:				<u>.</u>	1	
1. To und compo	derstand the various systems, principles, operations and application nents.	s of different types	of turb	bo ma	chine	ery	
UNIT I	INTRODUCTION TO TURBO MACHINES		9	0	0	9	
machines – c and Total –	city triangles Thermal Turbo machines – Classification – General compression and expansion process – Velocity triangles – Work – Toto – Static efficiencies. Dimensional analysis – Non dimensional imilarity laws, applications and limitations.	S-S and H-S diagram	n, Tota	al – to) – To	otal	
TINITED TT							
UNIT II	CENTRIFUGAL FANS AND COMPRESSOR		9	0	0	9	
Definition, se impeller blad measures. Ce	CENTRIFUGAL FANS AND COMPRESSOR election and classifications –Types of blading design-velocity triangles –Design parameter- Volute and Diffusers – Efficiencies and Losentrifugal Compressors: - Constructional details – Stage velocity trafficiency – Degree of reaction – Slip factor – H-S diagram – Efficien	ses – Fan noises – iangles — Stage w	rs – Flo Causes ork – S	ow an and a	alysis remed press	dial	
Definition, se impeller blad measures. Ce	election and classifications –Types of blading design-velocity triangles –Design parameter- Volute and Diffusers – Efficiencies and Losentrifugal Compressors: - Constructional details – Stage velocity triangles	ses – Fan noises – iangles — Stage w	rs – Flo Causes ork – S	ow an and a	alysis remed press	s in dial ure	
Definition, se impeller blad measures. Ce rise – Stage e UNIT III Definition an Cascade tunic Compressors pressure rise	election and classifications –Types of blading design-velocity triangles –Design parameter- Volute and Diffusers – Efficiencies and Losentrifugal Compressors: - Constructional details – Stage velocity trifficiency – Degree of reaction – Slip factor – H-S diagram – Efficien	ses – Fan noises – iangles — Stage w ncies – Performance nnce characteristics. in terms of lift and elocity triangles –	rs – Flo Causes ork – S charac g charac d drag Stage	ow and a stage of the stage of	alysis remed press ics. 0 blade ial Fl – Sta	s in dial ure	
Definition, se impeller blad measures. Ce rise – Stage e UNIT III Definition an Cascade tunic Compressors pressure rise	election and classifications –Types of blading design-velocity triangles –Design parameter- Volute and Diffusers – Efficiencies and Losentrifugal Compressors: - Constructional details – Stage velocity trafficiency – Degree of reaction – Slip factor – H-S diagram – Efficiency – AXIAL FANS AND COMPRESSOR and classifications – Stage parameters – Types of fan stages-performatel - Blade Geometry-Cascade Variables-Energy transfer and loss: definition and classifications – Constructional details – Stage velocity transfer and losser – H-S diagram – Stage efficiencies and losses- Degree of reactions.	ses – Fan noises – iangles — Stage w ncies – Performance nnce characteristics. in terms of lift and elocity triangles –	rs – Flo Causes ork – S charac g charac d drag Stage	ow and a stage of the stage of	alysis remed press ics. 0 blade ial Fl – Sta	s in dial ure 9 es – low	
Definition, se impeller blad measures. Ce rise – Stage e UNIT III Definition and Cascade tunic Compressors pressure rise Stalling – Per UNIT IV Construction	election and classifications –Types of blading design-velocity triangles –Design parameter- Volute and Diffusers – Efficiencies and Losentrifugal Compressors: - Constructional details – Stage velocity triafficiency – Degree of reaction – Slip factor – H-S diagram – Efficiency – AXIAL FANS AND COMPRESSOR declassifications – Stage parameters – Types of fan stages-performantel - Blade Geometry-Cascade Variables-Energy transfer and loss: definition and classifications – Constructional details – Stage vertical details –	ses – Fan noises – iangles — Stage we noises – Performance ance characteristics. in terms of lift and elocity triangles – tion – Radial Equi	Cascad drag Stage librium	ow and a stage of the stage of	alysis remed pressics. 0 blade ial Fl - Staging a	s in dial ure 9 es – ow age and	
Definition, se impeller blad measures. Ce rise – Stage e UNIT III Definition and Cascade tunic Compressors pressure rise Stalling – Per UNIT IV Construction	election and classifications –Types of blading design-velocity triangles –Design parameter- Volute and Diffusers – Efficiencies and Losentrifugal Compressors: - Constructional details – Stage velocity triafficiency – Degree of reaction – Slip factor – H-S diagram – Efficiency – AXIAL FANS AND COMPRESSOR In additional classifications – Stage parameters – Types of fan stages-performatel - Blade Geometry-Cascade Variables-Energy transfer and loss: definition and classifications – Constructional details – Stage velocity – H-S diagram – Stage efficiencies and losses- Degree of reactions – Constructional details – Stage velocity triangles	ses – Fan noises – iangles — Stage we noises – Performance ance characteristics. in terms of lift and elocity triangles – tion – Radial Equi	Cascad drag Stage librium	ow and a stage of the stage of	alysis remed pressics. 0 blade ial Fl - Staging a	s in dial ure 9 es – low age and	

Total (45L) = 45Periods

TEXT I	BOOKS:
1.	Yahya, S.M., "Turbines, Compressors and Fans", Tata McGraw Hill Publishing Company, 1996.
2.	Dixon S.L, "Fluid Mechanics, Thermodynamics of Turbo Machines", 2nd Edition, Pergamon press, 1990.
3.	Kadambi V and Manohar Prasad, "An Introduction to Energy Conversion - Vol. III Turbo Machines", Wiley Eastern India Ltd, 1977.
REFE	RENCES:
1	Bruneck, Fans, Pergamom Press, 1973.
2	Earl Logan, Jr., Hand book of Turbomachinery, Marcel Dekker Inc., 1992.
3	Shepherd, D.H., Principles of Turbomachinery, Macmillan, 1969.
4	Stepanpff, A.J., Blowers and Pumps, John Wiley and Sons Inc. 1965.
5	Ganesan, V., Gas Turbines, Tata McGraw Hill Pub. Co., 1999.
6	Rangwala A S, "Structural Dynamics of Turbo-Machines", New Age International, 2005.

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:						
CO1	Understand the Basic Concept of Compressors, Turbines, Fans and Blowers	Understand					
CO2	Analyze the velocity triangles of Centrifugal fans and Compressors.	Analyze					
CO3	Analyze the construction details and performance of axial fans and compressor.	Analyze					
CO4	Analyze the design variations of axial flow turbines	Analyze					
CO5	Understand the construction features and performance analysis of radial flow turbine and wind turbine	Understand					

COURSE A	ARTI	CULA	TIO	N MA	TRIX										
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	1	1	3	1	1	0	0	0	0	0	1	2	2
CO2	1	3	1	1	2	1	1	0	0	0	0	0	1	1	3
CO3	2	1	3	1	1	2	1	0	0	0	0	0	1	1	2
CO4	2	1	1	1	3	1	1	0	0	0	0	0	1	1	2
CO5	2	1	1	3	1	2	1	0	0	0	0	0	2	3	1
Avg	1.6	1.6	1.4	1.4	2.0	1.4	1.0	0.0	0.0	0.0	0.0	0.0	1.2	1.6	2.0
		•	3/2/1	– indi	cates st	rength	of co	relation	n (3 – ł	nigh, 2- r	nedium,	1- low)		•	•

	PE57	TOTAL QUALITY MANAGEMENT		SEM	IEST	ER	VIII
PRE	REQUI	SITES	CATEGORY	PE	Cre	dit	3
			TT /XX / 1 -	L	T	P	TH
			Hours/Week	3	0	0	3
COUF	RSE OB	BJECTIVES:					
1.		the need for quality, its evolution, basic concepts, contribution of quenefits of TQM.	uality gurus, TQM	framev	vork,	Barri	ers
2.	Explair	n the TQM Principles for application.					
3.	Define	the basics of Six Sigma and apply Traditional tools, New tools, Bendered	chmarking and FM	EA.			
4.	Describ and BP	be Taguchi's Quality Loss Function, Performance Measures and ap PR.	ply Techniques lik	ke QFD	, TPN	1, C0	QC
5.	Illustra	te and apply QMS and EMS in any organization.					
UNI	ΤI	INTRODUCTION		9	0	0	9
		- Quality council, Quality statements - Strategic planning - De	eming philosophy	- Bari	iers t	0 1	51v1
	ementation T II		eming philosophy	- Barr	0	0	9
UNI Custo Empl Conti	T II omer sati	on I	Service quality, and reward, Perfo	9 Customormanco, Sour	0 ner Re	0 etenti	9 on, l -
UNI Custo Empl Conti	T II omer sati	TQM PRINCIPLES isfaction - Customer perception of quality, Customer complaints, volvement - Motivation, Empowerment, Teams, Recognition a rocess improvement - Juran Trilogy, PDSA Cycle, 5S, Kaizen - St.	Service quality, and reward, Perfo	9 Customormanco, Sour	0 ner Re	0 etenti	9 on, l -
UNI Custo Employer Continued Continu	T II omer satioyee invitation, Suption, Suption	TQM PRINCIPLES isfaction - Customer perception of quality, Customer complaints, volvement - Motivation, Empowerment, Teams, Recognition a rocess improvement - Juran Trilogy, PDSA Cycle, 5S, Kaizen - Supplier rating, Relationship development - Performance measures, Base STATISTICAL PROCESS CONTROL (SPC) ols of quality, Statistical fundamentals - Measures of central tental curve - Control charts for variables and attributes, Process capab	Service quality, and reward, Performance Partnership ic concepts, Strates adency and dispers	9 Customormanco, Souregy 9	oner Ree appcing, S	oetenti raisa Supp	9 on, 1 - lier 9
UNI Custo Employer Continued Continu	T II omer satioyee invition, Suption,	TQM PRINCIPLES isfaction - Customer perception of quality, Customer complaints, volvement - Motivation, Empowerment, Teams, Recognition a rocess improvement - Juran Trilogy, PDSA Cycle, 5S, Kaizen - Supplier rating, Relationship development - Performance measures, Base STATISTICAL PROCESS CONTROL (SPC) ols of quality, Statistical fundamentals - Measures of central tental curve - Control charts for variables and attributes, Process capab	Service quality, and reward, Performance Partnership ic concepts, Strates adency and dispers	9 Customormanco, Souregy 9	oner Ree appcing, S	oetenti raisa Supp	9 on, l - lier 9
UNI' Custo Empl Conti select UNI' The samp Mana UNI' Benci qualit	T II omer satioyee invition, Suption, Suption, Suption, Suption, Suption, Suption agement to the seven too the se	TQM PRINCIPLES isfaction - Customer perception of quality, Customer complaints, volvement - Motivation, Empowerment, Teams, Recognition a rocess improvement - Juran Trilogy, PDSA Cycle, 5S, Kaizen - Supplier rating, Relationship development - Performance measures, Base STATISTICAL PROCESS CONTROL (SPC) ols of quality, Statistical fundamentals - Measures of central tental curve - Control charts for variables and attributes, Process capable tools.	Service quality, and reward, Performand reward, Performand ic concepts, Strates adency and dispersibility - Concept of strates deployment (QFD)	Customormanco, Sources 9 9 sion, Psix sign	oner Ree appring, Sono opulationa, ne	0 etenti rraisa Supp 0 tion a www.sev	9 on, 1 - lier 9 and wen 9
UNI' Custo Empl Conti select UNI' The samp Mana UNI' Benci qualit	T II omer satioyee invition, Suption, Suption, Suption, Suption, Suption, Suption, Suption, Normagement to T IV hmarking ty, Benef A – Stage	TQM PRINCIPLES isfaction - Customer perception of quality, Customer complaints, volvement - Motivation, Empowerment, Teams, Recognition as rocess improvement - Juran Trilogy, PDSA Cycle, 5S, Kaizen - Supplier rating, Relationship development - Performance measures, Base STATISTICAL PROCESS CONTROL (SPC) ols of quality, Statistical fundamentals - Measures of central tental curve - Control charts for variables and attributes, Process capabitools. TQM TOOLS g - Reasons to benchmark, Benchmarking process, Quality function fits - Taguchi quality loss function - Total productive maintenance	Service quality, and reward, Performand reward, Performand ic concepts, Strates adency and dispersibility - Concept of strates deployment (QFD)	Customormanco, Sources 9 9 sion, Psix sign	oner Ree appring, Sono opulationa, ne	0 etenti rraisa Supp 0 tion a www.sev	9 on, 1 - lier 9 and wen 9
UNI' Custo Empl Contiselect UNI' The samp Mana UNI' Bencl qualit FME. UNI'	omer sational contents of the seven too the seven too the seven to the	TQM PRINCIPLES isfaction - Customer perception of quality, Customer complaints, volvement - Motivation, Empowerment, Teams, Recognition a rocess improvement - Juran Trilogy, PDSA Cycle, 5S, Kaizen - Suplier rating, Relationship development - Performance measures, Base STATISTICAL PROCESS CONTROL (SPC) ols of quality, Statistical fundamentals - Measures of central tentral curve - Control charts for variables and attributes, Process capabitools. TQM TOOLS g - Reasons to benchmark, Benchmarking process, Quality function fits - Taguchi quality loss function - Total productive maintenance es of FMEA.	Service quality, and reward, Performership ic concepts, Strates adency and dispersility - Concept of strates (TPM) concept, I	Customormanco, Sources, Source	oner Rece appring, Some opulational, ner opulational o	0 etentiiraisa Supp 0 diion a w see	9 on, 1 - lier 9 9 ond wen 9 of ls - 9

TEXT B	OOKS:
1.	Dale H.Besterfiled, Carol B.Michna, Glen H. Bester field, Mary B.Sacre, Hemant Urdhwareshe and Rashmi Urdhwareshe, "Total Quality Management", Pearson Education Asia, Revised Third Edition, Indian Reprint, Sixth Impression, 2013.
2.	Feigenbaum.A.V. "Total Quality Management", McGraw Hill, 1991.
REFE	RENCES:
1	Joel.E. Ross, "Total Quality Management – Text and Cases",Routledge.,2017.
2	Kiran.D.R, "Total Quality Management: Key concepts and case studies, Butterworth – Heinemann Ltd, 2016.
3	Oakland, J.S. "TQM – Text with Cases", Butterworth – Heinemann Ltd., Oxford, Third Edition, 2003.

4	Suganthi, L and Anand Samuel, "Total Quality Management", Prentice Hall (India) Pvt. Ltd., 2006
5	Narayana V and Sreenivasan, N.S, "Quality Management – Concepts and Tasks", New Age International, 1996.
E-REFE	RENCES:
1	https://www.oreilly.com/library/view/total-quality-management/9780815330486/xhtml/Reference1.xhtml
2	https://www.sanfoundry.com/best-reference-books-total-quality-management/
3	https://www.routledge.com/Total-Quality-Management-TQM-Principles-Methods-and-Applications/Luthra-Garg-Agarwal-Mangla/p/book/9780367512835

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:							
CO1	Ability to apply TQM concepts in a selected enterprise.	Apply						
CO2	Ability to apply TQM principles in a selected enterprise.	Apply						
CO3	Ability to understand Six Sigma and apply Traditional tools, new tools, Benchmarking and FMEA.	Understand						
CO4	Ability to understand Taguchi's Quality Loss Function, Performance Measures and apply QFD, TPM, COQ and BPR.	Understand						
CO5	Ability to apply QMS and EMS in any organization.	Apply						

COURSE A	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	3	0	0	2	0	1	0	2	0	0	2	1	2	1
CO2	1	2	0	0	0	0	0	0	2	0	0	2	0	0	0
CO3	1	2	2	0	1	0	0	1	0	0	0	2	1	0	1
CO4	1	2	0	0	2	3	0	2	0	3	0	2	2	2	1
CO5	1	2	2	0	2	2	1	2	2	3	0	2	2	2	1
Avg	1	2.2	0.8	0	1.4	1	0.4	1	1.2	1.2	0	2	1.2	1.2	0.8
			3/2/1	– ind	icates	streng	th of co	orrelatio	on (3 –	high, 2-	medium	n, 1- low))		

PROFESSIONAL ELECTIVES – VI

22M	22MEPE61 DESIGN OF PRODUCTION TOOLING								
PRER	REQUIS	ITES	CATEGORY	PE	Cre	edit	C		
				L	Т	P	ТН		
			Hours/Week	3	0	0	3		
COUI	RSE OB	JECTIVES:			ı	1			
1.	Describ	be tool design methods and punch and die manufacturing techniques	3						
2.	Select 1	naterial for cutting tools and gages; classify various cutting tools an	d gages and identify	their	nome	nclatı	ıre		
3.	Describ	be the principles of clamping, drill jigs and computer aided jig desig	n						
4.	Design	fixtures for milling, boring, lathe, grinding, welding; identify fixture	res and cutting tools	for NC	mac	hine 1	tools		
5.	. Explain the principles of dies and moulds design								
UNIT	'I	9	0	0	9				
Tool	materials	, design of single point cutting tool, form tool, drill, reamer, broach	& plain milling cut	ter.					
UNIT	' II	METAL CUTTING		9	0	0	9		
		tal cutting – design of tool holders for single point tools – Boring economics of machining.	bars – selection of	tools	for m	achin	ing		
UNIT	'III	DESIGN OF FIXTURES		9	0	0	9		
clamp	ps – desią	c holding devices – principles of location and clamping – clamping & sketching of milling fixtures for simple components – Turning esign of gauges.							
UNIT	IV	DESIGN OF DRILL JIGS		9	0	0	9		
	bushings onents.	– types of jigs: Plate, Leaf, Turn over & Box Jigs – design & ske	tching of drill jigs f	or mac	hining	g sim	ple		
UNIT	UNIT V PRESS TOOLS								
– Pro drawi	gressive ing force	 die cutting operations – centre of pressure – scrap strip lay out f & Compound dies – die design for simple components. Drawing d blank holders & blank holding pressure – design & sketching o & Combination tools. 	ies – blank develop	ment –	estin	natior	ı of		

Total (45L) = 45 Periods

TEXT B	TEXT BOOKS:							
1.	Cyril Donaldson, Lecain and Goold: Tool Design – Tata McGraw Hill publications							
2.	A Bhattacharyya: Metal Cutting – Theory and Practice – Central Book Agency Kolkata							
REFERE	REFERENCES:							
1	ASTME: Fundamentals of Tool Design – Prentice Hall							
2	F W Wilson: Hand Book of Fixture Design - McGraw Hill publications.							
3	Edward G Hoffman, "Jigs and Fixture Design", Thomson – Delmar Learning, Singapore 2004.							
4	Joshi P H, "Jigs and Fixtures", Tata McGraw Hill Publishing Company Limited, New Delhi 2004.							
E-REFI	E-REFERENCES:							
1.	https://lecturenotes.in/subject/150/production-design-and-production-tooling-PDPT							

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:							
CO1	Identify the various cutting tools for different machining processes.	Evaluate						
CO2	Select suitable tools for metal machining	Apply						
CO3	Identify suitable fixtures for various components.	Apply						
CO4	Ability to design jigs for machining components.	Create						
CO5								

COURSE A	ARTI	CULA	TIO	N MA	TRIX	<u> </u>									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	0	0	0	0	0	0	0	0	0	0	1	1	0
CO2	0	1	0	0	0	0	0	0	0	0	0	0	1	1	0
CO3	0	1	2	0	0	0	0	0	0	0	0	0	1	1	0
CO4	1	2	3	0	0	0	0	0	0	0	0	0	1	2	0
CO5	1	1	1	3	0	0	0	0	0	0	0	0	0	0	0
Avg	0.8	1.2	1	0.6	0	0	0	0	0	0	0	0	0.8	1	0
	•	3/	$\frac{1}{2/1 - i}$	ndicat	es stre	ngth o	f corre	lation (3 – hig	h, 2- me	dium, 1-	low)			

22MEPE62	ENGINEERING SYSTEM MODELING AND SIM	ULATION	SEM	1EST	ER	VIII				
PREREQU	ISITES	CATEGORY	PE	Cr	edit	3				
			L	Т	P	TH				
		Hours/Week	3	0	0	3				
COURSE	OBJECTIVES:									
1. Outli	1. Outline the fundamentals of system simulation									
2. Identi	fy the different types of techniques to generate Random numbers									
3. Outli	ne random number and variate generation.									
4. The a	bility to analyze a system and to make use of the information to impr	ove the performance	2							
5. Outli	ne the fundamentals of system simulation									
UNIT I	INTRODUCTION		9	0	0	9				
	al models, dynamic physical models, static mathematical models, deling. System studies, a corporate model: Environment segment, protein study. MATHEMATICAL AND STATISTICAL MODELS									
		and Validation of re				9				
UNIT III	oncepts, Queuing Models, Methods for generating random variables DESIGN OF SIMULATION EXPERIMENTS	and vandation of ra	9	0	0	9				
Problem for	mulation, data collection and reduction, time flow mechanism, k n size, experimental design consideration, output analysis and interpr									
UNIT IV	SIMULATION LANGUAGES		9	0	0	9				
non-stationa Verification	ng: data collection, identifying the distribution with data, parameter y Poisson process, selecting input models without data, multi and validation of simulation models, model building, verification a pration and validation of models.	variate and time s	eries i	nput	mode	els.				
UNIT V	CASE STUDIES		9	0	0	9				
	t of simulation models using simulation language studied for systemtory systems, maintenance and replacement systems and Investmen		system	ıs, Pr	oduct	ion				
		Total	(45L)	= 45]	Perio	ods				

TEXT I	BOOKS:							
1.	Geoffrey Gordon, "System Simulation", 2nd Edition, Prentice Hall, India, 2002.							
2.	Narsingh Deo, "System Simulation with Digital Computer, "Prentice Hall, India, 2001.							
REFER	REFERENCES:							
1	Jerry Banks and John S.Carson, Barry L. Nelson, David M.Nicol, "Discrete Event System Simulation", 3rd Edition, Prentice Hall, India, 2002.							
2	Thomas J. Schriber, Simulation using GPSS, John Wiley, 1991.							
3	Shannon, R.E. Systems simulation, The art and science, Prentice Hall, 1975.							
4	Averill M. Law and W. David Kelton, "Simulation modeling and analysis", McGraw·HiII, Inc, 1991.							
E-REFI	ERENCES:							
1.	https://www.cs.nmt.edu/~jholten/ModelingAndSimulation/lectures.html							
2.	https://lecturenotes.in/subject/383/simulation-and-modelling-sm							
3.	https://backbencher.club/system-modelling-and-simulation/							

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:						
CO1	Modeling any given system with rationality.	Create					
CO2	Predicting the behavior through fine grained analysis.	Create					
CO3	Simulate the life cycle analysis, and drives over issues like model verification and validation.	Evaluate					
CO4	Design simulation models for various case studies like inventory, traffic flow networks, etc.,	Design					
CO5	Practice on simulation tools and impart knowledge on building simulation systems.	Apply					

COURSE A	ARTIO	CULA	TION	N MA	TRIX										
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	1	1	0	0	0	0	0	0	0	0	1	1	0
CO2	1	2	1	0	0	0	0	0	0	0	0	0	1	1	0
CO3	2	1	1	1	0	0	0	0	0	0	0	0	1	1	0
CO4	2	2	1	0	0	0	0	0	0	0	0	0	0	1	0
CO5	1	1	1	0	3	0	0	0	0	0	0	0	1	2	0
Avg	1.6	1.4	1	0.4	0.6	0	0	0	0	0	0	0	0.8	1.2	0
			3/2	1/1 - in	dicate	s stren	gth of	correlat	ion (3	– high, 2	2- mediu	m, 1- low	v)		

	EPE63	ENTREPRENEURSHIP DEVELOPMEN	T	SEM	IEST	ER	VIII
PRER	EQUIS	ITES	CATEGORY	PE	Cre	edit	3
l.Basic	knowle	dge in business strategies and ideas	TT /557 1	L	Т	P	ТН
2.Curre	ent and e	xisting business growth status in our country	Hours/Week	3	0	0	3
COUF	RSE OB	SJECTIVES:					
1.	Unders	tanding the business management and fundamental concepts of Ent	repreneurship				
2.	Learnii	ng about business idea generation and converting the idea into a bus	iness model.				
3.	Unders	standing the role of government and the machinery that renders supp	port in terms of polic	ies, as	sistano	ces et	c.
4.	Discus	sing various information about the process, procedure and rules and	regulations for setti	ng up i	new p	rojec	ts.
5.		ing knowledge and information about the sources of help, i ment in setting up new projects	ncentives and subs	sidies	availa	ble	from
UN	IT I	INTRODUCTION TO ENTREPRENEURSHIP		9	0	0	9
T	IT II	ement.					ion
Defin	nition-cha	SMALL ENTERPRISES AND OWNERSHIP STRUCTU aracteristics-objectives-opportunities and problems of small-scale	industries-Role of				9 in
Defin	nition-cha	SMALL ENTERPRISES AND OWNERSHIP STRUCTU	industries-Role of ion- project apprai	small sal-fin	enterp ancing	rises	9 in
Defin econo enterj	nition-cha	SMALL ENTERPRISES AND OWNERSHIP STRUCTURE aracteristics-objectives-opportunities and problems of small-scale velopment. Project identification and selection-project formulated are considered as a constant of the constant o	industries-Role of ion- project apprai	small sal-fin	enterp ancing	rises	9 in
Define economic enterproperty UNI Institute entreproperty small	nition-chapmic desprise. Ov T III utional depreneurs enterpri	SMALL ENTERPRISES AND OWNERSHIP STRUCTURE aracteristics-objectives-opportunities and problems of small-scale velopment. Project identification and selection-project formulate venership structures-proprietorship-company-cooperative-selection of	industries-Role of ion- project appraif form and ownersh	small sal-fin ip patte 9 itution ises. A	enterpancingern. 0 al finaccour	orises g of o ance ating	9 in an 9 to for
Defin econo enterp UNI Institute entrep small accounterports	nition-chapmic desprise. Ov T III utional depreneurs enterpri	SMALL ENTERPRISES AND OWNERSHIP STRUCTURARIC ACCOUNTING FINANCING AND ACCOUNTING finance to entrepreneurs —commercial banks and other financial taxation benefits to small scale industry—Government policy for itses—need-meaning-objectives. Accounting process-journal-ledge	industries-Role of ion- project appraif form and ownersh	small sal-fin ip patte 9 itution ises. A	enterpancingern. 0 al finaccour	orises g of o ance ating	9 in an good to for
Define econdentery UNI Institute entreps small account UNI Funda admin	nition-chapmic desprise. Over T III utional despreneurs enterprints from T IV amental nistration	small enterprises and ownership structures and problems of small-scale velopment. Project identification and selection-project formulate vnership structures-proprietorship-company-cooperative-selection of FINANCING AND ACCOUNTING finance to entrepreneurs —commercial banks and other financial taxation benefits to small scale industry- Government policy for itses-need-meaning-objectives. Accounting process-journal-ledge incomplete records.	industries-Role of ion- project appraif form and ownersh all institutions. Instead small scale enterpriger-trial balance-fines. Difference between	small sal-fin ip patter grant	enterpancing ern. 0 al finaccouracc	orises g of o ance nting nts a	9 to for and
Define economic enterproperty UNI Institute entreproperty Small account UNI Funda adminimana	nition-chapmic desprise. Over T III utional despreneurs enterprints from T IV amental nistration	SMALL ENTERPRISES AND OWNERSHIP STRUCTOR aracteristics-objectives-opportunities and problems of small-scale velopment. Project identification and selection-project formulate velopments by structures-proprietorship-company-cooperative-selection of FINANCING AND ACCOUNTING finance to entrepreneurs –commercial banks and other financi – taxation benefits to small scale industry- Government policy for rises- need-meaning-objectives. Accounting process-journal-ledge incomplete records. ENTREPRENEURSHIP MANAGEMENT of management process - meaning – characteristics scope-function in. Working capital management, Inventory management, production	industries-Role of ion- project appraif form and ownersh all institutions. Instead small scale enterpriger-trial balance-fines. Difference between	small sal-fin ip patter grant	enterpancing ern. 0 al finaccouracc	orises g of o ance nting nts a	9 to for and

TEXT B	TEXT BOOKS:								
1.	S.S.Khanka "Entrepreneurial Development", S.Chand and Co. Ltd, 1999.								
2.	Essentials of Entrepreneurship and Small Business management (5/ed.): Thomas W. Zimmerer, and Norman M.Scarborough. PHI								
REFER	REFERENCES:								
1	EDII, "Faulty and External Experts – A Hand Book for New Entrepreneurs Publishers. Entrepreneurship Development", Institute of India, Ahmadabad, 1986.								
2	Athore B. S and Saini J. S, "A Handbook of Entrepreneurship", Aapga Publications, 2004.								
3	Rabindra N. Kanungo, "Entrepreneurship and Innovation", Sage Publications, New Delhi, 1998.								
4	Gupta CB and Srinivasan P, "Entrepreneurship Development" Sultan Chand & Sons, New Delhi, 2005								

5	Hisrich. R. D and Peters M. P, "Entrepreneurship", 5th Edition, Tata McGraw Hill, 2002
E-REF	ERENCES:
1.	https://nptel.ac.in/courses

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:						
CO1	Describe the types of entrepreneurships and their development & growth	Understand					
CO2	Identify and select an appropriate project formation for any type of small enterprise	Apply					
CO3	Recognize various financial institutions and adapt the existing government policies for the growth of small-scale enterprises	Remember					
CO4	Illustrate various fields of entrepreneurship management and their functions	Understand					
CO5	Elaborate the steps of development processes for the small-scale industries	Understand					

COURSE A	ARTI	CULA	TIO	N MA	TRIX	\									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	0	0	1	1	0	1	1	0	0	0	0	0	0	0	0
CO2	0	3	0	0	0	0	0	0	1	0	1	1	0	0	0
CO3	0	0	0	0	0	0	0	0	1	0	3	0	0	0	0
CO4	0	0	1	0	0	0	1	0	0	0	0	0	0	0	0
CO5	0	0	0	0	0	1	1	0	0	1	0	0	0	0	0
Avg	0	0.6	0.4	0.2	0	0.4	0.6	0	0.4	0.2	0.8	0.2	0	0	0
	•		3/2	/1 – in	dicate	s stren	gth of	correlat	ion (3	– high, 2	2- mediu	m, 1- lov	v)		

REBE	PE64	INDUSTRIAL SAFETY		SEM	EST	EK V	/111
	QUIS	SITES	CATEGORY	PE	Cro	edit	3
Industri	ial Eng	gineering	**	L	Т	P	TE
.Power	Plant l	Engineering	Hours/Week	3	0	0	3
OURS	SE OB	BJECTIVES:			1		
1. T	To und	derstand the safety norms and inspection procedures to create risk free	working environ	ment			
2. T	То арр	oly adequate machine guarding to eliminate the hazards from flying ch	ips and sparks an	d movi	ng pai	rts	
		ply the safety concepts in welding, gas cutting, storage and hand ses for safe working	ling of gas cylin	iders, r	netal	form	ing
		edict, identify and evaluate, hazardous conditions and practices safe ag of metals	ety rules in in co	old wo	rking	and	hot
		ploy the safety rules in inspection and testing processes and take prev kers' aspects in engineering industry	ventive measures	in healt	th and	l welf	are
UNIT I	Ι	INTRODUCTION		9	0	0	9
planning	ig mac	ty rules-principles-maintenance-Inspections of turning machines, chine and grinding machines, CNC machines, Wood working m					
UNIT I	II ne Guar	PRINCIPLES OF MACHINE GUARDING rding, guarding of hazards, Machine Guarding types and its application.					ing
UNIT I Machine Safety Definition	II ne Guar ty in M	PRINCIPLES OF MACHINE GUARDING rding, guarding of hazards, Machine Guarding types and its application Manual and Mechanical material handling, Safety in use of electrolicy for ZMS - guarding of hazards - point of operation protective de	icity, Zero Mech	lding ananical	nd Ga State g, typ	s cutt (ZM es, fix	(S), xed
UNIT I Machine — Safety Definition guard. UNIT I	II ne Guar ty in M ion, Po	PRINCIPLES OF MACHINE GUARDING rding, guarding of hazards, Machine Guarding types and its application Manual and Mechanical material handling, Safety in use of electrolicy for ZMS - guarding of hazards - point of operation protective de SAFETY IN WELDING AND GAS CUTTING	icity, Zero Mechevices, machine g	Iding an anical guarding	nd Ga State g, typ	s cutt (ZM es, fix	ing (S), xed
UNIT I Machine — Safety Definition guard. UNIT I Safety i protective distribution	II ne Guar ty in M ion, Po III in Gas ive equition an	PRINCIPLES OF MACHINE GUARDING rding, guarding of hazards, Machine Guarding types and its application Manual and Mechanical material handling, Safety in use of electrolicy for ZMS - guarding of hazards - point of operation protective de	nd cutting, commplosive welding-	Iding an anical guarding	nd Ga State g, typ	(ZM es, fix	ing (S), xed
UNIT I Machine Safety Definition guard. UNIT I Safety i protective distribut and han-	II ne Guar ty in M ion, Pc III in Gas ive equation and indling of	PRINCIPLES OF MACHINE GUARDING rding, guarding of hazards, Machine Guarding types and its application Manual and Mechanical material handling, Safety in use of electrolicy for ZMS - guarding of hazards - point of operation protective descriptions of the safety in the safety in the safety in the safety in the safety precautions in brazing, soldering and metalizing - Example of the safety precautions in brazing, soldering and metalizing - Example of the safety precautions in brazing, soldering and metalizing - Example of the safety precautions in brazing, soldering and metalizing - Example of the safety precautions in brazing, soldering and metalizing - Example of the safety precautions in brazing, soldering and metalizing - Example of the safety precautions in brazing, soldering and metalizing - Example of the safety precautions in brazing, soldering and metalizing - Example of the safety precautions in brazing, soldering and metalizing - Example of the safety precautions in brazing, soldering and metalizing - Example of the safety precautions in brazing, soldering and metalizing - Example of the safety precautions in brazing, soldering and metalizing - Example of the safety precautions in brazing, soldering and metalizing - Example of the safety precautions in brazing, soldering and metalizing - Example of the safety precautions in brazing - Example of the safety precautions - Example of the safety precautions - Example of the safety precautions - Example o	nd cutting, commplosive welding-leak detection-pi	Iding an anical guarding	nd Ga State g, typ	(ZM es, fix	ing (S), xed
UNIT I Machine — Safety Definition guard. UNIT I Safety in protective distribute and hand UNIT I Cold we hand or safe guare	III The Guarty in Maion, Political III In Gastive equation and III IV Torking or foot-orards in and in the control III	PRINCIPLES OF MACHINE GUARDING rding, guarding of hazards, Machine Guarding types and its application Manual and Mechanical material handling, Safety in use of electrolicy for ZMS - guarding of hazards - point of operation protective de SAFETY IN WELDING AND GAS CUTTING s welding and oxygen cutting, resistance welding, arc welding and an inpment-safety precautions in brazing, soldering and metalizing - Ex and handling of industrial gases - colour coding - flashback arrestor - of gas cylinders.	nd cutting, communicate which is the services, machine go and cutting, communicate with the services with the services and cutting, communicate with the services with the services and cutting, and cutting the services with the services are services as the services with the services with the services are services as the services with the services are services as the services with the services with the services are services as the services are services as the services with the services are services as the serv	Iding an annical guarding	nd Ga State g, typ	os cutti (ZM es, fix o o o o o o o o o o o o o o o o o o o	ing (S), exed 9 onal on, aage 9
UNIT I Machine Safety Definition guard. UNIT I Safety in protective distribut and hand UNIT I Cold we hand or safe gua cupola,	III The Guarty in Maion, Political III In Gastive equation and III Forking or foot-orards in crucib	PRINCIPLES OF MACHINE GUARDING rding, guarding of hazards, Machine Guarding types and its application Manual and Mechanical material handling, Safety in use of electrolicy for ZMS - guarding of hazards - point of operation protective de SAFETY IN WELDING AND GAS CUTTING s welding and oxygen cutting, resistance welding, arc welding and an impenent-safety precautions in brazing, soldering and metalizing - Ex and handling of industrial gases - colour coding - flashback arrestor - of gas cylinders. SAFETY IN COLD FORMING AND HOT WORKING Of the presses - point of operation safe guarding-auxiliary mechanic operated presses, power press electric controls. Hot working: Safety in hot rolling mills - hot bending of pipes, hazards and control meas	nd cutting, communicate which is the services, machine go and cutting, communicate with the services with the services and cutting, communicate with the services with the services and cutting, and cutting the services with the services are services as the services with the services with the services are services as the services with the services are services as the services with the services with the services are services as the services are services as the services with the services are services as the serv	Iding an annical guarding	nd Ga State g, typ	os cutti (ZM es, fix o o o o o o o o o o o o o o o o o o o	ing (S), xed 9 onal on, age 9
UNIT I Machine — Safety Definition guard. UNIT I Safety in protective distribute and hand UNIT I Cold we hand or safe gua cupola, UNIT I Safety in dynamic radiogra	III The Guarty in Maion, Political Political IIII In Gastive equition and andling of the Political Political IV Vorking or foot-orands in crucib V	PRINCIPLES OF MACHINE GUARDING rding, guarding of hazards, Machine Guarding types and its application Manual and Mechanical material handling, Safety in use of electrolicy for ZMS - guarding of hazards - point of operation protective de SAFETY IN WELDING AND GAS CUTTING s welding and oxygen cutting, resistance welding, arc welding and an inpment-safety precautions in brazing, soldering and metalizing - Ex and handling of industrial gases - colour coding - flashback arrestor - of gas cylinders. SAFETY IN COLD FORMING AND HOT WORKING Of the presses - point of operation safe guarding-auxiliary mechanic operated presses, power press electric controls. Hot working: Safety in hot rolling mills - hot bending of pipes, hazards and control measures.	ad cutting, communication of cutting, communication of cutting, communication of cutting leak detection-pictory of cutting and in forging, hot roures. Safety in grant cutting and in safety in grant cutting and in safety in grant cutting and in forging, hot roures. Safety in grant cutting and in forging, hot roures. Safety in grant cutting and cutting a	dding ar nanical guarding 9 non haz safety ipeline 1 cuttin olling r nas furn 9 sspectic earn tes	ond Ga State g, typ o zards- in ger safety o g mec mill o ace o o o n and sting,	s cutt (ZM es, fix o perso nerati y-stora chanis perati o l testi safety	ing (S), (xed 9 onal on, age 9 on, on, on, on, on, on)

TEXT B	OOKS:						
1.	Andrew Furness, Martin Muckett, "Introduction to Fire Safety Management", Butterworth-Heinemann, 2007.						
2.	C.Rayasfahl, David W.Rieske, "Industrial Safety and Health Management", Pearson, 2009.						
3.	Philip Hagan "Accident Prevention Manual for Business and Industry", National Safety Council, Chicago, 13th edition 2009.						
REFE	REFERENCES:						
1	Peter Warren, "Handbook of Hazardous Chemicals Properties", Butterworth-Heinemann, 1997.						

2	Louis Theodore,Ryan Dupont, "Environmental Health and Hazard Risk Assessment: Principles and Calculations", CRC Press,2012.
3	John V.Grimaldi and Rollin H.Simonds, "Safety Management", Richard D Irwin, 1994.
4	Krishnan N.V. "Safety Management in Industry" Jaico Publishing House, Bombay, 1997.
5	Charles D.Reese, "Industrial Safety and Health for People- Oriented Services". CRC Press, 2009.
E-REF	ERENCES:
1.	NPTEL courses: http://nptel.iitm.ac.in/courses.php - web and video sources on Industrial Safety.

	RSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Understand the safety norms and inspection procedures to create risk free working environment	Understand
CO2	Apply adequate machine guarding to eliminate the hazards from flying chips and sparks and moving parts	Apply
СОЗ	Apply the safety concepts in welding, gas cutting, storage and handling of gas cylinders, metal forming processes for safe working	Apply
CO4	Predict, identify and evaluate, hazardous conditions and practices safety rules in in cold working and hot working of metals	Evaluate
CO5	Employ the safety rules in inspection and testing processes and take preventive measures in health and welfare of workers' aspects in engineering industry	Evaluate

COURSE A	ARTIC	CULA	TIOI	N MA	TRIX	<u> </u>									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	0	0	0	2	3	0	0	1	0	0	0	2	2	1
CO2	3	1	1	0	0	2	2	1	0	0	0	0	2	2	1
CO3	2	0	1	0	2	2	2	0	0	0	0	0	2	2	1
CO4	2	1	1	0	0	2	0	0	0	0	0	0	2	2	1
CO5	2	1	0	0	2	2	2	0	1	0	0	0	2	2	1
Avg	2	0.6	0.6	0	1.2	2.2	1.2	0.2	0.4	0	0	0	2	2	1
	•		3/2	2/1 — iı	ndicate	s stren	gth of	correla	tion (3	– high,	2- mediu	ım, 1- lov	w)	•	

2ME	EPE65	INTRODUCTION TO COMPUTATIONAL FLUID	DYNAMICS	SEM	EST	ER V	III
PRE	REQUI	SITES	CATEGORY	PE	Cre	edit	3
.Fund	lamental	knowledgein partial Differential Equations	TT /XX/ 1	L	P	TH	
.Conc	cepts of la	aws of motion and fluid mechanics	Hours/Week	3	3		
COU	JRSE O	BJECTIVES:					•
1.		standing the major theories, approaches, and methodologies and prynamics.	ogramming techniq	ues in o	comp	utatio	nal
2.	Studyir	ng various fluid flow governing equations from the conservation lav	vs of motion and flu	iid mec	hanics	s.	
3.		ying rigorous and comprehensive treatment of numerical methods neering applications.	in fluid flow and h	eat tran	sfer p	roble	ems
4.		nstrating the computational methods, algorithms and applied be imate solution.	oundary conditions	that w	ill af	fect	the
5.	Buildin	ng up the skills in the actual implementation of CFD methods and co	odes to investigate t	he resul	lts.		
UNI	TI	INTRODUCTION TO COMPUTATIONAL FLUID DY	NAMICS	9	0	0	9
		Philosophy of computational fluid dynamics, CFD as a design and Numerical Methods Programming fundamentals, simple coding tech				CFD	in
UNIT II GOVERNING EQUATIONS OF FLUID FLOW AND HEAT TRANSFER							
UNI	TII	GOVERNING EQUATIONS OF FLUID FLOW AND I TRANSFER	HEAT	9	0	0	9
Gove	erning Ed	_	al derivative, Physnergy equation, Na	sical me	eaning	g of	the
Gove diver for v	erning Ed	TRANSFER quations of Fluid Dynamics: Models of the flow, The substantic velocity, The continuity equation, The momentum equation, The ending of the flow of the f	al derivative, Phys nergy equation, Na	sical me	eaning	g of	the
Gove diver for vi	erning Edgence of iscous float TIII Forms of aring, Tils sification	TRANSFER quations of Fluid Dynamics: Models of the flow, The substantic velocity, The continuity equation, The momentum equation, The educy, Euler equations for in viscid flow, Physical boundary conditions. PARTIAL DIFFERENTIAL EQUATIONS AND ITS N	al derivative, Physnergy equation, Nas. IUMERICAL the equations, shoavior of Partial Di	sical movier Sto	eaning kes ed	g of quation	the ons 9 ock ons:
Gove diver for vi UNI The captu Class Hype	erning Edgence of iscous float TIII Forms of aring, Tils sification	TRANSFER quations of Fluid Dynamics: Models of the flow, The substantic velocity, The continuity equation, The momentum equation, The expose, Euler equations for in viscid flow, Physical boundary conditions PARTIAL DIFFERENTIAL EQUATIONS AND ITS NO BEHAVIOUR If the governing equations suited for CFD, Conservation form of the marching and space marching problems. Mathematical Behavior of quasi-linear partial differential equations, Methods of determining	al derivative, Physnergy equation, Nas. IUMERICAL the equations, shoavior of Partial Ding the classification	sical movier Sto	eaning kes ed	g of quation	the ons 9 ock ons:
Gove diver for visual transfer of the capture Class Hype UNI Basic expanda Appr Pertuand of	erning Edigence of iscous flooring, Times of the control of the co	TRANSFER quations of Fluid Dynamics: Models of the flow, The substantic velocity, The continuity equation, The momentum equation, The exponential equations for in viscid flow, Physical boundary conditions PARTIAL DIFFERENTIAL EQUATIONS AND ITS NOT BEHAVIOUR If the governing equations suited for CFD, Conservation form of the marching and space marching problems. Mathematical Behavior of quasi-linear partial differential equations, Methods of determining the determining and Elliptic equations.	al derivative, Physnergy equation, Nats. IUMERICAL the equations, show avior of Partial Ding the classification OF PDEs fference equations equally spaced grid dacobians. Stability Modified equations,	9 using d points ty Anal Artifici	eaning and all Equal behinders. Gridysis:	o d sho quation o do not set ds W Discressipat	9 9 views Vith eete ion
Gove diver for visual transfer of the capture Class Hype UNI Basic expanda Appr Pertuand of	erning Edragence of iscous flows flower in the iscous flower in the isco	quations of Fluid Dynamics: Models of the flow, The substantic velocity, The continuity equation, The momentum equation, The early Euler equations for in viscid flow, Physical boundary conditions PARTIAL DIFFERENTIAL EQUATIONS AND ITS NOTES BEHAVIOUR If the governing equations suited for CFD, Conservation form of the marching and space marching problems. Mathematical Behavior of quasi-linear partial differential equations, Methods of determinical and Elliptic equations DISCRETIZATION AND NUMERICAL METHODS (Conservation) in the control of the equations, Metrics and Elliptic equations of the equations, Metrics and Estability analysis, von Neumann Stability analysis, Error analysis, Notes, Grid Generation: Algebraic Grid Generation, Elliptic Grid Generation, Elliptic Grid Generation.	al derivative, Physnergy equation, Nata St. IUMERICAL the equations, sho avior of Partial Ding the classification OF PDEs fference equations equally spaced grid d Jacobians. Stability Modified equations, ration, Hyperbolic of	9 using d points ty Anal Artifici	eaning and all Equal behinders. Gridysis:	o d sho quation o do not set ds W Discressipat	9 9 vies Vith eete ion
Gove diver for visual to the capture Class Hype UNI Basic expandant of Parab	erning Edrgence of iscous flooring TIII Forms of aring, Tin sification erbolic, Particular Tipotation Sidispersion bolic Grid TIV bolic Particular Lands — L	quations of Fluid Dynamics: Models of the flow, The substantic velocity, The continuity equation, The momentum equation, The educy, Euler equations for in viscid flow, Physical boundary conditions PARTIAL DIFFERENTIAL EQUATIONS AND ITS NOTES BEHAVIOUR If the governing equations suited for CFD, Conservation form of the marching and space marching problems. Mathematical Behavior of quasi-linear partial differential equations, Methods of determining arabolic and Elliptic equations DISCRETIZATION AND NUMERICAL METHODS OF Section of Discretization: Introduction to finite differences, Finite differences of Discretization: Introduction to finite differences, Finite differences of Discretization: General transformation of the equations, Metrics and Stability analysis, von Neumann Stability analysis, Error analysis, No.; Grid Generation: Algebraic Grid Generation, Elliptic Grid Generation. SOLUTION METHODS AND APPLICATIONS OF NO.	al derivative, Physnergy equation, Nats. IUMERICAL the equations, showavior of Partial Ding the classification OF PDEs fference equations equally spaced gried Jacobians. Stability Modified equations, ration, Hyperbolic of the UMERICS TO I methods – FTCS, and Unstructured Grief equations.	9 using d points ty Anal Artifici Grid Ge	eaning kes ed o ng an al Eq al beh Taylors. Gri ysis: ial distenerat d dson. vantag	of quation of the property of	the ons 9 ock ons: r of 9 ries r/ith ete ete ion and

TEXT	TEXT BOOKS				
1.	Anderson, J.D. (Jr), "Computational Fluid Dynamics", McGraw-Hill Book Company, 1st Edition, 1995.				
2.	Hoffman, K.A., and Chiang, S.T., "Computational Fluid Dynamics", Vol. I, II and III, Engineering Education System, Kansas, USA, 2000.				
REFE	RENCES:				

1	Anderson, D.A., Tannehill, J.C., and Pletcher, R.H., "Computational Fluid Mechanics and Heat Transfer", McGraw Hill Book Company, 2002.
2	Chung, T.J., "Computational Fluid Dynamics", Cambridge University Press, 2003
3	Muralidhar K and Sundararajan., "Computational Fluid Flow & Heat Transfer", 2009.
E-REFE	CRENCES:
1.	https://nptel.ac.in/courses/112105045

	RSE OUTCOMES: ompletion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Summarize the basics of computational fluid dynamics and its applications in various industries as a tool for fluid analysis	Remember
CO2	Select an appropriate finite difference approach for numerical formulations based on fluid mechanics and/or heat transfer concepts to get the approximate solutions.	Apply
СОЗ	Develop the governing equations for computational fluid dynamics CFD analysis by setting appropriate boundary conditions.	Create
CO4	Identify different CFD techniques available for relevant partial differential equations to get analytical solutions for fluid flow.	Understand
CO5	Analyze the numerical solution of fluid flow problems using discretization methods addressing accuracy, stability and convergence aspects to minimize the errors.	Analyze

COURSE ARTICULATION MATRIX PO PO PO PO PO PO PO PO **PO8** PO10 PO11 COs/POs PSO1 PSO₂ PSO3 **PO12 CO1** CO₂ CO₃ **CO4 CO5** 1.2 0.8 0.2 0.6 0.8 0.8 0.8 0.4 0.2 0.2 0.4 Avg 3/2/1 – indicates strength of correlation (3 – high, 2- medium, 1- low)

22MEPE 6	6	MARINE ENGINEERING		SEM	EST	ER V	VIII
PREREC	UI	SITES	CATEGORY	PE	edit	3	
l. Internal C	om	bustion Engines	** /**/ 1	L	TH		
2.Fluid Mec	han	ics and Machinery	Hours/Week	3	3		
COURSE	OB	JECTIVES:					
1. To	und	erstand the basic principles of Marine Engineering					
2. To	und	erstand the naval architects and the fields related to the maritime in	idustry				
3. To	ana	lyze the vibrations in various equipment used in marine engineering	9				
4. To	und	erstand various electrical systems and environmental control and sa	afety in marine engi	neering			
5. To	und	erstand the nuclear applications in marine engineering					
UNIT I		INTRODUCTION		9	0	0	9
UNIT II Characteri	stic	ENGINES AND PROPULSION s of internal combustion engines-marine uses for such engines.	Marine steam gen	9 erators			9 and
UNIT II		ers. Main propulsion systems-steam engines, steam turbines, gas tu VIBRATIONS ANALYSIS	rbines. Electric proj	9	0	0	9
exchanger	s, d	fting and shafting system vibration analysis-Pumps, blowers, distilling plants. Hull machinery design considerations and machinestatic power transmission equipment and systems.					
UNIT IV	7	POWER DISTRIBUTION		9	0	0	9
Electronic	s 1	ating plants- switchboards and panels-lighting and power distributed avigation and radio communication-automation systems- system					
UNIT V		NUCLEAR APPLICATION		9	0	0	9
		of pressurized-water nuclear steam supply systems for use - Nuclear fuels, reactor coolants, reactor control, shielding, safety,				r des	ign
							riod

TEXT B	OOKS:
1.	Grover T K, "Marine Engineering", Anmol Publications Pvt Ltd, 2008.
2.	Harrington and Roy, L, "Marine Engineering", The Society of Naval Architects and Marine Engineers, 1991.
3.	D.A.Taylor, "Introduction to Marine Engineering", Butterworth Heinmann, 1996.
REFEI	RENCES:
1	Cameron, I.R., "Nuclear Fission Reactors", Plenum Press, 1998.
2	Henke and Russell, W., "Introduction to Fluid Power Circuits and Systems", Addison-Wesley, 1970.
3	John W.Gaythwaite, "Design of Marine Facilities: Engineering for Port and Harbour Structures", American Soceity of Civil Engineers, 2016.
4	Doug Woodyard, "Pounder's Marine Diesel Engines and Gas Turbines", Elsevier Ltd,2009.
5	Kuwahara, Takuya, "New Technologies for Emission Control in Marine Diesel Engines", Elsevier Science & Technology, 2019.
E-REFE	RENCES:
1.	NPTEL courses: http://nptel.iitm.ac.in/courses.php - web and video sources on Marine Engineering.

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:							
CO1	Understand the basic principles of marine engineering	Understand						
CO2	Understand the naval architects and the fields related to the maritime industry	Understand						
CO3	Analyze the vibrations in various equipment used in marine engineering	Analyze						
CO4	Understand various electrical systems and environmental control and safety in marine engineering	Understand						
CO5	Understand the nuclear applications in marine engineering	Understand						

COURSE A	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1	1	1	0	0	0	0	0	0	0	0	2	2	1
CO2	2	1	1	1	1	0	0	0	0	0	0	0	2	2	1
CO3	2	2	3	1	1	0	0	0	0	0	0	0	2	2	1
CO4	2	0	3	0	0	3	2	0	0	2	0	1	2	2	1
CO5	1	1	2	1	0	3	2	0	0	1	0	0	2	2	1
Avg	2.0	1.0	2.0	0.8	0.4	1.2	0.8	0.0	0.0	0.6	0.0	0.2	2.0	2.0	1.0
			3/2	/1 – in	dicate	s stren	gth of	correlat	ion (3	– high, 2	2- mediu	m, 1- lov	v)		

	EPE67	ROBOTICS	SEN	1EST	ER	VII	
PREF	REQUIS	CATEGORY CATEGORY	PE	Credit		3	
			L	Т	P	TF	
		Hours/Week	3	0	0	3	
COU	RSE OF	BJECTIVES:	I	I	1		
1.	To exp	olore concepts of Robot technologies that is playing vital role in manufacture					
2.	Descri	be various Robot technology applications.					
3.	Develo	op an understanding of Robot Kinematics and dynamics.					
4.	Explai	n and summarize Robot end effectors and Sensors.					
5.	Explor	e conceptual understanding of robot programming.					
UNI	TI	FUNDAMENTALS OF ROBOT	9	0	0	9	
Drive	ac _ hwdr	aulic pneumatic mechanical electrical - servo motors - stepper motors - salient featu	9 res apr	0 dication	0 on – (_	
effec	tors – ty	aulic, pneumatic, mechanical, electrical - servo motors - stepper motors - salient featu pes: tools - grippers - mechanical grippers - pneumatic and hydraulic grippers, magnetiple grippers.	res, app	olicati	on –	end	
effec gripp	tors – ty	pes: tools - grippers - mechanical grippers - pneumatic and hydraulic grippers, magne	res, app	olicati	on –		
UNI Requeffec (reso	tors – typers, multi- T III tirements t, capacital typers, op	pes: tools - grippers - mechanical grippers - pneumatic and hydraulic grippers, magnetiple grippers.	res, appetic grip 9 mity (inge) – s	olication of the peed,	on – o vacu o ive, H	end um 9 Hall ion	
effec gripp UNI Requ effec (reso visio	tors – typers, multi- T III tirements t, capacital typers, op	pes: tools - grippers - mechanical grippers - pneumatic and hydraulic grippers, magnetiple grippers. SENSORS AND MACHINE VISION of sensors – principles, types and applications of following types of sensors proxitive, ultrasonic and optical) – range (Triangulation, structured light approach, laser rartical encoders, pneumatic) – force – torque – touch sensors (binary, analog sensor) - interest to the sensors of the sensor	res, appetic grip 9 mity (inge) – s	olication of the peed,	on – o vacu o ive, H	end um 9 Hall ion ine	
effect gripp UNI Requestion (reso visio UNI Forward VAL	tors – ty pers, multi- T III direments t, capacitalivers, open -function T IV vard kine togeneous to program	pes: tools - grippers - mechanical grippers - pneumatic and hydraulic grippers, magnetiple grippers. SENSORS AND MACHINE VISION of sensors - principles, types and applications of following types of sensors proxitive, ultrasonic and optical) - range (Triangulation, structured light approach, laser rartical encoders, pneumatic) - force - torque - touch sensors (binary, analog sensor) - intons - image processing and analysis.	res, appetic grip 9 mity (in age) – stroducti 9 (in 2 drammin	on duction peed, on to	on – o vacu output vacu output out	end um 9 Hall ion ine 9 9 9	
effect gripp UNI Requestion (reso visio UNI Forward NAL	tors – typers, multiple tors, multiple tors, multiple to the transfer of the t	pes: tools - grippers - mechanical grippers - pneumatic and hydraulic grippers, magnetiple grippers. SENSORS AND MACHINE VISION of sensors - principles, types and applications of following types of sensors proxitive, ultrasonic and optical) - range (Triangulation, structured light approach, laser rartical encoders, pneumatic) - force - torque - touch sensors (binary, analog sensor) - intons - image processing and analysis. ROBOT KINEMATICS AND ROBOT PROGRAMMING ematics and reverse kinematics of manipulators - two, three degrees of freedom of transformation matrix - simple problems - lead through programming, robot programming -motion commands - sensor commands - end effecter commands - simple problems	res, appetic grip 9 mity (in age) – stroducti 9 (in 2 drammin	on duction peed, on to	on – o vacu output vacu output out	9 Hall ion iine	

Total (45L) = 45 Periods

TEXT B	OOKS:									
1.	M.P.Groover, "Industrial Robotics – Technology, Programming and Applications", McGraw-Hill, 2001									
2.	Fu.K.S. Gonzalz.R.C., and Lee C.S.G., "Robotics Control, Sensing, Vision and Intelligence", Mc Graw Hill Book Co.,1987									
REFERE	REFERENCES:									
1	Richard D.Klafter, Thomas A.Chmielewski and Micheal Negin, "Robotic engineering –An Integrated Approach", Prentice Hall Inc, Englewoods Cliffs, NJ, USA, 2005.									
2	Janakiraman.P.A. "Robotics and Image Processing", Tata McGraw-Hill, 1995.									
3	Yoram Koren, "Robotics for Engineers", McGraw-Hill Book Co., 1992.									
4	A.K.Gupta and S.K.Arora, "Industrial Automation and Robotics", Laxmi Publications Pvt ltd, 2007.									

E-REFERENCES:

1. NPTEL Videos/Tutorials

	RSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Describe the basic concepts, parts of robots and types of robots	Understand
CO2	Know the potential applications of robots in industries as part of automation tool	Understand
СОЗ	Familiar with the various drive systems for robot, sensors and their applications in robots, programming of robots.	Remember
CO4	Discuss about the various applications of robots, justification, implementation and safety of robot	Analyze
CO5	Select an appropriate robot for a particular application with economically.	Apply

COURSE	ARTICUL	ATION	MATRIX
COUNSI	ANTICUL		MAINA

COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	2	1	2	0	1	0	0	0	2	0	2	2	1
CO2	2	1	1	1	0	1	2	1	0	0	1	0	2	2	1
CO3	1	1	1	1	0	1	1	1	0	0	1	0	2	2	1
CO4	1	1	1	2	2	2	1	0	0	0	2	0	1	1	1
CO5	1	1	1	1	2	1	1	0	0	0	1	0	2	2	1
Avg	1.4	1	1.2	1.2	1.2	1	1.2	0.4	0	0	1.4	0	1.8	1.8	1

3/2/1 – indicates strength of correlation (3 – high, 2- medium, 1- low)

OPEN ELECTIVES COURSES

		DESIGN OF MACHINE ELEMENTS AND MACHINING									
		CATEGORY	OE	Cre	edit	3					
		Hours/Week	L	T	P	T H					
			3	0	0	3					
COURSE OB	BJECTIVES										
1 To familia	rize the various steps involved in the design process										
2 To understa	and the basic concepts of machining techniques										
3 To know th	ne factors influencing the processes and their applications										
4 Applying t	he principles of milling and gear cutting machines.										
5 To gain the	knowledge of cutting tool materials and surface finishing p	rocess.									
UNITI	STRESSES IN MACHINE ELEMENTS		9	0	0	9					
	ole machine members- axial, bending, torsional, bearing st ses, Theories of failure, factor of safety, stress concentration		s; comb	ined	stress	ses,					
UNITII	DESIGN OF SHAFTS AND WELDED JOINTS		9	0	0	9					
	ft members subjected to simple and combined stresses - Websts subjected to various load -Design of Riveted joints	lded joints- Types of we	lding sy	mbols	s, desi	ign					
UNITIII	DESIGN OF MACHINE ELEMENTS		9	0	0	9					
	gn of helical springs- stresses and deflection - design pro lling contact bearings, hydro- dynamic and hydro static bear										
UNITIV	METAL CUTTING		9	0	0	9					
	tal cutting: Introduction, mechanics of metal cutting, orthogon, heat generation, cutting fluids, cutting tool life, recent ded machining)										
UNITV	MACHINE TOOLS AND SURFACE FINISHING	PROCESSES	9	0	0	9					
planning, mill	chine tools: Cutting tool materials, cutting tool nomenclature ing, drilling and boring machines, working principle, operate roduction to Grinding honing, lapping processes and machin	tions, work holding devi	ces. Sur	face f							

REI	FERENCE BOOKS:
1	Rao P N, "Manufacturing Technology" Tata McGraw-Hill Publishing Company Ltd, New Delhi, 2006
2	HMT, "Production Technology" Tata McGraw-Hill Co., New Delhi, 1998
3	Milton C Shaw, "Metal Cutting Principles", Clarendon Press, Oxford, 1999.
4	James Brown, "Advanced Machining Technology Handbook", McGraw- Hill Book Company, New York, 1988.
5	Robert L Mott, "Machine Elements in Mechanical Design", Macmillan Publishing Co., London. UK, 1992.
6	Shighley and Mische, "Mechanical Engineering Design" McGraw Hill, 1992.
7	Rao. P.N "Manufacturing Technology," Metal Cutting and Machine Tools, Tata McGraw- Hill, New Delhi, 2003.
E-RE	FERENCES:

https://nptel.ac.in/courses/112105124
 Design of Machine Elements - V. B. Bhandari - Google Books
 A Textbook of Machine Design by R.S.Khurmi and J.K.Gupta [tortuka]_1490186411865.pdf | DocDroid

COU	RSE OUTCOMES:	Bloom Taxonomy
Upon	Mapped	
CO1	Analyze the stresses induced in a machine element.	Analyze
CO2	Familiarize the design concept of joints under various loading.	Remember
CO3	Familiarize the design of various types of bearings and Spring.	Remember
CO4	Identify the process parameters associated with various machining processes.	Apply
CO5	Familiarize the cutting tools materials and surface finishing processes.	Remember

COURSE A	COURSE ARTICULATION MATRIX													
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PSO1	PSO2	PSO3
CO1	2	2	1	2	0	1	1	0	0	0	1	0	3	2
CO2	2	2	1	2	0	1	1	0	0	0	1	0	3	2
CO3	2	2	1	2	0	1	1	0	0	0	1	0	3	2
CO4	2	2	1	2	0	1	1	0	0	0	1	0	3	2
CO5	2	2	1	2	0	1	1	0	0	0	1	0	3	2
Avg	2	2	1	2	0	1	1	0	0	0	1	0	3	2
			3/2/1 -	- indic	ates str	ength o	of corre	elation (3 - hig	h, 2- med	dium, 1-	ow)	•	

22MEOE02	EOE02 INDUSTRIAL ENGINEERING						
		CATEGORY	OE	Cr	edit		3
			L	T	P	T	Η
		Hours/Week	3	0	0		3
COURSE O	BJECTIVES			l l		-1	
1 Assume	Technical and Managerial roles in the industries.						
2 Apply I	Engineering Principles to the working environment.						
3 Use qua	lity tools to foresee and solve issues in the industrial situ	ations.					
4 Work co	ollaboratively						
5 To know	v the importance of EBQ						
UNITI	FORECASTING			9	0	0	9
	cient of Correlation- Problem solving. FACILITIES PLANNING AND WORK STUDY	Y		9	0	0	9
Objectives of Economy - 7 Predetermined	Layout Techniques - Design of Group Technology Lay Work Study -Method Study Procedure, Recording Techniques of Work measurement - Time Study - Motion Time System (PMTS) - Work Sampling Techni LEAN MANUFACTURING	chniques - Motion St Synthesis Method	udy - Pi	rincipl rtical	les of Estir	Mo natin	tio g
Objectives of Economy - Predetermined UNITHI Elements of Synchronous Concurrent Er process reeng Resources Pla	Work Study -Method Study Procedure, Recording Techniques of Work measurement - Time Study - Motion Time System (PMTS) - Work Sampling Techniques of Work measurement - Time Study - Motion Time System (PMTS) - Work Sampling Techniques In Time (JIT) - Pull and Push System, Kanban Manufacturing – Implementation of Six Sigma - Single Ingineering - Cellular Manufacturing – Enablersof Agile Ingineering (BPR) - Basics of Supply Chain Management (ERP) -Role of KAIZEN, Quality Circles and P	Synthesis Method iques. System- Optimized e MinuteExchange of Manufacturing – Rapint, Supply chain and	Production of the Production o	9 ionTec MED) acturietsu"	es of Estir	Monatin O ogy conce Busin terpr	an pt nessise
Objectives of Economy - Predetermined UNITHI Elements of Synchronous Concurrent Erprocess reeng Resources Pla wastes in Lean	Work Study -Method Study Procedure, Recording Tec Fechniques of Work measurement - Time Study - Motion Time System (PMTS) - Work Sampling Technic LEAN MANUFACTURING Fust In Time (JIT) - Pull and Push System, Kanban Manufacturing - Implementation of Six Sigma - Single Igineering (BPR) - Basics of Supply Chain Manageme	Synthesis Method iques. System- Optimized e MinuteExchange of Manufacturing – Rapint, Supply chain and	Production of the Production o	9 ionTec MED) acturietsu"	es of Estir	Monatin O ogy conce Busin terpr	g and pt ness ise
Objectives of Economy - Predetermined UNITHI Elements of Synchronous Concurrent Erprocess reeng Resources Pla wastes inLean UNITIV Objectives of Strategies for Materials Req	Work Study -Method Study Procedure, Recording Techniques of Work measurement - Time Study - Motion Time System (PMTS) - Work Sampling Techniques of Work Techniques (PMTS) - Work Sampling Techniques (PMTS) - Work Sampling Techniques (PMTS) - Pull and Push System, Kanban Manufacturing – Implementation of Six Sigma - Single Igineering (PMT) - Basics of Supply Chain Managemenning (PMT) - Role of KAIZEN, Quality Circles and P Manufacturing.	Synthesis Method iques. System- Optimized e MinuteExchange of Manufacturing – Rapint, Supply chain and OKA YOKE in Mod	Production of Control	9 sonTeoMED) facturietsu" ufactu 9 Capaci Oevelo	ety Ploping	Monatin O ogy once Busin terpr - Se O annii MP	an pt ness isee ve
Objectives of Economy - Predetermined UNITIII Elements of Synchronous Concurrent Erprocess reeng Resources Plawastes in Lean UNITIV Objectives of Strategies for Materials Req MRP - Manuf	Work Study -Method Study Procedure, Recording Tec Techniques of Work measurement - Time Study - Motion Time System (PMTS) - Work Sampling Techniques of Work measurement - Time Study - Motion Time System (PMTS) - Work Sampling Techniques of LEAN MANUFACTURING [Sust In Time (JIT) - Pull and Push System, Kanban Manufacturing - Implementation of Six Sigma - Single Ingineering - Cellular Manufacturing - Enablersof Agile In Interior (BPR) - Basics of Supply Chain Management (ERP) - Role of KAIZEN, Quality Circles and Pomanufacturing. [AGGREGATE PRODUCTION PLANNING] [Aggregate Planning - Capacity Requirement Planning Aggregate Capacity Planning - Master Production uirements Planning (MRP-I), Issues in MRP, Designing	Synthesis Method iques. System- Optimized e MinuteExchange of Manufacturing – Rapint, Supply chain and OKA YOKE in Mod	Production of Control	9 sonTeoMED) facturietsu" ufactu 9 Capaci Oevelo	ety Ploping	Monatin O ogy once Busin terpr - Se O annii MP	an pt ness isee ve
Objectives of Economy - Predetermined UNITHI Elements of Synchronous Concurrent Enprocess reeng Resources Pla wastes inLean UNITIV Objectives of Strategies for Materials Req MRP - Manufill UNITV Operations Plexpediting - I Dynamic Seques Scheduling in	Work Study -Method Study Procedure, Recording Tec Techniques of Work measurement - Time Study - Motion Time System (PMTS) - Work Sampling Technic LEAN MANUFACTURING Tust In Time (JIT) - Pull and Push System, Kanban Manufacturing - Implementation of Six Sigma - Single Igineering- Cellular Manufacturing - Enablersof Agile Is ineering (BPR) - Basics of Supply Chain Managemenning (ERP) -Role of KAIZEN, Quality Circles and P Manufacturing. AGGREGATE PRODUCTION PLANNING Aggregate Planning - Capacity Requirement Planning Aggregate Capacity Planning - Master Production uirements Planning (MRP-I), Issues in MRP, Designing acturing Resources Planning (MRP-II).	System- Optimized e MinuteExchange of Manufacturing – Rapint, Supply chain and OKA YOKE in Moderate of Managing the Managing the Machine LoadingChantity (EBQ) or Econation of units for a sign.	Production of Pr	generation of the state of the	es of Estir 0 chnol 55 c ng - En nring 0 ty Pl pping Evalu 0 g,Disp Sequength alloce	Monatin O ogy once Busin terpr - Se O annin MP nation O oatch encin (ERI cation	an pt nessiseeve
Objectives of Economy - Predetermined UNITII Elements of Synchronous Concurrent Erprocess reeng Resources Pla wastes inLean UNITIV Objectives of Strategies for Materials Req MRP - Manufill UNITV Operations Plexpediting - I Dynamic Sequences Scheduling in	Work Study -Method Study Procedure, Recording Techniques of Work measurement - Time Study - Motion Time System (PMTS) - Work Sampling Techniques of Work measurement - Time Study - Motion Time System (PMTS) - Work Sampling Techniques - Work Sampling Techniques - Lean Manufacturing - Enablers - Single Intering (IT) - Pull and Push System, Kanban Manufacturing - Implementation of Six Sigma - Single Intering (BPR) - Basics of Supply Chain Managemenning (ERP) - Role of KAIZEN, Quality Circles and P Manufacturing. AGGREGATE PRODUCTION PLANNING Aggregate Planning - Capacity Requirement Planning Aggregate Capacity Planning - Master Production unirements Planning (MRP-I), Issues in MRP, Designing acturing Resources Planning (MRP-II). SCHEDULING OF OPERATIONS anning and Scheduling - Scheduling Techniques - Finite Loading and Infinite Loading - Load Charts and lencing Rules - Batch Scheduling - Economic BatchQuare Repetitive, Batch and Job ShopManufacturing - Alloce	System- Optimized e MinuteExchange of Manufacturing – Rapint, Supply chain and OKA YOKE in Moderate of Managing the Managing the Machine LoadingChantity (EBQ) or Econation of units for a sign.	Production of the Production o	generation of the state of the	es of Estir 0 chnol 55 c ng - En nring 0 ty Pl pping Evalu 0 g,Disp Sequength alloce	Monatin O ogy once Busin terpr - Se O annin MP nation O oatch encin (ERI cation	an pt nessiseeve
Objectives of Economy - Predetermined UNITII Elements of Synchronous Concurrent Erprocess reeng Resources Pla wastes inLean UNITIV Objectives of Strategies for Materials Req MRP - Manufill UNITV Operations Plexpediting - I Dynamic Sequences Scheduling in	Work Study -Method Study Procedure, Recording Techniques of Work measurement - Time Study - Motion Time System (PMTS) - Work Sampling Techniques of Work measurement - Time Study - Motion Time System (PMTS) - Work Sampling Techniques In Time (JIT) - Pull and Push System, Kanban Manufacturing – Implementation of Six Sigma - Single Inference (BPR) - Basics of Supply Chain Management (BPR) - Role of KAIZEN, Quality Circles and P. Manufacturing. AGGREGATE PRODUCTION PLANNING Aggregate Planning - Capacity Requirement Planning Aggregate Capacity Planning - Master Production uirements Planning (MRP-I), Issues in MRP, Designing acturing Resources Planning (MRP-II). SCHEDULING OF OPERATIONS anning and Scheduling - Scheduling Techniques - Finite Loading and Infinite Loading - Load Charts and Bencing Rules - Batch Scheduling - Economic BatchQuartees - Resource balancing - Flexible manufacturing systems.	System- Optimized e MinuteExchange of Manufacturing – Rapint, Supply chain and OKA YOKE in Moderate of Managing the Managing the Machine LoadingChantity (EBQ) or Econation of units for a sign.	Production of Pr	generation of the state of the	es of Estir 0 chnol 55 c ng - En nring 0 ty Pl pping Evalu 0 g,Disp Sequength alloce	Monatin O ogy once Busin terpr - Se O annin MP nation O oatch encin (ERI cation	an pt ness is every sing ng n
Objectives of Economy - Predetermined UNITHI Elements of Synchronous Concurrent Erprocess reeng Resources Plawastes inLean UNITIV Objectives of Strategies for Materials Req MRP - Manufi UNITV Operations Plexpediting - I Dynamic Seques Scheduling in multiple resources	Work Study -Method Study Procedure,Recording Techniques of Work measurement - Time Study - Motion Time System (PMTS) - Work Sampling Techniques of Work measurement - Time Study - Motion Time System (PMTS) - Work Sampling Techniques In Time (JIT) - Pull and Push System, Kanban Manufacturing - Implementation of Six Sigma - Single Inference (BPR) - Basics of Supply Chain Managementing (BPR) - Basics of Supply Chain Managementing (ERP) -Role of KAIZEN, Quality Circles and PManufacturing. **AGGREGATE PRODUCTION PLANNING** Aggregate Planning - Capacity Requirement Planning Aggregate Capacity Planning - Master Production uirements Planning (MRP-I), Issues in MRP,Designing acturing Resources Planning(MRP-II). **SCHEDULING OF OPERATIONS** anning and Scheduling - Scheduling Techniques - Pinite Loading and Infinite Loading - Load Charts and tencing Rules - Batch Scheduling - Economic BatchQuarters - Resource balancing - Flexible manufacturing systems - Resource balancing - Flexible manufacturing systems - Resource balancing - Flexible manufacturing systems - Resource - Resource balancing - Flexible manufacturing systems - Resource - Resource balancing - Flexible manufacturing systems - Resource - R	System- Optimized e MinuteExchange of Manufacturing – Rapint, Supply chain and OKA YOKE in Moderate of Managing - Procedure and Managing the Machine LoadingChantity (EBQ) or Econtation of units for a signme.	Production of Pr	garacio de la contracta de la	es of Estir 0 chnol 55 c c ng - En uring 0 ty Pl pping Evalu 0 g,Disp Sequength allocated	Monatin O ogy once Busin terpr - Se O annin MP nation O oatch encin (ERI cation	ann pt innessisses S S S S S S S S S S S S S S S S S S

3	Dilworth B.James, "Operations Management Design, Planning and Control forManufacturing and Services", Mcgraw Hill Inc., New York, 1992
4	Vollman T.E, "Manufacturing Planning and Control Systems", Galgotia Publications, 2002.
E-REI	FERENCES:
1.	https://www.newtondesk.com/industrial-engineering-study-notes-hand-written/
2.	https://en.wikipedia.org/wiki/Lean_manufacturing
3.	https://www.planettogether.com/blog/types-of-scheduling-in-production-planning-and-control

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:					
CO1	Apply the knowledge of Engineering and Sciences to improve the productivity of Industries.	Apply				
CO2	Design a system to meet the desired needs within realistic constraints.	Create				
CO3	Function in multidisciplinary teams.	Apply				
CO4	Use the techniques, skills, and modern engineering tools in manufacturing practice.	Understand				
CO5	Perform as an effective Industrial Engineer integrating high and low levels of management	Create				

COURSE A	COURSE ARTICULATION MATRIX													
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PSO1	PSO2	PSO3
CO1	3	0	0	2	2	0	0	0	0	0	0	0	0	3
CO2	0	0	3	0	0	0	0	0	0	0	0	0	0	2
CO3	0	0	0	0	0	3	2	0	3	2	3	2	3	0
CO4	3	3	0	2	3	3	0	0	0	0	0	2	0	3
CO5	0	0	0	0	0	3	2	3	0	0	0	0	3	0
Avg	1.2	0.6	0.6	0.8	1	1.8	0.8	0.6	0.6	0.4	0.6	0.8	1.2	1.6
	3/2/1 – indicates strength of correlation (3 – high, 2- medium, 1- low)													

22M	2MEOE03 INDUSTRIAL ROBOTICS SE							VI/VII		
			CATEGORY	OE	Cre	dit		3		
			TT /XX/ 1	L	T	P	T	Ή		
			Hours/Week	3	0	0		3		
COU	RSE OB	SJECTIVES								
1	To expl	ore concepts of Robot technologies that is playing vital role	e in manufacture.							
2	Describ	e various Robot technology applications.								
3	Develop	an understanding of Robot Kinematics and dynamics.								
4	Explain	and summarize Robot End effectors and Sensors.								
5	Explore	conceptual understanding of Robot programming.								
UNI	TI	INTRODUCTION			9	0	0	9		
joint		on - robot anatomy - co-ordinate systems - work envelope - types of joints - speed of motion - pay load - robot page.								
UNI	T II	ROBOT DRIVE SYSTEMS AND END EFFECT	ORS		9	0	0	9		
- end	effectors	alic, pneumatic, mechanical and electrical - servo motors - types: tools - grippers - mechanical grippers - pneumatics, multiple grippers.								
UNIT III SENSORS AND MACHINE VISION							0	9		
effect positi	Requirements of sensors – principles, types and applications of following types of sensors proximity (inductive, Hall effect, capacitive, ultrasonic and optical) – range (Triangulation, structured light approach, laser range) – speed, position (resolvers, optical encoders, pneumatic) – force – torque – touch sensors (binary, analog sensor) – introduction to machine vision -functions - image processing and analysis.									
UNIT IV ROBOT KINEMATICS AND ROBOT PROGRAMMING 9 0 0								9		
Forw	Forward kinematics and reverse kinematics of manipulators - two three degrees of freedom (in 2 dimensional) -									

Forward kinematics and reverse kinematics of manipulators - two, three degrees of freedom (in 2 dimensional) – homogeneous transformation matrix - simple problems - lead through programming, robot programming languages -

VAL programming –motion commands - sensor commands - end effecter commands - simple programs for loading, unloading and palletizing operations.

UNIT V APPLICATIONS, IMPLEMENTATION AND ROBOT ECONOMICS 9 0 0 9

Robot cell design – types - Application of robots in processing - assembly - inspection - material handling - loading - unloading - automobile - implementation of robots in industries - safety considerations for robot operations – economic analysis of robots - pay back method and rate of return method.

Total (45L)= 45Periods

REFE	REFERENCE BOOKS:							
1	Mikell. P. Groover, 'Industrial Robotics Technology', Programming and Applications, McGraw Hill Co, 1995.							
2	Fu.K.S. Gonzalz.R.C., and Lee C.S.G., "Robotics Control, Sensing, Vision and Intelligence", McGraw Hill Book Co.,1987.							
3	Richard D.Klafter, Thomas A.Chmielewski and MichealNegin, "Robotic engineering –An Integrated Approach", Prentice Hall Inc, Englewoods Cliffs, NJ, USA, 2005.							
4	Janakiraman.P.A. "Robotics and Image Processing", Tata McGraw-Hill, 1995.							
5	YoramKoren, "Robotics for Engineers", McGraw-Hill Book Co., 1992.							
6	A.K.Gupta and S.K.Arora, "Industrial Automation and Robotics", Laxmi Publications Pvt ltd, 2007.							
7	Fu. K. S., Gonzalez. R. C. & Lee C.S.G., 'Robotics control, sensing, vision and intelligence', McGraw Hill Book co, 1987.							

8	Craig. J. J. 'Introduction to Robotics mechanics and control', Addison- Wesley, 1999
9	Ray Asfahl. C., 'Robots and Manufacturing Automation', John Wiley & Sons Inc., 1985.

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:						
CO1	O1 Understand the basic concepts, parts of robots and types of robots.						
CO2	Understand the potential applications of robots in industries as part of automation tool	Understand					
соз	Familiar with the various drive systems for robot, sensors and their applications in robots, programming of robots.	Remember					
CO4	Discuss about the various applications of robots, justification, implementation and safety of robot	Analyze					
CO5	Select an appropriate robot for a particular application.	Apply					

COURSE A	COURSE ARTICULATION MATRIX													
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PSO1	PSO2	PSO3
CO1	3	2	1	0	0	1	0	0	0	0	0	0	1	1
CO2	0	0	1	0	1	1	0	0	0	0	0	0	1	1
CO3	0	1	0	0	0	0	0	0	0	0	0	0	1	1
CO4	0	0	1	0	0	3	0	0	0	0	0	0	0	1
CO5	0	2	0	0	0	0	0	0	0	0	0	0	1	2
Avg	0.6	1	0.6	0	0.2	1	0	0	0	0	0	0	0.8	1.2
	3/2/1 – indicates strength of correlation (3 – high, 2- medium, 1- low)													

2MEOE04 POWER PLANT ENGINEERING						SEMESTER VI/VII						
PREREQUI	PREREQUISITES CATEGORY											
1. H	L	T	P	TH								
2. B	3	0	0	3								
COURSE O	BJECTIVES:											
1. and su	tanding of thermal power plant operation, different types of high- percharged boilers, fluidized bed combustion systems, Design edge of cooling tower operation											
2. Location	on of hydro power plant and its components to generate power											
3. Compl	ete knowledge about diesel and gas power plant											
4. Basic l	enowledge of nuclear reaction and types of nuclear power plant											
5. Basic l	enowledge of power plant economics and various tariff methods.											
UNIT I	STEAM POWER PLANT		9	0	0	9						
coal - Pulveri types - Chimr Circulated Flu	am power plant – boilers - Modern high pressure and supercritical zer - Dust collector - Ash removal; Stokers - Different types - Pulvey design - Selection of blowers, Cooling towers - Different types hidised Bed boilers	erized fuel burning;	Draughry, Flui	nt - D dised	iffere Bed	ent &						
UNIT II	HYDRO ELECTRIC POWER PLANT		9	0	0	9						
	del power plant- classification –working – components – layout of Pumped Store Schemes.	of pumped storage	power	plant	- Pla	ınt						
UNIT III	DIESEL AND GAS POWER PLANT		9	0	0	9						
	iesel power plant- Important components – performance analyof gas turbine cycles – components – relative thermal efficiencies of		gas po	wer 1	plant	_						
UNIT IV NUCLEAR, MHD POWER GENERATION						9						
	eatment - nuclear fission, chain reaction - Pressurized water react breeder reactors, Magneto Hydro Dynamic power- open cycle and			s, gas	cool	ed						
UNIT V	9	0	0	9								
and variable	d safety - Actual load curves - Fixed and operating costs - Tariff moad operations - Selection of generation type and general equipmental impacts - assessment for thermal power plant.											
		Tota	l(45L)	$= \frac{-}{45}$	5 Per	rioc						

TEXT I	TEXT BOOKS:						
1.	S. Domkundwar, A.V. Domkundwar, S.C. Arora.A Course in Power Plant Engineering, Dhanpat Rai Publications. 2013						
2.	P.K. Nag, Power Plant Engineering, Tata McGraw Hill, Laxmi Publications Pvt.Ltd New Delhi, 5th Edition, 2014.						
REFER	REFERENCES:						
1	R.K. Rajput. A Text of Power Plant Engineering, Laxmi publications, New Delhi 5th Edition, 2016.						
2	G.R. Nagpal, Power Plant Engineering, Khanna Publications 1998.						
3	Bernhardt G. Askrotzki and William A. Vopat, "Power Station Engineering and Economy", Tata McGraw Hill Publishing Co. Ltd., 1972.						
4	Frederick T. Mores, "Power Plant Engineering", Affiliated East-West Press Private Ltd., 1953.						

