	18ECPE808	PHYSICS OF SENSORS		Τ	P	С
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	Objectives:					
1.		e of the different types of sensors commonly used on mobile robotic plat	form	IS		
2. 3.		ne basic principles of operation of different types of sensors				
3.	To discuss commo	n practices and algorithms for processing raw sensor information				
Unit I		N AND DISPLACEMENT MEASUREMENT		9	+	0
		nts of a sensors- Classification of sensors - Static and Dynamic cha				
	ve type displacemen	nsors - Linear and Rotary displacement sensors – Potentiometer - C t sensor - Position sensors - Optical encoder - Photoelectric sensor -				
Unit II		NT OF PROXIMITY, FORCE AND PRESSURE		9	+	0
		sor - Inductive Proximity sensor - Capacitive Proximity sensor - Pneum				
	e Pressure sensors	es - Contact and Noncontact type – Strain Gauge – Diaphragm Pres - Bellows Pressure Sensor - Bourdon tube pressure sensor - Piezoeler				
Unit III	MEASUREM	ENT OF VELOCITY, FLOW AND LEVEL		9	+	0
nozzle-		tric sensors - Ultrasonic sensor – Resistive sensor - Pitot tube – Orific tameter - Electromagnetic flow meter - Float level sensor- Pressure le r.				
Unit IV	MEASUREM	ENT OF TEMPERATURE, MOTION AND LIGHT SENS		9	+	0
Detecto	ocouples - Thermisto or - Infrared Thermo	ors - Thermodiodes - Thermotransistors - BimetallicStrip - Resistance graphy - Vibrometer and accelerometer - Seismic accelerometer - Pho rs - Photocondutors.				
Unit V		ORS AND ACTUATORS		9	+	0
		nd examples - Force and pressure micro sensors - Position and speed m				
sensors	s - Micro Actuators: A	rs - Chemical sensors – Biosensors - Temperature micro sensors an Actuation principle - Shape memory effects - One way, two way and pseu Electrostatic - Magnetic - Fluidic - Inverse piezo effect - Other principle	nd fl udo (	ow	mic	ro
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