5	Joel Weisman and Roy Eckart, "Modern Power Plant Engineering", Prentice Hall International Inc., 1985.								
E-REF	E-REFERENCES:								
1.	https://en.wikipedia.org/wiki/Power_plant_engineering								
2.	https://onlinecourses.nptel.ac.in/noc21_me86/preview								

COU. Upon	Bloom Taxonomy Mapped	
CO1	Ample knowledge on thermal power plant operation and its merits and demerits.	Analyze
CO2	Potential Power of water to convert into useful energy by hydropower.	Remember
CO3	Augment with diesel and gas power plant operation and its components.	Understand
CO4	Able to cope with recent developments on nuclear power plant.	Understand
CO5	Understanding of various economics to construct power plant and to measure the consumption of power by different tariff.	Understand

COURSE A	OURSE ARTICULATION MATRIX														
COs/POs	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	PO7	PO8	PO 9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	3	2	1	0	1	1	2	0	2	2	2	1	2
CO2	1	2	3	2	1	0	1	1	2	0	2	2	2	1	2
CO3	1	2	3	2	1	0	1	1	2	0	2	2	2	1	2
CO4	1	2	3	2	1	0	1	1	2	0	2	2	2	1	2
CO5	2	0	1	2	0	0	0	2	2	1	1	1	2	0	0
Avg	1.2	1.6	2.6	2.0	0.8	0.0	0.8	1.2	2.0	0.2	1.8	1.8	2.0	0.8	1.6
	3/2/1 – indicates strength of correlation (3 – high, 2- medium, 1- low)														

	OE05	PRINCIPLES OF MANAGEMENT		MES VI/V	ESTER VIII				
			CATEGORY	OE	Cr	edit	3		
			Hours/Week	L	Т	P	T H		
				3	0	0	3		
COUF	RSE O	BJECTIVES							
1.	To unde	erstand the management basic features of management.							
2.	Princip	es usages in all walks of life and industrial growth.							
	3. Able to have a clear understanding of the managerial functions like planning, organizing, staffing, leading and controlling.								
4.	To gain	some basic knowledge in international aspect of management							
UNIT	ГІ	MANAGEMENT ANINTRODUCTIONANDOVERV	/IEW	9	0	0	9		
		management – features of management – Management thougagement – Arts or Science, Management Vs administration –			anago	ement	-		
UNIT	T II	FUNCTIONS OF MANAGEMENT		9	0	0	9		
functio	ons and	gers. Functions approach to management, Management func- role, responsibility of managers – towards subordinates, pe litors, shareholders, competitors etc.							
UNIT	III	MANAGERIAL PLANNING AND DECISION MA	KING	9	0	0	9		
types of	of plann tance of	amentals, objectives. Management by objectives – Changes ing, policies and objectives, procedures – methods, rules, progedecision making, types of decisions, decision making p decision making conditions – Operation Research (OR), I	rammes and schedule rocess – decision th	e, projec eory –	ts, bu quai	ıdgets ntitati	_		
		ision tree.		arcas	of o _l	perati			
	T IV	ORGANIZATION		9	of o ₁	peration of the second of the			
UNIT Organi - typol operati	ization: logy, in ive, pu		 sole trading, partner matrix committee-base 	9 modern	organ	onizationy, co	9 on -		
UNIT Organi - typol operati	ization: logy, in ive, pul mentaliz	ORGANIZATION Basic concepts – organization as a structure – as a process – as a protance of organization – business /industrial organization – blic enterprise line (military), line and staff, functional,	- sole trading, partner matrix committee-bar management.	9 modern	organ	onizationy, co	9 on -		
Organi - typol operati departr UNIT Nature sources imports - defin	ization: ilogy, in ive, pul mentaliz V e and pu es of recitance pr nition —	ORGANIZATION Basic concepts – organization as a structure – as a process – as a portance of organization – business /industrial organization – blic enterprise line (military), line and staff, functional, cation – need, bases of departmentation – career planning and a	- sole trading, partner matrix committee-be management. ATION of HR recruitment, so nice appraisal methods of effective commun	9 modern rship coased or 9 election s – comication	organized on the control of the cont	onization of training cation attrolling training troubles.	9 on 9 ng - ng		

REFE	REFERENCE BOOKS:							
	HeraldknootzandHeinzweihrich,EssentialsofManagement ,McGraw-HillPublishingCompany, SingaporeInternationalEdition,2007							
2	JosephL, Massie, Essentials of Management. Prentice Hallof India Pvt., Ltd (Pearson) Fourth Edition, 2003.							
3	StephenA. Robbins &David A. Decenzo &Mary Coulter, "Fundamentals of Management"							

	7thEdition,PearsonEducation,2011.						
4	RobertKreitner&MamataMohapatra,"Management",Biztantra,2008.						
5	HaroldKoontz &HeinzWeihrich"Essentialsof management"TataMcGrawHill,1998.						
6	TripathyPC &ReddyPN,"Principles of Management", Tata McGrawHill, 1999.						
7	R.S.N. Pillai&S. Kala "Principles and Practice of Management", S Chand & company, 2014.						
E-RE	E-REFERENCES:						
1.	https://nptel.ac.in/courses/110105146						
2.	https://nptel.ac.in/courses/122106031						

COU	Bloom Taxonomy Mapped	
CO1	Understand the basic concept so management	Understand
CO2	Familiarize the contribution sand functions, types of business organization	Understand
соз	List the various types of leadership and evaluate the motivation the ories and techniques.	Evaluate
CO4	Select forecasting models for future demands and to make decision in the management processes.	Evaluate

	COURSE ARTICULATION MATRIX													
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PSO1	PSO2	PSO3
CO1	0	0	0	0	0	0	1	3	1	0	2	2	1	1
CO2	0	0	0	0	0	0	1	1	2	0	3	2	1	1
CO3	0	0	0	0	0	0	0	1	2	0	1	1	1	1
CO4	0	0	0	0	0	0	2	1	2	0	2	1	1	1
Avg	0	0	0	0	0	0	1	1.5	1.75	0	2	1.5	1	1
	3/2/1 – indicates strength of correlation (3 – high, 2- medium, 1- low)													

22MI	EOE06	PROFESSIONAL ETHICS IN ENGINEE	RING		MES VI/V		.
			CATEGORY	OE	Cr	edit	3
			Horus/Week	L	Т	P	T H
				3	0	0	3
COU	JRSE O	BJECTIVES					
1		tte awareness on Engineering Ethics and providing basic knowlessues and Professional Ideals.	edge about engineeri	ng Eth	ics, V	ariet	y of
2	To pro	ovide basic familiarity about Engineers as responsible Expeds.	perimenters, Codes	of Eth	ics,	Indus	trial
3	To incu	llcate knowledge and exposure on Safety and Risk, Risk Benefi	t Analysis.				
UNI	TI	HUMAN VALUES		9	0	0	9
Peace Conf	efully – c idence – (s and Ethics – Integrity – Work Ethic – Service Learning – Caring – Sharing – Honesty – Courage – Valuing Time – Co-op Character – Spirituality.		nt – Ei			
UNI	TII	ENGINEERING ETHICS		9	0	0	9
Kohl	berg's the	gineering Ethics' - variety of moral issued - types of inquir cory - Gilligan's theory - consensus and controversy – Models on terest- customs and religion - uses of ethical theories.					
UNI	TIII	ENGINEERING AS SOCIAL EXPERIMENTATION		9	0	0	9
		s experimentation - engineers as responsible experimenters - coccase study.	des of ethics - a balan	ced ou	tlook	on la	.w –
UNI	TIV	SAFETY, RESPONSIBILITIES AND RIGHTS		9	0	0	9
Cherr confl	nobyl cas	k - assessment of safety and risk - risk benefit analysis and se studies. Collegiality and loyalty - respect for authority - terest – occupational crime - professional rights - employee ri	collective bargainin	g - co	onfide	ntiali	ity -
UNI	TV	GLOBAL ISSUES		9	0	0	9
const ASM	ulting en E,ASCE,	corporations - Environmental ethics - computer ethics - weap gineers-engineers as expert witnesses and advisors -moral, IEEE, Institution of Engineers (India), Indian Institute of telecommunication engineers (IETE),India.	leadership-sample	code o	of Et	hics	like

ASME, ASCE, IEEE, Institution of Engineers (India), Indi	lian Institute of Materials Management, Institution of
electronics and telecommunication engineers (IETE),India.	
	Total(45L) = 45Periods

REFE	REFERENCE BOOKS:						
1	Mike Martin and Roland Schinzinger, "Ethics in Engineering", McGraw-Hill, New York 2005.						
2	Govindarajan M, Natarajan S, Senthil Kumar V. S, "Engineering Ethics", Prentice Hall of India, New Delhi, 2004.						
3	Tripathi A N, "Human values", New Age international Pvt. Ltd., New Delhi, 2002.						
4	Charles D. Fleddermann, "Engineering Ethics", Pearson Education / Prentice Hall, New Jersey, 2004.						
5	Charles E Harris, Michael S. Protchard and Michael J Rabins, "Engineering Ethics – Concepts and Cases", Wadsworth Thompson Learning, United States, 2000.						

6	John R Boatright, "Ethics and the Conduct of Business", Pearson Education, New Delhi, 2003.
7	R S Naagarazan, "A Textbook on Professional Ethics and Human Values" New age international (p) limited, publishers, New Delhi – 110002, 2006.

	URSE OUTCOMES: n completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Understand the importance of ethics and values in life and society.	Understand
CO2	Understood the core values that shape the ethical behavior of an engineer.	Understand
CO3	Exposed awareness on professional ethics and human values.	Remember

COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PSO1	PSO2	PSO3
CO1	0	0	0	0	0	2	1	3	2	0	1	0	0	1
CO2	0	0	0	0	0	1	1	3	1	0	1	0	0	1
CO3	0	0	0	0	0	2	1	3	1	0	1	0	0	1
Avg	0	0	0	0	0	1.66	1	3	1.33	0	1	0	0	1
	•	•	3/2/1 -	- indica	ates str	ength o	of corre	elation (3 – hig	h, 2- me	dium, 1-	low)	•	·

22MEOE07												
PRE-REQUI 1. Basic idea al	SITE: pout solar radiation and other renewable energy that exists.	CATEGORY	OE	Cr	edit	3						
2. Understand	ling about various chemical reactions occur in the process	Horus/Week	L	Т	P	T H						
			3	0	1	4						
COURSEO	BJECTIVES											
1. To rec	ognize the consciousness of energy conservation in scholars											
2. To ide	To identify the employ of renewable energy sources for electrical power generation											
3. To col	To collect different energy storage methods											
4. To det	ect about environmental effects of energy conversion											
UNITI	SOLAR RADIATION AND ITS MEASUREMENTS		9	0	0	9						
Measurement UNITII	and Instruments – Data and estimation. SOLAR ENERGY COLLECTORS, SOLAR ENERGY APPLICATIONS OF SOLAR ENERGY	Y STORAGE AND	9	0	0	9						
Fundamentals Thermal ener	d Concentrating Collectors –Solar direct Thermal Applications of Solar Photo Voltaic Conversion – Solar Cells – Solar PV gy, Chemical Energy and Electromagnetic energy storage; Solar distillation, Solar pumping, Solar furnace, Solar cooling, Solar distillation, Solar pumping, Solar furnace, Solar cooling, Solar distillation, Solar pumping, Solar furnace, Solar cooling, Solar coo	Power Generation –Solar PV Applications:	olar E	nergy	Stor	age:						
UNITIII	BIOMASS AND ITS CONVERSION TECHNOLOGI	ES	9	0	0	9						
types; Wet Pr	eversion Techniques: Direct combustion (incineration); Thermoreocess- Classification of biogas plant- types of Anaerobic digent, Gasnesh biogas plant and Ferro-cement digester biogas plant)	estion (Khadi and Vil	lage I									
UNITIV	WIND, GEOTHERMAL AND TIDAL ENERGY		9	0	0	9						
geothermal re Comparison o	le of wind energy conversion, types of wind energy conversesources, geopressurised resources, hot dry rock resources of por flashed steam and total flow concept. Basic principle of tidal chods of utilization of tidal power.	petrothermal systems,	Magn	na res	source	es –						
UNITV	CHEMICAL ENERGY, HYDROGEN ENERGY ANI HYDRO DYNAMIC	O MAGNETO	9	0	0	9						
	rinciple operation of a Fuel cells, classification of fuel cells, typons of fuel cells. Basic principle of Magneto Hydro Dynamic – Company of the Company of					ıges						
		Total (4	15T) -	_ 15T	Damia	da						

REFE	REFERENCE BOOKS:										
1	G.D. Rai, "Non-Conventional Energy Sources", Khanna Publishers, New Delhi, 2014.										
2	Suhas P. Sukhatme, "Solar Energy", Tata McGraw Hill Publishing Company Ltd., 2007.										
3	Khan, B.H., "Non-Conventional Energy Resources", The McGraw Hill Companies, 2009.										
4	Twidell, J.W. & Weir, A., "Renewable Energy Resources", EFN Spon Ltd., UK, 2005.										
5	Solanki: Renewable Energy Technologies: Practical Guide for Beginners, PHI Learning Pvt.Ltd., 2008										

6	D. Mukherjee: Fundamentals of Renewable Energy Systems, New Age International publishers, 2007.											
7	Gilbert M. Masters: Renewable and Efficient Electric Power Systems, John Wiley & Sons, 2004.											
E-RE	E-REFERENCES:											
1.	https://en.wikipedia.org/wiki/Renewable_energy											
	Ellabban, Omar; Abu-Rub, Haitham; Blaabjerg, Frede (2014). "Renewable energy resources: Current status, future prospects and their enabling technology". Renewable and Sustainable Energy Reviews. 39: 748–764 [749]											

COU	JRSE OUTCOMES:	Bloom Taxonomy							
Upor	Upon completion of this course, the students will be able to:								
CO1	Understand the principles of solar radiation and its measuring devices Un								
CO2	Comprehend the ideology of solar energy collectors, solar photovoltaic power generationsolar energy storage and applications of solar energy	Analyze							
CO3	Acquire awareness about biomass sources of energy technologies	Understand							
CO4	Design various renewable energy gadgets such as wind and tidal plant	Create							
CO5	Learn about extracting energy from chemical methods	Understand							

COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PSO1	PSO2	PSO3
CO1	1	2	3	2	1	0	2	2	3	1	1	2	2	1
CO2	1	2	3	2	1	0	2	2	3	1	1	2	2	1
CO3	0	2	3	2	1	0	2	2	3	1	1	2	2	1
CO4	1	2	3	2	0	0	2	2	3	1	1	2	2	1
CO5	1	2	3	2	1	0	2	2	3	1	1	2	2	1
Avg	0.8	2	3	2	1	0	2	2	3	1	1	2	2	1
			3/2/1	– indi	cates st	rength	of corr	elation	(3 – hi	gh, 2- me	edium, 1-	low)		

2ME	2MEOE08 ROBOTIC PROCESS AUTOMATION											
Pre-re	quisite		CATEGORY	OE	Cre	edit	3					
1.	Basics i	n kinematics and dynamics	Hours/Week	L	Т	P	T H					
				3	0	0	3					
COU	RSEOI	BJECTIVES										
1.	To stud	ly the various parts of robots and fields of robotics.										
2.	To study the various kinematics and inverse kinematics of robots.											
3.	. To study the Euler, Lagrangian formulation of Robot dynamics.											
4.	To study the trajectory planning for robot.											
5.	To stud	ly the control of robots for some specific applications										
UNIT	ΓΙ	BASIC CONCEPTS		9	0	0	9					
Asimo	ov"s law	d origin of robotics – different types of robotics – various ges of robotics – dynamic stabilization of robots.	nerations of robots –		s of fi	reedo	m –					
UNIT	ГІІ	POWER SOURCES AND SENSORS		9	0	0	9					
arrang	gements	neumatic and electric drives – determination of HP of n – path determination – micro machines in robotics – mach er optic and tactile sensors										
UNIT	ГШ	MANIPULATORS, ACTUATORS AND GRIPPERS	}	9	0	0	9					
		of manipulators – manipulator dynamics and force control – el effectors – U various types of grippers – design considerations		ic mani	pulato	or cor	ıtrol					
UNIT	ΓIV	KINEMATICS AND PATH PLANNING		9	0	0	9					
		verse kinematics problem – multiple solution jacobian work olanguages	envelop – hill Climbir	ıg Tech	nique	s – re	obot					
UNIT	ΓV	CASE STUDIES		9	0	0	9					
	ple robo ction of	ts – machine interface – robots in manufacturing and non- marobot.	nufacturing application	ns – ro	bot ce	ell de	sign					
			Total	(45L) =	= 45I	erio	ds					

REFE	CRENCE BOOKS:
1	Mikell P. Weiss G.M., Nagel R.N., Odraj N.G., "Industrial Robotics", Mc Graw-Hill Singapore, 1996.
2	Ghosh, Control in Robotics and Automation: Sensor Based Integration, Allied Publishers, Chennai, 1998.
3	Deb. S.R., "Robotics Technology and flexible Automation", John Wiley, USA 1992.
4	Klafter R.D., Chimielewski T.A., Negin M., "Robotic Engineering – An integrated approach", Prentice Hall of India, New Delhi, 1994.
5	Barry Leatham – Jones, "Elements of industrial Robotics" PITMAN Publishing, 1987.
6	Mikell P.Groover, Mitchell Weiss, Roger N.Nagel Nicholas G.Odrey, "Industrial Robotics Technology, Programming and Applications", McGraw Hill Book Company 1986.
7	Fu K.S. Gonzaleaz R.C. and Lee C.S.G., "Robotics Control Sensing, Vision and Intelligence" McGraw Hill International Editions, 1987.

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:								
CO1	Explain the basic concepts of working of robot.	Understand							
CO2	Analyze the function of sensors in the robot.	Analyze							
CO3	Analyze the working of manipulates, actuators and grippers.	Analyze							
CO4	Write program to use a robot for a typical application.	Create							
CO5	Use robots in different applications.	Apply							

COURSE	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PSO1	PSO2	PSO3	
CO1	1	1	2	0	2	0	0	0	0	1	0	2	2	2	
CO2	1	3	2	1	1	0	0	0	0	0	0	2	1	3	
CO3	0	2	2	1	1	0	0	0	0	0	0	2	1	3	
CO4	0	1	1	2	3	0	0	1	3	2	1	2	0	0	
CO5	0	1	2	2	2	1	2	2	3	2	1	2	0	0	
Avg	1	1	2	1.4	2	0.2	0.4	0.6	1.2	1	0.4	2	2	2	
			3/2/1	– indic	ates st	rength	of corr	elation	(3 – hi	gh, 2- me	edium, 1-	low)			

22MEOE09	TOTAL QUALITY MANAGEME	NT		MES' /I/VI					
		CATEGORY OE Credi							
		Hours/Week	L	Т	P	T H			
			3	0	0	3			
COURSEO	BJECTIVES								
	the need for quality, its evolution, basic concepts, contrrs and Benefits of TQM.	ibution of quality gur	ıs, TQ	M fra	mew	ork,			
2. Explai	n the TQM Principles for application.								
3. Define	the basics of six sigma and apply traditional tools, new tools	s, Benchmarking and Fl	ÆΑ.						
4. Descri	be Taguchi's Quality Loss Function, Performance measures PR.	and apply techniques	ike QF	D, TP	M, C	OQ.			
5. Illustra	ate and apply QMS and EMS in any organization.								
UNITI	INTRODUCTION		9	0	0	9			
Basic conce	Quality - Dimensions of Quality - Quality planning - Quality pts of total quality management (TQM)-Historical r management-Qualitycouncil, Qualitystatements - Strategic plann	eview- Principles of	TQM	- Le	aders	hip-			
UNITII	TQM PRINCIPLES		9	0	0	9			
Employee in Continuous p	isfaction - Customer perception of quality, Customer comp volvement - Motivation, Empowerment, Teams, Recogn rocess improvement - Juran Trilogy, PDSA Cycle, 5S, Kaiz pplier rating, Relationship development - Performance measu	ition and reward, Per en - Supplier Partnersh	forman ip, Sou	ce ap	prais	al -			
UNITIII	STATISTICAL PROCESS CONTROL (SPC)		9	0	0	9			
	ols of quality, Statistical fundamentals – Measures of cent nal curve - Control charts for variables and attributes, Process tools.								
UNITIV	UNITIV TQM TOOLS 9 0 0 9								
of quality, Be	g – Reasons to benchmark, Benchmarking process, Quality enefits - Taguchi quality loss function - Total productive mainges of FMEA.								
UNITV	QUALITY MANAGEMENT SYSTEMS		9	0	0	9			
	Need for ISO 9000 and other quality systems, benefits of ISO registration, ISO 9001:2008 quality system – Elements, Implementation of quality system, Documentation, Quality auditing, AS 9100,TS 16949:2002 and TL 9000								
	Total (45L) = 45Periods								

REFERENCE BOOKS:										
1	Dale H.Besterfiled, Carol B.Michna, Glen H. Bester field, Mary B. Sacre, Hemant Urdhwareshe and Rashmi Urdhwareshe, "Total Quality Management", Pearson Education Asia, Revised Third Edition, Indian Reprint, Sixth Impression, 2013.									
2	Feigenbaum.A.V. "Total Quality Management", McGraw Hill, 1991.									

3	Joel.E. Ross, "Total Quality Management – Text and Cases", Routledge., 2017.							
4	Kiran.D.R, "Total Quality Management: Key concepts and case studies, Butterworth – Heinemann Ltd, 2016.							
5	Oakland, J.S. "TQM – Text with Cases", Butterworth – Heinemann Ltd., Oxford, Third Edition, 2003.							
6	Suganthi,L and Anand Samuel, "Total Quality Management", Prentice Hall (India) Pvt. Ltd., 2006							
7	Narayana V and Sreenivasan, N.S, "Quality Management – Concepts and Tasks", New Age International, 1996.							
E-RI	EFERENCES:							
1.	https://www.oreilly.com/library/view/total-quality-management/9780815330486/xhtml/Reference1.xhtml							
2.	https://www.sanfoundry.com/best-reference-books-total-quality-management/							
3.	https://www.routledge.com/Total-Quality-Management-TQM-Principles-Methods-and-Applications/Luthra-Garg-Agarwal-Mangla/p/book/9780367512835							

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:							
CO1	Ability to apply TQM concepts in a selected enterprise.	Apply						
CO2	Ability to apply TQM principles in a selected enterprise.	Apply						
соз	Ability to understand Six Sigma and apply Traditional tools, new tools, Benchmarking and FMEA.	Understand						
CO4	Ability to understand Taguchi's Quality Loss Function, Performance Measures and apply QFD, TPM, COQ and BPR.	Understand						
CO5	Ability to apply QMS and EMS in any organization.	Apply						

COURSE	OURSE ARTICULATION MATRIX													
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PSO1	PSO2	PSO3
CO1	1	3	0	0	2	0	1	0	2	0	0	2	1	2
CO2	1	2	0	0	0	0	0	0	2	0	0	2	0	0
CO3	1	2	2	0	1	0	0	1	0	0	0	2	1	0
CO4	1	2	0	0	2	3	0	2	0	3	0	2	2	2
CO5	1	2	2	0	2	2	1	2	2	3	0	2	2	2
Avg	1	2.2	0.8	0	1.4	1	0.4	1	1.2	1.2	0	2	1.2	1.2
			3/2/1	– indic	ates st	rength	of corr	elation	(3 – hi	gh, 2- m	edium, 1-	low)	•	•

PROFESSIONAL ELECTIVE COURSES – VERTICALS

VERTICAL 1 – CLEAN AND GREEN ENERGY TECHNOLOGY

22MF	ЕНО101	HYDROGEN AND FUEL CELL TECHNOLOGIES					
		CATEGOI	RY	PE	E Credit		C
		T		L	Т	P	ТН
		Hours/We	ek –	3	0	0	3
COU	RSE OBJI	ECTIVES	•		•	•	
1	To study i	n detail on the hydrogen production methodologies, possible applications and	various	stora	ge op	tions	
2	To unders	tand the working principle of atypical fuel cell, its types and to elaborat	ion its	thern	odyn	amic	s and
3	To study t	he cost effectiveness and eco-friendliness of Fuel Cells					
UNI	TI	INTRODUCTION		9	0	0	9
	olysis–gasif	cal and chemical properties, salient characteristics, Production of hydrogen ication-biological hydrogen production-photo dissociation- direct therma					
UNI	TII	HYDROGENSTORAGE		9	0	0	9
	rogenstorage gement of h		parison	s,	safet	y	and
UNI	TIII	FUELCELLS		9	0	0	9
		e-working-thermodynamicsandkineticsoffuelcellprocess-performance evaluate attery Vs fuel cell.	ion of f	uel ce	11—		
UNI	TIV	FUELCELL-TYPES		9	0	0	9
Туре	es of fuel cel	ls-AFC, PAFC,SOFC, MCFC, DMFC, PEMFC- Relative merit sand demerit	s.				
UNI	TV	APPLICATIONOFFUELCELLANDECONOMICS		9	0	0	9
		for domestic power systems, large scale power generation, Auto mobialysison usage of Hydrogen and Fuel cell, Future trendsin fuel cells.	le, Spa	ce, I	Econo	mic	and
			Total (4	45L)	= 45	Perio	ods

REFE	REFERENCE BOOKS:								
1	ViswanathanB.andAuliceScibioh.M,FuelCells-Principlesand Applications,UniversitiesPress,2006								
2	2 RebeccaL.andBusby,HydrogenandFuelCells:AComprehensiveGuide,Penn WellCorporation,Oklahoma,2005								
3	BentSorensen(Sorensen),HydrogenandFuelCells:EmergingTechnologies andApplications,Elsevier,UK2005								
4	KordeschK.AndG.Simader,FuelCellandtheirApplications,Wiley-Vch,Germany1996								
5	HartA.B.andG.J.Womack,FuelCells:TheoryandApplication,PrenticeHall,NewYorkLtd., London1989								
6	JeremyRifkin,TheHydrogenEconomy,PenguinGroup,USA2002								
7	BarclayF.J.,FuelCells,EnginesandHydrogen,Wiley,2009								

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:							
CO1	Describe and analyze the techniques of Hydrogen generation	Analyze						
CO2	Describe and classify various options for Hydrogen storage	Analyze						
CO3	Explain the principal operations of fuel cell, its thermodynamics and kinetics	Understand						
CO4	Comprehendthedifferenttypesoffuelcellscomparetheirmeritsanddemerits	Understand						
CO5	Identify the potential application of a fuel cells for domestic ,automotive, spacecraft power generations and evaluate the techno-economics of a fuel cells	Analyze						

COURSE	OURSE ARTICULATION MATRIX													
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PSO1	PSO2	PSO3
CO1	3	2	0	0	1	0	0	0	0	0	0	0	1	1
CO2	3	2	0	0	1	0	0	0	0	0	0	0	1	1
CO3	3	2	1	1	1	0	1	0	0	0	0	0	1	1
CO4	3	3	1	2	1	1	1	0	0	0	0	0	1	1
CO5	3	2	1	1	2	2	1	0	0	0	0	1	1	1
Avg	3	2.2	0.6	0.8	1.2	1.5	0.6	0.0	0.0	0.0	0.0	0.2	1	1
	3/2/1 – indicates strength of correlation (3 – high, 2- medium, 1- low)													

22M	IEHO102	THERMAL MANAGEMENT OF ELECTR BATTERY SYSTEMS	CIC VEHICLE						
	CATEGORY PE								
			II /\ \ \ \ -	L	T	P	T	Ή	
			Hours/Week	3	0	0		3	
COUR	SE OBJEC	TIVES			<u>.</u>				
1	To know Tl	nermal Management of Electric Vehicle Battery System	ns						
2	To recogniz	te the applications of PC Min Thermal Management							
3	To investig Experimenta	ate the Thermal be haviorsin Electric Vehicle Battery	Systems through Si	mulatio	n an	d			
4	To calculate	the Energy and Exergy Analyses of Battery TMSs							
5	Toobtainsol	utions for case Studies on Thermal Management Solutions of the state	ofElectricbatteries						
UNIT	ΓI	INTRODUCTION			9	0	0	9	
Batter	ies, Lithiun gement/Fault	ent Battery Technologies: Lead Acid Batteries, Nicken-Ion Batteries, Battery Environmental Impact, Diagnosis/Thermal Management.	Battery Manage	ement		Metal ems,	•	ride fety	
UNIT		PHASECHANGEMATERIALSFORTHERMA SYSTEMS	ALMANAGEME	NT	9	0	0	9	
		d Types of PCMs, Organic PCMs, Inorganic PCMs, lancements, Environmental Impact of Phase Change Ma				rties o	of PC	CMs	
UNIT		SIMULATION AND EXPERIMENTAL BATTERY TMS	NVESTIGATION	N OI	9	0	0	9	
Proced		Development for Cell and Sub modules, Cell and Level Experimentation Set Up and Procedure, Illustration PCMs							
UNIT	ΓΙV	ENERGYANDEXERGYANALYSESOFBATT	TERYTMS		9	0	0	9	
		Mode ling of Major TMS Components ,Energy and Eanagement Systems	Exergy Analyses, Ill	ustrativ	e Ex	ample	: Lic	quid	
UNIT	UNITY CASE STUDIESONTHERMALMANAGEMENT SOLUTIONSOF ELECTRIC BATTERIES							9	
Case Batter		rimental and Theoretical Investigation of Temperatur	re Distributions in	a Prisn	natic	Lithi	um-	Ion	
	tudy2: Thern arge Cycles	nal Management Solutions for Electric Vehicle Lithiun	m-Ion Batteries base	ed on V	ehic!	le Cha	arge	and	
			To	tal (45	(L) =	45P	erio	ds	

REFE	REFERENCE BOOKS:									
1	IbrahimDinçer, HalilS. Hamut, Nader Javani, Thermal Management of Electric Vehicle Battery Systems, C, 2017									
2	Halil S.Hamut,NaderJavani,IbrahimDinçer,Thermal Management ofElectricVehicle BatterySystems,Wiley,2016									
3	WeixiangShen,RuiXiong,AdvancedBatteryManagementTechnologiesforElectric Vehicles,JohnWileyandsons,Firstedition2019									
4	ChitraA.,SanjeevikumarPadmanaban,JensBoHolm-Nielsen,ArtificialIntelligentTechniques									

	forElectricandHybridElectricVehicles,JohnWileyandsons,Firstedition2020							
4	BrunoScrosati, ElectricVehicles,WoodheadPublishing,2015	Jurgen Garche, Werner Till metz, Advances in Battery Technologies for						

COURSE OUTCOMES: Upon completion of this course, the students will be able to:			
CO1	Describeandanalyzethetechniquesofthermalmanagementofelectricvehiclebatterysystems	Analyze	
CO2	Describe and classify various applications of PC Min thermal management	Understand	
соз	Investigate the thermal behaviour sin electric vehicle battery systems through simulation and experimental.	Analyze	
CO4	Calculate the energy and exergy analyses of battery TMSS	Analyze	
CO5	Identifythesolutionsforcasestudiesonthermalmanagementsolutionsofelectricbatteries	Analyze	

COURSE ARTICULATION MATRIX PSO2 PSO3 COs/POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 PO10 PO11 **PO12** PSO₁ **CO1** CO₂ **CO3 CO4 CO5** 2.8 2.2 1.2 0.2 0.04 0.0 1.8 0.0 0.0 Avg 0.8 0.6 0.8 0.01 0.01 3/2/1 – indicates strength of correlation (3 – high, 2- medium, 1- low)

22MEHO103	ELECTRIC AND HYBRID VEHICE	LE TECHNOLOGY					
		CATEGORY	PE	PE Cred			3
		TT /55/ 1	L	Т	P	Т	Н
		Hours/Week	3	0	0		3
COURSE OBJ	ECTIVES		•	•			
1 To intro	duce the concept of hybrid and electric drive train	1S					
2 Toelabo	orateonthetypesandutilizationofhybridandelectricd	rivetrains					
3 To expo	seon different types of AC and DC drives for elec-	ctric vehicles					
4 To und	erstand and utilize different types of energy storag	ge systems					
5 To intro	duce concept of energy management strategies ar	nd drive sizing					
UNIT I	INTRODUCTION			9	0	0	9
	e performance, vehicle power source characterizacles, social and environmental importance of hybrid HYBRID ELECTRIC DRIVE TRAINS		istics, F	listor:	of 1	nybr 0	id
hybriddrive-train	of hybridtraction, introduction to various hybridtopologies, fuel efficien cyanalysis. Electric Drive- lrive-traintopologies, power flow control in electr	trains:Basicconceptofelectric					
UNIT III	CONTROLOFAC&DCDRIVES			9	0	0	9
	lectric components used in hybrid and electric vel drives, Permanent MagnetMotordrive, and Switch						s,
UNIT IV	ENERGYSTORAGE AND DRIVE SIZIN	NG		9	0	0	9
Hybridization of	Energy Storage Requirements in Hybrid and E different energy storage devices, Sizing the dronengine(ICE), Sizing the propulsion motor, sizing the gy	ive system: Matching the el	lectric r	nachi	ne ar	nd tl	he
UNIT V	ENERGY MANAGEMENTSTRATEGIE	ES		9	0	0	9
	entStrategies:Introductiontoenergymanagementstra energymanagementstrategies,implementationissues		cvehicle	es,cla	ssific	atio	ıa
		To	otal(45	L) =	45 F	Peri	00

REFERENCE BOOKS:								
1	IqbalHussein,ElectricandHybridVehicles:DesignFundamentals,CRC press,2003							
2	JamesLarminie,johnlowry,ElectricVehicleTechnologyExplained,Wiley,2003							
3	MehrdadEhsani, YimiGao, SebastianE. Gay,AliEmadi, ModernElectric,HybridElectric andfuelcellvehicles: Fundamentals,theoryanddesign, CRC press,2004							
4	Randd.A.J,Woods,R&dellrmbatteriesforelectricvehicles,johnwiley&Sons,1998							

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:						
CO1	CO1 Characterize and configure hybrid drive trains requirement for a vehicle						
CO2	Design and apply appropriate hybrid and electric drive train sina vehicle	Create					
CO3	Design and install suitable AC and DC drives for electric vehicles	Create					
CO4	Arrive at a suitable energy storage system for a hybrid/electric vehicle	Understand					
CO5	Apply energy management strategiestoen sure better economy and efficiency	Apply					

COURSE .	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	0	1	1	1	0	0	0	0	0	0	0	1
CO2	3	2	2	0	1	1	0	1	1	0	0	0	0	0	2
CO3	3	1	3	1	2	1	1	2	0	1	0	0	0	0	2
CO4	2	3	1	1	1	1	1	1	0	1	2	0	0	1	1
CO5	3	2	0	0	1	1	1	0	0	2	1	2	0	1	1
Avg	2.8	2	1.6	0.4	1.2	1	1	0.8	0.2	0.8	0.6	0.4	0.0	0.4	1.4
			3/2/	′1 – in	dicates	stren	gth of	correla	tion (3 -	high, 2	- medium	, 1- low)			

	HO104	ALTERNATE FUELS FORICENGINES	5							
		(PE	Cre		C				
				L	Т	P	1	ГН		
		I.E.	Iours/Week	3	0	0		3		
COUR	RSE OBJ	ECTIVES		<u> </u>						
1	To exp	pose potential alternate fuels and their characteristics								
2	Tousea	appropriatesyntheticfuelsandfueladditivesforbettercombustionchara	acteristics							
3	To utilize alcohol fuels effectively for low emissions									
4	Toelab	oorateontheutilizationofBio-DieselanditstypesasasuitablefuelinClen	igines							
5	To util	lize different gaseousfuelsandpredicttheirperformanceandcombustion	oncharacteristics							
UNIT	ΓI	INTRODUCTION			9	0	0	9		
their	rent synth effec	SPECIAL AND SYNTHETIC FUELS etic fuels, Merits and demerits, Dual, Bi-fuel and Pilot inject defect on performance and emission characteristics	uel systems, Fuel cteristics of		9 tives- engin			and		
Differ their	rent synth effect andfuelad	etic fuels, Merits and demerits, Dual, Bi-fuel and Pilot inject defect on performance and emission characteristics.	•		tives-	- typ	es a	and rs–		
Differ their asfuel UNIT	rent synth effect andfuelad F III nols—Prope	etic fuels, Merits and demerits, Dual, Bi-fuel and Pilot inject defect on performance and emission characteristics	cteristics of		tives- engin	typnes,E	es a Ether	and rs-		
Differ their asfuel UNIT Alcoh in eng	rent synth effect andfuelad ITIII nols—Proper	etic fuels, Merits and demerits, Dual, Bi-fuel and Pilot inject defect on performance and emission characteristics ALCOHOL FUELS erties, Production methods and usage in engines. Performance, co	cteristics of		tives- engin	typnes,E	es a Ether	and rs—		
Differ their asfuel UNIT Alcoh in eng UNIT Veget Blend	rent synth effect andfuelad FIII nols—Proper gines. Issu FIV table oils	etic fuels, Merits and demerits, Dual, Bi-fuel and Pilot inject defect on performance and emission characteristics ALCOHOL FUELS erties, Production methods and usage in engines. Performance, co es & limitation in alcohols	ombustion and em	nission	g Cha	typnes,F o aracte ttable	es a Ether Oerist Oerist	rs-		
Differ their asfuel UNIT Alcoh in eng UNIT Veget Blend	rent synth effect andfuelad TIII nols—Proper gines. Issu TIV table oils ling,prehe engines	etic fuels, Merits and demerits, Dual, Bi-fuel and Pilot inject defect on performance and emission characteristics ALCOHOL FUELS erties, Production methods and usage in engines. Performance, coes & limitation in alcohols BIO-DIESEL FUELS and their important properties. Fuel properties characterizatio	ombustion and em	nission	g Cha	typnes,F o aracte ttable	es a Ether Oerist Oerist	and rs—		
Differ their asfuel UNIT Alcoh in eng UNIT Veget Blend diesel UNIT Bioga	rent synth effect andfuelad FIII nols—Proper gines. Issu FIV table oils ling,prehe engines FV as, Natural	etic fuels, Merits and demerits, Dual, Bi-fuel and Pilot inject defect on performance and emission characteristics ALCOHOL FUELS erties, Production methods and usage in engines. Performance, coes & limitation in alcohols BIO-DIESEL FUELS and their important properties. Fuel properties characterization ating, Transesterificationandemulsification—Performance, combustion	ombustion and em on. Methods of u	nission using n Ch	9 vege aract	table erist	es a a a a a a a a a a a a a a a a a a a	and rs— tics		

REF	REFERENCE BOOKS:					
1	KeithOwenandtrevoreoley,AutomotiveFuelsHandbook,SAE publications,1990					
2	PundirB.P,I.C.EnginesCombustionandEmission,2010, Narosapublishinghouse					
3	PundirB.P,EngineCombustionandEmission,2011, Narosapublishinghouse, Keith					
4	Richardl.Bechtold,AutomotiveFuelsguidebook, SAE publications,1997					

	URSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Analyze potential alternate fuels and their characteristics	Analyze
CO2	Useappropriatesyntheticfuelsandfueladditivesforbettercombustioncharacteristics	Understand
CO3	Describethepropertiesofalcoholfuelandestimatetheperformanceofalcoholfuelsand its emissions	Understand
CO4	Explaintheproperties and combustion and emission characteristics of bio-diesel	Understand
CO5	Explain different gaseous fuels and predicttheir performance and combustion characteristics	Understand

COURSE ARTICULATION MATRIX COs/POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 PO9 PO10 PO11 PSO1 PSO2 PSO3 **CO1 CO2 CO3 CO4 CO5** 2.2 1.8 0.8 0.8 0.6 0.4 0.0 0.2 0.6 0.8 0.0 1.4 1.6 Avg

22ME	CHO105	ADVANCED ENERGY STORAGE	TECHNOLOGIES					
			CATEGORY	PE	Cred	lit	3	
				L	Т	P	TI	I
			Hours/Week	3	0	0	3	
COUR	SE OBJ	ECTIVES	,	I	1			
1	Tound	erstandthevarioustypesofenergystoragetechnologi	esanditsapplications					
2	Tostud	ythevariousmodelingtechniquesofenergystorages	ystemsusingTRNSYS					
3	To lear	rn the concepts and types of batteries						
4	Tomak	ethestudentstogetunderstandtheconceptsofHydrog	genandBiogasstorage					
5	To pro	vide the insight son Fly wheel and compressed er	nergy storage systems					
UNI	TI	INTRODUCTION			9	0	0	9
Neces	sityofene	gystorage-typesofenergystorage-comparisonofe	nergystoragetechnologies-A _l	pplicati	ons	1		
UNIT	ΓII	THERMAL STORAGE SYSTEM			9	0	0	9
	_	e-Types-Modelling of thermal storage units-Si- stem-Modelling of phase change storage system	*	_	•	- pre	ssuri	ized
UNIT	ΓIII	ELECTRICAL ENERGY STORAGE			9	0	0	9
batter	y,storaged	nceptofbatteries-measuringofbatteryperformance, lensity,energydensity,andsafetyissues.Typesofbat um Battery		lmium	,Zinc M	langa	inese	e di
UNIT	ΓIV	HYDROGEN AND BIOGAS STORAGE	\mathbf{E}		9	0	0	9
	ogenstorag arisons.Sa	ge options–compressed gas–liquid hydrog fety and management of hydrogen and Bio gas st	gen–MetalHydrides,chemical orage- Applications	lStorag	ge,Bioga	ıs	stora	ige-
UNIT	ΓV	ALTERNATE ENERGY STORAGE TE	CHNOLOGIES		9	0	0	9
	neel,Super cations	capacitors,Principles&Methods-Applications,Co	mpressedairEnergystorage,C	oncept	ofHybr	idSto	rage	; —
				Total	(45L) =	45	Per	iods

REF	TERENCE BOOKS:							
1	1 IbrahimDincerandMark A.Rosen, ThermalEnergyStorageSystems and Applications, JohnWiley&Sons2002							
2	JamesLarminieandAndrewDicks,FuelcellsystemsExplained,Wileypublications,2003							
3	LuisaF.Cabeza,AdvancesinThermalEnergyStorageSystems:Methodsand Applications,ElsevierWoodheadPublishing,2015							
4	RobertHuggins,EnergyStorage:Fundamentals,MaterialsandApplications,2ndedition, Springer,2015							
5	Ru-shiliu,Leizhang,Xueliangsun,electrochemicaltechnologiesforenergystorageand conversion,Wileypublications,2012							

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:					
CO1	Identify the energy storage technologies for suitable applications	Analyze				
CO2	Analyze the energy storage systems	Analyze				
CO3	Recognize the concept sand types of batteries	Understand				
CO4	Diagnose the principle of operations of Hydrogen and Bio gas storage	Understand				
CO5	Analyze the concepts of Fly wheel and compressed energy storage systems	Analyze				

COURSE ARTICULATION MATRIX COs/POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 PO9 PO10 PO11 PSO1 PSO₂ PSO3 **CO1 CO2 CO3 CO4 CO5** 2.6 2.2 0.8 0.8 0.6 0.6 0.6 0.4 0.4 0.4 0.2 0.0 1.4 0.6 Avg

22ME	CHO106	SOLAR POWER I	PLANTS					
			CATEGORY	PE	Cre	dit		3
			Hours/Week	L	Т	P	Т	Ή
			Hours, week	3	0	0		3
COUR	RSE OBJ	ECTIVES		1	·	. I	<u> </u>	
1	Toexp	lainconceptofvariouspowercyclesinvolvedint	hesolarpowerplants					
2	To lea	rn and study the solar adiation and various so	lar power plants					
3	To out	line the variety of solar systems used to colle	ct solar energy					
4	To lea	rn electrical performance of PV power plants						
5	To sur	nmarize basic economics of solar power plan	ts					
UNIT	ΓΙ	INTRODUCTION			9	0	0	9
Power	rPlantSce	nario-Classification,BasicPrinciplesandFeatur	res-Comparisonandselection Cr	iteria				
UNIT	ГІІ	SOLARPOWERCYCLES			9	0	0	9
Vapoi	urcycles-	Organiccycles-CombinedCycles-BinaryCycl	es-StirlingCycle-BraytonCycle	e– Ericss	on Cy	cle		
UNIT	ΓIII	SOLAR THERMAL POWER PLANT	TS .		9	0	0	9
		eiver, Energy Transfer Power cycles-Tower, eys – Hybrid Systems	Trough and Dish Systems- Co	oncentra	ting D	Dish S	ystei	ns -
UNIT	ΓIV	SOLAR PV POWER PLANTS			9	0	0	9
		PowerProgrammes-PhotovoltaicPowerSyste Systems - Grid-Connected Systems –Electric		Storage -	Powe	er Elec	tron	ics -
UNI	ΓV	ECONOMICS OF POWER PLANTS			9	0	0	9
		ing power tariff –Simple Methods to Calcula allysis for the Selection of Alternative Decision			t - Pa	yback	Peri	od -
				Total(45L):	45P	erio	ds

REF	ERENCE BOOKS:
1	Duffie, J.A., and Beckman, W.A. Solar Energy Thermal Process, John Wiley and Sons, NewYork,2006
2	Kosuke Kurokawa (Ed.), Eergyfrom the Desert –Feasibilityofverylarge-scale photovoltaicpowergenerationsystems,JamesandJames2003
3	SukhatmeS.P.,SolarEnergy,TataMcGrawHillsPvtCo.,3 rd Edition,2008
4	C.J.Winter, R.L.Sizmann, L.L.Vant-Hull, SolarPowerPlants, Springer-Verlag Berlinand Heidelberg GmbH&Co.K,2001

	URSE OUTCOMES:	Bloom Taxonomy Mapped
Upon	completion of this course, the students will be able to:	Mappeu
CO1	Describe the concept of various power cycles involved in the solar power plants were learnt when the concept of the concept	Understand
CO2	Analyze different cycle for solar power generation	Analyze
CO3	Describe the construction and working of components olar thermal power plant	Understand
CO4	Explain PV system and its Integration	Understand
CO5	Fix power tariff and analyze economical aspects of power plant	Analyze

COURSE ARTICULATION MATRIX COs/POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 PO9 PO10 PO11 PSO1 PSO₂ PSO3 **CO1 CO2 CO3 CO4 CO5** 2.4 1.6 0.6 0.6 1.2 0.4 0.6 0.2 1.4 0.8 Avg

	HO107	MATERIALS FOR SOLAR DEVICES									
COURSE OBJECTIVES 1 To comprehend the materials that has been implicated in various forms of solar energy source 2 To educate the structure-property relationship and appreciate enovel developments in the ma 3 To explain the concept and the diverse materials used for solar devices 4 To explicate in depth knowledge of about solar cells, thermal energy storage and electrical endings to gather idea of system balance and analysis with reference toitscost UNITI MATERIALSFORSOLAR COLLECTORS Collector Materials for Low, Medium and High Temperature Applications-Glazing Materials, O Absorber Coatings, Insulations, Use of Plastics-Reliability and Durability of Solar Collectors Degradation of Low- Cost Solar Collectors UNIT II MATERIALS FOR SOLAR CELLS Crystalline Structure – Fundamental Principles of Energy Bands—Types of Semiconductors – Doping impuritieson energy levels—Structure of Silicon solar cell—Fabrication and Optimization of solar cellicon solar cells UNIT III NOVEL AND THIN FILM SOLAR CELLS											
			/XX/ 1	L	Т	P	Т	Н			
		Hours	s/Week	3	0	0		3			
COUR	SE OBJ	ECTIVES	•								
1	To cor	nprehend the materials that has been implicated in various forms of	solar energy	source	es and	its s	tora	ges			
2	To edu	he mat	erials								
3	To exp										
4	To exp	plicate in depth knowledge of about solar cells, thermal energy storage	ge and electi	rical en	ergy	stora	ges				
5	To gat	her idea of system balance and analysis with reference toitscost									
UNIT	ľ	MATERIALSFORSOLAR COLLECTORS			9	0	0	9			
Degrae UNIT	dation of	Low- Cost Solar Collectors			9	0	0				
	mme buu	licture – Fundamental Principles of Energy Bands–Types of Semicor	nductors – D	Ooping	_	Ů		_			
impuri	itieson en	nergy levels—Structure of Silicon solar cell-Fabrication and Optim			and ir	ıflue	nce	of			
impuri silicon	itieson en solar cel	nergy levels—Structure of Silicon solar cell–Fabrication and Optimils			and ir	ıflue	nce				
impuri silicon UNIT Cadmi	itieson en solar cel TIII	nergy levels—Structure of Silicon solar cell–Fabrication and Optimils	stalline, Pol	ycrysta	and in all sells— A	onflue Amor	nce pho	of us			
impuri silicon UNIT	itieson en a solar cel TIII ium Tella Junction	nergy levels—Structure of Silicon solar cell–Fabrication and Optimils NOVEL AND THIN FILM SOLAR CELLS uride, Galium-Arsenic, GaInP/GaAs/Ge-Thin Film, Single Crys	stalline, Pol	ycrysta	and in all sells— A	onflue Amor	nce pho	of us			
impuri silicon UNIT Cadmi Multi . UNIT	TIII ium Telli Junction TIV nal Storag	NOVEL AND THIN FILM SOLAR CELLS uride, Galium-Arsenic, GaInP/GaAs/Ge-Thin Film, Single Crystand Tandem Junction Solar Cells – Conversion Efficiency of Solar Cells – Center Cente	stalline, Pol Cells-Organ	ycrysta ic solar	and in ells— A	o Mate	nce pho orial orial	of us 9			
impuri silicon UNIT Cadmi Multi UNIT Therm Rechar	itieson er a solar cel c III ium Telli Junction a c IV nal Storag rgeable itors.	NOVEL AND THIN FILM SOLAR CELLS uride, Galium-Arsenic, GaInP/GaAs/Ge-Thin Film, Single Crystand Tandem Junction Solar Cells – Conversion Efficiency of Solar Center of Solar	stalline, Pol Cells-Organ	ycrysta ic solar	and in ells— A	o Mate	nce pho orial orial	of us			
UNIT Cadmi Multi UNIT Therm Rechar Capaci UNIT Functi Wires,	itieson en solar cel itim Tellium Tellium Tellium Tellium Storage rgeable itors. V onal requirements of V	NOVEL AND THIN FILM SOLAR CELLS uride, Galium-Arsenic, GaInP/GaAs/Ge-Thin Film, Single Crystand Tandem Junction Solar Cells – Conversion Efficiency of Solar Center Storage Concepts-Materials for Sensible and Latent Heat Energy Storage Batteries—Types, Operating range, Comparison and suitability	stalline, Pol Cells—Organ age. Chemic for vario	ycrysta ic solar cal storous ap	and irells— A 9 alline r cells 9 rage (plicate)	o Material O Conceions-	nce pho o erial o epts Sup	of us			

REF	ERENCE BOOKS:
1	Ibrahim Dincer and Marc A Rosan, Thermal Energy Storage: Systems and Applications, John Wiley, 2003.
2	Sukhatme and Nayak, Solar Energy: Principles of Thermal Collection & Storage, Tata McGrawHill, 2008
3	Nelson, J, The Physics of Solar Cells, Imperial College Press, 2003
4	Jef Poortmans and VladimirArkhipov, Thin Film Solar Cells, JohnWiley and Sons,2008.
5	ThomasMarkvart, SolarElectricity, JohnWiley and Sons,2007

	Upon completion of this course, the students will be able to: Describethefundamentalprinciplesofmaterialsbestsuitedformakingsolarcollectors, their	Bloom Taxonomy Mapped
COI Describethefundamentalprinciplesofmaterialsbestsuitedform reliability, characteristics and possibility of using plastics.		Understand
CO2	Explorethematerialsforsolarcells, principles, doping and fabrication and optimizations of solar cells.	Analyze

CO3	Explorethenovelmaterialsforthefabricationofsolarcell,theirefficiencyandorganic solar cells.	Analyze
CO4	Explain the concept and the diverse materials used for solar energy devices for diverse applications.	Understand
CO5	Describetherequirementsofsystembalanceandanalysiswithreferencetoitscost.	Understand

COURSE A	ARTI	CUL	ATIC	ON M	ATR	IX									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	1	0	0	0	0	1	0	0	0	0	1	1	1
CO2	3	2	1	0	0	0	1	0	0	0	0	0	1	1	2
CO3	2	3	0	0	1	0	0	0	0	0	0	0	2	2	2
CO4	2	1	0	0	2	1	0	0	1	0	0	0	1	1	1
CO5	3	2	0	1	0	0	1	0	0	0	0	1	1	1	2
Avg	2.6	2	1	1	1.5	1	1	1	1	0	0	1	1.2	1.2	1.6
	•	•	3/2	2/1 - ir	dicate	s strei	ngth of	f correla	ation (3	– high, 2	- medium	, 1- low)			

***	ЕНО108	DESIGN OF SOLAR AND WIND SYSTEMS						
	Y PE	Cre	dit		3			
			L	Т	P	T :		
		Hours/Week	3	0	0		3	
UF	RSE OBJ	IECTIVES	<u> </u>			1	_	
1	To learn	and study the radiation principles with respective solar energy estimation.					_	
To learn and study the radiation principles with respective solar energy estimation. TounderstandPVtechnologyprinciplesandtechniquesofvarioussolarcells/materialsforenergy con								
3								
4								
5	To learn	and study the radiation principles with respective solar energy estimation.						
UN	ITI	SOLAR RADIATION AND COLLECTORS		9	0	0	Ī	
Prin	nciple of v	SOLAR THERMAL TECHNOLOGIES working, types, design and operation of-Solar heating and cooling systems—	Therma	1 Eno	rove	tora	•	
		lar Desalination – Solar cooker: domestic, community – Solar Pond – Solar dry		ii Elle	igy s		_	
UN	IT III	lar Desalination – Solar cooker: domestic, community – Solar Pond – Solar dry SOLAR PV SYSTEM DESIGN		9	0	0	Į	
Sola	ar cells - cepts-PVs	· · · · · · · · · · · · · · · · · · ·	ing. -solar o	9	0	0 desig	<u> </u>	
Sola con- cent	ar cells - cepts-PVs	SOLAR PV SYSTEM DESIGN p-njunction- Solar cell array system analysis and performance prediction systemdesign-designprocessandoptimization—detailedarraydesign-storageautone	ing. -solar o omy-vo	9	0	0 desig	9	
Sola con- cent UN Wir turb	ar cells - cepts-PVs tralized ar ITT IV and Energy bines, Atm	p-njunction- Solar cell array system analysis and performance prediction systemdesign-designprocessandoptimization-detailedarraydesign-storageautomed decentralized SPV systems – hybrid and grid connected system.	solar comy-vo	9 cell ar ltage	orray or regular of the control of t	0 designation 0		
Sola con- cent UN Wir turb Betz	ar cells - cepts-PVs tralized ar ITT IV and Energy bines, Atm	p-njunction- Solar cell array system analysis and performance prediction systemdesign-designprocessandoptimization—detailedarraydesign-storageautoned decentralized SPV systems — hybrid and grid connected system. WIND ENERGY FUNDAMENTALS AND WIND MEASUREME Basics, Wind Speed sand scales, Terrain, Roughness, Wind Mechanics, Power cospheric Boundary Layers, Instrumentation for wind measurements, wind decentralized systems.	solar comy-vo	9 cell ar ltage	orray or regular of the control of t	0 designation 0)))	

REF	ERENCE BOOKS:
1	Sukhatme S.P., Nayak.J.P, 'SolarEnergy – Principle of Thermal Storage and collection', TataMcGrawHill, 2008.
2	SolarEnergyInternational, "Photovoltaic – Designand InstallationManual" –New SocietyPublishers,2006.
3	DuffieA.andBeckannW.A., "SolarEngineeringofThermalProcesses, JohnWiley, 1991.
4	JohnDSorensenandJensNSorensen, "WindEnergySystems", WoodheadPublishing

	SE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Classify and describe solar radiation and collectors.	Understand
CO2	Describe the principle and design the solar heating, cooling and other solar applications.	Understand
соз	Explain the principle, working, design optimization of PV system for different applications.	Understand
CO4	Describe the basics and measurements of wind energy.	Understand
CO5	Explain the aerodynamic constructional details of wind turbine.	Understand

COURSE A	ARTI	CUL	ATIC	ON M	ATR	IX									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	1	0	0	0	0	0	0	0	0	0	3	1	0
CO2	3	1	2	1	0	0	0	0	0	0	0	0	3	2	0
CO3	3	2	2	0	1	0	0	0	0	1	0	0	3	2	2
CO4	3	2	0	1	0	1	0	0	0	0	0	0	3	2	0
CO5	3	2	0	0	1	1	0	0	0	0	0	0	3	2	0
Avg	3	1.8	1	0.6	0.5	0.4	0	0	0	0.2	0	0	3	1.8	0.4
			3/2	/1 - in	dicate	s strer	ngth of	correla	ation (3	– high, 2	- medium	n, 1- low)			

	HO109	FIRE ENGINEERING AND EXPLOSION CONTROL	ı								
	PE	Cree	lit	3							
		11 // // // // // // // // // // //	1.	L	Т	P	Т	Ή			
		Hours/We	Hours/Week 3					3			
COURS	SE OBJ	ECTIVES		•			,				
1 7	Founders	standandlearnthefundamentalsoffire, explosion and theory of combustion.									
2	To know various classes of fires & types of fire extinguishers										
3 7	Γo under	estand and learn various fire protection systems, components and their w	orking								
4 7	Γo under	estand the various fire-resistant materials and to design fire protection of	buildi	ng							
5 7	Γo under	estand the principles of explosion protection systems									
UNITI	[FIREANDEXPLOSIONS			9	0	0				
		FIRE PREVENTION AND PROTECTION			9	0	0				
UNIT Sources		FIRE PREVENTION AND PROTECTION ition— fire triangle — principles of fire extinguishing — active and pas	sive fi	re pro				s			
		offires— A,B, C,D,E –types of fire extinguishers— fire stoppers— hydra m generators – escape from fire rescue operations—fire drills—notice- fire				fire a	aları	n			
UNIT	III	FIRE PREVENTION AND PROTECTION			9	0	0				
	tions, re	unts-standpipes—specialfiresuppressionsystemslikedelugeandemulsifier, se liability, maintenance, evaluation and standards—alarmand detection sy am system— smoke venting-firefighting systems.									
	IV	UNIT IV BUILDING FIRE SAFETY						l			
CO2sys		DOLLDING FIRE SAFETT			9	0		L			
CO2sys UNIT Objective structure		ire safe building design, Fire load, fire resistant material and fire testi- rity–concept of egress design–with calculations-fire certificates–fire safe			l fire	prote					
CO2sys UNIT Objective structur	al integr gs–snool	ire safe building design, Fire load, fire resistant material and fire testi- rity–concept of egress design–with calculations-fire certificates–fire safe			l fire	prote					

REFEI	RENCE BOOKS:									
1	Gupta,R.S., "HandBookofFire Technology" OrientLongman, Bombay 1977.									
2	"AccidentPreventionmanualforindustrialoperations" N.S.C., Chicago, 1982.									
3	DinkoTuhtar, "Fireandexplosionprotection".									
4	"DavisDanieletal,"HandBookoffiretechnology".									
5	FirefightershazardousmaterialsreferencebookFirePreventioninFactories",anNostrandReinHold,New York,1991.									

	SE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Describe the fundamentals of fire, explosion and theory of combustion.	Understand
CO2	Classify the fire, class of fire and equipment for fire extinguishing.	Understand
CO3	Explain various industrial fire protection systems components and their working.	Understand
CO4	Design the building with fire protection and concepts of their design.	Create
CO5	Describe the explosion protection system for various application.	Understand

COURSE .	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	0	1	0	1	0	0	0	0	0	0	2	0	0
CO2	3	2	0	0	0	1	2	0	0	0	0	0	2	0	0
CO3	3	2	0	1	2	1	2	0	0	0	0	0	2	0	0
CO4	2	1	3	2	0	1	2	0	0	0	1	0	2	0	0
CO5	3	2	0	1	2	2	1	0	0	0	1	0	2	0	0
Avg	2.8	1.8	3	1.25	2	1.2	1.75	0	0	0	1	1	2	0	0
	•	•	3/2	$\sqrt{1-ir}$	dicate	s strei	ngth of	correla	ation (3	- high, 2	2- medium	n, 1- low)	•	•	

22MEHO11	ENERGY MANAGEMENT AND BENEFITS											
		CATEGORY	PE	Cred	lit		3					
			L	T	P	T	H					
		Hours/Week	3	0	0		3					
COURSE O	BJECTIVES	-	II.			ı						
1 To cre	ate a warenesson the energy scenario of India wit	h respect to world										
2 To lea	To learn the methodology adopted for an energy audit											
3 To ap	preciate the concepts adopted in project management	ent										
4 Tostu	dythedifferenttechniquesadoptedforfinancialappra	isalofaproject										
5 To Co	mprehend the impact of energy on environment											
UNITI	ENERGYSCENARIO			9	0	0	9					
energy subst	t-need-types- methodology- barriers-analysis of itution-billing parameters in TANGEDCO-demand targeting- CUSUM energy labeling.											
UNIT III	PROJECT MANAGEMENT			9	0	0	9					
Definition as	Elements of Project Management- Project Managed Scope, Technical Design, Financing, Contract Performance Monitoring.											
UNIT IV	FINANCIAL MANAGEMENT			9	0	0	9					
	appraisal for energy conservation projects - Festment,Netpresentvalue,Internalrateofreturn-Cash											
UNIT V	ENERGY AND ENVIRONMENT			9	0	0	9					
Concerns- U Parties (COF	effect and the carbon cycle - current evidence and United Nations Frame work Convention on Clin (P), Emissions trading (ET), Joint Implementation (PCF), sustainable development.	mate Change (UNFCC),Kyoto l	Protoco	ol, Co	onfer	ence	e of					
		T-4-1	(45L) _ 4	5 Da		1					

REFE	RENCE BOOKS:										
1	Energy Manager Training Manual (4Volumes) available at http://www.em- ea.org/gbook1.asp, a website administered by Bureau of Energy Efficiency (BEE), a statutory body under Ministry of Power, Government ofIndia.2004.										
2	L.C.Witte, P.S.Schmidt, D.R.Brown, "Industrial Energy Management and Utilisation" Hemisphere Publ, Washing ton, 1988.										
3	W.C.turner, "EnergyManagementHandbook" Wiley, New York, 1982.										
4	W.R.MurphyandG.McKay"EnergyManagement"Butterworths,London1987.										
5	Eastop.T.D&Croft D.R,Energy Efficiency for Engineers andTechnologists,.LogmanScientific &Technical,ISBN-0-582-03184,1990.										

	SE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped					
CO1	CO1 Recognize the importance of energy conservation and suggest measures for improving percapita energy consumption.						
CO2	Analyses the energy sharing and cost sharing pattern of fuel susedin industries.	Analyze					
CO3	Apply Gantt Chart, CP M and PERT in energy conservation projects.	Apply					
CO4	Evaluate the techno-economics of a project adopting discounting and non-discounting cash flow techniques.	Evaluate					
CO5	Assess the sources of additional revenue generation for energy conservation projects adopting	Evaluate					

COURSE A	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	1	1	0	1	0	0	0	1	1	0	0	2	2
CO2	3	2	0	0	0	1	0	0	0	0	0	2	0	2	0
CO3	3	1	1	1	0	1	0	0	0	0	0	0	0	2	3
CO4	3	2	0	0	0	0	1	0	0	0	0	1	0	0	2
CO5	2	1	0	0	1	2	1	0	0	0	0	0	0	0	0
Avg	2.8	1.6	1	1	1	1.25	1	0	1	1	1	1.5	0	2	0
	•	•	3/2/	1 – in	dicates	stren	gth of	correla	tion (3 -	high, 2	- medium	, 1- low)		•	

VERTICAL 2 - COMPUTATIONAL ENGINEERING

	EHO201	NUMERICAL METHODS IN MECHANICAL ENGINEERI	NG				
REF	REQUISI	TES CATEG	ORY	PE	Cre	edit	C
				L	Т	P	TI
		Hours/V	Week	3	0	0	3
COU	RSE OBJ	ECTIVES:			•		
1.		mpletion of this course, the students will understand and systematize numeric ifferential equations governing the physics of mechanical engineering problem		on tech	nique	es for	the
2.	Numeric would ot	al Methods use computers to solve problems by step-wise, repeated and iteratherwise be tedious or unsolvable by hand-calculations.	ntive solu	tion m	ethod	ls, wh	ich
3.	This cou	urse is designed to give an overview of numerical methods of interest ts.	to scienti	ists an	ıd me	echani	ical
UNI	TI	ERRORS		9	0	0	9
Meth		ngle root, multiple roots, Iterative method for Non-linear equations - Ro to TWO Iterations. LINEAR ALGEBRAIC EQUATION	ots of p	_			
		ic Equation - Gauss Elimination Method. Pitfalls and improving techniques					od,
Gaus regre	ss-Jacobi a	ic Equation - Gauss Elimination Method. Pitfalls and improving techniques and Gauss-Seidel Iteration method. Curve Fitting & Interpolation- Least abolic regression - Interpolation-Interpolating polynomial, Lagrange's interpolation-	Square F	compo Regres	sition sion -	meth – Lin	od, lear
Gaus regre Diffe	ss-Jacobi a ession, Para	ic Equation - Gauss Elimination Method. Pitfalls and improving techniques and Gauss-Seidel Iteration method. Curve Fitting & Interpolation- Least abolic regression - Interpolation-Interpolating polynomial, Lagrange's interpolation-	Square F	compo Regres	sition sion -	meth – Lin	nod, near ded
Gaus regree Diffe UNI Num Integ	ess-Jacobi a ession, Para erence Forn TT III derical Differration of 1	ic Equation - Gauss Elimination Method. Pitfalls and improving techniques and Gauss-Seidel Iteration method. Curve Fitting & Interpolation- Least abolic regression - Interpolation-Interpolating polynomial, Lagrange's interpolation and Interpolation and Integration - Newton-Cote's Integration of equation: Trapez Equation: Gauss Quadrature methods Numerical differentiation: For Equala, Central difference Formula, Backward difference Formula, - For une	Square Foolating probability solidal ruliqually spa	compo Regres polyno 9 e, Simaced I	sition sion omial, omial, omial, pson'	meth Lir Divi	ood, near ded 9 es -
Gaus regree Diffe UNI Num Integ diffe diffe	ession, Para erence Form TT III perical Diffe gration of 1 rence Form	ic Equation - Gauss Elimination Method. Pitfalls and improving techniques and Gauss-Seidel Iteration method. Curve Fitting & Interpolation- Least abolic regression - Interpolation-Interpolating polynomial, Lagrange's interpolation and Interpolation and Integration - Newton-Cote's Integration of equation: Trapez Equation: Gauss Quadrature methods Numerical differentiation: For Equala, Central difference Formula, Backward difference Formula, - For une	Square Foolating probability solidal ruliqually spa	compo Regres polyno 9 e, Simaced I	sition sion omial, omial, omial, pson'	meth Lir Divi	od, near ded 9
Cause regree Diffee UNI Num Integ diffee UNI Ordinath	ass-Jacobi a ession, Para erence Form TIH derical Differration of 1 arence Form rence Form TIV nary Differ	ic Equation - Gauss Elimination Method. Pitfalls and improving techniques and Gauss-Seidel Iteration method. Curve Fitting & Interpolation- Least abolic regression - Interpolation—Interpolating polynomial, Lagrange's interpolation NUMERICAL DIFFERENTIATION AND INTEGRATION erentiation and Integration - Newton-Cote's Integration of equation: Trapez Equation: Gauss Quadrature methods Numerical differentiation: For Equala, Central difference Formula, Backward difference Formula, - For unequala.	Square Foolating probability spingly s	ecompo Regres polyno 9 e, Simaced I paced I	sition sion omial, 0 pson' Data: Data:	meth-Lir Divident of the control of	9 9 es - rard ded
Gaus regree Diffe UNI Num Integ diffe diffe UNI Ordineth Powe	ass-Jacobi a ession, Para erence Form TIH derical Difference Form rence Form TIV nary Difference Found and Difference Form TO IV	ic Equation - Gauss Elimination Method. Pitfalls and improving techniques and Gauss-Seidel Iteration method. Curve Fitting & Interpolation- Least abolic regression - Interpolation—Interpolating polynomial, Lagrange's interpolation and Interpolation and Integration - Newton-Cote's Integration of equation: Trapez Equation: Gauss Quadrature methods Numerical differentiation: For Equala, Central difference Formula, Backward difference Formula, - For unequala. ORDINARY DIFFERENTIAL EQUATION rential Equation - Taylor's series method, Picard's Method, Euler's Method	Square Foolating probability spingly s	ecompo Regres polyno 9 e, Simaced I paced I	sition sion omial, 0 pson' Data: Data:	meth-Lir Divident of the control of	od, aear ded 9 9 rder generated by the second of the s
Gaus regree Diffee UNI Num Integ diffee UNI Ordi meth Powe UNI Parti	ass-Jacobi a ession, Para erence Form TIII derical Difference Form rence Form TIV nary Difference Abounder method. TIV al Difference Son's Equa	ic Equation - Gauss Elimination Method. Pitfalls and improving techniques and Gauss-Seidel Iteration method. Curve Fitting & Interpolation- Least abolic regression - Interpolation—Interpolating polynomial, Lagrange's interpolation—Interpolation—Interpolating polynomial, Lagrange's interpolation—Interpolation—Interpolating polynomial, Lagrange's interpolation—Interpolati	Square Foolating probability spin qually spin qually spin hod, Rungen value od to S	ecompo Regres polyno 9 e, Simaced I baced I page-Ku e prob	sition sion sion omial, Onpson' Data: Data: Ontta 4 blem b	meth-Lir Divide O Control	od, near ded 9 9 rder on 9 and

TEXT B	EXT BOOKS:											
1.	B. S. Grewal and J. S. Grewal, "Numerical methods in Engineering and Science," 6 th Edition, Khanna publishers, New Delhi, 2004.											
2.	D. G. Luenberger, "Linear and Nonlinear Programming," Springer, 3rd Edition, 2008.											
REFER	RENCES:											
1.	K. E. Atkinson, "An Introduction to Numerical Analysis," Wiley, 2nd Edition, 1989.											
2.	S. D. Conte and C. de Boor, Elementary Numerical Analysis, Third Edition, Tata McGraw-Hill Education, 2005.											

3.	F.B. Hildebrand, Introduction to Numerical Analysis, Second (Revised) Edition, Courier Dover Publications, 1987.
4.	E. Kreyszig, Advanced Engineering Mathematics, Tenth Ed., John Wiley and Sons, 2010
5.	R. L. Burden and J. D. Faires, Numerical Analysis, 9th Edition (second Indian Reprint 2012), Brooks/Cole, 2011.
6.	L.N. Trefethen, David Bau III, Numerical Linear Algebra, SIAM, 1997.
7.	A.Quarteroni, R. Sacco, and F. Saleri. Numerical Mathematics, Springer-Verlag, New York, 2000.

COUR	SE OUTCOMES:	Bloom Taxonomy Mapped					
Upon c	Upon completion of this course, the students will be able to:						
CO1	CO1 Apply various methods to find roots of equations.						
CO2	Implement different methods to solve simultaneous equations and apply the methods of Regression and interpolation.	Apply& Evaluate					
CO3	Implement various numerical methods for differentiation and Integration.	Apply					
CO4	Apply various methods to solve engineering problems with Ordinary differential equations.	Apply					
CO5	Solve Partial differential equations involved in Engineering Problems.	Apply					

COURSE A	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	1	2	1	0	0	0	0	0	0	0	2	1	0
CO2	3	3	1	2	1	0	0	0	0	0	0	0	2	1	0
CO3	3	3	1	2	1	0	0	0	0	0	0	0	2	1	0
CO4	3	3	1	2	1	0	0	0	0	0	0	0	2	1	0
CO5	3	3	1	2	1	0	0	0	0	0	0	0	2	1	0
Avg	3	3	1	2	1	0	0	0	0	0	0	0	2	1	0
				3/2/1	– indi	cates	streng	th of c	orrela	tion (3	– high,	2- medi	um, 1- lo	w)	

22MEHO202	ADVANCED FLUID MECHANICS					
PREREQUISI	TES	CATEGORY	PE	edit	3	
			L	Т	P	TH
		Hours/Week	3	0	0	3
COURSE OBJ	ECTIVES:		I		1	ı
1. Enhanced	understanding of fluid mechanics, including the equations of moti	ion in differential fo	rm and	l turbu	ılence	e.
UNIT I	INTRODUCTION		9	0	0	9
Deformation of	agrangian Description of Fluid Motion, Lines of Flow Visualiza Fluid Elements, Linear and Volumetric Deformation; Perspective tegral Form Stream Function and Velocity Potential.					
UNIT II	VISCOUS FLUID FLOW		9	0	0	9
Reynolds Transcontrol volume	for Inviscid Flow, Bernoulli's Equation, Examples of Bernoulli's sport Theorem Mass and Linear Momentum Conservation, Reyno, Reynolds transport theorem angular momentum conservation, Invier equation, Navier Stokes equation.	olds transport theore	m arbi	trarily	mov	ing
Reynolds Transcontrol volume	sport Theorem Mass and Linear Momentum Conservation, Reyno, Reynolds transport theorem angular momentum conservation, I	olds transport theore	m arbi	trarily	mov	ing
Reynolds Transcontrol volume tensor, Cauchy.	sport Theorem Mass and Linear Momentum Conservation, Reynor, Reynolds transport theorem angular momentum conservation, I Navier equation, Navier Stokes equation.	olds transport theore	m arbi	trarily	mov	ring
Reynolds Transcontrol volume tensor, Cauchy.	sport Theorem Mass and Linear Momentum Conservation, Reyno, Reynolds transport theorem angular momentum conservation, I Navier equation, Navier Stokes equation. FLUID DYNAMICS	olds transport theore	m arbi	trarily	mov	ring
Reynolds Transcontrol volume tensor, Cauchy. UNIT III Lubrication Th UNIT IV Introduction to Boundary Layer	sport Theorem Mass and Linear Momentum Conservation, Reyno, Reynolds transport theorem angular momentum conservation, I Navier equation, Navier Stokes equation. FLUID DYNAMICS eory, Thin Film Dynamics, Stokes Flow past a Sphere.	olds transport theore introduction to tract Wall Velocity Prof	m arbi ion vec 9 files, I	trarily ctor as	o mov	ering ress 9 1 to
Reynolds Transcontrol volume tensor, Cauchy. UNIT III Lubrication Th UNIT IV Introduction to Boundary Layer	sport Theorem Mass and Linear Momentum Conservation, Reynol, Reynolds transport theorem angular momentum conservation, Invarier equation, Navier Stokes equation. FLUID DYNAMICS Beory, Thin Film Dynamics, Stokes Flow past a Sphere. TURBULENCE Turbulence, Statistical Treatment of Turbulence and Near - For Theory, Similarity Solution of Boundary Layer Equation, More	olds transport theore introduction to tract Wall Velocity Prof	m arbi ion vec 9 files, I	trarily ctor as	o mov	ering ress 9 1 to
Reynolds Transcontrol volume tensor, Cauchy. UNIT III Lubrication Th UNIT IV Introduction to Boundary Laye Momentum Int UNIT V Stagnation proposed	sport Theorem Mass and Linear Momentum Conservation, Reynolds, Reynolds transport theorem angular momentum conservation, In Navier equation, Navier Stokes equation. FLUID DYNAMICS Beory, Thin Film Dynamics, Stokes Flow past a Sphere. TURBULENCE Turbulence, Statistical Treatment of Turbulence and Near - 1 Theory, Similarity Solution of Boundary Layer Equation, More 1 Method and Boundary Layer Separation, Potential Flow.	Wall Velocity Prof	m arbi	o trarily ctor a	o movement of movement of the	gress 9 9 1 to a of

TEXT B	EXT BOOKS:						
1.	Rouse, H. (1957), "Advanced Fluid Mechanics", John Wiley & Sons, N York						
2.	Mohanty A.K. (1994), "Fluid Mechanics", Prentice Hall of India, N Delhi						
REFER	REFERENCES:						
1.	Wand D.J., and Harleman D.R. (91964) "Fluid Dynamics", Addison Wesley.						
2.	Schlichting, H.: (1976) "Boundary Layer theory", International Text – Butterworth						
3.	Lamb, H.R. (1945) "Hydrodynamics", Rover Publications						
4.	White, F.M. (1980) "Viscous Fluid Flow", McGraw Hill Pub. Co, N York						
5.	Yalin, M.S.(1971), "Theory of Hydraulic Models", McMillan Co., 1971.						

COUR	COURSE OUTCOMES:						
Upon	Upon completion of this course, the students will be able to:						
CO1	Explain the fundamental concepts of fluid flow.	Understand					
CO2	Apply the Bernoulli to solve problems related to Viscous fluid flow.	Apply					
CO3	Device the concepts of fluid dynamics in various geometry.	Create					
CO4	Depict the turbulence of fluid flow.	Analyze					
CO5	Interpret the knowledge for Compressible Flows in various geometrical configuration.	Evaluate					

COURSE AI	RTIC	ULAT	ΓΙΟΝ	MA	ΓRIX										
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	2	3	0	0	0	0	0	0	0	1	2	2	0
CO2	3	3	2	3	0	0	0	0	0	0	0	1	2	2	0
CO3	3	3	2	3	3	0	0	0	0	0	0	1	2	2	0
CO4	3	3	2	3	0	0	0	0	0	0	0	1	2	2	0
CO5	3	3	2	3	3	0	0	0	0	0	0	1	2	2	0
Avg	3	3	2	3	1.2	0	0	0	0	0	0	1	2	2	0
	•	•	3.	/2/1 -	indic	ates s	trengt	h of co	orrela	tion (3 -	high,	2- medi	um, 1- lo	w)	

22MEF	HO203	FUNDAMENTALS OF BIO-MECHANIO	CS				
RERE	EQUISI	TES	CATEGORY	PE	Cro	edit	C
1.Bas	sic knov	wledge of physics and biology which includes kinetics		L	Т	P	TI
	nematics.		Hours/Week	3	0	0	3
COURS	SE OBJ	IECTIVES:		ı	1		
1.	Explain	the principles of mechanics.					
2.	Discuss	the mechanics of physiological systems.					
3.	Explain	the mechanics of joints.					
4.	Illustrate	e the mathematical models used in the analysis of biomechanical s	ystems				
UNIT	'I	INTRODUCTION TO MECHANICS		9	0	0	9
	ons – Co	on, Kinematics – Link segment models, Force transducers, Fonstitutive equations of Non-viscous fluid, Newtonian Viscous fluid BIO-FLUID MECHANICS				nstitut 0	ive 9
UNII	. 11	DIO-LUID MECHANICS		7	v	U	9
cylinde mechar Stress, Blood Prosthe	er and co mics in s Effect of vessels, etic hear	properties – Density, Viscosity, Compressibility and Surface Terone and plate, Rheological properties of blood, Pressure-flow relationship to the Steady Laminar flow, Turbulent flow, Flow devote pulsatility, Boundary Layer Separation, Structure of blood vess Heart – Cardiac muscle characterization, Native heart valves – Met valve fluid dynamics.	ionship for Non-Ne elopment, Viscous els, Material proper	wtonian and Tu ties an and va	n Fluid rbule d mod alve dy	ds, Fl nt Sh deling ynam	uid eer of ics,
cylinde mechar Stress, Blood Prosthe	er and co nics in s Effect of vessels, etic hear	one and plate, Rheological properties of blood, Pressure-flow relativity traight tube – Steady Laminar flow, Turbulent flow, Flow developments of pulsatility, Boundary Layer Separation, Structure of blood vess Heart – Cardiac muscle characterization, Native heart valves – Met valve fluid dynamics. BIO-SOLID MECHANICS	ionship for Non-Ne elopment, Viscous els, Material proper echanical properties	wtonian and Tu ties an and va	n Fluid orbule d mod alve dy	ds, Fl nt Sh deling ynam	uid eer of ics,
cylinde mechar Stress, Blood Prosthe UNIT Constit circulat materia	er and counics in so, Effect of vessels, etic heart attutive econtion, ela al proper	one and plate, Rheological properties of blood, Pressure-flow relatives traight tube – Steady Laminar flow, Turbulent flow, Flow developed pulsatility, Boundary Layer Separation, Structure of blood vess Heart – Cardiac muscle characterization, Native heart valves – Most valve fluid dynamics. BIO-SOLID MECHANICS quation of viscoelasticity – Maxwell & Voight models, anisot sticity and strength, viscoelastic properties, functional adaptation ties and modeling of Soft Tissues – Cartilage, Tendons and Ligar	ionship for Non-Ne elopment, Viscous els, Material proper echanical properties cropy, Hard Tissues on, Soft Tissues – uments Skeletal Mus	wtonian and Turties and varies and varies 9 $\mathbf{S} - \mathbf{S}$ tructu	n Fluidribule di moci	ds, Fl nt Sh deling ynam 0	uid eer of ics, 9 ood ons,
cylinde mechar Stress, Blood Prosthe UNIT Constit circulat materia Hill's r	er and counics in so, Effect of vessels, etic heart. Itutive ecution, ela al proper models, reconstruction.	one and plate, Rheological properties of blood, Pressure-flow relativistraight tube – Steady Laminar flow, Turbulent flow, Flow develop pulsatility, Boundary Layer Separation, Structure of blood vess Heart – Cardiac muscle characterization, Native heart valves – Mot valve fluid dynamics. BIO-SOLID MECHANICS quation of viscoelasticity – Maxwell & Voight models, anisot asticity and strength, viscoelastic properties, functional adaptation	ionship for Non-Ne elopment, Viscous els, Material proper echanical properties cropy, Hard Tissues on, Soft Tissues – uments Skeletal Mus	wtonian and Turties and varies and varies 9 $\mathbf{S} - \mathbf{S}$ tructu	n Fluidribule di moci	ds, Fl nt Sh deling ynam 0	uid eer of ics, 9 ood ons,
cylinde mechar Stress, Blood y Prosthe UNIT Constit circulat materia Hill's n UNIT Skeleta of joint	er and counics in so, Effect of vessels, etic heart tutive exition, ela al proper models, in the country of the	one and plate, Rheological properties of blood, Pressure-flow relativistic straight tube – Steady Laminar flow, Turbulent flow, Flow develop pulsatility, Boundary Layer Separation, Structure of blood vess Heart – Cardiac muscle characterization, Native heart valves – Met valve fluid dynamics. BIO-SOLID MECHANICS quation of viscoelasticity – Maxwell & Voight models, anisotal stricity and strength, viscoelastic properties, functional adaptation ties and modeling of Soft Tissues – Cartilage, Tendons and Ligamathematical modeling, Bone fracture mechanics, Implants for both	ionship for Non-Ne elopment, Viscous els, Material proper echanical properties cropy, Hard Tissues on, Soft Tissues – uments Skeletal Musne fracture	wtoniar and Tuties an and varies and varies and varies = Structuscle = I	on Fluid ribule de modulive de modulive de modulive de modulive de modulie de	ds, Fl nt Sh deling ynam	uid eer of of ood ons, oon,
cylinde mechar Stress, Blood y Prosthe UNIT Constit circulat materia Hill's r UNIT Skeleta of joint	er and comics in so, Effect of vessels, etic heart of III attutive extended all proper models, to IV all joints, its, Typesial joints,	one and plate, Rheological properties of blood, Pressure-flow relativistic straight tube – Steady Laminar flow, Turbulent flow, Flow develop pulsatility, Boundary Layer Separation, Structure of blood vess Heart – Cardiac muscle characterization, Native heart valves – Most valve fluid dynamics. BIO-SOLID MECHANICS quation of viscoelasticity – Maxwell & Voight models, anisot esticity and strength, viscoelastic properties, functional adaptation tries and modeling of Soft Tissues – Cartilage, Tendons and Ligamathematical modeling, Bone fracture mechanics, Implants for both BIO-MECHANICS OF JOINTS forces and stresses in human joints, Analysis of rigid bodies in equation of joints, Biomechanical analysis of elbow, shoulder, spinal color	ionship for Non-Ne elopment, Viscous els, Material proper echanical properties cropy, Hard Tissues on, Soft Tissues – uments Skeletal Musne fracture	wtoniar and Tuties an and varies and varies and varies = Structuscle = I	on Fluid ribule de modulive de modulive de modulive de modulive de modulie de	ds, Fl nt Sh deling ynam	uid eer of of ood ons, oon,
cylinde mechar Stress, Blood y Prosthe UNIT Constit circulat materia Hill's r UNIT Skeleta of joint synovia UNIT Introdu disorde	er and comics in so, Effect of vessels, etic heart of III attutive extended all proper models, to IV all joints, its, Typesial joints, to V uction to ers, Ergo	one and plate, Rheological properties of blood, Pressure-flow relativistic straight tube – Steady Laminar flow, Turbulent flow, Flow develop pulsatility, Boundary Layer Separation, Structure of blood vess Heart – Cardiac muscle characterization, Native heart valves – Met valve fluid dynamics. BIO-SOLID MECHANICS quation of viscoelasticity – Maxwell & Voight models, anisot esticity and strength, viscoelastic properties, functional adaptation ties and modeling of Soft Tissues – Cartilage, Tendons and Ligar mathematical modeling, Bone fracture mechanics, Implants for both BIO-MECHANICS OF JOINTS forces and stresses in human joints, Analysis of rigid bodies in equation of soft joints, Biomechanical analysis of elbow, shoulder, spinal columns of gait analysis, Motion analysis using video.	ionship for Non-Ne elopment, Viscous els, Material proper echanical properties eropy, Hard Tissues on, Soft Tissues – uments Skeletal Musne fracture uilibrium, Free bodumn, hip, knee and spine; Ergonomica	wtoniar and Tuties and and varies and varies and varies and varies screen I structus screen I g g g g g g g g g g g g g g g g g g	o Fluid Institute of the state	ds, Fl nt Sh deling ynam	y ood ons, oon, 9 ure of
cylinde mechar Stress, Blood y Prosthe UNIT Constit circulat materia Hill's r UNIT Skeleta of joint synovia UNIT Introdu disorde	er and comics in so, Effect of vessels, etic heart of III attutive extended all proper models, to IV all joints, its, Typesial joints, to V uction to ers, Ergo	one and plate, Rheological properties of blood, Pressure-flow relativistic straight tube – Steady Laminar flow, Turbulent flow, Flow develop pulsatility, Boundary Layer Separation, Structure of blood vess Heart – Cardiac muscle characterization, Native heart valves – Met valve fluid dynamics. BIO-SOLID MECHANICS quation of viscoelasticity – Maxwell & Voight models, anisot esticity and strength, viscoelastic properties, functional adaptation tries and modeling of Soft Tissues – Cartilage, Tendons and Ligar mathematical modeling, Bone fracture mechanics, Implants for both BIO-MECHANICS OF JOINTS forces and stresses in human joints, Analysis of rigid bodies in equation of joints, Biomechanical analysis of elbow, shoulder, spinal color, Gait analysis, Motion analysis using video. MODELING AND ERGONOMICS or Finite Element Analysis, finite element analysis of lumbar anomic principles contributing to good workplace design, Design of	ionship for Non-Ne elopment, Viscous els, Material proper echanical properties echanical properties on, Soft Tissues – aments Skeletal Musine fracture uilibrium, Free bodamn, hip, knee and spine; Ergonomica of a Computer work	wtoniar and Tuties and and varies and varies and varies and varies screen I structus screen I g g g g g g g g g g g g g g g g g g	n Fluidribule d moon and the discourse of the discourse o	ds, Fl nt Sh deling ynam	uid eer of ics, 9 ood ons, oon, 9 ure of
cylinde mechar Stress, Blood y Prosthe UNIT Constit circulat materia Hill's r UNIT Skeleta of joint synovia UNIT Introdudisorde	er and comics in so, Effect of vessels, etic heart of III attutive extended all proper models, to IV all joints, its, Typesial joints, to V uction to ers, Ergo	one and plate, Rheological properties of blood, Pressure-flow relativistic straight tube – Steady Laminar flow, Turbulent flow, Flow develop pulsatility, Boundary Layer Separation, Structure of blood vess Heart – Cardiac muscle characterization, Native heart valves – Met valve fluid dynamics. BIO-SOLID MECHANICS quation of viscoelasticity – Maxwell & Voight models, anisot esticity and strength, viscoelastic properties, functional adaptation tries and modeling of Soft Tissues – Cartilage, Tendons and Ligar mathematical modeling, Bone fracture mechanics, Implants for both BIO-MECHANICS OF JOINTS forces and stresses in human joints, Analysis of rigid bodies in equation of joints, Biomechanical analysis of elbow, shoulder, spinal color, Gait analysis, Motion analysis using video. MODELING AND ERGONOMICS or Finite Element Analysis, finite element analysis of lumbar anomic principles contributing to good workplace design, Design of	ionship for Non-Ne elopment, Viscous els, Material proper echanical properties echanical properties on, Soft Tissues – aments Skeletal Musine fracture uilibrium, Free bodamn, hip, knee and spine; Ergonomica of a Computer work	wtoniar and Tuties and and varies and varies and varies and varies Structus scle – I	n Fluidribule d moon and the discourse of the discourse o	ds, Fl nt Sh deling ynam	uid eer of ics, 9 ood ons, oon, 9 ure of
cylinde mechar Stress, Blood y Prosthe UNIT Constit circulat materia Hill's r UNIT Skeleta of joint synovia UNIT Introdu disorde vibratio	er and comics in so, Effect of vessels, etic heart of III attutive extended all proper models, to IV all joints, its, Typesial joints, to V uction to ers, Ergo	one and plate, Rheological properties of blood, Pressure-flow relatives traight tube — Steady Laminar flow, Turbulent flow, Flow develop pulsatility, Boundary Layer Separation, Structure of blood vess Heart — Cardiac muscle characterization, Native heart valves — Met valve fluid dynamics. BIO-SOLID MECHANICS quation of viscoelasticity — Maxwell & Voight models, anisot esticity and strength, viscoelastic properties, functional adaptation tries and modeling of Soft Tissues — Cartilage, Tendons and Ligamathematical modeling, Bone fracture mechanics, Implants for both BIO-MECHANICS OF JOINTS forces and stresses in human joints, Analysis of rigid bodies in equations of joints, Biomechanical analysis of elbow, shoulder, spinal color, Gait analysis, Motion analysis using video. MODELING AND ERGONOMICS or Finite Element Analysis, finite element analysis of lumbar anomic principles contributing to good workplace design, Design of transmitted vibrations.	ionship for Non-Ne elopment, Viscous els, Material proper echanical properties echanical properties on, Soft Tissues – aments Skeletal Musne fracture uilibrium, Free bodamn, hip, knee and spine; Ergonomica of a Computer work	wtoniar and Tuties and and varies and varies and varies and varies Structus scle – I	n Fluidribule d moon and the discourse of the discourse o	ds, Fl nt Sh deling ynam	9 ood ons, on, 9 ure of
cylinde mechar Stress, Blood y Prosthe UNIT Constit circulat materia Hill's r UNIT Skeleta of joint synovia UNIT Introdu disorde vibratio	er and counics in so, Effect of vessels, etic heart of III attutive exaction, ela al proper models, of IV al joints, the solution to ers, Ergodons, Handal BOOKS	one and plate, Rheological properties of blood, Pressure-flow relatives traight tube — Steady Laminar flow, Turbulent flow, Flow develop pulsatility, Boundary Layer Separation, Structure of blood vess Heart — Cardiac muscle characterization, Native heart valves — Met valve fluid dynamics. BIO-SOLID MECHANICS quation of viscoelasticity — Maxwell & Voight models, anisot esticity and strength, viscoelastic properties, functional adaptation tries and modeling of Soft Tissues — Cartilage, Tendons and Ligamathematical modeling, Bone fracture mechanics, Implants for both BIO-MECHANICS OF JOINTS forces and stresses in human joints, Analysis of rigid bodies in equations of joints, Biomechanical analysis of elbow, shoulder, spinal color, Gait analysis, Motion analysis using video. MODELING AND ERGONOMICS or Finite Element Analysis, finite element analysis of lumbar anomic principles contributing to good workplace design, Design of transmitted vibrations.	ionship for Non-Ne elopment, Viscous els, Material proper echanical properties echanical properties on, Soft Tissues – ments Skeletal Musne fracture uilibrium, Free bodumn, hip, knee and spine; Ergonomica of a Computer work	wtoniar and Tuties and and varies and varies and varies and varies Structus scle – I	n Fluidribule d moon and the discourse of the discourse o	ds, Fl nt Sh deling ynam	uid eer of ics, 9 ood ons, oon, 9 ure of

TEXT B	OOKS:						
1.	Y.C. Fung, "Bio-Mechanics- Mechanical Properties of Tissues", Springer-Verlag, 1998.						
2.	Subrata Pal, "Textbook of Biomechanics", Viva Books Private Limited, 2009.						
REFE	RENCES:						
1.	Krishna B. Chandran, Ajit P. Yoganathan and Stanley E. Rittgers, "Biofluid Mechanics: The Human Circulation", Taylor and Francis, 2007.						
2.	Sheraz S. Malik and Shahbaz S. Malik, "Orthopaedic Biomechanics Made Easy", Cambridge University Press, 2015.						
3.	Jay D. Humphrey, Sherry De Lange, "An Introduction to Biomechanics: Solids and Fluids, Analysis and						

	Design", Springer Science Business Media, 2004.
4.	Shrawan Kumar, "Biomechanics in Ergonomics", Second Edition, CRC Press 2007.
5.	Neil J. Mansfeild, "Human Response to Vibration", CRC Press, 2005.
6.	Carl J. Payton, "Biomechanical Evaluation of movement in sports and Exercise", 2008
7.	NPTEL: Mechanical Engineering - NOC:Biomechanics of Joints and Orthopaedic Implants

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:							
CO1	COI Understand the fundamentals of mechanics and its application in human system.							
CO2	CO2 Understand the principles of bio-fluid dynamics and its application in human system.							
CO3	Understand the fundamentals of bio-solid mechanics.	Understand						
CO4	Analyze the biomechanics of different human joints and also the forces at a skeletal joint for various static and dynamic human activities.	Analyze						
CO5	Give Examples of computational mathematical modelling applied in Bio-mechanics.	Analyze						

COURSE ARTICULATION MATRIX

COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	2	2	0	0	0	0	0	0	1	0	2	2	0
CO2	2	2	2	2	0	0	0	0	0	0	1	0	2	2	0
CO3	2	2	2	2	0	0	0	0	0	0	1	0	2	2	0
CO4	2	2	2	2	0	0	0	0	0	0	1	0	2	2	0
CO5	2	2	2	2	2	0	0	0	0	0	1	0	2	2	0
Avg	2	2	2	2	0.4	0	0	0	0	0	1	0	2	2	0

Mach a good and ex	EQUISI						
a good		TES	CATEGORY	PE	Cre	dit	C
and ex		ng is a mathematical discipline, and students will benefit from		L	T	P	TH
		and in probability, linear algebra and calculus, programming, s essential.	Hours/Week	3	0	0	3
OUR	RSE OBJI	ECTIVES:					
1.	Understa	nd a wide variety of learning algorithms.					
2.	Understa	nd how to evaluate models generated from data.					
3.	Apply the	e algorithms to a real problem.					
4.	Optimize	the models learned and report on the expected accuracy that can	be achieved by a	pplying	the m	odels	
UNIT	ГΙ	INTRODUCTION		9	0	0	9
UNIT	ГII	c and inductive bias- evaluation-cross-validation. CONCEPT LEARNING AND THE GENERAL-TO-S ORDERING concept task, concept learning as search-find S: finding a maximum.		9 oothesis	0	0	9 paces
		e elimination algorithm-remarks on version spaces and candidate				ion s _l	,uces
UNIT	ΓIII	DECISION TREE LEARNING		9	0	0	9
	thm-hypot	cision tree representation-appropriate problems for decision tree hesis space search in decision tree learning-inductive bias in dec					
UNIT	ΓIV	ARTIFICIAL NEURAL NETWORKS		9	0	0	9
netwo	orks and th	iral network representation-appropriate problems for neural nee back propagation algorithm-remarks on the back propagation anced topics in artificial neural networks.					
UNIT	ΓV	LEARNING SYSTEM		9	0	0	9

Probability and Bayes learning, bayes optimal classifier, gibbs algorithm, Naïve bayes classifier, instance-based learning - K nearest neighbour learning - locally weighted regression, Computational learning theory-PAC learning model -Sample complexity-VC Dimension -Ensemble learning, analytical learning-learning with perfect domain theories: prolog –EBG.

REFERI	FERENCES:								
1.	Machine Learning. Tom Mitchell. First Edition, McGraw- Hill, 1997.								
2.	Introduction to Machine Learning Edition 2, by Ethem Alpaydin								
3.	T. Hastie, R. Tibshirani, and J. Friedman. The Elements of Statistical Learning. Springer 2011. (Available for download on the authors' web-page: http://statweb.stanford.edu/~tibs/ElemStat Learn/)								
4.	Kevin P. Murphy. Machine Learning: A Probabilistic Perspective, MIT Press 2012. (Electronic copy available through the Bodleian library.)								
5.	Christopher M. Bishop. Pattern Recognition and Machine Learning, Springer 2007.								
6.	S. Haykin. Neural networks and learning machines. Pearson 2008.								

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:					
CO1	CO1 Have a good understanding of the fundamental issues and challenges of machine learning: data, model selection, model complexity, etc.					
CO2	Have an understanding of the strengths and weaknesses of many popular machine learning approaches.	Understand				
СОЗ	Appreciate the underlying mathematical relationships within and across Machine Learning algorithms and the paradigms of supervised and un-supervised learning.	Understand				
CO4	Be able to design and implement Artificial Neural Networks algorithms in a range of real-world applications.	Create				
CO5	Be able to design and implement various machine learning algorithms in a range of real-world applications.	Create				

COURSE A	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	0	1	3	0	0	0	0	0	0	1	2	2	0
CO2	2	2	0	1	3	0	3	0	0	0	0	1	2	2	0
CO3	2	2	0	1	3	0	0	0	0	0	0	1	2	2	0
CO4	2	2	0	1	3	0	3	0	0	0	0	1	2	2	0
CO5	2	2	0	1	3	0	3	0	0	0	0	1	2	2	0
Avg	2	2	0	1	3	0	1.8	0	0	0	0	1	2	2	0
	3/2/1 – indicates strength of correlation (3 – high, 2- medium, 1- low)														

22MEHO205	DESIGN OPTIMIZATION & DESIGN THEORY					
PREREQUISI	TES CATEGORY	PE	Cro	edit	C	
	TT AND I	L	Т	P	TE	
	Hours/Week	3	0	0	3	
	·	•	•	•	•	
COURSE OBJ	TECTIVES:					
	mary objective of this course is for students to gain knowledge to translate practicals into mathematical optimization problems that can be solved using numerical method					
UNIT I	INTRODUCTION	9	0	0	9	
optimization te	chniques					
UNIT II The technique	DESIGN OPTIMIZATION TECHNIQUE of unconstrained minimization. The golden section, Random, Pattern, and Gradi	9 ent sea	0 arch 1	0 netho	9 ods,	
UNIT II The technique interpolation m	DESIGN OPTIMIZATION TECHNIQUE of unconstrained minimization. The golden section, Random, Pattern, and Gradiethods, and equality and inequality constraints.	ient sea	arch i	netho	ods,	
UNIT II The technique interpolation m UNIT III	DESIGN OPTIMIZATION TECHNIQUE of unconstrained minimization. The golden section, Random, Pattern, and Gradiethods, and equality and inequality constraints. PROGRAMME	ent sea	arch 1	netho	ods,	
UNIT II The technique interpolation m UNIT III Direct methods	DESIGN OPTIMIZATION TECHNIQUE of unconstrained minimization. The golden section, Random, Pattern, and Gradiethods, and equality and inequality constraints.	ent sea	arch 1	netho	ods,	
UNIT II The technique interpolation m UNIT III Direct methods	DESIGN OPTIMIZATION TECHNIQUE of unconstrained minimization. The golden section, Random, Pattern, and Gradiethods, and equality and inequality constraints. PROGRAMME and indirect methods using penalty function, Lagrange multipliers, Geometric programming in the programming of the programming in	ent sea	arch 1	netho	ods,	
UNIT II The technique interpolation multiple interpolation multiple. UNIT III Direct methods programming, surprise to the control of the c	DESIGN OPTIMIZATION TECHNIQUE of unconstrained minimization. The golden section, Random, Pattern, and Gradiethods, and equality and inequality constraints. PROGRAMME and indirect methods using penalty function, Lagrange multipliers, Geometric programming Genetic algorithms	grammi	o o o o o o o o o o o o o o o o o o o	netho	ods, 9 stic	
UNIT II The technique interpolation multiple interpolation multiple. UNIT III Direct methods programming, surprise to the control of the c	pESIGN OPTIMIZATION TECHNIQUE of unconstrained minimization. The golden section, Random, Pattern, and Gradiethods, and equality and inequality constraints. PROGRAMME s and indirect methods using penalty function, Lagrange multipliers, Geometric progrenetic algorithms ENGINEERING APPLICATION pplications, structural-design application axial and transverse loaded members	grammi	o o o o o o o o o o o o o o o o o o o	netho	ods, 9 stic	
UNIT II The technique interpolation m UNIT III Direct methods programming, unit IV Engineering a maximum weig UNIT V	DESIGN OPTIMIZATION TECHNIQUE of unconstrained minimization. The golden section, Random, Pattern, and Gradiethods, and equality and inequality constraints. PROGRAMME and indirect methods using penalty function, Lagrange multipliers, Geometric programment algorithms ENGINEERING APPLICATION pplications, structural-design application axial and transverse loaded members that. Design of shafts and torsion members, design optimization of springs.	grammi 9 for m	o ing, st	o cocha:	ods, 9 stic 9 ost,	

TEXT B	OOKS:
1.	S. S. Rao, Engineering Optimization: Theory and Practice, 4th edition, John Wiley & Sons, 2009. ISBN: 0470183527.
2.	Kalyanmoy Deb, "Optimization for Engineering Design", Prentice Hall of India, New Delhi, 2005
REFER	ENCES:
1.	R.C. Johnson, "Optimum Design of Mechanical Elements", Willey, New York, 1980
2.	Kalyanmoy Deb, "Evolutionary multi-objective optimization, Willey, New York.
3.	S. S. Stricker, "Optimising performance of energy systems" Battelle Press, New York, 1985.
4.	J. S. Arora, "Introduction to Optimum Design", McGraw Hill, New York, 1989.
5.	L.C.W. Dixon, "Non-Linear Optimisation - Theory and Algorithms", Birkhauser, Boston, 1980.
6.	R.J. Duffin, E.L. Peterson and C.Zener "Geometric Programming-Theory and Applications", Willey, New York, 1967.
7.	G.B.Dantzig "Linear Programming and Extensions Princeton University Press", Princeton, N. J., 1963
8.	R. Bellman "Dynamic Programming-Princeton" University Press, Princeton, N.J. 1957.

	SE OUTCOMES: ompletion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Demonstrate an understanding of how design optimization fits into the overall engineering design process.	Create
CO2	Formulate practical engineering design problems as well-posed optimization problems.	Create
CO3	Determine the advantages and disadvantages of applying different optimization techniques for a specific problem.	Analyze
CO4	Model and analyze multi-objective and multi-disciplinary optimization problems.	Analyze

CO	TIDCE	ADTICIT	ATION MATRIX
	UKSE	AKIICUL	A LIUJN WA LKIX

COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	3	3	1	0	0	0	0	0	0	2	2	2	0
CO2	2	2	3	3	1	0	0	0	0	0	0	2	2	2	0
CO3	2	2	2	3	1	0	0	0	0	0	0	2	2	2	0
CO4	2	2	2	3	1	0	0	0	0	0	0	2	2	2	0
Avg	2	2	2.5	3	1	0	0	0	0	0	0	2	2	2	0

PREREQU	ITES	ES CATEGORY PE Credit C					
KEKEQU.	IILS		CATEGORI		T	1	-
			Hours/Week	L	P	TH	
				3	0	0	3
	JECTIVES:						
	elop a thorough understanding of t						
	ity to effectively use the tools of t			nginee	ering	design	1.
	erstand and solve the Finite Eleme		ral problems.				
	elop and understand the dynamic p						
5. To ga	the knowledge of FEM for heat t	ansfer analysis and flow analysis	3	1	1	1	
UNIT I	INTRODUCTION			9	0	0	9
	ns, Linear Elements, Local and Gl ntegration, Nodal degrees of freed						
	ONE DIMENSIONAL DD	DI EMC		0	Λ	Λ	0
UNIT II Structural p. Boundary co and their ac conditions continuity (one dimensional geometrions and their incorporation: El antages and disadvantages. Form d introduction to contact problem and C1 Continuity), interpolations and C1 Continuity), interpolations and C1 Continuity.	try. Formulation of stiffness ma mination method, Penalty Metho ulation for Truss elements, Ca ns. Beams and Frames: Revie n for beam elements and formu	trix, consistent and od. Introduction to have see studies with emw of bending of bulation of FE chara	igher phasis ceams, cterist	order on higlics, F	eleme bound ner or Plane	ents lary der and
Structural p Boundary co and their ac conditions a continuity (space frame involving 1-	blems with one dimensional geomeditions and their incorporation: El antages and disadvantages. Form d introduction to contact problem and C1 Continuity), interpolational examples problems involving elements.	try. Formulation of stiffness mamination method, Penalty Methodulation for Truss elements, Cans. Beams and Frames: Revien for beam elements and formuland calculations. Algorithmic a	trix, consistent and od. Introduction to have see studies with emw of bending of bulation of FE chara	lumpe ligher lighasis peams, cterist ping c	d load order on high ics, F ompu	d vect eleme bound her or Plane tter co	ors. ents lary der and des
UNIT II Structural properties and their acconditions accontinuity (space frame involving 1- UNIT III	blems with one dimensional geomeditions and their incorporation: El antages and disadvantages. Form different to contact problems and C1 Continuity), interpolational examples problems involving elements. TWO DIMENSIONAL PR	try. Formulation of stiffness mamination method, Penalty Method lation for Truss elements, Cans. Beams and Frames: Revien for beam elements and formuland calculations. Algorithmic and DBLEMS	trix, consistent and od. Introduction to have se studies with emw of bending of bulation of FE chara approach for develo	lumpe higher highasis peams, cterist ping c	d load order on high ics, F ompu	d vect eleme bound her on Plane tter co	ors. ents lary rder and des
Structural programme to and their acconditions accontinuity (space frame involving 1-UNIT III Interpolation formulation elements, su	blems with one dimensional geomeditions and their incorporation: El antages and disadvantages. Form d introduction to contact problem and C1 Continuity), interpolational examples problems involving elements.	try. Formulation of stiffness mamination method, Penalty Methodulation for Truss elements, Cans. Beams and Frames: Review of the for beam elements and formulations and calculations. Algorithmic and calculations are parametric problems; Triangular or parametric elements. General	trix, consistent and od. Introduction to have se studies with emw of bending of bulation of FE chara approach for develoon, Concept of Jaco and Quadrilateral econsiderations in fi	lumpe higher aphasis beams, acterist ping c	d load order on high ics, Fompu	d vective elements of the control of	ors. ents lary rder and des
Structural programme to and their acconditions accontinuity (space frame involving 1-UNIT III Interpolation formulation elements, su	blems with one dimensional geomeditions and their incorporation: El antages and disadvantages. Form d introduction to contact problem and C1 Continuity), interpolational examples problems involving elements. TWO DIMENSIONAL PROBLEMS IN TWO DIMENSIONAL P	try. Formulation of stiffness mamination method, Penalty Methodulation for Truss elements, Cans. Beams and Frames: Review of the for beam elements and formulations and calculations. Algorithmic and calculations are parametric problems; Triangular or parametric elements. General	trix, consistent and od. Introduction to have se studies with emw of bending of bulation of FE chara approach for develoon, Concept of Jaco and Quadrilateral econsiderations in fi	lumpe higher aphasis beams, acterist ping c	d load order on high ics, Fompu	d vective elements of the control of	ors. ents lary rder and des
UNIT II Structural p Boundary co and their ac conditions continuity (space frame involving 1- UNIT III Interpolation formulation elements, su of two-dime UNIT IV FE formula Formulation	blems with one dimensional geomeditions and their incorporation: El antages and disadvantages. Form d introduction to contact problem of and C1 Continuity), interpolational examples problems involving elements. TWO DIMENSIONAL PROBLEMS in two dimensions, natural coordinates or plane stress plane strain and axisparametric, Isoparametric and supplements in the control of the cont	try. Formulation of stiffness mamination method, Penalty Methodilation for Truss elements, Cans. Beams and Frames: Review of for beam elements and formulations. Algorithmic and calculations. Algorithmic and telephones are parametric problems; Triangular or parametric elements. General ending elements and shell elements using Lagragian Method, and introduction to the solution	trix, consistent and od. Introduction to have see studies with emw of bending of bulation of FE chara approach for develoon, Concept of Jaco and Quadrilateral econsiderations in fints. Consistent and lucon procedures. Mo	lumper igher uphasis peams, cerist ping community of the properties of the propertie	d load order on high order on high order on high order on high order or on high order order or order or order orde	d vect elementer on order on order on order on order on order on order o	ors. ents lary der and des 9 enent der ysis
Structural p Boundary co and their ac conditions ac continuity (space frame involving 1- UNIT III Interpolation formulation elements, su of two-dime UNIT IV FE formula Formulation	blems with one dimensional geomeditions and their incorporation: El antages and disadvantages. Form d introduction to contact problem and C1 Continuity), interpolational examples problems involving elements. TWO DIMENSIONAL PROBLEMS IN TWO DIMENSIONAL P	try. Formulation of stiffness mamination method, Penalty Methodalation for Truss elements, Cans. Beams and Frames: Review of for beam elements and formuland calculations. Algorithmic and calculations. Algorithmic and test is presentated by the state of	trix, consistent and od. Introduction to have see studies with emw of bending of bulation of FE chara approach for develoon, Concept of Jaco and Quadrilateral econsiderations in fints. Consistent and lucon procedures. Mo	lumper igher uphasis peams, cerist ping community of the properties of the propertie	d load order on high order on high order on high order on high order or on high order order or order or order orde	d vect elementer on order on order on order on order on order on order o	ors. ents lary der and des 9 enent eder ysis
UNIT II Structural p Boundary co and their ac conditions ac continuity (space frame involving 1- UNIT III Interpolation elements, su of two-dime UNIT IV FE formula Formulation damping and UNIT V Finite elem characteristi boundaries.	blems with one dimensional geomeditions and their incorporation: El antages and disadvantages. Form d introduction to contact problems and C1 Continuity), interpolational examples problems involving elements. TWO DIMENSIONAL PROBLEMS INTRODUCTION INTERPOLATION INTERP	try. Formulation of stiffness mamination method, Penalty Methodilation for Truss elements, Cans. Beams and Frames: Review of for beam elements and formulation calculations. Algorithmic and test is problems; Triangular er parametric problems; Triangular er parametric elements. General ending elements and shell elements and introduction to the solution for an analysis, Mode superpositions. A & FLUID MECHANICS seat conduction with convective formulation for 2-D and 3-D hept problems. Finite element applied to the solution of the solution for 2-D and 3-D hept problems. Finite element applied to the solution of the solution for 2-D and 3-D hept problems. Finite element applied to the solution of the solution for 2-D and 3-D hept problems. Finite element applied to the solution of the solution for 2-D and 3-D hept problems. Finite element applied to the solution of the solution of the solution for 2-D and 3-D hept problems. Finite element applied to the solution of the solu	trix, consistent and od. Introduction to have se studies with emw of bending of bulation of FE chara approach for develous. On, Concept of Jaconard Quadrilateral electronsiderations in final considerations in final consistent and lucon procedures. Moston methods and reduce boundaries. Format conduction problem.	lumper igher iphasis peams, cterist ping c 9 bian. lement nite eld delling uction 9 mulatic ems w	d load order son high high high high high high high hig	d vect elementer or	ors. ents lary der and des 9 els, ural s. 9
Structural programments of two-dimes damping and their acconditions accontinuity (space frame involving 1-UNIT III Interpolation elements, sure of two-dimes unit in the structure of two-dimes	blems with one dimensional geomeditions and their incorporation: El antages and disadvantages. Form d introduction to contact problem and C1 Continuity), interpolation and examples problems involving elements. TWO DIMENSIONAL PRofession to dimensions, natural coordination plane stress plane strain and axisparametric, Isoparametric and supsion problems. Introduction plate by DYNAMIC ANALYSIS on in dynamic equations of motion formulation of damping matrices, in the solution for one dimensional and simple numerical problems. Introduction to thermo-elastic contact troduction to thermo-elastic contact and simple numerical problems.	try. Formulation of stiffness mamination method, Penalty Methodilation for Truss elements, Cans. Beams and Frames: Review of for beam elements and formulation calculations. Algorithmic and test is problems; Triangular er parametric problems; Triangular er parametric elements. General ending elements and shell elements and introduction to the solution for an analysis, Mode superpositions. A & FLUID MECHANICS seat conduction with convective formulation for 2-D and 3-D hept problems. Finite element applied to the solution of the solution for 2-D and 3-D hept problems. Finite element applied to the solution of the solution for 2-D and 3-D hept problems. Finite element applied to the solution of the solution for 2-D and 3-D hept problems. Finite element applied to the solution of the solution for 2-D and 3-D hept problems. Finite element applied to the solution of the solution of the solution for 2-D and 3-D hept problems. Finite element applied to the solution of the solu	trix, consistent and od. Introduction to have se studies with emw of bending of bulation of FE charampproach for develoon, Concept of Jacon and Quadrilateral econsiderations in fints. Consistent and luter procedures. Mo ion methods and reduction problematications in potential	lumper igher iphasis peams, cterist ping c 9 bian. lement nite eld delling uction 9 mulatic ems w	d load order son high ics, Formula of technology of techno	d vective elements of the control of	ors. ents lary der and des 9 enent der ysis

REFERE	ENCES:						
1.	K. J. Bathe, Finite Element Procedures, Prentice-Hall of India Private Limited, New Delhi, 1996						
2.	J. C. Simo and T. J. R. Hughes, Computational Inelasticity, Springer-Verlag New York, Inc., New York, 1998						
3.	Cook and Robert Davis etal, "Concepts and Applications of Finite Element Analysis", 4th Edition, John Wiley and Sons, 2001.						
4.	Segerlind L.J, "Applied Finite Element Analysis", 2nd Edition, John Wiley, 1984.						

O. C. Zienkiewicz and R. L. Taylor, Finite Element Method: Volume 2 Solid Mechanics, Fifth Edition,
Butterworth-Heinemann, Oxford.

5.

COUR	SE OUTCOMES:	Bloom Taxonomy
Upon c	ompletion of this course, the students will be able to:	Mapped
CO1	Understand the concept of the finite element method for solving design problems.	Understand
CO2	Formulate and solve manually problems in 1-D structural systems involving bars, trusses, beams and frames.	Apply
CO3	Develop 2-D FE formulations involving triangular, quadrilateral elements, and higher-order elements	Create
CO4	Apply the knowledge of FEM for stress analysis, model analysis, heat transfer analysis and flow analysis	Evaluate
CO5	Apply the knowledge of FEM for heat transfer analysis and flow analysis	Apply

COURSE A	OURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1	3	1	0	0	0	1	1	0	0	0	1	2	0
CO2	3	1	3	3	3	0	0	1	1	0	0	0	0	0	3
CO3	3	1	3	3	2	0	0	1	1	0	0	0	0	0	0
CO4	3	2	3	3	2	0	2	2	1	0	0	0	1	2	0
CO5	3	1	1	1	1	0	0	0	1	0	0	0	1	1	0
Avg	3.0	1.2	2.6	2.2	1.6	0.0	0.4	1.0	1.0	0.0	0.0	0.0	0.6	1.0	0.6
	•		•	3/2/1	l – ind	dicate	s strei	ngth of	corre	lation (3 – higl	n, 2- med	ium, 1- lo	w)	

22MEHO207						
PREREQUISIT	ES	CATEGORY	PE	Cre	Credit	
Knowledge of ur	dergraduate heat transfer and fluid mechanics, basic	II arrag/XVa al-	L	T	P	TH
computational flu	nid dynamics	Hours/Week	3	0	0	3

COURSE OBJECTIVES:

1.

The primary objective of the course is to teach fundamentals of computational method for solving non-linear partial differential equations (PDE) primarily in complex geometry. The emphasis of the course is to teach CFD techniques for solving incompressible and compressible N-S equation in primitive variables, grid generation in complex geometry, transformation of N-S equation in curvilinear coordinate system and introduction to turbulence modelling.

UNIT I INTRODUCTION 9 0 0 9

Brief introduction of boundary layer flow, incompressible and compressible flows, finite difference and finite volume method, example of parabolic and hyperbolic systems and time discretization technique, explicit and implicit methods, upwind and central difference schemes, stability, dissipation and dispersion errors

UNIT II SOLUTION OF SIMULTANEOUS EQUATIONS 9 0 0 9

Point iterative/block iterative methods, Gauss-Seidel iteration (concept of central coefficient and residue, SOR), CGS, Bi-CGSTAB and GMRES (m) matrix solvers, different acceleration techniques.

UNIT III INCOMPRESSIBLE FLOW 9 0 0 9

Higher order upwind schemes: second order convective schemes, QUICK. Solution of NS equations: Solution of incompressible N-S equation (Explicit time stepping, Semi-explicit time stepping). SMAC method for staggered grid: Predictor - Corrector step, discretization of N-S and continuity equations, Pressure correction Poisson's equation, boundary conditions (no-slip, moving wall, slip boundary and inflow conditions), outflow (zero gradient/Orlanski) boundary conditions for unsteady flows, algorithm for the SMAC method, stability considerations for SMAC method.

UNIT IV FDE IN COMPLEX GEOMETRIES 9 0 0 9

Transformation of governing equation in ξ η - plane, transformation of Laplace equation, introduction to geometrical parameters and the accuracy of the solution, basic facts about transformation, grid transformation on complex geometries. N-S equations in transformed plane, matrices and Jacobians

UNIT V COMPRESSIBLE FLOW 9 0 0 9

N-S and energy equations, properties of Euler equation, linearization. Solution of Euler equation: Explicit and implicit treatment such as Lax-Wendroff, MacCormark, Beam and Warming schemes, Upwind schemes for Euler equation: Steger and Warming, Van Leer's flux splitting, Roe's approximate Riemann solver, TVD schemes. Solution of N-S equations: MacCormack, Jameson algorithm in finite volume formulation and transformed coordinate system.

TEXT BOOKS:									
1.	Computational Fluid Flow and Heat Transfer, Second Edition by K. Muralidhar, T. Sundararajan (Narosa), 2011.								
2.	Computational Fluid Dynamics by Chung T. J., Cambridge University Press, 2003.								
3.	Computational Fluid Dynamics by Tapan K. Sengupta, University Press, 2005.								
4.	Numerical Computation of Internal and External Flows by Hirch C., Elesvier 2007.								
REFE	REFERENCES:								
1.	K. J. Bathe, Finite Element Procedures, Prentice-Hall of India Private Limited, New Delhi, 1996								
2.	J. C. Simo and T. J. R. Hughes, Computational Inelasticity, Springer-Verlag New York, Inc., New York, 1998								
3.	Cook and Robert Davis et.al, "Concepts and Applications of Finite Element Analysis", 4th Edition, John Wiley and Sons, 2001.								

4.	Segerlind L.J, "Applied Finite Element Analysis", 2nd Edition, John Wiley, 1984.										
5.	O. C. Zienkiewicz and R. L. Taylor, Finite Element Method: Volume 2 Solid Mechanics, Fifth Edition, Butterworth-Heinemann, Oxford,										

COUR Upon c	Bloom Taxonomy Mapped			
CO1	Understand and be able to numerically solve the incompressible and compressible flows.	Understand		
CO2	Solve computational problems related to iterative methods.	Evaluate		
CO3	Solve the problems related to incompressible fluid flow.	Evaluate		
CO4	Interpret the knowledge, capability of analyzing and solving FDE in complex geometries problem.	Apply		
CO5	Solve the problems related to compressible fluid flow.	Evaluate		

COURSE ARTICULATION MATRIX															
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	1	1	2	0	0	0	0	0	0	0	2	2	0
CO2	2	2	1	3	2	0	0	0	0	0	0	0	2	2	0
CO3	2	2	1	3	2	0	0	0	0	0	0	0	2	2	0
CO4	2	2	1	1	2	0	0	0	0	0	0	0	2	2	0
CO5	2	2	1	3	2	0	0	0	0	0	0	0	2	2	0
Avg	2	2	1	2.2	2	0	0	0	0	0	0	0	2	2	0
	3/2/1 – indicates strength of correlation (3 – high, 2- medium, 1- low)														

22MEHO208	SMART MATERIALS AND STRUCTURES					
PREREQUISITES	CA	ATEGORY	PE	Cre	dit	3
		/XX/ 1	L	T	P	TH
	H	Hours/Week				3
COURSE OBJECTIV	ES:					

UNIT I SMART STRUCTURES

0 0 9

Types of Smart Structures, Potential Feasibility of Smart Structures, Key Elements of Smart Structures, Applications of Smart Structures. Piezoelectric materials, Properties, piezoelectric Constitutive Relations, Depoling and Coersive Field, field strain relation. Hysteresis, Creep and Strain Rate effects, Inchworm Linear Motor. Beam Modeling: Beam Modeling with induced strain Rate effects, Inchworm Linear Motor Beam Modeling with induced strain Actuation-single Actuators, dual Actuators, Pure Extension, Pure Bending harmonic excitation, Bernoulli-Euler beam Model, problems, Piezoelectrical Applications.

applications, the course aims at training students in smart materials and structures application and analysis

UNIT II SHAPE MEMORY ALLOY

0 0

Experimental Phenomenology, Shape Memory Effect, Phase Transformation, Tanaka's Constitutive Model, testing of SMA Wires, Vibration Control through SMA, Multiplexing. Applications Of SMA and Problems. ER and MR Fluids: Mechanisms and properties, Fluid Composition and behavior, The Bingham Plastic and Related Models, Pre-Yield Response. Post-Yield flow applications in Clutches, Dampers and Others.

UNIT III VIBRATION ABSORBERS

0

9

)

9

9

series and Parallel Damped Vibrations (OverView), Active Vibration Absorbers, Fiber Optics, Physical Phenomena, Characteristics, Sensors, Fiber Optics in Crack Detection, applications. Control of Structures: Modeling, Control Strategies and Limitations, Active Structures in Practice. 13Hours

UNIT IV MEMS

9 0 0

Mechanical Properties of MEMS Materials, Scaling of Mechanical Systems, Fundamentals of Theory, The Intrinsic Characteristics of MEMS, Miniaturization, Microelectronics Integration.

UNIT V DEVICES

0 0

Sensors and Actuators, Conductivity of Semiconductors, Crystal Planes and Orientation, (Stress and Strain Relations, Flexural Beam Bending Analysis Under Simple Loading Conditions), Polymers in MEMS, Optical MEMS Applications.

TEXT B	OOKS:
1.	Smart Materials and Structures - M. V. Gandhi and B. So Thompson, Chapman and Hall, London; New York, 1992 (ISBN: 0412370107).
2.	Smart Structures and Materials - B. Culshaw, Artech House, Boston, 1996 (ISBN :0890066817). 3. Smart Structures: Analysis and Design - A. V. Srinivasan, Cambridge University Press, Cambridge; New York, 2001 (ISBN: 0521650267).
REFEI	RENCES:
1.	Electro ceramics: Materials, Properties and Applications - A. J. Moulson and J. M. Herbert. John Wiley &Sons, ISBN: 0471497429
2.	Piezoelectric Sensories: Force, Strain, Pressure, Acceleration and Acoustic Emission Sensors. Materials and Amplifiers, Springer, Berlin; New York, 2002 (ISBN: 3540422595).
3.	Piezoelectric Actuators and Transonic Motors - K. Uchino, Kluwer Academic Publishers, Boston, 1997 (ISBN: 0792398114).
4.	Handbook of Giant Magneto strictive Materials - G. Engdahl, Academic Press, San Diego, Calif.; London, 2000 (ISBN: 012238640X).

Shape Memory Materials - K. Otsuka and C. M. Wayman, Cambridge University Press, Cambridge; New York, 199~ (ISBN: 052144487X).

5.

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:						
CO1	Understand the behavior and applicability of various smart materials	Understand					
CO2	Design simple models for smart structures & materials	Create					
СОЗ	Perform simulations of smart structures & materials application	Analyse					
CO4	Conduct experiments to verify the predictions	Analyze					

COURSE A	ARTI	CUL	ATIO	N MA	ATRI	X									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	1	1	2	0	0	0	0	0	0	0	2	2	0
CO2	2	2	1	1	2	0	0	0	0	0	0	0	2	2	0
CO3	2	2	1	1	2	0	0	0	0	0	0	0	2	2	0
CO4	2	2	1	1	2	0	0	0	0	0	0	0	2	2	0
Avg	2	2	1	1	2	0	0	0	0	0	0	0	2	2	0
				3/2/1	– ind	icates	stren	gth of	correl	ation (3	– high,	, 2- med	ium, 1- le	ow)	

	EHO209	DESIGN OF PRESSURE VESSELS						
RER	EQUISI	ΓES	CATEGORY	PE	Credit		3	
				L	Т	P	TE	
			Hours/Week	3	0	0	3	
OUR	RSE OBJ	ECTIVES:		ı		1		
1.	To study	about the various types of stresses act in the pressure vessels						
2.	To design	n components of pressure vessel using codes and standards.						
3.	To study	the design the supportive members of pressure vessels.						
4.	To study	about design considerations of pressure vessels.						
5	To study	about the design of pipes related to design of pressure vessels.						
UNIT	ΓI	STRESSES IN PRESSURE VESSELS		9	0	0	9	
	electrical A	, Pure Extension, Pure Bending harmonic excitation, Bendapplications. DESIGN OF VESSELS USING CODES	ioum-Euier beam	9 g	0 p	0	ms, 9	
Exces reinfo	ssive elast orcement li	r plate. Thermal stresses, Stress concentration in plate having ic deformation, Plastic instability, Brittle rupture and creep mits, design of composite analysis, wind and seismic load consider	. Theory of reinfration in the design	forced of pre	open ssure	ing a	and 1.	
UNIT	T III	SUPPORTS FOR VERTICAL & HORIZONTAL VES	SELS	9	0	0	9	
codes		ASME codes for pressure vessel design, Pressure vessel and refor short vertical vessels, Stress concentration at a variable thic of nozzles.						
IINII	ΓIV	OTHER DESIGN CONSIDERATIONS		9	0	0	9	
01411								
Buckl cylind stiffer tempe	ners, and erature, irr	menon, Elastic Buckling of circular ring and cylinders under extension extension extension in Elastic Buckling buckling under combined External pressure and Axial loading adiation, corrosion, and other hostile environments; High strengthmal high pressures found in undersea exploration, offshore drilling	of Cylinders, Designers, Statigue, shock, a, light weight pres	gn of c high p sure ve	ircum oressu	feren re, h	tial igh	
Buckl cylind stiffen tempe resista	ners, and erature, irr ant to exte	menon, Elastic Buckling of circular ring and cylinders under extenses under external pressure, Effect of supports on Elastic Buckling buckling under combined External pressure and Axial loading adiation, corrosion, and other hostile environments; High strength	of Cylinders, Designers, Statigue, shock, a, light weight pres	gn of c high p sure ve	ircum oressu	feren re, h	tial igh	
Buckl cylind stiffen tempe resista UNIT	ners, and erature, irr ant to exte FV diagram, g system a	menon, Elastic Buckling of circular ring and cylinders under extension extension external pressure, Effect of supports on Elastic Buckling buckling under combined External pressure and Axial loading adiation, corrosion, and other hostile environments; High strengthmal high pressures found in undersea exploration, offshore drilling	of Cylinders, Designation of Cylinders, Designation of Cylinders, Stress intensification of Cylinders, Designation of Cylinders, Stress intensification of Cylinders, Designation of Cylinders, Designat	gn of chigh property of the sure versions. 9 on fact	or; D	feren re, h Vess 0	tial igh sels	
Buckl cylind stiffer tempe resista UNIT	ners, and erature, irr ant to exte FV diagram, g system a	menon, Elastic Buckling of circular ring and cylinders under extense under external pressure, Effect of supports on Elastic Buckling buckling under combined External pressure and Axial loading adiation, corrosion, and other hostile environments; High strength rnal high pressures found in undersea exploration, offshore drilling PIPING DESIGN Piping layout and piping stress analysis; Flexibility factor and s per B31.1 piping code. Piping components - bends, tees, bellow	of Cylinders, Designation of Cylinders, Designation of Cylinders, Space of Cylinders, Space of Cylinders, Space of Cylinders, Designation of Cylinders, Space of Cylinders, Space of Cylinders, Designation of Cylinders, Space of Cylinders, Space of Cylinders, Designation of Cylinders, Space	gn of chigh properties with the sure version of the sure versions.	or; D	feren re, h Vess 0 esign suppo	tial igh sels 9 of orts	
Buckl cylind stiffer tempe resista UNIT Flow piping and th	ners, and erature, irr ant to exte T V diagram, g system a neir behavi	menon, Elastic Buckling of circular ring and cylinders under exters under external pressure, Effect of supports on Elastic Buckling buckling under combined External pressure and Axial loading adiation, corrosion, and other hostile environments; High strength rnal high pressures found in undersea exploration, offshore drilling PIPING DESIGN Piping layout and piping stress analysis; Flexibility factor and is per B31.1 piping code. Piping components - bends, tees, bellow or; Introduction to piping Codes and Standards.	of Cylinders, Designation of Cylinders, Designation of Cylinders, Space of Cylinders, Space of Cylinders, Space of Cylinders, Designation of Cylinders, Space of Cylinders, Space of Cylinders, Designation of Cylinders, Space of Cylinders, Space of Cylinders, Designation of Cylinders, Space	gn of c high I sure veng. 9 on fact es of p	or; D	feren re, h Vess 0 esign suppo	tial igh sels 9 of orts	
Buckl cylind stiffer tempe resista UNIT Flow piping and th	ners, and erature, irr ant to exte TV diagram, g system a neir behavi	menon, Elastic Buckling of circular ring and cylinders under exters under external pressure, Effect of supports on Elastic Buckling buckling under combined External pressure and Axial loading adiation, corrosion, and other hostile environments; High strength rnal high pressures found in undersea exploration, offshore drilling PIPING DESIGN Piping layout and piping stress analysis; Flexibility factor and is per B31.1 piping code. Piping components - bends, tees, bellow or; Introduction to piping Codes and Standards.	of Cylinders, Designation of Cylinders, Designation of Cylinders, Space of Cylinders, Space of Cylinders, Space of Cylinders, Designation of Cylinders, Space of Cylinders, Space of Cylinders, Designation of Cylinders, Space of Cylinders, Space of Cylinders, Designation of Cylinders, Space	gn of c high I sure veng. 9 on fact es of p	or; D	feren re, h Vess 0 esign suppo	tial igh sels 9 of orts	

TEXT B	XT BOOKS:						
1.	Dennis Moss "Pressure Vessel Design Manual"						
2.	Henry H Bednar, "Pressure vessel Design Hand book", CBS publishers and distributors.						
REFER	RENCES:						
1.	Harvey J F, "Pressure vessel design", CBS, publication.						
2.	Brownell L. E & Young. E. D, "Process equipment design", Wiley Eastern Ltd., India.						
3.	Stanley M Wales, "Chemical Process Equipment, Selection and Design", Butterworths,						

4.	Series in Chemical Engineering, 1988. 6. J. Phillip Ellenberger "Pressure Vessels: ASME Code Simplified".
5.	"ASME Pressure Vessel and Boiler Code", Section VIII Div. 1, 2, and 3.
6.	"American standard code for pressure piping", B 31.1.
7.	Smith P, "Fundamentals of Piping Design", Elsevier.

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:						
CO1	Determine stresses in pressure vessels	Evaluate					
CO2	Design pressure vessels using ASME codes	Create					
CO3	Design support members of pressure vessels	Create					
CO4	Apply other design considerations for pressure vessels	Apply					
CO5	Design of pressurized fluid piping	Create					

COURSE A	ARTI	CUL	ATIO	N MA	ATRI	X									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	2	2	0	0	0	0	0	0	0	0	3	3	0
CO2	2	3	3	3	0	0	0	0	0	0	0	0	3	3	0
CO3	2	3	3	3	0	0	0	0	0	0	0	0	3	3	0
CO4	3	1	1	1	0	0	0	0	0	0	0	0	3	3	0
CO5	2	3	3	3	0	0	0	0	0	0	0	0	3	3	0
Avg	2	2.4	2.4	2.4	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	3	3	0.0
	•	•	•	3/2/1	– ind	icates	stren	gth of	correl	ation (3	– high,	2- med	ium, 1- lo	ow)	

	210	MECHANICAL VIBRATIONS								
PREREQ	UISI	TES	CATEGORY	PE	Cr	edit	3			
			TT /TT 1	L	P	TE				
			Hours/Week	eek 3 0 0			3			
COURSE	OBJ	JECTIVES:								
1.	To u	inderstand the Fundamentals of Vibration and its practical applications.								
2.	To understand the characteristics of free and forced vibration.									
3.	To u	inderstand the Single and Multi DOF of vibration system.								
4.	To u	inderstand the working principle and operations of various vibration me	asuring instrumen	its						
5	To u	anderstand about the vibration analysis methods.								
UNIT I		FUNDAMENTALS OF VIBRATIONS		9	0	0	9			
– periodic	c, non	of vibration – causes and effects of vibrations – vibration parameters - periodic, harmonic, non-harmonic. Degree of freedom, static equilibration analysis.								
UNIT II		FREE VIBRATION OF SINGLE DEGREE OF FREEDOM	SYSTEMS	9	0	0	9			
damped, c		differential equations by newton, energy, lagrangian and Rayleigh's mally damped, over damped – logarithmic decrement – Coulomb's damped								
damped, odamping. UNIT III Forced Sigmotion ex	I ngle I		OM SYSTEMS armonic force exceptility – motion tra	9 eitation	and c	oulor 0 harm	nb's 9 onic			
damped, odamping. UNIT III Forced Sigmotion ex	I ngle I	FORCED VIBRATION OF SINGLE DEGREE OF FREEDO DOF system – Analysis of linear and torsional systems subjected to h on (excluding elastic damper) – vibration isolation – force transmissil	OM SYSTEMS armonic force exceptility – motion transped.	9 eitation	and c	oulor 0 harm	nb's 9 onic			
damped, cdamping. UNIT III Forced Simotion exisolators & UNIT IV Free unda Matrix and method for	I ngle I scitation with the scitation of	FORCED VIBRATION OF SINGLE DEGREE OF FREEDO DOF system – Analysis of linear and torsional systems subjected to h on (excluding elastic damper) – vibration isolation – force transmissil unts – Rotor dynamics, critical speed of single rotor, undamped and dar	OM SYSTEMS armonic force exceptility – motion transped. MS s and stiffness coorsional two degree	9 citation ansmis 9 cefficie ee of fr	on and sibilit onts- Freedor	harmey, typ 0 Flexiben; Ho	9 onic oical 9 ility lzer			
damped, of damping. UNIT III Forced Simotion exisolators & UNIT IV Free unda Matrix and method for method for damping.	I ngle I scitation with the second stiff or line or tran	FORCED VIBRATION OF SINGLE DEGREE OF FREEDO DOF system – Analysis of linear and torsional systems subjected to h on (excluding elastic damper) – vibration isolation – force transmissil unts – Rotor dynamics, critical speed of single rotor, undamped and dar VIBRATION OF MULTI DEGREE OF FREEDOM SYSTE d Multi Degree of Freedom vibration system – Influence Coefficient finess Matrix - Eigen values and Eigen vectors for linear system and to ear and torsional unbalanced system; Two rotors, three rotors and gear	OM SYSTEMS armonic force exceptility – motion transped. MS s and stiffness coorsional two degree	9 efficie e of frreley's	on and sibilit onts- Freedor	harmey, typ 0 Flexiben; Ho	9 onicoical gility lzer			
damped, of damping. UNIT III Forced Simulation existed at the second s	I ngle I scitation with the second stiff or line for transport tra	FORCED VIBRATION OF SINGLE DEGREE OF FREEDO DOF system – Analysis of linear and torsional systems subjected to h on (excluding elastic damper) – vibration isolation – force transmissil unts – Rotor dynamics, critical speed of single rotor, undamped and dar VIBRATION OF MULTI DEGREE OF FREEDOM SYSTE d Multi Degree of Freedom vibration system – Influence Coefficient finess Matrix - Eigen values and Eigen vectors for linear system and to ear and torsional unbalanced system; Two rotors, three rotors and geare asverse vibratory system. VIBRATION MEASURING INSTRUMENTS AND	OM SYSTEMS armonic force exceptility – motion transped. MS s and stiffness coorsional two degreed system; Dunke VIBRATION tion Measuring In Electromagnetic ar	9 efficie e of frrley's strumend Electrical	on and sibilit onts- Freedor and R onts- ctrody	harmay, typ O Flexib n; Ho aylei O Selectorami	9 ponic pical 9 glility lizer gh's 9			
damped, of damping. UNIT III Forced Simution exisolators & UNIT IV Free unda Matrix ammethod for method for UNIT V Vibration of Sensors Frequency	I ngle I scitation with the second stiff or line for transport tra	FORCED VIBRATION OF SINGLE DEGREE OF FREEDO DOF system – Analysis of linear and torsional systems subjected to h on (excluding elastic damper) – vibration isolation – force transmissil unts – Rotor dynamics, critical speed of single rotor, undamped and dar VIBRATION OF MULTI DEGREE OF FREEDOM SYSTE d Multi Degree of Freedom vibration system – Influence Coefficient effness Matrix - Eigen values and Eigen vectors for linear system and to ear and torsional unbalanced system; Two rotors, three rotors and geare esverse vibratory system. VIBRATION MEASURING INSTRUMENTS AND ANALYSIS ysis Overview - Experimental Methods in Vibration AnalysisVibraticelerometer MountingsVibration Exciters-Mechanical, Hydraulic, E	OM SYSTEMS armonic force exceptility – motion transped. MS s and stiffness coorsional two degreed system; Dunke VIBRATION tion Measuring In Electromagnetic armse -Testing for	9 efficie e of frrley's strumend Electrical	on and sibilit onts- Freedor and R onts- etrody	harmey, typ O Flexib n; Ho aylei; O Selection in d m	9 ponic pical glass of the second sec			
damped, of damping. UNIT III Forced Simmotion exisolators & UNIT IV Free unda Matrix and method for method for UNIT V Vibration of Sensors Frequency shapes.	I ngle I ccitation with the contract of the co	FORCED VIBRATION OF SINGLE DEGREE OF FREEDO DOF system – Analysis of linear and torsional systems subjected to h on (excluding elastic damper) – vibration isolation – force transmissil unts – Rotor dynamics, critical speed of single rotor, undamped and dar VIBRATION OF MULTI DEGREE OF FREEDOM SYSTE d Multi Degree of Freedom vibration system – Influence Coefficient finess Matrix - Eigen values and Eigen vectors for linear system and to ear and torsional unbalanced system; Two rotors, three rotors and gears asverse vibratory system. VIBRATION MEASURING INSTRUMENTS AND ANALYSIS ysis Overview - Experimental Methods in Vibration AnalysisVibrat occlerometer MountingsVibration Exciters-Mechanical, Hydraulic, E asuring Instruments System Identification from Frequency Respon	OM SYSTEMS armonic force exceptility – motion transped. MS s and stiffness coorsional two degreed system; Dunke VIBRATION tion Measuring In Electromagnetic armse -Testing for	9 efficie e of frrley's strumend Electresona	on and sibilit onts- Freedor and R onts- etrody	harmey, typ O Flexib n; Ho aylei; O Selection in d m	9 ponic pical glass of the second sec			
damped, cdamping. UNIT III Forced Simution exisolators & UNIT IV Free unda Matrix and method for method for the distriction of Sensors Frequency	I ngle I scitation with the second stiff or line for transpect of the second stiff or line or or	FORCED VIBRATION OF SINGLE DEGREE OF FREEDO DOF system – Analysis of linear and torsional systems subjected to h on (excluding elastic damper) – vibration isolation – force transmissil unts – Rotor dynamics, critical speed of single rotor, undamped and dar VIBRATION OF MULTI DEGREE OF FREEDOM SYSTE d Multi Degree of Freedom vibration system – Influence Coefficient finess Matrix - Eigen values and Eigen vectors for linear system and to ear and torsional unbalanced system; Two rotors, three rotors and gears asverse vibratory system. VIBRATION MEASURING INSTRUMENTS AND ANALYSIS ysis Overview - Experimental Methods in Vibration AnalysisVibrat occlerometer MountingsVibration Exciters-Mechanical, Hydraulic, E asuring Instruments System Identification from Frequency Respon	OM SYSTEMS armonic force exceptility – motion transped. MS s and stiffness coorsional two degreed system; Dunke VIBRATION tion Measuring In Electromagnetic armse -Testing for	9 efficie e of frrley's strumend Electresona	on and sibilit onts- Freedor and R onts- etrody	harmey, typ O Flexib n; Ho aylei; O Selection in d m	9 ponic bical gility lzer gh's			

REFERENCES:							
1.	Benson H. Tongue, "Principles of Vibrations", Oxford University, 2007.						
2.	Grover. G.K., edited by Nigam. S. P., "Mechanical Vibrations", Nem Chand and Bros., 2014.						

3.	David A. Bies and Colin H. Hansen, "Engineering Noise Control – Theory and Practice", Spon Press, 2009.
4.	Julian Happian-Smith – "An Introduction to Modern Vehicle Design", Butterworth-Heinemann, 2001.
5.	William T. Thomson, "Theory of Vibration with Applications", Taylor and Francis, 2003.
6.	Balakumar Balachandran and Edward B. Magrab, "Fundamentals of Vibrations", 1st Editon, Cengage Learning, 2009
7.	Grover. G.T., "Mechanical Vibrations", Nem Chand and Bros., 2009
8.	NPTEL :: Mechanical Engineering - NOC:Introduction to Mechanical Vibration

	SE OUTCOMES: ompletion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Determine stresses in pressure vessels	Evaluate
CO2	Design pressure vessels using ASME codes	Create
CO3	Design support members of pressure vessels	Create
CO4	Apply other design considerations for pressure vessels	Apply
CO5	Design of pressurized fluid piping	Create

COURSE A	ARTIC	CULA	TIOI	N MA	TRIX										
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	2	1	0	0	0	0	0	0	0	0	2	2	0
CO2	3	3	2	2	0	0	0	0	0	0	0	0	2	2	0
CO3	3	3	2	2	0	0	0	0	0	0	0	0	2	2	0
CO4	3	3	2	2	0	0	0	0	0	0	0	0	2	2	0
CO5	1	1	2	2	0	0	0	0	0	0	0	0	2	2	0
Avg	2.2	2.4	2	1.8	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	2	2	0.0
	•	•		3/2/1	– indi	cates s	strengt	th of co	orrelat	ion (3 –	high, 2	- mediui	n, 1- low)	•

VERTICALS -3 PRODUCT AND PROCESS DEVELOPMENT

22MEHO301	PRECISION ENGINEERING								
PREREQUIS	ITES CATE	EGORY	PE	Cro	edit	3			
			L	Т	P	TH			
	Hour	s/Week	3	0	0	3			
COURSE OB	JECTIVES:			1	1	.1			
1. Explain	the need and progress of precision engineering.								
2. To know	w about the principle and working of different methods of precision machin	ing.							
3. To unde	erstand about micromachining.								
4. To know	w about Laser devices and machine vision.								
5. To unde	erstand about SEM and 3D surface topography.								
UNIT I	UNIT I INTRODUCTION								
- Normal, Pred	Precision Engineering, Need for precision manufacturing, Four Classes of tision, High-precision, Ultraprecision Processes and Nanotechnology	Achievabl				<u> </u>			
UNIT II	PRECISION MACHINING		9	0	0	9			
	Micro- and Nano-machining, Conventional micro machining techniques , Ultra-precision diamond turning, SPDT Single point diamond turning.	- micro t	urning,	mici	o-mi	lling,			
UNIT III	MICRO MACHINING		9	0	0	9			
	al discharge machining, Photochemical machining, Electro chemical g, Electron beam micromachining, Focused Ion Beam micromachining, etc		chining	g, La	ser 1	beam			
UNIT IV	LASER AND OPTICS		9	0	0	9			
	al discharge machining, Photochemical machining, Electro chemical g, Electron beam micromachining, Focused Ion Beam micromachining.	microma	chining	g, La	ser 1	beam			
UNIT V	MEASUREMENT AND CHARACTERISATION		9	0	0	9			
confocal Micro	of Typical Nanofeatures, Surface metrology - 3D surface topography - 1 oscopy, Interferometry, Non-optical Scanning Microscopy – Scanning electrarameters for characterizing 3D surface topography.								
		Total (45L) =	= 45 1	Perio	ods			

TEXT B	OOKS:
1.	Jain, V.K., Introduction to micromachining, Narosa publishers, 2018
2.	Venktesh V.C., Sudin Izman, Precision Engineering, Tata Mc.Graw Hill Publishing Company, New Delhi 2007.
REFERI	ENCES:
1.	David Dornfeld, Dae-Eun Lee, Precision Manufacturing, Springer, 2008
2.	Kevin Harding, "Handbook of Optical Dimensional Metrology, Series: Series in Optics and optoelectronics", Taylor & Francis, 2013
3.	Murty, R.L., Precision Engineering in Manufacturing, New Age publishers, 2005.

	SE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Impart knowledge progress of precision engineering	Understand
CO2	Identify principle and working of different methods of precision machining	Understand
СОЗ	Apply knowledge on micromachining	Apply
CO4	Define the uses of Laser devices and machine vision	Remember
CO5	Apply knowledge on Surface metrology	Apply

COURSE A	ARTIO	CULA	TIO	N MA	TRIX										
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	0	1	0	0	1	0	0	0	0	2	1	2	2
CO2	1	3	1	1	0	0	1	0	0	0	0	2	0	1	1
CO3	3	3	1	1	2	0	1	0	0	0	0	3	0	1	3
CO4	3	2	1	2	2	0	1	0	0	0	0	3	2	1	3
CO5	2	3	0	3	1	0	1	0	0	0	0	3	0	1	2
Avg	2.2	2.6	0.6	1.6	1.0	0.0	1.0	0.0	0.0	0.0	0.0	2.6	0.6	1.2	2.2
	•	•		3/2/1 -	– indi	cates s	strengt	th of co	orrelat	ion (3 –	high, 2	- mediui	n, 1- low)	

$\begin{array}{c c} & L & T \\ \hline 3 & 0 \\ \hline \end{array}$		TH 3
COURSE OBJECTIVES: 1. To understand knowledge of crack and failure of metals 2. To know different types of coatings 3. Apply knowledge of composites 4. To understand properties of modern alloys 5. To know about advanced aerospace alloys UNIT I REVIEW OF MECHANICAL BEHAVIOUR OF MATERIALS Plastic deformation in poly phase alloys – Strengthening mechanism –Griffith's theory of failure modes-b ductile fractures- damping property of materials- fracture toughness –initiation and propagation of fatigue cracks mechanism –Hydrogen embrittlement of metals UNIT II SURFACE MODIFICATION OF MATERIALS 9 0 Mechanical surface treatment and coating –Case hardening and hard facing –thermal spraying –Vapour deposi implantation- diffusion coating –electroplating and electroforming –conversion coating –Ceramic and organic	0 Orittle	3 9 and reep
COURSE OBJECTIVES: 1. To understand knowledge of crack and failure of metals 2. To know different types of coatings 3. Apply knowledge of composites 4. To understand properties of modern alloys 5. To know about advanced aerospace alloys UNIT I REVIEW OF MECHANICAL BEHAVIOUR OF MATERIALS Plastic deformation in poly phase alloys – Strengthening mechanism –Griffith's theory of failure modes-b ductile fractures- damping property of materials- fracture toughness –initiation and propagation of fatigue cracks mechanism –Hydrogen embrittlement of metals UNIT II SURFACE MODIFICATION OF MATERIALS 9 0 Mechanical surface treatment and coating –Case hardening and hard facing –thermal spraying –Vapour deposi implantation- diffusion coating –electroplating and electroforming –conversion coating –Ceramic and organic	0 rittle	9 and reep
1. To understand knowledge of crack and failure of metals 2. To know different types of coatings 3. Apply knowledge of composites 4. To understand properties of modern alloys 5. To know about advanced aerospace alloys UNIT I REVIEW OF MECHANICAL BEHAVIOUR OF MATERIALS 9 0 Plastic deformation in poly phase alloys – Strengthening mechanism –Griffith's theory of failure modes-b ductile fractures- damping property of materials- fracture toughness –initiation and propagation of fatigue cracks mechanism –Hydrogen embrittlement of metals UNIT II SURFACE MODIFICATION OF MATERIALS 9 0 Mechanical surface treatment and coating –Case hardening and hard facing –thermal spraying –Vapour deposi implantation- diffusion coating –electroplating and electroforming –conversion coating –Ceramic and organic	rittle s – Cı	and reep
2. To know different types of coatings 3. Apply knowledge of composites 4. To understand properties of modern alloys 5. To know about advanced aerospace alloys UNIT I REVIEW OF MECHANICAL BEHAVIOUR OF MATERIALS 9 0 Plastic deformation in poly phase alloys – Strengthening mechanism –Griffith's theory of failure modes-b ductile fractures- damping property of materials- fracture toughness –initiation and propagation of fatigue cracks mechanism –Hydrogen embrittlement of metals UNIT II SURFACE MODIFICATION OF MATERIALS 9 0 Mechanical surface treatment and coating –Case hardening and hard facing –thermal spraying –Vapour deposi implantation- diffusion coating –electroplating and electroforming –conversion coating –Ceramic and organic descriptions.	rittle s – Cı	and reep
3. Apply knowledge of composites 4. To understand properties of modern alloys 5. To know about advanced aerospace alloys UNIT I REVIEW OF MECHANICAL BEHAVIOUR OF MATERIALS 9 0 Plastic deformation in poly phase alloys – Strengthening mechanism –Griffith's theory of failure modes- b ductile fractures- damping property of materials- fracture toughness –initiation and propagation of fatigue cracks mechanism –Hydrogen embrittlement of metals UNIT II SURFACE MODIFICATION OF MATERIALS 9 0 Mechanical surface treatment and coating –Case hardening and hard facing –thermal spraying –Vapour deposi implantation- diffusion coating –electroplating and electroforming –conversion coating –Ceramic and organic electroplating and electroforming –conversion coating –Ceramic and organic electroplating and electroforming –conversion coating –Ceramic and organic electroplating and electroforming –conversion coating –Ceramic and organic electroforming –ceramic electroformi	rittle s – Cı	and reep
4. To understand properties of modern alloys 5. To know about advanced aerospace alloys UNIT I REVIEW OF MECHANICAL BEHAVIOUR OF MATERIALS 9 0 Plastic deformation in poly phase alloys – Strengthening mechanism –Griffith's theory of failure modes- b ductile fractures- damping property of materials- fracture toughness –initiation and propagation of fatigue cracks mechanism –Hydrogen embrittlement of metals UNIT II SURFACE MODIFICATION OF MATERIALS 9 0 Mechanical surface treatment and coating –Case hardening and hard facing –thermal spraying –Vapour deposi implantation- diffusion coating –electroplating and electroforming –conversion coating –Ceramic and organic electroplating and electroforming –conversion coating –Ceramic and organic electroplating and electroforming –conversion coating –Ceramic and organic electroplating and electroforming –conversion coating –Ceramic and organic electroforming –ceramic el	rittle s – Cı	and reep
5. To know about advanced aerospace alloys UNIT I REVIEW OF MECHANICAL BEHAVIOUR OF MATERIALS Plastic deformation in poly phase alloys – Strengthening mechanism –Griffith's theory of failure modes- b ductile fractures- damping property of materials- fracture toughness –initiation and propagation of fatigue cracks mechanism –Hydrogen embrittlement of metals UNIT II SURFACE MODIFICATION OF MATERIALS 9 0 Mechanical surface treatment and coating –Case hardening and hard facing –thermal spraying –Vapour deposi implantation- diffusion coating –electroplating and electroforming –conversion coating –Ceramic and organic specific properties of the control of the	rittle s – Cı	and reep
UNIT I REVIEW OF MECHANICAL BEHAVIOUR OF MATERIALS 9 0 Plastic deformation in poly phase alloys – Strengthening mechanism –Griffith's theory of failure modes-b ductile fractures- damping property of materials- fracture toughness –initiation and propagation of fatigue cracks mechanism –Hydrogen embrittlement of metals UNIT II SURFACE MODIFICATION OF MATERIALS 9 0 Mechanical surface treatment and coating –Case hardening and hard facing –thermal spraying –Vapour deposi implantation- diffusion coating –electroplating and electroforming –conversion coating –Ceramic and organic electroplating and electroforming –conversion coating –Ceramic and organic electroforming –ceramic electroforming –ce	rittle s – Cı	and reep
Plastic deformation in poly phase alloys – Strengthening mechanism –Griffith's theory of failure modes- b ductile fractures- damping property of materials- fracture toughness –initiation and propagation of fatigue cracks mechanism –Hydrogen embrittlement of metals UNIT II SURFACE MODIFICATION OF MATERIALS 9 0 Mechanical surface treatment and coating –Case hardening and hard facing –thermal spraying –Vapour deposi implantation- diffusion coating –electroplating and electroforming –conversion coating –Ceramic and organic electroplating and electroforming –conversion coating –Ceramic and organic electroplating and electroforming –conversion coating –Ceramic and organic electroplating and electroforming –conversion coating –Ceramic and organic electroforming –ceramic electroformin	rittle s – Cı	and reep
ductile fractures- damping property of materials- fracture toughness –initiation and propagation of fatigue cracks mechanism –Hydrogen embrittlement of metals UNIT II SURFACE MODIFICATION OF MATERIALS 9 0 Mechanical surface treatment and coating –Case hardening and hard facing –thermal spraying –Vapour deposi implantation- diffusion coating –electroplating and electroforming –conversion coating –Ceramic and organic electroplating and electroforming –conversion coating –Ceramic and organic electroplating and electroforming –conversion coating –Ceramic and organic electroplating electroplating electroforming –conversion coating –Ceramic and organic electroforming –ceramic electroforming –conversion coating –ceramic electroforming –ceramic electrof	s – C1	reep
UNIT III ADVANCED HEAT TREATMENT OF MATERIALS 9 0	0	9
Composite- Types- Natural composites- Metal matrix composites- Ceramic matrix composites- Applications		
UNIT IV MODERN MATERIALS AND ALLOYS 9 0	0	9
Super alloys Hastelloy, Inconel, Invar, and Monel and uses.—Refractory materials - Fireclay refractories. High refractories, Silica brick, Magnesite refractories Ceramic and their applications - Low melting alloys Mercury, Cadmium, Zinc, Lead—Shape memory alloys - Aluminium-Nickel and Nickel -Titanium		
UNIT V APPLICATION OF ADVANCED MATERIALS 9 0	0	9
Ti and Ni based alloys for gas turbine applications –Maraging (Low carbon and high Nickel) and cryogenic Newer materials and their treatment for automobile applications – Materials for aerospace (AL6061,AL 7075). AH36, DH36, and EH36)and nuclear systems		
Total $(45L) = 45$		

TEXT B	OOKS:
1.	Dowling, "Mechanical Behaviour Of Materials, Engineering Method Of Determination, Fracture", Mcgraw Hill, 1999
2.	Dieter, 'Engineering Design, A materials And Processing Approach'', Third Edition, Mcgraw Hill,1999
REFERI	ENCES:
1.	P.Rama Rao, "Advances In Materials And Their Applications", Willey Eastern Ltd.,1993.
2.	Serope Kalpakjian, "Manufacturing Engineering And Technology' Third Edition, Addison Wisley Publishing Co.,1995.
3.	Kennith G .Budinski, ''Surface Engineering For Wear Resistance'', Prentice Hall,1998.
4.	Dieter, "Mechanical Metallurgy" Mcgraw Hill, 1989
5.	D.R.Gabe, 'Principles Of Metal Surface Treatment And Protection', Pergamon Press1978.

	SE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Impartknowledge of crack and failure of metals	Understand
CO2	Identify the different types of coatings	Understand
CO3	Applyknowledge of composites	Apply
CO4	Definethe properties of modern alloys	Remember
CO5	Provide information of advanced aerospace alloys	Remember

COURSE A	ARTIO	CULA	TIO	N MA	TRIX										
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	0	1	0	0	1	0	0	0	0	2	1	2	2
CO2	1	3	1	1	0	0	1	0	0	0	0	2	0	1	1
CO3	3	3	1	1	2	0	1	0	0	0	0	3	0	1	3
CO4	3	2	1	2	2	0	1	0	0	0	0	3	2	1	3
CO5	2	3	0	3	1	0	1	0	0	0	0	3	0	1	2
Avg	2.2	2.6	0.6	1.6	1.0	0.0	1.0	0.0	0.0	0.0	0.0	2.6	0.6	1.2	2.2
	•	•		3/2/1 -	– indi	cates s	strengt	th of co	orrelat	ion (3 –	high, 2	- mediui	n, 1- low)	•

	ADDITIVE MANUFACTURING				
PREREQUIS	ITES CATEGORY	PE	Cre	edit	3
1. Manufacturi	ing technology, Drafting software	L	T	P	TH
2. Engineering	Materials Hours/Week	3	0	0	3
COURSE OB	JECTIVES:				
1. To introd	luce the development of Additive Manufacturing (AM), various business opportunities	and ap	plicat	ions	
	arize various software tools, processes and techniques to create physical objects that satient / prototyping requirements, using AM.	atisfy p	roduct	t	
3. To be acq	quainted with vat polymerization and material extrusion processes.				
4. To be fan	niliar with powder bed fusion and direct energy deposition.				
5. To gain k	nowledge on applications of binder jetting, material jetting and laminated object manu	facturii	ng pro	cess	es
UNIT I	INTRODUCTION	9	0	0	9
		1 1			T
DFAM for Pa Structure Gen	DESIGN FOR ADDITIVE MANUFACTURING (DFAM) Objectives- AM Unique Capabilities: Part Consolidation-Topology Optimization Light representation of the Processing - CAD Model Preparation -Part Orien eration -Model Slicing - Tool Path Generation-Customized Design and Fabric Case Studies.	tation	and S	Suppo	ort
Concepts and ODFAM for Pa	Objectives- AM Unique Capabilities: Part Consolidation-Topology Optimization Lighurt Quality Improvement. Data Processing - CAD Model Preparation -Part Orien eration -Model Slicing - Tool Path Generation-Customized Design and Fabric	nt weigh	nt Stru and S	ictur Suppe	e - ort
Concepts and Conce	Objectives- AM Unique Capabilities: Part Consolidation-Topology Optimization Lighurt Quality Improvement. Data Processing - CAD Model Preparation -Part Orien eration -Model Slicing - Tool Path Generation-Customized Design and Fabric Case Studies.	at weight tation cation	nt Struand S for M O Applic	icture Suppo Medic 0	e - ort cal 9
Concepts and Conce	Objectives- AM Unique Capabilities: Part Consolidation-Topology Optimization Light Quality Improvement. Data Processing - CAD Model Preparation -Part Orienteration -Model Slicing - Tool Path Generation-Customized Design and Fabric Case Studies. VAT POLYMERIZATION AND MATERIAL EXTRUSION Tization: Stereo lithography Apparatus (SLA)- Materials -Process -Advantages Limitate Processing (DLP) - Materials - Process - Advantages - Applications. Extrusion Ba	at weight tation cation	nt Struand S for M O Applic	icture Suppo Medic 0	e - ort cal 9
Concepts and O DFAM for Pa Structure Gen Applications- O UNIT III Photo polymer Digital Light I Deposition Mo UNIT IV Powder Bed F Typical Mater Process - Adva Beam Deposition	Objectives- AM Unique Capabilities: Part Consolidation-Topology Optimization Light Quality Improvement. Data Processing - CAD Model Preparation -Part Orien eration -Model Slicing - Tool Path Generation-Customized Design and Fabric Case Studies. VAT POLYMERIZATION AND MATERIAL EXTRUSION ization: Stereo lithography Apparatus (SLA)- Materials -Process -Advantages Limital Processing (DLP) - Materials - Process - Advantages - Applications. Extrusion Bandeling (FDM)- Process-Materials - Applications and Limitations.	t weight tation cation 9 tions- Ansed Systems In (EBM):	ont Struand S for M Applications: One of the structure	ocation Fus ocation Fus	9 9 9 5 - 5 - 5 - 5 - 5 - 5 - 5 - 5 - 5
Concepts and O DFAM for Pa Structure Gen Applications- O UNIT III Photo polymer Digital Light I Deposition Mo UNIT IV Powder Bed F Typical Mater Process - Adva Beam Deposition	Objectives- AM Unique Capabilities: Part Consolidation-Topology Optimization Light Quality Improvement. Data Processing - CAD Model Preparation -Part Orien eration -Model Slicing - Tool Path Generation-Customized Design and Fabric Case Studies. VAT POLYMERIZATION AND MATERIAL EXTRUSION ization: Stereo lithography Apparatus (SLA)- Materials -Process -Advantages Limita Processing (DLP) - Materials - Process - Advantages - Applications. Extrusion Badeling (FDM)- Process-Materials - Applications and Limitations. POWDER BED FUSION AND DIRECT ENERGY DEPOSITION Fusion: Selective Laser Sintering (SLS): Process - Powder Fusion Mechanism -Process and Applications. Selective Laser Melting (SLM) and Electron Beam Melting (Intages and Applications. Interpretation of the Capabilities: Part Consolidation-Topology Optimization - Part Capabilities: Process - Powder Fusion Mechanism - Process and Applications. Interpretation of the Capabilities: Part Consolidation-Topology Optimization - Part Capabilities: Part Consolidation - Part Capabilities: Part Cap	t weight tation cation 9 tions- Ansed Systems In (EBM):	ont Struand S for M Applications: One of the structure	ocation Fus ocation Fus	9
Concepts and O DFAM for Pa Structure Gen Applications- O UNIT III Photo polymer Digital Light I Deposition Mo UNIT IV Powder Bed F Typical Mater Process - Adva Beam Depositi Materials -Ben UNIT V Binder Jetting: Modeling- Ma	Objectives- AM Unique Capabilities: Part Consolidation-Topology Optimization Light Quality Improvement. Data Processing - CAD Model Preparation -Part Orien eration -Model Slicing - Tool Path Generation-Customized Design and Fabric Case Studies. VAT POLYMERIZATION AND MATERIAL EXTRUSION Dization: Stereo lithography Apparatus (SLA)- Materials -Process -Advantages Limitar Processing (DLP) - Materials - Process - Advantages - Applications. Extrusion Bandeling (FDM)- Process-Materials - Applications and Limitations. POWDER BED FUSION AND DIRECT ENERGY DEPOSITION Fusion: Selective Laser Sintering (SLS): Process - Powder Fusion Mechanism -Process and Applications. Selective Laser Melting (SLM) and Electron Beam Melting (Intages and Applications. To Process: Laser Engineered Net Shaping (LENS)- Process -Material Delivery - Process - Applications.	t weight tation cation 9 tions- Ansed Systems I(EBM): Process I (EBM): Trocess	ong: M	O eters of turb of tur	9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9

TEXT BOOKS:

- 1. Andreas Gebhardt and Jan-Steffen Hötter "Additive Manufacturing: 3D Printing for Prototyping and Manufacturing", Hanser publications, United States, 2015, ISBN: 978-1-56990-582-1.
- 2. Ian Gibson, David W. Rosen and Brent Stucker "Additive Manufacturing Technologies: Rapid Prototyping to Direct Digital Manufacturing", 2nd edition, Springer., United States, 2015, ISBN 13: 978-1493921126.

REFERENCES:

- 1. Amit Bandyopadhyay and Susmita Bose, "Additive Manufacturing", 1st Edition, CRC Press., United States, 2015, ISBN-13: 978-1482223590.
- 2. Andreas Gebhardt, "Understanding Additive Manufacturing: Rapid Prototyping, Rapid Manufacturing", Hanser

	Gardner Publication, Cincinnati., Ohio, 2011, ISBN: 9783446425521.
3.	Kamrani A.K. and Nasr E.A., "Rapid Prototyping: Theory and practice", Springer., United States, 2006, ISBN: 978-1-4614-9842-1.
4.	Liou, L.W. and Liou, F.W., "Rapid Prototyping and Engineering applications: A tool box for prototype development", CRC Press., United States, 2011, ISBN: 9780849334092.
5.	Milan Brandt, "Laser Additive Manufacturing: Materials, Design, Technologies, and Applications", Woodhead Publishing., United Kingdom, 2016, ISBN: 9780081004333.

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:				
CO1	Recognize the development of AM technology and how AM technology propagated into various businesses and developing opportunities.	Remember			
CO2	Acquire knowledge on process of transforming a concept into the final product in AM technology.	Understand			
CO3	Elaborate the vat polymerization and material extrusion processes and its applications.	Apply			
CO4	Acquire knowledge on process and applications of powder bed fusion and direct energy deposition.	Apply			
CO5	Evaluate the advantages, limitations, applications of binder jetting, material jetting and laminated object manufacturing processes.	Evaluate			

COURSE ARTICULATION MATRIX

COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	0	0	0	0	0	1	2	0	1	0	2	1	1	1
CO2	2	1	1	1	1	0	2	1	0	1	0	2	1	2	1
CO3	2	1	0	0	0	0	1	0	0	1	0	2	1	1	1
CO4	2	1	0	0	0	0	1	0	0	1	0	2	1	1	1
CO5	2	1	0	0	0	0	1	0	0	1	0	2	1	1	1
Avg	2.0	0.8	0.2	0.2	0.2	0.0	1.2	0.6	0.0	1.0	0.0	2.0	1.0	1.2	1.0

3/2/1 – indicates strength of correlation (3 – high, 2- medium, 1- low)

22MEHO304	NON DESTRUCTIVE TESTING AND FAILURE	ANALYSIS							
PREREQUIS	ITES	CATEGORY	PE	Cr	edit	3			
			L	Т	P	ТН			
	Hours/Week								
COURSE OBJ	ECTIVES:		ı		1				
	pp the fundamental knowledge about non-destructive and destruction and production engineering components.	active analysis, in	order 1	o coi	ntrol	the			
UNIT I	INTRODUCTION AND SURFACE NDT		9	0	0	9			
Tools, applicat	e testing— Comparison with destructive testing, importance, so ons and limitations. Liquid penetrant Inspection - Principles, progenetic particle inspection - Principles, advantage and limitations.								
UNIT II	RADIOGRAPHY AND ACOUSTIC EMISSION		9	0	0	9			
	basic principle, electromagnetic radiation sources, radiogramitations and safety. Acoustic emission testing- procedures and its		spectio	n tec	hniqu	ies,			
UNIT III	EDDY CURRENT AND ULTRASONIC TESTING		9	0	0	9			
Eddy current to	sting – principle, application, limitation; Ultrasonic testing – basi		d bear	n, traı	nsduc	ers,			
inspection metl				0					
unit iv	LEAK TESTING AND THERMOGRAPHY		9	U	0	9			
UNIT IV Leak testing, H	LEAK TESTING AND THERMOGRAPHY olography and Thermography – principles, procedures and applicating methods; Defects in casting, forging, rolling and welding.	ations; Comparison			Ů				
UNIT IV Leak testing, H	I olography and Thermography – principles, procedures and applica	ations; Comparison			Ů				
UNIT IV Leak testing, H destructive test UNIT V Failure analysis	olography and Thermography – principles, procedures and applicating methods; Defects in casting, forging, rolling and welding.	re data retrieval,	and se	lectio	n of N	Non 9			

TEXT	BOOKS:
1.	Baldev Raj, "Practical Non-Destructive Testing", Narosa Publishing House, 1997.
2.	J. Prasad and C. G. K. Nair, Non-Destructive Test and Evaluation of Materials, Tata McGraw-Hill Education, 2nd edition (2011).
3.	Peter J Shull, "Nondestructive Evaluation- Theory, Techniques and Applications" Marcel Dekker, Inc, USA 2002, ISBN: 0-8247-8872-9.
REFEI	RENCES:
1	George E Dieter, "Mechanical Metallurgy", McGraw Hill Book Company
2	B.Hull and V.John. "Non-Destructive Testing", McMillan
3	A.K Das, "Metallurgy of failure analysis", TMH, 1992

	SE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Understand the concept of destructive and Non-destructive testing methods.	Understand
CO2	Explain the working principle and application of die penetrant test and magnetic particle inspection.	Remember
CO3	Understand the working principle of eddy current inspection, Ultrasonic testing and applications.	Understand
CO4	Apply radiographic techniques for testing and acoustic emission testing.	Apply

CO5	Define tools and techniques of failure analysis, procedural steps for investigation of failure.	Remember
-----	---	----------

COURSE A	ARTI	CUL	ATIO	N M	ATRI	X									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	1	1	0	0	0	0	0	0	0	0	2	2	0
CO2	2	2	1	3	0	0	0	0	0	0	0	0	2	2	0
CO3	2	2	1	3	1	0	0	0	0	0	0	0	2	2	0
CO4	2	2	1	3	1	0	0	0	0	0	0	0	2	2	0
CO5	2	2	1	3	3	0	0	0	0	0	0	0	2	2	0
Avg	1.8	2	1	2.6	1	0	0	0	0	0	0	0	2	2	0
				3/2/1	– ind	icates	stren	gth of	correl	ation (3	- high	, 2- med	lium, 1-1	ow)	

	EHO305	PRODUCT LIFE CYCLE MANAGEMENT								
PRE	REQUIS	ITES CATEGORY	PE	Cr	edit	3				
		ANY 1	L	Т	P	ТН				
		Hours/Week	3	0	0	3				
COU	RSE OBJ	JECTIVES:	•		,	•				
1.	To study a	about the history, concepts and terminology in PLM								
2.	To learn t	o learn the functions and features of PLM/PDM								
3.	To develo	p different modules offered in commercial PLM/PDM tools								
4.	To demon	astrate PLM/PDM approaches for industrial applications								
5.	To use PL	M/PDM with legacy data bases, Coax& ERP systems								
U	NIT I	HISTORY, CONCEPTS AND TERMINOLOGY OF PLM	9	0	0	9				
Mana	gement, He	C), Product Lifecycle Management (PLM). PLM/PDM Infrastructure – Network and eterogeneous data sources and applications	Comm	ıunıca	ations	, Dat				
U	NIT II	PLM/PDM FUNCTIONS AND FEATURES	9	0	0	9				
User Mana	Functions gement, Pro	PLM/PDM FUNCTIONS AND FEATURES - Data Vault and Document Management, Workflow and Process Management Classification and Programme Management. Utility Functions – Communication anslation, image services, system administration and application integration	ent, P	roduc	t Str	ucture				
User Mana transp	Functions gement, Pro	 Data Vault and Document Management, Workflow and Process Management Oduct Classification and Programme Management. Utility Functions – Communication 	ent, P	roduc	t Str	uctur				
User Mana transp Ul Case Arena	Functions gement, Proport, data transfer III studies base, Oracle A	Data Vault and Document Management, Workflow and Process Management Classification and Programme Management. Utility Functions – Communication anslation, image services, system administration and application integration	ent, Pan and P	roduc Notifi 0 LM,	et Strication 0 SAP	ucturen, data				
User Mana transp Ul Case Arena applic	Functions gement, Proport, data transfer III studies base, Oracle A	 Data Vault and Document Management, Workflow and Process Management oduct Classification and Programme Management. Utility Functions – Communication anslation, image services, system administration and application integration DETAILS OF MODULES IN A PDM/PLM SOFTWARE seed on top few commercial PLM/PDM tools – Teamcenter, Windchill, ENOVIA, agile PLM and Autodesk VaultArchitecture of PLM software- selection criterion of 	ent, Pan and P	roduc Notifi 0 LM,	et Strication 0 SAP	uctur n, dat 9 PLM				
User Mana transp Ul Case Arena applic Case s strateg imple	Functions gement, Proport, data transfer III studies based, Oracle A cation - Brans III IV studies on Ingy, PLM mentation,	 Data Vault and Document Management, Workflow and Process Management oduct Classification and Programme Management. Utility Functions – Communication anslation, image services, system administration and application integration DETAILS OF MODULES IN A PDM/PLM SOFTWARE and on top few commercial PLM/PDM tools – Teamcenter, Windchill, ENOVIA, agile PLM and Autodesk VaultArchitecture of PLM software- selection criterion of an ame to be removed 	ent, P. n and I g g Aras P software sof	o CLM, are for the state of th	t Strication O SAP or part O oning,	9 PLM ticula				
User Mana transp Ul Case Arena applic Ul Case s strateg imple perfor	Functions gement, Proport, data transfer III studies based, Oracle A cation - Brans III IV studies on Ingy, PLM mentation,	- Data Vault and Document Management, Workflow and Process Management oduct Classification and Programme Management. Utility Functions - Communication anslation, image services, system administration and application integration DETAILS OF MODULES IN A PDM/PLM SOFTWARE seed on top few commercial PLM/PDM tools - Teamcenter, Windchill, ENOVIA, agile PLM and Autodesk VaultArchitecture of PLM software- selection criterion of an name to be removed ROLE OF PLM IN INDUSTRIES PLM selection and implementation (like auto, aero, electronic) - other possible sectors feasibility study, change management for PLM, financial justification of PL ten step approach to PLM, benefits of PLM for-business, organisation, users, process.	ent, P. n and I g g Aras P software sof	o CLM, are for the state of th	t Strication O SAP or part O oning,	9 PLM ticula				
User Mana transp Ul Case Arena applic Ul Case s strates imple perfor	Functions gement, Proport, data transfer of the studies based, Oracle A station - Brans of the studies on I gy, PLM mentation, mance- proportion of the studies of the stud	- Data Vault and Document Management, Workflow and Process Management oduct Classification and Programme Management. Utility Functions - Communication anslation, image services, system administration and application integration DETAILS OF MODULES IN A PDM/PLM SOFTWARE seed on top few commercial PLM/PDM tools - Teamcenter, Windchill, ENOVIA, agile PLM and Autodesk VaultArchitecture of PLM software- selection criterion of an name to be removed ROLE OF PLM IN INDUSTRIES PLM selection and implementation (like auto, aero, electronic) - other possible sectors feasibility study, change management for PLM, financial justification of PL ten step approach to PLM, benefits of PLM for-business, organisation, users, process compliance and process automation BASICS ON CUSTOMISATION/INTEGRATION OF PDM/PLM	ent, P. n and I g g S software P	o PLM, are for arrier servi	SAP or part Oning, s to ice, pr	PLM ticula 9 PLM trocess				

TEXT I	BOOKS:					
1.	Product Lifecycle Management for a Global Market, Springer; 2014 edition (29 September 2016),ISBN-10: 3662516330					
2.	Product Life Cycles and Product Management, Praeger Publishers Inc (27 March 1989)ISBN-10: 0899303196					
REFER	REFERENCES:					
1.	AnttiSaaksvuori and AnselmiImmonen, "Product Lifecycle Management", Springer Publisher, 2008 (3rd Edition)					
2.	IvicaCrnkovic, Ulf Asklund and AnnitaPerssonDahlqvist, "Implementing and Integrating Product Data Management and Software Configuration Management", Artech House Publishers, 2003.					
3.	J ohn Stark, "Global Product: Strategy, Product Lifecycle Management and the Billion Customer Question", Springer Publisher, 2007					
4.	John Stark, "Product Lifecycle Management: 21st Century Paradigm for Product Realisation", Springer Publisher, 2011 (2nd Edition).					

5. Michael Grieves, "Product Life Cycle Management", Tata McGraw Hill, 2006.

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:					
CO1	Summarize the history, concepts and terminology of PLM	Remember				
CO2	CO2 Develop the functions and features of PLM/PDM Create					
CO3	Discuss different modules offered in commercial PLM/PDM tools.	Evaluate				
CO4	Interpret the implement PLM/PDM approaches for industrial applications.	Analyze				
CO5	Integrate PLM/PDM with legacy data bases, cax& ERP systems	Analyze				

COURSE ARTICULATION MATRIX COs/POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 PSO₁ PSO₂ PSO3 CO₁ CO₂ **CO3 CO4 CO5** 0.8 Avg 3/2/1 – indicates strength of correlation (3 – high, 2- medium, 1- low)

22MEHO3 0	6 ERGONOMICS IN DESIGN					
PREREQUI	SITES CAT	TEGORY	PE	Cr	edit	3
	Hor	us/Week	L	T	P	TI
	Hor	us/ vveek	3	0	0	3
OURSE O	BJECTIVES:					
	ely recognize and evaluate hazards (ergonomic in nature) Accurately recognic in nature) which are likely to cause occupational illnesses or injuries.	nize and eval	uate h	azards	3	
2. To intro	duce students about the essentials of Static and dynamic anthropometry and	l Posture and	job re	lation		
3. Apply the	ne knowledge, skills, and abilities obtained in through subject into an indust	trial based pr	oblem.			
UNIT I	INTRODUCING ERGONOMICS AND DISCIPLINE APPROERGONOMICS/ HUMAN FACTORS	ОАСН:	9	0	0	9
Objective, M	- Human aid to lifestyle, Journey, Fitting task to man their contractual strutual task comfort: two way dialogue, communication model, Ergonomic work physiology) and stress					
UNIT II	HUMAN PHYSICAL DIMENSION CONCERN AND POSTU MOVEMENT	JRE AND	9	0	0	9
	- structure and function, Posture and job relation, Posture and body supports surface, Horizontal work surface, Movement, Work Counter. BEHAVIOUR AND PERCEPTION AND VISUAL ISSUES, ENVIRONMENTS FACTORS		9	0	0	9
Communication and perception	on and cognitive issues, Psycho-social behaviour aspects, behaviour and st on, Cognitive aspects and mental workload, Human error and risk percep		ormat	ion pr	ocess	ing
displays, Env	ironmental factors influencing human performance.			ı		
UNIT IV	ERGONOMIC DESIGN PROCESS, PERFORMANCE SUPI AND DESIGN INTERVENTION	PORT	9	0	0	9
check, Some fatigue, error	design methodology, Ergonomics criteria/check while designing, Design checklists for task easiness. Occupational safety and stress at workplaces, discomforts and unsafe acts, Workstation design, Furniture support, ossibility, Humanising design: Design and human compatibility, comfort and	e in view to Vertical arr	reduce n reac	e the ch and	poten	tial
UNIT V	OFFICE FURNITURE GUIDELINES FOR FIT AND FUNC DESIGN ERGONOMICS IN INDIA AND UNIVERSAL DES CONSIDERATIONS		9	0	0	9
	ure Guidelines for Fit and Function Anticipate Actions, Chairs, Desk and Valesources for Designing Ergonomic Products. Design Ergonomics in India: iderations Wheelchairs Crutches, Canes, and Walkers Knobs, Handles, a	: scope for ex	plorat	ion. U	Jnive	sal
Design Cons	rces on Universal Design.					
Design Cons		Total ((45L)	= 45	Perio	ods
Design Cons		Total	(45L)	= 45	Perio	ods

TEXT B	TEXT BOOKS:							
1.	Bridger, RS: Introduction to Ergonomics, 2nd Edition, Taylor &Francis, 2003.							
2.	Dul, J. and Weerdmeester, B. Ergonomics for beginners, a quick reference guide, Taylor & Francis, 1993.							
REFER	ENCES:							
1.	Green, W.S. and Jordan, P.W, Human Factors in Product Design, Taylor & rancis, 1999.							
2.	D. Chakrabarti, Indian Anthropometric Dimensions for ergonomic design practice, National Institute of Design,							

	Ahmedabad, 1997
3.	G. Salvendy (edit), Handbook of Human Factors and ergonomics, John Wiley & Sons, Inc., 1998.

	COURSE OUTCOMES: Upon completion of this course, the students will be able to:			
CO1	Learn about the basics of Human aid to lifestyle, Physiology and stress	Understand		
CO2	Learn about the anthropometry: body growth and somatotypes, further about Vertical work surface, Horizontal work surface can also be obtained.	Remember		
СОЗ	Study about the communication and cognitive issues, it promotes about environmental factors influencing human performance.	Understand		
CO4	Learn about the Ergonomics design methodology and gives fathom notion on Occupational safety and stress at workplace	Apply		
CO5	Study about Office furniture guidelines for fit and function and universal design considerations	Apply		

COURSE A	ARTI	CULA	ATIO	N MA	TRIX	K									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	0	0	0	0	3	2	2	0	0	0	2	1	2	1
CO2	1	0	0	0	0	3	2	2	0	0	0	2	1	2	1
CO3	1	0	0	0	0	3	2	2	0	0	0	2	1	2	1
CO4	1	0	0	0	0	3	2	2	0	0	0	2	1	2	1
CO5	1	0	0	0	0	3	2	2	0	0	0	2	1	2	1
Avg	1	0	0	0	0	3	2	2	0	0	0	2	1	2	1
	•			3/2/1	– indi	cates	streng	th of c	orrela	tion (3 -	high,	2- mediı	ım, 1- lov	<i>x</i>)	•

22M	EHO307	SURFACE ENGINEERING					
PRE	REQUISI	TES CATEGORY	PE	E Cre	edit	3	
			L	Т	P	TH	
		Hours/Week	3	0	0	3	
COU	RSE OBJ	ECTIVES:	l	1		1	
1.	To teach	students fundamental about surface properties in engineering applications and Wear	modes				
2. To introduce students about the essentials of electroplating and Other plating processes							
3.	To teach about the thin film for wear application, Coating specifications.						
4.	To teach						
5.	To teach	about the hard facing processes and applications					
UNIT I BASICS OF SURFACE ENGINEERING					0	9	
erosi	on, Fretting	ategories of wear, Low stress, High stress and Gouging abrasion, Cavitation, Slurry eg wear, Adhesive wear, Seizure, Galling, Oxidative wear, Spalling, Impact wear brine		, Impi	<u> </u>	1	
UNIT II PLATING PROCESSES					0	9	
		f electroplating, Electro deposition from plating baths, Electroless plating, Mentallidic, Other plating processes, Applicability of plating for wear resistance.	ng, Sel	ective	e plati	ing,	
UN	IT III	THIN FILM COATINGS	9	0	0	9	
Ther	mal evapor	ration, PVD and CVD, Sputter coating, Ion plating, Thin film for wear application, Co	ating s	pecif	icatio	ns.	
UN	IT IV	SPECIAL SURFACING PROCESSES	9	0	0	9	
		surface cements, Wear tiles, Electrospark deposition coatings, Fused carbide clo	th cera	mic	coatir	ngs,	
UN	NIT V	HARD FACING PROCESSES AND APPLICATIONS	9	0	0	9	
weld Hard	ing, Plasm facing tran	arc welding, Gas tungsten arc welding, Gas metal arc welding, Flux coaxed are well a arc welding oxyacetylene welding, Furnace fusing, Thermal spray processes an asformation, Fusion alloys, Non fusion materials. Hardfacing in new designs, Hardfusion processes, Nonfusion deposits, Weldability considerations, Finishing considerations.	d their	r app	licatio	ons,	

TEXT E	TEXT BOOKS:								
1.	Budinski, K.G., Surface Engineering for Wear Resistance, Prentice Hall (1988).								
2.	Mathews, A., Advanced Surface Coatings: A Hand book of Surface Engineering, Spinger (1991)								
REFER	REFERENCES:								
1.	Hocking, M.G., Metallic and Ceramic Coatings, John Wiley (1989)								
2.	Strafford, K.N., Datta, P.K., and Gray, J.S., Surface Engineering Practice, Processes, Fundamentals and Applications in Corrosion and Wear, Ellis Harwood (1990).								

COUR	COURSE OUTCOMES:						
Upon o	Upon completion of this course, the students will be able to:						
CO1	Learn about the basics and Current status of surface engineering. Wear modes	Understand					
CO2	Learn about the Fundamentals of electroplating and Other plating processes	Understand					
CO3	Study about the Thermal evaporation and wear application, Coating specifications.	Remember					
CO4	Learn about the rebuilding and surface cements, Wear sleeves, Wear plates	Understand					

Study about Shielded metal arc welding, Gas tungsten arc welding and Nonfusion deposits, Weldability considerations, Finishing considerations.	Understand
deposits, weldability considerations, i misming considerations.	

COURSE A	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	1	2	0	1	0	0	0	0	0	0	0	2	1	0
CO2	1	1	2	0	1	0	0	0	0	0	0	0	2	1	0
CO3	1	1	2	0	1	0	0	0	0	0	0	0	2	1	0
CO4	1	1	2	0	1	0	0	0	0	0	0	0	2	1	0
CO5	1	1	2	0	1	0	0	0	0	0	0	0	2	1	0
Avg	1	1	2	0	1	0	0	0	0	0	0	0	2	1	0
3/2/1 – indicates strength of correlation (3 – high, 2- medium, 1- low)															

Region Product Produ		ЕНО308	INDUSTRIAL LAYOUT DESIGN AND SA	FETY						
2. Knowledge in operations research 3. Knowledge in safety regulations. COURSE OBJECTIVES: 1. To get the basics of process layout & product layout 2. To explore the layout planning by computer applications following different algorithms. 3. To imbibe knowledge on safety management functions and its techniques. 4. To introduce knowledge on accident reporting & investigation procedure. 5. To assimilate knowledge on workplace hazards & its control UNIT I INTRODUCTION 9 0 0 Objectives of a good plant layout, principles of a good layout, Classification of Layout, Advantages and Limitations different layouts, Layout design procedures, Overview of the plant layout. Process layout & Product layout: Selecti specification, Implementation and follow up, comparison of product and process layout. UNIT II COMPUTERIZED LAYOUT PLANNING 9 0 0 Heuristics for Plant layout – ALDEP, CORELAP, CRAFT, Group Layout, Fixed position layout-Quadratic assignm model. Branch and bound method, Evaluation of layout. UNIT III SAFETY REGULATIONS 9 0 0 Need for safety. Safety and productivity. Definitions: Accident, Injury, Unsafe act, Unsafe Condition, Danger Occurrence, Reportable accidents. Theories of accident causation. Safety organization- objectives, types, functions, R of management, supervisors, workmen, unions, government and voluntary agencies in safety. Safety policy. Safety	1	REQUIS	ITES	CATEGORY	PE	Cr	edit	3		
2. Knowledge in operations research 3. Knowledge in safety regulations. COURSE OBJECTIVES: 1. To get the basics of process layout & product layout 2. To explore the layout planning by computer applications following different algorithms. 3. To imbibe knowledge on safety management functions and its techniques. 4. To introduce knowledge on accident reporting & investigation procedure. 5. To assimilate knowledge on workplace hazards & its control UNIT I INTRODUCTION 9 0 0 Objectives of a good plant layout, principles of a good layout, Classification of Layout, Advantages and Limitations different layouts, Layout design procedures, Overview of the plant layout. Process layout & Product layout: Selecti specification, Implementation and follow up, comparison of product and process layout. UNIT II COMPUTERIZED LAYOUT PLANNING 9 0 0 Heuristics for Plant layout – ALDEP, CORELAP, CRAFT, Group Layout, Fixed position layout-Quadratic assignm model. Branch and bound method, Evaluation of layout. UNIT III SAFETY REGULATIONS 9 0 0 Need for safety. Safety and productivity. Definitions: Accident, Injury, Unsafe act, Unsafe Condition, Danger Occurrence, Reportable accidents. Theories of accident causation. Safety organization- objectives, types, functions, R of management, supervisors, workmen, unions, government and voluntary agencies in safety. Safety policy. Safety		1. Know	eledge in basic manufacturing systems.		L	Т	P	TH		
COURSE OBJECTIVES: 1. To get the basics of process layout & product layout 2. To explore the layout planning by computer applications following different algorithms. 3. To imbibe knowledge on safety management functions and its techniques. 4. To introduce knowledge on accident reporting & investigation procedure. 5. To assimilate knowledge on workplace hazards & its control UNIT I INTRODUCTION Objectives of a good plant layout, principles of a good layout, Classification of Layout, Advantages and Limitations different layouts, Layout design procedures, Overview of the plant layout. Process layout & Product layout: Selecti specification, Implementation and follow up, comparison of product and process layout. UNIT II COMPUTERIZED LAYOUT PLANNING P 0 0 Heuristics for Plant layout – ALDEP, CORELAP, CRAFT, Group Layout, Fixed position layout- Quadratic assignm model. Branch and bound method, Evaluation of layout. UNIT III SAFETY REGULATIONS P 0 0 Need for safety. Safety and productivity. Definitions: Accident, Injury, Unsafe act, Unsafe Condition, Danger Occurrence, Reportable accidents. Theories of accident causation. Safety organization- objectives, types, functions, R of management, supervisors, workmen, unions, government and voluntary agencies in safety. Safety policy. Safety	2	2. Know	eledge in operations research	Hours/Week	3	0	0	3		
1. To get the basics of process layout & product layout 2. To explore the layout planning by computer applications following different algorithms. 3. To imbibe knowledge on safety management functions and its techniques. 4. To introduce knowledge on accident reporting & investigation procedure. 5. To assimilate knowledge on workplace hazards & its control UNIT I INTRODUCTION 9 0 0 Objectives of a good plant layout, principles of a good layout, Classification of Layout, Advantages and Limitations different layouts, Layout design procedures, Overview of the plant layout. Process layout & Product layout: Selecti specification, Implementation and follow up, comparison of product and process layout. UNIT II COMPUTERIZED LAYOUT PLANNING 9 0 0 Heuristics for Plant layout – ALDEP, CORELAP, CRAFT, Group Layout, Fixed position layout-Quadratic assignm model. Branch and bound method, Evaluation of layout. UNIT III SAFETY REGULATIONS 9 0 0 Need for safety. Safety and productivity. Definitions: Accident, Injury, Unsafe act, Unsafe Condition, Danger Occurrence, Reportable accidents. Theories of accident causation. Safety organization- objectives, types, functions, R of management, supervisors, workmen, unions, government and voluntary agencies in safety. Safety policy. Safety	3	3. Know	rledge in safety regulations.		I		<u>l</u>	ı		
2. To explore the layout planning by computer applications following different algorithms. 3. To imbibe knowledge on safety management functions and its techniques. 4. To introduce knowledge on accident reporting & investigation procedure. 5. To assimilate knowledge on workplace hazards & its control UNIT I INTRODUCTION 9 0 0 Objectives of a good plant layout, principles of a good layout, Classification of Layout, Advantages and Limitations different layouts, Layout design procedures, Overview of the plant layout. Process layout & Product layout: Selecti specification, Implementation and follow up, comparison of product and process layout. UNIT II COMPUTERIZED LAYOUT PLANNING 9 0 0 Heuristics for Plant layout – ALDEP, CORELAP, CRAFT, Group Layout, Fixed position layout- Quadratic assignm model. Branch and bound method, Evaluation of layout. UNIT III SAFETY REGULATIONS 9 0 0 Need for safety. Safety and productivity. Definitions: Accident, Injury, Unsafe act, Unsafe Condition, Danger Occurrence, Reportable accidents. Theories of accident causation. Safety organization- objectives, types, functions, R of management, supervisors, workmen, unions, government and voluntary agencies in safety. Safety policy. Safety	COUR	RSE OBJ	ECTIVES:							
3. To imbibe knowledge on safety management functions and its techniques. 4. To introduce knowledge on accident reporting & investigation procedure. 5. To assimilate knowledge on workplace hazards & its control UNIT I INTRODUCTION Objectives of a good plant layout, principles of a good layout, Classification of Layout, Advantages and Limitations different layouts, Layout design procedures, Overview of the plant layout. Process layout & Product layout: Selecti specification, Implementation and follow up, comparison of product and process layout. UNIT II COMPUTERIZED LAYOUT PLANNING Pull layout – ALDEP, CORELAP, CRAFT, Group Layout, Fixed position layout-Quadratic assignment. Branch and bound method, Evaluation of layout. UNIT III SAFETY REGULATIONS Pull layout – Alder of layout – Alder of layout. UNIT III SAFETY REGULATIONS Pull layout – Alder of layout – Alder of layout. UNIT III SAFETY REGULATIONS Pull layout – Alder of layout – Alder of layout. UNIT III SAFETY REGULATIONS Pull layout – Alder of layout – Alder of layout. UNIT III SAFETY REGULATIONS Pull layout – Alder of layout – Alder of layout. UNIT III SAFETY REGULATIONS Safety safety and productivity. Definitions: Accident, Injury, Unsafe act, Unsafe Condition, Danger Occurrence, Reportable accidents. Theories of accident causation. Safety organization- objectives, types, functions, Rof management, supervisors, workmen, unions, government and voluntary agencies in safety. Safety policy. Safety	1.	To get th	ne basics of process layout & product layout							
4. To introduce knowledge on accident reporting & investigation procedure. 5. To assimilate knowledge on workplace hazards & its control UNIT I INTRODUCTION Objectives of a good plant layout, principles of a good layout, Classification of Layout, Advantages and Limitations different layouts, Layout design procedures, Overview of the plant layout. Process layout & Product layout: Selectispecification, Implementation and follow up, comparison of product and process layout. UNIT II COMPUTERIZED LAYOUT PLANNING 9 0 0 Heuristics for Plant layout – ALDEP, CORELAP, CRAFT, Group Layout, Fixed position layout-Quadratic assignment and bound method, Evaluation of layout. UNIT III SAFETY REGULATIONS 9 0 0 Need for safety. Safety and productivity. Definitions: Accident, Injury, Unsafe act, Unsafe Condition, Danger Occurrence, Reportable accidents. Theories of accident causation. Safety organization- objectives, types, functions, R of management, supervisors, workmen, unions, government and voluntary agencies in safety. Safety policy. Safety	2.	To explo	re the layout planning by computer applications following differe	nt algorithms.						
5. To assimilate knowledge on workplace hazards & its control UNIT I INTRODUCTION Objectives of a good plant layout, principles of a good layout, Classification of Layout, Advantages and Limitations different layouts, Layout design procedures, Overview of the plant layout. Process layout & Product layout: Selectis specification, Implementation and follow up, comparison of product and process layout. UNIT II COMPUTERIZED LAYOUT PLANNING 9 0 0 Heuristics for Plant layout – ALDEP, CORELAP, CRAFT, Group Layout, Fixed position layout-Quadratic assignment and bound method, Evaluation of layout. UNIT III SAFETY REGULATIONS 9 0 0 Need for safety. Safety and productivity. Definitions: Accident, Injury, Unsafe act, Unsafe Condition, Danger Occurrence, Reportable accidents. Theories of accident causation. Safety organization- objectives, types, functions, R of management, supervisors, workmen, unions, government and voluntary agencies in safety. Safety policy. Safety	3.	To imbib	be knowledge on safety management functions and its techniques.							
UNIT I INTRODUCTION Objectives of a good plant layout, principles of a good layout, Classification of Layout, Advantages and Limitations different layouts, Layout design procedures, Overview of the plant layout. Process layout & Product layout: Selecti specification, Implementation and follow up, comparison of product and process layout. UNIT II COMPUTERIZED LAYOUT PLANNING 9 0 0 Heuristics for Plant layout – ALDEP, CORELAP, CRAFT, Group Layout, Fixed position layout- Quadratic assignment and bound method, Evaluation of layout. UNIT III SAFETY REGULATIONS 9 0 0 Need for safety. Safety and productivity. Definitions: Accident, Injury, Unsafe act, Unsafe Condition, Danger Occurrence, Reportable accidents. Theories of accident causation. Safety organization- objectives, types, functions, R of management, supervisors, workmen, unions, government and voluntary agencies in safety. Safety policy. Safety	4.	To introduce knowledge on accident reporting & investigation procedure.								
Objectives of a good plant layout, principles of a good layout, Classification of Layout, Advantages and Limitations different layouts, Layout design procedures, Overview of the plant layout. Process layout & Product layout: Selective specification, Implementation and follow up, comparison of product and process layout. UNIT II COMPUTERIZED LAYOUT PLANNING Pull of the plant layout of product and process layout. UNIT III SAFETY REGULATIONS Pull of the plant layout, Fixed position layout of position layout of position layout. UNIT III SAFETY REGULATIONS Pull of the plant layout, Process layout & Product layout: Selective specification, Implementation and follow up, comparison of product and process layout. UNIT III SAFETY REGULATIONS Pull of the plant layout, Process layout & Product layout: Selective specification, Implementation and bound method, Evaluation of product and process layout. UNIT III SAFETY REGULATIONS Pull of the plant layout, Process layout, Process layout & Product layout: Selective specification, Implementation and product layout. UNIT III SAFETY REGULATIONS Pull of the plant layout, Process layout, Process layout & Product layout: Selective specification, Implementation and product layout. Pull of the plant layout, Process layout, Process layout, Process layout & Product layout: Selective specification, Implementation and Product layout. Pull of the plant layout, Process layout, Proc	5.	To assim	ilate knowledge on workplace hazards & its control							
different layouts, Layout design procedures, Overview of the plant layout. Process layout & Product layout: Selectispecification, Implementation and follow up, comparison of product and process layout. UNIT II COMPUTERIZED LAYOUT PLANNING Pull layout – ALDEP, CORELAP, CRAFT, Group Layout, Fixed position layout-Quadratic assignment model. Branch and bound method, Evaluation of layout. UNIT III SAFETY REGULATIONS Pull layout – ALDEP, CORELAP, CRAFT, Group Layout, Fixed position layout-Quadratic assignment model. Branch and bound method, Evaluation of layout. UNIT III SAFETY REGULATIONS Pull layout – ALDEP, CORELAP, CRAFT, Group Layout, Fixed position layout-Quadratic assignment model. Branch and bound method, Evaluation of layout. UNIT III SAFETY REGULATIONS Pull layout – ALDEP, CORELAP, CRAFT, Group Layout, Fixed position layout-Quadratic assignment model. Branch and bound method, Evaluation of layout. UNIT III SAFETY REGULATIONS Pull layout – ALDEP, CORELAP, CRAFT, Group Layout, Fixed position layout-Quadratic assignment model. Branch and bound method, Evaluation of layout. UNIT III SAFETY REGULATIONS Pull layout – ALDEP, CORELAP, CRAFT, Group Layout, Fixed position layout-Quadratic assignment model. Branch and bound method, Evaluation of layout. Pull layout – ALDEP, CORELAP, CRAFT, Group Layout, Fixed position layout-Quadratic assignment model. Branch and bound method, Evaluation of layout. Pull layout – ALDEP, CORELAP, CRAFT, Group Layout, Fixed position layout-Quadratic assignment model. Branch and bound method, Evaluation of layout. Safety Planta layout – ALDEP, CORELAP, CRAFT, Group Layout, Fixed position layout-Quadratic assignment model. Branch and bound method, Evaluation of layout. Safety Planta layout – ALDEP, CORELAP, CRAFT, Group Layout, Fixed position layout-Quadratic assignment model. Branch layout – ALDEP, CORELAP, CRAFT, Group Layout, Fixed position layout-Quadratic assignment model. Branch layout – ALDEP, CORELAP, CRAFT, Group Layout, Fixed position layout-Quadratic assignment m	UN	ITI	INTRODUCTION		9	0	0	9		
Heuristics for Plant layout – ALDEP, CORELAP, CRAFT, Group Layout, Fixed position layout- Quadratic assignment model. Branch and bound method, Evaluation of layout. UNIT III SAFETY REGULATIONS 9 0 0 Need for safety. Safety and productivity. Definitions: Accident, Injury, Unsafe act, Unsafe Condition, Danger Occurrence, Reportable accidents. Theories of accident causation. Safety organization- objectives, types, functions, R of management, supervisors, workmen, unions, government and voluntary agencies in safety. Safety policy. Safety	specif	fication, I	mplementation and follow up, comparison of product and process		1			on, 9		
Need for safety. Safety and productivity. Definitions: Accident, Injury, Unsafe act, Unsafe Condition, Dangero Occurrence, Reportable accidents. Theories of accident causation. Safety organization- objectives, types, functions, R of management, supervisors, workmen, unions, government and voluntary agencies in safety. Safety policy. Saf	Heuris	stics for I	l Plant layout – ALDEP, CORELAP, CRAFT, Group Layout, Fixe	ed position layout- (Ť		_		
Occurrence, Reportable accidents. Theories of accident causation. Safety organization- objectives, types, functions, R of management, supervisors, workmen, unions, government and voluntary agencies in safety. Safety policy. Saf	UNIT III		SAFETY REGULATIONS	9	0	0	9			
Officer, Safety committee, Overview of factories act 1948 – ISO-45001.	Occur of ma	rrence, Re anagemen	portable accidents. Theories of accident causation. Safety organi	zation- objectives, t	pes, f	unctio	ns, R	ole		
UNIT IV SAFETY HARAZDS IN MACHINES 9 0 0	Office	IT IV	SAFETY HARAZDS IN MACHINES	9	0	0	9			
Machine Guarding, Guarding of hazards, Machine Guarding types and its application – Safety in welding and Gas cutt – Safety in Manual and Mechanical material handling- Safety in use of electricity					ding a	nd Ga	s cutt	ing		
UNIT V CHEMICAL AND FIRE HAZARDS 9 0 0	UNI Machi	oty in iviai	idar and ividentament material manaring surely in use of electrony							
Toxicity- TLV- Types of Chemical Hazards-Occupational diseases caused by dust, fumes, gases, smoke and solv hazards- control measures Fire triangle- Types of fire - first aid fire fighting equipment – flammability limit- LPG safet Hazard identification and Risk Analysis, case studies	UNI Machi – Safe				9	0	0	9		
Total (45L) = 45Perio	UNI Machi – Safe UNI Toxici hazaro	IT V	CHEMICAL AND FIRE HAZARDS - Types of Chemical Hazards-Occupational diseases caused by I measures Fire triangle- Types of fire - first aid fire fighting equi		, smok	te and	solv	er		

TEXT I	BOOKS:
1.	James M Moore-Plant Layout Design, Mac Millan Co.1962 LCCCN61-5204.
2.	Krishnan N.V. "Safety Management in Industry" Jaico Publishing House, Bombay, 1997
REFER	ENCES:
1.	James Apple, "Plant Layout & Material Handling", The Ronalt Press Co., New Delhi, 1998.
2.	Pannerselvam. R, "Production and Operations Management", PHI, 2017
3.	Sunderesh Heragu-Facilities Design, PWS Publishing Company, ISBN-0-534-95183.
4.	Heinrich H.W. "Industrial Accident Prevention" McGraw-Hill Company, New York, 1980.
5.	Blake R.B., "Industrial Safety" Prentice Hall, Inc., New Jersey, 1973
6.	John Ridley, "Safety at Work", Butterworth & Co., London, 1983.

	RSE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Able to get the basics of layout design procedure and selection of appropriate layout for industries.	Create
CO2	The students will be able to plan and design plant and production layouts through basic strategies and with computer application	Create
СОЗ	Apply principles of safety management, its functions and technique in any organization.	Apply
CO4	Apply machine guarding principles in industrial applications.	Apply
CO5	Realize chemical hazards, toxicity, fire and explosion in the work place and involve to take various control measures to prevent hazards	Understand

COURSE ARTICULATION MATRIX	

COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	1	2	3	2	1	1	2	2	2	2	3	2	2
CO2	0	1	2	3	0	1	0	1	2	0	2	0	1	2	1
CO3	0	2	2	1	3	1	1	1	1	0	1	2	2	3	2
CO4	0	2	1	1	2	0	0	1	1	1	2	0	2	1	1
CO5	1	2	2	1	2	0	0	1	1	1	1 2 1 3		2	1	
Avg	0.4	1.8	1.6	1.6	2.0	0.8	0.4	1.0	1.4	0.8	1.8	1.0	2.2	1.0	1.4

3/2/1-indicates strength of correlation (3 - high, 2- medium, 1- low)

22MEHO309 DIGITAL MANUFACTURING AND IOT				
PREREQUISITES CATEGORY	PE	Cr	edit	3
	L	Т	P	ТН
Hours/Week	3	0	0	3
COURSE OBJECTIVES:		1		1
1. To study the various aspects of digital manufacturing.				
2. To inculcate the importance of DM in Product Lifecycle Management and Supply chain Management	gement	į		
3. To formulate of smart manufacturing systems in the digital work environment				
4. To interpret IOT to support the digital manufacturing				
5. To elaborate the significance of digital twin				
UNIT I INTRODUCTION	9	0	0	9
Introduction – Need – Overview of Digital Manufacturing and the Past – Aspects of Digital Manufacturing – Tactical Benefits of Digital Manufacturing – Tacti	The Fu	ture o	of Dig	gital 9
and Product reuse – Engineering Change Management, Bill of Material and Process Consistency – Prototype development – Virtual testing and collateral. Overview of Digital Supply Chain - Scope& SC - Effective Digital Transformation - Future Practices in SCM	Digital	Moc	k up	and
UNIT III SMART FACTORY	9	0	0	9
Smart Factory – Levels of Smart Factories – Benefits – Technologies used in Smart Factory – Smart Principles of a Smart Factory – Creating a Smart Factory – Smart Factories and Cybersecurity	Factor	y in 1	oT- I	Key
UNIT IV INDUSTRY 4.0	9	0	0	9
Introduction – Industry 4.0 –Internet of Things – Industrial Internet of Things – Framework: Conreservices – Intelligent networks of manufacturing – Cloud computing – Data analytics –Cyber physics to Machine communication – Case Studies.				
UNIT V STUDY OF DIGITAL TWIN	9	0	0	9
Basic Concepts – Features and Implementation – Digital Twin: Digital Thread and Digital Shadow Types – Characteristics of a Good Digital Twin Platform – Benefits, Impact & Challenges – Future o				
-7,				

TEXT B	TEXT BOOKS:									
1.	Zude Zhou, Shane (Shengquan) Xie and Dejun Chen, Fundamentals of Digital Manufacturing Science, Springer-Verlag London Limited, 2012.									
2.	Alasdair Gilchrist, "Industry 4.0: The Industrial Internet of Things", A press, 2016.									
REFER	REFERENCES:									
1.	Lihui Wang and Andrew YehChing Nee, Collaborative Design and Planning for Digital Manufacturing, Springer-Verlag London Limited, 2009.									
2.	Andrew Yeh Chris Nee, Fei Tao, and Meng Zhang, "Digital Twin Driven Smart Manufacturing", Elsevier Science., United States, 2019.									
3.	Alp Ustundag and Emre Cevikcan, "Industry 4.0: Managing The Digital Transformation", Springer Series in Advanced Manufacturing., Switzerland, 2017									
4.	Ronald R. Yager and Jordan Pascual Espada, "New Advances in the Internet of Things", Springer., Switzerland, 2018.									

5. Ronald R. Yager and Jordan Pascual Espada, "New Advances in the Internet of Things", Springer., Switzerland, 2018

	SE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Impart knowledge to use various elements in the digital manufacturing.	Understand
CO2	Differentiate the concepts involved in digital product development life cycle process and supply chain management in digital environment.	Analyze
СОЗ	Select the proper procedure of validating practical work through digital validation in Factories.	Apply
CO4	Implementation the concepts of iot and its role in digital manufacturing.	Apply
CO5	Analyse and optimize various practical manufacturing process through digital twin.	Analyze

COURSE A	ARTI	CULA	ATIO	N MA	TRIX	X .									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	1	0	0	0	0	2	0	0	0	2	2	2	2	2
CO2	1	1	0	0	0	0	2	0	0	0	2	2	2	2	2
CO3	1	1	0	0	0	0	2	0	0	0	2	2	2	2	2
CO4	1	1	0	0	0	0	2	0	0	0	2	2	2	2	2
CO5	1	1	0	0	0	0	2	0	0	0	2	2	2	2	2
Avg	1	1	0	0	0	0	2	0	0	0	2	2	2	2	2
				3/2/1	– indi	cates	streng	th of c	orrela	tion (3 -	– high, í	2- mediı	ım, 1- lov	w)	

22MEHO310	SMART MOBILITY AND INTELLIGENT VE	HICLES				
PREREQUIS	SITES	CATEGORY	PE	Cre	edit	3
		Hours/Week	L	Т	P	TH
		Hours, Week	3	0	0	3
OURSE OB	JECTIVES:					
1. To introduce vehicles	duce students to the various technologies and systems used to imple	ement smart mobility	y and i	ntellig	ent	
	Basics of Radar Technology and Systems, Ultrasonic Sonar System and other sensors for automobile vision system	ns, LIDAR Sensor T	echnol	logy a	nd	
3. To learn	Basic Control System Theory applied to Autonomous Automobiles	1				
	ce overall impact of automating like various driving functions, con on that assist with a task	necting the automob	oile to	source	es of	
	the automobile to make autonomous intelligent decisions concerning impact the safety of the occupants through connected car & automobile to make autonomous intelligent decisions concerning the safety of the occupants through connected car & automobile to make autonomous intelligent decisions concerning the safety of the occupants through connected car & automobile to make autonomous intelligent decisions concerning the safety of the occupants through connected car & automobile to make autonomous intelligent decisions concerning the safety of the occupants through connected car & automobile to make autonomous intelligent decisions concerning the safety of the occupants through connected car & automobile to the occupants through car & automobile through car & automobile to the occupants through the occupant				hat	
UNIT I	9	0	0	9		
Powertrain El	utomotive Electronics, Electronics Overview, History & Evolu ectronics, Introduction to Automated, Connected, and Intellige d Intelligent Vehicles					
UNIT II	SENSOR TECHNOLOGY FOR SMART MOBILITY		9	0	0	9
	ar Technology and Systems, Ultrasonic Sonar Systems, Lidar Se Night Vision Technology, Other Sensors, Use of Sensor Data Fu Systems					
UNIT III	CONNECTED AUTONOMOUS VEHICLE		9	0	0	9
	System Theory applied to Automobiles, Overview of the Operation autonomous Vehicles, Role of Surroundings Sensing Systems a Autonomy.					
UNIT IV	VEHICLE WIRELESS TECHNOLOGY AND NETWO	ORKING	9	0	0	9
System Conce Computer Net	em Block Diagram and Overview of Components, Transmission Sycpts— Demodulation/Decoding, Wireless Networking and Applications working— the Internet of Things, Wireless Networking Fundamen Vehicle Networks	ations to Vehicle A	utono	ny, B	asics	of
UNIT V	CONNECTED CAR AND AUTONOMOUS VEHICLE TECHNOLOGY		9	0	0	9
Vehicle-to-Ro	Fundamentals, Navigation and Other Applications, Vehicle-to- adside and Vehicle-to-Infrastructure Applications, Autonomous Roadblock Issues, Technical Issues, Security Issues					
		Total	(45L)	= 451	Perio	ds
EXT BOOK	S:					
1. "Inte Board	lligent Transportation Systems and Connected and Automated Veh	icles", 2016, Transp	ortatio	n Res	earch	!
2. Rado	van Miucic, "Connected Vehicles: Intelligent Transportation System	ns", 2019, Springer				
EFERENCI	ES:					
1. Tom	Denton, "Automobile Electrical and Electronic systems, Roultedge	", Taylor & Francis	Group	, 5th E	Editio	n,

2018.

	SE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Recognize the concept of cyber-physical control systems and their application to collision avoidance and autonomous vehicles	Understand
CO2	Select the concept of remote sensing and the types of sensor technology needed to implement remote sensing	Understand
CO3	Familiar with the concept of fully autonomous vehicles	Understand
CO4	Apply the basic concepts of wireless communications and wireless data networks	Apply
CO5	Analyse the concept of the connected vehicle and its role in automated vehicles	Analyse

COURSE A	ARTI	CULA	ATIO	N MA	TRIX	K									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	2	0	2	1	0	0	0	0	1	2	2	2	0
CO2	2	2	2	0	2	1	0	0	0	0	1	2	2	2	0
CO3	2	2	2	0	2	1	0	0	0	0	1	2	2	2	0
CO4	2	2	2	0	2	1	0	0	0	0	1	2	2	2	0
CO5	2	2	2	0	2	1	0	0	0	0	1	2	2	2	0
Avg	2	2	2	0	2	1	0	0	0	0	1	2	2	2	0
	•		•	3/2/1	– indi	cates	streng	th of c	orrela	tion (3 -	high,	2- mediu	ım, 1- lov	w)	

MINOR DEGREE COURSES

		WITHOR DEGREE COURSE.	<u>2</u>									
22ME	MIO1	ENGINEERING THERMODYNAMIC										
ZZIVIC	IVIIUI	(Use of standard thermodynamic tables, Mollier diagram of										
PRE-F	REQUIS	SITE:	CATEGORY	PE	Cr	edit		C				
				L	T	P	7	ГН				
			Hours/Week	3	0	0		3				
Course	e Objec	tives:					•					
1.	To impart the knowledge on concepts of zeroth and first law of thermodynamics.											
2.	To make the learners to understand the third law of thermodynamics and analyze the various work and heat interactions in closed and open systems.											
3.	To teac	h properties of pure substance.										
4.	To imp	art knowledge on the concepts of steam power cycle.										
5.	To deri	ve thermodynamic relations for ideal and real gases.										
UNIT	I	BASIC CONCEPT AND FIRST LAW			9	0	0	9				
Thermo	odynamic nt. First la	roscopic approach, thermodynamic systems, Property, state, equilibrium, Displacement work, P-V diagram. Zeroth law of aw of thermodynamics – application to closed and open system equipment.	thermodynamics -	- conce	pt of	temp	era	ture				
UNIT	II	SECOND LAW AND ENTROPY			9	0	0	9				
of thes	e statem	efrigerator – Heat Pump, Second law of thermodynamics – Kelvents their corollaries. Reversibility and irreversibility. Carno ept of entropy, principle of increase of entropy, T-s diagram, T-	t cycle, reversed	Carno								
UNIT	III	PROPERTIES OF PURE SUBSTANCES			9	0	0	9				
	fraction	on and its thermodynamic properties - p-v, p-T, T-v, T-s, h-s. Calculation of work done and heat transfer in non-flow an										
UNIT	IV	STEAM POWER CYCLE			9	0	0	9				
	Rankine ation cyc	cycle, T-s & h-s diagrams - Performance Improvement - R les.	eheat cycle, reger	nerative	сус	le an	ıd t	their				
UNIT	UNIT V IDEAL AND REAL GASES AND THERMO DYNAMIC RELATIONS $9 \mid 0 \mid 0 \mid 9$											
states,	Principle	eal and real gases, equation of state of ideal and real gases, As of corresponding states, reduced properties and compressil ic heat equations, Tds, relations, ClausiusClapeyron equations a	oility chart. Exact	differ	entia	ls, M						
			To	tal (45	L)=	45 P	eri	ods				

Text I	Text Books:										
1.	Nag. P.K, "Engineering Thermodynamics", Tata McGraw-Hill, New Delhi, 2017.										
2.	Sonntag, R.E., Borgnakke, C., and Van Wylen, G.J., Fundamentals of Thermodynamics, 6th ed., John Wiley, 2003.										
3.	Arora C.P, "Thermodynamics", Tata McGraw Hill, New Delhi, 2003.										
4.	Venwylen and Sontag, "Classical Thermodynamics", Wiley Eastern, 1987.										
Refere	Reference Books:										
1.	Cengel, "Thermodynamics- An Engineering Approach", 3rd Edition, Tata McGraw Hill,2015.										

2	Merala C, Pother, Craig W and Somerton, "Thermodynamics for Engineers", Schaum	Outline Series, Tata
۷.	McGrawHill, New Delhi, 2004.	

	SE OUTCOMES: completion of this course, the students will be able to:	Bloom Taxonomy Mapped
CO1	Understand the concepts of zeroth, first and second law of thermodynamics.	Remember
CO2	Analyze the various work and heat interactions for different types of processes for closed and open systems	Evaluate
CO3	Evaluate the different properties of pure substances using steam tables and Mollier chart	Evaluate
CO4	Analyze the performance of steam power cycle.	Analyze
CO5	Derive thermodynamic relations for ideal and real gases.	Analyze

COURSE A	ARTI	CULA	ATIO	N MA	TRIX	K									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	2	2	0	0	1	0	0	0	0	1	3	1	1
CO2	3	3	2	2	0	0	1	0	0	0	0	1	3	1	1
CO3	3	3	3	2	0	1	1	0	0	0	0	1	3	1	1
CO4	2	3	2	2	0	1	1	0	0	0	0	1	3	1	1
CO5	3	3	2	2	0	1	0	0	0	0	0	1	3	1	1

2.2

0.6

0.8

2.8

Avg

3/2/1 – indicates strength of correlation (3 – high, 2- medium, 1- low)

22ME	MI02	FLUID MECHANICS AND MACHI	NERY				
PRE-I	REQUIS	SITE:	CATEGORY	PE	Cro	edit	С
1.Engii	neering Pl	hysics		L	T	P	TH
2.Engii	neering C	hemistry	Hours/Week	3	0	0	3
3.Engii	neering M	lathematics		•			
Cours	e Objec	tives:					
1.	To und	erstand the basic concepts and properties of fluids					
2.	To anal	yze the kinematic and dynamic concepts of fluid flow					
3.	To und	erstand the various incompressible fluid flow through pipes	and between parallel	plates			
4.	To app	ly the principles of fluid mechanics to design and operation	of hydraulic turbines				
5.	To app	ly the principles of fluid mechanics to design and operation	of hydraulic pumps				
UNIT	Ι	INTRODUCTION AND FLUID STATICS			9	0	0 9
relative	density,	and units of measurement of physical quantities- Classific vapour pressure, surface tension, Capillarity and viscosity principle.					
UNIT	II	FLUID KINEMATICS AND DYNAMICS			9	0	0 9
pattern: equatio	s- stream on and it	f fluid flow - system and control volume - Lagrangian a line, pathline, streakline and timeline. Velocity potenti s applications. Fluid dynamics - Bernoulli's equation neorem, dimensional homogeneity, similarity-laws and mod	al function and Strea and its applications.	ım func	tion	- co	ntinuit
UNIT	III	FLOW THROUGH PIPES AND PLATES			9	0	0 9
through total er	n pipes an nergy line ission-Bo	fluid flow-Laminar flow- Hagen-Poiseuille equation, shead flow between parallel plates. Turbulent flow – flow the hydraulic gradient line, flow through pipes in series and undary layer flows - Boundary layer thickness, momentum	ough pipes, friction fa parallel- Moody's fri	actors in ction fa	turb ctor o	ulen chart	t flow . Powe
IINIT		HVDD ALII IC TUDDINEC			0	Λ	Λ Λ

UNIT IV HYDRAULIC TURBINES 9 0 0 9

Hydraulic turbines classification-impulse and reaction turbines-Working Principle, work done-efficiency and performance curves for Pelton, Francis and Kaplan turbines (Only descriptive) - Comparison between impulse and reaction turbine-specific speed degree of reaction -draft tubes.

UNIT V HYDRAULIC PUMPS 9 0 0 9

Classification of hydraulic pumps-Centrifugal pumps - working principle, specific speed, performance curves and priming(Only descriptive) -Reciprocating pumps - classification, working principle, indicator diagram, air vessels and performance curves. Cavitation in pumps(Only descriptive) - Working principles of gear and vane pumps.

Text B	Books:
1.	Bansal, R.K., "A Textbook of Fluid Mechanics and Hydraulic Machines, 9th Ed", Laxmi Publication Pvt Ltd, 2010.
2.	Rajput, R.K., "A Textbook of Fluid Mechanics and Hydraulic Mechanics", S.Chand and Company Ltd, 2011.
3.	Subramanya. K., "Fluid Mechanics and Hydraulic Machines", Tata McGraw Hill Publishing Company Ltd, 2011.
Refere	ence Books:
1.	White, "Fluid Mechanics, 8 Ed", McGraw Hill India, 2017.
2.	Munson, Young and Okiishi, "Fundamentals of Fluid Mechanics 8 th Edition", Wiley, 2016.

3.	Yunuscengel, John. M.cimbala, "Fluid Mechanics Fundamentals and Applications", McGraw Hill, 2017.
4.	Som, S.K, Biswas.G and SumanChakraborty, "Introduction to Fluid Mechanics and Fluid Machines", Tata McGraw Hill India, 2011.
5.	Dr.P.N.Modi, Dr.S.M.Seth, "Hydraulics and Fluid Mechanics including Hydraulic Machines", Standard book house, 2018.
E-Refe	rences:
1.	NPTEL courses: http://nptel.iitm.ac.in/courses.php - web and video sources on fluid mechanics.

	SE OUTCOMES: Ompletion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Understand the basic concepts and properties of fluids	Remember
CO2	Analyze the kinematic and dynamic concepts of fluid flow	Analyze
СОЗ	Understand the various incompressible fluid flow through pipes and between parallel plates	Understand
CO4	Apply the principles of fluid mechanics to design and operation of hydraulic turbines	Apply
CO5	Apply the principles of fluid mechanics to design and operation of hydraulic pumps	Apply

COURSE A	ARTI	CULA	ATIO	N MA	TRIX	K									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1	1	0	0	0	2	0	0	0	1	0	2	2	1
CO2	3	3	1	0	2	0	0	0	0	0	0	0	2	2	1
CO3	2	3	2	2	1	0	0	0	0	0	0	0	2	2	1
CO4	3	3	3	2	1	2	1	0	0	0	0	0	2	2	1
CO5	3	3	3	2	1	2	1	0	0	0	0	0	2	2	1
Avg	2.8	2.6	2	1.2	1	0.8	0.8	0	0	0	0.2	0	2	2	1
				3/2/1	– indi	cates	streng	th of c	orrela	tion (3	high,	2- mediı	ım, 1- lov	w)	

22M	EMI03	MANUFACTURING PROCESSES	5						
PRE	-REQUI	SITE:	CATEGORY	PE	Cro	edit		3	
1. Bas	sic science	, Engineering mathematics, Engineering Physics	Hours/Week	L	L T P			TH	
2.Eng	ineering N	Materials	Hours/ week	3	0	0		3	
Cour	se Objec	tives:	•		•				
1.		e the students familiarize with various manufacturing process f casting.	ses and fabrication t	echniqu	ies of	meta	als	and	
2.	To deve	lop design concepts of various manufacturing processes.							
3.	Gain kno	owledge to select appropriate manufacturing processes for vari	ous parts.						
4.	To deve	lop an entrepreneur skill among the students.							
5.	To evalu	ate and select plastic deformation processes for various parts.							

Concepts of Manufacturing Process -Sand casting -Patterns – Design of Pattern, mould and cores- gating and risering design, solidification time calculation - Moulding machines - Core making. Special moulding processes – CO2 moulding; shell moulding, investment moulding, pressure die casting, centrifugal casting, casting defects.

UNIT II | WELDING | 9 | 0 | 0 | 9

Classification of welding processes. Principles of Oxy-acetylene gas welding. Metal arc welding, resistance welding, submerged arc welding, tungsten inert gas welding, metal inert gas welding, plasma arc welding, thermit welding, electron beam welding, laser beam welding, defects in welding, Soldering and Brazing, Adhesive Bonding.

UNIT III METAL FORMING 10 0 10

Metallurgical aspects of metal forming, slip, twinning mechanics of plastic deformation, load estimation of bulk deformation processes, Hot working and cold working of metals, Forging processes – open, closed and impression die forging – forging operations. Rolling of metals– Types of Rolling mill – Flat strip rolling – shape rolling operations – Defects in rolled parts. Principle of rod and wire drawing – Tube drawing – Principles of Extrusion – Types.

UNIT IV SHAPING OF PLASTICS 8 0 0 8

Types of plastics - Characteristics of the forming and shaping processes - Moulding of Thermoplastics - Working principles and typical applications of - Injection moulding - Plunger and screw machines - Blow moulding - Rotational moulding - Film blowing - Extrusion - Typical industrial applications - Thermoforming - Processing of Thermosets - Working principles and typical applications - Compression moulding - Transfer moulding.

UNIT V SHEET METAL FORMING AND POWDER METALLURGY 9 0 0 9

Formability of Sheet Metal, load estimation of sheet metal processes - Shearing, Deep drawing, Bending operations- types of presses used, Super Plastic forming; Introduction to Powder Metallurgy- Principal steps involved - sintering and compacting techniques, Advantages, limitations and applications of powder metallurgy.

Text B	ooks:
1.	HajraChoudhury, "Elements of Workshop Technology", Vol. I and II, Media Promoters and Publishers Pvt., Ltd., Mumbai, 2005.
2.	NagendraParashar B.S. and Mittal R.K., "Elements of Manufacturing Processes", Prentice-Hall of India Private Limited, 2007.
Refere	nce Books:
1.	SeropeKalpajian, Steven R.Schmid, "Manufacturing Processes for Engineering Materials",4/e, Pearson Education, Inc. 2007.
2.	Jain. R.K., and S.C. Gupta, "Production Technology", 16th Edition, Khanna Publishers, 2001.
3.	"H.M.T. "Production Technology – Handbook", Tata McGraw-Hill, 2000.

4.	Roy. A. Linberg, "Process and Materials of Manufacture", PHI, 2000.
5.	Mikell P. Groover, Fundamentals of Modern Manufacturing: Materials, Processes, and Systems.
E-Refe	erences:
1.	https://fdocuments.in/document/production-technology-55844cac00bfc.html?page=40

	SE OUTCOMES: ompletion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Describe the operational features of various casting processes, design gate and riser and discover various defects in casting.	Understand
CO2	Explain various metal joining processes and compare them.	Understand
соз	Summarize several types of metal forming processes and select suitable method for different applications.	Analyze
CO4	Analyze various manufacturing methods for plastics and their needs in industry.	Analyze
CO5	Describe various sheet metal forming processes, load estimation calculation and principles of powder metallurgy	Understand

COURSE A	ARTI	CULA	ATIO	N MA	TRIX	K									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	2	1	0	0	0	0	0	1	0	0	1	2	1
CO2	2	1	2	1	0	1	0	0	1	1	0	0	1	2	1
CO3	1	1	1	1	0	0	0	0	0	1	0	0	1	1	1
CO4	1	1	1	0	1	0	0	0	0	1	0	0	1	1	1
CO5	0	1	0	0	0	0	0	0	1	1	0	0	1	0	1
Avg	1.2	1	1.2	0.6	0.2	0.2	0	0	0.4	1	0	0	1	1.2	1
				3/2/1	– indi	cates	streng	th of c	orrela	tion (3 -	high,	2- mediı	ım, 1- lov	w)	

22ME	MI04	MATERIALS ENGINEERING					
PRE-F	REQUI	SITE:	CATEGORY	PE	Cr	edit	3
1. Engii	neering l			L	T	P	TH
2.Engin	neering (Chemistry	Hours/Week	3	0	0	3
Course	e Objec	ctives:					1
1.		npart concept on reactions, treatment, microstructure and mecha ent temperature.	nical behavior of	f engin	eering	materi	als a
2.	To lea	arn basic principles in metallurgy and materials engineering.					
3.	To ide	entity and select suitable engineering materials based on their applica-	ations				
UNIT	I P	PHASE DIAGRAMS		9	0	0	9
		ectic, Eutectoid, Peritectic systems. Lever rule, Equilibrium and its of alloying elements – Ferrite and Austenite Stabilizers, TTT and		cooling	, Fe-C	Equili	briun
UNIT		HEAT TREATMENT	CCT diagrams.	9	0	0	9
UNIT Definiti Isothern test – A	II ion – Fu mal trans Austempe ng. Hea		nalizing, hardenin n CCR - Hardena ding, carbo-nitrid	ng and ability, ing – F	Tempe Jomin	ring of y end q and Ind	steel uench uction
UNIT Definiti Isothern test – A hardenin	II ion – Fu mal trans Austempe ng. Hea	HEAT TREATMENT all annealing, stress relief, recrystallisation and spheroidizing –norm sformation diagrams – cooling curves superimposed on I.T. diagram ering, martempering – case hardening, carburising, nitriding, cyanic	nalizing, hardenin n CCR - Hardena ding, carbo-nitrid	ng and ability, ing – F	Tempe Jomin	ring of y end q and Ind	steel uench uction
UNIT Definiti Isothern test – A hardening gauges. UNIT Plain ca and pre-	ion – Fumal trans Austempeng. Hea III	HEAT TREATMENT all annealing, stress relief, recrystallisation and spheroidizing –norm sformation diagrams – cooling curves superimposed on I.T. diagram ering, martempering – case hardening, carburising, nitriding, cyanic treatment of non-ferrous alloys - precipitation hardening .Heat	nalizing, hardenin m CCR - Hardena ding, carbo-nitridi treatment of HSS - ferritic and Aus-	ng and ability, ing – F tools,	Tempe Jomin Flame a gears	ering of y end q and India, spring	steel uench uction s and
UNIT Definiti Isothern test – A hardening gauges. UNIT	ion – Fumal trans Austempeng. Head	HEAT TREATMENT all annealing, stress relief, recrystallisation and spheroidizing –norm sformation diagrams – cooling curves superimposed on I.T. diagram ering, martempering – case hardening, carburising, nitriding, cyanic treatment of non-ferrous alloys - precipitation hardening .Heat FERROUS AND NON FERROUS METALS eels – Tool steels - maraging steels – HSLA steels .Stainless steels on hardened stainless steels. Types of Cast Irons- Gray cast iron, w	nalizing, hardenin m CCR - Hardena ding, carbo-nitridi treatment of HSS - ferritic and Aus-	ng and ability, ing – F tools,	Tempe Jomin Flame a gears	ering of y end q and India, spring	steel uench uction s and
UNIT Definiti Isotherr test – A hardenin gauges. UNIT Plain ca and pre .Copper	ion – Fumal trans Austempeng. Head	HEAT TREATMENT all annealing, stress relief, recrystallisation and spheroidizing –norm sformation diagrams – cooling curves superimposed on I.T. diagram ering, martempering – case hardening, carburising, nitriding, cyanic treatment of non-ferrous alloys - precipitation hardening .Heat FERROUS AND NON FERROUS METALS eels – Tool steels - maraging steels – HSLA steels .Stainless steels on hardened stainless steels. Types of Cast Irons- Gray cast iron, we Brass, Bronze and Cupronickel , Aluminium alloys, Bearing alloy	nalizing, hardenin m CCR - Hardena ding, carbo-nitridi treatment of HSS - ferritic and Aus-	g and ability, ing – F tools,	Tempe Jomin Flame a gears 0 marte cast i	oring of y end quand India, spring one of the spring of t	steel uench uction s and

methods, high and low energy beam methods, surface engineering charts, elastic contact mechanics

Text Boo	oks:
1.	Kenneth G. Budinski and Michael K. Buinski, "Engineering Materials", Prentice Hall of India Ltd, 2002.
2.	Raghavan, V, "Materials Science and Engineering", Prentice Hall of India (P) Ltd., 1999.
3.	Aswani.K.G, "A Text Book of Material Science", S.Chand and Co. Ltd., New Delhi, 2001.
4.	Khanna O.P., "A Text Book of Materials Science and Metallurgy", DhanpatRai Sons, 2004.
Reference	ce Books:
1.	William. D.Callsber, "Material Science and Engineering", John Wiley and Sons, 1997.
2.	Sydney.H.Avner, "Introduction to Physical Metallurgy" Mc Graw Hill Book Company, 1994.

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:						
CO1	Understand the formation of materials and their classification based on atomic structure.	Understand					
CO2	Understand the principles of various heat treatment processes in fabrication industry.	Understand					
соз	Describe properties, applications and types of various ferrous and non-ferrous metals used in fabrication industry	Understand					
CO4	Describe various types of failure and select methods for destructive testing	Understand					
CO5	Select methods for Non destructive testing	Evaluate					

COURSE A	ARTI	CULA	ATIO	N MA	TRIX	X									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	1	2	2	1	1	1	0	0	0	0	0	2	3	1
CO2	1	0	2	1	1	2	1	0	0	0	0	0	2	3	1
CO3	0	1	1	1	1	0	1	0	0	0	0	0	3	2	1
CO4	0	2	2	1	1	1	1	0	0	0	0	0	2	3	1
CO5	0	2	2	2	1	0	1	0	0	0	0	0	2	2	1
Avg	0.4	1.2	1.8	1.4	1.0	0.8	1	0	0	0	0	0	2.2	2.6	1.0
		•	•	3/2/1	– indi	cates	streng	th of c	orrela	tion (3	– high, í	2- mediı	ım, 1- lov	w)	

22MEMI05	KINEMATICS OF MACHINE	RY							
PRE-REQ	ISITE:	CATEGORY	PE	Cr	edit		C		
1. Engineerir	g graphics. 2.Engineering Mechanics	/	L	Т	P	1	TH		
		Hours/Week 3					3		
Course Ob	ectives:		1	ı					
1. To 1	nderstand the basic components and layout of linkages in the	assembly of a system/ ma	chine.						
	To understand the principles in analyzing the assembly with respect to the displacement, velocity, and acceleration at any point in a link of a mechanism.								
3. To 1	nderstand basics of cam profile and its displacement.								
4. To 1	nderstand the basic concepts of toothed gearing and kinematic	cs of gear trains.							
5. Illus	trate the effects of friction drives in transmission system.								
UNIT I	BASICS OF MECHANISMS			9	0	0	9		
UNIT II	kinematic analysis			9	0	0			
centres - ki	, velocity and acceleration analysis of simple mechanisms, ematic analysis of simple mechanisms- slider-crank mechanisms three Postacceleration introduction to linkage synthesis three Postacceleration.	hanism dynamics Coin	cident	poin	its- (Cor	ioli		
UNIT III	KINEMATICS OF CAM			9	0	0	9		
simple harmo	of cams and followers- Terminology and definitions- Displ nic and cycloidal motions- derivatives of follower motions- se and undercutting, sizing of cams, graphical method for cam	specified contour cams cir							
UNIT IV	GEARS AND GEAR TRAINS			9	0	0	9		
	cycloidal gear profiles, gear parameters, fundamental law of ference/undercutting- helical, bevel, worm, rack & pinion ge								
UNIT V	FRICTION IN MACHINE ELEMENTS			9	0	0	9		
	cts- sliding and rolling friction- friction drives- friction in so and rope drives.	crew threads – bearings	and lub	ricat	ion-	fric	tion		
		Tot	al (451	<u>_</u>	45 P	eri	iod		

Text E	Text Books:								
1.	Rattan S.S, "Theory of Machines", Tata McGraw Hill Publishing Company Ltd., New Delhi, 1998.								
2.	Ghosh, A and Mallick, A.K, "Theory of Mechanisms and Machines", East-West Pvt. Ltd., New Delhi, 1988.								
Refere	ence Books:								
1.	Thomas Bevan, "Theory of Machines", CBS Publishers and Distributors, 1984.								
2.	Rao J.S and Dukkipati R.V, "Mechanism and Machine Theory", Wiley-Eastern Ltd., New Delhi, 1992.								
3.	Erdman AG and Sandor G N, "Mechanism Design, Analysis and Synthesis", Vol.I, PHI Inc., 1997.								
4.	Ambekar A.G, "Mechanism and Machine Theory" Prentice Hall of India, New Delhi, 2007.								
5.	John Hannah and Stephens R C, "Mechanisms of Machines", Viva Low Price Student Edition, New Delhi, 1999.								
E-Refe	erences:								

	1.	https://archive.nptel.ac.in/courses/112/104/112104121/
ſ	2.	https://nptel.ac.in/courses/112106270
ſ	3.	http://velhightech.com/Documents/ME8492 Kinematics of Machinery.pdf

	COURSE OUTCOMES: Upon completion of the course, the students will be able to:						
CO1	Demonstrate and understand the concepts of various mechanisms and pairs.	Apply					
CO2	Analyze the velocity and acceleration of simple mechanisms.	Analyze					
CO3	Construct the cam profile for various motion.	Create					
CO4	Solve problems on gears and gear trains.	Evaluate					
CO5	Evaluate the friction in transmission system	Evaluate					

COURSE A	ARTIO	CULA	TIO	N MA	TRIX	<u> </u>									
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	1	0	0	0	0	0	0	0	0	3	1	0
CO2	3	2	2	1	0	0	0	0	0	0	0	0	3	1	0
CO3	3	2	2	1	0	0	0	0	0	0	0	0	3	1	0
CO4	3	2	2	1	0	0	0	0	0	0	0	0	3	1	0
CO5	3	2	2	1	0	0	0	0	0	0	0	0	3	1	0
Avg	3	2	2	1	0	0	0	0	0	0	0	0	3	1	0
	•	•		3/2/1	– indi	cates	strengt	th of co	orrelat	ion (3 –	high, 2	- mediu	m, 1- low	· ')	•

22MEMI06	HYDRAULICS AND PNEUMATICS		,		
PRE-REQUI	SITE: CATEGORY	PE	Cre	edit	3
	Hours/Week	L	T	P	TH
	Hours/ week	3	0	0	3
Course Objec	etives:				
1. To enab	le the students understand the basics of hydraulics and pneumatics				
2. Applyin	g the working principles of hydraulic actuators and control components.				
3. Designing	ng and develop hydraulic circuits and systems.				
4. Applyin	g the working principles of pneumatic power system and its components.				
5. Solving	problems and troubles in fluid power systems.				
UNIT I FL	UID POWER PRINICIPLES AND HYDRAULIC PUMPS		9	0	0 9
Problems, Sour	Basics of Hydraulics – Pascal's Law – Principles of flow - Friction loss – Worces of Hydraulic power; Pumping Theory – Pump Classification – Construction – Construction – Pumping Theory – Pumping Theory – Fixed and Variable	ction, V	Worki	ng, I	Design
1 TOUICIIIS.	T				
UNIT II	HYDRAULIC ACTUATORS AND CONTROL COMPONENTS	- D	9	0	0 9
UNIT II Hydraulic Actu Hydraulic moto Construction an	HYDRAULIC ACTUATORS AND CONTROL COMPONENTS nators: Cylinders – Types and construction, Application, Hydraulic cushioning ors - Control Components: Direction Control, Flow control and pressure of Operation – Accessories; Reservoirs, Pressure Switches – Filters – types and swisi Symbols – Problems.	control	otary valve	actua	ators Types
UNIT II Hydraulic Actu Hydraulic moto Construction an	nators: Cylinders – Types and construction, Application, Hydraulic cushioning ors - Control Components: Direction Control, Flow control and pressure of Operation – Accessories; Reservoirs, Pressure Switches – Filters – types and s	control	otary valve	actua	ators Types
UNIT II Hydraulic Actu Hydraulic moto Construction an Fluid Power AN UNIT III Accumulators, Intensifier, Air- Sizing of hydra	nators: Cylinders – Types and construction, Application, Hydraulic cushioning ors - Control Components: Direction Control, Flow control and pressure of Operation – Accessories; Reservoirs, Pressure Switches – Filters – types and swill Symbols – Problems.	ouble -	otary valve n - Ap 9 - Pun elerati	actuales – oplicate oplic	ators Types tions -
UNIT II Hydraulic Actu Hydraulic moto Construction an Fluid Power AN UNIT III Accumulators, Intensifier, Air- Sizing of hydra	nators: Cylinders – Types and construction, Application, Hydraulic cushioning ors - Control Components: Direction Control, Flow control and pressure of Operation – Accessories; Reservoirs, Pressure Switches – Filters – types and swist Symbols – Problems. HYDRAULIC CIRCUITS AND SYSTEMS Intensifiers, Industrial hydraulic circuits – Regenerative, Pump Unloading, Deover oil, Sequence, Reciprocation, Synchronization, Fail - Safe, Speed Controlaulic systems, Hydrostatic transmission, Electro hydraulic circuits – Servo and	ouble -	otary valve n - Ap 9 - Pun elerati	actuales – oplicate oplic	ators Types tions -
UNIT II Hydraulic Actu Hydraulic moto Construction an Fluid Power AN UNIT III Accumulators, Intensifier, Air- Sizing of hydra Applications - M UNIT IV Properties of ai Exhaust Valves circuits - Cascac	nators: Cylinders – Types and construction, Application, Hydraulic cushioning ors - Control Components: Direction Control, Flow control and pressure of Operation – Accessories; Reservoirs, Pressure Switches – Filters – types and swist Symbols – Problems. HYDRAULIC CIRCUITS AND SYSTEMS Intensifiers, Industrial hydraulic circuits – Regenerative, Pump Unloading, Deover oil, Sequence, Reciprocation, Synchronization, Fail - Safe, Speed Control aulic systems, Hydrostatic transmission, Electro hydraulic circuits – Servo and Mechanical, hydraulic servo systems.	ouble - ol, Decod Prop	otary valve in - Ap 9 - Pumelerate ortion 9 rol Vand mi	actuals actual actuals actual actuals actual actuals actual actuals actual actuals actual actual actuals actual actual actuals actual actu	ators Types tions - 0 9 ressure ircuits lves - Quick ylinde
UNIT II Hydraulic Actu Hydraulic moto Construction an Fluid Power AN UNIT III Accumulators, Intensifier, Air- Sizing of hydra Applications - M UNIT IV Properties of ai Exhaust Valves circuits - Cascac	nators: Cylinders — Types and construction, Application, Hydraulic cushioning ors - Control Components: Direction Control, Flow control and pressure of Operation — Accessories; Reservoirs, Pressure Switches — Filters — types and start Symbols — Problems. HYDRAULIC CIRCUITS AND SYSTEMS Intensifiers, Industrial hydraulic circuits — Regenerative, Pump Unloading, Dover oil, Sequence, Reciprocation, Synchronization, Fail - Safe, Speed Control aulic systems, Hydrostatic transmission, Electro hydraulic circuits — Servo and Mechanical, hydraulic servo systems. PNEUMATIC AND ELECTRO PNEUMATIC SYSTEMS r — Air preparation and distribution — Filters, Regulator, Lubricator, Muffler, As, Pneumatic actuators, Design of Pneumatic circuit — classification - single cylide method — Integration of fringe circuits, Electro Pneumatic System — Elements —	ouble - ol, Decod Prop ir contrinder at- Ladde	otary valve in - Ap 9 - Pumelerate ortion 9 rol Vand mi	actuals — oplicate op	ators Types tions - 0 9 ressure ircuits lves - Quick ylinde
UNIT II Hydraulic Actu Hydraulic moto Construction an Fluid Power AN UNIT III Accumulators, Intensifier, Air- Sizing of hydra Applications - M UNIT IV Properties of ai Exhaust Valves circuits - Cascac circuits problem UNIT V Servo systems, electro hydrauli failure and troul – Low cost Auf	nators: Cylinders — Types and construction, Application, Hydraulic cushioning ors - Control Components: Direction Control, Flow control and pressure of Operation — Accessories; Reservoirs, Pressure Switches — Filters — types and swist Symbols — Problems. HYDRAULIC CIRCUITS AND SYSTEMS Intensifiers, Industrial hydraulic circuits — Regenerative, Pump Unloading, Dover oil, Sequence, Reciprocation, Synchronization, Fail - Safe, Speed Control aulic systems, Hydrostatic transmission, Electro hydraulic circuits — Servo and Mechanical, hydraulic servo systems. PNEUMATIC AND ELECTRO PNEUMATIC SYSTEMS r — Air preparation and distribution — Filters, Regulator, Lubricator, Muffler, As, Pneumatic actuators, Design of Pneumatic circuit — classification - single cylide method — Integration of fringe circuits, Electro Pneumatic System — Elements—as, Introduction to fluidics and pneumatic logic circuits.	ouble - ol, Decod Prop ir contrinder as- Ladde NG I Valve rol, Flu ounter a	otary valve in - Ap 9 - Pumelerate ortion 9 rol Vand must diag	actuals actual actual actuals actual actual actuals actual ac	o 9 Control of the c
UNIT II Hydraulic Actu Hydraulic moto Construction an Fluid Power AN UNIT III Accumulators, Intensifier, Air- Sizing of hydra Applications - M UNIT IV Properties of ai Exhaust Valves circuits - Cascac circuits problem UNIT V Servo systems, electro hydrauli failure and troul – Low cost Auf	nators: Cylinders – Types and construction, Application, Hydraulic cushioning ors - Control Components: Direction Control, Flow control and pressure of Operation – Accessories; Reservoirs, Pressure Switches – Filters – types and swist Symbols – Problems. HYDRAULIC CIRCUITS AND SYSTEMS Intensifiers, Industrial hydraulic circuits – Regenerative, Pump Unloading, Devover oil, Sequence, Reciprocation, Synchronization, Fail - Safe, Speed Control and Systems, Hydrostatic transmission, Electro hydraulic circuits – Servo and Mechanical, hydraulic servo systems. PNEUMATIC AND ELECTRO PNEUMATIC SYSTEMS r – Air preparation and distribution – Filters, Regulator, Lubricator, Muffler, A. S., Pneumatic actuators, Design of Pneumatic circuit – classification - single cylide method – Integration of fringe circuits, Electro Pneumatic System – Elements – as, Introduction to fluidics and pneumatic logic circuits. DESIGN OF FLUID POWER CIRCUITS AND TROUBLESHOOTI Hydro mechanical servo systems, electro hydraulic servo systems and proportional content of pheumatic circuits for metal working, handling, clamping content of the presence	ouble - ol, Decod Prop ir contrinder as- Ladde NG I Valve rol, Flu ounter a	otary valve in - Ap 9 - Pumelerate ortion 9 rol Vand must diag	actuals — oplicate of the population of the popu	o Quidind time

Text B	Text Books:								
1.	Manjumdar S.R, "Oil Hydraulics", Tata McGraw-Hill, December 2002.								
2.	Anthony Esposito, "Fluid Power with Applications", Pearson Education 2013.								
Refere	Reference Books:								
1.	Andrew Parr, "Hydraulic and Pneumatics", Jaico Publications House, 2005.								

2.	Bolton W. "Pneumatic and hydraulic system", Butterworth-Heinemann 1997						
3.	Majumdar S.R., "Pneumatic systems – Principles and maintenance", Tata McGraw Hill, 2010						
4.	Shanmugasundaram.K, "Hydraulic and Pneumatic controls", Chand & Co, 2006						
5.	Srinivasan.R. "Hydraulic and Pneumatic Controls", Vijay Nicole Imprints, 2008.						
	E-References:						
E-Refe	erences:						
E-Ref 1.	http://www.fluidpowerjournal.com						

	SE OUTCOMES: ompletion of the course, the students will be able to:	Bloom's Taxonomy Mapped
CO1	Select the components as per the application	Evaluate
CO2	Apply the working principles of hydraulic actuators and control components.	Apply
CO3	Design and develop hydraulic circuits and systems.	Create
CO4	Apply the working principles of pneumatic power system and its components.	Apply
CO5	Solve problems and troubles in fluid power systems.	Evaluate

COURSE ARTICULATION MATRIX

COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	1	0	0	0	0	0	0	0	0	0	1	1	1
CO2	0	2	2	1	0	0	0	0	0	0	0	0	1	1	1
CO3	1	2	3	0	0	1	0	0	0	0	0	0	1	2	1
CO4	1	1	3	2	2	0	0	0	0	0	0	0	2	1	1
CO5	1	1	2	0	0	0	0	0	0	0	0	0	1	1	1
Avg	1	1.4	2.2	0.6	0.4	0.2	0	0	0	0	0	0	1.2	1.2	1
				2/2/1	: 4::	4	.4	1. a.f. a.	1.4	: (2	hiah o		m 1 love	.)	

3/2/1 – indicates strength of correlation (3 – high, 2- medium, 1- low)

22M	EMI07	DESIGN OF MACHINE ELEMEN	TS						
PRE	-REQUIS	SITE:	CATEGORY	PE	Cre	edit		3	
1. Stu	dent shoul	d study engineering mechanics.	TT /557 1	L	T	P	Г	ТН	
2. Stu	dent shoul	d study kinematic of machinery.	Hours/Week	3	0	0		3	
Cour	se Objec	tives:		•					
1.	1. Understanding of background in mechanics of materials and design of machine components.								
2.	2. An understanding of the origins, nature and applicability of empirical design principles, based on safety considerations								
3.	An unde	rstanding the design of shafts and couplings.							
4.	Familiar	ize the design of energy storing elements and engine compor	nents.						
5.	5. An appreciation of the relationships between component level design and overall machine system design and performance								
UNI	UNIT I STEADY STRESSES AND VARIABLE STRESSES IN MACHINE 9 0 0 9								
based Calcu	on mecha lation of p	he design process – Product development cycle- factors infl nical properties - Preferred numbers – Direct, Bending and principle stresses for various load combinations, eccentric loading – design for variable loading – Soderberg, Goodman and	Torsional stress – I pading – Factor of	mpact and	l sho	ck loa	adin	ıg –	
UNI	ГII	DESIGN OF SHAFTS AND COUPLINGS			9	0	0	9	
		and hollow shafts based on strength, rigidity and critical spee e couplings.	eed – Design of key	s and key	ways	- De	sigr	ı of	
UNI	L III	DESIGN OF THREADED FASTENERS, RIV JOINTS	ETED AND W	ELDED	9	0	0	9	
		ers - Design of bolted joints including eccentric loading – Γ extremely theory of bonded joints.	Design of riveted and	d welded j	oints	for p	ress	ure	
UNI	ΓΙ	DESIGN OF ENERGY STORING ELEMICOMPONENTS	ENTS AND I	ENGINE	9	0	0	9	
		springs, optimization of helical springs - rubber springs - F punching machines- Connecting Rods and crank shafts.	lywheels considering	ng stresses	in riı	ns an	d aı	rms	
UNI	ΓV	DESIGN OF BEARINGS			9	0	0	9	
	Sliding contact and rolling contact bearings - Hydrodynamic journal bearings, Sommerfeld Number - Selection of Rolling Contact bearings.								
			7	Total (45	L) =	45 P	erio	ods	

Text I	Books:							
1.	Bhandari V.B, "Design of Machine Elements", Tata McGraw Hill Book Co, 2020							
2.	Md.Jalaludeen.S, "A text book of Machine Design", Anuradha Publications, 2006							
Refere	Reference Books:							
1.	Shigley, J.E. and Mischke, C.R., Mechanical Engineering Design, Fifth Edition, McGraw-Hill International; 1989.							
2.	Deutschman, D., Michels, W.J. and Wilson, C.E., Machine Design Theory and Practice, Macmillan, 1992.							
3.	Juvinal, R.C., Fundamentals of Machine Component Design, John Wiley, 1994.							
4.	PSG Tech, "Design Data Handbook", M/s.DPV Printers, Coimbatore, 2009							
E-Ref	E-References:							

1.	https://nptel.ac.in/courses/112105124
2.	Design of Machine Elements - V. B. Bhandari - Google Books
3.	A Textbook of Machine Design by R.S.Khurmi And J.K.Gupta [tortuka] 1490186411865.pdf DocDroid

	RSE OUTCOMES: ompletion of the course the student will be able to	Bloom's Taxonomy Mapped						
CO1	Explain the influence of steady and variable stresses in machine component design. Understa							
CO2	Apply the concepts of design to shafts, keys and couplings.	Apply						
CO3	Familiarize the design of temporary and permanent joints	Understand						
CO4	Design the various energy storing elements and engine components.	Analyse						
CO5	Familiarize the design of various types of bearings. Underst							

COURSE A	OURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	1	2	0	1	1	0	0	0	1	0	3	2	1
CO2	2	2	1	2	0	1	1	0	0	0	1	0	3	2	1
CO3	2	2	1	2	0	1	1	0	0	0	1	0	3	2	1
CO4	2	2	1	2	0	1	1	0	0	0	1	0	3	2	1
CO5	2	2	1	2	0	1	1	0	0	0	1	0	3	2	1
Avg	2.0	2.0	1.0	2.0	0.0	1.0	1.0	0.0	0.0	0.0	1.0	0.0	3.0	2.0	1.0
3/2/1 - in	3/2/1 – indicates strength of correlation (3 – high, 2- medium, 1- low)														

22ME	MI08	HEAT AND MASS TRANSFER								
PRER	EQUIS	ITES	CATEGORY	PE	Cr	edit	C			
1.The la	aws and	basic concepts of thermodynamics	TT /\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	L	Т	P	ТН			
2. The o	concept	of energy transfers and their conversion principles	Hours/Week	3	0	0	3			
COUR	RSE OB	JECTIVES		•		•				
1.	Understanding the science behind conduction heat transfer and its applications									
2.	Differe	ntiating the concepts of forced and natural convection heat transfer	er							
3.	Describ	ing the laws and concepts of radiation heat transfer								
4.	Unders	tanding phase change processes and analyzing heat exchangers								
5.	Studyir	ng the concept of mass transfer process and its modes								
UNI	9	0	0	9						
Extend charts.	led Surfa	plane and Composite Systems – Conduction with Internal HeatGeaces – Unsteady Heat Conduction – Lumped Analysis – Semi In		olids –	Use o	of He	isler's			
UNI	T-II	CONVECTION HEAT TRANSFER		9	0	0	9			
and ban	nk of tub	 quations, boundary layer concept – Forced convection: external fes. Internal flow – entrance effects. –flow over vertical plate, horizontal plate, inclined plate, cylinde 	-	lates, cy	linde	ers, sp	heres			
UNIT		BOILING, CONDENSATION AND HEAT EXCHANG		9	0	0	9			
		l boiling and Flow boiling, Nusselt's theory of condensation- cores - Overall Heat Transfer Coefficient – Fouling Factors.LMTD at		and cor	ndens	ation	. Heat			
UNI	T-IV	RADIATION HEAT TRANSFER		9	0	0	9			
Radiatio	on laws,	Black Body and Gray body Radiation. Shape Factor. Electrical A	nalogy. RadiationS	hields.						
UNI	T-V	MASS TRANSFER		9	0	0	9			
	Basic Concepts – Diffusion Mass Transfer – Fick's Law of Diffusion – Steady state Molecular Diffusion-Equimolal counter diffusion. Basic Convective Mass Transfer Problems.									
	Total(45L) = 45 Periods									

TEXT	TEXT BOOKS:								
1	R.C. Sachdeva, "Fundamentals of Engineering Heat & Mass transfer", New Age International Publishers, 2017								
2	Frank P. Incropera and David P. Dewitt, "Fundamentals of Heat and Mass Transfer", John Wiley & Sons, 7th Edition, 2014.								
REFE	REFERENCE BOOKS:								
1	Yunus A. Cengel, "Heat Transfer A Practical Approach" – Tata McGraw Hill, 5 th Edition - 2013								
2	Holman, J.P., "Heat and Mass Transfer", Tata McGraw Hill, 2017								
3	Kothandaraman, C.P., "Fundamentals of Heat and Mass Transfer", New Age International, New Delhi, 2012								
4	Ozisik, M.N., "Heat Transfer", McGraw Hill Book Co., 1994.								

	RSE OUTCOMES: mpletion of the course the student will be able to:	Bloom's Taxonomy Mapped			
CO1	Analyze the mechanism of heat conduction under steady and transient conditions.	Apply			
CO2	Develop solutions to problems involving convective heat transfer	Create			
CO3	Design a heat exchanger for any specific application	Understand			
CO4	Adopt the concept of radiation heat transfer in real time systems	Understand			
CO5	Develop solutions to problems involving combined heat and mass transfer	Apply			

COURSE .	OURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	2	0	1	0	0	0	0	0	3	3	1
CO2	3	3	3	3	2	0	1	0	0	0	0	0	3	3	1
CO3	3	3	3	3	2	0	1	0	0	0	0	0	3	3	1
CO4	3	3	3	3	2	0	1	0	0	0	0	0	3	2	1
CO5	2	2	2	2	1	0	1	0	0	0	0	0	3	1	0
Avg	2.8	2.8	2.8	2.8	1.8	0	1	0	0	0	0	0	3	2.4	0.8
3/2/1 - in	dicate	s stren	gth of	correl	ation (3 – hig	sh, 2- n	nedium	, 1- lov	w)					

22MEMI09	METROLOGY AND QUALITY (CONTROL							
PREREQUISI'	TES	CATEGO	ORY	PE	Credit		3		
		TT /XX	′1-	L	T P		TH		
		Horus/W	еек	3	0	0	3		
COURSE OBJ	ECTIVES						•		
1.	Explaining the importance of measurements in en to compute measurement uncertainty	gineering and	the facto	rs affec	ting m	easure	ments and		
2.	Applying the applications of linear and angular measuring instruments								
3.	Interpretation of various tolerance symbols.								
4.	Applying the SQC methods in manufacturing								
5.	Applying the advances in measurements for quali	ty control							
UNIT-I	BASICSOFMEASUREMENTSYSTEMA	NDDEVICE	S 9	0	0		9		
feeler gauges, dia	standards assuring instruments - principles of calibration, Cali l indicator, surface plates, slip gauges, care of gauge ards.Comparators-mechanical, electrical, optical and	blocks. Gener							
UNIT-III	GEOMETRICAL MEASUREMENT MACHINE ELEMENTS	AND	9	0	0		9		
principle, three to measurement of the errors ,base pitch	ment - optical protractors, sine bar, roundness meas asic types of limit gauges, Tomlinson surface me major, minor and effective diameters. Gear terminol measurement. Principle of interferometry, laser inter straightness, flatness, roundness deviations.,	eter, computer logy; spur gea	controll r measu	ed CM rement,	M. ISO	O meting of	ric thread, composite		
UNIT-IV	STATISTICAL QUALITY CONTROL		9	0	0		9		
	ninologyandmeasurements-Opticalmeasuringinstrum harts-Sampling plans	ents-Acceptan	cetestfor	machin	esStati	sticalÇ	uality		
UNIT-V	SIX SIGMA		9	0	0		9		
hart,Scatterchart,	neasure, analyse, improve and control phases. Analyze ph Cause and effect diagram, Pareto analysis, interrelations of eg, ANOVA Multi variate analysis.			ools:	Regres	ssion	Analysis,		
				Tot	al(45I	L) = 4	5 Periods		

TEXT BO	TEXT BOOKS:								
1	Gupta.I.C, —A text book of Engineering Metrology, Dhanpat Rai publications, New Delhi, 2018								
2	Beckwith.T.G,Roy D. Marangoni, John H. Lienhard, - Mechanical Measurements, Prentice Hall, 2006								
REFEREN	REFERENCE BOOKS:								
1	Jain.R.K, —Mechanical and Industrial Measurements, Khanna Publishers, Delhi, 1999.								
2	Holmen.J.P, —Experimental Methods for Engineersl, Tata McGraw Hill Publications Co Limited, 2017.								
3	Grant, E.L., Statistical Quality Control, Mc Graw-Hill, 2004. 3. Doeblin E.O., Measurement Systems, Mc								

	Graw-Hill, 2004.								
4	Alan S Morris, —Measurement and Instrumentation Principlesl, Butterworth, 2006.								
5	De Feo J A and Barnard W W, —Six Sigma: Break trough and BeyondG, Tata McGraw-Hill, New Delhi, 2005.								
E-REFERI	E-REFERENCES:								
1	https://nitsri.ac.in/Department/Mechanical%20Engineering/MEC_405_Book_2,_for_Unit_2B.pdf								
2 https://www.nist.gov/system/files/documents/srm/NIST-SRM-RM-Articlefinal.pdf									
3	https://www.researchgate.net/publication/319587859_Computer-Aided_Metrology-CAM								

	RSE OUTCOMES: mpletion of the course the student will be able to:	Bloom's Taxonomy Mapped
CO1	Explain the importance of measurements in engineering and the factors affecting measurements and to compute measurement uncertainty	Understand
CO2	Apply the working principle and the applications of linear and angular measuring instruments[Apply
CO3	Interpret of various tolerance symbols.	Apply
CO4	Apply the SQC methods in manufacturing.	Apply
CO5	Apply the advances in measurements for quality control in manufacturing industries.	Apply

COURSE .	COURSE ARTICULATION MATRIX														
COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	0	0	0	0	0	0	2	1	2	0	0	0	2	1	0
CO2	0	0	0	0	0	0	3	1	2	0	0	0	1	2	0
CO3	0	0	0	0	0	0	2	1	0	0	0	0	2	1	0
CO4	0	0	0	3	0	0	2	0	1	0	0	0	1	2	0
CO5	0	0	0	2	0	0	0	3	1	0	0	0	2	1	0
Avg	0.0	0.0	0.0	1.0	0.0	0.0	1.8	1.2	1.2	0.0	0.0	0.0	1.6	1.4	0.0
3/2/1 - in	dicate	s stren	gth of	correla	ation (3 – hig	gh, 2- n	nedium	, 1- lov	w)		•			

	MEMI	10 DYNAMICS OF MACHINERY					
PRF	EREQU	UISITES	CATEGORY	PE	Cre	edit	3
	_			L	T	P	TH
Engi	neering	Mechanics, Kinematics of Machinery, Strength of Materials	Hours\Week	3	0	0	3
CO	URSE	OBJECTIVES:	1	ı		I	
1.	To imp Work	part students with the knowledge about motion, masses and for	ces in machines and	the Pr	incipl	e of V	/irtual
2.	To faci	litate students to understand the concept of balancing of rotating a	and reciprocating mas	sses			
3.	To teac	ch concepts of free vibration analyses of one and two degree-of-free	eedom rigid body sys	tems			
4.		ch concepts of forced vibrations analyses of rigid body systemenon of vibration and its effects	ns and to give awar	eness to	o stud	lents (on the
5.	To lear	n about the concept of various types of governors					
UN	ITI	FORCE ANALYSIS		9	0	0	9
D'Al Mon	lembert' nent Dia	Analysis, Free Body Diagrams, Conditions of Two, Three at 's Principle – Inertia Force Analysis in Reciprocating Engines agrams and Fluctuation of Energy of Reciprocating Engine Mechweight of Flywheel Required.	- Crank Shaft Torq	ue. Fly	wheel	s – T	urning
UN	IT II	BALANCING		9	0	0	9
		lynamic balancing - Balancing of rotating masses - Balancing gines - Partial balancing in locomotive Engines - Balancing linkag			Balar	ncing	Multi-
UNI	III TI	FREE VIBRATION		9	0	0	9
Natu Free	ral Fred dom Sy	res of Vibratory Systems – Types – Single Degree of Freedom quency by Energy Method, Dunkerly's Method - Critical Speed stem -Types of Damping – Free Vibration with Viscous Dampin sional Systems: Natural Frequency of Two and Three Rotor Syste	l - Damped Free Vil g, Critically Damped	bration	of Si	ngle I	Degree
UNI	IT IV	FORCED VIBRATION		9	0	0	9
Resp		Periodic Force – Harmonic Force – Force caused by Unbalance on Factor – Vibration Isolation and Transmissibility.	- Support Motion -	Logari	thmic	Decre	ement-
Mag	IT V	GOVERNORS		9	0	0	9

TE	XT BOOKS:
1.	Design of Machinery, Fourth Edition, by R.L. Norton, McGraw Hill, 2007
2.	Mechanical Vibration, V.P.Singh, Dhanpatrai, Delhi
RE	FERENCE BOOKS:
1.	Ballaney, P.L., "Theory of Machines and Mechanisms", Khanna Publishers, New Delhi, 2002.
2.	Shigley, J.E. and Uicker, J.J., "Theory of Machines and Mechanisms", TMH ND, 1998.
3.	Amithabha Ghosh, and Ashok Kumar Malik., "Theory of Mechanisms and Machines", 2nd Ed., Affiliated East and West Press Limited, 1998.
4.	Prof.Nakara, IIT-Delhi Reference Books

E-REFERENCES: 1. www.university.youth4work.com/IIT_Kharagpur_Indian-Institute-of-Technology/study/1653-dynamics-of-

2. http://nptel.ac.in/courses/112104114/

Machinery-ebook

	COURSE OUTCOMES: On completion of the course the student will be able to					
CO1	Apply basic principles of mechanisms in mechanical system	Apply				
CO2	Familiarize the static and dynamic analysis of simple mechanisms	Understand				
CO3	Analyze the mechanical systems subjected to free vibration	Analyze				
CO4	Analyze mechanical systems subjected to forced vibration	Analyze				
CO5	Analyze the various types of governors and its speed control mechanism	Analyze				

COs/POs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	3	3	1	0	0	0	0	1	0	3	2	1	2
CO2	2	2	3	2	1	0	0	0	0	1	0	3	2	1	2
CO3	2	2	3	2	0	0	0	0	0	1	0	3	2	1	2
CO4	2	2	3	2	1	0	0	0	0	1	0	3	2	1	2
CO5	1	2	3	2	0	0	0	0	0	1	0	3	2	1	1
Avg	1.8	2.0	3.0	2.2	1.2	0.0	0.0	0.0	0.0	1.0	0.0	3.0	2.0	1.0	1.8
Avg 3/2/1 – in											0.0	3.0	2.0	1.0	